potential LTA problem	**impact / relevance** 1 - **high** (prevents successful mission) 2 - **medium** (has some influence, e.g. delays missions / reduces quality of results) 3 - **low** (no / minor influence on mission)	**difficulty to detect / solve** 1 - **easy** (simple solutions) 2 - **medium** (requires some effort, but doable in the scope of the work) 3 - **hard** (general problem)	**likelihood of occurrence** 1 - **very likely** (have experienced this in practice several times) 2 - **occurs** (e.g. have experienced this once / heard of it) 3 - **highly unlikely** (never seen / heard of it)
power management (battery failure / unexpected low battery)			
charging failure (unsuccessful docking / no charging)			
drastic weather change (e.g. storm, fog, extreme sunshine, heavy rain, extreme cold)			
certain dynamics (e.g. day / night)			
sensor (perception) failure			
perceptual aliasing issue			
data management (e.g. full memory, sensor data processing failure)			
lost connection (WiFi, RTK, UWB, LTE)			
obstacles blocking planned path (static / dynamic)			
robot gets stuck (e.g. spinning wheels)			
robot falls over			
navigation failure (move_base_flex / pdc)			
sustained recovery, i.e. no return to normal operation			
incorrect / inaccurate localization (GPS, IMU, odometry)			
mapping error (e.g. incorrect costmap entries)			
plan deployment failure, i.e. robot remains in idle state			