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LAGA_chapter06.02.wxm (LAGA examples)
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 A test document for Geometric Algebra with wxMaxima
 contains...
 Initialization
 Loading of functions (intrinsic and GA specific)
 Pseudoscalar definition (specifies the space dimension) and
 calculation of the inverse pseudoscalar used to generate the dual of a multivector
 Enumeration of the standard basis for the specified dimension
 Blades, Norms and Reversion in the geometric algebra, G4, i.e. using Plen=4
 Reference book...Linear and Geometric Algebra (LAGA)
 by Alan Macdonald
 Initialization
 (%i28) ext:["wxm"]$
              file_type_maxima:append(ext,file_type_maxima)$
               batchload("initialize_fns")$
 the pseudoscalar and its inverse
 the lowest useable dimension pseudoscalar should be \{e1,e2\} i.e. Plen = 2
 e.g. for four dimensions edit Pseudos:{e1,e2,e3}$ to Pseudos:{e1,e2,e3,e4}$
 (%i1) Pseudos:{e1,e2,e3,e4}$
             Pvar:listofvars(Pseudos)$
             Plen:length(Pvar)$
             I:Pseudos$
             ni:(Plen-1)*Plen/2$
             Ii:(-1)^ni*I$
             kill(ni)$
             ldisplay(Pvar)$
    (%t8) Pvar = [e1, e2, e3, e4]
(%i9) batchload("initialize_lsts")$
    (\%t9) | stb||ds = [[{e1},{e2},{e3},{e4}],[{e1,e2},{e1,e3},{e1,e4},{e2,e3},{e2,e4},{e2,e4},{e2,e4},{e3,e4}]
e3,e4}],[{e1,e2,e3},{e1,e2,e4},{e1,e3,e4},{e2,e3,e4}],[{e1,e2,e3,e4}]]
 e4},{e1,e2,e3},{e1,e2,e4},{e1,e3,e4},{e2,e3,e4},{e1,e3,e4}]
 (\%t11) invblds = [\{e1\}, \{e2\}, \{e3\}, \{e4\}, -\{e1, e2\}, -\{e1, e3\}, -\{e1, e4\}, -\{e2, e3\}, -\{e2, e4\}, -\{e2, e4\}, -\{e3, e4\}, -\{e3, e4\}, -\{e3, e4\}, -\{e4, e4\}
,-{e3,e4},-{e1,e2,e3},-{e1,e2,e4},-{e1,e3,e4},-{e2,e3,e4},{e1,e2,e3,e4}]
 end of Initialization
 G4
 Exercise 6.6
 page 99
 Show that if B is a 4-blade, then it has an inverse of the given form, using
 the blade (tilda) product
 (%i12) b1:s1*{e1}$
              b2:s2*{e2}$
              b3:s3*{e3}$
              b4:s4*{e4}$
              B:b1~*b2~*b3~*b4$
              ldisplay(B)$
 (\%t17) B = \{e1, e2, e3, e4\} * s1 * s2 * s3 * s4
 (%i18) Binv:(b4\sim*b3\sim*b2\sim*b1)/normod(B)^2$
               ldisplay(Binv)$
  (%t19) Binv = \frac{\{e1, e2, e3, e4\}}{s1*s2*s3*s4}
 (%i20) BBinv:B~*Binv$
               Idisplay(BBinv)$
  (\%t21) BBinv = 1
 Exercise 6.7
 page 99
 Show that if B is a 4-blade, then it has an inverse of the given form
 (\%i22) Bm1:(-1)^{(4*(4-1)/2)*B/normod(B)^2$
               ldisplay(Bm1)$
  (%t23) Bm1 = \frac{\{e1, e2, e3, e4\}}{s1*s2*s3*s4}
 (%i24) BBm1:B~*Bm1$
               ldisplay(BBm1)$
  (\%t25) BBm1 = 1
 Problem 6.2.5
 page 100
 6.2.5a e.g. for a 4-blade, A using the blade (tilda) outer product
 (%i26) a1:s1*{e1}$
               a2:s2*{e2}$
               a3:s3*{e3}$
               a4:s4*{e4}$
               A:a1~^a2~^a3~^a4$
               Arev:a4~^a3~^a2~^a1$
               ldisplay(A,Arev)$
  (\%t32) A = \{e1, e2, e3, e4\} * s1 * s2 * s3 * s4
  (\%t33) Arev = \{e1, e2, e3, e4\}*s1*s2*s3*s4
 6.2.5b e.g. for a 3-blade, A3, using the multivector reverse function, mvrev()
 (%i34) A3:a1~*a2~*a4$
               A3rev:mvrev(A3)$
               A3revrev:mvrev(A3rev)$
               ldisplay(A3,A3rev,A3revrev)$
  (\%t37) A3 = \{e1, e2, e4\} * s1 * s2 * s4
  (\%t38)/R/A3rev = -\{e1,e2,e4\}*s1*s2*s4
  (\%t39)/R/A3revrev = \{e1, e2, e4\}*s1*s2*s4
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Created with wxMaxima.