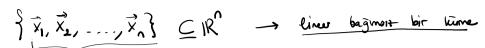
14. Hafta Çarşamba Dersi

26 Mayıs 2021 Çarşamba 08:37

Ortogonal Kûmeler, Ortogonal Batlar, Ortonormallike



Limedinin ortogonal almass: $\{\vec{y}_1, \vec{y}_2, \dots, \vec{y}_n\} \quad \vec{y}_i \perp \vec{y}_j \quad (i+j) \quad (\vec{y}_i \cdot \vec{y}_j = 0)$

standart (at: $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$ $\vec{e_1} \cdot \vec{e_2} = 1.0 + 0.1 + 0.0 = 0$ $\vec{e_1} \cdot \vec{e_3} = 1.0 + 0.0 + 0.1 = 0$ $\vec{e_2} \cdot \vec{e_3} = 0.0 + 1.0 + 0.1 = 0$

 $\vec{u_1} \cdot \vec{u_2} = 1.1 + 0.1 + 0.0 = 1$ \rightarrow ortogonal olnayon bir batdur.

veletion Winesinden news ortogonal bir kime olmayan bir * Ortogonal elde edilir?

Gram- Schmidt Ortogonallistirme

{XIX2, --, Xn} > ortogonal olvanyan | bir kine

=> {\forall \frac{1}{3} \sqrt{\frac{1}{3}} \sqrt{\f

$$\overrightarrow{y}_{1} = \overrightarrow{x}_{1} = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} \quad \overrightarrow{x}_{2} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \quad \overrightarrow{x}_{3} = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} \quad \{\overrightarrow{x}_{1}, \overrightarrow{x}_{2}, \overrightarrow{x}_{3}\} \quad \text{limes index of togard bir lime}$$

$$\overrightarrow{y}_{1} = \overrightarrow{x}_{1} = (2,0,0) \quad \xrightarrow{(2,0,0) \cdot (1,0,0)} = 2 \cdot 1 \cdot \cancel{x}_{1} \cdot \cancel{y}_{2} = 4$$

$$\overrightarrow{y}_{2} = \overrightarrow{x}_{2} - \underbrace{(2,0,0)}_{\overrightarrow{y}_{1} \cdot \overrightarrow{y}_{1}} \quad \overrightarrow{y}_{1} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \underbrace{2}_{1} \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\overrightarrow{y}_{3} = \overrightarrow{x}_{3} - \underbrace{\overrightarrow{x}_{3} \cdot \overrightarrow{y}_{1}}_{\overrightarrow{y}_{1} \cdot \overrightarrow{y}_{1}} \cdot \overrightarrow{y}_{1} - \underbrace{\overrightarrow{x}_{3} \cdot \overrightarrow{y}_{2}}_{\overrightarrow{y}_{2} \cdot \overrightarrow{y}_{2}} \cdot \overrightarrow{y}_{2} = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix} - \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

 $\frac{(-1,2,1)\cdot(2,0,0)}{4}\cdot\begin{bmatrix}2\\0\\0\end{bmatrix} \qquad \frac{(-1,2,1)\cdot(0,1,0)}{(0,1,0)\cdot(0,1,0)}\begin{bmatrix}0\\1\\0\end{bmatrix}$

 $\{\vec{y}_{1},\vec{y}_{2},\vec{y}_{3}\} = \{\begin{bmatrix}2\\0\end{bmatrix},\begin{bmatrix}0\\1\end{bmatrix},\begin{bmatrix}0\\1\end{bmatrix}\}$

Ortonormallestime

Ortonormal Kime
$$\begin{cases}
\vec{y}_1, \vec{y}_2, \dots, \vec{y}_n \\
\vec{y}_1, \vec{y}_2, \dots, \vec{y}_n
\end{cases} \rightarrow \text{ortonormal kine}$$

$$\begin{cases}
\vec{y}_1, \vec{y}_2, \dots, \vec{y}_n \\
||\vec{y}_1||, ||\vec{y}_2||, \dots, ||\vec{y}_n|| \\
(a_1, a_{1i}, a_n) \\
(b_1, b_2, \dots, b_n)
\end{cases} \xrightarrow{\text{her wetorn norms 1}} \text{otenormal kine denir.}$$

$$\Rightarrow \underbrace{a_1b_1 + a_2b_2 + \dots + a_nb_n = 0}$$

$$\frac{\vec{y}_1}{||\vec{y}_1||} \cdot \frac{\vec{y}_2}{||\vec{y}_1||} = \underbrace{a_1}_{\{\vec{z}a_1^{(1)}, \{\vec{z}b_1^{(1)}, \{\vec{z}b_1^{(1)},$$

$$= \frac{(a_1b_1 + a_2b_2 + \dots + a_nb_n)}{(\xi a_i^1)(\xi b_i^2)} = 0$$

$$\begin{cases} \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{cases} \rightarrow \text{ortogonal kine}$$

$$\begin{cases} y_1 \\ y_2 \\ y_3 \\ y_4 \end{cases} = 1$$

$$\begin{cases} y_2 \\ y_2 \\ y_3 \\ y_4 \end{cases} = 1$$