



PMS132/PMS132B

8bit OTP MCU with 12-bit ADC

Datasheet

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6F-6, No.1, Sec. 3, Gongdao 5th Rd., Hsinchu City 30069, Taiwan, R.O.C.

TEL: 886-3-572-8688  www.padauk.com.tw

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Revision History:

Revision	Date	Description
0.00	2016/08/08	Preliminary version
0.01	2016/12/01	<ol style="list-style-type: none"> 1. Revise Chapter 3: Pin Assignment and Description 2. Revise Section 5.8.2: Hardware and Timing Diagram 3. Revise Section 5.8.3: Frequency of PWM Output 4. Add Section 5.8: 11-bit PWM Generator Functional Description 5. Add Section 6.43~6.51: IO Registers
0.02	2017/11/23	<ol style="list-style-type: none"> 1. Revise Section 1.2 System Features 2. Add Section 1.4 Package Information 3. Revise Chapter 2 General Description and Block Diagram 4. Add Chapter 3 Pin Assignment and Description:PMS132/PMS132B-S08, PMS132/PMS132B-U06 5. Revise Section 4.1 AC/DC Device Characteristics: “V_{IL}” and “V_{IH}” 6. Revise Section 4.3 Typical ILRC frequency vs. VDD and temperature 7. Revise Section 4.4 Typical IHRC frequency deviation vs. VDD 8. Revise Section 4.5 Typical ILRC Frequency vs. Temperature 9. Revise Section 4.6 Typical IHRC Frequency vs. Temperature 10. Revise Section 4.7 Typical operating current vs. VDD @ system clock = ILRC/n 11. Revise Section 4.8 Typical operating current vs. VDD @ system clock = IHRC/n 12. Revise Section 4.9 Typical operating current vs.VDD@system clock=4MHz EOSC / n 13. Revise Section 4.10 Typical operating current vs.VDD@system clock=32KHz EOSC / n 14. Revise Section 4.11 Typical operating current vs.VDD@system clock=1MHz EOSC / n 15. Revise Section 4.12 Typical IO driving current (I_{OH}) and sink current (I_{OL}) 16. Revise Section 4.13 Typical IO input high/low threshold voltage (V_{IH}/V_{IL}) 17. Revise Section 4.14 Typical resistance of IO pull high device 18. Add Section 4.15 Typical power down current (I_{PD}) and power save current (I_{PS}) 19. Revise Section 5.1 Program Memory - OTP 20. Revise Table 2: Three oscillation circuits 21. Revise Section 5.4.3 IHRC Frequency Calibration and System Clock 22. Revise Section 5.4.4 External Crystal Oscillator 23. Revise Fig. 3: Options of System Clock 24. Revise Section 5.5.2 Using the comparator 25. Revise Section 5.6 16-bit Timer 26. Revise Section 5.8 11-bit PWM Generator 27. Revise Section 5.11.1 Power-Save mode 28. Revise Fig. 20: ADC Block Diagram 29. Revise Section 5.14.4 Configure the analog pin 30. Revise Section 5.14.5 Using the ADC 31. Revise Section 6.3 Clock Mode Register 32. Revise Section 6.4 Interrupt Enable Register 33. Revise Section 6.5 Interrupt Request Register 34. Revise Section 6.11 Port A Digital Input Enable Register 35. Revise Section 6.12 Port B Digital Input Enable Register 36. Delete Section 6.13 MISC2 Register 37. Revise Section 6.21 Comparator Control Register 38. Revise Section 6.28 PWMG0 control Register 39. Revise Section 6.29 PWMG0 Counter Upper Bound High Register 40. Revise Section 6.30 PWMG0 Counter Upper Bound Low Register 41. Revise Section 6.31 PWMG0 Duty Value High Register 42. Revise Section 6.32 PWMG0 Duty Value Low Register 43. Revise Section 6.38 ADC Control Register 44. Revise Section 6.40 ADC Regulator Control Register 45. Revise Section 6.43 PWMG1 control Register 46. Revise Section 6.49 PWMG2 control Register

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		47. Delete Chapter 7: Instructions symbol “word” and “pc0” 48. Revise Section 7.5 “ <i>swapc</i> IO.n” Bit Operation Instruction 49. Add Chapter 8 Code Options 50. Revise Section 9.2.1 IO pin usage and setting 51. Revise Section 9.2.3 System clock switching 52. Add Section 9.2.6 IHRC 53. Revise Section 9.2.7 LVR 54. Revise Section 9.2.8 The result of Comparator controls the PWM output pins 55. Revise Section 9.2.10 BIT definition 56. Revise Section 9.2.11 Programming the PMS132/PMS132B 57. Revise Section 9.3 Using ICE 58. Revise all PWMG registers from ” R/W” to “WO”
1.03	2018/11/28	1. Add PMS132B 2. Update company address & Tel No. 3. Open 32KHz EOSC mode 4. Revise Section 1.1, 1.2 and 1.3 5. Revise Chapter 3 Pin Assignment and Description (add AVDD and AGND) 6. Revise Section 4.1 AC/DC Device Characteristics 7. Update Section 4.3, 4.4, 4.5, 4.6, 4.12, 4.13, 4.14 and 4.15 8. Revise Section 5.4.1, 5.4.4 and 5.4.5 9. Revise Chapter 5 Comparator 10. Revise Fig.4: Hardware diagram of comparator 11. Revise Section 5.5.2 and 5.5.3 12. Revise Section 5.7 8-bit Timer (Timer2/Timer3) with PWM generation 13. Add Fig. 12: Comparator controls the output of PWM waveform 14. Revise Section 5.8.2 and 5.8.3 15. Revise Fig. 14: Hardware Diagram of 11-bit PWM Generator 16. Revise Section 5.10 Interrupt 17. Revise Section 5.11.1 and 5.11.2 18. Revise Table 6: Differences in wake-up sources between Power-Save mode and Power-Down mode 19. Revise Section 5.13.2 LVR reset 20. Revise Fig. 20: Analog Input Model 21. Revise Section 5.14.5 Using the ADC 22. Revise Section 6.2, 6.19, 6.28, 6.30, 6.45, 6.51, 23. Revise Section 7.8 Summary of Instructions Execution Cycle (Delete Section 9.2.9) 24. Add Section 7.10 BIT definition (Delete Section 9.2.10) 25. Revise Chapter 8 Code Options 26. Updated the link in Section 9.1 27. Revise Section 9.2.1 IO pin usage and setting 28. Revise Section 9.2.5: TIMER time out 29. Revise Section 9.2.9 Programming the PMS132/PMS132B 30. Revise Section 9.3 Using ICE
1.04	2020/06/02	1. Revise Chapter 3, Chapter 8 2. Update 4.1 AC/DC Device Characteristics: I_{OL} , I_{OH} 3. Revise Section 4.12, 5.4.6, 5.7.1, 5.7.2, 5.7.3, 5.8, 5.8.3, 5.11.1, 5.11.3, 5.14.5, 6.3, 6.11, 6.12, 6.22, 6.48, 9.2.4, 9.2.9, 9.3 4. Delete Section 4.16 and add Section 5.2.1 5. Add Section 5.8.4, Fig. 16, Table 5

1. Features

1.1. Special Features

- ◆ General purpose series
- ◆ **Not supposed to use in AC RC step-down powered or high EFT requirement applications.**
PADAUK assumes no liability if such kind of applications can not pass the safety regulation tests.
- ◆ Operating temperature range: -20°C ~ 70°C

1.2. System Features

- ◆ 2KW OTP program memory
- ◆ 128 Bytes data RAM
- ◆ One hardware 16-bit timer
- ◆ Two hardware 8-bit timers with PWM generation
- ◆ Three hardware 11-bit PWM generators (PWMG0, PWMG1 & PWMG2)
- ◆ Provide one hardware comparator
- ◆ Provide 1T 8x8 hardware multiplier
- ◆ 14 IO pins with optional pull-high resistor
- ◆ Every IO pin can be configured to enable wake-up function
- ◆ Band-gap circuit to provide 1.20V reference voltage
- ◆ Up to 12-channel 12-bit resolution ADC with one channel comes from internal band-gap reference voltage or $0.25 \times V_{DD}$
- ◆ Provide ADC reference high voltage: external input, internal V_{DD} , Band-gap(1.20V), 4V, 3V, 2V
- ◆ Clock sources: internal high RC oscillator, internal low RC oscillator and external crystal oscillator
- ◆ For every wake-up enabled IO, two optional wake-up speed are supported: normal and fast
- ◆ Eight levels of LVR reset: 4.0V, 3.5V, 3.0V, 2.75V, 2.5V, 2.2V, 2.0V, 1.8V
- ◆ Four selectable external interrupt pins

1.3. CPU Features

- ◆ One processing unit operating mode
- ◆ 87 powerful instructions
- ◆ Most instructions are 1T execution cycle
- ◆ Programmable stack pointer to provide adjustable stack level
- ◆ Direct and indirect addressing modes for data access. Data memories are available for use as an index pointer of Indirect addressing mode
- ◆ IO space and memory space are independent

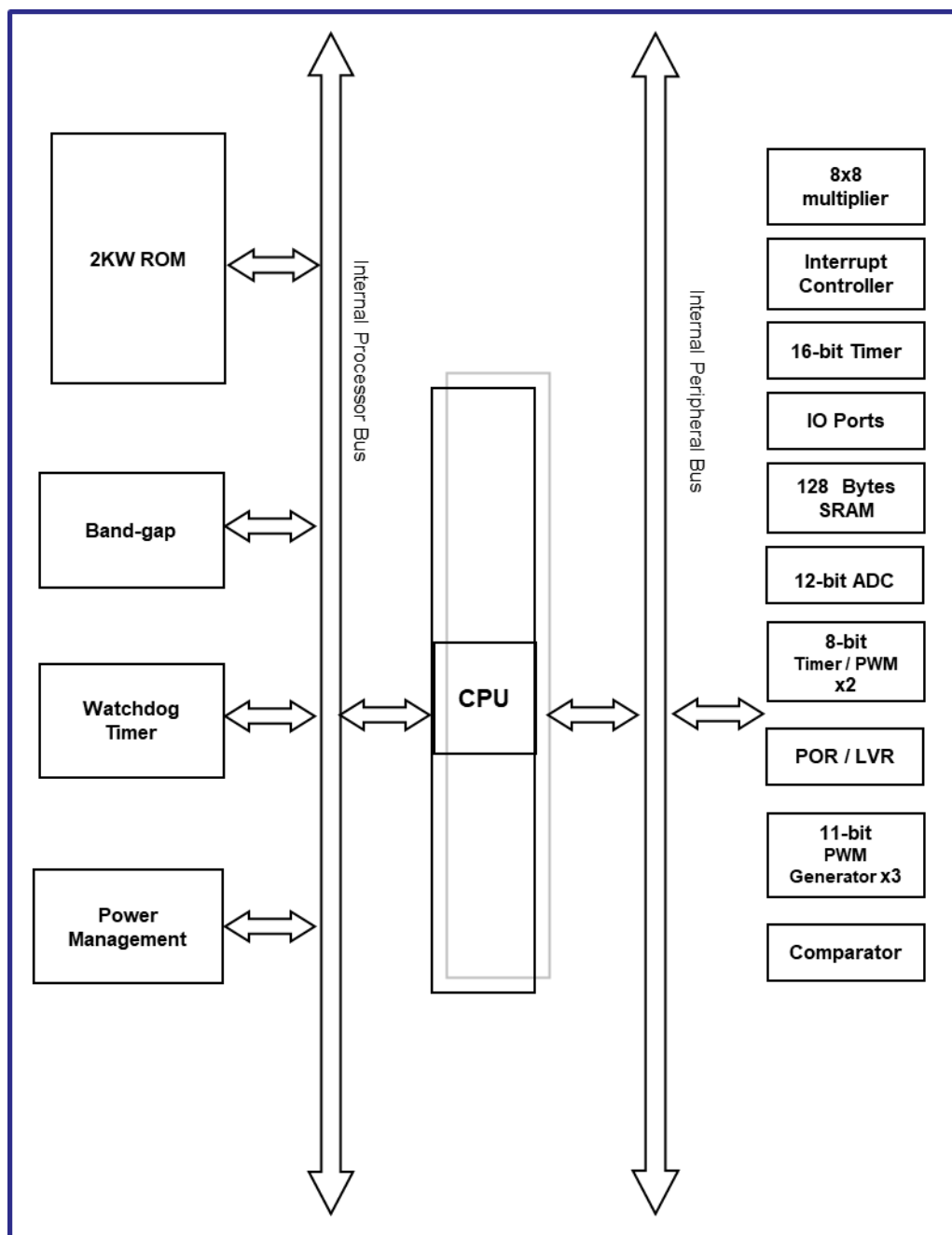
1.4. Package Information

- | | |
|--|---|
| ◆ PMS132/PMS132B-U06: SOT23-6 (60mil); | ◆ PMS132/PMS132B-S16A: SOP16A (150mil); |
| ◆ PMS132/PMS132B-S08: SOP8 (150mil); | ◆ PMS132/PMS132B-S16B: SOP16B (150mil); |
| ◆ PMS132/PMS132B-M10: MSOP10 (118mil); | ◆ PMS132/PMS132B-2J16A: QFN4*4-16P |
| ◆ PMS132/PMS132B-4N10: DFN3*3-10P | (0.65pitch); |
| (0.5pitch); | ◆ PMS132/PMS132B-1J16A: QFN3*3-16P |
| ◆ PMS132/PMS132B-S14: SOP14 (150mil); | (0.5pitch) |

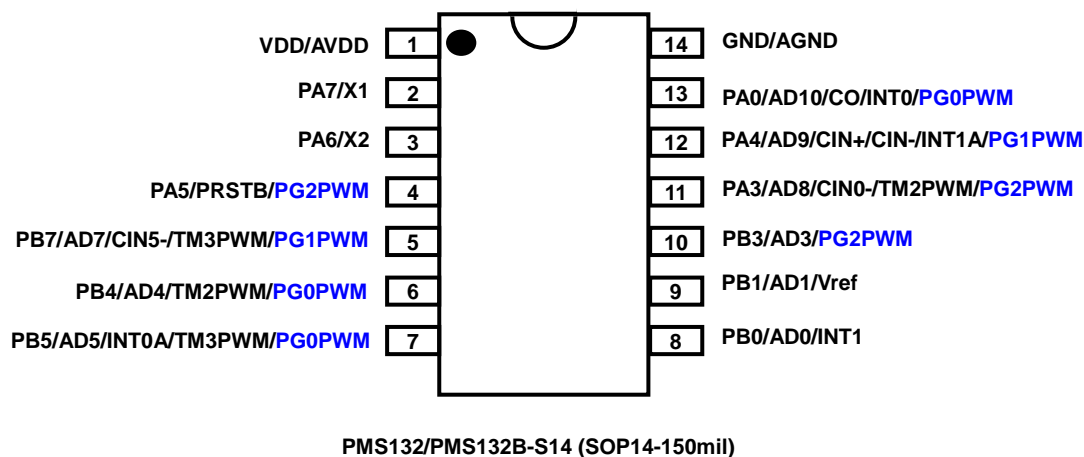
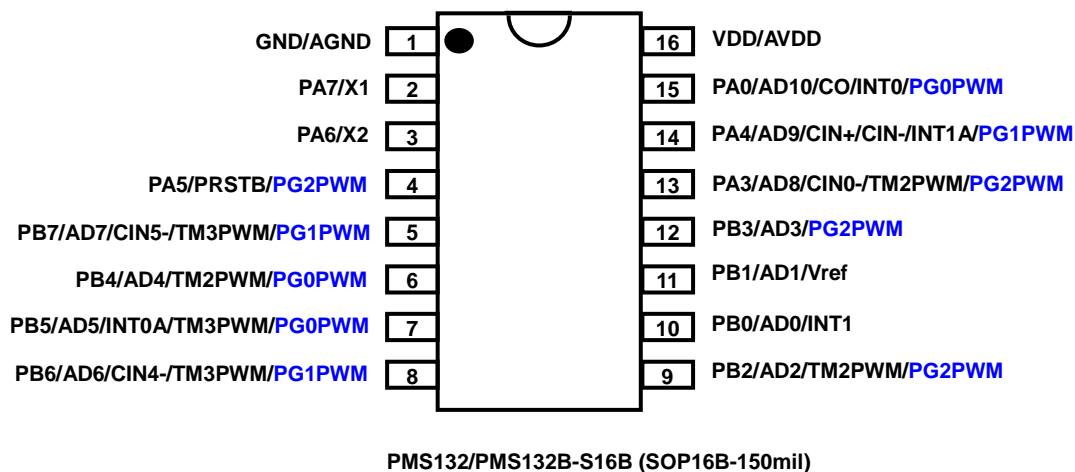
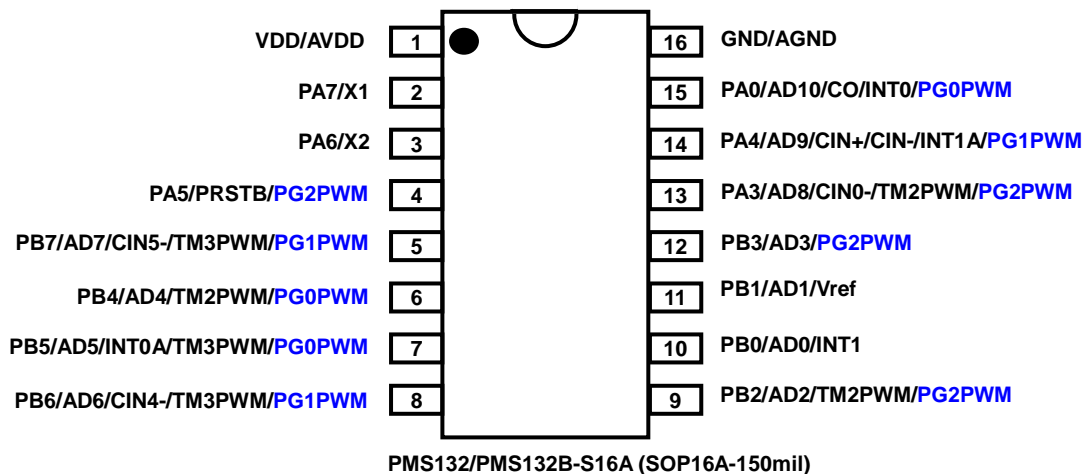
2. General Description and Block Diagram

The PMS132/PMS132B family is an ADC-Type, fully static, OTP-based CMOS 8-bit microcontroller. It employs RISC architecture and all the instructions are executed in one cycle except that some instructions are two cycles that handle indirect memory access.

2KW bits OTP program memory and 128 bytes data SRAM are inside, one up to 12 channels 12-bit ADC is built inside the chip with one channel for internal band-gap reference voltage or $0.25 \times V_{DD}$. PMS132/PMS132B also provides six hardware timers: one is 16-bit timer, two are 8-bit timers with PWM generation, and three hardware 11-bit timers with PWM generation are also included.

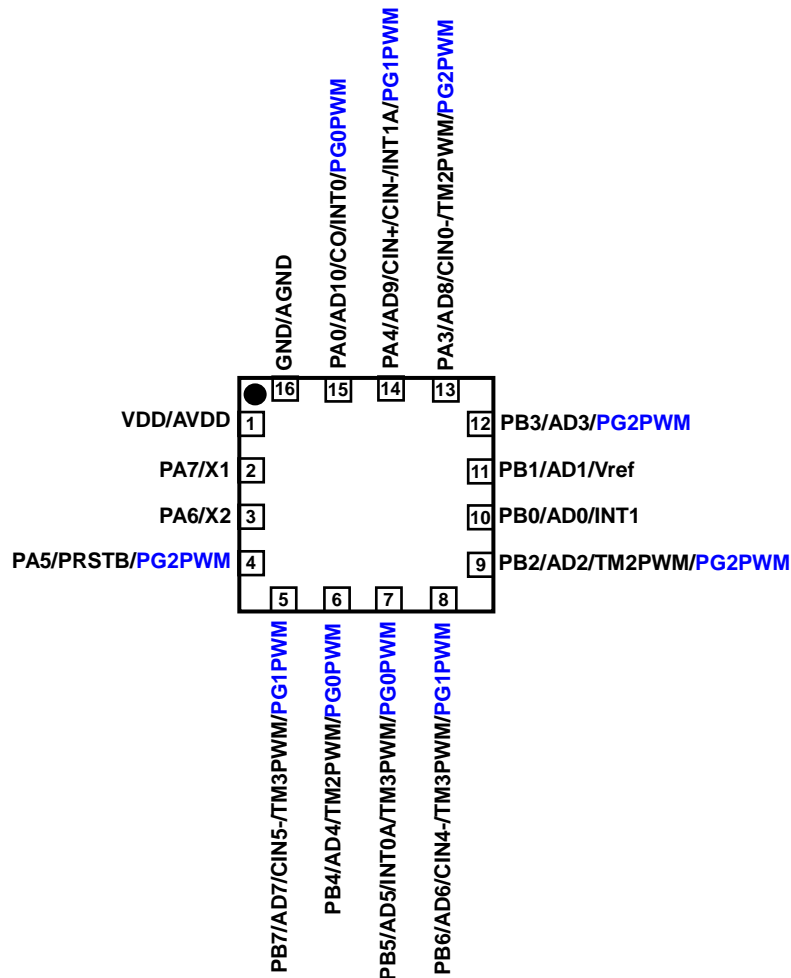


3. Pin Assignment and Description



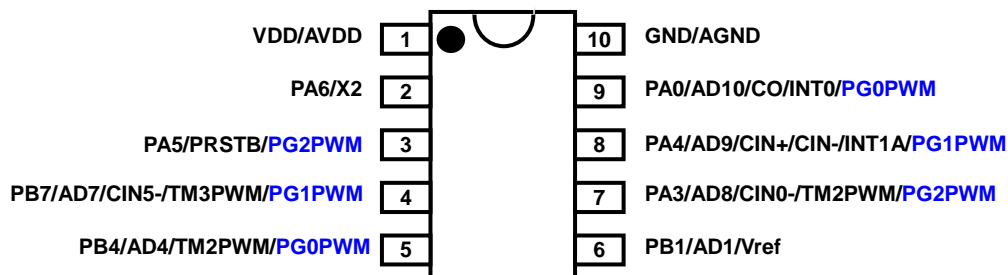
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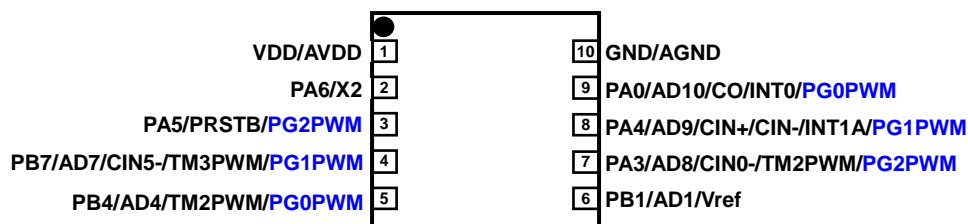


PMS132/PMS132B-2J16A(QFN4*4-16P-0.65pitch)

PMS132/PMS132B-1J16A(QFN3*3-16P-0.5pitch)



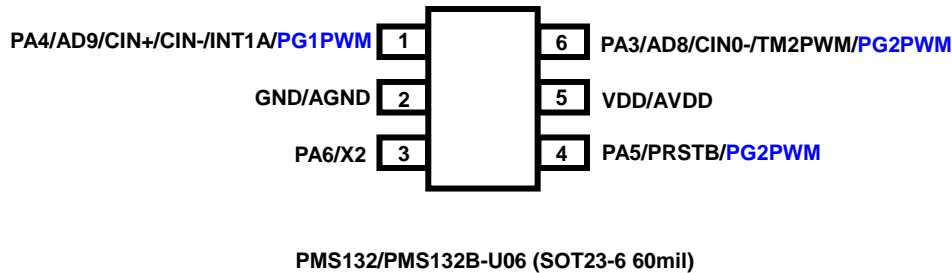
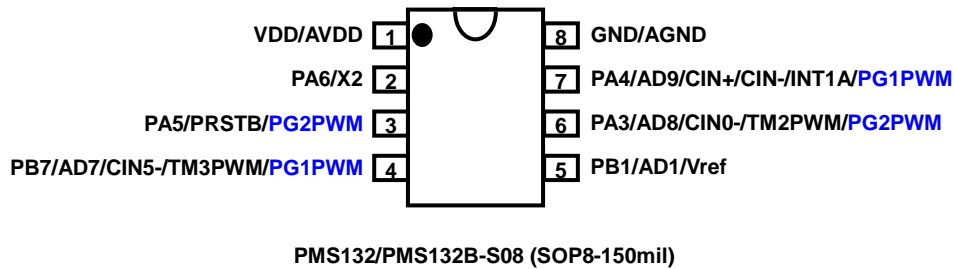
PMS132/PMS132B-M10 (MSOP10-118mil)



PMS132/PMS132B-4N10 (DFN3*3-10P-0.5pitch)

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Pin Description

Pin Name	Pin Type & Buffer Type	Description
PA7 / X1	IO ST / CMOS	<p>The functions of this pin can be:</p> <p>(1) Bit 7 of port A. It can be configured as digital input or two-state output, with pull-high resistor.</p> <p>(2) X1 when crystal oscillator is used.</p> <p>If this pin is used for crystal oscillator, bit 7 of padier register must be programmed "0" to avoid leakage current. This pin can be used to wake-up system during sleep mode; however, wake-up function is also disabled if bit 7 of padier register is "0".</p>
PA6 / X2	IO ST / CMOS	<p>The functions of this pin can be:</p> <p>(1) Bit 6 of port A. It can be configured as digital input or two-state output, with pull-high resistor.</p> <p>(2) X2 when crystal oscillator is used.</p> <p>If this pin is used for crystal oscillator, bit 6 of padier register must be programmed "0" to avoid leakage current. This pin can be used to wake-up system during sleep mode; however, wake-up function is also disabled if bit 6 of padier register is "0".</p>
PA5 / PRSTB / PG2PWM	IO (OD) ST / CMOS	<p>The functions of this pin can be:</p> <p>(1) Bit 5 of port A. It can be configured as digital input or open-drain output, with pull-high resistor.</p> <p>(2) Hardware reset.</p> <p>(3) Output of 11-bit PWM generator PWMG2. (ICE Does NOT support.)</p> <p>This pin can be used to wake-up system during sleep mode; however, wake-up function is also disabled if bit 5 of padier register is "0". <u>Please put 33Ω resistor in series to have high noise immunity when this pin is in input mode.</u></p>

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Pin Name	Pin Type & Buffer Type	Description
PA4 / AD9 / CIN+ / CIN1- / INT1A / PG1PWM	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ol style="list-style-type: none"> (1) Bit 4 of port A. It can be configured as digital input or two-state output, with pull-high resistor by software independently (2) Channel 9 of ADC analog input (3) Plus input source of comparator (4) Minus input source 1 of comparator (5) External interrupt line 1A. It can be used as an external interrupt line 1. <u>Both rising edge and falling edge are accepted to request interrupt service and configurable by register setting</u> (6) Output of 11-bit PWM generator PWMG1 <p>When this pin is configured as analog input, please use bit 4 of register padier to disable the digital input to prevent current leakage. The bit 4 of padier register can be set to "0" to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>
PA3 / AD8 / CIN0- / TM2PWM / PG2PWM	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ol style="list-style-type: none"> (1) Bit 3 of port A. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 8 of ADC analog input (3) Minus input source 0 of comparator (4) PWM output from Timer2 (5) Output of 11-bit PWM generator PWMG2 <p>When this pin is configured as analog input, please use bit 3 of register padier to disable the digital input to prevent current leakage. The bit 3 of padier register can be set to "0" to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>
PA0 / AD10 / CO / PG0PWM / INT0	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ol style="list-style-type: none"> (1) Bit 0 of port A. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 10 of ADC analog input (3) Output of comparator (4) Output of 11-bit PWM generator PWMG0 (5) External interrupt line 0. It can be used as an external interrupt line 0. <u>Both rising edge and falling edge are accepted to request interrupt service and configurable by register setting</u> <p>The bit 0 of padier register can be set to "0" to disable wake-up from power-down by toggling this pin.</p>

PMS132/PMS132B

8bit OTP MCU with 12-bit ADC

Pin Name	Pin Type & Buffer Type	Description
PB7 / AD7 / CIN5- / TM3PWM/ PG1PWM	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ul style="list-style-type: none"> (1) Bit 7 of port B. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 7 of ADC analog input (3) Minus input source 5 of comparator (4) PWM output from Timer3 (5) Output of 11-bit PWM generator PWMG1 <p>When this pin is configured as analog input, please use bit 7 of register <i>pbdier</i> to disable the digital input to prevent current leakage. The bit 7 of <i>pbdier</i> register can be set to “0” to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>
PB6 / AD6 / CIN4- / TM3PWM/ PG1PWM	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ul style="list-style-type: none"> (1) Bit 6 of port B. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 6 of ADC analog input (3) Minus input source 4 of comparator. (4) PWM output from Timer3 (5) Output of 11-bit PWM generator PWMG1 <p>When this pin is configured as analog input, please use bit 6 of register <i>pbdier</i> to disable the digital input to prevent current leakage. The bit 6 of <i>pbdier</i> register can be set to “0” to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>
PB5 / AD5 / TM3PWM / PG0PWM / INT0A	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ul style="list-style-type: none"> (1) Bit 5 of port B. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 5 of ADC analog input (3) PWM output from Timer3 (4) Output of 11-bit PWM generator PWMG0. (5) External interrupt line 0A. It can be used as an external interrupt line 0. <u>Both rising edge and falling edge are accepted to request interrupt service and configurable by register setting.</u> <p>When this pin is configured as analog input, please use bit 5 of register <i>pbdier</i> to disable the digital input to prevent current leakage. The bit 5 of <i>pbdier</i> register can be set to “0” to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>

PMS132/PMS132B

8bit OTP MCU with 12-bit ADC

Pin Name	Pin Type & Buffer Type	Description
PB4 / AD4 / TM2PWM / PG0PWM	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ul style="list-style-type: none"> (1) Bit 4 of port B. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 4 of ADC analog input (3) PWM output from Timer2 (4) Output of 11-bit PWM generator PWMG0. <p>When this pin is configured as analog input, please use bit 4 of register <i>pbdier</i> to disable the digital input to prevent current leakage. The bit 4 of <i>pbdier</i> register can be set to “0” to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>
PB3 / AD3 / PG2PWM	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ul style="list-style-type: none"> (1) Bit 3 of port B. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 3 of ADC analog input (3) Output of 11-bit PWM generator PWMG2 <p>When this pin is configured as analog input, please use bit 3 of register <i>pbdier</i> to disable the digital input to prevent current leakage. The bit 3 of <i>pbdier</i> register can be set to “0” to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>
PB2 / AD2 / TM2PWM / PG2PWM	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ul style="list-style-type: none"> (1) Bit 2 of port B. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 2 of ADC analog input (3) PWM output from Timer2 (4) Output of 11-bit PWM generator PWMG2 <p>When this pin is configured as analog input, please use bit 2 of register <i>pbdier</i> to disable the digital input to prevent current leakage. The bit 2 of <i>pbdier</i> register can be set to “0” to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>
PB1 / AD1 / Vref	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <ul style="list-style-type: none"> (1) Bit 1 of port B. It can be configured as digital input or two-state output, with pull-high resistor independently by software (2) Channel 1 of ADC analog input (3) External reference high voltage for ADC. <p>When this pin is configured as analog input, please use bit 1 of register <i>pbdier</i> to disable the digital input to prevent current leakage. The bit 1 of <i>pbdier</i> register can be set to “0” to disable digital input; wake-up from power-down by toggling this pin is also disabled.</p>

PMS132/PMS132B

8bit OTP MCU with 12-bit ADC

Pin Name	Pin Type & Buffer Type	Description
PB0 / AD0 / INT1	IO ST / CMOS / Analog	<p>The functions of this pin can be:</p> <p>(1) Bit 0 of port B. It can be configured as analog input, digital input or two-state output, with pull-high resistor independently by software.</p> <p>(2) Channel 0 of ADC analog input.</p> <p>(3) External interrupt line 1. It can be used as an external interrupt line 1. Both rising edge and falling edge are accepted to request interrupt service and configurable by register setting.</p> <p>When this pin acts as analog input, please use bit 0 of register <i>pbdier</i> to disable the digital input to prevent current leakage. If bit 0 of <i>pbdier</i> register is set to “0” to disable digital input, wake-up from power-down by toggling this pin is also disabled.</p>
VDD/ AVDD	VDD / AVDD	<p>VDD: digital positive power</p> <p>AVDD: Analog positive power</p> <p>VDD is the IC power supply while AVDD is the ADC power supply. AVDD and VDD are double bonding internally and they have the same external pin.</p>
GND / AGND	GND / AGND	<p>GND: digital negative power</p> <p>AGND: Analog negative power</p> <p>GND is the IC ground pin while AGND is the ADC ground pin. AGND and GND are double bonding internally and they have the same external pin.</p>
<p>Notes: IO: Input/Output; ST: Schmitt Trigger input; OD: Open Drain; Analog: Analog input pin</p> <p>CMOS: CMOS voltage level</p>		

4. Device Characteristics

4.1. AC/DC Device Characteristics

All data are acquired under the conditions of $V_{DD}=5.0V$, $f_{SYS}=2MHz$ unless noted.

Symbol	Description	Min	Typ	Max	Unit	Conditions (Ta=25°C)
V_{DD}	Operating Voltage	2.2	5.0	5.5	V	* Subject to LVR tolerance
LVR%	Low Voltage Reset Tolerance	-5		5	%	
f_{SYS}	System clock (CLK)* = IHRC/2 IHRC/4 IHRC/8 ILRC	0 0 0	55K	8M 4M 2M	Hz	$V_{DD} \geq 3.5V$ $V_{DD} \geq 2.5V$ $V_{DD} \geq 2.2V$ $V_{DD} = 5.0V$
I_{OP}	Operating Current		1 15		mA uA	$f_{SYS}=IHRC/16=1MIPS@5.0V$ $f_{SYS}=ILRC=55KHz@3.3V$
I_{PD}	Power Down Current (by stopsys command)		1 0.6		uA uA	$f_{SYS}=0Hz$, $V_{DD}=5.0V$ $f_{SYS}=0Hz$, $V_{DD}=3.3V$
I_{PS}	Power Save Current (by stopexe command)		5		uA	$V_{DD}=5.0V$; $f_{SYS}=ILRC$ Only ILRC module is enabled.
V_{IL}	Input low voltage for IO lines	0 0		0.1 V_{DD} 0.2 V_{DD}	V	PA5 Others IO
V_{IH}	Input high voltage for IO lines	0.8 V_{DD} 0.7 V_{DD}		V_{DD} V_{DD}	V	PA5 Others IO
I_{OL}	IO lines sink current PA0, PA3, PA4, PB2, PB5, PB6 PB4, PB7 (Strong) PB4, PB7 (Normal) Others IO		20 38 20 13		mA	$V_{DD}=5.0V$, $V_{OL}=0.5V$
I_{OH}	IO lines drive current PA5 PB4, PB7 (Strong) PB4, PB7 (Normal) Others IO		0 -32 -14 -12		mA	$V_{DD}=5.0V$, $V_{OH}=4.5V$
V_{IN}	Input voltage	-0.3		$V_{DD}+0.3$	V	
$I_{INJ}(PIN)$	Injected current on pin			1	mA	$V_{DD}+0.3 \geq V_{IN} \geq -0.3$
R_{PH}	Pull-high Resistance		100 200 450		K Ω	$V_{DD}=5.0V$ $V_{DD}=3.3V$ $V_{DD}=2.2V$
V_{BG}	Band-gap Reference Voltage	1.145*	1.20*	1.255*	V	$V_{DD}=2.2V \sim 5.5V$ $-20^{\circ}C < Ta < 70^{\circ}C$ *
f_{IHRC}	Frequency of IHRC after calibration *	15.76* 15.20*	16* 16*	16.24* 16.80*	MHz	$25^{\circ}C$, $V_{DD}=2.2V \sim 5.5V$ $V_{DD}=2.2V \sim 5.5V$, $0^{\circ}C < Ta < 70^{\circ}C$ *
t_{INT}	Interrupt pulse width	30			ns	$V_{DD}=5.0V$

PMS132/PMS132B

8bit OTP MCU with 12-bit ADC

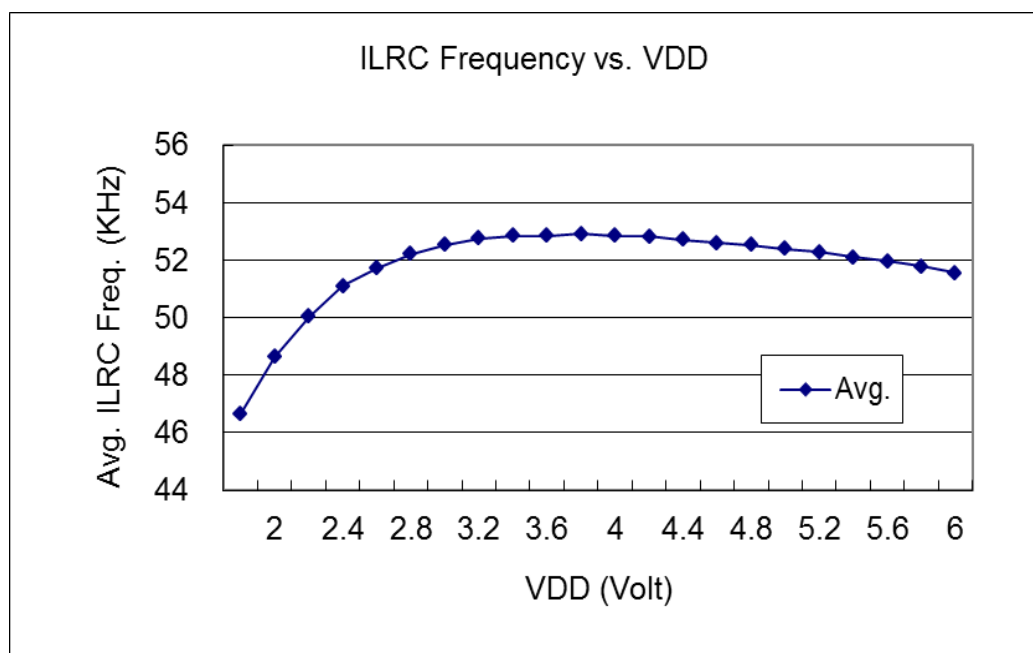
Symbol	Description	Min	Typ	Max	Unit	Conditions (Ta=25°C)
V _{ADC}	Supply voltage for workable ADC	2.2		V _{DD}	V	
V _{AD}	AD Input Voltage	0		V _{DD}	V	
ADrs	ADC resolution		12		bit	
ADcs	ADC current consumption		0.9 0.8		mA	@5V @3V
ADclk	ADC clock period		2		us	2.2V ~ 5.5V
t _{ADCONV}	ADC conversion time (T _{ADCLK} is the period of the selected AD conversion clock)		16		T _{ADCLK}	12-bit resolution
AD DNL	ADC Differential NonLinearity		±2*		LSB	
AD INL	ADC Integral NonLinearity		±4*		LSB	
ADos	ADC offset*		2		mV	@ V _{DD} =3V
V _{REFH}	ADC reference high voltage					@ V _{DD} =5V, 25 °C
	4V	3.90	4	4.10		
	3V	2.93	3	3.07		
	2V	1.95	2	2.05		
V _{DR}	RAM data retention voltage*	1.5			V	in stop mode
t _{WDT}	Watchdog timeout period		8k		T _{ILRC}	misc[1:0]=00 (default)
			16k			misc[1:0]=01
			64k			misc[1:0]=10
			256k			misc[1:0]=11
t _{WUP}	Wake-up time period for fast wake-up		45		T _{ILRC}	Where T _{ILRC} is the time period of ILRC
	Wake-up time period for normal wake-up		3000			
t _{SBP}	System boot-up period from power-on for Normal boot-up		60		ms	V _{DD} =5V
	System boot-up period from power-on for Fast boot-up		600		us	V _{DD} =5V
t _{RST}	External reset pulse width	120			us	@ V _{DD} =5V
CPos	Comparator offset*	-	±10	±20	mV	
CPcm	Comparator input common mode*	0		V _{DD} -1.5	V	
CPspt	Comparator response time**		100	500	ns	Both Rising and Falling
CPmc	Stable time to change comparator mode		2.5	7.5	us	
CPcs	Comparator current consumption		20		uA	V _{DD} = 3.3V

*These parameters are for design reference, not tested for each chip.

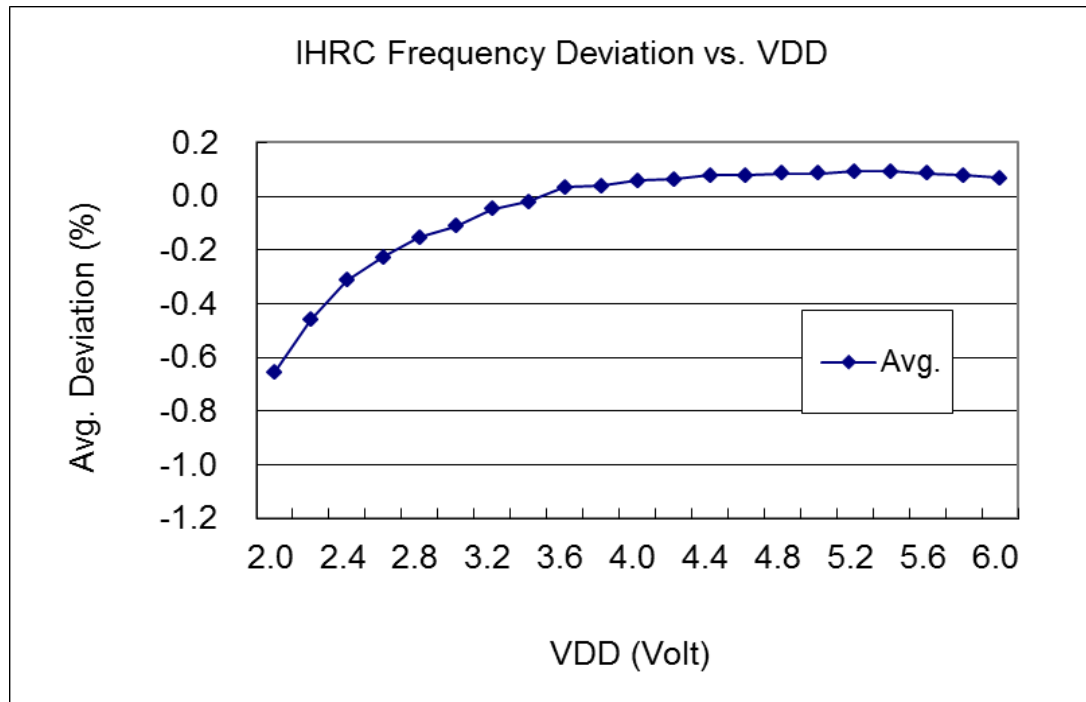
4.2. Absolute Maximum Ratings

- Supply Voltage 2.2V ~ 5.5V
- Input Voltage -0.3V ~ $V_{DD} + 0.3V$
- Operating Temperature -20°C ~ 70°C
- Junction Temperature 150°C
- Storage Temperature -50°C ~ 125°C

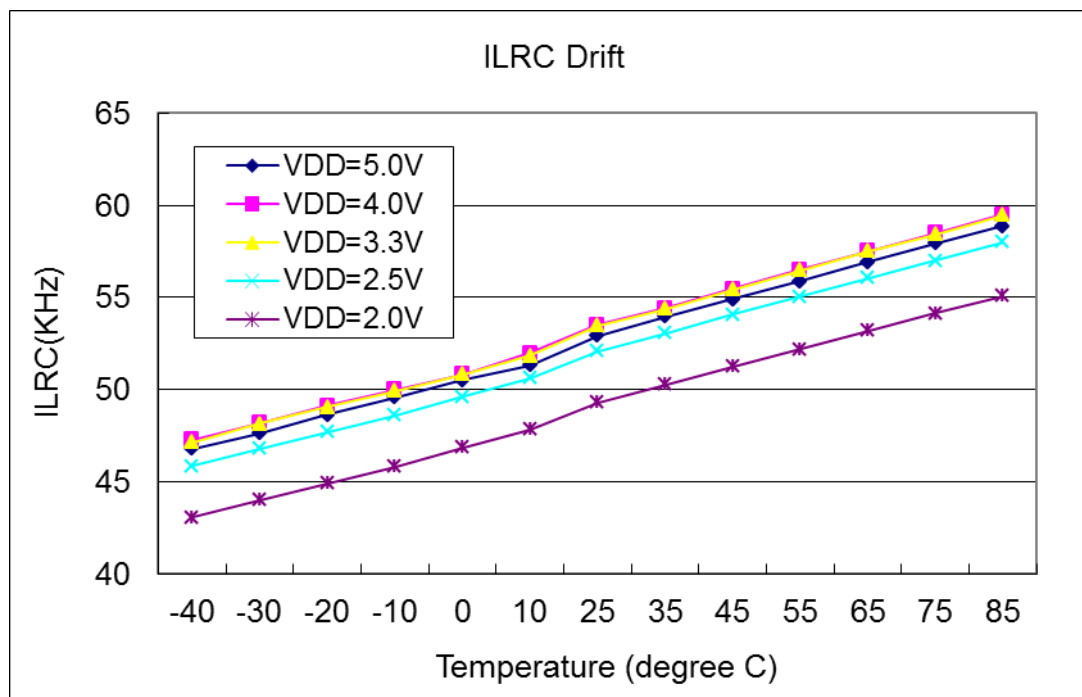
4.3. Typical ILRC frequency vs. VDD and temperature



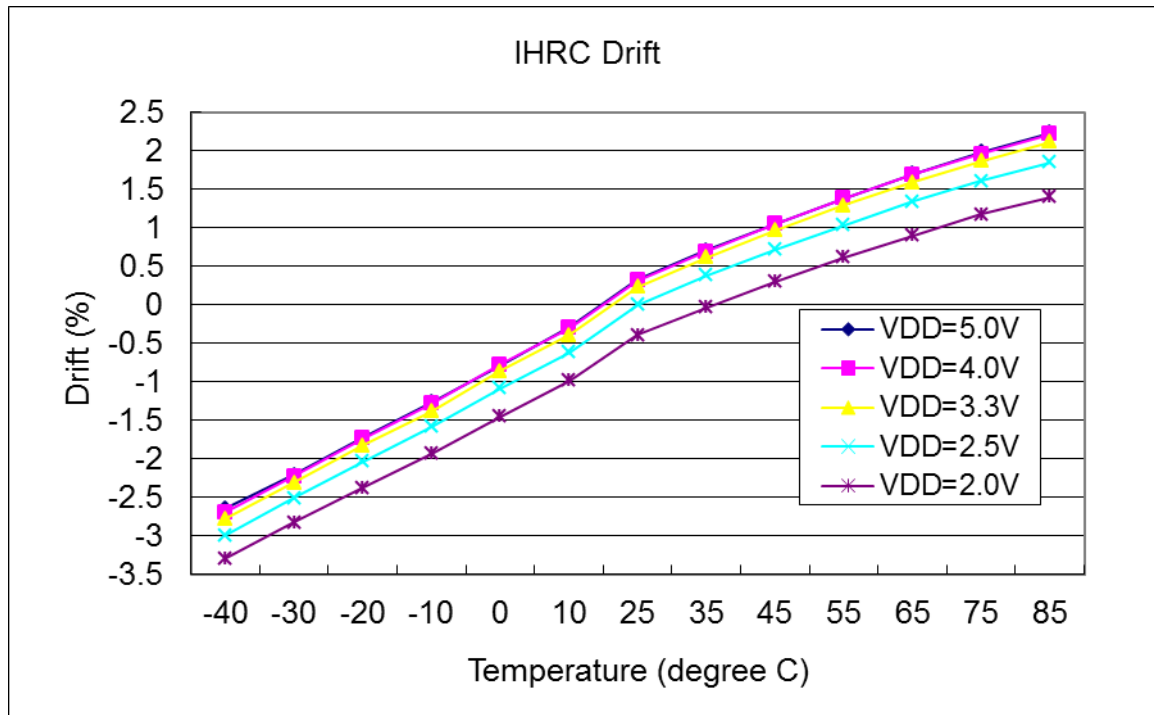
4.4. Typical IHRC frequency deviation vs. VDD(calibrated to 16MHz)



4.5. Typical ILRC Frequency vs. Temperature



4.6. Typical IHRC Frequency vs. Temperature (calibrated to 16MHz)

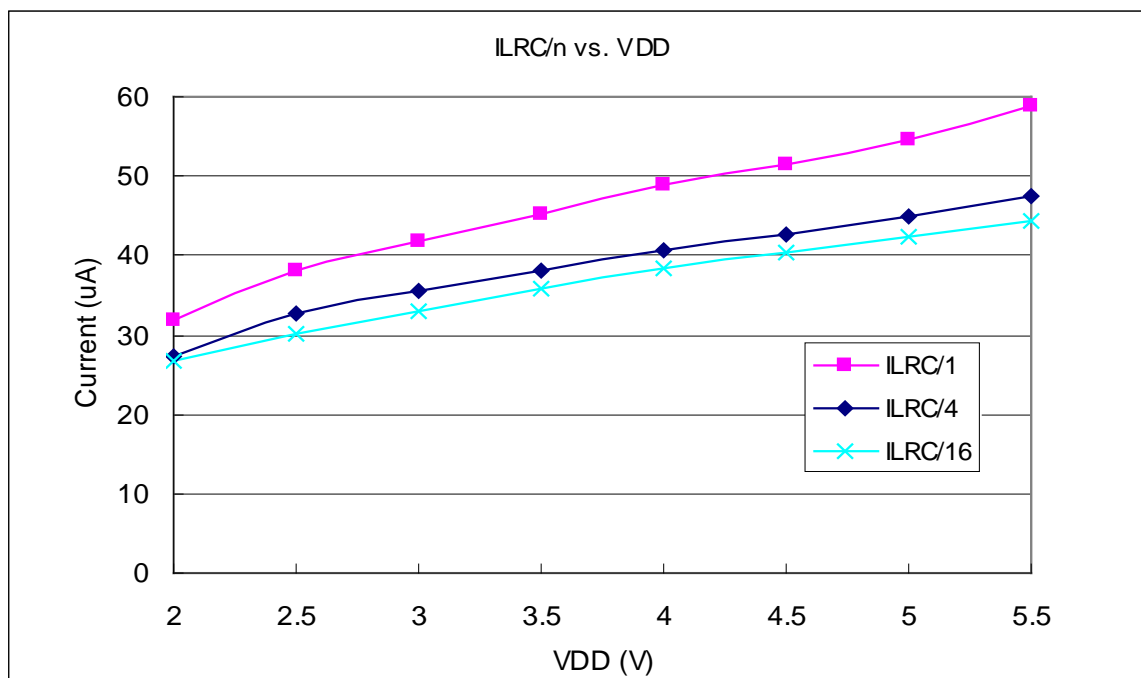


4.7. Typical operating current vs. VDD @ system clock = ILRC/n

Conditions:

ON: ILRC, Band-gap, LVR; **OFF:** IHRC, EOSC, T16, TM2, TM3, ADC modules;

IO: PA0:0.5Hz output toggle and no loading, **others:** input and no floating

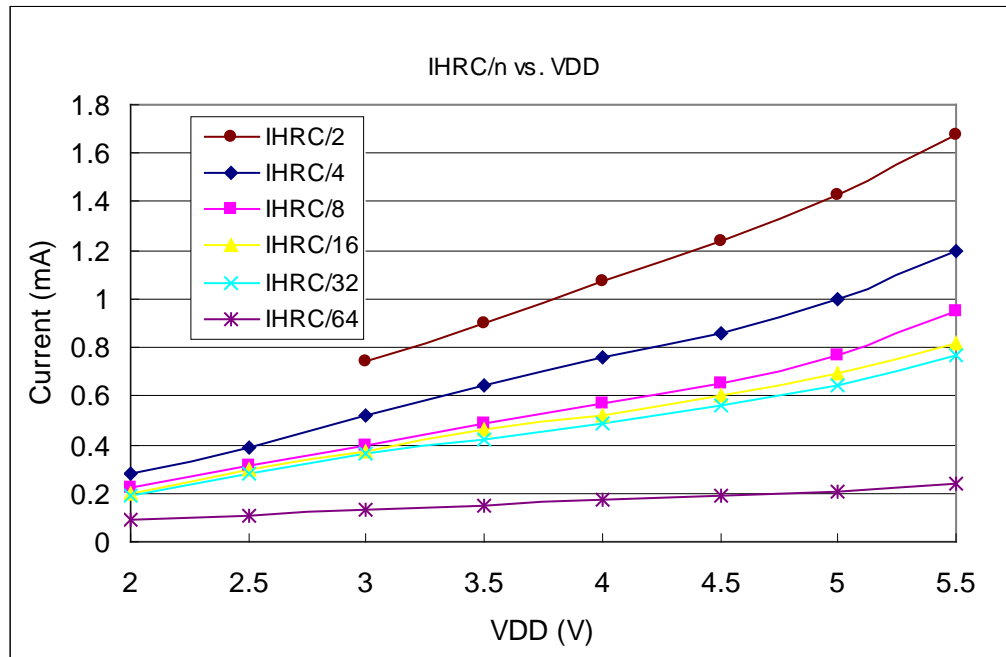


4.8. Typical operating current vs. VDD @ system clock = IHRC/n

Conditions:

ON: Band-gap, LVR, IHRC; **OFF:** ILRC, EOSC, LVR, T16, TM2, TM3, ADC modules;

IO: PA0:0.5Hz output toggle and no loading, **others:** input and no floating

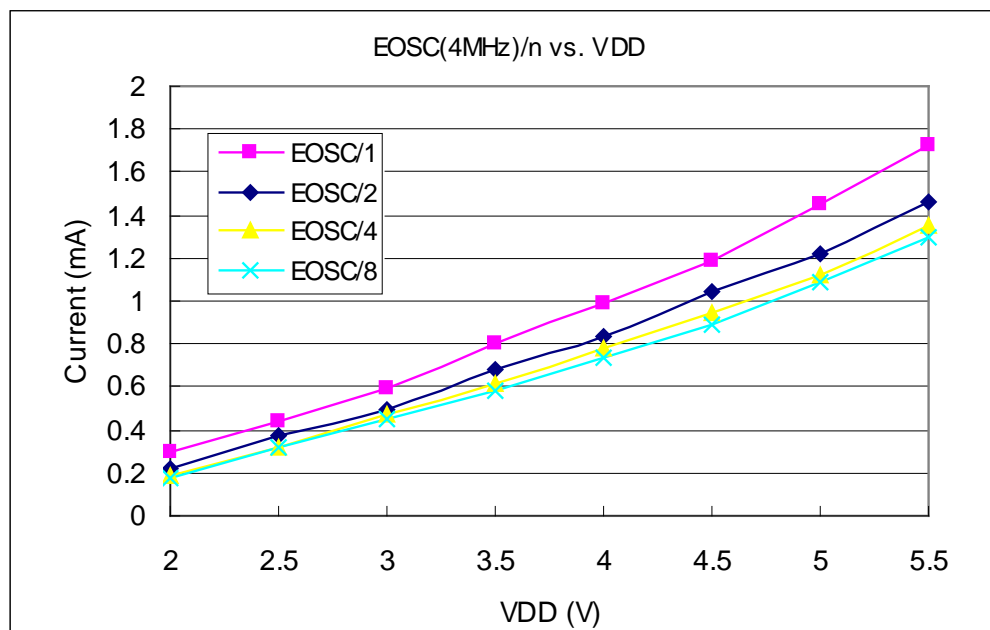


4.9. Typical operating current vs. VDD @ system clock = 4MHz EOSC / n

Conditions:

ON: EOSC, MISC.6 = 1, Band-gap, LVR; **OFF:** IHRC, ILRC, T16, TM2, TM3, ADC modules;

IO: PA0:0.5Hz output toggle and no loading, **others:** input and no floating

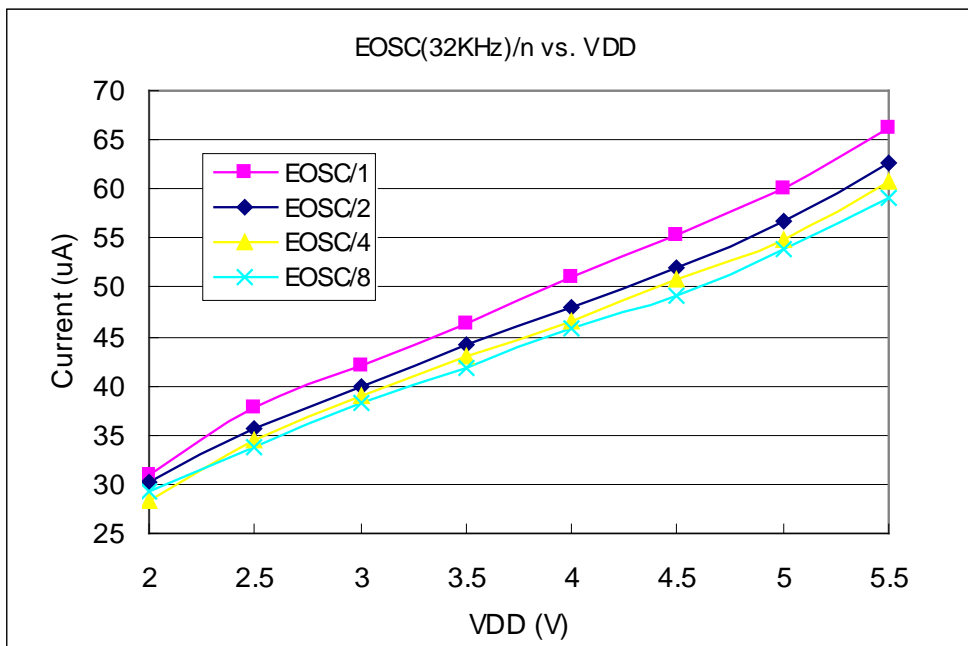


4.10. Typical operating current vs. VDD @ system clock = 32KHz EOSC / n

Conditions:

ON: EOSC, MISC.6 = 1, Band-gap, LVR; **OFF:** IHRC, ILRC, T16, TM2, TM3, ADC modules;

IO: PA0:0.5Hz output toggle and no loading, **others:** input and no floating

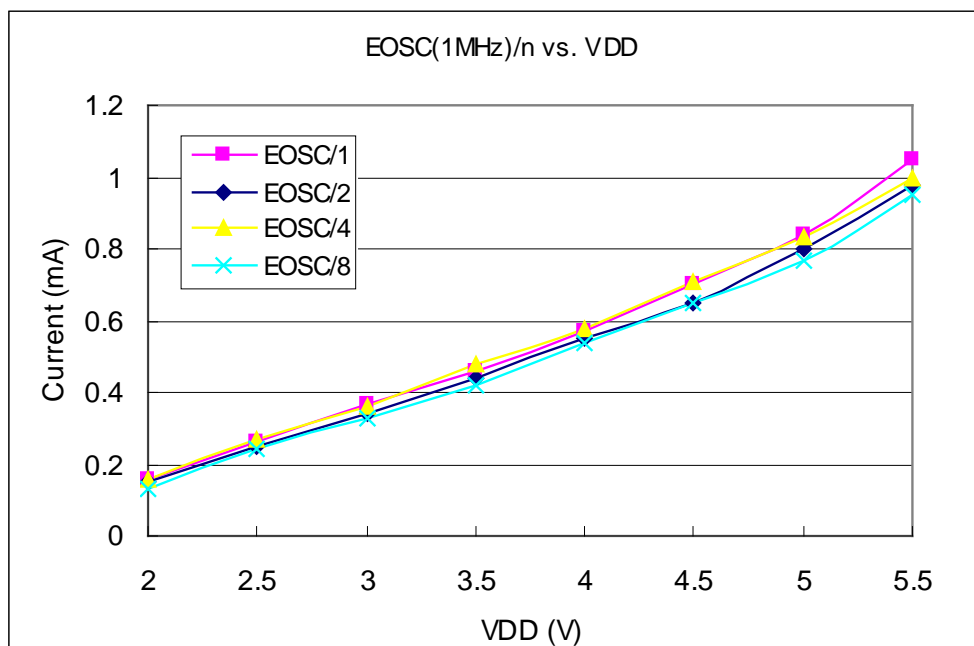


4.11. Typical operating current vs. VDD @ system clock = 1MHz EOSC / n

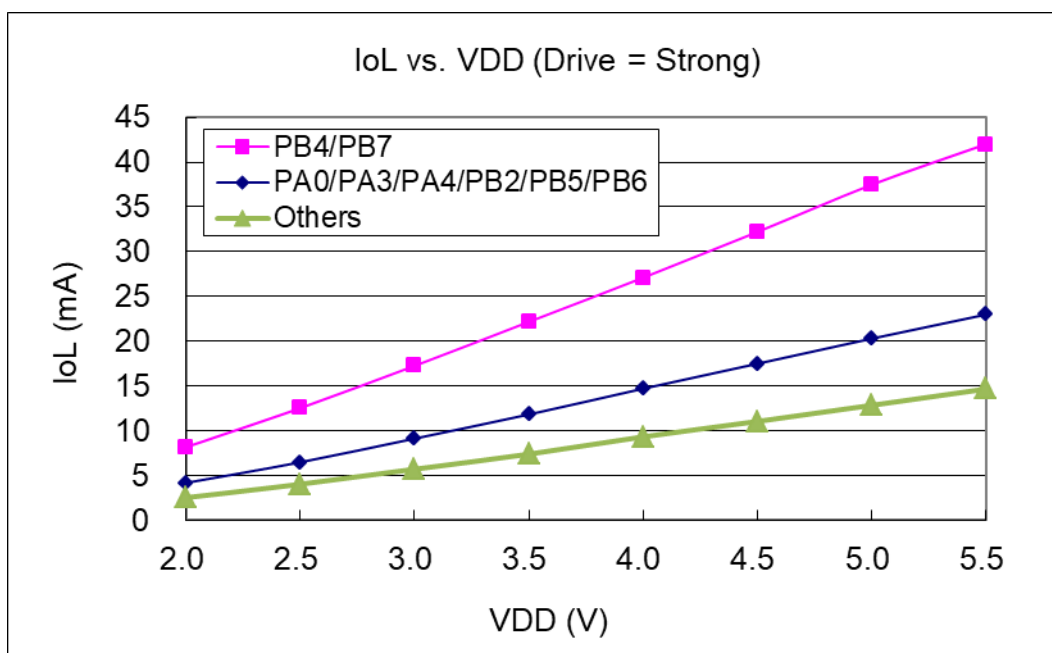
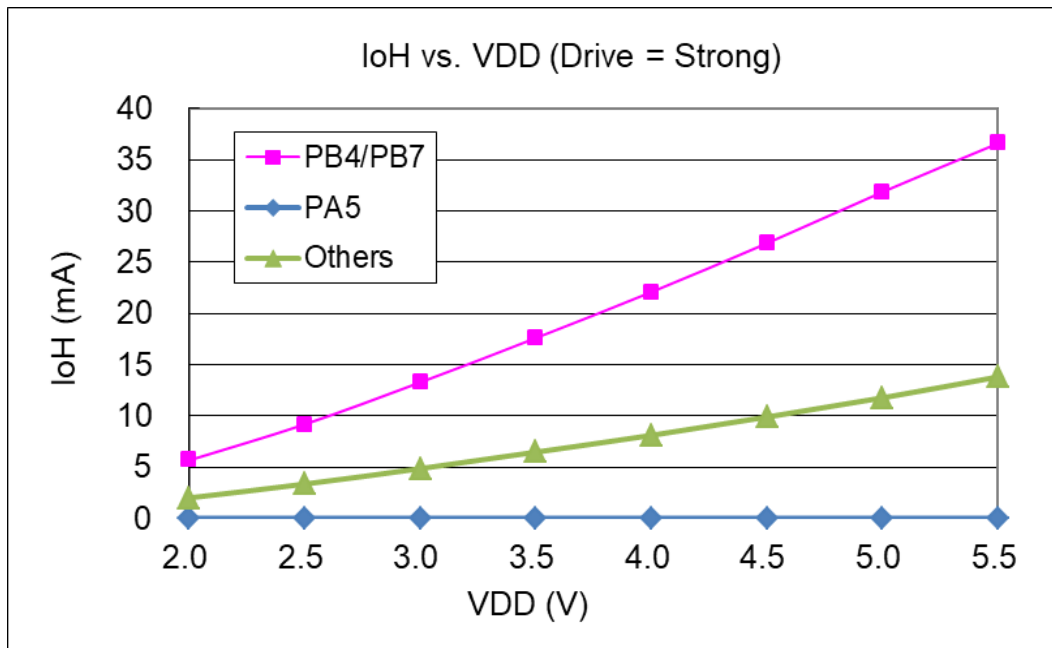
Conditions:

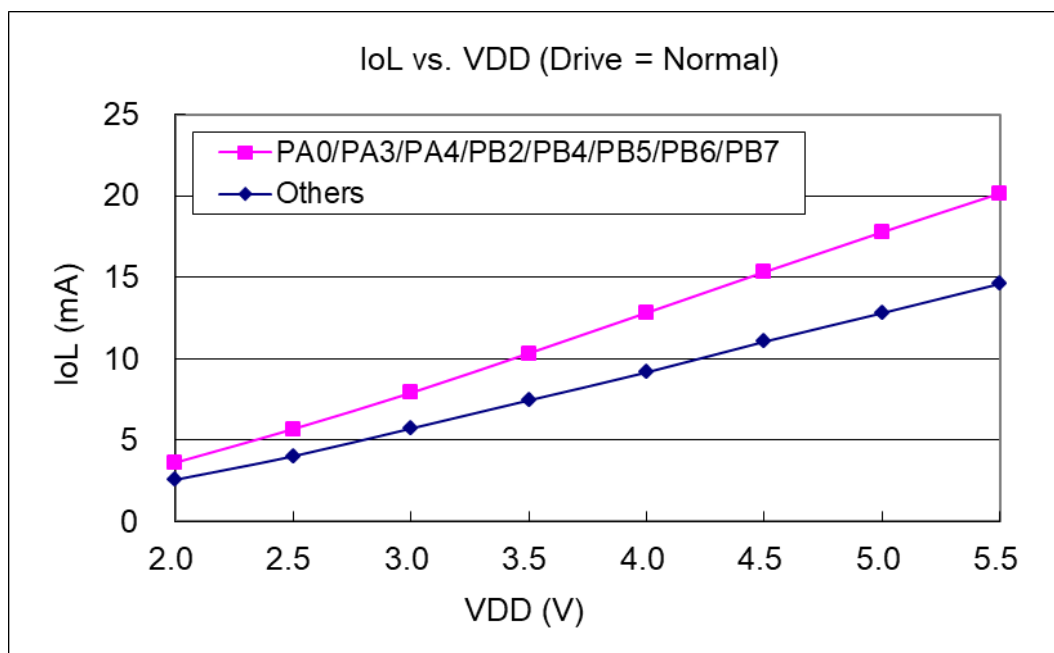
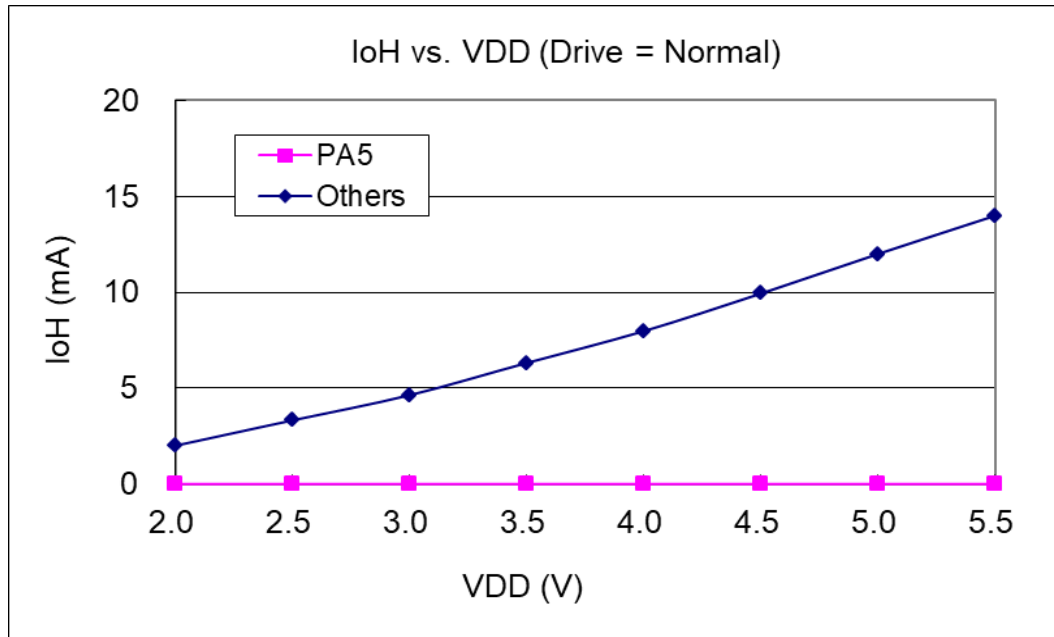
ON: EOSC, MISC.6 = 1, Band-gap, LVR; **OFF:** IHRC, ILRC, T16, TM2, TM3, ADC modules;

IO: PA0:0.5Hz output toggle and no loading, **others:** input and no floating

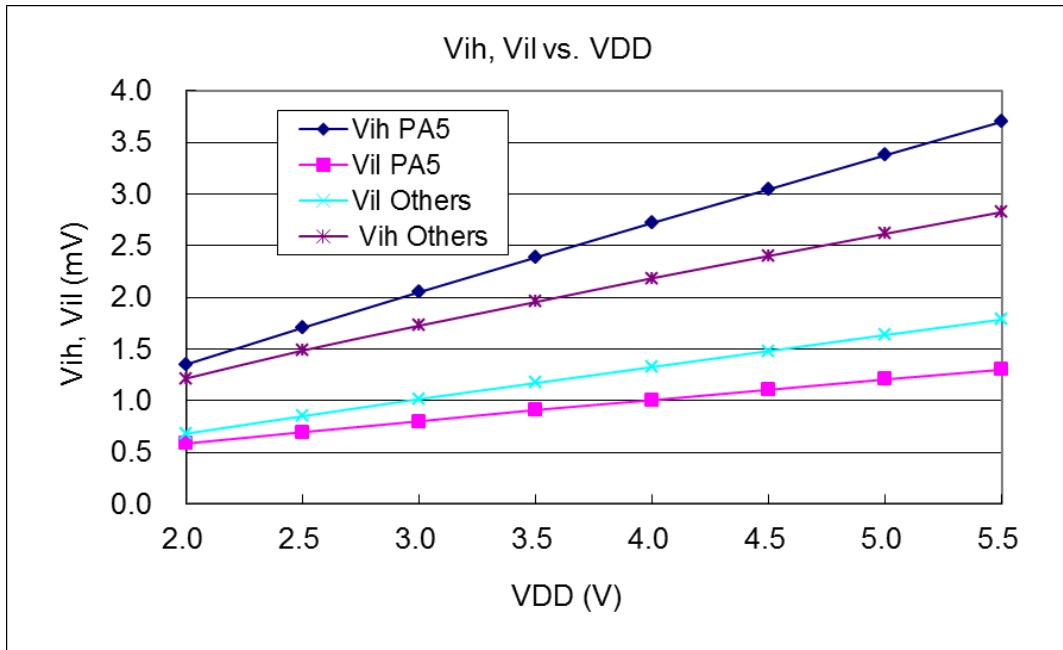


4.12. Typical IO driving current (I_{OH}) and sink current (I_{OL})

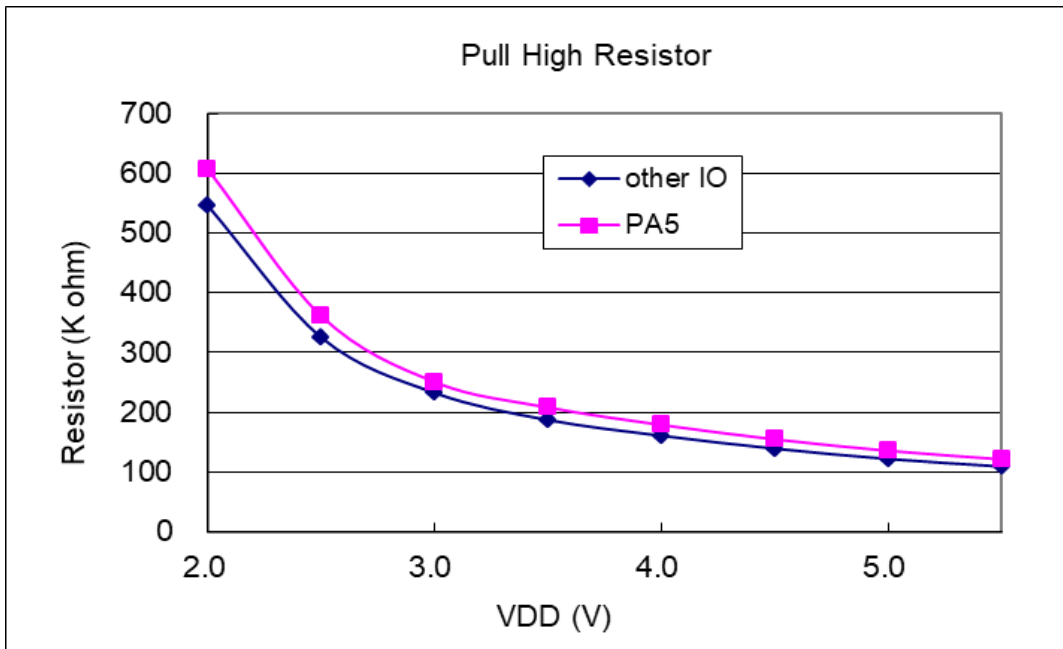




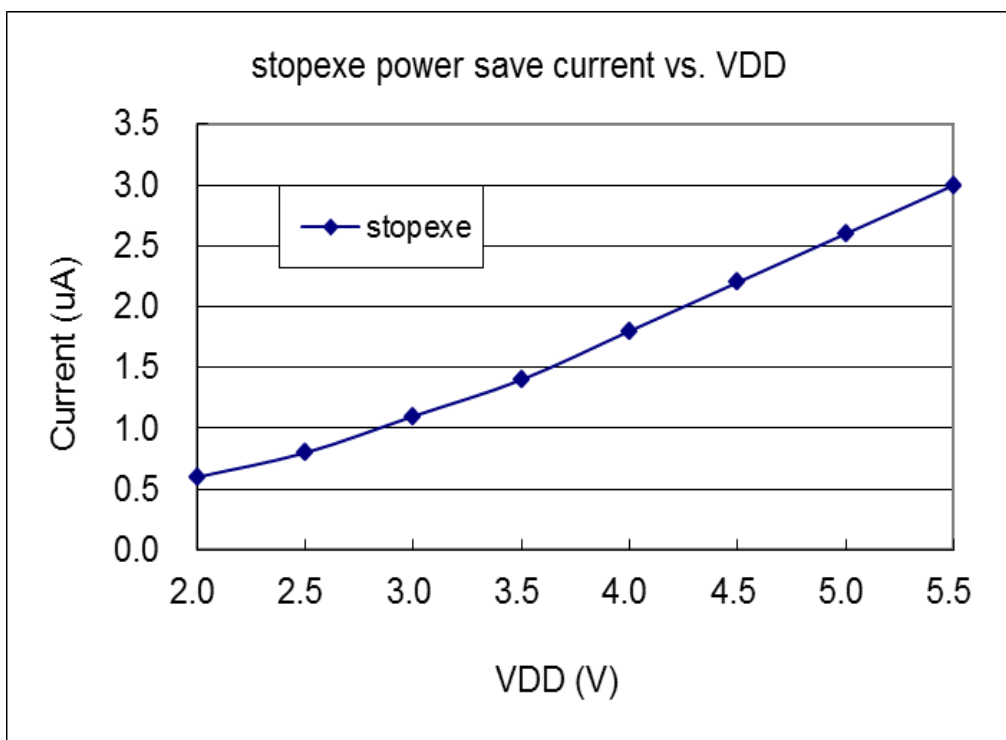
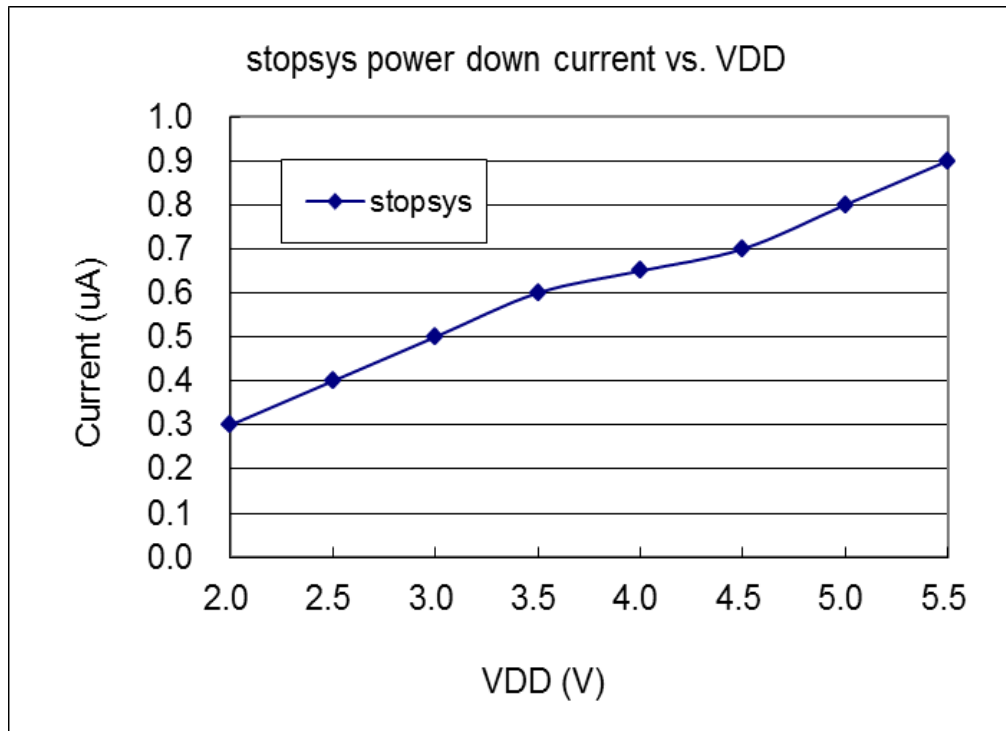
4.13. Typical IO input high/low threshold voltage (V_{IH}/V_{IL})



4.14. Typical resistance of IO pull high device



4.15. Typical power down current (I_{PD}) and power save current (I_{PS})



5. Functional Description

5.1. Program Memory - OTP

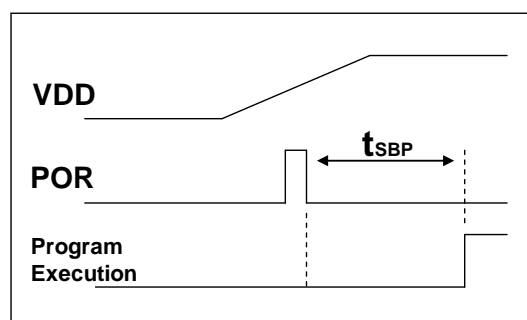
The OTP (One Time Programmable) program memory is used to store the program instructions to be executed. The OTP program memory may contains the data, tables and interrupt entry. After reset, the initial address 0x000 is reserved for system using, so the program will start from 0x001 which is GOTO FPPA0 instruction usually. The interrupt entry is 0x010 if used, the last 16 addresses are reserved for system using, like checksum, serial number, etc. The OTP program memory for PMS132/PMS132B is a 2Kx14 bit that is partitioned as Table 1. The OTP memory from address '0x7E8 to 0x7FF is for system using, address space from 0x002 to 0x00F and from 0x011 to 0x7E7 are user program spaces.

Address	Function
0x000	System Using
0x001	GOTO FPPA0 instruction
0x002	User program
•	•
0x00F	User program
0x010	Interrupt entry address
0x011	User program
•	•
0x7E7	User program
0x7E8	System Using
•	•
0x7FF	System Using

Table 1: Program Memory Organization

5.2. Boot Procedure

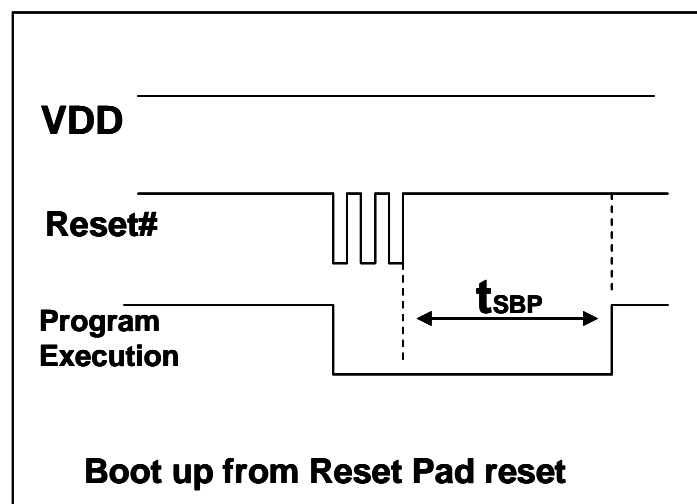
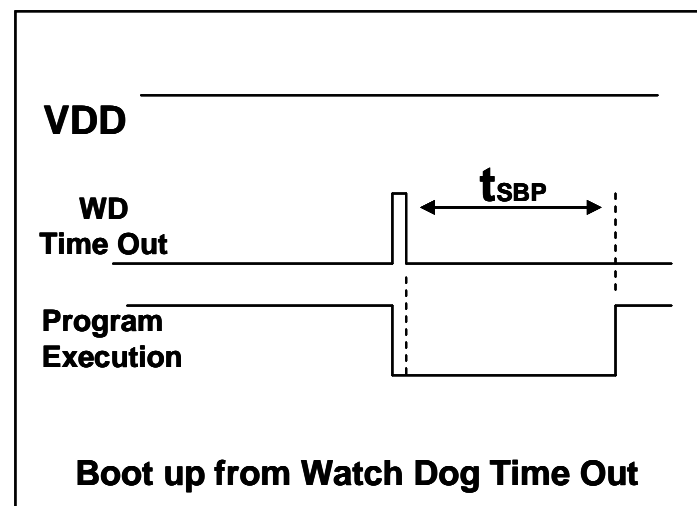
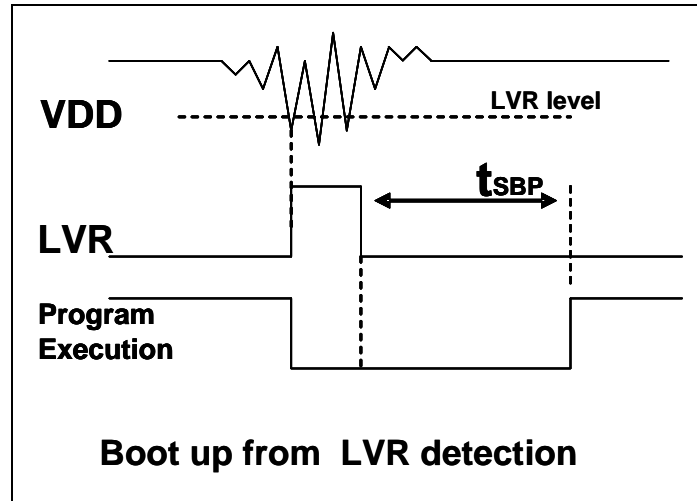
POR (Power-On-Reset) is used to reset PMS132/PMS132B when power up. The boot up time can be optional fast or normal. Time for fast boot-up is about 45 ILRC clock cycles whereas 3000 ILRC clock cycles for normal boot-up. Customer must ensure the stability of supply voltage after power up no matter which option is chosen, the power up sequence is shown in the Fig. 1 and t_{SBP} is the boot-up time.



Boot up from Power-On Reset

Fig.1: Power-Up Sequence

5.2.1. Timing charts for reset conditions



5.3. Data Memory - SRAM

The access of data memory can be byte or bit operation. Besides data storage, the SRAM data memory is also served as data pointer of indirect access method and the stack memory.

The stack memory is defined in the data memory. The stack pointer is defined in the stack pointer register; the depth of stack memory of each processing unit is defined by the user. The arrangement of stack memory fully flexible and can be dynamically adjusted by the user.

For indirect memory access mechanism, the data memory is used as the data pointer to address the data byte. All the data memory could be the data pointer; it's quite flexible and useful to do the indirect memory access. Since the data width is 8-bit, all the 128 bytes data memory of PMS132/PMS132B can be accessed by indirect access mechanism.

5.4. Oscillator and clock

There are three oscillator circuits provided by PMS132/PMS132B: external crystal oscillator (EOSC), internal high RC oscillator (IHRC) and internal low RC oscillator (ILRC), and these three oscillators are enabled or disabled by registers `eoscr.7`, `clkmd.4` and `clkmd.2` independently. User can choose one of these three oscillators as system clock source and use **clkmd** register to target the desired frequency as system clock to meet different applications.

Oscillator Module	Enable/Disable
EOSC	<code>eoscr.7</code>
IHRC	<code>clkmd.4</code>
ILRC	<code>clkmd.2</code>

Table 2: Three oscillation circuits

5.4.1. Internal High RC oscillator and Internal Low RC oscillator

After boot-up, the IHRC and ILRC oscillators are enabled. The frequency of IHRC can be calibrated to eliminate process variation by **ihrcr** register; normally it is calibrated to 16MHz. Please refer to the measurement chart for IHRC frequency verse V_{DD} and IHRC frequency verse temperature.

The frequency of ILRC will vary by process, supply voltage and temperature, please refer to DC specification and do not use for accurate timing application.

5.4.2. Chip calibration

The IHRC frequency and band-gap reference voltage may be different chip by chip due to manufacturing variation, PMS132/PMS132B provide the IHRC frequency calibration to eliminate this variation, and this function can be selected when compiling user's program and the command will be inserted into user's program automatically. The calibration command is shown as below:

`.ADJUST_IC SYSCLK=IHRC/(p1), IHRC=(p2)MHz, V_{DD} =(p3)V;`

Where, **p1**=2, 4, 8, 16, 32; In order to provide different system clock.

p2=14 ~ 18; In order to calibrate the chip to different frequency, 16MHz is the usually one.

p3=2.5 ~ 5.5; In order to calibrate the chip under different supply voltage.

5.4.3. IHRC Frequency Calibration and System Clock

During compiling the user program, the options for IHRC calibration and system clock are shown as Table 3:

SYSCLK	CLKMD	IHRCR	Description
○ Set IHRC / 2	= 34h (IHRC / 2)	Calibrated	IHRC calibrated to 16MHz, CLK=8MHz (IHRC/2)
○ Set IHRC / 4	= 14h (IHRC / 4)	Calibrated	IHRC calibrated to 16MHz, CLK=4MHz (IHRC/4)
○ Set IHRC / 8	= 3Ch (IHRC / 8)	Calibrated	IHRC calibrated to 16MHz, CLK=2MHz (IHRC/8)
○ Set IHRC / 16	= 1Ch (IHRC / 16)	Calibrated	IHRC calibrated to 16MHz, CLK=1MHz (IHRC/16)
○ Set IHRC / 32	= 7Ch (IHRC / 32)	Calibrated	IHRC calibrated to 16MHz, CLK=0.5MHz (IHRC/32)
○ Set ILRC	= E4h (ILRC / 1)	Calibrated	IHRC calibrated to 16MHz, CLK=ILRC
○ Disable	No change	No Change	IHRC not calibrated, CLK not changed

Table 3: Options for IHRC Frequency Calibration

Usually, .ADJUST_IC will be the first command after boot up, in order to set the target operating frequency whenever starting the system. The program code for IHRC frequency calibration is executed only one time that occurs in writing the codes into OTP memory; after then, it will not be executed again. If the different option for IHRC calibration is chosen, the system status is also different after boot. The following shows the status of PMS132/PMS132B for different option:

(1) .ADJUST_IC SYSCLK=IHRC/2, IHRC=16MHz, V_{DD}=5V

After boot up, CLKMD = 0x34:

- ◆ IHRC frequency is calibrated to 16MHz@V_{DD}=5V and IHRC module is enabled
- ◆ System CLK = IHRC/2 = 8MHz
- ◆ Watchdog timer is disabled, ILRC is enabled, PA5 is in input mode

(2) .ADJUST_IC SYSCLK=IHRC/4, IHRC=16MHz, V_{DD}=3.3V

After boot up, CLKMD = 0x14:

- ◆ IHRC frequency is calibrated to 16MHz@V_{DD}=3.3V and IHRC module is enabled
- ◆ System CLK = IHRC/4 = 4MHz
- ◆ Watchdog timer is disabled, ILRC is enabled, PA5 is in input mode

(3) .ADJUST_IC SYSCLK=IHRC/8, IHRC=16MHz, V_{DD}=2.5V

After boot up, CLKMD = 0x3C:

- ◆ IHRC frequency is calibrated to 16MHz@V_{DD}=2.5V and IHRC module is enabled
- ◆ System CLK = IHRC/8 = 2MHz
- ◆ Watchdog timer is disabled, ILRC is enabled, PA5 is in input mode

(4) .ADJUST_IC SYSCLK=IHRC/16, IHRC=16MHz, V_{DD}=2.5V

After boot up, CLKMD = 0x1C:

- ◆ IHRC frequency is calibrated to 16MHz@V_{DD}=2.5V and IHRC module is enabled
- ◆ System CLK = IHRC/16 = 1MHz
- ◆ Watchdog timer is disabled, ILRC is enabled, PA5 is in input mode

(5) .ADJUST_IC SYSCLK=IHRC/32, IHRC=16MHz, V_{DD}=5V

After boot up, CLKMD = 0x7C:

- ◆ IHRC frequency is calibrated to 16MHz@V_{DD}=5V and IHRC module is enabled
- ◆ System CLK = IHRC/32 = 500KHz
- ◆ Watchdog timer is disabled, ILRC is enabled, PA5 is in input mode

(6) .ADJUST_IC SYSCLK=ILRC, IHRC=16MHz, $V_{DD}=5V$

After boot up, CLKMD = 0XE4:

- ◆ IHRC frequency is calibrated to 16MHz@ $V_{DD}=5V$ and IHRC module is disabled
- ◆ System CLK = ILRC
- ◆ Watchdog timer is enabled, ILRC is enabled, PA5 is input mode

(7) .ADJUST_IC DISABLE

After boot up, CLKMD is not changed (Do nothing):

- ◆ IHRC is not calibrated and IHRC module is to be enabled or disabled by Boot-up Time.
- ◆ System CLK = ILRC or IHRC/64 (by Boot-up_Time)
- ◆ Watchdog timer is enabled, ILRC is enabled, PA5 is in input mode.

5.4.4. External Crystal Oscillator

If crystal oscillator is used, a crystal or resonator is required between X1 and X2. Fig.2 shows the hardware connection under this application; the range of operating frequency of crystal oscillator can be from 32 KHz to 4MHz, depending on the crystal placed on; higher frequency oscillator than 4MHz is NOT supported.

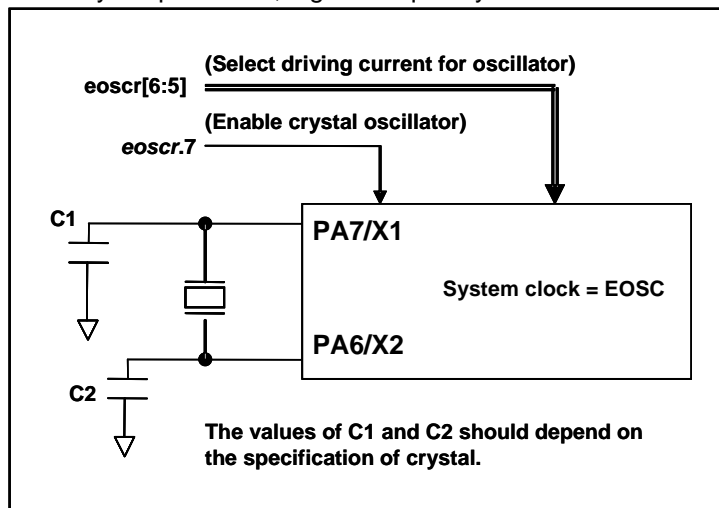


Fig.2: Connection of crystal oscillator

Besides crystal, external capacitor and options of PMS132/PMS132B should be fine tuned in *eoscr* (0x0a) register to have good sinusoidal waveform. The *eoscr.7* is used to enable crystal oscillator module, *eoscr.6* and *eoscr.5* are used to set the different driving current to meet the requirement of different frequency of crystal oscillator:

- ◆ *eoscr*.[6:5]=01 : Low driving capability, for lower frequency, ex: 32KHz crystal oscillator
- ◆ *eoscr*.[6:5]=10 : Middle driving capability, for middle frequency, ex: 1MHz crystal oscillator
- ◆ *eoscr*.[6:5]=11 : High driving capability, for higher frequency, ex: 4MHz crystal oscillator

Table 4 shows the recommended values of C1 and C2 for different crystal oscillator; the measured start-up time under its corresponding conditions is also shown. Since the crystal or resonator had its own characteristic, the capacitors and start-up time may be slightly different for different type of crystal or resonator, please refer to its specification for proper values of C1 and C2.

Frequency	C1	C2	Measured Start-up time	Conditions
4MHz	4.7pF	4.7pF	6ms	(<i>eoscr</i> [6:5]=11, <i>misc</i> .6=0)
1MHz	10pF	10pF	11ms	(<i>eoscr</i> [6:5]=10, <i>misc</i> .6=0)
32KHz	22pF	22pF	450ms	(<i>eoscr</i> [6:5]=01, <i>misc</i> .6=0)

Table 4: Recommend values of C1 and C2 for crystal and resonator oscillators

When using the crystal oscillator, user must pay attention to the stable time of oscillator after enabling it, the stable time of oscillator will depend on frequency, crystal type, external capacitor and supply voltage. Before switching the system to the crystal oscillator, user must make sure the oscillator is stable; the reference program is shown as below:

```

void   FPPA0 (void)
{
    . ADJUST_IC  SYSCLK=IHRC/16, IHRC=16MHz, VDD=5V
    $   EOSCR    Enable, 4MHz;      // EOSCR = 0b110_00000;
    $ T16M      EOSC, /1, BIT13;    // while T16.Bit13 0 => 1, Intrq.T16 => 1
                                           // suppose crystal EOSC is stable

    WORD      count = 0;
    stt16     count;
    Intrq.T16  = 0;
    while (! Intrq.T16) NULL;          // count from 0x0000 to 0x2000, then trigger INTRQ.T16

    clkmd= 0xb4;                      // switch system clock to EOSC;

    clkmd.4 = 0;                      // disable IHRC
    ...
}

```

Please notice that the crystal oscillator should be fully turned off before entering the power-down mode, in order to avoid unexpected wakeup event.

5.4.5. System Clock and LVR level

The clock source of system clock comes from EOSC, IHRC and ILRC, the hardware diagram of system clock in the PMS132/PMS132B is shown as Fig.3.

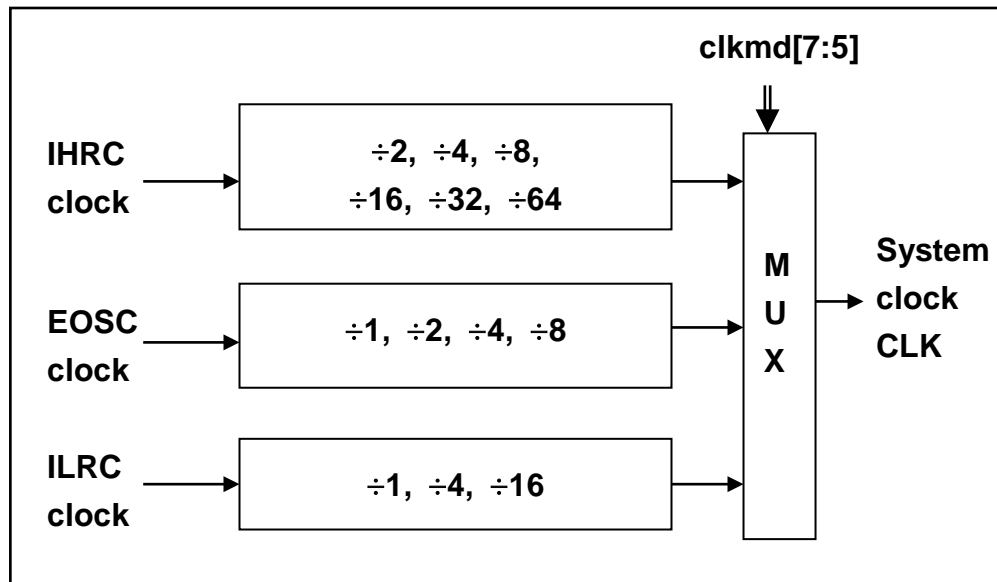


Fig.3: Options of System Clock

User can choose different operating system clock depends on its requirement; the selected operating system clock should be combined with supply voltage and LVR level to make system stable. The LVR level will be selected during compilation, and the lowest LVR levels can be chosen for different operating frequencies. Please refer to Section 4.1.

5.4.6. System Clock Switching

After IHRC calibration, user may want to switch system clock to a new frequency or may switch system clock at any time to optimize the system performance and power consumption. Basically, the system clock of PMS132/PMS132B can be switched among IHRC, ILRC and EOSC by setting the **clkmd** register at any time; system clock will be the new one after writing to **clkmd** register immediately. Please notice that the original clock module can NOT be turned off at the same time as writing command to **clkmd** register. The examples are shown as below and more information about clock switching, please refer to the “Help” -> “Application Note” -> “IC Introduction” -> “Register Introduction” -> CLKMD”.

Case 1: Switching system clock from ILRC to IHRC/2

```

...                                     // system clock is ILRC
CLKMD.4      =      1;                // turn on IHRC first to improve anti-interference ability
CLKMD        =      0x34 ;            // switch to IHRC/2, ILRC CAN NOT be disabled here
// CLKMD.2    =      0 ;              // if need, ILRC CAN be disabled at this time
...

```

Case 2: Switching system clock from ILRC to EOSC

```

...                                     // system clock is ILRC
CLKMD        =      0xA6 ;            // switch to IHRC, ILRC CAN NOT be disabled here
CLKMD.2      =      0 ;              // ILRC CAN be disabled at this time
...

```

Case 3: Switching system clock from IHRC/2 to ILRC

```

...                                     // system clock is IHRC/2
CLKMD        =      0xF4 ;            // switch to ILRC, IHRC CAN NOT be disabled here
CLKMD.4      =      0 ;              // IHRC CAN be disabled at this time
...

```

Case 4: Switching system clock from IHRC/2 to EOSC

```

...                                     // system clock is IHRC/2
CLKMD        =      0xB0 ;            // switch to EOSC, IHRC CAN NOT be disabled here
CLKMD.4      =      0 ;              // IHRC CAN be disabled at this time
...

```

Case 5: Switching system clock from IHRC/2 to IHRC/4

```

...                                     // system clock is IHRC/2, ILRC is enabled here
CLKMD        =      0X14 ;            // switch to IHRC/4
...

```

Case 6: System may hang if it is to switch clock and turn off original oscillator at the same time

```

...                                     // system clock is ILRC
CLKMD        =      0x30 ;            // CAN NOT switch clock from ILRC to IHRC/2 and
                                         turn off ILRC oscillator at the same time

```


5.5. Comparator

One hardware comparator is built inside the PMS132/PMS132B; Fig.4 shows its hardware diagram. It can compare signals between two pins or with either internal reference voltage $V_{\text{internal R}}$ or internal band-gap reference voltage. The two signals to be compared, one is the plus input and the other one is the minus input. For the minus input of comparator can be PA3, PA4, Internal band-gap 1.20 volt, PB6, PB7 or $V_{\text{internal R}}$ selected by bit [3:1] of gpcc register, and the plus input of comparator can be PA4 or $V_{\text{internal R}}$ selected by bit 0 of gpcc register.

The comparator result can be selected through gpcs.7 to forcibly output to PA0 whatever input or output state. It can be a direct output or sampled by Timer2 clock (TM2_CLK) which comes from Timer2 module. The output polarity can be also inverted by setting gpcc.4 register, the comparator output can be used to request interrupt service or read through gpcc.6.

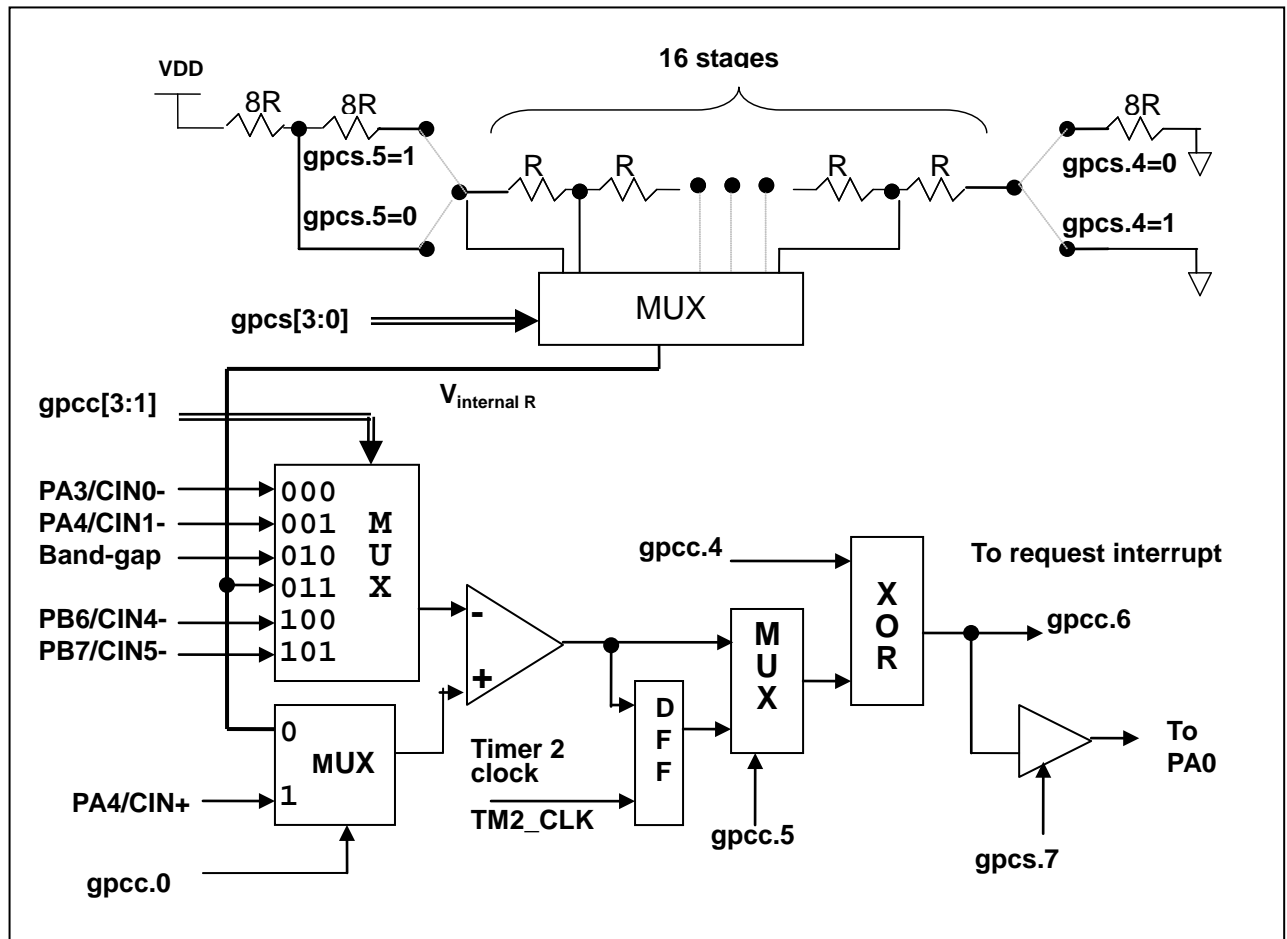


Fig.4: Hardware diagram of comparator

5.5.1 Internal reference voltage ($V_{\text{internal R}}$)

The internal reference voltage $V_{\text{internal R}}$ is built by series resistance to provide different level of reference voltage, bit 4 and bit 5 of **gpcs** register are used to select the maximum and minimum values of $V_{\text{internal R}}$ and bit [3:0] of **gpcs** register are used to select one of the voltage level which is divided-by-16 from the defined maximum level to minimum level. Fig.5 to Fig.8 shows four conditions to have different reference voltage $V_{\text{internal R}}$. By setting the **gpcs** register, the internal reference voltage $V_{\text{internal R}}$ can be ranged from $(1/32)*V_{\text{DD}}$ to $(3/4)*V_{\text{DD}}$.

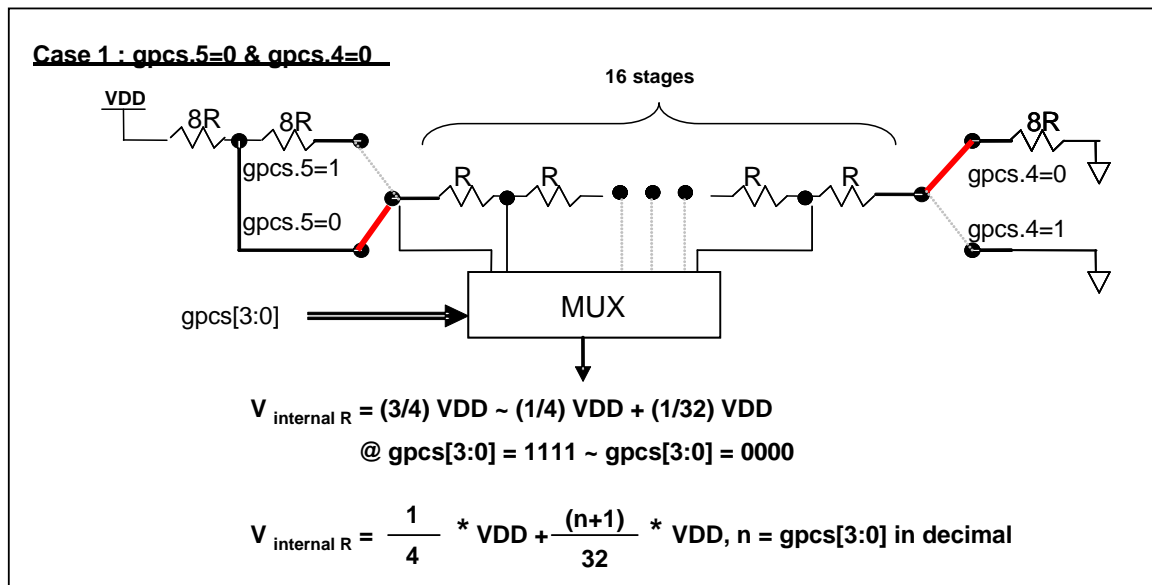


Fig.5: $V_{\text{internal R}}$ hardware connection if gpcs.5=0 and gpcs.4=0

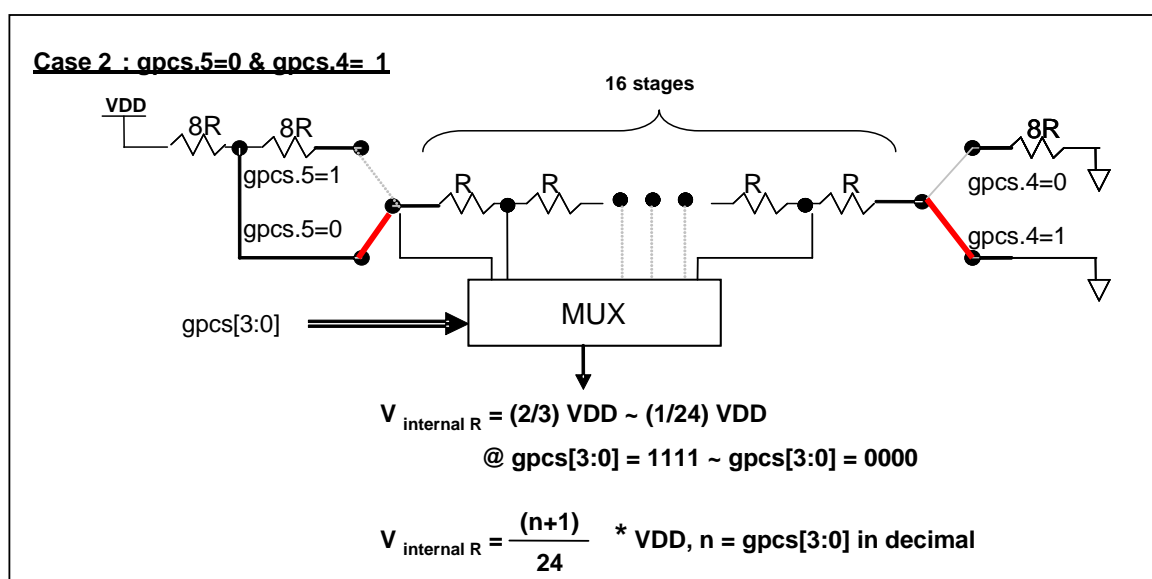


Fig.6: $V_{\text{internal R}}$ hardware connection if gpcs.5=0 and gpcs.4=1

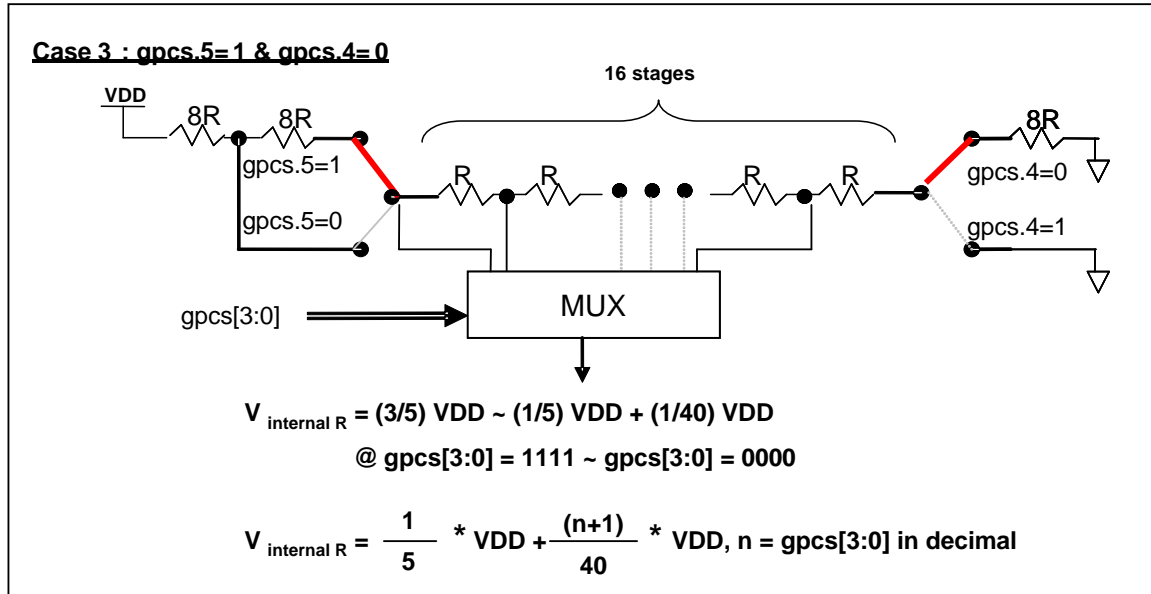


Fig.7: $V_{\text{internal R}}$ hardware connection if gpcs.5=1 and gpcs.4=0

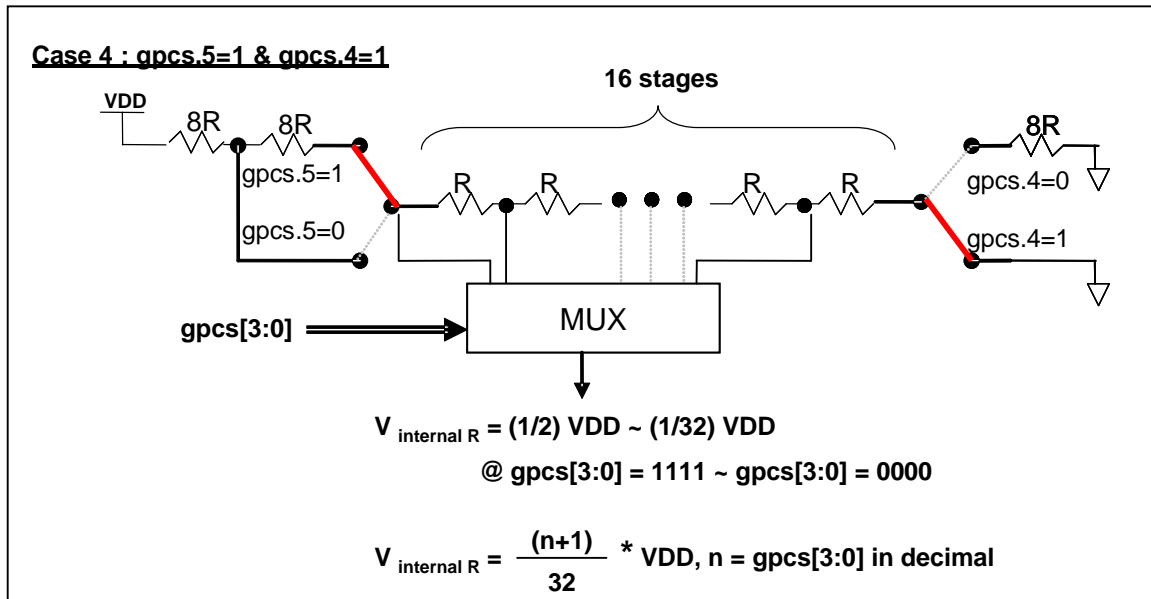


Fig.8: $V_{\text{internal R}}$ hardware connection if gpcs.5=1 and gpcs.4=1

5.5.2 Using the comparator

Case 1:

Choosing PA3 as minus input and $V_{\text{internal R}}$ with $(18/32)*V_{\text{DD}}$ voltage level as plus input. $V_{\text{internal R}}$ is configured as the above Figure “gpcs[5:4] = 2b’00” and gpcs [3:0] = 4b’1001 (n=9) to have $V_{\text{internal R}} = (1/4)*V_{\text{DD}} + [(9+1)/32]*V_{\text{DD}} = [(9+9)/32]*V_{\text{DD}} = (18/32)*V_{\text{DD}}$.

```
gpcs   = 0b0_0_00_1001;           //  $V_{\text{internal R}} = V_{\text{DD}}*(18/32)$ 
gpcc   = 0b1_0_0_0_000_0;         // enable comp, - input: PA3, + input:  $V_{\text{internal R}}$ 
padier = 0bxxxx_0_xxx;           // disable PA3 digital input to prevent leakage current
```

or

```
$ GPCS     $V_{\text{DD}}*18/32;$ 
$ GPCC    Enable, N_PA3, P_R;      // - input: N_xx, + input:  $P\_R(V_{\text{internal R}})$ 
PADIER = 0bxxxx_0_xxx;
```

Case 2:

Choosing $V_{\text{internal R}}$ as minus input with $(22/40)*V_{\text{DD}}$ voltage level and PA4 as plus input, the comparator result will be inversed and then output to PA0. $V_{\text{internal R}}$ is configured as the above Figure “gpcs[5:4] = 2b’10” and gpcs [3:0] = 4b’1101 (n=13) to have $V_{\text{internal R}} = (1/5)*V_{\text{DD}} + [(13+1)/40]*V_{\text{DD}} = [(13+9)/40]*V_{\text{DD}} = (22/40)*V_{\text{DD}}$.

```
gpcs   = 0b1_0_10_1101;           // output to PA0,  $V_{\text{internal R}} = V_{\text{DD}}*(22/40)$ 
gpcc   = 0b1_0_0_1_011_1;         // Inverse output, - input:  $V_{\text{internal R}}$ , + input: PA4
padier = 0bxxx_0_xxxx;           // disable PA4 digital input to prevent leakage current
```

or

```
$ GPCS    Output,  $V_{\text{DD}}*22/40;$ 
$ GPCC    Enable, Inverse, N_R, P_PA4; // - input:  $N\_R(V_{\text{internal R}})$ , + input:  $P\_xx$ 
PADIER = 0bxxx_0_xxxx;
```

Note: When selecting output to PA0 output, GPCS will affect the PA3 output function in ICE. Though the IC is fine, be careful to avoid this error during emulation.

5.5.3 Using the comparator and band-gap 1.20V

The internal band-gap module can provide 1.20 volt, it can measure the external supply voltage level. The band-gap 1.20 volt is selected as minus input of comparator and $V_{\text{internal R}}$ is selected as plus input, the supply voltage of $V_{\text{internal R}}$ is V_{DD} , the V_{DD} voltage level can be detected by adjusting the voltage level of $V_{\text{internal R}}$ to compare with band-gap. If N (gpcs[3:0] in decimal) is the number to let $V_{\text{internal R}}$ closest to band-gap 1.20 volt, the supply voltage V_{DD} can be calculated by using the following equations:

For using Case 1: $V_{\text{DD}} = [32 / (N+9)] * 1.20 \text{ volt} ;$

For using Case 2: $V_{\text{DD}} = [24 / (N+1)] * 1.20 \text{ volt} ;$

For using Case 3: $V_{\text{DD}} = [40 / (N+9)] * 1.20 \text{ volt} ;$

For using Case 4: $V_{\text{DD}} = [32 / (N+1)] * 1.20 \text{ volt} ;$

Case 1:

```

$ GPCS  $V_{\text{DD}} * 12 / 40$ ;           //    $4.0V * 12 / 40 = 1.2V$ 
$ GPCC Enable, BANDGAP, P_R;    //   - input: BANDGAP, + input:  $P\_R(V_{\text{internal R}})$ 
....
if (GPC_Out)                     //   or GPCC.6
{                                //   when  $V_{\text{DD}} > 4V$ 
}
else
{                                //   when  $V_{\text{DD}} < 4V$ 
}

```

5.6 16-bit Timer (Timer16)

A 16-bit hardware timer (Timer16) is implemented in the PMS132/PMS132B, the clock sources of Timer16 may come from system clock (CLK), clock of external crystal oscillator (EOSC), internal high RC oscillator (IHRC), internal low RC oscillator (ILRC), PA4 and PA0, a multiplex is used to select clock output for the clock source. Before sending clock to the counter16, a pre-scaling logic with divided-by-1, 4, 16, and 64 is used for wide range counting. The 16-bit counter performs up-counting operation only, the counter initial values can be stored from memory by *stt16* instruction and the counting values can be loaded to memory by *ldt16* instruction. A selector is used to select the interrupt condition of Timer16, whenever overflow occurs, the Timer16 interrupt can be triggered. The hardware diagram of Timer16 is shown as Fig.9. The interrupt source of Timer16 comes from one of bit 8 to 15 of 16-bit counter, and the interrupt type can be rising edge trigger or falling edge trigger which is specified in the bit 5 of *intregs* register (IO address 0x0C).

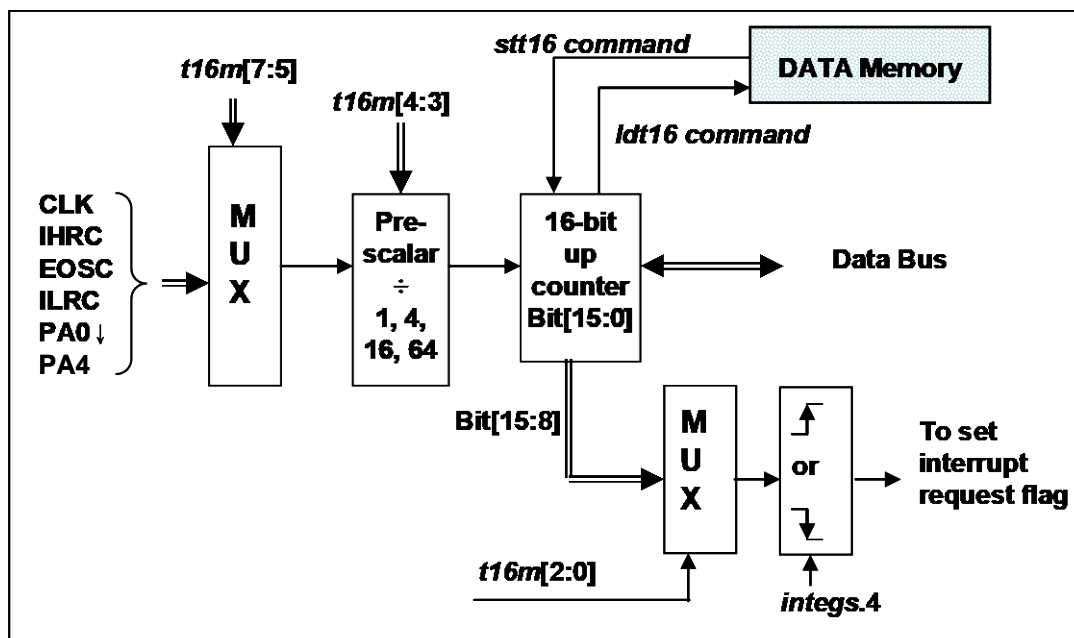


Fig.9: Hardware diagram of Timer16

When using the Timer16, the syntax for Timer16 has been defined in the .INC file. There are three parameters to define the Timer16; 1st parameter is used to define the clock source of Timer16, 2nd parameter is used to define the pre-scalar and the last one is to define the interrupt source. The detail description is shown as below:

```

T16M      IO_RW      0x06
$ 7~5: STOP, SYSCLK, X, PA4_F, IHRC, EOSC, ILRC, PA0_F // 1st par.
$ 4~3: /1, /4, /16, /64 // 2nd par.
$ 2~0: BIT8, BIT9, BIT10, BIT11, BIT12, BIT13, BIT14, BIT15 // 3d par.

```

User can define the parameters of T16M based on system requirement, some examples are shown below and more examples please refer to “Help → Application Note → IC Introduction → Register Introduction → T16M” in IDE utility.

\$ T16M SYCLK, /64, BIT15;

// choose (SYCLK/64) as clock source, every 2¹⁶ clock to set INTRQ.2=1
// if using System Clock = IHRC / 2 = 8 MHz
// SYCLK/64 = 8 MHz/64 = 125KHz, about every 512 mS to generate INTRQ.2=1

\$ T16M EOSC, /1, BIT13;

// choose (EOSC/1) as clock source, every 2¹⁴ clocks to generate INTRQ.2=1
// if EOSC=32768 Hz, 32768 Hz/(2¹⁴) = 2Hz, every 0.5S to generate INTRQ.2=1

\$ T16M PA0_F, /1, BIT8;

// choose PA0 as clock source, every 2⁹ to generate INTRQ.2=1
// receiving every 512 times PA0 to generate INTRQ.2=1

\$ T16M STOP;

// stop Timer16 counting

If Timer16 is operated at free running, the frequency of interrupt can be described as below:

$$F_{\text{INTRQ_T16M}} = F_{\text{clock source}} \div P \div 2^{n+1}$$

Where, F is the frequency of selected clock source to Timer16;

P is the selection of t16m [4:3]; (1, 4, 16, 64)

N is the nth bit selected to request interrupt service, for example: n=10 if bit 10 is selected.

5.7 8-bit Timer (Timer2/Timer3) with PWM generation

Two 8-bit hardware timers (Timer2 and Timer3) with PWM generation are implemented in the PMS132/PMS132B. The following descriptions thereafter are for Timer2 only. It is because Timer3 have same structure with Timer2. Please refer to Fig.10 shown the hardware diagram of Timer2, the clock sources of Timer2 may come from system clock, internal high RC oscillator (IHRC), internal low RC oscillator (ILRC), external crystal oscillator (EOSC), PA0, PB0, PA4 and comparator. Bit [7:4] of register tm2c are used to select the clock of Timer2. If IHRC is selected for Timer2 clock source, the clock sent to Timer2 will keep running when using ICE in halt state. According to the setting of register tm2c[3:2], Timer2 output can be selectively output to PB2, PA3 or PB4(Timer3 count output can be selected as PB5, PB6 or PB7). At this point, regardless of whether PX.x is the input or output state, Timer2(or Timer3) signal will be forced to output. A clock pre-scaling module is provided with divided-by- 1, 4, 16, and 64 options, controlled by bit [6:5] of tm2s register; one scaling module with divided-by-1~31 is also provided and controlled by bit [4:0] of tm2s register. In conjunction of pre-scaling function and scaling function, the frequency of Timer2 clock (TM2_CLK) can be wide range and flexible.

The Timer2 counter performs 8-bit up-counting operation only; the counter values can be set or read back by tm2ct register. The 8-bit counter will be clear to zero automatically when its values reach for upper bound register, the upper bound register is used to define the period of timer or duty of PWM. There are two operating modes for Timer2: period mode and PWM mode; period mode is used to generate periodical output waveform or interrupt event; PWM mode is used to generate PWM output waveform with optional 6-bit to 8-bit PWM resolution, Fig.11 shows the timing diagram of Timer2 for both period mode and PWM mode.

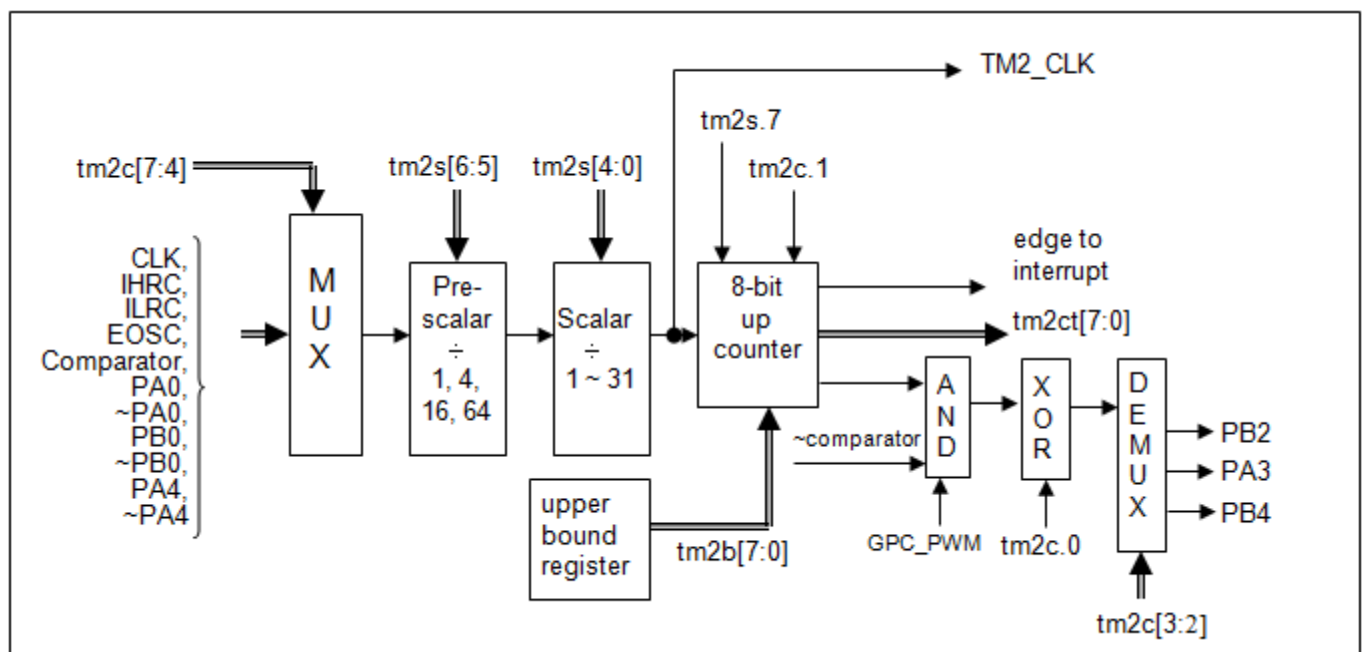


Fig.10: Timer2 hardware diagram

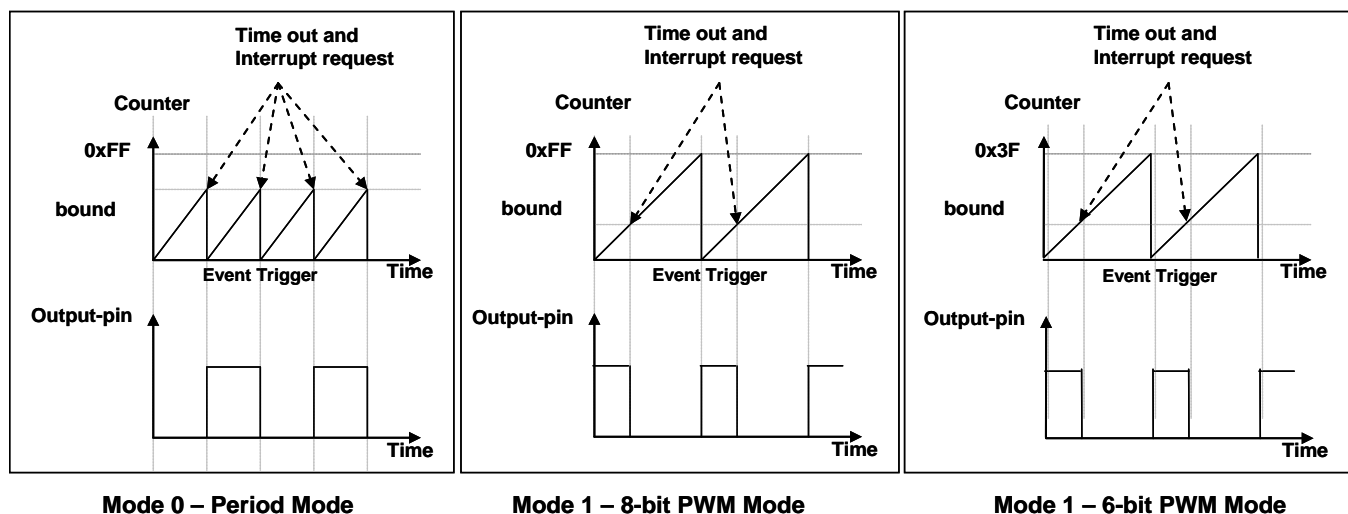


Fig.11: Timing diagram of Timer2 in period mode and PWM mode (tm2c.1=1)

A Code Option GPC_PWM is for the applications which need the generated PWM waveform to be controlled by the comparator result. If the Code Option GPC_PWM is selected, the PWM output stops while the comparator output is 1 and then the PWM output turns on while the comparator output goes back to 0, as shown in Fig. 12.

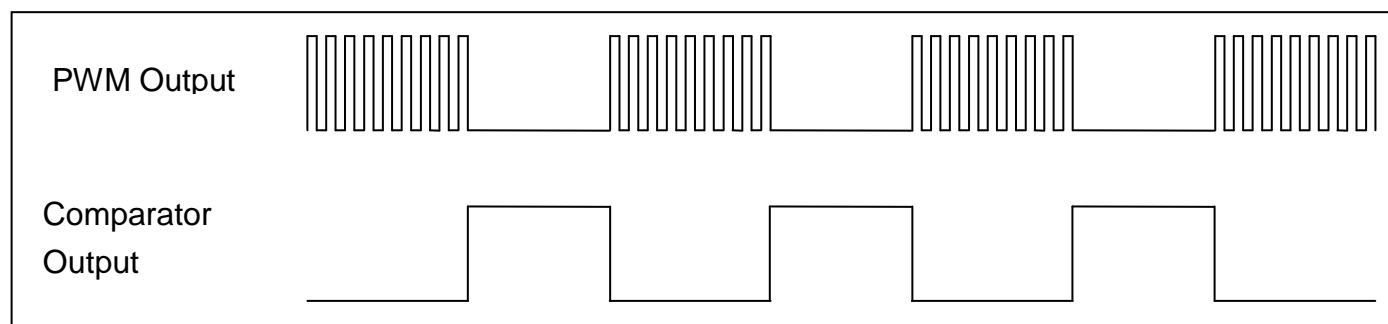


Fig.12 : Comparator controls the output of PWM waveform

5.7.1 Using the Timer2 to generate periodical waveform

If periodical mode is selected, the duty cycle of output is always 50%; its frequency can be summarized as below:

$$\text{Frequency of Output} = Y \div [2 \times (K+1) \times S1 \times (S2+1)]$$

Where, $Y = \text{tm2c}[7:4]$: frequency of selected clock source

$K = \text{tm2b}[7:0]$: bound register in decimal

$S1 = \text{tm2s}[6:5]$: pre-scalar ($S1 = 1, 4, 16, 64$)

$S2 = \text{tm2s}[4:0]$: scalar register in decimal ($S2 = 0 \sim 31$)

Example 1:

```
tm2c = 0b0001_1000, Y=8MHz
tm2b = 0b0111_1111, K=127
tm2s = 0b0000_00000, S1=1, S2=0
➔ frequency of output = 8MHz ÷ [ 2 × (127 + 1) × 1 × (0 + 1) ] = 31.25KHz
```

Example 2:

```
tm2c = 0b0001_1000, Y=8MHz
tm2b = 0b0111_1111, K=127
tm2s[7:0] = 0b0111_1111, S1=64, S2 = 31
➔ frequency = 8MHz ÷ ( 2 × (127 + 1) × 64 × (31 + 1) ) = 15.25Hz
```

Example 3:

```
tm2c = 0b0001_1000, Y=8MHz
tm2b = 0b0000_1111, K=15
tm2s = 0b0000_00000, S1=1, S2=0
➔ frequency = 8MHz ÷ ( 2 × (15 + 1) × 1 × (0 + 1) ) = 250KHz
```

Example 4:

```
tm2c = 0b0001_1000, Y=8MHz
tm2b = 0b0000_0001, K=1
tm2s = 0b0000_00000, S1=1, S2=0
➔ frequency = 8MHz ÷ ( 2 × (1 + 1) × 1 × (0 + 1) ) = 2MHz
```

The sample program for using the Timer2 to generate periodical waveform from PA3 is shown as below:

```
Void FPPA0 (void)
{
    . ADJUST_IC    SYSCLK=IHRC/2, IHRC=16MHz, VDD=5V
    ...
    tm2ct = 0x00;
    tm2b = 0x7f;
    tm2s = 0b0_00_00001;           // 8-bit PWM, pre-scalar = 1, scalar = 2
    tm2c = 0b0001_10_0_0;         // system clock, output=PA3, period mode
    while(1)
    {
        nop;
    }
}
```

5.7.2 Using the Timer2 to generate 8-bit PWM waveform

If 8-bit PWM mode is selected, it should set **tm2c[1]=1** and **tm2s[7]=0**, the frequency and duty cycle of output waveform can be summarized as below:

$$\text{Frequency of Output} = Y \div [256 \times S1 \times (S2+1)]$$

$$\text{Duty of Output} = [(K+1) \div 256] \times 100\%$$

Where, Y = tm2c[7:4] : frequency of selected clock source

K = tm2b[7:0] : bound register in decimal

S1= tm2s[6:5] : pre-scalar (S1= 1, 4, 16, 64)

S2 = tm2s[4:0] : scalar register in decimal (S2= 0 ~ 31)

Example 1:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b0111_1111, K=127

tm2s = 0b0000_00000, S1=1, S2=0

→ frequency of output = $8\text{MHz} \div (256 \times 1 \times (0+1)) = 31.25\text{KHz}$

→ duty of output = $[(127+1) \div 256] \times 100\% = 50\%$

Example 2:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b0111_1111, K=127

tm2s = 0b0111_11111, S1=64, S2=31

→ frequency of output = $8\text{MHz} \div (256 \times 64 \times (31+1)) = 15.25\text{Hz}$

→ duty of output = $[(127+1) \div 256] \times 100\% = 50\%$

Example 3:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b1111_1111, K=255

tm2s = 0b0000_00000, S1=1, S2=0

→ PWM output keep high

→ duty of output = $[(255+1) \div 256] \times 100\% = 100\%$

Example 4:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b0000_1001, K = 9

tm2s = 0b0000_00000, S1=1, S2=0

→ frequency of output = $8\text{MHz} \div (256 \times 1 \times (0+1)) = 31.25\text{KHz}$

→ duty of output = $[(9+1) \div 256] \times 100\% = 3.9\%$

The sample program for using the Timer2 to generate PWM waveform from PA3 is shown as below:

```
void  FPPA0 (void)
{
    .ADJUST_IC    SYSCLK=IHRC/2, IHRC=16MHz, VDD=5V
    wdreset;
    tm2ct = 0x00;
    tm2b = 0x7f;
    tm2s = 0b0_00_00001;           //      8-bit PWM, pre-scalar = 1, scalar = 2
    tm2c = 0b0001_10_1_0;         //      system clock, output=PA3, PWM mode
    while(1)
    {
        nop;
    }
}
```

5.7.3 Using the Timer2 to generate 6-bit PWM waveform

If 6-bit PWM mode is selected, it should set **tm2c[1]=1** and **tm2s[7]=1**, the frequency and duty cycle of output waveform can be summarized as below:

Frequency of Output = $Y \div [64 \times S1 \times (S2+1)]$

Duty of Output = $[(K+1) \div 64] \times 100\%$

Where, tm2c[7:4] = Y : frequency of selected clock source

tm2b[7:0] = K : bound register in decimal

tm2s[6:5] = S1 : pre-scalar (S1= 1, 4, 16, 64)

tm2s[4:0] = S2 : scalar register in decimal (S2= 0 ~ 31)

Example 1:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b0001_1111, K=31

tm2s = 0b1000_00000, S1=1, S2=0

➔ frequency of output = $8\text{MHz} \div (64 \times 1 \times (0+1)) = 125\text{KHz}$

➔ duty = $[(31+1) \div 64] \times 100\% = 50\%$

Example 2:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b0001_1111, K=31

tm2s = 0b1111_11111, S1=64, S2=31

➔ frequency of output = $8\text{MHz} \div (64 \times 64 \times (31+1)) = 61.03 \text{ Hz}$

➔ duty of output = $[(31+1) \div 64] \times 100\% = 50\%$

Example 3:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b0011_1111, K=63

tm2s = 0b1000_00000, S1=1, S2=0

→ PWM output keep high

→ duty of output = $[(63+1) \div 64] \times 100\% = 100\%$

Example 4:

tm2c = 0b0001_1010, Y=8MHz

tm2b = 0b0000_0000, K=0

tm2s = 0b1000_00000, S1=1, S2=0

→ frequency = $8\text{MHz} \div (64 \times 1 \times (0+1)) = 125\text{KHz}$

→ duty = $[(0+1) \div 64] \times 100\% = 1.5\%$

5.8 11-bit PWM Generator

Three 11-bit hardware PWM generators (PWMG0, PWMG1 & PWMG2) are implemented in the PMS132/PMS132B. The following descriptions thereafter are for PWMG0 only. It is because PWMG1 & PWMG2 have the same structures and functions with PWMG0.

Their individual outputs are listed as below:

- PWMG0 – PA0, PB4, PB5
- PWMG1 – PA4, PB6, PB7
- PWMG2 – PA3, PA5, PB2, PB3 (Note: PA5 open drain output only, user need to enable the internal pull-high resistor or add an external pull-high resistor when using, and ICE does not support PA5 PWM function.)

5.8.1 PWM Waveform

A PWM output waveform (Fig.13) has a time-base ($T_{\text{Period}} = \text{Time of Period}$) and a time with output high level (Duty Cycle). The frequency of the PWM output is the inverse of the period ($f_{\text{PWM}} = 1/T_{\text{Period}}$), the resolution of the PWM is the clock count numbers for one period ($N \text{ bits resolution}, 2^N \times T_{\text{clock}} = T_{\text{Period}}$).

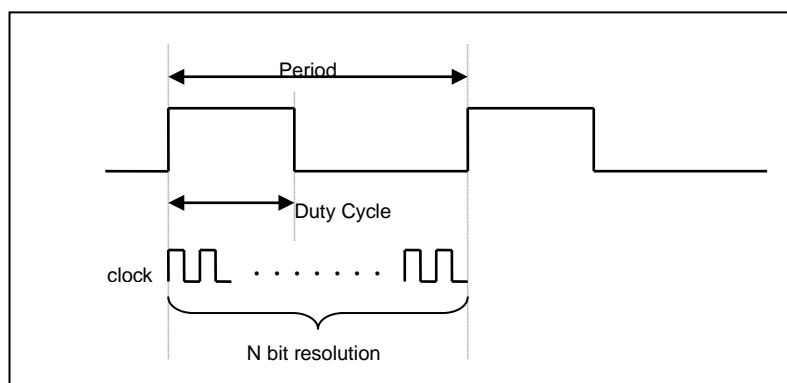


Fig.13: PWM Output Waveform

5.8.2 Hardware and Timing Diagram

Three 11-bit hardware PWM generators are built inside the PMS132/PMS132B; Fig.14 shows the hardware diagram PWMG0 as an example. The clock source can be IHRC or system clock. Depending on the setting of register PWMC, PWM can be optionally output to PA0, PB4 or PB5. At this point, PWM signal will be forced to output regardless of whether PX.x is the input or output state. The period of PWM waveform is defined in the PWM upper bond high and low registers, the duty cycle of PWM waveform is defined in the PWM duty high and low registers. Users can also use the comparator result to control the output of the PWM waveform by using the GPC_PWM code option.

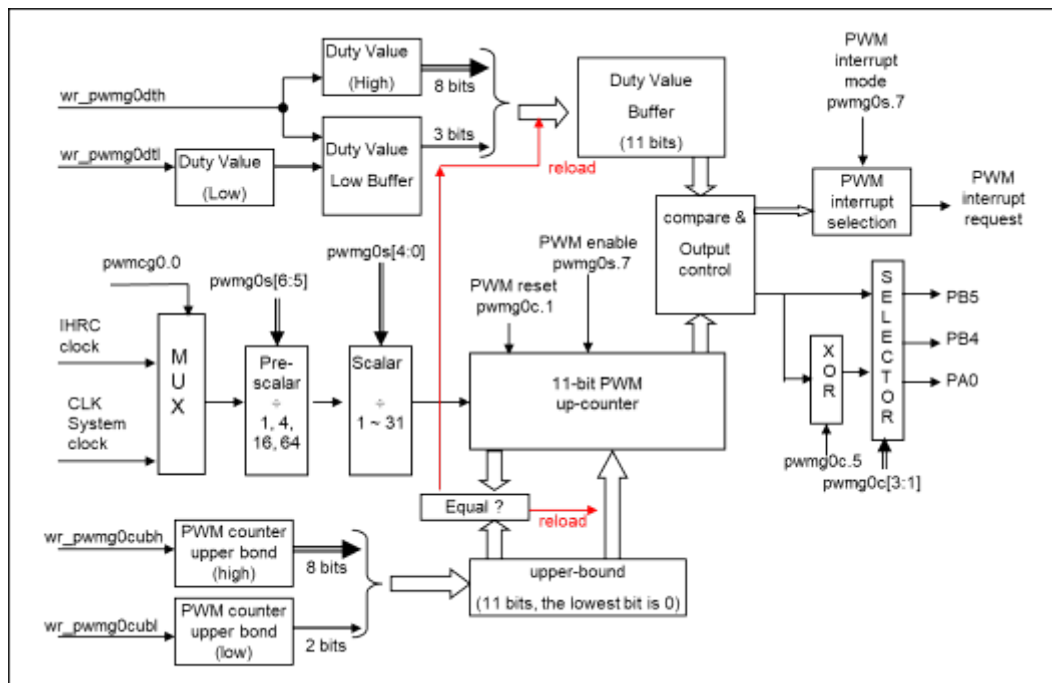


Fig.14: Hardware Diagram of 11-bit PWM Generator

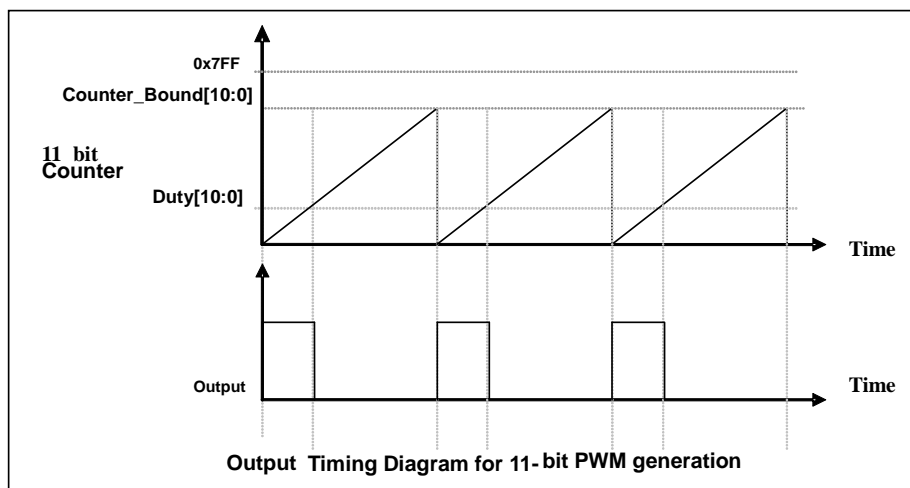


Fig.15: Output Timing Diagram of 11-bit PWM Generator

5.8.3 Equations for 11-bit PWM Generator

$$\text{PWM Frequency } F_{\text{PWM}} = F_{\text{clock source}} \div [P \times (K + 1) \times (CB10_1 + 1)]$$

$$\text{PWM Duty(in time)} = (1 / F_{\text{PWM}}) \times (DB10_1 + DB0 \times 0.5 + 0.5) \div (CB10_1 + 1)$$

$$\text{PWM Duty(in percentage)} = (DB10_1 + DB0 \times 0.5 + 0.5) \div (CB10_1 + 1) \times 100\%$$

Where, $P = \text{PWMGxS}[6:5]$: pre-scalar ($P = 1, 4, 16, 64$)

$K = \text{PWMGxS}[4:0]$: scalar in decimal ($K = 0 \sim 31$)

$DB10_1 = \text{Duty_Bound}[10:1] = \{\text{PWMGxDTH}[7:0], \text{PWMGxDTL}[7:6]\}$, duty bound

$DB0 = \text{Duty_Bound}[0] = \text{PWMGxDTL}[5]$

$CB10_1 = \text{Counter_Bound}[10:1] = \{\text{PWMGxCUBH}[7:0], \text{PWMGxCUBL}[7:6]\}$, counter bound

5.8.4 Complementary PWM with Dead Zones

Users can use two 11bit PWM generators to output two complementary PWM waveforms with dead zones. Take PWMG0 output PWM0, PWMG1 output PWM1 as an example, the program reference is as follows.

In addition, Timer2 and Timer3 can also output 8-bit PWM waveforms with complementary dead zones of two bands. The principle is similar to this, and it will not be described in detail.

```
#definedead_zone_R    2           //    Control dead-time before rising edge of PWM1
#definedead_zone_F    3           //    Control dead-time after falling edge of PWM1

void  FPPA0 (void)
{
    .ADJUST_IC        SYSCLK=IHRC/16, IHRC=16MHz, VDD=5V;
    //.....
    Byte duty          =    60;           //    Represents the duty cycle of PWM0
    Byte _duty =       100 - duty; //    Represents the duty cycle of PWM1

    //***** Set the counter upper bound and duty cycle *****
    PWMG0DTL           =    0x00;
    PWMG0DTH           =    _duty;
    PWMG0CUBL           =    0x00;
    PWMG0CUBH           =    100;

    PWMG1DTL           =    0x00;
    PWMG1DTH           =    _duty - dead_zone_F;
    //    Use duty cycle to adjust the dead-time after the falling edge of PWM1
    PWMG1CUBL           =    0x00;
    PWMG1CUBH           =    100; // The above values are assigned before enable PWM output

    //***** PWM out control *****
}
```

```

$ PWMG0C Enable,Inverse,PA0,SYSCCLK;           //PWMG0 output the PWM0 waveform to PA0
$ PWMG0S INTR_AT_DUTY,/1,/1;

.delay      dead_zone_R;      // Use delay to adjust the dead-time before the rising edge of PWM1

$ PWMG1C Enable, PA4, SYSCCLK;  //PWMG1 output the PWM1 waveform to PA4
$ PWMG1S INTR_AT_DUTY,/1,/1;

//***** Note: for the output control part of the program, the code sequence can not be moved *****//

While(1)
    {nop; }
}

```

The PWM0 / PWM1 waveform obtained by the above program is shown in Fig. 16.

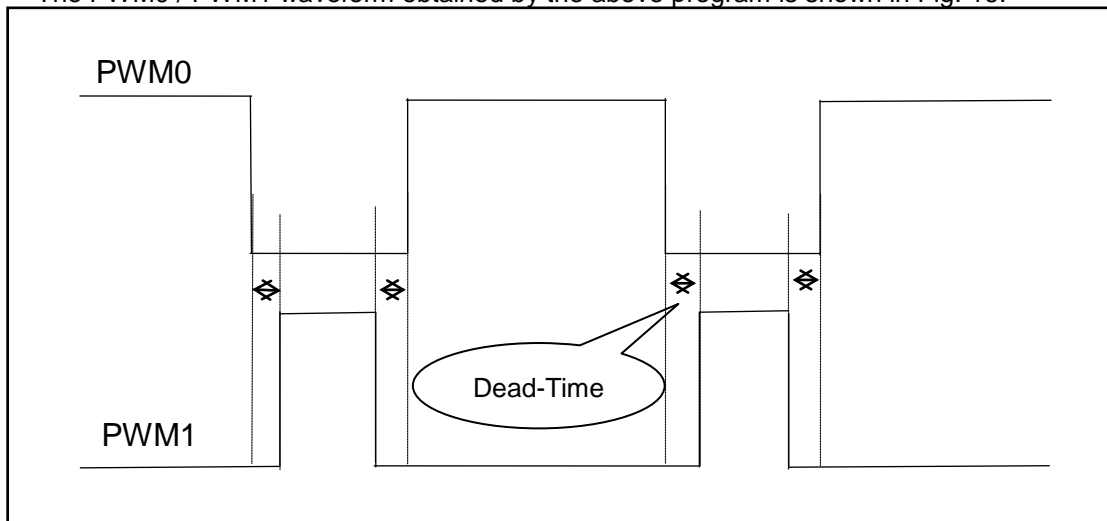


Fig. 16: Two complementary PWM waveforms with dead zones

Users can modify the **dead_zone_R** and **dead_zone_F** values in the program to adjust the dead-time. Table 5 provides data corresponding to different dead-time for users' reference. Where, if dead-time = 4us, then there are dead zones of 4us before and after PWM1 high level.

dead-time (us)	dead_zone_R	dead_zone_F
4 (minimum)	0	2
6	2	3
8	4	4
10	6	5
12	8	6
14	10	7

Table 5: The value of dead-time for reference

Dead_zone_R and **dead_zone_F** need to work together to get an ideal dead-time. If user wants to adjust other dead-time, please note that **dead_zone_R** and **dead_zone_F** need to meet the following criteria:

dead_zone_R	dead_zone_F
1 / 2 / 3	> 1
4 / 5 / 6 / 7	> 2
8 / 9	> 3
...	...

5.9 WatchDog Timer

The watchdog timer (WDT) is a counter with clock coming from ILRC. WDT can be cleared by power-on-reset or by command **wdreset** at any time. There are four different timeout periods of watchdog timer to be chosen by setting the **misc** register, it is:

- ◆ 8k ILRC clocks period if register misc[1:0]=00 (default)
- ◆ 16k ILRC clocks period if register misc[1:0]=01
- ◆ 64k ILRC clocks period if register misc[1:0]=10
- ◆ 256k ILRC clocks period if register misc[1:0]=11

The frequency of ILRC may drift a lot due to the variation of manufacture, supply voltage and temperature; user should reserve guard band for save operation. Besides, the watchdog period will also be shorter than expected after Reset or Wakeup events. It is suggested to clear WDT by **wdreset** command after these events to ensure enough clock periods before WDT timeout.

When WDT is timeout, PMS132/PMS132B will be reset to restart the program execution. The relative timing diagram of watchdog timer is shown as Fig.17.

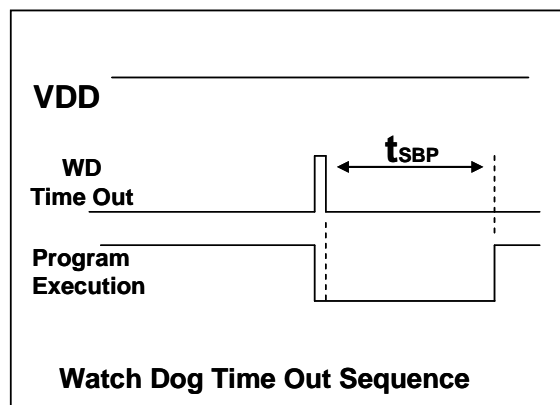


Fig.17: Sequence of Watch Dog Time Out

5.10 Interrupt

There are eight interrupt lines for PMS132/PMS132B:

- ◆ External interrupt PA0/PB5
- ◆ External interrupt PB0/PA4
- ◆ ADC interrupt
- ◆ Timer16 interrupt
- ◆ GPC interrupt
- ◆ PWMG0 interrupt
- ◆ Timer2 interrupt
- ◆ Timer3 interrupt

Every interrupt request line has its own corresponding interrupt control bit to enable or disable it; the hardware diagram of interrupt function is shown as Fig.18. All the interrupt request flags are set by hardware and cleared by writing **intrq** register. When the request flags are set, it can be rising edge, falling edge or both, depending on the setting of register **integs**. All the interrupt request lines are also controlled by **engint** instruction (enable global interrupt) to enable interrupt operation and **disgint** instruction (disable global interrupt) to disable it.

The stack memory for interrupt is shared with data memory and its address is specified by stack register **sp**. Since the program counter is 16 bits width, the bit 0 of stack register **sp** should be kept 0. Moreover, user can use **pushaf** / **popaf** instructions to store or restore the values of **ACC** and **flag** register **to** / **from** stack memory. Since the stack memory is shared with data memory, the stack position and level are arranged by the compiler in Mini-C project. When defining the stack level in ASM project, users should arrange their locations carefully to prevent address conflicts.

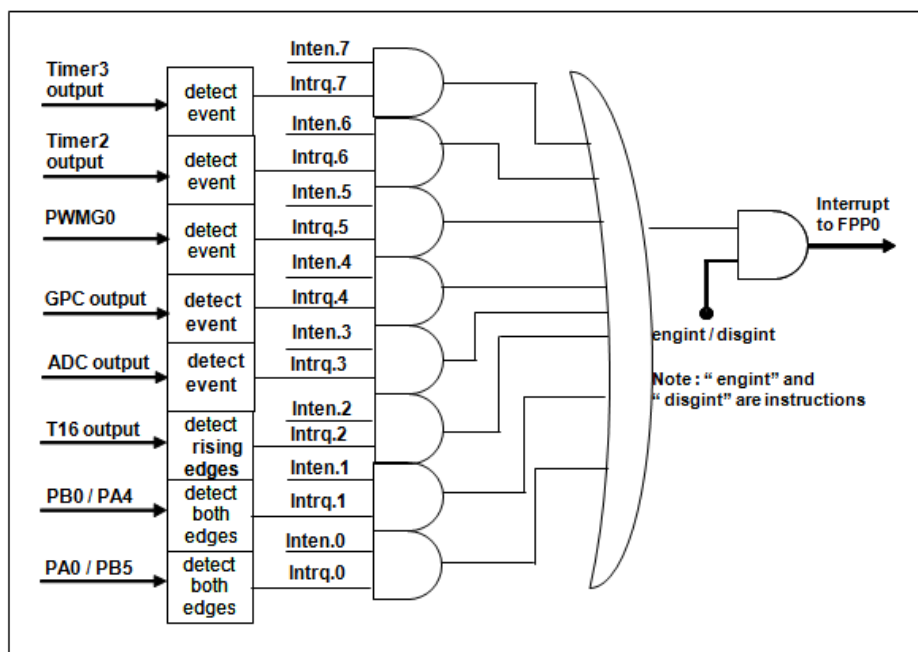


Fig.18: Hardware diagram of interrupt controller

Once the interrupt occurs, its operation will be:

- ◆ The program counter will be stored automatically to the stack memory specified by register **sp**.
- ◆ New **sp** will be updated to **sp+2**.
- ◆ Global interrupt will be disabled automatically.
- ◆ The next instruction will be fetched from address 0x010.

During the interrupt service routine, the interrupt source can be determined by reading the **intrq** register.

Note: Even if INTEN=0, INTRQ will be still triggered by the interrupt source.

After finishing the interrupt service routine and issuing the **reti** instruction to return back, its operation will be:

- ◆ The program counter will be restored automatically from the stack memory specified by register **sp**.
- ◆ New **sp** will be updated to **sp-2**.
- ◆ Global interrupt will be enabled automatically.
- ◆ The next instruction will be the original one before interrupt.

User must reserve enough stack memory for interrupt, two bytes stack memory for one level interrupt and four bytes for two levels interrupt. For interrupt operation, the following sample program shows how to handle the interrupt, noticing that it needs four bytes stack memory to handle interrupt and **pushaf**.

```

void      FPPA0      (void)
{
    ...
    $ INTEN PA0;      // INTEN =1; interrupt request when PA0 level changed
    INTRQ = 0;          // clear INTRQ
    ENGINT              // global interrupt enable
    ...
    DISGINT            // global interrupt disable
    ...
}

```

```

void    Interrupt (void)    // interrupt service routine
{
    PUSHAF                // store ALU and FLAG register

    // If INTEN.PA0 will be opened and closed dynamically,
    // user can judge whether INTEN.PA0 =1 or not.
    // Example:  If (INTEN.PA0 && INTRQ.PA0) {...}

    // If INTEN.PA0 is always enable,
    // user can omit the INTEN.PA0 judgement to speed up interrupt service routine.

    If (INTRQ.PA0)
    {
        // Here for PA0 interrupt service routine
        INTRQ.PA0 = 0;    // Delete corresponding bit (take PA0 for example)
        ...
    }
    ...
    // X : INTRQ = 0;    // It is not recommended to use INTRQ = 0 to clear all at the end of the
                        // interrupt service routine.
                        // It may accidentally clear out the interrupts that have just occurred
                        // and are not yet processed.

    POPAF                // restore ALU and FLAG register
}

```

5.11 Power-Save and Power-Down

There are three operational modes defined by hardware: ON mode, Power-Save mode and Power-Down modes. ON mode is the state of normal operation with all functions ON, Power-Save mode (“**stopexe**”) is the state to reduce operating current and CPU keeps ready to continue, Power-Down mode (“**stopsys**”) is used to save power deeply. Therefore, Power-Save mode is used in the system which needs low operating power with wake-up occasionally and Power-Down mode is used in the system which needs power down deeply with seldom wake-up. Table 6 shows the differences in oscillator modules between Power-Save mode (“**stopexe**”) and Power-Down mode (“**stopsys**”).

Differences in oscillator modules between STOPSYS and STOPEXE			
	IHRC	ILRC	EOSC
STOPSYS	Stop	Stop	Stop
STOPEXE	No Change	No Change	No Change

Table 6: Differences in oscillator modules between STOPSYS and STOPEXE

5.11.1 Power-Save mode (“**stopexe**”)

Using “**stopexe**” instruction to enter the Power-Save mode, only system clock is disabled, remaining all the oscillator modules active. For CPU, it stops executing; however, for Timer16, counter keep counting if its clock source is not the system clock. The wake-up sources for “**stopexe**” can be IO-toggle or Timer16 counts to set values when the clock source of Timer16 is IHRC or ILRC modules, or wakeup by comparator when setting *GPCC.7*=1 and *GPCS.6*=1 to enable the comparator wakeup function at the same time. Wake-up from input pins can be considered as a continuation of normal execution, the detail information for Power-Save mode shows below:

- IHRC and EOSC oscillator modules: No change, keep active if it was enabled
- ILRC oscillator modules: must remain enabled, need to start with ILRC when be wakening up
- System clock: Disable, therefore, CPU stops execution
- OTP memory is turned off
- Timer counter: Stop counting if system clock is selected or the corresponding oscillator module is disabled; otherwise, it keeps counting. (The Timer contains TM16, TM2, TM3, PWMG0, PWMG1, and PWMG2.)
- Wake-up sources:
 - a. IO toggle wake-up: IO toggling in digital input mode (*PxC* bit is 1 and *PxDIER* bit is 1).
 - b. Timer wake-up: If the clock source of Timer is not the SYSCLK, the system will be awakened when the Timer counter reaches the set value.
 - c. Comparator wake-up: It need setting *GPCC.7*=1 and *GPCS.6*=1 to enable the comparator wake-up function at the same time.

An example shows how to use Timer16 to wake-up from “**stopexe**”:

```

$ T16M      ILRC, /1, BIT8           // Timer16 setting
...
WORD        count =      0;
STT16        count;
stopexe;
...

```

The initial counting value of Timer16 is zero and the system will be woken up after the Timer16 counts 256 ILRC clocks.

5.11.2 Power-Down mode (“stopsys”)

Power-Down mode is the state of deeply power-saving with turning off all the oscillator modules. By using the “stopsys” instruction, this chip will be put on Power-Down mode directly. It is recommend to set GPCC.7=0 to disable the comparator before the command “stopsys”. The following shows the internal status of PMS132/PMS132B detail when “**stopsys**” command is issued:

- All the oscillator modules are turned off
- OTP memory is turned off
- The contents of SRAM and registers remain unchanged
- Wake-up sources: IO toggle in digital mode (PxDIER bit is 1).

Wake-up from input pins can be considered as a continuation of normal execution. To minimize power consumption, all the I/O pins should be carefully manipulated before entering power-down mode. The reference sample program for power down is shown as below:

```

CLKMD    =    0xF4;        //    Change clock from IHRC to ILRC
CLKMD.4  =    0;          //    disable IHRC
...
while (1)
{
    STOPSYS;                //    enter power-down
    if (...) break;         //    if wakeup happen and check OK, then return to high speed
                                //    else stay in power-down mode again
}
CLKMD=    0x34;          //    Change clock from ILRC to IHRC/2

```

5.11.3 Wake-up

After entering the Power-Down or Power-Save modes, the PMS132/PMS132B can be resumed to normal operation by toggling IO pins, Timer16 interrupt is available for Power-Save mode ONLY. Table 7 shows the differences in wake-up sources between STOPSYS and STOPEXE.

Differences in wake-up sources between STOPSYS and STOPEXE		
	IO Toggle	Timer Interrupt
STOPSYS	Yes	No
STOPEXE	Yes	Yes

Table 7: Differences in wake-up sources between Power-Save mode and Power-Down mode

When using the IO pins to wake-up the PMS132/PMS132B, registers **pxdier** should be properly set to enable the wake-up function for every corresponding pin. The time for normal wake-up is about 3000 ILRC

clocks counting from wake-up event; fast wake-up can be selected to reduce the wake-up time by *misc* register, and the time for fast wake-up is about 45 ILRC clocks from IO toggling.

Suspend mode	Wake-up mode	Wake-up time (t_{WUP}) from IO toggle
STOPEXE suspend or STOPSYS suspend	Fast wake-up	$45 * T_{ILRC}$, Where T_{ILRC} is the time period of ILRC
STOPEXE suspend or STOPSYS suspend	Normal wake-up	$3000 * T_{ILRC}$, Where T_{ILRC} is the clock period of ILRC

Please notice that when Fast boot-up is selected, no matter which wake-up mode is selected in *misc.5*, the wake-up mode will be forced to be FAST. If Normal boot-up is selected, the wake-up mode is determined by *misc.5*.

5.12 IO Pins

All the pins can be independently set into two states output or input by configuring the data registers (*pa*, *pb*), control registers (*pac*, *pbc*) and pull-high registers (*paph*, *pbph*). All these pins have Schmitt-trigger input buffer and output driver with CMOS level. When it is set to output low, the pull-high resistor is turned off automatically. If user wants to read the pin state, please notice that it should be set to input mode before reading the data port; if user reads the data port when it is set to output mode, the reading data comes from data register, NOT from IO pad. As an example, Table 8 shows the configuration table of bit 0 of port A. The hardware diagram of IO buffer is also shown as Fig.19.

<i>pa.0</i>	<i>pac.0</i>	<i>paph.0</i>	Description
X	0	0	Input without pull-high resistor
X	0	1	Input with pull- high resistor
0	1	X	Output low without pull- high resistor
1	1	0	Output high without pull- high resistor
1	1	1	Output high with pull- high resistor

Table 8: PA0 Configuration Table

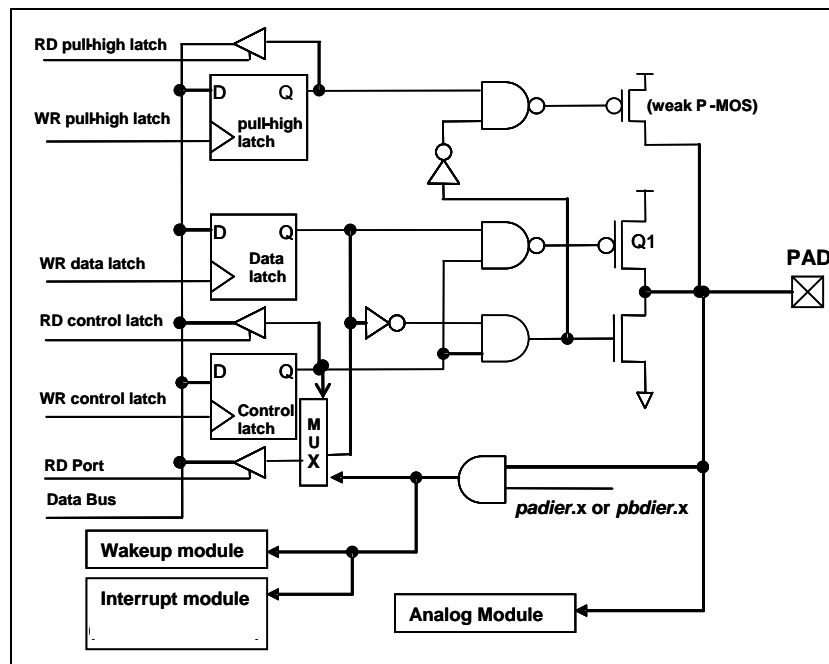


Fig.19: Hardware diagram of IO buffer

Other than PA5, all the IO pins have the same structure; PA5 can be open-drain ONLY when setting to output mode (without Q1). The corresponding bits in registers ***padier*** / ***pbdier*** should be set to low to prevent leakage current for those pins are selected to be analog function. When PMS132/PMS132B is put in power-down or power-save mode, every pin can be used to wake-up system by toggling its state. Therefore, those pins needed to wake-up system must be set to input mode and set the corresponding bits of registers ***padier*** and ***pbdier*** to high. The same reason, ***padier.0*** should be set high when PA0 is used as external interrupt pin, ***pbdier.0*** for PB0, ***padier.4*** for PA4 and ***pbdier.5*** for PB5.

5.13 Reset and LVR

5.13.1 Reset

There are many causes to reset the PMS132/PMS132B, once reset is asserted, most of all the registers in PMS132/PMS132B will be set to default values, system should be restarted once abnormal cases happen, or by jumping program counter to address 0x0. The data memory is in uncertain state when reset comes from power-up and LVR; however, the content will be kept when reset comes from PRSTB pin or WDT timeout.

5.13.2 LVR reset

By code option, there are many different levels of LVR for reset; usually, user selects LVR reset level to be in conjunction with operating frequency and supply voltage.

5.14 Analog-to-Digital Conversion (ADC) module

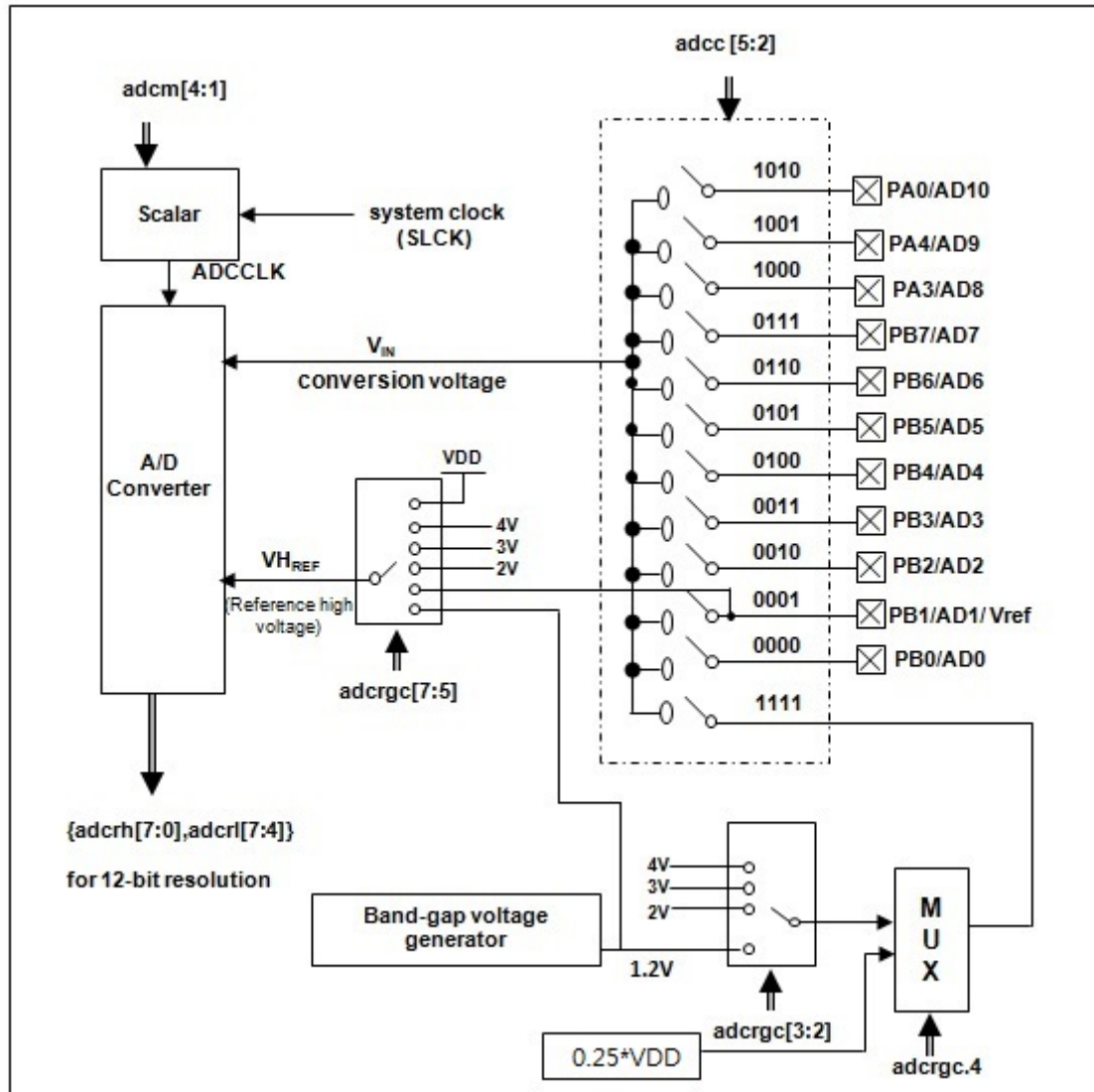


Fig.20: ADC Block Diagram

There are seven registers when using the ADC module, which are:

- ◆ ADC Control Register (**adcc**)
- ◆ ADC Regulator Control Register (**adcr gc**)
- ◆ ADC Mode Register (**adcm**)
- ◆ ADC Result High/Low Register (**adcrh**, **adcr l**)
- ◆ Port A/B Digital Input Enable Register (**padier**, **pbdier**)

The following steps are required to do the AD conversion procedure:

- (1) Configure the voltage reference high by **adcr gc** register
- (2) Configure the AD conversion clock by **adcm** register

- If user power down the ADC and enable the ADC again, be sure to go to step 6 to confirm the ADC becomes ready before the conversion.

For the AD conversion to meet its specified accuracy, the charge holding capacitor (C_{HOLD}) must be allowed to fully charge to the voltage reference high level and discharge to the voltage reference low level. The analog input model is shown as Fig.21, the signal driving source impedance (R_s) and the internal sampling switch impedance (R_{ss}) will affect the required time to charge the capacitor C_{HOLD} directly. The internal sampling switch impedance may vary with ADC supply voltage; the signal driving source impedance will affect accuracy of analog input signal. User must ensure the measured signal is stable before sampling; therefore, the maximum signal driving source impedance is highly dependent on the frequency of signal to be measured. The recommended maximum impedance for analog driving source is about 10K Ω under 500KHz input frequency.



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5.14.2 Select the reference high voltage

The ADC reference high voltage can be selected via bit[7:5] of register **adcrhc** and its option can be V_{DD} , 4V, 3V, 2V, band-gap (1.20V) reference voltage or PB1 from external pin.

5.14.3 ADC clock selection

The clock of ADC module (ADCLK) can be selected by **adcm** register; there are 8 possible options for ADCLK from $CLK \div 1$ to $CLK \div 128$ (CLK is the system clock). Due to the signal acquisition time T_{ACQ} is one clock period of ADCLK, the ADCLK must meet that requirement. The recommended ADC clock is to operate at 2us.

5.14.4 Configure the analog pins

There are 12 analog signals can be selected for AD conversion, 11 analog input signals come from external pins and one is from internal band-gap reference voltage or $0.25 \cdot V_{DD}$. There are 4 voltage levels selectable for the internal band-gap reference, they are 1.2V, 2V, 3V and 4V. For external pins, the analog signals are shared with Port A[0], Port A[3], Port A[4], and Port B[7:0]. To avoid leakage current at the digital circuit, those pins defined for analog input should disable the digital input function (set the corresponding bit of **padier** or **pbdier** register to be 0).

The measurement signals of ADC belong to small signal; it should avoid the measured signal to be interfered during the measurement period, the selected pin should (1) be set to input mode (2) turn off weak pull-high resistor (3) set the corresponding pin to analog input by port A/B digital input disable register (**padier** / **pbdier**).

5.14.5 Using the ADC

The following example shows how to use ADC with PB0~PB3.

First, defining the selected pins:

```
PBC      =    0B_XXXX_0000;      //    PB0 ~ PB3 as Input
PBPH    =    0B_XXXX_0000;      //    PB0 ~ PB3 without pull-high
PBDIER   =    0B_XXXX_0000;      //    PB0 ~ PB3 digital input is disabled
```

Next, setting **ADCC** register, example as below:

```
$ ADCC Enable, PB3;      //    set PB3 as ADC input
$ ADCC Enable, PB2;      //    set PB2 as ADC input
$ ADCC Enable, PB0;      //    set PB0 as ADC input
```

Next, setting **ADCM** and **ADCRGC** register, example as below:

```
$ ADCM 12BIT, /16;      //    recommend /16 @System Clock=8MHz
$ ADCM 12BIT, /8;       //    recommend /8 @System Clock=4MHz
$ ADCRGC VDD;
```

Next, delay 400us, example as below:

```
.Delay 8*400;           // System Clock=8MHz
.Delay 4*400;          // System Clock=4MHz
```

Then, start the ADC conversion:

```
AD_START= 1;           // start ADC conversion
while (!AD_DONE) NULL; // wait ADC conversion result
```

Finally, it can read ADC result when AD_DONE is high:

```
WORD = Data;           // two bytes result: ADCRH and ADCRL
Data$1 = ADCRH;
Data$0 = ADCRL;
Data = Data >> 4;
```

The ADC can be disabled by using the following method:

```
$ ADCC Disable;
```

or

```
ADCC = 0;
```

5.15 Multiplier

There is an 8x8 multiplier on-chip to enhance hardware capability in arithmetic function, its multiplication is an 8 x 8 unsigned operation and can be finished in one clock cycle. Before issuing the *mul* command, both multiplicand and multiplier must be put on ACC and register *mulop* (0x08); After *mul* command, the high byte result will be put on register *mulrh* (0x09) and low byte result on ACC. The hardware diagram of this multiplier is shown as Fig.22.

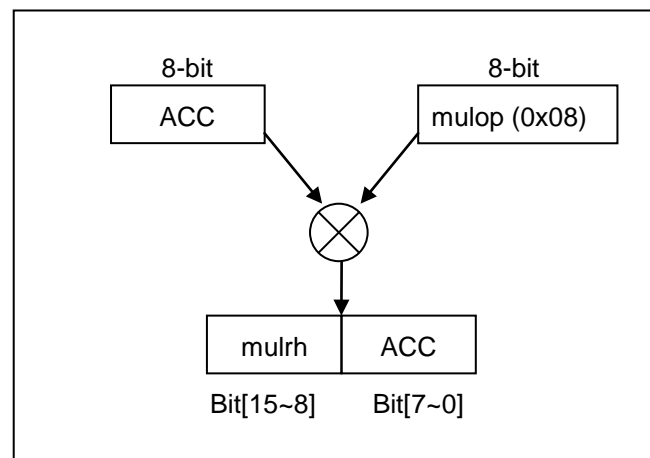


Fig.22: Block diagram of hardware multiplier

6. IO Registers

6.1. ACC Status Flag Register (*flag*), IO address = 0x00

Bit	Reset	R/W	Description
7 - 4	-	-	Reserved. Please do not use.
3	0	R/W	OV (Overflow Flag). This bit is set to be 1 whenever the sign operation is overflow.
2	0	R/W	AC (Auxiliary Carry Flag). There are two conditions to set this bit, the first one is carry out of low nibble in addition operation and the other one is borrow from the high nibble into low nibble in subtraction operation.
1	0	R/W	C (Carry Flag). There are two conditions to set this bit, the first one is carry out in addition operation, and the other one is borrow in subtraction operation. Carry is also affected by shift with carry instruction.
0	0	R/W	Z (Zero Flag). This bit will be set when the result of arithmetic or logic operation is zero; Otherwise, it is cleared.

6.2. Stack Pointer Register (*sp*), IO address = 0x02

Bit	Reset	R/W	Description
7 - 0	-	R/W	Stack Pointer Register. Read out the current stack pointer, or write to change the stack pointer. Please notice that bit 0 should be kept 0 due to program counter is 16 bits.

6.3. Clock Mode Register (*clkmd*), IO address = 0x03

Bit	Reset	R/W	Description
7 - 5	111	R/W	System clock (CLK) selection:
			<div style="display: flex; justify-content: space-between;"> <div>Type 0, clkmd[3]=0</div> <div>Type 1, clkmd[3]=1</div> </div>
			<div style="display: flex; justify-content: space-between;"> <div> 000: IHRC÷4 001: IHRC÷2 010: reserved 011: EOSC÷4 100: EOSC÷2 101: EOSC 110: ILRC÷4 111: ILRC (default) </div> <div> 000: IHRC÷16 001: IHRC÷8 010: ILRC÷16 (ICE does NOT Support.) 011: IHRC÷32 100: IHRC÷64 101: EOSC÷8 11x: reserved. </div> </div>
4	1	R/W	Internal High RC Enable. 0 / 1: disable / enable
3	0	R/W	Clock Type Select. This bit is used to select the clock type in bit [7:5]. 0 / 1: Type 0 / Type 1
2	1	R/W	Internal Low RC Enable. 0 / 1: disable / enable If ILRC is disabled, watchdog timer is also disabled.
1	1	R/W	Watch Dog Enable. 0 / 1: disable / enable
0	0	R/W	Pin PA5/PRSTB function. 0 / 1: PA5 / PRSTB

6.4. Interrupt Enable Register (*inten*), IO address = 0x04

Bit	Reset	R/W	Description
7	0	R/W	Enable interrupt from Timer3. 0 / 1: disable / enable.
6	0	R/W	Enable interrupt from Timer2. 0 / 1: disable / enable.
5	0	R/W	Enable interrupt from PWMG0. 0 / 1: disable / enable.
4	0	R/W	Enable interrupt from comparator. 0 / 1: disable / enable.
3	0	R/W	Enable interrupt from ADC. 0 / 1: disable / enable.
2	0	R/W	Enable interrupt from Timer16 overflow. 0 / 1: disable / enable.
1	0	R/W	Enable interrupt from PB0/PA4. 0 / 1: disable / enable.
0	0	R/W	Enable interrupt from PA0/PB5. 0 / 1: disable / enable.

6.5. Interrupt Request Register (*intrq*), IO address = 0x05

Bit	Reset	R/W	Description
7	-	R/W	Interrupt Request from Timer3, this bit is set by hardware and cleared by software. 0 / 1: No request / Request
6	-	R/W	Interrupt Request from Timer2, this bit is set by hardware and cleared by software. 0 / 1: No request / Request
5	-	R/W	Interrupt Request from PWMG0, this bit is set by hardware and cleared by software. 0 / 1: No request / Request
4	-	R/W	Interrupt Request from comparator, this bit is set by hardware and cleared by software. 0 / 1: No request / Request
3	-	R/W	Interrupt Request from ADC, this bit is set by hardware and cleared by software. 0 / 1: No request / Request
2	-	R/W	Interrupt Request from Timer16, this bit is set by hardware and cleared by software. 0 / 1: No request / Request
1	-	R/W	Interrupt Request from pin PB0/PA4, this bit is set by hardware and cleared by software. 0 / 1: No request / Request
0	-	R/W	Interrupt Request from pin PA0/PB5, this bit is set by hardware and cleared by software. 0 / 1: No Request / request

6.6. Multiplier Operand Register (*mulop*), IO address = 0x08

Bit	Reset	R/W	Description
7 - 0	-	R/W	Operand for hardware multiplication operation.

6.7. Multiplier Result High Byte Register (*mulrh*), IO address = 0x09

Bit	Reset	R/W	Description
7 - 0	-	RO	High byte result of multiplication operation (read only).

6.8. Timer16 mode Register (*t16m*), IO address = 0x06

Bit	Reset	R/W	Description
7 - 5	000	R/W	Timer16 Clock source selection. 000: disable 001: CLK (system clock) 010: reserved 011: PA4 falling edge (from external pin) 100: IHRC 101: EOSC 110: ILRC 111: PA0 falling edge (from external pin)
4 - 3	00	R/W	Timer16 clock pre-divider. 00: ÷1 01: ÷4 10: ÷16 11: ÷64
2 - 0	000	R/W	Interrupt source selection. Interrupt event happens when the selected bit status is changed. 0 : bit 8 of Timer16 1 : bit 9 of Timer16 2 : bit 10 of Timer16 3 : bit 11 of Timer16 4 : bit 12 of Timer16 5 : bit 13 of Timer16 6 : bit 14 of Timer16 7 : bit 15 of Timer16

6.9. External Oscillator setting Register (*eoscr*), IO address = 0x0a

Bit	Reset	R/W	Description
7	0	WO	Enable external crystal oscillator. 0 / 1 : Disable / Enable
6 - 5	00	WO	External crystal oscillator selection. 00 : reserved 01 : Low driving capability, for lower frequency, ex: 32KHz crystal oscillator 10 : Middle driving capability, for middle frequency, ex: 1MHz crystal oscillator 11 : High driving capability, for higher frequency, ex: 4MHz crystal oscillator
4 - 1	-	-	Reserved. Please keep 0 for future compatibility.
0	0	WO	Power-down the Band-gap and LVR hardware modules. 0 / 1: normal / power-down.

6.10. Interrupt Edge Select Register (*integs*), IO address = 0x0c

Bit	Reset	R/W	Description
7 - 5	-	-	Reserved.
4	0	WO	Timer16 edge selection. 0 : rising edge of the selected bit to trigger interrupt 1 : falling edge of the selected bit to trigger interrupt
3 - 2	00	WO	PB0/PA4 edge selection. 00 : both rising edge and falling edge of the selected bit to trigger interrupt 01 : rising edge of the selected bit to trigger interrupt 10 : falling edge of the selected bit to trigger interrupt 11 : reserved.
1 - 0	00	WO	PA0/PB5 edge selection. 00 : both rising edge and falling edge of the selected bit to trigger interrupt 01 : rising edge of the selected bit to trigger interrupt 10 : falling edge of the selected bit to trigger interrupt 11 reserved.

6.11. Port A Digital Input Enable Register (*padier*), IO address = 0x0d

Bit	Reset	R/W	Description
7	1	WO	Enable PA7 digital input and wake-up event. 1 / 0 : enable / disable. This bit should be set to low to prevent leakage current when external crystal oscillator is used. If this bit is set to low, PA7 can NOT be used to wake-up the system.
6	1	WO	Enable PA6 digital input and wake-up event. 1 / 0 : enable / disable. This bit should be set to low to prevent leakage current when external crystal oscillator is used. If this bit is set to low, PA6 can NOT be used to wake-up the system.
5	1	WO	Enable PA5 digital input and wake-up event. 1 / 0 : enable / disable. This bit can be set to low to disable wake-up from PA5 toggling.
4	1	WO	Enable PA4 digital input, wake-up event and interrupt request. 1 / 0 : enable / disable. This bit can be set to low to prevent leakage current when PA4 is assigned as AD input, and to disable wake-up from PA4 toggling and interrupt request from this pin.
3	1	WO	Enable PA3 digital input and wake-up event. 1 / 0 : enable / disable. This bit should be set to low when PA3 is assigned as AD input to prevent leakage current. If this bit is set to low, PA3 can NOT be used to wake-up the system.
2 - 1	1	WO	Reserved
0	1	WO	Enable PA0 digital input, wake-up event and interrupt request. 1 / 0: enable / disable. This bit can be set to low to prevent leakage current when PA0 is assigned as AD input, and to disable wake-up from PA0 toggling and interrupt request from this pin.

6.12. Port B Digital Input Enable Register (*pbdier*), IO address = 0x0e

Bit	Reset	R/W	Description
7 - 6	11	WO	Enable PB7~PB6 digital input and wake-up event. 1 /0: enable / disable. These bits should be set to low when PB7~PB6 assigned as AD input to prevent leakage current. If set to low, PB7~PB6 can NOT be used to wake-up the system.
5	1	WO	Enable PB5 digital input, wake-up event and interrupt request. 1 /0: enable / disable. This bit can be set to low to prevent leakage current when PB5 is assigned as AD input, and to disable wake-up from PB5 toggling and interrupt request from this pin.
4 - 1	1111	WO	Enable PB4~PB1 digital input and wake-up event. 1 /0: enable / disable. These bits should be set to low when PB4~PB1 assigned as AD input to prevent leakage current. If set to low, PB4~PB1 can NOT be used to wake-up the system.
0	1	WO	Enable PB0 digital input, wake-up event and interrupt request. 1 /0: enable / disable. This bit can be set to low to prevent leakage current when PB0 is assigned as AD input, and to disable wake-up from PB0 toggling and interrupt request from this pin.

6.13. Port A Data Register (*pa*), IO address = 0x10

Bit	Reset	R/W	Description
7 - 0	0x00	R/W	Data register for Port A.

6.14. Port A Control Register (*pac*), IO address = 0x11

Bit	Reset	R/W	Description
7 - 0	0x00	R/W	Port A control registers. This register is used to define input mode or output mode for each corresponding pin of port A. 0 / 1: input / output <u>Please note that PA5 can be INPUT or OUTPUT LOW ONLY, the output state will be tri-state when PA5 is programmed into output mode with data 1.</u>

6.15. Port A Pull-High Register (*paph*), IO address = 0x12

Bit	Reset	R/W	Description
7 - 0	0x00	R/W	Port A pull-high register. This register is used to enable the internal pull-high device on each corresponding pin of port A and this pull high function is active only for input mode. 0 / 1 : disable / enable

6.16. Port B Data Register (*pb*), IO address = 0x14

Bit	Reset	R/W	Description
7 - 0	0x00	R/W	Data register for Port B.

6.17. Port B Control Register (*pbc*), IO address = 0x15

Bit	Reset	R/W	Description
7 - 0	0x00	R/W	Port B control register. This register is used to define input mode or output mode for each corresponding pin of port B. 0 / 1: input / output

6.18. Port B Pull-High Register (*pbph*), IO address = 0x16

Bit	Reset	R/W	Description
7 - 0	0x00	R/W	Port B pull-high register. This register is used to enable the internal pull-high device on each corresponding pin of port B and this pull high function is active only for input mode. 0 / 1 : disable / enable

6.19. Miscellaneous Register (*misc*), IO address = 0x17

Bit	Reset	R/W	Description
7 - 6	-	-	Reserved. (keep 0 for future compatibility)
5	0	WO	Enable fast Wake-up. Fast wake-up is NOT supported when EOSC is enabled. 0: Normal wake-up. The wake-up time is 3000 ILRC clocks (Not for fast boot-up) 1: Fast wake-up. The wake-up time is 45 ILRC clocks
4 - 3	-	-	Reserved. (keep 0 for future compatibility)
2	0	WO	Disable LVR function. 0 / 1 : Enable / Disable
1 - 0	00	WO	Watch dog time out period. 00: 8k ILRC clock period 01: 16k ILRC clock period 10: 64k ILRC clock period 11: 256k ILRC clock period

6.20. Comparator Control Register (*gpcc*), IO address = 0x18

Bit	Reset	R/W	Description
7	0	R/W	Enable comparator. 0 / 1 : disable / enable When this bit is set to enable, please also set the corresponding analog input pins to be digital disable to prevent IO leakage.
6	-	RO	Comparator result of comparator. 0: plus input < minus input 1: plus input > minus input
5	0	R/W	Select whether the comparator result output will be sampled by TM2_CLK? 0: result output NOT sampled by TM2_CLK 1: result output sampled by TM2_CLK
4	0	R/W	Inverse the polarity of result output of comparator. 0: polarity is NOT inversed. 1: polarity is inversed.
3 - 1	000	R/W	Selection the minus input (-) of comparator. 000 : PA3 001 : PA4 010 : Internal 1.20 volt band-gap reference voltage 011 : V _{internal R} 100 : PB6 101 : PB7 11X: reserved
0	0	R/W	Selection the plus input (+) of comparator. 0 : V _{internal R} 1 : PA4

6.21. Comparator Selection Register (*gpcs*), IO address = 0x19

Bit	Reset	R/W	Description
7	0	WO	Comparator output enable (to PA0). 0 / 1 : disable / enable
6	0	-	Reserved
5	0	WO	Selection of high range of comparator.
4	0	WO	Selection of low range of comparator.
3 - 0	0000	WO	Selection the voltage level of comparator. 0000 (lowest) ~ 1111 (highest)

6.22. Reset Status Register (*rstst*), IO address = 0x1b

Bit	Reset (POR only)	R/W	Description
7	0	R/W	The reset flag for the Watch-Dog time-out. This bit is 1 when Watch-Dog reset occurs. Write 0 to clear this flag or POR clear.
6	0	R/W	The reset flag for the invalid code. This bit is 1 when invalid code reset occurs. Write 0 to clear this flag or POR clear.
5	0	-	Reserved. Please keep 0.
4	-	-	Reserved. Please keep 1.
3	-	R/W	The reset flag for the external reset pin (PA5). This bit is 1 when PA5 reset occurs. Write 0 to clear this flag.
2	-	R/W	VDD below 4V flag. This bit is 1 when the VDD voltage is lower than 4V. Write 0 to clear this flag. Please note that this bit will be 1 automatically when VDD is powered slowly. If necessary, it is recommended to clear this flag during the program initialization.
1	-	R/W	VDD below 3V flag. This bit is 1 when the VDD voltage is lower than 3V. Write 0 to clear this flag. Please note that this bit will be 1 automatically when VDD is powered slowly. If necessary, it is recommended to clear this flag during the program initialization.
0	-	R/W	VDD below 2V flag. This bit is 1 when the VDD voltage is lower than 2V. Write 0 to clear this flag. Please note that this bit will be 1 automatically when VDD is powered slowly. If necessary, it is recommended to clear this flag during the program initialization.

6.23. Timer2 Control Register (*tm2c*), IO address = 0x1c

Bit	Reset	R/W	Description
7 - 4	0000	R/W	Timer2 clock selection. 0000 : disable 0001 : CLK (system clock) 0010 : IHRC 0011 : EOSC 0100 : ILRC 0101 : comparator output 011x : reserved 1000 : PA0 (rising edge) 1001 : ~PA0 (falling edge) 1010 : PB0 (rising edge) 1011 : ~PB0 (falling edge) 1100 : PA4 (rising edge) 1101 : ~PA4 (falling edge) Notice: In ICE mode and IHRC is selected for Timer2 clock, <u>the clock sent to Timer2 does NOT be stopped, Timer2 will keep counting when ICE is in halt state.</u>
3 - 2	00	R/W	Timer2 output selection. 00 : disable 01 : PB2 10 : PA3 11 : PB4
1	0	R/W	Timer2 mode selection. 0 / 1 : period mode / PWM mode
0	0	R/W	Enable to inverse the polarity of Timer2 output. 0 / 1: disable / enable.

6.24. Timer2 Counter Register (*tm2ct*), IO address = 0x1d

Bit	Reset	R/W	Description
7-0	0x00	R/W	Bit [7:0] of Timer2 counter register.

6.25. Timer2 Scalar Register (*tm2s*), IO address = 0x1e

Bit	Reset	R/W	Description
7	0	WO	PWM resolution selection. 0 : 8-bit 1 : 6-bit
6 - 5	00	WO	Timer2 clock pre-scalar. 00 : ÷ 1 01 : ÷ 4 10 : ÷ 16 11 : ÷ 64
4 - 0	00000	WO	Timer2 clock scalar.

6.26. Timer2 Bound Register (*tm2b*), IO address = 0x09

Bit	Reset	R/W	Description
7 - 0	0x00	WO	Timer2 bound register.

6.27. PWMG0 control Register (*pwmg0c*), IO address = 0x20

Bit	Reset	R/W	Description
7	0	WO	Enable PWMG0 generator. 0 / 1 : disable / enable.
6	-	RO	Output status of PWMG0 generator.
5	0	WO	Enable to inverse the polarity of PWMG0 generator output. 0 / 1 : disable / enable.
4	0	WO	PWMG0 counter reset. Writing "1" to clear PWMG0 counter and this bit will be self clear to 0 after counter reset.
3 - 1	0	WO	Select PWM output pin for PWMG0. 000: none 001: PB5 011: PA0 100: PB4 Others: reserved
0	0	WO	Clock source of PWMG0 generator. 0 : SYSCLK 1 : IHRC or IHRC * 2 (by Code Option: PWM_Source)

6.28. PWMG0 Scalar Register (*pwmg0s*), IO address = 0x21

Bit	Reset	R/W	Description
7	0	WO	PWMG0 interrupt mode. 0: Generate interrupt when counter matches the duty value 1: Generate interrupt when counter is 0.
6 - 5	0	WO	PWMG0 clock pre-scalar. 00 : ÷1 01 : ÷4 10 : ÷16 11 : ÷64
4 - 0	0	WO	PWMG0 clock divider.

6.29. PWMG0 Counter Upper Bound High Register (*pwmg0cubh*), IO address = 0x24

Bit	Reset	R/W	Description
7 - 0	-	WO	Bit[10:3] of PWMG0 counter upper bound.

6.30. PWMG0 Counter Upper Bound Low Register (*pwmg0cubl*), IO address = 0x25

Bit	Reset	R/W	Description
7 - 6	-	WO	Bit[2:1] of PWMG0 counter upper bound.
5 - 0	-	-	Reserved

6.31. PWMG0 Duty Value High Register (*pwmg0dth*), IO address = 0x22

Bit	Reset	R/W	Description
7 - 0	-	WO	Duty values bit[10:3] of PWMG0.

6.32. PWMG0 Duty Value Low Register (*pwmg0dtl*), IO address = 0x23

Bit	Reset	R/W	Description
7 - 5	-	WO	Duty values bit [2:0] of PWMG0.
4 - 0	-	-	Reserved

Note: It's necessary to write PWMG0 Duty_Value Low Register before writing PWMG0 Duty_Value High Register.

6.33. Timer3 Control Register (*tm3c*), IO address = 0x32

Bit	Reset	R/W	Description
7 - 4	0000	R/W	Timer3 clock selection. 0000 : disable 0001 : CLK (system clock) 0010 : IHRC 0011 : EOSC 0100 : ILRC 0101 : comparator output 011x : reserved 1000 : PA0 (rising edge) 1001 : ~PA0 (falling edge) 1010 : PB0 (rising edge) 1011 : ~PB0 (falling edge) 1100 : PA4 (rising edge) 1101 : ~PA4 (falling edge) Notice: In ICE mode and IHRC is selected for Timer3 clock, the clock sent to Timer3 does NOT be stopped, Timer3 will keep counting when ICE is in halt state.
3 - 2	00	R/W	Timer3 output selection. 00 : disable 01 : PB5 10 : PB6 11 : PB7
1	0	R/W	Timer3 mode selection. 0 / 1 : period mode / PWM mode
0	0	R/W	Enable to inverse the polarity of Timer3 output. 0 / 1: disable / enable

6.34. Timer3 Counter Register (*tm3ct*), IO address = 0x33

Bit	Reset	R/W	Description
7 - 0	0x00	R/W	Bit [7:0] of Timer3 counter register.

6.35. Timer3 Scalar Register (*tm3s*), IO address = 0x34

Bit	Reset	R/W	Description
7	0	WO	PWM resolution selection. 0 : 8-bit 1 : 6-bit
6 - 5	00	WO	Timer3 clock pre-scalar. 00 : ÷ 1 01 : ÷ 4 10 : ÷ 16 11 : ÷ 64
4 - 0	00000	WO	Timer3 clock scalar.

6.36. Timer3 Bound Register (*tm3b*), IO address = 0x3f

Bit	Reset	R/W	Description
7 - 0	0x00	WO	Timer3 bound register.

6.37. ADC Control Register (*adcc*), IO address = 0x3b

Bit	Reset	R/W	Description
7	0	R/W	Enable ADC function. 0/1: Disable/Enable.
6	0	R/W	ADC process control bit. Read "1" to indicate the ADC is ready.
5 - 2	0000	R/W	Channel selector. These four bits are used to select input signal for AD conversion. 0000: PB0/AD0, 0001: PB1/AD1, 0010: PB2/AD2, 0011: PB3/AD3, 0100: PB4/AD4, 0101: PB5/AD5, 0110: PB6/AD6, 0111: PB7/AD7, 1000: PA3/AD8, 1001: PA4/AD9, 1010: PA0/AD10, 1111: (Channel F) Band-gap reference voltage or 0.25*V _{DD} Others: reserved
0 - 1	-	-	Reserved. (keep 0 for future compatibility)

6.38. ADC Mode Register (*adcm*), IO address = 0x3c

Bit	Reset	R/W	Description
7 - 4	-	-	Reserved (keep 0 for future compatibility)
3 - 1	000	WO	ADC clock source selection. 000: CLK (system clock) ÷ 1, 001: CLK (system clock) ÷ 2, 010: CLK (system clock) ÷ 4, 011: CLK (system clock) ÷ 8, 100: CLK (system clock) ÷ 16, 101: CLK (system clock) ÷ 32, 110: CLK (system clock) ÷ 64, 111: CLK (system clock) ÷ 128,
0	-	-	Reserved

6.39. ADC Regulator Control Register (*adcr gc*), IO address = 0x3d

Bit	Reset	R/W	Description
7 - 5	000	WO	These three bits are used to select input signal for ADC reference high voltage. 000: V_{DD} , 001: 2V, 010: 3V, 011: 4V, 100: PB1, 101: Band-gap 1.20 volt reference voltage Others: reserved
4	0	WO	ADC channel F selector: 0: Band-gap reference voltage 1: $0.25 \cdot V_{DD}$. The deviation is within $\pm 0.01 \cdot V_{DD}$ mostly.
3 - 2	00	WO	Band-gap reference voltage selector for ADC channel F: 00: 1.2V 01: 2V 10: 3V 11: 4V
1 - 0	-	-	Reserved. Please keep 0.

6.40. ADC Result High Register (*adcrh*), IO address = 0x3e

Bit	Reset	R/W	Description
7 - 0	-	RO	These eight read-only bits will be the bit [11:4] of AD conversion result. The bit 7 of this register is the MSB of ADC result for any resolution.

6.41. ADC Result Low Register (*adcr l*), IO address = 0x3f

Bit	Reset	R/W	Description
7 - 4	-	RO	These four bits will be the bit [3:0] of AD conversion result.
3 - 0	-	-	Reserved

6.42. PWMG1 control Register (*pwmg1c*), IO address = 0x26

Bit	Reset	R/W	Description
7	0	WO	Enable PWMG1. 0 / 1 : disable / enable.
6	-	RO	Output of PWMG1.
5	0	WO	Enable to inverse the polarity of PWMG1 output. 0 / 1 : disable / enable.
4	0	WO	PWMG1 counter reset. Writing "1" to clear PWMG1 counter.
3 - 1	0	WO	Select PWMG1 output pin. 000: none 001: PB6 011: PA4 100: PB7 Others: reserved
0	0	WO	Clock source of PWMG1. 0 : SYCLK 1 : IHRC or IHRC * 2 (by Code Option : PWM_Source)

6.43. PWMG1 Scalar Register (*pwmg1s*), IO address = 0x27

Bit	Reset	R/W	Description
7	0	WO	PWMG1 interrupt mode. 0: Generate interrupt when counter matches the duty value. 1: Generate interrupt when counter is 0.
6 - 5	0	WO	PWMG1 clock pre-scalar. 00 : ÷1 01 : ÷4 10 : ÷16 11 : ÷64
4 - 0	0	WO	PWMG1 clock divider.

6.44. PWMG1 Counter Upper Bound High Register (*pwmg1cubh*), IO address = 0x2A

Bit	Reset	R/W	Description
7 - 0	8'h00	WO	Bit[10:3] of PWMG1 counter upper bound.

6.45. PWMG1 Counter Upper Bound Low Register (*pwmg1cubl*), IO address = 0x2B

Bit	Reset	R/W	Description
7 - 6	000	WO	Bit[2:1] of PWMG1 counter upper bound.
5 - 0	-	-	Reserved

6.46. PWMG1 Duty Value High Register (*pwmg1dth*), IO address = 0x28

Bit	Reset	R/W	Description
7 - 0	8'h00	WO	Duty values bit[10:3] of PWMG1.

6.47. PWMG1 Duty Value Low Register (*pwmg1dtl*), IO address = 0x29

Bit	Reset	R/W	Description
7 - 5	000	WO	Duty values bit[2:0] of PWMG1.
4 - 0	-	-	Reserved

Note: It's necessary to write PWMG1 Duty_Value Low Register before writing PWMG1 Duty_Value High Register.

6.48. PWMG2 control Register (*pwmg2c*), IO address = 0x2C

Bit	Reset	R/W	Description
7	0	WO	Enable PWMG2. 0 / 1 : disable / enable.
6	-	RO	Output of PWMG2.
5	0	WO	Enable to inverse the polarity of PWMG2 output. 0 / 1 : disable / enable.
4	0	WO	PWMG2 counter reset. Writing "1" to clear PWMG2 counter.
3 - 1	0	WO	Select PWMG2 output pin. 000: disable 001: PB3 011: PA3 100: PB2 101: PA5 (ICE does NOT support) Others: reserved
0	0	WO	Clock source of PWMG2. 0 : SYSCLK 1 : IHRC or IHRC * 2 (by Code Option : PWM_Source)

6.49. PWMG2 Scalar Register (*pwmg2s*), IO address = 0x2D

Bit	Reset	R/W	Description
7	0	WO	PWMG2 interrupt mode. 0: Generate interrupt when counter matches the duty value. 1: Generate interrupt when counter is 0.
6 - 5	0	WO	PWMG2 clock pre-scalar. 00 : ÷1 01 : ÷4 10 : ÷16 11 : ÷64
4 - 0	0	WO	PWMG2 clock divider.

6.50. PWMG2 Counter Upper Bound High Register (*pwmg2cubh*), IO address = 0x30

Bit	Reset	R/W	Description
7 - 0	8'h00	WO	Bit[10:3] of PWMG2 counter upper bound.

6.51. PWMG2 Counter Upper Bound Low Register (*pwmg2cubl*), IO address = 0x31

Bit	Reset	R/W	Description
7 - 6	000	WO	Bit[2:1] of PWMG2 counter upper bound.
5 - 0	-	-	Reserved

6.52. PWMG2 Duty Value High Register (*pwmg2dth*), IO address = 0x2E

Bit	Reset	R/W	Description
7 - 0	8'h00	WO	Duty values bit[10:3] of PWMG2.

6.53. PWMG2 Duty Value Low Register (*pwmg2dtl*), IO address = 0x2F

Bit	Reset	R/W	Description
7 - 5	000	WO	Duty values bit[2:0] of PWMG2.
4 - 0	-	-	Reserved

Note: It's necessary to write PWMG2 Duty_Value Low Register before writing PWMG2 Duty_Value High Register.

7. Instructions

Symbol	Description
ACC	Accumulator (Abbreviation of accumulator)
a	Accumulator (symbol of accumulator in program)
sp	Stack pointer
flag	ACC status flag register
I	Immediate data
&	Logical AND
 	Logical OR
←	Movement
^	Exclusive logic OR
+	Add
—	Subtraction
~	NOT (logical complement, 1's complement)
⌋	NEG (2's complement)
OV	Overflow (The operational result is out of range in signed 2's complement number system)
Z	Zero (If the result of ALU operation is zero, this bit is set to 1)
C	Carry (The operational result is to have carry out for addition or to borrow carry for subtraction in unsigned number system)
AC	Auxiliary Carry (If there is a carry out from low nibble after the result of ALU operation, this bit is set to 1)
IO.n	The bit of register
M.n	Only addressed in 0~0x3F (0~63) is allowed

7.1. Data Transfer Instructions

<i>mov</i> a, I	<p>Move immediate data into ACC.</p> <p>Example: <i>mov</i> a, 0x0f;</p> <p>Result: $a \leftarrow 0fh$;</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>mov</i> M, a	<p>Move data from ACC into memory</p> <p>Example: <i>mov</i> MEM, a;</p> <p>Result: $MEM \leftarrow a$</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>mov</i> a, M	<p>Move data from memory into ACC</p> <p>Example: <i>mov</i> a, MEM ;</p> <p>Result: $a \leftarrow MEM$; Flag Z is set when MEM is zero.</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>mov</i> a, IO	<p>Move data from IO into ACC</p> <p>Example: <i>mov</i> a, pa ;</p> <p>Result: $a \leftarrow pa$; Flag Z is set when pa is zero.</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>mov</i> IO, a	<p>Move data from ACC into IO</p> <p>Example: <i>mov</i> pb, a;</p> <p>Result: $pb \leftarrow a$</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>ldt16</i> word	<p>Move 16-bit counting values in Timer16 to memory in word.</p> <p>Example: <i>ldt16</i> word;</p> <p>Result: $word \leftarrow 16\text{-bit timer}$</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <pre> word T16val ; // declare a RAM word ... clear lb@ T16val ; // clear T16val (LSB) clear hb@ T16val ; // clear T16val (MSB) stt16 T16val ; // initial T16 with 0 ... set1 t16m.5 ; // enable Timer16 ... set0 t16m.5 ; // disable Timer 16 ldt16 T16val ; // save the T16 counting value to T16val </pre>

<i>stt16</i> word	<p>Store 16-bit data from memory in word to Timer16.</p> <p>Example: <i>stt16</i> word;</p> <p>Result: 16-bit timer ← word</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <hr style="border-top: 1px dashed black;"/> <pre> word T16val ; // declare a RAM word ... mov a, 0x34 ; mov lb@ T16val , a ; // move 0x34 to T16val (LSB) mov a, 0x12 ; mov hb@ T16val , a ; // move 0x12 to T16val (MSB) stt16 T16val ; // initial T16 with 0x1234 ... </pre> <hr style="border-top: 1px dashed black;"/>
<i>idxm</i> a, index	<p>Move data from specified memory to ACC by indirect method. It needs 2T to execute this instruction.</p> <p>Example: <i>idxm</i> a, index;</p> <p>Result: a ← [index], where index is declared by word.</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <hr style="border-top: 1px dashed black;"/> <pre> word RAMIndex ; // declare a RAM pointer ... mov a, 0x5B ; // assign pointer to an address (LSB) mov lb@RAMIndex, a ; // save pointer to RAM (LSB) mov a, 0x00 ; // assign 0x00 to an address (MSB), should be 0 mov hb@RAMIndex, a ; // save pointer to RAM (MSB) ... idxm a, RAMIndex ; // mov memory data in address 0x5B to ACC </pre> <hr style="border-top: 1px dashed black;"/>
<i>ldxm</i> index, a	<p>Move data from ACC to specified memory by indirect method. It needs 2T to execute this instruction.</p> <p>Example: <i>ldxm</i> index, a;</p> <p>Result: [index] ← a; where index is declared by word.</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <hr style="border-top: 1px dashed black;"/> <pre> word RAMIndex ; // declare a RAM pointer ... mov a, 0x5B ; // assign pointer to an address (LSB) mov lb@RAMIndex, a ; // save pointer to RAM (LSB) mov a, 0x00 ; // assign 0x00 to an address (MSB), should be 0 mov hb@RAMIndex, a ; // save pointer to RAM (MSB) ... mov a, 0xA5 ; ldxm RAMIndex, a ; // mov 0xA5 to memory in address 0x5B </pre> <hr style="border-top: 1px dashed black;"/>

<i>xch</i> <i>M</i>	<p>Exchange data between ACC and memory</p> <p>Example: <code>xch MEM ;</code></p> <p>Result: $MEM \leftarrow a, a \leftarrow MEM$</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>pushaf</i>	<p>Move the ACC and flag register to memory that address specified in the stack pointer.</p> <p>Example: <code>pushaf;</code></p> <p>Result: $[sp] \leftarrow \{flag, ACC\};$ $sp \leftarrow sp + 2 ;$</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <hr/> <pre>.romadr 0x10 ; // ISR entry address pushaf ; // put ACC and flag into stack memory ... // ISR program ... // ISR program popaf ; // restore ACC and flag from stack memory reti ;</pre> <hr/>
<i>popaf</i>	<p>Restore ACC and flag from the memory which address is specified in the stack pointer.</p> <p>Example: <code>popaf;</code></p> <p>Result: $sp \leftarrow sp - 2 ;$ $\{Flag, ACC\} \leftarrow [sp] ;$</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>

7.2. Arithmetic Operation Instructions

<i>add</i> <i>a, l</i>	<p>Add immediate data with ACC, then put result into ACC</p> <p>Example: <code>add a, 0x0f ;</code></p> <p>Result: $a \leftarrow a + 0fh$</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>add</i> <i>a, M</i>	<p>Add data in memory with ACC, then put result into ACC</p> <p>Example: <code>add a, MEM ;</code></p> <p>Result: $a \leftarrow a + MEM$</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>add</i> <i>M, a</i>	<p>Add data in memory with ACC, then put result into memory</p> <p>Example: <code>add MEM, a;</code></p> <p>Result: $MEM \leftarrow a + MEM$</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>addc</i> <i>a, M</i>	<p>Add data in memory with ACC and carry bit, then put result into ACC</p> <p>Example: <code>addc a, MEM ;</code></p> <p>Result: $a \leftarrow a + MEM + C$</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>addc</i> <i>M, a</i>	<p>Add data in memory with ACC and carry bit, then put result into memory</p> <p>Example: <code>addc MEM, a ;</code></p> <p>Result: $MEM \leftarrow a + MEM + C$</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>

<i>addc a</i>	<p>Add carry with ACC, then put result into ACC</p> <p>Example: <i>addc a ;</i></p> <p>Result: $a \leftarrow a + C$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>addc M</i>	<p>Add carry with memory, then put result into memory</p> <p>Example: <i>addc MEM ;</i></p> <p>Result: $\text{MEM} \leftarrow \text{MEM} + C$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>nadd a, M</i>	<p>Add negative logic (2's complement) of ACC with memory</p> <p>Example: <i>nadd a, MEM ;</i></p> <p>Result: $a \leftarrow \overline{a} + \text{MEM}$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>nadd M, a</i>	<p>Add negative logic (2's complement) of memory with ACC</p> <p>Example: <i>nadd MEM, a ;</i></p> <p>Result: $\text{MEM} \leftarrow \overline{\text{MEM}} + a$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>sub a, l</i>	<p>Subtraction immediate data from ACC, then put result into ACC.</p> <p>Example: <i>sub a, 0x0f;</i></p> <p>Result: $a \leftarrow a - 0fh \text{ (} a + [2\text{'s complement of } 0fh] \text{)}$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>sub a, M</i>	<p>Subtraction data in memory from ACC, then put result into ACC</p> <p>Example: <i>sub a, MEM ;</i></p> <p>Result: $a \leftarrow a - \text{MEM} \text{ (} a + [2\text{'s complement of } M] \text{)}$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>sub M, a</i>	<p>Subtraction data in ACC from memory, then put result into memory</p> <p>Example: <i>sub MEM, a;</i></p> <p>Result: $\text{MEM} \leftarrow \text{MEM} - a \text{ (} \text{MEM} + [2\text{'s complement of } a] \text{)}$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>subc a, M</i>	<p>Subtraction data in memory and carry from ACC, then put result into ACC</p> <p>Example: <i>subc a, MEM;</i></p> <p>Result: $a \leftarrow a - \text{MEM} - C$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>subc M, a</i>	<p>Subtraction ACC and carry bit from memory, then put result into memory</p> <p>Example: <i>subc MEM, a ;</i></p> <p>Result: $\text{MEM} \leftarrow \text{MEM} - a - C$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>subc a</i>	<p>Subtraction carry from ACC, then put result into ACC</p> <p>Example: <i>subc a;</i></p> <p>Result: $a \leftarrow a - C$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>
<i>subc M</i>	<p>Subtraction carry from the content of memory, then put result into memory</p> <p>Example: <i>subc MEM;</i></p> <p>Result: $\text{MEM} \leftarrow \text{MEM} - C$</p> <p>Affected flags: $\text{『Y』Z} \quad \text{『Y』C} \quad \text{『Y』AC} \quad \text{『Y』OV}$</p>

<i>inc M</i>	Increment the content of memory Example: <code>inc MEM ;</code> Result: $MEM \leftarrow MEM + 1$ Affected flags: $\text{『Y』 Z } \text{『Y』 C } \text{『Y』 AC } \text{『Y』 OV}$
<i>dec M</i>	Decrement the content of memory Example: <code>dec MEM;</code> Result: $MEM \leftarrow MEM - 1$ Affected flags: $\text{『Y』 Z } \text{『Y』 C } \text{『Y』 AC } \text{『Y』 OV}$
<i>clear M</i>	Clear the content of memory Example: <code>clear MEM ;</code> Result: $MEM \leftarrow 0$ Affected flags: $\text{『N』 Z } \text{『N』 C } \text{『N』 AC } \text{『N』 OV}$
<i>mul</i>	Multiplication operation, 8x8 unsigned multiplications will be executed. Example: <code>mul ;</code> Result: $\{\text{MulRH,ACC}\} \leftarrow \text{ACC} * \text{MulOp}$ Affected flags: $\text{『N』 Z } \text{『N』 C } \text{『N』 AC } \text{『N』 OV}$ Application Example : ----- <pre> ... mov a, 0x5a ; mov mulop, a ; mov a, 0xa5 ; mul // 0x5A * 0xA5 = 3A02 (mulrh + ACC) mov ram0, a ; // LSB, ram0=0x02 mov a, mulrh ; // MSB, ACC=0X3A ... </pre> -----

7.3. Shift Operation Instructions

<i>sr a</i>	Shift right of ACC, shift 0 to bit 7 Example: <code>sr a ;</code> Result: $a(0, b7, b6, b5, b4, b3, b2, b1) \leftarrow a(b7, b6, b5, b4, b3, b2, b1, b0), C \leftarrow a(b0)$ Affected flags: $\text{『N』 Z } \text{『Y』 C } \text{『N』 AC } \text{『N』 OV}$
<i>src a</i>	Shift right of ACC with carry bit 7 to flag Example: <code>src a ;</code> Result: $a(c, b7, b6, b5, b4, b3, b2, b1) \leftarrow a(b7, b6, b5, b4, b3, b2, b1, b0), C \leftarrow a(b0)$ Affected flags: $\text{『N』 Z } \text{『Y』 C } \text{『N』 AC } \text{『N』 OV}$
<i>sr M</i>	Shift right the content of memory, shift 0 to bit 7 Example: <code>sr MEM ;</code> Result: $\text{MEM}(0, b7, b6, b5, b4, b3, b2, b1) \leftarrow \text{MEM}(b7, b6, b5, b4, b3, b2, b1, b0), C \leftarrow \text{MEM}(b0)$ Affected flags: $\text{『N』 Z } \text{『Y』 C } \text{『N』 AC } \text{『N』 OV}$
<i>src M</i>	Shift right of memory with carry bit 7 to flag Example: <code>src MEM ;</code> Result: $\text{MEM}(c, b7, b6, b5, b4, b3, b2, b1) \leftarrow \text{MEM}(b7, b6, b5, b4, b3, b2, b1, b0), C \leftarrow \text{MEM}(b0)$ Affected flags: $\text{『N』 Z } \text{『Y』 C } \text{『N』 AC } \text{『N』 OV}$

<i>sl a</i>	Shift left of ACC shift 0 to bit 0 Example: <i>sl a</i> ; Result: $a(b6, b5, b4, b3, b2, b1, b0, 0) \leftarrow a(b7, b6, b5, b4, b3, b2, b1, b0)$, $C \leftarrow a(b7)$ Affected flags: 『N』 Z 『Y』 C 『N』 AC 『N』 OV
<i>slc a</i>	Shift left of ACC with carry bit 0 to flag Example: <i>slc a</i> ; Result: $a(b6, b5, b4, b3, b2, b1, b0, c) \leftarrow a(b7, b6, b5, b4, b3, b2, b1, b0)$, $C \leftarrow a(b7)$ Affected flags: 『N』 Z 『Y』 C 『N』 AC 『N』 OV
<i>sl M</i>	Shift left of memory, shift 0 to bit 0 Example: <i>sl MEM</i> ; Result: $MEM(b6, b5, b4, b3, b2, b1, b0, 0) \leftarrow MEM(b7, b6, b5, b4, b3, b2, b1, b0)$, $C \leftarrow MEM(b7)$ Affected flags: 『N』 Z 『Y』 C 『N』 AC 『N』 OV
<i>slc M</i>	Shift left of memory with carry bit 0 to flag Example: <i>slc MEM</i> ; Result: $MEM(b6, b5, b4, b3, b2, b1, b0, C) \leftarrow MEM(b7, b6, b5, b4, b3, b2, b1, b0)$, $C \leftarrow MEM(b7)$ Affected flags: 『N』 Z 『Y』 C 『N』 AC 『N』 OV
<i>swap a</i>	Swap the high nibble and low nibble of ACC Example: <i>swap a</i> ; Result: $a(b3, b2, b1, b0, b7, b6, b5, b4) \leftarrow a(b7, b6, b5, b4, b3, b2, b1, b0)$ Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV

7.4. Logic Operation Instructions

<i>and a, l</i>	Perform logic AND on ACC and immediate data, then put result into ACC Example: <i>and a, 0x0f</i> ; Result: $a \leftarrow a \& 0fh$ Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV
<i>and a, M</i>	Perform logic AND on ACC and memory, then put result into ACC Example: <i>and a, RAM10</i> ; Result: $a \leftarrow a \& RAM10$ Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV
<i>and M, a</i>	Perform logic AND on ACC and memory, then put result into memory Example: <i>and MEM, a</i> ; Result: $MEM \leftarrow a \& MEM$ Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV
<i>or a, l</i>	Perform logic OR on ACC and immediate data, then put result into ACC Example: <i>or a, 0x0f</i> ; Result: $a \leftarrow a 0fh$ Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV
<i>or a, M</i>	Perform logic OR on ACC and memory, then put result into ACC Example: <i>or a, MEM</i> ; Result: $a \leftarrow a MEM$ Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV
<i>or M, a</i>	Perform logic OR on ACC and memory, then put result into memory Example: <i>or MEM, a</i> ; Result: $MEM \leftarrow a MEM$ Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV

<code>xor a, I</code>	<p>Perform logic XOR on ACC and immediate data, then put result into ACC</p> <p>Example: <code>xor a, 0x0f ;</code></p> <p>Result: $a \leftarrow a \oplus 0fh$</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p>
<code>xor IO, a</code>	<p>Perform logic XOR on ACC and IO register, then put result into IO register</p> <p>Example: <code>xor pa, a ;</code></p> <p>Result: $pa \leftarrow a \oplus pa$; // pa is the data register of port A</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<code>xor a, M</code>	<p>Perform logic XOR on ACC and memory, then put result into ACC</p> <p>Example: <code>xor a, MEM ;</code></p> <p>Result: $a \leftarrow a \oplus RAM10$</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p>
<code>xor M, a</code>	<p>Perform logic XOR on ACC and memory, then put result into memory</p> <p>Example: <code>xor MEM, a ;</code></p> <p>Result: $MEM \leftarrow a \oplus MEM$</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p>
<code>not a</code>	<p>Perform 1's complement (logical complement) of ACC</p> <p>Example: <code>not a ;</code></p> <p>Result: $a \leftarrow \sim a$</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <pre> mov a, 0x38 ; // ACC=0X38 not a ; // ACC=0XC7 </pre>
<code>not M</code>	<p>Perform 1's complement (logical complement) of memory</p> <p>Example: <code>not MEM ;</code></p> <p>Result: $MEM \leftarrow \sim MEM$</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <pre> mov a, 0x38 ; mov mem, a ; // mem = 0x38 not mem ; // mem = 0xC7 </pre>
<code>neg a</code>	<p>Perform 2's complement of ACC</p> <p>Example: <code>neg a ;</code></p> <p>Result: $a \leftarrow \overline{a}$</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <pre> mov a, 0x38 ; // ACC=0X38 neg a ; // ACC=0XC8 </pre>

<i>neg</i> <i>M</i>	<p>Perform 2's complement of memory</p> <p>Example: <code>neg MEM;</code></p> <p>Result: $MEM \leftarrow \overline{MEM}$</p> <p>Affected flags: 『Y』 Z 『N』 C 『N』 AC 『N』 OV</p> <p>Application Example:</p> <hr/> <pre> mov a, 0x38 ; mov mem, a ; // mem = 0x38 not mem ; // mem = 0xC8 </pre> <hr/>
<i>comp</i> <i>a, M</i>	<p>Compare ACC with the content of memory</p> <p>Example: <code>comp a, MEM;</code></p> <p>Result: Flag will be changed by regarding as (a - MEM)</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p> <p>Application Example:</p> <hr/> <pre> mov a, 0x38 ; mov mem, a ; comp a, mem ; // Z flag is set as 1 mov a, 0x42 ; mov mem, a ; mov a, 0x38 ; comp a, mem ; // C flag is set as 1 </pre> <hr/>
<i>comp</i> <i>M, a</i>	<p>Compare ACC with the content of memory</p> <p>Example: <code>comp MEM, a;</code></p> <p>Result: Flag will be changed by regarding as (MEM - a)</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>

7.5. Bit Operation Instructions

<i>set0</i> <i>IO.n</i>	<p>Set bit n of IO port to low</p> <p>Example: <code>set0 pa.5 ;</code></p> <p>Result: set bit 5 of port A to low</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>set1</i> <i>IO.n</i>	<p>Set bit n of IO port to high</p> <p>Example: <code>set1 pb.5 ;</code></p> <p>Result: set bit 5 of port B to high</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>

<i>swapc</i> IO.n	<p>Swap the nth bit of IO port with carry bit</p> <p>Example: <i>swapc</i> IO.0;</p> <p>Result: $C \leftarrow IO.0$, $IO.0 \leftarrow C$</p> <p>When IO.0 is a port to output pin, carry C will be sent to IO.0;</p> <p>When IO.0 is a port from input pin, IO.0 will be sent to carry C;</p> <p>Affected flags: 『N』 Z 『Y』 C 『N』 AC 『N』 OV</p> <p>Application Example1 (serial output) :</p> <hr/> <pre> ... set1 pac.0 ; // set PA.0 as output ... set0 flag.1 ; // C=0 swapc pa.0 ; // move C to PA.0 (bit operation), PA.0=0 set1 flag.1 ; // C=1 swapc pa.0 ; // move C to PA.0 (bit operation), PA.0=1 ... </pre> <hr/> <p>Application Example2 (serial input) :</p> <hr/> <pre> ... set0 pac.0 ; // set PA.0 as input ... swapc pa.0 ; // read PA.0 to C (bit operation) src a ; // shift C to bit 7 of ACC swapc pa.0 ; // read PA.0 to C (bit operation) src a ; // shift new C to bit 7, old C ... </pre> <hr/>
<i>set0</i> M.n	<p>Set bit n of memory to low</p> <p>Example: <i>set0</i> MEM.5 ;</p> <p>Result: set bit 5 of MEM to low</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>set1</i> M.n	<p>Set bit n of memory to high</p> <p>Example: <i>set1</i> MEM.5 ;</p> <p>Result: set bit 5 of MEM to high</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>

7.6. Conditional Operation Instructions

<i>ceqsn a, l</i>	<p>Compare ACC with immediate data and skip next instruction if both are equal.</p> <p>Flag will be changed like as ($a \leftarrow a - l$)</p> <p>Example: <i>ceqsn a, 0x55</i> ; <i>inc MEM</i> ; <i>goto error</i> ;</p> <p>Result: If $a=0x55$, then “goto error”; otherwise, “inc MEM”.</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>ceqsn a, M</i>	<p>Compare ACC with memory and skip next instruction if both are equal.</p> <p>Flag will be changed like as ($a \leftarrow a - M$)</p> <p>Example: <i>ceqsn a, MEM</i>;</p> <p>Result: If $a=MEM$, skip next instruction</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>cneqsn a, M</i>	<p>Compare ACC with memory and skip next instruction if both are not equal.</p> <p>Flag will be changed like as ($a \leftarrow a - M$)</p> <p>Example: <i>cneqsn a, MEM</i>;</p> <p>Result: If $a \neq MEM$, skip next instruction</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>cneqsn a, l</i>	<p>Compare ACC with immediate data and skip next instruction if both are no equal.</p> <p>Flag will be changed like as ($a \leftarrow a - l$)</p> <p>Example: <i>cneqsn a, 0x55</i> ; <i>inc MEM</i> ; <i>goto error</i> ;</p> <p>Result: If $a \neq 0x55$, then “goto error”; Otherwise, “inc MEM”.</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>
<i>t0sn IO.n</i>	<p>Check IO bit and skip next instruction if it's low</p> <p>Example: <i>t0sn pa.5</i>;</p> <p>Result: If bit 5 of port A is low, skip next instruction</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>t1sn IO.n</i>	<p>Check IO bit and skip next instruction if it's high</p> <p>Example: <i>t1sn pa.5</i> ;</p> <p>Result: If bit 5 of port A is high, skip next instruction</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>t0sn M.n</i>	<p>Check memory bit and skip next instruction if it's low</p> <p>Example: <i>t0sn MEM.5</i> ;</p> <p>Result: If bit 5 of MEM is low, then skip next instruction</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>t1sn M.n</i>	<p>Check memory bit and skip next instruction if it's high</p> <p>EX: <i>t1sn MEM.5</i> ;</p> <p>Result: If bit 5 of MEM is high, then skip next instruction</p> <p>Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>izsn a</i>	<p>Increment ACC and skip next instruction if ACC is zero</p> <p>Example: <i>izsn a</i>;</p> <p>Result: $a \leftarrow a + 1$, skip next instruction if $a = 0$</p> <p>Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV</p>

<i>dzn a</i>	Decrement ACC and skip next instruction if ACC is zero Example: <i>dzn a</i> ; Result: $A \leftarrow A - 1$, skip next instruction if $a = 0$ Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV
<i>izn M</i>	Increment memory and skip next instruction if memory is zero Example: <i>izn MEM</i> ; Result: $MEM \leftarrow MEM + 1$, skip next instruction if $MEM = 0$ Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV
<i>dzn M</i>	Decrement memory and skip next instruction if memory is zero Example: <i>dzn MEM</i> ; Result: $MEM \leftarrow MEM - 1$, skip next instruction if $MEM = 0$ Affected flags: 『Y』 Z 『Y』 C 『Y』 AC 『Y』 OV

7.7. System control Instructions

<i>call label</i>	Function call, address can be full range address space Example: <i>call function1</i> ; Result: $[sp] \leftarrow pc + 1$ $pc \leftarrow function1$ $sp \leftarrow sp + 2$ Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV
<i>goto label</i>	Go to specific address which can be full range address space Example: <i>goto error</i> ; Result: Go to error and execute program. Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV
<i>ret l</i>	Place immediate data to ACC, then return Example: <i>ret 0x55</i> ; Result: $A \leftarrow 55h$ <i>ret</i> ; Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV
<i>ret</i>	Return to program which had function call Example: <i>ret</i> ; Result: $sp \leftarrow sp - 2$ $pc \leftarrow [sp]$ Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV
<i>reti</i>	Return to program that is interrupt service routine. After this command is executed, global interrupt is enabled automatically. Example: <i>reti</i> ; Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV
<i>nop</i>	No operation Example: <i>nop</i> ; Result: nothing changed Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV

<i>pcadd a</i>	<p>Next program counter is current program counter plus ACC. Example: <code>pcadd a;</code> Result: <code>pc ← pc + a</code> Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV Application Example:</p> <hr style="border-top: 1px dashed black;"/> <pre> ... mov a, 0x02 ; pcadd a ; // PC <- PC+2 goto err1 ; goto correct ; // jump here goto err2 ; goto err3 ; ... correct: // jump here ... </pre> <hr style="border-top: 1px dashed black;"/>
<i>engint</i>	<p>Enable global interrupt enable Example: <code>engint;</code> Result: Interrupt request can be sent to CPU Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>disgint</i>	<p>Disable global interrupt enable Example: <code>disgint ;</code> Result: Interrupt request is blocked from CPU Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>stopsys</i>	<p>System halt. Example: <code>stopsys;</code> Result: Stop the system clocks and halt the system Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>stopexe</i>	<p>CPU halt. The oscillator module is still active to output clock, however, system clock is disabled to save power. Example: <code>stopexe;</code> Result: Stop the system clocks and keep oscillator modules active. Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>reset</i>	<p>Reset the whole chip, its operation will be same as hardware reset. Example: <code>reset;</code> Result: Reset the whole chip. Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>
<i>wdreset</i>	<p>Reset Watchdog timer. Example: <code>wdreset ;</code> Result: Reset Watchdog timer. Affected flags: 『N』 Z 『N』 C 『N』 AC 『N』 OV</p>

7.8. Summary of Instructions Execution Cycle

2T		<i>goto, call, idxm, pcadd, ret, reti,</i>
2T	Condition is fulfilled.	<i>ceqsn, cneqsn, t0sn, t1sn, dzsn, izsn</i>
1T	Condition is not fulfilled.	
1T		Others

7.9. Summary of affected flags by Instructions

Instruction	Z	C	AC	OV	Instruction	Z	C	AC	OV	Instruction	Z	C	AC	OV
<i>mov a, l</i>	-	-	-	-	<i>mov M, a</i>	-	-	-	-	<i>mov a, M</i>	Y	-	-	-
<i>mov a, IO</i>	Y	-	-	-	<i>mov IO, a</i>	-	-	-	-	<i>ldt16 word</i>	-	-	-	-
<i>stt16 word</i>	-	-	-	-	<i>idxm a, index</i>	-	-	-	-	<i>idxm index, a</i>	-	-	-	-
<i>xch M</i>	-	-	-	-	<i>pushaf</i>	-	-	-	-	<i>popaf</i>	Y	Y	Y	Y
<i>add a, l</i>	Y	Y	Y	Y	<i>add a, M</i>	Y	Y	Y	Y	<i>add M, a</i>	Y	Y	Y	Y
<i>addc a, M</i>	Y	Y	Y	Y	<i>addc M, a</i>	Y	Y	Y	Y	<i>addc a</i>	Y	Y	Y	Y
<i>addc M</i>	Y	Y	Y	Y	<i>nadd a, M</i>	Y	Y	Y	Y	<i>nadd M, a</i>	Y	Y	Y	Y
<i>sub a, l</i>	Y	Y	Y	Y	<i>sub a, M</i>	Y	Y	Y	Y	<i>sub M, a</i>	Y	Y	Y	Y
<i>subc a, M</i>	Y	Y	Y	Y	<i>subc M, a</i>	Y	Y	Y	Y	<i>subc a</i>	Y	Y	Y	Y
<i>subc M</i>	Y	Y	Y	Y	<i>inc M</i>	Y	Y	Y	Y	<i>dec M</i>	Y	Y	Y	Y
<i>clear M</i>	-	-	-	-	<i>mul</i>	-	-	-	-	<i>sra</i>	-	Y	-	-
<i>src a</i>	-	Y	-	-	<i>sr M</i>	-	Y	-	-	<i>src M</i>	-	Y	-	-
<i>sl a</i>	-	Y	-	-	<i>slc a</i>	-	Y	-	-	<i>sl M</i>	-	Y	-	-
<i>slc M</i>	-	Y	-	-	<i>swap a</i>	-	-	-	-	<i>and a, l</i>	Y	-	-	-
<i>and a, M</i>	Y	-	-	-	<i>and M, a</i>	Y	-	-	-	<i>or a, l</i>	Y	-	-	-
<i>or a, M</i>	Y	-	-	-	<i>or M, a</i>	Y	-	-	-	<i>xor a, l</i>	Y	-	-	-
<i>xor IO, a</i>	-	-	-	-	<i>xor a, M</i>	Y	-	-	-	<i>xor M, a</i>	Y	-	-	-
<i>not a</i>	Y	-	-	-	<i>not M</i>	Y	-	-	-	<i>neg a</i>	Y	-	-	-
<i>neg M</i>	Y	-	-	-	<i>comp a, M</i>	Y	Y	Y	Y	<i>comp M, a</i>	Y	Y	Y	Y
<i>set0 IO.n</i>	-	-	-	-	<i>set1 IO.n</i>	-	-	-	-	<i>set0 M.n</i>	-	-	-	-
<i>set1 M.n</i>	-	-	-	-	<i>swapc IO.n</i>	-	Y	-	-	<i>ceqsn a, l</i>	Y	Y	Y	Y
<i>ceqsn a, M</i>	Y	Y	Y	Y	<i>cneqsn a, M</i>	Y	Y	Y	Y	<i>cneqsn a, l</i>	Y	Y	Y	Y
<i>t0sn IO.n</i>	-	-	-	-	<i>t1sn IO.n</i>	-	-	-	-	<i>t0sn M.n</i>	-	-	-	-
<i>t1sn M.n</i>	-	-	-	-	<i>izsn a</i>	Y	Y	Y	Y	<i>dzsn a</i>	Y	Y	Y	Y
<i>izsn M</i>	Y	Y	Y	Y	<i>dzsn M</i>	Y	Y	Y	Y	<i>call label</i>	-	-	-	-
<i>goto label</i>	-	-	-	-	<i>ret l</i>	-	-	-	-	<i>ret</i>	-	-	-	-
<i>reti</i>	-	-	-	-	<i>nop</i>	-	-	-	-	<i>pcadd a</i>	-	-	-	-
<i>engint</i>	-	-	-	-	<i>disgint</i>	-	-	-	-	<i>stopsys</i>	-	-	-	-
<i>stopexe</i>	-	-	-	-	<i>reset</i>	-	-	-	-	<i>wdreset</i>	-	-	-	-

7.10. BIT definition

Bit defined: Only addressed at 0x00 ~ 0x3F.

8. Code Options

Option	Selection	Description
Security	Enable	OTP content is protected and program cannot be read back
	Disable	OTP content is not protected so program can be read back
LVR	4.0V	Select LVR = 4.0V
	3.5V	Select LVR = 3.5V
	3.0V	Select LVR = 3.0V
	2.75V	Select LVR = 2.75V
	2.5V	Select LVR = 2.5V
	2.2V	Select LVR = 2.2V
	2.0V	Select LVR = 2.0V
	1.8V	Select LVR = 1.8V
Boot-up_Time	Slow	Please refer to t_{WUP} and t_{SBP} in Section 4.1
	Fast	Please refer to t_{WUP} and t_{SBP} in Section 4.1
PWM_Source	16MHZ	When pwm0c.0= 1, PWMG0 clock source = IHRC = 16MHZ When pwm1c.0= 1, PWMG1 clock source = IHRC = 16MHZ When pwm2c.0= 1, PWMG2 clock source = IHRC = 16MHZ
	32MHZ	When pwm0c.0= 1, PWMG0 clock source = IHRC*2 = 32MHZ When pwm1c.0= 1, PWMG1 clock source = IHRC*2 = 32MHZ When pwm2c.0= 1, PWMG2 clock source = IHRC*2 = 32MHZ (ICE does NOT Support.)
GPC_PWM	Disable	GPC/ PWM are independent
	Enable	GPC output control PWM output (ICE does NOT Support.)
Interrupt Src0	PA.0	INTEN/ INTRQ.Bit0 is from PA.0
	PB.5	INTEN/ INTRQ.Bit0 is from PB.5
Interrupt Src1	PB.0	INTEN/ INTRQ.Bit1 is from PB.0
	PA.4	INTEN/ INTRQ.Bit1 is from PA.4
PB4_PB7_Drive	Normal	PB4 & PB7 Drive/ Sink Current is Normal
	Strong	PB4 & PB7 Drive/ Sink Current is Strong

9. Special Notes

This chapter is to remind user who use PMS132/PMS132B series IC in order to avoid frequent errors upon operation.

9.1. Warning

User must read all application notes of the IC by detail before using it. Please download the related application notes from the following link:

<http://www.padauk.com.tw/tw/technical/index.aspx>

9.2. Using IC

9.2.1 IO pin usage and setting

- (1) IO pin as digital input
 - ◆ When IO is set as digital input, the level of V_{ih} and V_{il} would changes with the voltage and temperature. Please follow the minimum value of V_{ih} and the maximum value of V_{il} .
 - ◆ The value of internal pull high resistor would also changes with the voltage, temperature and pin voltage. It is not the fixed value.
- (2) IO pin as digital input and enable wakeup function
 - ◆ Configure IO pin as input
 - ◆ Set PADIER and PBDIER registers to set the corresponding bit to 1.
- (3) PA5 is set to be output pin
 - ◆ PA5 can be set to be Open-Drain output pin only, output high requires adding pull-high resistor.
- (4) PA5 is set to be PRSTB input pin
 - ◆ Configure PA5 as input
 - ◆ Set CLKMD.0=1 to enable PA5 as PRSTB input pin
- (5) PA5 is set to be input pin and to connect with a push button or a switch by a long wire
 - ◆ Needs to put a $>33\Omega$ resistor in between PA5 and the long wire
 - ◆ Avoid using PA5 as input in such application.
- (6) PA7 and PA6 as external crystal oscillator
 - ◆ Configure PA7 and PA6 as input
 - ◆ Disable PA7 and PA6 internal pull-high resistor
 - ◆ Configure PADIER register to set PA6 and PA7 as analog input
 - ◆ EOSCR register bit [6:5] selects corresponding crystal oscillator frequency :
 - ✧ 01 : for lower frequency, ex : 32KHz
 - ✧ 10 : for middle frequency, ex : 455KHz, 1MHz
 - ✧ 11 : for higher frequency, ex : 4MHz
 - ◆ Program EOSCR.7 =1 to enable crystal oscillator
 - ◆ Ensure EOSC working well before switching from IHRC or ILRC to EOSC

Note: Please be sure to read the contents of PMC-APN013 carefully. According to this, the crystal oscillator should be used reasonably. If the following situations happen to cause IC start-up slowly or non-startup, PADAUK Technology is not responsible for this: the quality of the user's crystal oscillator is not good, the usage conditions are unreasonable, the PCB cleaner leakage current, or the PCB layouts are unreasonable.

9.2.2 Interrupt

(1) When using the interrupt function, the procedure should be:

Step1: Set INTEN register, enable the interrupt control bit

Step2: Clear INTRQ register

Step3: In the main program, using ENGINT to enable CPU interrupt function

Step4: Wait for interrupt. When interrupt occurs, enter to Interrupt Service Routine

Step5: After the Interrupt Service Routine being executed, return to the main program

*Use DISGINT in the main program to disable all interrupts

*When interrupt service routine starts, use PUSHAF instruction to save ALU and FLAG register.

POPAF instruction is to restore ALU and FLAG register before RETI as below:

```
void Interrupt (void)    // Once the interrupt occurs, jump to interrupt service routine
{
    // enter DISGINT status automatically, no more interrupt is accepted
    PUSHAF;
    ...
    POPAF;
} // RETI will be added automatically. After RETI being executed, ENGINT status will be
   restored
```

(2) INTEN and INTRQ have no initial values. Please set required value before enabling interrupt function

(3) PA4 and PB5 can be used as external interrupt pins. When using the PA4 as external interrupt pin, the setting method of **inten/intrq/integs** registers are same as that of PB0, the only difference is to choose PB0 or PA4 as source of interrupt_Src1 in PADAUK_CODE_OPTION. Similarly, when using the PB5 as external interrupt pin, the setting method of **inten/intrq/integs** registers are same as that of PA0, the only difference is to choose PA0 or PB5 as source of interrupt_Src0 in PADAUK_CODE_OPTION.

9.2.3 System clock switching

(1) System clock can be switched by CLKMD register. Please notice that, NEVER switch the system clock and turn off the original clock source at the same time. For example: When switching from clock A to clock B, please switch to clock B first; and after that turn off the clock A oscillator through CLKMD.

◆ Case 1 : Switch system clock from ILRC to IHRC/2

```
CLKMD = 0x36;    // switch to IHRC, ILRC can not be disabled here
```

```
CLKMD.2 = 0;    // ILRC can be disabled at this time
```

- ◆ Case 2 : Switch system clock from ILRC to EOSC

```
CLKMD = 0xA6;           // switch to EOSC, ILRC can not be disabled here
```

```
CLKMD.2 = 0;           // ILRC can be disabled at this time
```

- ◆ **ERROR.** Switch ILRC to IHRC and turn off ILRC simultaneously

```
CLKMD = 0x50;          // MCU will hang
```

(2) Please ensure the EOSC oscillation has established before switching from ILRC or IHRC to EOSC. MCU will not check its status. Please wait for a while after enabling EOSC. System clock can be switched to EOSC afterwards. Otherwise, MCU will hang. The example for switching system clock from ILRC to 4MHz EOSC after boot up is as below:

```
.ADJUST_IC  SYSCLK=ILRC;
$ EOSCR    Enable, 4MHz;           // 4MHz EOSC start to oscillate.
                                           // delay time to wait crystal oscillator stable

$ T16M EOSC, /1, BIT10
Word Count = 0;
Stt16 Count;
Intrq.T16 = 0;
do
{ nop; }while(!Intrq.T16);
CLKMD = 0xA4;                       // ILRC -> EOSC;
CLKMD.2 = 0;                         // turn off ILRC only if necessary
```

The delay duration should be adjusted in accordance with the characteristic of the crystal and PCB. To measure the oscillator signal by the oscilloscope, please select (x10) on the probe and measure through PA6(X2) pin to avoid the interference on the oscillator.

9.2.4 Watchdog

Watchdog will be inactive once ILRC is disabled.

9.2.5 TIMER time out

When select \$ INTEGS BIT_R (default value) and T16M counter BIT8 to generate interrupt, if T16M counts from 0, the first interrupt will occur when the counter reaches to 0x100 (BIT8 from 0 to 1) and the second interrupt will occur when the counter reaches 0x300 (BIT8 from 0 to 1). Therefore, selecting BIT8 as 1 to generate interrupt means that the interrupt occurs every 512 counts. Please notice that if T16M counter is restarted, the next interrupt will occur once Bit8 turns from 0 to 1.

If select \$ INTEGS BIT_F (BIT triggers from 1 to 0) and T16M counter BIT8 to generate interrupt, the T16M counter changes to an interrupt every 0x200/0x400/0x600/. Please pay attention to two differences with setting INTEGS methods.

9.2.6 IHRC

- (1) The IHRC frequency calibration is performed when IC is programmed by the writer.
- (2) Because the characteristic of the Epoxy Molding Compound (EMC) would some degrees affects the IHRC frequency (either for package or COB), if the calibration is done before molding process, the actual IHRC frequency after molding may be deviated or becomes out of spec. Normally , the frequency is getting slower a bit.
- (3) It usually happens in COB package or Quick Turnover Programming (QTP). And PADAUK would not take any responsibility for this situation.
- (4) Users can make some compensatory adjustments according to their own experiences. For example, users can set IHRC frequency to be 0.5% ~ 1% higher and aim to get better re-targeting after molding.

9.2.7 LVR

- (1) V_{DD} must reach or above 2.0V for successful power-on process; otherwise IC will be inactive.
- (2) The setting of LVR (1.8V, 2.0V, 2.2V etc.) will be valid just after successful power-on process.
- (3) User can set MISC.2 as “1” to disable LVR. However, V_{DD} must be kept as exceeding the lowest working voltage of chip; Otherwise IC may work abnormally.

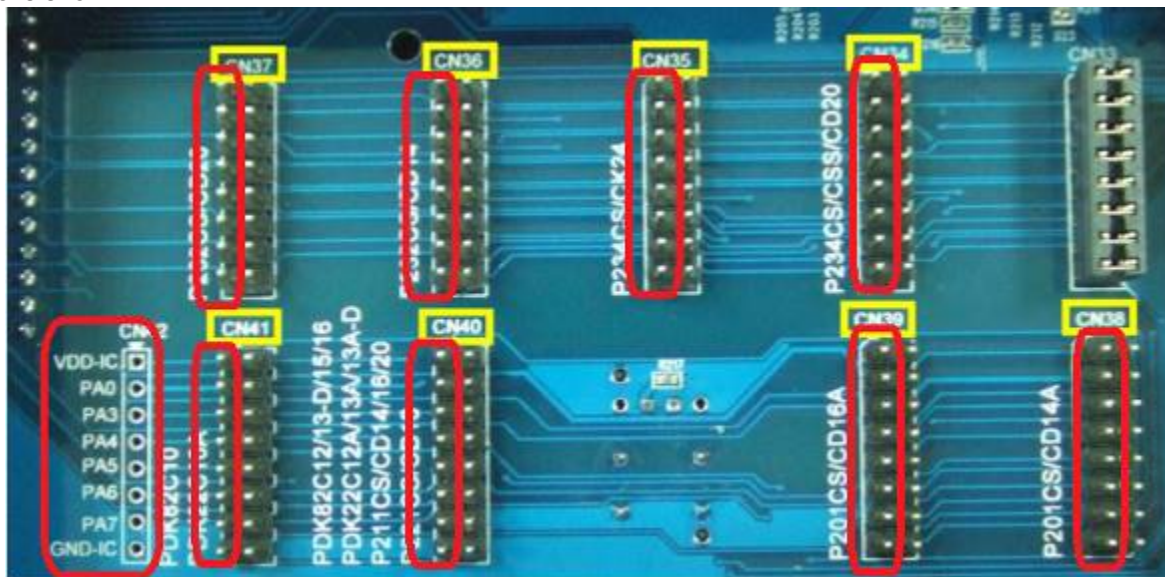
9.2.8 The result of Comparator controls the PWM output pins

The special function of GPC_PWM in PADAUK_CODE_OPTION is used to control the output pins of PWM modules including TM2, TM3 and PWMG0 / PWMG1 / PWMG2 according to the status of gpcc.6. Any output pins of those PWM modules will go to 0 when gpcc.6 is 1 and go back to normal PWM function when gpcc.6 is 0.

9.2.9 Programming the PMS132/PMS132B

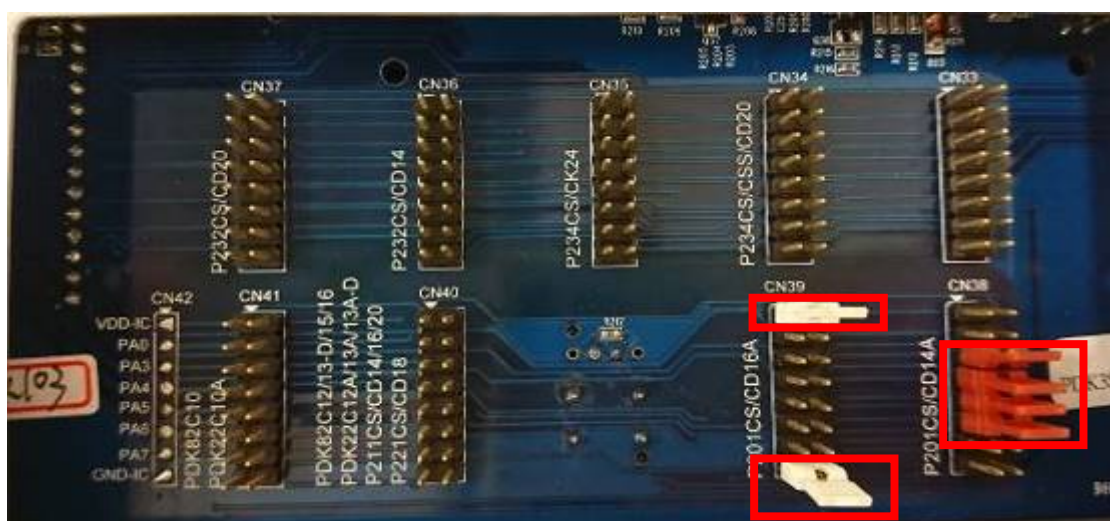
There are 6 pins for using the writer to program: PA3, PA4, PA5, PA6, V_{DD} , and GND.

Please use PDK3S-P-002 to program and put the PMS132/PMS132B-S16A /S14 to move down three spaces over the CN38. Other packages could be programmed by user's way. All the left signs behind the jumper are the same (there are V_{DD} , PA0(not required), PA3, PA4, PA5, PA6, PA7(not required), and GND).The following picture is shown:



If user uses PDK5S-P-002 or above to program, please follow the instruction.

Please use the following way when using the PMS132/PMS132B-S08:



- Special notes about voltage and current while Multi-Chip-Package(MCP) or On-Board Programming
 - (1) PA5 (V_{PP}) may be higher than 11V.
 - (2) V_{DD} may be higher than 6.5V, and its maximum current may reach about 20mA.
 - (3) All other signal pins level (except GND) are the same as V_{DD} .

User should confirm when using this product in MCP or On-Board Programming, the peripheral circuit or components will not be destroyed or limit the above voltages.

9.3 Using ICE

(1) It is recommended to use PDK5S-I-S01/2(B) for emulation of PMS132/PMS132B. PDK5S-I-S01/2(B) supports PMS132/PMS132B 1-FPPA MCU emulation work, the following items should be noted when using PDK5S-I-S01/2(B) to emulate PMS132/PMS132B:

- PDK5S-I-S01/2(B) doesn't support the instruction NADD/COMP of PMS132/PMS132B.
- PDK5S-I-S01/2(B) doesn't support SYSCLK=ILRC/16 of PMS132/PMS132B.
- PDK5S-I-S01/2(B) doesn't support the function TM2.GPCRS/TM3.GPCRS of PMS132/PMS132B.
- PDK5S-I-S01/2(B) doesn't support the function PWMG2C.PA5.
- PDK5S-I-S01/2(B) doesn't support the function ADCRGC.BG_2V/BG_3V/BG_4V, and fix BG_1V2 only.
- PDK5S-I-S01/2(B) doesn't support the code options: GPC_PWM, PWM_Source, and TMx_bit.
- The PA3 output function will be affected when GPCS selects output to PA0 output.
- When using PB1 in ADCRGC, PA1 must float.
- When simulating PWM waveform, please check the waveform during program running. When the ICE is suspended or single-step running, its waveform may be inconsistent with the reality.
- The ILRC frequency of the PDK5S-I-S01/2(B) simulator is different from the actual IC and is uncalibrated, with a frequency range of about 34K~38KHz.
- Fast Wakeup time is different from PDK5S-I-S01/2(B): 128 SYSCLK, PMS132/PMS132B: 45 ILRC
- Watch dog time out period is different from PDK5S-I-S01/2(B):

WDT period	PMS132/PMS132B	PDK5S-I-S01/2(B)
misc[1:0]=00	8K* T _{ILRC}	2048* T _{ILRC}
misc[1:0]=01	16K* T _{ILRC}	4096* T _{ILRC}
misc[1:0]=10	64K* T _{ILRC}	16384* T _{ILRC}
misc[1:0]=11	256K* T _{ILRC}	256* T _{ILRC}