

# Data-driven Model Falsification in Python

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## 1 Data-driven Model Falsification Module

For a theoretical overview on model falsification please see:

1. De, Subhayan, et al. “Investigation of model falsification using error and likelihood bounds with application to a structural system.” *Journal of Engineering Mechanics* 144.9 (2018): 04018078.
2. De, Subhayan, et al. “A hybrid probabilistic framework for model validation with application to structural dynamics modeling.” *Mechanical Systems and Signal Processing* 121 (2019): 961-980.

Download the module from [https://github.com/subhayande/Model\\_Falsification](https://github.com/subhayande/Model_Falsification). See the demo (`fals_test1.py`) for an example of the implementation.

**Required packages:** numpy, scipy, time

NOTE: Currently, only Gaussian distributions for residual errors are allowed and two-sided hypothesis tests are implemented.

Report any bugs to Subhayan.De@colorado.edu

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### 1.1 Procedures implemented

Error-bound and Likelihood-bound model falsification using error criteria:

- Familywise error rate (FWER)
  - Bonferroni
  - Sidák
- False discovery rate (FDR)
  - BH procedure

## 1.2 EBBonferroni

```
=====
|           Error-bound Falsification class using Bonferroni criterion           |
|           (derived from Error-bound Falsification class)                       |
=====

Initialization:
Fals = EBBonferroni(nModels, nMeas, alpha, paramDist, distVar, meas, func,
residualSD)
=====

Attributes:
models:           Model instances
nModels:          Total number of models
nParam:           Number of uncertain parameter in a model
paramDist:        Names of the probability distributions of the uncertain
parameters.
(Currently supports normal/gaussian, uniform, lognormal)
distVar:          Variables of the uncertain parameter distribution
nMeas:            Total number of measurements
predictions:      Predictions by the models
residualSD:       Standard deviation of the residual error
pValues:          p values for predictions from all the models
alphaValues:      alpha values for predictions from all the models
func:             prediction function
version:          version of the code
=====

Methods:
doFalsification:  performs falsification
using Bonferroni correction
inherited:
genModels:        generates all the model instances
funEval:          predicts
getAlphapValues:  calculates alpha and p values
=====

Reference: De, S., Brewick, P.T., Johnson, E.A. and Wojtkiewicz, S.F., 2018
"Investigation of Model Falsification Using Error and Likelihood Bounds
with Application to a Structural System."
Journal of Engineering Mechanics, 144(9), p.04018078.
=====

written by Subhayan De (email:Subhayan.De@colorado.edu)
=====
```

## 1.3 EBSidak

```
=====
|           Error-bound Falsification class using Sidak criterion               |
|           (derived from Error-bound Falsification class)                     |
=====
```

```

Initialization:
Fals = EBSidak(nModels, nMeas, alpha, paramDist, distVar, meas, func,
residualSD)
=====
Attributes:
models:          Model instances
nModels:         Total number of models
nParam:          Number of uncertain parameter in a model
paramDist:       Names of the probability distributions of the uncertain
parameters.
(Currently supports normal/gaussian, uniform, lognormal)
distVar:         Variables of the uncertain parameter distribution
nMeas:           Total number of measurements
predictions:     Predictions by the models
residualSD:      Standard deviation of the residual error
pValues:         p values for predictions from all the models
alphaValues:     alpha values for predictions from all the models
func:            prediction function
version:         version of the code
=====
Methods:
doFalsification: performs falsification using Sidak correction
inherited:
genModels:       generates all the model instances
funEval:         predicts
getAlphapValues: calculates alpha and p values
=====
Reference: De, S., Brewick, P.T., Johnson, E.A. and Wojtkiewicz, S.F., 2018
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=====
written by Subhayan De (email:Subhayan.De@colorado.edu)
=====

```

## 1.4 EBBH

```

=====
|          Error-bound Falsification class using BH procedure          |
|          (derived from Error-bound Falsification class)             |
=====
Initialization:
Fals = EBBH(nModels, nMeas, alpha, paramDist, distVar, meas, func,
residualSD)
=====
Attributes:
models:          Model instances
nModels:         Total number of models

```

```

nParam:          Number of uncertain parameter in a model
paramDist:       Names of the probability distributions of the uncertain
parameters.
(Currently supports normal/gaussian, uniform, lognormal)
distVar:         Variables of the uncertain parameter distribution
nMeas:           Total number of measurements
predictions:     Predictions by the models
residualSD:      Standard deviation of the residual error
pValues:         p values for predictions from all the models
alphaValues:     alpha values for predictions from all the models
func:            prediction function
version:         version of the code
=====

Methods:
doFalsification: performs falsification using BH procedure
inherited:
genModels:       generates all the model instances
funEval:         predicts
getAlphapValues: calculates alpha and p values
=====

Reference: De, S., Brewick, P.T., Johnson, E.A. and Wojtkiewicz, S.F., 2018
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with Application to a Structural System."
Journal of Engineering Mechanics, 144(9), p.04018078.
=====

written by Subhayan De (email:Subhayan.De@colorado.edu)
=====

```

## 1.5 LBBonferroni

```

=====
|      Likelihood-bound Falsification class using Bonferroni criterion      |
|      (derived from Likelihood-bound Falsification class)                  |
=====

Initialization:
Fals = LBBonferroni(nModels, nMeas, alpha, paramDist, distVar, meas, func,
residualSD)
=====

Attributes:
models:          Model instances
nModels:         Total number of models
nParam:          Number of uncertain parameter in a model
paramDist:       Names of the probability distributions of the uncertain
parameters.
(Currently supports normal/gaussian, uniform, lognormal)
distVar:         Variables of the uncertain parameter distribution
nMeas:           Total number of measurements
predictions:     Predictions by the models

```

```

residualSD:      Standard deviation of the residual error
pValues:         p values for predictions from all the models
alphaValues:     alpha values for predictions from all the models
func:           prediction function
version:         version of the code
=====
Methods:
doFalsification:      performs falsification using
Bonferroni criterion
inherited:
genModels:           generates all the model instances
funEval:             predicts
getAlphaValues:      calculates alpha and p values
=====
Reference: De, S., Brewick, P.T., Johnson, E.A. and Wojtkiewicz, S.F., 2018
"Investigation of Model Falsification Using Error and Likelihood Bounds
with Application to a Structural System."
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=====
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=====

```

## 1.6 LBSidak

```

=====
|      Likelihood-bound Falsification class using Sidak criterion      |
|      (derived from Likelihood-bound Falsification class)            |
=====
Initialization:
Fals = LBSidak(nModels, nMeas, alpha, paramDist, distVar, meas, func,
residualSD)
=====
Attributes:
models:      Model instances
nModels:     Total number of models
nParam:      Number of uncertain parameter in a model
paramDist:   Names of the probability distributions of the uncertain
parameters.
(Currently supports normal/gaussian, uniform, lognormal)
distVar:     Variables of the uncertain parameter distribution
nMeas:       Total number of measurements
predictions: Predictions by the models
residualSD:  Standard deviation of the residual error
pValues:     p values for predictions from all the models
alphaValues: alpha values for predictions from all the models
func:        prediction function
version:     version of the code
=====

```

```

Methods:
doFalsification:      performs falsification using
Bonferroni criterion
inherited:
genModels:           generates all the model instances
funEval:             predicts
getAlphapValues:     calculates alpha and p values
=====
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```

## 1.7 LBBH

```

=====
|           Likelihood-bound Falsification class using BH procedure           |
|           (derived from Likelihood-bound Falsification class)               |
=====
Initialization:
Fals = LBBH(nModels, nMeas, alpha, paramDist, distVar, meas, func,
residualSD)
=====
Attributes:
models:           Model instances
nModels:          Total number of models
nParam:           Number of uncertain parameter in a model
paramDist:        Names of the probability distributions of the uncertain
parameters.
(Currently supports normal/gaussian, uniform, lognormal)
distVar:          Variables of the uncertain parameter distribution
nMeas:            Total number of measurements
predictions:      Predictions by the models
residualSD:       Standard deviation of the residual error
pValues:          p values for predictions from all the models
alphaValues:      alpha values for predictions from all the models
func:             prediction function
version:          version of the code
=====
Methods:
doFalsification:      performs falsification using
Bonferroni criterion
inherited:
genModels:           generates all the model instances
funEval:             predicts

```

```

getAlphapValues:    calculates alpha and p values
=====
Reference: De, S., Brewick, P.T., Johnson, E.A. and Wojtkiewicz, S.F., 2018
"Investigation of Model Falsification Using Error and Likelihood Bounds
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Journal of Engineering Mechanics, 144(9), p.04018078.
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=====

```

## 2 Example

NOTE: Implementation of this example is in:

fals\_test1.py

Consider the following linear regression problem:

$$y = 3 + 4.5x + \text{noise} \quad (1)$$

where the regression parameters are  $\theta = [3, 4.5]^T$ . Using 200 measurements the above methods are implemented. The priors for the coefficients are assumed as  $\mathcal{U}(2, 5)$  and  $\mathcal{N}(4, 0.5^2)$ , *i.e.*, uniform and Gaussian, respectively. The problem is initialized using

```

# number of measurements
nMeas = 200

# parameters
w1 = 3.0
w2 = 4.5

# noisy data
X = 2.0*np.random.rand(nMeas,1)
np.savetxt('fals1_data.txt',X)
y = w1 + w2 * X + np.random.randn(nMeas,1)

# Model definition
thetaDist = np.array(['uniform','normal'])
modelDistVar = np.array([[2,5],[4.0,0.5]])

def fun(param):
    """
    function to calculate model predictions
    """
    X = np.loadtxt('fals1_data.txt')
    pred = param[0] + param[1]*X
    return pred

```





```
fls.doFalsification() # perform falsification
```

Using Error-bound model falsification with Sidak criterion

### STEP I: Generating candidate models

## STEP II: Predicting using candidate models

### STEP III: Calculating alpha and p values

STEP IV: Falsifying models

Number of unfalsified models = 572

### 2.3 EBBH

```
fls = EBBH(nModels =1000, nMeas=nMeas, alpha=0.05,
```

```
fls.doFalsification() # perform falsification
```

### Using Error-bound model falsification with BH procedure

Percent unfalsified = 50.70 %

```
fls = LBBonferroni(nModels = 1000, nMeas=nMeas, alpha=0.05,
                  paramDist=thetaDist, distVar=modelDistVar,
                  meas = y, func = fun, residualSD = 0.4) # initialize
```

```
fls.doFalsification() # perform falsification
```

The output is the following:

Using Likelihood-bound model falsification with Bonferroni criterion

Total number of models = 1000

-----  
STEP I: Generating candidate models

Likelihood-bound Bonferroni criterion  
|██| 100.0% Complete:  
Time Elapsed = 0.0s

-----  
STEP II: Predicting using candidate models

Likelihood-bound Bonferroni criterion  
|██| 100.0% Complete:  
Time Elapsed = 1.96s

-----  
STEP III: Calculating alpha and p values

Likelihood-bound Bonferroni criterion  
|██| 100.0% Complete:  
Time Elapsed = 79.68s

-----  
STEP IV: Calculating likelihood of the candidate models

Likelihood-bound Bonferroni criterion  
|██| 100.0% Complete:  
Time Elapsed = 111.81s

-----  
STEP V: Falsifying models

Likelihood-bound Bonferroni criterion  
|██| 100.0% Complete:  
Time Elapsed = 112.08s

Number of unfalsified models = 595

## 2.5 LBSidak

```
fls = LBSidak(nModels = 1000, nMeas=nMeas, alpha=0.05,
              paramDist=thetaDist, distVar=modelDistVar,
              meas = y, func = fun, residualSD = 0.4) # initialize
```

-----  
STEP V: Falsifying models

Likelihood-bound Sidak criterion | [REDACTED] |  
100.0% Complete:  
Time Elapsed = 111.52s

Number of unfalsified models = 592

Percent unfalsified = 59.20 %

## 2.6 LBBH

```
from Falsification import LBBH
```

```
fls = LBBH(nModels = 1000, nMeas=nMeas, alpha=0.05,  
           paramDist=thetaDist, distVar=modelDistVar,  
           meas = y, func = fun, residualSD = 0.4) # initialize
```

```
fls.doFalsification() # perform falsification
```

The output is the following:

Using Likelihood-bound model falsification with BH procedure

Total number of models = 1000

-----  
STEP I: Generating candidate models

Likelihood-bound BH procedure | [REDACTED] | 100.0% Complete:  
Time Elapsed = 0.0s

-----  
STEP II: Predicting using candidate models

Likelihood-bound BH procedure | [REDACTED] | 100.0% Complete:  
Time Elapsed = 1.97s

-----  
STEP III: Calculating alpha and p values

Likelihood-bound BH procedure | [REDACTED] | 100.0% Complete:  
Time Elapsed = 80.2s

#### STEP IV: Calculating likelihood of the candidate models

-----

## STEP V: Falsifying models

Number of unfalsified models = 185

Percent unfalsified = 18.50 %