- ☆ Framework: pytorch
- ☆ Requirements: see requirements.txt

```
torch==1.11.0+cu113
torchvision==0.12.0+cu113
torchsummary==1.5.1
numpy==1.21.6
matplotlib==3.2.2
sklearn==0.0
Pillow==7.1.2
```

☆ Model architecture: Resnet152

The original Resnet architecture is shown in resnet_arch.png.

Resnet152 is its variant with a larger size and more layers.

The fully connected layer is changed to output size of 10. The final architecture can be viewed in **torch_summary.txt.**

- ☆ Model source: **Pretrained model resnet152** from pytorch
- ☆ Hyperparameters:
 - Adam optimizer with learning rate (0.001) and weight decay (1e-5)
 - Cross Entropy Loss
 - learning rate scheduler (Decays the learning rate of each parameter group by gamma every step size epochs.)
 - batch size 512
 - trained without freezing layers.

☆ Data size: Training data size 47000, validation data size 3000

- ☆ Data preprocessing & augmentation:
 - train: random horizontal flip, normalization

val: normalizationtest: normalization

```
data_transforms = {
    'train': transforms.Compose([
        # transforms.Resize((256, 256)),
        # transforms.RandomCrop((224, 224)),
        transforms.RandomHorizontalFlip(),
        transforms.ToTensor(),
        transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
    1),
    'val': transforms.Compose([
       # transforms.Resize(256),
       # transforms.CenterCrop(224),
       transforms.ToTensor(),
        transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
    1),
    'test': transforms.Compose([
        # transforms.Resize(256),
        # transforms.CenterCrop(224),
        transforms.ToTensor(),
        transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
   1
```

☆ Environment & organization:

All source code is contained in **0811521_HW5.ipynb** and **inference.ipynb**, which I run at Colab. The model weights and data are loaded from google drive (need authentication).

0811521_HW5.ipynb:

This will import pretrained model, and then train and evaluate the model. The paths for data can be configured at the beginning.

```
from google.colab import drive
drive.mount('/content/drive')

Mounted at /content/drive

[2] path1 = "/content/drive/MyDrive/Current path2 = "/content/drive/MyDrive/Current path3 = "/content/drive/MyDrive/Current path3 = "/content/drive/MyDrive/Current path4 = "/content/drive/MyDrive/Current path4 = "/content/drive/MyDrive/Current path4 = "/content/drive/MyDrive/Current workspace/Pattern Recognition/x_test.npy" # x_test
path4 = "/content/drive/MyDrive/Current workspace/Pattern Recognition/y_test.npy" # y_test
```

inference.ipynb:

I have trained the model and stored its model weights. **inference.py** will load the weights and evaluate the model. The model weights are stored in **resnet152_wt.pth**. The paths for data and model weights can be configured at the beginning.

```
from google.colab import drive
drive.mount('/content/drive')

Mounted at /content/drive

path1 = "/content/drive/MyDrive/Current path2 = "/content/drive/MyDrive/Current path3 = "/content/drive/MyDrive/Current path4 = "/content/drive/MyDrive/Current path4 = "/content/drive/MyDrive/Current by Workspace/Pattern Recognition/x_test.npy" #x_test path4 = "/content/drive/MyDrive/Current by Workspace/Pattern Recognition/y_test.npy" #y_test by LOAD_WEIGHT_PATH = "/content/drive/MyDrive/Current by Workspace/Pattern Recognition/y_test.npy" #y_test
```

☆ Result & Accuracy:

```
[35] model = torchvision.models.resnet152(pretrained=True)
    num_ftrs = model.fc.in_features
    model.fc = nn.Linear(num_ftrs, 10)
    model = model.to(device)
    model.load_state_dict(torch.load(LOAD_WEIGHT_PATH))

[36] y_pred = predict(model)
    print(y_pred)

    [1 5 3 ... 8 8 1]

[37] assert y_pred.shape == (10000,)

[38] y_test = np.load(path4)
    y_test = y_test.reshape(len(y_test))
    print("Accuracy of my model on test set: ", accuracy_score(y_test, y_pred))

Accuracy of my model on test set: 0.8739
```