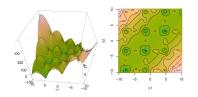
Optimization in Machine Learning

First order methods GD – Multimodality and Saddle points

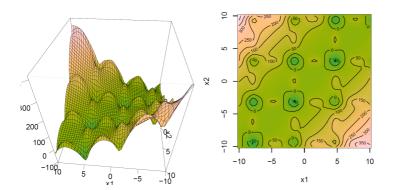




Learning goals

- Multimodality, GD result can be arbitrarily bad
- Saddle points, major problem in NN error landscapes, GD can get stuck or slow crawling

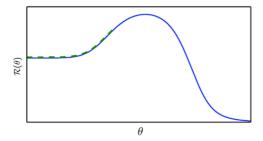
UNIMODAL VS. MULTIMODAL LOSS SURFACES



Snippet of a loss surface with many local optima

GD: ONLY LOCALLY OPTIMAL MOVES

- GD makes only locally optimal moves
- It may move away from the global optimum



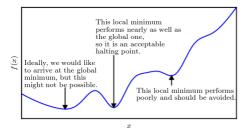
Source: Goodfellow et al., 2016

- Initialization on "wrong" side of the hill results in weak performance
- In higher dimensions, GD may move around the hill (potentially at the cost of longer trajectory and time to convergence)



LOCAL MINIMA

• In practice: Only local minima with high value compared to global minimium are problematic.







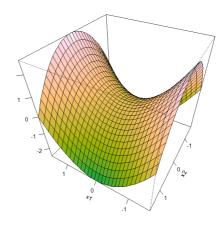
GD AT SADDLE POINTS

Example:

$$f(x_1, x_2) = x_1^2 - x_2^2$$

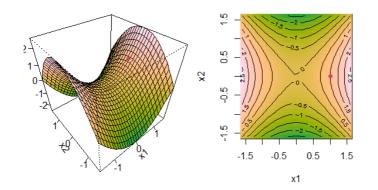
 $\nabla f(x_1, x_2) = (2x_1, -2x_2)^{\top}$
 $\mathbf{H} = \begin{pmatrix} 2 & 0 \\ 0 & -2 \end{pmatrix}$

- Along x_1 , curvature is positive ($\lambda_1 = 2 > 0$).
- Along x_2 , curvature is negative ($\lambda_2 = -2 < 0$).





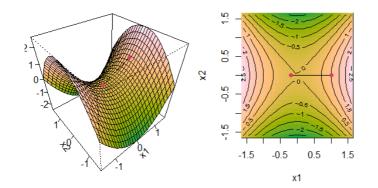
- How do saddle points impair optimization?
- Gradient-based algorithms **might** get stuck in saddle points



Red dot: Starting location



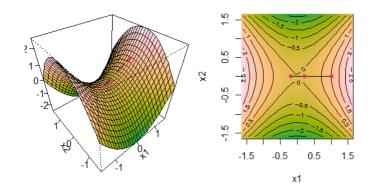
- How do saddle points impair optimization?
- Gradient-based algorithms **might** get stuck in saddle points



Step 1 ...



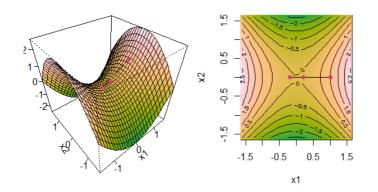
- How do saddle points impair optimization?
- Gradient-based algorithms **might** get stuck in saddle points



... Step 2 ...



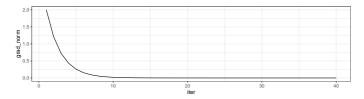
- How do saddle points impair optimization?
- Gradient-based algorithms might get stuck in saddle points



... Step 10 ... got stuck and cannot escape saddle point



- How do saddle points impair optimization?
- Gradient-based algorithms **might** get stuck in saddle points



... Step 10 ... got stuck and cannot escape saddle point



SADDLE POINTS IN NEURAL NETWORKS

- For the empirical risk $\mathcal{R}:\mathbb{R}^d\to\mathbb{R}$ of a neural network, the expected ratio of the number of saddle points to local minima typically grows exponentially with d
- In other words: Networks with more parameters (deeper networks or larger layers) exhibit a lot more saddle points than local minima
- Reason: Hessian at local minimum has only positive eigenvalues.
 Hessian at saddle point has positive and negative eigenvalues.

