

# Predictive Maintenance

Machine Learning, MQTT and json/protobuf

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- Recap on Predictive Maintenance
- Introduction to machine learning in python
- Introduction to MQTT and json/protobuf in python



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# **Condition Based Maintenance**

- The goal of CBM is to spot upcoming equipment failures so maintenance can be proactively scheduled when it is needed.
- Asset conditions need to trigger maintenance with a long enough time period before failure.
  - So work can be finished before the asset fails or performance falls below the optimal level

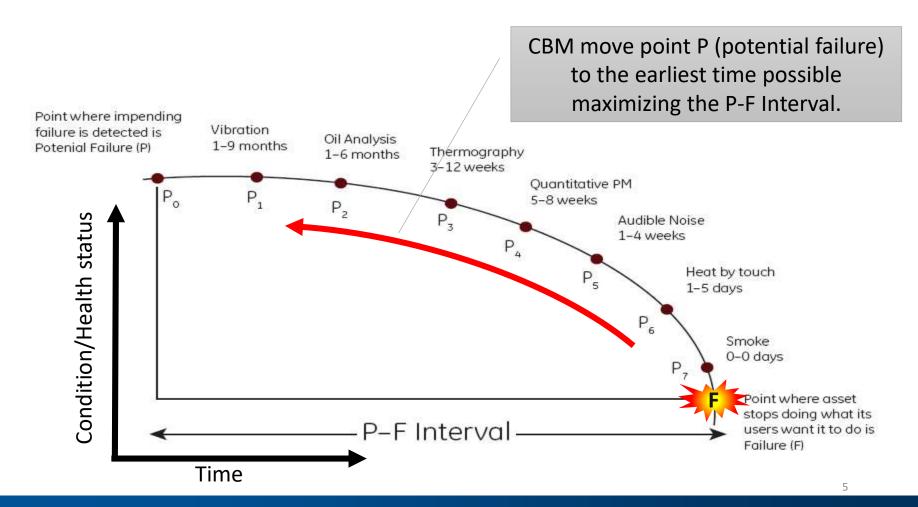
### CBM = Cost Savings + Higher system reliability

- CBM allows preventive and corrective actions to be scheduled at the optimal time, thus reducing the total cost of ownership.
- Today improvements in technology are making it easier to gather, store, and analyze data for CBM.
- CBM is highly effective where safety and reliability is the paramount concern such as Industry 4.0 aware plants, aircraft industry, semiconductor manufacturing, nuclear, oil and gas, and so on



### Potential-Failure Curve

• The P-F curve chart is one of the most important tools for reliability centered maintenance plan.





### Predictive maintenance

- Relies on maintenance based on trends acquired by equipment data.
- It is based on predicting when an asset needs attention rather than simply replacing a part, when it could last longer.
- It deals with online data
  - machine conditions are constantly monitored
  - data is constantly analyzed.

#### Data acquisition

 Data are acquired from the monitored equipment.

#### Data processing

 The acquired data are validated and transformed properly according to the requirements of the decision making techniques.

#### **Decision Making**

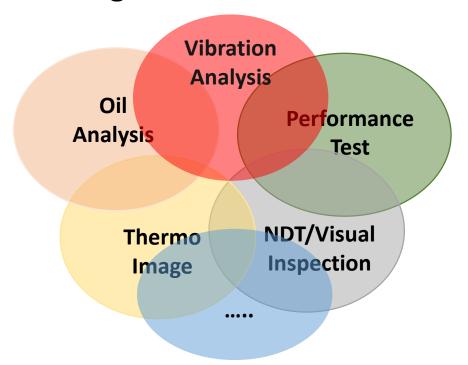
 A number of methods and techniques are applied to obtain the current health condition of the monitored equipment and recommend maintenance plans.



## Predictive Maintenance Tools

 The predictive maintenance principle is to use a combination of measurements on process and machinery to evaluate equipment conditions.

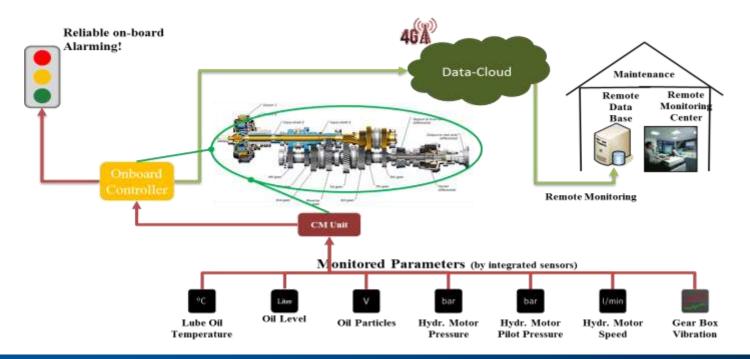
Several technologies are available:





### Data Collection and Storage

- All the methods described before need to analyze machine data.
- Data can be collected from the system by two different methods:
  - ➤ Spot readings: can be performed at regular intervals by using portable instruments.
  - Continuous readings: Sensors can be retrofitted to equipment or installed during manufacture for continuous data collection.
- Collected data is sent to the cloud for storage and for remote monitoring and processing

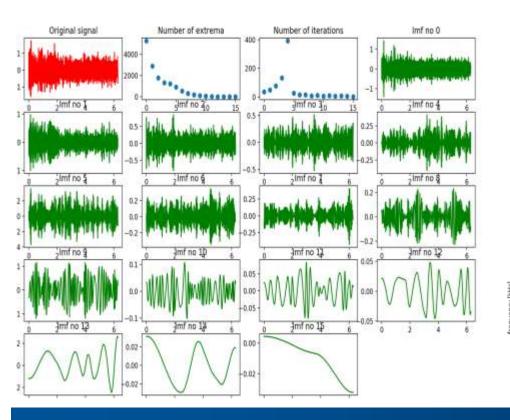


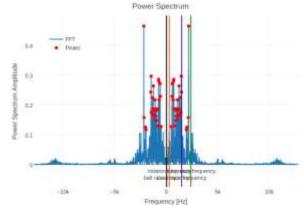


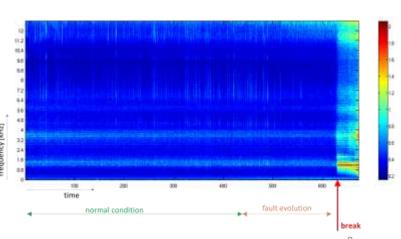
## **Data Processing**

 Collected data need to be analyzed to extract useful information to infer health status:

**➤ Digital Signal Processing** 









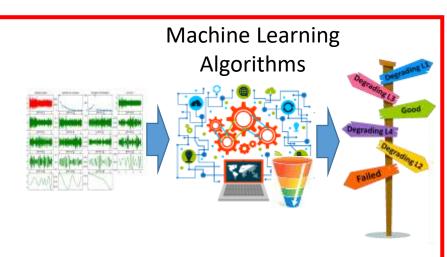
## Decision Making

 The processed data needs to be analyzed to extract health status and to identify the time to failure

➤ Manual analysis: a human operator visually inspects the acquired and processed data and leveraging on his experience guess the lath status and remaining useful life.



Computer based analysis:
Leveraging on decision making support systems like e.g. (deep) machine learning classify the acquired data with health status and predict the remaining useful life.



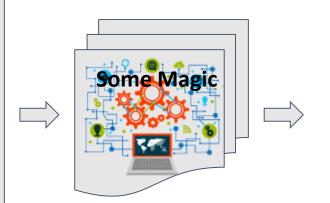


### Machine (deep) learning approach

#### Input

Raw data (eg vibration, temperature, ...) about

- the behaviour of n components (often obtained by ad hoc platforms) until degradation.
- 2. Current (n+1) running component



### Output.

#### Prediction on:

- Health condition (good/degrading/bad/...)
- 2. Remaining useful life (RUL)
- 3. Cause of fault
- 4. ...

### Two steps + some pre-processing:

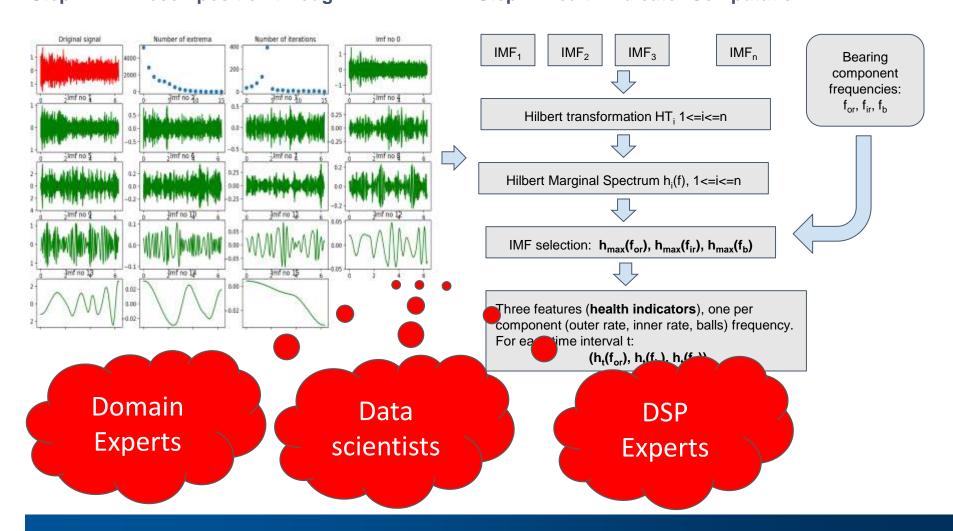
- 1. Pre-processing of data
- Learning to classify (based on ML technique)
- 3. Learning to estimate RUL (support vector regression)
- 4. ...



### Pre-processing and feature extraction

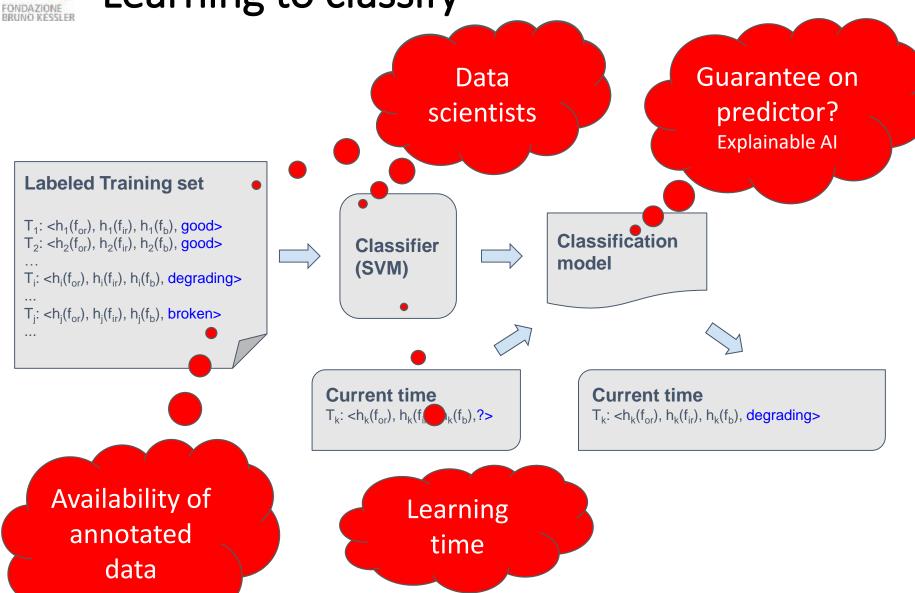
Step 1: IMF Decomposition through EMD

Step 2: Health Indicator Computation



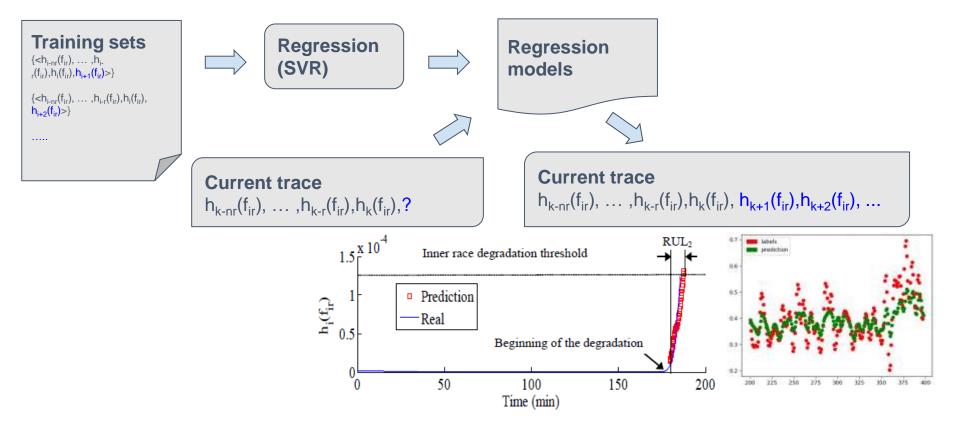


Learning to classify

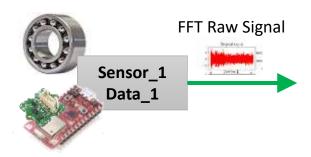




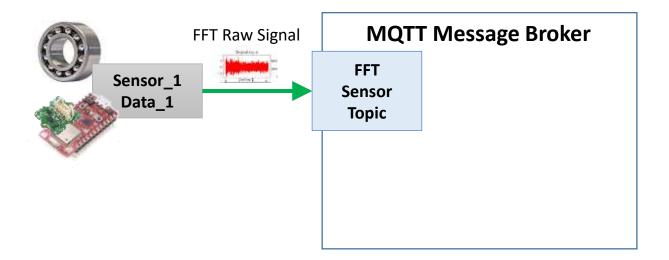
### Learning to predict RUL



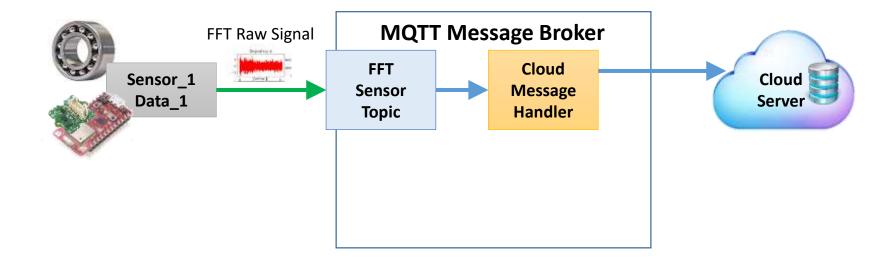




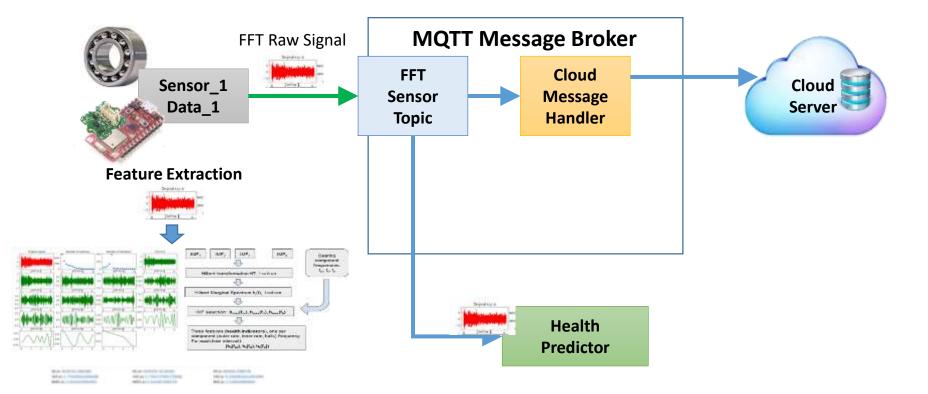




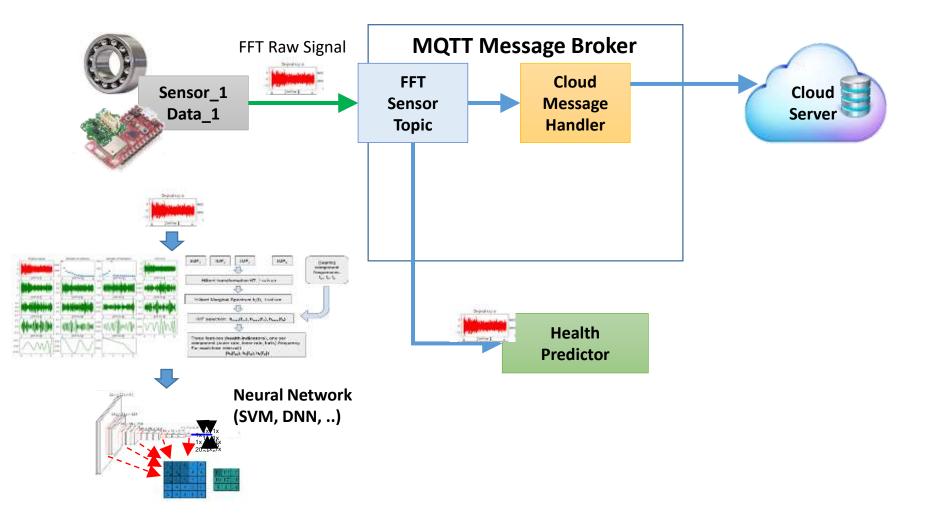




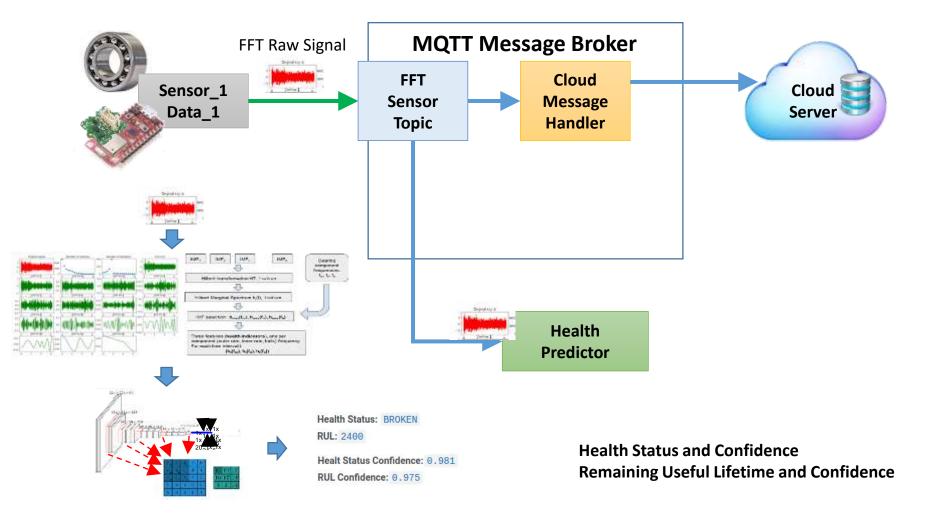




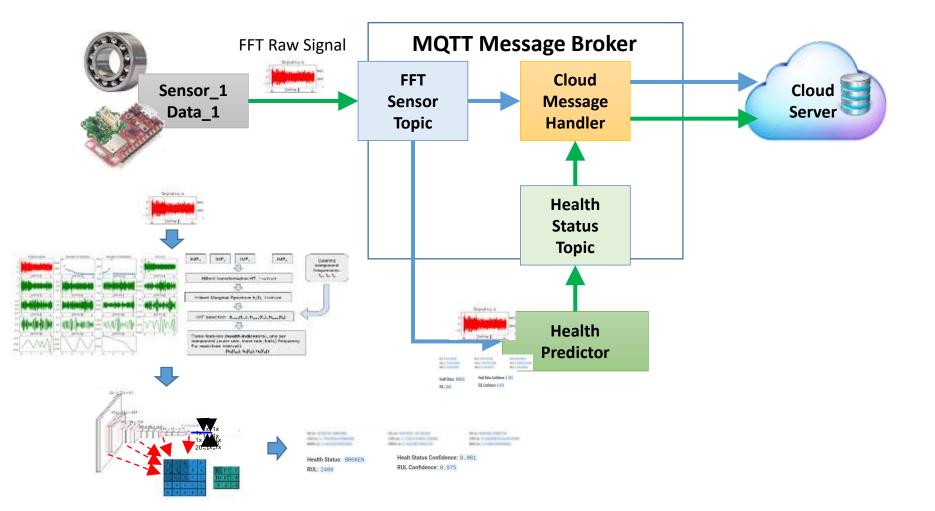




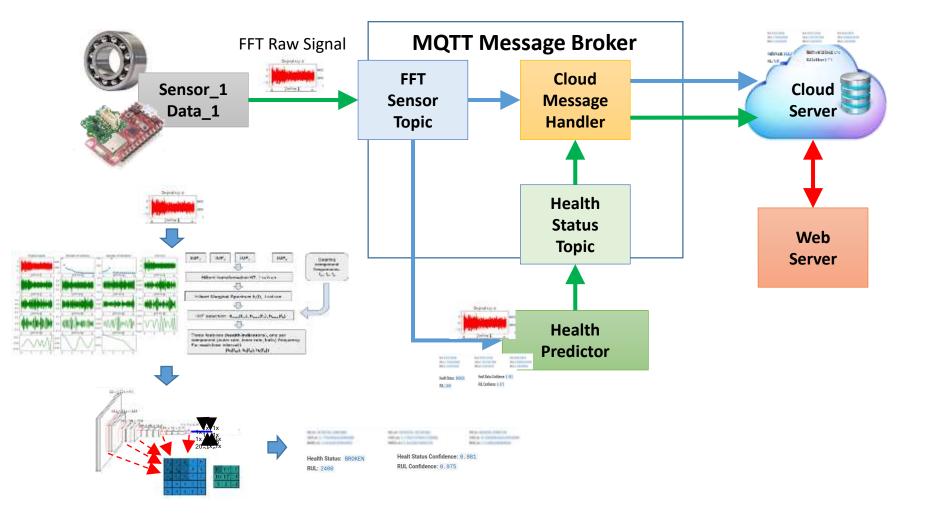




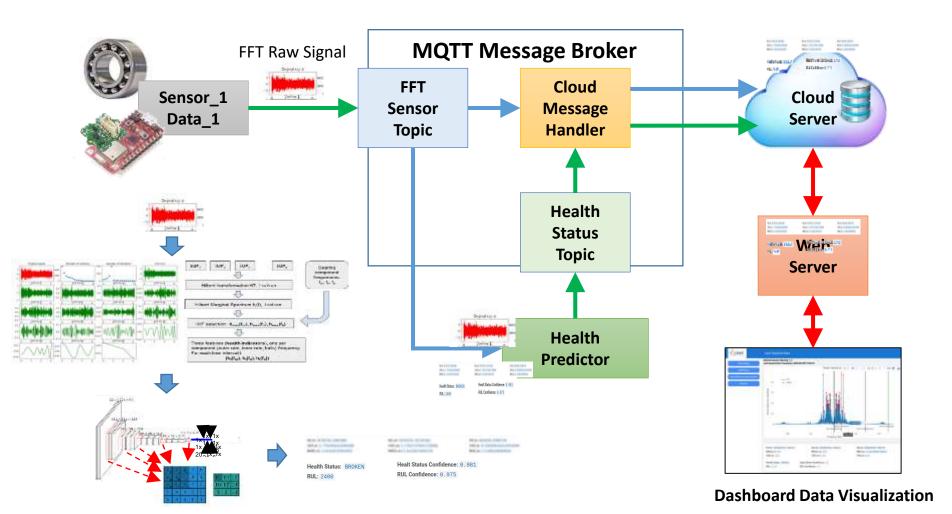
















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- What is Machine Learning?
  - Machine learning is the process of extracting knowledge from data automatically, usually with the goal of making predictions on new, unseen data.
    - Example: a spam filter
      - The user keeps labeling incoming mails as either spam or not spam.
      - A machine learning algorithm then "learns" a predictive model from data that distinguishes spam from normal emails, a model which can predict for new emails whether they are spam or not.
  - Central to machine learning is the concept of automating decision making from data without the user specifying explicit rules how this decision should be made.
    - For the case of emails, the user doesn't provide a list of words or characteristics that make an email spam. Instead, the user provides examples of spam and nonspam emails that are labeled as such.
  - The second central concept is **generalization**. The goal of a machine learning model is to predict on ....
    - For the case of emails, we are not interested in marking an already labeled email as spam or not. Instead, we want to make the user's life easier by automatically classifying new incoming mail.



- There are two kinds of machine learning we will talk about today:
  - supervised learning
  - unsupervised learning
- Supervised Learning: Classification and regression
  - In Supervised Learning, we have a dataset consisting of both input features and a desired output, such as in the spam / no-spam example. The task is to construct a model (or program) which is able to predict the desired output of an unseen object given the set of features.
  - Some more complicated examples are:
    - Given a multicolor image of an object through a telescope, determine whether that object is a star, a quasar, or a galaxy.
    - Given a photograph of a person, identify the person in the photo.
    - Given a list of movies a person has watched and their personal rating of the movie, recommend a list of movies they would like.
    - Given a persons age, education and position, infer their salary
  - What these tasks have in common is that there is one or more unknown quantities associated with the object which needs to be determined from other observed quantities.



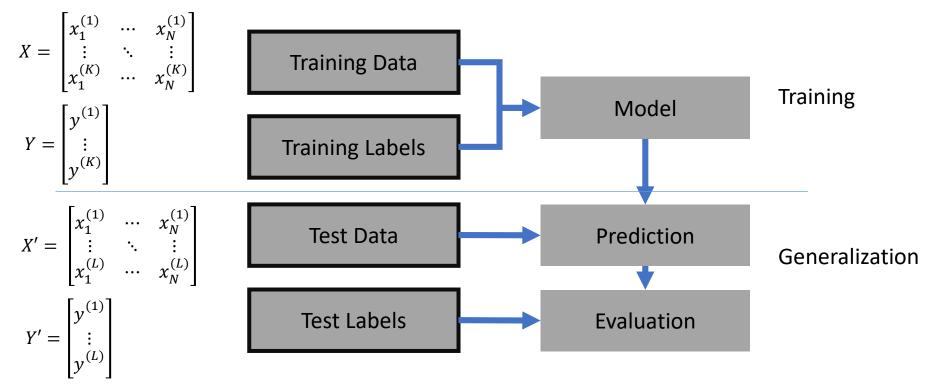
- Supervised learning is further broken down into two categories, classification and regression:
  - In classification, the label is discrete, such as "spam" or "no spam". In other words, it provides a clear-cut distinction between categories. Furthermore, it is important to note that class labels are nominal, not ordinal variables. Nominal and ordinal variables are both subcategories of categorical variable. Ordinal variables imply an order, for example, T-shirt sizes "XL > L > M > S". On the contrary, nominal variables don't imply an order, for example, we (usually) can't assume "orange > blue > green".
  - In regression, the label is continuous, that is a float output. For example, in astronomy, the task of determining whether an object is a star, a galaxy, or a quasar is a classification problem: the label is from three distinct categories. On the other hand, we might wish to estimate the age of an object based on such observations: this would be a regression problem, because the label (age) is a continuous quantity.
- In supervised learning, there is always a distinction between
  - a training set for which the desired outcome is given, and
  - a test set for which the desired outcome needs to be inferred.

The learning model fits the predictive model to the training set, and we use the test set to evaluate its generalization performance.



- Unsupervised Learning
  - In Unsupervised Learning there is no desired output associated with the data. Instead, we are interested in extracting some form of knowledge or model from the given data. In a sense, you can think of unsupervised learning as a means of discovering labels from the data itself. Unsupervised learning is often harder to understand and to evaluate.
  - Unsupervised learning comprises tasks such as dimensionality reduction, clustering, and density estimation. For example, in the iris data discussed later, we can use unsupervised methods to determine combinations of the measurements which best display the structure of the data. Some more involved unsupervised learning problems are:
    - Given detailed observations of distant galaxies, determine which features or combinations of features summarize best the information.
    - Given a mixture of two sound sources (for example, a person talking over some music), separate the two (this is called the blind source separation problem).
    - Given a video, isolate a moving object and categorize in relation to other moving objects which have been seen.
    - Given a large collection of news articles, find recurring topics inside these articles.
    - Given a collection of images, cluster similar images together (for example to group them when visualizing a collection)
- Sometimes the two may even be combined: e.g. unsupervised learning can be used to find useful features in heterogeneous data, and then these features can be used within a supervised framework.





The data is presented to the algorithm usually as a two-dimensional array (or matrix) of numbers. Each data point (also known as a sample or training instance) that we want to either learn from or make a decision on is represented as a list of numbers, a so-called feature vector, and its containing features represent the properties of this point.



0 = Iris Setosa





We represent each flower sample as one row in our data array, and the columns (features) represent the flower measurements in centimeters. For instance, we can represent this Iris dataset, consisting of 150 samples and 4 features, as a 2-dimensional array or matrix  $\mathbb{R}^{150\times4}$ 

$$X = \begin{bmatrix} x_1^{(1)} & x_2^{(1)} & x_3^{(1)} & x_4^{(1)} \\ \vdots & \vdots & \vdots & \vdots \\ x_1^{(150)} x_2^{(150)} x_3^{(150)} x_4^{(150)} \end{bmatrix} \qquad Y = \begin{bmatrix} 0 \\ \vdots \\ 2 \end{bmatrix}$$



```
import matplotlib.pyplot as plt
import numpy as np
from sklearn.datasets import load iris
from sklearn.neighbors import KNeighborsClassifier
from sklearn.model selection import train test split
iris = load iris()
X, y = iris.data, iris.target
classifier = KNeighborsClassifier()
train X, test X, train y, test y = train test split(X, y,
                                                 train_size=0.5,
                                                 test size=0.5,
                                                  random state=123,
                                                  stratify=y)
```



```
print("Labels for training and testing data")
print(train y)
print(test y)
[1110021110102002021100212101112122002
2002222020211022021212110012002210100 1
[0210201200212012222212112200100201001
1220101120111022210011021020211202100 1
print('All:', np.bincount(y) / float(len(y)) * 100.0)
print('Training:', np.bincount(train_y) / float(len(train_y)) * 100.0)
print('Test:', np.bincount(test y) / float(len(test y)) * 100.0)
('All:', array([ 33.33333333, 33.33333333, 33.33333333]))
('Training:', array([ 33.33333333, 33.3333333, 33.3333333]))
('Test:', array([ 33.33333333, 33.33333333, 33.33333333]))
```

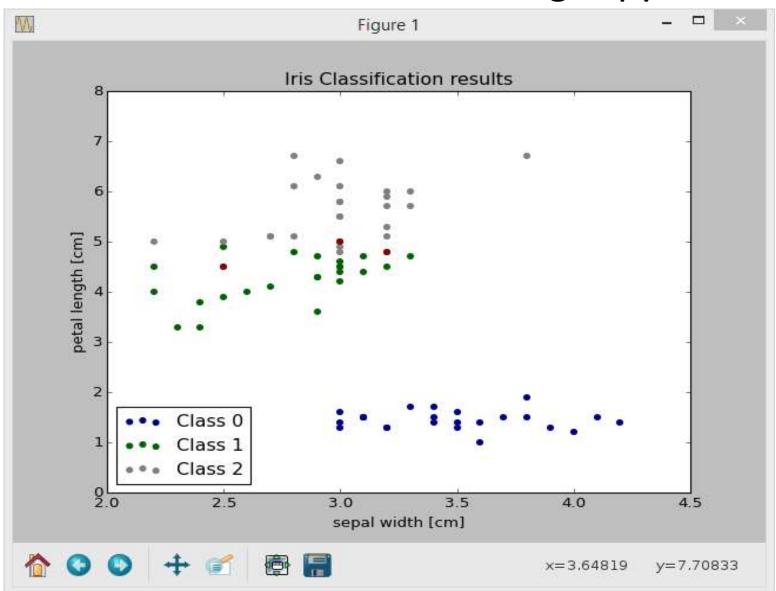


```
classifier.fit(train X, train y)
pred y = classifier.predict(test X)
print("Fraction Correct [Accuracy]:")
print(np.sum(pred y == test y) / float(len(test y)))
Fraction Correct [Accuracy]:
0.96
print('Samples correctly classified:')
correct_idx = np.where(pred_y == test_y)[0]
print(correct idx)
Samples correctly classified:
[0 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24
25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 45 46 47 48 50 51
52 53 54 55 56 57 58 59 61 62 63 64 65 66 67 68 69 70 71 72 73 74
print('\nSamples incorrectly classified:')
incorrect idx = np.where(pred y != test y)[0]
print(incorrect idx)
Samples incorrectly classified:
[44 49 60]
```



```
# Plot two dimensions
colors = ["darkblue", "darkgreen", "gray"]
for n, color in enumerate(colors):
  idx = np.where(test y == n)[0]
  plt.scatter(test X[idx, 1], test X[idx, 2], color=color, label="Class %s" % str(n))
plt.scatter(test X[incorrect idx, 1], test X[incorrect idx, 2], color="darkred")
plt.xlabel('sepal width [cm]')
plt.ylabel('petal length [cm]')
plt.legend(loc=3)
plt.title("Iris Classification results")
plt.show()
```







```
from __future__ import print_function import matplotlib.pyplot as plt import numpy as np from sklearn.datasets import make_blobs
```

There are many classifiers.

Here we see also another dataset

```
X, y = make blobs(centers=2, random state=0)
print('X ~ n samples x n features:', X.shape)
print('y ~ n _samples:', y.shape)
print('\nFirst 5 samples:\n', X[:5, :])
print('\nFirst 5 labels:', y[:5])
plt.scatter(X[y == 0, 0], X[y == 0, 1], c='blue', s=40, label='0')
plt.scatter(X[y == 1, 0], X[y == 1, 1], c='red', s=40, label='1', marker='s')
plt.xlabel('first feature')
plt.ylabel('second feature')
plt.legend(loc='upper right');
plt.show()
```



 $X \sim n_samples \times n_features$ : (100, 2)  $y \sim n_samples$ : (100,)

#### First 5 samples:

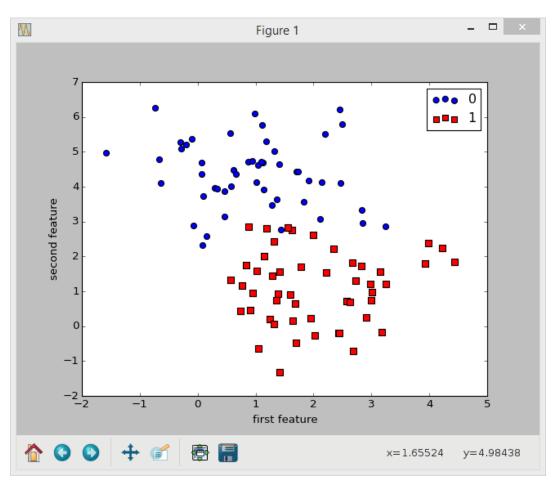
[[ 4.21850347 2.23419161]

[ 0.90779887 0.45984362]

[-0.27652528 5.08127768]

[ 3.24329731 1.21460627]]

First 5 labels: [1 1 0 0 1]



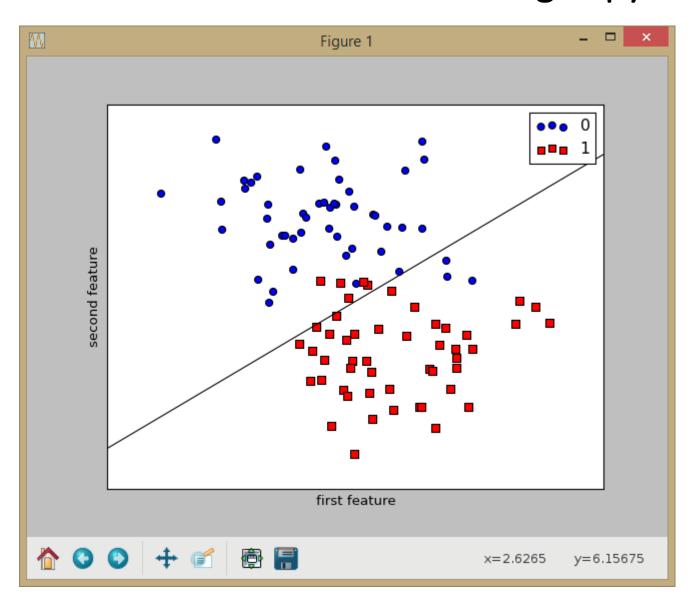


from sklearn.model selection import train test split from sklearn.linear model import LogisticRegression X train, X test, y train, y test = train test split(X, y, test size=0.25, random state=1234, stratify=y) classifier = LogisticRegression() classifier.fit(X train, y train) # We can then apply the model to unseen data and use the model to # predict the estimated outcome using the predict method: prediction = classifier.predict(X test) # We can compare these against the true labels: print(prediction) print(y\_test) [1010111111110000100100110][1110110110100001001001110]



```
# We can evaluate our classifier quantitatively by measuring what
# fraction of predictions is correct. This is called accuracy:
np.mean(prediction == y test)
# There is also a convenience function, score, that all scikit-learn
# classifiers have to compute this directly from the test data:
classifier.score(X test, y test) classifier.score(X test, y test)
# It is often helpful to compare the generalization performance (on the test set) to the
# performance on the training set:
classifier.score(X train, y train)
# LogisticRegression is a so-called linear model, that means it will create a decision that is
# linear in the input space. In 2d, this simply means it finds a line to separate the blue from the red:
from figures import plot 2d separator
plt.scatter(X[y == 0, 0], X[y == 0, 1], c='blue', s=40, label='0')
plt.scatter(X[y == 1, 0], X[y == 1, 1], c='red', s=40, label='1', marker='s')
plt.xlabel("first feature") plt.ylabel("second feature")
plot 2d separator(classifier, X)
plt.legend(loc='upper right')
plt.show()
```



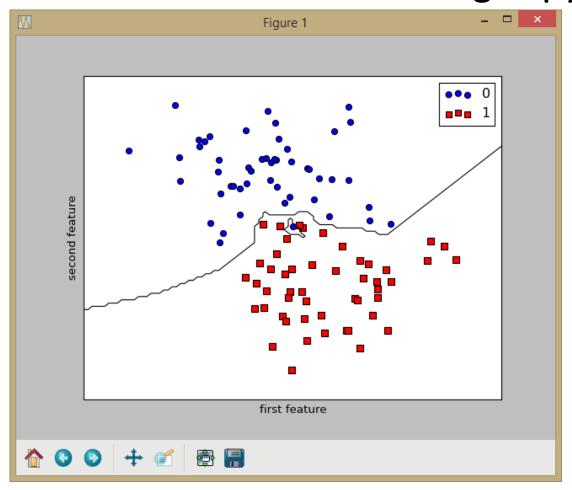




knn.score(X test, y test)

```
# Estimated parameters: All the estimated model parameters are attributes of the estimator object
# ending by an underscore. Here, these are the coefficients and the offset of the line:
print(classifier.coef ) print(classifier.intercept )
# Another popular and easy to understand classifier is K nearest neighbors (kNN). It has one of the
# simplest learning strategies: given a new, unknown observation, look up in your reference database
# which ones have the closest features and assign the predominant class.
from sklearn.neighbors import KNeighborsClassifier
knn = KNeighborsClassifier(n neighbors=1)
# We fit the model with out training data
knn.fit(X train, y train)
plt.scatter(X[y == 0, 0], X[y == 0, 1], c='blue', s=40, label='0')
plt.scatter(X[y == 1, 0], X[y == 1, 1], c='red', s=40, label='1', marker='s')
plt.xlabel("first feature")
plt.ylabel("second feature")
plot 2d separator(knn, X)
plt.legend(loc='upper right');
plt.show()
```





 $\hbox{[[ 1.38092515 -1.49993172]]}$ 

[ 1.54995538]



- Scikit-learn strives to have a uniform interface across all methods. Given a scikit-learn estimator object named model, the following methods are available (not all for each model):
- Available in all Estimators
  - model.fit(): fit training data. For supervised learning applications, this
    accepts two arguments: the data X and the labels y (e.g. model.fit(X, y)). For
    unsupervised learning applications, fit takes only a single argument, the data
    X (e.g. model.fit(X)).
  - model.predict(): given a trained model, predict the label of a new set of data. This method accepts one argument, the new data X\_new (e.g. model.predict(X\_new)), and returns the learned label for each object in the array.
  - model.predict\_proba(): For classification problems, some estimators also provide this method, which returns the probability that a new observation has each categorical label. In this case, the label with the highest probability is returned by model.predict().
  - model.score(): for classification or regression problems, most (all?)
     estimators implement a score method. Scores are between 0 and 1, with a
     larger score indicating a better fit. For classifiers, the score method computes
     the prediction accuracy. For regressors, score computes the coefficient of
     determination (R2) of the prediction.



- After training a scikit-learn model, it is desirable to have a way to persist the model for future use without having to retrain.
  - pickle
  - joblib

from sklearn import svm
from sklearn import datasets
clf = svm.SVC()
iris = datasets.load\_iris()
X, y = iris.data, iris.target
clf.fit(X, y)

import pickle
pickle.dump(clf, 'filename.pkl')
clf1 = pickle.load('filename.pkl')
clf1.predict(X[0:1])

from sklearn.externals import joblib
joblib.dump(clf, 'filename.pkl')
clf2 = joblib.load('filename.pkl')
clf2.predict(X[0:1])



- There are many estimators, and each estimator has a possibly large set of parameters.
- Typically machine learning libraries (e.g. sklearn) provide techniques and tools to perform exhaustive search over specified parameter values for an estimator.
- All estimators at least provide the two important member function: fit and predict.
- GridSearchCV implements a "fit" and a "score" method.
  - It also implements "predict", "predict\_proba", "decision\_function", "transform" and "inverse\_transform" if they are implemented in the estimator used.
  - The parameters of the estimator used to apply these methods are optimized by cross-validated grid-search over a parameter grid.





from sklearn import svm

```
from sklearn.model selection import GridSearchCV
import pikle
# The list of features and labels (all with same size)
f or = [] # array of values for f or
f ir = [] # array of values for f ir
f_b = [] # array of values for f_b
a_or = [] # array of values for a_or
a ir = [] # array of values for a ir
a b = [] # array of values for a b
label = [] # array of values for label
parameters = [{'kernel': ['rbf'], 'gamma': [1e-3, 1e-4],
                 'C': [1, 10, 100, 1000]}.
        {'kernel': ['linear'], 'C': [1, 10, 100, 1000]},
        {'kernel': ['poly'], 'C': [1, 10, 100, 1000]} ]
```

```
svc = svm.SVC()
clf = GridSearchCV(svc, parameters)
clf.fit(list(zip(f_or,f_ir,f_b,a_or,a_ir,a_b))), label)
clf = clf.best_estimator_
pickle.dump(clf, 'filename.pkl')
clf1 = pickle.load('filename.pkl')
newv = [0.45, 0.22, 0.33, 300.4, 200.1, 20.45]
clf1.predict(list(newv))
```





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- MQTT is a machine-to-machine (M2M)/"Internet of Things" connectivity protocol.
- It was designed as an extremely lightweight publish/subscribe messaging transport.
- It is useful for connections with remote locations where a small code footprint is required and/or network bandwidth is at a premium.
- It is also ideal for mobile applications because of its small size, low power usage, minimised data packets, and efficient distribution of information to one or many receivers

- You can Install the python client using PIP with the command
  - pip install paho-mqtt



 The core of the client library is the client class which provides all of the functions to publish messages and subscribe to topics.

- The paho mqtt client class has several methods.
  - The main ones are:
    - connect() and disconnect()
    - subscribe() and unsubscribe()
    - publish()



- Creating a Client Instance
  - The client constructor takes 4 optional parameters, but only the client\_id is necessary, and should be unique.
  - Client(client\_id="", clean\_session=True, userdata=None, protocol=MQTTv311, transport="tcp")
- Connecting to an MQTT Broker or Server
  - Before you can publish messages or subscribe to topics you need to establish a connection to a broker. To do this use the **connect** method of the Python mqtt client. The method can be called with 4 parameters. The connect method declaration is shown below with the default parameters.
  - connect(host, port=1883, keepalive=60, bind address="")
- Publishing Messages
  - Once you have a connection you can start to publish messages. To do this we use the **publish** method. The publish method accepts 4 parameters. The parameters are shown below with their default values.
  - publish(topic, payload=None, qos=0, retain=False)



- Subscribing To Topics
  - To subscribe to a topic you use the subscribe method of the Paho MQTT Class object. The subscribe method accepts 2 parameters – A topic or topics and a QOS (quality of Service) as shown below with their default values.
  - **subscribe**(topic, qos=0)
- When a client subscribes to a topic it is basically telling the broker to send messages sent to that topic to itself.
  - The broker is, in effect, publishing messages on that topic.
  - When the client receives messages it invokes the on\_message callback.
  - To handle those messages we need to activate and process the on\_message callback.
  - To process callbacks you need to:
    - 1. Create callback functions to Process any Messages
    - 2. Start a loop to check for callback messages.



```
def on message(client, userdata, message):
   print("message received ", str(message.payload.decode("utf-8")))
  print("message topic=", message.topic)
  print("message gos=", message.gos)
  print("message retain flag=", message.retain)
# Now we need to attach our callback function to our client object as follows:
                                    #attach function to callback
client.on message=on message
# and finally we need to run a loop otherwise we won't see the callbacks.
# The simplest method is to use loop start() as follows.
client.loop start() #start the loop
```



```
import paho.mgtt.client as mgtt #import the client1
import time
###########
def on_message(client, userdata, message):
   print("message received ", str(message.payload.decode("utf-8")))
   print("message topic=", message.topic)
   print("message qos=", message.qos)
   print("message retain flag=", message.retain)
broker address="192.168.1.184"
print("creating new instance")
client = mqtt.Client("P1") #create new instance
client.on message=on message #attach function to callback
print("connecting to broker")
client.connect(broker_address) #connect to broker
client.loop start() #start the loop
print("Subscribing to topic", "house/bulbs/bulb1")
client.subscribe("house/bulbs/bulb1")
print("Publishing message to topic", "house/bulbs/bulb1")
client.publish("house/bulbs/bulb1", "OFF")
```



- MQTT message payload is a "string".
- Typical data to be sent to a topic is a complex structure
  - e.g. the message with the accelerometer contains
    - The id of the sensor to uniquely identify the sensor
    - The accelerometer values over the sample period
    - The sampling period to properly interpret the sampled data (i.e. the interval among two samples)
    - Timestamp of the acquired data
- The complex structure needs to be serialized to be sent over MQTT, and de-serialized to properly reinterpret the message to analyze it
- There are many data serialization approaches with support for different programming languages
  - https://en.wikinedia.org/wiki/Comparison\_of\_data\_serialization\_formats
  - JSON
  - ASN. 1
  - Pickle
  - SOAP
  - Google Protocol Buffer



# Introduction to JSON in python

- JSON (JavaScript Object Notation) is a lightweight data interchange format inspired by JavaScript object literal syntax (although it is not a strict subset of JavaScript).
- There are several bindings for the different languages. Proper serialization, deserialization are needed for complex structures.

```
import ison
data = { "x" : [10, 20, 30], "y" : [3, 4, 5], "z" : {"a" : 2, "b" : 4}}
print "Original: ", data
data str = json.dumps(data)
data str
print "Encoded: ", data str
dec str = json.loads(data str)
dec str
print "Decoded: ", dec str
client.publish("sensor topic", data str)
• • •
data = json.loads(msg.payload)
```



- What are protocol buffers?
  - Protocol buffers are Google's language-neutral, platformneutral, extensible mechanism for serializing structured data, but smaller, faster, and simpler.
  - You define how you want your data to be structured once, then you can use special generated source code to easily write and read your structured data to and from a variety of data streams and using a variety of languages.
- Pick your favorite language
  - Protocol buffers currently supports generated code in
    - Java
    - Python

    - Objective-C
    - C++
    - Go,
    - JavaNano
    - RubyC#



```
package eu.fbk.promcamp.proto;
message BearingPredictiveData {
                                                        syntax = "proto2";
 required string id = 1;
 required int64 timestamp = 2;
                                                        package eu.fbk.promcap.proto;
 required double MHS f ir = 4;
 required double MHS f or = 5;
 required double MHS f b = 6;
                                                        message BearingData {
 required double H fr = 7;
                                                         required string id = 1;
 required double H f ir = 8;
                                                         required int64 timestamp = 2;
 required double H f or = 9;
                                                         required double delta = 3;
 required double H f b = 10;
                                                         repeated double raw = 4 [packed = true];
 required double HP fr = 11;
                                                        };
 required double HP f ir = 12;
 required double HP f or = 13;
 required double HP f b = 14;
 required double ff = 15;
 required double amp = 16;
 enum BearingStatus { GOOD = 0; DEGRADING = 1; BROKEN = 2; }
 required BearingStatus HealthStatus = 17 [default = GOOD];
 required double HealthStatusConfidence = 18 [default = -1];
 required double RUL = 19 [default = -1];
 required double RULConfidence = 20 [default = -1];
};
```



- To compile the python library protoc –I. file.protoc
- This generates a file file\_pb2.py
- To use it in python

```
Import file_pb2 as pbuf
import datetime
ts = datetime.datetime.now().timestamp()

data = ibm.BearingData()
data.id = "Sensor_ID"

data.timestamp = ts
data.delta = 25641
data.raw[:] = hvibration

Import file_pb2 as pbuf
data = ibm.BearingData()
data = ibm.BearingData()
data.ParseFromString(msg.payload)
print(data.id)
print(data.raw)
```

client.publish("sensor\_topic", data.SerializeToString())



# Thanks for the attention!!