

# Report on Homework 1

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## 1 k-means vs GMM

Basically, k-means employs One-in-K assignment while GMM utilizes soft assignment. It turns out that k-means has bad robust. Therefore, I tend to introduce some of the ideas in GMM into k-means to form a new variant of k-means.

There are two main differences in my variant of k-means algorithm compared with the original:

- I introduce parts of the soft assignment into k-means to make it more robust.
- I affiliate a hyper parameter  $Thres$  into original k-means. When the posteriori probability is large than  $Thres$ , it can be retained, or it would be 0.

The pseudo-codes of my algorithm can refer to Alg. 1.

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### Algorithm 1: Improvements of k-means

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**input** : The number of clusters  $K$

**output**:  $\pi_k, \mu_k, \Sigma_k, (k = 1, 2, \dots, K)$

1 Initialize the means  $\mu_k$ , covariances  $\Sigma_k$ , mixing coefficients  $\pi_k$  and threshold  $Thres$ .

2 Evaluating the initial value of the log likelihood.

3 **while** the convergence criterion of parameters or log likelihood is not satisfied **do**

4     **E step.** Evaluate the responsibilities using the current parameter values:

$$\omega \leftarrow \frac{\pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(x_n | \mu_j, \Sigma_j)}, \quad \gamma(z_{nk}) \leftarrow \begin{cases} \omega & \omega > Thres \\ 0 & \omega \leq Thres \end{cases}$$

$$z_n \leftarrow \frac{e^{z_{n_i}}}{\sum_{j=1}^K e^{z_{n_j}}}$$

**M step.** Re-estimate the parameters using the current responsibilities:

$$N_k \leftarrow \sum_{n=1}^N \gamma(z_{nk}), \quad \mu_k^{new} \leftarrow \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) x_n$$

$$\Sigma_k^{new} \leftarrow \frac{1}{N_k} \sum_{n=1}^N \gamma(z_{nk}) (x_n - \mu_k^{new})(x_n - \mu_k^{new})^T$$

$$\pi_k^{new} \leftarrow \frac{N_k}{N}$$

   Evaluate the log likelihood:

$$\ln p(X | \mu, \Sigma, \pi) \leftarrow \sum_{k=1}^K \ln \left\{ \sum_{k=1}^K \pi_k \mathcal{N}(x_n | \mu_k, \Sigma_k) \right\}.$$

5 **return**  $\pi_k, \mu_k, \Sigma_k, (k = 1, 2, \dots, K)$ ;

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With the introduction of probability, my algorithm is somewhat similar to EM algorithm and would be more robust than k-means. Besides, the *Thres* would eliminate the negligible posteriori probabilities and improve accuracy under the premise of robustness.

Generally speaking, more hyper parameters would result in more tricks, my algorithm is no exception. The choice of *Thres* may greatly affect the result.

Additionally, my algorithm also encounters the initialization and unknown  $K$  problems. But I think such problems do not contradict with my core ideas, and could be resolved by introducing more components (e.g. the idea of RPCL).

## 2 k-means vs CL

### 2.1 Comparison between k-means and CL

- **Similarities**

1. They can not estimate the total number of clusters from data.
2. The effects of these two algorithms highly rely on initialization.
3. Both of them have huge potential for expansion to improve their robustness.
4. They consider data in distance framework instead of probability.

- **Differences**

1. k-means is a batch learning algorithm while CL belongs to adaptive learning.
2. CL has a hyper parameter  $\eta$  to adjust, making the algorithm a little tricky. But k-means has no hyper parameter.
3. k-means would take more time to converge when it comes to large data size. CL avoids this issue by updating the center by one data point each time.
4. Comparing to k-means, CL requires less computing resource (CPU, memory and etc).
5. The process of k-means is more simple and succinct than CL.

### 2.2 Application of RPCL in k-means

I test this application in a three-cluster dataset generated by myself, and the results of initial centers choice can refer to Fig. ??

## 3 Model Selection of GMM

## References

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