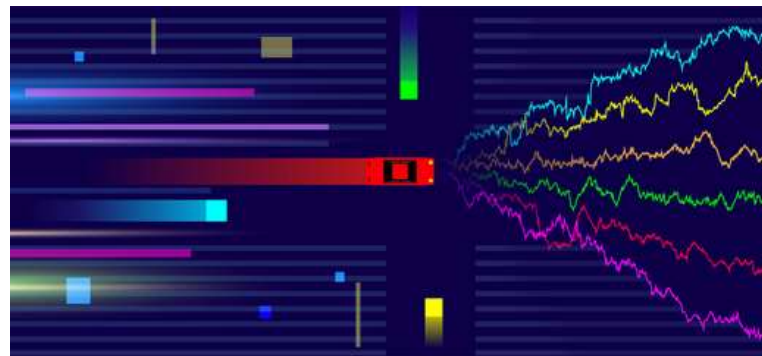


RL for Operations

Day 1: MDP Basics, VI+PI, Deep RL

Sean Sinclair, Sid Banerjee, Christina Yu
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Plan for Today

MDP Basics

- Basic framework for Markov Decision Processes
- Tabular RL Algorithms with policy iteration + value iteration
- DeepRL algorithms (and their “tabular” counterparts)

Simulation Packages

- OpenAI Framework for simulation design
- Existing packages and code-bases for RL algorithm development

Simulation Implementation

- Develop simulator for problem using OpenAI Gym API

Tabular RL Algorithms

- Implement basic tabular RL algorithms to understand key algorithmic design aspects of *value estimates + value iteration*, *policy iteration*

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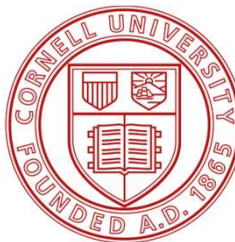
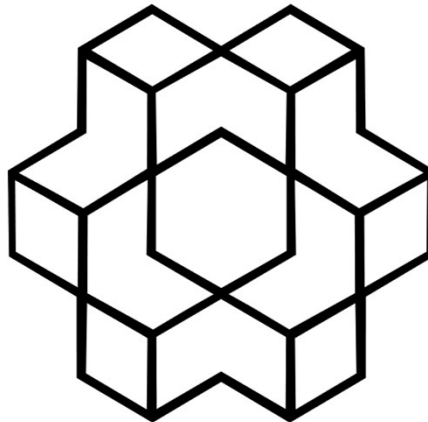
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Custom Simulator

Sean Sinclair,
Cornell University



Markov Decision Process (MDP)

Environment: Determine **reward** and new **state**



Policy: Determine **action** based on **state**

Finite Horizon

A MDP is defined by: $\mathcal{M} = \{\mathcal{S}, \mathcal{A}, r, T, s_0, \gamma\}$

\mathcal{S} State space

\mathcal{A} Action space

$r_h : \mathcal{S} \times \mathcal{A} \rightarrow [0, 1]$ Reward

$T_h : \mathcal{S} \times \mathcal{A} \rightarrow \Delta(\mathcal{S})$ Transitions

H Time horizon

$\pi_h : \mathcal{S} \rightarrow \Delta(\mathcal{A})$ Policy

This Code Demo

- Develop simulator for problem using OpenAI Gym API
- “Register” the environment with OpenAI Gym, check the environment for bugs via the stable baselines environment checker

References

<https://github.com/seanrsinclair/RLinOperations>



Step-By-Step

1. Open Anaconda Prompt via search toolbar
2. `git clone https://github.com/seanrsinclair/RLinOperations`

(Note: If git is not installed then can download from: <https://github.com/git-guides/install-git>)

3. `cd RLinOperations`
4. `code .`

This will open the visual studio code window. There will be five folders, one for the slides, and one for each of the code demos.

5. `cd custom_simulator\ORSuite` (or `custom_simulator/ORSuite` depending on platform)
6. `conda env create --name custom_simulator --file environment.yml`
7. `conda activate custom_simulator`
8. `pip install -e .`
9. `conda install jupyter`
10. `jupyter notebook`

Can now navigate to examples folder and open the demo.