

## **Supporting Technologies**

S oftware E ngineering & N etwork S ystems Lab

| Assurance     | Name        | Formal Search-based   |                    |  |
|---------------|-------------|---|--------------------|--|
| Adaptation    | Avida-MDE   | Spin  | Avida              |  |
|               | Plato Suite | Utility functions, exec spec                                  | pec GA, MOO        |  |
|               | Hermes      | State-based modeling  | GP                 |  |
| Verification  | Marple      | Spec patterns, Spin Avida, GP                                 |                    |  |
|               | AMOEBA      | Modular Model checking  |                    |  |
|               | AMOEBA-RT   | Run-time model checking                                       |                    |  |
| Validation    | Athena      | Utility functions, exec spec                                  |                    |  |
| Testing       | Veritas     | Adaptive parameters for GA, 1+1 Online EA, functional testing |                    |  |
|               | Proteus     | Adaptive Test plans   | GA                 |  |
|               | Loki/Enki   | Utility functions, exec spec GA, novelty search               |                    |  |
|               | Fenrir      | Instrumented code   | GA, novelty search |  |
| Specification | Adapt-LTL   | Extend LTL with adapt operator                                |                    |  |
|               | RELAX       | Logic spec language, fuzzy logic semantics                    |                    |  |
|               | AutoRELAX   | RELAX, exec spec  | GA                 |  |



## MICHICAN STATE UNIVERSITY Cyber-Physical Systems Assurance Technologies of tware ngineering &

N etwork S ystems Lab

| Objective   | Name   | Formal                                  | Search-based                                     |
|---|--|---|--|
| Requirements Completeness [SSBSE2017, M@RT17,MODELS2016]        | Ares, Ares-<br>EC, Lykus                       | Z3 SMT solver; Athena utility functions | GA+SA  |
| Feature Interaction [SEAMS2018, QRS2018, SEAMS2019, MODELS2019] | Phorcys,<br>Phorcys-EC<br>Phorcys-<br>RT,Soter | Z3 SMT solver; Athena utility functions | GA+SA  |
| Mode Boundary Discovery [SSCI2016]                              | EvoMODE  | Model-free controller                   | Loki and EC novelty search                       |
| Validation platform [GECCO2018]                                 | Evo-ROS  | ROS, Ardupilot                          | EC, Enki   |
| Robustness of Autonomous<br>Systems [SEAMS2019]                 | Evo-ROS and<br>Enki                            | ROS, PID Controller                     | Environmental uncertainty; controller robustness |
| Test and Improve ML wrt uncertainty [ICAC2019]                  | Enki   |   | EC, novelty search                               |
| Confidence assessment for Assurance Cases [NIER2018]            |  | GSN                                     | Dempster-Schafer theory,<br>GVSM                 |
| Adapting Security Assurance Case Framework [SPS2019]            | MAPE-SAC                                       | GSN                                     | Enki   |