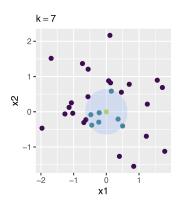
Introduction to Machine Learning

k-Nearest Neighbors Regression



Learning goals

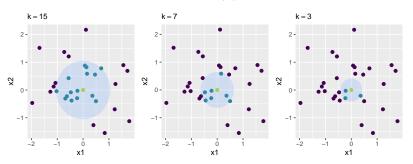
- Understand the basic idea of k-NN
- Know different distance measures for different scales of feature variables
- Understand that k-NN has no optimization step

NEAREST NEIGHBORS: INTUITION

- Say we know locations of cities in 2 different countries.
- Say we know which city is in which country.
- Say we don't know where the countries' border is.
- For a given location, we want to figure out which country it belongs to.
- Nearest neighbor rule: every location belongs to the same country as the closest city.
- k-nearest neighbor rule: vote over the k closest cities (smoother)

K-NEAREST-NEIGHBORS

- *k*-**NN** can be used for regression and classification
- It generates predictions ŷ for a given x by comparing the k observations that are closest to x
- "Closeness" requires a distance or similarity measure (usually: Euclidean).
- The set containing the k closest points $\mathbf{x}^{(i)}$ to \mathbf{x} in the training data is called the k-neighborhood $N_k(\mathbf{x})$ of \mathbf{x} .



How to calculate distances?

- Most popular distance measure for numerical features: Euclidean distance
- Imagine two data points $\mathbf{x} = (x_1, ..., x_p)$ and $\tilde{\mathbf{x}} = (\tilde{x}_1, ..., \tilde{x}_p)$ with p features $\in \mathbb{R}$.
- The Euclidean distance:

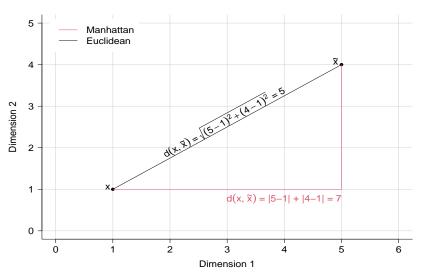
$$d_{Euclidean}(\mathbf{x}, \tilde{\mathbf{x}}) = \sqrt{\sum_{j=1}^{p} (x_j - \tilde{x}_j)^2}$$

- Example:
 - Three data points with two metric features each: a = (1,3), b = (4,5) and c = (7,8)
 - Which is the nearest neighbor of b in terms of the Euclidean distance?
 - $d(b,a) = \sqrt{(4-1)^2 + (5-3)^2} = 3.61$
 - $d(b,c) = \sqrt{(4-7)^2 + (5-8)^2} = 4.24$
 - \Rightarrow a is the nearest neighbor for b.
- Alternative distance measures are:
 - Manhattan distance

$$d_{manhattan}(\mathbf{x}, \tilde{\mathbf{x}}) = \sum_{j=1}^{p} |x_j - \tilde{x}_j|$$

ullet Mahalanobis distance (takes covariances in ${\mathcal X}$ into account)

Comparison between Euclidean and Manhattan distance measures:



Categorical variables, missing data and mixed space:

The Gower distance $d_{gower}(\mathbf{x}, \tilde{\mathbf{x}})$ is a weighted mean of $d_{gower}(x_j, \tilde{x}_j)$:

$$d_{gower}(\mathbf{x}, \widetilde{\mathbf{x}}) = rac{\sum\limits_{j=1}^{p} \delta_{x_{j}, \widetilde{x}_{j}} \cdot d_{gower}(x_{j}, \widetilde{x}_{j})}{\sum\limits_{j=1}^{p} \delta_{x_{j}, \widetilde{x}_{j}}}.$$

• δ_{x_j,\tilde{x}_j} is 0 or 1. It becomes 0 when the j-th variable is **missing** in at least one of the observations (\mathbf{x} or $\tilde{\mathbf{x}}$), or when the variable is asymmetric binary (where "1" is more important/distinctive than "0", e. g., "1" means "color-blind") and both values are zero. Otherwise it is 1.

• $d_{gower}(x_j, \tilde{x}_j)$, the j-th variable contribution to the total distance, is a distance between the values of x_j and \tilde{x}_j . For nominal variables the distance is 0 if both values are equal and 1 otherwise. The contribution of other variables is the absolute difference of both values, divided by the total range of that variable.

Example of Gower distance with data on sex and income:

index	sex	salary
1	m	2340
2	W	2100
3	NA	2680

$$d_{gower}(\mathbf{x}, ilde{\mathbf{x}}) = rac{\sum\limits_{j=1}^{p} \delta_{x_{j}, ilde{x}_{j}} \cdot d_{gower}(x_{j}, ilde{x}_{j})}{\sum\limits_{j=1}^{p} \delta_{x_{j}, ilde{x}_{j}}}$$

$$d_{gower}(\mathbf{x}^{(1)}, \mathbf{x}^{(2)}) = \frac{1 \cdot 1 + 1 \cdot \frac{|2340 - 2100|}{|2680 - 2100|}}{1 + 1} = \frac{1 + \frac{240}{580}}{2} = \frac{1 + 0.414}{2} = 0.707$$

$$d_{gower}(\mathbf{x}^{(1)}, \mathbf{x}^{(3)}) = \frac{0.1 + 1.\frac{|2340 - 2680|}{|2680 - 2100|}}{0 + 1} = \frac{0 + \frac{340}{580}}{1} = \frac{0 + 0.586}{1} = 0.586$$

$$d_{gower}(\mathbf{x}^{(2)}, \mathbf{x}^{(3)}) = \frac{0.1 + 1.\frac{|2100 - 2680|}{|2680 - 2100|}}{0 + 1} = \frac{0 + \frac{580}{580}}{1} = \frac{0 + 1.000}{1} = 1$$

Weights:

Weights can be used to address two problems in distance calculation:

- Standardization: Two features may have values with a different scale. Many distance formulas (not Gower) would place a higher importance on a feature with higher values, leading to an imbalance. Assigning a higher weight to the lower-valued feature can combat this effect.
- **Importance:** Sometimes one feature has a higher importance (e. g., more recent measurement). Assigning weights according to the importance of the feature can align the distance measure with known feature importance.

For example:

$$d_{ extit{Euclidean}}^{ extit{weighted}}\left(\mathbf{x}, \widetilde{\mathbf{x}}
ight) = \sqrt{\sum_{j=1}^{
ho} w_j (x_j - \widetilde{x}_j)^2}$$

K-NN REGRESSION

Predictions for regression:

$$\hat{y} = \frac{1}{k} \sum_{i: \mathbf{x}^{(i)} \in N_k(\mathbf{x})} y^{(i)}$$

$$\hat{y} = \frac{1}{\sum_{i: \mathbf{x}^{(i)} \in N_k(\mathbf{x})} w_i} \sum_{i: \mathbf{x}^{(i)} \in N_k(\mathbf{x})} w_i y^{(i)}$$

with neighbors weighted according to their distance to **x**: $w_i = \frac{1}{d(\mathbf{x}^{(i)}, \mathbf{x})}$

K-NN SUMMARY

- *k*-NN has no optimization step and is a very local model.
- We cannot simply use least-squares loss on the training data for picking k, because we would always pick k = 1.
- k-NN makes no assumptions about the underlying data distribution.
- The smaller k, the less stable, less smooth and more "wiggly" the decision boundary becomes.
- Accuracy of k-NN can be severely degraded by the presence of noisy or irrelevant features, or when the feature scales are not consistent with their importance.

K-NN SUMMARY

Hypothesis Space: Step functions over tesselations of \mathcal{X} .

Hyperparameters: distance measure $d(\cdot, \cdot)$ on \mathcal{X} ; size of neighborhood k.

Risk: Use any loss function for regression or classification.

Optimization: Not applicable/necessary.

But: clever look-up methods & data structures to avoid computing all *n* distances for generating predictions.