Matrix.h:

```
#include <fstream> // for file access
#include <iostream>

using namespace std;

#pragma once
class Matrix
{
private:
	unsigned m_rowSize; // cannot be negative, saves memory space
	unsigned m_colSize; // cannot be negative, saves memory space
	double** m_matrix;
public:
	Matrix();
	Matrix(unsigned, unsigned, double); // holds row size, column size, initial value for each cell
	Matrix(const Matrix&); // copy constructor
	~Matrix(); // destructor

	// Matrix Operations
	Matrix operator+(Matrix&); // sum two matrices
	Matrix operator-(Matrix&); // subtract two matrices
	Matrix operator*(Matrix&); // multiply two matrices
	Matrix operator=(Matrix&);
	Matrix transpose();

	// Scalar Operations
	Matrix operator+(double);
	Matrix operator-(double);
```

```
        Matrix operator*(double);
        Matrix operator/(double);

        // Another Methods
        double& operator()(const unsigned&, const unsigned&); // Matrix(3,4)
        void print() const;
        unsigned getRows() const;
        unsigned getCols() const;
        void getMatrixFromConsole() const;
        void printPrimaryDiagonal(unsigned) const;
        void printSecondaryDiagonal(unsigned) const;
        void writeMatrixToFile() const;
};
```

Matrix.cpp:

```
#include "Matrix.h"

using namespace std;

// Default constructor
Matrix::Matrix()
{
        m_rowSize = 0;
        m_colSize = 0;
        m_matrix = NULL;
}

// Constructor for any matrix
Matrix::Matrix(unsigned rowSize, unsigned colSize, double initial = 0.0)
```

```
{
	m_rowSize = rowSize;
	m_colSize = colSize;
	m_matrix = new double* [m_rowSize];

	for (unsigned row = 0; row < m_rowSize; row++)
	{
		m_matrix[row] = new double[m_colSize];

		for (unsigned col = 0; col < m_colSize; col++)
		{
			m_matrix[row][col] = initial;
		}
	}
}

// Copy constructor
Matrix::Matrix(const Matrix& other)
{
	cout << "\nCopy constructor invoked\n";
	m_rowSize = other.m_rowSize;
	m_colSize = other.m_colSize;

	m_matrix = new double* [other.m_rowSize]; // create new instance

	for (unsigned row = 0; row < m_rowSize; row++)
	{
		m_matrix[row] = new double[m_colSize];
```

```
                for (unsigned col = 0; col < m_colSize; col++)
                {
                        m_matrix[row][col] = other.m_matrix[row][col];
                }
        }
}

// Destructor
Matrix::~Matrix()
{
        for (unsigned row = 0; row < m_rowSize; row++)
        {
                delete m_matrix[row];
        }

        delete[] m_matrix;
}

// Addition of two matrices
Matrix Matrix::operator+(Matrix& other)
{
        Matrix resultMatrix(m_colSize, m_rowSize, 0.0); // create new matrix instance

        for (unsigned row = 0; row < m_rowSize; row++)
        {
                for (unsigned col = 0; col < m_colSize; col++)
                {
                        resultMatrix(row, col) = this->m_matrix[row][col] + other(row, col);
                }
```

```
	}

	return resultMatrix;
}

// Subtraction of two matrices
Matrix Matrix::operator-(Matrix& other)
{
	Matrix resultMatrix(m_colSize, m_rowSize, 0.0);

	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
			resultMatrix(row, col) = this->m_matrix[row][col] - other(row, col);
		}
	}

	return resultMatrix;
}

// Multiplication of two matrices
Matrix Matrix::operator*(Matrix& other)
{
	Matrix resultMatrix(m_rowSize, other.getCols(), 0.0);

	if (m_colSize == other.getRows())
	{
		double temp = 0.0;
```

```
            for (unsigned row = 0; row < m_rowSize; row++)
            {
                for (unsigned col = 0; col < other.getCols(); col++)
                {
                    temp = 0.0;

                    for (unsigned k = 0; k < m_colSize; k++)
                    {
                        temp += m_matrix[row][k] * other(k, col);
                    }

                    resultMatrix(row, col) = temp;
                    // cout << multiply(row,col) << " ";
                }

                // cout << endl;
            }

            return resultMatrix;
        }
        else
        {
            Matrix emptyMatrix(m_rowSize, m_colSize);
            return emptyMatrix;
        }
}
```

```
Matrix Matrix::operator=(Matrix& other)
{
	swap(m_matrix, other.m_matrix);
	swap(m_rowSize, other.m_rowSize);
	swap(m_colSize, other.m_colSize);

	return *this;
}

// Scalar Addition
Matrix Matrix::operator+(double scalar)
{
	Matrix result(m_rowSize, m_colSize, 0.0);

	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
			result(row, col) = this->m_matrix[row][col] + scalar;
		}
	}

	return result;
}

// Scalar Subtraction
Matrix Matrix::operator-(double scalar)
{
	Matrix result(m_rowSize, m_colSize, 0.0);
```

```
	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
			result(row, col) = this->m_matrix[row][col] - scalar;
		}
	}

	return result;
}

// Scalar Multiplication
Matrix Matrix::operator*(double scalar)
{
	Matrix result(m_rowSize, m_colSize, 0.0);

	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
			result(row, col) = this->m_matrix[row][col] * scalar;
		}
	}

	return result;
}
```

```
// Scalar Division
Matrix Matrix::operator/(double scalar)
{
	Matrix result(m_rowSize, m_colSize, 0.0);

	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
			result(row, col) = this->m_matrix[row][col] / scalar;
		}
	}

	return result;
}

// Returns value of given location when asked in the form Matrix(x,y)
double& Matrix::operator()(const unsigned& rowNumber, const unsigned& colNumber)
{
	return this->m_matrix[rowNumber][colNumber];
}

// Row size getter
unsigned Matrix::getRows() const
{
	return this->m_rowSize;
}
```

```
// Col size getter
unsigned Matrix::getCols() const
{
	return this->m_colSize;
}

// Take any given matrices transpose and returns another matrix
Matrix Matrix::transpose()
{
	Matrix transpose(m_colSize, m_rowSize, 0.0);

	for (unsigned row = 0; row < m_colSize; row++)
	{
		for (unsigned col = 0; col < m_rowSize; col++)
		{
			transpose(row, col) = this->m_matrix[col][row];
		}
	}

	return transpose;
}

// Get matrix from console
void Matrix::getMatrixFromConsole() const
{
	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
```

```
                cin >> m_matrix[row][col];
            }
        }
}

void Matrix::printPrimaryDiagonal(unsigned m_rowSize) const
{
        cout << "Primary diagonal: ";

        for (unsigned row = 0; row < m_rowSize; row++)
        {
            for (unsigned col = 0; col < m_rowSize; col++)
            {
                if (row == col)
                {
                    cout << m_matrix[row][col] << ", ";
                }
            }
        }

        cout << endl;
}

void Matrix::printSecondaryDiagonal(unsigned m_rowSize) const
{
        cout << "Secondary diagonal: ";

        for (unsigned row = 0; row < m_rowSize; row++)
        {
```

```
		for (unsigned col = 0; col < m_rowSize; col++)
		{
			if ((row + col) == (m_rowSize - 1))
			{
				cout << m_matrix[row][col] << ", ";
			}
		}
	}

	cout << endl;
}

void Matrix::writeMatrixToFile() const
{
	ofstream file("matrix.txt");

	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
			file << "[" << m_matrix[row][col] << "]";
		}

		file << "\n";
	}

	file.close();
}
```

```
void Matrix::print() const
{
	for (unsigned row = 0; row < m_rowSize; row++)
	{
		for (unsigned col = 0; col < m_colSize; col++)
		{
			cout << "[" << m_matrix[row][col] << "]";
		}

		cout << endl;
	}
}
```

Main.cpp:

```
#include <fstream> // for file access
#include <iostream>

#include "Matrix.h"

using namespace std;

void readMatrixFromFile(Matrix& matrix, unsigned m_rowSize, unsigned m_colSize);

int main()
{
	int m_rowSize, m_colSize;
	cout << "Enter rows and columns of the matrix:\n";
	cin >> m_rowSize >> m_colSize;
```

```
Matrix firstMatrix(m_rowSize, m_colSize, 0.0);
cout << "\nEnter the matrix elements one by one:\n";
firstMatrix.getMatrixFromConsole();

cout << "\nEntered matrix is:\n";
firstMatrix.print();

Matrix secondMatrix = firstMatrix; // invoke copy constructor
cout << "\nResult of the copy constructor is:\n";
secondMatrix.print();

Matrix duplicatedMatrix;
duplicatedMatrix = firstMatrix; // invoke operator=
cout << "\nResult of assignment operator:\n";
duplicatedMatrix.print();

Matrix transposedMatrix = duplicatedMatrix.transpose();
cout << "\nResult of transposed matrix:\n";
transposedMatrix.print();

cout << "\nResult of new matrix with initial values:\n";
Matrix testMatrix(m_rowSize, m_colSize, 7);
testMatrix.print();

cout << "\nPrint primary and secondary diagonals:\n";
transposedMatrix.printPrimaryDiagonal(m_rowSize);
transposedMatrix.printSecondaryDiagonal(m_rowSize);

cout << "\nRead matrix from file:\n";
```

```
	Matrix matrix(m_rowSize, m_colSize, 0.0);
	readMatrixFromFile(matrix, m_rowSize, m_colSize);
	matrix.print();

	// Addition of two matrices
	Matrix additionMatrix = matrix + transposedMatrix;
	cout << "\nAddition of matrix from file with transposed matrix:\n";
	additionMatrix.print();

	// Subtraction of two matrices
	Matrix subtractionMatrix = matrix - transposedMatrix;
	cout << "\nSubtraction of matrix from file with transposed matrix:\n";
	subtractionMatrix.print();

	// Multiplication of two matrices
	Matrix multiplicationMatrix = matrix * transposedMatrix;
	cout << "\Multiplication of matrix from file with transposed matrix:\n";
	multiplicationMatrix.print();

	// Scalar Addition
	Matrix matrixWithAddedScalar = testMatrix + 3;
	matrixWithAddedScalar.print();
}

// External method to read matrix from file
void readMatrixFromFile(Matrix& matrix, unsigned m_rowSize, unsigned m_colSize)
{
	ifstream file("matrix.txt");
```

```
        for (unsigned row = 0; row < m_rowSize; row++)
        {
                for (unsigned col = 0; col < m_colSize; col++)
                {
                        file >> matrix(row, col);
                }
        }

        file.close();
}
```