

Software Engineering in the Mariokart System

Wim Looman

wgl18@uclive.ac.nz

Coauthors: Simon Richards, Zachary Taylor and Henry Jenkins

scr52@uclive.ac.nz zjt14@uclive.ac.nz hvj10@uclive.ac.nz

Supervisor: Dr. Andrew Bainbridge-Smith

andrew.bainbridge-smith@canterbury.ac.nz

Department of Electrical and Computer Engineering

University of Canterbury

Christchurch, New Zealand

Abstract—Something amazing about engineering a software system.

I. INTRODUCTION

A. Software Engineering

Since this report is aimed at an engineering audience most of you will believe that a description of Software Engineering is not really required. Unfortunately true Software Engineering is relatively unknown, especially in programming courses run in Electrical departments around the world. That is not to say that Computer Science departments do a better job of teaching it, in fact Software Engineering really should be taught as a subset of Engineering [1], just that the style of programming taught to Electrical students is generally light on following the engineering practices that the rest of their courses rely on.

So, what is Software Engineering? It is simply the application of standard Engineering practice to the development of software. However because of the nature of software as a much more fluid abstract thing than the normal circuits designed by Electrical Engineers the precise method of application has to be changed.

At the same time as being more abstract than a circuit software is also much more concrete; there are no (or at least very few) annoying real world effects directly on the software. Assuming the circuit a microprocessor is in has been designed well the Software Engineer can take it for granted that the digital I/O used by something like a Inter-Integrated Circuit (I²C) is basically a perfect connection straight to the internals of another device. Internally if there are no weird defects in the microcontroller you can assume that a function like:

```
int return_three() {  
    int three = 3;  
    return three;  
}
```

will always return exactly 3. Not 2 when the batteries start running low, not 4 when it is a particularly hot day, always exactly 3.

This exactness of software enables the use of a few techniques that are not normally available in most engineering professions. For example it is possible to perform exhaustive testing and/or modelling of the system within acceptable time.

B. Mariokart

The system on which this report will base most of the examples was codenamed Mariokart. This was a final year project for the University of Canterbury's Bachelor of Engineering degree carried out by the authors. The overall goal of the project was to take one of the electric go-karts the department had and retrofit a drive-by-wire system on to it with an overall goal of having the kart autonomously drive around the campus. For the purposes of this report the main details are:

The overall design is a distributed system, 5 boards are used; one for communication with a host laptop, one for steering, one for brakes, one to interface to the motor controller and one for collecting data from a variety of sensors.

Each board is running an Atmel SAM7XC microprocessor.

For more details see *Embedded Hardware Design For Autonomous Electric Vehicle* by Henry Jenkins [2].

REFERENCES

- [1] D. L. Parnas, "Software engineering programs are not computer science programs," *IEEE Software*, vol. 16, no. 6, pp. 19–30, 1999. [Online]. Available: <http://ieeexplore.ieee.org/lpdocs/epic03/wrapper.htm?arnumber=805469>

- [2] H. Jenkins, "Embedded hardware design for autonomous electric vehicle," 2011. [Online]. Available: <https://raw.githubusercontent.com/team-ramrod/mariokart/Documentation/ScientificReport/Henry/report.pdf>