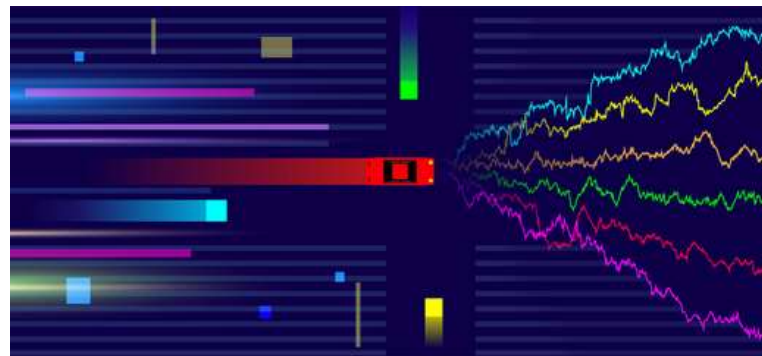


# RL for Operations

## Day 1: MDP Basics, VI+PI, Deep RL

Sean Sinclair, Sid Banerjee, Christina Yu  
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# Plan for Today

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## MDP Basics

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- Basic framework for Markov Decision Processes
- Tabular RL Algorithms with policy iteration + value iteration
- DeepRL algorithms (and their “tabular” counterparts)

## Simulation Packages

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- OpenAI Framework for simulation design
- Existing packages and code-bases for RL algorithm development

## Simulation Implementation

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- Develop simulator for problem using OpenAI Gym API

## Tabular RL Algorithms

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- Implement basic tabular RL algorithms to understand key algorithmic design aspects of *value estimates + value iteration*, *policy iteration*

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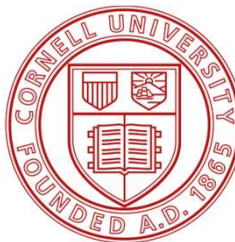
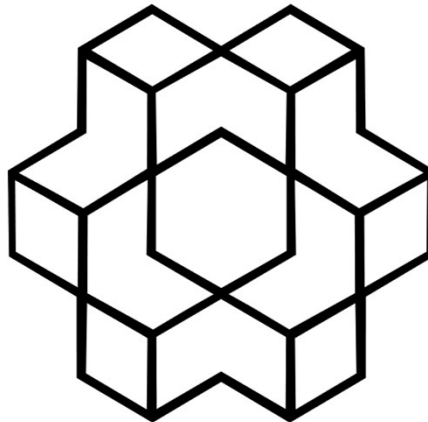
## Tabular RL Algorithms

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# Custom Simulator

Sean Sinclair,  
Cornell University



# Markov Decision Process (MDP)

**Environment:** Determine **reward** and new **state**



**Policy:** Determine **action** based on **state**

## Finite Horizon

An MDP is defined by:  $\mathcal{M} = \{\mathcal{S}, \mathcal{A}, r, T, s_0, \gamma\}$

$\mathcal{S}$  State space

$\mathcal{A}$  Action space

$r_h : \mathcal{S} \times \mathcal{A} \rightarrow [0, 1]$  Reward

$T_h : \mathcal{S} \times \mathcal{A} \rightarrow \Delta(\mathcal{S})$  Transitions

$H$  Time horizon

$\pi_h : \mathcal{S} \rightarrow \Delta(\mathcal{A})$  Policy

## This Code Demo

- Develop simulator for problem using OpenAI Gym API
- “Register” the environment with OpenAI Gym, check the environment for bugs via the stable baselines environment checker

## References

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<https://github.com/seanrsinclair/RLinOperations>





## Step-By-Step

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1. Open Anaconda Prompt via search toolbar
2. `git clone https://github.com/seanrsinclair/RLinOperations`

(Note: If git is not installed then can download from: <https://github.com/git-guides/install-git>)

3. `cd RLinOperations`
4. `code .`

This will open the visual studio code window. There will be five folders, one for the slides, and one for each of the code demos.

5. `cd custom_simulator\ORSuite` (or `custom_simulator/ORSuite` depending on platform)
6. `conda env create --name custom_simulator --file environment.yml`
7. `conda activate custom_simulator`
8. `pip install -e .`
9. `conda install jupyter`
10. `jupyter notebook`

Can now navigate to examples folder and open the demo.