

Summary

Until recently, SciPy’s best options for scalar quadrature, minimization, and root finding called compiled code, which could not take advantage of a vectorized Python integrand, objective function, or residual function; SciPy offered no functions for accurate numerical differentiation or series summation. These gaps are being filled with a family of pure-Python, array API compatible functions for dramatically faster vectorized calculation of scalar integrals, infinite sums, derivatives, minimizers, and roots.

Methods

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| Need: Differentiation of $f: \mathbf{R}^1 \rightarrow \mathbf{R}^1$ Solution: <code>scipy.differentiate.differentiate</code> |
| Need: Differentiation of $f: \mathbf{R}^m \rightarrow \mathbf{R}^n$ Solution: <code>scipy.differentiate.jacobian</code> |
| Need: Differentiation (2 nd order) of $f: \mathbf{R}^m \rightarrow \mathbf{R}^1$ Solution: <code>scipy.differentiate.hessian</code> |
| Need: Integration of $f: \mathbf{R}^1 \rightarrow \mathbf{R}^1$ Solution: <code>scipy.integrate._tanhsinh</code> |
| Need: Summation of $\sum_{i=a}^b f(x_i)$ Solution: <code>scipy.integrate.nsum</code> |
| Need: Finding root of $f: \mathbf{R}^1 \rightarrow \mathbf{R}^1$ Solution: <code>scipy.optimize.elementwise.find_root</code> |
| Need: Bracketing root of $f: \mathbf{R}^1 \rightarrow \mathbf{R}^1$ Solution: <code>scipy.optimize.elementwise.bracket_root</code> |
| Need: Finding minimum of $f: \mathbf{R}^1 \rightarrow \mathbf{R}^1$ Solution: <code>scipy.optimize.elementwise.find_minimum</code> |
| Need: Bracketing minimum of $f: \mathbf{R}^1 \rightarrow \mathbf{R}^1$ Solution: <code>scipy.optimize.elementwise.bracket_minimum</code> |

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References

[1] Virtanen, P, Gommers, R., Oliphant, T. E., Haberland, M., Reddy, T., Cournapeau, D., ... & Van Mulbregt, P. (2020). SciPy 1.0: fundamental algorithms for scientific computing in Python. Nature methods, 17(3), 261-272.
<https://doi.org/10.1038/s41592-019-0686-2>.

SciPy 1.15 will offer array API compatible functions for quadrature, series summation, differentiation, optimization, and root finding.

Example Code

New sub-package for numerical differentiation
`from` `scipy.differentiate` `import` `differentiate`

Accepts objects compatible with Python array API standard
`x = torch.asarray([[0.25], [0.75]])`

`differentiate(f, x, args=(scale,))`

`def f(x, scale):`
 `return scipy.special.ndtr(x / scale)`
Dispatches to array backend

`scale = torch.asarray([1., 2., 3.])`
Supports broadcasting; works elementwise

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Example Result

`success: tensor([[True, True, True], [True, True, True]])`
`status: tensor([[0, 0, 0], [0, 0, 0]], dtype=torch.int32)`
`df: tensor([[0.3867, 0.1979, 0.1325], [0.3011, 0.1859, 0.1289]])`
`error: tensor([[5.0664e-07, 1.5646e-06, 3.4422e-06], [5.3644e-07, 1.5646e-06, 3.2485e-06]])`
`nit: tensor([[2, 2, 2], [2, 2, 2]], dtype=torch.int32)`
`nfev: tensor([[11, 11, 11], [11, 11, 11]], dtype=torch.int32)`

Success/status information for each element

Accurate derivative and error estimates

Requires only a few (vectorized) calls to f