Package find projections

Comprehensively searches for informative projections (2-d projections) in the data to find boxes which separate out homogeneous data points.

Returns all projection boxes which match search criteria (support, purity).

For discrete output, the algorithm tries to find 2-d projection boxes which can separate out any class of data from the rest with high purity.

For numeric output, the algorithm tries to find 2-d projection boxes which can separate out data points with low variance.

Classes:

Datset in find projections.search projections

Data structure representing the input and output feature set.

Methods:

Datset(data)

Constructor. Creates Datset instance with numpy 2-d array of floats.

Methods:

setOutputForClassification(output)

Set output array for classification task.

setOutputForRegression(output)

Set output array for regression task.

isValid()

Checks if Datset instance has been populated properly.

Returns boolean.

getSize()

Returns the number of data points.

Search in find projections.search projections

Class to perform different types of search operations.

Methods:

search_projections(ds, binsize=10, support=50, purity=0.9, mode=0, num_threads=1)

Comprehensively evaluates all possible pairs of 2-d projections in the data

Returns all projection boxes which match search criteria

Parameters

ds: Datset instance created with your data

binsize: No. of data points for binning. Should be a positive integer

support: Minimum number of data points to be present in a projection box for evaluation. Should be a positive integer.

purity: Minimum purity (class proportion) in a projection box. Should be in the range 0.0 - 1.0

mode: Used for numeric output (regression-based analysis). Valid values are 0, 1, 2.

num_threads: No. of threads for multi-threaded operation. Should be a positive integer

Returns FeatureMap instance containing all the projection boxes found meeting the search criteria

find_easy_explain_data(ds, validation_size=0.1, binsize=10, support=50, purity=0.9, mode=0, num_threads=1)

Learns decision list of projection boxes for easy-to-explain data (for classification/regression). Returns FeatureMap instance containing all the projection boxes found meeting the search criteria.

<u>Parameters</u>

ds: Datset instance created with your data

binsize: No. of data points for binning. Should be a positive integer

support: Minimum number of data points to be present in a projection box for evaluation. Should be a positive integer.

purity: Minimum purity (class proportion) in a projection box. Should be in the range 0.0 - 1.0

mode: Used for numeric output (regression-based analysis). Valid values are 0, 1, 2. 0: Low variance boxes, 1: high mean boxes and 2: low mean boxes.

num_threads: No. of threads for multi-threaded operation. Should be a positive integer

Returns FeatureMap instance containing all the projection boxes found meeting the search criteria

FeatureMap in find projections.search projections

Container class containing projection boxes found from search operations

Methods:

```
get_num_projections():
```

Returns the total number of projection boxes in this container object

```
get_projection(i)
```

Retrieve the i'th projection-box

projection in find projections

Represents 2-d subset of data, bounded like a rectangular box. Each projection box is defined by a pair of attributes and a range of values for each of the attributes.

Methods:

```
Get_total()
```

Returns the total number of data points contained in the projection box.

```
Get_att1()
```

Returns the index of the first attribute

```
Get_att2()
```

Returns the index of the second attribute

```
Get_att1_start()
```

Returns the starting value for the range of the first attribute.

```
Get_att1_end()
```

Returns the ending value for the range of the first attribute.

```
Get_att2_start()
```

Returns the starting value for the range of the second attribute.

Get_att2_end()

Returns the ending value for the range of the second attribute.

Pprojection()

Prints out the contents of the projection

discrete projection (derives from projection class) in find projections

Represents a projection box learnt from data with discrete output (multi-class data).

Methods:

Get_class()

Returns the index of the majority class of data points inside the projection box. This will be referred to as positive class and other class points will be referred to as negatives.

Get_pos()

Returns the number of positive data points in the projection box.

Get_neg()

Returns the number of negative data points in the projection box.

numeric projection (derives from projection class) in find projections

Represents a projection box learnt from data with numeric output (output for regression).

Methods:

Get_mean()

Returns the arithmetic mean of the data points contained within the projection box.

Get_sum_sq_error()

Returns the number sum-of-squared-error for the points contained within the projection box.