## Further Treatment Of Geometric Sets

Spencer T. Parkin

Abstract. Abstract goes here...

## 1. Introduction

We let  $P(\mathbb{V})$  denote the set of all possible vector sub-spaces of  $\mathbb{V}$ , not the power-set of  $\mathbb{V}$ .

## 2. The Meet And Join Of Vector Sub-Spaces

An excellent treatment of *meet* and *join* is given in []. Unlike [], however, here we will not, as they said, abuse language by referring to any blade as a vector sub-space.<sup>1</sup> In an attempt to be as rigorous as possible, we will introduce a function  $\overline{B}: \mathbb{B} \to P(\mathbb{V})$ , and, for any blade B, only refer to  $\overline{B}(B)$  as a vector sub-space. For convenience in notation, we write  $\overline{B}$  instead of  $\overline{B}(B)$ .

**Definition 2.1.** For any blade  $B \in \mathbb{B}$ , we define the function  $\overline{B} : \mathbb{B} \to P(\mathbb{V})$  as

$$\overline{B} = \{ x \in \mathbb{V} | x \land B = 0 \}. \tag{2.1}$$

In light of Definition ??, it is important to realize that for any two blades  $A, B \in \mathbb{B}$ , and a vector sub-space  $V \subseteq \mathbb{V}$ , if we have  $\overline{A} = V$  and  $\overline{B} = V$ , then there exists a scalar  $\lambda \in \mathbb{R}$  such that  $A = \lambda B$ .

As operations (or well defined functions), *meet* and *join* operate on vector spaces, not blades. We therefore do not speak of taking the *meet* or *join* of two blades. Rather, the blades of a geometric algebra will help us calculate the *meet* and *join* of vector sub-spaces represented by those blades.

**Definition 2.2 (The** *meet* of two vector sub-spaces). For any two blades  $A, B \in \mathbb{B}$ , the *meet* M of  $\overline{A}$  and  $\overline{B}$  is the vector space given by

$$M = \overline{A} \cap \overline{B} = \{ x \in \mathbb{V} | x \in \overline{A} \text{ and } x \in \overline{B} \}.$$
 (2.2)

<sup>&</sup>lt;sup>1</sup>The present author has abused language in this way in other writings, but repents of this, at least in the present paper.

From Defintion 2.2, we see that the *meet* of two vector subspaces is the largest common sub-space. Notice that *meet* is clearly communitative.

**Definition 2.3 (The** *join* **of two vector sub-spaces).** For any two blades  $A, B \in \mathbb{B}$ , the *join* J of  $\overline{A}$  and  $\overline{B}$  is the vector space given by

$$J = \overline{A} + \overline{B} = \{x_1 + x_2 \in \mathbb{V} | x_1 \in \overline{A} \text{ and } x_2 \in \overline{B}\}.$$
 (2.3)

From Definition 2.3, we see that the join of two vector spaces is the smallest common super-space. Notice here too the commutativity of join.

Note that some care should be taken with Definition 2.2 and Definition 2.3 by easily verifying that M and J each satisfy the necessary properties of a vector space. Also note that any pair of blades, each representative of the same meet or join, are clearly scalar multiples of one another.

At this point, a natural question arrises. Given two blades  $A, B \in \mathbb{B}$ , how do we find a blade  $C \in \mathbb{B}$  such that  $\overline{C} = \overline{A} \cap \overline{B}$  and  $\overline{C} = \overline{A} + \overline{B}$ ? Do this in terms of orthogonal complement...define that first...

Spencer T. Parkin 102 W. 500 S., Salt Lake City, UT 84101

e-mail: spencerparkin@outlook.com