# **Post-BERT Era**

# **BERT-based architectures**



# Learning goals

- changes to the pre-traing objectives
- dynamic masking
- architectural details of BERT & Co.

blocks.

- October 2018 BERT
- BERT (Devlin et al., 2018) is a
- bidirectional contextual embedding model purely relying on Self-Attention by using multiple **Transformer encoder**
- BERT (and its successors) rely on the
  Masked Language Modelling objective
  during pre-training on huge unlabelled

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07/2019

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Other approaches now more and more concentrate on improving, down-scaling or understanding BERT. A new research direction called **BERTology** emerges.

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#### October 2019 - DistilBERT

Sanh et al., 2019 employed the concept of 'model distillation' to create a smaller BERT-type model (contrary to the current trend of building ever larger models).

DistilBERT shows an impressive performance when fine-tuned on downstream tasks despite only exhibiting half the size of the ordinary BERT-BASE model.

## ROBERTA – PRE-TRAINING IMPROVEMENTS

Robustly optimizied BERT approach Liu et al., 2019

### **Short summary:**

- Change of the MASKing strategy
  - → BERT masks the sequences once before pre-training
  - → RoBERTa uses dynamic MASKing
  - → RoBERTa sees the same sequence MASKed differently
- RoBERTa does not use the additional NSP objective during pre-training
- Authors claim that BERT is seriously "undertrained"
  - 160 GB pre-training corpus instead of 13 GB
  - Pre-training is performed with larger batch sizes (8k)
- Training on full-length sequences only (512 tokens)

## ROBERTA – THE ARCHITECTURE

### Architectural differences:

- Architecture (layers, heads, embedding size) identical to BERT
- 50k token BPE vocabulary instead of 30k
- Model size differs (due to the larger embedding matrix)
   ⇒ ~ 125M (360M) for the BASE (LARGE) variant

### Performance differences:

	MNLI	QNLI	QQP	RTE	SST	MRPC	CoLA	STS	WNLI	Avg
Single-task single models on dev										
$BERT_{LARGE}$	86.6/-	92.3	91.3	70.4	93.2	88.0	60.6	90.0	-	-
$XLNet_{LARGE}$	89.8/-	93.9	91.8	83.8	95.6	89.2	63.6	91.8	-	-
RoBERTa	90.2/90.2	94.7	92.2	86.6	96.4	90.9	68.0	92.4	91.3	-

► Source: Liu et al., 2019

*Note:* Liu et al. (2019) report the accuracy for QQP while Devlin et al. (2019) report the F1 score (cf. results displayed in chapter 6.2.3); XLNet: see next Chapter.

# DYNAMIC VS. STATIC MASKING

### Static Masking (BERT):

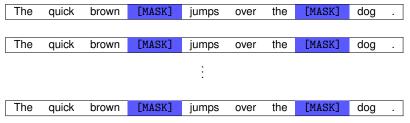
- Apply MASKing procedure to pre-training corpus once
- (additional for BERT: Modify the corpus for NSP)
- Train for approximately 40 epochs

## Dynamic Masking (RoBERTa):

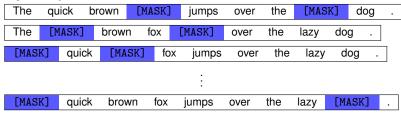
- Duplicate the training corpus ten times
- Apply MASKing procedure to each duplicate of the pre-training corpus
- Train for 40 epochs
- Model sees each training instance in ten different "versions" (each version four times) during pre-training

## DYNAMIC VS. STATIC MASKING

#### BERT:



#### RoBERTa:



# DYNAMIC VS. STATIC MASKING

Masking	SQuAD 2.0	MNLI-m	SST-2					
reference	76.3	84.3	92.8					
Our reimplementation:								
static	78.3	84.3	92.5					
dynamic	78.7	84.0	92.9					

Table 1: Comparison between static and dynamic masking for BERT<sub>BASE</sub>. We report F1 for SQuAD and accuracy for MNLI-m and SST-2. Reported results are medians over 5 random initializations (seeds). Reference results are from Yang et al. (2019).



# NO NEXT SENTENCE PREDICTION

- Described as important part of the pre-training process in BERT
- Liu et al., 2019 report that it hurts performance
- → Especially for QNLI, MNLI, and SQuAD 1.1
  - Conduct experiments in multiple settings:
    - SEGMENT-PAIR+NSP (Exactly like BERT)
    - SENTENCE-PAIR+NSP
       (Like BERT, but with natural sentences)
    - FULL-SENTENCES
       (No NSP, inputs may cross document boundaries)
    - DOC-SENTENCES
       (No NSP, only sentences from one document)

# NO NEXT SENTENCE PREDICTION

Model	SQuAD 1.1/2.0	MNLI-m	SST-2	RACE		
Our reimplementation	on (with NSP loss):	•				
SEGMENT-PAIR	90.4/78.7	84.0	92.9	64.2		
SENTENCE-PAIR	88.7/76.2	82.9	92.1	63.0		
Our reimplementation (without NSP loss):						
FULL-SENTENCES	90.4/79.1	84.7	92.5	64.8		
DOC-SENTENCES	90.6/79.7	84.7	92.7	65.6		
BERT <sub>BASE</sub>	88.5/76.3	84.3	92.8	64.3		
$XLNet_{BASE} (K = 7)$	-/81.3	85.8	92.7	66.1		
$XLNet_{BASE} (K = 6)$	-/81.0	85.6	93.4	66.7		

Table 2: Development set results for base models pretrained over BOOKCORPUS and WIKIPEDIA. All models are trained for 1M steps with a batch size of 256 sequences. We report F1 for SQuAD and accuracy for MNLI-m, SST-2 and RACE. Reported results are medians over five random initializations (seeds). Results for BERT<sub>BASE</sub> and XLNeta<sub>RASF</sub> are from Yang et al. (2019).

► Source: Liu et al., 2019

Note: XLNet: see next Chapter.

## **BATCH SIZE**

bsz	steps	lr	ppl	MNLI-m	SST-2
256	1M	1e-4	3.99	84.7	92.7
2K	125K	7e-4	3.68	85.2	92.9
8K	31K	1e-3	3.77	84.6	92.8

Table 3: Perplexity on held-out training data (ppl) and development set accuracy for base models trained over BOOKCORPUS and WIKIPEDIA with varying batch sizes (bsz). We tune the learning rate (lr) for each setting. Models make the same number of passes over the data (epochs) and have the same computational cost.

► Source: Liu et al., 2019

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## **FURTHER CHANGES IN PRE-TRAINING**

Model	data	bsz	steps	<b>SQuAD</b> (v1.1/2.0)	MNLI-m	SST-2
RoBERTa						
with BOOKS + WIKI	16GB	8K	100K	93.6/87.3	89.0	95.3
+ additional data (§3.2)	160GB	8K	100K	94.0/87.7	89.3	95.6
+ pretrain longer	160GB	8K	300K	94.4/88.7	90.0	96.1
+ pretrain even longer	160GB	8K	500K	94.6/89.4	90.2	96.4
$\begin{aligned} & BERT_{LARGE} \\ & with BOOKS + WIKI \\ & XLNet_{LARGE} \end{aligned}$	13GB	256	1M	90.9/81.8	86.6	93.7
with BOOKS + WIKI	13GB	256	1 <b>M</b>	94.0/87.8	88.4	94.4
+ additional data	126GB	2K	500K	94.5/88.8	89.8	95.6

Table 4: Development set results for RoBERTa as we pretrain over more data ( $16GB \rightarrow 160GB$  of text) and pretrain for longer ( $100K \rightarrow 300K \rightarrow 500K$  steps). Each row accumulates improvements from the rows above. RoBERTa matches the architecture and training objective of BERT<sub>LARGE</sub>. Results for BERT<sub>LARGE</sub> and XLNet<sub>LARGE</sub> are from Devlin et al. (2019) and Yang et al. (2019), respectively. Complete results on all GLUE tasks can be found in the Appendix.

➤ Source: Liu et al., 2019

Note: XLNet: see next Chapter.

## **ALBERT**

## A Lite BERT Lan et al., 2019

## **Short summary:**

- Major change to the architecture
  - $\rightarrow$  Size of embedding layer independent from hidden layer (rember in Transformer/BERT: E = H)
  - $\rightarrow$  Saves memory and compute
- Parameter sharing across layers
- Substitution of the NSP objective during pre-training

(C)

# ARCHITECTURAL CHANGES

### Disentanglement of E and H

- WordPiece-Embeddings (size E)
  - first layer of the model
  - each token is initially mapped to this embedding
  - context-independent
- In Transformer/BERT:
  - $\bullet$  H = E
  - down-project E to keys, queries and values of size H/A
  - concatenate resulting embeddings from all A heads
  - results in hidden layer representation of size H
- Question: What are the implications?

(C)

# **ARCHITECTURAL CHANGES**

## Thoughts / Implications

- WordPiece-Embeddings (size E)
  - required representational capacity?
  - probably could be limited w/o loosing much
- Hidden-Layer-Embedding (size H)
  - required representational capacity?
  - depending on how polysemous a word/token might be
  - difficult to say "one size fits all"
  - probably might be better to rather increase this, compared to the WordPiece embeddings

 $\rightarrow$  Setting E = H does not allow us to pursue these considerations

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## ARCHITECTURAL CHANGES

## Disentanglement solves this

- ◆ Hidden-Layer-Embeddings (size H) context-dependent
   → providing more capacity makes more sense here
- Setting H >> E enlargens model capacity in the hidden layers without increasing the size of the embedding matrix
- $O(V \times H) > O(V \times E + E \times H)$  if H >> E

# **CROSS-LAYER PARAMETER SHARING**

- Pre-trained transformer-based models are deep stacks of identically parametrized layers and thus have many parameters
- Sharing them as a way to gain parameter efficiency
- Two different places in the network, where sharing can be done
  - Attention parameters
  - FFN parameters
- Ablation studies:
  - both
  - both individually
  - none

# **CROSS-LAYER PARAMETER SHARING**

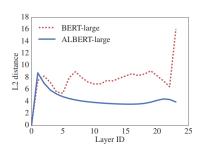
Model		Parameters	SQuAD1.1	SQuAD2.0	MNLI	SST-2	RACE	Avg
AL DEDT	all-shared	31M	88.6/81.5	79.2/76.6	82.0	90.6	63.3	79.8
ALBERT base	shared-attention	83M	89.9/82.7	80.0/77.2	84.0	91.4	67.7	81.6
E=768	shared-FFN	57M	89.2/82.1	78.2/75.4	81.5	90.8	62.6	79.5
	not-shared	108M	90.4/83.2	80.4/77.6	84.5	92.8	68.2	82.3
ALDEDT	all-shared	12M	89.3/82.3	80.0/77.1	82.0	90.3	64.0	80.1
ALBERT base E=128	shared-attention	64M	89.9/82.8	80.7/77.9	83.4	91.9	67.6	81.7
	shared-FFN	38M	88.9/81.6	78.6/75.6	82.3	91.7	64.4	80.2
	not-shared	89M	89.9/82.8	80.3/77.3	83.2	91.5	67.9	81.6

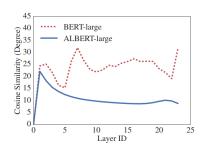
Table 4: The effect of cross-layer parameter-sharing strategies, ALBERT-base configuration.



- (Drastic) reduction of model size (more for sharing FFN weights)
- Sharing parameters hurts performance
  - Worse for models with larger E
  - Worse for sharing FNN compared to Attention weights
  - Question: Why? What is the intuition here?

# **CROSS-LAYER PARAMETER SHARING**





➤ Source: Lan et al., 2019

- Distince/Similarity of input and output embeddings per layer
- Smoother transitions for ALBERT models

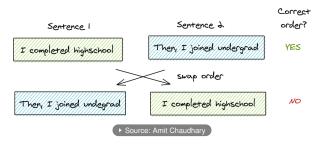
## CHANGES IN PRE-TRAINING

### Substitution of the NSP objective

- Previous works questioned the usefulness of NSP
- → Lan et al. assume that this is due to lacking difficulty
  - Introduction of Sentence-Order Prediction (SOP) as a new pre-training task
  - Positive examples created alike to those from NSP (take two consecutive sentences from the same document)
  - Negative examples: Just swap the ordering of sentences

## **CHANGES IN PRE-TRAINING**

#### Illustration:



### **Effectiveness:**

	Intrinsic Tasks			Downstream Tasks					
SP tasks	MLM	NSP	SOP	SQuAD1.1	SQuAD2.0	MNLI	SST-2	RACE	Avg
None	54.9	52.4	53.3	88.6/81.5	78.1/75.3	81.5	89.9	61.7	79.0
NSP	54.5	90.5	52.0	88.4/81.5	77.2/74.6	81.6	91.1	62.3	79.2
SOP	54.0	78.9	86.5	89.3/82.3	80.0/77.1	82.0	90.3	64.0	80.1

Table 5: The effect of sentence-prediction loss, NSP vs. SOP, on intrinsic and downstream tasks.



## **CHANGES IN PRE-TRAINING**

## n-gram masking for the MLM task

- During pre-training BERT single tokens are masked
- Lan et al. mask up to three consecutive tokens
- Choice of n:

$$p(n) = \frac{1/n}{\sum_{k=1}^{N} 1/k}$$

## **PERFORMANCE**

#### Performance differences:

Mod	iel	Parameters	SQuAD1.1	SQuAD2.0	MNLI	SST-2	RACE	Avg	Speedup
	base	108M	90.4/83.2	80.4/77.6	84.5	92.8	68.2	82.3	4.7x
BERT	large	334M	92.2/85.5	85.0/82.2	86.6	93.0	73.9	85.2	1.0
ALBERT	base	12M	89.3/82.3	80.0/77.1	81.6	90.3	64.0	80.1	5.6x
	large	18M	90.6/83.9	82.3/79.4	83.5	91.7	68.5	82.4	1.7x
	xlarge	60M	92.5/86.1	86.1/83.1	86.4	92.4	74.8	85.5	0.6x
	xxlarge	235M	94.1/88.3	88.1/85.1	88.0	95.2	82.3	88.7	0.3x

➤ Source: Lan et al., 2019

### Notes:

- In General: Smaller model size (because of parameter sharing)
- Nevertheless: Scale model up to almost similar size (xxlarge version)
- Strong performance compared to BERT