Advanced Lane Finding

Meets Specifications

Congratulations, your project meets all specifications!

I've enjoyed very much reviewing your project, you can be proud of the hard work you've done!

Keep learning and stay ***Udacious***! :D

Writeup / README

The writeup / README should include a statement and supporting figures / images that explain how each rubric item was addressed, and specifically where in the code each step was handled.
The provided README file includes a very detailed step by step explanation covering each rubric point, the provided examples images are very explanatory providing a quicker idea on how is the pipeline working. Very good job!

Camera Calibration

OpenCV functions or other methods were used to calculate the correct camera matrix and distortion coefficients using the calibration chessboard images provided in the repository (note these are 9x6 chessboard images, unlike the 8x6 images used in the lesson). The distortion matrix should be used to un-distort one of the calibration images provided as a demonstration that the calibration is correct. Example of undistorted calibration image is Included in the writeup (or saved to a folder).