# **Introduction to Machine Learning**

Advanced Risk Minimization
Bias-Variance 2:
Approximation and Estimation error





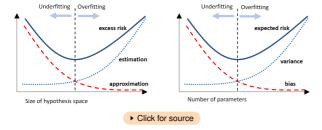
#### Learning goals

- Decomposing excess risk
- Into estimation, approx. and optim. error

• BV decomp often confused with related (but different) decomp:

$$\underbrace{\mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}_{\mathit{all}}})}_{\text{excess risk}} = \underbrace{\mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}})}_{\text{estimation error}} + \underbrace{\mathcal{R}(\mathit{f}^*_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}_{\mathit{all}}})}_{\text{approx. error}}$$

Both commonly described using same figure and analogies



BV decomp. only holds for certain losses, above is universal



## APPROX./ESTIMATION ERROR > Brown and Ali 2024

- Approx. error is a structural property of  $\mathcal{H}$
- Estimation error is random due to dependence on data in  $\hat{f}$
- Estimation error occurs as we choose  $f \in \mathcal{H}$  with limited train data minimizing  $\mathcal{R}_{\mathsf{emp}}$  instead of  $\mathcal{R}$
- Knowing  $\hat{f}_{\mathcal{H}} \in \arg\inf_{f \in \mathcal{H}} \mathcal{R}_{emp}(f)$  assumes we found a global minimizer of  $\mathcal{R}_{emp}$ , which is often impossible (e.g. ANNs)
- In practice, optimizing  $\mathcal{R}_{emp}$  gives us "best guess"  $\tilde{f}_{\mathcal{H}} \in \mathcal{H}$  of  $\hat{f}_{\mathcal{H}}$
- Can now decompose its excess risk finer as

$$\underbrace{\mathcal{R}(\tilde{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}\mathit{all}})}_{\text{excess risk}} = \underbrace{\mathcal{R}(\tilde{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}})}_{\text{optim. error}} + \underbrace{\mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}})}_{\text{estimation error}} + \underbrace{\mathcal{R}(\mathit{f}^*_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}\mathit{all}})}_{\text{approx. error}}$$

• NB: Optim err. can be < 0, but  $\mathcal{R}_{emp}(\tilde{t}_{\mathcal{H}}) > \mathcal{R}_{emp}(\hat{t}_{\mathcal{H}})$  always



### APPROX./ESTIMATION ERROR • Brown and Ali 2024

- We can further decompose estimation error more finely by defining the *centroid* model or "systematic" model part
- For  $\hat{t}_{\mathcal{H}} \in \arg\min_{f \in \mathcal{H}} \mathcal{R}_{emp}(f)$  centroid model under L2 loss is mean prediction at each x over all  $\mathcal{D}_n$ ,  $f_{\mathcal{H}}^{\circ} := \mathbb{E}_{\mathcal{D}_n \sim \mathbb{P}_{xy}^n}[\hat{f}_{\mathcal{H}}]$
- With  $f_{\mathcal{H}}^{\circ}$ , can decompose expected estimation error as

$$\underbrace{\mathbb{E}_{\mathcal{D}_{n} \sim \mathbb{P}_{xy}^{n}}\left[\mathcal{R}(\hat{t}_{\mathcal{H}}) - \mathcal{R}(t_{\mathcal{H}}^{*})\right]}_{\text{expected estimation error}} = \underbrace{\mathbb{E}_{\mathcal{D}_{n} \sim \mathbb{P}_{xy}^{n}}\left[\mathcal{R}(\hat{t}_{\mathcal{H}}) - \mathcal{R}(t_{\mathcal{H}}^{\circ})\right]}_{\text{estimation bias}} + \underbrace{\mathcal{R}(t_{\mathcal{H}}^{\circ}) - \mathcal{R}(t_{\mathcal{H}}^{*})}_{\text{estimation bias}}$$

- Estimation bias measures distance of centroid model to risk minimizer over  $\mathcal{H}$ .
- Estimation var. spread of ERM around centroid model induced by randomness due to  $\mathcal{D}_n$



#### APPROX./ESTIMATION ERROR • Brown and Ali 2024

- Can now connect derived quantities back to bias and variance
- Bias is not only approx. error and variance is not estimation error
- Many details skipped here, see paper!

bias = approximation error + estimation bias variance = optimization error + estimation variance



• NB: For special case of LM and L2 loss, we have very small optim / numerical error and estimation bias; so both decomps agree

