

## Steps: To move script file inside Raspberry Pi Pico W of NetPi

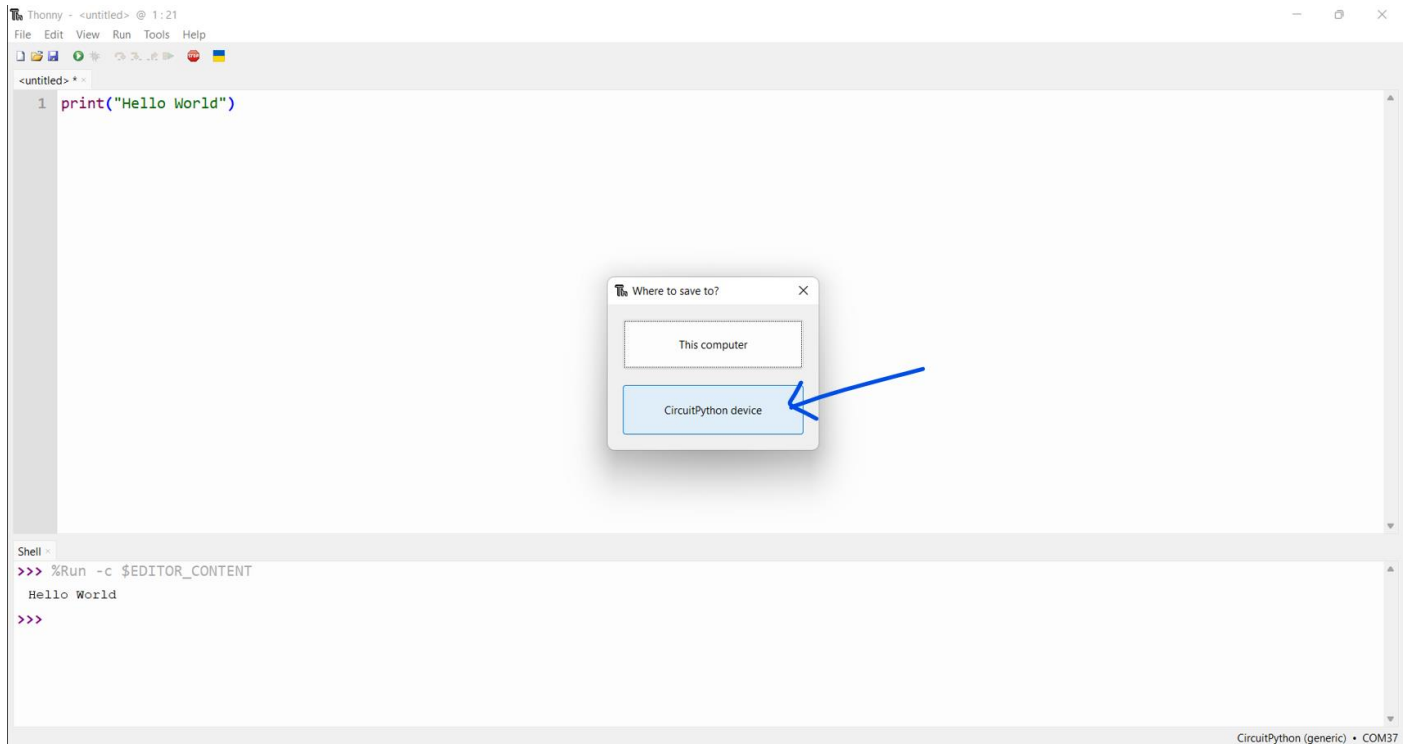


The screenshot shows the Thonny IDE interface. The main editor window contains a single line of Python code: `print("Hello World")`. Below the editor is a Shell window showing the command `>>> %Run -c $EDITOR_CONTENT` and the output `Hello World`. The status bar at the bottom indicates the device is `CircuitPython (generic) • COM37`.

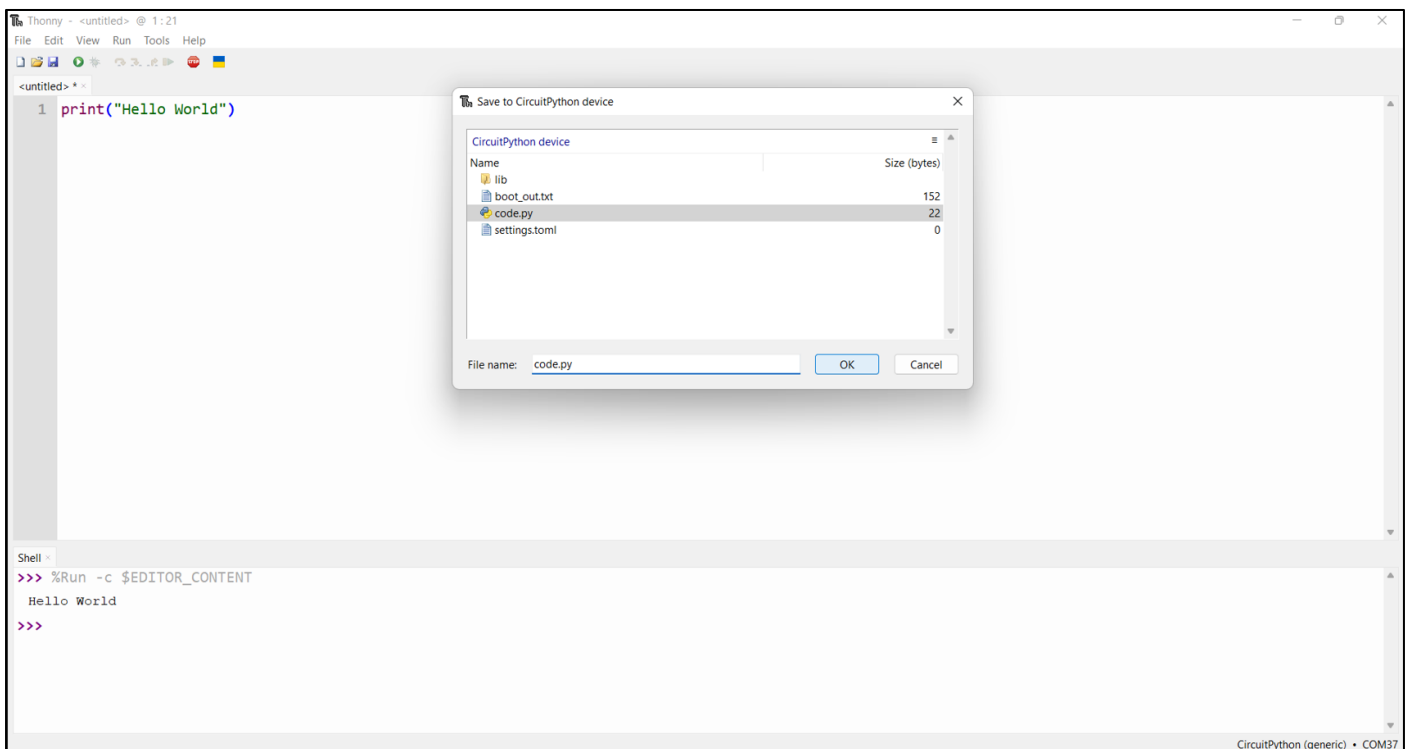
- Above example code is opened in thonny IDE and run with NetPi's Pico but to move this file on Pico click on File -> Save copy.. and Select the CircuitPython device

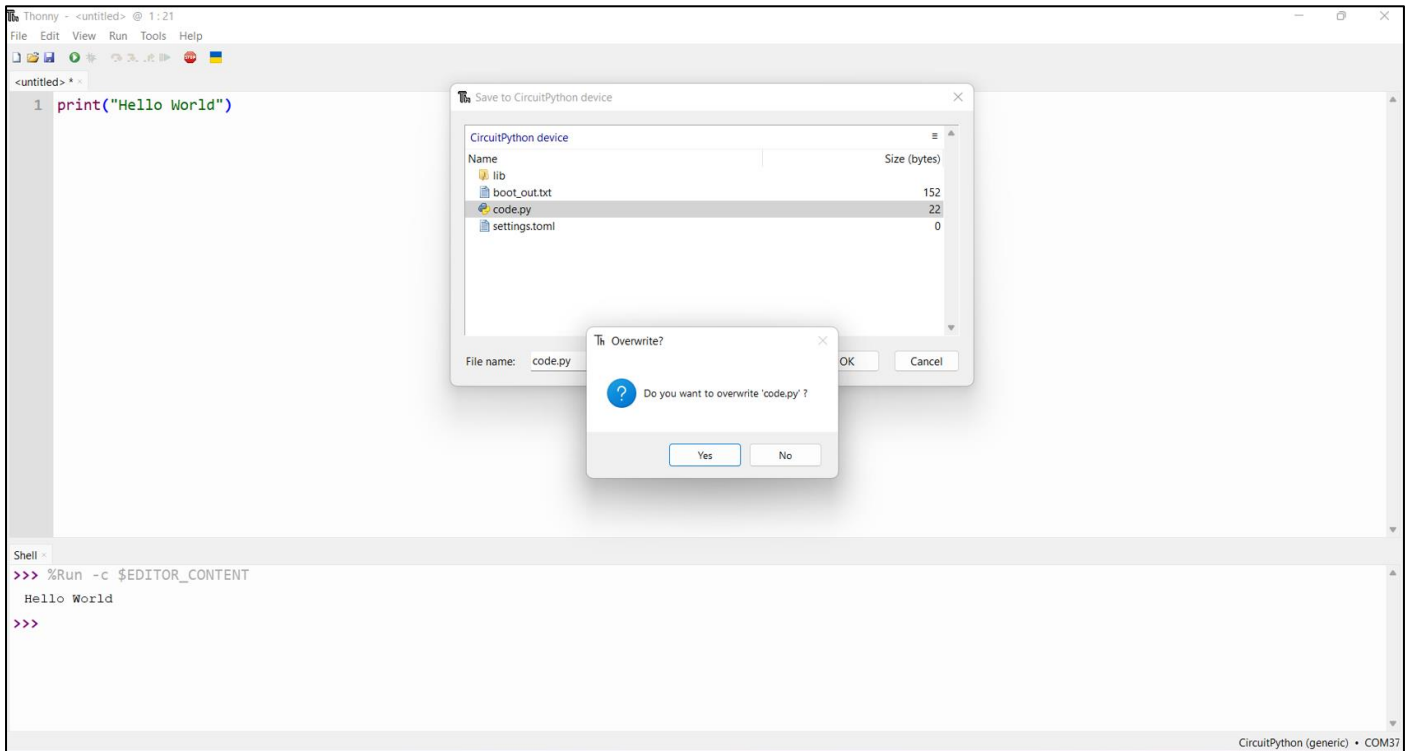


The screenshot shows the Thonny IDE interface with the File menu open. The 'Save copy...' option is highlighted. The Shell window shows the command `>>> %Run -c $EDITOR_CONTENT` and the output `Hello World`. The status bar at the bottom indicates the device is `CircuitPython (generic) • COM37`.



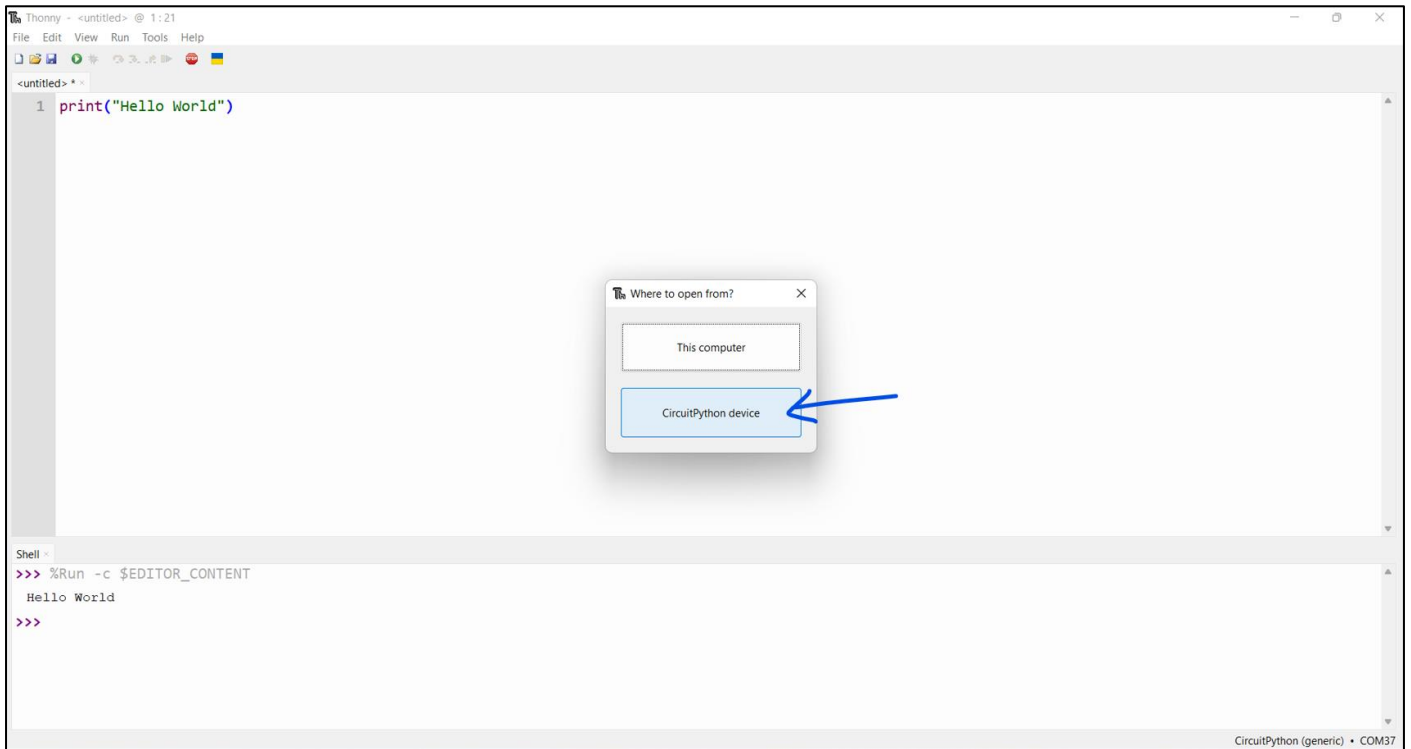
- Save file with name "code.py". Already you will find default file there with same name then overwrite it.



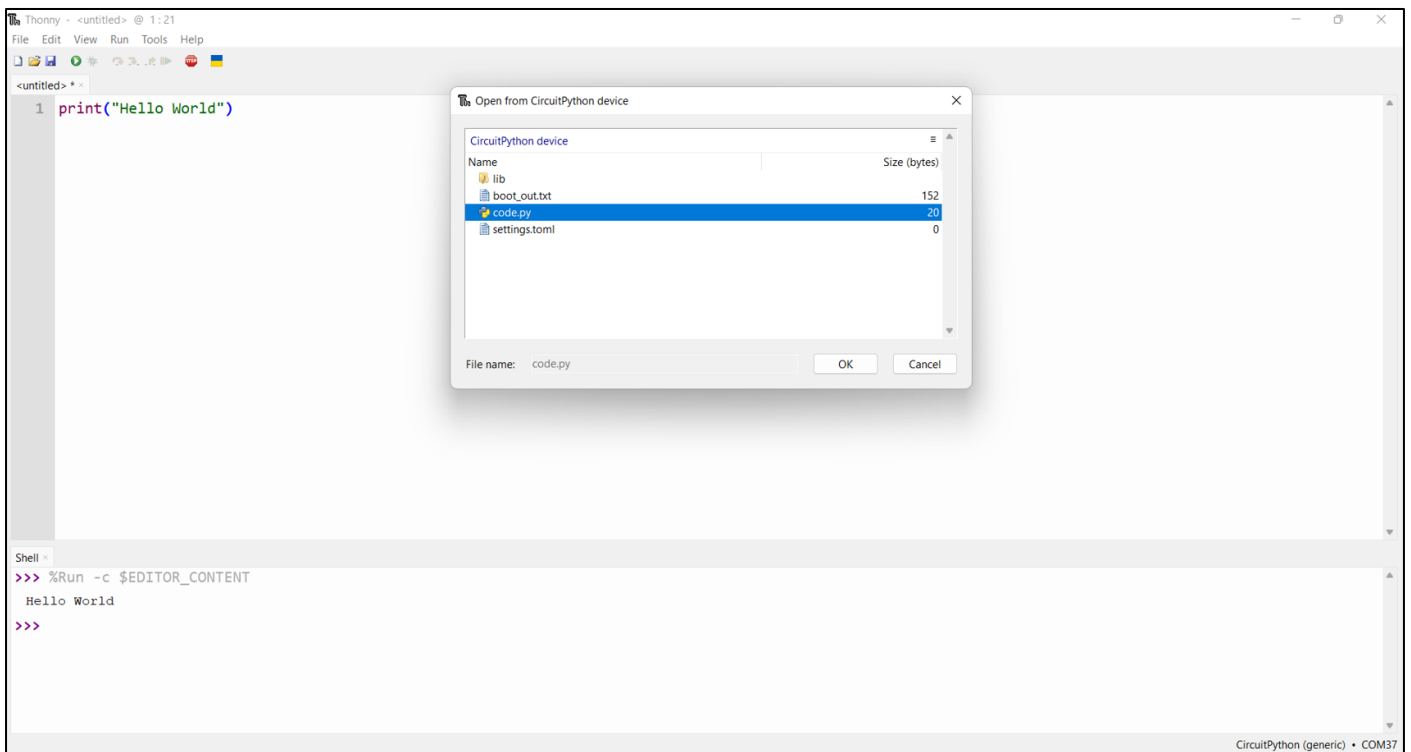


- You can verify if file is moved or not. For this just click open folder icon, and again select CircuitPython device





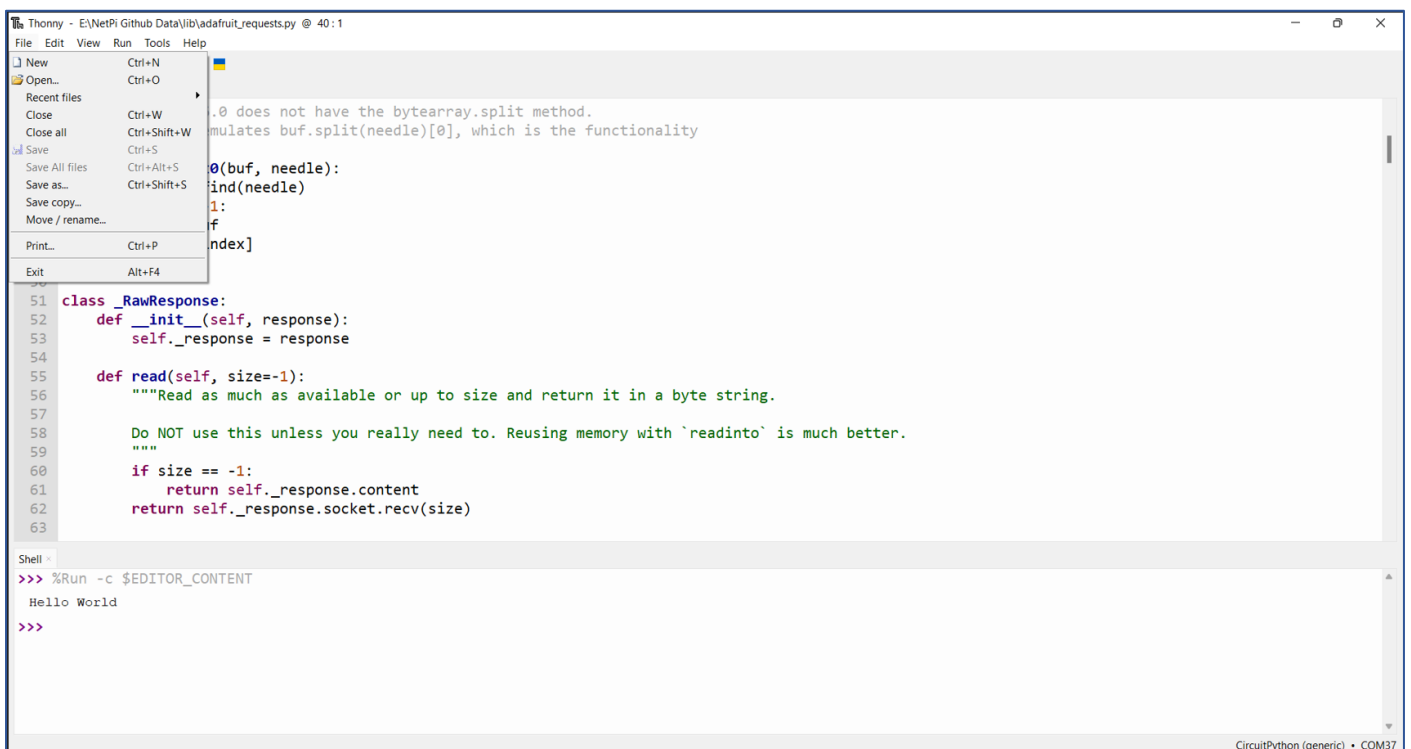
- Open code.py file from device and see [code.py] bracket which indicates file from inside Pico.





The screenshot shows the Thonny IDE interface. The top menu bar includes File, Edit, View, Run, Tools, and Help. The toolbar contains icons for file operations and running code. The main editor window displays a single line of Python code: `1 print("Hello World")`. A blue arrow points to the Run button in the toolbar. Below the editor is a Shell window showing the command `>>> %Run -c $EDITOR_CONTENT` and the output `Hello World`.

Checkout below steps to copy files inside **lib** folder of **device**, process is same ->



The screenshot shows the Thonny IDE interface with a file menu open. The menu options are: New (Ctrl+N), Open... (Ctrl+O), Recent files, Close (Ctrl+W), Close all (Ctrl+Shift+W), Save (Ctrl+S), Save All files (Ctrl+Alt+S), Save as... (Ctrl+Shift+S), Save copy..., Move / rename..., Print... (Ctrl+P), and Exit (Alt+F4). The main editor window displays a Python class definition for `_RawResponse`. The class has an `__init__` method and a `read` method. The `read` method has a docstring and a comment: "Do NOT use this unless you really need to. Reusing memory with 'readinto' is much better." The Shell window shows the command `>>> %Run -c $EDITOR_CONTENT` and the output `Hello World`.

Thonny - E:\NetPi Github Data\lib\adafruit\_requests.py @ 40:1

File Edit View Run Tools Help

adafruit\_requests.py

```
41 # CircuitPython 6.0 does not have the bytearray
42 # This function emulates buf.split(needle)[0]
43 # required.
44 def _buffer_split0(buf, needle):
45     index = buf.find(needle)
46     if index == -1:
47         return buf
48     return buf[:index]
49
50
51 class _RawResponse:
52     def __init__(self, response):
53         self._response = response
54
55     def read(self, size=-1):
56         """Read as much as available or up to size and return it in a byte string.
57
58         Do NOT use this unless you really need to. Reusing memory with `readinto` is much better.
59         """
60         if size == -1:
61             return self._response.content
62         return self._response.socket.recv(size)
63
```

Save to CircuitPython device

Name	Size (bytes)
lib	
boot_out.txt	152
code.py	20
settings.toml	0

File name:  OK Cancel

Shell

```
>>> %Run -c $EDITOR_CONTENT
Hello World
>>>
```

CircuitPython (generic) • COM37

Thonny - E:\NetPi Github Data\lib\adafruit\_requests.py @ 40:1

File Edit View Run Tools Help

adafruit\_requests.py

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58         Do NOT use this unless you really need to. Reusing memory with `readinto` is much better.
59         """
60         if size == -1:
61             return self._response.content
62         return self._response.socket.recv(size)
63
```

Save to CircuitPython device

Name	Size (bytes)
/ lib	

File name: adafruit\_requests.py OK Cancel

Shell

```
>>> %Run -c $EDITOR_CONTENT
Hello World
>>>
```

CircuitPython (generic) • COM37

Thonny - E:\NetPi Github Data\lib\adafruit\_requests.py @ 40:1

File Edit View Run Tools Help

adafruit\_requests.py

```

41 # CircuitPython 6.0 does not have the bytearray.split method.
42 # This function emulates buf.split(needle)[0], which is the functionality
43 # required.
44 def _buffer_split0(buf, needle):
45     index = buf.find(needle)
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47         return buf
48     return buf[:index]
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51 class _RawResponse:
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59
60         if size == -1:
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62         return self._response.socket.recv(size)
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```

Shell

```

>>> %Run -c $EDITOR_CONTENT
Hello World
>>>

```

CircuitPython (generic) • COM37

Thonny - E:\NetPi Github Data\lib\adafruit\_requests.py @ 40:1

File Edit View Run Tools Help

adafruit\_requests.py

```

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57         Do NOT use this unless you really need to. Reusing memory with readinto is much better.
58         """
59
60         if size == -1:
61             return self._response.content
62         return self._response.socket.recv(size)
63

```

Open from CircuitPython device

Name	Size (bytes)
adafruit_requests.py	23869

File name: OK Cancel

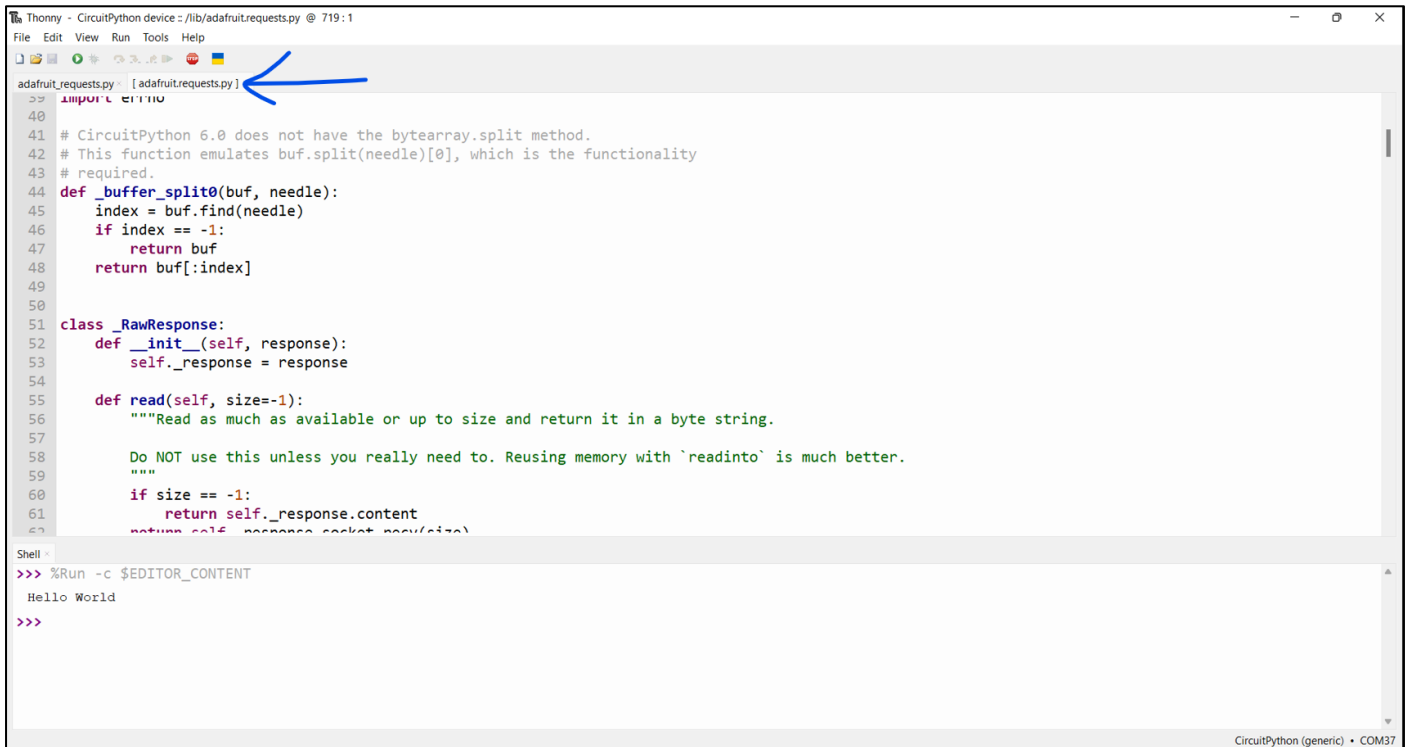
Shell

```

>>> %Run -c $EDITOR_CONTENT
Hello World
>>>

```

CircuitPython (generic) • COM37



```
Thonny - CircuitPython device - /lib/adafruit_requests.py @ 719:1
File Edit View Run Tools Help
adafruit_requests.py [adafruit_requests.py]
39 import errno
40
41 # CircuitPython 6.0 does not have the bytearray.split method.
42 # This function emulates buf.split(needle)[0], which is the functionality
43 # required.
44 def _buffer_split0(buf, needle):
45     index = buf.find(needle)
46     if index == -1:
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59         """
60         if size == -1:
61             return self._response.content
62         return self._response.socket.recv(size)
63
64
65 Shell
66 >>> %Run -c $EDITOR_CONTENT
67 Hello World
68 >>>
```

CircuitPython (generic) • COM37

[] around file confirms that file successfully transferred to device.

Similarly, copy all script files of lib( [https://github.com/sbcshop/NetPi\\_Pico\\_Ethernet/tree/main/lib](https://github.com/sbcshop/NetPi_Pico_Ethernet/tree/main/lib) ) folder from github to device lib folder before try any of code otherwise file error will pops up.