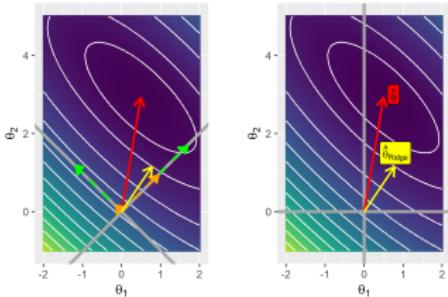


Introduction to Machine Learning

Regularization

Geometry of L2 Regularization



Learning goals

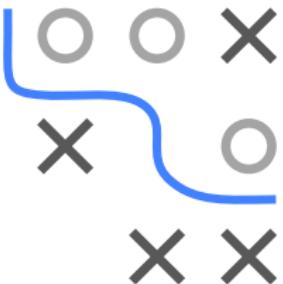
- Approximate transformation of unregularized minimizer to regularized
- Principal components of Hessian influence where parameters are decayed

GEOMETRIC ANALYSIS OF L_2 REGULARIZATION

Quadratic Taylor approx of the unregularized objective $\mathcal{R}_{\text{emp}}(\theta)$ around its minimizer $\hat{\theta}$:

$$\tilde{\mathcal{R}}_{\text{emp}}(\theta) = \mathcal{R}_{\text{emp}}(\hat{\theta}) + \nabla_{\theta} \mathcal{R}_{\text{emp}}(\hat{\theta}) \cdot (\theta - \hat{\theta}) + \frac{1}{2}(\theta - \hat{\theta})^T \mathbf{H}(\theta - \hat{\theta})$$

where \mathbf{H} is the Hessian of $\mathcal{R}_{\text{emp}}(\theta)$ at $\hat{\theta}$



We notice:

- First-order term is 0, because gradient must be 0 at minimizer
- \mathbf{H} is positive semidefinite, because we are at the minimizer

$$\tilde{\mathcal{R}}_{\text{emp}}(\theta) = \mathcal{R}_{\text{emp}}(\hat{\theta}) + \frac{1}{2}(\theta - \hat{\theta})^T \mathbf{H}(\theta - \hat{\theta})$$

GEOMETRIC ANALYSIS OF L2 REGULARIZATION

The minimum of $\tilde{\mathcal{R}}_{\text{emp}}(\theta)$ occurs where $\nabla_{\theta}\tilde{\mathcal{R}}_{\text{emp}}(\theta) = \mathbf{H}(\theta - \hat{\theta})$ is 0.

Now we L2-regularize $\tilde{\mathcal{R}}_{\text{emp}}(\theta)$, such that

$$\tilde{\mathcal{R}}_{\text{reg}}(\theta) = \tilde{\mathcal{R}}_{\text{emp}}(\theta) + \frac{\lambda}{2} \|\theta\|_2^2$$



and solve this approximation of \mathcal{R}_{reg} for the minimizer $\hat{\theta}_{\text{ridge}}$:

$$\nabla_{\theta}\tilde{\mathcal{R}}_{\text{reg}}(\theta) = 0$$

$$\lambda\theta + \mathbf{H}(\theta - \hat{\theta}) = 0$$

$$(\mathbf{H} + \lambda\mathbf{I})\theta = \mathbf{H}\hat{\theta}$$

$$\hat{\theta}_{\text{ridge}} = (\mathbf{H} + \lambda\mathbf{I})^{-1} \mathbf{H}\hat{\theta}$$

We see: minimizer of L2-regularized version is (approximately!) transformation of minimizer of the unpenalized version.

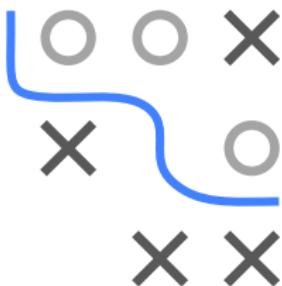
Doesn't matter whether the model is an LM – or something else!

GEOMETRIC ANALYSIS OF L2 REGULARIZATION

- As λ approaches 0, the regularized solution $\hat{\theta}_{\text{ridge}}$ approaches $\hat{\theta}$. What happens as λ grows?
- Because H is a real symmetric matrix, it can be decomposed as $H = Q\Sigma Q^T$, where Σ is a diagonal matrix of eigenvalues and Q is an orthonormal basis of eigenvectors.
- Rewriting the transformation formula with this:

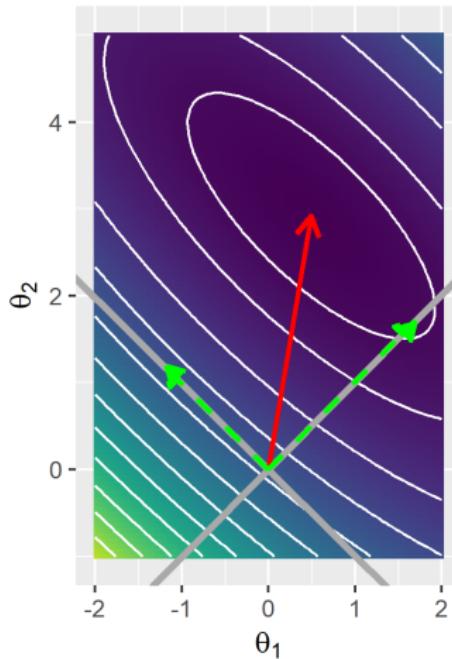
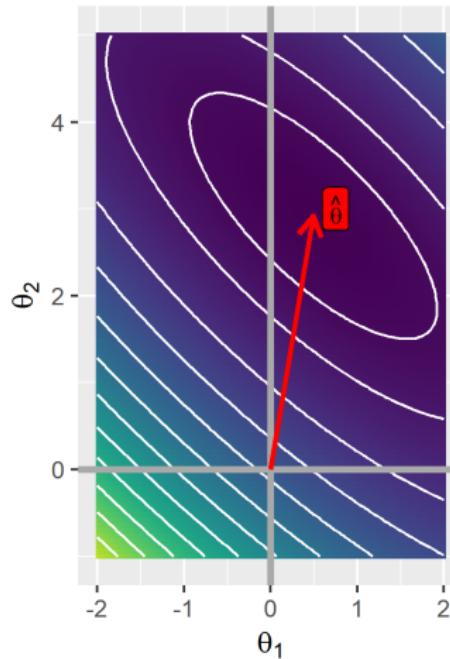
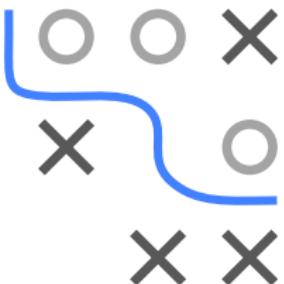
$$\begin{aligned}\hat{\theta}_{\text{ridge}} &= (Q\Sigma Q^T + \lambda I)^{-1} Q\Sigma Q^T \hat{\theta} \\ &= [Q(\Sigma + \lambda I)Q^T]^{-1} Q\Sigma Q^T \hat{\theta} \\ &= Q(\Sigma + \lambda I)^{-1} \Sigma Q^T \hat{\theta}\end{aligned}$$

- So: We rescale $\hat{\theta}$ along axes defined by eigenvectors of H . The component of $\hat{\theta}$ that is associated with the j -th eigenvector of H is rescaled by factor of $\frac{\sigma_j}{\sigma_j + \lambda}$, where σ_j is eigenvalue.



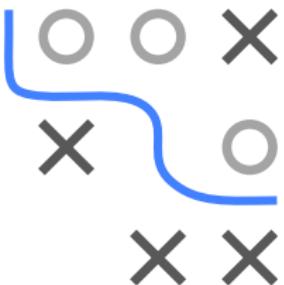
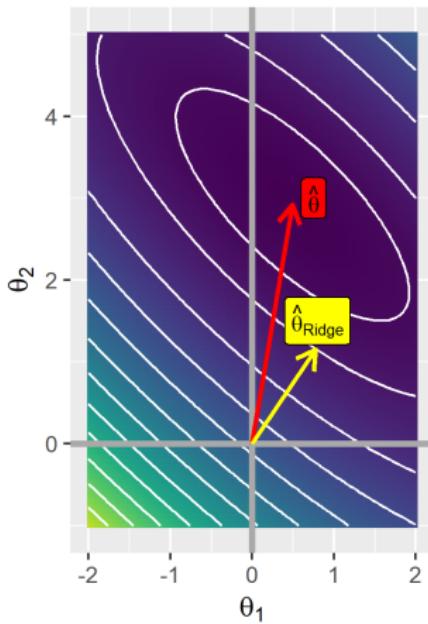
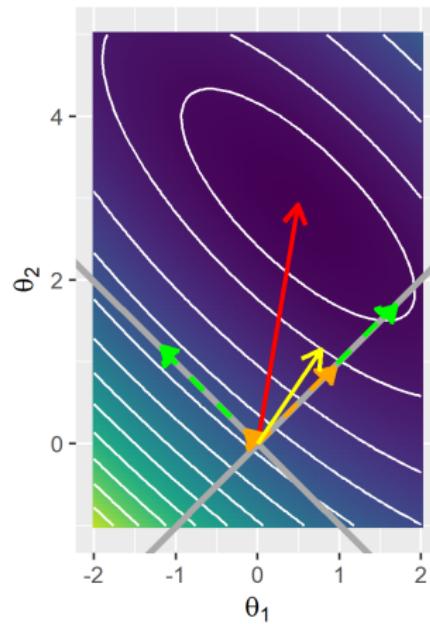
GEOMETRIC ANALYSIS OF L_2 REGULARIZATION

First, $\hat{\theta}$ is rotated by \mathbf{Q}^T , which we can interpret as projection of $\hat{\theta}$ on rotated coord system defined by principal directions of \mathbf{H} :



GEOMETRIC ANALYSIS OF L2 REGULARIZATION

j -th (new) axis is rescaled by $\frac{\sigma_j}{\sigma_j + \lambda}$ before we rotate back.



GEOMETRIC ANALYSIS OF L2 REGULARIZATION

- Decay: $\frac{\sigma_j}{\sigma_j + \lambda}$
- Along directions where eigenvalues of H are relatively large, e.g., $\sigma_j \gg \lambda$, effect of regularization is small.
- Components / directions with $\sigma_j \ll \lambda$ are strongly shrunken.
- So: Directions along which parameters contribute strongly to objective are preserved relatively intact.
- In other directions, small eigenvalue of Hessian means that moving in this direction will not decrease objective much. For such unimportant directions, corresponding components of θ are decayed away.

