ECSE 421 – Embedded Systems System Design Document

Team 1:

Walid Hussein (260215780)
Samuel Cormier-Iijima (260174995)
Amin Mirzaee (260209556)
Benjamin Nahill (260174420)
Jules Farajallah (260188388)
Bassel Khaddam (260215343)
Christopher Bedirian (260260217)
Dong Kwak (260244875)

March 10, 2010

Contents

Introduction			2	
1	Overview			3
2	Hardware			4
	2.1 Controller: Microchip PIC32MX695F512H			4
	2.1.1 Hardware Peripheral Support			4
	2.1.2 Programming			5
	2.2 Amplifier A – Cirrus CS4245			5
	2.3 Amplifier B – Cirrus CS4412			5
	2.4 EEPROM – Microchip 24FC1025			5
	2.5 LCD – Hitachi HD44780			5
	2.6 Buttons			5
	2.7 Continuous Rotary Switch			5
	2.8 Power Regulation			5

Introduction

Chapter 1

Overview

Chapter 2

Hardware

2.1 Controller: Microchip PIC32MX695F512H

The core of the system is the powerful Microchip PIC32MX695F512H controller, which directly interfaces with each of the system's peripherals. This controller was chosen due to the high processing speed, low cost, and abundant peripherals. It operates at 3.3V with an instruction clock of 80MHz, referenced to an 8MHz crystal for improved stability with the extreme temperature fluctuations provided by the amplifiers. The controller is based on a MIPS32 M4K 32-bit core, featuring a 5-stage pipeline, 512kB of flash program memory (with an additional 12kB available for a bootloader), and 128kB of RAM.

2.1.1 Hardware Peripheral Support

The PIC32MX695F512H Its abundant hardware peripherals include:

- 4 I²C channels
- 3 SPI channels
- 16 channel 10-bit ADC
- 10/100Mbit ethernet controller
- USB 2.0 transciever with On-The-Go (OTG) and full-speed capabilities
- 6 UART channels
- 5 16-bit timers
- 5 Output Compare modules for PWM output
- 5 Input Capture modules for PWM input
- Up to 53 general purpose I/Os, many of which are 5V tolerant.

The following peripherals are used in our system:

I^2C

I²C (Inter-Integrated Circuit) is a bi-directional bus which requires minimal connectivity and can have any number of masters or slaves. Only two signalling wires are required: SDA (Serial DAta) and SCL (Serial CLock.) Since, unlike with SPI, there is no *select* line, slave selection is done by prefixing all operations with the address of the intended slave. The I²C bus is used primarily as a messaging bus due to its minial

connectivity requirements and low maximum clock rate, which is usually 100 or 400kHz, making it ill suited for applications requiring high data throughput. All of our peripherals operate only as slaves and the controller acts only as a master.

10-bit ADC

The 10-bit Successive Approximation Register (SAR) Analog-to-Digital Converter (ADC) has a 16-input analog multiplexer and can sample values from 0V to 3.3V (Vcc) at up to 1MHz.

2.1.2 Programming

Microchip offers a free C compiler, MPLAB C32, for educational use. Compiled code can be loaded to the chip using the In-Circuit Serial Programming (ICSP) header on the board and a PICKit2, which is a small USB programming device. Programming may also be done directly over USB to the controller by incorporating Microchip's USB bootloader into our code.

- 2.2 Amplifier A Cirrus CS4245
- 2.3 Amplifier B Cirrus CS4412
- 2.4 EEPROM Microchip 24FC1025
- 2.5 LCD Hitachi HD44780

The 16x2 character LCD employs the industry-standard protocol of the Hitachi HD44780 controller.

- 2.6 Buttons
- 2.7 Continuous Rotary Switch
- 2.8 Power Regulation