

Ch2notes

2020年10月13日 星期二 19:04

Note: (*) means skip in the presentation.

All surface means surface without boundary.

I. Surfaces.

1 Definitions and Facts

Classification of closed surfaces.

Triangulation.

Def: Two triangle share an edge are consistently oriented if they induce opposite orientations on the shared edge.

Thm: M is orientable \Leftrightarrow The triangles can be oriented in such way that adjacent pair are consistently oriented.

Example: T^2 : 

Klein bottle:



not consistent

Def: For a finite triangulation, $n = \#$ vertices, $m = \#$ edges, $\ell = \#$ triangles. The Euler characteristic $\chi(S) = n - m + \ell$

Thus we have $\chi(gT^2) = 2 - 2g$ $\chi(gP^2) = 2 - g$, g is genus.

△ Doubling (*).

The compact non-orientable surface can be obtained from the orientable surface by identifying points in pairs.

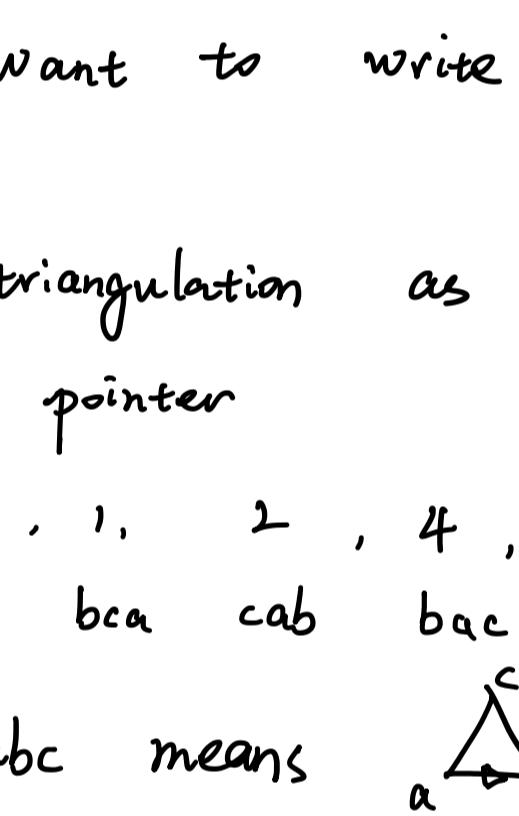
Example: $S^2 / \{x \sim -x\} = RP^2$.

Want to do the other direction;

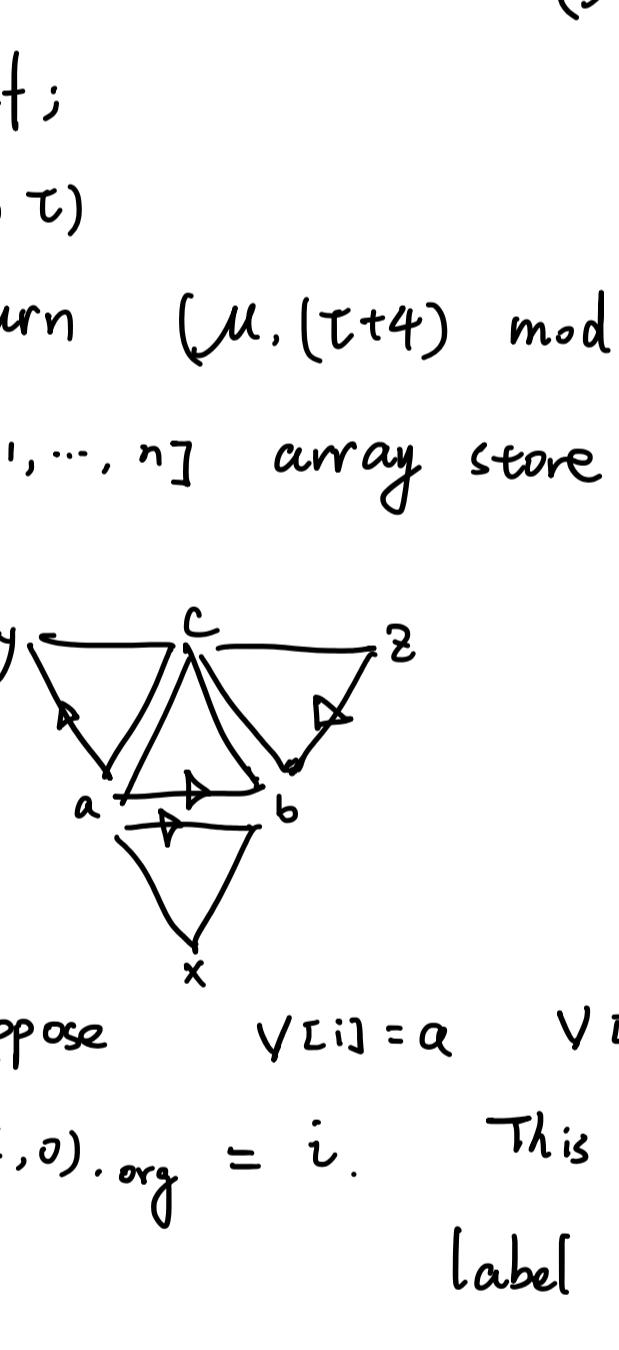
Let N = compact connected non-orientable surface.

Get a triangulation \rightarrow make two copy of each triangle, edge, vertex. \rightarrow get connected surface M , M is orientable since one side is consistently facing N .

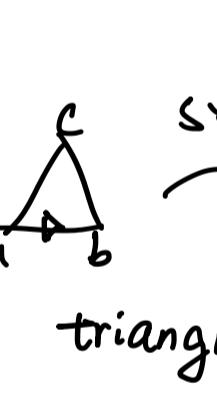
Example: Klein bottle



Double



That is



T^2

identify these two edges
get consistently oriented
triangles.

Since all triangles, edges, vertices doubled, $\chi(M) = 2\chi(N)$

$$2 - 2g(M) = 2(2 - g(N)) \Rightarrow g(M) = g(N) - 1.$$

II. Classification.

Goal: Determine the surface from the given triangulation. K .

Observe: each triangle has 3 edges, each edge belong 2 triangles. So $3\ell = 2m$

$$\Rightarrow \begin{cases} 2n - \ell = 4 - 4g & \text{if orientable} \\ 2n - \ell = 4 - 2g & \text{if nonorientable} \end{cases}$$

If already know # vertices n , suffices to get orientability and ℓ to determine the surface.

Genus

$$\ell = \text{Triangles};$$

$$\text{if isOrientable then return } (\ell - 2n + 4)/4$$

$$\text{else return } (\ell - 2n + 4)/2.$$

endif;

Now, want to write the function Triangles and isOrientable

View triangulation as a graph, triangles = nodes (μ, τ)

μ is a pointer

$\tau = 0, 1, 2, 4, 5, 6$ order of a triangle

abc bac cab bac cba acb

Here abc means 

ENEXT(μ, τ)

if $\tau \in 2$ then return $(\mu, (\tau+1) \bmod 3)$

else return $(\mu, (\tau+1) \bmod 3 + 4)$

endif;

SYM(μ, τ)

return $(\mu, (\tau+4) \bmod 8)$

Let $V[1, \dots, n]$ array store vertices of triangulation K

Example:

Suppose $V[i] = a$ $V[j] = b$ $V[k] = c$.

$(\mu, 0).org = i$. This means the first vertex in the label $\tau=0$ in triangle μ .

$(\mu, 0).fnext = (\mu_x, 0)$ This means a triangle share with an edge μ , the edge given by first two vertex in label $\tau=0$ in triangle μ .

More examples: $(\mu, 1).org = j$ $(\mu, 1).fnext = (\mu_x, 1)$.

We will use Depth-First Search (DFS) to search the graph.

VISIT(μ)

if μ is unmarked then mark μ ; P_1 ;

for all nbhd v of μ do

VISIT(v)

end for; P_2 ;

else P_3 ;

endif;

Here P_1, P_2, P_3 are operations need to do.

For triangles,

Int Triangle(μ, τ)

if μ is unmarked then mark μ

$\ell_x = \text{Triangle}(\text{SYM}(\mu, \tau).fnext)$

$\ell_y = \text{Triangle}(\text{ENEXT}(\text{SYM}(\mu, \tau).fnext))$

$\ell_z = \text{Triangle}(\text{ENEXT}(\text{SYM}(\mu, \tau).fnext))$

return $\ell_x + \ell_y + \ell_z$

else return 0

endif;

Note: We can view $S^2 \cong$ and use this as

an example to compute orientability and triangles to be familiar with the programs.