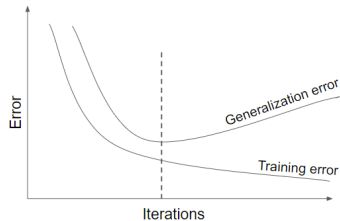
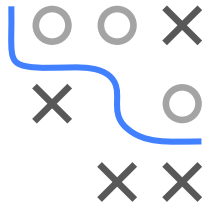


# Introduction to Machine Learning

## Regularization Early Stopping

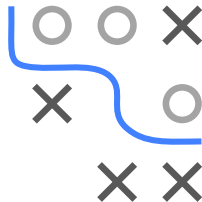
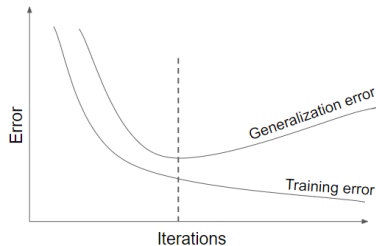


### Learning goals

- Know how early stopping works
- Understand how early stopping acts as a regularizer

# EARLY STOPPING

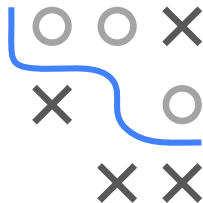
- Especially for complex nonlinear models we can easily overfit
- In optimization: Often, after a certain number of iterations, generalization error begins to increase even though training error continues to decrease



# EARLY STOPPING AND $L_2$

► Goodfellow, Bengio, and Courville 2016

Strengths	Weaknesses
Effective and simple	Periodical evaluation of validation error
Applicable to almost any model without adjustment	Temporary copy of $\theta$ (we have to save the whole model each time validation error improves)
Combinable with other regularization methods	Less data for training $\rightarrow$ include $\mathcal{D}_{\text{val}}$ afterwards



- For simple case of LM with squared loss and GD optim initialized at  $\theta = 0$ : Early stopping has exact correspondence with  $L_2$  regularization/WD: optimal early-stopping iter  $T_{\text{stop}}$  inversely proportional to  $\lambda$  scaled by step-size  $\alpha$

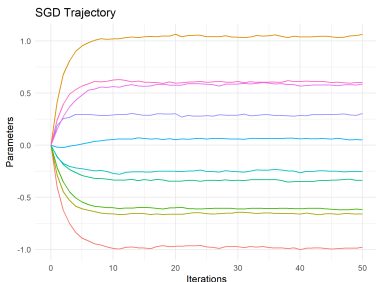
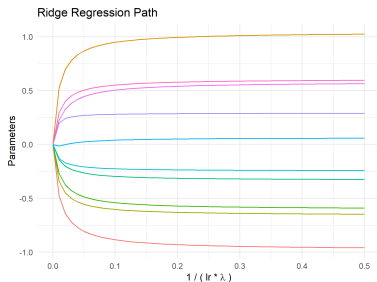
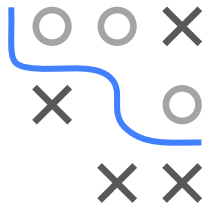
$$T_{\text{stop}} \approx \frac{1}{\alpha \lambda} \Leftrightarrow \lambda \approx \frac{1}{T_{\text{stop}} \alpha}$$

- Small  $\lambda$  ( regu.  $\downarrow$ )  $\Rightarrow$  large  $T_{\text{stop}}$  (complexity  $\uparrow$ ) and vice versa

# SGD TRAJECTORY AND $L_2$

► Ali, Dobriban, and Tibshirani 2020

Solution paths for  $L_2$  regularized linear model closely matches SGD trajectory of unregularized LM initialized at  $\theta = 0$



**Caveat:** Initialization at the origin is crucial for this equivalence to hold, which is almost never exactly used in practice in ML/DL applications