

# Using the Transformer

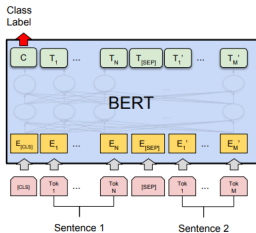
## T5 (Raffel et al., 2019)



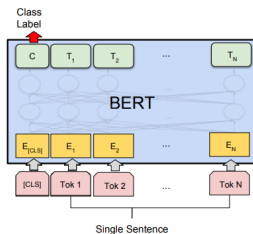
### Learning goals

- shortcomings of BERT & Co.
- everything as text-to-text
- Dynamic Masking

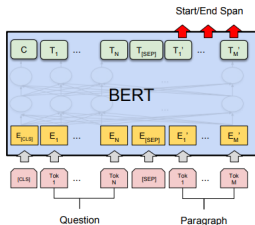
# RECAP: FINE-TUNING BERT



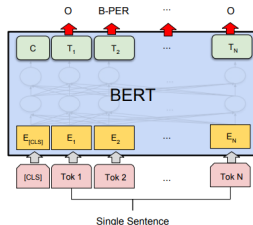
(a) Sentence Pair Classification Tasks:  
MNLI, QQP, QNLI, STS-B, MRPC,  
RTE, SWAG



(b) Single Sentence Classification Tasks:  
SST-2, CoLA



(c) Question Answering Tasks:  
SQuAD v1.1



(d) Single Sentence Tagging Tasks:  
CoNLL-2003 NER

► Source: Devlin et al., 2019

# RECAP: BERT, ROBERTA, ETC.

- Transformer encoder
- Training: Masked language modeling (or similar)
- BERT\* learns an enormous amount of knowledge about language and the world through MLM training on large corpora
- Application: fine-tune on a particular task
- Great performance!
- **Question:** What's not to like?

\*In what follows we will use BERT as a representative for this class of language models and only talk about BERT – but the discussion includes RoBERTa, Albert, XLNet etc.

# PROBLEMS WITH BERT (1)

- You need a different model for each task.  
(Because BERT is differently fine-tuned for each task.)  
→ Not realistic in many real deployment scenarios, e.g., on mobile devices.
- *Human learning*: We arguably have a **single** model that solves all tasks!
- **Question**: Is there a framework that allows us to create a single model that solves all tasks?

# PROBLEMS WITH BERT (2)

- Two training modes: first (MLM) pretraining, then fine-tuning.
- Fine-tuning is **supervised learning**, i.e., learning from labeled examples.
- Arguably, learning from labeled examples is untypical for human learning.
- You never learn a task solely by being presented a bunch of examples, without explanation.
- Instead, in human learning, there is almost always a **task description**.

# PROBLEMS WITH BERT (2)

- Example: *How to boil an egg.*
  - “Place eggs in the bottom of a saucepan.”
  - “Fill the pan with cold water.”
  - “Etc.”
- Notice that this is **not** an example but a *description* of the task
- **Question:** Is there a framework that allows us to leverage task descriptions?

# PROBLEMS WITH BERT (3)

- BERT has great performance, but ...
- ... only if the training set is large, generally 1000s of examples
- This is completely different from human learning!
- We do use examples in learning, but in most cases, only a few

## PROBLEMS WITH BERT (3)

- Example: Maybe the person teaching you how to boil an egg will show you how to do it *one or two times*
- But probably **not** 10 times
- Definitely **not** a 1000 times
- More practical concern: it's very expensive to label 1000s of examples for each task (there are many tasks).
- **Question:** Is there a framework that allows us to learn from just a small number of examples?
- This is called **few-shot learning**.



# PROBLEMS WITH BERT (4)

- More subtle aspect of the same problem (i.e., large training sets):  
→ **Overfitting**
- Even though performance looks good on standard train/dev/test splits, the deviation between the training set and the data actually encountered in real application can be large
- So our benchmarks often overestimate what performance would be in reality

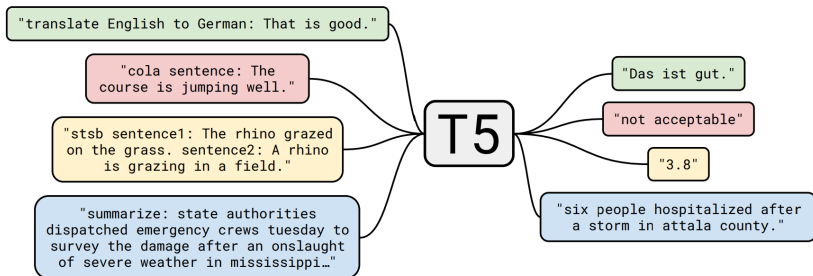
# T5

## Short summary:

- *Text-to-Text Transfer Transformer (T5)*
  - A complete encoder-decoder Transformer architecture
  - Relative positional emeddings
  - All tasks reformulated as text-to-text tasks
- Probably the most important innovation of this work
- From BERT-size up to 11 Billion parameters
  - Paradigm shift from *Sequential Transfer Learning* towards *Multi-Task Learning*

▶ [Animation \(Link\)](#)

# ILLUSTRATION



► Raffel et al. (2020)

# ILLUSTRATION

# INPUT AND OUTPUT FORMAT

## Input Side:

- SentencePiece framework w/ WordPiece tokens
  - Add task-specific (text) prefix to the original input
  - Choice of the prefix: Hyperparameter!!
- Changing this had limited impact
- No extensive experiments performed by the authors

## Output Side:

- Output as a word or a piece of text (also similarity scores)
- If output not present in set of potential alternatives, prediction considered as wrong

# ADD-ON: DISTINCTION TO PROMPTING

## Adding task-specific (text) prefix:

- Add task-specific (text) prefix to the original input
  - Model is fine-tuned on samples prepended with this prefix
- It learns to recognize what it is expected to do when encountering a specific prefix at test time
- Probably because of this: limited impact found by the authors

## Prompting:

- Refers to just querying a trained w/o fine-tuning it (cf. next chapter)
- Paradigm of Few-/Zero-Shot Learning
- This is found to have a *huge* impact on model performance

# PRE-TRAINING T5

Original text

Thank you ~~for inviting~~ me to your party ~~last~~ week.

Inputs

Thank you <X> me to your party <Y> week.

Targets

<X> for inviting <Y> last <Z>

Baseline objective (Source: Raffel et al., 2019)

- 1 Mark spans in input sequence for corruptions
- 2 Replace tokens with sentinel tokens
- 3 Predict sentinel tokens and replaced tokens

# PRE-TRAINING OBJECTIVES

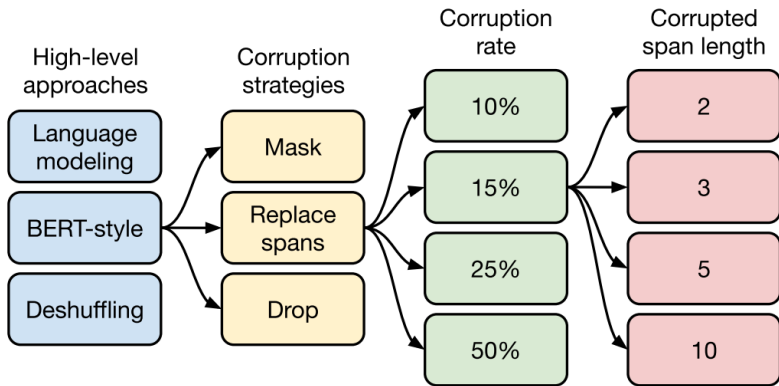
- Authors experimented with different objectives
- Most of them rely in some way on MLM

Objective	Inputs	Targets
Prefix language modeling	Thank you for inviting	me to your party last week .
BERT-style <a href="#">Devlin et al. (2018)</a>	Thank you <M> <M> me to your party apple week .	<i>(original text)</i>
Deshuffling	party me for your to . last fun you inviting week Thank	<i>(original text)</i>
MASS-style <a href="#">Song et al. (2019)</a>	Thank you <M> <M> me to your party <M> week .	<i>(original text)</i>
I.i.d. noise, replace spans	Thank you <X> me to your party <Y> week .	<X> for inviting <Y> last <Z>
I.i.d. noise, drop tokens	Thank you me to your party week .	for inviting last
Random spans	Thank you <X> to <Y> week .	<X> for inviting me <Y> your party last <Z>

Source: Raffel et al. (2019)



# PRE-TRAINING OBJECTIVES



Source: Raffel et al. (2019)

# THE COLOSSAL CLEAN CRAWLED CORPUS (C4)

- Effort to measure the effect of quality, characteristics & size of the pre-training resources
- Common Crawl as basis, careful cleaning and filtering for English language
- Orders of magnitude larger (750GB) compared to commonly used corpora

# THE COLOSSAL CLEAN CRAWLED CORPUS (C4)

## Experiments (with respect to C4)

Data set	Size	GLUE	CNNDM	SQuAD	SGLUE	EnDe	EnFr	EnRo
★ C4	745GB	83.28	<b>19.24</b>	80.88	71.36	<b>26.98</b>	<b>39.82</b>	<b>27.65</b>
C4, unfiltered	6.1TB	81.46	19.14	78.78	68.04	26.55	39.34	27.21
RealNews-like	35GB	<b>83.83</b>	<b>19.23</b>	80.39	72.38	<b>26.75</b>	<b>39.90</b>	<b>27.48</b>
WebText-like	17GB	<b>84.03</b>	<b>19.31</b>	<b>81.42</b>	71.40	<b>26.80</b>	<b>39.74</b>	<b>27.59</b>
Wikipedia	16GB	81.85	<b>19.31</b>	81.29	68.01	<b>26.94</b>	39.69	<b>27.67</b>
Wikipedia + TBC	20GB	83.65	<b>19.28</b>	<b>82.08</b>	<b>73.24</b>	<b>26.77</b>	39.63	<b>27.57</b>

Number of tokens	Repeats	GLUE	CNNDM	SQuAD	SGLUE	EnDe	EnFr	EnRo
★ Full data set	0	<b>83.28</b>	<b>19.24</b>	<b>80.88</b>	<b>71.36</b>	<b>26.98</b>	<b>39.82</b>	<b>27.65</b>
2 <sup>29</sup>	64	<b>82.87</b>	<b>19.19</b>	<b>80.97</b>	<b>72.03</b>	<b>26.83</b>	<b>39.74</b>	<b>27.63</b>
2 <sup>27</sup>	256	82.62	<b>19.20</b>	79.78	69.97	<b>27.02</b>	<b>39.71</b>	27.33
2 <sup>25</sup>	1,024	79.55	18.57	76.27	64.76	26.38	39.56	26.80
2 <sup>23</sup>	4,096	76.34	18.33	70.92	59.29	26.37	38.84	25.81

Source: Raffel et al. (2019)

# T5 - EXHAUSTIVE EXPERIMENTS

## Performed experiments with respect to ..

- .. *architecture, size & objective*
  - enc, dec, enc-dec
  - Between 60M and 11B parameters
- .. *details of the Denoising objective (which was found to work best)*
- .. *fine-tuning methods*
  - Adapter layers
  - Gradual Unfreezing (cf. ULMFiT)
- .. *Multi-task learning strategies*
  - Examples-proportional mixing
  - Temperature-scaled mixing

# BENCHMARK RESULTS

Model	GLUE Average	CoLA Matthew's	SST-2 Accuracy	MRPC F1	MRPC Accuracy	STS-B Pearson	STS-B Spearman
Previous best	89.4 <sup>a</sup>	69.2 <sup>b</sup>	97.1 <sup>a</sup>	<b>93.6<sup>b</sup></b>	<b>91.5<sup>b</sup></b>	92.7 <sup>b</sup>	92.3 <sup>b</sup>
T5-Small	77.4	41.0	91.8	89.7	86.6	85.6	85.0
T5-Base	82.7	51.1	95.2	90.7	87.5	89.4	88.6
T5-Large	86.4	61.2	96.3	92.4	89.9	89.9	89.2
T5-3B	88.5	67.1	97.4	92.5	90.0	90.6	89.8
T5-11B	<b>90.3</b>	<b>71.6</b>	<b>97.5</b>	92.8	90.4	<b>93.1</b>	<b>92.8</b>

Model	QQP F1	QQP Accuracy	MNLI-m Accuracy	MNLI-mm Accuracy	QNLI Accuracy	RTE Accuracy	WNLI Accuracy
Previous best	74.8 <sup>c</sup>	<b>90.7<sup>b</sup></b>	91.3 <sup>a</sup>	91.0 <sup>a</sup>	<b>99.2<sup>a</sup></b>	89.2 <sup>a</sup>	91.8 <sup>a</sup>
T5-Small	70.0	88.0	82.4	82.3	90.3	69.9	69.2
T5-Base	72.6	89.4	87.1	86.2	93.7	80.1	78.8
T5-Large	73.9	89.9	89.9	89.6	94.8	87.2	85.6
T5-3B	74.4	89.7	91.4	91.2	96.3	91.1	89.7
T5-11B	<b>75.1</b>	90.6	<b>92.2</b>	<b>91.9</b>	96.9	<b>92.8</b>	<b>94.5</b>

Results on GLUE (Source: Raffel et al., 2019)

# BENCHMARK RESULTS

Model	SQuAD EM	SQuAD F1	SuperGLUE Average	BoolQ Accuracy	CB F1	CB Accuracy	COPA Accuracy
Previous best	90.1 <sup>a</sup>	95.5 <sup>a</sup>	84.6 <sup>d</sup>	87.1 <sup>d</sup>	90.5 <sup>d</sup>	95.2 <sup>d</sup>	90.6 <sup>d</sup>
T5-Small	79.10	87.24	63.3	76.4	56.9	81.6	46.0
T5-Base	85.44	92.08	76.2	81.4	86.2	94.0	71.2
T5-Large	86.66	93.79	82.3	85.4	91.6	94.8	83.4
T5-3B	88.53	94.95	86.4	89.9	90.3	94.4	92.0
T5-11B	<b>91.26</b>	<b>96.22</b>	<b>88.9</b>	<b>91.2</b>	<b>93.9</b>	<b>96.8</b>	<b>94.8</b>

Model	MultiRC F1a	MultiRC EM	ReCoRD F1	ReCoRD Accuracy	RTE Accuracy	WiC Accuracy	WSC Accuracy
Previous best	84.4 <sup>d</sup>	52.5 <sup>d</sup>	90.6 <sup>d</sup>	90.0 <sup>d</sup>	88.2 <sup>d</sup>	69.9 <sup>d</sup>	89.0 <sup>d</sup>
T5-Small	69.3	26.3	56.3	55.4	73.3	66.9	70.5
T5-Base	79.7	43.1	75.0	74.2	81.5	68.3	80.8
T5-Large	83.3	50.7	86.8	85.9	87.8	69.3	86.3
T5-3B	86.8	58.3	91.2	90.4	90.7	72.1	90.4
T5-11B	<b>88.1</b>	<b>63.3</b>	<b>94.1</b>	<b>93.4</b>	<b>92.5</b>	<b>76.9</b>	<b>93.8</b>

Results on SQUAD and S-GLUE (Source: Raffel et al., 2019)

# BENCHMARK RESULTS

Model	WMT EnDe BLEU	WMT EnFr BLEU	WMT EnRo BLEU	CNN/DM ROUGE-1	CNN/DM ROUGE-2	CNN/DM ROUGE-L
Previous best	<b>33.8<sup>e</sup></b>	<b>43.8<sup>e</sup></b>	<b>38.5<sup>f</sup></b>	43.47 <sup>g</sup>	20.30 <sup>g</sup>	40.63 <sup>g</sup>
T5-Small	26.7	36.0	26.8	41.12	19.56	38.35
T5-Base	30.9	41.2	28.0	42.05	20.34	39.40
T5-Large	32.0	41.5	28.1	42.50	20.68	39.75
T5-3B	31.8	42.6	28.2	42.72	21.02	39.94
T5-11B	32.1	43.4	28.1	<b>43.52</b>	<b>21.55</b>	<b>40.69</b>

Results on MT/Summarization Benchmarks (Source: Raffel et al., 2019)

# T5 - EXHAUSTIVE EXPERIMENTS

## Conclusions

- Encoder-decoder architecture works best in this "text-to-text" setting
- More data, larger models & ensembling all boost the performance
  - Larger models trained for fewer steps better than smaller models on more data
  - Ensembling: Using same base pre-trained models worse than complete separate model ensembles
- Different denoising objectives work similarly well
- Updating *all* model parameters during fine-tuning works best (but expensive)