# SOFTWARE ENGINEERING IN THE MARIOKART SYSTEM

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## OUTLINE

- 1 Build Toolchain
  - GNU, GNU, GNU
- 2 Source Control
  - Git
  - Github
- 3 Continuous Integration
  - What is it?
  - Why would you use it?
  - CI Joe
  - Examples
- 4 Questions

# BUILD TOOLCHAIN

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arm-eabi-gcc - The GNU Compiler Collection

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## Build Toolchain

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- arm-eabi-gdb The GNU Project Debugger
- openocd Open On-Chip Debugger
- GNU make
  - Lots of targets to enable easy programming, debugging and testing.

GIT

## GIT

Distributed Version Control System (DVCS)

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- Very "branch-friendly."



## GITHUB

#### About

"Originally founded by Chris Wanstrath, PJ Hyett and Tom Preston-Werner as a project to simplify sharing code, GitHub has grown into an application used by nearly a million people to store over two million code repositories, making GitHub the largest code host in the world." – https://github.com/about GITHUB

# Web Interface<sup>†</sup>

	name	age	message	history
	Altium/	September 03, 2011	Updated the pdf [steakunderscore]	
	CAD/	September 08, 2011	Stress calculations and visual output [SimonRichards]	
=	Documentation/	12 minutes ago	Merge branch 'master' of github.com:team-ramrod/ma [steakunderscore]	
	Modeling/	September 09, 2011	completed models [Simon Richards]	
	Simon/	about 6 hours ago	more text [SimonRichards]	
	Software/	3 days ago	Merge branch 'master' of github.com:team-ramrod/ma [Nemo157]	
	.gitattributes	April 25, 2011	Spelling mistake in gitignore and gitattributes. A [Nemo157]	
	.gitignore	3 days ago	Added my presentation [Nemo157]	
	README.md	August 24, 2011	an attempt to annoy wim [SimonRichards]	

<sup>†</sup>https://github.com/team-ramrod/mariokart

### GITHUB

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#### **Project Goal**

This was taken from the inital project list:

The aim of this project is to take the departments go-karts and build in a system to replace the human driver. This will entail (at least), selection of appropriate actuators, motion and distance sensors, development of a navigation system, an interface to the existing control system, and a central computing platform. A suitable navigational goal would include a circumnavigation of S block.

## WHAT IS CONTINUOUS INTEGRATION?

#### Definition<sup>†</sup>

"Continuous Integration is a software development practice . . . leading to multiple integrations per day . . . verified by an automated build . . . to detect integration errors as quickly as possible." — Martin Fowler

<sup>†</sup>http://martinfowler.com/articles/continuousIntegration.html

Detect errors early.

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  - Very useful for branch-happy development in git.
- Peer pressure.

## CI JOE<sup>†</sup>

REPOSITORY DESCRIPTION

"CI Joe is a fun Continuous Integration server."

<sup>†</sup>https://github.com/defunkt/cijoe

Simple setup.

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- Designed to work with git.
- · Can trigger a build via a post-hook on github.
- Reports status via build-hook (used to send email).

CI Joe because knowing is half the battle

#### mariokart



2011-09-18 01:28 » Built master at <u>b464a16</u> (worked) in 135.826144 seconds.

Cl Joe because knowing is half the battle

#### mariokart

```
2011-09-18 03:20 » Build starting...
```

2011-09-18 01:28 » Built master at <u>b464a16</u> (worked) in 135.826144 seconds.

```
CI Joe because knowing is half the battle
mariokart
Build
2011-09-18 03:20 » Built master at fc2a97c (failed) in 4.422625 seconds.
make: Entering directory \'var/www/cijoe-repos/mariokart/app/Software'
make[1]: Entering directory `/var/www/cijoe-repos/mariokart/app/Software'
src/brake/main.c: In function 'main':
src/brake/main.c:102:27: error: expected expression before ';' token
src/brake/main.c:135:5: error: expected ';' before '}' token
src/brake/main.c:97:15: error: unused variable 'msq' [-Werror=unused-variable]
ccl: all warnings being treated as errors
make[1]: *** [build/objs/src/brake/main.o] Error 1
make[1]: Target `rebuild' not remade because of errors.
make[1]: Leaving directory \daryww/cijoe-repos/mariokart/app/Software'
make: *** [test] Error 2
make: Leaving directory \u2214var/www/cijoe-repos/mariokart/app/Software'
```

From: CI Joe <cijoe@nemo157.com>

Subject: Building mariokart Failed

Date: 18 September 2011 3:21:23 PM NZST

To: ag@henryjenkins.name

Hide
1 Duplicate 2

### **Building mariokart failed**

#### Latest commit info:

• fc2a97c: Breaking the build for my presentation - Wim Looman <ghostunderscore@gmail.com>

#### **Build Output**

```
make: Entering directory `/var/www/cijoe-repos/mariokart/app/Software'
make[1]: Entering directory `/var/www/cijoe-repos/mariokart/app/Software'
src/broke/main.c: In function 'main':
src/broke/main.c: In function 'main':
src/broke/main.c: In function 'main':
src/broke/main.cib/sis-enrore appeared '' bafore '' bafore
src/broke/main.cib/sis-enrore appeared '' bafore '' bafore
src/broke/main.cib/sis-enrore appeared '' bafore ''
total damning being stacked to stand

make[1]: *** [build/objs/src/broke/main.o] Error 1
sector of the standard appeared to standard to stand
```

CI Joe

Because knowing is half the battle.



## GIT VS SVN

#### GIT

- Distributed (central repository can be used).
- Every clone is a full repository.
- Continual branching and merging is expected.

#### SVN

- Needs a single central repository.
- Can't commit without access to central repository.
- Branching and merging is painful.

## GIT OVERVIEW

## GITHUB OVERVIEW

### Unit Testing

- Initially was planned.
- Would require mocking and simulating the entire SAM7XC architecture.
  - · Hundreds to thousands of registers.
  - · Need constraints on which registers get written in which orders.
- Would be awesome, but probably too large for even its own final year project.