### Report on Homework 2

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### 1 PCA algorithm

When it comes to principal component, the most common used approach is principal component analysis (PCA) algorithm. Thus, I can use the original PCA algorithm to extract the first principal component of the dataset. The computational details can refer to Alg. 1.

### **Algorithm 1:** Original PCA

**Input**: The dataset X, a  $n \times N$  matrix **Output:** The first principal component w

- 1 Conduct normalization for X, and make sure the mean of X is 0;
- 2 Find the covariance matrix of X, denoted by C:

$$C = XX^T$$
:

- 3 Calculate the eigenvalues  $\lambda$  and eigenvectors V of X;
- 4 Choose the maximal eigenvalue  $\lambda_m$  and corresponding eigenvector  $v_m$ ;
- 5 Calculate the first principal component:

$$w = v_m^T X;$$

#### $\epsilon$ return w;

The above algorithm (PCA) is a classical and commonly used method to solve principal components, which has the following characteristics.

#### Pros:

- 1. PCA has simple logic and is easy to implement;
- 2. The orthogonality among principal components chosen by PCA can eliminate the interaction between original data components;
- 3. PCA belongs to unsupervised learning, and it is not restricted by sample labels.

#### Cons:

- 1. PCA treats all samples, namely the collection of eigenvectors, as a whole and neglects the category attributes. Nevertheless, the projection direction it neglects might contain some important separability information;
- 2. PCA would be time-consuming when facing large amount of data;
- 3. The actual meanings of principal components extracted by PCA are a little bit ad-hoc and hard to explain.

The original PCA might have good performance when handling linear data, but it would encounter difficulties under non-linear data. In non-linear cases, a variant of PCA called KPCA (kernel principal components analysis) shows its strength.

The innovation of KPCA is that it introduces a non-linear mapping function, mapping the data from original space to high-dimensional space. The details of KPCA can refer to Alg. 2.

### **Algorithm 2: KPCA**

**Input**: The dataset X, a  $n \times N$  matrix **Output**: The first principal component w

- 1 Conduct normalization for X, and make sure the mean of X is 0;
- 2 Find the covariance matrix of X, denoted by C:

$$C = XX^T$$
;

- 3 Calculate the eigenvalues  $\lambda$  and eigenvectors V of X;
- 4 Choose the maximal eigenvalue  $\lambda_m$  and corresponding eigenvector  $v_m$ ;
- 5 Calculate the first principal component:

$$w = v_m^T X;$$

6 return w;

# 2 Factor Analysis (FA)

$$p(y|x) = \frac{p(x|y)p(y)}{p(x)}$$

$$= \frac{G(x|Ay + \mu, \Sigma_e)G(y|0, \Sigma_y)}{p(x)}$$

$$= \frac{G(x|Ay + \mu, \Sigma_e)G(y|0, \Sigma_y)}{G(x|\mu + \mu_e, AA^T\Sigma_y + \Sigma_e)}$$

where  $\mu_e$  denotes the mean value of e, generally considered to be 0.

# 3 Independent Component Analysis (ICA)

ICA aims to decompose the source signal into independent parts. If the source signals are non-Gaussian, the decomposition is unique, or there would be a variety of such decompositions.

Suppose the source signal s consists of two components, conforming to multi-valued normal distribution, namely  $s \sim N(0, I)$ . Obviously, the probability density function of s is centered on the mean 0, and the projection plane is an ellipse.

Meanwhile, we have x = As, where x denotes the actual signals received while A represents a mixing matrix. Then x is also Gaussian, with a mean of 0 and a covariance of  $E[xx^T] = E[Ass^TA^T] = AA^T$ .

Let C be a orthogonal matrix, and A' = AR. If A is replaced by A', then we can get x' = A's. It is easy to find that x' also conforms to normal distribution, with a mean of 0 and a covariance of  $E[x'(x')^T] = E[A'ss^T(A')^T] = E[ACss^T(AC)^T] = ACC^TA^T = AA^T$ .

Apparently, x and x' conform to the same distribution with different mixing matrices. Then we cannot determine the mixing matrix or the source signals from the received signals. Nevertheless, if x is non-Gaussian (e.g. Uniform Distribution), such case would be effectively avoided. Therefore, maximizing non-Gaussianity should be used as a principle for ICA estimation.

### 4 Causal discovery algorithms

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# 5 Causal tree reconstruction

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