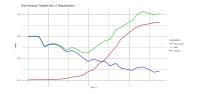
Introduction to Machine Learning

Regularization
Perspectives on Ridge Regression
(Deep-Dive)





Learning goals

- Interpretation of L2 regularization as row-augmentation
- Interpretation of L2 regularization as minimizing risk under feature noise

PERSPECTIVES ON L2 REGULARIZATION I

We already saw two interpretations of *L*2 regularization.

• We know that it is equivalent to a constrained optimization problem:

$$\hat{\theta}_{\text{ridge}} = \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2} + \lambda \|\boldsymbol{\theta}\|_{2}^{2} = (\mathbf{X}^{\mathsf{T}} \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^{\mathsf{T}} \mathbf{y}$$

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For some t depending on λ this is equivalent to:

$$\hat{\theta}_{\mathsf{ridge}} = \underset{\boldsymbol{\theta}}{\operatorname{arg min}} \sum_{i=1}^{n} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2} \text{ s.t. } \|\boldsymbol{\theta}\|_{2}^{2} \leq t$$

• Bayesian interpretation of ridge regression: For additive Gaussian errors $\mathcal{N}(\mathbf{0},\sigma^2)$ and i.i.d. normal priors $\theta_j \sim \mathcal{N}(\mathbf{0},\tau^2)$, the resulting MAP estimate is $\hat{\theta}_{\text{ridge}}$ with $\lambda = \frac{\sigma^2}{\tau^2}$:

$$\hat{\theta}_{\mathsf{MAP}} = \argmax_{\theta} \log[p(\mathbf{y}|\mathbf{X}, \boldsymbol{\theta})p(\boldsymbol{\theta})] = \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2} + \frac{\sigma^{2}}{\tau^{2}} \|\boldsymbol{\theta}\|_{2}^{2}$$

L2 AND ROW-AUGMENTATION I

We can also recover the ridge estimator by performing least-squares on a row-augmented data set: Let $\tilde{\mathbf{X}} := \begin{pmatrix} \mathbf{X} \\ \sqrt{\lambda} \mathbf{I}_{\mathbf{0}} \end{pmatrix}$ and $\tilde{\mathbf{y}} := \begin{pmatrix} \mathbf{y} \\ \mathbf{0}_{\mathbf{0}} \end{pmatrix}$.

a **row-augmented** data set: Let
$$\tilde{\mathbf{X}} := \begin{pmatrix} \mathbf{X} \\ \sqrt{\lambda} \mathbf{I}_p \end{pmatrix}$$
 and $\tilde{\mathbf{y}} := \begin{pmatrix} \mathbf{y} \\ \mathbf{0}_p \end{pmatrix}$. With the augmented data, the unreg. least-squares solution $\tilde{\boldsymbol{\theta}}$ is:

$$\tilde{\boldsymbol{\theta}} = \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n+p} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{T} \boldsymbol{x}^{(i)} \right)^{2}$$

$$= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{T} \boldsymbol{x}^{(i)} \right)^{2} + \sum_{j=1}^{p} \left(0 - \sqrt{\lambda} \theta_{j} \right)^{2}$$

$$= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{T} \boldsymbol{x}^{(i)} \right)^{2} + \lambda \|\boldsymbol{\theta}\|_{2}^{2}$$



This is a sometimes useful "recasting" or "rewriting" for ridge.



L2 AND NOISY FEATURES I

Now consider perturbed features $\tilde{x}^{(i)} := \mathbf{x}^{(i)} + \delta^{(i)}$ where $\delta^{(i)} \stackrel{\textit{iid}}{\sim} (\mathbf{0}, \lambda \mathbf{I_p})$. We assume no specific distribution. Now minimize risk with L2 loss, we define it slightly different than usual, as here our data $\mathbf{x}^{(i)}$, $y^{(i)}$ are fixed, but we integrate over the random permutations δ :

$$\begin{split} \mathcal{R}(\boldsymbol{\theta}) &:= \mathbb{E}_{\boldsymbol{\delta}} \left[\sum_{i=1}^{n} (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{\top} \tilde{\boldsymbol{x}}^{(i)})^{2} \right] = \mathbb{E}_{\boldsymbol{\delta}} \left[\sum_{i=1}^{n} (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{\top} (\boldsymbol{x}^{(i)} + \boldsymbol{\delta}^{(i)}))^{2} \right] \ \middle| \ \text{expand} \\ \mathcal{R}(\boldsymbol{\theta}) &= \mathbb{E}_{\boldsymbol{\delta}} \left[\sum_{i=1}^{n} ((\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{\top} \boldsymbol{x}^{(i)})^{2} - 2\boldsymbol{\theta}^{\top} \boldsymbol{\delta}^{(i)} (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{\top} \boldsymbol{x}^{(i)}) + \boldsymbol{\theta}^{\top} \boldsymbol{\delta}^{(i)} \boldsymbol{\delta}^{(i)\top} \boldsymbol{\theta}) \right] \end{split}$$

By linearity of expectation, $\mathbb{E}_{\delta}[\delta^{(i)}] = \mathbf{0}_{p}$ and $\mathbb{E}_{\delta}[\delta^{(i)}\delta^{(i)\top}] = \lambda \mathbf{I}_{p}$, this is

$$\mathcal{R}(\boldsymbol{\theta}) = \sum_{i=1}^{n} ((\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)})^{2} - 2\boldsymbol{\theta}^{\top} \mathbb{E}_{\boldsymbol{\delta}} [\boldsymbol{\delta}^{(i)}] (\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)}) + \boldsymbol{\theta}^{\top} \mathbb{E}_{\boldsymbol{\delta}} [\boldsymbol{\delta}^{(i)} \boldsymbol{\delta}^{(i)\top}] \boldsymbol{\theta})$$
$$= \sum_{i=1}^{n} (\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)})^{2} + \lambda \|\boldsymbol{\theta}\|_{2}^{2}$$

 \implies Ridge regression on unperturbed features $\mathbf{x}^{(i)}$ turns out to be the same as minimizing squared loss averaged over feature noise distribution!