

Codechef Learn, Episode Lecture-2 TULIPS & IOI-18 Werewolf

<https://youtu.be/DTCvKPdWH2M>

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<https://www.codechef.com/problems/TULIPS>

<https://ioi2018.jp/wp-content/tasks/contest1/werewolf.pdf>

TULIPS - Problem Statement

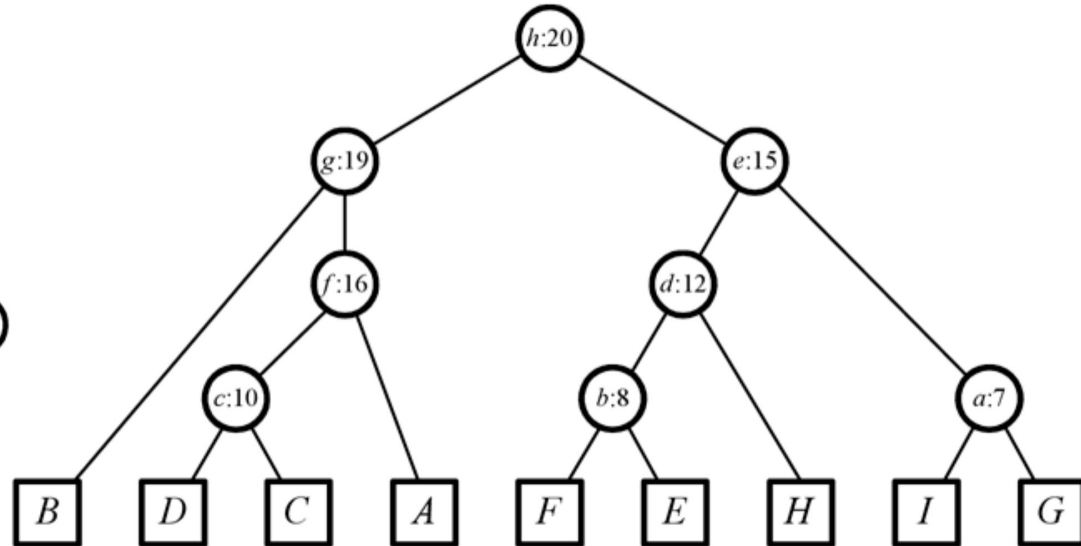
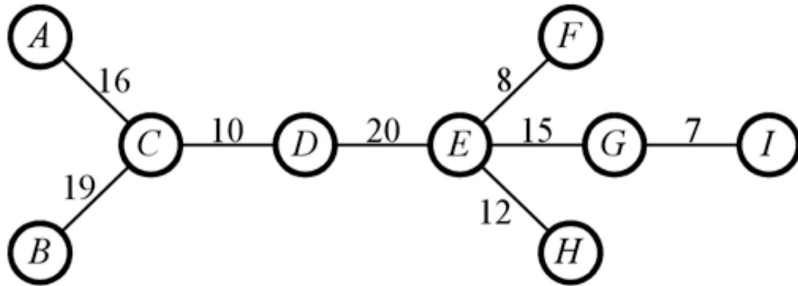
- <https://www.codechef.com/problems/TULIPS>
- Given a tree with N nodes, each node can have a TULIP growing on it. It takes X consecutive days for a TULIP to fully grow on any node. Answer Q queries of the form
 - $D\ U\ K$ - How many Tulips can you pick if you start on day D from node U and visit all nodes reachable by only traversing edges of length $\leq K$
 - Note that visiting a node also disturbs the TULIPS growing on that node, and hence resets the day on which next TULIP will become available to $D + X$.

Edge Decomposition Trees - Quick Recap

- Decompose the original tree by picking an edge, removing it and recursing on the resulting subtrees $T1$ and $T2$.
 - The removed edge gets added as a new node in the Reachability Tree (RT) / Edge Decomposition Tree / DSU Tree
 - $RT(T1)$ and $RT(T2)$ get's attached as left and right children of this newly added root node.
- Nodes reachable by traversing edges with length $\leq K$ correspond to a subtree in the Reachability Tree.
 - Hence, such queries can be reduced to subtree queries on RT which can be answered via Euler Tour Technique (ETT).

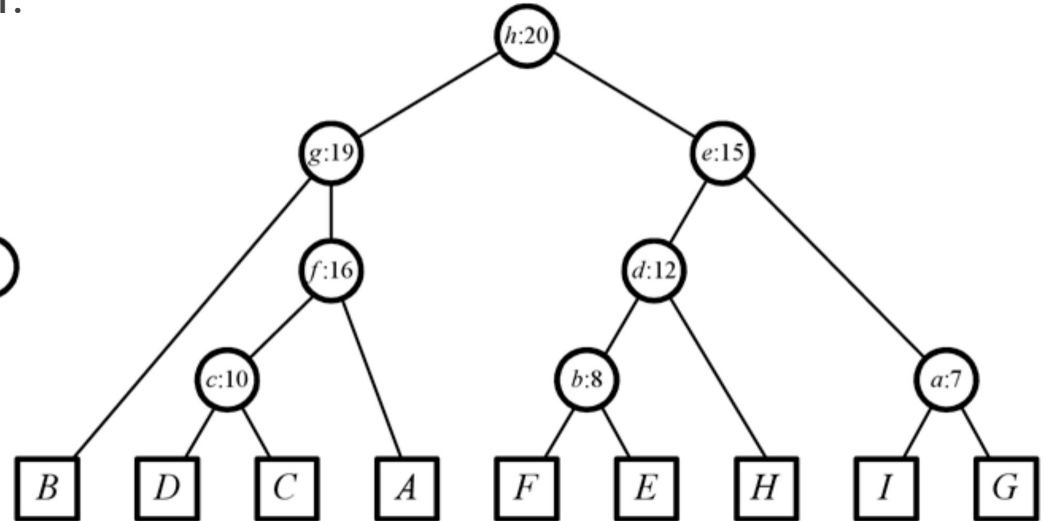
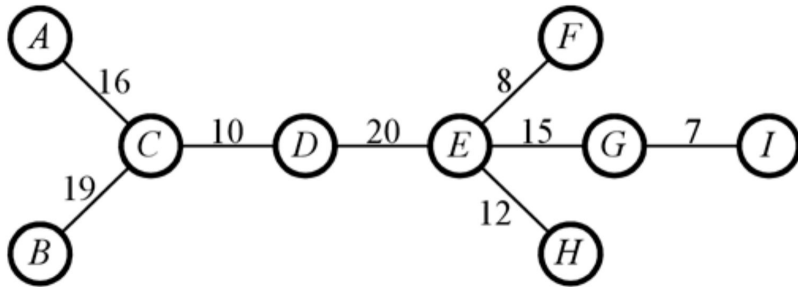
TULIPS - Solution Idea

- Build a “Max-RT” of the given tree with the property that all nodes in the subtree of a node `e` are reachable by traversing edges of length $\leq W[e]$.



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TULIPS - Solution Idea

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- Linearize the RT using ETT such that a subtree in the RT reduces to a consecutive range in the ETT.
- A query $D \ U \ K$ can now be reduced to
 - Tell the number of elements in $[L, R]$ which have a grown TULIP on day D .
 - Update all elements in $[L, R]$ such that next TULIP grows on day $D + X$.

TULIPS - How to answer the range queries?

- Given an array of N elements, initially every index has a grown TULIP on Day-1. Process the following queries
 - Q D L R: Tell the number of elements in $[L, R]$ which have a grown TULIP on day D .
 - U D L R: Update all elements in $[L, R]$ such that next TULIP grows on day $D + X$.
- The days D are given in increasing order and an update is performed for every query.

TULIPS - Way-1 Using Segment Trees + Queues.

- Let $A[i] = 0$ represent that there's a fully grown TULIP on index i .

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- Let $A[i] = 0$ represent that there's a fully grown TULIP on index i .
- To process an update $D \ L \ R$,
 - Add 1 to all elements in the range $[L, R]$ on day D
 - Subtract 1 from all elements in the range $[L, R]$ on day $D + X$ -- This can be done by pushing $(D + X, L, R)$ in a queue and processing the deletions before answering any subsequent query on day D_j .

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- To answer a query $D \ L \ R$
 - First process all deletions from the queue which are supposed to happen before day D .
 - Find the number of 0's in the range $[L, R]$.

TULIPS - Way-2 Sqrt Decomposition

- Divide the array into blocks of size \sqrt{N} and for each block, store
 - $mp[b]$: Map of <day, count> pairs storing number of fully grown tulips on day D.
 - $block_val[b]$: Lazy value storing the day at which all elements of the block will have a grown TULIP.
- To process a query & update D, [L, R], X:
 - Query Indices: For blocks in which L & R lie, iterate on individual indices [L, $en[b[L]]$ and [$st[b[R]]$, R] and compare $\max(val[i], block_val[b[i]])$ with D to check whether the index has a fully grown TULIP on day D or not.
 - Query Blocks: For blocks in between, iterate on the map storing <day, count> pairs and sum all counts for days $\leq D$. Reset the map and set $mp[b][D + X] = sz[b]$ to perform an update.

TULIPS - Way-2 Sqrt Decomposition

- Note that storing and updating the whole map for a block still works well in amortized complexity $O(Q * \sqrt{N})$.
 - The days are always increasing and we perform an update whenever we perform a query.
 - Therefore, whenever we iterate on an entry of day D in the map of a block, we end up resetting the map and hence popping that entry.
 - Therefore, every entry which is pushed into the map is iterated on at-most once, and hence the amortized complexity across all queries is $O(Q\sqrt{N})$.

TULIPS Implementation

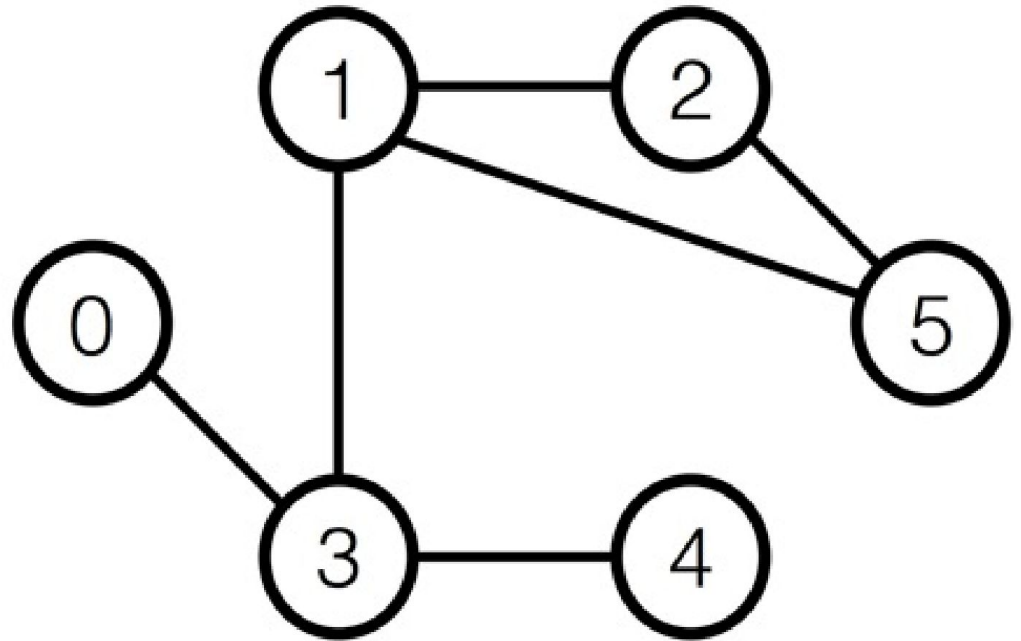
<https://github.com/tanujkhattar/cp-teaching/blob/master/CWC/Ep01:%20Edge%20Decomposition%20Tree/tulips.cpp>

IOI 2018 Werewolf

- <https://ioi2018.jp/wp-content/tasks/contest1/werewolf.pdf>
- You are a werewolf and start at a given start node in the human form. You can change your form exactly once from, human to wolf, while traversing a path. Given a graph with N nodes and M edges, you want to answer Q queries of the form:
 - $S \ E \ L \ R$: Can you go from start node S to end node E such that you cannot visit the nodes numbered $[1 \dots L - 1]$ while in human form and nodes numbered $[R + 1 \dots N]$ while in wolf form.
 - Note that you start at node S in human form and on node E you must be in the wolf form. You can change your form exactly once while traversing the path from S to E .

IOI 2018 Werewolf

- Eg: 4 2 1 2
- Start node = 4
- End Node = 2
- Avoid in Human Form: [0..1]
- Avoid in Wolf Form: [3..5]

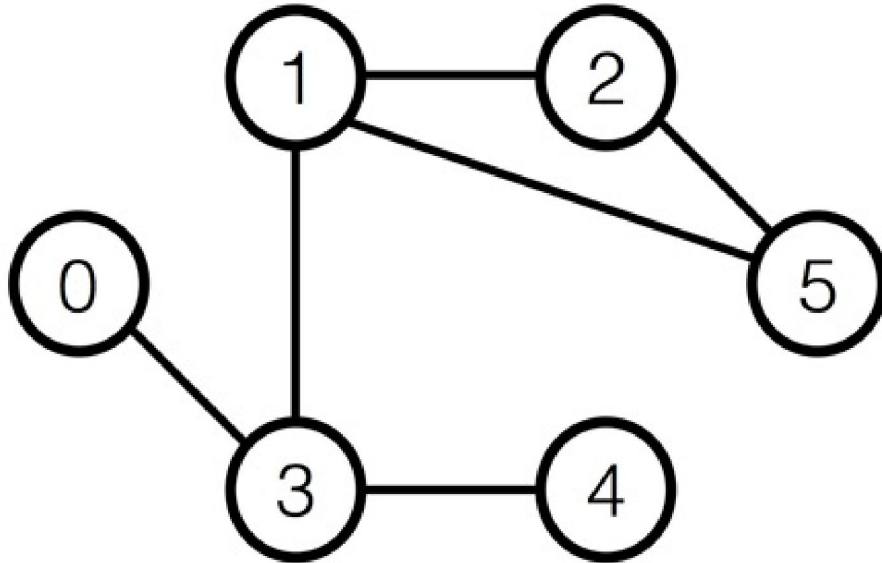


For the trip 0, you can travel from the city 4 to the city 2 as follows:

- Start at the city 4 (You are in human form)
- Move to the city 3 (You are in human form)
- Move to the city 1 (You are in human form)
- Transform yourself into wolf form (You are in wolf form)
- Move to the city 2 (You are in wolf form)

IOI 2018 Werewolf Solution Ideas

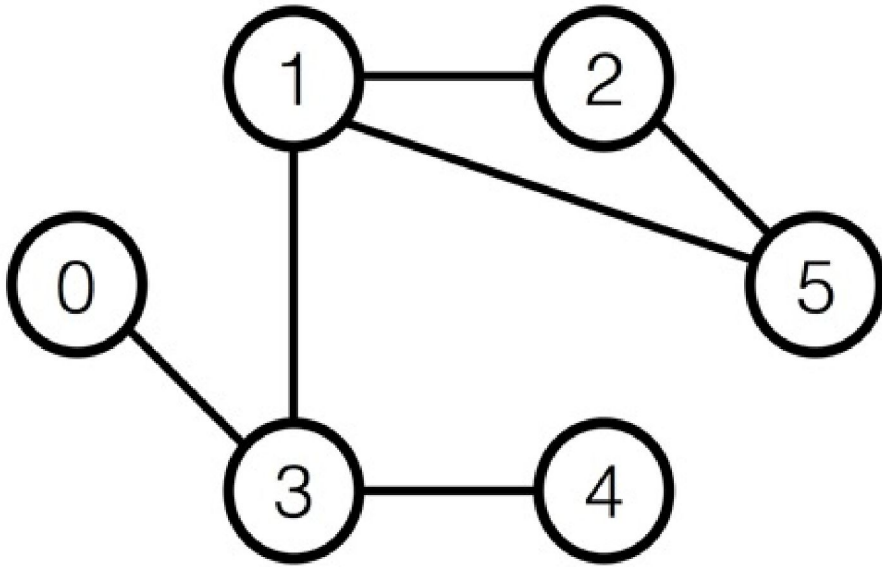
- Both S and E nodes have two different reachability conditions
 - Nodes $[L \dots N]$ can be reached by node S
 - Nodes $[1 \dots R]$ can be reached by node E



IOI 2018 Werewolf Solution Ideas

- Both S and E nodes have two different reachability conditions
 - Nodes $[L .. N]$ can be reached by node S
 - Nodes $[1 ... R]$ can be reached by node E
- Build two different reachability trees for human form and wolf form.
 - For Human Form RT, start adding nodes from the end such that subtree of the RT represents set of nodes reachable by visiting only nodes $\geq K$.
 - For Wolf Form RT, start adding nodes from the start such that subtree of the RT represents set of nodes reachable by visiting only nodes $\leq K$.

IOI 2018 Werewolf Solution Ideas



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- Build two different reachability trees for human form and wolf form.
 - For Human Form RT, start adding nodes from the end such that subtree of the RT represents set of nodes reachable by visiting only nodes $\geq K$.
 - For Wolf Form RT, start adding nodes from the start such that subtree of the RT represents set of nodes reachable by visiting only nodes $\leq K$.
- Find the subtrees in Human RT and Wolf RT based on S, L and E, R.
- A path exists if there's a common node that lies in both of these subtrees -- this is node where we can change forms.

IOI 2018 Werewolf Solution Ideas

- It reduces the problem to a range query $[L1, R1]$, $[L2, R2]$ - Find whether there exists a common element between $A[L1...R1]$ and $B[L2...R2]$ where A and B are permutations of $[1...N]$
- This can easily solved via Segment Trees

IOI 2018 Werewolf Implementation

<https://github.com/tanujkhattar/cp-teaching/blob/master/CWC/Ep01:%20Edge%20Decomposition%20Tree/werewolf.cpp>

More Practice Problems

- <https://www.codechef.com/problems/TULIPS>
- IOI 2018 Werewolf:
<https://ioi2018.jp/wp-content/tasks/contest1/werewolf.pdf>
- <https://www.codechef.com/JULY19A/problems/MXMN> (related)

Conclusion

- RT has a nice property that every subtree represents a connected component in the original tree and the edges in the connected component satisfy a certain property (eg: all edge weights $\leq K$).
- The reachability property can be different based on the problems, for eg: Min / Max edge traversal, Min / Max node visitation etc.