Codechef Learn, Episode 1 Lec-1 **Square Root Decomposition on Trees**

https://youtu.be/g5g1UqSjOIQ

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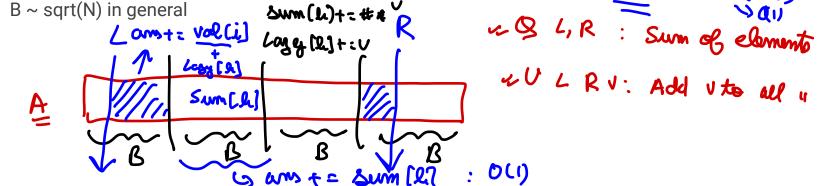
Square Root Decomposition Recap

There are 4 different types of "standard" Square Root Decomposition techniques:

- Array Square Root Decomposition
- (Lookahead) Query Square Root Decomposition
- MOs Algorithm (+ updates)
- Heavy Set / Light Set based Query Decomposition

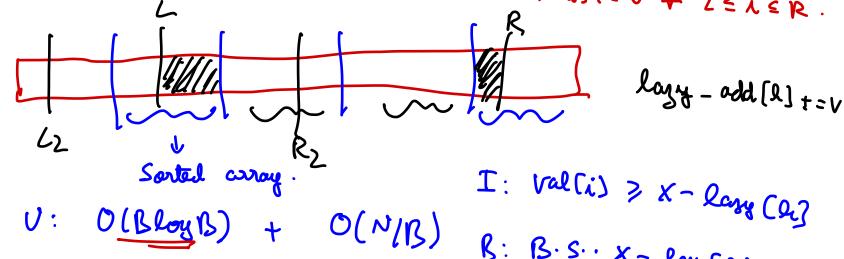
Recap: Array Square Root Decomposition

- Step-1: Divide the array of N elements into N / B blocks of size B.
- Step-2: Maintain some data structure / information for every block b.
 - o The DS should support query and updates in time sublinear(B), مركا کارلا) ما
- Step-3: Support a query/update on range [L, R] by
 - Iterating over individual elements for blocks of L and R, takes O(2 * B) ~ O(B * sublinear(B))
 - Iterating over at-most N / B blocks in between L and R and use the data structure maintained + some lazy update information for query & updates takes O(N / B * sublinear(B))



Recap: Array Square Root Decomposition

- Given an array A of N elements, support the following operations:
 - Query LRX: Tell number of elements > (X) in [L, R] st. A(i) > X where L \(\xi \xi \xi \xi.\)



- 2) 0: 0(2B) + 0(N/B* log B)

Recap: Array Square Root Decomposition

- Given an array A of N elements, support the following operations:
 - Query L R X : Tell number of elements >= X in [L, R]
 - Update L R V: Add V to all elements in the range [L, R]

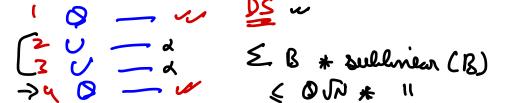
Solution:

- Divide the array into blocks of size B and maintain a sorted vector of elements for each block
- Also maintain a lazy_add[b] integer for each block.
- o To process a query [L, R], X
 - For blocks of L & R, iterate over all individual elements and check A[i] + lazy_add[b] >= X.
 - O(2 * B)
 - For every block in between, binary search for # elements >= X lazy_add[b]:
 - O(N / B * logB)
- To process an update [L, R], V
 - Recompute the sorted vector of blocks L & R -- O(2 * B logB)
 - For blocks in between, simply update lazy_add[b] += V -- O(N / B)
- Total complexity: O(N / B logB + B * logB) → O(N * sqrt(N) * logN) (choose B ~ sqrt(N))

Recap: Query Square Root Decomposition

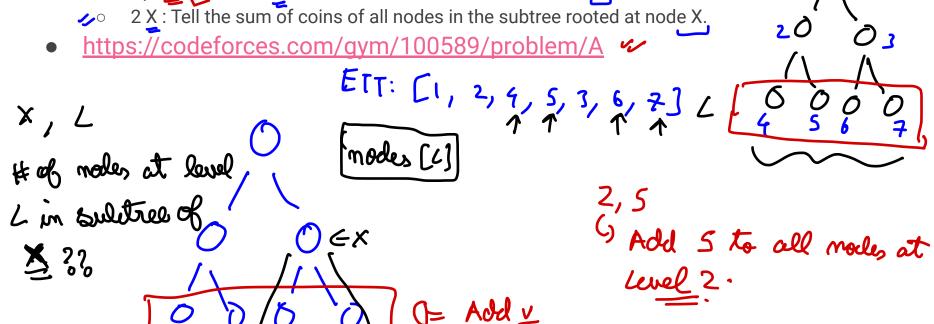
- Divide the Q queries into Q / B blocks of size B.
- Maintain some information / data structure using which the queries can be answered efficiently.
 - The data structure can be of the type "hard to update" but "easy to query", Eg: Prefix Sums.
- After every block, process all the updates which occurred in that block together via some expensive method (eg: in O(N) time).
 - Since there are Q / B blocks, this would take O(N * Q / B) time.

 ○(N * 5→)
- To answer a query,
 - Compute an approximate answer using information maintained till end of previous block
 - Iterate on all updates in the current block and reflect the contribution of an update on the current query quickly (~O(B) such updates).



Recap: Query Square Root Decomposition

- Given a tree with N nodes, each node contains O coins. Support Q operations of the form:
 - Update L Y: Add Y coins to all nodes which are distance L from the root.



Recap: Query Square Root Decomposition

- Given a tree with N nodes, each node contains 0 coins. Support Q operations of the form:
 - Update L Y: Add Y coins to all nodes which are distance L from the root.
 - 2 X: Tell the sum of coins of all nodes in the subtree rooted at node X.

Solution

- Do a DFS and push all nodes at level L in a sorted vector nodes[L]
- Divide the queries in blocks of sqrt(N) and for each query,
 - Get an approx answer by a precomputed dfs storing subtree sums of each node.
 - Process all updates that have occurred before this query in the same block.
 - Reflect contribution of an update L Y on query X, find number of nodes in subtree of X at distance L from the root -- This can easily be done by binary search on nodes[L].
 - This takes O(sqrt(N) * logN) per query.
- After each block of sqrt(N), process all updates in a single O(N) DFS.
- Therefore, total complexity is O(N * sqrt(N) * logN).

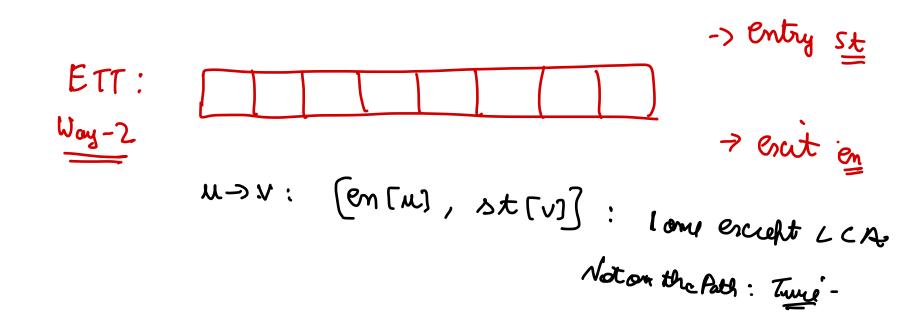
Recap: MOs Algorithm

- Find a way to quickly "add" and "remove" an element to a range.
 - Given some DS and an answer for the range [L, R], we should be able to quickly "add"/"remove" an element s.t. we have updated DS and updated answer for range [L, R+1] / [L, R - 1].
- Notice that it takes $|L_1 L_2| + |R_1 R_2|$ operations to go from $[L_1, R_1]$ to $[L_2, R_2]$
 - Here an "operation" refers to the add or remove operation. -> O(1)
- Sort the queries offline such that $\sum (|L_i L_{i+1}| + |R_i R_{i+1}|)$ is minimized.
 - Reduces to TSP NP Hard,
 - Can sort the queries smartly such that this summation is O((N + Q) * Sqrt(Q)
 - bool cmp(Query a, Query b) { ~
 - - return (a.lb < b.lb) || (a.lb == b.lb && a.r < b.r);

R Rt1

Recap: MOs Algorithm

- Given a tree with N nodes, Support Q operations of the form:
 - o Q u v : Tell the number of distinct elements on the path from u to v
- https://www.spoj.com/problems/COT2/



Recap: MOs Algorithm

- Given a tree with N nodes, Support Q operations of the form:
 - o Q u v: Tell the number of distinct elements on the path from u to v
- Solution
 - Linearize the tree using ETT Way-2 such that each node is pushed in the ETT array twice upon entry and exit.
 - Range [en[u], st[v]] contains single occurrence of all nodes on the path from u to v (except LCA) and double occurrence of all nodes not on the path from u to v.
 - Sort the queries via MOs algorithm and maintain count of each node + frequency of each distinct element seen the range.
 - To add/remove an element in the range
 - If count of node is event, add the element or else remove the element.
 - To add/remove an element, increase/decrease counts in frequency array.
 - Keep a track of number of distinct elements seen so far by observing $0 \rightarrow 1$ and $1 \rightarrow 0$ transitions in the frequency array.

Recap: Heavy Set / Light Set based Sqrt Decomp.

- Identify some property in the problem statement which can divided into Heavy(Large) Set and Light (Small) Set
 - SizeOf(HeavySet) > B 7
 - SizeOf(LightSet) < B
- We process the Heavy Set and Light Sets independently in order to obtain £ Sigo (sets) ≤ N. amortized O(N * Sqrt(N)),
 - Heavy Set
 - Since SizeOf(HeavySet) > B, Therefore at-most N / B such Heavy Sets possible.
 - Process each Heavy Set in O(g(N)) like O(N) time -- O(N * N / B). $\Rightarrow O(N * N / B)$
 - Light Set
 - Process each Light Set in O(f(CNT)) like $O(CNT^2)$ etc. where CNT = SizeOf(LightSet)
 - \sum (CNT²) <= O(N * B)

$$O(K^2) \quad K = \text{Sign}(Lightst) < Th$$

$$\leq K^{\circ} = \leq K * Th = N * Th \quad K \leq Th * \leq K \leq h$$





Recap: Heavy Set / Light Set based Sqrt Decomp.

- Given a weighted tree with N nodes and Q queries of the form:
 - o K,n1, n2, n3 ... nk : Find the sum of distances between each pair of nodes.
- 됐
- https://www.hackerrank.com/contests/worldcupsemifinals/challenges/wccit
 v

S)
$$K > IN$$
: $S = S(N)$ DP $C = N$: $S = N$:

Recap: Heavy Set / Light Set based Sqrt Decomp.

- Given a weighted tree with N nodes and Q queries of the form:
 - o K n1, n2, n3 ... nk : Find the sum of distances between each pair of nodes.

Solution:

- Since sum of K over all queries is bounded (\sim O(N)).
- \circ For K <= sqrt(N): Do an O(K ** 2) approach by iterative over each pair.
- \circ For K >= sqrt(N) : Do an O(N) approach by DFS on the whole tree.
- Final complexity: O(N * root(N)).

Recap: Square Root Decomposition

- Array Square Root Decomposition
 - Divide the array into blocks of Size B ~ Sqrt(N) & maintain some information for each block.
 - Divide a query/update into two parts
 - Individual elements in blocks of L & R
 - Complete Blocks which lie between L & R
 - Perform Range Updates Lazily
- Query Square Root Decomposition
 - Divide Q queries into blocks of size B ~Sqrt(Q)
 - o Process all updates at the end of each block and maintain a "hard-to-update" DS for queries.
 - Reflect contribution of B updates on a query "quickly".
- MOs Algorithm
 - \circ Find a way to quickly "add"/"remove" elements in a range (eg: [L, R] \rightarrow [L, R + 1] / [L, R 1])
 - \circ Process the queries in a sorted order s.t. \sum (|Li Li+1| + |Ri Ri+1|) is minimized / bounded.
- Heavy Set / Light Set based Query Decomposition
 - Identify a property whose sum(count) is bounded and can divided into heavy and light sets.
 - Process the heavy and light sets separately Eg: O(N * #HeavySets) + O(SizeOf(LightSet)^2).

Dynamic Trees - Hackerrank

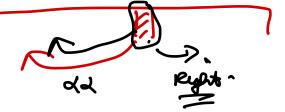
 Given a tree with N nodes where p_i (< i) represents the parent of node i and each node is either black or white. Support the following queries

- Cuv: Set $p_u = v$ i.e. remove the edge $u \to p_u$ and add the edge $u \to v$ (v < u to ensure that graph remains a tree after the update).
 - K u v k : Output k'th black node on the path from u to v.

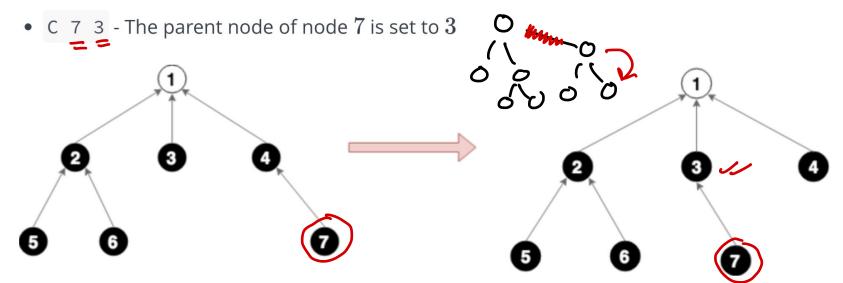
- Practice Problem
 - https://www.hackerrank.com/contests/world-codesprint-13/challenges/dynamic-trees



Dynamic Trees - Hackerrank

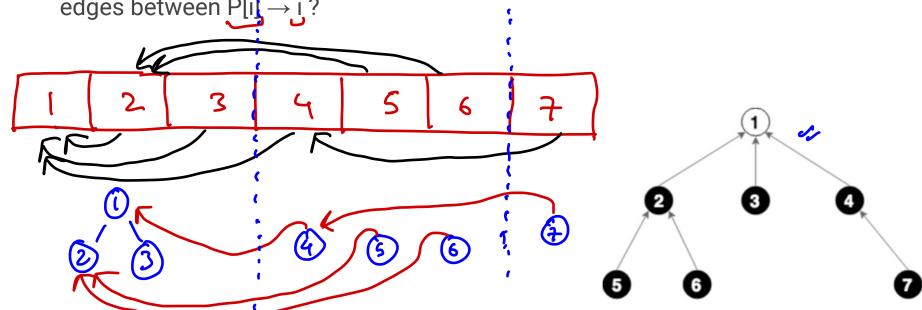


- K 5 3 2 The query gives result 2, since the 2nd black node on the simple path from 5 to 3 is 2
- ullet T $\,$ 1 The query results in node 1 being toggled from black to white

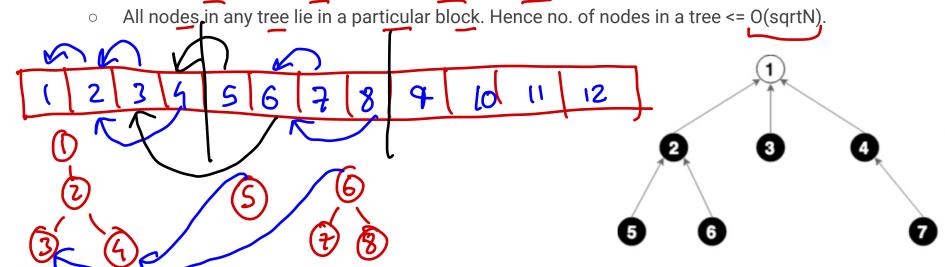


Any Ideas?

- Notice the invariant in the problem that p_i < i always.
- What happens if I divide the array [1, 2, ..., N] into blocks of size B and add edges between $P[i] \rightarrow i$?



- Notice the invariant in the problem that p_i < i always.
- What happens if I divide the array [1, 2, ..., N] into blocks of size B and add edges between P[i] → i?
- We have divided the tree into a forest of trees s.t.

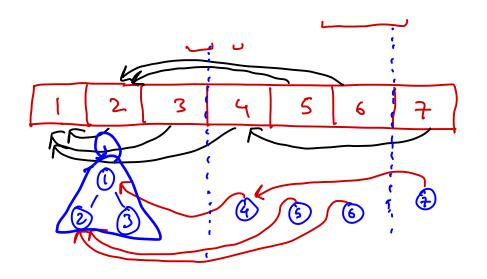


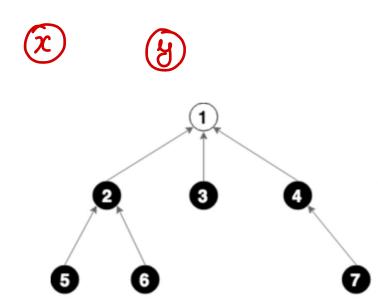
- Notice the invariant in the problem that p_i < i always.
- What happens if I divide the array [1, 2, ..., N] into blocks of size B and add edges between P[i] → i?
- We have divided the tree into a forest of trees s.t.
 - All nodes in any tree lie in a particular block. Hence no. of nodes in a tree <= O(sqrtN).
 - Every time you traverse an edge from $x \to P[x]$ s.t. root[x]!= root[P[x]], you jump to a block on the <u>left</u>.
 - Because P[x] < x and hence BLOCK[P[x]] < BLOCK[x].

```
for (auto w : g[u]) {
  Decomposing the Tree
                                    // P[w] = u \& BLOCK[w] == BLOCK[u];
                                    level[w] = level[u] + 1; 
                                    ans[w] = ans[u] + A[w];
                                   root[w] = root[u];
                                   dfs(w);
void process(int t) {
 // Build forest for each square root block
 int st = \max(1, t * SQRT), en = \min(n + 1, (t + 1) * SQRT);
 for (int i = st; i < en; i++)
   if (BLOCK[P[i]] != t || P[i] == i)
     level[i] = \emptyset, root[i] = i, ans[i] = A[i], dfs(i);
 // done :)
```

void dfs(int u) {

How do you find LCA of two nodes x & y using this square root structure?

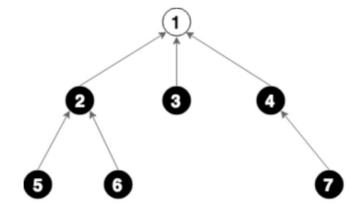


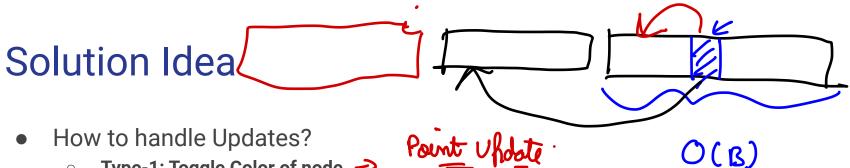


• How do you find LCA of two nodes x & y using this square root structure? 3

```
int lca(int x, int y){
   while(root[x] != root[y]){
                                                               Doot(x)=コム
         if (x > y) swap (x, y); O(N(B)
        y = P[root[y]]; < Traversed the block es moved left:
    fif(level[x] > level[y]) swap(x, y);
 while(level[y] > level[x])y = P[y];
while(x != y) x = P[x], y = P[y];
    return x;
                   O(B+ MB) = O(24)
```

- How to answer Queries? (K'th black node from $x \rightarrow y$)
 - For each node x in the forest, store no. of black nodes from $x \rightarrow root[x]$,
 - Use this information and traverse the blocks like LCA query to answer the query in O(rootN).







Type-1: Toggle Color of node →

- Only cnt[x] values of all x in the same block change.
- Recompute the block in O(rootN),



Type-2: Change Parent.

- The structure would only change in 1 block in which node x lies.
- Hence recompute the values of those block in O(rootN).



Implementation

 https://github.com/tanujkhattar/cp-teaching/blob/master/CWC/Ep02%20SR D%20on%20Trees/dynamic_trees.cpp

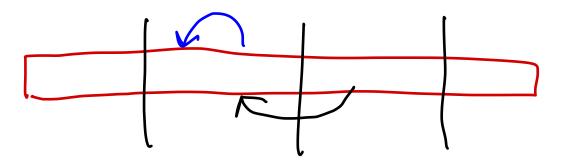


Subtree Update & Path Queries (non invertible fn)

- Given a rooted tree with N nodes and Q queries of the form:
 - A X V Add V to all nodes in the subtree of X. ✓
 - O XY-Report maximum value on the path from to
- Practice Problem:
 - https://www.hackerrank.com/challenges/subtrees-and-paths/problem

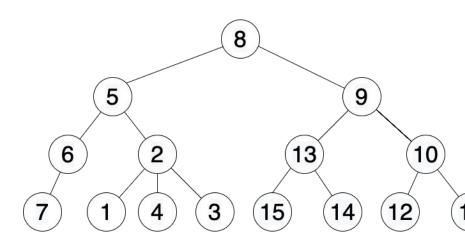
Subtree Update & Path Queries (non invertible fn)

- Linearize the tree using ETT Way-1
- Note that once the tree is linearized using ETT, the condition that st[P[x]] < st[x] is satisfied for all x.
- Hence, we can do Array Square Root Decomposition on this ETT Way-1 linearized array.



Subtree Update & Path Queries (non invertible fn)

- To perform subtree updates
 - o perform an update from [L, R] on the ETT using Array Square Root Decomposition.
- To answer path queries,
 - o traverse the decomposed blocks from right to left on the ETT array.
 - Use the DS + Lazy information stored for each block to answer path queries.
 - Note that path query for any block is from node to root of the processed tree.



ETT Way-1: [8, 5, 6, 7, 2, 1, 4, 3, 9, 13, 15, 14, 10, 12, 11]

Implementation

https://github.com/tanujkhattar/cp-teaching/blob/master/CWC/Ep02%20SR
 D%20on%20Trees/subtree_and_paths.cpp

Can we support Path Updates as well?

- Updates on paths would require us to maintain another special structure for each processed tree inside the ETT sqrt blocks because ETT doesn't store path information by default.
- We could do HLD (+ETT) and build a sqrt structure on top of it but then updates would take O(logN * sqrt(N) * (time of DS per update))
- We'll look at another advance technique tomorrow to support path updates!
 - Try https://www.codechef.com/problems/TRS for tomorrow!
- See Lecture-2 to learn more https://youtu.be/8VHWdNnP3h4