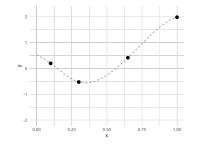
Optimization in Machine Learning

Bayesian Optimization Basic BO Loop and Surrogate Modelling





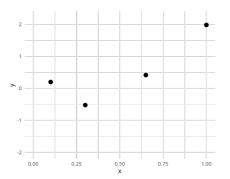
Learning goals

- Initial design
- Surrogate modeling
- Basic loop

OPTIMIZATION VIA SURROGATE MODELING

Starting point:

- ullet We do not know the objective function $f:\mathcal{S} \to \mathbb{R}$
- ullet But we can evaluate f for a few different inputs ${f x} \in \mathcal{S}$
- For now we assume that those evaluations are noise-free
- Idea: Use the data $\mathcal{D}^{[t]} = \{(\mathbf{x}^{[i]}, y^{[i]})\}_{i=1,...t}, y^{[i]} := f(\mathbf{x}^{[i]}),$ to derive properties about the unknown function f





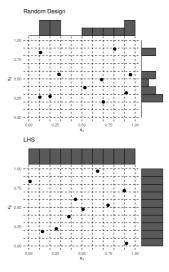
INITIAL DESIGN

- Should cover / explore input space sufficiently:
 - Random design
 - Latin hypercube sampling
 - Sobol sampling
- Type of design usually has not the largest effect
- A more important choice is the size of the initial design
 - Should neither be too small (bad initial fit) nor too large (spending too much budget without doing "intelligent" optimization)
 - Rule of thumb: 4d



LATIN HYPERCUBE SAMPLING

- LHS partitions the search space into bins of equal probability
- Goal is to attain a more even distribution of sample points than random sampling
- Allow at most one sample per bin; exactly one sample per row and column





Marginal histograms RS vs. LHS

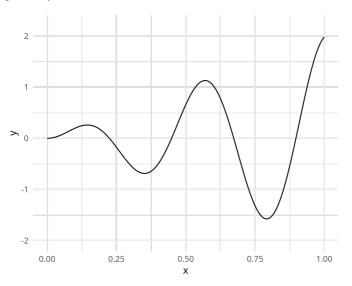
LATIN HYPERCUBE SAMPLING

Actual sampling of points, e.g., constructed via **Maximin**:

- The minimum distance between any two points in \mathcal{D} is $2q = \min_{\mathbf{x} \in \mathcal{D}, \mathbf{x}' \in \mathcal{D}} \rho(\mathbf{x}, \mathbf{x}')$ (ρ any metric, e.g., Euclidean distance)
- q is the packing radius the radius of the largest ball that can be placed around every design point such that no two balls overlap
- Goal: Find \mathcal{D} that maximizes 2q: $\max_{\mathcal{D}} \min_{\mathbf{x} \in \mathcal{D}, \mathbf{x}' \in \mathcal{D}} \rho(\mathbf{x}, \mathbf{x}')$
- \bullet Ensures that the design points in ${\mathcal D}$ are as far apart from each other as possible

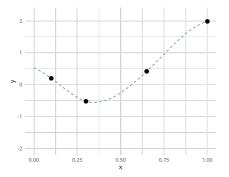


Running example = minimize this "black-box":





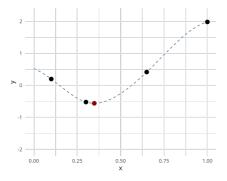
• Fit a regression model $\hat{f}: \mathcal{D}^{[t]} \to \mathbb{R}$ (blue) to extract maximum information from the design points (black) and learn properties of f



As we can eval f without noise, we fit an interpolator

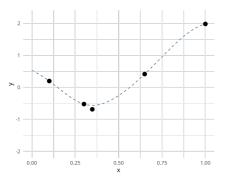


② Instead of the expensive f, we optimize the cheap surrogate \hat{f} (blue) to **propose** a new point (red) for evaluation



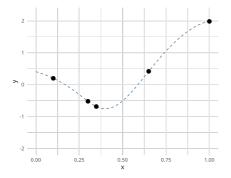


We finally evaluate the newly proposed point



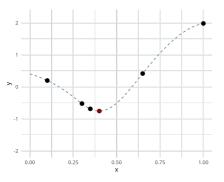


 After evaluation of the new point, we adjust the model on the expanded dataset via (slower) refitting or a (cheaper) online update



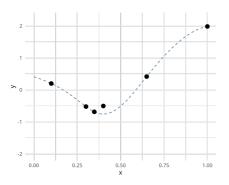


 We again obtain a new candidate point (red) by optimizing the cheap surrogate model function (blue) ...



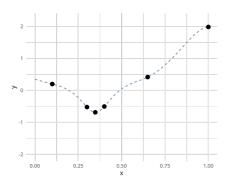


• ... and evaluate that candidate



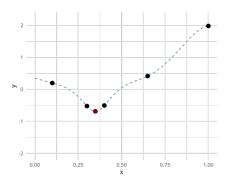


• We repeat: (i) fit the model



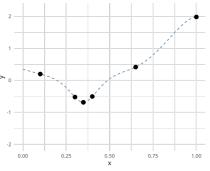


• (ii) **propose** a new point





• (iii) evaluate that point





We observe that the algorithm converged

BASIC LOOP

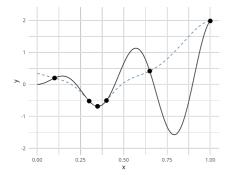
The basic loop of our sequential optimization procedure is:

- Fit surrogate model \hat{t} on previous evaluations $\mathcal{D}^{[t]} = \{(\mathbf{x}^{[i]}, y^{[i]})\}_{i=1,...,t}$
- Optimize the surrogate model \hat{f} to obtain a new point $\mathbf{x}^{[t+1]} := \arg\min_{\mathbf{x} \in \mathcal{S}} \hat{f}(\mathbf{x})$
- **3** Evaluate $\mathbf{x}^{[t+1]}$ and update data $\mathcal{D}^{[t+1]} = \mathcal{D}^{[t]} \cup \{(\mathbf{x}^{[t+1]}, f(\mathbf{x}^{[t+1]}))\}$



EXPLORATION VS. EXPLOITATION

We see: We ran into a local minimum. We did not "explore" the most crucial areas and **missed** the global minimum.



- Better ways to propose points based on our model exist, so-called acquisition functions
- Optimizing SM directly corresponds to raw / mean prediction as AQF
- Results in high exploitation but low exploration

