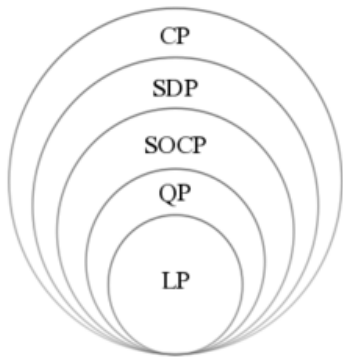


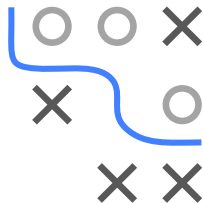
# Optimization in Machine Learning

## Linear Programming



### Learning goals

- Instances of LPs underlying statistical estimation
- Definition of an LP
- Geometric intuition of LPs



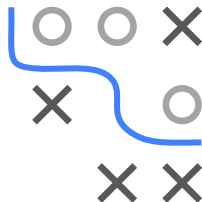
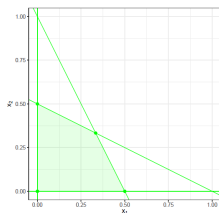
# LINEAR PROGRAMMING

Linear problems (LP):

**linear** objective function + **linear** constraints

**Example:**

$$\begin{array}{ll}\min & -x_1 - x_2 \\ \text{s.t.} & x_1 + 2x_2 \leq 1 \\ & 2x_1 + x_2 \leq 1 \\ & x_1, x_2 \geq 0\end{array}$$

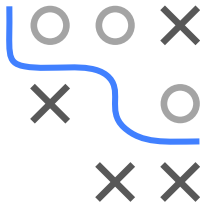


# GEOMETRIC INTERPRETATION

Linear programming can be interpreted geometrically.

## Feasible set:

- $i$ -th inequality constraint:  $\mathbf{a}_i^\top \mathbf{x} \leq b_i$
- Points  $\{\mathbf{x} : \mathbf{a}_i^\top \mathbf{x} = b_i\}$  form a hyperplane in  $\mathbb{R}^n$   
( $\mathbf{a}_i$  is perpendicular to the hyperplane and called **normal vector**)
- Points  $\{\mathbf{x} : \mathbf{a}_i^\top \mathbf{x} \geq b_i\}$  lie on the side of the hyperplane into which the normal vector points (“half-space”)



There are 3 ways to solve linear programming:

- 
- A 3x3 grid with a blue path starting at the top-left cell (0,0) and ending at the bottom-right cell (2,2). The path consists of the following cells: (0,0), (0,1), (1,1), (1,2), and (2,2). The cells (0,2), (1,0), and (2,0) are empty. The cells (1,0) and (2,0) contain a black 'X'. The cells (0,1) and (1,1) contain a grey circle. The cell (2,1) contains a grey circle.

