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Matrix theory - Assignment 7

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Abstract—This document illustrates on finding foot of perpendicular from plane using SVD

Download all python codes from

https://github.com/shreeprasadbhat/matrix-theory/blob/master/assignment7/

and latex-tikz from

https://github.com/shreeprasadbhat/matrix-theory/blob/master/assignment7/

1 Problem

Determine the distance from the Y-axis to the plane 5x - 2z - 3 = 0

2 Solution

Equation of plane can be expressed as

$$\mathbf{n}^T \mathbf{x} = c \tag{2.0.1}$$

Rewriting given equation of plane in (2.0.1) form

$$\begin{pmatrix} 5 & 0 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 3 \tag{2.0.2}$$

where :
$$\mathbf{n} = \begin{pmatrix} 5 \\ 0 \\ -2 \end{pmatrix}$$
, $\mathbf{x} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ and $c = 3$

We need to represent equation of plane in parametric form,

$$\mathbf{x} = \mathbf{p} + \lambda_1 \mathbf{q} + \lambda_2 \mathbf{r} \tag{2.0.3}$$

Here p is any point on plane and \mathbf{q} , \mathbf{r} are two vectors parallel to plane and hence \perp to \mathbf{n} . Find two vectors that are \perp to \mathbf{n}

$$(5 \quad 0 \quad -2) \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0$$
 (2.0.4)

Put a = 0 and b = 1 in (2.0.3), $\implies c = 0$ Put a = 1 and b = 0 in (2.0.3), $\implies c = \frac{5}{2}$

Hence
$$\mathbf{q} = \begin{pmatrix} 1 \\ 0 \\ \frac{5}{2} \end{pmatrix}, \mathbf{r} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

Let us find point **p** on the plane. Put x = 1, y = 0 in

(2.0.2), we get
$$\mathbf{p} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

Since given plane is parallel to y-axis, we can use any point P on y-axis to compute shortest distance.

$$\mathbf{P} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \tag{2.0.5}$$

Let \mathbf{Q} be the point on plane with shortest distance to \mathbf{P} . \mathbf{Q} can be expressed in (2.0.4) form as

$$\mathbf{Q} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \lambda_1 \begin{pmatrix} 1 \\ 0 \\ \frac{5}{2} \end{pmatrix} + \lambda_2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \tag{2.0.6}$$

Equation **P** and **Q**, and computing pseudo inverse using SVD should give the value of λ_1 and λ_2 (since plane and y-axis never intersect pseudo inverse should give the points which are closest)

$$\begin{pmatrix} 1\\0\\1 \end{pmatrix} + \lambda_1 \begin{pmatrix} 1\\0\\\frac{5}{2} \end{pmatrix} + \lambda_2 \begin{pmatrix} 0\\1\\0 \end{pmatrix} = \begin{pmatrix} 0\\0\\0 \end{pmatrix}$$
 (2.0.7)

$$\lambda_1 \begin{pmatrix} 1\\0\\\frac{5}{2} \end{pmatrix} + \lambda_2 \begin{pmatrix} 0\\1\\0 \end{pmatrix} = \begin{pmatrix} -1\\0\\-1 \end{pmatrix} \tag{2.0.8}$$

$$\begin{pmatrix}
1 & 0 \\
0 & 1 \\
\frac{5}{2} & 0
\end{pmatrix}
\begin{pmatrix}
\lambda_1 \\
\lambda_2
\end{pmatrix} = \begin{pmatrix}
-1 \\
0 \\
-1
\end{pmatrix}
(2.0.9)$$

$$\mathbf{M}\mathbf{x} = \mathbf{b} \tag{2.0.10}$$

$$\mathbf{x} = \mathbf{M}^{+}\mathbf{b} \tag{2.0.11}$$

where
$$\mathbf{M} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \frac{5}{2} & 0 \end{pmatrix}$$
, $\mathbf{x} = \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} -1 \\ 0 \\ -1 \end{pmatrix}$

Diagonalize $\mathbf{M}\mathbf{M}^T$

$$\mathbf{M}\mathbf{M}^{T} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \frac{5}{2} & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & \frac{5}{2} \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & \frac{5}{2} \\ 0 & 1 & 0 \\ \frac{5}{2} & 0 & \frac{25}{4} \end{pmatrix} \quad (2.0.12)$$

$$= \begin{pmatrix} 0 & \frac{2}{5} & -\frac{5}{2} \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} \frac{29}{4} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ \frac{2}{5} & 0 & 1 \\ -\frac{5}{2} & 0 & 1 \end{pmatrix} \quad (2.0.13)$$

$$= \mathbf{U}\boldsymbol{\Sigma}^{T} \boldsymbol{\Sigma} \mathbf{U}^{T} \quad (2.0.14)$$

Verify (2.0.13) from,

codes/diagonalize1.py

Diagonalize $\mathbf{M}^T \mathbf{M}$

$$\mathbf{M}^{T}\mathbf{M} = \begin{pmatrix} 1 & 0 & \frac{5}{2} \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \frac{5}{2} & 0 \end{pmatrix} = \begin{pmatrix} \frac{29}{4} & 0 \\ 0 & 1 \end{pmatrix}$$
 (2.0.15)
$$= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & \frac{29}{4} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$
 (2.0.16)
$$= \mathbf{V} \mathbf{\Sigma}^{T} \mathbf{\Sigma} \mathbf{V}^{T}$$
 (2.0.17)

Verify (2.0.16) from,

codes/diagonalize2.py

Perform SVD on M,

$$\mathbf{M} = \mathbf{U}\Sigma\mathbf{V}^T \tag{2.0.18}$$

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \frac{5}{2} & 0 \end{pmatrix} = \begin{pmatrix} 0 & \frac{2}{5} & -\frac{5}{2} \\ 1 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} \frac{\sqrt{29}}{2} & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
 (2.0.19)

$$M^{+} = \mathbf{V}\Sigma^{T}\mathbf{U}^{T}$$

$$= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \frac{\sqrt{29}}{2} & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ \frac{2}{5} & 0 & 1 \\ -\frac{5}{2} & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{4}{29} & 0 & \frac{10}{29} \\ 0 & 1 & 0 \end{pmatrix}$$

$$(2.0.22)$$

Verify (2.0.22) from,

codes/pseudo inverse.py

Substitute (2.0.22) in (2.0.11),

$$\mathbf{x} = \begin{pmatrix} \frac{4}{29} & 0 & \frac{10}{29} \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} -1 \\ 0 \\ -1 \end{pmatrix} = \begin{pmatrix} -\frac{14}{29} \\ 0 \end{pmatrix} = \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix}$$
 (2.0.23)

Substituting λ_1 , λ_2 in (2.0.6)

$$\mathbf{Q} = \begin{pmatrix} \frac{15}{29} \\ 0 \\ -\frac{6}{29} \end{pmatrix} \tag{2.0.24}$$

Distance between point P and Q is

$$\|\mathbf{P} - \mathbf{Q}\| = \sqrt{\left(\frac{15}{29}\right)^2 + 0 + \left(-\frac{6}{29}\right)^2} = \frac{3}{\sqrt{29}} (2.0.25)$$

Hence the distance from y-axis to 5x - 2z - 3 = 0 is $\frac{3}{\sqrt{29}}$