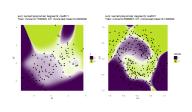
Introduction to Machine Learning

The Polynomial Kernel



Learning goals

- Know the homogeneous and non-homogeneous polynomial kernel
- Understand the influence of the choice of the degree on the decision boundary

HOMOGENEOUS POLYNOMIAL KERNEL

$$k(\mathbf{x}, \tilde{\mathbf{x}}) = (\mathbf{x}^T \tilde{\mathbf{x}})^d$$
, for $d \in \mathbb{N}$

The feature map contains all monomials of exactly order d.

$$\phi(\mathbf{x}) = \left(\sqrt{\binom{d}{k_1, \dots, k_p}} x_1^{k_1} \dots x_p^{k_p}\right)_{k_i \geq 0, \sum_i k_i = d}$$

That $\langle \phi(\mathbf{x}), \phi(\tilde{\mathbf{x}}) \rangle = k(\mathbf{x}, \tilde{\mathbf{x}})$ holds can easily be checked by simple calculation and using the multinomial formula

$$(x_1 + \ldots + x_p)^d = \sum_{k_i > 0, \sum_i k_i = d} {d \choose k_1, \ldots, k_p} x_1^{k_1} \ldots x_p^{k_p}$$

The map $\phi(\mathbf{x})$ has $\binom{p+d-1}{d}$ dimensions. We see that $\phi(\mathbf{x})$ contains no terms of "lesser" order, so, e.g., linear effects. As an example for p=d=2: $\phi(\mathbf{x})=(x_1^2,x_2^2,\sqrt{2}x_1x_2)$.

NONHOMOGENEOUS POLYNOMIAL KERNEL

$$k(\mathbf{x}, \tilde{\mathbf{x}}) = (\mathbf{x}^T \tilde{\mathbf{x}} + b)^d$$
, for $b \ge 0, d \in \mathbb{N}$

The maths is very similar as before, we kind of add a further constant term in the original space, with

$$(\mathbf{x}^T \tilde{\mathbf{x}} + b)^d = (x_1 \tilde{x}_1 + \ldots + x_p \tilde{x}_p + \sqrt{b} \sqrt{b})^d$$

The feature map contains all monomials up to order *d*.

$$\phi(\mathbf{x}) = \left(\sqrt{\binom{d}{k_1, \dots, k_{p+1}}} x_1^{k_1} \dots x_p^{k_p} b^{k_{p+1}/2}\right)_{k_i \ge 0, \sum_i k_i = d}$$

The map $\phi(\mathbf{x})$ has $\binom{p+d}{d}$ dimensions. For p=d=2:

$$\phi(\mathbf{x}) = (x_1^2, x_2^2, \sqrt{2}x_1x_2, \sqrt{2b}x_1, \sqrt{2b}x_2, b)$$

NONHOMOGENEOUS POLYNOMIAL KERNEL

The relationship between the kernel and the feature map can be shown by unraveling the polynomial formula. For p=d=2:

$$(\mathbf{x}^{T}\tilde{\mathbf{x}} + b)^{2} = \begin{pmatrix} (x_{1} \\ x_{2}) \cdot (\tilde{x}_{1} \ \tilde{x}_{2}) + b \end{pmatrix} \cdot \begin{pmatrix} (x_{1} \\ x_{2}) \cdot (\tilde{x}_{1} \ \tilde{x}_{2}) + b \end{pmatrix}$$

$$= (x_{1}\tilde{x}_{1} + x_{1}\tilde{x}_{2} + x_{2}\tilde{x}_{1} + x_{2}\tilde{x}_{2} + b) \cdot$$

$$(x_{1}\tilde{x}_{1} + x_{1}\tilde{x}_{2} + x_{2}\tilde{x}_{1} + x_{2}\tilde{x}_{2} + b)$$

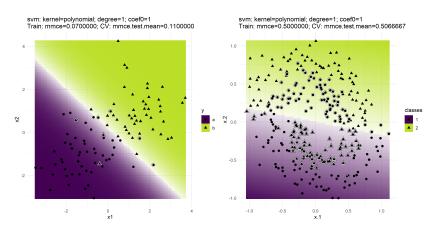
$$= x_{1}^{2}\tilde{x}_{1}^{2} + x_{2}^{2}\tilde{x}_{2}^{2} + 2x_{1}\tilde{x}_{1}x_{2}\tilde{x}_{2} + 2bx_{1}\tilde{x}_{1} + 2bx_{2}\tilde{x}_{2} + b^{2}$$

$$= (x_{1}^{2}, x_{2}^{2}, \sqrt{2}x_{1}x_{2}, \sqrt{2b}x_{1}, \sqrt{2b}x_{2}, b)^{T} \cdot$$

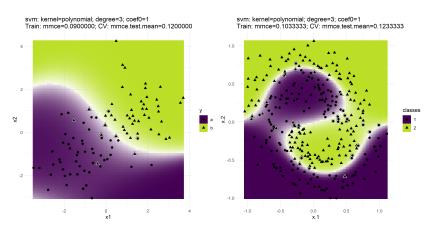
$$(\tilde{x}_{1}^{2}, \tilde{x}_{2}^{2}, \sqrt{2}\tilde{x}_{1}\tilde{x}_{2}, \sqrt{2b}\tilde{x}_{1}, \sqrt{2b}\tilde{x}_{2}, b)$$

$$= \phi(\mathbf{x})^{T} \cdot \phi(\tilde{\mathbf{x}})$$

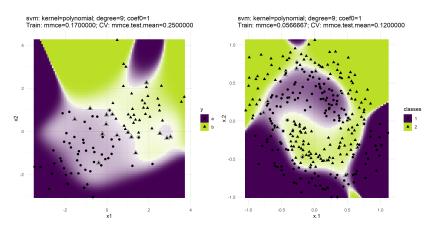
Degree d = 1 yields a linear decision boundary.



The higher the degree, the more nonlinearity in the decision boundary.



The higher the degree, the more nonlinearity in the decision boundary.



For $k(\mathbf{x}, \tilde{\mathbf{x}}) = (\mathbf{x}^{\top} \tilde{\mathbf{x}} + 0)^d$ we get no lower order effects.

