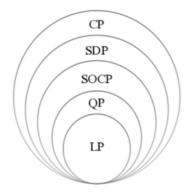
Optimization in Machine Learning Algorithms for linear programs





Learning goals

- Definition
- Max. Likelihood
- Normal regression
- Risk Minimization

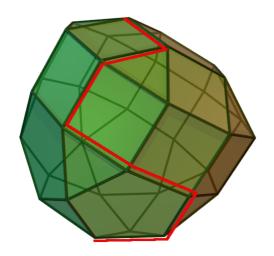
The Simplex algorithm is the most important method for solving Linear programming. It was published in 1947 by Georg Dantzig.

Basic idea: start from an arbitrary corner of the polytope. Run along this edge as long as the solution improves. Find a new edge, ...

Output: a path along the corners of the polytope that ends at the optimal point of the polytope.

Since linear programming is a **convex** optimization problem, the optimal corner found in this way is also a global optimum.







The simplex algorithm can be divided into two steps:

- Phase I: determination of a starting point
- Phase II: determination of the optimal solution

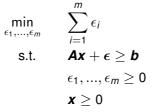
To be able to start, a starting point must first be found in **Phase I**, i.e. a feasible corner x_0 .

In **phase II** this solution is iteratively improved by searching for an edge that improves the solution and running along it to the next corner.



Phase I:

One way to find a starting point x_0 is to solve a auxiliary linear problem with artificial variables ϵ :



ullet A feasible starting point for the auxiliary problem is ${m x}={m 0}$ and

$$\epsilon_i = \begin{cases} 0 & \text{if } b_i < 0 \\ b_i & \text{if } b_i \ge 0 \end{cases}$$



- We then apply phase II of the simplex algorithm to the auxiliary problem.
- If the original problem has a feasible solution, then the optimal solution of the auxiliary problem **must** be $\epsilon = (0, ..., 0)$ (all artificial variables disappear) and the objective function is 0.
- If we find a solution with $\epsilon = \mathbf{0}$, then we have found a valid starting point.
- If we do not find a solution with $\epsilon=\mathbf{0}$, the problem can not be solved.



Example:

A starting point is the corner (0,0).



