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Report

Digital Image Processing

« Assignments »

2014-2015

Summary

A. Image representation and description

A.1 Problem statement

(a) Develop a program to implement the boundary following algorithm, the resampling grid and calculate the chain code and the first difference chain code. Use the image 'noisy_stroke.tif' for test. (For technique details, please refer to pp.818-822 (3rd edition, Gonzalez DIP) or boundaryfollowing.pdf at the same address of the slides.)

(b) Develop a program to implement the image description by the principal components (PC). Calculate and display the PC images and the reconstructed images from 2 PCs. Use the six images in 'washingtonDC.rar' as the test images.

A.2 Python implementation

Four programs :

- Boundary following : **boundary.py**
  Usage : **boundary.py [-h] [–smooth] image_path**
  Use **python boundary.py -h** to see the help.

- Resampling grid : **resampling.py**
  Usage : **resampling.py [-h] [-s SAMPLING [SAMPLING ...]] boundary_image**
  Use **python resampling.py -h** to see the help.

- Chain code : **chaincode.py**
  Usage : **chaincode.py [-h] [-s SAMPLING [SAMPLING ...]] boundary_image**
  Use **python chaincode.py -h** to see the help.

- Image description by the principal components (PC) : **pc.py**
  Usage : **pc.py [-h] [-n N] [–debug] [–diff] [–nshow]**
  Use **python pc.py -h** to see the help.

A.3 Boundary following

python boundary.py noisy_stroke.tif.

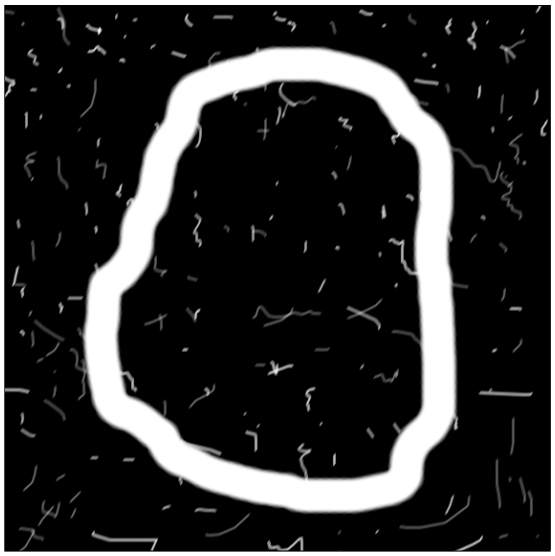

Figure A.1 – Original image

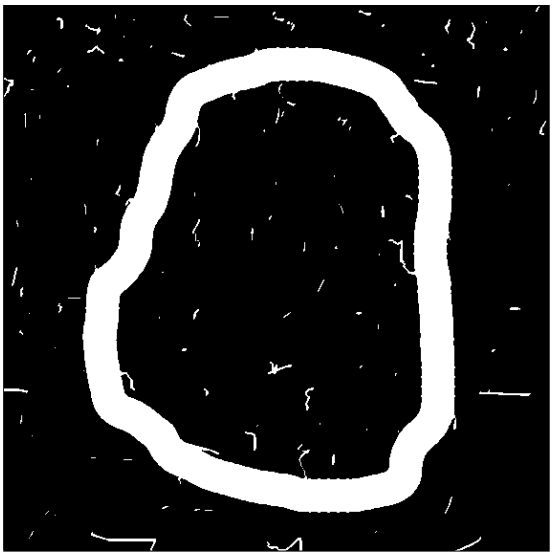

Figure A.2 – Black & white

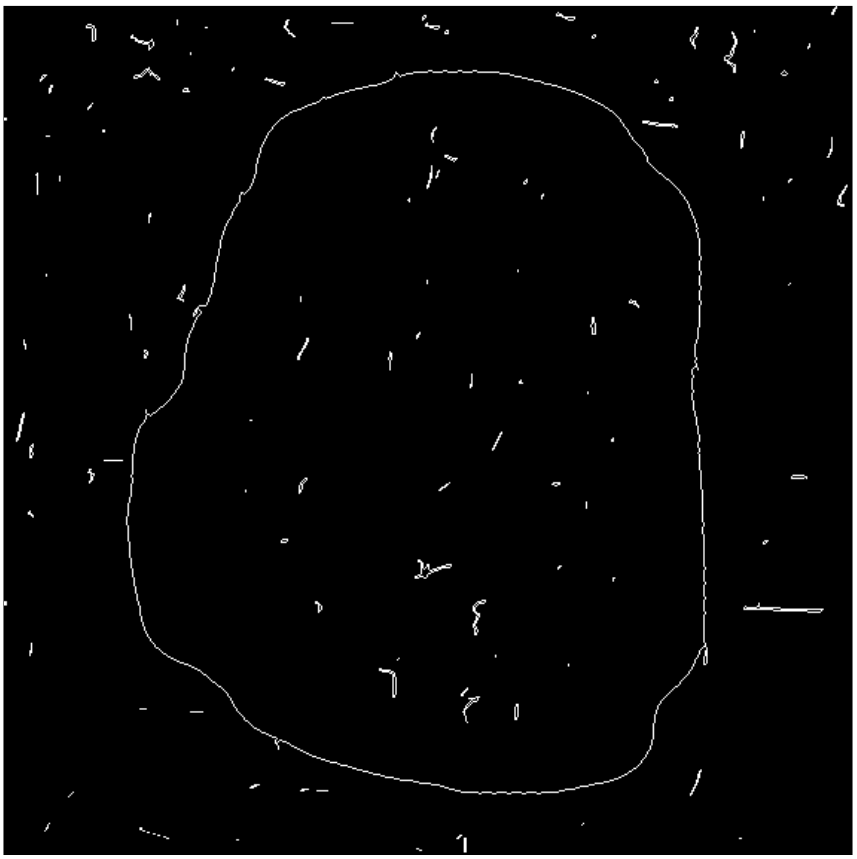

Figure A.3 – Boundaries

Even the boundaries of the noise are found... We need to remove the noise beforehand. For that, let use a Gaussian blur of mean 0 and variance 10.

python boundary.py noisy_stroke.tif –smooth.

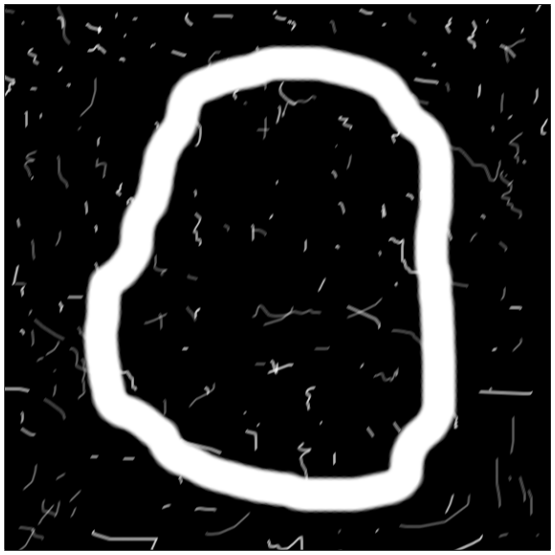

Figure A.4 – Original image

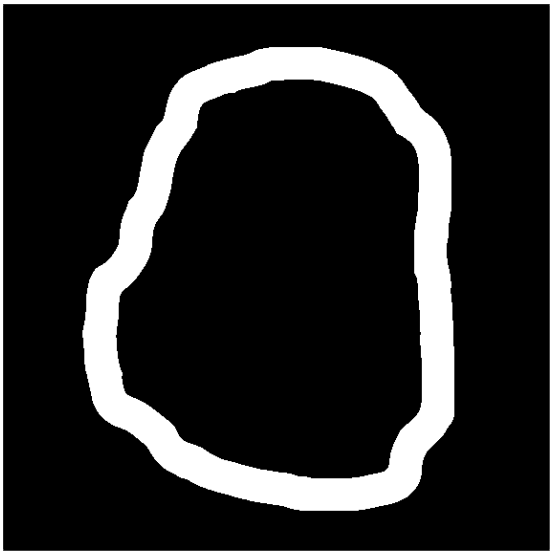

Figure A.5 – Smoothing + binarisation

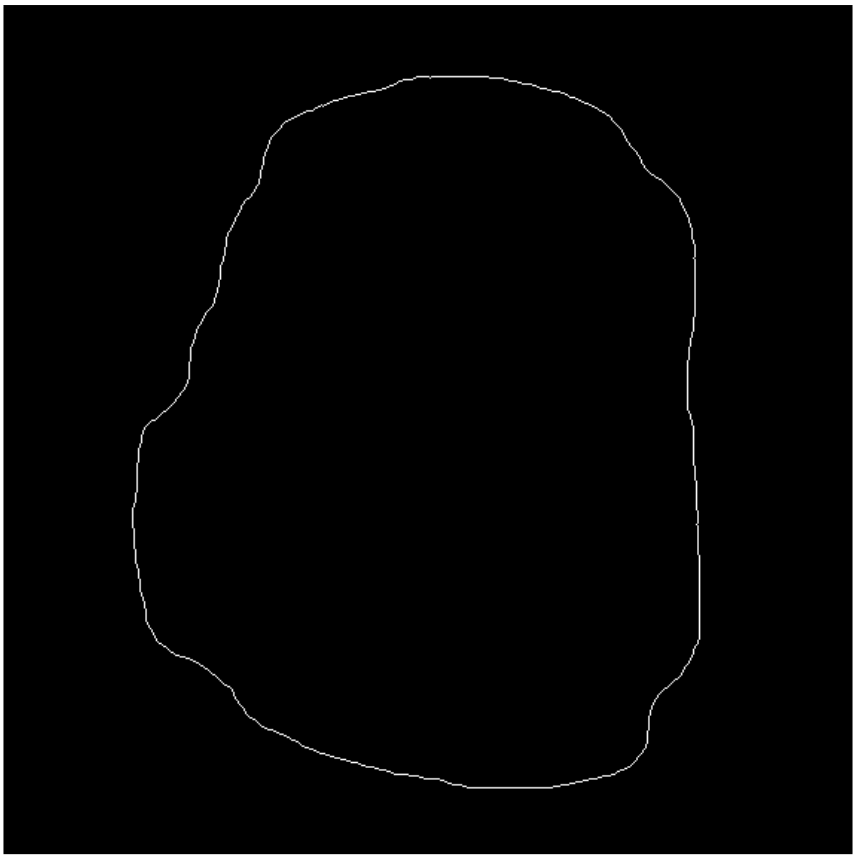

Figure A.6 – Boundaries

A.4 Resampling grid

python resampling.py noisy_stroke_boundary.png -s Sx Sy, where Sx and Sy are the sampling intervalles along the X and Y axis.

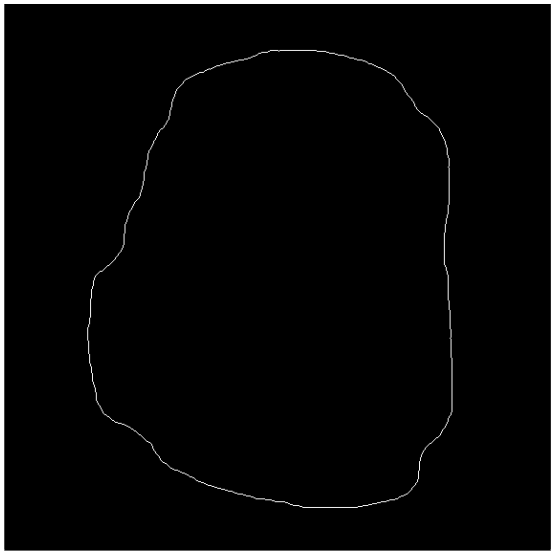

Figure A.7 – Original image

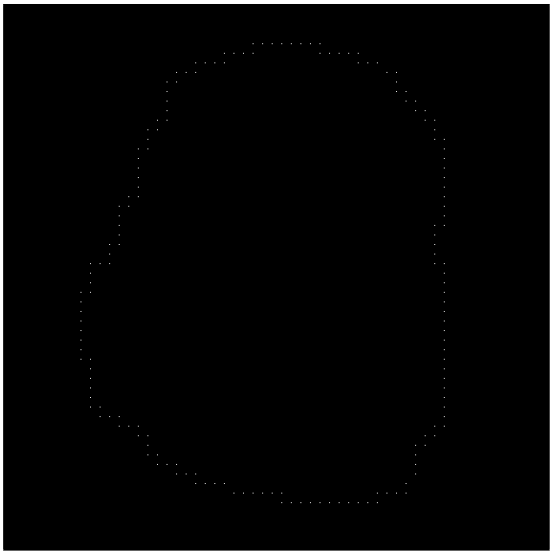

Figure A.8 – R-grid (S = (10, 10))

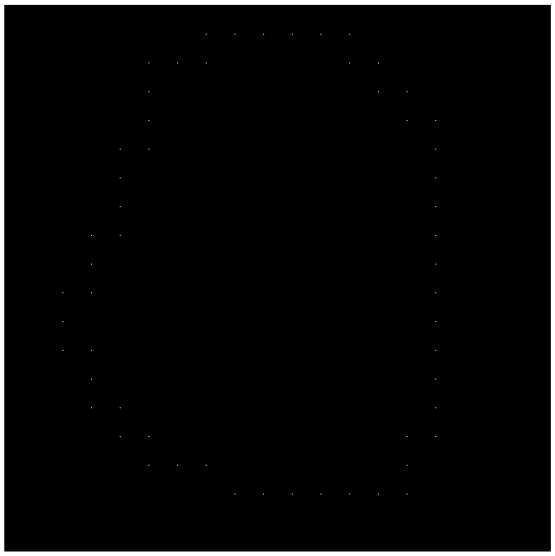

Figure A.9 – R-grid (S = (30, 30))

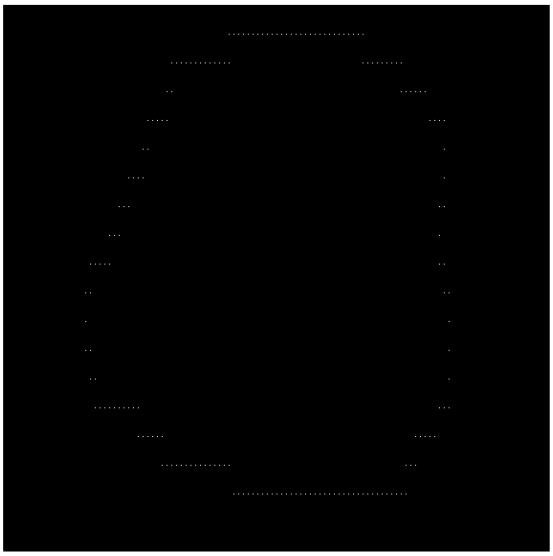

Figure A.10 – R-grid (S = (5, 30))

A.5 Chain code and first difference chain code

A.5.1 Chain code - resampling grid (10, 10)

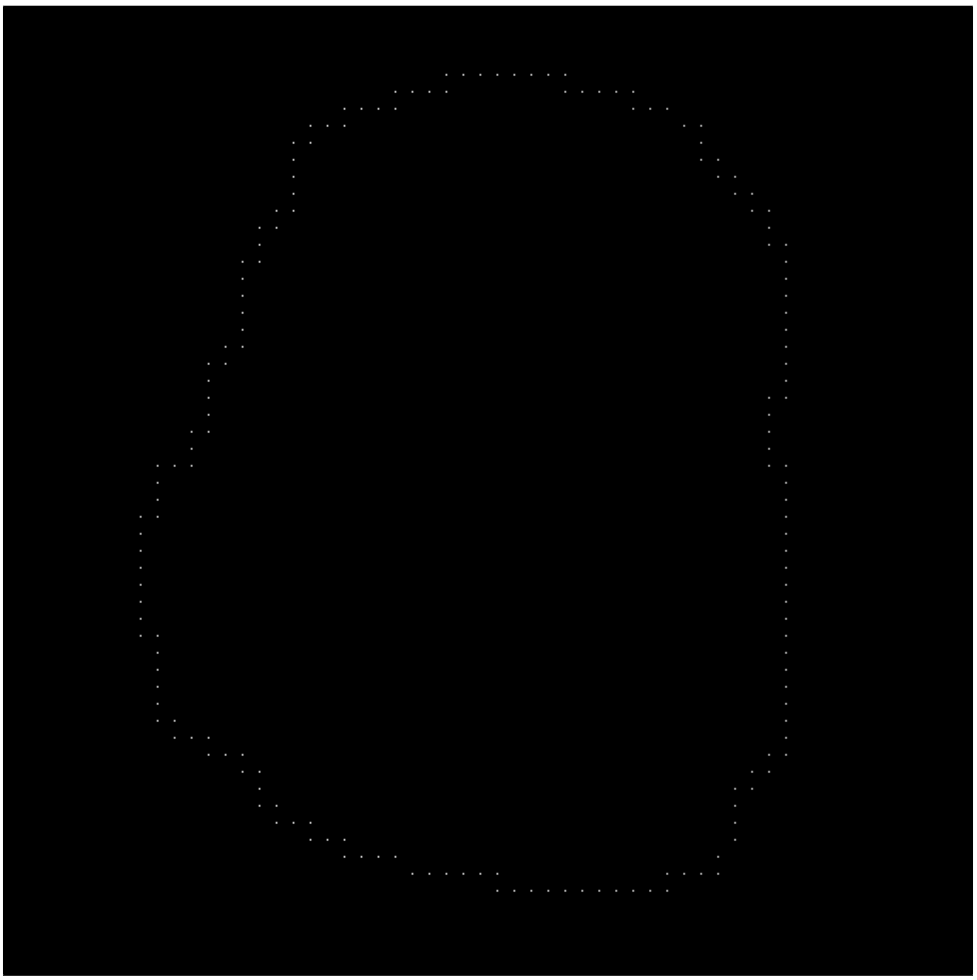

Figure A.11 – Resampling grid (S = (10, 10))

Chaincode (length = 170) :

00000060000600706606060606606666666
66466660666666666666666664646466656
44464444444442444443444244244242224
24424424222224222222202220022022220
20222220220202222020020002 0002

First difference (length = 169) :

00000620006207160262626260260000000
06200026000000000000000062626200716
00260000000006200007100620620626026
20620626000026000000620060206200062
62000062062620006260260026002

A.5.2 Chain code - resampling grid (30, 30)

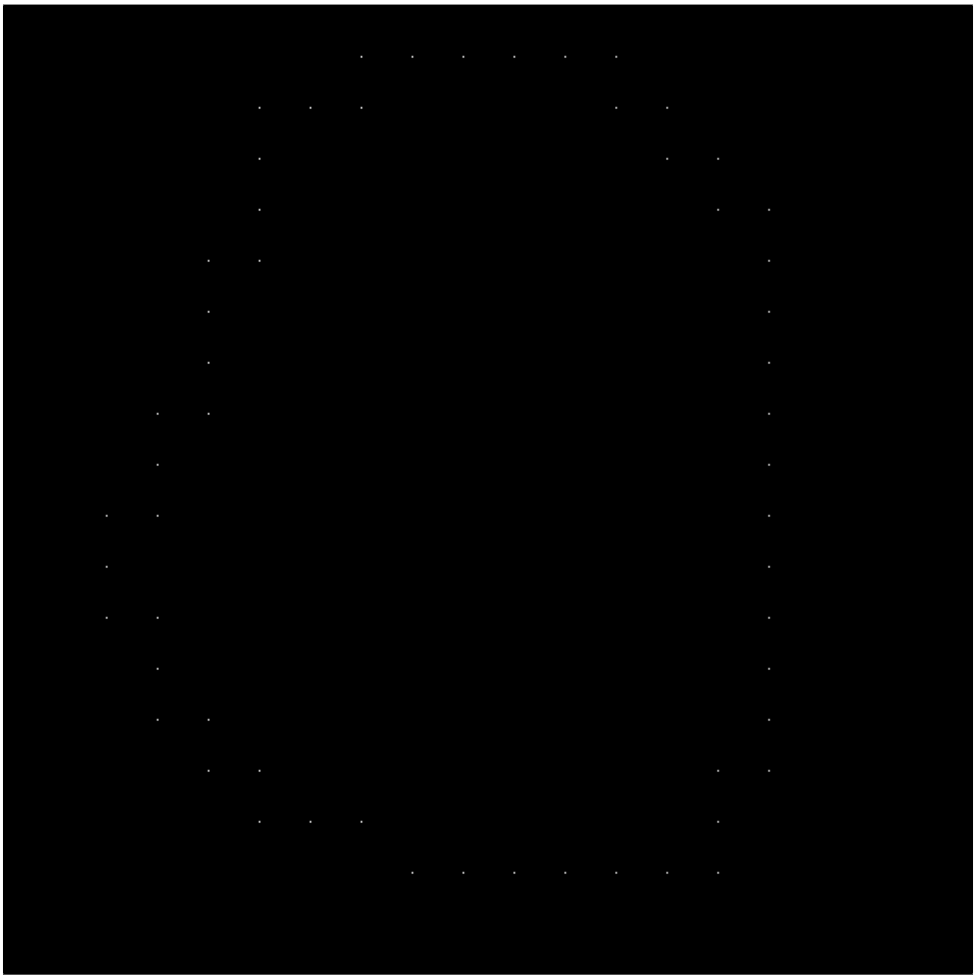

Figure A.12 – Resampling grid (S = (30, 30))

Chaincode (length = 56) :

00060606066666666666466444444344242422422022022022020020

First difference (length = 55) :

00626262600000000006206000007106262602606206200620060 26

A.6 Principal components

python pc.py –diff -n 2

We keep only 2 principal components for the images reconstruction.

Figure A.13 – Band 1

Figure A.14 – Band 1 reconstructed

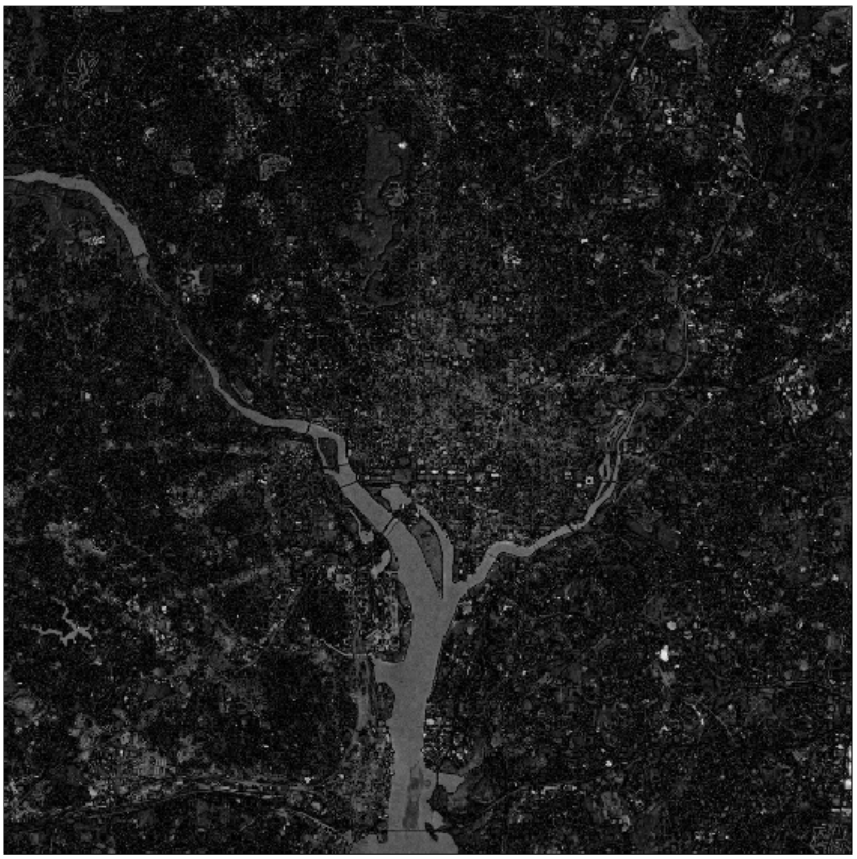

Figure A.15 – Band 1 difference

Figure A.16 – Band 2

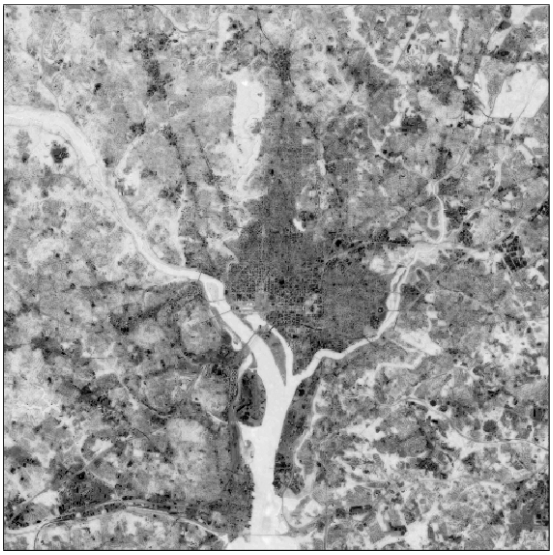

Figure A.17 – Band 2 reconstructed

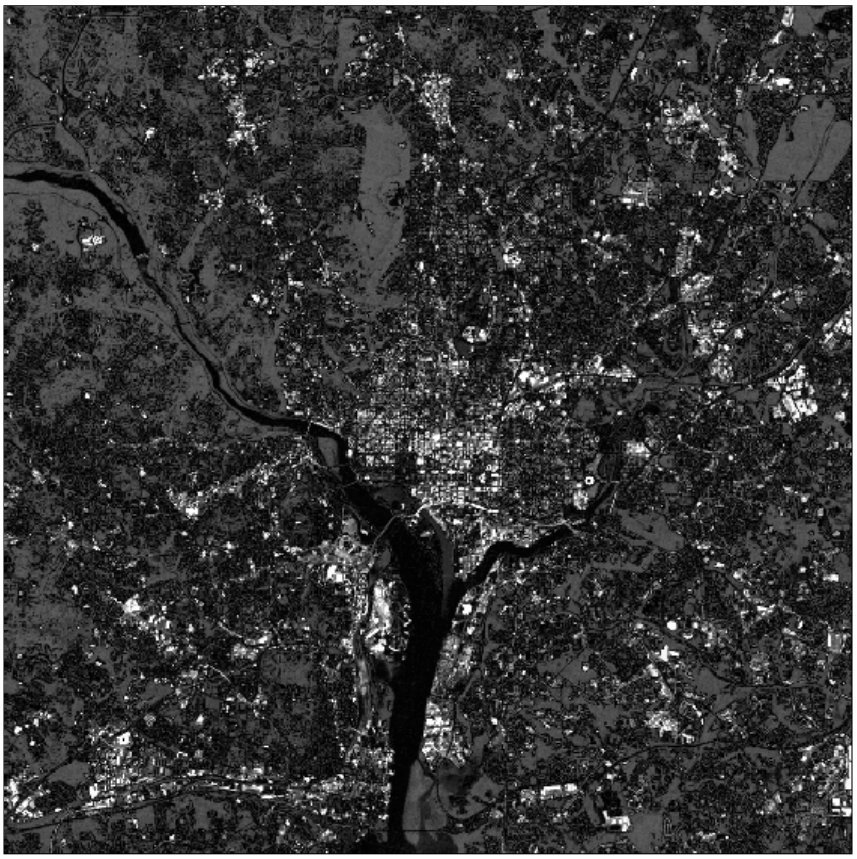

Figure A.18 – Band 2 difference

Figure A.19 – Band 3

Figure A.20 – Band 3 reconstructed

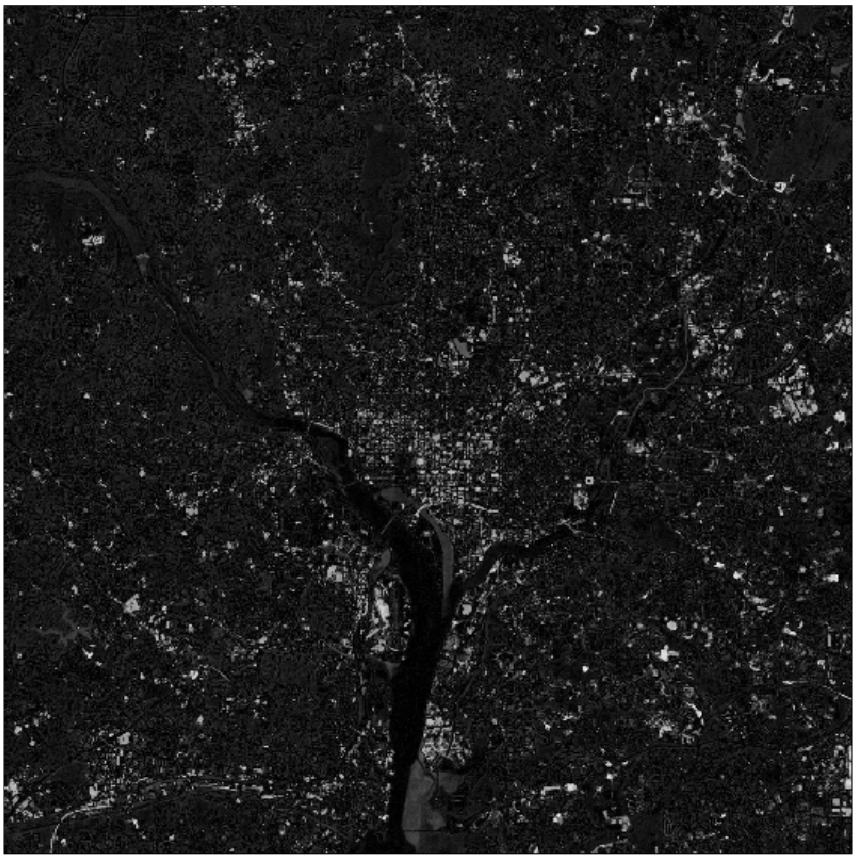

Figure A.21 – Band 3 difference

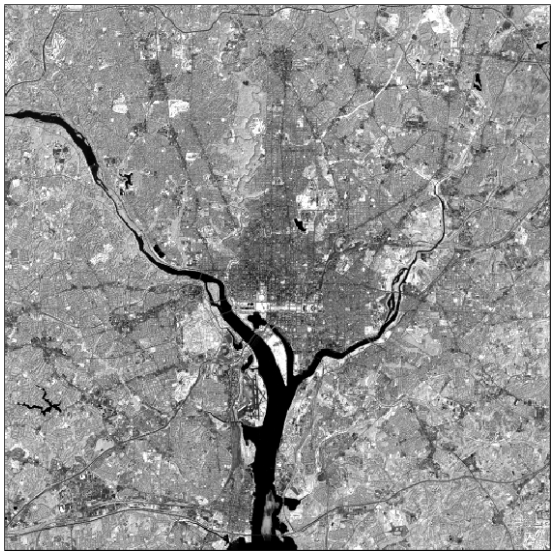

Figure A.22 – Band 4

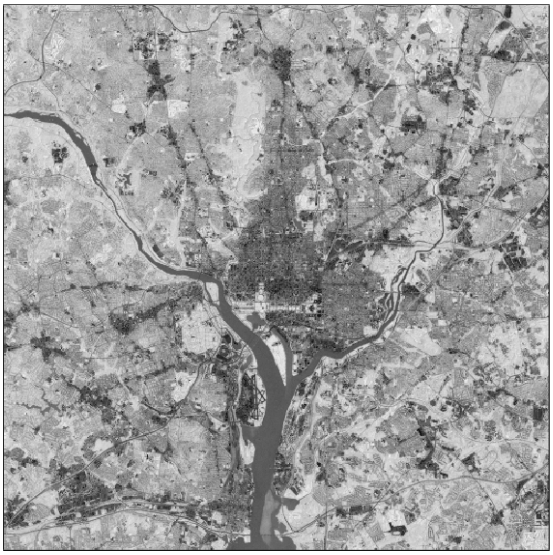

Figure A.23 – Band 4 reconstructed

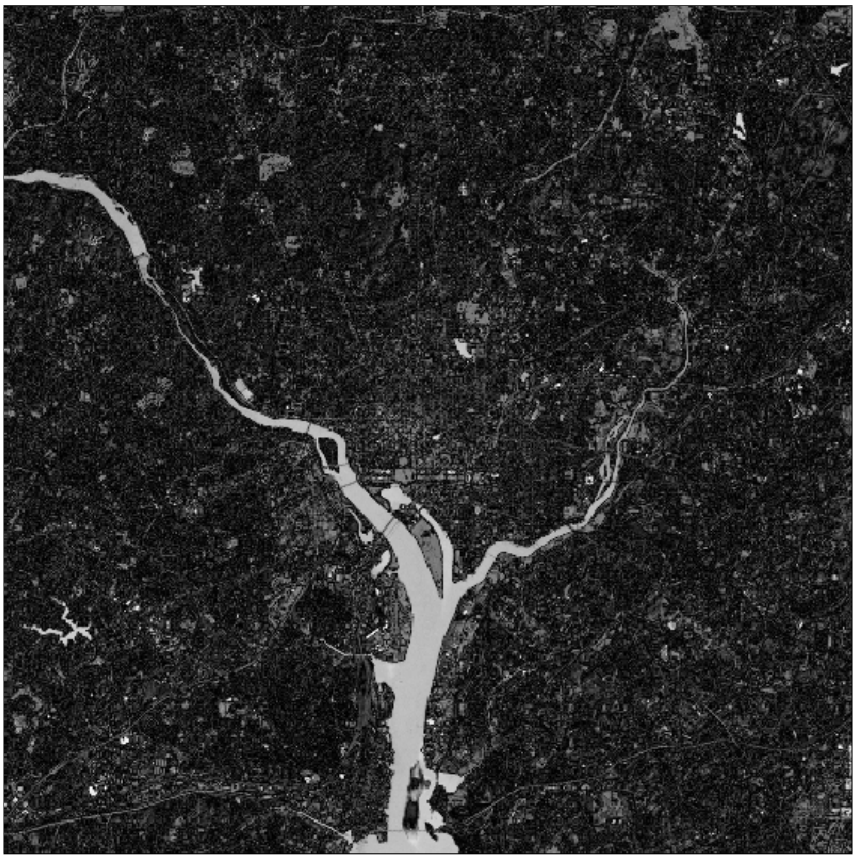

Figure A.24 – Band 4 difference

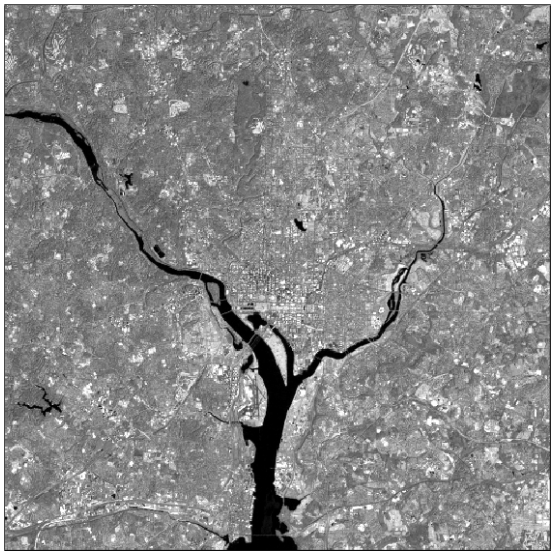

Figure A.25 – Band 5

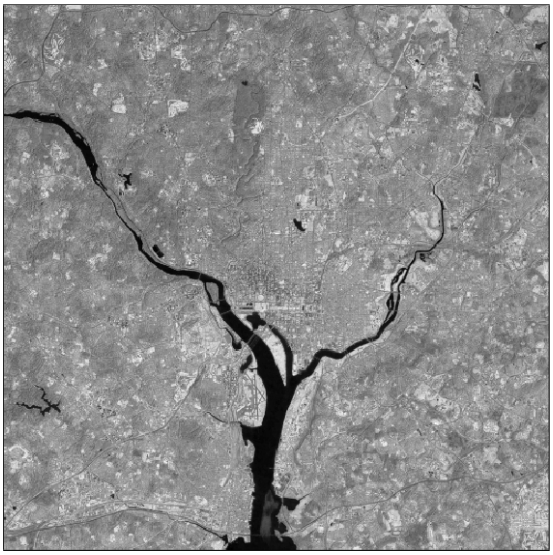

Figure A.26 – Band 5 reconstructed

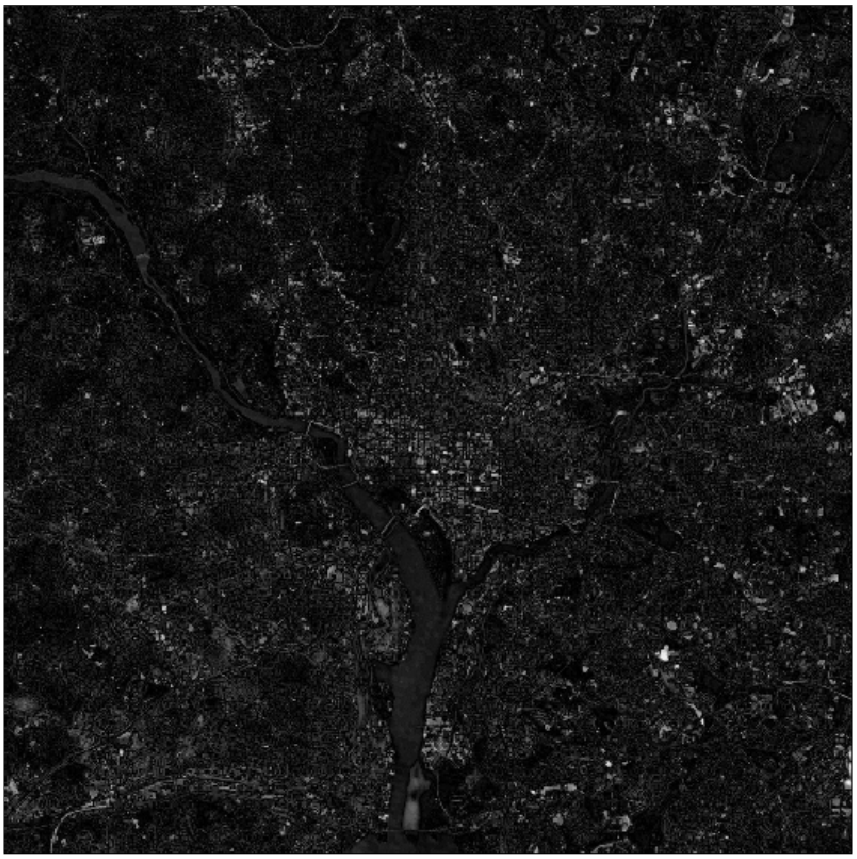

Figure A.27 – Band 5 difference

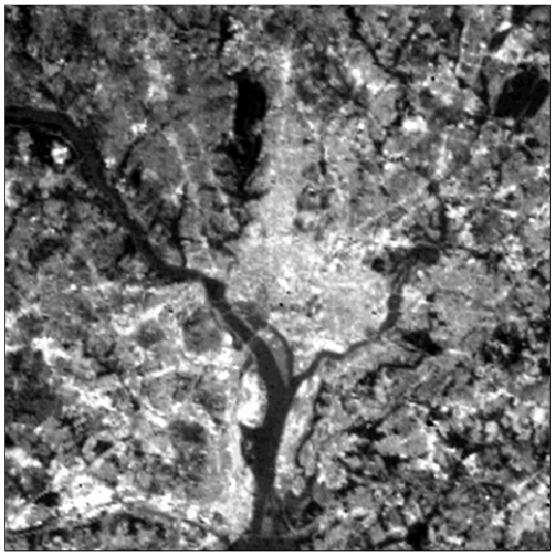

Figure A.28 – Band 6

Figure A.29 – Band 6 reconstructed

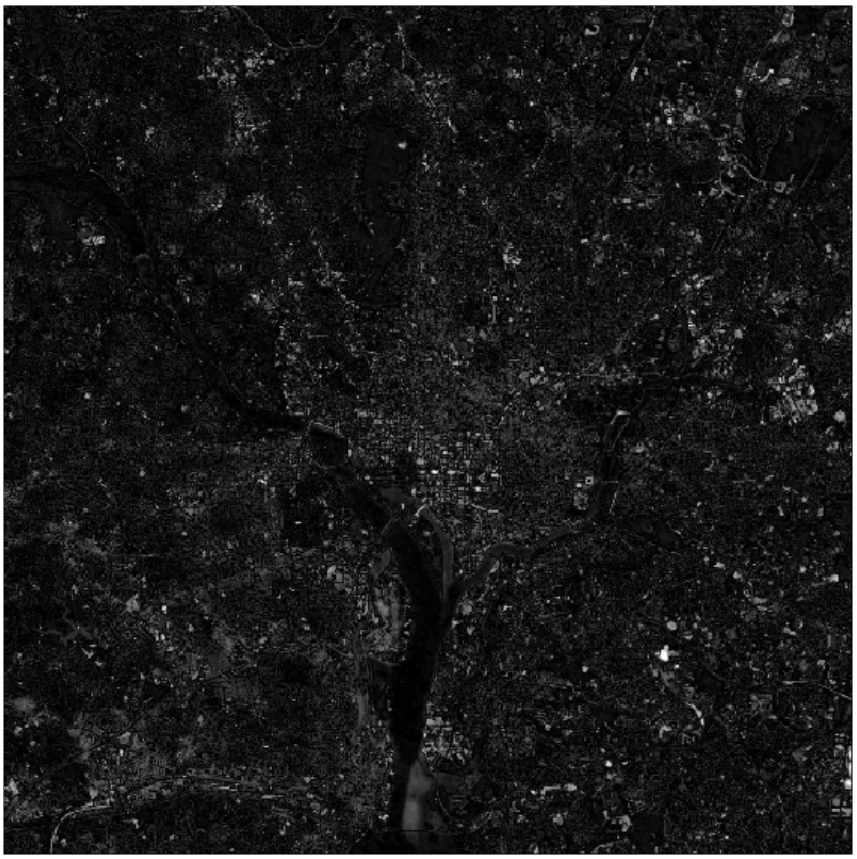

Figure A.30 – Band 6 difference