

# Competitive Programming Reference

First, solve the problem. Then, write the code.

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By

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# Coding Resources

## C++

### Decimal Precision

```
// rounds up the decimal number
cout << setprecision(N) << n << endl;
// specify N fixed number of decimals
cout << fixed << setprecision(N) << n << endl;
```

### Int To Binary

```
typedef long long int lli;

lli bitsInInt(lli n) { // clz = count leading zeroes
    return sizeof(n) * 8 - __builtin_clzll(n);
}

vector<bool> intToBitsArray(lli n) {
    n = abs(n);
    if (!n) return {};
    int length = bitsInInt(n), lastPos = length - 1;
    vector<bool> v(length);
    for (lli i = lastPos, j = 0; i > -1LL; i--, j++)
        ↪ v[j] = (n >> i) & 1LL;
    return v;
}
```

### IO Optimization

```
int main() {
    ios_base::sync_with_stdio(0);
    cin.tie(0);
}
```

### Map Value To Int

```
// val = value
typedef string Val;
unordered_map<Val, int> intForVal;
unordered_map<int, Val> valForInt;
int mapId = 0;

int Map(Val val) {
    valForInt[mapId] = val;
    return intForVal.count(val) ? intForVal[val] :
        ↪ intForVal[val] = mapId++;
}

int IMap(int val) {
    return valForInt[val];
}

void initMapping() {
    mapId = 0;
    intForVal.clear();
    valForInt.clear();
}
```

### Permutations

```
typedef vector<int> T; // typedef string T;

vector<T> permutations(T v) {
    vector<vector<int>> ans;
    sort(v.begin(), v.end());
    do
        ans.push_back(v);
    while (next_permutation(v.begin(), v.end()));
    return ans;
}
```

### Print Vector

```
void printv(vector<int> v) {
    if (v.size() == 0) {
        cout << "[]" << endl;
        return;
    }
    cout << "[" << v[0];
    for (int i = 1; i < v.size(); i++) cout << ", " <<
        ↪ v[i];
    cout << "]" << endl;
}
```

### Priority Queue Of Object

```
struct Object {
    char first;
    int second;
};

int main() {
    auto cmp = [](const Object& a,
                  const Object& b) {
        return a.second > b.second;
    };
    priority_queue<Object, vector<Object>,
                  decltype(cmp)>
        pq(cmp);
    vector<Object> v = {
        {'c', 3}, {'a', 1}, {'b', 2}};
    sort(v.begin(), v.end(), cmp);
    return 0;
}
```

### Random

```
int random(int min, int max) {
    return min + rand() % (max - min + 1);
}

int main() {
    srand(time(0));
    // code
}
```

## Read Line

```
// when reading lines, don't mix 'cin' with
// 'getline' just use getline and split
string input() {
    string ans;
    // cin >> ws; // eats all whitespaces.
    getline(cin, ans);
    return ans;
}
```

## Sort Pair

```
pair<int, int> p;
sort(p.begin(), p.end());
// sorts array on the basis of the first element
```

## Sort Vector Of Object

```
struct Object {
    char first;
    int second;
};

bool cmp(const Object& a, const Object& b) {
    return a.second > b.second;
}

int main() {
    vector<Object> v = {
        {'c', 3}, {'a', 1}, {'b', 2}};
    sort(v.begin(), v.end(), cmp);
    printv(v);
    return 0;
}
```

## Split String

```
vector<string> split(string str, char token) {
    stringstream test(str);
    string seg;
    vector<string> seglist;
    while (getline(test, seg, token))
        seglist.push_back(seg);
    return seglist;
}
```

## Typedef

```
typedef TYPE ALIAS;
// example:
typedef int T;
```

# Python

## Combinations

```
import itertools
# from arr choose k = > combinations(arr, k)
print(list(itertools.combinations([1, 2, 3], 3)))
```

## Fast IO

```
from sys import stdin, stdout
```

```
N = 10
# Reads N chars from stdin (it counts '\n' as char)
stdin.read(N)
# Reads until '\n' or EOF
line = stdin.readline()
# Reads all lines in stdin until EOF
lines = stdin.readlines()
# Writes a string to stdout, it doesn't add '\n'
stdout.write(line)
# Writes a list of strings to stdout
stdout.writelines(lines)
# Reads numbers separated by space in a line
numbers = list(map(int, stdin.readline().split()))
```

## Permutations

```
import itertools
print(list(itertools.permutations([1, 2, 3])))
```

## Random

```
import random
# Initialize the random number generator.
random.seed(None)
# Returns a random integer N such that a <= N <= b.
random.randint(a, b)
# Returns a random integer N such that 0 <= N < b
random.randrange(b)
# Returns a random integer N such that a <= N < b.
random.randrange(a, b)
# Returns an integer with k random bits.
random.getrandbits(k)
# shuffles a list
random.shuffle(li)
```

## Sort List

```
li = ['a', 'c', 'b']
# sorts inplace in descending order
li.sort(reverse=True)
# returns sorted list ascending order
ol = sorted(li)
```

## Sort List Of Object

```
class MyObject :
    def __init__(self, first, second, third):
```

```
self.first = first
self.second = second
self.third = third
```

```
li = [MyObject('b', 3, 1), MyObject('a', 3, 2),
      ↪ MyObject('b', 3, 3)]
# returns list sorted by first then by second then by
↪ third in increasing order
ol = sorted(li, key = lambda x: (x.first, x.second,
      ↪ x.third), reverse=False)
# sorts inplace by first then by second then by third
↪ in increasing order
li.sort(key = lambda x: (x.first, x.second, x.third),
      ↪ reverse=False)
```

# Data Structures

## Geometry

### K-D Tree

## Graphs

### UnionFind

```
struct UnionFind {
    vector<int> dad, size;
    int n;

    UnionFind(int N = 0) : n(N), dad(N), size(N, 1) {
        while (N--) dad[N] = N;
    }

    int root(int u) {
        if (dad[u] == u) return u;
        return dad[u] = root(dad[u]);
    }

    bool areConnected(int u, int v) {
        return root(u) == root(v);
    }

    void join(int u, int v) {
        int Ru = root(u), Rv = root(v);
        if (Ru == Rv) return;
        --n, dad[Ru] = Rv;
        size[Rv] += size[Ru];
    }

    int getSize(int u) {
        return size[root(u)];
    }

    int numberOfSets() {
        return n;
    }
};
```

## Ranges

### BIT

```
typedef long long int T;
T neutro = 0;
vector<T> bit;
```

```
void initVars(int n) {
    bit.assign(++n, neutro);
}
```

```
T F(T a, T b) {
    return a + b;
    // return a * b;
}
```

```
// Inverse of F
T I(T a, T b) {
    return a - b;
    // return a / b;
}
```

```
// O(N)
void build() {
    for (int i = 1; i < bit.size(); i++) {
        int j = i + (i & -i);
        if (j < bit.size()) bit[j] = F(bit[j], bit[i]);
    }
}
```

```
// O(lg(N))
void update(int i, T val) {
    for (i++; i < bit.size(); i += i & -i) bit[i] =
        ↪ F(bit[i], val);
}
```

```
// O(lg(N))
T query(int i) {
    T ans = neutro;
    for (i++; i; i -= i & -i) ans = F(ans, bit[i]);
    return ans;
}
```

```
// O(lg(N)), [l, r]
T query(int l, int r) {
    return I(query(r), query(--l));
}
```

```
void setValAt(T val, int i) {
    bit[++i] = val;
}
```

## BIT Range Update

```
typedef long long int T;
T neutro = 0;
vector<T> bit1, bit2;

void initVars(int n) {
    bit1.assign(++n, neutro);
    bit2 = bit1;
}

// O(lg(N))
void update(vector<T> &bit, int i, T val) {
    for (i++; i < bit.size(); i += i & -i) bit[i] +=
        val;
}

// O(lg(N)), [l, r]
void update(int l, int r, T val) {
    update(bit1, l, val);
    update(bit1, r + 1, -val);
    update(bit2, r + 1, val * r);
    update(bit2, l, -val * (l - 1));
}

// O(lg(N))
T query(vector<T> &bit, int i) {
    T ans = neutro;
    for (i++; i; i -= i & -i) ans += bit[i];
    return ans;
}

// O(lg(N))
T query(int i) {
    return query(bit1, i) * i + query(bit2, i);
}

// O(lg(N)), [l, r]
T query(int l, int r) {
    return query(r) - query(l - 1);
}
```

## Segment Tree

```
// st = segment tree. st[1] = root;
// neutro = operation neutral value
// e.g. for sum is 0, for multiplication
// is 1, for gcd is 0, for min is INF, etc.
typedef int T;
T neutro = 0;
int N;
vector<T> st;

void initVars(int n) {
    st.assign(2 * (N = n), neutro);
}

T F(T a, T b) {
    return a + b;
    // return __gcd(a, b);
    // return a * b;
    // return min(a, b);
}
```

```
// O(2N)
void build() {
    for (int i = N - 1; i > 0; i--) st[i] = F(st[i <<
        1], st[i << 1 | 1]);
}

// O(lg(2N))
void update(int i, T val) {
    for (st[i += N] = val; i > 1; i >>= 1) st[i >> 1] =
        F(st[i], st[i ^ 1]);
}

// O(3N), [l, r]
void update(int l, int r, T val) {
    for (l += N, r += N; l <= r; l++) st[l] = val;
    build();
}

// O(lg(2N)), [l, r]
T query(int l, int r) {
    T ans = neutro;
    for (l += N, r += N; l <= r; l >>= 1, r >>= 1) {
        if (l & 1) ans = F(ans, st[l++]);
        if (~r & 1) ans = F(ans, st[r--]);
    }
    return ans;
}

void setValAt(T val, int i) {
    st[i + N] = val;
}
```

## Segment Tree Lazy Propagation

```
// st = segment tree, st[1] = root, H = height of st
// u = updates, d = delayed updates
// neutro = operation neutral val
// e.g. for sum is 0, for multiplication
// is 1, for gcd is 0, for min is INF, etc.
template <class T>
struct SegmentTree {
    T neutro = 0;
    int N, H;
    vector<T> st, d;
    vector<bool> u;

    SegmentTree(int n) : st(2 * n, neutro), d(n), u(n,
        0) {
        H = sizeof(int) * 8 - __builtin_clz(N = n);
    }

    T F(T a, T b) {
        return a + b;
        // return __gcd(a, b);
        // return a * b;
        // return min(a, b);
    }
}
```

```

void apply(int i, T val, int k) {
    st[i] = val * k; // sum
    // st[i] = val; // min, max, gcd
    // st[i] = pow(a, k); // multiplication
    if (i < N) d[i] = val, u[i] = 1;
}

void calc(int i) {
    if (!u[i]) st[i] = F(st[i << 1], st[i << 1 | 1]);
}

// O(2N)
void build() {
    for (int i = N - 1; i > 0; i--) calc(i);
}

// O(lg(N))
void build(int p) {
    while (p > 1) p >>= 1, calc(p);
}

// O(lg(N))
void push(int p) {
    for (int s = H, k = 1 << (H - 1); s > 0; s--, k
        ↪ >>= 1) {
        int i = p >> s;
        if (u[i]) {
            apply(i << 1, d[i], k);
            apply(i << 1 | 1, d[i], k);
            u[i] = 0, d[i] = neutro;
        }
    }
}

// O(lg(N)), [l, r]
void update(int l, int r, T val) {
    push(l += N);
    push(r += N);
    int ll = l, rr = r, k = 1;
    for (; l <= r; l >>= 1, r >>= 1, k <== 1) {
        if (l & 1) apply(l++, val, k);
        if (~r & 1) apply(r--, val, k);
    }
    build(ll);
    build(rr);
}

// O(lg(2N)), [l, r]
T query(int l, int r) {
    push(l += N);
    push(r += N);
    T ans = neutro;
    for (; l <= r; l >>= 1, r >>= 1) {
        if (l & 1) ans = F(ans, st[l++]);
        if (~r & 1) ans = F(ans, st[r--]);
    }
    return ans;
}

void setValAt(T val, int i) {
    st[i + N] = val;
}
};

```

## Sparse Table

```

// st = sparse table, Arith = Arithmetic
typedef int T;
int neutro = 0;
vector<vector<T>> st;

T F(T a, T b) {
    // return min(a, b);
    return __gcd(a, b);
    // return a + b; // Arith
    // return a * b; // Arith
}

// O(Nlg(N))
void build(vector<T> &arr) {
    st.assign(log2(arr.size()), vector<T>(arr.size()));
    st[0] = arr;
    for (int i = 1; (1 << i) <= arr.size(); i++)
        for (int j = 0; j + (1 << i) <= arr.size(); j++)
            ↪ st[i][j] = F(st[i - 1][j], st[i - 1][j + (1 <<
            ↪ (i - 1))]);
}

// O(1), [l, r]
T query(int l, int r) {
    int i = log2(r - l + 1);
    return F(st[i][l], st[i][r + 1 - (1 << i)]);
}

// O(lg(N)), [l, r]
T queryArith(int l, int r) {
    T ans = neutro;
    while (true) {
        int k = log2(r - l + 1);
        ans = F(ans, st[k][l]);
        l += 1 << k;
        if (l > r) break;
    }
    return ans;
}

```

## Strings

### Trie

```

// wpt = number of words passing through
// w = number of words ending in the node
// c = character
struct Trie {

    struct Node {
        // for lexicographical order use 'map'
        // map<char, Node*> ch;
        unordered_map<char, Node*> ch;
        int w = 0, wpt = 0;
    };

    Node *root = new Node();
}

```

```
// O(STR.SIZE)
void insert(string str) {
    Node *curr = root;
    for (auto &c : str) {
        curr->wpt++;
        if (!curr->ch.count(c)) curr->ch[c] = new
            ↪ Node();
        curr = curr->ch[c];
    }
    curr->wpt++;
    curr->w++;
}

// O(STR.SIZE)
Node *find(string &str) {
    Node *curr = root;
    for (auto &c : str) {
        if (!curr->ch.count(c)) return nullptr;
        curr = curr->ch[c];
    }
    return curr;
}

// number of words with given prefix O(N)
int prefixCount(string prefix) {
    Node *node = find(prefix);
    return node ? node->wpt : 0;
}

// number of words matching str O(N)
int strCount(string str) {
    Node *node = find(str);
    return node ? node->w : 0;
}

// O(N)
void getWords(Node *curr, vector<string> &words,
    ↪ string &word) {
    if (!curr) return;
    if (curr->w) words.push_back(word);
    for (auto &c : curr->ch) {
        getWords(c.second, words, word += c.first);
        word.pop_back();
    }
}

// O(N)
vector<string> getWords() {
    vector<string> words;
    string word = "";
    getWords(root, words, word);
    return words;
}

// O(N)
vector<string> getWordsByPrefix(string prefix) {
    vector<string> words;
    getWords(find(prefix), words, prefix);
}
```

```
// O(STR.SIZE)
bool remove(Node *curr, string &str, int &i) {
    if (i == str.size()) {
        curr->wpt--;
        return curr->w ? !(curr->w = 0) : 0;
    }
    int c = str[i];
    if (!curr->ch.count(c)) return false;
    if (remove(curr->ch[c], str, ++i)) {
        if (!curr->ch[c]->wpt) curr->wpt--,
            ↪ curr->ch.erase(c);
        return true;
    }
    return false;
}

// O(STR.SIZE)
int remove(string str) {
    int i = 0;
    return remove(root, str, i);
}
};
```

## Trees And Heaps

### Treap

## Graphs

### Articulation Points And Bridges

```
// APB = articulation points and bridges
// ap = Articulation Point
// br = bridges, p = parent
// disc = discovery time
// low = lowTime, ch = children
typedef pair<int, int> Edge;
int Time;
vector<vector<int>>> ady;
vector<int> disc, low, ap;
vector<Edge> br;

void initVars(int N) {
    ady.assign(N, vector<int>());
}
```



```

int dfsAPB(int u, int p) {
    int ch = 0;
    low[u] = disc[u] = ++Time;
    for (int &v : ady[u]) {
        if (v == p) continue;
        if (!disc[v]) {
            ch++, dfsAPB(v, u);
            if (disc[u] <= low[v]) ap[u]++;
            if (disc[u] < low[v]) br.push_back({u, v});
            low[u] = min(low[u], low[v]);
        } else
            low[u] = min(low[u], disc[v]);
    }
    return ch;
}

// O(N)
void APB() {
    br.clear();
    ap = low = disc = vector<int>(ady.size());
    Time = 0;
    for (int u = 0; u < ady.size(); u++)
        if (!disc[u]) ap[u] = dfsAPB(u, u) > 1;
}

void addEdge(int u, int v) {
    ady[u].push_back(v);
    ady[v].push_back(u);
}

```

## Connected Components

```

// comp = component
int compId;
vector<vector<int>>> ady;
vector<int> getComp;

void initVars(int N) {
    ady.assign(N, vector<int>());
    getComp.assign(N, -1);
    compId = 0;
}

void dfsCC(int u, vector<int> &comp) {
    if (getComp[u] > -1) return;
    getComp[u] = compId;
    comp.push_back(u);
    for (auto &v : ady[u]) dfsCC(v, comp);
}

// O(N)
vector<vector<int>>> connectedComponents() {
    vector<vector<int>>> comps;
    for (int u = 0; u < ady.size(); u++) {
        vector<int> comp;
        dfsCC(u, comp);
        if (!comp.empty()) comps.push_back(comp),
            compId++;
    }
    return comps;
}

```

```

void addEdge(int u, int v) {
    ady[u].push_back(v);
    ady[v].push_back(u);
}

```

## Cycles

### Get All Simple Cycles

### Get Some Cycles

```

// at least detects one cycle per component
vector<vector<int>>> ady, cycles;
vector<int> vis, cycle;
bool flag = false, isDirected = false;
int root = -1;

void initVars(int N) {
    ady.assign(N, vector<int>());
    vis.assign(N, 0);
    cycles.clear();
    root = -1, flag = false;
}

// O(N)
bool hasCycle(int u, int prev) {
    vis[u] = 1;
    for (auto &v : ady[u]) {
        if (v == u || vis[v] == 2 || (!isDirected && v ==
            ↪ prev)) continue;
        if (flag) {
            if (!vis[v]) hasCycle(v, u);
            continue;
        }
        if (vis[v] || hasCycle(v, u)) {
            if (root == -1) root = v, flag = true;
            cycle.push_back(u);
            if (root == u) flag = false, root = -1,
                ↪ cycles.push_back(cycle), cycle.clear();
        }
    }
    vis[u] = 2;
    return flag;
}

// O(N)
bool hasCycle() {
    for (int u = 0; u < ady.size(); u++)
        if (!vis[u]) cycle.clear(), hasCycle(u, -1);
    return cycles.size() > 0;
}

void addEdge(int u, int v) {
    ady[u].push_back(v);
    if (!isDirected) ady[v].push_back(u);
}

```

## Has Cycle

```
vector<vector<int>>> ady;
vector<int> vis;
bool isDirected = false;
void initVars(int N) {
    ady.assign(N, vector<int>());
    vis.assign(N, 0);
}
bool hasCycle(int u, int prev) {
    vis[u] = 1;
    for (auto &v : ady[u])
        if (v != u && vis[v] != 2 && (isDirected || v !=
            ↪ prev) && (vis[v] || hasCycle(v, u))) return
            ↪ true;
    vis[u] = 2;
    return false;
}
// O(N)
bool hasCycle() {
    for (int u = 0; u < ady.size(); u++)
        if (!vis[u] && hasCycle(u, -1)) return true;
}
void addEdge(int u, int v) {
    ady[u].push_back(v);
    if (!isDirected) ady[v].push_back(u);
}
```

## Flood Fill

```
int n, m, oldColor = 0, color = 1;
vector<vector<int>>> mat;

vector<vector<int>>> movs = {{1, 0}, {0, 1}, {-1, 0},
    ↪ {0, -1}};
void floodFill(int i, int j) {
    if (i >= mat.size() || i < 0 || j >= mat[i].size()
        ↪ || j < 0 || mat[i][j] != oldColor) return;
    mat[i][j] = color;
    for (auto move : movs) floodFill(i + move[1], j +
        ↪ move[0]);
}
void floodFill() {
    for (int i = 0; i < n; i++)
        for (int j = 0; j < m; j++)
            if (mat[i][j] == oldColor) floodFill(i, j);
}
```

# Flow

## Max Flow Dinic

```
// cap[a][b] = Capacity from a to b
// flow[a][b] = flow occupied from a to b
// level[a] = level in graph of node a
typedef int T;
vector<int> level;
vector<vector<int>>> ady;
unordered_map<int, unordered_map<int, T>>> cap, flow;
```

```
void initVars(int N) {
    ady.assign(N, vector<int>());
    cap.clear();
    flow.clear();
}

bool levelGraph(int s, int t) {
    level = vector<int>(ady.size());
    level[s] = 1;
    queue<int> q;
    q.push(s);
    while (!q.empty()) {
        int u = q.front();
        q.pop();
        for (int &v : ady[u]) {
            if (!level[v] && flow[u][v] < cap[u][v]) {
                q.push(v);
                level[v] = level[u] + 1;
            }
        }
    }
    return level[t];
}

T blockingFlow(int u, int t, T currPathMaxFlow) {
    if (u == t) return currPathMaxFlow;
    for (int v : ady[u]) {
        T capleft = cap[u][v] - flow[u][v];
        if ((level[v] == (level[u] + 1)) && (capleft > 0))
            ↪ {
                T pathMaxFlow = blockingFlow(v, t,
                    ↪ min(currPathMaxFlow, capleft));
                if (pathMaxFlow > 0) {
                    flow[u][v] += pathMaxFlow;
                    flow[v][u] -= pathMaxFlow;
                    return pathMaxFlow;
                }
            }
    }
    return 0;
}

// O(E * V^2)
T dinicMaxFlow(int s, int t) {
    if (s == t) return -1;
    T maxFlow = 0;
    while (levelGraph(s, t))
        while (T flow = blockingFlow(s, t, 1 << 30))
            ↪ maxFlow += flow;
    return maxFlow;
}

void addEdge(int u, int v, T capacity) {
    cap[u][v] = capacity;
    ady[u].push_back(v);
}
```

## Maximum Bipartite Matching

```
#include "Max Flow Dinic.cpp"

void addEdge(int u, int v) {
    cap[u][v] = 1;
    ady[u].push_back(v);
}

int main() {
    int n, s = 0, t = 1;
    cin >> n;
    initVars(n);
    while (n--) {
        int u, v;
        cin >> u >> v;
        addEdge(u += 2, v += 2);
        addEdge(s, u);
        addEdge(v, t);
    }
    cout << dinicMaxFlow(s, t) << endl;
    return 0;
}
```

## Is Bipartite

```
vector<vector<int>>> ady;

void initVars(int N) {
    ady.assign(N, vector<int>());
}

// O(N)
bool isBipartite() {
    vector<int> color(ady.size(), -1);
    for (int s = 0; s < ady.size(); s++) {
        if (color[s] > -1) continue;
        color[s] = 0;
        queue<int> q;
        q.push(s);
        while (!q.empty()) {
            int u = q.front();
            q.pop();
            for (int &v : ady[u]) {
                if (color[v] < 0) q.push(v), color[v] =
                    !color[u];
                if (color[v] == color[u]) return false;
            }
        }
    }
    return true;
}
```

## LCA

```
// st = sparse table
typedef pair<int, int> T;
int neutro = 0;
vector<vector<T>>> st;
```

```
vector<int> first;
vector<T> tour;
vector<vector<int>>> ady;

void initVars(int N) {
    ady.assign(N, vector<int>());
}

T F(T a, T b) {
    return a.first < b.first ? a : b;
}

void build() {
    st.assign(log2(tour.size()),
        vector<T>(tour.size()));
    st[0] = tour;
    for (int i = 1; (1 << i) <= tour.size(); i++)
        for (int j = 0; j + (1 << i) <= tour.size(); j++)
            st[i][j] = F(st[i - 1][j], st[i - 1][j + (1 <<
                i - 1)]);
}

void eulerTour(int u, int p, int h) {
    first[u] = tour.size();
    tour.push_back({h, u});
    for (int v : ady[u])
        if (v != p) {
            eulerTour(v, u, h + 1);
            tour.push_back({h, u});
        }
}

void preprocess() {
    tour.clear();
    first.assign(ady.size(), -1);
    eulerTour(0, 0, 0);
    build();
}

// O(1)
int lca(int u, int v) {
    int l = min(first[u], first[v]);
    int r = max(first[u], first[v]);
    int i = log2(r - l + 1);
    return F(st[i][l], st[i][r + 1 - (1 << i)]).second;
}

void addEdge(int u, int v) {
    ady[u].push_back(v);
    ady[v].push_back(u);
}
```

## MST Kruskal

```
// N = number of nodes, Wedge = Weighted Edge
#include "../Data Structures/Graphs/UnionFind.cpp"
typedef int T;
typedef pair<int, int> Edge;
typedef pair<T, Edge> Wedge;
vector<Wedge> Wedges;
vector<Wedge> mst;
UnionFind uf(0);
```

```

void initVars(int N) {
    mst.clear();
    Wedges.clear();
    uf = UnionFind(N);
}

T kruskal() {
    T cost = 0;
    sort(Wedges.begin(), Wedges.end());
    // reverse(Wedges.begin(), Wedges.end());
    for (Wedge &wedge : Wedges) {
        int u = wedge.second.first, v =
            ↪ wedge.second.second;
        if (!uf.areConnected(u, v)) uf.join(u, v),
            ↪ mst.push_back(wedge), cost += wedge.first;
    }
    return cost;
}

void addEdge(int u, int v, T w) {
    Wedges.push_back({w, {u, v}});
}

```

## MST Prim

```

// st = spanning tree, p = parent
// vis = visited, dist = distance
typedef int T;
typedef pair<int, int> Edge;
typedef pair<T, Edge> Wedge;
typedef pair<T, int> DistNode;
int MAXN = 20001, INF = 1 << 30;
vector<vector<int>>> ady;
unordered_map<int, unordered_map<int, T>> weight;
vector<int> p, vis;
vector<T> dist;
vector<vector<Wedge>> msts;

void initVars(int N) {
    ady.assign(N, vector<int>());
    p.assign(N, 0);
    vis.assign(N, 0);
    dist.assign(N, INF);
    weight.clear();
    msts.clear();
}

```

```

// O(E * log(V))
T prim(int s) {
    vector<Wedge> mst;
    vector<set<Edge>::iterator> pos(ady.size());
    vector<T> dist(ady.size(), INF);
    set<Edge> q;
    T cost = dist[s] = 0;
    q.insert({0, s});
    while (q.size()) {
        int u = q.begin()->second;
        q.erase(q.begin());
        vis[u] = 1, cost += dist[u];
        mst.push_back({dist[u], {p[u], u}});
        for (int &v : ady[u]) {
            T w = weight[u][v];
            if (!vis[v] && w < dist[v]) {
                if (dist[v] != INF) q.erase(pos[v]);
                pos[v] = q.insert({dist[v] = w, v}).first;
            }
        }
    }
    msts.push_back(vector<Wedge>(mst.begin() + 1,
        ↪ mst.end()));
    return cost;
}

```

```

T primLazy(int s) {
    vector<Wedge> mst;
    vector<set<Edge>::iterator> pos(ady.size());
    vector<T> dist(ady.size(), INF);
    priority_queue<DistNode, vector<DistNode>,
        ↪ greater<DistNode>> q;
    T cost = dist[s] = 0;
    q.push({0, s});
    while (q.size()) {
        pair<int, int> aux = q.top();
        int u = aux.second;
        q.pop();
        if (dist[u] < aux.first) continue;
        vis[u] = 1, cost += dist[u];
        mst.push_back({dist[u], {p[u], u}});
        for (int &v : ady[u]) {
            T w = weight[u][v];
            if (!vis[v] && w < dist[v]) q.push({dist[v] = w,
                ↪ v});
        }
    }
    msts.push_back(vector<Wedge>(mst.begin() + 1,
        ↪ mst.end()));
    return cost;
}

```

```

// O(V + E * log(V))
T prim() {
    T cost = 0;
    map<int, T> q;
    for (int i = 0; i < ady.size(); i++)
        if (!vis[i]) cost += prim(i);
    return cost;
}

```

```
void addEdge(int u, int v, T w) {
    ady[u].push_back(v);
    weight[u][v] = w;
    ady[v].push_back(u);
    weight[v][u] = w;
}
```

## ShortestPaths

### Bellman Ford

```
// N = number of nodes
// returns {} if there is a negative weight cycle
typedef int T;
int MAXN = 20001, N, INF = 1 << 30, isDirected = true;
vector<vector<int>> ady;
unordered_map<int, unordered_map<int, T>> weight;
```

```
void initVars(int N) {
    ady.assign(N, vector<int>());
    weight.clear();
}
```

```
// O(V * E)
vector<T> bellmanFord(int s) {
    vector<T> dist(ady.size(), INF);
    dist[s] = 0;
    for (int i = 1; i <= ady.size(); i++)
        for (int u = 0; u < ady.size(); u++)
            for (auto &v : ady[u]) {
                T w = weight[u][v];
                if (dist[u] != INF && dist[u] + w < dist[v]) {
                    if (i == ady.size()) return {};
                    dist[v] = dist[u] + w;
                }
            }
    return dist;
}
```

```
void addEdge(int u, int v, T w) {
    ady[u].push_back(v);
    weight[u][v] = w;
    if (isDirected) return;
    ady[v].push_back(u);
    weight[v][u] = w;
}
```

### Dijkstra

```
typedef int T;
typedef pair<T, int> DistNode;
int MAXN = 20001, INF = 1 << 30, isDirected = false;
vector<vector<int>> ady;
unordered_map<int, unordered_map<int, T>> weight;

void initVars(int N) {
    ady.assign(N, vector<int>());
    weight.clear();
}
```

```
// O(E * lg(V))
vector<int> dijkstra(int s) {
    vector<set<DistNode>::iterator> pos(ady.size());
    vector<T> dist(ady.size(), INF);
    set<DistNode> q;
    q.insert({0, s}), dist[s] = 0;
    while (q.size()) {
        int u = q.begin()->second;
        q.erase(q.begin());
        for (int &v : ady[u]) {
            T w = weight[u][v];
            if (dist[u] + w < dist[v]) {
                if (dist[v] != INF) q.erase(pos[v]);
                pos[v] = q.insert({dist[v] = dist[u] + w,
                    ↪ v}).first;
            }
        }
    }
    return dist;
}
```

```
vector<int> dijkstraLazy(int s) {
    vector<int> dist(ady.size(), INF);
    priority_queue<DistNode, vector<DistNode>,
        ↪ greater<DistNode>> q;
    q.push({0, s}), dist[s] = 0;
    while (q.size()) {
        DistNode top = q.top(); q.pop();
        int u = top.second;
        if (dist[u] < top.first) continue;
        for (int &v : ady[u]) {
            T w = weight[u][v];
            if (dist[u] + w < dist[v]) q.push({dist[v] =
                ↪ dist[u] + w, v});
        }
    }
    return dist;
}
```

```
void addEdge(int u, int v, T w) {
    ady[u].push_back(v);
    weight[u][v] = w;
    if (isDirected) return;
    ady[v].push_back(u);
    weight[v][u] = w;
}
```

### Strongly Connected Components

```
// tv = top value from stack
// sccs = strongly connected components
// scc = strongly connected component
// disc = discovery time
// low = low time
// s = stack
// top = top index of the stack
int Time, top;
vector<vector<int>> ady, sccs;
vector<int> disc, low, s;
```

```

void initVars(int N) {
    ady.assign(N, vector<int>());
}

void dfsSCCS(int u) {
    if (disc[u]) return;
    low[u] = disc[u] = ++Time;
    s[++top] = u;
    for (int &v : ady[u]) dfsSCCS(v), low[u] =
        ↪ min(low[u], low[v]);
    if (disc[u] == low[u]) {
        vector<int> scc;
        while (true) {
            int tv = s[top--];
            scc.push_back(tv);
            low[tv] = ady.size();
            if (tv == u) break;
        }
        sccs.push_back(scc);
    }
}

// O(N)
void SCCS() {
    s = low = disc = vector<int>(ady.size());
    Time = 0, top = -1, sccs.clear();
    for (int u = 0; u < ady.size(); u++) dfsSCCS(u);
}

void addEdge(int u, int v) {
    ady[u].push_back(v);
}

```

## Topological Sort

```

// vis = visited
vector<vector<int>> ady;
vector<int> vis, toposorted;

void initVars(int N) {
    ady.assign(N, vector<int>());
    vis.assign(N, 0);
    toposorted.clear();
}

// returns false if there is a cycle
bool toposort(int u) {
    vis[u] = 1;
    for (auto &v : ady[u])
        if (v != u && vis[v] != 2 && (vis[v] ||
            ↪ !toposort(v))) return false;
    vis[u] = 2;
    toposorted.push_back(u);
    return true;
}

// O(N)
bool toposort() {
    vis.clear();
    for (int u = 0; u < ady.size(); u++)
        if (!vis[u] && !toposort(u)) return false;
    return true;
}

```

# Maths

## Number Theory

### Divisibility Criterion

```

def divisorCriteria(n, lim):
    results = []
    tenElevated = 1
    for i in range(lim):
        # remainder = pow(10, i, n)
        remainder = tenElevated % n
        negremainder = remainder - n
        if(remainder <= abs(negremainder)):
            results.append(remainder)
        else:
            results.append(negremainder)
        tenElevated *= 10
    return results

def testDivisibility(dividend, divisor,
    ↪ divisor_criteria):
    dividend = str(dividend)
    addition = 0
    dividendSize = len(dividend)
    i = dividendSize - 1
    j = 0
    while j < dividendSize:
        addition += int(dividend[i]) *
            ↪ divisor_criteria[j]
        i -= 1
        j += 1
    return addition % divisor == 0

if __name__ == '__main__':
    dividend, divisor = map(int, input().split())
    divisor_criteria = divisorCriteria(divisor,
        ↪ len(str(dividend)))
    print(divisor_criteria)
    print(testDivisibility(dividend, divisor,
        ↪ divisor_criteria))

```

## Extended Euclidean

```
// gcd(a, b) = ax + by
vector<long long int> extendedGCD(long long int a,
    ↪ long long int b) {
    if (a > 0LL && b == 0LL) {
        return {a, 1LL, 0LL};
    }
    long long int x = 1LL, y = 0LL, prevx = 0LL, prevy =
    ↪ 1LL, q, remainder;
    while (true) {
        q = a / b;
        remainder = a - b * q;
        if (remainder == 0LL) break;
        a = b;
        b = remainder;
        x = x - prevx * q;
        swap(x, prevx);
        y = y - prevy * q;
        swap(y, prevy);
    }
    // gcd = b, x = prevx, y = prevy
    return {b, prevx, prevy};
}
```

## GCD

```
// recursive
int gcd(int a, int b) {
    return !b ? a : gcd(b, a % b);
}

// iterative
int gcd(int a, int b) {
    while (b) {
        a %= b;
        swap(a, b);
    }
    return a;
}
```

## LCM

```
int lcm(int a, int b) {
    int c = gcd(a, b);
    return c ? a / c * b : 0;
}
```

## Prime Check Miller Rabin

```
from random import randrange
```

```
def is_prime(p):
    k = 100
    if p == 2 or p == 3:
        return True
    if (p & 1) == 0 or p == 1:
        return False
    phi = p - 1
    d = phi
    r = 0
    while (d & 1) == 0:
        d = int(d >> 1)
        r += 1
    for i in range(k):
        a = randrange(2, p - 2)
        exp = pow(a, d, p)
        if exp == 1 or exp == p - 1:
            continue
        flag = False
        for j in range(r - 1):
            exp = pow(exp, 2, p)
            if exp == 1:
                return False
            if exp == p - 1:
                flag = True
                break
        if flag:
            continue
        else:
            return False
    return True
```

## Prime Sieve

```
vector<int> primeSieve(int n) {
    vector<int> sieve(n + 1);
    for (int i = 4; i <= n; i += 2) sieve[i] = 2;
    for (int i = 3; i * i <= n; i += 2)
        if (!sieve[i])
            for (int j = i * i; j <= n; j += 2 * i)
                if (!sieve[j]) sieve[j] = i;
    return sieve;
}
```

# Strings

## KMP

```
// f = error function
// cf = create error function
// p = pattern
// t = text
// pos = positions where pattern is found in text
int MAXN = 1000000;
vector<int> f(MAXN + 1);
```



```
vector<int> kmp(string &p, string &t, int cf) {
    vector<int> pos;
    if (cf) f[0] = -1;
    for (int i = cf, j = 0; j < t.size(); i = f[i], j++) {
        while (i > -1 && p[i] != t[j]) i = f[i];
        if (cf) f[j] = i;
        if (!cf && i == p.size()) pos.push_back(j - i), i = f[i];
    }
    return pos;
}
```

```
vector<int> search(string &p, string &t) {
    kmp(p, p, -1); // create error function
    return kmp(p, t, 0); // search in text
}
```

## Rabin Karp

```
class RollingHash {
public:
    vector<unsigned long long int> pow;
    vector<unsigned long long int> hash;
    unsigned long long int B;

    RollingHash(const string &text) : B(257) {
        int N = text.size();
        pow.resize(N + 1);
        hash.resize(N + 1);
        pow[0] = 1;
        hash[0] = 0;
        for (int i = 1; i <= N; ++i) {
            // in c++ an unsigned long long int is
            // automatically modulated by 2^64
            pow[i] = pow[i - 1] * B;
            hash[i] = hash[i - 1] * B + text[i - 1];
        }
    }

    unsigned long long int getWordHash() {
        return hash[hash.size() - 1];
    }

    unsigned long long int getSubstrHash(int begin, int
    ↪ end) {
        return hash[end] - hash[begin - 1] * pow[end -
    ↪ begin + 1];
    }

    int size() {
        return hash.size();
    }
};
```

```
vector<int> rabinKarp(RollingHash &rhStr, string
    ↪ &pattern) {
    vector<int> positions;
    RollingHash rhPattern(pattern);
    unsigned long long int patternHash =
    ↪ rhPattern.getWordHash();
    int windowSize = pattern.size(), end = windowSize;
    for (int i = 1; end < rhStr.size(); i++) {
        if (patternHash == rhStr.getSubstrHash(i, end))
            ↪ positions.push_back(i);
        end = i + windowSize;
    }
    return positions;
}
```

# Techniques

## Binary Search

## Multiple Queries

### Mo

```
// q = query
// qs = queries

struct Query {
    int l, r;
};

int blksize;
vector<Query> qs;
vector<int> arr;

void initVars(int N, int M) {
    arr = vector<int>(N);
    qs = vector<Query>(M);
}

bool cmp(Query &a, Query &b) {
    if (a.l == b.l) return a.r < b.r;
    return a.l / blksize < b.l / blksize;
}
```



```

void getResults() {
    blksize = (int)sqrt(arr.size());
    sort(qs.begin(), qs.end(), cmp);
    int prevL = 0, prevR = -1;
    int sum = 0;
    for (auto &q : qs) {
        int L = q.l, R = q.r;
        while (prevL < L) {
            sum -= arr[prevL]; // problem specific
            prevL++;
        }
        while (prevL > L) {
            prevL--;
            sum += arr[prevL]; // problem specific
        }
        while (prevR < R) {
            prevR++;
            sum += arr[prevR]; // problem specific
        }
        while (prevR > R) {
            sum -= arr[prevR]; // problem specific
            prevR--;
        }

        cout << "sum[" << L << ", " << R << "] = " << sum
              << endl;
    }
}

int main() {
    initVars(9, 2);
    arr = {1, 1, 2, 1, 3, 4, 5, 2, 8};
    qs = {{0, 8}, {3, 5}};
    getResults();
}

```

## SQRT Decomposition

```

// sum of elements in range
int neutro = 0;

vector<int> arr;
vector<int> blks;

void initVars(int n) {
    arr.assign(n, neutro);
    blks.assign(sqrt(n), neutro);
}

void preprocess() {
    for (int i = 0, j = 0; i < arr.size(); i++) {
        if (i == blks.size() * j) j++;
        blks[j - 1] += arr[i]; // problem specific
    }
}

// problem specific
void update(int i, int val) {
    blks[i / blks.size()] += val - arr[i];
    arr[i] = val;
}

```

```

int query(int l, int r) {
    int sum = 0;
    int lblk = l / blks.size();
    if (l != blks.size() * lblk++) {
        while (l < r && l != lblk * blks.size()) {
            sum += arr[l]; // problem specific
            l++;
        }
    }

    while (l + blks.size() <= r) {
        sum += blks[l / blks.size()]; // problem specific
        l += blks.size();
    }
    while (l <= r) {
        sum += arr[l]; // problem specific
        l++;
    }
    return sum;
}

int main() {
    initVars(10);
    arr = {1, 5, 2, 4, 6, 1, 3, 5, 7, 10};
    preprocess();
    for (int i = 0; i < blks.size() + 1; i++) cout <<
        blks[i] << " ";
    // output: 8 11 15 10
    cout << endl;
    cout << query(3, 8) << " ";
    cout << query(1, 6) << " ";
    update(8, 0);
    cout << query(8, 8) << endl;
    // output: 26 21 0
    return 0;
}

```