

Exercise (Success amplification by majority voting). Let \mathbb{G} be a finite q -element group such that all elements $y \in \mathbb{G}$ can be expressed as powers of $g \in \mathbb{G}$. Let \mathcal{A} be an algorithm for finding the most significant bit of discrete logarithm such that $\Pr[\mathcal{A}(y) \text{ guesses correctly}] \geq \varepsilon > \frac{1}{2}$ for any $y \in \mathbb{G}$. Construct an algorithm that fails with probability 2^{-n} . Show that it is possible to give a construction with the running-time that is linear in n and quadratic in $1/(\varepsilon - \frac{1}{2})$.

Solution. SIMPLE AMPLIFICATION. According to the assumptions the probability that $\mathcal{A}(y)$ returns correctly the most significant bit is at least $\varepsilon > \frac{1}{2}$ for all $y \in \mathbb{G}$. This assumption automatically excludes probability that \mathcal{A} is a deterministic algorithm. Indeed, if \mathcal{A} is deterministic then for any y it either outputs a correct answer or not. As the probability of outputting the correct answer is nonzero for all $y \in \mathbb{G}$, the deterministic \mathcal{A} must output the correct output for all $y \in \mathbb{G}$ and there is nothing for us to do further. If \mathcal{A} is a randomised algorithm, then depending on the randomness we get sometimes correct and sometimes incorrect answers for a fixed input y . By the assumption the fraction of correct answers is at least ε . In particular, not that if we run $\mathcal{A}(y)$ twice with freshly chosen randomness we get two independent samples from the set of all answers. Therefore, we can define the amplification algorithm as follows:

$$\mathcal{B}^{\mathcal{A}}(m, y) \quad \left[\begin{array}{l} \text{For } i \in \{1 \dots m\} \text{ do} \\ \quad [x_i \leftarrow \mathcal{A}(y)] \\ s \leftarrow x_1 + \dots + x_m \\ \textbf{return } [2 \cdot s > m] \end{array} \right. .$$

Now recall the Hoeffding bound. Let X_1, \dots, X_m be independent samples from a fixed zero-one distribution such that the probability of one is α . Then the probability that the sum of these individual samples $S = X_1 + \dots + X_m$ is significantly less than mathematical expectation $\mathbf{E}(S)$ is negligible:

$$\Pr[\mathbf{E}(S) - S \leq m \cdot \delta] \leq \exp(-2m\delta^2) .$$

For the analysis let us consider the case, when the the correct answer is one. Then by our assumption the probability that $\mathcal{A}(y)$ returns one is at least ε . On the same time \mathcal{B} returns one only if the majority of x_i -s are ones. That is we can express the failure probability as follows:

$$\begin{aligned} \Pr[x_1 + \dots + x_m \leq m/2] &= \Pr[m\varepsilon - (x_1 + \dots + x_m) \leq m\varepsilon - m/2] \\ &\leq \Pr[\mathbf{E}(x_1 + \dots + x_m) - (x_1 + \dots + x_m) \leq m(\varepsilon - 1/2)] . \end{aligned}$$

As the right-hand side of the inequality corresponds to the left-hand side of the Hoeffding bound, we get

$$\Pr[x_1 + \dots + x_m \leq m/2] \leq \exp(-2m(\varepsilon - 1/2)^2)$$

Thus, we can guarantee that the failure probability is below 2^{-n} if

$$\exp(-2m(\varepsilon - 1/2)^2) \leq 2^{-n} \iff n \ln 2 \leq 2m(\varepsilon - 1/2)^2 .$$

The latter provides a lower bound for required samples:

$$m \geq \frac{n \ln 2}{2(\varepsilon - 1/2)^2} ,$$

which is indeed linear in n and quadratic in $1/(\varepsilon - \frac{1}{2})$. The analysis of the case where the correct answer is zero is symmetrical — again the decision bound $m/2$ is quite far from the expected number of ones.

CONSTRUCTION OF THE DISCRETE LOGARITHM SOLVER. Recall that it was possible to reconstruct the full discrete logarithm if we had a perfect solver \mathcal{B}_o for the most significant bit. Let us quickly recall the

corresponding construction \mathcal{C} under the assumption that the size of \mathbb{G} is below 2^k . Let $y = g^x$ where $x = x_k \dots x_0$ in binary. Let $\text{msb}(x) = x_k$ denote the most significant bit of x . Then clearly

$$y_1 = g^{x_{k-1} \dots x_0 0} = y \cdot g^{\text{msb}(x)}$$

and we can use the most significant bit solver \mathcal{B}_o for y_1 to recover x_{k-1} . By repeating this procedure, we can recover all bits of x by making k calls to \mathcal{B}_o :

$$\begin{array}{l} \mathcal{C}^{\mathcal{B}_o}(y) \\ \quad \left[\begin{array}{l} \text{For } i = k, \dots, 0 \text{ do} \\ \quad \left[\begin{array}{l} x_i \leftarrow \mathcal{A}_1(y) \\ y \leftarrow y^2 g^{-2x_i} \end{array} \right] \\ \text{return } x_k \dots x_0 \end{array} \right. \end{array}$$

If the solver \mathcal{B} for the most significant bit is guaranteed to succeed with probability at least δ for any $y \in \mathbb{G}$, then it reconstructs the correct answer with the probability at least δ^k . To get a bigger success probability, we can use standard discrete logarithm amplification technique for \mathcal{C} . Due to the quasi-linearity of this amplification scheme, ℓ repetitions of \mathcal{C} increases the success probability approximately ℓ times.

This leads us to an interesting tradeoff issue. Given an initial solver \mathcal{A} for the most significant bit, we can first amplify its success by constructing the majority vote amplifier \mathcal{B} with m -fold repetition and then doing an additional amplification by running ℓ times the discrete logarithm solver \mathcal{C} . As a result, different choices of m and ℓ can lead to the same success probability. Let us analyse the situation in more detail to determine the optimal ratio between parameters. First, note that for fixed ε and m the success probability

$$\delta \geq 1 - \exp(-2m(\varepsilon - 1/2)^2)$$

and thus the overall failure probability after ℓ reruns of \mathcal{C} is not larger than

$$\Pr[\text{Failure}] = \left(1 - \left(1 - \exp(-2m(\varepsilon - 1/2)^2)\right)^k\right)^\ell \approx \left(k \cdot \exp(-2m(\varepsilon - 1/2)^2)\right)^\ell,$$

which itself implies

$$\log \Pr[\text{Failure}] \approx \ell \cdot \log k - 2\ell \cdot m(\varepsilon - 1/2)^2.$$

By looking to the equation, we see that the second term remains constant as long as $\ell \cdot m$ remains constant and the first term increases when we increase ℓ . Consequently, an approximately optimal solution is to choose $\ell = 1$ and choose m large enough to get the desired failure probability.

ON THE RANDOM SELF-REDUCIBILITY OF THE MOST SIGNIFICANT BIT. All these reductions so far assume that the success probability \mathcal{A} is uniformly large for any $y \in \mathbb{G}$. In practice, we might encounter an algorithm, for which the probability of correct answer is $\varepsilon > \frac{1}{2}$ only if y is chosen uniformly from \mathbb{G} . Hence, we might ask is it possible to convert a particular most significant bit instance to a random most significant bit instance.

This seems to be a difficult task for the following reason. Let $x = x_k \dots x_0$ and $\bar{x} = \bar{x}_k \dots \bar{x}_0$. Then the standard rerandomisation procedure $\bar{y} = y \cdot g^{\bar{x}}$ leads to the new most significant bit $\text{msb}(x + \bar{x} \bmod q)$. The latter is difficult to predict even if $x + \bar{x} < q$, since

$$\text{msb}(x + \bar{x}) \begin{cases} x_k \oplus \bar{x}_k, & \text{if } x + \bar{x} < q \wedge x_{k-1} \dots x_0 + \bar{x}_{k-1} \dots \bar{x}_0 < 2^k, \\ 1 \oplus x_k \oplus \bar{x}_k, & \text{if } x + \bar{x} < q \wedge x_{k-1} \dots x_0 + \bar{x}_{k-1} \dots \bar{x}_0 \geq 2^k \end{cases}$$

and we have no information about the tail $x_{k-1} \dots x_0$.