

Derivative Free Optimization

**Solution 1: Coordinate Descent I**

$$\begin{aligned}\mathcal{R}_{\text{emp}}(\boldsymbol{\theta}) &= \frac{1}{2}\|\mathbf{X}\boldsymbol{\theta} - \mathbf{y}\|_2^2 + \frac{\lambda}{2}\|\boldsymbol{\theta}\|_2^2 = \frac{1}{2}\mathbf{y}^\top \mathbf{y} - \mathbf{y}^\top \mathbf{X}\boldsymbol{\theta} + \frac{1}{2}\boldsymbol{\theta}^\top \boldsymbol{\theta} + \frac{\lambda}{2}\boldsymbol{\theta}^\top \boldsymbol{\theta} \\ &= \frac{1}{2}\mathbf{y}^\top \mathbf{y} - \sum_{j=1}^d \mathbf{y}^\top \mathbf{x}_j \theta_j + \frac{1}{2}(1 + \lambda)\boldsymbol{\theta}^\top \boldsymbol{\theta} \\ \frac{\partial \mathcal{R}_{\text{emp}}}{\partial \theta_j} &= (1 + \lambda)\theta_j - \mathbf{y}^\top \mathbf{x}_j \stackrel{!}{=} 0 \\ \Rightarrow \theta_j^* &= \frac{\mathbf{y}^\top \mathbf{x}_j}{1 + \lambda}\end{aligned}$$

**Solution 2: Coordinate Descent II**

- (a) Update  $x_1$  while fixing  $x_2$ : We fix  $x_2 = c$  (constant). The function then states as

$$g(x_1, c) = |x_1 - c| + 0.1(x_1 + c).$$

We want to choose  $x_1$  to minimize this. Due to the absolute value, there are two cases.

- (i) Case 1:  $x_1 \geq c$ : Then  $|x_1 - c| = x_1 - c$ . So  $g(x_1, c) = (x_1 - c) + 0.1x_1 + 0.1c = 1.1x_1 - 0.9c$ . As a function of  $x_1$  this is strictly increasing (derivative of  $1.1 > 0$ ). Therefore, the minimizer given  $x_1 \geq c$  is at the left boundary, i.e.,  $x_1 = c$ .
- (ii) Case 2:  $x_1 < c$ : Then  $|x_1 - c| = c - x_1$ . So  $g(x_1, c) = (c - x_1) + 0.1x_1 + 0.1c = 1.1c - 0.9x_1$ . As a function of  $x_1$  this is strictly decreasing (derivative of  $-0.9 < 0$ ). Therefore, the minimizer given  $x_1 < c$  is at the right boundary, i.e.,  $x_1 = c$ .

In both cases, the best choice is  $x_1^* = c$ . Note that  $x_2$  was fixed to be  $c$ , i.e., the function is minimized exactly when  $x_1 = x_2$ .

After updating  $x_1$  while holding  $x_2$  constant, we arrive at  $(x_1^{[1]}, x_2^{[0]}) = (x_2^{[0]}, x_2^{[0]})$ .

Update  $x_2$  while fixing  $x_1$ : We now fix  $x_1 = c$  (constant). The function then states as

$$g(c, x_2) = |c - x_2| + 0.1(c + x_2).$$

Note that  $g$  is symmetric in its arguments, therefore based on the first analysis, we conclude that again  $x_2^* = c$ .

After updating  $x_2$  while holding  $x_1$  constant, we arrive at  $(x_1^{[1]}, x_2^{[1]}) = (x_1^{[1]}, x_1^{[1]}) = (x_2^{[0]}, x_2^{[0]})$ .

We observe that coordinate updates will set the respective coordinate to the value of the other constant held coordinate value and once the algorithm arrives at  $x_1 = x_2 = c$ , neither coordinate update will move the point.

- (b) Along the diagonal  $x_1 = x_2 = t$ , the function simplifies to

$$g(t, t) = |t - t| + 0.1(t + t) = 0.2t.$$

As  $t \rightarrow -\infty$ ,  $0.2t \rightarrow -\infty$ , hence the infimum of  $g$  is  $-\infty$ . No finite  $(x_1, x_2)$  can achieve that infimum, i.e., there is no global minimizer, but the values of  $g$  can be made arbitrarily negative by letting  $x_1, x_2$  be arbitrarily negative.