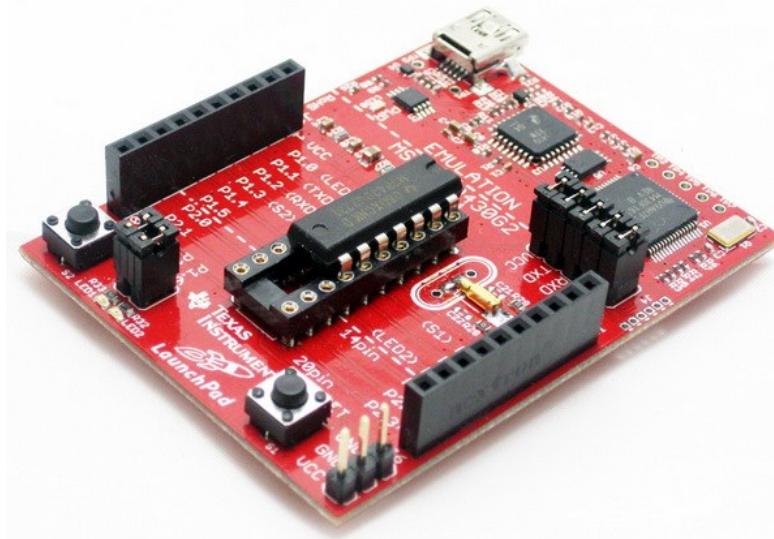


Introducing TI MSP430 Microcontrollers

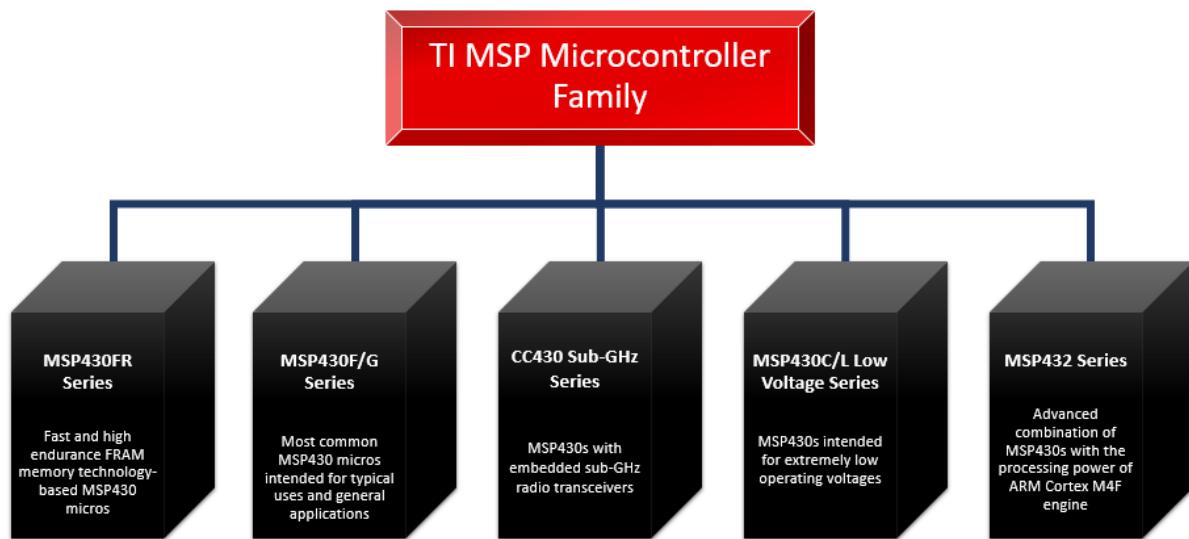
Texas Instruments (TI) is a well-known US-based semiconductor manufacturer. TI is perhaps best known to many as the manufacturer of some of the fanciest scientific calculators in the market. Of the long list of electronic devices produced by TI, microcontrollers are on the top. TI manufactures some of the coolest and advanced microcontrollers of the market today. There are several categories of micros from TI. These include general purpose low power MCUs which mainly comprise of MSP430s, ARMs like TM4Cs, MSP432s, etc, micros for wireless communications like CC2xxx series, ARM + DSP micros, DSP-specialized micros like the TMS32xxx series and so on. It will look as if TI is committed toward mixed signal microcontrollers that are engineered for highly sophisticated industrial challenges. This issue will cover an insight of value-line MSP430 general purpose micros.



MSP430s are not seen as much as the popular 8051s, PICs and AVR. In most of the Asian market, for example, MSP430s are rare when compared to other microcontrollers and even still rare when compared to other chips produced by TI itself. I don't know why there is such an imbalance. Perhaps one big reason is its inclination towards low power consumption and limited resources. Low-power means that these MCUs are crafted for special low power applications unlike most other micros. Secondly TI micros are a bit expensive than other micros. Despitess these, TI has provided some great tools for making things simple. You can get your hands on some cool MSP430 chips through some affordable Launchpad boards and still it worth every penny learning MSP430s. Firstly, it is a family of ultra-low power high performance 16-bit (16-bit data bus) micros which are unlike the popular 8-bit platforms. Secondly MSP430s have highly rich internal hardware peripherals that are second to none. For instance, MSP430s can be operated over a wide voltage and frequency ranges. Another great feature that is less common in most 8-bit micros is the DMA controller. Fortunately, MSP430s possess this. Probably it is your first such micro family that is somewhere between 8-bit and 32-bit micros. In the end, MSP430s will surely give you a taste of absolute American technology and concepts.

The MSP430 Family

Shown below is the family tree of MSP430 series microcontrollers from TI.



The most common MSP430 micros are the MSP430FR series, MSP430F series, MSP430G series and the newly introduced MSP432 series.

MSP430FR series micros mainly feature high reliability, high endurance, 10-year data retention non-volatile FRAM (ferroelectric random-access memory) memories. This series offer 16-bit solutions for ultra-low-power sensing and system management in areas like smart building management systems, smart grids, military and industrial designs. They feature the lowest standby power consumption of about 350 nA with RTC, 100 µA/MHz active power consumption and the unique ability to save and instantly restore system state right after power failures.

MSP432 series micros are the perfect combinations of MSP430 low-power portfolio with advanced mixed-signal features and the high-performance processing capabilities of 32-bit ARM M4F engine. These micros have high measurement precisions and contain high performance peripherals like high resolution differential ADCs, DMA, IOT connectivity, etc. This series fills the gap between 16-bit MSP430s and 32-bit ARM architecture and as of this moment this series is the most recent development in the MSP430 family.

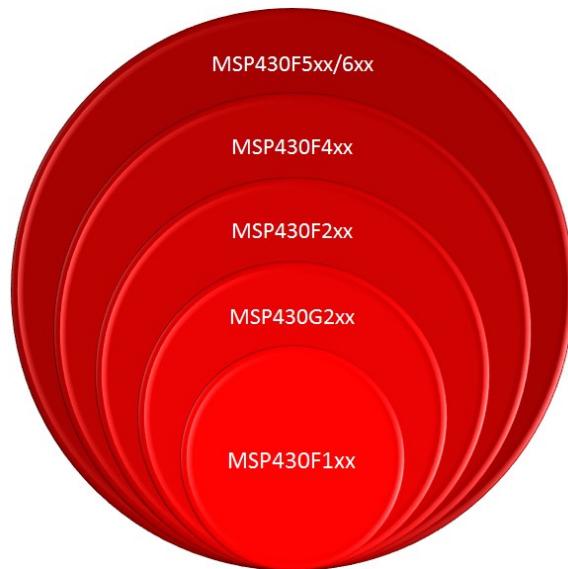
CC430 series is a small series of MSP430s with almost all features one can find in a typical MSP430 micro and embedded sub-GHz radio transceivers. They are well-stuffed true **System-on-Chip (SOC)** solutions that remove the necessity of additional off-board wireless solutions.

Yet another tiny series of MSP430 micros include MSP430Cxx and MSP430Lxx micros. These micros are intended for extreme low voltage (0.9 – 1.65V) operations. With just one Nickel Cadmium (NiCd) battery it is possible to run any micro of this series. They feature low resolution analogue frontends and low pin counts.

The only series that is left to be discussed is the general purpose MSP430s series microcontrollers. By general purpose, it is meant that these micros can be used in almost any scenario. It is this series of micros that we will be dealing here. The table below summarizes this family:

	MSP430x1xx	MSP430x2xx	MSP430x3xx	MSP430F4xx	MSP430x5xx	MSP430x6xx
Flash (KB)	1 – 60	0.5 – 120	N/A OTP UV ROM	4 - 120	1 - 512	1 - 512
ROM (KB)	1 – 16	Flash used as ROM	2 – 32	Flash used as ROM	Flash used as ROM	Flash used as ROM
RAM (KB)	0.1 – 10	0.1 – 8	0.5 – 1	0.2 – 8	1 – 66	1 – 66
Pin Count	14, 22 and 48	10, 11, 16, 24, 32 and 48	14 and 40	14, 32, 48, 56, 68, 72 and 80	29, 31, 47, 48, 63, 67, 74 and 87	74
MIPS	8	16	8	8 – 16	25	25
VDD (V)	1.8 – 3.6	1.8 – 3.6	2.5 – 5.5	1.8 – 3.6	1.6 – 3.6	1.6 – 3.6
Max. Clock (MHz)	8	16	8	16	25	25
Hardware Peripherals	ADC10, ADC12, DAC12, up to two 16-bit Timers, WDT, SVS, USART, DMA, Brownout Reset, Comp_A, 16x16 H/W Multiplier	Op Amps, ADC10, ADC12, SD16_A, SD12_A, Capacitive Touch I/Os, DAC12, up to two 16-bit Timers, Comp_A+, Brownout Reset, SVS, USI, USCI, WDT+, VLO, DMA, 16x16 H/W Multiplier	14-bit Slope ADC, UART, FLL, H/W Multiplier, LCD Controller, WDT, PWM	ADC10, ADC12, SD16_A, SCAN_IF, ESP430, DAC12, Op Amps, RTC, up to two 16-bit Timers, WDT+, Basic Timer, Brownout Reset, SVS, USART, USCI, LCD Controller, DMA, 16x16 & 32x32 H/W Multiplier, FLL, SVS, Comp_A+	ADC10, ADC12, High Resolution PWM, USB, Backup Battery Switch, up to four 16-bit Timers, WDT+, RTC, Brownout Reset, SVS, USCI, DMA, Comp_B, 32x32 H/W Multiplier, 5V Tolerant I/Os	ADC10, ADC12, DAC12, High Resolution PWM, USB, up to four 16-bit Timers, WDT+, RTC, Brownout Reset, LDO, SVS, SVM, USCI, DMA, 32x32 H/W Multiplier, Comp_B, 5V Tolerant I/Os, LCD Controller
Note	Flash-based and similar to MSP430x3xx series without LCD H/W support	Value-line-devices intended for mainly for medical instrumentations	Oldest and now obsolete	Upgraded MSP430x3xx intended for low power instruments with LCDs	High performance MCUs with USB	Advanced variant of MSP430x5xx with additional hardware like LCD controller

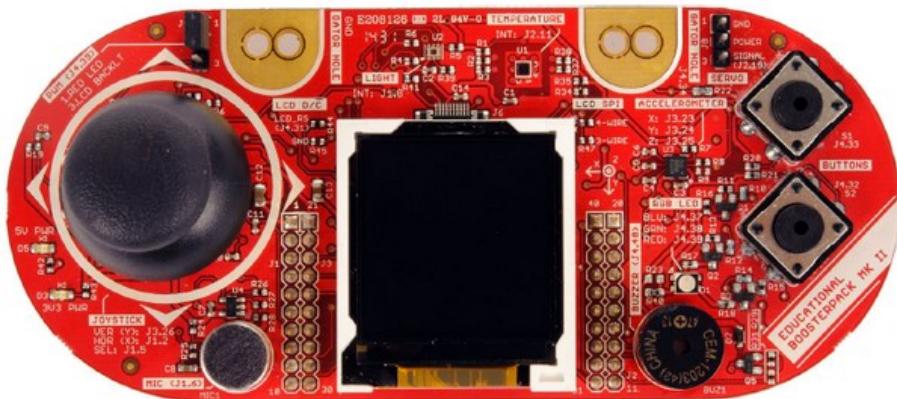
For now, don't struggle to understand the abbreviations of this table. You'll eventually know about them as we proceed.



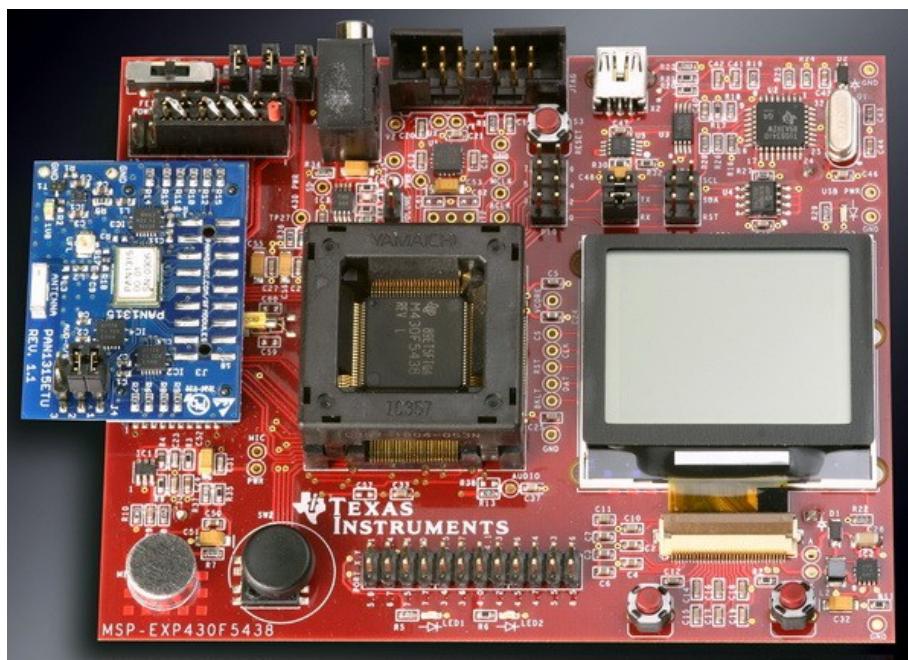
Note that there are some other MSP430 devices that are not accounted here. These devices are either rare or subset of the mentioned families. If you want to know more about MSP430s then you can read the following Wikipedia article: https://en.wikipedia.org/wiki/TI_MSP430.

Launchpad Boards and BoosterPacks

Launchpad boards are affordable MSP430 evaluation kits. For just few dollars, you can have your own Launchpad boards. They are so cheap that an average school-going student can afford one with his/her own pocket money. However, this cheapness doesn't compromise quality nor performance. They are more-or-less alike Arduino boards in terms of board size and on-board resources except they don't share same pin naming conventions and board layouts. Well that's not a big issue. However, it would have been better if the Launchpads shared Arduino-like form factor. This would have enabled using Arduino shields with Launchpads. TI has, however, its own brand of shields called **BoosterPacks** and they seem to like promoting their own idea, owing to which there's still no official TI Launchpad that share exactly Arduino form-factor/shape. It is a very aggressive marketing boldness. Shown below is the **BOOSTXL-EDUMKII BoosterPack**. It is just like Arduino Esplora with lots of on-board sensors and devices except for the MCU. It is good for game development and sensor applications. There are other useful BoosterPacks dedicated for capacitive touch, displays and so on.



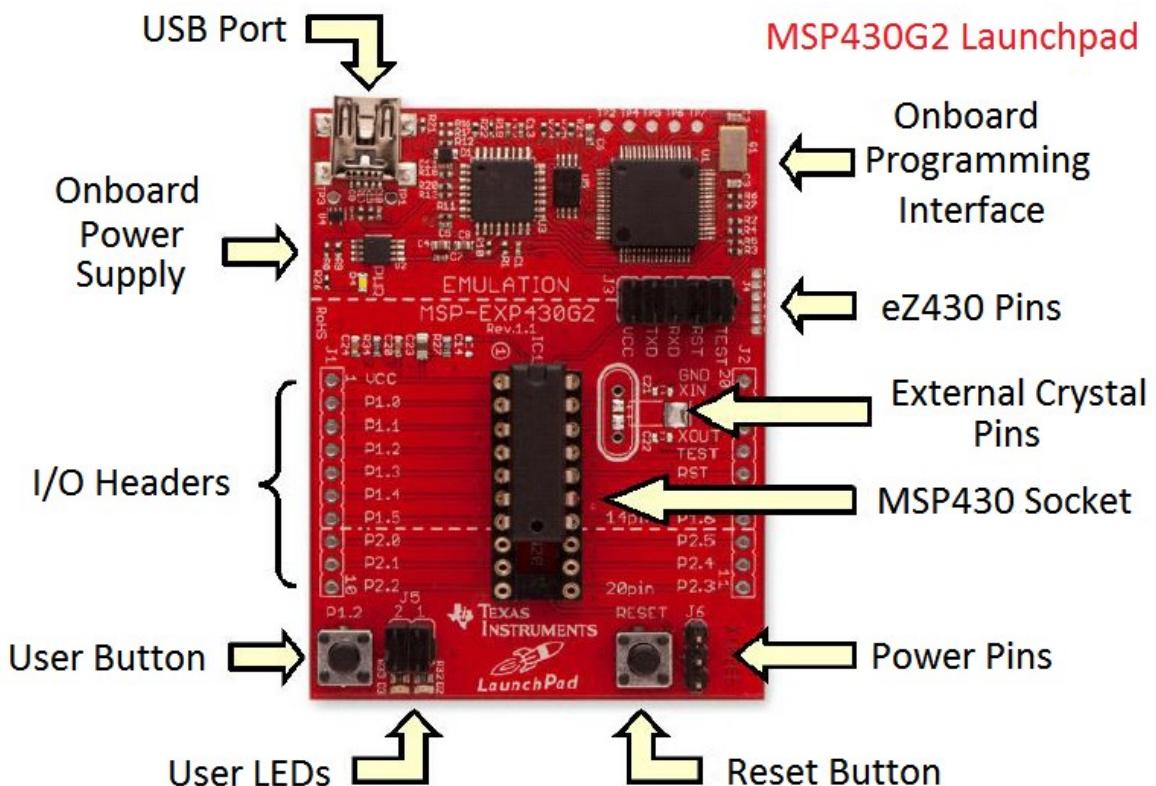
Launchpad boards are not the only development boards offered by TI. There are many other dev boards too. Shown below is the TI MSP-EXP430F5438 Bluetooth platform development board.



However due to cheapness and relatively good availability Launchpad boards are by far most popular, particularly the ***MSP-EXP430G2 Experimenter's Launchpad*** board.

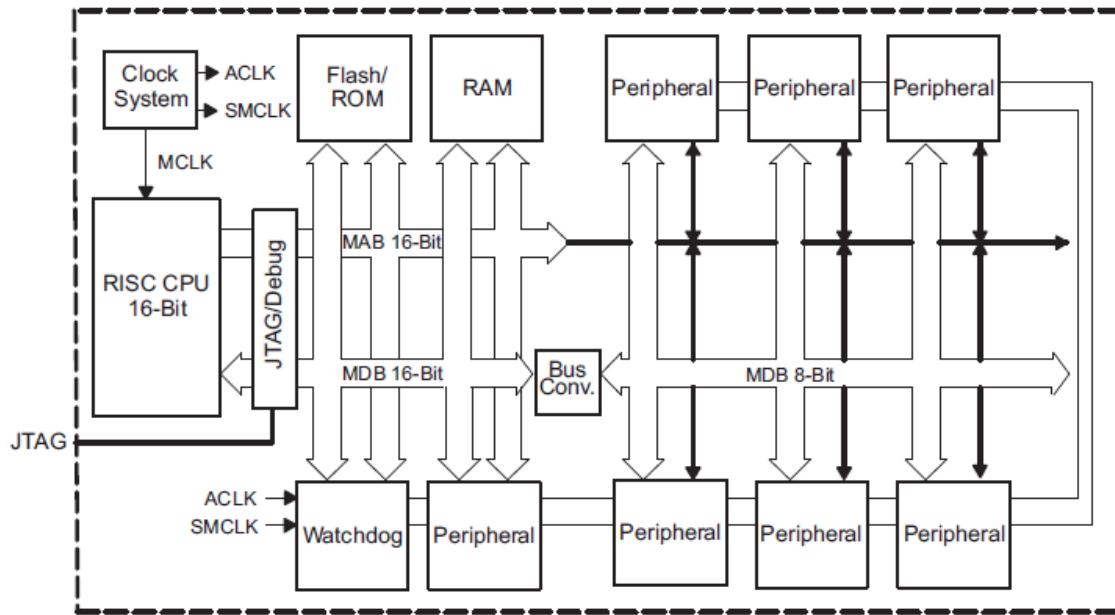


This board comes boxed with two micros – ***MSP430G2452*** and ***MSP430G2553***. Both of these mixed-signal MCUs come in PDIP packages. We can take them off from the board and use them in breadboards, strip boards, PCBs, etc. Shown below is the layout of a MSP-EXP430G2 Launchpad board.



Just like any other evaluation kit, every Launchpad comes embedded with user LEDs, buttons, I/O port headers (also known as BoosterPack connectors), onboard power supply, USB-to-serial converter and programming interfaces.

MSP430s are ultra-low power 16-bit general purpose microcontrollers. A MSP430 micro consists of a 16-bit RISC CPU, wide variety of feature-rich peripherals and a flexible clock system all under the hood of a *von-Neumann* architecture. Because of their ultra-low energy consumption profile, MSP430s are well-suited for battery/solar powered/limited or renewable energy applications.



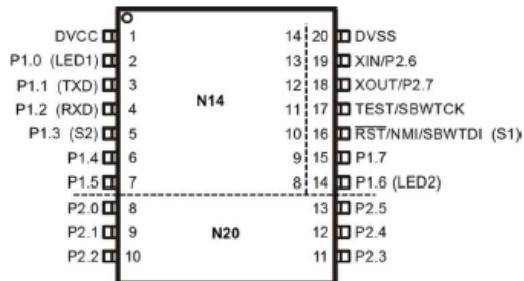
MSP430G2452 and MSP430G2553 are both almost identical in terms of hardware peripherals and pin count. MSP430G2553 has some additional hardware features like more RAM-ROM memories, timers and USCI-based hardware interfaces for LIN and IrDA communications.



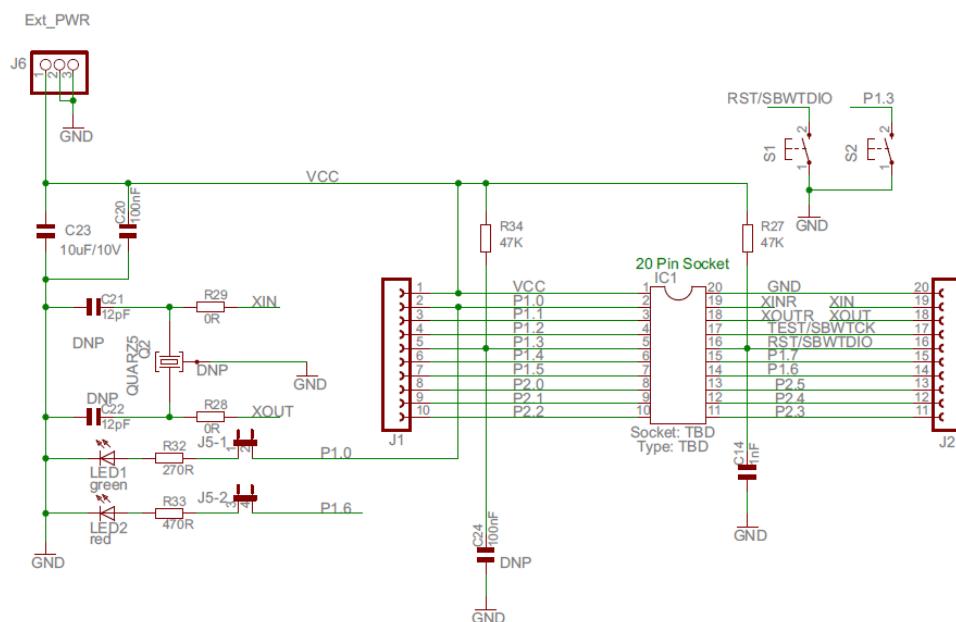
Shown below is a comparison table of some common MSP430 chips usually found with Launchpad boards.

	MSP430G2201	MSP430G2231	MSP430G2452	MSP430G2553
Program Memory (kB)	8	8	8	16
SRAM (Bytes)	128	128	256	512
I/O Pins	10	10	16	16
ADC Channels	N/A	8	8	8
ADC Resolution (Bits)	N/A	10	10	10
USI/USCI	N/A	1	1	1
16-bit Timer	1	1	1	2
Capture/Compare Hardware	2	2	3	3

Other Launchpad boards contain other chips but fortunately they share the same pin layout and so they are fully pin compatible. The fourteen pin parts and twenty pin parts share the same pin layout as shown below:



Though the pin names are labelled properly on the silkscreens of the boards, it is sometimes necessary to check the schematic for details. Shown below is the basic schematic of a MSP-EXP430G2 Launchpad.



From the schematic, we can see what has been placed on the board by default. Parts labelled **DNP** are not placed on a fresh Launchpad board. These have been left for the users.

If these don't matter much and you need something simpler, then there are Arduino-like pin maps for Launchpads. Though they are made for Energia IDE, they are useful for quick overviews.

Energia

LaunchPad with MSP430G2452

Revision 1.5

The diagram shows the physical layout of the LaunchPad with MSP430G2452. It includes a Texas Instruments MSP430G2452 microcontroller, a USB port, push buttons, and various jumpers. To the right is a detailed pin mapping table:

Hardware		Pin number	
		PC	
		P2_6	XIN
		P2_7	XOUT
			TEST
			RESET
		analogRead()	
		digitalRead() and digitalWrite()	
		digitalRead(), digitalWrite() and analogWrite()	

Flash Serial 8 KB TimerSerial

Pin Mapping Table (Pins 1-10)

+3.3V									
RED_LED		A0	P1_0	2					
	RXD	A1	P1_1	3					
	TXD	A2	P1_2	4					
PUSH2		A3	P1_3	5					
		A4	P1_4	6					
	SCK (B0)	A5	P1_5	7					
	CS (B0)		P2_0	8					
			P2_1	9					
			P2_2	10					

Pin Mapping Table (Pins 11-20)

20									GROUND
19	P2_6								XIN
18	P2_7								XOUT
17									TEST
16									RESET
15	P1_7	A7	SDA	MISO (B0)					
14	P1_6	A6	SCL	MOSI (B0)	GREEN_LED				
13	P2_5								
12	P2_4								
11	P2_3								

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version 1.3 2102-09-09

Energia

LaunchPad with MSP430G2553

Revision 1.5

The diagram shows the physical layout of the LaunchPad with MSP430G2553. It includes a Texas Instruments MSP430G2553 microcontroller, a USB port, push buttons, and various jumpers. To the right is a detailed pin mapping table:

Hardware		Pin number	
		PC	
		Serial UART	SPI
		analogRead()	
		digitalRead() and digitalWrite()	
		digitalRead(), digitalWrite() and analogWrite()	

Flash Serial 16 KB Hardware

Pin Mapping Table (Pins 1-10)

+3.3V									
RED_LED		A0	P1_0	2					
	RXD	A1	P1_1	3					
	TXD	A2	P1_2	4					
PUSH2		A3	P1_3	5					
		A4	P1_4	6					
	SCK (B0)	A5	P1_5	7					
	CS (B0)		P2_0	8					
			P2_1	9					
			P2_2	10					

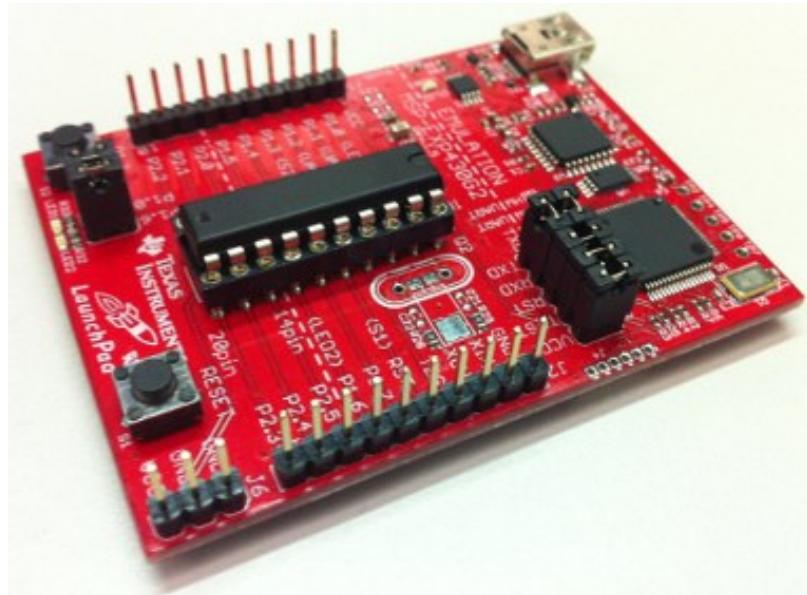
Pin Mapping Table (Pins 11-20)

20	P2_6								GROUND
19	P2_7								XIN
18									XOUT
17									TEST
16									RESET
15	P1_7	A7	SDA	MOSI (B0)					
14	P1_6	A6	SCL	MISO (B0)	GREEN_LED				
13	P2_5								
12	P2_4								
11	P2_3								

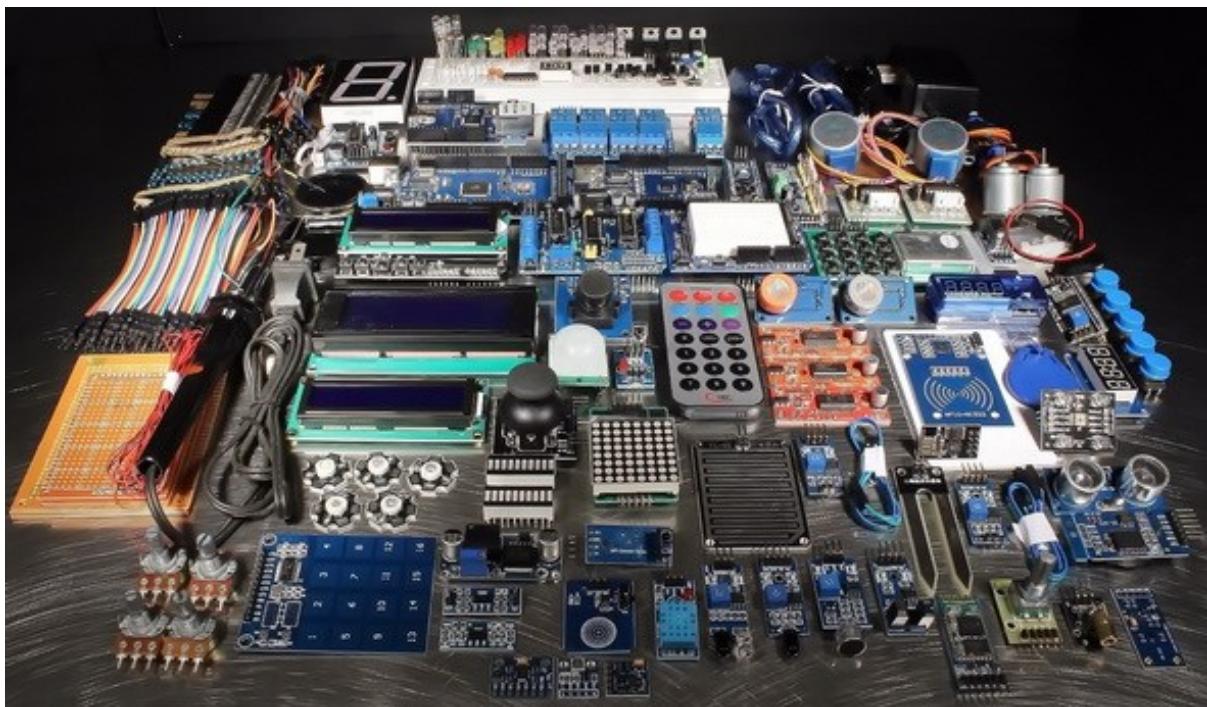
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version 1.3 2102-09-09

Hardware

We will obviously need a MSP430 Launchpad board. For this tutorial, I used MSP-EXP430G2 Launchpad board with MSP430G2553 and MSP430G2452 microcontrollers.



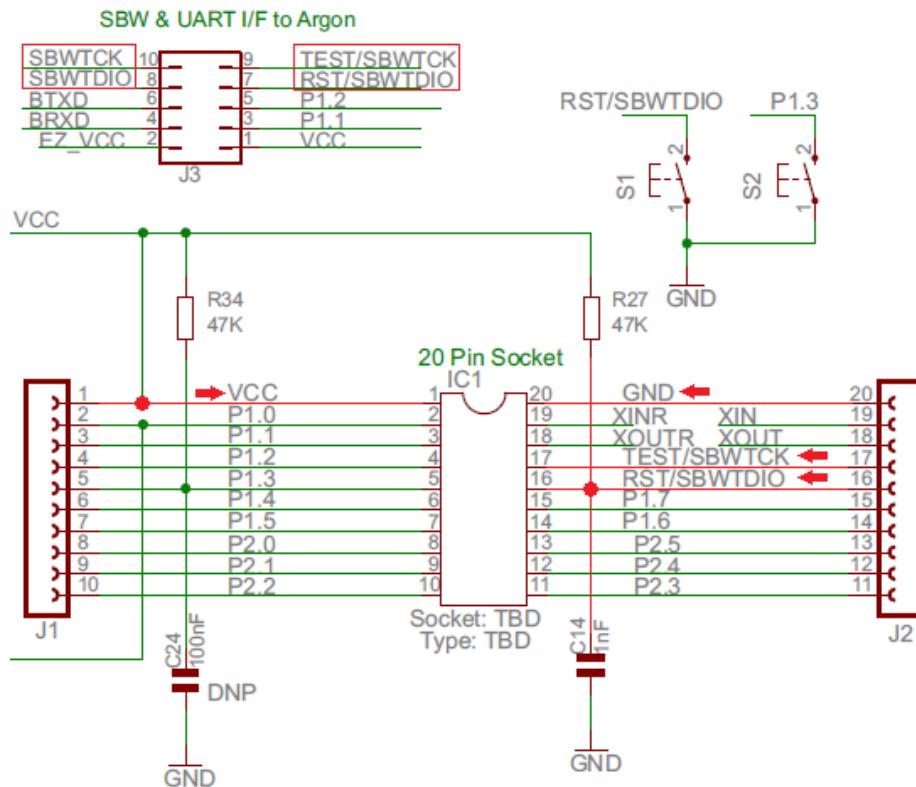
Apart from the Launchpad board, we will need basic tools like a digital multimeter (DMM), wires or jumper cables, a power bank and other stuffs typically available in an Arduino starter kit like the [RIASpire](#) one shown below.



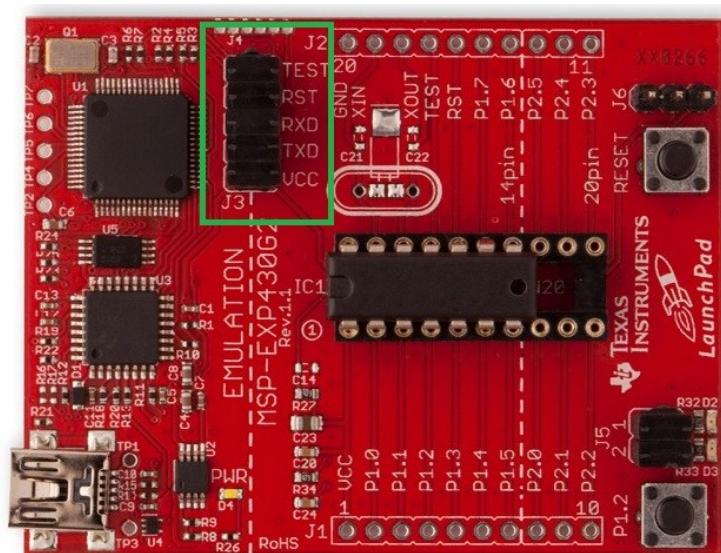
An additional external or off board programmer/debugger is not needed since MSP430 Launchpad boards come with on board **Spy-Bi-Wire (SBW)** programming/debugging interface. This interface

utilizes pins labelled **TEST** and **RST** apart from power pins and so only four wires are needed. Note reset pin should be externally pulled up. Check the diagram below.

Similarly, we don't need to buy/use any external USB-serial converter for serial communication as the boards come with onboard hardware for this communication.



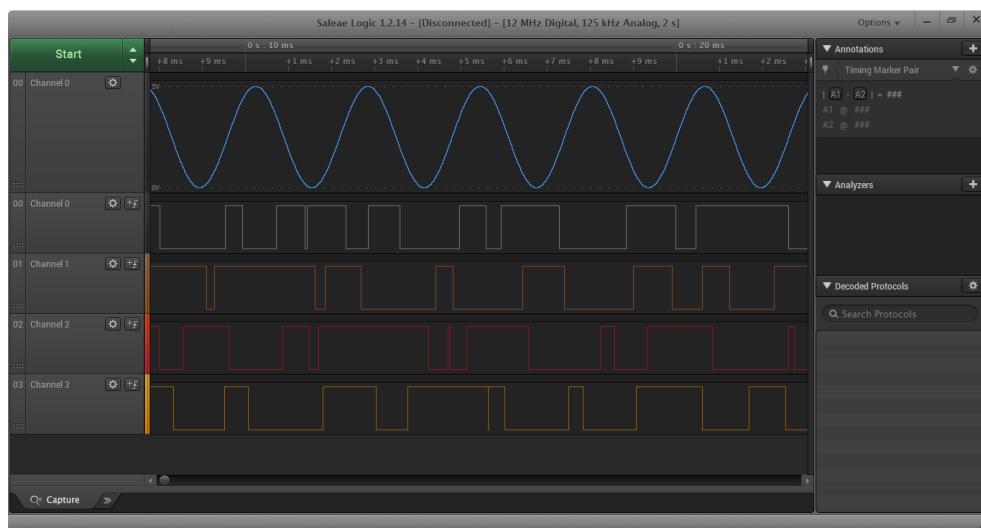
In all Launchpad boards, there are headers with jumpers as shown below to separate onboard programmer from the target. This allows us to use a Launchpad board as standalone programmer. We can also detach it. The top dotted line marks the border between the target and the programmer.



It is still nice to have one external MSP-FET programmer. **FET** stands for Flash Emulation Tool and it supports both JTAG and SWD interfaces. FETs are pretty expensive tools.



Lastly, I strongly recommend having an oscilloscope or a logic analyser for checking signals and timing-related info. In many cases, informations provided by these tools become extremely necessary.



Software

There are numerous ways of learning and using a new microcontroller family effectively. A number of C/C++ compilers are available for coding MSP430 micros. Hobbyists and novice users find Arduino-like solutions easy and quick but from an engineer's perspective such solutions are inexplicably incapable of extracting the sweet fruits of a well-armed microcontroller. Rawer approaches are preferred by professionals but they too seek reduced efforts and quick solutions. The learning curve is also needed to be a smooth one. In this segment, we will checkout some common software solutions for MSP430s.

Firstly, there is the free open-source **Energia** IDE. This is an Arduino-like IDE that enables users to code MSP430s in the Arduino way. It supports many Launchpad boards including those which are based on ARM cores. I have used it a lot and it is fun using it for simple hobby projects. However, I wanted to harness the true power of MSP430s. As with Arduino, you can access MSP430 registers in Energia too but that doesn't make significant differences in terms of coding efficiency and memory consumptions. Energia has the same issues as with Arduino. Arduino framework on top of an AVR makes it much less robust when compared to a crude AVR. The same thing applies for Energia too. Another key limitation of Energia is the fact that not all MSP430 chips are supported by it. Energia is, however, very easy to use, quick and useful for rapid prototyping or testing. The costs are low overall efficiency and larger code size. Just like Arduino, Energia is not well-suited for highly sophisticate professional projects. It is just a rapid prototyping tool that we can use to check a proof-of-concept but not the right tool to build that concept. A smaller hammer is useful for nailing a pin but it is not the perfect tool for breaking a giant boulder.

Energia is available at <http://energia.nu/>.



The screenshot shows the Energia IDE interface with the title bar "Blink | Energia 0101E0017". The menu bar includes File, Edit, Sketch, Tools, and Help. Below the menu is a toolbar with icons for file operations. The main window displays the "Blink" sketch source code. The code is as follows:

```
// most launchpads have a red LED
#define LED RED_LED

// see pins_energia.h for more LED definitions
//#define LED GREEN_LED

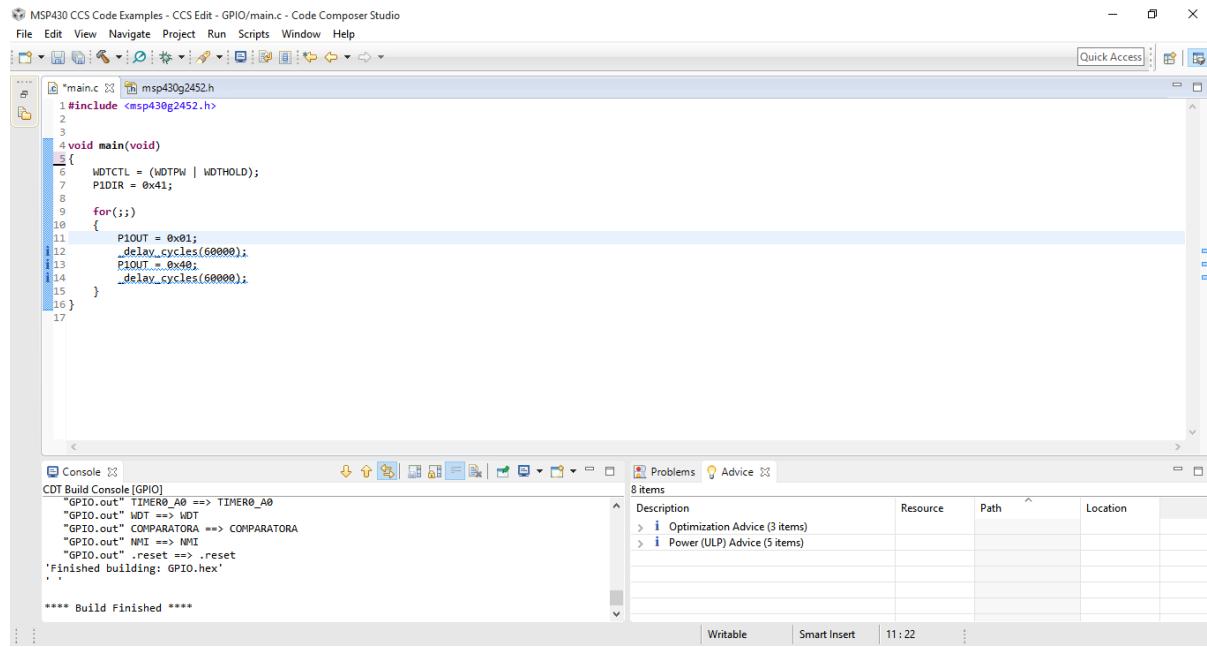
// the setup routine runs once when you press reset:
void setup() {
    // initialize the digital pin as an output.
    pinMode(LED, OUTPUT);
}

// the loop routine runs over and over again forever:
void loop() {
    digitalWrite(LED, HIGH);    // turn the LED on (HIGH is the voltage level)
    delay(1000);               // wait for a second
    digitalWrite(LED, LOW);     // turn the LED off by making the voltage LOW
    delay(1000);               // wait for a second
}
```

The status bar at the bottom indicates "LaunchPad w/ msp430g2231 (1MHz) on COM1".

Please note that Energia is not supported by the Arduino LCC which means it not developed or maintained by the guys from the Arduino team. This doesn't matter much for its users. However, the IDE is not frequently updated like the Arduino IDE.

Next, we have TI's own compiler – the **Code Composer Studio (CCS)**. CCS is a C/C++ compiler based on Eclipse IDE. CCS comes with TI's proprietary compilers that are best in code optimization. Those who have used Eclipse-based IDEs before know the advantages Eclipse framework brings with it. It has an excellent code navigation system, perspective views, refactoring, etc. CCS compiler comes with all of these stuffs and many more like debugger interface and TI App Store. Apart from all these there are some helpful cloud-based tools from TI. This tutorial is based on CCS compiler. It is free for download from TI's website - <http://www.ti.com/tool/ccstudio>. Make sure you have a TI account.

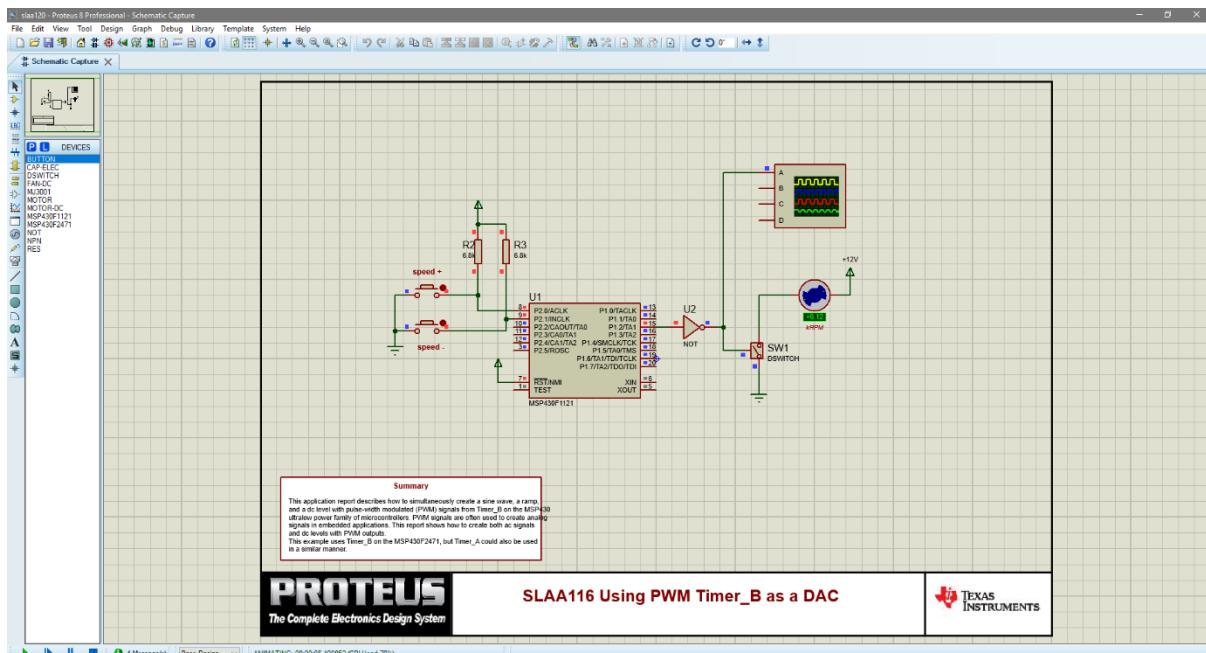


Then there is IAR compiler. I have never used IAR products but I have heard from many that it is very popular and widely used. However, it is expensive too.

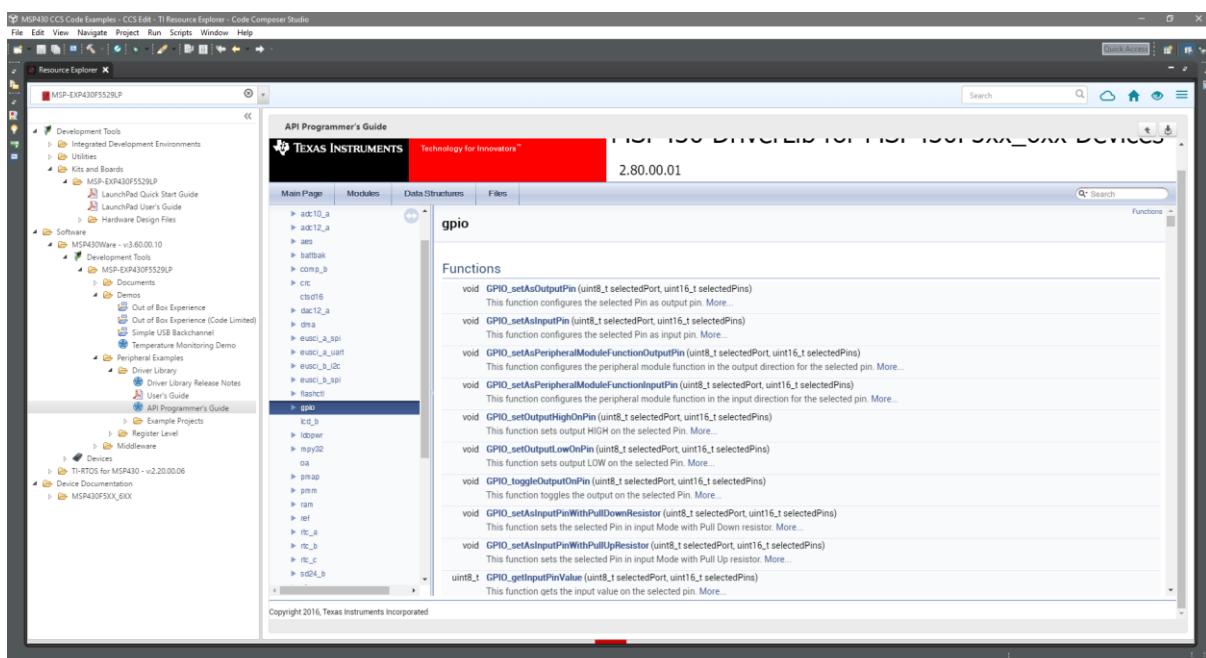
Lastly, like for many other platforms we have the free open-source GCC compiler for MSP430s. MSP430 GCC can be integrated with CCS IDE.

We will see during coding that compilers don't make significant differences in coding style, making codes cross-platform compatible. I also intend to keep things simple and quick. This is why I focus on tools rather than other stuffs. With right set of tools, any issue can be addressed decently and rapidly.

Additionally, some more software tools are needed for supportive purposes. **Proteus VSM** is a good interactive simulator cum PCB design software. Luckily it supports MSP430 micros. However, it is very expensive unless you are using a pirated version of it. Frankly speaking, I have never advocated for simulations because simulations do not address the real-world challenges we encounter in a real-life real-time project. Simulations, for example, cannot simulate real-world environment conditions nor can they emulate situations which result in "hang"-like stuck up conditions. Simulations don't take the effect of noise and electromagnetic disturbances into account. Additionally, sometimes simulations give wrong results. I have spent many wasted hours trying to debug an issue with simulation only to find out that the simulation was incorrect. Still however, simulations are helpful in some special cases. For instance, when designing a LCD menu, simulation is a time and effort saver. Personally, I recommend and use real-world debugging over simulations. This gives me a lot of confidence.



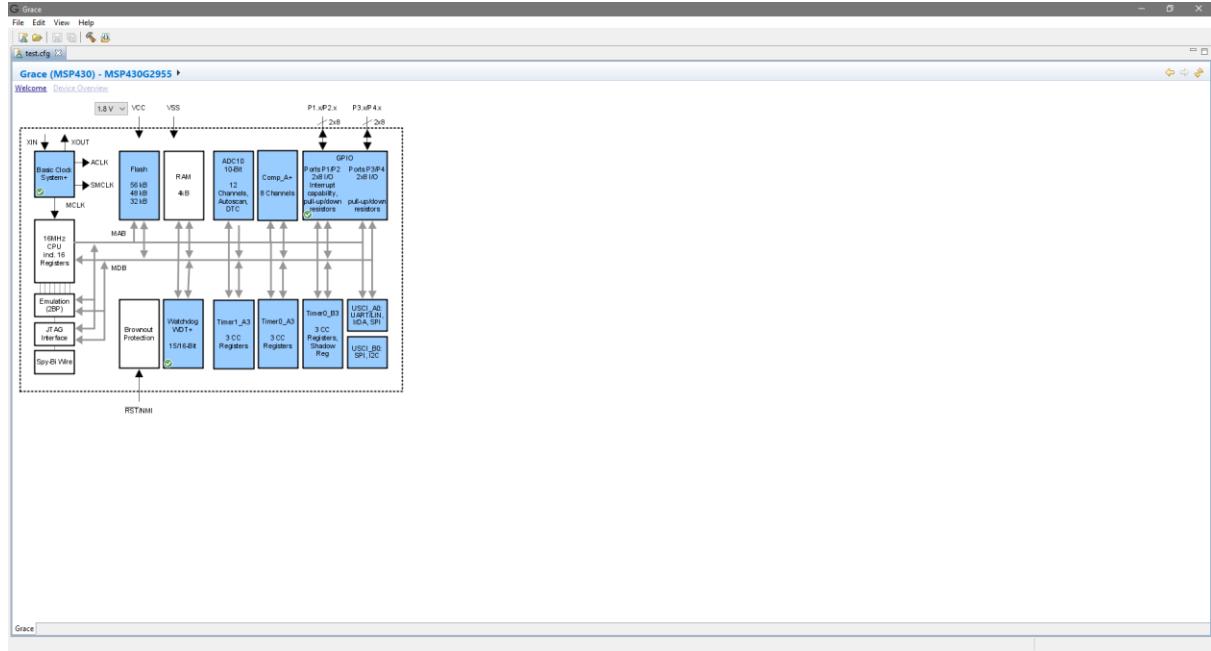
The coolest stuffs for MSP430s are TI's **MSP430Ware driver libraries (driverlib)** and **GRACE**. Driver libraries remove the pain of traditionally coding MSP430s using registers. Driver libraries provide easy-to-use API functions for configuring MSP430 peripherals just like the Standard Peripheral Libraries (SPL) of STM8 micros. However, these libraries are only supported for the newest and resource-rich MSP430 microcontrollers like the MSP430F5529LP. This idea of driver libraries is quickly gaining mass popularity and is becoming standard day-by-day for all modern era micros. MSP430Ware can be downloaded for free from <http://www.ti.com/tool/mspware>.



You can use TI's Resource Explorer to check out what's in **driverlib** and if your target MCU is supported.

GRACE, on the other hand, is intended for relatively less-resourceful micros like the MSP430G2231 that are mostly well-suited for lower level assembly language environments. GRACE is basically a

graphical code generator tool, much like the STM32CubeMX that can be used to generate setup configuration codes for MSP430F2xx, MSP430G2xx and some FR series micros. However, GRACE only generates register values for small MSP430 micros. For large and advanced MSP430 micros driverlib-based codes are generated instead of register-level codes. The rest is just like coding any other microcontroller. Throughout this tutorial, GRACE has been used for all demos.



Grace (MSP430) ▶ Clock - Power User Mode

[Overview](#) [Basic User](#) [Power User](#) [Registers](#)

Configure Clock Source

Internal High Speed Clock Source

Internal DCO⁽²⁾ kHz

Pre-calibrated DCO Values

Disable DCO

Low / High Speed External Clock Source 1

Select Clock Source**

XT1

Int. Load Eff. Capacitance

External Digital Source

System Start-up Delay⁽³⁾ ms

** This setting uses an internal low frequency oscillator. Frequency can vary between 4kHz to 20kHz. See specific device datasheet.

Note 1: By enabling the interrupt handler, Grace generates a fully working interrupt service routine in InterruptVectors.init.c file inside src folder. User could insert code inside the specified area of the ISR and the code is preserved. When a user disables the interrupt handler, the user's inserted code remains at the bottom of the file which is automatically re-inserted if the user re-enables the interrupt handler. User could also manually remove the code when it is no longer needed.

Note 2: Manually configuring the DCO frequency can result in a +/-10% frequency deviation. The Pre-calibrated DCO has a

Select Clock Source

Clock Source

Divider

Main System Clock (MCLK)

Output MCLK

Clock Source

Divider

Sub System Clock (SMCLK)

Output SMCLK

Clock Source from Low / High Speed External Clock Source 1

Divider

Auxiliary Clock (ACLK)

Output ACLK

Interrupt Enables

Oscillator Fault Interrupt Enable

[View All Interrupt Handlers](#)

Grace | BCS+ [X](#)

```

20
21 #include <msp430.h>
22
23 /* USER CODE START (section: BCSplus_init_c_prologue) */
24 /* User defined includes, defines, global variables and functions */
25 /* USER CODE END (section: BCSplus_init_c_prologue) */
26
27 /*
28 * ===== BCSplus_graceInit =====
29 * Initialize MSP430 Basic Clock System
30 */
31 void BCSplus_graceInit(void)
32 {
33     /* USER CODE START (section: BCSplus_graceInit_prologue) */
34     /* User initialization code */
35     /* USER CODE END (section: BCSplus_graceInit_prologue) */
36
37     /*
38     * Basic Clock System Control 2
39     *
40     * SELM_0 -- DCOCLK
41     * DIVM_0 -- Divide by 1
42     * ~SELS -- DCOCLK
43     * DIVS_0 -- Divide by 1
44     * ~DCOR -- DCO uses internal resistor
45     *
46     * Note: ~<BIT> indicates that <BIT> has value zero
47     */
48     BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;
49
50     if (CALBC1_16MHZ != 0xFF) {
51         /* Adjust this accordingly to your VCC rise time */
52         __delay_cycles(100000);
53
54         /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
55         * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
56         */
57         DCOCTL = 0x00;
58         BCSCTL1 = CALBC1_16MHZ;      /* Set DCO to 16MHz */
59         CALDCO_16MHZ;
60     }
61
62     /*
63     * Basic Clock System Control 1
64     *
65     * XT2OFF -- Disable XT2CLK
66     * ~XTS -- Low Frequency
67     * DIVA_0 -- Divide by 1
68     *
69     * Note: ~XTS indicates that XTS has value zero
70     */
71     BCSCTL1 |= XT2OFF | DIVA_0;
72
73     /*
74     * Basic Clock System Control 3
75     *
76     * XT2S_0 -- 0.4 - 1 MHz
77     * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal or r
78     * XCAP_1 -- ~6 pF
79     */
80     BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;
81
82     /* USER CODE START (section: BCSplus_graceInit_epilogue) */
83     /* User code */
84     /* USER CODE END (section: BCSplus_graceInit_epilogue) */
85 }
86

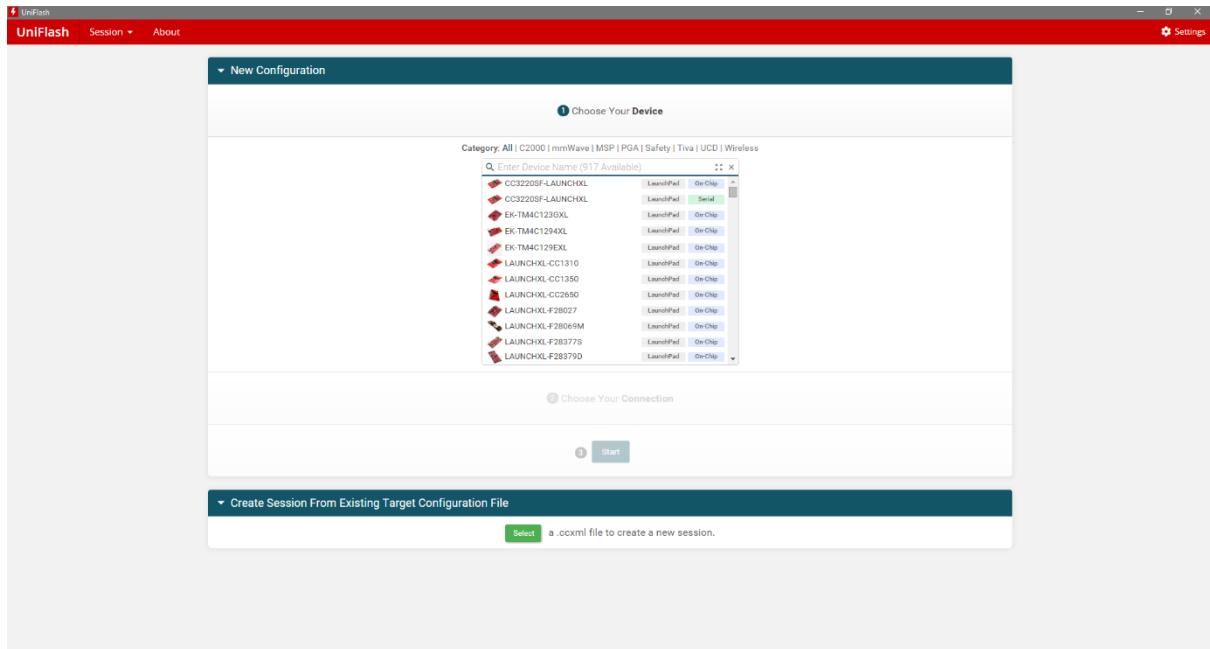
```

As we can see the generated code snippet sets appropriate registers as per our setup in GRACE GUI.

GRACE can be downloaded without any charge from TI's website:

<http://www.ti.com/tool/GRACE?keyMatch=grace%203&tisearch=Search-EN-Products>.

We will also need a separate standalone programmer GUI tool. Why? Because it looks totally stupid to open the heavy CCS software every time to upload a code to a new target after having built the final code for it. For this purpose, we will need ***UniFlash*** programmer GUI.



UniFlash can be downloaded from <http://www.ti.com/tool/uniflash> or can be accessed via TI cloud.

Additionally, I recommend installing and using ***Sublime Text*** (<https://www.sublimetext.com/3>) or ***NotePad++*** (<https://notepad-plus-plus.org/download/v7.4.2.html>) as a code viewer/editor.

```

File Edit Selection Find View Goto Tools Project Preferences Help
main.c *
1 /*
2 * ===== Standard MSP430 includes =====
3 */
4 #include <msp430.h>
5
6 /*
7 * ===== Grace related declaration =====
8 */
9 extern void Grace_init(void);
10
11 /*
12 * ===== main =====
13 */
14 int main( void )
15 {
16     Grace_init(); // Activate Grace-generated configuration
17
18     // >>> Fill-in user code here <<<
19
20     return (0);
21 }
22

```

Make sure you also downloaded Launchpad board drivers from here:
<http://www.ti.com/lit/sw/slac524/slac524.zip>.

Documents, Pages and Forums

The following documents must be acquired:

- **Device Datasheet.**

This write up covers MSP430G2452 and MSP430G2553 microcontrollers and so we will be needing the datasheet of these microcontroller for technical specs and characteristics. These can be found in the following links:

<http://www.ti.com/lit/ds/symlink/msp430g2452.pdf>
<http://www.ti.com/lit/ds/symlink/msp430g2553.pdf>

If you are using some other microcontroller then you must acquire its datasheet first.

- **Reference Manual.**

MSP430G2xx reference manual covers the details of all the hardware available in this family of microcontrollers. Unlike other microcontrollers, datasheet of a MSP430 micro, only says about technical specs and characteristics. Reference manuals say about internal hardware, how to use them and about internal registers. This is the most important document of all.

<http://www.ti.com/lit/ug/slau144j/slau144j.pdf>

- **Launchpad User Manual and Associated Files.**

Visit the following link for Launchpad board user manual and other docs:

<http://www.ti.com/tool/msp-exp430g2>. This document not just introduces the Launchpad board, it also contains schematics, layouts and other stuffs. Of all the stuffs in the user manual, Launchpad board's schematic is the most valuable thing.

- **App Notes.**

Though not mandatory, having a collection of MSP430 application notes is a surplus. These show various ideas and design concepts. Visit TI's website for these docs.

There are some important websites, online communities and forums that are very helpful. Some of the most popular ones are:

<http://www.43oh.com/>

<http://forum.43oh.com/>

<https://e2e.ti.com/support/microcontrollers/msp430/>

http://processors.wiki.ti.com/index.php/Main_Page

<http://www.ti.com/lscds/ti/microcontrollers-16-bit-32-bit/msp/overview.page>

<http://www.ti.com/lscds/ti/tools-software/launchpads/overview/overview.page>

Starting a New CCS Project

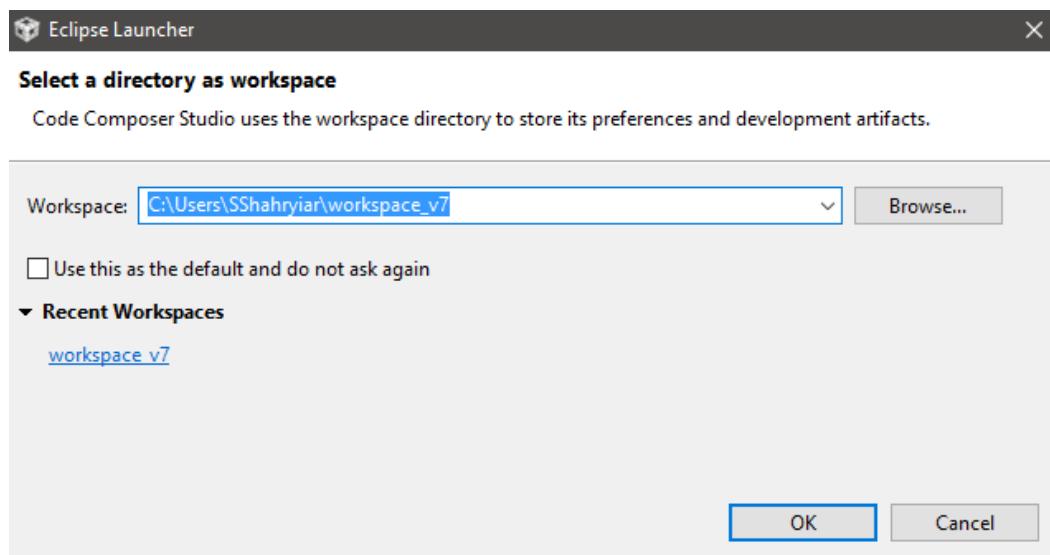
Beginning a new CCS project is not too complicated. Provided that CCS is installed in your PC, simply run it.



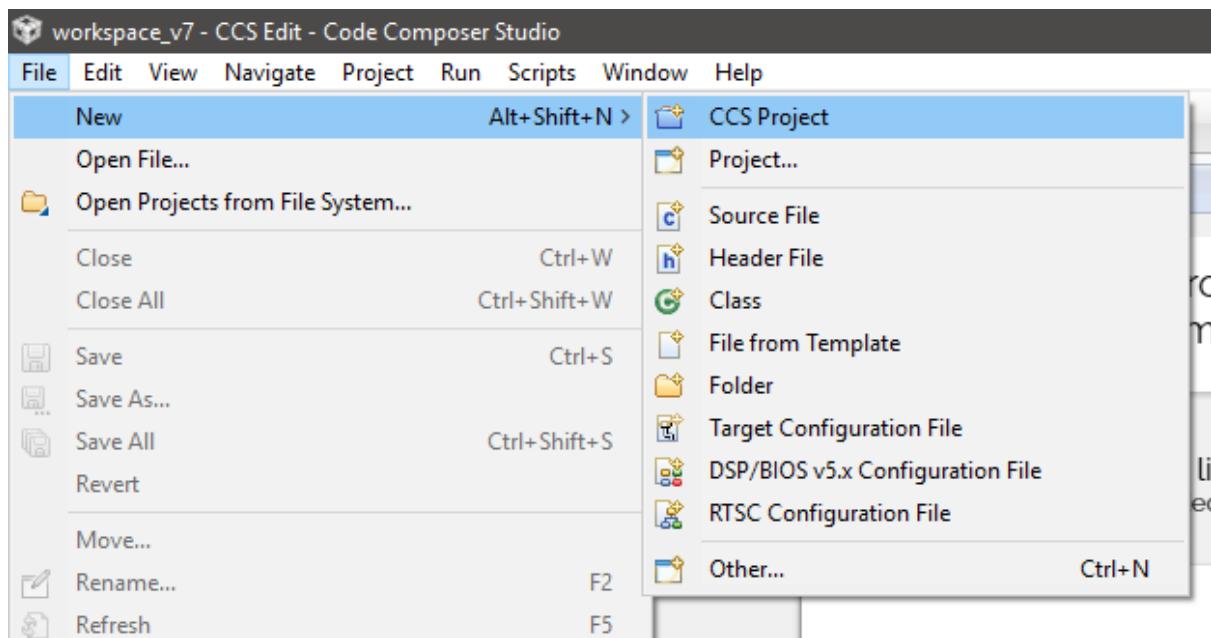
In just a few seconds, CCS's logo splashes.



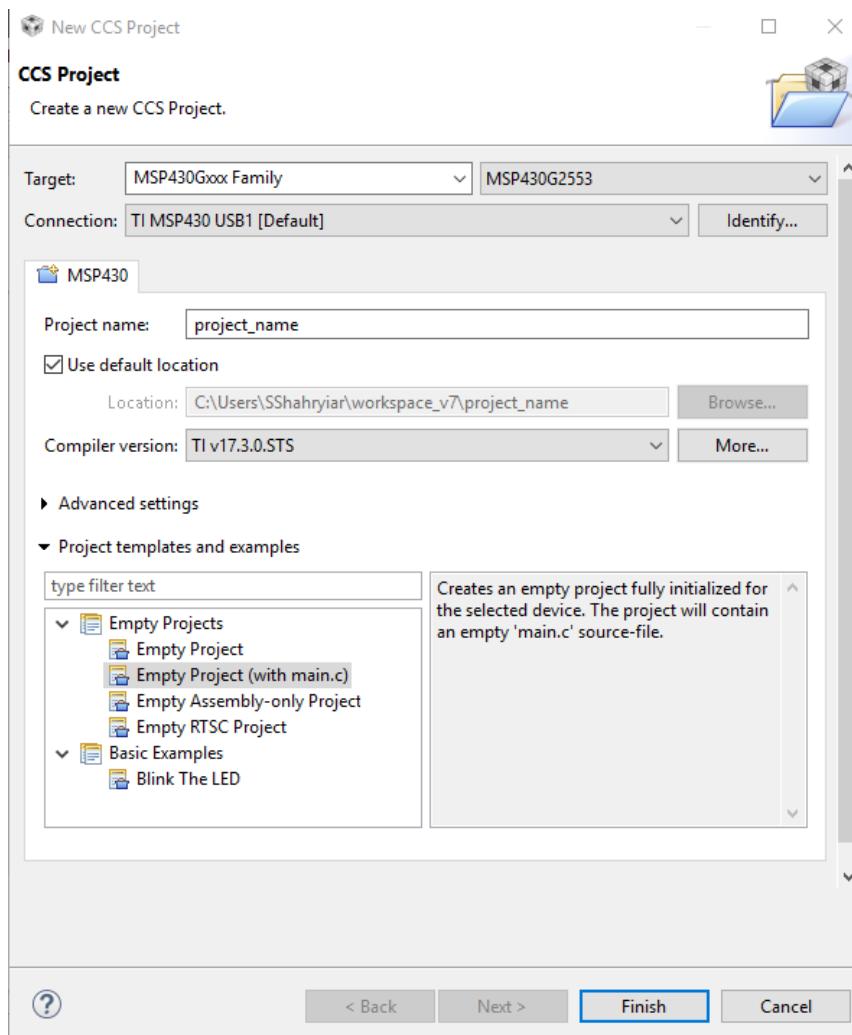
You'll be asked for workspace location. Either select an existing workspace if you have one or create a new one.



Next click **File >> New >> CCS Project.**

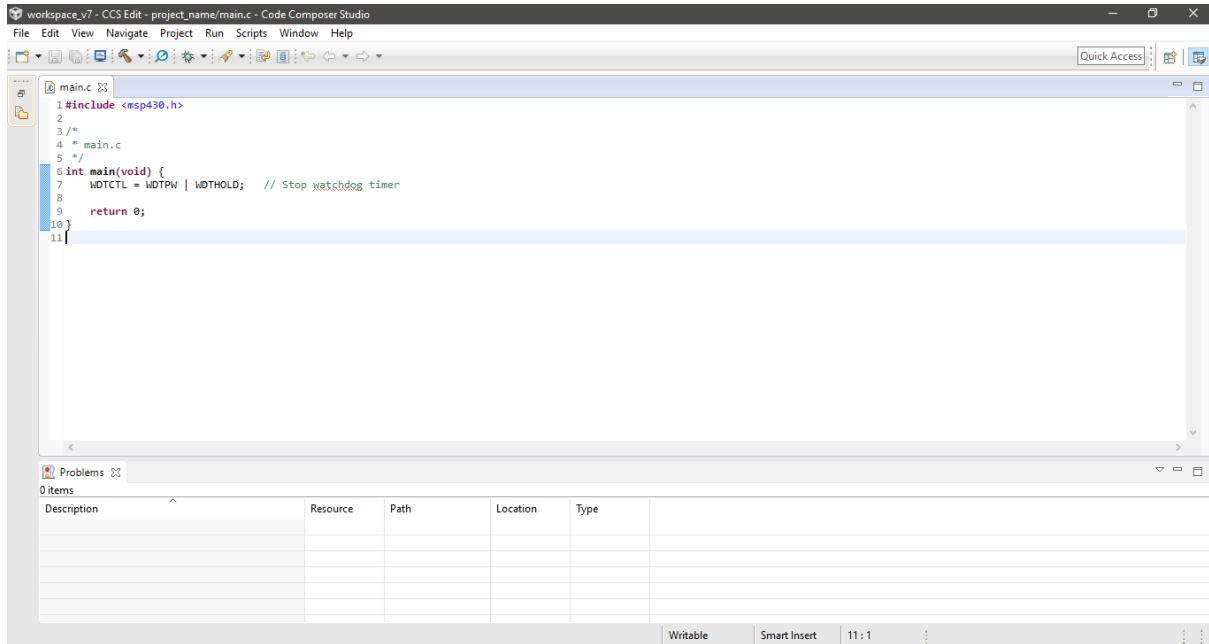


The following window will show up then:



Here we just need to setup target MCU, name of the project, compiler version and project type. Keep other options unchanged unless you are sure of your actions.

The following window appears after hitting the finish and we are good to go for coding. It is just that simple.



The screenshot shows the CCS IDE interface. The title bar reads "workspace_v7 - CCS Edit - project_name/main.c - Code Composer Studio". The menu bar includes File, Edit, View, Navigate, Project, Run, Scripts, Window, and Help. The toolbar has various icons for file operations like Open, Save, and Build. The main workspace contains a code editor with the file "main.c" open. The code is as follows:

```
1 #include <msp430.h>
2
3 /*
4 * main.c
5 */
6 int main(void) {
7     WDTCTL = WDTPW | WDTHOLD; // Stop watchdog timer
8
9     return 0;
10}
11
```

Below the editor is a "Problems" view which is currently empty, showing "0 items". At the bottom of the interface are several status indicators: "Writable", "Smart Insert", "11:1", and three vertical dots.

One advice I would like to give here, never delete any workspace file or folder unless you created it. It is possible to rename and remove projects from CCS IDE.

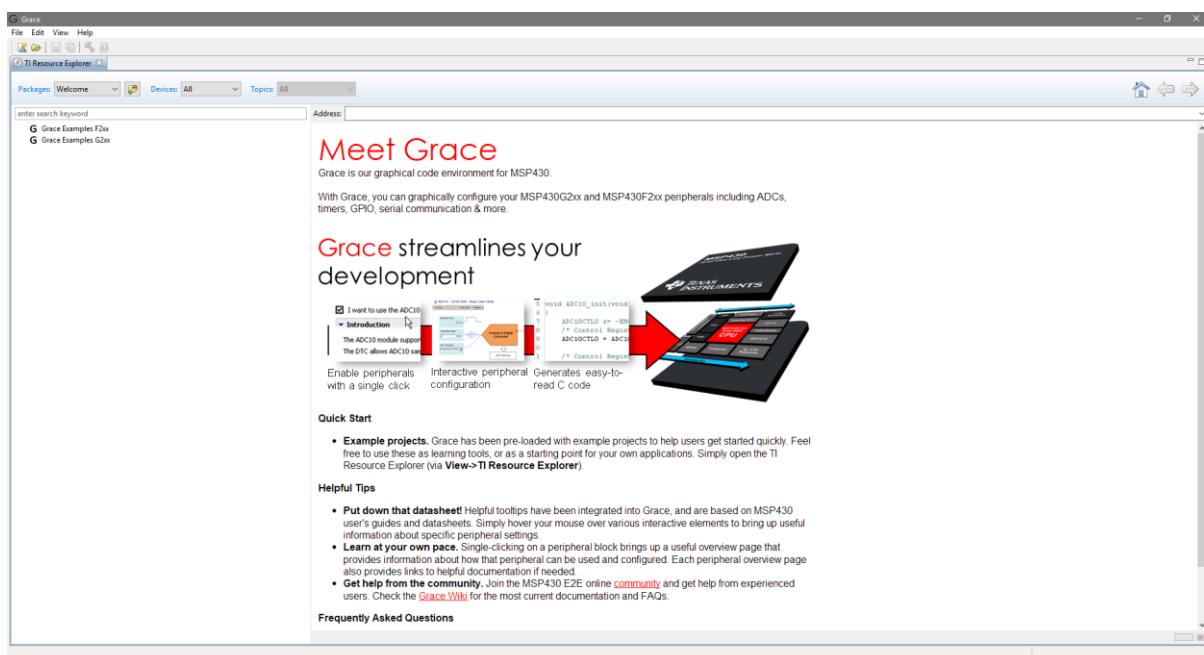
GRACE

As stated earlier, GRACE is a graphical configuration tool. It reduces the effort of thoroughly reading datasheets and reference manuals. I highly recommend using it no matter if you are novice or expert.

First run GRACE.



Wait for it to launch.

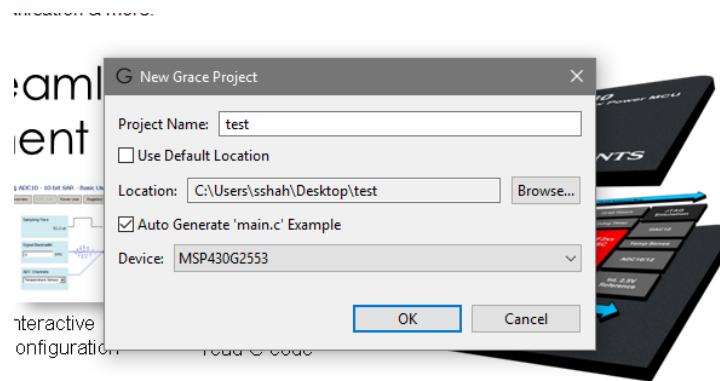


TI's Resource Explorer kicks in on first start up. It may not do so every time though.

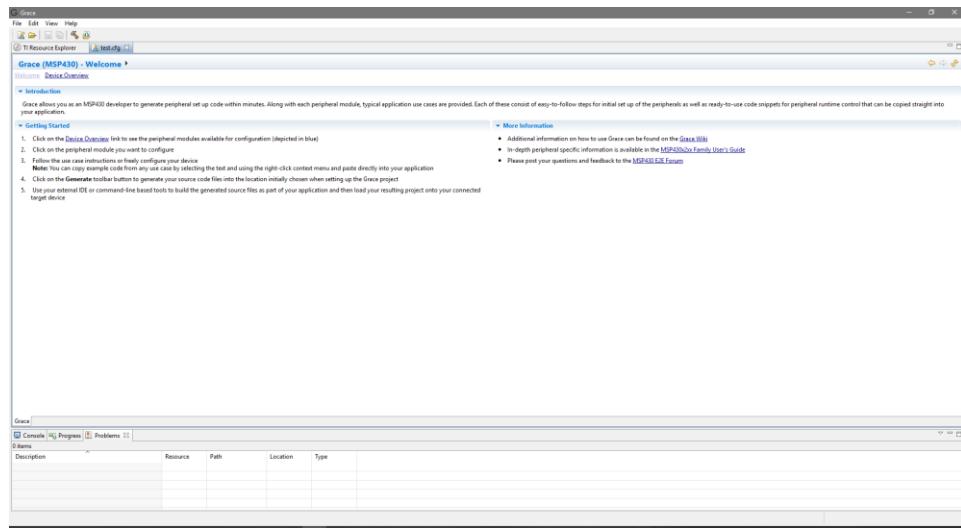
Click **File >> New** to begin a new GRACE project.



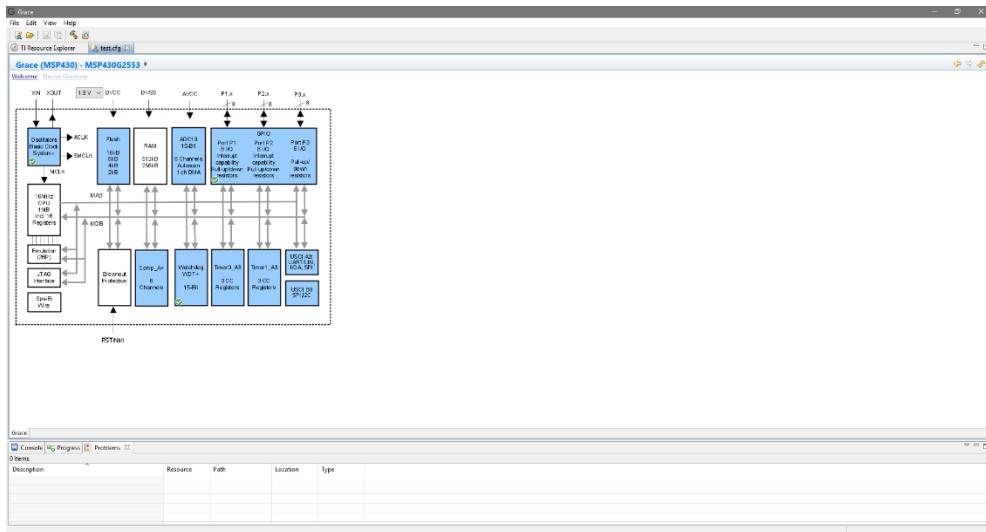
You'll be prompted for project location, MCU part number and project name as shown below:



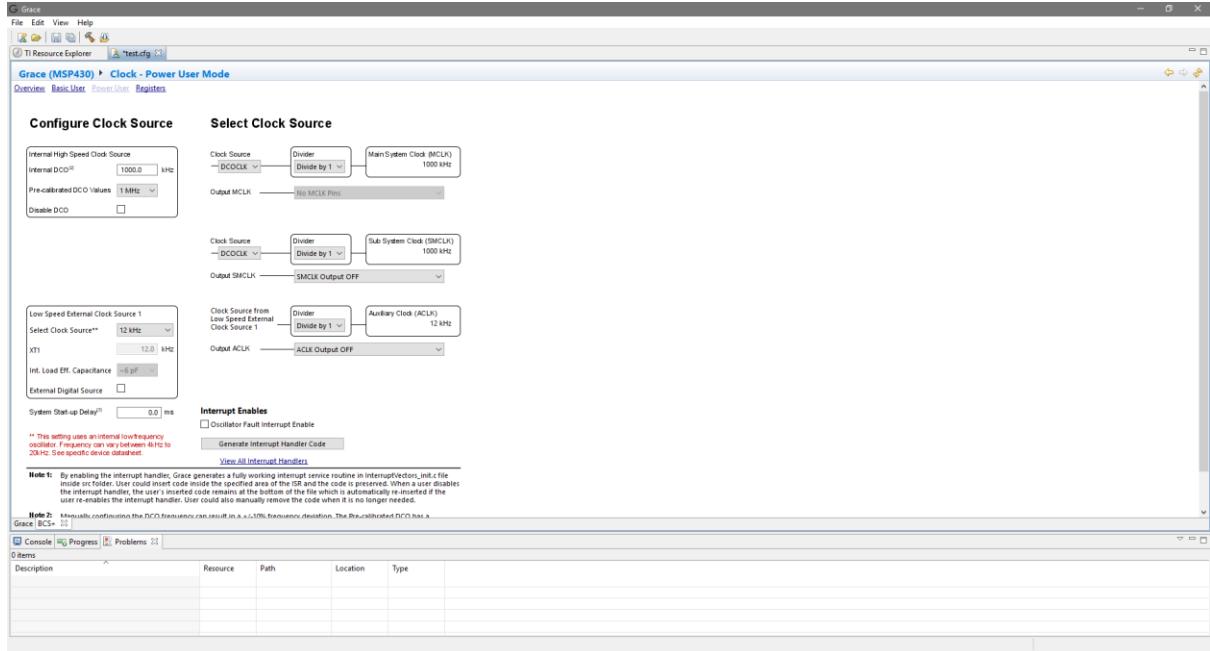
Once all the parameter fields are filled, we are ready to configure our target MCU. A welcome screen shows up next.



From the welcome screen, we have to click on **Device Overview** and get an insight of the device's peripherals as peripheral blocks.



We can now click desired hardware peripheral block (blue blocks) to check what features and code examples it offers and set it up as required. There are two types of setups for all modules - **Basic** and **Power** users. **Basic User** setup is for simple setup when you don't know everything of a peripheral in details and don't want to mess things up. **Power User** setup is for expert users with more advanced options. Shown below are the Power User options for setting up the clock system:



After setting up everything, just hit the hammer or **Build** button and the configuration codes are generated in the preset folder. It may take some time to complete the process. Next, we just need to open the generated files and copy them in our main CCS code.

How to create a new CCS project and use Grace is well documented in this video: <https://www.youtube.com/watch?v=QCYMBsKwRfY>.

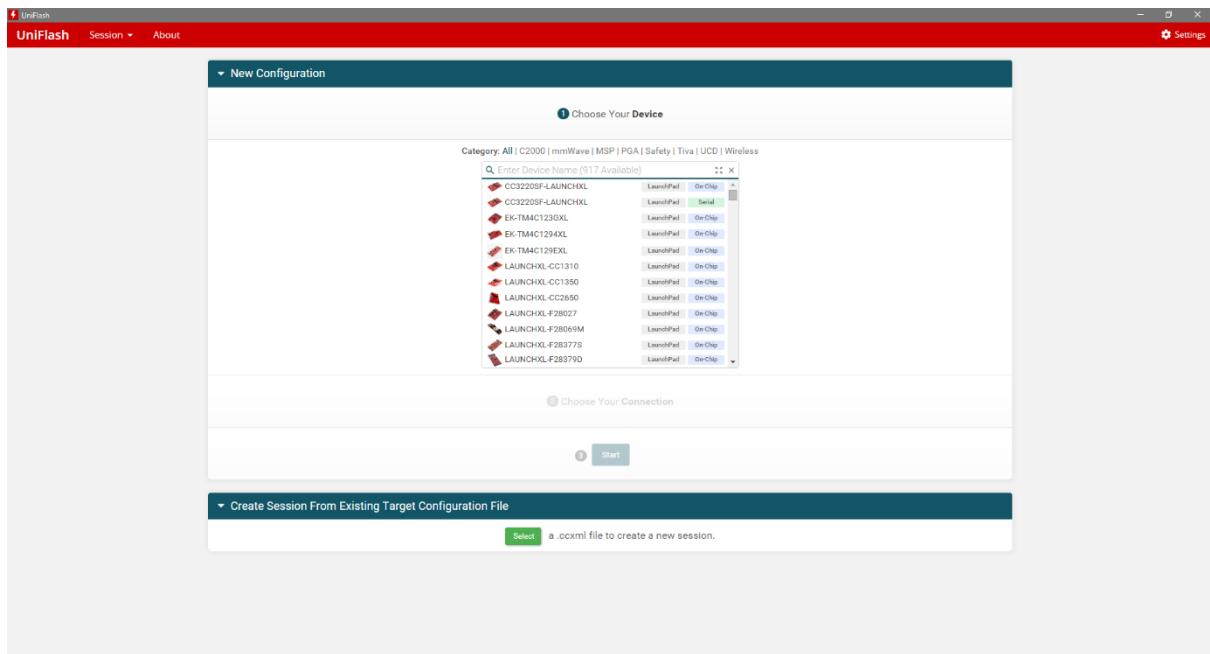
UniFlash

Most of the times during development, a separate standalone programmer software is not a compulsory necessity as CCS IDE provides an inbuilt programmer/debugger interface. However, at times long after final application development, it becomes completely unnecessary to reopen CCS just to load a firmware to a new micro. UniFlash comes in aid at that time.

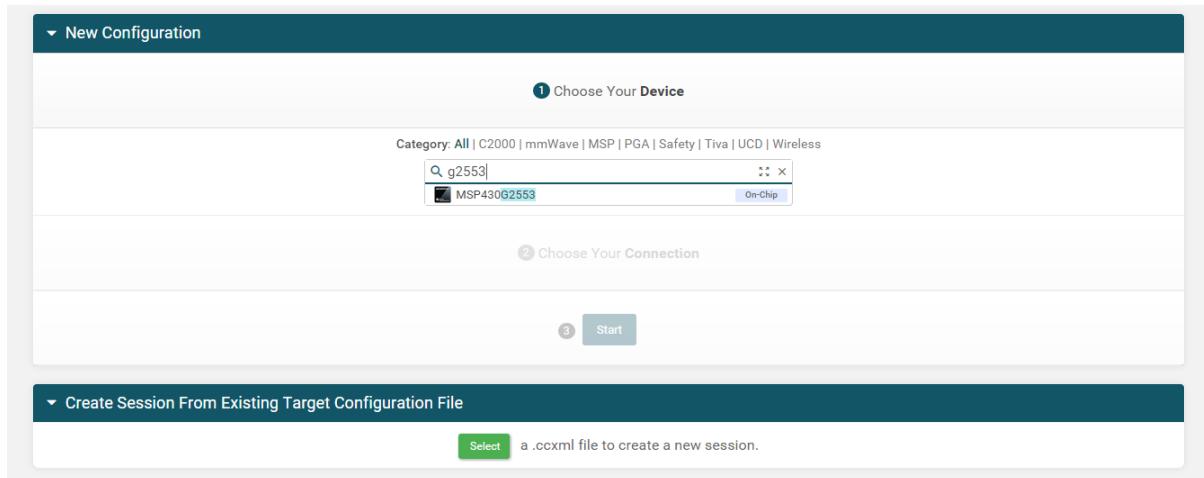
Run Uniflash by clicking its icon.



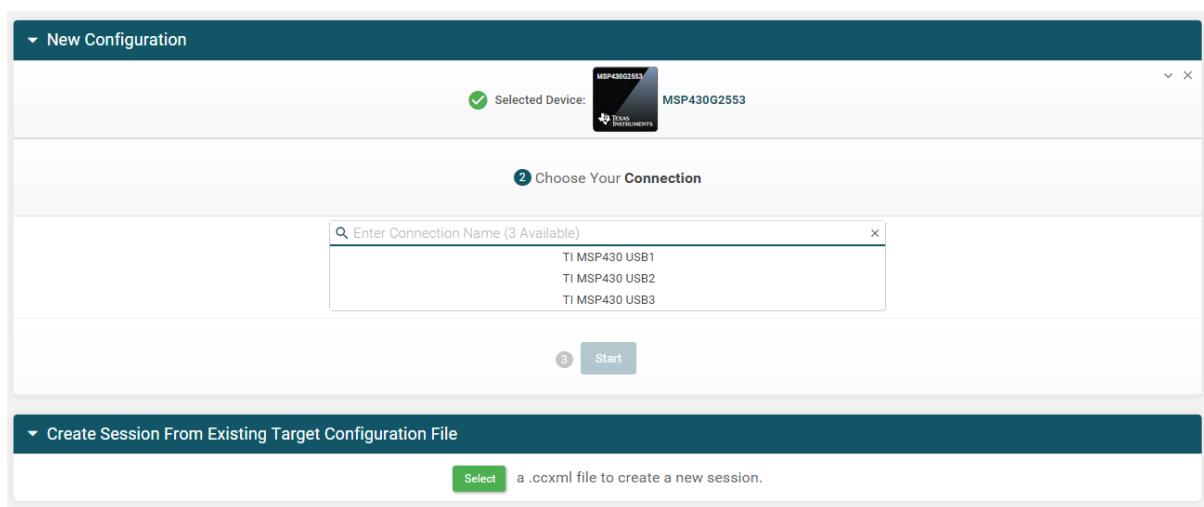
The following window appears:



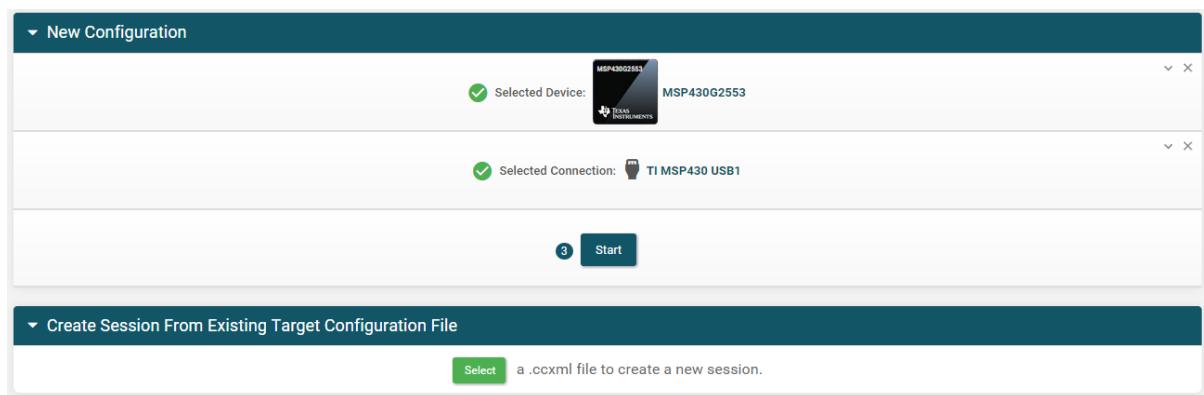
From here we need to select either target board or target microcontroller. No need to type the whole part number of a micro, just few digits/letters are enough to find the correct micro:



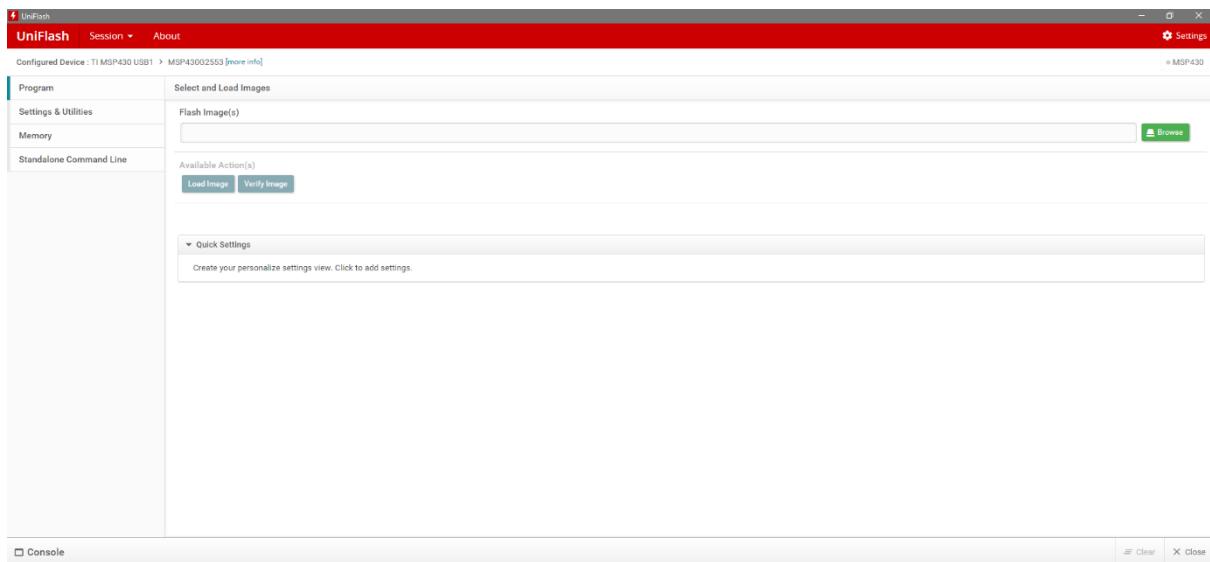
Similarly, we need to setup connection to target too. **USB1** - the first option is what we need to select.



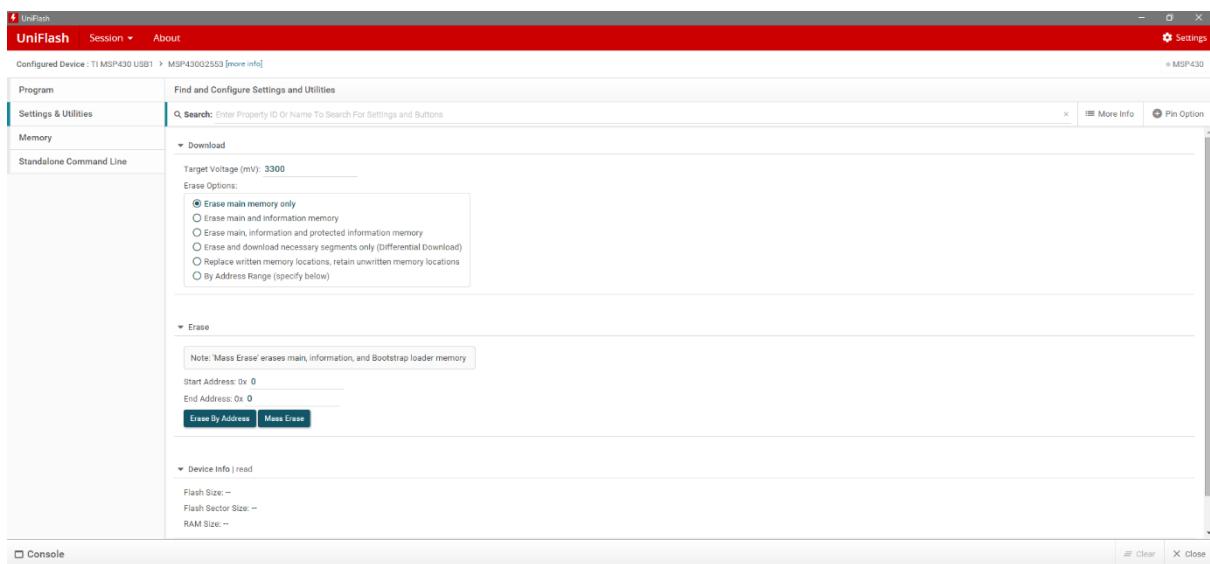
Now we are ready to begin firmware upload. Click the **Start** button.



Browse the firmware you wish to upload.



You can optionally set some more parameters for the target as shown:



To flash new firmware, just hit the **Load Image** button.

Watch this video for details: <https://www.youtube.com/watch?v=4uwQSSX-HrM>.

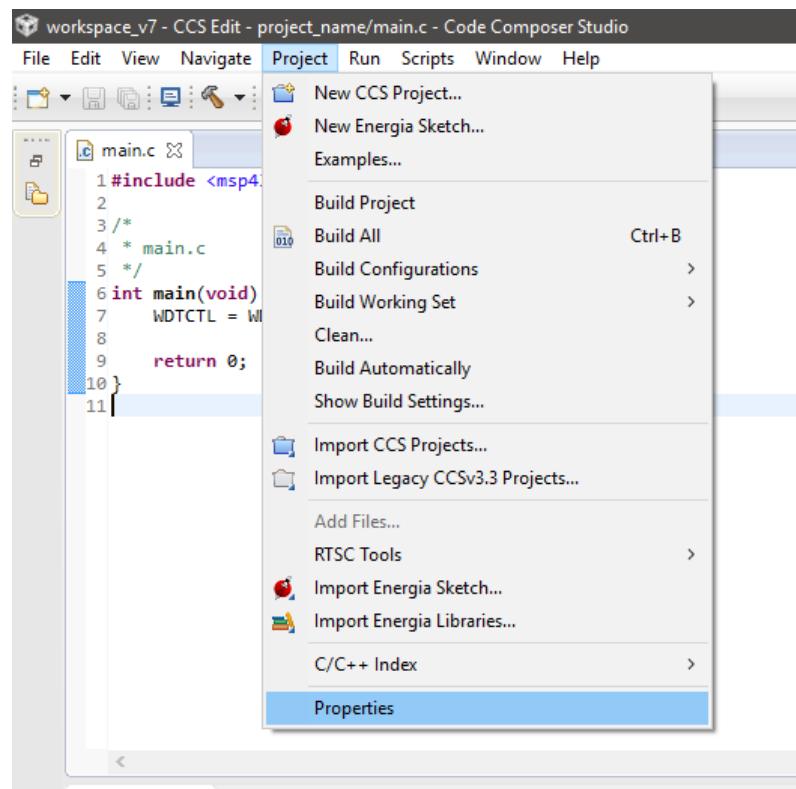
Strategies and Tactics

Before we begin exploring MSP430 micros, I would like to discuss certain things though they may look like advanced stuffs for the moment.

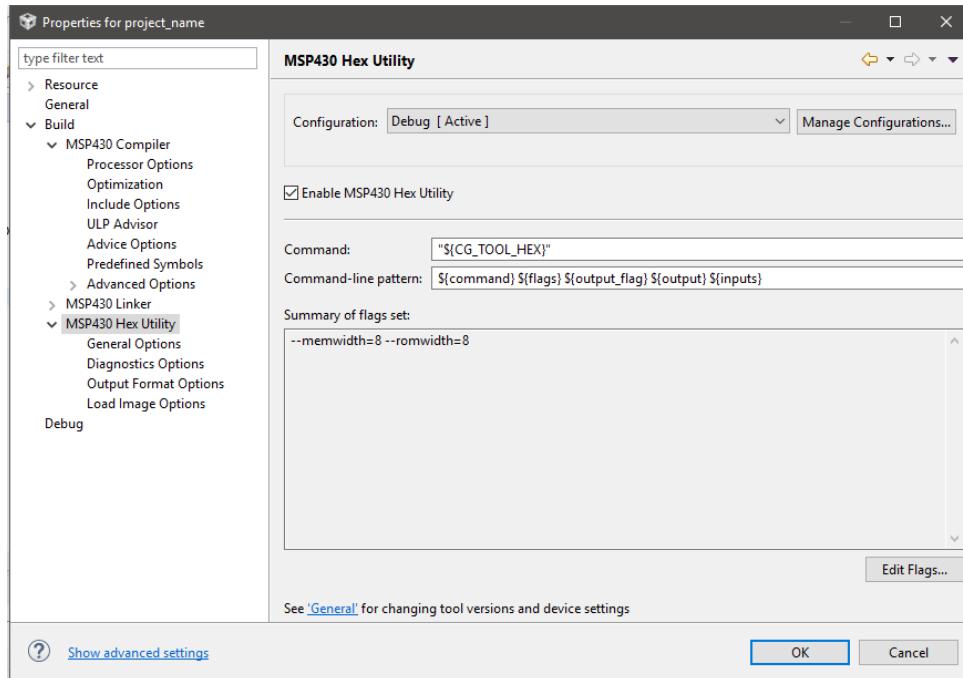
Generating HEX Output Files

By default, CCS doesn't generate any hex formatted output file. Everyone working in the embedded system sector is familiar with it. Hex outputs are useful for Proteus VSM simulations and loading code to a new MSP430 micro using an external programmer like UniFlash. Thus, it is essential if not imperative to unlock hex utility.

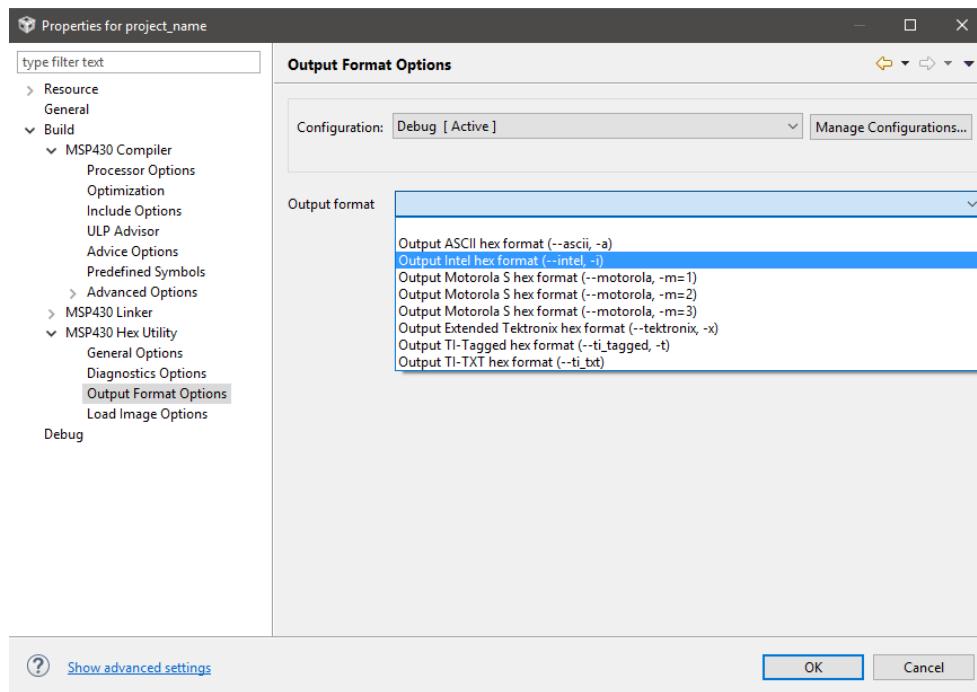
First go to **Project > Properties**.



Navigate to find **MSP430 Hex Utility** and then enable it as shown below.



Finally select hex output format as shown:



Select **Intel** hex format as it is the one widely used.

Having set as shown, from now on, whenever you build your current project, you'll get an output **.hex** file in the project's debug/release folder depending on your project type selection.

Building New Libraries

Building new libraries is simple. All we need to do is to follow a few set of rules:

- For each module, there should be a separate header file and source file.
- Header file should contain definitions, variables, constants and function prototypes only.
- Header files should begin with the inclusion of MSP430 header file.
- Source files should include their respective header files and addition header files (if any).
- Source files should contain actual function codes only.
- Be aware of reserved keywords and constants.
- Global variables with same names should never be declared more than once.
- Empty functions and functions without prototypes must be avoided.
- Functions should have small and meaningful names.
- Be careful about case-sensitivity, function type assignment and argument type of functions.
- Hierarchical order of library inclusion must be followed.

delay.h

```
#include <msp430.h>

#define F_CPU 8

void delay_us(unsigned int value);
void delay_ms(unsigned int value);
```

delay.c

```
#include "delay.h"

void delay_us(unsigned int value)
{
    register unsigned int loops = ((F_CPU * value) >> 2);

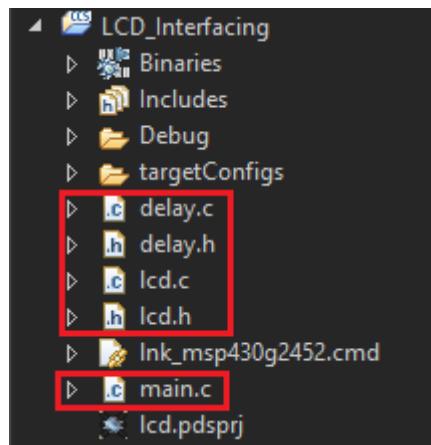
    while(loops)
    {
        _delay_cycles(1);
        loops--;
    };
}

void delay_ms(unsigned int value)
{
    while(value)
    {
        delay_us(1000);
        value--;
    };
}
```

Adding Custom Library Files

Adding own developed libraries to a project is key requirement for any software developer. This is because no compiler includes libraries for all hardware. We must realize a compiler as a tool only. The rest is how we use it and what we do with it. As for example, CCS comes with **_delay_cycles** instead of more commonly preferred **delay_ms** or **delay_us** functions. We will, thus, need software delay library. We need to code it and include it in our projects.

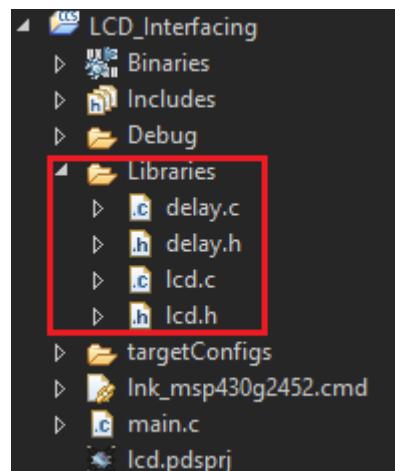
Custom libraries can be included in two ways. The easiest way is to add the include and source files in your projects root location, i.e. its folder. No additional job is needed because the root contains the **main.c** source file and its location is automatically included when you start a project.



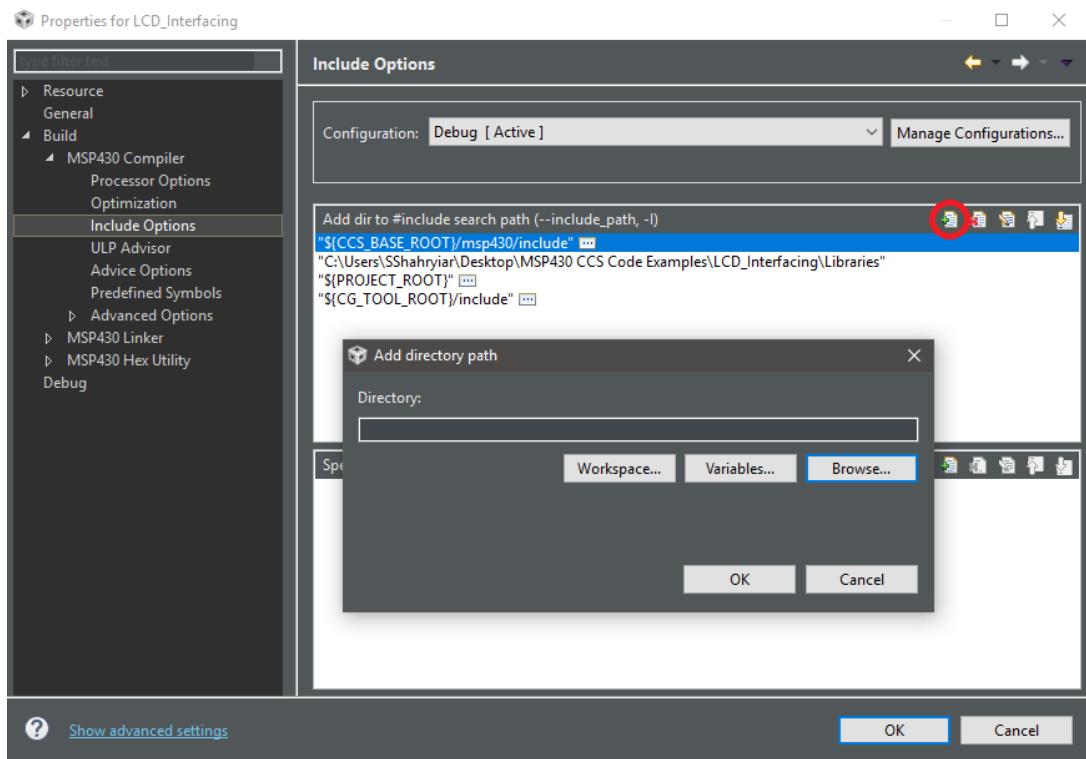
However, the aforementioned method becomes clumsy and unprofessional when there are too many custom library files in a large project and if you care for some neatness. The other method needs some additional tasks to be done before we can use our library files.

First make a folder in your project directory and give it a name. For example, I named this folder **Libraries** in my examples.

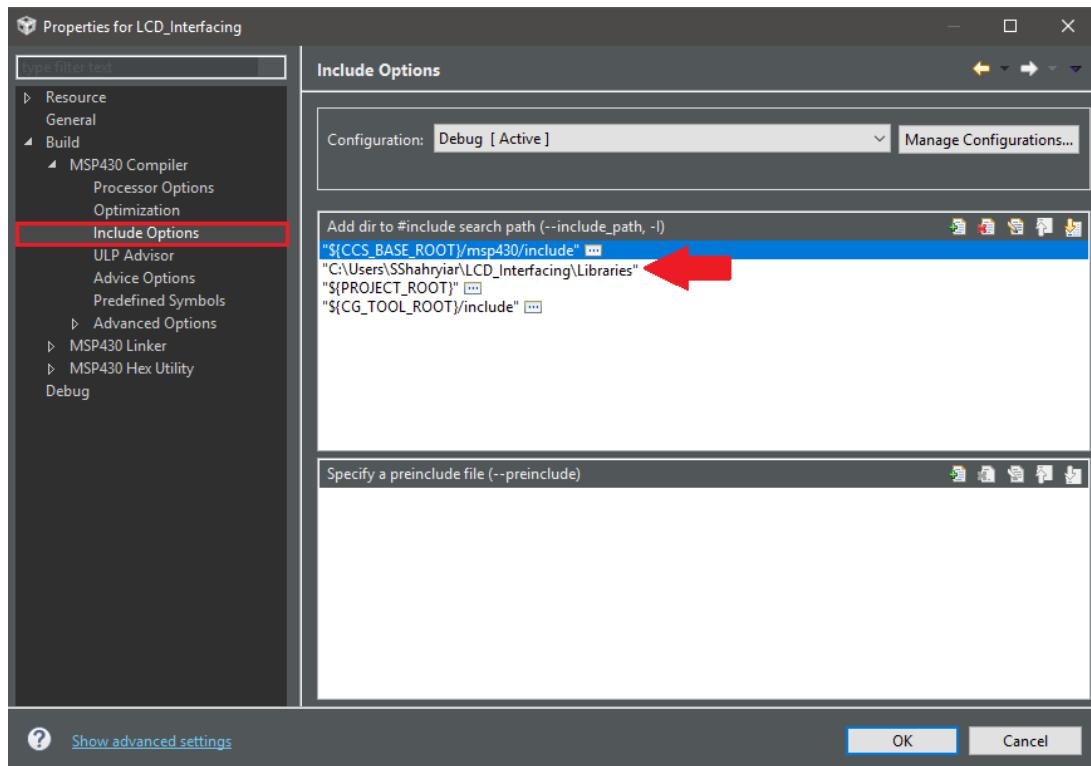
Next add the desired library source and header files in this folder.



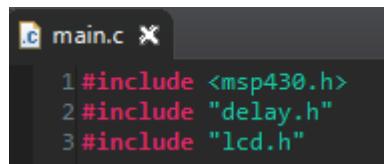
At this stage, we still cannot use these libraries because the compiler does not know their path(s) and so we need to inform the compiler about their location. We need to go to **Project >> Properties** first and then navigate to **Include Options** menu under **Build >> MSP430 Compiler** menu as shown:



Right after clicking the circled icon as shown above, we will be asked for folder location. It is just a simple browsing to the library folder location.



To use the libraries we added, we now just need to add some **#include** statements in our **main.c** file.



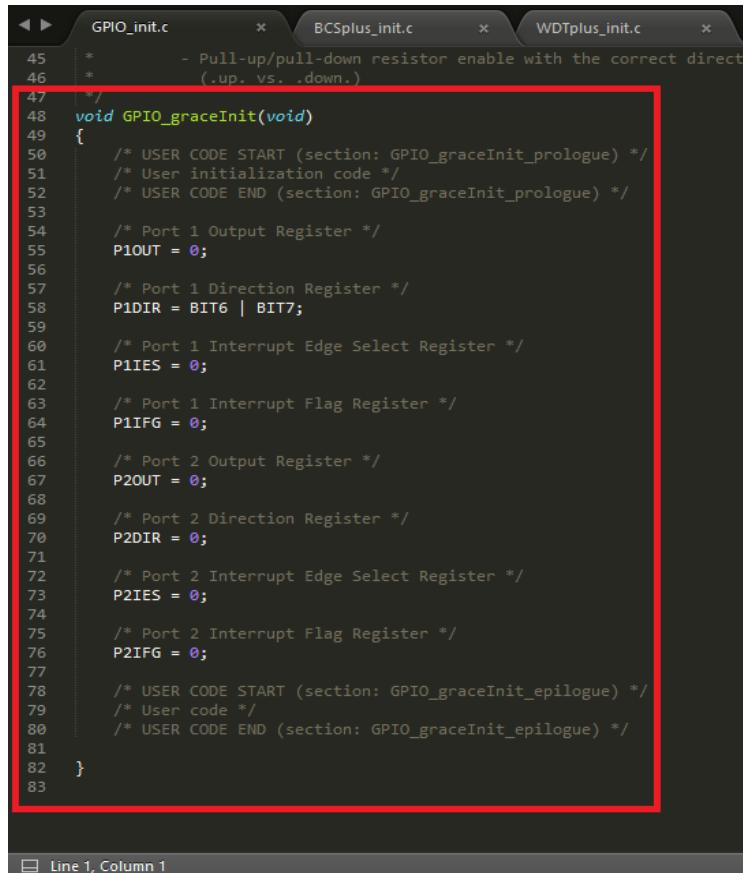
```
1 #include <msp430.h>
2 #include "delay.h"
3 #include "lcd.h"
```

Be careful about the hierachial order of library files because they may be interdependent. For example, as shown above, the LCD library has dependency on software delay library and so the delay library is added or called before the LCD library.

Using GRACE Simply but Effectively

GRACE should be used for quick setups. Who would like to waste time fixing register values when we have such a useful tool at our side. We will need a code viewer/editor like Sublime Text for viewing codes generated by GRACE. I like Sublime Text for its way of highlighting keywords and important stuffs with different colours. This helps in building quick situational awareness. A dark IDE is also good for night-time coding and less stressful for eyes.

Previously I showed how to use GRACE to generate configuration codes. GRACE generates individual source files for each hardware used. In this way, it doesn't create too much mess. We will open each of these files with Sublime Text and copy only the needed **init** functions in our main source code. GRACE also generates other stuffs but that are like mere junks to us and so we will just ignore them.



```
45 * - Pull-up/pull-down resistor enable with the correct direct
46 * (.up. vs. .down.)
47 */
48 void GPIO_graceInit(void)
49 {
50     /* USER CODE START (section: GPIO_graceInit_prologue) */
51     /* User initialization code */
52     /* USER CODE END (section: GPIO_graceInit_prologue) */

53     /* Port 1 Output Register */
54     P1OUT = 0;

55     /* Port 1 Direction Register */
56     P1DIR = BIT6 | BIT7;

57     /* Port 1 Interrupt Edge Select Register */
58     P1IES = 0;

59     /* Port 1 Interrupt Flag Register */
60     P1IFG = 0;

61     /* Port 2 Output Register */
62     P2OUT = 0;

63     /* Port 2 Direction Register */
64     P2DIR = 0;

65     /* Port 2 Interrupt Edge Select Register */
66     P2IES = 0;

67     /* Port 2 Interrupt Flag Register */
68     P2IFG = 0;

69     /* USER CODE START (section: GPIO_graceInit_epilogue) */
70     /* User code */
71     /* USER CODE END (section: GPIO_graceInit_epilogue) */
72 }
```

My code examples will give you an idea of what to copy. Keep in mind to stop the watchdog timer in the beginning of your code or it may reset your micro before entering actual application.

Optional Customizations

Explore the IDE **Preferences** for customizing CCS IDE according to your wishes. For instance, unlike the default white theme, I like a full black IDE interface like the one in Sublime Text. This is really effective when you work at night and in low light conditions. Just like Sublime Text key words are highlighted and it is easy to navigate in such an environment.

In a busy world, we often forget to update software in regular schedules and therefore miss important changes and bug fixes. Automatic updates come in aid in such case. I configured my CCS in such a way that it auto updates and notifies me about new software versions. I also added some tools from CCS/TI App Store like the GCC compiler.

Other customizations include **MSP430Ware** and **EnergyTrace Technology** debugger. **EnergyTrace Technology** allows us to compute energy consumptions. It helps in estimating battery requirements (if any). I recommend readers to explore CCS IDE properties for more custom settings.

Advanced Concepts

Most of the times during code compilation you'll notice that the compiler not only compiled your code but has also given you some optional advices. These advices aid in code optimizations and hint ways to enhance overall performance. For instance, it is better to use **switch-case** statements instead of **if-else** statements when dealing with fixed-discrete conditions. Try to follow the advices whenever possible. Same goes for compiler warnings. You must address the warnings for flawless coding.

In the internet, we can find lot of documents on C code optimization and good C language practices. Here is one such document from Atmel: <http://www.atmel.com/images/doc8453.pdf>. Although it was written for Atmel AVR microcontrollers but the document applies for all microcontrollers and C compilers. Similarly, Microchip has documents named **Tips 'n Tricks**. Visit and search Microchip's site for these documents. These tricks and tips help in designs significantly. Try to follow these to achieve best utilization of your micro's assets. TI's application notes are also equally helpful literatures. Personally, I recommend studying the app notes, and other documents of other micro families too. This will help advance in developing new concepts, strategies and techniques.

Additionally, I would like to point out some issues and techniques when using CCS. Here are followings:

- Be careful about case sensitivity. Also, be careful about compiler's reserved keywords and constants.
- Although not mandatory, it is, however, a good practice not to keep empty argument field in any function. Argumentless functions should have **void** argument instead of empty spaces.

- Flags are important event markers and so wherever they are present and needed you must use and check them unless automatically cleared. For instance, it is necessary to clear timer flags upon exiting timer interrupts.
- Try to avoid polling methods. Try to use interrupt-based ones but make sure that there is no interrupt-within-interrupt case or otherwise your code may behave erratically. Best is to attach interrupts for important tasks like timing-related jobs, ADC conversions and communications. It is up to your design requirements and choices.
- Where fast processing is required, try to mix assembly with your C-code if you can or temporarily speed up your micro by increasing its oscillator speed or switching to a faster clock source. Checkout the assembly examples from **TI's Resource Explorer** and **MSP430Ware**. Also try to study and learn about advanced C concepts like pointer, structures, functions, etc.
- Avoid empty loops and blank conditional statements.
- When you hover mouse cursor over a function, a small window appears. This window shows the internal coding of that function and relieve you from opening a new tab for it.
- **CTRL + Space** or code assist is a great helper. Likewise, CCS has some auto complete features.
- If you are using multiple computers during your project's development stage, make sure that your custom library locations and workspace paths are properly added.
- Try to follow compiler advices and optimizations. Study the MSP430 header files if you can.
- You can straight include the header file of your target MCU like as shown below if code cross compatibility among different MCUs of the same group like MSP430x2xx is not needed:

```
#include <msp430g2553.h>
```

instead of:

```
#include <msp430.h>
```

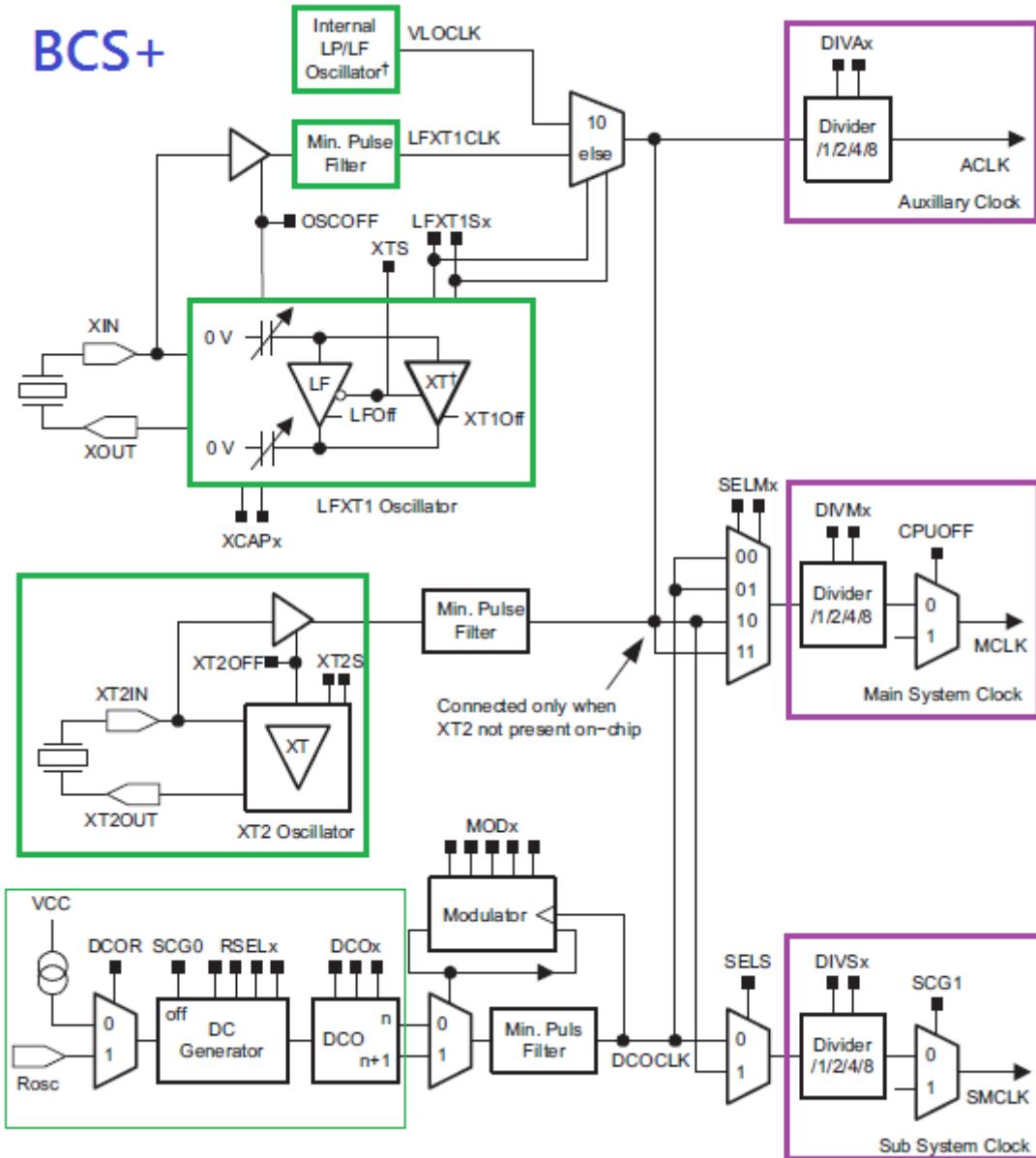
The latter is universal for all MSP430 micros and should be used unless otherwise.

- Bitwise and logic operations are useful. Not only they are fast, they just deal with the designated bits only. Although the MSP430 header files have efficient support for such operations, it is still better to know them. Shown below are some such common operations:

```
//For setting a bit of a register
#define bit_set(reg, bit_val) reg |= (1 << bit_val)
//For clearing a bit of a register
#define bit_clr(reg, bit_val) reg &= (~(1 << bit_val))
//For toggling a bit of a register
#define bit_tgl(reg, bit_val) reg ^= (1 << bit_val)
//For extracting the bit state of a register
#define get_bit(reg, bit_val) (reg & (1 << bit_val))
//For extracting masked bits of a register
#define get_regr(reg, msk) (reg & msk)
```

Basic Clock System Plus (BCS+)

In all microcontrollers, power consumption and operating speed are interdependent and it is needed to balance these well to maximize overall performance while conserving energy. MSP430s are crafted with ultra-low power consumption feature in mind while not compromising performance. For this reason, MSP430s are equipped with a number of clock sources that vary in speed, accuracy and area of use. They also have clock dividers at various points apart from peripherals prescalers. This combination leads to a highly flexible clock system called **Basic Clock System Plus (BCS+)**.



The block diagram for MSP420x2xx BCS+ module shown above highlights important components. It looks very sophisticated but if we divide it into important sections then it becomes simple to understand. Highlighted in green are clock sources and highlighted in purple are various clock signals that can be used for peripherals and the CPU. Now let's check BCS+ in short.

	Internal Very Low-Power, Low-Frequency Oscillator (VLOCLK)	Low or High Frequency Crystal Oscillator (LFXT1CLK)	High-Frequency Crystal Oscillator (XT2CLK)	Digitally-Controlled Oscillator (DCOCLK)
Oscillator Type	Internal RC Oscillator	External Clock Crystal	External Crystal, Resonator, TCXO, etc.	Internal RC Oscillator
Frequency Range	12kHz	32.768kHz (LF) or 0.4 – 16MHz (HF)	0.4 – 16MHz	1.0 – 16MHz
Accuracy	Very Low	High	High	Moderate
Availability	New devices only	All devices	Not all devices	All devices
Notes	Most suitable clock source for low power modes	HF mode is not available in all devices. HF mode can be used to synchronize with other devices	Optional and accurate	A key feature of MSP430s that has a very low startup time

	Auxiliary Clock (ACLK)	Master Clock (MCLK)	Sub-Main Clock (SMCLK)
Clock Source	LFXT1CLK VLOCLK	Any	Any
Clock Output Pin	Available	Unavailable	Available
Accuracy	Low	High	High
Application	Low Power Modes & Peripherals	CPU	Peripherals
Prescalers	1, 2, 4 and 8		

After having a sneak-a-peek of the MSP430's clock system, we have to know some basic rules of using the BCS+ module of MSP430G2xx devices:

- XT2CLK and LFXT1CLK high frequency mode are both unavailable. We can't use them.
- DCOCLK is the most reliable clock source and should be used for both MCLK and SMCLK.
- DCOCLK is dependent on VDD and so set VDD in GRACE before trying to setup BCS+.
- Pre-calibrated DCOCLK values should be used as they offer good tolerance figures.
- It is not wise to use custom DCOCLK values as accuracy issues surface.
- If LFXT1CLK is used and needs precise timings, use a good clock crystal/TCXO/clock source.
- Use proper capacitance value for LFXT1CLK when an external crystal is used.
- Unused clock sources should be disabled to reduce power consumption.
- Pins that connect with external clock sources should be set as inputs if they are not used.
- Add a system start up delay of about 10 – 100ms to allow stabilization of clock sources.
- Clock outputs are available only in certain pins. If used, they are needed to be set accordingly.
- Use oscillator fault interrupt if needed. This becomes extremely necessary to ensure fail-safe clock operation when external clock sources are used alongside internal clock sources.
- For time sensitive hardware like timers, try to use a reliable clock source.
- Check for warnings in GRACE.

Code Example

```
#include <msp430.h>

void BCSplus_graceInit(void);
void GPIO_graceInit(void);
void WDTplus_graceInit(void);
void System_graceInit(void);

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        P1OUT ^= BIT6;
        _delay_cycles(1);
    }
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_1 -- Divide by 2
     * SELS -- XT2CLK when XT2 oscillator present. LFXT1CLK or VLOCLK when XT2
     * oscillator not present
     * DIVS_3 -- Divide by 8
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~DCOR indicates that DCOR has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_1 | SELS | DIVS_3;

    if (CALBC1_1MHZ != 0xFF) {
        /* Follow recommended flow. First, clear all DCOr and MODx bits. Then

```

```

        * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
        */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

```

```

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT0 | BIT4;

    /* Port 1 Direction Register */
    P1DIR = BIT0 | BIT4 | BIT6;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;
}

```

```

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {

```

```

// Clear OSC fault flag
IFG1 &= ~OFIFG;

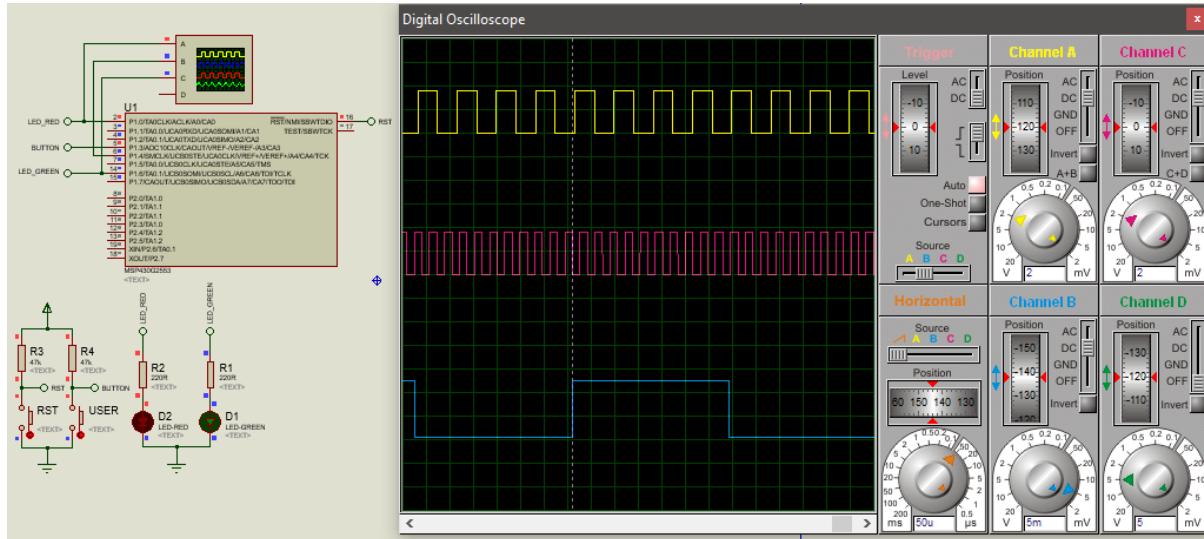
    // 50us delay
    __delay_cycles(25);
} while (IFG1 & OFIFG);

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
__bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

```

Simulation



Explanation

The demo example here is primarily used to extract SMCLK and ACLK signals. Here we just verified if these signals are as they are supposed to be. Using GRACE, we set MCLK 500 kHz, SMCLK 1500 Hz and ACLK 12 kHz. Clock outputs are obtained from respective pins as shown in the snap. The only thing additional here (not shown) is the P1.6 digital I/O. In the code, this I/O is toggled every one CPU cycle. It is not an indicator of CPU clock speed but just a test of I/O toggling speed for. MCLK has no output associated with it and so we can't see its signal.

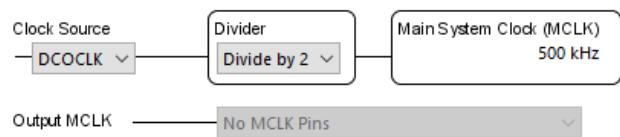
One major thing to note is the power supply voltage level. This is so because DCOCLK is dependent on VDD level. For low VDD voltages, high frequency oscillation generation is not possible. We have to remember that MSP430s are energy efficient devices and so there is always a trade-off between operating frequency and operating power consumption.

Another odd but important thing you may notice is the fact that the VDD value in MSP430 Launchpads is 3.6V instead of the more commonly used 3.3V. This is the maximum recommended VDD value although MSP430s can tolerate voltages up to 4.0V.

Configure Clock Source

Internal High Speed Clock Source	
Internal DCO ^[2]	<input type="text" value="1000.0"/> kHz
Pre-calibrated DCO Values	<input type="button" value="1 MHz"/>
<input type="checkbox"/> Disable DCO	

Select Clock Source



Low Speed External Clock Source 1	
Select Clock Source**	<input type="button" value="12 kHz"/>
XT1	<input type="text" value="12.0"/> kHz
Int. Load Eff. Capacitance	<input type="button" value="~6 pF"/>
<input type="checkbox"/> External Digital Source	
System Start-up Delay ^[3]	<input type="text" value="100.0"/> ms

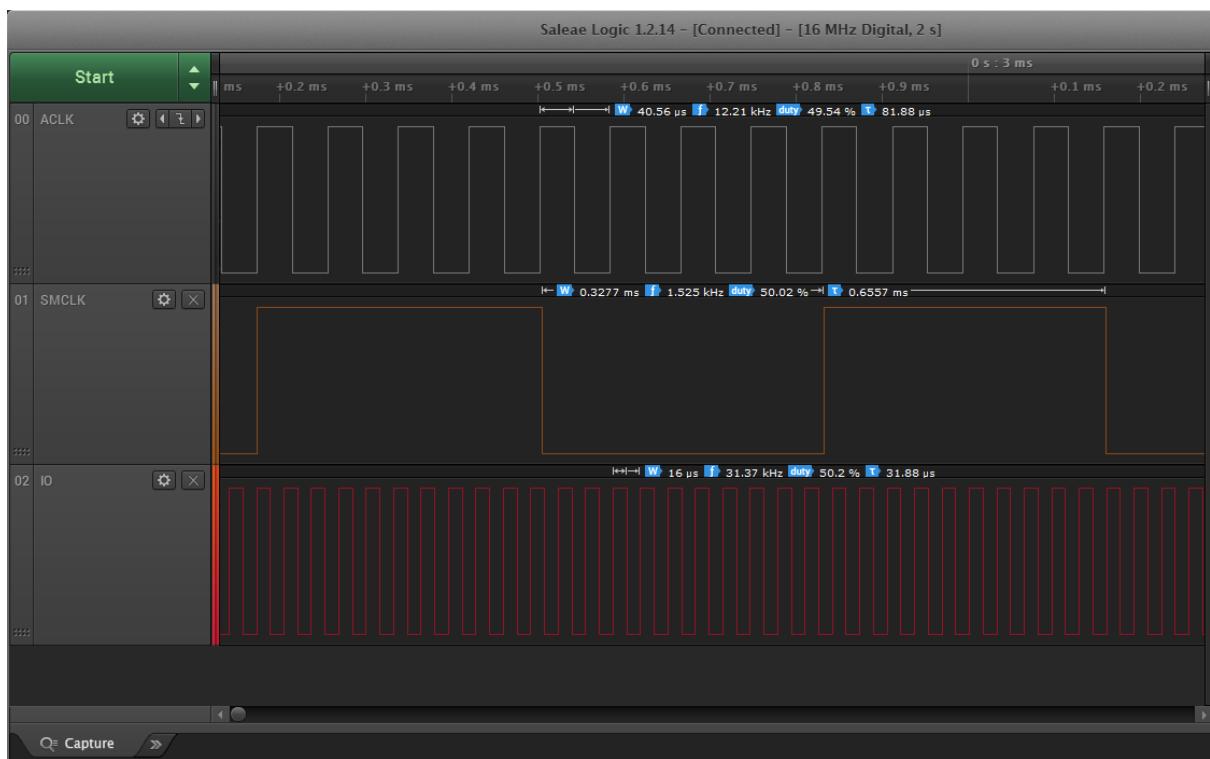
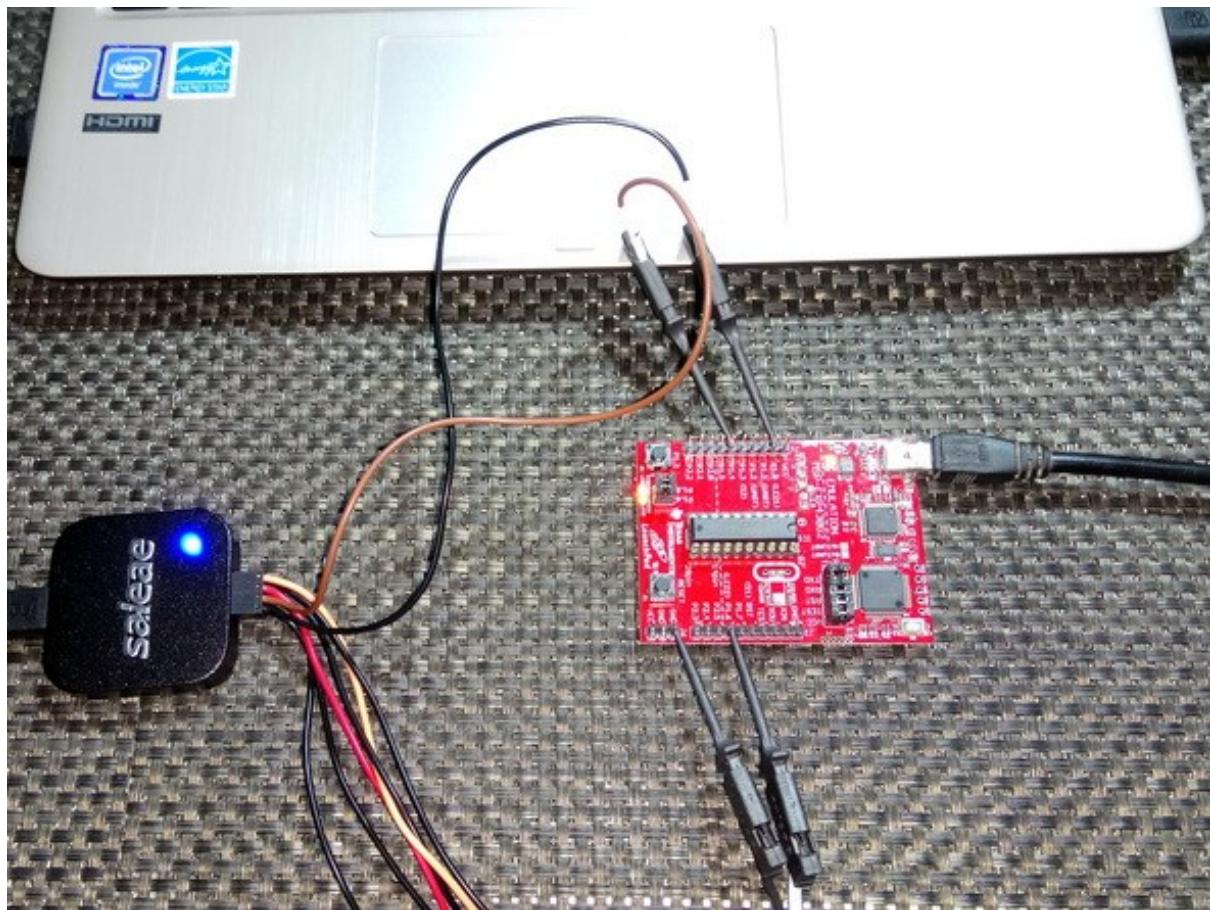
Interrupt Enables

Oscillator Fault Interrupt Enable



Oscillators may show deviations in frequency due to changes in ambient temperature conditions. This in turn may affect communication and timing-related tasks.

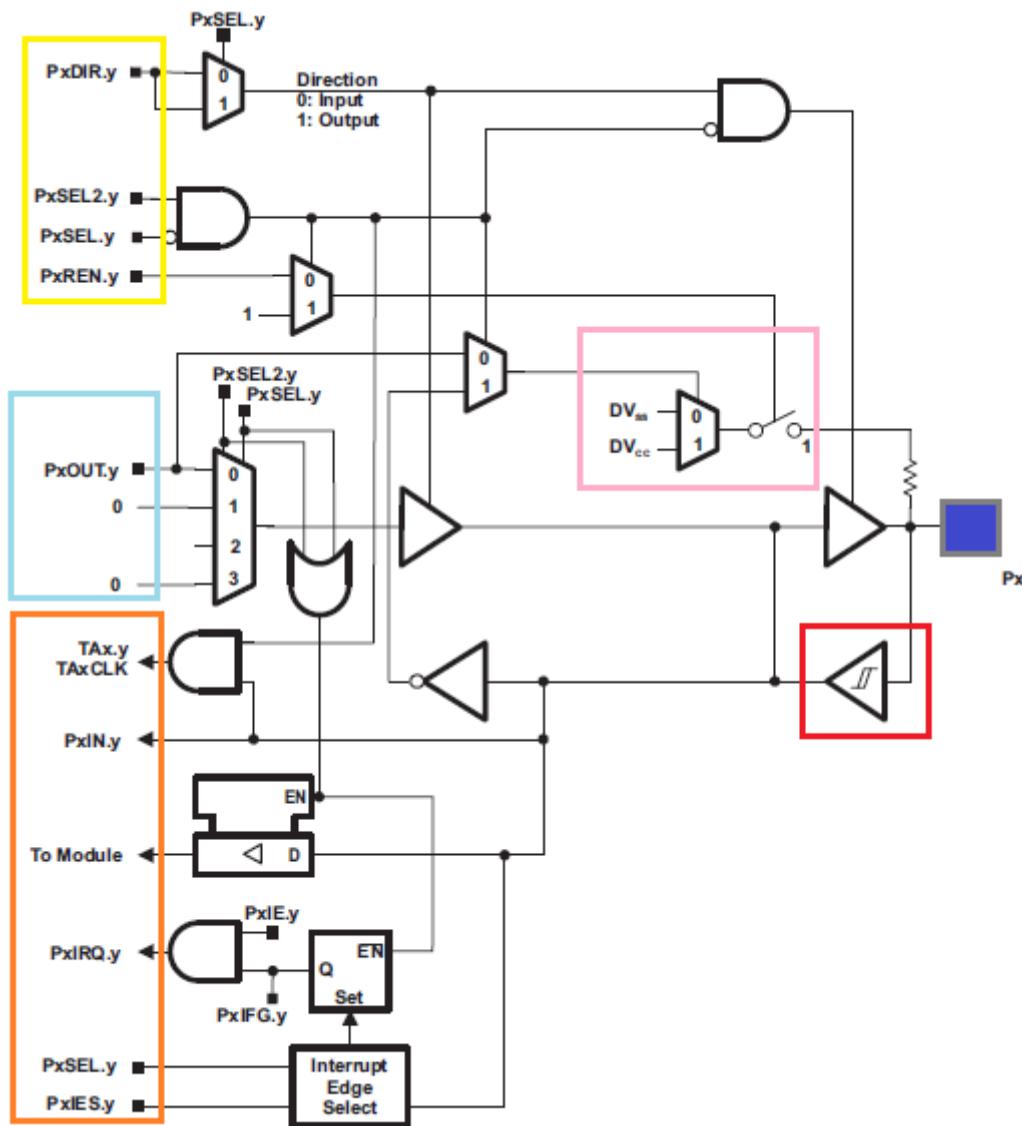
Demo



Demo video: <https://www.youtube.com/watch?v=gHDibVxfegU>.

Digital I/Os (DIO)

MSP430s, just like any micro, have digital I/Os for general-purpose input-output operations. The resources and features of MSP430 digital I/Os are very rich and more or less comparable to a typical ARM microcontroller. All I/O can be independently programmed. Many I/Os have external interrupt feature. Another cool feature is the availability of both internal pull-up and pull-down resistors for all I/Os and they can be individually and independently set. Additionally, many I/Os have alternate roles for communication buses, clock, etc. However, the digital I/Os are not 5V tolerant and we must be careful interfacing external devices with our MSP430 chips. I strongly recommend using some form of logic-level conversion circuitry in such cases.



Typically, there are four major components in a digital I/O as highlighted in the block diagram above. The yellow region is responsible for setting I/O properties, the light blue area is dedicated for output functionalities, the orange area for inputs and external interrupts, the pink zone for internal pull resistors and finally the red area signifying the presence of a Schmitt trigger input stage which is very useful for noisy environments.

Code Example

```
#include <msp430g2452.h>

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void WDTplus_graceInit(void);
void System_graceInit(void);

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    for(;;)
    {
        if((P1IN & BIT3) == !BIT3)
        {
            P1OUT |= BIT0;
            _delay_cycles(40000);
            P1OUT &= ~BIT0;
        }

        P1OUT ^= BIT6;
        _delay_cycles(30000);
    }
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     */
}
```

```

 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;          /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
P1OUT = BIT3;

    /* Port 1 Direction Register */
P1DIR = BIT0 | BIT6;

    /* Port 1 Resistor Enable Register */
P1REN = BIT3;

    /* Port 1 Interrupt Edge Select Register */
P1IES = 0;

    /* Port 1 Interrupt Flag Register */

```

```

P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO0_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(50);
    } while (IFG1 & OFIFG);

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    __bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
}

```

```

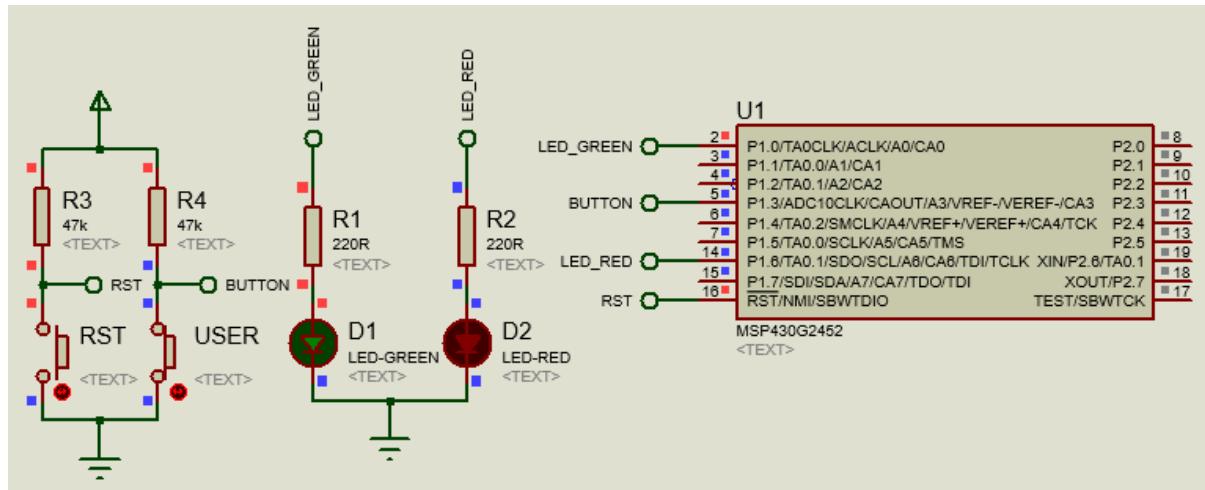
/* USER CODE END (section: RTC_B_graceInit_prologue) */

/*
 * WDTCTL, Watchdog Timer+ Register
 *
 * WDTPW -- Watchdog password
 * WDTHOLD -- Watchdog timer+ is stopped
 * ~WDTNMIES -- NMI on rising edge
 * ~WDTNMI -- Reset function
 * ~WDTTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * ~WDTSSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation



Explanation

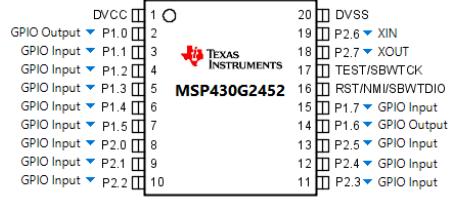
The most classical “**Hello World**” demo for digital I/Os is blinking a LED. Here I demonstrated the same but with some minor differences. Here Launchpad board’s user button and LEDs are used. LED connected to P1.6 blinks continuously while P1.0 LED blinks only when the user button is pressed, slowing down P1.6 LED’s blink rate. Note **_delay_cycles** were used to create software delays.

At this stage I must point out, some basic rules that we must follow when we use digital I/Os of MSP430s:

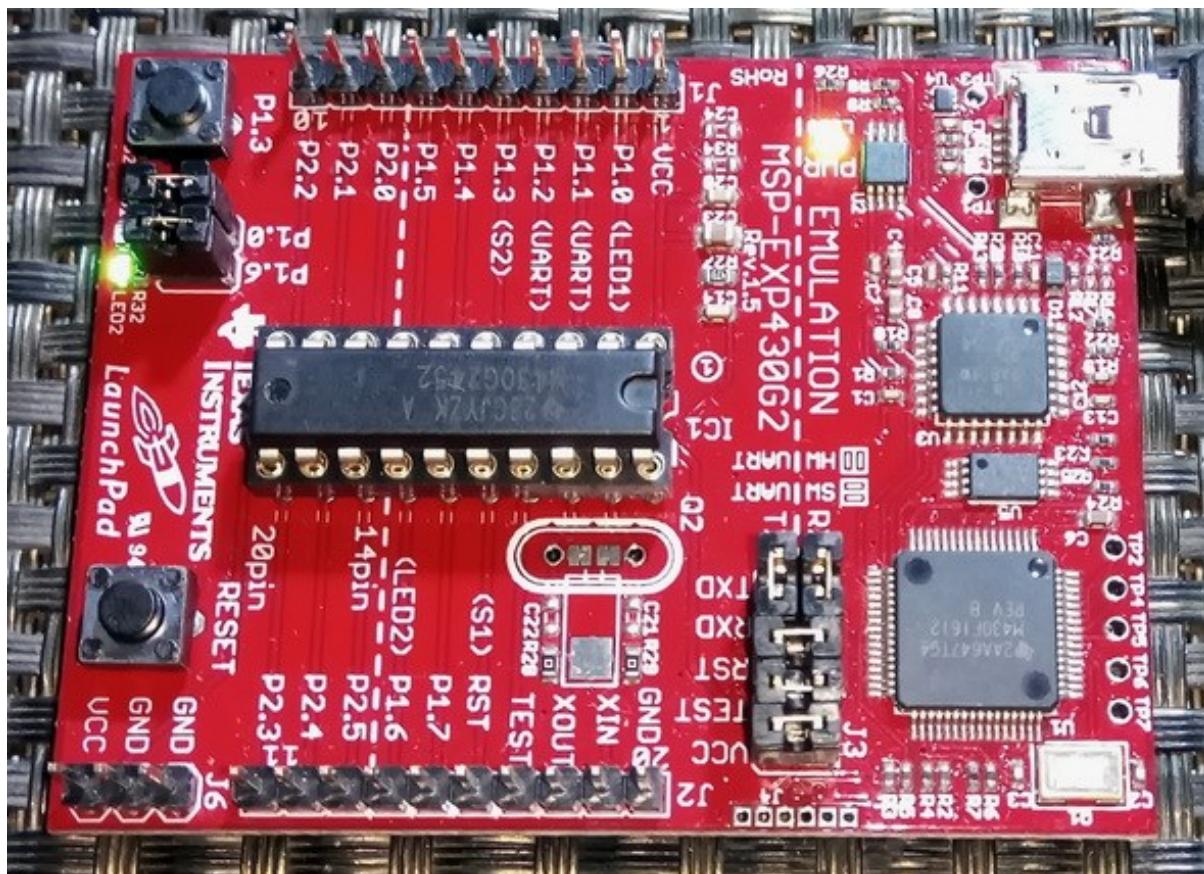
- Unused I/Os should be declared as inputs or they should be externally pulled to VDD/VSS.

- Unused digital I/Os can be left unconnected and floating although it is not wise to do so.
- The same applies for oscillator pins. By default, GRACE treats them as oscillator pins.
- I/Os are not 5V tolerant. Some sort of mechanism must be applied when using 5V devices.
- Most I/Os have more than one function and so be aware of conflicts.
- When driving large loads with I/O, use external components like BJTs, FETs, drivers, etc.
- When using GRACE, be sure of the IC package you are using.
- When external pull resistor is present, do not use the internal ones and vice versa.
- Explore your device's datasheet for I/O features and limits although most are common.

GPIO Function	Output State	Pull-Up/Down Resistor Enable	Interrupt Enable
P1.0 ▾ GPIO Output	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P1.1 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P1.2 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P1.3 ▾ GPIO Input	▼ Output Set High	▼ Pull-Up Resistor	▼ Disabled
P1.4 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P1.5 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P1.6 ▾ GPIO Output	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P1.7 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P2.6 ▾ XIN	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled
P2.7 ▾ XOUT	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled


MSP430G2452
 20-pin package
 Pinout details:
 1: DVCC, 2: P1.0, 3: P1.1, 4: P1.2, 5: P1.3, 6: P1.4, 7: P1.5, 8: P2.0, 9: P2.1, 10: P2.2, 11: P2.3, 12: P2.4, 13: P2.5, 14: P1.6, 15: P1.7, 16: RST/NMI/SWDTIO, 17: TEST/SWDTCK, 18: P2.7/XOUT, 19: P2.6/XIN, 20: DVSS

Demo



Demo video: <https://www.youtube.com/watch?v=fWINiEZk4iM>.

External Interrupts (EXTI)

External interrupt is an extended feature of digital I/Os in input mode. External interrupts make a micro to respond instantly to changes done on its digital input pin(s) by an external event(s)/trigger(s), skipping other tasks. Such interrupts are useful in a wide variety of applications. In case of low power energy efficient micros like the MSP430s, interrupts as such can be used to bring a micro out of sleep mode. In other words, an external interrupt acts like a wakeup call. For example, it is extremely important to conserve very limited battery energy in a TV remote controller while at the same time it is also necessary to keep it completely responsive to button presses. Thus, we need to put its host micro in sleep mode when we are not using it and make it respond to button presses immediately when any button is pressed. A MSP430 micro in sleep/idle mode consumes literally no energy at all and that is why they are the best micros for battery-backed low power applications.

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
Power-Up External Reset Watchdog Timer+ Flash key violation PC out-of-range ⁽¹⁾	PORIFG RSTIFG WDTIFG KEYV ⁽²⁾	Reset	0FFF Eh	31, highest
NMI Oscillator fault Flash memory access violation	NMIIFG OFIFG ACCVIFG ⁽²⁾⁽³⁾	(non)-maskable (non)-maskable (non)-maskable	0FFF Ch	30
Timer1_A3	TA1CCR0 CCIFG ⁽⁴⁾	maskable	0FFF Ah	29
Timer1_A3	TA1CCR2 TA1CCR1 CCIFG, TAIFG ⁽²⁾⁽⁴⁾	maskable	0FFF 8h	28
Comparator_A+	CAIFG ⁽⁴⁾	maskable	0FFF 6h	27
Watchdog Timer+	WDTIFG	maskable	0FFF 4h	26
Timer0_A3	TA0CCR0 CCIFG ⁽⁴⁾	maskable	0FFF 2h	25
Timer0_A3	TA0CCR2 TA0CCR1 CCIFG, TAIFG ⁽⁵⁾⁽⁴⁾	maskable	0FFF 0h	24
USCI_A0/USCI_B0 receive USCI_B0 I2C status	UCA0RXIFG, UCB0RXIFG ⁽²⁾⁽⁵⁾	maskable	0FFE Eh	23
USCI_A0/USCI_B0 transmit USCI_B0 I2C receive/transmit	UCA0TXIFG, UCB0TXIFG ⁽²⁾⁽⁶⁾	maskable	0FFE Ch	22
ADC10 (MSP430G2x53 only)	ADC10IFG ⁽⁴⁾	maskable	0FFE Ah	21
			0FFE 8h	20
I/O Port P2 (up to eight flags)	P2IFG.0 to P2IFG.7 ⁽²⁾⁽⁴⁾	maskable	0FFE 6h	19
I/O Port P1 (up to eight flags)	P1IFG.0 to P1IFG.7 ⁽²⁾⁽⁴⁾	maskable	0FFE 4h	18
			0FFE 2h	17
			0FFE 0h	16
See ⁽⁷⁾			0FFDEh	15
See ⁽⁸⁾			0FFDEh to 0FFC0h	14 to 0, lowest

Fortunately for us, most MSP430G2xx digital I/Os have external interrupt handling capability – a much desired feature. Shown above is the interrupt map for MSP430G2553. Note external interrupts are maskable interrupts and have low priority compares to other interrupts. We must consider this fact when coding a multi-interrupt-based application.

Code Example

```
#include <MSP430G2452.h>

unsigned char state = 0x00;

void BCSplus_graceInit(void);
void GPIO_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

#pragma vector=PORT1_VECTOR
__interrupt void PORT1_ISR_HOOK(void)
{
    state = ~state;
    P1OUT ^= BIT0;
    P1IFG = 0x00;
}

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    do
    {
        P1OUT ^= BIT6;
        if(state)
        {
            _delay_cycles(60000);
        }
        else
        {
            _delay_cycles(30000);
        }
    }while(1);
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
```

```

/* User initialization code */
/* USER CODE END (section: BCSplus_graceInit_prologue) */

/*
 * Basic Clock System Control 2
 *
 * SELM_0 -- DCOCLK
 * DIVM_0 -- Divide by 1
 * ~SELS -- DCOCLK
 * DIVS_0 -- Divide by 1
 * ~DCOR -- DCO uses internal resistor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
}

```

```

P1OUT = 0;

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT6;

/* Port 1 Interrupt Edge Select Register */
P1IES = BIT3;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 1 Interrupt Enable Register */
P1IE = BIT3;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

```

```

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(50);
    } while (IFG1 & OFIFG);

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
    */
}

```

```

/*
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
__bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

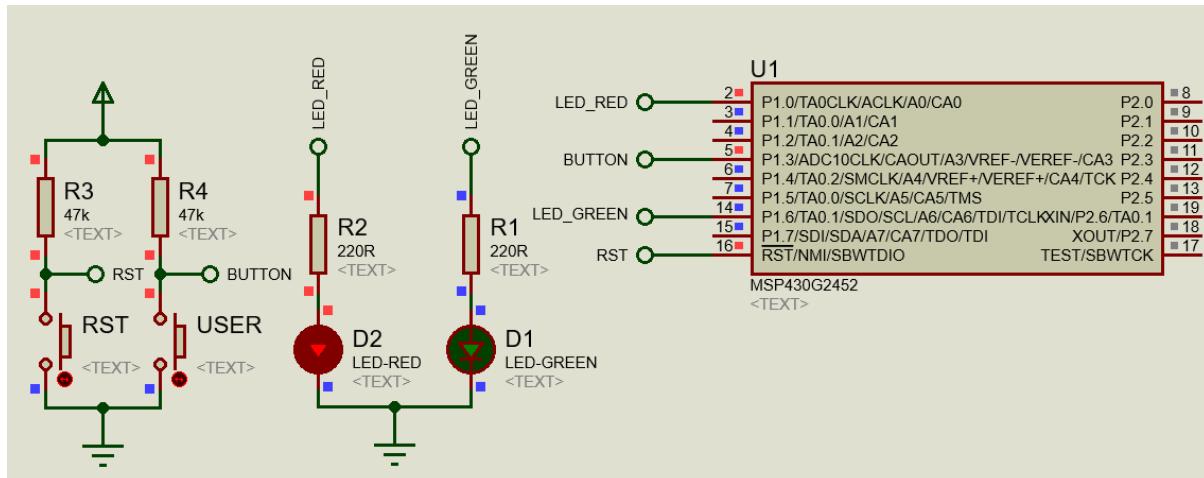
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation



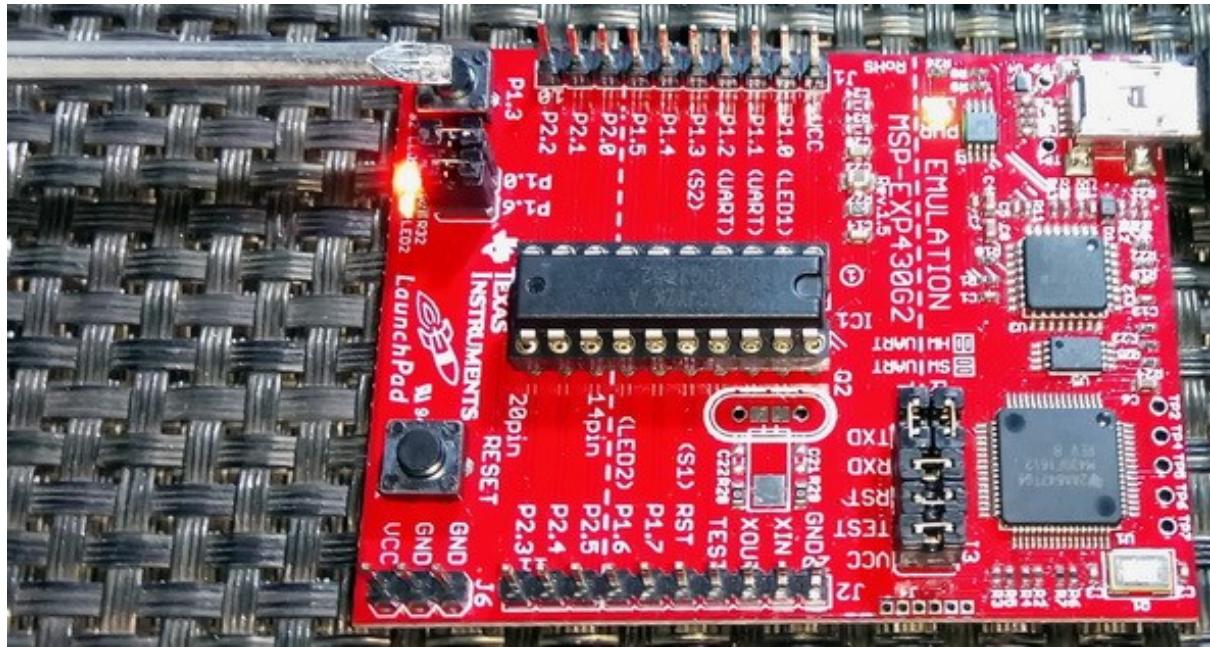
Explanation

The basic theme and the hardware setup for this demo is same as that of the previous one. The only difference is the Launchpad user button. Rather than using polling method, external interrupt method is used. When P1.3 detects a falling edge, P1.0's state is altered while P1.6 toggles independently in the main loop, denoting two separate independent processes at work simultaneously. Every external interrupt changes the toggle speed of P1.6 LED.

GPIO Function	Output State	Pull-Up/Down Resistor Enable	Interrupt Enable	
P1.0 ▾ GPIO Output	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	DVCC 1 O
P1.1 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	20 DVSS
P1.2 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	19 P2.6 ▾ GPIO Input
P1.3 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Interrupt Enabled Falling Edge	18 P2.7 ▾ GPIO Input
P1.4 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	17 TEST/SBWTCK
P1.5 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	16 RSTIN/MISBWTDO
P1.6 ▾ GPIO Output	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	15 P1.7 ▾ GPIO Input
P1.7 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	14 P1.6 ▾ GPIO Output
P2.6 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	13 P2.5 ▾ GPIO Input
P2.7 ▾ GPIO Input	▼ Output Set Low (Default)	▼ Disabled	▼ Disabled	12 P2.4 ▾ GPIO Input
				11 P2.3 ▾ GPIO Input

MSP430G2452

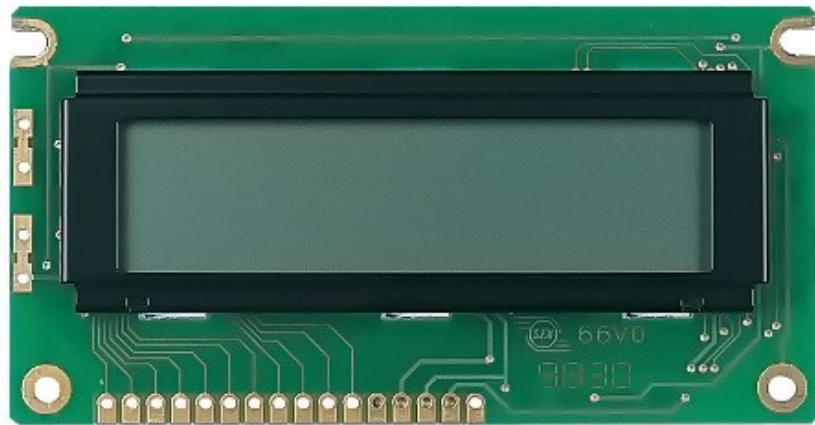
Demo



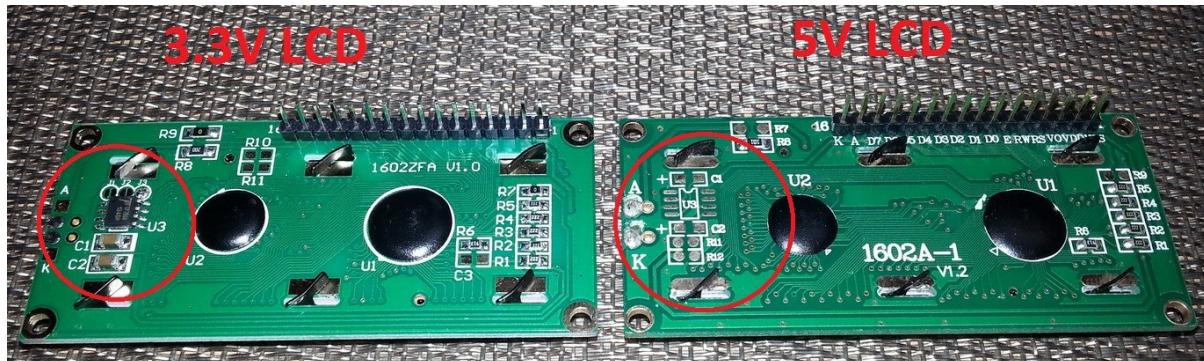
Demo video: <https://www.youtube.com/watch?v=LITvj-CSiBE>.

Alphanumeric LCD

Alphanumeric LCDs are popular for projecting data and information quickly and efficiently. To use them, we do not need any additional hardware feature in a micro. Digital I/Os are what we need to use these displays.



Usually to use these LCDs we need 5V power supply. 3.3V versions of these LCD are rare on the other hand. It is, however, possible to power up 5V version LCDs with 5V supply while using 3.3V logic for communication. In TTL logic, something above 2.8V is just above the minimum allowed logic high voltage. When VDD is less than 3V, it, then, becomes necessary to use logic level conversion circuitry. Here in my demo I used a 3.3V version LCD to keep things simple and tidy. Shown below are LCDs for different voltage levels. Both LCDs look same but if you check the backside of both LCDs you'll notice a difference. In the 3.3V version LCD, there are some additional components present, notably an 8 pin SMD IC. This is a ICL7660 negative voltage generator IC.

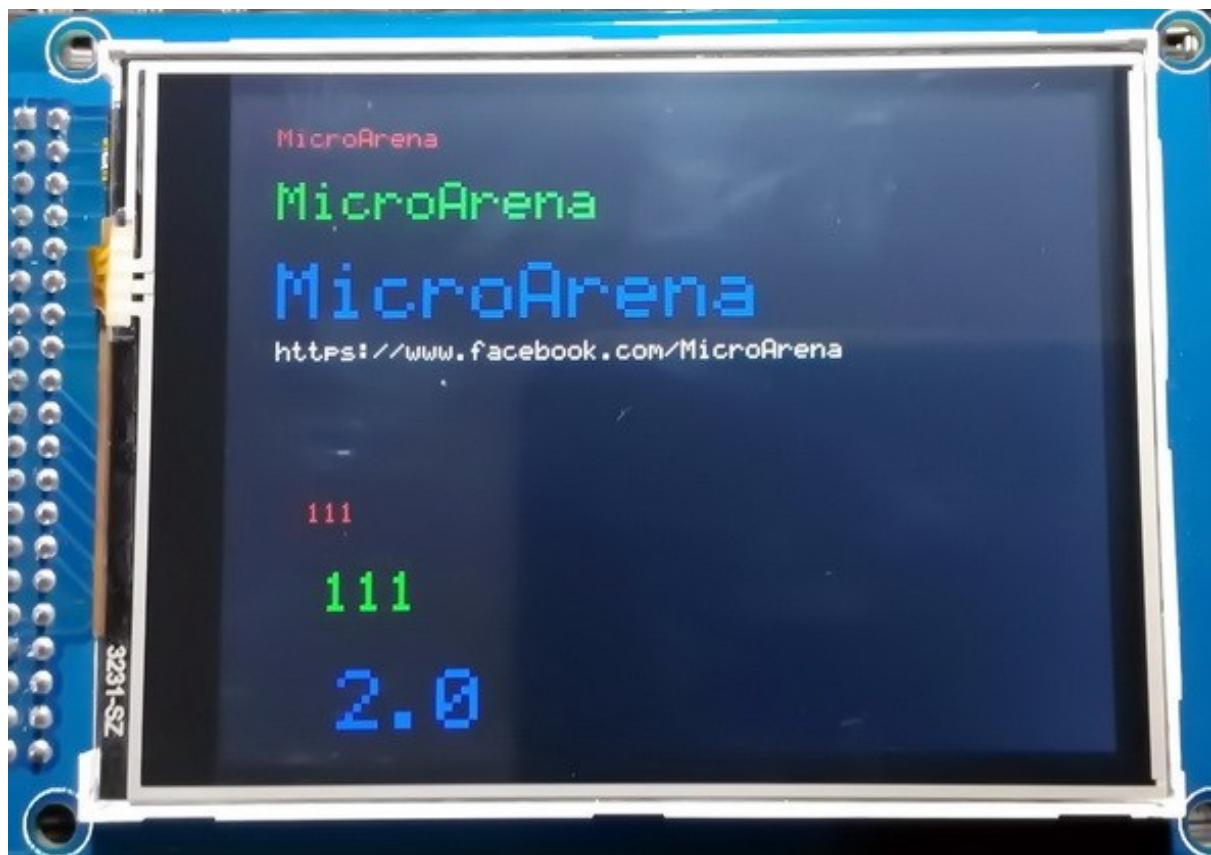


Similarly, alphanumeric

LCDs also have operating frequency limit. Usually it is about 250 kHz. Refer to the datasheet of the LCD you are using. If the digital I/Os are faster than this max limit value, it is highly likely that the LCD won't show any valid data at all or it will show up garbage characters. To counter this issue, either we have to use a low MCU clock frequency or add some delays in our LCD library to slow the processes down.

Software delays are often required to introduce time delays in a code. Such delays will be needed for the LCD library. As discussed before by default, CCS doesn't provide delay time functions i.e. delay milliseconds (**delay_ms**) and delay micro-seconds (**delay_us**). Instead it provides **_delay_cycles** function for delays. Most of us will not be comfortable with delay cycles function as it doesn't directly signify the amount of time wasted. Thus, delay time functions are musts. Although software delays are inefficient in terms of coding and performance, they are helpful in debugging stuffs quickly in a rudimentary fashion. A much novel and precise approach of creating time delays is achieved using a timer. In this example, we will need both LCD and delay libraries. I already showed how to incorporate custom libraries in a CCS Project and here I implemented that addition.

There are other types of displays in the realm of LCDs. These include monochrome graphical LCDs, TFT LCDs, OLED LCDs, etc. However, it is literally impossible to integrate these displays with MSP430G2xx micros. Firstly, this is so due to low memories and secondly due to low pin counts. MSP430G2xx micros are also not as fast as ARM micros. Speed plays a vital role in processing graphics.



Code Example

delay.h

```
#include <msp430.h>

#define F_CPU 8

void delay_us(unsigned int value);
void delay_ms(unsigned int value);
```

delay.c

```
#include "delay.h"

void delay_us(unsigned int value)
{
    register unsigned int loops = ((F_CPU * value) >> 2);

    while(loops)
    {
        _delay_cycles(1);
        loops--;
    }
}

void delay_ms(unsigned int value)
{
    while(value)
    {
        delay_us(1000);
        value--;
    }
}
```

lcd.h

```
#include <msp430.h>
#include <delay.h>

#define LCD_PORT P2OUT

#define LCD_RS BIT0
#define LCD_EN BIT1
#define LCD_DB4 BIT2
#define LCD_DB5 BIT3
#define LCD_DB6 BIT4
#define LCD_DB7 BIT5

#define LCD_RS_HIGH LCD_PORT |= LCD_RS
```

```

#define LCD_RS_LOW           LCD_PORT &= ~LCD_RS
#define LCD_EN_HIGH          LCD_PORT |= LCD_EN
#define LCD_EN_LOW           LCD_PORT &= ~LCD_EN

#define LCD_DB4_HIGH         LCD_PORT |= LCD_DB4
#define LCD_DB4_LOW          LCD_PORT &= ~LCD_DB4

#define LCD_DB5_HIGH         LCD_PORT |= LCD_DB5
#define LCD_DB5_LOW          LCD_PORT &= ~LCD_DB5

#define LCD_DB6_HIGH         LCD_PORT |= LCD_DB6
#define LCD_DB6_LOW          LCD_PORT &= ~LCD_DB6

#define LCD_DB7_HIGH         LCD_PORT |= LCD_DB7
#define LCD_DB7_LOW          LCD_PORT &= ~LCD_DB7

#define clear_display        0x01
#define goto_home             0x02

#define cursor_direction_inc (0x04 | 0x02)
#define cursor_direction_dec (0x04 | 0x00)
#define display_shift         (0x04 | 0x01)
#define display_no_shift      (0x04 | 0x00)

#define display_on            (0x08 | 0x04)
#define display_off           (0x08 | 0x02)
#define cursor_on              (0x08 | 0x02)
#define cursor_off             (0x08 | 0x00)
#define blink_on               (0x08 | 0x01)
#define blink_off              (0x08 | 0x00)

#define _8_pin_interface      (0x20 | 0x10)
#define _4_pin_interface       (0x20 | 0x00)
#define _2_row_display         (0x20 | 0x08)
#define _1_row_display         (0x20 | 0x00)
#define _5x10_dots             (0x20 | 0x40)
#define _5x7_dots               (0x20 | 0x00)

#define DAT                  1
#define CMD                  0

void LCD_init(void);
void LCD_send(unsigned char value, unsigned char mode);
void LCD_4bit_send(unsigned char lcd_data);
void LCD_putstr(char *lcd_string);
void LCD_putchar(char char_data);
void LCD_clear_home(void);
void LCD_goto(unsigned char x_pos, unsigned char y_pos);
void toggle_EN_pin(void);
void toggle_io(unsigned char lcd_data, unsigned char bit_pos, unsigned char pin_num);

```

lcd.c

```
#include "lcd.h"

void LCD_init(void)
{
    LCD_PORT |= (LCD_RS | LCD_EN | LCD_DB4 | LCD_DB5 | LCD_DB6 | LCD_DB7);

    delay_ms(20);

    toggle_EN_pin();

    LCD_RS_LOW;

    LCD_DB7_LOW;
    LCD_DB6_LOW;
    LCD_DB5_HIGH;
    LCD_DB4_HIGH;

    toggle_EN_pin();

    LCD_DB7_LOW;
    LCD_DB6_LOW;
    LCD_DB5_HIGH;
    LCD_DB4_HIGH;

    toggle_EN_pin();

    LCD_DB7_LOW;
    LCD_DB6_LOW;
    LCD_DB5_HIGH;
    LCD_DB4_LOW;

    toggle_EN_pin();

    LCD_send((_4_pin_interface | _2_row_display | _5x7_dots), CMD);
    LCD_send((display_on | cursor_off | blink_off), CMD);
    LCD_send(clear_display, CMD);
    LCD_send((cursor_direction_inc | display_no_shift), CMD);
}

void LCD_send(unsigned char value, unsigned char mode)
{
    switch(mode)
    {
        case DAT:
        {
            LCD_RS_HIGH;
            break;
        }
    }
}
```

```

    case CMD:
    {
        LCD_RS_LOW;
        break;
    }
}

LCD_4bit_send(value);
}

void LCD_4bit_send(unsigned char lcd_data)
{
    toggle_io(lcd_data, 7, LCD_DB7);
    toggle_io(lcd_data, 6, LCD_DB6);
    toggle_io(lcd_data, 5, LCD_DB5);
    toggle_io(lcd_data, 4, LCD_DB4);

    toggle_EN_pin();

    toggle_io(lcd_data, 3, LCD_DB7);
    toggle_io(lcd_data, 2, LCD_DB6);
    toggle_io(lcd_data, 1, LCD_DB5);
    toggle_io(lcd_data, 0, LCD_DB4);

    toggle_EN_pin();
}

void LCD_putstr(char *lcd_string)
{
    do
    {
        LCD_send(*lcd_string++, DAT);
    }while(*lcd_string != '\0');
}

void LCD_putchar(char char_data)
{
    LCD_send(char_data, DAT);
}

void LCD_clear_home(void)
{
    LCD_send(clear_display, CMD);
    LCD_send(goto_home, CMD);
}

void LCD_goto(unsigned char x_pos, unsigned char y_pos)
{
    if(y_pos == 0)
    {
        LCD_send((0x80 | x_pos), CMD);
    }
    else
    {

```

```

        LCD_send((0x80 | 0x40 | x_pos), CMD);
    }

void toggle_EN_pin(void)
{
    LCD_EN_HIGH;
    delay_ms(2);
    LCD_EN_LOW;
    delay_ms(2);
}

void toggle_io(unsigned char lcd_data, unsigned char bit_pos, unsigned char
pin_num)
{
    unsigned char temp = 0x00;

    temp = (0x01 & (lcd_data >> bit_pos));

    switch(temp)
    {
        case 0:
        {
            LCD_PORT &= ~pin_num;
            break;
        }

        default:
        {
            LCD_PORT |= pin_num;
            break;
        }
    }
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "lcd.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

void main(void)
{
    unsigned char s = 0;

    const char txt1[] = {"MICROARENA"};
    const char txt2[] = {"SShahryiar"};
    const char txt3[] = {"MSP-EXP430G2"};
    const char txt4[] = {"Launchpad!"};

```

```

/* Stop watchdog timer from timing out during initial start-up. */
WDTCTL = WDTPW | WDTHOLD;

/* initialize Config for the MSP430 GPIO */
GPIO_graceInit();

/* initialize Config for the MSP430 2xx family clock systems (BCS) */
BCSplus_graceInit();

/* initialize Config for the MSP430 System Registers */
System_graceInit();

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

LCD_init();

LCD_clear_home();

LCD_goto(3, 0);
LCD_putstr(txt1);
LCD_goto(3, 1);
LCD_putstr(txt2);
delay_ms(2600);

LCD_clear_home();

for(s = 0; s < 12; s++)
{
    LCD_goto((2 + s), 0);
    LCD_putchar(txt3[s]);
    delay_ms(90);
}
for(s = 0; s < 10; s++)
{
    LCD_goto((3 + s), 1);
    LCD_putchar(txt4[s]);
    delay_ms(90);
}

while(1)
{
};

}

void GPIO_graceInit(void)
{
/* USER CODE START (section: GPIO_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Direction Register */
P1DIR = 0;

```

```

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = BIT0 | BIT1 | BIT2 | BIT3 | BIT4 | BIT5;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF) {
        /* Adjust this accordingly to your VCC rise time */
        __delay_cycles(100000);

        // Follow recommended flow. First, clear all DCOx and MODx bits. Then
        // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_8MHZ;      /* Set DCO to 8MHz */
        DCOCTL = CALDCO_8MHZ;
    }

    /*
     * Basic Clock System Control 1

```

```

/*
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    __bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     */
}

```

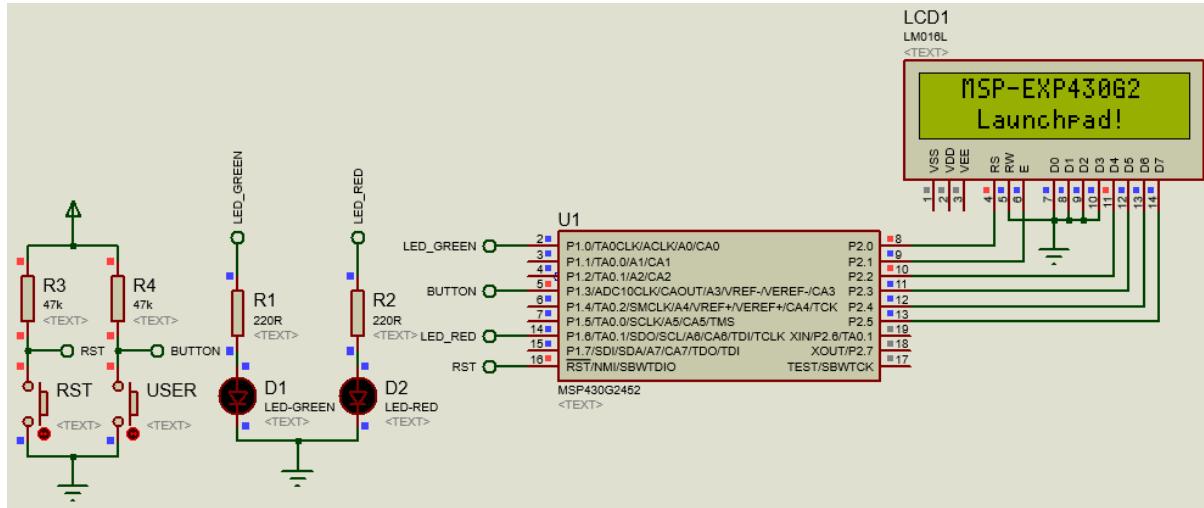
```

/* WDTPW -- Watchdog password
 * WDTHOLD -- Watchdog timer+ is stopped
 * ~WDTNMIES -- NMI on rising edge
 * ~WDTNMI -- Reset function
 * ~WDTTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * ~WDTSSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation

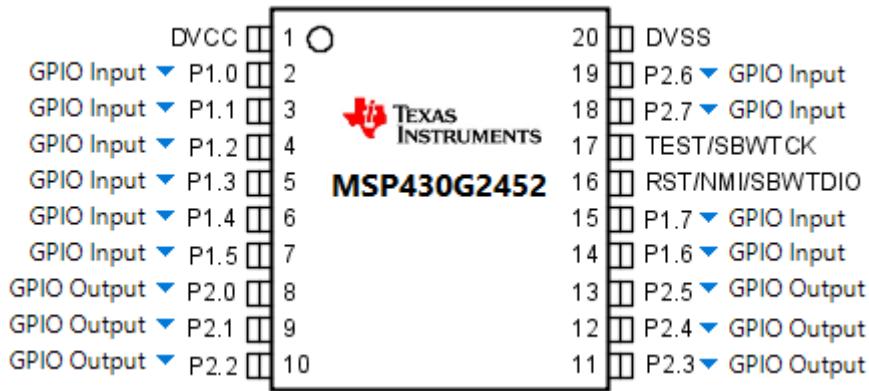


Explanation

Hardly there is a thing to explain here. However, there are a few things to note. After having decided the CPU clock frequency, we must edit the following line of the delay header file to make our delays work as much as accurate as possible:

```
#define F_CPU 8 //CPU Clock in MHz
```

Software delays are not 100% accurate since they employ wasteful loops of delay cycles which in turn add extra CPU cycles. They are always somewhat close to the actual required value. Delays are also dependent on oscillator accuracy.



Though it is not mandatory but I still recommend that we try to use digital I/Os that have no or least alternate functionalities. This will ensure maximum utilization of limited resources and avoid conflicts as well. Here in this demo, I used P2 port just for that.

Choosing the right display for a project is often tedious. We have lot of options nowadays ranging from simple LED displays to TFT LCDs. However, considering low power consumption and limited resource availability, it wise to use the simplest form of display. If a project can be completed using seven segment displays, it wasteful and expensive to use a OLED display with seven segment fonts.

LCD displays host their own set of electronics and are prone to **Electromagnetic Interference (EMI)** and related issues. In many cases, one may end up having a EMI troubled LCD while having the host MCU fully functional and vice-versa. It is always wise to use a short path between a LCD and its host MCU. If needed, use passive low pass antialiasing filters.

Demo



Demo video: <https://www.youtube.com/watch?v=sJF8oJPu18s>.

Low Power Modes (LPM)

From the smart watches in our wrists to the vehicles we use for transportation, many modern electronic gadgets and gizmos are battery-powered. Some are even dependent on renewable energy sources like solar energy. In such devices, there is always an inherent energy crisis and so saving energy is a must in such designs for prolonged usage. At present there is hardly any microcontroller in the market that does not come equipped with energy-saving schemes or low power modes of operation. MSP430s were mainly designed for battery-backed instruments and it is no surprise that they come loaded with the some of the best possible energy-saving mechanisms.

There six modes of operation of which five are low power modes. These are as follows:

SCG1	SCG0	OSCOFF	CPUOFF	Mode	CPU and Clocks Status
0	0	0	0	Active	CPU is active, all enabled clocks are active
0	0	0	1	LPM0	CPU, MCLK are disabled, SMCLK, ACLK are active
0	1	0	1	LPM1	CPU, MCLK are disabled. DCO and DC generator are disabled if the DCO is not used for SMCLK. ACLK is active.
1	0	0	1	LPM2	CPU, MCLK, SMCLK, DCO are disabled. DC generator remains enabled. ACLK is active.
1	1	0	1	LPM3	CPU, MCLK, SMCLK, DCO are disabled. DC generator disabled. ACLK is active.
1	1	1	1	LPM4	CPU and all clocks disabled

Of these six modes, three modes are mostly used – Active Mode (AM), LPM0 and LPM3. In Active Mode, the typical self-consumption of a MSP430 device is roughly about $300\mu\text{A}$ with nothing connected to it. In LPM0 the self-consumption is about a third of active mode while in LPM3, this consumption is just about $1\mu\text{A}$. These figures tell us how much energy efficient MSP430s are.

Entering and exiting LPM is easy in terms of coding. However, the most common question that coders face with LPMs is how to get back to active mode or some other low power mode from a given low power mode. Well, it is pretty simple and it is accomplished with interrupts. It is up to coders to decide how to manage interrupts, clock sources and what do to after waking up from a LPM condition. Note that in LPMs, the CPU is disabled and so any task that requires CPU's intervention is stalled. Since the CPU and some clocks are halted in LPMs, don't even think that the tasks depending on them will be magically done. For instance, if a code has entered LPM3 and a timer is being driven with SMCLK, we should not expect it to tick because in LPM3, SMCLK is turned off. Organizing the code in a decent and well-planned manner is the secret behind successfully implementing LPMs.

Code Example

```
#include <msp430.h>
#include "delay.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
```

```

#pragma vector = PORT1_VECTOR
__interrupt void PORT1_ISR_HOOK(void)
{
    LPM2_EXIT;
    P1OUT |= BIT6;
    P1IFG = 0x00;
}

void main(void)
{
    unsigned char s = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        for(s = 0; s < 9; s++)
        {
            P1OUT ^= BIT0;
            delay_ms(160);
        }

        P1OUT &= ~BIT6;
        LPM2;
    };
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = BIT3;

    /* Port 1 Direction Register */
    P1DIR = BIT0 | BIT6;

    /* Port 1 Resistor Enable Register */
    P1REN = BIT3;

    /* Port 1 Interrupt Edge Select Register */
}

```

```

P1IES = BIT3;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 1 Interrupt Enable Register */
P1IE = BIT3;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO0_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF)
    {
        /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
         * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
         */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }
}
/*

```

```

    * Basic Clock System Control 1
    *
    * XT2OFF -- Disable XT2CLK
    * ~XTS -- Low Frequency
    * DIVA_0 -- Divide by 1
    *
    * Note: ~XTS indicates that XTS has value zero
    */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(50);
    } while (IFG1 & OFIFG);

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    __bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

```

```

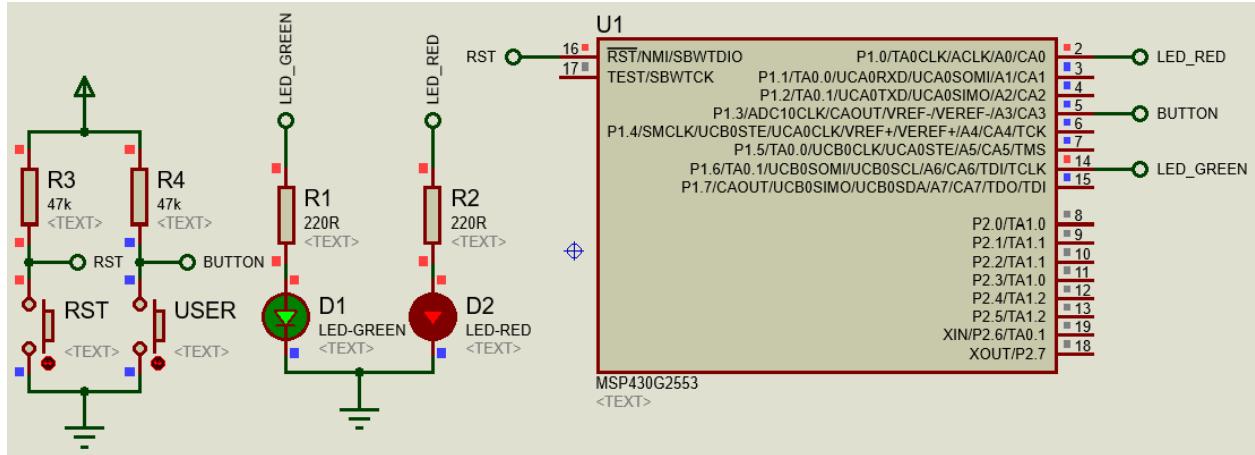
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation



The simulation log of Proteus shown below shows when the internal oscillators started and stopped. These indicate LPM and AM states.

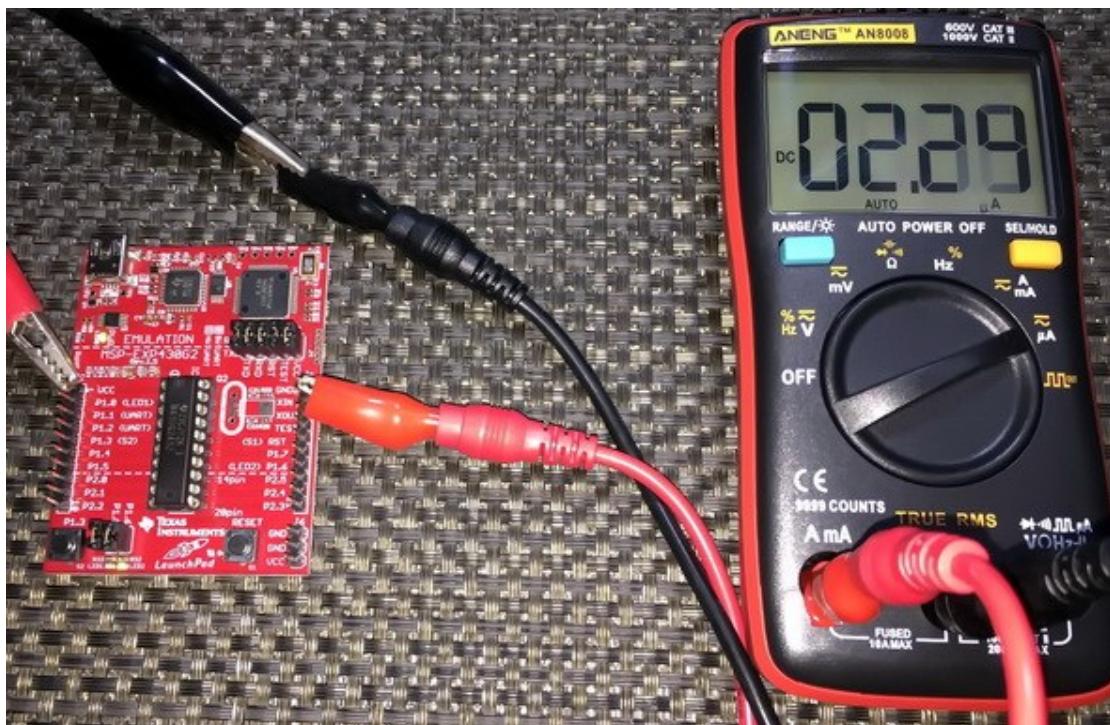
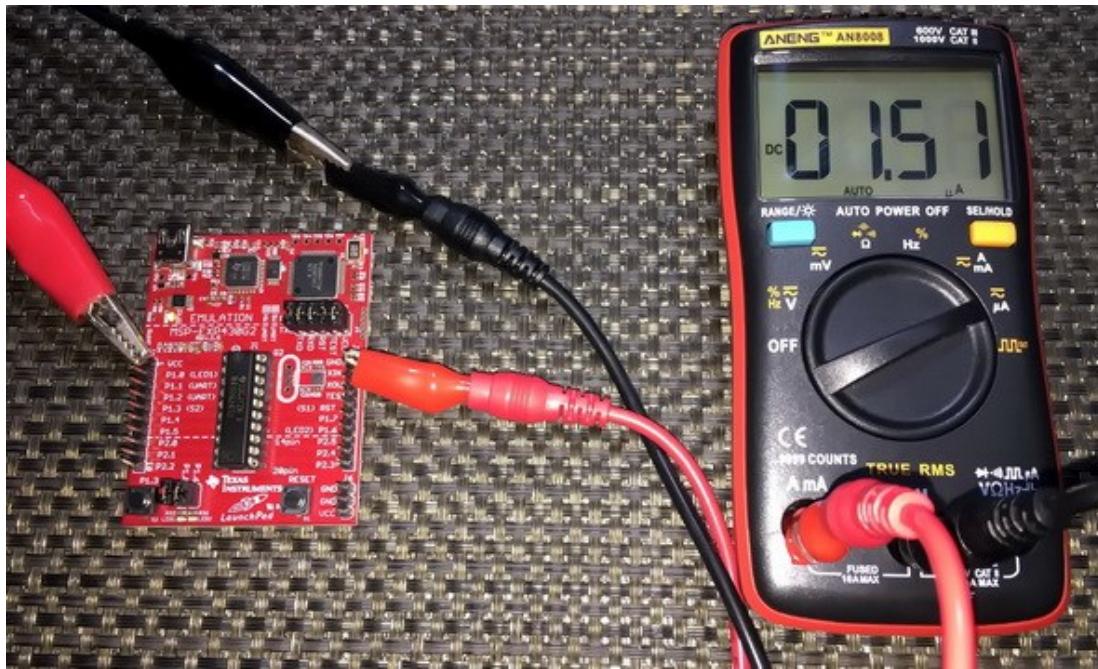
Message	Source	Time
PC=0x0000. [MSP430 CLOCK] Clock source DCO stop	U1 MCUCORE	
PC=0x0000. [MSP430 CLOCK] Clock source LFXT1 stop	U1 MCUCORE	
PC=0x0000. [MSP430 CLOCK] Clock source XT2 stop	U1 MCUCORE	
PC=0x0000. [MSP430 CLOCK] Clock source DCO stop	U1 MCUCORE	
PC=0x0000. [MSP430 CLOCK] Clock source LFXT1 stop	U1 MCUCORE	
PC=0x0000. [MSP430 CLOCK] Clock source XT2 stop	U1 MCUCORE	
PC=0x0000. [MSP430 CLOCK] Clock source DCO start	U1 MCUCORE	0.000006000s
PC=0x0000. [MSP430 CLOCK] DCO frequency = 0.08 MHz	U1 MCUCORE	0.000006000s
PC=0x0000. [MSP430 CLOCK] Clock source LFXT1 start	U1 MCUCORE	0.000006000s
PC=0x0000. [MSP430 CLOCK] Clock source XT2 start	U1 MCUCORE	0.000006000s
PC=0xC086. [MSP430 CLOCK] MOD = 0, DCO = 0, SEL = 7	U1 MCUCORE	0.000014208s
PC=0xC086. [MSP430 CLOCK] DCO frequency = 0.91 MHz	U1 MCUCORE	0.000014208s
PC=0xC086. [MSP430 CLOCK] Clock source DCO stop	U1 MCUCORE	0.000014208s
PC=0xC086. [MSP430 CLOCK] Clock source DCO start	U1 MCUCORE	0.000014208s
PC=0xC086. [MSP430 CLOCK] DCO frequency = 0.91 MHz	U1 MCUCORE	0.000014208s
PC=0xC08C. [MSP430 CLOCK] MOD = 0, DCO = 1, SEL = 7	U1 MCUCORE	0.000014708s
PC=0xC08C. [MSP430 CLOCK] DCO frequency = 0.99 MHz	U1 MCUCORE	0.000014708s
PC=0xC08C. [MSP430 CLOCK] Clock source DCO stop	U1 MCUCORE	0.000014708s
PC=0xC08C. [MSP430 CLOCK] Clock source DCO start	U1 MCUCORE	0.000014708s
PC=0xC08C. [MSP430 CLOCK] DCO frequency = 0.99 MHz	U1 MCUCORE	0.000014708s
PC=0xC092. [MSP430 CLOCK] Clock source XT2 stop	U1 MCUCORE	0.000015208s
PC=0xC098. [MSP430 CLOCK] Clock source LFXT1 stop	U1 MCUCORE	0.000015625s
PC=0xC098. [MSP430 CLOCK] Clock source VLO start	U1 MCUCORE	0.000015625s
PC=0xC03E. [MSP430 INTERRUPT] Handling IRQ_PORT1, address=0xC0CA.	U1 MCUCORE	0.698721864s
PC=0xC03E. [MSP430 INTERRUPT] IRQ_PORT1 completed.	U1 MCUCORE	0.698723531s
PC=0xC03E. [MSP430 INTERRUPT] Handling IRQ_PORT1, address=0xC0CA.	U1 MCUCORE	00:00:01.282947
PC=0xC03E. [MSP430 INTERRUPT] IRQ_PORT1 completed.	U1 MCUCORE	00:00:01.282949

Explanation

This is a pretty straight example. The code here works by first flashing the Launchpad board's red LED for some time. During this time the MSP430 is running in active mode. After the flashing is over, the MP430 micro enters LPM2 state. Note that in LPM2 state all except the DC generator and ACLK are turned off. At this stage to wake up and exit LPM2, an interrupt is needed. Here this interrupt is generated by the external interrupt caused by pressing the Launchpad board's user button. In the interrupt service routine (ISR), LPM2 is left and is indicated by a brief flash from the Launchpad board's green LED. After executing the ISR, the code returns to main function and the process repeats again.

Note that for LPMs, there is no segment in Grace and LPM code definitions can be found in device's header files.

Demo

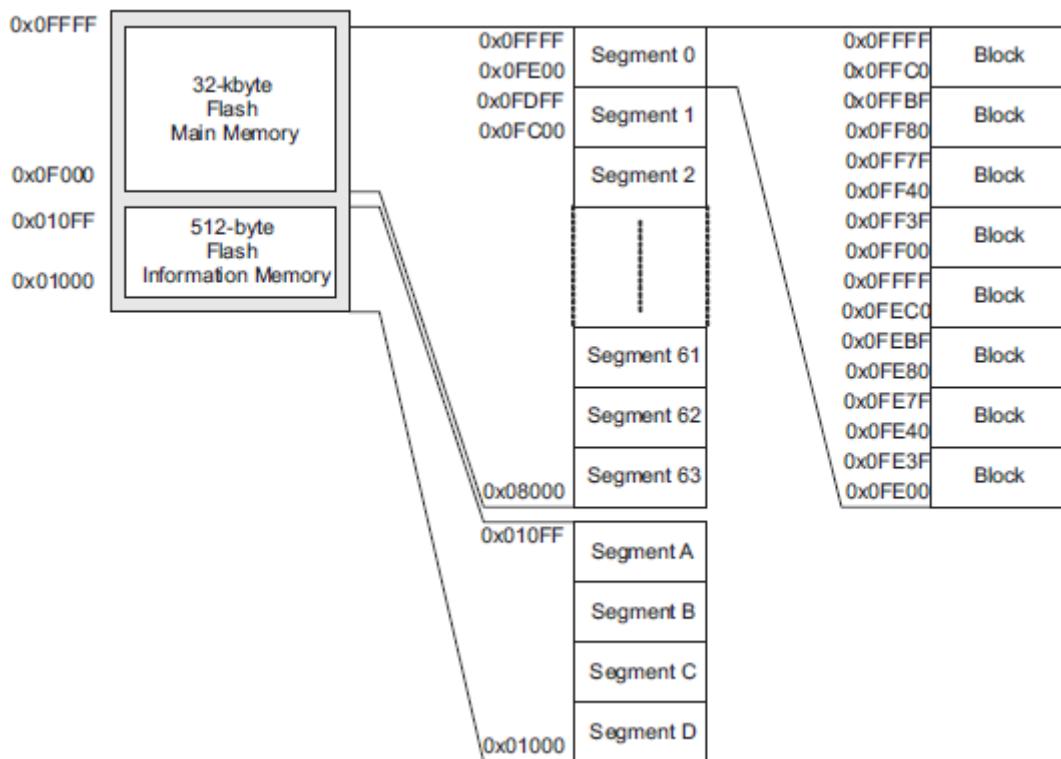


Demo video: <https://youtu.be/DSRTfoSNDlo>.

Internal Flash Memory

In some applications, there are some very important data that we wish to retain in our target device even when it is powered down. For such purposes we need a nonvolatile memory. Like many modern micros of today's market, MSP430s do not contain any separate EEPROM memory or battery-backed nonvolatile memory. For storing data like calibration data, settings, etc. that we would have saved in EEPROM memories, we can use the internal flash memory of our MSP430 devices. Though it may sound difficult and challenging, it is not so. However, we need to be very careful about storage locations as such that we don't accidentally use locations where application codes reside.

Shown below is a flash memory map example of a MSP430G2xxx device.



Note that there are four segments labelled A through D. These are the locations that we will be using for data storage and are called information memory. The rest is code space. We can also use the code space too but the code space has 512-byte segment size compared to 64-byte segment size of information memory. Now why is it so important to use information memory space instead of code memory? This is because of its small segment size. During memory erase, we have to erase a full segment. Bit, byte and word level read-write operations can be done easily but erasing is not possible at these levels. Two separate segments can be used to emulate low level erase. When such mechanism is applied. One segment acts like a buffer while the other is used for actual storage. Wear-leveling may optionally be applied. However, these processes add delays and extra costing.

Segment A is a very important segment as it stores important internal calibration data like DCO frequency variables, etc. Thus, it is protected and locked separately. It will be wise to leave it and use the other three segments of information memory space to store data.

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"

void Flash_graceInit(void);
void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned char value);
void Flash_Erase(unsigned int address);
void Flash_Write_Char(unsigned int address, char value);
char Flash_Read_Char(unsigned int address);
void Flash_Write_Word(unsigned int address, unsigned int value);
unsigned int Flash_Read_Word(unsigned int address);

void main(void)
{
    unsigned char value = 0x00;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430F2xx Flash Memory Controller */
    Flash_graceInit();

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    LCD_init();
    LCD_clear_home();

    LCD_goto(0, 0);
    LCD_putstr("MSP430 Flash Ex.");

    value = Flash_Read_Char(0x1000);

    LCD_goto(0, 1);
    LCD_putstr("WR: ---");
    LCD_goto(9, 1);
    LCD_putstr("RD:");
    lcd_print(13, 1, value);
    delay_ms(2000);
```

```

while(1)
{
    if((P1IN & BIT3) == !BIT3)
    {
        while((P1IN & BIT3) == !BIT3);
        Flash_Erase(0x1000);
        Flash_Write_Char(0x1000, value);
        lcd_print(13, 1, value);
        P1OUT |= BIT0;
        _delay_cycles(40000);
        P1OUT &= ~BIT0;
    }

    delay_ms(20);
    lcd_print(4, 1, value);

    value++;
    delay_ms(200);
}
}

void Flash_graceInit(void)
{
/* USER CODE START (section: Flash_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: Flash_graceInit_prologue) */

/*
 * Flash Memory Control Register 2
 *
 * FSSEL_1 -- MCLK
 * ~FN5 -- Flash controller clock divider bit 5
 * FN4 -- Flash controller clock divider bit 4
 * ~FN3 -- Flash controller clock divider bit 3
 * FN2 -- Flash controller clock divider bit 2
 * ~FN1 -- Flash controller clock divider bit 1
 * FN0 -- Flash controller clock divider bit 0
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
FCTL2 = FWKEY | FSSEL_1 | FN4 | FN2 | FN0;

/* USER CODE START (section: Flash_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Flash_graceInit_epilogue) */
}

void GPIO_graceInit(void)
{
/* USER CODE START (section: GPIO_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = BIT3;
}

```

```

/* Port 1 Direction Register */
P1DIR = BIT0;

/* Port 1 Resistor Enable Register */
P1REN = BIT3;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF) {
        /* Adjust this accordingly to your VCC rise time */
        delay_cycles(100000);
    }
}

```

```

    // Follow recommended flow. First, clear all DCOx and MODx bits. Then
    // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_8MHZ;           /* Set DCO to 8MHz */
    DCOCTL = CALDCO_8MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    __bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

```

```

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned char value)
{
    char chr = 0x00;

    chr = ((value / 100) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(chr);

    chr = (((value / 10) % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(chr);

    chr = ((value % 10) + 0x30);
    LCD_goto((x_pos + 2), y_pos);
    LCD_putchar(chr);
}

void Flash_Erase(unsigned int address)
{
    char *FlashPtr;

    FlashPtr = (char *)address;
    FCTL1 = FWKEY + ERASE;                                // Set Erase bit
    FCTL3 = FWKEY;                                         // Clear Lock bit
    __bic_SR_register(GIE);                               // Disable Interrupts
    *FlashPtr = 0;                                         // Dummy write to erase Flash
segment B
    while((FCTL3 & BUSY) == BUSY);                      // Busy
}

```

```

__bis_SR_register(GIE);                                // Enable Interrupts
FCTL1 = FWKEY;                                         // Lock
FCTL3 = FWKEY + LOCK;                                  // Set Lock bit
}

void Flash_Write_Char(unsigned int address, char value)
{
    char *FlashPtr = (char *)address;

    FCTL1 = FWKEY + WRT;                                // Set WRT bit for write operation
    FCTL3 = FWKEY;                                         // Clear Lock bit
    __bic_SR_register(GIE);                             // Disable Interrupts
    *FlashPtr = value;                                    // Save Data
    while((FCTL3 & BUSY) == BUSY);                     // Busy
    __bis_SR_register(GIE);                             // Enable Interrupts
    FCTL1 = FWKEY;                                         // Clear WRT bit
    FCTL3 = FWKEY + LOCK;                                // Set LOCK bit
}

char Flash_Read_Char(unsigned int address)
{
    char value = 0x00;
    char *FlashPtr = (char *)address;

    value = *FlashPtr;

    return value;
}

void Flash_Write_Word(unsigned int address, unsigned int value)
{
    unsigned int *FlashPtr = (unsigned int *)address;

    FCTL1 = FWKEY + WRT;                                // Set WRT bit for write operation
    FCTL3 = FWKEY;                                         // Clear Lock bit
    __bic_SR_register(GIE);                             // Disable Interrupts
    *FlashPtr = value;                                    // Save Data
    while((FCTL3 & BUSY) == BUSY);                     // Busy
    __bis_SR_register(GIE);                             // Enable Interrupts
    FCTL1 = FWKEY;                                         // Clear WRT bit
    FCTL3 = FWKEY + LOCK;                                // Set LOCK bit
}

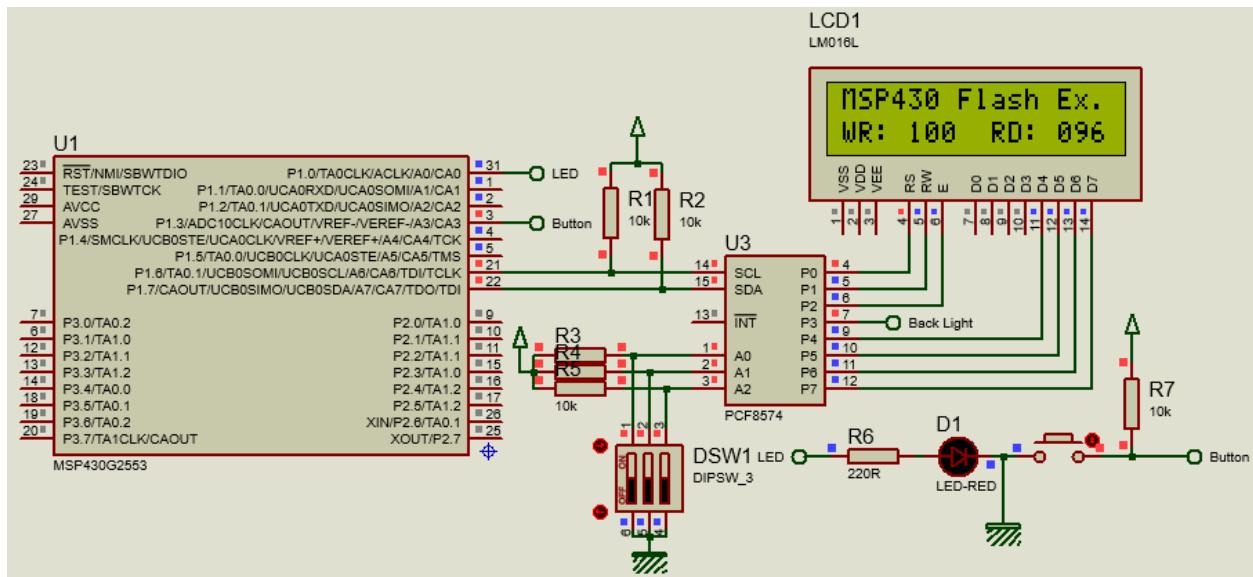
unsigned int Flash_Read_Word(unsigned int address)
{
    unsigned int value = 0x0000;
    unsigned int *FlashPtr = (unsigned int *)address;

    value = *FlashPtr;

    return value;
}

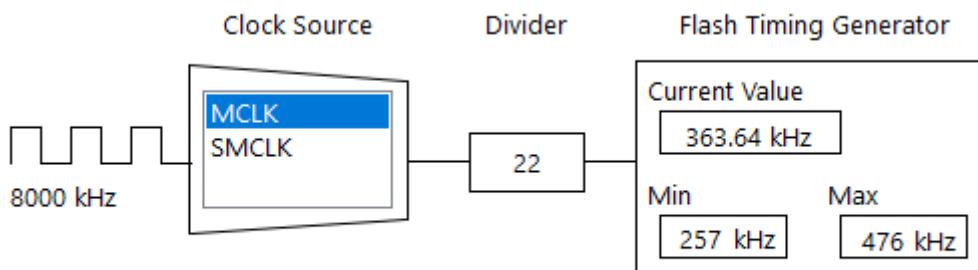
```

Simulation



Explanation

The flash memory module of MSP430s has an integrated controller that controls programming and erase operations. The controller has four registers, a timing generator, and a voltage generator to supply program and erase voltages.



Interrupt Enables

Flash Ctrl Access Violation Int Enable

[Generate Interrupt Handler Code](#)

[View All Interrupt Handlers](#)

Note 1: Min and Max values for Flash Timing Generator are from datasheet.

Note 2: By enabling the interrupt handler, Grace generates a fully working interrupt service routine in `InterruptVectors_init.c` file inside `src` folder. User could insert code inside the specified area of the ISR and the code is preserved. When a user disables the interrupt handler, the user's inserted code remains at the bottom of the file which is automatically re-inserted if the user re-enables the interrupt handler. User could also manually remove the code when it is no longer needed.

Using Grace, we initialize the aforementioned:

```
FCTL2 = FWKEY | FSSEL_1 | FN4 | FN2 | FN0;
```

To write a byte, we need two things – memory location and the value we wish to write. This memory location is that piece of memory space where we wish to store the value.

```
void Flash_Write_Char(unsigned int address, char value)
{
    char *FlashPtr = (char *)address;

    FCTL1 = FWKEY + WRT;                                // Set WRT bit for write operation
    FCTL3 = FWKEY;                                     // Clear Lock bit
    __bic_SR_register(GIE);                            // Disable Interrupts
    *FlashPtr = value;                                 // Save Data
    while((FCTL3 & BUSY) == BUSY);                   // Busy
    __bis_SR_register(GIE);                            // Enable Interrupts
    FCTL1 = FWKEY;                                     // Clear WRT bit
    FCTL3 = FWKEY + LOCK;                             // Set LOCK bit
}
```

Firstly, the address of the memory location where data is to be stored is pointed out. Flash write process starts by setting the write bit, followed by removing the flash protection. Once these are done, all interrupts are temporarily disabled to avoid any accidental write or illegal operation. The value to be written is then pointed. Until the value is successfully written all other processes are halted. Once the value to be stored is successfully written, interrupts are enabled, the write bit is cleared and the flash lock is applied.

Reading the flash is simpler. We just have to point the location we wish to read.

```
char Flash_Read_Char(unsigned int address)
{
    char value = 0x00;
    char *FlashPtr = (char *)address;

    value = *FlashPtr;

    return value;
}
```

The process for erasing is similar to write processes. The only difference is Erase bit instead of Write bit.

```
void Flash_Erase(unsigned int address)
{
    char *FlashPtr;

    FlashPtr = (char *)address;
    FCTL1 = FWKEY + ERASE;                           // Set Erase bit
    FCTL3 = FWKEY;                                  // Clear Lock bit
    __bic_SR_register(GIE);                         // Disable Interrupts
    *FlashPtr = 0;                                   // Dummy write to erase Flash
segment B
    while((FCTL3 & BUSY) == BUSY);                 // Busy
    __bis_SR_register(GIE);                         // Enable Interrupts
    FCTL1 = FWKEY;                                 // Lock
    FCTL3 = FWKEY + LOCK;                          // Set Lock bit
}
```

The same read-write processes can also be applied to read/write word-level values.

The code demoed here works by reading the last data stored in the target flash location (0x1000) and incrementing a variable named **value**. Only this location is read and updated when the Launchpad board's button is pressed.

Demo



Demo video: https://youtu.be/o_LUBiWJ5Og.

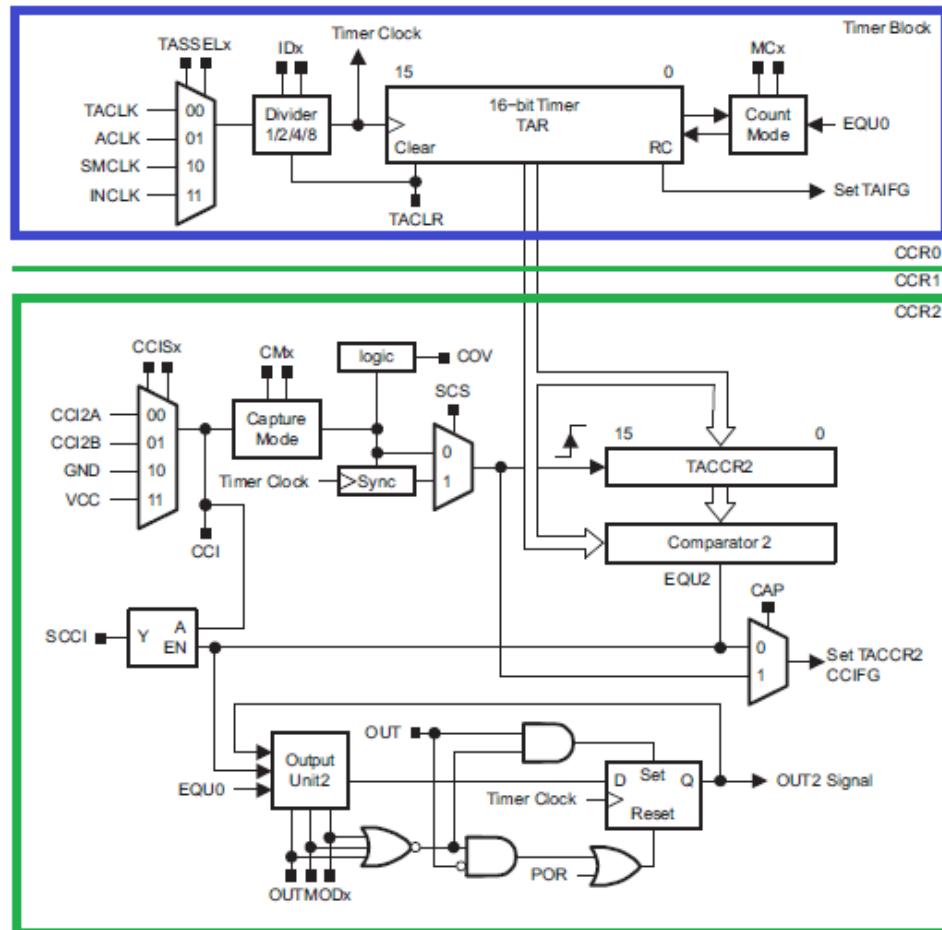
Timer Overview

There are several types of timers in MSP430 micros. These include **Watchdog Timer (WDT)**, **Real Time Clock (RTC)**, **Basic Timer 1 and Timer A** and **Timer B**. Timer As and Bs are general purpose 16-bit timers that are suitable for time base generations, pulse width modulations (PWM) and input captures. The other three types have special uses and their names suggest their purposes. All MSP430 devices have at least one Timer A module and a WDT module. Since both are common amongst all devices, we will be studying about them here. Timer As and Bs are almost same. The difference between the two is the presence of some additional features like more **Capture/Compare (CC)** channels in Timer Bs.

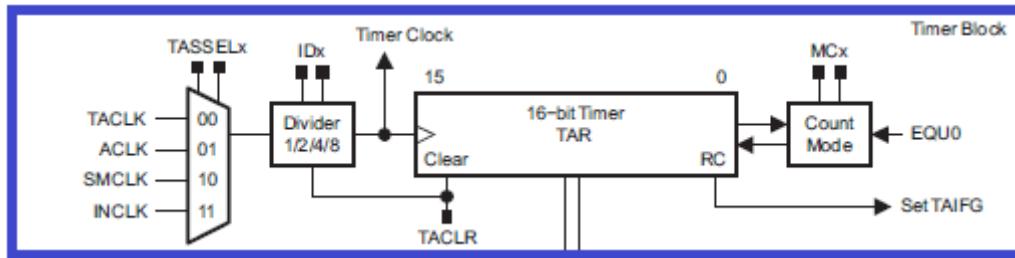
Timer A

In TI's literature, timers are named like **Timer0_A3**, **Timer_B7**, etc. A number can be present right after the word **Timer** in some case and in other cases, it may be absent. This number is present whenever there are multiple timers of same type in a MSP430 micro. For example, there are two Timer A3s in MSP430G2553 micros and so they are labelled as **Timer0_A3** and **Timer1_A3**. The other number in the timer's name after the timer type letter denotes the number of CC channels available with it.

Shown below is the block diagram of Timer A module. MSP430G2452 has one and MSP430G2553 has two Timer A3 modules. Typically, in any micro's timer we would expect two things - first a counter block (highlighted in purple) and second CC modules (highlighted in green). As we can see the CC channels share the same TAR register and so they share the similar properties.



The diagram below shows that clock sources we can use for a Timer A module. It can be clocked with two internal clock sources – ACLK and SMCLK or with two external clock sources – TACLK and INCLK. Actually, INCLK and TACLK are same but one is complementary of the other. These external clocks can be used to make the timer module work as counter.

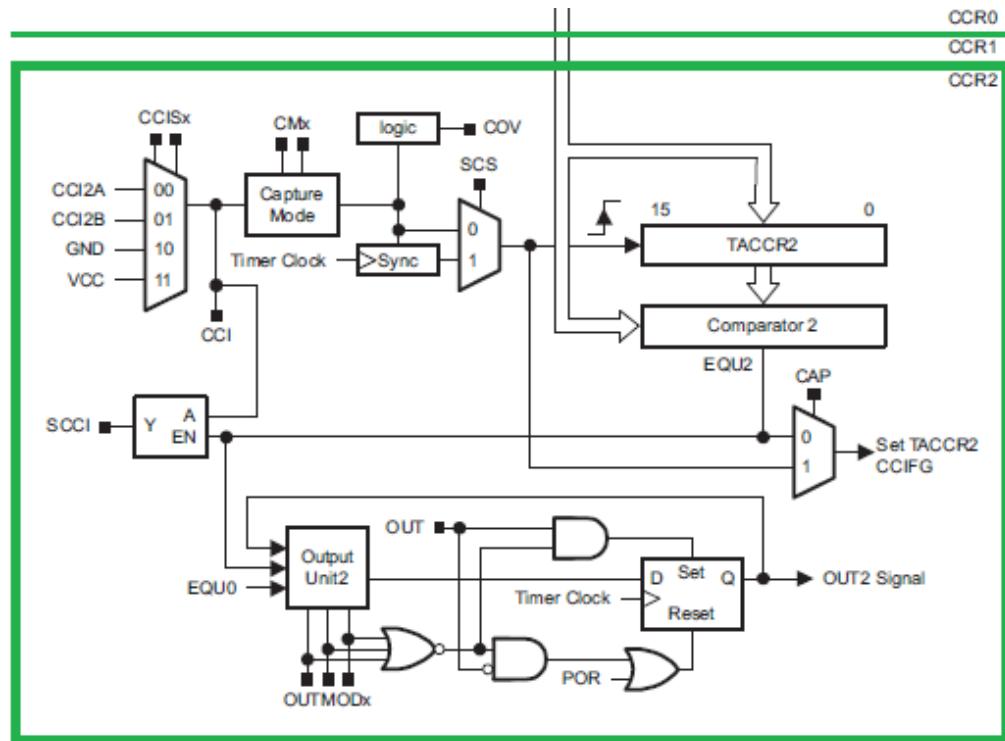


Next, we have a prescaler to scale down selected clock source followed by the counter block. What's interesting about MSP430 timers is the counter's mode of operation. There are four modes of counter operation and these modes define counting direction:

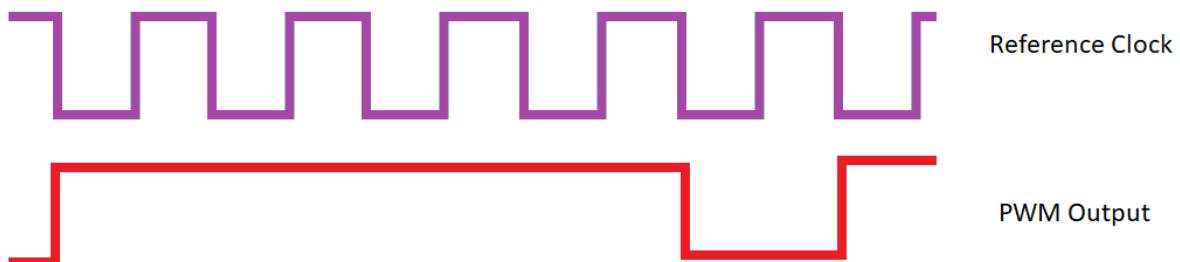
- **Stop Mode**
It is basically a hold state. All timer registers are retained and the timer is halted.
- **Continuous Mode**
In this mode, the timer counts up from 0 to top value (here 0xFFFF or 65535 in 16-bit Timer A3) and then rolls over to zero.
- **Up Mode**
This mode is same as continuous mode except for the top value. The top value of the timer is set by the value in TACCR0.
- **Up/Down Mode**
In this mode, the timer counts from 0 to TACCR0 value and then rolls back from that value to 0. The period of the timer is twice the TACCR0 counts.

Then we have timer interrupt just as in any other microcontroller.

MSP430G2452 has one Timer A3 module and so it has three CC channels. Likewise, MSP430G2553 has six CC channels. When it comes to extreme engineering, TI sometimes seems to overengineer their products. For example, CC channels are not hard fixed to dedicated pins only unlike other micros. Each CC channel has a set of pins associated with it and so they can be remapped if needed. Shown below is the block diagram of a Timer A3 CC channel. The left side of the diagram has all the components for input capture while the right side is intended for compare-match or PWM output. Common to both is the **TACCRn** block. It is a very important block.

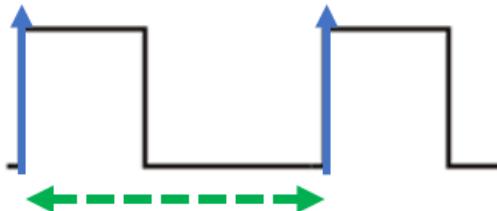


The basic theme of PWM generation as with any microcontroller is to change the logic state of an output pin when the count in its associated TACCR register matches with the count in its timer's counter register – simply like a binary comparator. This process is called **compare-match** process. This is exactly the same idea used in MSP430s. Check the rudimentary timing diagram below. For five successive falling edges of the reference clock, the PWM output is high and for one edge, the output is low, resulting in about 83% duty cycle. The reference clock here is actually the timer clock and the comparison is done by comparing the count stored in TACCRn. Varying TACCRn's count results in duty cycle change.



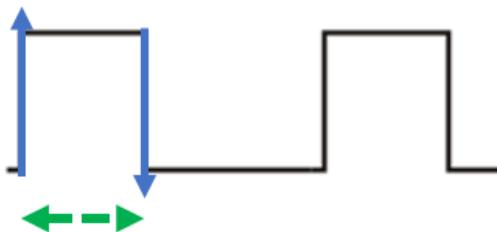
Input capture is somewhat just the opposite of PWM generation. In capture mode, CC channels can be used to record time-related info of an incoming waveform. A timer in this mode can be left to run on its own. When a waveform edge is detected, the corresponding time count of the timer is stored in CC register. With two such consecutive captures, we get a difference in timer's time counts. This difference can be used to measure frequency if the captured events are alike (two successive rising/falling edges) or duty cycle if the captured events are different (different edges). Again, TACCRn stores the time capture when a capture event occurs.

Frequency Capture



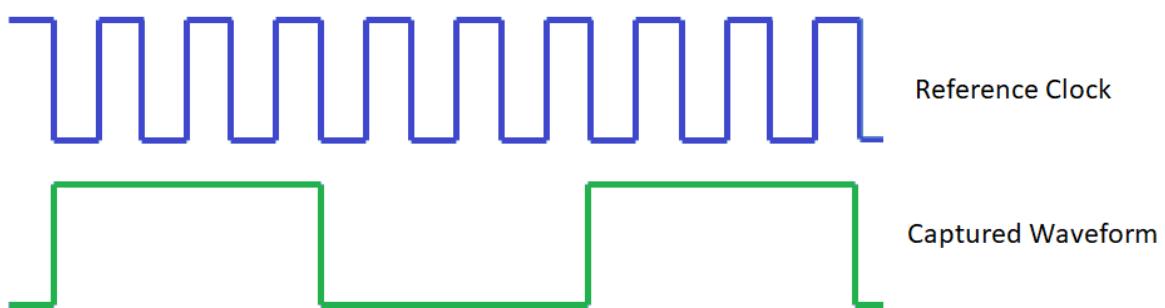
Capturing two same successive edge gives frequency readout

Duty Cycle Capture



Capturing two different successive edge gives duty cycle readout

As an example, check the arbitrary timing diagram below:

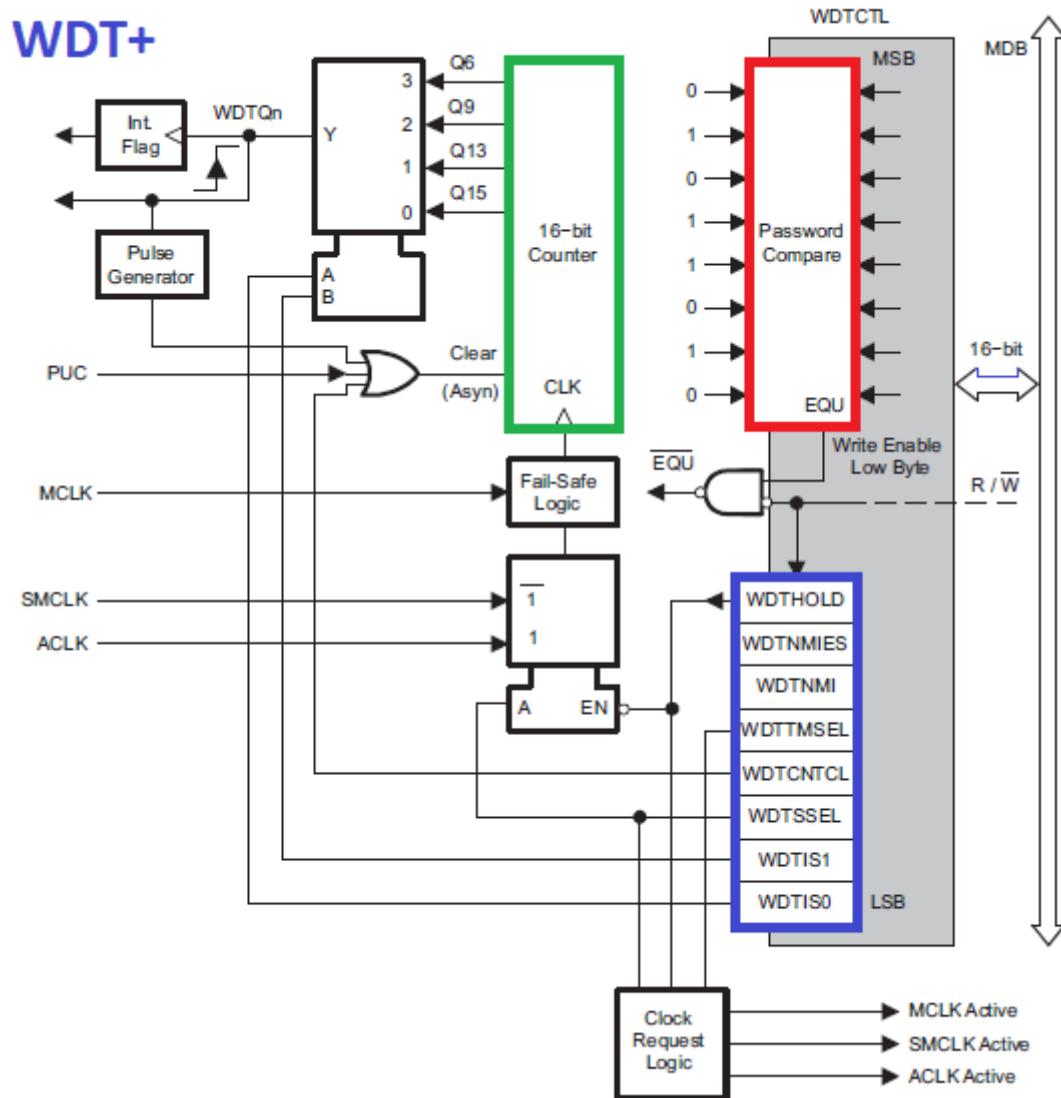


Here four falling edges of reference clock (timer clock) is equal to the high or on time of the captured waveform. Since the reference clock's period is known, we can deduce pulse width.

WDT+

WDT+ is a 15/16-bit watchdog timer. It is mainly intended to prevent unanticipated loops or stuck up conditions due to malfunctions or firmware bugs. The concept behind any watchdog timer is to regularly refresh a counter so that the count never reaches a predefined limit. If due to any reason this limit is exceeded, a reset is issued, causing the host micro to start over again.

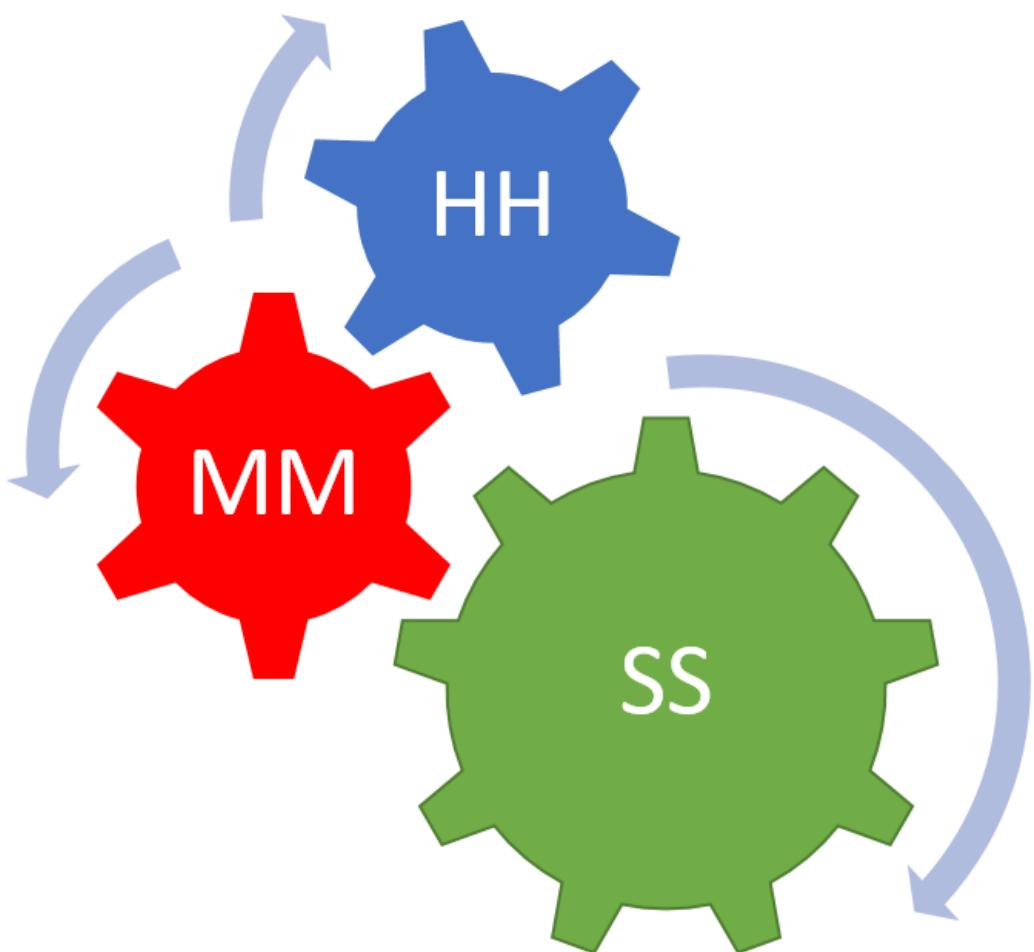
WDT+ can additional be used as an interval timer just like other timers if watchdog timer functionality is not needed. We can, then, use WDT+ for time-base generations.



WDT+ is password protected and so a wrong password causes it to fail and reset immediately. This is the red box in the diagram above. Whenever we need to change anything related to WDT+, we have to enter the correct password which is 0x5A00. WDT+ consists of a 16-bit counter (green box) but we don't have access to it. The purple region consists of WDT options. The red and the purple boxes make up **Watchdog Control (WDTCTL)** register and this is what we are only allowed to code.

Free Running Timer

Free running timers are useful in many cases. Free running timers can be used as random number generators, time delay generators, instance markers, etc. Consider the case of time delay generation for instance. Rather than using wasteful CPU-cycle dependent software delay loops, it is much wiser to use a hardware timer to create precise delays and timed events. In terms of ideal coding, no task should keep CPU busy unnecessarily nor should it keep other tasks waiting for its completion. Best coding and design are achieved if things are arranged in such an orderly way that there is almost no wastage of any resource at all.



By free-running what I really mean is we start a timer at the beginning of our code and keep it running without timer interrupt. We just take note of its counter. Here we will see how to use Timer_A3 like a free running timer and we will use it to blink Launchpad board's LEDs.

Code Example

```
#include <msp430.h>

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void Timer0_A3_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

#pragma vector=TIMER0_A1_VECTOR
__interrupt void TIMER0_A1_ISR_HOOK(void)
{

}

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 A3 Timer0 */
    Timer0_A3_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        if(TA0R >= 32768)
        {
            P1OUT |= BIT6;
            P1OUT &= ~BIT0;
        }

        else
        {
            P1OUT |= BIT0;
            P1OUT &= ~BIT6;
        }
    };
}

void BCSplus_graceInit(void)
{
```

```

/* USER CODE START (section: BCSplus_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: BCSplus_graceInit_prologue) */

/*
 * Basic Clock System Control 2
 *
 * SELM_0 -- DCOCLK
 * DIVM_0 -- Divide by 1
 * ~SELS -- DCOCLK
 * DIVS_0 -- Divide by 1
 * ~DCOR -- DCO uses internal resistor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */
}

```

```

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT6;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO0_graceInit_epilogue) */
}

void Timer0_A3_graceInit(void)
{
    /* USER CODE START (section: Timer0_A3_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: Timer0_A3_graceInit_prologue) */

    /*
     * TA0CTL, Timer_A3 Control Register
     *
     * TASSEL_2 -- SMCLK
     * ID_3 -- Divider - /8
     * MC_2 -- Continuous Mode
     */
    TA0CTL = TASSEL_2 | ID_3 | MC_2;

    /* USER CODE START (section: Timer0_A3_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: Timer0_A3_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */
}

```

```

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
__bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

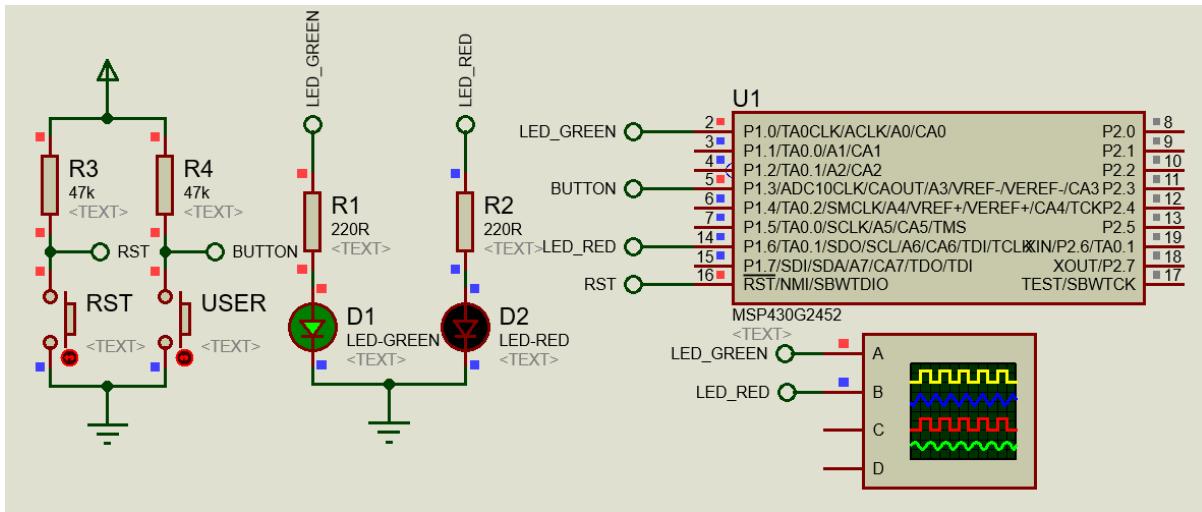
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

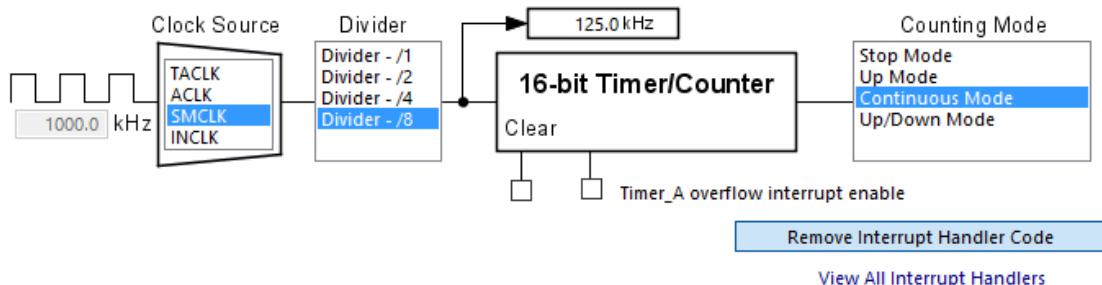
```

Simulation



Explanation

In this demo, Timer_A3 is clocked with SMCLK divided by 8. SMCLK has a frequency of 1MHz and so Timer_A3 is feed with a 125kHz clock. This gives us a timer tick period of 8 microseconds. Since the timer is programmed to operate in continuous mode, i.e. it will count from 0 to top value of 65535, the timer will overflow roughly about every 500 milliseconds. We, thus, have an interval window of 500 milliseconds.



Timer Capture/Compare Block #0

Desired Timer Period:	524.28 ms	Time(r) Period	524.3 ms	
Capture Register:	0	Clock Ticks	Time(r) Frequency	1.9 Hz
Input Selection	CC Input OFF P1.1/TA0.CCI0A GND VCC	Capture Mode	Mode	Output Pins
	No Capture Rising Edge Falling Edge Both Edges	Timer OFF Output Compare/Period Input Capture		TA0.0 Output OFF P1.1/TA0.0 P1.5/TA0.0
Output Mode:	PWM output mode: 0 - OUT bit value	<input type="checkbox"/> Set OUT bit High/Low		

Interrupt Enables

Capture/compare interrupt enable 0

[View All Interrupt Handlers](#)

```

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_3 -- Divider - /8
 * MC_2 -- Continuous Mode
 */
TA0CTL = TASSEL_2 | ID_3 | MC_2;

```

We want to blink the Launchpad board's LEDs at the rate of 250 milliseconds. Thus, we need to check or compare if the counter register **TA0R** has gone past 50% of the full scale 16-bit value. This is an event marker because with reference to this mark, we toggle the states of the LEDs. The idea shown here is actually the concept with which PWMs are generated by compare-match principle inside timer hardware and so it is worth understanding this idea.

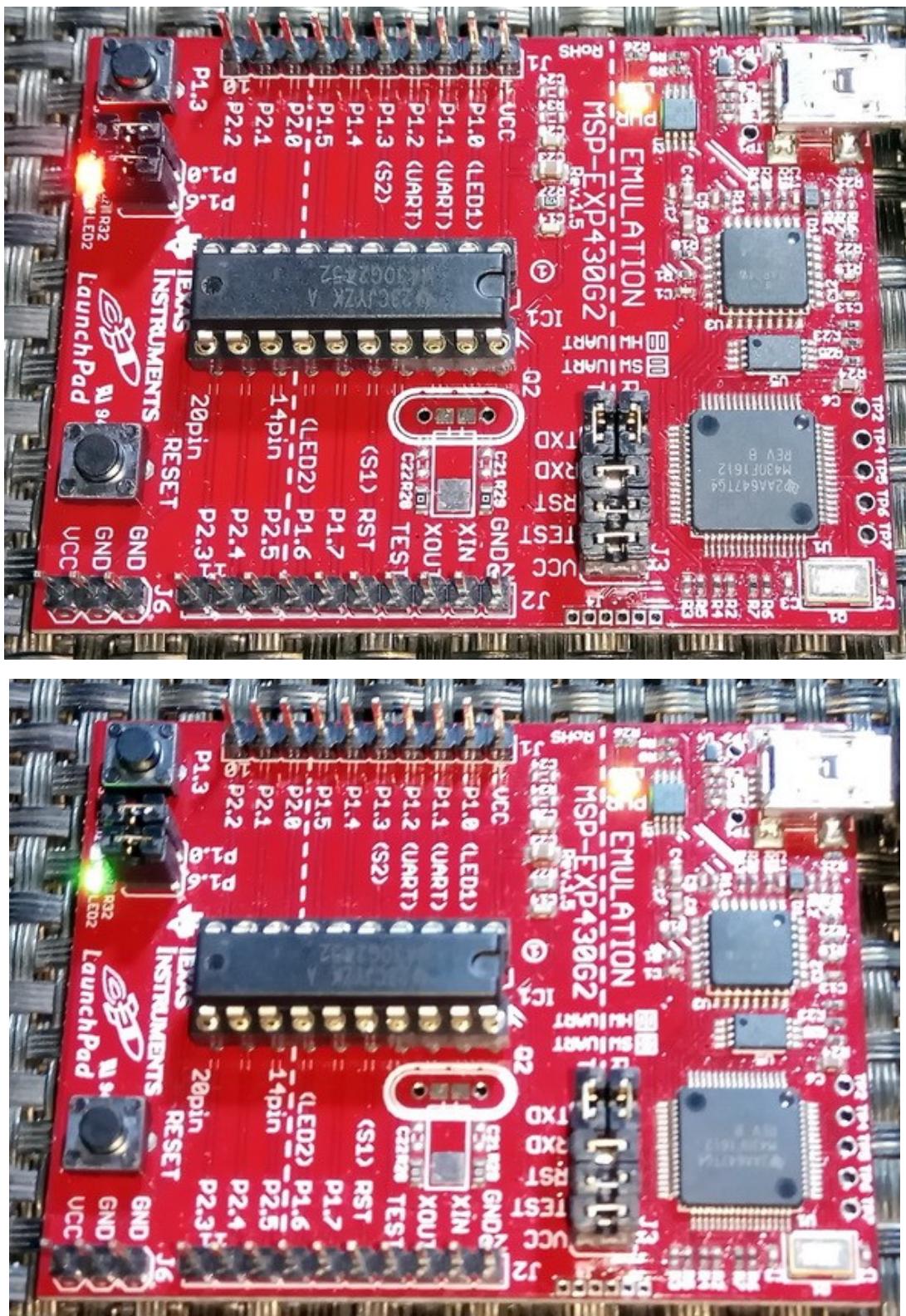
```

if(TA0R >= 32768)
{
    P1OUT |= BIT6;
    P1OUT &= ~BIT0;
}

else
{
    P1OUT |= BIT0;
    P1OUT &= ~BIT6;
}

```

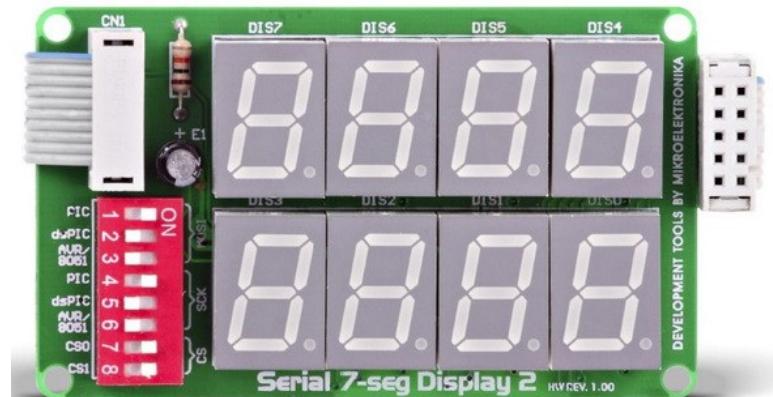
Demo



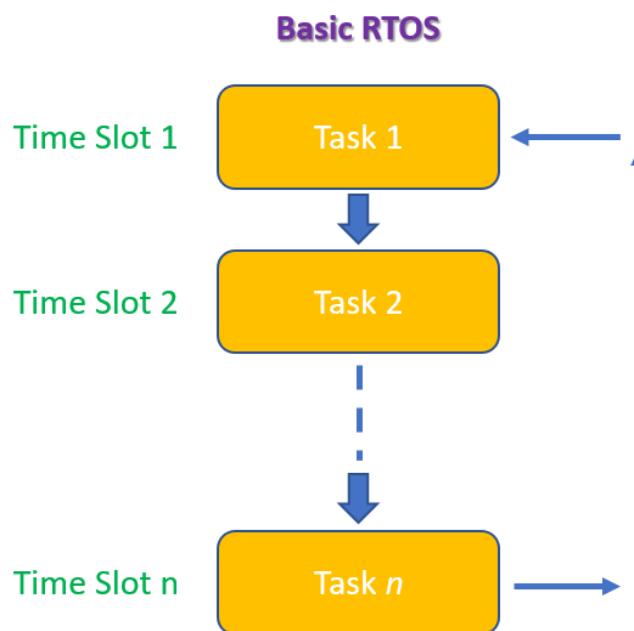
Demo video: <https://www.youtube.com/watch?v=OGvswRhb7ds>.

Timer Interrupt

We have already seen how to use a timer as a free-running timer. However, in most cases we will need timer interrupts. Timer interrupts are periodic interrupts which means they occur at fixed intervals just like clock ticks. Owing to this nature we can split multiple tasks and make them appear as if all of them are happening concurrently. For instance, we can use an ADC to measure the temperature of a room while using a timer to periodically update the temperature display. This is the main concept in driving segment displays, dot-matrix displays and many more although it is not the only thing we can do with timer interrupts.



A timer interrupt is also at the heart of any typical *Real-Time Operating System (RTOS)*.



Here we will stick to a simple example of a seven-segment display-based second counter. Rather than demoing LED blinking with timer interrupt I chose this example because this has many applications in the field of displaying information on LED-based displays. The same concept can be expanded for dot-matrix displays, LED bar graphs, alphanumeric segmented displays and many more.

Code Example

```
#include <msp430.h>

unsigned int ms = 0;
unsigned int value = 0;

unsigned char n = 0;
unsigned char seg = 0;
const unsigned char num[10] = {0xC0, 0xF9, 0xA4, 0xB0, 0x99, 0x92, 0x82, 0xF8,
0x80, 0x90};

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void Timer0_A3_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

#pragma vector=TIMER0_A1_VECTOR
__interrupt void TIMER0_A1_ISR_HOOK(void)
{
    ms++;
    if(ms > 999)
    {
        ms = 0;
        value++;

        if(value > 9999)
        {
            value = 0;
        }
    }
    switch(seg)
    {
        case 1:
        {
            n = (value / 1000);
            P2OUT = num[n];
            P1OUT = 0xE0;
            break;
        }

        case 2:
        {
            n = ((value / 100) % 10);
            P2OUT = num[n];
            P1OUT = 0xD0;
            break;
        }

        case 3:
        {
            n = ((value / 10) % 10);
            P2OUT = num[n];
            P1OUT = 0xB0;
        }
    }
}
```

```

        break;
    }

    case 4:
    {
        n = (value % 10);
        P2OUT = num[n];
        P1OUT = 0x70;
        break;
    }
}

seg++;
if(seg > 4)
{
    seg = 1;
}

TA0CTL &= ~TAIFG;
TAIV &= ~TA0IV_TAIFG;
}

void main(void)
{
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSpplus_graceInit();

    /* initialize Config for the MSP430 A3 Timer0 */
    Timer0_A3_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
    };
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Direction Register */
    P1DIR = BIT4 | BIT5 | BIT6 | BIT7;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;
}

```

```

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = BIT0 | BIT1 | BIT2 | BIT3 | BIT4 | BIT5 | BIT6 | BIT7;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF) {
        /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
         * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
         */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     */
}

```

```

/*
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void Timer0_A3_graceInit(void)
{
/* USER CODE START (section: Timer0_A3_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: Timer0_A3_graceInit_prologue) */

/* TA0CCR0, Timer_A Capture/Compare Register 0 */
TA0CCR0 = 999;

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_0 -- Divider - /1
 * MC_1 -- Up Mode
 */
TA0CTL = TASSEL_2 | ID_0 | MC_1 | TAIE;

/* USER CODE START (section: Timer0_A3_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Timer0_A3_graceInit_epilogue) */
}

void System_graceInit(void)
{
/* USER CODE START (section: System_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: System_graceInit_prologue) */

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable

```

```

/*
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
__bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue)
}

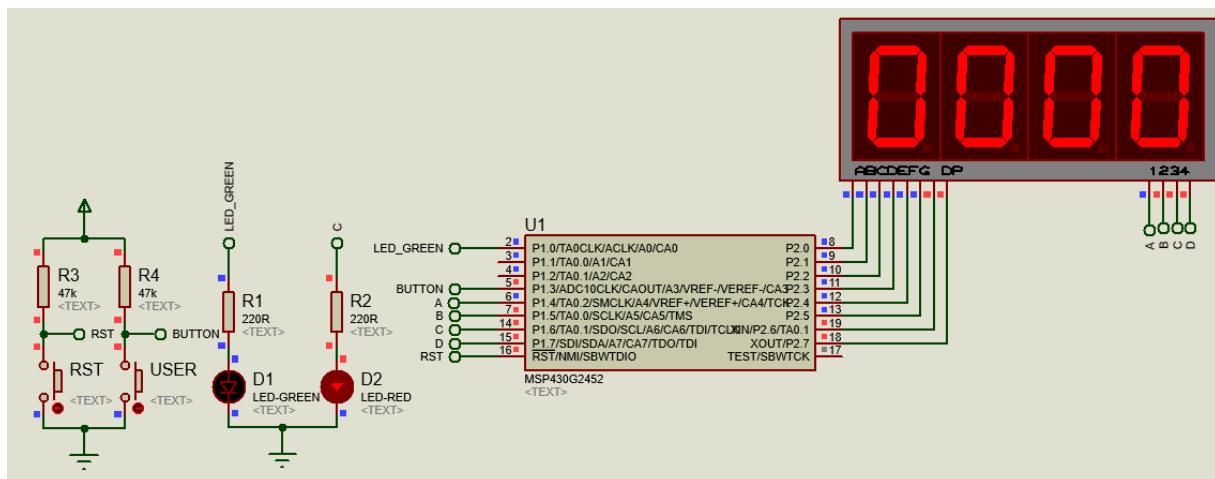
void WDTplus_graceInit(void)
{
/* USER CODE START (section: RTC_B_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: RTC_B_graceInit_prologue) */

/*
 * WDTCTL, Watchdog Timer+ Register
 *
 * WDTPW -- Watchdog password
 * WDTHOLD -- Watchdog timer+ is stopped
 * ~WDTNMIES -- NMI on rising edge
 * ~WDTNMI -- Reset function
 * ~WDTTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * ~WDTSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue)
}

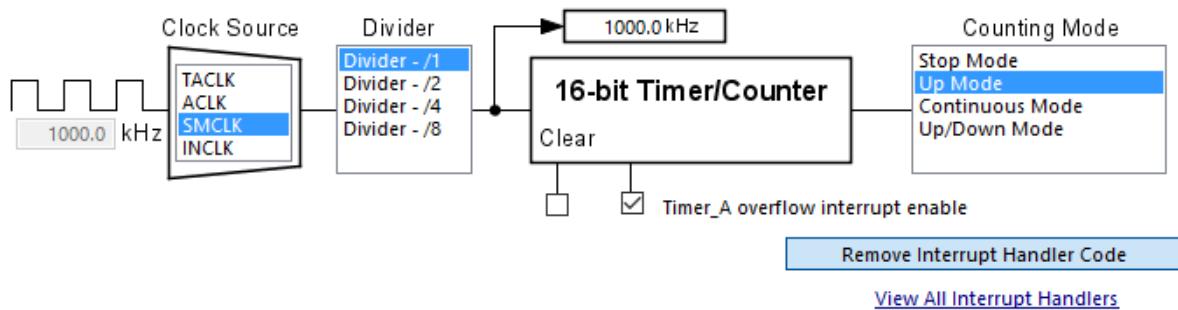
```

Simulation



Explanation

In this demo, Timer_A3 is configured as an up counting timer, i.e. it will count from 0 to a top value determined by the contents of **TA0CCR0** register. Again, SMCLK is used as the clock source for the timer but this time it is not scaled down. SMCLK is set to 1 MHz and so does Timer_A3. This means every one tick of Timer_A3 is one microsecond in duration. To make it appear that all four seven segments are simultaneously on without any flickering, we need to scan them fast enough to fool our eyes. We also have to ensure that each segment gets enough time to light up properly. In order to do so we need to scan the segments at one millisecond rate. To get one millisecond from a timer with one microsecond tick interval, we have to load it with 999, not 1000. This is so because from 0 to 999 the total number of ticks is 1000. In short, 1000 times 1 microsecond equals 1 millisecond. Thus, TA0CCR0 is loaded with 999.



Timer Capture/Compare Block #0

Desired Timer Period:	<input type="text" value="1.001"/> ms	Time(r) Period	1 ms
Capture Register:	<input type="text" value="1000"/> Clock Ticks	Time(r) Frequency	999 Hz
Input Selection	Capture Mode	Mode	Output Pins
<input type="checkbox"/> CCI Input OFF P1.1/TA0.CCI0A GND VCC	<input type="checkbox"/> No Capture Rising Edge Falling Edge Both Edges	<input type="checkbox"/> Timer OFF Output Compare/Period Input Capture	<input type="checkbox"/> TA0.0 Output OFF P1.1/TA0.0 P1.5/TA0.0
Output Mode:	<input type="button" value="PWM output mode: 0 - OUT bit value"/> <input type="checkbox"/> Set OUT bit High/Low		

Interrupt Enables

Capture/compare interrupt enable 0

[View All Interrupt Handlers](#)

```
/*
 * TA0CCR0, Timer_A Capture/Compare Register 0 */
TA0CCR0 = 999;

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_0 -- Divider - /1
 * MC_1 -- Up Mode
 */
TA0CTL = TASSEL_2 | ID_0 | MC_1 | TAIE;
```

Everything else in this demo is done inside Timer_A3 interrupt subroutine (ISR). There are two parts inside the ISR. The first as shown below is responsible for counting time.

```
ms++;
if(ms > 999)
{
    ms = 0;
    value++;

    if(value > 9999)
    {
        value = 0;
    }
}
```

The other portion is tasked with the LED segment scanning and data display part. At every millisecond, a new segment is turned on, keeping others off. At the end of the ISR, interrupt flags are cleared.

```
switch(seg)
{
    case 1:
    {
        n = (value / 1000);
        P2OUT = num[n];
        P1OUT = 0xE0;
        break;
    }

    case 2:
    {
        n = ((value / 100) % 10);
        P2OUT = num[n];
        P1OUT = 0xD0;
        break;
    }

    case 3:
    {
        n = ((value / 10) % 10);
        P2OUT = num[n];
        P1OUT = 0xB0;
        break;
    }

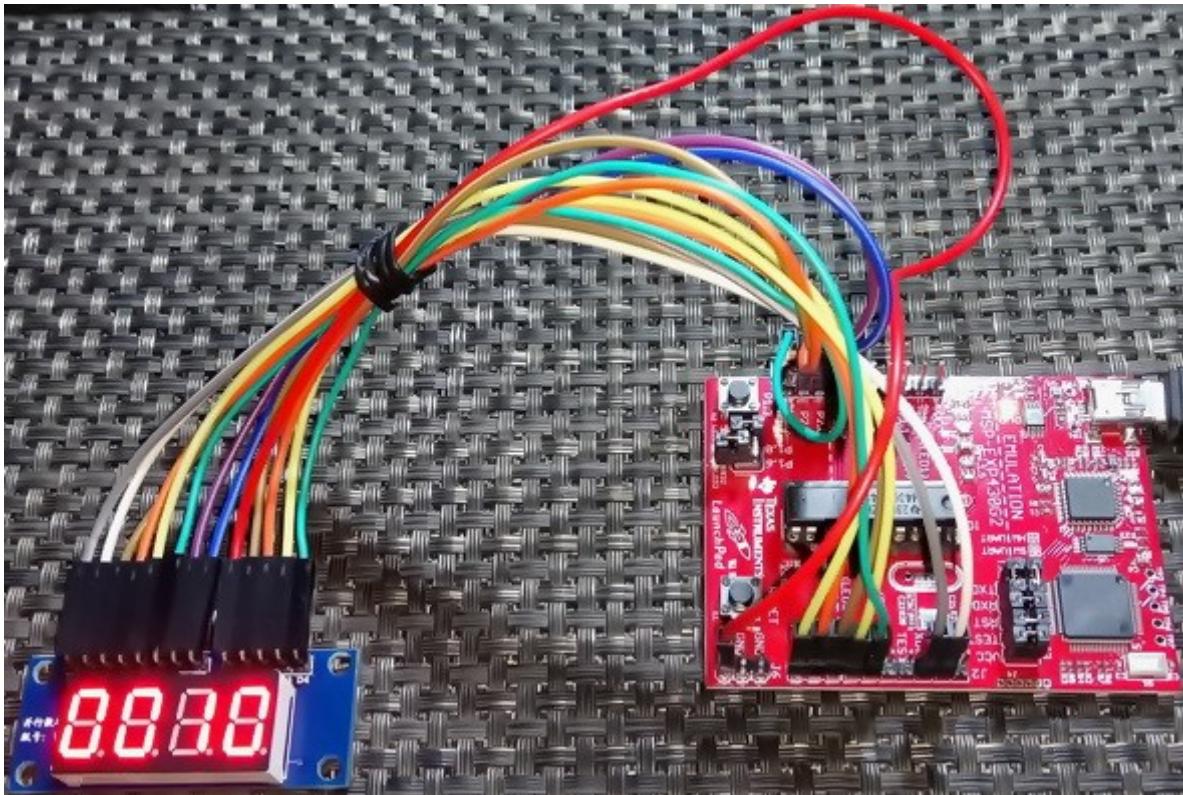
    case 4:
    {
        n = (value % 10);
        P2OUT = num[n];
        P1OUT = 0x70;
        break;
    }
}

seg++;
if(seg > 4)
{
    seg = 1;
```

```
}

TA0CTL &= ~TAIFG;
TAIV &= ~TA0IV_TAIFG;
```

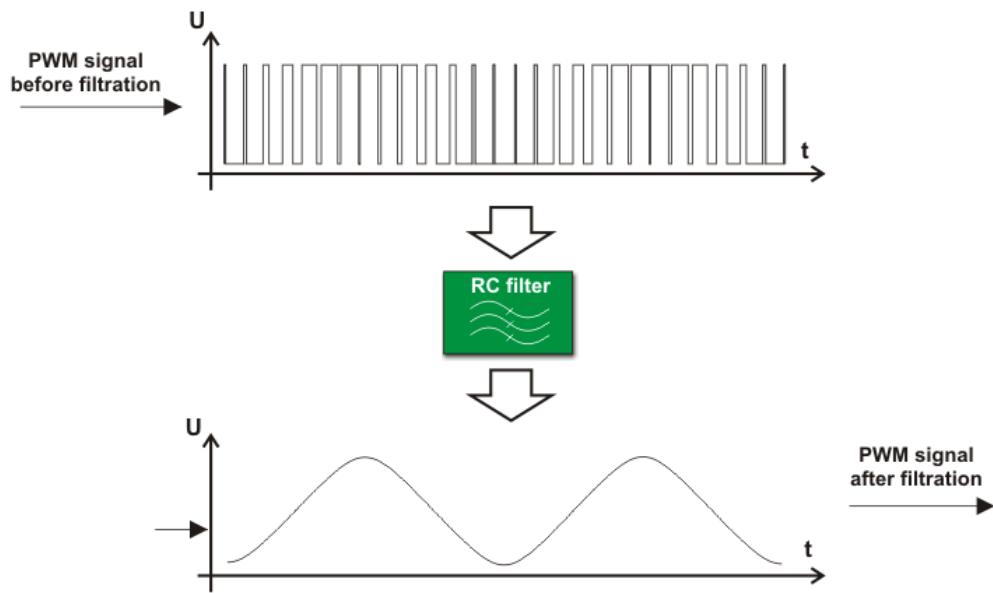
Demo



Demo video: <https://www.youtube.com/watch?v=8EG9rcOAATo>.

Pulse Width Modulation (PWM)

At present PWM hardware is a must for any microcontroller because in many cases, it is needed to extract something more than ones and zeros from it. For example, consider the case of a sine wave generator. Without the aid of a **Digital-to-Analog Converter (DAC)**, generating sine waves seems nearly impossible. However, we can still achieve that using **Pulse Width Modulation (PWM)** and some mathematical tricks.



Generating waveforms, pulses with variable widths, patterns, sounds, communications pulses like those in IR remotes, speed control, etc require PWM hardware. Keep in mind that all MSP30x2xxx devices do not have any inbuilt DAC and so if analogue output is needed, we can use PWM with necessary external RC filtering to create analogue output.

A few things must be observed before using MSP430 PWM hardware:

- Timer A PWMs are general purpose PWMs.
- There's no separate option for dead-time.
- Maximum PWM resolution is 16-bit.
- CC Channel 0 is not like the other two channels. It has limited output options and in GRACE you'll notice that you can't set PWM duty cycle.
- PWM frequency and resolution are interdependent.
- PWM pins are limitedly remappable.

Code Example

```
#include <msp430.h>
#include "delay.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void Timer0_A3_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

void main(void)
{
    unsigned int pwm_value = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 A3 Timer0 */
    Timer0_A3_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        for(pwm_value = 0; pwm_value < 1000; pwm_value++)
        {
            TA0CCR1 = pwm_value;
            TA0CCR2 = pwm_value;
            delay_ms(1);
        }
        for(pwm_value = 999; pwm_value > 0; pwm_value--)
        {
            TA0CCR1 = pwm_value;
            TA0CCR2 = pwm_value;
            delay_ms(1);
        }
    };
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */
}
```

```

/* Port 1 Port Select 2 Register */
P1SEL2 = BIT4;

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Port Select Register */
P1SEL = BIT1 | BIT4 | BIT6;

/* Port 1 Direction Register */
P1DIR = BIT1 | BIT4 | BIT6;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;
}

```

```

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;          /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void Timer0_A3_graceInit(void)
{
    /* USER CODE START (section: Timer0_A3_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: Timer0_A3_graceInit_prologue) */

    /*
     * TA0CCTL0, Capture/Compare Control Register 0
     *
     * CM_0 -- No Capture
     * CCIS_0 -- CCIxA
     * ~SCS -- Asynchronous Capture
     * ~SCCI -- Latched capture signal (read)
     * ~CAP -- Compare mode
     * OUTMOD_4 -- PWM output mode: 4 - Toggle
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    TA0CCTL0 = CM_0 | CCIS_0 | OUTMOD_4;

    /*
     * TA0CCTL1, Capture/Compare Control Register 1
     *

```

```

    * CM_0 -- No Capture
    * CCIS_0 -- CCIxA
    * ~SCS -- Asynchronous Capture
    * ~SCCI -- Latched capture signal (read)
    * ~CAP -- Compare mode
    * OUTMOD_3 -- PWM output mode: 3 - PWM set/reset
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
TA0CCTL1 = CM_0 | CCIS_0 | OUTMOD_3;

/*
 * TA0CCTL2, Capture/Compare Control Register 2
 *
 * CM_0 -- No Capture
 * CCIS_0 -- CCIxA
 * ~SCS -- Asynchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * ~CAP -- Compare mode
 * OUTMOD_7 -- PWM output mode: 7 - PWM reset/set
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
TA0CCTL2 = CM_0 | CCIS_0 | OUTMOD_7;

/* TA0CCR0, Timer_A Capture/Compare Register 0 */
TA0CCR0 = 999;

/* TA0CCR1, Timer_A Capture/Compare Register 1 */
TA0CCR1 = 10;

/* TA0CCR2, Timer_A Capture/Compare Register 2 */
TA0CCR2 = 10;

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_0 -- Divider - /1
 * MC_1 -- Up Mode
 */
TA0CTL = TASSEL_2 | ID_0 | MC_1;

/* USER CODE START (section: Timer0_A3_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Timer0_A3_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
do
{
    // Clear OSC fault flag
}

```

```

    IFG1 &= ~OFIFG;

    // 50us delay
    __delay_cycles(50);
} while (IFG1 & OFIFG);

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
__bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

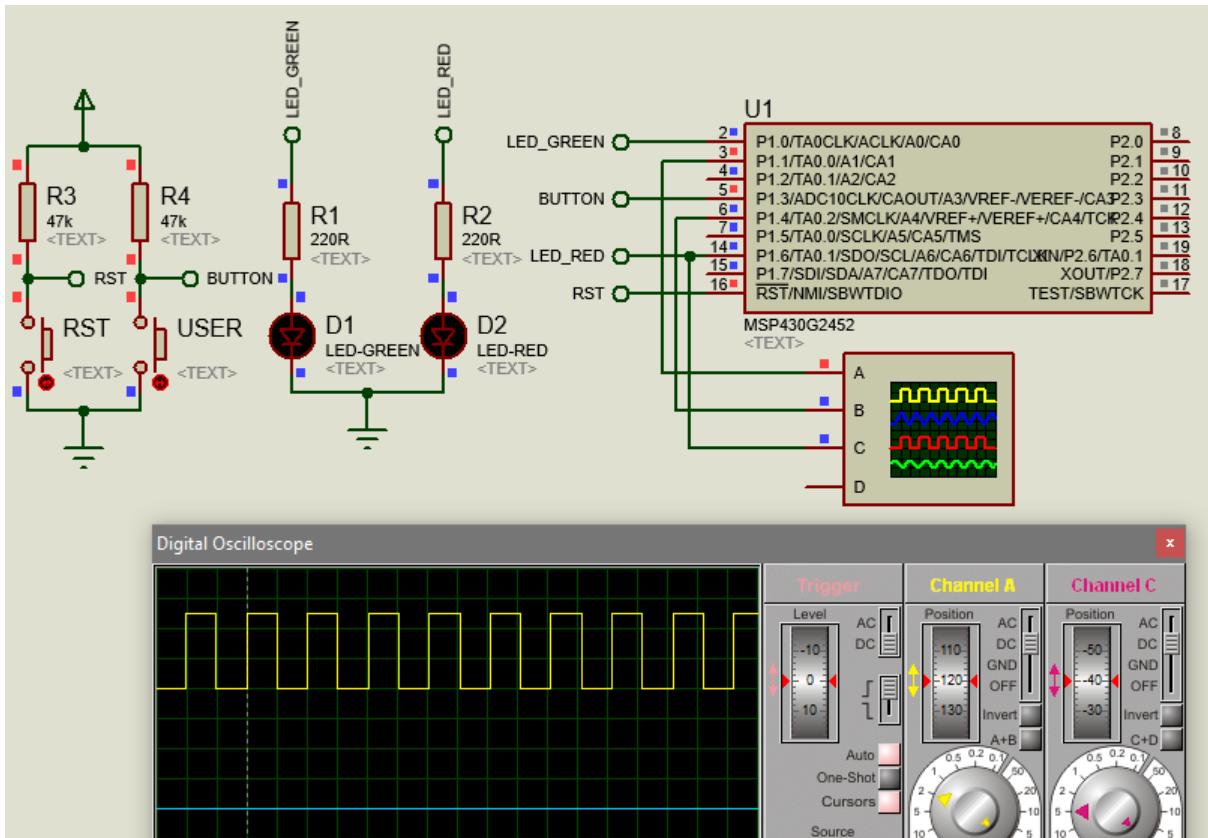
void WDTplus_graceInit(void)
{
/* USER CODE START (section: RTC_B_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: RTC_B_graceInit_prologue) */

/*
 * WDTCTL, Watchdog Timer+ Register
 *
 * WDTPW -- Watchdog password
 * WDTHOLD -- Watchdog timer+ is stopped
 * ~WDTNMIES -- NMI on rising edge
 * ~WDTNMI -- Reset function
 * ~WDTTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * ~WDTSSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation



Explanation

Just as in the previous example, SMCLK is set to 1MHz. Timer_A3 is also setup for up counting with a top value of 999, resulting in 1ms time duration. Note no interrupt is used and other CCR registers are loaded with 10 – an arbitrary value.

```

/* TA0CCR0, Timer_A Capture/Compare Register 0 */
TA0CCR0 = 999;

/* TA0CCR1, Timer_A Capture/Compare Register 1 */
TA0CCR1 = 10;

/* TA0CCR2, Timer_A Capture/Compare Register 2 */
TA0CCR2 = 10;

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_0 -- Divider - /1
 * MC_1 -- Up Mode
 */
TA0CTL = TASSEL_2 | ID_0 | MC_1;

```

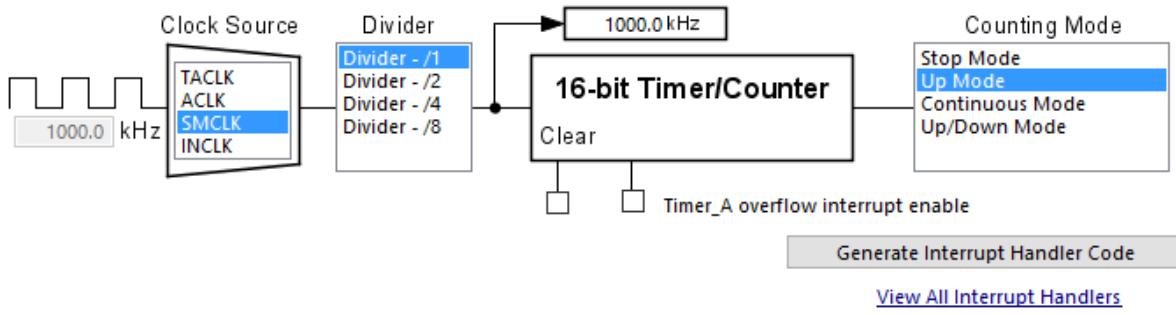
Prior to Timer_A3 setup, CC channels are setup. **OUTMOD** is that stuff that sets PWM type.

```
/*
 * TA0CCTL0, Capture/Compare Control Register 0
 *
 * CM_0 -- No Capture
 * CCIS_0 -- CCIxA
 * ~SCS -- Asynchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * ~CAP -- Compare mode
 * OUTMOD_4 -- PWM output mode: 4 - Toggle
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
TA0CCTL0 = CM_0 | CCIS_0 | OUTMOD_4;

/*
 * TA0CCTL1, Capture/Compare Control Register 1
 *
 * CM_0 -- No Capture
 * CCIS_0 -- CCIxA
 * ~SCS -- Asynchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * ~CAP -- Compare mode
 * OUTMOD_3 -- PWM output mode: 3 - PWM set/reset
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
TA0CCTL1 = CM_0 | CCIS_0 | OUTMOD_3;

/*
 * TA0CCTL2, Capture/Compare Control Register 2
 *
 * CM_0 -- No Capture
 * CCIS_0 -- CCIxA
 * ~SCS -- Asynchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * ~CAP -- Compare mode
 * OUTMOD_7 -- PWM output mode: 7 - PWM reset/set
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
TA0CCTL2 = CM_0 | CCIS_0 | OUTMOD_7;
```

In this demo, three different PWMs are set to show the differences.



Timer Capture/Compare Block #0

Desired Timer Period: ms Time(r) Period 1 ms

Capture Register: Clock Ticks Time(r) Frequency 1000 Hz

Input Selection	Capture Mode	Mode	Output Pins
CC Input OFF P1.1/TA0.CC10A GND VCC	No Capture Rising Edge Falling Edge Both Edges	Timer OFF Output Compare/Period Input Capture	TA0.0 Output OFF P1.1/TA0.0 P1.5/TA0.0

Output Mode: Set OUT bit High/Low

Interrupt Enables

Capture/compare interrupt enable 0

[View All Interrupt Handlers](#)

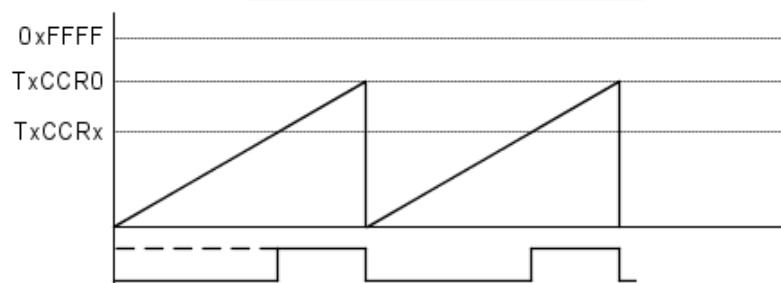
Timer Capture/Compare Block #1

Desired PWM Duty Cycle: %

Capture Register: Clock Ticks

Input Selection	Capture Mode	Mode	Output Pins
CC Input OFF P1.2/TA0.CC11A GND VCC	No Capture Rising Edge Falling Edge Both Edges	Timer OFF Output Compare Input Capture	TA0.1 Output OFF P1.2/TA0.1 P1.6/TA0.1 P2.6/TA0.1

Output Mode: Set OUT bit High/Low



PWM Duty Cycle
Period - Frequency | 1% | 1 ms | 1000 Hz |

Interrupt Enables

Capture/compare interrupt enable 1

[View All Interrupt Handlers](#)

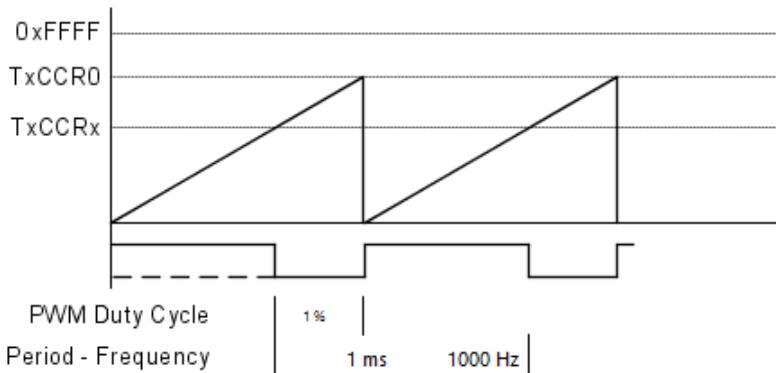
Timer Capture/Compare Block #2

Desired PWM Duty Cycle: %

Capture Register: Clock Ticks

Input Selection	Capture Mode	Mode	Output Pins
CC Input OFF P1.4/TA0.CCI2A GND VCC	No Capture Rising Edge Falling Edge Both Edges	Timer OFF Output Compare Input Capture	TA0.2 Output OFF P1.4/TA0.2

Output Mode: Set OUT bit High/Low



Interrupt Enables

Capture/compare interrupt enable 2

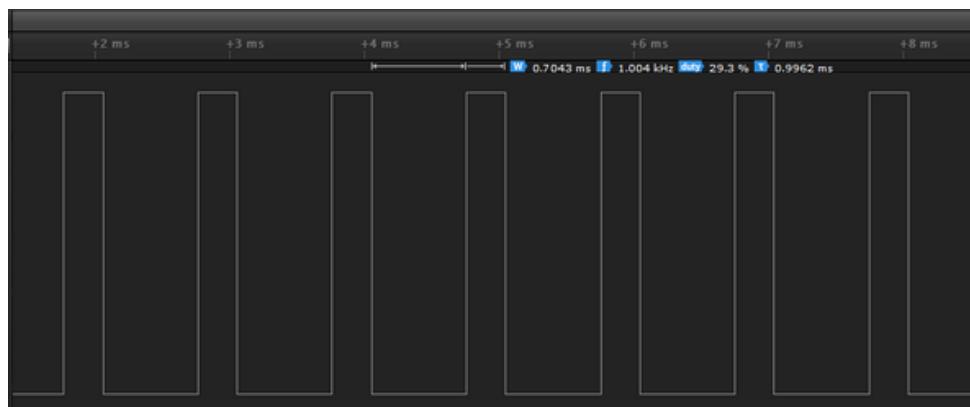
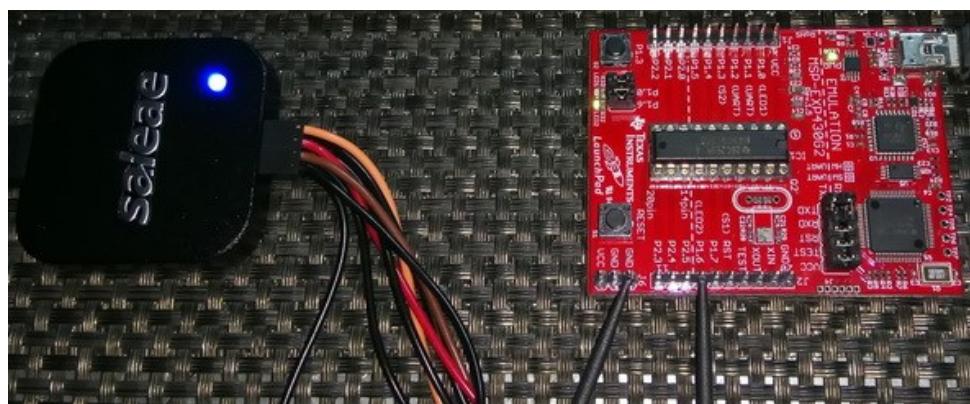
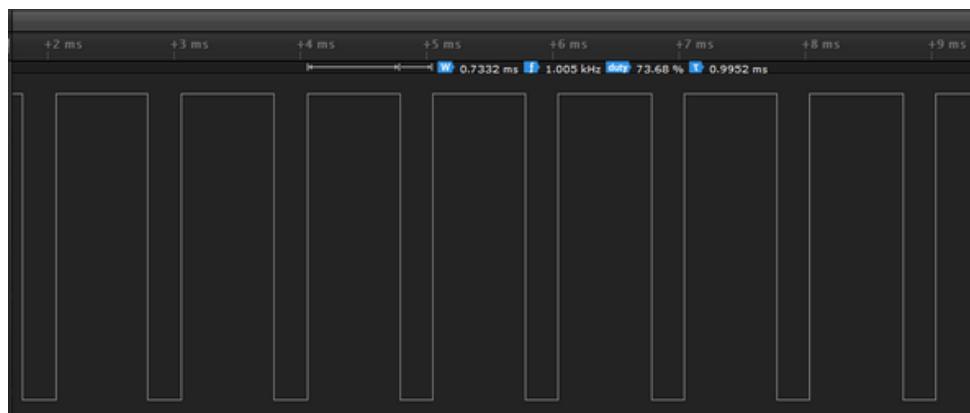
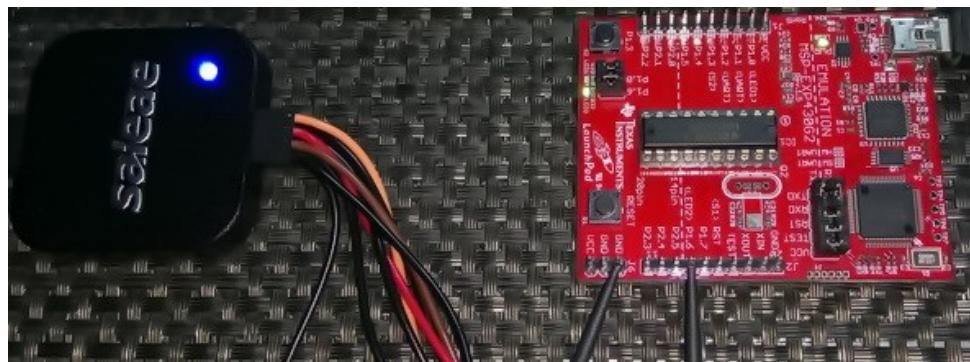
[View All Interrupt Handlers](#)

PWMs can be of the following types:

OUTMODx	Mode	Description
000	Output	The output signal OUTx is defined by the OUTx bit. The OUTx signal updates immediately when OUTx is updated.
001	Set	The output is set when the timer <i>counts</i> to the TACCRx value. It remains set until a reset of the timer, or until another output mode is selected and affects the output.
010	Toggle/Reset	The output is toggled when the timer <i>counts</i> to the TACCRx value. It is reset when the timer <i>counts</i> to the TACCR0 value.
011	Set/Reset	The output is set when the timer <i>counts</i> to the TACCRx value. It is reset when the timer <i>counts</i> to the TACCR0 value.
100	Toggle	The output is toggled when the timer <i>counts</i> to the TACCRx value. The output period is double the timer period.
101	Reset	The output is reset when the timer <i>counts</i> to the TACCRx value. It remains reset until another output mode is selected and affects the output.
110	Toggle/Set	The output is toggled when the timer <i>counts</i> to the TACCRx value. It is set when the timer <i>counts</i> to the TACCR0 value.
111	Reset/Set	The output is reset when the timer <i>counts</i> to the TACCRx value. It is set when the timer <i>counts</i> to the TACCR0 value.

Note that CCR0 has limited PWM options and it is the value of its register that sets PWM frequency. The other CCR registers are loaded with values that determine respective PWM duty cycles.

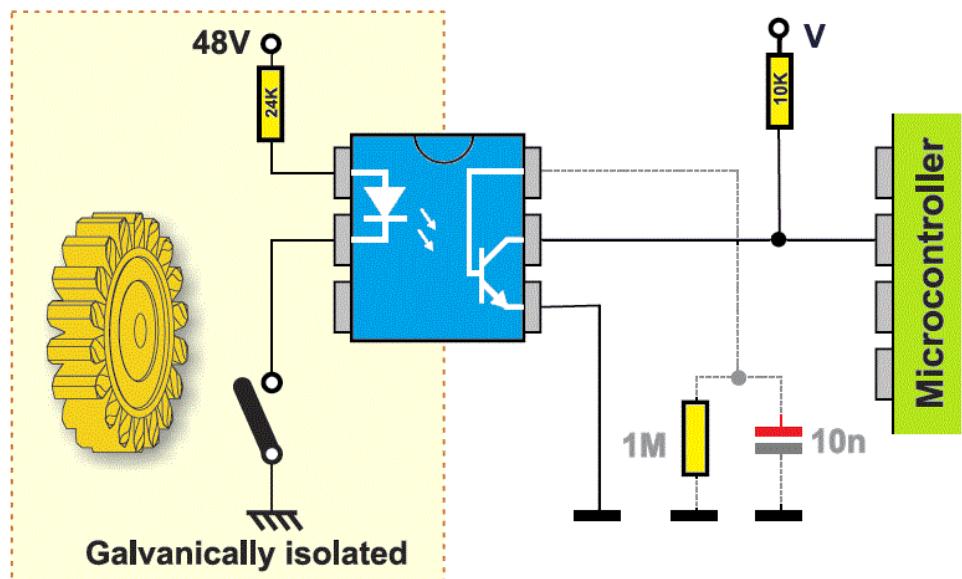
Demo



Demo video: <https://www.youtube.com/watch?v=dbSPi6LbsQg>.

Timer Input Capture

In many cases, it is needed to measure the timing info like period, frequency, duty cycle, etc of an incoming signal. Based on these data we can find out the RPM of a robot's wheel, the pulse widths of an IR remote stream carrying command information, the frequency of AC mains, the patterns of an incoming waveform, etc. Hence comes the purpose of timer input captures.



We know that Timer A3 has three such CC channels and so there are three capture inputs per Timer A module. We can use these channels to capture incoming waveforms of unknown frequencies/duty cycles and have them measured with respect to a known clock like SMCLK.

Again a few things must be observed before using MSP430 input capture hardware:

- Signals coming to input pins must never cross the max. VDD limit or fall below ground level (i.e. sensing negative potentials).
- It is better to galvanically isolate input pins if they are to sense external high voltage signals.
- Input pins must not be left floating.
- Unless needed, it is wise not to use RC filters for inputs.
- Input capture pins are limited remappable just like PWM pins.
- Timer clock must be set as such that we get maximum measurement resolution without compromising reliability.
- Timer overruns/overflows must be taken into account.
- Timer capture inputs can be tied to power pins internally and connecting so results in no measurements. When not capturing anything, select stop mode and clear the timer.

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "lcd.h"

unsigned int overflow_count = 0;
unsigned int pulse_ticks = 0;
unsigned int start_time = 0;
unsigned int end_time = 0;

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void Timer0_A3_graceInit(void);
void Timer1_A3_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned long value);

#pragma vector=TIMER1_A1_VECTOR
__interrupt void TIMER1_A1_ISR_HOOK(void)
{
    if(TA1IV == TA1IV_TACCR1)
    {
        end_time = TA1CCR1;
        pulse_ticks = (end_time - start_time);
        start_time = end_time;
        TA1CCTL1 &= ~CCIFG;
    }
}

void main(void)
{
    unsigned char i = 0;
    unsigned long time_period = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 A3 Timer0 */
    Timer0_A3_graceInit();

    /* initialize Config for the MSP430 A3 Timer0 */
    Timer1_A3_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();
```

```

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

LCD_init();
LCD_clear_home();

LCD_goto(0, 0);
LCD_putstr("Capt./us:");
delay_ms(10);

while(1)
{
    if((P1IN & BIT3) == 0)
    {
        P1OUT |= BIT0;
        while((P1IN & BIT3) == 0);

        i++;
        if(i > 9)
        {
            i = 0;
        }
        P1OUT &= ~BIT0;
    }

    switch(i)
    {
        case 1:
        {
            TA0CCR0 = 9999;
            LCD_goto(0, 1);
            LCD_putstr("Period/ms:    20");
            break;
        }
        case 2:
        {
            TA0CCR0 = 4999;
            LCD_goto(0, 1);
            LCD_putstr("Period/ms:    10");
            break;
        }
        case 3:
        {
            TA0CCR0 = 1999;
            LCD_goto(0, 1);
            LCD_putstr("Period/ms:    4");
            break;
        }
        case 4:
        {
            TA0CCR0 = 999;
            LCD_goto(0, 1);
            LCD_putstr("Period/ms:    2");
            break;
        }
        case 5:
        {
            TA0CCR0 = 166;
            LCD_goto(0, 1);
    }
}

```

```

        LCD_putstr("Period/us:  334");
        break;
    }
    case 6:
    {
        TA0CCR0 = 1230;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:  2.5");
        break;
    }
    case 7:
    {
        TA0CCR0 = 2626;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:  5.3");
        break;
    }
    case 8:
    {
        TA0CCR0 = 4579;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:  9.2");
        break;
    }
    case 9:
    {
        TA0CCR0 = 499;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:  1");
        break;
    }
    default:
    {
        TA0CCR0 = 6964;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:  13.9");
        break;
    }
}

time_period = (pulse_ticks >> 1);
lcd_print(10, 0, time_period);
delay_ms(400);
};

}

void GPIO_graceInit(void)
{
/* USER CODE START (section: GPIO_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = BIT3;

/* Port 1 Port Select Register */
P1SEL = BIT1;
}

```

```

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT1 | BIT6 | BIT7;

/* Port 1 Resistor Enable Register */
P1REN = BIT3;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL = BIT1;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
}

```

```

BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;          /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void Timer0_A3_graceInit(void)
{
    /* USER CODE START (section: Timer0_A3_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: Timer0_A3_graceInit_prologue) */

    /*
     * TA0CCTL0, Capture/Compare Control Register 0
     *
     * CM_0 -- No Capture
     * CCIS_0 -- CCIxA
     * ~SCS -- Asynchronous Capture
     * ~SCCI -- Latched capture signal (read)
     * ~CAP -- Compare mode
     * OUTMOD_4 -- PWM output mode: 4 - Toggle
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    TA0CCTL0 = CM_0 | CCIS_0 | OUTMOD_4;

    /* TA0CCR0, Timer_A Capture/Compare Register 0 */
}

```

```

TA0CCR0 = 9999;

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_1 -- Divider - /2
 * MC_1 -- Up Mode
 */
TA0CTL = TASSEL_2 | ID_1 | MC_1;

/* USER CODE START (section: Timer0_A3_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Timer0_A3_graceInit_epilogue) */
}

void Timer1_A3_graceInit(void)
{
    /* USER CODE START (section: Timer1_A3_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: Timer1_A3_graceInit_prologue) */

    /*
     * TA1CCTL0, Capture/Compare Control Register 0
     *
     * CM_1 -- Rising Edge
     * CCIS_0 -- CCIxA
     * ~SCS -- Asynchronous Capture
     * ~SCCI -- Latched capture signal (read)
     * ~CAP -- Compare mode
     * OUTMOD_1 -- PWM output mode: 1 - Set
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    TA1CCTL0 = CM_1 | CCIS_0 | OUTMOD_1;

    /*
     * TA1CCTL1, Capture/Compare Control Register 1
     *
     * CM_1 -- Rising Edge
     * CCIS_0 -- CCIxA
     * SCS -- Synchronous Capture
     * ~SCCI -- Latched capture signal (read)
     * CAP -- Capture mode
     * OUTMOD_0 -- PWM output mode: 0 - OUT bit value
     *
     * Note: ~SCCI indicates that SCCI has value zero
     */
    TA1CCTL1 = CM_1 | CCIS_0 | SCS | CAP | OUTMOD_0 | CCIE;

    /*
     * TA1CTL, Timer_A3 Control Register
     *
     * TASSEL_2 -- SMCLK
     * ID_0 -- Divider - /1
     * MC_2 -- Continuous Mode
     */
    TA1CTL = TASSEL_2 | ID_0 | MC_2;
}

```

```

/* USER CODE START (section: Timer1_A3_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Timer1_A3_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
do
{
    // Clear OSC fault flag
    IFG1 &= ~OFIFG;

    // 50us delay
    delay_cycles(50);
} while (IFG1 & OFIFG);

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled

```

```

/*
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

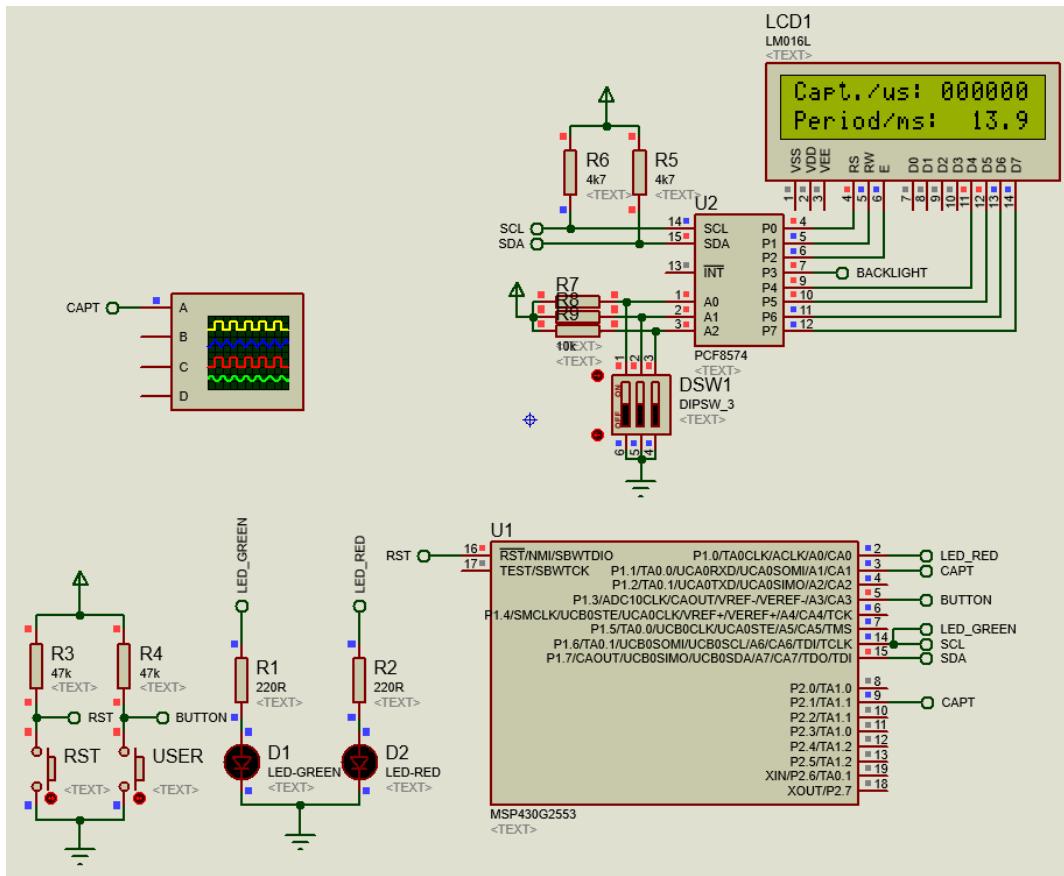
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned long value)
{
    char tmp[6] = {0x20, 0x20, 0x20, 0x20, 0x20, 0x20} ;

    tmp[0] = (((value / 100000) % 10) + 0x30);
    tmp[1] = (((value / 10000) % 10) + 0x30);
    tmp[2] = (((value / 1000) % 10) + 0x30);
    tmp[3] = (((value / 100) % 10) + 0x30);
    tmp[4] = (((value / 10) % 10) + 0x30);
    tmp[5] = ((value % 10) + 0x30);

    LCD_goto(x_pos, y_pos);
    LCD_putstr(tmp);
}

```

Simulation



Explanation

For this demo, I used a MSP430G2553 micro as it has two independent timers. One of these timers is used as a waveform generator and the other as a waveform capture unit.

Timer0_A3 is set up as a PWM output generator with only CC channel 0 active. CC channel 0 is set just to toggle its output logic states and not duty cycle. SMCLK is divided by two and feed to this timer, i.e. this timer has a tick frequency of 500 kHz. As stated before, in order to change the PWM frequency, we need to change the value of TA0CCR0 in up mode counting. We will employ this fact to alter waveform frequency in the main loop.

```
/*
 * TA0CCTL0, Capture/Compare Control Register 0
 *
 * CM_0 -- No Capture
 * CCIS_0 -- CCIXA
 * ~SCS -- Asynchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * ~CAP -- Compare mode
 * OUTMOD_4 -- PWM output mode: 4 - Toggle
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
TA0CCTL0 = CM_0 | CCIS_0 | OUTMOD_4;

/* TA0CCR0, Timer_A Capture/Compare Register 0 */
TA0CCR0 = 9999;

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_1 -- Divider - /2
 * MC_1 -- Up Mode
 */
TA0CTL = TASSEL_2 | ID_1 | MC_1;
```

The other timer - Timer1_A3 is setup to capture the waveform generated by Timer0_A3. Timer interrupt is used to quickly respond to incoming waveform's rising edges. We will be measuring the time period of Timer0_A3's waveform and so we are interest in measuring the time difference between like edges – here rising edges. To get high accuracy, SMCLK is not divided. This gives us a minimum capture period of 1 microsecond and a maximum of about 65 milliseconds provided that we are using continuous mode counting. In other words, Timer1_A3 has double scanning rate than what Timer0_A3 can throw at it – a concept similar to [Nyquist theorem](#).

```

/*
 * TA1CCTL0, Capture/Compare Control Register 0
 *
 * CM_1 -- Rising Edge
 * CCIS_0 -- CCIxA
 * ~SCS -- Asynchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * ~CAP -- Compare mode
 * OUTMOD_1 -- PWM output mode: 1 - Set
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
*/
TA1CCTL0 = CM_1 | CCIS_0 | OUTMOD_1;

/*
 * TA1CCTL1, Capture/Compare Control Register 1
 *
 * CM_1 -- Rising Edge
 * CCIS_0 -- CCIxA
 * SCS -- Synchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * CAP -- Capture mode
 * OUTMOD_0 -- PWM output mode: 0 - OUT bit value
 *
 * Note: ~SCCI indicates that SCCI has value zero
*/
TA1CCTL1 = CM_1 | CCIS_0 | SCS | CAP | OUTMOD_0 | CCIE;

/*
 * TA1CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_0 -- Divider - /1
 * MC_2 -- Continuous Mode
*/
TA1CTL = TASSEL_2 | ID_0 | MC_2;

```

In the timer ISR, we need to check first what caused the interrupt. If it was due to a rising edge capture then we have to take note of current time count in TA1CCR1 since we are using input capture channel 1 of Timer1_A3. Two such time counts are needed to find out the time difference between two adjacent rising edges. This gives us the time period of the captured incoming waveform. However, we are not stopping input capture or the timer even after two successive capture events. This is because we are continuous monitoring the incoming waveform.

```

#pragma vector=TIMER1_A1_VECTOR
_interrupt void TIMER1_A1_ISR_HOOK(void)
{
    if(TA1IV == TA1IV_TACCR1)
    {
        end_time = TA1CCR1;
        pulse_ticks = (end_time - start_time);
        start_time = end_time;
        TA1CCTL1 &= ~CCIFG;
    }
}

```

In the main loop, we are using the Launchpad's user button to alter TA0CCR0's value and hence PWM frequency or period. There are ten different time periods to select. The main code also displays captured waveform time period vs expected time period on a LCD.

```
if((P1IN & BIT3) == 0)
{
    P1OUT |= BIT0;
    while((P1IN & BIT3) == 0);

    i++;
    if(i > 9)
    {
        i = 0;
    }
    P1OUT &= ~BIT0;
}

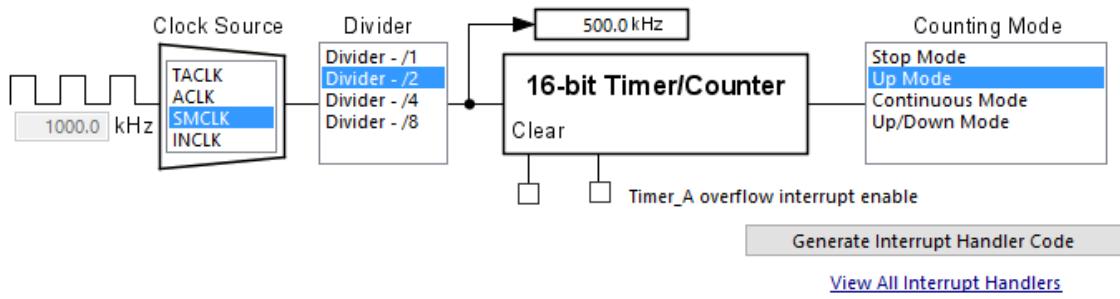
switch(i)
{
    case 1:
    {
        TA0CCR0 = 9999;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:      20");
        break;
    }
    case 2:
    {
        TA0CCR0 = 4999;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:      10");
        break;
    }
    case 3:
    {
        TA0CCR0 = 1999;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:      4");
        break;
    }
    case 4:
    {
        TA0CCR0 = 999;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:      2");
        break;
    }
    case 5:
    {
        TA0CCR0 = 166;
        LCD_goto(0, 1);
        LCD_putstr("Period/us:     334");
        break;
    }
    case 6:
    {
        TA0CCR0 = 1230;
        LCD_goto(0, 1);
```

```

        LCD_putstr("Period/ms:  2.5");
        break;
    }
    case 7:
    {
        TA0CCR0 = 2626;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:  5.3");
        break;
    }
    case 8:
    {
        TA0CCR0 = 4579;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:  9.2");
        break;
    }
    case 9:
    {
        TA0CCR0 = 499;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms:     1");
        break;
    }
    default:
    {
        TA0CCR0 = 6964;
        LCD_goto(0, 1);
        LCD_putstr("Period/ms: 13.9");
        break;
    }
}

time_period = (pulse_ticks >> 1);
lcd_print(10, 0, time_period);
delay_ms(400);

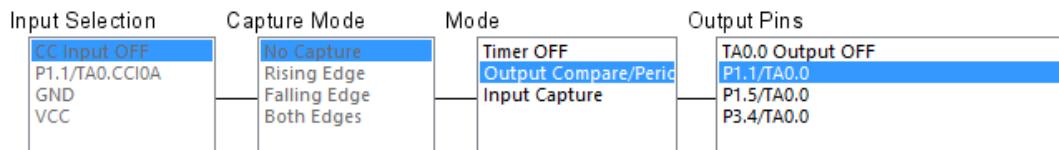
```



Timer Capture/Compare Block #0

Desired Timer Period: ms Time(r) Period 20 ms

Capture Register: Clock Ticks Time(r) Frequency 50 Hz

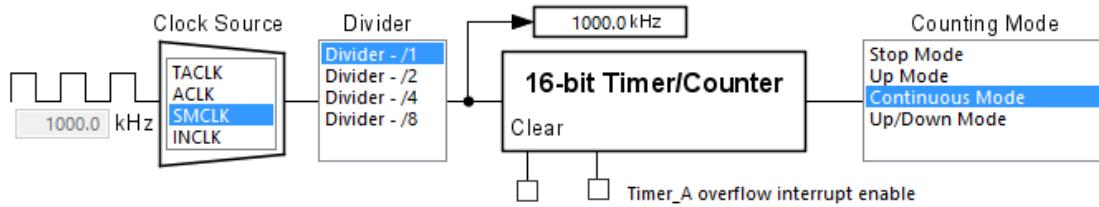


Output Mode: Set OUT bit High/Low

Interrupt Enables

Capture/compare interrupt enable 0

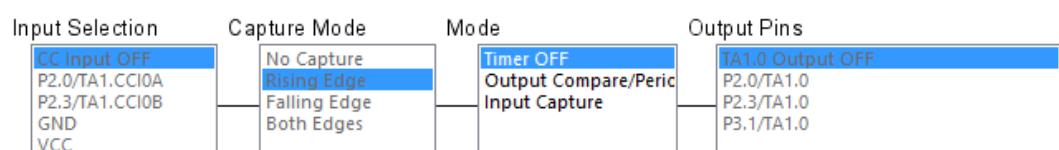
[View All Interrupt Handlers](#)



Timer Capture/Compare Block #0

Desired Timer Period: ms Time(r) Period 65.5 ms

Capture Register: Clock Ticks Time(r) Frequency 15.3 Hz



Output Mode: Set OUT bit High/Low

Interrupt Enables

Capture/compare interrupt enable 0

[View All Interrupt Handlers](#)

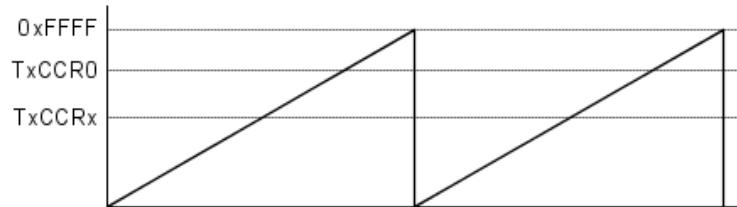
Timer Capture/Compare Block #1

Desired PWM Duty Cycle: %

Capture Register: Clock Ticks

Input Selection	Capture Mode	Mode	Output Pins
CC Input OFF P2.1/TA1.CCI1A P2.2/TA1.CCI1B GND VCC	No Capture Rising Edge Falling Edge Both Edges	Timer OFF Output Compare Input Capture	TA1.1 Output OFF P2.1/TA1.1 P2.2/TA1.1 P3.2/TA1.1

Output Mode: Set OUT bit High/Low

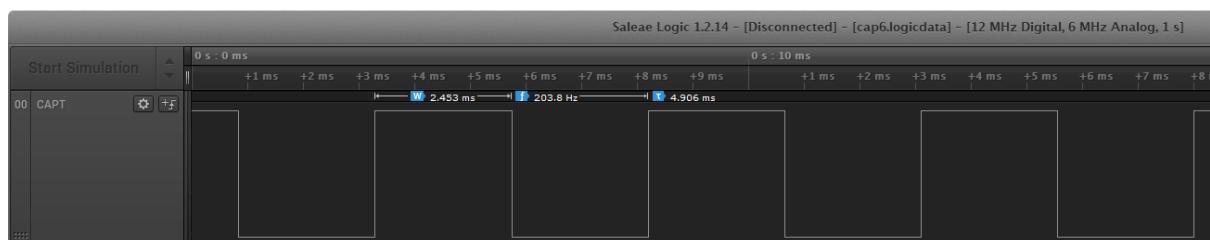
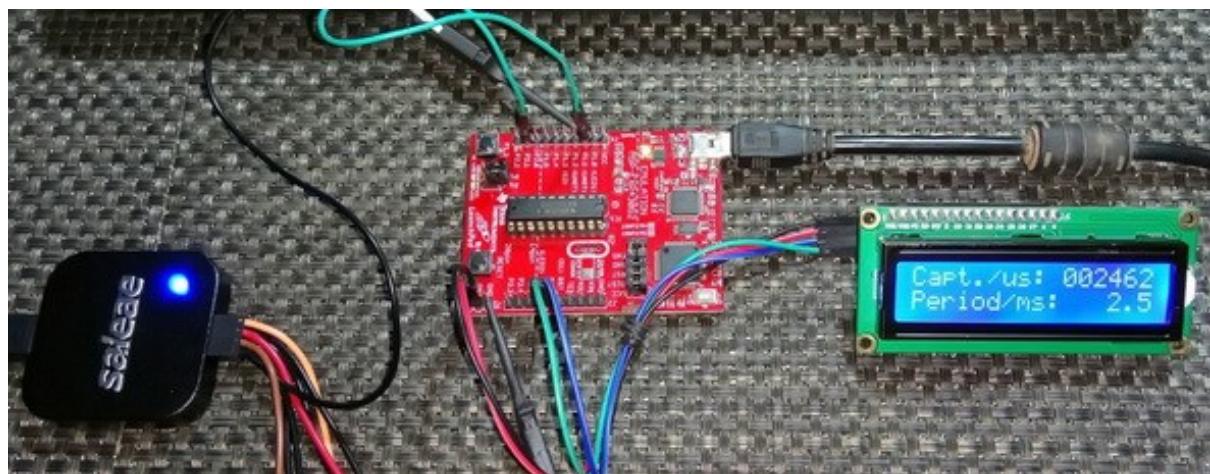


Interrupt Enables

Capture/compare interrupt enable 1

[View All Interrupt Handlers](#)

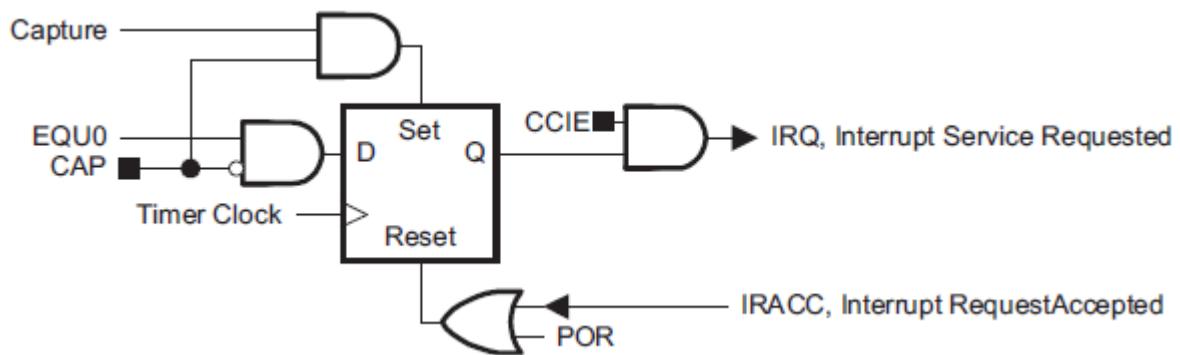
Demo



Demo video: <https://www.youtube.com/watch?v=CHLkXf8MqbQ>.

Time Delay Generation with Timer Compare-Match Feature

Time-bases and delays can be generated in many different ways, ranging from software techniques to using a dedicated hardware timer. Between software-based methods and hardware-based ones, the latter is more efficient and effective. This is because software-based methods rely on wasteful CPU-intensive loops and other resource-consuming processes. Hardware approaches for generating time-bases and delays are smart choices because the prime job of a timer is to count ticks or measure time. Yet within hardware-based methods, there are several techniques and tricks. We can choose between polling a free running timer or using interrupts to get things done in a more real-time sense. We have seen previously that we can use timer interrupts to time events. Here we will also see the same but this time compare-match interrupt is used instead of timer interrupt.



Code Example

```
#include <msp430.h>

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void Timer0_A3_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

#pragma vector = TIMER0_A0_VECTOR
__interrupt void TIMER0_A0_ISR_HOOK(void)
{
    P1OUT ^= (BIT0 | BIT6);
    __bic_SR_register_on_exit(LPM0_bits);
}

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
}
```

```

BCSplus_graceInit();

/* initialize Config for the MSP430 A3 Timer0 */
Timer0_A3_graceInit();

/* initialize Config for the MSP430 System Registers */
System_graceInit();

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

P1OUT |= BIT0;
P1OUT &= ~BIT6;

while(1)
{
    __bis_SR_register(LPM0_bits);
};

}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Direction Register */
    P1DIR = BIT0 | BIT6;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Port Select Register */
    P2SEL &= ~(BIT6 | BIT7);

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */
}

```

```

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF)
    {
        /* Follow recommended flow. First, clear all DCox and MODx bits. Then
         * apply new RSELx values. Finally, apply new DCox and MODx bit values.
         */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;           /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;

    /*
     * Basic Clock System Control 3
     *
     * XT2S_0 -- 0.4 - 1 MHz
     * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
     * XCAP_1 -- ~6 pF
     */
    BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

    /* USER CODE START (section: BCSplus_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void Timer0_A3_graceInit(void)
{

```

```

/* USER CODE START (section: Timer0_A3_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: Timer0_A3_graceInit_prologue) */

/*
 * TA0CCTL0, Capture/Compare Control Register 0
 *
 * CM_0 -- No Capture
 * CCIS_0 -- CCIxA
 * ~SCS -- Asynchronous Capture
 * ~SCCI -- Latched capture signal (read)
 * ~CAP -- Compare mode
 * OUTMOD_0 -- PWM output mode: 0 - OUT bit value
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
TA0CCTL0 = CM_0 | CCIS_0 | OUTMOD_0 | CCIE;

/* TA0CCR0, Timer_A Capture/Compare Register 0 */
TA0CCR0 = 49999;

/*
 * TA0CTL, Timer_A3 Control Register
 *
 * TASSEL_2 -- SMCLK
 * ID_3 -- Divider - /8
 * MC_1 -- Up Mode
 */
TA0CTL = TASSEL_2 | ID_3 | MC_1;

/* USER CODE START (section: Timer0_A3_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Timer0_A3_graceInit_epilogue) */
}

void System_graceInit(void)
{
/* USER CODE START (section: System_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: System_graceInit_prologue) */

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
_bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

```

```

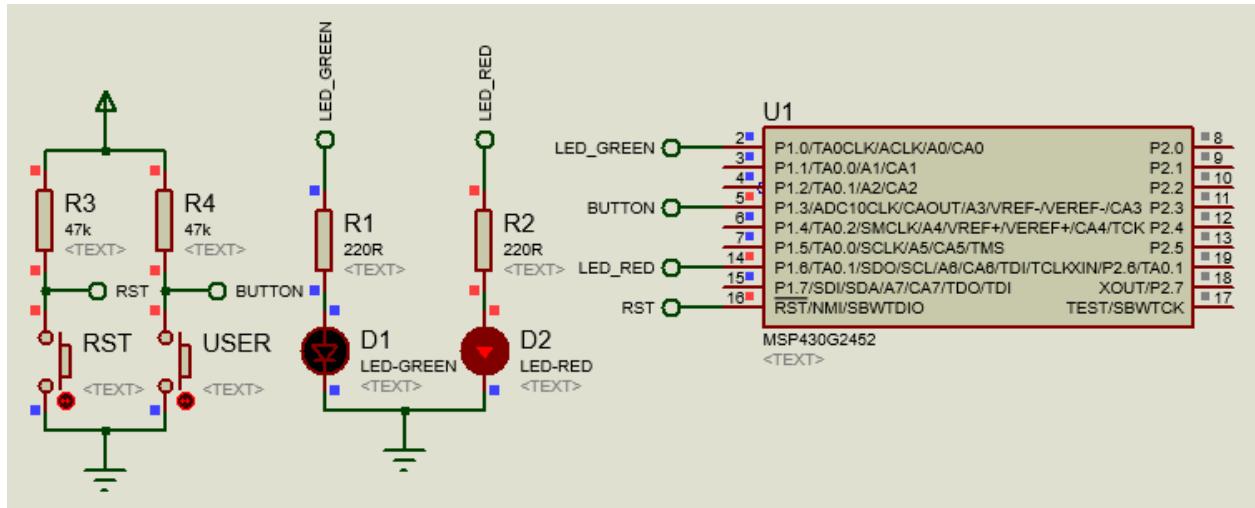
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

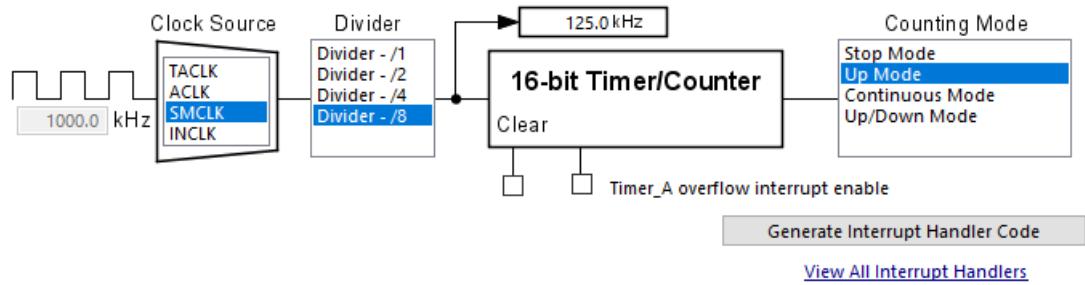
Simulation



Explanation

Timer0_A3 is set here for compare-match interval mode. In this mode, Timer0_A3's settings are same as we would do for ordinary timer overflow interrupt. However, the key difference is the interrupt

source. Note that in the diagram below timer overflow interrupt is not being used. Timer capture-compare interrupt is used instead.



Timer Capture/Compare Block #0

Desired Timer Period: ms Time(r) Period 400 ms

Capture Register: Clock Ticks Time(r) Frequency 2.5 Hz

Input Selection	Capture Mode	Mode	Output Pins
CC Input OFF P1.1/TA0.CCI0A GND VCC	No Capture Rising Edge Falling Edge Both Edges	Timer OFF Output Compare/Period Input Capture	TA0.0 Output OFF P1.1/TA0.0 P1.5/TA0.0

Output Mode: Set OUT bit High/Low

Interrupt Enables

Capture/compare interrupt enable 0

[View All Interrupt Handlers](#)

The desire time period is set for 400ms or 2.5Hz. At every 400ms interval, a compare-match interrupt will occur. How this is done? Well the timer is set for up counting and it has an input clock of 125kHz – 1MHz SMCLK prescaled by 8.

```
void Timer0_A3_graceInit(void)
{
    /* USER CODE START (section: Timer0_A3_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: Timer0_A3_graceInit_prologue) */

    /*
     * TA0CCTL0, Capture/Compare Control Register 0
     *
     * CM_0 -- No Capture
     * CCIS_0 -- CCIxA
     * ~SCS -- Asynchronous Capture
     * ~SCCI -- Latched capture signal (read)
     * ~CAP -- Compare mode
     * OUTMOD_0 -- PWM output mode: 0 - OUT bit value
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    TA0CCTL0 = CM_0 | CCIS_0 | OUTMOD_0 | CCIE;

    /* TA0CCR0, Timer_A Capture/Compare Register 0 */
    TA0CCR0 = 49999;

    /*

```

```

    * TA0CTL, Timer_A3 Control Register
    *
    * TASSEL_2 -- SMCLK
    * ID_3 -- Divider - /8
    * MC_1 -- Up Mode
    */
TA0CTL = TASSEL_2 | ID_3 | MC_1;

/* USER CODE START (section: Timer0_A3_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Timer0_A3_graceInit_epilogue) */
}

```

Inside the interrupt function, the LEDs of Launchpad board are toggled. Note that after the occurrence of the interrupt LPM0 is exited.

```

#pragma vector = TIMER0_A0_VECTOR
_interrupt void TIMER0_A0_ISR_HOOK(void)
{
    P1OUT ^= (BIT0 | BIT6);
    __bic_SR_register_on_exit(LPM0_bits);
}

```

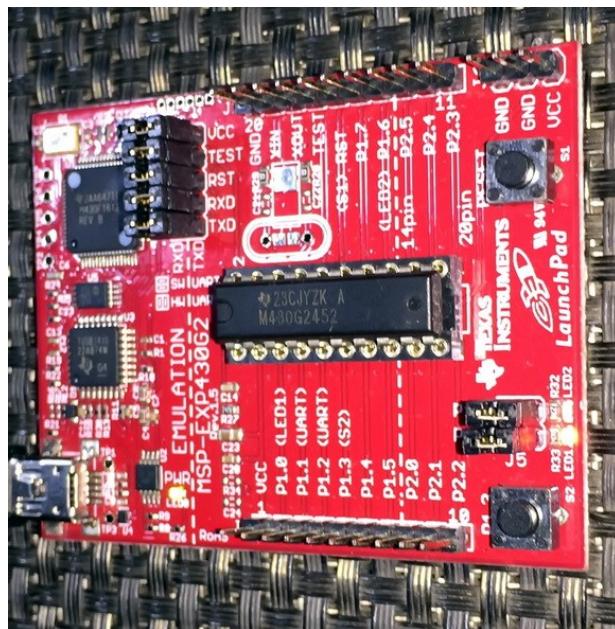
In the main, there is no task and in it LPM0 is entered. Thus, the process is independent of the main and is energy efficient.

```

while(1)
{
    __bis_SR_register(LPM0_bits);
};

```

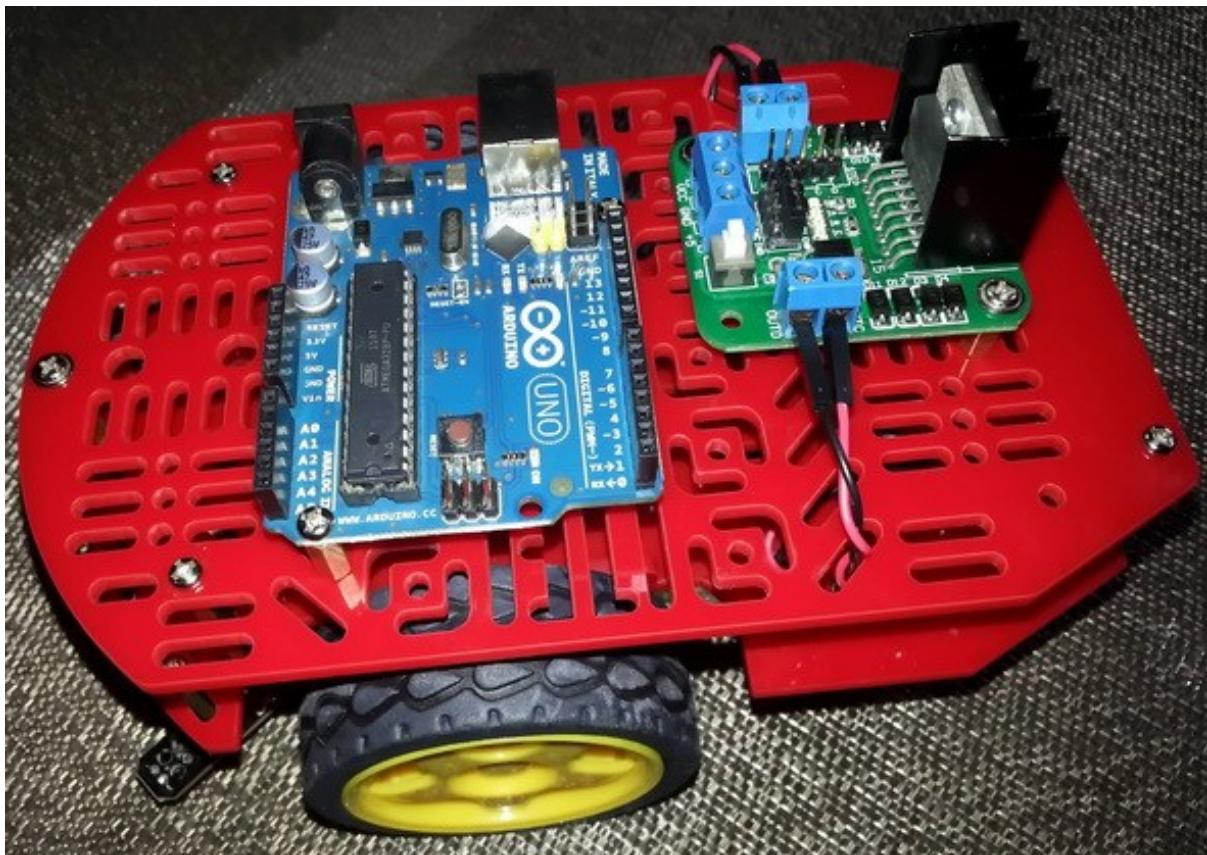
Demo



Demo video: <https://youtu.be/Q7z8qEF04UY>.

Watchdog Timer Plus (WDT+)

At present, any commercial/industrial/professional electronic good must pass a number of tests and obtain some certifications before its introduction to market, most notably **CE**, **FCC**, **UL** and **TUV** certifications. This is so as it is imperative that a device pass **Electromagnetic Compliance (EMC)** test not just for flawless performance but also for user safety. Hobby electronics projects don't need these and most hobbyists don't fully understand the issues caused by EMI or what causes them. This is why many simple robots like the line follower robot shown below fail to perform properly in robotics competitions. Some of them seem to behave erratically while others seem to be unresponsive after working for some time. If both hardware and software designs are well designed and tested against harsh conditions, the chances of failure reduce significantly. A hardware designer should consider proper PCB layout and component placement as well and component selection. Likewise, a programmer should avoid polling-based solutions, blocking codes, unwanted loops, and should consider using watchdog timers and other coding tricks. To avoid getting a device into a stalled state, both hardware and software ends must merge properly and accordingly.



A watchdog timer is basically a fail-safe time. It is a very important module when considering an embedded-system-based design that is likely to operate in noisy environments or when there is a probability of its application firmware to get stuck due to malfunctions. Any programmer would want to get that stuck up firmware up and running again after recovering from the issue that cause it to fail. All MSP430s are equipped with a WDT module and here we will see how it helps us in recovering it when we simulate an entry into an unanticipated loop.

Code Example

```
#include <msp430.h>

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void InterruptVectors_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

void main(void)
{
    // Stop WDT+
    WDTCTL = WDTPW + WDTHOLD; // Set hold bit and clear others

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        P1OUT ^= BIT0;
        _delay_cycles(60000);

        WDTCTL = WDTPW | WDTCNTCL;

        if((P1IN & BIT3) == !BIT3)
        {
            WDTCTL = WDTPW | WDTSEL;

            while(1)
            {
                P1OUT ^= BIT6;
                _delay_cycles(45000);
            };
        }
    }
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
}
```

```

P1OUT = BIT3;

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT6;

/* Port 1 Resistor Enable Register */
P1REN = BIT3;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF) {
        /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
         * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
         */
        DCOCTL = 0x00;
}

```

```

        BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
        DCOTCL = CALDCO_1MHZ;
    }

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_3 -- Divide by 8
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_3;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
do
{
    // Clear OSC fault flag
    IFG1 &= ~OFIFG;

    // 50us delay
    _delay_cycles(50);
} while (IFG1 & OFIFG);

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
_bis_SR_register(GIE);
}

```

```

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue)
}

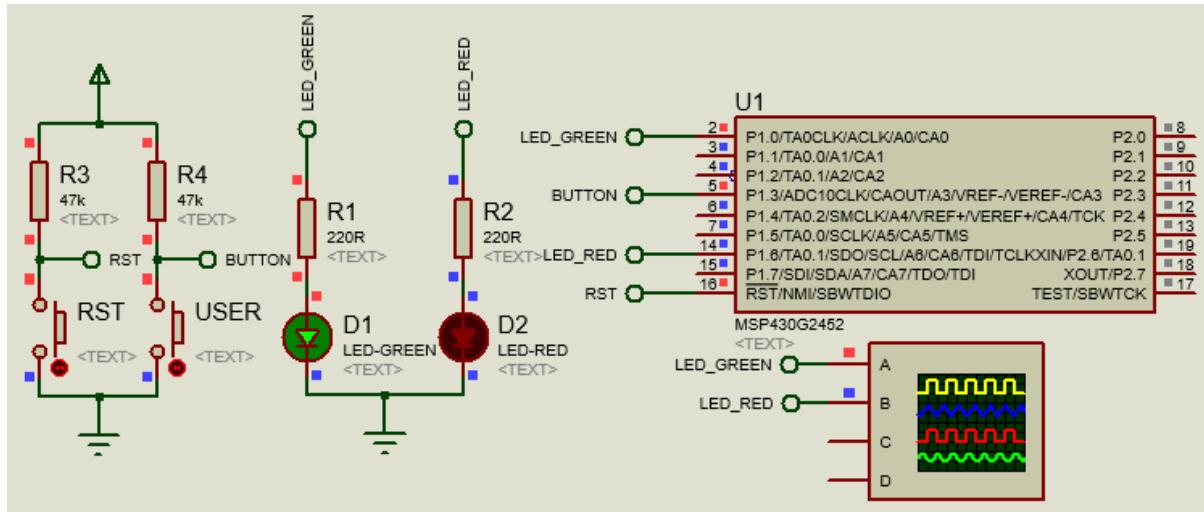
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * ~WDTHOLD -- Watchdog timer+ is not stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * WDTSSEL -- ACLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTSSEL;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue)
}

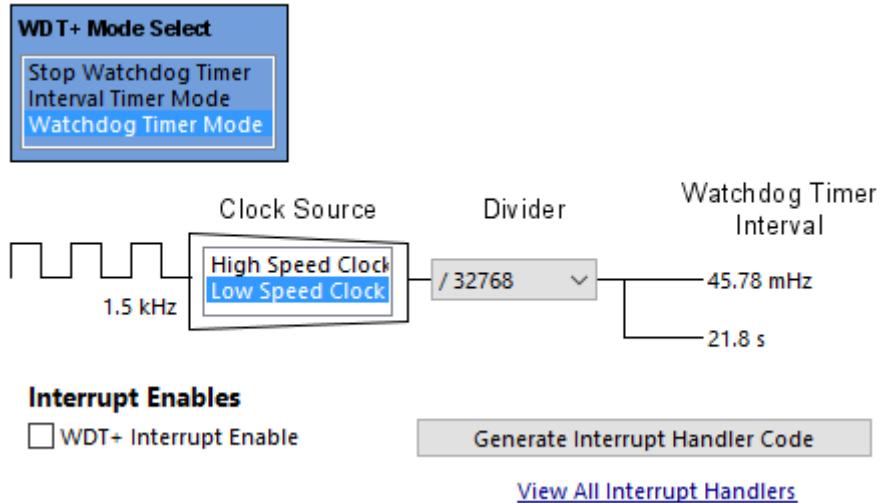
```

Simulation



Explanation

Unlike previous timer examples, 12 kHz ACLK is used. ACLK is divided by 8 to make it 1.5 kHz low speed clock source for the WDT+ module. This clock is further prescaled by 32768 to get a WDT+ timeout of about 22 seconds.



```
/*
 * WDTCTL, Watchdog Timer+ Register
 *
 * WDTPW -- Watchdog password
 * ~WDTHOLD -- Watchdog timer+ is not stopped
 * ~WDTNMIES -- NMI on rising edge
 * ~WDTNMI -- Reset function
 * ~WDTTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * WDTSEL -- ACLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTSEL;
```

In the main loop, P1.0 toggles without any issue. WDT+ is regularly refreshed. However, when the user button is pressed, WDT+ is no longer refreshed and P1.6 LED is toggled inside a simulated undesired loop. P1.0 LED appears to have gotten stuck. This causes the WDT+ to cross maximum timeout limit and thereby trigger a reset.

```
P1OUT ^= BIT0;
_delay_cycles(60000);

WDTCTL = WDTPW | WDTCNTCL;

if((P1IN & BIT3) == !BIT3)
{
    WDTCTL = WDTPW | WDTSEL;
```

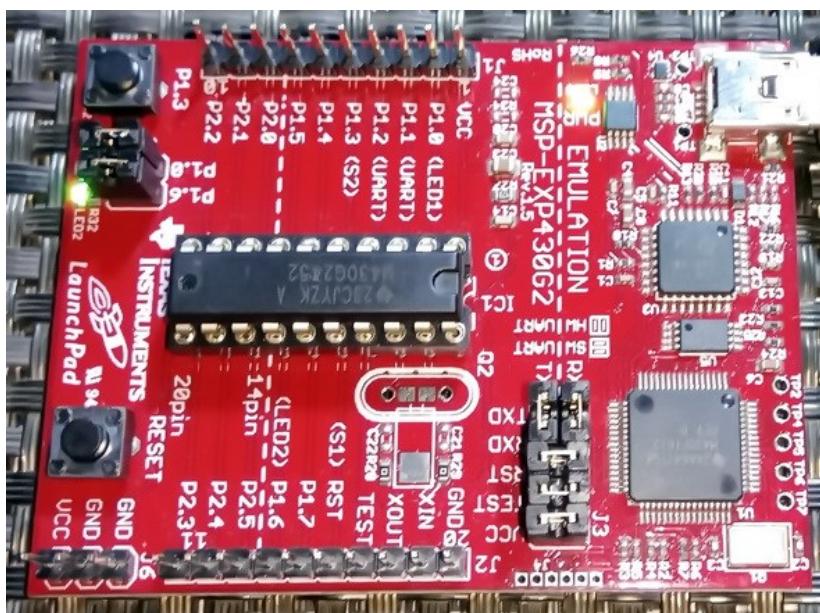
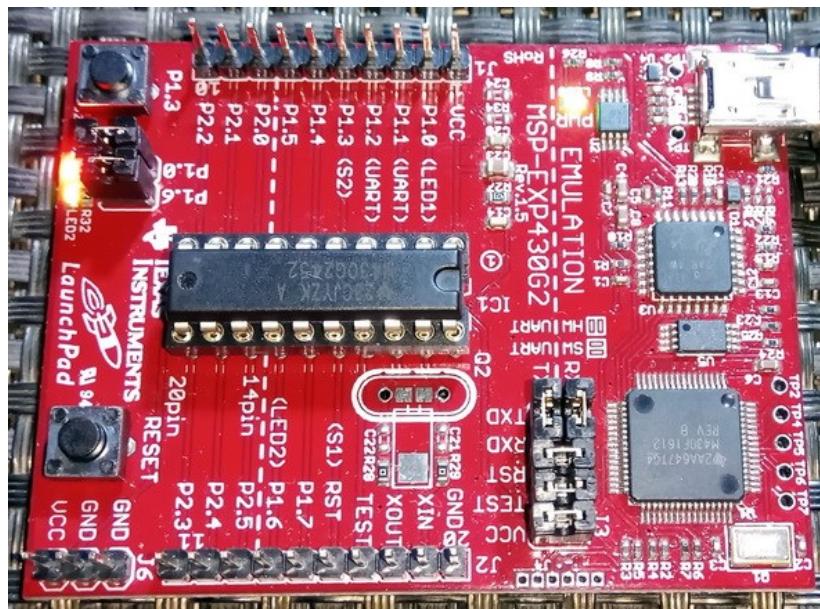
```

while(1)
{
    P1OUT ^= BIT6;
    _delay_cycles(45000);
}

```

In reality, the timeout time may vary due to variations in ACLK time period. In my demo, I noticed this variation. During that time, I found that ACLK is about 10 kHz instead of 12 kHz.

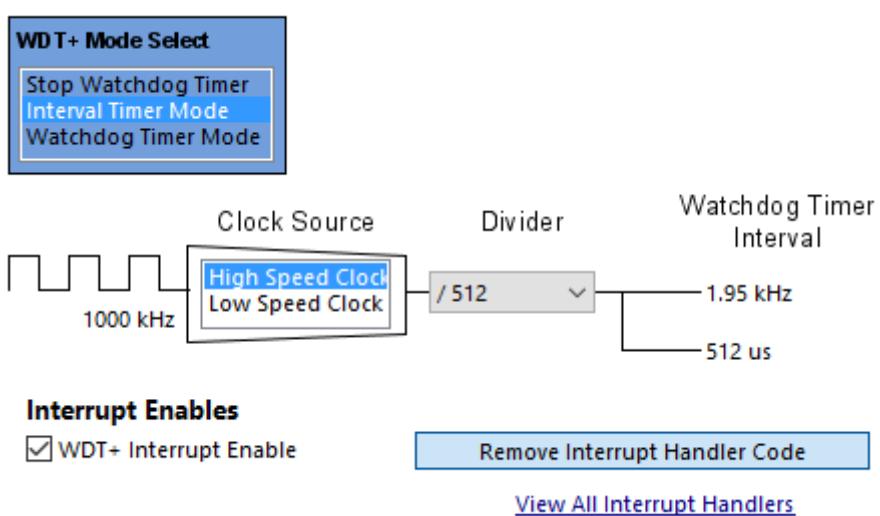
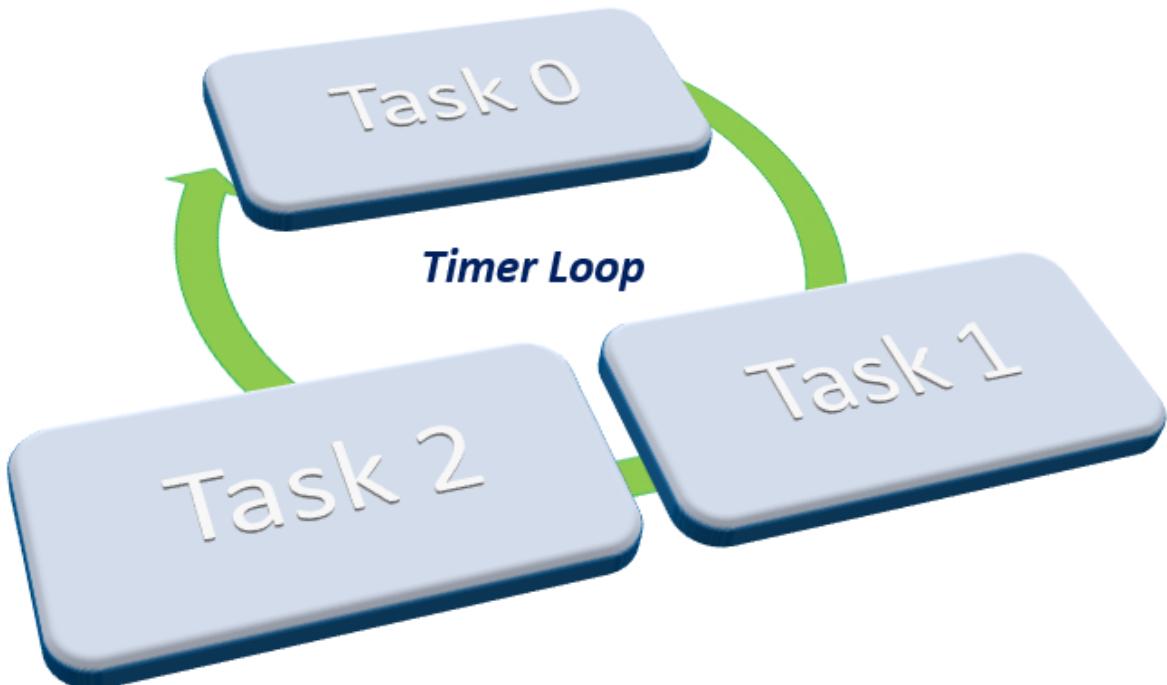
Demo



Demo video: <https://www.youtube.com/watch?v=vYCLeWZZt7U>.

WDT+ as an Interval Timer

There are cases in which we don't need the protection feature of WDT+. This leaves with a free timer which can be used for other jobs. As I said before, Americans think differently than the rest of the world and here is one proof of that ingenious concept. However, since WDT+ was intended for a special mission, we cannot expect it to be completely like other timers. For example, it doesn't have any capture-compare pin associated with it nor do we have access to its counter. Even with these limitations, it is still a useful bonus.



A lame demonstration of RTOS concept is demoed here.

Code Example

```
#include <msp430.h>

unsigned char state = 0;

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

/*
 * ===== Watchdog Timer Interval Interrupt Handler Generation =====
 */
#pragma vector=WDT_VECTOR
_interrupt void WDT_ISR_HOOK(void)
{
    state++;

    if(state >= 3)
    {
        state = 0;
    }

    IFG1 &= ~WDTIFG;
}

void main(void)
{
    unsigned int s = 0;
    unsigned char i = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        switch(state)
        {
            case 1:
            {

```

```

        switch(i)
    {
        case 0:
        {
            P1OUT &= ~BIT0;
            break;
        }
        default:
        {
            P1OUT |= BIT0;
            break;
        }
    }

    break;
}
case 2:
{
    _delay_cycles(1);
    s++;
    if(s > 20000)
    {
        P1OUT ^= BIT6;
        s = 0;
    }

    break;
}
default:
{
    if((P1IN & BIT3) != BIT3)
    {
        i ^= BIT0;
    }
    break;
}
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = BIT3;

    /* Port 1 Direction Register */
    P1DIR = BIT0 | BIT6;

    /* Port 1 Resistor Enable Register */
    P1REN = BIT3;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;
}

```

```

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~BIT6 | BIT7;

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF) {
        /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
         * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
         */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_2 -- Divide by 4
     */
}

```

```

        * Note: ~XTS indicates that XTS has value zero
        */
BCSCTL1 |= XT20FF | DIVA_2;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(50);
    } while (IFG1 & OFIFG);

    /*
     * IFG1, Interrupt Flag Register 1
     *
     * ~ACCVIFG -- No interrupt pending
     * ~NMIIIFG -- No interrupt pending
     * ~OFIFG -- No interrupt pending
     * WDTIFG -- Interrupt pending
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    IFG1 &= ~(WDTIFG);

    /*
     * IE1, Interrupt Enable Register 1
     *
     * ~ACCVIE -- Interrupt not enabled
     * ~NMIIIE -- Interrupt not enabled
     * ~OFIE -- Interrupt not enabled
     * WDTIE -- Interrupt enabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    IE1 |= WDTIE;
}

```

```

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
__bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

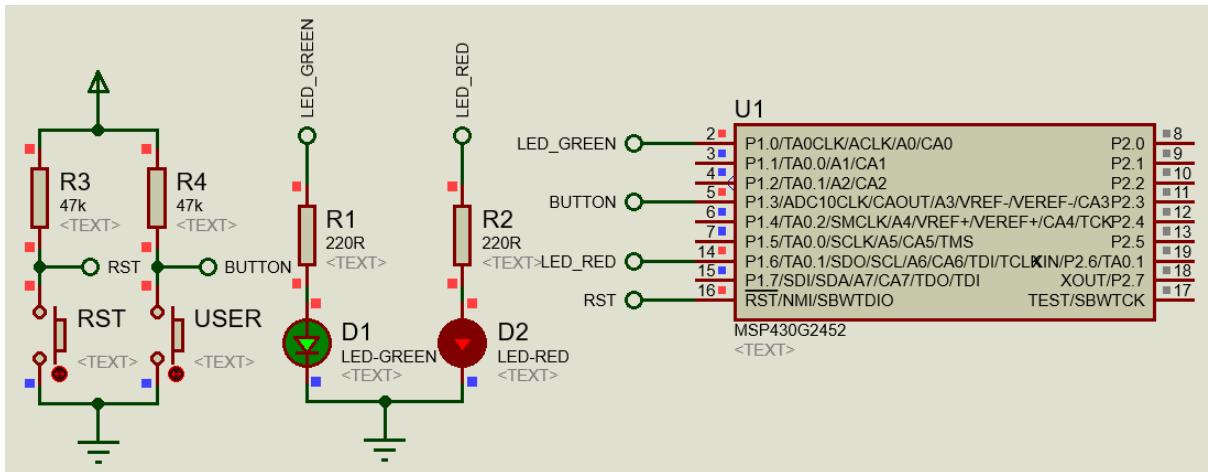
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * ~WDTHOLD -- Watchdog timer+ is not stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * WDTMSEL -- Interval timer mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * WDTIS1 -- Watchdog clock source bit1 enabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTMSEL | WDTIS1;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation



Explanation

WDT+ is used here as an interval timer with a time period of 512 microseconds. After every 512 microseconds, there is a WDT+ interrupt.

```
/*
 * WDTCTL, Watchdog Timer+ Register
 *
 * WDTPW -- Watchdog password
 * ~WDTHOLD -- Watchdog timer+ is not stopped
 * ~WDTNMIES -- NMI on rising edge
 * ~WDTNMI -- Reset function
 * WDTMSEL -- Interval timer mode
 * ~WDTCNTCL -- No action
 * ~WDTSSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * WDTIS1 -- Watchdog clock source bit1 enabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTMSEL | WDTIS1;
```

Inside this interrupt we just change the value of a variable called *task*.

```
#pragma vector=WDT_VECTOR
_interrupt void WDT_ISR_HOOK(void)
{
    task++;

    if(task >= 3)
    {
        task = 0;
    }

    IFG1 &= ~WDTIFG;
}
```

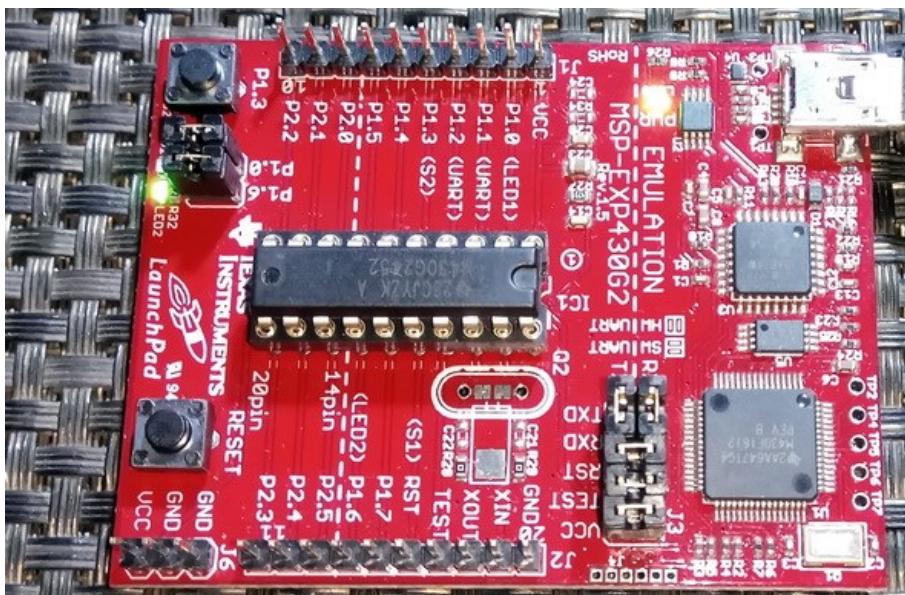
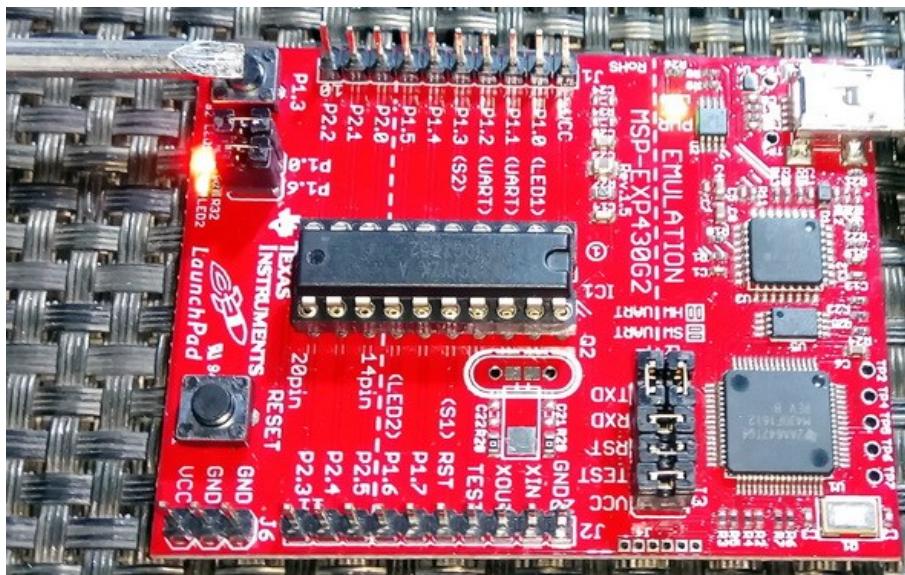
The variable *task* in the main loop is used to switch between different tasks, each task having same time frame and priority. This is called a task scheduling.

```
switch(task)
{
    case 1:
    {
        switch(i)
        {
            case 0:
            {
                P1OUT &= ~BIT0;
                break;
            }
            default:
            {
                P1OUT |= BIT0;
                break;
            }
        }

        break;
    }
    case 2:
    {
        _delay_cycles(1);
        s++;
        if(s > 20000)
        {
            P1OUT ^= BIT6;
            s = 0;
        }
        break;
    }
    default:
    {
        if((P1IN & BIT3) != BIT3)
        {
            i ^= BIT0;
        }
        break;
    }
}
```

Task 1 lights P1.0 LED based on the logic state of the user button. Task 0 checks the state of the user button. Task 2 blinks P1.6 LED independent of the other tasks. The total time for the completion of all these processes is about 1.5 milliseconds – a very short time. In this method, no task waits for other tasks. The whole process is so fast to human eyes that everything this code does will appear to occur parallelly.

Demo



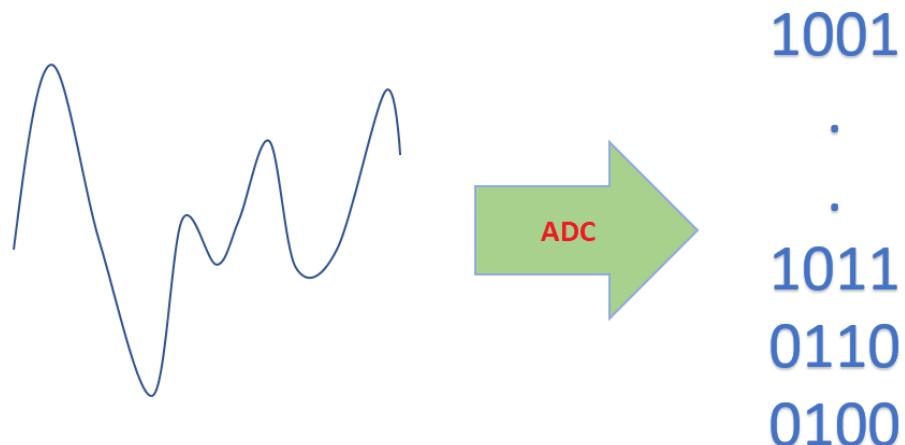
Demo video: <https://www.youtube.com/watch?v=BNwxdgLQerU>.

Analogue Frontend Overview

MSP stands for mixed signal processor. Mixed signal means combination of both analogue and digital. We can, therefore, expect a great deal of cool stuffs when it comes to their analogue features. Chips vary in features and so do the analogue peripherals. There are various types of analogue peripherals offered by MSP430s and we can categorize them into four basic categories:

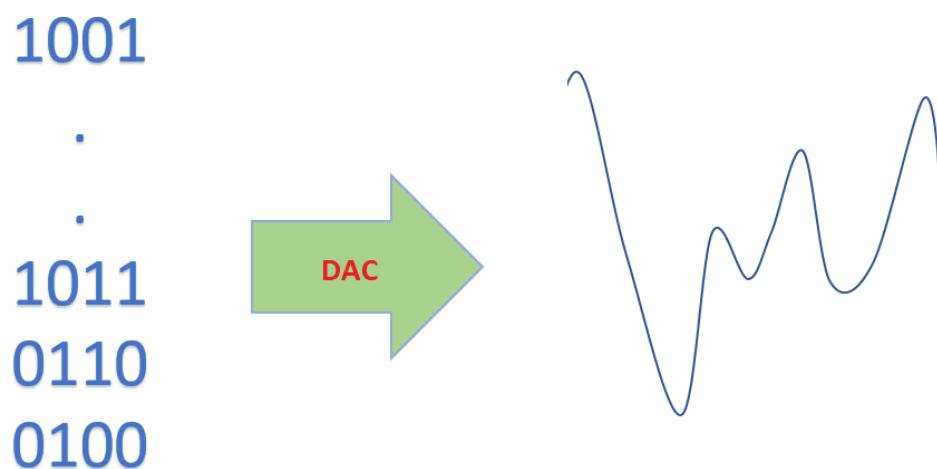
Analogue-to-Digital Converters (ADC)

ADC are used to measure time-varying voltages. They digitize analogue signals by representing them in quantized binary formats. The most common ADCs in MSP430s are **ADC10** and **ADC12**. These are **Successive Approximation (SAR)** ADCs. Both of these ADCs are similar in many aspects except in resolution. Some MSP430 devices have more advanced high-resolution delta-sigma ADCs like **SD16_A** and **SD24_A**. All MSP430s additionally have internal temperature sensors.



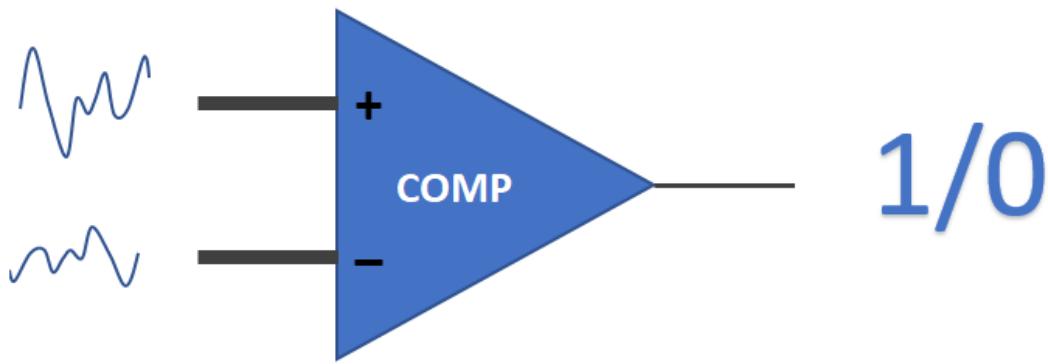
Digital-to-Analogue Converters (DAC)

DACs are opposites of ADCs. They give variable voltage output with respect to binary inputs and can be used to generate waveforms, audio signals, wave patterns, control actuator and power supplies, etc. 12-bit DACs - **DAC12** are available in some advanced MSP430 devices.



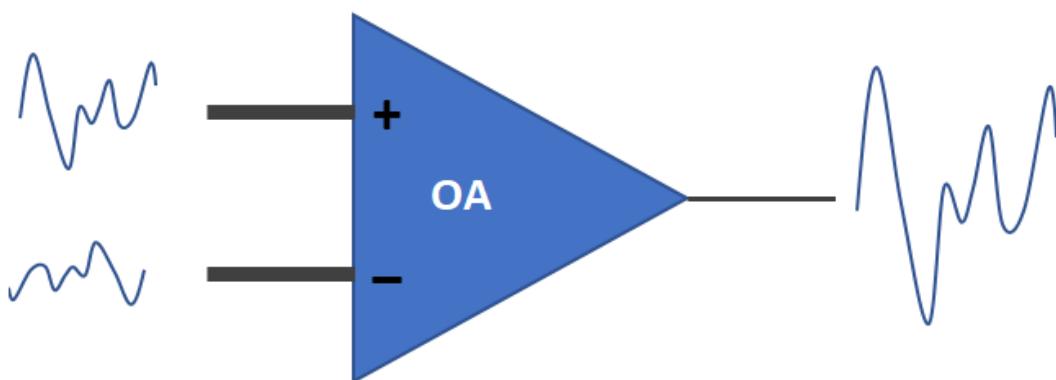
Comparators (COMP)

A comparator compares two analogue voltage levels. This comparison results in an indication of which signal is at a higher/lower voltage level than the other. In simple terms, it is a one-bit ADC. Though it may look that a comparator is unnecessary when we have a good built-in ADC, it is otherwise. A comparator is a very important analogue building block. A whole lot of electronics is based on it. Examples of such electronics include oscillators, level sensing, VU meters, capacitive touch sensing, measurement devices, etc. A LC meter is a perfect example. A LC meter is usually based on an oscillator. This oscillator uses a comparator. Its frequency varies with the L and C components, oscillating at a fixed frequency with known L and C values. Measuring frequency shifts as a result of changing L/C values leads us to measure unknown L/C effectively.



Op-Amps (OA)

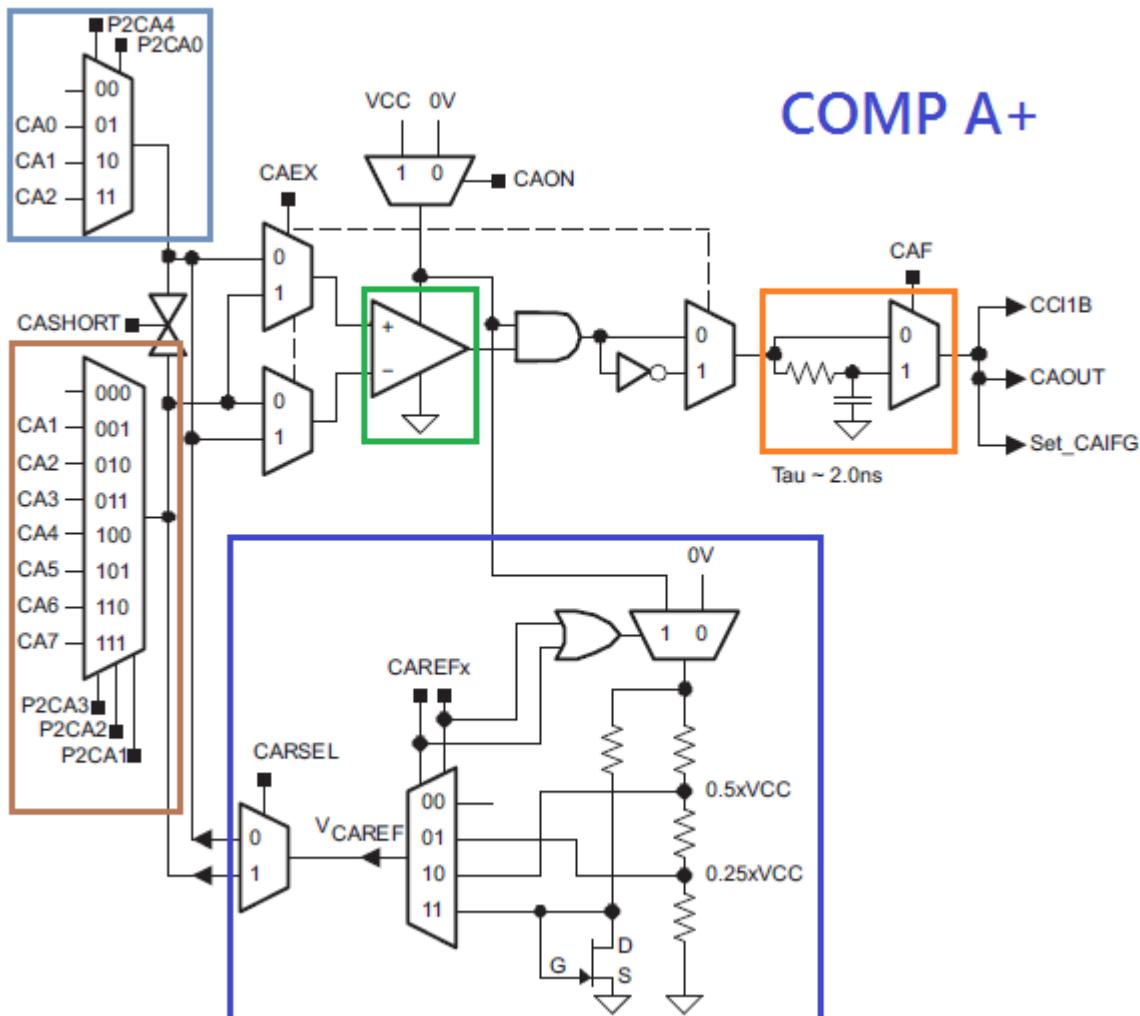
Some MSP430s are equipped with single supply general-purpose Op-Amps. These can be used like any other external Op-Amps but they have wide variety of goodies like PGA built-in. We can use them as comparators (although it is unnecessary in the presence of comparator modules) signal amplifiers, etc. We can also use them to make filters, oscillators, analogue computers, etc.



In this article only ADC10 and COMP_A+ will be discussed. The rest two will be skipped as the MSP430 chips discussed here don't have any more hardware other than these.

Comp_A+ Module

Apart from ADCs MSP430x2xx devices are equipped with an analogue comparator called **Comparator A+** or simply **Comp_A+** module.



Shown above is the block diagram for Comp A+ module. The left most side includes comparator inputs. A good thing to note is that unlike other micros where comparator pins are generally fixed to some dedicated I/Os only, the pins of COMP A+ can be tied with a number of I/O, adding great flexibility in design. The purple region in the centre houses reference sources that can be tied to the comparator inputs. At the comparator output stage (orange area), there is an optional low pass filter. Additionally, comparator inputs can be shorted to remove any stray static. Use GRACE to explore more features of Comp A+.

Code Example

```
#include <msp430.h>
#include "delay.h"

void BCSplus_graceInit(void);
void GPIO_graceInit(void);
void Comparator_Aplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

#pragma vector=COMPARATORA_VECTOR
__interrupt void COMPARATORA_ISR_HOOK(void)
{
    P1OUT ^= BIT0;
    CACTL2 &= ~CAIFG;
}

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430F2xx Comparator_A+ */
    Comparator_Aplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        if (CACTL2 & CAOUT)
        {
            delay_ms(300);
        }

        if (!(CACTL2 & CAOUT))
        {
            delay_ms(100);
        }

        P1OUT ^= BIT6;
    }
}

void BCSplus_graceInit(void)
```

```

/*
 * USER CODE START (section: BCSplus_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: BCSplus_graceInit_prologue) */

/*
 * Basic Clock System Control 2
 *
 * SELM_0 -- DCOCLK
 * DIVM_0 -- Divide by 1
 * ~SELS -- DCOCLK
 * DIVS_0 -- Divide by 1
 * ~DCOR -- DCO uses internal resistor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_8MHZ != 0xFF) {
    /* Adjust this accordingly to your VCC rise time */
    _delay_cycles(100000);

    // Follow recommended flow. First, clear all DC0x and MODx bits. Then
    // apply new RSELx values. Finally, apply new DC0x and MODx bit values.
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_8MHZ;      /* Set DCO to 8MHz */
    DCOCTL = CALDCO_8MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */

```

```

/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Port Select Register */
P1SEL = BIT7;

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT6 | BIT7;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue)
}

void Comparator_Aplus_graceInit(void)
{
    /* USER CODE START (section: Comparator_Aplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: Comparator_Aplus_graceInit_prologue) */

    /* CACTL1 Register */
    CACTL1 = CAREF_2 | CAON | CAIES | CAIE;

    /* CACTL2 Register */
    CACTL2 = P2CA3 | P2CA1;

    /* CAPD, Register */
    CAPD = CAPD5;
}

```

```

/* USER CODE START (section: Comparator_Aplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: Comparator_Aplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

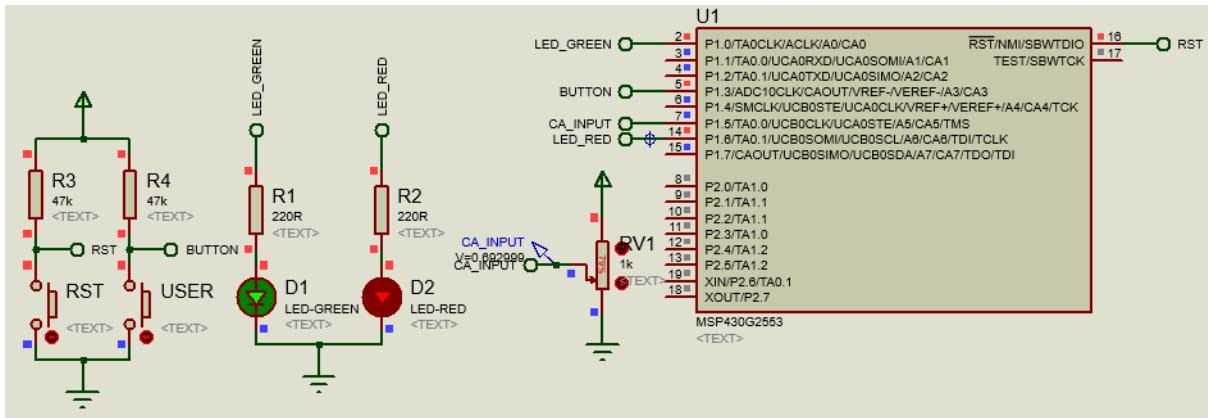
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

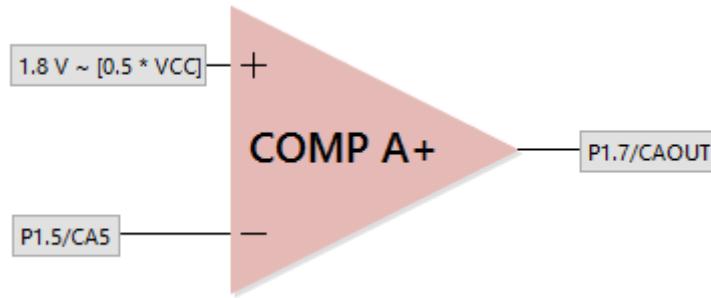
```

Simulation



Explanation

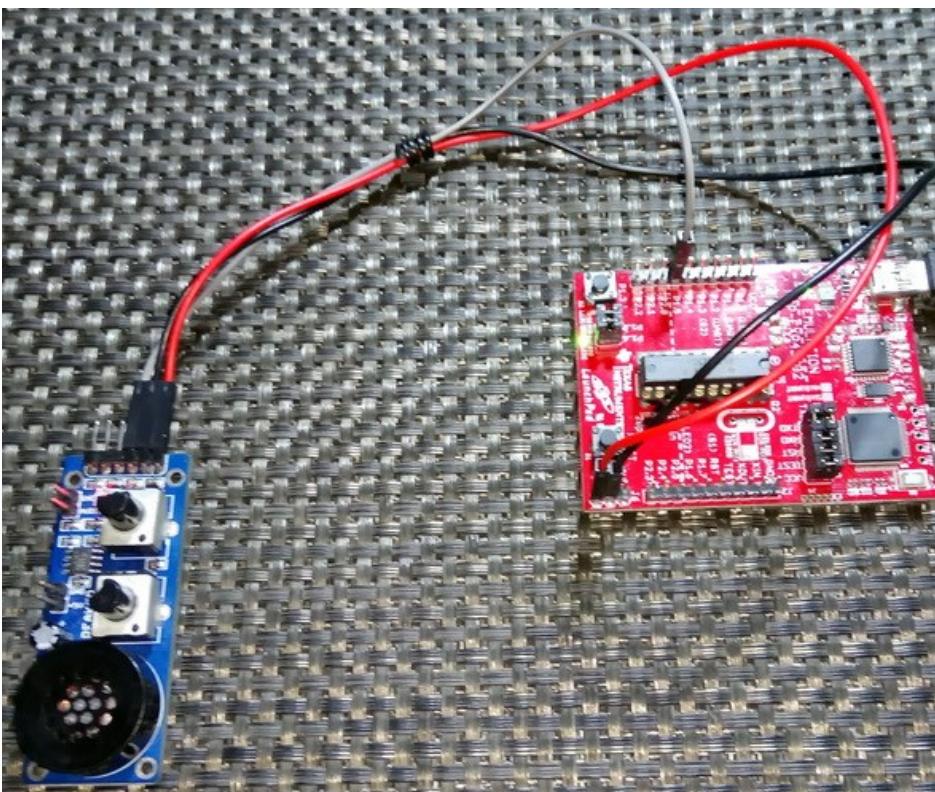
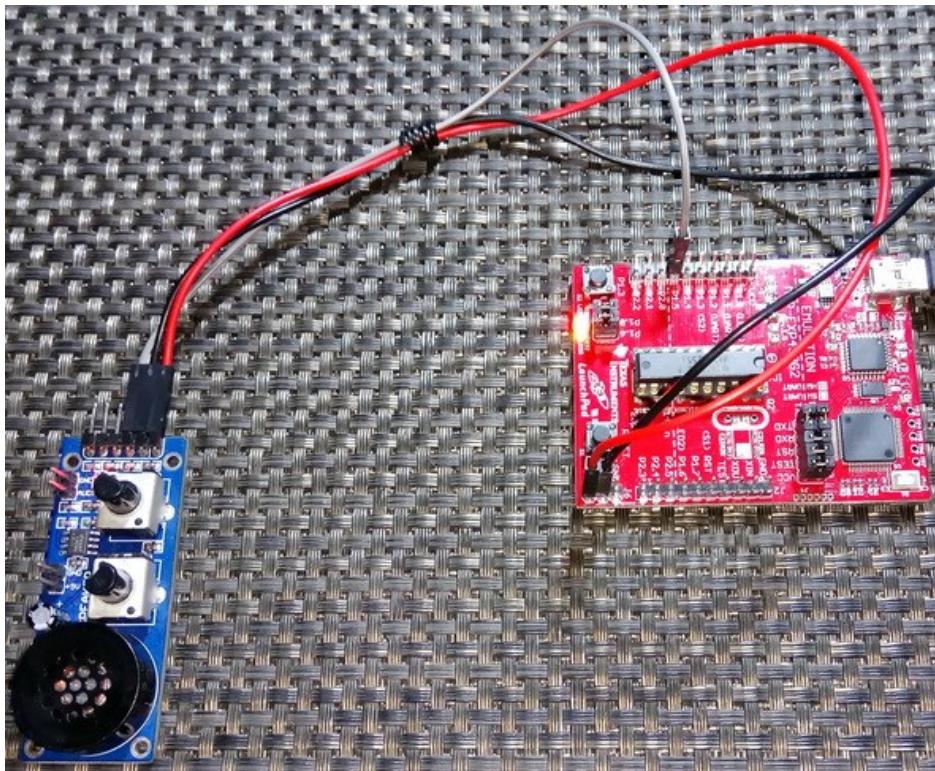
For this demo, a MSP430G2553 is used. Launchpad board's LEDs are used and additionally a potentiometer (pot) is tied to P1.5. The pot has its ends connected to VDD and GND. The internal connection is as shown below:



The code dictates that Comp A+ interrupt will occur on falling edges only. Now the question is whose falling edge? Certainly not the inputs. Interrupt will only occur when there is a logic high-low transition on **CAOUT** pin – P1.7 here. According to the simplified comparator internal connection shown above, this transition will occur only when P1.5's voltage exceeds that of the 1.8V reference. When a Comp_A+ interrupt occurs, P1.0's logic state is toggled.

One thing to note here is the fact that though it is not mandatory to clear comparator interrupt flag, it is wise to clear it after processing the interrupt request.

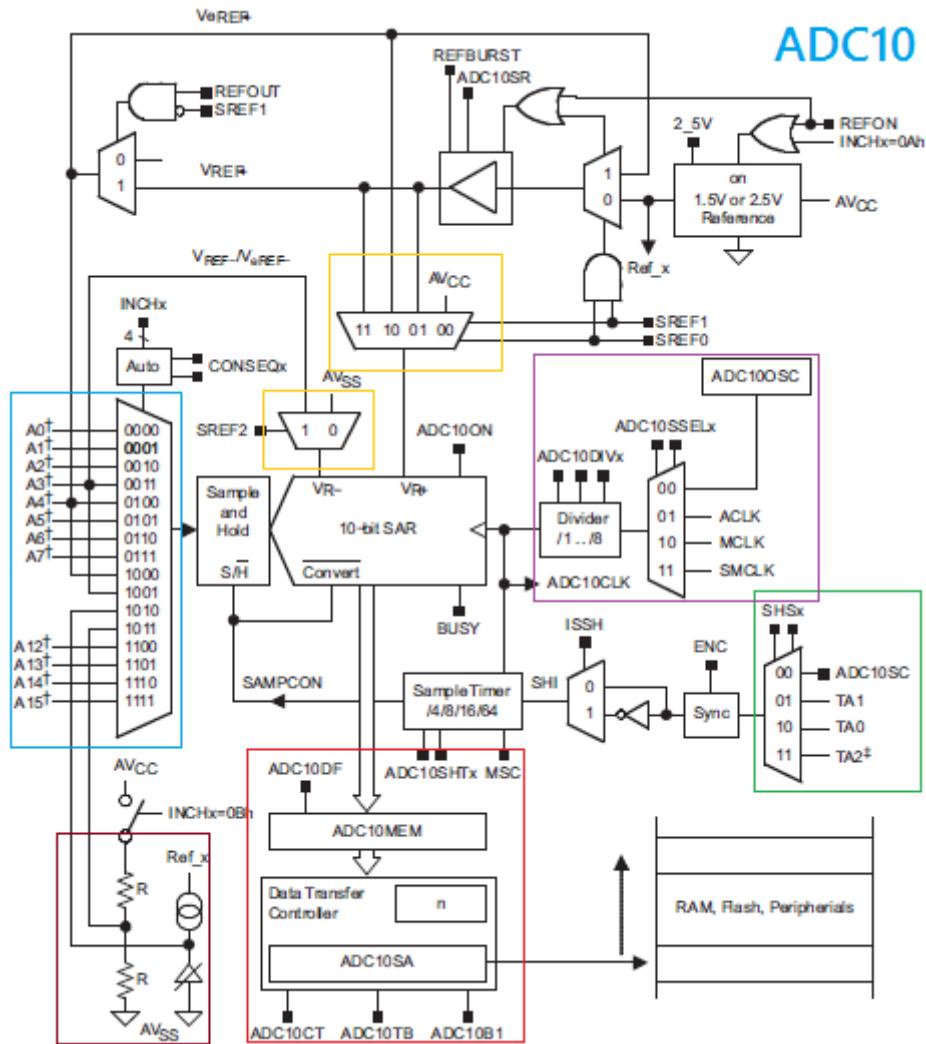
Demo



Demo video: <https://www.youtube.com/watch?v=XIzvhpWopil>.

ADC10

In most value-line devices (VLD) like MSP430G2553 and MSP430G2452, ADC12 is not present and the ADC tasks are accomplished with ADC10 modules.



Shown above is the simple block diagram of the ADC10 module. ADC10 is a SAR ADC. Highlighted segments include:

- ADC channel selector (light blue area) – select the highest channel from where the first ADC conversion starts. An internal counter counts down from this channel all the way down to A0.
- DMA and ADC output (red area) – here we get AD conversion results and can optionally do a peripheral to memory DMA transfer.
- ADC clock source (purple area) – this is the clock source that runs the ADC.
- ADC trigger source (light green area) – selects what triggers the ADC to start a conversion.
- Reference selectors (orange boxes) – selects ADC's positive and negative references.
- Built-in signal sources (Deep red area) – includes on-chip temperature sensor, supply voltage sensing voltage divider, etc.

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "lcd.h"

#define T_offset      -18

void BCSplus_graceInit(void);
void GPIO_graceInit(void);
void ADC10_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
unsigned int get_ADC(unsigned int channel);
unsigned int get_volt(unsigned int value);
unsigned int get_temp(unsigned int value);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value);

void main(void)
{
    unsigned char n = 0;

    unsigned int res = 0;
    unsigned int ADC_Value = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 10-bit Analog to Digital Converter (ADC)
*/
    ADC10_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    LCD_init();
    LCD_clear_home();

    while(1)
    {
        if((P1IN & BIT3) == 0)
        {
            P1OUT |= BIT6;
            while((P1IN & BIT3) == 0);

            n++;
        }
    }
}
```

```

        if(n > 2)
        {
            n = 0;
        }
        P1OUT &= ~BIT6;
    }

    switch(n)
    {
        case 1:
        {
            ADC_Value = get_ADC(INCH_1);
            res = get_volt(ADC_Value);

            LCD_goto(0, 0);
            LCD_putstr("ADC Ch01:");
            LCD_goto(0, 1);
            LCD_putstr("Volts/mV:");
            break;
        }
        case 2:
        {
            ADC_Value = get_ADC(INCH_2);
            res = get_volt(ADC_Value);

            LCD_goto(0, 0);
            LCD_putstr("ADC Ch02:");
            LCD_goto(0, 1);
            LCD_putstr("Volts/mV:");
            break;
        }
        default:
        {
            ADC_Value = get_ADC(INCH_10);
            res = get_temp(get_volt(ADC_Value));

            LCD_goto(0, 0);
            LCD_putstr("ADC Ch10:");
            LCD_goto(0, 1);
            LCD_putstr("TC/Deg.C:");
            break;
        }
    }

    lcd_print(12, 0, ADC_Value);
    lcd_print(12, 1, res);
    delay_ms(200);
};

}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = BIT3;
}

```

```

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT6;

/* Port 1 Resistor Enable Register */
P1REN = BIT3;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = BIT0 | BIT1 | BIT2 | BIT3 | BIT4 | BIT5;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;
}

```

```

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;          /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void ADC10_graceInit(void)
{
    /* USER CODE START (section: ADC10_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: ADC10_graceInit_prologue) */

    /* disable ADC10 during initialization */
    ADC10CTL0 &= ~ENC;

    /*
     * Control Register 0
     *
     * ~ADC10SC -- No conversion
     * ~ENC -- Disable ADC
     * ~ADC10IFG -- Clear ADC interrupt flag
     * ~ADC10IE -- Disable ADC interrupt
     * ADC10ON -- Switch On ADC10
     * ~REFON -- Disable ADC reference generator
     * ~REF2_5V -- Set reference voltage generator = 1.5V
     * ~MSC -- Disable multiple sample and conversion
     * ~REFBURST -- Reference buffer on continuously
     * ~REFOUT -- Reference output off
     * ~ADC10SR -- Reference buffer supports up to ~200 ksps
    */
}

```

```

/*
 * ADC10SHT_3 -- 64 x ADC10CLKs
 * SREF_0 -- VR+ = VCC and VR- = VSS
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL0 = ADC10ON | ADC10SHT_3 | SREF_0;

/*
 * Control Register 1
 *
 * ~ADC10BUSY -- No operation is active
 * CONSEQ_2 -- Repeat single channel
 * ADC10SSEL_3 -- SMCLK
 * ADC10DIV_3 -- Divide by 4
 * ~ISSH -- Input signal not inverted
 * ~ADC10DF -- ADC10 Data Format as binary
 * SHS_0 -- ADC10SC
 * INCH_10 -- Temperature Sensor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL1 = CONSEQ_2 | ADC10SSEL_3 | ADC10DIV_3 | SHS_0;

/* Analog (Input) Enable Control Register 0 */
ADC10AE0 = 0x6;

/* enable ADC10 */
ADC10CTL0 |= ENC;

/* USER CODE START (section: ADC10_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: ADC10_graceInit_epilogue) */
}

void System_graceInit(void)
{
/* USER CODE START (section: System_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: System_graceInit_prologue) */

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
_bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

```

```

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

unsigned int get_ADC(unsigned int channel)
{
    P1OUT ^= BIT0;
    ADC10CTL0 &= ~ENC;
    ADC10CTL1 &= ~(0xF000);
    ADC10CTL1 |= channel;
    ADC10CTL0 |= ENC;
    ADC10CTL0 |= ADC10SC;
    while ((ADC10CTL0 & ADC10IFG) == 0);

    return ADC10MEM;
}

unsigned int get_volt(unsigned int value)
{
    return (unsigned int)((value * 3600.0) / 1023.0);
}

unsigned int get_temp(unsigned int value)
{
    return (unsigned int)(((value / 1000.0) - 0.986) / 0.00355) + T_offset;
}

```

```

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value)
{
    char chr = 0x00;

    chr = ((value / 1000) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(chr);

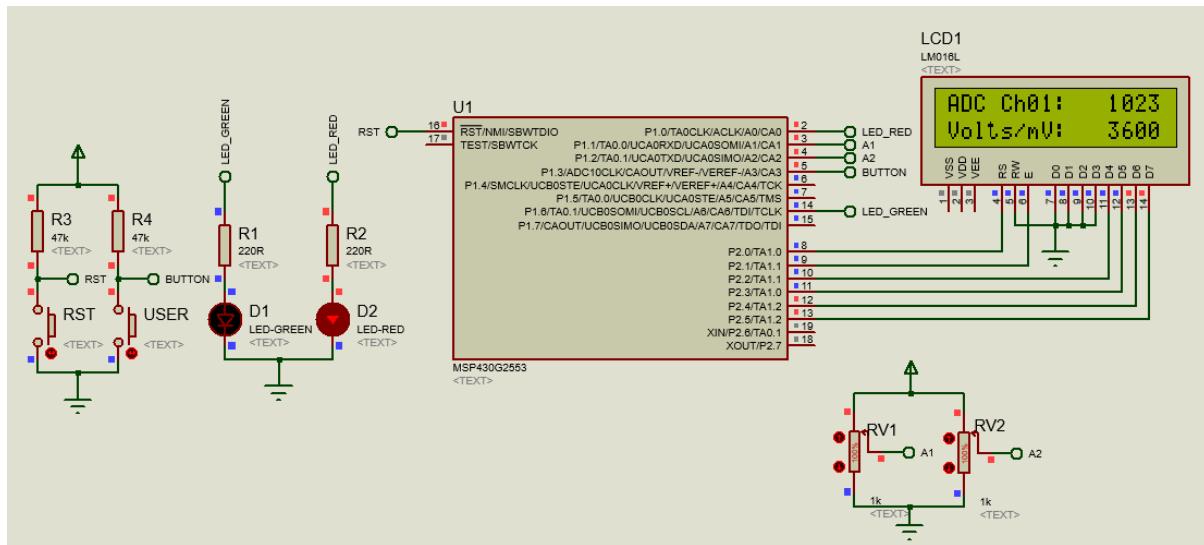
    chr = (((value / 100) % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(chr);

    chr = (((value / 10) % 10) + 0x30);
    LCD_goto((x_pos + 2), y_pos);
    LCD_putchar(chr);

    chr = ((value % 10) + 0x30);
    LCD_goto((x_pos + 3), y_pos);
    LCD_putchar(chr);
}

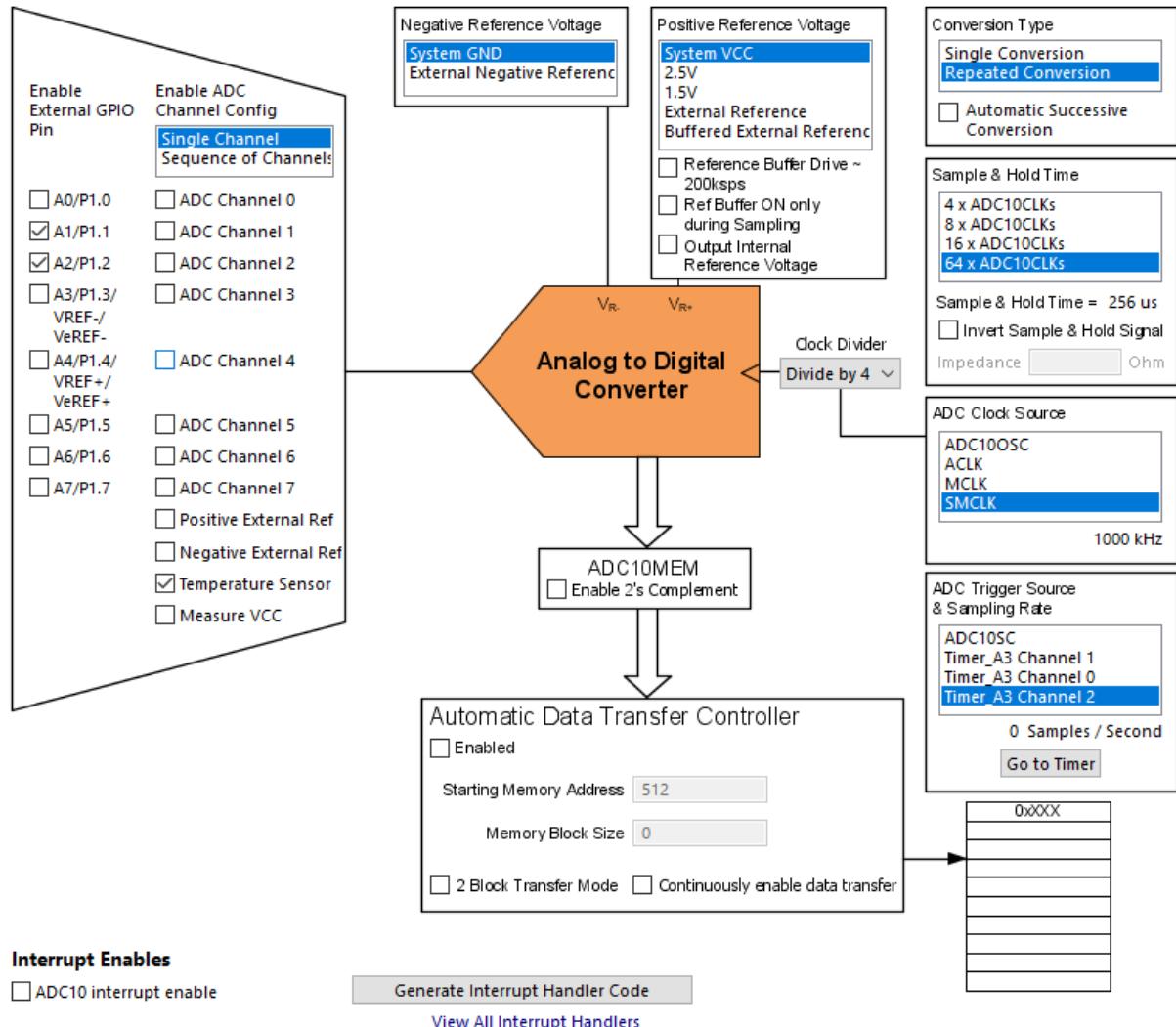
```

Simulation



Explanation

ADC10 is set up initially as depicted below:



Note that we are not using ADC10 interrupt and enabled two external channels (A1 and A2) although only the temperature sensor channel is selected for conversion. The internal temperature sensor has the highest channel number (channel 10) after VDD measurement channel (channel 11). If we also want to sense A1 and A2 along with the internal temperature sensor, we have to select all channels from channel 0 to channel 10 even when we don't want the others. This is so because in sequence scan mode conversion, all channels are scanned from the highest channel to channel 0. The other way to sense only the desired channels is to sense them one at a time i.e. as single channels. The latter method is used here.

```
unsigned int get_ADC(unsigned int channel)
{
    P1OUT ^= BIT0;
    ADC10CTL0 &= ~ENC;
    ADC10CTL1 &= ~(0xF000);
    ADC10CTL1 |= channel;
```

```

ADC10CTL0 |= ENC;

ADC10CTL0 |= ADC10SC;
while ((ADC10CTL0 & ADC10IFG) == 0);

return ADC10MEM;
}

```

The function above first disables the momentarily and clears channel number or count. Then the desired channel is chosen. AD conversion is started following ADC restart and we wait for AD conversion completion. At the end of the conversion ADC result is extracted and returned.

In the main loop, we simply select channel using the Launchpad user button and display ADC data on a LCD. For ease, I demoed ADC10 using two external channels (A1 and A2) and one internal ADC channel – the internal temperature sensor.

```

switch(n)
{
    case 1:
    {
        ADC_Value = get_ADC(INCH_1);
        res = get_volt(ADC_Value);

        LCD_goto(0, 0);
        LCD_putstr("ADC Ch01:");
        LCD_goto(0, 1);
        LCD_putstr("Volts/mV:");
        break;
    }
    case 2:
    {
        ADC_Value = get_ADC(INCH_2);
        res = get_volt(ADC_Value);

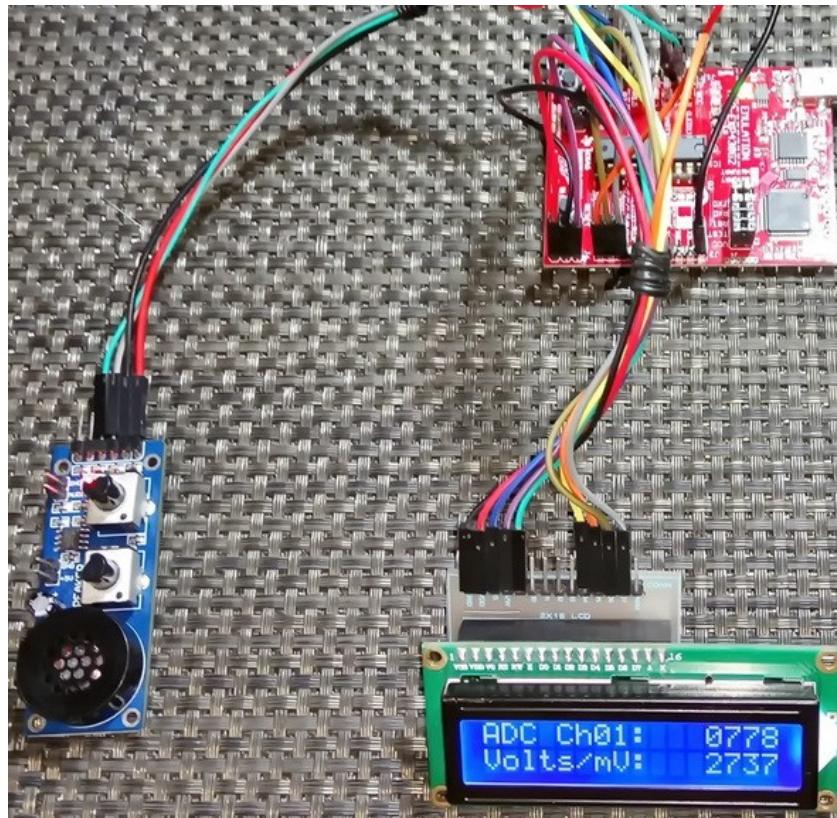
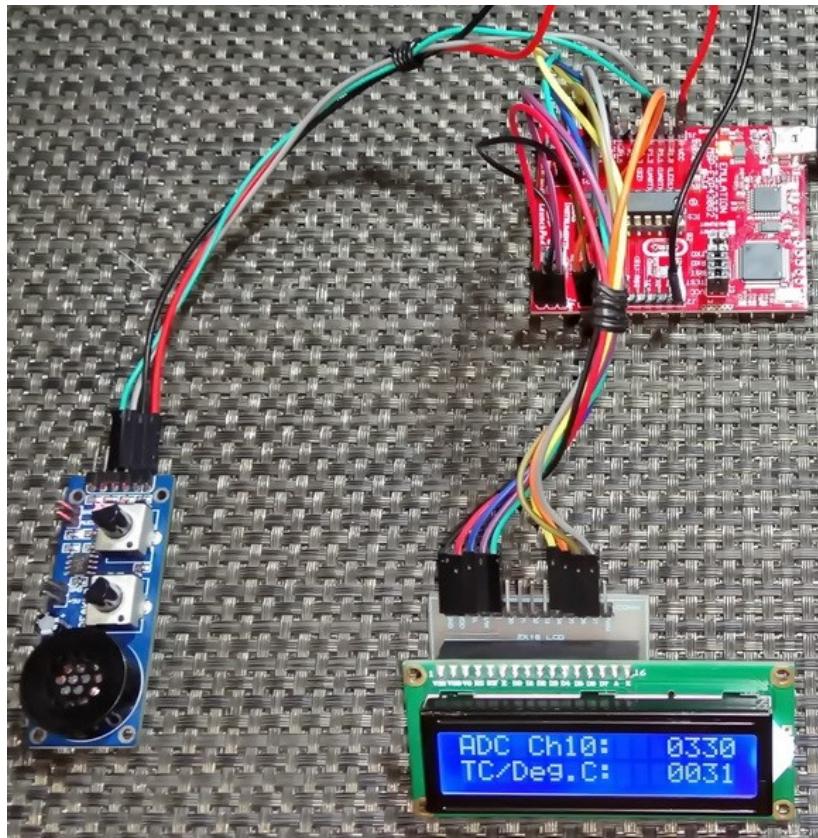
        LCD_goto(0, 0);
        LCD_putstr("ADC Ch02:");
        LCD_goto(0, 1);
        LCD_putstr("Volts/mV:");
        break;
    }
    default:
    {
        ADC_Value = get_ADC(INCH_10);
        res = get_temp(get_volt(ADC_Value));

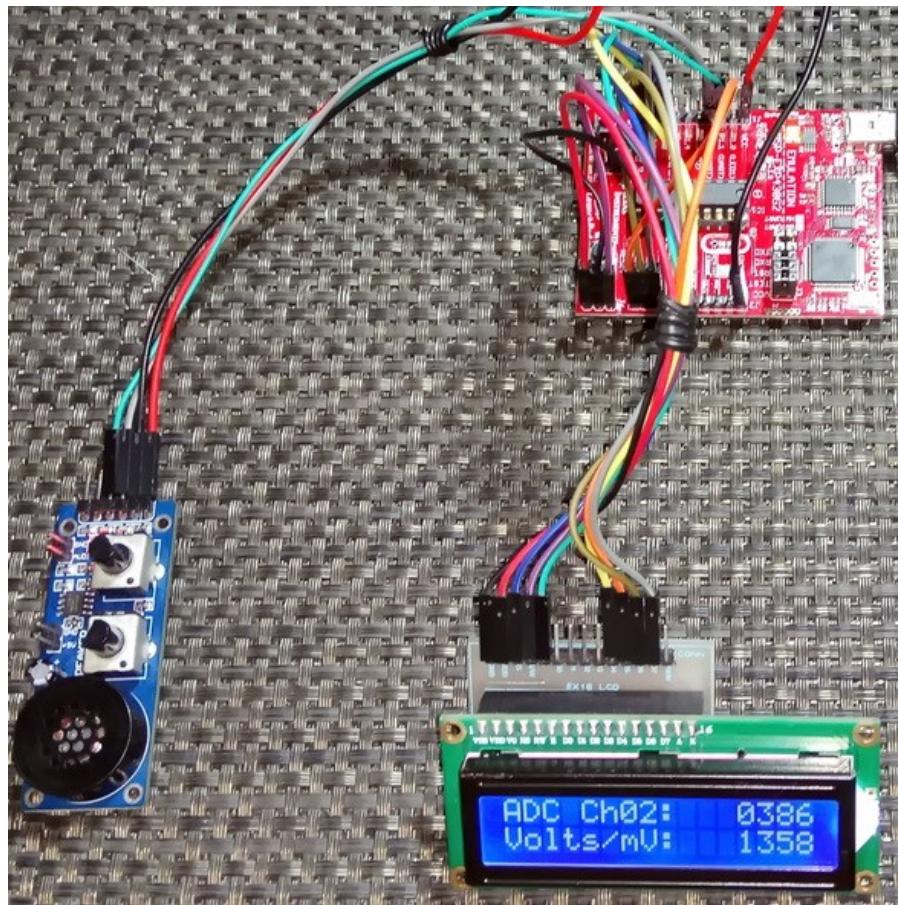
        LCD_goto(0, 0);
        LCD_putstr("ADC Ch10:");
        LCD_goto(0, 1);
        LCD_putstr("TC/Deg.C:");
        break;
    }
}

lcd_print(12, 0, ADC_Value);
lcd_print(12, 1, res);
delay_ms(200);

```

Demo

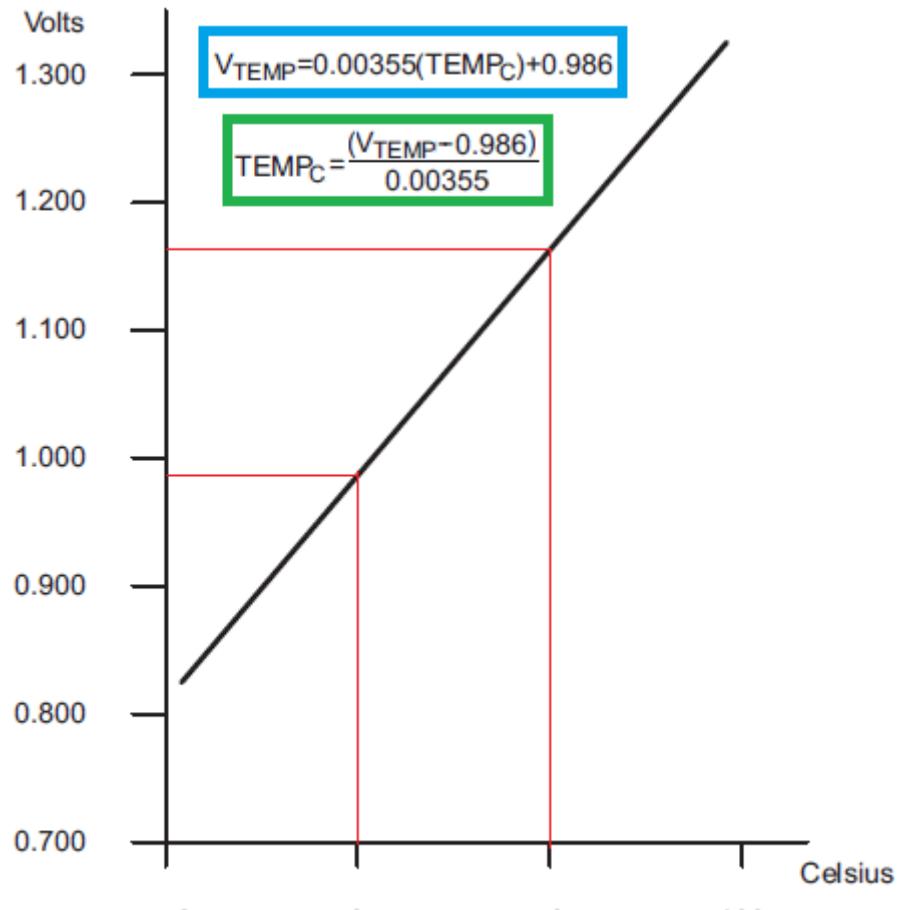




Demo video: https://www.youtube.com/watch?v=M_txQs2ajdk.

ADC10 Interrupt

In previous example, we didn't use ADC10 interrupt and the code was based on polling. ADC interrupts are as important as timer interrupts. We can start an ADC and extract conversion data in an orderly manner when conversion is complete. No other process waits for the ADC, freeing up the CPU.



Typical Temperature Sensor Transfer Function

Many present-day microcontrollers have on-chip temperature sensors. While many people think they are just mere additions, they are not. Such sensors have a number of applications – most notably correction of ADC readings with temperature drift. Other applications include thermal protection, temperature compensations, temperature reference, etc. However, these sensors are not meant to be as precise and accurate as dedicated temperature sensor chips like LM35 and DS18B20. This makes them highly unsuitable for measurements of wide range of temperatures and unsuitable for reliable readings. Shown above is the typical voltage output vs temperature graph of MSP430G2xx devices' internal temperature sensor. Though it is linear, the word "*typical*" is indirectly telling us that there can be some deviations.

In this example, we will see how to read the internal temperature sensor of a MSP430G2xx micro using ADC10 interrupt.

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "lcd.h"

#define T_offset      -18

unsigned int ADC_Value = 0;

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void ADC10_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
unsigned int get_volt(unsigned int value);
unsigned int get_temp(unsigned int value);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value);

#pragma vector = ADC10_VECTOR
__interrupt void ADC10_ISR_HOOK(void)
{
    P1OUT ^= BIT0;
    ADC_Value = ADC10MEM;
    ADC10CTL0 &= ~ADC10IFG;
}

void main(void)
{
    signed int t = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 10-bit Analog to Digital Converter (ADC) */
    /* */
    ADC10_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    LCD_init();
    LCD_clear_home();
    LCD_goto(0, 0);
    LCD_putstr("ADC Value:");
}
```

```

LCD_goto(0, 1);
LCD_putstr("Tmp/Deg.C:");

while(1)
{
    // ADC Start Conversion - Software trigger
    ADC10CTL0 |= ADC10SC;

    P1OUT ^= BIT6;

    t = get_volt(ADC_Value);
    t = get_temp(t);

    lcd_print(12, 0, ADC_Value);
    lcd_print(12, 1, t);
    delay_ms(200);
};

void GPIO_graceInit(void)
{
    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Direction Register */
    P1DIR = BIT0 | BIT6;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Port Select Register */
    P2SEL &= ~(BIT6 | BIT7);

    /* Port 2 Direction Register */
    P2DIR = BIT0 | BIT1 | BIT2 | BIT3 | BIT4 | BIT5;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* Port 3 Output Register */
    P3OUT = 0;

    /* Port 3 Direction Register */
    P3DIR = 0;
}

void BCSplus_graceInit(void)
{

```

```

/*
 * Basic Clock System Control 2
 *
 * SELM_0 -- DCOCLK
 * DIVM_0 -- Divide by 1
 * ~SELS -- DCOCLK
 * DIVS_0 -- Divide by 1
 * ~DCOR -- DCO uses internal resistor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_12MHZ != 0xFF)
{
    /* Adjust this accordingly to your VCC rise time */
    _delay_cycles(1000);

    /* Follow recommended flow. First, clear all DC0x and MODx bits. Then
     * apply new RSELx values. Finally, apply new DC0x and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_12MHZ;      /* Set DCO to 12MHz */
    DCOCTL = CALDCO_12MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;
}

void ADC10_graceInit(void)
{
    /* disable ADC10 during initialization */
    ADC10CTL0 &= ~ENC;

    /*
     * Control Register 0
     *
     * ~ADC10SC -- No conversion
     * ~ENC -- Disable ADC

```

```

* ~ADC10IFG -- Clear ADC interrupt flag
* ADC10IE -- Enable ADC interrupt
* ADC10ON -- Switch On ADC10
* ~REFON -- Disable ADC reference generator
* ~REF2_5V -- Set reference voltage generator = 1.5V
* MSC -- Enable multiple sample and conversion
* ~REFBURST -- Reference buffer on continuously
* ~REFOUT -- Reference output off
* ADC10SR -- Reference buffer supports up to ~50 ksps
* ADC10SHT_3 -- 64 x ADC10CLKs
* SREF_0 -- VR+ = VCC and VR- = VSS
*
* Note: ~<BIT> indicates that <BIT> has value zero
*/
ADC10CTL0 = ADC10IE | ADC10ON | MSC | ADC10SR | ADC10SHT_3 | SREF_0;

/*
* Control Register 1
*
* ~ADC10BUSY -- No operation is active
* CONSEQ_2 -- Repeat single channel
* ADC10SSEL_3 -- SMCLK
* ADC10DIV_7 -- Divide by 8
* ~ISSH -- Input signal not inverted
* ~ADC10DF -- ADC10 Data Format as binary
* SHS_0 -- ADC10SC
* INCH_10 -- Temperature Sensor
*
* Note: ~<BIT> indicates that <BIT> has value zero
*/
ADC10CTL1 = CONSEQ_2 | ADC10SSEL_3 | ADC10DIV_7 | SHS_0 | INCH_10;

/* enable ADC10 */
ADC10CTL0 |= ENC;
}

void System_graceInit(void)
{
    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(600);
    } while (IFG1 & OFIFG);

    /*
    * SR, Status Register
    *
    * ~SCG1 -- Disable System clock generator 1
    * ~SCG0 -- Disable System clock generator 0
    * ~OSCOFF -- Oscillator On
    * ~CPUOFF -- CPU On
    * GIE -- General interrupt enable
    */
}

```

```

        * Note: ~<BIT> indicates that <BIT> has value zero
        */
        __bis_SR_register(GIE);
    }

void WDTplus_graceInit(void)
{
/*
 * WDTCTL, Watchdog Timer+ Register
 *
 * WDTPW -- Watchdog password
 * WDTHOLD -- Watchdog timer+ is stopped
 * ~WDTNMIES -- NMI on rising edge
 * ~WDTNMI -- Reset function
 * ~WDTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * ~WDTSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;
}

unsigned int get_volt(unsigned int value)
{
    return (unsigned int)((value * 3600.0) / 1023.0);
}

unsigned int get_temp(unsigned int value)
{
    return (unsigned int)(((value / 1000.0) - 0.986) / 0.00355) + T_offset;
}

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value)
{
    char chr = 0x00;

    chr = ((value / 1000) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(chr);

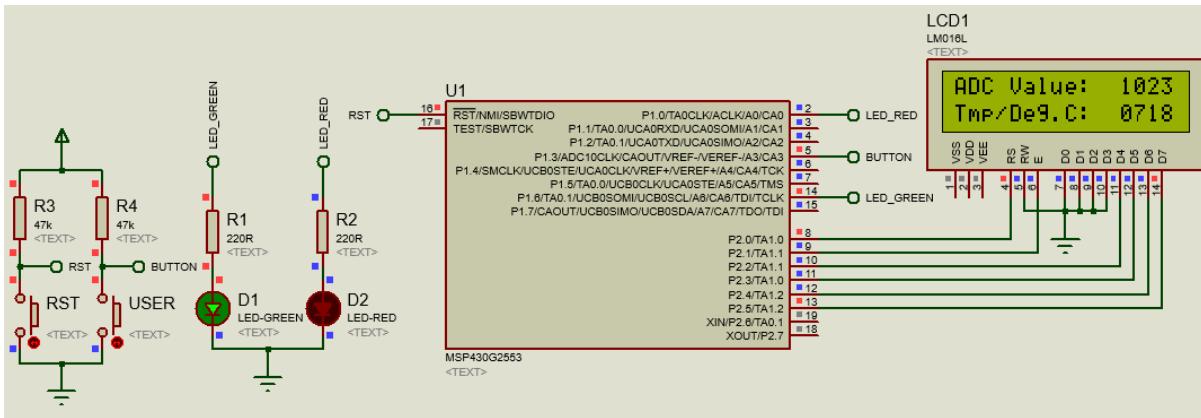
    chr = (((value / 100) % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(chr);

    chr = (((value / 10) % 10) + 0x30);
    LCD_goto((x_pos + 2), y_pos);
    LCD_putchar(chr);

    chr = ((value % 10) + 0x30);
    LCD_goto((x_pos + 3), y_pos);
    LCD_putchar(chr);
}

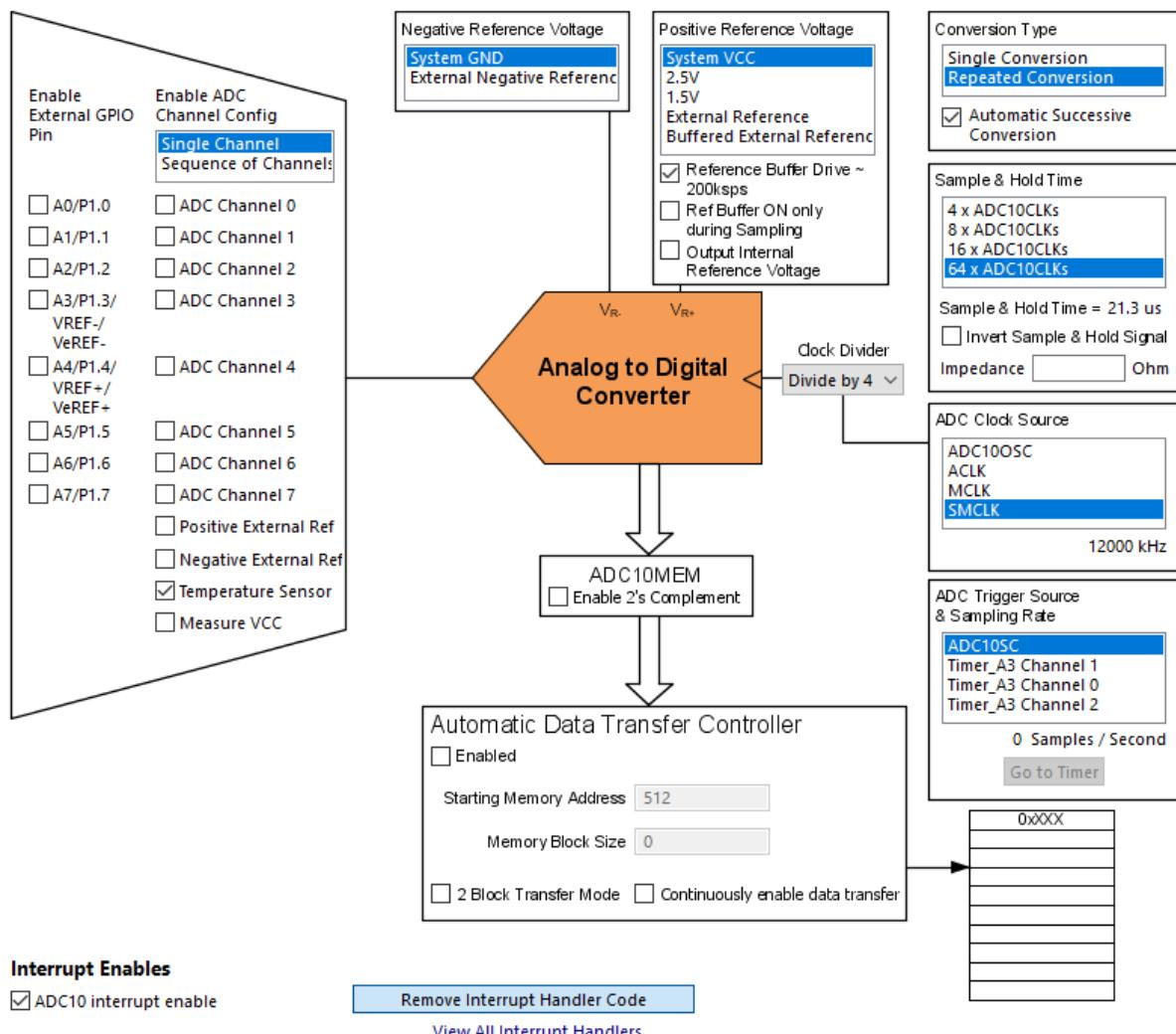
```

Simulation



*Note Proteus VSM cannot simulate internal temperature sensor. The simulation here only shows connections. The readouts are misleading.

Explanation



ADC10 setup is similar to the setup we have seen in the last example. However, this time we enabled ADC10 interrupt as this is an interrupt-based demo.

The ADC ISR is simple. Here we are just toggling P1.0 LED to indicate ADC conversion completion and clearing ADC interrupt flag after reading ADC data value.

```
#pragma vector = ADC10_VECTOR
__interrupt void ADC10_ISR_HOOK(void)
{
    P1OUT ^= BIT0;
    ADC_Value = ADC10MEM;
    ADC10CTL0 &= ~ADC10IFG;
}
```

In the main loop, AD conversion process starts using software trigger. The result of this conversion is extracted from the ADC ISR shown above. The ADC data obtained from the ISR is shown on a LCD. Two values are shown – actual ADC count and the corresponding temperature against that ADC readout.

```
// ADC Start Conversion - Software trigger
ADC10CTL0 |= ADC10SC;

P1OUT ^= BIT6;

t = get_volt(ADC_Value);
t = get_temp(t);

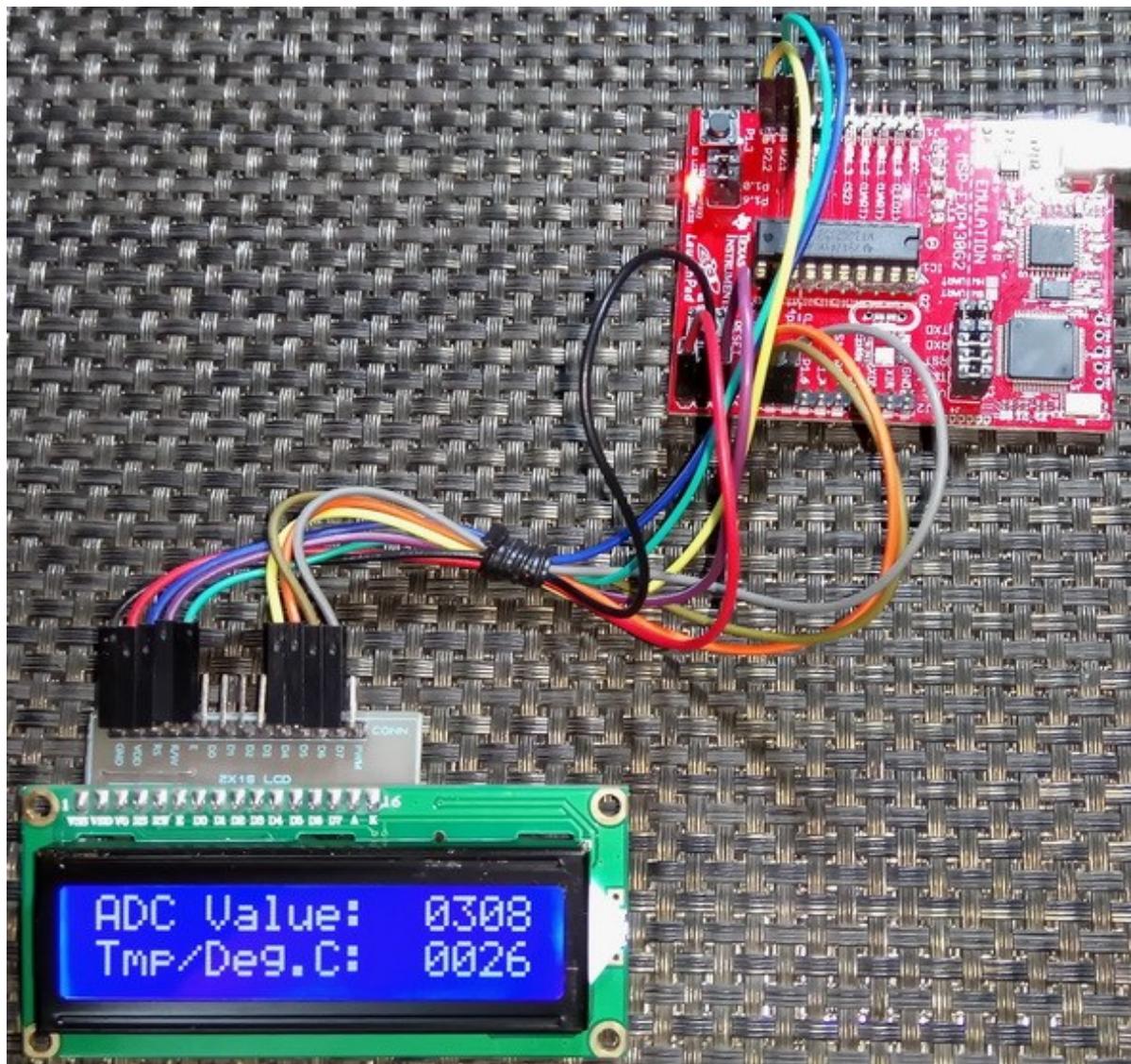
lcd_print(12, 0, ADC_Value);
lcd_print(12, 1, t);
delay_ms(200);
```

To extract temperature in degree Celsius, first the ADC count is converted to millivolts and then this voltage value is translated to temperature value using the voltage vs temperature transfer function shown earlier. *T_offset* is an optional constant that is used to negate any offset in temperature readout.

```
unsigned int get_volt(unsigned int value)
{
    return (unsigned int)((value * 3600.0) / 1023.0);
}

unsigned int get_temp(unsigned int value)
{
    return (unsigned int)((((value / 1000.0) - 0.986) / 0.00355) + T_offset);
```

Demo



Demo video: <https://www.youtube.com/watch?v=XOll3Vfjfb8>.

ADC10 with Direct Memory Access (DMA)

The concept of Direct Memory Access (DMA) or Data Transfer Controller (DTC) is usually found in 32-bit ARM-Cortex-based micros and in some highly advanced DSP microcontrollers. In recent times, a few new generation 8-bit and 16-bit devices have emerged with DMA hardware feature. The DMA hardware may look a bit complicated for those who are new to it but it is practically very simple. Just consider what you have been doing all these times without DMA. Consider an ADC for an example. Without DMA, the ADC senses its channel(s) and saves sensed data on an ADC result register waiting to be read and continue the same operation over and over again. This process involves the CPU very often as sensing/extracting analog data, storing it and starting ADC conversion all needs CPU's attention. Thus, the CPU bus is always busy with these engagements. With DMA the process becomes more automatic and intelligent. The DMA controller automatically transfers AD conversion data to specified memory location(s) using its separate data bus. In the whole process the CPU is not involved much. Conversions take place and the conversion results are immediately transferred. Thus, the process becomes both autonomous and fast.

Please note that the DMA bus is only available for ADC to memory or in other words peripheral to memory transfers. It cannot be used for other peripherals like USCI, USI, etc. or for memory-memory transfers. However, it is not a big issue for now.

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"

#define no_of_samples      16

unsigned int adc_pointer[no_of_samples];

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void ADC10_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value);

void main(void)
{
    unsigned char s = 0;
    unsigned int adc_avg = 0;
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
```

```

GPIO_graceInit();

/* initialize Config for the MSP430 2xx family clock systems (BCS) */
BCSplus_graceInit();

/* initialize Config for the MSP430 10-bit Analog to Digital Converter (ADC)
*/
ADC10_graceInit();

/* initialize Config for the MSP430 System Registers */
System_graceInit();

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

LCD_init();
LCD_clear_home();

LCD_goto(0, 0);
LCD_putstr("MSP430 ADC + DMA:");

LCD_goto(0, 1);
LCD_putstr("A1:");

while(1)
{
    adc_avg = 0;
    P1OUT |= BIT0;
    ADC10CTL0 &= ~ENC;
    while (ADC10CTL1 & BUSY);
    ADC10CTL0 |= (ENC | ADC10SC);

    for(s = 0; s < no_of_samples; s++)
    {
        adc_avg += adc_pointer[s];
    }

    adc_avg = (adc_avg / no_of_samples);
    lcd_print(12, 1, adc_avg);
    delay_ms(100);
    P1OUT &= ~BIT0;
    delay_ms(100);
};

}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Direction Register */
    P1DIR = BIT0;
}

```

```

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF)
    {
        /* Adjust this accordingly to your VCC rise time */
        __delay_cycles(100000);

        // Follow recommended flow. First, clear all DCOx and MODx bits. Then
        // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_8MHZ;      /* Set DCO to 8MHz */
        DCOCTL = CALDCO_8MHZ;
    }

    /*
     * Basic Clock System Control 1
     */
}

```

```

    * XT2OFF -- Disable XT2CLK
    * ~XTS -- Low Frequency
    * DIVA_0 -- Divide by 1
    *
    * Note: ~XTS indicates that XTS has value zero
    */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void ADC10_graceInit(void)
{
/* USER CODE START (section: ADC10_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: ADC10_graceInit_prologue) */

/* disable ADC10 during initialization */
ADC10CTL0 &= ~ENC;

/*
 * Control Register 0
 *
 * ~ADC10SC -- No conversion
 * ~ENC -- Disable ADC
 * ~ADC10IFG -- Clear ADC interrupt flag
 * ~ADC10IE -- Disable ADC interrupt
 * ADC10ON -- Switch On ADC10
 * ~REFON -- Disable ADC reference generator
 * ~REF2_5V -- Set reference voltage generator = 1.5V
 * MSC -- Enable multiple sample and conversion
 * ~REFBURST -- Reference buffer on continuously
 * ~REFOUT -- Reference output off
 * ~ADC10SR -- Reference buffer supports up to ~200 ksps
 * ADC10SHT_2 -- 16 x ADC10CLKs
 * SREF_0 -- VR+ = VCC and VR- = VSS
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL0 = ADC10ON | MSC | ADC10SHT_2 | SREF_0;

/*
 * Control Register 1
 *
 * ~ADC10BUSY -- No operation is active
 * CONSEQ_2 -- Repeat single channel

```

```

/*
 * ADC10SSEL_0 -- ADC10OSC
 * ADC10DIV_0 -- Divide by 1
 * ~ISSH -- Input signal not inverted
 * ~ADC10DF -- ADC10 Data Format as binary
 * SHS_0 -- ADC10SC
 * INCH_1 -- ADC Channel 1
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL1 = CONSEQ_2 | ADC10SSEL_0 | ADC10DIV_0 | SHS_0 | INCH_1;

/* Analog (Input) Enable Control Register 0 */
ADC10AE0 = 0x2;

/*
 * Data Transfer Control Register 0
 *
 * ~ADC10TB -- One-block transfer mode
 * ADC10CT -- Data is transferred continuously after every conversion
 *
 * Note: ~ADC10TB indicates that ADC10TB has value zero
 */
ADC10DTC0 = ADC10CT;

/* Data Transfer Control Register 1 */
ADC10DTC1 = no_of_samples;

/* Data Transfer Start Address */
ADC10SA = ((unsigned int)adc_pointer);

/* enable ADC10 */
ADC10CTL0 |= ENC;

/* USER CODE START (section: ADC10_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: ADC10_graceInit_epilogue) */
}

void System_graceInit(void)
{
/* USER CODE START (section: System_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: System_graceInit_prologue) */

/* Clear oscillator fault flag with software delay */
do
{
    // Clear OSC fault flag
    IFG1 &= ~OFIFG;

    // 50us delay
    __delay_cycles(400);
} while (IFG1 & OFIFG);

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1

```

```

    * ~SCG0 -- Disable System clock generator 0
    * ~OSCOFF -- Oscillator On
    * ~CPUOFF -- CPU On
    * GIE -- General interrupt enable
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
_bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value)
{
    char chr = 0;

    chr = ((value / 1000) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(chr);

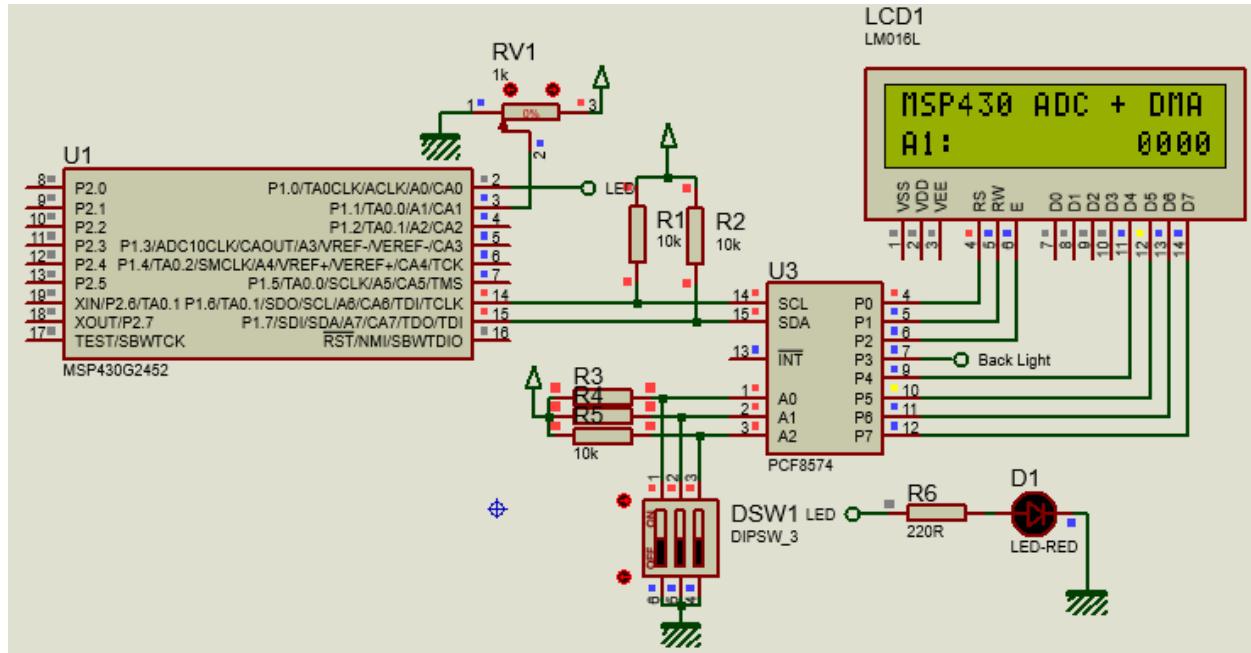
    chr = (((value / 100) % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(chr);

    chr = (((value / 10) % 10) + 0x30);
    LCD_goto((x_pos + 2), y_pos);
    LCD_putchar(chr);
}

```

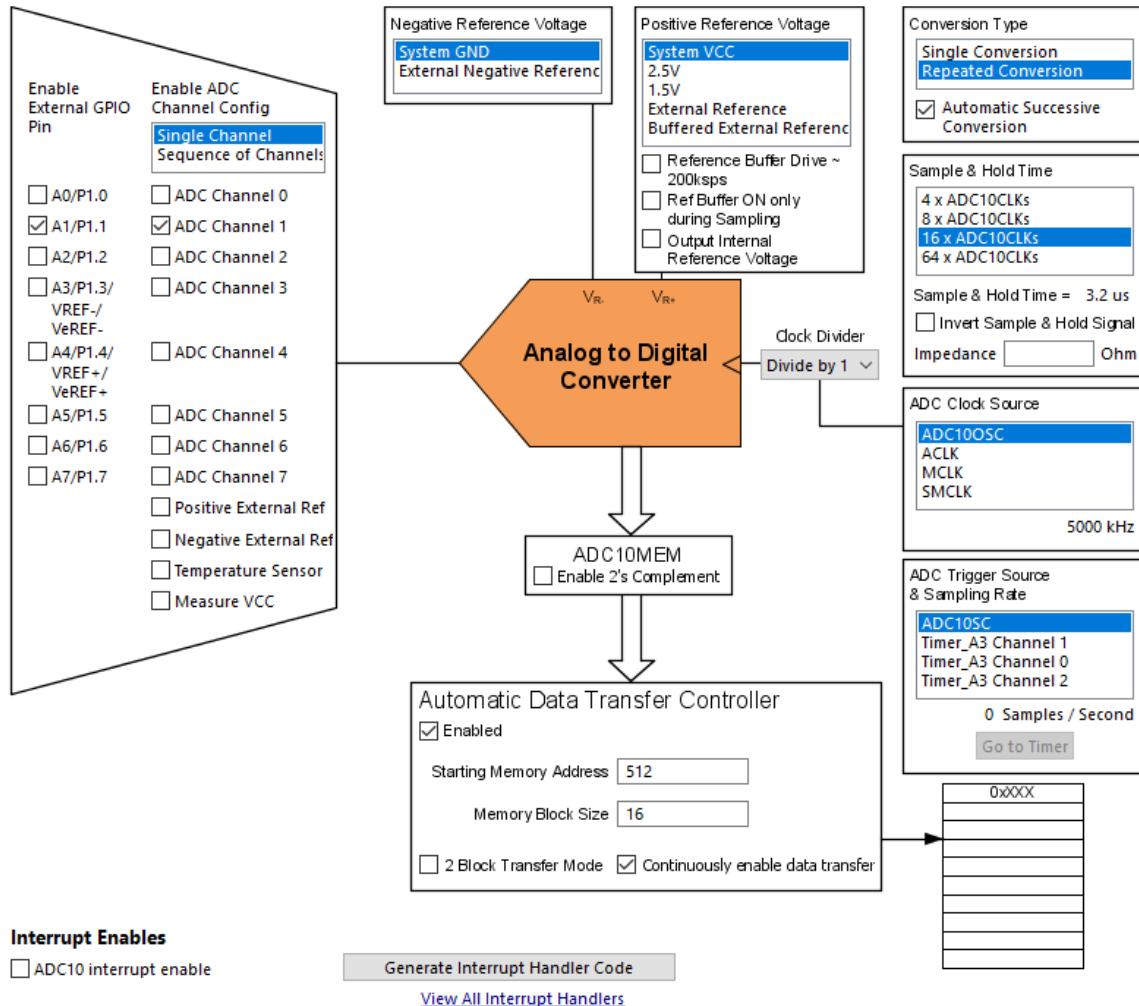
```
    chr = ((value % 10) + 0x30);  
    LCD_goto((x_pos + 3), y_pos);  
    LCD_putchar(chr);  
}
```

Simulation



Explanation

Use **Power User** setup screen of Grace to configure the DTC. Observe the setup as shown below:



Here only channel 1 was used. The setup is similar to the first ADC10 example setup. The main difference is the enabling of the DTC block. Note the starting memory address and the memory block size. The memory we are talking about here is no other than MSP430's RAM. Unless you want to assign a different pointer address, keep it untouched. So why is it pointed at RAM location 512 (0x200) by default? The answer is the fact that this is first RAM location for our target MSP430G2452 microcontroller. Check the memory map below:

		MSP430G2112 MSP430G2152	MSP430G2212 MSP430G2252	MSP430G2312 MSP430G2352	MSP430G2412 MSP430G2452
Memory	Size	1kB	2kB	4kB	8kB
Main: interrupt vector	Flash	0xFFFF to 0xFFC0	0xFFFF to 0xFFC0	0xFFFF to 0xFFC0	0xFFFF to 0xFFC0
Main: code memory	Flash	0xFFFF to 0xFC00	0xFFFF to 0xF800	0xFFFF to 0xF000	0xFFFF to 0xE000
Information memory	Size	256 Byte	256 Byte	256 Byte	256 Byte
	Flash	010FFh to 01000h	010FFh to 01000h	010FFh to 01000h	010FFh to 01000h
RAM	Size	128 B	256 B	256 B	256 B
		0x027F to 0x0200	0x02FF to 0x0200	0x02FF to 0x0200	0x02FF to 0x0200
Peripherals	16-bit	01FFh to 0100h	01FFh to 0100h	01FFh to 0100h	01FFh to 0100h
	8-bit	0FFh to 010h	0FFh to 010h	0FFh to 010h	0FFh to 010h
	8-bit SFR	0Fh to 00h	0Fh to 00h	0Fh to 00h	0Fh to 00h

The block size indicates that number of locations that we will need to store ADC10 data. MSP430s are 16-bit microcontrollers and since ADC10 gives 10-bit data, we need sixteen word-sized (16-bit) locations to store sixteen ADC samples. These 16 samples are to be averaged.

```
#define no_of_samples      16
....
unsigned int adc_pointer[no_of_samples];
....
ADC10DTC1 = no_of_samples;
ADC10SA = ((unsigned int)adc_pointer);
```

Grace generates the initialization code but the above lines must be edited by the coder.

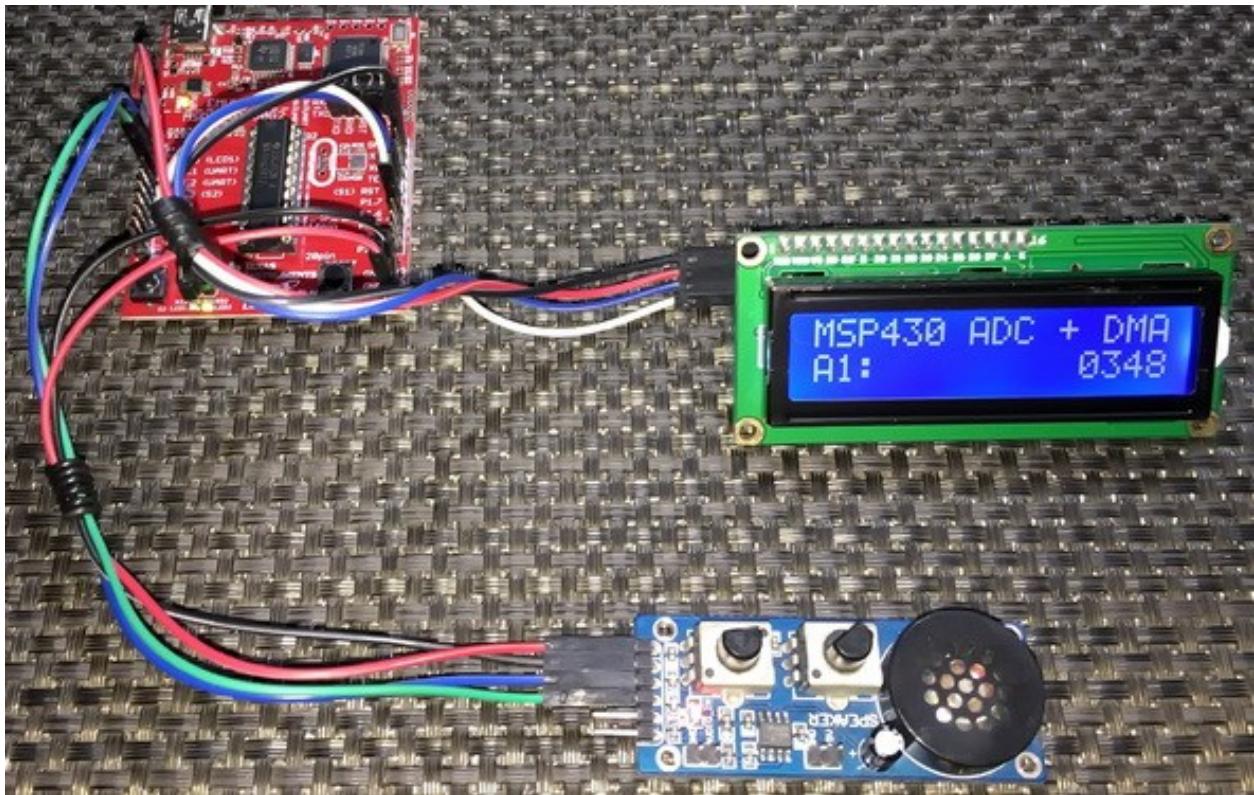
In the main function, ADC10 is commanded to begin and store conversions. Once all sixteen ADC10 data are captured, they are summed up and averaged. The averaged data is shown on a LCD screen. Note that ADC10 interrupt is not used and not anywhere in the code the *ADC10MEM* register is directly read. The ADC is read and processed by the DMA, freeing up the CPU for other tasks. The process is repetitive, automomous and continuous.

```
adc_avg = 0;
P1OUT |= BIT0;
ADC10CTL0 &= ~ENC;
while (ADC10CTL1 & BUSY);
ADC10CTL0 |= (ENC | ADC10SC);

for(s = 0; s < no_of_samples; s++)
{
    adc_avg += adc_pointer[s];
}

adc_avg = (adc_avg / no_of_samples);
lcd_print(12, 1, adc_avg);
delay_ms(100);
P1OUT &= ~BIT0;
delay_ms(100);
```

Demo



Demo video: <https://youtu.be/0V2zOTRwPKI>.

Sensing a Sequence of ADC10 Channels with DMA

We have seen in the last segment that how we can compute the average value of an ADC10 channel without involving the CPU much and using the MSP430's DMA/DTC controller. The DTC of MSP430s can be used in many innovative ways. One such way is to sense multiple channels in a row. In this method, the ADC is basically scanned in an orderly fashion from the coder-specified topmost channel to the bottommost (channel 0), saving the result of each ADC channel conversion in separate memory locations. Scanning a sequence of AD channels in this way has many potential applications. Consider the case of a solar charger controller. With one command you get both the input and output voltages, and currents quickly from your MSP430 micro. DMA-assisted ADC scanning is perhaps the most efficient and simple way to sense multiple ADC channels quickly.

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"

unsigned int ADC_value[2] = {0, 0};

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void ADC10_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value);

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 10-bit Analog to Digital Converter (ADC) */
    ADC10_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    LCD_init();
}
```

```

LCD_clear_home();

LCD_goto(0, 0);
LCD_putstr("A0:");

LCD_goto(0, 1);
LCD_putstr("A1:");

while(1)
{
    ADC10CTL0 &= ~ENC;
    while (ADC10CTL1 & BUSY);
    ADC10CTL0 |= (ENC | ADC10SC);
    lcd_print(12, 0, ADC_value[1]);
    lcd_print(12, 1, ADC_value[0]);
    delay_ms(400);
};

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Direction Register */
    P1DIR = 0;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */

```

```

/* User initialization code */
/* USER CODE END (section: BCSplus_graceInit_prologue) */

/*
 * Basic Clock System Control 2
 *
 * SELM_0 -- DCOCLK
 * DIVM_0 -- Divide by 1
 * ~SELS -- DCOCLK
 * DIVS_0 -- Divide by 1
 * ~DCOR -- DCO uses internal resistor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_8MHZ != 0xFF)
{
    /* Adjust this accordingly to your VCC rise time */
    _delay_cycles(100000);

    // Follow recommended flow. First, clear all DCOx and MODx bits. Then
    // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_8MHZ;      /* Set DCO to 8MHz */
    DCOCTL = CALDCO_8MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void ADC10_graceInit(void)
{
    /* USER CODE START (section: ADC10_graceInit_prologue) */
    /* User initialization code */
}

```

```

/* USER CODE END (section: ADC10_graceInit_prologue) */

/* disable ADC10 during initialization */
ADC10CTL0 &= ~ENC;

/*
 * Control Register 0
 *
 * ~ADC10SC -- No conversion
 * ~ENC -- Disable ADC
 * ~ADC10IFG -- Clear ADC interrupt flag
 * ~ADC10IE -- Disable ADC interrupt
 * ADC10ON -- Switch On ADC10
 * ~REFON -- Disable ADC reference generator
 * ~REF2_5V -- Set reference voltage generator = 1.5V
 * MSC -- Enable multiple sample and conversion
 * ~REFBURST -- Reference buffer on continuously
 * ~REFOUT -- Reference output off
 * ~ADC10SR -- Reference buffer supports up to ~200 ksps
 * ADC10SHT_2 -- 16 x ADC10CLKs
 * SREF_0 -- VR+ = VCC and VR- = VSS
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL0 = ADC10ON | MSC | ADC10SHT_2 | SREF_0;

/*
 * Control Register 1
 *
 * ~ADC10BUSY -- No operation is active
 * CONSEQ_3 -- Repeat sequence of channels
 * ADC10SSEL_0 -- ADC10OSC
 * ADC10DIV_0 -- Divide by 1
 * ~ISSH -- Input signal not inverted
 * ~ADC10DF -- ADC10 Data Format as binary
 * SHS_0 -- ADC10SC
 * INCH_1 -- ADC Channel 1
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL1 = CONSEQ_3 | ADC10SSEL_0 | ADC10DIV_0 | SHS_0 | INCH_1;

/* Analog (Input) Enable Control Register 0 */
ADC10AE0 = 0x3;

/*
 * Data Transfer Control Register 0
 *
 * ~ADC10TB -- One-block transfer mode
 * ADC10CT -- Data is transferred continuously after every conversion
 *
 * Note: ~ADC10TB indicates that ADC10TB has value zero
 */
ADC10DTC0 = ADC10CT;

/* Data Transfer Control Register 1 */
ADC10DTC1 = 2;

/* Data Transfer Start Address */

```

```

ADC10SA = ((unsigned int)ADC_value);

/* enable ADC10 */
ADC10CTL0 |= ENC;

/* USER CODE START (section: ADC10_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: ADC10_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(400);
    } while (IFG1 & OFIFG);

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    __bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
    */
}

```

```

/*
 * ~WDTTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * ~WDTSSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value)
{
    char chr = 0;

    chr = ((value / 1000) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(chr);

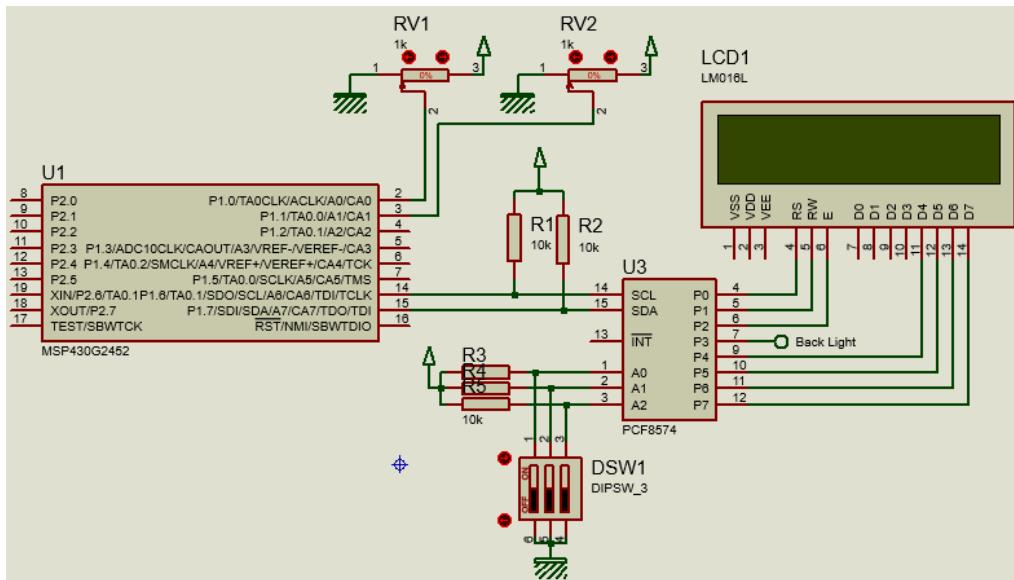
    chr = (((value / 100) % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(chr);

    chr = (((value / 10) % 10) + 0x30);
    LCD_goto((x_pos + 2), y_pos);
    LCD_putchar(chr);

    chr = ((value % 10) + 0x30);
    LCD_goto((x_pos + 3), y_pos);
    LCD_putchar(chr);
}

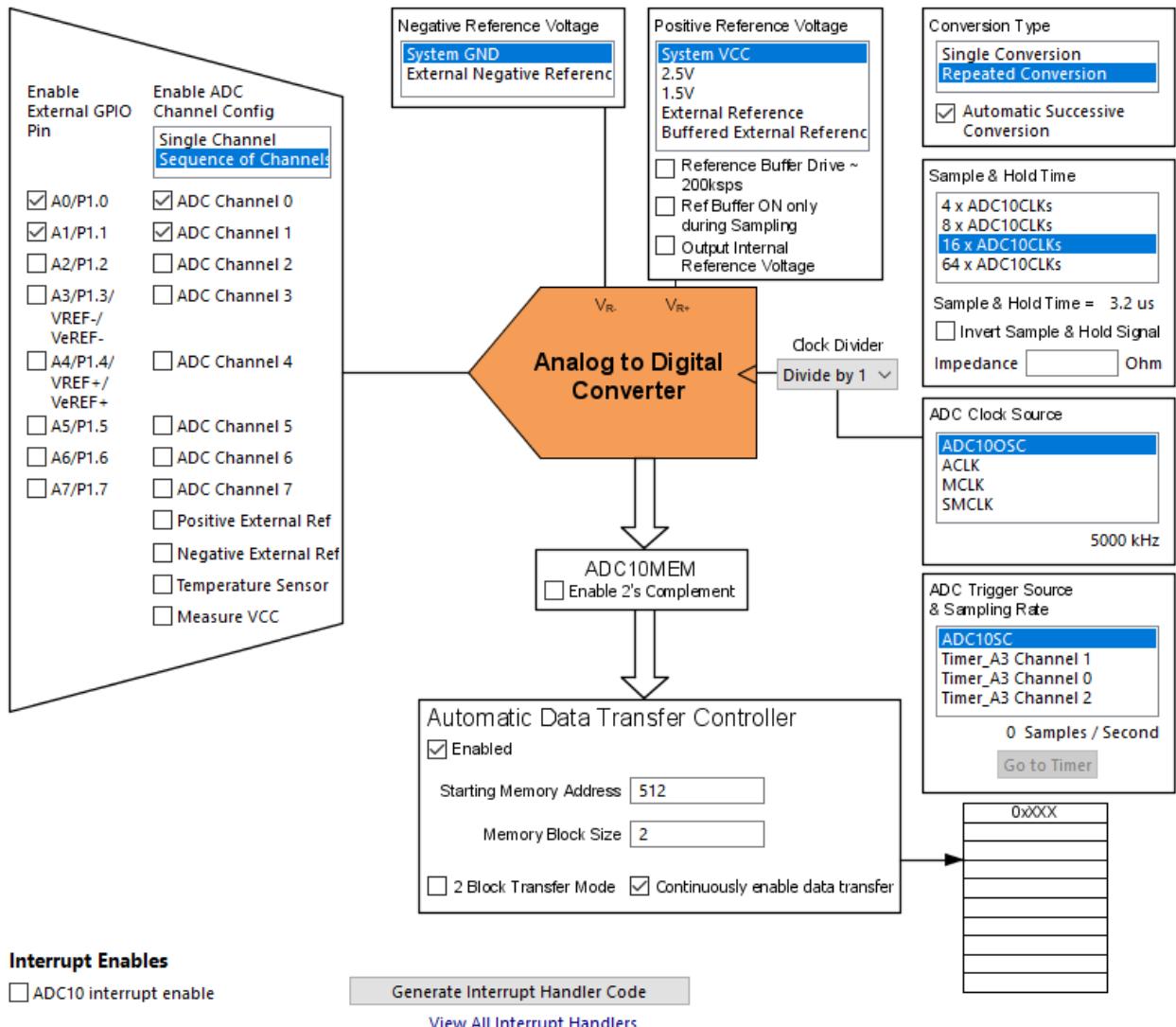
```

Simulation



Explanation

Except some minor differences, the Grace setup here is same as the one used in the DMA example. The first difference is the **Sequence of Channels** selection, second is the number of ADC channels and finally the size of memory block.



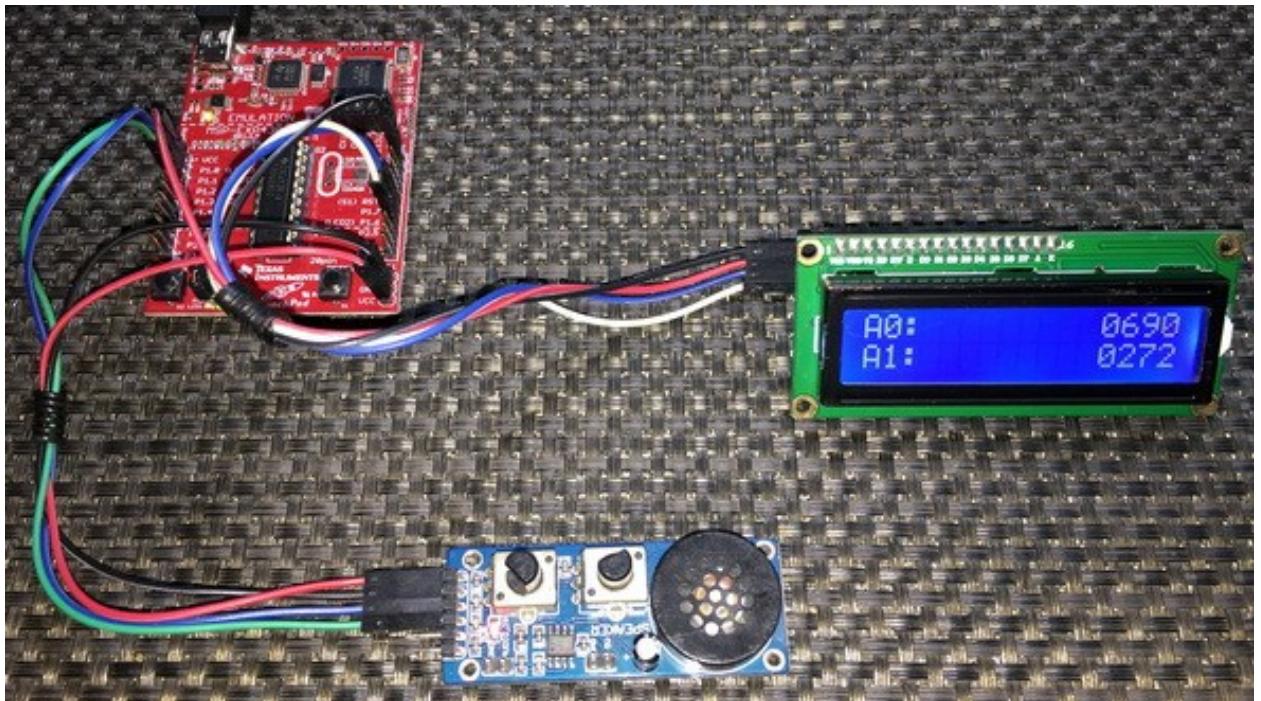
In the main, most of the things are same as in the DMA example. Since two channels are read, two memory locations store individual ADC data. Scanning starts from topmost channel to the bottommost and so the bottommost memory location will hold the data of the topmost channel and vice versa. In short, the memory locations are flipped with respect to ADC channels.

```

ADC10CTL0 &= ~ENC;
while (ADC10CTL1 & BUSY);
ADC10CTL0 |= (ENC | ADC10SC);
lcd_print(12, 0, ADC_value[1]);
lcd_print(12, 1, ADC_value[0]);
delay_ms(400);

```

Demo



Demo video: <https://youtu.be/ZSfkjQHgrKs>.

Sensing Multiple Out-of-Sequence ADC10 Channels with DMA

Due to several obligations and design constraints, we may often fall in situations where we would not be able to enjoy the sequential DTC-assisted ADC scanning feature demonstrated in the previous section. ADC channels may not be in an orderly sequence. Still we can apply similar techniques as in ADC scanning but certain things are needed to be kept in mind in such cases.

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"

#define no_of_channels 12

unsigned int ADC_value[no_of_channels];

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void ADC10_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value);

void main(void)
{
    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 10-bit Analog to Digital Converter (ADC) */
    ADC10_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    LCD_init();
    LCD_clear_home();
```

```

while(1)
{
    ADC10CTL0 &= ~ENC;
    while (ADC10CTL1 & BUSY);
    ADC10CTL0 |= (ENC | ADC10SC);

    LCD_goto(0, 0);
    LCD_putstr("A03:");
    lcd_print(12, 0, ADC_value[8]);
    LCD_goto(0, 1);
    LCD_putstr("A11:");
    lcd_print(12, 1, ADC_value[0]);

    P1OUT ^= BIT0;
    delay_ms(900);

    ADC10CTL0 &= ~ENC;
    while (ADC10CTL1 & BUSY);
    ADC10CTL0 |= (ENC | ADC10SC);

    LCD_goto(0, 0);
    LCD_putstr("A00:");
    lcd_print(12, 0, ADC_value[11]);
    LCD_goto(0, 1);
    LCD_putstr("A10:");
    lcd_print(12, 1, ADC_value[1]);

    P1OUT ^= BIT0;
    delay_ms(900);

}
}

void GPIO_graceInit(void)
{
/* USER CODE START (section: GPIO_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Direction Register */
P1DIR = BIT0;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */

```

```

P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF)
    {
        /* Adjust this accordingly to your VCC rise time */
        delay_cycles(100000);

        // Follow recommended flow. First, clear all DCOx and MODx bits. Then
        // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_8MHZ;          /* Set DCO to 8MHz */
        DCOCTL = CALDCO_8MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;

    /*
     * Basic Clock System Control 3
     *

```

```

        * XT2S_0 -- 0.4 - 1 MHz
        * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
        * XCAP_1 -- ~6 pF
        */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void ADC10_graceInit(void)
{
    /* USER CODE START (section: ADC10_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: ADC10_graceInit_prologue) */

    /* disable ADC10 during initialization */
ADC10CTL0 &= ~ENC;

/*
 * Control Register 0
 *
 * ~ADC10SC -- No conversion
 * ~ENC -- Disable ADC
 * ~ADC10IFG -- Clear ADC interrupt flag
 * ~ADC10IE -- Disable ADC interrupt
 * ADC10ON -- Switch On ADC10
 * ~REFON -- Disable ADC reference generator
 * ~REF2_5V -- Set reference voltage generator = 1.5V
 * MSC -- Enable multiple sample and conversion
 * ~REFBURST -- Reference buffer on continuously
 * ~REFOUT -- Reference output off
 * ~ADC10SR -- Reference buffer supports up to ~200 ksps
 * ADC10SHT_2 -- 16 x ADC10CLKs
 * SREF_0 -- VR+ = VCC and VR- = VSS
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL0 = ADC10ON | MSC | ADC10SHT_2 | SREF_0;

/*
 * Control Register 1
 *
 * ~ADC10BUSY -- No operation is active
 * CONSEQ_3 -- Repeat sequence of channels
 * ADC10SSEL_0 -- ADC10OSC
 * ADC10DIV_0 -- Divide by 1
 * ~ISSH -- Input signal not inverted
 * ~ADC10DF -- ADC10 Data Format as binary
 * SHS_0 -- ADC10SC
 * INCH_11 -- ADC convert VCC
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
ADC10CTL1 = CONSEQ_3 | ADC10SSEL_0 | ADC10DIV_0 | SHS_0 | INCH_11;

```

```

/* Analog (Input) Enable Control Register 0 */
ADC10AE0 = 0x8;

/*
 * Data Transfer Control Register 0
 *
 * ~ADC10TB -- One-block transfer mode
 * ADC10CT -- Data is transferred continuously after every conversion
 *
 * Note: ~ADC10TB indicates that ADC10TB has value zero
 */
ADC10DTC0 = ADC10CT;

/* Data Transfer Control Register 1 */
ADC10DTC1 = 12;

/* Data Transfer Start Address */
ADC10SA = ((unsigned int)ADC_value);

/* enable ADC10 */
ADC10CTL0 |= ENC;

/* USER CODE START (section: ADC10_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: ADC10_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(400);
    } while (IFG1 & OFIFG);

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    __bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
}

```

```

/* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value)
{
    char chr = 0;

    chr = ((value / 1000) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(chr);

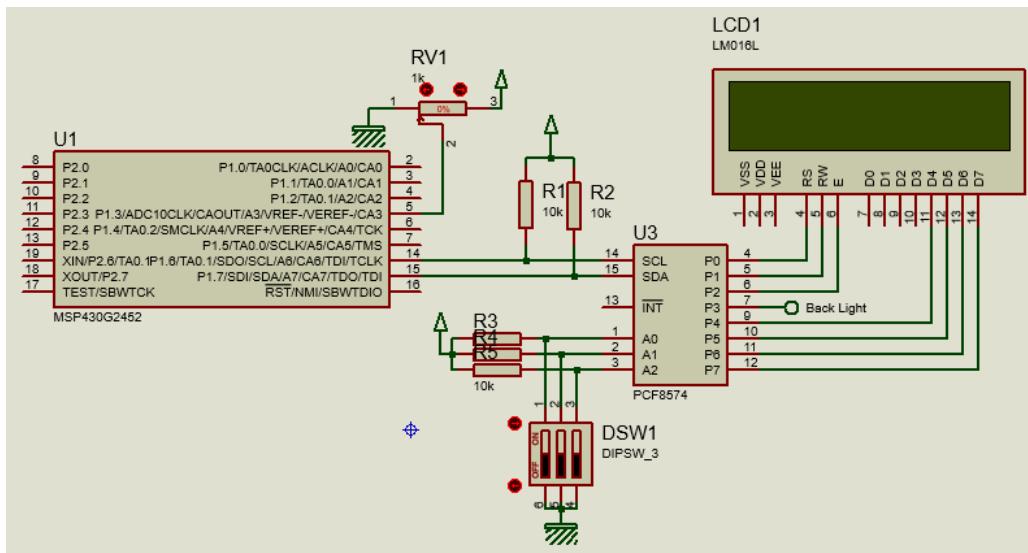
    chr = (((value / 100) % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(chr);

    chr = (((value / 10) % 10) + 0x30);
    LCD_goto((x_pos + 2), y_pos);
    LCD_putchar(chr);

    chr = ((value % 10) + 0x30);
    LCD_goto((x_pos + 3), y_pos);
    LCD_putchar(chr);
}

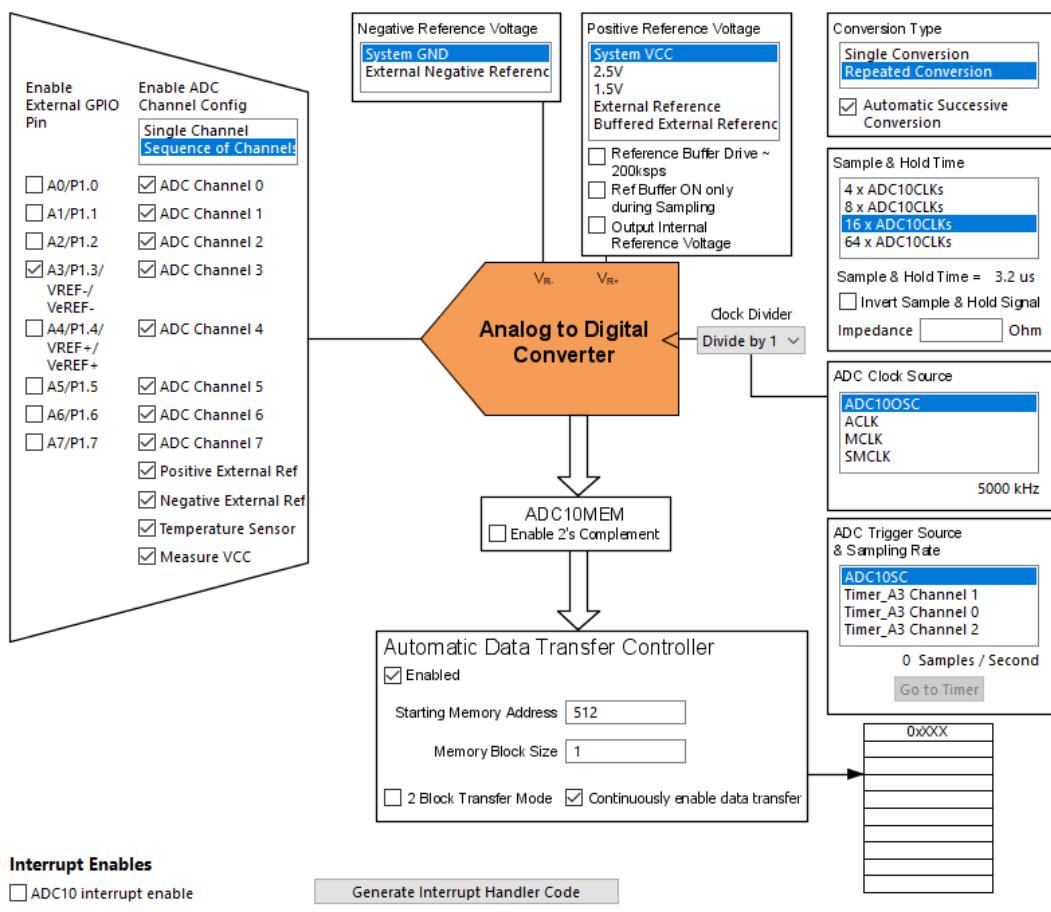
```

Simulation



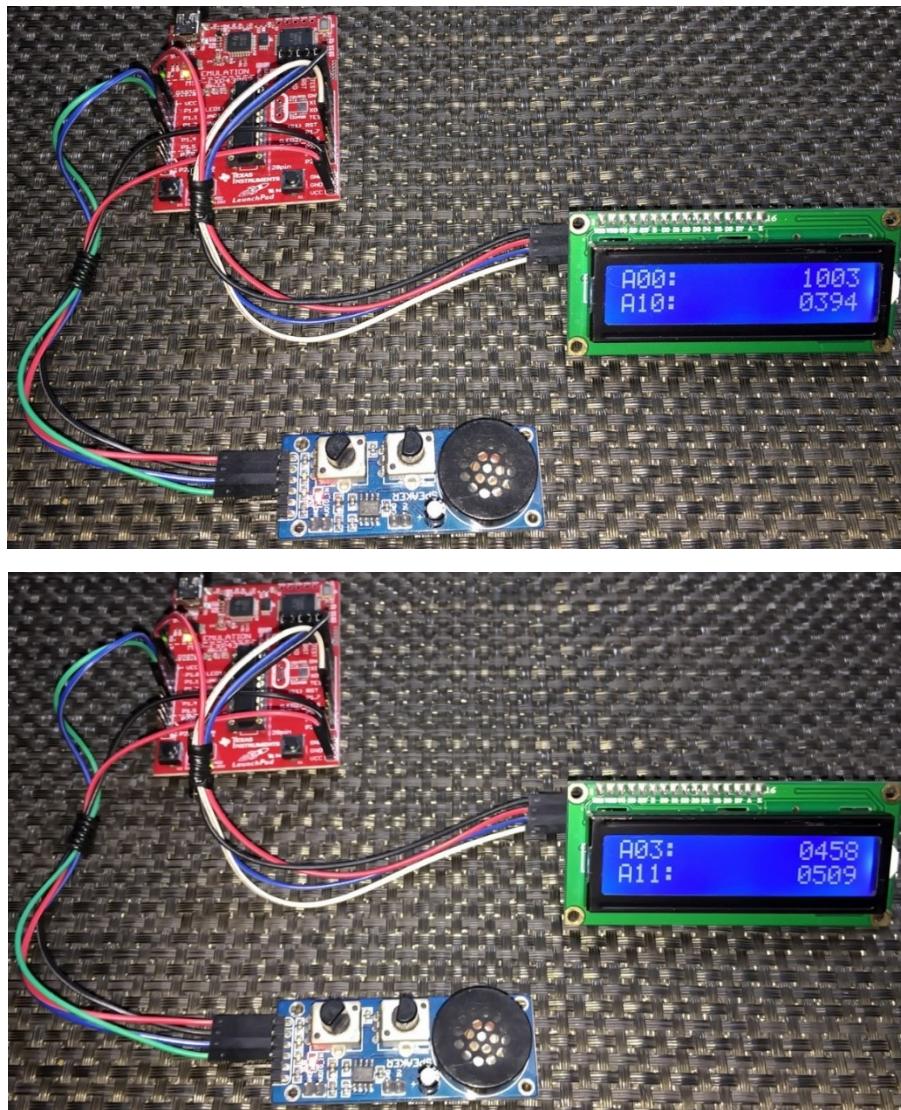
Explanation

In the last example, the ADC channels that were scanned were in an order. Here, however, the story is different but the concept is the same.



Note that all channels are enabled since the topmost channel we have measured here is the **Measure VCC** channel but intentionally the memory block size is set 1 instead of 12 and only one external channel is enabled. Well, there are some proof-of-concepts to show. The first proof-of-concept is the fact that since we have to set memory block size and memory pointer on our own in the initialization code, it doesn't matter what these values are in Grace. Secondly, only external channel A3 is sensed since its external I/O is enabled. The rest of the external channels are ignored. This is why A0 reads floating values when the code runs because its external I/O to ADC is disconnected and furthermore it is used to blink the onboard Launchpad LED connected with it. Channel A10 (internal temperature sensor) and A11 (internal VCC sensor) are internal channels and so are not dependent on external I/Os. These channels read as they should. Despite scanning all channels, we can decide which ones we need. Here I demoed sensing channels A0, A3, A10 and A11. Note that these channels are out of a regular or orderly sequence, hence the name of the topic **Sensing Multiple Out-of-Sequence ADC10 Channels with DMA**.

Demo



Demo video: <https://youtu.be/75IyIXIVtrY>.

Communication Overview

Most MSP430 micros are equipped with **Universal Serial Interface (USI)** and **Universal Serial Communication Interface (USCI)** modules. Some devices have **Universal Asynchronous Receiver-Transmitter (UART)** modules. These interfaces are needed to communicate with external devices like sensors, actuators, drives, other microcontrollers or onboard devices, etc and are responsible for handling the most commonly used serial communications like **Universal Asynchronous Receiver-Transmitter (UART)**, **Serial Peripheral Interface (SPI)** and **Inter-Integrated Circuit (I2C)**. Also, there are other additional more robust communication interfaces like **Controller Area Network (CAN)**, **Local Interconnect Network (LIN)**, **Infrared Data Association (IrDA)** and **RS-485**. The latter communications will not be discussed here as they are advanced and are basically extension of the aforementioned serial communications. Each method communication has its own advantages and disadvantages. In the table below, some individual basics of various methods of communications are shown:

Comm.	Description	I/O	Max. Speed	Max. Distance	Max. Possible Number of Devices in a Bus
UART	Asynchronous serial point-to-point communication	2	115.2kbps	15m	2 (Point-to-Point)
SPI	Short-range synchronous master-slave serial communication	3/4	4Mbps	0.1m	Virtually unlimited
I2C	Short-range synchronous master-slave serial communication using one data and one clock line	2	1Mbps	0.5m	127
RS-485	Asynchronous differential two wire serial communication with one master	2	115.2kbps	1.2km	Several
CAN	Industrial differential two wire communication with more than one master support	2	1Mbps	5km	Several
LIN	Asynchronous two wire serial communication similar to UART	2	20kbps	40m	Several
IrDA	Wireless serial communication using infrared medium	2	115.2kbps	<1m	2 (Point-to-Point)

We can also use software-based methods instead of using dedicated hardware to replicate some of these communications but these methods are not efficient as they consume resources like clock cycles, memories and often employ polling strategies. However, in the absence of dedicated hardware, software methods are the last resorts.

USI vs USCI - Which one is better?

USI and USCI are both hardware-based serial communication handlers but the question which one is better lurks in every beginner's mind. Although both modules do same tasks, they are not identical.

- **Universal Serial Interface (USI)**

Mainly USI is intended for I2C and SPI communications. Technically speaking, USI is a pumped-up shift register that does all the bit-banging in hardware that a programmer would have done in software end. Apart from its aforementioned shift register, it has clock generator, bit counter and few extra assists for I2C communications.

In the firmware end, we need to load the bit counter with the number of bits to transfer. This bit counter always counts down to zero. During transmission, the shift register is loaded with the value that is to be transmitted while during reception, the shift register is read back once the bit counter hits zero.

- **Universal Serial Communication Interface (USCI)**

USCI, on the other hand, is a highly sophisticated module that is intended for most forms of serial communications. USCI is more advanced than USI in terms of hardware. It has a one-byte I/O buffer and DMA transfer capability for higher throughput. USCI can be subcategorized in two types:

- ◆ **Asynchronous USCI (USCI_A)**

It is used for UART, SPI, LIN and IRDA as it can detect the baud rate of an incoming signal. This type is most common.

- ◆ **Synchronous USCI (USCI_B)**

This type can handle synchronous communications like SPI and I2C that need a clock signal. The coolest part is the fact that the full I2C communication protocol as per NXP is implemented in I2C mode with an in-built I2C state machine.

Both USI and USCI support master-slave modes although most of the times we don't need slave modes. This is because most of the times we do not need communicate with multiple microcontrollers on board. I2C and SPI are usually used to establish communication between external devices (sensors and drivers) and a host microcontroller. UART, on the other hand, is mainly used to communicate with a computer. It is also used for long-distance communications like RS232, RS485, LIN and IrDA.

Software-based Communication

When USI/USCI are absent or used up, we have to stick to software-based methods to emulate SPI, I2C and UART. They are slow and may require the aid of other hardware like timers and external interrupts. Software methods add considerable amounts of coding overhead and consume both CPU cycles as well as memories. We can't also use them for communications that are more complex than I2C, SPI or UART. It is better to avoid them whenever possible. Still however, these methods help in learning the details of UART, I2C and SPI communications to a great extent. A good thing about software solutions is the fact that we can virtually create unlimited amounts of communication ports.

USI SPI – Interfacing MAX7219

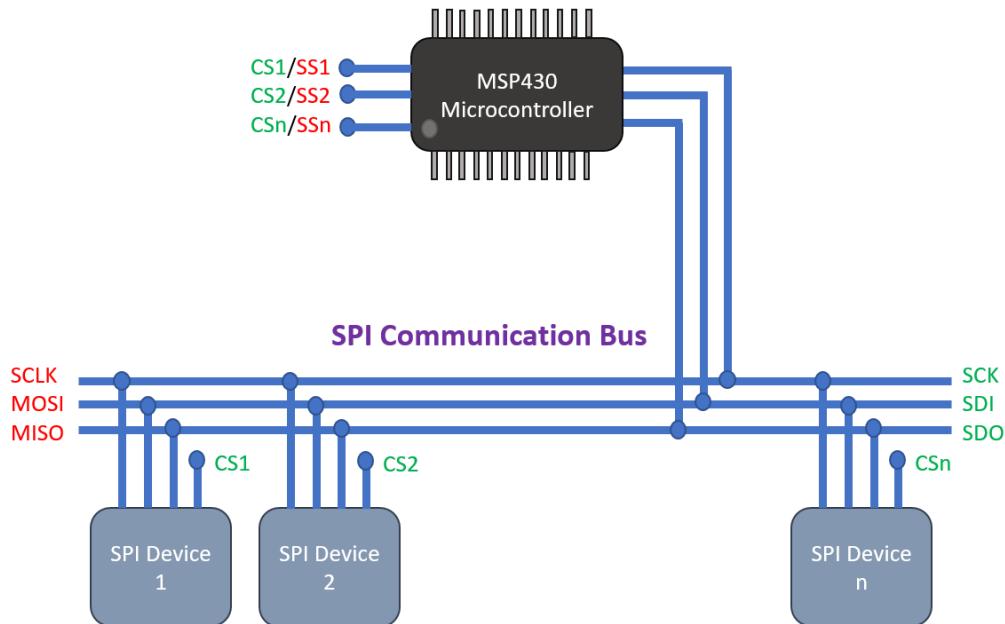
SPI communication is an onboard synchronous communication method. It is used for communicating with a number of devices including sensors, TFT displays, port expanders, PWM controller ICs, memory chips, addon support devices and even other microcontrollers.

In a SPI communication bus, there is always one master device which generates clock and select slave(s). Master sends commands to slave(s). Slave(s) responds to commands sent by the master. The number of slaves in a SPI bus is virtually unlimited provided that there is no issue with slave selection hardware and bus speed. Except the chip selection pin, all SPI devices in a bus can share the same clock and data pins.

Typical full-duplex SPI bus requires four basic I/O pins:

- **Master-Out-Slave-In (MOSI)** connected to **Slave-Data-In (SDI)**.
- **Master-In-Slave-Out (MISO)** connected to **Slave-Data-Out (SDO)**.
- **Serial Clock (SCLK)** connected to **Slave Clock (SCK)**.
- **Slave Select (SS)** connected to **Chip Select (CS)**.

The diagram below illustrates SPI communication with a MSP430 micro. The green labels are for slaves while the red ones are for the master or host MSP430 micro.



In general, if you wish to know more about SPI bus here are some cool links:

- <https://learn.mikroe.com/spi-bus/>
- <https://learn.sparkfun.com/tutorials/serial-peripheral-interface-spi>
- <http://ww1.microchip.com/downloads/en/devicedoc/spi.pdf>
- <http://tronixstuff.com/2011/05/13/tutorial-arduino-and-the-spi-bus/>
- <https://embeddedmicro.com/tutorials/mojo/serial-peripheral-interface-spi>
- <http://www.circuitbasics.com/basics-of-the-spi-communication-protocol/>

Code Example

SPI.h

```
#include <msp430.h>

unsigned char SPI_transfer(unsigned char data_out);
```

SPI.c

```
#include "SPI.h"

unsigned char SPI_transfer(unsigned char data_out)
{
    unsigned char data_in = 0;

    USISRL = data_out;           // Load shift register with data byte to be TXed
    USICNT = 8;                 // Load bit-counter to send/receive data byte
    while (!(USIIFG & USICTL1)); // Loop until data byte transmitted
    data_in = USISRL;           // Read out the received data

    return data_in;
}
```

MAX72xx.h

```
#include <MSP430.h>
#include "delay.h"
#include "SPI.h"

#define HW_SPI_DIR          P1DIR
#define HW_SPI_OUT          P1OUT
#define HW_SPI_IN           P1IN

#define CS_pin              BIT4

#define CS_DIR_OUT()         do{HW_SPI_DIR |= CS_pin;}while(0)
#define CS_DIR_IN()         do{HW_SPI_DIR &= ~CS_pin;}while(0)

#define CS_HIGH()            do{HW_SPI_OUT |= CS_pin;}while(0)
#define CS_LOW()             do{HW_SPI_OUT &= ~CS_pin;}while(0)

#define NOP                 0x00
#define DIG0                 0x01
#define DIG1                 0x02
#define DIG2                 0x03
#define DIG3                 0x04
#define DIG4                 0x05
#define DIG5                 0x06
#define DIG6                 0x07
#define DIG7                 0x08
#define decode_mode_reg      0x09
#define intensity_reg        0x0A
```

```

#define scan_limit_reg          0x0B
#define shutdown_reg            0x0C
#define display_test_reg        0x0F

#define shutdown_cmd             0x00
#define run_cmd                  0x01

#define no_test_cmd              0x00
#define test_cmd                 0x01

void MAX72xx_init(void);
void MAX72xx_write(unsigned char address, unsigned char value);

```

MAX72xx.c

```

#include "MAX72xx.h"

void MAX72xx_init(void)
{
    CS_DIR_OUT();
    CS_HIGH();

    MAX72xx_write(shutdown_reg, run_cmd);
    MAX72xx_write(decode_mode_reg, 0x00);
    MAX72xx_write(scan_limit_reg, 0x07);
    MAX72xx_write(intensity_reg, 0x04);
    MAX72xx_write(display_test_reg, test_cmd);
    delay_ms(100);
    MAX72xx_write(display_test_reg, no_test_cmd);
}

void MAX72xx_write(unsigned char address, unsigned char value)
{
    CS_LOW();

    SPI_transfer(address);
    SPI_transfer(value);

    CS_HIGH();
}

```

main.c

```

#include <msp430.h>
#include <string.h>
#include "delay.h"
#include "SPI.h"
#include "MAX72xx.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USI_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

```

```

void main(void)
{
    unsigned char i = 0;
    unsigned char j = 0;

    unsigned char temp[8];

    const unsigned char text[80] =
    {
        0x00, 0x7E, 0x04, 0x08, 0x08, 0x04, 0x7E, 0x00, //M
        0x00, 0x42, 0x42, 0x7E, 0x7E, 0x42, 0x42, 0x00, //I
        0x00, 0x3C, 0x42, 0x42, 0x42, 0x24, 0x00, //C
        0x00, 0x7E, 0x1A, 0x1A, 0x1A, 0x2A, 0x44, 0x00, //R
        0x00, 0x3C, 0x42, 0x42, 0x42, 0x3C, 0x00, //O
        0x00, 0x7C, 0x12, 0x12, 0x12, 0x7C, 0x00, //A
        0x00, 0x7E, 0x1A, 0x1A, 0x1A, 0x2A, 0x44, 0x00, //R
        0x00, 0x7E, 0x7E, 0x4A, 0x4A, 0x4A, 0x42, 0x00, //E
        0x00, 0x7E, 0x04, 0x08, 0x10, 0x20, 0x7E, 0x00, //N
        0x00, 0x7C, 0x12, 0x12, 0x12, 0x7C, 0x00 //A
    };

    const unsigned char symbols[56] =
    {
        0x55, 0xAA, 0x55, 0xAA, 0x55, 0xAA, 0x55, 0xAA,
        0x3C, 0x42, 0x95, 0xA1, 0xA1, 0x95, 0x42, 0x3C,
        0xFF, 0xC3, 0xBD, 0xA5, 0xA5, 0xBD, 0xC3, 0xFF,
        0x99, 0x5A, 0x3C, 0xFF, 0xFF, 0x3C, 0x5A, 0x99,
        0x1C, 0x22, 0x41, 0x86, 0x86, 0x41, 0x22, 0x1C,
        0xDF, 0xDF, 0xD8, 0xFF, 0xFF, 0x1B, 0xFB, 0xFB,
        0xAA, 0x55, 0xAA, 0x55, 0xAA, 0x55, 0xAA, 0x55
    };

    memset(temp, 0x00, sizeof(temp));

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 USI */
    USI_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    MAX72xx_init();

    while(1)
    {
        for(i = 0; i < 80; i++)

```

```

    {
        for(j = 0; j < 8; j++)
        {
            temp[j] = text[(i + j)];
            MAX72xx_write((j + 1), temp[j]);
            delay_ms(6);
        }
    }

    for(j = 0; j < 56; j = (j + 8))
    {
        for(i = 0; i < 8; i++)
        {
            MAX72xx_write((i + 1), symbols[(i + j)]);
        }

        delay_ms(2000);
    }
};

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT5 | BIT6;

    /* Port 1 Direction Register */
    P1DIR = BIT4;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */
}

```

```

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF) {
        /* Follow recommended flow. First, clear all DC0x and MODx bits. Then
         * apply new RSELx values. Finally, apply new DC0x and MODx bit values.
         */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;           /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;

    /*
     * Basic Clock System Control 3
     *
     * XT2S_0 -- 0.4 - 1 MHz
     * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
     or resonator
     * XCAP_1 -- ~6 pF
     */
    BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

    /* USER CODE START (section: BCSplus_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void USI_graceInit(void)
{

```

```

/* USER CODE START (section: USI_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: USI_graceInit_prologue) */

/* Disable USI */
USICTL0 |= USISWRST;

/*
 * USI Control Register 0
 *
 * ~USIPE7 -- USI function disabled
 * USIPE6 -- USI function enabled
 * USIPE5 -- USI function enabled
 * ~USILSB -- MSB first
 * USIMST -- Master mode
 * ~USIGE -- Output latch enable depends on shift clock
 * USIOE -- Output enabled
 * USISWRST -- USI logic held in reset state
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
USICTL0 = USIPE6 | USIPE5 | USIMST | USIOE | USISWRST;

/*
 * USI Clock Control Register
 *
 * USIDIV_3 -- Divide by 8
 * USISSEL_2 -- SMCLK
 * USICKPL -- Inactive state is high
 * ~USISWCLK -- Input clock is low
 *
 * Note: ~USISWCLK indicates that USISWCLK has value zero
 */
USICKCTL = USIDIV_3 | USISSEL_2 | USICKPL;

/* Enable USI */
USICTL0 &= ~USISWRST;

/* USER CODE START (section: USI_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: USI_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(50);
    } while (IFG1 & OFIFG);
}

```

```

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
__bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

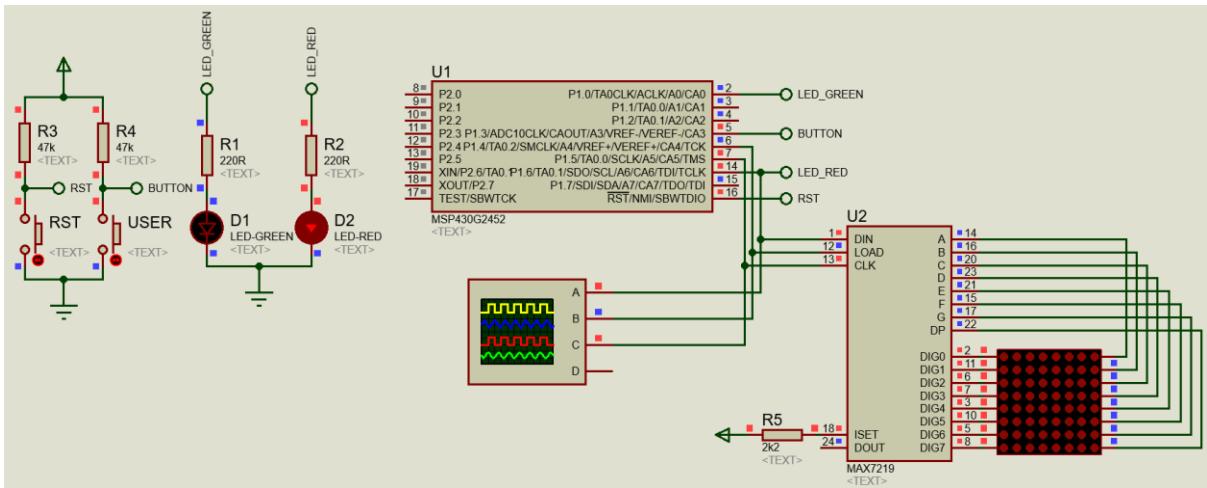
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

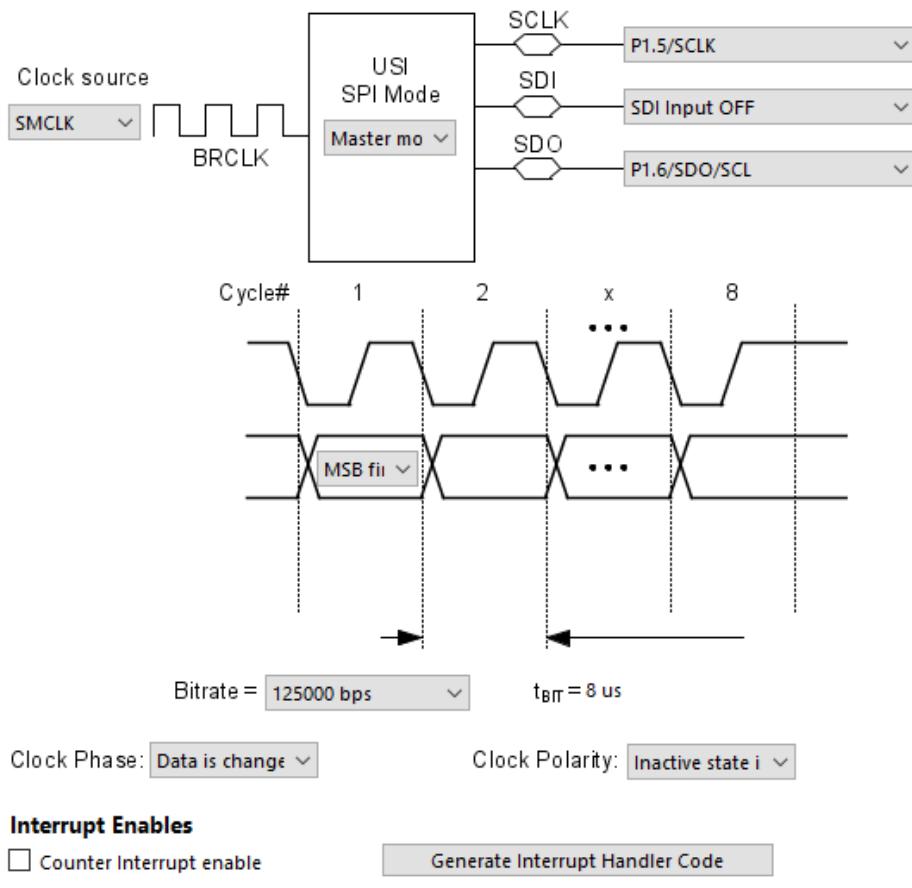
```

Simulation



Explanation

USI-based SPI is best realized with a MAX7219-based dot-matrix display and this demo is based on it. USI is setup for SPI mode. Every time USI is initialized it is disabled first just like other hardware. We, then, proceed to setup the SPI data transfer properties like SPI clock speed, device role, mode of operation, etc. Finally, USI is enabled for data transfer over SPI bus.



```

/* Disable USI */
USICTL0 |= USISWRST;

/*
 * USI Control Register 0
 *
 * ~USIPE7 -- USI function disabled
 * USIPE6 -- USI function enabled
 * USIPE5 -- USI function enabled
 * ~USILSB -- MSB first
 * USIMST -- Master mode
 * ~USIGE -- Output latch enable depends on shift clock
 * USIOE -- Output enabled
 * USISWRST -- USI logic held in reset state
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
*/
USICTL0 = USIPE6 | USIPE5 | USIMST | USIOE | USISWRST;

/*
 * USI Clock Control Register
 *
 * USIDIV_3 -- Divide by 8
 * USISSEL_2 -- SMCLK
 * USICKPL -- Inactive state is high
 * ~USISWCLK -- Input clock is low
 *
 * Note: ~USISWCLK indicates that USISWCLK has value zero
*/
USICKCTL = USIDIV_3 | USISSEL_2 | USICKPL;

/* Enable USI */
USICTL0 &= ~USISWRST;

```

The function below does the actual SPI data transfer. It both transmits and receives data over SPI bus. Data to be transmitted is loaded in **USISRL** register. USI bit counter is loaded with the number of bits to transfer, here 8. In the hardware end, this counter is decremented with data being shifted and clock signal being generated on each decrement. Since SPI bus is a circular bus, reading USISRL register back returns received data. Note slave select pin is not used here as it is used in MAX7219 source file.

```

unsigned char SPI_transfer(unsigned char data_out)
{
    unsigned char data_in = 0;

    USISRL = data_out;           // Load shift register with data byte to be TXed
    USICNT = 8;                 // Load bit-counter to send/receive data byte
    while (!(USIIIFG & USICNT)); // Loop until data byte transmitted
    data_in = USISRL;           // Read out the received data

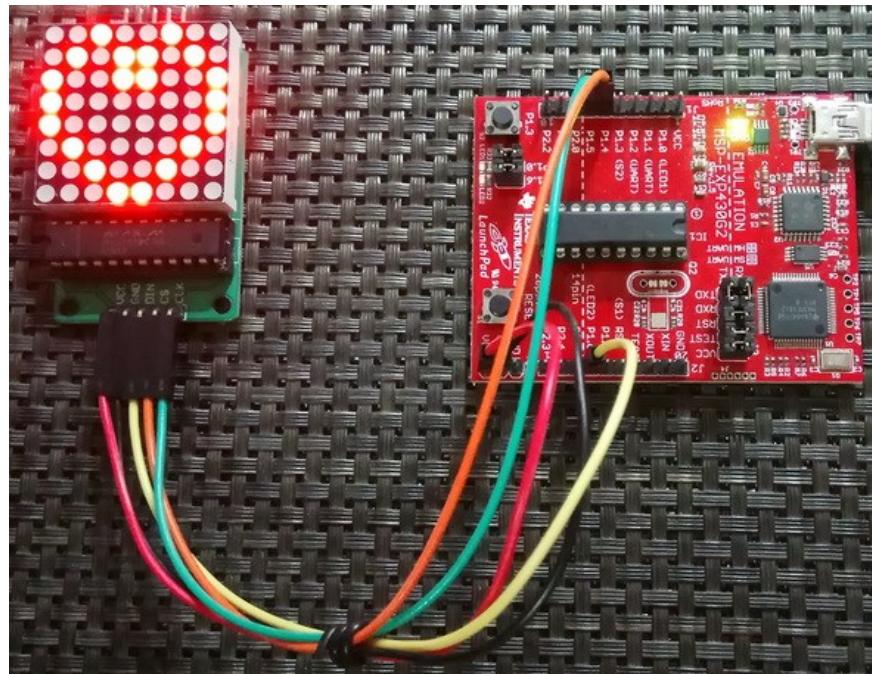
    return data_in;
}

```

The rest of the code is the implementation of MAX7219 driver and how to use it to create patterns in the dot-matrix display. When started, the display scrolls the letters of the word “[MICROARENA](#)” - the

name of my Facebook page followed by some symbols. I assume that readers will understand what I have done here.

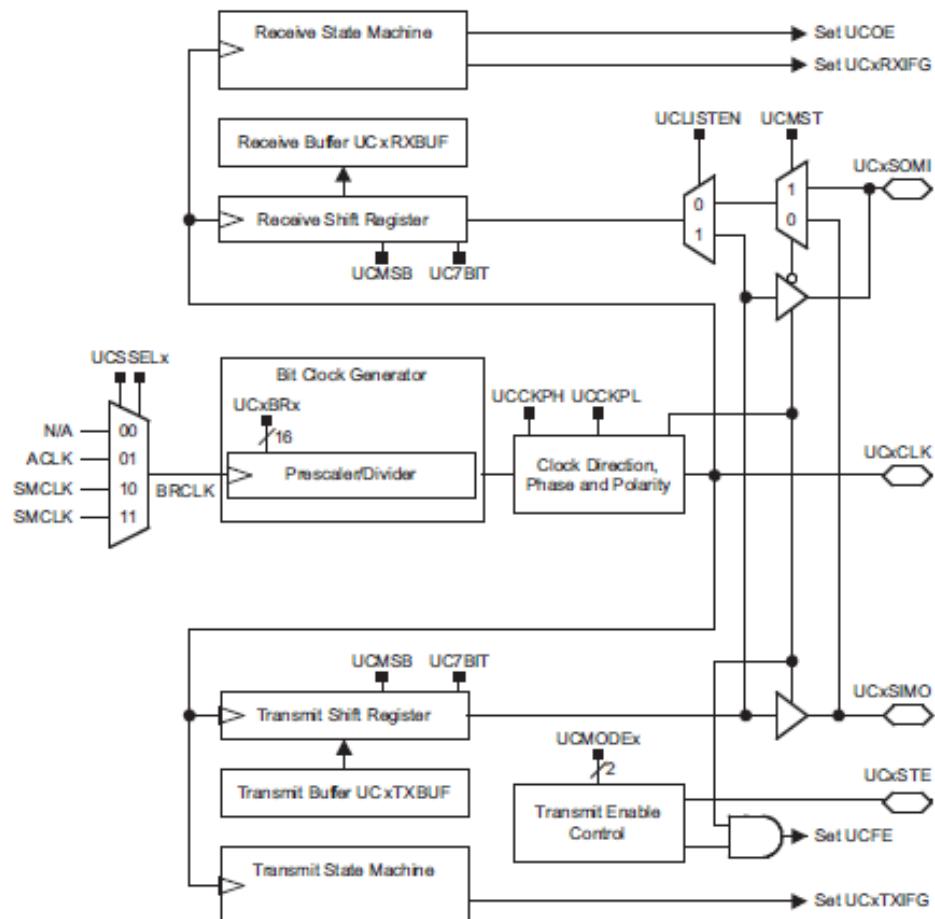
Demo



Demo video: <https://www.youtube.com/watch?v=FY3jtRD8FCA>.

USCI SPI – Interfacing MPL115A1 Atmospheric Pressure Sensor

We have already seen that MSP430's USI module can be used to implement both I2C and SPI communication platforms. However, there will be times we will have to use USCI modules. USCI is a bit complicated and is a bit difficult to use in simple terms. Here in this article, however, I kept things simple and projected ways to use this module simply. Four examples of USCI module in I2C and SPI modes will be presented in this article. The first one will demo how to interface a MSP430 device with a MPL115A1 atmospheric pressure sensor in a full-duplex SPI bus. Full-duplex SPI bus is needed the most when interfacing sensors, RTCs, SPI-based memory chips, SD cards, etc.



Code Example

HW_SPI.h

```
#include <msp430.h>

void HW_SPI_init(void);
void SPI_write(unsigned char tx_data);
unsigned char SPI_read(void);
unsigned char SPI_transfer(unsigned char tx_data);
```

HW_SPI.c

```
#include "HW_SPI.h"

void HW_SPI_init(void)
{
    UCA0CTL1 |= UCSWRST;
    UCA0CTL0 = UCCKPH | UCMSB | UCMST | UCMODE_1 | UCSYNC;
    UCA0CTL1 = UCSSEL_2 | UCSWRST;
    UCA0BR0 = 8;
    UCA0CTL1 &= ~UCSWRST;
}

void SPI_write(unsigned char tx_data)
{
    while(!(IFG2 & UCA0TXIFG));
    UCA0TXBUF = tx_data;
    while(UCA0STAT & UCBUSY);
}

unsigned char SPI_read(void)
{
    unsigned char rx_data = 0;

    while(!(IFG2 & UCA0RXIFG));
    rx_data = UCA0RXBUF;
    while(UCA0STAT & UCBUSY);

    return rx_data;
}

unsigned char SPI_transfer(unsigned char tx_data)
{
    unsigned char rx_data = 0;

    while(!(IFG2 & UCA0TXIFG));
    UCA0TXBUF = tx_data;
    while(UCA0STAT & UCBUSY);

    while(!(IFG2 & UCA0RXIFG));
    rx_data = UCA0RXBUF;
    while(UCA0STAT & UCBUSY);

    return rx_data;
}
```

MPL115A1.h

```
#include <msp430.h>
#include "delay.h"
#include "HW_SPI.h"
```

```

#define LOW 0
#define HIGH 1

#define PRESH 0x80
#define PRESL 0x82
#define TEMPH 0x84
#define TEMPL 0x86

#define A0_H 0x88
#define A0_L 0x8A
#define B1_H 0x8C
#define B1_L 0x8E
#define B2_H 0x90
#define B2_L 0x92
#define C12_H 0x94
#define C12_L 0x96

#define conv_cmd 0x24

#define MPL115A1_CSN_PORT_OUT P2OUT
#define MPL115A1_SDN_PORT_OUT P2OUT

#define MPL115A1_CSN_PORT_DIR P2DIR
#define MPL115A1_SDN_PORT_DIR P2DIR

#define MPL115A1_SDN_pin BIT0
#define MPL115A1_CSN_pin BIT1

#define MPL115A1_SDN_HIGH() P2OUT |= MPL115A1_SDN_pin
#define MPL115A1_SDN_LOW() P2OUT &= ~MPL115A1_SDN_pin
#define MPL115A1_CSN_HIGH() P2OUT |= MPL115A1_CSN_pin
#define MPL115A1_CSN_LOW() P2OUT &= ~MPL115A1_CSN_pin

struct
{
    float A0;
    float B1;
    float B2;
    float C12;
}coefficients;

void MPL115A1_init(void);
unsigned char MPL115A1_read(unsigned char address);
void MPL115A1_write(unsigned char address, unsigned char value);
void MPL115A1_get_coefficients(void);
void MPL115A1_get_bytes(unsigned int *hb, unsigned int *lb, unsigned char address);
void MPL115A1_get_data(float *pres, float *temp);

```

MPL115A1.c

```

#include "MPL115A1.h"

void MPL115A1_init(void)
{

```

```

MPL115A1_SDN_PORT_DIR |= MPL115A1_SDN_pin;
MPL115A1_CSN_PORT_DIR |= MPL115A1_CSN_pin;

MPL115A1_SDN_HIGH();
MPL115A1_CSN_HIGH();
HW_SPI_init();
MPL115A1_get_coefficients();
}

unsigned char MPL115A1_read(unsigned char address)
{
    unsigned char value = 0;

    MPL115A1_CSN_LOW();
    delay_ms(3);
    SPI_write(address);
    value = SPI_read();

    value = SPI_transfer(address);
    MPL115A1_CSN_HIGH();

    return value;
}

void MPL115A1_write(unsigned char address, unsigned char value)
{
    MPL115A1_CSN_LOW();
    delay_ms(3);
    SPI_write((address & 0x7F));
    SPI_write(value);
    MPL115A1_CSN_HIGH();
}

void MPL115A1_get_coefficients(void)
{
    unsigned int hb = 0;
    unsigned int lb = 0;

    MPL115A1_get_bytes(&hb, &lb, A0_H);
    coefficients.A0 = ((hb << 5) + (lb >> 3) + ((lb & 0x07) / 8.0));

    MPL115A1_get_bytes(&hb, &lb, B1_H);
    coefficients.B1 = (((((hb & 0x1F) * 0x0100) + lb) / 8192.0) - 3.0);

    MPL115A1_get_bytes(&hb, &lb, B2_H);
    coefficients.B2 = (((((hb - 0x80) << 8) + lb) / 16384.0) - 2.0);

    MPL115A1_get_bytes(&hb, &lb, C12_H);
    coefficients.C12 = (((hb * 0x100) + lb) / 16777216.0);
}

void MPL115A1_get_bytes(unsigned int *hb, unsigned int *lb, unsigned char address)
{
    *hb = ((unsigned int)MPL115A1_read(address));
    *lb = ((unsigned int)MPL115A1_read((address + 2)));
}

```

```

}

void MPL115A1_get_data(float *pres, float *temp)
{
    unsigned int hb = 0;
    unsigned int lb = 0;

    signed long Padc = 0;
    signed long Tadc = 0;

    MPL115A1_write(conv_cmd, 0);

    MPL115A1_get_bytes(&hb, &lb, PRESH);
    Padc = (((hb << 8) + lb) >> 6);

    MPL115A1_get_bytes(&hb, &lb, TEMPH);
    Tadc = (((hb << 8) + lb) >> 6);

    *pres = ( coefficients.A0 + (( coefficients.B1 + ( coefficients.C12 * Tadc)) *
    Padc) + ( coefficients.B2 * Tadc));
    *pres = (((*pres * 65.0) / 1023.0) + 50.0);

    *temp = (30.0 + ((Tadc - 472) / (-5.35)));
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "HW_SPI.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"
#include "MPL115A1.h"

const unsigned char symbol[8] =
{
    0x00, 0x06, 0x09, 0x09, 0x06, 0x00, 0x00, 0x00
};

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USCI_A0_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_symbol(void);
void print_C(unsigned char x_pos, unsigned char y_pos, signed int value);
void print_I(unsigned char x_pos, unsigned char y_pos, signed long value);
void print_D(unsigned char x_pos, unsigned char y_pos, signed int value, unsigned
char points);
void print_F(unsigned char x_pos, unsigned char y_pos, float value, unsigned char
points);

void main(void)

```

```

{
    float t = 0.0;
    float p = 0.0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSpusl_graceInit();

    /* initialize Config for the MSP430 USCI_A0 */
    USCI_A0_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    LCD_init();
    LCD_clear_home();
    lcd_symbol();

    LCD_goto(0, 0);
    LCD_putstr("P/kPa:");
    LCD_goto(0, 1);
    LCD_putstr("T/ C :");
    LCD_goto(2, 1);
    LCD_send(0, DAT);

    MPL115A1_init();

    while(1)
    {
        MPL115A1_get_data(&p, &t);
        print_F(10, 0, p, 1);
        print_F(11, 1, t, 1);
        delay_ms(400);
    };
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Port Select 2 Register */
    P1SEL2 = BIT1 | BIT2 | BIT4;

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT1 | BIT2 | BIT4;
}

```

```

/* Port 1 Direction Register */
P1DIR = 0;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Direction Register */
P2DIR = BIT0 | BIT1;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF)
    {
        /* Adjust this accordingly to your VCC rise time */
        __delay_cycles(100000);

```

```

// Follow recommended flow. First, clear all DCOx and MODx bits. Then
// apply new RSELx values. Finally, apply new DCOx and MODx bit values.
DCOCTL = 0x00;
BCSCTL1 = CALBC1_8MHZ;           /* Set DCO to 8MHz */
DCOCTL = CALDCO_8MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void USCI_A0_graceInit(void)
{
/* USER CODE START (section: USCI_A0_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: USCI_A0_graceInit_prologue) */

/* Disable USCI */
/* Disable USCI */
UCA0CTL1 |= UCSWRST;

/*
 * Control Register 0
 *
 * UCCKPH -- Data is captured on the first UCLK edge and changed on the
following edge
 * ~UCCKPL -- Inactive state is low
 * UCMSB -- MSB first
 * ~UC7BIT -- 8-bit
 * UCMST -- Master mode
 * UCMODE_1 -- 4-Pin SPI with UCxSTE active high: slave enabled when UCxSTE =
1
 * UCSYNC -- Synchronous Mode
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
}

```

```

UCA0CTL0 = UCCKPH | UCMSB | UCMST | UCMODE_1 | UCSYNC;

/*
 * Control Register 1
 *
 * UCSSEL_2 -- SMCLK
 * UCSWRST -- Enabled. USCI logic held in reset state
 */
UCA0CTL1 = UCSSEL_2 | UCSWRST;

/* Bit Rate Control Register 0 */
UCA0BR0 = 8;

/* Enable USCI */
UCA0CTL1 &= ~UCSWRST;

/* USER CODE START (section: USCI_A0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: USCI_A0_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
    */
}

```

```

/*
 * ~WDTNMI -- Reset function
 * ~WDTTMSEL -- Watchdog mode
 * ~WDTCNTCL -- No action
 * ~WDTSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void lcd_symbol(void)
{
    unsigned char s = 0;

    LCD_send(0x40, CMD);

    for(s = 0; s < 8; s++)
    {
        LCD_send(symbol[s], DAT);
    }

    LCD_send(0x80, CMD);
}

void print_C(unsigned char x_pos, unsigned char y_pos, signed int value)
{
    char ch[5] = {0x20, 0x20, 0x20, 0x20, '\0'};

    if(value < 0x00)
    {
        ch[0] = 0x2D;
        value = -value;
    }
    else
    {
        ch[0] = 0x20;
    }

    if((value > 99) && (value <= 999))
    {
        ch[1] = ((value / 100) + 0x30);
        ch[2] = (((value % 100) / 10) + 0x30);
        ch[3] = ((value % 10) + 0x30);
    }
    else if((value > 9) && (value <= 99))
    {
        ch[1] = (((value % 100) / 10) + 0x30);
        ch[2] = ((value % 10) + 0x30);
        ch[3] = 0x20;
    }
    else if((value >= 0) && (value <= 9))

```

```

    {
        ch[1] = ((value % 10) + 0x30);
        ch[2] = 0x20;
        ch[3] = 0x20;
    }

    LCD_goto(x_pos, y_pos);
    LCD_putstr(ch);
}

void print_I(unsigned char x_pos, unsigned char y_pos, signed long value)
{
    char ch[7] = {0x20, 0x20, 0x20, 0x20, 0x20, 0x20, '\0'};

    if(value < 0)
    {
        ch[0] = 0x2D;
        value = -value;
    }
    else
    {
        ch[0] = 0x20;
    }

    if(value > 9999)
    {
        ch[1] = ((value / 10000) + 0x30);
        ch[2] = (((value % 10000)/ 1000) + 0x30);
        ch[3] = (((value % 1000) / 100) + 0x30);
        ch[4] = (((value % 100) / 10) + 0x30);
        ch[5] = ((value % 10) + 0x30);
    }

    else if((value > 99) && (value <= 999))
    {
        ch[1] = (((value % 10000)/ 1000) + 0x30);
        ch[2] = (((value % 1000) / 100) + 0x30);
        ch[3] = (((value % 100) / 10) + 0x30);
        ch[4] = ((value % 10) + 0x30);
        ch[5] = 0x20;
    }
    else if((value > 9) && (value <= 99))
    {
        ch[1] = (((value % 100) / 10) + 0x30);
        ch[2] = ((value % 10) + 0x30);
        ch[3] = 0x20;
        ch[4] = 0x20;
        ch[5] = 0x20;
    }
    else

```

```

    {
        ch[1] = ((value % 10) + 0x30);
        ch[2] = 0x20;
        ch[3] = 0x20;
        ch[4] = 0x20;
        ch[5] = 0x20;
    }

    LCD_goto(x_pos, y_pos);
    LCD_putstr(ch);
}

void print_D(unsigned char x_pos, unsigned char y_pos, signed int value, unsigned char points)
{
    char ch[5] = {0x2E, 0x20, 0x20, '\0'};

    ch[1] = ((value / 100) + 0x30);

    if(points > 1)
    {
        ch[2] = (((value / 10) % 10) + 0x30);

        if(points > 1)
        {
            ch[3] = ((value % 10) + 0x30);
        }
    }

    LCD_goto(x_pos, y_pos);
    LCD_putstr(ch);
}

void print_F(unsigned char x_pos, unsigned char y_pos, float value, unsigned char points)
{
    signed long tmp = 0x0000;

    tmp = value;
    print_I(x_pos, y_pos, tmp);
    tmp = ((value - tmp) * 1000);

    if(tmp < 0)
    {
        tmp = -tmp;
    }

    if(value < 0)
    {
        value = -value;
        LCD_goto(x_pos, y_pos);
        LCD_putchar(0x2D);
    }
    else
    {
        LCD_goto(x_pos, y_pos);
        LCD_putchar(0x20);
    }
}

```

```

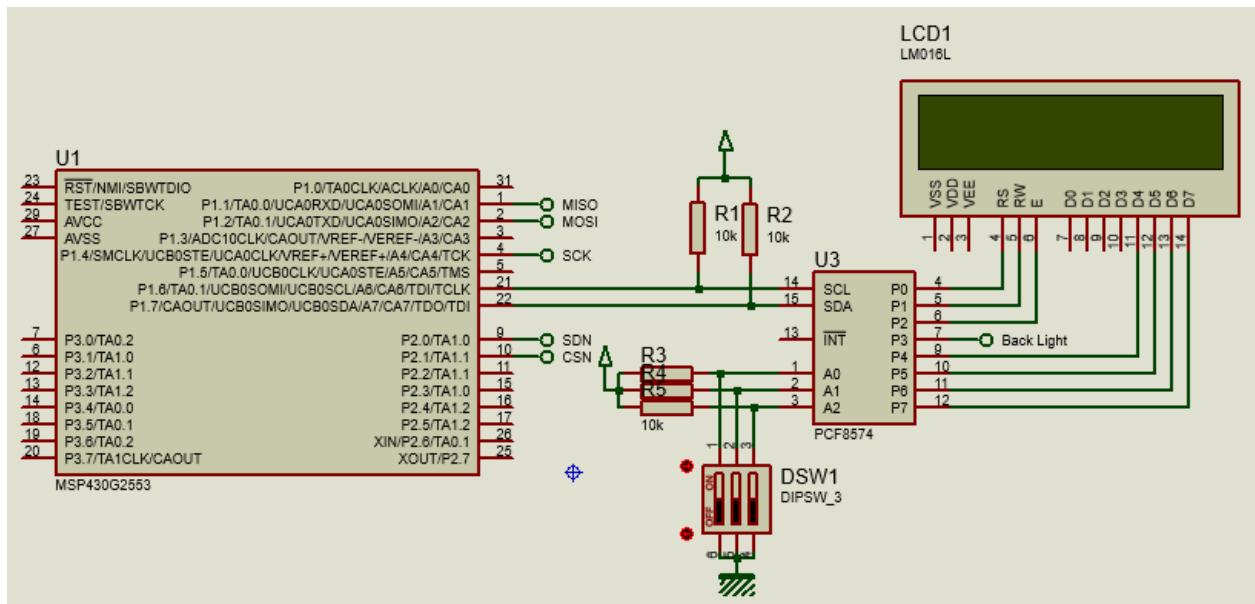
}

if((value >= 10000) && (value < 100000))
{
    print_D((x_pos + 6), y_pos, tmp, points);
}
else if((value >= 1000) && (value < 10000))
{
    print_D((x_pos + 5), y_pos, tmp, points);
}
else if((value >= 100) && (value < 1000))
{
    print_D((x_pos + 4), y_pos, tmp, points);
}
else if((value >= 10) && (value < 100))
{
    print_D((x_pos + 3), y_pos, tmp, points);
}
else if(value < 10)
{
    print_D((x_pos + 2), y_pos, tmp, points);
}
}

```

Simulation

The model for MPL115A1 is not available in Proteus VSM and so it cannot be simulated. Only the pinouts are shown in the schematic below.

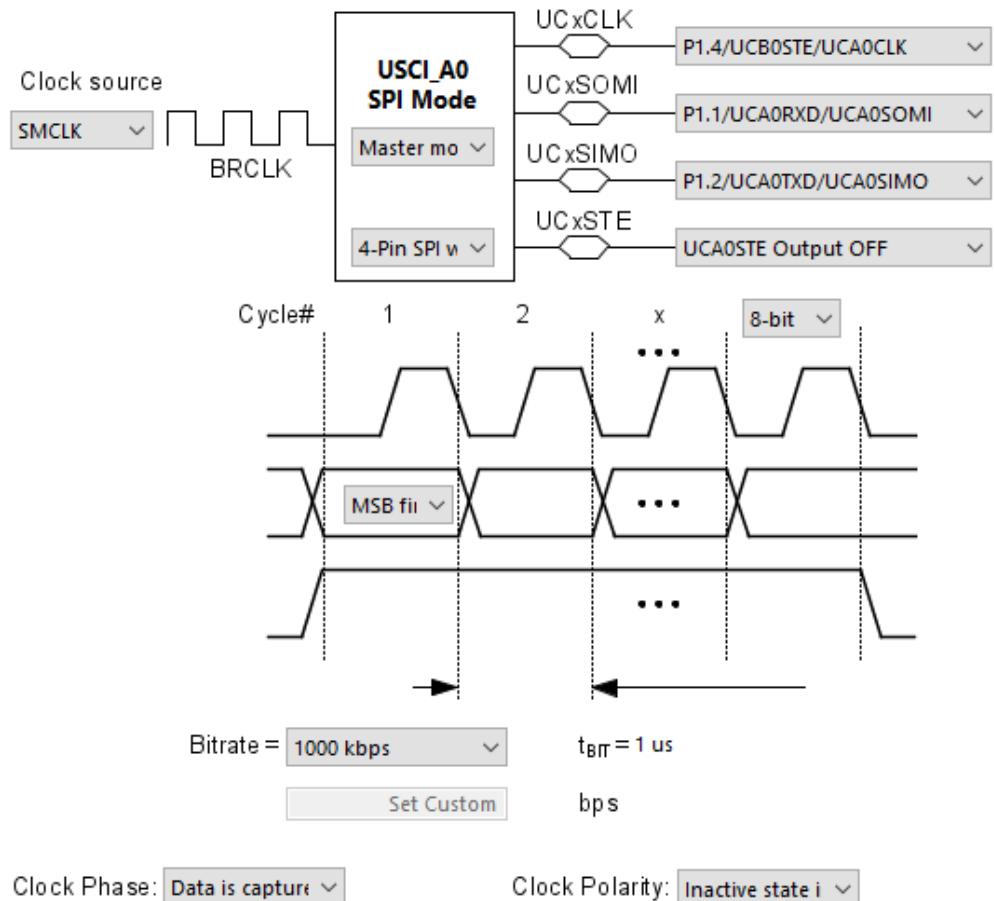


Explanation

HW_SPI.h and **HW_SPI.c** files describe the functionality of USCI-SPI hardware.

```
void HW_SPI_init(void);
void SPI_write(unsigned char tx_data);
unsigned char SPI_read(void);
unsigned char SPI_transfer(unsigned char tx_data);
```

The first function as shown above initiates the USCI-SPI hardware. The initialization is generated using Grace. Note the Grace screenshot below:



These settings describe which pins are being used, their purposes, communication speed, SPI mode, clock polarity and so on. Note the slave select pin is not shown here as we have used a different pin for that purpose.

SPI_read, SPI_write and SPI_transfer functions do their jobs as per their namings.

Now let's get inside the read and write function of USCI-SPI

```
void SPI_write(unsigned char tx_data)
{
    while(!(IFG2 & UCA0TXIFG));
    UCA0TXBUF = tx_data;
```

```

        while(UCA0STAT & UCBUSY);
    }

unsigned char SPI_read(void)
{
    unsigned char rx_data = 0;

    while(!(IFG2 & UCA0RXIFG));
    rx_data = UCA0RXBUF;
    while(UCA0STAT & UCBUSY);

    return rx_data;
}

unsigned char SPI_transfer(unsigned char tx_data)
{
    unsigned char rx_data = 0;

    while(!(IFG2 & UCA0TXIFG));
    UCA0TXBUF = tx_data;
    while(UCA0STAT & UCBUSY);

    while(!(IFG2 & UCA0RXIFG));
    rx_data = UCA0RXBUF;
    while(UCA0STAT & UCBUSY);

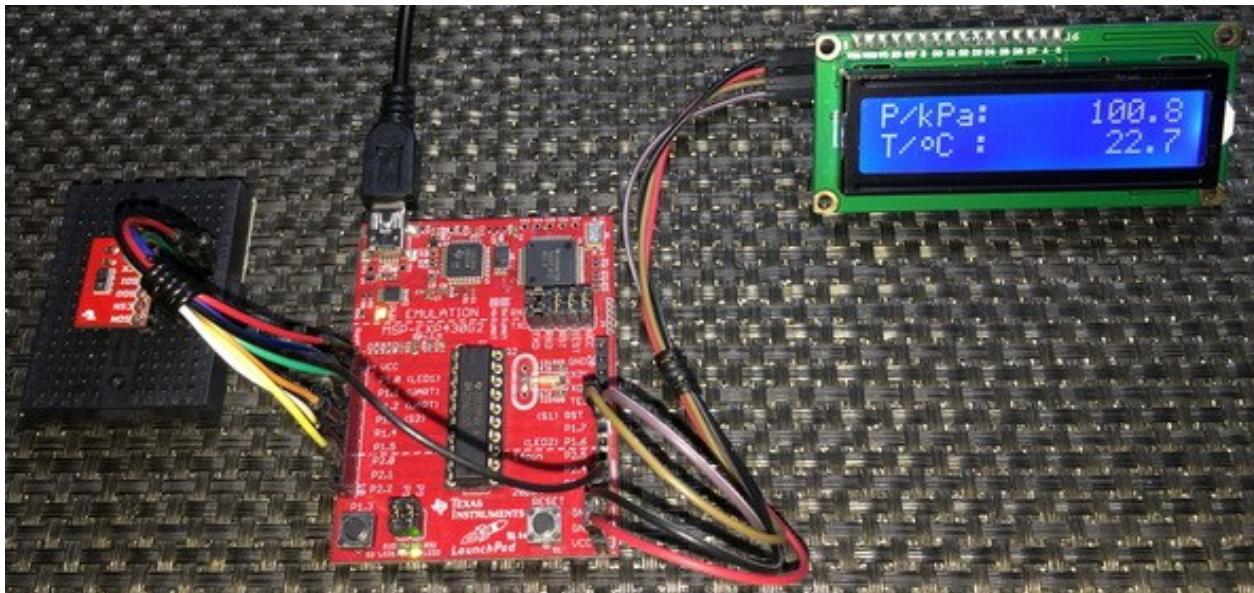
    return rx_data;
}

```

The SPI read and write processes are simplest to understand. Before starting communication, respective data transaction interrupt flags are polled. Note that these flags are needed even if we don't use USCI interrupts. Once polled okay, data is sent from MSP430 device in SPI write mode or received while in read mode. Then we have to check if data has been fully received/transmitted by asserting the USCI busy flag. Lastly the USCI SPI transfer function is a mixture of both SPI read and write functions.

The code here is used to read a MPL115A1 barometric pressure sensor and display atmospheric pressure-temperature data. MPL115A1 uses full-duplex SPI communication medium to communicate with its host device and here MSP430's USCI_A0 in SPI mode is employed to achieve that.

Demo



Demo video: <https://youtu.be/1uFOF87f0Hw>.

USCI SPI – Interfacing SSD1306 OLED Display

SPI is perhaps best known for the communication speed it offers. This raw communication speed is most needed when we need to interface external memories and smart displays like TFT displays and OLED displays. Here, we will see how to interface a SSD1306 OLED display with MSP430 using half-duplex or unidirectional USCI-based SPI communication bus.



Code Example

HW_SPI.h

```
#include <msp430.h>

void HW_SPI_init(void);
void SPI_write(unsigned char tx_data);
unsigned char SPI_read(void);
unsigned char SPI_transfer(unsigned char tx_data);
```

HW_SPI.c

```
#include "HW_SPI.h"

void HW_SPI_init(void)
{
    UCB0CTL1 |= UCSWRST;
    UCB0CTL0 = UCCKPH | UCMSB | UCMST | UCMODE_1 | UCSYNC;
    UCB0CTL1 = UCSSEL_2;
    UCB0BR0 = 8;
    UCB0BR1 = 0;
    UCB0CTL1 &= ~UCSWRST;
}

void SPI_write(unsigned char tx_data)
```

```

{
    while(!(IFG2 & UCB0TXIFG));
    UCB0TXBUF = tx_data;
    while(UCB0STAT & UCBUSY);
}

unsigned char SPI_read(void)
{
    unsigned char rx_data = 0;

    while(!(IFG2 & UCB0RXIFG));
    rx_data = UCB0RXBUF;
    while(UCB0STAT & UCBUSY);

    return rx_data;
}

unsigned char SPI_transfer(unsigned char tx_data)
{
    unsigned char rx_data = 0;

    while(!(IFG2 & UCB0TXIFG));
    UCB0TXBUF = tx_data;
    while(UCB0STAT & UCBUSY);

    while(!(IFG2 & UCB0RXIFG));
    rx_data = UCB0RXBUF;
    while(UCB0STAT & UCBUSY);

    return rx_data;
}

```

SSD1306.h

```

#include <MSP430.h>
#include "delay.h"
#include "HW_SPI.h"

#define OLED_PORT          P1OUT
#define OLED_DIR           P1DIR

#define RST_pin            BIT2
#define DC_pin             BIT3
#define CS_pin             BIT4

#define OLED_PORT_OUT()    (OLED_DIR |= (RST_pin | DC_pin | CS_pin))
#define OLED_RST_HIGH()    (OLED_PORT |= RST_pin)
#define OLED_RST_LOW()     (OLED_PORT &= ~RST_pin)
#define OLED_DC_HIGH()     (OLED_PORT |= DC_pin)
#define OLED_DC_LOW()      (OLED_PORT &= ~DC_pin)
#define OLED_CS_HIGH()     (OLED_PORT |= CS_pin)
#define OLED_CS_LOW()      (OLED_PORT &= ~CS_pin)

#define Set_Lower_Column_Start_Address_CMD 0x00

```

```

#define Set_Higher_Column_Start_Address_CMD 0x10
#define Set_Memory_Addressing_Mode_CMD 0x20
#define Set_Column_Address_CMD 0x21
#define Set_Page_Address_CMD 0x22
#define Set_Display_Start_Line_CMD 0x40
#define Set_Contrast_Control_CMD 0x81
#define Set_Charge_Pump_CMD 0x8D
#define Set_Segment_Remap_CMD 0xA0
#define Set_Entire_Display_ON_CMD 0xA4
#define Set_Normal_or_Inverse_Display_CMD 0xA6
#define Set_Multiplex_Ratio_CMD 0xA8
#define Set_Display_ON_or_OFF_CMD 0xAE
#define Set_Page_Start_Address_CMD 0xB0
#define Set_COM_Output_Scan_Direction_CMD 0xC0
#define Set_Display_Offset_CMD 0xD3
#define Set_Display_Clock_CMD 0xD5
#define Set_Pre_charge_Period_CMD 0xD9
#define Set_Common_HW_Config_CMD 0xDA
#define Set_VCOMH_Level_CMD 0xDB
#define Set_NOP_CMD 0xE3
#define Horizontal_Addressing_Mode 0x00
#define Vertical_Addressing_Mode 0x01
#define Page_Addressing_Mode 0x02
#define Disable_Charge_Pump 0x00
#define Enable_Charge_Pump 0x04
#define Column_Address_0_Mapped_to_SEG0 0x00
#define Column_Address_0_Mapped_to_SEG127 0x01
#define Normal_Display 0x00
#define Entire_Display_ON 0x01
#define Non_Inverted_Display 0x00
#define Inverted_Display 0x01
#define Display_OFF 0x00
#define Display_ON 0x01
#define Scan_from_COM0_to_63 0x00
#define Scan_from_COM63_to_0 0x08

#define x_size 128
#define x_max x_size
#define x_min 0
#define y_size 64
#define y_max 8
#define y_min 0

#define ON 1
#define OFF 0

#define YES 1
#define NO 0

#define HIGH 1
#define LOW 0

#define DAT 1
#define CMD 0

void setup_GPIOs(void);
void OLED_init(void);
void OLED_reset_sequence(void);

```

```

void OLED_write(unsigned char value, unsigned char type);
void OLED_gotoxy(unsigned char x_pos, unsigned char y_pos);
void OLED_fill(unsigned char bmp_data);
void OLED_clear_screen(void);
void OLED_cursor(unsigned char x_pos, unsigned char y_pos);
void OLED_print_char(unsigned char x_pos, unsigned char y_pos, unsigned char ch);
void OLED_print_string(unsigned char x_pos, unsigned char y_pos, unsigned char
*ch);
void OLED_print_chr(unsigned char x_pos, unsigned char y_pos, signed int value);
void OLED_print_int(unsigned char x_pos, unsigned char y_pos, signed long value);
void OLED_print_decimal(unsigned char x_pos, unsigned char y_pos, unsigned int
value, unsigned char points);
void OLED_print_float(unsigned char x_pos, unsigned char y_pos, float value,
unsigned char points);

```

SSD1306.c

```

#include "SSD1306.h"
#include "fonts.h"

void setup_GPIOs(void)
{
    OLED_PORT_OUT();
    P1SEL2 = BIT5 | BIT7;
    P1SEL = BIT5 | BIT7;
}

void OLED_init(void)
{
    setup_GPIOs();
    HW_SPI_init();

    OLED_reset_sequence();

    OLED_write((Set_Display_ON_or_OFF_CMD + Display_OFF), CMD);

    OLED_write(Set_Display_Clock_CMD, CMD);
    OLED_write(0x80, CMD);

    OLED_write(Set_Multiplex_Ratio_CMD, CMD);
    OLED_write(0x3F, CMD);

    OLED_write(Set_Display_Offset_CMD, CMD);
    OLED_write(0x00, CMD);

    OLED_write((Set_Display_Start_Line_CMD | 0x00), CMD);

    OLED_write(Set_Charge_Pump_CMD, CMD);
    OLED_write((Set_Higher_Column_Start_Address_CMD | Enable_Charge_Pump), CMD);

    OLED_write(Set_Memory_Addressing_Mode_CMD, CMD);
    OLED_write(Page_Addressing_Mode, CMD);

    OLED_write((Set_Segment_Remap_CMD | Column_Address_0_Mapped_to_SEG127), CMD);

    OLED_write((Set_COM_Output_Scan_Direction_CMD | Scan_from_COM63_to_0), CMD);

```

```

OLED_write(Set_Common_Hw_Config_CMD, CMD);
OLED_write(0x12, CMD);

OLED_write(Set_Contrast_Control_CMD, CMD);
OLED_write(0xCF, CMD);

OLED_write(Set_Pre_charge_Period_CMD, CMD);
OLED_write(0xF1, CMD);

OLED_write(Set_VCOMH_Level_CMD, CMD);
OLED_write(0x40, CMD);

OLED_write((Set_Entire_Display_ON_CMD | Normal_Display), CMD);

OLED_write((Set_Normal_or_Inverse_Display_CMD | Non_Inverted_Display), CMD);

OLED_write((Set_Display_ON_or_OFF_CMD + Display_ON) , CMD);

OLED_gotoxy(0, 0);

OLED_clear_screen();
}

void OLED_reset_sequence(void)
{
    delay_ms(40);
    OLED_RST_LOW();
    delay_ms(40);
    OLED_RST_HIGH();
}

void OLED_write(unsigned char value, unsigned char type)
{
    switch(type)
    {
        case DAT:
        {
            OLED_DC_HIGH();
            break;
        }
        case CMD:
        {
            OLED_DC_LOW();
            break;
        }
    }

    OLED_CS_LOW();
    SPI_transfer(value);
    OLED_CS_HIGH();
}

void OLED_gotoxy(unsigned char x_pos, unsigned char y_pos)
{
    OLED_write((Set_Page_Start_Address_CMD + y_pos), CMD);
}

```

```

    OLED_write(((x_pos & 0x0F) | Set_Lower_Column_Start_Address_CMD), CMD);
    OLED_write(((x_pos & 0xF0) >> 0x04) | Set_Higher_Column_Start_Address_CMD),
CMD);
}

void OLED_fill(unsigned char bmp_data)
{
    unsigned char x_pos = 0;
    unsigned char page = 0;

    for(page = y_min; page < y_max; page++)
    {
        OLED_write((Set_Page_Start_Address_CMD + page), CMD);
        OLED_write(Set_Lower_Column_Start_Address_CMD, CMD);
        OLED_write(Set_Higher_Column_Start_Address_CMD, CMD);

        for(x_pos = x_min; x_pos < x_max; x_pos++)
        {
            OLED_write(bmp_data, DAT);
        }
    }
}

void OLED_clear_screen(void)
{
    OLED_fill(0x00);
}

void OLED_cursor(unsigned char x_pos, unsigned char y_pos)
{
    unsigned char i = 0;

    if(y_pos != 0)
    {
        if(x_pos == 1)
        {
            OLED_gotoxy(0x00, (y_pos + 0x02));
        }
        else
        {
            OLED_gotoxy((0x50 + ((x_pos - 0x02) * 0x06)), (y_pos + 0x02));
        }

        for(i = 0; i < 6; i++)
        {
            OLED_write(0xFF, DAT);
        }
    }
}

void OLED_print_char(unsigned char x_pos, unsigned char y_pos, unsigned char ch)
{
    unsigned char chr = 0;
    unsigned char s = 0;
}

```

```

chr = (ch - 32);

if(x_pos > (x_max - 6))
{
    x_pos = 0;
    y_pos++;
}

OLED_gotoxy(x_pos, y_pos);

for(s = 0; s < 6; s++)
{
    OLED_write(font_regular[chr][s], DAT);
}
}

void OLED_print_string(unsigned char x_pos, unsigned char y_pos, unsigned char *ch)
{
    unsigned char chr = 0;
    unsigned char i = 0;
    unsigned char j = 0;

    while(ch[j] != '\0')
    {
        chr = (ch[j] - 32);

        if(x_pos > (x_max - 0x06))
        {
            x_pos = 0x00;
            y_pos++;
        }
        OLED_gotoxy(x_pos, y_pos);

        for(i = 0; i < 6; i++)
        {
            OLED_write(font_regular[chr][i], DAT);
        }

        j++;
        x_pos += 6;
    }
}

void OLED_print_chr(unsigned char x_pos, unsigned char y_pos, signed int value)
{
    unsigned char ch = 0;

    if(value < 0)
    {
        OLED_print_char(x_pos, y_pos, '-');
        value = -value;
    }
    else
    {
        OLED_print_char(x_pos, y_pos, ' ');
    }
}

```

```

if((value > 99) && (value <= 999))
{
    ch = (value / 100);
    OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));
    ch = ((value % 100) / 10);
    OLED_print_char((x_pos + 12), y_pos , (0x30 + ch));
    ch = (value % 10);
    OLED_print_char((x_pos + 18), y_pos , (0x30 + ch));
}
else if((value > 9) && (value <= 99))
{
    ch = ((value % 100) / 10);
    OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));
    ch = (value % 10);
    OLED_print_char((x_pos + 12), y_pos , (0x30 + ch));
    OLED_print_char((x_pos + 18), y_pos , 0x20);
}
else if((value >= 0) && (value <= 9))
{
    ch = (value % 10);
    OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));
    OLED_print_char((x_pos + 12), y_pos , 0x20);
    OLED_print_char((x_pos + 18), y_pos , 0x20);
}
}

void OLED_print_int(unsigned char x_pos, unsigned char y_pos, signed long value)
{
    unsigned char ch = 0;

    if(value < 0)
    {
        OLED_print_char(x_pos, y_pos, '-');
        value = -value;
    }
    else
    {
        OLED_print_char(x_pos, y_pos, ' ');
    }

    if(value > 9999)
    {
        ch = (value / 10000);
        OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));

        ch = ((value % 10000)/ 1000);
        OLED_print_char((x_pos + 12), y_pos , (0x30 + ch));

        ch = ((value % 1000) / 100);
        OLED_print_char((x_pos + 18), y_pos , (0x30 + ch));

        ch = ((value % 100) / 10);
        OLED_print_char((x_pos + 24), y_pos , (0x30 + ch));

        ch = (value % 10);
        OLED_print_char((x_pos + 30), y_pos , (0x30 + ch));
    }
}

```

```

else if((value > 999) && (value <= 9999))
{
    ch = ((value % 1000)/ 1000);
    OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));

    ch = ((value % 100) / 100);
    OLED_print_char((x_pos + 12), y_pos , (0x30 + ch));

    ch = ((value % 10) / 10);
    OLED_print_char((x_pos + 18), y_pos , (0x30 + ch));
    OLED_print_char((x_pos + 24), y_pos , (0x30 + ch));
}
else if((value > 99) && (value <= 999))
{
    ch = ((value % 1000) / 100);
    OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));

    ch = ((value % 100) / 10);
    OLED_print_char((x_pos + 12), y_pos , (0x30 + ch));

    ch = (value % 10);
    OLED_print_char((x_pos + 18), y_pos , (0x30 + ch));
    OLED_print_char((x_pos + 24), y_pos , 0x20);
    OLED_print_char((x_pos + 30), y_pos , 0x20);
}
else if((value > 9) && (value <= 99))
{
    ch = ((value % 100) / 10);
    OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));

    ch = (value % 10);
    OLED_print_char((x_pos + 12), y_pos , (0x30 + ch));

    OLED_print_char((x_pos + 18), y_pos , 0x20);
    OLED_print_char((x_pos + 24), y_pos , 0x20);
    OLED_print_char((x_pos + 30), y_pos , 0x20);
}
else
{
    ch = (value % 10);
    OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));
    OLED_print_char((x_pos + 12), y_pos , 0x20);
    OLED_print_char((x_pos + 18), y_pos , 0x20);
    OLED_print_char((x_pos + 24), y_pos , 0x20);
    OLED_print_char((x_pos + 30), y_pos , 0x20);
}
}

void OLED_print_decimal(unsigned char x_pos, unsigned char y_pos, unsigned int value, unsigned char points)
{
    unsigned char ch = 0;

    OLED_print_char(x_pos, y_pos, '.');

```

```

ch = (value / 1000);
OLED_print_char((x_pos + 6), y_pos , (0x30 + ch));

if(points > 1)
{
    ch = ((value % 1000) / 100);
    OLED_print_char((x_pos + 12), y_pos , (0x30 + ch));

    if(points > 2)
    {
        ch = ((value % 100) / 10);
        OLED_print_char((x_pos + 18), y_pos , (0x30 + ch));

        if(points > 3)
        {
            ch = (value % 10);
            OLED_print_char((x_pos + 24), y_pos , (0x30 + ch));
        }
    }
}

void OLED_print_float(unsigned char x_pos, unsigned char y_pos, float value,
unsigned char points)
{
    signed long tmp = 0;

    tmp = value;
    OLED_print_int(x_pos, y_pos, tmp);
    tmp = ((value - tmp) * 10000);

    if(tmp < 0)
    {
        tmp = -tmp;
    }

    if((value >= 10000) && (value < 100000))
    {
        OLED_print_decimal((x_pos + 36), y_pos, tmp, points);
    }
    else if((value >= 1000) && (value < 10000))
    {
        OLED_print_decimal((x_pos + 30), y_pos, tmp, points);
    }
    else if((value >= 100) && (value < 1000))
    {
        OLED_print_decimal((x_pos + 24), y_pos, tmp, points);
    }
    else if((value >= 10) && (value < 100))
    {
        OLED_print_decimal((x_pos + 18), y_pos, tmp, points);
    }
    else if(value < 10)
    {
        OLED_print_decimal((x_pos + 12), y_pos, tmp, points);
        if(value < 0)

```

```

    {
        OLED_print_char(x_pos, y_pos, '-');
    }
    else
    {
        OLED_print_char(x_pos, y_pos, ' ');
    }
}
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "HW_SPI.h"
#include "SSD1306.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USCI_B0_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

void main(void)
{
    signed char c = -11;
    signed int i = -111;
    float f = -1.9;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 USCI_B0 */
    USCI_B0_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    OLED_init();

    OLED_print_string(4, 0, "MSP430G2553 SSD1306");
    OLED_print_string(16, 1, "USCI_B0 SPI Test");
    OLED_print_string(0, 4, "Char :");
    OLED_print_string(0, 5, "Int. :");
    OLED_print_string(0, 6, "Float:");

    while(1)

```

```

    {
        OLED_print_chr(92, 4, c);
        OLED_print_int(92, 5, i);
        OLED_print_float(92, 6, f, 1);
        c++;
        i++;
        f += 0.1;
        delay_ms(200);
    };
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Port Select 2 Register */
    P1SEL2 = BIT5 | BIT7;

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT5 | BIT7;

    /* Port 1 Direction Register */
    P1DIR = BIT2 | BIT3 | BIT4;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* Port 3 Output Register */
    P3OUT = 0;

    /* Port 3 Direction Register */
    P3DIR = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */
}

```

```

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF)
    {
        /* Adjust this accordingly to your VCC rise time */
        delay_cycles(100000);

        // Follow recommended flow. First, clear all DCOx and MODx bits. Then
        // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_8MHZ;          /* Set DCO to 8MHz */
        DCOCTL = CALDCO_8MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;

    /*
     * Basic Clock System Control 3
     *
     * XT2S_0 -- 0.4 - 1 MHz
     * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
     MHz crystal or resonator
     * XCAP_1 -- ~6 pF
     */
    BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

    /* USER CODE START (section: BCSplus_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

```

```

void USCI_B0_graceInit(void)
{
    /* USER CODE START (section: USCI_B0_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: USCI_B0_graceInit_prologue) */

    /* Disable USCI */
    UCB0CTL1 |= UCSWRST;

    /*
     * Control Register 0
     *
     * UCCKPH -- Data is captured on the first UCLK edge and changed on the
     following edge
     * ~UCCKPL -- Inactive state is low
     * UCMSB -- MSB first
     * ~UC7BIT -- 8-bit
     * UCMST -- Master mode
     * UCMODE_1 -- 4-Pin SPI with UCxSTE active high: slave enabled when UCxSTE =
     1
     * UCSYNC -- Synchronous Mode
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    UCB0CTL0 = UCCKPH | UCMSB | UCMST | UCMODE_1 | UCSYNC;

    /*
     * Control Register 1
     *
     * UCSSEL_2 -- SMCLK
     * UCSWRST -- Enabled. USCI logic held in reset state
     */
    UCB0CTL1 = UCSSEL_2 | UCSWRST;

    /* Bit Rate Control Register 0 */
    UCB0BR0 = 8;

    /* Enable USCI */
    UCB0CTL1 &= ~UCSWRST;

    /* USER CODE START (section: USCI_B0_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: USCI_B0_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     */
}

```

```

    * GIE -- General interrupt enable
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
_bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

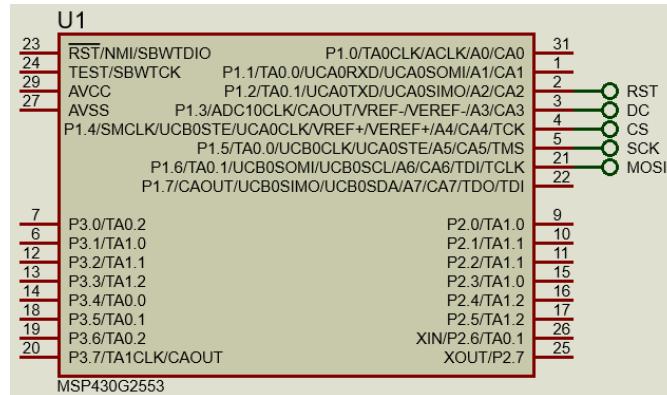
    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

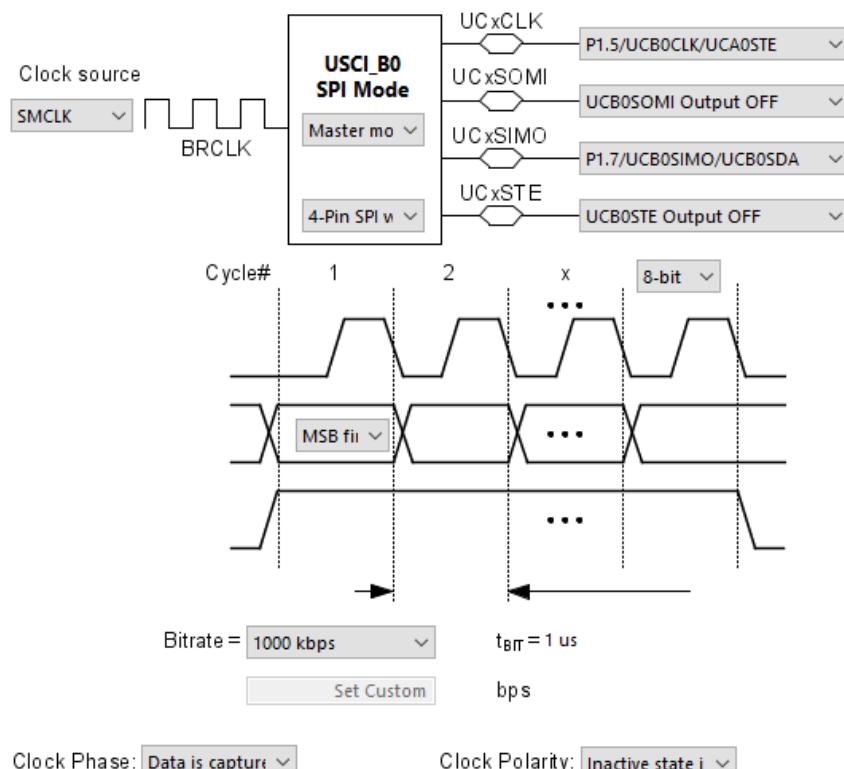
Simulation

The model for SPI-based SSD1306 OLED display is not available in Proteus VSM and so it cannot be simulated. Only the pinouts are shown in the schematic below.

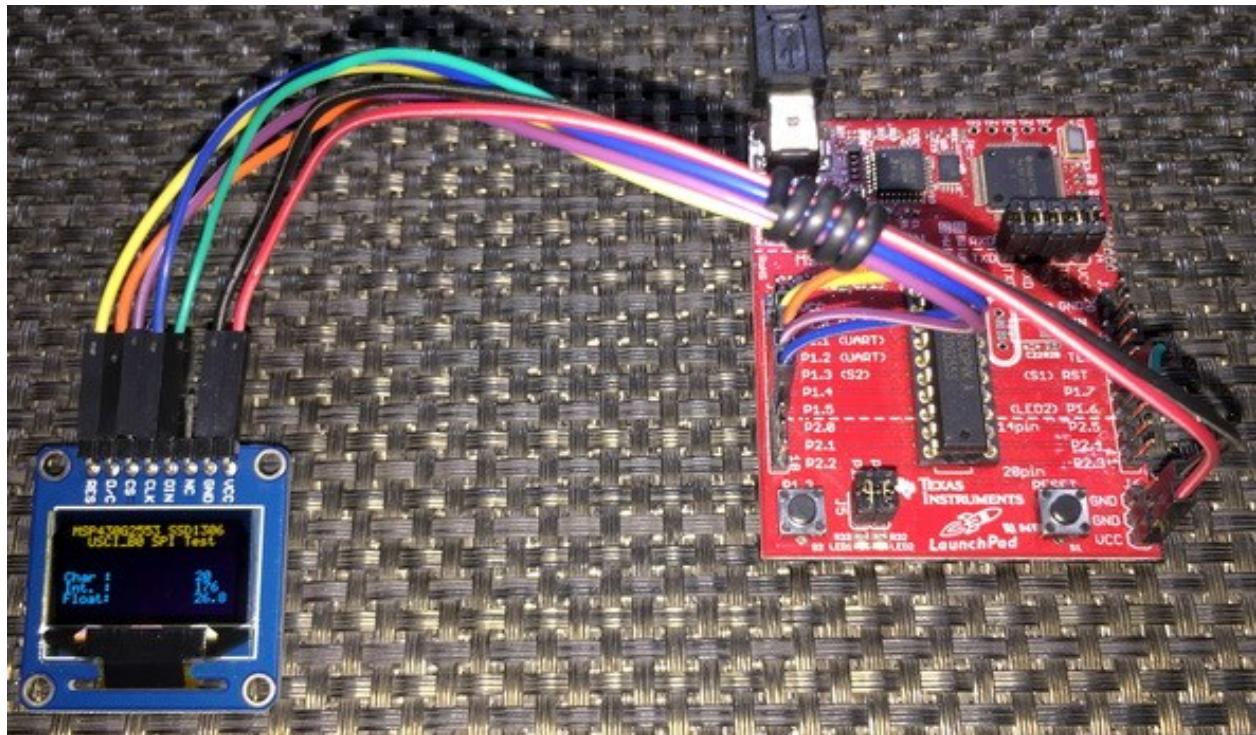


Explanation

The code here basically uses the same functions as in the previous example except for the fact that USCI_B0 is used in half-duplex mode here. The rest of the code is the driver implementation for SSD1306 OLED display. Note that the driver has been cut short of graphical functions due to low memory capacity of Value-Line Devices. Explaining the operation of the OLED display is beyond the scope of this article.



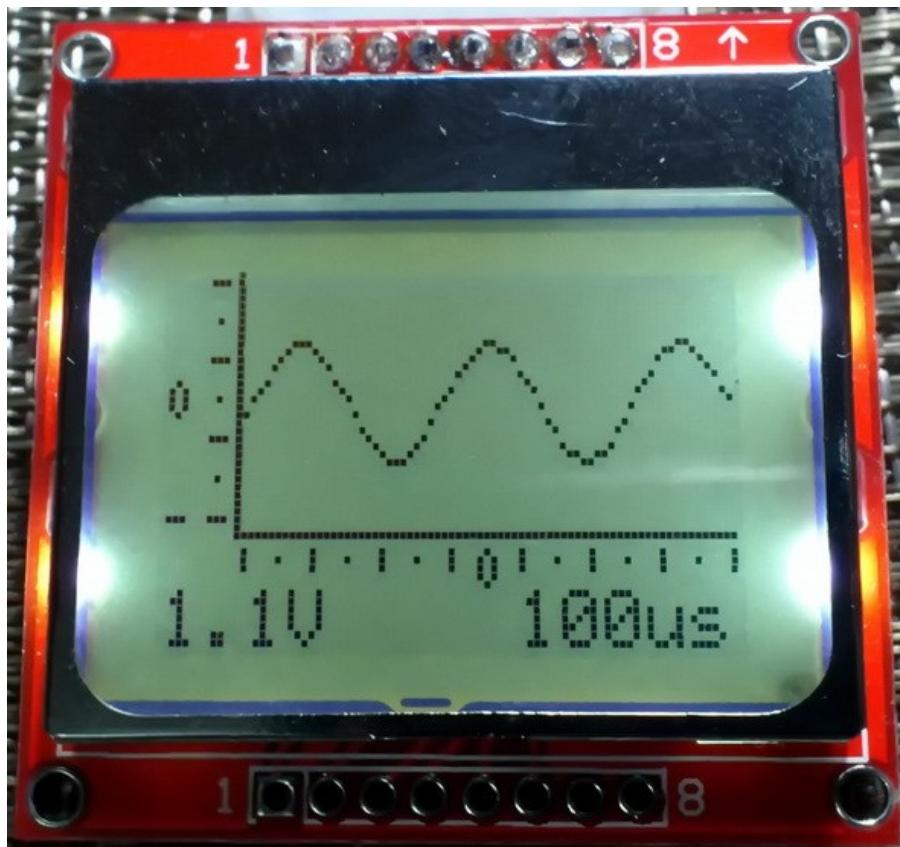
Demo



Demo video: <https://youtu.be/nxIARm-RGoY>.

Software SPI – Interfacing MCP4921

Software SPI is the only solution in absence of USI/USCI modules. We need to code every step after studying device datasheet since there are four modes of SPI communication and we need to be sure which modes are supported by the device we are trying to communicate with. It should be noted that software SPI is not as fast as hardware-based SPI and this become more evident when software SPI is used to drive displays like TFTs, OLEDs, dot-matrix displays and monochrome displays like the one shown below. Software SPI may encounter issues due to glitches if improperly coded.



However, for a beginner, software-based SPI is good for understanding the concept behind SPI communication. Shown below is a typical SPI bus timing diagram. As you see it is simply a pattern of ones and zeroes. Digital I/O can generate these patterns if coded.



Code Example

MCP4921.h

```
#include <msp430.h>
#include "delay.h"

#define SW_SPI_DIR          P2DIR
#define SW_SPI_OUT          P2OUT
#define SW_SPI_IN           P2IN

#define SCK_pin              BIT0
#define CS_pin               BIT1
#define SDI_pin              BIT2
#define LDAC_pin             BIT3

#define SCK_DIR_OUT()        do{SW_SPI_DIR |= SCK_pin;}while(0)
#define SCK_DIR_IN()         do{SW_SPI_DIR &= ~SCK_pin;}while(0)
#define CS_DIR_OUT()         do{SW_SPI_DIR |= CS_pin;}while(0)
#define CS_DIR_IN()          do{SW_SPI_DIR &= ~CS_pin;}while(0)
#define SDI_DIR_OUT()        do{SW_SPI_DIR |= SDI_pin;}while(0)
#define SDI_DIR_IN()         do{SW_SPI_DIR &= ~SDI_pin;}while(0)
#define LDAC_DIR_OUT()       do{SW_SPI_DIR |= LDAC_pin;}while(0)
#define LDAC_DIR_IN()        do{SW_SPI_DIR &= ~LDAC_pin;}while(0)

#define SCK_HIGH()           do{SW_SPI_OUT |= SCK_pin;}while(0)
#define SCK_LOW()            do{SW_SPI_OUT &= ~SCK_pin;}while(0)
#define CS_HIGH()            do{SW_SPI_OUT |= CS_pin;}while(0)
#define CS_LOW()             do{SW_SPI_OUT &= ~CS_pin;}while(0)
#define SDI_HIGH()           do{SW_SPI_OUT |= SDI_pin;}while(0)
#define SDI_LOW()            do{SW_SPI_OUT &= ~SDI_pin;}while(0)
#define LDAC_HIGH()          do{SW_SPI_OUT |= LDAC_pin;}while(0)
#define LDAC_LOW()           do{SW_SPI_OUT &= ~LDAC_pin;}while(0)

#define ignore_cmd           0x80
#define DAC_write_cmd        0x00
#define Buffer_on             0x40
#define Buffer_off            0x00
#define Gain_1X               0x20
#define Gain_2X               0x00
#define Run_cmd                0x10
#define Shutdown              0x00

void MCP4921_init(void);
void MCP4921_write(unsigned char cmd, unsigned int dac_value);
```

MCP4921.c

```
#include "MCP4921.h"

void MCP4921_init(void)
{
    CS_DIR_OUT();
    SCK_DIR_OUT();
```

```

SDI_DIR_OUT();
LDAC_DIR_OUT();

CS_HIGH();
LDAC_HIGH();
SCK_HIGH();
SDI_HIGH();
}

void MCP4921_write(unsigned char cmd, unsigned int dac_value)
{
    unsigned char s = 16;

    unsigned int value = 0;

    value = cmd;
    value <= 8;
    value |= (dac_value & 0x0FFF);

    CS_LOW();

    while(s > 0)
    {
        if((value & 0x8000) != 0)
        {
            SDI_HIGH();
        }
        else
        {
            SDI_LOW();
        }

        SCK_LOW();
        SCK_HIGH();
        value <= 1;
        s--;
    }

    LDAC_LOW();
    CS_HIGH();
    delay_us(10);
    LDAC_HIGH();
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "MCP4921.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

```

```
const unsigned int sine_table[33] =
{
    0,
    100,
    201,
    301,
    400,
    498,
    595,
    690,
    784,
    876,
    965,
    1053,
    1138,
    1220,
    1299,
    1375,
    1448,
    1517,
    1583,
    1645,
    1703,
    1757,
    1806,
    1851,
    1892,
    1928,
    1960,
    1987,
    2026,
    2038,
    2046,
    2047
};

const unsigned int triangle_table[33] =
{
    0,
    64,
    128,
    192,
    256,
    320,
    384,
    448,
    512,
    576,
    640,
    704,
    768,
    832,
    896,
    960,
    1024,
    1088,
    1152,
    1216,
```

```
1280,
1344,
1408,
1472,
1536,
1600,
1664,
1728,
1792,
1856,
1920,
1984,
2047
};

const unsigned int square_table[33] =
{
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
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    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047,
    2047
};

void main(void)
{
    unsigned char s = 0;
    unsigned char wave = 0;
```

```

/* Stop watchdog timer from timing out during initial start-up. */
WDTCTL = WDTPW | WDTHOLD;

/* initialize Config for the MSP430 GPIO */
GPIO_graceInit();

/* initialize Config for the MSP430 2xx family clock systems (BCS) */
BCSplus_graceInit();

/* initialize Config for the MSP430 System Registers */
System_graceInit();

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

MCP4921_init();

while(1)
{
    if((P1IN & BIT3) == 0)
    {
        P1OUT |= BIT0;

        while((P1IN & BIT3) == 0);
        wave++;

        if(wave > 2)
        {
            wave = 0;
        }

        P1OUT &= ~BIT0;
    }

    else
    {
        switch(wave)
        {
            case 1:
            {
                for(s = 0; s < 32; s++)
                {
                    MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 + square_table[s]));
                    delay_ms(10);
                }
                for(s = 31; s > 0; s--)
                {
                    MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 + square_table[s]));
                    delay_ms(10);
                }
                for(s = 0; s < 32; s++)
                {
                    MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 - square_table[s]));
                    delay_ms(10);
                }
                for(s = 31; s > 0; s--)
            }
        }
    }
}

```

```

        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 - square_table[s]));
            delay_ms(10);
        }
        break;
    }
    case 2:
    {
        for(s = 0; s < 32; s++)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 + triangle_table[s]));
            delay_ms(10);
        }
        for(s = 31; s > 0; s--)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 + triangle_table[s]));
            delay_ms(10);
        }
        for(s = 0; s < 32; s++)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 - triangle_table[s]));
            delay_ms(10);
        }
        for(s = 31; s > 0; s--)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 - triangle_table[s]));
            delay_ms(10);
        }
        break;
    }
    default:
    {
        for(s = 0; s < 32; s++)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 + sine_table[s]));
            delay_ms(10);
        }
        for(s = 31; s > 0; s--)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 + sine_table[s]));
            delay_ms(10);
        }
        for(s = 0; s < 32; s++)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run_cmd), (2047 - sine_table[s]));
            delay_ms(10);
        }
        for(s = 31; s > 0; s--)
        {
            MCP4921_write((DAC_write_cmd | Buffer_on | Gain_1X |
Run cmd), (2047 - sine_table[s]));
        }
    }
}

```

```

        delay_ms(10);
    }
    break;
}
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = BIT3;

    /* Port 1 Direction Register */
    P1DIR = BIT0;

    /* Port 1 Resistor Enable Register */
    P1REN = BIT3;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Port Select Register */
    P2SEL &= ~(BIT6 | BIT7);

    /* Port 2 Direction Register */
    P2DIR = BIT0 | BIT1 | BIT2 | BIT3;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*

```

```

    * Basic Clock System Control 2
    *
    * SELM_0 -- DCOCLK
    * DIVM_0 -- Divide by 1
    * ~SELS -- DCOCLK
    * DIVS_0 -- Divide by 1
    * ~DCOR -- DCO uses internal resistor
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
    * SR, Status Register
    *
    * ~SCG1 -- Disable System clock generator 1
    * ~SCG0 -- Disable System clock generator 0

```

```

    * ~OSCOFF -- Oscillator On
    * ~CPUOFF -- CPU On
    * GIE -- General interrupt enable
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
_bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

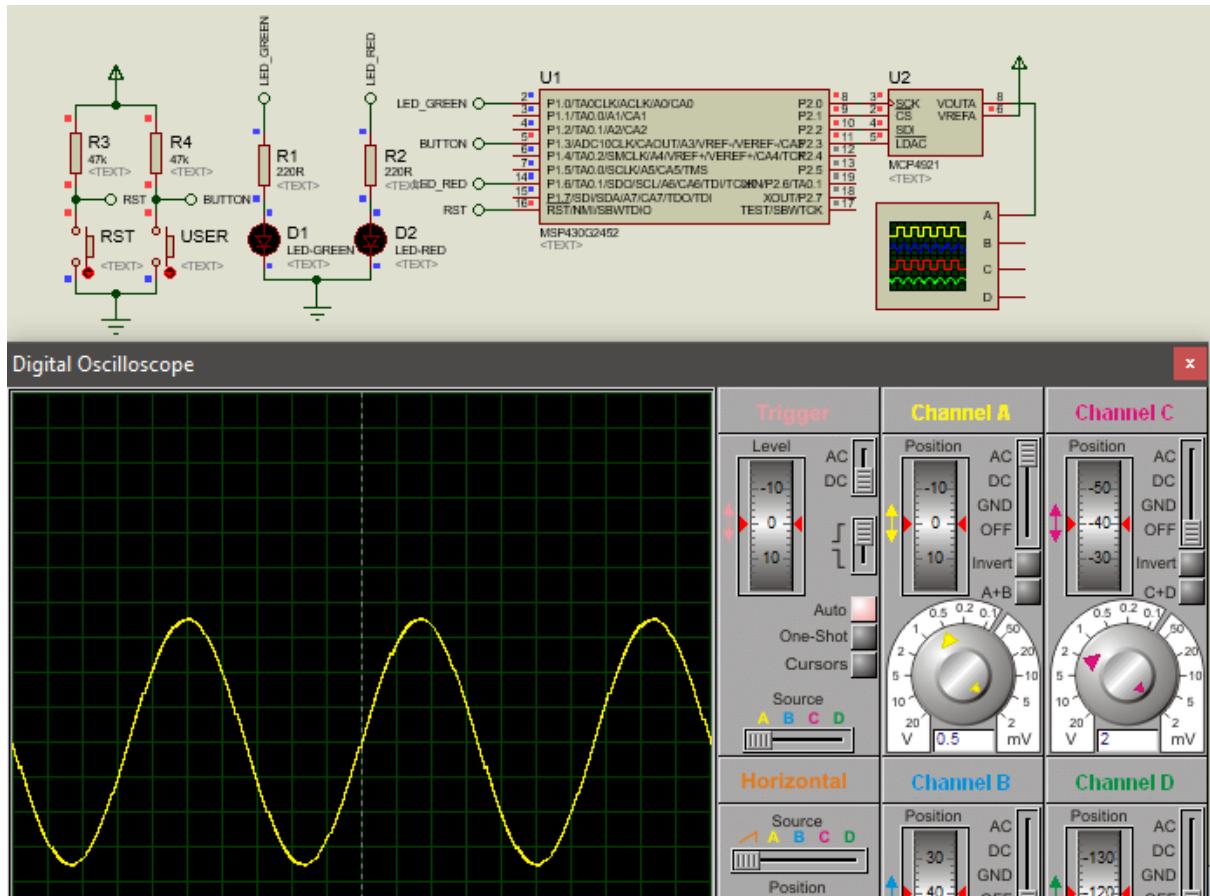
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation



Explanation

Software SPI requires digital I/Os only. Software SPI is achieved using bit-banging technique. For this demo, a MCP4921 12-bit DAC is used. This DAC communicates with a host micro using SPI bus. Check the function below. Here from the data bit to the clock signal, everything is controlled by changing the logic states of digital I/Os. The changes are done in such a way that they do exactly the same thing a hardware SPI would have done. If we used hardware-based SPI as in the last example, it would have taken one or two lines of code unlike the long listing given below. This extra coding along with some hardware limitations reduces SPI clock speed.

```
void MCP4921_write(unsigned char cmd, unsigned int dac_value)
{
    unsigned char s = 16;
    unsigned int value = 0;

    value = cmd;
    value <= 8;
    value |= (dac_value & 0x0FFF);

    CS_LOW();
```

```

while(s > 0)
{
    if((value & 0x8000) != 0)
    {
        SDI_HIGH();
    }
    else
    {
        SDI_LOW();
    }

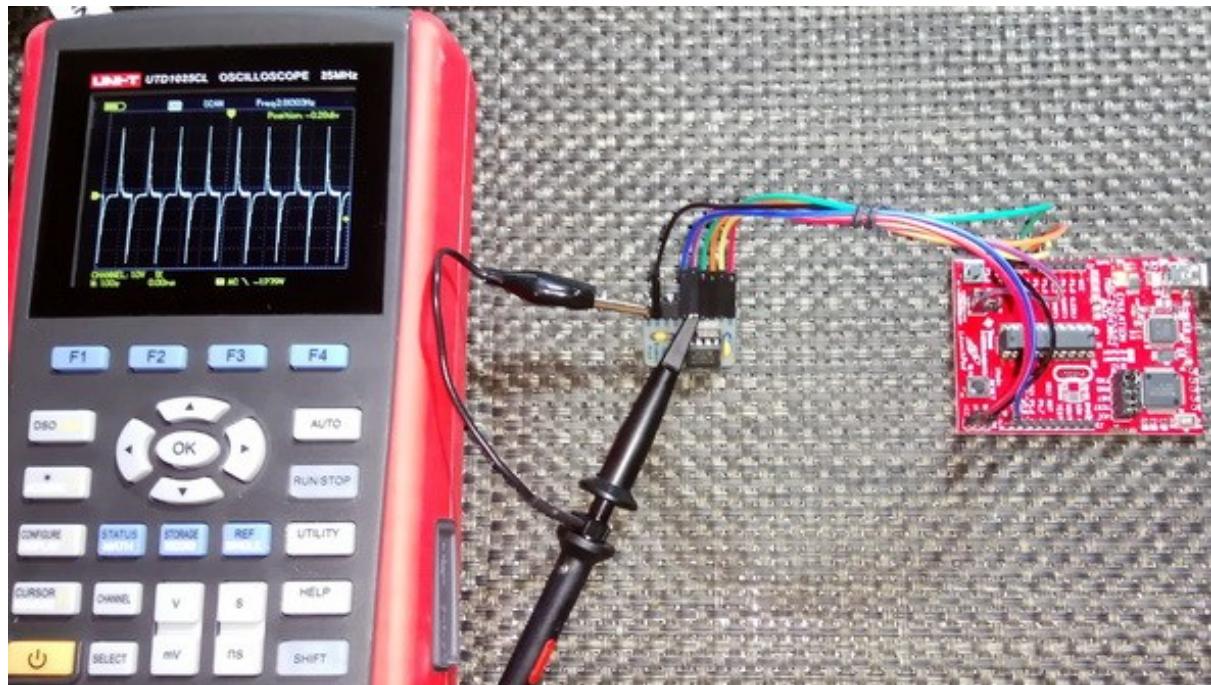
    SCK_LOW();
    SCK_HIGH();
    value <= 1;
    s--;
}

LDAC_LOW();
CS_HIGH();
delay_us(10);
LDAC_HIGH();
}

```

The rest of the code simply does the work of a **Digital Signal Synthesizer (DSS)** a.k.a waveform generator. It generates three types of waves using wave tables and some basic mathematics.

Demo



Demo video: <https://www.youtube.com/watch?v=gPZJyL9LWQc>.

LCD using DIO Bit-Banging

Some MSP430 devices, especially the 14-pin parts have limited number of pins and so it is wise to use port expanders like MCP23S17 or MAX7300, serial LCDs and shift register-based LCDs. Everything is same here just as in the LCD example. The only exception is the method of handling the device responsible for port-expansion task. In some cases, it may be necessary to use additional hardware like UART/I2C/SPI or emulate these methods using software when such dedicated hardware is either unavailable or used up for some other jobs. Thus, in such cases, things are no longer as simple as with digital I/Os. In the software end, we will also need to code for the additional interface too.



Everything that has an advantage must also have a disadvantage. The primary disadvantages that we are left with when using port-expanded LCDs are slower displays and vulnerability to EMI. Noise and glitches are big issues when your device is working in a harsh industrial environment surrounded by electromagnetics. Likewise, if the wires connecting the LCD pack with the host MCU are too long, it is highly likely to fail or show garbage characters after some time. The simplest solution to these issues are to use shorter connection wires, slower communication speed and frequent but periodic reinitialization of the LCD pack. Again, all these lead to slow functioning. Thus, a careful system design is an absolute must.

The most popular methods of driving alphanumeric LCDs with fewer wires include:

- SPI-based solutions using shift registers like 74HC595 and CD4094B
- I2C-based solutions using I2C port expander ICs like PCF8574 and MCP23S17.

We can use either hardware-based SPI/I2C modules or emulate these in software using bit-banging methods. The former adds some much-needed processing speed which is impossible with bit-banging.

In this segment, we will see how to use a CD4094B CMOS shift-register with software SPI to drive an alphanumeric LCD.

Code Example

lcd.h

```
#include <msp430.h>
#include <delay.h>

#define LCD_PORT P2OUT

#define SDO BIT0
#define SCK BIT1
#define STB BIT2

#define SDO_HIGH LCD_PORT |= SDO
#define SDO_LOW LCD_PORT &= ~SDO

#define SCK_HIGH LCD_PORT |= SCK
#define SCK_LOW LCD_PORT &= ~SCK

#define STB_HIGH LCD_PORT |= STB
#define STB_LOW LCD_PORT &= ~STB

#define clear_display 0x01
#define goto_home 0x02

#define cursor_direction_inc (0x04 | 0x02)
#define cursor_direction_dec (0x04 | 0x00)
#define display_shift (0x04 | 0x01)
#define display_no_shift (0x04 | 0x00)

#define display_on (0x08 | 0x04)
#define display_off (0x08 | 0x02)
#define cursor_on (0x08 | 0x02)
#define cursor_off (0x08 | 0x00)
#define blink_on (0x08 | 0x01)
#define blink_off (0x08 | 0x00)

#define _8_pin_interface (0x20 | 0x10)
#define _4_pin_interface (0x20 | 0x00)
#define _2_row_display (0x20 | 0x08)
#define _1_row_display (0x20 | 0x00)
#define _5x10_dots (0x20 | 0x40)
#define _5x7_dots (0x20 | 0x00)

#define dly 1

unsigned char data_value;

void SIPO(void);
void LCD_init(void);
void LCD_command(unsigned char value);
void LCD_send_data(unsigned char value);
void LCD_4bit_send(unsigned char lcd_data);
void LCD_putstr(char *lcd_string);
void LCD_putchar(char char_data);
```

```
void LCD_clear_home(void);
void LCD_goto(unsigned char x_pos, unsigned char y_pos);
```

lcd.c

```
#include "lcd.h"

void SIPO(void)
{
    unsigned char bit = 0;
    unsigned char clk = 8;
    unsigned char temp = 0;

    temp = data_value;
    STB_LOW;

    while(clk > 0)
    {
        bit = ((temp & 0x80) >> 0x07);
        bit &= 0x01;

        switch(bit)
        {
            case 0:
            {
                SDO_LOW;
                break;
            }
            default:
            {
                SDO_HIGH;
                break;
            }
        }

        SCK_HIGH;

        temp <<= 1;
        clk--;
    }

    STB_HIGH;
}

void LCD_init(void)
{
    unsigned char t = 0x0A;

    data_value = 0x08;
    SIPO();
    while(t > 0x00)
    {
        delay_ms(dly);
    }
}
```

```

        t--;
    };

    data_value = 0x30;
    SIPO();

    data_value |= 0x08;
    SIPO();
    delay_ms(dly);
    data_value &= 0xF7;
    SIPO();
    delay_ms(dly);

    data_value = 0x30;
    SIPO();

    data_value |= 0x08;
    SIPO();
    delay_ms(dly);
    data_value &= 0xF7;
    SIPO();
    delay_ms(dly);

    data_value = 0x30;
    SIPO();

    data_value |= 0x08;
    SIPO();
    delay_ms(dly);
    data_value &= 0xF7;
    SIPO();
    delay_ms(dly);

    data_value = 0x20;
    SIPO();

    data_value |= 0x08;
    SIPO();
    delay_ms(dly);
    data_value &= 0xF7;
    SIPO();
    delay_ms(dly);

    LCD_command(_4_pin_interface | _2_row_display | _5x7_dots);
    LCD_command(display_on | cursor_off | blink_off);
    LCD_command(clear_display);
    LCD_command(cursor_direction_inc | display_no_shift);
}

void LCD_command(unsigned char value)
{
    data_value &= 0xFB;
    SIPO();
    LCD_4bit_send(value);
}

void LCD_send_data(unsigned char value)

```

```

{
    data_value |= 0x04;
    SIPO();
    LCD_4bit_send(value);
}

void LCD_4bit_send(unsigned char lcd_data)
{
    unsigned char temp = 0x00;

    temp = (lcd_data & 0xF0);
    data_value &= 0x0F;
    data_value |= temp;
    SIPO();

    data_value |= 0x08;
    SIPO();
    delay_ms(dly);
    data_value &= 0xF7;
    SIPO();
    delay_ms(dly);

    temp = (lcd_data & 0x0F);
    temp <= 0x04;
    data_value &= 0x0F;
    data_value |= temp;
    SIPO();

    data_value |= 0x08;
    SIPO();
    delay_ms(dly);
    data_value &= 0xF7;
    SIPO();
    delay_ms(dly);
}

void LCD_putstr(char *lcd_string)
{
    while (*lcd_string != '\0')
    {
        LCD_send_data(*lcd_string);
        lcd_string++;
    };
}

void LCD_putchar(char char_data)
{
    LCD_send_data(char_data);
}

void LCD_clear_home(void)
{
    LCD_command(clear_display);
    LCD_command(goto_home);
}

```

```

void LCD_goto(unsigned char x_pos,unsigned char y_pos)
{
    if(y_pos == 0)
    {
        LCD_command(0x80 | x_pos);
    }
    else
    {
        LCD_command(0x80 | 0x40 | x_pos);
    }
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "lcd.h"

void BCSplus_graceInit(void);
void GPIO_graceInit(void);
void System_graceInit(void);

/*
 * main.c
 */
void main(void)
{
    unsigned char s = 0x00;

    const char txt1[] = {"MICROARENA"};
    const char txt2[] = {"SShahryiar"};
    const char txt3[] = {"MSP-EXP430G2"};
    const char txt4[] = {"Launchpad!"};

    BCSplus_graceInit();
    GPIO_graceInit();
    System_graceInit();
    LCD_init();

    LCD_clear_home();

    LCD_goto(3, 0);
    LCD_putstr(txt1);
    LCD_goto(3, 1);
    LCD_putstr(txt2);
    delay_ms(2600);

    LCD_clear_home();

    for(s = 0; s < 12; s++)
    {
        LCD_goto((2 + s), 0);
        LCD_putchar(txt3[s]);
        delay_ms(60);
    }
}

```

```

for(s = 0; s < 10; s++)
{
    LCD_goto((3 + s), 1);
    LCD_putchar(txt4[s]);
    delay_ms(60);
}

s = 0;
LCD_clear_home();

LCD_goto(3, 0);
LCD_putstr(txt1);

while(1)
{
    show_value(s);
    s++;
    delay_ms(200);
};

}

void BCSplus_graceInit(void)
{
/*
 * Basic Clock System Control 2
 *
 * SELM_0 -- DCOCLK
 * DIVM_0 -- Divide by 1
 * ~SELS -- DCOCLK
 * DIVS_0 -- Divide by 1
 * ~DCOR -- DCO uses internal resistor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_16MHZ != 0xFF)
{
    /* Adjust this accordingly to your VCC rise time */
    __delay_cycles(1000);

    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_16MHZ;      /* Set DCO to 16MHz */
    DCOCTL = CALDCO_16MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
*/

```

```

BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;
}

void GPIO_graceInit(void)
{
    /* Port 1 Output Register */
P1OUT = 0;

    /* Port 1 Direction Register */
P1DIR = 0;

    /* Port 1 Interrupt Edge Select Register */
P1IES = 0;

    /* Port 1 Interrupt Flag Register */
P1IFG = 0;

    /* Port 2 Output Register */
P2OUT = 0;

    /* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

    /* Port 2 Direction Register */
P2DIR = BIT0 | BIT1 | BIT2;

    /* Port 2 Interrupt Edge Select Register */
P2IES = 0;

    /* Port 2 Interrupt Flag Register */
P2IFG = 0;
}

void System_graceInit(void)
{
    WDTCTL = WDTPW | WDTHOLD;
}

void show_value(unsigned char value)
{
    unsigned char ch = 0x00;

    ch = ((value / 100) + 0x30);
    LCD_goto(6, 1);
    LCD_putchar(ch);
}

```

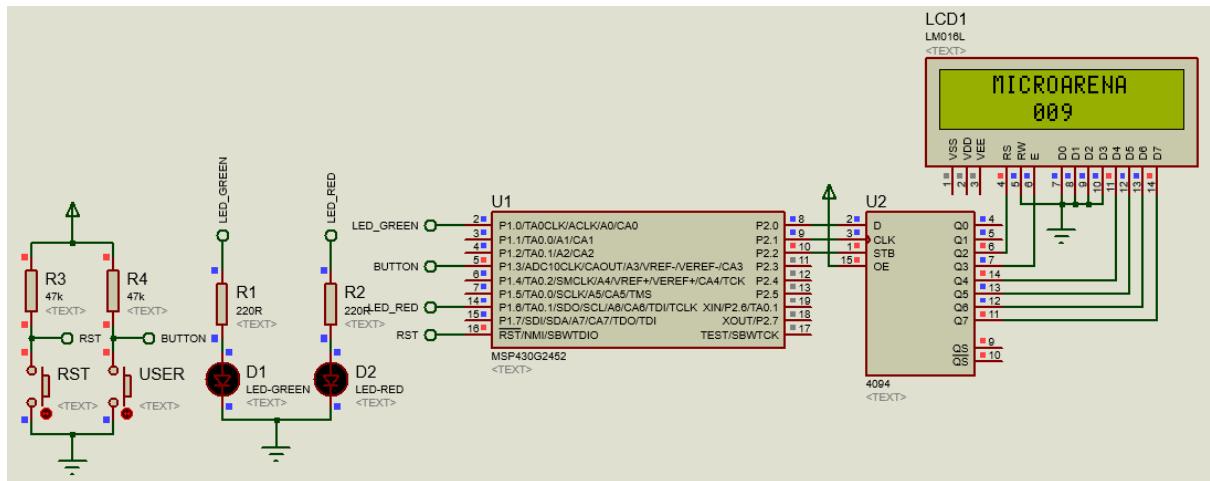
```

ch = (((value / 10) % 10) + 0x30);
LCD_goto(7, 1);
LCD_putchar(ch);

ch = ((value % 10) + 0x30);
LCD_goto(8, 1);
LCD_putchar(ch);
}

```

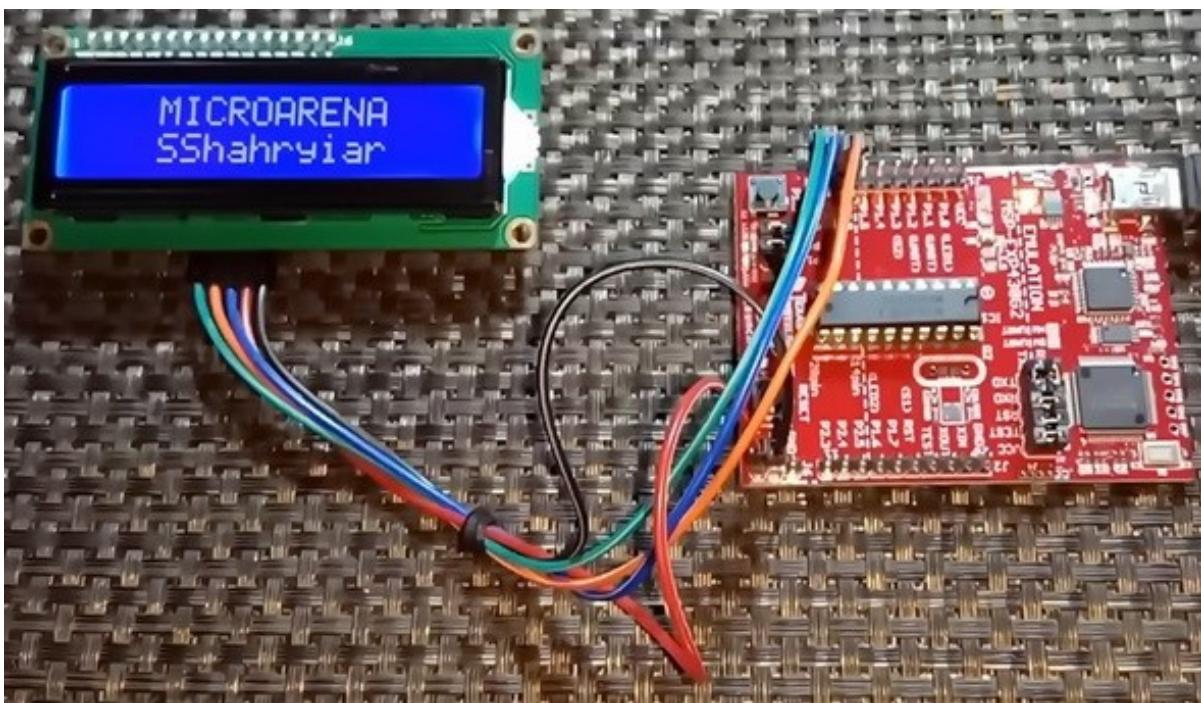
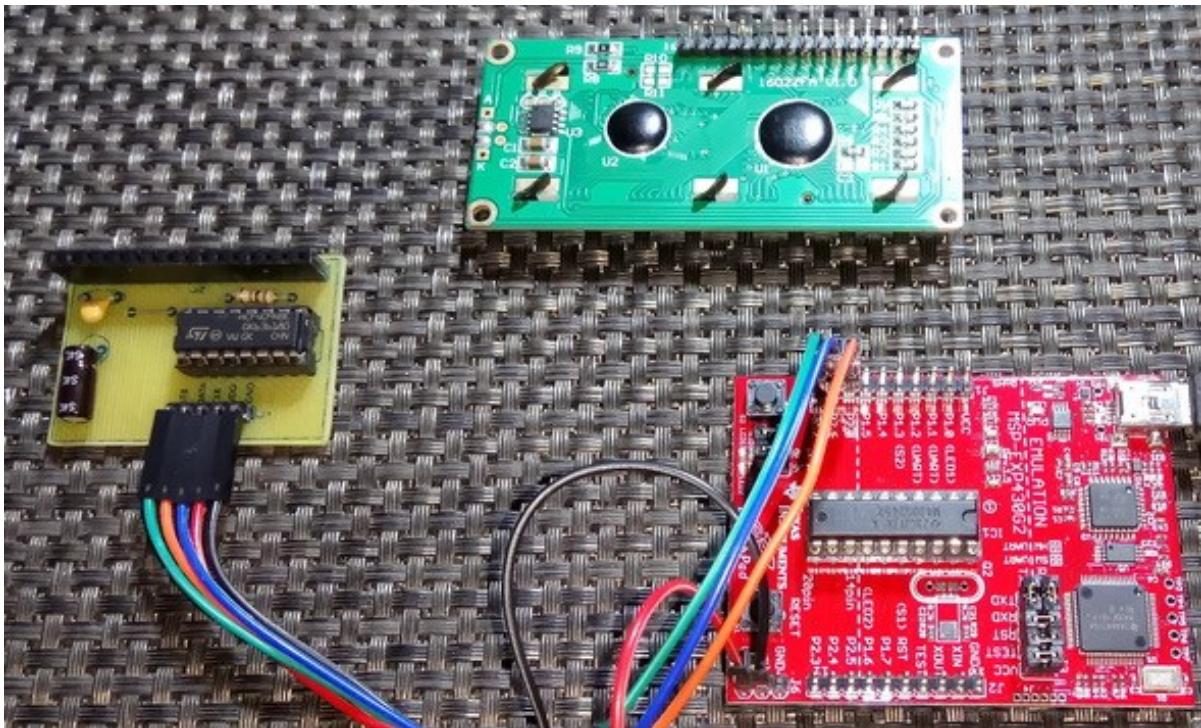
Simulation



Explanation

Basically here, the same LCD library as in the LCD example has been used. The only difference is the **Serial-In-Parallel-Out (SIPO)** part. I used a CD4094B CMOS SIPO shift register between the LCD and the host MSP430 micro to achieve the port-expansion task. Only three pins of the host micro are needed to drive the LCD. In the LCD library, you can see SIPO function on the top. This part translates serial inputs to parallel outputs. Note that at every level the stored value in the SIPO is either **OrEd** or inverse **ANDED** instead of entirely changing the SIPO's current content. In simple terms, it is like read-modification-write. This is to ensure that only the target bits are altered, not the entire content of the SIPO. In this way to some extent, data corruption is prevented.

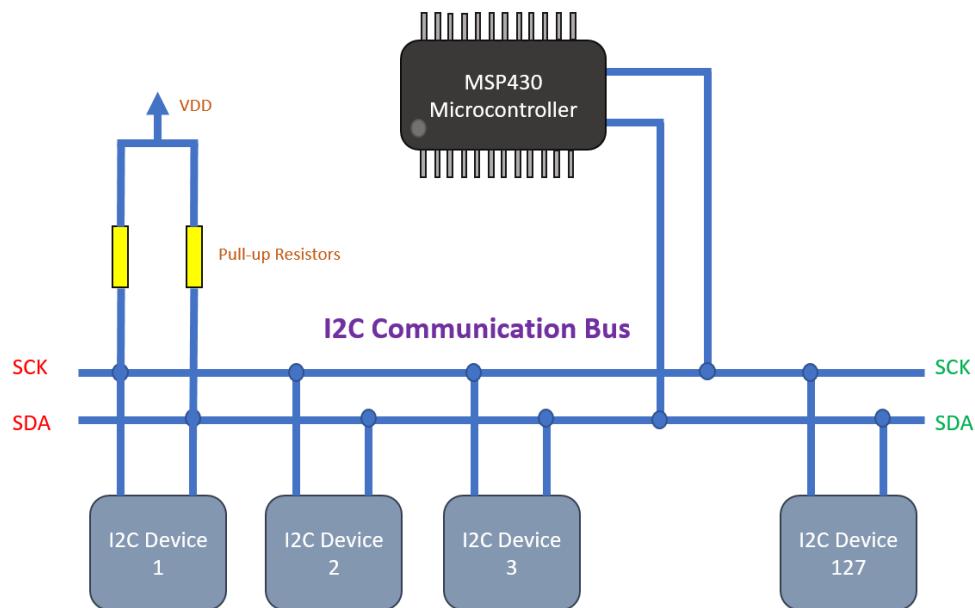
Demo



Demo video: <https://www.youtube.com/watch?v=NBfBqtjZ35s>.

USI I2C – Interfacing PCF8574 I/O Expander

I2C is another popular form of on board synchronous serial communication developed by NXP. It just uses two wires for communication and so it is also referred as **Two Wire Interface (TWI)**. Just like SPI, I2C is widely used in interfacing real-time clocks (RTC), digital sensors, memory chips and so on. It rivals SPI but compared to SPI it is slower and have some limitations. Typical bus speed ranges from a few kilohertz to 400kHz. Up to 127 devices can coexist in an I2C bus. In an I2C bus it is not possible, by conventional means to interface devices with same device IDs or devices with different logic voltage levels without logic level converters and so on. Still however, I2C is very popular because these issues rarely arise and because of its simplicity. Unlike other communications, there's no pin/wire swapping as two wires connect straight to the bus – SDA to SDA and SCL to SCL.



As with SPI, an I2C bus must contain one master and one or more slaves. The master is solely responsible for generating clock signals and initiating communication. Communication starts when master sends out a slave's ID with read/write command and request. The slave reacts to this command by processing the request from the master and sending out data or processing it. I2C bus is always pulled-up using pull-up resistors. Without these pull-up resistors, I2C bus may not function properly.

To know more about I2C interface visit the following links:

- <https://learn.mikroe.com/i2c-everything-need-know/>
- <https://learn.sparkfun.com/tutorials/i2c>
- <http://www.ti.com/lscds/ti/interface/i2c-overview.page>
- <http://www.robot-electronics.co.uk/i2c-tutorial>
- <https://www.i2c-bus.org/i2c-bus/>
- <http://i2c.info/>

Other protocols like SMBus and I2S have similarities with I2C and so learning about I2C advances learning these too.

Code Example

I2C.h

```
#include <msp430.h>

#define FALSE          0
#define TRUE           1

#define wr             FALSE
#define rd             TRUE

#define SET_SDA_AS_OUTPUT()      (USICTL0 |= USIOE)
#define SET_SDA_AS_INPUT()       (USICTL0 &= ~USIOE)

#define FORCING_SDA_HIGH()      \
{                           \
    USISRL = 0xFF;          \
    USICTL0 |= USIGE;        \
    USICTL0 &= ~(USIGE + USIOE); \
}

#define FORCING_SDA_LOW()       \
{                           \
    USISRL = 0x00;          \
    USICTL0 |= (USIGE + USIOE); \
    USICTL0 &= ~USIGE;        \
}

void i2c_usi_mst_gen_start(void);
void i2c_usi_mst_gen_repeated_start(void);
void i2c_usi_mst_gen_stop(void);
void i2c_usi_mst_wait_usi_cnt_flag(void);
unsigned char i2c_usi_mst_send_byte(unsigned char value);
unsigned char i2c_usi_mst_read_byte(void);
void i2c_usi_mst_send_n_ack(unsigned char ack);
unsigned char i2c_usi_mst_send_address(unsigned char addr, unsigned char r_w);
```

I2C.c

```
#include "I2C.h"

static unsigned char usi_cnt_flag = FALSE;

// function to generate I2C START condition
void i2c_usi_mst_gen_start(void)
{
    // make sure SDA line is in HIGH level
    FORCING_SDA_HIGH();

    // small delay
    _delay_cycles(100);
```

```

    // pull down SDA to create START condition
    FORCING_SDA_LOW();
}

// function to generate I2C REPEATED START condition
void i2c_usi_mst_gen_repeated_start(void)
{
    USICCTL0 |= USIOE;
    USISRL = 0xFF;
    USICNT = 1;

    // wait for USIIFG is set
    i2c_usi_mst_wait_usi_cnt_flag();

    // small delay
    _delay_cycles(100);

    // pull down SDA to create START condition
    FORCING_SDA_LOW();

    // small delay
    _delay_cycles(100);
}

// function to generate I2C STOP condition
void i2c_usi_mst_gen_stop(void)
{
    USICCTL0 |= USIOE;
    USISRL = 0x00;
    USICNT = 1;

    // wait for USIIFG is set
    i2c_usi_mst_wait_usi_cnt_flag();

    FORCING_SDA_HIGH();
}

// function to wait for I2C counter flag condition
void i2c_usi_mst_wait_usi_cnt_flag(void)
{
    while(usi_cnt_flag == FALSE)
    {
        //__bis_SR_register(LPM0_bits);
    }

    // reset flag
    usi_cnt_flag = FALSE;
}

// function to send a byte
unsigned char i2c_usi_mst_send_byte(unsigned char data_byte)
{
    // send address and R/W bit
    SET_SDA_AS_OUTPUT();
}

```

```

USISRL = data_byte;
USICNT = (USICNT & 0xE0) + 8;

// wait until USIIFG is set
i2c_usi_mst_wait_usi_cnt_flag();

// check NACK/ACK
SET_SDA_AS_INPUT();
USICNT = (USICNT & 0xE0) + 1;

// wait for USIIFG is set
i2c_usi_mst_wait_usi_cnt_flag();

if(USISRL & 0x01)
{
    // NACK received returns FALSE
    return FALSE;
}

return TRUE;
}

// function to read a byte
unsigned char i2c_usi_mst_read_byte(void)
{
    SET_SDA_AS_INPUT();
   USICNT = (USICNT & 0xE0) + 8;

    // wait for USIIFG is set
    i2c_usi_mst_wait_usi_cnt_flag();

    return USISRL;
}

// function to send (N)ACK bit
void i2c_usi_mst_send_n_ack(unsigned char ack)
{
    // send (N)ack bit
    SET_SDA_AS_OUTPUT();
    if(ack)
    {
        USISRL = 0x00;
    }
    else
    {
        USISRL = 0xFF;
    }
   USICNT = (USICNT & 0xE0) + 1;

    // wait until USIIFG is set
    i2c_usi_mst_wait_usi_cnt_flag();

    // set SDA as input
    SET_SDA_AS_INPUT();
}

```

```

// function to send I2C address with R/W bit
unsigned char i2c_usi_mst_send_address(unsigned char addr, unsigned char r_w)
{
    addr <= 1;
    if(r_w)
    {
        addr |= 0x01;
    }
    return(i2c_usi_mst_send_byte(addr));
}

// USI I2C ISR function
#pragma vector=USI_VECTOR
__interrupt void USI_ISR (void)
{
    if(USICL1 & USISTTIFG)
    {
        // do something if necessary

        // clear flag
        USICL1 &= ~USISTTIFG;
    }

    if(USICL1 & USIIFG)
    {
        // USI counter interrupt flag
        usi_cnt_flag = TRUE;

        // clear flag
        USICL1 &= ~USIIFG;
    }

    //__bic_SR_register_on_exit(LPM0_bits);
}

```

PCF8574.h

```

#include "I2C.h"

#define PCF8574_address          0x20

unsigned char PCF8574_read(void);
void PCF8574_write(unsigned char data_byte);

```

PCF8574.c

```

#include "PCF8574.h"

unsigned char PCF8574_read(void)
{
    unsigned char port_byte = 0x00;

    i2c_usi_mst_gen_start();
    i2c_usi_mst_send_address(PCF8574_address, rd);

```

```

port_byte = i2c_usi_mst_read_byte();
i2c_usi_mst_send_n_ack(0);
i2c_usi_mst_gen_stop();

return port_byte;
}

void PCF8574_write(unsigned char data_byte)
{
    i2c_usi_mst_gen_start();
    i2c_usi_mst_send_address(PCF8574_address, wr);
    i2c_usi_mst_send_byte(data_byte);
    i2c_usi_mst_gen_stop();
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "I2C.h"
#include "PCF8574.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USI_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

void main(void)
{
    unsigned char i = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 USI */
    USI_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    while(1)
    {
        for(i = 1; i < 128; i <= 1)
        {
            PCF8574_write(i);
        }
    }
}

```

```

        delay_ms(200);
    }
    for(i = 128; i > 1; i >>= 1)
    {
        PCF8574_write(i);
        delay_ms(200);
    }
};

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT6 | BIT7;

    /* Port 1 Direction Register */
    P1DIR = 0;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *

```

```

    * SELM_0 -- DCOCLK
    * DIVM_0 -- Divide by 1
    * ~SELS -- DCOCLK
    * DIVS_0 -- Divide by 1
    * ~DCOR -- DCO uses internal resistor
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;          /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void USI_graceInit(void)
{
    /* USER CODE START (section: USI_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: USI_graceInit_prologue) */

    /* Disable USI */
    USICTL0 |= USISWRST;

    /*
     * USI Control Register 0
     *
     * USIPE7 -- USI function enabled

```

```

/* USIPE6 -- USI function enabled
 * ~USIPE5 -- USI function disabled
 * ~USILSB -- MSB first
 * USIMST -- Master mode
 * ~USIGE -- Output latch enable depends on shift clock
 * ~USIOE -- Output disabled
 * USISWRST -- USI logic held in reset state
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
USICTL0 = USIPE7 | USIPE6 | USIMST | USISWRST;

/*
 * USI Control Register 1
 *
 * ~USICKPH -- Data is changed on the first SCLK edge and captured on the
following edge
 * USII2C -- I2C mode enabled
 * ~USISTTIE -- Interrupt on START condition disabled
 * USIIIE -- Interrupt enabled
 * ~USIAL -- No arbitration lost condition
 * ~USISTP -- No STOP condition received
 * ~USISTTIFG -- No START condition received. No interrupt pending
 * USIIFG -- Interrupt pending
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
USICTL1 = USII2C | USIIIE | USIIFG;

/*
 * USI Clock Control Register
 *
 * USIDIV_4 -- Divide by 16
 * USISSEL_2 -- SMCLK
 * USICKPL -- Inactive state is high
 * ~USISWCLK -- Input clock is low
 *
 * Note: ~USISWCLK indicates that USISWCLK has value zero
 */
USICKCTL = USIDIV_4 | USISSEL_2 | USICKPL;

/*
 * USI Bit Counter Register
 *
 * ~USISCLREL -- SCL line is held low if USIIFG is set
 * ~USI16B -- 8-bit shift register mode. Low byte register USISRL is used
 * USIIFGCC -- USIIFG is not cleared automatically
 * ~USICNT4 -- USI bit count
 * ~USICNT3 -- USI bit count
 * ~USICNT2 -- USI bit count
 * ~USICNT1 -- USI bit count
 * ~USICNT0 -- USI bit count
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
USICNT = USIIFGCC;

/* Enable USI */
USICTL0 &= ~USISWRST;

```

```

/* Clear pending flag */
USICTL1 &= ~(USIIFG + USISTTIFG);

/* USER CODE START (section: USI_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: USI_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        _delay_cycles(50);
    } while (IFG1 & OFIFG);

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
    */
}

```

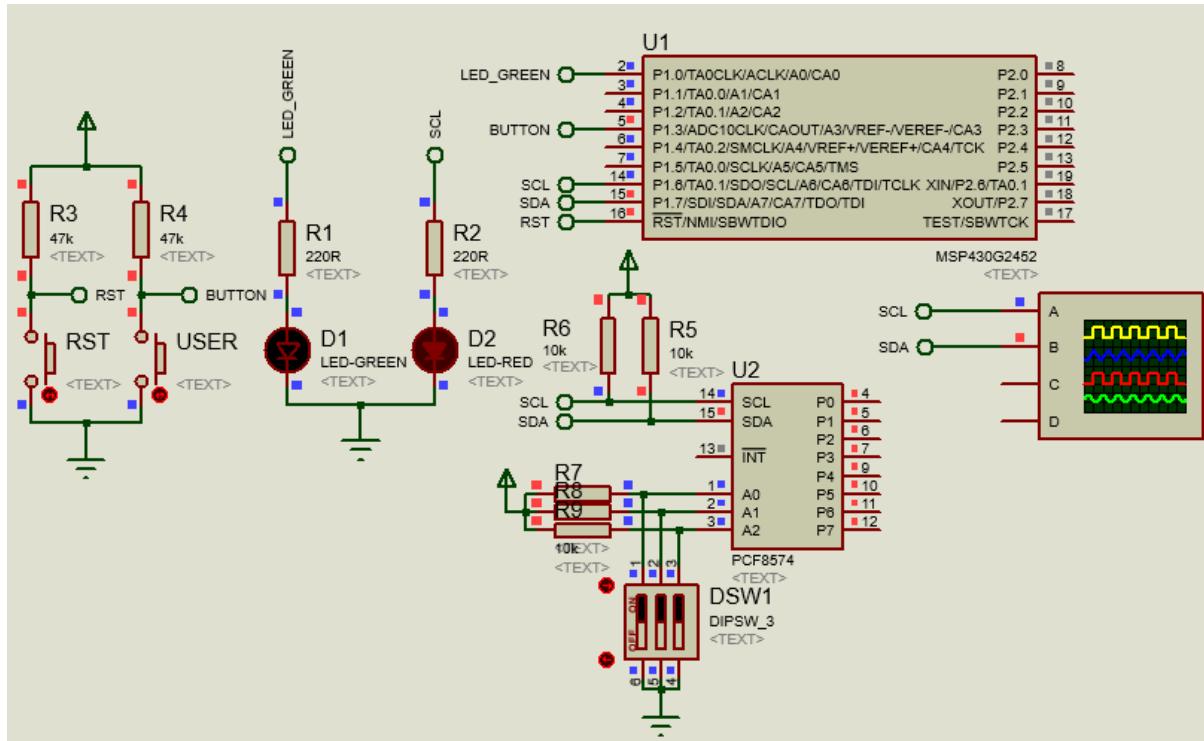
```

/*
 * ~WDTCNTCL -- No action
 * ~WDTSEL -- SMCLK
 * ~WDTIS0 -- Watchdog clock source bit0 disabled
 * ~WDTIS1 -- Watchdog clock source bit1 disabled
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

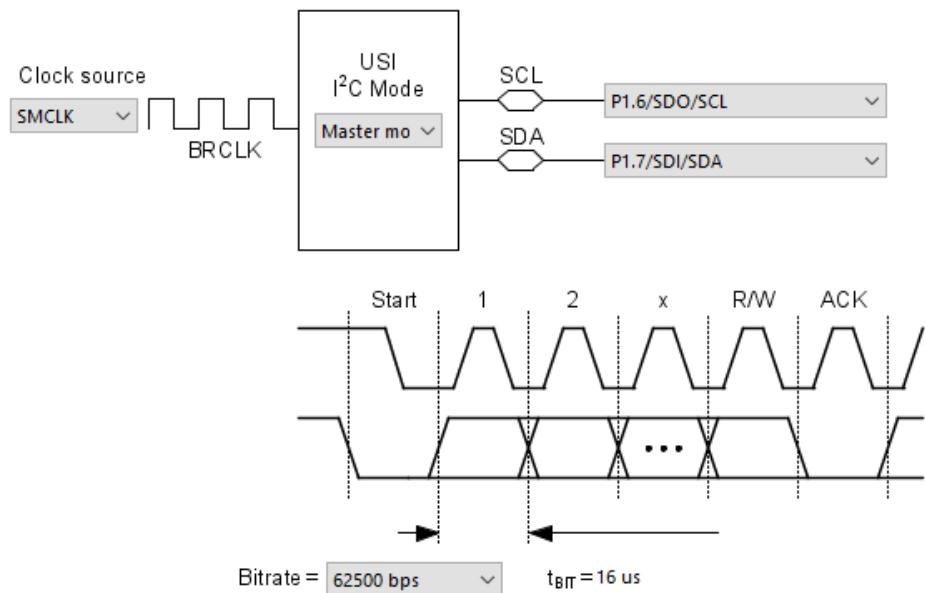
```

Simulation



Explanation

To keep things simple, I demoed USI-based I2C using PCF8574 8-bit I2C GPIO expander. Here the GPIOs of PCF8574 are used to create a running LED light pattern similar to *Kitt Scan* from the popular series *Knight Rider*. The code for USI-based I2C implementation is obtained from TI's wiki page, http://processors.wiki.ti.com/index.php/I2C_Communication_with_USI_Module. I did some minor modifications on it. The code is self-explanatory with detailed documentation on the wiki page and so I won't be discussing it. The rest of the code is the implementation of PCF8574 driver and actual demo code.



Interrupt Enables

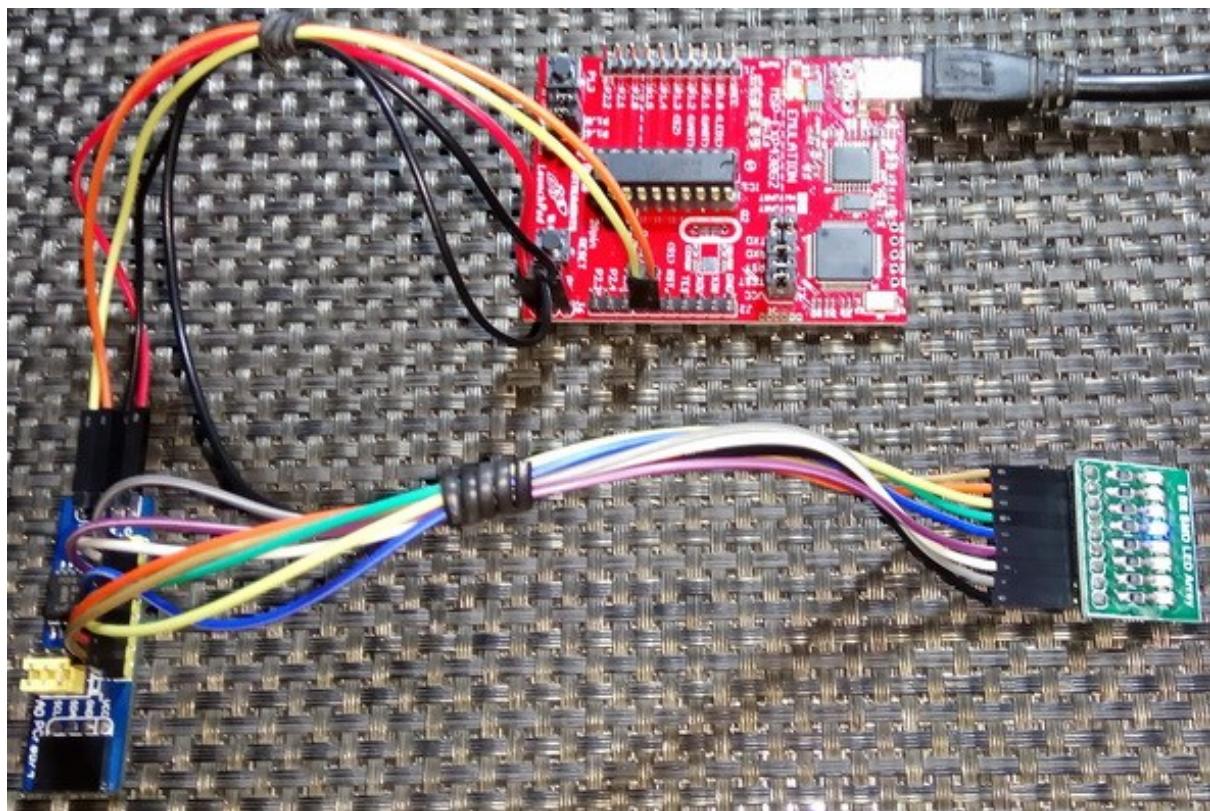
Counter Interrupt enable

[Remove Interrupt Handler Code](#)

START Condition interrupt enable

[View All Interrupt Handlers](#)

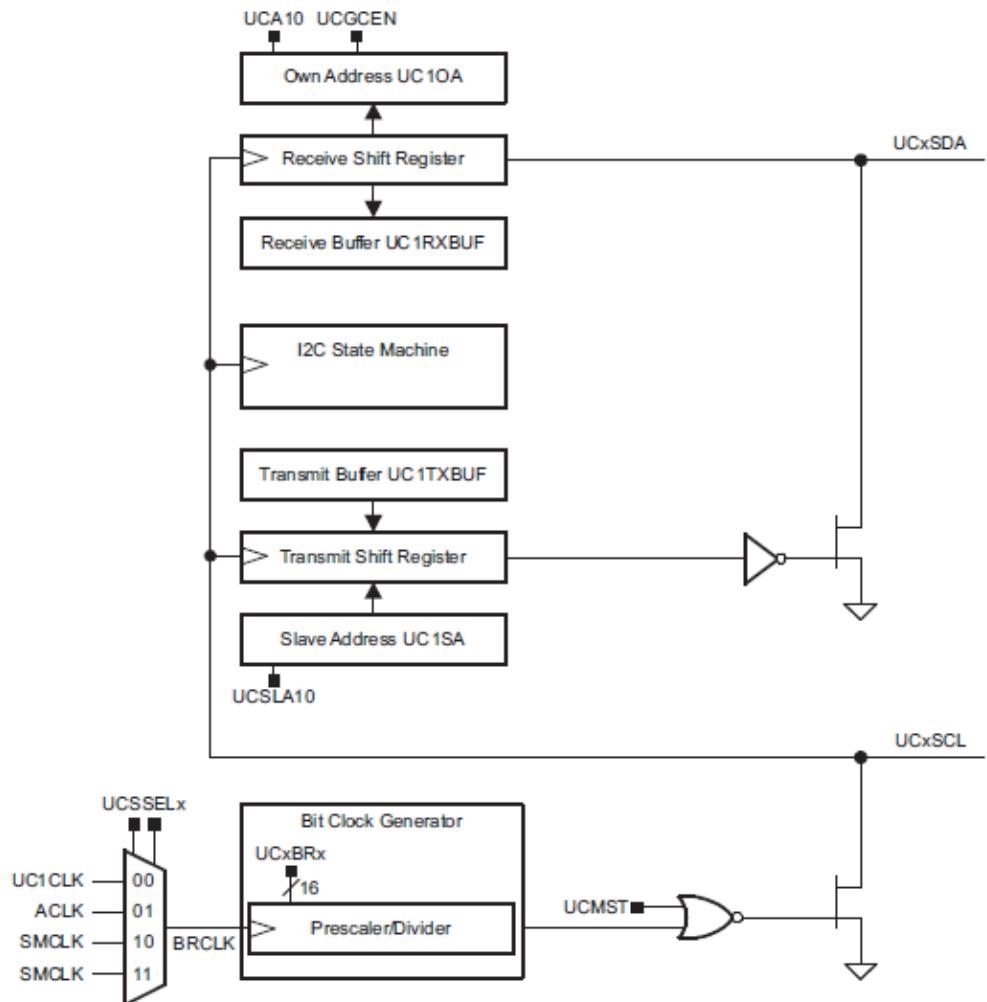
Demo



Demo video: <https://www.youtube.com/watch?v=9svi-0cd2gk>.

USCI I2C – Interfacing BH1750 Ambient Light Sensor

Using USCI in I2C mode is a bit difficult compared to using USCI in SPI mode. This is because of the many iterations and function calls in I2C mode. Again, here I tried to keep things simple and kept things in a fashion we would normally expect. USCI-based I2C can be realized with a state-of-machine too but that way is not easy for beginners.



Code Example

HW_I2C.h

```
#include <msp430.h>

void I2C_USCI_init(unsigned char address);
void I2C_USCI_set_address(unsigned char address);
unsigned char I2C_USCI_read_byte(unsigned char address);
unsigned char I2C_USCI_read_word(unsigned char address,unsigned char *value,
unsigned char length);
unsigned char I2C_USCI_write_byte(unsigned char address, unsigned char value);
```

HW_I2C.c

```
#include "HW_I2C.h"

void I2C_USCI_init(unsigned char address)
{
    P1DIR &= ~(BIT6 + BIT7);
    P1OUT |= (BIT6 + BIT7);
    P1SEL2 |= (BIT6 | BIT7);
    P1SEL |= (BIT6 | BIT7);

    UCB0CTL1 |= UCSWRST;
    UCB0CTL0 = (UCMST | UCMODE_3 | UCSYNC);
    UCB0CTL1 = (UCSSEL_2 | UCSWRST);
    UCB0BR0 = 20;
    UCB0I2CSA = address;
    UCB0CTL1 &= ~UCSWRST;
}

void I2C_USCI_set_address(unsigned char address)
{
    UCB0CTL1 |= UCSWRST;
    UCB0I2CSA = address;
    UCB0CTL1 &= ~UCSWRST;
}

unsigned char I2C_USCI_read_byte(unsigned char address)
{
    while(UCB0CTL1 & UCTXSTP);
    UCB0CTL1 |= (UCTR | UCTXSTT);

    while(!(IFG2 & UCB0TXIFG));
    UCB0TXBUF = address;

    while(!(IFG2 & UCB0TXIFG));
    UCB0CTL1 &= ~UCTR;
    UCB0CTL1 |= UCTXSTT;
    IFG2 &= ~UCB0TXIFG;

    while(UCB0CTL1 & UCTXSTT);
    UCB0CTL1 |= UCTXSTP;

    return UCB0RXBUF;
}

unsigned char I2C_USCI_read_word(unsigned char address,unsigned char *value,
                                unsigned char length)
{
    unsigned char i = 0;

    while (UCB0CTL1 & UCTXSTP);
    UCB0CTL1 |= (UCTR | UCTXSTT);

    while (!(IFG2 & UCB0TXIFG));
```

```

IFG2 &= ~UCB0TXIFG;

if(UCB0STAT & UCNACKIFG)
{
    return UCB0STAT;
}

UCB0TXBUF = address;

while (!(IFG2 & UCB0TXIFG));

if(UCB0STAT & UCNACKIFG)
{
    return UCB0STAT;
}

UCB0CTL1 &= ~UCTR;
UCB0CTL1 |= UCTXSTT;
IFG2 &= ~UCB0TXIFG;

while (UCB0CTL1 & UCTXSTT);

for(i = 0; i < (length - 1); i)
{
    while (!(IFG2&UCB0RXIFG));
    IFG2 &= ~UCB0TXIFG;
    value[i] = UCB0RXBUF;
}

while (!(IFG2 & UCB0RXIFG));

IFG2 &= ~UCB0TXIFG;
UCB0CTL1 |= UCTXSTP;
value[length - 1] = UCB0RXBUF;
IFG2 &= ~UCB0TXIFG;

return 0;
}

unsigned char I2C_USCI_write_byte(unsigned char address, unsigned char value)
{
    while(UCB0CTL1 & UCTXSTP);

    UCB0CTL1 |= (UCTR | UCTXSTT);

    while(!(IFG2 & UCB0TXIFG));

    if(UCB0STAT & UCNACKIFG)
    {
        return UCB0STAT;
    }

    UCB0TXBUF = address;

    while(!(IFG2 & UCB0TXIFG));

    if(UCB0STAT & UCNACKIFG)

```

```

{
    return UCB0STAT;
}

UCB0TXBUF = value;

while(!(IFG2 & UCB0TXIFG));

if(UCB0STAT & UCNACKIFG)
{
    return UCB0STAT;
}

UCB0CTL1 |= UCTXSTP;
IFG2 &= ~UCB0TXIFG;

return 0;
}

```

BH1750.h

```

#include <msp430.h>
#include "delay.h"
#include "HW_I2C.h"

#define BH1750_addr          0x23

#define power_down           0x00
#define power_up             0x01
#define reset                0x07
#define cont_H_res_mode1    0x10
#define cont_H_res_mode2    0x11
#define cont_L_res_mode     0x13
#define one_time_H_res_mode1 0x20
#define one_time_H_res_mode2 0x21
#define one_time_L_res_mode 0x23

void BH1750_init(void);
void BH1750_write(unsigned char cmd);
unsigned int BH1750_read_word(void);
unsigned int get_lux_value(unsigned char mode, unsigned int delay_time);

```

BH1750.c

```

#include "BH1750.h"

void BH1750_init(void)
{
    I2C_USCI_init(BH1750_addr);
    delay_ms(10);
    BH1750_write(power_down);
}

void BH1750_write(unsigned char cmd)

```

```

{
    I2C_USCI_write_byte(BH1750_addr, cmd);
}

unsigned int BH1750_read_word(void)
{
    unsigned long value = 0x0000;
    unsigned char bytes[2] = {0x00, 0x00};

    I2C_USCI_read_word(0x11, bytes, 2);

    value = ((bytes[1] << 8) | bytes[0]);

    return value;
}

unsigned int get_lux_value(unsigned char mode, unsigned int delay_time)
{
    unsigned long lux_value = 0x00;
    unsigned char dly = 0x00;
    unsigned char s = 0x08;

    while(s)
    {
        BH1750_write(power_up);
        BH1750_write(mode);
        lux_value += BH1750_read_word();
        for(dly = 0; dly < delay_time; dly += 1)
        {
            delay_ms(1);
        }
        BH1750_write(power_down);
        s--;
    }
    lux_value >>= 3;

    return ((unsigned int)lux_value);
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "HW_I2C.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"
#include "BH1750.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USCI_B0_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value);

```

```

void main(void)
{
    unsigned int LX = 0x0000;
    unsigned int tmp = 0x0000;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 USCI_B0 */
    USCI_B0_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    BH1750_init();

    LCD_init();
    LCD_clear_home();

    LCD_goto(0, 0);
    LCD_putstr("MSP430G USCI I2C");
    LCD_goto(0, 1);
    LCD_putstr("Lux:");

    while(1)
    {
        tmp = get_lux_value(cont_H_res_mode1, 20);

        if(tmp > 10)
        {
            LX = tmp;
        }
        else
        {
            LX = get_lux_value(cont_H_res_mode1, 140);
        }

        lcd_print(11, 1, LX);

        delay_ms(200);
    }
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
}

```

```

/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Port Select 2 Register */
P1SEL2 = BIT6 | BIT7;

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Port Select Register */
P1SEL = BIT6 | BIT7;

/* Port 1 Direction Register */
P1DIR = 0;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor

```

```

/*
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF)
{
    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;          /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void USCI_B0_graceInit(void)
{
    /* USER CODE START (section: USCI_B0_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: USCI_B0_graceInit_prologue) */

    /* Disable USCI */
    UCB0CTL1 |= UCSWRST;

    /*
     * Control Register 0
     *
     * ~UCA10 -- Own address is a 7-bit address
     * ~UCSLA10 -- Address slave with 7-bit address
     * ~UCMM -- Single master environment. There is no other master in the system.
     The address compare unit is disabled
     * UCMST -- Master mode

```

```

    * UCMODE_3 -- I2C Mode
    * UCSYNC -- Synchronous Mode
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
UCB0CTL0 = UCMST | UCMODE_3 | UCSYNC;

/*
 * Control Register 1
 *
 * UCSSEL_2 -- SMCLK
 * ~UCTR -- Receiver
 * ~UCTXNACK -- Acknowledge normally
 * ~UCTXSTP -- No STOP generated
 * ~UCTXSTT -- Do not generate START condition
 * UCSWRST -- Enabled. USCI logic held in reset state
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
UCB0CTL1 = UCSSEL_2 | UCSWRST;

/* I2C Slave Address Register */
UCB0I2CSA = BH1750_addr;

/* Bit Rate Control Register 0 */
UCB0BR0 = 20;

/* Enable USCI */
UCB0CTL1 |= UCSWRST;

/* USER CODE START (section: USCI_B0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: USCI_B0_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

```

```

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned int value)
{
    char tmp[6] = {0x20, 0x20, 0x20, 0x20, 0x20, '\0'};

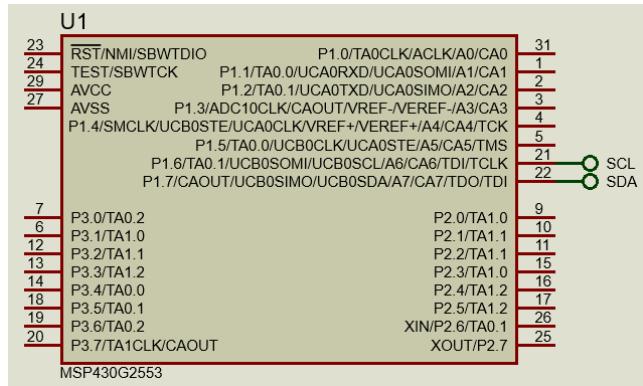
    tmp[0] = ((value / 10000) + 0x30);
    tmp[1] = (((value / 1000) % 10) + 0x30);
    tmp[2] = (((value / 100) % 10) + 0x30);
    tmp[3] = (((value / 10) % 10) + 0x30);
    tmp[4] = ((value % 10) + 0x30);

    LCD_goto(x_pos, y_pos);
    LCD_putstr(tmp);
}

```

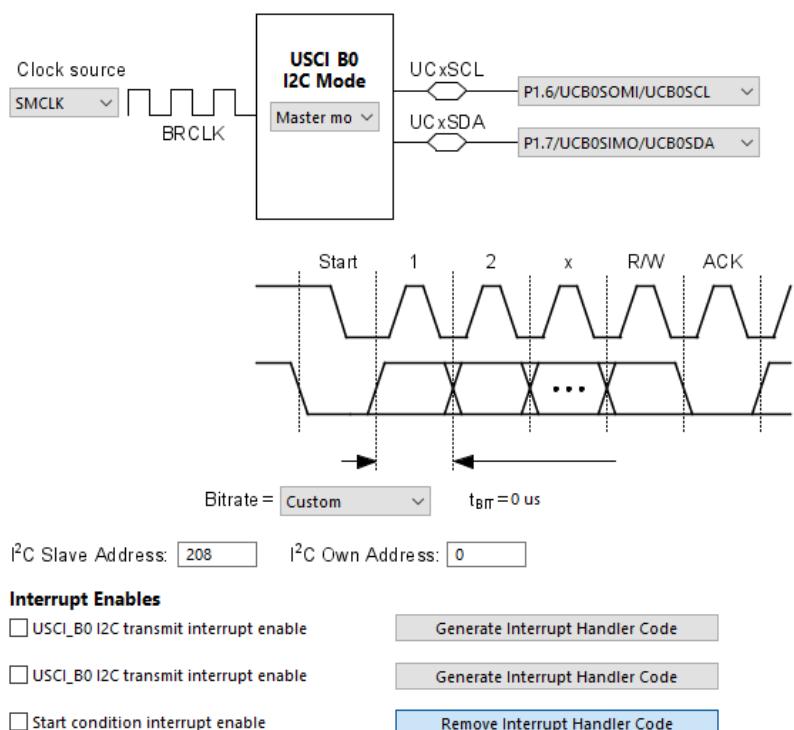
Simulation

The model for BH1750FVI is not available in Proteus VSM and so it cannot be simulated. Only the pinouts are shown in the schematic below.



Explanation

Just like USCI SPI setup, Grace is used for setting the basic parameters for USCI I2C communication. Note only USCI_B0 supports I2C communication unlike USCI SPI communication. Since our MSP430 micro is the master device in the I2C bus, USCI module is configured as I2C master. One particular thing to observe is the **I2C Slave Address**. Here as shown in the screenshot below, it is 208. This is not an important figure. Same goes for the **I2C Own Address** part. No interrupts are to be used and so none of them are enabled.



Out of the configuration set by Grace, I2C pins are set also in the I2C initialization function. This should be done manually before initializing the USCI hardware.

```

void I2C_USCI_init(unsigned char address)
{
    P1DIR &= ~(BIT6 + BIT7);
    P1OUT |= (BIT6 + BIT7);
    P1SEL2 |= (BIT6 | BIT7);
    P1SEL |= (BIT6 | BIT7);

    UCB0CTL1 |= UCSWRST;
    UCB0CTL0 = (UCMST | UCMODE_3 | UCSYNC);
    UCB0CTL1 = (UCSSEL_2 | UCSWRST);
    UCB0BR0 = 20;
    UCB0I2CSA = address;
    UCB0CTL1 &= ~UCSWRST;
}

```

Off all the functions used in the HW_I2C files, the following are of high importance:

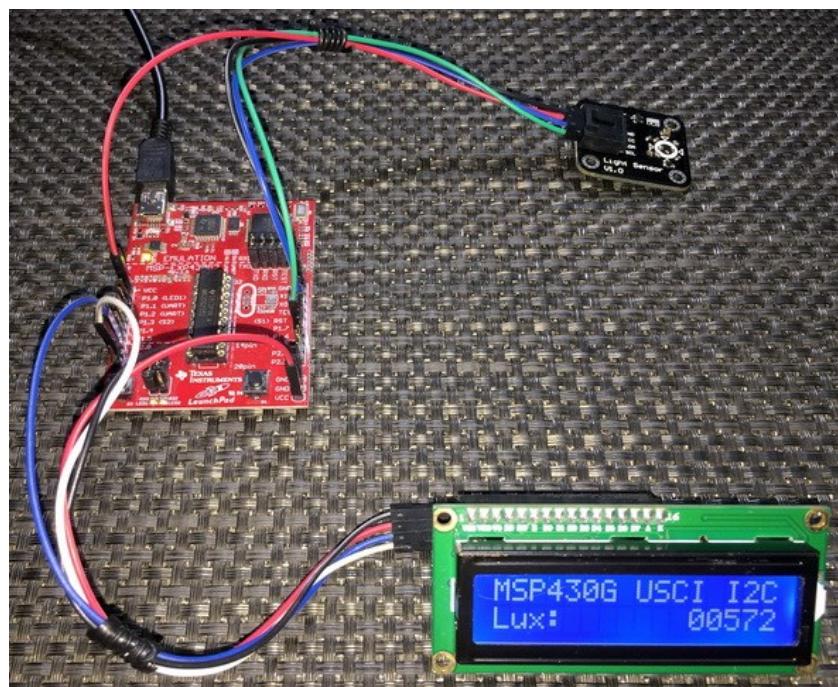
```

unsigned char I2C_USCI_read_byte(unsigned char address);
unsigned char I2C_USCI_read_word(unsigned char address,unsigned char *value,
unsigned char length);
unsigned char I2C_USCI_write_byte(unsigned char address, unsigned char value);

```

Their names suggest their functionality. The codes inside them are arranged as such that they take care of start-stop conditions generation, clock generation, etc. I2C communication needs device address along side read-write info. Based on read-write info, the host device writes or read I2C bus. The drawback of using I2C with these functions is the vulnerability to falling inside a loop since loops are used in these functions widely. This setback can be overcome with timeouts.

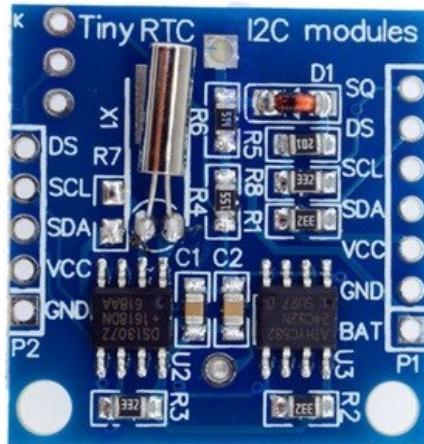
Demo



Demo video: <https://youtu.be/RkTjCcCLEdg>.

USCI I2C – Interfacing DS1307 Real Time Clock (RTC)

This part shows another example of I2C implementation using MSP430's USCI hardware. This time the I2C device that is connected with a MSP430 is the popular DS1307 real time clock (RTC). This is the last USCI hardware example.



Code Example

HW_I2C.h

```
#include <msp430.h>

void I2C_USCI_init(unsigned char address);
void I2C_USCI_set_address(unsigned char address);
unsigned char I2C_USCI_read_byte(unsigned char address);
unsigned char I2C_USCI_read_word(unsigned char address,unsigned char *value,
unsigned char length);
unsigned char I2C_USCI_write_byte(unsigned char address, unsigned char value);
```

HW_I2C.c

```
#include "HW_I2C.h"

void I2C_USCI_init(unsigned char address)
{
    P1DIR &= ~(BIT6 + BIT7);
    P1OUT |= (BIT6 + BIT7);
    P1SEL2 |= (BIT6 | BIT7);
    P1SEL |= (BIT6 | BIT7);

    UCB0CTL1 |= UCSWRST;
    UCB0CTL0 = (UCMST | UCMODE_3 | UCSYNC);
    UCB0CTL1 = (UCSSEL_2 | UCSWRST);
    UCB0BR0 = 20;
    UCB0I2CSA = address;
    UCB0CTL1 &= ~UCSWRST;
```

```

}

void I2C_USCI_set_address(unsigned char address)
{
    UCB0CTL1 |= UCSWRST;
    UCB0I2CSA = address;
    UCB0CTL1 &= ~UCSWRST;
}

unsigned char I2C_USCI_read_byte(unsigned char address)
{
    while(UCB0CTL1 & UCTXSTP);
    UCB0CTL1 |= (UCTR | UCTXSTT);

    while(!(IFG2 & UCB0TXIFG));
    UCB0TXBUF = address;

    while(!(IFG2 & UCB0TXIFG));
    UCB0CTL1 &= ~UCTR;
    UCB0CTL1 |= UCTXSTT;
    IFG2 &= ~UCB0TXIFG;

    while(UCB0CTL1 & UCTXSTT);
    UCB0CTL1 |= UCTXSTP;

    return UCB0RXBUF;
}

unsigned char I2C_USCI_read_word(unsigned char address,unsigned char *value,
unsigned char length)
{
    unsigned char i = 0;

    while (UCB0CTL1 & UCTXSTP);

    UCB0CTL1 |= (UCTR | UCTXSTT);

    while (!(IFG2 & UCB0TXIFG));

    IFG2 &= ~UCB0TXIFG;

    if(UCB0STAT & UCNACKIFG)
    {
        return UCB0STAT;
    }

    UCB0TXBUF = address;

    while (!(IFG2 & UCB0TXIFG));

    if(UCB0STAT & UCNACKIFG)
    {
        return UCB0STAT;
    }

    UCB0CTL1 &= ~UCTR;
}

```

```

UCB0CTL1 |= UCTXSTT;
IFG2 &= ~UCB0TXIFG;

while (UCB0CTL1 & UCTXSTT);

for(i = 0; i < (length - 1); i++)
{
    while (!(IFG2&UCB0RXIFG));
    IFG2 &= ~UCB0TXIFG;
    value[i] = UCB0RXBUF;
}

while (!(IFG2 & UCB0RXIFG));

IFG2 &= ~UCB0TXIFG;
UCB0CTL1 |= UCTXSTP;
value[length - 1] = UCB0RXBUF;
IFG2 &= ~UCB0TXIFG;

return 0;
}

unsigned char I2C_USCI_write_byte(unsigned char address, unsigned char value)
{
    while(UCB0CTL1 & UCTXSTP);

    UCB0CTL1 |= (UCTR | UCTXSTT);

    while(!(IFG2 & UCB0TXIFG));

    if(UCB0STAT & UCNACKIFG)
    {
        return UCB0STAT;
    }

    UCB0TXBUF = address;

    while(!(IFG2 & UCB0TXIFG));

    if(UCB0STAT & UCNACKIFG)
    {
        return UCB0STAT;
    }

    UCB0TXBUF = value;

    while(!(IFG2 & UCB0TXIFG));

    if(UCB0STAT & UCNACKIFG)
    {
        return UCB0STAT;
    }

    UCB0CTL1 |= UCTXSTP;
    IFG2 &= ~UCB0TXIFG;

    return 0;
}

```

DS1307.h

```
#include "HW_I2C.h"

#define DS1307_address          0x68

#define sec_reg                  0x00
#define min_reg                 0x01
#define hr_reg                   0x02
#define day_reg                  0x03
#define date_reg                 0x04
#define month_reg                0x05
#define year_reg                 0x06
#define control_reg               0x07

void DS1307_init(void);
unsigned char DS1307_read(unsigned char address);
void DS1307_write(unsigned char address, unsigned char value);
unsigned char bcd_to_decimal(unsigned char value);
unsigned char decimal_to_bcd(unsigned char value);
void get_time(void);
void get_date(void);
void set_time(void);
void set_date(void);
```

DS1307.c

```
#include "DS1307.h"

extern struct
{
    unsigned char sec;
    unsigned char min;
    unsigned char hr;
    unsigned char day;
    unsigned char dt;
    unsigned char mt;
    unsigned char yr;
}rtc;

void DS1307_init(void)
{
    I2C_USCI_init(DS1307_address);
    DS1307_write(sec_reg, 0x00);
    DS1307_write(control_reg, 0x90);
}

unsigned char DS1307_read(unsigned char address)
{
    return I2C_USCI_read_byte(address);
}
```

```

void DS1307_write(unsigned char address, unsigned char value)
{
    I2C_USCI_write_byte(address, value);
}

unsigned char bcd_to_decimal(unsigned char value)
{
    return ((value & 0x0F) + (((value & 0xF0) >> 0x04) * 0x0A));
}

unsigned char decimal_to_bcd(unsigned char value)
{
    return (((value / 0x0A) << 0x04) & 0xF0) | ((value % 0x0A) & 0x0F);
}

void get_time(void)
{
    rtc.sec = DS1307_read(sec_reg);
    rtc.sec = bcd_to_decimal(rtc.sec);

    rtc.min = DS1307_read(min_reg);
    rtc.min = bcd_to_decimal(rtc.min);

    rtc.hr = DS1307_read(hr_reg);
    rtc.hr = bcd_to_decimal(rtc.hr);
}

void get_date(void)
{
    rtc.day = DS1307_read(day_reg);
    rtc.day = bcd_to_decimal(rtc.day);

    rtc.dt = DS1307_read(date_reg);
    rtc.dt = bcd_to_decimal(rtc.dt);

    rtc.mt = DS1307_read(month_reg);
    rtc.mt = bcd_to_decimal(rtc.mt);

    rtc.yr = DS1307_read(year_reg);
    rtc.yr = bcd_to_decimal(rtc.yr);
}

void set_time(void)
{
    rtc.sec = decimal_to_bcd(rtc.sec);
    DS1307_write(sec_reg, rtc.sec);

    rtc.min = decimal_to_bcd(rtc.min);
    DS1307_write(min_reg, rtc.min);

    rtc.hr = decimal_to_bcd(rtc.hr);
    DS1307_write(hr_reg, rtc.hr);
}

```

```

void set_date(void)
{
    rtc.day = decimal_to_bcd(rtc.day);
    DS1307_write(day_reg, rtc.day);

    rtc.dt = decimal_to_bcd(rtc.dt);
    DS1307_write(date_reg, rtc.dt);

    rtc.mt = decimal_to_bcd(rtc.mt);
    DS1307_write(month_reg, rtc.mt);

    rtc.yr = decimal_to_bcd(rtc.yr);
    DS1307_write(year_reg, rtc.yr);
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "HW_I2C.h"
#include "DS1307.h"
#include "lcd.h"

struct
{
    unsigned char sec;
    unsigned char min;
    unsigned char hr;
    unsigned char day;
    unsigned char dt;
    unsigned char mt;
    unsigned char yr;
}rtc;

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USCI_B0_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void show_value(unsigned char x_pos, unsigned char y_pos, unsigned char value);
void display_time(void);

void main(void)
{
    rtc.sec = 30;
    rtc.min = 58;
    rtc.hr = 23;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();
}

```

```

/* initialize Config for the MSP430 2xx family clock systems (BCS) */
BCSplus_graceInit();

/* initialize Config for the MSP430 USCI_B0 */
USCI_B0_graceInit();

/* initialize Config for the MSP430 System Registers */
System_graceInit();

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

LCD_init();
LCD_clear_home();

LCD_goto(0, 0);

LCD_putstr("MSP430G USCI I2C");

DS1307_init();
set_time();

while(1)
{
    get_time();
    display_time();
}
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Port Select 2 Register */
    P1SEL2 = BIT6 | BIT7;

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT6 | BIT7;

    /* Port 1 Direction Register */
    P1DIR = 0;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = 0;
}

```

```

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* Port 3 Output Register */
P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF)
    {
        /* Follow recommended flow. First, clear all DC0x and MODx bits. Then
         * apply new RSELx values. Finally, apply new DC0x and MODx bit values.
         */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;          /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;
}

```

```

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void USCI_B0_graceInit(void)
{
    /* USER CODE START (section: USCI_B0_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: USCI_B0_graceInit_prologue) */

    /* Disable USCI */
    UCB0CTL1 |= UCSWRST;

    /*
     * Control Register 0
     *
     * ~UCA10 -- Own address is a 7-bit address
     * ~UCSLA10 -- Address slave with 7-bit address
     * ~UCMM -- Single master environment. There is no other master in the system.
The address compare unit is disabled
     * UCMST -- Master mode
     * UCMODE_3 -- I2C Mode
     * UCSYNC -- Synchronous Mode
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    UCB0CTL0 = UCMST | UCMODE_3 | UCSYNC;

    /*
     * Control Register 1
     *
     * UCSSEL_2 -- SMCLK
     * ~UCTR -- Receiver
     * ~UCTXNACK -- Acknowledge normally
     * ~UCTXSTP -- No STOP generated
     * ~UCTXSTT -- Do not generate START condition
     * UCSWRST -- Enabled. USCI logic held in reset state
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    UCB0CTL1 = UCSSEL_2 | UCSWRST;

    /* I2C Slave Address Register */
    UCB0I2CSA = DS1307_address;

    /* Bit Rate Control Register 0 */
}

```

```

UCB0BR0 = 20;

/* Enable USCI */
UCB0CTL1 &= ~UCSWRST;

/* USER CODE START (section: USCI_B0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: USCI_B0_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;
}

```

```

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void show_value(unsigned char x_pos, unsigned char y_pos, unsigned char value)
{
    char chr = 0;

    chr = ((value / 10) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(chr);

    chr = ((value % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(chr);
}

void display_time(void)
{
    LCD_goto(6, 1);
    LCD_putchar(' ');
    LCD_goto(9, 1);
    LCD_putchar('.');
    delay_ms(450);

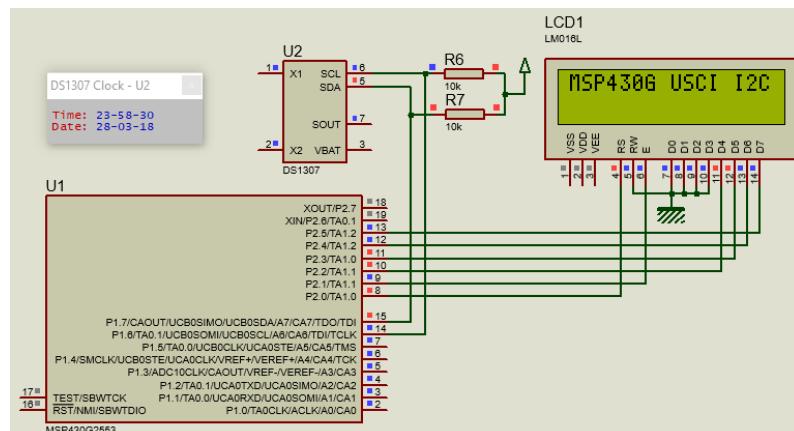
    show_value(7, 1, rtc.hr);
    show_value(10, 1, rtc.min);
    show_value(4, 1, rtc.sec);

    LCD_goto(6, 1);
    LCD_putchar(':');
    LCD_goto(9, 1);
    LCD_putchar(':');
    delay_ms(450);
}

```

Simulation

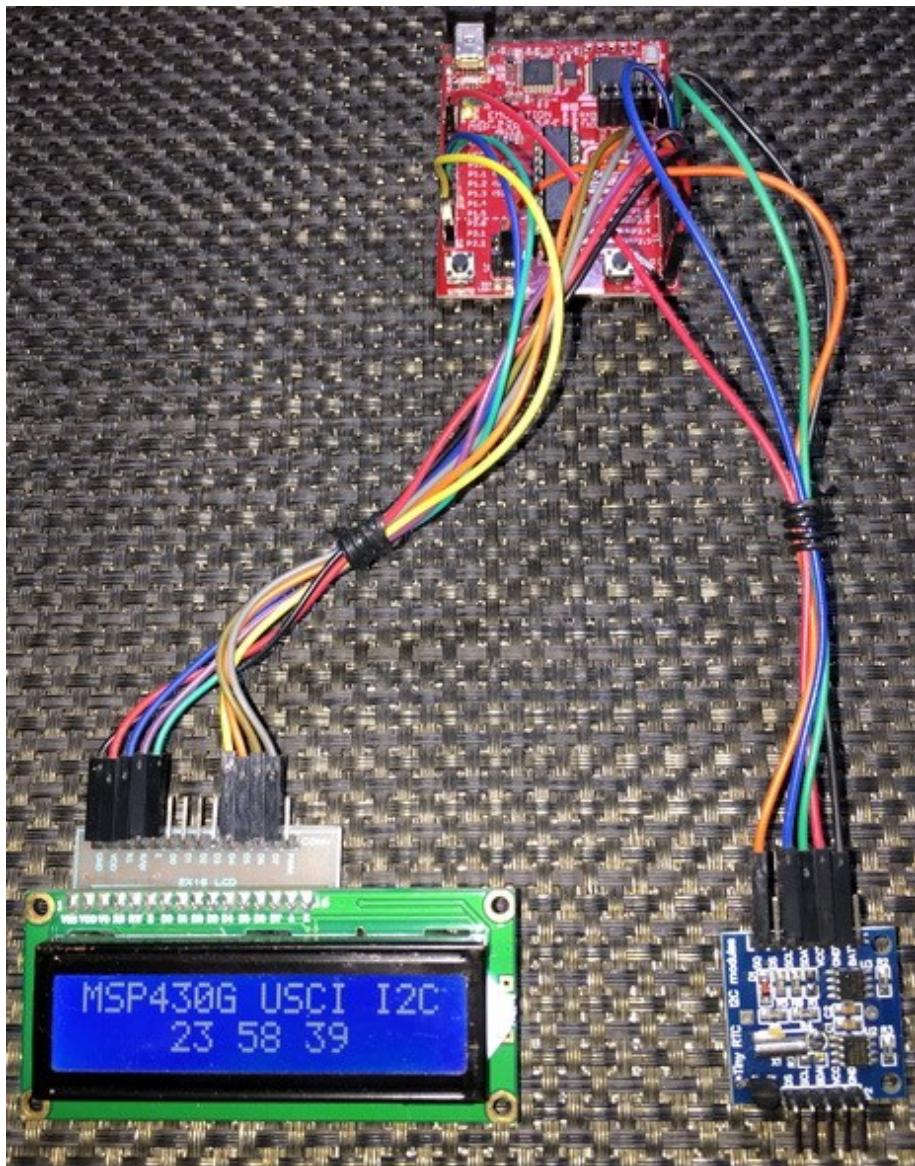
DS1307 simulation encountered some weird issues but it does work.



Explanation

Since it uses the same ideas as in the previous example, there is hardly a thing to explain here.

Demo



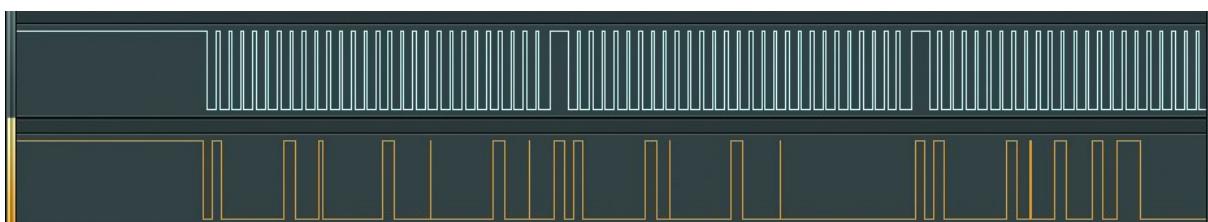
Demo video: <https://youtu.be/bhwn6l5ztk5>.

Software I2C – Interfacing PCF8591 ADC-DAC

Software I2C implementation is a bit complex compared to software SPI. This is because there are start-stop conditions and acknowledgments that are also needed to be taken care off along with data transactions. However, it becomes the only option when USI/USCI are absent. Unlike SPI, I2C is slow and so software implementation doesn't affect performance significantly.



Shown above is an I2C-based SSD1306 OLED display. This was the display for my weather station. The weather station was based on a [Sparkfun Weather Board](#). During that project, I was encountering an issue with the on board SHT15 relative humidity-temperature sensor chip and I could not find out the issue for quite some time. I thought that the MCU's TWI module was malfunctioning and so I took the help of software I2C for rooting out the cause. Cases like these make software I2C-based testing really useful and interesting.



Shown above is the typical timing diagram for a I2C bus. We can expect the same patterns in both hardware I2C and software I2C but bus speed may differ. I2C bus speed become critical in some cases. For example, consider the case of the OLED display above.

Code Example

SW_I2C.h

```
#include <msp430.h>
#include "delay.h"

#define SW_I2C_DIR          P1DIR
#define SW_I2C_OUT          P1OUT
#define SW_I2C_IN           P1IN

#define SDA_pin              BIT7
#define SCL_pin              BIT6

#define SDA_DIR_OUT()        do{SW_I2C_DIR |= SDA_pin;}while(0)
#define SDA_DIR_IN()         do{SW_I2C_DIR &= ~SDA_pin;}while(0)
#define SCL_DIR_OUT()        do{SW_I2C_DIR |= SCL_pin;}while(0)
#define SCL_DIR_IN()         do{SW_I2C_DIR &= ~SCL_pin;}while(0)

#define SDA_HIGH()           do{SW_I2C_OUT |= SDA_pin;}while(0)
#define SDA_LOW()            do{SW_I2C_OUT &= ~SDA_pin;}while(0)
#define SCL_HIGH()           do{SW_I2C_OUT |= SCL_pin;}while(0)
#define SCL_LOW()            do{SW_I2C_OUT &= ~SCL_pin;}while(0)

#define SDA_IN()             (SW_I2C_IN & SDA_pin)

#define I2C_ACK              0xFF
#define I2C_NACK             0x00

#define I2C_timeout          1000

void SW_I2C_init(void);
void SW_I2C_start(void);
void SW_I2C_stop(void);
unsigned char SW_I2C_read(unsigned char ack);
void SW_I2C_write(unsigned char value);
void SW_I2C_ACK_NACK(unsigned char mode);
unsigned char SW_I2C_wait_ACK(void);
```

SW_I2C.c

```
#include "SW_I2C.h"

void SW_I2C_init(void)
{
    SDA_DIR_OUT();
    SCL_DIR_OUT();
    delay_ms(1);
    SDA_HIGH();
    SCL_HIGH();
}

void SW_I2C_start(void)
{
    SDA_DTR_OUT();
```

```

    SDA_HIGH();
    SCL_HIGH();
    delay_us(4);
    SDA_LOW();
    delay_us(4);
    SCL_LOW();
}

void SW_I2C_stop(void)
{
    SDA_DIR_OUT();
    SDA_LOW();
    SCL_HIGH();
    delay_us(4);
    SDA_HIGH();
    SCL_HIGH();
    delay_us(4);
}

unsigned char SW_I2C_read(unsigned char ack)
{
    unsigned char i = 8;
    unsigned char j = 0;

    SDA_DIR_IN();

    while(i > 0)
    {
        SCL_LOW();
        delay_us(2);
        SCL_HIGH();
        delay_us(2);
        j <= 1;

        if(SDA_IN() != 0x00)
        {
            j++;
        }

        delay_us(1);
        i--;
    };

    switch(ack)
    {
        case I2C_ACK:
        {
            SW_I2C_ACK_NACK(I2C_ACK);;
            break;
        }
        default:
        {
            SW_I2C_ACK_NACK(I2C_NACK);;
            break;
        }
    }
}

```

```

    return j;
}

void SW_I2C_write(unsigned char value)
{
    unsigned char i = 8;

    SDA_DIR_OUT();
    SCL_LOW();

    while(i > 0)
    {

        if(((value & 0x80) >> 7) != 0x00)
        {
            SDA_HIGH();
        }
        else
        {
            SDA_LOW();
        }

        value <= 1;
        delay_us(2);
        SCL_HIGH();
        delay_us(2);
        SCL_LOW();
        delay_us(2);
        i--;
    };
}

void SW_I2C_ACK_NACK(unsigned char mode)
{
    SCL_LOW();
    SDA_DIR_OUT();

    switch(mode)
    {
        case I2C_ACK:
        {
            SDA_LOW();
            break;
        }
        default:
        {
            SDA_HIGH();
            break;
        }
    }

    delay_us(2);
    SCL_HIGH();
    delay_us(2);
    SCL_LOW();
}

```

```

unsigned char SW_I2C_wait_ACK(void)
{
    signed int timeout = 0;

    SDA_DIR_IN();

    SDA_HIGH();
    delay_us(1);
    SCL_HIGH();
    delay_us(1);

    while(SDA_IN() != 0x00)
    {
        timeout++;

        if(timeout > I2C_timeout)
        {
            SW_I2C_stop();
            return 1;
        }
    };

    SCL_LOW();
    return 0;
}

```

PCF8591.h

#define PCF8591_address	0x90
#define PCF8591_read_cmd	(PCF8591_address 0x01)
#define PCF8591_write_cmd	PCF8591_address
#define AIN0	0x00
#define AIN1	0x01
#define AIN2	0x02
#define AIN3	0x03
#define Auto_Increment_Enable	0x04
#define Auto_Increment_Disable	0x00
#define Four_Channel_ADC	0x00
#define Three_differential_Inputs	0x10
#define AIN0_and_1_Single_AIN2_and_AIN3_Differential	0x20
#define All_Differential	0x30
#define AOut_enable	0x40
#define AOut_disable	0x00
void PCF8591_write(unsigned char control_value, unsigned char data_value);	
unsigned char PCF8591_read(unsigned char control_value);	

PCF8591.c

```
#include "PCF8591.h"

void PCF8591_write(unsigned char control_value, unsigned char data_value)
{
    SW_I2C_start();
    SW_I2C_write(PCF8591_write_cmd);
    SW_I2C_wait_ACK();
    SW_I2C_write((control_value & 0xFF));
    SW_I2C_wait_ACK();
    SW_I2C_write(data_value);
    SW_I2C_wait_ACK();
    SW_I2C_stop();
}

unsigned char PCF8591_read(unsigned char control_value)
{
    unsigned char value = 0;

    SW_I2C_start();
    SW_I2C_write(PCF8591_write_cmd);
    SW_I2C_wait_ACK();
    SW_I2C_write((control_value & 0xFF));
    SW_I2C_NACK(I2C_ACK);
    SW_I2C_stop();

    SW_I2C_start();
    SW_I2C_write(PCF8591_read_cmd);
    SW_I2C_wait_ACK();
    value = SW_I2C_read(0);
    SW_I2C_wait_ACK();
    SW_I2C_stop();

    return value;
}
```

main.c

```
#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8591.h"
#include "lcd.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned char value);

void main(void)
{
    unsigned char adc0 = 0;
```

```

unsigned char adc1 = 0;
unsigned char adc2 = 0;
unsigned char adc3 = 0;

WDTCTL = WDTPW | WDTHOLD;      // Stop watchdog timer

/* initialize Config for the MSP430 GPIO */
GPIO_graceInit();

/* initialize Config for the MSP430 2xx family clock systems (BCS) */
BCSplus_graceInit();

/* initialize Config for the MSP430 System Registers */
System_graceInit();

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

SW_I2C_init();
LCD_init();

LCD_goto(0, 0);
LCD_putstr("A0:");

LCD_goto(9, 0);
LCD_putstr("A1:");

LCD_goto(0, 1);
LCD_putstr("A2:");

LCD_goto(9, 1);
LCD_putstr("A3:");

while(1)
{
    adc0 = PCF8591_read(AOut_enable | Four_Channel_ADC |
Auto_Increment_Disable | AIN0);
    lcd_print(4, 0, adc0);

    adc1 = PCF8591_read(AOut_enable | Four_Channel_ADC |
Auto_Increment_Disable | AIN1);
    lcd_print(13, 0, adc1);

    adc2 = PCF8591_read(AOut_enable | Four_Channel_ADC |
Auto_Increment_Disable | AIN2);
    lcd_print(4, 1, adc2);

    adc3 = PCF8591_read(AOut_enable | Four_Channel_ADC |
Auto_Increment_Disable | AIN3);
    lcd_print(13, 1, adc3);

    PCF8591_write(AOut_enable, adc0);
    delay_ms(400);
};

void GPIO_graceInit(void)
{

```

```

/* USER CODE START (section: GPIO_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT6 | BIT7;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = BIT0 | BIT1 | BIT2;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */
}

```

```

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF) {
        /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
         * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
    }
}

```

```

        */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
/* USER CODE START (section: System_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: System_graceInit_prologue) */

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
_bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)

```

```

{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

```

void lcd_print(unsigned char x_pos, unsigned char y_pos, unsigned char value)
{
    unsigned char ch = 0;

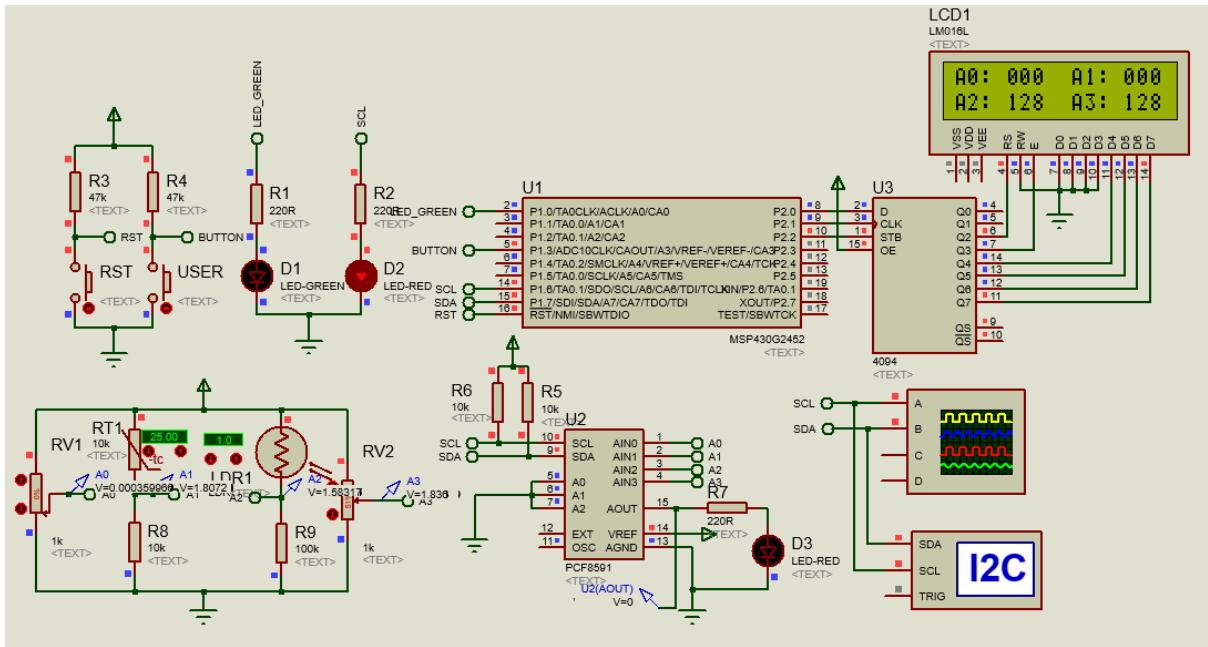
    ch = ((value / 100) + 0x30);
    LCD_goto(x_pos, y_pos);
    LCD_putchar(ch);

    ch = (((value / 10) % 10) + 0x30);
    LCD_goto((x_pos + 1), y_pos);
    LCD_putchar(ch);

    ch = ((value % 10) + 0x30);
    LCD_goto((x_pos + 2), y_pos);
    LCD_putchar(ch);
}

```

Simulation

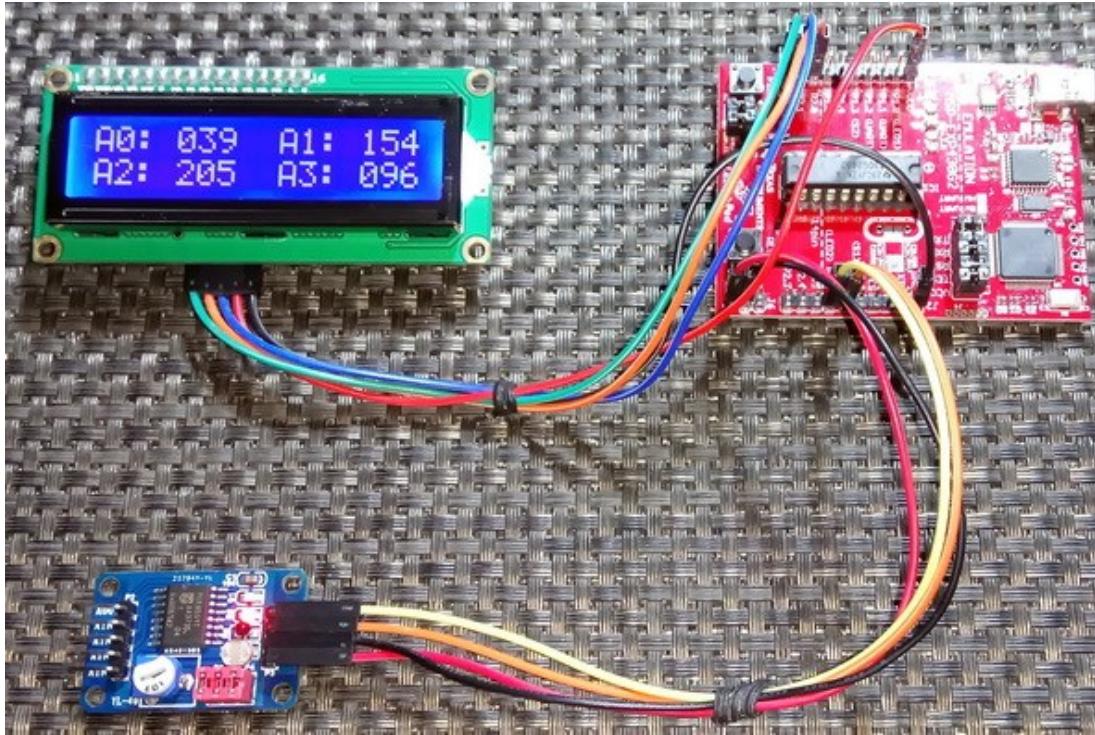


Explanation

Just like software-based SPI, software-based I2C employs bit-banging ordinary digital I/Os. The whole functioning of I2C protocol is implemented in software. Again, the software I2C codes are self-explanatory. This software I2C implementation can be used for any I2C-based device. If you have gone through the pages recommended earlier, you will understand how it is working.

For this demo, a PCF8591 8-bit ADC-DAC module is used. This ready-made board hosts four 8-bit ADC input channels and an 8-bit DAC output channel. Off the shelf, it contains a thermistor for sensing ambient temperature, a light-dependent resistor (LDR) for detecting light level, a potentiometer connected across the power rail and a free ADC input. The ADC inputs can also be used in various ways. Check the device's datasheet for details. I did a very raw level coding for the demo, and so I just read and showed the ADC values. The DAC is operated using the value of ADC channel 0.

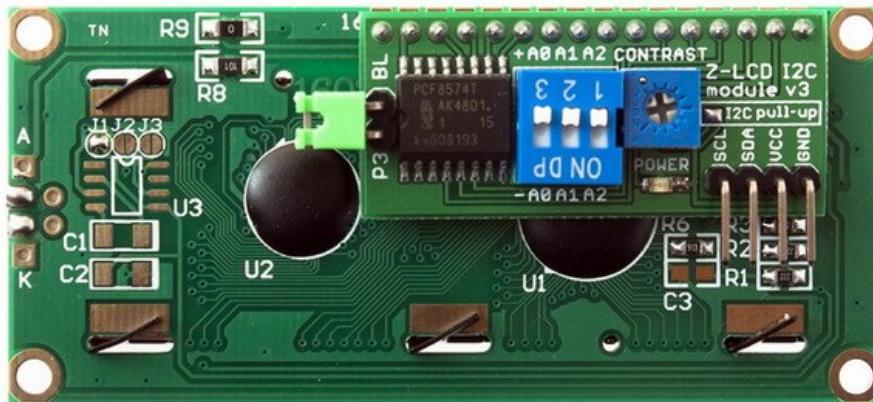
Demo



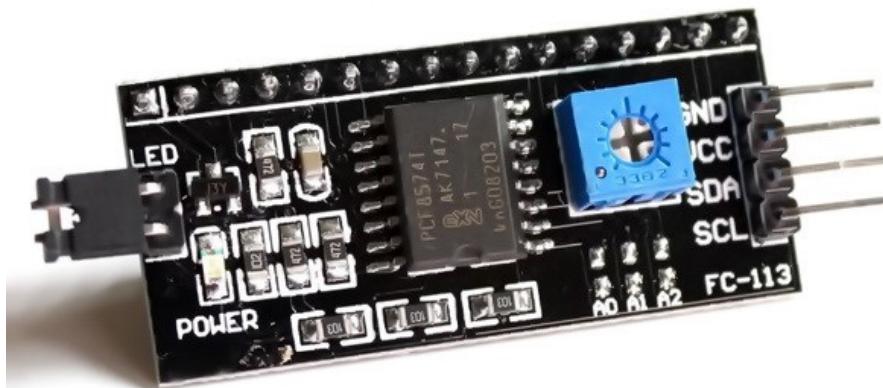
Demo video: <https://www.youtube.com/watch?v=ElRvBRv7YY4>.

Two Wire LCD

This segment is basically the repetition of the bit-banging-based LCD example shown earlier. In that example, we saw software SPI-based LCD driving technique. Here we will see the same but with USI-based I2C. We can also use software I2C for the same purpose.



In the embedded system world, there is a cheap and popular 2-wire LCD module based on PCF8574T.



There are a few advantages of this module. Firstly, it is based on a PCF8574T chip that is made by NXP (*a.k.a* Philips). NXP happens to be the founder of I2C communication and so the chip is well documented in terms of I2C communication. Secondly, there are three external address selection bits which can be used to address multiple LCDs existing on the same I2C bus. Lastly the module is compact and readily plug-and-playable.

Code Example

lcd.h

```
#include <msp430.h>
#include "PCF8574.h"
#include "delay.h"

#define clear_display          0x01
#define goto_home              0x02

#define cursor_direction_inc   (0x04 | 0x02)
#define cursor_direction_dec   (0x04 | 0x00)
#define display_shift          (0x04 | 0x01)
#define display_no_shift        (0x04 | 0x00)

#define display_on              (0x08 | 0x04)
#define display_off             (0x08 | 0x02)
#define cursor_on               (0x08 | 0x02)
#define cursor_off              (0x08 | 0x00)
#define blink_on                (0x08 | 0x01)
#define blink_off               (0x08 | 0x00)

#define _8_pin_interface        (0x20 | 0x10)
#define _4_pin_interface        (0x20 | 0x00)
#define _2_row_display          (0x20 | 0x08)
#define _1_row_display          (0x20 | 0x00)
#define _5x10_dots              (0x20 | 0x40)
#define _5x7_dots               (0x20 | 0x00)

#define dly                    1

#define CMD                    0
#define DAT                    1

#define BL_ON                  1
#define BL_OFF                 0

unsigned char bl_state;
unsigned char data_value;

void LCD_init(void);
void LCD_send(unsigned char value, unsigned char control_type);
void LCD_4bit_send(unsigned char lcd_data);
void LCD_putstr(char *lcd_string);
void LCD_putchar(char char_data);
void LCD_clear_home(void);
void LCD_goto(unsigned char x_pos, unsigned char y_pos);
```

lcd.c

```
#include "lcd.h"

extern unsigned char data_value;

void LCD_init(void)
{
    bl_state = BL_ON;
    data_value = 0x04;
    PCF8574_write(data_value);

    delay_ms(10);

    data_value = 0x30;
    PCF8574_write(data_value);

    data_value |= 0x04;
    PCF8574_write(data_value);
    delay_ms(dly);
    data_value &= 0xF1;
    PCF8574_write(data_value);
    delay_ms(dly);

    data_value = 0x30;
    PCF8574_write(data_value);

    data_value |= 0x04;
    PCF8574_write(data_value);
    delay_ms(dly);
    data_value &= 0xF1;
    PCF8574_write(data_value);
    delay_ms(dly);

    data_value = 0x30;
    PCF8574_write(data_value);

    data_value |= 0x04;
    PCF8574_write(data_value);
    delay_ms(dly);
    data_value &= 0xF1;
    PCF8574_write(data_value);
    delay_ms(dly);

    data_value = 0x20;
    PCF8574_write(data_value);

    data_value |= 0x04;
    PCF8574_write(data_value);
    delay_ms(dly);
    data_value &= 0xF1;
    PCF8574_write(data_value);
    delay_ms(dly);

    LCD_send((_4_pin_interface | _2_row_display | _5x7_dots), CMD);
    LCD_send((display_on | cursor_off | blink_off), CMD);
    LCD_send((clear_display), CMD);
```

```

        LCD_send((cursor_direction_inc | display_no_shift), CMD);
    }

void LCD_send(unsigned char value, unsigned char control_type)
{
    switch(control_type)
    {
        case CMD:
        {
            data_value &= 0xF4;
            break;
        }
        case DAT:
        {
            data_value |= 0x01;
            break;
        }
    }

    switch(bl_state)
    {
        case BL_ON:
        {
            data_value |= 0x08;
            break;
        }
        case BL_OFF:
        {
            data_value &= 0xF7;
            break;
        }
    }

    PCF8574_write(data_value);
    LCD_4bit_send(value);
    delay_ms(10);
}

void LCD_4bit_send(unsigned char lcd_data)
{
    unsigned char temp = 0x00;

    temp = (lcd_data & 0xF0);
    data_value &= 0x0F;
    data_value |= temp;
    PCF8574_write(data_value);

    data_value |= 0x04;
    PCF8574_write(data_value);
    delay_ms(dly);
    data_value &= 0xF9;
    PCF8574_write(data_value);
    delay_ms(dly);

    temp = (lcd_data & 0x0F);
    temp <= 0x04;
    data_value &= 0x0F;
}

```

```

    data_value |= temp;
    PCF8574_write(data_value);

    data_value |= 0x04;
    PCF8574_write(data_value);
    delay_ms(dly);
    data_value &= 0xF9;
    PCF8574_write(data_value);
    delay_ms(dly);
}

void LCD_putstr(char *lcd_string)
{
    while(*lcd_string != '\0')
    {
        LCD_send(*lcd_string++, DAT);
    };
}

void LCD_putchar(char char_data)
{
    LCD_send(char_data, DAT);
}

void LCD_clear_home(void)
{
    LCD_send(clear_display, CMD);
    LCD_send(goto_home, CMD);
}

void LCD_goto(unsigned char x_pos,unsigned char y_pos)
{
    if(y_pos == 0)
    {
        LCD_send((0x80 | x_pos), CMD);
    }
    else
    {
        LCD_send((0x80 | 0x40 | x_pos), CMD);
    }
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "I2C.h"
#include "PCF8574.h"
#include "lcd.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USI_graceInit(void);

```

```

void System_graceInit(void);
void WDTplus_graceInit(void);
void show_value(unsigned char value);

void main(void)
{
    unsigned char s = 0;

    char txt1[] = {"MICROARENA"};
    char txt2[] = {"SShahryiar"};
    char txt3[] = {"MSP-EXP430G2"};
    char txt4[] = {"Launchpad!"};

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 USI */
    USI_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    LCD_init();
    LCD_clear_home();

    LCD_goto(3, 0);
    LCD_putstr(txt1);
    LCD_goto(3, 1);
    LCD_putstr(txt2);
    delay_ms(2600);

    LCD_clear_home();

    for(s = 0; s < 12; s++)
    {
        LCD_goto((2 + s), 0);
        LCD_putchar(txt3[s]);
        delay_ms(60);
    }
    for(s = 0; s < 10; s++)
    {
        LCD_goto((3 + s), 1);
        LCD_putchar(txt4[s]);
        delay_ms(60);
    }

    delay_ms(2600);

    s = 0;
}

```

```

LCD_clear_home();

LCD_goto(3, 0);
LCD_putstr(txt1);

while(1)
{
    show_value(s);
    s++;
    delay_ms(200);
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT6 | BIT7;

    /* Port 1 Direction Register */
    P1DIR = 0;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */
}

```

```

/*
 * Basic Clock System Control 2
 *
 * SELM_0 -- DCOCLK
 * DIVM_0 -- Divide by 1
 * ~SELS -- DCOCLK
 * DIVS_0 -- Divide by 1
 * ~DCOR -- DCO uses internal resistor
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

if (CALBC1_1MHZ != 0xFF) {
    /* Follow recommended flow. First, clear all DCox and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCox and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
    DCOCTL = CALDCO_1MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void USI_graceInit(void)
{
    /* USER CODE START (section: USI_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: USI_graceInit_prologue) */

    /* Disable USI */
    USICTL0 |= USISWRST;

    /*

```

```

* USI Control Register 0
*
* USIPE7 -- USI function enabled
* USIPE6 -- USI function enabled
* ~USIPE5 -- USI function disabled
* ~USILSB -- MSB first
* USIMST -- Master mode
* ~USIGE -- Output latch enable depends on shift clock
* ~USIOE -- Output disabled
* USISWRST -- USI logic held in reset state
*
* Note: ~<BIT> indicates that <BIT> has value zero
*/
USICTL0 = USIPE7 | USIPE6 | USIMST | USISWRST;

/*
* USI Control Register 1
*
* ~USICKPH -- Data is changed on the first SCLK edge and captured on the
following edge
* USII2C -- I2C mode enabled
* ~USISTTIE -- Interrupt on START condition disabled
* USIIIE -- Interrupt enabled
* ~USIAL -- No arbitration lost condition
* ~USISTP -- No STOP condition received
* ~USISTTIFG -- No START condition received. No interrupt pending
* USIIFG -- Interrupt pending
*
* Note: ~<BIT> indicates that <BIT> has value zero
*/
USICTL1 = USII2C | USIIIE | USIIFG;

/*
* USI Clock Control Register
*
* USIDIV_4 -- Divide by 16
* USISSEL_2 -- SMCLK
* USICKPL -- Inactive state is high
* ~USISWCLK -- Input clock is low
*
* Note: ~USISWCLK indicates that USISWCLK has value zero
*/
USICKCTL = USIDIV_7 | USISSEL_2 | USICKPL;

/*
* USI Bit Counter Register
*
* ~USISCLREL -- SCL line is held low if USIIFG is set
* ~USI16B -- 8-bit shift register mode. Low byte register USISRL is used
* USIIFGCC -- USIIFG is not cleared automatically
* ~USICNT4 -- USI bit count
* ~USICNT3 -- USI bit count
* ~USICNT2 -- USI bit count
* ~USICNT1 -- USI bit count
* ~USICNT0 -- USI bit count
*
* Note: ~<BIT> indicates that <BIT> has value zero
*/
USICNT = USIIFGCC;

```

```

/* Enable USI */
USICTL0 &= ~USISWRST;

/* Clear pending flag */
USICTL1 &= ~(USIIFG + USISTTIFG);

/* USER CODE START (section: USI_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: USI_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /* Clear oscillator fault flag with software delay */
    do
    {
        // Clear OSC fault flag
        IFG1 &= ~OFIFG;

        // 50us delay
        __delay_cycles(50);
    } while (IFG1 & OFIFG);

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    __bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped

```

```

    * ~WDTNMIES -- NMI on rising edge
    * ~WDTNMI -- Reset function
    * ~WDTTMSEL -- Watchdog mode
    * ~WDTCNTCL -- No action
    * ~WDTSSEL -- SMCLK
    * ~WDTIS0 -- Watchdog clock source bit0 disabled
    * ~WDTIS1 -- Watchdog clock source bit1 disabled
    *
    * Note: ~<BIT> indicates that <BIT> has value zero
    */
WDTCTL = WDTPW | WDTHOLD;

/* USER CODE START (section: RTC_B_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void show_value(unsigned char value)
{
    unsigned char ch = 0x00;

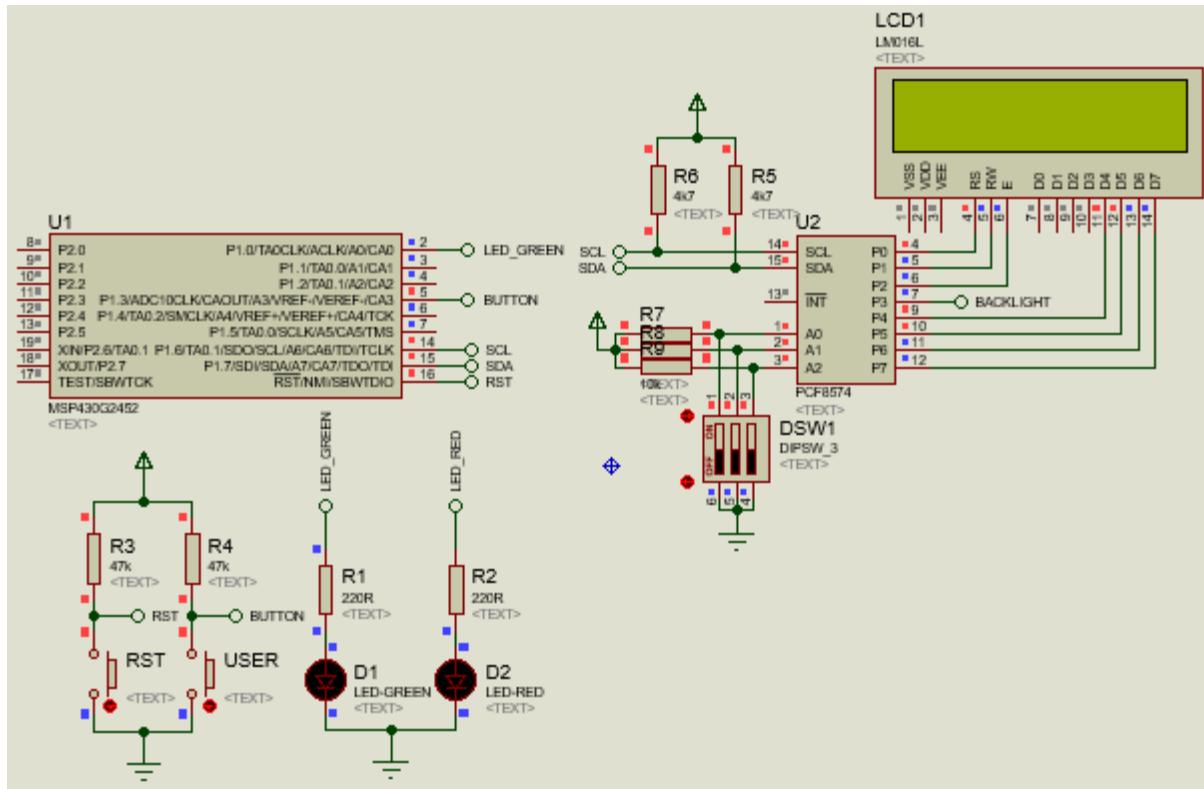
    ch = ((value / 100) + 0x30);
    LCD_goto(6, 1);
    LCD_putchar(ch);

    ch = (((value / 10) % 10) + 0x30);
    LCD_goto(7, 1);
    LCD_putchar(ch);

    ch = ((value % 10) + 0x30);
    LCD_goto(8, 1);
    LCD_putchar(ch);
}

```

Simulation

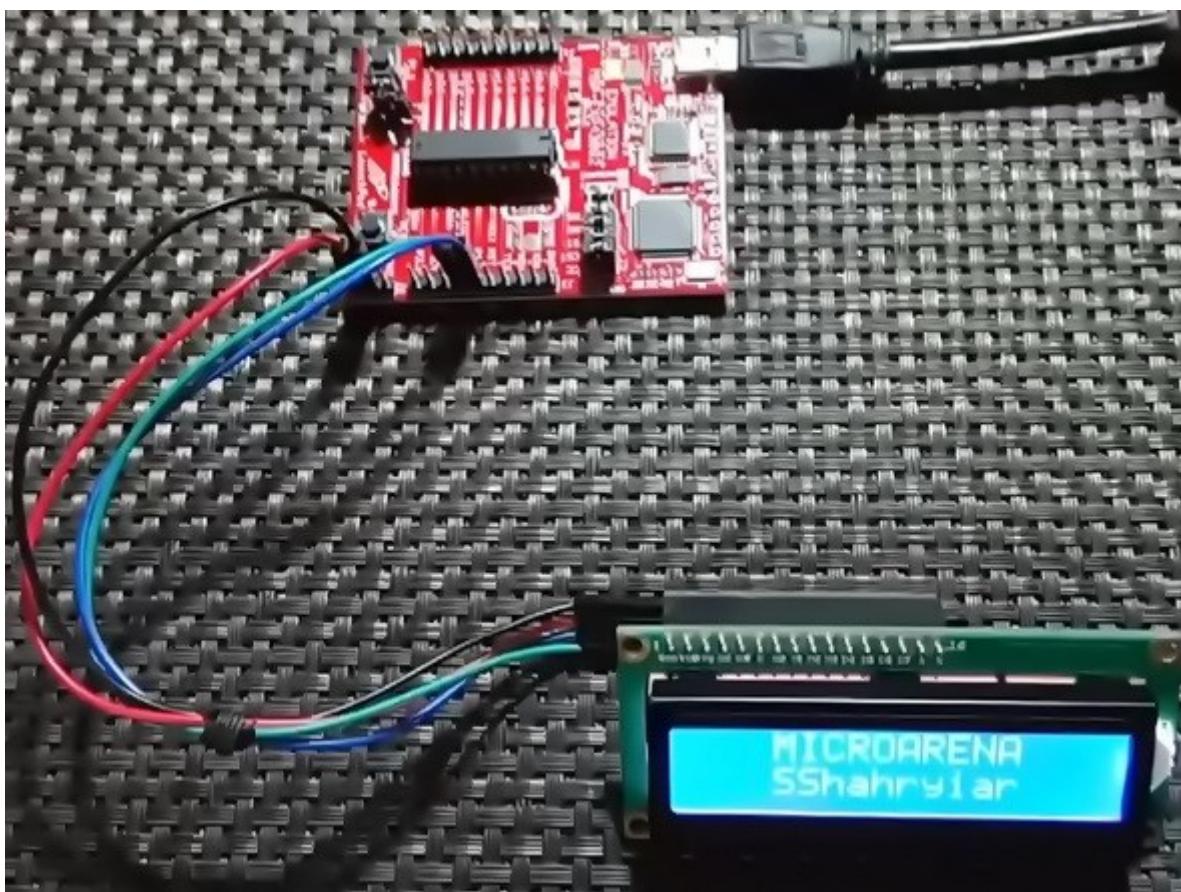
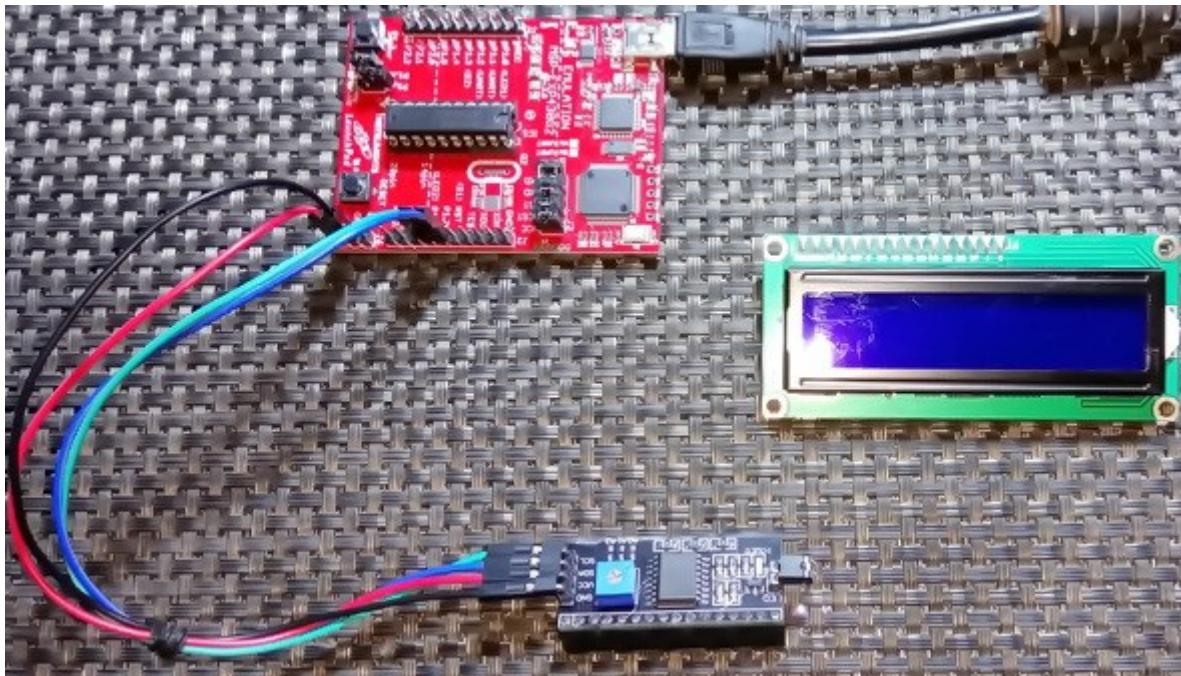


*Note Proteus VSM could not simulate I2C-based simulations. The simulation here only shows connections.

Explanation

The code utilizes the same USI-based I2C library as in the USI-I2C example. Just like the software SPI-based LCD example, the main difference is the way the LCD is driven. LCD data and commands are sent through I2C bus and the PCF8574 GPIO expander IC converts these to parallel outputs. The expanded GPIOs are then used to drive the LCD in 4-bit mode.

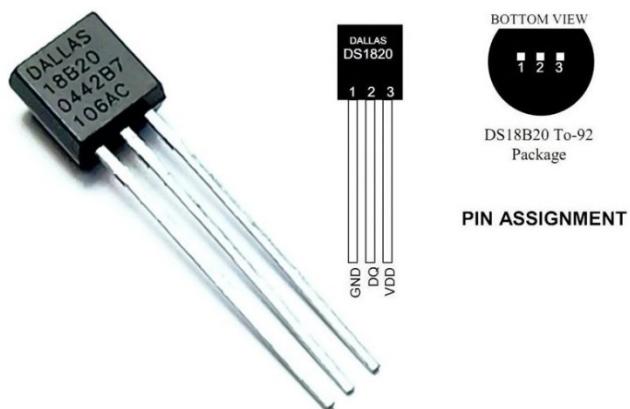
Demo



Demo video: <https://www.youtube.com/watch?v=y6HQATVucNk>.

One Wire (OW) – Interfacing DS18B20 Temperature Sensor

One Wire (OW) or single wire communication is different from other more common and conventional communication platforms like SPI or I2C in terms of data exchange behavior. OW communication is also not very much popular compared to SPI, UART (RS232), I2C, RS485, etc. From device to device, the way of exchanging data varies but what's common is the fact that all devices that use this communication method use a sort of time-slotted mechanism. Ones and zeros are defined by high pulse time over a fixed period. This trick is widely used in infrared remote controllers. One major advantage of OW communication is the fact that no special or dedicated hardware block is needed to implement it. All that is typically needed is a digital I/O pin. A timer can be used for tracking time-slots but it is optional. External interrupts can also be optionally used alongside the timer. DS18B20 one wire digital temperature sensor from Dallas semiconductor uses this communication protocol.



Code Example

one_wire.h

```
#include <msp430.h>
#include "delay.h"

#define DS18B20_DIR          P2DIR
#define DS18B20_OUT_PORT     P2OUT
#define DS18B20_IN_PORT      P2IN
#define DS18B20_PIN           BIT0

#define DS18B20_OUTPUT()      do{DS18B20_DIR |= DS18B20_PIN;}while(0)
#define DS18B20_INPUT()       do{DS18B20_DIR &= ~DS18B20_PIN;}while(0)

#define DS18B20_IN()          (DS18B20_IN_PORT & DS18B20_PIN)

#define DS18B20_OUT_LOW()     do{DS18B20_OUT_PORT &= ~DS18B20_PIN;}while(0)
#define DS18B20_OUT_HIGH()    do{DS18B20_OUT_PORT |= DS18B20_PIN;}while(0)

#define TRUE                 1
#define FALSE                0
```

```
unsigned char onewire_reset(void);
void onewire_write_bit(unsigned char bit_value);
unsigned char onewire_read_bit(void);
void onewire_write(unsigned char value);
unsigned char onewire_read(void);
```

one_wire.c

```
#include "one_wire.h"

unsigned char onewire_reset(void)
{
    unsigned char res = FALSE;

    DS18B20_OUTPUT();
    DS18B20_OUT_LOW();
    delay_us(480);
    DS18B20_OUT_HIGH();
    delay_us(60);

    DS18B20_INPUT();
    res = DS18B20_IN();
    delay_us(480);

    return res;
}

void onewire_write_bit(unsigned char bit_value)
{
    DS18B20_OUTPUT();
    DS18B20_OUT_LOW();

    if(bit_value)
    {
        delay_us(104);
        DS18B20_OUT_HIGH();
    }
}

unsigned char onewire_read_bit(void)
{
    DS18B20_OUTPUT();
    DS18B20_OUT_LOW();
    DS18B20_OUT_HIGH();
    delay_us(15);
    DS18B20_INPUT();

    return(DS18B20_IN());
}

void onewire_write(unsigned char value)
{
    unsigned char s = 0;
```

```

DS18B20_OUTPUT();

while(s < 8)
{
    if((value & (1 << s)))
    {
        DS18B20_OUT_LOW();
        _delay_cycles(1);
        DS18B20_OUT_HIGH();
        delay_us(60);
    }

    else
    {
        DS18B20_OUT_LOW();
        delay_us(60);
        DS18B20_OUT_HIGH();
        _delay_cycles(1);
    }

    s++;
}

unsigned char onewire_read(void)
{
    unsigned char s = 0x00;
    unsigned char value = 0x00;

    while(s < 8)
    {
        DS18B20_OUTPUT();

        DS18B20_OUT_LOW();
        _delay_cycles(1);
        DS18B20_OUT_HIGH();

        DS18B20_INPUT();
        if(DS18B20_IN())
        {
            value |= (1 << s);
        }

        delay_us(60);

        s++;
    }

    return value;
}

```

DS18B20.h

```

#include <msp430.h>
#include "delay.h"
#include "one_wire.h"

```

```

#define convert_T          0x44
#define read_scratchpad   0xBE
#define write_scratchpad  0x4E
#define copy_scratchpad   0x48
#define recall_E2          0xB8
#define read_power_supply 0xB4
#define skip_ROM           0xCC

#define resolution         12

void DS18B20_init(void);
float DS18B20_get_temperature(void);

```

DS18B20.c

```

#include "DS18B20.h"

void DS18B20_init(void)
{
    onewire_reset();
    delay_ms(100);
}

float DS18B20_get_temperature(void)
{
    unsigned char msb = 0x00;
    unsigned char lsb = 0x00;
    register float temp = 0.0;

    onewire_reset();
    onewire_write(skip_ROM);
    onewire_write(convert_T);

    switch(resolution)
    {
        case 12:
        {
            delay_ms(750);
            break;
        }
        case 11:
        {
            delay_ms(375);
            break;
        }
        case 10:
        {
            delay_ms(188);
            break;
        }
        case 9:
        {
            delay_ms(94);
            break;
        }
    }
}

```

```

        }

    onewire_reset();

    onewire_write(skip_ROM);
    onewire_write(read_scratchpad);

    lsb = onewire_read();
    msb = onewire_read();

    temp = msb;
    temp *= 256.0;
    temp += lsb;

    switch(resolution)
    {
        case 12:
        {
            temp *= 0.0625;
            break;
        }
        case 11:
        {
            temp *= 0.125;
            break;
        }
        case 10:
        {
            temp *= 0.25;
            break;
        }
        case 9:
        {
            temp *= 0.5;
            break;
        }
    }

    delay_ms(40);

    return (temp);
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "one_wire.h"
#include "DS18B20.h"
#include "lcd.h"

const unsigned char symbol[8] =
{

```

```

    0x00, 0x06, 0x09, 0x09, 0x06, 0x00, 0x00, 0x00
};

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_symbol(void);
void print_C(unsigned char x_pos, unsigned char y_pos, signed int value);
void print_I(unsigned char x_pos, unsigned char y_pos, signed long value);
void print_D(unsigned char x_pos, unsigned char y_pos, signed int value, unsigned
char points);
void print_F(unsigned char x_pos, unsigned char y_pos, float value, unsigned char
points);

void main(void)
{
    float t = 0.0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    DS18B20_init();
    LCD_init();
    lcd_symbol();

    LCD_goto(1, 0);
    LCD_putstr("MSP430 DS18B20");

    LCD_goto(0, 1);
    LCD_putstr("T/ C");
    LCD_goto(2, 1);
    LCD_send(0, DAT);

    while(1)
    {
        t = DS18B20_get_temperature();
        print_F(9, 1, t, 3);
        delay_ms(1000);
    };
}

void GPIO_graceInit(void)
{

```

```

/* USER CODE START (section: GPIO_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Direction Register */
P1DIR = 0;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF)
    {

```

```

/* Adjust this accordingly to your VCC rise time */
_delay_cycles(100000);

// Follow recommended flow. First, clear all DCOx and MODx bits. Then
// apply new RSELx values. Finally, apply new DCOx and MODx bit values.
DCOCTL = 0x00;
BCSCTL1 = CALBC1_8MHZ;           /* Set DCO to 8MHz */
DCOCTL = CALDCO_8MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
/* USER CODE START (section: System_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: System_graceInit_prologue) */

/*
 * SR, Status Register
 *
 * ~SCG1 -- Disable System clock generator 1
 * ~SCG0 -- Disable System clock generator 0
 * ~OSCOFF -- Oscillator On
 * ~CPUOFF -- CPU On
 * GIE -- General interrupt enable
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
_bis_SR_register(GIE);

/* USER CODE START (section: System_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: System_graceInit_epilogue) */
}

```

```

}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void lcd_symbol(void)
{
    unsigned char s = 0;

    LCD_send(0x40, CMD);

    for(s = 0; s < 8; s++)
    {
        LCD_send(symbol[s], DAT);
    }

    LCD_send(0x80, CMD);
}

void print_C(unsigned char x_pos, unsigned char y_pos, signed int value)
{
    char ch[5] = {0x20, 0x20, 0x20, 0x20, '\0'};

    if(value < 0x00)
    {
        ch[0] = 0x2D;
        value = -value;
    }
    else
    {
        ch[0] = 0x20;
    }
}

```

```

}

if((value > 99) && (value <= 999))
{
    ch[1] = ((value / 100) + 0x30);
    ch[2] = (((value % 100) / 10) + 0x30);
    ch[3] = ((value % 10) + 0x30);
}
else if((value > 9) && (value <= 99))
{
    ch[1] = (((value % 100) / 10) + 0x30);
    ch[2] = ((value % 10) + 0x30);
    ch[3] = 0x20;
}
else if((value >= 0) && (value <= 9))
{
    ch[1] = ((value % 10) + 0x30);
    ch[2] = 0x20;
    ch[3] = 0x20;
}

LCD_goto(x_pos, y_pos);
LCD_putstr(ch);
}

void print_I(unsigned char x_pos, unsigned char y_pos, signed long value)
{
    char ch[7] = {0x20, 0x20, 0x20, 0x20, 0x20, 0x20, '\0'};

    if(value < 0)
    {
        ch[0] = 0x2D;
        value = -value;
    }
    else
    {
        ch[0] = 0x20;
    }

    if(value > 9999)
    {
        ch[1] = ((value / 10000) + 0x30);
        ch[2] = (((value % 10000)/ 1000) + 0x30);
        ch[3] = (((value % 1000) / 100) + 0x30);
        ch[4] = (((value % 100) / 10) + 0x30);
        ch[5] = ((value % 10) + 0x30);
    }

    else if((value > 999) && (value <= 9999))
    {
        ch[1] = (((value % 10000)/ 1000) + 0x30);
        ch[2] = (((value % 1000) / 100) + 0x30);
        ch[3] = (((value % 100) / 10) + 0x30);
        ch[4] = ((value % 10) + 0x30);
        ch[5] = 0x20;
    }

    else if((value > 99) && (value <= 999))
    {

```

```

        ch[1] = (((value % 1000) / 100) + 0x30);
        ch[2] = (((value % 100) / 10) + 0x30);
        ch[3] = ((value % 10) + 0x30);
        ch[4] = 0x20;
        ch[5] = 0x20;
    }
    else if((value > 9) && (value <= 99))
    {
        ch[1] = (((value % 100) / 10) + 0x30);
        ch[2] = ((value % 10) + 0x30);
        ch[3] = 0x20;
        ch[4] = 0x20;
        ch[5] = 0x20;
    }
    else
    {
        ch[1] = ((value % 10) + 0x30);
        ch[2] = 0x20;
        ch[3] = 0x20;
        ch[4] = 0x20;
        ch[5] = 0x20;
    }
    LCD_goto(x_pos, y_pos);
    LCD_putstr(ch);
}

void print_D(unsigned char x_pos, unsigned char y_pos, signed int value, unsigned char points)
{
    char ch[5] = {0x2E, 0x20, 0x20, '\0'};

    ch[1] = ((value / 100) + 0x30);

    if(points > 1)
    {
        ch[2] = (((value / 10) % 10) + 0x30);

        if(points > 1)
        {
            ch[3] = ((value % 10) + 0x30);
        }
    }

    LCD_goto(x_pos, y_pos);
    LCD_putstr(ch);
}

void print_F(unsigned char x_pos, unsigned char y_pos, float value, unsigned char points)
{
    signed long tmp = 0x0000;

    tmp = value;
    print_I(x_pos, y_pos, tmp);
    tmp = ((value - tmp) * 1000);
}

```

```

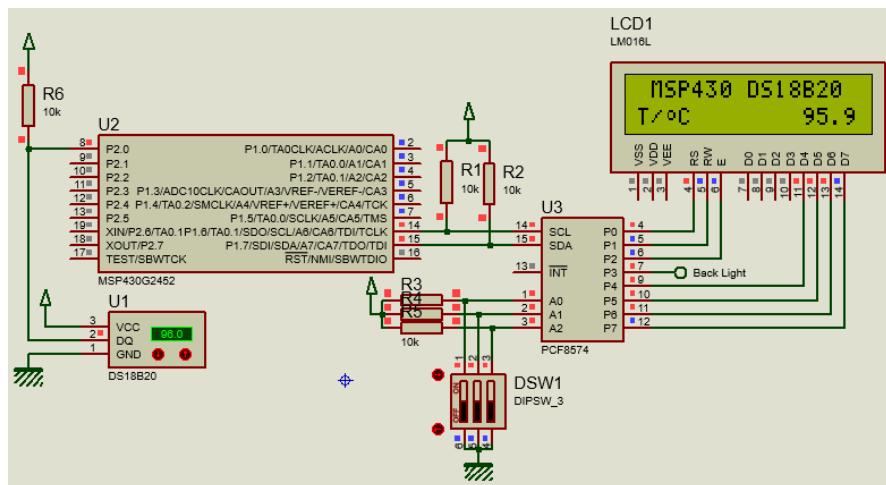
if(tmp < 0)
{
    tmp = -tmp;
}

if(value < 0)
{
    value = -value;
    LCD_goto(x_pos, y_pos);
    LCD_putchar(0x2D);
}
else
{
    LCD_goto(x_pos, y_pos);
    LCD_putchar(0x20);
}

if((value >= 10000) && (value < 100000))
{
    print_D((x_pos + 6), y_pos, tmp, points);
}
else if((value >= 1000) && (value < 10000))
{
    print_D((x_pos + 5), y_pos, tmp, points);
}
else if((value >= 100) && (value < 1000))
{
    print_D((x_pos + 4), y_pos, tmp, points);
}
else if((value >= 10) && (value < 100))
{
    print_D((x_pos + 3), y_pos, tmp, points);
}
else if(value < 10)
{
    print_D((x_pos + 2), y_pos, tmp, points);
}
}

```

Simulation



Explanation

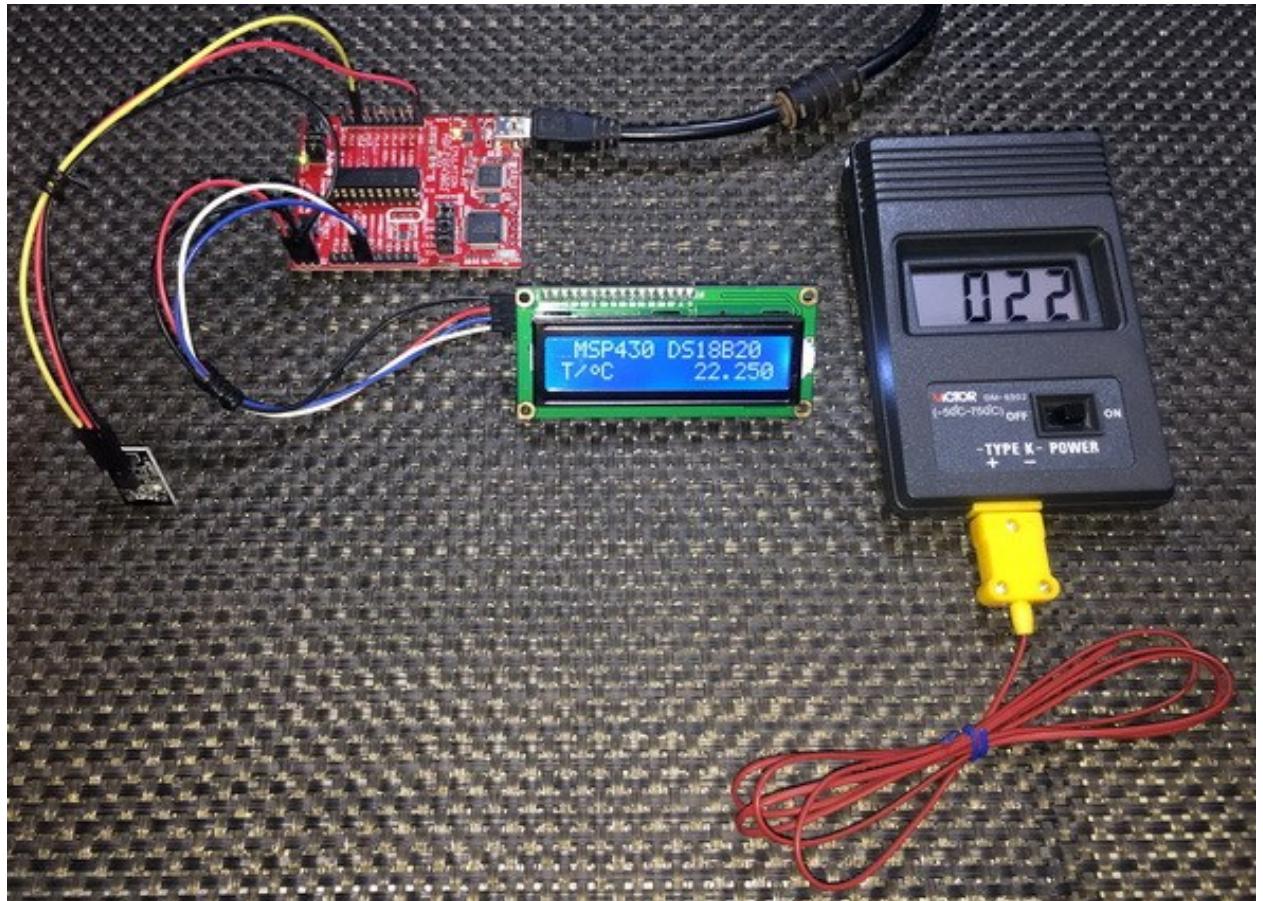
One wire communication is detailed in these application notes from Maxim:

<https://www.maximintegrated.com/en/app-notes/index.mvp/id/126>

<https://www.maximintegrated.com/en/app-notes/index.mvp/id/162>

These notes are all that are needed for implementing the one wire communication interface for DS18B20. Please go through these notes for details. The codes are self-explanatory and are implemented from the code examples in these app notes.

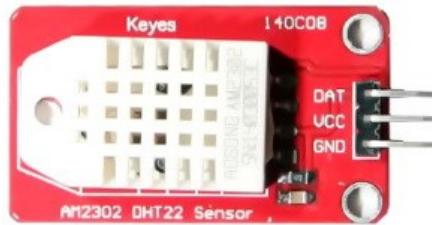
Demo



Demo video: <https://youtu.be/G0rSDnkcSZA>.

One Wire (OW) – Interfacing DHT22 Hygrometer Sensor

Like DS18B20, DHT22 (a.k.a AM2302) digital relative humidity-temperature or hygrometer sensor uses time-slotted principle over one wire to transfer data to its host controller. Apart from other technical specs, these sensors differ in terms of time-slots and in the process of data exchanging and communication bus arbitration. Since data is transferred digitally over one wire, there is no need for such sensors to be present on board and close to the host MCU. Thus, such sensors can be placed significantly far from the host micro. This is not so easily possible with analog sensors or with sensors using multiple wires. This feature is what makes OW communication method an impressive one.



Code Example

DHT22.h

```
#include <msp430.h>
#include <delay.h>

#define DHT22_DIR P2DIR
#define DHT22_OUT_PORT P2OUT
#define DHT22_IN_PORT P2IN
#define DHT22_PIN BIT0

#define DHT22_DIR_OUT() do{DHT22_DIR |= DHT22_PIN;}while(0)
#define DHT22_DIR_IN() do{DHT22_DIR &= ~DHT22_PIN;}while(0)

#define DHT22_IN() (DHT22_IN_PORT & DHT22_PIN)

#define DHT22_OUT_LOW() do{DHT22_OUT_PORT &= ~DHT22_PIN;}while(0)
#define DHT22_OUT_HIGH() do{DHT22_OUT_PORT |= DHT22_PIN;}while(0)

#define TRUE 1
#define FALSE 0

extern unsigned char values[5];

void DHT22_init(void);
unsigned char DHT22_get_byte(void);
unsigned char DHT22_get_data(void);
```

DHT22.c

```
#include "DHT22.h"

unsigned char values[5];

void DHT22_init(void)
{
    DHT22_DIR_IN();
    delay_ms(1000);
}

unsigned char DHT22_get_byte(void)
{
    unsigned char s = 8;
    unsigned char value = 0;

    DHT22_DIR_IN();

    while(s > 0)
    {
        value <<= 1;

        while(DHT22_IN() == FALSE);
        delay_us(30);

        if(DHT22_IN())
        {
            value |= 1;
        }

        while(DHT22_IN());
        s--;
    }

    return value;
}

unsigned char DHT22_get_data(void)
{
    unsigned char chk = FALSE;
    unsigned char s = 0;
    unsigned char check_sum = 0;

    DHT22_DIR_OUT();
    DHT22_OUT_HIGH();
    DHT22_OUT_LOW();

    delay_ms(1);

    DHT22_OUT_HIGH();

    delay_us(32);
    DHT22_DIR_IN();
```

```

chk = DHT22_IN();
delay_us(2);

if(chk == TRUE)
{
    return 1;
}

delay_us(80);

chk = DHT22_IN();

if(chk == FALSE)
{
    return 2;
}

delay_us(80);

for(s = 0; s <= 4; s += 1)
{
    values[s] = DHT22_get_byte();
}

DHT22_DIR_OUT();
DHT22_OUT_HIGH();

for(s = 0; s < 4; s++)
{
    check_sum += values[s];
}

if(check_sum != values[4])
{
    return 3;
}
else
{
    return 0;
}
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"
#include "DHT22.h"

const unsigned char symbol[8] =
{
    0x00, 0x06, 0x09, 0x09, 0x06, 0x00, 0x00, 0x00
};

```

```

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void lcd_symbol(void);
void print_C(unsigned char x_pos, unsigned char y_pos, signed int value);
void print_I(unsigned char x_pos, unsigned char y_pos, signed long value);
void print_D(unsigned char x_pos, unsigned char y_pos, signed int value, unsigned
char points);
void print_F(unsigned char x_pos, unsigned char y_pos, float value, unsigned char
points);

void main(void)
{
    float value = 0.0;
    unsigned char state = 0;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    DHT22_init();
    LCD_init();
    lcd_symbol();

    while(1)
    {
        state = DHT22_get_data();

        switch(state)
        {
            case 1:
            {
                LCD_goto(0, 0);
                LCD_putstr("No Sensor Found!");
                LCD_goto(0, 1);
                LCD_putstr("          ");
                break;
            }

            case 2:
            {
                LCD_goto(0, 0);
                LCD_putstr("Checksum Error!");
                LCD_goto(0, 1);
                LCD_putstr("          ");
            }
        }
    }
}

```

```

        break;
    }

default:
{
    value = ((values[0] * 256.0 + values[1]) * 0.1);

    LCD_goto(0, 0);
    LCD_putstr("R.H%:      ");
    print_F(11, 0, value, 1);

    value = ((values[2] * 256.0 + values[3]) * 0.1);

    LCD_goto(0, 1);
    LCD_putstr("T/ C :      ");
    LCD_goto(2, 1);
    LCD_send(0, DAT);
    print_F(11, 1, value, 1);

    break;
}
}

delay_ms(1000);
};

void GPIO_graceInit(void)
{
/* USER CODE START (section: GPIO_graceInit_prologue) */
/* User initialization code */
/* USER CODE END (section: GPIO_graceInit_prologue) */

/* Port 1 Output Register */
P1OUT = 0;

/* Port 1 Direction Register */
P1DIR = 0;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */

```

```

P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF)
    {
        /* Adjust this accordingly to your VCC rise time */
        __delay_cycles(100000);

        // Follow recommended flow. First, clear all DCOx and MODx bits. Then
        // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_8MHZ;          /* Set DCO to 8MHz */
        DCOCTL = CALDCO_8MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;

    /*
     * Basic Clock System Control 3
     *
     * XT2S_0 -- 0.4 - 1 MHz
     * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
     * XCAP_1 -- ~6 pF
     */
}

```

```

BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

```

}

void lcd_symbol(void)
{
    unsigned char s = 0;

    LCD_send(0x40, CMD);

    for(s = 0; s < 8; s++)
    {
        LCD_send(symbol[s], DAT);
    }

    LCD_send(0x80, CMD);
}

void print_C(unsigned char x_pos, unsigned char y_pos, signed int value)
{
    char ch[5] = {0x20, 0x20, 0x20, 0x20, '\0'};

    if(value < 0x00)
    {
        ch[0] = 0x2D;
        value = -value;
    }
    else
    {
        ch[0] = 0x20;
    }

    if((value > 99) && (value <= 999))
    {
        ch[1] = ((value / 100) + 0x30);
        ch[2] = (((value % 100) / 10) + 0x30);
        ch[3] = ((value % 10) + 0x30);
    }
    else if((value > 9) && (value <= 99))
    {
        ch[1] = (((value % 100) / 10) + 0x30);
        ch[2] = ((value % 10) + 0x30);
        ch[3] = 0x20;
    }
    else if((value >= 0) && (value <= 9))
    {
        ch[1] = ((value % 10) + 0x30);
        ch[2] = 0x20;
        ch[3] = 0x20;
    }

    LCD_goto(x_pos, y_pos);
    LCD_putstr(ch);
}

void print_I(unsigned char x_pos, unsigned char y_pos, signed long value)
{
    char ch[7] = {0x20, 0x20, 0x20, 0x20, 0x20, 0x20, '\0'};
}

```

```

if(value < 0)
{
    ch[0] = 0x2D;
    value = -value;
}
else
{
    ch[0] = 0x20;
}

if(value > 9999)
{
    ch[1] = ((value / 10000) + 0x30);
    ch[2] = (((value % 10000)/ 1000) + 0x30);
    ch[3] = (((value % 1000) / 100) + 0x30);
    ch[4] = (((value % 100) / 10) + 0x30);
    ch[5] = ((value % 10) + 0x30);
}

else if((value > 999) && (value <= 9999))
{
    ch[1] = (((value % 10000)/ 1000) + 0x30);
    ch[2] = (((value % 1000) / 100) + 0x30);
    ch[3] = (((value % 100) / 10) + 0x30);
    ch[4] = ((value % 10) + 0x30);
    ch[5] = 0x20;
}
else if((value > 99) && (value <= 999))
{
    ch[1] = (((value % 1000) / 100) + 0x30);
    ch[2] = (((value % 100) / 10) + 0x30);
    ch[3] = ((value % 10) + 0x30);
    ch[4] = 0x20;
    ch[5] = 0x20;
}
else if((value > 9) && (value <= 99))
{
    ch[1] = (((value % 100) / 10) + 0x30);
    ch[2] = ((value % 10) + 0x30);
    ch[3] = 0x20;
    ch[4] = 0x20;
    ch[5] = 0x20;
}
else
{
    ch[1] = ((value % 10) + 0x30);
    ch[2] = 0x20;
    ch[3] = 0x20;
    ch[4] = 0x20;
    ch[5] = 0x20;
}

LCD_goto(x_pos, y_pos);
LCD_putstr(ch);
}

```

```

void print_D(unsigned char x_pos, unsigned char y_pos, signed int value, unsigned char points)
{
    char ch[5] = {0x2E, 0x20, 0x20, '\0'};

    ch[1] = ((value / 100) + 0x30);

    if(points > 1)
    {
        ch[2] = (((value / 10) % 10) + 0x30);

        if(points > 1)
        {
            ch[3] = ((value % 10) + 0x30);
        }
    }

    LCD_goto(x_pos, y_pos);
    LCD_putstr(ch);
}

void print_F(unsigned char x_pos, unsigned char y_pos, float value, unsigned char points)
{
    signed long tmp = 0x0000;

    tmp = value;
    print_I(x_pos, y_pos, tmp);
    tmp = ((value - tmp) * 1000);

    if(tmp < 0)
    {
        tmp = -tmp;
    }

    if(value < 0)
    {
        value = -value;
        LCD_goto(x_pos, y_pos);
        LCD_putchar(0x2D);
    }
    else
    {
        LCD_goto(x_pos, y_pos);
        LCD_putchar(0x20);
    }

    if((value >= 10000) && (value < 100000))
    {
        print_D((x_pos + 6), y_pos, tmp, points);
    }
    else if((value >= 1000) && (value < 10000))
    {
        print_D((x_pos + 5), y_pos, tmp, points);
    }
    else if((value >= 100) && (value < 1000))
    {
        print_D((x_pos + 4), y_pos, tmp, points);
    }
}

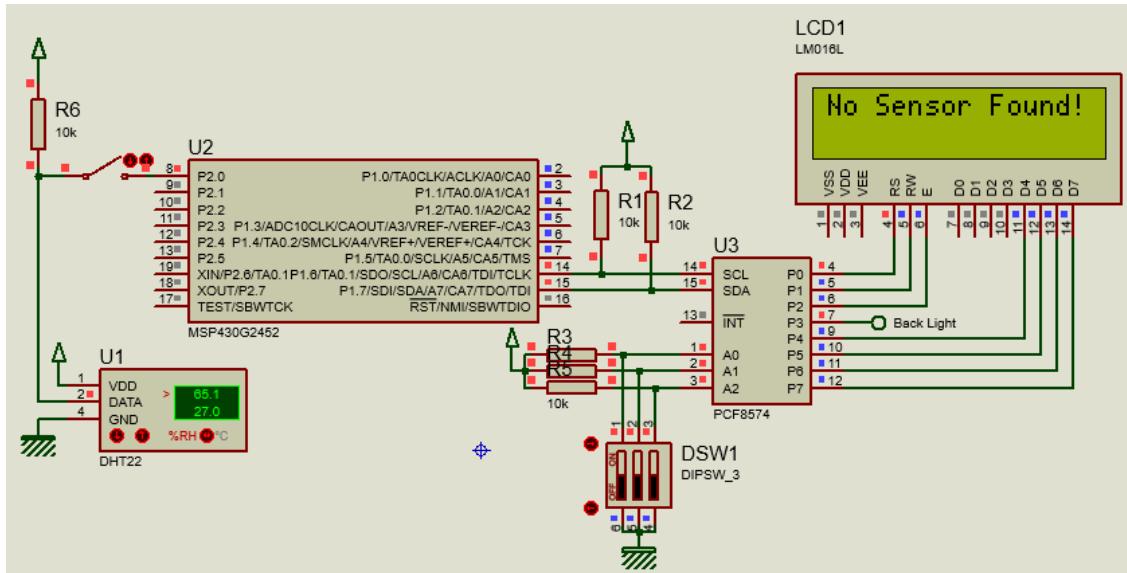
```

```

    }
    else if((value >= 10) && (value < 100))
    {
        print_D((x_pos + 3), y_pos, tmp, points);
    }
    else if(value < 10)
    {
        print_D((x_pos + 2), y_pos, tmp, points);
    }
}

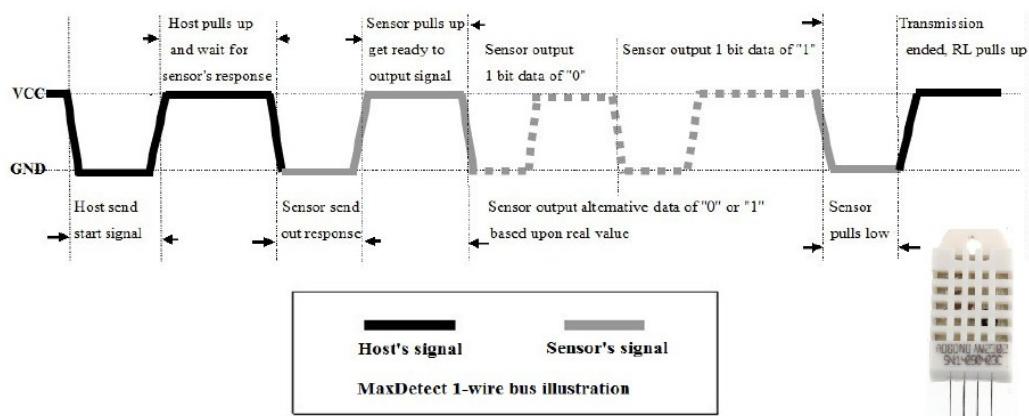
```

Simulation



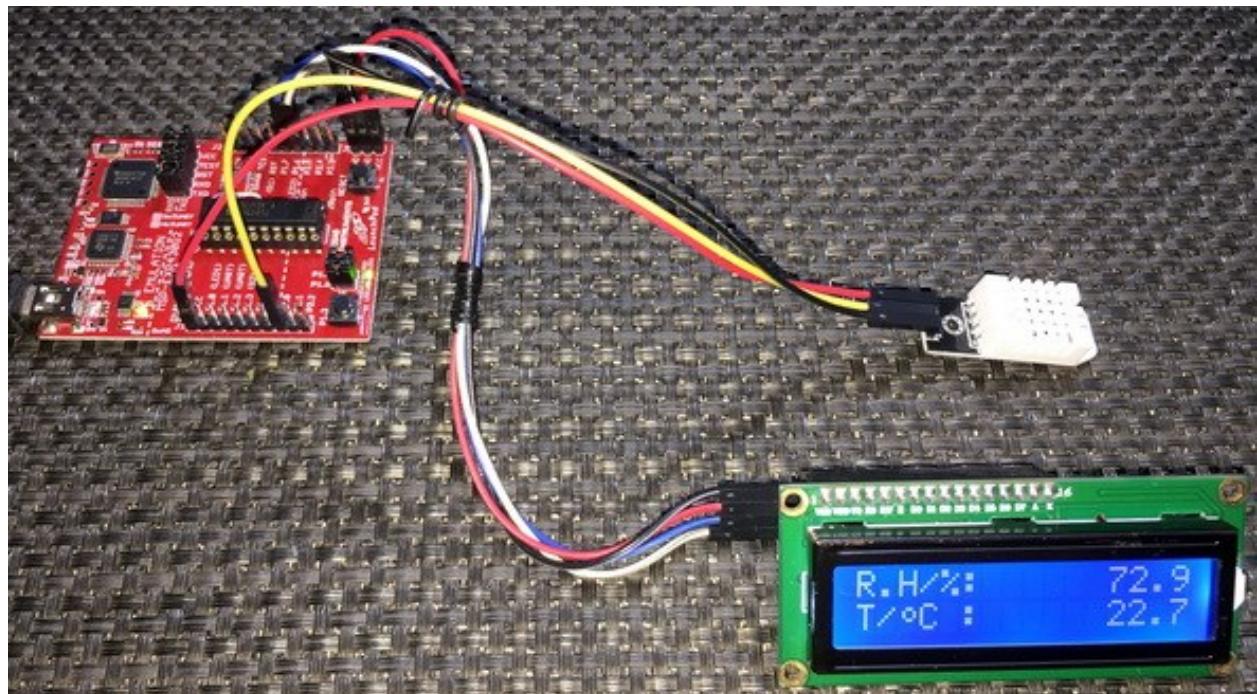
Explanation

Unlike I2C, SPI, UART and other communication methods, one wire communication has no fixed communication standard. A perfect example is the difference between the way of communicating with DHT22 and DS18B20. Although they appear to share a similar methodology but the communication protocols are different.



Shown above is the timing diagram of DHT22. If you compare the timings for ones and zeroes in both devices you'll notice that these timings are way different. Same goes for the data, command and control processes. Here again the datasheet of DHT22 is used to create the library for DHT22 and the process is just manipulation of a single GPIO pin.

Demo



Demo video: <https://youtu.be/Emi-skFcs4A>.

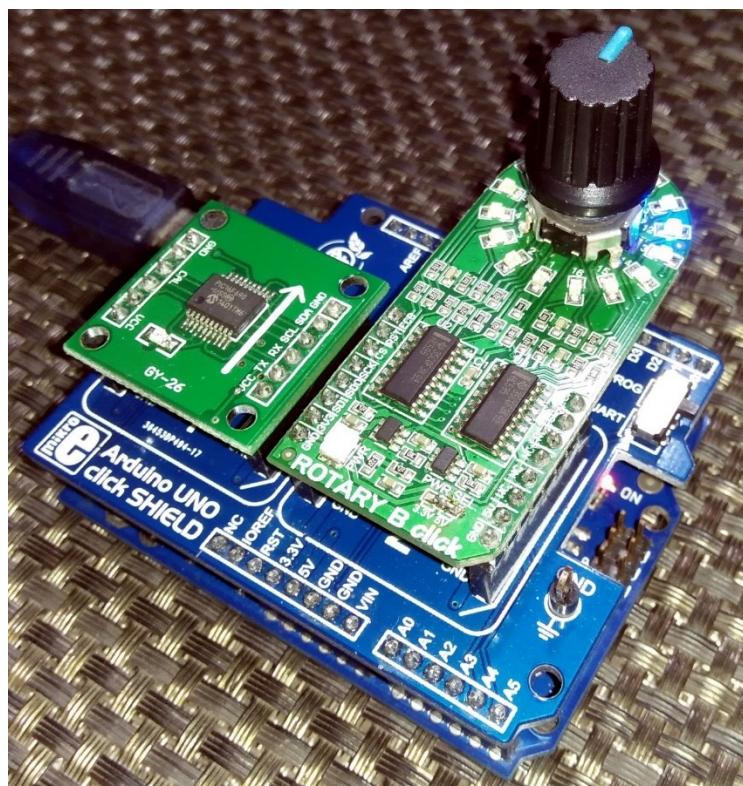
USCI - UART

Serial communication is perhaps the most widely used communication method for interfacing a PC or other machines with a micro and over long distances. With just two cross-connecting wires, we can achieve a full-duplex point-to-point communication. Owing to its simplicity, range and wide usage, it is the communication interface backbone that is used for GSM modems, RF modules, Zigbee devices like CC2530, BLE devices like CC2540, Wi-Fi devices like CC3200, etc. Other forms of advance serial communications have their lineages tracing back to it, for example, RS-485, LIN, IrDA, etc.



Serial Communication Bus

Shown below is a demo of HMC1022-based LED compass. To communicate with this chip to get compass heading, we need to send-receive data via UART.



To learn more about UART visit the following link:
<https://learn.mikroe.com/uart-serial-communication/>

Code Example

```
#include <msp430.h>
#include "delay.h"
#include "lcd.h"

unsigned char rx = 0;

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void USCI_A0_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);
void UART_putc(char ch);
void UART_puts(char *str);

#pragma vector=USCIAB0RX_VECTOR
__interrupt void USCI0RX_ISR_HOOK(void)
{
    rx = UCA0RXBUF;
}

void main(void)
{
    unsigned char tx = 0x20;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();

    /* initialize Config for the MSP430 USCI_A0 */
    USCI_A0_graceInit();

    /* initialize Config for the MSP430 System Registers */
    System_graceInit();

    /* initialize Config for the MSP430 WDT+ */
    WDTplus_graceInit();

    UART_puts("\f");
    UART_puts("MSP430G2553 UART Demo\n");
    UART_puts("Shawon Shahryiar\n");
    UART_puts("https://www.facebook.com/MicroArena\n");

    LCD_init();

    LCD_goto(0, 0);
    LCD_putstr("TXD:");
    LCD_goto(0, 1);
```

```

LCD_putstr("RXD:");

while(1)
{
    LCD_goto(15, 0);
    LCD_putchar(tx);
    UART_putc(tx);
    tx++;

    if(tx > 0x7F)
    {
        tx = 0x20;
    }

    LCD_goto(15, 1);
    LCD_putchar(rx);

    delay_ms(400);
};

}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Port Select 2 Register */
    P1SEL2 = BIT1 | BIT2;

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Port Select Register */
    P1SEL = BIT1 | BIT2;

    /* Port 1 Direction Register */
    P1DIR = 0;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = BIT0 | BIT1 | BIT2;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* Port 3 Output Register */
}

```

```

P3OUT = 0;

/* Port 3 Direction Register */
P3DIR = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue)
}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_1MHZ != 0xFF) {
        /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
         * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
         */
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_1MHZ;      /* Set DCO to 1MHz */
        DCOCTL = CALDCO_1MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;

    /*
     * Basic Clock System Control 3
     *
     * XT2S_0 -- 0.4 - 1 MHz
     * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
     * XCAP_1 -- ~6 pF
     */
    BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;
}

```

```

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void USCI_A0_graceInit(void)
{
    /* USER CODE START (section: USCI_A0_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: USCI_A0_graceInit_prologue) */

    /* Disable USCI */
    UCA0CTL1 |= UCSWRST;

    /*
     * Control Register 0
     *
     * ~UCPEN -- Parity Disabled
     * UCPAR -- Even parity
     * ~UCMSB -- LSB first
     * ~UC7BIT -- 8-bit
     * ~UCSPB -- One stop bit
     * UCMODE_0 -- UART Mode
     * ~UCSYNC -- Asynchronous mode
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    UCA0CTL0 = UCPAR | UCMODE_0;

    /*
     * Control Register 1
     *
     * UCSSEL_2 -- SMCLK
     * ~UCRXIE -- Erroneous characters rejected and UCAxRXIFG is not set
     * ~UCBRKIE -- Received break characters do not set UCAxRXIFG
     * ~UCDORM -- Not dormant. All received characters will set UCAxRXIFG
     * ~UCTXADDR -- Next frame transmitted is data
     * ~UCTXBKR -- Next frame transmitted is not a break
     * UCSWRST -- Enabled. USCI logic held in reset state
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    UCA0CTL1 = UCSSEL_2 | UCSWRST;

    /*
     * Modulation Control Register
     *
     * UCBRF_0 -- First stage 0
     * UCBRS_1 -- Second stage 1
     * ~UCOS16 -- Disabled
     *
     * Note: ~UCOS16 indicates that UCOS16 has value zero
     */
    UCA0MCTL = UCBRF_0 | UCBRS_1;

    /* Baud rate control register 0 */
    UCA0BR0 = 104;
}

```

```

/* Enable USCI */
UCA0CTL1 &= ~UCSWRST;

/* USER CODE START (section: USCI_A0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: USCI_A0_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * IFG2, Interrupt Flag Register 2
     *
     * ~UCB0TXIFG -- No interrupt pending
     * ~UCB0RXIFG -- No interrupt pending
     * ~UCA0TXIFG -- No interrupt pending
     * UCA0RXIFG -- Interrupt pending
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    IFG2 &= ~(UCA0RXIFG);

    /*
     * IE2, Interrupt Enable Register 2
     *
     * ~UCB0TXIE -- Interrupt disabled
     * ~UCB0RXIE -- Interrupt disabled
     * ~UCA0TXIE -- Interrupt disabled
     * UCA0RXIE -- Interrupt enabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    IE2 |= UCA0RXIE;

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

```

```

void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

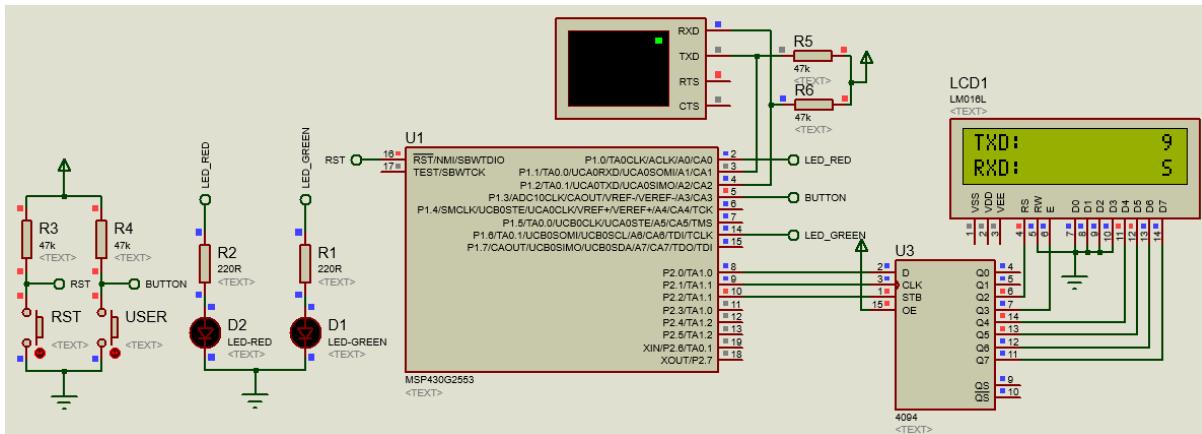
    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

void UART_putc(char ch)
{
    while(!(IFG2 & UCA0TXIFG));
    UCA0TXBUF = ch;
}

void UART_puts(char *str)
{
    while(*str != 0)
    {
        while(!(IFG2 & UCA0TXIFG));
        UCA0TXBUF = *str++;
    }
}

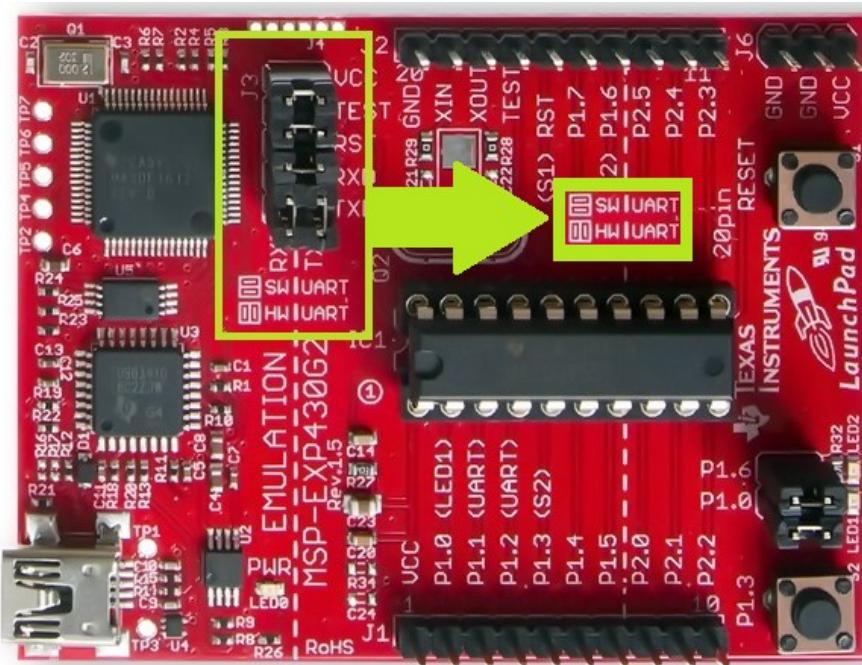
```

Simulation



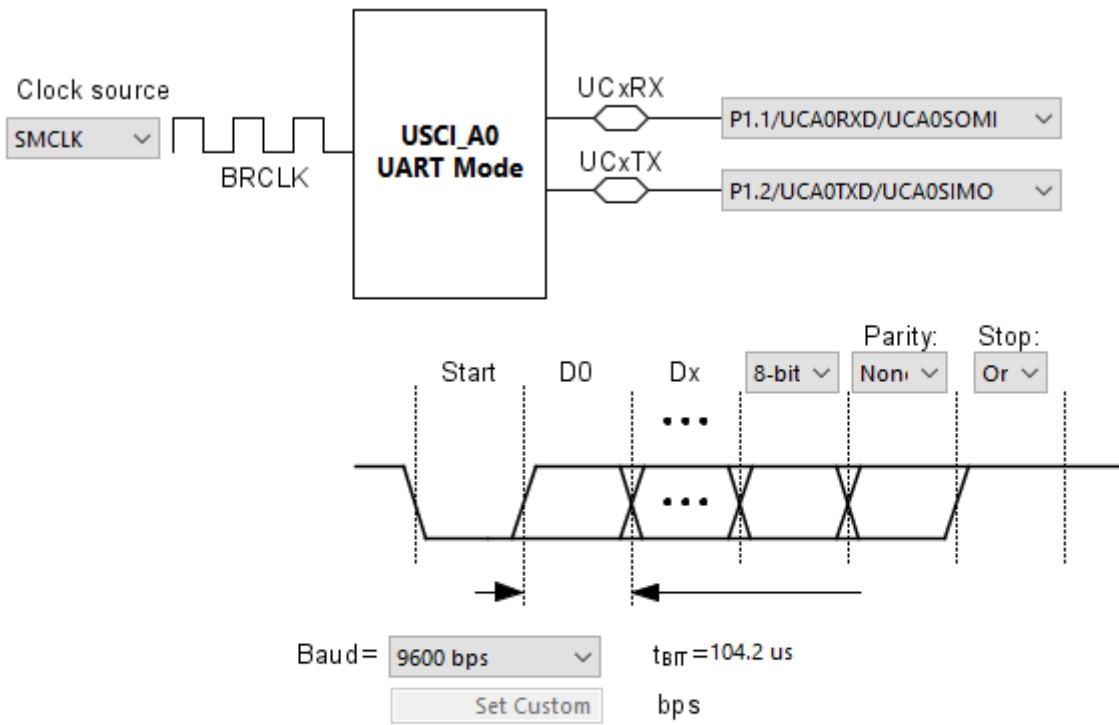
Explanation

MSP430G2553 is used for this demo since it has UART-supporting USCI module. An important thing to note before trying to use the UART is the jumper settings shown below:



The photo shows that the TX-RX jumpers are connected in way perpendicular to other jumpers. However, by default, jumpers are connected the other way around, i.e. software UART. If the jumpers are setup as shown, we can access the on-board USB-UART converter, i.e. hardware UART. We will need this piece of hardware for communicating with a computer.

Using GRACE, we setup the USCI module in asynchronous UART mode with typical settings like 9600 baudrate and 8-bit data transfer mode. GRACE also takes care of baud rate generation calculation. UART data reception interrupt is also used to quickly respond to incoming characters.



Interrupt Enables

USCI_A0 UART transmit interrupt enable

[Generate Interrupt Handler Code](#)

USCI_A0 UART receive interrupt enable

[Remove Interrupt Handler Code](#)

[View All Interrupt Handlers](#)

```
/* Disable USCI */
UCA0CTL1 |= UCSWRST;

/*
 * Control Register 0
 *
 * ~UCPEN -- Parity Disabled
 * UCPAR -- Even parity
 * ~UCMSB -- LSB first
 * ~UC7BIT -- 8-bit
 * ~UCSPB -- One stop bit
 * UCMODE_0 -- UART Mode
 * ~UCSYNC -- Asynchronous mode
 *
 * Note: ~<BIT> indicates that <BIT> has value zero
 */
UCA0CTL0 = UCPAR | UCMODE_0;

/*
 * Control Register 1
 *
 * UCSSEL_2 -- SMCLK
 * ~UCRXIE -- Erroneous characters rejected and UCAxRXIFG is not set
 * ~UCBRKIE -- Received break characters do not set UCAxRXIFG
 * ~UCDORM -- Not dormant. All received characters will set UCAxRXIFG
 * ~UCTXADDR -- Next frame transmitted is data
 * ~UCTXBRK -- Next frame transmitted is not a break
*/
```

```

/* UCSWRST -- Enabled. USCI logic held in reset state
*
* Note: ~<BIT> indicates that <BIT> has value zero
*/
UCA0CTL1 = UCSSEL_2 | UCSWRST;

/*
* Modulation Control Register
*
* UCBRF_0 -- First stage 0
* UCBRS_1 -- Second stage 1
* ~UCOS16 -- Disabled
*
* Note: ~UCOS16 indicates that UCOS16 has value zero
*/
UCA0MCTL = UCBRF_0 | UCBRS_1;

/* Baud rate control register 0 */
UCA0BR0 = 104;

/* Enable USCI */
UCA0CTL1 |= ~UCSWRST;

```

Right after initialization of all required hardware, the UART starts sending some strings.

```

UART_puts("\f");
UART_puts("MSP430G2553 UART Demo\n");
UART_puts("Shawon Shahryiar\n");
UART_puts("https://www.facebook.com/MicroArena\n");

```

The following functions transmit data via UART. The first one can transmit one character at a time while the second can transmit a string of characters. In both cases, it is checked if the last character has been successfully sent before sending a new character.

```

void UART_putc(char ch)
{
    while(!(IFG2 & UCA0TXIFG));
    UCA0TXBUF = ch;
}

void UART_puts(char *str)
{
    while(*str != 0)
    {
        while(!(IFG2 & UCA0TXIFG));
        UCA0TXBUF = *str++;
    };
}

```

Since data reception interrupt is used, data received is extracted from UART reception ISR.

```

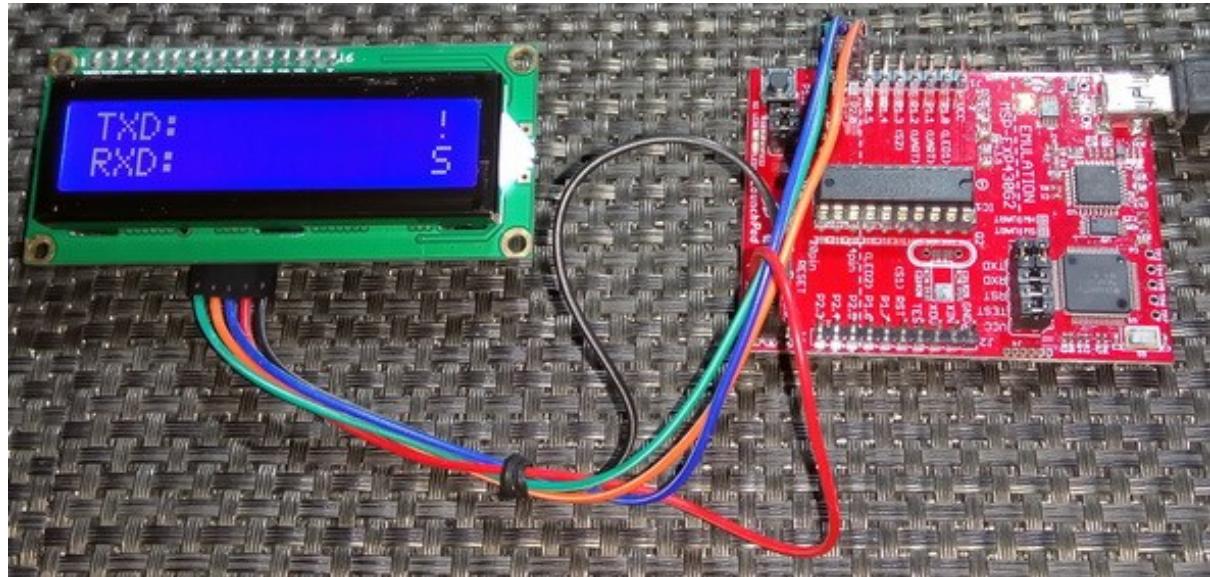
#pragma vector=USCIAB0RX_VECTOR
__interrupt void USCI0RX_ISR_HOOK(void)
{
    rx = UCA0RXBUF;
}

```

Whenever a new character is received by the UART, RX interrupt fires up and catches the sent character. The received character is shown on a LCD. In the main loop, the code sends out ASCII characters and the LCD shows what has been sent out.

CCS IDE comes with a built-in serial terminal interface. You can use that or you can use third-party software like **CoolTerm**, **Putty**, **Termite**, **Docklight**, **RealTerm**, **Tera Term**, etc to check or monitor serial communication transactions.

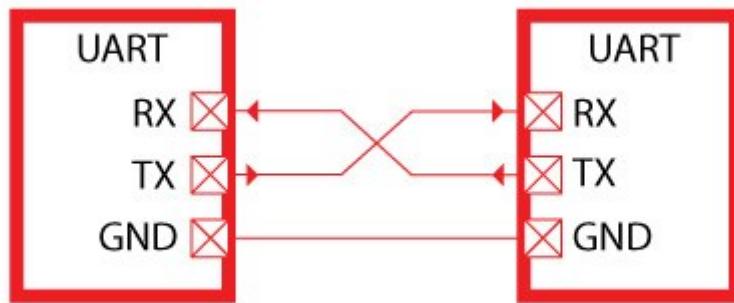
Demo



Demo video: <https://www.youtube.com/watch?v=Mm2i4rVGyoo>.

Software UART

Software UART is seldom needed but it comes really useful in absence of hardware UART. In some cases, we may not have the luxury of using hardware UART. Hardware UART block may also be absent. We already know that USCI module can be used for implementing hardware UART but this block is not present in chips like MSP430G2452. In such devices, we have to use software-generated UART. Software UART uses ordinary digital I/Os and delays. Both additionally and optionally external interrupts and timers can be used for better results. Owing to its hardware independency and simplicity, it is very robust. However extra coding and therefore extra memory spaces are needed.



Code Example

SW_UART.h

```
#include <msp430.h>
#include "delay.h"

#define SW_UART_RXD_DIR          P1DIR
#define SW_UART_TXD_DIR          P1DIR
#define SW_UART_RXD_OUT          P1OUT
#define SW_UART_TXD_OUT          P1OUT
#define SW_UART_RXD_IN           P1IN
#define SW_UART_RXD_IN_RES       P1REN

#define SW_UART_RXD_PIN          BIT1
#define SW_UART_TXD_PIN          BIT2

#define SW_UART_RXD_DIR_IN()     do{SW_UART_RXD_OUT |= SW_UART_RXD_PIN; \
SW_UART_RXD_DIR &= ~SW_UART_RXD_PIN; SW_UART_RXD_IN_RES |= \
SW_UART_RXD_PIN;}while(0)

#define SW_UART_TXD_DIR_OUT()    do{SW_UART_TXD_DIR |= SW_UART_TXD_PIN;}while(0)

#define SW_UART_TXD_OUT_HIGH()   do{SW_UART_TXD_OUT |= SW_UART_TXD_PIN;}while(0)
#define SW_UART_TXD_OUT_LOW()    do{SW_UART_TXD_OUT &= ~SW_UART_TXD_PIN;}while(0)

#define SW_UART_RXD_INPUT()      (SW_UART_RXD_IN & SW_UART_RXD_PIN)
```

```

#define baudrate          4800
#define no_of_bits        8
#define one_bit_delay     (1000000 / baudrate)
#define half_bit_delay    (one_bit_delay / 2)

void SW_UART_init(void);
void SW_UART_transmit(unsigned char value);
unsigned char SW_UART_receive(void);

```

SW_UART.c

```

#include "SW_UART.h"

void SW_UART_init(void)
{
    SW_UART_TXD_DIR_OUT();
    SW_UART_RXD_DIR_IN();
    SW_UART_TXD_OUT_HIGH();
    delay_ms(10);
}

void SW_UART_transmit(unsigned char value)
{
    unsigned char bits = 0;

    SW_UART_TXD_OUT_LOW();
    delay_us(one_bit_delay);

    for(bits = 0; bits < no_of_bits; bits++)
    {
        if((value >> bits) & 0x01)
        {
            SW_UART_TXD_OUT_HIGH();
        }
        else
        {
            SW_UART_TXD_OUT_LOW();
        }
        delay_us(one_bit_delay);
    };

    SW_UART_TXD_OUT_HIGH();
    delay_us(one_bit_delay);
}

unsigned char SW_UART_receive(void)
{
    unsigned char bits = 0;
    unsigned char value = 0;

    while(SW_UART_RXD_INPUT());
}

```

```

delay_us(one_bit_delay);
delay_us(half_bit_delay);

for(bits = 0; bits < no_of_bits; bits++)
{
    if(SW_UART_RXD_INPUT())
    {
        value += (1 << bits);
    }

    delay_us(one_bit_delay);
};

if(SW_UART_RXD_INPUT())
{
    delay_us(half_bit_delay);

    return value;
}

else
{
    delay_us(half_bit_delay);

    return 0;
}
}

```

main.c

```

#include <msp430.h>
#include "delay.h"
#include "SW_I2C.h"
#include "PCF8574.h"
#include "lcd.h"
#include "SW_UART.h"

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void System_graceInit(void);
void WDTplus_graceInit(void);

void main(void)
{
    unsigned char rx_value = 0x00;
    unsigned char tx_value = 0x20;

    /* Stop watchdog timer from timing out during initial start-up. */
    WDTCTL = WDTPW | WDTHOLD;

    /* initialize Config for the MSP430 GPIO */
    GPIO_graceInit();

    /* initialize Config for the MSP430 2xx family clock systems (BCS) */
    BCSplus_graceInit();
}

```

```

/* initialize Config for the MSP430 System Registers */
System_graceInit();

/* initialize Config for the MSP430 WDT+ */
WDTplus_graceInit();

LCD_init();
LCD_clear_home();

LCD_goto(0, 0);
LCD_putstr("TXD:");
LCD_goto(0, 1);
LCD_putstr("RXD:");

SW_UART_init();

while(1)
{
    rx_value = SW_UART_receive();
    LCD_goto(15, 0);
    LCD_putchar(rx_value);
    tx_value++;
    LCD_goto(15, 1);
    LCD_putchar(tx_value);
    SW_UART_transmit(tx_value);
    delay_ms(200);
}
}

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Direction Register */
    P1DIR = 0;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;
}

```

```

/* USER CODE START (section: GPIO0_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO0_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF) {
        /* Adjust this accordingly to your VCC rise time */
        __delay_cycles(100000);

        // Follow recommended flow. First, clear all DC0x and MODx bits. Then
        // apply new RSELx values. Finally, apply new DC0x and MODx bit values.
        DCOCTL = 0x00;
        BCSCTL1 = CALBC1_8MHZ;      /* Set DCO to 8MHz */
        DCOCTL = CALDCO_8MHZ;
    }

    /*
     * Basic Clock System Control 1
     *
     * XT2OFF -- Disable XT2CLK
     * ~XTS -- Low Frequency
     * DIVA_0 -- Divide by 1
     *
     * Note: ~XTS indicates that XTS has value zero
     */
    BCSCTL1 |= XT2OFF | DIVA_0;

    /*
     * Basic Clock System Control 3
     *
     * XT2S_0 -- 0.4 - 1 MHz
     * LFXT1S_0 -- If XTS = 0, XT1 = 32768kHz Crystal ; If XTS = 1, XT1 = 0.4 - 1-
MHz crystal or resonator
     * XCAP_1 -- ~6 pF
     */
    BCSCTL3 = XT2S_0 | LFXT1S_0 | XCAP_1;
}

```

```

/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void System_graceInit(void)
{
    /* USER CODE START (section: System_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: System_graceInit_prologue) */

    /*
     * SR, Status Register
     *
     * ~SCG1 -- Disable System clock generator 1
     * ~SCG0 -- Disable System clock generator 0
     * ~OSCOFF -- Oscillator On
     * ~CPUOFF -- CPU On
     * GIE -- General interrupt enable
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    _bis_SR_register(GIE);

    /* USER CODE START (section: System_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: System_graceInit_epilogue) */
}

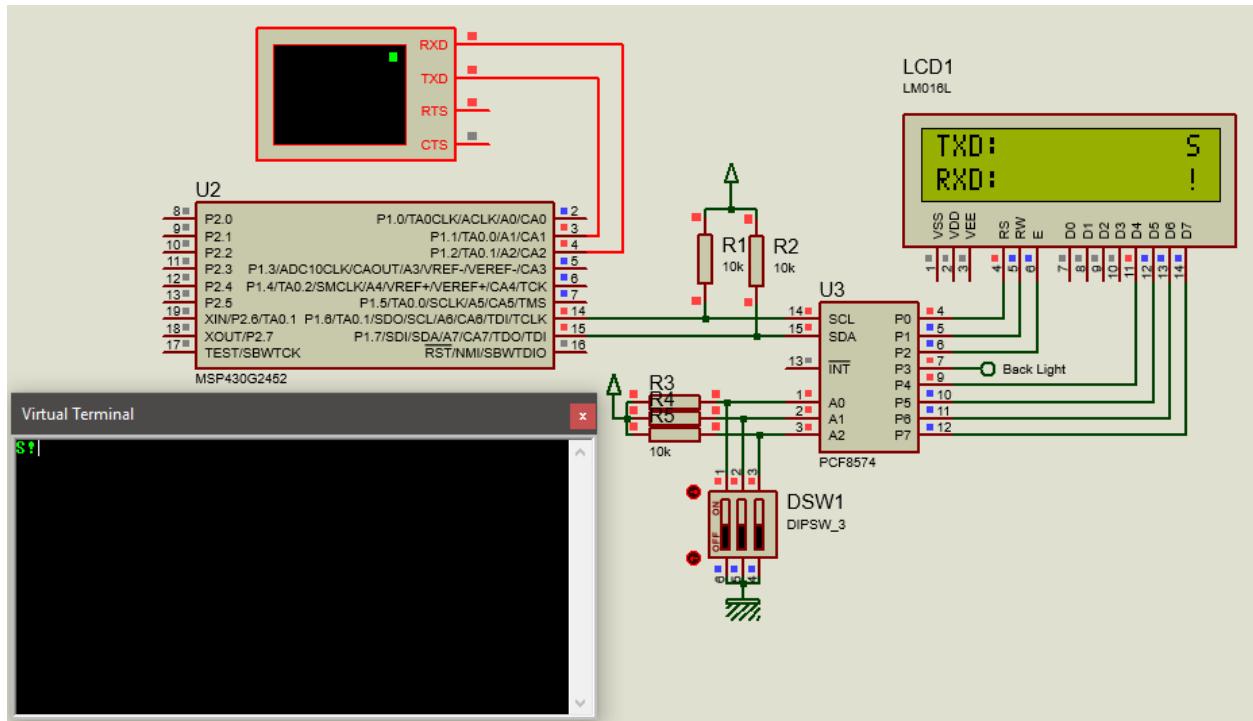
void WDTplus_graceInit(void)
{
    /* USER CODE START (section: RTC_B_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: RTC_B_graceInit_prologue) */

    /*
     * WDTCTL, Watchdog Timer+ Register
     *
     * WDTPW -- Watchdog password
     * WDTHOLD -- Watchdog timer+ is stopped
     * ~WDTNMIES -- NMI on rising edge
     * ~WDTNMI -- Reset function
     * ~WDTTMSEL -- Watchdog mode
     * ~WDTCNTCL -- No action
     * ~WDTSSEL -- SMCLK
     * ~WDTIS0 -- Watchdog clock source bit0 disabled
     * ~WDTIS1 -- Watchdog clock source bit1 disabled
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    WDTCTL = WDTPW | WDTHOLD;

    /* USER CODE START (section: RTC_B_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: RTC_B_graceInit_epilogue) */
}

```

Simulation



Explanation

Software UART is created with digital I/Os. Thus, the very first task we need to do is to initialize these pins. The SW_UART header file states which pins and ports are used. So, you only need to set these first. All of my codes are modular and so once you set these properly the functions and the definitions associated take care of other tasks. This, in turn, makes the codes easily to use and ready for quick modifications/deployments.

```
#define SW_UART_RXD_DIR          P1DIR
#define SW_UART_TXD_DIR          P1DIR
#define SW_UART_RXD_OUT          P1OUT
#define SW_UART_TXD_OUT          P1OUT
#define SW_UART_RXD_IN           P1IN
#define SW_UART_RXD_IN_RES       P1REN

#define SW_UART_RXD_PIN           BIT1
#define SW_UART_TXD_PIN           BIT2
```

Once the pins are set as per requirement, it is needed to initialize them for software UART functionality.

```
void SW_UART_init(void)
{
    SW_UART_TXD_DIR_OUT();
    SW_UART_RXD_DIR_IN();
    SW_UART_TXD_OUT_HIGH();
    delay_ms(10);
}
```

The header file also states the communication baud rate and number of bits:

```
#define baudrate          4800
#define no_of_bits         8
#define one_bit_delay     (1000000 / baudrate)
#define half_bit_delay    (one_bit_delay / 2)
```

Based on the baud rate further timing infos are calculated. Software UART is not as reliable as hardware UART and so it is better to use low baud rates. It is even better if it can be skipped. However, when there is no other option or when there is a need for additional UART, it must be used.

The UART transmit and receive functions are written using polling methods. External digital I/O interrupt can be used for receiving data. These functions are created just by studying the signal patterns and using the same tactics as with other software communication libraries. The trick is to emulate/receive the signals as a real hardware would do.

```
void SW_UART_transmit(unsigned char value)
{
    unsigned char bits = 0;

    SW_UART_TXD_OUT_LOW();
    delay_us(one_bit_delay);

    for(bits = 0; bits < no_of_bits; bits++)
    {
        if((value >> bits) & 0x01)
        {
            SW_UART_TXD_OUT_HIGH();
        }
        else
        {
            SW_UART_TXD_OUT_LOW();
        }

        delay_us(one_bit_delay);
    };

    SW_UART_TXD_OUT_HIGH();
    delay_us(one_bit_delay);
}

unsigned char SW_UART_receive(void)
{
    unsigned char bits = 0;
    unsigned char value = 0;

    while(SW_UART_RXD_INPUT());
    delay_us(one_bit_delay);
    delay_us(half_bit_delay);

    for(bits = 0; bits < no_of_bits; bits++)
    {
        if(SW_UART_RXD_INPUT())
        {
            value += (1 << bits);
        }
    }
}
```

```
    delay_us(one_bit_delay);
};

if(SW_UART_RXD_INPUT())
{
    delay_us(half_bit_delay);

    return value;
}

else
{
    delay_us(half_bit_delay);

    return 0;
}
}
```

Demo

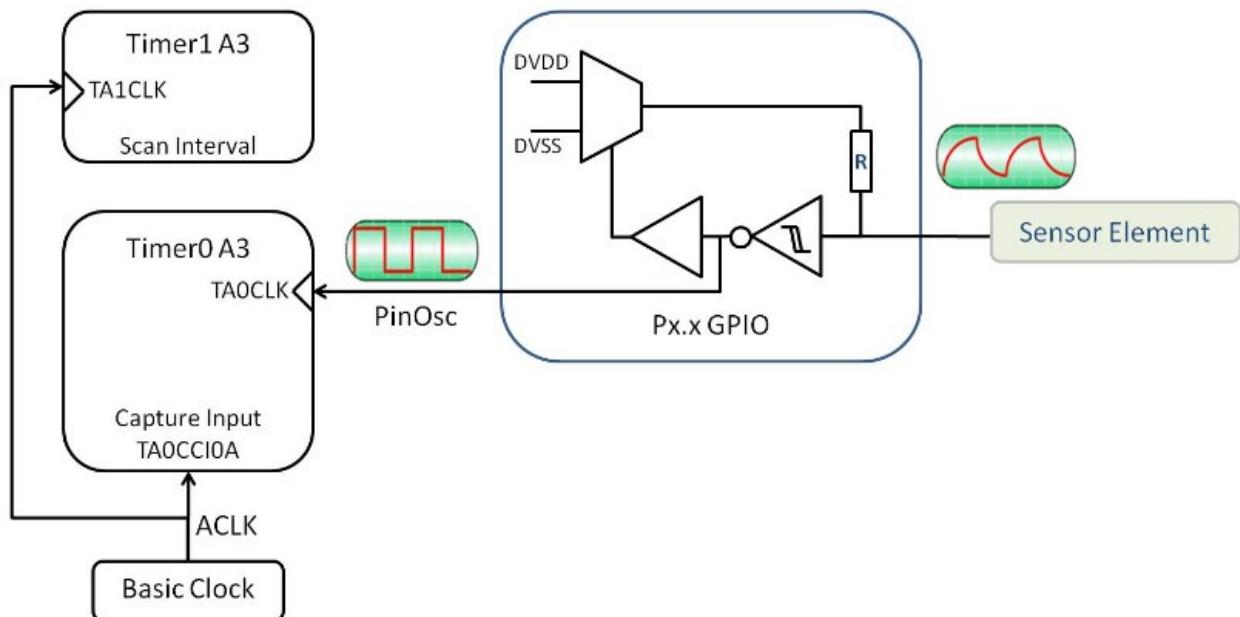


Demo video: https://youtu.be/AZIA7_Ydxww.

Capacitive Touch Overview

Capacitive touch sensing technology is nothing new at present. Cell phones, smartwatches, tablets, portable music players, and even many home appliances that you can name no longer have mechanical touch keys/switches/buttons/variables. All such switching elements have been replaced by more smart and elegant capacitive touch sensors. At present due to this trend even the tiniest new generation microcontroller has capacitive touch sensing capability. When it comes to TI micros, this trend seems to explode to a whole new level.

I haven't seen so far, any TI MCU without capacitive touch feature. Almost all digital I/Os can be used for capacitive touch as there is no specific dedicated I/Os for such implementations. This makes capacitive touch sensing easy in terms of hardware design. Designing capacitive touch sensors is another story.



In MSP430s, capacitive touch sensing requires two separate timers. These timers create independent time bases and these time bases are compared against each other. One of these time bases is fixed while the other is dependent of the value of touch sensor's capacitance. When a touch is detected, capacitance changes. This creates a significant difference between the time bases which otherwise remains fairly constant. This is how a touch is detected. This is also a mean to measure capacitance other than touch sensing.

For making all these tasks simple and for rapid development, TI has provided a dedicated **Hardware Abstraction Layer (HAL)** library for capacitive touch sensing. Use TI's Resource Explorer to download code examples and library files. Programmer's Guide [SLAA490D](#) discusses implementation of capacitive touch sensing in terms of coding, hardware combinations and others. This [page](#) is also an equally important one. Apart from these, there are good literatures from TI that discuss tons of valuable info about capacitive touch sensing technology – from hardware designs to implementation methods.

TI discusses about three methods with which capacitive touch sensing can be achieved. These methods are as follows:

- **Relaxation Oscillator (RO)**

This method counts the number of relaxation oscillator cycles within a fixed period called gate time. Usually for the Value-Line Devices (VLD), the [PinOsc](#) feature is used in this method and the key thing to note here is the fact that no external components like external resistors or capacitors are needed to implement capacitive touch sensors. It is this method that we will be observing in this article as our target devices are VLDs.

- **Resistor Capacitor (RC)**

This method is just the opposite of RO method. In this method, the gate time is variable as it is the representation of capacitance while the oscillator time period is fixed. The fixed time base is connected to an internal MSP430 oscillator like the DCO. The variable time base is connected to a capacitor and resistor network. The time it takes to charge and discharge the capacitor through the resistor is now the gate time. The RC method can be realized with any MSP430.

- **Fast Relaxation Oscillator (fRO)**

This method is similar to the RC method except that the variable gate period is created with a relaxation oscillator instead of the charge and discharge time.

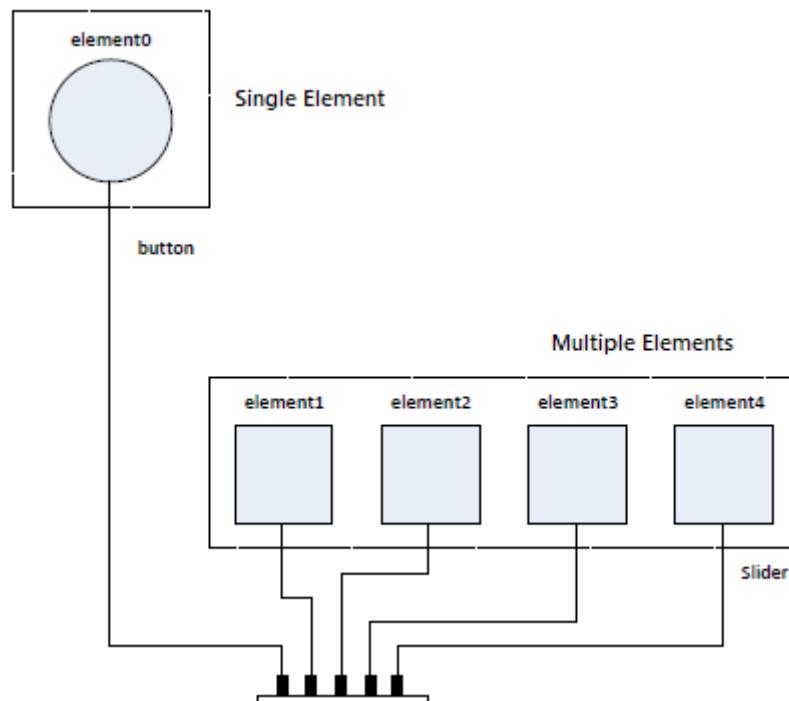
TI's capacitive touch library documentation also recommends which hardware combination to use for a given family of MSP430 microcontroller. Though these are not mandatory, following these recommended combinations reduces code development time and best performances.

Devices	HALs
G2xx2	RO_PINOSC_TA0_WDTp
G2xx3	RO_PINOSC_TA0_WDTp
	fRO_PINOSC_TA0_TA1
G2xx5	RO_PINOSC_TA1_WDTp
	fRO_PINOSC_TA1_TB0
F51xx	RO_COMPB_TA0_WDTA
F52xx	RO_COMPB_TA1_WDTA
	fRO_COMPB_TA1_TA0
FR4xx	fRO_CSIO_TA0_TA1 RO_CSIO_TA0_RTC
F55xx	RO_COMPB_TA1_WDTA
	fRO_COMPB_TA1_TA0
FR58xx and FR59xx	RO_CSIO_TA2_WDTA
	fRO_CSIO_TA2_TA3

I don't have TI's Capacitive Touch Boosterpack and so I had to make the capacitive touch sensors on my own. I wish I had such a boosterpack because the rudimentary way with which I made the capacitive sensors quickly is certainly not the best way to follow. I used just bare PCBs, jumper cables and transparent scotch tape. I highly recommend not to use this technique for professional works.

Single-Channel Capacitive Touch

This is the very first capacitive touch example we will look at. Although a single capacitive touch button has very little use in real life, it is good for realizing the mechanism behind this capacitive touch technology. If this example is well understood then everything related to capacitive touch sensing will be realized without any confusion or doubt.



Code Example

structure.h (top part only)

```
#ifndef CTS_STRUCTURE_H_
#define CTS_STRUCTURE_H_

#include "msp430.h"
#include <stdint.h>

/* Public Globals */

// Middle Element on the LaunchPad Capacitive Touch BoosterPack
extern const struct Element middle_element;
// One Button Sensor
extern const struct Sensor one_button;

//***** RAM ALLOCATION *****
// TOTAL_NUMBER_OF_ELEMENTS represents the total number of elements used, even if
// they are going to be segmented into separate groups. This defines the
// RAM allocation for the baseline tracking. If only the TI_CAPT_Raw function
// is used, then this definition should be removed to conserve RAM space.
```

```

#define TOTAL_NUMBER_OF_ELEMENTS 1
// If the RAM_FOR_FLASH definition is removed, then the appropriate HEAP size
// must be allocated. 2 bytes * MAXIMUM_NUMBER_OF_ELEMENTS_PER_SENSOR + 2 bytes
// of overhead.
#define RAM_FOR_FLASH
***** Structure Array Definition *****
// This defines the array size in the sensor strucure. In the event that
// RAM_FOR_FLASH is defined, then this also defines the amount of RAM space
// allocated (global variable) for computations.
#define MAXIMUM_NUMBER_OF_ELEMENTS_PER_SENSOR 1
***** Choosing a Measurement Method *****
// These variables are references to the definitions found in structure.c and
// must be generated per the application.
// possible values for the method field

// OSCILLATOR DEFINITIONS
#define RO_COMPAp_TA0_WDTp 64
#define RO_PINOSC_TA0_WDTp 65
...

```

structure.c

```

#include "structure.h"

// Middle Element (P2.5)
const struct Element middle_element =
{
    .inputPxselRegister = (uint8_t *)&P2SEL,
    .inputPxsel2Register = (uint8_t *)&P2SEL2,
    .inputBits = BIT4,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (450 + 655),
    .threshold = 450
};

// One Button Sensor
const struct Sensor one_button =
{
    .halDefinition = RO_PINOSC_TA0_WDTp,    // Sensing Method
    .numElements = 1,                         // # of Elements
    .baseOffset = 0,                           // First element index = 0
    // Pointer to elements
    .arrayPtr[0] = &middle_element,          // point to middle element
    // Timer Information
    .measGateSource= GATE_WDT_ACLK,           // 0->SMCLK, 1-> ACLK
    .accumulationCycles= WDTp_GATE_64        //64 - Default
};

```

main.c

```

#include <msp430.h>
#include "CTS_Layer.h"
#include "CTS_HAL.h"
#include "structure.h"

```

```

#define DELAY 4000

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void sleep(unsigned int time);

#pragma vector = TIMER0_A0_VECTOR
__interrupt void ISR_Timer0_A0(void)
{
    TA0CTL &= ~MC_1;
    TA0CCTL0 &= ~(CCIE);
    __bic_SR_register_on_exit(LPM3_bits + GIE);
}

#pragma vector = PORT2_VECTOR,
PORT1_VECTOR,                                \
TIMER0_A1_VECTOR,                            \
USI_VECTOR,                                 \
NMI_VECTOR,COMPARATORA_VECTOR,              \
ADC10_VECTOR                                \
__interrupt void ISR_trap(void)
{
    // the following will cause an access violation which results in a PUC reset
    WDTCTL = 0;
}

// Main Function
void main(void)
{
    WDTCTL = WDTPW + WDTHOLD;                  // Stop watchdog timer

    GPIO_graceInit();
    BCSplus_graceInit();

    TI_CAPT_Init_Baseline(&one_button);
    TI_CAPT_Update_Baseline(&one_button, 6);

    while (1)
    {
        if(TI_CAPT_Button(&one_button))
        {
            P1OUT ^= BIT0;
            P1OUT |= BIT6;
        }

        else
        {
            P1OUT &= ~BIT6;
        }

        sleep(DELAY);
    }
}

```

```

} // End Main

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;

    /* Port 1 Direction Register */
    P1DIR = BIT0 | BIT6;

    /* Port 1 Interrupt Edge Select Register */
    P1IES = 0;

    /* Port 1 Interrupt Flag Register */
    P1IFG = 0;

    /* Port 2 Output Register */
    P2OUT = 0;

    /* Port 2 Port Select Register */
    P2SEL &= ~BIT6 | BIT7;

    /* Port 2 Direction Register */
    P2DIR = 0;

    /* Port 2 Interrupt Edge Select Register */
    P2IES = 0;

    /* Port 2 Interrupt Flag Register */
    P2IFG = 0;

    /* USER CODE START (section: GPIO_graceInit_epilogue) */
    /* User code */
    /* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_3 -- Divide by 8
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
    */
}

```

```

/*
BCSCTL2 = SELM_0 | DIVM_0 | DIVS_3;

if (CALBC1_12MHZ != 0xFF) {
    /* Adjust this accordingly to your VCC rise time */
    _delay_cycles(100000);

    /* Follow recommended flow. First, clear all DCOx and MODx bits. Then
     * apply new RSELx values. Finally, apply new DCOx and MODx bit values.
     */
    DCOCTL = 0x00;
    BCSCTL1 = CALBC1_12MHZ;      /* Set DCO to 12MHz */
    DCOCTL = CALDCO_12MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

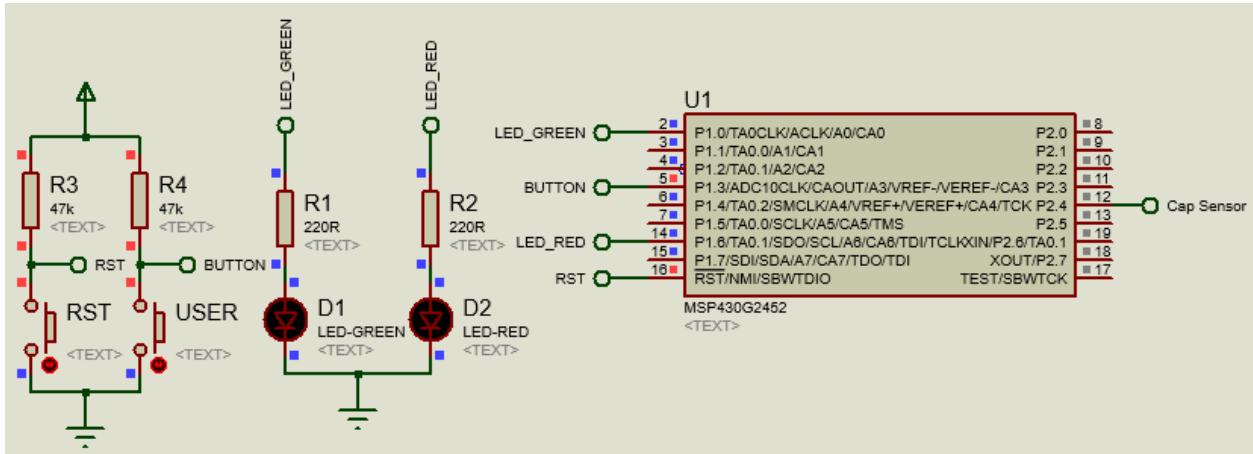
/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void sleep(unsigned int time)
{
    TA0CCR0 = time;
    TA0CTL = TASSEL_1 | ID_0 | MC_1 | TACLR;
    TA0CCTL0 &= ~CCIFG;
    TA0CCTL0 |= CCIE;
    _bis_SR_register(LPM3_bits+GIE);
    _no_operation();
}

```

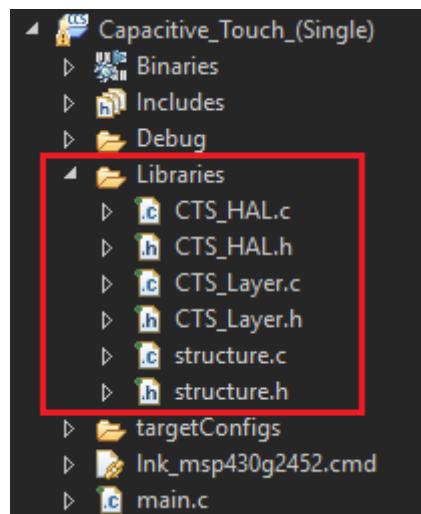
Simulation

Capacitive touch sensing cannot be simulated in software like Proteus VSM.



Explanation

In Grace, there is no option to generate configuration for capacitive touch. However, MSP430Ware demos some examples for such. It is better to use the examples given there for project start up. I did the same. However, for a beginner it is must to which things to modify and why do so. Implementing capacitive touch requires three pairs of TI's HAL library files. These are as follows and are needed to be integrated with your project:



Of these files, the important files that are needed to be edited to set capacitive touch properties of capacitive touch sensor(s) are the **structure** header and source files. The rest two pairs of files should be left untouched.

In the structure header file, external constant structure named **middle_element** defines I/O port(s) properties of capacitive sensor(s). Similarly, **one_button** defines timer/watchdog properties. These

two external structures have other functions too. We will see these properties when we will discuss the source file. Next, we have to define how many capacitive touch sensors are there in our design. Finally, we have to set which hardware combination to use. In our case, Timer0_A, watchdog timer and digital I/O's PinOsc functionality are used to implement capacitive touch. The rest of the file is not needed to be changed anywhere.

```
// Middle Element on the LaunchPad Capacitive Touch BoosterPack
extern const struct Element middle_element;
// One Button Sensor
extern const struct Sensor one_button;

***** RAM ALLOCATION *****
// TOTAL_NUMBER_OF_ELEMENTS represents the total number of elements used, even if
// they are going to be segmented into separate groups. This defines the
// RAM allocation for the baseline tracking. If only the TI_CAPT_Raw function
// is used, then this definition should be removed to conserve RAM space.
#define TOTAL_NUMBER_OF_ELEMENTS 1
// If the RAM_FOR_FLASH definition is removed, then the appropriate HEAP size
// must be allocated. 2 bytes * MAXIMUM_NUMBER_OF_ELEMENTS_PER_SENSOR + 2 bytes
// of overhead.
#define RAM_FOR_FLASH
***** Structure Array Definition *****
// This defines the array size in the sensor structure. In the event that
// RAM_FOR_FLASH is defined, then this also defines the amount of RAM space
// allocated (global variable) for computations.
#define MAXIMUM_NUMBER_OF_ELEMENTS_PER_SENSOR 1
***** Choosing a Measurement Method *****
// These variables are references to the definitions found in structure.c and
// must be generated per the application.
// possible values for the method field

// OSCILLATOR DEFINITIONS
#ifndef RO_COMPAp_TA0_WDTp          64
#define RO_PINOSC_TA0_WDTp           65
```

Now it is time to explain the structure source file.

```
const struct Element middle_element =
{
    .inputPxselRegister = (uint8_t *)&P2SEL,
    .inputPxsel2Register = (uint8_t *)&P2SEL2,
    .inputBits = BIT4,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (450 + 655),
    .threshold = 450
};
```

PxSEL and **PxSEL2** bits internally set PinOsc feature. Since this example demonstrated one capacitive touch button only one element is connected to **BIT4** of port **P2**. Optionally, we can set the threshold limit on which we can positively identify a touch.

```
// One Button Sensor
const struct Sensor one_button =
```

```

{
    .halDefinition = RO_PINOSC_TA0_WDTp, // Sensing Method
    .numElements = 1,                  // # of Elements
    .baseOffset = 0,                  // First element index = 0
    // Pointer to elements
    .arrayPtr[0] = &middle_element,   // point to middle element
    // Timer Information
    .measGateSource= GATE_WDT_ACLK,   // 0->SMCLK, 1-> ACLK
    .accumulationCycles= WDTp_GATE_64 //64 - Default
};

```

The second part of the source file details which method is used along with the name and number of element(s) to sense. Basically, here we have nothing to do other than to let this part know the structure name of our element(s) and the number of sensors.

```

#pragma vector = TIMER0_A0_VECTOR
__interrupt void ISR_Timer0_A0(void)
{
    TA0CTL &= ~MC_1;
    TA0CCTL0 &= ~(CCIE);
    __bic_SR_register_on_exit(LPM3_bits + GIE);
}

#pragma vector = PORT2_VECTOR,
    PORT1_VECTOR,                                \
    TIMER0_A1_VECTOR,                            \
    USI_VECTOR,                                 \
    NMI_VECTOR,COMPARATORA_VECTOR,             \
    ADC10_VECTOR                                \
__interrupt void ISR_trap(void)
{
    // the following will cause an access violation which results in a PUC reset
    WDTCTL = 0;
}

```

Two interrupts are needed to be called. The first is the Timer0_A ISR. This acts like a wakeup alarm. Once the capacitive sensing and other tasks in the main loop are completed, this timer is started and low power mode is entered. After timeout, this timer interrupts causing the main tasks to reoccur and leave low power mode momentarily. The second is a Trap ISR. Trap ISR ensures that if for some reason something happens that you didn't expect it will reset the MCU. The interrupt vectors assigned here are those vectors which we won't be using. If any of these pop-up, a reset will occur.

```

void main(void)
{
    WDTCTL = WDTPW + WDTHOLD;                  // Stop watchdog timer

    GPIO_graceInit();
    BCSpplus_graceInit();

    TI_CAPT_Init_Baseline(&one_button);
    TI_CAPT_Update_Baseline(&one_button, 6);

    while (1)
    {
        if(TI_CAPT_Button(&one_button))

```

```

    {
        P1OUT ^= BIT0;
        P1OUT |= BIT6;
    }

    else
    {
        P1OUT &= ~BIT6;
    }

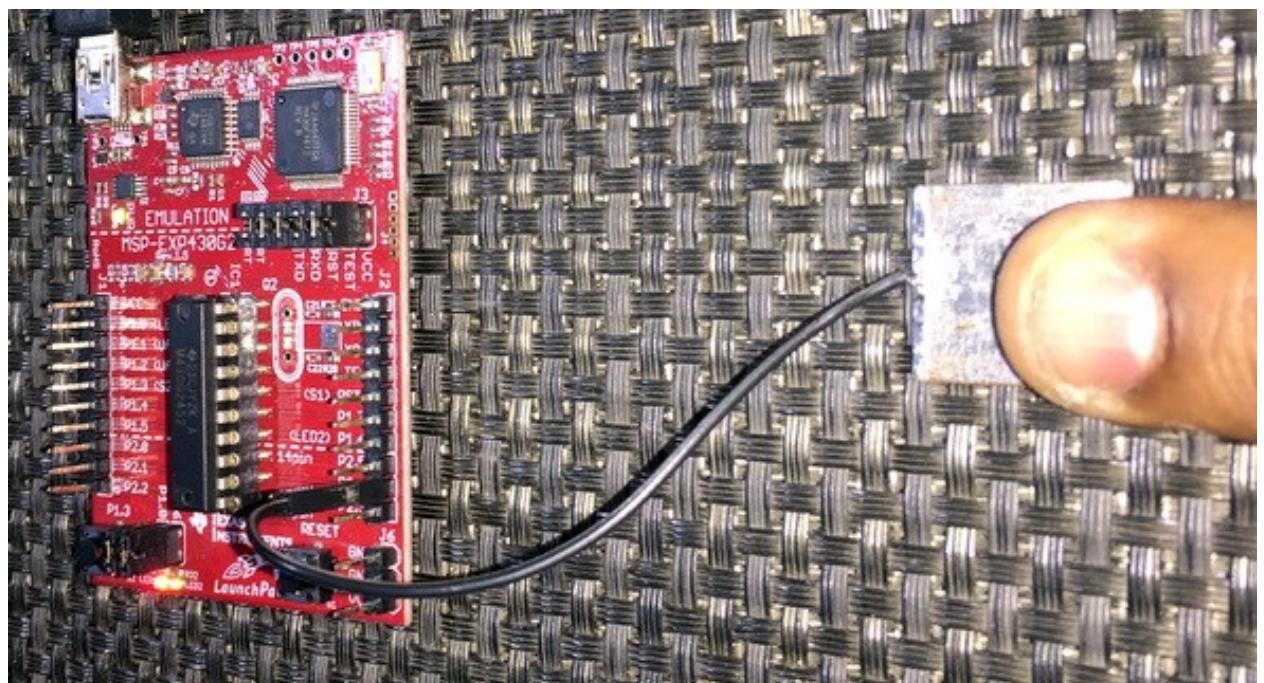
    sleep(DELAY);

}

```

The main function is perhaps the smallest one here. Except for the other parts with which by now we are familiar, there are a few new lines of code. Just before the main loop, the two lines of code right above it, initialize the capacitive touch sensor. Number 6 in the function ***TI_CAPT_Update_Baseline*** states the number of samples to capture for accurately sensing a touch. If a valid touch is detected, the LEDs of Launchpad board are toggled.

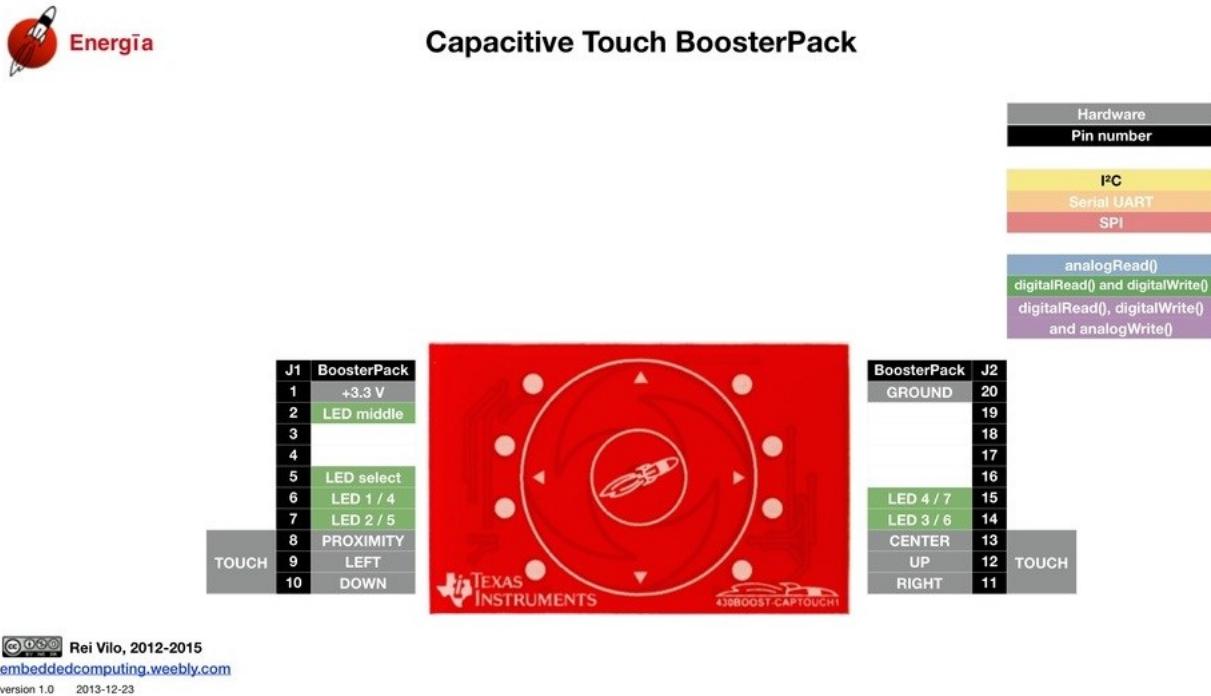
Demo



Demo video: <https://youtu.be/sh8nk0l2XKw>.

Multi-Channel Capacitive Touch

Unlike single capacitive touch buttons, multiple capacitive sensors have several potential uses. These include multi-touch buttons, sliders, wheels, rotary encoders, etc. Here we will have a look at multiple capacitive touch buttons and the example demonstrated here is basically the extension of the last one. However, for multi-touch capacitive touch sensors, there are twists in the software end apart from hardware design and considerations.



Code Example

structure.h (top part only)

```
#ifndef CTS_STRUCTURE_H_
#define CTS_STRUCTURE_H_

#include "msp430.h"
#include <stdint.h>

/* Public Globals */
extern const struct Element middle_element;
extern const struct Element up_element;
extern const struct Element down_element;

// Identify all sensors defined in structure.c
extern const struct Sensor multi_buttons;

//***** RAM ALLOCATION *****
// TOTAL_NUMBER_OF_ELEMENTS represents the total number of elements used, even if
// they are going to be segmented into separate groups. This defines the
// RAM allocation for the baseline tracking. If only the TI_CAPT_Raw function
```

```

// is used, then this definition should be removed to conserve RAM space.
#define TOTAL_NUMBER_OF_ELEMENTS 3
// If the RAM_FOR_FLASH definition is removed, then the appropriate HEAP size
// must be allocated. 2 bytes * MAXIMUM_NUMBER_OF_ELEMENTS_PER_SENSOR + 2 bytes
// of overhead.
#define RAM_FOR_FLASH
***** Structure Array Definition *****
// This defines the array size in the sensor structure. In the event that
// RAM_FOR_FLASH is defined, then this also defines the amount of RAM space
// allocated (global variable) for computations.
#define MAXIMUM_NUMBER_OF_ELEMENTS_PER_SENSOR 3
***** Choosing a Measurement Method *****
// These variables are references to the definitions found in structure.c and
// must be generated per the application.
// possible values for the method field

// OSCILLATOR DEFINITIONS
#ifndef RO_COMPAp_TAO_WDTp          64
#define RO_PINOSC_TAO_WDTp           65
...

```

structure.c

```

#include "structure.h"

// Middle Element (P2.5)
const struct Element middle_element = {

    .inputPxselRegister = (unsigned char *)&P2SEL,
    .inputPxsel2Register = (unsigned char *)&P2SEL2,
    .inputBits = BIT5,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (100 + 655),
    .threshold = 100
};

// Up Element (P2.4)
const struct Element up_element = {

    .inputPxselRegister = (unsigned char *)&P2SEL,
    .inputPxsel2Register = (unsigned char *)&P2SEL2,
    .inputBits = BIT4,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (100 + 655),
    .threshold = 100
};

// Down Element (P2.3)
const struct Element down_element =
{
    .inputPxselRegister = (unsigned char *)&P2SEL,
    .inputPxsel2Register = (unsigned char *)&P2SEL2,

```

```

    .inputBits = BIT3,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (100 + 655),
    .threshold = 100
};

//*** CAP TOUCH HANDLER *****/
// This defines the grouping of sensors, the method to measure change in
// capacitance, and the function of the group

const struct Sensor multi_buttons =
{
    .halDefinition = RO_PINOSC_TA0_WDTp,
    .numElements = 3,
    .baseOffset = 0,
    // Pointer to elements
    .arrayPtr[0] = &up_element,           // point to up element
    .arrayPtr[1] = &down_element,         // point to down element
    .arrayPtr[2] = &middle_element,        // point to middle element
    // Timer Information
    .measGateSource= GATE_WDT_ACLK,      // 0->SMCLK, 1-> ACLK
    .accumulationCycles= WDTp_GATE_64   //64 - Default
};

```

main.c

```

#include <msp430.h>
#include "CTS_Layer.h"
#include "CTS_HAL.h"
#include "structure.h"

#define DELAY 4000

struct Element * keyPressed;

void GPIO_graceInit(void);
void BCSplus_graceInit(void);
void sleep(unsigned int time);

#pragma vector = TIMER0_A0_VECTOR
__interrupt void ISR_Timer0_A0(void)
{
    TA0CTL &= ~MC_1;
    TA0CCTL0 &= ~(CCIE);
    __bic_SR_register_on_exit(LPM3_bits + GIE);
}

#pragma vector = PORT2_VECTOR,          \
PORT1_VECTOR,                      \
TIMER0_A1_VECTOR,                  \
USI_VECTOR,                         \

```

```

NMI_VECTOR,COMPARATORA_VECTOR,           \
ADC10_VECTOR
__interrupt void ISR_trap(void)
{
    // the following will cause an access violation which results in a PUC reset
    WDTCTL = 0;
}

// Main Function
void main(void)
{
    WDTCTL = WDTPW + WDTHOLD;           // Stop watchdog timer

    GPIO_graceInit();
    BCSplus_graceInit();

    TI_CAPT_Init_Baseline(&multi_buttons);
    TI_CAPT_Update_Baseline(&multi_buttons, 25);

    // Main loop starts here
    while (1)
    {
        keyPressed = (struct Element *)TI_CAPTButtons(&multi_buttons);

        if(keyPressed)
        {
            // Up Element
            if(keyPressed == &up_element)
            {
                P1OUT |= BIT0;
            }
            // Down Element
            if(keyPressed == &down_element)
            {
                P1OUT |= BIT6;
            }
            // Middle Element
            if(keyPressed == &middle_element)
            {
                P1OUT = 0;
            }
        }

        sleep(DELAY);
    }
}

} // End Main

void GPIO_graceInit(void)
{
    /* USER CODE START (section: GPIO_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: GPIO_graceInit_prologue) */

    /* Port 1 Output Register */
    P1OUT = 0;
}

```

```

/* Port 1 Direction Register */
P1DIR = BIT0 | BIT6;

/* Port 1 Interrupt Edge Select Register */
P1IES = 0;

/* Port 1 Interrupt Flag Register */
P1IFG = 0;

/* Port 2 Output Register */
P2OUT = 0;

/* Port 2 Port Select Register */
P2SEL &= ~(BIT6 | BIT7);

/* Port 2 Direction Register */
P2DIR = 0;

/* Port 2 Interrupt Edge Select Register */
P2IES = 0;

/* Port 2 Interrupt Flag Register */
P2IFG = 0;

/* USER CODE START (section: GPIO_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: GPIO_graceInit_epilogue) */

}

void BCSplus_graceInit(void)
{
    /* USER CODE START (section: BCSplus_graceInit_prologue) */
    /* User initialization code */
    /* USER CODE END (section: BCSplus_graceInit_prologue) */

    /*
     * Basic Clock System Control 2
     *
     * SELM_0 -- DCOCLK
     * DIVM_0 -- Divide by 1
     * ~SELS -- DCOCLK
     * DIVS_0 -- Divide by 1
     * ~DCOR -- DCO uses internal resistor
     *
     * Note: ~<BIT> indicates that <BIT> has value zero
     */
    BCSCTL2 = SELM_0 | DIVM_0 | DIVS_0;

    if (CALBC1_8MHZ != 0xFF)
    {
        /* Adjust this accordingly to your VCC rise time */
        delay_cycles(100000);

        // Follow recommended flow. First, clear all DCOx and MODx bits. Then
        // apply new RSELx values. Finally, apply new DCOx and MODx bit values.
        DCOCTL = 0x00;
}

```

```

BCSCTL1 = CALBC1_8MHZ;           /* Set DCO to 8MHz */
DCOCTL = CALDCO_8MHZ;
}

/*
 * Basic Clock System Control 1
 *
 * XT2OFF -- Disable XT2CLK
 * ~XTS -- Low Frequency
 * DIVA_0 -- Divide by 1
 *
 * Note: ~XTS indicates that XTS has value zero
 */
BCSCTL1 |= XT2OFF | DIVA_0;

/*
 * Basic Clock System Control 3
 *
 * XT2S_0 -- 0.4 - 1 MHz
 * LFXT1S_2 -- If XTS = 0, XT1 = VLOCLK ; If XTS = 1, XT1 = 3 - 16-MHz crystal
or resonator
 * XCAP_1 -- ~6 pF
 */
BCSCTL3 = XT2S_0 | LFXT1S_2 | XCAP_1;

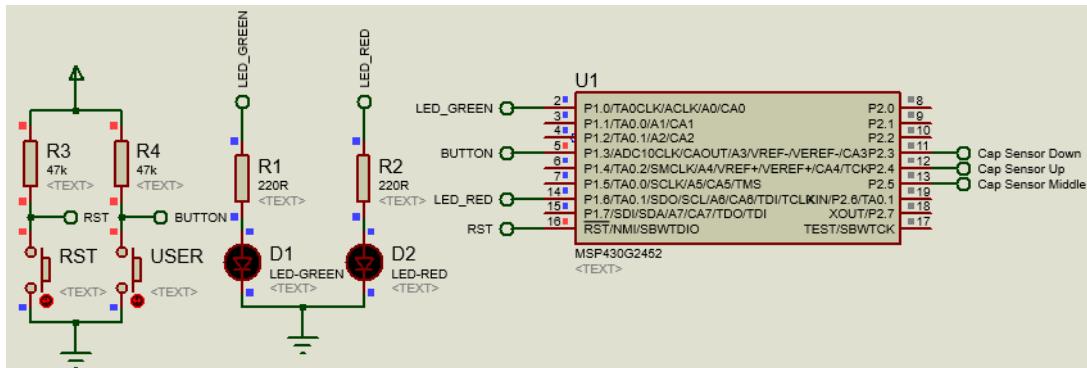
/* USER CODE START (section: BCSplus_graceInit_epilogue) */
/* User code */
/* USER CODE END (section: BCSplus_graceInit_epilogue) */
}

void sleep(unsigned int time)
{
    TA0CCR0 = time;
    TA0CTL = TASSEL_1 | ID_0 | MC_1 | TACLR;
    TA0CCTL0 &= ~CCIFG;
    TA0CCTL0 |= CCIE;
    __bis_SR_register(LPM3_bits + GIE);
    __no_operation();
}

```

Simulation

Capacitive touch sensing cannot be simulated in software like Proteus VSM.



Explanation

This example uses the same ideas as in the previous example. The header file is slightly modified. Three sensor elements are used and so the number of sensor is set 3. The elements are named differently since each are independent of the other.

```
extern const struct Element middle_element;
extern const struct Element up_element;
extern const struct Element down_element;

// Identify all sensors defined in structure.c
extern const struct Sensor multi_buttons;

//***** RAM ALLOCATION *****
// TOTAL_NUMBER_OF_ELEMENTS represents the total number of elements used, even if
// they are going to be segmented into separate groups. This defines the
// RAM allocation for the baseline tracking. If only the TI_CAPT_Raw function
// is used, then this definition should be removed to conserve RAM space.
#define TOTAL_NUMBER_OF_ELEMENTS 3

...
//***** Structure Array Definition *****
// This defines the array size in the sensor structure. In the event that
// RAM_FOR_FLASH is defined, then this also defines the amount of RAM space
// allocated (global variable) for computations.
#define MAXIMUM_NUMBER_OF_ELEMENTS_PER_SENSOR 3
```

The main difference is present in the structure source file. The three different elements are declared independently despite being in the same port. This is so because we need to identify them when a touch is detected.

```
const struct Element middle_element = {

    .inputPxselRegister = (unsigned char *)&P2SEL,
    .inputPxsel2Register = (unsigned char *)&P2SEL2,
    .inputBits = BIT5,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (100 + 655),
    .threshold = 100
};

// Up Element (P2.4)
const struct Element up_element = {

    .inputPxselRegister = (unsigned char *)&P2SEL,
    .inputPxsel2Register = (unsigned char *)&P2SEL2,
    .inputBits = BIT4,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (100 + 655),
    .threshold = 100
};

// Down Element (P2.3)
```

```

const struct Element down_element =
{
    .inputPxselRegister = (unsigned char *)&P2SEL,
    .inputPxsel2Register = (unsigned char *)&P2SEL2,
    .inputBits = BIT3,
    // When using an abstracted function to measure the element
    // the 100*(maxResponse - threshold) < 0xFFFF
    // ie maxResponse - threshold < 655
    .maxResponse = (100 + 655),
    .threshold = 100
};

//**** CAP TOUCH HANDLER *****/
// This defines the grouping of sensors, the method to measure change in
// capacitance, and the function of the group

const struct Sensor multi_buttons =
{
    .halDefinition = RO_PINOSC_TA0_WDTp,
    .numElements = 3,
    .baseOffset = 0,
    // Pointer to elements
    .arrayPtr[0] = &up_element,           // point to up element
    .arrayPtr[1] = &down_element,         // point to down element
    .arrayPtr[2] = &middle_element,        // point to middle element
    // Timer Information
    .measGateSource= GATE_WDT_ACLK,      // 0->SMCLK, 1-> ACLK
    .accumulationCycles= WDTp_GATE_64   //64 - Default
};

```

Similarly, the sensor structure is also modified for these three elements.

The main code is almost identical to the single sensor demo. However, the variable **keyPressed** is used to check which element was touched. According to touch on different element states of Launchpad board LEDs are altered.

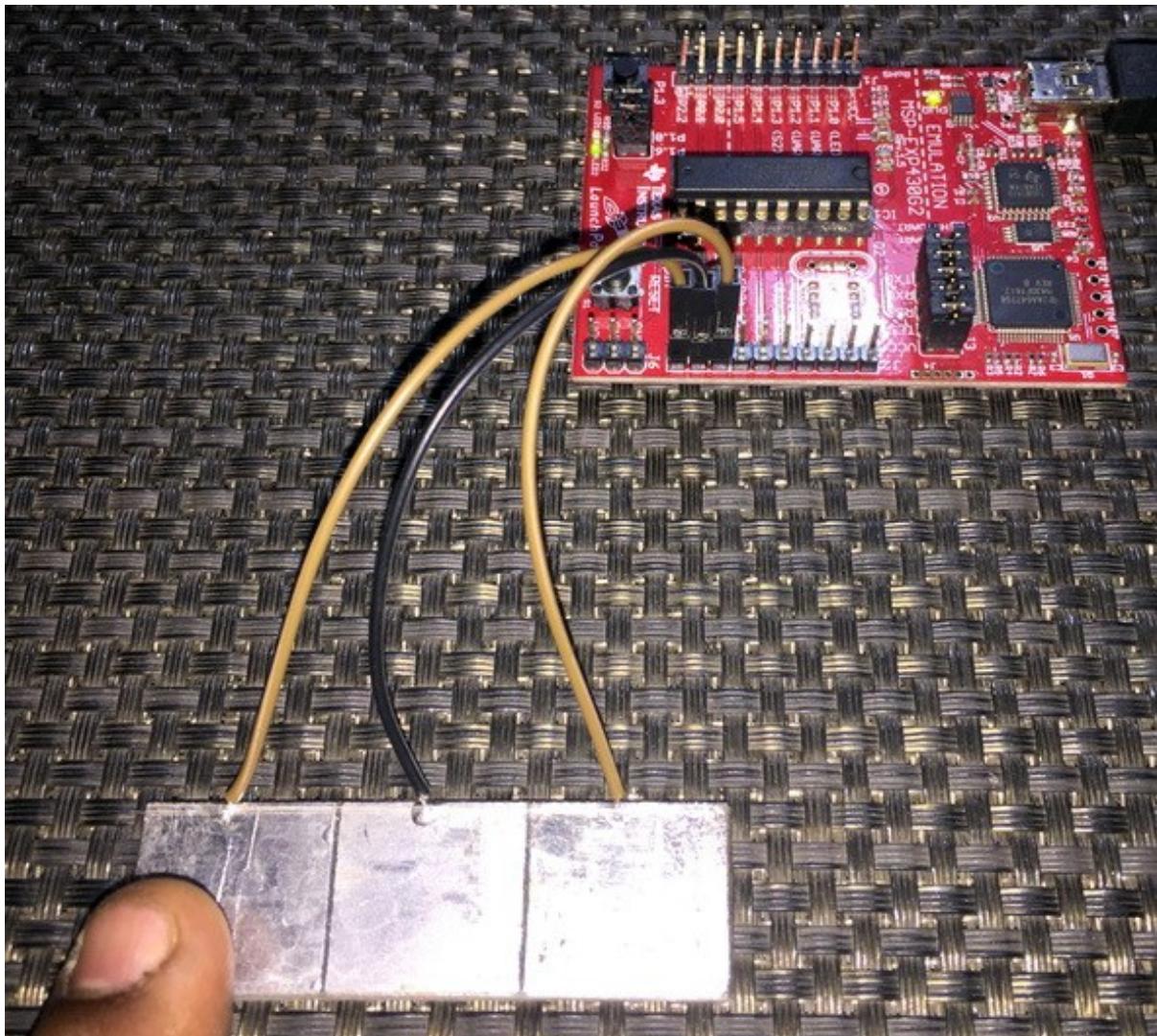
```

keyPressed = (struct Element *)TI_CAPT.Buttons(&multi_buttons);

if(keyPressed)
{
    // Up Element
    if(keyPressed == &up_element)
    {
        P1OUT |= BIT0;
    }
    // Down Element
    if(keyPressed == &down_element)
    {
        P1OUT |= BIT6;
    }
    // Middle Element
    if(keyPressed == &middle_element)
    {
        P1OUT = 0;
    }
}

```

Demo

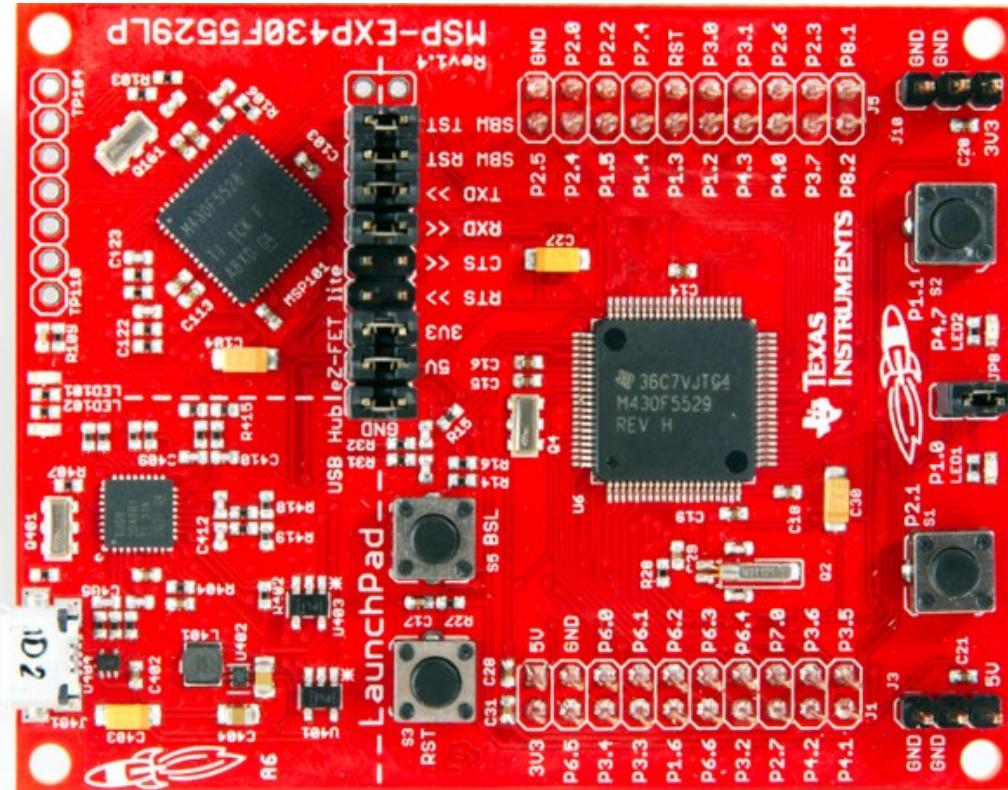


Demo video: <https://youtu.be/uCgi11GNajI>.

A Brief Intro of MSP430F5529LP Launchpad and TI's Driver Library

Up till now we have seen and used the power of Grace configuration tool, MSP430G2xxx devices and only mentioned the name **Driver Library**. At present for micros with too many hardware resources, it is really very difficult to go through their individual datasheet line-by-line and memorize register names and their purposes. However, we just need peripheral initialization once in a code and it should not take much of a project's development time. Likewise, when moving from one micro sub family to another or just interchanging devices within a given family, there should be some similarity in coding and hardware or else it be really very much difficult to keep track of everything. To overcome such issues and many others, mainstream embedded system solution manufacturers like TI offer different code development solutions ranging from graphical tools like Grace to code examples/templates as in TI's Resource Explorer. The Peripheral Driver Library or simply **DriverLib** is one solution that somewhat resides between aforementioned two. It is a set of drivers for accessing the peripherals found on MSP430 micros and is similar to HAL libraries used for ARM micros. So far, we have not used this library pack as it doesn't support VLDs. Details of TI's driver library can be found [here](#). Please have it downloaded as we will need it for the demo.

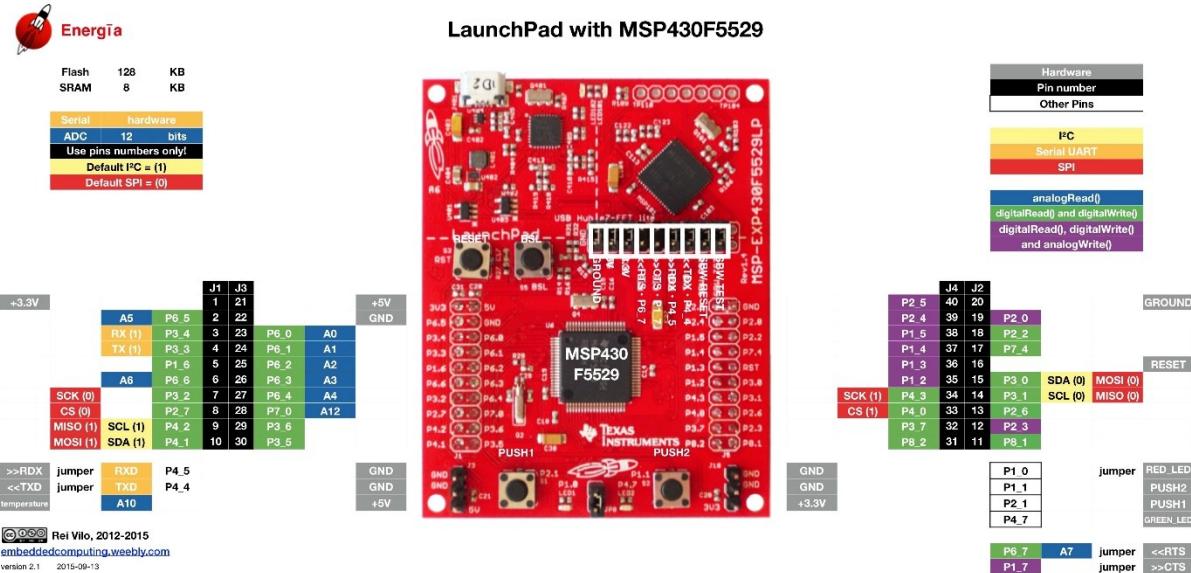
As mentioned before, there are other more resourceful and powerful MSP430s and the driver library is intended for such robust devices. MSP430F5529LP is one such powerful device. It is a microcontroller mainly intended for USB application development and has 128kB of flash and 8kB RAM. There is an inexpensive Launchpad board dedicated for this awesome micro and it delivers the punch needed in complex big projects. Details of this Launchpad board can be found [here](#).



In this section, we will briefly see the potential of combining TI's Driver Library with MSP430F5529LP.

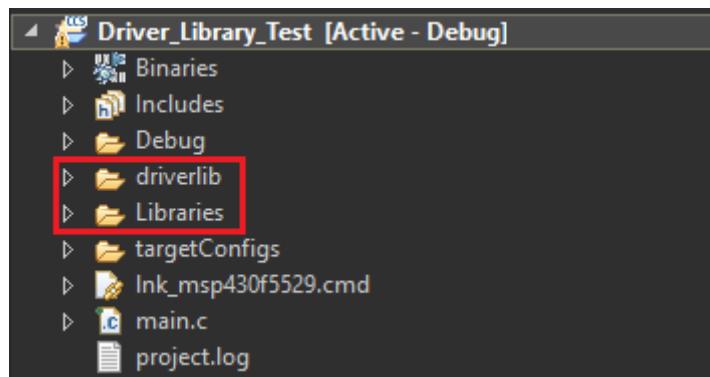
How tos?

Google and download the Energia pinmap for MSP430F5529LP.



I assume that by now you have downloaded the latest version of **DriverLib** and other documentations regarding this and the MSP430F5529LP Launchpad board.

Extract the DriverLib zip file and copy the correct DriverLib folder (MSP430F5xx_6xx folder in our case) to your project folder. In my case, I copied this folder and renamed it as *driverlib*. The process is same as what we did for our own-built library files.



Let the compiler know the physical paths of this folder just like the custom library files. Rest of the works is same as before.

Code Example

```
#include "driverlib.h"
#include "delay.h"

void main(void)
{
    unsigned char s = 0x00;

    WDT_A_hold(WDT_A_BASE);

    GPIO_setAsOutputPin (GPIO_PORT_P1, GPIO_PIN0);
    GPIO_setDriveStrength(GPIO_PORT_P1, GPIO_PIN0,
    GPIO_FULL_OUTPUT_DRIVE_STRENGTH);
    GPIO_setAsOutputPin (GPIO_PORT_P4, GPIO_PIN7);
    GPIO_setDriveStrength(GPIO_PORT_P4, GPIO_PIN7,
    GPIO_FULL_OUTPUT_DRIVE_STRENGTH);
    GPIO_setAsInputPinWithPullUpResistor(GPIO_PORT_P2, GPIO_PIN1);

    GPIO_setAsPeripheralModuleFunctionInputPin(GPIO_PORT_P5, (GPIO_PIN2 |
    GPIO_PIN4));
    GPIO_setAsPeripheralModuleFunctionOutputPin(GPIO_PORT_P5, (GPIO_PIN2 |
    GPIO_PIN4));
    UCS_setExternalClockSource(32768, 4000000);
    UCS_turnOnXT2(UCS_XT2_DRIVE_4MHZ_8MHZ);
    UCS_turnOnLFXT1(UCS_XT1_DRIVE_0, UCS_XCAP_3);
    UCS_initClockSignal(UCS_MCLK, UCS_XT2CLK_SELECT, UCS_CLOCK_DIVIDER_1);
    UCS_initClockSignal(UCS_SMCLK, UCS_XT2CLK_SELECT, UCS_CLOCK_DIVIDER_1);
    UCS_initClockSignal(UCS_ACLK, UCS_XT1CLK_SELECT, UCS_CLOCK_DIVIDER_1);

    while(1)
    {
        if(GPIO_getInputPinValue(GPIO_PORT_P2, GPIO_PIN1) == false)
        {
            while(GPIO_getInputPinValue(GPIO_PORT_P2, GPIO_PIN1) == false);
            GPIO_setOutputHighOnPin(GPIO_PORT_P1, GPIO_PIN0);
            delay_ms(100);
            GPIO_setOutputLowOnPin(GPIO_PORT_P1, GPIO_PIN0);
            s = ~s;
        }

        P4OUT ^= BIT7;
        switch(s)
        {
            case 0:
            {
                delay_ms(100);
                break;
            }

            default:
            {
                delay_ms(600);
                break;
            }
        }
    };
}
```

Explanation

To keep things simple, I demoed another LED blinking code. Notice that with inclusion of driverlib, everything has changed with meaningful functions. Take the setting of watchdog timer as an example.

```
WDTCTL = WDTPW | WDTHOLD; //Register-level access  
WDT_A_hold(WDT_A_BASE); //DriverLib function call
```

Instead of setting registers, driverlib functions are just taking some function argument(s) to set desired pin according to our wish. The functions and the arguments have meaningful names instead of magical numbers. This way of coding gives a fast overview of our code and the development time and efforts are greatly reduced. All register-level tasks are done under the hood of driverlib. This doesn't however restrict us from going the old-fashioned way of using register-based coding. Still it is possible:

```
P4OUT ^= BIT7;
```

The code begins with GPIO settings as follows:

```
GPIO_setAsOutputPin (GPIO_PORT_P1, GPIO_PIN0);  
GPIO_setDriveStrength(GPIO_PORT_P1, GPIO_PIN0, GPIO_FULL_OUTPUT_DRIVE_STRENGTH);  
GPIO_setAsOutputPin (GPIO_PORT_P4, GPIO_PIN7);  
GPIO_setDriveStrength(GPIO_PORT_P4, GPIO_PIN7, GPIO_FULL_OUTPUT_DRIVE_STRENGTH);  
  
GPIO_setAsInputPinWithPullUpResistor(GPIO_PORT_P2, GPIO_PIN1);  
  
GPIO_setAsPeripheralModuleFunctionInputPin(GPIO_PORT_P5, (GPIO_PIN2 | GPIO_PIN4));  
GPIO_setAsPeripheralModuleFunctionOutputPin(GPIO_PORT_P5, (GPIO_PIN2 |  
GPIO_PIN4));
```

Two pins **P1_0** and **P4_7** are set as outputs with full drive strength since these pins have LEDs connected with them. **P2_1** is set as an input with pull-up as it is connected with an onboard push button. Some pins of **P5** are set for peripheral modules because these pins are connected with external crystals.

Next, we set to configure the clock system. There are two onboard external crystals – one 32.768kHz clock crystal and one 4MHz crystal. **UCS** stands for **Unified Clock System**. Like the basic clock system in MSP430G2xxx devices, this a complex network of clock system with lot of options. There are several internal and external clock sources to clock the main clock, the sub-main clock and the auxiliary clock signals. Here, I used the external crystal clocks to clock MCLK, SMCLK and ACLK

```
UCS_setExternalClockSource(32768, 4000000);  
  
UCS_turnOnXT2(UCS_XT2_DRIVE_4MHZ_8MHZ);  
UCS_turnOnLFXT1(UCS_XT1_DRIVE_0, UCS_XCAP_3);  
  
UCS_initClockSignal(UCS_MCLK, UCS_XT2CLK_SELECT, UCS_CLOCK_DIVIDER_1);  
UCS_initClockSignal(UCS_SMCLK, UCS_XT2CLK_SELECT, UCS_CLOCK_DIVIDER_1);  
UCS_initClockSignal(UCS_ACLK, UCS_XT1CLK_SELECT, UCS_CLOCK_DIVIDER_1);
```

In the main loop, the Launchpad's green LED (*P4_7*) is toggled at a given flash rate. When the onboard user push button (*P2_1*) is pressed, the onboard red LED (*P1_0*) is briefly turned on and the rate of green LED's flashing is altered.

```

if(GPIO_getInputPinValue(GPIO_PORT_P2, GPIO_PIN1) == false)
{
    while(GPIO_getInputPinValue(GPIO_PORT_P2, GPIO_PIN1) == false);
    GPIO_setOutputHighOnPin(GPIO_PORT_P1, GPIO_PIN0);
    delay_ms(100);
    GPIO_setOutputLowOnPin(GPIO_PORT_P1, GPIO_PIN0);
    s = ~s;
}

P4OUT ^= BIT7;

switch(s)
{
    case 0:
    {
        delay_ms(100);
        break;
    }

    default:
    {
        delay_ms(600);
        break;
    }
}

```

Demo



Demo video: <https://youtu.be/ppgQP661JDw>.

Ending

A microcontroller like the ones in MSP430G2xxx series may look tiny and less resourceful but it is impossible to show everything in full details. This writeup is just a summary. Even at this stage after explaining and demoing multiple basic hardware of MSP430s, I have yet to cover more stuffs.

As an advice, it is imperative that readers study app notes, reference manuals and TI wiki pages to improve proficiency and in-depth knowledge. There are some good books on MSP430s too. Books like ***MSP430 Microcontroller Basics*** by ***John Davies*** and ***Analog and Digital Circuits for Electronic Control System Applications Using the TI MSP430 Microcontroller*** by ***Jerry Luecke*** discuss MSP430 microcontrollers and their applications in really great details. For now, I ask readers to practice and experiment what I have shown so far. Try stuffs without using GRACE assist, try out different combinations and try out different MSP430 micros.

Happy coding.

Author: Shawon M. Shahryiar

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25.08.2017

*** Some images have been taken from the documents and webpages of Texas Instruments (TI) and Mikroelektronika.*