

1 - Solving system of LE. (2-3)

what about the solutions?
 → Use Cramer's Rule
 → Use Gauss Gauss-Jordan
 →

2 - Operations on matrices

multiplication, addition, transpose...
 → det
 → inverse → $[A|I]$
 → adjoint

3 - Elementary Matrices

↓
determinant
Inverses

{ 4 - Vector space (why not?)
 5 - Subspace or not

$A = \begin{bmatrix} 1 & 2 & -2 \\ 1 & 0 & 4 \\ 2 & 1 & 3 \end{bmatrix}$ is given.

! $\det(AB) = \det(A)\det(B)$

a) $\det(A) = ?$

→ b) Using only $\det(A)$, find $\det(A^{-1})$, $\det(A^3)$, $\det(A^T A)$

$\det(3A)$.

→ c) Find A^{-1} using row operations.

$$\det(A) = 1 \begin{vmatrix} 0 & 4 \\ 1 & 3 \end{vmatrix} - 2 \begin{vmatrix} 1 & 4 \\ 2 & 3 \end{vmatrix} + (-2) \begin{vmatrix} 1 & 0 \\ 2 & 1 \end{vmatrix} = 4$$

-4 3-8 -2

+10

$A \cdot A^{-1} = I$
 $\det(A \cdot A^{-1}) = \det(I) = 1$
 $\det(A) \cdot \det(A^{-1}) = 1$
 $\det(A^{-1}) = \frac{1}{\det(A)} = \frac{1}{4}$

$\det(A^3) = \frac{\det(A)}{4} \cdot \frac{\det(A)}{4} \cdot \frac{\det(A)}{4} = 4^3 = 64$

$\det(A^T A) = \frac{\det(A^T)}{4} \cdot \frac{\det(A)}{4} = 16$

$\det(3A) = !$

$A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & j \end{bmatrix}$ $3A = \begin{bmatrix} 3a & 3b & 3c \\ 3d & 3e & 3f \\ 3g & 3h & 3j \end{bmatrix}$

$3r_1 \rightarrow r_1$ $3r_2 \rightarrow r_2$ $3r_3 \rightarrow r_3$
 E_3

Type-1 $(r_i \leftrightarrow r_j)$
 $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$
 $\det(E) = -1$

Type-2 $(kr_i \rightarrow r_i) \quad k \neq 0$
 $\begin{bmatrix} 1 & 0 & 0 \\ 0 & k & 0 \\ 0 & 0 & 1 \end{bmatrix}$
 $\det(E) = k$

Type-3 $(kr_j + r_i \rightarrow r_i)$
 $\begin{bmatrix} 1 & 0 & 0 \\ k & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\left. \begin{array}{l} 3r_1 \rightarrow r_1 \\ 3r_2 \rightarrow r_2 \end{array} \right\} \begin{array}{l} E_1 \\ E_2 \end{array} \quad E_3$$

type-3 ($k r_j + r_i \rightarrow r_i$)

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \rightarrow \det(E) = 1$$

$$\underline{E_3 E_2 E_1 A = 3A}$$

$$\rightarrow \det(3A) = \det(E_3 E_2 E_1 A) = \overbrace{\det(E_3)}^3 \cdot \overbrace{\det(E_2)}^3 \cdot \overbrace{\det(E_1)}^3 \cdot \overbrace{\det(A)}^4$$

$$= 27 \cdot 4$$

$A \rightarrow 3 \times 3$ matrix, $k \in \mathbb{R}$

$$\det(kA) = k \cdot k \cdot k \cdot \det(A)$$

$A \rightarrow 4 \times 4$ matrix

$$\det(kA) = k \cdot k \cdot k \cdot k \cdot \det(A)$$

$$A \rightarrow n \times n \text{ matrix} \rightarrow \det(kA) = k^n \cdot \det(A)$$

$$c) [A | I] \rightarrow [I | A^{-1}]$$

1)

$$\begin{bmatrix} 2 & 7 & 3 & 1 \\ 1 & 3 & 5 & -2 \\ 1 & 5 & -9 & 8 \\ 5 & 18 & 4 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} + \begin{bmatrix} 2 & 1 & 0 \\ 2 & -1 & 1 \\ 0 & -1 & 1 \\ -2 & 2 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} = 0$$

$4 \times 3 \quad 3 \times 1 \quad 4 \times 1$

- Write the system in the form of $Ax = b$.
- Transform the augmented matrix into RREF.
- Solve the system.

$$\begin{bmatrix} 2 & 1 & 0 \\ 2 & -1 & 1 \\ 0 & -1 & 1 \\ -2 & 2 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 5 \\ 3 \\ 1 \\ 12 \end{bmatrix}$$

$$\begin{aligned} 2 \cdot 1 + 1 \cdot 3 + 0 \cdot 4 &= 5 \\ 2 \cdot 1 + (-1) \cdot 3 + 1 \cdot 4 &= 3 \\ -2 \cdot 1 + 2 \cdot 3 + 2 \cdot 4 &= 12 \\ &6 + 8 \end{aligned}$$

$$\rightarrow \begin{bmatrix} 2 & 7 & 3 & 1 \\ 1 & 3 & 5 & -2 \\ 1 & 5 & -9 & 8 \\ 5 & 18 & 4 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -5 \\ -3 \\ -1 \\ -12 \end{bmatrix}$$

Gauss \rightarrow REF

Gauss-Jordan \rightarrow RREF

$$\begin{bmatrix} 2 & -4 & 4 & 10 \\ 0 & 1 & 2 & 0 \\ 1 & -2 & 2 & 5 \\ 4 & 4 & 5 & 6 \end{bmatrix} \xrightarrow{-2r_3 + r_1 \rightarrow r_1} \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 2 & 0 \\ 1 & -2 & 2 & 5 \\ 4 & 4 & 5 & 6 \end{bmatrix}$$

$A \quad E \quad A'$

$$\det(A') = 0$$

$$\begin{aligned} EA &= A' \\ \det(EA) &= \det(E) \det(A) = \det(A') \\ &= 1 \cdot ? = 0 \end{aligned}$$

$$\det(A) = 0$$

$$\begin{aligned} x_1 + x_2 &= 3 \\ x_1 + (a^2 - 8)x_2 &= a \end{aligned}$$

$$\begin{bmatrix} 1 & 1 & 3 \\ 1 & a^2 - 8 & a \end{bmatrix} \xrightarrow{\sim \text{REF}} \begin{bmatrix} 1 & 1 & 3 \\ 0 & a^2 - 9 & a - 3 \end{bmatrix}$$

augmented matrix

$$\begin{array}{l} x_1 + x_2 = 3 \\ x_1 + (a^2 - 8)x_2 = a \end{array} \rightarrow \left[\begin{array}{cc|c} 1 & 1 & 3 \\ 1 & a^2 - 8 & a \end{array} \right] \xrightarrow{-r_1 + r_2} \left[\begin{array}{cc|c} 1 & 1 & 3 \\ 0 & a^2 - 9 & a - 3 \end{array} \right]$$

$$(a^2 - 9)x_2 = (a - 3)$$

$a = 3 \rightarrow$ inf. many soln.

$\rightarrow \boxed{0 = \text{başka Sayı}} \rightarrow \text{no soln.}$
 $\rightarrow \boxed{0 = 0} \rightarrow \text{inf. many soln.}$
 bunlar dışında
 her bir durum \rightarrow unique.

$a \neq 3$:

$$\cancel{(a-3)}(a+3)x_2 = \cancel{(a-3)}$$

$$(a+3)x_2 = \underline{1} \quad a = -3 \rightarrow \text{no soln.}$$

$a \neq 3, -3 \Rightarrow$ unique soln. $x_2 = \frac{1}{a+3} \checkmark \rightarrow$ substitute
 find x_1