

CMSC 828T Activity Recognition from Group Context

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In this project, we will work on Activity Recognition of people in images and videos. In traditional activity recognition, each person is analyzed independently from others. For instance, if we look at a single person standing, we do not know whether he/she is talking with others, being in a queue or waiting for someone. However, if we take into account other people in the scene as a context, we will be able to identify more detailed activity of the person. For instance, if there are multiple people forming a line, facing towards the same direction, it is likely that they are in a line. If there are two people facing each other, most likely they are talking each other. Thus, our goal is to identify each person's activity with considering a context from other people.

Our system needs the following steps to obtain an input to the high level activity recognition tasks. First, people in each frame are detected using a standard pedestrian detector. Then the orientation of each person is estimated by a trained estimator. Each person's location is represented as a point on a 2D plane using the camera parameters and the size of the detection. Tracking is done by considering the moving distance. This spatial and temporal information is used to analyze the activity of the people.

For the activity recognition task, we take a learning-based approach, where we have an access to a database of videos with activity class label associated to each person. The detection, orientation estimation and tracking is done on them. We will come up with algorithms which utilize the training data to detect and recognize the activity in testing videos.

In this project, we assume that people in a group (i.e., people talking each other) have the same activity label. Thus, before processing the test video, we cluster people in the scene into different groups, each of which is conducting independent activity.

The clustering can be done based on the distance between each person.

Manifold Based Approach

One of the approaches would be based on nearest neighbor matching. From the training dataset, we mathematically represent each group activity by capturing each person's movement as well as the group interaction. With such representation, we define a proper distance between two instances of the group activity. This distance should be smaller if two activities are same and larger if not. The group activity recognition is done by finding the instance in the training database which is the closest to the given test instance. We will represent group activity as a point on a special Euclidean group, which is a Riemannian manifold and define a distance as a geodesic distance on the manifold.

Context free Grammars(CFG)

Another approach that we intend to take will be based on Context free Grammars (CFG). We want to represent atomic actions (actions performed by individuals) in terms of strings drawn from a predefined knowledge base. For defining the atomic actions we use the pose and trajectory information that is available to us as input. Once we obtain the atomic action descriptions, we can build an *activity tree* for each individual per frame. This would also then indicate how the action evolves over frames. The group activity description will be obtained by merging the individual trees in a suitable way. The two main concerns here are : to find a method to represent group activities using compositions of individual activity trees and finding a *distance measure* to compare two activity trees.