
Pattern Recognition

SVM 개념 잡기

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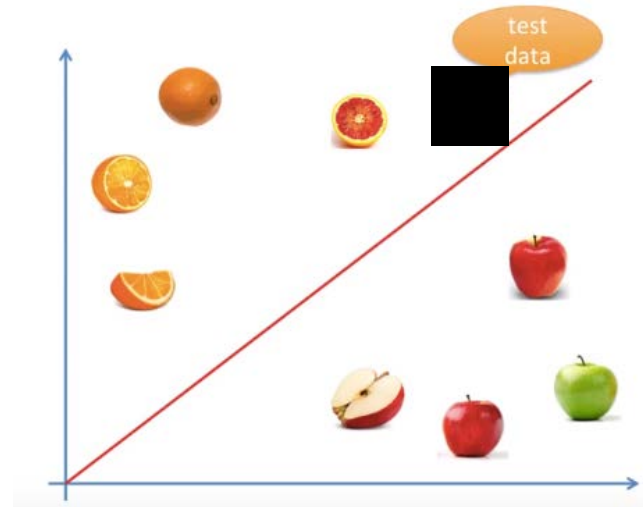
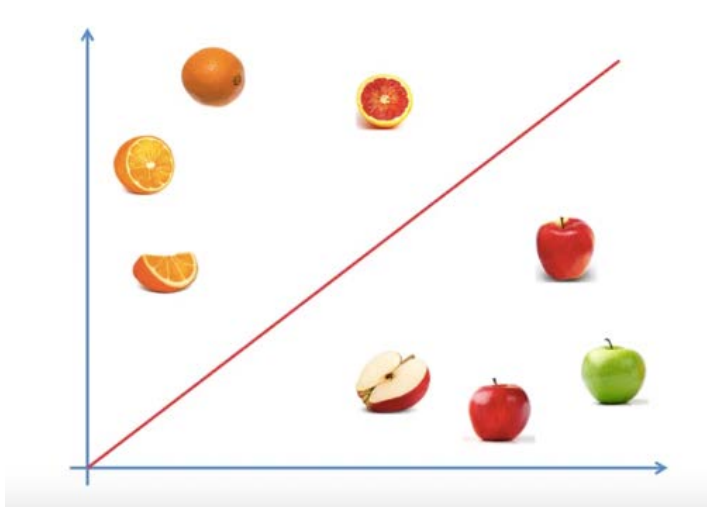
What is SVM?

- Support **V**ector **M**achine → SVM
- Traditional Classifier
- Until now, favorite classifier to everyone
 - Wondering why? **Kernel Trick!!!**

“만약, 문제에 어떠한 알고리즘을 사용할지 모르겠다면,
SVM은 좋은 출발선이 될 수 있음”

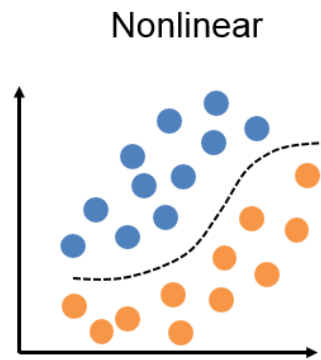
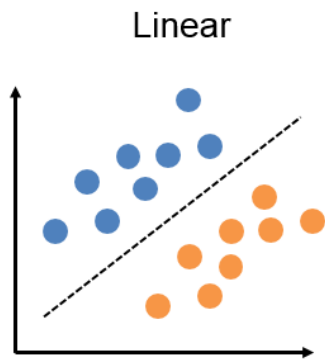
Classifier

- **Classifier** is a hypothesis or discrete-valued function that is used to **assign (categorical) class labels to particular data points.**
- In the email classification example, this classifier could be a hypothesis for labeling emails as **spam** or **non-spam**.



Classifier

- $y = \text{label}$, $x = \text{data}$, $y = f(x)$, f : classifier
- If **decision function** is linear, this classifier (f) is **linear classifier**
- If not, this classifier (f) is **non-linear classifier**



$$y = f(x)$$

데이터를 구획해주는 이 점선의 함수
(**decision boundary**)를 우리는 **판별 함수**
(**decision function**)라 부른다.

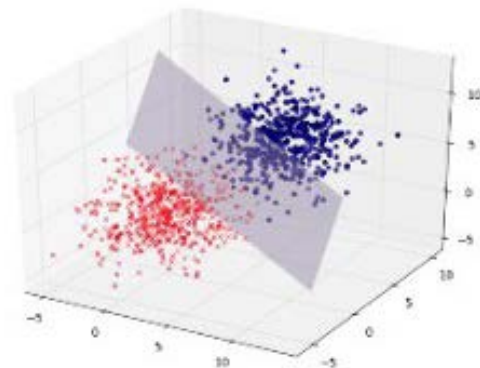
Classifier

- **Hyperplane**

- In geometry, a hyperplane is a subspace whose dimension is one less than that of its ambient space. If a space is **3-dimensional** then its hyperplanes are the **2-dimensional planes**, while if the space is **2-dimensional**, its hyperplanes are the **1-dimensional lines**.

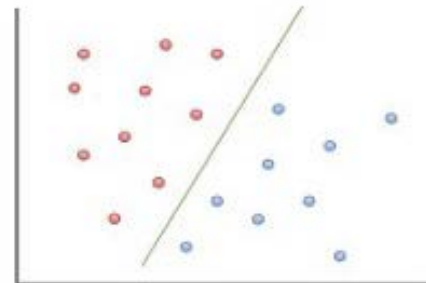
$$\mathbf{w}^T \mathbf{x} = 0$$

Hyperplane



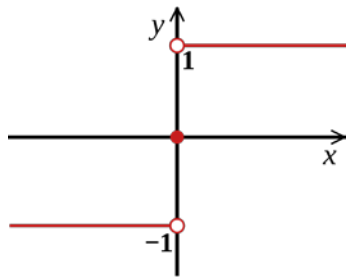
$$y = ax + b$$

Line

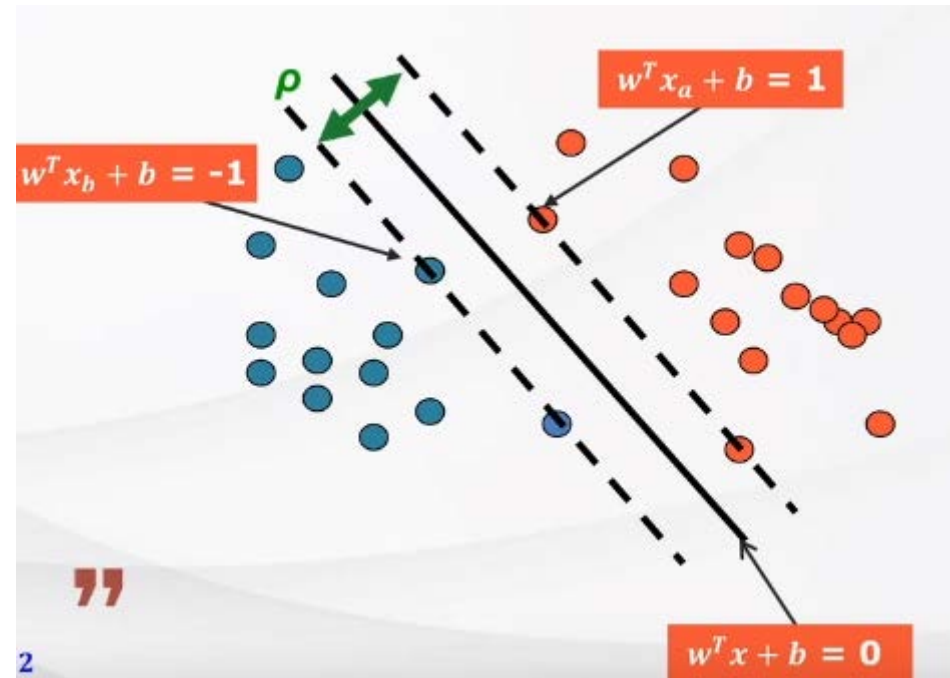


SVM Classifier

- W : vector for hyperplane
- x_i : i_{th} data, y_i : label (class) of i_{th} data
- $Y = \text{sign}(W^T X + b) = f(X)$
 - $Y_i = +1$ when $W^T X_i + b > 1$
 - $Y_i = -1$ when $W^T X_i + b < -1$

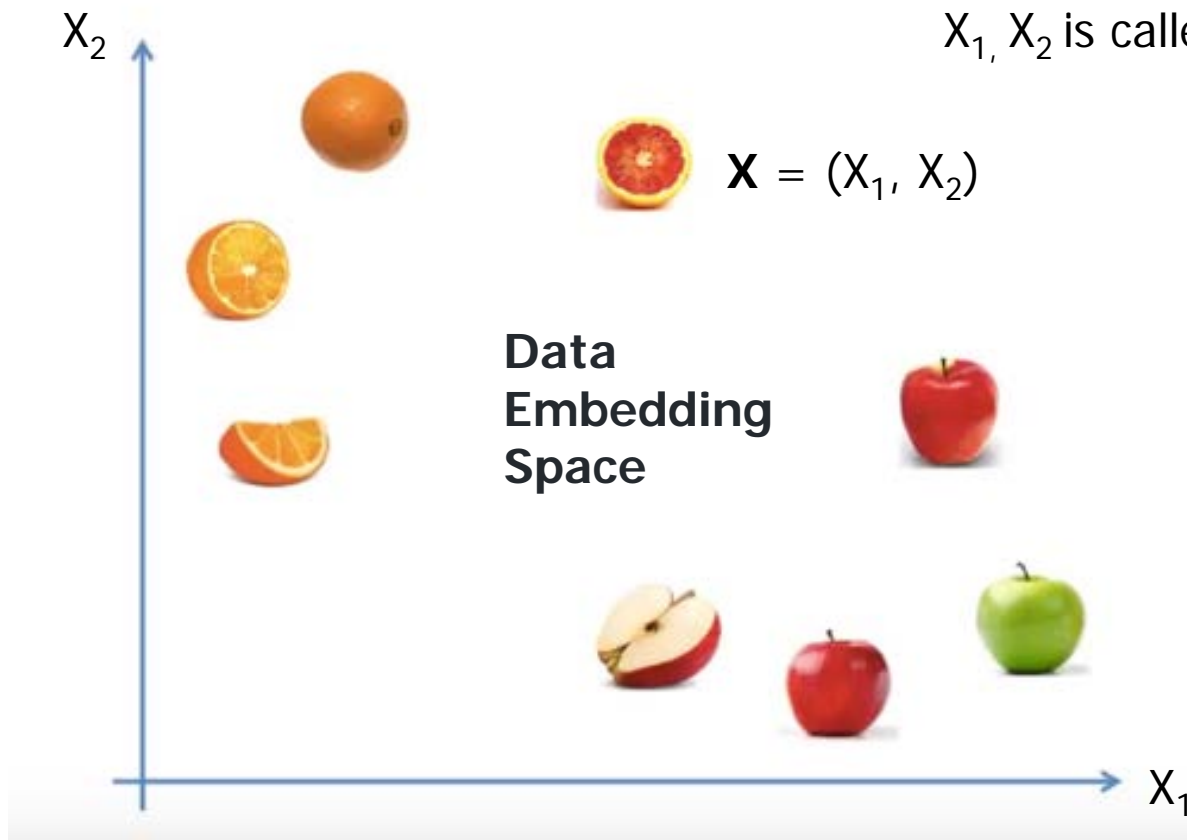


Sign function



Apple, orange classifier

▪ Data Embedding Space



Data Embedding

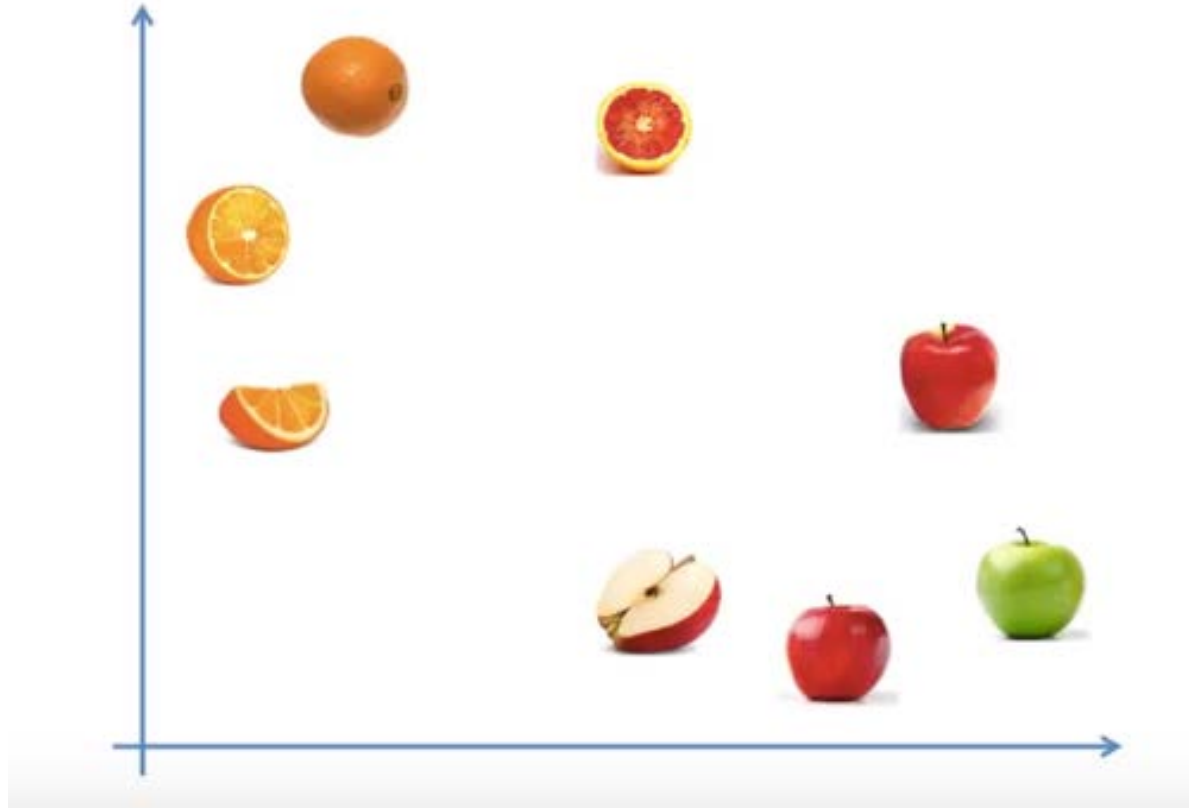
범주형 자료를 **벡터 형태**로 바꾸는 것

Categorical Data

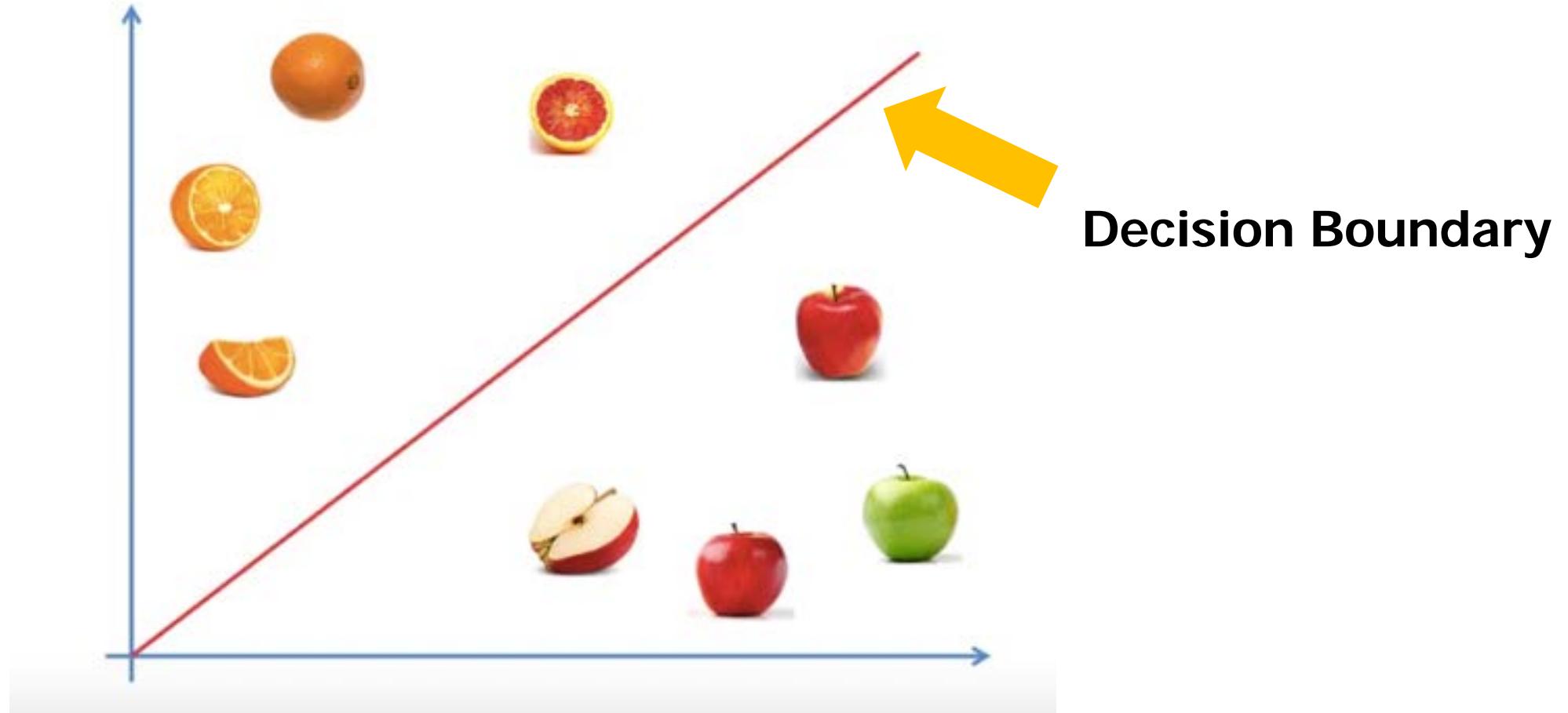
범주형 데이터란 몇 개의 범주로 나누어진 데이터 예) 남/여, A/B/O/AB

Apple, orange classifier

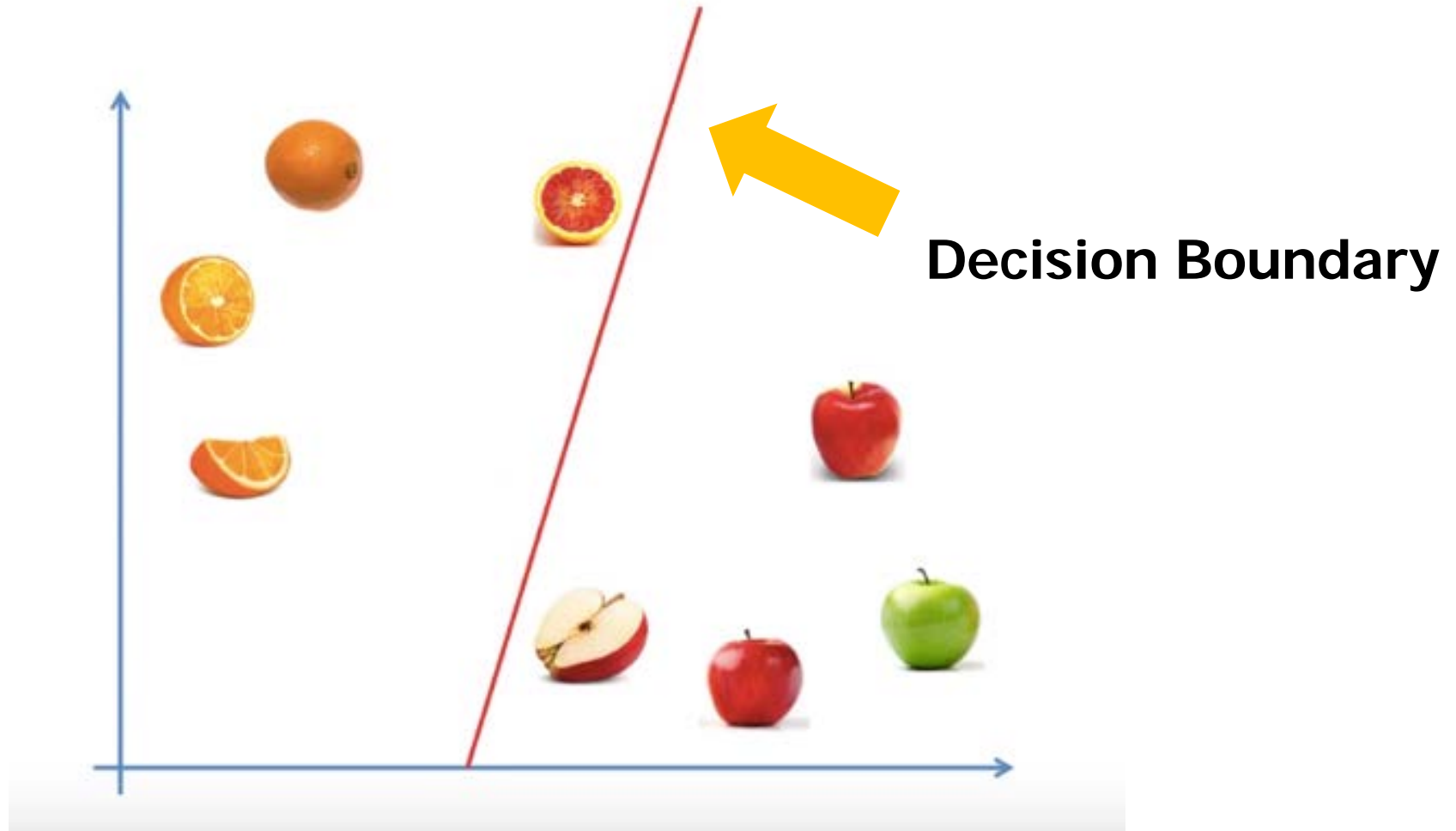
- Which hyperplane can we choose?



Apple, orange classifier



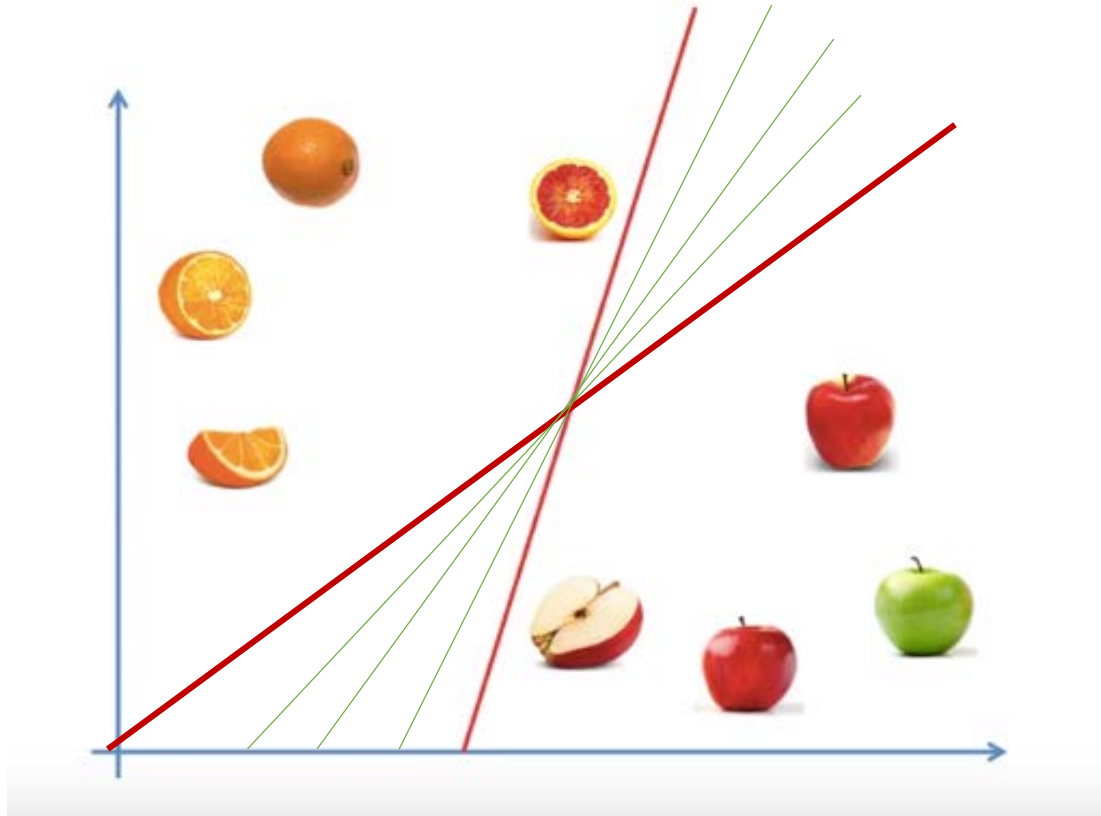
Apple, orange classifier



Apple, orange classifier

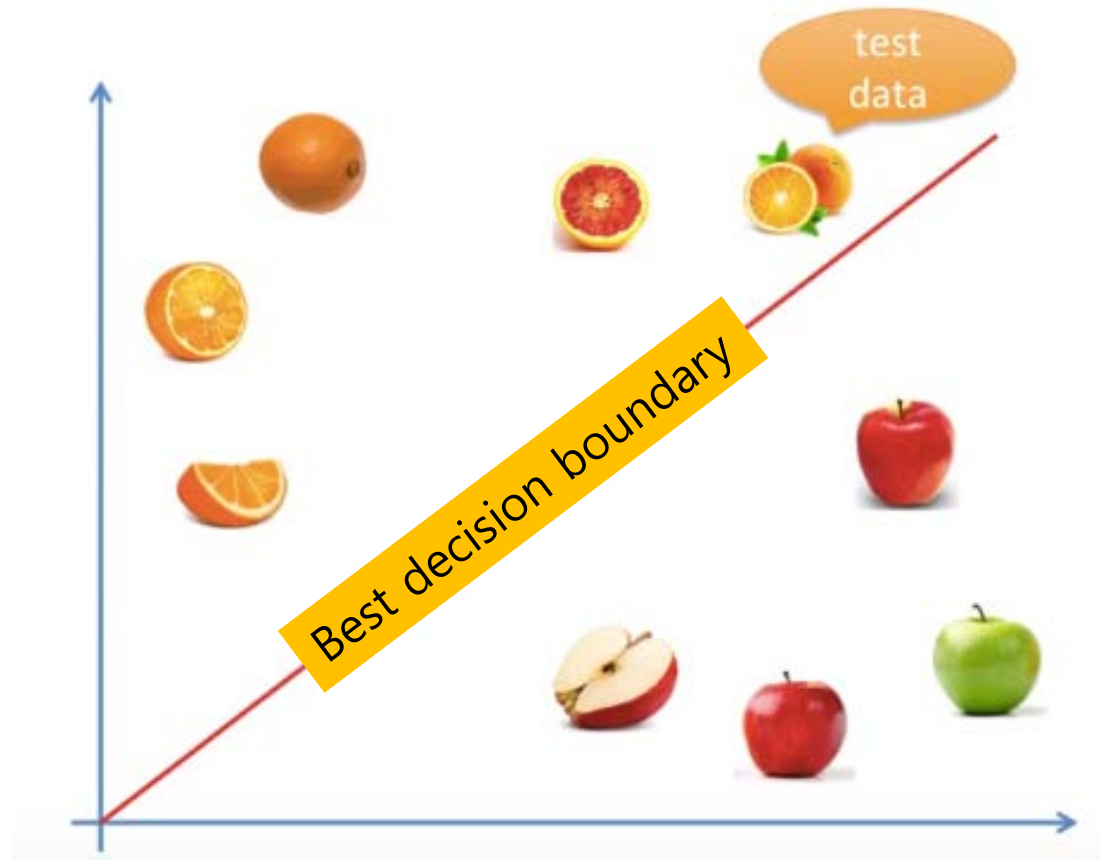
- Which one is better?
 - Classifier should have dealt with **unseen data**

Train sample data → seen data
Test sample data → unseen data



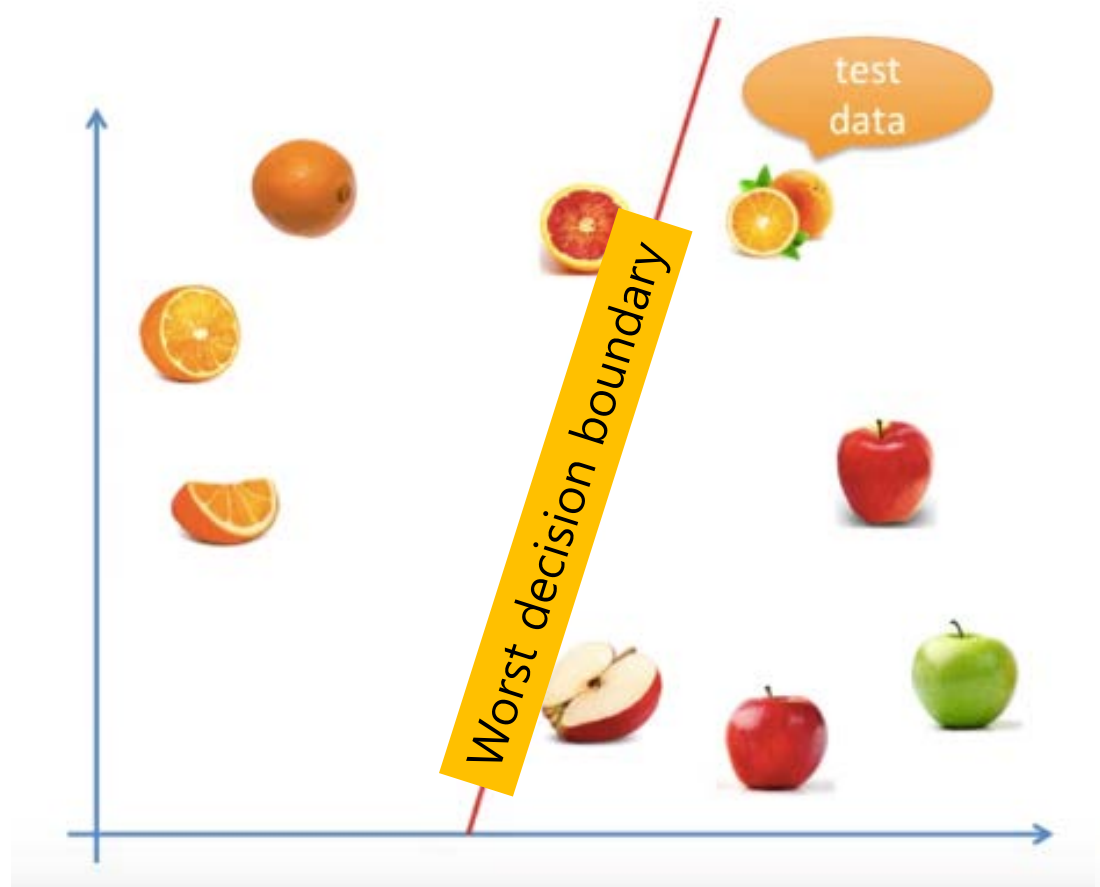
How can we decide decision boundary?

- Test data predicted well (0)



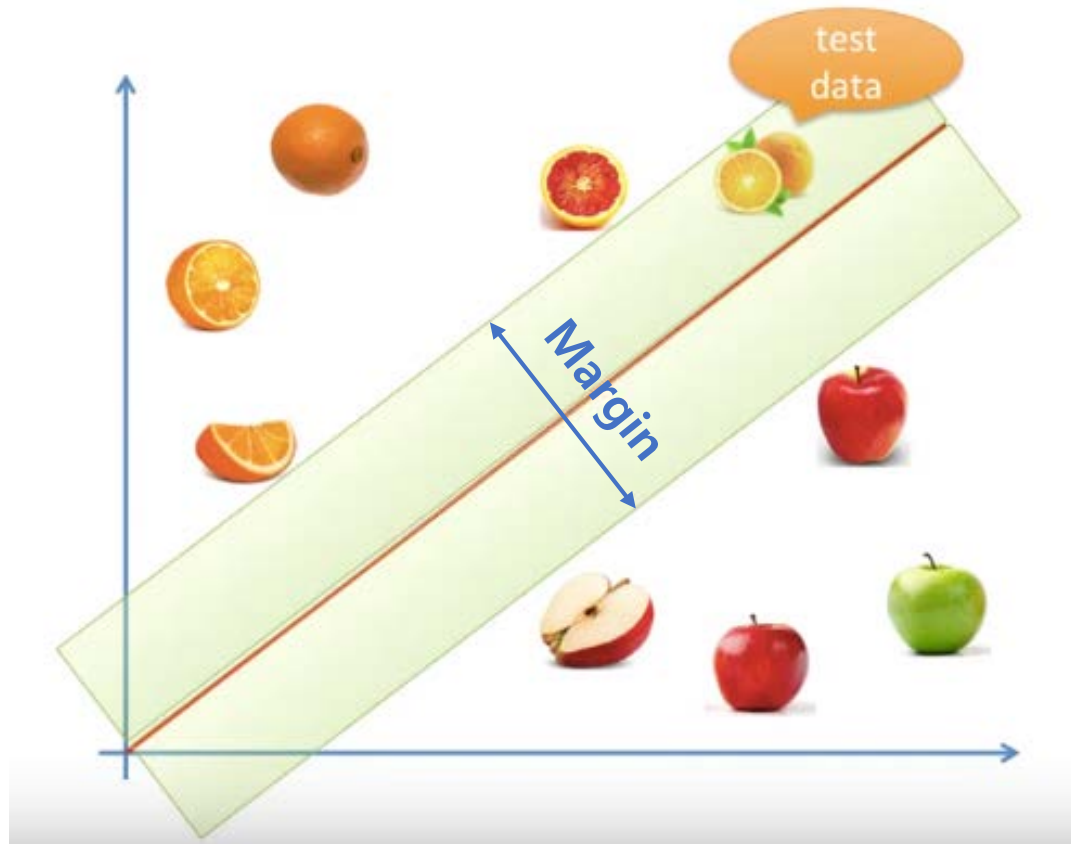
How can we decide decision boundary?

- Test data predicted well (X)



How can we decide decision boundary?

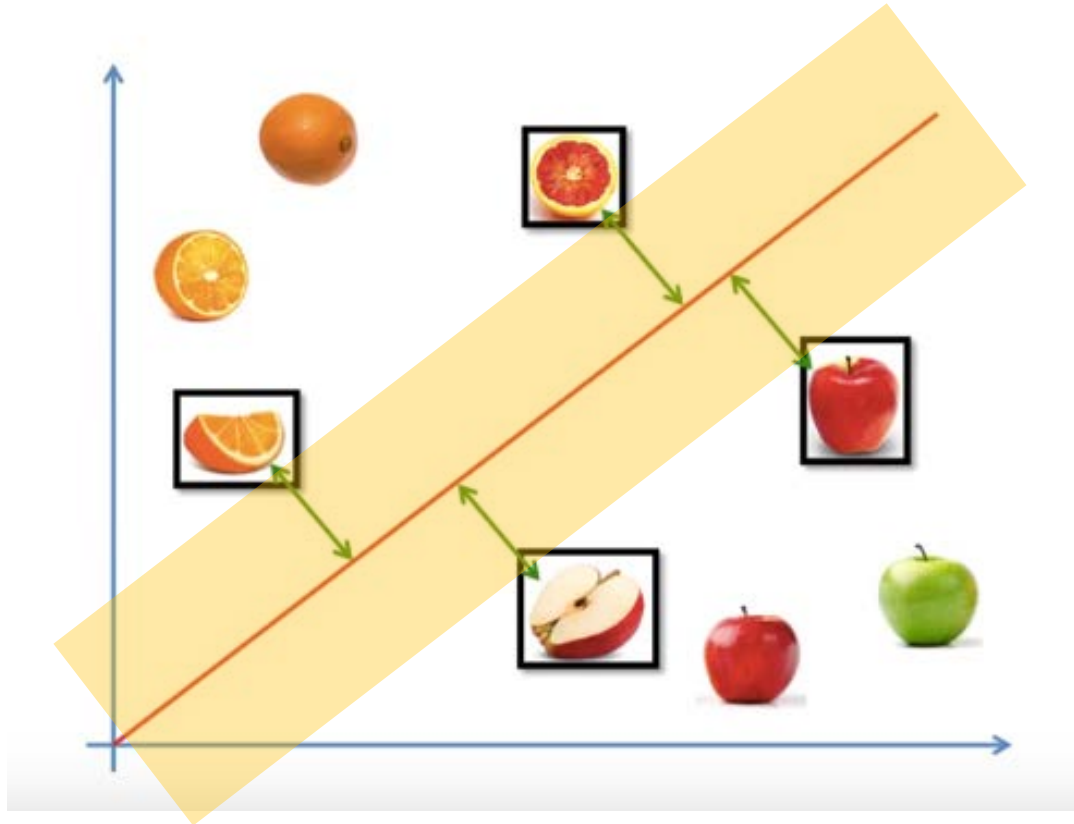
- The answer is “Large Margin”!!



Support Vector

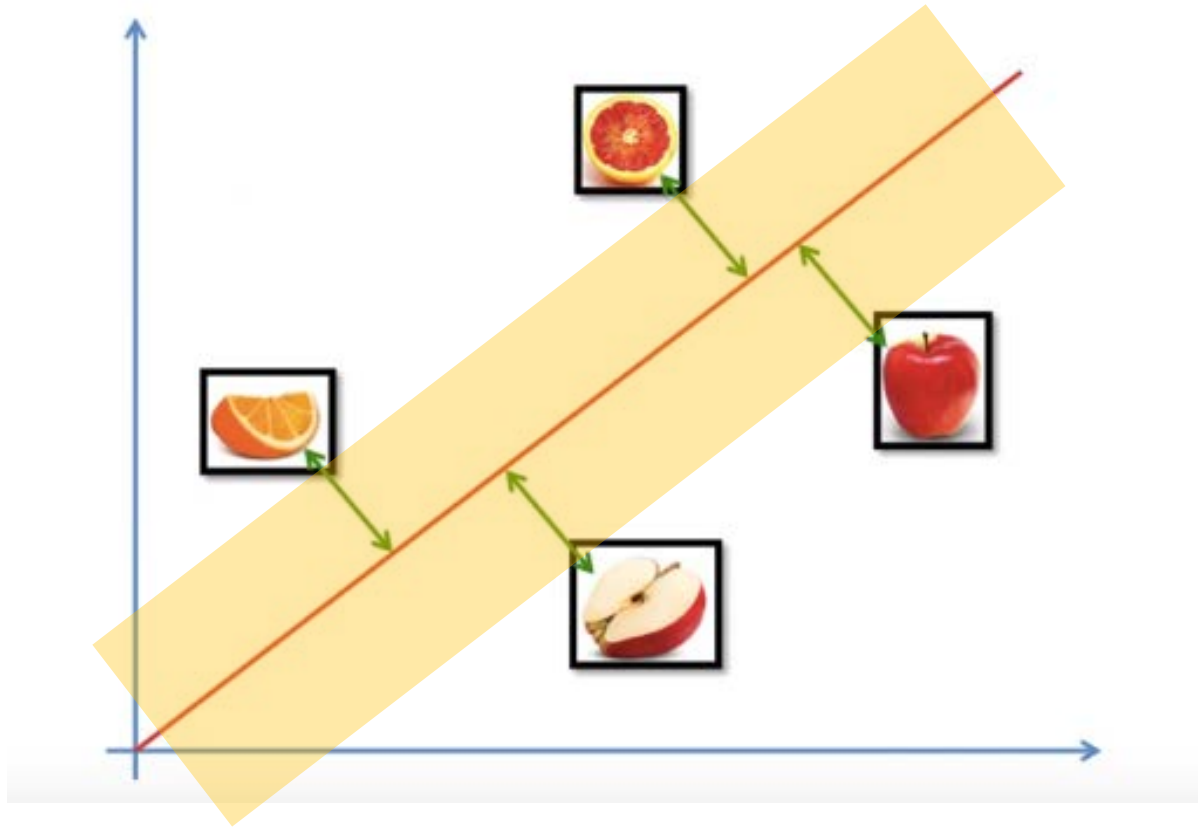
- **Support Vector**

- Samples on the margin are called the support vectors.

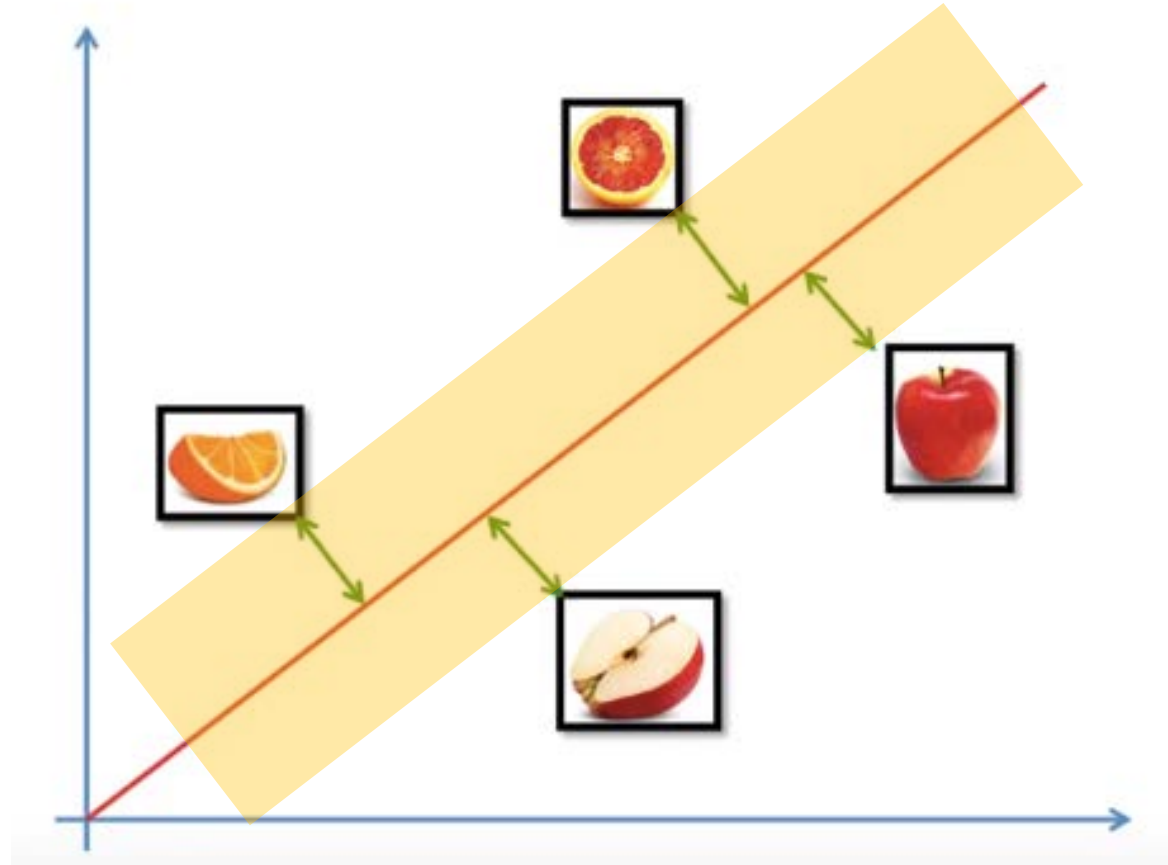


Support Vector

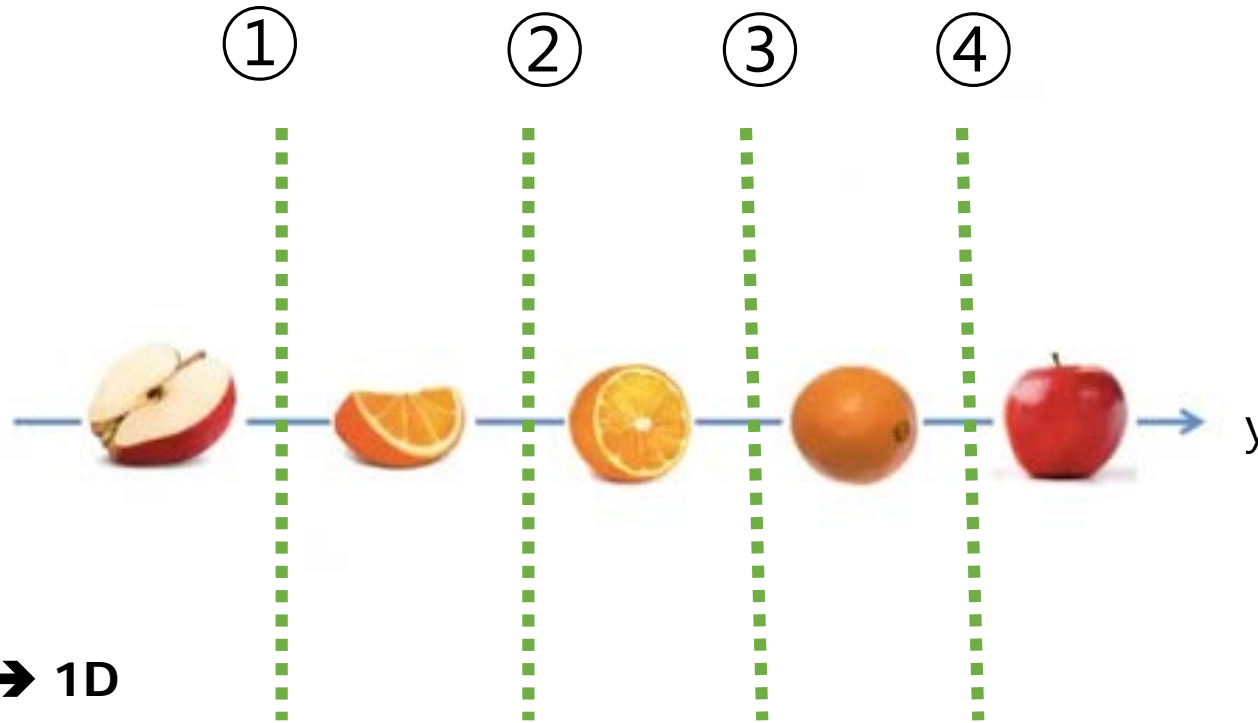
- SVM only uses support vector for prediction
 - Less computation!!!



Linearly Separable or not



What if data is not linearly separable?

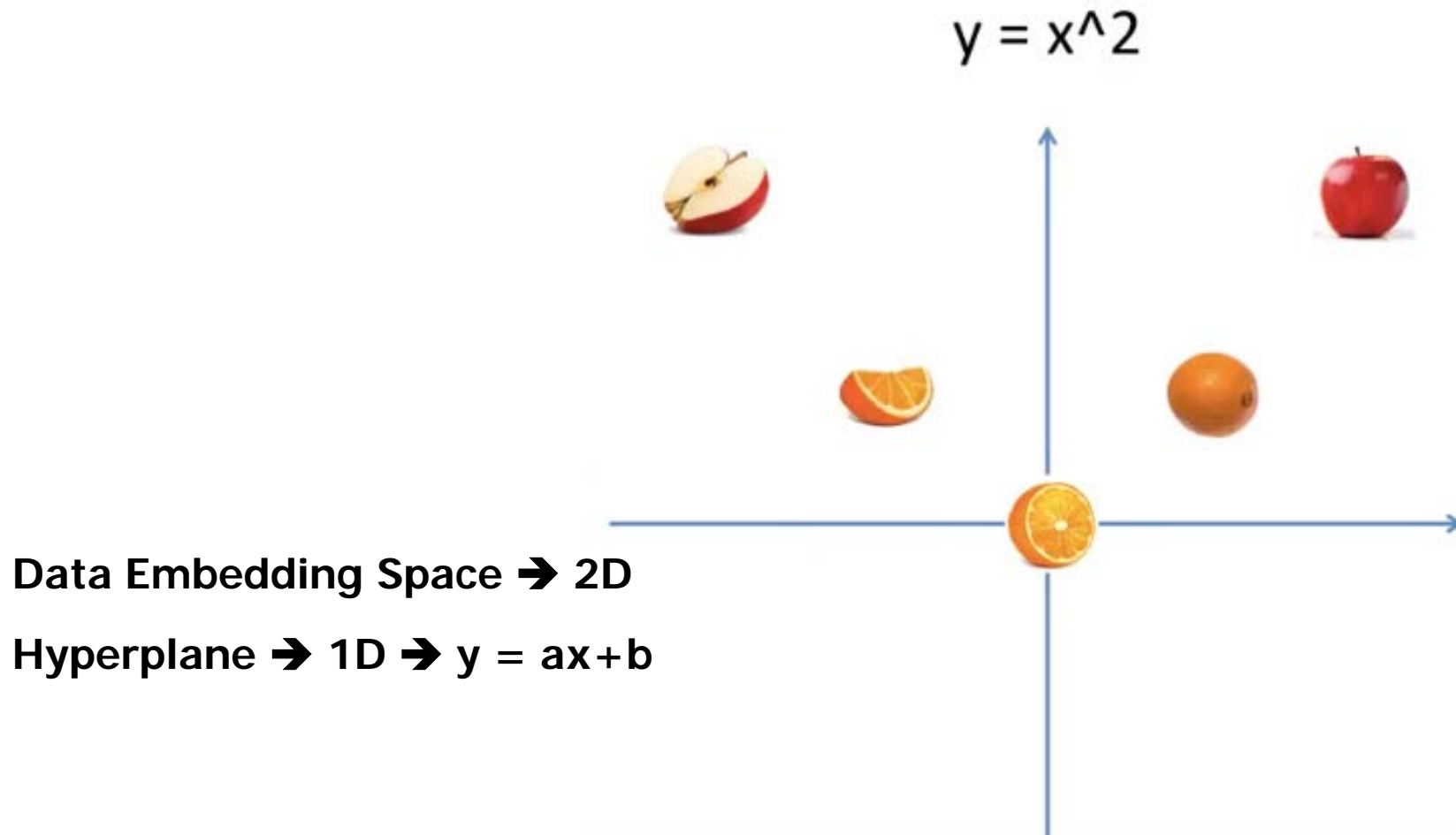


Data Embedding Space → 1D

Hyperplane → 0D → $y = b$

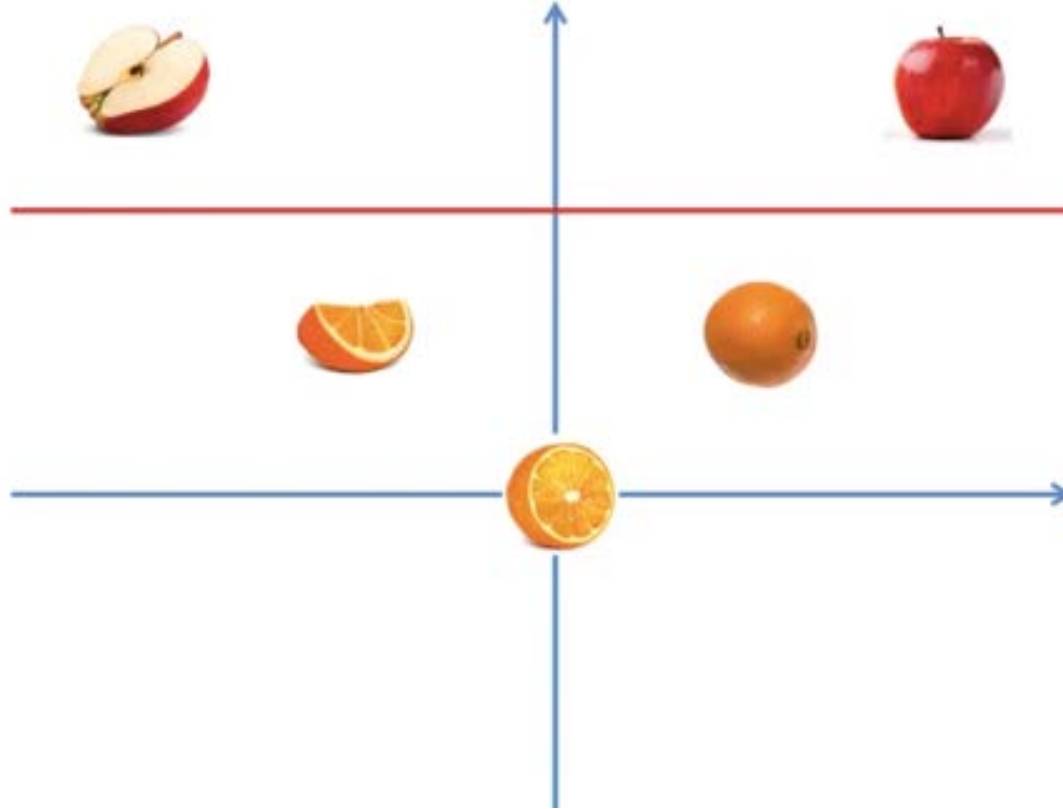
What if data is not linearly separable?

- **Mapping** lower dimension to high dimension



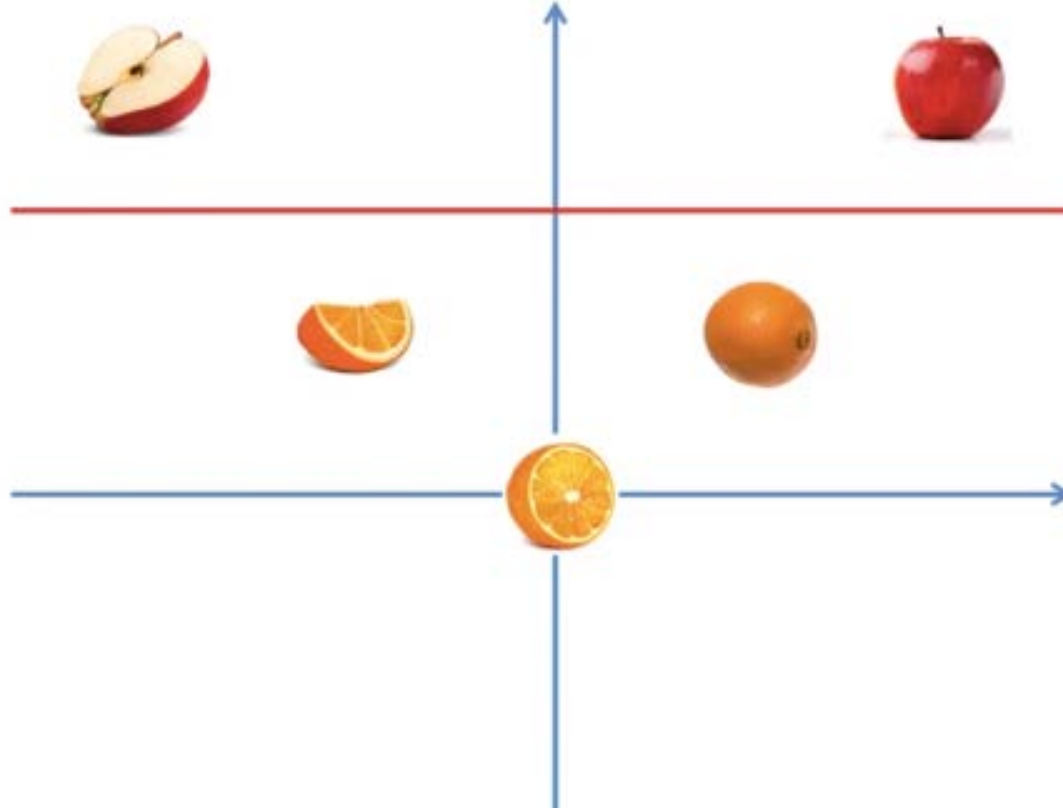
What if data is not linearly separable?

- Now it is linearly separable in higher dimension
 - Mapping to high dimension requires **much computation!**



What if data is not linearly separable?

- **Kernel trick** in SVM do this without explicitly
 - Move data point to higher dimension with **low computation!**



Kernel Trick

- The **kernel trick** avoids the explicit mapping that is needed to get linear learning algorithms.
- **Kernel methods** owe their name to the use of kernel functions, which enable them to operate in a high-dimensional, implicit feature space without ever computing the coordinates of the data in that space, but rather by **simply computing the inner products** between the images of all pairs of data in the feature space

Kernel Trick

- Kernel Function → **simply computing the inner products**

The *kernel function* can be any of the following:

- **linear**: $\langle x, x' \rangle$.
- **polynomial**: $(\gamma \langle x, x' \rangle + r)^d$. d is specified by keyword `degree`, r by `coef0`.
- **rbf**: $\exp(-\gamma \|x - x'\|^2)$. γ is specified by keyword `gamma`, must be greater than 0.
- **sigmoid** ($\tanh(\gamma \langle x, x' \rangle + r)$), where r is specified by `coef0`.

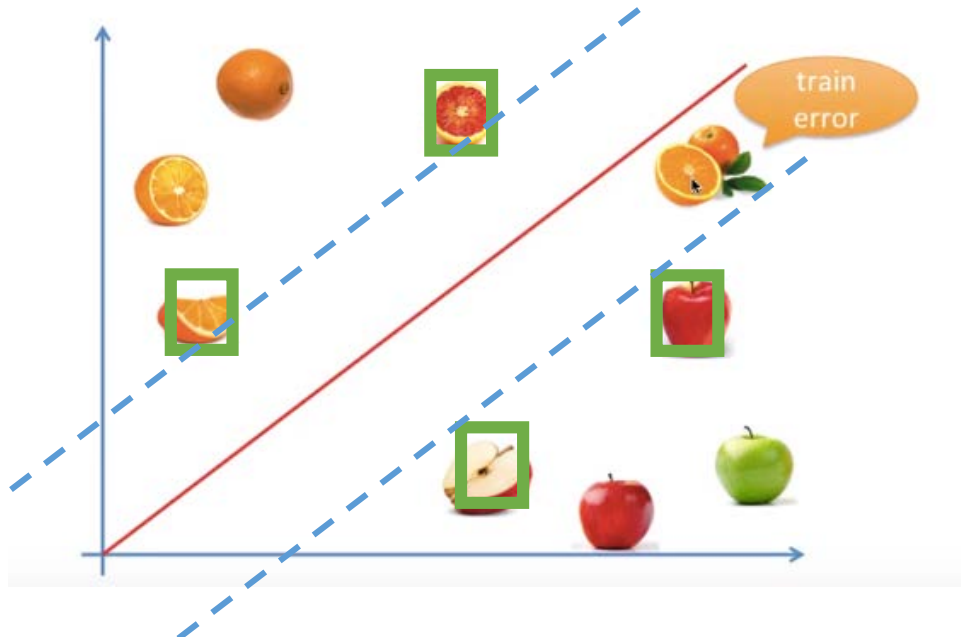
Mapping 함수의 inner-product.. Mapping ($m \rightarrow n$)

$$K(x_i, x_j) = \Phi(x_i)^T \Phi(x_j) = x_i^T A^T A x_j$$

SVM Parameter - Cost

Manually hand-tuned

- Cost is small == Margin is large



$$\min_{w,b,\zeta} \frac{1}{2} w^T w + C \sum_{i=1}^n \zeta_i \quad \text{subject to } y_i (w^T \phi(x_i) + b) \geq 1 - \zeta_i, \\ \zeta_i \geq 0, i = 1, \dots, n$$

Margin width

misclassification

C is small

Training error is allowed

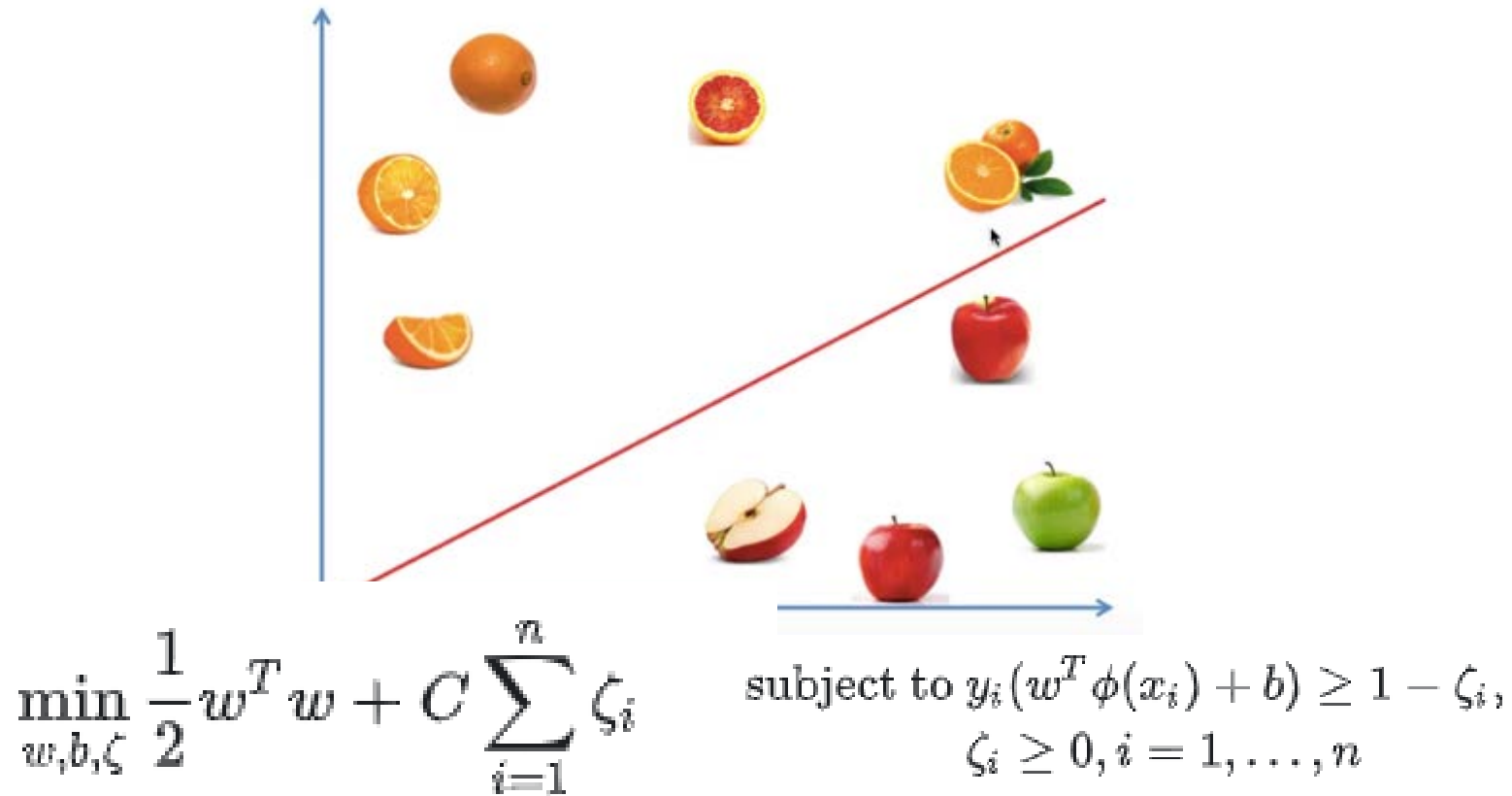
Overfitting is not allowed

Margin is large

Testing error is small

SVM Parameter - Cost

- Cost is large == Margin is small

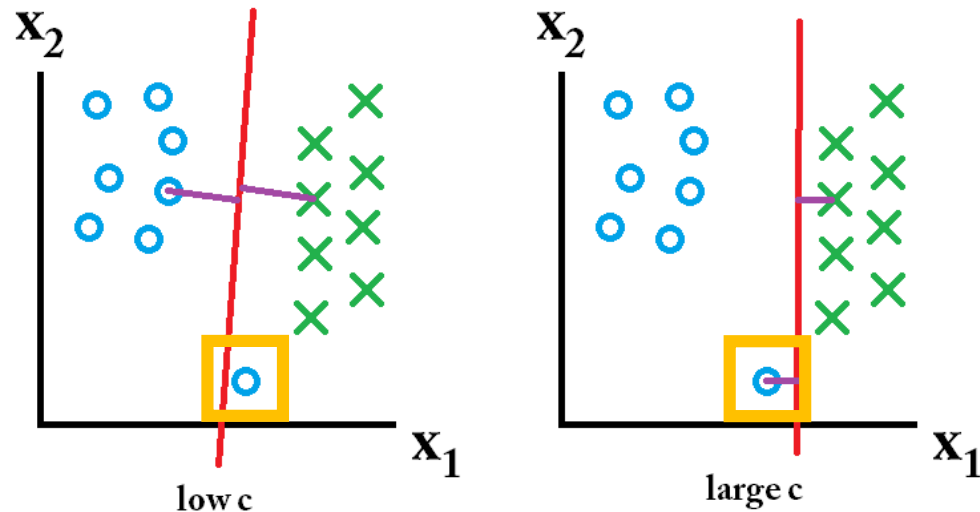


Margin width misclassification

C is large
Training error is not allowed
Overfitting is allowed
Margin is small
Testing error is large

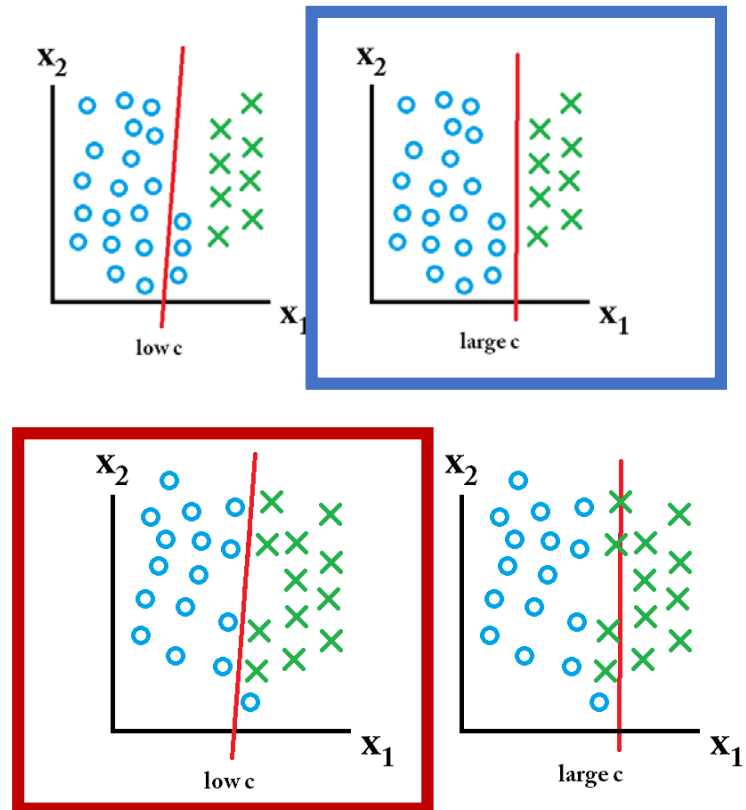
SVM Parameter - Cost

- We **assume** that some samples caused by train error are the **outlier**.
- Therefore, we generally select a **large margin** for decision boundary.
- But, if not?



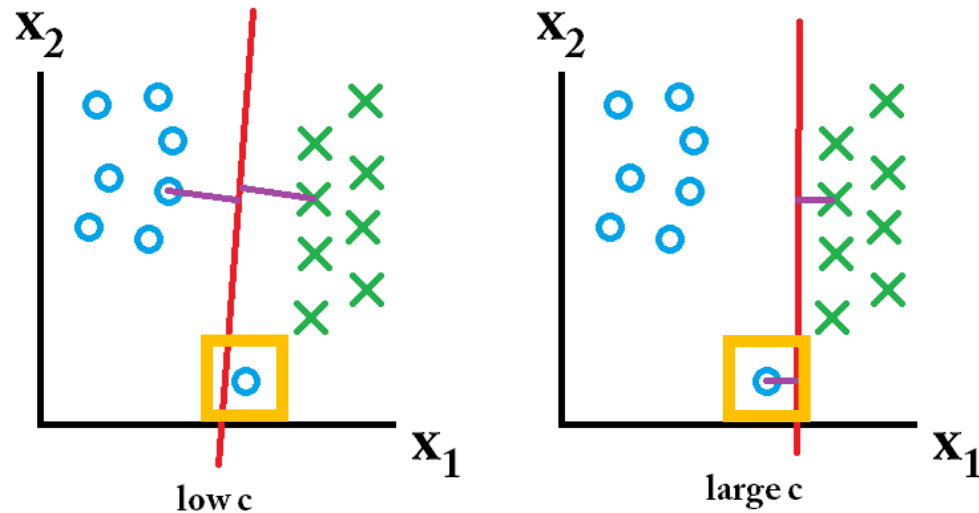
Inlier or outlier

?



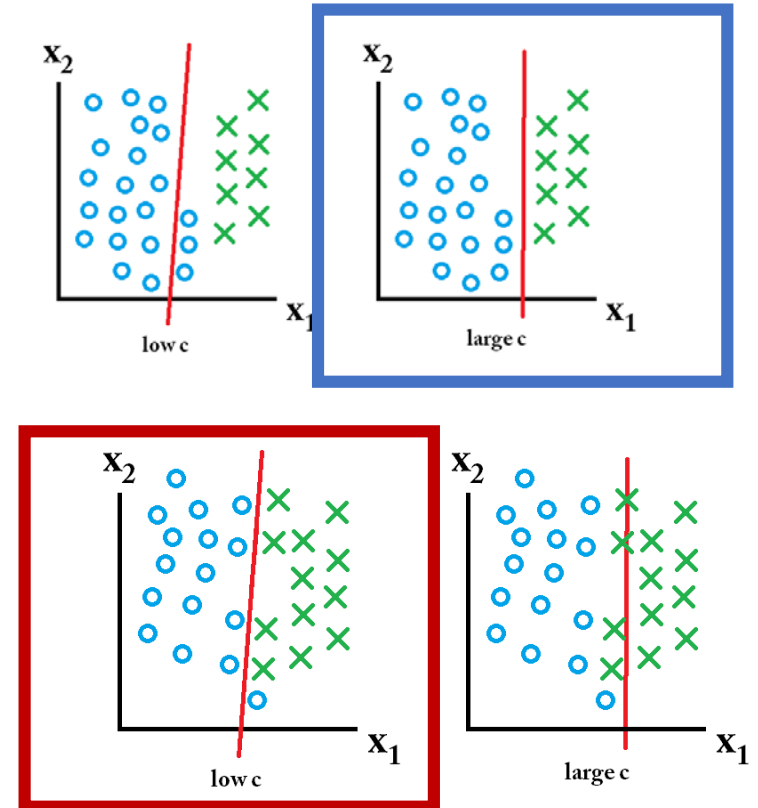
SVM Parameter - Cost

- Therefore, we cannot argue that we should choose large C , but we must make a decision through **data analysis**.

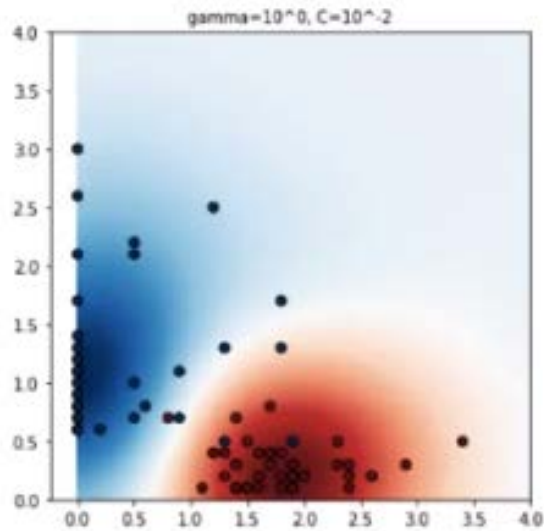


Inlier or outlier

?

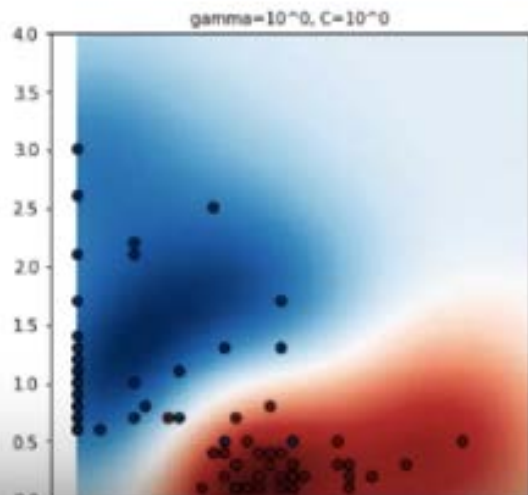


SVM Parameter - Cost



cost= 0.01

Cost is small
Training error is allowed
Overfitting is not allowed
Decision boundary is simple



cost= 1

Cost is large
Training error is allowed
Overfitting is allowed
Decision boundary is complex

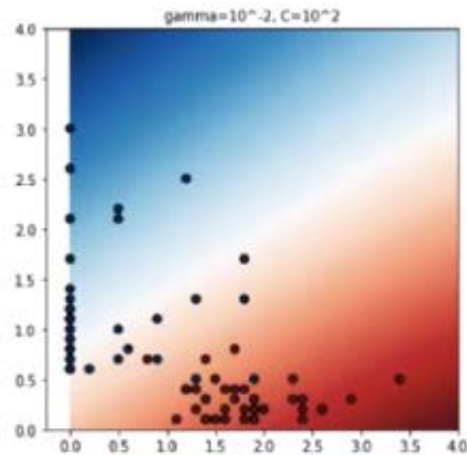
SVM parameter – Gamma in RBF kernel

- Intuitively, the **gamma parameter** defines how far the influence of a single training example reaches, with low values meaning 'far' and high values meaning 'close'.

Radial Base Function (also called Gaussian Kernel)

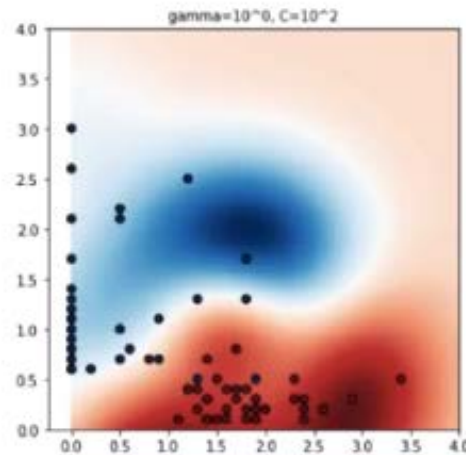
$$K(x, x') = \exp(-\gamma * ||x - x'||^2)$$

Far

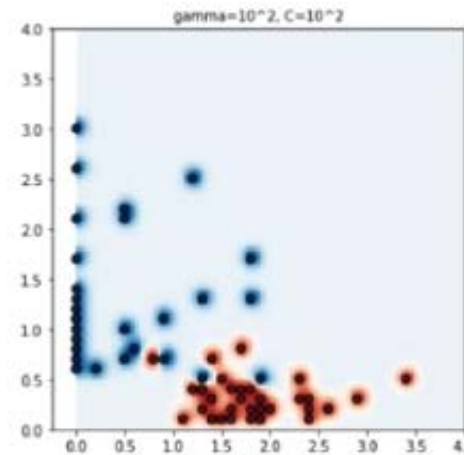


gamma = 0.01

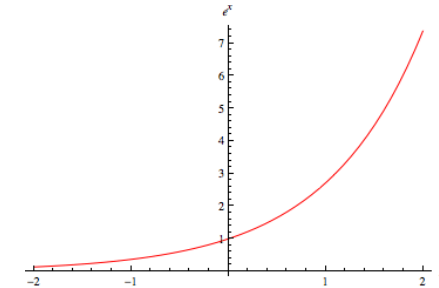
Close



gamma = 1

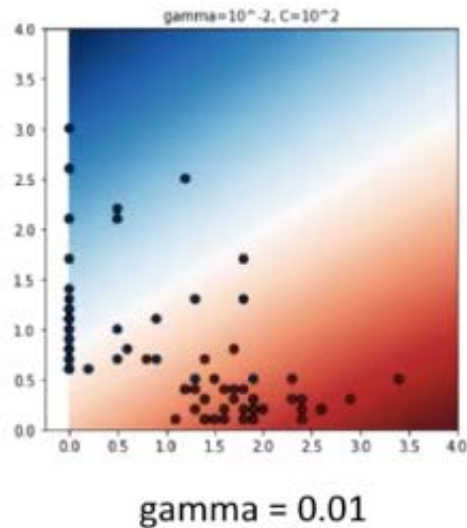


gamma = 100



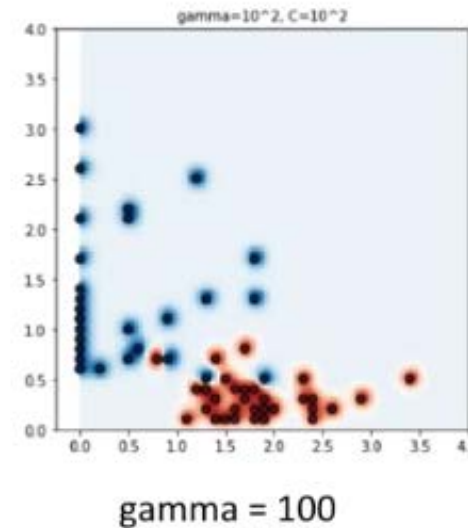
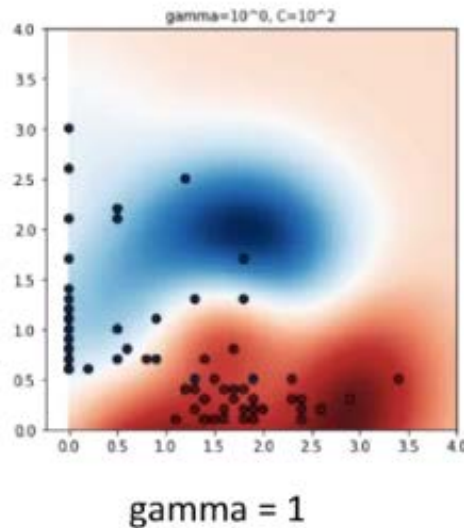
SVM parameter – Gamma in RBF kernel

Far



Gamma is small
Influence is large
Margin is large
Similarly to a linear model

Close

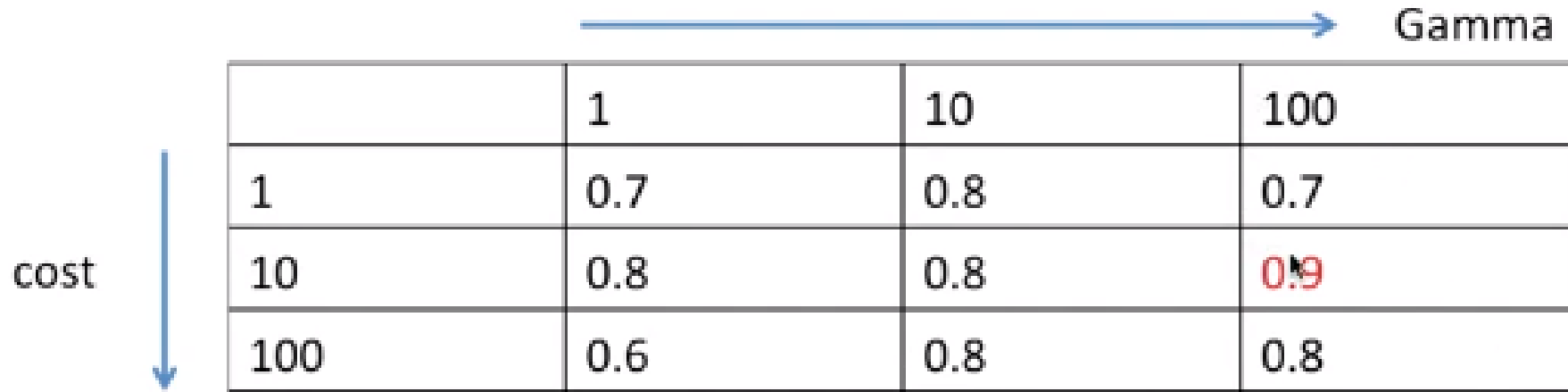


Gamma is large
Influence is small
Margin is small
Overfitting is allowed

Find optimal parameter – **data analysis**

- **Grid Search**

- **Grid search** builds a model for **every combination** of hyper-parameters specified and evaluates each model.



	1	10	100
1	0.7	0.8	0.7
10	0.8	0.8	0.9
100	0.6	0.8	0.8

Pattern Recognition

SVM 개념 잡기 II

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Previous Work

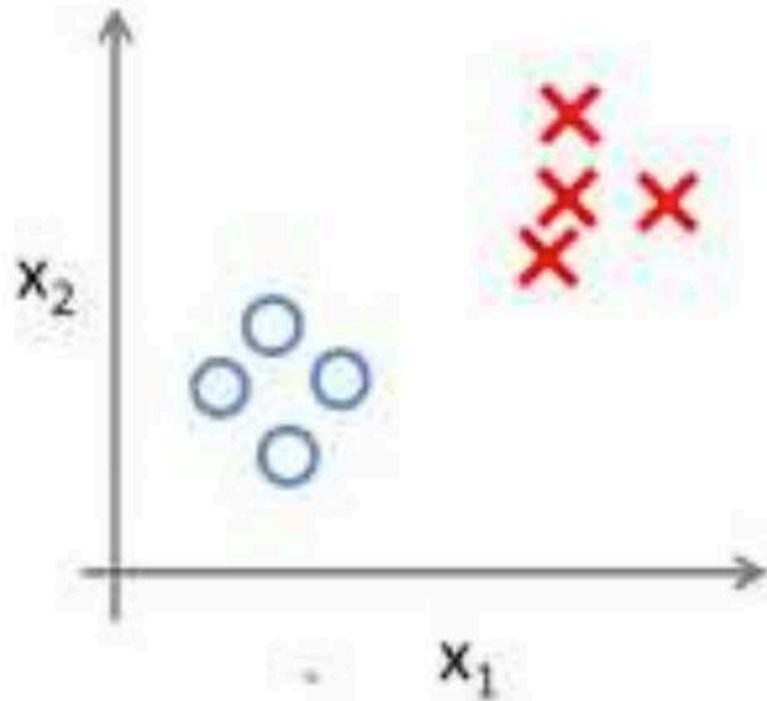
- What is a support vector
- What is a best decision boundary
- Hard-SVM
- Soft-SVM
- Parameter C
- Parameter γ

Today Lecture

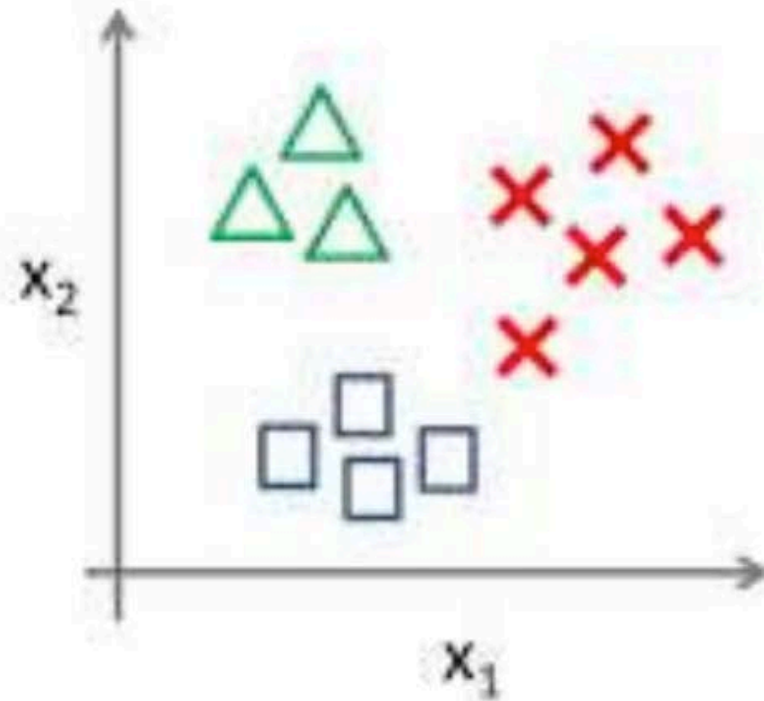
- Multiclass SVM
 - One vs One
 - One vs Rest (One vs All)
- SVM with Unbalanced Data
- SVM Optimizer

Multiclass Classification

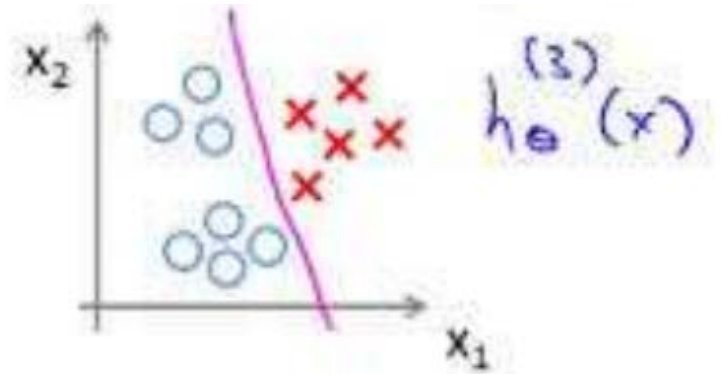
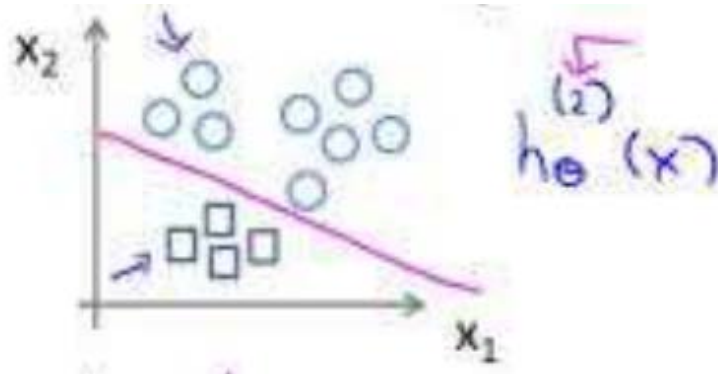
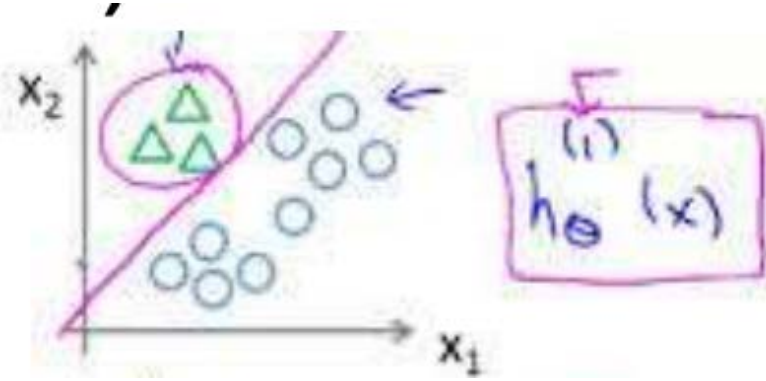
Binary classification:



Multi-class classification:



One-vs-Rest (OVR)



One-vs-Rest (OVR)

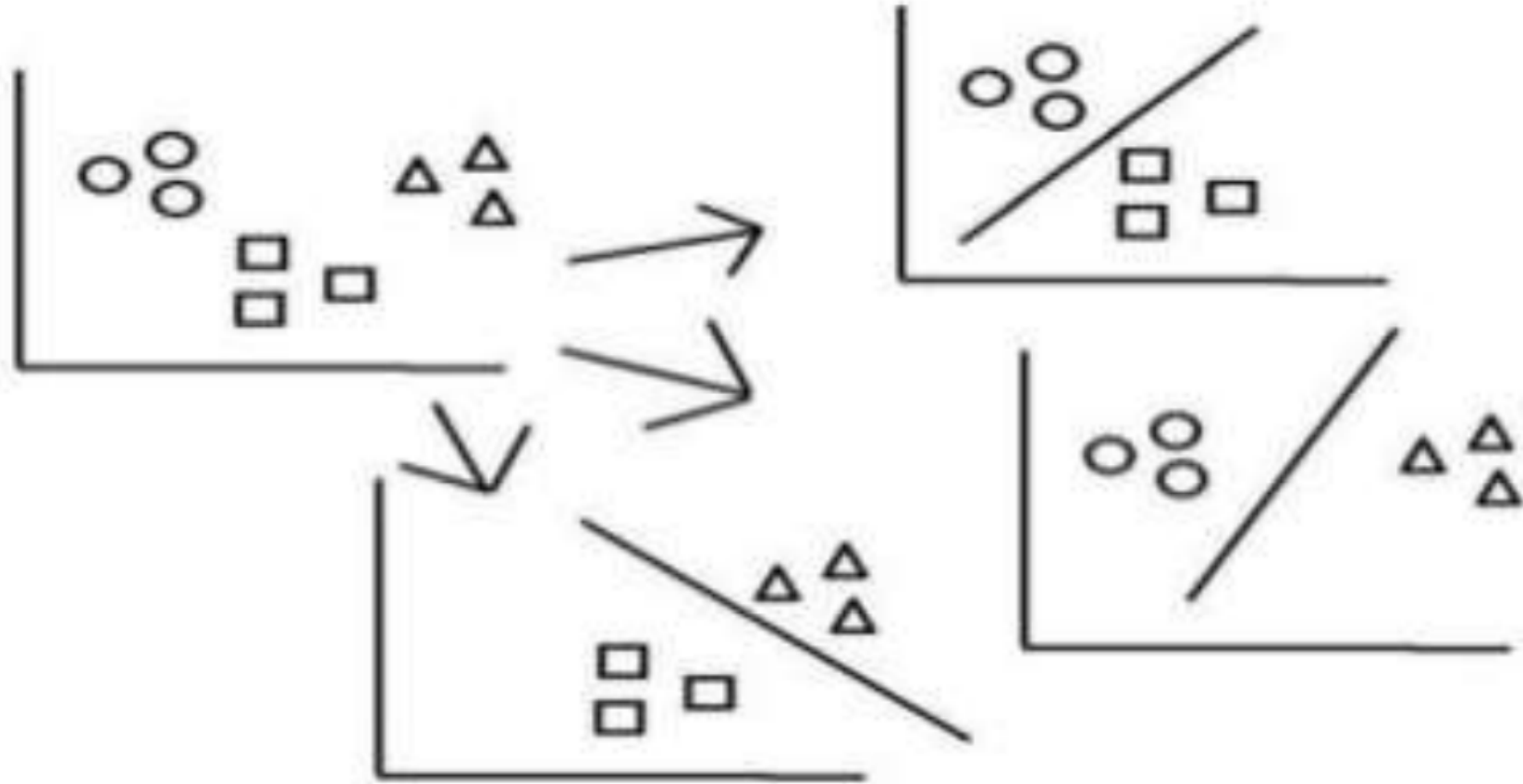
Training: Fits one classifier per class against all other data as a negative class. In total K classifiers.

Pros:

- Efficient
- Interpretable

Prediction: applies K classifiers to a new data point. Selects the one that got a positive class. In case of ties, selects the class with highest confidence.

One vs One (OvO)



One vs One (OvO)

Training: Fits $(K-1)$ classifier per class against each other class. In total $K*(K-1)/2$ classifiers.

Prediction: applies $K*(K-1)/2$ classifiers to a new data point. Selects the class that got the majority of votes (“+1”). In case of ties, selects the class with highest confidence.

Pros:

- Used for Kernel algorithms (e.g. “SVM”).

Cons:

- Not as fast as OVR

Sklearn SVM: OvO vs OvR

```
>>> X = [[0], [1], [2], [3]]
>>> Y = [0, 1, 2, 3]
>>> clf = svm.SVC(gamma='scale', decision_function_shape='ovo')
>>> clf.fit(X, Y)
SVC(C=1.0, cache_size=200, class_weight=None, coef0=0.0,
    decision_function_shape='ovo', degree=3, gamma='scale', kernel='rbf',
    max_iter=-1, probability=False, random_state=None, shrinking=True,
    tol=0.001, verbose=False)
>>> dec = clf.decision_function([[1]])
>>> dec.shape[1] # 4 classes: 4*3/2 = 6
6
>>> clf.decision_function_shape = "ovr"
>>> dec = clf.decision_function([[1]])
>>> dec.shape[1] # 4 classes
4
```

```
>>> lin_clf = svm.LinearSVC()
>>> lin_clf.fit(X, Y)
LinearSVC(C=1.0, class_weight=None, dual=True, fit_intercept=True,
    intercept_scaling=1, loss='squared_hinge', max_iter=1000,
    multi_class='ovr', penalty='l2', random_state=None, tol=0.0001,
    verbose=0)
>>> dec = lin_clf.decision_function([[1]])
>>> dec.shape[1]
4
```

Similar to SVC with parameter kernel='linear', but implemented in terms of liblinear rather than libsvm

Sklearn SVM: OvO vs OvR

Below is an example of multiclass learning using **OvO**:

```
>>> from sklearn import datasets
>>> from sklearn.multiclass import OneVsOneClassifier
>>> from sklearn.svm import LinearSVC
>>> iris = datasets.load_iris()
>>> X, y = iris.data, iris.target
>>> OneVsOneClassifier(LinearSVC(random_state=0)).fit(X, y).predict(X)
array([0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
       0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
       0, 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
       1, 2, 1, 2, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
       1, 1, 1, 1, 1, 1, 1, 1, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
       2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2,
       2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2])
```

«

1.12.2.1. Multiclass learning

Below is an example of multiclass learning using **OvR**:

```
>>> from sklearn import datasets
>>> from sklearn.multiclass import OneVsRestClassifier
>>> from sklearn.svm import LinearSVC
>>> iris = datasets.load_iris()
>>> X, y = iris.data, iris.target
>>> OneVsRestClassifier(LinearSVC(random_state=0)).fit(X, y).predict(X)
array([0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
       0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0,
       0, 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1,
       1, 2, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 2, 2, 1, 1, 1, 1, 1, 1,
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       2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2, 2])
```

Colab 실습

- 지난 시간 SVM 열어 확인

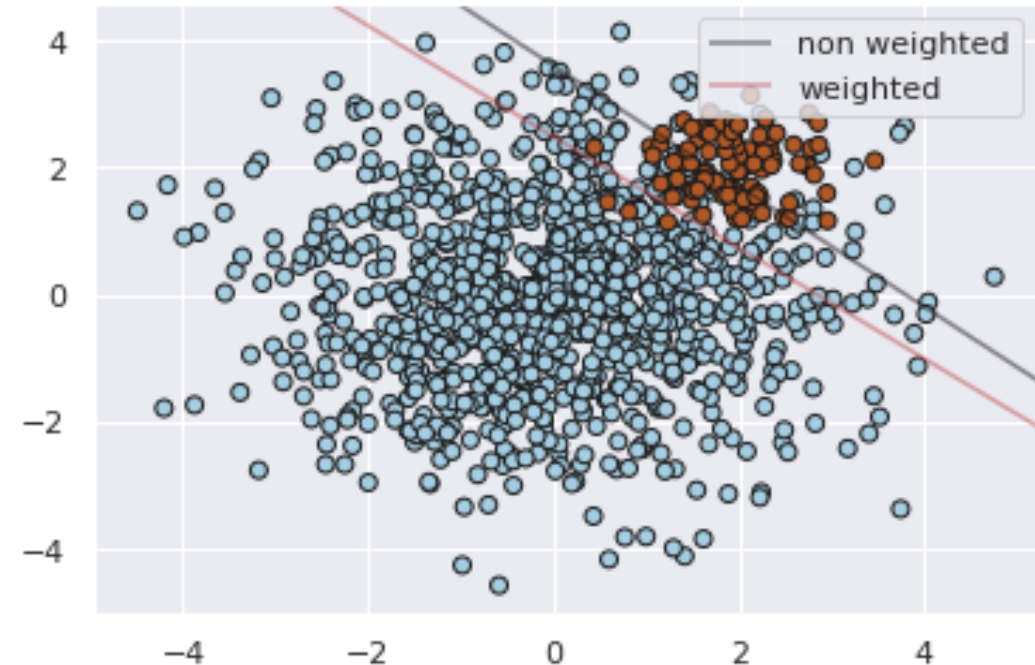
Unbalanced problems

- Sklearn: class_weight

```
n_samples_1 = 1000  
n_samples_2 = 100
```

```
# 1번 클래스에 10배 가중치;;  
# 샘플 비율 차이만큼 가중치
```

```
wclf = svm.SVC(kernel='linear', class_weight={1: 10})  
wclf.fit(X, y)
```



Sklearn SVM OvR 에서는 default로 Unbalanced Problem을 해결해주지 않음

Unbalanced problems

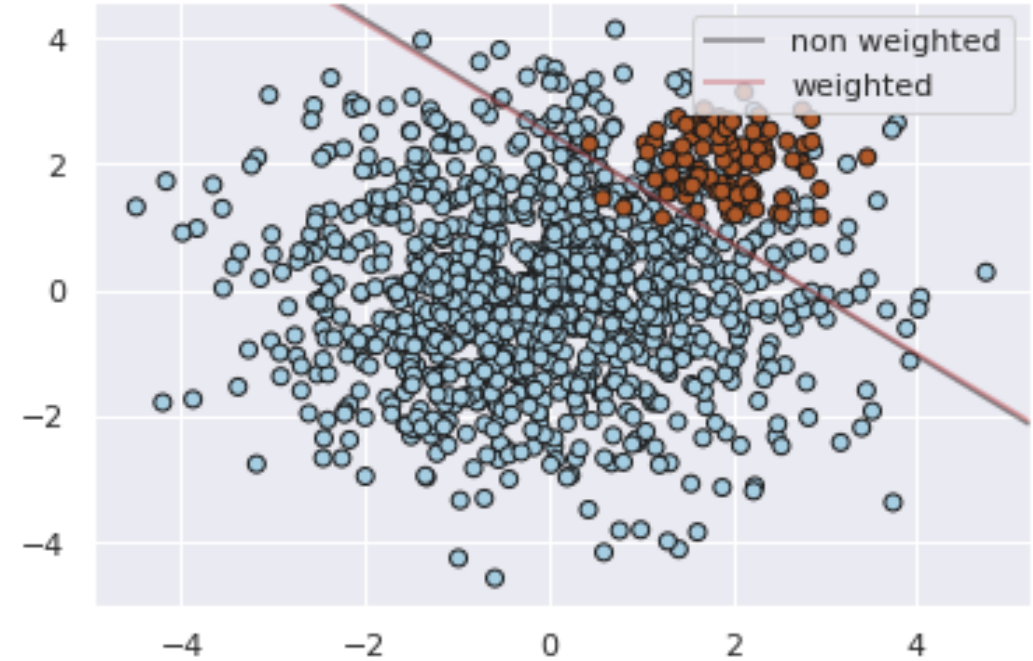
- Sklearn: `class_weight`

```
n_samples_1 = 1000  
n_samples_2 = 100
```

```
# 1번 클래스에 10배 가중치;;  
# 샘플 비율 차이만큼 가중치
```

```
wclf = svm.SVC(kernel='linear', class_weight='balanced')  
wclf.fit(X, y)
```

Sklearn SVM 옵션으로 `class_weight='balanced'`



Colab 실습

- 지난 시간 SVM 열어 확인

Pattern Recognition

SVM 개념 잡기 III

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SVM Optimization

❖ 여백은 아래와 같이 공식화

$$\text{여백} = 2h = \frac{2|d(\mathbf{x})|}{\|\mathbf{w}\|} = \frac{2}{\|\mathbf{w}\|} \quad (5.4)$$

❖ 이제 문제를 **조건부 최적화 문제**로 공식화

• 조건부 최적화 문제

아래 조건 하에,

$$\mathbf{w}^T \mathbf{x}_i + b \geq 1, \forall \mathbf{x}_i \in \omega_1$$

$$\mathbf{w}^T \mathbf{x}_i + b \leq -1, \forall \mathbf{x}_i \in \omega_2$$

$\frac{2}{\|\mathbf{w}\|}$ 를 최대화하라.

(5.5)

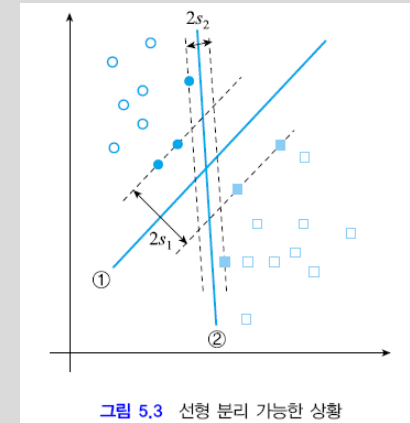


그림 5.3 선형 분리 가능한 상황

❖ 훈련 집합 $X = \{(\mathbf{x}_1, t_1), \dots, (\mathbf{x}_N, t_N)\}$

SVM Optimization

❖ (5.5)를 간단한 형태로 변형하면,

- 조건부 최적화 문제

아래 조건 하에,

$$\left. \begin{array}{l} t_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 \geq 0, i = 1, \dots, N \\ J(\mathbf{w}) = \frac{1}{2} \|\mathbf{w}\|^2 \text{ 을 최소화하라.} \end{array} \right\} \quad (5.6)$$

$$\begin{array}{l} \mathbf{w}^T \mathbf{x}_i + b \geq 1, \forall \mathbf{x}_i \in \omega_1 \\ \mathbf{w}^T \mathbf{x}_i + b \leq -1, \forall \mathbf{x}_i \in \omega_2 \end{array} \quad t_i \text{ 를 통해 합쳐 쓰고}$$

최대화 문제 → 최소화 문제로 변경

❖ 문제의 특성

❖ 해의 유일성

❖ (5.6)은 볼록이므로 해는 유일하다.

❖ 따라서 구한 해는 **전역 최적 점을 보장한다.** (Convex Optimization!!)

❖ 문제의 난이도

❖ N 개의 선형 부등식을 조건으로 가진 2차 함수의 최적화 문제

❖ **조건부 최적화 문제는 “라그랑제 승수”로 푼다.** (11.2.3 절)

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❖ 문제의 볼록 성질을 이용하여 풀기 쉬운 형태로 변환 (prime \rightarrow dual)

❖ 볼록 성질을 만족하는 조건부 최적화 문제는 **Wolfe 듀얼**로 변형할 수 있다.

볼록 성질을 만족하는 조건부 최적화 문제는 Wolfe 듀얼 문제로 변형할 수 있다. 원래 문제가 $f_i(\theta) \geq 0, i = 1, \dots, N$ 이라는 조건 하에 $J(\theta)$ 를 최소화하는 것이라 하자. 이때 Wolfe 듀얼 문제는 $\partial L(\theta, \alpha) / \partial \theta = 0$ 과 $\alpha_i \geq 0, i = 1 \dots, N$ 이라는 두 가지 조건 하에 $L(\theta, \alpha) = J(\theta) - \sum_{i=1}^N \alpha_i f_i(\theta)$ 를 최대화하는 것이다. 부등식 조건이 등식 조건으로 바뀌었고 최소화 문제가 최대화 문제로 바뀌었다.

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❖ 라그랑제 승수 방법

- ① 목적 함수와 조건을 하나의 식 (즉, 라그랑제 함수 L)으로 만들고,
- ② KKT조건을 이용 (변수 제거)
- ③ 라그랑제 함수를 최소화하는 해를 구한다. (α_i 는 라그랑제 승수만으로 구성된 식)

- ① 목적 함수와 조건을 하나의 식 (즉, 라그랑제 함수 L)으로 만들고,

라그랑제 함수 $L(\theta, \lambda) = J(\theta) - \sum_{i=1, N} \lambda_i f_i(\theta)$



$$L(\mathbf{w}, b, \alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \alpha_i (t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1)$$

$t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1 \geq 0, i = 1, \dots, N$

$J(\mathbf{w}) = \frac{1}{2} \|\mathbf{w}\|^2$ 을 최소화하라.

$f(\mathbf{w}, b)$

(5.7)

SVM Optimization

② KKT조건을 이용 (변수 제거)

❖ (5.7)의 KKT 조건



$$\frac{\partial L(\mathbf{w}, b, \boldsymbol{\alpha})}{\partial \mathbf{w}} = 0 \rightarrow \mathbf{w} = \sum_{i=1}^N \alpha_i t_i \mathbf{x}_i \quad (5.8)$$

$$\frac{\partial L(\mathbf{w}, b, \boldsymbol{\alpha})}{\partial b} = 0 \rightarrow \sum_{i=1}^N \alpha_i t_i = 0 \quad (5.9)$$

$$\alpha_i \geq 0, i = 1, \dots, N \quad (5.10)$$

$$\alpha_i (t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) = 0, i = 1, \dots, N \quad (5.11)$$

$$\textcircled{1} \quad \partial L(\boldsymbol{\theta}, \boldsymbol{\lambda}) / \partial \boldsymbol{\theta} = 0$$

$$\textcircled{2} \quad \lambda_i \geq 0, i = 1, \dots, N$$

$$\textcircled{3} \quad \lambda_i f_i(\boldsymbol{\theta}) = 0, i = 1, \dots, N$$

$$L(\mathbf{w}, b, \boldsymbol{\alpha}) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \alpha_i (t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1)$$

❖ (5.11)에 의하면 모든 샘플이 $\alpha_i = 0$ 또는 $t_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 = 0$ 이어야 함. $\boldsymbol{\alpha} \neq \mathbf{0}$ 인 샘플이 서포트 벡터임

❖ (5.8)에 의하면, **라그랑제 승수 $\boldsymbol{\alpha}$ 알면 \mathbf{w} 구할 수 있음 (결정 초평면을 구한 셈)**

❖ 이제부터 ' \mathbf{w} 구하는 대신 라그랑제 승수 구하는' 문제로 관심 전환

❖ (5.11)로 **b 구할 수 있음**

SVM Optimization

❖ (5.6)을 Wolfe 듀얼로 바꾸어 쓰면,

- 조건부 최적화 문제

$$\left. \begin{array}{l} \text{아래 조건 하에,} \\ t_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 \geq 0, i = 1, \dots, N \\ J(\mathbf{w}) = \frac{1}{2} \|\mathbf{w}\|^2 \text{ 을 최소화하라.} \end{array} \right\} \quad (5.6)$$

❖ 5.8~5.10



- 조건부 최적화 문제

$$\left. \begin{array}{l} \text{아래 조건 하에,} \\ \mathbf{w} = \sum_{i=1}^N \alpha_i t_i \mathbf{x}_i \\ \sum_{i=1}^N \alpha_i t_i = 0 \\ \alpha_i \geq 0, i = 1, 2, \dots, N \\ L(\mathbf{w}, b, \alpha) \text{ 를 최대화하라.} \end{array} \right\} \quad (5.12)$$

- 조건부 최적화 문제

$$\left. \begin{array}{l} \text{아래 조건 하에,} \\ t_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 \geq 0, i = 1, \dots, N \\ J(\mathbf{w}) = \frac{1}{2} \|\mathbf{w}\|^2 \text{ 을 최소화하라.} \end{array} \right\}$$

(Due to KKT Condition)

$$\frac{\partial L(\mathbf{w}, b, \alpha)}{\partial \mathbf{w}} = 0 \rightarrow \mathbf{w} = \sum_{i=1}^N \alpha_i t_i \mathbf{x}_i \quad (5.8)$$

$$\frac{\partial L(\mathbf{w}, b, \alpha)}{\partial b} = 0 \rightarrow \sum_{i=1}^N \alpha_i t_i = 0 \quad (5.9)$$

$$\alpha_i \geq 0, i = 1, \dots, N \quad (5.10)$$

$$\alpha_i (t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) = 0, i = 1, \dots, N \quad (5.11)$$

SVM Optimization

❖ 간단한 수식 정리를 하면,

• 조건부 최적화 문제

아래 조건 하에,

$$\sum_{i=1}^N \alpha_i t_i = 0$$

$$\alpha_i \geq 0, i = 1, \dots, N$$

$$\tilde{L}(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j t_i t_j \mathbf{x}_i^T \mathbf{x}_j \text{ 를 최대화하라.}$$

최소화 문제 → 최대화 문제

$$L(\mathbf{w}, b, \alpha) = \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^N \alpha_i (t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) \quad (5.7)$$

(5.9)식으로 앞 식 삭제

$$L(\mathbf{w}, b, \alpha) = \sum_{i=1}^N \alpha_i (t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) - \frac{1}{2} \|\mathbf{w}\|^2 \quad (5.7)$$

(5.13)

$$\frac{\partial L(\mathbf{w}, b, \alpha)}{\partial \mathbf{w}} = 0 \rightarrow \mathbf{w} = \sum_{i=1}^N \alpha_i t_i \mathbf{x}_i \quad (5.8)$$

$$\frac{\partial L(\mathbf{w}, b, \alpha)}{\partial b} = 0 \rightarrow \sum_{i=1}^N \alpha_i t_i = 0 \quad (5.9)$$

$$\alpha_i \geq 0, i = 1, \dots, N \quad (5.10)$$

$$\alpha_i (t_i (\mathbf{w}^T \mathbf{x}_i + b) - 1) = 0, i = 1, \dots, N \quad (5.11)$$

❖ 흥미로운 특성들

❖ 2차 함수의 최대화 문제임

❖ \mathbf{w} 와 b 가 사라졌다. (α 를 찾는 문제가 되었다.)

❖ 특징 벡터 \mathbf{x}_j 가 내적 형태로 나타난다. (비선형으로 확장하는 발판)

❖ 목적 함수의 두번째 Σ 항은 N^2 개의 항을 갖는다. (여전히 풀기 어려운 문제)

SVM Optimization

- 조건부 최적화 문제

$$\left. \begin{array}{l} \text{아래 조건 하에,} \\ t_i(\mathbf{w}^T \mathbf{x}_i + b) - 1 \geq 0, i = 1, \dots, N \\ J(\mathbf{w}) = \frac{1}{2} \|\mathbf{w}\|^2 \text{ 을 최소화하라.} \end{array} \right\} \quad (5.6)$$



- 조건부 최적화 문제

$$\left. \begin{array}{l} \text{아래 조건 하에,} \\ \sum_{i=1}^N \alpha_i t_i = 0 \\ \alpha_i \geq 0, i = 1, \dots, N \\ \tilde{L}(\boldsymbol{\alpha}) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j t_i t_j \mathbf{x}_i^T \mathbf{x}_j \text{ 를 최대화하라.} \end{array} \right\} \quad (5.13)$$

SVM Optimization

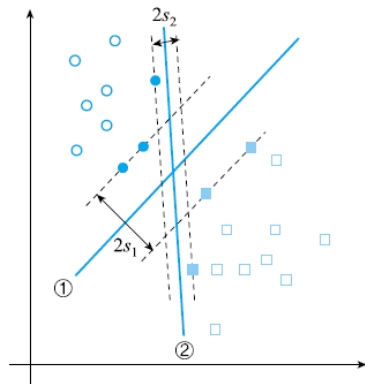


그림 5.3 선형 분리 가능한 상황

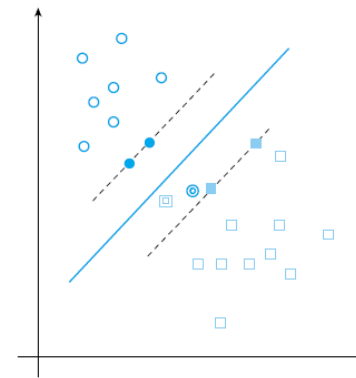


그림 5.6 선형 분리 불가능한 상황의 SVM

- 조건부 최적화 문제

아래 조건 하에,

$$\left. \begin{aligned} \sum_{i=1}^N \alpha_i t_i &= 0 \\ \alpha_i &\geq 0, i=1, \dots, N \end{aligned} \right\} \quad (5.13)$$

$\tilde{L}(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j t_i t_j \mathbf{x}_i^T \mathbf{x}_j$ 를 최대화하라.

- 조건부 최적화 문제 (선형 SVM)

아래 조건 하에,

$$\left. \begin{aligned} \sum_{i=1}^N \alpha_i t_i &= 0 \\ 0 \leq \alpha_i \leq C, i=1, \dots, N \end{aligned} \right\} \quad (5.27)$$

$\tilde{L}(\alpha) = \sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \alpha_i \alpha_j t_i t_j \mathbf{x}_i^T \mathbf{x}_j$ 를 최대화하라.

쉬운 방정식으로 변경했으나, N이 크면 여전히 분석적으로 최적화 하기는 어렵다.
결국 수치적(수치해석..)으로 풀어야 한다.

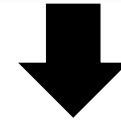
Solution: Quadratic Programming(Q.P)

$$\begin{aligned} \min \quad & \frac{1}{2} x^T P x + q^T x \\ \text{s.t.} \quad & Gx \leq h \\ & Ax = b \end{aligned}$$

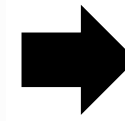
`cvxopt.solvers.qp(P, q, G, h, A, b)`

$$\max_{\alpha} \sum_i^m \alpha_i - \frac{1}{2} \sum_{i,j}^m y^{(i)} y^{(j)} \alpha_i \alpha_j < x^{(i)} x^{(j)} >$$

$$H_{i,j} = y^{(i)} y^{(j)} < x^{(i)} x^{(j)} >$$



$$\begin{aligned} \max_{\alpha} \quad & \sum_i^m \alpha_i - \frac{1}{2} \alpha^T \mathbf{H} \alpha \\ \text{s.t.} \quad & \alpha_i \geq 0 \\ & \sum_i^m \alpha_i y^{(i)} = 0 \end{aligned}$$



$$\begin{aligned} \min_{\alpha} \quad & \frac{1}{2} \alpha^T \mathbf{H} \alpha - \mathbf{1}^T \alpha \\ \text{s.t.} \quad & -\alpha_i \leq 0 \\ & y^T \alpha = 0 \end{aligned}$$

- $P := H$ a matrix of size $m \times m$
- $q := -\vec{1}$ a vector of size $m \times 1$
- $G := -\text{diag}[1]$ a diagonal matrix of -1s of size $m \times m$
- $h := \vec{0}$ a vector of zeros of size $m \times 1$
- $A := y$ the label vector of size $m \times 1$
- $b := 0$ a scalar

Computing matrix H

Consider the simple example with 2 input samples $\{x^{(1)}, x^{(2)}\} \in \mathbb{R}^2$ which are two dimensional vectors. i.e. $x^{(1)} = (x_1^{(1)}, x_2^{(1)})^T$

$$X = \begin{bmatrix} x_1^{(1)} & x_2^{(1)} \\ x_1^{(2)} & x_2^{(2)} \end{bmatrix} \quad y = \begin{bmatrix} y^{(1)} \\ y^{(2)} \end{bmatrix}$$

We now proceed to creating a new matrix X' where each input sample x is multiplied by the corresponding output label y . This can be done easily in Numpy using vectorization and padding.

$$X' = \begin{bmatrix} x_1^{(1)}y^{(1)} & x_2^{(1)}y^{(1)} \\ x_1^{(2)}y^{(2)} & x_2^{(2)}y^{(2)} \end{bmatrix} \quad \Rightarrow X' = y \cdot x$$

Finally we take the **matrix multiplication** of X' and its transpose giving $H = X'X'^T$

$$H = X' @ X'^T = \begin{bmatrix} x_1^{(1)}y^{(1)} & x_2^{(1)}y^{(1)} \\ x_1^{(2)}y^{(2)} & x_2^{(2)}y^{(2)} \end{bmatrix} \begin{bmatrix} x_1^{(1)}y^{(1)} & x_1^{(2)}y^{(2)} \\ x_2^{(1)}y^{(1)} & x_2^{(2)}y^{(2)} \end{bmatrix}$$
$$H = \begin{bmatrix} x_1^{(1)}x_1^{(1)}y^{(1)}y^{(1)} + x_2^{(1)}x_2^{(1)}y^{(1)}y^{(1)} & x_1^{(1)}x_1^{(2)}y^{(1)}y^{(2)} + x_2^{(1)}x_2^{(2)}y^{(1)}y^{(2)} \\ x_1^{(2)}x_1^{(1)}y^{(2)}y^{(1)} + x_2^{(2)}x_2^{(1)}y^{(2)}y^{(1)} & x_1^{(2)}x_1^{(2)}y^{(2)}y^{(2)} + x_2^{(2)}x_2^{(2)}y^{(2)}y^{(2)} \end{bmatrix}$$

SVM Implementation from scratch

```
#Initializing values and computing H. Note the 1. to force to float type
m,n = X.shape
y = y.reshape(-1,1) * 1.
X_dash = y * X
H = np.dot(X_dash , X_dash.T) * 1.

#Converting into cvxopt format
P = cvxopt_matrix(H)
q = cvxopt_matrix(-np.ones((m, 1)))
G = cvxopt_matrix(-np.eye(m))
h = cvxopt_matrix(np.zeros(m))
A = cvxopt_matrix(y.reshape(1, -1))
b = cvxopt_matrix(np.zeros(1))

#Setting solver parameters (change default to decrease tolerance)
cvxopt_solvers.options['show_progress'] = False
cvxopt_solvers.options['abstol'] = 1e-10
cvxopt_solvers.options['reltol'] = 1e-10
cvxopt_solvers.options['feastol'] = 1e-10

#Run solver
sol = cvxopt_solvers.qp(P, q, G, h, A, b)
alphas = np.array(sol['x'])
```

$$\begin{aligned} \min_{\alpha} \quad & \frac{1}{2} \alpha^T \mathbf{H} \alpha - \mathbf{1}^T \alpha \\ \text{s.t.} \quad & -\alpha_i \leq 0 \\ \text{s.t.} \quad & y^T \alpha = 0 \end{aligned}$$

- $P := H$ a matrix of size $m \times m$
- $q := -\vec{1}$ a vector of size $m \times 1$
- $G := -\text{diag}[1]$ a diagonal matrix of -1s of size $m \times m$
- $h := \vec{0}$ a vector of zeros of size $m \times 1$
- $A := y$ the label vector of size $m \times 1$
- $b := 0$ a scalar

Colab 실습

- SVM_CVXOPT