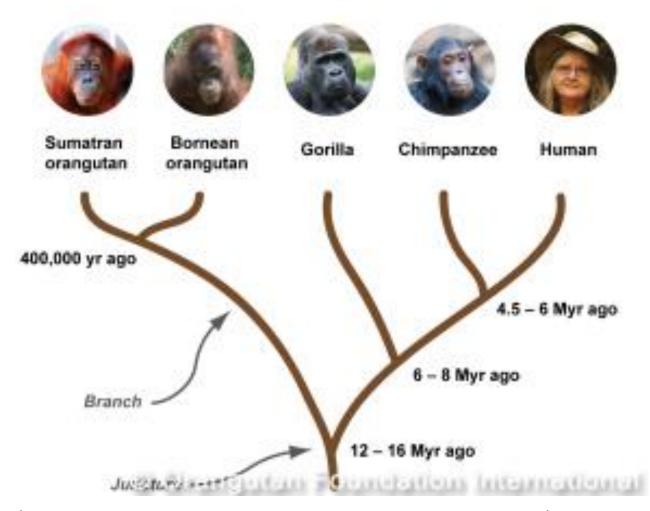
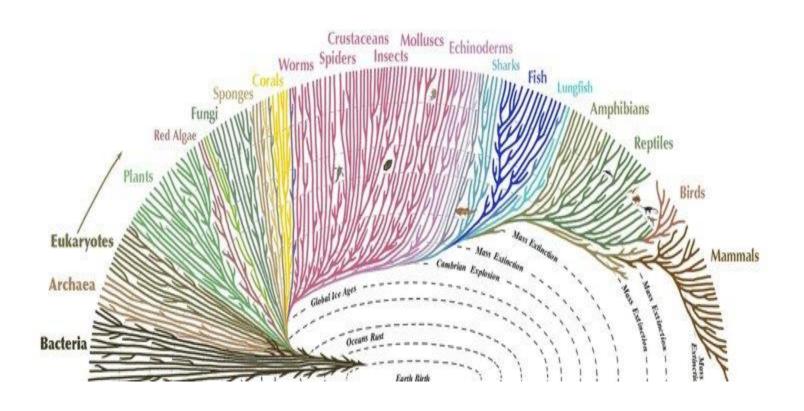
# **Hierarchical Clustering**

# Apes and Us

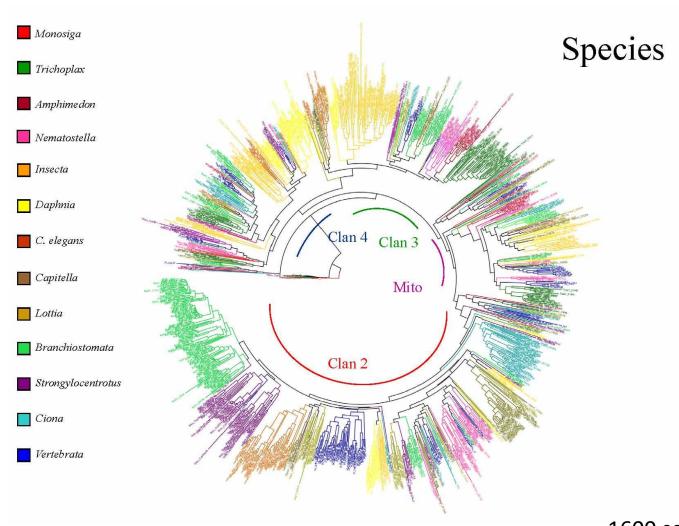


## The Tree of Life



http://pixgood.com/evolution-of-life-poster.html

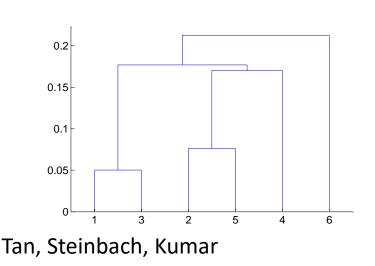
# P450 protein superfamily

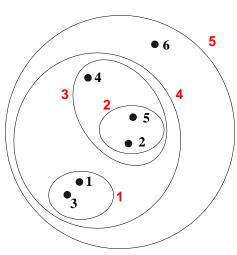


1600 sequences16 species

# Hierarchical Clustering

- Produces a set of nested clusters organized as a hierarchical tree
- Can be visualized as a dendrogram
  - A tree like diagram that records the sequences of merges or splits





Chapter 8

# Strengths of Hierarchical Clustering

- Do not have to assume any particular number of clusters
  - Any desired number of clusters can be obtained by 'cutting' the dendogram at the proper level

- They may correspond to meaningful taxonomies
  - Example in biological sciences (e.g., animal kingdom, phylogeny reconstruction, ...)

# Hierarchical Clustering

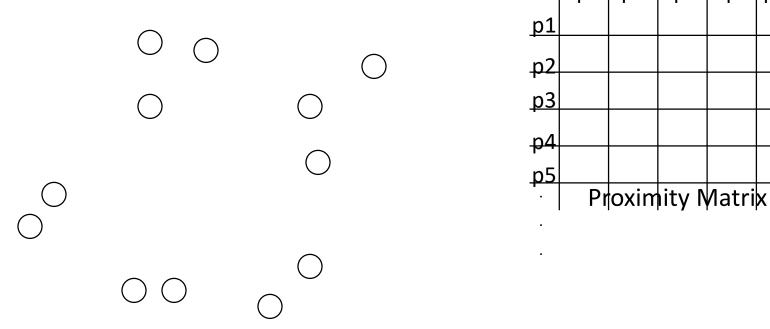
- Two main types of hierarchical clustering
  - Agglomerative:
    - Start with the points as individual clusters
    - At each step, merge the closest pair of clusters until only one cluster (or k clusters) left
  - Divisive:
    - Start with one, all-inclusive cluster
    - At each step, split a cluster until each cluster contains a point (or there are k clusters)
- Traditional hierarchical algorithms use a similarity or distance matrix
  - Merge or split one cluster at a time

## **Agglomerative Clustering Algorithm**

- More popular hierarchical clustering technique
- Basic algorithm is straightforward
  - 1. Compute the proximity matrix
  - 2. Let each data point be a cluster
  - 3. Repeat
  - 4. Merge the two closest clusters
  - 5. Update the proximity matrix
  - **6. Until** only a single cluster remains
- Key operation is the computation of the proximity of two clusters
  - Different approaches to defining the distance between clusters distinguish the different algorithms

# **Starting Situation**

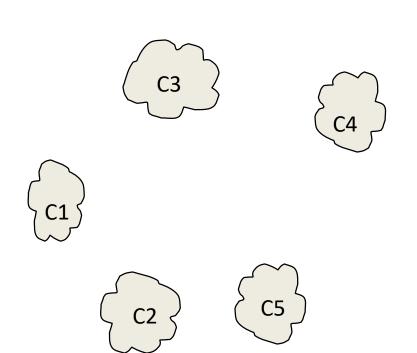
Start with clusters of individual points and a proximity matrix

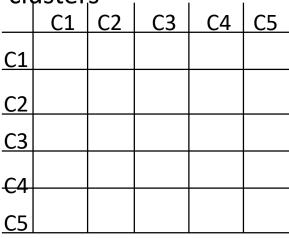




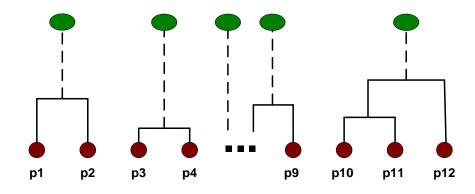
## Intermediate Situation

After some merging steps, we have some clusters





**Proximity Matrix** 



## Intermediate Situation

We want to merge the two closest clusters (C2 and C5) and update the proximity matrix.

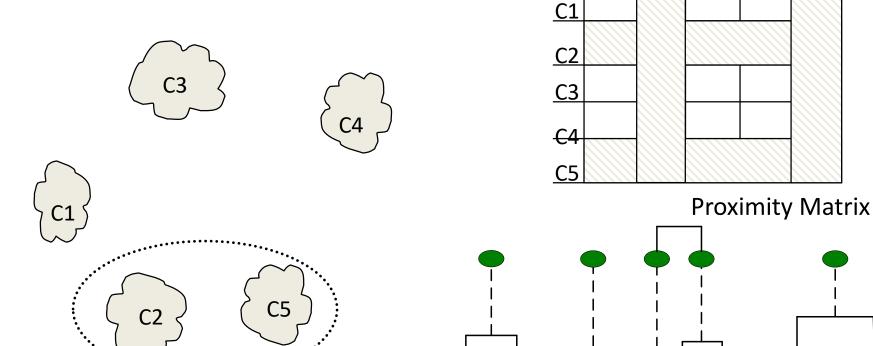
p2

p9

p10

p11

p12



# After Merging

C3

p9

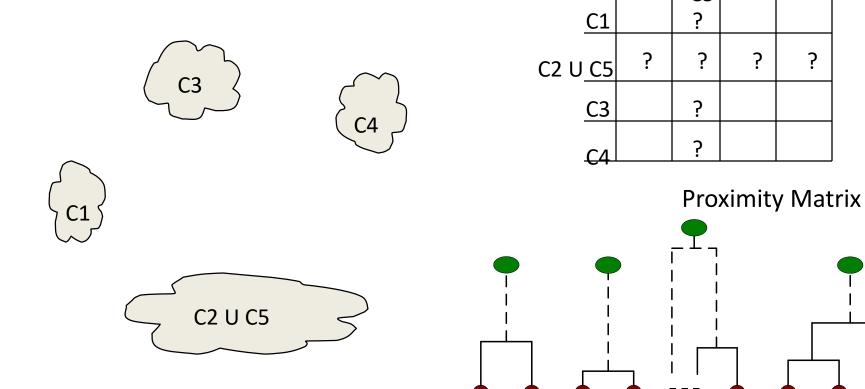
p10

p11

p12

C4

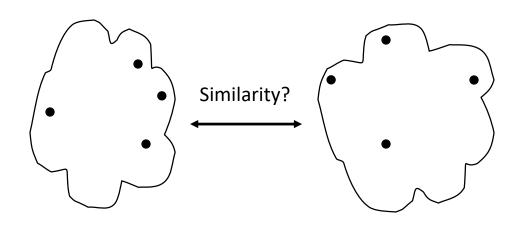
The question is "How do we update the proximity matrix?"



p1

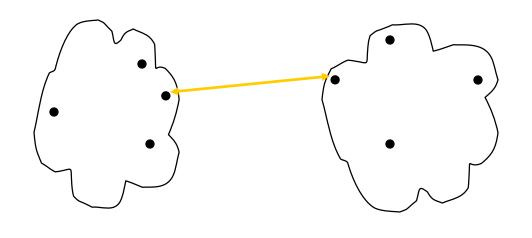
p2

р3



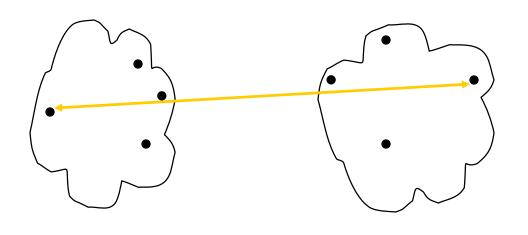
	p1	p2	рЗ	p4	p5	<u>.</u>
<u>p1</u>						
<u>p2</u>						
<u>p2</u> <u>p3</u>						
<u>p4</u> <u>p5</u>						
•						

- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error



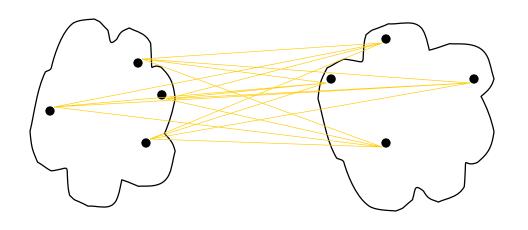
	p1	p2	р3	p4	р5	<u>.</u>
<b>p1</b>						
<u>p2</u>						
<u>p2</u> p3						
<u>p4</u> <u>p5</u>						
•						

- □ MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error



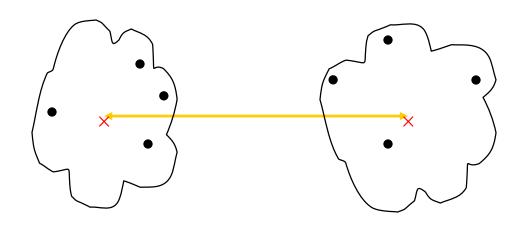
	p1	p2	рЗ	p4	р5	<u>.</u>
р1						
<b>p</b> 2						
<u>p2</u> <u>p3</u>						
<u>p4</u> <u>p5</u>						

- MIN
- MAX
- Group Average
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	p1	p2	рЗ	p4	р5	<u>.</u>
р1						
<b>p</b> 2						
<u>p2</u> <u>p3</u>						
<u>p4</u> <u>p5</u>						

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	p1	p2	рЗ	p4	р5	<u>.</u>
<b>p1</b>						
<u>p2</u>						
<u>p2</u> <u>p3</u>						
<u>p4</u> <u>p5</u>						

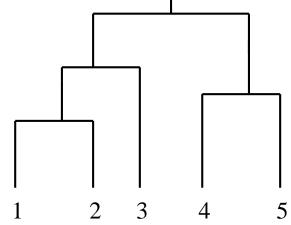
- MIN
- MAX
- Group Average
- Distance Between Centroids
- Other methods driven by an objective function
  - Ward's Method uses squared error

## Cluster Similarity: MIN or Single Link

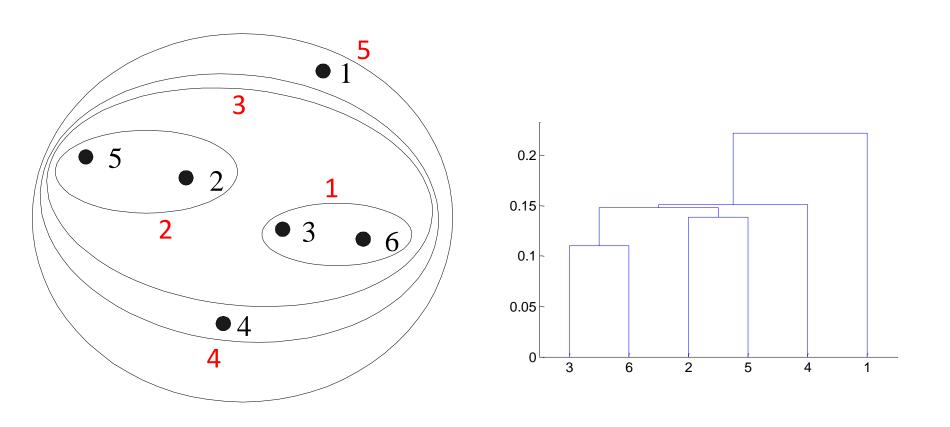
 Similarity of two clusters is based on the two most similar (closest) points in the different clusters

Determined by one pair of points, i.e., by one link in the proximity graph.

•	11	12	13	14 8	15 15
	1.00				
12	0.90	1.00	0.70	0.60	0.50
13	0.10	0.70	1.00	0.40	0.30
14	0.65	0.60	0.40	1.00	0.80
15	0.20	0.50	0.30	0.80	1.00



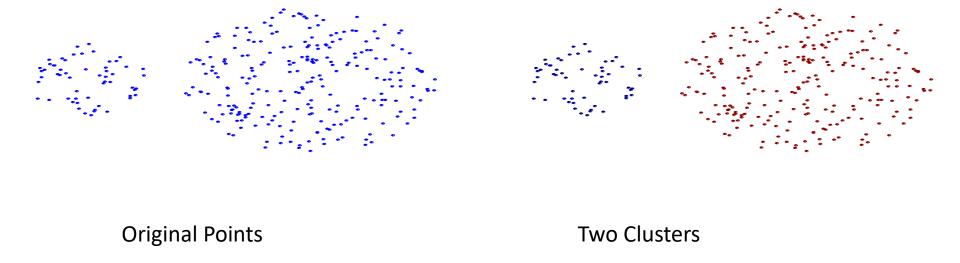
# Hierarchical Clustering: MIN



**Nested Clusters** 

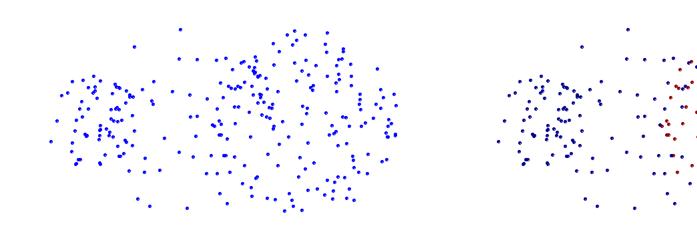
Dendrogram

# Strength of MIN



• Can handle non-elliptical shapes

## **Limitations of MIN**



**Original Points** 

**Two Clusters** 

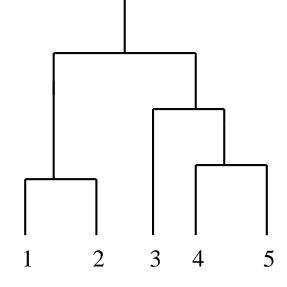
• Sensitive to noise and outliers

### Cluster Similarity: MAX or Complete Linkage

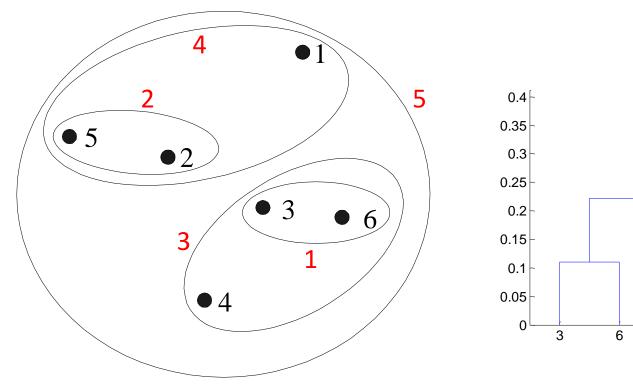
 Similarity of two clusters is based on the two least similar (most distant) points in the different clusters

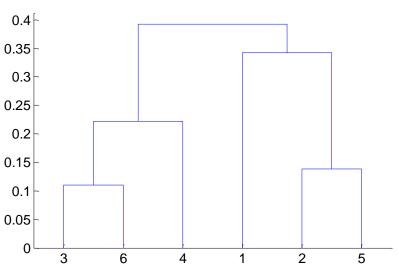
Determined by all pairs of points in the two clusters

_	<b>I</b> 1	<b>l</b> 2	<b>I</b> 3	<b>1</b> 4	<b>I</b> 5
11	1.00	0.90	0.10	0.65	0.20
12	0.90	1.00	0.70	0.60	0.50
<b>I</b> 3	0.10	0.70	1.00	0.40	0.30
<b>1</b> 4	0.65	0.60	0.40	1.00	0.80
<b>I</b> 5	0.20	0.50	0.30	0.80	0.20 0.50 0.30 0.80 1.00



# Hierarchical Clustering: MAX

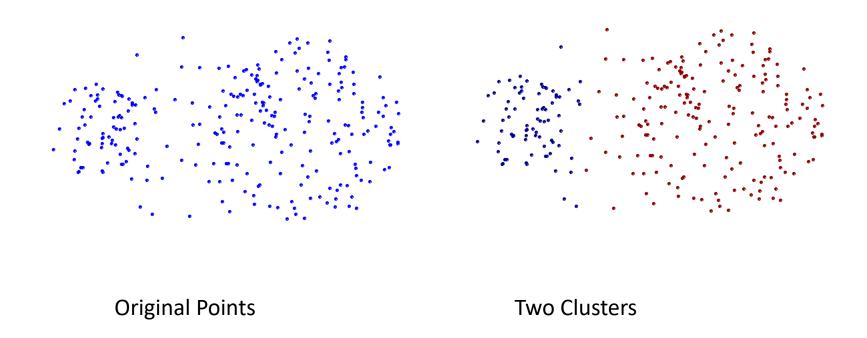




**Nested Clusters** 

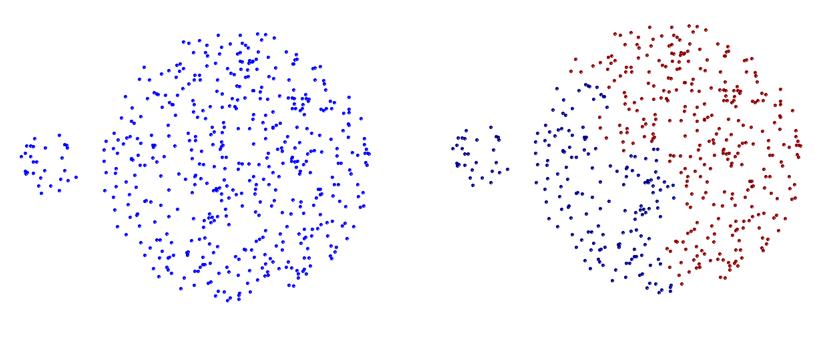
Dendrogram

# Strength of MAX



• Less susceptible to noise and outliers

## Limitations of MAX



**Original Points** 

**Two Clusters** 

- •Tends to break large clusters
- Biased towards globular clusters

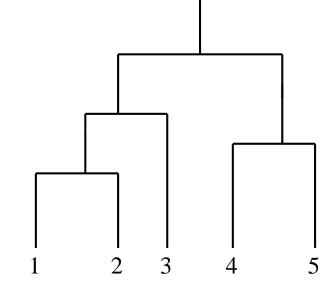
# Cluster Similarity: Group Average

 Proximity of two clusters is the average of pairwise proximity between points in the two clusters.

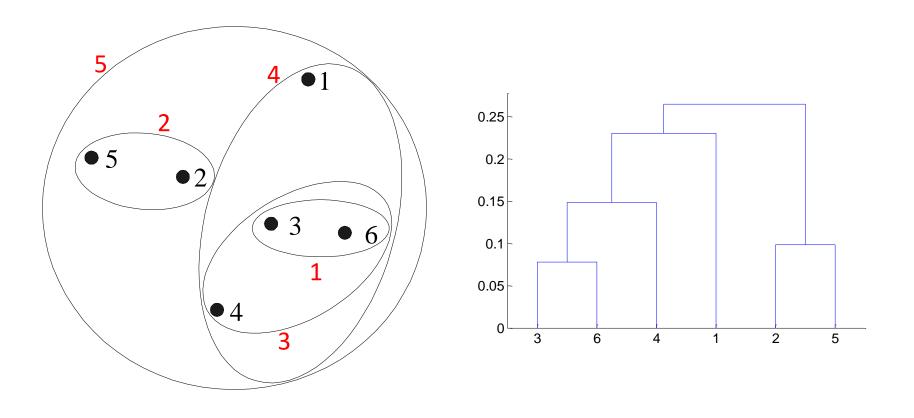
$$proximity(Cluster_{i}, Cluster_{j}) = \frac{\sum\limits_{\substack{p_{i} \in Cluster_{i} \\ p_{j} \in Cluster_{j}}} \sum\limits_{\substack{p_{i} \in Cluster_{i} \\ |Cluster_{i}| * |Cluster_{i}|}} \sum\limits_{\substack{p_{i} \in Cluster_{i}|}} \sum\limits$$

 Need to use average connectivity for scalability since total proximity favors large clusters

_	<b>I</b> 1			<b>1</b> 4	
11	1.00	0.90	0.10	0.65	0.20 0.50 0.30 0.80 1.00
12	0.90	1.00	0.70	0.60	0.50
13	0.10	0.70	1.00	0.40	0.30
14	0.65	0.60	0.40	1.00	0.80
15	0.20	0.50	0.30	0.80	1.00



# Hierarchical Clustering: Group Average



**Nested Clusters** 

Dendrogram

## Hierarchical Clustering: Group Average

 Compromise between Single and Complete Link

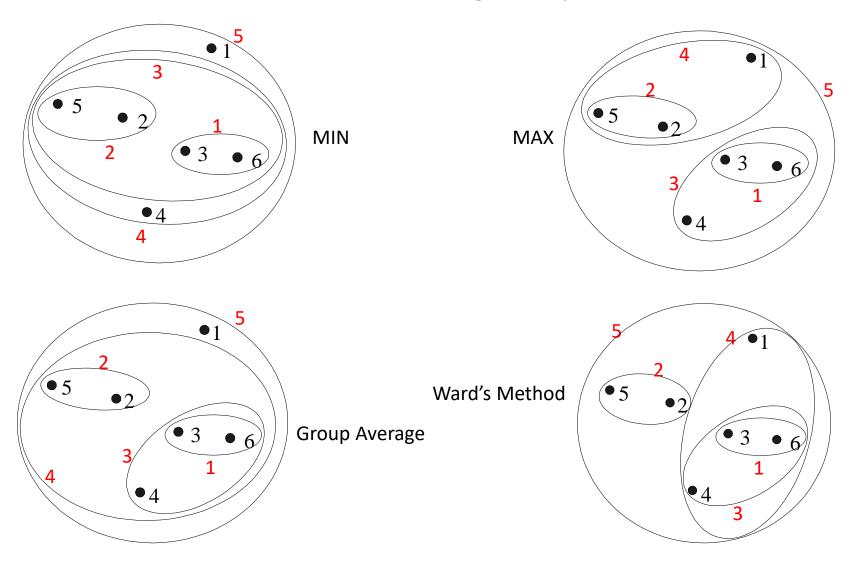
- Strengths
  - Less susceptible to noise and outliers

- Limitations
  - Biased towards globular clusters

# Cluster Similarity: Ward's Method

- Similarity of two clusters is based on the increase in squared error when two clusters are merged
  - Similar to group average if distance between points is distance squared
- Less susceptible to noise and outliers
- Biased towards globular clusters
- Hierarchical analogue of K-means
  - Can be used to initialize K-means

#### Hierarchical Clustering: Comparison



#### Hierarchical Clustering: Time and Space requirements

- O(N<sup>2</sup>) space since it uses the proximity matrix.
  - N is the number of points.

- O(N³) time in many cases
  - There are N steps and at each step the size, N<sup>2</sup>,
     proximity matrix must be updated and searched
  - Complexity can be reduced to O(N<sup>2</sup> log(N)) time for some approaches

#### Hierarchical Clustering: Problems and Limitations

- Once a decision is made to combine two clusters, it cannot be undone
- No objective function is directly minimized
- Different schemes have problems with one or more of the following:
  - Sensitivity to noise and outliers
  - Difficulty handling different sized clusters and convex shapes
  - Breaking large clusters

# Divisive Hierarchical Clustering

- Start with the entire data set as the root node
- Apply K-means clustering at every level until each data point is a leaf node
- Can also stop midway if sufficient number of clusters are obtained

# How many clusters?

• Like K-means clustering, hierarchical clustering also does not answer the above question.

 A variation of hierarchical clustering, called the SCALE BASED CLUSTERING, does.

# Scale-based Clustering

- Clustering is done at a "scale"
- An answer to the question of "how many clusters"
- Best clusters tend to live over the longest range of scales

# Algorithm $_{ ot}$

- Start with a large number of clusters
- Initialize by selecting from data set
- Initialize "sigma" to a small value
- Update all centroids
- Eliminate duplicate centroids whenever there is a merger
- Increase sigma by a constant factor
- If there are more than 1 unique centroid continue update of centroids
- Stop only when a single unique centroid remains

## Data set

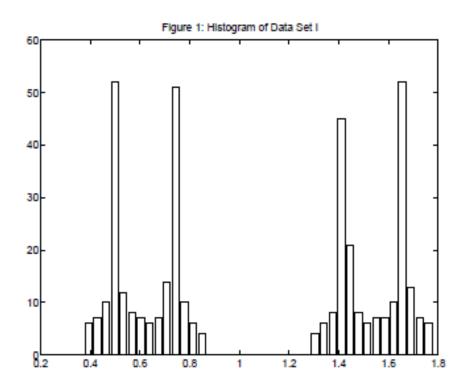


Figure 1: Histogram of Data Set I with 400 pts.

# Clustering result: Evolution of the centroids

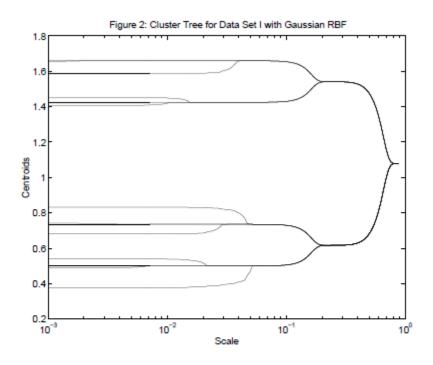


Figure 2: Cluster Tree for Data Set I with 14 RBF nodes. Only 13 branches seem to be present even at the lowest scale because the topmost "branch" is actually two branches which merge at  $\sigma = 0.002$ .