Models Of Geometry In Geometric Algebra

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Abstract. Abstract goes here...

Mathematics Subject Classification (2010). Primary 14J27; Secondary 14J29.

1. Introduction And Motivation

Many of the pieces of geometry we study can be described as the roots of a given polynomial. Consequently, the geometries generated by many different polynomials have been studied; and, naturally, this has led to a general theory of geometries that can be described as the zero set of one or more polynomials; namely, algebraic geometry. Ideals of polynomial rings being the generators of algebraic sets, abstract algebra became the basic framework of the theory.

Similarly, various models of geometry have been developed in the framework of geometric algebra, but they all have one thing in common: they're based upon the idea of the algebraic set. It stands to reason, then, that it may be worth trying to find a unified theory of such models in geometric algebra. In other words, it may be worth studying such models in a more abstract setting. That is the focus of this paper.

2. From Polynomials To Blades

Let F be a field of characteristic 1, and let $f \in F[x_1, \ldots, x_n]$ be a polynomial of arbitrary degree in n variables. Being interested in the set of all $x \in F(x_1, \ldots, x_n)$ such that f(x) = 0, how might we translate the description of this set into the language of geometric algebra? Letting \mathbb{G} denote a geometric algebra generated by an infinitely-dimensional vector space \mathbb{V} whose scalars are taken from F, (the set of euclidean vectors $\{e_i\}_{i=1}^{\infty}$ generate \mathbb{V}),

 $^{^{1}}$ Modern algebraic geometry has grown far beyond algebraic sets as the primary object of study; but originally, this is what algebraic geometry was about.

we introduce an appropriately defined function $p: \mathbb{V} \to F$ and simply factor it out of the equation f(x)=0 to obtain

$$p(x) \cdot v = 0,$$

where $v \in \mathbb{V}$. Defined appropriately, for every $f \in F[x_1, \ldots, x_n]$, there would exist a unique $v \in \mathbb{V}$ such that $p(x) \cdot v = 0$ if and only if f(x) = 0. The existence of such a function p, and the establishment of the ensuing claim, therefore, must constitute our first result.

Lemma 2.1. Letting $p: \mathbb{V} \to F$ be defined as

$$p(x) = \sum_{i=1}^{\infty} m_i(x)e_i, \qquad (2.1)$$

where the polynomial sequence $\{m_i\}_{i=1}^{\infty} \subset F[x_1, \ldots, x_n]$ enumerates all possible unit monomials in the variables x_1, \ldots, x_n , there exists, for every polynomial $f \in F[x_1, \ldots, x_n]$, a unique vector $v \in \mathbb{V}$, such that for all $x \in F$, we have $f(x) = p(x) \cdot v$.

Proof. It is clear that there must exist a sequence of scalars $\{\alpha_i\}_{i=1}^{\infty} \subset F$ such that

$$f(x) = \sum_{i=1}^{\infty} \alpha_i m_i(x).$$

Letting $v = \sum_{i=1}^{\infty} \alpha_i e_i$, we find that v factors out of this equation as $f(x) = p(x) \cdot v$, as desired. To show uniqueness, suppose $v \neq w \in \mathbb{V}$ satisfies the equation $f(x) = p(x) \cdot w$ with $w = \sum_{i=1}^{\infty} \beta_i e_i$. Then, since $v \neq w$, there exists a positive integer i such that $\alpha_i = v \cdot e_i \neq w \cdot e_i = \beta_i$, and therefore, $\alpha_i m_i(x) \neq \beta_i m_i(x)$, which is a contradiction.

At this point it is important to say that we should not get caught up in the way that p is or may be defined. It really doesn't matter. What does matter is that p is defined in such a way as to satisfy the property of Lemma 2.1 (i.e., that there is a one-to-one correspondence between polynomials in $F[x_1, \ldots, x_n]$ and vectors in \mathbb{V} .) We therefore shall not make any further use of equation (2.1) in the remainder of this paper.

Our interest, however, does not stop at the zero set of a single polynomial. For a set of r polynomials $\{f_j\}_{j=1}^r \subset F[x_1,\ldots,x_n]$, we want the set of all $x \in F(x_1,\ldots,x_n)$ such that for all $f \in \{f_j\}_{i=1}^r$, we have f(x) = 0. Interestingly, geometric algebra provides a convenient description of such a set.

References

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