

A multigrid multilevel Monte Carlo method for transport in the Darcy-Stokes flow

Prashant Kumar

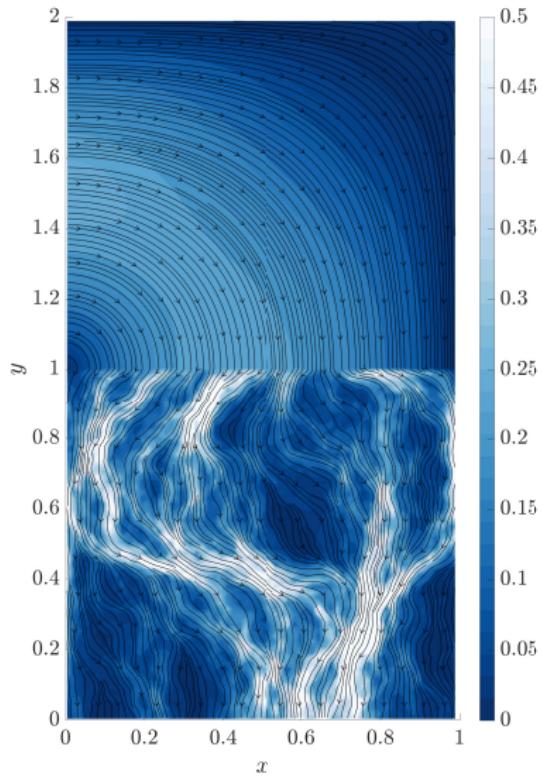
Joint work with

P. Luo, C. Rodrigo, F. J. Gaspar, C. W. Oosterlee

Workshop Day: Multilevel and Multigrid Methods, 30 May, 2018

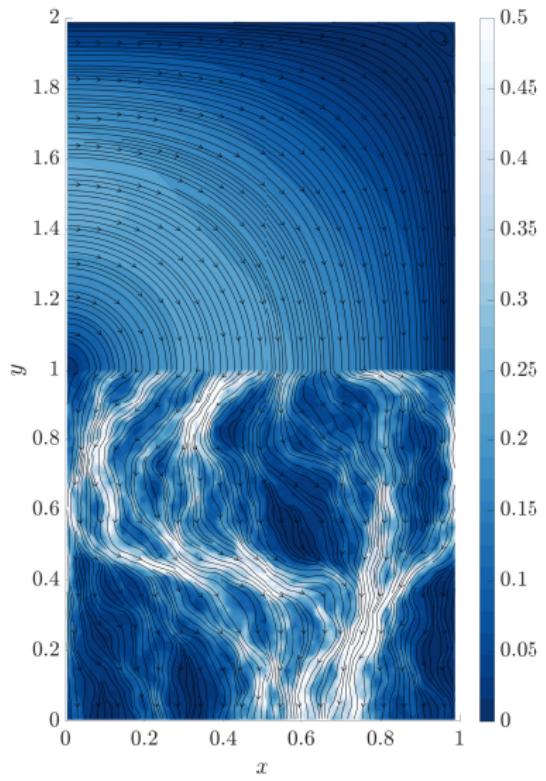
Introduction

Darcy-Stokes flow

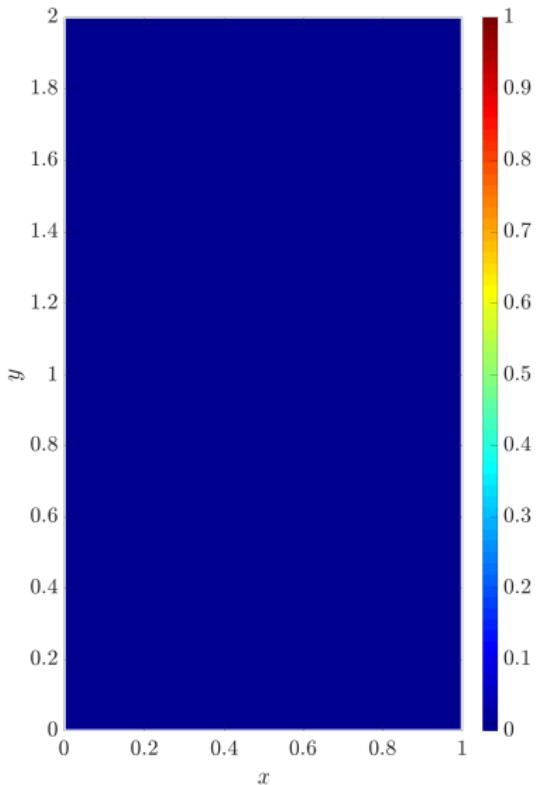


Introduction

Darcy-Stokes flow



Convection dominated transport



Outline

Three parts:

1. Solver optimized w.r.t random inputs

Monolithic multigrid for Darcy-Stokes flow

Benchmarking

ADI time-stepping for transport

Outline

Three parts:

1. Solver optimized w.r.t random inputs

Monolithic multigrid for Darcy-Stokes flow

Benchmarking

ADI time-stepping for transport

2. Multilevel Monte Carlo (MLMC) method

MLMC estimator and error analysis

Sampling strategies and computational complexity

Outline

Three parts:

1. Solver optimized w.r.t random inputs

Monolithic multigrid for Darcy-Stokes flow

Benchmarking

ADI time-stepping for transport

2. Multilevel Monte Carlo (MLMC) method

MLMC estimator and error analysis

Sampling strategies and computational complexity

3. Performance of the Multigrid MLMC method

Governing equations

Stokes flow

$$-\nabla \cdot \boldsymbol{\sigma}^s = \mathbf{f}^s$$

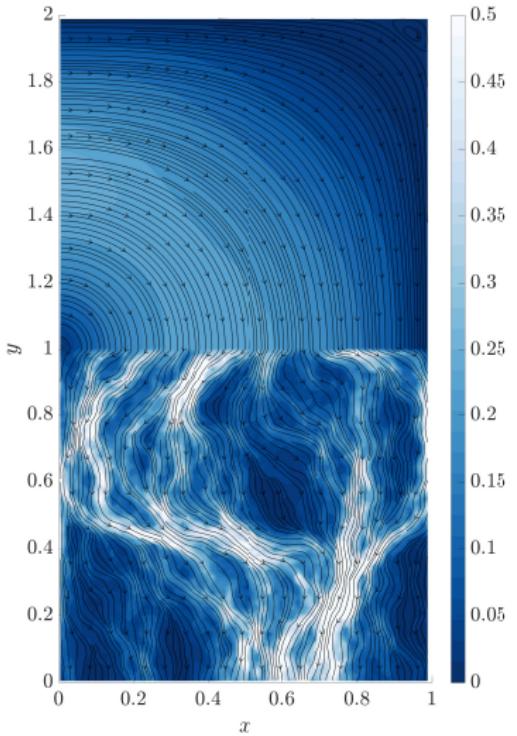
$$\nabla \cdot \mathbf{u}^s = \mathbf{0}$$

Darcy flow

$$\eta \mathbf{K}^{-1} \mathbf{u}^d + \nabla p^d = \mathbf{0}$$

$$\nabla \cdot \mathbf{u}^d = f^d$$

\mathbf{K} : log-normal random field



Discretization: FV on a staggered mesh

Interface conditions

1. Mass conservation

$$\mathbf{u}^s \cdot \mathbf{n} = \mathbf{u}^d \cdot \mathbf{n}$$

2. Normal stress balance

$$-\mathbf{n} \cdot \boldsymbol{\sigma}^s \cdot \mathbf{n} = p^d$$

3. Beaver-Joseph-Saffman condition

$$\mathbf{u}^s \cdot \boldsymbol{\tau} + \left(\frac{\sqrt{K}}{\alpha_{BJ}} \right) \boldsymbol{\tau} \cdot \boldsymbol{\sigma}^s \cdot \mathbf{n} = \mathbf{0}$$

No slip condition

$$\mathbf{u}^s \cdot \boldsymbol{\tau} = \mathbf{0}$$

$\mathbf{n}, \boldsymbol{\tau}$ are normal and tangential vectors to the interface

Stochastic model for permeability

Parametrized Matérn covariance model

$$C_{\Phi}(r) = \sigma_c^2 \frac{2^{1-\nu_c}}{\Gamma(\nu_c)} \left(2\sqrt{\nu_c} \frac{r}{\lambda_c} \right)^{\nu_c} K_{\nu_c} \left(2\sqrt{\nu_c} \frac{r}{\lambda_c} \right), \quad r = \|\mathbf{x} - \mathbf{y}\|$$

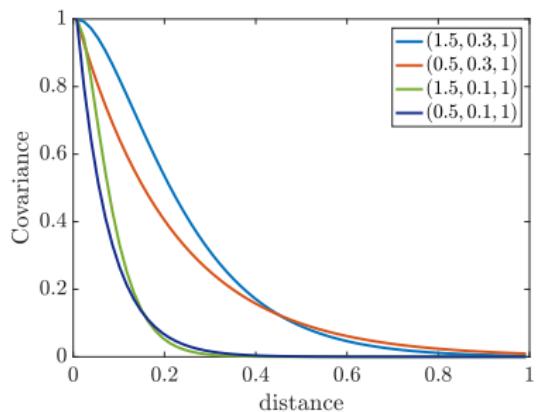
$$\Phi = (\nu_c, \lambda_c, \sigma_c^2) = (\text{smoothness, correlation length, variance})$$

Stochastic model for permeability

Parametrized Matérn covariance model

$$C_{\Phi}(r) = \sigma_c^2 \frac{2^{1-\nu_c}}{\Gamma(\nu_c)} \left(2\sqrt{\nu_c} \frac{r}{\lambda_c} \right)^{\nu_c} K_{\nu_c} \left(2\sqrt{\nu_c} \frac{r}{\lambda_c} \right), \quad r = \|\mathbf{x} - \mathbf{y}\|$$

$$\Phi = (\nu_c, \lambda_c, \sigma_c^2) = (\text{smoothness, correlation length, variance})$$

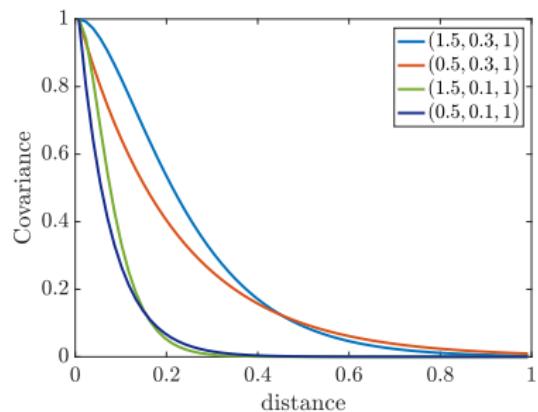


Stochastic model for permeability

Parametrized Matérn covariance model

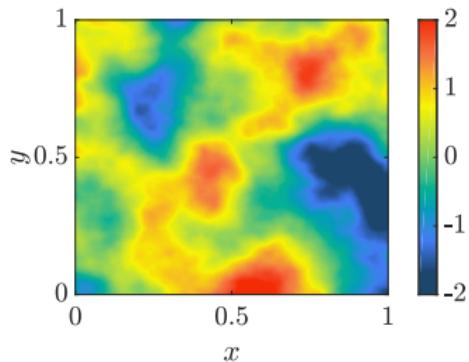
$$C_{\Phi}(r) = \sigma_c^2 \frac{2^{1-\nu_c}}{\Gamma(\nu_c)} \left(2\sqrt{\nu_c} \frac{r}{\lambda_c}\right)^{\nu_c} K_{\nu_c} \left(2\sqrt{\nu_c} \frac{r}{\lambda_c}\right), \quad r = \|\mathbf{x} - \mathbf{y}\|$$

$$\Phi = (\nu_c, \lambda_c, \sigma_c^2) = (\text{smoothness, correlation length, variance})$$

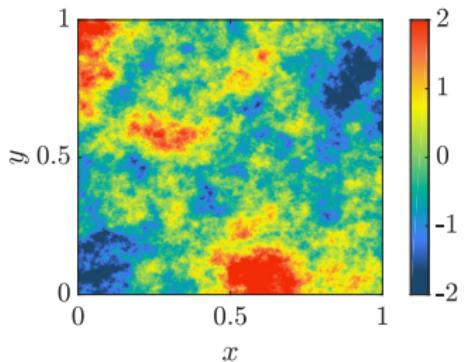


Sampling technique: Karhunen-Loéve expansion, **Circulant embedding**, etc

Isotropic random fields

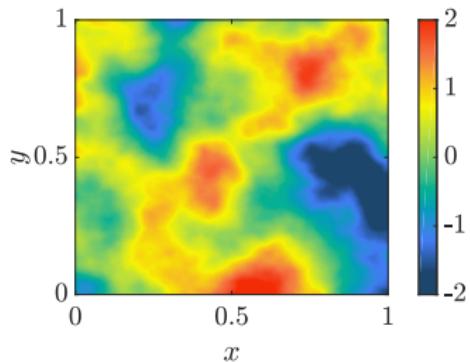


$$\Phi_1 = (1.5, 0.3, 1)$$

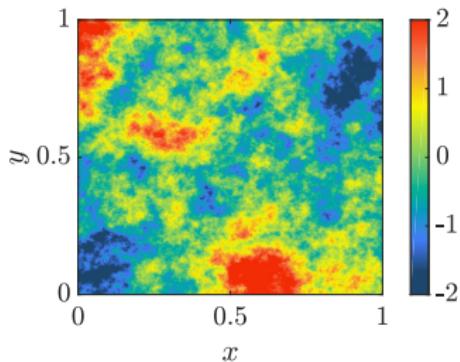


$$\Phi_2 = (0.5, 0.3, 1)$$

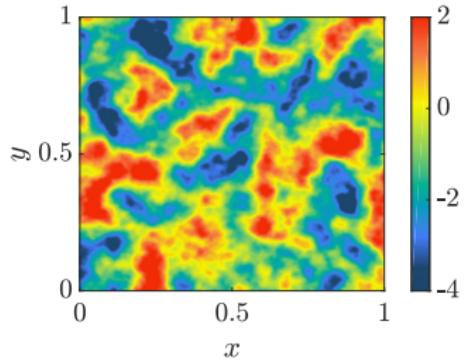
Isotropic random fields



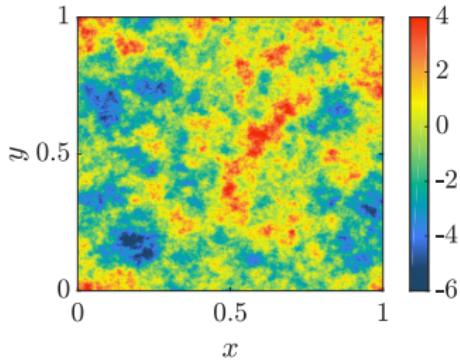
$\Phi_1 = (1.5, 0.3, 1)$



$\Phi_2 = (0.5, 0.3, 1)$

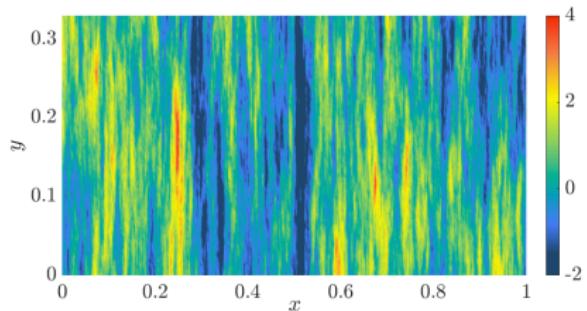


$\Phi_3 = (1.5, 0.1, 3)$

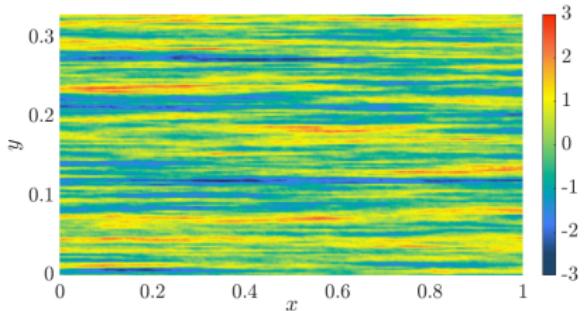


$\Phi_4 = (0.5, 0.1, 3)$

Anisotropic random fields

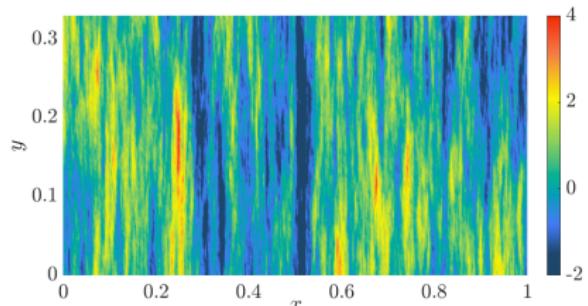


$$\lambda_{cx} = 0.06, \lambda_{cy} = 0.33$$

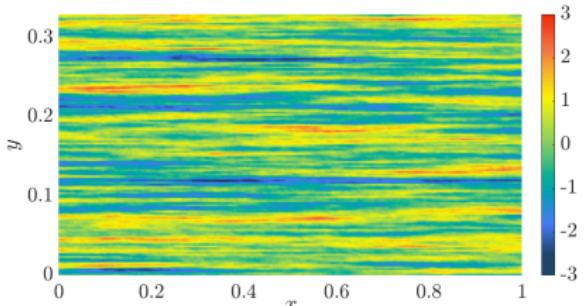


$$\lambda_{cx} = 2, \lambda_{cy} = 0.02$$

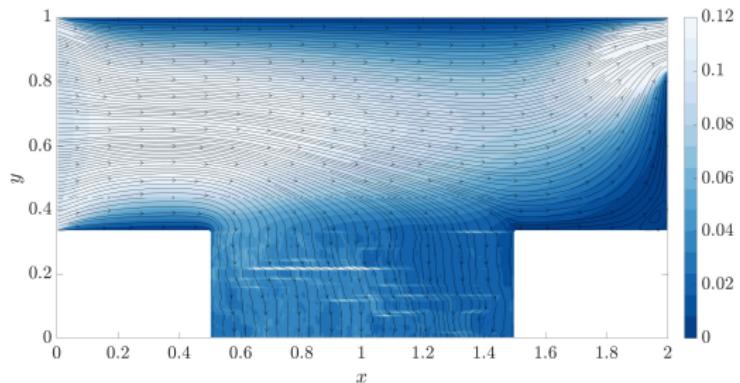
Anisotropic random fields



$$\lambda_{cx} = 0.06, \lambda_{cy} = 0.33$$



$$\lambda_{cx} = 2, \lambda_{cy} = 0.02$$



Cross-flow filtration problem

Stochastic transport model

$$\phi \frac{\partial c}{\partial t} + \nabla \cdot (c \mathbf{u} - \mathbb{D} \nabla c) = \phi f^t$$

$$c = c_0 \quad \text{in} \quad t = 0.$$

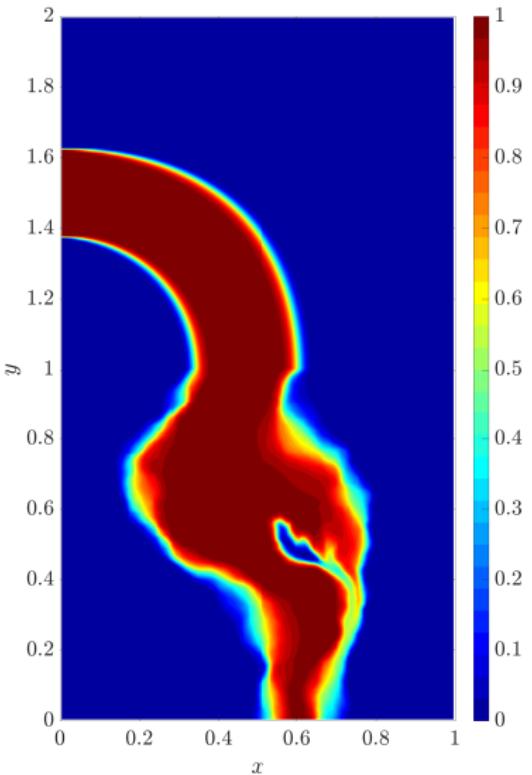
Boundary condition

$$(\mathbf{c}\mathbf{u} - \mathbb{D} \nabla c) \cdot \mathbf{n} = (c_{in} \mathbf{u}) \cdot \mathbf{n} \quad \text{inflow boundary}$$

$$\mathbb{D} \nabla c \cdot \mathbf{n} = 0 \quad \text{outflow boundary}$$

Discontinuous inflow condition

$$c_{in}(0, y, t) = 1, \quad \text{for} \quad |y - 1.5| \leq 1/8, \quad t \geq 0$$



Stochastic transport model

$$\phi \frac{\partial c}{\partial t} + \nabla \cdot (c \mathbf{u} - \mathbb{D} \nabla c) = \phi f^t$$

$$c = c_0 \quad \text{in} \quad t = 0.$$

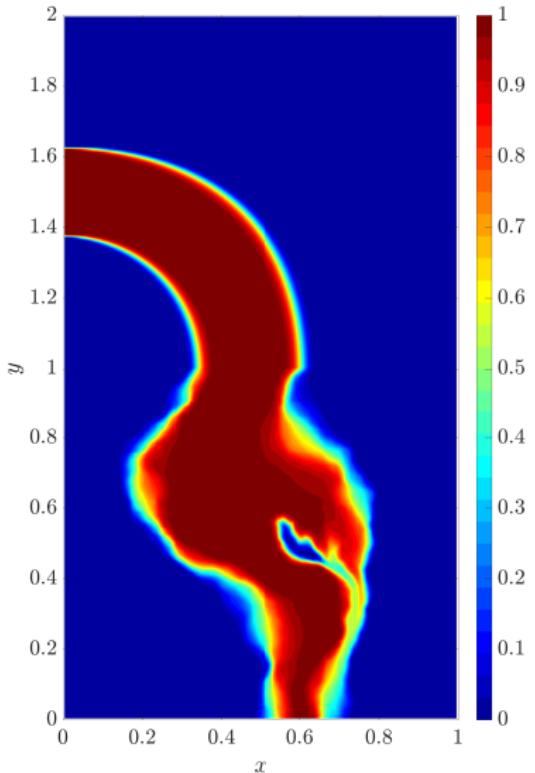
Boundary condition

$$(\mathbf{c}\mathbf{u} - \mathbb{D} \nabla c) \cdot \mathbf{n} = (c_{in} \mathbf{u}) \cdot \mathbf{n} \quad \text{inflow boundary}$$

$$\mathbb{D} \nabla c \cdot \mathbf{n} = 0 \quad \text{outflow boundary}$$

Discontinuous inflow condition

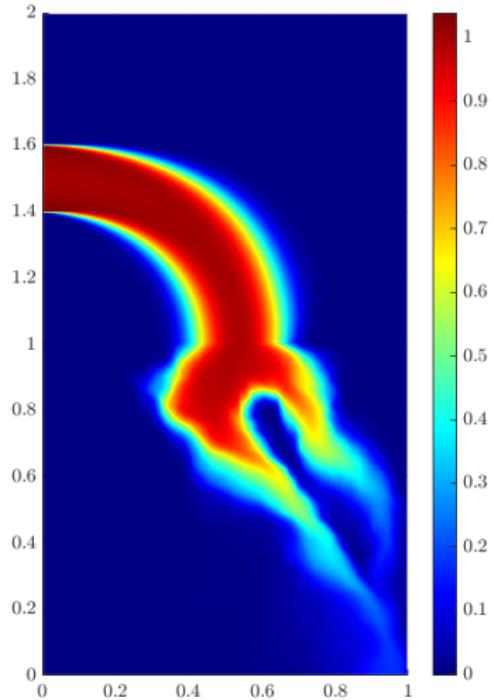
$$c_{in}(0, y, t) = 1, \quad \text{for} \quad |y - 1.5| \leq 1/8, \quad t \geq 0$$



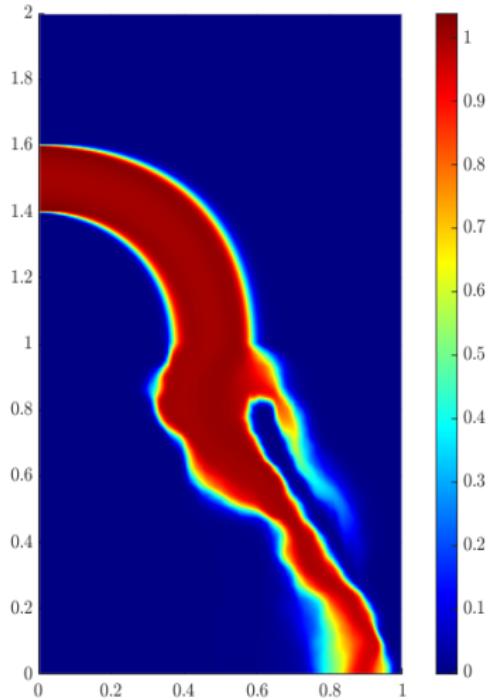
Discretization: Quadratic upwinding combined with ADI time-stepping

Sensitivity to numerical diffusion

First order upwind $c(x, y, t = 6.0)$



Flux limited QUICK¹ $c(x, y, t = 6.0)$



1. Solver optimized w.r.t random inputs

Monolithic multigrid for Darcy-Stokes flow

Benchmarking

ADI time-stepping for transport

2. Multilevel Monte Carlo (MLMC) method

MLMC estimator and error analysis

Sampling strategies and computational complexity

3. Performance of the Multigrid MLMC method

Multigrid

$$L_h u_h = f_h, \quad u_h^m \rightarrow u_h^{m+1}$$

Multigrid

$$L_h u_h = f_h, \quad u_h^m \rightarrow u_h^{m+1}$$

Pre-smoothing: $\bar{u}_h^m = \mathcal{S}_h u_h^m$

Post-smoothing: $u_h^{m+1} = \mathcal{S}_h \bar{u}_h^{m+1}$

Compute: $\bar{r}_h^m = f_h - L_h \bar{u}_h^m$



Correct: $\bar{u}_h^{m+1} = \bar{u}_h^m + \bar{e}_h^m$

Restriction: $\bar{r}_{2h}^m = \mathcal{I}_h^{2h} \bar{r}_h^m$

Interpolate: $\bar{e}_h^m = \mathcal{I}_{2h}^h \bar{e}_{2h}^m$

Solve: $L_{2h} \bar{e}_{2h}^m = \bar{r}_{2h}^m$

Saddle point system

Discretization of the Darcy-Stokes system

$$\begin{bmatrix} \mathcal{A}_h & \mathcal{B}_h^T \\ \mathcal{B}_h & 0 \end{bmatrix} \begin{bmatrix} \mathbf{u}_h \\ p_h \end{bmatrix} = \begin{bmatrix} \mathbf{g}_h \\ f_h \end{bmatrix}$$

- ▶ \mathcal{B}_h^T : discrete gradient
- ▶ \mathcal{B}_h : minus discrete divergence
- ▶ \mathcal{A}_h : discrete $-\eta\Delta$ for the Stokes equation
discrete $K^{-1}I_h$ for the Darcy equation

Uzawa smoothing

Splitting the saddle point system:

$$\begin{bmatrix} \mathcal{A}_h & \mathcal{B}_h^T \\ \mathcal{B}_h & 0 \end{bmatrix} = \begin{bmatrix} \mathcal{M}_h & 0 \\ \mathcal{B}_h & -\zeta_h^{-1} I_h \end{bmatrix} - \begin{bmatrix} \mathcal{M}_h - \mathcal{A}_h & -\mathcal{B}_h^T \\ 0 & -\zeta_h^{-1} I_h \end{bmatrix}$$

- ▶ ζ_h : some positive parameter
- ▶ \mathcal{M}_h : a suitable smoother corresponding to operator \mathcal{A}_h

Uzawa smoother

Define an iteration $\mathbf{u}_h^{k-1}, p_h^{k-1} \rightarrow \mathbf{u}_h^k, p_h^k$

$$\begin{bmatrix} \mathcal{M}_h & 0 \\ \mathcal{B}_h & -\zeta_h^{-1} I_h \end{bmatrix} \begin{bmatrix} \mathbf{u}_h^k \\ p_h^k \end{bmatrix} = \begin{bmatrix} \mathcal{M}_h - \mathcal{A}_h & -\mathcal{B}_h^T \\ 0 & -\zeta_h^{-1} I_h \end{bmatrix} \begin{bmatrix} \mathbf{u}_h^{k-1} \\ p_h^{k-1} \end{bmatrix} + \begin{bmatrix} \mathbf{g}_h \\ f_h \end{bmatrix}$$

Uzawa smoother

Define an iteration $\mathbf{u}_h^{k-1}, p_h^{k-1} \rightarrow \mathbf{u}_h^k, p_h^k$

$$\begin{bmatrix} \mathcal{M}_h & 0 \\ \mathcal{B}_h & -\zeta_h^{-1} I_h \end{bmatrix} \begin{bmatrix} \mathbf{u}_h^k \\ p_h^k \end{bmatrix} = \begin{bmatrix} \mathcal{M}_h - \mathcal{A}_h & -\mathcal{B}_h^T \\ 0 & -\zeta_h^{-1} I_h \end{bmatrix} \begin{bmatrix} \mathbf{u}_h^{k-1} \\ p_h^{k-1} \end{bmatrix} + \begin{bmatrix} \mathbf{g}_h \\ f_h \end{bmatrix}$$

Symmetric Gauss-Seidel iteration for velocity

$$\mathbf{u}_h^k = \mathbf{u}_h^{k-1} + \mathcal{M}_h^{-1} \left(\mathbf{g}_h - \mathcal{A}_h \mathbf{u}_h^{k-1} - \mathcal{B}_h^T p_h^{k-1} \right)$$

Uzawa smoother

Define an iteration $\mathbf{u}_h^{k-1}, p_h^{k-1} \rightarrow \mathbf{u}_h^k, p_h^k$

$$\begin{bmatrix} \mathcal{M}_h & 0 \\ \mathcal{B}_h & -\zeta_h^{-1} I_h \end{bmatrix} \begin{bmatrix} \mathbf{u}_h^k \\ p_h^k \end{bmatrix} = \begin{bmatrix} \mathcal{M}_h - \mathcal{A}_h & -\mathcal{B}_h^T \\ 0 & -\zeta_h^{-1} I_h \end{bmatrix} \begin{bmatrix} \mathbf{u}_h^{k-1} \\ p_h^{k-1} \end{bmatrix} + \begin{bmatrix} \mathbf{g}_h \\ f_h \end{bmatrix}$$

Symmetric Gauss-Seidel iteration for velocity

$$\mathbf{u}_h^k = \mathbf{u}_h^{k-1} + \mathcal{M}_h^{-1} \left(\mathbf{g}_h - \mathcal{A}_h \mathbf{u}_h^{k-1} - \mathcal{B}_h^T p_h^{k-1} \right)$$

Richardson iteration for pressure

$$p_h^k = p_h^{k-1} + \zeta_h (\mathcal{B}_h \mathbf{u}_h^k - f_h)$$

Optimal Richardson parameter

Local Fourier Analysis (LFA) is used to obtain optimal ζ_h

$$\zeta_h(i, j) = \begin{cases} \eta \text{ (viscosity)} & \text{in Stokes domain} \\ \frac{\eta h^2}{5\bar{K}_h(i, j)} & \text{in Darcy domain} \end{cases}$$

where

$$\bar{K}_h(i, j) = \frac{1}{8}[4K_{i,j} + K_{i-1,j} + K_{i+1,j} + K_{i,j-1} + K_{i,j+1}]$$

Optimal Richardson parameter

Local Fourier Analysis (LFA) is used to obtain optimal ζ_h

$$\zeta_h(i, j) = \begin{cases} \eta \text{ (viscosity)} & \text{in Stokes domain} \\ \frac{\eta h^2}{5\bar{K}_h(i, j)} & \text{in Darcy domain} \end{cases}$$

where

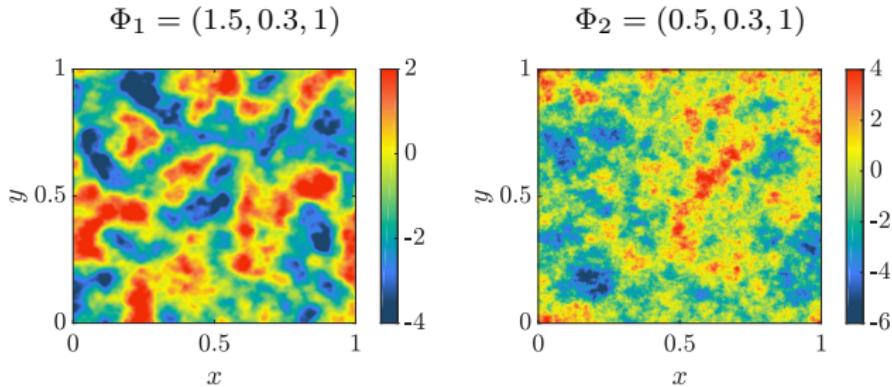
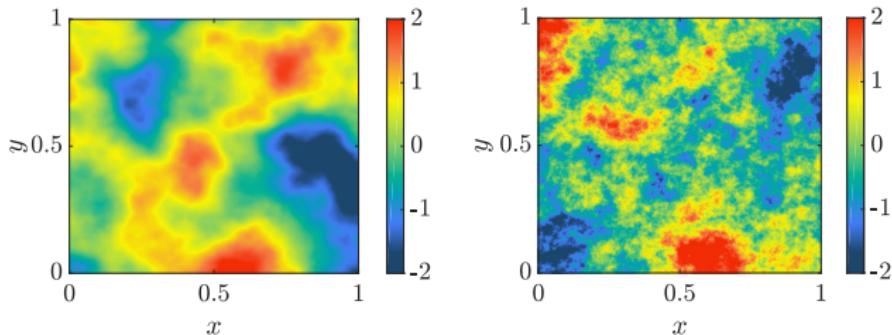
$$\bar{K}_h(i, j) = \frac{1}{8}[4K_{i,j} + K_{i-1,j} + K_{i+1,j} + K_{i,j-1} + K_{i,j+1}]$$

Optimized w.r.t random field

- fluctuations in permeability is incorporated via $\bar{K}_h(i, j)$
- ζ_h is modified on each grid level

Benchmarking

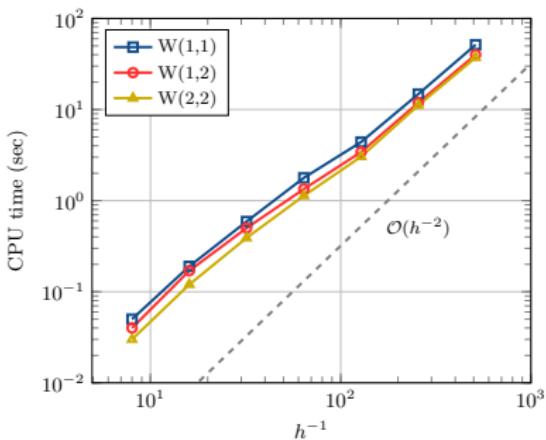
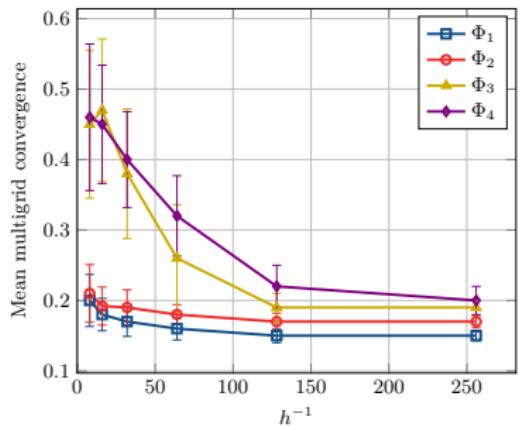
$$\Phi = (\nu_c, \lambda_c, \sigma_c^2) = (\text{smoothness, correlation length, variance})$$



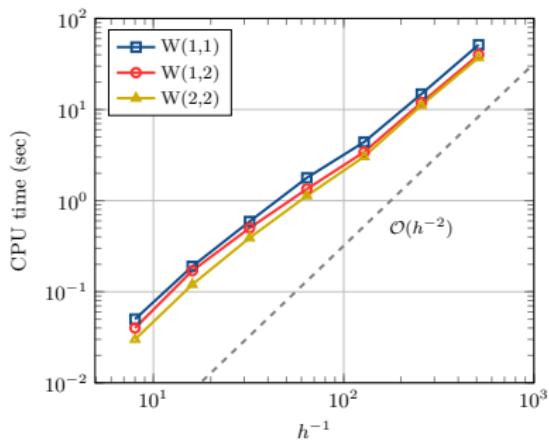
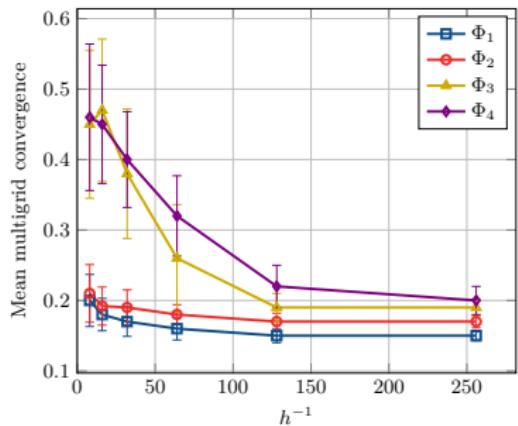
$$\Phi_3 = (1.5, 0.1, 3)$$

$$\Phi_4 = (0.5, 0.1, 3)$$

Multigrid performance for W(2,2)-cycle



Multigrid performance for W(2,2)-cycle



- Efficiency matches with constant permeability case after certain refinement

Alternating Direction Implicit (ADI) time-stepping

Semi-discrete formulation for transport equation

$$\frac{\partial c_h}{\partial t} + \mathcal{L}_h c_h = f_h$$

Alternating Direction Implicit (ADI) time-stepping

Semi-discrete formulation for transport equation

$$\frac{\partial c_h}{\partial t} + \mathcal{L}_h c_h = f_h$$

Apply splitting : $\mathcal{L}_h = \mathcal{L}_h^x + \mathcal{L}_h^y$

Alternating Direction Implicit (ADI) time-stepping

Semi-discrete formulation for transport equation

$$\frac{\partial c_h}{\partial t} + \mathcal{L}_h c_h = f_h$$

Apply splitting : $\mathcal{L}_h = \mathcal{L}_h^x + \mathcal{L}_h^y$

$$\left(I_h + \frac{\Delta t}{2} \mathcal{L}_h^x \right) c_h^{m-1/2} = \frac{\Delta t}{2} f_h^{m-1/2} + \left(I_h - \frac{\Delta t}{2} \mathcal{L}_h^y \right) c_h^{m-1}$$

x-Implicit, y-Explicit

Alternating Direction Implicit (ADI) time-stepping

Semi-discrete formulation for transport equation

$$\frac{\partial c_h}{\partial t} + \mathcal{L}_h c_h = f_h$$

Apply splitting : $\mathcal{L}_h = \mathcal{L}_h^x + \mathcal{L}_h^y$

$$(I_h + \frac{\Delta t}{2} \mathcal{L}_h^x) c_h^{m-1/2} = \frac{\Delta t}{2} f_h^{m-1/2} + (I_h - \frac{\Delta t}{2} \mathcal{L}_h^y) c_h^{m-1} \quad \text{x-Implicit, y-Explicit}$$

$$(I_h + \frac{\Delta t}{2} \mathcal{L}_h^y) c_h^m = \frac{\Delta t}{2} f_h^m + (I_h - \frac{\Delta t}{2} \mathcal{L}_h^x) c_h^{m-1/2} \quad \text{y-Implicit, x-Explicit}$$

Alternating Direction Implicit (ADI) time-stepping

Semi-discrete formulation for transport equation

$$\frac{\partial c_h}{\partial t} + \mathcal{L}_h c_h = f_h$$

Apply splitting : $\mathcal{L}_h = \mathcal{L}_h^x + \mathcal{L}_h^y$

$$(I_h + \frac{\Delta t}{2} \mathcal{L}_h^x) c_h^{m-1/2} = \frac{\Delta t}{2} f_h^{m-1/2} + (I_h - \frac{\Delta t}{2} \mathcal{L}_h^y) c_h^{m-1} \quad \text{x-Implicit, y-Explicit}$$

$$(I_h + \frac{\Delta t}{2} \mathcal{L}_h^y) c_h^m = \frac{\Delta t}{2} f_h^m + (I_h - \frac{\Delta t}{2} \mathcal{L}_h^x) c_h^{m-1/2} \quad \text{y-Implicit, x-Explicit}$$

Benefits:

- ▶ Requires inverting two tridiagonal matrices
- ▶ Second-order accurate in time
- ▶ Unconditionally stable (coarser time-step can be used in MLMC)

1. Solver optimized w.r.t random inputs

Monolithic multigrid for Darcy-Stokes flow

Benchmarking

ADI time-stepping for transport

2. Multilevel Monte Carlo (MLMC) method

MLMC estimator and error analysis

Sampling strategies and computational complexity

3. Performance of the Multigrid MLMC method

Monte Carlo for stochastic transport model

Monte Carlo estimator

$$\mathbb{E}[c_h] \approx \mathcal{E}_N^{MC}[c_h] := \frac{1}{N} \sum_{i=1}^N c_h(\omega_i)$$

Monte Carlo for stochastic transport model

Monte Carlo estimator

$$\mathbb{E}[c_h] \approx \mathcal{E}_N^{MC}[c_h] := \frac{1}{N} \sum_{i=1}^N c_h(\omega_i)$$

- ▶ Balance discretization error $\mathcal{O}(h^\alpha)$ with sampling error $\sqrt{\frac{\mathbb{V}[c]}{N}}$

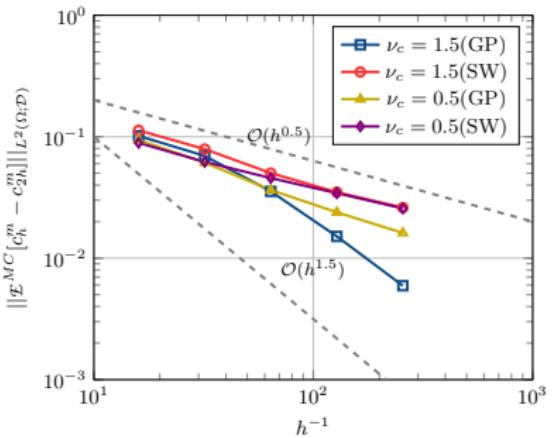
Monte Carlo for stochastic transport model

Monte Carlo estimator

$$\mathbb{E}[c_h] \approx \mathcal{E}_N^{MC}[c_h] := \frac{1}{N} \sum_{i=1}^N c_h(\omega_i)$$

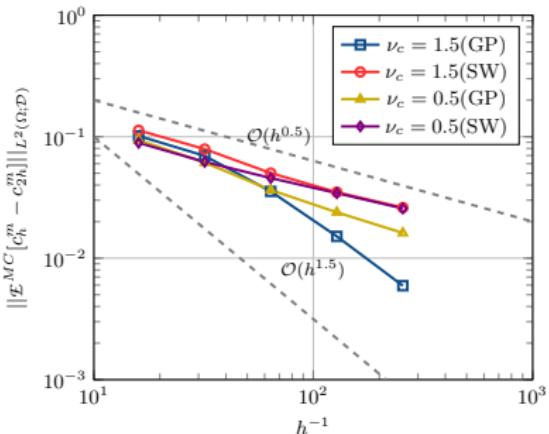
- ▶ Balance discretization error $\mathcal{O}(h^\alpha)$ with sampling error $\sqrt{\frac{\mathbb{V}[c]}{N}}$
- ▶ Cost scales as $\sim \mathcal{O}(h^{-(2\alpha+\gamma)})$ where $\mathcal{O}(h^{-\gamma})$ is cost of one sample

Discretization error (α)



Inflow boundary conditions: Gaussian plume (GP) and Square wave (SW)

Discretization error (α)



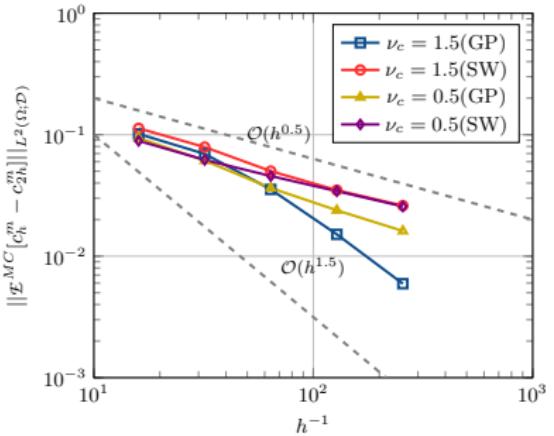
Inflow boundary conditions: Gaussian plume (GP) and Square wave (SW)

For “hardest” case: $\nu_c = 0.5$ (SW)

$\alpha = \nu_c = 0.5$ (rough permeability field)

$\gamma = 3$ (optimal solver for 2D unsteady problems)

Discretization error (α)



Inflow boundary conditions: Gaussian plume (GP) and Square wave (SW)

For “hardest” case: $\nu_c = 0.5$ (SW)

$\alpha = \nu_c = 0.5$ (rough permeability field)

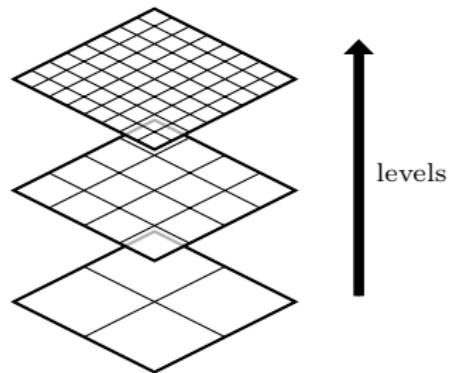
$\gamma = 3$ (optimal solver for 2D unsteady problems)

- To get an error reduction of factor 2 → cost grows by a factor of 256

Multilevel Monte Carlo (MLMC)

Distribute the cost on a hierarchy of levels:

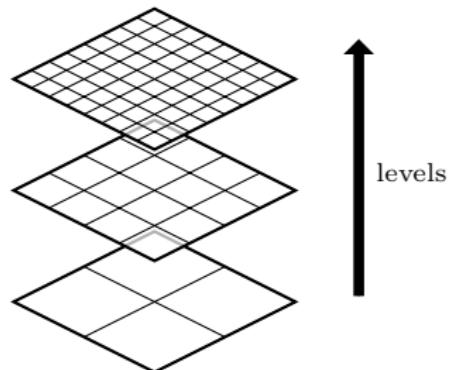
$$\mathbb{E}[c_L] = \mathbb{E}[c_0] + \sum_{\ell=1}^L \mathbb{E}[c_\ell - c_{\ell-1}]$$



Multilevel Monte Carlo (MLMC)

Distribute the cost on a hierarchy of levels:

$$\mathbb{E}[c_L] = \mathbb{E}[c_0] + \sum_{\ell=1}^L \mathbb{E}[c_\ell - c_{\ell-1}]$$



Inexpensive to compute

- ▶ $\mathbb{E}[c_0]$ due to coarse grid
- ▶ $\mathbb{E}[c_\ell - c_{\ell-1}]$ due to small sample variance $\mathbb{V}[c_\ell - c_{\ell-1}]$

MLMC estimator

Standard Monte Carlo estimator for each expectation

$$\mathcal{E}_L^{ML}[c_L] := \mathcal{E}_{N_0}^{MC}[c_0] + \sum_{\ell=1}^L \mathcal{E}_{N_\ell}^{MC}[c_\ell - c_{\ell-1}]$$

MLMC estimator

Standard Monte Carlo estimator for each expectation

$$\mathcal{E}_L^{ML}[c_L] := \mathcal{E}_{N_0}^{MC}[c_0] + \sum_{\ell=1}^L \mathcal{E}_{N_\ell}^{MC}[c_\ell - c_{\ell-1}]$$

The associated MSE can be decomposed as

$$\left\| \mathbb{E}[c] - \mathcal{E}_L^{ML}[c_L] \right\|_{L^2(\Omega, \mathcal{D})}^2 \leq \mathcal{O}(h_L^{2\alpha}) + \sum_{\ell=0}^L \frac{\mathcal{V}[c_\ell - c_{\ell-1}]}{N_\ell},$$

MLMC estimator

Standard Monte Carlo estimator for each expectation

$$\mathcal{E}_L^{ML}[c_L] := \mathcal{E}_{N_0}^{MC}[c_0] + \sum_{\ell=1}^L \mathcal{E}_{N_\ell}^{MC}[c_\ell - c_{\ell-1}]$$

The associated MSE can be decomposed as

$$\left\| \mathbb{E}[c] - \mathcal{E}_L^{ML}[c_L] \right\|_{L^2(\Omega, \mathcal{D})}^2 \leq \mathcal{O}(h_L^{2\alpha}) + \sum_{\ell=0}^L \frac{\mathcal{V}[c_\ell - c_{\ell-1}]}{N_\ell},$$

- Best possible MSE is $\sim \mathcal{O}(h_L^{2\alpha}) = TOL^2$

Sampling strategy

- ▶ Fix number of samples on finest level, $N_L \sim \mathcal{O}(10)$

Sampling strategy

- ▶ Fix number of samples on finest level, $N_L \sim \mathcal{O}(10)$

Ideally:
$$\frac{\mathcal{V}[c_L - c_{L-1}]}{N_L} < \text{TOL}^2$$

Sampling strategy

- ▶ Fix number of samples on finest level, $N_L \sim \mathcal{O}(10)$

Ideally:
$$\frac{\mathcal{V}[c_L - c_{L-1}]}{N_L} < \text{TOL}^2$$

- ▶ This also holds for coarser level

$$\frac{\mathcal{V}[c_\ell - c_{\ell-1}]}{N_\ell} < \text{TOL}^2$$

Sampling strategy

- ▶ Fix number of samples on finest level, $N_L \sim \mathcal{O}(10)$

$$\text{ Ideally: } \frac{\mathcal{V}[c_L - c_{L-1}]}{N_L} < \text{TOL}^2$$

- ▶ This also holds for coarser level

$$\frac{\mathcal{V}[c_\ell - c_{\ell-1}]}{N_\ell} < \text{TOL}^2$$

- ▶ Assuming $\mathcal{V}[c_\ell - c_{\ell-1}] = \mathcal{O}(h_\ell^\beta)$, we get $N_\ell = N_L 2^{\beta(L-\ell)}$

Sampling strategy

- ▶ Fix number of samples on finest level, $N_L \sim \mathcal{O}(10)$

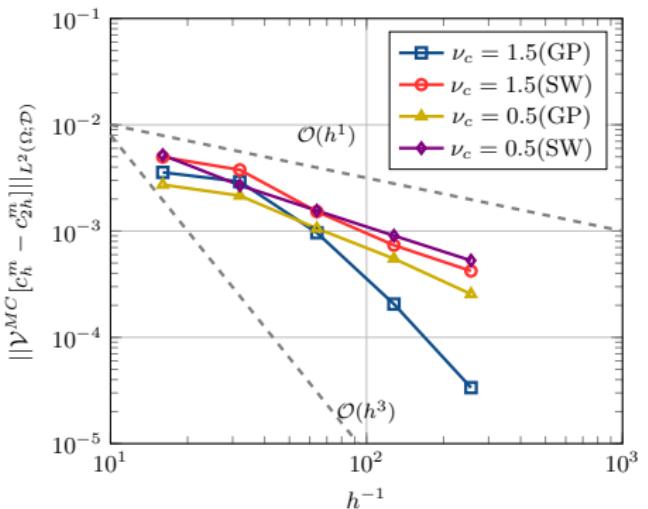
$$\text{ Ideally: } \frac{\mathcal{V}[c_L - c_{L-1}]}{N_L} < \text{TOL}^2$$

- ▶ This also holds for coarser level

$$\frac{\mathcal{V}[c_\ell - c_{\ell-1}]}{N_\ell} < \text{TOL}^2$$

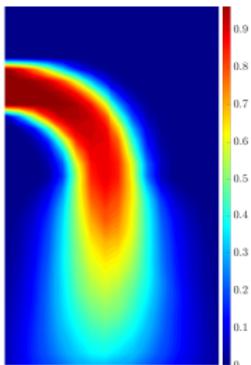
- ▶ Assuming $\mathcal{V}[c_\ell - c_{\ell-1}] = \mathcal{O}(h_\ell^\beta)$, we get $N_\ell = N_L 2^{\beta(L-\ell)}$
 - *Asymptotically optimized*

Level-dependent variance (β)

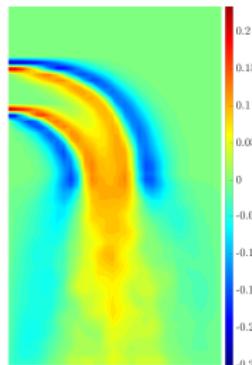


- Typically, variance decays 2x faster than the discretization error, i.e. $\beta = 2\alpha$
- From this, we can deduce $N_\ell = N_L 2^{\beta(L-\ell)}$

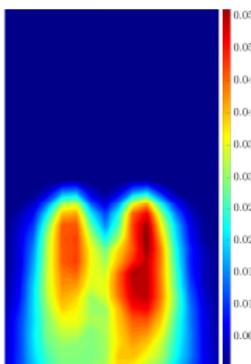
2-level MLMC: Concentration field at $t = 6.00$



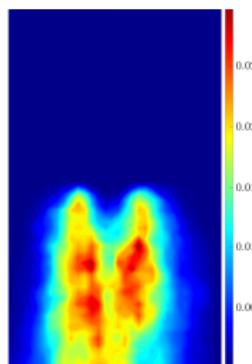
$$\mathbb{E}[c_0] \quad | \quad h_0 = \nabla t_0 = 1/16 \quad | \quad N_0 = 512$$



$$\mathbb{E}[c_1 - c_0] \quad | \quad h_1 = \nabla t_1 = 1/32 \quad | \quad N_1 = 256$$

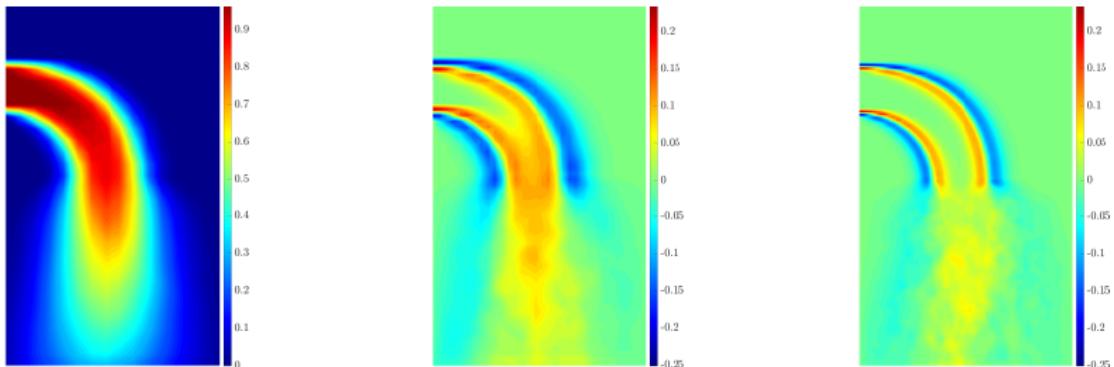


$$\mathbb{V}[c_0] \quad | \quad h_0 = \nabla t_0 = 1/16 \quad | \quad N_0 = 512$$



$$\mathbb{V}[c_1] - \mathbb{V}[c_0] \quad | \quad h_1 = \nabla t_1 = 1/32 \quad | \quad N_1 = 256$$

3-level MLMC: Concentration field at $t = 6.00$



$\mathbb{E}[c_0]$

$\mathbb{E}[c_1 - c_0]$

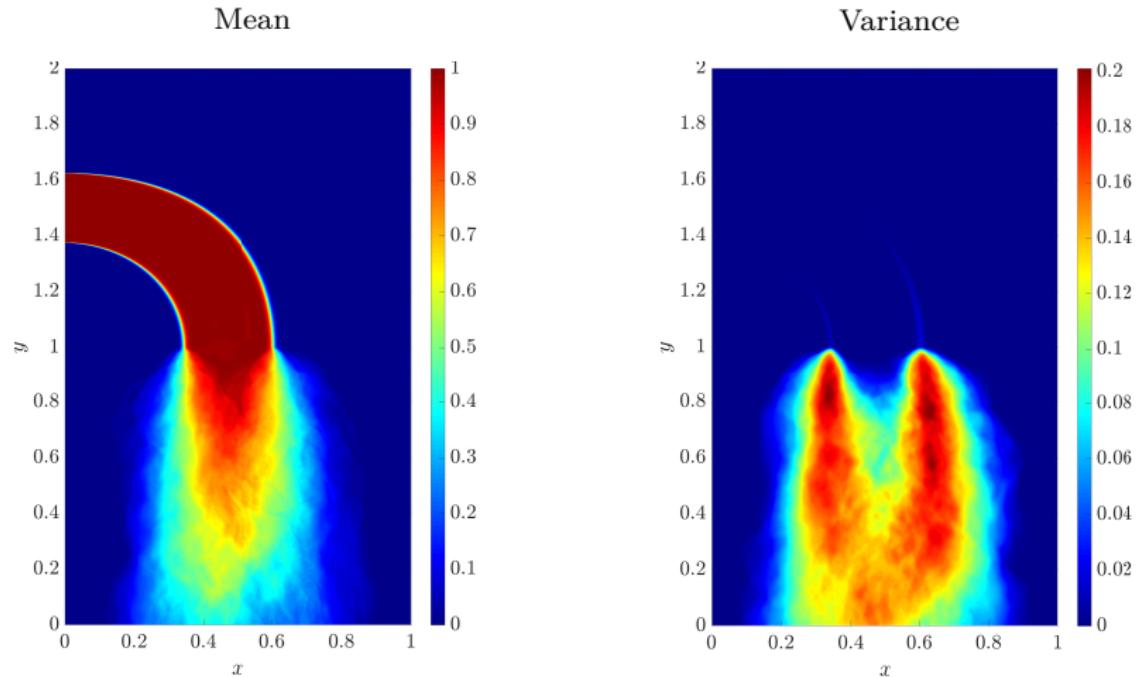
$\mathbb{E}[c_2 - c_1]$

$V[c_0]$

$V[c_1] - V[c_0]$

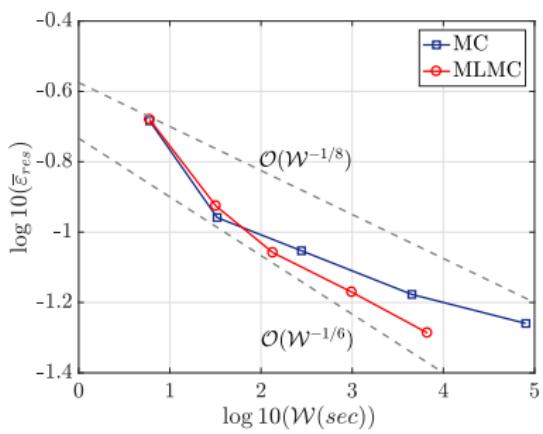
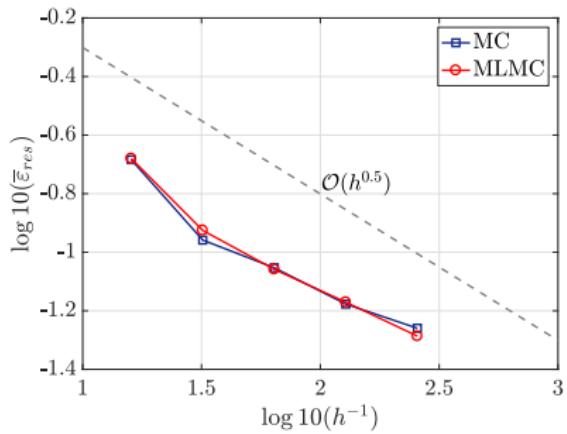
$V[c_2] - V[c_1]$

6-level MLMC estimate: Concentration field $c(x, y, T = 6.00)$



- Finest level: $h_L = \nabla t_L = 1/512$
- Sampling sequence: $N_\ell = N_L 2^{(L-\ell)}$ with $N_L = 16$
- Uncertainty dimension: 512×512

Accuracy vs cost



- Asymptotically optimal MLMC estimator

Conclusion

Presented a multigrid MLMC method for transport in Darcy-Stokes flow

- ▶ Uzawa smoothers in multigrid can result in a fast solver for Darcy-Stokes flow
- ▶ Transport in random porous media is very sensitive to numerical diffusion
- ▶ ADI method is highly suitable for MLMC due to stability, accuracy and fast time-stepping
- ▶ For rough problems, MLMC estimator has same computational complexity as its deterministic counterpart

Thank you for your attention!

Questions?

1. P. Kumar, C. W. Oosterlee, R. P. Dwight, *A Multigrid Multilevel Monte Carlo method using high-order finite-volume scheme for lognormal diffusion problem*, *International Journal for Uncertainty Quantification* 7 (1) (2017) 57-81.
2. P. Kumar, P. Luo, F. J. Gaspar, C. W. Oosterlee, *A multigrid multilevel Monte Carlo method for transport in the Darcy-Stokes system*, *Journal of Computational Physics* (to appear)
3. P. Kumar, C. Rodrigo, F. J. Gaspar, C. W. Oosterlee, *On cell-centered multigrid methods and Local Fourier Analysis for PDEs with random coefficients*, *arXiv preprint arXiv:1803.08864*

MLMC complexity

Cost of MLMC estimator

$$\mathcal{W}_L^{ML} = \sum_{\ell=0}^L N_\ell \mathcal{W}_\ell$$

MLMC complexity

Cost of MLMC estimator

$$\mathcal{W}_L^{ML} = \sum_{\ell=0}^L N_\ell \mathcal{W}_\ell = C_{big} \sum_{\ell=0}^L 2^{-\beta\ell} 2^{\gamma\ell} = C_{big} \sum_{\ell=0}^L 2^{(\gamma-\beta)\ell}$$

MLMC complexity

Cost of MLMC estimator

$$\mathcal{W}_L^{ML} = \sum_{\ell=0}^L N_\ell \mathcal{W}_\ell = C_{big} \sum_{\ell=0}^L 2^{-\beta\ell} 2^{\gamma\ell} = C_{big} \sum_{\ell=0}^L 2^{(\gamma-\beta)\ell}$$

$$\beta > \gamma$$

- ▶ Dominant cost from the coarsest level

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}(N_0 \mathcal{W}_0) \\ &= \mathcal{O}(\text{TOL}^{-2})\end{aligned}$$

MLMC complexity

Cost of MLMC estimator

$$\mathcal{W}_L^{ML} = \sum_{\ell=0}^L N_\ell \mathcal{W}_\ell = C_{big} \sum_{\ell=0}^L 2^{-\beta\ell} 2^{\gamma\ell} = C_{big} \sum_{\ell=0}^L 2^{(\gamma-\beta)\ell}$$

$$\beta > \gamma$$

$$\beta = \gamma$$

- — — — —
▶ Dominant cost from
the coarsest level

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}(N_0 \mathcal{W}_0) \\ &= \mathcal{O}(\text{TOL}^{-2})\end{aligned}$$

- — — — —
▶ All levels equally
contribute

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}((L+1)N_0 \mathcal{W}_0) \\ &= \mathcal{O}(\text{TOL}^{-2}(\log(\text{TOL}))^2)\end{aligned}$$

MLMC complexity

Cost of MLMC estimator

$$\mathcal{W}_L^{ML} = \sum_{\ell=0}^L N_\ell \mathcal{W}_\ell = C_{big} \sum_{\ell=0}^L 2^{-\beta\ell} 2^{\gamma\ell} = C_{big} \sum_{\ell=0}^L 2^{(\gamma-\beta)\ell}$$

$$\beta > \gamma$$

$$\beta = \gamma$$

$$\beta < \gamma$$

- Dominant cost from the coarsest level

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}(N_0 \mathcal{W}_0) \\ &= \mathcal{O}(\text{TOL}^{-2})\end{aligned}$$

- All levels equally contribute

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}((L+1)N_0 \mathcal{W}_0) \\ &= \mathcal{O}(\text{TOL}^{-2}(\log(\text{TOL}))^2)\end{aligned}$$

- Dominant cost from the finest level

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}(N_L \mathcal{W}_L) \\ &= \mathcal{O}(\text{TOL}^{-2-(\gamma-\beta)/\alpha})\end{aligned}$$

MLMC complexity

Cost of MLMC estimator

$$\mathcal{W}_L^{ML} = \sum_{\ell=0}^L N_\ell \mathcal{W}_\ell = C_{big} \sum_{\ell=0}^L 2^{-\beta\ell} 2^{\gamma\ell} = C_{big} \sum_{\ell=0}^L 2^{(\gamma-\beta)\ell}$$

$$\beta > \gamma$$

$$\beta = \gamma$$

$$\beta < \gamma$$

- Dominant cost from the coarsest level

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}(N_0 \mathcal{W}_0) \\ &= \mathcal{O}(\text{TOL}^{-2})\end{aligned}$$

- All levels equally contribute

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}((L+1)N_0 \mathcal{W}_0) \\ &= \mathcal{O}(\text{TOL}^{-2}(\log(\text{TOL}))^2)\end{aligned}$$

- Dominant cost from the finest level

$$\begin{aligned}\mathcal{W}_L^{ML} &= \mathcal{O}(N_L \mathcal{W}_L) \\ &= \mathcal{O}(\text{TOL}^{-2-(\gamma-\beta)/\alpha})\end{aligned}$$

– Standard MC: $\mathcal{W}^{MC} = \mathcal{O}(\text{TOL}^{-2-\gamma/\alpha})$