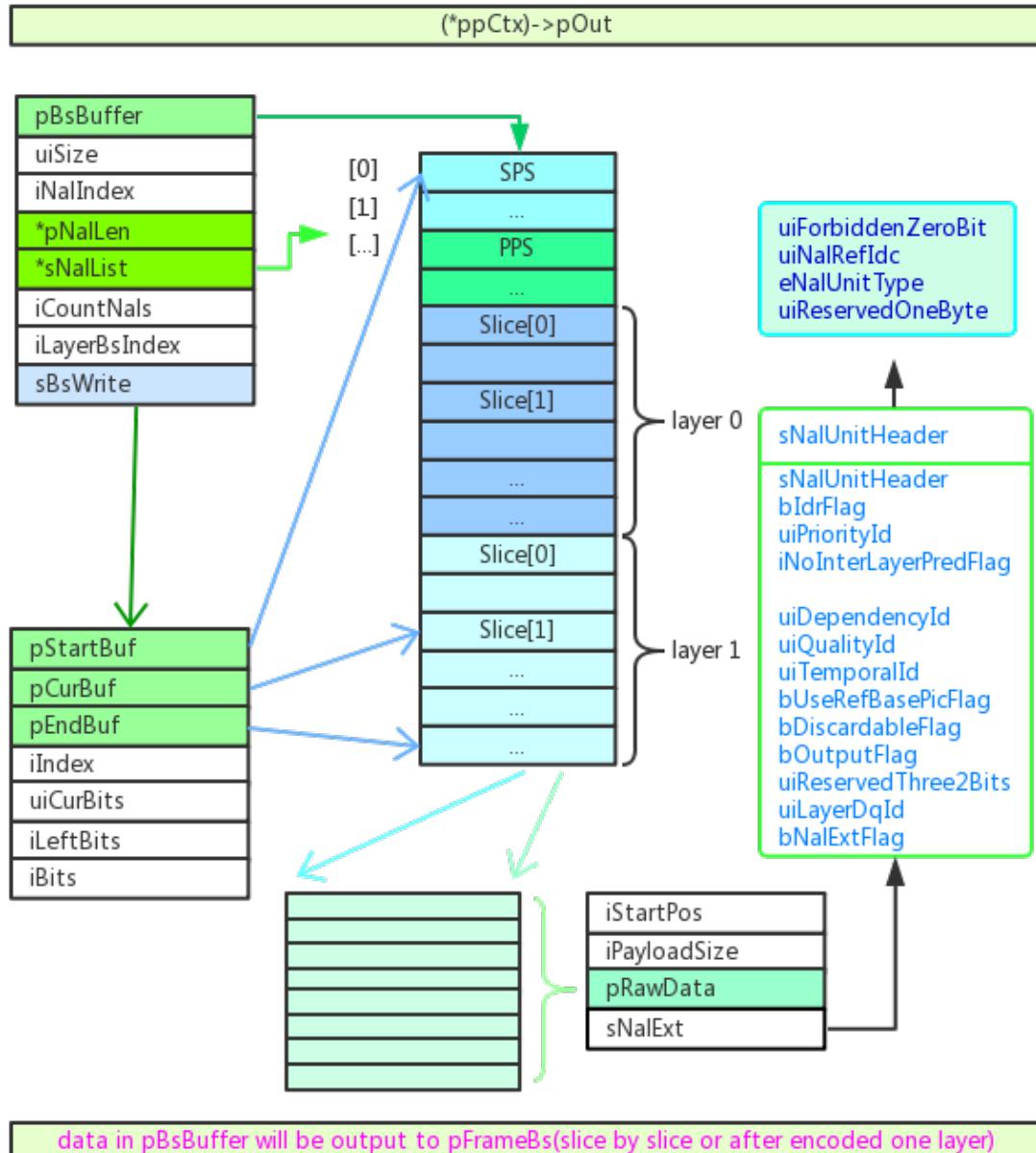


Slice buffer design

Table of Contents

1. OVERVIEW FOR NEW DESIGN	3
.1. ORIGIN DESIGN.....	3
<i>1.1.1. Single thread.....</i>	<i>3</i>
<i>1.1.2. Multi thread</i>	<i>4</i>
I.....	4
1.2 NEW DESIGN IN REVIEW.....	5
<i>1.2.1 Single thread</i>	<i>5</i>
<i>1.2.2. Multi-thread.....</i>	<i>6</i>
2. SLICE BUFFER AND THREAD.....	7
2.1 BEFORE ENCODING ONE LAYER.....	7
2.2 NORMAL CASE FOR THREAD INDEX AND SLICE BUFFER INDEX	9
2.3 SLICE NUM NOT THE SAME AMONG THREADS	10
2.4 DIFFERENT THREAD INDEX IN THE SAME SLICE BUFFER	12
2.5. SLICE INDEX OUT-OF-ORDER CASE.....	13
2.6. DYNAMIC SLICE MODE CASE1	14
2.7. DYNAMIC SLICE MODE CASE2	15
3. SLICE BUFFER INIT/UPDATE/REORDER.....	16
3.1. ALLOCATE AND INITIAL BEFORE ENCODE FIRST IDR.....	16
3.2 SLICE BUFFER INFO BEFORE ENCODER ONE LAYER.....	17
<i>3.3.1 basic flow chart for encoding one slice task</i>	<i>18</i>
<i>3.3.2 Task manager.....</i>	<i>19</i>
<i>3.3.3. InitTask before encode one slice</i>	<i>20</i>
<i>3.3.4 Slice buffer update/reallocate during execute task</i>	<i>21</i>
3.4. SLICE BUFFER UPDATE AFTER ENCODER ONE LAYER	22
<i>3.4.1. ppSliceInLayer update: extend and reallocate ppSliceInLayer buffer,.....</i>	<i>22</i>
<i>ppSliceInLayer buffer num == All thread slice buffer num.....</i>	<i>22</i>
<i>3.4.2. Slice buffer reorder</i>	<i>23</i>
4. BS BUFFER DESIGN	25
4.1. SLICE Bs BUFFER.....	25
4.2. FRAME Bs BUFFER.....	26
4.3 PCTX-POUT	27



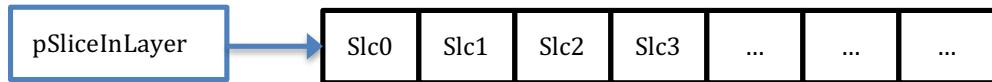
..... 27
 4.4. DYNAMIC SLICE, SLICE BOUNDARY STRATEGY 28

1. Overview for new design

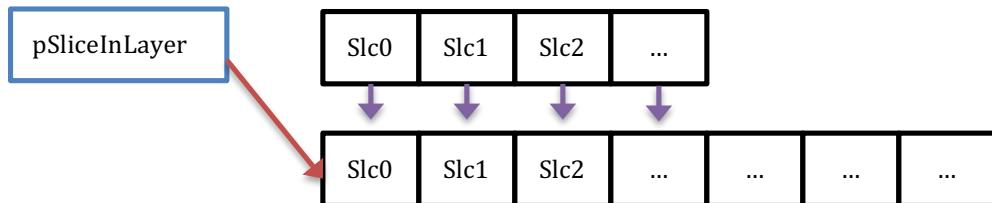
.1. Origin design

```
SSlice* pSliceInLayer // slice buffer for all slices in layer
```

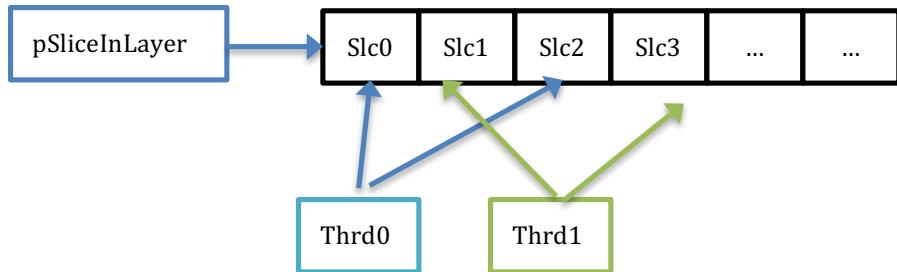
1.1.1. Single thread



realloc when current slice index larger than max slice num

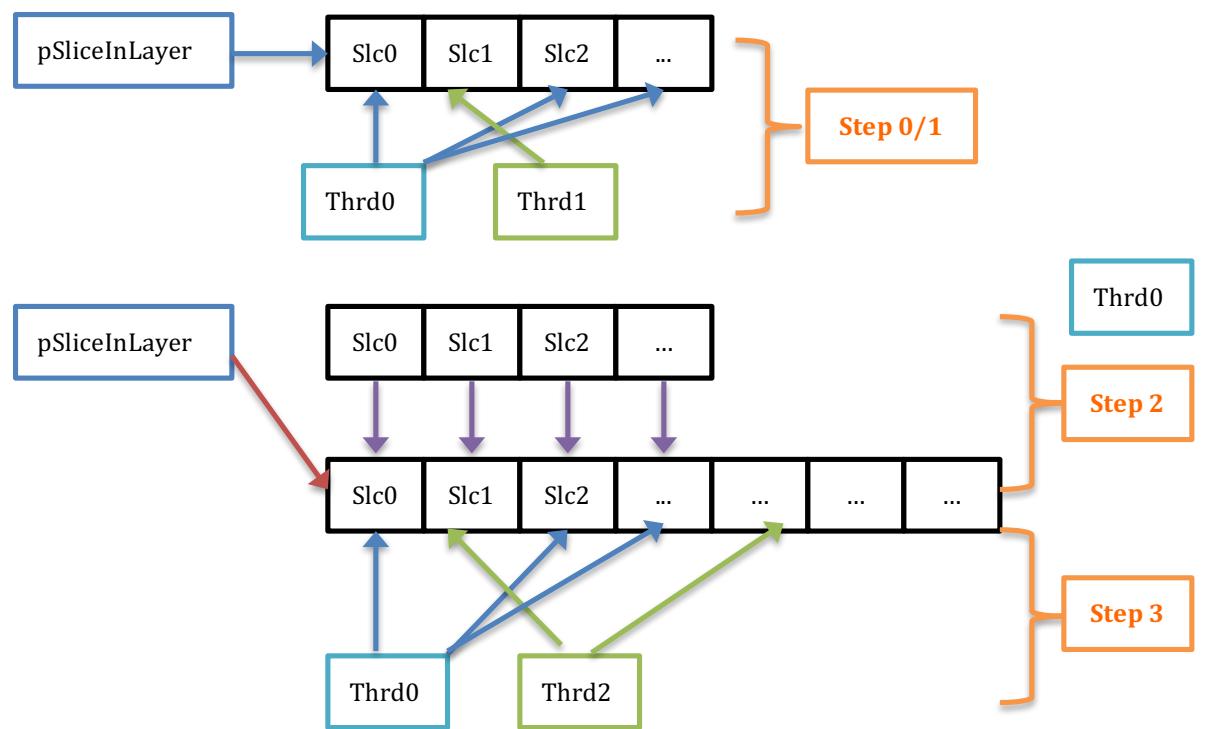


1.1.2. Multi thread



realloc when current slice index larger than max slice num ,

- step 0: thread[0] detect that current slice index larger than max slice num;
- step 1: thread[0] need to wait thread[1] completed current slice encoding task
- step 2: thread[1] stop slice encoding and thread[0] reallocate slice buffer,
- step 3: thread[0]/thread[1] start to encode new slice

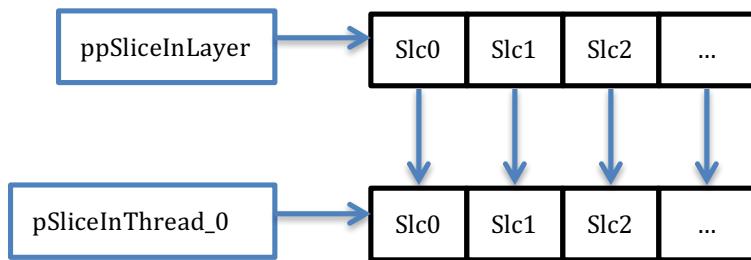


i.

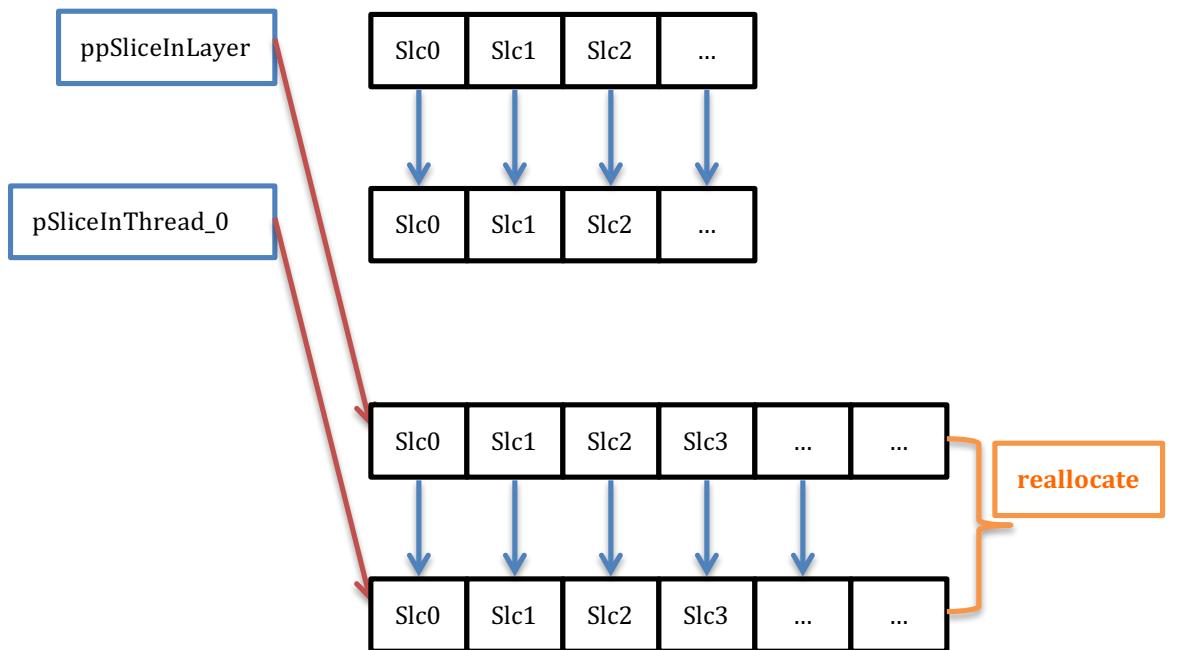
1.2 New design in review

```
SSlice** ppSliceInLayer;      // point to actual slice buffer
typedef struct TagSliceThreadInfo {
    SSlice*
    int32_t
    int32_t
}SSliceThreadInfo;
```

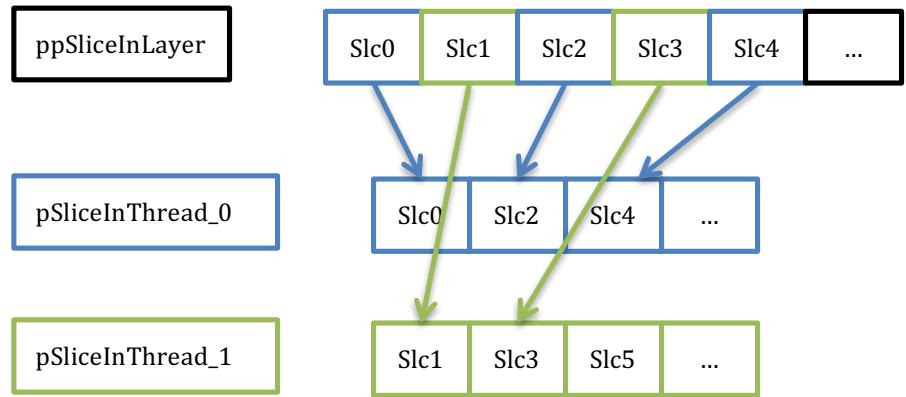
1.2.1 Single thread



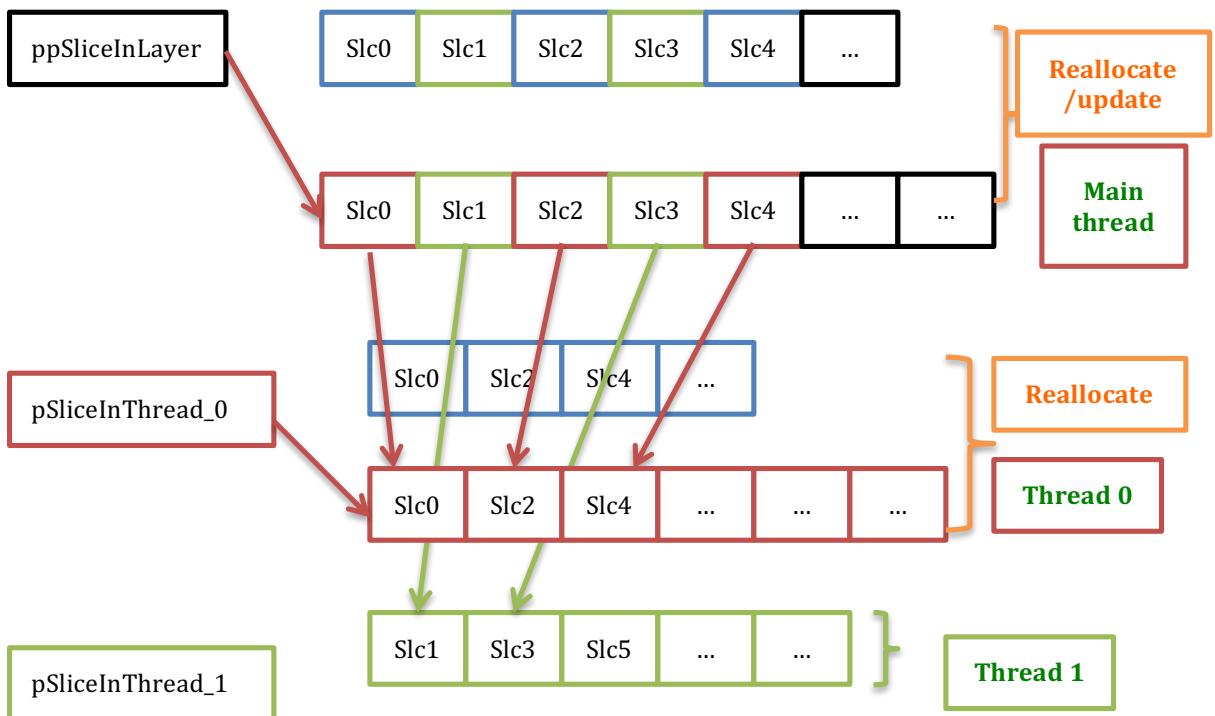
realloc when current slice index larger than max slice num



1.2.2. Multi-thread



for reallocate, each thread will do it independently, and will update `ppSliceInLayer` by **main thread** when all slices in layer are encoded.



2. SLICE BUFFER AND THREAD

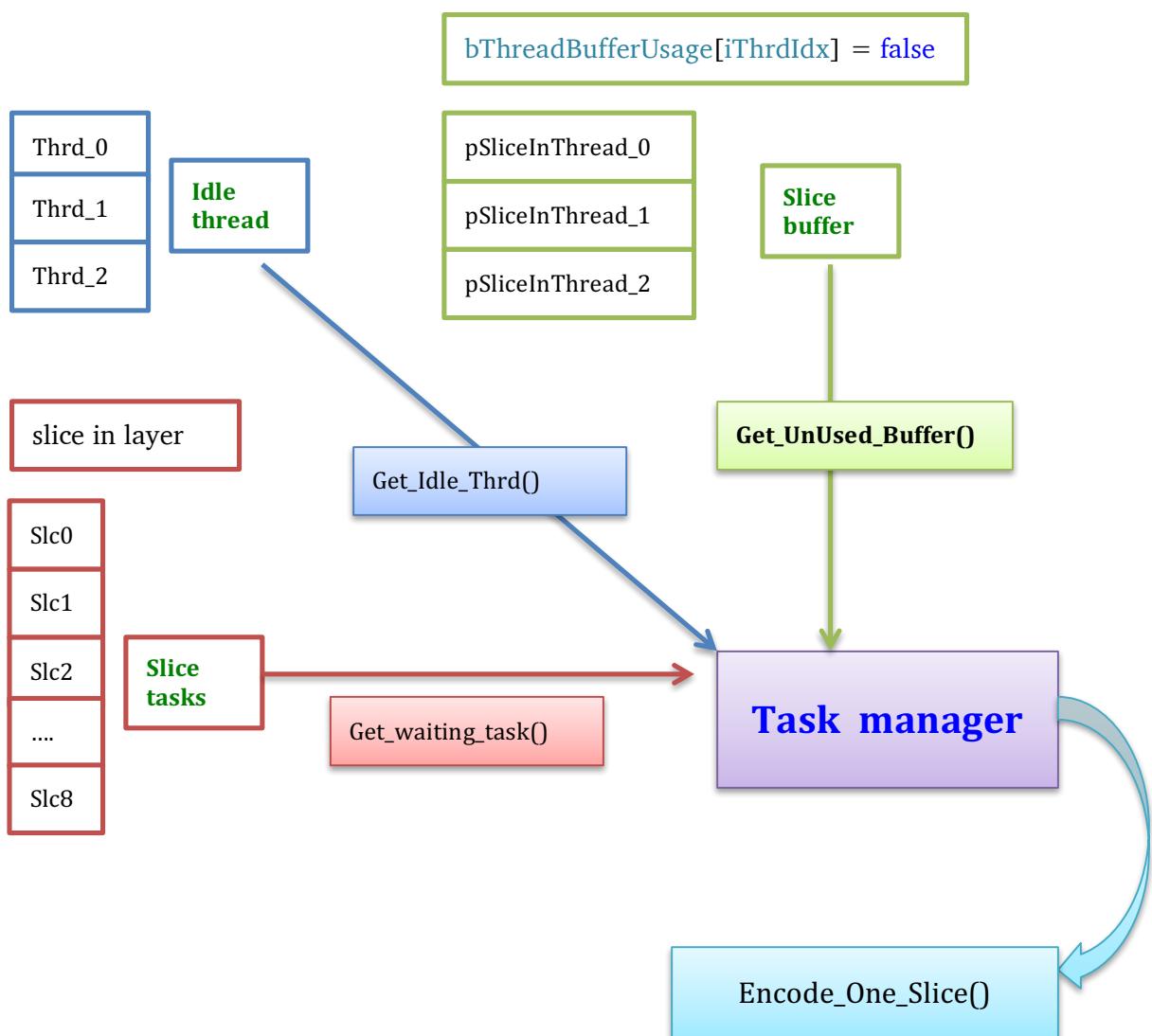
2.1 Before encoding one layer

the status of slice buffer and thread :

example:

thread: 3 threads

slices: 9 slices in layer



Query thread buffer function:

```
int32_t CWelsSliceEncodingTask::QueryEmptyThread (bool* pThreadBsBufferUsage) {  
    for (int32_t k = 0; k < MAX_THREADS_NUM; k++) {  
        if (pThreadBsBufferUsage[k] == false) {  
            pThreadBsBufferUsage[k] = true;  
            return k;  
        }  
    }  
    return -1;  
}
```

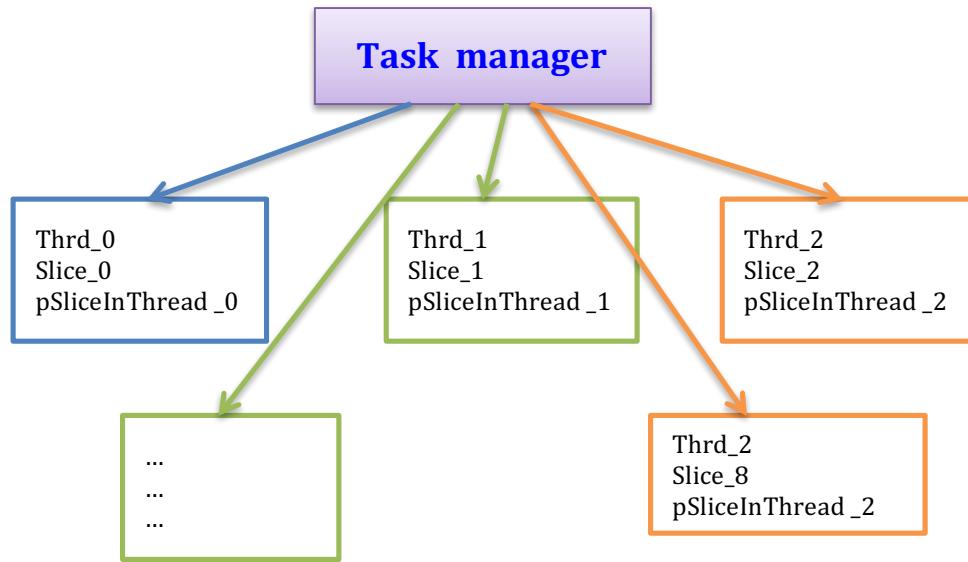
Example:

k=1, means that encode slice task using pSliceInThread_0 as slice buffer

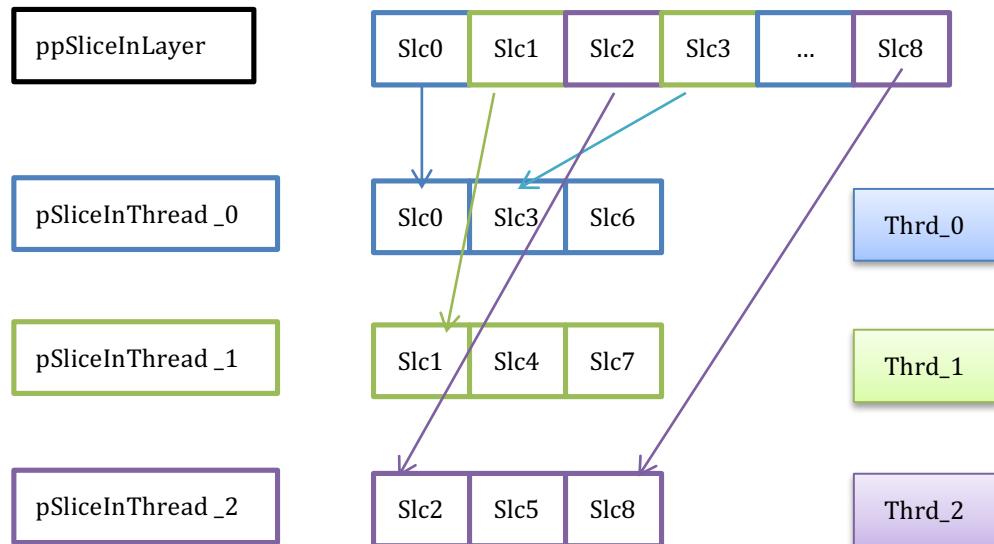
Query IDLE thread for slice task function:

```
CWelsTaskThread* CWelsThreadPool::GetIdleThread() {  
    CWelsAutoLock cLock (m_cLockIdleTasks);  
  
    if (m_cIdleThreads->size() == 0) {  
        return NULL;  
    }  
  
    CWelsTaskThread* pThread = m_cIdleThreads->begin();  
    m_cIdleThreads->pop_front();  
    return pThread;  
}
```

2.2. Normal case for thread index and slice buffer index

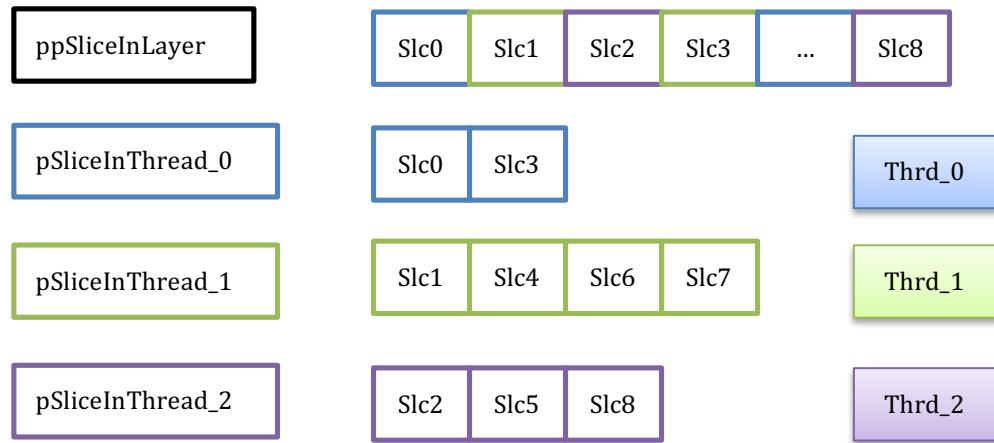


Final map for thread index and slice buffer index, slice index



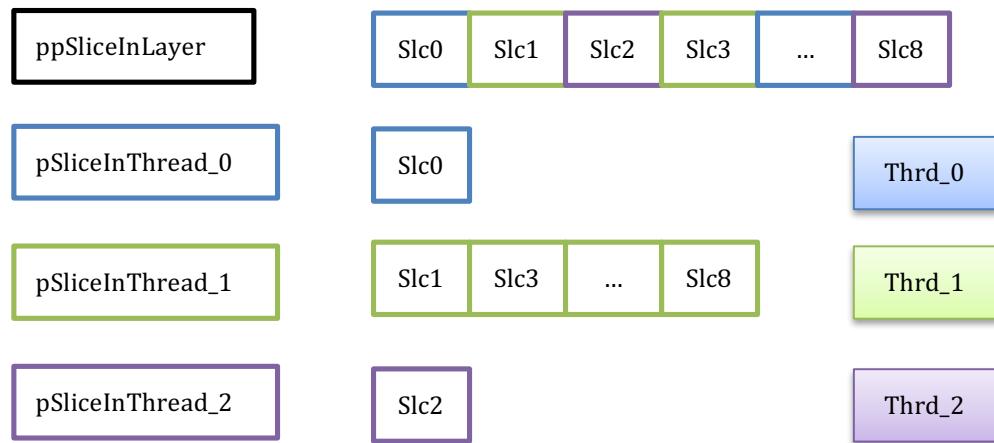
2.3. Slice num not the same among threads

case 1:



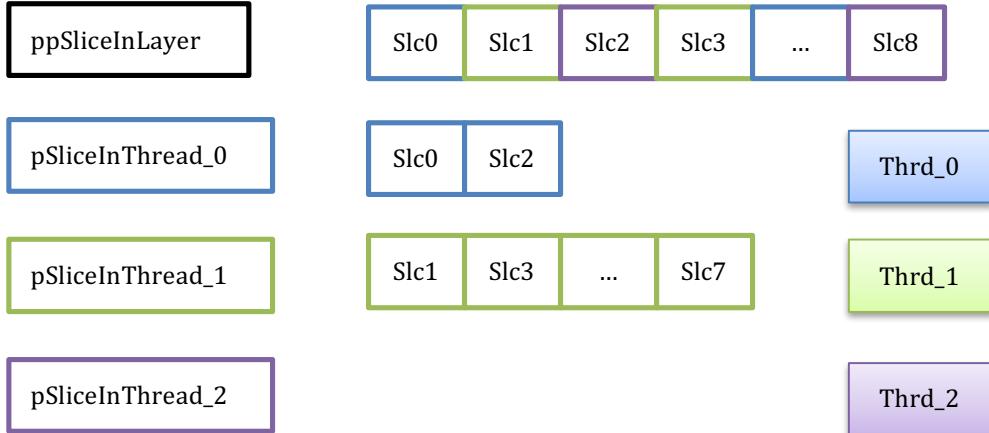
case 2:

encode time for Slc0 and Slc_2 are longer than Slc1, Slc3~Slc8



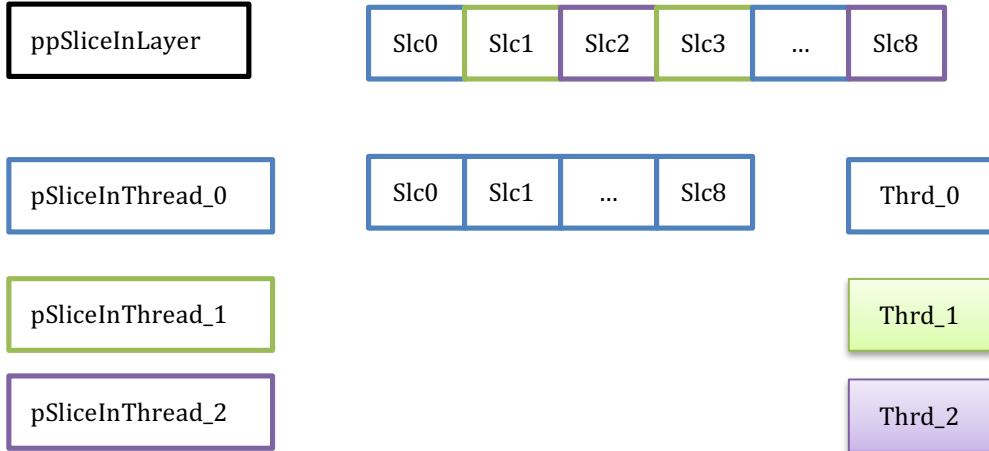
Corner case 1, no encoded slice for one thread:

Thread_0 and Thread_1 are fast enough and always get CPU resource,
Thread_2 is under waiting status/IDLE status.



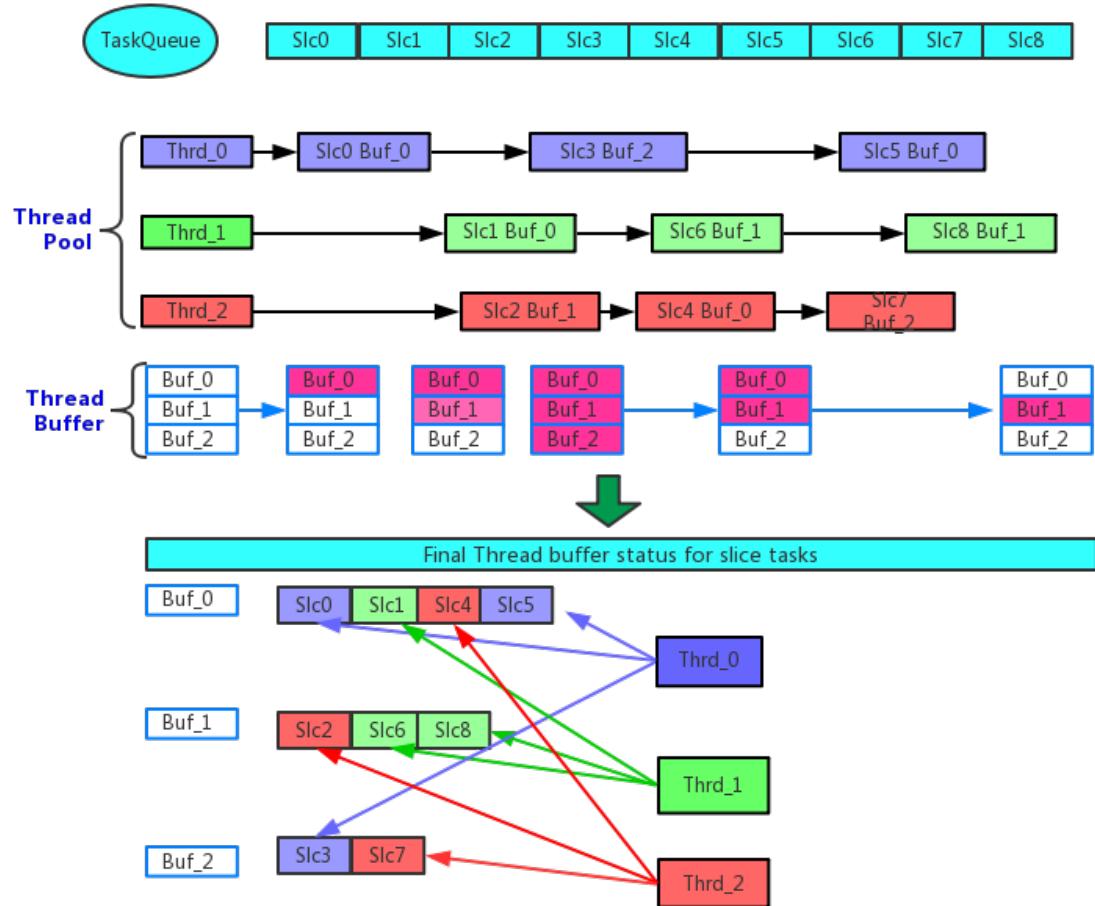
Corner case 2, all slices encoded by one thread :

Thread_0 is fast enough and always get CPU resource,
Thread_1 and Thread_2 are under waiting status/IDLE status.

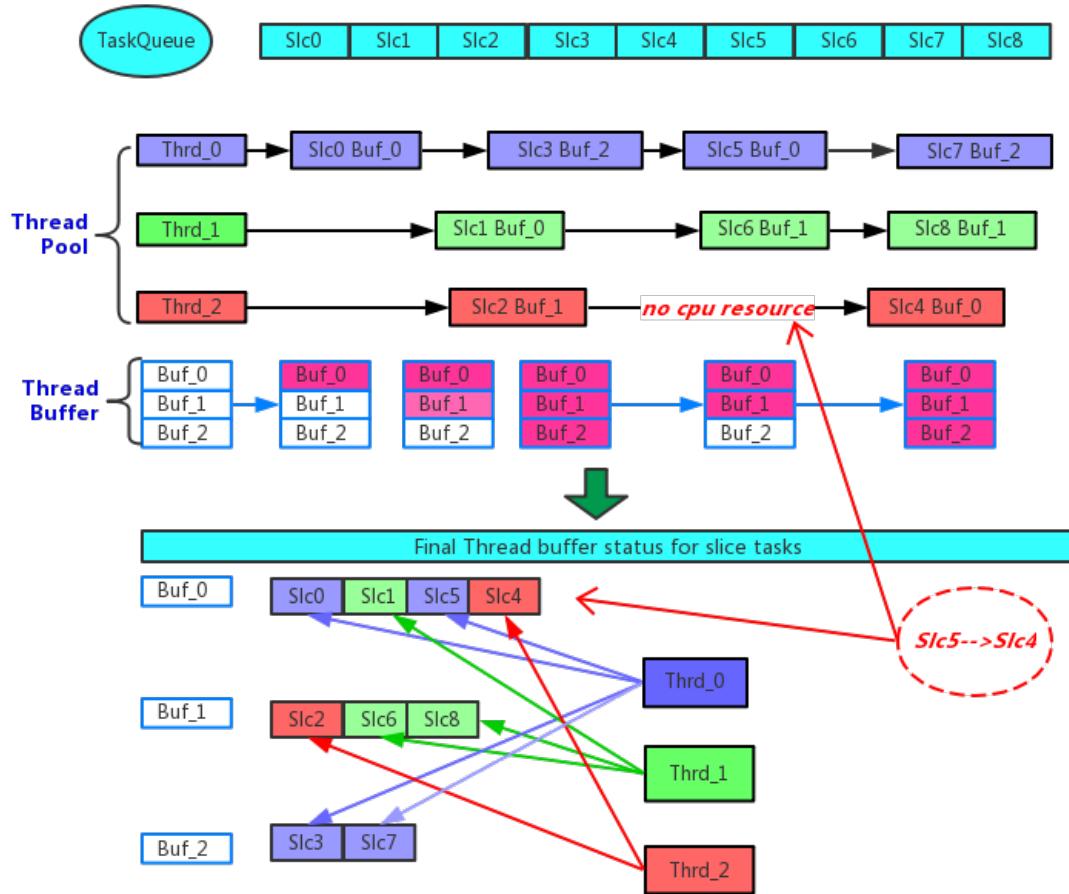


2.4. Different thread index in the same slice buffer

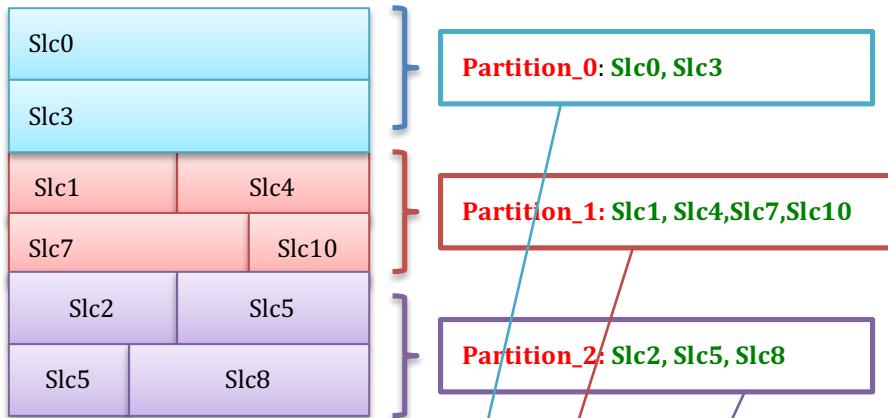
Timing diagram for Thread—SlcTask—ThreadBuffer



2.5. Slice index out-of-order case



2.6. Dynamic slice mode case1



$$\text{Slice_Index} = \text{PartitonID} + \text{Partition_Num} * \text{Slice_Index_InPartition}$$

$$\text{Example: } \text{Slc7} = 1 + 3 * 2$$

$$\text{Slc5} = 2 + 3 * 1$$

$$\text{Slice_Index_InLayer} = \text{PartitonOffset}[\text{Partiton_ID}] + \text{Slice_Index} / \text{Partition_Num}$$

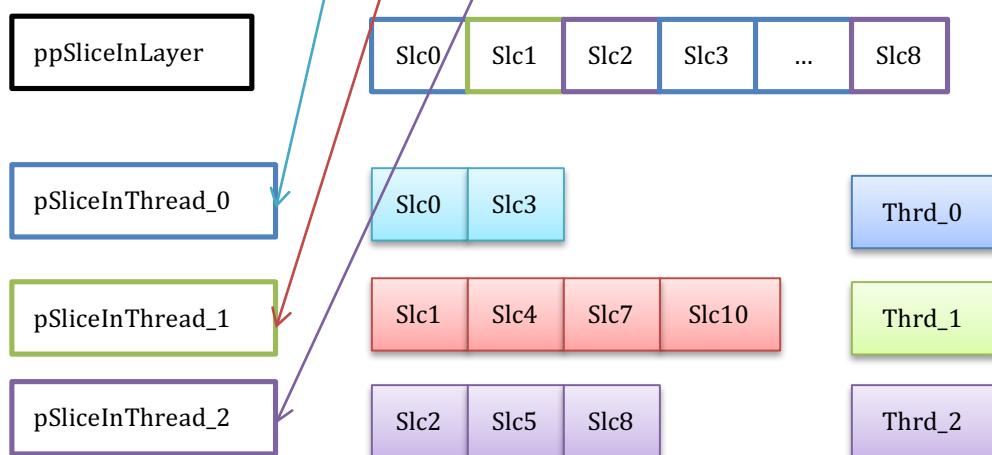
Here in example, PartitonOffset[0] = 0;

$$\text{PartitonOffset}[1] = 0 + 2 = 2;$$

$$\text{PartitonOffset}[2] = 0 + 2 + 4 = 6;$$

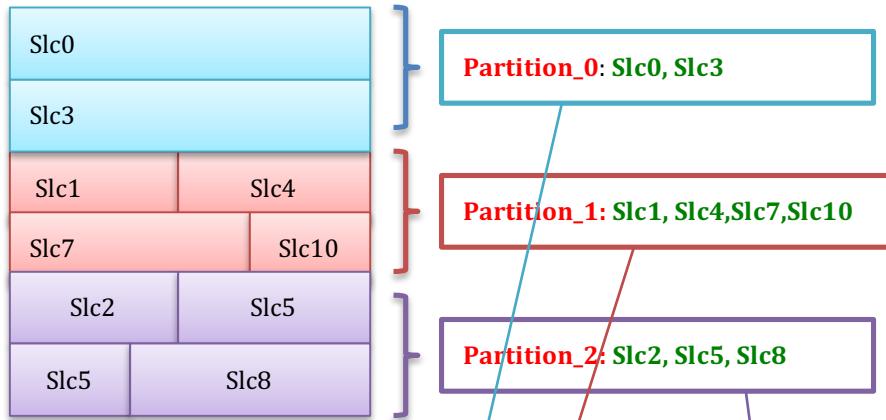
$$\text{Slc7} = \text{PartitonOffset}[1] + 7 / 3 = 2 + 2 = 4;$$

Which ppSliceInLayer[4] = Slc7



2.7. Dynamic slice mode case2

**Thread_0 encoded two partitions
while no partition for Thread_2**



$$\text{Slice_Index} = \text{PartitonID} + \text{Partition_Num} * \text{Slice_Index_InPartition}$$

$$\text{Example: } \text{Slc7} = 1 + 3 * 2$$

$$\text{Slc5} = 2 + 3 * 1$$

$$\text{Slice_Index_InLayer} = \text{PartitonOffset}[\text{Partiton_ID}] + \text{Slice_Index} / \text{Partition_Num}$$

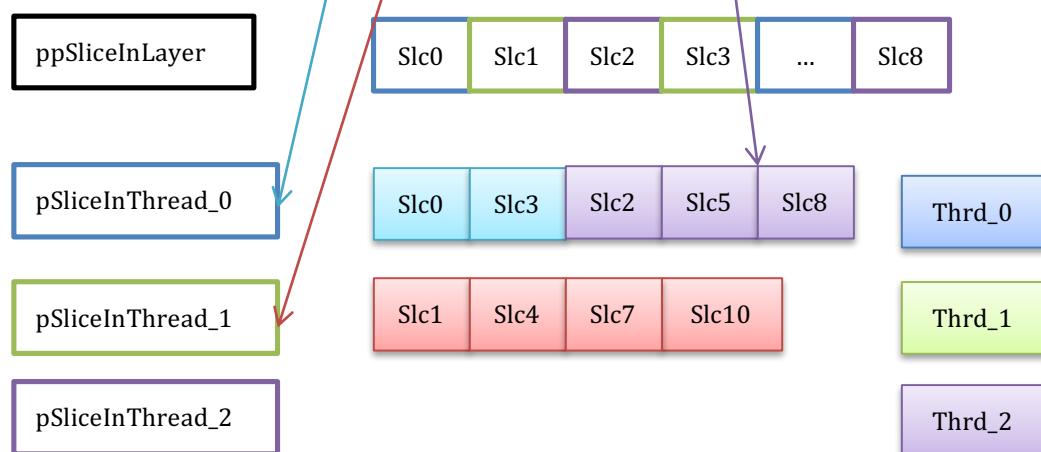
$$\text{Here in example, PartitonOffset[0] = 0;}$$

$$\text{PartitonOffset[1] = } 0 + 2 = 2;$$

$$\text{PartitonOffset[2] = } 0 + 2 + 4 = 6;$$

$$\text{Slc7} = \text{PartitonOffset[1]} + 7 / 3 = 2 + 2 = 4;$$

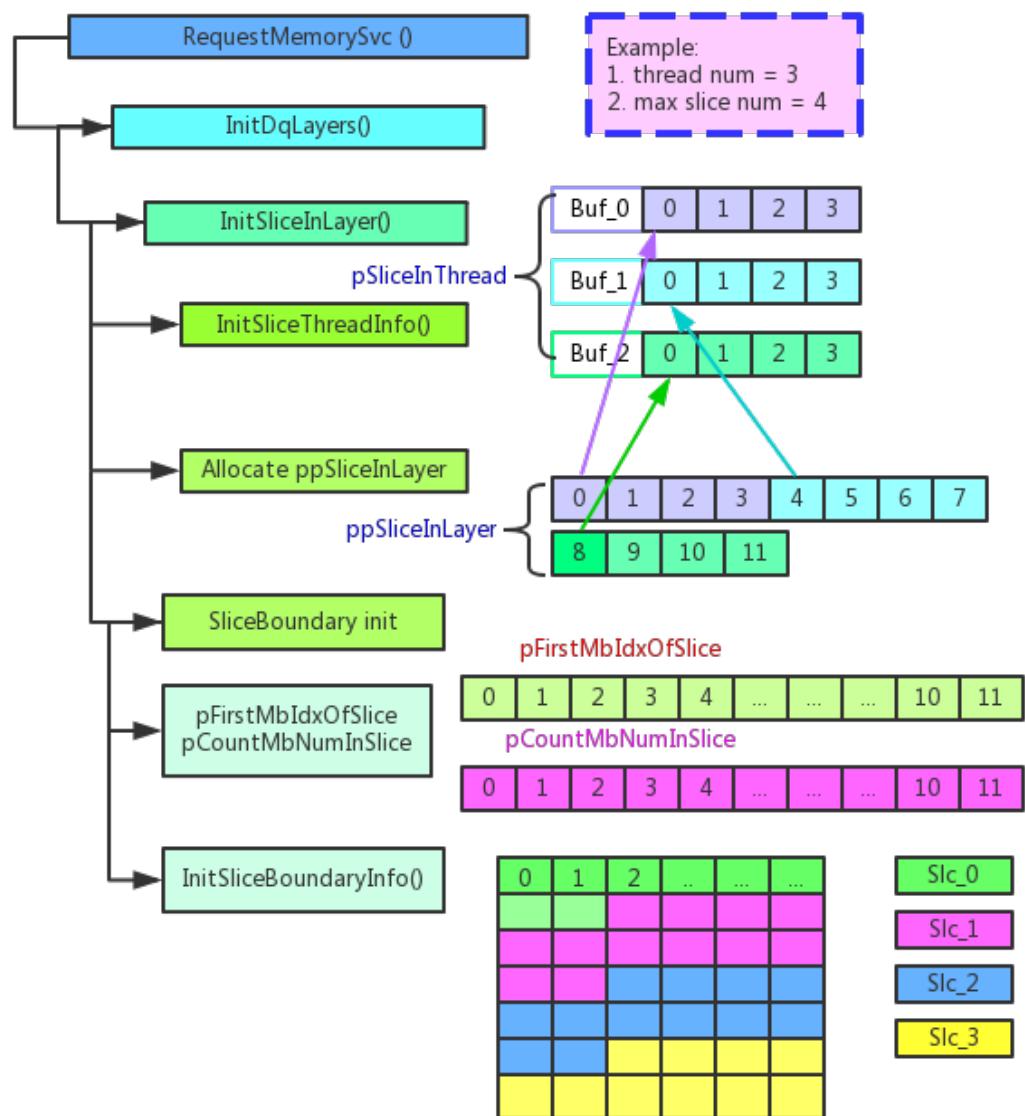
Which ppSliceInLayer[4] = Slc7



3. Slice Buffer Init/Update/Reorder

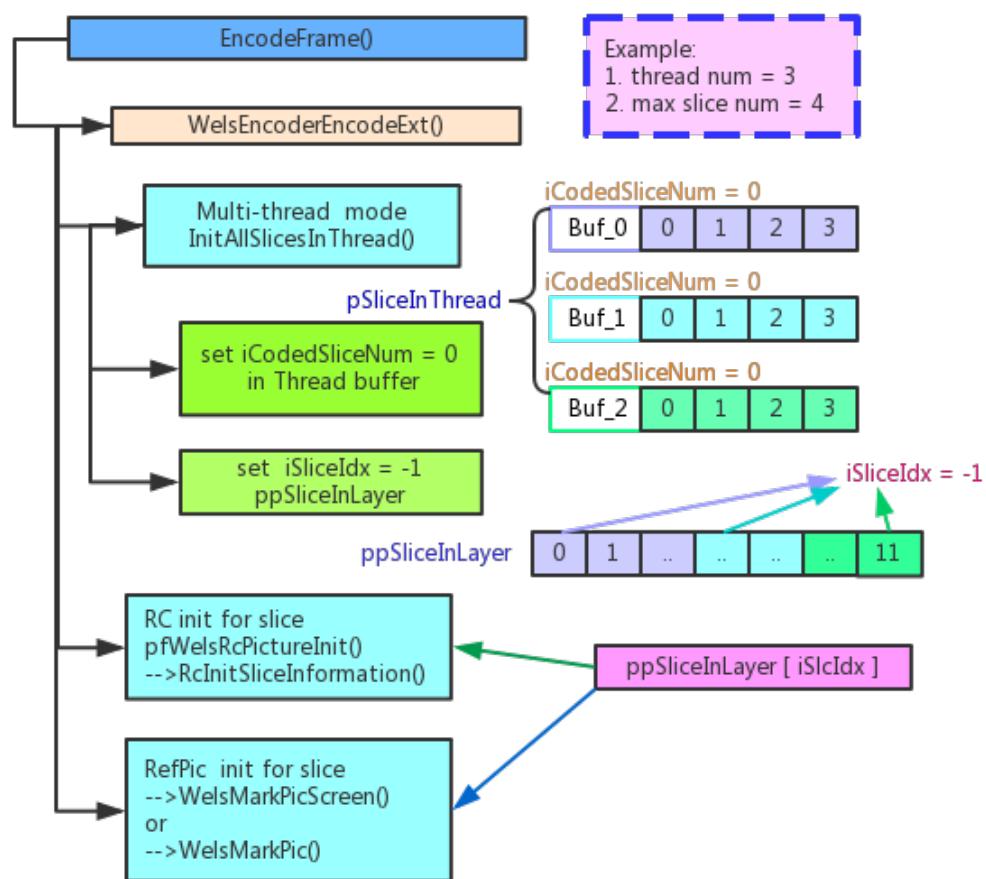
3.1. Allocate and initial before encode first IDR

- Allocate pSliceInThread buffer
- Allocate ppSliceInLayer buffer
- Allocate pFirstMbIdxOfSlice and pCountMbNumInSlice buffer
Init slice boundary info



3.2 Slice buffer info before encoder one layer

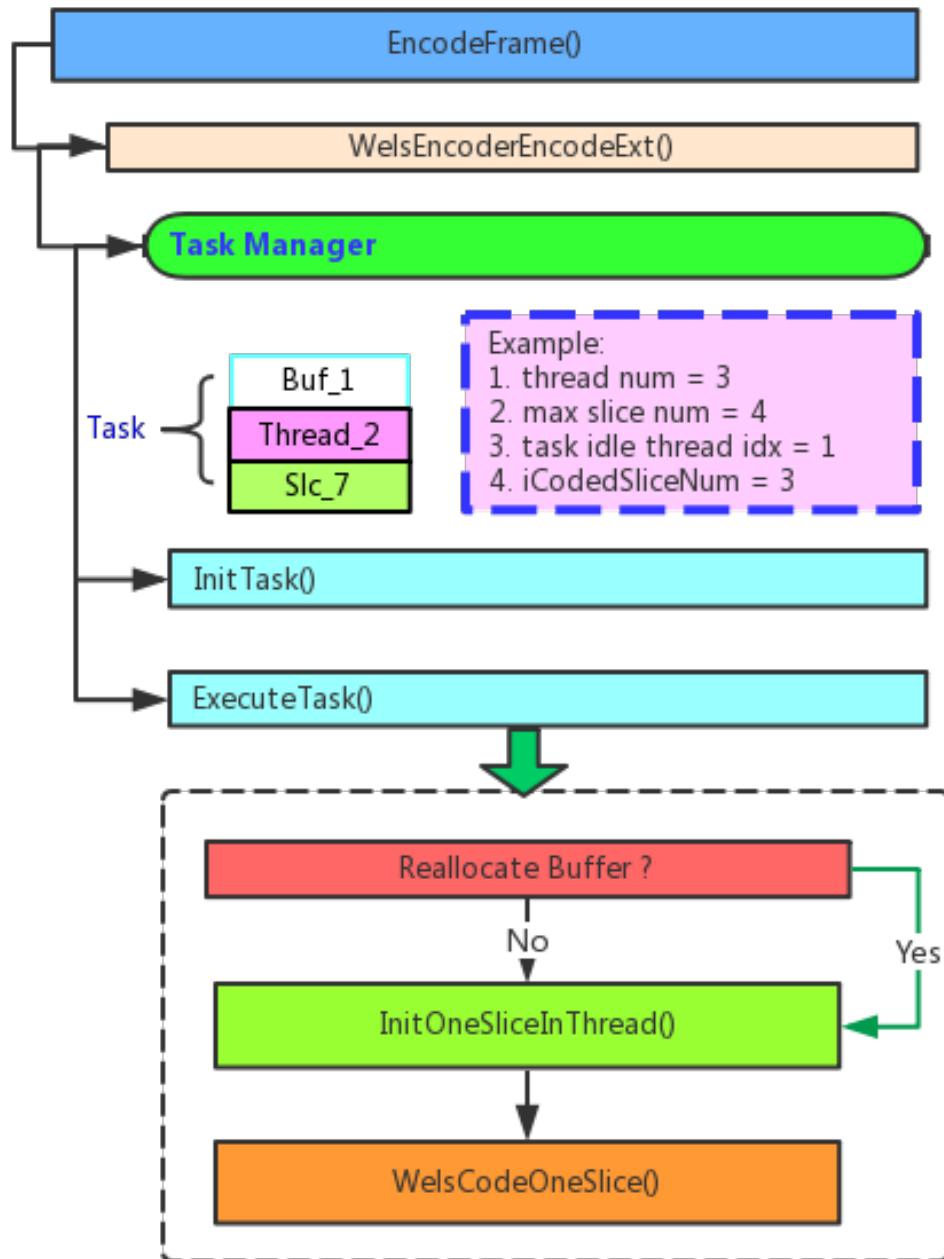
- Set iCodedSliceNum = 0 for all thread buffer
- Set iSliceIdx = -1 for all slice buffer (will set to actual slice idx during encoding one slice)
- Init RC info for all slice level parameters
- Init reference pic info for all slices using ppSliceInLayer[iSlcIdx]



3.3 Slice buffer init/update/reallocate during encoding one slice

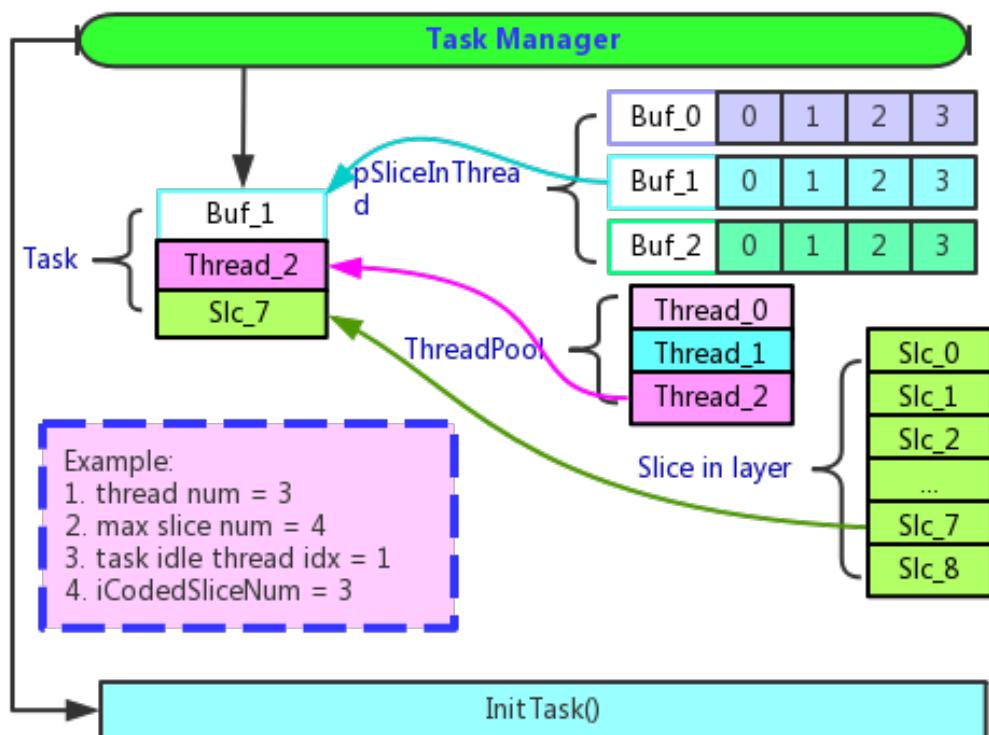
3.3.1 basic flow chart for encoding one slice task

- Task manager: Get idle thread, unused thread buffer, and encoding slice
- Init task: Init slice boundary info etc.
- Execute task: Encode one slice etc



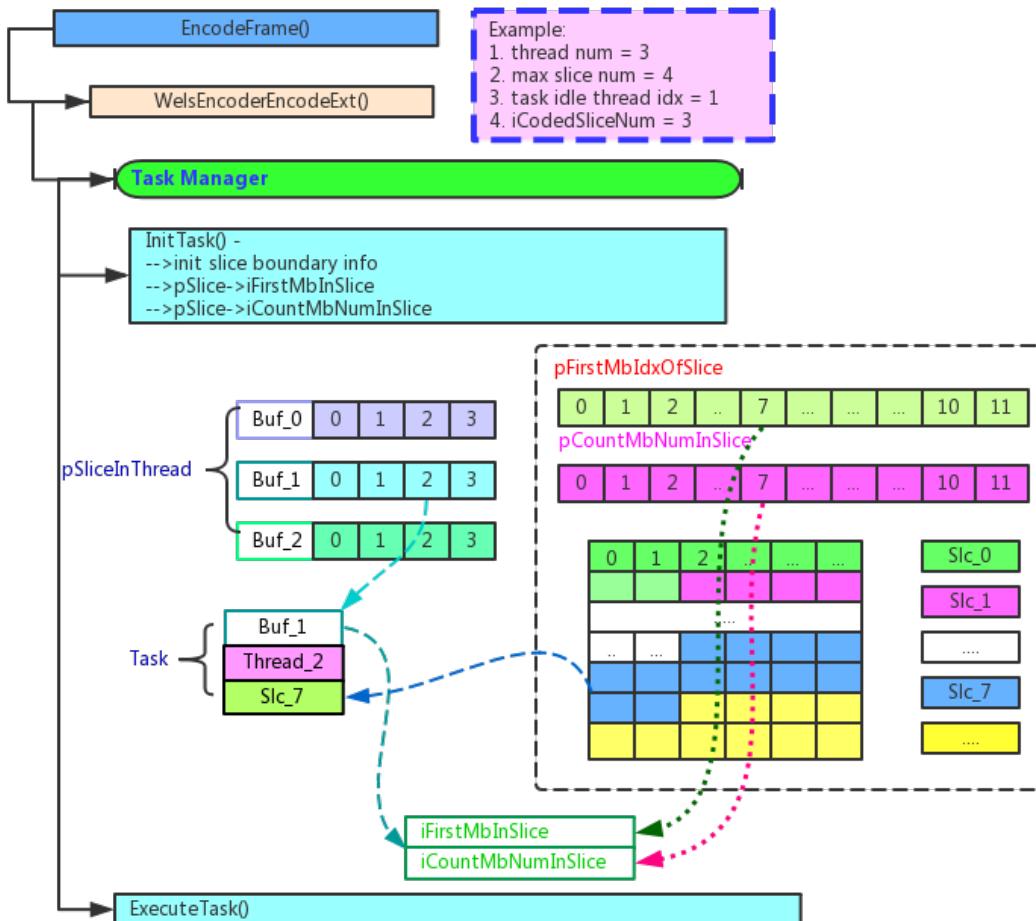
3.3.2 Task manager

- Get unused thread buffer, in this example, choose Buf_1 as slice buffer
- Get Idle thread, thread_2
- Get encode slice index in layer which will be encoded in this task, Slc_7



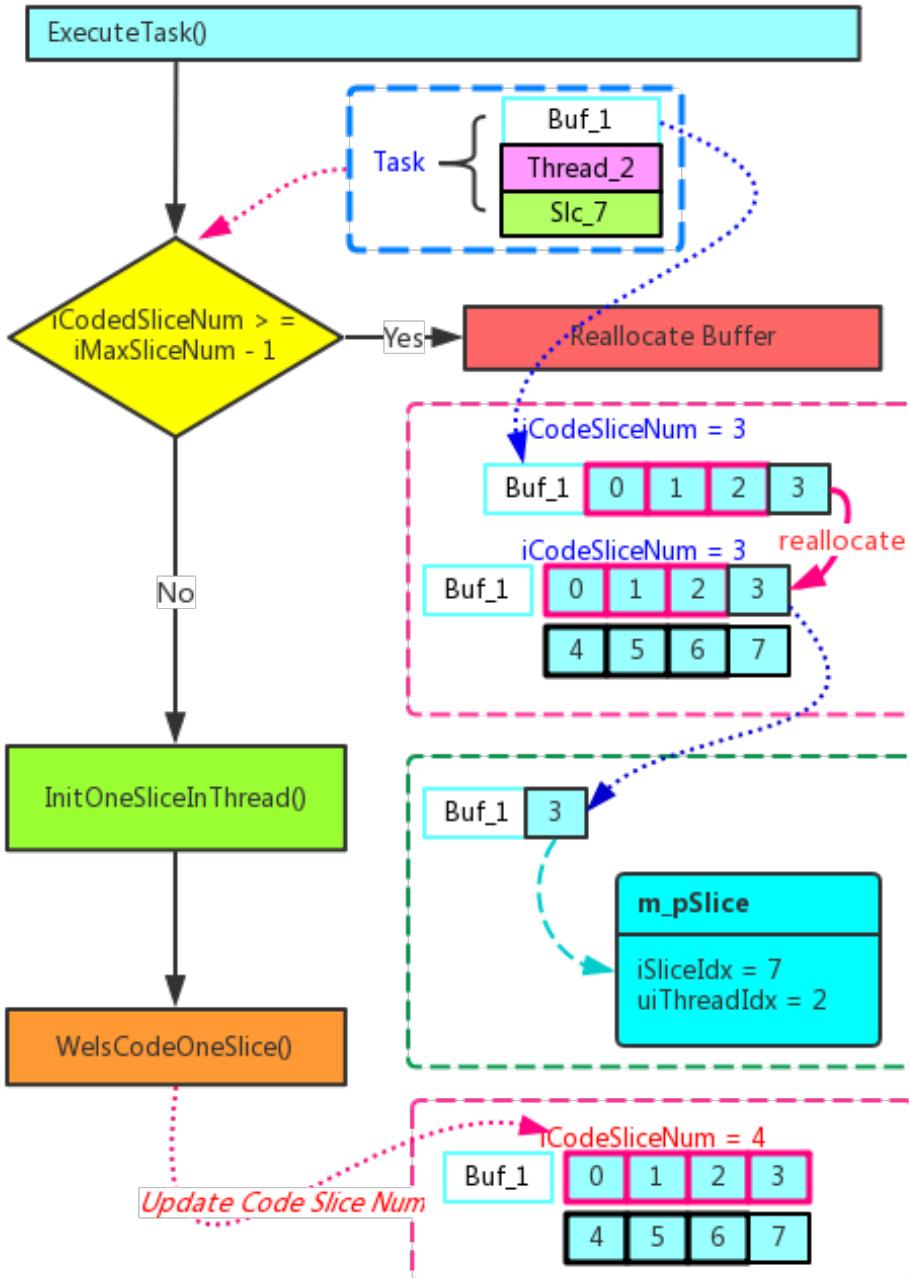
3.3.3. InitTask before encode one slice

- init rc with boundary info
- update next slice boundary(start MB index etc.)



3.3.4 Slice buffer update/reallocate during execute task

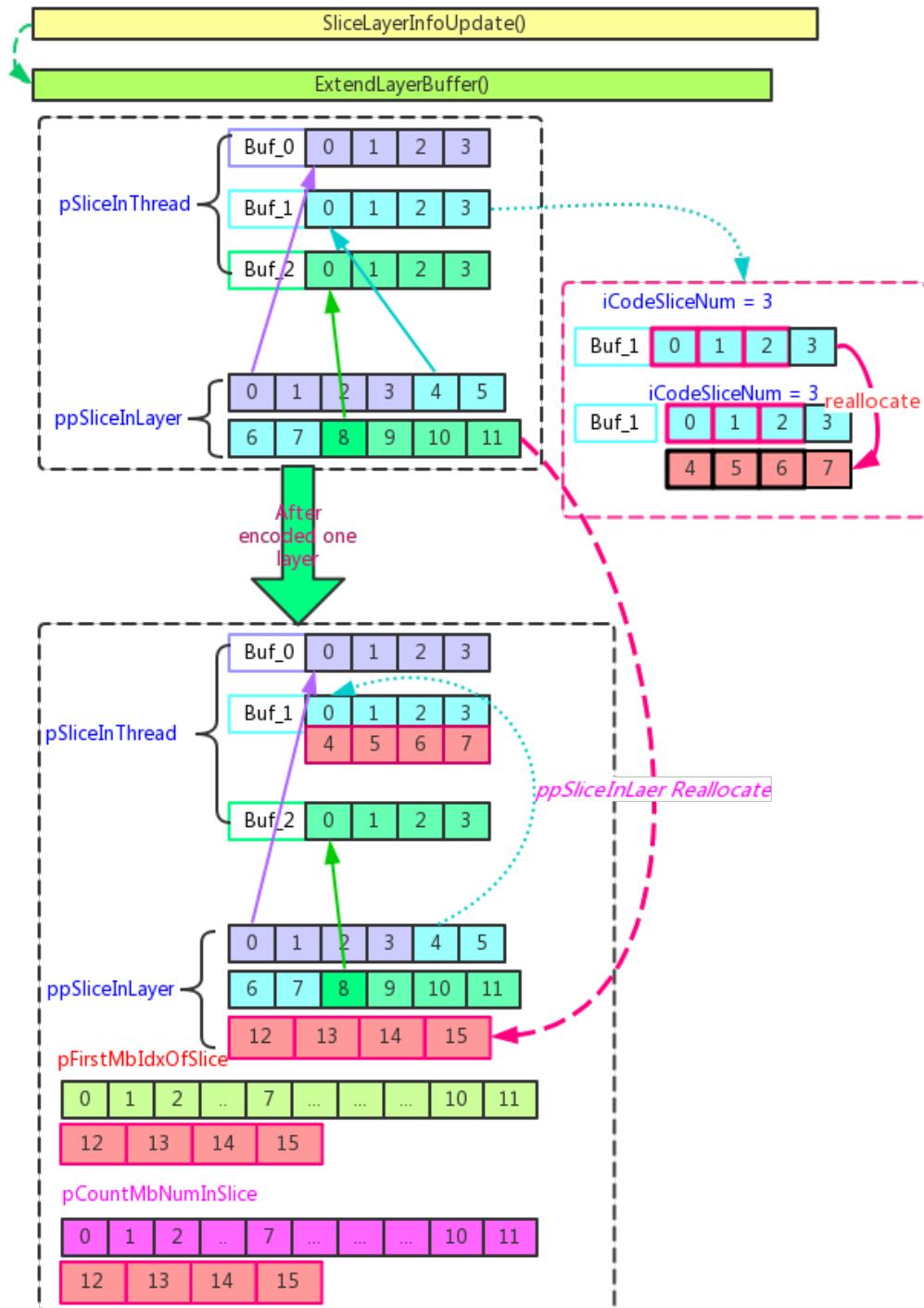
- ⊕ check whether need to reallocate
- ⊕ init m_pSlice buffer
- ⊕ update thread buffer info, iCodeSliceNum ++



3.4. Slice buffer update after encoder one layer

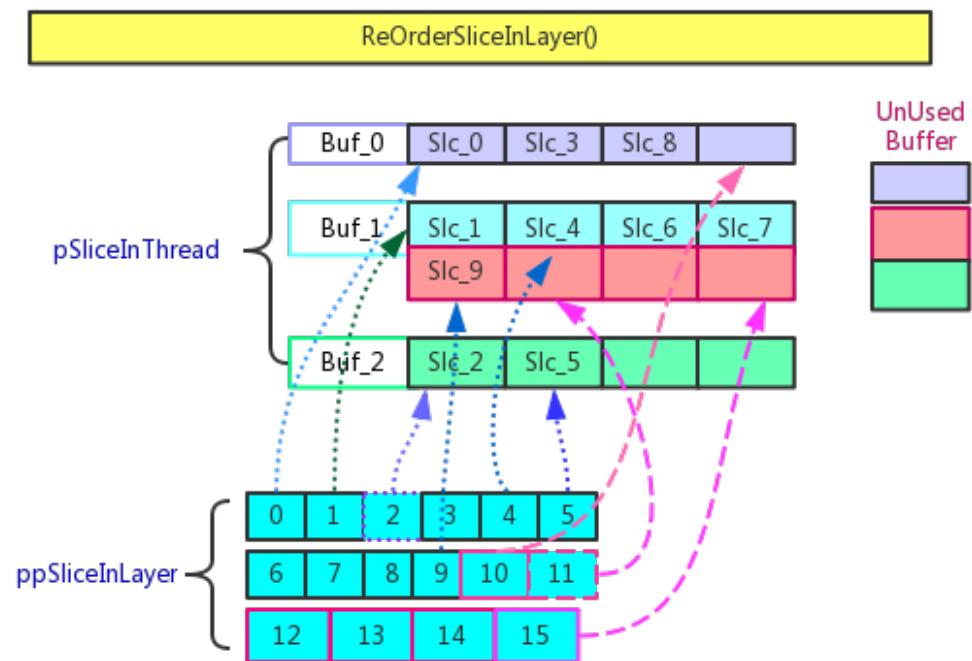
3.4.1. `ppSliceInLayer` update: extend and reallocate `ppSliceInLayer` buffer,

`ppSliceInLayer` buffer num == All thread slice buffer num



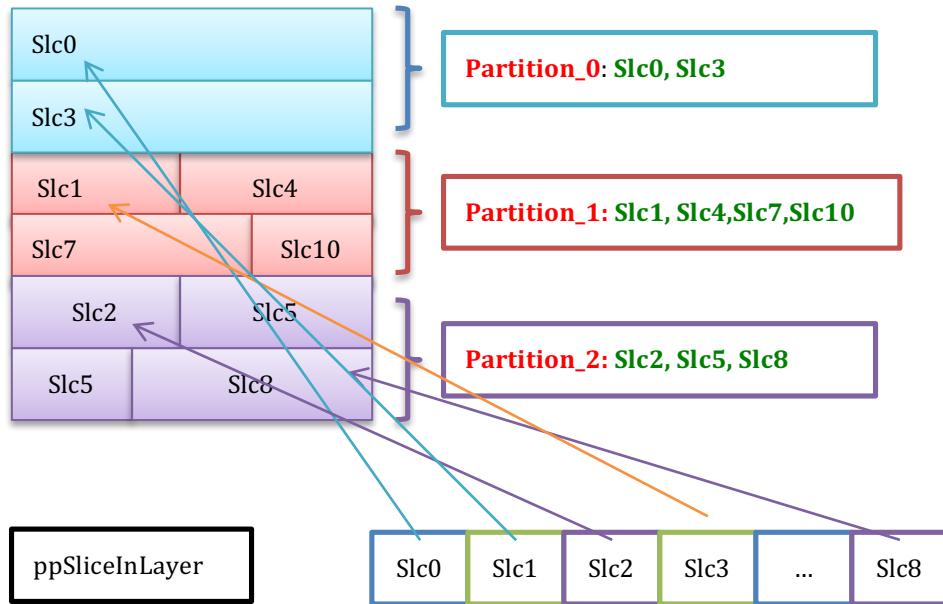
3.4.2. Slice buffer reorder

example 1

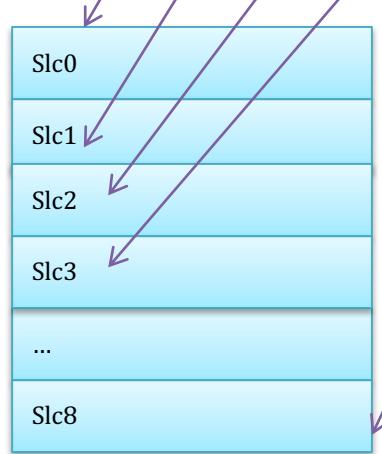


Example 2 Slice index in different slice mode.

Dynamic slice mode

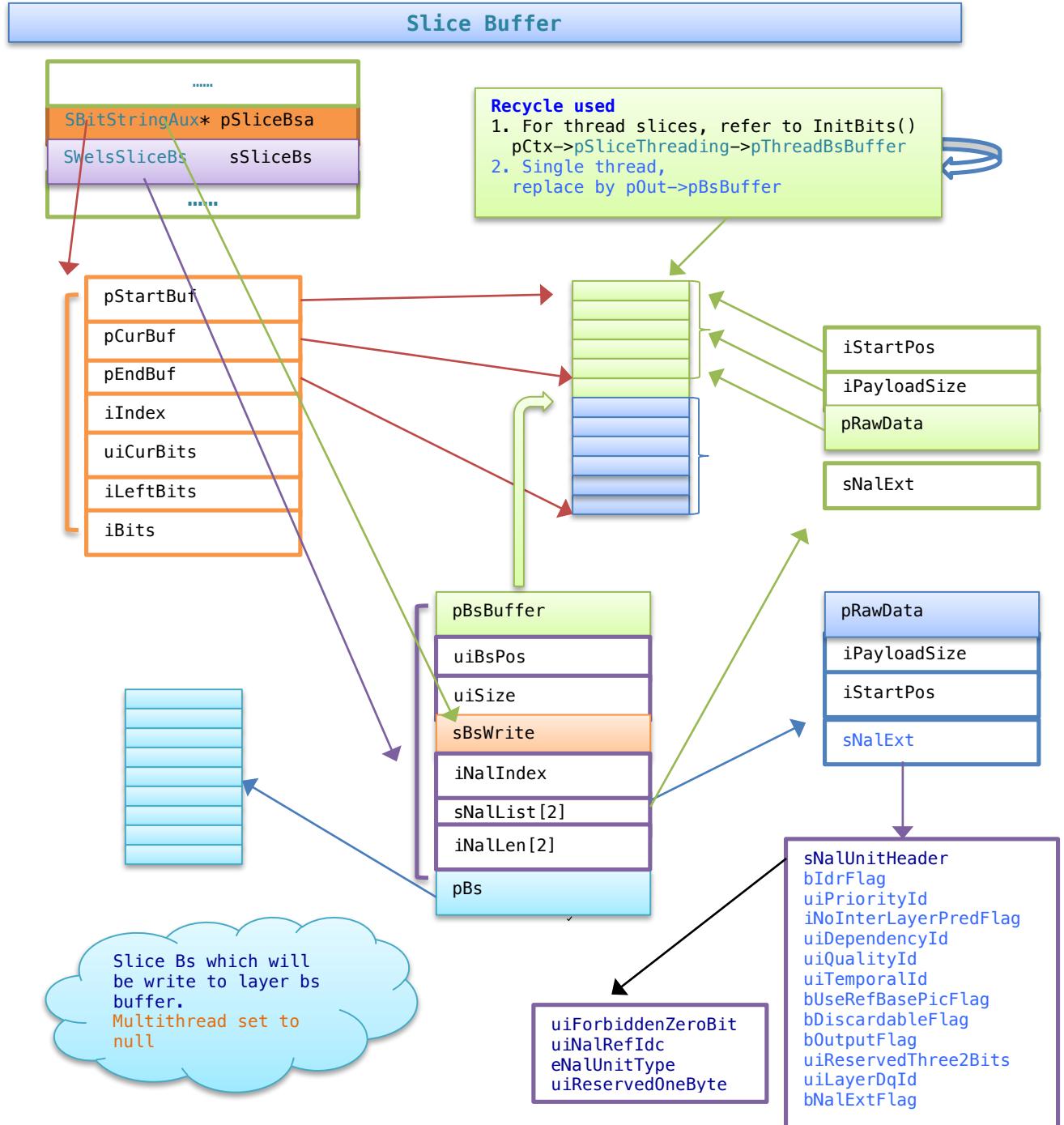


Non-dynamic slice mode

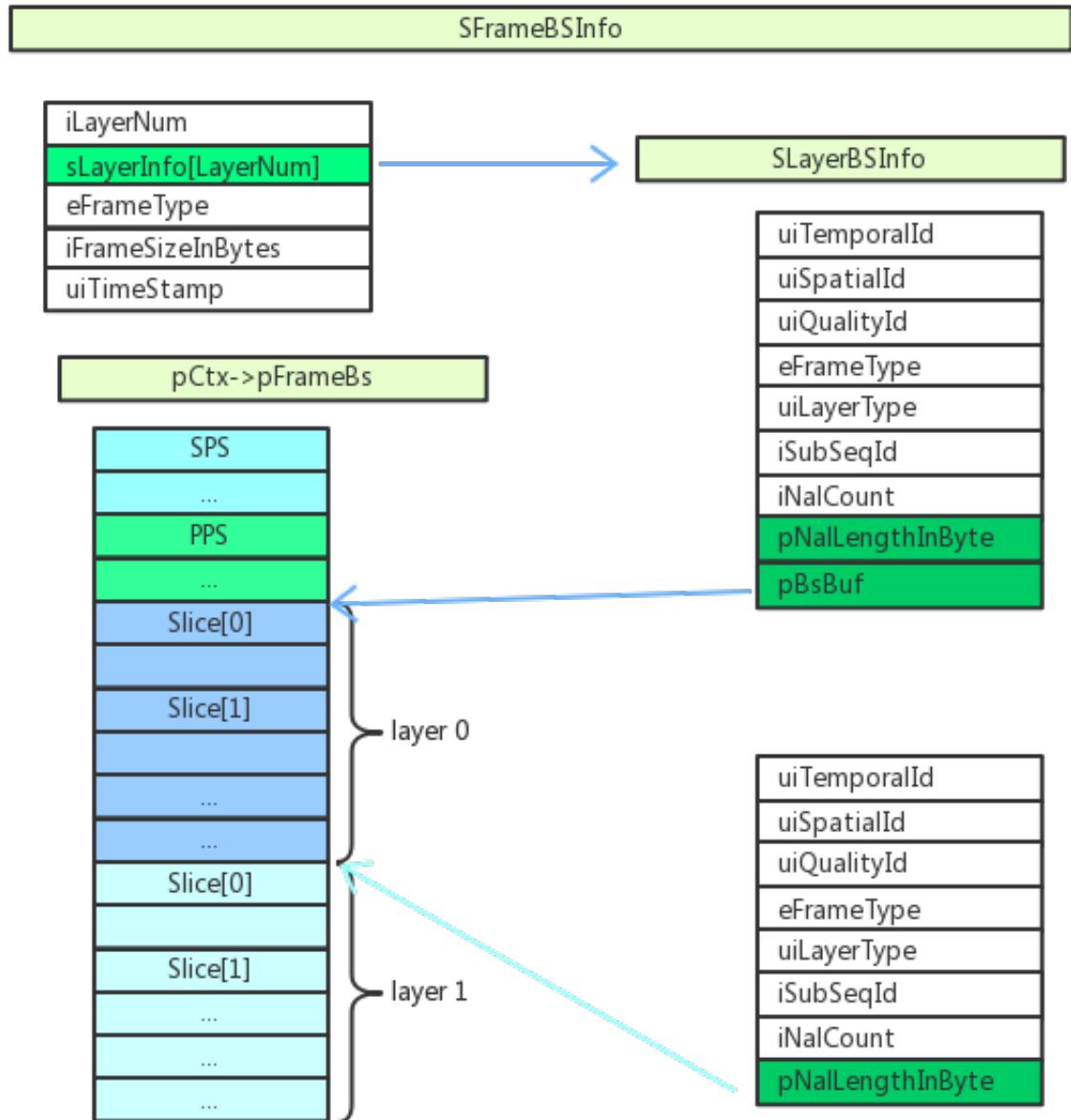


4. Bs buffer design

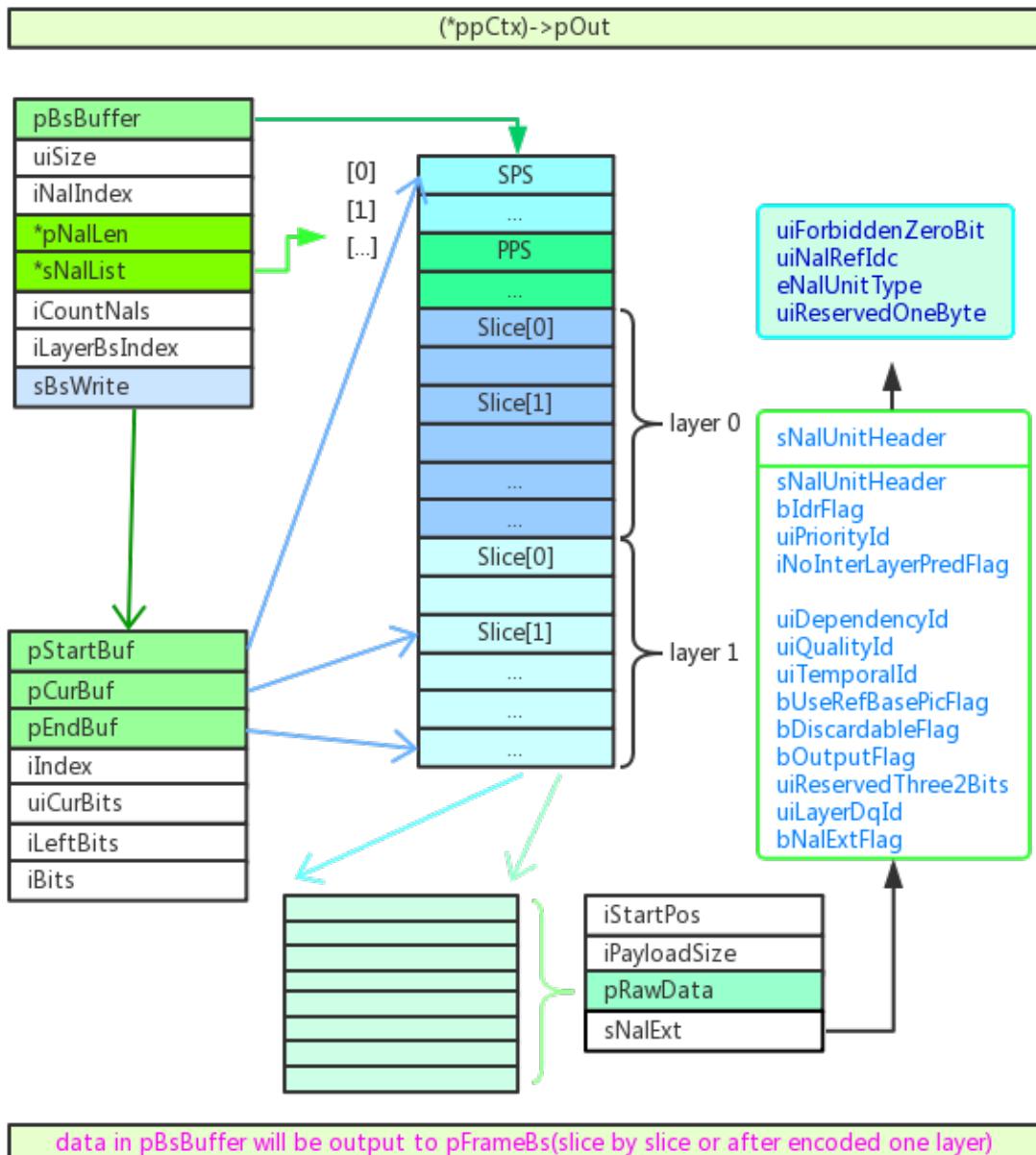
4.1. Slice Bs buffer



4.2. Frame bs buffer



4.3 pCtx-pOut



4.4. dynamic slice, slice boundary strategy

