

# Design Proposal

## Project Proposal

- **Project Description**

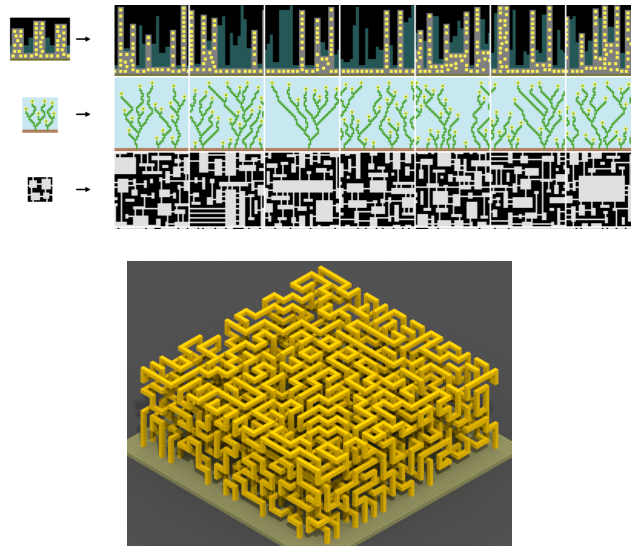
*Cube Spacer*

This project is a constraint based 2.5D world generation. It involves a set of tiles in the form of cubical 2.5D isometric geometry and the Wave Function Collapse algorithm (WFC) (Gumin,2016) to place tiles according to the tile set's connectivity rules.

- **Competitive Analysis**

Existing applications are mostly in 2d and the very few that are 3d are implemented in game engines such as Unity or Blender. Most of the implementations are in C# and with higher dimensions performance is known to be an issue.

This project seeks to implement a higher dimension world generation in python within the cmu graphics framework. This would involve resolving performance issues by scaling the setting and constraints. Also it will provide a novel 3d tile set that can serve as a maze or generate interesting 3d patterns.



- **Structural Plan**

main.py	onAppStart	bring in settings
		store user action states
	onKeyPress	functions to rotate tile / board
	onMousePress	functions to select tile from tile set and place tiles on board
		isTileSet, isTileLegal
	onMouseMove	functions for play to hold the tile and rotate
	redrawAll	drawBoard, drawTileSet, drawMovingTile
	Isometric Functions	cartToIso, isoToCart, getCornerPointsIsoRect
		drawIsoRect, drawIsoGrid, drawCartGrid
	Tile Functions	drawTileOnCanvas, drawTileSet, drawTileBound
		placeTileOnBoard

settings.py	setting used in main and tile class	returns dictionary where key: margin, rows, cols, cubeSize, cubeDim, tileDim, levels value : input values of setting
tile.py	TileSet and Tile class	includes tile map, adjacency constraints and board/pixel location.

- **Algorithmic Plan / Timeline Plan**

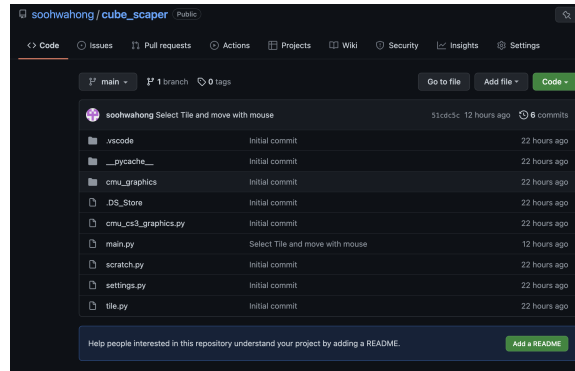
Algorithm		UI	
<b>Isometric projection</b> <input checked="" type="checkbox"/> Mapping 2d to 2.5d <input checked="" type="checkbox"/> Create 2.5d unit cube <input checked="" type="checkbox"/> Create tile class (3*3*3 or 5*5*5 cubes) (matrix) <input checked="" type="checkbox"/> Use numpy	3 2 3 2	<b>Framework</b> <input checked="" type="checkbox"/> Integration within 112 graphics <input checked="" type="checkbox"/> Isometric background grid	2 1
TP0 / Evaluate Backup			
<b>Tile Design</b> <input type="checkbox"/> Tile set class - 2d, 3d + constraints <input type="checkbox"/> Create simple tile set <input type="checkbox"/> V1. pipes (geometric relation) <input type="checkbox"/> V2. building (spatial relation)	3 4	<b>User input</b> <input type="checkbox"/> Initiate tiles by drag and drop <input type="checkbox"/> Snapping tiles to grid <input type="checkbox"/> Show shadow of possible placement	2 2 2
TP1 (Design Proposal + Project Proposal + Storyboard)			
<b>Wave Function Collapse</b> <input type="checkbox"/> Implement WFC <input type="checkbox"/> Create intricate tile set <input type="checkbox"/> Rotate <input type="checkbox"/> Find faces / constraints	4 4		
TP2 (Working demo + Updated Design Docs)			
<b>(+)Maze generation</b> <input type="checkbox"/> Add start and goal tile <input type="checkbox"/> Add maze generating constraint to create maze path	2 4	<b>(+)User input</b> <input type="checkbox"/> Initiate tiles by drag and drop <input type="checkbox"/> Snapping tiles to grid <input type="checkbox"/> Show shadow of possible placement <input type="checkbox"/> Ability to 'save' results and parameters	3 3  3
TP3 (Project Codebase + Readme File + Project Demo(video & live) + Style)			

Wave Function Collapse algorithm (WFC) (Gumin,2016) : constraint satisfaction algorithm acting on a set of tiles with associated connectivity rules

```
Iteratively samples a grid location
Samples a tile to be assigned to that location
Updates each remaining grid locations' probability distribution over what tiles can be sampled Given the constraints defined by til
This process repeats, and ends when all grid locations have an assigned tile.
```

- **Version Control Plan**

Using Github repository for version control.



- **Module List** : numpy

## Resources

<https://robertheaton.com/2018/12/17/wavefunction-collapse-algorithm/>

<https://boristhebrave.github.io/DeBroglie/articles/index.html>

<https://bitbucket.org/mxgmn/basic3dwfc/src/master/>

## TP2 Update

- Created tileset with connectivity constraints (was more complex than expected..)
- Became path finding game in the sense that given the start and end goal, user needs to use tile set & rotations to create path
- Autosolver: Designate start(home) & end(destination) tile and location → DFS to find connecting path
- Potential MVP features
  - UI elements ( instructions, switch from manual to autosolving mode...)
  - Transparent path + ball moving through path view
  - Rotating view