

# Visión Computacional y Machine Learning en la Industria Post-cosecha

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DataDay 2023  
EGADE, Tec de Mty  
Nov-14

# Sistema de Visión para la industria postcosecha





13 de junio de 2022

### Tomate rojo (Jitomate)

Producción 2022		Comercio exterior 2021		Semáforo
Estimada	Otoño-Invierno Abril 2022	Importaciones	Exportaciones	
<b>1,562,558</b> toneladas	<b>862,557</b> toneladas	NS toneladas	<b>1,730,149</b> toneladas	

**Evolución mensual de las importaciones y exportaciones mexicanas de jitomate 2019-2022**  
(miles de toneladas)



Nota: Los volúmenes comerciales no consideran los retornos.

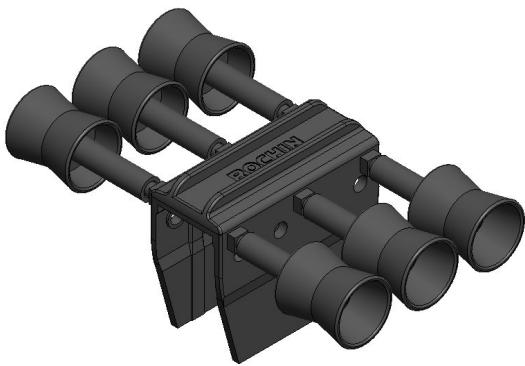
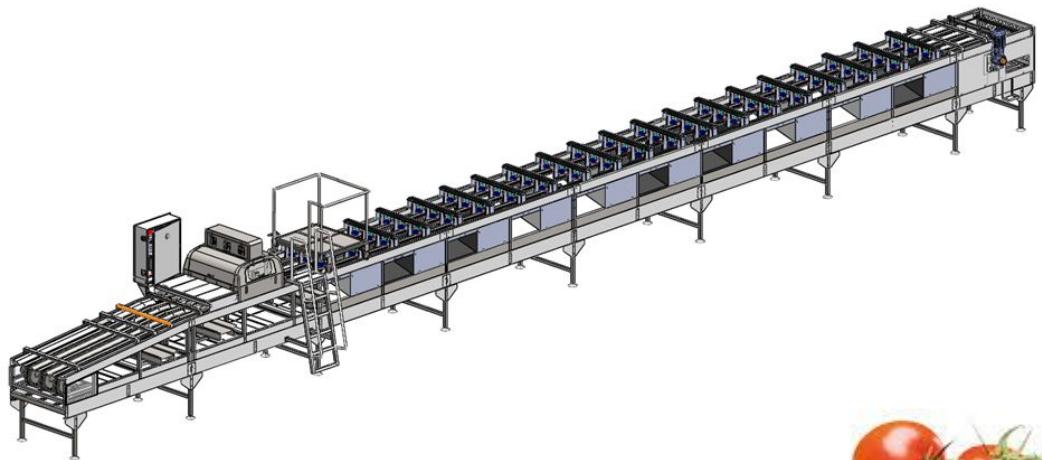
Fuente: SIAP con datos aduaneros de México.

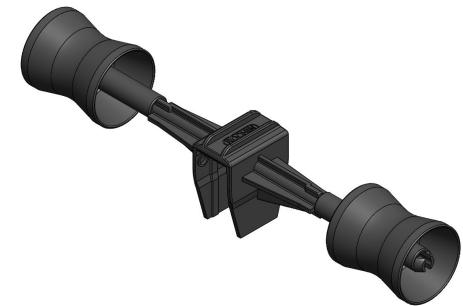
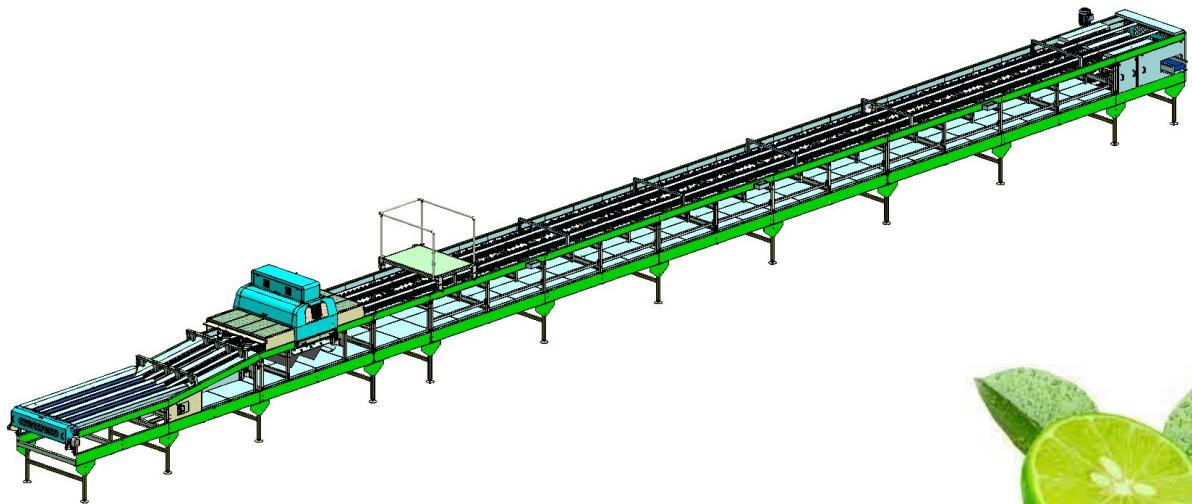
## Principales países exportadores de tomate en 2020

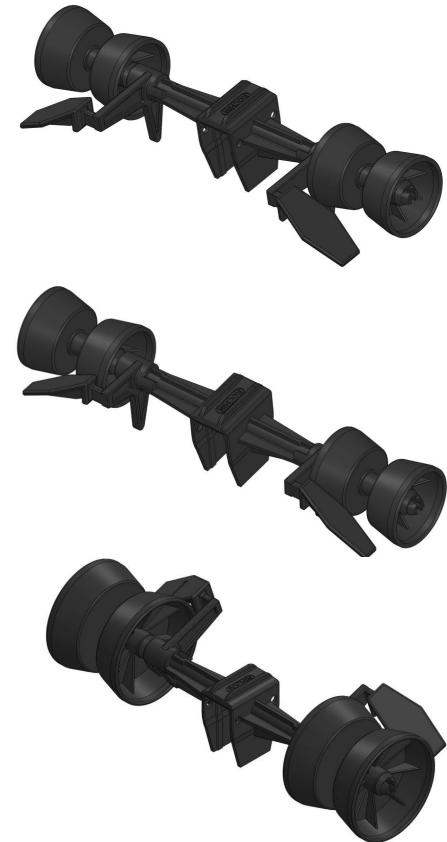
País	Volumen (t)	Volumen (%)	Valor (mdd)	Valor (%)
México	1,826,715	23.5	2,606	26.4
Países Bajos	1,024,069	13.2	1,919	19.4
España	734,223	9.4	1,074	10.9
Marruecos	596,719	7.7	770	7.8
Turquía	513,835	6.6	310	3.1

Fuente: FAO-FAOSTAT/ProducePay 2020

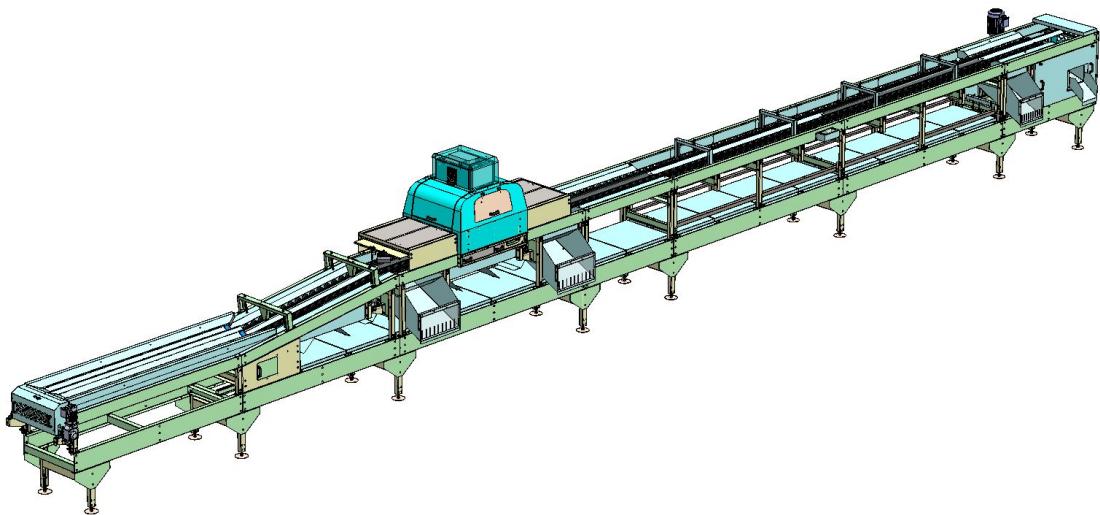
Food and Agriculture Organization (FAO)



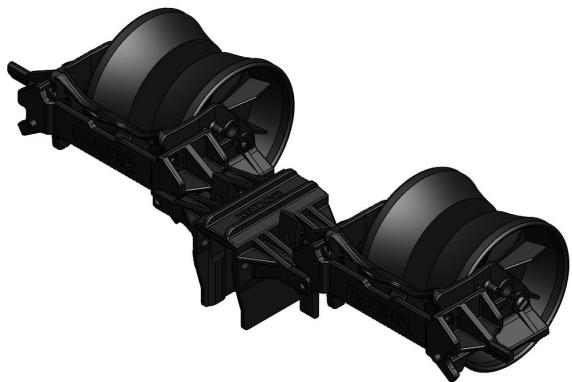
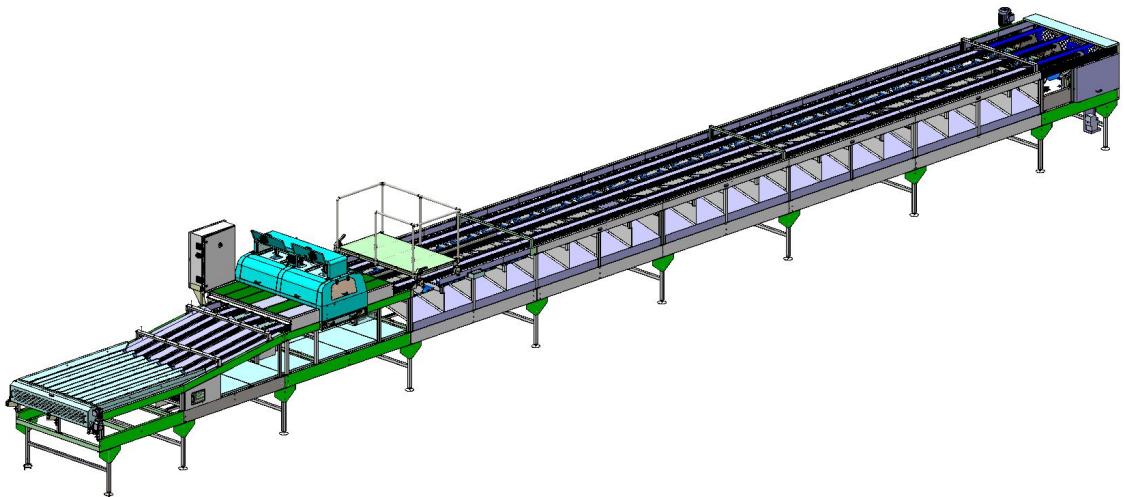




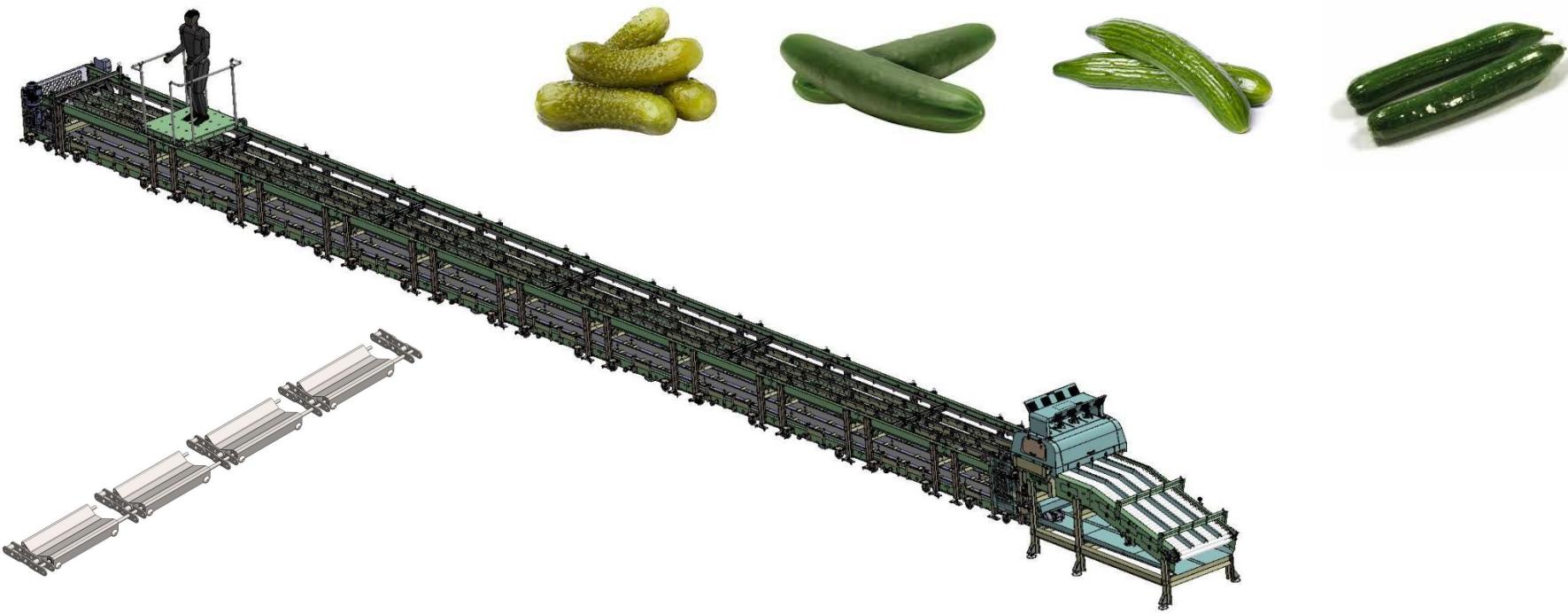
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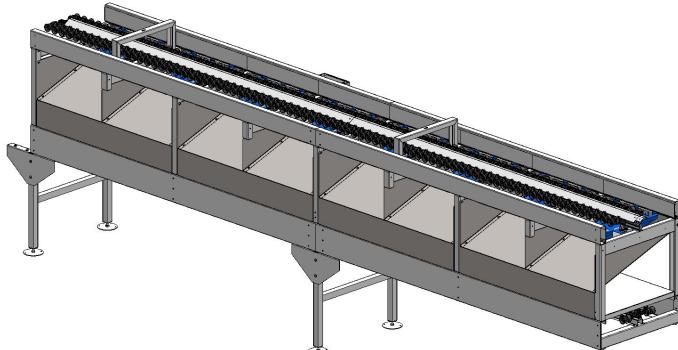


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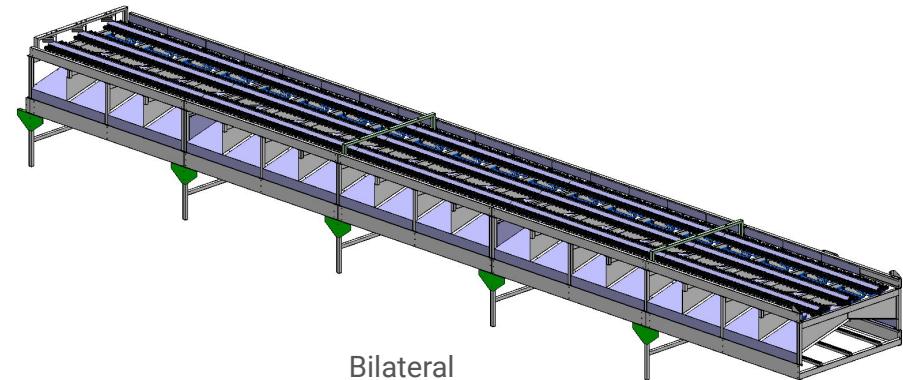


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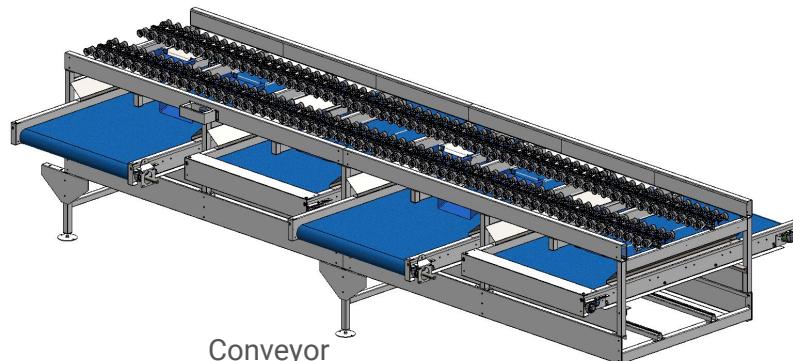
# Outlets



Lateral

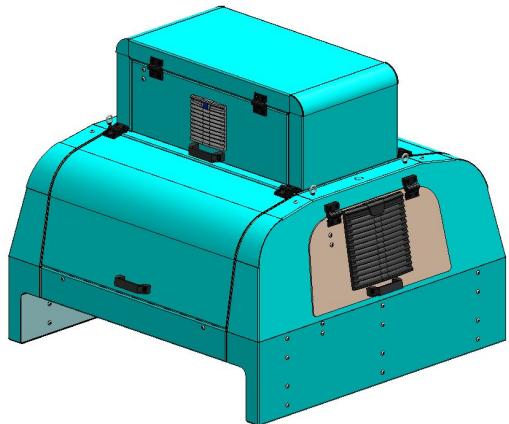


Bilateral

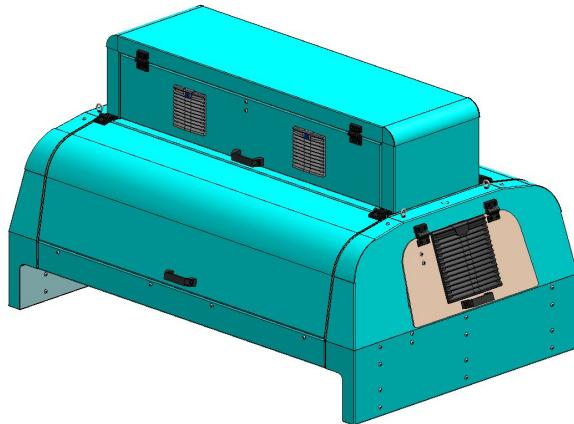


Conveyor

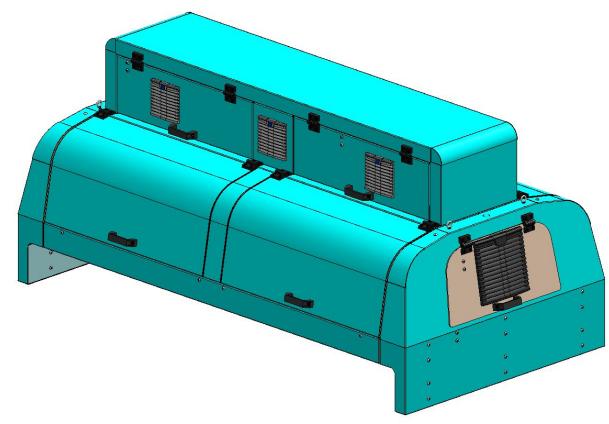
# Camera cabinet



2 lines sorter



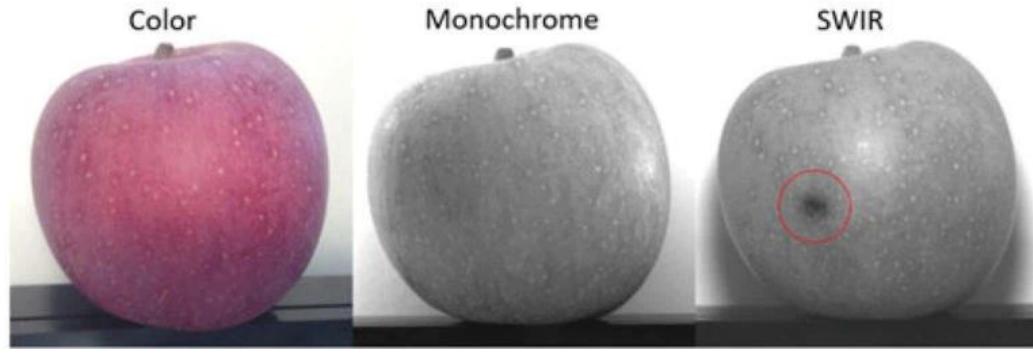
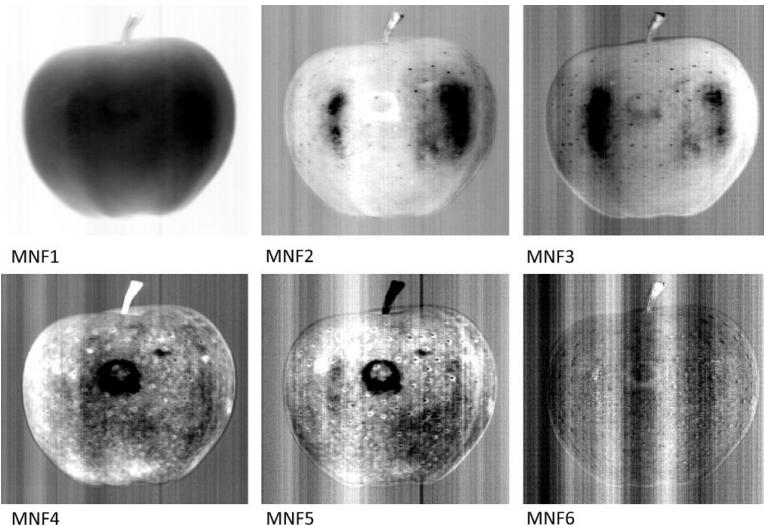
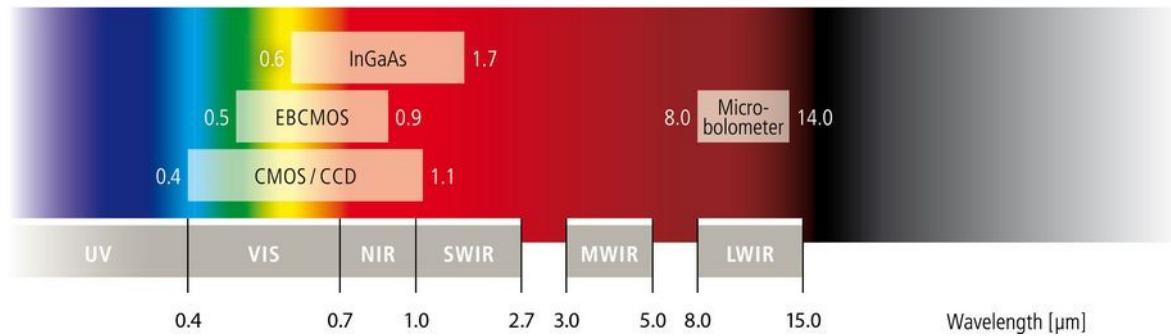
4 lines sorter



6-8 lines sorter

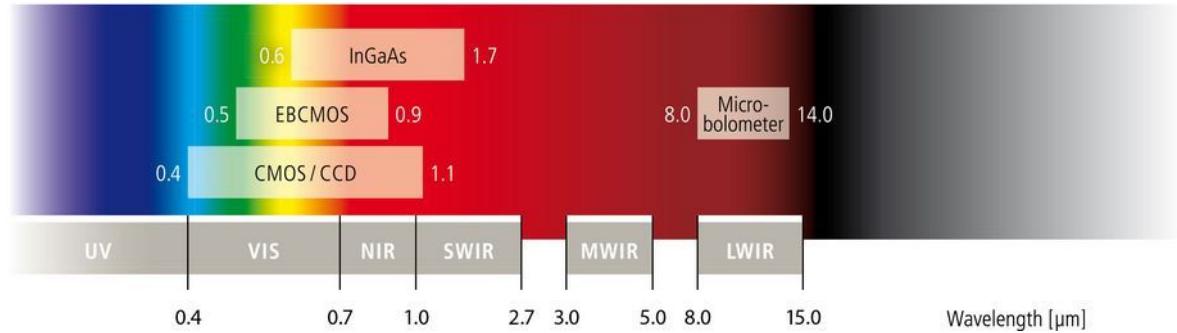
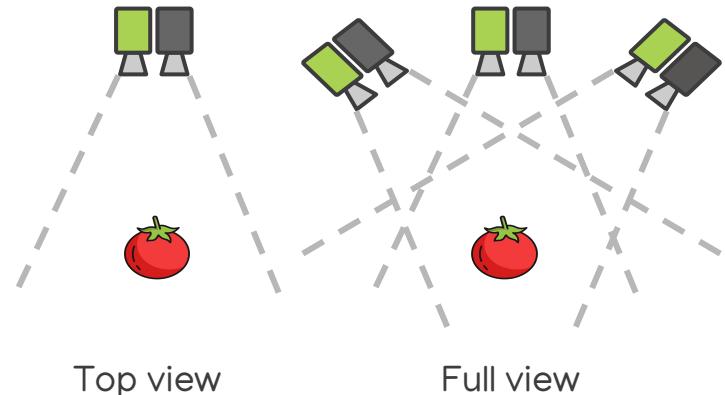
# Espectro de Luz:

- Color
- Monocromática y/o NIR (Infrarroja)
- SWIR (Mayo penetración en la piel de la fruta)

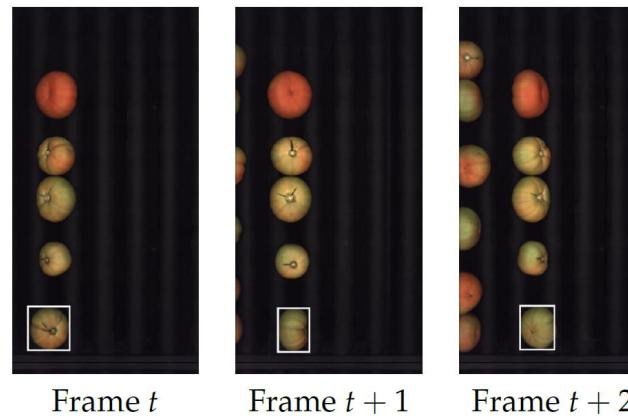
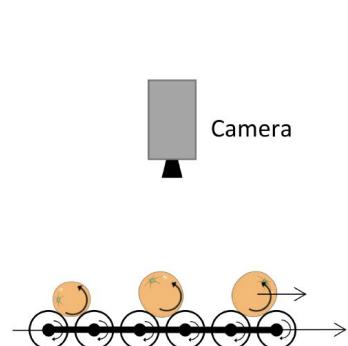
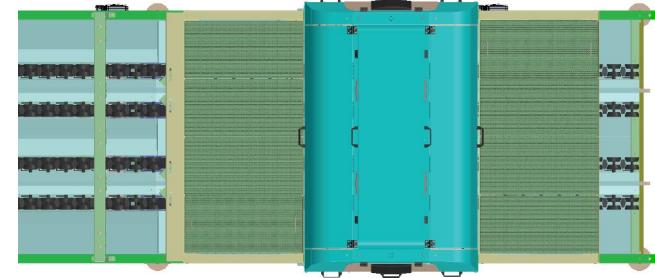
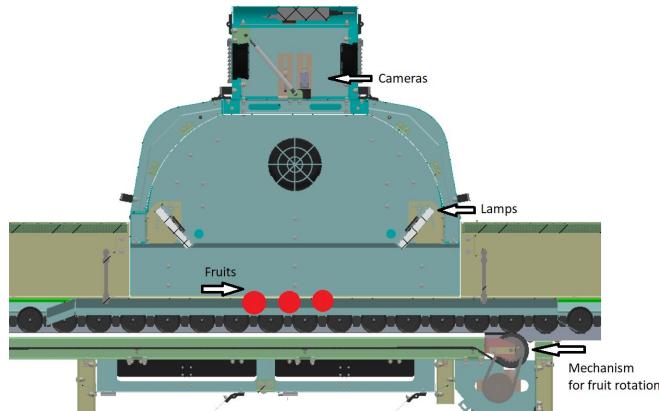


# Espectro de Luz:

- Color
- Monocromática y/o NIR (Infrarroja)
- SWIR (Mayo penetración en la piel de la fruta)



# Usual camera technologies: ***Firewire*** and ***Ethernet*** (**GigE Vision**).

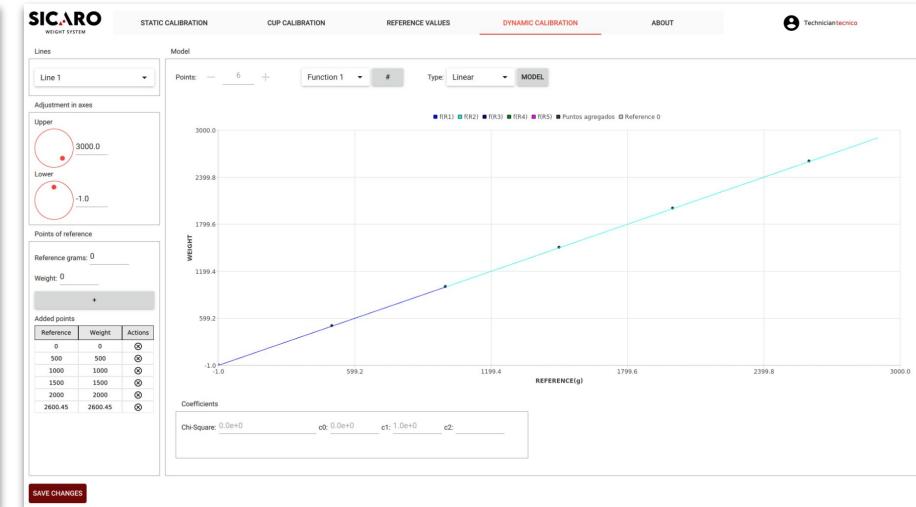


# Pesaje

Módulo para clasificar por peso, puede ser combinado para estimar densidad



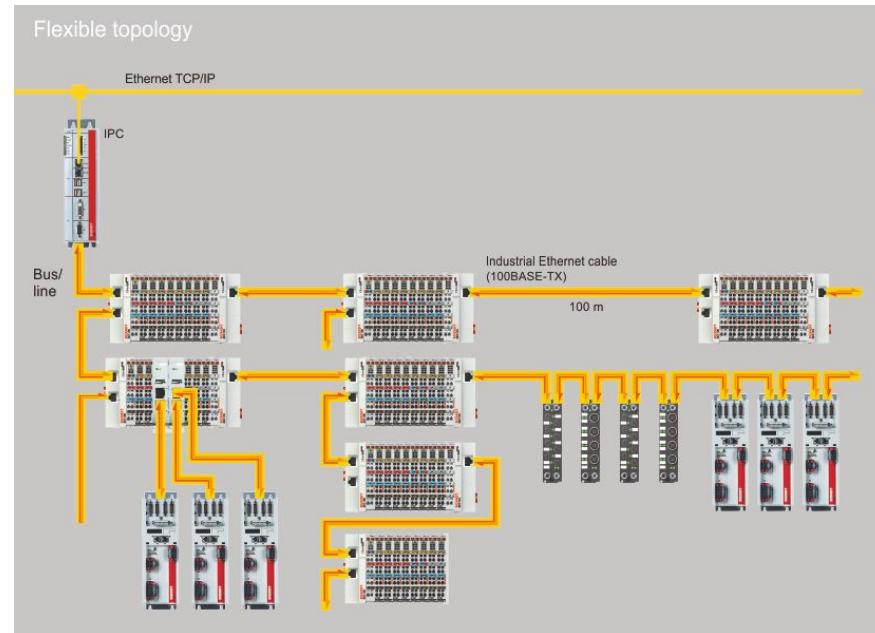
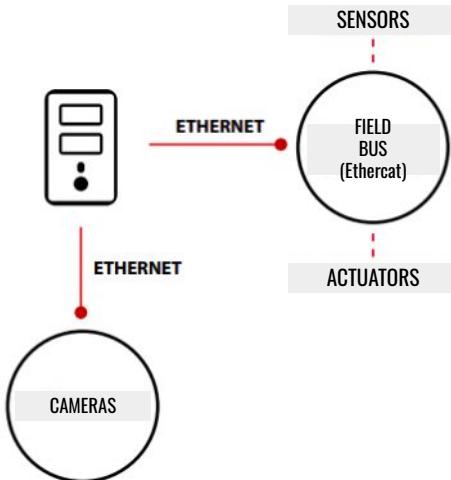
Diseño de carrier



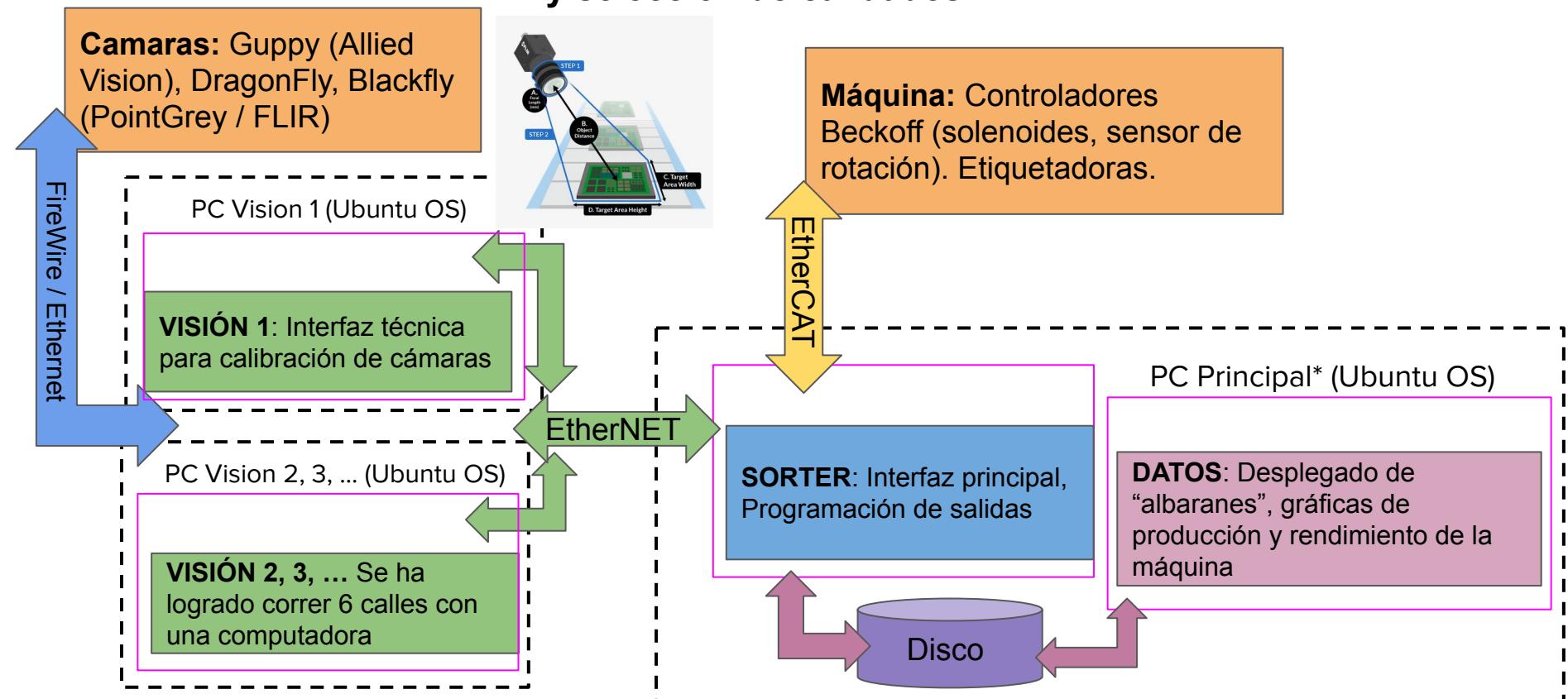
Software UI

# Industrial control bus

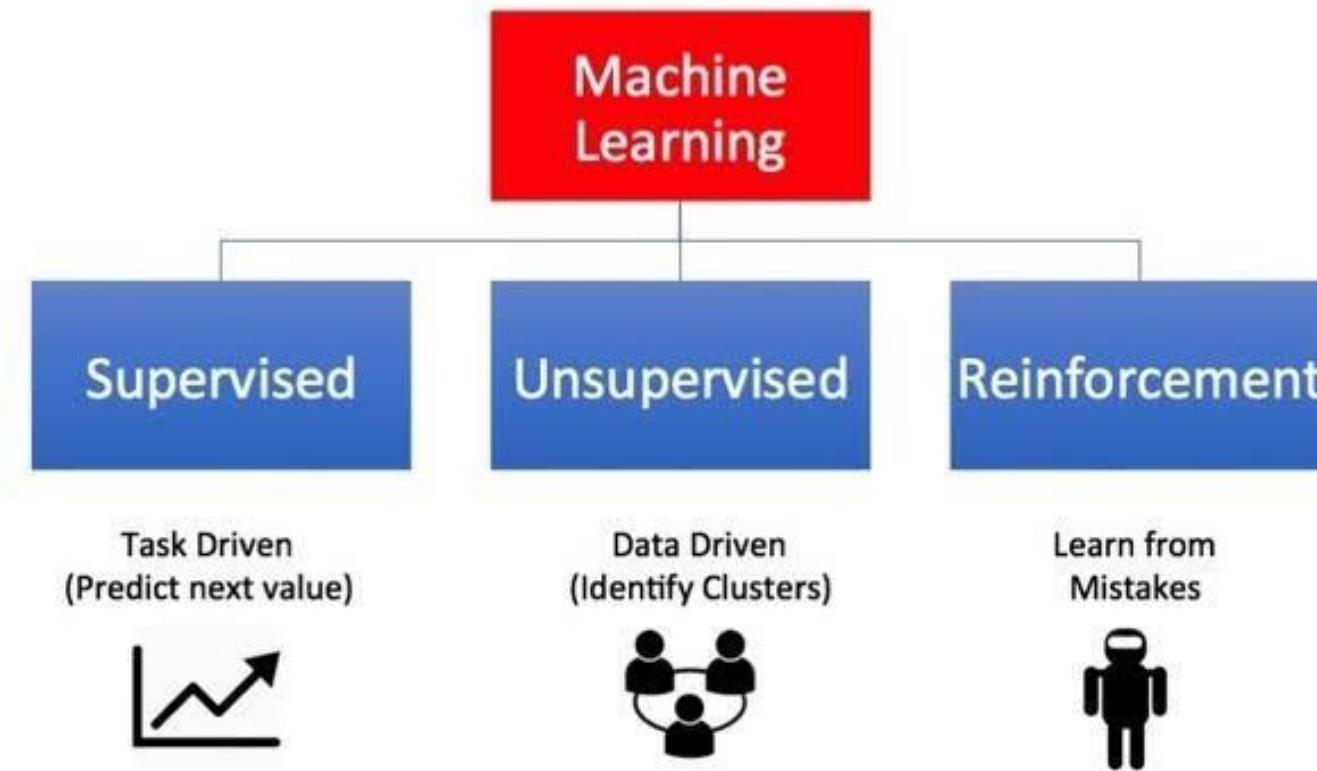
*Ethercat industrial bus protocol, since they offer wide bandwidth of data with very fast access.*  
Open source available.



# Mapa conceptual: Sistema de visión artificial para el control de líneas de tratamiento y selección de calidades

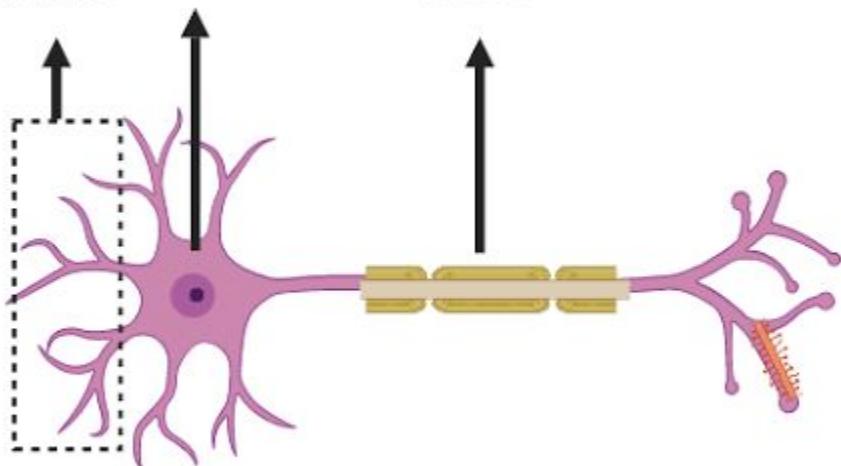


# Types of Machine Learning

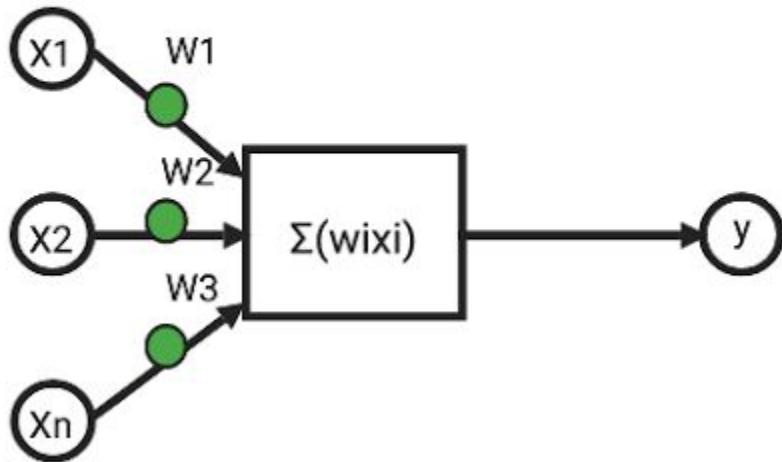


# Redes neuronales, el perceptrón

Dendritas      Soma      Axón

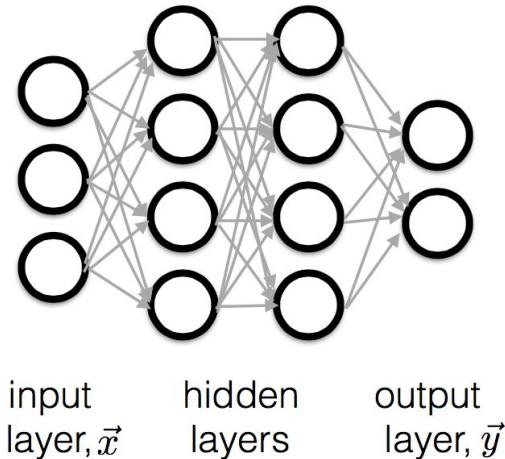


Entradas      Función de activación      Salida

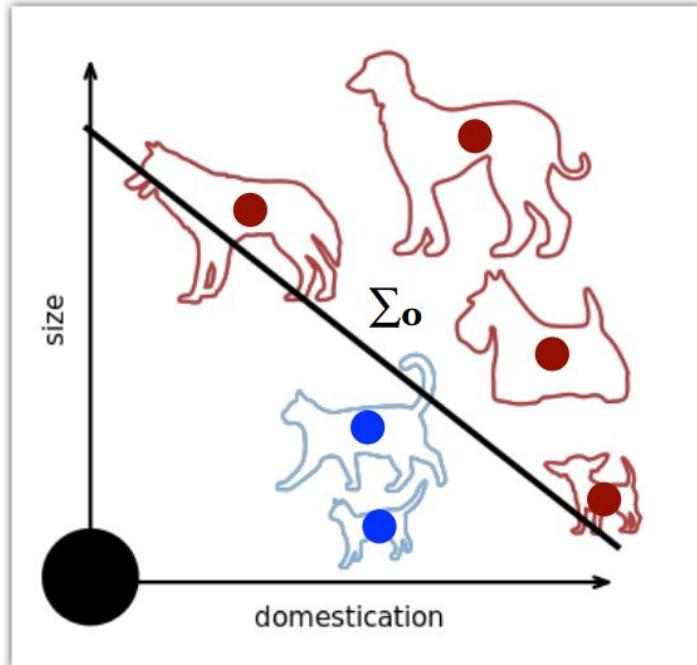


# “Traditional neural net”

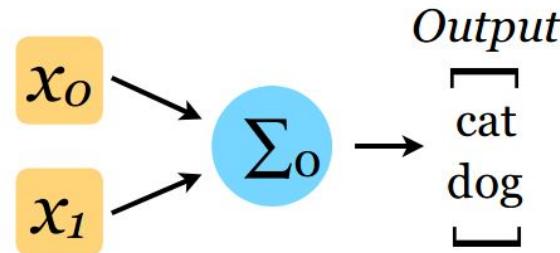
## Fully-Connected Multi-Layer Perceptrons



Imagine using two features to separate cats and dogs

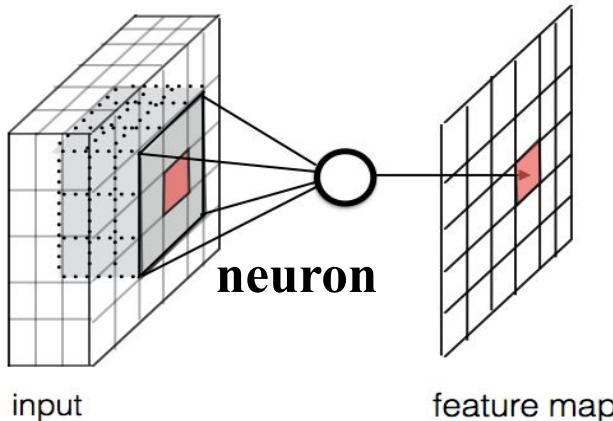


$$\sigma(\vec{x}) = \begin{cases} \vec{w}_i \cdot \vec{x} + b_i & \vec{w}_i \cdot \vec{x} + b_i \geq 0 \\ 0 & \vec{w}_i \cdot \vec{x} + b_i < 0. \end{cases}$$

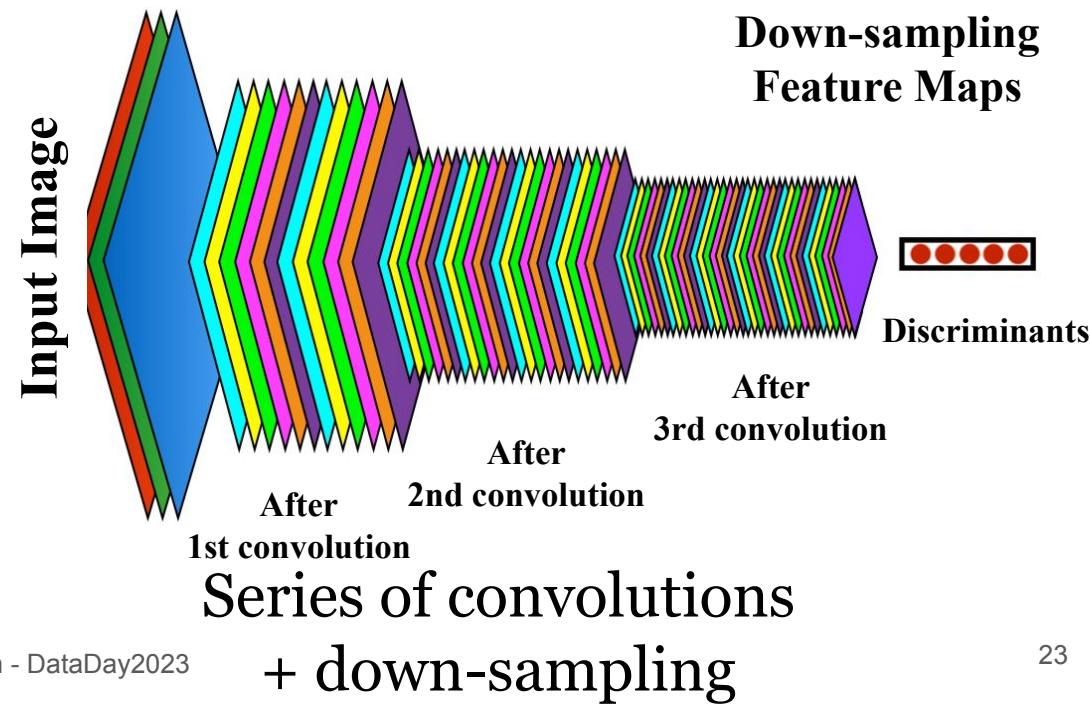


By picking a value for **w** and **b**,  
we define a boundary  
between the two sets of data

- CNNs are “**feature extraction machine**”
- Consists of a “convolution layer” with “kernels”
- A chain of parallelizable linear algebra operations
- CNN seen as a **geometrical data transformer**

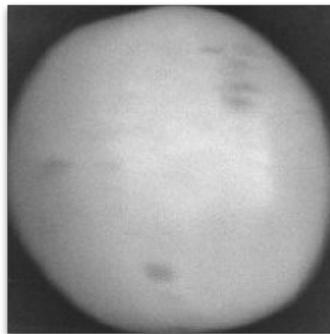


Convolution  
Operation

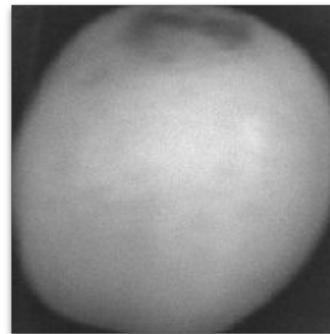


# Skin quality classification using DL

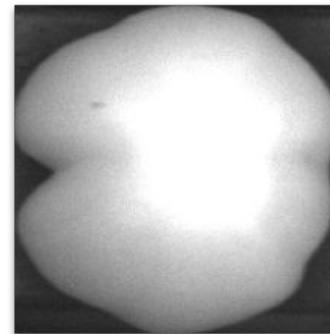
- Capacity to recollect high definition data base images during production to reuse, improve and adapt classification models.



Predicted label: Bad  
Scarring



Predicted label: Bad  
Localized bruise



Predicted label: Bad  
Deformation

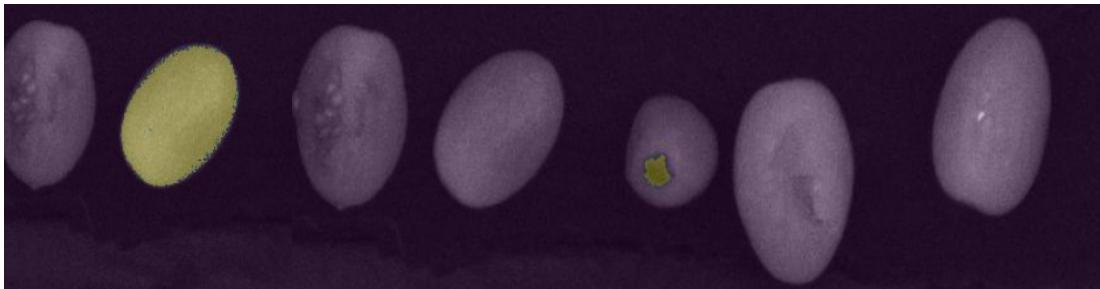


# Pixel precision segmentation using DL

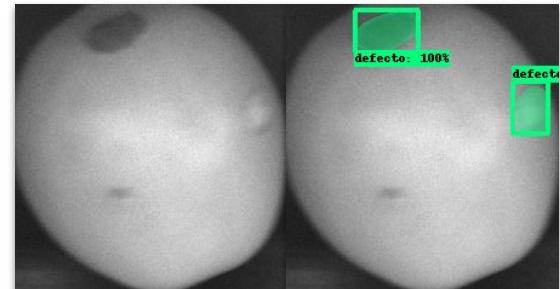
Quality detection with pixel precision: module for sorting fruit by pixel area. Customizable defects.

Levels of detection:

- Isolate fruit from background
- Color specific
- Texture specific
- Defect specific

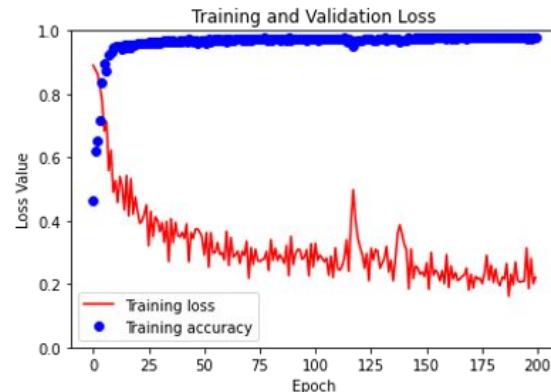
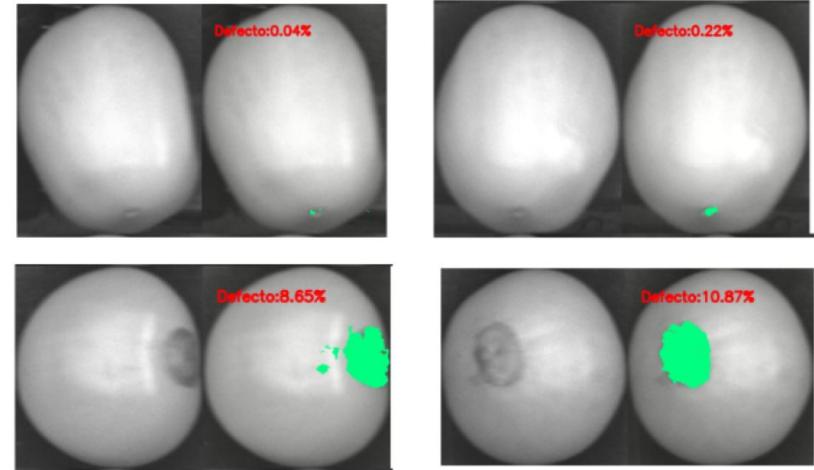
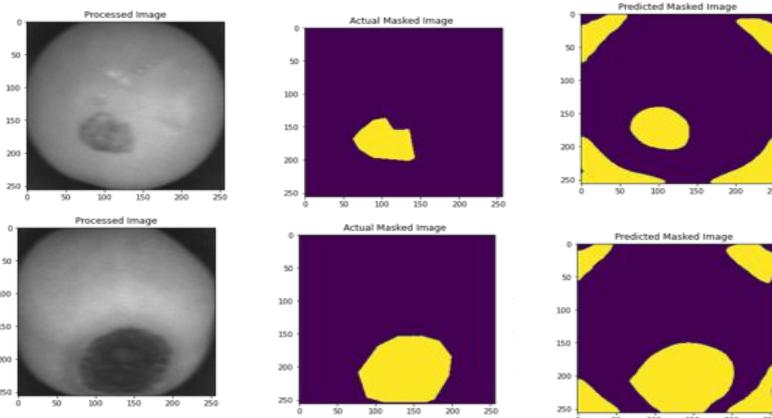


Fruit-background isolation and defect-fruit  
isolation example



Pixel segmentation of  
defects

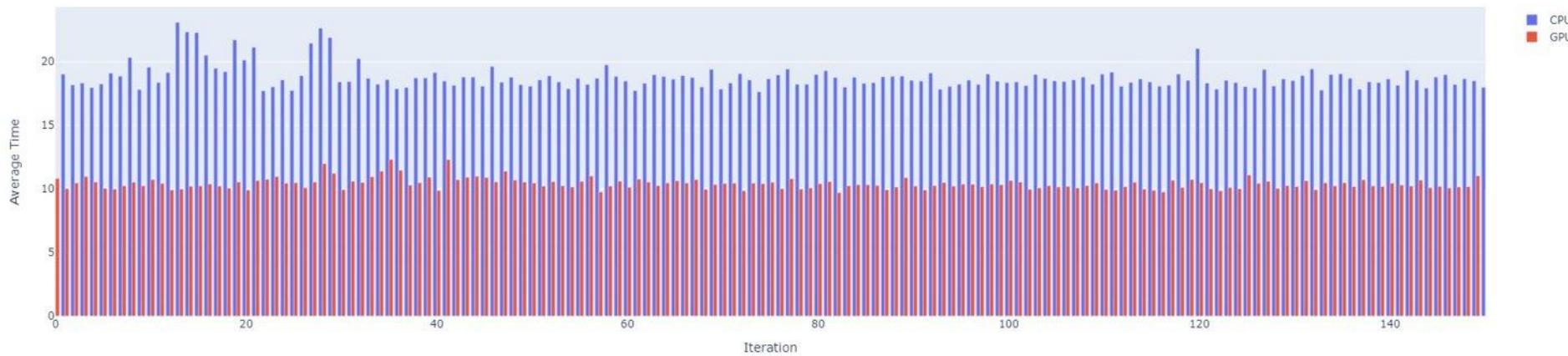
# UNet para clasificación y segmentación



Segmentation demo frames with  
imperfection detection percentage

# Performance, we need real-time inferences!

Total time (ms) for Each Iteration [9 threads]



- 9 inferencias en paralelo
  - 20ms total en CPU intel i9 12 Gen, o approx 2ms por inferencia
  - 10ms total en GPU RTX-3070, o approx 1ms por inferencia
  -

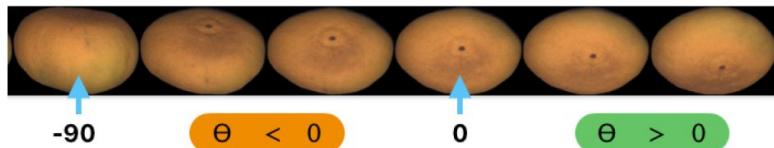
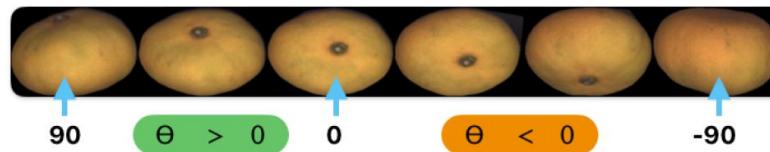
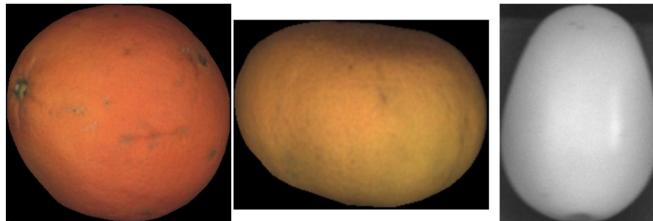
# Estimación de pose y radios internos

Spheroid models:

Sphere (orange)

Oblate (tomato)

Prolate (cherry tomato)



Article

Fast 3D Rotation Estimation of Fruits Using Spheroid Models

Antonio Albiol <sup>1,\*</sup> , Alberto Albiol <sup>1</sup> and Carlos Sánchez de Merás <sup>2</sup>

Sensors 2021, 21, 2232. <https://doi.org/10.3390/s21062232>

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Work by Tec de Mty students:

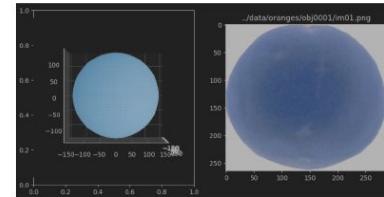


Fig. 3. Sphere spheroid compared with orange view

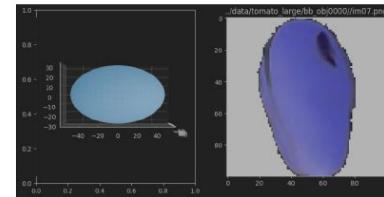


Fig. 4. Prolate spheroid compared with tomato view

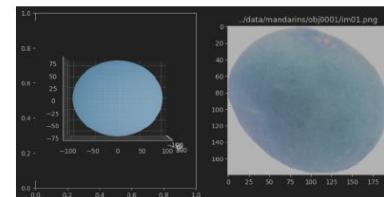
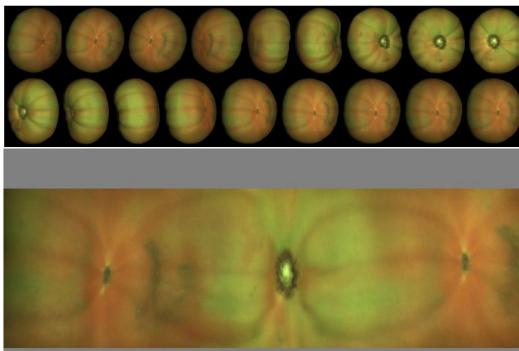
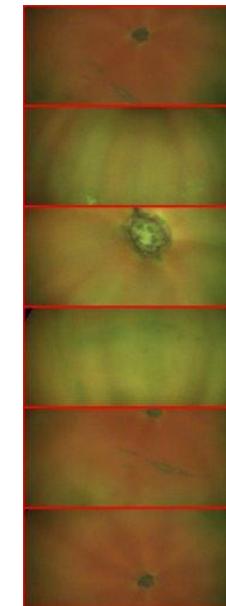
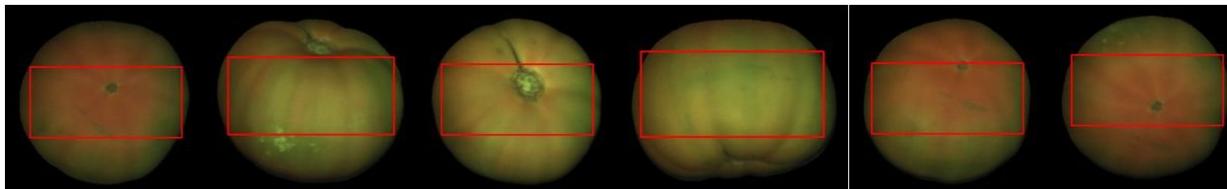


Fig. 5. Oblate spheroid compared with mandarin view

# Fusión de imágenes

- Bajar el número de inferencias
- Porcentajes de segmentación de fruta completa y no solo de una imagen



*Article*

## Single Fusion Image from Collections of Fruit Views for Defect Detection and Classification

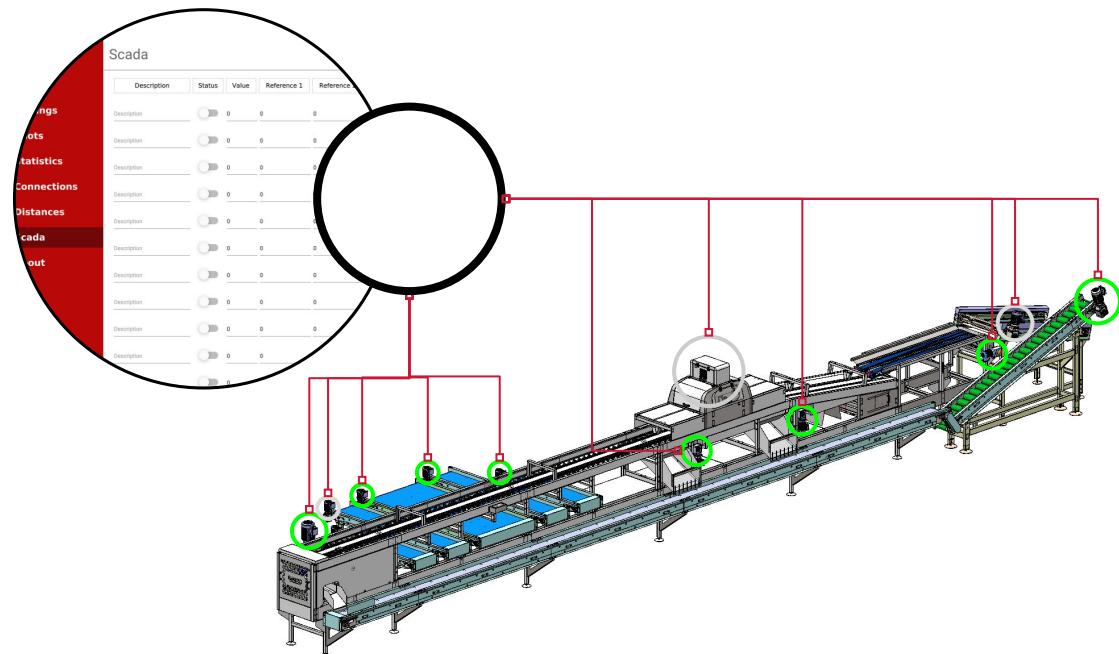
Antonio Albiol <sup>1,\*</sup>, Carlos Sánchez de Merás <sup>1</sup>, Alberto Albiol <sup>2</sup> and Sara Hinojosa <sup>3</sup>

Sensors 2022, 22, 5452. <https://doi.org/10.3390/s22145452>

# SCADA

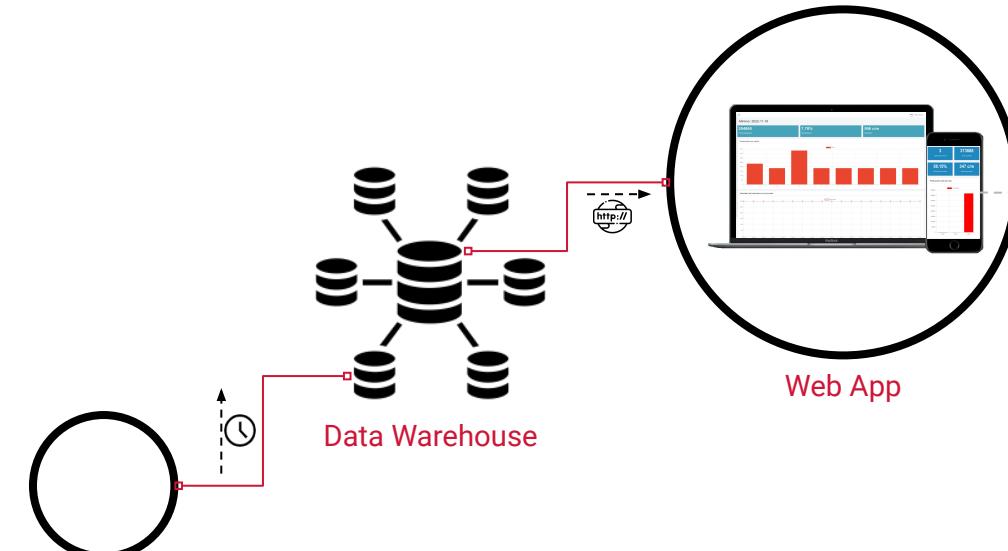
To control the entire treatment line:

- Lighting, motors, starts, shutdowns, etc.
- Perform automatic startup and shutdown sequences
- AI could be applied to predict failure

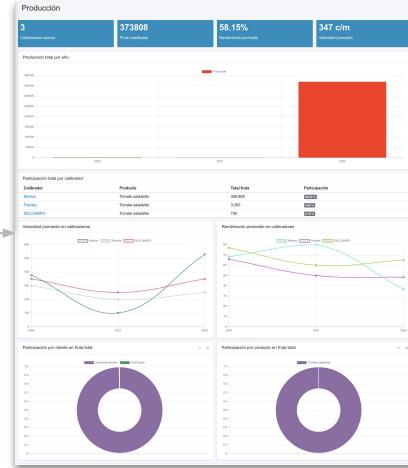


# Power BI

Cloud-based business intelligence application: **offsite access**



Web User Interface



user: saul@rochin.com  
pass: 12345678



Contacto. Quedo atento a sus comentarios :)



Profesor Investigador - Tecnologico de Monterrey, Escuela Ingenieria y Ciencias.

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 Saul Cuen Rochin