

ambitools Documentation

Pierre Lecomte
pierre.lecomte@gadz.org

June 26, 2016

Contents

1	Introduction	2
1.1	Goals of ambitools	2
1.2	Ambisonics overview	2
1.2.1	Principles	2
1.2.2	Spherical coordinate system	2
1.2.3	Spherical harmonics	2
2	Installing ambitools	4
2.1	Retrieve ambitools repository	4
2.2	Dependencies	4
2.3	Compile the FAUST plug-ins	5
2.4	Local FAUST installation	5
2.5	FAUSTLIVE	5
2.6	Compile the PROCESSING VU-Meter	6
3	The different tools	6
3.1	FAUST	6
3.1.1	hoa_N_sources_encoder	7
3.1.2	hoa_mic_encoder*	8
3.1.3	hoa_decoder_*	9
3.1.4	hoa_decoder_lebedev50_binaural	11
3.1.5	hoa_panning_*	12
3.1.6	Note about sound field transformation tools in Ambisonic domain	13
3.1.7	hoa_mirroring	14
3.1.8	hoa_azimuth_rotator	15
3.1.9	hoa_beamforming_hypercardioid_to_mono	16
3.1.10	hoa_beamforming_hypercardioid_to_hoa	17
3.1.11	hoa_beamforming_dirac_to_hoa	17
3.2	Processing	18
3.2.1	Spherical_VU_Meter	18
3.3	Jconvolver	19
3.3.1	jconvolver_mic*	19
3.3.2	hrir_lebedev50	19
3.4	Pure Data	19
3.4.1	andOSC.pd for Head Tracking	19
3.4.2	joyscick_XYZ_to_OSC.pd to control Faust tools with a Joystick	19
3.4.3	houseflushell.pd to generate the sound of flies	19
4	Examples of use	19
4.0.4	Listening to a 3D HOA recording through binaural rendering	19
4.0.5	Spatialize and control the trajectories of flies	19

1 Introduction

1.1 Goals of ambitools

ambitools is a collection of tools for sound-field synthesis using Near-Field Compensated Higher Orders Ambisonics (NFC-HOA). For the rest of this document, the denomination Ambisonics will be used for simplicity. ambitools is developed in the context of my PhD on 3D sound field synthesis. The audio processing is coded in FAUST¹ (Functional Audio Stream) which allows to produce efficient C++ code and exports in various DSP tools format : VST, standalone applications, LV2, etc. Thus, ambitools is multi-platform (although conceived under Linux/Jack).

The goal of ambitools is mainly to produce several modules to encode, decode and transform 3D synthesized sound field or 3D recordings in a context of physical sound field synthesis.

The project is open-source under GPL licence. ambitools is thought to be very flexible to adapt to your configuration. The FAUST-code for each tool has an header with the required order. So, for example, if you need an encoder up to order $M = 4$, for $N = 5$ sources, you just have to change these two parameters in `hoa_encoder_N_sources.dsp` and produce the required plug-in using FAUSTLIVE¹ for example.

Don't hesitate to contact me for any suggestions, requirements, critics or even just to tell me you're using ambitools !

Pierre Lecomte

1.2 Ambisonics overview

This section presents the basis of Ambisonics for 3D sound field synthesis. It is written with relatively few maths to focus on the concepts instead of the mathematical rigor, which would be out of scope of this document. If you want more insights to Ambisonics refer for example to [Daniel, 2000, Poletti, 2005, Ahrens, 2012].

1.2.1 Principles

Ambisonics are some mathematical approaches to represent a sound field in two or three dimensions over a basis of spherical harmonics. Without giving more mathematical details, Ambisonic main possibilities are displayed on Fig. 1.

Thus, in accordance to this Fig. 1, ambitools provides tools to:

- Encode a sound field captured by a spherical microphone.
- Encode a sound field from monophonic signals and explicit position in space.
- Transform and manipulate the encoded sound field in Ambisonic domain.
- Decode the sound field over spherical grids of speaker or over headphones with binaural convolution.

1.2.2 Spherical coordinate system

Ambisonics are usually described in spherical coordinate systems. In ambitools, the following spherical coordinate system is used: The following spherical coordinate system is used and is shown in Fig. 2:

$$x = r \cos(\theta) \cos(\delta), \quad y = r \sin(\theta) \cos(\delta), \quad z = r \sin(\delta). \quad (1)$$

The azimuth angle $\theta \in [0 \ 360^\circ]$. The elevation angle $\delta \in [-90^\circ \ 90^\circ]$. The convention for rotation is counterclockwise direction (i.e. trigonometric direction).

1.2.3 Spherical harmonics

As mentioned before, Ambisonics describes a sound field over a spherical harmonics basis. Those functions are directional functions of the variable θ, δ . They are denoted $Y_{mn}(\theta, \delta)$ where subscript m represents the order of the spherical harmonic and n its degree. There is several definition for these functions. In ambitools, the N3D real spherical harmonic definition is used [Daniel, 2000]:

$$Y_{mn}(\theta, \delta) = \sqrt{(2m+1)\epsilon_n \frac{(m-|n|)!}{(m+|n|)!}} P_{m|n|}(\sin(\delta)) \times \begin{cases} \cos(|n|\theta) & \text{if } n \geq 0 \\ \sin(|n|\theta) & \text{if } n < 0 \end{cases}, \quad (2)$$

¹<http://faust.grame.fr>

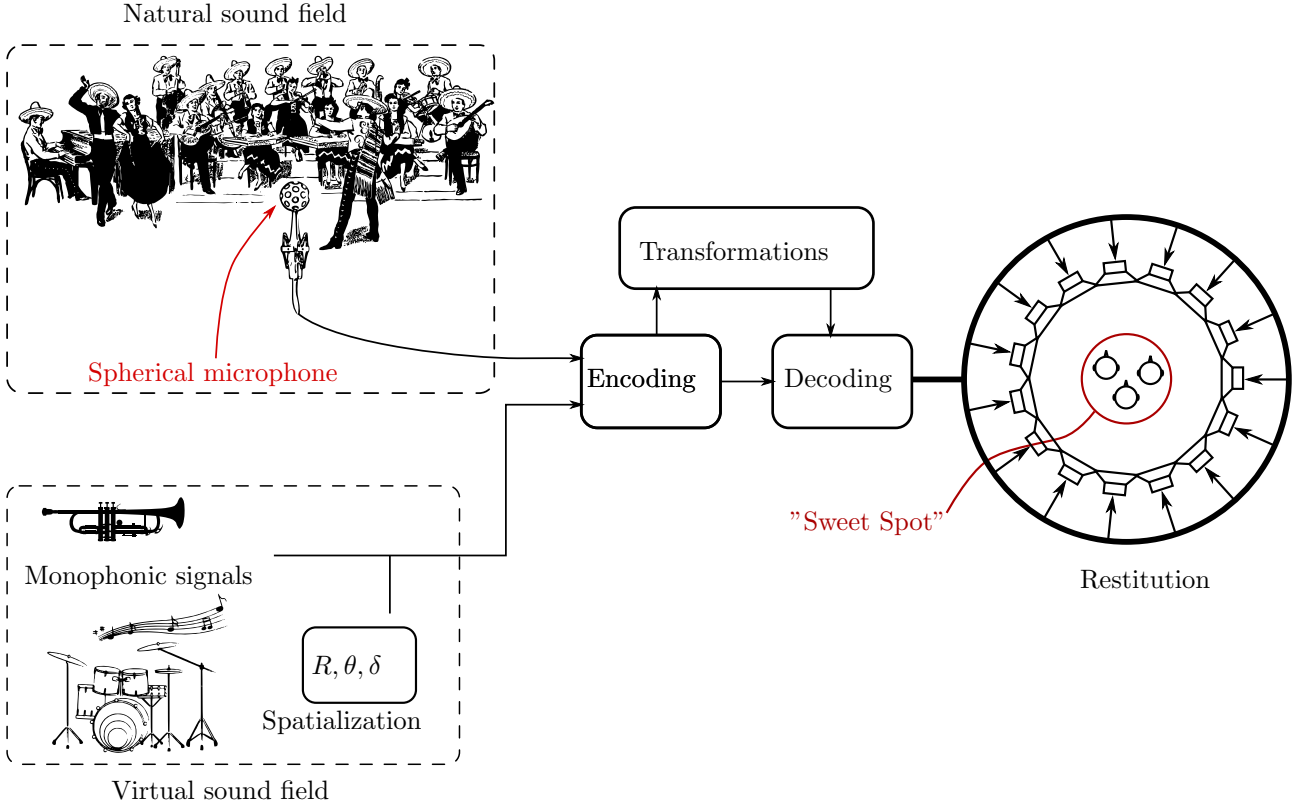


Figure 1: Ambisonic principles: A sound field can be captured in three dimensions using spherical microphone or it can be synthesized with monophonic signals and explicit positions in space. These two approaches result in an encoded sound field in Ambisonic domain up to order M . In this domain, transformations can be done such as: sound field mirroring, rotation, warping, directional filtering, etc. Finally, the decoding step computes the driving signals of the playback loudspeakers to recreate the encoded sound field in a sweet spot region of space. The decoding can be done over various configurations of speakers and even over headphones !

where $P_{m|n|}$ are the associated Legendre polynomials of order m and degree $|n|$, $(m, n) \in (\mathbb{N}, \mathbb{Z})$ with $|n| \leq m$, and $\epsilon_n = 1$ if $n = 0$, $\epsilon_n = 2$ if $|n| > 0$. In Eq. (2), m denotes the spherical harmonic order and n its degree.

For each order m , there are $(2m + 1)$ spherical harmonics. Thus a basis truncated at order M contains $(M + 1)^2$ functions. For example, on Fig. 3 are displayed the spherical harmonics up to order $M = 5$ as balloon plots.

Thus, a sound field can be described as a linear combination of spherical harmonics. The weights of this linear combination are called the Ambisonics components or *B-Format* components. As an example, a sound field described up to order $M = 1$ is described with $(M + 1)^2 = 4$ Ambisonics components. At order $M = 5$ there will be 36 components, etc.

Without giving more details, the concept to retain is that the more components are available to describe the sound field (i.e. the higher the order), the larger the sweet-spot will be on Fig. 1.

At the moment, ambitoools offers the possibility of 3D Ambisonics up to order $M = 5$. Thus for all the tools you need to compile, **M SHOULD BE CHOSEN SUCH AS $M \leq 5$.**

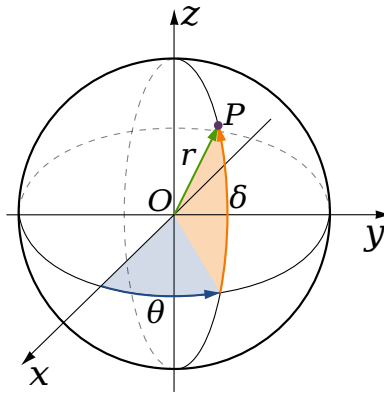


Figure 2: Spherical coordinate system in use. A point $P(x, y, z)$ is described by radius r , azimuth θ and elevation δ .

2 Installing ambitools

2.1 Retrieve ambitools repository

To install ambitools, simply go on the github repository² and clone it. To do so, open a terminal in the directory you'd like to clone the repository and type the following command:

```
$ git clone https://github.com/sekisushai/ambitools
```

To keep the repository up to date, type the following command at the root of the directory `ambitools/`:

```
$ git pull
```

You can also download a `.zip` file from github³

The resulting `ambitools/` folder should have the following structure:

- **Documentation/** Everything concerning the documentation (pdfs, including some scientific papers).
- **Faust/** Everything written in FAUST language (all the ambitools plug-ins + some utilities).
 - `bin/` Compiled plug-ins in various formats.
 - `src/` Source code of the plug-ins.
 - `src/lib/` Shared libraries (spherical harmonics, gui, etc.).
- **FIR/** Finite Impulse Response (FIR) filters banks for binaural rendering and spherical microphone equalization filters, to use with Jconvolver⁴, fast convolution software.
 - `spherical_microphones/` Equalization filters for rigid spherical microphone, such as mh acoustics EigenMike⁵
 - `hrir/` Head Related Impulses Responses (HRIR) of several people to use with binaural rendering over headphones.
- **Processing/** Everything written in PROCESSING language, namely the spherical VU-Meter ((see Sec. 3.2.1).
 - `bin/` Compiled spherical VU-Meter in Java for various architectures.
 - `src/` PROCESSING source code.
- **PureData/** Everything written in Pure Data (a few sounds generator patches, head-tracking patch and PlayStation-like remote patch to drive FAUST plug-ins with Open Sound Control protocol, OSC).

2.2 Dependencies

Depending on what you're looking for with the code, the following dependencies should be provided:

²<https://github.com/sekisushai/ambitools>

³<https://github.com/sekisushai/ambitools/archive/master.zip>

⁴<http://kokkinizita.linuxaudio.org/linuxaudio/>

⁵<http://www.mhacoustics.com>

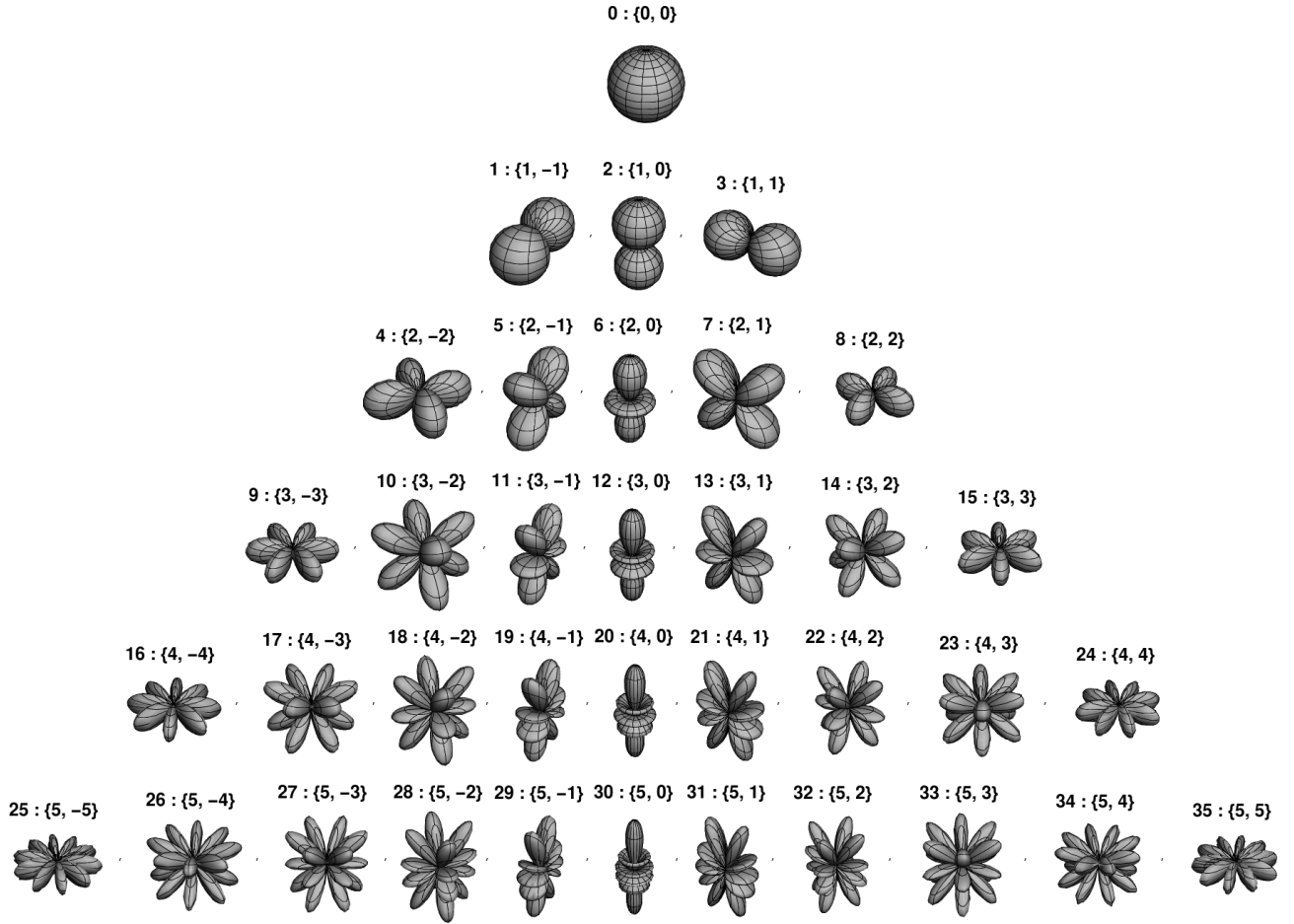


Figure 3: Balloon-plot of the spherical harmonics up to order $M = 5$.

Dependency	Usage
OSC support	Drive the tools standalone tools with OSC.
JAVA	Run the Spherical VU-Meter (see Sec. 3.2.1).
JCONVolver	Real-time convolution for binaural rendering or spherical microphone signals filtering.
PROCESSING	Edit and compile the Processing code.
FAUST or FAUSTLIVE	Edit and compile the FAUST code.

Table 1: Dependencies of ambitools

2.3 Compile the Faust plug-ins

The FAUST plug-ins source codes are in the sub-folder [Faust/src/](#).

2.4 Local Faust installation

If you have FAUST installed on your machine with the required dependencies, you can run the scripts collection [faust2*](#) to produce the plug-in of your choice in the desired format.

For example, to compile [hoa_encoder_N_sources.dsp](#) into a standalone Linux jack-qt application with OSC support, type the following command in a terminal in the folder [\Faust/src](#)

```
$ faust2jaqt hoa_encoder_N_sources.dsp -osc
```

2.5 FaustLive

To compile the plug-ins to your requirements, load the chosen plug-in in FAUSTLIVE¹ and choose [Window/Export As...](#) (see Fig. 4).



Figure 4: FAUSTLIVE Export Manager

2.6 Compile the Processing VU-Meter

The PROCESSING source code is in the folder [Processing/scr](#). You should open the file [Spherical_VU_Meter.pde](#) in the PROCESSING editor and select "File/Export..." to produce a binary application.

3 The different tools

This section gives a quick presentation of each tool contained in ambitools.

3.1 Faust

The core of the sound processing is written in FAUST language. Note that the majority of the figures presented in the following section will be screen-shots of the tools compiled as standalone JACK applications for Linux, using [faust2jaqt](#) script. However, thanks to the versatility of FAUST language, note that each of these tools can be compiled for various architecture, using FAUSTLIVE¹ for example.

3.1.1 `hoa_N_sources_encoder`

- Inputs: N
- Outputs: $(M + 1)^2$

This first tool allows to encode N signal inputs to an 3D Ambisonics scene described with Ambisonics components signals up to order M (the B -Format). You can choose N and M at the compilation time in file `hoa_encoder_N_sources.dsp`. The resulting graphical user interface when using `faust2jaqt` script is shown in Fig. 5 for $N = 3, M = 5$. Each input signal can be encoded in B -Format as a plane wave or a spherical wave.

For the plane wave case, the check-box **Spherical Wave** should be unchecked. Consequently, the knob **Radius** and input entry **Speakers Radius** are without effect in this case (a plane wave has no distance information).

For the spherical wave case, the knob **Radius** allows to choose the source radius to origin. Note that to represent a spherical wave in Ambisonic domain, near-field filters are activated [Daniel, 2003, Lecomte and Gauthier, 2015]. Those filters, unstable by nature, are stabilized using the near-field compensation filters from decoding step. Thus in this case, the radius of the spherical loudspeakers grid should be known prior to decoding and given in **Speakers Radius** input entry.

Finally, the outputs of this tool are B -Format signals up to order M . Each order can be muted or each individual Ambisonic components individually.



Figure 5: `hoa_encoder_N_sources` plug-in compiled using `faust2jaqt` script with $N = 2$ and $M = 5$. The **Gain** knob allows to adjust the input level of the input. **Radius** knob allows to choose the source distance to origin in case of spherical wave encoding. **Azimuth** and **Elevation** knobs allow to choose the source direction. The **Spherical Wave** check-box enables the encoding of spherical wave, using near-field filters. **Speakers Radius** sets the radius for the spherical arrays of loudspeakers at decoding stage in case of spherical wave encoding. Finally, the VU-Meters shows the level of 3D B -Format signals in dBFS up to order M . Each meter as a **Mute** check-box and each order as well.

3.1.2 `hoa_mic_encoder*`

- Inputs: 06, 26, 32, or 50 depending on the configuration.
- Outputs: $(M + 1)^2$

It is possible to encode a natural sound field captured by a rigid spherical microphone, according to Fig. 1. To do so, the signals from each capsule on the spherical microphone are mixed to operate the Discrete Spherical Fourier Transform (DSFT) [Moreau et al., 2006]. Then, the resulting $(M + 1)^2$ components are filtered to obtain the Ambisonics components. In `ambitools`, the DSFT projection is done for several spherical rigid spherical microphone configurations using `hoa_mic_encoder*` tools. The filtering of the resulting components is done using `Jconvolver`, a real-time fast convolution software. See Sec. 3.3 for further details. Note that the filtering of the outputs signals of `hoa_mic_encoder*` tools is mandatory in order to obtain the Ambisonics components. The different microphone configuration available in `ambitools` are 06, 26 or 50 capsules spherical microphone arranged on a Lebedev grid [Lecomte et al., 2015] and a 32 capsules spherical microphone arranged on a pentakis-dodecahedron grid, i.e. the mh acoustics Eigenmike[®] microphone [Elko et al., 2009]. Those configuration can operate the Spherical Fourier Transform up to order $M = 1$, $M = 3$, $M = 5$ and $M = 4$ respectively [Lecomte et al., 2015, Moreau et al., 2006]. The corresponding tools are named `hoa_mic_encoder_lebedev06`, `hoa_mic_encoder_lebedev26`, `hoa_mic_encoder_lebedev50` and `hoa_mic_encoder_eigenmike32` respectively. The graphical user interface when using `faust2jaqt` script is shown in Fig. 6 for the `hoa_mic_encoder_lebedev26` tool compiled with $M = 3$.

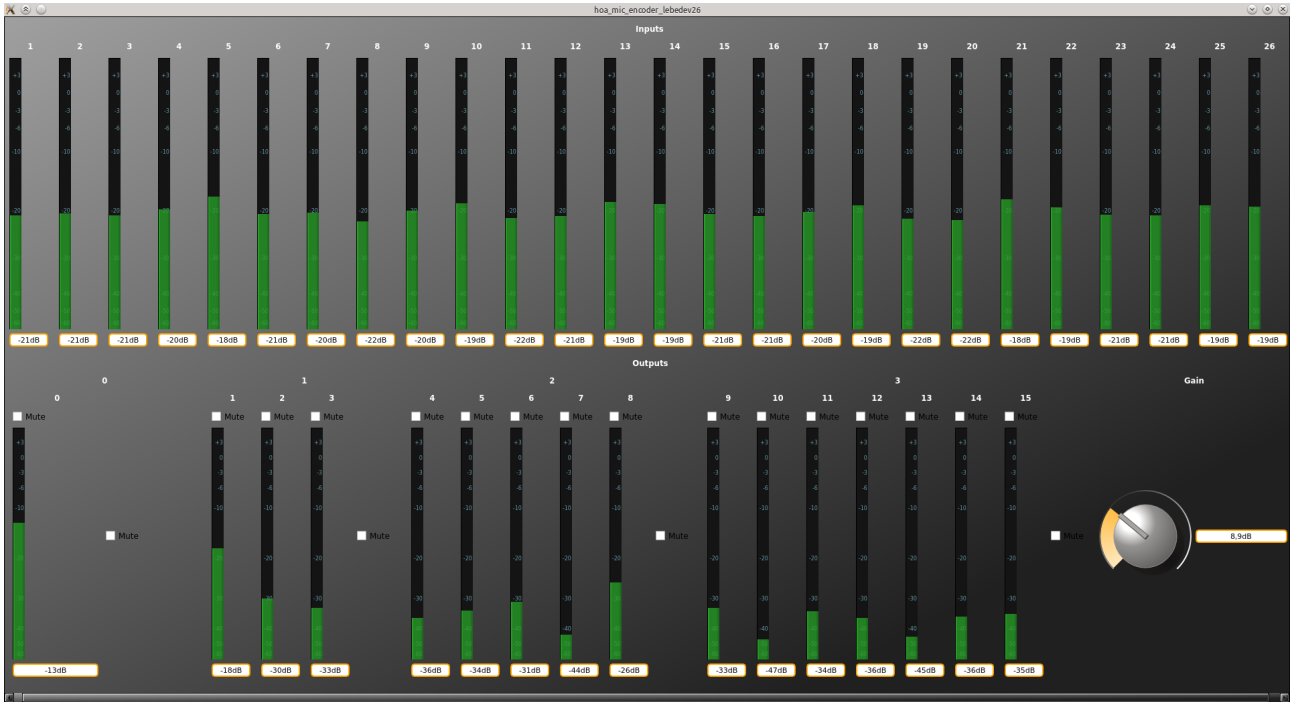


Figure 6: `hoa_mic_encoder_lebedev26` compiled using `faust2jaqt` script with $M = 3$. The VU-Meters at the top show the signal level in dBFS of each capsule on the spherical microphone. The VU-Meters at the bottom show the signal level of each components after the DSFT operation. The check-boxes `Mute` allow to mute some components or all components of an order. The knob `Gain` applies a global gain on the output signals.

Fig. 7 shows the connection in order to obtain the Ambisonics components from the signals of a rigid spherical microphone. The raw signals issued from the spherical microphone are played using a Digital Audio Workstation, Ardour 4 in this case. Those signals feed the tool `hoa_mic_encoder_lebedev50` in the middle of Fig. 7. This tool mix the signals to operate the DSFT. The resulting outputs signals are finally filtered using `Jconvolver`, on the right of Fig. 7. The outputs of `Jconvolver` are the Ambisonics components, here up to order $M = 5$.

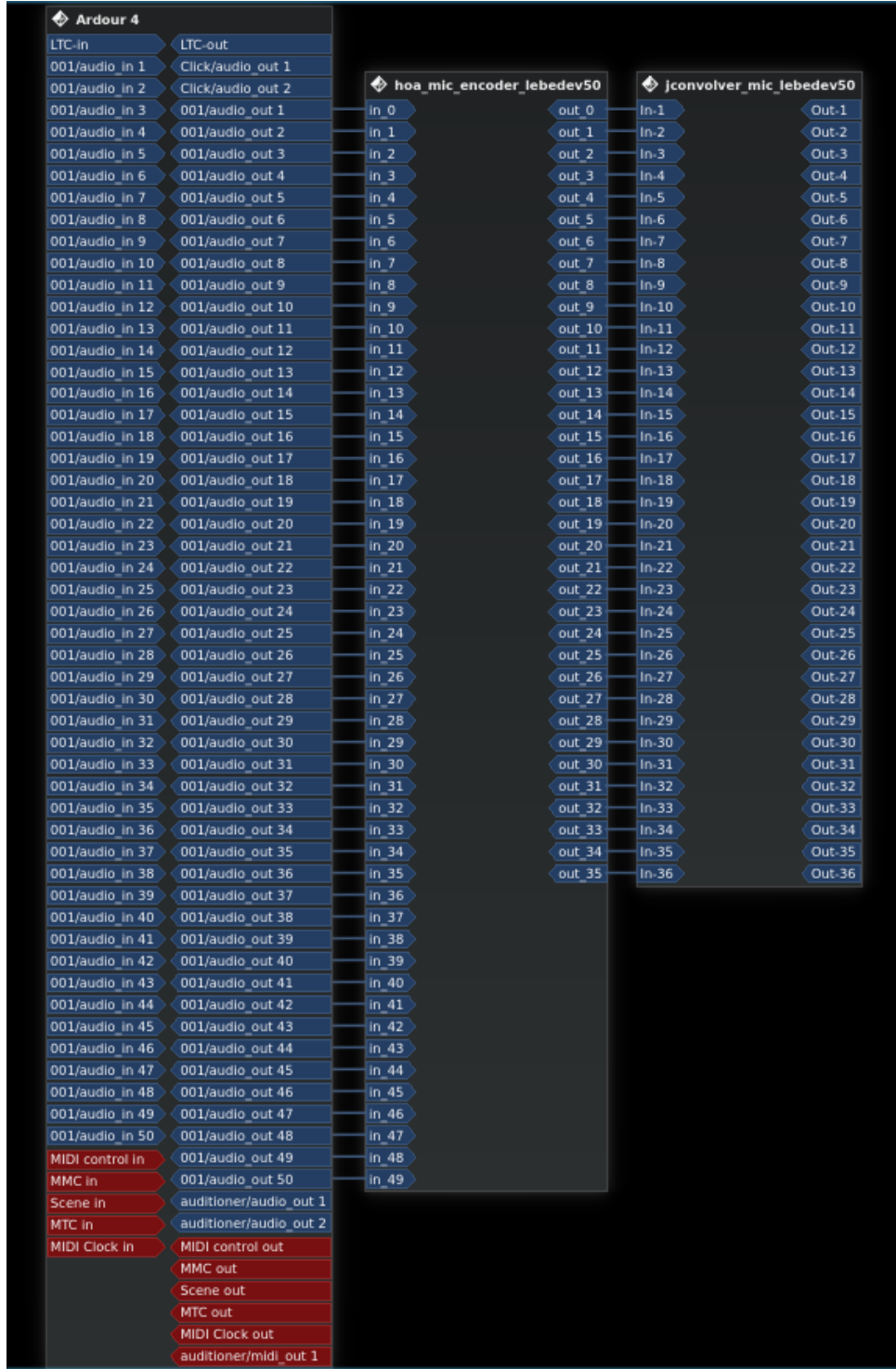


Figure 7: Connections in order to obtain the Ambisonics components from the signals of a rigid spherical microphone. On the left, the 50 outputs of Ardour 4: the 50 signals of the rigid spherical microphone with a 50-node Lebedev configuration. On the middle, the tool `hoa_mic_encoder_lebedev50` which operates the DSFT. On the right, the filtering of the signals with Jconvolver, the outputs of this box are the Ambisonics components up to order $M = 5$. Screen-shot taken from Claudia under KXStudio Linux distribution.

3.1.3 `hoa_decoder_*`

- Inputs: $(M + 1)^2$
- Outputs: 06, 26 or 50 depending on the decoder.

Three basic decoders by mode-matching [Daniel, 2000, Poletti, 2005] are available at the moment in am-bitools: `hoa_decoder_lebedev06`, `hoa_decoder_lebedev26` and `hoa_decoder_lebedev50`. Those decoders

allow to decode $(M + 1)^2$ Ambisonics signals on Lebedev grids with respectively 6, 26 and 50 loudspeakers [Lebedev, 1975, Lecomte et al., 2015]. Those grids are able to reconstruct the sound field up to order $M = 1$, $M = 3$ and $M = 5$ respectively. If other decoders are required, you should have a look at the ambisonic decoder toolbox from Aaron Heller [Heller et al., 2012], or contact me. The graphical user interface when using `faust2jaqt` script is shown in Fig. 8 for the `hoa_decoder_lebedev50` decoder compiled with $M = 5$. The decoder can be with or without near-field compensation (NFC) filters [Daniel et al., 2003, Lecomte and Gauthier, 2015]. Those filters allow to take into account the finite distance of the loudspeakers: In other terms, if they are disabled, the loudspeakers are modeled as plane-wave generators. In case of spherical wave encoding using the `hoa_N_sources_encoder` plug-in, the **NFC** check-box should be unchecked as the near-field compensation filters are already used at encoding step (see Sec. 3.1.1).

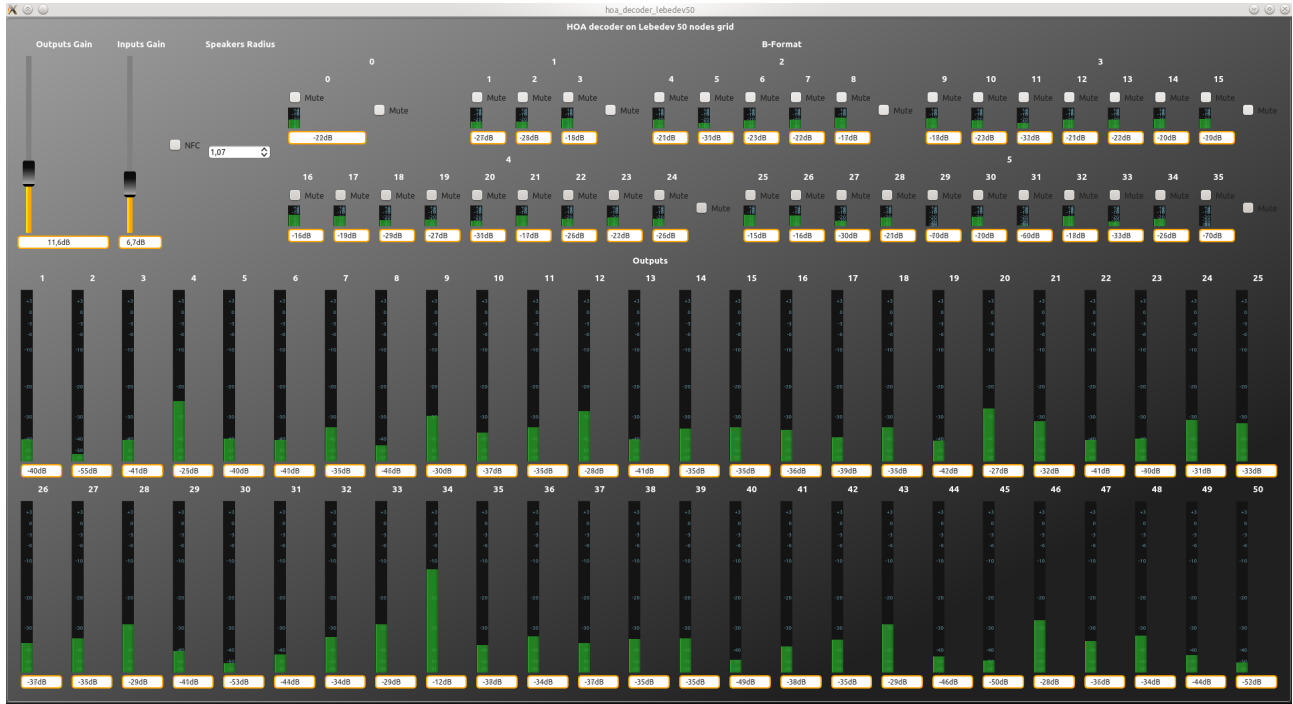


Figure 8: `hoa_decoder_lebedev50` compiled using `faust2jaqt` script with $M = 5$. The slider **Outputs Gain** applies a global gain on all outputs (loudspeakers signals). The slider **Inputs Gain** applies a global gain on all inputs (*B-Format* signals). The VU-Meters **Inputs** and **Outputs** give the signals level in dBFS. The check-box **NFC** activate or deactivate the near-field compensation filters. The input entry **Speakers Radius** allows to set the spherical grid radius. Finally, the check-boxes **Mute** above all inputs VU-meters allow to mute some specific *B-Format* signals. Or, all the signal from an order with **Mute** check-boxes on side of a VU-Meter group.

Usage with the Spherical VU-Meter Note that when using these tools to drive the Spherical VU-Meter (Sec. 3.2.1) with OSC, you need to activate OSC transmission mode 2. This is done by launching the tool with the argument `-xmit 2`. For example, with the decoder `hoa_decoder_lebedev50`, the command should be:

```
$ ./hoa_decoder_lebedev50 -xmit 2
```

3.1.4 `hoa_decoder_lebedev50_binaural`

- Inputs: $(M + 1)^2$
- Outputs: 2

3.1.5 `hoa_panning_*`

- Inputs: N
- Outputs: 06, 26 or 50 depending on the configuration.

It is possible to compute directly the signals of the loudspeakers without passing by an encoding and decoding process [Lecomte et al., 2015]. This equivalent 3D-panning is implemented in the tools `hoa_panning_N_sources_lebedev06`, `hoa_panning_N_sources_lebedev26` and `hoa_panning_N_sources_lebedev50` for Lebedev grids with 6, 26 and 50 loudspeakers respectively [Lebedev, 1975, Lecomte et al., 2015]. Those grids allow to control the sound field up to order $M = 1$, $M = 3$ and $M = 5$ respectively [Lecomte et al., 2015]. The graphical user interface when using `faust2jaqt` script is shown in Fig. 9 for the `hoa_panning_N_sources_lebedev50` panning tool compiled with $M = 5$ and $N = 2$.

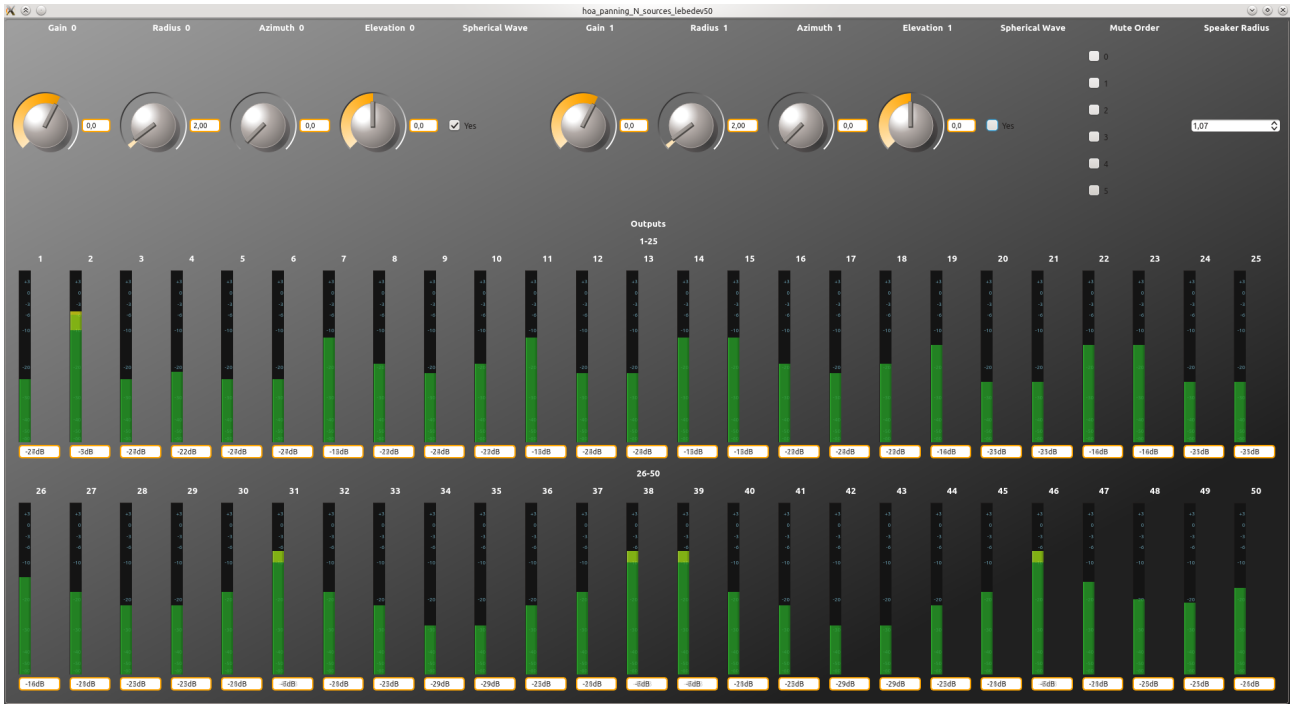


Figure 9: `hoa_panning_N_sources_lebedev50` compiled using `faust2jaqt` script with $M = 5$ and $N = 2$. The slider **Outputs Gain** applies a global gain on all outputs (loudspeakers signals). The check-boxes **Mute Order** allow to mute some Ambisonic order in the computation of the driving signals. The sliders **Gain Radius Azimuth Elevation** control the position and gain of the sources. The check-box **Spherical Wave** allows to switch between the synthesis of a spherical wave or a plane wave. In the case of spherical wave synthesis, the input entry **Speakers Radius** sets the spherical loudspeakers system radius.

Usage with the Spherical VU-Meter Note that when using these tools to drive the Spherical VU-Meter (Sec. 3.2.1) with OSC, you need to activate OSC transmission mode 2. This is done by launching the tool with the argument `-xmit 2`. For example, with the panning tool `hoa_panning_N_sources_lebedev50`, the command should be:

```
$ ./hoa_panning_N_sources_lebedev50 -xmit 2
```

3.1.6 Note about sound field transformation tools in Ambisonic domain

The tools presented in the next sections perform sound field transformations in Ambisonic domain. Thus, they should be used on Ambisonic signals and inserted after encoding step and before decoding step. For instance, on Fig. 10 is shown the connections for the tool `hoa_mirroring`: It is inserted after `hoa_encoder_N_sources` and before `hoa_decoder_lebedev50`, acting on Ambisonic signals.

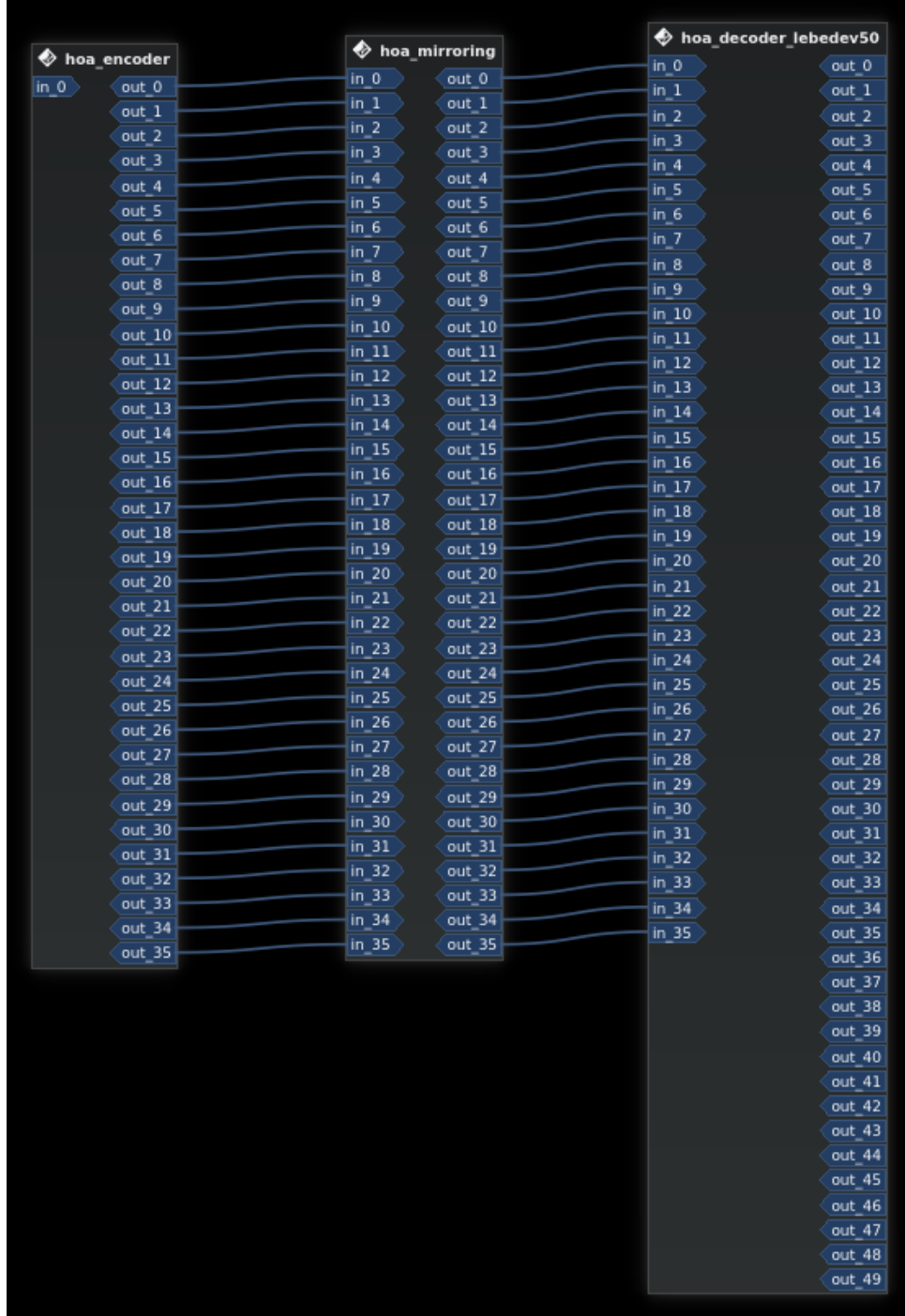


Figure 10: Connections between plug-ins `hoa_encoder_N_sources`, `hoa_mirroring` and `hoa_decoder_lebedev50` compiled with `faust2jaqt` script with $M = 5$. `hoa_mirroring` acts on Ambisonics signals. Screen-shot taken from Claudia under KXStudio Linux distribution.

3.1.7 hoa_mirroring

- Inputs: $(M + 1)^2$
- Outputs: $(M + 1)^2$

`hoa_mirroring` performs mirroring operations on the sound field. The directions front and back can be inverted, as well as left and right, up and down, or any combination of the above. In fact, the transformation changes the sign of particular Ambisonic components [Kronlachner and Zotter, 2014]. The graphical user interface when using `faust2jaqt` script is shown in Fig. 11. To "visualize" the transformation, Fig. 12 shows the Spherical VU-Meter (see Sec. 3.2.1) for a 50-node Lebedev grid with a source positioned at $(1.07 \text{ m}, 0^\circ, 90^\circ)$, i.e, above the head of the listener. One can observe the signal level of each loudspeaker after decoding step. Thus, on Fig. 12(a), when the `hoa_mirroring` tool is not active, the maximum sound energy is above. When the checkbox `up-down` is checked, on Fig. 12(b) one observes that the sound field has been mirrored according to the up-down inversion. Thus, the sound energy is coming from under the listener at present.



Figure 11: `hoa_mirroring` compiled using `faust2jaqt` script. The check-boxes allows to select the mirror transformations among: `left-right`, `front-back` or `up-down`.

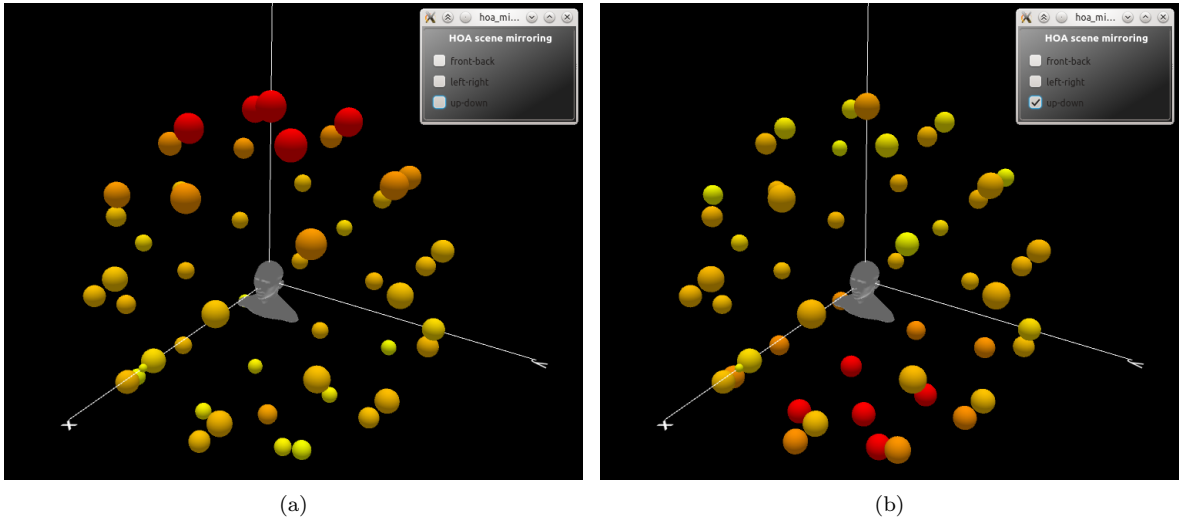


Figure 12: `hoa_mirroring` effects on a sound field. (a): original sound field decoded on a 50 loudspeaker Lebedev grid. (b) the sound field has been transformed according to a mirroring up-down with `hoa_mirroring` tool.

3.1.8 hoa_azimuth_rotator

- Inputs: $(M + 1)^2$
- Outputs: $(M + 1)^2$

`hoa_azimuth_rotator` performs a rotation of the sound field around z -axis (yaw angle). One recalls that the trigonometric sens is chosen for rotation convention (i.e. anti-clockwise) (see Sec. 1.2.2). The transformation is done by a rotation matrix operation on the Ambisonic components [Daniel, 2000, Moreau, 2006, Kronlachner and Zotter, 2014]. The graphical user interface when using `faust2jaqt` script is shown in Fig. 13. It's basically just a slider to choose the azimuth angle of rotation. To "visualize" the transformation, Fig. 14 shows the Spherical VU-Meter (see Sec. 3.2.1) for a 50-node Lebedev grid with a source positioned at $(1.07\text{ m}, 0^\circ, 0^\circ)$, i.e. in front of the listener. One can observe the signal level of each loudspeaker after decoding step. Thus, on Fig. 12(a), when the `hoa_azimuth_rotator` slider `Azimuth` is set to 0° , i.e. no rotation, the maximum sound energy is in front of the listener. When the slider `Azimuth` is set to 90° , on Fig. 12(b) one observes that the sound field has been rotated 90° counter-clockwise around the z -axis. Thus, the sound energy is coming from the left of the listener at present.

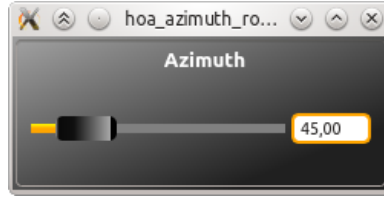


Figure 13: `hoa_azimuth_rotator` compiled using `faust2jaqt` script. The slider `Azimuth` allows to choose the azimuth angle of rotation, around the z -axis.

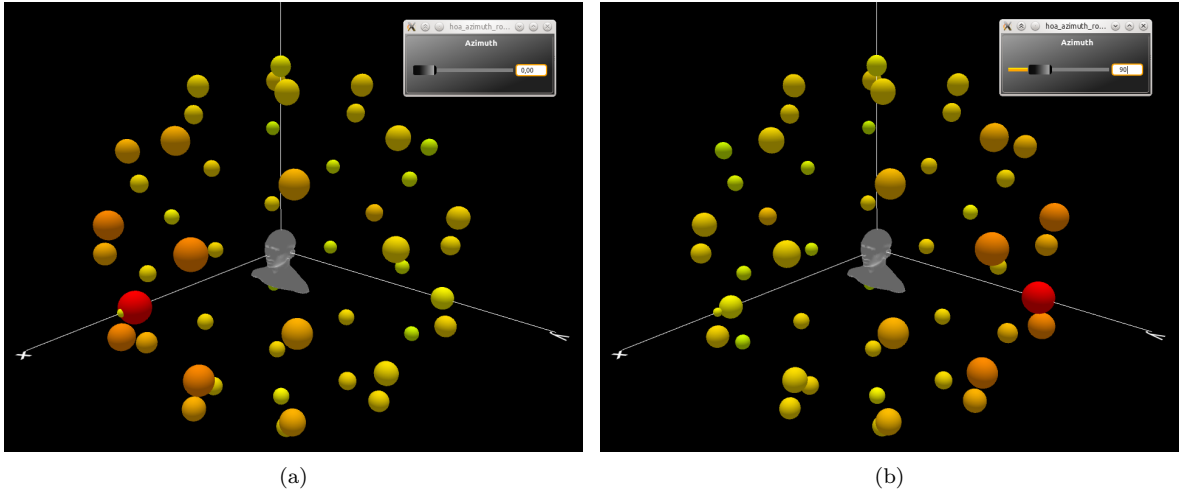


Figure 14: `hoa_azimuth_rotator` effects on a sound field. (a): original sound field decoded on a 50 loudspeaker Lebedev grid. (b) the sound field has been rotated according to a rotation around z -axis of $+90^\circ$ using `hoa_azimuth_rotator` tool.

Head Tracking One possible use of the tool `hoa_azimuth_rotator` is to compensate the rotation of the head of the listener around z -axis when driven by a head-tracking system [Noisternig et al., 2003]. Thus, when using binaural rendering over headphone, the sound field is rotated of minus the angle of rotation of the head, to compensate the head rotation and leave the source at the same position in space for the listener. `ambitools` provides a Pure Data patch to drive `hoa_azimuth_rotator` with OSC and perform an cheap head-tracking system with a smart-phone. See Sec. 3.4.1 for further informations.

3.1.9 hoa_beamforming_hypercardioid_to_mono

- Inputs: $(M + 1)^2$
- Output: 1

`hoa_beamforming_hypercardioid_to_mono` is a tool to perform modal beamforming and extract a monophonic signal as if it was recorded by a directional microphone in the sound field. In fact, the Ambisonic signals are weighted and summed to give the monophonic output signal. The weights of the combination traduce the beampattern of the directional microphone which is used [Meyer and Elko, 2002]. Thus, this tool allows to listen to a chosen direction in the 3D sound field as if you were recording in the middle of the sound field with a directional microphone with a specific beampattern. `hoa_beamforming_hypercardioid_to_mono` provides the weights corresponding to regular hyper-cardioid microphone up to order 3 [Meyer and Elko, 2002, Lecomte et al., 2016]. On Fig. 16, the beampatterns available are shown: the higher the order of the hyper-cardioid is, the more directional the corresponding virtual microphone becomes. The graphical user interface when using `faust2jaqt` script is shown in Fig. 15 for $M = 3$.

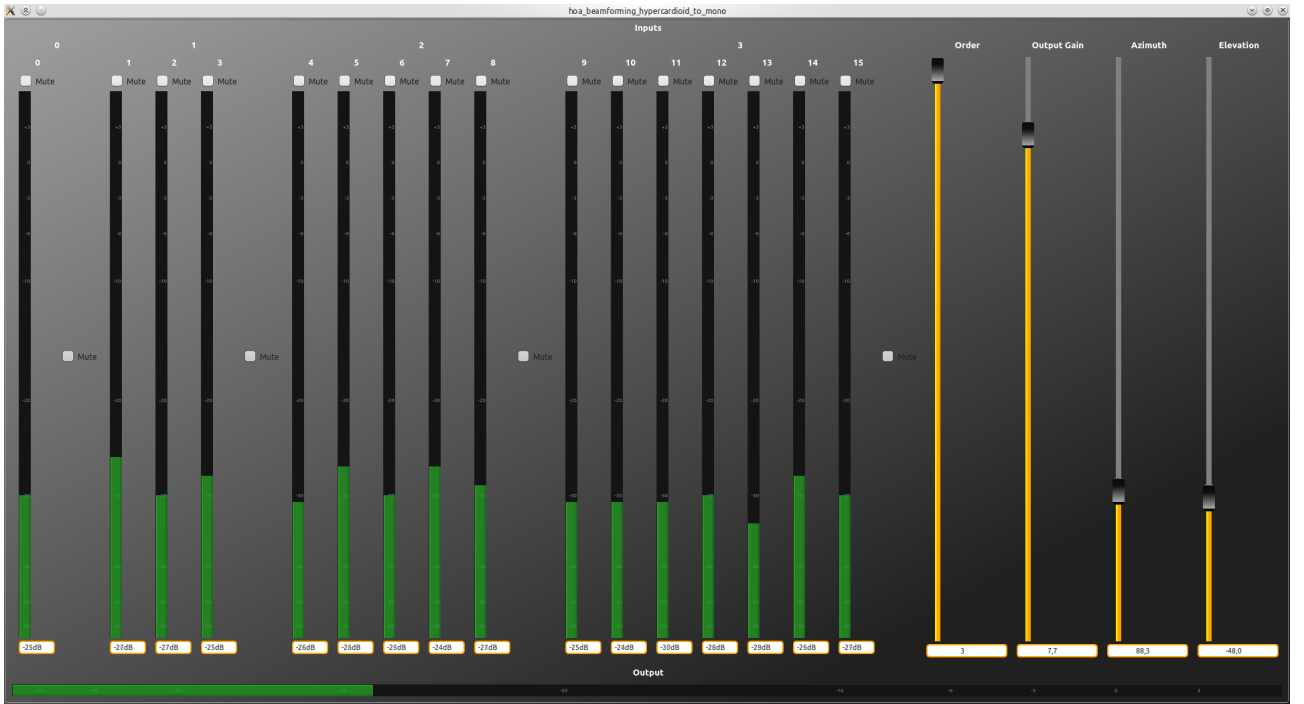


Figure 15: `hoa_beamforming_hypercardioid_to_mono` compiled using `faust2jaqt` script. The VU-Meters on the left give the signal level of each Ambisonic component. The check-boxes **Mute** allow to mute some components of all the components of an order. On the right, the slider **Order** allows to select the regular hyper-cardioid order. The slider **Output Gain** applies a gain on the output signal. The sliders **Azimuth** and **Elevation** allow to set the steering angles (θ_0, δ_0) of the hyper-cardioid beampattern. Finally, the horizontal VU-Meter on bottom shows the output signal level.

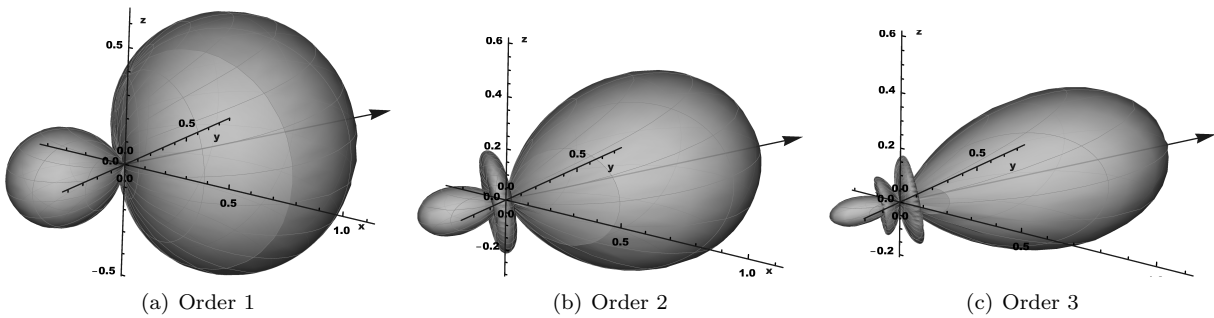


Figure 16: Regular hyper-cardioid beampattern up to order 3. The steering angles are $(\theta_0 = 45^\circ, \delta_0 = 10^\circ)$.

3.1.10 `hoa_beamforming_hypercardioid_to_hoa`

3.1.11 `hoa_beamforming_dirac_to_hoa`

3.2 Processing

3.2.1 Spherical_VU_Meter

ambitools provides a Spherical VU-Meter developed with PROCESSING language. A screen-shot is shown on Fig. 17. This tool allows to "see" where the sound energy is in space, instead of using classical in-line VU-Meter. You can zoom, pan and rotate the view of the meter while running. The FAUST tools [hoa_panning*](#) and [hoa_decoder*](#) emit OSC messages on port UDP 5511. Those messages drive the spherical VU-Meter rendering in real-time: loudspeakers size and color for the meter, and source position.

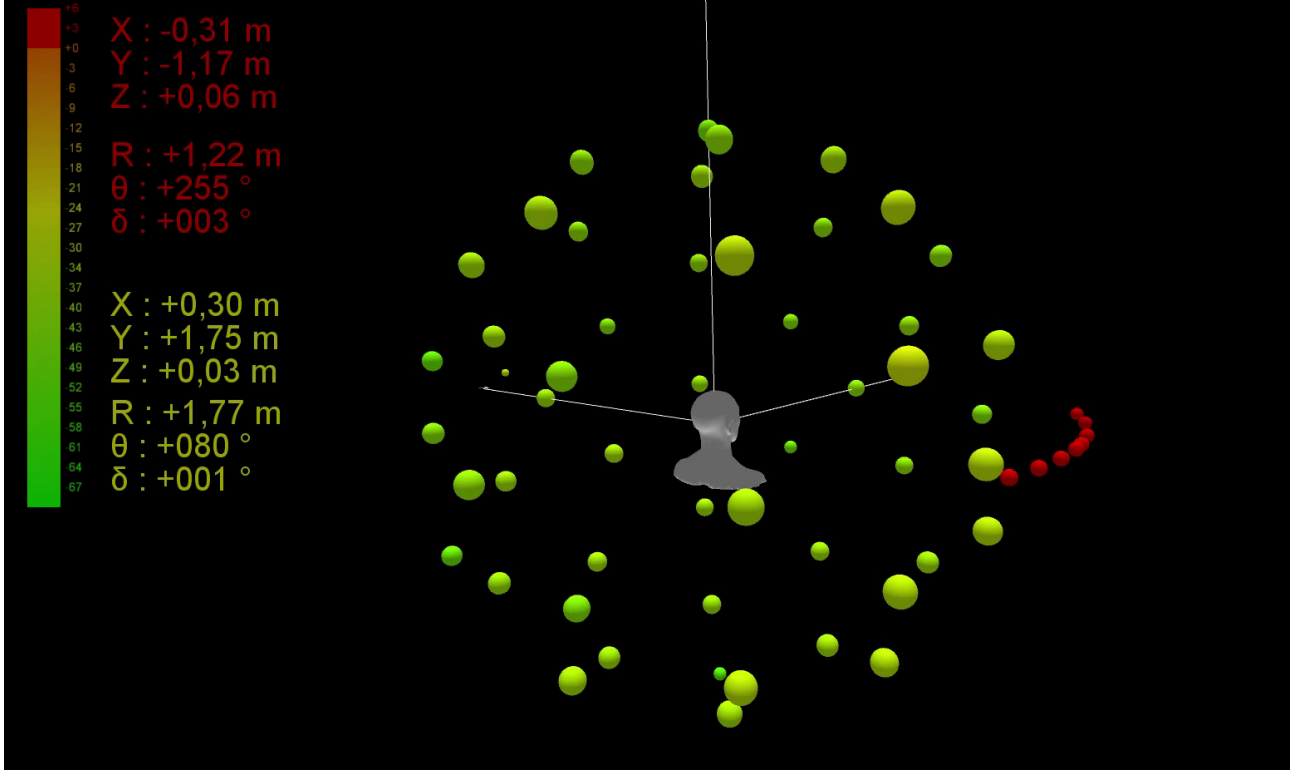


Figure 17: [Spherical_VU_Meter](#) for a 50 loudspeaker Lebedev array and two virtual sources. Each loudspeaker is represented as a color ball with size and color proportional to RMS Level in dBFS. A scale in dBFS is displayed on the left of the screen. The virtual sources are represented as red and yellow dots. Their coordinates are displayed in Cartesian and spherical coordinates on the left. A grey manikin is standing in the middle of the array to indicate the front direction.

3.3 Jconvolver

3.3.1 jconvolver_mic*

3.3.2 hrir_lebedev50

3.4 Pure Data

3.4.1 andOSC.pd for Head Tracking

3.4.2 joystick_XYZ_to_OSC.pd to control Faust tools with a Joystick

3.4.3 houseflushell.pd to generate the sound of flies

4 Examples of use

4.0.4 Listening to a 3D HOA recording through binaural rendering

4.0.5 Spatialize and control the trajectories of flies

References

- [Ahrens, 2012] Ahrens, J. (2012). *Analytic Methods of Sound Field Synthesis*. Springer.
- [Daniel, 2000] Daniel, J. (2000). *Représentation de champs acoustiques, application à la transmission et à la reproduction de scènes sonores complexes dans un contexte multimédia*. PhD thesis, Université Paris 6, Paris.
- [Daniel, 2003] Daniel, J. (2003). Spatial sound encoding including near field effect: Introducing distance coding filters and a viable, new ambisonic format. In *Audio Engineering Society Conference: 23rd International Conference: Signal Processing in Audio Recording and Reproduction*, pages 1–15, Helsingør. Audio Engineering Society.
- [Daniel et al., 2003] Daniel, J., Moreau, S., and Nicol, R. (2003). Further investigations of high-order ambisonics and wavefield synthesis for holophonic sound imaging. In *Audio Engineering Society Convention 114*, pages 1–18, Amsterdam. AES.
- [Elko et al., 2009] Elko, G., Kubli, R. A., and Meyer, J. (2009). Audio system based on at least second-order eigenbeams.
- [Heller et al., 2012] Heller, A. J., Benjamin, E. M., and Lee, R. (2012). A toolkit for the design of ambisonic decoders. *Linux Audio Conference*.
- [Kronlachner and Zotter, 2014] Kronlachner, M. and Zotter, F. (2014). Spatial transformations for the enhancement of Ambisonic recordings. In *2nd International Conference on Spatial Audio*, Erlangen.
- [Lebedev, 1975] Lebedev, V. (1975). Values of the nodes and weights of quadrature formulas of Gauss-Markov type for a sphere from the ninth to seventeenth order of accuracy that are invariant with respect to an octahedron. *USSR Computational Mathematics and Mathematical Physics*, 15(1):44–51.
- [Lecomte and Gauthier, 2015] Lecomte, P. and Gauthier, P.-A. (2015). Real-Time 3D Ambisonics using Faust, Processing, Pure Data, And OSC. In *15th International Conference on Digital Audio Effects (DAFx-15)*, Trondheim.
- [Lecomte et al., 2016] Lecomte, P., Gauthier, P.-A., Langrenne, C., Berry, A., and Garcia, A. (2016). Filtrage directionnel dans un scène sonore 3D par une utilisation conjointe de Beamforming et d’Ambisonie d’ordre élevés. In *CFA / VISHNO 2016*, pages 169–175, Le Mans.
- [Lecomte et al., 2015] Lecomte, P., Gauthier, P.-A., Langrenne, C., Garcia, A., and Berry, A. (2015). On the use of a Lebedev grid for Ambisonics. In *Audio Engineering Society Convention 139*, New York.
- [Meyer and Elko, 2002] Meyer, J. and Elko, G. (2002). A highly scalable spherical microphone array based on an orthonormal decomposition of the soundfield. In *IEEE International Conference on Acoustics, Speech, and Signal Processing*, volume 2, pages 1781–1784.
- [Moreau, 2006] Moreau, S. (2006). *Étude et réalisation d’outils avancés d’encodage spatial pour la technique de spatialisation sonore Higher Order Ambisonics: microphone 3D et contrôle de distance*. PhD thesis, Université du Maine, Le Mans.

- [Moreau et al., 2006] Moreau, S., Daniel, J., and Bertet, S. (2006). 3d sound field recording with higher order ambisonics-objective measurements and validation of spherical microphone. In *Audio Engineering Society Convention 120*, pages 1–24, Paris. Audio Engineering Society.
- [Noisternig et al., 2003] Noisternig, M., Sontacchi, A., Musil, T., and Holdrich, R. (2003). A 3d ambisonic based binaural sound reproduction system. In *Audio Engineering Society Conference: 24th International Conference: Multichannel Audio, The New Reality*. AES.
- [Poletti, 2005] Poletti, M. A. (2005). Three-dimensional surround sound systems based on spherical harmonics. *Journal of the Audio Engineering Society*, 53(11):1004–1025.