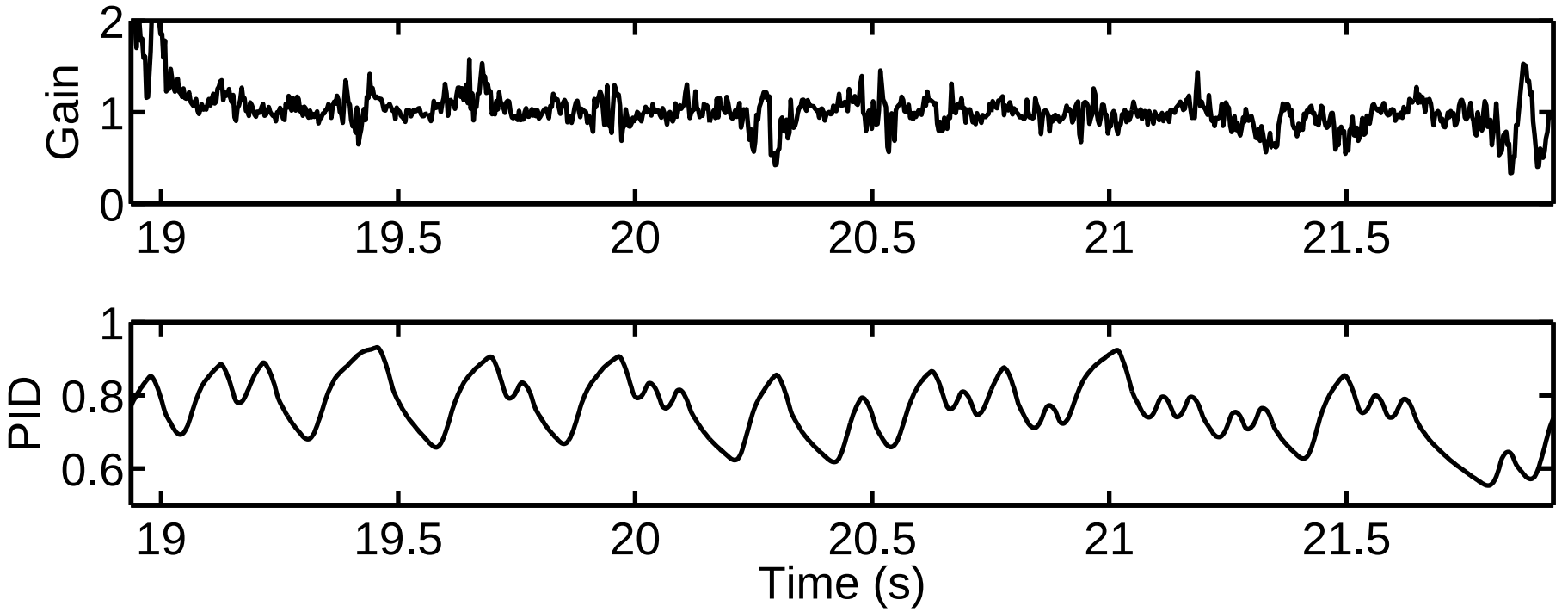
Gain
2
1
0
19
19.5
20
20.5
21
21.5
PID
1
0.8
0.6
19
19.5
20
20.5
21
21.5
Time (s)