

# SHENAO ZHANG

1087 Westshire Place 30318, Atlanta, Georgia.  
shenao@gatech.edu | <https://shenao-zhang.github.io>

## EDUCATION

---

<b>Georgia Institute of Technology</b> M.S. in ECE, GPA: 3.88/4.00	<i>May 2020 - Present</i>
<b>Georgia Institute of Technology</b> M.S. in CSE, GPA: 4.00/4.00	<i>January 2021 - Present</i>
<b>South China University of Technology</b> B.Eng. in EE (information engineering innovation class)	<i>August 2016 - May 2020</i>
<b>University of California, Berkeley</b> Visiting student at Department of EECS, GPA: 3.90/4.00	<i>January 2019 - May 2019</i>

## RESEARCH INTERESTS

---

Reinforcement learning, robotics and the analysis of machine learning algorithms from stochastic and Bayesian perspectives.

## PUBLICATIONS

---

- [1] **Shenao Zhang**. Dual Conservative Policy Update for Efficient Model-Based Reinforcement Learning. Under review at *Neural Information Processing Systems (NeurIPS)*, 2021. [Full paper](#).
- [2] **Shenao Zhang**, Li Shen, Lei Han, Li Shen. Learning Meta Representation for Agents in Multi-Agent Reinforcement Learning. Under review at *Neural Information Processing Systems (NeurIPS)*, 2021. [Arxiv paper](#).
- [3] **Shenao Zhang**, Li Shen, Zhifeng Li, Wei Liu. Structure-Regularized Attention for Deformable Object Representation. Accepted at *Advances in Neural Information Processing Systems (NeurIPS) Workshop*, 2020. [Paper website](#) and [full paper](#).

## RESEARCH EXPERIENCE

---

<b>Tencent AI Lab</b> Research Intern. Advisors: Li Shen, Lei Han and Li Shen	<i>August 2019 - August 2020</i> Shenzhen, China
<b>Columbia University</b> Research Assistant. Advisor: Bo Wu	<i>May 2019 - August 2019</i> New York, NY
<b>South China University of Technology</b> Research Assistant. Advisors: Huabiao Qin and Mingkui Tan	<i>September 2017 - January 2019</i> Guangzhou, China

## SELECTED PROJECTS

---

<b>Object Detection</b> <a href="#">Project paper</a> , advised by Bo Wu	<i>May 2019 - October 2019</i> Columbia University, New York
<b>Computer Graphics</b> Advisors: Ren Ng and Jonathan Ragan-Kelley <ul style="list-style-type: none"><li>• Final project: Cloth Simulation using OpenGL Shader, <a href="#">project website</a></li><li>• Projects of Rasterizer, MeshEdit, PathTracer, Physical Simulation, code and reports can be found <a href="#">here</a></li></ul>	<i>January 2019 - May 2019</i> University of California, Berkeley
<b>Gaze Tracking in Natural Light</b> <a href="#">Project paper</a> , accepted at <i>International Conference on Control and Automation (ICCA)</i> , 2019	<i>October 2017 - October 2018</i>

## RELEVANT COURSES

---

**Undergraduate courses:** Computer Graphics (CS 184 at UC Berkeley), Intro to AI (CS 188 at UC Berkeley), Algorithms (CS 170 at UC Berkeley), Machine Perception, Information Theory, Deep Learning.  
**Graduate courses at Georgia Tech:** Linear Systems and Controls (ECE 6550), Nonlinear Systems and Control (ECE 6552), Optimal Control and Optimization (ECE 6553), Statistical Machine Learning (ECE 6254), Autonomous Control of Robotic Systems (ECE 6562),

## TEACHING

---

**Graduate Teaching Assistant:** Head TA of [CS 7648: Interactive Robot Learning](#) (Fall 2021) at Georgia Tech.

## PROFESSIONAL ACTIVITIES

---

**Conference Review:** NeurIPS 2020, NeurIPS 2021, ICLR 2021, RSS 2021.

**Journal Review:** Neurocomputing.

## HONORS AND REWARDS

---

Second Prize in 2018 Undergraduate Electronics Design Contest	<i>2018</i>
Third Prize in 2018 Intel Undergraduate Embedded System Contest	<i>2018</i>
Outstanding Freshmen Scholarships (Awarded to 30 among 6,500 students)	<i>2016</i>