

1. A **confusion matrix** is a summary of the performance of a (supervised) classifier over a set of development ("test") data, by counting the various instances:

		Actual			
		a	b	c	d
Classified	a	10	2	3	1
	b	2	5	3	1
	c	1	3	7	1
	d	3	0	3	5

- (i). Calculate the classification **accuracy** of the system. Find the **error rate** for the system.

$$Acc = \frac{\# \text{ of correctly classified}}{\text{total } \# \text{ of instances}}$$

$$= \frac{10 + 5 + 7 + 5}{\text{Sum of the table}} = 50$$

$$= \frac{27}{50}$$

$$= 54\%$$

$$ER = 1 - Acc = 46\%$$

- (ii). Calculate the **precision**, **recall** and **F-score** (where  $\beta = 1$ ), for class *d*. (Why can't we do this for the whole system? How can we consider the whole system?)

$$\text{Precision} = \frac{\# \text{ of instances "correctly" classified as } d}{\# \text{ of instances classified as } d} = \frac{TP}{TP+FP} = \frac{5}{5+6} = \frac{5}{11}$$

$$\text{Recall} = \frac{\# \text{ of instances "correctly" classified as } d}{\# \text{ of instances truly } d} = \frac{TP}{TP+FN} = \frac{5}{5+3} = \frac{5}{8}$$

		Actual			
		a	b	c	d
Classified	a	10	2	3	1
	b	2	5	3	1
	c	1	3	7	1
	d	3	0	3	5

$\left. \begin{array}{l} \\ \\ \end{array} \right\} FN=3$

$\underbrace{\hspace{10em}}_{FP=6}$      $\underbrace{\hspace{10em}}_{TP=5}$

$$\beta = 1 : F_1 = \frac{2P \cdot R}{P + R} = \frac{2}{\frac{1}{P} + \frac{1}{R}} \quad (\text{harmonic mean})$$

$$= \frac{2 \cdot \frac{5}{11} \cdot \frac{5}{8}}{\frac{5}{11} + \frac{5}{8}}$$

$$= 53\%$$

2. For the following dataset:

ID	Outl	Temp	Humi	Wind	PLAY
TRAINING INSTANCES					
A	s	h	n	f	N
B	s	h	h	t	N
C	o	h	h	f	Y
D	r	m	h	f	Y
E	r	c	n	f	Y
F	r	c	n	t	N
TEST INSTANCES					
G	o	m	n	t	?
H	?	h	?	f	?

(i). Classify the test instances using the method of 0-R.

0-R : Majority class classifier

train : 3Y, 3N (choose either!)

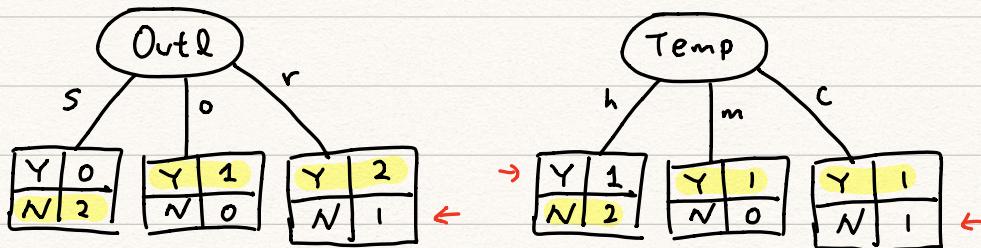
⇒ Let's choose "N"

⇒ Instances : G → N

H → N

(ii). [OPTIONAL] Classify the test instances using the method of 1-R. (Assume Outl = s for H)

1-R: Classify instances based on one attribute



$$ER = \frac{1}{6}$$

$$ER = \frac{2}{6}$$

Choose attribute with lowest ER : Assume "Outl" is best

⇒ Instances : G: Outl = o → Y

H: Outl = s → N

<i>ID</i>	<i>Outl</i>	<i>Temp</i>	<i>Humi</i>	<i>Wind</i>	<i>PLAY</i>
TRAINING INSTANCES					
A	s	h	n	f	N
B	s	h	h	t	N
C	o	h	h	f	Y
D	r	m	h	f	Y
E	r	c	n	f	Y
F	r	c	n	t	N
TEST INSTANCES					
G	o	m	n	t	?
H	?	h	?	f	?

3. Given the above dataset, build a Naïve Bayes model for the given training instances. (6 training instances)

NB : probabilistic classification model

⇒ Calculate prior & conditional probs

Prior probs :

$$P(Y) = \frac{1}{2} \quad P(N) = \frac{1}{2}$$

Conditional :

$$P(Outl=s | Y) = 0$$

$$P(Outl=s | N) = \frac{2}{3}$$

$$P(Outl=o | Y) = \frac{1}{3}$$

$$P(Outl=o | N) = 0$$

$$P(Outl=r | Y) = \frac{2}{3}$$

$$P(Outl=r | N) = \frac{1}{3}$$

$$P(Temp = h | N) = \frac{2}{3}$$

$$P(Temp = m | N) = 0$$

$$P(Temp = c | N) = \frac{1}{3}$$

$$P(Temp = h | Y) = \frac{1}{3}$$

$$P(Temp = m | Y) = \frac{1}{3}$$

$$P(Temp = c | Y) = \frac{1}{3}$$

$$P(Humi = n | N) = \frac{2}{3}$$

$$P(Humi = h | N) = \frac{1}{3}$$

$$P(Humi = n | Y) = \frac{1}{3}$$

$$P(Humi = h | Y) = \frac{2}{3}$$

$$P(Wind = T | N) = \frac{2}{3}$$

$$P(Wind = F | N) = \frac{1}{3}$$

$$P(Wind = T | Y) = 0$$

$$P(Wind = F | Y) = 1$$

4. Using the Naïve Bayes model that you developed in question 4, classify the given test instances.

(i). No smoothing.

$$\hat{C} = \underset{C}{\operatorname{argmax}} P(C | t_1, \dots, t_k)$$

attributes

$$= \underset{C}{\operatorname{argmax}} \frac{P(t_1, \dots, t_k | C) P(C)}{P(t_1, \dots, t_k)}$$

same for all classes  
(ignore in "argmax")

$$= \underset{C}{\operatorname{argmax}} P(t_1, \dots, t_k | C) P(C)$$

$$= \underset{C}{\operatorname{argmax}} \left\{ \prod_{i=1}^k P(t_i | C) \right\} \cdot P(C)$$

NB assumption:  
attributes are conditionally independent

TEST INSTANCES					
G	O	m	n	T	?
H	?	h	?	F	?

Instance G:

- Class Y:

$$P(\text{Outl} = o | Y) P(\text{Temp} = m | Y) P(\text{Humi} = n | Y)$$

$$\times P(\text{Wind} = T | Y) P(Y)$$

$$= \frac{1}{3} \times \frac{1}{3} \times \frac{1}{3} \times 0 \times \frac{1}{2} = 0$$

- Class N:

$$P(\dots) \dots P(N)$$

$$= 0 \times 0 \times \frac{2}{3} \times \frac{2}{3} \times \frac{1}{2}$$

$$= 0$$

⇒ Choose either label for G

(e.g. Y)

$P(\text{Outl} = s   N) = \frac{2}{3}$	$P(\text{Outl} = o   N) = 0$	$P(\text{Outl} = r   N) = \frac{1}{3}$
$P(\text{Outl} = s   Y) = 0$	$P(\text{Outl} = o   Y) = \frac{1}{3}$	$P(\text{Outl} = r   Y) = \frac{2}{3}$
$P(\text{Temp} = h   N) = \frac{2}{3}$	$P(\text{Temp} = m   N) = 0$	$P(\text{Temp} = c   N) = \frac{1}{3}$
$P(\text{Temp} = h   Y) = \frac{1}{3}$	$P(\text{Temp} = m   Y) = \frac{1}{3}$	$P(\text{Temp} = c   Y) = \frac{1}{3}$
$P(\text{Humi} = n   N) = \frac{2}{3}$	$P(\text{Humi} = h   N) = \frac{1}{3}$	$P(Y) = \frac{1}{2}$
$P(\text{Humi} = n   Y) = \frac{1}{3}$	$P(\text{Humi} = h   Y) = \frac{2}{3}$	$P(N) = \frac{1}{2}$
$P(\text{Wind} = T   N) = \frac{2}{3}$	$P(\text{Wind} = F   N) = \frac{1}{3}$	
$P(\text{Wind} = T   Y) = 0$	$P(\text{Wind} = F   Y) = 1$	

Instance H:

missing values ⇒ use what we have.

- Class Y:

$$P(\text{Temp} = h | Y) P(\text{Wind} = F | Y) P(Y)$$

$$= \frac{1}{3} \times 1 \times \frac{1}{2} = \frac{1}{6} \quad \checkmark$$

- Class N:

$$P(\text{Temp} = h | N) P(\text{Wind} = F | N) P(N)$$

$$= \frac{2}{3} \times \frac{1}{3} \times \frac{1}{2} = \frac{1}{9}$$

$\Rightarrow$  Classify instance  $H$  as  $Y$ .

(E)

(ii). Using the “epsilon” smoothing method.

Replace zero probabilities with  $\varepsilon$  (a small value, e.g.  $10^{-6}$ )

For instance  $G_1$ :

$$Y: P(Outl = o | Y) P(Temp = m | Y) P(Humi = n | Y)$$

$$\times P(Wind = T | Y) P(Y)$$

$$= \frac{1}{3} \times \frac{1}{3} \times \frac{1}{3} \times \varepsilon \times \frac{1}{2} = \frac{\varepsilon}{54}$$

$$N: P(\dots) \dots P(N)$$

$$= \varepsilon \times \varepsilon \times \frac{2}{3} \times \frac{2}{3} \times \frac{1}{2}$$

$$= \frac{2\varepsilon^2}{9}$$

$$\frac{\varepsilon}{54} > \frac{2\varepsilon^2}{9} \Rightarrow \text{Classify } G_1 \text{ as } Y.$$

For instance  $H$ : no zero probabilities  $\Rightarrow$  still  $Y$ .

add 1 smoothing

(iii). [OPTIONAL] Using “Laplace” smoothing ( $\alpha = 1$ )

For conditional probs:

$$P_i = \frac{x_i + \alpha}{N + \alpha d} \quad (\text{was } P_i = \frac{x_i}{N})$$

# possible values for this attribute

$$\Rightarrow \text{ensure } \sum_k P(A_i = k | \text{Class } c) = 1$$

$$\Rightarrow \text{No zero conditional probs! (If } x_i = 0, P_i = \frac{\alpha}{N+\alpha d})$$

Instance  $G_1$ :

$$Y: P(Outl = o | Y) P(Temp = m | Y) P(Humi = n | Y)$$

$$\times P(Wind = T | Y) P(Y)$$

$$= \frac{1+1}{3+3} \times \frac{1+1}{3+3} \times \frac{1+1}{3+2} \times \frac{0+1}{3+2} \times \frac{1}{2}$$

$$= \frac{2}{6} \times \frac{2}{6} \times \frac{2}{5} \times \frac{1}{5} \times \frac{1}{2}$$

$$= 0.0044$$

$N : P(\dots) \dots P(N)$

$$= \frac{0+1}{3+3} \times \frac{0+1}{3+3} \times \frac{2+1}{3+2} \times \frac{2+1}{3+2} \times \frac{1}{2}$$

$$= \frac{1}{6} \times \frac{1}{6} \times \frac{3}{5} \times \frac{3}{5} \times \frac{1}{2}$$

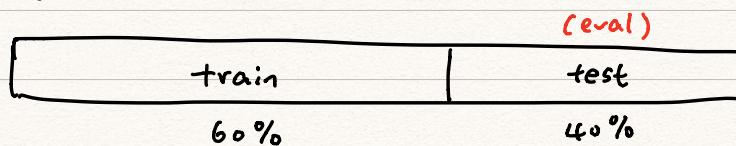
$$= 0.005 \quad \checkmark$$

$\Rightarrow$  Classify instance  $G$  as  $N$ .

Similarly for  $H \dots$

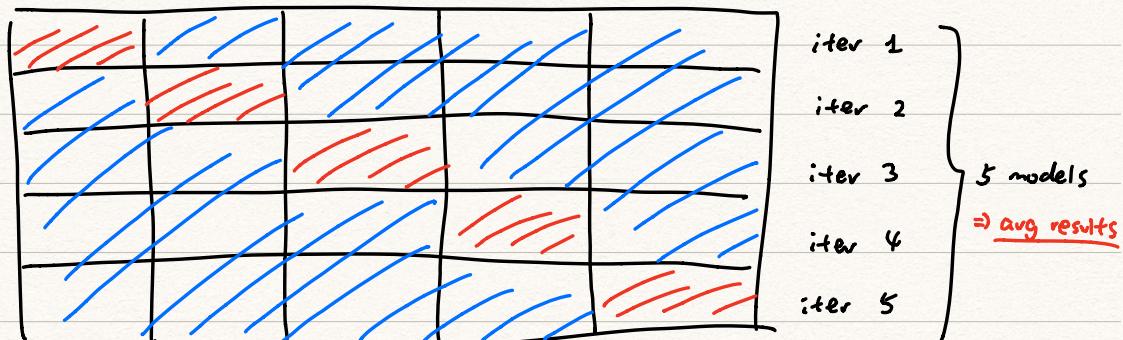
5. [OPTIONAL] How is **holdout** evaluation different to **cross-validation** evaluation? What are some reasons we would prefer one strategy over the other?

Hold-out : fixed



subject to some random variation in allocation  
of instances (to train & test)

Cross-validation: K-fold ( $K=5$  partitions)



for test

Each instance is used for testing.

for train

(But CV takes longer)