

1. Simulation of data with Student's t noise

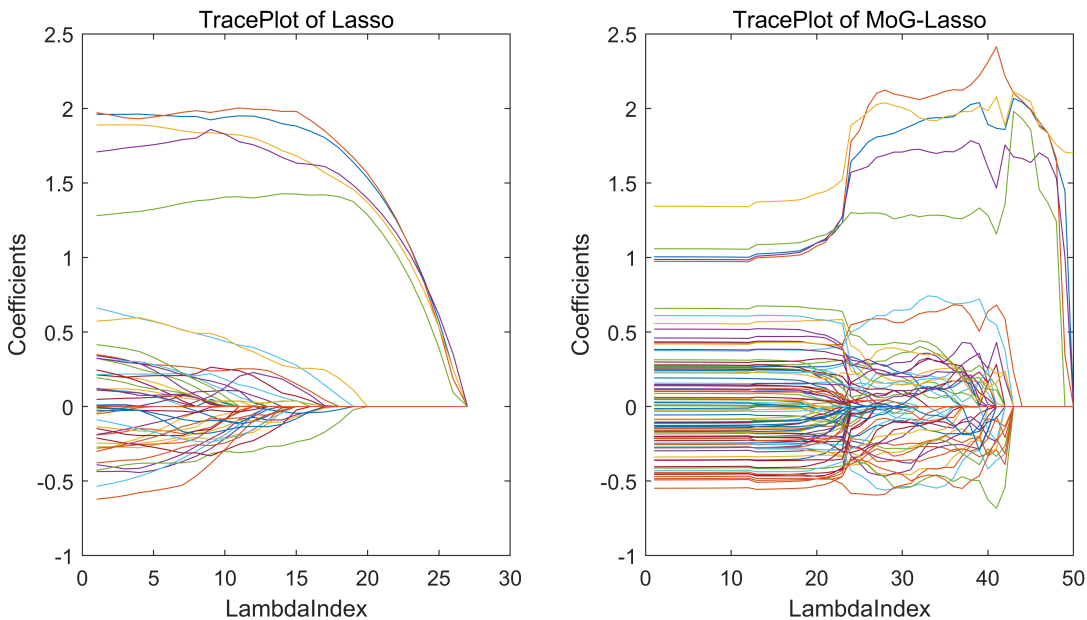
```
n      = 50;  
p      = 100;  
X      = randn(n,p);  
beta   = [2*ones(5,1);zeros(p-5,1)];  
rng(1)  
noise  = random('t',4,[n,1]);  
y      = X*beta+noise;
```

2. Lasso vs MoG-Lasso

```
nfold = 5;  
nlambda = 50;  
[B,FitInfo] = lasso(X,y,'CV',nfold,'NumLambda',nlambda);  
b1 = B(:,FitInfo.Index1SE);  
  
k = 2; % the number of Gaussian components  
rho = 1;  
[BETA, W, meanBIC, meanRSS, lambda] = cvmogspreg(X, y, nfold, nlambda, k, rho);  
b2 = BETA(:,meanBIC==min(meanBIC)); % select the best estimate according to BIC
```

3. Trace plot

```
figure('Position',[300,300,800,400])  
subplot(1,2,1),plot(B'),xlabel('LambdaIndex'), ylabel('Coefficients'),title('TracePlot of Lasso')  
subplot(1,2,2),plot(BETA'),xlabel('LambdaIndex'), ylabel('Coefficients'),title('TracePlot of MoG-Lasso')
```



4. Evaluation: True positive (TP) and true negative (TN) are used for evaluate the performance. Higher the both metrics are, better the algorithm is.

```

true = beta~=0;
bb1 = b1~=0;
bb2 = b2~=0;
TP = [true'*bb1/5;true'*bb2/5];
TN = [(1-true)'*(1-bb1)/(p-5);(1-true)'*(1-bb2)/(p-5)];
display(table(TP,TN, 'rowNames',{'Lasso', 'MoG-Lasso'}))

```

2×2 table

	TP	TN
	—	—
Lasso	1	0.98947
MoG-Lasso	1	1