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REPORT

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# Digital Image Processing

## « Assignments »

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# Summary

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# A. Image representation and description

## A.1 Problem statement

- (a) Develop a program to implement the boundary following algorithm, the resampling grid and calculate the chain code and the first difference chain code. Use the image ‘noisy\_stroke.tif’ for test. (For technique details, please refer to pp.818-822 (3rd edition, Gonzalez DIP) or boundaryfollowing.pdf at the same address of the slides.)
- (b) Develop a program to implement the image description by the principal components (PC). Calculate and display the PC images and the reconstructed images from 2 PCs. Use the six images in ‘washingtonDC.rar’ as the test images.

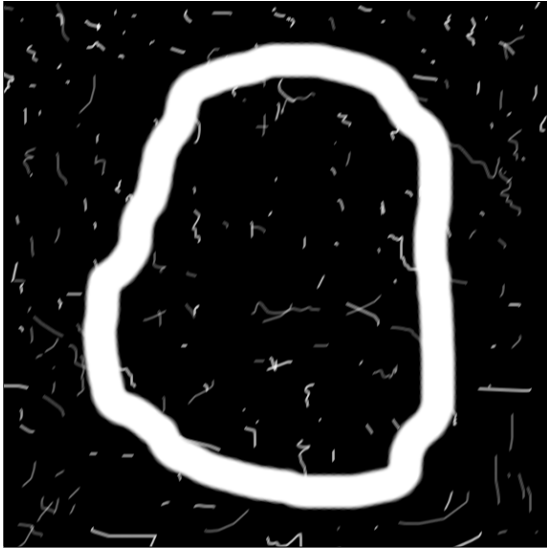
## A.2 Python implementation

Four programs :

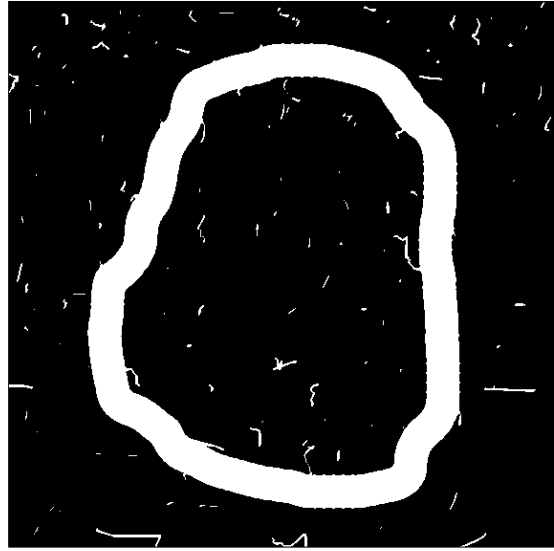
- Boundary following : **boundary.py**  
Usage : **boundary.py [-h] [-smooth] image\_path**  
Use **python boundary.py -h** to see the help.
- Resampling grid : **resampling.py**  
Usage : **resampling.py [-h] [-s SAMPLING [SAMPLING ...]] boundary\_image**  
Use **python resampling.py -h** to see the help.
- Chain code : **chaincode.py**  
Usage : **chaincode.py [-h] [-s SAMPLING [SAMPLING ...]] boundary\_image**  
Use **python chaincode.py -h** to see the help.
- Image description by the principal components (PC) : **pc.py**  
Usage : **pc.py [-h] [-n N] [-debug] [-diff] [-nshow]**  
Use **python pc.py -h** to see the help.

## A.3 Boundary following

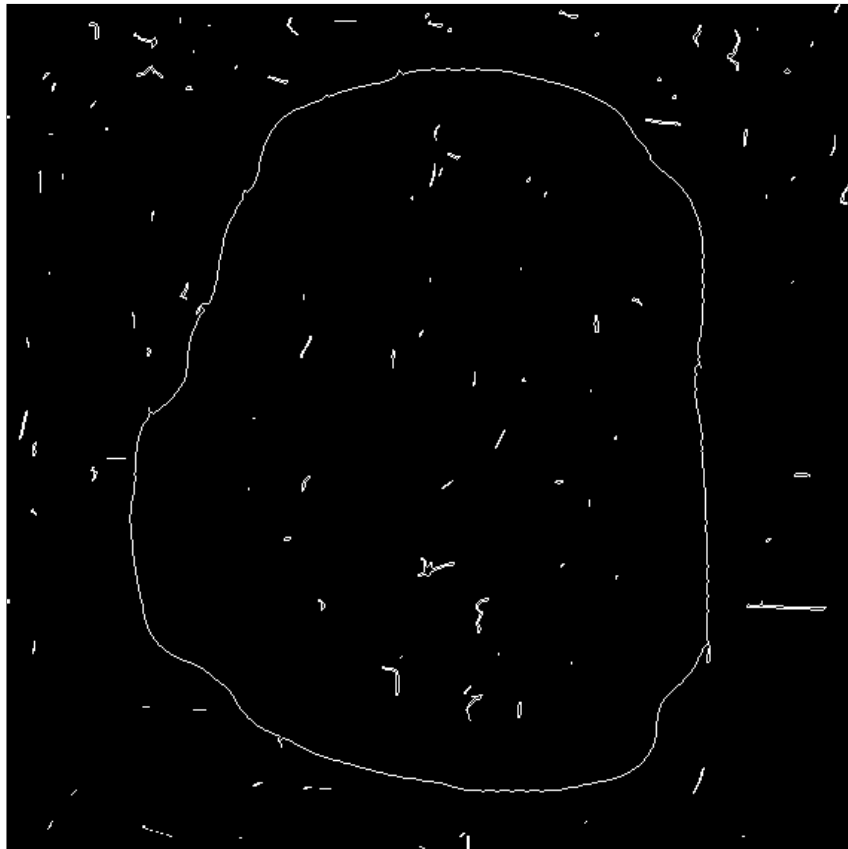
```
python boundary.py noisy_stroke.tif.
```



**FIGURE A.1** – Original image



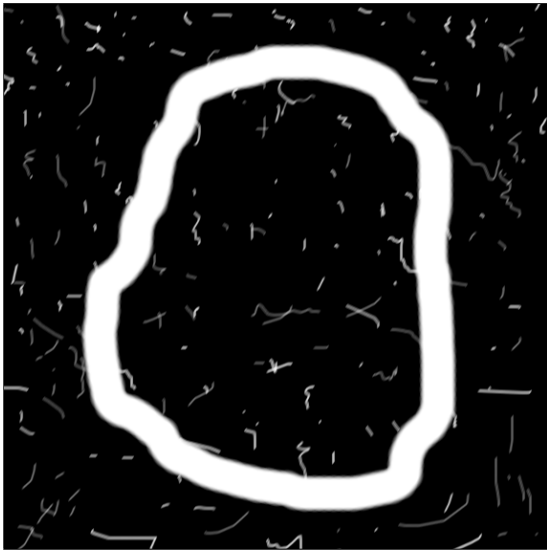
**FIGURE A.2** – Black & white



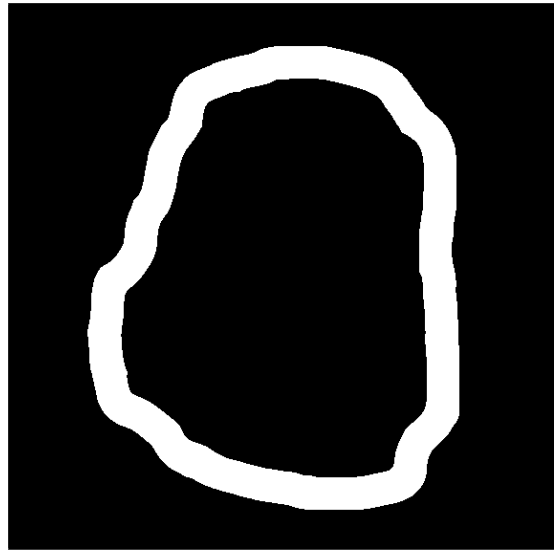
**FIGURE A.3** – Boundaries

Even the boundaries of the noise are found... We need to remove the noise beforehand. For that, let use a Gaussian blur of mean 0 and variance 10.

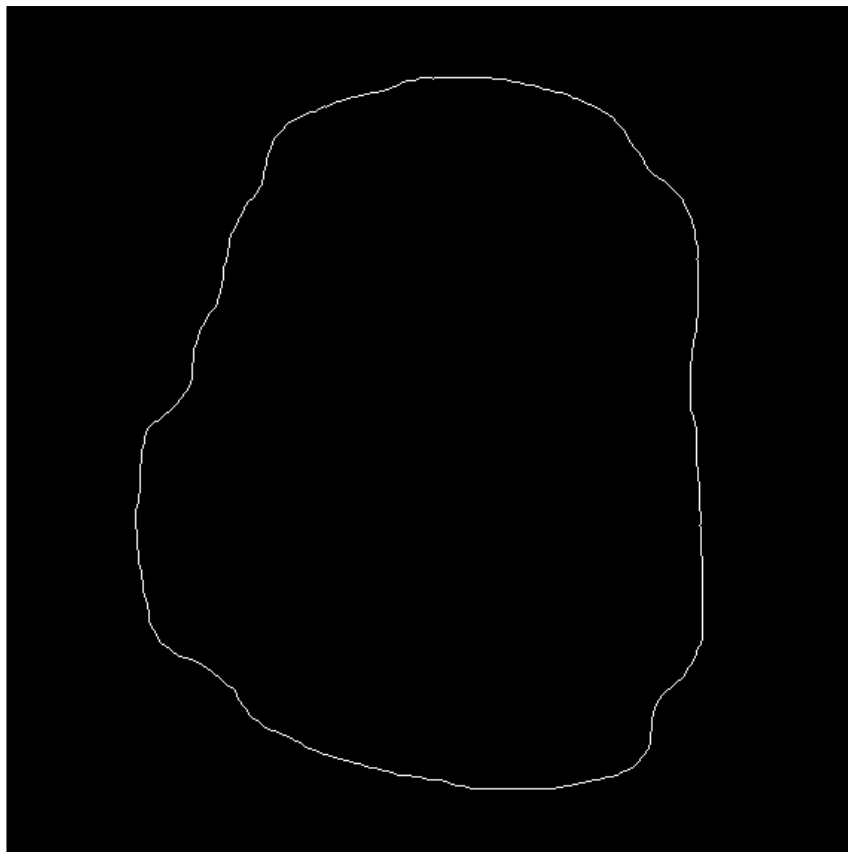
```
python boundary.py noisy_stroke.tif --smooth.
```



**FIGURE A.4** – Original image



**FIGURE A.5** – Smoothing + binarisation



**FIGURE A.6** – Boundaries

## A.4 Resampling grid

`python resampling.py noisy_stroke_boundary.png -s Sx Sy`, where  $Sx$  and  $Sy$  are the sampling intervals along the X and Y axis.

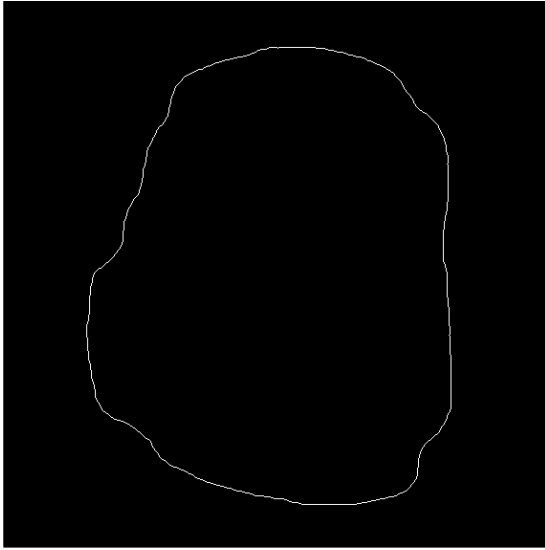


FIGURE A.7 – Original image

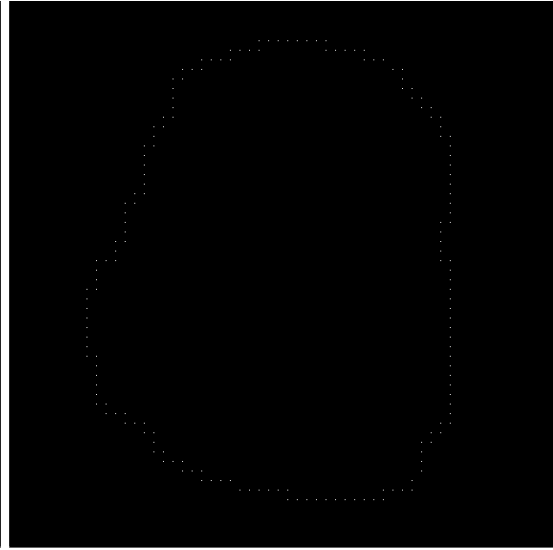


FIGURE A.8 – R-grid ( $S = (10, 10)$ )

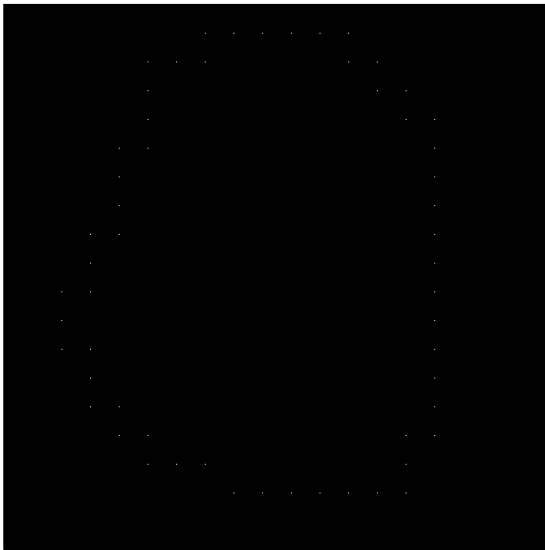


FIGURE A.9 – R-grid ( $S = (30, 30)$ )



FIGURE A.10 – R-grid ( $S = (5, 30)$ )

## A.5 Chain code and first difference chain code

### A.5.1 Chain code - resampling grid (10, 10)

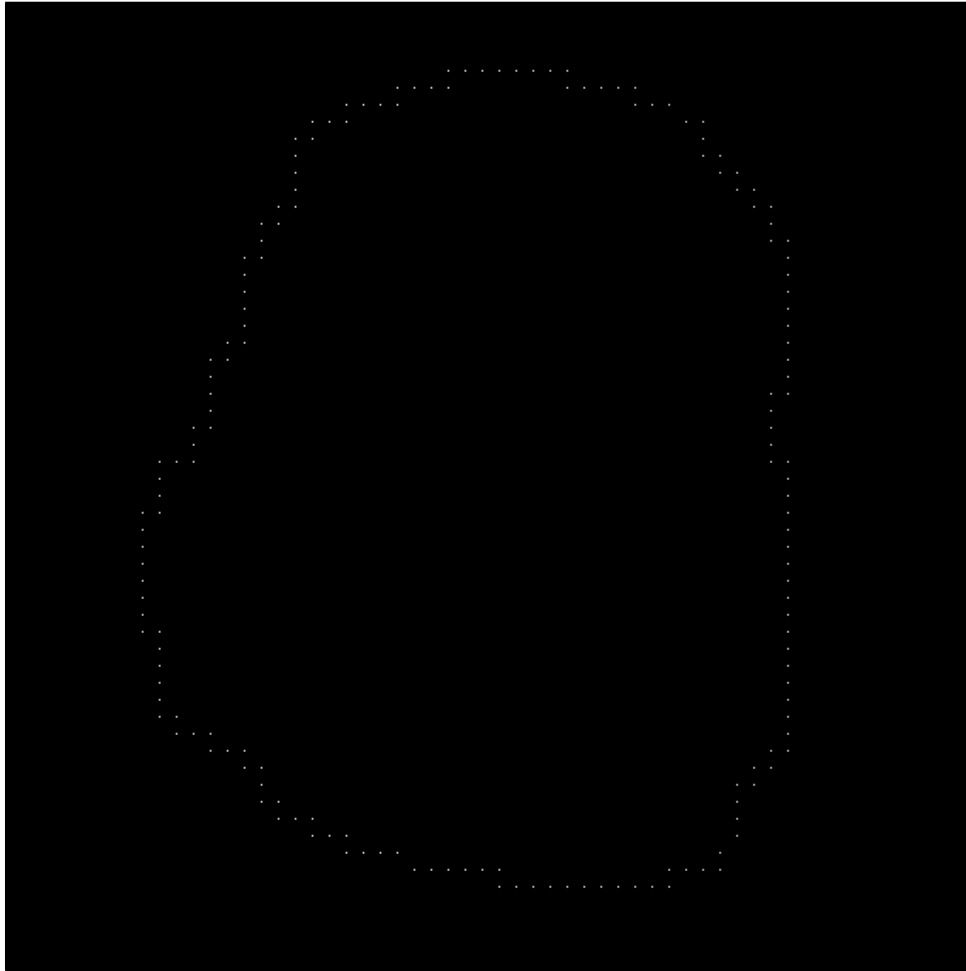


FIGURE A.11 – Resampling grid ( $S = (10, 10)$ )

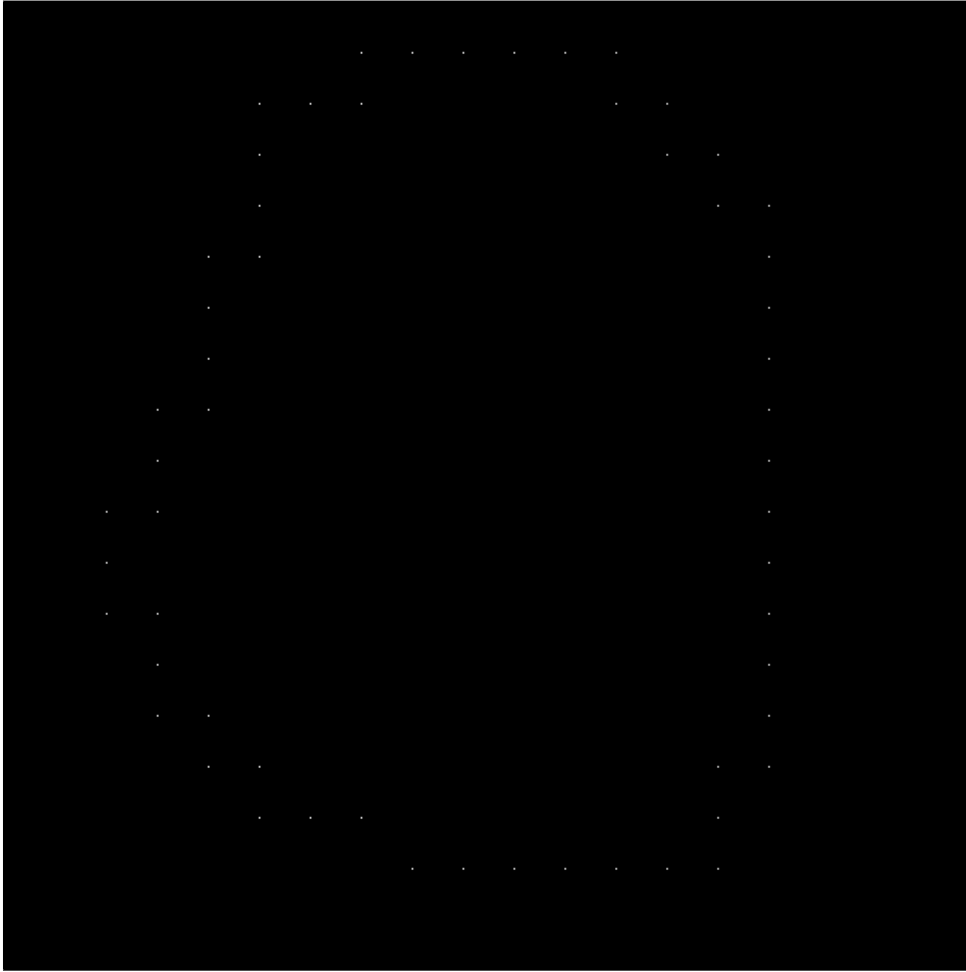
Chaincode (length = 170) :

```
0000006000060070660606060660666666
664666606666666666666666664646466656
4446444444444244444344424424424224
244244242222422222202220022022220
202222202202022220200200020002
```

First difference (length = 169) :

```
00000620006207160262626260260000000
062000260000000000000000062626200716
00260000000006200007100620620626026
20620626000026000000620060206200062
62000062062620006260260026002
```

### A.5.2 Chain code - resampling grid (30, 30)



**FIGURE A.12** – Resampling grid ( $S = (30, 30)$ )

Chaincode (length = 56) :

00060606066666666666466444444344242422422022022202220020

First difference (length = 55) :

0062626260000000000620600000710626260260620620062006026



## A.6 Principal components

```
python pc.py -diff -n 2
```