

# **VICE, the Versatile Commodore Emulator**

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```

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## 2 About VICE

VICE is the one and only *Versatile Commodore Emulator*. It provides emulation of the Commodore C64, C64DTV, C128, VIC20, PET, PLUS4 and CBM-II computers within a single package. The emulators run as separate programs, but have the same user interface, share the same settings and support the same file formats.

**Important notice:** If you have no idea what a Commodore 8-bit computer is, or have questions about how these machines are used, how the file formats work or anything else that is not strictly related to VICE, you should read the appropriate FAQs *first*, as that kind of information is not available here. See [Chapter 18 \[Contacts\]](#), [page 149](#). for information about how to retrieve the FAQs.

All the emulators provide an accurate 6502/6510 emulator, with emulation of all the opcodes (both documented and undocumented ones) and accurate timing. Unlike other emulators, VICE aims to be cycle accurate; it tries to emulate chip timings as precisely as possible and does so *efficiently*.

Please do *not* expect the C64DTV, C128, PET, PLUS4 and CBM-II emulators to be as good as the C64 or VIC20 one, as they are still under construction.

*Notice:* This documentation is written for the Unix release of VICE.

### 2.1 C64 emulator features

As of version 2.3, two C64 emulators are provided: ‘x64’ (fast) and ‘x64sc’ (accurate).

The fast C64 emulator, called ‘x64’, features a fairly complete emulation of the VIC-II video chip: sprites, all registers and all video modes are fully emulated. The emulation has been fully cycle-accurate since version 0.13.0.

The accurate C64 emulator, called ‘x64sc’, features a cycle-based and pixel-accurate VIC-II emulation. This requires a much faster machine than the old ‘x64’.

A rather complete emulation of the SID sound chip is also provided. All the basic features are implemented as well as most of the complex ones including synchronisation, ring modulation and filters. There are three emulators of the SID chip available: first is the “standard” VICE emulator, available since VICE 0.12; the second is Dag Lem’s reSID engine and the third one is reSID-fp. The reSID engines are a lot more accurate than the standard engine, but they are also a lot slower, and only suitable for faster machines.

Naturally, also both CIAs (or VIAs, in some cases) are fully emulated and cycle accurate.

### 2.2 C64DTV emulator features

The C64DTV emulator, called ‘x64dtv’, features emulation of C64DTV revisions 2 and 3. The emulator is under construction, but most of the DTV specific features are already supported (with varying accuracy).

Video cache is disabled by default as it currently doesn’t work with some of C64DTV’s new video modes. The new video modes have a simple “fake” video cache implementation that may give incorrect results and decreased performance.

## 2.3 C128 emulator features

The C128 emulator, called ‘x128’, features a complete emulation of the internal MMU (*Memory Management Unit*), 80 column VDC screen, fast IEC bus emulation, 2 MHz mode, Z80 emulation plus all the features of the C64 emulation.

## 2.4 VIC20 emulator features

The VIC20 emulates all the internal hardware, including the VIA chips. The VIC-I video chip is fully emulated except NTSC interlace mode, so most graphical effects will work correctly.

Sound support is implemented, but is still at an experimental stage. If you think it could be improved and know how to do so, feel free to contact us (see [Chapter 18 \[Contacts\]](#), [page 149](#)).

The VIC20 emulator now allows the use of the VIC1112 IEEE488 interface. You have to enable the hardware (by menu, resource, or commandline option) and then load the IEEE488 ROM (see for example <http://www.funet.fi/pub/cbm/schematics/cartridges/vic20/ieee-488/325329-04.bin>, but you have to double the size to 4k for now). The IEEE-488 code is then started by SYS45065.

## 2.5 PET emulator features

The PET emulator emulates the 2001, 3032, 4032, 8032, 8096, 8296 and SuperPET (MicroMainFrame 9000) models, covering practically the whole series. The hardware is pretty much the same in each and that is why one single program is enough to emulate all of them. For more detailed information about PET hardware please refer to the ‘PETdoc’ file.

Both the 40 column and 80 column CRTC video chips are emulated (from the 4032 onward), but a few of the features are not implemented yet (numbers of rasterlines per char and lines per screen). Fortunately, they are not very important for average applications.

Sound is available for the PET as well, but like the VIC20’s it is still under construction.

The PET 8096 is basically a PET 8032 with a 64k extension board which allows remapping the upper 32k with RAM. You have to write to a special register at \$fff0 to remap the memory. The PET 8296 is a 8096 but with a completely redesigned motherboard with 128k RAM in total. Of the additional 32k RAM you can use only some in blocks of 4k, but you have to set jumpers on the motherboard for it. VICE uses the command line options ‘-petram9’ and ‘-petramA’ instead. Also, the video controller can handle a larger address range. The PET 8x96 model emulations run the Commodore LOS-96 operating system - basically an improved BASIC 4 version with up to 32k for BASIC text and 32k for variables. See ‘PETdoc’ for more information.

The SuperPET also is a PET 8032 with an expansion board. It can map 4k at a time out of 64k into the \$9\*\*\* area. Also it has an ACIA 6551 for RS232 communication. The 6809 that is built into the SuperPET is not emulated, though.

The PET computers came with three major ROM revisions, so-called BASIC 1, 2 and 4, all of which are provided. The PET 2001 uses the version 1, the PET 3032 uses version 2, and the others use version 4. The 2001 ROM is horribly broken with respect to IEEE488

(they shipped it before they tested it with the floppy drive, so only tape worked. Therefore the emulator patches the ROM to fix the IEEE488 routines.

As well as other low-level fixes the 2001 patch obtains the load address for a program file from the first two bytes of the file. This allows the loading of both PET2001-saved files (that have \$0400 as their load address) and other PET files (that have \$0401). The PET2001 saves from \$0400 and not from \$0401 as other PETs do.

Moreover, the secondary addresses used are now 0 and 1 for load and save, respectively, and not arbitrary unused secondary addresses.

To select which model to run, specify it on the command line with the `-model MODEL` option, where `MODEL` can be one of a list of PET model numbers, all described in see [Section 7.6.1 \[PET model\]](#), page 79

## 2.6 CBM-II emulator features

The CBM-II emulator emulates several types of CBM-II models. Those models are known under different names in the USA and Europe. In the States they have been sold as B128 and B256, in Europe as CBM 610, CBM 620 (low-profile case) or CBM 710 and CBM 720 (high-profile case with monitor). In addition to that now an experimental C510 emulation is included. The C510 (also known as P500) is the little brother of the C600/700 machines. It runs at roughly 1 MHz and, surprise, it has a VIC-II instead of the CRTIC. Otherwise the different line of computers are very similar.

These computers are prepared to take a coprocessor board with an 8088 or Z80 CPU. Indeed there are models CBM 630 and CBM 730 that supposedly had those processors. However these models are not emulated.

The basic difference is the amount of RAM these machines have been supplied with. The B128 and the CBM \*10 models had 128k RAM, the others 256k. This implies some banking scheme, as the 6502 can only address 64k. And indeed those machines use a 6509, that can address 1 MByte of RAM. It has 2 registers at addresses 0 and 1. The indirect bank register at address 1 determines the bank (0-15) where the opcodes LDA (zp),Y and STA (zp),Y take the data from. The exec bank register at address 0 determines the bank where all other read and write addresses take place.

The business line machines (C6xx/7xx) have the RAM in banks 1-2, resp. 1-4. All available banks are used for BASIC, where program code is separated from all variables, resp. from normal variables, strings and arrays that are distributed over other banks. The C510 instead has RAM in banks 0 and 1, and uses bank 1 for program and all variables. Bank 0, though, can be accessed by the VIC-II to display graphics.

Many models have been expanded to more than the built-in memory. In fact some machines have been expanded to the full 1M. Bank 15 is used as system bank, with only little RAM, and lots of expansion cartridge ROM area, the I/O and the kernal/basic ROMs. Some models have been modified to map RAM into the expansion ROM area. Those modifications can be emulated as well.

The different settings are described in see [Section 7.7.1 \[CBM-II model\]](#), page 83.

## 2.7 The keyboard emulation

There are two ways of emulating the keyboard in VICE.

The default way (*symbolic mapping*) is to map every key combination to the corresponding key combination on the real machine: for example, if you press `*`, which is bound to `Shift-8` on a U.S. keyboard, in the C64 emulator, the emulated machine will have just the *unshifted* `*` key pressed (as `*` is unshifted on the C64 keyboard). Likewise, pressing `'` on the same U.S. keyboard without any shift key will cause the combination `Shift-7` to be pressed in the emulated C64. This way, it becomes quite obvious what keys should be typed to obtain all the symbols.

There is, however, one problem with symbolic mapping: some keys really need to be mapped specially regardless. The most important examples being, in the VIC20, C64 and C128 emulators, that `CTRL` is mapped to `Tab` and that the `Commodore` key is mapped to the left `Control`). The `RUN/STOP` key is mapped to the `ESC` key on the PC keyboard. The PET emulator, lacking the `Commodore` key but having an `ESC` key, uses the left `Control` key as `RUN/STOP` and the `ESC` key as `ESC` of course.

The second way (*positional mapping*) is to map every key on the “real” keyboard to the key which has the same position on the keyboard of the emulated machine. This way, no `Shift` key is forced by the program (with the exception of the function keys `F2`, `F4`, `F6` and `F8`, which require `Shift` on the Commodore keyboards), and the keyboard is more comfortable to use in those programs (such as some games) that require the keys to be in the correct positions.

**Warning:** unlike the real C64, VICE “presses” the `Shift` key *together* with the key to shift when the `Shift` must be forced. In most cases this should work fine, but some keyboard routines are quite picky and tend not to recognize the shift key because of this. For instance, `F6` (which on the real C64 is obtained with `Shift + F5`) could be recognized as `F5`. In that case, use the shift key manually (i.e., type `Shift + F5` in the example). Yes, we know this is a bug.

The `RESTORE` key is mapped to `Page Up` (or `Prev`) by default.

## 2.8 The joystick emulation

Joysticks can be emulated both via the keyboard and via a real joystick connected to the host machine (the latter only works on GNU/Linux systems).

There are two keyboard layouts for joystick use, known as *numpad* and *custom*.

The *numpad* layout uses the numeric keypad keys, i.e., the numbers `1 . . . 9` which emulate all the directions including the diagonal ones; `0` emulates the fire button.

The *custom* layout uses the keys `w`, `e`, `r`, `s`, `d`, `f`, `x`, `c`, `v` for the directions and `space` for the fire button instead.

## 2.9 The disk drive emulation

All the emulators support up to 4 external disk drives as devices 8, 9, 10 and 11. Each of these devices can emulate virtual Commodore 1541, 1541-II, 1571, 1581, 2031, 2040, 3040, 4040, 1001, 8050 and 8250 drives in one of four ways:

- using disk images, i.e., files that contain a dump of all the blocks contained in a real floppy disk (if you want more information about what a disk image is, consult the `comp.emulators.cbm` FAQ);

- accessing file system directories, thus giving you the use of files without having to copy them to disk images; this also allows you to read and write files in the P00 format (again, consult the `comp.emulators.cbm` FAQ for more info).
- accessing a real device connected to the host machine. As of VICE 1.11 it is possible to connect real drives like Commodore 1541 to the printer port of the host using the XA1541 or XM1541 cable. Currently this only works on Linux or Windows using the OpenCBM library. You can get it from <http://www.lb.shuttle.de/puffin/cbm4linux> (cbm4linux, Linux version) or from <http://cbm4win.sf.net/> (cbm4win, Windows version).
- directly using the disk drive of the host. The 3.5" disk drive of the host can be used to read or write Commodore 1581 formatted disks. Currently this raw drive access feature is only available for Linux hosts.

When using disk images there are two available types of drive emulation. One of them the *virtual drive* emulation. It does *not* really emulate the serial line, but patches the kernal ROM (with the so-called *kernal traps*) so that serial line operations can be emulated via C language routines. This emulation is very fast, but only allows use of standard DOS functions (and not even all of them). For real device or raw drive access it is required to enable this type of emulation.

The IEEE488 drives (2031, 2040, 3040, 4040, 1001, 8050 and 8250) do not use kernal traps. Instead the IEEE488 interface lines are monitored and the data is passed to the drive emulation. To use them on the C64, you need to enable the IEEE488 interface emulation. Only if the IEEE488 emulation is enabled, those drives can be selected.

The other alternative is a *true drive* emulation. The Commodore disk drives are provided with their own CPU (a 6502 as the VIC20 and the PETs) and their own RAM and ROM. So, in order to more closely emulate its features, a complete emulation of this hardware must be provided and that is what the *hardware level* emulation does. When the *hardware level* emulation is used, the kernal routines are remain unpatched and the serial line is fully emulated. The problem with this emulation is that it needs a lot of processing power, mainly because the emulator has to emulate two CPUs instead of one.

The PETs do not use a serial IEC bus to communicate with the floppy drive but instead use the parallel IEEE488 bus. This does *byte by byte* transfers, as opposed to the *bit by bit* transfers of the C64 and VIC20, so making it feasible to emulate the parallel line completely while emulating the drive at DOS level only. The IEEE488 line interpreter maps the drives 8-11 (as described above) to the IEEE488 disk units, and no kernal traps are needed. The same emulation of the Commodore IEEE488 bus interface is available for the C64 and the VIC20. With IEEE488 drives you can have true 2031 emulation at unit #8, and still have filesystem access at units #10 or #11, because monitoring the IEEE488 lines does not interfere with the true drive emulation.

The IEEE488 disk drives 3040, 4040, 8050 and 8250 are Dual Drive Floppy Disks. This means that these drives handle two disks. To Accomplish the emulation, only one disk can be emulated, namely unit #8. The attached image, track display and LED display of unit #9 are used for the second drive of the dual disk drives. On unix the unit number display (8 or 9) in the emulation window changes to the drive number display (0 or 1).

The Commodore 3040, 4040, 1001, 8050 and 8250 disk drives are so-called "old-style" disk drives. Their architecture includes not one, but two processors of the 6502 type,

namely a 6502 for the file handling and communication with the PET (IP), and a 6504 (which is a 6502 with reduced address space) for the drive handling (FDC). Both processors communicate over a shared memory area. The IP writes commands to read/write blocks to this area and the FDC executes them. To make the emulation feasible, the FDC processor is not emulated cycle-exactly as a 6504, but simply by checking the commands and executing them on the host. This provides a fast FDC emulation, but disallows the sending the FDC processor commands to execute code. Applications where this is necessary are believed to be rather seldom. Only the format command uses this feature, but this is checked for.

The dual disk drive 2040 emulates one of the very first CBM disk drives. This drive has DOS version 1. DOS1 uses an own disk type, that is closely related to the 1541 disk image. Only on tracks 18-24 DOS1 disks have a sector more than 1541 disks. DOS1 disk images have the extension .d67.

The dual disk drives 3040 and 4040 use the same logical disk format as the VC1541 and the 2031. In fact, the 4040 was the first disk with DOS version 2. The 3040 emulated here originally was the same as 2040, only for the european 30xx PET series. As many of the original DOS1 disk drives were upgraded (a simple ROM upgrade!) to DOS2, I use the 3040 number for a DOS 2.0 disk drive, and 4040 for a revised DOS 2 disk drive. It is, however, not yet clear whether the disks here are write compatible to the 1541, as rumors exist that the write gap between sectors is different. But read compatible they are. As VICE emulates the FDC processor in C and not as 6504 emulation, this does not matter in VICE.

The drives 1001, 8050 and 8250 do actually have the very same DOS ROM. Only the code in the FDC is different, which is taken care of by VICE. So for all three of those disk drives, only `dos1001` is needed. The DOS version used is 2.7.

## 2.10 Supported file formats

VICE supports the most popular Commodore file formats:

- X64 (preferred) or D64 disk image files; Used by the 1541, 2031, 3040, 4040 drives.
- G64 GCR-encoded 1541 disk image files;
- D67 CBM2040 (DOS1) disk image format
- D71 VC1571 disk image format
- D81 VC1581 disk image format
- D80 CBM8050 disk image format
- D82 CBM8250/1001 disk image format
- T64 tape image files (read-only);
- P00 program files;

An utility (`c1541`, see [Chapter 12 \[c1541\]](#), page 111) is provided to allow transfers and conversions between these formats.

Notice that the use of the X64 file format is depreciated now.

You can convert an X64 file back into a D64 file with the UNIX `dd` command:

```
dd bs=64 skip=1 if=IMAGE.X64 of=IMAGE.D64
```

See [Chapter 15 \[File formats\]](#), page 119. for a technical description of the supported file formats.

## 2.11 Common problems

This section tries to describe the most common known problems with VICE, and how to resolve them.

### 2.11.1 Sound problems

VICE should compile and run without major problems on many UNIX systems, but there are some known issues related to the sound driver. In fact, the sound code is the least portable part of the emulator and has not yet been thoroughly tested on all the supported platforms.

Linux, AIX and SGI systems should play sound without any problems; if you are running Linux please use a 2.x kernel, as VICE needs some features that were not implemented in older versions of the Linux sound driver.

On the other hand, HP-UX and Solaris machines are known to cause troubles. If you think you can help debugging the code for these systems, your help would be really appreciated. We are having troubles finding HP-UX and SUN consoles to work at. . .

Some problems have been reported with the proprietary version of the Open Sound System for Linux. With a Crystal sound card, sound output was significantly delayed and, apparently, the allocated buffer size was completely wrong. This is not a VICE bug, but rather an OSS bug.

### 2.11.2 Shared memory problems

If you cannot start VICE because you get errors about shared memory, try to run it with the `+mitshm` command-line option (see [Section 6.4.2 \[Video options\]](#), page 29). This will completely disable usage of the MITSHM extensions, that are normally used to speed up the emulation window updates. Of course, this will also result in a big loss in speed.

Reasons for this failure could be:

- IPC support has been disabled at the system level; some system administrators disable this for security reasons. If *you* are the system administrator, use a kernel that has IPC support compiled in and enabled.
- You are attempting to run the emulator across the network (i.e., the emulator runs on one machine, and the output is displayed on another machine that works as an X terminal) and for some reason VICE does not recognize this fact. In this case, you have found a bug, so please report it to us.

If you want to avoid running the emulator with `+mitshm` every time, run it once with `+mitshm` and then choose "Save settings" from the right-button menu.

### 2.11.3 Printer problems

VICE supports the emulation of a printer either on the userport or as IEC device 4. Unfortunately the Commodore IEC routines do not send all commands to the IEC bus. For example an `OPEN 1,4` is not seen on the IEC bus. Also a `CLOSE 1` after that is not seen. VICE can see from printing that there was an `OPEN`, but it cannot see when the close was. Also a "finish print job" cannot be seen on the userport device. To flush the printer buffer (write to `print.dump` or to the printer) now a menu entry can be used. Disabling and re-enabling the printer should work as well.



The printing services have not been extensively tested but apart from the problem mentioned above it should work fine now.

#### 2.11.4 PET keyboard problems

If you find that the German keyboard mapping (plus German charset) does not print uppercase umlauts, then you are right. The umlauts replace the [,\ and ] characters in the charset. The keys that make these characters do not have a different entry in the PET editor ROM tables when shifted. Thus it is not possible to get the uppercase umlauts in the editor. Nevertheless other programs are reported to change the keyboard mapping table and thus allow the use of the shifted (uppercase) umlauts.

Anyway, the VICE keyboard mappings are far from being perfect and we are open to any suggestions.

## 3 Invoking the emulators

The names of the available emulators are:

- **x64**, the fast C64 emulator
- **x64sc**, the accurate C64 emulator
- **x64dtv**, the C64DTV emulator
- **x128**, the C128 emulator
- **xvic**, the VIC20 emulator
- **xpet**, the PET emulator
- **xplus4**, the PLUS4 emulator
- **xcbm2**, the CBM-II emulator

You can run each of them by simply typing the name from a shell. If you want to run them from another application (e.g., a window manager or some other sort of program launcher) you should always run them from a terminal window such as **xterm** or **rxvt** since VICE provides a lot of debugging information that is sent to the terminal and has built-in monitor that also appears there. For example, you could do

```
xterm -e x64
```

### 3.1 Command-line options used during initialization

There are several options you can specify on the command line. Some of them are used to specify emulation settings and will be described in detail later (see [Chapter 6 \[Settings and resources\]](#), [page 25](#) for a complete list). The remaining options are used only to give usage information or to initialize the emulator in some way:

- help**
- ?** List all the available command-line options and their meaning.
- default** Set default resources (see [Chapter 6 \[Settings and resources\]](#), [page 25](#)). This will override all the settings specified before, but not the settings specified afterwards on the command line.



`-config <filename>`  
Specify config file

`-logfile <name>`  
Specify log file name

`-verbose` Enable verbose log output.

`-keybuf <string>`  
Put the specified string into the keyboard buffer.

`-console` Console mode (for music playback)

`-chdir <directory>`  
Change the working directory.

`-autostart IMAGE`  
Autostart 'IMAGE' (see [Section 3.2 \[Command-line autostart\]](#), page 16).

`-autoload <name>`  
Attach and autoload tape/disk image <name>

`-basicload`  
On autostart, load to BASIC start (without ',1')

`+basicload`  
On autostart, load with ',1'

`-autostartwithcolon`  
On autostart, use the 'RUN' command with a colon, i.e., 'RUN:'

`+autostartwithcolon`  
On autostart, do not use the 'RUN' command with a colon; i.e., 'RUN'

`-autostart-handle-tde`  
`+autostart-handle-tde`  
Handle/Do not handle True Drive Emulation on autostart

`+autostart-warp`  
Enable/Disable warp mode during autostart

`-autostartprgmode`  
Set autostart mode for PRG files

`-autostartprgdiskimage`  
Set disk image for autostart of PRG files

`-1 NAME` Attach 'NAME' as a tape image file.

`-8 NAME`

`-9 NAME`

`-10 NAME`

`-11 NAME` Attach 'NAME' as a disk image to device 8, 9, 10 or 11.

`-attach8ro`

`-attach9ro`

`-attach10ro`

`-attach11ro`  
Attach disk image for drive #8-11 read only

```
-attach8rw
-attach9rw
-attach10rw
-attach11rw
```

Attach disk image for drive #8-11 read write (if possible)

## 3.2 Autostarting programs from the command-line

It is possible to let the emulator *autostart* a disk or tape image file, by simply specifying its name as the *last* argument on the command line, for example

```
x64 lovelygame.x64.gz
```

will start the C64 emulator, attaching ‘lovelygame.x64.gz’ as a disk image and running the first program on it. You can also specify the name of the program on the disk image by appending a colon (‘:’) the name itself to the argument; for example

```
x64 "lovelygame.x64.gz:run me"
```

will run the program named ‘run me’ on ‘lovelygame.x64.gz’ instead of the first one.

Using the command-line option `-autostart` is equivalent; so the same result can be obtained with

```
x64 -autostart "lovelygame.x64.gz:run me"
```

If you specify a raw CBM or P00 file, the emulator will setup the file system based drive emulation so that it is enabled and accesses the directory containing the file first. This is a very convenient way to start multi-file programs stored in file system directories and not requiring “true” drive emulation.

See [Section 5.5 \[Disk and tape images\]](#), page 23. for more information about images and autostart.

## 4 System files

In order to work properly, the emulators need to load a few system files:

- the *system ROMs*, raw binary files containing copies of the original ROMs of the machine you are emulating;
- the *keyboard maps*, text files describing the keyboard layout;
- the *palette files*, text files describing the colors of the machine you are emulating.
- the *romset files*, text files describing the different ROMs to load.

The place where they will be searched for depends on the value of the **Directory** resource, which is a colon (:)-separated search path list, like the UNIX **PATH** environment variable. The default value is

```
PREFIX/lib/vice/EMU:$HOME/.vice/EMU:BOOTPATH/EMU
```

Where **PREFIX** is the installation prefix (usually ‘/usr/local’), **EMU** is the name of the emulated machine (C64, C128, PET, CBM-II or VIC20) and **BOOTPATH** is the directory where the executable resides. The disk drive ROMs are looked for in a directory with **EMU** set to **DRIVES**. **\$HOME** is the user’s home directory.

For example, if you have the C64 emulator installed in

```
/usr/local/bin/x64
```

then the value will be

```
/usr/local/lib/vice/C64:$HOME/.vice/C64:/usr/local/bin/C64
```

And system files will be searched for under the following directories, in the specified order:

1. `/usr/local/lib/VICE/C64`
2. `$HOME/.vice/C64`
3. `/usr/local/bin/C64`

System files can still be installed in a different directory if you specify a complete path instead of just a file name. For example, if you specify `./kernal` as the kernal image name, the kernal image will be loaded from the current directory. This can be done by using command-line options or by modifying resource values (see [Section 6.1 \[Resource files\]](#), page 26).

## 4.1 ROM files

Every emulator requires its own ROM set. For the VIC20 and the C64, the ROM set consists of the following files:

- `'kernal'`, the Kernal ROM (8 KBytes)
- `'basic'`, the Basic ROM (8 KBytes)
- `'chargen'`, the character generator ROM (4 Kbytes)

The C128 needs the following files:

- `'kernal'`, the Kernal ROM (8 Kbytes)
- `'basic'`, the Basic + Editor ROM (32 Kbytes)
- `'chargen'`, the character generator ROM (4 Kbytes)

The C128, VIC20 and C64 emulators also need the following DOS ROMs for the hardware-level emulation of the 1541, 1571 and 1581 disk drives:

- `'dos1541'`, the 1541 drive ROM (16 Kbytes)
- `'dos1541II'`, the 1541-II drive ROM (16 Kbytes)
- `'dos1571'`, the 1571 drive ROM (32 Kbytes)
- `'dos1581'`, the 1581 drive ROM (32 Kbytes)

In addition to those all emulators can handle a parallel IEEE488 interface (the C64 and C128 via `$df**` extension, the VIC20 via VIC1112 emulation) so they also need the DOS ROM for the IEEE disk drives:

- `'dos2031'`, the 2031 drive ROM (16 Kbytes) (DOS 2.6, Commodore ROM images 901484-03 and 901484-05)
- `'dos2040'`, the 2040 drive ROM (8 Kbytes) (DOS 1, Commodore ROM images 901468-06, 901468-07)
- `'dos3040'`, the 3040 drive ROM (12 Kbytes) (DOS 2, Commodore ROM images 901468-11, 901468-12 and 901468-13)
- `'dos4040'`, the 4040 drive ROM (12 Kbytes) (DOS 2, Commodore ROM images 901468-14, 901468-15 and 901468-16)

- ‘dos1001’, the 1001/8050/8250 drive ROM (16 Kbytes) (DOS 2.7, Commodore ROM images 901887-01 and 901888-01)

Note that there are other DOS images on the internet. The DOS 2.5 images might be used with the 8050, but it cannot handle the double sided drives of the 1001 and 8250 and it is not supported by VICE.

The PET emulator uses an expanded setup, because there are three major versions of the Basic and the Kernal, and many versions of the Editor ROM. In addition there are cartridge ROM sockets.

The Kernal files contain the memory from range \$F000-\$FFFF, the Basic ROMs either the range \$C000-\$DFFF or \$B000-\$DFFF. To handle the different screen sizes and keyboards, different so-called “editor-ROMs” for the memory range \$E000-\$E800 are provided. The PET ROMs have the following names:

- ‘kernal1’, the PET2001 Kernal ROM (4 KBytes) (Commodore ROM images 901447-06 and 901447-07)
- ‘kernal2’, the PET3032 Kernal ROM (4 KBytes) (Commodore ROM image 901465-03)
- ‘kernal4’, the PET4032/8032 Kernal ROM (4 KBytes) (Commodore ROM image 901465-22)
- ‘basic1’, the PET2001 Basic 1 ROM (8 KBytes) (Commodore ROM images 901447-09, 901447-02, 901447-03, 901447-04.bin. The -09 ROM is the revised -01 ROM)
- ‘basic2’, the PET3032 Basic 2 ROM (8 KBytes) (Commodore ROM images 901465-01 and 901465-01)
- ‘basic4’, the PET4032/8032 Basic 4 ROM (12 KBytes) (Commodore ROM images 901465-23, 901465-20 and 901465-21. The -23 ROM is a revised -19 ROM)
- ‘edit1g’, the PET2001 editor for graphics keyboards (2 KBytes) (Commodore ROM image 901447-05)
- ‘edit2b’, the PET3032 editor for business keyboards (2 KBytes) (Commodore ROM image 901474-01)
- ‘edit2g’, the PET3032 editor for graphics keyboards (2 KBytes) (Commodore ROM image 901447-24)
- ‘edit4g40’, the PET4032 editor for graphics keyboards (2 KBytes) (Commodore ROM image 901498-01)
- ‘edit4b40’, the PET4032 editor for business keyboards (2 KBytes) (Commodore ROM image 901474-02)
- ‘edit4b80’, the PET8032 editor for business keyboards (2 KBytes) (Commodore ROM image 901474-04-?)
- 
- ‘chargen’, the character generator ROM (2k). It has two sets with 128 chars each. The second (inverted) half of each set is computed from the first half by inverting it. This is a PET hardware feature. (Commodore ROM image 901447-10)
- ‘chargen.de’, the character generator ROM (2k). This version is a patched German charset, with the characters [ , \ and ] replaced by umlauts. It has been provided by U. Guettich and he reports that it is supported by some programs.

The PETs also have sockets for extension ROMs for the addresses \$9000-\$9FFF, \$A000-\$AFFF and \$B000-\$BFFF (the last one for PET2001 and PET3032 only). You can specify ROM image files for those extensions command line options `-petrom9`, `-petromA` and `-petromB` resp.

An alternative would be to specify a long kernal ROM with the `-kernal` option that includes the extension ROM areas.

Also, you can specify replacements for the basic ROM at \$B000-\$DFFF with the `-petromBasic` option and for the editor ROM at \$E000-\$E7FF with the `-petromEditor` option.

The CBM-II emulator again uses another setup. For those models the kernal used is the same for all. However, for different amounts of memory exist different versions of the BASIC ROMs. The 128k RAM version (C610, C710, B128) uses one bank of 64k for the BASIC text and another one for all the variables. The 256k RAM version uses one bank for text, one for variables, one for arrays and one for strings.

Also the character generator ROMs have a format different from the above. The other character ROMs have 8 bytes of pixel data per character. Those ROMs have 16 bytes per character instead. The C6x0 only uses the first 8 of it, but the C7x0 uses 14 lines per character and needs those increased ROMs. Both ROMs hold, like the PET, two character sets with 128 characters each. Again the second half of the full (256 char) character set is computed by inverting.

- ‘kernal’, the KERNAL (8k) for the business machines (6xx/7xx)
- ‘kernal.500’, the KERNAL (8k) for the personal machine (510) (901234-02)
- ‘basic.128’, the CBM-II 128k BASIC (16k)
- ‘basic.256’, CBM-II 256k BASIC (16k)
- ‘basic.500’, C510 BASIC (16k) (901236-02 + 901235-02)
- ‘chargen.500’, character generator ROM for the C5x0 (4k) (901225-01)
- ‘chargen.600’, character generator ROM for the C6x0 (4k)
- ‘chargen.700’, character generator ROM for the C7x0 (4k)

## 4.2 Keymap files

*Keymap files* are used to define the keyboard layout, defining which key (or combination of keys) must be mapped to each keysym.

In other words, the keyboard emulation works like this: whenever the user presses or releases a key while the emulation window has the input focus, the emulator receives an X-Window event with a value that identifies that key. That value is called a *keysym* and is unique to that key. The emulator then looks up that keysym in an internal table that tells it which key(s) to press or release on the emulated keyboard.

This table is described by the keymap file, which is made up of lines like the following:

```
KEYSYM ROW COLUMN SHIFTFLAG
```

Where:

- **KEYSYM** is a string identifying the keysym: you can use the `xev` utility (shipped with the X Window system) to see what keysym is bound to any key;

- ROW and COLUMN identify the key on the emulated keyboard;
- SHIFTFLAG can have one of the following values:
  - 0: the key is never shifted;
  - 1: the key is shifted;
  - 2: the key is the left shift;
  - 4: the key is the right shift;
  - 8: the key can be (optionally) shifted by the user.

The SHIFTFLAG is useful if you want certain keys to be “artificially” shifted by the emulator, and not by the user. For example, F2 is shifted on the C64 keyboard, but you might want it to be mapped to the unshifted F2 key on the PC keyboard. To do so, you just have to use a line like the following:

```
F2 0 4 1
```

where 0 and 4 identify the key (row 0, column 4 on the keyboard matrix), and 1 specifies that every time the user presses F2 the shift key on the C64 keyboard must be pressed.

There are also some special commands you can put into the keyboard file; they are recognized because they start with an exclamation mark:

- !CLEAR clears the currently loaded keyboard map; it is necessary to put this at the beginning of the file if you want the keymap file to override all of the current internal settings;
- !LSHIFT, !RSHIFT, followed by a row and a column value, specify where the left and right shift keys are located on the emulated keyboard; for example, C64 default keymaps will specify

```
!LSHIFT 1 7
!RSHIFT 6 4
```

Any line starting with the # sign, instead, is completely ignored. This is useful for adding comments within the keymap file.

VICE keymap files have the ‘.vkm’ default extension, and every emulator comes with a default positional mapping and a default symbolic mapping.

### 4.3 Palette files

*Palette files* are used to specify the colors used in the emulators. They are made up of lines like the following:

```
RED GREEN BLUE DITHER
```

where RED, GREEN and BLUE are hexadecimal values ranging from 0 to FF and specifying the amount of red, green and blue you want for each color and DITHER is a 4-bit hexadecimal number specifying the pattern you want when rendering on a B/W display.

You have to include as many lines as the number of colors the emulated machine has, and the order of the lines must respect the one used in the machine (so the N’t line must contain the specifications for color N - 1 in the emulated machine).

Lines starting with the # sign are completely ignored. This is useful for adding comments (such as color names) within the palette file.

For example, the default PET palette file (which has only two colors, 0 for background and 1 for foreground), looks like the following:

```
#
# VICE Palette file
#
# Syntax:
# Red Green Blue Dither
#

# Background
00 00 00 0

# Foreground
00 FF 00 F
```

## 4.4 Romset files

The Romset files are not used by default on all emulators. You might have recognized that the names of the ROM images are saved in resources. Loading a Romset file now just means a ‘shortcut’ to changing all the resources with ROM image names and reloading the ROMs.

The PET and CBM-II emulators use this feature to change between the different ROM versions available for those machines. E.g. the Romset file for the PET 2001 is

```
KernalName="pet2001"
EditorName=
ChargenName="chargen"
RomModule9Name=
RomModuleAName=
RomModuleBName=
```

As you can see, the file even uses the same syntax as the resource file, it is just a bit stripped down.

# 5 Basic operation

This section describes the basic things you can do once the emulator has been fired up.

## 5.1 The emulation window

When the emulator is run, the screen of the emulated machine is displayed in a standard X Window which we will call the *emulation window*. This window will be updated in real time, displaying the same contents that a real monitor or TV set would.

Below the emulation window there is an area which is used to display information about the state of the emulator; we will call this area the *status bar*.

On the extreme left of the status bar, there is a *performance meter*. This displays the current relative speed of the emulator (as a percentage) and the update frequency (in frames per second). All the machines emulated are PAL, so the update frequency will be 50 frames per second if your system is fast enough to allow emulation at the speed of the real machine.

On the extreme right of the status bar, there is a *drive status indicator*. This is only visible if the hardware-level (“True”) 1541 emulation is turned on. In that case, the drive status indicator will contain a rectangle emulating the drive LED and will display the current track position of the drive’s read/write head.

## 5.2 Using the menus

It is possible to execute some commands and change emulation parameters while the emulator is running: when the pointer is over the emulation window, two menus are available by pressing either the left or right mouse buttons. The left mouse button will open the *command menu* from which several emulation-related commands can be executed; the right mouse button will open the *settings menu* from which emulation parameters can be changed. The basic difference between the command and the settings menu is that, while commands have only effect on the current session, settings can be saved and later used with the “Save settings” and “Load settings” right-button menu items, respectively. “Restore default settings” restores the factory defaults. See [Chapter 6 \[Settings and resources\], page 25](#). for more information about how settings work in VICE.

Sometimes commands can be reached via *shortcuts* or *hotkeys*, i.e., it is possible to execute them by pressing a sequence of keys instead of going through the menu with the mouse. Where shortcuts exist, they are displayed in parentheses at the right edge of the menu item. In VICE, all shortcuts must begin with the **Meta** or **Alt** key. So, for example, to attach a disk image to drive #8 (the corresponding menu item displays “M-8”), you have to press the **Meta** (or **Alt**) and then 8.

Note that no other key presses are passed on to the emulated machine while either **Meta** or **Alt** are held down.

## 5.3 Getting help

At any time, if you get stuck or do not remember how to perform a certain action, you can use the “Browse manuals” command (left button menu). This will popup a browser and open the HTML version of this documentation. Notice that this requires VICE to be properly (and fully) installed with a ‘**make install**’.

The browser can be specified via the `HTMLBrowserCommand` string resource (see [Chapter 6 \[Settings and resources\], page 25](#) for information about resources). Every ‘%s’ in the string will be replaced with a URL to the VICE HTML pages.

## 5.4 Using the file selector

In those situations where it is necessary to specify a file name, all of the VICE emulators will pop up a file selector window allowing you to select or specify a file interactively.

To the left of the file selector, there is a list of ancestor directories: by clicking on them, you can ascend the directory tree. To the right, there is a list of the files in the current directory; files can be selected by clicking on them. If you click on a directory, that directory becomes the current one; if you click on an ordinary file, it becomes the active selection.

At the top, there is a *directory box*, with the complete path of the current directory, and a *file name box*, with the name of the currently selected file. At the bottom there are two



buttons: “OK” confirms the selected file and “Cancel” abandons the file selector without cancelling the operation.

It is also possible to specify what files you want to show in the file selector by writing an appropriate shell-like pattern in the directory box; e.g., ‘~/\*. [dx]64’ will only show files in the home directory whose name ends with either ‘.d64’ or with ‘.x64’.

## 5.5 Using disk and tape images

The emulator is able to emulate disk drives and (read-only) tape recorders if provided with suitable *disk images* or *tape images*. An *image* is a raw dump of the contents of the media, and must be *attached* before the emulator can use it. “Attaching” a disk or tape image is like “virtually” inserting a diskette or a cassette into the disk drive or the tape recorder: once an image is attached, the emulator is able to use it as a storage media.

There are five commands (in the left button menu) that deal with disk and tape images:

- Attach Disk Image
- Detach Disk Image
- Attach Tape Image
- Detach Tape Image
- Smart-attach a file

The first four commands are used to insert and remove the virtual disks and cassettes from the respective units. On the other hand, the last commands tries to guess the type of the image you are attaching from its name and size, and attaches it to the most reasonable device.

Supported formats are D64 and X64 for disk images (devices 8, 9 and 10) and T64 for tape images. Notice that T64 support is *read-only*, and that the cassette is automatically rewound when you reach its end.

Another important feature is that raw Commodore BASIC binary files and .P00 files can be attached as tapes. As you can autostart a tape image when it is attached (see [Section 5.5.2 \[Autostart\], page 24](#)), this allows you to autostart these particular files as well.

You can attach a disk for which you do not have write permissions: when this happens, the 1541 emulator will emulate a write-protected disk. This is also useful if you want to prevent certain disk images from being written to; in the latter case, just remove the write permission for that file, e.g., by doing a `chmod a-w`.

### 5.5.1 Previewing the image contents

It is possible to examine the directory of a disk or tape image before attaching it. Just press the “Contents” button in the file selector window and a new window will pop up with the contents of the selected image.

Notice that this function automatically translates the directory from PETSCII to ASCII; but, due to differences in the two encodings, it is not always possible to translate all the characters, so you might get funny results when “weird” characters such as the semi-graphical ones are being used.

### 5.5.2 “Autostarting” an image

If you want to reset the machine and run the first program on a certain image without typing any commands at the Commodore BASIC prompt, you can use the “Autostart” button in the file selector window after selecting a proper disk or tape image file.

Notice that, if true drive emulation is turned on, it will be turned off before running the program and then turned on again after it has been loaded. This way, you get the maximum possible speed while loading the file, but you do not lose compatibility once the program itself is running.

This method is not completely safe, because some autostarting methods might cause the true drive emulation not to be turned on again. In such cases, the best thing to do is to disable kernal traps (which will cause true drive emulation to be always kept turned on), or to manually load the program with true drive emulation turned on.

### 5.5.3 Using compressed files

It is also possible to attach disk or tape images that have been compressed through various algorithms; compression formats are identified from the file extension. The following formats are supported (the expected file name extension is in parenthesis):

- GNU Zip (`.gz` or `.z`);
- BZip version 2 (`.bz2`);
- PkZip (`.zip`);
- GNU Zipped TAR archives (`.tar.gz`, `.tgz`);
- Zoo (`.zoo`).

PkZip, `tar.gz`, `lha` and `zoo` support is *read-only* and always uses the *first* T64 or D64 file in the archive. So archives containing multiple files will always be handled as if they contain only a single file.

Windows and MSDOS don’t contain the needful programs to handle compressed archives. Get `gzip` and `unzip` for Windows at <ftp://ftp.freeware.com/pub/infozip/WIN32> and for MSDOS at <ftp://ftp.freeware.com/pub/infozip/MSDOS>. Don’t use `pkunzip` for MSDOS, it doesn’t work. The programs to use BZip2 archives may be found at <http://sourceware.cygnus.com/bzip2>. Just put the programs (`unzip.exe`, `gzip.exe`, `bzip2.exe`) into a directory of your search path (e.g. `C:\DOS` or `C:\WINDOWS\COMMAND`; have a look at the `PATH` variable).

### 5.5.4 Using Zipcode and Lynx images

Since version 0.15, the VICE emulators have been able to attach disks packed with Zipcode or Lynx directly, removing the need to manually convert them into D64 or X64 files with `c1541`. This is achieved by automatically invoking `c1541`, letting it decode the file into a temporary image and attaching the resulting temporary image read-only. For this to work, the directory containing `c1541` must be in your `PATH`.

This uses the `-unlynx` and `-zcreate` options of `c1541` (see [Section 12.3 \[c1541 commands and options\]](#), page 112); these commands are not very reliable yet, and could fail with certain kinds of Lynx and Zipcode images (for example, they cannot deal with `DEL` files properly). So please use them with caution.

Lynx files usually come as ‘.lnx’ files which are unpacked into single disk images. On the other hand, Zipcode files do not have a particular extension (although ‘.z64’ is sometimes used), and represent a disk by means of component files, named as follows:

- ‘1!NAME’
- ‘2!NAME’
- ‘3!NAME’
- ‘4!NAME’

If you attach as a disk image (or smart-attach) any one of these files, the emulator will simply pick up the other three (by examining the name) and then build a disk image using all four.

## 5.6 Resetting the machine

You can reset the emulated machine at any time by using the “Reset” command from the command menu. There are two types of reset:

- *soft reset*, which simply resets the CPU and all the other chips;
- *hard reset*, which also clears up the contents of RAM.

A *soft reset* is the same as a hardware reset achieved by pulling the RESET line down; a *hard reset* is more like a power on/power off sequence in that it makes sure the whole RAM is cleared.

It is possible that a soft reset may not be enough to take the machine to the OS initialization sequence: in such cases, you will have to do a hard reset instead.

This is especially the case for the CBM-II emulators. Those machines examine a memory location and if they find a certain "magic" value they only do what you know from the C64 as Run/Stop-Restore. Therefore, to really reset a CBM-II use hard reset.

## 6 Settings and resources

In the VICE emulators, all the settings are stored in entities known as called *resources*. Each resource has a name and a value which may be either an integer or a string. Integer values are often used as boolean values with the usual convention of using zero for “false” and any other value for “true”.

Resource values can be changed via the right-button menu (the *settings* menu), via command-line options or via the *resource file*.

The *resource file* is a human-readable file containing resource values: it is called ‘vicerc’ and is stored in the directory ‘.vice/’ in the user’s home directory. It is possible to dump the current values of the resources into that file or load the values stored into that file as the current values, at any time. This is achieved with the “Save settings” and “Load settings” right menu items. A third menu item, “Restore Default Settings”, can be used to reset all the values to the factory defaults.

A special resource, **SaveResourcesOnExit**, if set to a non zero value, causes the emulator to ask you if you want to save the current (changed) settings before exiting, and can be toggled with the “Save settings on exit” command from the right-button menu.

Notice that not all the resources can be changed from the menus; some of them can only be changed by manually modifying the resource file or by using command-line options.

## 6.1 Format of resource files

A resource file is made up of several sections; sections have the purpose of separating the resources of a certain emulator from the ones of the other emulators. A section starts with the name of an emulator in brackets (e.g., '[C64]') and ends when another section starts or when the file ends.

Every line in a section has the following format:

RESOURCE=VALUE

where RESOURCE is the name of a resource and VALUE is its assigned value. Resource names are case-sensitive and resource values are either strings or integers. Strings must start and end with a double quote character ("), while integers must be given in decimal notation.

Here is an example of a stripped-down '.vice/vicerc' file:

```
[VIC20]
HTMLBrowserCommand="netscape %s"
SaveResourcesOnExit=0
FileSystemDevice8=1
FSDevice8ConvertP00=1
FSDevice8Dir="/home/ettore/cbm/stuff/vic20p00"
FSDevice8SaveP00=1
FSDevice8HideCBMFiles=1
[C64]
HTMLBrowserCommand="netscape %s"
SaveResourcesOnExit=1
FileSystemDevice8=1
FSDevice8ConvertP00=1
FSDevice8Dir="/home/ettore/cbm/stuff/c64p00"
FSDevice8SaveP00=1
FSDevice8HideCBMFiles=1
```

Notice that, when resource values are saved with “Save settings”, the emulator only modifies its own section, leaving the others unchanged.

## 6.2 Using command-line options to change resources

Resources can also be changed via command-line options.

Command-line options always override the defaults from .vice/vicerc, and their assignments last for the whole session. So, if you specify a certain command-line option that changes a certain resource from its default value and then use “Save Settings”, the value specified with the command-line option will be saved back to the resource file.

Command-line options can begin with with a minus sign ('-') or with a plus sign ('+'). Options beginning with a minus sign may require an additional parameter, while the ones beginning with the plus sign never require one.

Moreover, options beginning with a plus sign always have a counterpart with the same name, but with a minus sign; in that case, the option beginning with a minus sign is used to *enable* a certain feature, while the one beginning with a plus sign is used to *disable* the same feature (this is an X11 convention). For example, `-mitshm` enables support of MITSHM, while `+mitshm` disables it.

## 6.3 Performance settings

It is possible to control the emulation speed by using the “Maximum speed” menu item in the right-button menu. The default setting is 100, which causes the emulation to never run faster than the real machine. A higher value allows the emulator to run faster, a lower one may force it to run slower. The setting “No limit” means to run as fast as possible, without limiting speed.

It is also possible to control the emulator’s rate of frame update using the “Refresh rate” setting; the value ranges from “1/1” (update 1/1 of the frames of the real machine, that is 50 frames per second) to “1/10” (update 1 every 10 frames) and can be changed via the “Refresh Rate” submenu. The “Auto” setting means to dynamically adapt the refresh rate to the current speed of the host machine, making sure the maximum speed specified by the via “Maximum speed” is always reached if possible. In any case, the refresh rate will never be worse than 1/10 if this option is specified.

Note that you cannot simultaneously specify “Auto” as the refresh rate and “No limit” as the maximum speed..

Moreover, a special *warp speed* mode is provided and can be toggled with the “Enable Warp Mode” menu item. If this mode is enabled, it will cause the emulator to disable any speed limit, turn sound emulation off and use a 1/10 refresh rate, so that it will run at the maximum possible speed.

### 6.3.1 Performance resources

**Speed** Integer specifying the maximum relative speed, as a percentage. 0 stands for “no limit”.

**RefreshRate** Integer specifying the refresh rate; a value of *n* specifies a refresh rate of 1/*n*. A value of 0 enables automatic frame skipping.

**WarpMode** Boolean specifying whether “warp mode” is turned on or not.

### 6.3.2 Performance command-line options

**-speed VALUE** Specifies the maximum speed as a percentage. 0 stands for “no limit”. (Same as setting the **Speed** resource.)

**-refresh VALUE** Specifies refresh rate; a value of *n* specifies a refresh rate of 1/*n*. A value of 0 enables automatic frame skipping. (Same as setting the **RefreshRate** resource.)

**-warp**

**+warp** Enables/disables warp mode (**WarpMode**=1, **WarpMode**=0).

## 6.4 Video settings

The following right-button menu items control the video output. On emulators that include two video chips (like `x128`) all options but `XSync` exist twice, once for each chip. `XSync` is shared between the video chips.

- “Video Cache” enables a video cache that can speed up the emulation when little graphics activity is going on; it is especially useful when you run the emulator on a networked X terminal as it can reduce the network bandwidth required. However, this setting can actually make the emulator slower when there is little graphics activity and the amount of work needed to maintain the cache is greater than the amount of work that would be wasted by not using it (if any).
- “Double Size” toggles *double-size mode*, which makes the emulation window twice as big. When emulating a 80-column PET, only the height is doubled, so that the aspect ratio is closer to that of the real thing.
- “Double Scan” toggles *double-scan mode*, which causes the emulator to draw only odd lines when running in double-size mode (this saves some CPU time and also makes the emulation window look more like an old monitor).
- “Use XSync()” causes the emulator to call the X11 function `XSync()` before updating the emulation window: this might be necessary on low-end systems to prevent it from consuming so many system resources that it becomes impossible for the user to interact with it.

### 6.4.1 Video resources

The following resources affect the screen emulation. The prefix of some of the resources and commandline options denote the video chip the values apply to.

**UseXSync** Boolean specifying whether `XSync()` is called after updating the emulation window.

**MITSHM** Integer specifying whether VICE should try to use the shared memory extensions (MITSHM) when starting up. The shared memory extensions make things a lot faster but might not be available on your system. You will not be able to use these extensions if you are sitting at an X terminal while running the emulator on a remote machine across a network. Valid values are: 0 = do not use MITSHM, 1 = do use MITSHM, -1 = try to autodetect availability on startup (default). The last is a simple test if the emulator runs across a network and if so disables MITSHM (If you have problems with this test please report it).

**PrivateColormap**

Boolean specifying whether VICE should install a private colormap at startup. This makes sense for 8-bit displays that could run out of colors if other color-hungry applications are running at the same time.

**DisplayDepth**

Integer specifying the depth of the host display. The value ‘0’ (the default) causes the emulator to autodetect it.

### 6.4.2 Video command-line options

**-xsync**  
**+xsync**     Enable/disable usage of `XSsync()` when updating the emulation window (`UseXSsync=1`, `UseXSsync=0`).  
  
**-mitshm**  
**+mitshm**     Enable/disable usage of the MITSHM extensions (`MITSHM=1`, `MITSHM=0`).  
  
**-install**  
**+install**     Enable/disable installation of a private colormap (`PrivateColormap=1`, `PrivateColormap=0`).  
  
**-displaydepth DEPTH**  
               Specify the display depth (`DisplayDepth`).  
  
**-fullscreen**  
**+fullscreen**  
               Enable/disable fullscreen mode

## 6.5 Keyboard settings

It is possible to specify whether the “positional” or “symbolic” keyboard mapping should be used with the “Keyboard mapping type” submenu (see [Section 2.7 \[Keyboard emulation\]](#), [page 9](#) for an explanation of positional and symbolic mappings).

The keyboard settings submenu also allows you to:

- Load custom-made positional and symbolic keymap files (“Set symbolic keymap file” and “Set positional keymap file”).
- Dump the current keymap to a user-defined keymap file (“Dump to keymap file”).

### 6.5.1 Keyboard resources

#### KeymapIndex

Integer identifying which keymap is being used; 0 indicates symbolic mapping, 1 positional mapping. For the PET the even values represent symbolic mapping, odd positional. Then add 0 for UK business keyboard or 2 for graphics keyboard.

#### KeymapSymFile

String specifying the name of the keymap file for the symbolic mapping (see [Section 2.7 \[Keyboard emulation\]](#), [page 9](#), all but PET and CBM-II).

#### KeymapPosFile

String specifying the name of the keymap file for the positional mapping (see [Section 2.7 \[Keyboard emulation\]](#), [page 9](#), all but PET and CBM-II).

#### KeymapBusinessUKSymFile

#### KeymapBusinessUKPosFile

String specifying the name of the keymap file for the symbolic and positional mapping for the UK business keyboard (see [Section 2.7 \[Keyboard emulation\]](#), [page 9](#), PET and CBM-II).

KeymapGraphicsSymFile

KeymapGraphicsPosFile

String specifying the name of the keymap file for the symbolic and positional mapping for the graphics keyboard (see [Section 2.7 \[Keyboard emulation\]](#), [page 9](#), PET only).

KeymapBusinessDESymFile

KeymapBusinessDEPosFile

String specifying the name of the keymap file for the symbolic and positional mapping for the German business keyboard. (see [Section 2.7 \[Keyboard emulation\]](#), [page 9](#), PET only).

## 6.5.2 Keyboard command-line options

**-keymap N** Specifies which keymap is being used; 0 indicates symbolic mapping, 1 positional mapping (as for the `KeymapIndex` resource).

**-symkeymap NAME**

Specify ‘NAME’ as the symbolic keymap file (`KeymapSymFile`).

**-poskeymap NAME**

Specify ‘NAME’ as the positional keymap file (`KeymapPosFile`).

**-symdekeymap NAME**

Specify ‘NAME’ as the symbolic keymap file (`KeymapSymDeFile`).

**-bksymkeymap NAME**

**-bukposkeymap NAME**

Specify ‘NAME’ as the symbolic/positional keymap file for the UK business keyboard (`KeymapBusinessUKSymFile`, `KeymapBusinessUKPosFile`, PET and CBM-II).

**-grsymkeymap NAME**

**-grposkeymap NAME**

Specify ‘NAME’ as the symbolic/positional keymap file for the graphics keyboard (`KeymapGraphicsSymFile`, `KeymapGraphicsPosFile`, PET only).

**-bdesymkeymap NAME**

**-bdeposkeymap NAME**

Specify ‘NAME’ as the symbolic/positional keymap file for the German business keyboard (`KeymapBusinessDESymFile`, `KeymapBusinessDEPosFile`, PET only).

## 6.6 Joystick settings

### 6.6.1 Joystick command-line options

**-joydev1 <0-8>**

**-joydev2 <0-8>**

Set the device for joystick emulation of port 1 and 2, respectively (`JoyDevice1`, `JoyDevice2`).



```

-extrajoydev1 <0-8>
-extrajoydev2 <0-8>
    Set device for extra joystick port 1 and 2.

-mouse
+mouse    Enable/Disable mouse grab

-mousetype <value>
    Select the mouse type (0 = 1351, 1 = NEOS, 2 = Amiga, 3 = Paddles)

-mouseport <value>
    Select the joystick port the mouse is attached to

-lightpen
+lightpen
    Enable/Disable lightpen emulation

-lightpentype <type>
    Set lightpen type

```

## 6.7 Sound settings

The following menu items control sound output:

- “Enable sound playback” turns sound emulation on and off.
- “Sound synchronization” specifies the method for synchronizing the sound playback. Possible settings are:
  - “Flexible”, i.e., the audio renderer flexibly adds/removes samples to the output to smoothly adapt the playback to slight changes in the speed of the emulator.
  - “Adjusting” works like “flexible”, but supports bigger differences in speed. For example, if the emulation speed drops down from 100% to 50%, audio slows down by the same amount too.
  - “Exact”, instead, makes the audio renderer output always the same sounds you would hear from the real thing, without trying to adapt the ratio; to compensate the tolerances in speed, some extra frames will be skipped or added.
- “Sample rate” specifies the sampling frequency, ranging from 8000 to 48000 Hz (not all the sound cards and/or sound drivers can support all the frequencies, so actually the nearest candidate will be chosen).
- “Buffer size” specifies the size of the audio buffer; the bigger the buffer, the longer the delay with which sounds are played. You should pick the smallest value your machine can handle without problems.
- “Sound suspend time”, will cause the audio playback to pause for the specified number of seconds whenever some clicking happens. If “Keep going” is selected, no pausing is done.
- “Oversample” specifies an oversampling factor, from 1 to 8 times (warning: this eats CPU cycles!).

### 6.7.1 Sound resources

**Sound**      Boolean specifying whether audio emulation is turned on.

**SoundSpeedAdjustment**

Integer specifying what speed adjustment method the audio renderer should use. Possible values are:

- 0: “flexible”
- 1: “adjusting”
- 2: “exact”

**SoundSampleRate**

Integer specifying the sampling frequency, ranging from 8000 to 48000 Hz (not all the sound cards and/or sound drivers can support all the frequencies, so actually the nearest candidate will be chosen).

**SoundBufferSize**

Integer specifying the size of the audio buffer, in milliseconds.

**SoundSuspendTime**

Integer specifying the pause interval when audio underflows (“clicks”) happen. 0 means no pause is done.

**SoundDeviceName**

String specifying the audio driver.

Implemented drivers are:

- **aix**, for the IBM AIX sound driver.
- **uss**, for the Linux/FreeBSD Universal Sound System driver (**SoundDeviceArg** specifies the audio device, `‘/dev/dsp’` by default);
- **sgi**, for the Silicon Graphics audio device (**SoundDeviceArg** specifies the audio device, `‘/dev/audio’` by default);
- **sun**, for the Solaris audio device (unfinished; **SoundDeviceArg** specifies the audio device, `‘/dev/audio’` by default).
- **hpux**, for the HP-UX audio device (unfinished; **SoundDeviceArg** specifies the audio device, `‘/dev/audio’` by default).
- **sd1**, for the Simple DirectMedia Layer audio driver.
- **esd**, for Esound, the Enlightened Sound Daemon; **SoundDeviceArg** specifies the ESD server (`‘host:port’`) to connect, empty by default.
- **dummy**, fully emulating the SID, but not actually playing samples.
- **dump**, writing all the write accesses to the registers to a file (specified by **SoundDeviceArg**, default value is `vicesnd.sid`);
- **speed**, like **dummy** but also calculating samples (mainly used to evaluate the speed of the sample generator);
- **fs**, writing samples to a file (specified by **SoundDeviceArg**; default is `‘vicesnd.raw’`);

These drivers will actually be present only if the VICE configuration script detected the corresponding devices at the time of compilation.

**SoundDeviceArg**

String specifying an additional parameter for the audio driver (see **SoundDeviceName**).

### 6.7.2 Sound command-line options

**-sound**  
**+sound** Turns sound emulation on (**Sound=1**) and off (**Sound=0**).  
**-soundsync N**  
 Specify **N** as the sound speed adjustment method (**SoundSpeedAdjustment**).  
**-soundrate RATE**  
 Specifies the sound playback sample rate (**SoundSampleRate**).  
**-soundbufsize SIZE**  
 Specifies the size of the audio buffer in milliseconds (**SoundBufferSize**).  
**-soundfragsize <value>**  
 Set sound fragment size (0 = small, 1 = medium, 2 = large)  
**-sounddev NAME**  
 Specifies the name of the audio device (**SoundDeviceName**).  
**-soundarg ARG**  
 Specifies an additional parameter for the audio device (**SoundDeviceArg**).  
**-soundrecdev <name>**  
 Specify recording sound driver  
**-soundrecarg <args>**  
 Specify initialization parameters for recording sound driver

## 6.8 Tape settings

These settings are used to control the hardware-level emulation of the Tape drive.

### 6.8.1 Tape command-line options

**-dsresetwithcpu**  
**+dsresetwithcpu**  
 Enable/Disable automatic Datasette-Reset  
**-dszerogapdelay <value>**  
 Set delay in cycles for a zero in the tap  
**-dsspeedtuning <value>**  
 Set number of cycles added to each gap in the tap

## 6.9 Drive settings

These settings are used to control the hardware-level emulation of the Disk drives. When hardware-level emulation is turned on, only drives 8 and 9 are being emulated.

The following settings affect both drives:

- “Enable true drive emulation” enables the (slow) hardware-level emulation of the drives for maximum compatibility. This must be turned on for any of the following settings to have effect.

- “Drive sync factor” specifies the speed of the drive’s CPU. This can be used to help loading certain programs that have trouble with the default PAL setting (for example, programs designed for NTSC machines). The ratio is calculated as follows:

$$\text{sync\_factor} = 65536 * \text{clk\_drive} / \text{clk\_machine}$$

where `clk_drive` and `clk_machine` are clock speeds in MHz. The menu lets you choose between the PAL and NTSC values, and also lets you specify whatever value you want. Be careful when changing it, though, because a wrong value can break things and even corrupt disk images.

The following settings, instead, are specific of each drive:

- “Drive model” specifies the model of the drive being emulated. **Warning:** This will reset the drive.
- “Enable parallel cable” enables emulation of a SpeedDOS parallel cable; if you switch this option on and replace the original Commodore ROMs with SpeedDOS-compatible ones, you can speed up loading/saving times.
- “Idle method” specifies which method the drive emulation should use to save CPU cycles in the host CPU. There are three methods:
  - *Skip cycles*: Each time the serial line is accessed by the C64, the drive executes all the cycles since the last time it ran. If the number of elapsed cycles is larger than a certain value, the drive discards part of them.
  - *Trap idle*: The disk drive is still emulated upon serial line accesses as with the previous option, but it is also always emulated at the end of each screen frame. If the drive gets into the DOS idle loop, only pending interrupts are emulated to save time.
  - *No traps*: Like “Trap idle”, but without any traps at all. So basically the drive works exactly as with the real thing, and nothing is done to reduce the power needs of the drive emulation.

The first option (“Skip cycles”) is usually best for performance, as the drive is emulated as little as possible; on the other hand, you may notice sudden slowdowns (when the drive executes several cycles at once) and the LED status is never updated (because it would not be possible to do correctly so). Moreover, if the drive tries to get in sync with the computer in some weird way and the computer does not access the serial line for a long time, it is possible that some cycles are discarded and the sync is lost. Notice that this hack will have no effect on performance if a program continuously reads from the IEC port, as the drive will have to be fully emulated in any case (some stupid programs do this, even when they don’t actually need to use the drive).

The second option (“Trap idle”) is usually a bit slower, as at least interrupts are always emulated, but ensures the LED state is always updated correctly and always keeps the drive and the computer in sync. On the other hand, if a program installs a non-standard idle loop in the drive, the drive CPU has to be emulated even when not necessary and the global emulation speed is then *much* slower.

- “40-track image support” specifies how 40-track (“extended”) disk images should be supported. There are three possible ways:
  - “Never extend” never extends disk images at all (so if a program tries to write tracks beyond the 35th, it is not allowed to do so);

- “Ask on extend” prompts the user as soon as a program tries to write tracks beyond the 35th, and the user can then choose whether he wants the disk image to be extended or not;
- “Extend on access” simply extends the disk image as soon the program needs it, without prompting the user.

### 6.9.1 Drive resources

**DriveTrueEmulation**

Boolean controlling whether the “true” drive emulation is turned on.

**Drive8Type**

**Drive9Type**

Integers specifying the model number for drives 8 and 9. Possible values are 1541, 1571, 1581 and 2031.

**Drive8ParallelCable**

**Drive9ParallelCable**

Booleans controlling whether the SpeedDOS-compatible cable is emulated or not for drives 8 and 9.

**Drive8ExtendImagePolicy**

**Drive9ExtendImagePolicy**

Integer specifying the policy for 40-track support for drives 8 and 9. Possible values are 0 (never extend), 1 (ask on extend), 2 (extend on access).

**Drive8IdleMethod**

**Drive9IdleMethod**

Integers specifying the idling method for the drive CPU. Possible values are 0 (none), 1 (skip cycles), 2 (trap idle). See [Section 6.9 \[Drive settings\], page 33](#).

**DosName1541**

**DosName1571**

**DosName1581**

**DosName2031**

Strings specifying the names of the ROM images for the drive emulation.

### 6.9.2 Drive command-line options

**-truedrive**

**+truedrive**

Turns true drive emulation on (**DriveTrueEmulation=1**) and off (**DriveTrueEmulation=0**), respectively.

**-drive8type TYPE**

**-drive9type TYPE**

**-drive10type TYPE**

**-drive11type TYPE**

Specifies the drive types for drives 8-11, respectively. Possible values for **TYPE** are 1541, 1542 (meaning 1541-II), 1551, 1570, 1571, 1573 (meaning 1571cr), 1581, 2031, 2040, 3040, 4040, 1001, 8050 and 8250.

```
-parallel8 <type>
-parallel9 <type>
-parallel10 <type>
-parallel11 <type>
```

Set parallel cable type (0: none, 1: standard, 2: Dolphin DOS)

```
-drive8idle NUM
-drive9idle NUM
-drive10idle NUM
-drive11idle NUM
```

Specifies NUM as the idling method for drives 8-11 (0: no traps, 1: skip cycles, 2: trap idle), respectively (Drive8IdleMethod, Drive9IdleMethod), Drive10IdleMethod, Drive11IdleMethod).

```
-drive8extend NUM
-drive9extend NUM
-drive10extend NUM
-drive11extend NUM
```

Specifies NUM as the track 40 extend policy in drives 8 and 9, respectively (Drive8ExtendImagePolicy, Drive9ExtendImagePolicy).

```
-dos1541 <name>
-dos1541II <name>
-dos1551 <name>
-dos1570 <name>
-dos1571 <name>
-dos1571cr <name>
-dos1581 <name>
-dos2031 <name>
-dos2040 <name>
-dos3040 <name>
-dos4040 <name>
-dos1001 <name>
```

Specify the ROM names for the 1541, 1541II, 1551, 1570, 1571, 1571cr, 1581, 2031, 2040, 3040, 4040 and 1001 emulation respectively.

```
-drive8ram2000, +drive8ram2000
-drive9ram2000, +drive9ram2000
-drive10ram2000, +drive10ram2000
-drive11ram2000, +drive11ram2000
```

Enable/Disable 8KB RAM expansion at \$2000-\$3FFF

```
-drive8ram4000, +drive8ram4000
-drive9ram4000, +drive9ram4000
-drive10ram4000, +drive10ram4000
-drive11ram4000, +drive11ram4000
```

Enable/Disable 8KB RAM expansion at \$4000-\$5FFF

```

-drive8ram6000, +drive8ram6000
-drive9ram6000, +drive9ram6000
-drive10ram6000, +drive10ram6000
-drive11ram6000, +drive11ram6000
    Enable/Disable 8KB RAM expansion at $6000-$7FFF

-drive8ram8000, +drive8ram8000
-drive9ram8000, +drive9ram8000
-drive10ram8000, +drive10ram8000
-drive11ram8000, +drive11ram8000
    Enable/Disable 8KB RAM expansion at $8000-$9FFF

-drive8rama000, +drive8rama000
-drive9rama000, +drive9rama000
-drive10rama000, +drive10rama000
-drive11rama000, +drive11rama000
    Enable/Disable 8KB RAM expansion at $A000-$BFFF

-drive8profdos, +drive8profdos
-drive9profdos, +drive9profdos
-drive10profdos, +drive10profdos
-drive11profdos, +drive11profdos
    Enable/Disable Professional DOS

-profdos1571 <name>
Specify name of Professional DOS 1571 ROM image

```

## 6.10 Peripheral settings

VICE is able to support some special peripherals:

- *file system devices*, pseudo-drives accessing the Unix file system;
- printers.

These features depend on some *kernal traps* that replace the existing routines in the original Commodore operating system with custom-made C routines.

### 6.10.1 Settings for file system devices

These settings deal with the drive-like peripherals connected to the bus of the emulated machine. The first setting relates to the parallel IEEE488 interface. With this interface a special engine is used to listen to the bus lines to translates them to the filesystem code. Thus the PET will always detect a drive for example, but it can also use drives 10 and 11 even together with true disk drive emulation.

- “Enable virtual devices”, enables the peripheral access via the fast disk emulation (either kernal traps or IEEE488 interface). Both, filesystem and disk image access via fast drive emulation, are affected.

Four peripherals, numbered from 8 to 11, are accessible; each of them provides the following settings:

- “File system access”, if enabled, allows the device to emulate a drive accessing a file system directory; note that when a disk image is attached to the same drive, the directory is no longer visible and the attached disk is used instead.

- “File system directory” specifies the directory to be accessed by the drive.
- “Convert P00 file names”, if enabled, allows access to P00 files using their built-in name instead of the Unix one.
- “Create P00 files on save”, if enabled, creates P00 files (instead of raw CBM files) whenever a program creates a file.

Note that, by default, all drives except 11 create P00 files on save, while drive 11 creates raw CBM files. Those files come without any header, but also with the filename restrictions given by the operating system VICE runs on.

### 6.10.1.1 Resources for file system devices

`FSDevice8ConvertP00`

`FSDevice9ConvertP00`

`FSDevice10ConvertP00`

`FSDevice11ConvertP00`

Booleans specifying whether on-read support for P00 files is enabled on drives 8, 9, 10 and 11 respectively (on by default).

`FSDevice8SaveP00`

`FSDevice9SaveP00`

`FSDevice10SaveP00`

`FSDevice11SaveP00`

Booleans specifying whether the drives should create P00 files instead of plain CBM ones (on by default for drives 8-10, off for 11).

`FSDevice8HideCBMFiles`

`FSDevice9HideCBMFiles`

`FSDevice10HideCBMFiles`

`FSDevice11HideCBMFiles`

Booleans specifying whether non-P00 files should be invisible to programs running in the emulator (do not hide by default).

`FSDevice8Dir`

`FSDevice9Dir`

`FSDevice10Dir`

`FSDevice11Dir`

Strings specifying the directories to which drives 8, 9, 10 and 11 have access.

### 6.10.1.2 Command-line options for file system devices

`-iecdevice8`

`+iecdevice8`

Enable/Disable IEC device emulation for device #8

`-iecdevice9`

`+iecdevice9`

Enable/Disable IEC device emulation for device #9

`-iecdevice10`

`+iecdevice10`

Enable/Disable IEC device emulation for device #10



```

-iecdevice11
+iecdevice11
    Enable/Disable IEC device emulation for device #11

-device8 <type>
-device9 <type>
-device10 <type>
-device11 <type>
    Set device type for device 8-11 (0: NONE, 1: FILESYSTEM, 2: OPENCBM,
    3: BLOCK DEVICE)

-fs8 PATH
-fs9 PATH
-fs10 PATH
-fs11 PATH
    Specify the paths for the file system access on drives 8, 9, 10 and 11, respectively
    (FSDevice8Dir, FSDevice9Dir, FSDevice10Dir and FSDevice11Dir).

-flipname <name>
    Specify name of the flip list file image

```

### 6.10.2 Printer settings

The VICE emulators can emulate printers connected to either the IEC buffer or the user port. Emulation can be achieved by redirecting the printer output to a file or by piping it through an external process. This is defined by so-called *printer device file names*; a printer device file name can be either a simple path, or a command name preceded by a pipe symbol ‘|’.

For example, printer device ‘filename’ will cause the output to be appended to the file ‘filename’, while printer device ‘|lpr’ will cause the lpr command to be executed and be fed the printer output. The printer output will not be converted but saved as printed by the emulated machine.

Up to three printer devices may be specified through the following resources:

- device 1, whose default value is `print.dump`;
- device 2, whose default value is `|lpr`.
- device 3, whose default value is `|petlp -F PS|lpr`;

So, basically, by default printer device 1 will dump printer output to ‘`print.dump`’; printer device 2 will print it via `lpr` directly to the printer and device 3 will print it via `petlp` (a not-yet-complete utility that will produce Postscript output from the Commodore printer code) and then to the printer via `lpr`.

#### 6.10.2.1 Printer resources

```

PrinterTextDevice1
PrinterTextDevice2
PrinterTextDevice3

```

Strings specifying the printer devices (see [Section 6.10.2 \[Printer settings\]](#), [page 39](#)).

Printer4TextDevice

Printer5TextDevice

Integer (ranging from 0 to 2, for device 1-3) specifying what printer device (see [Section 6.10.2 \[Printer settings\], page 39](#)) the IEC printer is using.

Printer4

Printer5 Integer specifying how the IEC printer (device 4-5) is being emulated. (0: NONE, 1: FS, 2: REAL)

Printer4Driver

Printer5Driver

String specifying the IEC printer output driver.

Printer4Output

Printer5Output

String specifying the IEC printer output device.

PrinterUserport

Boolean specifying if the user-port printer is being emulated.

PrinterUserportTextDevice

Integer (ranging from 0 to 2, for device 1-3) specifying what printer device the user-port printer is using.

PrinterUserportDriver

String specifying the user-port printer output driver.

PrinterUserportOutput

String specifying the user-port printer output device.

### 6.10.2.2 Printer command-line options

-iecdevice4

+iecdevice4

Enable/Disable IEC device emulation for device #4

-iecdevice5

+iecdevice5

Enable/Disable IEC device emulation for device #5

-device4 <type>

-device5 <type>

Set device type for device 4-5 (0: NONE, 1: FS, 2: REAL)

-prttxtdev1 <name>

-prttxtdev2 <name>

-prttxtdev3 <name>

Specify name of printer text device or dump file

-pr4txtdev <0-2>

-pr5txtdev <0-2>

Specify printer text output device for IEC printer #4-5

```

-pr4output <name>
-pr5output <name>
    Specify name of output device for device #4-5 Specify name of output device
    for device #5-5

-pr4drv <name>
-pr5drv <name>
    Specify name of printer driver for device #4-5 Specify name of printer driver
    for device #5-5

-pruser
+pruser    Enable/disable emulation of the userport printer emulation (PrUser=1,
    PrUser=0).

-prusertxtdev <0-2>
    Specify printer text output device for userport printer

-pruseroutput <name>
    Specify name of output device for the userport printer

-pruserdrv <name>
    Specify name of printer driver for the userport printer

```

### 6.10.3 Disabling kernal traps

If you have compatibility problems, you can completely disable Kernal traps with the “Disable kernal traps” option. This will of course disable all the features that depend on it, such as the fast 1541 emulation (so you will have to turn true 1541 emulation on if you want to be able to read or write disk images) and tape support.

#### 6.10.3.1 Resources to control Kernal traps

##### VirtualDevices

Boolean specifying whether all the mechanisms for virtual device emulation should be enabled. Serial IEC devices use kernal traps, parallel IEEE488 devices use an own IEEE488 engine. Both are switched on and off with this resource.

#### 6.10.3.2 Command-line options to control Kernal traps

```

-virtualdev
+virtualdev
    Enable (VirtualDevices=1) or disable (VirtualDevices=0) virtual devices.

```

## 6.11 RS232 settings

The VICE emulators can emulate the RS232 device most of the machines have. The C64, C128 and VIC20 emulators emulate the userport RS232 interface at 300 and 1200 baud. The C64 and C128 can also use the 9600 baud interface by Daniel Dallmann, using the shift registers of the two CIA 6526 chips. The PET can have a 6551 ACIA RS232 interface when running as a SuperPET, and the CBM-II has such an ACIA by default. The C64 and C128 emulators can emulate an ACIA 6551 (also known as Datapump for example) as extension at \$de\*\*.

Emulation can be achieved by either:

- connecting a real UNIX serial device;
- dumping to a file;
- piping through a process.

It is possible to define up to four UNIX serial devices, and then decide which interface should be connected to which device. This is done by so-called *rs232 device file names*; an rs232 device file name can be either a simple path, or a command name preceded by a pipe symbol '|'. If the path specifies a special device (e.g. `/dev/ttyS0`) it is recognized by VICE and the emulator can set the baudrate.

For example, rs232 device `'filename'` will cause the output to be written (not appended) to the file `'filename'`, while printer device `'|lpr'` will cause the `lpr` command to be executed and be fed the rs232 output. The rs232 output will not be converted but saved as sent by the emulated machine. The same holds true for the rs232 input. If the command writes data to the standard output it will be caught by VICE and sent back to the emulator. Also the data sent by the pseudo device will be sent back to VICE.

For example you can setup a null-modem cable between two serial ports of your PC, setup one port for login and use the other in VICE. Then you can login from your emulator via the RS232 emulation and the null-modem cable to your machine again.

You can not simply run a shell from VICE, as the shell will notice that it does not run on its own pseudo terminal and will thus buffer its output. You need to write some program that opens an own pseudo terminal and runs the shell from there (not yet finished).

Up to four RS232 devices may be specified through the following resources:

- device 1, whose default value is `/dev/ttyS0`;
- device 2, whose default value is `/dev/ttyS1`;
- device 3, whose default value is `rs232.dump`;
- device 4, whose default value is `|lpr`.

For the first two devices you can change the baudrate the tty device is set to by specifying it on the commandline or in the menu. This baudrate is 9600 by default for the latter two, but can be changed only by resources (The baudrate is independent from the baudrate the emulator actually expects).

### 6.11.1 RS232 resources

`RsDevice1`

`RsDevice2`

`RsDevice3`

`RsDevice4`

Strings specifying the RS232 devices (see [Section 6.11 \[RS232 settings\]](#), [page 41](#)).

`RsDevice1Baud`

`RsDevice2Baud`

`RsDevice3Baud`

`RsDevice4Baud`

Integer specifying the RS232 baudrate devices if the device file points to a special device (like `/dev/ttyS0`; see [Section 6.11 \[RS232 settings\]](#), [page 41](#)).

<b>Acia1Dev</b>	Integer (ranging from 0 to 3, for device 1-4) specifying what RS232 device (see <a href="#">Section 6.11 [RS232 settings], page 41</a> ) the ACIA is using (all except VIC20).
<b>Acia1Irq</b>	Integer specifying which interrupt to use. 0 = none, 1 = IRQ, 2 = NMI (C64 and C128 only)
<b>RsUserEnable</b>	Boolean specifying if the user-port RS232 interface is being emulated (C64, C128 and VIC20).
<b>RsUserBaud</b>	Integer specifying the baudrate of the user-port RS232 interface (C64, C128 and VIC20).
<b>RsUserDev</b>	Integer (ranging from 0 to 3, for device 1-4) specifying what RS232 device the user-port interface is using (C64, C128 and VIC20).

### 6.11.2 RS232 command-line options

<b>-rsdev1 NAME</b>	
<b>-rsdev2 NAME</b>	
<b>-rsdev3 NAME</b>	
<b>-rsdev4 NAME</b>	Specify NAME as RS232 devices 1, 2, 3 and 4, respectively (RsDevice1, RsDevice2 RsDevice3 and RsDevice4).
<b>-rsdev1 BAUDRATE</b>	
<b>-rsdev2 BAUDRATE</b>	
<b>-rsdev3 BAUDRATE</b>	
<b>-rsdev4 BAUDRATE</b>	Specify BAUDRATE as baudrate for the RS232 devices if the device name specifies a special device (like '/dev/ttyS0' for example, see <a href="#">Section 6.11 [RS232 settings], page 41</a> ; RsDevice1Baud, RsDevice2Baud RsDevice3Baud and RsDevice4Baud).
<b>-myaciadev &lt;0-3&gt;</b>	Specify RS232 device the ACIA should work on
<b>-rsuser</b>	
<b>+rsuser</b>	Enable or disable emulation of the userport RS232 emulation (RsUser; C64, C128 and VIC20)
<b>-rsuserbaud &lt;baud&gt;</b>	Set the baud rate of the RS232 userport emulation.
<b>-rsuserdev &lt;0-3&gt;</b>	Specify device for the userport RS232 emulation (RsUserDev; C64, C128 and VIC20).

### 6.11.3 RS232 usage example

Here we give you a simple example how to set up an emulated C64 using the modem connected to your PC. The following list shows each step.

Attach your modem to your PC at a serial port.

Normally you should set it up to use the modem as `"/dev/modem"`.

start VICE

Setup VICE to use your modem as "serial device 1"

Go to the RS232 settings menu and change "Serial 1 device" to `"/dev/modem"` (or the device where you attached your modem to) Then go to the RS232 settings menu and change "Serial 1 baudrate" to the baudrate your modem should run at. Watch out, e.g. on Linux there is an additional multiplier to multiply with the baudrate (so e.g. 19200 gives 115200 or so baud) See the "setserial" manpage on Linux for example. However, most modems should be able to autodetect the speed to the computer as well.

Select the RS232 emulation your programs use

If you want to use the Userport emulation, go to the RS232 settings and change "Userport RS232 Device" to "Serial 1". If you want ACIA emulation (swiftlink or what's it called?) then change "ACIA \$DE\*\* device" to "Serial 1".

Enable the emulation

Go to the RS232 settings and select either "ACIA \$DE\*\* emulation" or Userport 300/1200 baud or CIA 9600 baud emulation.

Load your program and start it.

If it is able to detect an RS232 cartridge like swiftlink or so, try to detect the ACIA emulation if enabled. Otherwise just set the baudrate to either 300, 1200 or 9600 according to what you enabled in the VICE menu for the userport.

## 6.12 Monitor settings

This section lists command-line options specific to the built-in monitor.

### 6.12.1 Monitor command-line options

`-moncommands FILENAME`

Execute the commands from the file `FILENAME` in the monitor after starting up. This command line switch is mainly thought to load labels and to set breakpoints. Not all other commands are useful to be executed in this way, some may even lead to strange effects.

`-initbreak <address>`

Set an initial breakpoint for the monitor. Addresses with prefix `"0x"` are hexadecimal.

`-remotemonitor`

`+remotemonitor`

Enable/Disable remote monitor

`-remotemonitoraddress <name>`

The local address the remote monitor should bind to

## 6.13 Machine settings

### 6.13.1 Machine command-line options

<code>-pal</code>	Use PAL sync factor
<code>-ntsc</code>	Use NTSC sync factor
<code>-ntscold</code>	Use old NTSC sync factor
<code>-paln</code>	Use PAL-N sync factor

## 6.14 Memory settings

### 6.14.1 Memory command-line options

<code>-raminitstartvalue &lt;value&gt;</code>	Set the value for the very first RAM address after powerup
<code>-raminitvalueinvert &lt;num of bytes&gt;</code>	Length of memory block initialized with the same value
<code>-raminitpatterninvert &lt;num of bytes&gt;</code>	Length of memory block initialized with the same pattern

## 6.15 Miscellaneous settings

This section lists generic resources that do not fit in the other categories.

### 6.15.1 Miscellaneous resources

#### Directory

String specifying the search path for system files. It is defined as a sequence of directory names, separated by colons (':'), just like the `PATH` variable in the shell. The special string '\$\$' stands for the default search path, which is initialized at startup to the following value:

`LIBDIR/EMUID:$HOME/.vice/EMUID:BOOTPATH/EMUID:LIBDIR/DRIVES:$HOME/.vice/DRIV`

where:

- `LIBDIR` is the VICE installation directory (usually `"/usr/local/lib/vice"`, `"/usr/lib/vice"` or `"/opt/vice/lib"`);
- `EMUID` is the emulation identification string (C64, C128, VIC20 or PET);
- `BOOTPATH` is the directory where the binary lies (usually `"/usr/local/bin"`, `"/usr/bin"` or `"/opt/vice/bin"`).
- `DRIVES` is the directory called "DRIVES", where the disk drive ROMs are. (The disk drive ROMs are used by all emulators, so there is an extra directory for them.)

Notice that the middle entry points to a default location in the user's home directory. Here private ROM versions (e.g. speeddos or JiffyDos) can be stored for example.

See [Chapter 4 \[System files\]](#), page 16. for a description of the method used to load the emulator's system files.

**HTMLBrowserCommand**

String specifying the command to run the help browser. The help browser can be any HTML browser, and every ‘%s’ in the string is replaced with the name of the toplevel file of the VICE documentation. For example, the default value ‘netscape %s’ runs Netscape Navigator.

**SaveResourcesOnExit**

Boolean specifying whether the emulator should save changed settings before exiting. If this is enabled, the user will be always prompted first, in case the settings have changed.

**DoCoreDump**

Boolean specifying whether the emulator should dump core when it gets a signal.

**JoyDevice1****JoyDevice2**

Integer specifying which joystick device the emulator should use for joystick emulation for ports 1 and 2, respectively (0=None, 1=Numpad, 2=Custom keys, 3=Analog joystick 1, 4=Analog joystick 2, 5=Digital joystick 1, 6=Digital joystick 2 on Unix) The available joysticks might differ depending on operating system and joystick support in the OS (Linux joystick module must be available for example).

### 6.15.2 Miscellaneous command-line options

**-directory SEARCHPATH**

Specify the system file search path (Directory).

**-htmlbrowser COMMAND**

Specify the command to run the HTML browser for the on-line help (HTMLBrowserCommand).

**-saveres**

**+saveres** Enable/disable automatic saving of settings on exit (SaveResourcesOnExit=1, SaveResourcesOnExit=0).

**-confirmexit**

Confirm quitting VICE

**+confirmexit**

Never confirm quitting VICE

**-core**

**+core** Enable/disable generation of core dumps (DoCoreDump=1, DoCoreDump=0).

## 7 Machine-specific features



## 7.1 C64/128-specific commands and settings

This section lists the settings and commands that are C64/128 specific and thus are not present in the other emulators.

### 7.1.1 Using cartridges

The cartridge system is organized in "Slots" to allow more than one cartridge connected at a time, like it can be done using an expansion port expander on a real C64 (see below).

Generally a cartridge can be enabled by attaching its respective cartridge image, or using the respective menu option for cartridges that do not require an image.

x64, x64sc and x128 allow you to attach the following kinds of images:

- ‘.crt’ images, as used by the CCS64 emulator by Per Hkan Sundell
- raw ‘.bin’ images, with or without load address

*Cartridge images* are like disk images, but contain the contents of cartridge ROM and/or RAM images instead of disk images.

To attach cartridges, use the “Attach a cartridge image” submenu. When using ‘.crt’ images, this will work for every cartridge which is supported. For raw ‘.bin’ images you might have to use command line options.

When you have successfully attached a cartridge image, you should then reset the machine to make sure the cartridge initializes itself. (Or enable the "reset on cartridge change" option).

Of course, it is also possible to detach a currently attached cartridge image (“Detach cartridge image”).

If you are using a freezer cart like an Action Replay cartridge, you can emulate the cartridge’s freeze button with the “Cartridge freeze” command.

The imaginary expansion port expander is organized in 4 slots, the cartridges are associated with them like this:

#### 7.1.1.1 Slot 0

All carts that have a passthrough connector go here. Once a "Slot 0" cartridge is enabled all further cartridges are connected to its respective passthrough port.

Only one cartridge of this type can be active at a time.

"Slot 0" carts have individual "enable" switches, enabling means enabling permanently.

The following cartridges are emulated in this slot:

- IEEE-488 Interface (<http://www.funet.fi/pub/cbm/schematics/cartridges/c64/ieee-488/eprom.bin>)
- Magic Voice
- MMC64

#### 7.1.1.2 Slot 1

Mostly RAM based cartridges which for one reason or the other might make sense to be enabled together with one of the "Main Slot" cartridges go here.

Only one cartridge of this type can be active at a time.

"Slot 1" carts have individual "enable" switches, enabling means enabling permanently  
The following cartridges are emulated in this slot:

- Double Quick Brown Box (DQBB)
- Expert Cartridge
- ISEPIC
- RamCart

### 7.1.1.3 Main Slot

All other cartridges which are not pure i/o extensions go here.

Only one cartridge of this type can be active at a time.

Cartridges in the "Main Slot" must be explicitly set as default to enable them permanently.

The following cartridges are emulated in this slot:

- generic 4K, 8K and 16K game- and ultimax cartridges
- Action Replay V5
- Action Replay MK2
- Action Replay MK3
- Action Replay MK4
- Atomic Power
- C64 Games System
- Capture
- Comal 80
- Dela EP64
- Dela EP7x8
- Dela EP256
- Diashow-Maker
- Dinamic
- EasyFlash
- Epyx FastLoad
- EXOS
- The Final Cartridge
- The Final Cartridge III
- Final Cartridge Plus
- Freeze Frame
- Freeze Machine
- Fun Play
- Game Killer
- IDE64 (<http://www.volny.cz/dundera/>)
- KCS Power Cartridge

- MACH 5
- Magic Desk
- Magic Formel
- Mikro Assembler
- MMC Replay
- Ocean
- Prophet64
- REX 256k EPROM Cart
- REX Utility
- Retro Replay
- ROSS
- Simons' BASIC
- Snapshot 64
- Stardos
- Structured BASIC
- Super Explode V5.0
- Super Games
- Super Snapshot V4
- Super Snapshot V5
- Warp Speed
- Westermann Learning
- Zaxxon

#### 7.1.1.4 I/O Slot

All carts that are pure I/O extensions go here.

Any number of "I/O Slot" Carts may be active at a time.

"I/O Slot" carts have individual "enable" switches, enabling means enabling permanently.

The following cartridges are emulated in this slot:

- ACIA (Swiftlink, Turbo232)
- DigiMAX
- Ethernet (The Final Ethernet, RR-Net)
- GEO-RAM
- MIDI (Passport, Datel, Maplin, Namesoft, Sequential)
- RAM Expansion Module (REU)
- SFX Sound Expander
- SFX Sound Sampler

### 7.1.1.5 Expected behaviour

When the emulator is run without arguments, all settings from the config file should be applied and arguments override settings from the config file.

When saving the settings to the config file it is expected that on the next run of the emulator all settings will be in the same state as they were when saved.

There is an exception to this rule: the cartridge in the "Main Slot" must be explicitly set as default before it gets saved to the config file.

**+cart** should disable ALL cartridges, including eventually activated REU, Swithlink and all similar expansionport devices.

**-cartXYZ** options should generally attach AND activate a cart of type XYZ. As a consequence, attaching carts this way which are NOT in the "Main Slot" will also enable the cart permanently.

### 7.1.1.6 Common problems

If attaching a cartridge does not work as expected, this may be because of various reasons:

- Not seldomly the CRT type is incorrectly set in `.crt` files found "in the wild". Make sure this is not the case (if in doubt use `cartconv` to verify and/or fix).
- You may have unintentionally enabled more than one cartridge at once, for example by saving the settings with REU enabled, and then later attaching a game cartridge from the command-line. The cartridge system will allow certain combinations, but (as on the real thing) not all do (can) actually work. To make sure this is not the case, either detach all cartridges from the menus, or use **+cart** on the command-line.
- The cartridge image might be broken. Try one from a different source. If you are sure the dump is ok (for example because you dumped it yourself) then make sure it is in proper linear order (on some cartridges, for example "capture", address and/or data lines at the eeprom are shuffled around so a dump made with an eeprom burner can not be used as is).
- Last not least you might have encountered a bug in the emulation. If you suspect this is the case, and you can still reproduce the bug after checking the things above, please file a bug report including the following information:
  - attach your vicerc and a reference to the cartridge binaries
  - if you can, comment in the respective DEBUGXYZ macros prominently defined at the top of these files: `src/c64/cart/c64cart.c` `src/c64/cart/c64cartmem.c` `src/c64/c64io.c` `src/c64/c64export.c` and then recompile. this will add debug output that might make it much easier to locate certain problems.

### 7.1.1.7 IEEE-488 interface

To be able to use an IEEE drive, you need to enable IEEE emulation for the emulator. To do this, follow the following steps:

Download the IEEE 488 ROM image from the CBM archives (formerly known as FUNET) Attach that image with File/Attach cartridge image/IEEE488 interface image.

Make sure you have a one-drive system only (that is, go to Settings/Peripheral Setting, uncheck "use IEC device" for all devices, go to Settings/Drive Settings and select "Floppy type" as "none" for all drives other than drive 8.

After this, all drives can be selected in x64 and x128.

### 7.1.1.8 The Final Cartridge 3

The Final Cartridge 3 detects whether a mouse is connected when it starts and disables mouse support if it doesn't detect one. So to make mouse emulation work you must either enable it on the command line, or reset the cartridge after enabling it from the user interface.

## 7.1.2 C64 cartridge settings

### 7.1.2.1 C64 cartridge resources

CartridgeReset

CartridgeType

CartridgeFile

DQBB Boolean specifying whether the Double Quick Brown Box should be emulated or not.

DQBBfilename

DQBBIImageWrite

ExpertCartridgeEnabled

Boolean specifying whether the Expert Cartridge should be emulated or not.

Expertfilename

ExpertImageWrite

ExpertCartridgeMode

IDE64Image1

IDE64Image2

IDE64Image3

IDE64Image4

IDE64Config

IDE64Cylinders

IDE64Heads

IDE64Sectors

IDE64AutodetectSize

IDE64version4

IDE64RTCOffset

IEEE488 Boolean specifying whether the IEEE488 interface should be emulated or not.

IEEE488Image

IsepicCartridgeEnabled

Boolean specifying whether ISEPIC should be emulated or not.

Isepicfilename

IsepicSwitch

IsepicImageWrite

MagicVoiceCartridgeEnabled

Boolean specifying whether the Magic Voice should be emulated or not.

MagicVoiceImage

MMC64 Boolean specifying whether the MMC64 should be emulated or not.

```

MMC64BIOSfilename
MMC64_bios_write
MMC64_flashjumper
MMC64_revision
MMC64imagefilename
MMC64_RO

MMC64_sd_type
MMCRCardImage
MMCREEPROMImage
MMCRRescueMode
MMCRImageWrite
MMCRCardRW
MMCRSDType
MMCREEPROMRW
RAMCART    Boolean specifying whether the RAMCart should be emulated or not.

RAMCARTfilename
RAMCARTImageWrite
RAMCART_RO
RAMCARTsize
RRFlashJumper
RRBankJumper
RRBiosWrite

```

### 7.1.2.2 C64 cartridge command-line options

```

+cart      Disable all cartridges (which would eventually be enabled in the config file).

-cartreset
+cartreset
            Reset/Do not reset machine if a cartridge is attached or detached

-cart8 <name>
            Attach generic 8KB cartridge image

-cart16 <name>
            Attach generic 16KB cartridge image

-cartultimax <name>
            Attach generic 16kB Ultimax cartridge image

-cartcrt <name>
            Attach CRT cartridge image

-cartap <name>
            Attach raw 32KB Atomic Power cartridge image

-cartar2 <name>
            Attach raw 16kB Action Replay MK2 cartridge image

-cartar3 <name>
            Attach raw 16KB Action Replay MK3 cartridge image

```

`-cartar4 <name>`  
Attach raw 32KB Action Replay MK4 cartridge image

`-cartar5 <name>`  
Attach raw 32KB Action Replay cartridge image

`-cartcap <name>`  
Attach raw 8kB Capture cartridge image

`-cartcomal <name>`  
Attach raw 64kB Comal 80 cartridge image

`-cartdep256 <name>`  
Attach raw Dela EP256 cartridge image

`-cartdep64 <name>`  
Attach raw Dela EP64 cartridge image

`-cartdep7x8 <name>`  
Attach raw Dela EP7x8 cartridge image

`-cartdin <name>`  
Attach raw 128kB Dinamic cartridge image

`-cartdsm <name>`  
Attach raw 8kB Diashow-Maker cartridge image

`-cartdqbb <name>`  
Attach raw 16kB Double Quick Brown Box cartridge image

`-dqbb`  
`+dqbb` Enable/Disable Double Quick Brown Box

`-dqbbimage <name>`  
Specify Double Quick Brown Box filename

`-dqbbimagerw`  
`+dqbbimagerw`  
Allow/Disallow writing to DQBB image

`-carteasy <name>`  
Attach raw EasyFlash cartridge image

`-easyflashjumper`  
`+easyflashjumper`  
Enable/Disable EasyFlash jumper

`-easyflashcrtwrite`  
`+easyflashcrtwrite`  
Allow/Disallow writing to EasyFlash .crt image

`-cartepyx <name>`  
Attach raw 8KB Epyx FastLoad cartridge image

`-cartexos <name>`  
Attach raw 8kB EXOS cartridge image

```
-cartexpert <name>
    Attach raw 8kB Expert Cartridge image

-expert
+expert    Enable/Disable the Expert Cartridge

-expertimagenam <name>
    Set Expert Cartridge image name

-expertimagerw
+expertimagerw
    Allow/Disallow writing to Expert Cartridge image

-cartfc1 <name>
    Attach raw 16kB Final Cartridge image

-cartfc3 <name>
    Attach raw 64kB Final Cartridge III image

-cartfcplus <name>
    Attach raw 32kB Final Cartridge Plus image

-cartff <name>
    Attach raw 8kB Freeze Frame image

-cartfm <name>
    Attach raw 32kB Freeze Machine image

-cartfp <name>
    Attach raw 128kB Fun Play/Power Play cartridge image

-cartgk <name>
    Attach raw 8KB Game Killer cartridge image

-cartgs <name>
    Attach raw 512kB Game System cartridge image

-cartide64 <name>
    Attach raw 64KB IDE64 cartridge image

-IDE64image1 <name>
    Specify name of IDE64 image file

-IDE64image2 <name>
    Specify name of IDE64 image file

-IDE64image3 <name>
    Specify name of IDE64 image file

-IDE64image4 <name>
    Specify name of IDE64 image file

-IDE64cyl <value>
    Set number of cylinders for the IDE64 emulation

-IDE64hds <value>
    Set number of heads for the IDE64 emulation
```



-IDE64sec <value>  
Set number of sectors for the IDE64 emulation

-IDE64autosize  
+IDE64autosize  
Autodetect/do not autodetect geometry of formatted images

-IDE64version4  
+IDE64version4  
Emulate version 4 hardware/Emulate pre version 4 hardware

-cartieee <name>  
Attach CBM IEEE-488 cartridge image

-ieee488  
+ieee488 Enable (IEEE488=1) or disable (IEEE488=0) emulation of the IEEE488 interface.

-ieee488image <name>  
Set IEEE488 interface image name

-isepic  
+isepic Enable/Disable the ISEPIC cart

-cartisepic <name>  
Attach raw 2kB ISEPIC cartridge image

-isepicimagename <name>  
Set ISEPIC image name

-isepicimagerw  
+isepicimagerw  
Allow/Disallow writing to ISEPIC image

-cartkcs <name>  
Attach raw 16kB KCS Power cartridge image

-cartks <name>  
Attach raw 24kB Kingsoft cartridge image

-cartmach5 <name>  
Attach raw 8kB MACH 5 cartridge image

-cartmd <name>  
Attach raw 32/64/128kB Magic Desk cartridge image

-cartmf <name>  
Attach raw Magic Formel cartridge image

-cartmikro <name>  
Attach raw 8kB Mikro Assembler cartridge image

-mmc64  
+mmc64 Enable/Disable the MMC64 expansion

-cartmmc64 <name>  
Attach raw 8kB MMC64 cartridge image

`-mmc64bios <name>`  
Specify name of MMC64 BIOS image

`-mmc64image <name>`  
Specify name of MMC64 image

`-mmc64readonly`  
Set the MMC64 card to read-only

`-mmc64readwrite`  
Set the MMC64 card to read/write

`-mmc64bioswrite`  
Save the MMC64 bios when changed

`-cartmmcr <name>`  
Attach raw 512kB MMC Replay cartridge image

`-mmcrrescue`  
`+mmcrrescue`  
Enable/Disable MMC Replay rescue mode

`-mmcrimagerw`  
`+mmcrimagerw`  
Allow/Disallow writing to MMC Replay image

`-mmcrcardimage <filename>`  
Specify MMC Replay card image filename

`-mmcrcardrw`  
`+mmcrcardrw`  
Allow/Disallow writes to MMC Replay card image

`-mmcreepromimage`  
Specify MMC Replay EEPROM image filename

`-mmcreepromrw`  
`+mmcreepromrw`  
Allow/Disallow writes to MMC Replay EEPROM image

`-cartmv <name>`  
Attach raw 16kB Magic Voice cartridge image

`-cartocean <name>`  
Attach raw Ocean cartridge image

`-cartp64 <name>`  
Attach raw 256KB Prophet 64 cartridge image

`-cartpf <name>`  
Attach raw 64kb Pagefox cartridge image

`-cartramcart <name>`  
Attach raw RamCart cartridge image

`-ramcart`  
`+ramcart` Enable/Disable the RAMCART expansion

`-ramcartsize <size in KB>`  
Size of the RAMCART expansion

`-ramcartimage <name>`  
Specify name of RAMCART image

`-ramcartimagerw`  
`+ramcartimagerw`  
Allow/Disallow writing to RAMCart image

`-cartrep256 <name>`  
Attach raw REX EP256 cartridge image

`-cartross <name>`  
Attach raw 16/32kB ROSS cartridge image

`-cartrr <name>`  
Attach raw 64KB Retro Replay cartridge image

`-rrbioswrite`  
`+rrbioswrite`  
Enable/Disable saving of the RR ROM at exit

`-rrbankjumper`  
`+rrbankjumper`  
Set/Unset RR Bank Jumper

`-rrflashjumper`  
`+rrflashjumper`  
Set/Unset RR Flash Jumper

`-cartru <name>`  
Attach raw 8kB REX Utility cartridge image

`-carts64 <name>`  
Attach raw 4kB Snapshot 64 cartridge image

`-cartsb <name>`  
Attach raw Structured Basic cartridge image

`-cartse5 <name>`  
Attach raw 16kB Super Explode V5 cartridge image

`-cartsg <name>`  
Attach raw 64kB Super Games cartridge image

`-cartsimon <name>`  
Attach raw 16kB Simons Basic cartridge image

`-cartss4 <name>`  
Attach raw 32KB Super Snapshot V4 cartridge image

`-cartss5 <name>`  
Attach raw 64KB Super Snapshot V5 cartridge image

`-cartstar <name>`  
Attach raw 16KB Stardos cartridge image

```
-cartwl <name>
    Attach raw 16KB Westermann Learning cartridge image

-cartws <name>
    Attach raw 8kB Warp Speed cartridge image

-cartzaxxon <name>
    Attach raw 16kB Zaxxon cartridge image
```

### 7.1.3 CIA settings

#### 7.1.3.1 CIA command-line options

```
-ciamodel <model>
    Set both CIA models (0 = old 6526, 1 = new 6526A)

-cia1model <model>
    Set CIA 1 model (0 = old 6526, 1 = new 6526A)

-cia2model <model>
    Set CIA 2 model (0 = old 6526, 1 = new 6526A)
```

### 7.1.4 VIC-II settings

These settings control the emulation of the VIC-II (MOS6569) video chip used in both the C64 and the C128.

- “Sprite-sprite collisions” and “Sprite-background collisions”, if enabled, cause the hardware detection of sprite-to-sprite and sprite-to-background collisions of the VIC-II to be emulated. This feature is used by many games, and disabling either of the two detection systems can sometimes make you invincible (although there is also a chance that also enemies become invincible then).
- “Color set” can be used to dynamically change the palette file being used by choosing one of the available predefined color sets:
  - ‘default.vpl’ (“default”), the default VICE palette;
  - ‘c64s.vpl’ (“C64S”), palette taken from the shareware C64S emulator by Miha Peternel.
  - ‘ccs64.vpl’ (“CCS64”), palette taken from the shareware CCS64 emulator by Per Hkan Sundell.
  - ‘frodo.vpl’ (“Frodo”), palette taken from the free Frodo emulator by Christian Bauer (<http://www.uni-mainz.de/~bauec002/FRMain.html>).
  - ‘pc64.vpl’ (“PC64”), palette taken from the free PC64 emulator by Wolfgang Lorenz.
  - ‘godot.vpl’ (“GoDot”), palette as suggested by the authors of the C64 graphics package GoDot (<http://users.aol.com/howtgodot/welcome.htm>).

#### 7.1.4.1 VIC-II resources

```
VICIICheckSsColl
    Boolean specifying whether the sprite-sprite hardware collision detection must
    be emulated.
```

**VICIICheckSbColl**

Boolean specifying whether the sprite-background hardware collision detection must be emulated.

**VICIIVideoCache**

Boolean specifying whether the video cache is turned on.

**VICIIDoubleSize**

Boolean specifying whether double-size mode is turned on.

**VICIIDoubleScan**

Boolean specifying whether double-scan mode is turned on.

**VICIIPaletteFile**

String specifying the name of the palette file being used. The ‘.vpl’ extension is optional.

**7.1.4.2 VIC-II command-line options****-VICIICheckss****+VICIICheckss**

Enable (VICIICheckSsColl=1) and disable (VICIICheckSsColl=0) emulation of hardware sprite-sprite collision detection, respectively.

**-VICIIChecksb****+VICIIChecksb**

Enable (VICIICheckSbColl=1) and disable (VICIICheckSbColl=0) emulation of hardware sprite-background collision detection, respectively.

**-VICIIVcache****+VICIIVcache**

Enable/disable the video cache (VICIIVideoCache=1, VICIIVideoCache=0).

**-VICIIDsize****+VICIIDsize**

Enable/disable the double size mode (VICIIDoubleSize=1, VICIIDoubleSize=0).

**-VICIIDscan****+VICIIDscan**

Enable/disable the double scan mode (VICIIDoubleScan=1, VICIIDoubleScan=0).

**-VICIIhwscale****+VICIIhwscale**

Enable/Disable hardware scaling

**-VICIIscale2x****+VICIIscale2x**

Enable/Disable Scale2x

**-VICIIintpal**

Use an internal calculated palette

`-VICIIextpal`  
Use an external palette (file)

`-VICIIPalette NAME`  
Specify NAME as the palette file (`VICIIPaletteFile`).

`-VICIIfulldevice <device>`  
Select fullscreen device

`-VICIIXRANDRfullmode <mode>`  
Select fullscreen mode

`-VICIIVidmodefullmode <mode>`  
Select fullscreen mode

`-VICIIBorders <mode>`  
Set VIC-II border display mode (0: normal, 1: full, 2: debug)

`-VICIImodel <model>`  
Set VIC-II model (6569/6569r1/8565/6567/8562/6567r56a). This setting is only available in `x64sc`.

`-newluminance`  
`+newluminance`  
Enable/Disable new luminances.

`-saturation <0-2000>`  
Set saturation of internal calculated palette [1000]

`-contrast <0-2000>`  
Set contrast of internal calculated palette [1000]

`-brightness <0-2000>`  
Set brightness of internal calculated palette [1000]

`-gamma <0-4000>`  
Set gamma of internal calculated palette [2200]

`-tint <0-2000>`  
Set tint of internal calculated palette [1000]

`-oddlinesphase <0-2000>`  
Set phase for color carrier in odd lines [1250]

`-oddlinesoffset <0-2000>`  
Set phase offset for color carrier in odd lines [750]

`-crtblur <0-1000>`  
Amount of horizontal blur for the CRT emulation. [500]

`-crtscanlineshade <0-1000>`  
Amount of scan line shading for the CRT emulation [667]

### 7.1.5 SID settings

These settings control the emulation of the SID (MOS6581 or MOS8580) audio chip.

- “Second SID” maps a second SID chip into the address space for stereo sound. This emulates e.g. the “SID Symphony Stereo Cartridge” from Dr. Evil Laboratories. The second SID can be used with software such as “Stereo SID Player” by Mark Dickenson or “The Enhanced Sidplayer” by Craig Chamberlain.
- “Second SID base address” sets the start address for the second SID chip. Software normally uses \$DE00 or \$DF00, since \$DE00-\$DEFF and \$DF00-\$DFFF can be mapped through the cartridge port of the C64. The default start address is \$DE00.
- “Emulate filters” causes the built-in programmable filters of the SID chip to be emulated. A lot of C64 music requires them to be emulated properly, but their emulation requires some additional processor power.
- “ChipModel” specifies the model of the SID chip being emulated: there are two slightly different generations of SID chips: MOS6581 ones and MOS8580 ones.
- “Use reSID emulation” specifies whether the more accurate (and resource hungry) reSID emulation is turned on or off.
- “reSID sampling method” selects the method for conversion of the SID output signal to a sampling rate appropriate for playback by standard digital sound equipment. Possible settings are:
  - “Fast” simply clocks the SID chip at the output sampling frequency, picking the nearest sample. This yields acceptable sound quality, but sampling noise is noticeable in some cases, especially with SID combined waveforms. The sound emulation is still cycle exact.
  - “Interpolating” clocks the SID chip each cycle, and calculates each sample with linear interpolation. The sampling noise is now strongly attenuated by the SID external filter (as long as “Emulate filters” is selected), and the linear interpolation further improves the sound quality.
  - “Resampling” clocks the SID chip each cycle, and uses the theoretically correct method for sample generation. This delivers CD quality sound, but is extremely CPU intensive, and is thus most useful for non-interactive sound generation. Unless you have a very fast machine, that is.
- “reSID resampling passband” specifies the percentage of the total bandwidth allocated to the resampling filter passband. The work rate of the resampling filter is inversely proportional to the remaining transition band percentage. This implies that e.g. with the transition band starting at ~ 20kHz, it is faster to generate 48kHz than 44.1kHz samples. For CD quality sound generation at 44.1kHz the passband percentage should be set to 90 (i.e. the transition band starting at almost 20kHz).

#### 7.1.5.1 SID resources

**SidStereo**

Boolean selecting emulation of a second SID.

**SidStereoAddressStart**

Integer specifying the start address for the second SID.

**SidFilters**

Boolean specifying whether the built-in SID filters must be emulated.

**SidModel** Integer specifying what model of the SID must be emulated (0: MOS6581, 1: MOS8580).

**SidEngine****SidResidSampling**

Integer specifying the sampling method (0: Fast, 1: Interpolation, 2: Resampling)

**SidResidPassband**

Integer specifying the resampling filter passband in percentage of the total bandwidth (0 - 90).

**7.1.5.2 SID command-line options****-sidstereo**

Emulates a second SID chip for stereo sound (**SidStereo**).

**-sidstereoaddress ADDRESS**

Specifies the start address for the second SID chip (**SidStereoAddressStart**).

**-sidenginemodel <engine and model>**

Specify **SID engine** and **MODEL** for the emulated SID chip ( 0: FastSID 6581, 1: FastSID 8580, 256: ReSID 6581, 257: ReSID 8580, 258: ReSID 8580 + digiboost, 1024: ParSID in par port 1, 1280: ParSID in par port 2, 1536: ParSID in par port 3, 1800: ReSID-FP 6581R3 4885, 1801: ReSID-FP 6581R3 0486S, 1802: ReSID-FP 6581R3 3984, 1803: ReSID-FP 6581R4 AR 3789, 1804: ReSID-FP 6581R3 4485, 1805: ReSID-FP 6581R4 1986S, 1808: ReSID-FP 8580R5 3691, 1809: ReSID-FP 8580R5 3691 + digiboost, 1810: ReSID-FP 8580R5 1489, 1811: ReSID-FP 8580R5 1489D).

**-sidfilters****+sidfilters**

Enable (**SidFilters=1**) or disable (**SidFilters=0**) emulation of the built-in SID filters.

**-residsamp METHOD**

Specifies the sampling method; fast (**SidResidSampling=0**), interpolating (**SidResidSampling=1**), resampling (**SidResidSampling=2**), fast resampling (**SidResidSampling=3**).

**-residpass PERCENTAGE**

Specifies the resampling filter passband in percentage of the total bandwidth (**SidResidPassband=0-90**).

**-residgain PERCENTAGE**

Specifies reSID gain in percent (90 - 100).

**-residfilterbias <number>**

reSID filter bias setting, which can be used to adjust DAC bias in millivolts.



### 7.1.6 C64 I/O extension settings

I/O extensions are (usually) cartridges which do not map into ROM space, but use only the I/O space at address range \$DE00 . . . \$DEFF and/or \$DF00 . . . \$DFFF.

Please use these extensions only when needed, as they might cause compatibility problems.

The following I/O extensions are available:

- ACIA (Swiftlink, Turbo232)
- DigiMAX
- Ethernet (The Final Ethernet, RR-Net)
- GEO-RAM
- MIDI (Passport, Datel, Maplin, Namesoft, Sequential)
- REU - The “RAM Expansion Module” extension emulates a standard Commodore RAM Expansion Unit; this can be used with GEOS and other programs that are designed to take advantage of it. This currently works only in the C64 emulator.
- SFX Sound Expander
- SFX Sound Sampler

#### 7.1.6.1 C64 I/O extension resources

TODO

Acia1Enable

Boolean specifying whether the ACIA (Swiftlink, Turbo232) cartridge should be emulated or not.

DIGIMAX Boolean specifying whether the DigiMAX cartridge should be emulated or not.

DIGIMAXbase

ETHERNET\_INTERFACE

ETHERNET\_DISABLED

ETHERNET\_ACTIVE

ETHERNET\_AS\_RR

GEORAM Boolean specifying whether the GEO-RAM cartridge should be emulated or not.

GEORAMfilename

GEORAMImageWrite

GEORAMsize

MIDIEnable

Boolean specifying whether the MIDI cartridge should be emulated or not.

MIDIMode

REU Boolean specifying whether the RAM Expansion Module should be emulated or not.

REUfilename

REUImageWrite

REUsize

**SFXSoundExpander**

Boolean specifying whether the SFX Sound Expander should be emulated or not.

**SFXSoundExpanderChip****SFXSoundSampler**

Boolean specifying whether the SFX Sound Sampler should be emulated or not.

**7.1.6.2 C64 I/O extension command-line options****-acia1**

**+acia1** Enable/Disable the \$DE\*\* ACIA RS232 interface emulation

**-digimax**

**+digimax** Enable/Disable the DigiMAX cartridge

**-digimaxbase <base address>**

Base address of the DigiMAX cartridge

**-miditype <0-4>**

MIDI interface type (0: Sequential, 1: Passport, 2: DATEL, 3: Namesoft, 4: Maplin)

**-midi**

**+midi** Enable/Disable MIDI emulation

**-midiin <name>**

Specify MIDI-In device

**-midiout <name>**

Specify MIDI-Out device

**-mididrv <driver>**

Specify MIDI driver (0 = OSS, 1 = ALSA)

**-georam**

**+georam** Enable/Disable the GEORAM expansion unit

**-cartgeoram <name>**

Attach raw GEO-RAM cartridge image

**-georamimage <name>**

Specify name of GEORAM image

**-georamimagerw****+georamimagerw**

Allow/Disallow writing to GEORAM image

**-georamsize <size in KB>**

Size of the GEORAM expansion unit

**-reu**

**+reu** Enable (REU=1) or disable (REU=0) emulation of the RAM Expansion Module.

**-cartreu <name>**

Attach raw REU cartridge image

```

-reuimage <name>
    Specify name of REU image

-reuimagerw
+reuimagerw
    Allow/Disallow writing to REU image

-reusize <size in KB>
    Size of the RAM expansion unit

-sfxse
+sfxse    Enable/Disable the SFX soundexpander cartridge

-sfxsetype <type>
    Set YM chip type (3526 / 3812)

-sfxss
+sfxss    Enable/Disable the SFX Sound Sampler cartridge

-tfe
+tfe      Enable/Disable the TFE ("The Final Ethernet") unit

-tfeif <name>
    Set the system ethernet interface for TFE emulation

-tferrnet
+tferrnet
    Enable/Disable RRNet mode of TFE emulation

```

### 7.1.7 C64/128 system ROM settings

These settings can be used to control what system ROMs are loaded in the C64/128 emulators at startup. They cannot be changed from the menus.

#### 7.1.7.1 C64/128 system ROM resources

**KernalName**  
String specifying the name of the Kernal ROM (default 'kernal').

**BasicName**  
String specifying the name of the Basic ROM (default 'basic'). In the C128 emulator, the ROM image must actually include the editor ROM too.

**ChargenName**  
String specifying the name of the character generator ROM (default 'chargen').

**KernalRev**  
String specifying the Kernal revision. This resource can be used to control what revision of the C64 kernal is being used; it cannot be changed at runtime. VICE is able to automatically convert one ROM revision into another, by manually patching the loaded image. This way, it is possible to use any of the ROM revisions without changing the ROM set. Valid values are:

0	Kernal revision 0;
3	Kernal revision 3;

<b>sx</b>	
67	Commodore SX-64 ROM;
100	
4064	Commodore 4064 (also known as “PET64” or “Educator 64”) ROM.

### 7.1.7.2 C64/128 system ROM command-line options

- kernal NAME**  
Specify ‘NAME’ as the Kernal ROM file (`KernalName`).
- basic NAME**  
Specify ‘NAME’ as the Basic ROM file (`BasicName`).
- chargen NAME**  
Specify ‘NAME’ as the character generator ROM file (`ChargenName`).
- kernalrev REVISION**  
Specify Kernal revision (`KernalRev`).

## 7.1.8 C64 settings

### 7.1.8.1 C64 command-line options

- gluelogictype <type>**  
Set glue logic type (0 = discrete, 1 = 252535-01)
- plus60k**  
**+plus60k** Enable/Disable the PLUS60K RAM expansion
- plus60kimage <name>**  
Specify name of PLUS60K image
- plus60kbase <base address>**  
Base address of the PLUS60K expansion
- plus256k**  
**+plus256k** Enable/Disable the PLUS256K RAM expansion
- plus256kimage <name>**  
Specify name of PLUS256K image
- 256k**  
**+256k** Enable/Disable the 256K RAM expansion
- 256kimage <name>**  
Specify name of 256K image
- 256kbase <base address>**  
Base address of the 256K expansion

## 7.2 C128-specific commands and settings

### 7.2.1 VDC settings

#### 7.2.1.1 VDC command-line options

`-VDCvcache`  
`+VDCvcache`  
Enable/Disable the video cache

`-VDCdsize`  
`+VDCdsize`  
Enable/Disable double size

`-VDCdscan`  
`+VDCdscan`  
Enable/Disable double scan

`-VDChwscale`  
`+VDChwscale`  
Enable/Disable hardware scaling

`-VDCintpal`  
Use an internal calculated palette

`-VDCextpal`  
Use an external palette (file)

`-VDCpalette <name>`  
Specify name of file of external palette

`-VDCfulldevice <device>`  
Select fullscreen device

`-VDCXRANDRfullmode <mode>`  
Select fullscreen mode

`-VDCVidmodefullmode <mode>`  
Select fullscreen mode

`-VDC16KB` Set the VDC memory size to 16KB

`-VDC64KB` Set the VDC memory size to 64KB

`-VDCRevision <number>`  
Set VDC revision (0..2)

`-saturation <0-2000>`  
Set saturation of internal calculated palette [1000]

`-contrast <0-2000>`  
Set contrast of internal calculated palette [1000]

`-brightness <0-2000>`  
Set brightness of internal calculated palette [1000]

`-gamma <0-4000>`  
Set gamma of internal calculated palette [2200]

`-tint <0-2000>`  
Set tint of internal calculated palette [1000]

`-oddlinesphase <0-2000>`  
Set phase for color carrier in odd lines [1250]

`-oddlinesoffset <0-2000>`  
Set phase offset for color carrier in odd lines [750]

`-crtblur <0-1000>`  
Amount of horizontal blur for the CRT emulation. [500]

`-crtscanlineshade <0-1000>`  
Amount of scan line shading for the CRT emulation [667]

## 7.2.2 C128 system ROM settings

### 7.2.2.1 C128 system ROM command-line options

`-basic64 <name>`  
Specify name of C64 mode BASIC ROM image

`-kernel64 <name>`  
Specify name of C64 mode Kernal ROM image

`-basiclo <name>`  
Specify name of BASIC ROM image (lower part)

`-basichi <name>`  
Specify name of BASIC ROM image (higher part)

`-kernel <name>`  
Specify name of international Kernal ROM image

`-kernelde <name>`  
Specify name of German Kernal ROM image

`-kernelfi <name>`  
Specify name of Finnish Kernal ROM image

`-kernelfr <name>`  
Specify name of French Kernal ROM image

`-kernelit <name>`  
Specify name of Italian Kernal ROM image

`-kernelno <name>`  
Specify name of Norwegian Kernal ROM image

`-kernelse <name>`  
Specify name of Swedish Kernal ROM image

`-chargen <name>`  
Specify name of international character generator ROM image

**-chargde <name>**  
Specify name of German character generator ROM image

**-chargfr <name>**  
Specify name of French character generator ROM image

**-chargse <name>**  
Specify name of Swedish character generator ROM image

**-intfunc**  
**+intfunc** Enable/Disable the internal Function ROM

**-intfrom <name>**  
Specify name of internal Function ROM image

**-extfunc**  
**+extfunc** Enable/Disable the external Function ROM

**-extfrom <name>**  
Specify name of external Function ROM image

### 7.2.3 C128 settings

#### 7.2.3.1 C128 command-line options

**-40col** Activate 40 column mode

**-80col** Activate 80 column mode

**-go64** Always switch to C64 mode on reset

**+go64** Always switch to C128 mode on reset

## 7.3 C64DTV-specific commands and settings

This section lists the settings and commands that are C64DTV specific and thus are not present in the other emulators.

### 7.3.1 C64DTV ROM image

The DTV has a 2MB Flash chip which contains the kernal, basic and character set ROMs along with other data, such as games in the case of the original C64DTV ROM.

The image file is a dump of the flash chip. It is exactly 2MB (2097152 bytes).

If you do not have a suitable image file, an image using the C64 kernal, basic and charset is automatically created.

If writing to the C64DTV ROM is enabled, the image file is rewritten with the current data when exiting x64dtv.

Note that x64dtv tries to load the image file from the C64DTV directory first, and if it isn't found there, x64dtv tries to load it from the current directory. If you do not have 'dtvrom.bin' in your C64DTV directory and writing to DTV ROM is enabled, the 'dtvrom.bin' file is created to the current directory.

NOTE: The original C64DTV ROM has somewhat distorted colors, normally you should use a patched rom.

**-c64dtvromimage NAME**

Specify 'NAME' as the C64DTV ROM image

**-c64dtvromrw**

**+c64dtvromrw**

Enable or disable writing to C64DTV ROM image

The trueflashfs option is analogous to True drive emulation. If disabled, any file access to the flash filesystem (device 1) will go to the local file system instead.

**-trueflashfs**

**+trueflashfs**

Enable or disable true hardware flash file system

**-fsflash NAME**

Specify 'NAME' as directory for flash file system device

### 7.3.2 DTV revision

The DTV revision 2 has a bug in the Blitter. Using revision 3 is recommended. Emulation of DTV revision 2 including Blitter bug is intended for testing DTV software.

**-dtvrev REVISION**

Specify DTV 'REVISION' (2 or 3)

### 7.3.3 LumaFix

The PAL C64DTVs have wrong resistors in the video output circuit, which causes incorrect luminances. Several hardware solutions ("LumaFixes") have been developed to fix this flaw.

The fixed video output is emulated by selecting "New Luminances". The unmodified C64DTV video output can be emulated with "Old Luminances".

The default setting is "New Luminances".

### 7.3.4 Userport

The C64DTV userport emulation currently supports three devices: Hummer ADC, userport joystick and PS/2 mouse.

The joystick that controls either the Hummer ADC or userport joystick can be selected using the same parameter or menu option.

While using the Hummer ADC, joystick UP and DOWN are mapped to the Hummer buttons A and B respectively. LEFT and RIGHT set the ADCs output to 0 and 255. Centering the joystick results in the ADC value of 128.

Currently the Hummer ADC and userport joystick are mutually exclusive. This means that enabling one disables the other. PS/2 mouse emulation can be used simultaneously with either Hummer ADC or userport joystick.

**-hummeradc**

**+hummeradc**

Enable/Disable Hummer ADC

**-ps2mouse**

**+ps2mouse**

Enable or disable PS/2 mouse on userport



### 7.3.5 Debug

Debugging information on Blitter, DMA and Flash can be enabled with command line parameters. This can be useful for DTV software development.

```
-dtvblitterlog
+dtvblitterlog
    Enable or disable DTV Blitter log

-dtvdmalog
+dtvdmalog
    Enable or disable DTV DMA log

-dtvflashlog
+dtvflashlog
    Enable or disable DTV Flash log
```

### 7.3.6 Monitor DTV features

Currently the registers A, Y and X are registers R0, R1 and R2 regardless of the mapping, which can be seen and modified via the registers ACM and XYM.

The monitor can access all 2MB of RAM and 2MB of Flash, but only 64 kB at a time. The 64kB bank can be selected with "bank ram00".. "ram1f" for RAM and "bank rom00".. "rom1f" for Flash.

The "load" command can load large files (>64kB) correctly if the bank is set to "ramXX", where XX is the starting bank (usually "bank00").

## 7.4 VIC20-specific commands and settings

This section lists the settings and commands that are VIC20-specific and thus are not present in the other emulators.

### 7.4.1 Using cartridge images

As with the C64 (see [Section 7.1.1 \[C64 cartridges\]](#), page 47), it is possible to attach several types of cartridge images:

- 4 or 8 Kbyte cartridges located at \$2000;
- 4 or 8 Kbyte cartridges located at \$4000;
- 4 or 8 Kbyte cartridges located at \$6000;
- 4 or 8 Kbyte cartridges located at \$A000;
- 4 Kbyte cartridges located at \$B000.

This can all be done via the “Attach cartridge image...” command in the left-button menu. It is also possible to let xvix “guess” the type of cartridge using “Smart-attach cartridge image...”.

Notice that several cartridges are actually made up of two pieces (and two files), that need to be loaded separately at different addresses. In that case, you have to know the addresses (which are usually specified in the file name) and use the “attach” command twice.

A special kind of cartridge file is where the two files mentioned above are concatenated (with removing the two byte load address of the second image) into one 16k image. There are only few of those images, though. Normally the second part is located at \$A000. Vice can now attach such concatenated files at the start address \$2000, \$4000, and \$6000. The second half of such an image is moved to \$A000. If you encounter 16k images that have the second half not at \$A000 you can split the image into two halves (i.e. one 8194 byte and one 8192 byte, because the first has the load address) and attach both files separately.

One cartridge that is currently only partially supported here is the VIC1112 IEEE488 interface. You have to load the ROM as a cartridge, but you also have to enable the IEEE488 hardware by menu.

## 7.4.2 VIC20 cartridge settings

### 7.4.2.1 VIC20 cartridge command-line options

```
-cart2 <name>
    Specify 4/8/16K extension ROM name at $2000

-cart4 <name>
    Specify 4/8/16K extension ROM name at $4000

-cart6 <name>
    Specify 4/8/16K extension ROM name at $6000

-cartA <name>
    Specify 4/8K extension ROM name at $A000

-cartB <name>
    Specify 4K extension ROM name at $B000

-cartgeneric <name>
    Specify generic extension ROM name

-cartmega <name>
    Specify Mega-Cart extension ROM name

-mcnvramfile <name>
    Set Mega-Cart NvRAM filename

-mcnvramwriteback
+mcnvramwriteback
    Enable/Disable Mega-Cart NvRAM writeback

-cartfe <name>
    Specify Final Expansion extension ROM name

-fewriteback
+fewriteback
    Enable/Disable Final Expansion write back to ROM file

-cartfp <name>
    Specify Vic Flash Plugin extension ROM name
```

`-fpwriteback`  
`+fpwriteback`      Enable/Disable Vic Flash Plugin write back to ROM file  
  
`-ieee488`  
`+ieee488`      Enable/Disable VIC-1112 IEEE488 interface  
  
`-sidcart`  
`+sidcart`      Enable/Disable SID Cartridge

### 7.4.3 VIC settings

#### 7.4.3.1 VIC resources

**VICVideoCache**  
                 Boolean specifying whether the video cache is turned on.  
  
**VICDoubleSize**  
                 Boolean specifying whether double-size mode is turned on.  
  
**VICDoubleScan**  
                 Boolean specifying whether double-scan mode is turned on.  
  
**VICPaletteFile**  
                 String specifying the name of the palette file being used. The ‘.vpl’ extension is optional.

#### 7.4.3.2 VIC command-line options

`-VICvcache`  
`+VICvcache`      Enable/disable the video cache (VICVideoCache=1, VICVideoCache=0).  
  
`-VICdsize`  
`+VICdsize`      Enable/disable the double size mode (VICDoubleSize=1, VICDoubleSize=0).  
  
`-VICdscan`  
`+VICdscan`      Enable/disable the double scan mode (VICDoubleScan=1, VICDoubleScan=0).  
  
`-VIChwscale`  
`+VIChwscale`      Enable/Disable hardware scaling  
  
`-VICscale2x`  
`+VICscale2x`      Enable/Disable Scale2x  
  
`-VICpalette NAME`  
                 Specify NAME as the palette file (VICPaletteFile).  
  
`-VICintpal`  
                 Use an internal calculated palette

```

-VICextpal
    Use an external palette (file)

-VICfulldevice <device>
    Select fullscreen device

-VICXRANDRfullmode <mode>
    Select fullscreen mode

-VICVidmodefullmode <mode>
    Select fullscreen mode

-saturation <0-2000>
    Set saturation of internal calculated palette [1000]

-contrast <0-2000>
    Set contrast of internal calculated palette [1000]

-brightness <0-2000>
    Set brightness of internal calculated palette [1000]

-gamma <0-4000>
    Set gamma of internal calculated palette [2200]

-tint <0-2000>
    Set tint of internal calculated palette [1000]

-oddlinesphase <0-2000>
    Set phase for color carrier in odd lines [1250]

-oddlinesoffset <0-2000>
    Set phase offset for color carrier in odd lines [750]

-crtblur <0-1000>
    Amount of horizontal blur for the CRT emulation. [500]

-crtscanlineshade <0-1000>
    Amount of scan line shading for the CRT emulation [667]

```

#### 7.4.4 Changing memory configuration

It is possible to change the VIC20 memory configuration in two ways: by enabling and/or disabling certain individual memory blocks, or by choosing one among a few typical memory configurations. The former can be done by modifying resource values directly or from the right-button menu; the latter can only be done from the menu.

There are 5 RAM expansion blocks in the VIC20, numbered 0, 1, 2, 3 and 5:

- block 0 (3 Kbytes at \$0400-\$0FFF);
- block 1 (8 Kbytes at \$2000-\$3FFF);
- block 2 (8 Kbytes at \$4000-\$5FFF);
- block 3 (8 Kbytes at \$6000-\$7FFF);
- block 5 (8 Kbytes at \$A000-\$BFFF).

These blocks are called *expansion blocks* because they are not present a stock (“unexpanded”) machine. Each of them is associated to a boolean `RamBlockX` resource (where `X` is the block number) that specifies whether the block is enabled or not.

There are also some common memory configurations you can pick from the right-button menu:

- no RAM expansion blocks at all;
- all RAM expansion blocks enabled;
- 3K expansion (only block 0 is enabled);
- 8K expansion (only block 1 is enabled);
- 16K expansion (only blocks 1 and 2 are enabled);
- 24K expansion (only blocks 1, 2 and 3 are enabled).

#### 7.4.4.1 VIC20 memory configuration resources

`RAMBlock0`  
`RAMBlock1`  
`RAMBlock2`  
`RAMBlock3`  
`RAMBlock5`

Booleans specifying whether RAM blocks 0, 1, 2, 3 and 5 must be enabled.

#### 7.4.4.2 VIC20 memory configuration command-line options

`-memory CONFIG`

Specify memory configuration. It must be a comma-separated list of options, each of which can be one the following:

- `none` (no extension);
- `all` (all blocks);
- `3k` (3k space in block 0);
- `8k` (first 8k extension block);
- `16k` (first and second 8k extension blocks);
- `24k` (first, second and 3rd extension blocks);
- `0, 1, 2, 3, 5` (memory in respective blocks);
- `04, 20, 40, 60, A0` (memory at respective address).

For example,

```
xvic -memory none
```

gives an unexpanded VIC20. While

```
xvic -memory 60,a0
```

or

```
xvic -memory 3,5
```

enables memory in blocks 3 and 5, which is the usual configuration for 16k ROM modules.

### 7.4.5 VIC20 system ROM settings

These settings can be used to control what system ROMs are loaded in the VIC20 emulator at startup. They cannot be changed from the menus.

#### 7.4.5.1 VIC20 system ROM resources

**KernalName**

String specifying the name of the Kernal ROM (default ‘**kernal**’).

**BasicName**

String specifying the name of the Basic ROM (default ‘**basic**’).

**ChargenName**

String specifying the name of the character generator ROM (default ‘**chargen**’).

**GenericCartridgeFile2000**

**GenericCartridgeFile4000**

**GenericCartridgeFile6000**

**GenericCartridgeFileA000**

**GenericCartridgeFileB000**

String specifying the name of the respective cartridge ROM images.

#### 7.4.5.2 VIC20 system ROM command-line options

**-kernal NAME**

Specify ‘NAME’ as the Kernal ROM file (**KernalName**).

**-basic NAME**

Specify ‘NAME’ as the Basic ROM file (**BasicName**).

**-chargen NAME**

Specify ‘NAME’ as the character generator ROM file (**ChargenName**).

**-cart2 NAME**

**-cart4 NAME**

**-cart6 NAME**

**-cartA NAME**

**-cartB NAME**

Specify ‘NAME’ as the cartridge image to attach. (**CartridgeFile2000**,...,**CartridgeFileB000**). ■

### 7.4.6 VIC20 settings

#### 7.4.6.1 VIC20 command-line options

**-OEMjoy**

**+OEMjoy** Enable/Disable the OEM userport joystick adapter

## 7.5 PLUS4-specific commands and settings

### 7.5.1 TED settings

### 7.5.1.1 TED command-line options

`-TEDvcache`  
`+TEDvcache`  
Enable/Disable the video cache

`-TEDddsize`  
`+TEDddsize`  
Enable/Disable double size

`-TEDddscan`  
`+TEDddscan`  
Enable/Disable double scan

`-TEDscale2x`  
`+TEDscale2x`  
Enable/Disable Scale2x filter

`-TEDhwscale`  
`+TEDhwscale`  
Enable/Disable hardware scaling

`-TEDintpal`  
Use an internal calculated palette

`-TEDextpal`  
Use an external palette (file)

`-TEDpalette <name>`  
Specify name of file of external palette

`-TEDfulldevice <device>`  
Select fullscreen device

`-TEDXRANDRfullmode <mode>`  
Select fullscreen mode

`-TEDVidmodefullmode <mode>`  
Select fullscreen mode

`-saturation <0-2000>`  
Set saturation of internal calculated palette [1000]

`-contrast <0-2000>`  
Set contrast of internal calculated palette [1000]

`-brightness <0-2000>`  
Set brightness of internal calculated palette [1000]

`-gamma <0-4000>`  
Set gamma of internal calculated palette [2200]

`-tint <0-2000>`  
Set tint of internal calculated palette [1000]

`-oddlinesphase <0-2000>`  
Set phase for color carrier in odd lines [1250]

`-oddlinesoffset <0-2000>`  
     Set phase offset for color carrier in odd lines [750]

`-crtblur <0-1000>`  
     Amount of horizontal blur for the CRT emulation. [500]

`-crtscanlineshade <0-1000>`  
     Amount of scan line shading for the CRT emulation [667]

## 7.5.2 PLUS4 I/O extension settings

### 7.5.2.1 PLUS4 I/O extension command-line options

`-digiblaster`  
`+digiblaster`  
     Enable/Disable the digiblaster add-on

`-sidcart`  
`+sidcart`   Enable/Disable SID Cartridge

`-sidcartjoy`  
`+sidcartjoy`  
     Enable/Disable SID cartridge joystick

`-speech`  
`+speech`    Enable/Disable the v364 speech add-on

`-speechrom <name>`  
     Attach Speech ROM image

## 7.5.3 PLUS4 system ROM settings

### 7.5.3.1 PLUS4 system ROM command-line options

`-functionlo <name>`  
     Specify name of Function low ROM image

`-functionhi <name>`  
     Specify name of Function high ROM image

`-c1lo <name>`  
     Specify name of Cartridge 1 low ROM image

`-c1hi <name>`  
     Specify name of Cartridge 1 high ROM image

`-c2lo <name>`  
     Specify name of Cartridge 2 low ROM image

`-c2hi <name>`  
     Specify name of Cartridge 2 high ROM image

## 7.5.4 PLUS4 settings



### 7.5.4.1 PLUS4 command-line options

**-ramsize** <ramsize>  
Specify size of RAM installed in kb (16/32/64)

**-h256k** Enable the HANNES 256K RAM expansion

**-h1024k** Enable the HANNES 1024K RAM expansion

**-h4096k** Enable the HANNES 4096K RAM expansion

**-cs256k** Enable the CSORY 256K RAM expansion

## 7.6 PET-specific commands and settings

This section lists the settings and commands that are PET-specific and thus are not present in the other emulators.

### 7.6.1 Changing PET model settings

With `xpet`, it is possible to change at runtime the characteristics of the emulated PET so that it matches (or not) the ones of a certain PET model, and it is also possible to select from a common set of PET models so that all the features are selected accordingly.

The former is done by changing the following resources (via resource file, command line options or right-menu items):

**RamSize** Size of memory in kByte. 96k denotes a 8096, 128k a 8296.

**IOSize** Size of I/O area in Byte. Either 2048 or 256 for 8296.

**VideoSize**  
The number of columns on the screen (40 or 80). A 0 auto-detects this from the ROM.

**Ram9** The 8296 can map RAM into the address range \$9\*\*\*

**RamA** The 8296 can map RAM into the address range \$A\*\*\*

**SuperPET** This resource enables the SuperPET (MicroMainFrame 9000) I/O and disables the 8x96 mappings.

**Basic1** If (by checksum) a version 1 kernal is detected, then the kernal ROM is patched to make the IEEE488 interface work.

**Basic1Chars**  
Exchanges some character in the character ROM that have changed between the first PET 2001 and all newer versions.

**EoiBlank** This resource enables the "blank screen on EOI" feature of the oldest PET 2001.

**DiagPin** Set the diagnositic pin on the PET userport (see below).

**ChargenName**  
Specify 'NAME' as the character generator ROM file

**KernalName**

Specify ‘NAME’ as the kernal ROM file. This file contains the complete BASIC, EDITOR and KERNAL ROMs and is either 16k (BASIC 1 and 2) or 20k (BASIC 4) in size.

**EditorName**

Specify ‘NAME’ as the editor ROM file. This file contains an overlay for the editor ROM at \$E000-\$E7FF if necessary.

**RomModule9Name**

Specify ‘NAME’ as the \$9\*\*\* Expansion ROM file. This file contains an expansion ROM image of 4k.

**RomModuleAName**

Specify ‘NAME’ as the \$A\*\*\* Expansion ROM file. This file contains an expansion ROM image of 4k.

**RomModuleBName**

Specify ‘NAME’ as the \$B\*\*\* Expansion ROM file. This file contains an expansion ROM image of 4k. This file overlays the lowest 4k of a BASIC 4 ROM.

Choosing a common PET model is done from the right-button menu instead, by choosing an item from the “Model defaults” submenu. Available models are:

- PET 2001-8N
- PET 3008
- PET 3016
- PET 3032
- PET 3032B
- PET 4016
- PET 4032
- PET 4032B
- PET 8032
- PET 8096
- PET 8296
- SuperPET

Notice that this will **reset the emulated machine**.

It is also possible to select the PET model at startup, with the `-model` command-line option: for example, ‘`xpet -model 3032`’ will emulate a PET 3032 while ‘`xpet -model 8296`’ will emulate a PET 8296.

## 7.6.2 CRTC Settings

### 7.6.2.1 CRTC resources

**Crtc** Enables CRTC 6545 emulation (all models from 40xx and above)

**CrtcVideoCache**

Boolean specifying whether the video cache is turned on.

**CrtcDoubleSize**

Boolean specifying whether double-size mode is turned on.

**CrtcDoubleScan**

Boolean specifying whether double-scan mode is turned on.

**CrtcPaletteFile**

String specifying the name of the palette file being used. The ‘.vpl’ extension is optional.

**7.6.2.2 CRTC command-line options****-Crtcvcache****+Crtcvcache**

Enable/Disable the video cache

**-Crtcdsize****+Crtcdsize**

Enable/Disable double size

**-Crtcdscan****+Crtcdscan**

Enable/Disable double scan

**-Crtcyscale2x****+Crtcyscale2x**

Enable/Disable Scale2x filter

**-Crtchwscale****+Crtchwscale**

Enable/Disable hardware scaling

**-Crtcintpal**

Use an internal calculated palette

**-Crtcextpal**

Use an external palette (file)

**-Crtcpalette NAME**

Specify NAME as the palette file (CrtcPaletteFile).

**-Crtcfulldevice <device>**

Select fullscreen device

**-CrtcXRANDRfullmode <mode>**

Select fullscreen mode

**-CrtcVidmodefullmode <mode>**

Select fullscreen mode

**-saturation <0-2000>**

Set saturation of internal calculated palette [1000]

**-contrast <0-2000>**

Set contrast of internal calculated palette [1000]

**-brightness <0-2000>**  
Set brightness of internal calculated palette [1000]

**-gamma <0-4000>**  
Set gamma of internal calculated palette [2200]

**-tint <0-2000>**  
Set tint of internal calculated palette [1000]

**-oddlinesphase <0-2000>**  
Set phase for color carrier in odd lines [1250]

**-oddlinesoffset <0-2000>**  
Set phase offset for color carrier in odd lines [750]

**-crtblur <0-1000>**  
Amount of horizontal blur for the CRT emulation. [500]

**-crtscanlineshade <0-1000>**  
Amount of scan line shading for the CRT emulation [667]

### 7.6.3 The PET diagnostic pin

It is possible to enable or disable emulation of the PET diagnostic pin via the `DiagPin` resource, or the “PET userport diagnostic pin” item in the right-button menu.

When the diagnostic pin is set, the Kernal does not try to initialize the BASIC, but directly jumps into the builtin machine monitor.

### 7.6.4 PET command line options

These are the commandline options specific for the CBM-II models.

**-model MODEL**  
Specify the PET model you want to emulate.

**-kernal NAME**  
Specify ‘NAME’ as the Kernal/BASIC ROM file (`KernalName`).

**-editor NAME**  
Specify ‘NAME’ as the editor ROM file (`EditorName`).

**-chargen NAME**  
Specify ‘NAME’ as the character generator ROM file (`ChargenName`).

**-rom9 NAME, -romA NAME, -romB NAME**  
Specify ‘NAME’ as the ROM image file for the respective cartridge areas (`RomModule9Name`, `RomModuleAName`, `RomModuleBName`).

**-petram9, +petram9**  
Switch on RAM mapping on addresses \$9000-\$9fff (`Ram9`).

**-petramA, +petramA**  
Switch on RAM mapping on addresses \$a000-\$afff (`RamA`).

**-superpet, +superpet**  
Enable/Disable SuperPET I/O emulation (`SuperPET`).

**-basic1, +basic1**  
 Enable/Disable patching the IEEE488 section of the PET2001 ROM when detected (**Basic1**).

**-basic1char, +basic1char**  
 Enable/Disable PET 2001 character generator (**Basic1Chars**).

**-eoiblack, +eoiblack**  
 Enable/Disable EOI blanking the screen (**EoiBlank**).

**-diagpin**  
**+diagpin** Enable (**DiagPin=1**) or disable (**DiagPin=0**) the diagnostic pin at the PET userport.

**-petreu**  
**+petreu** Enable or disable the PET Memory Expansion Unit.

**-petreuimage <name>**  
 Specify name of PET Ram and Expansion Unit image

**-petreuramsize <size in KB>**  
 Size of the PET Ram and Expansion Unit

**-userportdac, +userportdac**  
 Enable or disable the userport DAC.

**-petdww**  
**+petdww** Enable/Disable the PET DWW hi-res board

**-petdwwimage <name>**  
 Specify name of PET DWW image

**-sidcart**  
**+sidcart** Enable/Disable SID Cartridge

### 7.6.5 Changing screen colors

It is also possible to choose what color set is used for the emulation window. This is done by specifying a palette file name (see [Section 4.3 \[Palette files\], page 20](#)) in the **PaletteName** resource. The menu provides the following values:

- **green.vpl** (default, “green”), the good old green-on-black feeling;
- **amber.vpl** (“amber”), an amber phosphor lookalike;
- **white.vpl** (“white”), simple white-on-black palette.

## 7.7 CBM-II-specific commands and settings

This section lists the settings and commands that are CBM-II-specific and thus are not present in the other emulators.

### 7.7.1 Changing CBM-II model

With **xcbm2**, it is possible to change at runtime the characteristics of the emulated CBM so that it matches (or not) the ones of a certain CBM model, and it is also possible to select from a common set of CBM models so that all the features are selected accordingly.

The former is done by changing the following resources (via resource file, command line options or right-menu items):

**UseVicII** Whether to use VIC-II for video output (value 1) or the CRTC for the other machines (value 0)

**RamSize** Size of memory in kByte. Possible values are 128, 256, 512 and 1024

**Ram08, Ram1, Ram2, Ram4, Ram6, RamC**

Expanded CBM-II models could map RAM to the expansion ROM areas at \$0800-\$0fff, \$1000-\$1fff, \$2000-\$3FFF, \$4000-\$5FFF, \$6000-\$7FFF and \$c000-\$cfff respectively.

**Cart2Name, Cart4Name, Cart6Name**

Specify 'NAME' as the \$2000-\$3FFF, \$4000-\$5FFF or \$6000-\$6FFF Expansion ROM file. This file contains an 8k ROM dump.

**ModelLine**

The CBM-II business models have two hardcoded lines at one of the I/O ports. From those lines the kernal determines how it should init the CRTC video chip for either 50Hz (Europe) or 60Hz (North America), and either for 8 (C6x0) or 14 (C7x0) scanlines per character. 0 = CBM 7x0 (50Hz), 1 = 60Hz C6x0, 2 = 50Hz C6x0).

Choosing a common CBM-II model is done from the right-button menu instead, by choosing an item from the “Model defaults” submenu. Available models are:

- C510 (128k RAM)
- C610 (128k RAM)
- C620 (256k RAM)
- C620+ (1024k RAM, expanded)
- C710 (128k RAM)
- C720 (256k RAM)
- C720+ (1024k RAM, expanded)

Notice that this will **reset the emulated machine**.

**Warning:** At this time switching between 510 and other machines during runtime is not supported and will not work.

It is also possible to select the CBM model at startup, with the `-model` command-line option: for example, `'xcbm2 -model 610'` will emulate a CBM 610 while `'xcbm2 -model 620'` will emulate a CBM 620. Notably this is the only way to start a C510 emulation, with `-model 510`.

## 7.7.2 CBM-II command line options

These are the commandline options specific for the CBM-II models.

`-ramsize <ramsize>`

Specify size of RAM (64/128/256/512/1024 kByte)

`-usevicii`

`+usevicii`

Specify whether to use (`-usevicii`) or not to use (`+usevicii`) the VIC-II emulation.

- kernal NAME**  
Specify 'NAME' as the Kernal ROM file (**KernalName**).
- basic NAME**  
Specify 'NAME' as the Basic ROM file (**BasicName**).
- chargen NAME**  
Specify 'NAME' as the character generator ROM file (**ChargenName**).
- cart1 <name>**  
Specify 'NAME' as the ROM image file for the cartridge area \$1000-\$1FFF (**Cart1Name**).
- cart2 <name>**  
Specify 'NAME' as the ROM image file for the cartridge area \$2000-\$3fff (**Cart2Name**).
- cart4 <name>**  
Specify 'NAME' as the ROM image file for the cartridge area \$4000-\$5fff (**Cart4Name**).
- cart6 <name>**  
Specify 'NAME' as the ROM image file for the cartridge area \$6000-\$7fff (**Cart6Name**).
- ram08**  
**+ram08** Enable/Disable RAM mapping in bank 15 on addresses \$0800-\$0FFF resp (**Ram08**).
- ram1**  
**+ram1** Enable/Disable RAM mapping in bank 15 on addresses \$1000-\$1FFF resp (**Ram1**).
- ram2**  
**+ram2** Enable/Disable RAM mapping in bank 15 on addresses \$2000-\$3FFF resp (**Ram2**).
- ram4**  
**+ram4** Enable/Disable RAM mapping in bank 15 on addresses \$4000-\$5FFF resp (**Ram4**).
- ram6**  
**+ram6** Enable/Disable RAM mapping in bank 15 on addresses \$6000-\$7FFF resp (**Ram6**).
- ramC**  
**+ramC** Enable/Disable RAM mapping in bank 15 on addresses \$C000-\$CFFF resp (**RamC**).
- modelline**  
Define the hardcoded model switch in the CBM-II models.

### 7.7.3 Changing screen colors

It is also possible to choose what color set is used for the emulation window. This is done by specifying a palette file name (see [Section 4.3 \[Palette files\], page 20](#)) in the `PaletteName` resource. The menu provides the following values:

- `green.vpl` (default, “green”), the good old green-on-black feeling;
- `amber.vpl` (“amber”), an amber phosphor lookalike;
- `white.vpl` (“white”), simple white-on-black palette.

## 7.8 VSID-specific commands and settings

### 7.8.1 VSID settings

#### 7.8.1.1 VSID command-line options

```
-vsid      SID player mode (x64 only).
-keepenv   Override PSID settings for Video standard and SID model
-tune <number>
           Specify PSID tune <number>
```

## 8 Snapshots

Every VICE emulator has a built-in snapshot feature, that saves the complete emulator state into one file for later use. You can therefore save the emulator state - including the state of the game you are playing for example - in a single file.

### 8.1 Snapshot usage

A snapshot is one file containing the complete emulator state. A snapshot file can be generated by selecting the “Save snapshot” command at any time. This will pop up a requester from which you can specify whether the snapshot should also contain the disk and ROM status.

A snapshot file can be used to restore the emulator state by selecting the `load snapshot` menu entry at any time. Unfortunately attached ROM images/cartridges are only supported in the VIC20, the PET and the CBM-II emulators at this time.

The memory configuration of the emulator is saved in the snapshot file as well. This configuration is restored when the snapshot is loaded.

A quick snapshot can now be made by pressing the M-F11 key and reloaded by pressing the M-F10 key.

### 8.2 Snapshot format

A snapshot file consists of several modules of mostly different types. Each module has a name and saves the state of an entity like a CIA, the CPU, or the memory.

#### 8.2.1 Emulator modules

This section lists the modules that are contained in each of the emulators snapshot files.



### 8.2.1.1 x64 modules

The modules in the x64 emulator are:

Name	Type	Description
MAINCPU	6502	The Main CPU - although it is a 6510, only the 6502 core is saved here
C64MEM	Memory	Holds the RAM contents of the C64. Also the CPU I/O register contents are saved here.
C64ROM	ROM images	Dump of the system ROMs
VIC-II	656*	The VIC-II of the C64/128
CIA1	6526	The CIA for the interrupts and the keyboard
CIA2	6526	The CIA for the userport, IEC-bus and RS232.
SID	6581	The SID sound chip of the C64/C128
REU*		The RAM Extension Unit state (optional)
ACIA1	6551	An ACIA (RS232 interface) at \$DE00 (optional)
TPI	6525	A TPI at \$DF00 for a parallel IEEE488 interface (optional)
*	Drive modules	The emulated drive(s) have their own modules see <a href="#">Section 8.2.1.6 [Drive modules]</a> , <a href="#">page 89</a>

Some of the modules are optional and are only saved if the specific feature is enabled at save-time. If the module is found when restoring the state the optional features are enabled, and disabled otherwise.

### 8.2.1.2 x128 modules

The modules in the x128 emulator are:

Name	Type	Description
MAINCPU	6502	The Main CPU - although it is a 6510, only the 6502 core is saved here
C128MEM	Memory	Holds the RAM contents of the C64. Also the CPU I/O register contents are saved here.
C128ROM	ROM images	Dump of the system ROMs
VIC-II	656*	The VIC-II of the C64/128
CIA1	6526	The CIA for the interrupts and the keyboard
CIA2	6526	The CIA for the userport, IEC-bus and RS232.
SID	6581	The SID sound chip of the C64/C128
ACIA1	6551	An ACIA at \$DE00 (optional)
TPI	6525	A TPI at \$DF00 for a parallel IEEE488 interface (optional)

\* Drive modules      The emulated drive(s) have their own modules see [Section 8.2.1.6 \[Drive modules\]](#), page 89

Some of the modules are optional and are only saved if the specific feature is enabled at save-time. If the module is found when restoring the state the optional features are enabled, and disabled otherwise.

Not yet supported are the 80 column video chip, cartridges and RAM expansion unit.

### 8.2.1.3 xvic modules

The modules in the xvic emulator are:

Name	Type	Description
MAINCPU	6502	The Main CPU
VIC20MEM	Memory	Holds the RAM contents of the VIC20.
VIC20ROM	ROM images	Holds the ROM images of the VIC20, including possibly attached cartridges
VIC-I	656*	The VIC-I of the VIC20
VIA1	6522	The VIA for the interrupts and the keyboard
VIA2	6522	The VIA for the userport, IEC-bus and RS232.
* Drive modules		The emulated drive(s) have their own modules see <a href="#">Section 8.2.1.6 [Drive modules]</a> , page 89

### 8.2.1.4 xpet modules

The modules in the xpet emulator are:

Name	Type	Description
MAINCPU	6502	The Main CPU
PETMEM	Memory	Holds the RAM contents of the PET.
PETROM	ROM images	Holds the ROM images of the PET, including possibly attached cartridges
CRTC	6545	The CRTC of the PET. This is also included if it is a dump of a PET without CRTC, because the video state is saved here anyway.
PIA1	6520	The PIA for the interrupts, tape and the keyboard
PIA2	6520	The PIA for the IEEE488-bus
VIA	6522	The VIA for IEEE488, userport, sound
ACIA1	6551	The ACIA for the SuperPET. This module is optional.
* Drive modules		The emulated drive(s) have their own modules see <a href="#">Section 8.2.1.6 [Drive modules]</a> , page 89

### 8.2.1.5 xcbm2 modules

The modules in the xcbm2 emulator are:

Name	Type	Description
MAINCPU	6502	The Main CPU - although it is a 6509, only the 6502 core is saved here
CBM2MEM	Memory	Holds the RAM contents of the CBM-II models. Also holds the exec-bank and indirection bank registers
C500DATA		Holds additional state information necessary for the C500 (e.g. cycles till the next IRQ)
CBM2ROM	Memory	optional. Holds the ROM images.
CRTC	6545	The video chip for the C6*0 and C7*0 models (only those models).
VIC-II	656?	The video chip for the C5*0 models (only the C5*0 models).
CIA1	6526	The CIA for IEEE 488 and userport.
TPI1	6525	TPI 1 for IEEE488
TPI2	6525	TPI 2 for interrupts and keyboard.
ACIA1	6551	The RS232 interface
SID	6581	The CBM2s SID sound chip
*	Drive modules	The emulated drive(s) have their own modules see <a href="#">Section 8.2.1.6 [Drive modules]</a> , <a href="#">page 89</a>

The snapshot either contains CRTC or VIC-II snapshot modules, but not both. Currently switching between the two video emulations is not possible at runtime, so only snapshots that fit the current UseVicII resource are accepted.

### 8.2.1.6 Drive modules

The modules for the real disk drive emulation are included in the emulator when the emulation is enabled during the writing of the snapshot.

Name	Type	Description
*CPU	6502	The Drive 0 CPU
*	*	*

## 8.2.2 Module formats

This section shows the basic module framework and the contents of the different types of modules.

The single chip modules contain the **chip** state, not the state of the emulator. We tried to make the format as implementation-independent as possible, to allow reuse of snapshots in later versions of this emulator, or even in other emulators.

### 8.2.2.1 Terminology

In this section we use certain abbreviations to define the types of the data saved in the snapshot.

BYTE	8 bit integer.
WORD	16 bit integer. Saved with low-byte first, high-byte last.
DWORD	32 bit integer. Saved with low-word first, then high-word. Each word saved with its low-byte first.
ARRAY	Array of BYTE values. Length depends on the description.

The tables for the single modules state the type, name and description of the data saved in the modules. The data is saved in the order it is in the tables, so no offset is given.

### 8.2.2.2 Module framework

The VICE snapshot file starts with the magic string and includes the fileformat version number.

Type	Name	Description
19	MAGIC	"VICE Snapshot File\032", padded with 0
BYTE		
BYTE	VMAJOR	fileformat major version number
BYTE	VMINOR	fileformat minor version number
16	MACHINENAME	Name of emulated machine, like "PET", "CBM-II", "VIC20", "C64" or "C128".
BYTE		zero-byte-padded.

The file header is followed by a number of different snapshot modules.

Each module has a header with the information given in the table below. The header includes two version numbers, VMAJOR and VMINOR. Modules with the same VMAJOR should be able to be exchanged. I.e. higher VMINOR numbers only append to the data for lower VMINOR. This additional data is ignored by older restore routines. The other way around newer restore routines must accept the fewer info from lower VMINOR dumps. Changes in VMAJOR might introduce any incompatibility you like, but that's what VMAJOR is for after all :-)

Type	Name	Description
16	MODULENAME	The name of the module in ASCII, padded with 0 to 16 byte.
BYTE		
BYTE	VMAJOR	major version number
BYTE	VMINOR	minor version number
DWORD	SIZE	size of the module, including this header

### 8.2.2.3 CPU module

This module saves the core 6502 state. You will find a clock value there. All other modules save their own clock values relative to this value. However, the drive modules save their clocks relative to their appropriate CPUs of course.

**Warning:** This module is still under construction and saves some information that is not sure to be VICE-independent. If in doubt, read the source.

Type	Name	Description
DWORD	CLK	the current CPU clock value. All other clock values are relative to this.

BYTE	AC	Accumulator
BYTE	XR	X index register
BYTE	YR	Y index register
BYTE	SP	Stack Pointer
WORD	PC	Programm Counter
BYTE	ST	Status Registers
DWORD	LASTOPCODE	?
DWORD	IRQCLK	absolute CLK when the IRQ line came active
DOWRD	NMICLK	absolute CLK when the NMI line came active
DWORD	?	?
DWORD	?	?

#### 8.2.2.4 CIA module

The CIA 6526 is an I/O port chip with 2 8-bit I/O ports, a shift register, two timers, a Time of Day clock and interrupts.

Version numbers: Major 1, Minor 1.

Type	Name	Description
BYTE	ORA	Output register A
BYTE	ORB	Output register B
BYTE	DDRA	Data direction register A
BYTE	DDRB	Data direction register B
WORD	TAC	Timer A counter value
WORD	TBC	Timer B counter value
BYTE	TOD_TEN	Time of Day - current tenth of second
BYTE	TOD_SEC	Time of Day - current seconds
BYTE	TOD_MIN	Time of Day - current minutes
BYTE	TOD_HR	Time of Day - current hours
BYTE	SDR	contents of shift register
BYTE	IER	mask of enabled interrupt masks
BYTE	CRA	Control register A
BYTE	CRB	Control register B
WORD	TAL	Timer A latch value
WORD	TBL	Timer B latch value
BYTE	IFR	mask of currently active interrupts
BYTE	PBSTATE	Bit 6/7 reflect the PB6/7 toggle bit state. Bit 2/3 reflect the corresponding port bit state.
BYTE	SRHBITS	number of half-bits to still shift in/out SDR
BYTE	ALARM_TEN	Time of Day - alarm tenth of second
BYTE	ALARM_SEC	Time of Day - alarm seconds
BYTE	ALARM_MIN	Time of Day - alarm minutes
BYTE	ALARM_HR	Time of Day - alarm hours
BYTE	READICR	current clock minus the clock when ICR was read last plus 128.

BYTE	TODLATCHED	Bit 0: 1= latched for reading, Bit 1: 2=stopped for writing
BYTE	TODL_TEN	Time of Day - latched tenth of second
BYTE	TODL_SEC	Time of Day - latched seconds
BYTE	TODL_MIN	Time of Day - latched minutes
BYTE	TODL_HR	Time of Day - latched hours
DWORD	TOD_TICKS	clk ticks till next tenth of second
—	—	The next items have been added in V1.1
WORD	TASTATE	The state bits of the CIA timer A, according to ciatimer.h
WORD	TBSTATE	The state bits of the CIA timer B, according to ciatimer.h

The last two items have been added in CIA snapshot version 1.1 due to the improved CIA emulation in the newer VICE versions. Some state bits correspond to the CIA state as described in the "A Software Model of the CIA 6526" document by Wolfgang Lorenz, some are delayed versions. For more read the source file `ciatimer.h`.

### 8.2.2.5 VIA module

The VIA 6522 is the predecessor of the CIA and also an I/O port chip with 2 8-bit I/O ports, a shift register, two timers and interrupts.

Version numbers: Major 1, Minor 0.

Type	Name	Description
BYTE	ORA	Output register A
BYTE	DDRA	Data direction register A
BYTE	ORB	Output register B
BYTE	DDRB	Data direction register B
WORD	T1L	Timer 1 Latch value
WORD	T1C	Timer 1 counter value
BYTE	T2L	Timer 2 latch (8 bit as only lower byte is used)
WORD	T2C	Timer 2 counter value
BYTE	RUNFL	bit 7: timer 1 will generate IRQ on underflow; bit 6: timer 2 will generate IRQ on underflow
BYTE	SR	Shift register value
BYTE	ACR	Auxiliary control register
BYTE	PCR	Peripheral control register
BYTE	IFR	active interrupts
BYTE	IER	interrupt mask
BYTE	PB7	bit 7 = pb7 state
BYTE	SRHBITS	number of half-bits to shift out on SR
BYTE	CABSTATE	bit 7: state of CA2 pin, bit 6: state of CB2 pin
BYTE	ILA	Port A Input Latch (see ACR bit 0)
BYTE	ILB	Port B Input Latch (see ACR bit 1)

### 8.2.2.6 PIA module

The PIA 6520 is a chip with two I/O ports (Parallel Interface Adapter) and four additional handshake lines. The chip is pretty the same for Port A and B, only that Port A implements handshake on read operation and port B on write operation.

Version numbers: Major 1, Minor 0.

Type	Name	Description
UBYTE	ORA	Output register A
UBYTE	DDRA	Data Direction Register A
UBYTE	CTRLA	Control Register A
UBYTE	ORB	Output register B
UBYTE	DDRB	Data Direction Register B
UBYTE	CTRLB	Control Register B
UBYTE	CABSTATE	Bit 7 = state of CA2, Bit 6 = state of CB2

### 8.2.2.7 TPI module

The TPI 6525 is a chip with three I/O ports (Tri-Port-Interface). One of the ports can double as an interrupt prioritizer. Therefore we also have to save the states of the interrupt stack etc.

Version numbers: Major 1, Minor 0.

Type	Name	Description
BYTE	PRA	Port A output register
BYTE	PRB	Port B output register
BYTE	PRC	Port C output register (doubles as IRQ latch register)
BYTE	DDRA	Port A data direction register
BYTE	DDRB	Port B data direction register
BYTE	DDRC	Port C data direction register (doubles as IRQ mask register)
BYTE	CR	Control Register
BYTE	AIR	Active interrupt register
BYTE	STACK	Interrupt stack - the interrupt bits that are not (yet) served.
BYTE	CABSTATE	State of CA/CB pins. Bit 7 = state of CA, Bit 6 = state of CB

### 8.2.2.8 RIOT module

The RIOT 6532 is a chip with two I/O ports, some RAM and a Timer. The chip contains 128 byte RAM, but the RAM is not saved in the RIOT snapshot, but in the memory section.

**Warning:** This module is still under construction

Version numbers: Major 0, Minor 0.

Type	Name	Description
BYTE	ORA	Port A output register
BYTE	DDRA	Port A data direction register
BYTE	ORB	Port B output register

BYTE	DDRB	Port B data direction register
BYTE	EDGECTRL	Bit 0/1: A0/A1 address bits written to edgecontrol registers
BYTE	IRQFL	Bit 6/7: A6/A7 IRQ flag register. Bit 0: state of the IRQ line (0=inactive, 1=active)
BYTE	N	timer value
WORD	DIVIDER	Pre-scale divider value (1, 8, 64, or 1024)
WORD	REST	cycles since the last counter change
BYTE	IRQEN	Bit 0: 0= timer IRQ disabled, 1= timer IRQ enabled

### 8.2.2.9 SID module

**Warning:** This module is still under construction.

### 8.2.2.10 ACIA module

The ACIA 6551 is an RS232 interface chip. VICE emulates RS232 connections via `/dev/ttyS*` (Unix) or `COM:` (DOS/WIN - not yet?). When saving a snapshot, those connections are of course lost. The state of the ACIA however is restored if possible. I.e. if a connection is already open when restoring the snapshot, this connection is used instead. If no connection is open, a carrier/DTR drop is emulated.

Version numbers: Major 1, Minor 0.

Type	Name	Description
BYTE	TDR	Transmit Data Register
BYTE	RDR	Receiver Data Register
BYTE	SR	Status Register
BYTE	CMD	Command Register
BYTE	CTRL	Ctrl Register
BYTE	INTX	0 = no data to tx; 1 = Data is being transmitted; 2 = Data is being transmitted while data in TDR waiting to be put to internal transmit register
DWORD	TICKS	Clock ticks till the next TDR empty interrupt

### 8.2.2.11 VIC-I module

**Warning:** This module is still under construction.

### 8.2.2.12 VIC-II module

**Warning:** This module is still under construction.

### 8.2.2.13 CRTC module

**Warning:** After VICE version 1.0 the CRTC emulation has improved considerably. Especially it is now cycle exact. Therefore a lot more variables must be saved. The snapshot module version jumped from 0.0 to 1.0. Newer versions of VICE can read the old snapshots, but older versions (1.0 and below) cannot read the new snapshots.



**Warning:** This module is still under construction. Especially the RASTERY and RASTERLINE values might be bogus.

Version numbers: Major 1, Minor 1.

Type	Name	Description
		Hardware options
WORD	VADDR_MASK	Mask of the address bits valid when accessing the video memory
WORD	VADDR_CHARSWITCH	If one bit in the video address is used to switch the character generator, it is masked here.
WORD	VADDR_CHAROFFSET	The offset in characters in the character generator that CHARSWITCH switches.
WORD	VADDR_REVSWITCH	If one bit in the video address inverts the screen, it is masked here.
WORD	CHARGEN_MASK	size of character generator in byte - 1
WORD	CHARGEN_OFFSET	offset given by external circuitry
BYTE	HW_CURSOR	external hardware cursor circuitry enabled
BYTE	HW_COLS	number of displayed columns during one character clock cycle
BYTE	HW_BLANK	set if the hardware blank feature is available
20	REGISTERS	CRTC register
BYTE		register DUMP of the CRTC registers 0-19.
		CRTC internal registers
BYTE	REGNO	The current index in the CRTC register file
BYTE	CHAR	The current cycle within the current rasterline
BYTE	CHARLINE	The current character line
BYTE	YCOUNTER	The current rasterline in the character
BYTE	CRSRCNT	Framecounter for the blinking cursor
BYTE	CRSRSTATE	if set the hardware cursor is visible
BYTE	CRSRLINES	set if ycounter is within the active cursor rasterlines for a char
WORD	CHARGEN_REL	relative base of currently used character generator in ROM (in byte)
WORD	SCREEN_REL	screen address to load the counter at the beginning of the next rasterline
WORD	VSNC	number of rasterlines left within vsync; 0 = not in vsync
BYTE	VENABLE	vertical enable flipflop; 1= display, 0= blank.
		(VICE-dependent?) variables
WORD	SCREEN_WIDTH	width of the current display window
WORD	SCREEN_HEIGHT	height of the current display window

WORD	SCREEN_XOFFSET	x position where the first character in a line starts in the window...
WORD	HJITTER	...but only after adding this jitter
WORD	SCREEN_YOFFSET	x position where the first character in a line starts in the window...
WORD	FRAMELINES	expected number of rasterlines for the current frame
WORD	CURRENT_LINE	current rasterline as seen from the CRTC This value has been added in module version V1.1
BYTE	FLAG	Bit 0: If 1 then bit in VADDR_REVSWITCH must be set for reverse; if 0 then bit must be cleared for reverse.

Here is the reference for the previous CRTC snapshot module. It is outdated and will not be read by this and later versions of VICE.

Version numbers: Major 0, Minor 0.

Type	Name	Description
BYTE	RASTERY	The number of clock cycles from rasterlines start
WORD	RASTERLINE	The current rasterline
WORD	ADDRMASK	The address mask valid for the CRTC. All memory accesses are masked with this value
BYTE	HWFLAG	Bit 0: 1= hardware cursor available. Bit 1: 1= number of columns is doubled by external hardware
20 BYTE	REGISTERS	register DUMP of the CRTC registers 0-19.
BYTE	CRSRSTATE	Hardware cursor: Bits 0-3: frame counter till next crsr line toggle. Bit 7: 1= cursor line active

#### 8.2.2.14 C64 memory module

The C64 memory module actually consists of two modules. The "C64MEM" module is mandatory and contains the RAM dump. The "C64ROM" module is optional and contains a dump of the ROM images.

The size of the C64 memory modules differs with each different memory configuration. The RAM configuration is saved in the snapshot, and restored when the snapshot is loaded. The attached cartridges are **not yet(!)** saved and not yet restored upon load.

Version numbers: Major 0, Minor 0

##### The C64MEM module

Type	Name	Description
BYTE	CPUDATA	CPU port data byte
BYTE	CPUDIR	CPU port direction byte
BYTE	EXROM	state of the EXROM line (?)

BYTE	GAME	state of the GAME line (?)
ARRAY	RAM	64k RAM dump

#### **The C64ROM module**

Type	Name	Description
ARRAY	KERNAL	8k dump of the kernal ROM
ARRAY	BASIC	8k dump of the basic ROM
ARRAY	CHARGEN	4k dump of the chargen ROM

### **8.2.2.15 C128 memory module**

The C128 memory module actually consists of two modules. The "C128MEM" module is mandatory and contains the RAM dump. The "C128ROM" module is optional and contains a dump of the ROM images.

The size of the C128 memory modules differs with each different memory configuration. The RAM configuration is saved in the snapshot, and restored when the snapshot is loaded. The attached cartridges are also restored upon load if they have been saved in the snapshot.

Version numbers: Major 0, Minor 0

#### **The C128MEM module**

Type	Name	Description
12	MMU	dump of the 12 MMU registers
BYTE		
ARRAY	RAM	128k RAM dump banks 0 and 1

#### **The C128ROM module**

Type	Name	Description
ARRAY	KERNAL	8k dump of the kernal ROM
ARRAY	BASIC	32k dump of the basic ROM
ARRAY	EDITOR	4k dump of the editor ROM
ARRAY	4k CHARGEN	dump of the chargen ROM

### **8.2.2.16 VIC20 memory module**

The VIC20 memory module actually consists of two modules. The "VIC20MEM" module is mandatory and contains the RAM dump. The "VIC20ROM" module is optional and contains a dump of the ROM images.

The size of the VIC20 memory modules differs with each different memory configuration. The RAM configuration is saved in the snapshot, and restored when the snapshot is loaded. The attached cartridges are also restored upon load if they have been saved in the snapshot.

#### **The VIC20MEM module**

Version numbers: Major 1, Minor 0

Type	Name	Description
BYTE	CONFIG	Configuration register. Bits 0,1,2,3,5 reflect if the corresponding memory block is RAM (bit=1) or not (bit=0).
ARRAY	RAM0	1k RAM dump \$0000-\$03ff
ARRAY	RAM1	4k RAM dump \$1000-\$1fff
ARRAY	COLORRAM	2k Color RAM, \$9400-\$9bff

ARRAY	BLK0	if CONFIG & 1 then: 3k RAM dump \$0400-\$0fff
ARRAY	BLK1	if CONFIG & 2 then: 8k RAM dump \$2000-\$3fff
ARRAY	BLK2	if CONFIG & 4 then: 8k RAM dump \$4000-\$5fff
ARRAY	BLK3	if CONFIG & 8 then: 8k RAM dump \$6000-\$7fff
ARRAY	BLK5	if CONFIG & 32 then: 8k RAM dump \$a000-\$bfff

### The VIC20ROM module

Version numbers: Major 1, Minor 1

Type	Name	Description
BYTE	CONFIG	Bit 0: 1= ROM block \$2*** enabled. Bit 1: 1= ROM block \$3*** enabled. Bit 2: 1= ROM block \$4*** enabled. Bit 3: 1= ROM block \$5*** enabled. Bit 4: 1= ROM block \$6*** enabled. Bit 5: 1= ROM block \$7*** enabled. Bit 6: 1= ROM block \$A*** enabled. Bit 7: 1= ROM block \$B*** enabled.
ARRAY	KERNAL	8k KERNAL ROM image \$e000-\$ffff
ARRAY	BASIC	16k BASIC ROM image \$c000-\$dfff
ARRAY	CHARGEN	4k CHARGEN ROM image
ARRAY	BLK1A	4k ROM image \$2*** (if CONFIG & 1)
ARRAY	BLK1B	4k ROM image \$3*** (if CONFIG & 2)
ARRAY	BLK3A	4k ROM image \$6*** (if CONFIG & 16)
ARRAY	BLK3B	4k ROM image \$7*** (if CONFIG & 32)
ARRAY	BLK5A	4k ROM image \$A*** (if CONFIG & 64)
ARRAY	BLK5B	4k ROM image \$B*** (if CONFIG & 128)
ARRAY	BLK2A	4k ROM image \$4*** (if CONFIG & 4; added in V1.1)
ARRAY	BLK2B	4k ROM image \$5*** (if CONFIG & 8; added in V1.1)

### 8.2.2.17 PET memory module

The PET memory module actually consists of two modules. The "PETMEM" module is mandatory and contains the RAM dump. The "PETROM" module is optional and contains a dump of the ROM images.

The size of the PET memory modules differs with each different memory configuration. The RAM configuration is saved in the snapshot, and restored when the snapshot is loaded.

### The PETMEM module

Version numbers: Major 1, Minor 2

Type	Name	Description
------	------	-------------

BYTE	CONFIG	Configuration value. Bits 0-3: 0= 40 col PET without CRTC; 1= 40 col PET with CRTC; 2 = 80 col PET (with CRTC); 3= SuperPET; 4= 8096; 5= 8296. Bit 6: 1= RAM at \$9***. Bit 7: 1= RAM at \$A***.
BYTE	KEYBOARD	Keyboard type. 0= UK business; 1= Graphics; 2= German business
BYTE	MEMSIZE	memory size of low 32k in k (possible values 4, 8, 16, 32)
BYTE	CONF8X96	Value of the 8x96 configuration register
BYTE	SUPERPET	SuperPET config. Bit 0: 1= \$9*** RAM enabled. Bit 1: 1= RAM write protected. Bit 2: 1= CTRL register write protected. Bit 3: 0= DIAG pin active. Bits 4-7: RAM block in use.
ARRAY	RAM	4-32k RAM (not 8296, size depends on MEMSIZE)
ARRAY	VRAM	2/4k RAM (not 8296, size depends on CONFIG)
ARRAY	EXTRAM	64k expansion RAM (SuperPET and 8096 only)
ARRAY	RAM	128k RAM (8296 only)
—	—	The following item has been added in V1.1
BYTE	POSITIONAL	bit 0=0 = symbolic keyboard mapping, bit 0=1 = positional mapping.
—	—	The following item has been added in V1.1
BYTE	EOIBLANK	bit 0=0 = EOI does not blank screen, bit 0=1 = EOI blanks screen.

The last item has been added in PETMEM snapshot version 1.1. It is ignored by earlier restore routines (V1.0) and the V1.1 restore routines do not change the current setting when reading a V1.0 snapshot.

In V1.2 the new EOIBLANK variable has been added. This implements the "blank screen on EOI" feature that was previously linked to a wrong resource.

### The PETROM module

Version numbers: Major 1, Minor 0

Type	Name	Description
BYTE	CONFIG	Bit 0: 1= \$9*** ROM included. Bit 1: 1= \$A*** ROM included. Bit 2: 1= \$B*** ROM included. Bit 3: 1= \$e900-\$efff ROM included
ARRAY	KERNAL	4k KERNAL ROM image \$f000-\$ffff
ARRAY	EDITOR	2k EDITOR ROM image \$e000-\$e7ff
ARRAY	CHARGEN	2k CHARGEN ROM image
ARRAY	ROM9	4k \$9*** ROM image (if CONFIG & 1)
ARRAY	ROMA	4k \$A*** ROM image (if CONFIG & 2)

ARRAY	ROMB	4k \$B*** ROM image (if CONFIG & 4)
ARRAY	ROMC	4k \$C*** ROM image
ARRAY	ROMD	4k \$D*** ROM image
ARRAY	ROME9	7 blocks \$e900-\$efff ROM image (if CONFIG & 8)

### 8.2.2.18 CBM-II memory module

The CBM-II memory module actually consists of two modules. The "CBM2MEM" module is mandatory and contains the RAM dump. The "CBM2ROM" module is optional and contains a dump of the ROM images.

The size of the CBM-II memory modules differs with each different memory configuration. The RAM configuration is saved in the snapshot, and restored when the snapshot is loaded.

Version numbers: Major 1, Minor 0

#### The CBM2MEM module

Type	Name	Description
UBYTE	MEMSIZE	Memory size in 128k blocks (1=128k, 2=256k, 4=512k, 8=1024k)
UBYTE	CONFIG	Bit 0 = \$f0800-\$f0fff RAM, Bit 1 = \$f1000-\$f1fff RAM, Bit 2 = \$f2000-\$f3fff RAM, Bit 3 = \$f4000-\$f5fff RAM, Bit 4 = \$f6000-\$f7fff RAM, Bit 5 = \$fc000-\$fcfff RAM, Bit 6 = is a C500
UBYTE	HWCONFIG	Bit 0/1: model line configuration
UBYTE	EXECBANK	CPUs execution bank register
UBYTE	INDBANK	CPUs indirection bank register
ARRAY	SYSRAM	2k system RAM \$f0000-\$f07ff
ARRAY	VIDEO	2k video RAM \$fd000-\$fd7ff
ARRAY	RAM	RAM dump, size according to MEMSIZE
ARRAY	RAM08	if memsize < 1M and CONFIG & 1 : 2k RAM \$f0800-\$f0fff
ARRAY	RAM1	if memsize < 1M and CONFIG & 2 : 4k RAM \$f1000-\$f1fff
ARRAY	RAM2	if memsize < 1M and CONFIG & 4 : 8k RAM \$f2000-\$f3fff
ARRAY	RAM4	if memsize < 1M and CONFIG & 8 : 8k RAM \$f4000-\$f5fff
ARRAY	RAM6	if memsize < 1M and CONFIG & 16 : 8k RAM \$f6000-\$f7fff
ARRAY	RAMC	if memsize < 1M and CONFIG & 32 : 4k RAM \$fc000-\$fcfff

The RAM\* arrays are only saved if the RAM itself is less than 1M. If the memory size is 1M then those areas are taken from the bank 15 area of the normal RAM.

The memory array starts at \$10000 if the memory size is less than 512k, or at \$00000 if 512k or more. In case of a C510, then the memory array also always starts at \$00000.

**The CBM2ROM module**

Type	Name	Description
UBYTE	CONFIG	Bit 1: 1= \$1*** ROM image included. Bit 2: 1= \$2000-\$3fff ROM image included. Bit 3: 1= \$4000-\$5fff ROM image included. Bit 4: 1= \$6000-\$7fff ROM image included. Bit 5: 1= chargen ROM is VIC-II chargen, 0= CRTC chargen.
ARRAY	KERNAL	8 KERNAL ROM image (\$e000-\$efff)
ARRAY	BASIC	BASIC ROM image (\$8000-\$bfff)
ARRAY	CHARGEN	4k CHARGEN ROM image
ARRAY	ROM1	4k cartridge ROM image for \$1*** (if CONFIG & 2)
ARRAY	ROM2	8k cartridge ROM image for \$2000-\$3fff (if CONFIG & 4)
ARRAY	ROM4	8k cartridge ROM image for \$4000-\$5fff (if CONFIG & 8)
ARRAY	ROM6	8k cartridge ROM image for \$6000-\$7fff (if CONFIG & 16)

**8.2.2.19 C500 data module**

The C500 data module contains simple state information not already saved in the other modules.

Version numbers: Major 0, Minor 0

**The C500DATA module**

Type	Name	Description
DWORD	IRQCLK	CPU clock ticks till next 50Hz IRQ

## 9 Media images

### 9.1 Media images command-line options

**-doodleoversize <method>**

Select the way the oversized input should be handled, (0: scale down, 1: crop left top, 2: crop center top, 3: crop right top, 4: crop left center, 5: crop center, 6: crop right center, 7: crop left bottom, 8: crop center bottom, 9: crop right bottom)

**-doodlemc <method>**

Select the way the multicolor to hires should be handled, (0: b&w, 1: 2 colors, 2: 4 colors, 3: gray scale, 4: best cell colors)

**-doodletedlum <method>**

Select the way the TED luminosity should be handled, (0: ignore, 1: dither)

**-doodlecrtctextcolor <color>**

Select the CRTC text color (0: white, 1: amber, 2: green)

`-ffmpegaudiobitrate <value>`  
     Set bitrate for audio stream in media file

`-ffmpegvideobitrate <value>`  
     Set bitrate for video stream in media file

## 10 Event history

### 10.1 Event history command-line options

`-playback`  
     Playback recorded events

## 11 Monitor

Every VICE emulator has a complete built-in monitor, which can be used to examine, disassemble and assemble machine language programs, as well as debug them through break-points. It can be activated by using the “Activate monitor” command (left button menu). Notice that you have to run the emulator from a terminal emulation program (such as `rxvt` or `xterm`) in order to use the monitor.

**Warning:** this version of the monitor is still under construction, and some of the features are not fully working yet.

### 11.1 Terminology

**‘address\_space’**  
     This refers to the range of memory locations and a set of registers. This can be the addresses available to the computer’s processor, the disk drive’s processor or a specific memory configuration of one of the mentioned processors.

**‘bankname’**  
     The CPU can only see 64k of memory at any one time, due to its 16 bit address bus. The C64 and other computers have more than this amount, and this is handled by banking: a memory address can have different contents, depending on the active memory bank. A bankname names a specific bank in the current address\_space.

**‘register’**  
     One of the following: program counter (PC), stack pointer (SP), accumulator (A), X register (X), or Y register (Y).

**‘address’**   A specific memory location in the range \$0000 to \$FFFF.

**‘address\_range’**  
     Two addresses. If the second address is less than the first, the range is assumed to wraparound from \$FFFF to \$0000. Both addresses must be in the same address space.



<code>'address_opt_range'</code>	An address or an address range.
<code>'label'</code>	<code>label</code> is the name of a label. it must start with a dot (".") in order for the monitor to recognize it as a label.
<code>'prompt'</code>	The prompt has the format <code>[x:y]</code> . If <code>x</code> is <code>-</code> , memory reads from the monitor do not have side effects. Otherwise, <code>x</code> is <code>S</code> . The second part of the prompt, <code>y</code> , shows the default address space.
<code>'checkpoint'</code>	The monitor has the ability to setup triggers that perform an action when a specified situation occurs. There are three types of checkpoints; breakpoints, tracepoints and watchpoints.
<code>'breakpoint'</code>	A breakpoint is triggered based on the program counter. When it is triggered, the monitor is entered.
<code>'tracepoint'</code>	Like breakpoints, a tracepoint is triggered based on the program counter. Instead of entering the monitor, the program counter is printed and execution continues.
<code>'watchpoint'</code>	Watchpoints are triggered by a read and/or write to an address. When a watchpoint is triggered, the monitor is entered.
<code>'memmap'</code>	The memmap keeps track of RAM/ROM/IO read/write/execute accesses. The feature must be enabled with <code>"-enable-memmap"</code> configure option, as it might decrease performance notably on slower hardware. The option also enables CPU history.
<code>'&lt;...&gt;'</code>	A data type.
<code>'*'</code>	Zero or more occurrences.
<code>'[...]'</code>	An optional argument.

## 11.2 Machine state commands

### `backtrace`

`bt` Print JSR call chain (most recent call first). Stack offset relative to `SP+1` is printed in parentheses. This is a best guess only.

### `cpuhistory [<count>]`

#### `chis [<count>]`

Show `<count>` last executed commands. (disabled by default; configure with `-enable-memmap` to enable)

### `dump "<filename>"`

Write a snapshot of the machine into the file specified. This snapshot is compatible with a snapshot written out by the UI. Note: No ROM images are included into the dump.

**goto** <address>

**g** <address>

Change the PC to address and continue execution.

**io** [<address>]

Display i/o registers. Invoking without an address shows a dump of the entire io range, if an address is given then details for the chip at the respective (base-)address are displayed (if available).

**next** [<count>]

**n** [<count>]

Advance to the next instruction. Subroutines are treated as a single instruction.

**registers** [<reg\_name> = <number> [, <reg\_name> = <number>]\*]

**r** [<reg\_name> = <number> [, <reg\_name> = <number>]\*]

Assign respective registers. With no parameters, display register values.

**reset** [<type>]

Reset the machine or drive. **type**: 0 = soft, 1 = hard, 8-11 = drive.

**return**

**ret** Continues execution and returns to the monitor just after the next RTS or RTI is executed.

**step** [<count>]

**z** [<count>]

Single step through instructions. An optional count allows stepping more than a single instruction at a time.

**undump** "<filename>"

Read a snapshot of the machine from the file specified.

## 11.3 Memory commands

**bank** [<bankname>]

Without a bankname, display all available banks for the current address\_space. With a bankname given, switch to the specified bank. If a bank is not completely filled (ROM banks for example) normally the **ram** bank is used where the bank has holes. The **cpu** bank uses the bank currently used by the CPU.

**compare** <address\_range> <address>

**c** <address\_range> <address>

Compare memory from the source specified by the address range to the destination specified by the address. The regions may overlap. Any values that miscompare are displayed using the default displaytype.

**device** [c:|8:|9:]

Set the default address space to either the computer 'c:' or the specified drive '8:' or '9:'

**fill** <address\_range> <data\_list>

**f** <address\_range> <data\_list>

Fill memory in the specified address range with the data in <data\_list>. If the size of the address range is greater than the size of the data\_list, the data\_list is repeated.

**hunt** <address\_range> <data\_list>

**h** <address\_range> <data\_list>

Hunt memory in the specified address range for the data in <data\_list>. If the data is found, the starting address of the match is displayed. The entire range is searched for all possible matches. The data list may have 'xx' as a wildcard.

**i** <address\_opt\_range>

Display memory contents as PETSCII text.

**ii** <address\_opt\_range>

Display memory contents as screen code text

**mem** [<data\_type>] [<address\_opt\_range>]

**m** [<data\_type>] [<address\_opt\_range>]

Display the contents of memory. If no datatype is given, the default is used. If only one address is specified, the length of data displayed is based on the datatype. If no addresses are given, the 'dot' address is used.

**memmapshow** [<mask>] [<address\_opt\_range>]

**mmsh** [<mask>] [<address\_opt\_range>]

Show the memmap. The mask can be specified to show only those locations with accesses of certain type(s). The mask is a number with the bits "ioRWXrwx", where RWX are for ROM and rwx for RAM. Optionally, an address range can be specified. (disabled by default; configure with `-enable-memmap` to enable)

**memmapzap**

**mmzap** Clear the memmap. (disabled by default; configure with `-enable-memmap` to enable)

**memmapsave** "<filename>" <format>

**mmsave** "<filename>" <format>

Save the memmap as a picture. **format**: 0 = BMP, 1 = PCX, 2 = PNG, 3 = GIF, 4 = IFF. (disabled by default; configure with `-enable-memmap` to enable)

**memchar** [<data\_type>] [<address\_opt\_range>]

**mc** [<data\_type>] [<address\_opt\_range>]

Display the contents of memory as character data. If only one address is specified, only one character is displayed. If no addresses are given, the "dot" address is used.

**memsprite** [<data\_type>] [<address\_opt\_range>]

**ms** [<data\_type>] [<address\_opt\_range>]

Display the contents of memory as sprite data. If only one address is specified, only one sprite is displayed. If no addresses are given, the "dot" address is used.

**move** <address\_range> <address>

**t** <address\_range> <address>

Move memory from the source specified by the address range to the destination specified by the address. The regions may overlap.

**screen**

**sc** Displays the contents of the screen.

**sidefx** [on|off|toggle]

**sfx** [on|off|toggle]

Control how monitor generated reads affect memory locations that have read side-effects, like CIA interrupt registers for example. If the argument is 'on' then reads may cause side-effects. If the argument is 'off' then reads don't cause side-effects. If the argument is 'toggle' then the current mode is switched. No argument displays the current state.

**>** [<address>] <data\_list>

Write the specified data at address.

## 11.4 Assembly commands

**a** <address> [ <instruction> [: <instruction>]\* ]

Assemble instructions to the specified address. If only one instruction is specified, enter assembly mode (enter an empty line to exit assembly mode).

**disass** [<address> [<address>]]

**d** [<address> [<address>]]

Disassemble instructions. If two addresses are specified, they are used as a start and end address. If only one is specified, it is treated as the start address and a default number of instructions are disassembled. If no addresses are specified, a default number of instructions are disassembled from the dot address.

## 11.5 Checkpoint commands

**break** [load|store|exec] [address [address] [if <cond\_expr>]]

This command allows setting a breakpoint or listing the current breakpoints. If no address is given, the currently valid checkpoints are printed. If an address is given, a breakpoint is set for that address and the breakpoint number is printed. The "load|store|exec" parameter can be either "load", "store" or "exec" (or any combination of these) to determine on which operation the monitor breaks. If not specified, the monitor breaks on "exec". A conditional expression can also be specified for the breakpoint. For more information on conditions, see the CONDITION command.

**enable** <checknum>

**disable** <checknum>

Each checkpoint can be enabled or disabled. This command allows changing between these states.

**command** <checknum> "<command>"

When checkpoint **checknum** is hit, the specified command is executed by the monitor. Note that the **x** command is not yet supported as a command argument.

**condition** <checknum> if <cond\_expr>

**cond** <checknum> if <cond\_expr>

Each time the specified checkpoint is examined, the condition is evaluated. If it evaluates to true, the checkpoint is activated. Otherwise, it is ignored. If registers are specified in the expression, the values used are those at the time the checkpoint is examined, not when the condition is set.

Currently, the **cond\_expr** is very limited. You can use registers (**.A**, **.X**, **.Y**, **.PC**, and **.SP**) and compare against other registers or absolute values. For example, the following are all valid conditions: **.A == 0**, **.X == .Y**, **8:.X == .X**, **.A != 5**, **.A < .X**.

However, you cannot specify memory contents and compare that.

**delete** <checknum>

**del** <checknum>

Delete the specified checkpoint.

**ignore** <checknum> [<count>]

Ignore a checkpoint after a given number of crossings. If no count is given, the default value is 1.

**trace** [load|store|exec] [address [address] [if <cond\_expr>]]

**tr** [load|store|exec] [address [address] [if <cond\_expr>]]

This command is similar to the **break** command except that it operates on tracepoints. A tracepoint differs from a breakpoint by not stopping execution but simply printing the PC, giving the user an execution trace. The second optional address can be used to specify the end of an range of addresses to be traced. If no addresses are given, a list of all the checkpoints is printed. The "load|store|exec" parameter can be either "load", "store" or "exec" (or any combination of these) to determine which operation the monitor traces. If not specified, the monitor traces all operations. A conditional expression can also be specified for the tracepoint. For more information on conditions, see the **CONDITION** command.

**until** [<address>]

**un** [<address>]

If no address is given, the currently valid breakpoints are printed. If an address is given, a temporary breakpoint is set for that address and the breakpoint number is printed. Control is returned to the emulator by this command. The breakpoint is deleted once it is hit.

**watch** [load|store|exec] [address [address] [if <cond\_expr>]]

**w** [load|store|exec] [address [address] [if <cond\_expr>]]

This command is similar to the **break** command except that it operates on watchpoints. A watchpoint differs from a breakpoint by stopping on a read and/or write to an address or range of addresses. If no addresses are given, a

list of all the checkpoints is printed. The "load|store|exec" parameter can be either "load", "store" or "exec" (or any combination of these) to determine on which operation the monitor breaks. If not specified, the monitor breaks on "load" and "store" operations. A conditional expression can also be specified for the watchpoint. For more information on conditions, see the CONDITION command.

## 11.6 General commands

**cd** <directory>

Change the working directory.

**device** [c:d:]

**dev** [c:d:]

Set the default memory device to either the computer (c:) or the disk (d:).

**dir** [<directory>]

**ls** [<directory>]

Display the directory contents.

**pwd** Show current working directory.

**radix** [H|D|O|B]

**rad** [H|D|O|B]

Set the default radix to hex, decimal, octal, or binary. With no argument, the current radix is printed.

## 11.7 Disk commands

**attach** <filename> <device>

Attach file to device. (device 32 = cart)

**block\_read** <track> <sector> [<address>]

**br** <track> <sector> [<address>]

Read the block at the specified track and sector. If an address is specified, the data is loaded into memory. If no address is given, the data is displayed using the default datatype.

**block\_write** <track> <sector> <address>

**bw** <track> <sector> <address>

Write a block of data at **address** to the specified track and sector of disk in drive 8.

**detach** <device>

Detach file from device. (device 32 = cart)

**@<disk command>**

Perform a disk command on the currently attached disk image on drive 8. The specified disk command is sent to the drive's channel #15.

**load** "<filename>" <device> [<address>]

**l** "<filename>" <device> [<address>]

Load the specified file into memory. If no address is given, the file is loaded to the address specified by the first two bytes read from the file. If address is

given, the file is loaded to the specified address and the first two bytes read from the file are skipped. If device is 0, the file is read from the file system.

**list** [<directory>]

List disk contents.

**bload** "<filename>" <device> <address>

**bl** "<filename>" <device> <address>

Load the specified file into memory at the specified address. If device is 0, the file is read from the file system.

**save** "<filename>" <device> <address1> <address2>

**s** "<filename>" <device> <address1> <address2>

Save the memory from address1 to address2 to the specified file. Write two-byte load address. If device is 0, the file is written to the file system.

**bsave** "<filename>" <device> <address1> <address2>

**bs** "<filename>" <device> <address1> <address2>

Save the memory from address1 to address2 to the specified file. If device is 0, the file is written to the file system.

## 11.8 Command file commands

**playback** "<filename>"

**pb** "<filename>"

Monitor commands from the specified file are read and executed. This command stops at the end of file or when a STOP command is read.

**record** "<filename>"

**rec** "<filename>"

After this command, all commands entered are written to the specified file until the STOP command is entered.

**stop** Stop recording commands. See **record**.

## 11.9 Label commands

**add\_label** <address> <label>

**al** <address> <label>

Map a given address to a label. This label can be used when entering assembly code and is shown during disassembly. Additionally, it can be used whenever an address must be specified.

<label> is the name of the label; it must start with a dot (".") in order for the monitor to recognize it as a label.

**delete\_label** [<memspace>] <label>

**dl** [<memspace>] <label>

Remove the specified label from the label tables. If no memory space is checked, all tables are checked.

```
load_labels [<memspace>] "<filename>"
```

```
ll [<memspace>] "<filename>"
```

Load a file containing a mapping of labels to addresses. If no memory space is specified, the default readspace is used.

The file must contain commands the monitor understands, e.g. `add_label`. The compiler `cc65` can create such label files.

Vice can also load label files created by the Acme assembler. Their syntax is e.g. `"labelname = $1234 ; Maybe a comment"`. A dot will be added automatically to label names assigned in this way to fit to the Vice label syntax. Normally the semicolon separates commands but after an assignment of this kind it may be used to start a comment to end of line, so unchanged Acme label files can be fed into Vice.

```
save_labels [<memspace>] "<filename>"
```

```
sl [<memspace>] "<filename>"
```

Save labels to a file. If no memory space is specified, all of the labels are saved.

```
show_labels [<memspace>]
```

```
shl [<memspace>]
```

Display current label mappings. If no memory space is specified, show all labels.

## 11.10 Miscellaneous commands

```
cartfreeze
```

Use cartridge freeze.

```
cpu <type>
```

Specify the type of CPU currently used (6502/z80).

```
exit
```

```
x
```

Leave the monitor and return to execution.

```
export
```

```
exp
```

Print out list of attached expansion port devices.

```
help [<command>]
```

If no argument is given, prints out a list of all available commands. If an argument is given, prints out specific help for that command.

```
keybuf "<string>"
```

Put the specified string into the keyboard buffer. Note that you can specify specific keycodes by using C-style escaped hexcodes (`"\x0a"`).

```
print <expression>
```

```
p <expression>
```

Evaluate the specified expression and output the result.

```
resourceget "<resource>"
```

```
resget "<resource>"
```

Displays the value of the `resource`.



```

resourceset "<resource>" "<value>"
reset "<resource>" "<value>"
    Sets the value of the resource.

screenshot "<filename>" [<format>]
scrsh "<filename>" [<format>]
    Take a screenshot. format: default = BMP, 1 = PCX, 2 = PNG, 3 = GIF, 4
    = IFF.

tapectrl <command>
    Control the datasette. command: 0 = stop, 1 = start, 2 = forward, 3 = rewind,
    4 = record, 5 = reset, 6 = reset counter.

quit
    Exit the emulator immediately.

~ <number>
    Display the specified number in decimal, hex, octal and binary.

```

## 12 c1541

VICE is provided with a complete stand-alone disk image maintenance utility, called **c1541**.

You can either invoke it from the command line or from within one of the VICE emulators, using the “Run c1541” command which will open a new **xterm** window with a running **c1541** in it.

The syntax is:

```
c1541 [IMAGE1 [IMAGE2]] [COMMAND1 COMMAND2 ... COMMANDN]
```

**IMAGE1** and **IMAGE2** are disk image names that can be attached before **c1541** starts. **c1541** can handle up to two disk images at the same time by using two virtual built-in drives, numbered 8 and 9; **IMAGE1** (if present) is always attached to drive 8, while **IMAGE2** is attached to drive 9.

**COMMANDS** specified on the command-line all begin with the minus sign (-); if present, **c1541** executes them in the same order as they are on the command line and returns a zero error code if they were successful. If any of the **COMMANDS** fails, **c1541** stops and returns a nonzero error code.

If no **COMMANDS** are specified at all, **c1541** enters interactive mode, where you can type commands manually. Commands in interactive mode are the same as commands in batch mode, but do not require a leading -. As with the monitor, file name completion and command line editing with history are provided via GNU **readline**. Use the command ‘quit’ or press **C-d** to exit.

### 12.1 Specifying files in c1541

When accessing CBM DOS files (i.e. files that reside on disk images), **c1541** uses a special syntax that lets you access files on both drive 8 and 9. If you prepend the file name with **@8:** or **@9:**, you will specified that file is to be found or created on drive 8 and 9, respectively.

For instance,

```
@8:somefile
will name file named somefile on unit 8, while
@9:somefile
will name file named somefile on unit 9.
```

## 12.2 Using quotes and backslashes

You can use quotes (") in a command to embed spaces into file names. For instance,

```
read some file
will read file some from the disk image and write it into the file system as file, while
read "some file"
will copy some file into the file system, with the name some file.
```

The backslash character (\) has a special meaning too: it lets you literally insert the following character no matter what it is. For example,

```
read some\ file
will copy file some file into the file system, while
read some\ file this\"file
will copy some file into the file system with name this"file (with an embedded quote).
```

## 12.3 c1541 commands and options

This is a list of the c1541 commands. They are shown in their interactive form, without the leading -. Square brackets [] indicate an optional part, and "<COMMAND>" translates to a disk command according to CBM DOS, like "i0" for example.

```
[<command>]
    Execute specified CBM DOS command and print the current status of the drive.
    If no command is specified, just print the status.

? [<command>]
    Explain specified command. If no command is specified, list available ones.

attach <diskimage> [<unit>]
    Attach diskimage to unit (default unit is 8).

block <track> <sector> <disp> [<drive>]
    Show specified disk block in hex form.

copy <source1> [<source2> ... <sourceN>] <destination>
    Copy source1 ... sourceN into destination. If N > 1, destination must be a
    simple drive specifier (@n:).

delete <file1> [<file2> ... <fileN>]
    Delete the specified files.

exit
    Exit (same as quit).

extract
    Extract all the files to the file system.
```

**format** <diskname,id> [<type> <imagename>] [<unit>]  
 If **unit** is specified, format the disk in unit **unit**. If **type** and **imagename** are specified, create a new image named **imagename**, attach it to unit 8 and format it. **type** is a disk image type, and must be either **x64**, **d64** (both VC1541/2031), **g64** (VC1541/2031 but in GCR coding), **d71** (VC1571), **d81** (VC1581), **d80** (CBM8050) or **d82** (CBM8250/1001). Otherwise, format the disk in the current unit, if any.

**gcrformat** <diskname,id> <imagename>  
 Create and format a G64 disk image named **imagename**.

**help** [<command>]  
 Explain specified command. If no command is specified, list available ones.

**info** [<unit>]  
 Display information about unit **unit** (if unspecified, use the current one).

**list** [<pattern>]  
 List files matching **pattern** (default is all files).

**quit**      Exit (same as **exit**).

**read** <source> [<destination>]  
 Read **source** from the disk image and copy it into **destination** in the file system. If **destination** is not specified, copy it into a file with the same name as **source**.",

**rename** <oldname> <newname>  
 Rename **oldname** into **newname**. The files must be on the same drive.

**tape** <t64name> [<file1> ... <fileN>]  
 Extract files from a T64 image.

**unit** <number>  
 Make unit **number** the current unit.

**unlynx** <lynxname> [<unit>]  
 Extract the specified Lynx image file into the specified unit (default is the current unit).

**validate** [<unit>]  
 Validate the disk in unit **unit**. If **unit** is not specified, validate the disk in the current unit.

**write** <source> [<destination>]  
 Write **source** from the file system into **destination** on a disk image.

**zcreate** <x64name> <zipname> [<label,id>]  
 Create an X64 disk image out of a set of four Zipcoded files named **1!zipname**, **2!zipname**, **3!zipname** and **4!zipname**.

## 12.4 Executing shell commands

If you want to execute a shell command from within `c1541`, just prepend it with an exclamation mark (`!`). For example,

```
!ls -la
```

will execute the command `ls -la`, which will show you all the files in the current directory.

## 12.5 c1541 examples

```
c1541 -attach test.d64 -write test.prg testfile  
Write test.prg to test.d64 as testfile.
```

# 13 cartconv

The `cartconv` program is a cartridge conversion utility, it can convert between binary and `.crt` images and it can 'insert' binary and/or `.crt` images into the EPROM type of cartridges.

## 13.1 cartconv command line options

The `cartconv` program has the following parameters:

`-i "input name"`

This parameter is mandatory, it should contain the name of the binary/`.crt` file you want to convert. For the EPROM type of cartridges this parameter can be used multiple times to insert images into the resulting file.

`-o "output name"`

This parameter is mandatory, it should contain the name of the binary/`.crt` file you want to convert the input file to.

`-t carttype`

This parameter is optional. It is only needed when converting to a `.crt` file. See below for the supported cartridge types.

`-n "cart name"`

This parameter is optional and is used as the cartridge name when creating a `.crt` file.

`-l loadaddress`

This parameter is optional and is used as the load-address when converting a `.crt` file to a `.prg` file, or when converting to a generic type `.crt` file.

`-f "input name"`

This parameter is optional, and is meant to output information about the named file. It can't be used in conjunction with any of the other parameters.

`-r` This parameter is optional, it enables repair mode (accept broken input files)

The following cartridge types are supported:

`bin` Binary `.bin` file (Default `crt->bin`)

<code>normal</code>	Generic 8kB/12kB/16kB .crt file (Default bin->crt)
<code>prg</code>	Binary C64 .prg file with load-address
<code>ulti</code>	Ultimax mode 4kB/8kB/16kB .crt file
<code>ap</code>	Atomic Power .crt file
<code>ar2</code>	Action Replay MK2 .crt file
<code>ar3</code>	Action Replay MK3 .crt file
<code>ar4</code>	Action Replay MK4 .crt file
<code>ar5</code>	Action Replay V5 .crt file
<code>cap</code>	Capture .crt file
<code>comal</code>	Comal 80 .crt file
<code>dep256</code>	Dela EP256 .crt file, extra files can be inserted (1)(2)
<code>dep64</code>	Dela EP64 .crt file, extra files can be inserted (1)
<code>dep7x8</code>	Dela EP7x8 .crt file, extra files can be inserted (1)(2)(3)
<code>din</code>	Dinamic .crt file
<code>dsm</code>	Diashow-Maker .crt file
<code>easy</code>	EasyFlash .crt file
<code>epyx</code>	Epyx FastLoad .crt file
<code>exos</code>	EXOS .crt file
<code>expert</code>	Expert Cartridge .crt file
<code>fc1</code>	The Final Cartridge .crt file
<code>fc3</code>	The Final Cartridge III .crt file
<code>fcP</code>	Final Cartridge Plus .crt file
<code>ff</code>	Freeze Frame .crt file
<code>fm</code>	Freeze Machine .crt file
<code>fp</code>	Fun Play .crt file
<code>gk</code>	Game Killer .crt file
<code>gs</code>	C64 Games System .crt file
<code>ide64</code>	IDE64 .crt file
<code>ieee</code>	IEEE-488 Interface .crt file
<code>kcs</code>	KCS Power Cartridge .crt file
<code>mach5</code>	MACH 5 .crt file
<code>md</code>	Magic Desk .crt file
<code>mf</code>	Magic Formel .crt file

<b>mikro</b>	Mikro Assembler .crt file
<b>mmc64</b>	MMC64 .crt file
<b>mmcr</b>	MMC Replay .crt file
<b>mv</b>	Magic Voice .crt file
<b>ocean</b>	Ocean .crt file
<b>p64</b>	Prophet64 .crt file
<b>rep256</b>	REX 256k EPROM Cart .crt file, extra files can be inserted (1)(2)(3)
<b>ross</b>	ROSS .crt file
<b>rr</b>	Retro Replay .crt file
<b>ru</b>	REX Utility .crt file
<b>s64</b>	Snapshot 64 .crt file
<b>sb</b>	Structured BASIC .crt file
<b>se5</b>	Super Explode V5.0 .crt file
<b>sg</b>	Super Games .crt file
<b>simon</b>	Simons' BASIC .crt file
<b>ss4</b>	Super Snapshot V4 .crt file
<b>ss5</b>	Super Snapshot V5 .crt file
<b>star</b>	Stardos .crt file
<b>wl</b>	Westermann Learning .crt file
<b>ws</b>	Warp Speed .crt file
<b>zaxxon</b>	Zaxxon .crt file

- (1) insertion of 32kB EPROM files supported.
- (2) insertion of 8kB .crt/binary files supported.
- (3) insertion of 16kB .crt/binary files supported.

## 13.2 cartconv examples

```
cartconv -i foo.crt -o foo.bin
    Convert a .crt file to a binary file with no load-address.
```

```
cartconv -t prg -i foo.crt -o foo.prg
    Convert a .crt file to a .prg file with default load-address.
```

```
cartconv -t prg -l 49152 -i foo.crt -o foo.prg
    Convert a .crt file to a .prg file with 49152 as the load-address.
```

```
cartconv -t ocean -i foo.bin -o foo.crt
    Convert a binary file to an ocean type cartridge.
```

```
cartconv -t dep64 -i dep64.bin -i eprom.prg -o foo.crt
```

Inserting a 32kB EPROM file into an dep64 type cartridge.

- step 1 : use the dep64 binary file in VICE as a generic 8kB cartridge.
- step 2 : generate an EPROM file.
- step 3 : get the EPROM file to the host computer.
- step 4 : insert the EPROM file into the final dep64 .crt file:

```
cartconv -t dep256 -i dep256.bin -i somegame.crt -o foo.crt
```

Insert an 8kB .crt file into a dep256 type cartridge.

```
cartconv -t rep256 -i rep256.bin -i foo1.crt -i foo2.crt -i foo3.crt -o foo.crt
```

Insert multiple 8kB .crt files into a rep256 type cartridge.

```
cartconv -f foo.crt
```

Get information about a .crt file.

## 14 petcat

The petcat program is a text conversion utility, it can convert between ASCII, PETSCII and tokenized BASIC.

### 14.1 petcat command line options

- help**      Output help text
- v**          Same as above
- c**          controls (interpret also control codes) (default if textmode)
- nc**        no controls (suppress control codes in printout) (default if non-textmode)
- ic**        interpret control codes case-insensitive
- h**          write header (default if output is stdout)
- nh**        no header (default if output is a file)
- skip <n>**   Skip <n> bytes in the beginning of input file. Ignored on P00.
- text**      Force text mode
- <version>**  
             use keywords for <version> instead of the v7.0 ones
- w<version>**  
             tokenize using keywords on specified Basic version.
- k<version>**  
             list all keywords for the specified Basic version
- k**          list all Basic versions available.
- l**          Specify load address for program (in hex, no loading chars!).
- o <name>**   Specify the output file name

**-f** Force overwritten the output file. The default depends on the BASIC version.

#### BASIC Versions:

<b>1</b>	PET Basic V1.0
<b>2</b>	Basic v2.0
<b>superexp</b>	Basic v2.0 with Super Expander (VIC20)
<b>turtle</b>	Basic v2.0 with Turtle Basic by Craig Bruce (VIC20)
<b>mighty</b>	Basic v2.0 with Mighty Basic by Craig Bruce (VIC20)
<b>a</b>	Basic v2.0 with AtBasic (C64)
<b>simon</b>	Basic v2.0 with Simon's Basic extension (C64)
<b>speech</b>	Basic v2.0 with Speech Basic v2.7 (C64)
<b>F</b>	Basic v2.0 with Final Cartridge III (C64)
<b>ultra</b>	Basic v2.0 with Ultrabasic-64 (C64)
<b>graph</b>	Basic v2.0 with Graphics basic (C64)
<b>WSB</b>	Basic v2.0 with WS basic (C64)
<b>WSBF</b>	Basic v2.0 with WS basic final (C64)
<b>Pegasus</b>	Basic v2.0 with Pegasus basic 4.0 (C64)
<b>Xbasic</b>	Basic v2.0 with Xbasic (C64)
<b>Drago</b>	Basic v2.0 with Drago basic 2.2 (C64)
<b>REU</b>	Basic v2.0 with REU-basic (C64)
<b>Lightning</b>	Basic v2.0 with Basic Lightning (C64)
<b>magic</b>	Basic v2.0 with Magic Basic (C64)
<b>easy</b>	Basic v2.0 with Easy Basic (VIC20)
<b>blarg</b>	Basic v2.0 with Blarg (C64)
<b>Game</b>	Basic v2.0 with Game Basic (C64)
<b>BSX</b>	Basic v2.0 with Basex (C64)
<b>superbas</b>	Basic v2.0 with Super Basic (C64)
<b>exp20</b>	Basic 2.0 with Expanded Basic (VIC20)
<b>exp64</b>	Basic 2.0 with Expanded Basic (C64)
<b>sxc</b>	Basic 2.0 with Super Expander Chip (C64)
<b>warsaw</b>	Basic 2.0 with Warsaw Basic (C64)
<b>4v</b>	Basic 2.0 with Basic 4.0 extensions (VIC20)
<b>4 -w4e</b>	PET Basic v4.0 program (PET/C64)



5	Basic 2.0 with Basic 5.0 extensions (VIC20)
3	Basic v3.5 program (C16)
70	Basic v7.0 program (C128)
71	Basic v7.1 program (C128)
10	Basic v10.0 program (C64DX)

## 14.2 petcat examples

```
petcat -2 -o outputfile.txt -- inputfile.prg
```

Convert inputfile.prg to a text file in outputfile.txt, using BASIC V2 only

```
petcat -wsimon -o outputfile.prg -- inputfile.txt
```

Convert inputfile.txt to a PRG file in outputfile.prg, using Simon's BASIC

# 15 The emulator file formats

This chapter gives a technical description of the various files supported by the emulators.

## 15.1 The T64 tape image format

(This section was taken from the C64S distribution.)

The T64 File Structure was developed by Miha Peternel for use in the C64S emulator. It is easy to use and allows future extensions.

### 15.1.1 T64 File structure

Offset	Size	Description
0	64	tape record
64	32*n	file records for n directory entries
64+32*n	varies	binary contents of the files

### 15.1.2 Tape Record

Offset	Size	Description
0	32	DOS tape description + EOF (for type)
32	2	tape version (\$0200)
34	2	number of directory entries
36	2	number of used entries (can be 0 in my loader)
38	2	free
40	24	user description as displayed in tape menu

### 15.1.3 File record

Offset	Size	Description
0	1	entry type (see below)
1	1	C64 file type
2	2	start address
4	2	end address
6	2	free
8	4	offset of file contents start within T64 file
12	4	free
16	16	C64 file name

Valid entry types are:

Code	Explanation
0	free entry
1	normal tape file
2	tape file with header: header is saved just before file data
3	memory snapshot v0.9, uncompressed
4	tape block
5	digitized stream
6 . . . 255	reserved

Notes:

- VICE only supports file type 1.
- Types 3, 4 and 5 are subject to change (and are rarely used).

## 15.2 The G64 GCR-encoded disk image format

(This section was contributed by Peter Schepers and slightly edited by Ettore Perazzoli.)

This format was defined in 1998 as a cooperative effort between several emulator people, mainly Per Hkan Sundell, author of the CCS64 C64 emulator, Andreas Boose of the VICE CBM emulator team and Joe Forster/STA, the author of Star Commander. It was the first real public attempt to create a format for the emulator community which removed almost all of the drawbacks of the other existing image formats, namely D64.

The intention behind G64 is not to replace the widely used D64 format, as D64 works fine with the vast majority of disks in existence. It is intended for those small percentage of programs which demand to work with the 1541 drive in a non-standard way, such as reading or writing data in a custom format. The best example is with speeder software such as Action Cartridge in Warp Save mode or Vorpall which write track/sector data in another format other than standard GCR. The other obvious example is copy-protected software which looks for some specific data on a track, like the disk ID, which is not stored in a standard D64 image.

G64 has a deceptively simply layout for what it is capable of doing. We have a signature, version byte, some predefined size values, and a series of offsets to the track data and speed zones. It is what's contained in the track data areas and speed zones which is really at the heart of this format.

Each track entry is simply the raw stream of GCR data, just what a read head would see when a diskette is rotating past it. How the data gets interpreted is up to the program trying to access the disk. Because the data is stored in such a low-level manner, just about anything can be done. Most of the time I would suspect the data in the track would be standard sectors, with SYNC, GAP, header, data and checksums. The arrangement of the data when it is in a standard GCR sector layout is beyond the scope of this document.

Since it is a flexible format in both track count and track byte size, there is no “standard” file size. However, given a few constants like 42 tracks and halftracks, a track size of 7928 bytes and no speed offset entries, the typical file size will be a minimum of 333744 bytes.

Below is a dump of the header, broken down into its various parts. After that will be an explanation of the track offset and speed zone offset areas, as they demand much more explanation.

Addr	00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F
----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----
0000:	47	43	52	2D	31	35	34	31	00	54	F8	1E	..	..	..	..
Offset	Description															
\$0000-0007	File signature (GCR-1541)															
\$0008	G64 version (presently only \$00 defined)															
\$0009	Number of tracks in image (usually \$54, decimal 84)															
\$000A-000B	Size of each stored track in bytes (usually 7928, or \$1EF8) in LO/HI format.															

An obvious question here is “why are there 84 tracks defined when a normal D64 disk only has 35 tracks?” Well, by definition, this image includes all half-tracks, so there are actually 42 tracks and 42 half tracks. The 1541 stepper motor can access up to 42 tracks and the in-between half-tracks. Even though using more than 35 tracks is not typical, it was important to define this format from the start with what the 1541 is capable of doing, and not just what it typically does.

At first, the defined track size value of 7928 bytes may seem to be arbitrary, but it is not. It is determined by the fastest write speed possible (speed zone 0), coupled with the average rotation speed of the disk (300 rpm). After some math, the answer that actually comes up is 7692 bytes. Why the discrepancy between the actual size of 7692 and the defined size of 7928? Simply put, not all drives rotate at 300 rpm. Some can be faster or slower, so an upper safety margin of +3% was built added, in case some disks rotate slower and can write more data. After applying this safety factor, and some rounding-up, 7928 bytes per track was arrived at.

Also note that this upper limit of 7928 bytes per track really only applies to 1541 and compatible disks. If this format were applied to another disk type like the SFD1001, this value would be higher.

Below is a dump of the first section of a G64 file, showing the offsets to the data portion for each track and half-track entry. Following that is a dump of the speed zone offsets.

Addr	00	01	02	03	04	05	06	07	08	09	0A	0B	0C	0D	0E	0F
----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----
0000:	..	..	..	..	..	..	..	..	..	..	..	..	AC	02	00	00
0010:	00	00	00	00	A6	21	00	00	00	00	00	00	A0	40	00	00
0020:	00	00	00	00	9A	5F	00	00	00	00	00	00	94	7E	00	00

```

0030: 00 00 00 00 8E 9D 00 00 00 00 00 00 88 BC 00 00
0040: 00 00 00 00 82 DB 00 00 00 00 00 00 7C FA 00 00
0050: 00 00 00 00 76 19 01 00 00 00 00 00 70 38 01 00
0060: 00 00 00 00 6A 57 01 00 00 00 00 00 64 76 01 00
0070: 00 00 00 00 5E 95 01 00 00 00 00 00 58 B4 01 00
0080: 00 00 00 00 52 D3 01 00 00 00 00 00 4C F2 01 00
0090: 00 00 00 00 46 11 02 00 00 00 00 00 40 30 02 00
00A0: 00 00 00 00 3A 4F 02 00 00 00 00 00 34 6E 02 00
00B0: 00 00 00 00 2E 8D 02 00 00 00 00 00 28 AC 02 00
00C0: 00 00 00 00 22 CB 02 00 00 00 00 00 1C EA 02 00
00D0: 00 00 00 00 16 09 03 00 00 00 00 00 10 28 03 00
00E0: 00 00 00 00 0A 47 03 00 00 00 00 00 04 66 03 00
00F0: 00 00 00 00 FE 84 03 00 00 00 00 00 F8 A3 03 00
0100: 00 00 00 00 F2 C2 03 00 00 00 00 00 EC E1 03 00
0110: 00 00 00 00 E6 00 04 00 00 00 00 00 E0 1F 04 00
0120: 00 00 00 00 DA 3E 04 00 00 00 00 00 D4 5D 04 00
0130: 00 00 00 00 CE 7C 04 00 00 00 00 00 C8 9B 04 00
0140: 00 00 00 00 C2 BA 04 00 00 00 00 00 BC D9 04 00
0150: 00 00 00 00 B6 F8 04 00 00 00 00 00 .. .. .. ..

```

Offset	Description
\$000C-000F	Offset to stored track 1.0 (\$000002AC, in LO/HI format, see below for more)
\$0010-0013	Offset to stored track 1.5 (\$00000000)
\$0014-0017	Offset to stored track 2.0 (\$000021A6)
...	
\$0154-0157	Offset to stored track 42.0 (\$0004F8B6)
\$0158-015B	Offset to stored track 42.5 (\$00000000)

```

      00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
      -----
0150: .. .. .. .. .. .. .. .. .. .. .. 03 00 00 00
0160: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
0170: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
0180: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
0190: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
01A0: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
01B0: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
01C0: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
01D0: 00 00 00 00 03 00 00 00 00 00 00 00 03 00 00 00
01E0: 00 00 00 00 02 00 00 00 00 00 00 00 02 00 00 00
01F0: 00 00 00 00 02 00 00 00 00 00 00 00 02 00 00 00
0200: 00 00 00 00 02 00 00 00 00 00 00 00 02 00 00 00
0210: 00 00 00 00 02 00 00 00 00 00 00 00 01 00 00 00
0220: 00 00 00 00 01 00 00 00 00 00 00 00 01 00 00 00
0230: 00 00 00 00 01 00 00 00 00 00 00 00 01 00 00 00
0240: 00 00 00 00 01 00 00 00 00 00 00 00 00 00 00 00
0250: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

```

```

0260: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0270: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0280: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0290: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
02A0: 00 00 00 00 00 00 00 00 00 00 00 00 00 .. .. .. ..

```

Offset	Description
\$015C-015F	Speed zone entry for track 1 (\$03, in LO/HI format, see below for more)
\$0160-0163	Speed zone entry for track 1.5 (\$03)
...	
\$02A4-02A7	Speed zone entry for track 42 (\$00)
\$02A8-02AB	Speed zone entry for track 42.5 (\$00)

Starting here at \$02AC is the first track entry (from above, it is the first entry for track 1.0)

The track offsets (from above) require some explanation. When one is set to all 0's, no track data exists for this entry. If there is a value, it is an absolute reference into the file (starting from the beginning of the file). From the track 1.0 entry we see it is set for \$000002AC. Going to that file offset, here is what we see...

```

      00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
      -----
02A0:  .. .. .. .. .. .. .. .. .. .. .. .. 0C 1E FF FF
02B0:  FF FF FF 52 54 B5 29 4B 7A 5E 95 55 55 55 55 55
02C0:  55 55 55 55 55 55 FF FF FF FF FF 55 D4 A5 29 4A
02D0:  52 94 A5 29 4A 52 94 A5 29 4A 52 94 A5 29 4A 52

```

Offset	Description
\$02AC-02AD	Actual size of stored track (7692 or \$1E0C, in LO/HI format)
\$02AE-02AE+\$1E0C	Track data

Following the track data is filler bytes. In this case, there are 368 bytes of unused space. This space can contain anything, but for the sake of those wishing to compress these images for storage, they should all be set to the same value. In the sample I used, these are all set to \$FF.

Below is a dump of the end of the track 1.0 data area. Note the actual track data ends at address \$20B9, with the rest of the block being unused, and set to \$FF.

```

      00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
      -----
1FE0:  52 94 A5 29 4A 52 94 A5 29 4A 52 94 A5 29 4A 52
1FF0:  94 A5 29 4A 52 94 A5 29 4A 52 94 A5 29 4A 52 94
2000:  A5 29 4A 52 94 A5 29 4A 52 94 A5 29 4A 52 94 A5
2010:  29 4A 52 94 A5 29 4A 52 94 A5 29 4A 52 94 A5 29
2020:  4A 52 94 A5 29 4A 52 94 A5 29 4A 52 94 A5 29 4A
2030:  55 55 55 55 55 55 FF FF FF FF FF FF FF FF FF FF
2040:  FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2050:  FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2060:  FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF

```

```

2070: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2080: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2090: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
20A0: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
20B0: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
20C0: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
20D0: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
20E0: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
20F0: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2100: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2110: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2120: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2130: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2140: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2150: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2160: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2170: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2180: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
2190: FF FF FF FF FF FF FF FF FF FF FF FF FF FF FF
21A0: FF FF FF FF FF FF .. .. .. .. .. .. .. ..

```

The speed offset entries can be a little more complex. The 1541 has four speed zones defined, which means the drive can write data at four distinct speeds. On a normal 1541 disk, these zones are as follows:

Track Range	Speed Zone
1-17	3 (highest writing speed)
18-24	2
25-30	1
31 and up	0 (lowest writing speed)

Note that you can, through custom programming of the 1541, change the speed zone of any track to something different (change the 3 to a 0) and write data differently. From the dump of the speed offset entries above, we see that all the entries are in the range of 0-3. If any entry is less than 4, this is not considered a speed offset but defines the whole track to be recorded at that one speed.

In the example I had, there were no offsets defined, so no speed zone dump can be shown. However, I can define what should be there. You will have a block of data, 1982 bytes long. Each byte is encoded to represent the speed of 4 bytes in the track offset area, and is broken down as follows:

```

Speed entry $FF:  in binary %11111111
                  |'|'|'|'
                  ||||
                  ||| +- 4'th byte speed (binary 11, 3 dec)
                  || +--- 3'rd byte speed (binary 11, 3 dec)
                  | +----- 2'nd byte speed (binary 11, 3 dec)
                  +----- 1'st byte speed (binary 11, 3 dec)

```

It was very smart thinking to allow for two speed zone settings, one in the offset block and another defining the speed on a per-byte basis. If you are working with a normal disk,

where each track is one constant speed, then you don't need the extra blocks of information hanging around the image, wasting space.

What may not be obvious is the flexibility of this format to add tracks and speed offset zones at will. If a program decides to write a track out with varying speeds, and no speed offset exist, a new block will be created by appending it to the end of the image, and the offset pointer for that track set to point to the new block. If a track has no offset yet, meaning it doesn't exist (like a half-track), and one needs to be added, the same procedure applies. The location of the actual track or speed zone data is not important, meaning they do not have to be in any particular order since they are all referenced by the offsets at the beginning of the image.

### 15.3 The D64 disk image format

(This section was contributed by Peter Schepers and slightly edited by Marco van den Heuvel.)

First and foremost we have D64, which is basically a sector-for-sector copy of a 1540/1541 disk. There are several versions of these which I will cover shortly. The standard D64 is a 174848 byte file comprised of 256 byte sectors arranged in 35 tracks with a varying number of sectors per track for a total of 683 sectors. Track counting starts at 1, not 0, and goes up to 35. Sector counting starts at 0, not 1, for the first sector, therefore a track with 21 sectors will go from 0 to 20.

The original media (a 5.25" disk) has the tracks laid out in circles, with track 1 on the very outside of the disk (closest to the sides) to track 35 being on the inside of the disk (closest to the inner hub ring). Commodore, in their infinite wisdom, varied the number of sectors per track and data densities across the disk to optimize available storage, resulting in the chart below. It shows the sectors/track for a standard D64. Since the outside diameter of a circle is the largest (versus closer to the center), the outside tracks have the largest amount of storage.

Track	Sectors/track	# Sectors
1-17	21	357
18-24	19	133
25-30	18	108
31-35	17	85
36-40(*)	17	85

  

Track	#Sect	#SectorsIn	D64 Offset
1	21	0	\$00000
2	21	21	\$01500
3	21	42	\$02A00
4	21	63	\$03F00
5	21	84	\$05400
6	21	105	\$06900
7	21	126	\$07E00
8	21	147	\$09300
9	21	168	\$0A800
10	21	189	\$0BD00
11	21	210	\$0D200

12	21	231	\$0E700
13	21	252	\$0FC00
14	21	273	\$11100
15	21	294	\$12600
16	21	315	\$13B00
17	21	336	\$15000
18	19	357	\$16500
19	19	376	\$17800
20	19	395	\$18B00
21	19	414	\$19E00
22	19	433	\$1B100
23	19	452	\$1C400
24	19	471	\$1D700
25	18	490	\$1EA00
26	18	508	\$1FC00
27	18	526	\$20E00
28	18	544	\$22000
29	18	562	\$23200
30	18	580	\$24400
31	17	598	\$25600
32	17	615	\$26700
33	17	632	\$27800
34	17	649	\$28900
35	17	666	\$29A00
36(*)	17	683	\$2AB00
37(*)	17	700	\$2BC00
38(*)	17	717	\$2CD00
39(*)	17	734	\$2DE00
40(*)	17	751	\$2EF00

(\*) Tracks 36-40 apply to 40-track images only.

The directory track should be contained totally on track 18. Sectors 1-18 contain the entries and sector 0 contains the BAM (Block Availability Map) and disk name/ID. Since the directory is only 18 sectors large (19 less one for the BAM), and each sector can contain only 8 entries (32 bytes per entry), the maximum number of directory entries is  $18 * 8 = 144$ . The first directory sector is always 18/1, even though the t/s pointer at 18/0 (first two bytes) might point somewhere else. It then follows the same chain structure as a normal file, using a sector interleave of 3. This makes the chain links go 18/1, 18/4, 18/7 etc.

Note that you can extend the directory off of track 18, but only when reading the disk or image. Attempting to write to a directory sector not on track 18 will cause directory corruption. Each directory sector has the following layout (18/1 partial dump):

```
00: 12 04 81 11 00 4E 41 4D 45 53 20 26 20 50 4F 53 <- notice the T/S link■
10: 49 54 A0 A0 A0 00 00 00 00 00 00 00 00 15 00 <- to 18/4 ($12/$04)■
20: 00 00 84 11 02 41 44 44 49 54 49 4F 4E 41 4C 20 <- and how its not here■
30: 49 4E 46 4F A0 11 0C FE 00 00 00 00 00 00 61 01 <- ($00/$00)
```

The first two bytes of the sector (\$12/\$04) indicate the location of the next track/sector of the directory (18/4). If the track is set to \$00, then it is the last sector of the directory. It



is possible, however unlikely, that the directory may *\*not\** be completely on track 18 (some disks do exist like this). Just follow the chain anyhow.

When the directory is done, the track value will be \$00. The sector link should contain a value of \$FF, meaning the whole sector is allocated, but the actual value doesn't matter. The drive will return all the available entries anyways.

This is a breakdown of a standard directory sector:

Bytes	Description
\$00-\$1F	First directory entry
\$20-\$3F	Second dir entry
\$40-\$5F	Third dir entry
\$60-\$7F	Fourth dir entry
\$80-\$9F	Fifth dir entry
\$A0-\$BF	Sixth dir entry
\$C0-\$DF	Seventh dir entry
\$E0-\$FF	Eighth dir entry

This is a breakdown of a standard directory entry:

Bytes	Description
\$00-\$01	Track/Sector location of next directory sector (\$00 \$00 if not the first entry in the sector)
\$02	File type
\$03-\$04	Track/sector location of first sector of file
\$05-\$14	16 character filename (in PETASCII, padded with \$A0)
\$15-\$16	Track/Sector location of first side-sector block (REL file only)
\$17	REL file record length (REL file only, max. value 254)
\$18-\$1D	Unused (except with GEOS disks)
\$1E-\$1F	File size in sectors, low/high byte order (\$1E+\$1F*256). The approx. filesize in bytes is $\leq \#sectors * 254$

The file type field is used as follows:

Bits	Description
0-3	The actual file type
4	Unused
5	Used only during SAVE- replacement
6	Locked flag (Set produces ">" locked files)
7	Closed flag (Not set produces "*", or "splat" files)

The actual file type can be one of the following:

Binary	Decimal	File type
0000	0	DEL
0001	1	SEQ
0010	2	PRG
0011	3	USR
0100	4	REL

Values 5-15 are illegal, but if used will produce very strange results. The 1541 is inconsistent in how it treats these bits. Some routines use all 4 bits, others ignore bit 3, resulting in values from 0-7.

Files, on a standard 1541, are stored using an interleave of 10. Assuming a starting track/sector of 17/0, the chain would run 17/0, 17/10, 17/20, 17/8, 17/18, etc.

### \*\*\* Non-Standard & Long Directories

Most Commodore floppy disk drives use a single dedicated directory track where all filenames are stored. This limits the number of files stored on a disk based on the number of sectors on the directory track. There are some disk images that contain more files than would normally be allowed. This requires extending the directory off the default directory track by changing the last directory sector pointer to a new track, allocating the new sectors in the BAM, and manually placing (or moving existing) file entries there. The directory of an extended disk can be read and the files that reside there can be loaded without problems on a real drive. However, this is still a very dangerous practice as writing to the extended portion of the directory will cause directory corruption in the non-extended part. Many of the floppy drives core ROM routines ignore the track value that the directory is on and assume the default directory track for operations.

To explain: assume that the directory has been extended from track 18 to track 19/6 and that the directory is full except for a few slots on 19/6. When saving a new file, the drive DOS will find an empty file slot at 19/6 offset \$40 and correctly write the filename and a few other things into this slot. When the file is done being saved the final file information will be written to 18/6 offset \$40 instead of 19/6 causing some directory corruption to the entry at 18/6. Also, the BAM entries for the sectors occupied by the new file will not be saved and the new file will be left as a SPLAT (\*) file.

Attempts to validate the disk will result in those files residing off the directory track to not be allocated in the BAM, and could also send the drive into an endless loop. The default directory track is assumed for all sector reads when validating so if the directory goes to 19/6, then the validate code will read 18/6 instead. If 18/6 is part of the normal directory chain then the validate routine will loop endlessly.

### \*\*\* BAM layout

The layout of the BAM area (sector 18/0) is a bit more complicated...

```

00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
-----
00: 12 01 41 00 12 FF F9 17 15 FF FF 1F 15 FF FF 1F
10: 15 FF FF 1F 12 FF F9 17 00 00 00 00 00 00 00
20: 00 00 00 00 0E FF 74 03 15 FF FF 1F 15 FF FF 1F
30: 0E 3F FC 11 07 E1 80 01 15 FF FF 1F 15 FF FF 1F
40: 15 FF FF 1F 15 FF FF 1F 0D C0 FF 07 13 FF FF 07
50: 13 FF FF 07 11 FF CF 07 13 FF FF 07 12 7F FF 07
60: 13 FF FF 07 0A 75 55 01 00 00 00 00 00 00 00
70: 00 00 00 00 00 00 00 00 01 08 00 00 03 02 48 00
80: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
90: 53 48 41 52 45 57 41 52 45 20 31 20 20 A0 A0 A0
A0: A0 A0 56 54 A0 32 41 A0 A0 A0 A0 00 00 00 00
B0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
C0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
D0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
E0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

```

F0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

Bytes	Description
\$00-\$01	Track/Sector location of the first directory sector (should be set to 18/1 but it doesn't matter, and don't trust what is there, always go to 18/1 for first directory entry)
\$02	Disk DOS version type (see note below) \$41 ("A")
\$03	Unused
\$04-\$8F	BAM entries for each track, in groups of four bytes per track, starting on track 1 (see below for more details)
\$90-\$9F	Disk Name (padded with \$A0)
\$A0-\$A1	Filled with \$A0
\$A2-\$A3	Disk ID
\$A4	Usually \$A0
\$A5-\$A6	DOS type, usually "2A"
\$A7-\$AA	Filled with \$A0
\$AB	Unused (\$00)
\$AC-\$BF	For DOLPHIN DOS track 36-40 BAM entries, otherwise unused (\$00)
\$C0-\$D3	For SPEED DOS track 36-40 BAM entries, otherwise unused (\$00)
\$D4-\$FF	Unused (\$00)

Note: The BAM entries for SPEED, DOLPHIN and ProLogic DOS use the same layout as standard BAM entries. One of the interesting things from the BAM sector is the byte at offset \$02, the DOS version byte. If it is set to anything other than \$41 or \$00, then we have what is called "soft write protection". Any attempt to write to the disk will return the "DOS Version" error code 73, "CBM DOS V 2.6 1541". The 1541 is simply telling you that it thinks the disk format version is incorrect. This message will normally come up when you first turn on the 1541 and read the error channel. If you write a \$00 or a \$41 into 1541 memory location \$00FF (for device 0), then you can circumvent this type of write-protection, and change the DOS version back to what it should be.

The BAM entries require a bit (no pun intended) more of a breakdown. Take the first entry at bytes \$04-\$07 (\$12 \$FF \$F9 \$17). The first byte (\$12) is the number of free sectors on that track. Since we are looking at the track 1 entry, this means it has 18 (decimal) free sectors. The next three bytes represent the bitmap of which sectors are used/free. Since it is 3 bytes (8 bits/byte) we have 24 bits of storage. Remember that at most, each track only has 21 sectors, so there are a few unused bits.

Bytes	Data	Description
\$04-\$07	\$12 \$FF \$F9 \$17	Track 1 BAM
\$08-\$0B	\$15 \$FF \$FF \$FF	Track 2 BAM
\$0C-\$0F	\$15 \$FF \$FF \$1F	Track 3 BAM
...	...	...
\$8C-\$8F	\$11 \$FF \$FF \$01	Track 35 BAM

These entries must be viewed in binary to make any sense. We will use the first entry (track 1) at bytes 04-07:

FF=11111111, F9=11111001, 17=00010111

In order to make any sense from the binary notation, flip the bits around.

```

          111111 11112222
01234567 89012345 67890123
-----
11111111 10011111 11101000
^               ^
sector 0         sector 20

```

Since we are on the first track, we have 21 sectors, and only use up to the bit 20 position. If a bit is on (1), the sector is free. Therefore, track 1 has sectors 9, 10 and 19 used, all the rest are free. Any leftover bits that refer to sectors that don't exist, like bits 21-23 in the above example, are set to allocated.

Each filetype has its own unique properties, but most follow one simple structure. The first file sector is pointed to by the directory and follows a t/s chain, until the track value reaches \$00. When this happens, the value in the sector link location indicates how much of the sector is used. For example, the following chain indicates a file 6 sectors long, and ends when we encounter the \$00/\$34 chain. At this point the last sector occupies from bytes \$02-\$34.

1	2	3	4	5	6
—	—	—	—	—	—
17/0	17/10	17/20	17/1	17/11	0/52
(11/00)	(11/0A)	(11/14)	(11/01)	(11/0B)	(0/34)

\*\*\* Variations on the D64 layout

These are some variations of the D64 layout:

1. Standard 35 track layout but with 683 error bytes added on to the end of the file. Each byte of the error info corresponds to a single sector stored in the D64, indicating if the sector on the original disk contained an error. The first byte is for track 1/0, and the last byte is for track 35/16.
2. A 40 track layout, following the same layout as a 35 track disk, but with 5 extra tracks. These contain 17 sectors each, like tracks 31-35. Some of the PC utilities do allow you to create and work with these files. This can also have error bytes attached like variant #1.
3. The Commodore 128 allowed for "auto-boot" disks. With this, t/s 1/0 holds a specific byte sequence which the computer recognizes as boot code.

Below is a small chart detailing the standard file sizes of D64 images, 35 or 40 tracks, with or without error bytes.

Disk type	Size
35 track, no errors	174848
35 track, 683 error bytes	175531
40 track, no errors	196608
40 track, 768 error bytes	197376

The following table (provided by Wolfgang Moser) outlines the differences between the standard 1541 DOS and the various "speeder" DOS's that exist. The 'header 7/8' category is the 'fill bytes' as the end of the sector header of a real 1541 disk.

Disk format	tracks	header 7/8	Dos type	Diskdos type	vs.
-------------	--------	---------------	-------------	-----------------	-----

Original CBM DOS v2.6	35	\$0f \$0f	"2A"	\$41/'A'
*SpeedDOS+	40	\$0f \$0f	"2A"	\$41/'A'
Professional DOS Initial	35	\$0f \$0f	"2A"	\$41/'A'
Professional DOS Version 1/Prototype	40	\$0f \$0f	"2A"	\$41/'A'
ProfDOS Release	40	\$0f \$0f	"4A"	\$41/'A'
Dolphin-DOS 2.0/3.0	35	\$0f \$0f	"2A"	\$41/'A'
Dolphin-DOS 2.0/3.0	40	\$0d	"2A"	\$41/'A'
		\$0f		
PrologicDOS 1541	35	\$0f \$0f	"2A"	\$41/'A'
PrologicDOS 1541	40	\$0f \$0f	"2P"	\$50/'P'
ProSpeed 1571 2.0	35	\$0f \$0f	"2A"	\$41/'A'
ProSpeed 1571 2.0	40	\$0f \$0f	"2P"	\$50/'P'

\*Note: There are also clones of SpeedDOS that exist, such as RoloDOS and DigiDOS. Both are just a change of the DOS startup string.

The location of the extra BAM information in sector 18/0, for 40 track images, will be different depending on what standard the disks have been formatted with. SPEED DOS stores them from \$C0 to \$D3, DOLPHIN DOS stores them from \$AC to \$BF and PrologicDOS stored them right after the existing BAM entries from \$90-A3. PrologicDOS also moves the disk label and ID forward from the standard location of \$90 to \$A4. 64COPY and Star Commander let you select from several different types of extended disk formats you want to create/work with.

All three of the speeder DOS's mentioned above don't alter the standard sector interleave of 10 for files and 3 for directories. The reason is that they use a memory cache installed in the drive which reads the entire track in one pass. This alleviates the need for custom interleave values. They do seem to alter the algorithm that finds the next available free sector so that the interleave value can deviate from 10 under certain circumstances, but I don't know why they would bother.

Below is a HEX dump of a Speed DOS BAM sector. Note the location of the extra BAM info from \$C0-D3.

```

00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
-----
0070: 12 FF FF 03 12 FF FF 03 12 FF FF 03 11 FF FF 01
0080: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
0090: A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0
00A0: A0 A0 30 30 A0 32 41 A0 A0 A0 A0 00 00 00 00
00B0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00C0: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
00D0: 11 FF FF 01 00 00 00 00 00 00 00 00 00 00 00

```

Below is a HEX dump of a Dolphin DOS BAM sector. Note the location of the extra BAM info from \$AC-BF.

```

00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
-----
0070: 12 FF FF 03 12 FF FF 03 12 FF FF 03 11 FF FF 01
0080: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
0090: A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0

```

```

00A0: A0 A0 30 30 A0 32 41 A0 A0 A0 A0 00 11 FF FF 01
00B0: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
00C0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00D0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

```

Below is a HEX dump of a PrologicDOS BAM sector. Note that the disk name and ID are now located at \$A4 instead of starting at \$90.

```

      00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
      -----
0070: 12 FF FF 03 12 FF FF 03 12 FF FF 03 11 FF FF 01
0080: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
0090: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
00A0: 11 FF FF 01 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0
00B0: A0 A0 A0 A0 A0 A0 30 30 A0 32 50 A0 A0 A0 A0 00
00C0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
00D0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

```

### \*\*\* Error codes

Here is the meaning of the error bytes added onto the end of any extended D64. The CODE is the same as that generated by the 1541 drive controller... it reports these numbers, not the error code we usually see when an error occurs.

Some of what comes below is taken from Immers/Neufeld book "Inside Commodore DOS". Note the descriptions are not completely accurate as to what the drive DOS is actually doing to seek/read/decode/write sectors, but serve as simple examples only. The "type" field is where the error usually occurs, whether it's searching for any SYNC mark, any header ID, any valid header, or reading a sector.

These first errors are "seek" errors, where the disk controller is simply reading headers and looking at descriptor bytes, checksums, format ID's and reporting what errors it sees. These errors do *\*not\** necessarily apply to the exact sector being looked for. This fact makes duplication of these errors very unreliable.

Code : \$03 Error : 21 Type : Seek Message : No SYNC sequence found.

Each sector data block and header block are preceeded by SYNC marks. If *\*no\** sync sequence is found within 20 milliseconds (only ~1/10 of a disk rotation!) then this error is generated. This error used to mean the entire track is bad, but it does not have to be the case. Only a small area of the track needs to be without a SYNC mark and this error will be generated.

Converting this error to a D64 is very problematic because it depends on where the physical head is on the disk when a read attempt is made. If it is on valid header/sectors then it won't occur. If it happens over an area without SYNC marks, it will happen.

Code : \$02 Error : 20 Type : Seek Message : Header descriptor byte not found (HEX \$08, GCR \$52)

Each sector is preceeded by an 8-byte GCR header block, which starts with the value \$52 (GCR). If this value is not found after 90 attempts, this error is generated.

Basically, what a track has is SYNC marks, and possibly valid data blocks, but no valid header descriptors.

Code : \$09 Error : 27 Type : Seek Message : Checksum error in header block

The header block contains a checksum value, calculated by XOR'ing the TRACK, SECTOR, ID1 and ID2 values. If this checksum is wrong, this error is generated.

Code : \$0B Error : 29 Type : Seek Message : Disk sector ID mismatch

The ID's from the header block of the currently read sector are compared against the ones from the low-level header of 18/0. If there is a mismatch, this error is generated.

Code : \$02 Error : 20 Type : Seek Message : Header block not found

This error can be reported again when searching for the correct header block. An image of the header is built and searched for, but not found after 90 read attempts. Note the difference from the first occurrence. The first one only searches for a valid ID, not the whole header.

Note that error 20 occurs twice during this phase. The first time is when a header ID is being searched for, the second is when the proper header pattern for the sector being searched for is not found.

From this point on, all the errors apply to the specific sector you are looking for. If a read passed all the previous checks, then we are at the sector being searched for.

Note that the entire sector is read before these errors are detected. Therefore the data, checksum and off bytes are available.

Code : \$04 Error : 22 Type : Read Message : Data descriptor byte not found (HEX \$07, GCR \$55)

Each sector data block is preceded by the value \$07, the "data block" descriptor. If this value is not there, this error is generated. Each encoded sector has actually 260 bytes. First is the descriptor byte, then follows the 256 bytes of data, a checksum, and two "off" bytes.

Code : \$05 Error : 23 Type : Read Message : Checksum error in data block

The checksum of the data read of the disk is calculated, and compared against the one stored at the end of the sector. If there's a discrepancy, this error is generated.

Code : \$0F Error : 74 Type : Read Message : Drive Not Ready (no disk in drive or no device 1)

These errors only apply when writing to a disk. I don't see the usefulness of having these as they cannot be present when only \*reading\* a disk.

Code : \$06 Error : 24 Type : Write Message : Write verify (on format)

Code : \$07 Error : 25 Type : Write Message : Write verify error

Once the GCR-encoded sector is written out, the drive waits for the sector to come around again and verifies the whole 325-byte GCR block. Any errors encountered will generate this error.

Code : \$08 Error : 26 Type : Write Message : Write protect on

Self explanatory. Remove the write-protect tab, and try again.

Code : \$0A Error : 28 Type : Write Message : Write error

In actual fact, this error never occurs, but it is included for completeness.

This is not an error at all, but it gets reported when the read of a sector is ok.

Code : \$01 Error : 00 Type : N/A Message : No error.

Self explanatory. No errors were detected in the reading and decoding of the sector.

The advantage with using the 35 track D64 format, regardless of error bytes, is that it can be converted directly back to a 1541 disk by either using the proper cable and software on the PC, or send it down to the C64 and writing it back to a 1541. It is the best documented format since it is also native to the C64, with many books explaining the disk layout and the internals of the 1541.

## 15.4 The X64 disk image format

(This section was contributed by Peter Schepers and slightly edited by Marco van den Heuvel.)

This file type, created by Teemu Rantanen, is used on the X64 emulator (a UNIX-based emulator) which has been superceded by VICE. Both VICE and X64 support the X64 file standard, with VICE also supporting the regular D64 and T64 files.

X64 is not a specific type of file, but rather encompasses \*all\* known C64 disk types (hard disk, floppies, etc). An X64 is created by prepending a 64-byte header to an existing image (1541, 1571, etc) and setting specific bytes which describe what type of image follows. This header has undergone some revision, and this description is based on the 1.02 version, which was the last known at the time of writing.

The most common X64 file you will see is the D64 variety, typically 174912 bytes long (174848 for the D64 and 64 bytes for the header, assuming no error bytes are appended). The header layout (as used in 64COPY) is as follows:

```

      00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
      -----
0000: 43 15 41 64 01 02 01 23 00 00 00 00 00 00 00 00
0010: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0020: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0030: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
0040: XX XX XX <- standard C64 image starts here....

```

Bytes	Description
\$00-\$03	This is the "Magic header" (\$43 \$15 \$41 \$64)
\$04	Header version major (\$01)
\$05	Header version minor (\$01, now its up to \$02)
\$06	Device type represented
\$07	Maximum tracks in image (only in version 1.02 or greater) 1540/41/70: 35 1571: 35 1581: 80 (Logical single-sided disk)
\$08	Number of disk sides in image. This value must be \$00 for all 1541 and 1581 formats. \$00=No second side \$01=Second side
\$09	Error data flag.
\$0A-\$1F	Unused, set to \$00
\$20-\$3E	Disk image description (in ASCII or ISO Latin/1)
\$3F	Always set to \$00
\$40-	Standard C64 file begins here.

The device types are:

Value	Drive type
\$00	1540 See note below...
\$01	1541 (Default)



\$02	1542
\$03	1551
\$04	1570
\$05	1571
\$06	1572
\$08	1581
\$10	2031 or 4031
\$11	2040 or 3040
\$12	2041
\$18	4040
\$20	8050
\$21	8060
\$22	8061
\$30	SFD-1001
\$31	8250
\$32	8280

The first four bytes used for the device type at position \$06 (\$00 to \$03) are functionally the same, and are compatible with older version of X64 files. Some old X64 files might have \$00 for the device type (instead of \$01), but it makes no real difference.

As most instances of X64 files will be strictly 1541 images, bytes \$08-\$3F are set to zero, and some versions of the X64 emulator don't use bytes \$08-\$3F.

## 15.5 The D71 disk image format

(This section was contributed by Peter Schepers and slightly edited by Marco van den Heuvel.)

Similar to the D64 (1541), the 1571 drive can operate in either single-sided (1541 compatible) mode or double-sided (1571) mode. In this section I will be dealing with the double-sided mode only. For the breakdown of the single-sided mode, see the D64 section.

The D71 has 70 tracks, double that of the 1541, with a DOS file size of 349696 bytes. If the error byte block (1366 bytes) is attached, this makes the file size 351062 bytes. The track range and offsets into the D71 files are as follows:

Track	Sec/trk	# Sectors
1-17 (side 0)	21	357
18-24 (side 0)	19	133
25-30 (side 0)	18	108
31-35 (side 0)	17	85
36-52 (side 1)	21	357
53-59 (side 1)	19	133
60-65 (side 1)	18	108
66-70 (side 1)	17	85

  

Track	#Sect	#SectorsIn	D71 Offset
1	21	0	\$00000
2	21	21	\$01500
3	21	42	\$02A00
4	21	63	\$03F00

5	21	84	\$05400
6	21	105	\$06900
7	21	126	\$07E00
8	21	147	\$09300
9	21	168	\$0A800
10	21	189	\$0BD00
11	21	210	\$0D200
12	21	231	\$0E700
13	21	252	\$0FC00
14	21	273	\$11100
15	21	294	\$12600
16	21	315	\$13B00
17	21	336	\$15000
18	19	357	\$16500
19	19	376	\$17800
20	19	395	\$18B00
21	19	414	\$19E00
22	19	433	\$1B100
23	19	452	\$1C400
24	19	471	\$1D700
25	18	490	\$1EA00
26	18	508	\$1FC00
27	18	526	\$20E00
28	18	544	\$22000
29	18	562	\$23200
30	18	580	\$24400
31	17	598	\$25600
32	17	615	\$26700
33	17	632	\$27800
34	17	649	\$28900
35	17	666	\$29A00
36	21	683	\$2AB00
37	21	704	\$2C000
38	21	725	\$2D500
39	21	746	\$2EA00
40	21	767	\$2FF00
41	21	788	\$31400
42	21	809	\$32900
43	21	830	\$33E00
44	21	851	\$35300
45	21	872	\$36800
46	21	893	\$37D00
47	21	914	\$39200
48	21	935	\$3A700
49	21	956	\$3BC00
50	21	977	\$3D100
51	21	998	\$3E600

52	21	1019	\$3FB00
53	19	1040	\$41000
54	19	1059	\$42300
55	19	1078	\$43600
56	19	1097	\$44900
57	19	1116	\$45C00
58	19	1135	\$46F00
59	19	1154	\$48200
60	18	1173	\$49500
61	18	1191	\$4A700
62	18	1209	\$4B900
63	18	1227	\$4CB00
64	18	1245	\$4DD00
65	18	1263	\$4EF00
66	17	1281	\$50100
67	17	1298	\$51200
68	17	1315	\$52300
69	17	1332	\$53400
70	17	1349	\$54500

The directory structure is the same as a D64/1541. All the same filetypes apply, the directory still only holds 144 files per disk and should only exist on track 18.

The first two bytes of the sector (\$12/\$04 or 18/4) indicate the location of the next track/sector of the directory. If the track value is set to \$00, then it is the last sector of the directory. It is possible, however unlikely, that the directory may \*not\* be completely on track 18 (some disks do exist like this). Just follow the chain anyhow.

When the directory is done, the track value will be \$00. The sector link should contain a value of \$FF, meaning the whole sector is allocated, but the actual value doesn't matter. The drive will return all the available entries anyways. This is a breakdown of a standard directory sector and entry:

```

00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
-----
00: 12 04 82 11 00 4A 45 54 20 53 45 54 20 57 49 4C
10: 4C 59 A0 A0 A0 00 00 00 00 00 00 00 00 00 2B 00
20: 00 00 82 0F 01 4A 53 57 20 31 A0 A0 A0 A0 A0 A0
30: A0 A0 A0 A0 A0 00 00 00 00 00 00 00 00 00 BF 00
40: 00 00 82 06 03 53 4F 4E 20 4F 46 20 42 4C 41 47
50: 47 45 52 A0 A0 00 00 00 00 00 00 00 00 00 AE 00
60: 00 00 82 15 0D 50 4F 54 54 59 20 50 49 47 45 4F
70: 4E A0 A0 A0 A0 00 00 00 00 00 00 00 00 00 A2 00
80: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
90: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
A0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
B0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
C0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
D0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
E0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

```

F0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

Bytes	Description
\$00-\$1F	First directory entry
\$20-\$3F	Second dir entry
\$40-\$5F	Third dir entry
\$60-\$7F	Fourth dir entry
\$80-\$9F	Fifth dir entry
\$A0-\$BF	Sixth dir entry
\$C0-\$DF	Seventh dir entry
\$E0-\$FF	Eighth dir entry

This is a breakdown of a standard directory entry:

Bytes	Description
\$00-\$01	Track/Sector location of next directory sector (\$00/\$FF if its the last sector)
\$02	File type
\$03-\$04	Track/sector location of first sector of file
\$05-\$14	16 character filename (in PETASCII, padded with \$A0)
\$15-\$16	Track/Sector location of first side-sector block (REL file only)
\$17	REL file record length (REL file only, max. value 254)
\$18-\$1D	Unused (except with GEOS disks)
\$1E-\$1F	File size in sectors, low/high byte order (\$1E+\$1F*256). The approx. filesize in bytes is $\leq \#sectors * 254$

The file type field is used as follows:

Bits	Description
0-3	The actual file type
4	Unused
5	Used only during SAVE- replacement
6	Locked flag (Set produces ">" locked files)
7	Closed flag (Not set produces "*", or "splat" files)

The actual file type can be one of the following:

Binary	Decimal	File type
0000	0	DEL
0001	1	SEQ
0010	2	PRG
0011	3	USR
0100	4	REL

Values 5-15 are illegal, but if used will produce very strange results. The 1571 is inconsistent in how it treats these bits. Some routines use all 4 bits, others ignore bit 3, resulting in values from 0-7.

When the 1571 is in is native ("1571") mode, files are stored with a sector interleave of 6, rather than 10 which the 1541 (and the 1571 in "1541" mode) uses. The directory still uses an interleave of 3.

### \*\*\* Non-Standard & Long Directories

Most Commodore floppy disk drives use a single dedicated directory track where all filenames are stored. This limits the number of files stored on a disk based on the number

of sectors on the directory track. There are some disk images that contain more files than would normally be allowed. This requires extending the directory off the default directory track by changing the last directory sector pointer to a new track, allocating the new sectors in the BAM, and manually placing (or moving existing) file entries there. The directory of an extended disk can be read and the files that reside there can be loaded without problems on a real drive. However, this is still a very dangerous practice as writing to the extended portion of the directory will cause directory corruption in the non-extended part. Many of the floppy drives core ROM routines ignore the track value that the directory is on and assume the default directory track for operations.

To explain: assume that the directory has been extended from track 18 to track 19/6 and that the directory is full except for a few slots on 19/6. When saving a new file, the drive DOS will find an empty file slot at 19/6 offset \$40 and correctly write the filename and a few other things into this slot. When the file is done being saved the final file information will be written to 18/6 offset \$40 instead of 19/6 causing some directory corruption to the entry at 18/6. Also, the BAM entries for the sectors occupied by the new file will not be saved and the new file will be left as a SPLAT (\*) file.

Attempts to validate the disk will result in those files residing off the directory track to not be allocated in the BAM, and could also send the drive into an endless loop. The default directory track is assumed for all sector reads when validating so if the directory goes to 19/6, then the validate code will read 18/6 instead. If 18/6 is part of the normal directory chain then the validate routine will loop endlessly.

\*\*\* Bam layout The BAM is somewhat different as it now has to take 35 new tracks into account. In order to do this, most of the extra BAM information is stored on track 53/0, and the remaining sectors on track 53 are marked in the BAM as allocated. This does mean that except for one allocated sector on track 53, the rest of the track is unused and wasted. (Track 53 is the equivalent to track 18, but on the flip side of the disk). Here is a dump of the first BAM sector...

```

00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
-----
00: 12 01 41 80 12 FF F9 17 15 FF FF 1F 15 FF FF 1F
10: 15 FF FF 1F 15 FF FF 1F 15 FF FF 1F 15 FF FF 1F
20: 15 FF FF 1F 15 FF FF 1F 15 FF FF 1F 15 FF FF 1F
30: 15 FF FF 1F 15 FF FF 1F 15 FF FF 1F 15 FF FF 1F
40: 15 FF FF 1F 15 FF FF 1F 11 FC FF 07 13 FF FF 07
50: 13 FF FF 07 13 FF FF 07 13 FF FF 07 13 FF FF 07
60: 13 FF FF 07 12 FF FF 03 12 FF FF 03 12 FF FF 03
70: 12 FF FF 03 12 FF FF 03 12 FF FF 03 11 FF FF 01
80: 11 FF FF 01 11 FF FF 01 11 FF FF 01 11 FF FF 01
90: A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0 A0
A0: A0 A0 30 30 A0 32 41 A0 A0 A0 A0 00 00 00 00
B0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
C0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
D0: 00 00 00 00 00 00 00 00 00 00 00 00 00 15 15 15
E0: 15 15 15 15 15 15 15 15 15 15 15 15 15 00 13
F0: 13 13 13 13 13 12 12 12 12 12 12 11 11 11 11

```

Bytes

Description

\$00-\$01	Track/Sector location of the first directory sector (should be set to 18/1 but it doesn't matter, and don't trust what is there, always go to 18/1 for first directory entry)
\$02	Disk DOS version type (see note below) \$41 ('A') = 1541
\$03	Double-sided flag \$00 - Single sided disk \$80 - Double sided disk
\$04-8F	BAM entries for each track, in groups of four bytes per track, starting on track 1.
\$90-\$9F	Disk Name (padded with \$A0)
\$A0-\$A1	Filled with \$A0
\$A2-\$A3	Disk ID
\$A4	Usually \$A0
\$A5-\$A6	DOS type, usually "2A"
\$A7-\$AA	Filled with \$A0
\$AB-\$DC	Not used (\$00's)
\$DD-\$FF	Free sector count for tracks 36-70 (1 byte/track).

The "free sector" entries for tracks 36-70 are likely included here in the first BAM sector due to some memory restrictions in the 1571 drive. There is only enough memory available for one BAM sector, but in order to generate the "blocks free" value at the end of a directory listing, the drive needs to know the extra track "free sector" values. It does make working with the BAM a little more difficult, though.

These are the values that would normally be with the 4-byte BAM entry, but the rest of the entry is contained on 53/0.

Note: If the DOS version byte is set to anything other than \$41 or \$00, then we have what is called "soft write protection". Any attempt to write to the disk will return the "DOS Version" error code 73. The 1571 is simply telling you that it thinks the disk format version is incorrect.

The BAM entries require some explanation. Take the first entry at bytes \$04-\$07 (\$12 \$FF \$F9 \$17). The first byte (\$12) is the number of free sectors on that track. Since we are looking at the track 1 entry, this means it has 18 (decimal) free sectors.

The next three bytes represent the bitmap of which sectors are used/free. Since it is 3 bytes (8 bits/byte) we have 24 bits of storage. Remember that at most, each track only has 21 sectors, so there are a few unused bits. These entries must be viewed in binary to make any sense. We will use the first entry (track 1) at bytes 04-07:

FF=11111111, F9=11111001, 17=00010111

In order to make any sense from the binary notation, flip the bits around.

```

      111111 11112222
01234567 89012345 67890123
-----
11111111 10011111 11101000
^               ^
sector 0       sector 20
```

Since we are on the first track, we have 21 sectors, and only use up to the bit 20 position. If a bit is on (1), the sector is free. Therefore, track 1 has sectors 9,10 and 19 used, all the rest are free.

In order to complete the BAM, we must check 53/0.

```

      00 01 02 03 04 05 06 07 08 09 0A 0B 0C 0D 0E 0F
      -----
00: FF FF 1F FF FF 1F FF FF 1F FF FF 1F FF FF 1F FF
10: FF 1F FF FF 1F FF FF 1F FF FF 1F FF FF 1F FF FF
20: 1F FF FF 1F FF FF 1F FF FF 1F FF FF 1F FF FF 1F
30: FF FF 1F 00 00 00 FF FF 07 FF FF 07 FF FF 07 FF
40: FF 07 FF FF 07 FF FF 07 FF FF 03 FF FF 03 FF FF
50: 03 FF FF 03 FF FF 03 FF FF 03 FF FF 01 FF FF 01
60: FF FF 01 FF FF 01 FF FF 01 00 00 00 00 00 00 00
70: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
80: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
90: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
A0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
B0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
C0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
D0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
E0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00
F0: 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00 00

```

Each track from 36-70 has 3 byte entries, starting at address \$00.

```

Byte: $00-$02: $FF $FF $1F - BAM map for track 36
      $03-$05: $FF $FF $1F - BAM map for track 37
      ...
      $33-$35: $00 $00 $00 - BAM map for track 53
      ...
      $66-$68: $FF $FF $01 - BAM map for track 70
      $69-$FF:                - Not used

```

You can break down the entries for tracks 36-70 the same way as track 1, just combine the free sector bytes from 18/0 and the BAM usage from 53 to get the full 4-byte entry.

Just like a D64, you can attach error bytes to the file, for sector error information. This block is 1366 bytes long, 1 byte for each of the 1366 sectors in the image. With the error bytes, the file size is 351062 bytes.

## 16 Acknowledgments

VICE derives from X64, the first Commodore 64 emulator for the X Window System. Here is an informal list of the people who were mostly involved in the development of X64 and VICE:

The VICE core team:

- **Dag Lem** Implemented the reSID SID emulation engine and video hardware scaling.

- **Andreas Matthies** Improved the datasette support, the VIC20 video emulation and some UI stuff in the Win32 and DOS ports. He also wrote the BeOS port and implemented video/audio capture support. Improved history recording/playback and implemented support for video recording and the netlink feature. Made the Win32 user changable keyboard shortcut system. Improved CIA and VIA emulation. Worked on x64sc, especially interrupt timing. Wrote test programs. Various bug(fixe)s. ;-)
- **Martin Pottendorfer** Implemented the Gnome Port based on Oliver Schaertels GTK+ port. Added support code for internationalization based on gettext. Improved the \*nix fullscreen support. Translated the UI to German. Implemented the fliplists + UI (\*nix).
- **Spiro Trikaliotis** Wrote the Win32 console implementation for the built-in monitor, corrected some REU related bugs, improved the CIA emulation, added com-port CIA support to the Win32 port, added text copy and paste support to the Win32 port, added support for the TFE and RR-Net (cs8900a), and wrote some further patches.
- **Marco van den Heuvel** Translated the UI to Dutch. Made the internationalization support for the Win32 and Amiga ports. Wrote the GEO-RAM and RamCart cartridge code. Wrote the c64 +60K, +256K and 256K memory expansions code. Wrote the pet REU code. Wrote the plus4 memory expansions code. Made the ethernet support for the DOS port. Maintains the QNX 4.x, QNX 6.x, Solaris, Openserver, Unixware, Minix 3.x, Amiga, BeOS, Syllable and OS/2 binary ports. Maintains the Win64 and Watcom project files. Maintains the SDL port(s). Added new .crt support. Added new screenshot formats. Added new sound recording support. Added SIDcart support for xpet, xplus4 and xvic. Improved the MMC64 emulation. Added 2 MHz mode and banks 2/3 support for x128. Added the various userport joystick emulations. Added text copy and paste support to the Amiga and BeOS ports. Added DQBB and ISEPIC cartridge support. Added SFX Sound Sampler and SFX Sound Expander support. Added digiblaster support. And lots of other fixes and improvements.
- **Christian Vogelgsang** Maintains the Mac OS X port. Added Intel Mac support and universal binary creation. Wrote the build scripts for all external Mac libraries and the bindist bundle tool. Improved the TFE chip emulation. Added some GTK+ fixes.
- **Fabrizio Gennari** Added some improvements to the DOS and GTK+ ports.
- **Daniel Kahlin** Worked on DTV VIC emulation, palette, DTV SID support in resid, better DMA/Blitter support and did lots of refactoring. Added new monitor commands and features. Improved the VIC emulation for xvic. Made MIDI driver code for Win32. Rewrote the xvic cartridge system. Added Mega-Cart and Final Expansion V3.2 support to xvic. Wrote large parts of the new VIC-II emulation used in x64sc, especially the dot clock domain emulation. Wrote many test programs for hardware analysis.
- **Antti S. Lankila** Made the ReSID-fp engine, rewrote the PAL emulation code and fixed the sound core for lower latency. Rewrote DTV SID support (ReSID-dtv). Improved 1541 drive rotation emulation. Worked on x64sc.
- **Groepaz/Hitmen** Added new more precise CRT emulation. Added support for the new cartridge system and many new cartridges. Fixed up parts of cartconv. Implemented many bug fixes. Wrote test programs.



- **Ingo Korb** Corrected block allocation and interleave for c1541/vdrive, added rudimentary xplus4 tape recording support, corrected a case of missing Pi symbols in petcat, changed the trap opcode byte, stopped the high-level serial drive code from responding to addresses 16-30 and was forced to update this entry himself.
- **Errol Smith** Improved VDC emulation.
- **Olaf Seibert** Contributed some PET, including PET DWW hires, Xaw, lightpen, hardware scaling, and disk drive patches. Maintains the Xaw UI.
- **Stefan Haubenthal** Added some Amiga fixes.
- **Thomas Giesel** Added new monitor commands and features.
- **Marcus Sutton** Made some console, dialog and joystick fixes for the BeOS port.
- **Ulrich Schulz** Maintains the Dingoo port(s).

Former/inactive team members:

- **Hannu Nuotio** Copyright © 2007-2011 Implemented DTV flash emulation, DTV support in the monitor, large parts of the DTV VIC, burst mode and skip cycle emulation as well as many other things. Added NEOS and Amiga mouse, paddle and light pen support. Added new monitor commands and features, including memmap. Made MIDI support and OSS MIDI driver. Implemented most of the SDL UI. Rewrote xvix CPU/VIC-I core for cycle based emulation. Implemented C64 cartridge snapshot support. Initiated and worked on all parts of implementing x64sc. Wrote test programs.
- **Andreas Boose** Copyright © 1998-2010 Gave lots of information and bug reports about the VIC-II, the 6510 and the CIAs; moreover, he wrote several test-routines that were used to improve the emulation. He also added cartridge support and has been the main head behind the drive and datasette emulation since version 0.15. Also added several UI elements to the DOS, Win32 and \*nix ports. He rewrote the C128 emulation adding Z80 mode, C64 mode and function ROM support, wrote the screenshot and the event system and started the plus4 emulator. Restructured the serial bus emulation and added realdrive and rawdrive support.
- **Tibor Biczo** Copyright © 1998-2010 Improved the Win32 port and plus4 emulation.
- **M. Kiesel** Copyright © 2007-2010 Started implementing x64dtv. The C64DTV memory model and early versions of the DMA and Blitter engine have been implemented by him. Added new monitor commands and features.
- **Andreas Dehmel** Copyright © 1999-2007 Wrote the Acorn RISC OS port.
- **David Hansel** Copyright © 2003-2005 Wrote the Star NL10 printer driver, implemented IEC devices and improved the tape emulation.
- **Markus Brenner** Copyright © 2000-2004 Added VDC emulation to x128 and added support for some more cartridges.
- **Thomas Bretz** Copyright © 1999-2004 Started the OS/2 port.
- **Daniel Sladic** Copyright © 1997-2001 Started the work on hardware-level 1541 emulation and wrote the new monitor introduced with VICE 0.15.
- **Andr Fachat** Copyright © 1996-2001 Wrote the PET and CBM-II emulators, the CIA and VIA emulation, the IEEE488 interface, implemented the IEC serial bus in 'xvix' and made tons of bug fixes.

- **Ettore Perazzoli** Copyright © 1996-1999 Made the 6510, VIC-II, VIC-I and CRTC emulations, part of the hardware-level 1541 emulation, speed optimizations, bug fixes, the event-driven cycle-exact engine, the Xt/Xaw/Xfwf-based GUI for X11, a general code reorganization, the new resource handling, most of the documentation. He also wrote the DOS port and the initial Win32 port (well, somebody had to do it).
- **Teemu Rantanen** Copyright © 1993-1994, 1997-1999 Implemented the SID emulation and the trap-based disk drive and serial bus implementation; added support for multiple display depths under X11. Also wrote `c1541`
- **Jouko Valta** Copyright © 1993-1996 Wrote `petcat` and `c1541`, T64 handling, user service and maintenance (most of the work in x64 0.3.x was made by him); retired from the project in July 96, after VICE 0.10.0.
- **Jarkko Somminen** Copyright © 1993-1994 He was the founder of the project, wrote the old version of the 6502 emulation and the XDebugger, and retired from the project after x64 0.2.1.

Internationalization Team:

- **Mikkel Holm Olsen** Provided the Danish user interface translations and fixed a few monitor bugs.
- Paul Dub** From Rivire-du-Loup, Qubec, provided the French user interface translations.
- Czirkos Zoltan** and **Karai Csaba** Provided the Hungarian user interface translations.
- Andrea Musuruane** Provided the Italian user interface translations.
- Jesse Lee** Provided the Korean user interface translations.
- Michael Litvinov** Provided the Russian user interface translations.
- Peter Krefting** Provided the Swedish user interface translations.
- Emir Akaydin** Provided the Turkish user interface translations (in world record time).

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- **ck!** Provided a win32 cbm character font.
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- **Mike Dawson** Provided the GP2X port.
- **Paul David Doherty** Wrote `zip2disk`, on which the Zipcode support in `c1541` is based.
- **Peter Edwards** Implemented the SDL UI slider control and fixed some GP2X/Dingoo SDL UI issues.
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- **Mathias Roslund** Provided the AmigaOS4 port.
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- **Johan Samuelsson** Provided the Swedish Amiga translations.
- **Oliver Schaertel** Wrote the X11 full screen, parts of custom ROM set support and 1351 mouse emulation for unix.
- **Peter Schepers** Contributed a document describing the G64 image format.
- **Michael Schwendt** Helped with the SID (audio) chip emulation, bringing important suggestions and bug reports, as well as the wave tables and filter emulation from his SIDplay emulator.
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- **Robert Willie** Added some additional commands to the fsdevice emulation.
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(We hope we have not forgotten anybody; if you think we have, please tell us.)

The people around the world providing results from running our test programs on various machines deserve a special mention:

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## 17 Copyright

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## 18 Contact information

### 18.1 VICE home page

You can find the latest news about VICE at the official VICE home page:

<http://vice-emu.sourceforge.net/>

VICE has moved its source repository to public services provided by SourceForge. You can find it at

<http://sf.net/projects/vice-emu>.

We would like to thank the SourceForge staff for that help.

If you are going to report a bug, please check those pages *first*; it is possible that the problem you encountered has already been fixed with a newer version.

Please, also have a look at the VICE knowledge base at

<http://vicekb.trikaliotis.net/>

### 18.2 How to send feedback

Before contacting us, have a look at the VICE knowledge base at <http://vicekb.trikaliotis.net/> if your question is answered there. Keep in mind that we work on VICE in our spare-time, so the more time we don't need to answer the same questions over and over again, the more time we have to improve the emulation itself. On the other hand, that does not mean that you should not contact us, especially if you find bugs or have suggestions which might improve the emulation.

Bug reports, suggestions, support requests should be directed to the SourceForge trackers at

- [http://sourceforge.net/tracker/?group\\_id=223021](http://sourceforge.net/tracker/?group_id=223021).

This way, you, the users, and we, the developers, can track what has been reported and what has been already fixed. Ideally, also sent the report to the mailing address of the Vice team at

- VICE Mailing List ([vice-emu-mail@lists.sourceforge.net](mailto:vice-emu-mail@lists.sourceforge.net)) for all general questions, bug reports, suggestions.

You can also contact (some of) us on IRC, at #vice-dev on freenode.

It's always nice to receive feedback and/or bugreports about VICE, but please read these few notes before sending mail to anybody in the team.

- Please put the word 'VICE' *in all capitals* in your subject line (e.g., 'VICE fails to run game XXX'). This helps mail splitting and reduces chances that your message is unintentionally deleted, forgotten or lost.
- Please don't send any HTML mail (we really hate that!). If you use M\$ Outlook or Netscape Communicator, make sure you turn off the "rich text" (HTML) feature.
- Please don't send *any* binaries without asking first.
- Please read the following documents carefully before reporting a bug or a problem you cannot solve:

- the VICE documentation (you are reading it!);
- the VICE FAQ (it is available on the Internet, and reachable from the VICE home page: <http://vice-emu.sourceforge.net/>);
- The VICE knowledge base (it is available on the Internet at <http://vicekb.trikaliotis.net/>);
- the `comp.emulators.cbm` and `comp.sys.cbm` FAQs (see [Section 18.5 \[FAQs you should read\]](#), page 151).
- When you report a bug, please try to be as accurate as possible and describe how it can be reproduced to the very detail. You should also tell us what machine you are running on, what operating system you are using as well as the version of it.
- Please don't ask us how to transfer original C64 disk or tapes to your PC; this has been asked a gazillion times through email. To transfer disks, you can use the Star Commander (<http://sta.c64.org/sc.html>) on DOS, and OpenCBM (<http://www.trikaliotis.net/opencbm>) on Windows and Linux. And no, you cannot read C64 disks with your old 5"1/4 PC drive.
- Please don't ask us where to find games for the emulator on the Internet.
- Please don't ask us when the next version will be out, because we really don't know.
- Please write in English.

In any case, we would be *really* glad to receive your comments about VICE. We cannot always answer all the email, but we surely read all of it.

Thanks!

## 18.3 How to contribute

If you want to make a major contribution, please *ask* first. It has already happened a couple of times that somebody started working at something that had already been done but not released to the public yet, and we really do *not* want anybody to waste time.

If you are going to make a patch, please make sure the patch is relative to the very latest version, and provide us with the following:

- Make sure you are giving us a diff against the latest Subversion trunk version of VICE. For instructions on accessing the Subversion repository, first read [http://sourceforge.net/svn/?group\\_id=223021](http://sourceforge.net/svn/?group_id=223021) and get it with the command:  

```
'svn co https://vice-emu.svn.sourceforge.net/svnroot/vice-emu/trunk vice-src'
```
- send a unified diff file against the trunk version of VICE (see above bullet point) by using the command: `'svn diff'` inside of the SVN workspace you checked out before.
- If you cannot use SVN for one or the other reason, send a unified diff file containing all the changes you have made `'diff -u'`; please don't use plain `'diff'`, as it adds much work for us to get it working;
- GNU-style `'ChangeLog'` entries with a description of the changes you have made (look at the `'ChangeLog'`s provided with the original VICE sources for an example).

This is very important, and makes adding patches much smoother and safer.

People willing to port VICE to other platforms are always welcome. But notice from experience it will take at least a full year of continuous work to write a well working and stable port.



## 18.4 Interesting newsgroups

There are some Usenet newsgroups you might be interested in:

- `comp.emulators.cbm`, discussing about emulators of Commodore 8-bit machines (definitely not Amiga emulators).
- `comp.sys.cbm`, discussing various topics regarding real Commodore 8-bit machines. This newsgroup is mainly for people who actually use original Commodore equipment (so please don't talk about emulation here).
- `comp.emulators.misc`, discussing emulators in general.

## 18.5 FAQs you should read

We recommend reading the `comp.emulators.cbm` and `comp.sys.cbm` FAQs, which are posted regularly on the corresponding newsgroups and are also available via FTP from <ftp://rtfm.mit.edu>.

# Concept Index

<b>+</b>		
+cart	52	
<b>-</b>		
-?	14	
-1	15	
-10	15	
-11	15	
-256k, +256k	66	
-256kbase	66	
-256kimage	66	
-40col	69	
-8	15	
-80col	69	
-9	15	
-acial, +acial	64	
-attach10ro	15	
-attach10rw	15	
-attach11ro	15	
-attach11rw	15	
-attach8ro	15	
-attach8rw	15	
-attach9ro	15	
-attach9rw	15	
-autoload	15	
-autostart	15, 16	
-autostart-handle-tde, +autostart-handle-tde	15	
-autostart-warp, +autostart-warp	15	
-autostartprgdiskimage	15	
-autostartprgmode	15	
-autostartwithcolon, +autostartwithcolon	15	
-basic	66, 76, 85	
-basic1, +basic1	82	
-basic1char, +basic1char	83	
-basic64	68	
-basichi	68	
-basiclo	68	
-basicload, +basicload	15	
-bdesymkeymap, -bdeposkeymap	30	
-brightness	60, 67, 74, 77, 81	
-bksymkeymap, -bukposkeymap	30	
-c	117	
-c1hi	78	
-c1lo	78	
-c2hi	78	
-c2lo	78	
-c64dtvromimage	70	
-c64dtvromrw, +c64dtvromrw	70	
-cart1	85	
-cart16	52	
-cart2	72, 76, 85	
-cart4	72, 76, 85	
-cart6	72, 76, 85	
-cart8	52	
-cartA	72, 76	
-cartap	52	
-cartar2	52	
-cartar3	52	
-cartar4	52	
-cartar5	53	
-cartB	72, 76	
-cartcap	53	
-cartcomal	53	
-cartert	52	
-cartdep256	53	
-cartdep64	53	
-cartdep7x8	53	

-cartdin .....	53	-cia1model .....	58
-cartdqbb .....	53	-cia2model .....	58
-cartdsm .....	53	-ciamodel .....	58
-carteasy .....	53	-config .....	14
-cartepyx .....	53	-confirmexit, +confirmexit .....	46
-cartexos .....	53	-console .....	15
-cartexpert .....	53	-contrast .....	60, 67, 74, 77, 81
-cartfc1 .....	54	-core, +core .....	46
-cartfc3 .....	54	-crtblur .....	60, 68, 74, 78, 82
-cartfcplus .....	54	-Crtcdscan, +Crtcdscan .....	81
-cartfe .....	72	-Crtcdsize, +Crtcdsize .....	81
-cartff .....	54	-Crtcextpal .....	81
-cartfm .....	54	-Crtcfulldevice .....	81
-cartfp .....	54, 72	-Crtchwscale, +Crtchwscale .....	81
-cartgeneric .....	72	-Crtcintpal .....	81
-cartgeoram .....	64	-Crtcpalette .....	81
-cartgk .....	54	-Crtcscale2x, +Crtcscale2x .....	81
-cartgs .....	54	-Crtcvcache, +Crtcvcache .....	81
-cartide64 .....	54	-CrtcVidmodefullmode .....	81
-cartieee .....	55	-CrtcXRANDRfullmode .....	81
-cartisepic .....	55	-crtscanlineshade .....	60, 68, 74, 78, 82
-cartkcs .....	55	-cs256k .....	79
-cartks .....	55	-default .....	14
-cartmach5 .....	55	-device10 .....	39
-cartmd .....	55	-device11 .....	39
-cartmega .....	72	-device4 .....	40
-cartmf .....	55	-device5 .....	40
-cartmikro .....	55	-device8 .....	39
-cartmmc64 .....	55	-device9 .....	39
-cartmmcr .....	56	-diagpin, +diagpin .....	83
-cartmv .....	56	-digiblaster, +digiblaster .....	78
-cartocean .....	56	-digimax, +digimax .....	64
-cartp64 .....	56	-digimaxbase .....	64
-cartpf .....	56	-directory .....	46
-cartramcart .....	56	-displaydepth .....	29
-cartrep256 .....	57	-doodlecrtctextcolor .....	101
-cartreset, +cartreset .....	52	-doodlemc .....	101
-cartreu .....	64	-doodleoversize .....	101
-cartross .....	57	-doodletedlum .....	101
-cartrr .....	57	-dos1001 .....	36
-cartru .....	57	-dos1541 .....	36
-carts64 .....	57	-dos1541II .....	36
-cartsb .....	57	-dos1551 .....	36
-cartse5 .....	57	-dos1570 .....	36
-cartsg .....	57	-dos1571 .....	36
-cartsimon .....	57	-dos1571cr .....	36
-cartss4 .....	57	-dos1581 .....	36
-cartss5 .....	57	-dos2031 .....	36
-cartstar .....	57	-dos2040 .....	36
-cartultimax .....	52	-dos3040 .....	36
-cartwl .....	57	-dos4040 .....	36
-cartws .....	58	-dqbb, +dqbb .....	53
-cartzaxxon .....	58	-dqbbimage .....	53
-chargde .....	68	-dqbbimagerw, +dqbbimagerw .....	53
-chargen .....	66, 68, 76, 82, 85	-drive10extend .....	36
-chargfr .....	69	-drive10idle .....	36
-chargse .....	69	-drive10profdos, +drive10profdos .....	37
-chdir .....	15	-drive10ram2000, +drive10ram2000 .....	36

-drive10ram4000, +drive10ram4000	36	-fs8	39
-drive10ram6000, +drive10ram6000	36	-fs9	39
-drive10ram8000, +drive10ram8000	37	-fsflash	70
-drive10rama000, +drive10rama000	37	-fullscreen, +fullscreen	29
-drive10type	35	-functionhi	78
-drive11extend	36	-functionlo	78
-drive11idle	36	-gamma	60, 67, 74, 77, 82
-drive11profdos, +drive11profdos	37	-georam, +georam	64
-drive11ram2000, +drive11ram2000	36	-georamimage	64
-drive11ram4000, +drive11ram4000	36	-georamimagerw, +georamimagerw	64
-drive11ram6000, +drive11ram6000	36	-georamsize	64
-drive11ram8000, +drive11ram8000	37	-gluelogictype	66
-drive11rama000, +drive11rama000	37	-go64, +go64	69
-drive11type	35	-grsymkeymap, -grposkeymap	30
-drive8extend	36	-h	117
-drive8idle	36	-h1024k	79
-drive8profdos, +drive8profdos	37	-h256k	79
-drive8ram2000, +drive8ram2000	36	-h4096k	79
-drive8ram4000, +drive8ram4000	36	-help	14, 117
-drive8ram6000, +drive8ram6000	36	-htmlbrowser	46
-drive8ram8000, +drive8ram8000	37	-hummeradc, +hummeradc	70
-drive8rama000, +drive8rama000	37	-i	114
-drive8type	35	-ic	117
-drive9extend	36	-IDE64autosize, +IDE64autosize	55
-drive9idle	36	-IDE64cyl	54
-drive9profdos, +drive9profdos	37	-IDE64hds	54
-drive9ram2000, +drive9ram2000	36	-IDE64image1	54
-drive9ram4000, +drive9ram4000	36	-IDE64image2	54
-drive9ram6000, +drive9ram6000	36	-IDE64image3	54
-drive9ram8000, +drive9ram8000	37	-IDE64image4	54
-drive9rama000, +drive9rama000	37	-IDE64sec	54
-drive9type	35	-IDE64version4, +IDE64version4	55
-dsresetwithcpu, +dsresetwithcpu	33	-iecdevice10, +iecdevice10	38
-dsspeedtuning	33	-iecdevice11, +iecdevice11	38
-dszerogapdelay	33	-iecdevice4, +iecdevice4	40
-dtvblitterlog, +dtvblitterlog	71	-iecdevice5, +iecdevice5	40
-dtvdmalog, +dtvdmalog	71	-iecdevice8, +iecdevice8	38
-dtvflashlog, +dtvflashlog	71	-iecdevice9, +iecdevice9	38
-dtvrev	70	-ieee488, +ieee488	55, 73
-easyflashcrtwrite, +easyflashcrtwrite	53	-ieee488image	55
-easyflashjumper, +easyflashjumper	53	-initbreak	44
-editor	82	-install, +install	29
-eoiblack, +eoiblack	83	-intfrom	69
-expert, +expert	54	-intfunc, +intfunc	69
-expertimagename	54	-isepic, +isepic	55
-expertimagerw, +expertimagerw	54	-isepicimagename	55
-extfrom	69	-isepicimagerw, +isepicimagerw	55
-extfunc, +extfunc	69	-joydev1	30
-extrajoydev1	30	-joydev2	30
-extrajoydev2	30	-k	117
-f	114, 117	-k<version>	117
-fewwriteback, +fewwriteback	72	-keepenv	86
-ffmpegaudiobitrate	101	-kernal	66, 68, 76, 82, 84
-ffmpegvideobitrate	102	-kernal64	68
-flipname	39	-kernalde	68
-fpwriteback, +fpwriteback	72	-kernalfi	68
-fs10	39	-kernalfr	68
-fs11	39	-kernalit	68

-kernalno .....	68	-petreu, +petreu .....	83
-kernalrev .....	66	-petreuimage .....	83
-kernalse .....	68	-petreuramsize .....	83
-keybuf .....	15	-playback .....	102
-keymap .....	30	-plus256k, +plus256k .....	66
-l .....	114, 117	-plus256kimage .....	66
-lightpen, +lightpen .....	31	-plus60k, +plus60k .....	66
-lightpentype .....	31	-plus60kbase .....	66
-logfile .....	15	-plus60kimage .....	66
-mcnvramfile .....	72	-poskeymap .....	30
-mcnvramwriteback, +mcnvramwriteback .....	72	-pr4drv .....	41
-memory .....	75	-pr4output .....	40
-midi, +midi .....	64	-pr4txtdev .....	40
-mididrv .....	64	-pr5drv .....	41
-midiin .....	64	-pr5output .....	40
-midiout .....	64	-pr5txtdev .....	40
-miditype .....	64	-profdos1571 .....	37
-mitshm, +mitshm .....	13, 29	-prtxtdev1 .....	40
-mmc64, +mmc64 .....	55	-prtxtdev2 .....	40
-mmc64bios .....	55	-prtxtdev3 .....	40
-mmc64bioswrite .....	56	-pruser, +pruser .....	41
-mmc64image .....	56	-pruserdrv .....	41
-mmc64readonly .....	56	-pruseroutput .....	41
-mmc64readwrite .....	56	-prusertxtdev .....	41
-mmccardimage .....	56	-ps2mouse, +ps2mouse .....	70
-mmccardrw, +mmccardrw .....	56	-r .....	114
-mmcreepromimage .....	56	-ram08, +ram08 .....	85
-mmcreepromrw, +mmcreepromrw .....	56	-ram1, +ram1 .....	85
-mmcrimagerw, +mmcrimagerw .....	56	-ram2, +ram2 .....	85
-mmcrrescue, +mmcrrescue .....	56	-ram4, +ram4 .....	85
-model .....	82	-ram6, +ram6 .....	85
-modelline .....	85	-ramC, +ramC .....	85
-moncommands .....	44	-ramcart, +ramcart .....	56
-mouse, +mouse .....	31	-ramcartimage .....	57
-mouseport .....	31	-ramcartimagerw, +ramcartimagerw .....	57
-mousetype .....	31	-ramcartsize .....	56
-myaciadev .....	43	-raminitpatterninvert .....	45
-n .....	114	-raminitstartvalue .....	45
-nc .....	117	-raminitvalueinvert .....	45
-newluminance, +newluminance .....	60	-ramsize .....	79, 84
-nh .....	117	-refresh .....	27
-ntsc .....	45	-remotemonitor, +remotemonitor .....	44
-ntscold .....	45	-remotemonitoraddress .....	44
-o .....	114	-residfilterbias .....	62
-o <name> .....	117	-residgain .....	62
-oddlinesoffset .....	60, 68, 74, 77, 82	-residpass .....	62
-oddlinesphase .....	60, 68, 74, 77, 82	-residsamp .....	62
-OEMjoy, +OEMjoy .....	76	-reu, +reu .....	64
-pal .....	45	-reuimage .....	64
-paln .....	45	-reuimagerw, +reuimagerw .....	65
-parallel10 .....	35	-resize .....	65
-parallel11 .....	35	-rom9 .....	82
-parallel8 .....	35	-romA .....	82
-parallel9 .....	35	-romB .....	82
-petdww, +petdww .....	83	-rrbankjumper, +rrbankjumper .....	57
-petdwwimage .....	83	-rrbioswrite, +rrbioswrite .....	57
-petram9, +petram9 .....	82	-rrflashjumper, +rrflashjumper .....	57
-petramA, +petramA .....	82	-rsdev1 .....	43

-rsdev1baud .....	43
-rsdev2 .....	43
-rsdev2baud .....	43
-rsdev3 .....	43
-rsdev3baud .....	43
-rsdev4 .....	43
-rsdev4baud .....	43
-rsuser, +rsuser .....	43
-rsuserbaud .....	43
-rsuserdev .....	43
-saturation .....	60, 67, 74, 77, 81
-saveres, +saveres .....	46
-sfxse, +sfxse .....	65
-sfxsetype .....	65
-sfxss, +sfxss .....	65
-sidcart, +sidcart .....	73, 78, 83
-sidcartjoy, +sidcartjoy .....	78
-sidenginemodel .....	62
-sidfilters, +sidfilters .....	62
-sidstereo .....	62
-sidstereoaddress .....	62
-skip <n> .....	117
-sound, +sound .....	33
-soundarg .....	33
-soundbufsize .....	33
-sounddev .....	33
-soundfragsize .....	33
-soundrate .....	33
-soundrecarg .....	33
-soundrecdev .....	33
-soundsync .....	33
-speech, +speech .....	78
-speechrom .....	78
-speed .....	27
-superpet, +superpet .....	82
-symdekeymap .....	30
-symkeymap .....	30
-t .....	114
-TEDdscan, +TEDdscan .....	77
-TEDdsize, +TEDdsize .....	77
-TEDextpal .....	77
-TEDfulldevice .....	77
-TEDhwscale, +TEDhwscale .....	77
-TEDintpal .....	77
-TEDpalette .....	77
-TEDscale2x, +TEDscale2x .....	77
-TEDvcache, +TEDvcache .....	77
-TEDVidmodefullmode .....	77
-TEDXRANDRfullmode .....	77
-text .....	117
-tfe, +tfe .....	65
-tfeif .....	65
-tfernet, +tfernet .....	65
-tint .....	60, 68, 74, 77, 82
-truedrive, +truedrive .....	35
-trueflashfs, +trueflashfs .....	70
-tune <number> .....	86
-userportdac, +userportdac .....	83
-usevicii, +usevicii .....	84
-v .....	117
-VDC16KB .....	67
-VDC64KB .....	67
-VDCdscan, +VDCdscan .....	67
-VDCdsize, +VDCdsize .....	67
-VDCextpal .....	67
-VDCfulldevice .....	67
-VDChwscale, +VDChwscale .....	67
-VDCintpal .....	67
-VDCpalette .....	67
-VDCRevision .....	67
-VDCvcache, +VDCvcache .....	67
-VDCVidmodefullmode .....	67
-VDCXRANDRfullmode .....	67
-verbose .....	15
-VICdscan, +VICdscan .....	73
-VICdsize, +VICdsize .....	73
-VICextpal .....	73
-VICfulldevice .....	74
-VICHwscale, +VICHwscale .....	73
-VICHborders .....	60
-VICHchecksb, +VICHchecksb .....	59
-VICHcheckss, +VICHcheckss .....	59
-VICHdscan, +VICHdscan .....	59
-VICHdsize, +VICHdsize .....	59
-VICHextpal .....	59
-VICHfulldevice .....	60
-VICHhwscale, +VICHhwscale .....	59
-VICHintpal .....	59
-VICHmodel .....	60
-VICHpalette .....	60
-VICHscale2x, +VICHscale2x .....	59
-VICHvcache, +VICHvcache .....	59
-VICHVidmodefullmode .....	60
-VICHXRANDRfullmode .....	60
-VICintpal .....	73
-VICpalette .....	73
-VICscale2x, +VICscale2x .....	73
-VICvcache, +VICvcache .....	73
-VICVidmodefullmode .....	74
-VICXRANDRfullmode .....	74
-virtualdev, +virtualdev .....	41
-vsid .....	86
-w<version> .....	117
-warp, +warp .....	27
-xsync, +xsync .....	29
<b>A</b>	
ACIA (Swiftlink, Turbo232) .....	63
Audio buffer size .....	31
<b>C</b>	
Converting X64 files into D64 .....	12

**D**

DigiMAX.....	63
Double-scan mode.....	28
Double-size mode.....	28

**E**

Ethernet (The Final Ethernet, RR-Net).....	63
--	----

**G**

GEO-RAM.....	63
--------------	----

**H**

HP-UX and Solaris audio problems.....	13
---------------------------------------	----

**L**

Limiting emulation speed.....	27
Loosing control on low-end systems.....	28

**M**

MIDI (Passport, Datel, Maplin, Namesoft, Sequential).....	63
MITSHM.....	13

**O**

OSS/Linux problems.....	13
Oversampling.....	31

**R**

Refresh rate.....	27
-------------------	----

**Index of Resources****A**

Acia1Dev.....	42
Acia1Enable.....	63
Acia1Irq.....	43

**B**

Basic1.....	79
Basic1Chars.....	79
BasicName.....	65, 76

**C**

Cart2Name.....	84
Cart4Name.....	84

reSID resampling passband.....	61
reSID sampling method.....	61
REU.....	63

**S**

Sample rate.....	31
Second SID.....	61
Second SID base address.....	61
SFX Sound Expander.....	63
SFX Sound Sampler.....	63
SID filters.....	61
SID models.....	61
Sound buffer size.....	31
Sound speed adjustment.....	31
Sound suspend time.....	31
Sound synchronization.....	31
Sprite collision detection.....	58

**T**

Toggling reSID emulation.....	61
Turning sound playback on/off.....	31

**U**

Using XSync().....	28
--------------------	----

**V**

VIC-II color sets.....	58
Video cache.....	28

**W**

Warp speed mode.....	27
----------------------	----

Cart6Name.....	84
CartridgeFile.....	51
CartridgeReset.....	51
CartridgeType.....	51
ChargenName.....	65, 76, 79
Crtc.....	80
CrtcDoubleScan.....	81
CrtcDoubleSize.....	80
CrtcPaletteFile.....	81
CrtcVideoCache.....	80

**D**

DiagPin.....	79
DIGIMAX.....	63

DIGIMAXbase .....	63
Directory .....	45
DisplayDepth .....	28
DoCoreDump .....	46
DosName1541 .....	35
DosName1571 .....	35
DosName1581 .....	35
DosName2031 .....	35
DQBB .....	51
DQBBfilename .....	51
DQBBImageWrite .....	51
Drive8ExtendImagePolicy .....	35
Drive8IdleMethod .....	35
Drive8ParallelCable .....	35
Drive8Type .....	35
Drive9ExtendImagePolicy .....	35
Drive9IdleMethod .....	35
Drive9ParallelCable .....	35
Drive9Type .....	35
DriveTrueEmulation .....	35

## E

EditorName .....	80
EoiBlank .....	79
ETHERNET_ACTIVE .....	63
ETHERNET_AS_RR .....	63
ETHERNET_DISABLED .....	63
ETHERNET_INTERFACE .....	63
ExpertCartridgeEnabled .....	51
ExpertCartridgeMode .....	51
Expertfilename .....	51
ExpertImageWrite .....	51

## F

FSDevice10ConvertP00 .....	38
FSDevice10Dir .....	38
FSDevice10HideCBMFiles .....	38
FSDevice10SaveP00 .....	38
FSDevice11ConvertP00 .....	38
FSDevice11Dir .....	38
FSDevice11HideCBMFiles .....	38
FSDevice11SaveP00 .....	38
FSDevice8ConvertP00 .....	38
FSDevice8Dir .....	38
FSDevice8HideCBMFiles .....	38
FSDevice8SaveP00 .....	38
FSDevice9ConvertP00 .....	38
FSDevice9Dir .....	38
FSDevice9HideCBMFiles .....	38
FSDevice9SaveP00 .....	38

## G

GenericCartridgeFile2000 .....	76
GenericCartridgeFile4000 .....	76
GenericCartridgeFile6000 .....	76

GenericCartridgeFileA000 .....	76
GenericCartridgeFileB000 .....	76
GEORAM .....	63
GEORAMfilename .....	63
GEORAMImageWrite .....	63
GEORAMsize .....	63

## H

HTMLBrowserCommand .....	45
--------------------------	----

## I

IDE64AutodetectSize .....	51
IDE64Config .....	51
IDE64Cylinders .....	51
IDE64Heads .....	51
IDE64Image1 .....	51
IDE64Image2 .....	51
IDE64Image3 .....	51
IDE64Image4 .....	51
IDE64RTCOffset .....	51
IDE64Sectors .....	51
IDE64version4 .....	51
IEEE488 .....	51
IEEE488Image .....	51
IOSize .....	79
IsepicCartridgeEnabled .....	51
Isepicfilename .....	51
IsepicImageWrite .....	51
IsepicSwitch .....	51

## J

JoyDevice1 .....	46
JoyDevice2 .....	46

## K

KernalName .....	65, 76, 79
KernalRev .....	65
KeymapBusinessDEPosFile .....	30
KeymapBusinessDESymFile .....	30
KeymapBusinessUKPosFile .....	29
KeymapBusinessUKSymFile .....	29
KeymapGraphicsPosFile .....	29
KeymapGraphicsSymFile .....	29
KeymapIndex .....	29
KeymapPosFile .....	29
KeymapSymFile .....	29

## M

MagicVoiceCartridgeEnabled .....	51
MagicVoiceImage .....	51
MIDIEnable .....	63
MIDI Mode .....	63
MITSHM .....	28

MMC64 .....	51
MMC64_bios_write .....	52
MMC64_flashjumper .....	52
MMC64_revision .....	52
MMC64_R0 .....	52
MMC64_sd_type .....	52
MMC64BIOSfilename .....	51
MMC64imagefilename .....	52
MMCRCardImage .....	52
MMCRCardRW .....	52
MMCREEPROMImage .....	52
MMCREEPROMRW .....	52
MMCRImageWrite .....	52
MMCRRescueMode .....	52
MMCRSDType .....	52
Modelline .....	84

## P

Printer4 .....	40
Printer4Driver .....	40
Printer4Output .....	40
Printer4TextDevice .....	39
Printer5 .....	40
Printer5Driver .....	40
Printer5Output .....	40
Printer5TextDevice .....	40
PrinterTextDevice1 .....	39
PrinterTextDevice2 .....	39
PrinterTextDevice3 .....	39
PrinterUserport .....	40
PrinterUserportDriver .....	40
PrinterUserportOutput .....	40
PrinterUserportTextDevice .....	40
PrivateColormap .....	28

## R

Ram08 .....	84
Ram1 .....	84
Ram2 .....	84
Ram4 .....	84
Ram6 .....	84
Ram9 .....	79
RamA .....	79
RAMBlock0 .....	75
RAMBlock1 .....	75
RAMBlock2 .....	75
RAMBlock3 .....	75
RAMBlock5 .....	75
RamC .....	84
RAMCART .....	52
RAMCART_R0 .....	52
RAMCARTfilename .....	52
RAMCARTImageWrite .....	52
RAMCARTsize .....	52
RamSize .....	79, 84
RefreshRate .....	27

REU .....	63
REUfilename .....	63
REUImageWrite .....	63
REUsize .....	63
RomModule9Name .....	80
RomModuleAName .....	80
RomModuleBName .....	80
RRBankJumper .....	52
RRBiosWrite .....	52
RRFlashJumper .....	52
RsDevice1 .....	42
RsDevice1Baud .....	42
RsDevice2 .....	42
RsDevice2Baud .....	42
RsDevice3 .....	42
RsDevice3Baud .....	42
RsDevice4 .....	42
RsDevice4Baud .....	42
RsUserBaud .....	43
RsUserDev .....	43
RsUserEnable .....	43

## S

SaveResourcesOnExit .....	46
SFXSoundExpander .....	63
SFXSoundExpanderChip .....	64
SFXSoundSampler .....	64
SidEngine .....	62
SidFilters .....	61
SidModel .....	62
SidResidPassband .....	62
SidResidSampling .....	62
SidStereo .....	61
SidStereoAddressStart .....	61
Sound .....	31
SoundBufferSize .....	32
SoundDeviceArg .....	32
SoundDeviceName .....	32
SoundSampleRate .....	32
SoundSpeedAdjustment .....	31
SoundSuspendTime .....	32
Speed .....	27
SuperPET .....	79

## U

UseVicII .....	84
UseXSync .....	28

## V

VICDoubleScan .....	73
VICDoubleSize .....	73
VICIICheckSbColl .....	58
VICIICheckSsColl .....	58
VICIIDoubleScan .....	59
VICIIDoubleSize .....	59



VICIIPaletteFile.....	59	VirtualDevices.....	41
VICIIVideoCache.....	59		
VICPaletteFile.....	73	<b>W</b>	
VICVideoCache.....	73	WarpMode.....	27
VideoSize.....	79		

# Table of Contents

<b>1</b>	<b>GNU GENERAL PUBLIC LICENSE .....</b>	<b>1</b>
	Preamble.....	1
	TERMS AND CONDITIONS FOR COPYING, DISTRIBUTION AND MODIFICATION.....	2
	How to Apply These Terms to Your New Programs .....	6
<b>2</b>	<b>About VICE .....</b>	<b>7</b>
2.1	C64 emulator features.....	7
2.2	C64DTV emulator features.....	7
2.3	C128 emulator features.....	8
2.4	VIC20 emulator features .....	8
2.5	PET emulator features .....	8
2.6	CBM-II emulator features.....	9
2.7	The keyboard emulation.....	9
2.8	The joystick emulation .....	10
2.9	The disk drive emulation .....	10
2.10	Supported file formats .....	12
2.11	Common problems .....	13
2.11.1	Sound problems.....	13
2.11.2	Shared memory problems .....	13
2.11.3	Printer problems .....	13
2.11.4	PET keyboard problems .....	14
<b>3</b>	<b>Invoking the emulators.....</b>	<b>14</b>
3.1	Command-line options used during initialization.....	14
3.2	Autostarting programs from the command-line .....	16
<b>4</b>	<b>System files .....</b>	<b>16</b>
4.1	ROM files.....	17
4.2	Keymap files.....	19
4.3	Palette files .....	20
4.4	Romset files.....	21
<b>5</b>	<b>Basic operation .....</b>	<b>21</b>
5.1	The emulation window .....	21
5.2	Using the menus .....	22
5.3	Getting help .....	22
5.4	Using the file selector .....	22
5.5	Using disk and tape images .....	23
5.5.1	Previewing the image contents.....	23
5.5.2	“Autostarting” an image .....	24
5.5.3	Using compressed files.....	24

5.5.4	Using Zipcode and Lynx images .....	24
5.6	Resetting the machine.....	25
<b>6</b>	<b>Settings and resources .....</b>	<b>25</b>
6.1	Format of resource files.....	26
6.2	Using command-line options to change resources.....	26
6.3	Performance settings .....	27
6.3.1	Performance resources .....	27
6.3.2	Performance command-line options .....	27
6.4	Video settings.....	28
6.4.1	Video resources .....	28
6.4.2	Video command-line options.....	29
6.5	Keyboard settings.....	29
6.5.1	Keyboard resources .....	29
6.5.2	Keyboard command-line options.....	30
6.6	Joystick settings .....	30
6.6.1	Joystick command-line options .....	30
6.7	Sound settings .....	31
6.7.1	Sound resources .....	31
6.7.2	Sound command-line options .....	33
6.8	Tape settings .....	33
6.8.1	Tape command-line options .....	33
6.9	Drive settings .....	33
6.9.1	Drive resources .....	35
6.9.2	Drive command-line options .....	35
6.10	Peripheral settings .....	37
6.10.1	Settings for file system devices .....	37
6.10.1.1	Resources for file system devices.....	38
6.10.1.2	Command-line options for file system devices .....	38
6.10.2	Printer settings .....	39
6.10.2.1	Printer resources .....	39
6.10.2.2	Printer command-line options .....	40
6.10.3	Disabling kernal traps.....	41
6.10.3.1	Resources to control Kernal traps.....	41
6.10.3.2	Command-line options to control Kernal traps.....	41
6.11	RS232 settings.....	41
6.11.1	RS232 resources.....	42
6.11.2	RS232 command-line options .....	43
6.11.3	RS232 usage example .....	43
6.12	Monitor settings .....	44
6.12.1	Monitor command-line options .....	44
6.13	Machine settings.....	44
6.13.1	Machine command-line options .....	45
6.14	Memory settings.....	45
6.14.1	Memory command-line options .....	45
6.15	Miscellaneous settings.....	45
6.15.1	Miscellaneous resources .....	45
6.15.2	Miscellaneous command-line options.....	46

<b>7</b>	<b>Machine-specific features</b>	<b>46</b>
7.1	C64/128-specific commands and settings	47
7.1.1	Using cartridges	47
7.1.1.1	Slot 0	47
7.1.1.2	Slot 1	47
7.1.1.3	Main Slot	48
7.1.1.4	I/O Slot	49
7.1.1.5	Expected behaviour	50
7.1.1.6	Common problems	50
7.1.1.7	IEEE-488 interface	50
7.1.1.8	The Final Cartridge 3	51
7.1.2	C64 cartridge settings	51
7.1.2.1	C64 cartridge resources	51
7.1.2.2	C64 cartridge command-line options	52
7.1.3	CIA settings	58
7.1.3.1	CIA command-line options	58
7.1.4	VIC-II settings	58
7.1.4.1	VIC-II resources	58
7.1.4.2	VIC-II command-line options	59
7.1.5	SID settings	61
7.1.5.1	SID resources	61
7.1.5.2	SID command-line options	62
7.1.6	C64 I/O extension settings	63
7.1.6.1	C64 I/O extension resources	63
7.1.6.2	C64 I/O extension command-line options	64
7.1.7	C64/128 system ROM settings	65
7.1.7.1	C64/128 system ROM resources	65
7.1.7.2	C64/128 system ROM command-line options	66
7.1.8	C64 settings	66
7.1.8.1	C64 command-line options	66
7.2	C128-specific commands and settings	67
7.2.1	VDC settings	67
7.2.1.1	VDC command-line options	67
7.2.2	C128 system ROM settings	68
7.2.2.1	C128 system ROM command-line options	68
7.2.3	C128 settings	69
7.2.3.1	C128 command-line options	69
7.3	C64DTV-specific commands and settings	69
7.3.1	C64DTV ROM image	69
7.3.2	DTV revision	70
7.3.3	LumaFix	70
7.3.4	Userport	70
7.3.5	Debug	71
7.3.6	Monitor DTV features	71
7.4	VIC20-specific commands and settings	71
7.4.1	Using cartridge images	71
7.4.2	VIC20 cartridge settings	72
7.4.2.1	VIC20 cartridge command-line options	72

7.4.3	VIC settings .....	73
7.4.3.1	VIC resources .....	73
7.4.3.2	VIC command-line options .....	73
7.4.4	Changing memory configuration .....	74
7.4.4.1	VIC20 memory configuration resources .....	75
7.4.4.2	VIC20 memory configuration command-line options ..	75
7.4.5	VIC20 system ROM settings .....	76
7.4.5.1	VIC20 system ROM resources .....	76
7.4.5.2	VIC20 system ROM command-line options .....	76
7.4.6	VIC20 settings .....	76
7.4.6.1	VIC20 command-line options .....	76
7.5	PLUS4-specific commands and settings .....	76
7.5.1	TED settings .....	76
7.5.1.1	TED command-line options .....	77
7.5.2	PLUS4 I/O extension settings .....	78
7.5.2.1	PLUS4 I/O extension command-line options .....	78
7.5.3	PLUS4 system ROM settings .....	78
7.5.3.1	PLUS4 system ROM command-line options .....	78
7.5.4	PLUS4 settings .....	78
7.5.4.1	PLUS4 command-line options .....	79
7.6	PET-specific commands and settings .....	79
7.6.1	Changing PET model settings .....	79
7.6.2	CRTC Settings .....	80
7.6.2.1	CRTC resources .....	80
7.6.2.2	CRTC command-line options .....	81
7.6.3	The PET diagnostic pin .....	82
7.6.4	PET command line options .....	82
7.6.5	Changing screen colors .....	83
7.7	CBM-II-specific commands and settings .....	83
7.7.1	Changing CBM-II model .....	83
7.7.2	CBM-II command line options .....	84
7.7.3	Changing screen colors .....	86
7.8	VSID-specific commands and settings .....	86
7.8.1	VSID settings .....	86
7.8.1.1	VSID command-line options .....	86
<b>8</b>	<b>Snapshots .....</b>	<b>86</b>
8.1	Snapshot usage .....	86
8.2	Snapshot format .....	86
8.2.1	Emulator modules .....	86
8.2.1.1	x64 modules .....	87
8.2.1.2	x128 modules .....	87
8.2.1.3	xvic modules .....	88
8.2.1.4	xpet modules .....	88
8.2.1.5	xcbm2 modules .....	89
8.2.1.6	Drive modules .....	89
8.2.2	Module formats .....	89
8.2.2.1	Terminology .....	89

8.2.2.2	Module framework .....	90
8.2.2.3	CPU module .....	90
8.2.2.4	CIA module .....	91
8.2.2.5	VIA module .....	92
8.2.2.6	PIA module .....	93
8.2.2.7	TPI module .....	93
8.2.2.8	RIOT module .....	93
8.2.2.9	SID module .....	94
8.2.2.10	ACIA module .....	94
8.2.2.11	VIC-I module .....	94
8.2.2.12	VIC-II module .....	94
8.2.2.13	CRTC module .....	94
8.2.2.14	C64 memory module .....	96
8.2.2.15	C128 memory module .....	97
8.2.2.16	VIC20 memory module .....	97
8.2.2.17	PET memory module .....	98
8.2.2.18	CBM-II memory module .....	100
8.2.2.19	C500 data module .....	101
<b>9</b>	<b>Media images .....</b>	<b>101</b>
9.1	Media images command-line options .....	101
<b>10</b>	<b>Event history .....</b>	<b>102</b>
10.1	Event history command-line options .....	102
<b>11</b>	<b>Monitor .....</b>	<b>102</b>
11.1	Terminology .....	102
11.2	Machine state commands .....	103
11.3	Memory commands .....	104
11.4	Assembly commands .....	106
11.5	Checkpoint commands .....	106
11.6	General commands .....	108
11.7	Disk commands .....	108
11.8	Command file commands .....	109
11.9	Label commands .....	109
11.10	Miscellaneous commands .....	110
<b>12</b>	<b>c1541 .....</b>	<b>111</b>
12.1	Specifying files in c1541 .....	111
12.2	Using quotes and backslashes .....	112
12.3	c1541 commands and options .....	112
12.4	Executing shell commands .....	114
12.5	c1541 examples .....	114
<b>13</b>	<b>cartconv .....</b>	<b>114</b>
13.1	cartconv command line options .....	114
13.2	cartconv examples .....	116

<b>14</b>	<b>petcat</b> .....	<b>117</b>
14.1	petcat command line options .....	117
14.2	petcat examples .....	119
<b>15</b>	<b>The emulator file formats</b> .....	<b>119</b>
15.1	The T64 tape image format .....	119
15.1.1	T64 File structure .....	119
15.1.2	Tape Record .....	119
15.1.3	File record .....	120
15.2	The G64 GCR-encoded disk image format .....	120
15.3	The D64 disk image format .....	125
15.4	The X64 disk image format .....	134
15.5	The D71 disk image format .....	135
<b>16</b>	<b>Acknowledgments</b> .....	<b>141</b>
<b>17</b>	<b>Copyright</b> .....	<b>148</b>
<b>18</b>	<b>Contact information</b> .....	<b>149</b>
18.1	VICE home page .....	149
18.2	How to send feedback .....	149
18.3	How to contribute .....	150
18.4	Interesting newsgroups .....	151
18.5	FAQs you should read .....	151
	<b>Concept Index</b> .....	<b>151</b>
	<b>Index of Resources</b> .....	<b>156</b>