

Introduction to Deep Learning

Chapter 5: MLP – Matrix Notation

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LECTURE OUTLINE

This chapter introduces a compact way for representing feedforward neural networks: the matrix formalism from linear algebra.

- First, we explore networks with one hidden layer and one output unit.
- Next, we investigate networks with one hidden layer but multiple output units.
- Finally, we focus on multi-layer feedforward networks with an arbitrary number of hidden layers and output units.

Single Hidden Layer Networks for Regression and Binary Classification

SINGLE HIDDEN LAYER NETWORKS

- The input **x** is a column vector with dimensions $p \times 1$.
- **W** is a weight matrix with dimensions $p \times m$:

$$\mathbf{W} = \begin{pmatrix} w_{1,1} & w_{1,2} & \cdots & w_{1,m} \\ w_{2,1} & w_{2,2} & \cdots & w_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ w_{\rho,1} & w_{\rho,2} & \cdots & w_{\rho,m} \end{pmatrix}$$

• For example, to obtain z_1 , we pick the first column of W:

$$\mathbf{W}_1 = \begin{pmatrix} w_{1,1} \\ w_{2,1} \\ \vdots \\ w_{p,1} \end{pmatrix}$$

and compute $z_1 = \sigma(W_1^\top \mathbf{x} + b_1)$, where b_1 is the bias of the first hidden neuron and $\sigma : \mathbb{R} \to \mathbb{R}$ is an activation function.

General notation:

• The network has m hidden neurons z_1, \ldots, z_m with

$$z_j = \sigma(\mathbf{W}_j^{\top} \mathbf{x} + b_j)$$

- $\bullet \ z_{in,j} = \mathbf{W}_{i}^{\top} \mathbf{x} + b_{j}$
- $\bullet \ \ z_{out,j} = \sigma(z_{in,j}) = \sigma(\mathbf{W}_j^{\top} \mathbf{x} + b_j)$

for $j \in \{1, ..., m\}$.

- Vectorized notation:
 - $\mathbf{z}_{in} = (z_{in,1}, \dots, z_{in,m})^{\top} = \mathbf{W}^{\top} \mathbf{x} + \mathbf{b}$ (Note: $\mathbf{W}^{\top} \mathbf{x} = (\mathbf{x}^{\top} \mathbf{W})^{\top}$)
 - $\mathbf{z} = \mathbf{z}_{out} = \sigma(\mathbf{z}_{in}) = \sigma(\mathbf{W}^{\top}\mathbf{x} + \mathbf{b})$, where the (hidden layer) activation function σ is applied element-wise to \mathbf{z}_{in} .
- Bias term:
 - We sometimes omit the bias term by adding a constant feature to the input $\tilde{\mathbf{x}} = (1, x_1, ..., x_p)$ and by adding the bias term to the weight matrix

$$\tilde{\mathbf{W}} = (\mathbf{b}, \mathbf{W}_1, ..., \mathbf{W}_p).$$

 Note: For simplification purposes, we will not explicitly represent the bias term graphically in the following. However, the above "trick" makes it straightforward to represent it graphically.

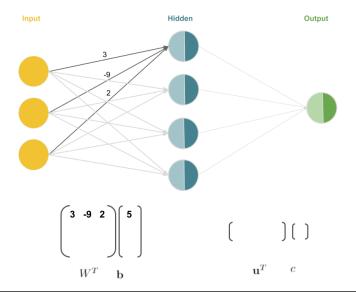
General notation:

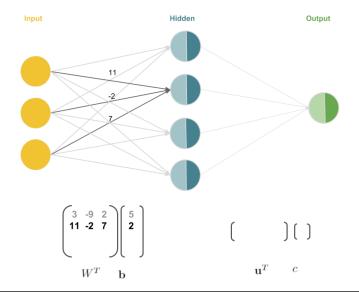
- For regression or binary classification: one output unit f where
 - $f_{in} = \mathbf{u}^{\top}\mathbf{z} + c$, i.e. a linear combination of derived features plus the bias term c of the output neuron, and
 - $f(\mathbf{x}) = f_{out} = \tau(f_{in}) = \tau(\mathbf{u}^{\top}\mathbf{z} + c)$, where τ is the output activation function.
- For regression τ is the identity function.
- ullet For binary classification, au is a sigmoid function.
- **Note**: The purpose of the hidden-layer activation function σ is to introduce non-linearities so that the network is able to learn complex functions whereas the purpose of τ is merely to get the final score on the same scale as the target.

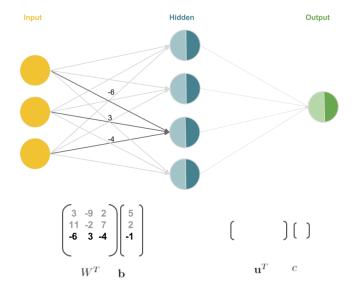
General notation: Multiple inputs

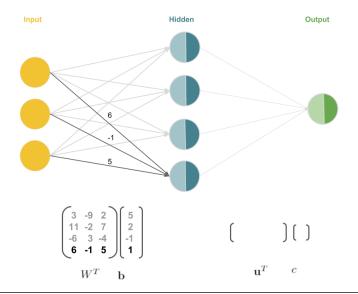
- It is possible to feed multiple inputs to a neural network simultaneously.
- The inputs $\mathbf{x}^{(i)}$, for $i \in \{1, ..., n\}$, are arranged as rows in the design matrix \mathbf{X} .
 - **X** is a $(n \times p)$ -matrix.
- The weighted sum in the hidden layer is now computed as $\mathbf{XW} + \mathbf{B}$, where,
 - **W**, as usual, is a $(p \times m)$ matrix, and,
 - B is a (n × m) matrix containing the bias vector b (duplicated) as the rows of the matrix.
- The *matrix* of hidden activations $\mathbf{Z} = \sigma(\mathbf{XW} + \mathbf{B})$
 - \boldsymbol{Z} is a $(n \times m)$ matrix.

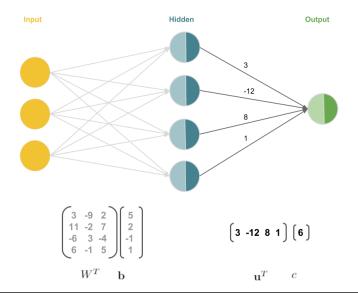
- The final output of the network, which contains a prediction for each input, is $\tau(\mathbf{Z}\mathbf{u} + \mathbf{C})$, where
 - **u** is the vector of weights of the output neuron, and,
 - C is a (n × 1) matrix whose elements are the (scalar) bias c
 of the output neuron.

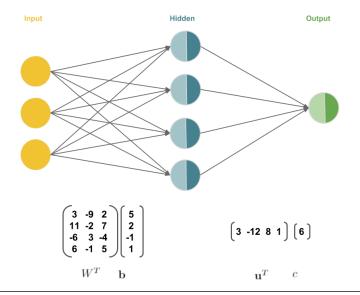


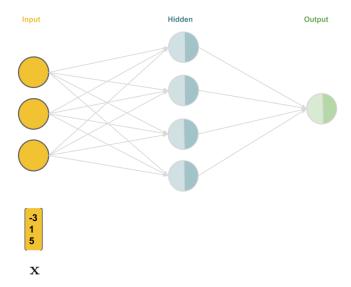


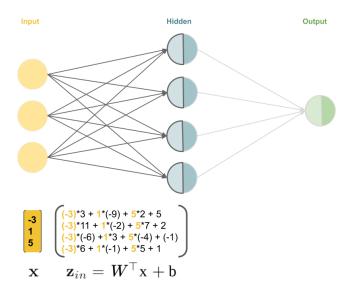


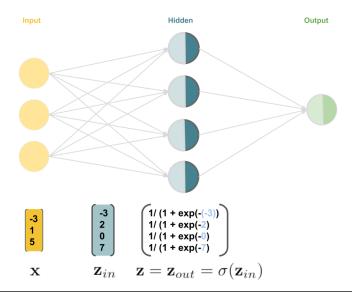


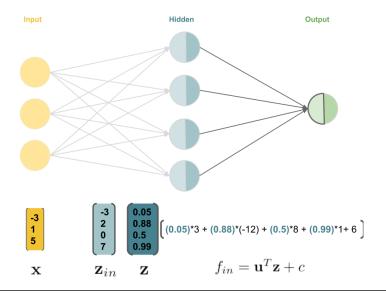


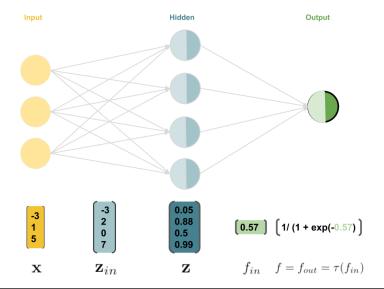


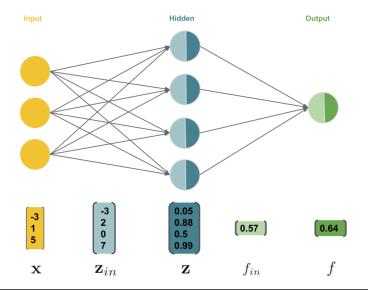












HIDDEN LAYER: ACTIVATION FUNCTION

- It is important to note that if the hidden layer does not have a non-linear activation, the network can only learn linear decision boundaries.
- For simplification purposes, we drop the bias terms in notation and let $\sigma = \text{id}$. Then:

$$f(\mathbf{x}) = \tau(\mathbf{u}^{\top}\mathbf{z}) = \tau(\mathbf{u}^{\top}\sigma(\mathbf{W}^{\top}\mathbf{x}))$$
$$= \tau(\mathbf{u}^{\top}\sigma(\mathbf{W}^{\top}\mathbf{x}))$$
$$= \tau(\mathbf{u}^{\top}\mathbf{W}^{\top}\mathbf{x}) = \tau(\mathbf{v}^{\top}\mathbf{x})$$

where $\mathbf{v} = \mathbf{W}\mathbf{u}$. It can be seen that $f(\mathbf{x})$ can only yield a linear decision boundary.

Single Hidden Layer Networks for Multi-Class Classification

- We have only considered regression and binary classification problems so far.
- How can we get a neural network to perform multiclass classification?

- The first step is to add additional neurons to the output layer.
- Each neuron in the layer will represent a specific class (number of neurons in the output layer = number of classes).

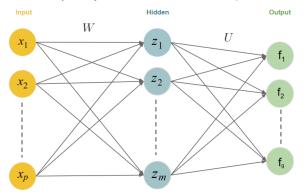


Figure: Structure of a single hidden layer, feed-forward neural network for g-class classification problems (bias term omitted).

Notation:

• For *g*-class classification, *g* output units:

$$\mathbf{f} = (f_1, \ldots, f_g)$$

• m hidden neurons z_1, \ldots, z_m , with

$$z_j = \sigma(\mathbf{W}_i^{\top} \mathbf{x}), \quad j = 1, \dots, m.$$

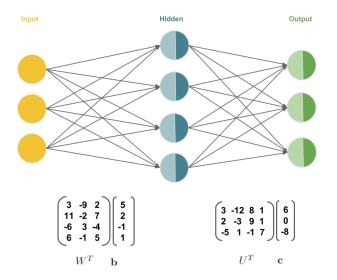
Compute linear combinations of derived features z:

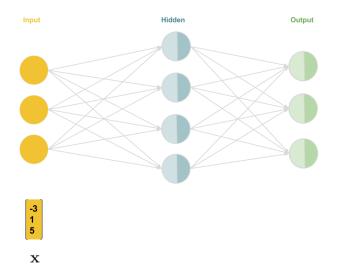
$$f_{in,k} = \boldsymbol{U}_k^{\top} \mathbf{z}, \quad \mathbf{z} = (z_1, \dots, z_m)^{\top}, \quad k = 1, \dots, g$$

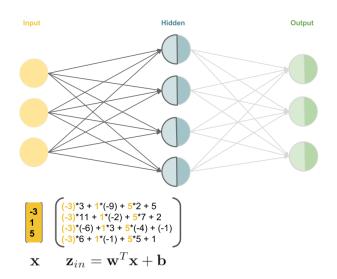
- The second step is to apply a softmax activation function to the output layer.
- This gives us a probability distribution over g different possible classes:

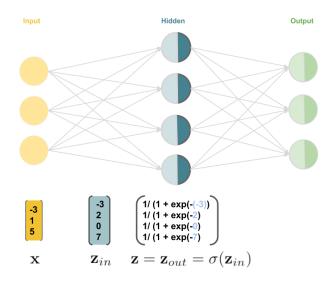
$$f_{out,k} = \tau_k(f_{in,k}) = \frac{\exp(f_{in,k})}{\sum_{k'=1}^g \exp(f_{in,k'})}$$

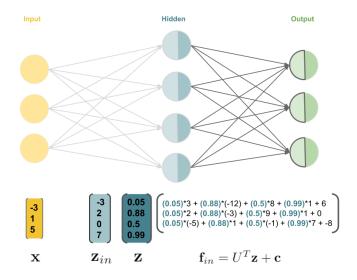
- This is the same transformation used in softmax regression!
- Derivative $\frac{\delta au(\mathbf{f}_{\textit{in}})}{\delta \mathbf{f}_{\textit{in}}} = \text{diag}(au(\mathbf{f}_{\textit{in}})) au(\mathbf{f}_{\textit{in}}) au(\mathbf{f}_{\textit{in}})^{\top}$
- It is a "smooth" approximation of the argmax operation, so $\tau((1,1000,2)^{\top}) \approx (0,1,0)^{\top}$ (picks out 2nd element!).

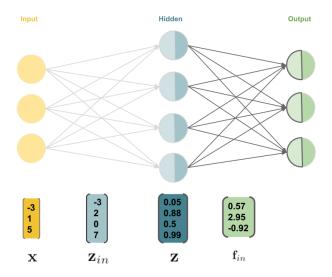


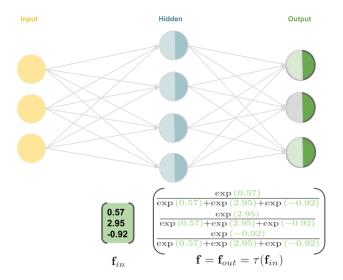


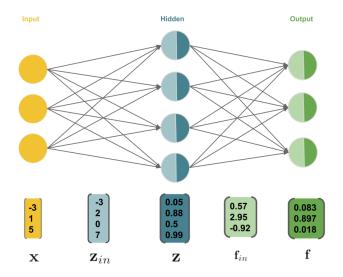












SOFTMAX LOSS

The loss function for a softmax classifier is

$$L(y, f(\mathbf{x})) = -\sum_{k=1}^{g} [y = k] \log \left(\frac{\exp(f_{in,k})}{\sum_{k'=1}^{g} \exp(f_{in,k'})} \right)$$
 where $[y = k] = \begin{cases} 1 & \text{if } y = k \\ 0 & \text{otherwise} \end{cases}$.

- This is equivalent to the cross-entropy loss when the label vector \mathbf{y} is one-hot coded (e.g. $\mathbf{y} = (0, 0, 1, 0)^{\top}$).
- Optimization: Again, there is no analytic solution.



FEEDFORWARD NEURAL NETWORKS

- We will now extend the model class once again, such that we allow an arbitrary amount of *I* (hidden) layers.
- The general term for this model class is (multi-layer) feedforward networks (inputs are passed through the network from left to right, no feedback-loops are allowed)

FEEDFORWARD NEURAL NETWORKS

• We can characterize those models by the following chain structure:

$$f(\mathbf{x}) = \tau \circ \phi \circ \sigma^{(l)} \circ \phi^{(l)} \circ \sigma^{(l-1)} \circ \phi^{(l-1)} \circ \dots \circ \sigma^{(1)} \circ \phi^{(1)}$$

where $\sigma^{(i)}$ and $\phi^{(i)}$ are the activation function and the weighted sum of hidden layer i, respectively. τ and ϕ are the corresponding components of the output layer.

- Each hidden layer has:
 - an associated weight matrix $\mathbf{W}^{(i)}$, bias $\mathbf{b}^{(i)}$ and activations $\mathbf{z}^{(i)}$ for $i \in \{1 \dots l\}$

$$\bullet \ \mathbf{z}^{(i)} = \sigma^{(i)}(\phi^{(i)}) = \sigma^{(i)}(\mathbf{W}^{(i)\intercal}\mathbf{z}^{(i-1)} + \mathbf{b}^{(i)}) \ \text{, where } \mathbf{z}^{(0)} = \mathbf{x}.$$

 Again, without non-linear activations in the hidden layers, the network can only learn linear decision boundaries.

FEEDFORWARD NEURAL NETWORKS

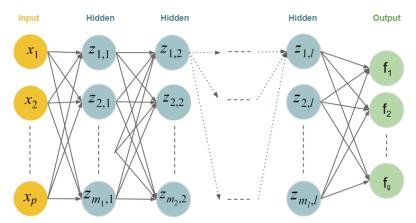
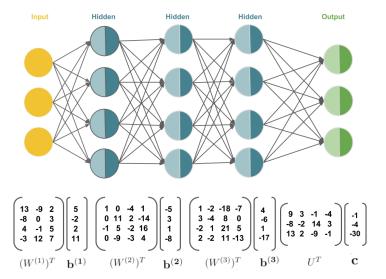
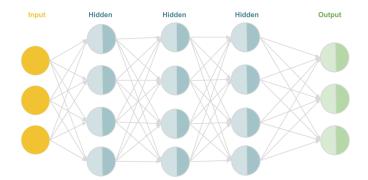


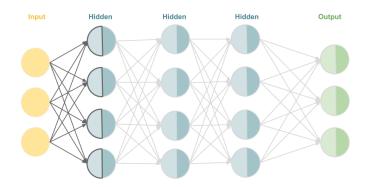
Figure: Structure of a deep neural network with / hidden layers (bias terms omitted).



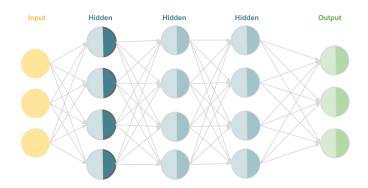




 \mathbf{x}



$$\mathbf{x} \quad \mathbf{z}_{in}^{(1)} = W^{(1)T}\mathbf{x} + \mathbf{b}^{(1)}$$



$$\begin{bmatrix} 7 \\ 1 \\ -4 \\ \end{bmatrix} \begin{bmatrix} 79 \\ -70 \\ 9 \\ -26 \\ \end{bmatrix} \begin{bmatrix} max(0, 79) \\ max(0, -70) \\ max(0, 9) \\ max(0, -26) \\ \end{bmatrix}$$

$$\mathbf{x} \quad \mathbf{z}_{in}^{(1)} \ \mathbf{z}^{(1)} = \mathbf{z}_{out}^{(1)} = \sigma(\mathbf{z}_{in}^{(1)})$$

