

**M8063 Falcon
SBC-11/21
Single-Board
Computer
User's Guide**

PRELIMINARY

Prepared by Educational Services
of
Digital Equipment Corporation

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PREFACE

This manual provides the user with configuration, system architecture and programming information for the SBC-11/21. The configuration requirements are described in Chapter 2 and the system architecture is presented in Chapter 5. The programming techniques are described in Chapter 6 and the instruction set is listed in Chapter 7. The operational theory is presented in Chapter 8 and the schematics are in Appendix E. The Macro-ODT option is described in Chapter 4 and the listing is in Appendix D. Options for use on the LSI-11 bus are listed in Chapter 3 and the module bus requirements are described in Chapter 9. An example of software development is covered by Appendix C. Appendix A summarizes the instruction timing and Appendix B compares the SBC-11/21 to other LSI-11 microprocessors.

NOTE

This manual is to be used only for the SBC-11/21 module, M8063 Revision C. This revision can be identified by the circuit board #501448C located on the module as described in Figure 1-1.

CHAPTER 1
INTRODUCTION

1.0 GENERAL

The KXT11-AA (M8063) module is shown in Figure 1-1 and designated as the SBC-11/21 single board computer. It is a complete computer system on an 8.5 X 5.2 inch printed circuit board that executes the well known PDP-11 instruction set (see Appendix B). The SBC-11/21 module contains 4 Kb of RAM, sockets for up to 32 Kb of PROM or additional RAM, two serial I/O lines, 24 lines of parallel I/O and a 50 Hz, 60 Hz or 800 Hz real time clock. In addition, the SBC-11/21 is equipped with a complete LSI-11 bus interface which enables it to communicate with most of DIGITAL's large family of modules (see Chapter 3) as described in the Microcomputer Interfaces and Microcomputers and Memories handbooks.

The SBC-11/21 features the following:

- o A powerful processor running the PDP-11 instruction set.
- o Direct addressing of 32K, 16-bit words, or 64K 8-bit bytes ($K = 1024$).
- o Efficient processing of 8-bit characters without the need to rotate, swap or mask.
- o On-board 4K bytes of static read/write memory.
- o Sockets for up to 32K bytes of PROM, jumper configurable for a wide range of memory types from several vendors. Additional RAM can also be installed in these sockets.
- o Hardware memory stack for handling structured data, subroutines, and interrupts.
- o Direct-memory access for high-data-rate devices inherent in the bus architecture.
- o Eight general-purpose registers that are available for data storage, pointers and accumulators; two are dedicated: SP and PC.
- o Fast on-board bus for high throughput when external memory access is not required.
- o LSI-11 bus structure that provides position-dependent priority as peripheral device interfaces are connected to the I/O bus.
- o Fast interrupt response without device polling.
- o A powerful and convenient set of programming

instructions.

- o Two serial I/O interfaces, compatible with EIA RS-232C and EIA RS-423, with software programmable baud rates over the range of 300 to 38,400 baud.
- o One parallel I/O interface, with two bidirectional 8-bit input/output ports, and one 8-bit control port.
- o Real-time clock which can be set by the user to 50 Hz, 60 Hz or 800 Hz.
- o Many jumper-configurable operating modes, including four different memory maps, exception handling, start and restart address, parallel I/O configurations, and real-time clock frequency.
- o Optional PROM resident Macro-ODT containing module diagnostics, bootstrap programs for mass storage devices (TU58, RX02 and RX02), console communications and on-line debugging facility.

1.1 SPECIFICATIONS

The SBC-11/21 module specifications are described below:

1.1.1 Physical

Height	13.2 cm (5.2 in)
Length (includes module handle)	22.8 cm (8.9 in)
Width	1.27 cm (0.5 in)
Weight	360 gm (12 oz) max

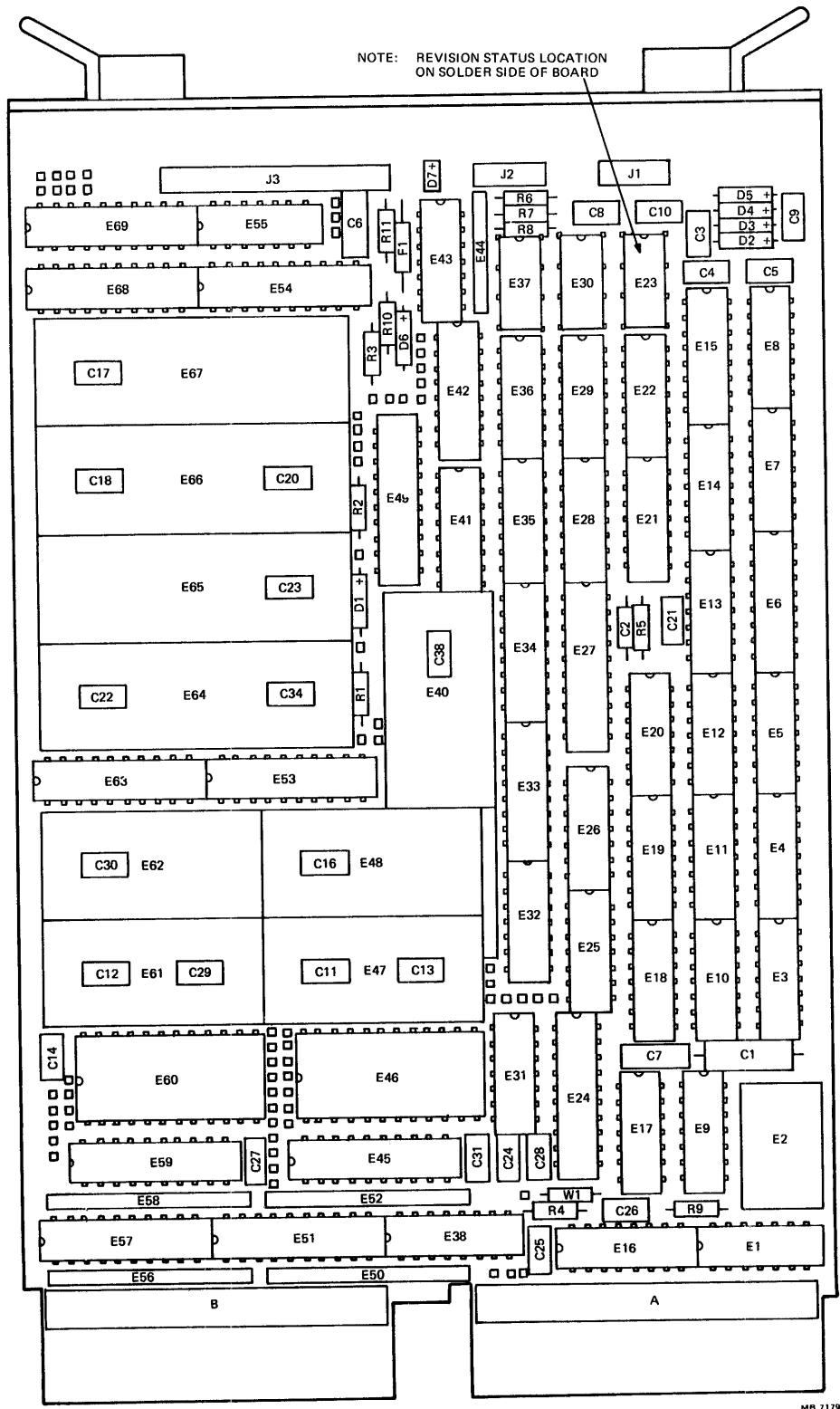
1.1.2 Power Requirements

Power Supply:

+5.0 V \pm 5%	2.5 A (Typical) 2.8 A (Maximum)
+12.0 V \pm 5%	60 mA (typical) used by on-board circuitry
	1.1 A (Maximum) includes current supplied to outside world through pin 10 of the serial I/O connector

Battery Backup:

+5.0 V \pm 5%	170 mA (Typical) 260 mA (Maximum)
-----------------	--------------------------------------



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Figure 1-1 KXT11-AA (M8063) SBC-11/21 Module

NOTE

The +12.0 V typical current is measured with no connections at pin 10 of the serial I/O connectors (fused line).

1.1.3 Bus Loading

A.C. Loads	2.4
D.C. Loads	1.0

1.1.4 Environmental

Temperature:

Storage	-40° to 65° C (-40 to 150° F)
Operating	5° to 60° C (41° to 140° F)

NOTE

The module must be brought into the operating temperature environment and allowed to stabilize before operating.

Relative Humidity:

Storage	10% to 90% (no condensation)
Operating	10% to 90% (no condensation)

Altitude:

Storage	Up to 15 Km (50,000 ft)
Operating	Up to 15 Km (50,000 ft) (90 mm mercury minimum)

NOTE

Derate the maximum operating temperature by 1° C (1.8° F) for each 300 m (1000 ft) of altitude above 2.4 Km (8000 ft).

Environment: Air must be non-caustic.

Airflow: (operating)

Adequate airflow must be provided to limit the inlet to outlet temperature rise across the module to 5° C (9° F) when the inlet temperature is 60° C (140° F). For operation below 55° C (131° F), airflow must be provided to limit the inlet to outlet temperature rise across the module to 10° C (18° F) maximum.

NOTE

These are design limits. Lower temperature limits will serve to increase the life of the product.

1.2 BACKPLANE PIN UTILIZATION

Backplane pin connections for the SBC-11/21 module are listed in Table 1-1. The table also includes pin utilization and signal names unique to the SBC-11/21 module and a list of standard LSI-11 bus backplane names associated with each pin. Note that although the signal names may differ, the module is completely LSI-11 bus compatible, with the exception of bus refresh transaction (BREF), not performed by the SBC-11/21. Signals STOP L, SRUN L, and START L are not used on the LSI-11 bus. These are TTL level signals unique to the SBC-11/21.

Table 1-1 SBC-11/21 Module Backplane Pin Utilization

Side 1 (Component Side)

Backplane Pin	SBC-11/21 Signal Function	LSI-11 Bus Signal Name
AA1	Bus terminator	BIRQ5 L
AB1	Bus terminator	BIRQ6 L
AC1	Bus terminator	BDAL16 L
AD1	Bus terminator	BDAL17 L
AE1	STOP L	SSPARE1
AF1	SRUN L	SSPARE2
AH1	Not connected	SSPARE3
AJ1	GND	GND
AK1	Not connected	MSPAREA
AL1	GND	MSPAREA
AM1	GND	GND
AN1	BDMR L	BDMR L
AP1	BHALT L	BHALT L
AR1	Bus terminator	BREF L
AS1	Not connected	+12B
AT1	GND	GND
AU1	Not connected	PSPARE1
AV1	+5 VB (battery)	+5B
BA1	BDCOK H	BDCOK H
BB1	BPOK H	BPOK H
BC1	Bus terminator	SSPARE4
BD1	Bus terminator	SSPARE5
BE1	Bus terminator	SSPARE6
BF1	Bus terminator	SSPARE7
BH1	START L	SSPARE8
BJ1	GND	
BK1	Not connected	MSPAREB
BL1	Not connected	MSPAREB
BM1	GND	
BN1	BSACK L	BSACK L
BP1	Bus terminator	BIRQ7 L
BR1	BEVNT L	BEVNT L
BS1	Not connected	+12B
BT1	GND	GND
BU1	Not connected	PSPARE2
BV1	+5 V	+5 V

Table 1-1 SBC-11/21 Module Backplane Pin Utilization (Cont)

Side 2 (Solder Side)

Backplane Pin	SBC-11/21 Signal Function	LSI-11 Bus Signal Name
AA2	+5 V	+5 V
AB2	Not connected	-12 V
AC2	GND	GND
AD2	+12 V	+12 V
AE2	BDOUT L	BDOUT L
AF2	BRPLY L	BRPLY L
AH2	BDIN L	BDIN L
AJ2	BSYNC L	BSYNC L
AK2	BWTBT L	BWTBT L
AL2	BIRQ4 L	BIRQ4 L
AM2	Not connected	BIRKI L
AN2	BIAKO L	BIAKO L
AP2	BBS7 L	BBS7 L
AR2	Not connected	BDMGI L
AS2	BDMGO L	BDMGO L
AT2	BINIT L	BINIT L
AU2	BDAL0 L	BDAL0 L
AV2	BDAL1 L	BDAL1 L
BA2	+5 V	+5 V
BB2	Not connected	-12 V
BC2	GND	GND
BD2	+12 V	+12 V
BE2	BDAL2 L	BDAL2 L
BF2	BDAL3 L	BDAL3 L
BH2	BDAL4 L	BDAL4 L
BJ2	BDAL5 L	BDAL5 L
BK2	BDAL6 L	BDAL6 L
BL2	BDAL7 L	BDAL7 L
BM2	BDAL8 L	BDAL8 L
BN2	BDAL9 L	BDAL9 L
BP2	BDAL10 L	BDAL10 L
BR2	BDAL11 L	BDAL11 L
BS2	BDAL12 L	BDAL12 L
BT2	BDAL13 L	BDAL13 L
BU2	BDAL14 L	BDAL14 L
BV2	BDAL15 L	BDAL15 L

1.3 RELATED HARDWARE MANUALS

The primary reference document for the SBC-11/21 is this volume. A considerable amount of useful information about other LSI-11 bus compatible products may be found in the following publications.

Title	Document No.
Microcomputers and Memories Handbook, 1981 Edition	EB-18451-20
Microcomputer Interfaces Handbook, 1980 Edition	EB-20175-20
PDP-11 Bus Handbook, 1979 Edition	EB-17525-20

These documents can be ordered from:

Digital Equipment Corporation
444 Whitney St.
Northboro, MA 01532

Attention: Printing and Circulation
Mail Station NR-2/W3

CHAPTER 2 INSTALLATION

2.0 GENERAL

The installation procedure for the SBC-11/21 single-board computer module must include the following.

NOTE

It is best to leave the factory configuration undisturbed until module performance has been verified.

- o Install jumpers to select operational features.
- o Select and mount an LSI-11 bus-structured backplane and add any required LSI-11 bus options.
- o Select and connect an appropriate power supply.
- o Provide appropriate cables to connect external devices to the serial and parallel I/O interfaces.
- o Verify operation of the module.

These items are discussed in detail in this chapter.

2.1 SELECTING OPERATIONAL FEATURES

The module has 66 wirewrap pins for the users to configure the module for the operating modes necessary to meet their requirements. This is accomplished by either installing or removing jumper wires between the wirewrap pins. The locations and numerical identification of the wirewrap pins are shown in Figure 2-1. The wirewrap pins and their functions are listed in Table 2-1, by the features they support. The selectable features are Battery Backup, Power Up, Starting Address, Interrupts, Parallel I/O Buffering and Memory maps. Detailed requirements for each of these configurations are described in the following paragraphs. The standard factory configuration is described in Table 2-2.

2.1.1 Battery Backup

The user can select the Battery Backup mode to maintain a +5 Vdc battery supply to the 4KB of static RAM and, if desired, to the two 28-pin sockets that are designated as socket set A. The +5 Vdc battery supply is provided through the LSI-11 bus via pin AV1 and a maximum of 260 mA is required. This supply is connected to wirewrap pin M3. To enable battery backup of 4KB of static RAM, remove the jumper wire between M1 and M2, and install a jumper wire between M3 and M2. To provide backup for socket set A, remove the jumper wire between M4 and M1, and install a jumper wire between M2 and M4.

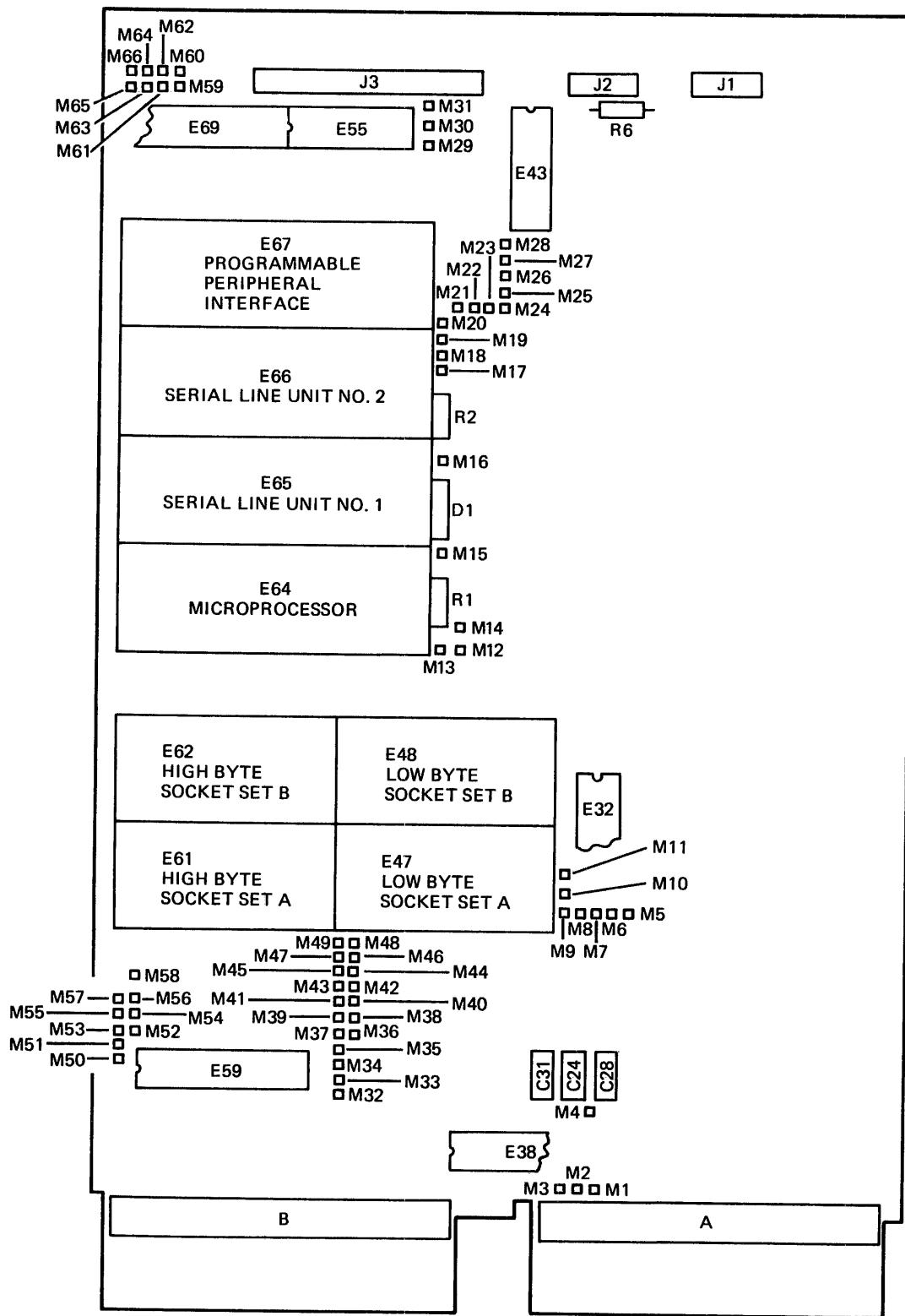


Figure 2-1 SBC-11/21 Module Layout

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Table 2-1 Configuration Pin Definitions

Pin	Function	Description
	Battery Backup	
M1		System +5 V power
M2		+5 Vdc power distribution to support static RAM
M3		Battery backup +5 V power source
M4		Socket set A, pin 26, high and low byte.
	Nonmaskable Interrupt and Trap to the Restart Address	
M5		+5 Vdc voltage level
M6		-CTMER interrupt request input (edge sensitive)
M7		Timeout error (TMR) output
M8		-CTMER interrupt enable
M9		Interrupt Acknowledge (-IAK) output
M10		System GND
M11		High logic level (+3 Vdc)
	Serial Line Unit #1	
M12		System GND
M13		Transmit side of BHALT line transceiver
M14		Serial Line unit #1 Break Detect, Interrupt request output
	Power Up	
M15		System +5 V power, wake up circuit diode, cathode side.
M16		Wake up circuit diode, anode side.

Table 2-1 Configuration Pin Definitions (Cont)

Pin	Function	Description
Serial Line Unit 2		
M17		Transmit side of BEVNT line transceiver
M18		50 Hz real time clock output
M19		60 Hz real time clock output
M20		800 Hz real time clock output
Memory Map Decoder		
M21		High logic level (+3 Vdc)
M22		Memory map select (LSB)
M23		Memory map select (MSB)
M24		System GND
Start Address (Mode Register)		
M25		Start address control
M26		Start address control
M27		Start address control
M28		High logic level (+3 Vdc)
BHALT Interrupt (Level 7, maskable)		
M29		System GND
M30		Receive side of BHALT line transceiver
M31		BHALT interrupt request input (edge sensitive)

Table 2-1 Configuration Pin Definitions (Cont)

Pin	Function	Description
Memory		
M32		Address line 11
M33		High logic level, for PROMs
M34		Socket set A, high byte, pin 23
M35		Socket set B, high and low byte, pin 27
M36		Socket set A, high and low byte, pin 20
M37		Socket set B, high byte, pin 23
M38		Socket set B, high and low byte, pin 20
M39		Socket set B, high byte, pin 22
M40		Socket set B, low byte, pin 22
M41		Socket set A, low byte, pin 22
M42		Socket set B, low byte, pin 23
M43		Socket set A, low byte, pin 23
M44		Socket set A, high and low byte, pin 2
M45		Socket Set B, high and low byte, pin 2
M46		Address line 13
M47		Socket Set B Chip Select (-CSKTB)
M48		Socket Set A, high and low byte, pin 27
M49		Address line 12
M50		System GND
M51		Read Strobe (-Read)
M52		Write low byte strobe (-WLB)

Table 2-1 Configuration Pin Definitions (Cont)

Pin	Function	Description
M53		Static RAM high byte Output Enable (OE)
M54		Static RAM low byte Output Enable (OE)
M55		High byte write strobe (-WHB)
M56		Socket set A Chip Select (-CSKTA)
M57		Socket set A, high byte, pin 22
M58		Socket set A and B, high and low byte, pin 21
Parallel Input/Output		
M59		Port B Buffer direction control
M60		System GND
M61		Port C buffered output, to J3 pin 5
M62		Port C buffered output, to J3 pin 7
M63		Port C PC4 output (8255A-5 pin 13)
M64		Port C PC6 output (8255A-5 pin 11)
M65		High logic level (+3 Vdc)
M66		Port A buffer direction control

2.1.2 Wake Up Circuit

The module has an on-board power wake up circuit designed to be used in systems without the LSI-11 bus power sequencing protocol. This circuit holds the BDCOK line negated until one second after +5 V power is applied. When the module is being used in an LSI-11 backplane, which has a power sequencing routine, the module wake up circuit must be disabled. This is accomplished by installing a jumper wire between M15 and M16. The jumper wire is removed when using power supplies without power sequencing. The user should note that the module requires the +5 Vdc and +12 Vdc power supplies to have a rise time of less than 50 ms.

Table 2-2 Standard Factory Configuration

Function	Jumpers Installed Between
Standard LSI-11 Bus Power (No Battery Backup)	M1 and M2 M1 and M4
Wake up Circuit Enabled	No jumpers
Start Address*	M25 and M26
Start address 10000	M26 and M24
Restart address 10004	M27 and M28
Memories:	
Memory Map 0	M22 and M23 M23 and M24
2K X 8 INTEL EPROM	M34 and M43 M5 and M34 M41 and M57 M56 and M36 M51 and M57 M32 and M58 M37 and M42 M5 and M37 M41 and M39 M47 and M38 M51 and M40
Interrupts:	
Timeout traps to restart address except during LSI-11 bus IAK.	M9 and M8 M7 and M6
SLU#1 Break asserts BHALT and BHALT is received as level 7 interrupt (vector 140)	M13 and M14 M30 and M31
SLU#2 60 Hz Real Time Clock asserts LSI-11 BEVNT	M19 and M17
Parallel I/O in Mode 1: Port A Receive data, with STROBEA on PC4 Port B Transmit data	M59 and M60 M65 and M66 M61 and M63
No Connection to pins M3, M10, M11, M12, M15, M16, M18, M20, M21, M33, M35, M44, M45, M46, M48, M49, M50, M52, M53, M54, M55, M62, M64	
*Before using with Macro-ODT the start address must be changed to 172000, as described in Table 2-3.	

2.1.3 Starting Address

The starting address for the microprocessor is selected by the user via wire wrap pins. When the module is powered up, the microprocessor loads this value into R7 (program counter) as the first fetch address. The wirewrap pins are M24, M25, M26, M27, and M28, defined in Table 2-1. The user has eight starting addresses available to choose from. Table 2-3 lists the available addresses and the jumper connections required for each address. The restart address is always the start address incremented by four. The wirewrap pin locations are shown in Figure 2-1.

Table 2-3 Mode Register Configuration

Start Address	Restart Address	Connect M27 to	Connect M26 to	Connect M25 to
000000	000004	M28	M24	M28
010000*	010004	M28	M24	M24
020000	020004	M24	M28	M28
040000	040004	M24	M28	M24
100000	100004	M24	M24	M28
140000	140004	M24	M24	M24
172000	172004	M28	M28	M28
173000	173004	M28	M28	M24

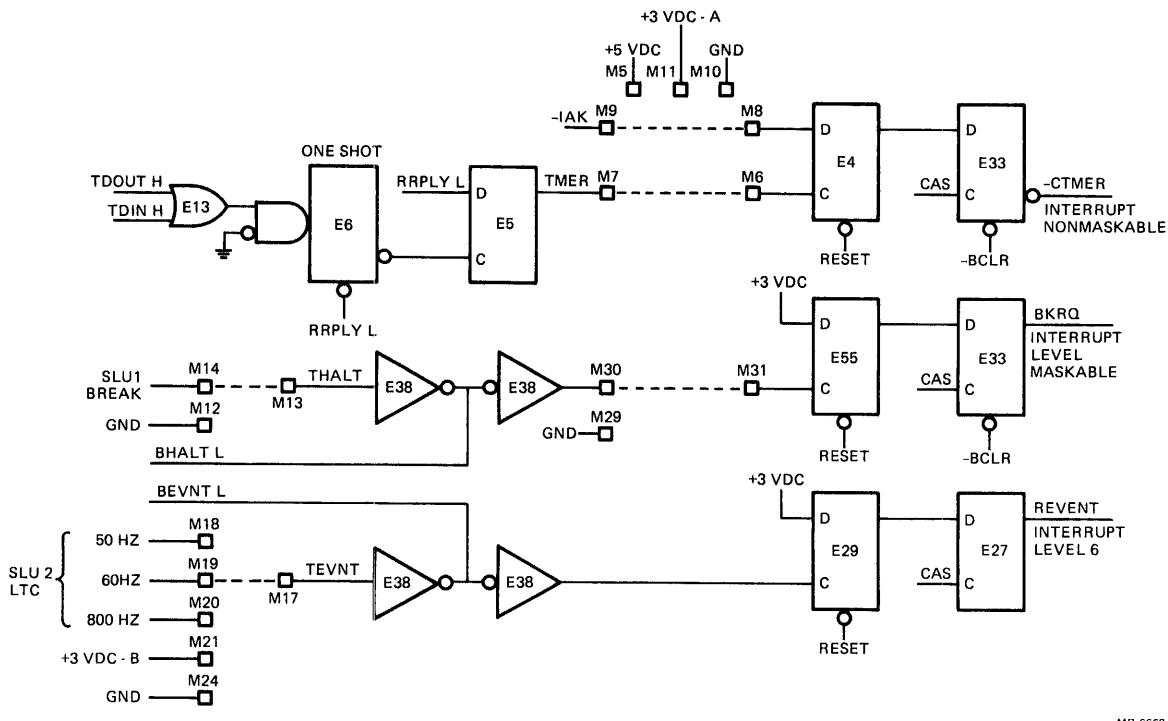
*Factory setting. The start address should be selected in conjunction with the memory map configuration. Figure 2-6 shows how the available start addresses fit into the memory maps.

2.1.4 Interrupts

The SBC-11/21 implements a multilevel interrupt system that consists of eleven separate interrupts. A complete listing of system interrupts will be found in Table 5-3. Three of these interrupts, CTMER, BKRQ, and REVNT, are user-configurable by means of jumper wires as shown in Figure 2-2 and will be discussed here.

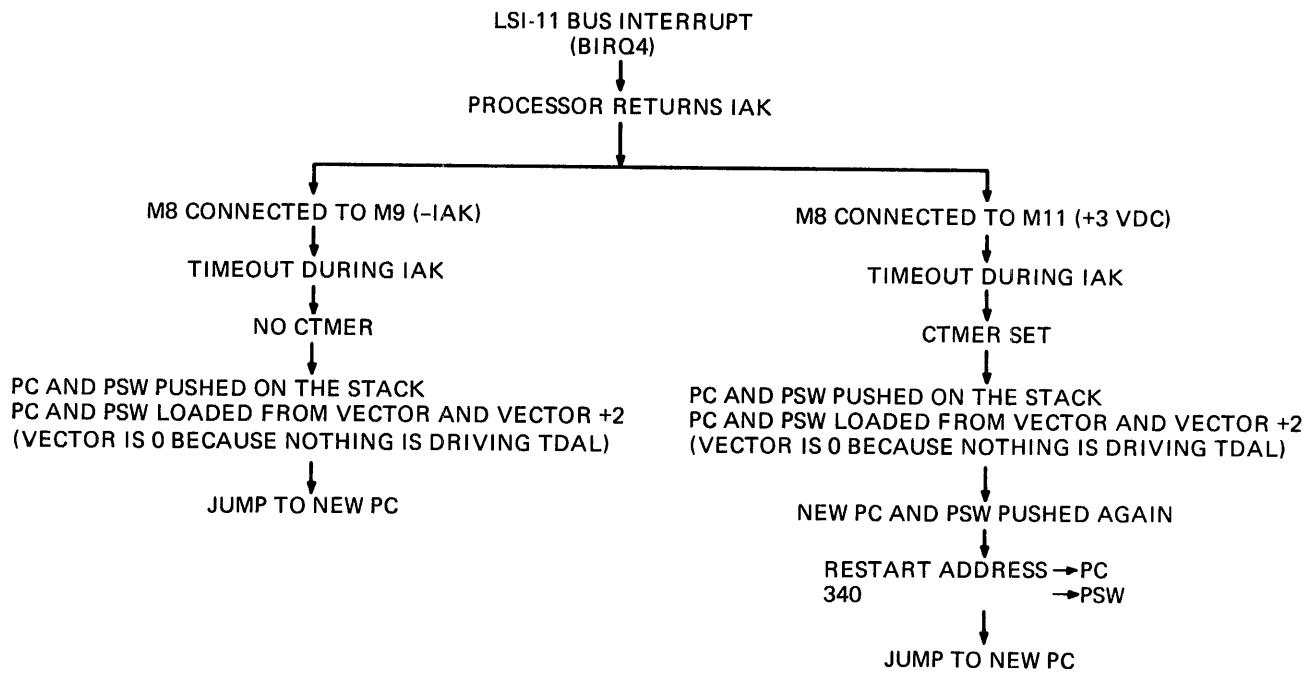
The CTMER interrupt is at the highest level (non-maskable). It is caused by a timeout, that is, failure to detect RRPLY during a FETCH/READ, WRITE, or IACK transaction. For the factory configuration, -IAK is connected to the D input of flip-flop E4 via M9 to M8 jumper. This prevents setting that flip-flop and inhibits CTMER for timeouts occurring during IACK transactions. Such a condition could only occur if the peripheral which caused the interrupt failed to return BRPLY during the vector reading operation. Refer to Chapter 8 for a discussion of External Interrupts. To help the user evaluate the advantages and disadvantages of this jumper option, the sequence of events which takes place during the IAK timeout is described in Figure 2-3.

Observe that a timeout during IAK causes a zero vector to be read in by the microprocessor. This occurs in both cases described in Figure 2-3. The difference is in the setting of CTMER, which causes the second stacking of PC and PSW, followed by jump to RESTART.



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Figure 2-2 Interrupt Configurations



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Figure 2-3 Time-out During LSI-11 Bus Interrupt Acknowledge

The other two interrupts configurable by the user are BKRQ and REVNT. Their vectors and priorities are described in Table 5-3. All jumper combinations which are "electrically correct" as described in Figure 2-2 are legal.

Some typical configurations are described below to familiarize the user with the various combinations available.

Install jumpers between M7 and M31
M8 and M11
M6 and M14
M12 and M13
M17 and M20

This arrangement allows the SLU 1 BREAK input to set the -CTMER nonmaskable interrupt and trap to the restart address. The timeout (TMER) input sets the BKRQ level 7 maskable interrupt. The BHALT L bus signal is ignored. The SLU 2 800 Hz line time clock and the BEVNT L bus signal enable the REVNT interrupt.

Install jumpers between M6 and M30
M14 and M31
M8 and M11
M13 and M12
M17 and M24

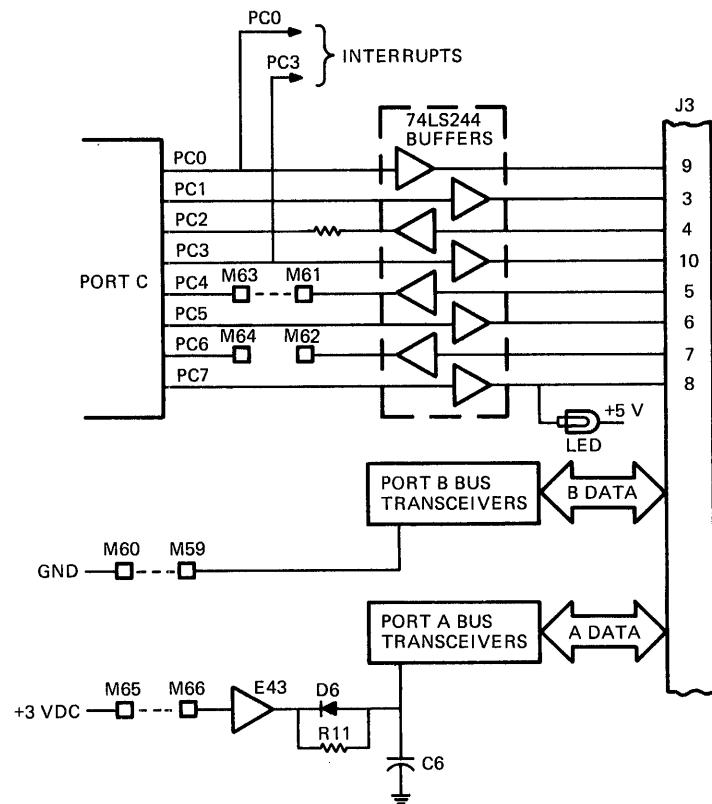
This arrangement allows the BHALT L bus signal to set the -CTMER nonmaskable interrupt and trap to the restart address. The SLU 1 BREAK input sets the BKRQ level 7 maskable interrupt and only the BEVENT L bus signal enables the REVNT interrupt.

Install jumpers between M7 and M6
M8 and M11
M14 and M13
M30 and M31
M17 and M21

This arrangement allows the timeout (TMER) to set the -CTMER nonmaskable interrupt for all timeouts. The SLU 1 BREAK or the BHALT bus signal set the BKRQ level 7 maskable interrupt and the BEVNT L bus line is clamped low and therefore no interrupts can be generated by BEVNT L.

2.1.5 Parallel I/O

The Parallel I/O is implemented with the 8255A-5 Programmable Peripheral Interface (PPI) and connects to the user's interface through the J3 connector. Wirewrap pins used for the configuration of the Parallel I/O are shown in Figure 2-4 and are defined in Table 2-1. Dash lines in Figure 2-4 represent the factory configuration jumpers installed. The wirewrap pin locations are



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Figure 2-4 Parallel I/O Configuration

shown in Figure 2-1. The directions of port A and port B transceivers are dependent upon the logic level connected to M59 and M66. Wirewrap pin 66 connects to port A through a 200 ns minimum rising edge time delay circuit. When M65 (+3 Vdc) is jumpered to pins M59 and M66, port A and port B buffers act as inputs to the Programmable Peripheral Interface from the J3 connectors. When M60 (GND) is jumpered to pins M59 and M66, port A and port B buffers act as outputs from the Programmable Peripheral Interface to the J3 connector.

The direction of port A and port B can also be controlled by the user's program. To make this possible, M63 and M64 must be jumpered to M59 and M66. Then data outputs via port C will control the voltage levels at the direction control inputs to ports A and B. The software required to accomplish this control is discussed in Chapter 6.

Wirewrap pins M61 and M62 can be jumpered to M59 and M66 to allow the user to control the direction of the transceivers via J3 connector pins 5 and 7. When not using wirewrap pins M63 and M61 or M64 and M62 to control the direction of ports A and B, jumpers connected between M63 and M61 and between M64 and M62 allow PC4 and PC6 to be used as inputs to the PPI from the J3 connector.

NOTE

If pins M61, M62, M63 or M64 are used for program control of ports A or B, the user must ensure that the PPI and the buffer do not contend as driver output to driver output. If this condition is allowed to occur, damage to both drivers may result.

The Programmable Peripheral Interface can function in three modes selected by software. The jumper configurations and the handshake signals for each of these modes are shown in Tables 2-4, 2-5, and 2-6. For programming information refer to Chapter 6.

Table 2-4 Mode 0 Buffer Configuration (No Handshake)

PPI Element	To Act as Input	To Act as Output	Program Control via Port C
Port A	M66 to M65	M66 to M60	M66 to M64 or M63
Port B	M59 to M65	M59 to M60	M59 to M64 or M63
PC7	Never an Input	Always an Output	
PC6	M64 to M62	Never an external Output	
PC5	Never an Input	Always an Output	
PC4	M63 to M61	Never an External Output	
PC3	Never an Input	Interrupt A (Vector 134) Always an Output	
PC2	Always an Input	Never an Output	
PC1	Never an Input	Always an Output	
PC0	Never an Input	Interrupt B (Vector 130) Always an Output	

Table 2-5 Mode 1 Buffer Configuration (Strobed I/O)

PPI Element	To Act As Input	To Act As Output	Program Control via Port C
Port A	M66 to M65	M66 to M60	N/A
Port B	M59 to M65	M59 to M60	M59 to M64 or M63
PC7	Never an Input	Indicates Buffer A Full	
PC6	M62 to M64 (Acknowledge A)*	Never an External Output	
PC5	Never an Input	Indicates Buffer A Full	
PC4	M61 to M63 (Strobe A)	Never an External Output	
PC3	Never an Input	Interrupt A	
PC2	Strobe B in Input Mode Acknowledge B in Output Mode	Never an Output	
PC1	Never an Input	Buffer B Full on Input or Output	
PC0	Never an Input	Interrupt B (Vector 130)	

*User's hardware acknowledges receipt of data output by port A.

2.1.6 Serial I/O

The jumper options relating to the serial I/O determine the interrupt response of the system, and have been thoroughly explained in Paragraph 2.1.4. For the sake of completeness, a tabulation of responses to the BREAK detection by the SLU1 is given in Table 2-7.

2.1.7 Memories

The memory system for the module consists of the LSI-11 bus, 4K bytes of local RAM and four 28-pin sockets that will accept either 24-pin or 28-pin industry standard +5 V memory chips. These chips are provided by the user and can be either EPROMs, PROMs, ROMs or static RAM. The sockets will accept 1K X 8, 2K X 8, 4K X 8, and 8K X 8 PROMs/EPROM or 2K X 8 static RAMs.

Table 2-6 Mode 2 Buffer Configuration and Handshake

PPI Element	Input Signal	Output Signal
Port A	Bidirectional bus	If M66 to M64 to M62
Port B	Not used in Mode 2	Not used in Mode 2
PC7	Never an Input	Output Buffer A Full
PC6	Acknowledge A	Never an Output
PC5	Never an Input	Input Buffer A Full
PC4	Strobe A (if M61 to M63)	Never an Output
PC3	Never an Input	Interrupt A
PC2	Always on Input	Never an Output
PC1	Never an Input	Always an Output
PC0	Never an Input	Always an Output

Table 2-7 SLU1 BREAK Detection

Jumper Connection	BREAK Response
M14 to M13 M30 to M31	BHALT L Signal to the LSI-11 Bus and BKRQ interrupt (vector 140)
M13 to M12 M30 to M31 M14 NC	no response
M14 to M31 M13 to M12	BKRQ interrupt (vector 140) (no BHALT L to bus)
M14 to M6 M13 to M12 M8 to M11	CTMER interrupt (HALT trap) through Restart

There are two socket sets, one designated as SET A which is controlled by -CSKTA and the other designated as SET B which is controlled by -CSKTB. Each set consists of a high byte socket and a low byte socket which are interconnected as shown in Figure 2-5. The wirewrap pins used to configure the memory are shown in Figure 2-6 and described in Table 2-1. The standard factory configuration of the jumper wires installed is represented by the dash lines in Figure 2-6. In addition to configuring the sockets, the user must configure the Decode Memory Address chip to select one of the four memory maps available.

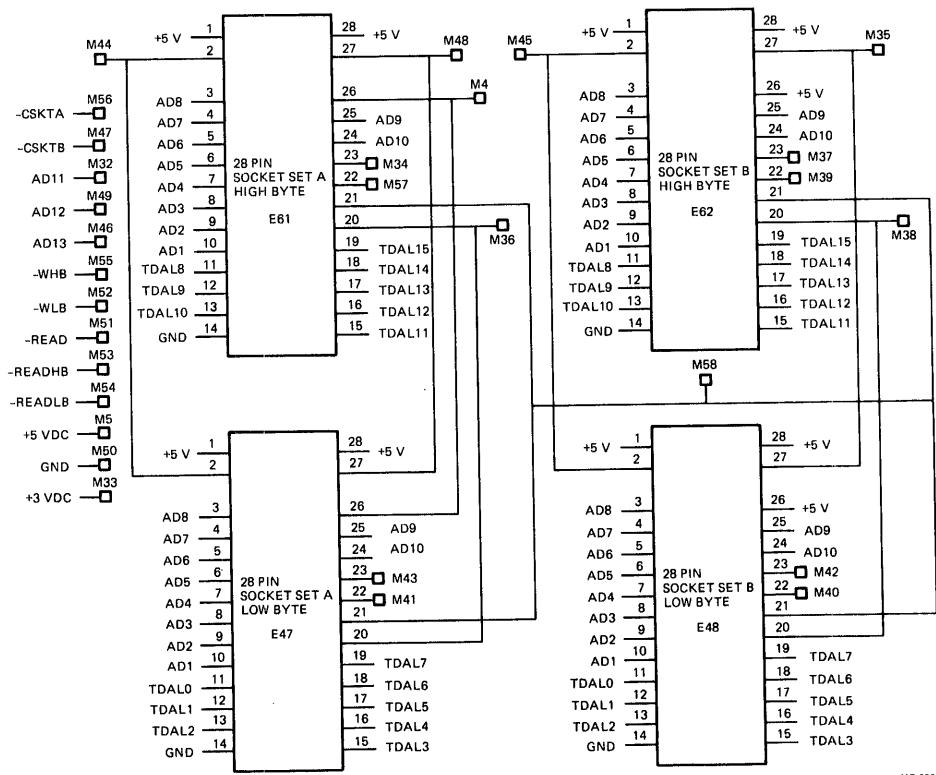


Figure 2-5 Socket Sets A and B Interconnection

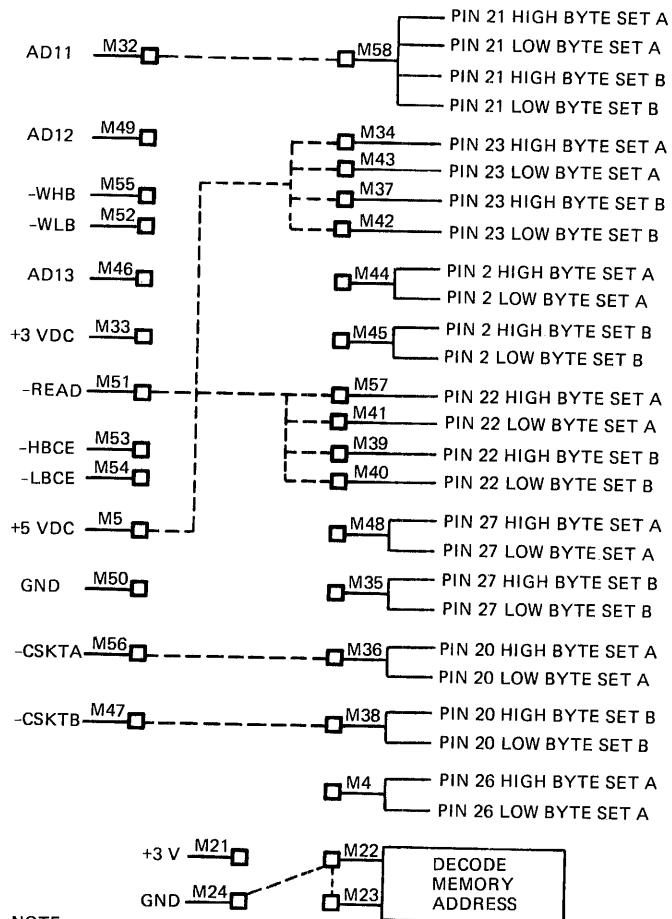
NOTE

When configuring pins M32 to M58 the RAM chips in sockets E60 and E46 must be removed. The RAM chips are replaced into the sockets when the configuration is completed.

2.1.7.1 Memory Maps -- There are four memory maps available as shown in Figure 2-7 and the module can be configured to select one that meets the user's requirements. Wirewrap pins M21, M22, M23, and M24 are used to select the memory map and the jumper requirements are listed in Table 2-8.

Table 2-8 Memory Map Configurations

Map Selection	Jumper M22 to	Jumper M23 to
Map 0	M23	M24
Map 1	M21	M24
Map 2	M24	M21
Map 3	M23	M21

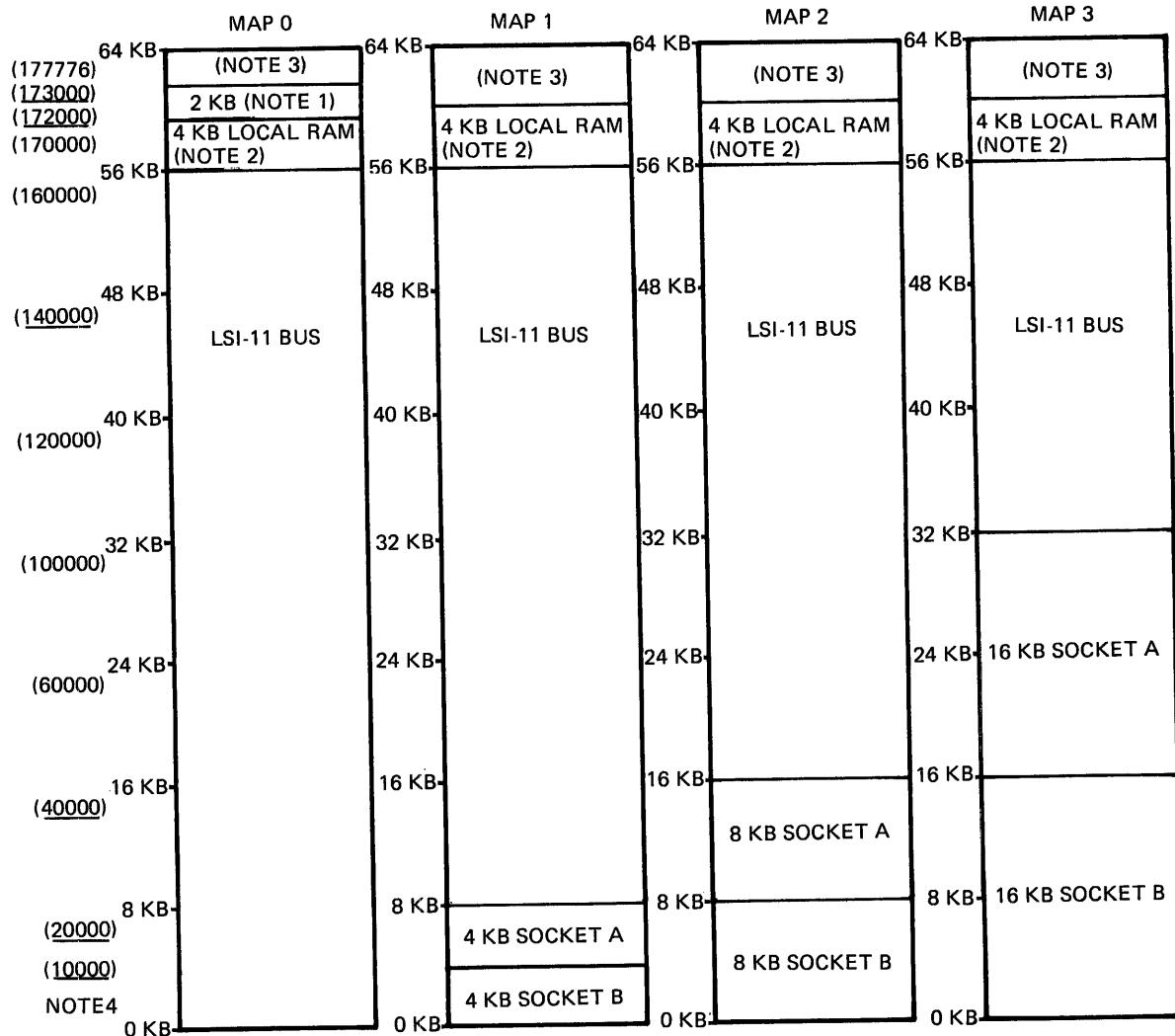


NOTE:

M4 IS USED TO PROVIDE BATTERY
BACKUP POWER TO SOCKET SET A
WHEN THIS OPTION IS INCORPORATED.

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Figure 2-6 Memory Configuration



NOTES:

1. SOCKET SET A IS MAPPED OVER SOCKET SET B AND IS THEREFORE LIMITED TO USING EITHER SOCKET A OR SOCKET B, BUT NOT BOTH TOGETHER.
2. ADDRESSES 160000 THROUGH 160007 ARE ASSUMED TO RESIDE ON THE LSI-11 BUS.
3. THIS SECTION CONTAINS THE LOCAL I/O ADDRESSES FOR THE SLUs AND PPI. ALL UNASSIGNED ADDRESSES ARE ASSUMED TO RESIDE ON THE LSI-11 BUS.
4. UNDERLINED ADDRESSES ARE JUMPER-SELECTABLE START ADDRESSES, ACCORDING TO TABLE 2-3.

Figure 2-7 Memory Maps

MR-7243

2.1.7.2 PROMs/EPROMs -- The 28-pin sockets accept 24-pin and 28-pin PROMs or EPROMs. If 24-pin chips are selected, caution must be observed to ensure pin 1 of the chip is placed into socket hole 3. The configuration requirements of some industry compatible PROMs/EPROMs are described by Tables 2-9 and 2-10. The user may select chips from other vendors but the pin configuration must be compatible with the sockets provided. A 250 ns maximum output

Table 2-9 Socket Set A Configuration for EPROM/PROM

Vendor	Part	Pins	Size	Connect Referenced Pin to Socket A Pin									
				M43	M48	M44	M34	M57	M36	M41	M58		
EPROMS													
INTEL	2758	24	1K X 8	M5	NC	NC	M5	M51	M56	M51	M50		
INTEL	2716	24	2K X 8	M5	NC	NC	M5	M51	M56	M51	M32		
	2716-1	24	2K X 8										
	2716-2	24	2K X 8										
INTEL	2732	24	4K X 8	M49	NC	NC	M49	M51	M56	M51	M32		
	2732A	24	4K X 8										
INTEL	2764	28	8K X 8	M49	M33	M46	M49	M51	M56	M51	M32		
TI	TMS2508	24	1K X 8	M5	NC	NC	M5	M51	M56	M51	M33		
TI	TMS2516	24	2K X 8	M5	NC	NC	M5	M51	M56	M51	M32		
	TMS2516-35	24	2K X 8										
TI	TMS2564	28	8K X 8	M46	M50	M51	M46	M56	M49	M51	M32		
Mostek	MK2716	24	2K X 8	M5	NC	NC	M5	M51	M56	M51	M32		
Mostek	MK2764	28	8K X 8	M49	NC	M46	M49	M51	M56	M51	M32		
PROMS													
INTEL	3628	24	1K X 8	M56	NC	NC	M56	M51	M33	M51	M33		
Signetics	82LS181	24	1K X 8	M56	NC	NC	M56	M51	M33	M51	M33		

NC requires NO connection.

enable time is also required and the maximum access time for compatible PROMs/EPROMs is 450 ns. The maximum output enable time is defined as the time from the assertion of TDIN or TDOUT by a bus master to the time the module asserts valid data onto the bus.

The user installs a jumper wire from the pin referenced by the chip type to the socket pin described in the tables. Figure 2-6 provides a reference for all signals and the socket pins associated with the wirewrap pins. These interconnections are listed separately under socket set A and socket set B, and some jumper wires are common to both socket sets. Some devices may not require a connection or a jumper wire installed and these are designated by an "NC" in the tables. The wirewrap pin locations are shown in Figure 2-1.

Table 2-10 Socket Set B Configuration for EPROM/PROM

Vendor	Part	Pins	Size	Connect Referenced Pin to Socket B Pin									
				M42	M35	M45	M37	M39	M38	M40	M58		
EPROMS													
INTEL	2758	24	1K X 8	M5	NC	NC	M5	M51	M47	M51	M50		
INTEL	2716	24	2K X 8	M5	NC	NC	M5	M51	M47	M51	M32		
	2716-1	24	2K X 8										
	2716-2	24	2K X 8										
INTEL	2732	24	4K X 8	M49	NC	NC	M49	M51	M47	M51	M32		
	2732A	24	4K X 8										
INTEL	2764	28	8K X 8	M49	M33	M46	M49	M51	M47	M51	M32		
TI	TMS2508	24	1K X 8	M5	NC	NC	M5	M51	M47	M51	M33		
TI	TMS2516	24	2K X 8	M5	NC	NC	M5	M51	M47	M51	M32		
	TMS2516-35	24	2K X 8										
TI	TMS2564	28	8K X 8	M46	M50	M51	M46	M47	M49	M51	M32		
Mostek	MK2716	24	2K X 8	M5	NC	NC	M5	M51	M47	M51	M32		
Mostek	MK2764	28	8K X 8	M49	NC	M46	M49	M51	M47	M51	M32		
PROMS													
INTEL	3628	24	1K X 8	M47	NC	NC	M47	M51	M33	M51	M33		
SIGNETICS	82LS181	24	1K X 8	M47	NC	NC	M47	M51	M33	M51	M33		

NC requires NO connection.

2.1.7.3 RAMs -- The 28-pin sockets can also accept 24-pin static RAM chips and caution must be observed to ensure pin 1 of the chip is installed into socket hole 3. The configuration requirements of some industry compatible RAMs are described in Tables 2-11 and 2-12. The user may select chips from other vendors but the pin configuration must be compatible with the sockets provided. The selected RAMs are required to meet the maximum output enable time and the maximum access time specified for the PROMs.

The user installs a jumper wire from the pin referenced by the chip type to the socket pin described in the tables. Figure 2-6 provides a reference for all signals and the socket pins associated with the wirewrap pins. The interconnections are listed

separately under socket A and socket B, and some jumper wires are common to both socket sets. Some devices may not require a connection or a jumper wire installed and these are designated by "NC" in the tables. The wirewrap locations are shown in Figure 2-1.

Table 2-11 Socket Set A Configuration for RAM

Vendor	Part	Pins	Size	Connect Referenced Pin to Socket A Pin							
				M43	M48	M44	M34	M57	M36	M41	M58
MOSTEK	MK4802	24	2K X 8	M52	NC	NC	M55	M53	M56	M54	M32
TOSHIBA	TMM2016P	24	2K X 8	M52	NC	NC	M55	M53	M56	M54	M32
	TMM2016P-1	24	2K X 8								
HITACHI	HM6116P	24	2K X 8	M52	NC	NC	M55	M53	M56	M54	M32

NC requires NO connection.

Table 2-12 Socket Set B Configuration for RAM

Vendor	Part	Pins	Size	Connect Referenced Pin to Socket B Pin							
				M42	M35	M45	M37	M39	M38	M40	M58
MOSTEK	MK4802	24	2K X 8	M52	NC	NC	M55	M53	M47	M54	M32
TOSHIBA	TMM2016P	24	2K X 8	M52	NC	NC	M55	M53	M47	M54	M32
	TMM2016P-1	24	2K X 8								
HITACHI	HM6116P	24	2K X 8	M52	NC	NC	M55	M53	M47	M54	M32

NC requires NO connection.

2.2 SELECTING BACKPLANES AND OPTIONS

A number of different LSI-11 bus compatible backplanes and boxes are available from Digital. The choice must be dictated by the system requirements such as the number and type of options (described in Chapter 3), environmental conditions and packaging considerations. A list of all available backplanes and boxes is described in the Microcomputer Interfaces Handbook referenced in Chapter 1.

2.3 POWER SUPPLY

The choice of power supply is governed by the size of the system and packaging requirements. An important consideration is the behavior of the supply during power up and power down. All Digital power supplies listed in the Microcomputer Interfaces Handbook (see Chapter 1) are compatible with the LSI-11 bus protocol. This assures reliable operation with no loss of data when using battery-supported memories. Any user-designed power supply must conform to this protocol.

2.4 EXTERNAL CABLES

The module has a 30-pin connector (J3) for external interfacing with the Programmable I/O Interface and two 10-pin connectors (J1 and J2) for external interfacing with the Serial Line Units (SLU). The location of these connectors on the module is shown in Figure 2-1. The user's requirements to interface with these connectors is defined below.

2.4.1 Parallel I/O Interface (J3)

The module connector is a 30-pin AMP MODU connector with the I/O signals defined by Figure 2-8. The I/O signals are buffered and are capable of driving up to 50 feet (maximum) of unshielded flat ribbon or round cable with a 30-pin AMP contact housing at each end. The following list of connectors is compatible with the module connector.

AMP MODU polarized or nonpolarized contact housings for crimp snap-in pin and receptacle contacts:

Latching, polarized housings:	2-87631-6 no strain relief 87733-6 strain relief
Nonlatching, polarized housings:	1-87977-3 no strain relief 1-102184-3 strain relief
Nonlatching, nonpolarized housings:	2-87456-6 no strain relief 2-87832-7 strain relief
Receptacle contacts:	87045-3 for 30 to 26 AWG 102098-3 for 32 to 27 AWG

Mass termination connectors for flat cables

Separate parts: (nonpolarized)	1-88378-1 connector 1-86873-2 cover 1-88340-1 strain relief cover
Separate parts: (polarized)	1-88392-1 connector 1-86373-2 cover 1-88340-1 strain relief cover
Connector and cover kits: (nonpolarized)	1-88379-1 no strain relief 1-88476-1 with strain relief
Connector and cover kits: (polarized)	1-88393-1 no strain relief 1-88478-1 with strain relief

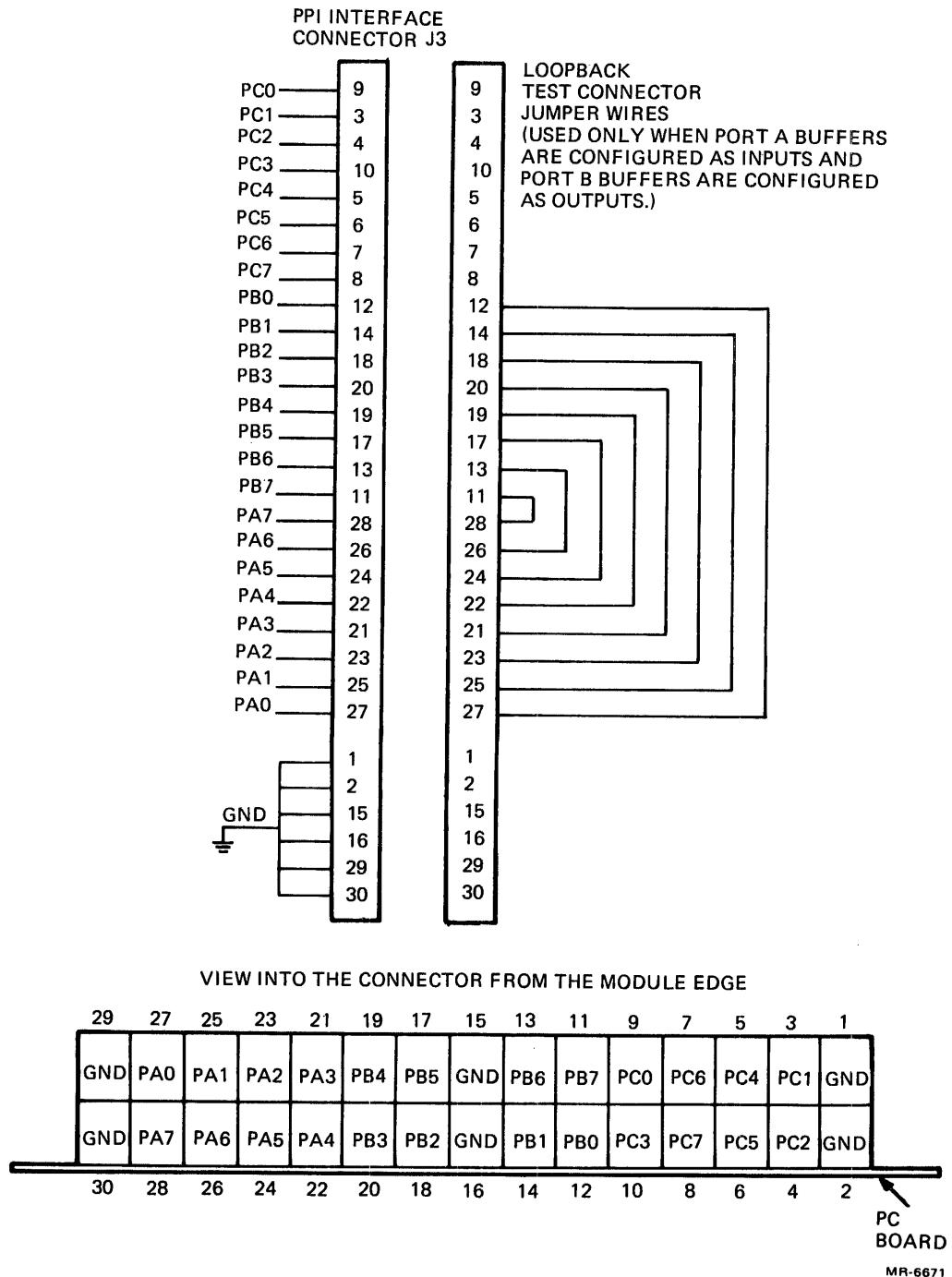


Figure 2-8 30 Pin Parallel I/O Connector

Separate parts:	1-88392-1 connector 1-86873-2 cover 1-88340-1 strain relief cover
Latching connectors and covers: (polarized)	1-88423-1 no strain relief 1-88479-1 with strain relief
Mass Modular Connector System:	1-102393-3 housing for 30-26 AWG 1-102396-3 cover 1-102392-3 kit 1-102398-3 housing for 26-22 AWG 1-102396-3 cover 1-102397-3 kit

Connectors can be terminated to discrete wire in sizes 30-26 AWG, 26-24 AWG, as well as jacketed cable and bonded ribbon cable.

2.4.2 Serial Line Interfaces (J1 and J2)

Each of the Serial Line Units is compatible with EIA RS-232 C and EIA RS-423 serial type interfaces. Serial line unit #1 interfaces through J1 and serial line unit #2 interfaces through J2. When a 20 mA current loop device is desired, then the DLV11-KA option must be used. The option has an EIA cable (BC21A-03) that connects the converter box to the module and the box mates with the standard 20 mA cable using the 8-pin Mate-N-Lock connector. Note that the option does not support the Reader Run strobe and the 110 baud rate so that LA-33 or similar devices cannot be used.

The user is required to install a slew rate resistor determined by the operating baud rate as defined in Table 2-13. The slew rate resistor is designated as R6 and its location on the module is shown in Figure 2-1.

Table 2-13 EIA Slew Rate Resistor Values

Baud Rate	Resistor R6 (ohms)
38400	22K*
19200	51K
9600	120K
4800	200K
2400	430K
1200	820K
600	1M
300	1M

* Factory Installed Value.

The serial line unit connectors showing the signals assigned to the connector pins are shown in Figure 2-9. The user is required to provide the interconnecting cables. The following list describes some standard DIGITAL cables and also some information to assist the user in designing cables.

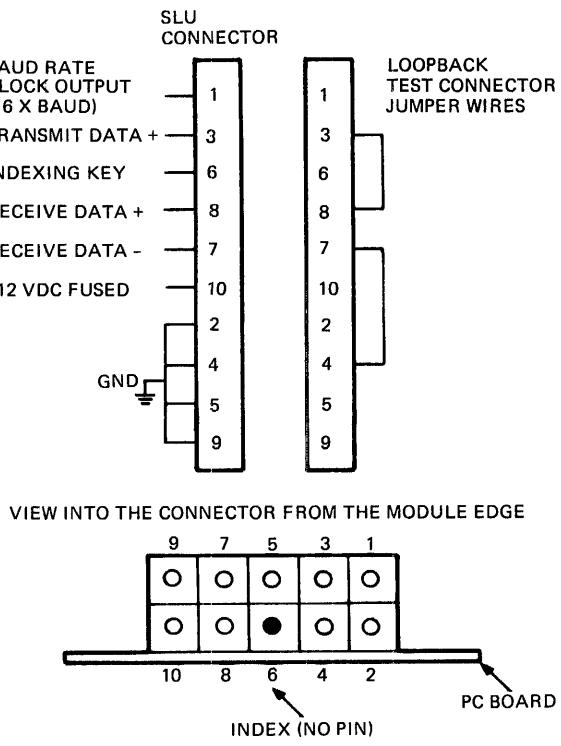
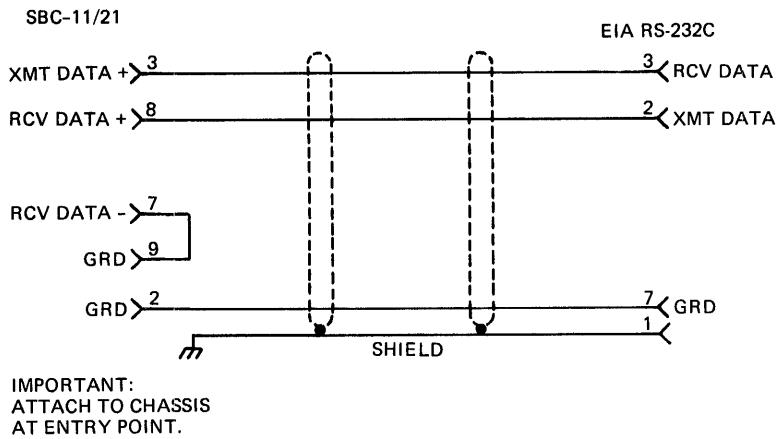


Figure 2-9 10 Pin Serial Line Unit Connector

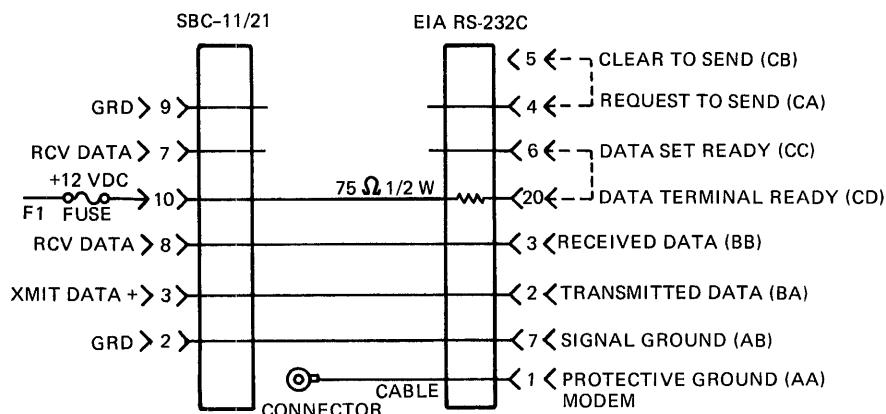
DIGITAL cables for the SBC-11/21

- BC20N-05 5 foot EIA RS-232C null modem cable to directly interface with the EIA RS-232C terminal (2 X 5 pin Amp female to RS-232C female; see Figure 2-10).
- BC21B-05 5 foot EIA RS-232C modem cable to interface with modems and acoustic couplers (2 X 5 pin Amp female to RS-232 C male; see Figure 2-11).
- BC20M-50 50 foot EIA RS-422 or RS-423 cable for highspeed transmission (19.2K baud) between two SBC-11/21's (2 X 5 pin Amp female to 2 X 5 pin Amp female).



MR-6672

Figure 2-10 BC20N-05 "Null Modem" Cable



MR-6673

Figure 2-11 BC21B-05 Modem Cable

When designing a cable for the SBC-11/21, here are several points to consider:

1. The receivers on the SBC-11/21 have differential inputs. Therefore, when designing an RS-232C or RS-423 cable, RECEIVE DATA- (pin 7 on the 2 X 5 pin Amp connector) must be tied to signal ground (pins 2, 5, or 9) in order to maintain proper EIA levels. RS-422 is balanced and uses both RECEIVE DATA+ and RECEIVE DATA-.

2. To directly connect to a local EIA RS-232C terminal, it is necessary to use a null modem. To design the null modem into the cable, one must switch RECEIVE DATA (pin 2) with TRANSMITTED DATA (pin 3) on the RS-232C male connector as shown in Figure 2-10.
3. To mate to the 2 X 5 pin connector block, the following parts are needed.

Cable Receptacle	AMP PN 87133-5 DEC PN 12-14268-02
Locking Clip Contacts	AMP PN 87124-1 DEC PN 12-14267-00
Key Pin (pin 6)	AMP PN 87179-1 DEC PN 12-15418-00

2.5 VERIFYING OPERATION

The SBC-11/21 can be field tested to verify its functional operation. The Macro-ODT option and the loopback connectors are used to support the testing of the module.

2.5.1 Macro-ODT Option

The Macro-ODT option (part # KXT11-A2) consists of two, 24 pin, 2K X 8 PROM chips that contain the Macro-ODT code and module diagnostic programs. The Macro-ODT code is used to establish communication between the module and the user via console commands. The use of ODT commands is detailed in Chapter 4. The module diagnostic programs verify that the Parallel I/O and Serial Line Unit interfaces will function with commands from the microprocessor.

2.5.2 Loopback Connectors

The loopback connectors can be fabricated by the user for the module diagnostic tests. The 30-pin connector with the loopback jumper wires installed is shown in Figure 2-8, and is used with the Parallel I/O connector J3. The Serial Line Unit connector with the loopback jumper wires installed is shown in Figure 2-9, and is used with the serial line unit #2 connector J2.

2.5.3 Verification Procedure

The module must be restored to the standard factory configuration for the test to be valid, except that the start address must be 172000 instead of 10000. The module can be verified by using the following procedure.

1. Set the start address to 172000 as shown in Table 2-3.
2. Insert the high byte ODT ROM into socket set A, high byte socket E61. Ensure pin 1 is inserted into socket hole 3.
3. Insert the low byte ODT ROM into socket set A, low byte socket E47. Ensure pin 1 is inserted into socket hole 3.
4. Insert the 30-pin loopback connector (see Paragraph 2.5.2) into the module Parallel I/O connector J3.
5. Insert the 10-pin loopback connector (see Paragraph 2.5.2) into the serial line unit #2 connector J2.
6. Install the module into the LSI-11 backplane with the power turned off. An external power supply may be used to provide +5 Vdc to finger pins BV1, BA2, and AA2, +12 Vdc to finger pin BD2 and Ground to finger pins BJ1, AJ1, AT1, AC2, BC2, AM1, and BM1.
7. Connect an external terminal (printer or video). The terminal must be capable of generating a 7-bit ASCII code with odd parity or 8-bit ASCII code with no parity, and baud rates of 300, 600, 1200, 2400, 4800, or 9600. The terminal is connected to the serial line unit #1 connector J1 using a Digital BC2ON-05 cable or equivalent. Turn the terminal on and on line.
8. Turn on the backplane power or enable the +5 Vdc and +12 Vdc sources. Monitor the module LED. The LED should illuminate and then return to the normal OFF state. If the LED remains illuminated, there is a fault in the serial line unit #1 circuits or the on-board RAM memory.
9. After the backplane power is turned on, press the "RETURN" key (carriage return) on the terminal in order for the module to synchronize its baud rate to that of the terminal. The module responds with the prompt character "@".
10. To initiate the module diagnostic programs press the "X" key. The diagnostic test will exercise the module including the Parallel I/O and Serial line unit #2. The results of the test are printed out on the terminal. The error results are listed in Table 2-14 and indicate what area of the module contains a fault. The error code "000000" indicates a good module.

Table 2-14 Diagnostic Fault Indicators

Printout	Parallel I/O Loopback Test	Internal Serial* I/O Loopback Test	External Serial** I/O Loopback Test
000000	Passed	Passed	Passed
000001	Failed	Passed	Passed
000010	Passed	Failed	Not Performed
000011	Failed	Failed	Not Performed
000100	Passed	Passed	Failed
000101	Failed	Passed	Failed
000110	Not Used	Not Used	Not Used
000111	Not Used	Not Used	Not Used

*The Internal Serial I/O Loopback Test exercises the parallel-to-serial conversion, the serial-to-parallel conversion, and the baud rate. This test can be performed without the loopback connector.

**The External Serial I/O Loopback Test exercises the above functions as well as the drivers, receivers, and the external signal paths.

CHAPTER 3 OPTIONS

3.0 GENERAL

The SBC-11/21 is a complete single board microcomputer that will operate on the LSI-11 bus or in a standalone configuration. In some applications it could be advantageous to add optional modules to the SBC-11/21 to extend its functionality beyond that provided by the module itself. A listing of all such options is given in the following sections. More information may be found in hardware manuals listed in Chapter 1 of this manual.

3.1 SUPPORTED OPTIONS

The following options are functionally compatible with the SBC-11/21. Software diagnostics for these options will run on the SBC-11/21 equipped with a mass storage device (TU58, RX01 or RX02) and the Macro-ODT option. To order diagnostics, contact your DEC sales representative.

- | | |
|---------|--|
| TU58 | This low cost mass memory device can be used with the SBC-11/21 by attaching it to one of the serial I/O lines. TU58 offers random access to block formatted data on pocket-size cartridge media. It is ideal as a small computer systems device, as inexpensive archive mass storage, or as a software update distribution medium. A dual drive TU58 offers 512 Kb of storage space, making it one of the lowest cost complete mass storage subsystems available. For mounting flexibility, the TU58 is offered both as a component level subsystem and as a fully powered 5-1/2 inch rack-mount subsystem. The TU58 interfaces with the microprocessor over an RS-423 serial line interface. |
| DLV11-E | The DLV11-E is an asynchronous line interface module that interconnects the LSI-11 bus to standard serial communications lines. The module receives serial data, converts it to parallel data, and transfers it to the LSI-11 bus. Also, it accepts parallel data from the LSI-11 bus, converts it to serial data, and transmits it to the peripheral device. The module has jumper-selectable or software-selectable baud rates (50-19,200), and jumper-selectable data bit formats. The DLV11-E offers full modem control for EIA/CCITT interfaces. |
| DLV11-F | The DLV11-F is an asynchronous line interface module that interconnects the LSI-11 bus to several types of standard serial communications lines. The module receives serial data, converts it to parallel data, and transfers it to the LSI-11 bus. It also accepts parallel data from the LSI-11 bus, converts it to serial data, and transmits it to the peripheral |

device. The module has jumper-selectable or software-selectable baud rates (50-19,200) and jumper-selectable data bits. The DLV11-F supports either 20 mA current loop or EIA standard lines, but does not include modem control.

- DLV11-J The DLV11-J contains four independent asynchronous serial line channels used to interface peripheral devices to the LSI-11 bus. Each channel transmits and receives data from the peripheral device over EIA data leads (lines that do not use a control line). The module can be used with 20 mA current loop devices if a DLV11-KA adapter is used. The DLV11-J has jumper-selectable baud rates from 150 to 39.4 K baud.
- DPV11-DA The DPV11-DA is a single-line program-controlled, double-buffered communication device designed to interface the LSI-11 Bus to a serial synchronous line. This self-contained unit is capable of handling a wide variety of protocols including bit-oriented protocols such as SDLC, HDLC, ADCCP, and X.25, and byte-oriented protocols such as DDCMP and BISYNC.
- The module is used for high speed synchronous lines such as remote batch, remote data collection, remote concentration, and communication networking. In addition to being compatible with EIA RS-232 and CCITT V.28 interface standards, the module is compatible with EIA RS-423 and 422 electrical standards, permitting low cost, local communications capability.
- DRV11 The DRV11 is a parallel interface module that is used to interconnect the LSI-11 bus with general-purpose parallel line TTL or DTL devices. It allows program-controlled data transfers at rates up to 40K words per second and uses LSI-11 bus interface and control logic to generate interrupts and process vector handling. The data is handled by 16 diode-clamped input lines and 16 latched output lines. There are two 40-pin connectors on the module for user interface applications.
- DRV11-B The DRV11-B is an interface module that uses direct memory access (DMA) to transfer data directly between the system memory and an I/O device. The interface is programmed by the processor to move variable length blocks of 8- or 16-bit data words to or from specified locations in the system memory. Once programmed, there is no processor intervention required. The module can transfer up to 250K 16-bit words per second in the single-cycle mode and up to 500K 16-bit words per second in the burst mode. It also allows read-modify-restore operations.

- DRV11-J The DRV11-J provides sixty-four input/outut data lines on a double-height module for the LSI-11 bus. The DRV11-J also includes an advanced interrupt structure with bit interruptability up to 16 lines, programmable interrupt vectors, and program selection of fixed or rotating interrupt priority within the DRV11-J. The DRV11-J's bit interrupts for real-time response make it especially useful for sensor I/O applications. It can also be used as a general-purpose interface to custom devices, and two DRV11-Js can be connected back-to-back as a link between two LSI-11 buses.
- DUV11-DA The DUV11-DA synchronous line interface module establishes a data communication line between the LSI-11 bus and a Bell 201 synchronous modem or equivalent. The module is fully programmable with respect to sync characters, character length (up to 8 bits), and parity selection. The receiver logic accepts serial data for the LSI-11 bus. The transmitter logic converts the parallel LSI-11 bus data into serial data for the transmission line. The interface logic converts the TTL logic levels to the EIA voltage levels required by the Bell 201 modems and also controls the modem for half-duplex or full-duplex operation.
- DZV11-B The DZV11-B is an asynchronous multiplexer interface module that interconnects the LSI-11 bus with up to four asynchronous serial data communications channels. The module provides EIA interface voltage levels and data set control to permit dial-up (auto-answer) options with full-duplex modems such as Bell models 103, 113, 212, or equivalent. The DZV11-B does not support half-duplex operations or the secondary transmit and receive operations available in some modems such as Bell 202. The module has applications in data concentration and collection systems where front-end systems interface to a host computer and for use in a cluster controller for terminal applications.
- IBV11-A The IBV11-A is an interface module that interconnects the LSI-11 bus with the instrument bus described in IEEE standard 488 1975, "Digital Interface for Programmable Instrumentation." The IBV11-A makes a processor-controlled programmable instrument system possible. The module can accomodate up to 15 IEEE-488 devices.
- MRV11-C The MRV11-C is a flexible, high-density ROM module used with the LSI-11 bus. The module contains sixteen 24-pin sockets which accept a variety of user-supplied ROM chips. It will accept masked ROMs, fusible link PROMs, and ultraviolet erasable PROMs. It accepts several densities of ROM chips up to and including 4K

X 8 chips. Using these high-density chips gives the module a total capacity of 64K bytes. The contents of the module can be accessed in one of two ways -- either directly or window-mapped. Direct access provides total random access to all ROM locations on the module. Window-mapping provides two 2K-byte windows of memory address space to access 2K-byte segments of the ROM array. The segments that are viewed through each window can be varied under program control.

MSV11-D The MSV11-D module has either 8K, 16K, or 32K X 16 bits of MOS memory. The module has an on-board memory refresh and performs the necessary LSI-11 bus cycles. The memory addressing is selectable by the user by configuring switch settings. The module can use a battery backup system to preserve data when primary power is lost.

MXV11-A The MXV11-A is a dual height multifunction option module for the LSI-11 bus. It contains a read/write memory, provisions for read-only memory, two asynchronous serial line interfaces and a 60 Hz clock signal derived from a crystal oscillator. Read/write memory is supplied with either 8K or 32K bytes (4K or 16K words). Two 24-pin sockets are provided for +5 V read-only memories. 1K X 8, 2K X 8, or 4K X 8 ROMS may be used. The sockets may also be used for 256 words of bootstrap code. The two asynchronous serial lines transmit and receive EIA-423 signal levels from 150 baud to 38.4K baud. 20 mA active or passive current loop operation at 110 baud may be obtained with the DLV11-KA EIA to 20 mA converter option. The serial lines will not support the reader run function of the DLV11-KA option. The serial lines provide error indicator bits for overrun error, frame error, and parity error, but do not have modem controls. Serial line 1 may be configured to respond to a break signal. The serial lines have signal level interrupt logic. Serial line 1 along with serial line 0, may be used with any of several standard types of serial communication devices. The 60 Hz clock signal can be selected by a wirewrap jumper to provide line-time clock interrupts on the bus.

RXV21 The RXV21 floppy disk option is a random access mass memory device that stores data in fixed-length blocks on a preformatted, flexible diskette. Each diskette can store and retrieve up to 512K 8-bit bytes of data. The RXV21 system is rack-mountable and consists of an interface module, an interface cable, and either a single or dual RX02 floppy disk drive. The interface module converts the RX02 I/O bus to the LSI-11 bus structure. It controls the RX02 interrupts to the

processor, decodes device addresses for register selection, and handles the data interchange between the RX02 and the processor via DMA transfers. Power for the interface module is supplied by the LSI-11 bus.

RXV11 The RXV11 option consists of an interface module, cable assembly, and either a single or dual drive RX01 floppy disk. This option is a random access, mass storage device that stores data in fixed-length blocks on a preformatted flexible diskette. Each diskette can store and retrieve up to 256K, 8-bit bytes of data. The RXV11 system is rack mountable in the standard 48.3 cm (19 in) cabinet.

3.2 UNSUPPORTED OPTIONS

The following LSI-11 bus options listed in Table 3-1 are not guaranteed to be functionally compatible with the SBC-11/21, and are termed "unsupported." Their diagnostics are not available.

Table 3-1 Unsupported LSI-11 Options

AAV11-A	FEPTC-BA	LPV11	TRV11
ADV11-A	FPF11	MRV11-AA/BA/VU	TSV11
BDV11-AA/BA	IPV12	MSV11-E/P	VMV66-A
DA11-MS/QQ/QU	KD11-F	NCV11-A	VK170
DAV11-A/B	KD11-HA	REV11	VSV11
DRL11-SN	KDF11-AB/AC/BB	RKV11	VTV01-A
DUV11-E/F	KDF11-BC/P	RLV11	VTW30-H
DUV25	KPV11-A	RLV12	
DW11	KWV11-A	TEV11	
DWV11-A	LAV11		

4.0 GENERAL

The Macro-ODT is the KXT11-A2 option that is available for users of the SBC-11/21 single board computer. The option consists of two 24-pin, 2K X 8 ROM chips which contain the Macro-ODT firmware, and a complete listing of the firmware. The chips are installed on the module using the PROM sockets.

Macro-ODT allows the user to do the following:

- o Examine and deposit data in memory or general registers.
- o Examine or alter the Processor Status Word (PSW).
- o Start the execution of the program.
- o Resume the execution of a halted program.
- o Bootstrap programs from a mass storage device (TU58 cassette, RX01 or RX02 floppy disks).
- o Run a confidence test for on-board devices.

4.1 INSTALLATION AND CONFIGURATION

This is described in detail in Chapter 2 and the user is referred to it for installation and startup instructions.

4.2 ENTRY CONDITIONS

Macro-ODT is entered:

1. Upon power up.
2. Via the "BREAK" key on the console terminal.
3. Execution of a HALT instruction.
4. Assertion of the BHALT L signal on the LSI-11 Bus.
5. Accessing nonexistent memory (i.e., a bus timeout).

4.2.1 Macro-ODT Input Sequence

Upon entry to Macro-ODT, the RBUF register is read using a DATI and the character present in the buffer is ignored. This is done so that erroneous characters or user program characters are not interpreted by Macro-ODT as commands, especially when a program is halted.

The input sequence for Macro-ODT is as follows.

1. Read and ignore character in RBUF.

2. Output a <CR> <LF> to terminal.
3. Output contents of PC (program counter R7) in six digits to terminal if ODT is entered via a BREAK, BHALT, HALT instruction or an attempt to fetch an instruction from nonexistent memory. Output a "?" to the terminal if ODT is entered via a bus timeout.
4. Output a <CR> <LF> to terminal.
5. Output the prompt character, @, to terminal.
6. Enter a wait loop for terminal input. The Done flag, bit 7 in RCSR, is tested using a DATI. If it is 0, the test continues.
7. If RCSR bit 7 is a 1, then low byte of RBUF is read using a DATI.

4.2.2 Macro-ODT Output Sequence

The output sequence for ODT is as follows.

1. Test XCSR byte 7 (Done flag) using a DATI and if a 0, continue testing.
2. If XCSR bit 7 is 1, write character to low byte of XBUF using a DATI followed by a DATO (high byte is ignored by interface).

4.3 MACRO-ODT COMMANDS

The Macro-ODT commands are listed in Table 4-1 and described in the following paragraphs. The commands are a subset of ODT-11 and use the same command character. The Macro-ODT internal states are listed in Table 4-2. For each state only specific characters are recognized as valid inputs; other inputs invoke a "?" response.

The parity bit, bit 7, on all input characters is ignored by Macro-ODT, and if the input character is echoed, the state of the parity is copied to the output buffer (XBUF). Output characters internally generated by ODT (e.g., <CR>) have the parity bit equal to 0. All input characters are echoed. Only uppercase command characters are recognized.

NOTE

The use of ODT commands establishes a dialog between the user and the microcomputer. Therefore, all the characters typed by the user are underlined and the system response is not underlined.

Table 4-1 Macro-ODT Commands

Command	Symbol	Use
Slash	/	Prints the contents of a specified location.
Carriage Return	<CR>	Closes an open location.
Line Feed	<LF>	Closes an open location and then opens the next location. This command cannot be used with the general registers.
Internal Register Designator	R	Opens a specific processor register.
Processor Status Word Designator	S	Opens the PSW -- must follow R command.
Go	G	Starts program execution.
Proceed	P	Resumes execution of a program.
Boot from Device	D	Loads and runs programs from floppy diskettes or TU58 cassettes.
Execute Diagnostics	X	Runs SBC-11/21 module verification diagnostic.

4.3.1 / (ASCII 057) Slash

This command is used to open an on board module address, LSI-11 Bus address, processor register, or processor status word and must be normally preceded by other characters which specify a location. In response to /, Macro-ODT prints the contents of the location (i.e., six characters) and then a space (ASCII 40). After printing is complete, Macro-ODT waits for either new data for that location or a valid close command (<CR> or <LF>). The space character is issued so that the location's contents and possible new contents entered by the user are legible on the terminal.

Example: @001000/12525<SPACE>

where:

@ = Macro-ODT prompt character

001000 = octal location in the LSI-11 Bus address space desired by the user (leading 0s are not required)

```
/      = command to open and print contents of  
          location  
012525    = contents of octal location 1000  
<SPACE>   = space character generated by Macro-ODT
```

A issued immediately after a prompt character causes a ? <CR> <LF> to be printed because a location is not open.

4.3.2 <CR>(ASCII 15) Carriage Return

This command is used to close an open location. If a location's contents are to be changed, the user should precede the <CR> with the new data. If no change is desired, <CR> closes the location without altering its contents.

Example: @R1/004321<SPACE> <CR> <CR> <LF>
@

Processor register R1 was opened and no change was desired so the user issued <CR>. In response to the <CR>, Macro-ODT printed <CR> <LF>@.

Example: @R1/004321<SPACE> 1234 <CR> <CR> <LF>
@

In this case the user desired to change R1, so new data, 1234, were entered before issuing the <CR>. Macro-ODT deposited the new data in the open location and then printed <CR> <LF> @.

Macro-ODT echoes the <CR> entered by the user and then prints an additional <CR>, followed by a <LF>, and @.

Example: @1000/012525<SPACE> 1234 <CR> <CR> <LF>

where:

first line = new data of 1234 entered into location 1000
and the location is closed with <CR>

4.3.3 <LF> (ASCII 12) Line Feed

This command is used to close an open location and then open the next contiguous location. LSI-11 Bus addresses are incremented by 2. If a processor register is open and a <LF> command is issued, the register is closed and any data that was typed in prior to <LF> will not enter the register. ODT prints the error message <CR> ? <CR> <LF>. If the open location's contents are to be changed, the new data should precede the <LF>. If no data are entered, the location is closed without being altered.

Example: @1000/123456<SPACE> <LF> <CR> <LF>
@1002/054321<SPACE>

Table 4-2 Macro-ODT States and Valid Input Characters

State	Example of Terminal Output	Valid Input
1	@	0--7 P X D
2	@R	0--7 S
3	@1000/ 123456	0--7 <CR>
4	@R1/123456	0--7 <CR> <LF>
5	@1000	0--7 / G
6	@R1 or @RS	/
7	@1000/ 123456 1000	0--7 <CR> <LF>
8	@R1/ 123456 1000	0--7 <CR>
9*	@DY	0 1 <CR>
10*	@DX	0 1 <CR>
11*	@DD	<CR> 0 1

*NOTE: Do not enter 0 or 1 followed by <CR>.

In this case, the user entered <LF> with no data preceding it. In response, Macro-ODT closed location 1000 and then opened location 1002.

4.3.4 R(ASCII 122) Internal Register Designator

The "R" character when followed by a register number, 0 to 7, or PS designator, S, will open that specific processor register.

Example: @R0/054321<SPACE>

or

@R7/000123<SPACE> 456 <CR> <CR> <LF>

@

If more than one character is typed (digit or S) after the R, Macro-ODT uses all the characters as the register designator.

Example: @R00007/000123<SPACE> <CR> <CR> <LF>

@

4.3.5 S (ASCII 123) Processor Status Word

This designator is for opening the PSW (processor status word) and must be employed after the user has entered the R register designator.

Example: @RS/100377<SPACE> 0 <CR> <CR> <LF>
@RS/100317<SPACE>

Note that the T-BIT FILTER prevents the user from setting the T-BIT via Macro-ODT. The T-BIT can be cleared by any write to the PSW. When the filter is disabled, the T-BIT can be set by loading the PSW to set bit 4 to a one. This is normally not considered desirable. The T-BIT FILTER can be disabled by setting bit 15 of location 167772 to a one.

The PRIORITY 7 FILTER prevents the user from setting a priority level of 7 via Macro-ODT. Operation at priority level 7 masks out (disables) the BREAK interrupt and makes it impossible to return to Macro-ODT. This type of operation is normally undesirable. If required, the PRIORITY 7 FILTER can be disabled by setting bit 7 of location 167772 to a one. With the filter disabled, a priority level of 7 is established by writing 340 into the PSW.

4.3.6 G (ASCII 107) Go

This command is used to start program execution at a location entered immediately before the G.

Example: @200G

The Macro-ODT sequence for a G, after echoing the command character, is as follows.

1. Load R7 (PC) with the entered data. (In the above example, R7 is equal to 200 and that is where program execution begins.)
2. The PS is cleared to 0.
3. The LSI-11 Bus is initialized by the processor's asserting BINIT L for 17 microseconds minimum and then negates BINIT L.
4. The user program begins execution at the location specified.

The user is warned that the command clears the PSW, which will permit clock interrupts to be acknowledged. Failure to load the address of the clock service routine into the clock vector address (100) may lead to unpredictable results.

4.3.7 P (ASCII 120) Proceed

This command is used to resume execution of a program. No programmer-visible machine state is altered using this command.

Example: @P

Program execution resumes at the address pointed to by R7. After P is echoed, Macro-ODT exits and the program resumes execution.

4.3.8 DD, DX, DY Bootstraps

This command is used to bootstrap a standalone program or XXDP+ diagnostics from an RX01, RX02 floppy diskette or a TU58 tape cartridge. The next character after the D command determines the type of device being booted. The numerical character, either 0 or 1, is optionally used to specify a particular drive or unit of the device being booted. If <CR> is typed instead of 0 or 1, then unit 0 is assumed.

Examples: Boot unit 0 of TU58 device:

@DD<CR>

Boot unit 1 of RX01 device:

@DX1

Boot unit 0 of RX02 device:

@DY0

NOTE

Do not type both unit number and <CR>.

To boot a diskette drive, ODT expects the RXV11 or RXV21 controller CSR address to be configured for 177170. To boot the TU58, it must be connected to SLU2 and the baud rate set for 38,400.

Any error detected during the execution of a boot command will cause a halt at one of several addresses in the boot portion of the ROM, with the PC contents printed on the console. The actual addresses, and the specific error each signifies, are given in the listing supplied with the option.

Some errors, however, are not reported. If no TU58 is connected to SLU2, or if baud rates are incompatible, no error indication is given after using the "DD" command and the program simply waits forever. This is also true when booting from floppies when the drive power is off. In either case, the user can use <BREAK> to return to ODT prompt level "@".

The D command will perform the following operations.

1. If there is no RAM memory at address zero, it will cause a halt.
2. It will initialize the LSI-11 Bus by asserting BINIT L for 17 microseconds minimum.
3. It will read Block 0 (the first 512 bytes) from the selected mass storage device into memory locations 000--777.
4. It will read location zero and if it is 240, it will load R1 register with the CSR address of the booted device, load R0 register with the selected unit or drive number, and jump to location zero.
5. If the contents of location zero is 260, then the mass storage device contains a "standalone program". Macro-ODT interprets the contents of locations 2, 4, and 6 as a RADIX-50 encoded six character file name. Macro-ODT assumes that the mass storage device is an RT-11 file structured volume and searches the directory of the volume for the file name provided by locations 2, 4, and 6. When the file is found, the entire file is loaded into contiguous memory starting at location zero. The R0 register is loaded with the number of the unit or drive and the R1 register is loaded with the CSR address of the booted device. The Stack Pointer (SP) is loaded with the contents of location 42 and the Program Counter (PC) is loaded with the contents of location 40. The program begins execution.
6. If the contents of location zero is not 240 or 260, then the device does not contain a valid boot block. The boot command is aborted and the SBC-11/21 is initialized as if a power up occurred.

4.3.9 X (ASCII 130) Diagnostics

After typing the letter "X", a 3-second delay will occur, then an octal number will be displayed. This command is described in detail in Chapter 2.

4.4 INITIALIZATION

When it is desired to re-initialize the system without removing power, enter 173000G from the console in response to the "@". Note that a carriage return will have to be typed, after a pause, to resynchronize the terminal as described in the following example.

Example: @173000G

After a pause of at least one second, type <CR> to resynchronize.

4.5 WARNINGS AND PROGRAMMING HINTS

The following warnings and programming hints are provided to assist the user in operating Macro-ODT.

4.5.1 Error Decoding

In the event of an unexpected appearance of "@", it is a good practice to examine the word at 167774. This is an error word that indicates the cause of entry to ODT. A HALT instruction, BREAK, or an attempt to fetch from nonexistent memory will appear as 100000. Other attempted bus transactions to nonexistent memory will appear as 000200, or 000201 if accessed by the stack pointer R6.

4.5.2 ODT Stack Warning

While performing its various functions, Macro-ODT requires two words of user stack. It will transparently push and pop internal information there. It is imperative then, that the user always provide two more words than those actually necessary for the proper execution of the application program. If desired, these two words can be given back when the program is completely debugged and operating within its own ROMs without ODT.

For proper program operation, R6 should always contain a valid even RAM memory address. Failure to observe this rule will cause unpredictable results.

4.5.3 Addresses to Avoid

Since the firmware uses the top of the SBC-11/21 on-board RAM as its scratchpad, the user should not write to any address above 167642 unless specifically designated in this manual.

The vector at 140 governs the BREAK interrupt. Altering locations 140 and 142 could result in the inability to suspend program execution.

4.5.4 CPU Priority

When the PSW is set to 340, the BREAK key will have no effect, and will not invoke Macro-ODT. Running at a level 6 priority (PSW set to 300) is adequate for most programming needs. This will disable all interrupts except for BREAK.

4.5.5 Terminal Related Problems

Macro-ODT echoes every character typed in response to the "@" prompt. Some intelligent terminals also respond to control characters as commands. The results may include loss of communication.

4.5.6 Spurious HALTs

When the last word of an instruction is all zeros and causes a bus timeout, Macro-ODT will interpret it as a HALT instruction. It will then print the contents of PC on the terminal, before issuing the "@" prompt.

4.5.7 Serial I/O Protocol

The Macro-ODT operates the serial line interface in full duplex mode and each character is echoed by the microprocessor to the terminal. Programmed I/O techniques are used rather than interrupts. When the Macro-ODT firmware is busy printing a multi-character message using the transmit side of the interface, the firmware is not monitoring the receive side for incoming characters. Any characters coming in at this time are lost. The interface may set the overrun error bit, but the Macro-ODT does not check this bit and those characters are not recognized. All peripherals communicating with the Macro-ODT through this interface must observe this protocol.

4.5.8 Interrupt Vector Initialization

Upon power-up, Macro-ODT initializes the LTC interrupt vector (REVNT at 100) and the BREAK interrupt vector (BKRQ at 140). No other vectors are initialized and may contain spurious data.

CHAPTER 5 SYSTEM ARCHITECTURE

5.0 GENERAL

This chapter describes the architecture of the microprocessor, memory organization and power up method. The microprocessor architecture describes the registers, hardware stack, interrupts and DMA mechanism. The memory organization describes byte or word addressing and memory mapping. The power up procedure and initialization are also briefly described.

5.1 MICROPROCESSOR ARCHITECTURE

The SBC-11/21 microprocessor executes a subset of the PDP-11 instruction set. It has eight, high speed, general purpose registers that are used as accumulators, address pointers, index registers and for other specialized functions. The microprocessor executes single and double operand instructions using either 16-bit words or 8-bit bytes. The Direct Memory Access (DMA) function transfers data directly from the LSI-11 bus to the on board I/O devices and memory, while the program continues to run.

5.1.1 Registers

With reference to Figure 5-1, the microprocessor contains a number of internal registers which are used for various purposes. The registers are broken up into two groups:

- o General
- o Status

5.1.1.1 General Registers -- The microprocessor contains eight 16-bit general-purpose registers that can perform a variety of functions. These registers can serve as accumulators, index registers, autoincrement registers, autodecrement registers, or as stack pointers for temporary storage of data. Arithmetic operations can be performed from one general register to another, from one memory location or device register to another, or between memory locations or a device register and a general register.

Registers R6 and R7 are dedicated. R6 serves as the Stack Pointer (SP) and contains the location (address) of the last entry in the stack. Register R7 serves as the processor Program Counter (PC) and contains the address of the next instruction to be executed. It is normally used for addressing purposes only and not as an accumulator.

5.1.1.2 Status Register -- The Processor Status Word (PSW) contains information on the current processor status. This information includes the current processor priority, the condition codes describing the arithmetic or logic results of the last instruction, and an indicator for detecting the execution of an instruction to be trapped during program debugging. The PSW format is shown in Figure 5-1, and Table 5-1 lists status word bit descriptions. Certain instructions allow programmed manipulation

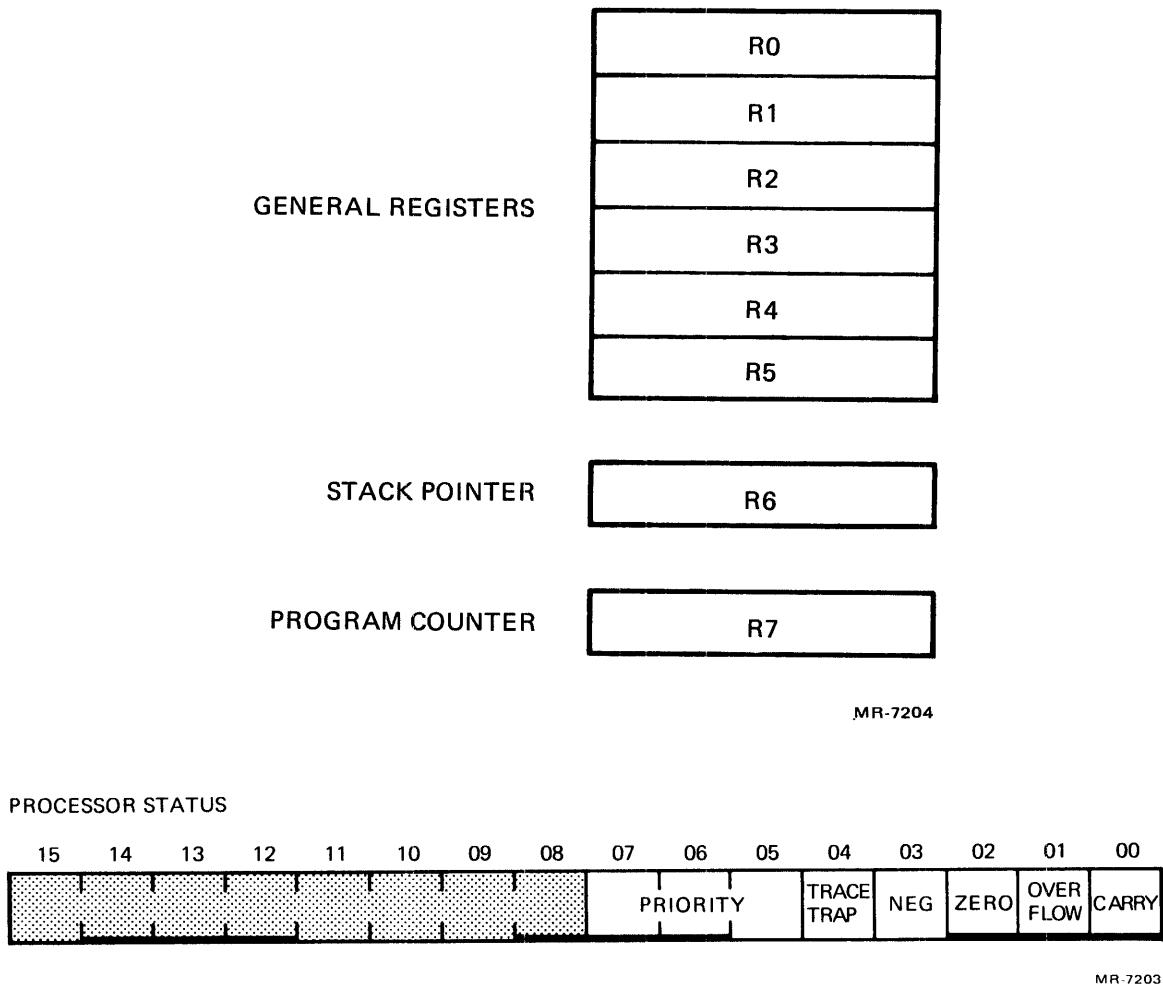


Figure 5-1 Registers and Processor Status Word

of condition code bits and loading and storing (moving) the processor status. Not all instructions affect the condition codes in an obvious manner. For details of specific instructions refer to Chapter 7.

5.1.2 Hardware Stack

The hardware stack is part of the basic design architecture of the SBC-11/21. It is an area of memory set aside by the programmer or by the operating system for temporary storage and linkage. It is handled on a LIFO (last in/first out) basis, where items are retrieved in the reverse of the order they were stored. The stack starts at the highest location reserved for it (376 octal at power up) and expands linearly downward to a lower address as items are added to the stack.

Table 5-1 Processor Status Word Bit Descriptions

Bit	Name	Description
15--8	N/A	These bits are not accessible to the programmer and contain no valid information.
7--5	Priority	These bits define the current priority level of the microprocessor program and only interrupts with a higher priority are recognized by the microprocessor. Table 5-2 describes the microprocessor interrupt levels as functions of bits 5-7.
4	Trace	When set this bit allows the microprocessor to trap to locations 14 and 16 after an instruction is executed. It can only be set by executing an RTI or RTT instruction with the desired PSW already on the stack. The trace bit is useful in debugging programs by allowing them to be single stepped.
3	Condition Code N	This bit is set when an instruction causes the result to be negative.
2	Condition Code Z	This bit is set when an instruction causes the result to be zero.
1	Condition Code V	This bit is set when an instruction causes an overflow condition.
0	Condition Code C	This bit is set when an instruction causes a carry out of the most significant bit.

It is not necessary to keep track of the actual locations into which data is being stacked. This is done automatically through the use of the Stack Pointer (SP). Register six (R6) always contains the memory address where the last item is stored in the stack. Instructions associated with subroutine linkage and interrupt service automatically use register six as the hardware stack pointer. For this reason, R6 is frequently referred to as the system SP. The hardware stack is organized in full word units only.

5.1.3 Interrupts

Interrupts are requests, made by peripheral devices, which cause the processor to temporarily suspend its present program execution to service the requesting device. A device can interrupt the processor only when its priority is higher than the processor priority indicated by PSW<7:5>, as shown in Table 5-2.

SBC-11/21 supports a vectored interrupt structure with priority on four levels. In addition, it supports two nonmaskable interrupts: Power Fail and -HALT.

Every interrupt except HALT is associated with an interrupt vector. The interrupt vector is a pair of words, next PC (address of that device's service routine) and next PSW (priority with which the routine must be executed). Upon interrupt the current PC and PSW are saved on the stack and the new PC and PSW are loaded from the vector address.

Up to 64 vectors may reside in the first 256 memory locations (octal 374 is the highest vector location). The vector address is provided by the interrupting device (external vector address) or generated internally by the microprocessor.

NOTE

The Power Fail interrupt uses interrupt vector address 24. HALT interrupt is not associated with a vector. It pushes the PC and PSW onto the stack and immediately goes to the restart address with PSW 340.

Table 5-2 PSW Interrupt Levels

Microprocessor Priority	Interrupt Levels Acknowledged	PSW Bits
		7 6 5
level 7	Unmaskable Interrupt	1 1 1
level 6	7	1 1 0
level 5	7,6	1 0 1
level 4	7,6,5	1 0 0
level 0-3	7,6,5,4	0 X X

The SBC-11/21 has eleven interrupt sources of which nine are maskable and two are nonmaskable. The interrupt request can occur at any time but is not acknowledged until the completion of the current instruction. This allows the microprocessor to execute a program until the interrupt occurs and then the microprocessor vectors to the service routine for the interrupt. After the service routine is completed, a Return From Interrupt (RTI) instruction is executed. The microprocessor then pops the top two words from the system stack, which were the original PC and PSW, and the interrupted program is resumed.

The eleven interrupt sources with their respective priorities are listed in Table 5-3. For a device to be serviced, its priority level must be higher than the current microprocessor level. When two devices with equal priority numbers simultaneously request an interrupt, the device listed closest to the top of the table will be serviced first.

When the interrupt is requested by several LSI-11 bus devices simultaneously, the device electrically nearest to the SBC-11/21 is serviced first.

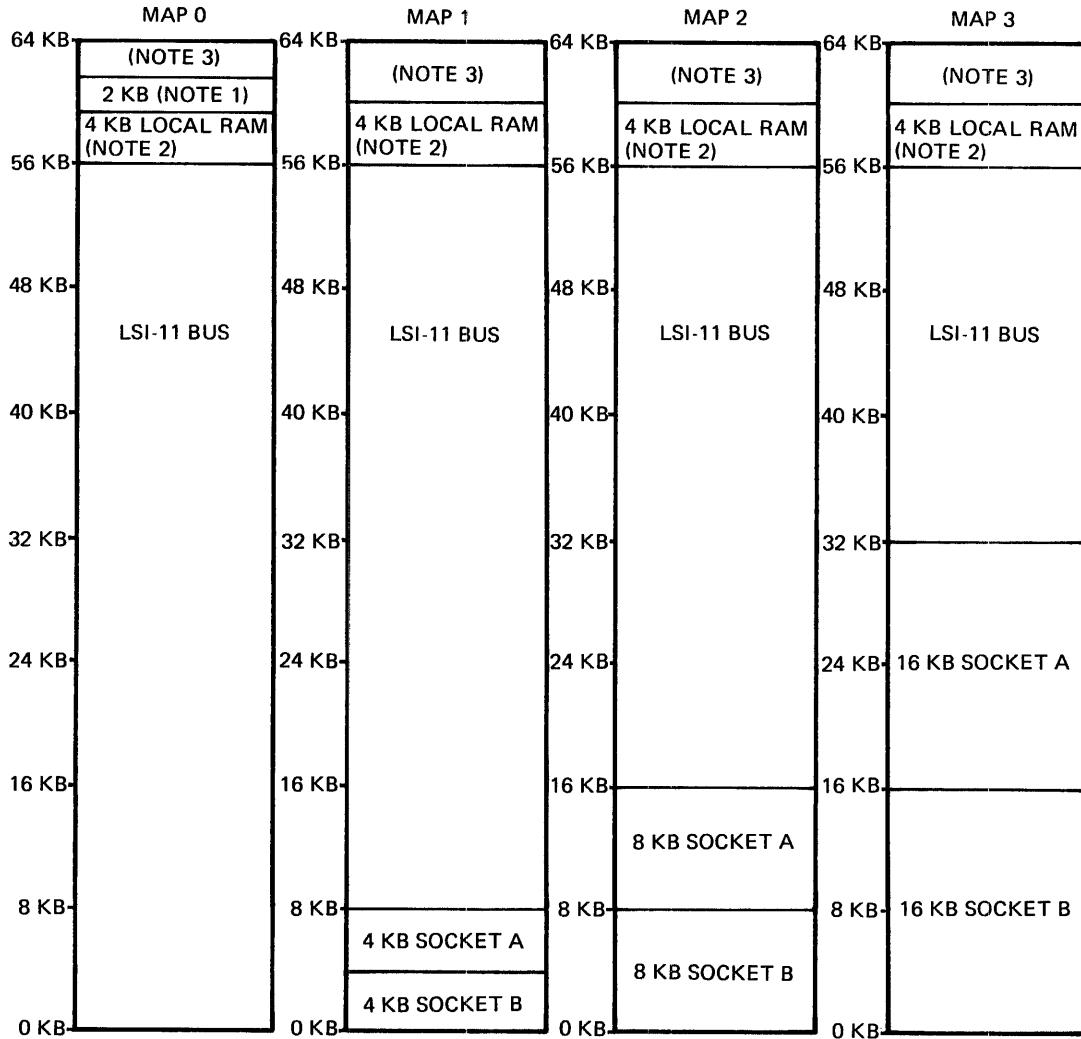
5.2 DMA (DIRECT MEMORY ACCESS)

DMA allows the programmer to implement block transfers by specifying the direction of transfer, the starting address in memory, the number of words and any additional parameters that a particular external device requires. SBC-11/21 does not have an on-board DMA interface, but can support DMA transfers for external devices via the LSI-11 bus interface. A typical device utilizing the DMA technique is the RX02 double-density floppy. User designed devices can also be connected to the SBC-11/21 DMA facility. For a more detailed treatment the reader is referred to Chapter 9.

5.3 MEMORY ORGANIZATION

The SBC-11/21 memory consists of onboard memory and LSI-11 bus memory. The memory map configurations and the types of onboard memory chips are described in Chapter 2. The memory maps are described in Figure 5-2. Addresses from 0 to 376 octal are reserved for vector locations and addresses from 60 Kb to 64 Kb are reserved for I/O devices.

The address space of the SBC-11/21 module is 64 Kbytes. A 16-bit word is composed of two 8-bit bytes with bits 0--7 representing the low byte and bits 8--15 representing the high byte. Words are always addressed by even numbers. The bytes are addressed by either even or odd numbers. The high bytes are stored in the odd numbered locations and the low bytes are stored in the even numbered locations.



NOTES:

1. SOCKET SET A IS MAPPED OVER SOCKET SET B AND IS THEREFORE LIMITED TO USING EITHER SOCKET A OR SOCKET B, BUT NOT BOTH TOGETHER.
2. ADDRESSES 160000 THROUGH 160007 ARE ASSUMED TO RESIDE ON THE LSI-11 BUS.
3. THIS SECTION CONTAINS THE LOCAL I/O ADDRESSES FOR THE SLUs AND PPI. ALL UNASSIGNED ADDRESSES ARE ASSUMED TO RESIDE ON THE LSI-11 BUS.

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Figure 5-2 Memory Maps

Table 5-3 SBC-11/21 Interrupts

Interrupt Source	Control Signal	Priority Level	Vector Address**
HALT	-CTMER	nonmaskable	*
POWER FAIL	-PFAIL	nonmaskable	24
LSI-11 Bus Signal BHALT	BKRQ	7	140
LSI-11 Bus Signal BEVNT	REVNT	6	100
SLU2 REC	RDL2	5	120
SLU2 XMIT	XDL2	5	124
PARALLEL I/O B	PBRQST	5	130
PARALLEL I/O A	PARQST	5	134
SLU1 REC	RDLL	4	60
SLU1 XMIT	XDLL	4	64
LSI-11 Bus Signal BIRQ4	IRQ4	4	Read from LSI-11 Bus

*The microprocessor jumps directly to the restart address with a PSW priority level 7. (RESTART is loaded into PC and 340 into PSW).

**All vectors defined in this table are internal vectors supplied by the microprocessor, except for the BIRQ4 interrupt which is read from the bus.

5.4 POWER UP/DOWN FACILITY

SBC-11/21 has facilities for assuring an automatic program start-up when power is turned on and for orderly shutdown, without loss of data, when power is turned off or lost. This is accomplished by a combination of hardware features and software.

Hardware features:

- o Two signal lines in the LSI-11 bus called BDCOK H and BPOK H used only for power up/down protocol. These signals are usually generated by the power supply.
- o One signal line in the LSI-11 bus, called BINIT L, which resets the system.
- o The vectoring on interrupt facility of the SBC-11/21.
- o Battery backup connections

Software features:

The programmer must provide power up and power down routines, and store their addresses at the jumper selected start address for power up, and at location 24 for the power down routine.

The detailed description of the power up/down protocol will be found in Chapter 9.

CHAPTER 6
PROGRAMMING INFORMATION

6.0 GENERAL

The SBC-11/21 has three on-board interfaces, one parallel I/O and two serial I/O lines. These interfaces contain a number of programmable features that allow the user to change their operating characteristics. This chapter explains how this can be accomplished.

SBC-11/21 is also equipped with hardware that enables the microprocessor to behave in a controlled manner when the power is turned on and off. This specialized hardware requires software to make it work and an example in Appendix C describes the basic principles of this programming.

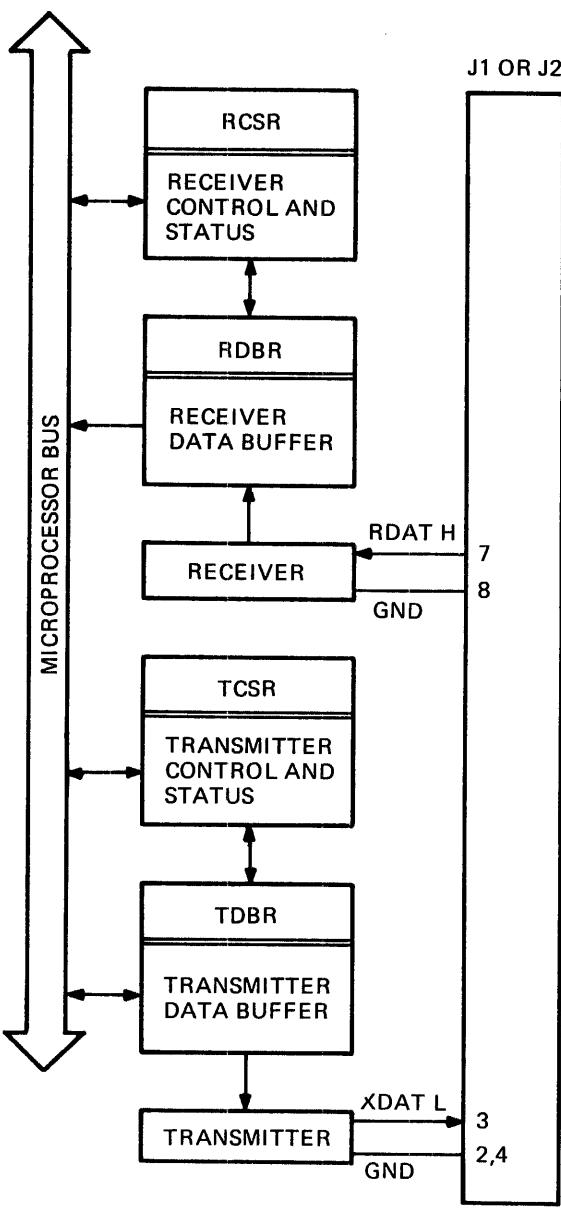
6.1 ASYNCHRONOUS SERIAL LINE UNITS

The two Serial Line Units (SLUs) are described by Figure 6-1 and provide the means of transferring data between the microprocessor and two user connectors J1 or J2. The user interfaces support the RS232C EIA standard and RS423 protocol, at baud rates ranging from 300 to 38400.

Each SLU is equipped with four addressable registers that are listed in Table 6-1, described by Figure 6-2, and functionally described by Tables 6-2, 6-3, 6-4, and 6-5. The registers can be accessed by the microprocessor or any DMA bus master. SLU1, with the proper software handling, can be used as a system console and is capable of initiating a hardware interrupt when BREAK is detected. SBC-11/21 can be configured for the BREAK to cause a level 7 interrupt with an internal vector of 140, enable the BHALT interrupt or request a HALT trap to the restart address. SLU2 provides three line time clocks at 50 Hz, 60 Hz and 800 Hz, which can be wire-jumper configured to enable the BEVNT level 6 interrupt. Refer to Chapter 2 for details on how to configure the SLUs.

Table 6-1 . Serial Line Unit Register Addresses

Register	Description	Address	AD2	AD1
SLU1				
RCSR	Receiver Control and Status	177560	0	0
RDBR	Receiver Data Buffer	177562	0	1
TCSR	Transmitter Control and Status	177564	1	0
TDBR	Transmitter Data Buffer	177566	1	1
SLU2				
RCSR	Receiver Control and Status	176540	0	0
RDBR	Receiver Data Buffer	176542	0	1
TCSR	Transmitter Control and Status	176544	1	0
TDBR	Transmitter Data Buffer	176546	1	1



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Figure 6-1 Serial Line Unit Interface (SLU)
6-2

Table 6-2 Receiver Control and Status Bit Descriptions

Bit	Name	Direction	Function
12-15	Not Used	Read Only	Reserved for future use.
11	Receiver Active	Read Only	This bit is set to a "one" by the start bit and is cleared to a "zero" by the stop bit at the end of each byte. It is also cleared to a "zero" on power-up.
08-10	Not Used	Read Only	Reserved for future use.
07	Receiver Done	Read Only	This bit is set to a "one" when the byte received is transferred into the RCV Data Buffer. It is cleared to a "zero" when the RCV Data Buffer is read. It is also cleared to "zero" on power-up.
06	Receiver Interrupt Enable	Read Write	This bit is set to a "one" under program control. When set, it allows an Interrupt Request to be initiated whenever the Receiver Done bit is set. It is cleared to a "zero" by RESET, power-up or under program control. Refer to Chapter 2 for interrupt jumper configuration.
00-05	Not Used	Read Only	Reserved for future use.

6.1.1 Data Baud Rates

The serial line units transmit or receive data serially by bit and by character. Each character consists of ten bits; a start bit, 8 bits of data, and the stop bit. Split speed operation of the receiver and transmitter for the SLU is not supported and the user cannot supply an external baud rate clock to the SLU. During Power Up or RESET, the outputs are disabled and later the baud rate defaults to 300.

The baud rates are programmable for 300, 600, 1200, 2400, 4800, 9600, 19200 or 38400 when bit 01 of the Transmitter Control and Status register (TCSR) is set to a one. The baud rate is then selected by programming bits 05--03 of the TCSR.

These four bits used for the baud rate selection are level sensitive, and do not latch. Therefore, the software in control of the TCSR must use bit set and bit reset type instructions after the baud rate is written into the SLU. Each SLU provides an output at TTL levels to pin 1 of its connector (J1 or J2) at 16 times the baud rate selected for that SLU.

RECEIVER CONTROL AND STATUS REGISTER

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
0	0	0	0	RCV ACT	0	0	0	RCV DONE	RCV IE	0	0	0	0	0	0

SLU 1 ADDRESS 177560

SLU 2 ADDRESS 176540

RECEIVER DATA BUFFER REGISTER

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
ERR	OR ERR	FR ERR	0	REC BRK	0	0	0								RECEIVED DATA BUFFER

SLU 1 ADDRESS 177562

SLU 2 ADDRESS 176542

TRANSMITTER CONTROL AND STATUS REGISTER

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
0	0	0	0	0	0	0	0	XMIT RDY	XMIT IE	PBR SEL2	PBR SEL1	PBR SEL0	MAINT	PBR ENB	XMT BRK

SLU 1 ADDRESS 177564

SLU 2 ADDRESS 176544

TRANSMITTER DATA BUFFER REGISTER

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
0	0	0	0	0	0	0	0								TRANSMIT DATA BUFFER

SLU 1 ADDRESS 177566

SLU 2 ADDRESS 176546

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Figure 6-2 Serial Line Unit Register Bit Maps

Table 6-3 Receiver Data Buffer Bit Descriptions

Bit	Name	Direction	Function
15	Error	Read Only	The bit is set to a "one" when the Overrun Error or the Framing Error bit is set. It is cleared to a "zero" when the error producing condition is removed.
14	Overrun Error	Read Only	The bit is set to a "one" when the received byte is transferred into the RCV Data Buffer before the RCV DONE bit is cleared. The Overrun Error indicates that the previous byte in the RCV Data Buffer was not cleared prior to receiving a new byte. The bit is updated when a byte is transferred into the RCV Data Buffer and cleared to a "zero" on power-up.
13	Framing Error	Read Only	The bit is set to a "one" when the received character does not have a valid stop bit and is transferred into the RCV Data Buffer. The bit is cleared to a "zero" when a character with a valid stop bit is received and is transferred into the RCV Data Buffer or on power-up.
12	Not Used	Read Only	Reserved for future use.
11	Received Break	Read Only	The bit is set to a "one" when the received signal goes from a MARK to a SPACE and stays in the SPACE condition for 11 bit times after serial reception starts. The bit is cleared to a "zero" when the received signal returns to the MARK condition or on power-up.
08-10	Not Used	Read Only	Reserved for future use.
00-07	Received Data Buffer	Read Only	These 8 bits represent the most recent byte received. These bits are cleared to "zero" on power-up.

Table 6-4 Transmitter Control and Status Bit Description

Bit	Name	Direction	Function
08-15	Not Used	Read Only	Reserved for future use.
07	Transmitter Ready	Read Only	The bit is set to a "one" when the XMIT DATA BUFFER is ready to accept a byte. The bit is cleared to a "zero" by writing into the XMIT DATA BUFFER. The bit is also set to a "one" on power-up.
06	Transmitter Interrupt Enable	Read Write	This bit is set to a "one" under program control. When set, it allows an Interrupt Request to be initiated whenever the Transmitter Ready bit is set. The bit is cleared to a "zero" by RESET, power-up or under program control.
03-05	Programmable Baud Rate Select	Read Write	The condition of these bits selects the baud rate under program control, provided the Programmable Baud Rate Select Enable bit is set. The baud rates are selectable by setting these bits as follows.
			05 04 03 BAUD RATE
			0 0 0 300
			0 0 1 600
			0 1 0 1200
			0 1 1 2400
			1 0 0 4800
			1 0 1 9600
			1 1 0 19200
			1 1 1 38400
			When the Programmable Baud Rate Select Enable bit is not set baud rate defaults to 300.

Table 6-4 Transmitter Control and Status Bit Description (Cont)

Bit	Name	Direction	Function
NOTE			
	The transmitter Programmable Baud Rate Select and Enable bits are level sensitive and not latched. This requires that software in control of the TCSR must use bit set and clear instructions to access the TCSR once the baud rate has been written into the SLU.		
02	Maintenance	Read Write	This bit is controlled by the program. When set to a "one" the transmitter serial output is connected to the receiver serial input and disconnects the external serial input. This bit is cleared to a "zero" by INIT, on power-up, or the program.
01	Programmable Baud Rate Enable	Read Write	This bit is controlled by the program. When set to a "one", bits 03-05 are used to determine the baud rate. When cleared to a "zero" the baud rate will be 300 baud. This bit is cleared to a "zero" by INIT, power-up or the program.
00	Transmit Break	Read Write	This bit is controlled by the program. When set to a "one", the serial output is forced into the SPACE condition. This bit is cleared by INIT, power-up or the program.

Table 6-5 Transmitter Data Buffer Bit Descriptions

Bit	Name	Direction	Function
08-15	Not Used	Read Only	Reserved for future use.
00-07	Transmit Data Buffer	Read Write	These 8 bits represent the next data byte to be transmitted. These bits are cleared by power-up.

It should be noted that the Macro-ODT option is equipped with the autobaud feature that enables SLU1 to adjust itself to the terminal's baud rate between 300 and 9600 baud. The autobaud feature is operating only when Macro-ODT is running on the system.

6.1.2 Interrupts

Each SLU provides both a Receiver Interrupt and a Transmitter Interrupt to request service from the on-board microprocessor. The Receiver and Transmitter requests can be independently enabled by software. The Receiver Interrupt request is enabled when the RCV Interrupt Enable (bit 06) of the Receiver Control and Status register (RCSR) is set to a one.

SLU2 has a higher interrupt priority, level 5, than SLU1 which has a level 4 interrupt priority. Within each unit the receiver has higher priority than the transmitter. SLU1 uses vector address 60 for the receiver and 64 for the transmitter. SLU2 uses 120 for the receiver and 124 for the transmitter. These relationships are summarized in Table 5-3.

6.2 PROGRAMMING THE PARALLEL I/O INTERFACE

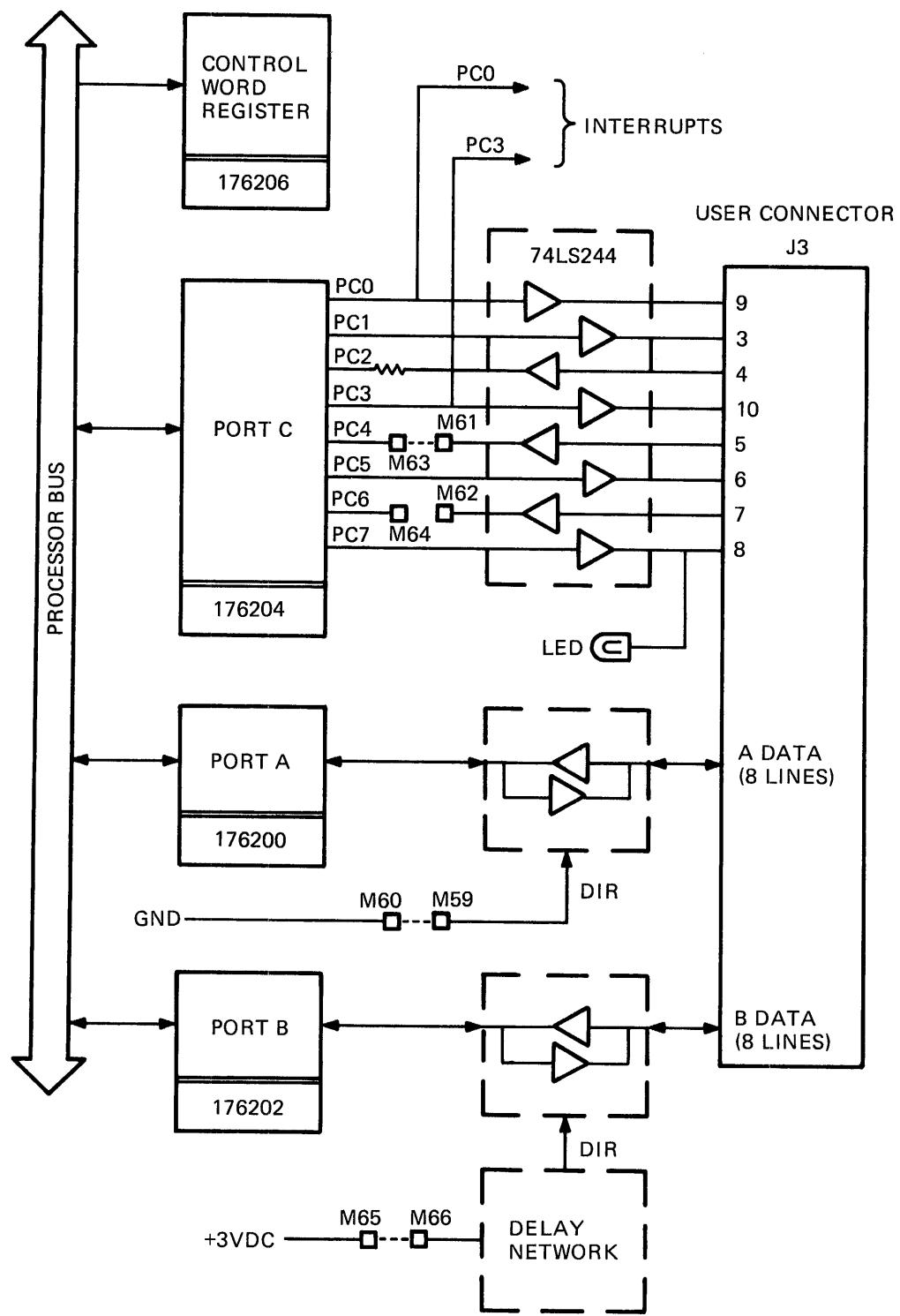
The parallel I/O interface, described by Figure 6-3, provides the means of transferring data between the microprocessor bus and the user interface connector J3. The interface is equipped with four addressable registers for data and control which are summarized in Table 6-6.

Table 6-6 Parallel I/O Register Addresses

Register	Address	Status
Port A	176200	Read/Write
Port B	176202	Read/Write
Port C	176204	Read/Write
Control Word	176206	Write Only

Port A and B registers are used only for data transfer to and from the user interface. Port C is used for both, data transfer and control. The control word register is used exclusively for control of the Parallel I/O interface. The interface owes its programmability to this register.

In addition to software programming, the parallel interface can also be programmed by hardware. This is covered in Chapter 2.



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Figure 6-3 Parallel I/O Interface
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6.2.1 How To Use This Section of The Manual

The parallel I/O interface is quite complex and a thorough understanding of all its capabilities will require a considerable effort. However, a very efficient use can be made of the parallel I/O by using a subset of these capabilities. This section has been organized to make the task of finding the needed information easier. The flowchart shown in Figure 6-4 provides an overview of the contents of this section and a few minutes reviewing it will aid the user.

After examining the flowchart the reader will be in a better position to decide whether to read in detail the rest of this chapter or if a specific I/O configuration is of immediate interest. If this is the case, the reader is encouraged to refer directly to that section.

6.2.2 Modes of Operation

The interface ports can operate in three basic modes that are selected by system software setting bits in the Control Word register. The modes are designated as Mode 0, 1 and 2 and define how the data is routed through ports A and B.

NOTE

If the bidirectional buffers are being hardwired, care must be taken to insure that the wired direction conforms to the programmed directions of ports A and B. This is necessary to avoid driver output to driver output connections, which could damage the integrated circuits.

6.2.2.1 Port C Register -- The bit assignments for the port C register are dependent upon the mode selected and the direction of ports A and B. This register provides the handshake controls to interface between the 8255A-5 and the output connector. The handshake control bits are set/reset by using the Control Word register which is described in the Control Word section. The port C condition for the various modes will be described in the sections dealing with those modes.

6.2.2.2 Mode 0 Basic Input/Output -- This mode provides simple input and output of either port A or port B or both as described in Table 6-7. The data is simply read from the port if programmed as an input or written to the port if programmed as an output with no handshaking requirements. The port A and port B bidirectional buffers may be hardwired as described in Chapter 2. They may also be program controlled by port C bits 4 and 6 if dynamic change of the port direction is desired. In this mode the outputs are latched but the inputs are not.

6.2.2.3 Port A and B Registers -- The bit assignments for the port A and B registers are shown in Figure 6-5 and described in Table 6-8. These registers are used as data buffers for all modes of operation.

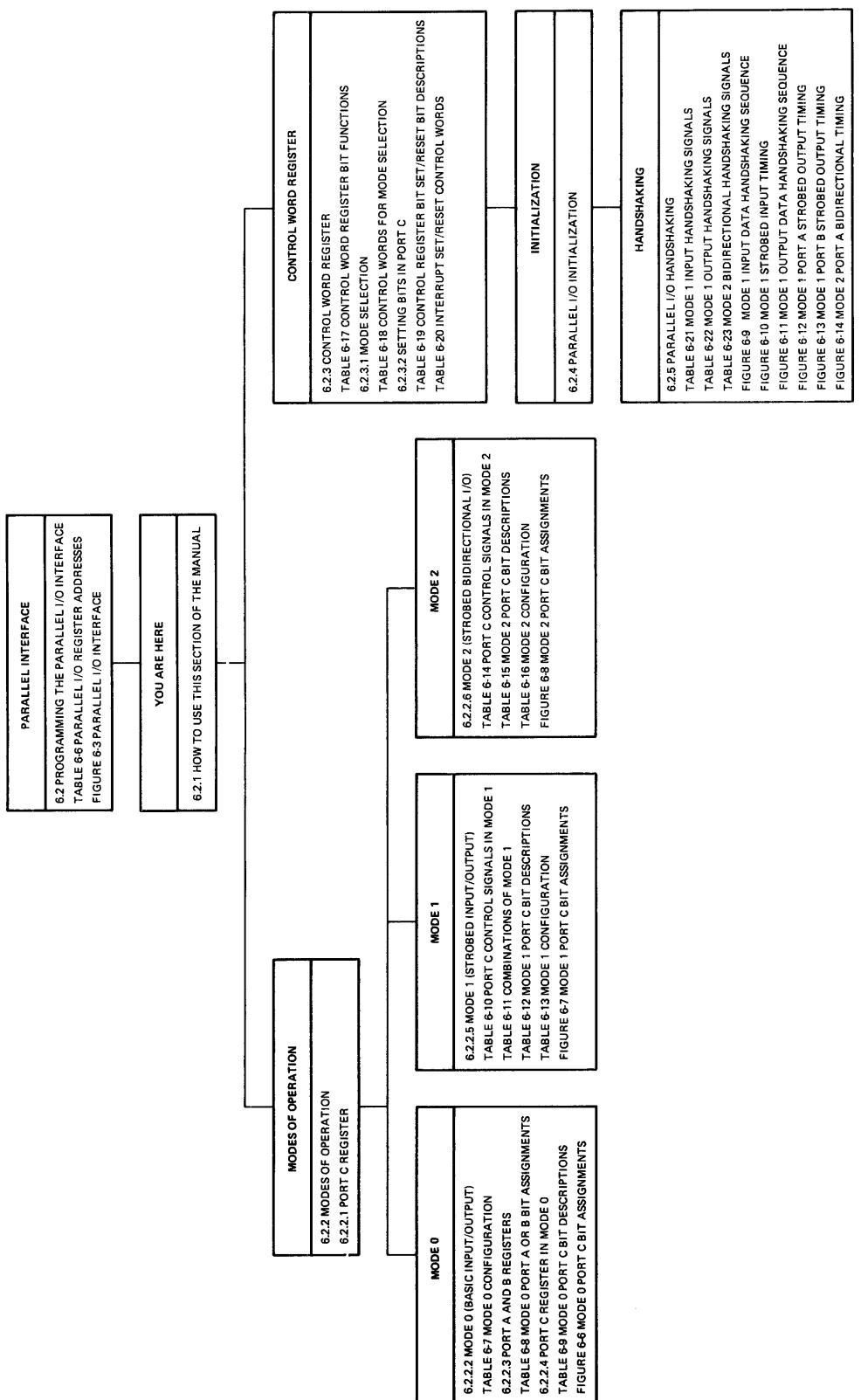
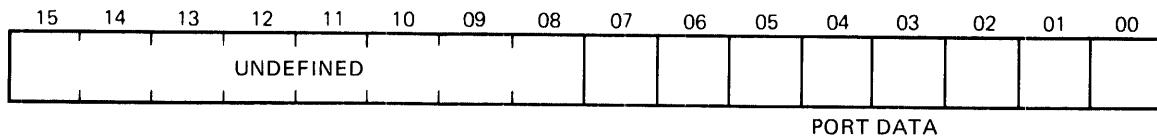


Figure 6-4 Parallel I/O Flowchart Guide

Table 6-7 Mode 0 Configuration

PPI Element	To Act as Input	To Act as Output	Direction Control via Port C
Port A	M66 to M65	M66 to M60	M66 to M64 or M63
Port B	M59 to M65	M59 to M60	M59 to M64 or M63
PC7	Never an Input	Always an Output	
PC6	M64 to M62	Never an Output	
PC5	Never an Input	Always an Output	
PC4	M63 to M61	Never an External Output	
PC3	Never an Input	Interrupt A (Vector 134) Always an Output	
PC2	Always an Input	Never an Output	
PC1	Never an Input	Always an Output	
PC0	Never an Input	Interrupt B (Vector 130) Always an Output	



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Figure 6-5 Mode 0, Port A or B, Bit Assignments

Table 6-8 Mode 0 Port A or B Bit Descriptions

Bit	Name	Direction	Function
8-15	Undefined	-	Not valid if a read is performed on the entire word.
0-7	Port Data	Read/Write	Data to output or input data to be read, depending on the port direction.

6.2.2.4 Port C Register in Mode 0 -- Ports A and B use no handshaking signals and some of port C lines can be used as Input/Output data lines. The bit assignments are shown in Figure 6-6 and described in Table 6-9. When PC0 and PC3 lines are not being used as interrupt requests, these bits should be cleared by the Control Word to prevent erroneous interrupts.

15	14	13	12	11	10	09	08	07	I/O PC7	I/O PC6	I/O PC5	I/O PC4	NOT USED	03	02	01	00
									UNDEFINED						INPUT PC2	NOT USED	NOT USED

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Figure 6-6 Mode 0 Port C Bit Assignments

Table 6-9 Mode 0 Port C Bit Descriptions

Bit	Name	Direction	Function
8-15	Undefined	-	Not valid if a read is performed on the entire word.
7	PC7	Read/Write*	Output bit. Drives the LED
6	PC6	Read/Write*	If Port C Upper is defined as input and M64 is connected to M62 then it is an input bit. If Port C Upper is defined as output and M64 is connected to M66 (M59) then it is output which controls the buffer direction for Port A (Port B). A "1" sets the buffer for input and a "0" for output.
5	PC5	Read/Write*	Same as PC7. No LED.
4	PC4	Read/Write*	If Port C Upper is defined as input and M63 is connected to M61 then it is an input bit. If Port C Upper is defined as output and M63 is connected to M59 (M66) then it is output which controls the buffer direction for Port B (Port A). A "1" sets the buffer for input and a "0" for output.
3	PC3	Not used	Not valid.
2	PC2	Read Only	Input bit.
0-1	PC0-PC1	Not used	Not valid.

*Bit is written by using the Control Word bit set/reset function explained in the Control Word section.

6.2.2.5 Mode 1 (Strobed Input/Output) -- In this mode, the lines on port C generate or accept signals from the user interface which control the transfer of data through ports A and B. Port C bits 0--3 (lower nibble) are used in conjunction with port B and bits 4--7 (upper nibble) are used with port A. These signals are known as "handshaking" signals. Before describing the details of the handshaking protocol, the basic functions of these control signals are defined in Table 6-10.

Table 6-11 describes the four input/output combinations of ports A and B usable in mode 1. The port C bit assignments as used in mode 1 are described by Figure 6-7 and tabulated in Table 6-12. Finally, Table 6-13 links operation of mode 1 to the jumper configurations discussed in Chapter 2.

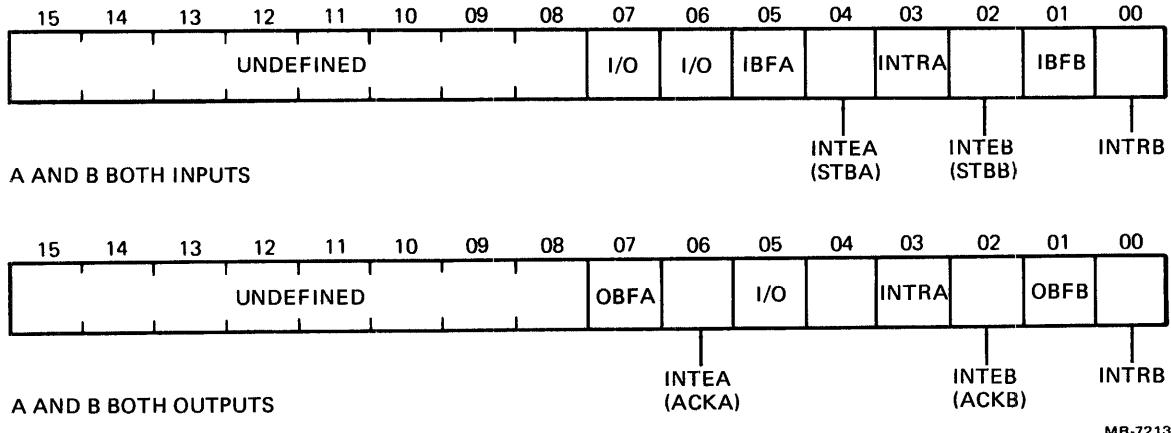


Figure 6-7 Mode 1 Port C Bit Assignments

6.2.2.6 Mode 2 (Strobed Bidirectional I/O) -- This mode implements a means of communication with a user device over a single 8-bit bus for both transmitting and receiving data. Handshaking and interrupt signals are used in a manner similar to mode 1.

This mode is used with port A only and five control lines on port C. Both inputs and outputs are latched. When port A is operating in this mode, the port B bidirectional buffers cannot be operated under program control since PC4 and PC6 are being used. Port B can still operate in either mode 0 or mode 1, but the buffers must be hardwired. PC0--PC2 are defined by port B usage for mode 1 and are available as I/O lines when port B is in mode 0.

Table 6-10 Port C Control Signals in Mode 1

Signal	Abbrev/Port C Bit	Function
Strobe Input	-STB _A /PC4 -STB _B /PC2	A low on this input loads user data into the input latch.
Input Buffer Full	IBF _A /PC5 IBF _B /PC1	A high on this output acknowledges that the data has been loaded into the input latch. Set by STB and reset by the program reading the input latch.
Interrupt Request (Input Mode)	INTR _A /PC3 INTR _B /PC0	A high on this output can interrupt the CPU when an input device strobes its data into the port.
Interrupt Enable (Input Mode)	INTE _A /PC4 INTE _B /PC2	Enables setting of INTR _A and INTR _B . Program controlled by PC4 or PC2.
Output Buffer Full	-OBF _A /PC7 -OBF _B /PC1	This output goes low to tell the user interface that CPU has written data to the port. Reset by ACK input being low.
Acknowledge Input	-ACK _A /PC6 -ACK _B /PC2	A low on this input tells the processor that the user's device accepted the data from A or B.
Interrupt Request (Output Mode)	INTR _A /PC3 INTR _B /PC0	A high on this output can interrupt the CPU when an output device has accepted data transmitted by the CPU. Set by ACK. Reset when new data is written to the port.
Interrupt Enable (Output Mode)	INTE _A /PC6 INTE _B /PC2	Enables setting of INTR. Program controlled by PC6 or PC2.

Table 6-11 Combinations of Mode 1

Port C Bit Functions	Port A Input with Port B Output	Port A Output with Port B Input	Ports A & B Output	Ports A & B Input
STB _A	PC4	N/A	N/A	PC4
STB _B	N/A	PC2	N/A	PC2
IBF _A	PC5	N/A	N/A	PC5
IBF _B	N/A	PC1	N/A	PC1
INTR _A	PC3	PC3	PC3	PC3
INTR _B	PC0	PC0	PC0	PC0
OBF _A	N/A	PC7	PC7	N/A
OBF _B	PC1	N/A	PC1	N/A
ACK _A	N/A	PC6	PC6	N/A
ACK _B	PC2	N/A	PC2	N/A
Other Port C outputs	PC7 (Controls LED)	N/A	PC5	N/A
Other Port C inputs	N/A	PC4	N/A	PC6,7

Control Word

D0 (Direction of PC0-3)	X	X	X	X
D1 (Direction of Port B)	0	1	0	1
D2 (Mode of Port B)	1	1	1	1
D3 (Direction of PC4-7)	0	1	1	0
D4 (Direction of Port A)	1	0	0	1
D5 Port A Mode	1	1	1	1
D6 Port A Mode	0	0	0	0
D7 Mode set enable	1	1	1	1

Table 6-12 Mode 1 Port C Bit Descriptions

Bit	Name	Direction	Function
8-15	Undefined	-	Not valid if a read is performed on the entire word.
7	PC7	Read/Write*	<p>If Port A Mode 1 Input:</p> <p>If Port C bits 4-7, defined as output this bit is an output bit and controls the LED. A "0" turns the LED on and a "1" turns it off.</p> <p>Unused if PORT C bits 4-7 defined as input</p>
	OBFA	Read Only	<p>If Port A Mode 1 Output:</p> <p>OBFA goes low to indicate that data has been written into the output buffer by the processor. This bit is set when the ACKA (PC6, M64 to M62) input goes low indicating that the external device has accepted the output data. OBFA is present on PC7 to the external device.</p>
6	PC6	Read/Write*	<p>If Port A Mode 1 Input:</p> <p>If Port C bits 4-7 defined as input and M64 is connected to M62 then it is an input bit. If Port C bits 4-7 defined as output and M59 is connected to M64 it is an output which controls the buffer direction for Port B. A "1" sets the buffer for input and a "0" sets the buffer for output.</p>
	INTEA	Read/Write*	<p>If Port A Mode 1 Output:</p> <p>INTEA when set enables INTRA to interrupt the SBC-11/21 when output data has been accepted by the external device.</p>
	ACKA		<p>When M64 is connected to M62, an external signal acknowledging the receipt of data acts as INTEA.</p>

Table 6-12 Mode 1 Port C Bit Descriptions (Cont)

Bit	Name	Direction	Function
5	IBFA	Read Only	If Port A Mode 1 Input: IBFA indicates that the input data has been latched for Port A. It is set by the STBA input (PC4, M63 to M61) being low and is reset by the processor reading the port data. This signal is present on PC5 to the external device.
	PC5	Read/Write*	If Port A Mode 1 Output: If Port C Upper defined as output then it is an output bit. If Port C Upper defined as input it is unused.
4	INTEA	Read/Write*	If Port A Mode 1 Input: INTEA if set will allow INTRA to interrupt the SBC-11/21 whenever the input buffer is full.
	PC4	Read/Write*	If Port A Mode 1 Output: If Port C bits 4-7 is defined as output and M59 is connected to M63 then this bit is output which controls the direction of the Port B buffer. A "1" sets the buffer for input and a "0" sets it for output. If Port C bits 4-7 is defined as input and M63 is connected to M61 then it is an input bit and is interpreted as STBA (input strobe).
3	INTRA	Read Only	If Port A Mode 1 Input: A "1" indicates that Port A has valid input data. It is set by STBA (PC4, M63 to M61) being pulsed low and is reset by the processor reading the Port data. INTRA is enabled by INTEA being a "1" and disabled by INTEA being a "0".

Table 6-12 Mode 1 Port C Bit Descriptions (Cont)

Bit	Name	Direction	Function
If Port A Mode 1 Output:			
A "1" indicates that Port A is ready to accept new output data. It is set by ACKA (PC6, M64 to M62) being pulsed low and reset by the processor writing new output data to the port. Enabled and disabled as above.			
When enabled INTRA interrupts the processor and has a vector of 134.			
This signal is also an output to the external device on line PC3.			
2	INTEB	Read/Write*	INTEB when set will allow INTRB to interrupt the SBC-11/21 to request service.
1	IBFB	Read Only	If Port B Mode 1 Input: IBFB indicates input data has been latched for Port B when a "1". It is set by the STBB (PC2) being low and is reset by the processor reading the port data. This signal is present on PC1 to the external device.
	OBFB	Read Only	If Port B Mode 1 Output: OBFB goes low to indicate that the processor has written data to the port. This bit is set by ACKB (PC2) going low indicating the external device has accepted the output data. This signal is present on PC1 to the external device.

Table 6-12 Mode 1 Port C Bit Descriptions (Cont)

Bit	Name	Direction	Function
0	INTRB	Read Only	If Port B Mode 1 Input: A "1" indicates Port B has valid input data. It is set by STBB (PC2 being pulsed low and is reset by the processor reading the port data. INTRB is enabled when INTEB is "1" and disabled when it is "0".
			If Port B Mode 1 Output: A "1" indicates the port is ready to accept new output data. It is set by ACKB (PC2) being pulsed low and reset by the processor writing new output data to the port. Enabled and disabled as above.
			This signal is also an output to the external device on PC0.

*Bit is written by using the Control Word Bit set/reset function described in the Control Word section.

NOTE

If OBF is asserted low and a read or write access is made to the port by the processor before an ACK strobe is sent by the external device, the OBF line for the accessed port will negate during the assertion of the read or write to the port and become reasserted when the read or write operation is complete.

Table 6-13 Mode 1 Configuration

PPI Element	Input Conditions	Output Conditions	Program Control via Port C
Port A	M66 to M65	M66 to M60	N/A
Port B	M59 to M65	M59 to M60	M59 to M64 or M63
PC7	Never an Input	Output Buffer A Full	
PC6	M62 to M64 (Acknowledge A)*	Never an External Output	
PC5	Never an Input	Input Buffer A Full	
PC4	M61 to M63 (Strobe A)	Never an External Output	
PC3	Never an Input	Interrupt A (Vector 134)	
PC2	Strobe B in Input Mode. Acknowledge B in Output Mode	Never an Output	
PC1	Never an Input	Buffer B Full on Input or Output	
PC0	Never an Input	Interrupt B (Vector 130)	

*User's hardware acknowledges receipt of data output by port A.

Control signals are defined in Table 6-14. The port C bit assignments as used in mode 2 are described by Figure 6-8 and tabulated in Table 6-15. Finally, Table 6-16 links operation of mode 2 to the jumper configurations discussed in Chapter 2.

6.2.3 Control Word Register

The Control Word register controls the operation of the parallel interface. If bit 7 is set (active high), the contents of the register determines the mode of operation and the Input/Output direction of the ports. If bit 7 is cleared (active low), the contents of the register will set/reset the Port C register bits. The functions of the register bits are described in Table 6-17, and determined by the state (active high or active low) of the bit.

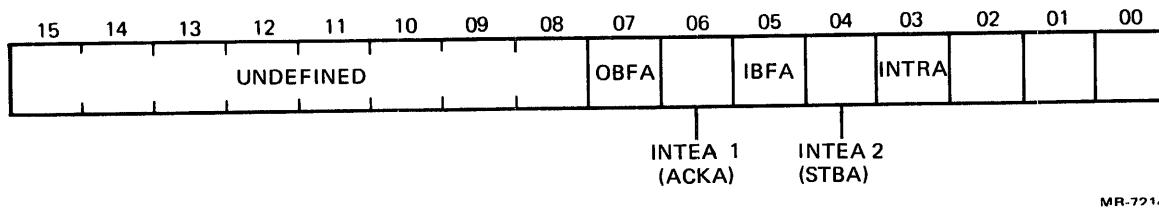


Figure 6-8 Mode 2 Port C Bit Assignments

Table 6-14 Port C Control Signals in Mode 2

Signal	Abbrev/Port C Bit	Function
Interrupt Request	INTR _A /PC3	A high on this output can interrupt the CPU for both input and output operations.
Output Buffer Full	OBF _A /PC7	This output goes low to indicate that the CPU has written data to port A.
Acknowledge	ACK _A /PC6	A low on this input enables the output tristate buffers of port A to send out the data. Otherwise that buffer is in the high impedance state.
Interrupt Enable	INTEA1/PC6	Enables INTR when OBF is true. Controlled by bit set/reset of PC6.
Strobe Input	STB _A /PC4	A low on this input loads data into the input latch.
Input Buffer Full	IBF _A /PC5	A high on this output indicates that data has been loaded into the input latch.
Interrupt Enable	INTEA2/PC4	Enables INTR when IBF is true. Controlled by bit set/reset of PC4.

Table 6-15 Mode 2 Port C Bit Descriptions

Bit	Name	Direction	Function
8-15	Undefined	-	Not valid. If a read is done on the entire word.
7	OBFA	Read Only	Will go low to indicate that the processor has written output data to the port. It is set when ACKA (PC6 M64 to M62) goes low indicating the external device has accepted the data. This signal is output on PC7 to the external device.
6	INTEA1	Read/Write*	When this bit is set it allows an interrupt INTA when the output buffer is ready to accept new data.
5	IBFA	Read Only	IBFA indicates that input data has been latched when a "1". This bit is reset when the processor reads the input data. This signal is output on PC5 to the external device.
4	INTEA2	Read/Write*	When this bit is set it allows an interrupt INTA when the input buffer is full.
3	INTA	Read Only	A high on this bit indicates that the port is requesting service of the processor. This signal is output on PC3 to the external device.
2-0	PC0-PC2	-	These bits are defined by Port B mode selection.

NOTE

When using Port A in mode 2 operation the software must clear the input buffer of Port A if the input buffer full flag (IBFA) is set before it performs the read during an intended write to ensure that the handshake lines and port flags are not set out of sequence.

Table 6-16 Mode 2 Configuration

PPI Element	Input Conditions	Output Conditions
Port A	Bidirectional bus	M66 to M64 to M62
Port B	Hardwired only	Hardwired only
PC7	Never an Input	Output Buffer A Full
PC6	Acknowledge A	Never an Output
PC5	Never an Input	Input Buffer A Full
PC4	Strobe A (M61 to M63)	Never an Output
PC3	Never an Input	Interrupt A (Vector 134)
PC2	Always an Input	Never an Output
PC1	Never an Input	Always an Output
PC0	Never an Input	Always an Output

Table 6-17 Control Register Mode Selection Bit Functions

Bit	Bit Set	Bit Reset
8-15	Unused	Unused
7	Always set	Always set
6	Port A Mode 2	Port A mode 0 or 1
5	Port A Mode 1	Port A Mode 0
4	Port A input	Port A output
3	Port C bits 4 and 6 are inputs	Port C 4--7 are outputs
2	Port B Mode 1	Port B Mode 0
1	Port B input	Port B output
0	Port C bit 2 input	Port C bits 0, 1 and 3 outputs

6.2.3.1 Mode Selection -- The user determines the mode of operation for the ports and defines them as inputs, outputs or bidirectional. The user then must insure that the bidirectional buffers are configured (See Chapter 2) to match the software requirements. Table 6-18 lists all the control words available for the Control Word register. The user selects the control word that matches the requirements and loads it into the register. The register is defined as "write only" and any attempts to read the register results in erroneous data.

6.2.3.2 Setting Bits in Port C -- The control word register is also used to set or reset the Port C register bits. The control word bit functions are described in Table 6-19. To set a bit the

Table 6-18 Control Words for Mode Selection

	Port B Mode 0 IN	Port B Mode 0 OUT	Port B Mode 1 IN	Port B Mode 1 OUT	Port C PC4,PC6	Port C PC5,PC7
Port A Mode 0 IN	233	231	237	235	INPUT	
	233	221	227	225		OUTPUT
Port A Mode 0 OUT	213	211	217	215	INPUT	
	203	201	207	205		OUTPUT
Port A Mode 1 IN	273	271	277	275	INPUT	
	263	261	267	265		OUTPUT
Port A Mode 1 OUT	253	251	257	255	INPUT	
	243	241	247	245		OUTPUT
Port A Mode 2	3X3	3X1	3X7	3X5	*	

* Port C Unavailable, Used for handshaking

X = Don't care condition

Table 6-19 Control Register Bit Set/Reset Bit Functions

Bit	Function
8-15	Not used
7	Always reset
6,5,4	Not used
3,2,1	These bits select the Port C bit that is to be set or reset as follows.
	Bit 03 02 01
	PC0 0 0 0 PC1 0 0 1 PC2 0 1 0 PC3 0 1 1 PC4 1 0 0 PC5 1 0 1 PC6 1 1 0 PC7 1 1 1
0	This bit is set to set the selected bit or is cleared to reset the selected bit of Port C.

register is loaded with bit 7 cleared, bits 1--3 equal to the bit number being set and bit 0 set. To reset the same bit, bit 0 would be cleared. The bit set/reset can be used to enable or disable the Port A and B interrupts for the SBC-11/21. The control words used to enable or disable the interrupts are listed in Table 6-20.

Table 6-20 Interrupt Set/Reset Control Words

Mode	Direction	INTRA		INTRB	
		Enable	Disable	Enable	Disable
1	Input	011	010	005	004
1	Output	015	014	005	004
2	Input	011	010	None*	None*
2	Output	015	014	None*	None*

*Port B does not function in the bidirectional Mode 2.

6.2.4 Parallel I/O Initialization

During Power up or the execution of a RESET instruction, the Port C data lines are driven high and the LED (driven by bit 7 of port C) is turned off. If Ports A and B bidirectional buffers are hardwired, the directions are not altered and the data lines are driven high if the buffer is configured as an output. If Ports A and B bidirectional buffers are program controlled by Port C, the data lines will go to the input state.

6.2.5 Parallel I/O Handshaking

The Parallel I/O can operate in either mode 0, 1 or 2 to transfer data into or out of the SBC-11/21. The mode 0 data transfers do not require any handshaking control signals. The mode 0 input data is not latched and data should be available on the I/O connector at the same time as the read strobe enables the 8255A-5. The mode 0 output data is latched and data is valid at the I/O connector 362 nsec after the trailing edge of the WRITE strobe to the 8255A-5.

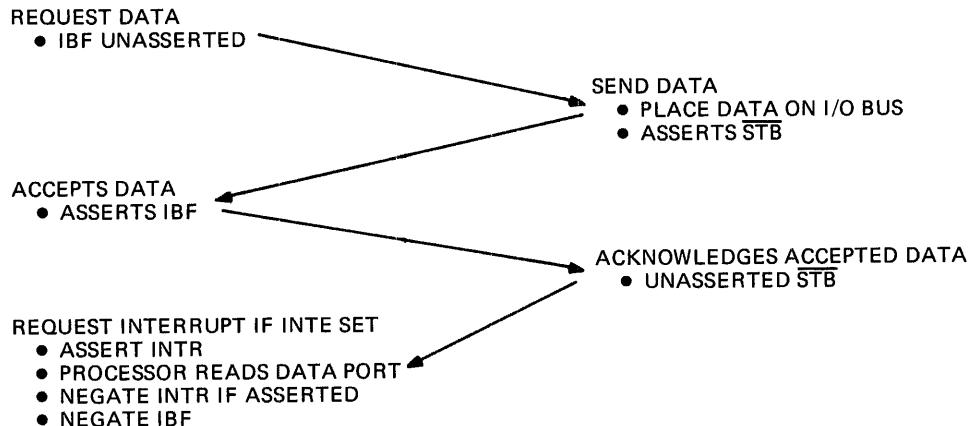
The handshaking signals which pass across the user interface are detailed as follows. Mode 1 operation requires the handshaking control signals and these are dependent upon defining the ports as inputs or outputs. Mode 1 input signals are listed in Table 6-21 and the handshaking function is shown in Figure 6-9. Mode 1 input timing is described in Figure 6-10. Mode 1 output signals are listed in Table 6-22 and the handshaking function is shown in Figure 6-11. Mode 1 output timing is described for Port A in Figure 6-12 and Port B in Figure 6-13. Mode 2 operation allows Port A to be bidirectional and the handshaking signals are listed in Table 6-23. Mode 2 timing is described in Figure 6-14. When Port A operates in mode 2, Port B can only operate in mode 0 or mode 1.

Table 6-21 Mode 1 Input Handshaking Signals

Signal Name	Function
STB (A or B) Port A - PC4 Port B - PC2	Strobe Input - This signal is asserted low by the external device and loads data into the SBC-11/21 input port latch. It must be asserted low for 525 ns minimum.
IBF (A or B) Port A - PC5 Port B - PC1	Input Buffer Full - This signal is asserted by the SBC-11/21 in response to an assertion of STB to notify the interface that data was loaded into the input latch.
INTR (A or B) Port A - PC3 Port B - PC0	Interrupt Request - This signal can be used to generate an interrupt to the microprocessor. The bitset/bitreset commands must be used to enable/disable the INTE bit for each port. Interrupts will be generated either when STB is negated with IBF asserted.

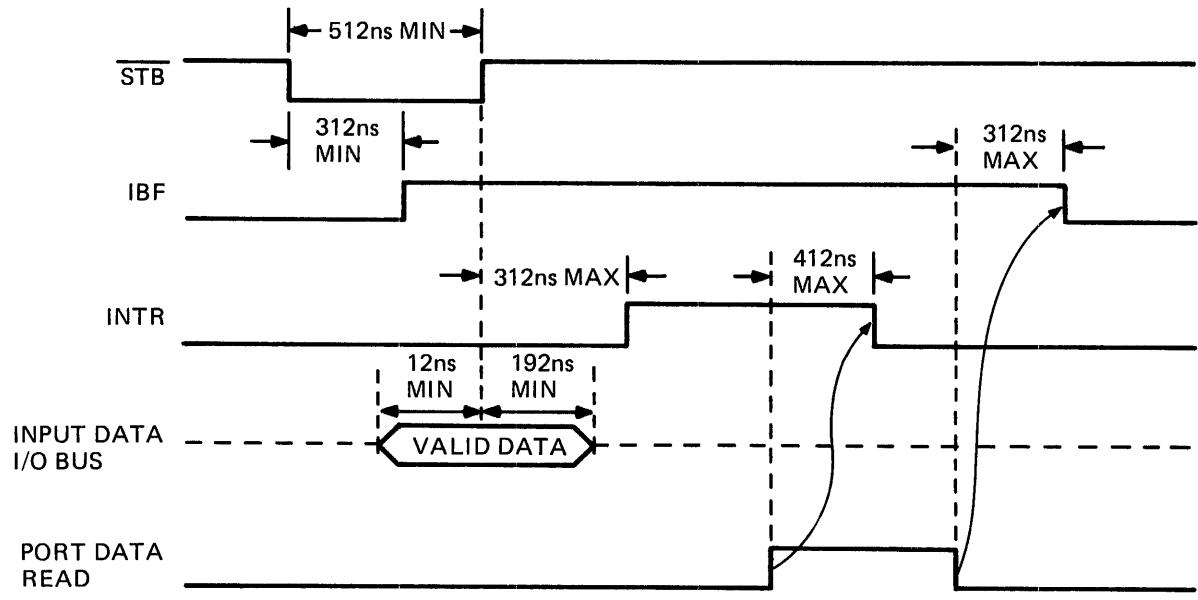
SBC-11/21

EXTERNAL DEVICE



MR-7216

Figure 6-9 Mode 1 Input Data Handshaking Sequence

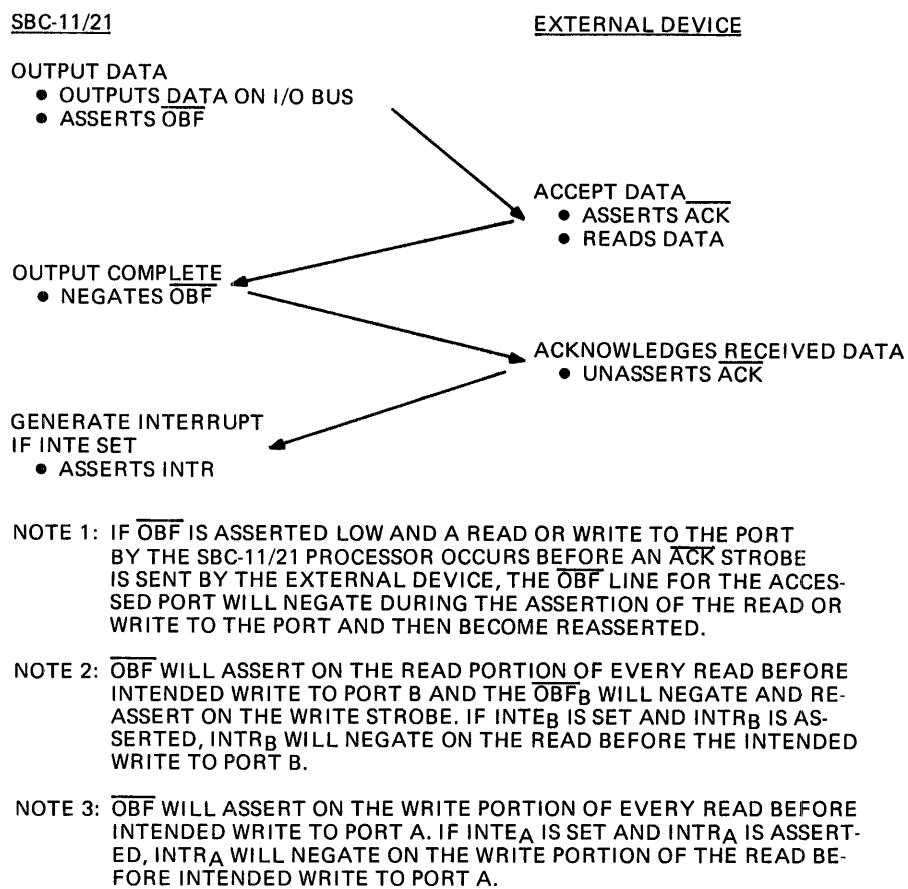


MR-7217

Figure 6-10 Mode 1 Strobed Input Timing

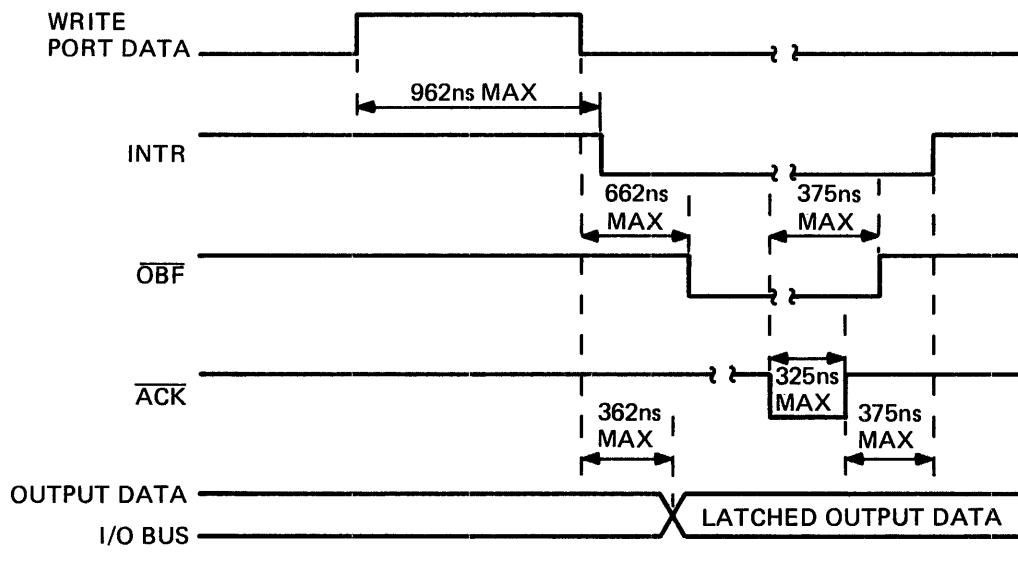
Table 6-22 Mode 1 Output Handshaking Signals

Signal Name	Function
<u>OBF</u> (A or B)	Output Buffer Full - This output is asserted low to indicate that the microprocessor has written data into the specified port latches.
Port A - PC7 Port B - PC1	
<u>ACK</u> (A or B)	Acknowledge Input - This signal is asserted low by the external device to indicate it has accepted the latched output data from the specified port.
Port A - PC6 Port B - PC2	
INTR (A or B)	Interrupt Request - This signal can be used to generate an interrupt to the microprocessor when the external device has received the data and INTE is set and ACK is negated.
Port A - PC3 Port B - PC0	



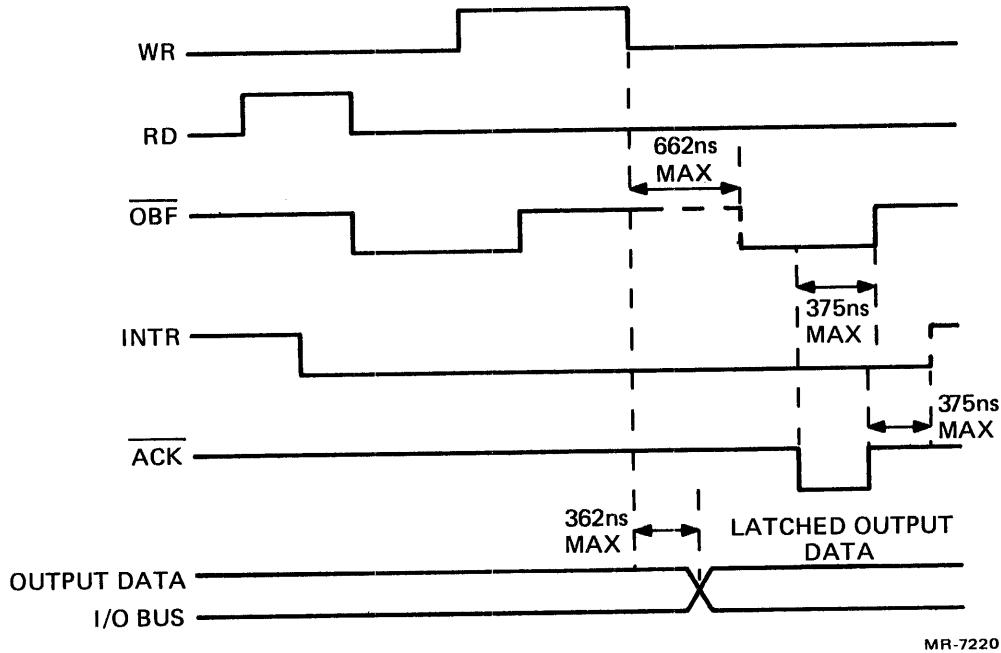
MR-7218

Figure 6-11 Mode 1 Output Data Handshaking Sequence



MR-7219

Figure 6-12 Mode 1 Strobed Output Timing



MR-7220

Figure 6-13 Mode 1 Port B Strobed Output Timing

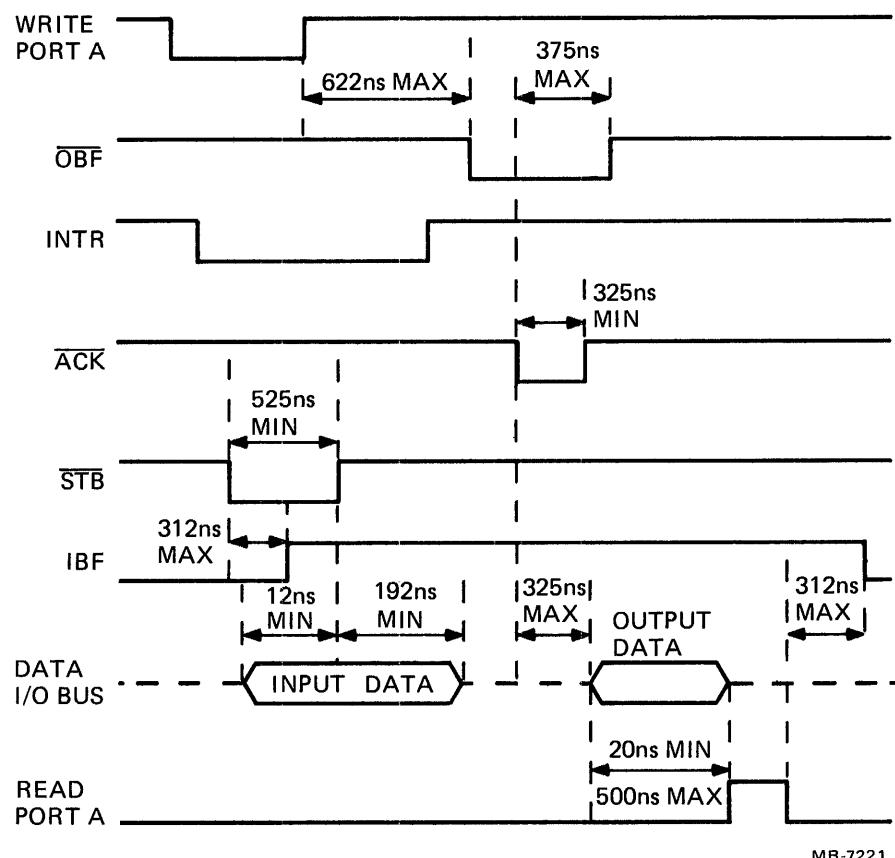
Table 6-23 Mode 2 Bidirectional Handshaking Signals

Signal Name	Function
STB (PC4)	Strobe Input - This signal is asserted low by the external device and strobes data into Port A.
IBF (PC5)	Input Buffer Full - This signal is asserted when the microprocessor has accepted STB strobe.
INTR (PC3)	Interrupt Request - This signal can be used to generate an interrupt to the microprocessor when the external device is demanding service.
OBF (PC7)	Output Buffer Full - This output is asserted to indicate that the microprocessor has written data into the output port latches.
ACK (PC6)	Acknowledge Input - This signal is asserted low by the external device to indicate it has taken data from the output port latches. It controls the DIR pin of the port A buffer.

NOTE

When mode 2 is configured, PC6 (ACK) is jumpered to the port A direction control pin through a rising edge delay circuit. Hence, when PC6 is negated, the rising edge is delayed by 250 ns minimum, which means that the buffer will be driving data out the connector 250 ns minimum after the user interface negates ACK.

Since every write is preceded by a read, the contents of the input buffer should be saved if IBF_A is asserted prior to writing port A mode 2 data.



MR-7221

Figure 6-14 Mode 2 Port A Bidirectional Timing

CHAPTER 7

ADDRESSING MODES AND INSTRUCTION SET

7.0 GENERAL

The discussion of addressing modes is divided into six major topics:

- o Single Operand Addressing -- One part of the instruction word specifies the registers; the remaining part provides information for locating the operand.
- o Double Operand Addressing -- Part of the instruction word specifies the registers; the remaining parts provide information for locating two operands.
- o Direct Addressing -- The operand is the content of the selected register.
- o Deferred (Indirect) Addressing -- The contents of the selected register is the address of the operand.
- o Use of the PC as a General Purpose Register -- The PC is unique from other general-purpose registers in one important respect. Whenever the processor retrieves an instruction, it automatically advances the PC by 2. By combining this automatic advancement of the PC with four of the basic addressing modes, we produce the four special PC modes -- immediate, absolute, relative, and relative deferred.
- o Use of the Stack Pointer as a General Purpose Register -- Can be used for stack operations.

These addressing modes will now be discussed in detail, followed by descriptions of individual instructions.

NOTE

Instruction mnemonics and address mode symbols are sufficient for writing assembly language programs. The programmer need not be concerned about conversion to binary digits; this is accomplished automatically by the assembler program.

7.1 ADDRESSING MODES

Data stored in memory must be accessed and manipulated. Data handling is specified by an SBC-11/21 instruction (MOV, ADD, etc.), which usually indicates:

- o The function (operation code).

- o A general-purpose register to be used when locating the source operand and/or a general-purpose register to be used when locating the destination operand.
- o An addressing mode (to specify how the selected register(s) is/are to be used).

A large portion of the data handled by a computer is usually structured (in character strings, arrays, lists, etc.). SBC-11/21 addressing modes provide for efficient and flexible handling of structured data.

The general registers may be used with an instruction in any of the following ways.

- o As accumulators. The data to be manipulated resides within the register.
- o As pointers. The contents of the register is the address of the operand, rather than the operand itself.
- o As pointers which automatically step through memory locations. Automatically stepping forward through consecutive locations is known as autoincrement addressing; automatically stepping backward is known as autodecrement addressing. These modes are particularly useful for processing tabular or array data.
- o As index registers. In this instance, the contents of the register and the word following the instruction are summed to produce the address of the operand. This allows easy access to variable entries in a list.

An important microprocessor feature, which should be considered in conjunction with the addressing modes, is the register arrangement.

- o Six general-purpose registers (R0--R5)
- o A hardware Stack Pointer (SP) register (R6)
- o A Program Counter (PC) register (R7)

Registers R0 through R5 are not dedicated to any specific function; their use is determined by the instruction that is decoded.

- o They can be used for operand storage. For example, contents of two registers can be added and stored in another register.
- o They can contain the address of an operand or serve as pointers to the address of an operand.
- o They can be used for the autoincrement or autodecrement features.
- o They can be used as index registers for convenient data and program access

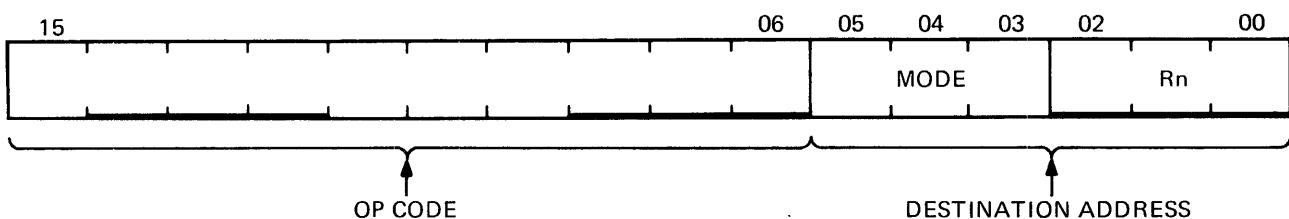
The SBC-11/21 also has instruction addressing mode combinations that facilitate temporary data storage structures. This can be used for convenient handling of data that must be accessed frequently. This is known as stack manipulation. The register used to keep track of stack manipulation is known as the stack pointer (SP). Any register can be used as a "stack pointer" under program control; however, certain instructions associated with subroutine linkage and interrupt service automatically use register R6 as a "hardware stack pointer". For this reason, R6 is frequently referred to as the "SP".

- o The stack pointer (SP) keeps track of the latest entry on the stack.
- o The stack pointer moves down as items are added to the stack and moves up as items are removed. Therefore, it always points to the top of the stack.
- o The hardware stack is used during trap or interrupt handling to store information allowing the processor to return to the main program.

Register R7 is used by the processor as its program counter (PC). It is recommended that R7 not be used as a stack pointer or accumulator. Whenever an instruction is fetched from memory, the program counter is automatically incremented by two to point to the next instruction word.

7.1.1 Single Operand Addressing

The instruction format for all single operand instructions (such as clear, increment, test) is:



MR-5458

Figure 7-1 Single Operand Addressing

Bits 15 through 6 specify the operation code that defines the type of instruction to be executed.

Bits five through zero form a six-bit field called the destination address field. This consists of two subfields.

- o Bits zero through two specify which of the eight general-purpose registers is to be referenced by this instruction word.

- o Bits three through five specify how the selected register will be used (address mode). Bit three is set to indicate deferred (indirect) addressing.

7.1.2 Double Operand Addressing

Operations which imply two operands (such as add, subtract, move, and compare) are handled by instructions that specify two addresses. The first operand is called the source operand, the second the destination operand. Bit assignments in the source and destination address fields may specify different modes and different registers. The instruction format for the double operand instruction is:

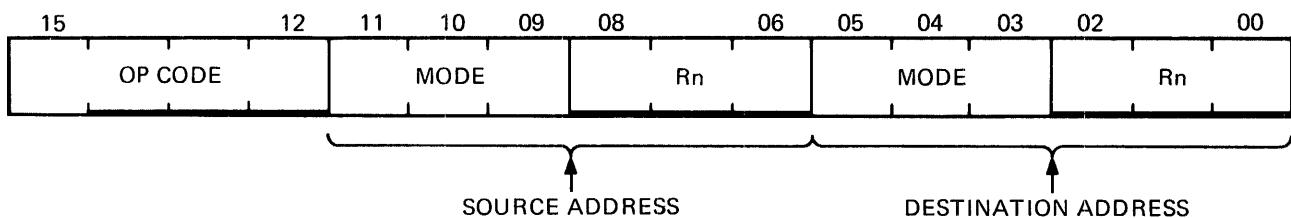


Figure 7-2 Double Operand Addressing

MR-5459

The source address field is used to select the source operand, the first operand. The destination is used similarly, and locates the second operand and the result. For example, the instruction ADD A, B adds the contents (source operand) of location A to the contents (destination operand) of location B. After execution B will contain the result of the addition and the contents of A will be unchanged.

Examples in this paragraph and chapter use the following sample SBC-11/21 instructions. A complete listing of the SBC-11/21 instructions is located in Paragraph 7.2.

Mnemonic	Description	Octal Code
CLR	Clear (zero the specified destination)	0050DD
CLRB	Clear byte (zero the byte in the specified destination)	1050DD
INC	Increment (add one to contents of destination)	0052DD
INCB	Increment byte (add one to the contents of destination byte)	1052DD

COM	Complement (replace the contents of the destination by its logical complement; each zero bit is set and each one bit is cleared)	0051DD
COMB	Complement byte (replace the contents of the destination byte by its logical complement; each 0 bit is set and each 1 bit is cleared).	1051DD
ADD	Add (add source operand to destination operand and store the result at destination address)	06SSDD

DD = destination field (six bits)

SS = source field (six bits)

() = contents of

7.1.3 Direct Addressing

The following table summarizes the four basic modes used with direct addressing.

DIRECT MODES

Mode	Name	Assembler Syntax	Function
0	Register	Rn	Register contains operand

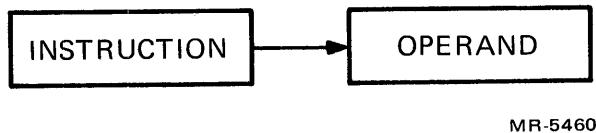


Figure 7-3 Mode 0 Register

2	Autoincrement (Rn)+	Register is used as a pointer to sequential data, then incremented
---	---------------------	--

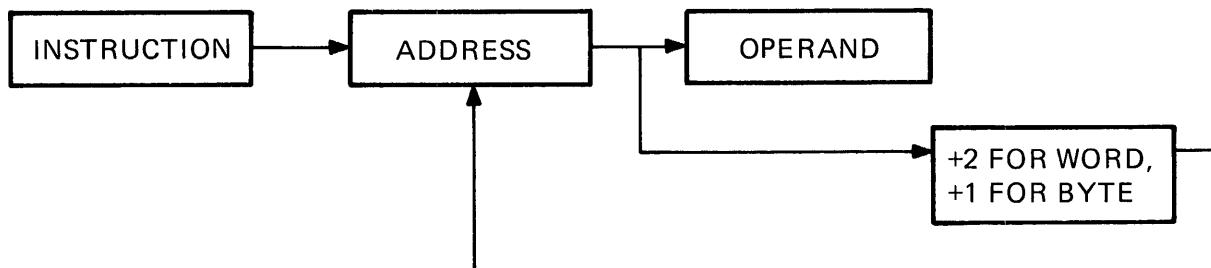
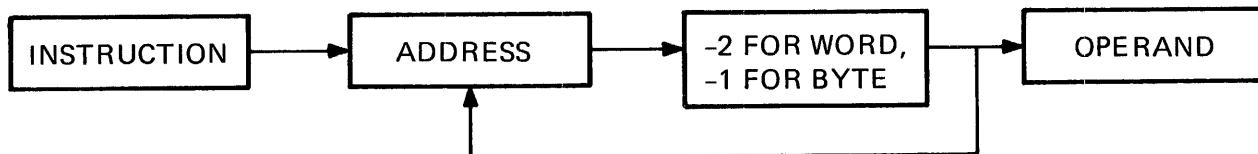


Figure 7-4 Mode 2 Autoincrement

4 Autodecrement -(Rn)

Register is decremented and then used as a pointer.



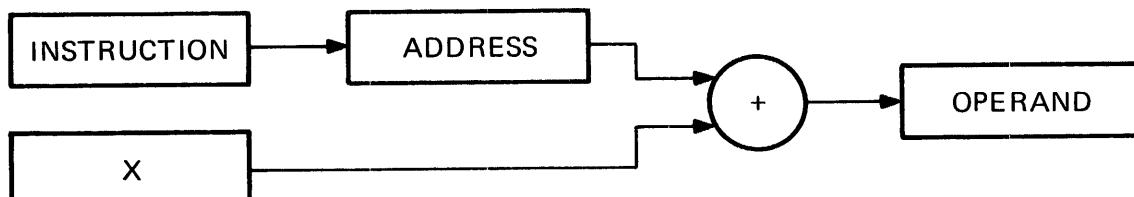
MR-5462

Figure 7-5 Mode 4 Autodecrement

6 Index

X(Rn)

Value X is added to (Rn) to produce address of operand. Neither X nor (Rn) is modified.



MR-5463

Figure 7-6 Mode 6 Index

7.1.3.1 Register Mode -- With register mode any of the general registers may be used as simple accumulators and the operand is contained in the selected register. Since they are hardware registers, within the processor, the general registers operate at high speeds and provide speed advantages when used for operating on frequently-accessed variables. The assembler interprets and assembles instructions of the form OPR Rn as register mode operations. Rn represents a general register name or number and OPR is used to represent a general instruction mnemonic. Assembler syntax requires that a general register be defined as follows.

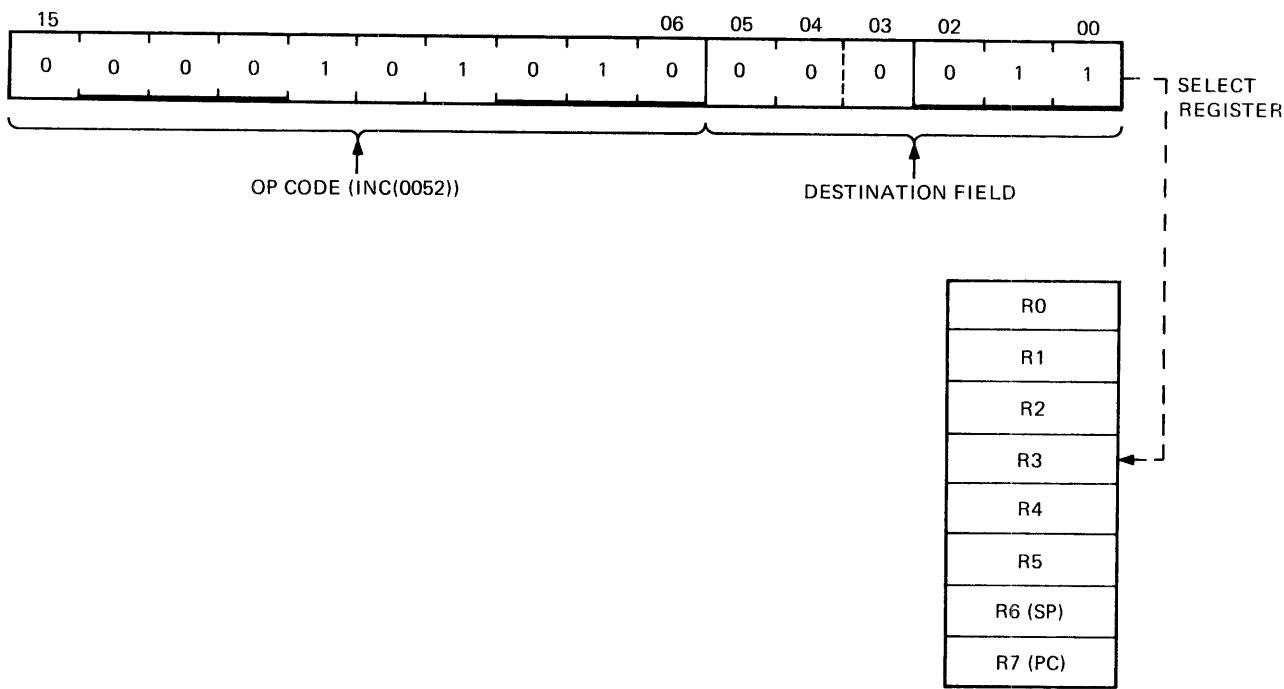
```
R0 = %0 (% sign indicates register definition)
R1 = %1
R2 = %2, etc.
```

Registers are typically referred to by name as R0, R1, R2, R3, R4, R5, R6, and R7. However, R6 and R7 are also referred to as SP and PC, respectively.

OPR Rn

Register Mode Examples
 (all numbers in octal)

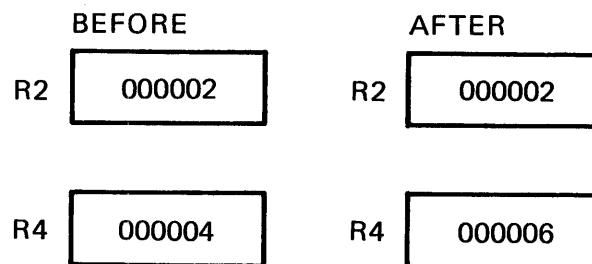
Symbolic	Octal Code	Instruction Name
1. INC R3	005203	Increment
Operation:	Add one to the contents of general purpose register R3.	



MR-5467

Figure 7-7 INC R3 Increment

2. ADD R2, R4	060204	Add
Operation:	Add the contents of R2 to the contents of R4.	



MR-5468

Figure 7-8 ADD R2, R4 Add

3. COMB R4

105104

Complement Byte

Operation:

One's complement bits 0--7 (byte) in R4. (When general registers are used, byte instructions only operate on bits 0--7; i.e., byte 0 of the register.)

	BEFORE	AFTER
R4	022222	022155

MR-5469

Figure 7-9 COMB R4 Complement Byte

7.1.3.2 Autoincrement Mode -- This mode provides for automatic stepping of a pointer through sequential elements of a table of operands. It assumes the contents of the selected general purpose register to be the address of the operand. Contents of registers are stepped (by one for bytes, by two for words, always by two for R6 and R7) to address the next sequential location. The autoincrement mode is especially useful for array processing and stack processing. It will access an element of a table and then step the pointer to address the next operand in the table. Although most useful for table handling, this mode is completely general and may be used for a variety of purposes.

OPR (Rn)+

Autoincrement Mode Examples

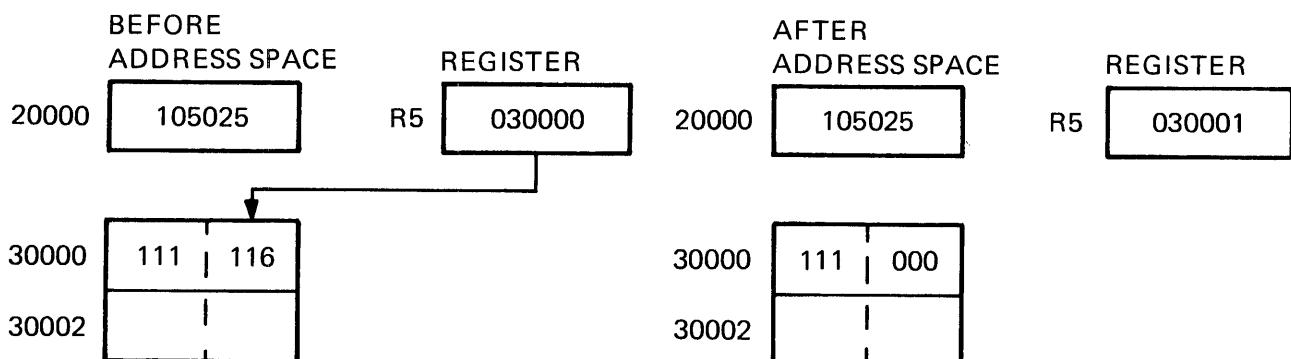
Symbolic	Octal Code	Instruction Name	
1. CLR (R5)+	005025	Clear	
Operation:	Use contents of R5 as the address of the operand. Clear selected operand and then increment the contents of R5 by two.		
BEFORE ADDRESS SPACE	REGISTER	AFTER ADDRESS SPACE	REGISTER
20000 005025	R5 030000	20000 005025	R5 030002
		30000 000000	

MR-5464

Figure 7-10 CLR (R5)+ Clear

2. CLRB (R5)+ 105025 Clear Byte

Operation: Use contents of R5 as the address of the operand. Clear selected byte operand and then increment the contents of R5 by one.

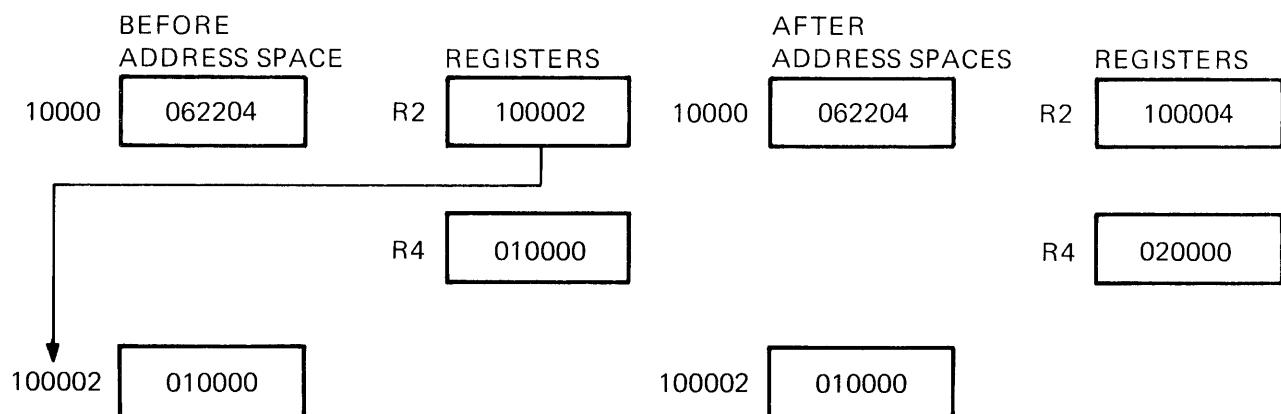


MR-5465

Figure 7-11 CLRB (R5)+ Clear Byte

3. ADD (R2)+,R4 062204 Add

Operation: The contents of R2 are used as the address of the operand which is added to the contents of R4. R2 is then incremented by two.



MR 5470

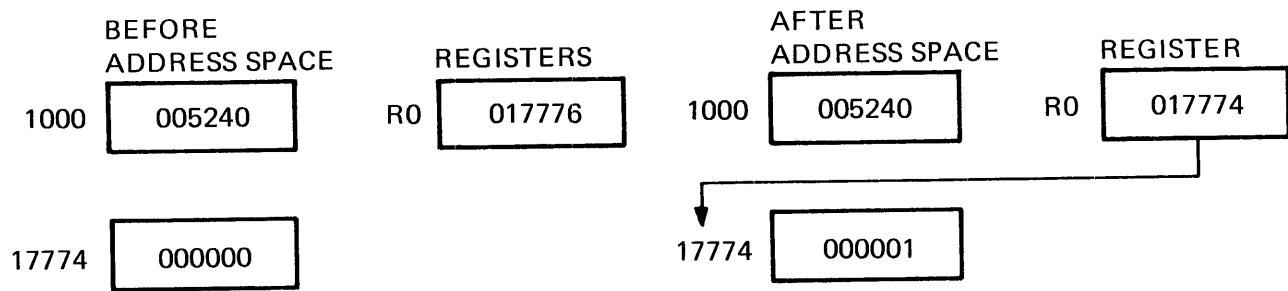
Figure 7-12 ADD (R2) + R4 Add

7.1.3.3 Autodecrement Mode (Mode 4) -- This mode is useful for processing data in a list in reverse direction. The contents of the selected general purpose register are decremented (by two for word instructions, by one for byte instructions) and then used as the address of the operand. The choice of postincrement, predecrement features for the SBC-11/21 were not arbitrary decisions, but were intended to facilitate hardware/software stack operations.

OPR- (Rn)

Autodecrement Mode Examples

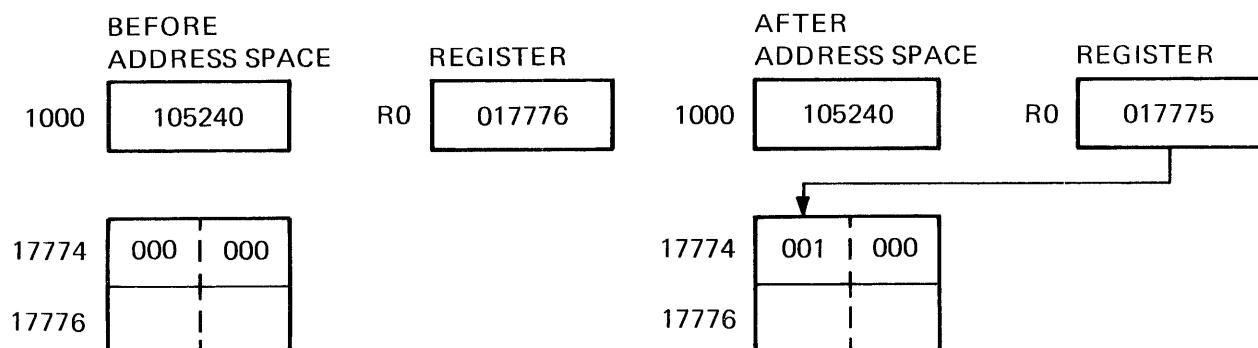
Symbolic	Octal Code	Instruction Name
1. INC -(R0)	005240	Increment
Operation:	The contents of R0 are decremented by two and used as the address of the operand. The operand is incremented by one.	



MR-5466

Figure 7-13 INC -(R0) Increment

2. INCB -(R0)	105240	Increment Byte
Operation:	The contents of R0 are decremented by one then used as the address of the operand. The operand byte is increased by one.	

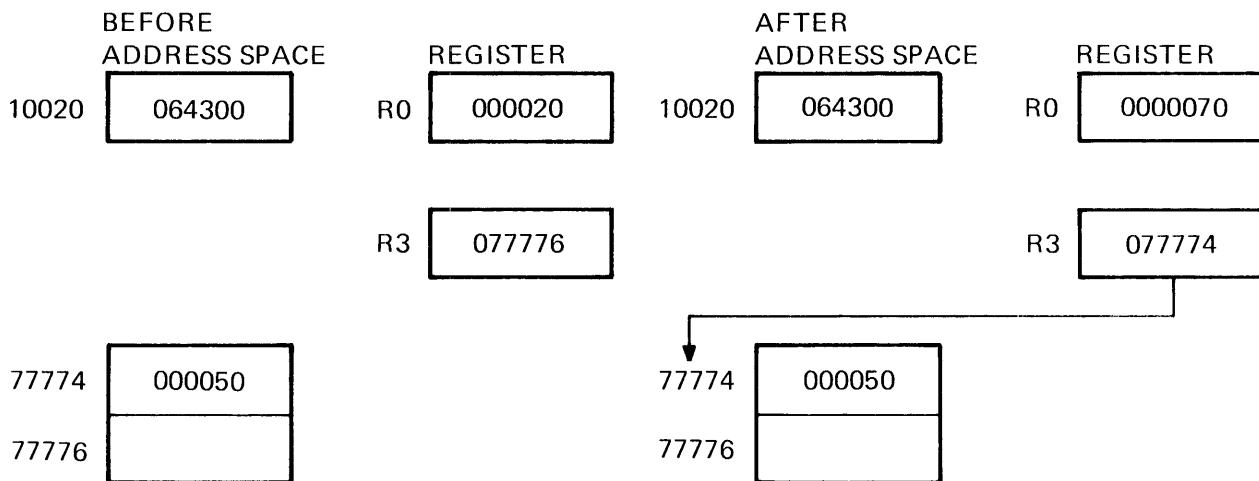


MR 5471

Figure 7-14 INCB -(R0) Increment Byte
7-10

3. ADD - (R3), R0 064300 Add

Operation: The contents of R3 are decremented by two then used as a pointer to an operand (source) which is added to the contents of R0 (destination operand).



MR 5472

Figure 7-15 ADD - (R3), R0 Add

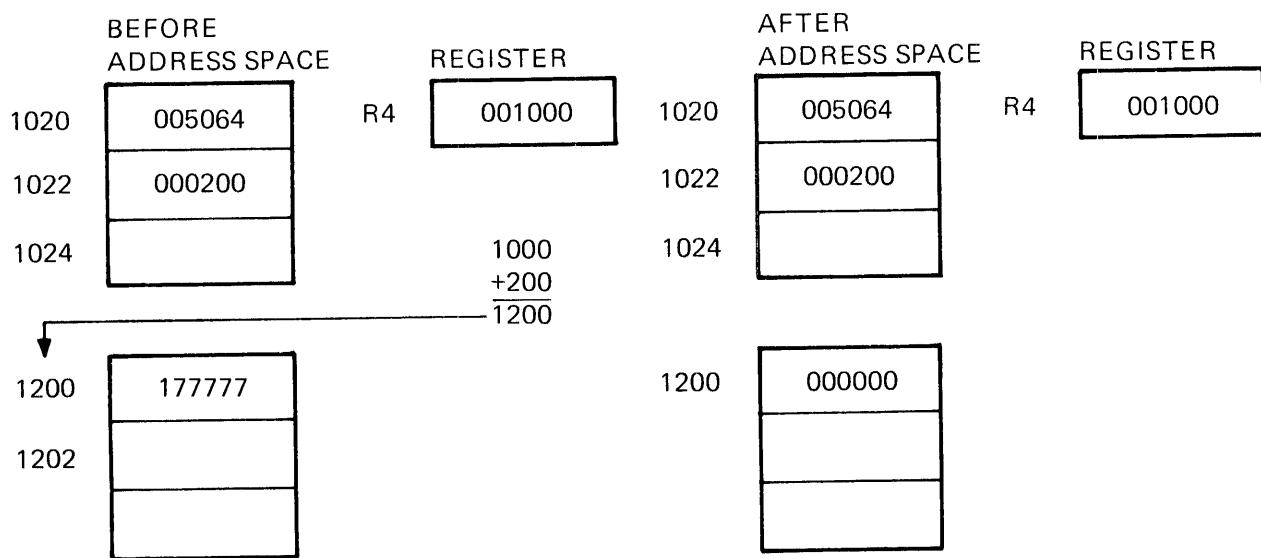
7.1.3.4 Index Mode (Mode 6) -- The contents of the selected general purpose register, and an index word following the instruction word, are summed to form the address of the operand. The contents of the selected register may be used as a base for calculating a series of addresses, thus allowing random access to elements of data structures. The selected register can then be modified by program to access data in the table. Index addressing instructions are of the form OPR X(Rn) where X is the indexed word and is located in the memory location following the instruction word and Rn is the selected general purpose register.

OPR X(Rn)

Index Mode Examples

Symbolic	Octal Code	Instruction Name
1. CLR 200(R4)	005064 000200	Clear

Operation: The address of the operand is determined by adding 200 to the contents of R4. The operand location is then cleared.

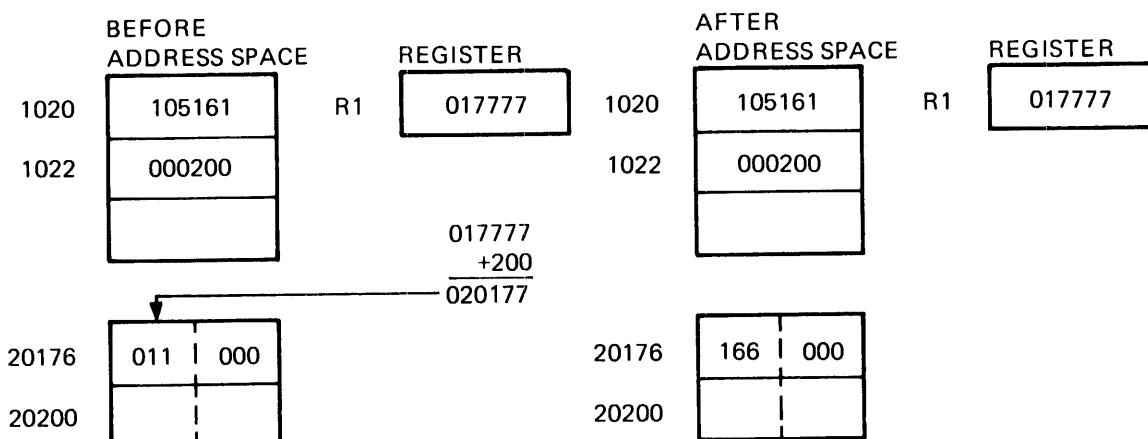


MR 5473

Figure 7-16 CLR 200 (R4) Clear

2. COMB 200(R1) 105161 Complement Byte
000200

Operation: The contents of a location which is determined by adding 200 to the contents of R1 are one's complemented (i.e., logically complemented).

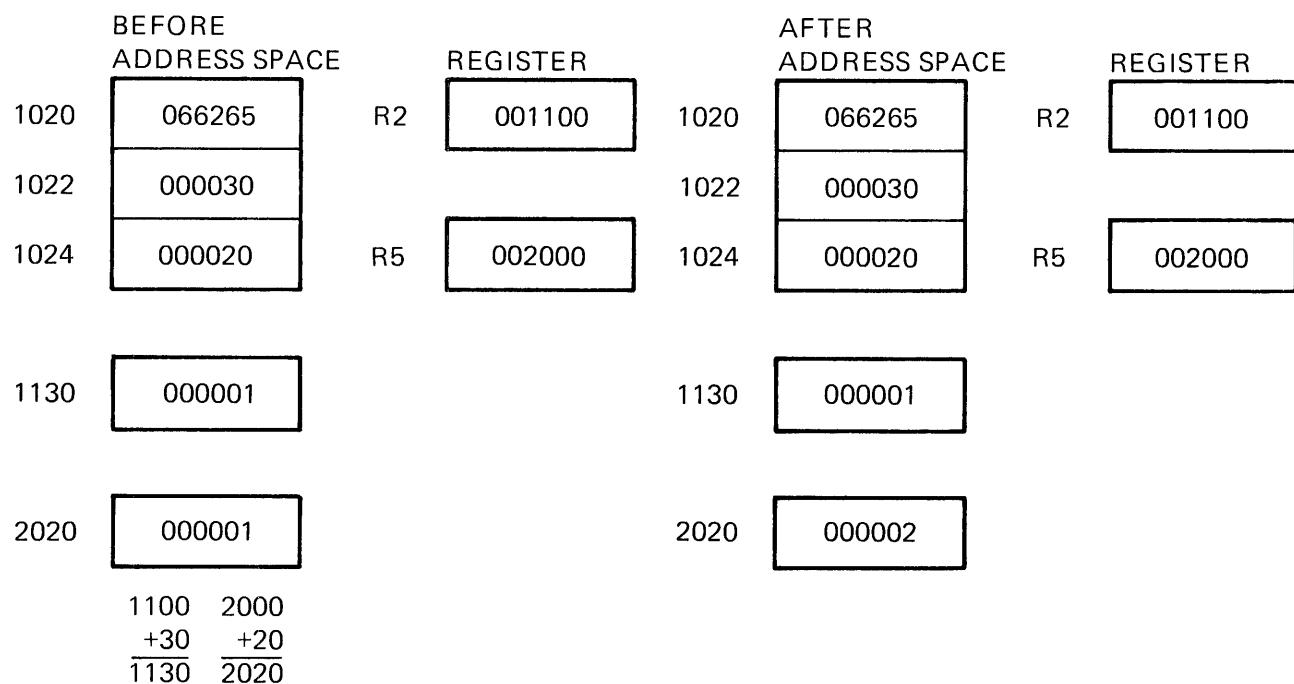


MR-7230

Figure 7-17 COMB 200 (R1) Complement Byte

3. ADD 30(R2),20(R5) 066265 Add
 000030
 000020

Operation: The contents of a location which is determined by adding 30 to the contents of R2 are added to the contents of a location which is determined by adding 20 to the contents of R5. The result is stored at the destination address, i.e., 20(R5).



MR-5475

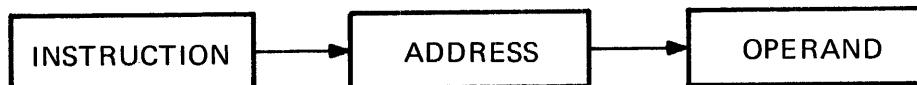
Figure 7-18 ADD 30 (R2), 20 (R5) Add

7.1.4 Deferred (Indirect) Addressing

The four basic modes may also be used with deferred addressing. Whereas in the register mode the operand is the contents of the selected register, in the register deferred mode the contents of the selected register is the address of the operand.

In the three other deferred modes, the contents of the register select the address of the operand rather than the operand itself. These modes are therefore used when a table consists of addresses rather than operands. Assembler syntax for indicating deferred addressing is "@" (or "(" when this is not ambiguous). The following table summarizes the deferred versions of the basic modes.

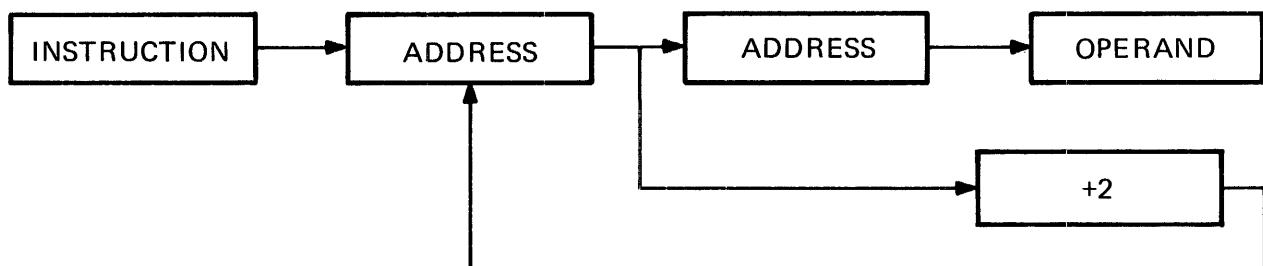
Mode	Name	Assembler Syntax	Function
1	Register Deferred	@Rn or (Rn)	Register contains the address of the operand.



MR-5476

Figure 7-19 Mode 1 Register Deferred

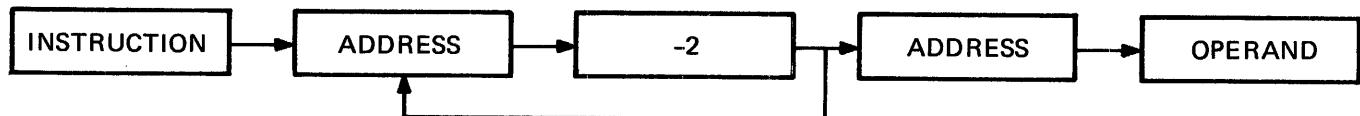
3	Autoincrement Deferred	$\@(\text{Rn}) +$	Register is first used as a pointer to a word containing the address of the operand, then incremented (always by two; even for byte instructions).
---	------------------------	-------------------	--



MR-5477

Figure 7-20 Mode 3 Autoincrement Deferred

5	Autodecrement Deferred	$\@-(\text{Rn})$	Register is decremented (always by two; even for byte instructions) and then used as a pointer to a word containing the address of the operand.
---	------------------------	------------------	---



MR-5478

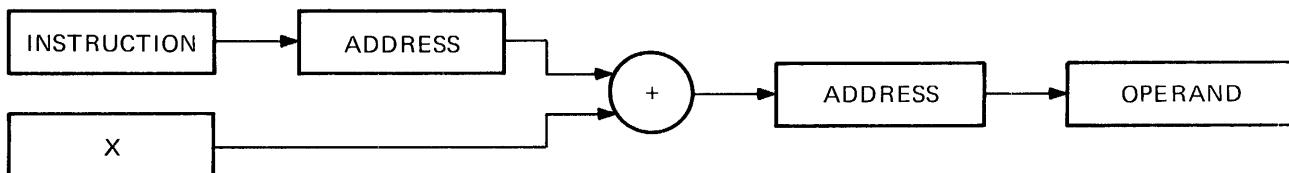
Figure 7-21 Mode 5 Autodecrement Deferred

7

**Index
Deferred**

@X(Rn)

Value X (stored in a word following the instruction) and (Rn) are added and the sum is used as a pointer to a word containing the address of the operand. Neither X nor (Rn) is modified.



MR-5479

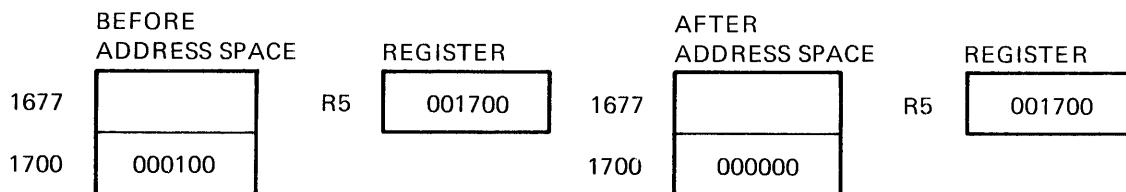
Figure 7-22 Mode 7 Index Deferred

The following examples illustrate the deferred modes.

Register Deferred Mode Example

Symbolic	Octal Code	Instruction Name
CLR @R5	005015	Clear

Operation: The contents of location specified in R5 are cleared.



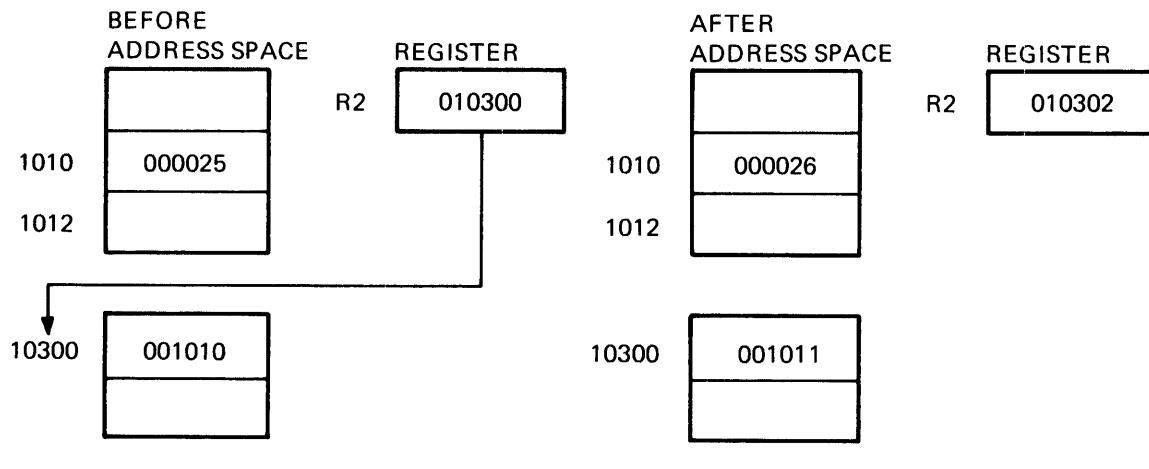
MR-5480

Figure 7-23 CLR @ R5 Clear

Autoincrement Deferred Mode Example (Mode 3)

Symbolic	Octal Code	Instruction Name
INC@(R2)+	005232	Increment

Operation: The contents of R2 are used as the address of the address of the operand. Operand is increased by one. Contents of R2 are incremented by two.



MR-7231

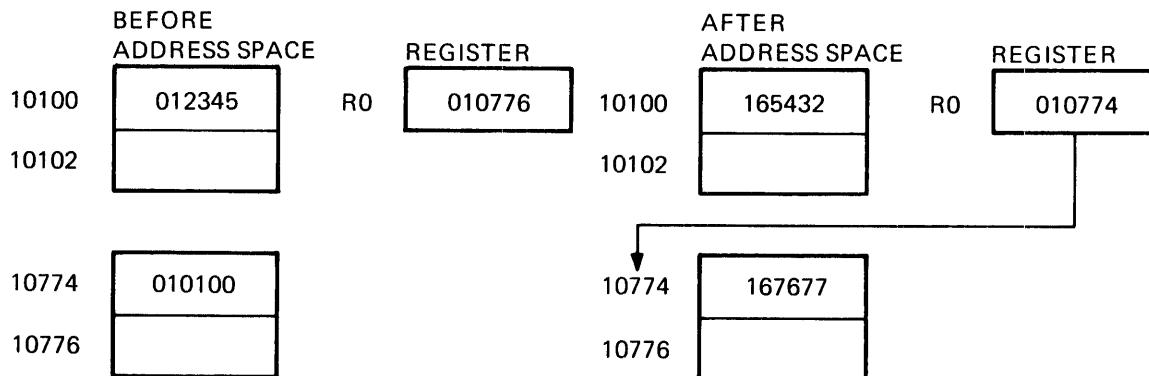
Figure 7-24 INC @ (R2) + Increment

Autodecrement Deferred Mode Example (Mode 5)

Symbolic	Octal Code	Complement
COM @- (R0)	005150	

Operation:

The contents of R0 are decremented by two and then used as the address of the operand. Operand is one's complemented (i.e., logically complemented).



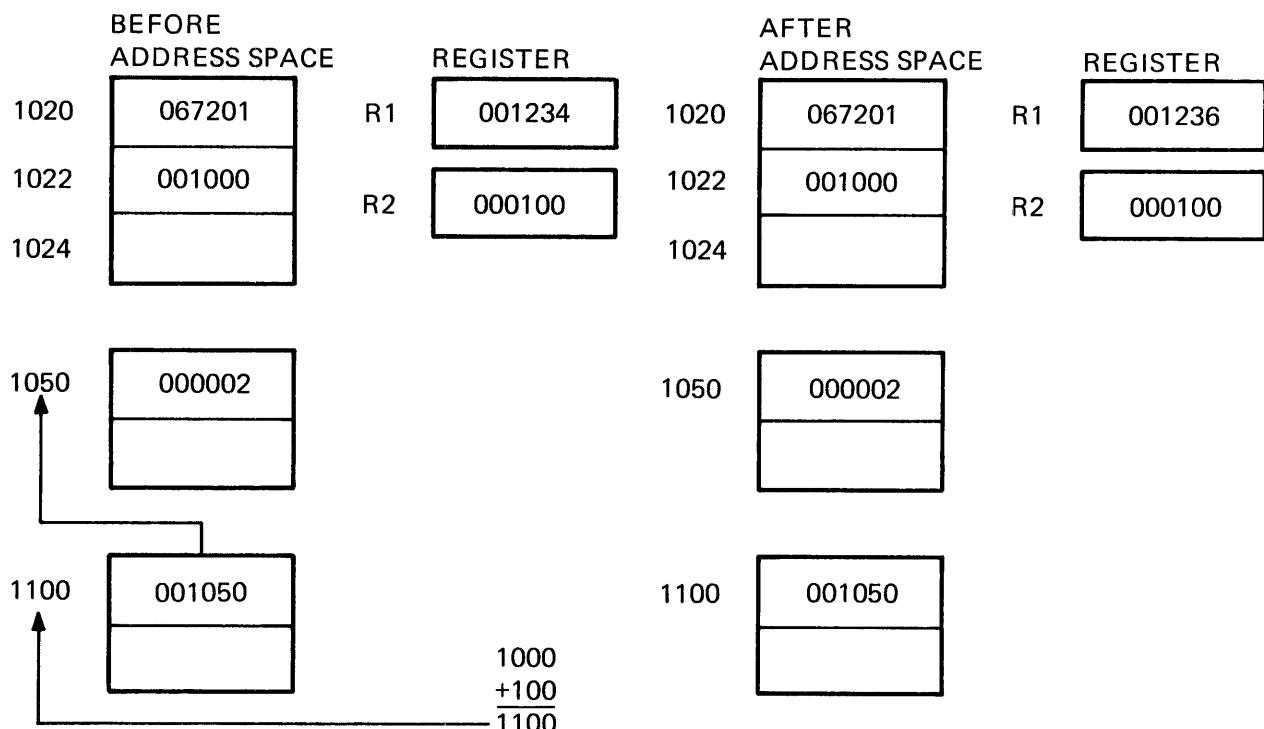
MR-7232

Figure 7-25 COM @-(R0) Complement

Index Deferred Mode Example (Mode 7)

Symbolic	Octal Code	Instruction Name
ADD @ 1000(R2), R1	067201 001000	ADD

Operation: 1000 and contents of R2 are summed to produce the address of the address of the source operand the contents of which are added to contents of R1; the result is stored in R1.



MR-5483

Figure 7-26 ADD @ 1000 (R2), R1 Add

7.1.5 Use of the PC as a General Register

Although register seven is a general purpose register, it doubles in function as the program counter for the microprocessor. Whenever the processor uses the program counter to acquire a word from memory, the program counter is automatically incremented by two to contain the address of the next word of the instruction being executed or the address of the next instruction to be executed. (When the program uses the PC to locate byte data, the PC is still incremented by two.)

The PC responds to all the standard SBC-11/21 addressing modes. However, there are four of these modes with which the PC can provide advantages for handling position independent code and unstructured data. When utilizing the PC these modes are termed immediate, absolute (or immediate deferred), relative and relative deferred, and are summarized below.

Mode	Name	Assembler Syntax	Function
2	Immediate	#n	Operand follows instruction.
3	Absolute	@#A	Absolute Address of operand follows instruction.
6	Relative	A	Relative Address (index value) follows the instruction.
7	Relative Deferred	@A	Index value (stored in the word following the instruction) is the relative address for the address of the operand.

When a standard program is available for different users, it often is helpful to be able to load it into different areas of memory and run it there. SBC-11/21 can accomplish the relocation of a program very efficiently through the use of position independent code (PIC) which is written by using the PC addressing modes. If an instruction and its operands are moved in such a way that the relative distance between them is not altered, the same offset relative to the PC can be used in all positions in memory. Thus, PIC usually references locations relative to the current location.

The PC also greatly facilitates the handling of unstructured data. This is particularly true of the immediate and relative modes.

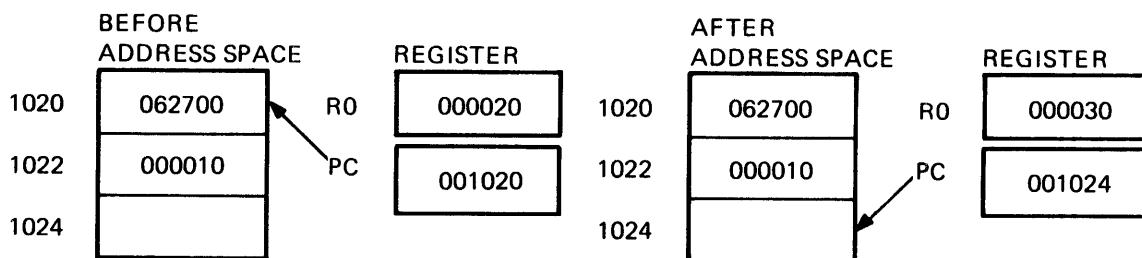
7.1.5.1 Immediate Mode -- Immediate mode is equivalent to using the autoincrement mode with the PC. It provides time improvements for accessing constant operands by including the constant in the memory location immediately following the instruction word.

OPR #n,DD

Immediate Mode Example

Symbolic	Octal Code	Instruction Name
ADD #10,R0	062700 000010	Add

Operation: The value 10 is located in the second word of the instruction and is added to the contents of R0. Just before this instruction is fetched and executed, the PC points to the first word of the instruction. The processor fetches the first word and increments the PC by two. The source operand mode is 27 (autoincrement the PC). Thus, the PC is used as a pointer to fetch the operand (the second word of the instruction) before being incremented by two to point to the next instruction.



MR-7233

Figure 7-27 ADD # 10, R0 Add

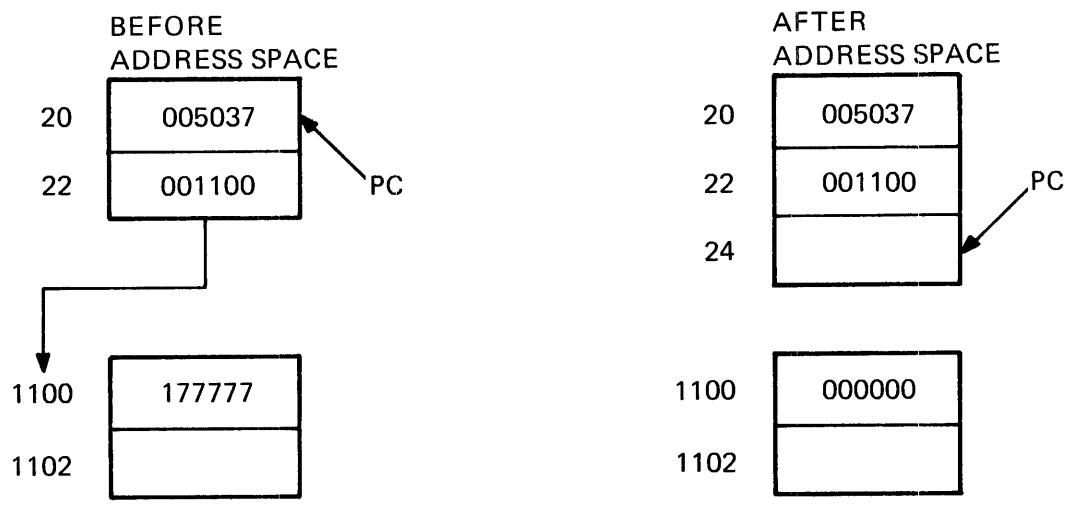
7.1.5.2 Absolute Addressing -- This mode is the equivalent of immediate deferred or autoincrement deferred using the PC. The contents of the location following the instruction are taken as the address of the operand. Immediate data is interpreted as an absolute address (i.e., an address that remains constant no matter where in memory the assembled instruction is executed).

OPR @ #A

Absolute Mode Examples

Symbolic	Octal Code	Instruction Name
1. CLR @ #1100	005037 001100	Clear

Operation: Clear the contents of location 1100.



MR-5485

Figure 7-28 CLR @ # 1100 Clear

2. ADD @ #2000,R3 063703
002000

Operation: Add contents of location 2000 to R3.



MR-7234

Figure 7-29 ADD @ # 2000 Add

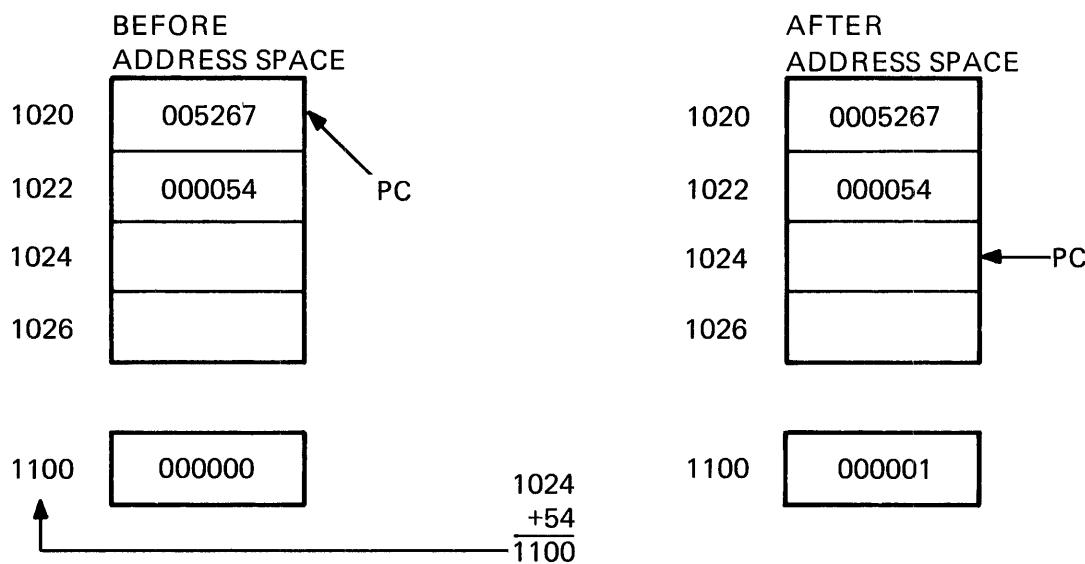
7.1.5.3 Relative Addressing -- This mode is assembled as index mode using R7. The base of the address calculation, which is stored in the second or third word of the instruction, is not the address of the operand, but the number which, when added to the (PC), becomes the address of the operand. This mode is useful for writing position independent code since the location referenced is always fixed relative to the PC. When instructions are to be relocated, the operand is moved by the same amount.

OPR A or OPR X (PC)
where X is the location of A relative to the instruction.

Relative Addressing Example

Symbolic	Octal Code	Instruction Name
INC A	005267 000054	Increment

Operation: To increment location A, contents of memory location immediately following instruction word are added to (PC) to produce address A. Contents of A are increased by one.



MR-5487

Figure 7-30 INC A Increment

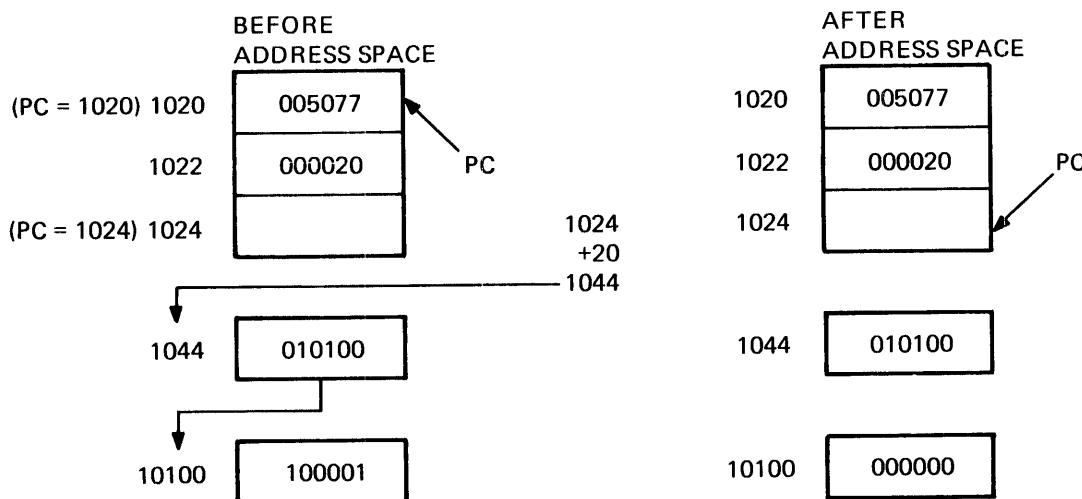
7.1.5.4 Relative Deferred Addressing -- This mode is similar to the relative mode, except that the second word of the instruction, when added to the PC, contains the address of the address of the operand, rather than the address of the operand.

OPR @A or OPR @X(PC)
where x is location containing address of A, relative to the instruction.

Relative Deferred Mode Example

Symbolic	Octal Code	Instruction Name
CLR @A	005077 000020	Clear

Operation: Add second word of instruction to updated PC to produce address of address of operand. Clear operand.



MR-7235

Figure 7-31 CLR @ A Clear

7.1.6 Use of Stack Pointer as General Register

The processor stack pointer (SP, register R6) is in most cases the general register used for the stack operations related to program nesting. Autodecrement with register R6 "pushes" data on to the stack and autoincrement with register R6 "pops" data off the stack. Since the SP is used by the processor for interrupt handling, it has a special attribute: autoincrements and autodecrements are always done in steps of two. Byte operations using the SP in this way leave odd addresses unmodified.

7.2 INSTRUCTION SET

The specification for each instruction includes the mnemonic, octal code, binary code, a diagram showing the format of the instruction, a symbolic notation describing its execution and the effect on the condition codes, a description, special comments, and examples.

MNEMONIC: This is indicated before each description. When the word instruction has a byte equivalent, the byte mnemonic is also shown.

INSTRUCTION FORMAT: A diagram accompanying each instruction shows the octal op code, the binary op code, and bit assignments. [Note that in byte instructions the most significant bit (bit 15) is always a one].

SYMBOLS:

() = contents of

SS or src = source address

DD or dst = destination address

loc = location

< = becomes

↑ = "is popped from stack"

Ψ = "is pushed onto stack"

Λ = boolean AND

∨ = boolean OR

⊻ = exclusive OR

~ = boolean not

Reg or R = register

B = Byte

0 for word

■ =

1 for byte

, = concatenated

7.2.1 Instruction Formats

The following formats include all instructions used in the SBC-11/21. Refer to individual instructions for more detailed information.

1. Single Operand Group (CLR, CLRB, COM, COMB, INC, INCB, DEC, DECB, NEG, NEGB, ADC, ADCB, SBC, SBCB, TST, TSTB, ROR, RORB, ROL, ROLB, ASR, ASRB, ASL, ASLB, JMP, SWAB, MFPS, MTPS, SXT, XOR)

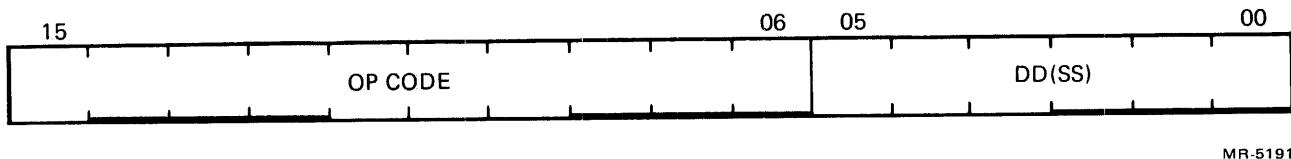


Figure 7-32 Single Operand Group

2. Double Operand Group (BIT, BITB, BIC, BICB, BIS, BISB, ADD, SUB, MOV, MOVB, CMP, CMPB)

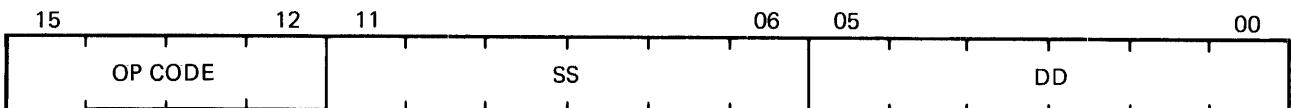


Figure 7-33 Double Operand Group

3. Program Control Group

- a. Branch (all branch instructions)

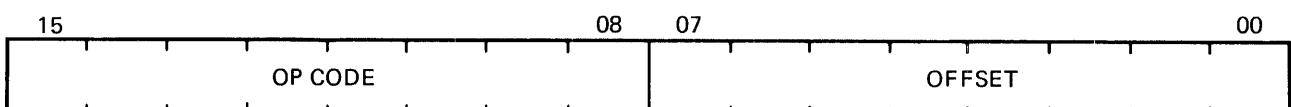


Figure 7-34 Program Control Group Branch

- b. Jump To Subroutine (JSR)

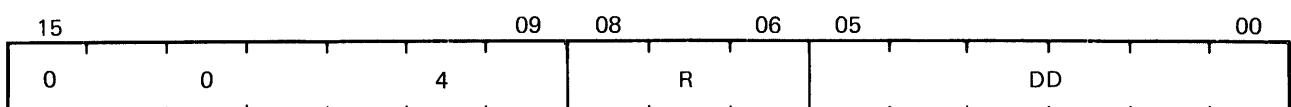
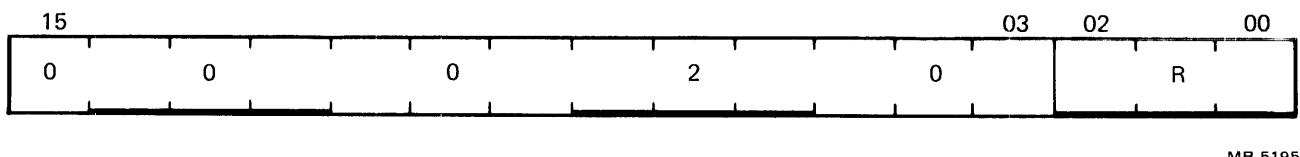


Figure 7-35 Program Control Group JSR

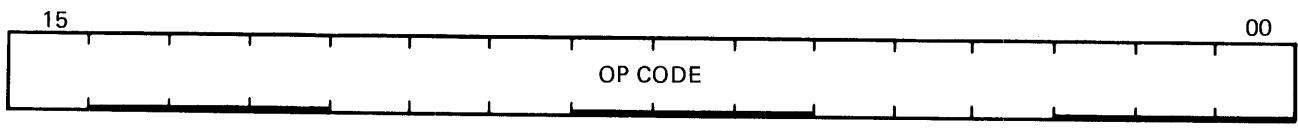
c. Subroutine Return (RTS)



MR-5195

Figure 7-36 Program Control Group (RTS)

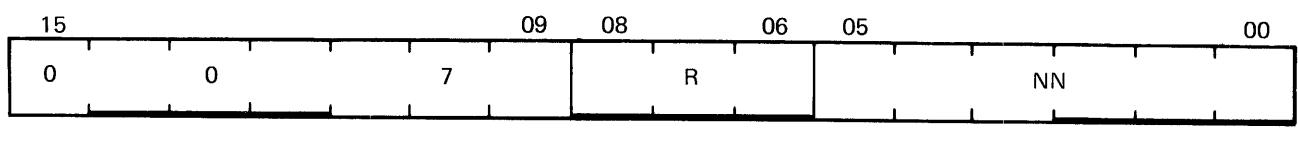
d. Traps (break point, IOT, EMT, TRAP, BPT)



MR-5196

Figure 7-37 Program Control Group Traps

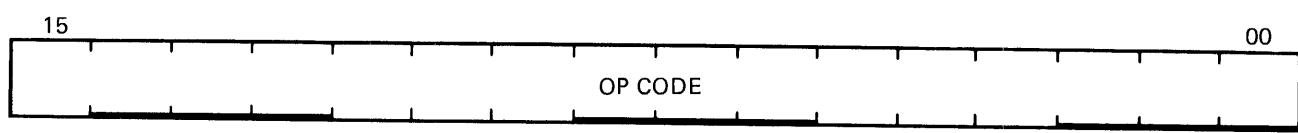
e. Subtract I and branch if = 0 (SOB)



MR-5197

Figure 7-38 Program Control Group Subtract

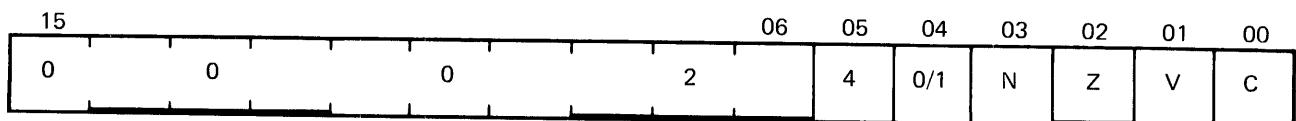
4. Operate Group (HALT, WAIT, RTI, RESET, RTT, NOP, MFPT)



MR-5198

Figure 7-39 Operate Group

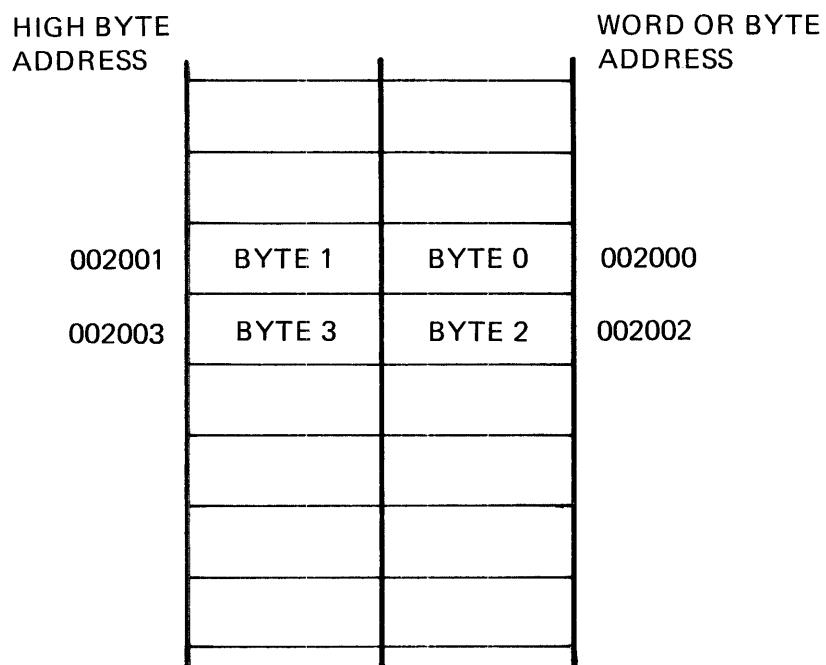
5. Condition Code Operators (all condition code instructions)



MR-5199

Figure 7-40 Condition Group

7.2.1.1 Byte Instructions -- The SBC-11/21 includes a full complement of instructions that manipulate byte operands. Since all microprocessor addressing is byte-oriented, byte manipulation addressing is straightforward. Byte instructions with autoincrement or autodecrement direct addressing cause the specified register to be modified by one to point to the next byte of data. Byte operations in register mode access the low-order byte of the specified register. These provisions enable the SBC-11/21 to perform as either a word or byte microprocessor. The numbering scheme for word and byte addresses in memory is:



MR-5201

Figure 7-41 Byte Instructions

The most significant bit (Bit 15) of the instruction word is set to indicate a byte instruction.

Example:

Symbolic	Octal	
CLR	0050DD	Clear Word
CLRB	1050DD	Clear Byte

7.2.2 List of Instructions

The SBC-11/21 instruction set is shown in the following sequence.

SINGLE OPERAND

Mnemonic	Instruction	Op Code
General		
CLR(B)	clear dst	050DD
COM(B)	complement dst	051DD
INC(B)	increment dst	052DD
DEC(B)	decrement dst	053DD
NEG(B)	negate dst	054DD
TST(B)	test dst	057DD
Shift & Rotate		
ASR(B)	arithmetic shift right	062DD
ASL(B)	arithmetic shift left	063DD
ROR(B)	rotate right	060DD
ROL(B)	rotate left	061DD
SWAB	swap bytes	0003DD
Multiple Precision		
ADC(B)	add carry	055DD
SBC(B)	subtract carry	056DD
SXT	sign extend	0067DD
PS Word Operators		
MFPS	move byte from PS	1067DD
MTPS	move byte to PS	1064SS

DOUBLE OPERAND

General		
MOV(B)	move source to destination	1SSDD
CMP(B)	compare src to dst	2SSDD
ADD	add src to dst	06SSDD
SUB	subtract src from dst	16SSDD
Logical		
BIT(B)	bit test	3SSDD
BIC(B)	bit clear	4SSDD
BIS(B)	bit set	5SSDD
XOR	exclusive or	074RDD

PROGRAM CONTROL

Mnemonic	Instruction	Op Code or Base Code
Branch		
BR	branch (unconditional)	000400
BNE	branch if not equal (to zero)	001000
BEQ	branch if equal (to zero)	001400
BPL	branch if plus	100000
BMI	branch if minus	100400
BVC	branch if overflow is clear	102000
BVS	branch if overflow is set	102400
BCC	branch if carry is clear	103000
BCS	branch if carry is set	103400
Signed Conditional Branch		
BGE	branch if greater than or equal (to zero)	002000
BLT	branch if less than (zero)	002400
BGT	branch if greater than (zero)	003000
BLE	branch if less than or equal (to zero)	003400
Unsigned Conditional Branch		
BHI	branch if higher	101000
BLOS	branch if lower or same	101400
BHIS	branch if higher or same	103000
BLO	branch if lower	103400
Jump & Subroutine		
JMP	jump	0001DD
JSR	jump to subroutine	004RDD
RTS	return from subroutine	00020R
SOB	subtract one and branch (if ≠ 0)	077R00
Trap & Interrupt		
EMT	emulator trap	104000--104377
TRAP	trap	104400--104777
BPT	breakpoint trap	000003
IOT	input/output trap	000004
RTI	return from interrupt	000002
RTT	return from interrupt	000006
MISCELLANEOUS		
HALT	halt	000000
WAIT	wait for interrupt	000001
RESET	reset external bus	000005
MFPT	move processor type	000007

RESERVED INSTRUCTIONS

00021R
00022

CONDITION CODE OPERATORS

CLC	clear C	000241
CLV	clear V	000242
CLZ	clear Z	000244
CLN	clear N	000250
CCC	clear all CC bits	000257
SEC	set C	000261
SEV	set V	000262
SEZ	set Z	000264
SEN	set N	000270
SCC	set all CC bits	000277
NOP	no operation	00240

7.2.3 Single Operand Instructions

NOTE

In all SBC-11/21 instructions a write operation to a memory location or register is always preceded by a read operation from the same location. The exception is when writing PC and PSW to the stack in two cases.

1. The execution of the microcode preceding an interrupt or trap service routine.
2. Interrupt and trap instructions:

HLT
TRAP
BPT
IOT

7.2.3.1 General --

CLR
CLRB

CLEAR DESTINATION

■050DD

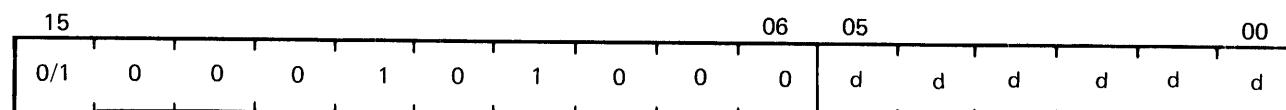


Figure 7-42 CLR

MR-5202

Operation: $(dst) \leftarrow 0$

Condition Codes: N: cleared
Z: set
V: cleared
C: cleared

Description: Word: Contents of specified destination are replaced with zeros.
Byte: Same

Example: CLR R1

Before	After
(R1) = 177777	(R1) = 000000
NZVC 1111	NZVC 0100

COM

COMB

COMPLEMENT DST

■051DD

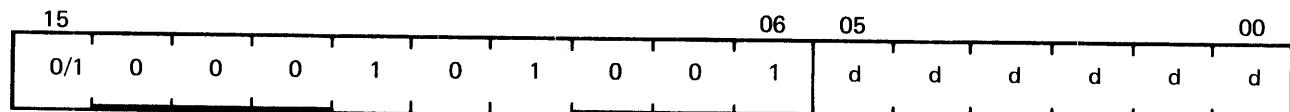


Figure 7-43 COM

MR-5203

Operation: $(dst) \leftarrow \sim(dst)$

Condition Codes: N: set if most significant bit of result is set;
cleared otherwise
Z: set if result is 0; cleared otherwise
V: cleared
C: set

Description: Replaces the contents of the destination address by their logical complement (each bit equal to 0 is set and each bit equal to one is cleared)
Byte: Same

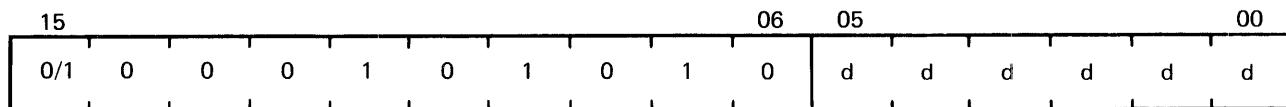
Example: COM R0

Before	After
(R0) = 013333	(R0) = 164444
NZVC 0110	NZVC 1001

INC
INCB

INCREMENT DST

■052DD



MR-5204

Figure 7-44 INC

Operation: $(dst) \leftarrow (dst) + 1$

Condition Codes: N: set if result is <0; cleared otherwise
Z: set if result is 0; cleared otherwise
V: set if (dst) held 077777; cleared otherwise
C: not affected

Description: Word: Add one to contents of destination
Byte: Same

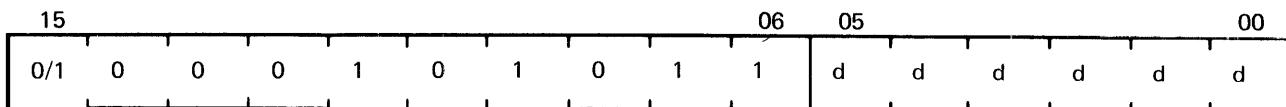
Example: INC R2

Before	After
$(R2) = 000333$	$(R2) = 000334$
NZVC	NZVC
0000	0000

DEC
DECB

DECREMENT DST

■053DD



MR-5205

Figure 7-45 DEC

Operation: $(dst) \leftarrow (dst) - 1$

Condition Codes: N: set if result is <0, cleared otherwise
Z: set if result is 0; cleared otherwise
V: set if (dst) was 100000; cleared otherwise
C: not affected

Description: Word: Subtract one from the contents of the destination
Byte: Same

Example:

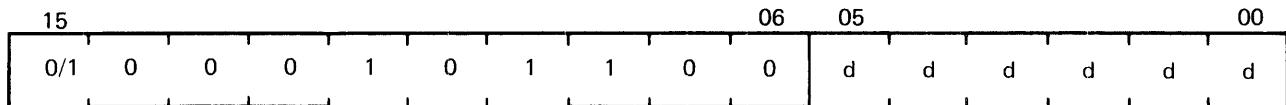
DEC R5

	Before	After
(R5) =	000001	000000
	NZVC 1000	NZVC 0100

NEG
NEGB

NEGATE DST

■054DD



MR-5206

Figure 7-46 NEG

Operation: $(dst) \leftarrow -(dst)$

Condition Codes: N: set if the result is <0; cleared otherwise
Z: set if result is 0; cleared otherwise
V: set if the result is 100000; cleared otherwise
C: cleared if the result is 0; set otherwise

Description: Word: Replaces the contents of the destination address by its two's complement. Note that 100000 is replaced by itself (in two's complement notation the most negative number has no positive counterpart).
Byte: Same

Example:

NEG R0

	Before	After
(R0) =	000010	177770
	NZVC 0000	NZVC 1001

TST
TSTB

TEST DST

■057DD

15	0	0	0	1	0	1	1	1	1	06	05	00
0/1	0	0	0	1	0	1	1	1	d	d	d	d

MR-5207

Figure 7-47 TST

Operation: $(dst) \leftarrow (dst)$

Condition Codes: N: set if the result is <0; cleared otherwise
 Z: set if result is 0; cleared otherwise
 V: cleared
 C: cleared

Description: Word: Sets the condition codes N and Z according to the contents of the destination address, contents of dst remains unmodified
 Byte: Same

Example: TST R1

Before	After
$(R1) = 012340$	$(R1) = 012340$
NZVC	NZVC
0011	0000

7.2.3.2 Shifts & Rotates -- Scaling data by factors of two is accomplished by the shift instructions:

ASR -- Arithmetic shift right

ASL -- Arithmetic shift left

The sign bit (bit 15) of the operand is reproduced in shifts to the right. The low order bit is filled with zero in shifts to the left. Bits shifted out of the C bit, as shown in the following examples, are lost.

The rotate instructions operate on the destination word and the C bit as though they formed a 17-bit "circular buffer." These instructions facilitate sequential bit testing and detailed bit manipulation.

ASRASRB

ARITHMETIC SHIFT RIGHT

■062DD

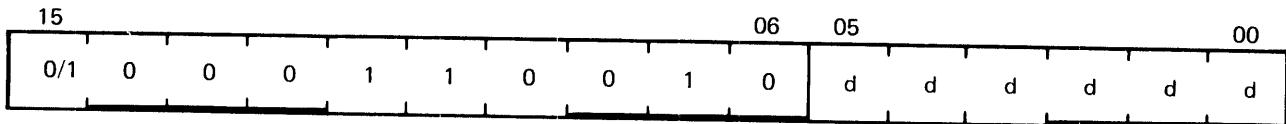


Figure 7-48 ASR

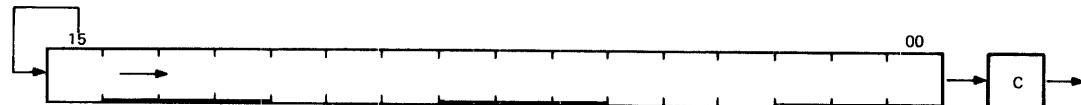
MR-5208

Operation: $(dst) \leftarrow (dst)$ shifted one place to the right

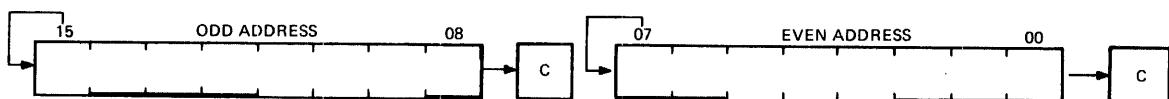
Condition Codes: N: set if the high-order bit of the result is set ($result < 0$); cleared otherwise
 Z: set if the result = 0; cleared otherwise
 V: loaded from the Exclusive OR of the N-bit and C-bit (as set by the completion of the shift operation)
 C: loaded from low-order bit of the destination

Description: Word: Shifts all bits of the destination right one place. Bit 15 is reproduced. The C-bit is loaded from bit zero of the destination. ASR performs signed division of the destination by two.
 Word:

Example:



BYTE:



MR-7236

Figure 7-49 ASR Description

ASLASLB

ARITHMETIC SHIFT LEFT

■063DD

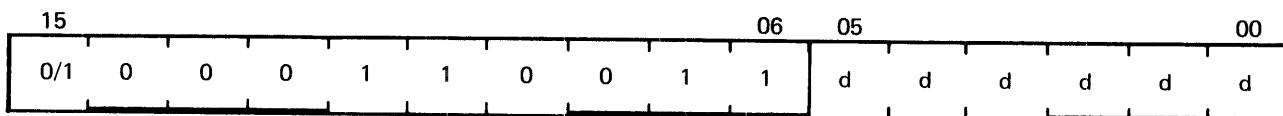


Figure 7-50 ASL

MR-5210

Operation: $(dst) \ll (dst)$ shifted one place to the left

Condition Codes: N: set if high-order bit of the result is set (result < 0); cleared otherwise
Z: set if the result = 0; cleared otherwise
V: loaded with the exclusive OR of the N-bit and C-bit (as set by the completion of the shift operation)
C: loaded with the high-order bit of the destination

Description: Word: Shifts all bits of the destination left one place. Bit zero is loaded with a zero. The C-bit of the status word is loaded from the most significant bit of the destination. ASL performs a signed multiplication of the destination by two with overflow indication.
Word:

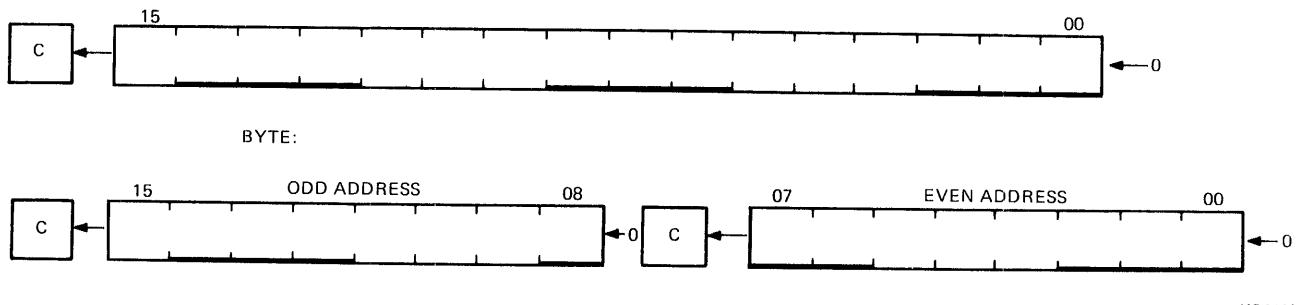


Figure 7-51 ASL Description

MR-5211

ROR

RORB

ROTATE RIGHT

■060DD

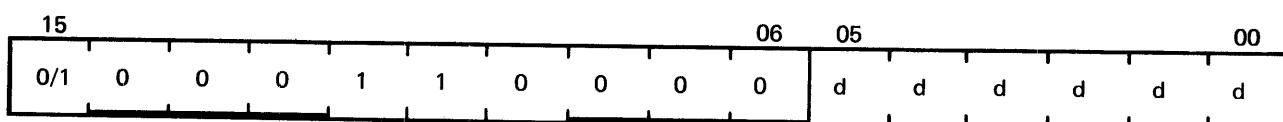


Figure 7-52 ROR

MR-5212

Operation: $(dst) \ll (dst)$ rotate right one place

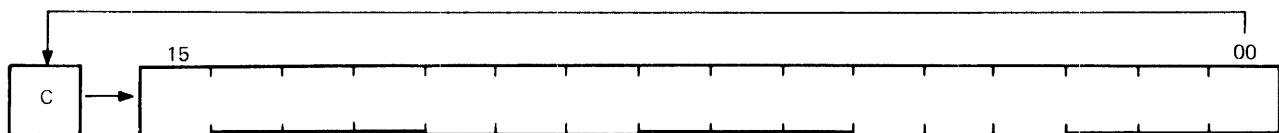
Condition Codes: N: set if the high-order bit of the result is set (result < 0); cleared otherwise
Z: set if all bits of result = 0; cleared otherwise

V: loaded with the Exclusive OR of the N-bit and C-bit (as set by the completion of the rotate operation)
 C: loaded with the low-order bit of the destination

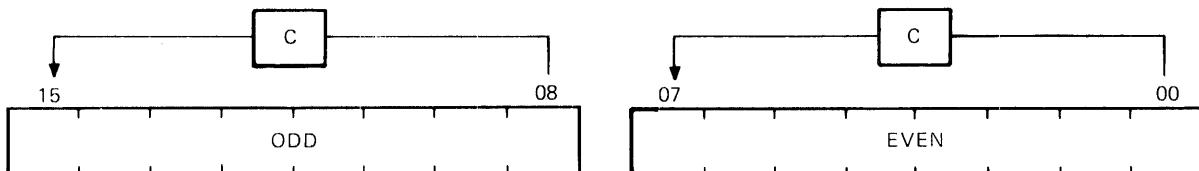
Description: Rotates all bits of the destination right one place. Bit 0 is loaded into the C-bit and the previous contents of the C-bit are loaded into bit 15 of the destination.

Example:

WORD:



BYTE:



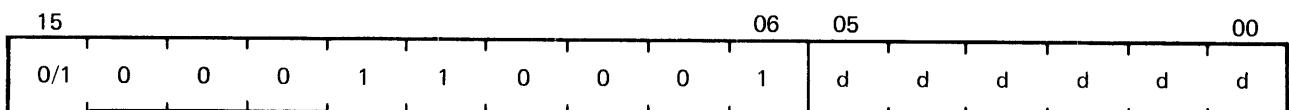
MR 5213

Figure 7-53 ROR Description

ROL
ROLB

ROTATE LEFT

■061DD



MR-5214

Figure 7-54 ROL

Operation: $(dst) \leftarrow (dst)$ rotate left one place

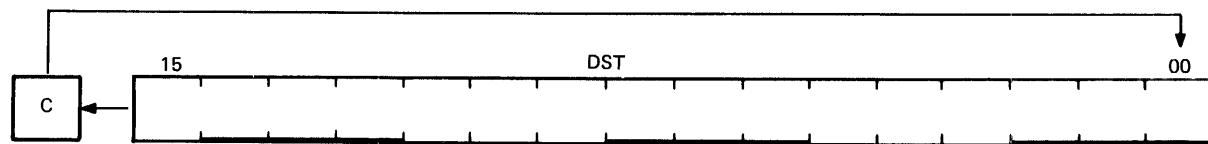
Condition Codes: N: set if the high-order bit of the result word is set ($result < 0$); cleared otherwise
 Z: set if all bits of the result word = 0; cleared otherwise

V: loaded with the Exclusive OR of the N-bit and C-bit (as set by the completion of the rotate operation)
 C: loaded with the high-order bit of the destination

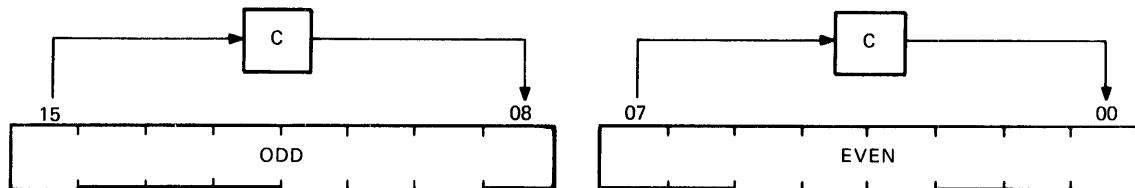
Description: Word: Rotate all bits of the destination left one place. Bit 15 is loaded into the C-bit of the status word and the previous contents of the C-bit are loaded into Bit 0 of the destination.

Example:

WORD:



BYTE:



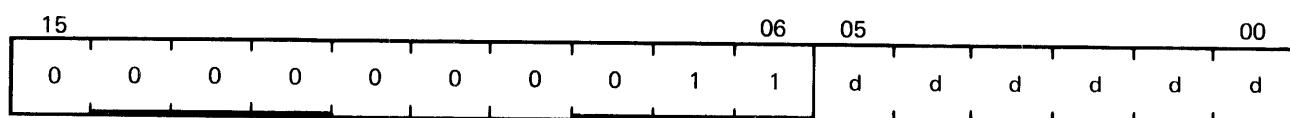
MR-5215

Figure 7-55 ROL Description

SWAB

SWAP BYTES

0003DD



MR-5216

Figure 7-56 SWAB

Operation: Byte 1/Byte 0 <Byte 0/Byte 1

Condition Codes: N: set if high-order bit of low-order byte (bit 7) of result is set; cleared otherwise
Z: set if low-order byte of result = 0; cleared otherwise
V: cleared
C: cleared

Description: Exchanges high-order byte and low-order byte of the destination word (destination must be a word address).

Example:

SWAB R1

Before	After
$(R1) = 077777$	$(R1) = 177577$
NZVC	NZVC
1111	0000

7.2.3.3 Multiple Precision -- It is sometimes necessary to do arithmetic on operands considered as multiple words or bytes. The SBC-11/21 makes special provision for such operations with the instructions ADC (Add Carry) and SBC (Subtract Carry) and their byte equivalents.

For example, two 16-bit words may be combined into a 32-bit double precision word and added or subtracted as shown below.

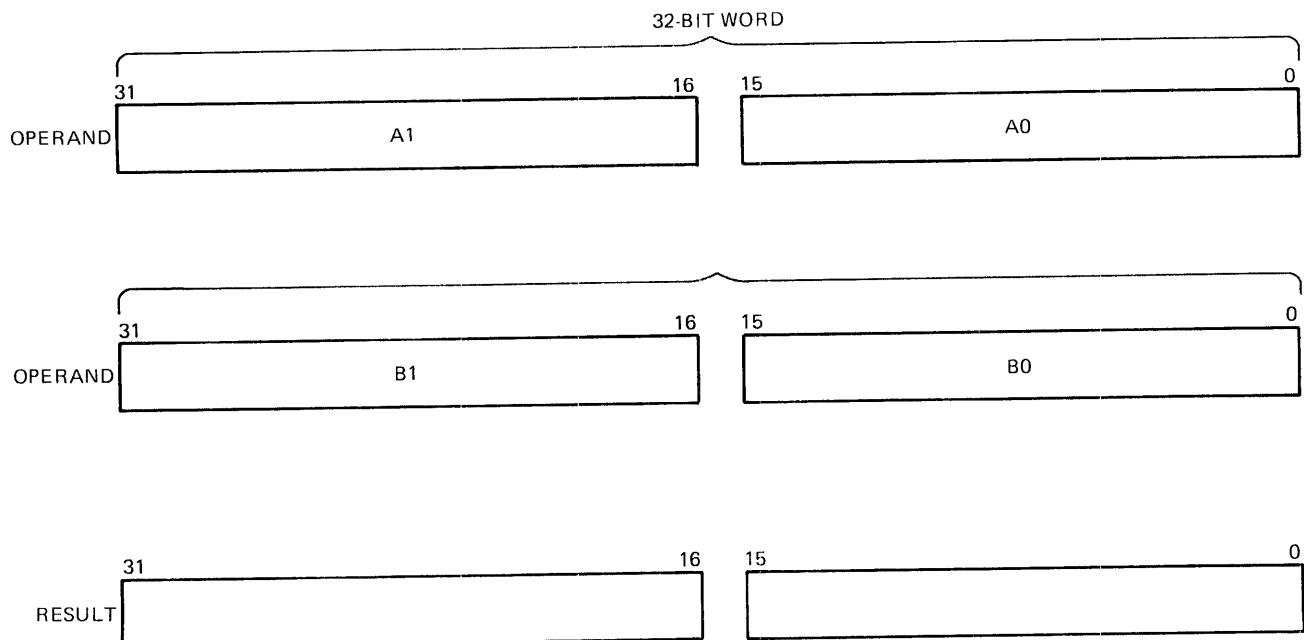


Figure 7-57 Multiple Precision

MR-5217

Example:

The addition of -1 and -1 could be performed as follows:

-1 = 37777777777

(R1) = 177777 (R2) = 177777 (R3) = 177777 (R4) = 177777

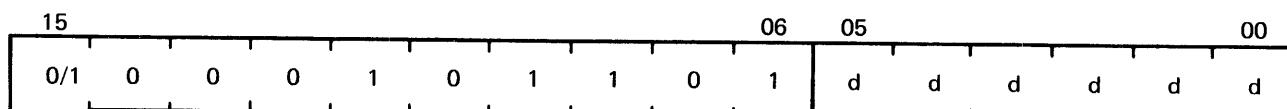
ADD R1,R2
ADC R3
ADD R4,R3

1. After (R1) and (R2) are added, 1 is loaded into the C bit
2. ADC instruction adds C bit to (R3); (R3) = 0
3. (R3) and (R4) are added
4. Result is 37777777776 or -2

ADC
ADC B

ADD CARRY

■055DD



MR-5218

Figure 7-58 ADC

Operation: (dst) <= (dst) + (C bit)

Condition Codes: N: set if result < 0; cleared otherwise
Z: set if result = 0; cleared otherwise
V: set if (dst) was 077777 and (C) was 1;
cleared otherwise
C: set if (dst) was 177777 and (c) was 1;
cleared otherwise

Description: Adds the contents of the C-bit into the destination. This permits the carry from the addition of the low-order words to be carried into the high-order result.

Byte: Same

Example: Double precision addition may be done with the following instruction sequence:

ADD A0,B0	; add low-order parts
ADC B1	; add carry into high-order
ADD A1,B1	; add high-order parts

SBC
SBCB

SUBTRACT CARRY

■056DD

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
0/1	0	0	0	1	0	1	1	1	0	d	d	d	d	d	d

MR-5219

Figure 7-59 SBC

Operation: $(dst) \leftarrow (dst) - (C)$

Condition Codes: N: set if result <0; cleared otherwise
Z: set if result 0; cleared otherwise
V: set if (dst) was 100000; cleared otherwise
C: set if (dst) was 0 and C was 1; cleared otherwise

Description: Word: Subtracts the contents of the C-bit from the destination. This permits the carry from the subtraction of two low-order words to be subtracted from the high order part of the result.
Byte: Same

Example: Double precision subtraction is done by:

```
SUB    A0,B0
SBC    B1
SUB    A1,B1
```

SXT

SIGN EXTEND

0067DD

15	0	0	0	0	1	1	0	1	1	1	06	05	00
											d	d	d

MR-5220

Figure 7-60 SXT

Operation: $(dst) \leftarrow 0$ if N-bit is clear
 $(dst) \leftarrow 1$ N-bit is set

Condition Codes: N: unaffected
Z: set if N-bit clear
V: cleared
C: unaffected

Description: If the condition code bit N is set then a -1 is placed in the destination operand; if N bit is clear, then a zero is placed in the destination operand. This instruction is particularly useful in multiple precision arithmetic because it permits the sign to be extended through multiple words.

Example:

SXT A

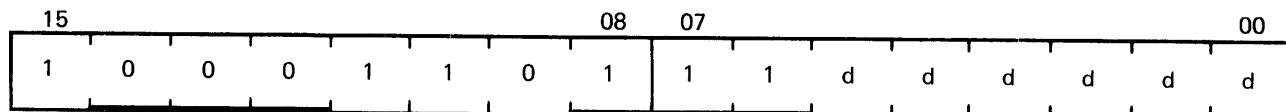
Before	After
(A) = 012345	(A) = 177777
NZVC	NZVC
1000	1000

7.2.3.4 PS Word Operators --

MFPS

MOVE BYTE FROM PROCESSOR STATUS WORD

1067DD



MR-5221

Figure 7-61 MFPS

Operation: (dst) <PS
dst lower 8 bits

Condition Code

N = set if PS bit 7 = 1; cleared otherwise
Z = set if PS <0:7> = 0; cleared otherwise
V = cleared
C = not affected

Description: The 8 bit contents of the PS are moved to the effective destination. If destination is mode 0, PS bit 7 is sign extended through upper byte of the register. The destination operand address is treated as a byte address.

Example:

MFPS R0

Before		After	
R0	[0]	R0	[000014]
PS	[000014]	PS	[0000001]

MTPS

MOVE BYTE TO PROCESSOR STATUS WORD

1064SS

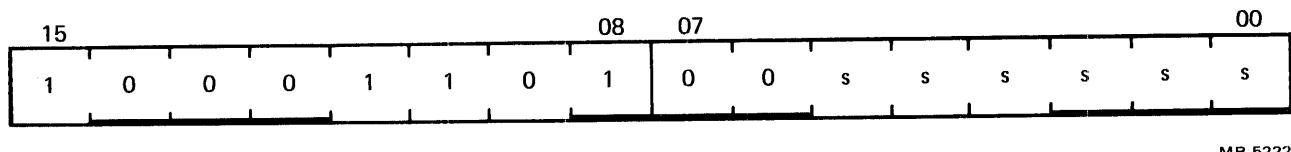


Figure 7-62 MTPS

Operation: PS<(SRC)

Condition Codes: Set according to effective SRC operand bits 0--3

Description: The eight bits of the effective operand replaces the current contents of the PS. The source operand address is treated as a byte address. Note that the T bit (PS bit four) cannot be set with this instruction. The SRC operand remains unchanged. This instruction can be used to change the priority bits (PS bits 7--5) in the PS.

7.2.4 Double Operand Instructions

Double operand instructions provide an instruction (and time) saving facility since they eliminate the need for "load" and "save" sequences such as those used in accumulator-oriented machines.

7.2.4.1 General --

MOV MOVB

MOVE SOURCE TO DESTINATION

■1SSDD

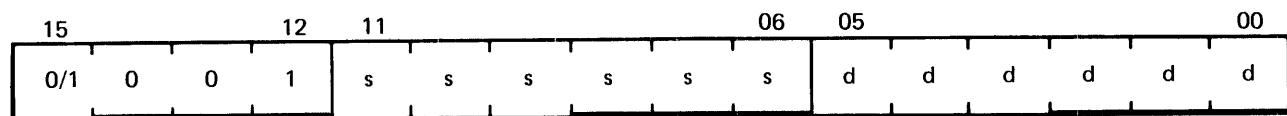


Figure 7-63 MOV

Operation: (dst) <= (src)

Condition Codes: N: set if (src) < 0; cleared otherwise
 Z: set if (src) = 0; cleared otherwise
 V: cleared
 C: not affected

Description: Word: Moves the source operand to the destination location. The previous contents of the destination are lost. The contents of the source address are not affected.
 Byte: Same as MOV. The MOVB to a register (unique among byte instructions) extends the most significant bit of the low order byte (sign extension). Otherwise MOVB operates on bytes exactly as MOV operates on words.

Example:

MOV XXX,R1	; loads Register one with the contents of memory location; XXX represents a programmer-defined mnemonic used to represent a memory location.
MOV #20,R0	; loads the number 20 into Register 0; "#" indicates that the value 20 is the operand.
MOV @ #20, -(R6)	; pushes the operand contained in location 20 onto the stack.
MOV (R6) +,@ #177566	; pops the operand off a stack and moves it into memory location 177566 (terminal print buffer).
MOV R1,R3	; performs an inter register transfer.
MOVB @#177562, @#177566	; moves a character from terminal keyboard buffer to terminal printer buffer.

CMP
CMPB

COMPARE SRC TO DST

■2SSDD

15	12	11				06	05		00
0/1	0	1	0	s	s	s	s	d	d

MR-5224

Figure 7-64 CMP

Operation: $(src) - (dst)$

Condition Codes: N: set if result <0; cleared otherwise
Z: set if result = 0; cleared otherwise
V: set if there was arithmetic overflow; that is, operands were of opposite signs and the sign of the destination was the same as the sign of the result; cleared otherwise.
C: cleared if there was a carry from the most significant bit of the result; set otherwise.

Description: Compares the source and destination operands and sets the condition codes, which may then be used for arithmetic and logical conditional branches. Both operands are unaffected. The only action is to set the condition codes. The compare is customarily followed by a conditional branch instruction.
Note that unlike the subtract instruction the order of operation is $(src) - (dst)$, not $(dst) - (src)$.

ADD

ADD SRC TO DST

06SSDD

15	12	11				06	05		00
0	1	1	0	s	s	s	s	d	d

MR-5225

Figure 7-65 ADD

Operation: $(dst) \leftarrow (src) + (dst)$

Condition Codes: N: set if result <0; cleared otherwise.
Z: set if result = 0; cleared otherwise.
V: set if there was arithmetic overflow as a

result of the operation; that is both operands were of the same sign and the result was of the opposite sign; cleared otherwise.

C: set if there was a carry from the most significant bit of the result; cleared otherwise.

Description: Adds the source operand to the destination operand and stores the result at the destination address. The original contents of the destination are lost. The contents of the source are not affected. Two's complement addition is performed.

Note: There is no equivalent byte mode.

Examples:

Add to register:	ADD	20,R0
Add to memory:	ADD	R1,XXX
Add register to register:	ADD	R1,R2
Add memory to memory:	ADD@ # 17750,XXX	

XXX is a programmer-defined mnemonic for a memory location.

SUB

SUBTRACT SRC FROM DST 16SSDD



Figure 7-66 SUB

MR-5226

Operation: $(dst) \leftarrow (dst) - (src)$

Condition Codes:

- N: set if result < 0; cleared otherwise
- Z: set if result = 0; cleared otherwise
- V: set if there was arithmetic overflow as a result of the operation, that is if operands were of opposite signs and the sign of the source was the same as the sign of the result; cleared otherwise.
- C: cleared if there was a carry from the most significant bit of the result; set otherwise.

Description: Subtracts the source operand from the destination operand and leaves the result at the destination address. The original contents of the destination are lost. The contents of the source are not affected. In double-precision arithmetic the C-bit, when set, indicates a "borrow".

Note: There is no equivalent byte mode.

Example:

SUB R1,R2

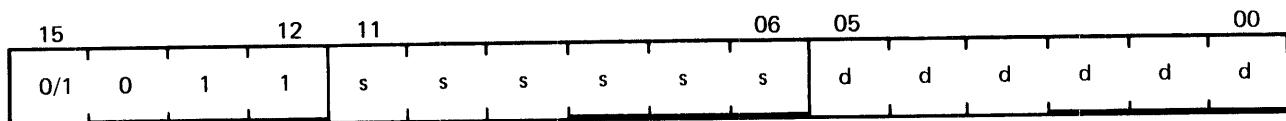
Before	After
(R1) = 011111	(R1) = 011111
(R2) = 012345	(R2) = 001234
NZVC	NZVC
1111	0000

7.2.4.2 Logical -- These instructions have the same format as the double operand arithmetic group. They permit operations on data at the bit level.

BIT
BITB

BIT TEST

■3SSDD



MR-5227

Figure 7-67 BIT

Operation: $(src) \wedge (dst)$

Condition Codes: N: set if high-order bit of result set; cleared otherwise
Z: set if result = 0; cleared otherwise
V: cleared
C: not affected

Description: Performs logical "and" comparison of the source and destination operands and modifies condition codes accordingly. Neither the source nor destination is affected. The BIT instruction may be used to test whether any of the corresponding bits that are set in the destination are also set in the source or whether all corresponding bits set in the destination are clear in the source.

Example: BIT #30,R3 test bits three and four of R3
 to see if both are off

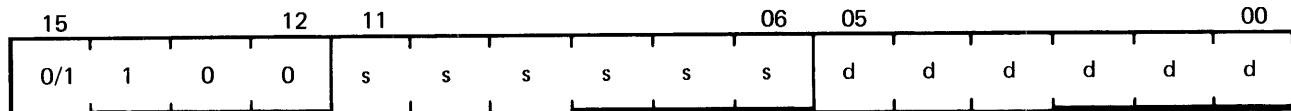
R3 = 0 000 000 000 011 000

Before	After
NZVC	NZVC
1111	0001

BIC
BICB

BIT CLEAR

■4SSDD



MR-5228

Figure 7-68 BIC

Operation: $(dst) \ll (dst) \wedge \sim (src)$

Condition Codes: N: set if high order bit of result set; cleared otherwise
Z: set if result = 0; cleared otherwise
V: cleared
C: not affected

Description: Clears each bit in the destination that corresponds to a set bit in the source. The original contents of the destination are lost. The contents of the source are unaffected.

Example: BIC R3,R4

Before	After
(R3) = 001234	(R3) = 001234
(R4) = 001111	(R4) = 000101

NZVC
1111

NZVC
0001

Before: (R3) = 0 000 001 010 011 100
 (R4) = 0 000 001 001 001 001

After: (R4) = 0 000 000 001 000 001

BIS
BISB

BIT SET

■5SSDD

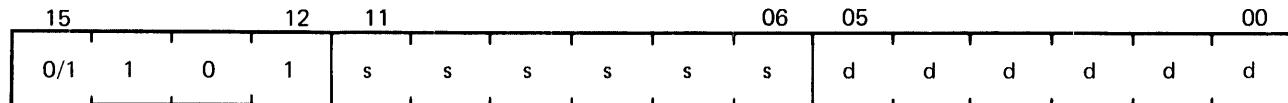


Figure 7-69 BIS

MR-5229

Operation: $(dst) \leftarrow (dst) \vee (src)$

Condition Codes: N: set if high-order bit of result set, cleared otherwise
Z: set if result = 0; cleared otherwise
V: cleared
C: not affected

Description: Performs "Inclusive OR" operation between the source and destination operands and leaves the result at the destination address; that is, corresponding bits set in the source are set in the destination. The contents of the destination are lost.

Example: BIS R0,R1

	Before	After
(R0) =	001234	001234
(R1) =	001111	001335

	NZVC	NZVC
	0000	0000

Before: (R0) = 0 000 001 010 011 100
 (R1) = 0 000 001 001 001 001

After: (R1) = 0 000 001 011 011 101

XOR

EXCLUSIVE OR

074RDD

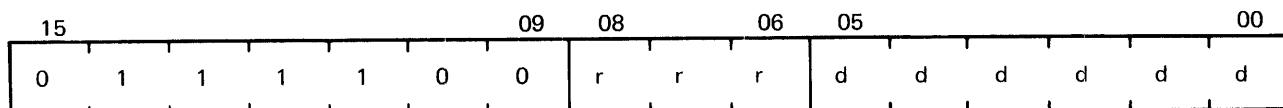


Figure 7-70 XOR

MR-5230

Operation: $(dst) \leftarrow (dst) \Delta (Reg)$

Condition Codes: N: set if the result <0; cleared otherwise
Z: set if result = 0; cleared otherwise
V: cleared
C: unaffected

Description: The exclusive OR of the register and destination operand is stored in the destination address. Contents of register are unaffected. Assembler format is: XOR R,D.

Example: XOR R0,R2

Before	After
$(R0) = 001234$	$(R0) = 001234$
$(R2) = 001111$	$(R2) = 000325$
NZVC	NZVC
1111	0001
Before:	$(R0) = 0\ 000\ 001\ 010\ 011\ 100$
	$(R2) = 0\ 000\ 001\ 001\ 001\ 001$
After:	$(R2) = 0\ 000\ 000\ 011\ 010\ 101$

7.2.5 Program Control Instructions

7.2.5.1 Branches -- These instructions cause a branch to a location defined by the sum of the offset (multiplied by two) and the current contents of the Program Counter if:

1. the branch instruction is unconditional.
2. it is conditional and the conditions are met after testing the condition codes (NZVC).

The offset is the number of words from the current contents of the PC forward or backward. Note that the current contents of the PC point to the word following the branch instruction.

Although the offset expresses a byte address the PC is expressed in words. The offset is automatically multiplied by two and sign extended to express words before it is added to the PC. Bit seven is the sign of the offset. If it is set, the offset is negative and the branch is done in the backward direction. Similarly if it is not set, the offset is positive and the branch is done in the forward direction.

The 8-bit offset allows branching in the backward direction by 200_8 words (400 bytes) from the current PC, and in the forward direction by 177_8 words (376 bytes) from the current PC.

The microprocessor assembler handles address arithmetic for the user and computes and assembles the proper offset field for branch instructions in the form:

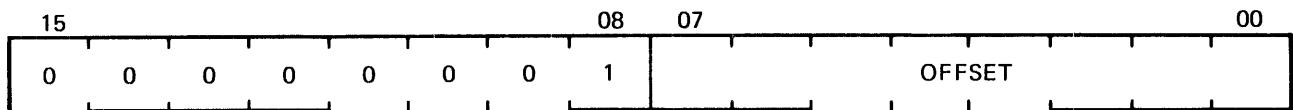
Bxx loc

Where "Bxx" is the branch instruction and "loc" is the address to which the branch is to be made. The assembler gives an error indication in the instruction if the permissible branch range is exceeded. Branch instructions have no effect on condition codes. Conditional branch instructions where the branch condition is not met, are treated as NO OPs.

BR

BRANCH (UNCONDITIONAL)

000400 PLUS OFFSET



MR-5231

Figure 7-71 BR

Operation: $PC \leftarrow PC + (2 \times \text{offset})$

Condition Codes: Unaffected

Description: Provides a way of transferring program control within a range of -128_{10} to $+127_{10}$ words with a one word instruction.

New PC address = updated PC + (2 X offset)

Updated PC = address of branch instruction +2

Example: With the Branch instruction at location 500, the following offsets apply.

New PC Address	Offset Code	Offset (decimal)
474	375	-3
476	376	-2
500	377	-1
502	000	0
504	001	+1
506	002	+2

BNE

BRANCH IF NOT EQUAL (TO ZERO)

001000 PLUS OFFSET

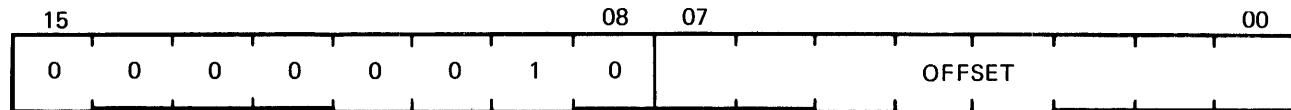


Figure 7-72 BNE

MR-5232

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $Z = 0$

Condition Codes: Unaffected

Description: Tests the state of the Z-bit and causes a branch if the Z-bit is clear. BNE is the complementary operation to BEQ. It is used to test inequality following a CMP, to test that some bits set in the destination were also in the source, following a BIT operation, and generally, to test that the result of the previous operation was not zero.

Example:

CMP A,B	; compare A and B
BNE C	; branch if they are not equal

will branch to C if $A \neq B$

and the sequence

ADD A,B	; add A to B
BNE C	; Branch if the result is not equal to 0

will branch to C if $A + B \neq 0$

BEQ

BRANCH IF EQUAL (TO ZERO)

001400 PLUS OFFSET

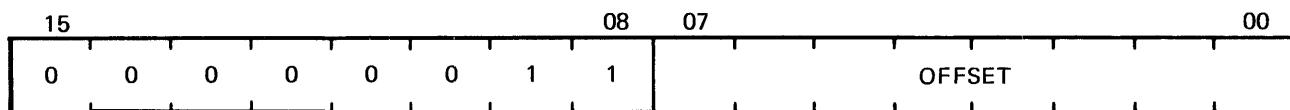


Figure 7-73 BEQ

MR-5233

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $Z = 1$
Condition Codes: Unaffected
Description: Tests the state of the Z-bit and causes a branch if Z is set. As an example, it is used to test equality following a CMP operation, to test that no bits set in the destination were also set in the source following a BIT operation, and generally, to test that the result of the previous operation was zero.
Example:

```

    CMP A,B           ;compare A and B
    BEQ C             ;branch if they are equal
    will branch to C if A = B      (A - B = 0)
    and the sequence

    ADD A,B           ;add A to B
    BEQ C             ;branch if the result = 0
    will branch to C if A + B = 0.
  
```

BPL

BRANCH IF PLUS

100000 PLUS OFFSET

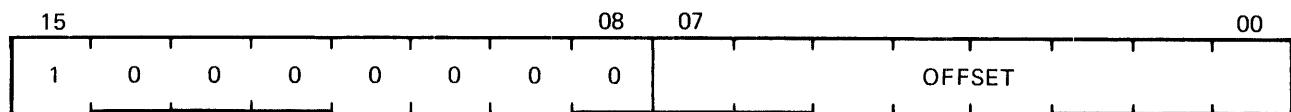


Figure 7-74 BPL

MR-5234

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $N = 0$
Condition Codes: Unaffected
Description: Tests the state of the N-bit and causes a branch if N is clear, (positive result). BPL is the complementary operation of BMI.

BMI

BRANCH IF MINUS

100400 PLUS OFFSET

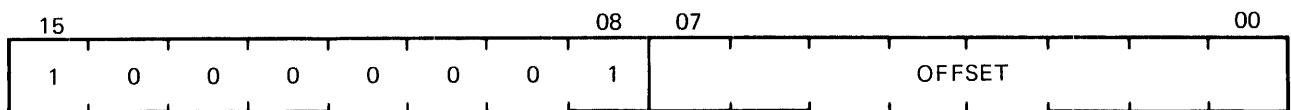


Figure 7-75 BMI

MR-5235

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $N = 1$

Condition Codes: Unaffected

Description: Tests the state of the N-bit and causes a branch if N is set. It is used to test the sign (most significant bit) of the result of the previous operation, branching if negative. BMI is the complementary function of BPL.

BVC

BRANCH IF OVERFLOW IS CLEAR

102000 PLUS OFFSET

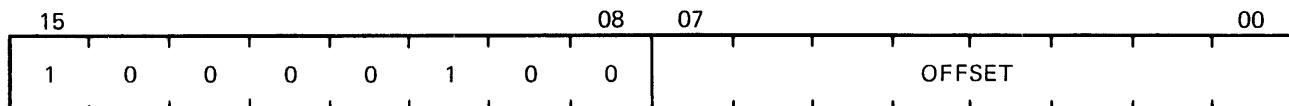


Figure 7-76 BVC

MR-5236

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $V = 0$

Condition Codes: Unaffected

Description: Tests the state of the V-bit and causes a branch if the V bit is clear. BVC is complementary operation to BVS.

BVS

BRANCH IF OVERFLOW IS SET

102400 PLUS OFFSET

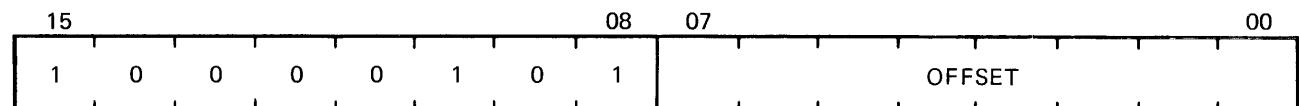


Figure 7-77 BVS

MR-5237

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $V = 1$

Condition Codes: Unaffected

Description: Tests the state of V-bit (overflow) and causes a branch if the V bit is set. BVS is used to detect arithmetic overflow in the previous operation.

BCC

BRANCH IF CARRY IS CLEAR

103000 PLUS OFFSET

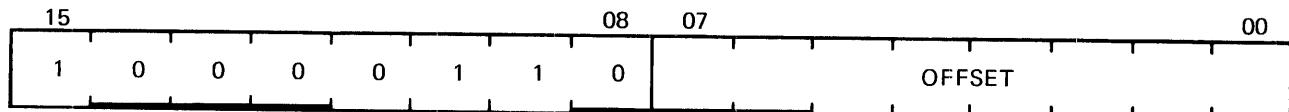


Figure 7-78 BCC

MR-5238

Operation: $PC \leftarrow PC + (2 \times \text{offset}) \text{ if } C = 0$

Condition Codes: Unaffected

Description: Tests the state of the C-bit and causes a branch if C is clear. BCC is the complementary operation to BCS.

BCS

BRANCH IF CARRY IS SET

103400 PLUS OFFSET

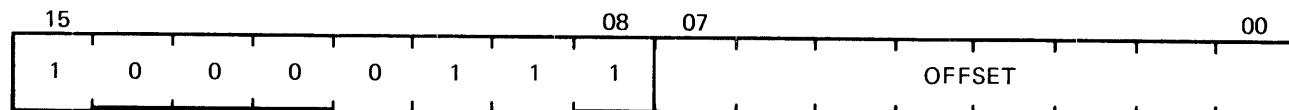


Figure 7-79 BCS

MR-5239

Operation: $PC \leftarrow PC + (2 \times \text{offset}) \text{ if } C = 1$

Condition Codes: Unaffected

Description: Tests the state of the C-bit and causes a branch if C is set. It is used to test for a carry in the result of a previous operation.

7.2.5.2 Signed Conditional Branches -- Particular combinations of the condition code bits are tested with the signed conditional branches. These instructions are used to test the results of instructions in which the operands were considered as signed (two's complement) values.

Note that the sense of signed comparisons differs from that of unsigned comparisons in that in signed 16-bit, two's complement arithmetic the sequence of values is as follows.

largest 077777
 077776

positive	.
	.
	.
	000001
zero	000000
	177777
	177776
	.
negative	.
	.
	100001
smallest	100000

whereas in unsigned 16-bit arithmetic the sequence is considered to be

highest	177777
	.
	.
	.
	.
	.
	.
	000002
	000001
lowest	000000

BGE

BRANCH IF GREATER THAN OR EQUAL
(TO ZERO)

002000 PLUS OFFSET

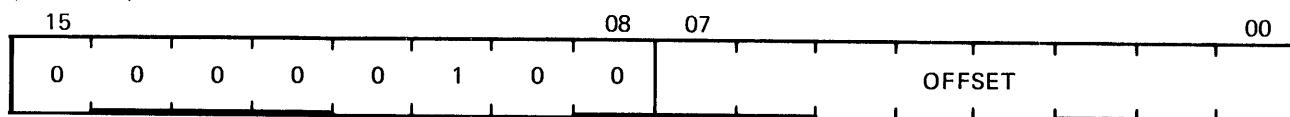


Figure 7-80 BGE

MR-5240

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $N \neq V = 0$

Condition Codes: Unaffected

Description: Causes a branch if N and V are either both clear or both set. BGE is the complementary operation to BLT. Thus BGE will always cause a branch when it follows an operation that caused addition of two positive numbers. BGE will also cause a branch on a zero result.

BLT

BRANCH IF LESS THAN (ZERO)

002400 PLUS OFFSET

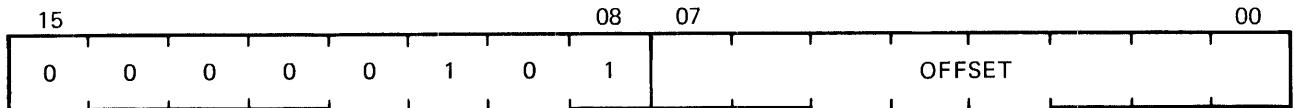


Figure 7-81 BLT

MR-5241

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $N \nabla V = 1$

Condition Codes: Unaffected

Description: Causes a branch if the "Exclusive Or" of the N and V bits are one. Thus BLT will always branch following an operation that added two negative numbers, even if overflow occurred. In particular, BLT will always cause a branch if it follows a CMP instruction operating on a negative source and a positive destination (even if overflow occurred). Further, BLT will never cause a branch when it follows a CMP instruction operating on a positive source and negative destination. BLT will not cause a branch if the result of the previous operation was zero (without overflow).

BGT

BRANCH IF GREATER THAN (ZERO)

003000 PLUS OFFSET

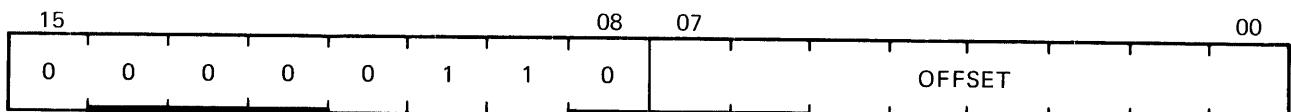


Figure 7-82 BGT

MR-5242

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $z \vee (N \nabla V) = 0$

Condition Codes: Unaffected

Description: Operation of BGT is similar to BGE, except BGT will not cause a branch on a zero result.

BLE

BRANCH IF LESS THAN OR EQUAL (TO ZERO)

003400 PLUS OFFSET

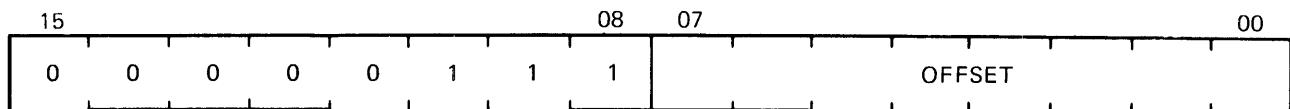


Figure 7-83 B.I.E.

MR-5243

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $Z \vee (N \neq V) = 1$

Condition Codes: Unaffected

Description: Operation is similar to BLT but in addition will cause a branch if the result of the previous operation was zero.

7.2.5.3 Unsigned Conditional Branches -- The unsigned conditional Branches provide a means for testing the result of comparison operations in which the operands are considered as unsigned values.

BHI

BRANCH IF HIGHER

101000 PLUS OFFSET

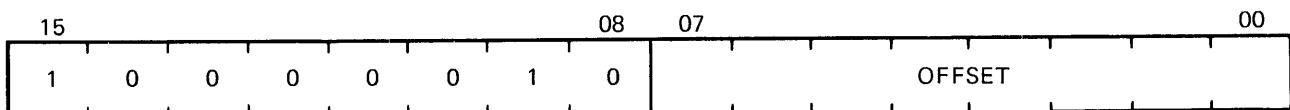


Figure 7-84 BHT

MR-5244

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $C = 0$ and $Z = 0$

Condition Codes: Unaffected

Description: Causes a branch if the previous operation caused neither a carry nor a zero result. This will happen in comparison (CMP) operations as long as the source has a higher unsigned value than the destination.

BLOS

BRANCH IF LOWER OR SAME

101400 PLUS OFFSET

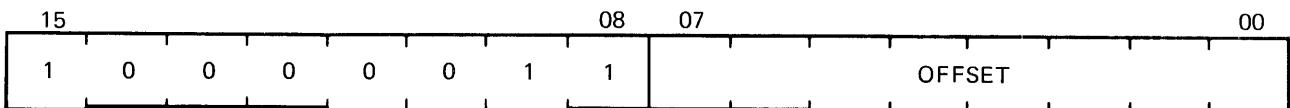


Figure 7-85 BLOS

MB-5245

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $C \vee Z = 1$

Condition Codes: Unaffected

Description: Causes a branch if the previous operation caused either a carry or a zero result. BLOS is the complementary operation to BHI. The branch will occur in comparison operations as long as the source is equal to, or has a lower unsigned value than the destination.

BHIS

BRANCH IF HIGHER OR SAME

103000 PLUS OFFSET

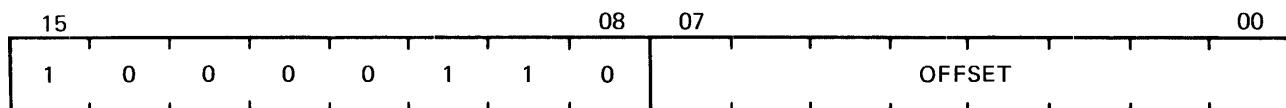


Figure 7-86 BHIS

MR-5246

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $C = 0$

Condition Codes: Unaffected

Description: BHIS is the same instruction as BCC. This mnemonic included only for convenience.

BLO

BRANCH IF LOWER

103400 PLUS OFFSET

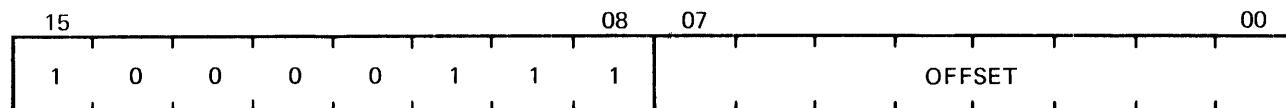


Figure 7-87 BLO

MR-5247

Operation: $PC \leftarrow PC + (2 \times \text{offset})$ if $C = 1$

Condition Codes: Unaffected

Description: BLO is same instruction as BCS. This mnemonic is included only for convenience.

7.2.5.4 Jump & Subroutine Instructions -- The subroutine call in the microprocessor provides for automatic nesting of subroutines, reentrancy, and multiple entry points. Subroutines may call other subroutines (or indeed themselves) to any level of nesting without making special provision for storage of return addresses at each level of subroutine call. The subroutine calling mechanism does not modify any fixed location in memory, thus providing for reentrancy. This allows one copy of a subroutine to be shared among several interrupting processes.

JMP

JUMP

0001DD

15	0	0	0	0	0	0	0	0	0	1	d	d	d	d	d	00
0	0	0	0	0	0	0	0	0	0	1	d	d	d	d	d	00

Figure 7-88 JMP

MR-5248

Operation: PC \leftarrow (dst)

Condition Codes: Unaffected

Description: JMP provides more flexible program branching than provided with the branch instructions. Control may be transferred to any location in memory (no range limitation) and can be accomplished with the full flexibility of the addressing modes, with the exception of register mode 0. Execution of a jump with Mode 0 will cause an "illegal instruction" condition, and will cause the CPU to trap to vector address four. (Program control cannot be transferred to a register.) Register deferred mode is legal and will cause program control to be transferred to the address held in the specified register. Note that instructions are word data and must therefore be fetched from an even-numbered address.

Deferred index mode JMP instructions permit transfer of control to the address contained in a selectable element of a table of dispatch vectors.

Example:

```
JMP      FIRST      ;Transfers to First
First:   .....
        .....
JMP      @LIST      ;Transfers to location pointed
List:    .....
        FIRST       ;pointer to FIRST
                .....
JMP      @(SP)+    ;Transfer to location pointed
                    to by the top of the stack,
                    and remove the pointer from
                    the stack.
```

JSR

JUMP TO SUBROUTINE

004RDD

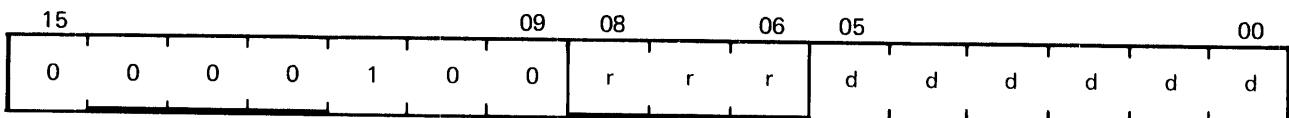


Figure 7-89 JSR

MR-5249

Operation:

(tmp) < (dst) (tmp is an internal processor register)

↓(SP)<reg (Push reg contents onto processor stack)

reg<PC (PC holds location following JSR; this address now put in reg)

PC<(dst) (PC now points to subroutine destination)

Description:

In execution of the JSR, the old contents of the specified register (the "LINKAGE POINTER") are automatically pushed onto the processor stack and new linkage information placed in the register. Thus subroutines nested within subroutines to any depth may all be called with the same linkage register. There is no need either to plan the maximum depth at which any particular subroutine will be called or to include instructions in each routine to save and restore the linkage pointer. Further, since all linkages are saved in a reentrant manner on the processor stack, execution of a subroutine may be interrupted, and the same subroutine reentered and executed by an interrupt service routine.

Execution of the initial subroutine can then be resumed when other requests are satisfied. This process (called nesting) can proceed to any level.

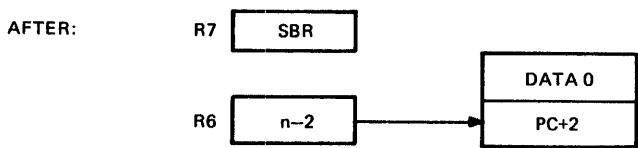
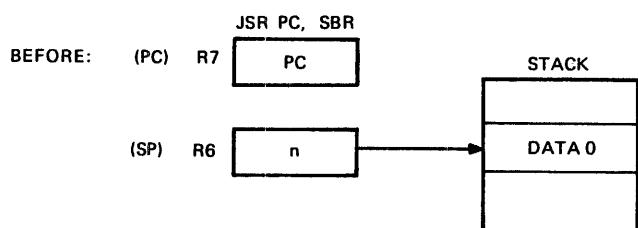
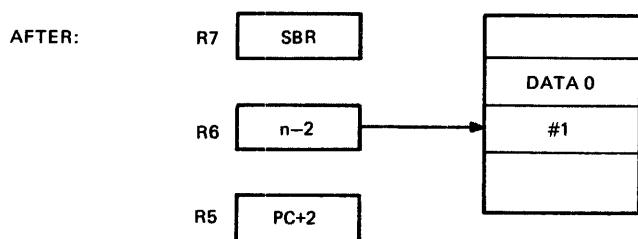
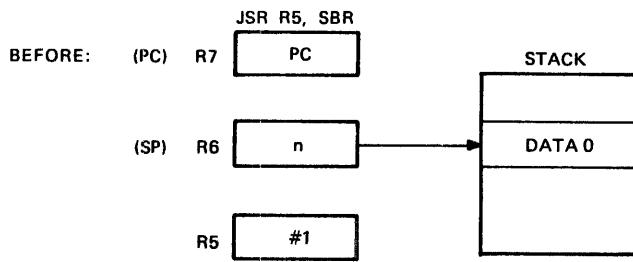
A subroutine called with a JSR reg,dst instruction can access the arguments following the call with either autoincrement addressing, (reg) +, (if arguments are accessed sequentially) or by indexed addressing, X(reg), (if accessed in random order). These addressing modes may also be deferred, @(reg)+ and @X(reg) if the parameters are operand addresses rather than the operands themselves.

JSR PC, dst is a special case of the microprocessor subroutine call suitable for subroutine calls that transmit parameters through the general registers. The SP and the PC are the only registers that may be modified by this call.

Another special case of the JSR instruction is JSR PC, @(SP) + which exchanges the top element of the processor stack and the contents of the program counter. Use of this instruction allows two routines to swap program control and resume operation when recalled where they left off. Such routines are called "co-routines."

Return from a subroutine is done by the RTS instruction. RTS reg loads the contents of reg into the PC and pops the top element of the processor stack into the specified register.

Example:		R5	R6	R7
	SBCALL : JSR R5, SBR	#1	n	SBCALL
	SBCALL+4 : ARG 1			
	ARG 2			
	.			
	.			
	SBCALL+2+2M: ARG M			
	CONT : NEXT INSTRUCTION	#1	n	CONT
	.			
	.			
	SBR : MOV(R5)+,dst1		SBCALL+4	n-2 SBR
	MOV(R5)+,dst2			
	.			
	MOV(R5)+,dst2			
	.			
	MOV(R5)+,dstM		SBCALL+2+2M	
	OTHER INSTRUCTIONS		CONT	
	EXIT : RTS R5		CONT	n-2 EXIT



MR-5250

Figure 7-90 JSR Example

RTS

RETURN FROM SUBROUTINE

00020R

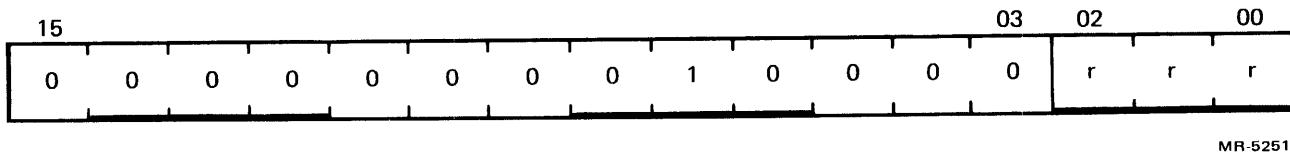


Figure 7-91 RTS

Operation: $PC \leftarrow (\text{reg})$
 $(\text{reg}) \leftarrow (\text{SP}) \uparrow$

Description: Loads contents of register into PC and pops the top element of the processor stack into the specified register.

Return from a non-reentrant subroutine is typically made through the same register that was used in its call. Thus, a subroutine called with a JSR PC, dst exits with an RTS PC and a subroutine called with a JSR R5, dst, may pick up parameters with addressing modes (R5) +, X(R5), or @X(R5) and finally exits, with an RTS R5.

Example:

RTS R5

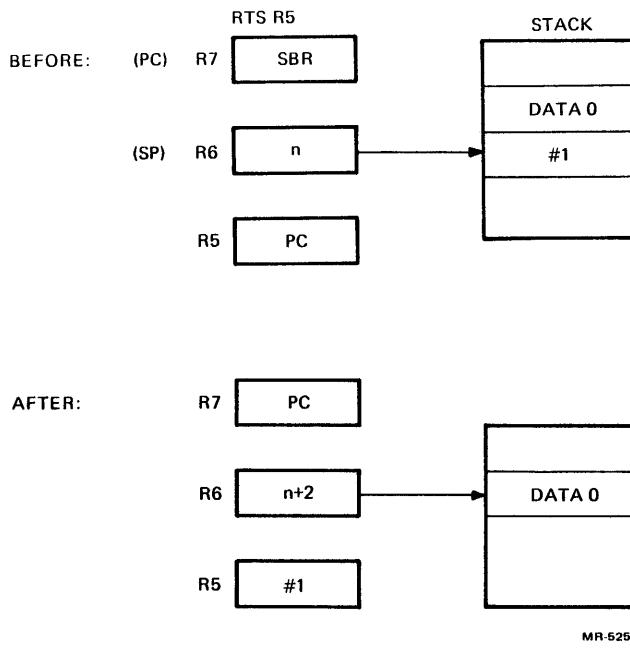
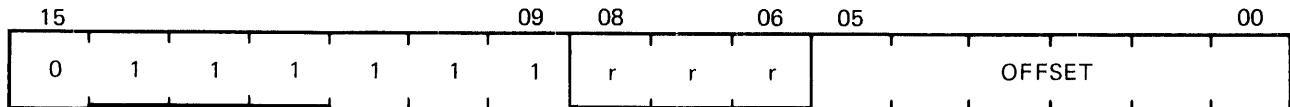


Figure 7-92 RTS Example

SOB

SUBTRACT ONE AND BRANCH (IF $\neq 0$)

077RNN



MR-5253

Figure 7-93 SOB

Operation: $(R) \leftarrow (R) - 1$; if this result $\neq 0$ then $PC \leftarrow PC - (2 \times \text{offset})$, if $(R) = 0$ then $PC \leftarrow PC$

Condition Codes: Unaffected

Description: The register is decremented. If it is not equal to zero, twice the offset is subtracted from the PC (now pointing to the following word). The offset is interpreted as a six bit positive number. This instruction provides a fast, efficient method of loop control. Assembler syntax is:

SOB R,A

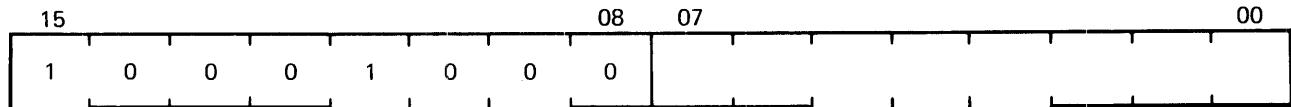
where A is the address to which transfer is to be made if the decremented R is not equal to 0. Note that the SOB instruction cannot be used to transfer control in the forward direction.

7.2.5.5 Traps -- Trap instructions provide for calls to emulators, I/O monitors, debugging packages, and user-defined interpreters. A trap is effectively an interrupt generated by software. When a trap occurs the contents of the current Program Counter (PC) and processor Status Word (PS) are pushed onto the processor stack and replaced by the contents of a two-word trap vector containing a new PC and new PS. The return sequence from a trap involves executing an RTI or RTT instruction which restores the old PC and old PS by popping them from the stack. Trap instruction vectors are located at permanently assigned fixed addresses.

EMT

EMULATOR TRAP

104000–104377



MR-5254

Figure 7-94 EMT

Operation: $\downarrow(SP) \leftarrow PS$
 $\downarrow(SP) \leftarrow PC$
 $PC \leftarrow (30)$
 $PS \leftarrow (32)$

Condition Codes: N: loaded from trap vector
Z: loaded from trap vector
V: loaded from trap vector
C: loaded from trap vector

Description: All operation codes from 104000 to 104377 are EMT instructions and may be used to transmit information to the emulating routine (e.g., function to be performed). The trap vector for EMT is at address 30. The new PC is taken from the word at address 30; the new processor status (PS) is taken from the word at address 32.

Caution: EMT is used frequently by DEC system software and is therefore not recommended for general use.

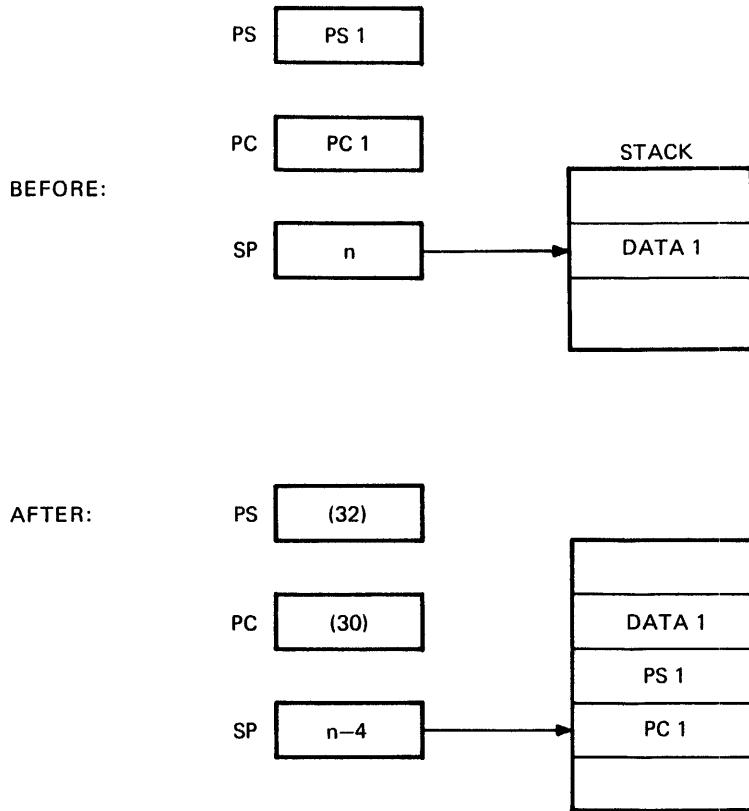


Figure 7-95 EMT Example

TRAP

TRAP

104400–104777

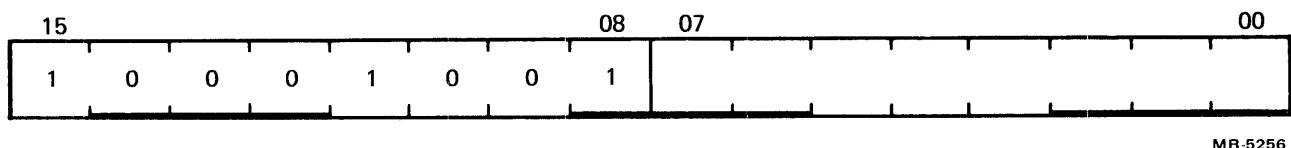


Figure 7-96 TRAP

Operation: $\downarrow(\text{SP}) \leftarrow \text{PS}$
 $\downarrow(\text{SP}) \leftarrow \text{PC}$
 $\text{PC} \leftarrow (34)$
 $\text{PS} \leftarrow (36)$

Condition Codes: N: loaded from trap vector
 Z: loaded from trap vector
 V: loaded from trap vector
 C: loaded from trap vector

Description: Operation codes from 104400 to 104777 are TRAP instructions. TRAPs and EMTs are identical in operation, except that the trap vector for TRAP is at address 34.

Note: Since DEC software makes frequent use of EMT, the TRAP instruction is recommended for general use.

BPT

BREAKPOINT TRAP

000003

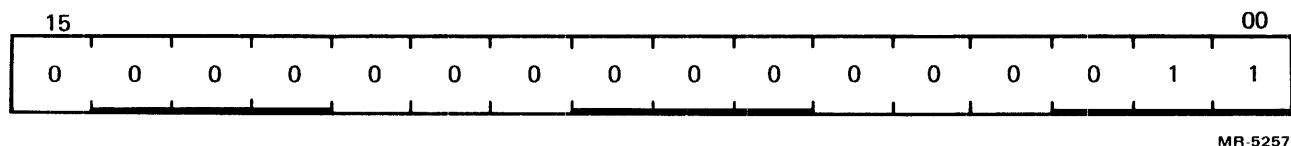


Figure 7-97 BPT

Operation: $\downarrow(\text{SP}) \leftarrow \text{PS}$
 $\downarrow(\text{SP}) \leftarrow \text{PC}$
 $\text{PC} \leftarrow (14)$
 $\text{PS} \leftarrow (16)$

Condition Codes: N: loaded from trap vector
 Z: loaded from trap vector
 V: loaded from trap vector
 C: loaded from trap vector

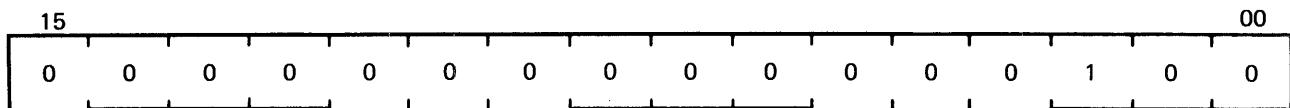
Description: Performs a trap sequence with a trap vector address of 14. Used to call debugging aids. The user is cautioned against employing code 000003 in programs run under these debugging aids.

(No information is transmitted in the low byte.)

IOT

INPUT/OUTPUT TRAP

000004



MR-5258

Figure 7-98 IOT

Operation: $\downarrow(SP) \leftarrow PS$
 $\downarrow(SP) \leftarrow PC$
 $PC \leftarrow (20)$
 $PS \leftarrow (22)$

Condition Codes: N: loaded from trap vector
Z: loaded from trap vector
V: loaded from trap vector
C: loaded from trap vector

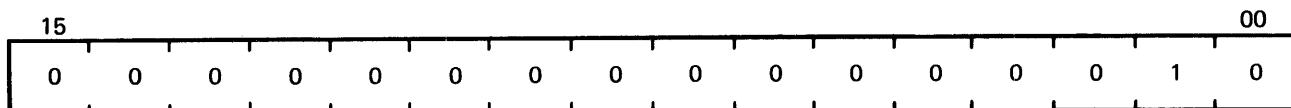
Description: Performs a trap sequence with a trap vector address of 20.

(No information is transmitted in the low byte.)

RTI

RETURN FROM INTERRUPT

000002



MR-5259

Figure 7-99 RTI

Operation: $PC \leftarrow (SP) \uparrow$
 $PS \leftarrow (SP) \uparrow$

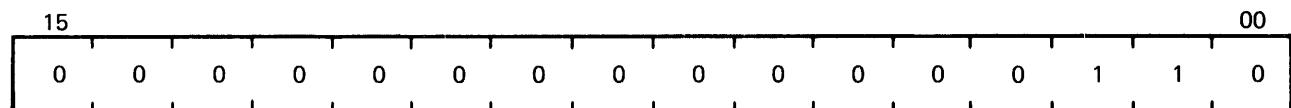
Condition Codes: N: loaded from processor stack
Z: loaded from processor stack
V: loaded from processor stack
C: loaded from processor stack

Description: Used to exit from an interrupt or TRAP service routine. The PC and PS are restored (popped) from the processor stack. If a trace trap is pending, the first instruction after RTI will not be executed prior to the next T trap.

RTT

RETURN FROM INTERRUPT

000006



MR-5260

Figure 7-100 RTT

Operation: $PC \leftarrow (SP) \uparrow$
 $PS \leftarrow (SP) \uparrow$

Condition Codes: N: loaded from processor stack
Z: loaded from processor stack
V: loaded from processor stack
C: loaded from processor stack

Description: Operation is the same as RTI except that it inhibits a trace trap while RTI permits trace trap. If new PS has T bit set, trap will occur after execution of first instruction after RTT.

7.2.5.6 Reserved Instruction Traps -- These are caused by attempts to execute instruction codes reserved for future processor expansion (reserved instructions) or instructions with illegal addressing modes (illegal instructions). Order codes not corresponding to any of the instructions described are considered to be reserved instructions. JMP and JSR with register mode destinations are illegal instructions, and trap to vector address four. Reserved instructions trap to vector address 10.

7.2.5.7 Halt Interrupt -- This is caused by the -HALT line. The -HALT interrupt saves the PC and PS and goes to the restart address with PS = 340.

7.2.5.8 Trace Trap -- Trace Trap is enabled by bit four of the PS and causes processor traps at the end of instruction execution. The instruction that is executed after the instruction that set the T-bit will proceed to completion and then trap through the trap vector at address 14. Note that the trace trap is a system debugging aid and is transparent to the general programmer.

7.2.5.9 Power Failure Interrupt -- Occurs when -PF line is asserted. Vector for power failure is location 24 and 26. Trap will occur if an RTI instruction is executed in power fail service routine.

7.2.5.10 Interrupts -- Refer to Table 5-3.

NOTE

Bit four of the PS can only be set indirectly by executing an RTI or RTT instruction with the desired PS on the stack.

7.2.5.11 Special Cases T-bit -- The following are special cases of the T-bit.

NOTE

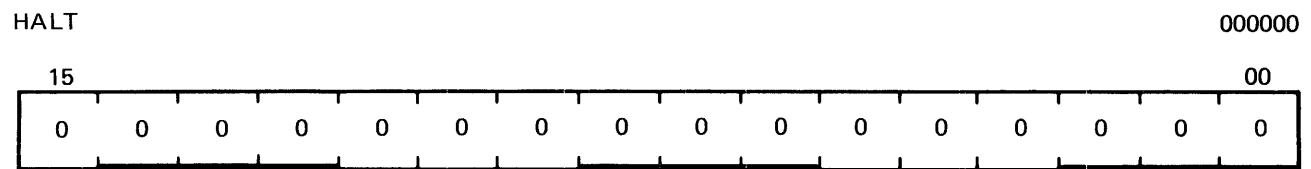
The traced instruction is the instruction after the one that set the T-bit.

1. An instruction that cleared the T-bit -- Upon fetching the traced instruction, an internal flag, the trace flag, was set. The trap will still occur at the end of execution of this instruction. The status word on the stack, however, will have a clear T-bit.
2. An instruction that set the T-bit -- Since the T-bit was already set, setting it again has no effect. The trap will occur.
3. An instruction that caused an Instruction Trap -- The instruction trap is performed and the entire routine for the service trap is executed. If the service routine exits with an RTI or in any other way restores the stacked status word, the T-bit is set again, the instruction following the traced instruction is executed and, unless it is one of the special cases noted previously, a trace trap occurs.
4. Interrupt Trap Priorities -- In case of multiple trap and interrupt conditions, occurring simultaneously, the following order of priorities is observed (from high to low):

Halt Line
Power Fail Trap
Trace Trap
Internal Interrupt Request
External Interrupt Request
Instruction Traps

7.2.6 Miscellaneous Instructions

HALT



MR-5261

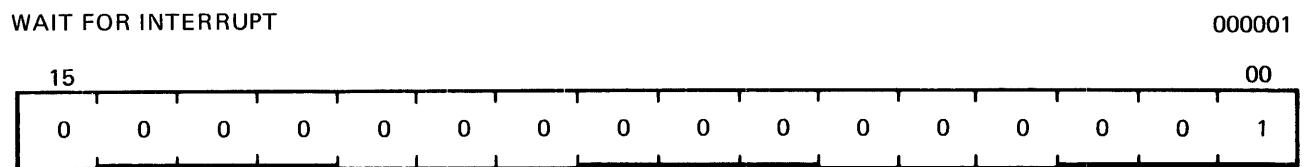
Figure 7-101 HALT

Operation: $\downarrow(\text{SP}) \leftarrow \text{PS}$
 $\downarrow(\text{SP}) \leftarrow \text{PC}$
 $\text{PC} \leftarrow \text{restart address}$
 $\text{PS} \leftarrow 340$

Condition Codes: Unaffected

Description: The processor goes to the restart address after placing the current PC and PS on the stack. PS is initialized to 340.

WAIT



MR-5262

Figure 7-102 WAIT

Condition Codes: Unaffected

Description: In WAIT, as in all instructions, the PC points to the next instruction following the WAIT instruction. Thus when an interrupt causes the PC and PS to be pushed onto the processor stack, the address of the next instruction following the WAIT is saved. The exit from the interrupt routine (i.e., execution of an RTI instruction) will cause resumption of the interrupted process at the instruction following the WAIT.

RESET

RESET EXTERNAL BUS

000005

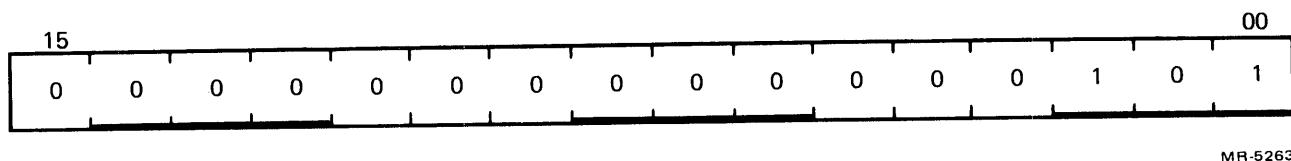


Figure 7-103 RESET

Condition Codes: Unaffected

Description: The -BCLR line is asserted and the mode register is loaded. -BCLR is negated and an ASPI transaction takes place. PC, PS, and R0--R5 are not affected.

MFPT

MOVE FROM PROCESSOR TYPE WORD

000007

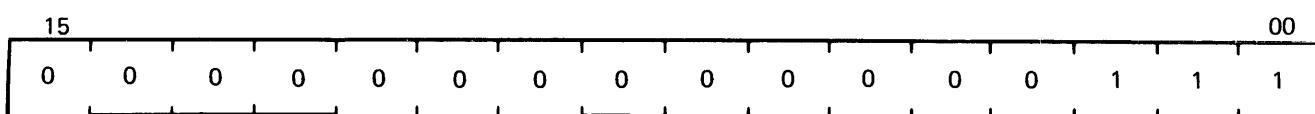


Figure 7-104 MFPT

Operation: R0<4

Condition Codes: Unaffected

Description: The number four is placed in R0 indicating to the system software that the processor type is SBC-11/21.

7.2.7 Condition Code Operators

CLN	SEN
CLZ	SEZ
CLV	SEV
CLC	SEC
CCC	SCC

CONDITION CODE OPERATORS

0002XX

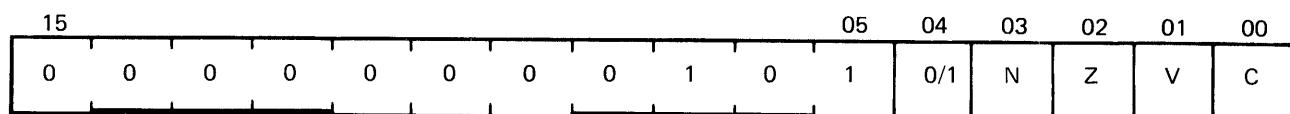


Figure 7-105 Condition Code Operators

Description: Set and clear condition code bits. Selectable combinations of these bits may be cleared or set together. Condition code bits corresponding to bits in the condition code operator (Bits 0--3) are modified according to the sense of bit four, the set/clear bit of the operator; i.e., set the bit specified by bit zero, one, two, or three, if bit four is a one. Clear corresponding bits if bit 4 = 0.

Mnemonic	Operation	OP Code
CLC	Clear C	000241
CLV	Clear V	000242
CLZ	Clear Z	000244
CLN	Clear N	000250
SEC	Set C	000261
SEV	Set V	000262
SEZ	Set Z	000264
SEN	Set N	000270
SCC	Set all CCs	000277
CCC	Clear all CCs	000257
	Clear V and C*	000243
NOP	No Operation	000240

*Combinations of the above set or clear operations may be ORed together to form combined instructions. Clear V and C represents CLC (241) ORed with CLV (code 242).

CHAPTER 8 THEORY OF OPERATION

8.0 GENERAL

This chapter provides a detailed explanation of the SBC-11/21 hardware operation from the point of view of the logic designer. It will be useful for troubleshooting the device to the chip level.

NOTE

The negated or inverse signal is designated by the "-" character. For example, RAS is normally low and asserted high when activated and the -RAS would be normally high and asserted low when activated. This convention is used throughout this chapter. The LSI-11 bus signals will remain consistent with the standard bus conventions.

The SBC-11/21 functional block diagram (Figure 8-1) provides an overview of the module functions and how they are related. The main components of the single board computer are shown on sheet 1. The single board computer is comprised of the microprocessor interconnected to the Serial Line Units, RAM memory, ROM memory and the Parallel I/O Interface via the on-board TDAL bus. The TDAL bus can access the LSI-11 bus (BDAL bus) by the Bus Control function shown by broken lines and is for reference only. Also on sheet 1 is the Address bus, the Memory Address Decode function and the Interrupt Control function.

The microprocessor support functions and the LSI-11 interfacing functions are described on sheet 2. The microprocessor is shown by broken lines for reference only. The Power Up, Clock, Clock Control, Ready, DMA and Halt functions are used by the microprocessor. The IAK Data In, Sync, Read/Write, Reply Timeout and Bus Control functions are used to interface the LSI-11 bus to the microprocessor.

The functional descriptions used in this chapter will first define the microprocessor and the input/output signals associated with its operation. The support functions, the LSI-11 bus interface functions and the remaining single board computer devices are also described in detail.

8.1 MICROPROCESSOR

The microprocessor is contained within a 40-pin LSI chip shown in Figure 8-2. There are eight 16-bit general purpose registers (R0--R7) of which R6 operates as the Stack Pointer (SP) and R7 operates as the microprocessor Program Counter (PC). A special purpose status register contains the current Processor Status Word

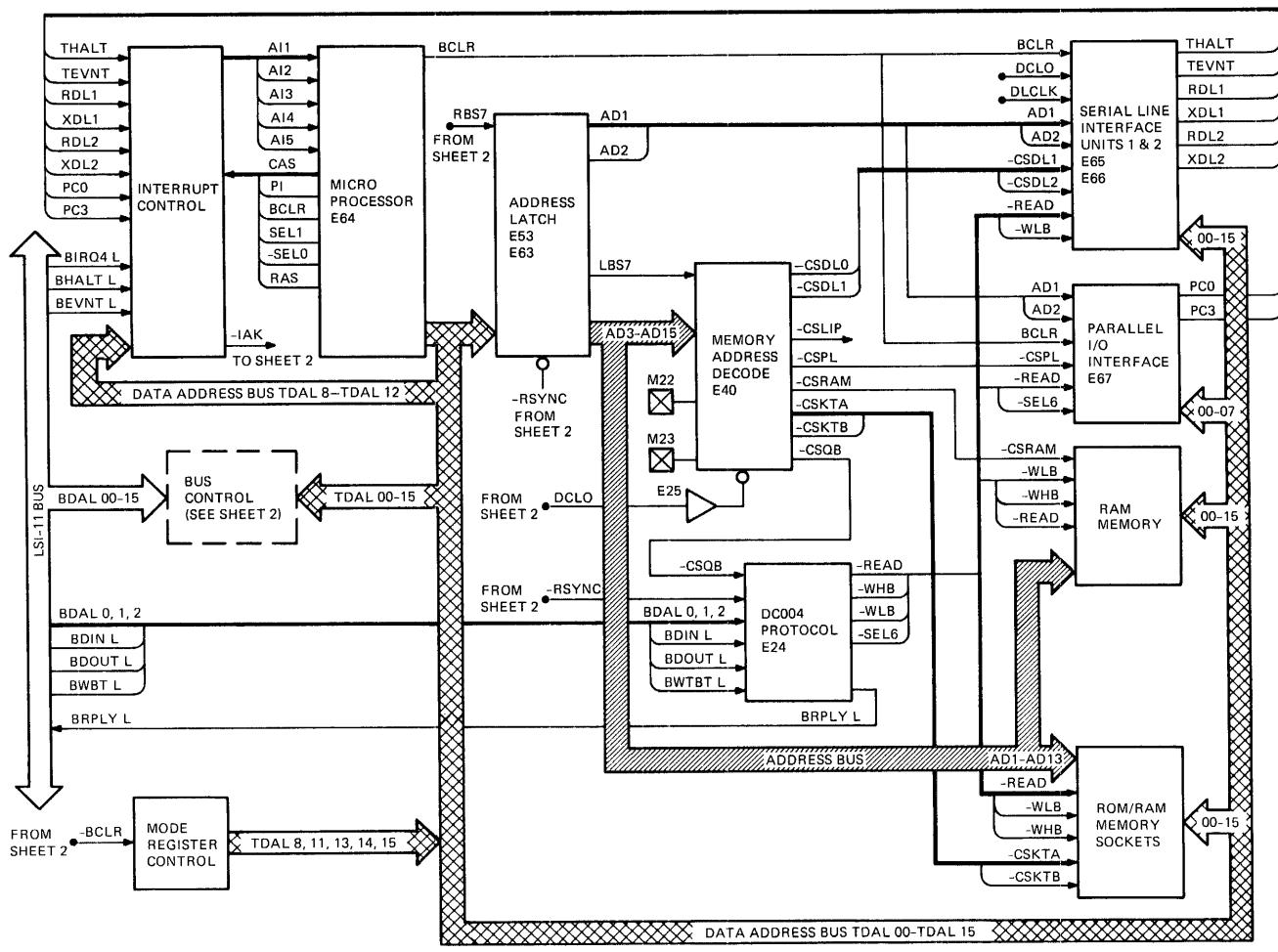


Figure 8-1 SBC-11/21 Functional Block Diagram
(Sheet 1 of 2)

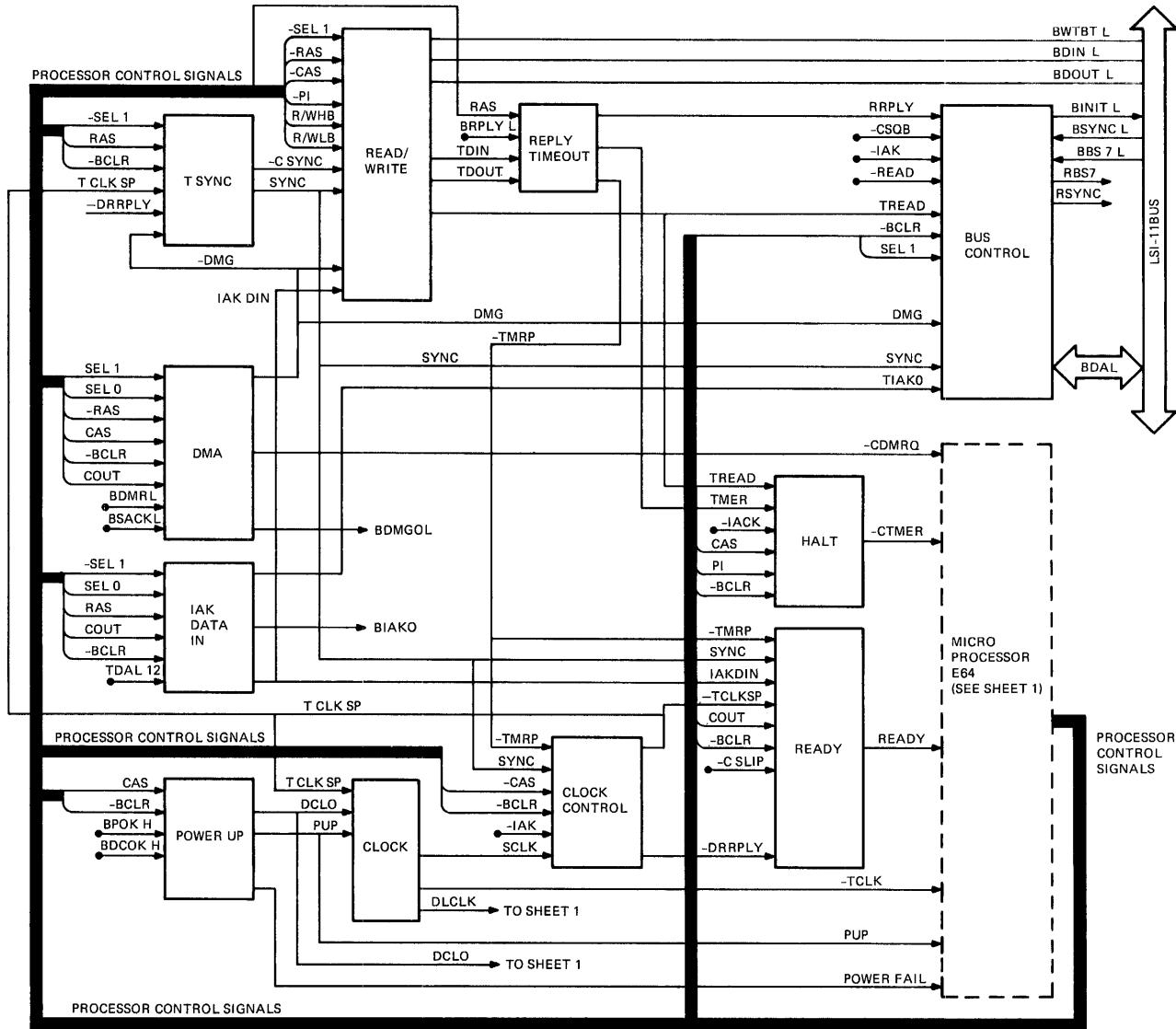
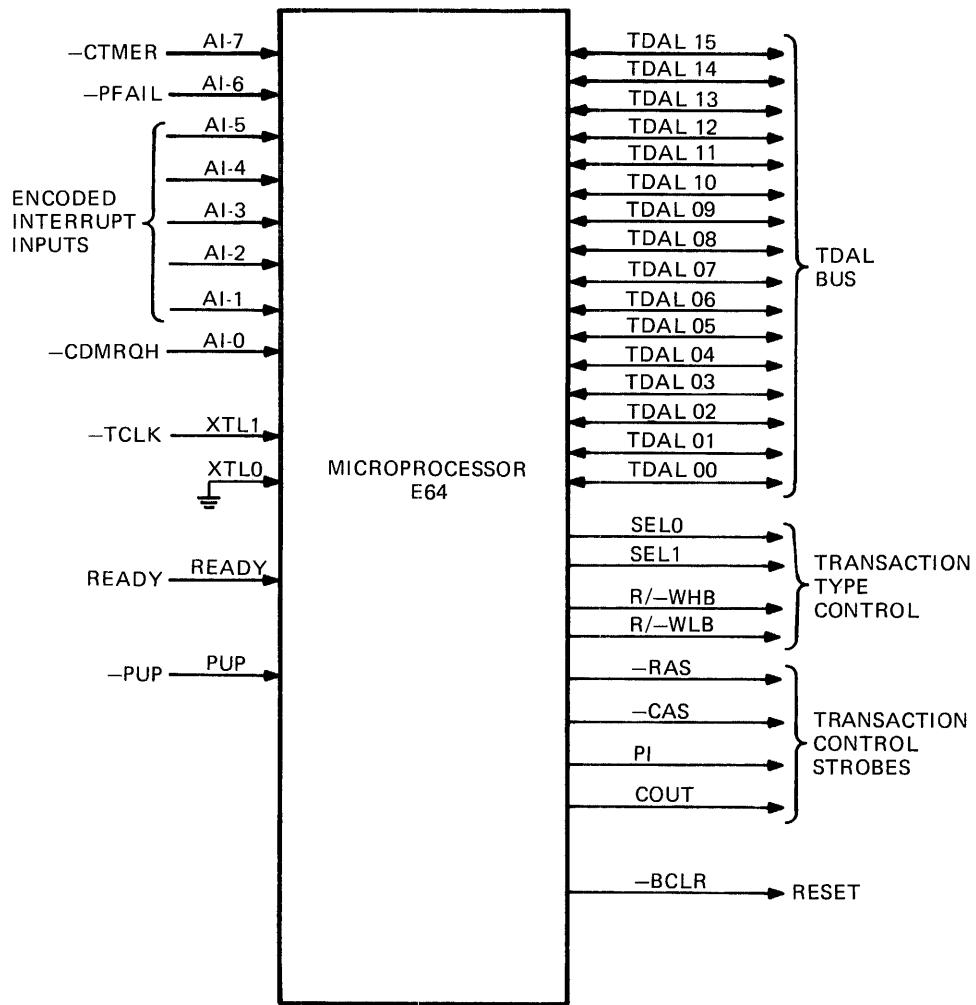


Figure 8-1 SBC-11/21 Functional Block Diagram
(Sheet 2 of 2)



MR-6634

Figure 8-2 SBC-11/21 Microprocessor

(PSW). The operating characteristics of the microprocessor are affected by the mode register. It is discussed in detail in section 8.2.

8.1.1 Microprocessor Initialization

The microprocessor will initialize the SBC-11/21 module during the power up sequence or whenever the RESET instruction is executed.

8.1.1.1 RESET -- The RESET instruction asserts the -BCLR output and this clears or resets the control logic of the module to an initial state. The microprocessor loads the Mode Register from the TDAL bus with the Mode Register Control data. The LSI-11 bus transceivers are disabled when -BCLR is asserted. The RCVIE bit of the RCSRs and the XMITIE, MAINT and XMITBRK bits of the XCSRs are reset in the Serial Line Units (SLU). The port C buffer output

lines of the Parallel I/O are set high. Also, if port A and port B buffers are output to the connectors, they are set high. The LED is turned off during reset. The -BCLR output is then negated and an Assert Priority In (ASPI) transaction is performed to service any Interrupts or DMA requests. The RESET instruction does not disturb the PSW or any internal registers.

8.1.1.2 Power Up -- The Power Up (PUP) input goes from low to high when the 5.0 V power is first applied and this initiates the power up sequence. The -BCLR output is asserted. The module is cleared and reset in the same manner described for the RESET instruction except the Serial Line Units (SLU) registers are completely reset. After a delay, the BDCOK and BPOK are asserted, PUP is negated, and the -BCLR output goes high. The microprocessor then performs ten bus NOP transactions. The processor loads the starting address into the Program Counter (R7), location 376 into the Stack Pointer (R6) and the Processor Status Word is set to 340. An Assert Priority In (ASPI) transaction is performed to service any interrupts or DMA requests before the first instruction is fetched.

The PUP input normally remains low for all operations. If PUP is asserted high, the present transaction is terminated and the internal registers go to an undetermined state. The TDAL bus, the interrupt inputs and the microprocessor control signals will all go to an initial reset state.

8.1.2 Clock Input

The -TCLK input is a 4.9152 MHz clock that comes from the 19.6608 MHz crystal oscillator. This clock input is used for the internal time base of the microprocessor and the source of the clock output (COUT). COUT is pulsed once for every microcycle and a microcycle can represent either three or four -TCLK input pulses depending on the type of transaction. The microprocessor will halt or stop whenever the -TCLK input is disabled.

8.1.3 Ready Input

The READY input is normally high and will not interfere with the microprocessor transactions in any way. However, when this input is held low, a single microcycle slip occurs during every transaction. When READY is clocked with COUT, while RAS is asserted, then the microprocessor will slip a microcycle every time the input is pulsed. This allows the microprocessor to be placed in an idle or wait state until a peripheral device has either received or asserted data on the bus.

8.1.4 Microprocessor Control Signals

The microprocessor controls the functions of the SBC-11/21 through the use of eight microprocessor control signals. These signals are listed below with a description of the functions they perform. The RAS, CAS, PI, COUT, and BCLR are transaction control strobes used for logic transitions. The R/-WLB, R/-WHB, SEL0 and SEL1 are steady state logic signals used as transaction type control signals.

8.1.4.1 Row Address Strobe (RAS) -- The leading edge of the signal is used to acknowledge that the address is stable on the TDAL bus during Read/Write and Fetch transactions. During interrupt transactions the leading edge strobes the interrupt acknowledge data onto the TDAL 12--08 bus lines.

8.1.4.2 Column Address Strobe (CAS) -- The trailing edge of the signal is used to acknowledge that data on the TDAL bus lines during Read and Fetch transactions was read by the microprocessor. For Write transactions it is used to acknowledge that the microprocessor data will be removed after a specified time.

The leading edge is used to request that READ data be placed on the TDAL bus, and to strobe interrupt requests into latches which are read during the assertion of PI.

8.1.4.3 Priority In (PI) -- The leading edge of the signal is used to acknowledge that data on the TDAL bus lines during Write transactions is stable. The leading edge is also used to enable the microprocessor to read the interrupt inputs AI-0 to AI-7 and to initiate IAK, RESTART, POWER FAIL, or DMA transactions.

8.1.4.4 Read/Write (R/-WHB and R/-WLB) -- These two signals control the Read/Write and Fetch transactions by enabling the TDIN, TDOUT and TWTBT control signals. For Read and Fetch transactions, both are asserted high and enable the TDIN control circuits. During Write transactions the TDOUT and TWTBT control circuits are enabled when either or both signals are asserted low. If only one is asserted low the TWTBT control circuits are enabled by the leading edge of CAS and a Write byte transaction occurs for either high byte or low byte.

8.1.4.5 Select Output Flags (SEL0 and SEL1) -- These two signals indicate the transaction being performed. When both are low, a Read, Write, ASPI or NOP transaction is selected and when both are high, a DMA transaction is selected. When SEL1 is low and SEL0 high the Fetch transaction is selected and when SEL1 is high and SEL0 is low an IAK transaction is being performed.

8.1.4.6 Bus Clear (BCLR) -- This signal is used to reset the control logic and generate BINIT. It is only asserted during the Power Up sequence and during the execution of a RESET instruction.

8.1.4.7 Clock Out (COUT) -- This signal is asserted once for every microcycle and is used to time the microprocessor transactions.

8.1.5 Microprocessor Transactions

The microprocessor performs six types of transactions to support the instruction set, direct memory access, and the interrupt structure. The types of transactions are Fetch Read, Write, DMA, IAK, ASPI, and Bus NOP. A normal Fetch/Read or IAK transaction

requires either one or two microcycles and extended transactions can take as many as required before a timeout occurs. The COUT signal is asserted once for every microcycle. The transactions are used to transfer information and data via the TDAL bus which interconnects all local devices and connects them to the LSI-11 bus interface. The operation of the transactions is described below.

8.1.5.1 Fetch/Read -- This transaction is used to either fetch an instruction or read data for the microprocessor. The data may originate from the on-board memory, I/O device, or from the LSI-11 bus. The microprocessor control signals for the transaction are described by Figure 8-3. The R/-WLB and R/-WHB control signals are asserted. The SEL0 output is high and the SEL1 output is low for the Fetch transaction and both of these outputs are low for the Read transaction.

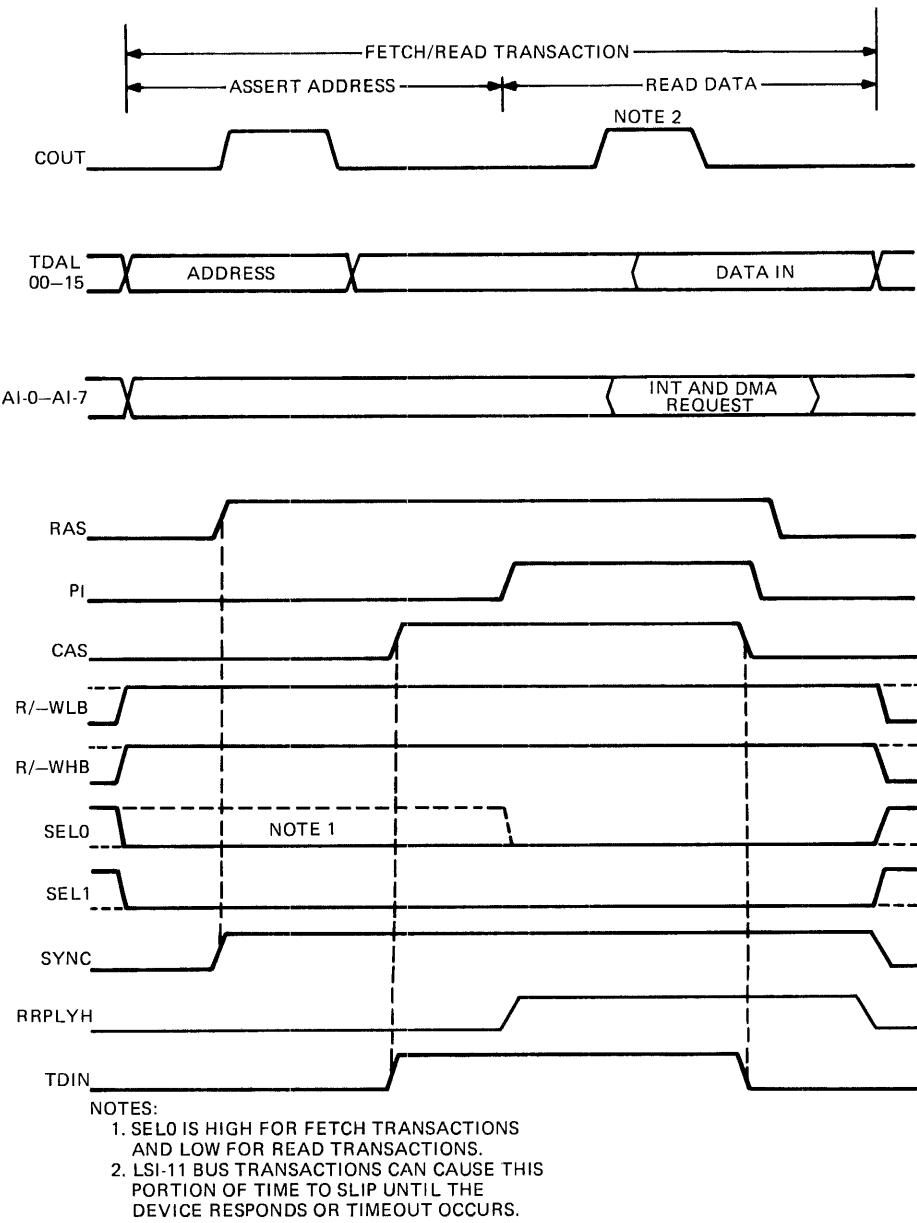
The following sequence of events then takes place.

- o The microprocessor places the address onto the TDAL bus when the transaction is initiated and it is latched into the Memory Address circuits by the assertion of SYNC.
- o The data is received on the TDAL bus after RRPLY is received. The microprocessor accepts the data and negates TDIN.
- o Interrupt and DMA requests are latched by CAS, set up while PI is asserted, and latched into the microprocessor when PI is negated.

NOTE

A write transaction is always preceded by a read transaction except when the microprocessor pushes onto the stack. Therefore, each write consists of at least four microcycles, assert address, read data, assert address, and write data.

8.1.5.2 Write -- This transaction is used to write data from the microprocessor to memory, a local I/O device or an LSI-11 bus peripheral device. The microprocessor control signals for the transaction are described by Figure 8-4. The R/-WLB and R/-WHB control signals are asserted low when writing a word and for writing a byte, either the high or byte signal is asserted. Both SEL0 and SEL1 control signals are negated.



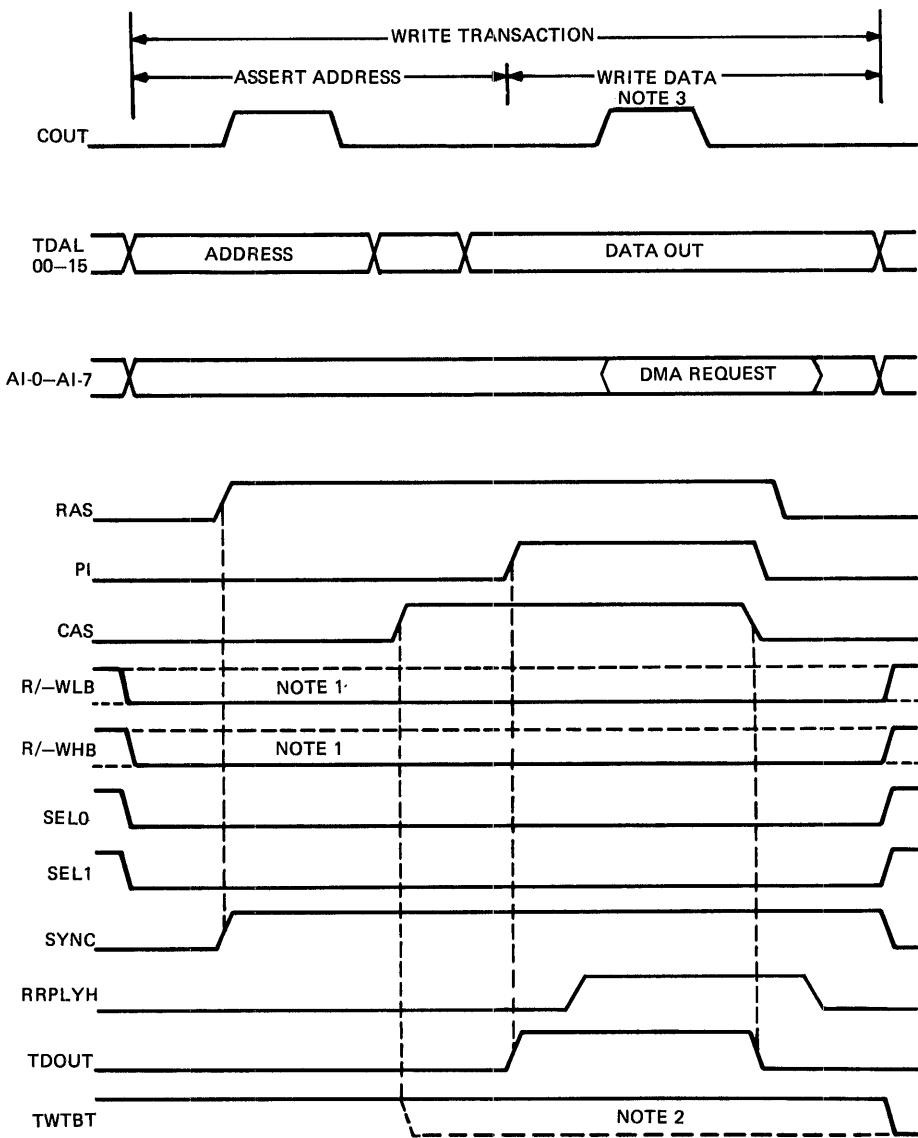
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Figure 8-3 Fetch/Read Transaction

The following sequence of events take place.

- The microprocessor places the address on the TDAL bus and the state of the R/W lines causes TWTBT to be asserted. The address is latched into the Memory Address circuits by the assertion of SYNC.
- When CAS is asserted, TWTBT is negated for word transactions and left asserted for byte transactions.

- The data is placed on the TDAL bus before TDOUT is asserted and is written into the addressed location when TDOUT is negated.
- When the addressed device negates BRPLY, the SYNC and TWTBT signals are cleared.
- The DMA requests are detected while PI is asserted and latched into the microprocessor when PI is negated. No other interrupts are read by the microprocessor during write transactions.



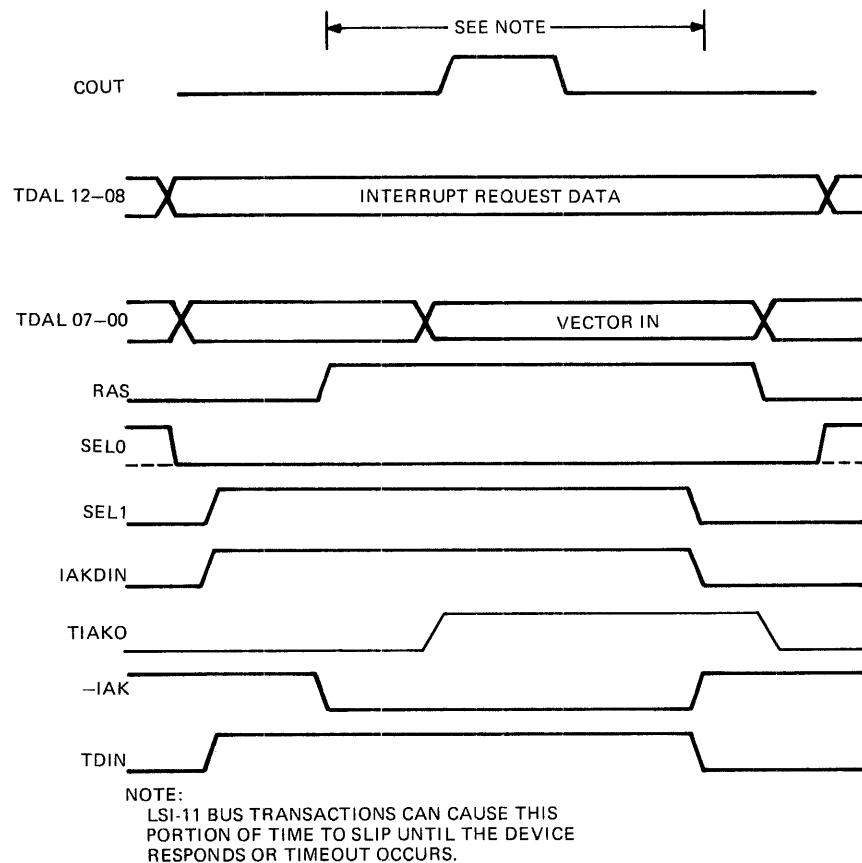
NOTES:

- R-/WLB OR R-/WHB CAN BE HIGH WHEN PERFORMING A WRITE BYTE TRANSACTION.
- TWTBT IS LOW FOR WORD TRANSACTIONS.
- LSI-11 BUS TRANSACTIONS CAN CAUSE THIS PORTION OF TIME TO SLIP UNTIL THE DEVICE RESPONDS OR TIMEOUT OCCURS.

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Figure 8-4 Write Transaction

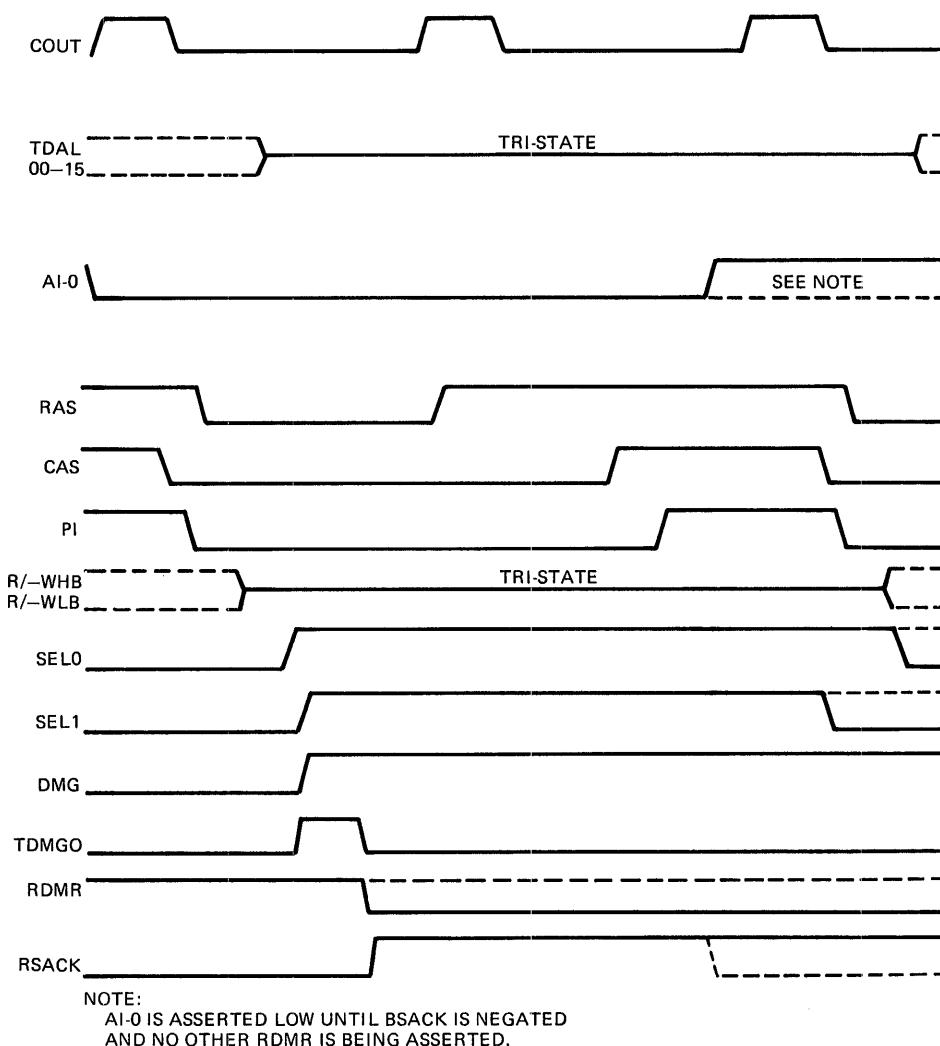
8.1.5.3 IAK -- The interrupt request was detected during a previous read transaction and the microprocessor initiates an IAK transaction as described by Figure 8-5. The R/-WHB and R/-WLB control signals are asserted high and CAS, PI, and SEL0 are asserted low for the transaction. The TDAL bits 12--08 represent the acknowledged input and are used to reset the interrupt request. For local interrupts TDAL bits 07--00 are ignored because the vector address is in the microprocessor. For LSI-11 bus interrupts, the vector address is read from the bus using TDAL bits 07--02. TDAL bus bit 12 is set low for this type of IAK and directs the control logic to initiate an LSI-11 bus IAK transaction. The TDIN signal is asserted for the transaction and the TIAK0 output acknowledges the interrupt. The requesting device then places the vector address on the low byte of the bus and asserts BRPLY. The microprocessor stops slipping microcycles, negates TDIN, and accepts the vector. It then negates TIAK0 on the trailing edge of RAS and continues to the next transaction.



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Figure 8-5 IACK Transaction

8.1.5.4 DMA -- The DMA request was read during a previous transaction. The microprocessor will acknowledge the request by tri-stating the TDAL bus as shown in Figure 8-6. The SEL0 and SEL1 outputs are asserted to indicate that the bus mastership has been relinquished. The transaction will continue with no interruptions until the DMA transfer is completed. The microprocessor will then negate SEL1 control output to indicate that it is resuming bus mastership, followed by the negation of SEL0 if the next transaction is not a fetch.



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Figure 8-6 DMA Transaction

8.1.5.5 ASPI -- The Assert Priority In (ASPI) transaction is used by the RESET and WAIT instructions or the power up sequence as shown described in Figure 8-7. The CAS and PI outputs are asserted to allow the microprocessor to recognize and latch any pending interrupts or DMA requests. The R/-WLB and R/-WLB outputs are asserted and the SEL0, SEL1, and RAS outputs are negated for the transaction.

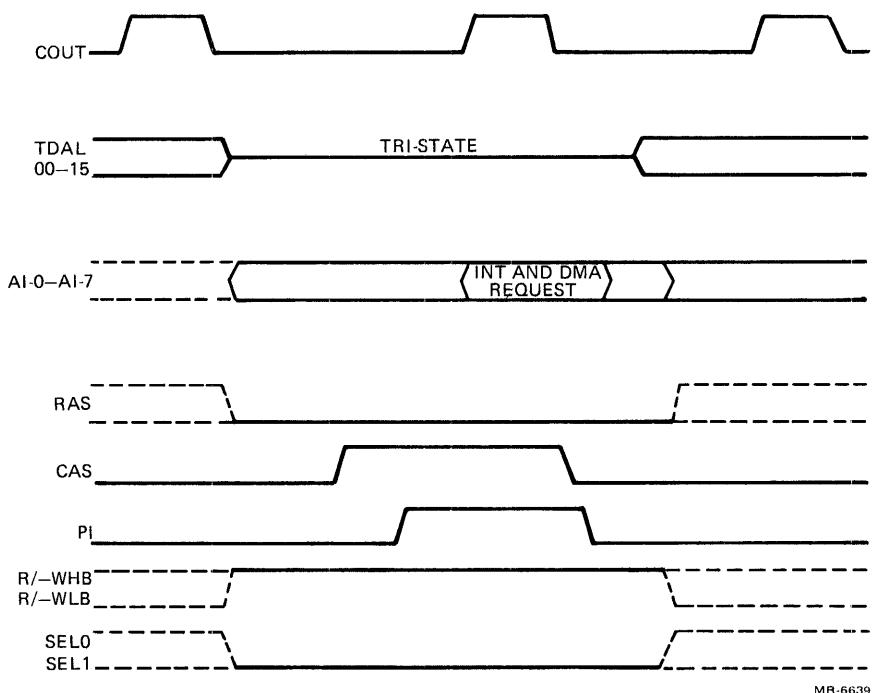


Figure 8-7 ASPI Transaction

8.1.5.6 NOP -- The Bus NOP transaction performs no operation and is used during the power-up sequence or if the programmer intentionally introduces a delay into the program. The AI-0 through AI-7 inputs are tri-stated to prevent interrupts. The R/-WLB and R/-WLB outputs are asserted and the SEL0 and SEL1 outputs are taken low. The RAS, CAS, and PI control strobes are inhibited during the transaction as shown in Figure 8-8.

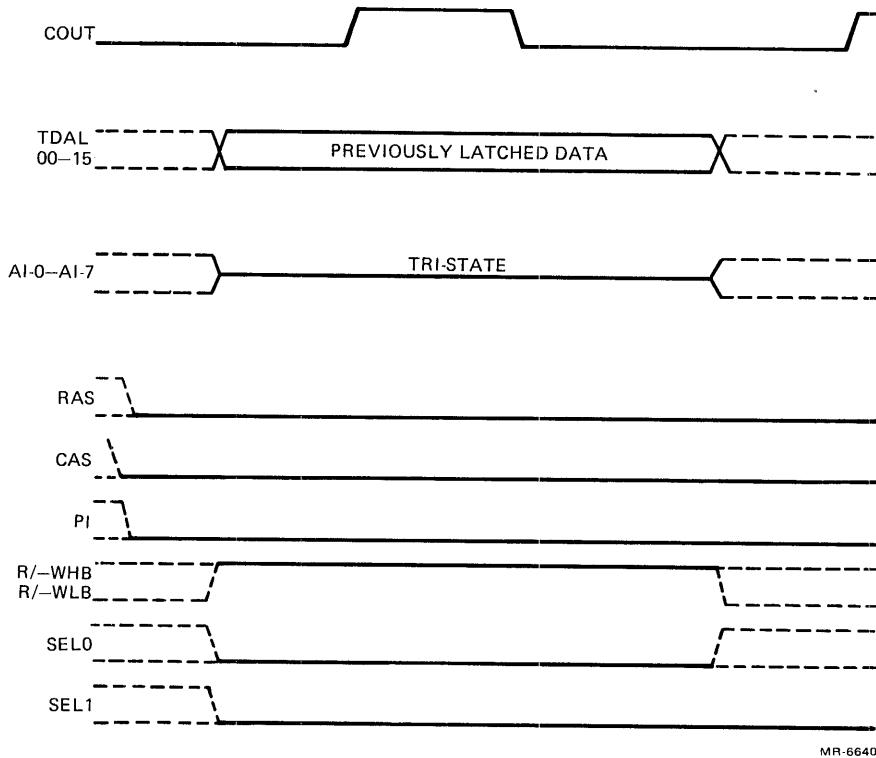


Figure 8-8 BUS NOP Transaction

8.2 MODE REGISTER CONTROL

The mode register is an internal microprocessor register used to define the operating mode of the microprocessor. The 16-bit mode register is written into from the TDAL 00--15 data lines during a power up sequence or when a reset instruction is executed. During this time the -BCLR output is low and the mode register is loaded. The mode register logic (Figure 8-9) has five tri-state drivers that are enabled when the -BCLR input goes low. TDAL bits 11 and 8 are factory set to force the microprocessor to operate in the following mode.

- The microprocessor clock mode is selected. The microprocessor pulses the COUT output once for every four XTLL input pulses during DMA and Interrupt transactions. For all other transactions, the microprocessor pulses the COUT output once for every three XTLL input pulses.
- The standard microcycle mode is selected. The standard microcycle uses four XTLL input periods for DMA and Interrupts and three XTLL input periods for all other transactions.

- o The normal Read/Write mode is selected. The normal Read/Write mode establishes the read/write control lines (R/-WLB and R/-WHB) prior to the assertion of -RAS and remain valid after the negation of -CAS.
- o The static memory mode is selected and therefore no dynamic memory chips may be installed on the module. The refresh function is disabled.
- o The memory addressing is limited to 64K bytes.
- o The bus consists of 16 bits.
- o The user mode is selected. This mode performs transactions with no automatic test of the Processor Status Word.

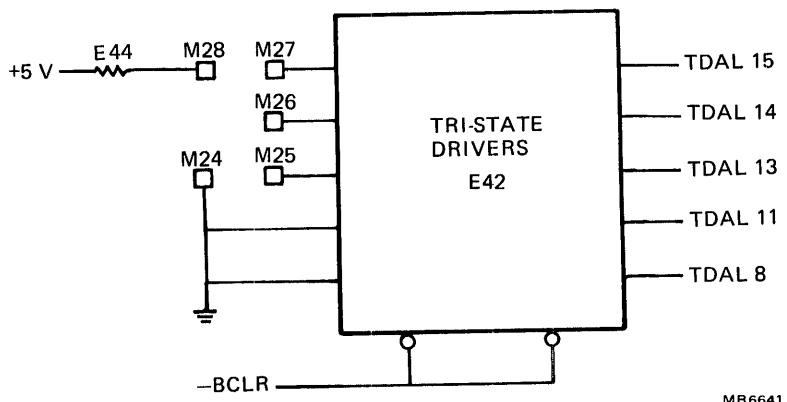


Figure 8-9 Mode Register Control

The status of the TDAL bits 13--15 are selected by the user and determine the start and restart addresses for the microprocessor. The start address is the location of the first fetch after power up and the restart address is the location of a fetch after a HALT instruction is executed or the assertion of the HALT interrupt. The wire wrap pins M27, M26, and M25 control the status of the TDAL 13--15 bits during the power up sequence. Wire wrap pin M28 is pulled up to +5 Vdc and represents a one, while wire wrap pin M24 is connected to ground and represents a zero. Pins M27, M26, and M25 are jumpered to either M28 or M24 according to the listing in **Table 8-1** to select the start and restart address for the microprocessor.

Table 8-1 Start Address Configurations

Wirewrap Pins			Start Address	Restart Address
Bit 15 M27	Bit 14 M26	Bit 13 M25		
1	1	1	172000	172004
1	1	0	173000	173004
1	0	1	000000	000004
1	0	0	010000	010004
0	1	1	020000	020004
0	1	0	040000	040004
0	0	1	100000	100004
0	0	0	140000	140004

Connection to M28 = 1
 Connection to M24 = 0

8.3 INTERRUPT CONTROL

The interrupt logic, as a block diagram, is illustrated in Figure 8-10. Studying this diagram will make the detailed explanation presented later in this section easier to follow.

The elements of this scheme include:

- o Five D flip-flops which latch five of the interrupt lines.

REVNT	Wire OR-ed TEVNT or BEVNT.
PARQST	Parallel I/O Port A interrupt request.
PBRQST	Parallel I/O Port B interrupt request.
BKRQ	Level 7, maskable interrupt, configurable.
HLTRQ	Produces CTMER, nonmaskable interrupt, configurable.

- o Twelve interrupt synchronizing latches, which latch the following signals.

Outputs of five latches described above

3 interrupt signals:

IRQ4	Level 4 LSI-11 bus interrupt
DMRQ	DMA request
PFAIL	Power fail nonmaskable interrupt

4 signals from the Interrupt Acknowledge Decoder, wire OR-ed with Interrupt Requests from SLUs.

RDL1	SLU1 Receiver Interrupt Request
XDL1	SLU1 Transmitter Interrupt Request
RDL2	SLU2 Receiver Interrupt Request
XDL2	SLU2 Transmitter Interrupt Request

The operation centers around eight microprocessor input lines, AI-0 to AI-7, driven by interrupt signals, either directly or indirectly, through the Interrupt Encoding PROM.

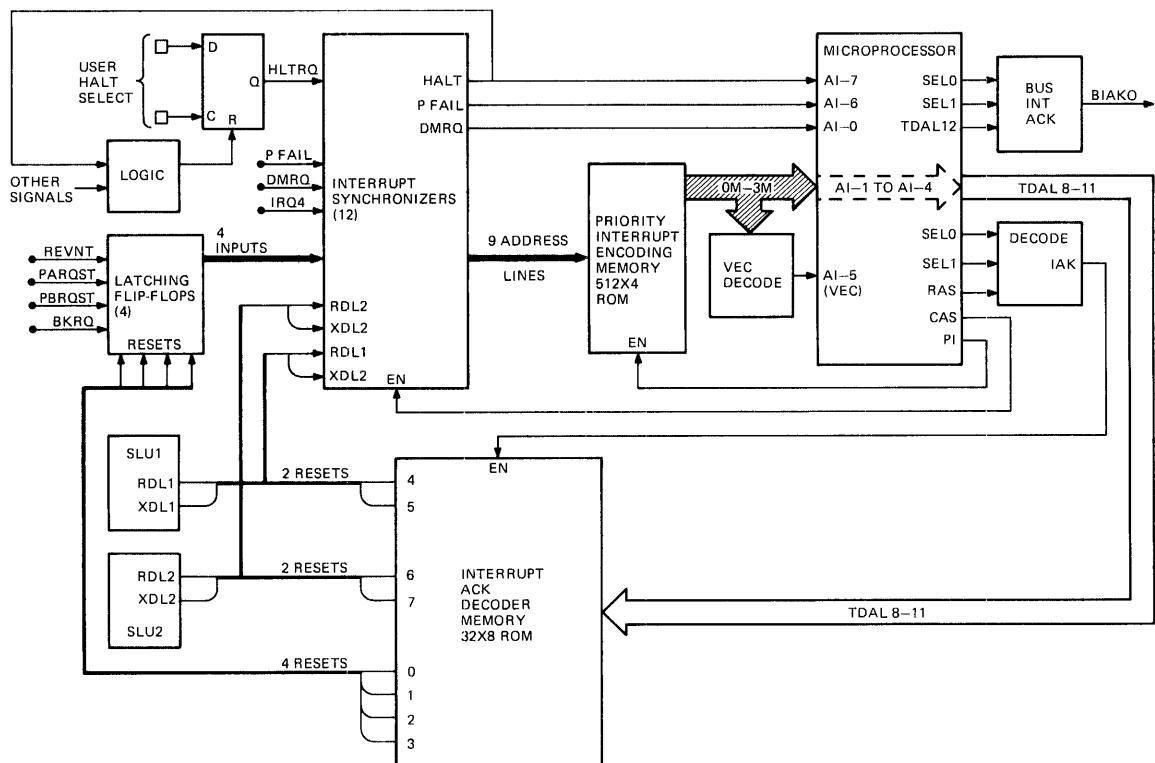
AI-0 serves as a DMA request line connected directly to DMRQ.

AI-1 to AI-4 are driven by the output of the Interrupt Encoder to request maskable interrupts.

AI-5 is driven by the VEC gate which detects the presence of the LSI-11 bus interrupt on the outputs of the Interrupt Encoder. It calls for a vector read transaction from the bus.

AI-6 is driven directly by the Power Fail input line to force a power fail trap.

AI-7 is driven directly by the HALT interrupt line to force a restart trap.



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Figure 8-10 SBC-11/21 Interrupt Logic

The microprocessor reads the AI-0 to AI-7 input lines, and arbitrates the interrupt priority according to Table 8-2. In addition, the state of AI-1 to AI-5 is reproduced on TDAL 12-8 lines during the Acknowledge cycle. TDAL 11-8 lines are used as an address in the Interrupt Acknowledge Decoder, which is a 32-byte PROM. Output bits 7-4 of that PROM are the previously mentioned SLU receive and transmitter interrupt requests (RDL1, RDL2, XDL1, XDL2) which are wire-ORed to reset the latched requests in the SLUs. TDALL2 reflects the state of the -VEC signal and is used in the LSI-11 bus protocol.

Bits 0-3 are used as reset signals for the four interrupt latches mentioned earlier.

With this general understanding of the interrupt scheme in mind, the reader can proceed into the more detailed explanation that follows.

8.3.1 Details of Interrupt Control Logic

The Interrupt Logic (Figure 8-11) receives the interrupt requests from the interface devices and applies them to the microprocessor. The microprocessor will acknowledge the highest priority interrupt, provided its priority is higher than the current microprocessor status word priority. There are nine interrupts

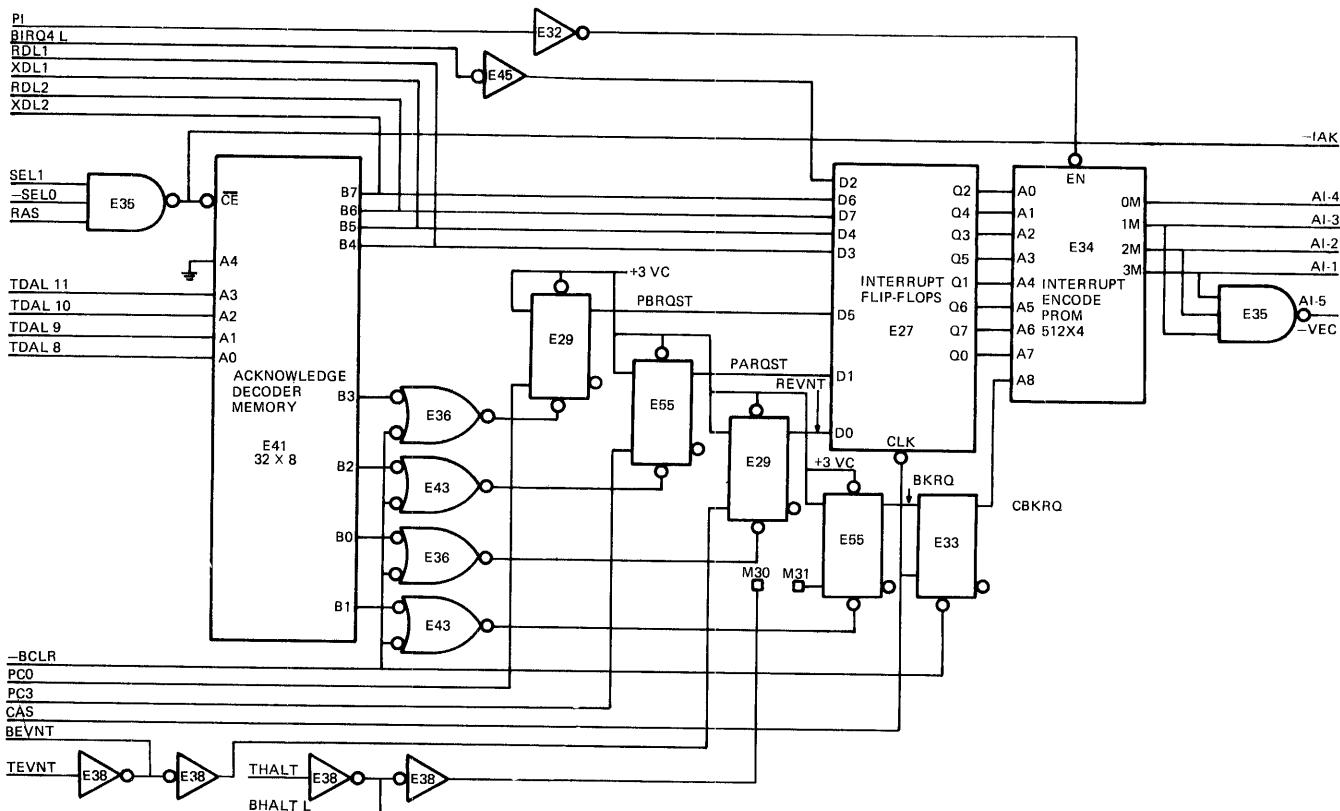


Figure 8-11 Interrupt Control

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available and either one or all can be inputs to the Interrupt synchronizers E27 and E33. Any interrupt is active when the signal goes high. Five of these inputs are latched and remain high until reset. Four interrupts are clocked through flip-flops E29, and E55 to maintain a high output. The enabled interrupts are clocked through the Interrupt flip-flops by CAS asserting during the present transaction. These outputs address the locations of the Interrupt Encode Memory which is enabled by the -PI input of the present transaction. The Interrupt Encode Memory outputs an interrupt code equivalent to the highest input priority.

The interrupt codes and their priority levels are listed by descending rank in Table 8-2. When the PI output is enabled, the

Table 8-2 Designated Interrupts

Interrupt Source	Input Signal	Priority Level	Coded Input					Vector Address
			AI-1	AI-2	AI-3	AI-4	AI-5	
HALT	HLTRQ	Non-maskable	X	X	X	X	X	Restart Address
Power Fail	PFAIL	Non-maskable	X	X	X	X	X	24
LSI-11 Bus Signal BHALT	BKRQ	7	0	0	0	0	1	140
LSI-11 Bus Signal BEVNT	REVNT	6	0	1	0	0	1	100
SLU2 REC	RDL2	5	1	0	0	0	1	120
SLU2 XMIT	XDL2	5	1	0	0	1	1	124
PARALLEL I/O B	PBRQST	5	1	0	1	0	1	130
PARALLEL I/O A	PARQST	5	1	0	1	1	1	134
SLU1 REC	RDL1	4	1	1	0	0	1	60
SLU1 XMIT	XDL1	4	1	1	0	1	1	64
LSI-11 Bus Signal BIRQ4	IRQ4	4	1	1	1	0	0	Read from LSI-11 Bus

NOTE: HALT and Power Fail interrupts are not generated by the coded inputs AI-1 to AI-5. All signals are listed in the order of descending priority.

microprocessor looks at the interrupt inputs and will follow the completion of a Read transaction initiate an IAK transaction for an interrupt with the proper priority. The coded input to the microprocessor is placed on the TDAL bus using bits 08 through 12. Bit 08 represents the AI-1 input and bit 11 represents the AI-4 input. These four TDAL bus bits are inputs to the Acknowledge Decoder Memory which is enabled when the microprocessor starts the IAK transaction and the -IAK input goes low. These inputs are decoded to determine which interrupt was granted and will output a low to negate that interrupt. The interrupt flip-flop is reset by the clear line for that interrupt switching the output of the selected AND gate low. The E66 and E65 transmitter and receiver interrupt lines are latched outputs and are reset by wire OR-ing and asserting low the output of the Acknowledge Decoder PROM. The LSI-11 bus interrupt is an exception to this process. This interrupt code enables the inputs of NAND gate E35 and the low output enables the -VEC (AI-5) input to the microprocessor. This input instructs the microprocessor to receive the vector address from the TDAL bus. TDAL 12 reflects the state of the -VEC input when the microprocessor acknowledges the interrupt and is used to determine that the LSI-11 bus Interrupt Acknowledge handshake protocol must be invoked. The LSI-11 bus interrupt is not reset by the Acknowledge Decoder PROM, but it should be reset when the TDIN and TIAKO signals are received by the bus device during the Interrupt Acknowledge Sequence.

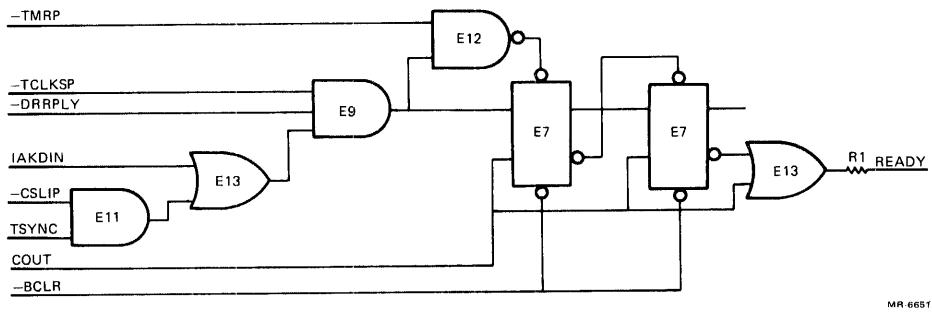
Before further discussion of the Interrupt system, the READY logic must be described.

NOTE

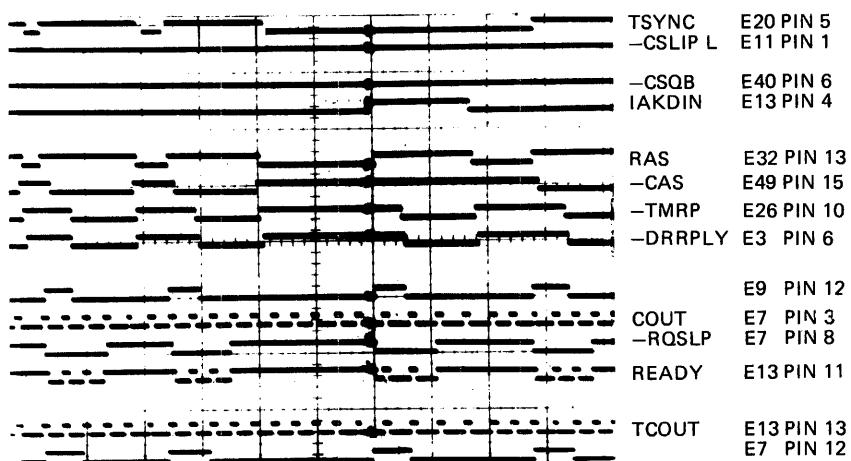
The waveform diagrams shown in Figure 8-12 and subsequent figures are referenced to the circuit schematics in Appendix E. They were obtained by photographing the displays produced by a logic analyzer and are subject to quantization errors inherent in all logic analyzers. They are intended only as a help in understanding the logic and not as a precise representation of timing relationships.

8.3.2 READY

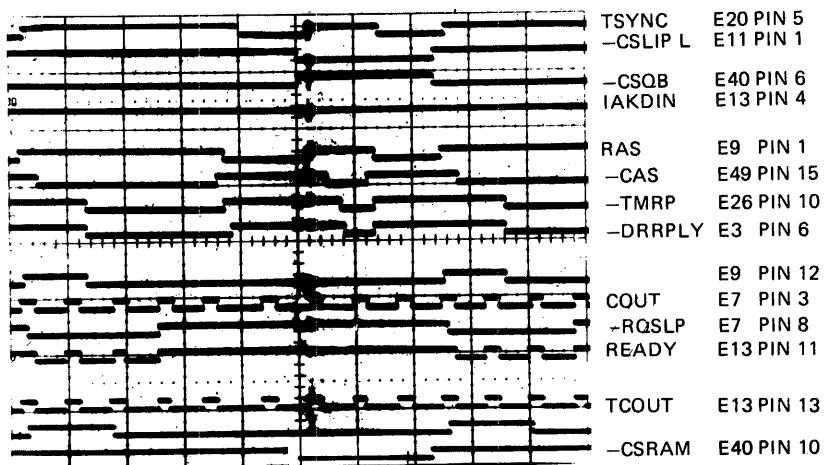
The Ready logic (Figure 8-12) provides the READY input to the microprocessor and is used to control the cycle slip function. The microprocessor will cycle slip when the READY input is being pulsed while RAS is asserted and the cycle slip function is inhibited when the READY input is set high. The output of the Ready flip-flop and the COUT input go to the E13 OR gate and generate the READY input. When the -CSLIP input to E11 is high and the TSYNC input is high, the output of the E11 AND gate goes high. -DRRPLY is not yet asserted and the -TCLKSP and the output of E13 are high, so the output of E9 is high. This enables E12



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A. Signals during LSI-11 Bus transaction



B. Signals during local transaction

Figure 8-12 Ready

and the preset input to the E7 flip-flops to go low. The flip-flop output is low at OR gate E13 and it enables the READY input with every COUT. When the IAKDIN input goes high and the -CSLIP and TSYNC inputs are negated, the output of the E9 AND gate goes high. It allows the E12 NAND gate output to go low and forces the preset terminal of the E4 flip-flops low. The output of the flip-flop to the OR gate is now low and this allows the COUT input to clock the READY output. The microprocessor will continue to cycle slip while this input is being pulsed. The -TMRP input to the NAND gate will go low when either the BRPLY or TMER input from the bus is received. This will remove the low from the preset input of the first flip-flop. Shortly after the -TMRP input goes low the -DRRPLY input also goes low and forces a high to the input of the flip-flop. The high is clocked through by the COUT clock and the flip-flop output to E13 will go high. This disables the READY input to the microprocessor and allows the transaction to be completed.

The second E7 flip-flop is required to ensure that data is stable at the microprocessor or at the peripheral prior to transaction completion. The Ready circuit is inactive during local address references.

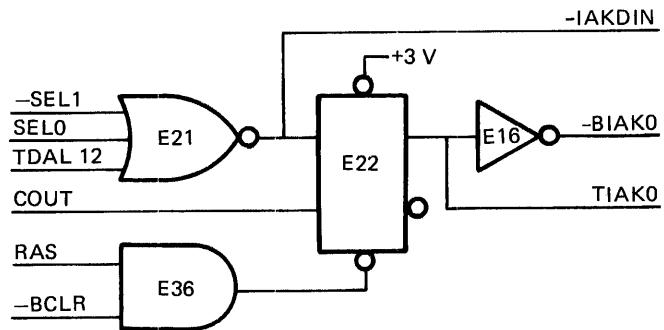
8.3.3 IAK DATA IN (IAKDIN)

The IAKDIN output is enabled by the output of the NOR gate E21 as shown in Figure 8-13. The microprocessor acknowledges an external interrupt request, asserts -SELL and negates SEL0. When the microprocessor has to read the interrupt vector from the bus, the TDAL12 input is low as a result of AI-5 being low during the interrupt request read. This allows the IAKDIN output to go high and assert TDIN to the bus. The RAS input is high and this enables the TIAK0 flip-flop E22. IAKDIN is clocked by the COUT input causing TIAK0 to go high and the inverter E16 sets the BIAK0 output low. The BIAK0 output goes to the bus as an interrupt acknowledge. The TIAK0 output goes to the Bus transceiver logic and enables the low byte transceivers to receive the vector. The IAKDIN output goes to the Ready logic and allows the microprocessor to cycle slip until the interrupting device asserts the -BRPLY input or a timeout occurs. When either response is received, the SEL0 input goes high to disable the IAKDIN output and signals that the microprocessor has read the vector. The RAS goes low to clear the TIAK0 flip-flop.

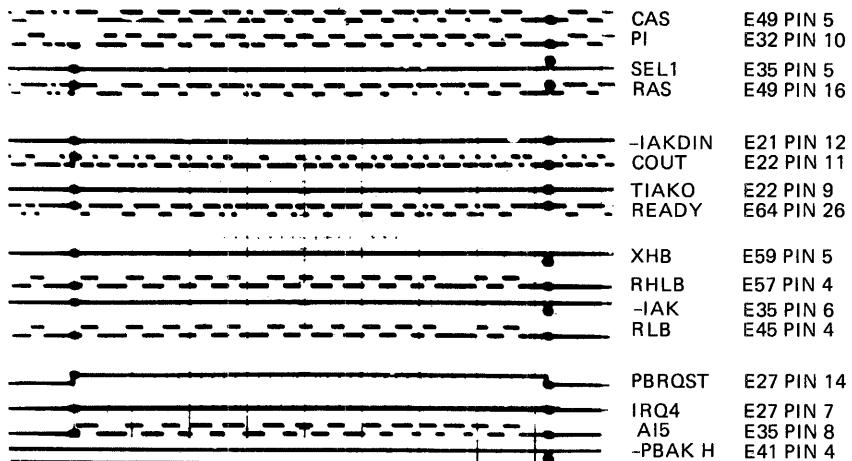
The microprocessor cannot abort the reading of a vector if a timeout occurs and will read a vector of zero in all cases if -BRPLY is not asserted and the timeout counter triggers.

8.3.4 HALT INTERRUPT

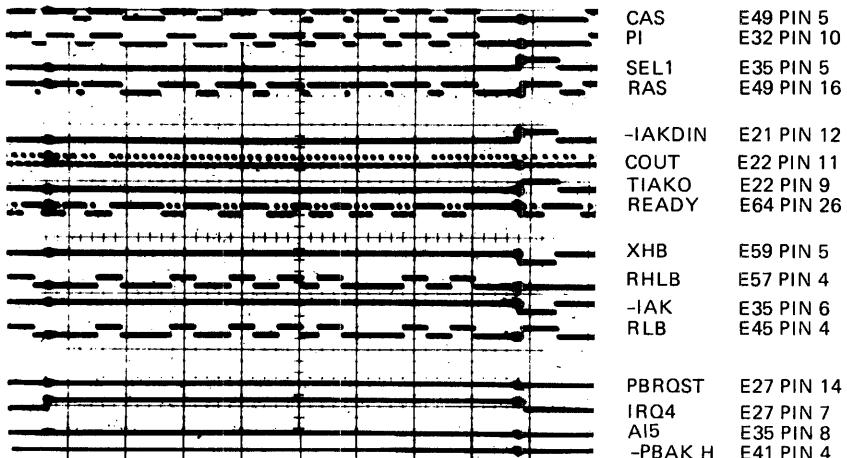
The HALT interrupt (Figure 8-14) is designated as -CTMER and goes to the microprocessor AI-7 input. The user determines the configuration of the control signals, such as TMER, SLU BREAK request or BHALT that can trigger this interrupt. The E4



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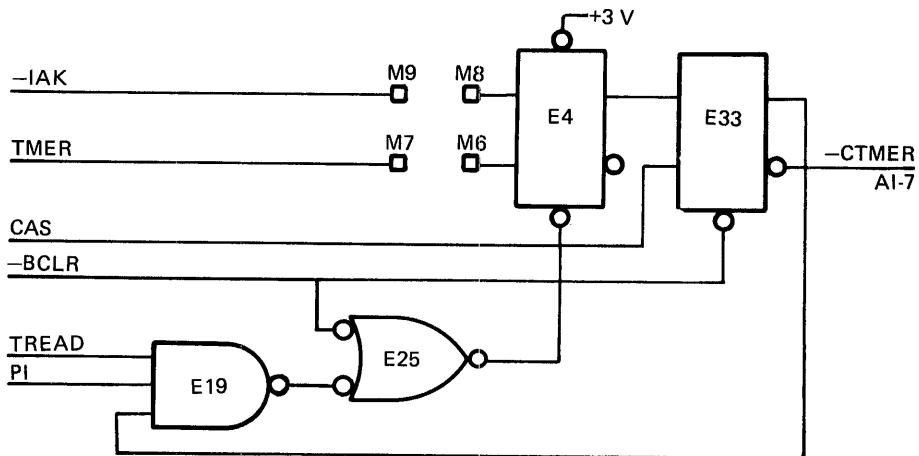


A. Signals during local interrupt

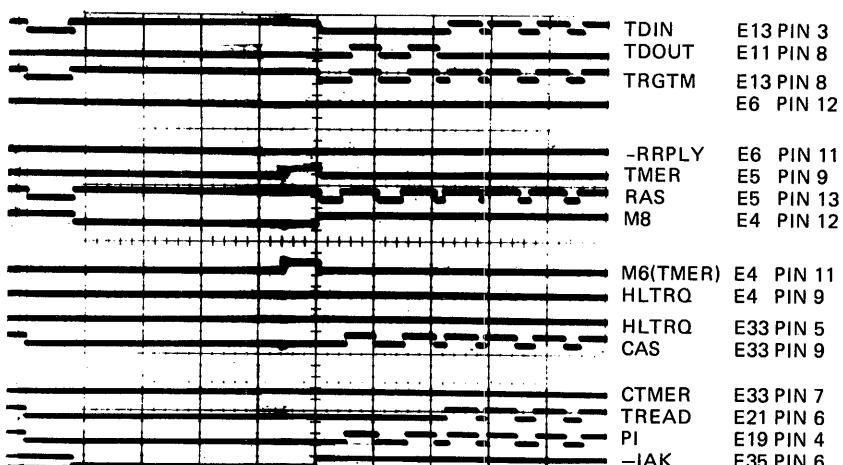


B. Signals during LSI-11 Bus interrupt

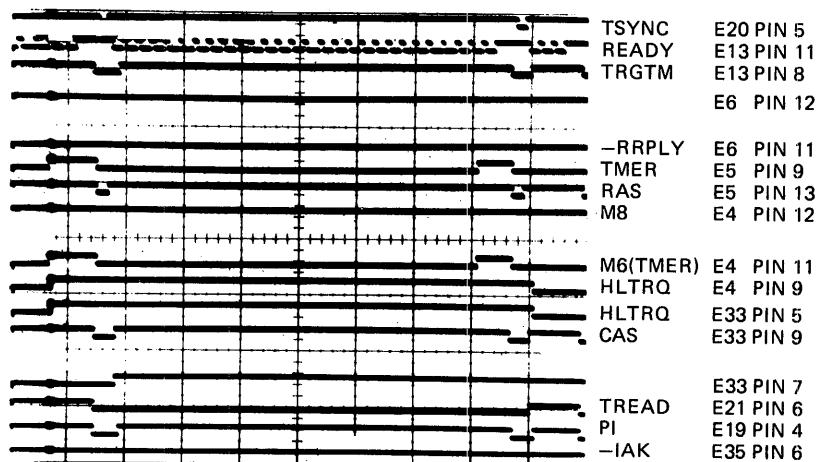
Figure 8-13 IAKDI



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A. Signals during LSI-11 Bus time out
(Interrupt Acknowledge with M8 and M9 jumpered)



B. Signals during nonexistent LSI-11 bus address
(with M8 and M9 jumpered)

Figure 8-14 HALT Interrupt

flip-flop is clocked by the input to M6 and this asserts the E33 flip-flop input. The assertion of CAS clocks the E33 flip-flop and enables the -CTMER output. The CTMER output is set high and goes to the NAND gate E19. The assertion of PI during a microprocessor Read or Fetch transaction latches -CTMER into the microprocessor and at the same time switches the E19 NAND gate output low. This sets the output of the E25 AND gate low to reset the E4 flip-flop for the next HALT interrupt. The E33 flip-flop is cleared by the next CAS strobe. The microprocessor AI-7 input is pseudo edge-sensitive, that is, it must be negated for one PI time before another trap to the restart address can be invoked.

As explained in Chapter 2, connecting M8 to M9 prevents -CTMER assertion during LSI-11 bus interrupt acknowledge transactions. This will prevent the restart trap resulting from this timeout.

8.3.5 Power Fail

The -PFAIL output is connected to the AI-6 input of the microprocessor and is recognized as the power fail interrupt which is nonmaskable. This is the second highest priority interrupt and it does not initiate an IAK transaction. When acknowledged, the microprocessor traps through octal addresses 24 and 26 to access the FC and PSW for the User's Power Fail Routine. This routine should include a RESET instruction and any other instructions required to initialize the bus and the module, as well as an MTPS instruction that will load 340 into the PSW and a wait instruction to inhibit the assertion of any LSI-11 bus control signal when battery backup is being utilized.

As an alternative to the MTPS instruction, 340 may simply be stored at location 26. Then, when the microprocessor vectors through 24, 340 will automatically be loaded into the PSW.

NOTE

BDCOK can be used as a microprocessor reset signal, unrelated to power failure. To guarantee correct restart, the BDCOK pulse must be at least 100 microseconds wide. BPOK should remain inactive during this reset operation.

8.3.6 Local

The on-board local interrupts are listed in Table 8-2 and use a coded input on the AI-1 through AI-5 inputs to the microprocessor. Some of these interrupt functions are determined by the user when configuring the module. There are eight local interrupts and they are all maskable. The multiple interrupts are arbitrated and the interrupt with the highest priority is serviced by the microprocessor. All local interrupts initiate an IAK transaction and their vector addresses are internal to the microprocessor. During IAK, the serviced interrupt is driven on TDAL lines 11--08 to address the interrupt acknowledge PROM. The outputs of the PROM reset the interrupts. TDAL bits 07--00 are ignored. The

microprocessor pushes the present PSW and PC onto the stack and receives a new PC and PSW from the vector address location and the next location.

8.3.7 External

A level 4 LSI-11 bus interrupt also uses a coded input on the AI-1 through AI-4 inputs to the microprocessor and the interrupt is maskable. For the bus interrupt the AI-5 input to the microprocessor is taken low to indicate that the vector address must be read from LSI-11 bus bits 07--02. The microprocessor does an IAK transaction and places the BDIN and BIAKO signals on the bus to the requesting peripheral device. This device responds with -BRPLY and the vector address is read from the LSI-11 bus. The microprocessor pushes the current PC and PSW onto the stack and reads a new PSW and PC from the vector address location and the next location.

If the interrupting peripheral device fails to assert the BRPLY bus signal within 10 usec after BDIN is asserted, the module timeout signal TMER is enabled. The microprocessor completes the IAK transaction and receives a vector address of zero, since there is nothing driving the bus. The new PSW and PC are then read from locations zero and two. However, the user has the option to connect the timeout signal TMER to the HALT interrupt. The HALT interrupt can then be processed and pushes the current PSW and PC, which were read from locations 0 and 2, onto the stack. It then loads the PC with the restart address and the PSW with 340. If the HALT is ignored for the vector timeout, then only a vector through locations zero and two will occur.

8.3.8 DMA Interrupt

The DMA request is connected to the AI-0 input to the microprocessor. The DMA request is received by the microprocessor during any Read, Write, Fetch or ASPI transaction. The request is not acknowledged by an IAK transaction but is acknowledged by the microprocessor asserting the SEL0 and SEL1 outputs to initiate a DMA transaction as described in Paragraph 8.14.

8.4 DC004 PROTOCOL

The DC004 protocol logic chip (see Figure 8-1, Sheet 1) interfaces the LSI-11 read/write signals with the module read/write signals. The -CSQB input goes high and is strobed by RSYNC to enable the logic. The BDIN L input goes low to request read data and switches the -READ output low. The BDOU T input goes low to strobe write data and switches the -WHB and -WLB outputs low if the BWTBT L input is high. When the BWTBT L input is low, the BDAL0 L input will select either the -WHB or the -WLB. A low on the BDAL0 L input switches the -WLB output low. The BRPLY L output is controlled by the -CSQB input. When -CSQB input is high, this indicates the LSI-11 bus was not selected. The BRPLY L output is enabled and is switched low, after an RC delay, whenever BSYNC L and either the BDIN L or BDOU T outputs are switched low. If the -CSQB input is low, the LSI-11 bus is selected and the BRPLY L output is disabled. The BDAL0, 1, and 2 inputs control the -SEL6 output. The output goes low when BDAL1 L and BDAL2 L inputs are low and the BDAL0 L is high.

8.5 ADDRESS LATCH

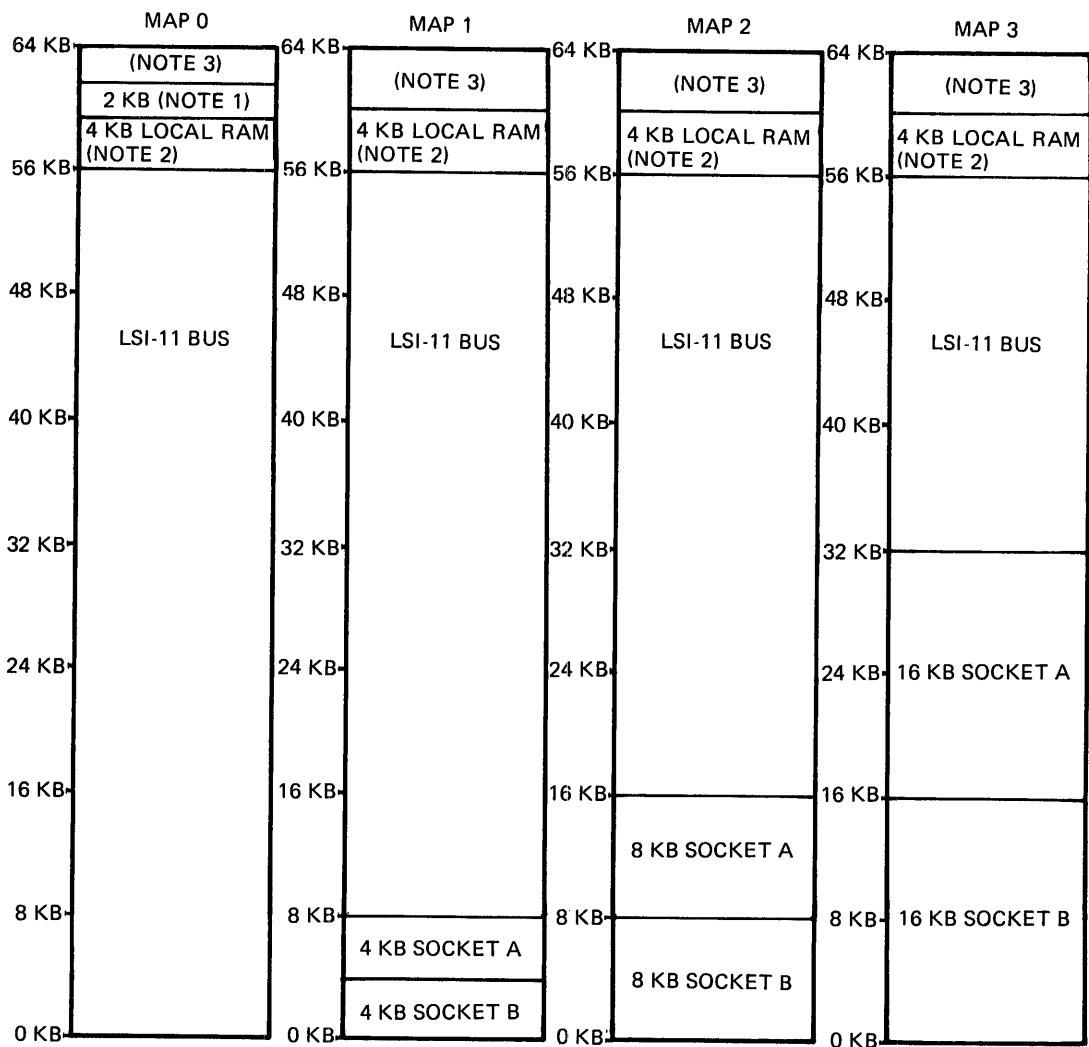
The Address Latching logic (see Figure 8-1, Sheet 1) consists of 16 transparent latches designated E53 and E63. The latches are always enabled by grounding the Output Control input. The TDAL bus bits 01--15 and the I/O page select signal RBS7 are monitored. The status of these inputs is latched to the Address Bus as bits AD1 through AD15 by the RSYNC input going high. The Address Bus and the latched LBS7 signal go to the Memory Address Decode logic (FPLA). The address bus is common to the module memories and the I/O circuits and remains stable while RSYNC is asserted.

8.6 MEMORY ADDRESS DECODE

The Memory Decode logic (see Figure 8-1, Sheet 1) consists of a Field Programmable Logic Array (FPLA) that decodes the applied address bits and the latched LBS7 signal. The FPLA selects a predetermined output according to the selected memory map. The module address range includes the on-board memory, the I/O interface registers and LSI-11 bus addresses. There are four different memory maps available to the user and these are described in Figure 8-15. The M22 and M23 wire-wrap pins allow the user to select one of these maps and these are described in Chapter 2. The FPLA is enabled provided the DCLO input is low. An address location in the RAM memory enables the -CSRAM output and an address location of either socket set A or B of PROM enables either the -CSKTA or -CSKTB outputs. A register address for either SLU 1 or SLU 2 will enable the -CSDL0 or -CSDL1 outputs. The -CSPL output is enabled when a register of the parallel I/O logic is addressed. The -CSLIP output is low for all the above address conditions. The -CSLIP output goes high only when the address is located on the LSI-11 bus and the -CSQB output is enabled low. The -CSLIP output allows the processor to cycle slip during the LSI-11 bus read/write and IAK transactions.

8.7 RAM MEMORY

The Static RAM memory is a 2K X 16-bit memory that consists of a 2K X 8-bit high byte chip and a 2K X 8-bit low byte chip as described by Figure 8-16. The memory is selected by the -CS RAM input going low to the CS pin. The memory is addressed by address bits AD1--AD11 and 16-bit data is read from or written to via TDAL bits 00--15. The memory is read by the -READ input going low to produce a low output from the AND gate E25 to the OE pin of the memories. The -WLB selects the low byte and the -WHB selects the high byte. The -WHB and -WLB inputs to the WE pin enables the write function and the output of AND gate E25 also goes low to the OE pin of the memories, to accommodate the dual CS function of some vendor's static RAMs.



NOTES:

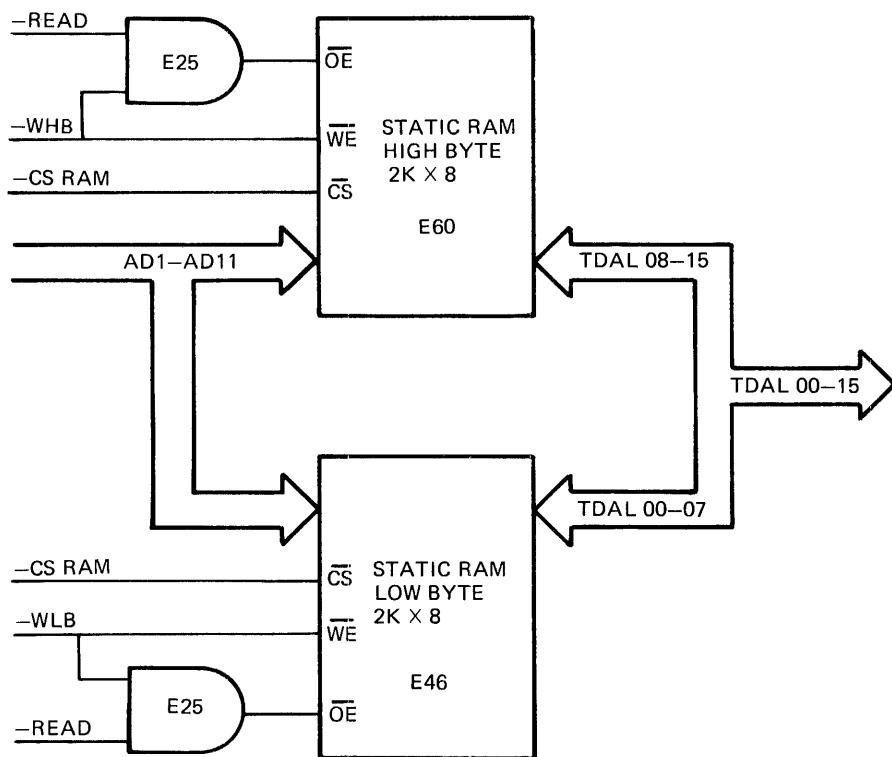
1. SOCKET SET A IS MAPPED OVER SOCKET SET B AND IS THEREFORE LIMITED TO USING EITHER SOCKET A OR SOCKET B, BUT NOT BOTH TOGETHER.
2. ADDRESSES 160000 THROUGH 160007 ARE ASSUMED TO RESIDE ON THE LSI-11 BUS.
3. THIS SECTION CONTAINS THE LOCAL I/O ADDRESSES FOR THE SLUs AND PPI. ALL UNASSIGNED ADDRESSES ARE ASSUMED TO RESIDE ON THE LSI-11 BUS.

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Figure 8-15 Memory Maps

8.8 ROM/RAM MEMORY SOCKETS

The ROM/RAM memory provides the user with four 28-pin sockets, as described by Figure 8-17, to accept either 24-pin or 28-pin industry standard +5 V chips. The sockets can accommodate up to 32KB of UV PROMs, PROMs or ROMs and up to 8KB of static RAM. The socket sets are designated A and B, and each designation has a high byte socket and a low byte socket. The sockets use the -CSKTA



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Figure 8-16 RAM Memory

and -CSKTB outputs from the Memory Address Decode and the user should refer to Figure 8-15 for the memory maps associated with these signals. The -READ, -WLB and -WLB signals from the DC004 Protocol are used to provide a High Byte Chip Enable (HBCE) and a Low Byte Chip Enable (LBCE). There are 30 wire-wrap jumper posts available for the memory configuration and detailed information is provided in Chapter 2.

NOTE

When a memory chip is placed into a socket wired for a larger capacity part, for example a 1K X 8 chip in a 2K X 8 socket, the addresses above the 1K boundary will wrap around into the start of the memory. This should be kept in mind when choosing the memory map configuration.

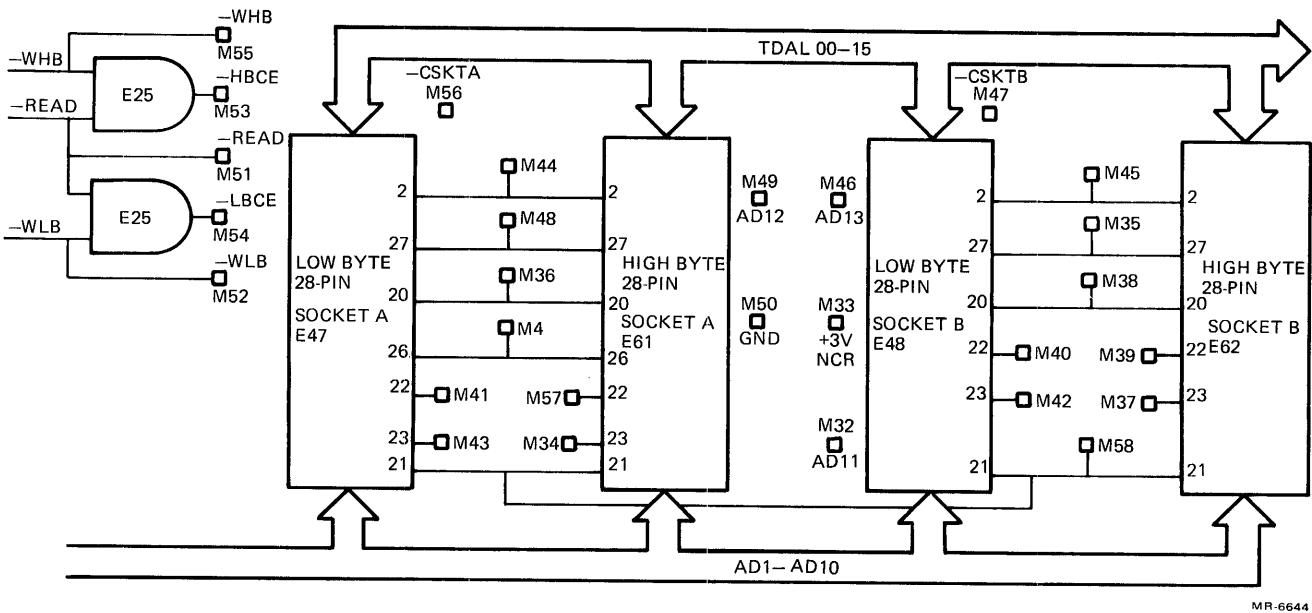


Figure 8-17 ROM/RAM Memory Sockets

8.9 SERIAL LINE INTERFACE UNITS

There are two Asynchronous Serial Line Units designated SLU1 and SLU2 to provide serial I/O interface through J1 and J2 as shown in Figure 8-18. Operational aspects are discussed in Chapter 2.

The SLUs transmit or receive 8-bit, byte-oriented data, with no parity, one start bit, and one stop bit. SLU1 provides the XDL1 and RDL1 interrupts for transmit and receive, and the BREAK output which is wired to pin M14. The user can jumper the BREAK output to the HALT interrupt (pin M13) and use SLU1 as a system console. SLU2 provides the XDL2 and RDL2 interrupts for transmit and receive, and three real time clock interrupts at 50 Hz, 60 Hz, and 800 Hz. These interrupts are wired to pins M18, M19, and M20 for use with the TEVNT interrupt (pin M17).

When the serial line units are addressed, the -CSDL0 input selects SLU1 and the -CSDL1 input selects SLU2 by enabling the chip select (CS) inputs. Address bits AD2 and AD1 are used to select individual registers within the SLUs. These registers are listed in Table 8-3 with their address and the logic states for AD2 and AD1 to access them. The -READ input will read the 16 bit register selected by -CSDL0 or -CSDL1, AD2 and AD1 by placing the contents onto the TDAL bus provided the -WLB input is not asserted low. When asserted low, the -WLB input will write the low byte of the TDAL bus into the register selected by -CSDL0 or -CSDL1, AD2 and AD1. However, only the register bits designated as read/write will be written into. The DLCLK input is a crystal controlled

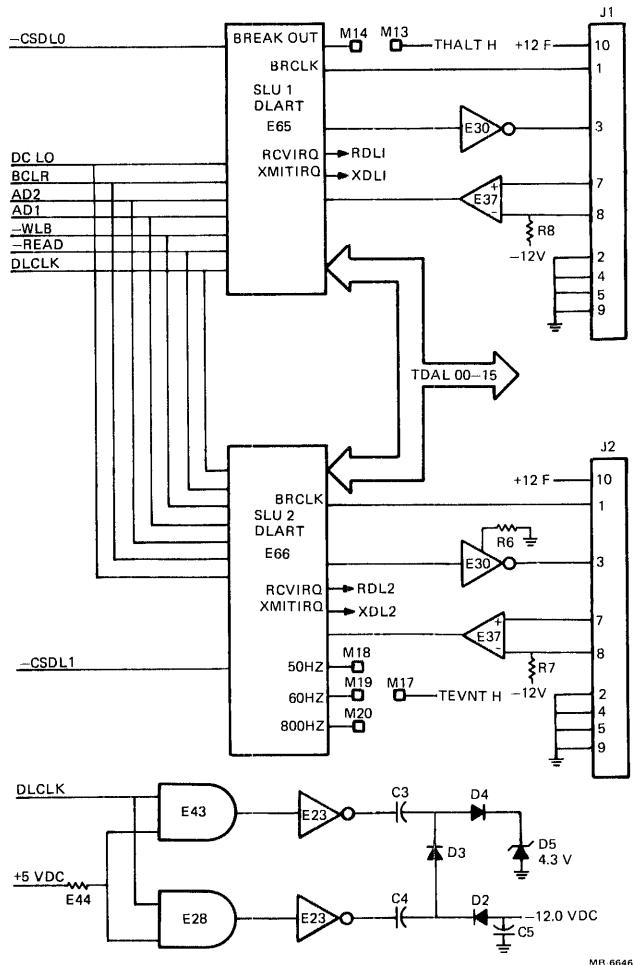


Figure 8-18 Serial Line Interface Units

clock reference used by the SLU to generate baud rates and real time clocks. The BCLR input is asserted during a RESET instruction, the RCVIE bit of the RCSR register and the XMITIE, MAINT and XMIT BRK bits of the XCSR register are reset. When the DCLO input is asserted during power up, it disables all SLU outputs and resets all internal logic and registers. The baud rate will be set at 300 baud after the SLU is initialized by DCLO.

The RS232 and RS423 signals for the interface connector are provided by 9636 (E30) and 9637 (E37) dual line drivers and dual line receivers. The slew rate for both channels is controlled by resistor R6. The factory configuration uses a 22K ohm resistor to provide a 2 usec slew rate for operating at a 38.4 K baud rate. Refer to Chapter 2 for the configuration requirements at other baud rates.

Table 8-3 Serial Line Unit Registers

Register	Description	Address	AD2	AD1
SLU1				
RCSR	Receiver Control/Status	177560	0	0
RBR	Receiver Buffer	177562	0	1
TCSR	Transmitter Control/Status	177564	1	0
TBR	Transmitter Buffer	177566	1	1
SLU2				
RCSR	Receiver Control/Status	176540	0	0
RBR	Receiver Buffer	176542	0	1
TCSR	Transmitter Control/Status	176544	1	0
TBR	Transmitter Buffer	176546	1	1

8.10 PARALLEL I/O INTERFACE

The programmable parallel I/O provides a 30 pin connector for transferring parallel data into or out of the SBC-11/21 module. The parallel I/O uses an 8255A-5 programmable interface chip, two 8-bit transceiver chips and an 8-bit buffer chip as described by Figure 8-19. The 8255A-5 has three input/output ports defined as port A, port B and port C. Port A and Port B outputs are connected to 8-bit bidirectional transceivers that are controlled by wirewrap pins M59 and M66. When a logical one is applied to these pins the data lines act as inputs to the module and when a logical zero is applied to these pins the data lines act as outputs from the module. The user can configure these as inputs or outputs using wirewrap pins M60 and M65 or as programmable inputs/outputs by programming the PC4 and PC6 lines (M64, M63) of Port C as described in the configuration description in Chapter 2. The Port C outputs are connected to directional buffers and used for interrupts and the handshake control for ports A and B. PC0 and PC3 are wired as outputs, PC3 enables the Parallel Interrupt Request for port A and PC0 enables the Parallel Interrupt Request for port B. PC4 and PC6 can be used as acknowledge or strobe inputs or can be configured to dynamically control the direction of ports A and B from either the 8255A-5 interface or the external peripheral device. PC1, PC5 and PC7 are wired as outputs and PC7 is wired to a LED that can be program controlled. PC2 is wired as an input and has a current limiting resistor for protection when PC2 might be programmed as an output from the 8255A-5 interface. Detailed configuration requirements are provided in Chapter 2 and the programming information is provided in Chapter 6.

The 8255A-5 Programmable Peripheral Interface (PPI) is enabled by the -CSPL input from the Memory Address Decode chip whenever the 176200-176207 addresses are selected. The AD1 and AD2 address lines are decoded to select one of four registers within the PPI and listed in Table 8-4. The Port A, Port B and Port C registers

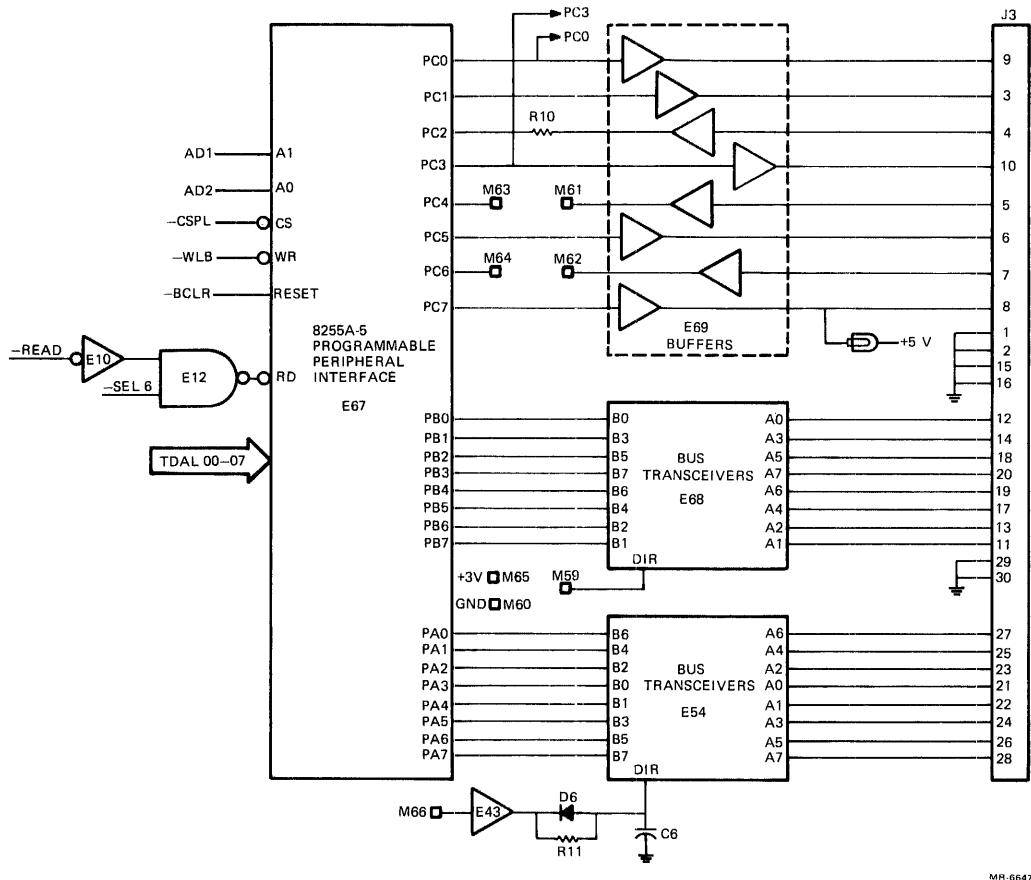
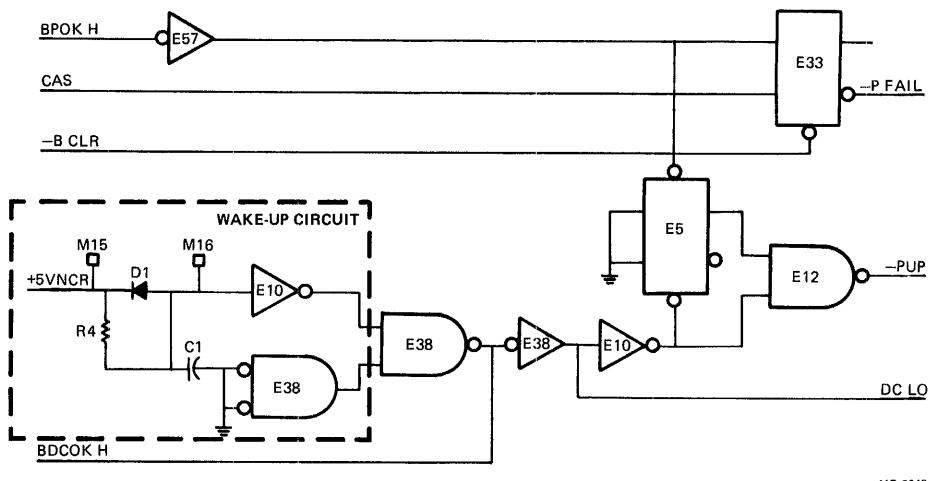


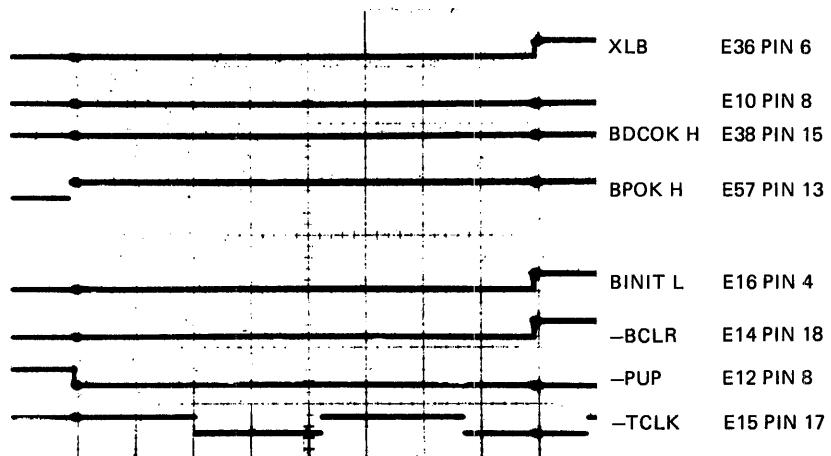
Figure 8-19 Parallel I/O Interface

Table 8-4 PPI Addressable Registers

Register	Address	Status
Port A	176200	Read/Write
Port B	176202	Read/Write
Port C	176204	Read/Write
Control Word	176206	Write Only



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Signals during Power-Up

Figure 8-20 Power Up

are read/write and the Control Word register is a write only register. The addressed register is written into with the data on TDAL 07-00 bus when the -WLB input is asserted. The contents of the addressed register is placed on the TDAL 07-00 bus when the -READ input is asserted. The -SEL6 L input to NAND gate E12 inhibits the read strobe from the Control Word register and therefore any read of the control word register produces erroneous data to the microprocessor. Only the low byte of the TDAL bus is used with the PPI and any data on the high byte is always treated as erroneous. The -BCLR input is used to reset the PPI when it is asserted and all 8255A-5 24 I/O lines are then defined as inputs. The buffer outputs to the connector will be driven high.

8.11 POWER UP

The power up circuits (Figure 8-20) sense the application of +5VNCR power source to the module and initiate a power-up sequence. When the +5VNCR input is first applied, the input at the

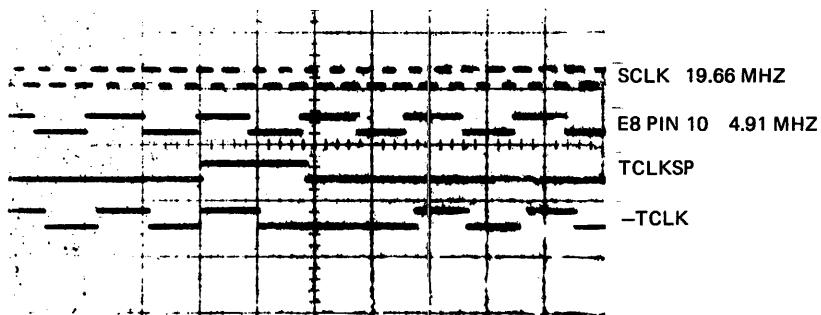
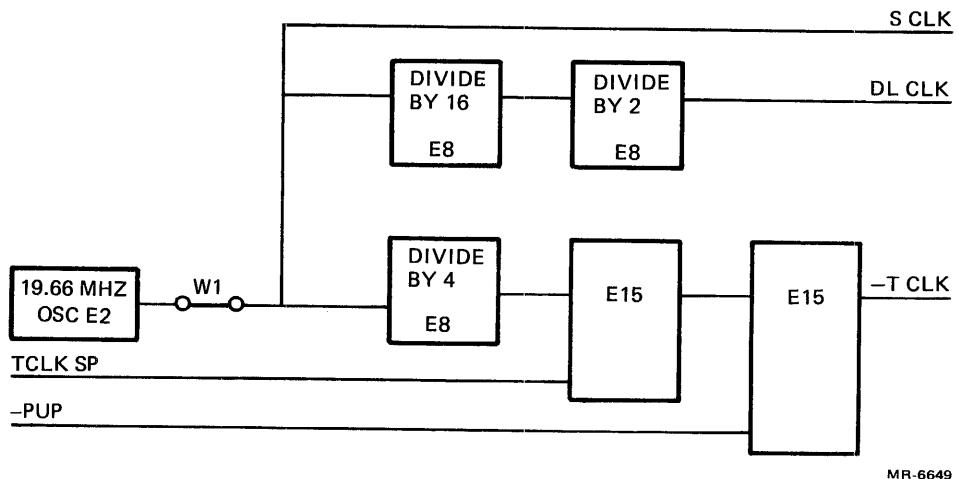
inverter E10 is low and causes the clear input of the PUP flip-flop E5 to be low, thus keeping its output low. Since an input to the nand gate E12 is low, the -PUP output is high, the microprocessor is held reset and asserts the -BCLR output. The +5VNCR input charges C1 through R4 until the threshold level of inverter E10 is reached. This occurs at approximately 2.6 Vdc and 70 ms after +5VNCR was applied. This causes the reset input to the PUP flip-flop to go high and set input to go low, setting the flip-flop. The -PUP output of the nand gate E12 goes low. This initiates the power up sequence of the processor.

The power up delay circuit can be by-passed by inserting a jumper between M15 and M16. This allows the BDCOK H and BPOK H bus signals to control the PUP output. The +5VCNR input goes directly to the inverter E10 driving input to the inverter E38 low. E38 output is then controlled by BDCOK. The BDCOK H signal is low until power supply stabilizes, causing the reset input to the PUP flip-flop to be low. The BPOK H signal is also low and this causes the preset input to the flip-flop to be high. The low input to nand gate E12 drives the PUP output high. The microprocessor then asserts the -BCLR output resetting the PFAIL flip-flop. After a minimum of 3 ms the BDCOK bus input goes high and allows the PUP flip-flop E5 reset to go high. After a minimum of 70 ms the BPOK H bus input goes high causing the PUP preset input to go low. This allows the output to go high and when both inputs to the nand gate E12 are high the -PUP output is low. This initiates the power up sequence of the microprocessor.

The BPOK H bus input also goes to the PWR FAIL flip-flop E33. This flip-flop is not enabled until the microprocessor power up sequence is completed and therefore the BPOK H input is already high. Following the power up sequence, the first CAS pulse sets the PFAIL flip-flop. The flip-flop remains set until the BPOK input goes low indicating a power fail. The next CAS input clocks the PFAIL flip-flop and resets it. This causes the power fail interrupt and trap to location 24. This interrupt must be negated for at least one microprocessor read before another assertion will be recognized by the microprocessor.

8.12 CLOCK

The module uses a 19.6608 Mhz crystal oscillator as the basic time base reference. The oscillator output goes to the Clock Control logic (see Figure 8-21) and to the E8 binary counters. The counters are always enabled. The 19.6608 MHz output is divided by 32 and the DLCLK output, at 614.4 KHz, goes to the Serial Line units and to the charge pump. The oscillator is also divided by 4 and the 4.91 MHz output goes to the pulse sync circuit E15. When the TCLKSP input is low the circuits are enabled and the output goes to the next pulse sync circuit. When the TCLKSP input is high the circuits are inhibited and there is no output. The second pulse sync circuit is controlled by the PUP input. When the PUP input is low, TCLK to the XTL1 input is enabled and when the PUP input is high, the XTL1 input is inhibited.

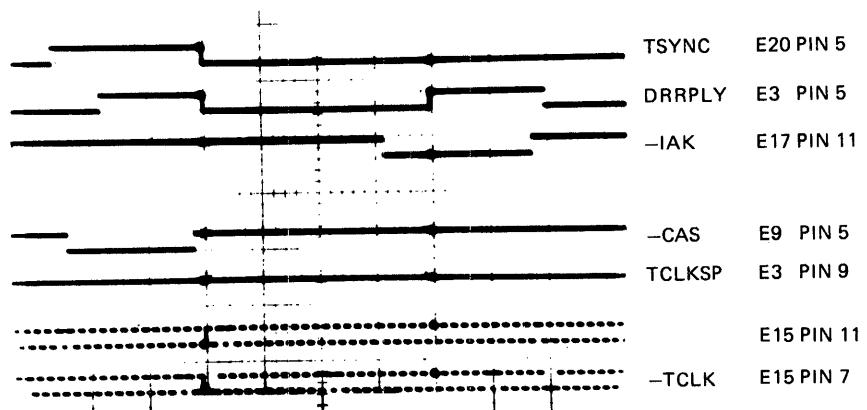
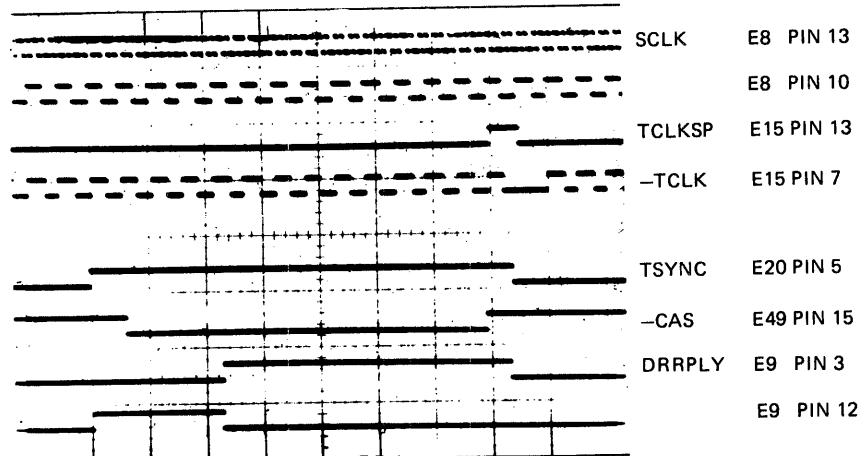
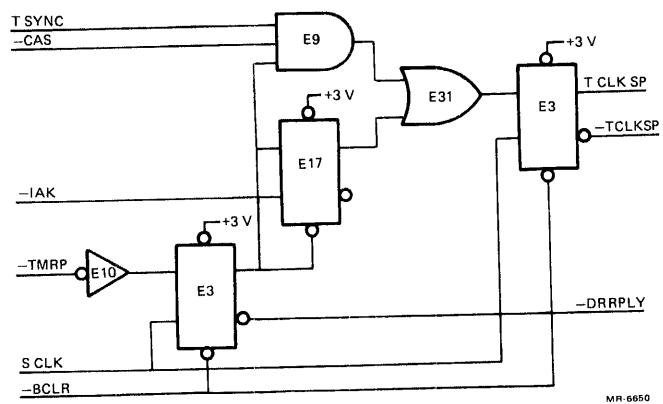


Signals for clock logic

Figure 8-21 Clock

8.13 CLOCK CONTROL

The clock control logic (Figure 8-22) is used to stop the XTL1 input to the microprocessor and forces the microprocessor to stop or wait until the XTL1 input is enabled again. The TCLKSP output is normally low to enable XTL1 and this is controlled by the TMRP input being high. This forces a low for both inputs to the OR gate E31 and the low output is clocked through the TCLKSP flip-flop by the 19.6 MHZ input. When TMRP goes low this removes the low inputs to the AND gate E9 and the IAK flip-flop E17. The TSYNC input is high for Read/Write and Fetch transactions and when the -CAS input goes high the AND gate E9 output also goes high. This is clocked through the TCLKSP flip-flop and the output goes high to stop the 4.91 MHZ clock output of E15. The TSYNC input is low for DMA and IAK transactions so that input to the AND gate E9 holds the output low. However the IAK flip-flop E17 is set when the -IAK clock input goes high at the end of an external interrupt transaction and the E31 output goes high. This is clocked through the TCLKSP flip-flop and the output goes high to stop the 4.91 MHz clock output of E15. The microprocessor XTL1 input will remain stopped until the TMRP input goes high again signaling that either BRPLY or TMER have been negated. This forces the IAK flip-flop E17 output to go low. This negates the TCLKSP output and enables the XTL1 input to the microprocessor.

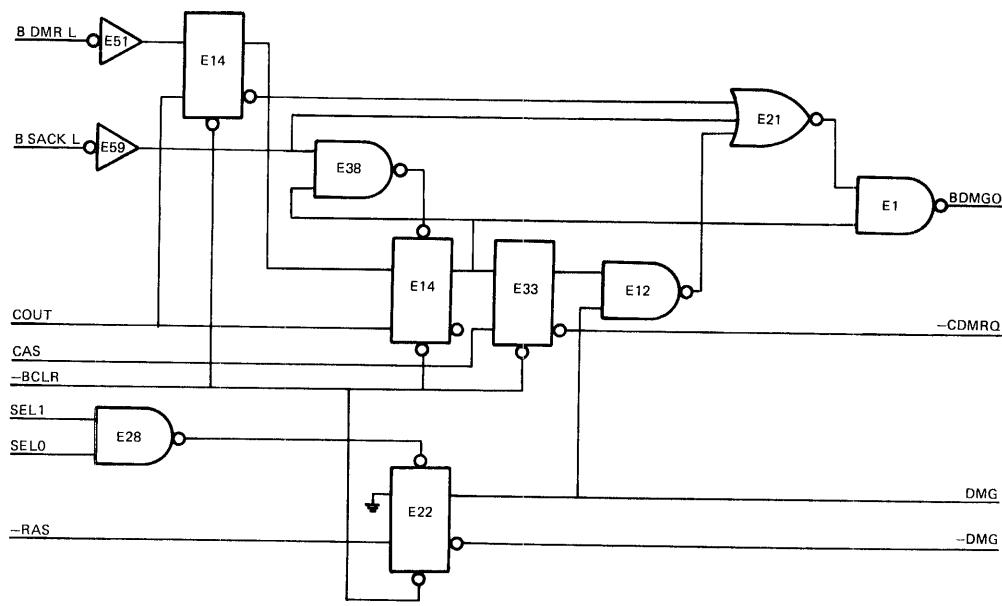


Signals for clock control

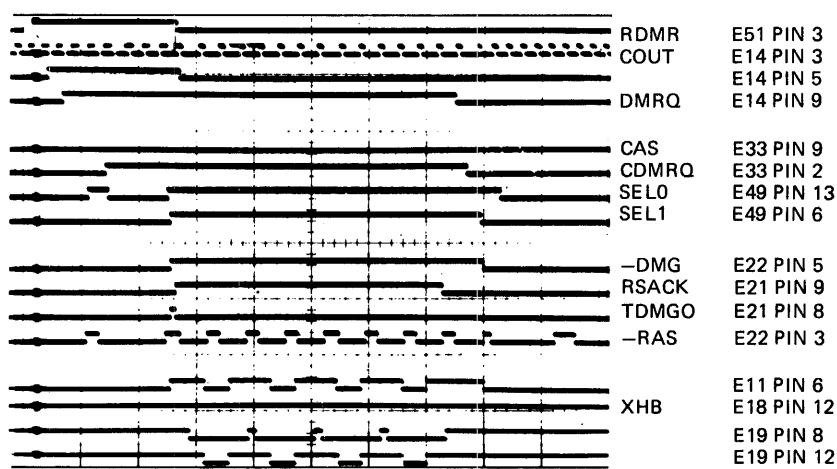
Figure 8-22 Clock Control

8.14 DMA

The DMA logic (Figure 8-23) controls the bus and microprocessor for DMA transactions. The BDMR L input goes low to initiate a DMA request. The output of the inverter E5 goes high and is clocked through flip-flop E14 by COUT. The low output goes to the E21 NOR gate and the high output goes to flip-flop E14. The high output is clocked through by COUT and the high output enables the two NAND gates E28 and E1. The high output is also clocked through flip-flop E33 by the CAS input. The high output enables the NAND gate E12 and the -CDMRQ output (AIO Input) is switched low. The -CDMRQ output is the DMA interrupt to the microprocessor and initiates a DMG transaction. The microprocessor acknowledges the



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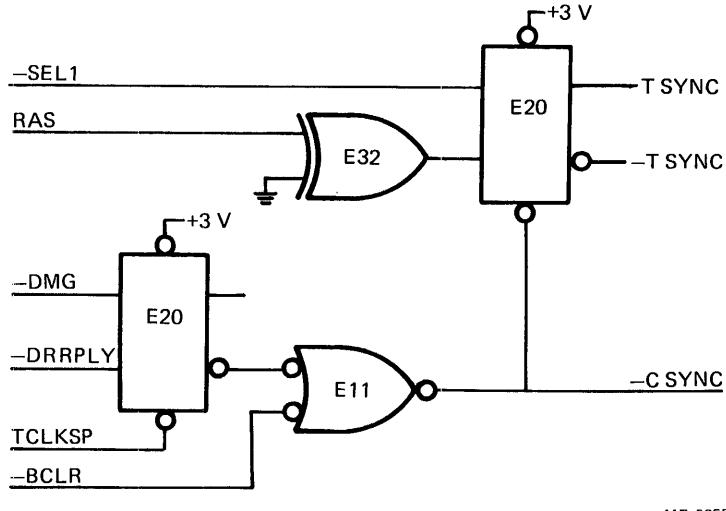
Signals for DMA logic

Figure 8-23 DMA

request by outputting SEL1 and SEL0 high to NAND gate E28. The preset of flip-flop E22 goes low to set the DMG output high and the -DMG output low. The DMG high input to NAND gate E12 switches the output low and it goes to NOR gate E21. The BSACK L input is normally high and when inverted by E59 is a low input to the NOR gate E21. All three inputs to the NOR gate E21 are now low causing the output to switch high. Two high inputs to the NAND gate E1 switches BDMGO low on the bus to the originator of the DMA request. The requesting device then sets the bus signal BSACK L low and the BDMR L input high. BSACK L is inverted by E59 and removes the low from the NOR gate E21 and the high input to the NAND gate E1 causing the BDMGO output to go high. It also provides a high input to the NAND gate E28 causing the output to switch low. This low goes to the preset input of the flip-flop E14 and clamps the output high which holds the microprocessor in the DMG mode. The requesting device maintains the BSACK L input low for the duration of the DMA transfer and then sets it high. This removes the low from the preset input of flip-flop E14 and enables the flip-flop. Previously the BDMR L input went high and was inverted as a low to flip-flop E14. This low was clocked through by COUT and provides a low input to the enabled flip-flop E14. The low is now clocked through causing the -CDMRQ output to go high which removes the request from the microprocessor. The microprocessor completes the DMA interrupt transaction and negates the SEL1 and SEL0 outputs. The preset input of flip-flop E22 is no longer low and the low data input is clocked through when RAS goes high. The DMG output goes low and the -DMG output goes high to complete the DMA transaction.

8.15 TSYNC

The TSYNC output (Figure 8-24) is normally high for the microprocessor controlled Fetch/Read and Write transactions and low for IAK and DMA transactions. These conditions follow the -SEL1 input which is high and low for the same transactions. The exclusive OR gate E32 acts as a non inverting buffer and when RAS goes high the -SEL1 input of the TSYNC flip-flop E20 is clocked through as the output. Whenever the -CSYNC clear input goes low, it forces the output of the TSYNC flip-flop E20 to go low. The CSYNC flip-flop E20 normally has the clear input pulled low by TCLKSP and the output to the AND gate E11 is high. When the TCLKSP input goes high the input of the CSYNC flip-flop is enabled. At this time the -DRRPLY clock input is low and goes high to clock the flip-flop shortly before the TCLKSP input gets reset. If a DMA transaction is in progress the -DMG input is high and the CSYNC flip-flop output remains low when clocked by -DRRPLY going high. For any transaction other than the DMA, the -DMG input is low and the CSYNC flip-flop output goes high when clocked by -RPTM going high. This allows the CSYNC output to go high and clear the TSYNC flip-flop E20 the write byte flip-flop E17 and the disable WT flip-flop E4 in Figure 8-25.



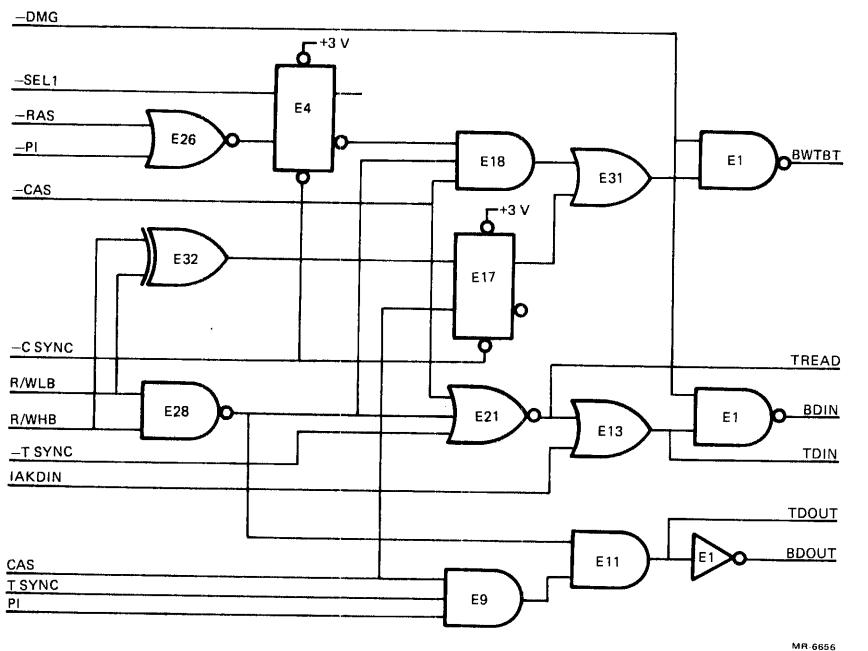
MR-6655

Figure 8-24 TSYNC

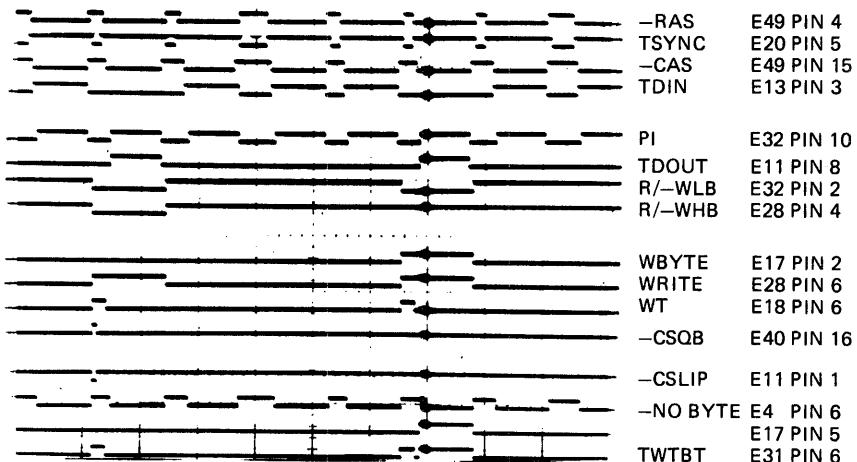
8.16 READ/WRITE

The Read/Write logic (Figure 8-25) controls the read, write, and fetch transactions for the microprocessor and supports the IAK and DMA transactions. The microprocessor controls the R/-WLB and R/-WLB inputs to select either BDIN, BDOUT or BWTBT bus signals. To select the BDIN output the microprocessor sets both R/-WLB and R/-WLB inputs high to the NAND gate E28. The output goes low to enable the NOR gate E21 and disables the AND gates E18 and E11. The -TSYNC input to E21 is low for read/write transactions. When the -CAS input goes low, the TREAD output goes high. The TDIN output of OR gate E13 goes high and the BDIN output of NAND gate E21 goes low. The -DMG input to the NAND gate is always high except for DMA transactions. During interrupt transactions, the IAKDIN input to E13 is enabled high, and also causes TDIN to go high and BDIN to go low.

The microprocessor determines any write condition by setting either R/-WLB or R/-WLB input low or both of these inputs low. The output of NAND gate E28 goes high and enables the AND gates E11 and E18. The output of flip-flop E4 is high and the -CAS input to AND gate E18 is also high. The output of AND gate E18 goes high and the output of OR gate E31 goes high. The DMA input to NAND gate E1 is high and allows the BWTBT output to go low. At this time the write destination address is written onto the bus. The logic now determines if the data being written is a word or a byte. The exclusive OR gate E32 monitors the R/-WLB and R/-WLB inputs and the output goes high when the inputs are different. A high output indicates the data is a byte and a low output indicates the data is a word. The output goes to flip-flop E17.



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Signals for Read/Write logic

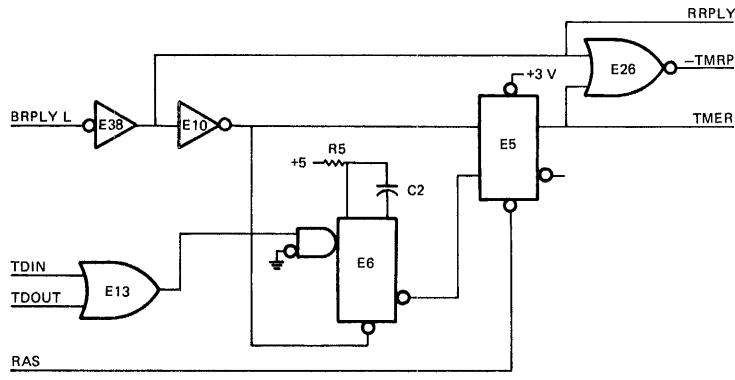
Figure 8-25 Read/Write

The microprocessor asserts CAS, the CAS input to E17 and E9 goes high and -CAS input to E18 goes low. The -CAS input to AND gate E18 switches the output low, to remove BWTBT but the CAS input clocks flip-flop E17 and enables the WBYTE signal to E31. The output of the flip-flop E17 is high for byte transactions and low for word transactions. The BWTBT L signal will either remain asserted low for a byte transaction or be negated high for a word transaction. The TSYNC and CAS inputs to AND gate E9 are set high and when the PI input goes high the gate output goes high. The AND gate E11 is enabled and the output of E9 switches the TDOUT output high. This is inverted and the BDOUT output is enabled by going low and writes the data word.

At the same time the -RAS and -PI inputs to NOR gate E26 are both low switching the output high. The high clocks flip-flop E4 and the output goes low. This inhibits the AND gate E18 when the -CAS input goes high again. The flip-flops are reset by CSYNC at the end of the transaction.

8.17 REPLY TIMEOUT

The Reply Timeout logic (Figure 8-26) monitors the bus BRPLY L input to indicate that an LSI-11 bus device responds to an address. The TMER flip-flop E5 output is normally set low by the RAS input to clear the flip-flop. The BRPLY L input is high and inverted so the RRPLY output is low. The -TMRP NOR gate inputs are both low and the -TMRP output is high. The bus transaction is initiated by either TDIN or TDOU inputs going high. This enables the 10 usec timeout (50 cycle slips) monostable multivibrator to start. The microprocessor starts to cycle slip while waiting for the BRPLY L input to go low indicating the bus transaction can complete. When BRPLY L switches low, the RRPLY output goes high and the -TMRP output goes low. The TMER output remains low. If the BRPLY L does not go low and the 50 usec timeout circuit allows the 50 cycle slips and the TMER flip-flop is clocked and the TMER output goes high. This also forces the -TMRP output to go low. The assertion of the TMER output goes to the HALT logic and the microprocessor action is dependent upon the configuration of the module. The -TMRP output goes to the Clock Enable, SYNC, Ready logic, and disables cycle slips and the start/stop of the XTLL clock. The RRPLY output goes to the Bus Control logic, and enables bus data to be received during LSI-11 bus device reads.



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Figure 8-26 Reply Timeout

8.18 BUS CONTROL

The Bus Control logic (Figure 8-27) controls the transmit and receive functions of the Bus Transceivers. The transceivers are in transmit mode for microprocessor controlled Read/WRITE and Fetch transactions to local memory, Local I/O and during LSI-11 bus writes. The transceivers go to the receive mode during an LSI-11 bus read. During DMA, the transceivers go to the receive mode to accept the local device address and will stay in this mode until the device is addressed. When a read transaction occurs, the transceivers go into the transmit mode. When the -BCLR input is high the transceivers are able to transmit data and when -BCLR is asserted low, the transceivers are disabled. During an IAK transaction, the -IAK input to AND gate E18 goes low to disable the transceiver high byte and the low byte goes to the receive mode to accept the vector.

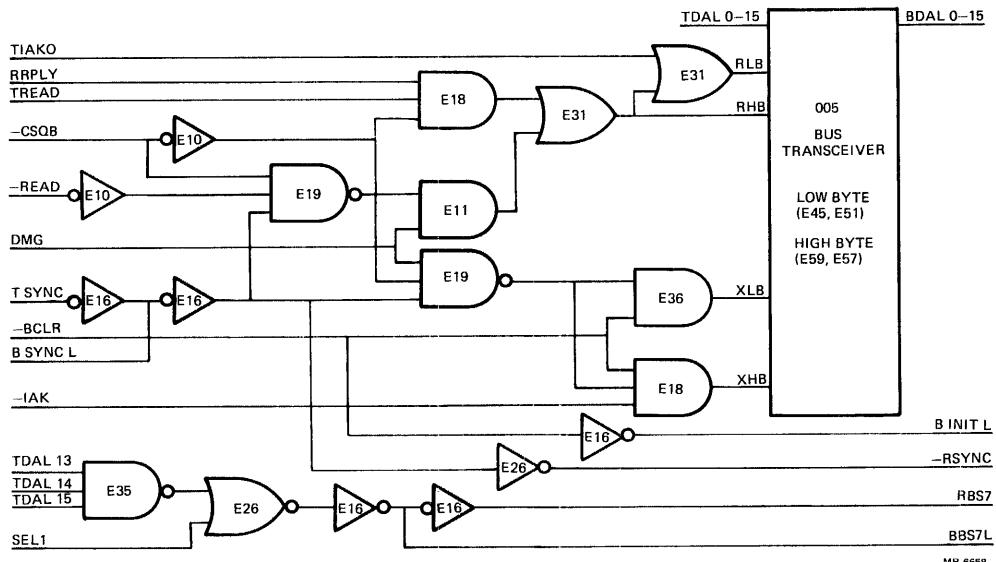


Figure 8-27 Bus Control

The receive function of the bus transceivers will override the transmit function any time the receive inputs are enabled high. When data is to be read from an LSI-11 bus device, the -CSQB input is low and inverter E10 makes it a high input to AND gate E18. The TREAD input to AND gate E18 is set high for the receive function. When the data is on the bus the DRRPLY input to AND gate E18 goes high and the output of the gate goes high. The two OR gates E31 allow the high output to enable the Receive Low Byte and Receive High Byte inputs to the transceivers. The data is now read onto the TDAL bus. During an interrupt transaction, the TIAKO input goes high and enables only the Receive Low Byte input of the transceivers.

The DMG transaction grants bus control to the external device that requested the direct memory grant. The DMG input goes high for the duration of the DMG transaction. This input enables the AND gate E11 and the NAND gate E19. The BSYNC L input is high and inverted low to the two NAND gates E19. This switches the NAND gate outputs high and the receive and transmit functions are both enabled. However, the receive function overrides the transmit function and the TDAL bus receives data from the BDAL bus. This condition exists until the bus master asserts the BDIN L input low. It is inverted high and enables the NAND gate E19. The -CSQB input is dependent upon the address received from the BDAL bus. This input is low if the address is a bus location and high if the address is for the local memory or I/O device. A low input sets the output of NAND gate E19 high and enables the receive function of the transceivers. At the same time, the -CSQB low input is inverted high and the output of NAND gate E19 is switched low to disable the transmit function. When the -CSQB input is high indicating the local memory is being addressed, the NAND gate E19 is enabled. The -CSQB high input is also inverted low to NAND gate E19 and enables the receive function. The bus master now asserts either BDIN L or BDOUT L bus signals. The -READ input goes low for the BDIN L signal and goes high for the BDOUT L signal. If -READ goes high, it is inverted low and switches the output of NAND gate E19 high to enable the receive function. If -READ goes low, it is inverted high and switches the output of NAND gate E19 low to inhibit the receive function and the transmit function remains enabled. Therefore, when the bus master asserts the BDIN L bus signal, the data is transmitted from the module and when it asserts the BDOUT L bus signal the data is received by the module even if it was not addressed.

The BBS7 L bus signal is enabled low whenever the bus addresses the I/O page during the address portion of a transaction. This consists of the upper 8K bytes from 56KB to 64KB. This page is normally reserved for I/O devices on the LSI-11 bus, but the 4K bytes of local RAM memory resides within this page. It is also possible to have an additional 2K bytes of memory located within this page.

To address this page, the TDAL bus bits 13, 14, and 15 are set high and are inputs to NAND gate E35. The output is switched low and goes to the NOR gate E26. The SEL1 input to NOR gate E26 is low for read, write and fetch transactions. When both inputs to NOR gate E26 are low, the output is switched high. This is inverted to a low for BBS7 L output. It is inverted again to set RBS7 high.

9.0 GENERAL

The LSI-11 bus provides interconnections for LSI-11 type modules such as processors, memories, and interfaces to communicate with each other. Not all of the bus functions are supported by the SBC-11/21. Only the supported functions are described in this chapter. For a more complete treatment of the LSI-11 bus the reader is referred to the PDP-11 Bus Handbook.

The LSI-11 bus has 40 signal lines, 18 are devoted to data and 22 are for control. The SBC-11/21 supports only 16 data lines and 18 control lines.

There are four groups of control lines.

a. Six data transfer control lines:

BBS7
BDIN
BDOU
BRPLY
BSYNC
BWTBT

b. Four direct memory access control lines:

BDMGI
BDMGO
BDMR
BSACK

c. Six interrupt control lines:

BIAKI
BIAKO
BIRQ4
BIRQ5 Not used by SBC-11/21
BIRQ6 Not used by SBC-11/21
BIRQ7 Not used by SBC-11/21

d. Six system control lines:

BDCOK
BPOK
BHALT
BINIT
BREF Not used by SBC-11/21
BEVNT

(Refer to Table 9-4 for functional description of these signals.)

Most LSI-11 Bus signals are bidirectional and use terminations for a negated (high) signal level. Modules connect to these lines via high-impedance bus receivers and open collector drivers. The asserted state is produced when a bus driver asserts the line low. Although bidirectional lines are electrically bidirectional (any point along the line can be driven or received), certain lines are functionally unidirectional. These lines communicate to or from a bus master or signal source, but not both. Interrupt acknowledge (BIAK) and direct memory access grant (BDMG) signals are physically unidirectional in a daisy-chain fashion. These signals originate at the processor output signal pins. Each is received on device input pins (BIAKI or BDMGI) and conditionally retransmitted via device output pins (BIAKO or BDMGO). These signals are received from higher priority devices and are retransmitted to lower priority devices along the bus.

9.1 SBC-11/21 SINGLE BOARD COMPUTER

The SBC-11/21 module functions on the LSI-11 bus and can act as a bus-master, a bus slave, or a bus arbitrator and allows a DMA master to access the on board functions. The module supports only 16 data/address lines and terminates the excess lines. It also contains its own on-board memory and accesses the bus for external memory or devices. It should be noted, however, that while accessing its on-board devices the SBC-11/21 asserts bus control signals in the same manner as when communicating with the LSI-11 bus. The memory maps defining on-board and external addressing are described in Chapter 2. The module's microprocessor supports an on board multilevel interrupt structure and the BIRQ4 bus interrupt control line is an active bus interrupt with a level four priority. Therefore the BIRQ5, BIRQ6, and BIRQ7 bus control interrupt lines are not recognized or accepted by the SBC-11/21 module. The DMA request is recognized by the module at the lowest interrupt level, but once the DMA master has accessed the bus, there are no other interrupts until the transfer is complete or the DMA master relinquishes the bus. The module does not use or support the BREF control line for refreshing dynamic memory.

9.2 MASTER/SLAVE RELATIONSHIP

Communication between devices on the bus is asynchronous. A master/slave relationship exists throughout each bus transaction. At any time, there is one device that has control of the bus. This controlling device is termed the bus master. The master device controls the bus when communicating with another device on the bus, termed the slave. The bus master (typically the processor or a DMA device) initiates a bus transaction. The slave device responds by acknowledging the transaction in progress and by receiving data from, or transmitting data to, the bus master. LSI-11 Bus control signals transmitted or received by the bus master or bus slave device must complete the sequence according to bus protocol.

The processor controls bus arbitration, i.e., who becomes bus master at any given time. A typical example of this relationship is the processor, as master, fetching an instruction from memory,

which is always a slave. Another example is a disk, as master, transferring data to memory as slave. Communication on the LSI-11 Bus is interlocked so that for certain control signals issued by the master device, there must be a response from the slave in order to complete the transfer. It is the master/slave signal protocol that makes the LSI-11 Bus asynchronous. The asynchronous operation precludes the need for synchronizing with, and waiting for, clock pulses.

Since bus cycle completion by the bus master requires response from the slave device, each bus master must include a time-out error circuit that will abort the bus cycle if the slave device does not respond to the bus transaction within 10 microseconds.

The actual time before a time-out error occurs must be longer than the reply time of the slowest peripheral or memory device on the bus.

The signal assignments are shown in Table 9-1.

Table 9-1 Signal Assignments

Number of Pins	Functional Category	Signal Names
16	Data/Address	BDAL0, BDAL1, BDAL2...BDAL15,
6	Data Control	BDOUT, BRPLY, BDIN, BSYNC, BWTBT, BBS7
3	Interrupt Control	BIRQ4, BIAKO, BIAKI
4	DMA Control	BDMR, BDGO, BDMGI, BSACK
5	System Control	BHALT, BDCOK, BPOK, BEVNT, BINIT
3	+5 Vdc	
2	+12 Vdc	
2	-12 Vdc	
1	+5 B (battery)	
8	GND	
8	SSPARES	
4	MSPARES	
2	PSPARES	

9.3 DATA TRANSFER BUS CYCLES

Data transfer bus cycles are listed and defined in Table 9-2.

NOTE

The SBC-11/21 microcomputer performs a read transaction before every write transaction. It does not perform DATIO or DATIOB bus transactions as one address. It executes read-modify-write instructions by addressing the source as one transaction and addressing the destination as another transaction.

Table 9-2 Data Transfer Operations

Bus Cycle Mnemonic	Description	Function (with Respect to the Bus Master)
DATI	Data word input	Read
DATO	Data word output	Write
DATOB	Data byte output	Write byte

These bus cycles, executed by bus master devices, transfer 16-bit words or 8-bit bytes to or from slave devices. The bus signals listed in Table 9-3 are used in the data transfer operations described in Table 9-2.

Table 9-3 Bus Signals Used in Data Transfer Operations

Mnemonic	Description	Function
BDAL <15:00> L	16 Data/address lines	BDAL<15:00> L are used for word and byte transfers.
BSYNC L	Bus Cycle Control	Strobe signal.
BDIN L	Data input indicator	Strobe signal.
BDOOUT L	Data output indicator	Strobe signal.
BRPLY L	Slave's acknowledge of bus cycle	Strobe signal.
BWTBT L	Write/byte control	Control signal.
BBS7	I/O device select Indicates address is in the I/O page	Control signal.

Data transfer bus cycles can be reduced to two basic types: DATI, and DATO(B). These transactions occur between the bus master and one slave device selected during the addressing portion of the bus cycle.

9.3.1 Bus Cycle Protocol

Before initiating a bus cycle, the previous bus transaction must have been completed (BSYNC L negated) and the device must become bus master. The bus cycle can be divided into two parts, an addressing portion, and a data transfer portion. During the addressing portion, the bus master outputs the address for the desired slave device, memory location or device register. The selected slave device responds by latching the address bits and holding this condition for the duration of the bus cycle until BSYNC L becomes negated. During the data transfer portion, the actual data transfer occurs.

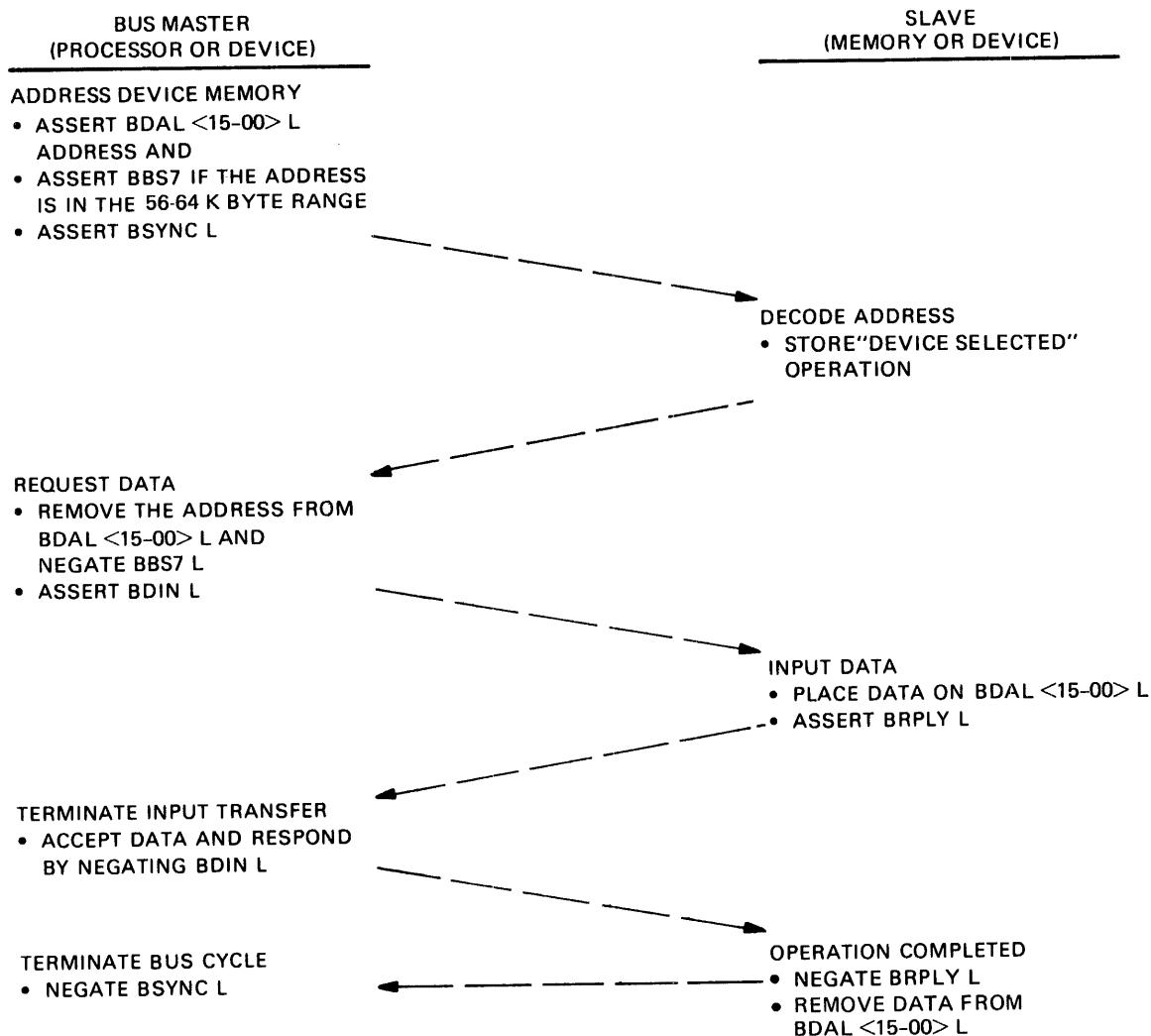
9.3.1.1 Device Addressing -- The device addressing portion of a data transfer bus cycle comprises an address setup and deskew time and an address hold and deskew time. During the address setup and deskew time, the bus master does the following:

- o Asserts BDAL <15:00> L with the desired slave device address bits
- o Asserts BBS7 L if a device in the I/O page (56--64 Kb for SBC-11/21) is being addressed. Devices in the I/O page ignore BDAL <15:13>, and decode BBS7 L along with BDAL <12:00>.
- o Asserts BWTBT L if the cycle is a DATO(B) bus cycle. Inactive BWTBT L indicates a DATI or DATIO (B) operation.
- o Asserts BSYNC at least 150 ns after BDAL <15:00> L, BBS7 L and BWTBT L are valid.

The address, BBS7 L, and BWTBT L signals must be asserted at the slave bus receiver for at least 75 ns before BSYNC goes active. The address hold and deskew time begins after BSYNC L is asserted.

The slave device uses the active BSYNC L bus receiver output to clock BDAL address bits, BBS7 L, and BWTBT L into its internal logic. BDAL <15:00> L, BBS7 L, and BWTBT L will remain active for 25 ns (minimum) after BSYNC L bus receiver goes active. BSYNC L remains active for the duration of the bus cycle.

Memory devices generally do not respond to addresses in the I/O page; however, some system applications may permit memory to reside in the I/O page for use as DMA buffers, read-only memory bootstraps or diagnostics, etc.



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Figure 9-1 DATI Bus Cycle

DATI -- The DATI bus cycle, illustrated in Figure 9-1, is a read operation. During DATI, data are input to the bus master. Data consist of 16-bit word transfers over the bus. During the data transfer portion of the DATI bus cycle, the bus master asserts BDIN L 100 ns minimum after BSYNC L is asserted. The slave device responds to BDIN L active as follows:

- o Asserts BRPLY L after receiving BDIN L and 125 ns (maximum) before BDAL bus driver data bits are valid
- o Asserts BDAL <15:00> L with the addressed data

When the bus master receives BRPLY L, it does the following:

- o Waits at least 200 ns deskew time and then accepts input data at BDAL <15:00> L bus receivers.
- o Negates BDIN L 150 ns (minimum) to 2 microseconds (maximum) after BRPLY L goes active.

NOTE

Continuous assertion of BSYNC L retains control of the bus by the bus master, and the previously addressed slave device remains selected. Also, a slow slave device can hold off data transfers to itself by keeping BRPLY L asserted, which will cause the master to keep BSYNC L asserted.

The slave device responds to BDIN L negation by negating BRPLY L and removing read data from BDAL bus drives. BRPLY L must be negated 100 ns (maximum) prior to removal of read data. The bus master responds to the negated BRPLY L by negating BSYNC L.

Conditions for the next BSYNC L assertion are as follows:

- o BSYNC L must remain negated for 200 ns (minimum)
- o BSYNC L must not become asserted within 300 ns of previous BRPLY L negation

Figure 9-2 illustrates DATI bus cycle timing.

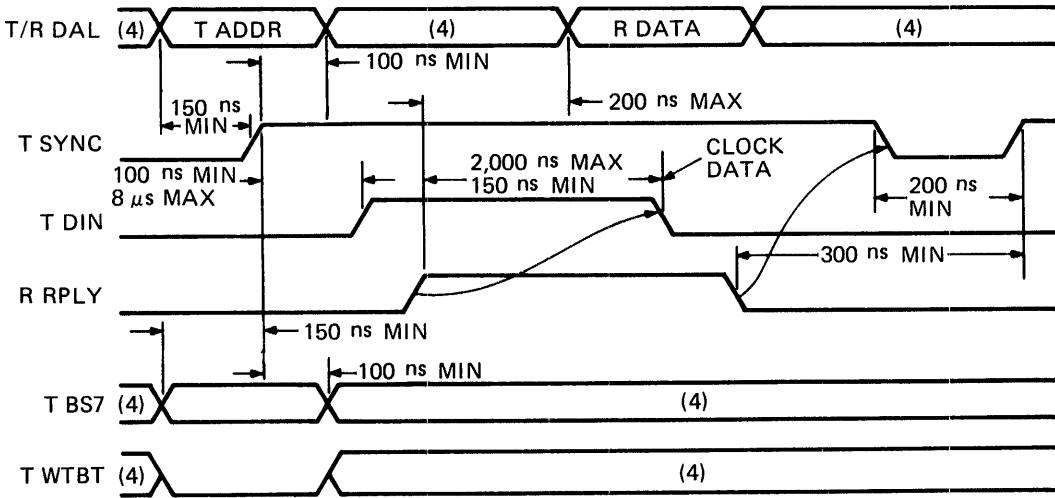
DATO(B) -- DATO(B), illustrated in Figure 9-3, is a write operation. Data is transferred in 16-bit words (DATO) or 8-bit bytes (DATOB) from the bus master to the slave device. The data transfer output can occur after the addressing portion of a bus cycle when BWTBT L has been asserted by the bus master.

The data transfer portion of a DATO(B) bus cycle comprises a data setup and deskew time and a data hold and deskew time.

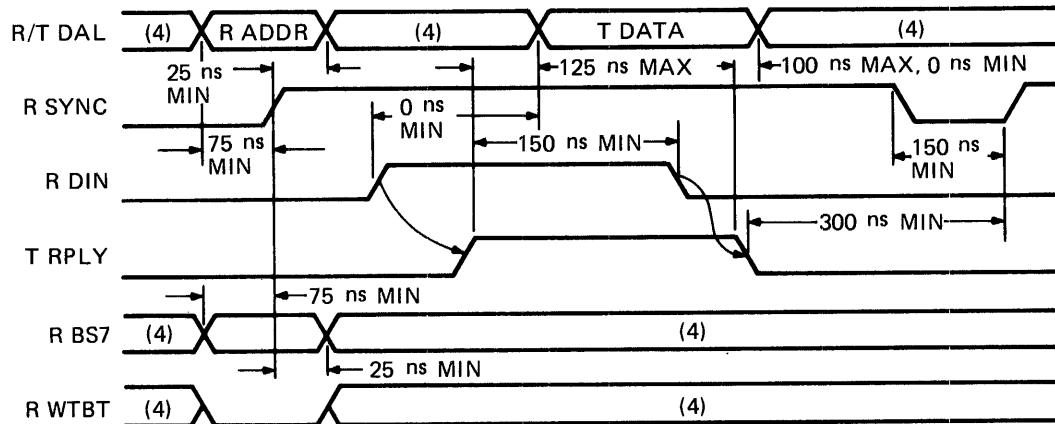
During the data setup and deskew time, the bus master outputs the data on BDAL <15:00> L at least 100 ns after BSYNC L is asserted. If it is a word transfer, the bus master negates BWTBT L at least 100 ns after BSYNC L assertion. BWTBT L remains negated for the length of the bus cycle. If the transfer is a byte transfer, BWTBT L remains asserted. During a byte transfer, BDAL 00 L selects the high or low byte. This occurs while in the addressing portion of the cycle. If asserted, the high byte (BDAL <15:08> L) is selected; otherwise, the low byte (BDAL <07:00> L) is selected. The bus master asserts BDOU T L at least 100 ns after BDAL and BWTBT L bus drives are stable. The slave device responds by asserting BRPLY L within 10 microseconds to avoid bus time-out. This completes the data setup and deskew time.

During the data hold and deskew time the bus master receives BRPLY L and negates BDOU T L. BDOU T L must remain asserted for at least 150 ns from the receipt of BRPLY L before being negated by the bus master. BDAL <15:00> L bus drivers remain asserted for at least 100 ns after BDOU T L negation. The bus master then negates BDAL inputs.

TIMING AT MASTER DEVICE



TIMING AT SLAVE DEVICE



NOTES:

1. TIMING SHOWN AT MASTER AND SLAVE DEVICE BUS DRIVER INPUTS AND BUS RECEIVER OUTPUTS
2. SIGNAL NAME PREFIXES ARE DEFINED BELOW:
T = BUS DRIVER INPUT
R = BUS RECEIVER OUTPUT
3. BUS DRIVER OUTPUT AND BUS RECEIVER INPUT SIGNAL NAMES INCLUDE A "B" PREFIX
4. DON'T CARE CONDITION

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Figure 9-2 DATI Bus Cycle Timing

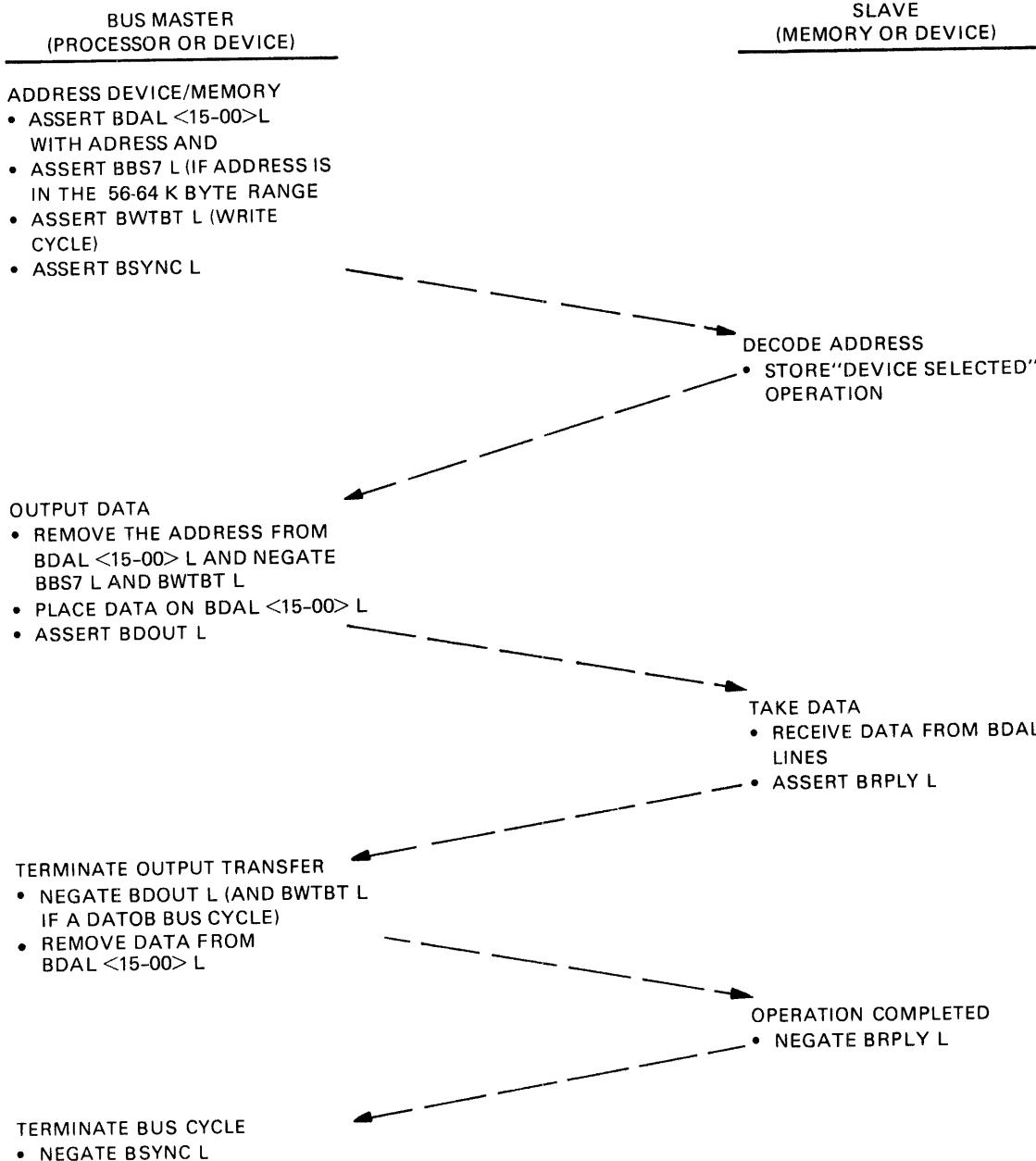
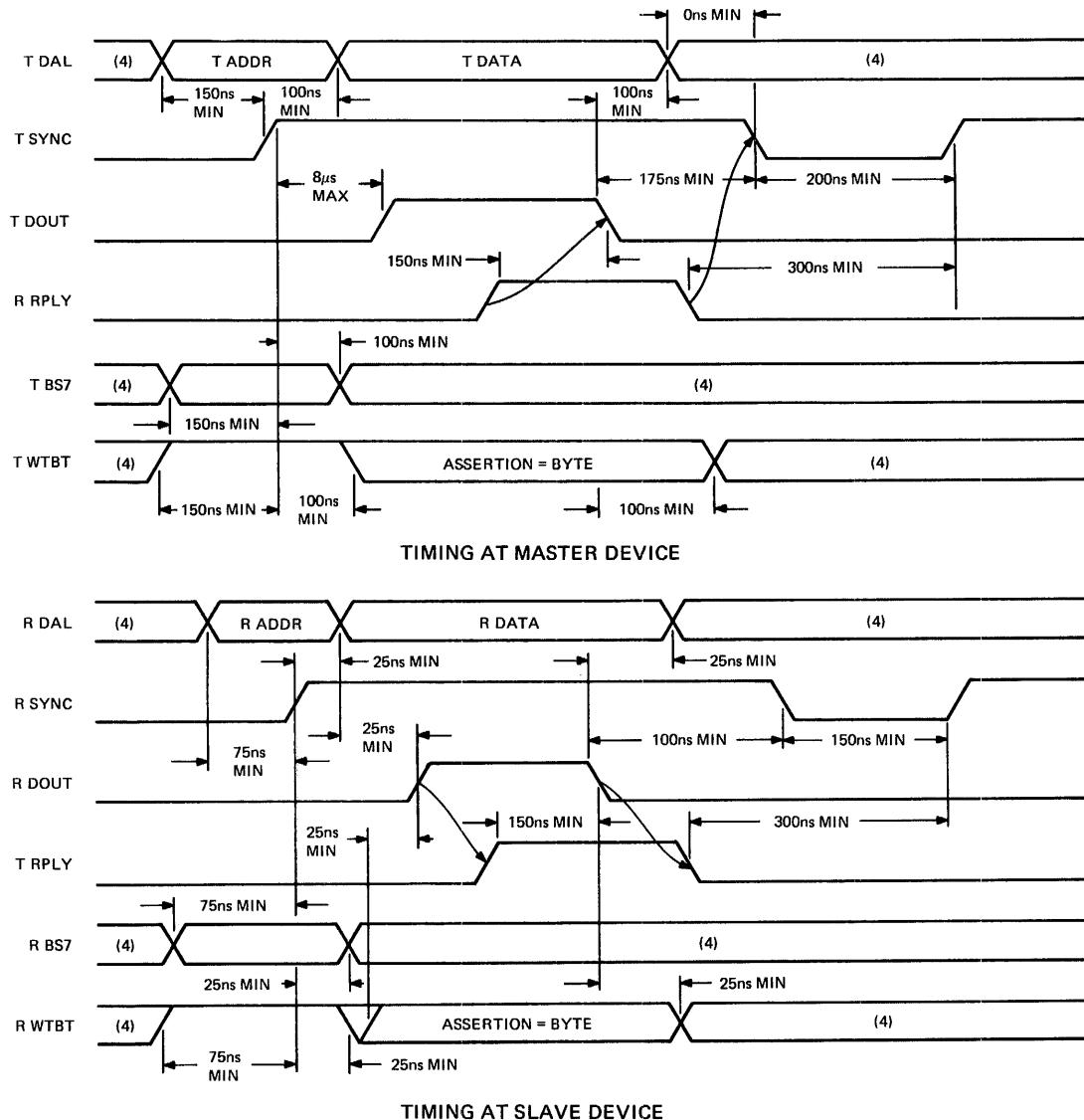


Figure 9-3 DATO or DATOB Bus Cycle

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During this time, the slave device senses BDOUT L negation. The data are accepted and the slave device negates BRPLY L. The bus master responds by negating BSYNC L. However, the processor will not negate BSYNC L for at least 175 ns after negating BDOUT L. This completes the DATO(B) bus cycle. Before the next cycle BSYNC L must remain unasserted for at least 200 ns. Figure 9-4 illustrates DATO(B) bus cycle timing.



NOTES:

1. TIMING SHOWN AT MASTER AND SLAVE DEVICE 3. BUS DRIVER OUTPUT AND BUS RECEIVER INPUT
BUS DRIVER INPUTS AND BUS RECEIVER OUTPUTS. SIGNAL NAMES INCLUDE A "B" PREFIX.

2. SIGNAL NAME PREFIXES ARE DEFINED BELOW:

T = BUS DRIVER INPUT

R = BUS RECEIVER OUTPUT

4. DON'T CARE CONDITION.

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Figure 9-4 DATO or DATOB Bus Cycle Timing

9.3.2 Direct Memory Access

DMA is accomplished after the processor (normally bus master) has passed bus mastership to the highest priority DMA device that is requesting the bus. The processor arbitrates all requests and grants the bus to the DMA device located electrically closest to it. A DMA device remains bus master indefinitely until it relinquishes its mastership. The following control signals are used during bus arbitration.

BDMGI L	DMA Grant Input
BDMGO L	DMA Grant Output
BDMR L	DMA Request Line
BSACK L	Bus Grant Acknowledge

A DMA transaction can be divided into three phases:

- o Bus mastership acquisition phase
- o Data transfer phase
- o Bus mastership relinquish phase

During the bus mastership acquisition phase, a DMA device requests the bus by asserting BDMR L. The processor arbitrates the request and initiates the transfer of bus mastership by asserting BDMGO L. The maximum time between BDMR L assertion and BDMGO L assertion is DMA latency. This is processor-dependent. BDMGO L/BDMGI L is one signal that is daisy-chained through each module in the backplane. It is driven out of the processor on the BDMGO L pin, enters each module on the BDMGI L pin and exits on the BDMGO L pin. This signal passes through the modules in descending order of priority until it is stopped by the requesting device. The requesting device blocks the output of BMDGO L and asserts BSACK L. If BDMR L is continuously asserted, the bus will be hung.

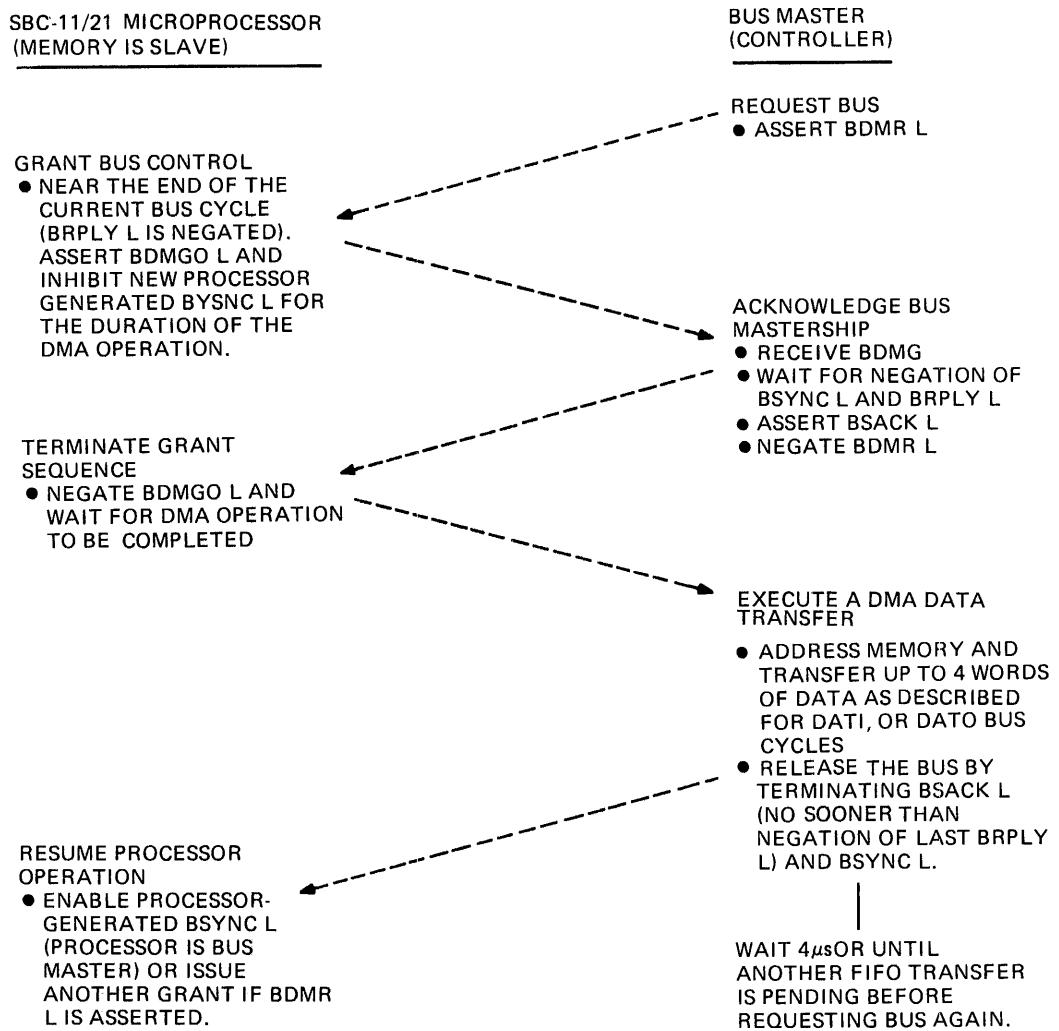
During the data transfer phase, the DMA device continues asserting BSACK L. The actual data transfer is performed as described earlier.

NOTE

If multiple data transfers are performed during this phase, consideration must be given to the use of the bus for other system functions.

The DMA device can assert BSYNC L for a data transfer 250 ns (minimum) after it receives BDMGI L and its BSYNC L and BRPLY L become negated.

During the bus mastership relinquish phase, the DMA device relinquishes the bus by negating BSACK L. This occurs after completing (or aborting) the last data transfer cycle (BRPLY L negated). BSACK L may be negated up to a maximum of 300 ns before negating BSYNC L. Figure 9-5 illustrates the DMA protocol and



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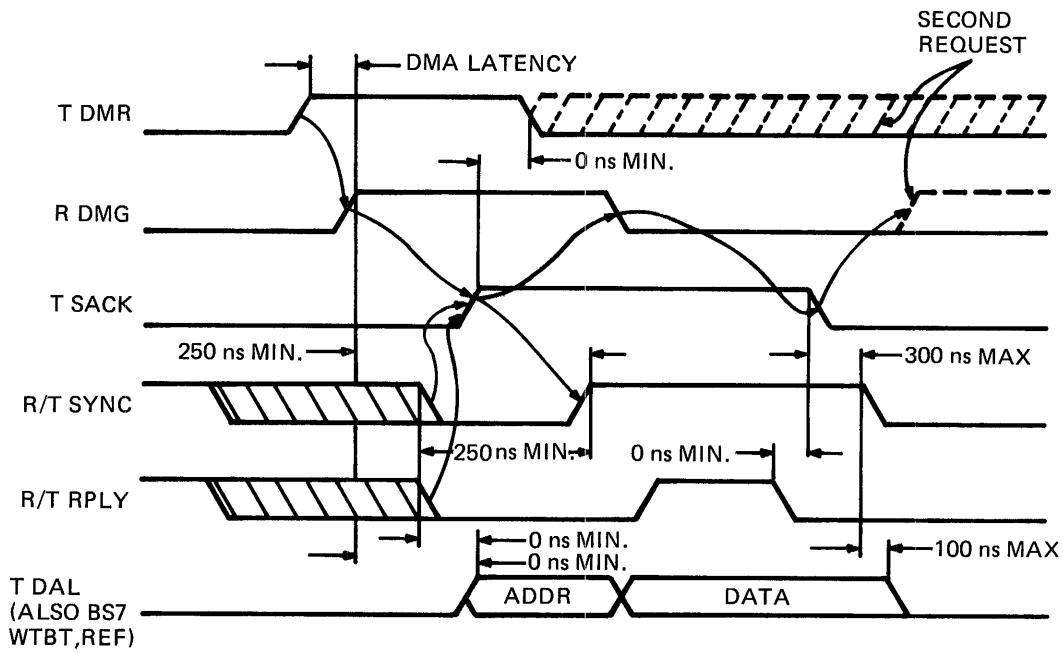
Figure 9-5 DMA Protocol

Figure 9-6 illustrates DMA request/grant timing.

9.4 INTERRUPTS

The LSI-11 Bus signals used in interrupt transactions are:

BIRQ4 L	Interrupt request priority level 4
BIAKI L	Interrupt acknowledge input
BIAKO L	Interrupt acknowledge output
BDAL <15:00> L	Data/address lines
BDIN L	Data input strobe
BRPLY L	Reply



NOTES:

- 1 TIMING SHOWN AT REQUESTING DEVICE BUS DRIVER INPUTS AND BUS RECEIVER OUTPUTS.
- 2 SIGNAL NAME PREFIXES ARE DEFINED BELOW
 T = BUS DRIVER INPUT
 R = BUS RECEIVER OUTPUT
- 3 BUS DRIVER OUTPUT AND BUS RECEIVER INPUT SIGNAL NAMES INCLUDE A "B" PREFIX

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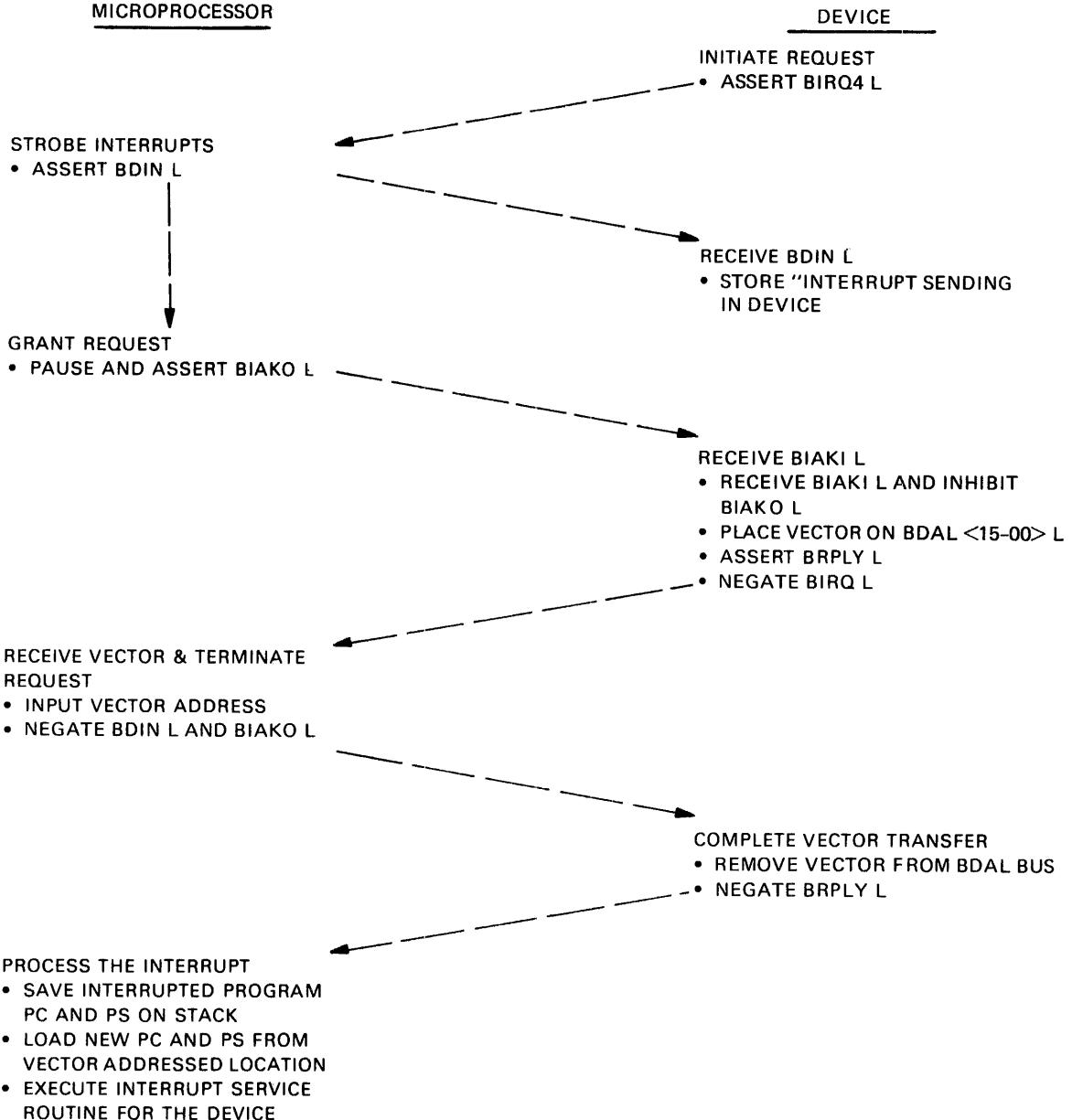
Figure 9-6 DMA Request/Grant Timing

9.4.1 Device Priority

The SBC-11/21 supports only one method of device priority arbitration: position-defined arbitration -- priority is determined solely by electrical position on the bus. The closer a device is to the processor, the higher its priority is.

9.4.2 Interrupt Protocol

Interrupt protocol on the SBC-11/21 has three phases: interrupt request phase, interrupt acknowledge and priority arbitration phase, and interrupt vector transfer phase. Figure 9-7 illustrates the interrupt request/acknowledge sequence.



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Figure 9-7 Interrupt Request/Acknowledge Sequence

The interrupt request phase begins when a device meets its specific conditions for interrupt requests. For example, the device is ready, done, or an error has occurred. The interrupt enable bit in a device status register must be set. The device then initiates the interrupt by asserting the interrupt request line. BIRQ4 L is the only hardware priority level on SBC-11/21 and is asserted for all interrupt requests.

The interrupt request line remains asserted until the request is acknowledged.

During the interrupt acknowledge and priority arbitration phase the SBC-11/21 processor will acknowledge interrupts under the following conditions:

1. The device interrupt priority is higher than the current PS<7:5>.
2. The processor has completed instruction execution and no additional bus cycles are pending.

The processor acknowledges the interrupt request by asserting BDIN L, and 225 ns (minimum) later asserting BIAKO L. The device electrically closest to the processor receives the acknowledge on its BIAKI L bus receiver.

When the device receives the acknowledge, it reacts as follows:

- o If not requesting an interrupt, the device asserts BIAKO L and the acknowledge propagates to the next device on the bus.
- o If the device was requesting an interrupt, the acknowledge is blocked using the leading edge of BDIN L and arbitration is won. The interrupt vector transfer phase begins.

The interrupt vector transfer phase is enabled by BDIN L and BIAKI L. The device responds by asserting BRPLY L and its BDAL <15:00> L bus driver inputs with the vector address bits. The BDAL bus driver inputs must be stable within 125 ns (maximum) after BRPLY L is asserted. The processor then inputs the vector address and negates BDIN L and BIAKO L. The device then negates BRPLY L and 100 ns (maximum) later removes the vector address bits. The processor then enters the device's service routine.

NOTE

Propagation delay from BIAKI L to BIAKO L must not be greater than 500 ns per LSI-11 Bus slot.

The device must assert BRPLY L within 10 microseconds (maximum) after the processor asserts BIAKI L.

9.5 CONTROL FUNCTIONS

The following LSI-11 Bus signals provide control functions.

BHALT L	Processor halt
BINIT L	Initialize
BPOK H	Power OK
BDCOK H	DC power OK
BEVNT L	External Event

9.5.1 Halt

Refer to Chapter 2 for explanation of BHALT L response.

9.5.2 Initialization

Devices along the bus are initialized when BINIT L is asserted. The microprocessor can assert BINIT L as a result of executing a RESET instruction or as part of a power-up sequence. BINIT L is asserted for approximately 17 microseconds when RESET is executed.

9.5.3 Power Status

Power status protocol is controlled by two signals, BPOK H and BDCOK H. These signals are driven by some external device (usually the power supply).

BDCOK H -- When asserted, this indicates that dc power has been stable for at least 3 ms. Once asserted, this line remains asserted until the power fails. Its negation indicates that only 5 microseconds of dc power reserve remains.

BPOK H -- When asserted this indicates that there is at least an 8 ms reserve of dc power and that BDCOK H has been asserted for at least 70 ms. Once BPOK H has been asserted, it must remain asserted for at least 3 ms. The negation of this line, the first event in the power-fail sequence, indicates that power is failing and that only 4 ms of dc power reserve remains.

9.5.4 Power-Up/Down Protocol

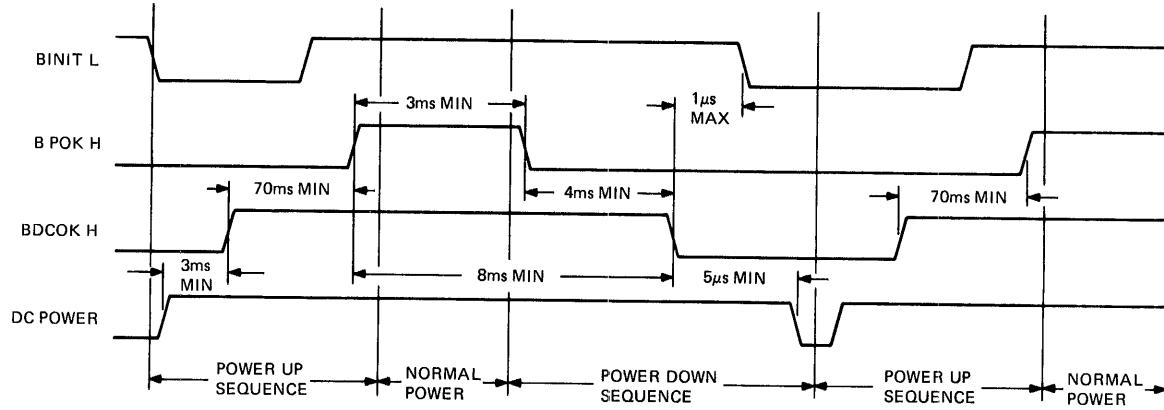
Power-up protocol (Figure 9-8) begins when the power supply applies power with BDCOK H negated. This forces the processor to assert BINIT L. When the dc voltages are stable, the power supply or other external device asserts BDCOK H. The processor responds by clearing the PS. BINIT L is asserted for 17 microseconds and then negated for 110 microseconds. The processor continues to test for BPOK H until it is asserted. The power supply asserts BPOK H 70 ms (minimum) after BDCOK H is asserted. The processor then performs its power-up sequence. Normal power must be maintained at least 3.0 ms before a power-down sequence can begin.

A power-down sequence begins when the power supply negates BPOK H. When the current instruction is completed, the microprocessor traps to a power-down routine at location 24. The routine must provide for loading 340 into the PSW, execute a RESET instruction and must terminate in a WAIT instruction or branch on itself.

There should be no DMA requests issued after the RESET is executed. This procedure prevents any possible memory corruption in the battery supported system as the dc voltages decay.

NOTE

SBC-11/21 does not generate BINIT L during the power-down sequence. The power-down routine must therefore include a RESET instruction to set bus devices into a known state.



NOTE:

ONCE A POWER DOWN SEQUENCE IS STARTED,
IT MUST BE COMPLETED BEFORE A POWER UP
SEQUENCE IS STARTED.

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Figure 9-8 Power-Up/Power-Down Timing

9.6 LSI-11 BUS ELECTRICAL CHARACTERISTICS

Configuring LSI-11 bus systems requires an appreciation of its transmission line characteristics which can be best obtained from the PDP-11 Bus Handbook.

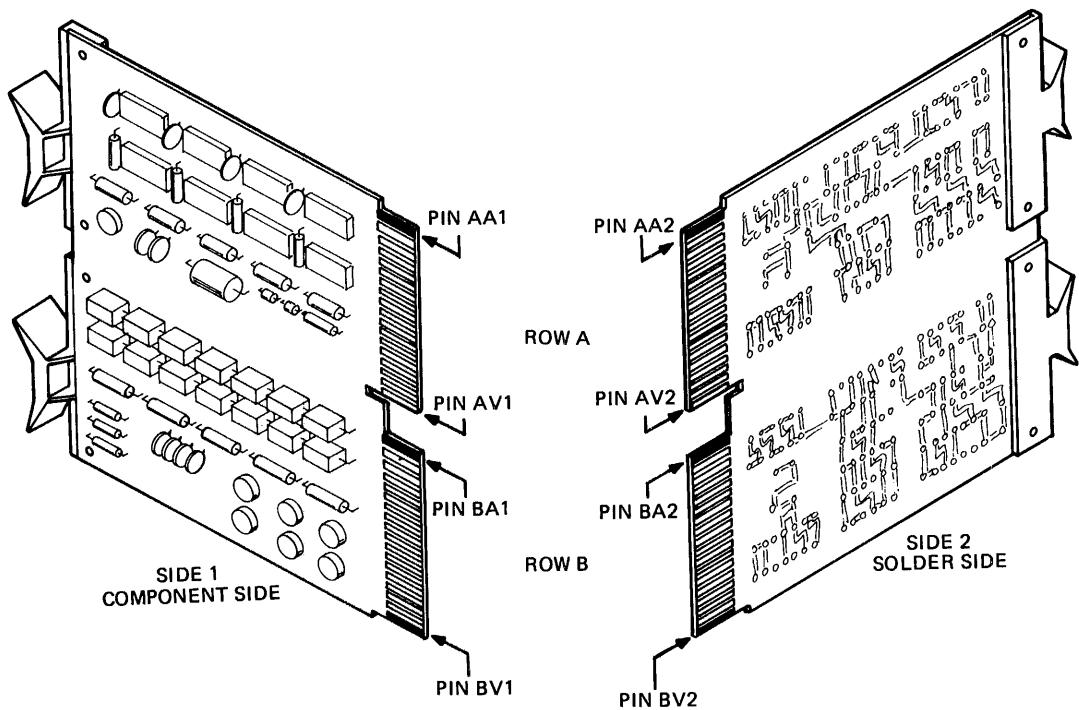
9.7 MODULE CONTACT FINGER IDENTIFICATION

DIGITAL plug-in modules, including the SBC-11/21, all use the same contact finger (pin) identification system. The LSI-11 bus is based on the use of double-height modules that plug into a 2-slot bus connector. Each slot contains 36 lines (18 each on component and solder sides of circuit board).

Slots, shown as row A and row B in Figure 9-9, include a numeric identifier for the side of the module. The component side is designated side 1 and the solder side is designated side 2. Letters ranging from A through V (excluding G, I, O, and Q) identify a particular pin on a side of a slot. Table 9-4 lists and identifies the bus pins of the double-height module. For a quick summary refer to Table 1-1. The bus pin identifier ending with a 1 is found on the component side of the board, while a bus pin identifier ending with a 2 is found on the solder side of the board. A typical pin is designated as follows.

AE2: Row A, pin E, Side 2

The positioning notch between the two rows of pins mates with a protrusion on the connector block for correct module positioning.



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Figure 9-9 Double-Height Module Contact Finger Identification

Table 9-4 Bus Pin Identifiers

Bus Pin	Mnemonics	Description
AE1	SSPARE1 (Alternate +5B)	Special Spare -- not assigned or bused in DIGITAL cable or backplane assemblies; available for user connection. Optionally, this pin may be used for +5 V battery (+5B) backup power to keep critical circuits alive during power failures. A jumper is required on LSI-11 bus options to open (disconnect) the +5B circuit in systems that use this line as SSPARE1.
AF1	SSPARE2	Special Spare -- not assigned or bused in DIGITAL cable or backplane assemblies; available for user interconnection.
AJ1	GND	Ground -- System signal ground and dc return.
AK1	MSPAREA	
ALL	MSPAREA	Maintenance Spare -- Normally connected together on the backplane at each option location (not bused connection).
AM1	GND	Ground -- System signal ground and dc return.
AN1	BDMR L	Direct Memory Access (DMA) Request -- A device asserts this signal to request bus mastership. The processor arbitrates bus mastership between itself and all DMA devices on the bus. If the processor is not bus master (it has completed a bus cycle and BSYNC L is not being asserted by the processor), it grants bus mastership to the requesting device by asserting BDMGO L. The device responds by negating BDMR L and asserting BSACK L.
AP1	BHALT L	Processor Halt -- Refer to Chapter 2.
AT1	GND	Ground -- System signal ground and dc return.
AU1	PSPARE 1	Spare (Not assigned. Customer usage not recommended.) Prevents damage when modules are inserted upside down.

Table 9-4 Bus Pin Identifiers (Cont)

Bus Pin	Mnemonics	Description
AV1	+5B	+5 V Battery Power -- Secondary +5 V power connection. Battery power can be used with certain devices.
BAL	BDCOK H	DC Power OK -- Power supply-generated signal that is asserted when there is sufficient dc voltage available to sustain reliable system operation.
BB1	BPOK H	Power OK -- Asserted by the power supply 70 ms after BDCOK. Negated when ac power drop below the value required to sustain power (approximately 75% of nominal). When negated during processor operation, a power fail trap sequence is initiated.
BH1	SSPARE8	Special Spare -- Not assigned or bused in DIGITAL cable and backplane assemblies; available for user interconnection.
BJ1	GND	Ground -- System signal ground and dc return.
BK1 BL1	MSPAREB MSPAREB	Maintenance Spare -- Normally connected together on the backplane at each option location (not a bused connection).
BM1	GND	Ground -- System signal ground and dc return.
BN1	BSACK L	This signal is asserted by a DMA device in response to the processor's BDMGO L signal, indicating that the DMA device is bus master.
BR1	BEVNT L	External Event Interrupt Request -- When asserted, the processor responds (if PS bit 7 is 0) by entering a service routine via vector address 100. A typical use of this signal is a line time clock interrupt.
BS1	PSPARE 4	Power Spare 4 (Not assigned a function, not recommended for use).

Table 9-4 Bus Pin Identifiers (Cont)

Bus Pin	Mnemonics	Description
BT1	GND	Ground -- System signal ground and dc return.
BU1	PSPARE2	Power Spare 2 (not assigned a function, not recommended for use). If a module is using -12 V (on pin AB2) and if the module is accidentally inserted upside down in the backplane, -12 Vdc appears on pin BU1.
BV1	+5	+5 V Power -- Normal +5 Vdc system power.
AA2	+5	+5 V Power -- Normal +5 Vdc system power.
AB2	-12	-12 V Power -- -12 Vdc (optional) power for devices requiring this voltage.

NOTE

LSI-11 modules which require negative voltages contain an inverter circuit (on each module) which generates the required voltage(s). Hence, -12 V power is not required with DIGITAL-supplied options.

AC2	GND	Ground -- System signal ground and dc return.
AD2	+12	+12 V Power -- 12 Vdc system power.
AE2	BDOUT L	Data Output -- BDOUT, when asserted, implies that valid data is available on BDAL <0:15> L and that an output transfer, with respect to the bus master device, is taking place. BDOUT L is deskewed with respect to data on the bus. The slave device responding to the BDOUT L signal must assert BRPLY L to complete the transfer.
AF2	BRPLY L	Reply -- BRPLY L is asserted in response to BDIN L or BDOUT L and during IAK transactions. It is generated by a slave device to indicate that it has placed its data on the BDAL bus or that it has accepted output data from the bus.

Table 9-4 Bus Pin Identifiers (Cont)

Bus Pin	Mnemonics	Description
AH2	BDIN L	<p>Data Input -- BDIN L is used for two types of bus operation:</p> <p>When asserted during BSYNC L time, BDIN L implies an input transfer with respect to the current bus master, and requires a response (BRPLY L). BDIN L is asserted when the master device is ready to accept data from a slave device.</p> <p>When asserted without BSYNC L, it indicates that an interrupt operation is occurring.</p> <p>The master device must deskew input data from BRPLY L.</p>
AJ2	BSYNC L	Synchronize -- BSYNC L is asserted by the bus master device to indicate that it has placed an address on BDAL <0:15> L. The transfer is in process until BSYNC L is negated.
AK2	BWTBT L	<p>Write/Byte -- BWTBT L is used in two ways to control a bus cycle:</p> <p>It is asserted at the leading edge of BSYNC L to indicate that an output sequence is to follow (DATO or DATOB), rather than an input sequence.</p> <p>It is asserted during BDOUT L, in a DATOB bus cycle, for byte addressing.</p>
AL2	BIRQ4 L	Interrupt Request Priority Level 4 -- A level 4 device asserts this signal when its interrupt enable and interrupt request flip-flops are set. If the PS word bit 7 is 0, the processor responds by acknowledging the request by asserting BDIN L and BIAKO L.

Table 9-4 Bus Pin Identifiers (Cont)

Bus Pin	Mnemonics	Description
AM2	BIAKI L	
AN2	BIAKO L	<p>Interrupt Acknowledge -- In accordance with interrupt protocol, the processor asserts BIAKO L to acknowledge receipt of an interrupt. The bus transmits this to BIAKI L of the device electrically closest to the processor. This device accepts the interrupt acknowledge under two conditions:</p> <ol style="list-style-type: none"> 1. The device requested the bus by asserting BIRQ4L, and 2. the device has the highest priority interrupt request on the bus at that time. <p>If these conditions are not met, the device asserts BIAKO L to the next device on the bus. This process continues in a daisy-chain fashion until the device with the highest interrupt priority receives the interrupt acknowledge signal.</p>
AP2	BBS7 L	<p>Bank 7 Select -- The bus master asserts this signal to reference the I/O page (including that portion of the I/O page reserved for nonexistent memory). The address in BDAL <0:12> L when BBS7 L is asserted is the address within the I/O page.</p>
AR2	BDMGI L	
AS2	BDMBO L	<p>Direct Memory Access Grant -- The Bus arbitrator asserts this signal to grant bus mastership to a requesting device, according to bus mastership protocol. The signal is passed in a daisy-chain from the arbitrator (as BDMGO L) through the bus to BDMGI L of the next priority device (electrically closest device on the bus). This device accepts the grant only if it requested to be bus master (by a BDMR L). If not, the device passes the grant (asserts BDMGO L) to the next device on the bus. This process continues until the requesting device acknowledges the grant.</p>

Table 9-4 Bus Pin Identifiers (Cont)

Bus Pin	Mnemonics	Description
AT2	BINIT L	Initialize -- This signal is used for system reset. All devices on the bus are to return to a known, initial state; i.e., registers are reset to zero, and logic is reset to state 0. Exceptions should be completely documented in programming and engineering specifications for the device.
AU2	BDAL0 L	Data/Address Lines -- These two lines are part of the 16-line data/address bus over which address and data information are communicated. Address information is first placed on the bus by the bus master device. The same device then either receives input data from, or outputs data to the addressed slave device or memory over the same bus lines.
AV2	BDALL L	
BA2	+5	+5 V Power -- Normal +5 Vdc system power.
BB2	-12	-12 V Power -- -12 Vdc (optional) power for devices requiring this voltage.
BC2	GND	Ground -- System signal ground and dc return.
BD2	+12	+12 V Power -- +12 V system power.
BE2	BDAL2 L	Data/Address Lines -- These 14 lines are part of the 16-line data/address bus previously described.
BF2	BDAL3 L	
BH2	BDAL4 L	
BJ2	BDAL5 L	
BK2	BDAL6 L	
BL2	BDAL7 L	
BM2	BDAL8 L	
BN2	BDAL9 L	
BP2	BDAL10 L	
BR2	BDAL11 L	
BS2	BDAL12 L	
BT2	BDAL13 L	
BU2	BDAL14 L	
BV2	BDAL15 L	

APPENDIX A
INSTRUCTION TIMING

INSTRUCTION TIMING

The following fetch and execute times assume that the SBC-11/21 is transacting with local devices that do not require cycle slips when accessed.

Single Operand Instructions	Destination Mode	Fetch and Execute Time (usec)	Number of Bus Transactions	Number of Microcycles
CLR(B), COM(B),	0	2.44	1	4
INC(B), DEC(B),	1	4.27	3	7
NEG(B), ROR(B),	2	4.27	3	7
ROL(B), ASR(B),	3	5.49	4	9
ASL(B), SWAP,	4	4.88	3	8
ADC(B), SBC(B),	5	6.10	4	10
SXT, MFPS,	6	6.10	4	10
XOR	7	7.32	5	12
TST(B)	0	2.44	1	4
	1	3.66	2	6
	2	3.66	2	6
	3	5.49	3	8
	4	4.27	2	7
	5	5.49	3	9
	6	5.49	3	9
	7	6.71	4	11
MTPS	0	4.88	1	8
	1	6.10	2	10
	2	6.10	2	10
	3	7.32	3	12
	4	6.71	2	11
	5	7.93	3	13
	6	7.93	3	13
	7	9.16	4	15
Double Operand Instructions	Source Mode	Source Mode Time (usec) Includes Fetch		
MOV(B), CMP(B),	0	1.83	1	3
ADD, SUB,	1	3.05	2	5
BIT(B), BIC(B),	2	3.05	2	5
BIS(B)	3	4.27	3	7
	4	3.66	2	6
	5	4.88	3	8
	6	4.88	3	8
	7	6.10	4	10

Double Operand Instructions	Destination Mode	Destination Mode Time (usec)		
MOV(B), CMP(B), ADD, SUB	0	0.61	0	1
BIT(B), BIC(B), BIS(B)	1	2.44	2	4
	2	2.44	2	4
	3	3.66	3	6
	4	3.05	2	5
	5	4.27	3	7
	6	4.27	3	7
	7	5.49	4	9
CMP(B), BIT(B)	0	0.61	0	1
	1	1.83	1	3
	2	1.83	1	3
	3	3.05	2	5
	4	2.44	1	4
	5	3.66	2	6
	6	3.66	2	6
	7	4.88	3	8
Jump and Subroutine Instructions		Fetch and Execute Time (usec)		
JMP	1	3.05	2	5
	2	3.66	2	6
	3	3.66	3	6
	4	3.66	2	6
	5	4.27	3	7
	6	4.27	3	7
	7	5.49	4	9
JSR	1	5.49	4	9
	2	6.10	4	10
	3	6.10	5	10
	4	6.10	4	10
	5	6.71	5	11
	6	6.71	5	11
	7	7.90	6	13
RTS	NA	4.27	2	7
SOB	NA	3.66	1	6
Branch, Trap and Interrupt Instructions		Fetch and Execute Time (usec)		
BR, BNE, BEQ, BPL, BMI, BVC,	NA	2.44	1	4

BVS, BCC, BCS, BGE, BLT, BGT, BLE, BHI, BLOS, BHIS, BLO				
EMT, TRAP BPT, IOT	NA	9.77	7	16
RTI	NA	4.88	3	8
RTT	NA	6.71	3	11
Miscellaneous and Condition Code Instructions	Destination Mode	Fetch and Execute Time (usec)		
HALT	NA	8.54	5	14
WAIT	NA	2.44	1	4 then loop
RESET	NA	22.28	1	39
NOP	NA	3.66	1	6
CLC, CLV, CLZ, CLN, CCC, SEC, SEV, SEZ, SEN, SCC	NA	3.66	1	6
MFPT	NA	3.05	1	5

The measure of LSI-11 BUS interrupt latency is the time from assertion of BIRQ until BIAKI is accepted by the interrupting device electrically closest to the processor on the LSI-11 BUS.

The measure of local interrupt latency is the time from assertion of the request until the time the microprocessor is ready to fetch the first instruction in the interrupt service routine. This time is primarily comprised of the time to perform two pushes and a PC and PSW restore.

DMA latency is known as the period of time between a device asserting its BDMR and receiving BDMGI when it resides on the LSI-11 BUS as the electrically closest DMA device to the processor.

Interrupt Latency:	LOCAL	23.2 usec
	LSI-11 BUS	9.3 usec

NOTE

Assume that the stack and vector memory reside on the SBC-11/21 and that the LSI-11 BUS device can assert BRPLY and vector within 600 nsec after receiving IAKI. The service latency (time from BIRQ until the time the microprocessor is ready to fetch the first instruction in the interrupt service routine) depends on the response time of the interrupting device i.e., RDIN to TRPLY and negation of TRPLY.

DMA latency: 1.3 usec minimum 11.0 usec maximum

WAIT instruction latencies:

internal vector	11.8 usec
external vector	12.4 usec
DMA	5.06 usec

APPENDIX B
PROGRAMMING DIFFERENCE LIST

DIFFERENCE LIST

The following table presents a concise comparison between the SBC-11/21, LSI-11/2, and LSI-11/23.

Activity	SBC-11/21	LSI-11/2	LSI-11/23
OPR %R, (R)+ or OPR %R,-(R) using the same register as both source and destination: contents of R are incremented (decremented) by 2 before being used as the source operand.	X	X	
OPR %R, @(R)+ or OPR %R,@-(R) using the same register as both source and destination: contents of R are incremented (decremented) by 2 before being used as the source operand.	X		X
In the above two cases, initial contents of R are used as the source operand.		X	
OPR PC, X(R); OPR PC,@X(R); OPR PC,@A; OPR PC,A: Location A will contain the PC of OPR + 4.	X		X
In the above case, location A will contain the PC of OPR + 2.		X	
JMP (R)+ or JSR reg,(R)+: Initial contents of R are used as the new PC.	X	X	X
JMP %R or JSR reg,%R traps to 4 (illegal instruction).	X	X	X
Only one LSI-11 bus interrupt level (BR4) exists.	X	X	
Four local interrupt levels exist.	X		
Four LSI-11 interrupt levels exist.		X	
Stack overflow not implemented.	X	X	
A stack overflow trap exists.			X

The first instruction in an interrupt routine will not be executed if another interrupt occurs at a higher priority level than assumed by the first interrupt.	X	X	X
Eight general purpose registers.	X	X	X
PSW address, 177776, not implemented. Must use MTPS and MFPS instructions.	X	X	
Only implicit references (RTI, RTT, traps and interrupts) can load T bit. Console cannot load T bit.	X	X	X
If an interrupt occurs during an instruction that has the T bit set, the T bit trap is acknowledged before the interrupt.	X	X	X
If RTI sets the T bit, T bit trap is acknowledged immediately following RTI.	X	X	X
T bit trap will sequence out of WAIT instruction.	X		X
If RTT sets the T bit, the T bit trap occurs after the instruction following RTT.	X	X	X
RESET instruction consists of 10 usec of INIT followed by a 90 usec pause. Power fail not recognized until the instruction is complete.		X	X
RESET instruction consists of 17 usec of INIT followed by a minimum 3.2 usec pause. Power fail not recognized until the instruction is complete.	X		
Odd address references using the SP do not trap.	X		
Non-existent address references using the SP trap to the restart address.	X		

MOVB instruction does a READ (DATIP) and a WRITE (DATO) bus sequence for last memory cycle.		X	
MOV instruction does a WRITE (DATO) bus sequence for the last memory cycle.		X	X
MOV instruction does a READ (DATI) and a WRITE (DATO) bus sequence for last memory cycle.	X		
From	Through	Response	11/21 11/2 11/23
210	217	Trap to 10 X	NOTE 1 X Reserved Instr.
210	227	Trap to 10 X	X X Reserved Instr.
70000	73777	Trap to 10 X	NOTE 2 NOTE 2 Extended Instr. Set
75000	75037	Trap to 10 X	X NOTE 2 Floating point
75040	75777	Trap to 10 X	NOTE 2 X Reserved Instr.
170000	177777	Trap to 10 X	NOTE 2 NOTE 2 Reserved Instr.
NOTE 1: Maintenance instructions			
NOTE 2: Response depends on processor options			
CLR(B) and SXT do a READ (DATI) and a WRITE (DATO) sequence for the last bus cycle.		X	
CLR(B) and SXT do a READ (DATI) and a WRITE (DATO) bus sequence for the last bus cycle.			X
CLR(B) and SXT do a WRITE (DATO) bus sequence for the last bus cycle.			X
MARK instruction.		X	X
SOB, RTT, SXT, XOR instructions.	X	X	X
SWAB clears V.	X	X	X
ASH, ASHC, DIV, MUL instructions.	X		X

Register addresses (177700-177717) are handled as regular memory addresses. No internal registers are addressable from either the bus or the console.	X		
Register addresses (177000-177717) time-out when used as a program address by the CPU.		X	X
If PC contains a non-existent memory address and a bus error occurs, PC will have been incremented.	X	X	X
If register contains a non-existent memory address in mode 2 and a bus error occurs, register will be incremented.	X	X	X
If register contains an odd value in mode 2 and a bus error occurs, register will be incremented.	X	X	X
HALT in user mode traps to 10.			X
HALT instruction pushes PC and PSW on the stack and loads the PS with 340 and the PC with the restart address.	X		
Only power-up mode 2 implemented.	X		
Resident ODT microcode.		X	X
Instruction execution runs to completion regardless of bus error.	X		
BEVNT line interrupt on level 6.	X		X
Bus error traps to restart address. Instruction runs to completion before trap.	X		
Bus error during IAK vectors through 0 and traps to restart address. The first instruction of service routine is guaranteed to execute.	X		
Only sixteen-bit addressing supported.	X	X	

The no-BSACK 18 usec time-out
implemented. If time-out occurs
BDMGO aborted. X

Bus halt line is a jumper-
configured nonmaskable interrupt. X
Acknowledgement causes PC and
PSW to be stacked and the
processor vectors thru level 7
internal vector 140.

Vector address accepted only on X
BDAL<7-2>. This limits vector
address space to 374.

Certain vector addresses are X
reserved for "local" devices
other than BEVNT.

SBC-11/21 Priorities

Priority of DMA, system traps, external interrupts, internal
interrupts, HALT trap, and WAIT:

DMA	(highest priority)
HALT trap (timeout request)	
Power Fail Trap	
Traps (illegal instruction, T bit, EMT)	
Internal Interrupt Request	
External Interrupt Request	
WAIT instruction	(lowest priority)

APPENDIX C
SOFTWARE DEVELOPMENT

C.0 GENERAL

This section of the manual presents programming hints which may be helpful to application programmers in gaining familiarity with the SBC-11/21. The following three topics are discussed:

- o Running stand-alone programs
- o The software development process
- o An application example

A method of creating, loading and running stand-alone programs is briefly explained. This is followed by a discussion of the software development process, as it applies to a ROM based single board computer. The last section of this appendix presents a practical example of a real-time program written to run on the SBC-11/21. The output chosen for the program is deliberately simple, but the methodology is applicable to programs with a much greater degree of complexity. The program has been thoroughly tested and studying it should prove quite rewarding to the first time users of the SBC-11/21.

C.1 RUNNING STAND-ALONE PROGRAMS

The user can develop stand-alone programs, that is programs not requiring an operating system, on a separate RT-11 based system. The .SAV image can then be loaded into the SBC-11/21 and run. Macro-ODT option is required to load the program and to run it.

To be used with Macro-ODT, the stand-alone program must have the address of Macro-ODT BREAK service routine in location 140 and a PSW value of 300 in location 142. This will enable the program to transfer control to Macro-ODT when the BREAK key is depressed.

In order to be able to load the stand-alone program from the mass storage device into the SBC-11/21, the device's boot block must be modified. This modification extends to locations 0, 2, 4 and 6. Location 0 normally contains 240 and must be changed to 260. When the device is booted, this tells the Macro-ODT that the mass storage device contains a stand-alone program. Macro-ODT will then interpret the contents of locations 2, 4 and 6 as a RADIX-50 encoded six character file name, and search the directory of the volume for that file. The volume must have the RT-11 file structure. When the file is found, the entire file is loaded into contiguous memory starting at location zero. Then Macro-ODT loads register R0 with the number of the unit or drive, and register R1 with the CSR address of the booted device.

This information may be of interest to the stand-alone program if it uses overlays. Then the Stack Pointer (SP) is loaded with the contents of location 42, the Program Counter (PC) is loaded with the contents of location 40, and the program begins execution. Please note, that a stand-alone program developed on an RT-11

based system will already have the correct values for PC and SP in locations 40 and 42.

The detailed procedure for performing these modifications in the boot block and the stand-alone program will now be outlined. This will be done on an RT-11 based system using the SIPP utility.

In the examples below, the program that is to be loaded and run from the stand-alone volume is named FOOBAR.SAV and resides on DK. The characters entered by the operator are underlined. "<CR>" is a carriage return and not the four characters "<", "C", "R" and ">". The "^C" and "^Y" symbols are obtained by holding down the "CTRL" key and typing "C" or "Y" respectively before releasing "CTRL". The "XXXXXX" is a string of octal digits whose value can be anything but is not relevant to the process.

First modify the stand-alone program:

```
. R SIPP <CR> ;Run the SIPP utility
* DK:FOOBAR.SAV <CR> ;Name of file to be
                           patched
Base? <CR> ;Defaults to zero
Offset? 140 <CR>
Base   Offset  Old      New?
000000  000140  xxxxxx  170000 <CR> ;load address of Break
                                           ;routine at Break vector
000000  000142  xxxxxx  300 <CR> ;PSW during Break routine
000000  000144  xxxxxx  ^Y <CR> ;Exit patching
*^C ;Exit SIPP
```

NOTE
If you are using your own BREAK intercepting routine, put its address at location 140 in place of the value 170000.

Now modify the bootblock:

```
.R SIPP <CR>
*DK:/A <CR>
Base? <CR>
Offset? <CR>
```

Base	Offset	Old	New?
000000	000000	xxxxxx	<u>000260</u>
000000	000002	xxxxxx	<u>;RFOO <CR></u>
000000	000004	xxxxxx	<u>;RBAR <CR></u>
000000	000006	xxxxxx	<u>;RSAV <CR></u>
000000	000010	xxxxxx	<u>^Y <CR></u>

*C

C.2 THE SOFTWARE DEVELOPMENT PROCESS

Software development for the SBC-11/21 can be thought of as consisting of four distinct steps as shown in Figure C-1.

1. Design the software and code the source tasks.
2. Enter, edit and assemble the tasks that make up the application.
3. Build the application into a runnable memory image.
4. Load the program into the SBC-11/21 and execute the application program. This step will involve the debugging of the application.

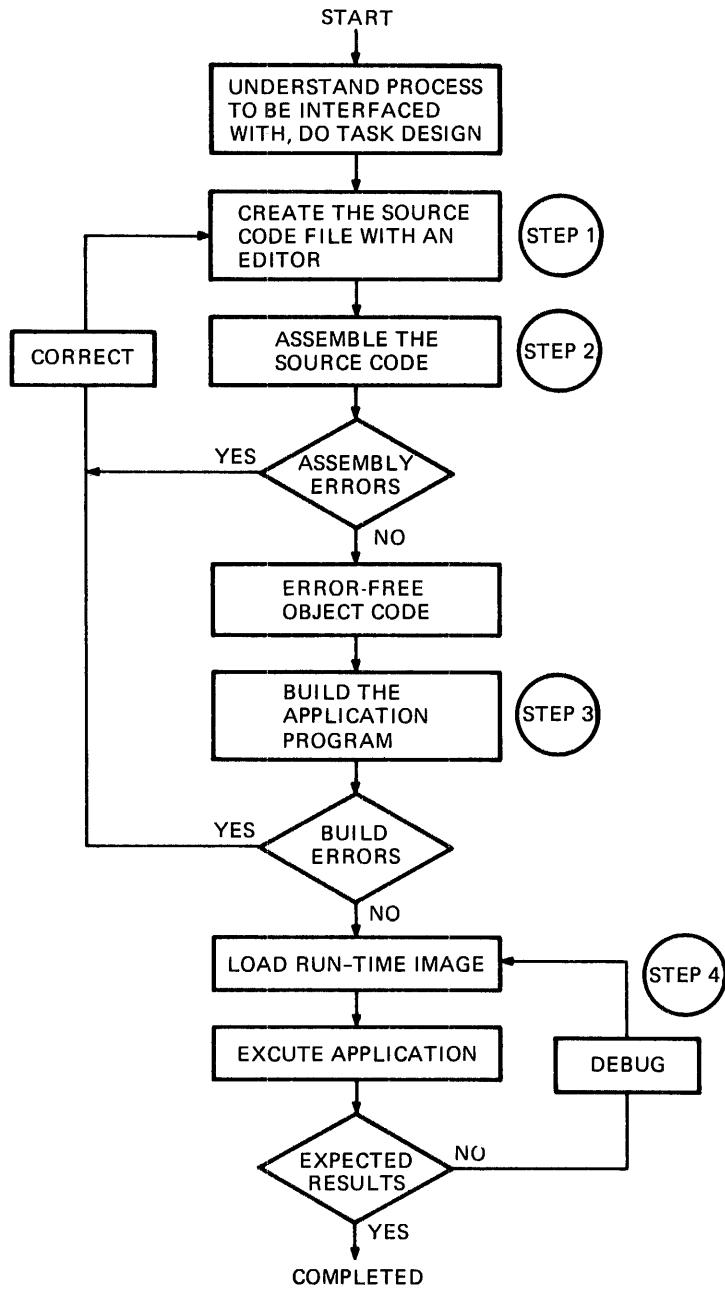
C.2.1 Design of the Software

An important consideration in the design of application software is the run-time memory configuration. Since the SBC-11/21 is a ROM/RAM system, the location of the ROM/RAM boundaries must be defined. All instructions and constants must be grouped separately for location in the ROM portion of memory. Variable information must be grouped together for location in the RAM portion of memory. Throughout the development process, the segregation of ROM and RAM information must be maintained. MACRO-11 Language Reference Manual describes methods of data and code separation.

C.2.2 Editing and Assembly

The second step in the development cycle is the entry, editing, and assembly of the application software. To enter and create the application software involves the use of an editor on the development system. Once the application software is entered and the designer is satisfied with the contents, it can be saved on a mass storage device. The assembler must then be used to convert the source code instructions into executable code. The result of the assembly process is an object file.

The assembler detects common assembly language coding errors and issues appropriate warnings. If errors are detected, corrections should be made by re-editing the source and assembling again.



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Figure C-1 Overview of Software Development

Once the application software has been translated error-free into object form, it is ready for the next step.

C.2.3 Building Process

The third step in the development cycle is the building process to create a runnable memory image. The build process involves the linking of the tasks that make up the application software into a single memory image. The building process takes an object module or modules and assigns absolute memory references to the information contained in the object code. The user assigns these locations by the sectioning of the code that took place during design. The result of the build phase is an executable run-time memory image that can now be loaded and tested.

C.2.4 Running and Debugging the Program

The fourth step in the development cycle is the loading of the runnable memory image into the SBC-11/21. Once loaded, the program can be run and debugged. There are three techniques that can be employed to transfer the software to the target. The methods are:

1. ROM transfer. This method involves the programming of ROMS via a PROM blasting utility, such as PB-11, and placing the PROMS into the target configuration. This simple loading technique most closely resembles the final target configuration since actual ROM storage is used.
2. Media transfer. When this method is used, the application program is loaded, in stand-alone form, into the target from a mass storage system. The directions on creating a stand-alone bootable program are provided in the first part of this appendix. The target configuration uses LSI-11 bus RAM memory in place of the SBC-11/21 on-board ROM during initial start-up and debug. The SBC-11/21 configuration must contain the Macro-ODT ROMs described in Chapter 4. The ODT ROMs provide the means of loading the application program and are used during program debug. Media transfer does not reflect the final configuration, but execution from RAM makes debugging and testing easier. The speed of the program in this mode is approximately half that of the ROM based system.
3. Down-line loading. This method of loading allows transfer of the controller software from the development system to the target system via a serial communication link. The down-line loader must be a development system utility. The target configuration is similar to the media transfer configuration. In addition to the LSI-11 bus, RAM, and the Macro-ODT ROMs one of the serial I/O lines on the SBC-11/21 must be dedicated to the communication with the development system.

When the desired loading technique is implemented, the final phase of development is to debug and run. The loading technique employed

dictates the approach that will be taken during debug.

If the application is being loaded via the ROM transfer method, initial testing and debugging is difficult. When ROM transfer is used there must be embedded code in the application that will report the state of the control system periodically. Another way to check the system is to observe changes that occur in the external devices. If errors are found, correction requires a complete reprogramming of the PROMs. This type of testing and debugging can be quite cumbersome.

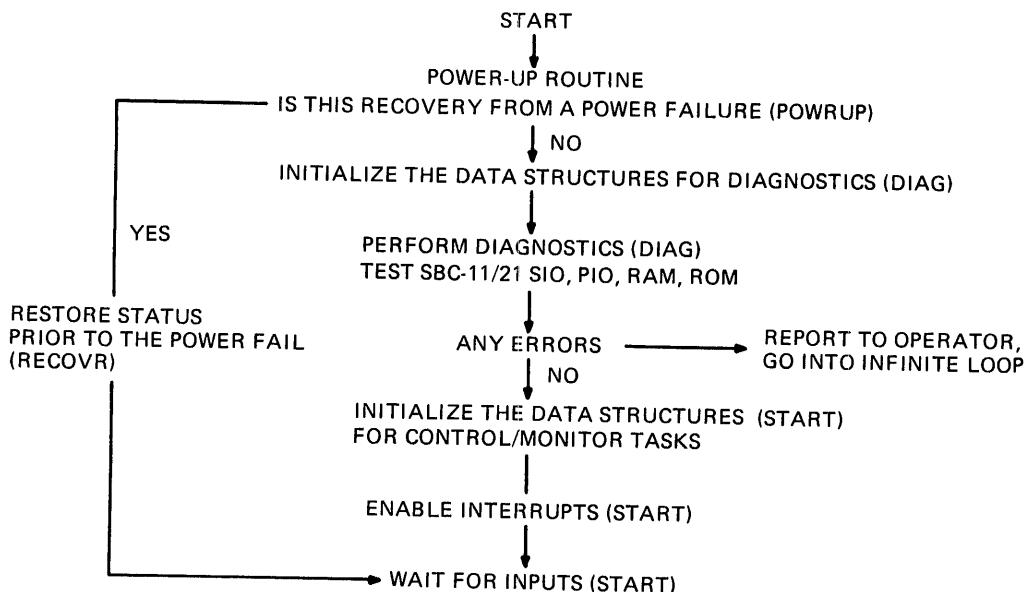
When the application is loaded via media transfer, the initial testing and debugging becomes easier than the ROM method. Once the application program is loaded into LSI-11 bus RAM or into on-board RAM, it can be run using the features of Macro-ODT. The designer can also embed reporting tasks and periodic halts in the application to examine the current state of the system. It should be noted that executing out of LSI-11 bus RAM during debug will be approximately twice as slow as running out of the SBC-11/21 on-board memory. If errors are found minor modifications can be made in the application code since testing is being done in RAM. This eliminates the loop of making new run-time memory images for every change. Once the target system is running successfully, with all of the tasks integrated, the run-time configuration can be set-up. The last step is to commit the application program to ROM and run in the SBC-11/21.

C.3 AN APPLICATION EXAMPLE

This is a sample application (Figure C-2) to show the development of a controller program using MACRO-11. The sample program will simply light the LED used by Port C of the SBC-11/21. The LED will light for ten seconds whenever an input is detected on the console port (SLU1).

The controller program for this simple system is best served by using an interrupt driven environment. An interrupt service routine is used to monitor the console port. When an input is received, a routine is entered that will set the timer for ten seconds and light the LED. A second interrupt service routine is used to count up to ten seconds and then turn off the LED. This routine is serviced by the BEVNT interrupts. In addition to the application tasks, there are tasks to initialize the input/output devices and data structures. Also there are diagnostic programs for the SBC-11/21 and programs used to handle any exceptions. The controller program is developed as individual tasks and then integrated into a complete final program.

The monitor program is described by Figure C-3 and consists of Power Up programs, Diagnostic programs, Task programs and Exception programs. The Power Up programs consist of POWRUP and RECOVR which is initiated by POWRUP. The Diagnostic programs



<u>REC OR BREAK</u>	<u>TIMER</u>	<u>HANDLE EXCEPTIONS</u>
INTERRUPT TASK NO. 1 ENTERED BY AN INPUT RECEIVED VIA CONSOLE SLU INPUTS	INTERRUPT TASK NO. 2 ENTERED EVERY 1/60 OF A SECOND BY BEVTN INTERRUPT	POWER FAIL (POWERF) BUS ERRORS (RESTRRT)
DO THE FOLLOWING:	DO THE FOLLOWING:	
1. SET TIMER FOR TEN SECONDS 2. LIGHT THE LED	1. TICK OFF TIME IF THE TIMER IS SET TO GREATER THAN 0. 2. IF TIME EXPIRES TURN OFF THE LED	

MR-7200

Figure C-2 Application Overview

consist of SLUTST, PIOTST, RAMTST and ROMTST. The Task programs consist of TIMER, REC and BREAK. The Exception programs consist of POWERF, RESTRRT and PRINT. All these programs with the constants and instruction data are located in the ROM memory. The variable data for the application and the stack are located in the RAM memory. Memory Map 1 is assumed (Table 2-8), with the program in ROM socket set B, and data in battery-backed RAM starting at 160000. The Load Map in Figure C-4 shows actual memory locations assigned to code and data.

C.3.1 Power Up Programs

The controller program begins when the system power is applied. The microprocessor accesses location zero which is the jumper-configured start address. This location contains a jump to the power up routine POWRUP (see Figure C-5). This routine determines if this is a normal power up or a recovery from a power failure. This is determined by checking the POWER FAIL flags in the RAM memory. If the flag is set to indicate that the system is recovering from a power fail condition the program jumps to the RECOVR program (see Figure C-6). This program restores the system to the conditions that existed prior to the power fail and resumes program execution. If the flag is not set, an initial power up program is executed and then the program branches to the Diagnostic programs.

```

1 .TITLE FALCON DEVELOPMENT EXAMPLE
2 .ENABL LC
3 .GLOBL POWERF,BREAK,REC,TIMER,RECOVR,SLUTST,PIOTST,RAMTST,ROMTST
4 .GLOBL POWER1,POWER2,ERROR,STACK,RESTRT
5 ;+
6 ; This is an example of a simple controller application for the KXTII-AA.
7 ;-
8
9
10 .SBTTL Program section definitions
11 ;+
12 ; Define the three program sections that will be used
13 ;-
14 000000 .ASECT ; Assign absolute memory locations
15 000000 .PSECT ROM ; For instructions and constant data
16 000000 .PSECT RAM,D ; that will be stored in rom memory
17 ; To define all RAM locations
18
19
20 .SBTTL Equates
21 ;+
22 ; Constant definitions
23 ;-
24 176540 RCSR1 == 176540 ; Auxiliary SLU addresses
25 177560 RCSRC == 177560 ; Console SLU addresses
26 000052 CUNBR == 52 ; Programmable baud rate mask (9600)
27
28 176200 PPA == 176200 ; Parallel port A
29 176206 PCW == 176206 ; Parallel control word
30 000261 LEDON == 261 ; Parallel CSW to light the LED
31 000017 LEDOFF == 17 ; Parallel CSW to turn off the LED
32
33 160010 RAMBGN == 160010 ; Bottom of the user RAM
34 167776 RAMTOP == 167776 ; Top of the user RAM
35
36 106016 CSUM == 106016 ; Checksum value for the system tasks
37
38
39 .SBTTL Macro definitions
40 ;+
41 ; Define macros that will be used by the application
42 ;-
43 44 .MACRO PUSH ARG ; stack push operation
45 45 MOV ARG,-(SP) ; move the argument onto the stack
46 .ENDM
47
48 48 .MACRO POP ARG ; stack pop operation
49 49 MOV (SP)+,ARG ; move the argument from the stack
50 .ENDM
51
52
53 .SBTTL Entry points
54 ;+
55 ; Define entry point, interrupt, and trap service routine addresses
56 ;-
57 000000 .ASECT
58 000000 .#0 JMP POWERUP ; Jump to the power-up routine
59 000000 000167 000000' .#24 JMP RESTRT ; Jump to the restart routine
60 000004 000167 000000G
61 000024 000000G 000340 .WORD POWERF,340 ; Power fail service routine
62
63 000060 000000G 000300 .#60 .WORD REC,300 ; Console receiver service routine
64
65 000100 000000G 000300 .#100 .WORD TIMER,300 ; Timer service routine
66
67 000140 000000G 000300 .#140 .WORD BREAK,300 ; Console break service routine
68
69
70
71
72
73
74 000000 .SBTTL Power up routine
75 000000 .PSECT ROM
76
77 000000 POWRUP:;
78 ;+
79 ; Come here first under all circumstances and decide if this is a normal
80 ; power up or recovery from a power fail
81 ;-
82 000000 026727 000000G 123456 CMP POWER1,#123456 ; Is this recovery from power failure
83 000006 001006 000000G 135724 BNE DIAG ; or is it a normal power-up ?
84 000010 026727 000000G 135724 CMP POWER2,#135724 ; Increase the chance to distinguish
85 000016 001002 BNE DIAG ; by checking against a 32 bit pattern
86
87 000020 000167 000000G JMP RECOVR ; This a recovery from power fail
88

```

Figure C-3 Monitor Program

```

89
90
91
92 000024           .SBTTL Diagnostics
93
94
95
96 000024 012706 000000G      MOV    #STACK,SP      ; Initialize the stack
97 000030 005067 000000G      CLR    ERROR          ; Initialize the error flag
98 000034 052737 000052 177564  BIS    #CUNBR,#RCSRC+4 ; Initialize the console SLU
99
100 000042 004767 000074       CALL   PRINT          ; Tell the operator that the power-
101 000046 000174*             .WORD  DIAGN          ; up diagnostics are running
102 000050 004767 000000G      CALL   RAMIST         ; Perform the KXT11 RAM memory test
103 000054 004767 000000G      CALL   ROMTST         ; Perform the KXT11 ROM memory test
104 000060 004767 000000G      CALL   SLUTST         ; Perform the KXT11 serial line test
105 000064 004767 000000G      CALL   PIOTST         ; Perform the KXT11 parallel I/O test
106
107 000070 005767 000000G      TST    ERROR          ; Is the error flag zero
108 000074 001404             BEQ    18              ; Yes, no errors proceed to init
109 000076 004767 000040       CALL   PRINT          ; No, diagnostic failure
110 000102 000332*             .WORD  EMESS
111 000104 000777             BR    .
112 000106 004767 000030       18:   CALL   PRINT          ; Wait until there is operator action
113 000112 000253*             .WORD  HMESS          ; Indicate that things are OK
114
115
116           .SBTTL Initialization completion, allow application tasks to run
117
118 000114           START:::
119
120
121
122 000114 105737 177562      TSFB  #RCSKC+2      ; Flush the receiver buffer
123 000120 052737 000100 177560  BIS   #100,#RCSKC     ; Enable interrupt on the receiver
124 000126 106427 000000      MTPS  #0            ; Allow interrupts to happen
125 000132 004767 000004       CALL   PRINT          ; Tell the operator that the
126 000136 001015*             .WORD  GO            ; application is up and running
127
128 000140 000777             BR    .
129
130
131 000142           PRINT:::
132
133
134
135
136 000142 017604 000000      .ENABL LSB
137 000146 005216             MOV    #($P),R4      ; Point to the beginning of the message
138 000150 005216             INC    ($P)          ; Increment beyond message address in the
139 000152 112405             INC    ($P)          ; calling routine
140 000154 001406             18:   MOVB  (R4)+,R5      ; Move the next character to be printed
141 000156 105737 177564       BEQ    38              ; Is this the end of message marker ?
142 000162 100375             28:   TSTB  #RCSKC+4      ; No, output another character
143 000164 110537 177566       BPL    28              ; Transmitter ready
144 000170 000770             MOVB  R5,#RCSRC+6    ; Output the character
145 000172 000207             BR    18              ; Get another character
146
147
148
149           .SBTTL Messages sent to the operator
150
151
152 000174 015    012    040  DIAGM::: .ASCIZ <15><12>/ The power-up diagnostics are running ... /<15><12>
153 000253 015    012    040  HMESS::: .ASCIZ <15><12>/ System checked out, there were no faults /<15><12>
154 000332 015    012    040  EMESS::: .ASCIZ <15><12>/ System did not pass initial power up test /<15><12>
155 000412 015    012    007  FMESS::: .ASCIZ <15><12><7><7><7><7>/ RUN-TIME FAILURE /<15><12>
156 000445 015    012    040  SLUET::: .ASCIZ <15><12>/ Serial line unit diagnostic failure /<15><12>
157 000517 015    012    040  SLGOODD::: .ASCIZ <15><12>/ Serial line unit passed diagnostics /<15><12>
158 000571 015    012    040  MESRA1::: .ASCIZ <15><12>/ RAM failure /<15><12>
159 000613 015    012    040  RAGOODD::: .ASCIZ <15><12>/ RAM passed diagnostics /<15><12>
160 000650 015    012    040  MESRU1::: .ASCIZ <15><12>/ ROM checksum error /<15><12>
161 000701 015    012    040  ROGOODD::: .ASCIZ <15><12>/ ROM passed diagnostics /<15><12>
162 000736 015    012    040  PGOODD::: .ASCIZ <15><12>/ Parallel input/output passed diagnostics ?<15><12>
163 001015 015    012    040  GOI::: .ASCII <15><12>/ The application is running ... / <15><12>
164 001061 040    040    040  .EVEN
165
166
167 000001           .END

```

Figure C-3 Monitor Program (Cont)

```

RT-11 LINK V06.01C Load Map      Tue 06-Oct-81 09:02:01
C .SAV Title: FALCUN Ident: /R:000400

Section Addr  Size .Global Value Global Value Global Value
.ABS. 000000 000400 (RW,I,LBL,ABS,DVR)
LEDOFF 000017 CUNBR 000052 LEDON 000261
CSUM 106016 RAMBGN 160010 RAMTOP 167776
PPA 176200 PCW 176206 KCSR1 176540
RCSR1 177560
ROM 000400 157400 (RW,I,LCL,REL,CUN)
POWERUP 000400 DIAG 000424 START 000514
PRINT 000542 DIAGM 000574 HMESS 000653
EMESS 000732 FMESS 001012 SLUE 001045
SLGOOD 001117 MESRA1 001171 RAGOOD 001213
MESR01 001250 ROGOOD 001301 PGOOD 001336
GO 001415 RECOVR 001556 REC 001634
TIMER 001656 BREAK 001702 LAST 001716
POWERF 001720 RESTRT 001764 SLUTST 001774
RAMTST 002132 ROMTST 002212 PIUTS1 002262
RAM 160000 000332 (RW,D,LCL,REL,CUN)
POWER1 160010 POWER2 160012 SAVER6 160014
ERROR 160016 TIME 160020 STACK 160332

```

Transfer address = 000001, High limit = 160330 = 28780. words

Figure C-4 Load Map

```

1 .ENABL LC
2 000000 .PSECT RAM,D
3
4 ; The variable data is assigned to the user RAM space on the KXT11-AA
5 ;
6
7 000000 .BLKW 4 ; Non existant KXT11-AA memory
8 000010 000000 POWER1::WORD 0 ; Power failure 32-bit comparision
9 000012 000000 POWER2::WORD 0 ; flag
10 000014 000000 SAVER6::WORD 0 ; Stack pointer area for power failure
11 000016 000000 ERROR1::WORD 0 ; Diagnostic error flag
12
13 000020 000000 TIME:: WORD 0 ; Time flag
14 000022 .BLKW 100. ; This is the stack
15 000332
16
17 000001 .END

```

Figure C-5 Power Up Task

```

1 .ENABL LC
2 .GLOBL SAVER6,TIME,RCSR1,CONBR,LEDON,PCW
3 .MCALL POP
4 000000 .PSECT ROM
5
6 000000 RECOVR::
7 ;
8 ;This routine is entered if a recovery from a power failure is taking place
9 ;- Entered from PowRUP
10 000000 016706 000000G MOV SAVER6,SP ; Restore the stack pointer
11 000004 POP TIME ; Restore any variable information
12 000010 POP R5 ; Restore the general purpose
13 000012 POP R4 ; registers
14 000014 POP R3
15 000016 POP R2
16 000020 POP R1
17 000022 POP R0
18 000024 052737 000100 000000G BIS #100,0#RCSR1 ; Re-initialize console SLU, enable
19 000032 052737 000000G 000004G BIS #CONBR,0#RCSR1+4 ; interrupts and set-up baud rate
20 000040 005767 000000G TST TIME ; Is the LED timer set
21 000044 001403 BEQ 3# ; No, continue
22 000046 012737 000000G 000000G MOV #LEDON,0#PCW ; Yes turn the LED on for the rest
23 ; of the time prior to power-fail
24 000054 000002 3# RTI ; Return from point of power-fail
25 ; interrupt
26
27 000001 .END

```

Figure C-6 Power Fail Recovery

C.3.2 Diagnostic Programs

The diagnostic programs are entered via a diagnostic initialization routine. The SLUTST (see Figure C-7) program is the first diagnostic and it tests the auxiliary Serial Line Unit on the SBC-11/21. The diagnostic enables the SLU maintenance mode and transmits various test patterns. After a certain amount of time the program checks to see that the test patterns were correctly received. It should be noted that the SLU maintenance mode allows data to be transmitted to the EIA port as well as through the internal loopback. Therefore if a device is connected to the port it will respond to this data.

The second diagnostic is RAMTST (see Figure C-8) which tests the RAM memory. This test is performed by writing known data into a RAM location and then checking that the correct information is in that location.

```

1          .ENABL  LC,LSB
2          .GLOBL  RCSR1,ERROR,PRINT,SLUE,SLGOOD
3 000000  .PSECT  ROM
4
5 000000
6          SLUTST:::
7          ;+           ; This routine checks the auxiliary SLU port on the KXT11-AA
8          ;-
9
10 000000 012701 000000G      MOV    #RCSR1,R1      ; Point to the address
11 000004 105761 000002       TSTB. 2(R1)      ; Flush the contents of RBUF
12 000010 012761 000006 000004   MOV    #6,4(R1)    ; Set the SLU for maintenance and
13                                     ; programmable baud rates
14 000016 012702 000010       MOV    #8,,R2      ; Initialize the baud rate counter
15 000022 012703 000132"     18:  MOV    #PATERN,R3  ; Point to the test patterns
16 000026 005005               28:  CLR    R5        ; Initialize time out counter
17 000030 105761 000004       38:  TSTB. 4(R1)    ; Loop the pattern around
18 000034 100402               BMI    48        ; Branch if ready to send
19 000036 077504               SODB   R5,38      ; If not ready, bump time out counter
20 000040 000422               BR     100$      ; IF timed out then -ERROR-
21 000042 111361 000006       48:  MOVB   (R3),6(R1) ; Send the information out
22 000046 005005               CLR    R5        ; Initialize the time out counter
23 000050 105711               58:  TSTB. (R1)    ; Is the receiver ready ?
24 000052 100402               BMI    68        ; Yes it is and branch
25 000054 077503               SODB   R5,58      ; If not ready, bump time out counter
26 000056 000413               BR     100$      ; If timed out then -ERROR-
27 000060 126113 000002       68:  CMPB   2(R1),(R3) ; Was the information sent OK ?
28 000064 001010               BNE    100$      ; No it was not -ERROR-
29 000066 105723               TSTB. (R3)+    ; All of the test patterns done ?
30 000070 001356               BNE    2$        ; No, go do another pattern
31 000072 005302               DEC    R2        ; All of the baud rates tested ?
32 000074 001412               BEQ    200$      ; Yes, get out of this routine
33 000076 062761 000010 000004   ADD    $10,4(R1) ; No, set-up the next baud rate
34 000104 000746               BR     16        ; Do another loop, reinit patterns
35
36 000106 005267 000000G      100$: INC    ERROR      ; Bump the error counter
37 000112 004761 000000G      CALL   PRINT      ; Print the error message
38 000116 000000G              .WORD  SLUE
39 000120 000403               BR     150$      ; Go back
40 000122 004767 000000G      200$: CALL   PRINT      ; The test was successful
41 000126 000000G              .WORD  SLGOOD
42 000130 000207               150$: RETURN      ; Bye
43
44 000132    177    040    000  PATERN: .BYTE  177,40,0  ; Test patterns for SLU
45          .EVEN
46
47          .DSABL  LSB
48          000001  .END

```

Figure C-7 SLU Diagnostic Task

```

1 .ENABL LC,LSB
2 .GLOBL RAMBGN,PRINT,RAMTOP,MESRA1,RAGOOD,ERROR
3 .PSECT ROM
4
5 000000
6
7 .RAMTST:::
8 ; This routine checks the user RAM on the KXTII-AA
9
10 000000 011602
11 000002 016703 000000G
12 000006 012700 000000G
13
14 000012 010010
15 000014 020010
16 000016 001405
17 000020 004767 000000G
18 000024 000000G
19 000026 005203
20 000030 000407
21 000032 005720
22 000034 020027 000002G
23 000040 103764
24 000042 004767 000000G
25 000046 000000G
26
27 000050 010216
28 000052 010367 000000G
29 000056 000207
30
31
32 000001

    MOV    (SP),R2          ; Save the return address
    MOV    ERROR,R3          ; Save the contents of the ERROR flag
    MOV    #RAMBGN,R0          ; Point to the start of the user RAM
18:   MOV    R0,(R0)          ; Write the address
    CMP    R0,(R0)
    BEQ    28
    CALL   PRINT
    .WORD  MESRA1
    INC    R3
    BR    38
28:   TST    (R0)+          ; Was the value read correctly
    CMP    R0,#RAMTOP+2
    BLO    18
    CALL   PRINT
    .WORD  RAGOOD
38:   MOV    R2,(SP)          ; Go onto the next location
    MOV    R3,ERROR          ; Until there is no more to test
    RETURN
30
31
32 .DSABL LSB
.END

```

Figure C-8 RAM Diagnostic Task

The third diagnostic is ROMTST (see Figure C-9) which checks the ROM memory. This test calculates a checksum on the actual control and monitoring tasks. If there is a checksum mismatch then there is a potential failure at some ROM location.

The last diagnostic is PIOTST (see Figure C-10) which checks the Parallel I/O port on the SBC-11/21. This test verifies that the Parallel I/O registers can be addressed. The send/receive capability cannot be checked unless there is a loopback connector installed on the J3 connector. When data are written into these registers and a device is connected to the port, the device can respond to the data.

```

1 .ENABL LC,LSB
2 .GLOBL REC,LAST,CSUM,PRINT,MESR01,ROGOOD,ERROR
3 .PSECT ROM
4
5 000000
6
7 .ROMTST:::
8 ; This routine will check the ROM on the KXTII-AA, this test checks
9 ; the portion of the ROM that contains the actual control/monitor tasks
10
11 000000 012700 000000G
12 000004 005001
13 000006 062001
14 000010 022700 000002G
15 000014 001374
16 000016 022701 000000G
17 000022 001406
18 000024 004767 000000G
19 000030 000000G
20 000032 005267 000000G
21 000036 000403
22 000040 004767 000000G
23 000044 000000G
24 000046 000207
25
26
27 000001

    MOV    #REC,R0          ; Point to the control task address
    CLR    R1
    ADD    (R0)+,R1          ; Initialize checksum value
    CMP    #LAST+2,R0
    BNE    18
    CMP    #CSUM,R1          ; Update value
    BEQ    28
    CALL   PRINT
    .WORD  MESR01
    INC    ERROR
    BR    38
28:   CALL   PRINT
    .WORD  RAGOOD
38:   RETURN
30
31
32 .DSABL LSB
.END

```

Figure C-9 ROM Diagnostic Task

```

1          .ENABL  LC,LSB
2          .GLOBL  PPA,PRINT,PGOOD
3          .PSECT  RGM
4
5 000000
6          PIOTST:::
7          ;+
8          ; This routine checks the parallel ports on the KXT11-AA this only
9          ; test the ability to address the port
;-
10
11 000000 012701 000003      MOV    #3,R1           ; Initialize loop counter
12 000004 005000             CLR    R0'              ; Initialize counting index
13 000006 005760 000000G     18:   TST    PEA(R0)        ; Attempt to address PIO port if the
14                               ; attempt fails a trap through the
15                               ; restart will occur and report a run
16                               ; time error
17 000012 005720             TST    (R0)+           ; Increment the index, this will not
18                               ; time out since there is memory at
19                               ; locations 2-4
20 000014 077104             S0B    R1,18
21 000016 004767 000000G     CALL   PRINT           ; Do the port
22 000022 000000G            .WORD  PGODD          ; Indicate success
23
24 000024 000207             RETURN
25
26
27 000001             .DSABL  LSB
          .END

```

Figure C-10 Parallel I/O Diagnostic Task

When any of the above diagnostics detect a failure, the program will set an Error Flag. The diagnostic program will check the status of all Error Flags before it enters the task programs. If an error is found, the operator is informed that a diagnostic test failed and the program enters a loop to wait for the operator to intervene. Each diagnostic will print a message to the operator indicating success or failure. If there are no failures, then a success message is printed and the program enters the task programs.

C.3.3 Control Task Programs

The Control Tasks programs (see Figure C-11) complete the initialization of the system by clearing the receive buffer, enabling the interrupts, and lowering the microprocessor priority to accept interrupts. The operator is then informed that the system is running and waiting for interrupts. The TIMER receives a BEVNT input sixty times per second. The REC program is entered when an interrupt is received from the console. The program will then turn on the LED and load the ten second counter. The BREAK program is entered whenever a break is detected and performs the same task as REC. A TIMER program will decrement the ten second counter, if it is enabled, every time BEVNT is received. When the ten second counter is decremented to zero, the program will turn off the LED. If the LED is turned on and another break or interrupt occurs, the ten second counter is reset for ten seconds. The program also anticipates any exception conditions.

C.3.4 Exception Programs

The system is now running and the exception programs are entered only when a power fail occurs or a bus timeout occurs. The PRINT program is entered only to establish communication with the operator.

```

1          .SBITL CONTROL AND MONITORING TASKS
2
3          .ENABLE LC
4          .GLOBAL TIME,LEDON,PCW,RCSRC,LEDOFF
5 000000  .PSECT ROM
6
7 000000      REC:::
8
9          ; This interrupt routine accepts an input from the console. When the input is
10         ; received a ten second counter is initialized and the LED is turned on.
11
12
13 000000  012767  001130  000000G      MOV    #<10.* 60.>,TIME      ; Set timer for ten seconds
14 000006  012737  000000G  000000G      MOV    #LEDON,#$PCW        ; Turn the LED on
15 000014  105737  000002G      TSTB   #$RCSRC+2        ; Flush the receive buffer
16 000020  000002      RTI               ; Go back
17
18 000022      TIMER:::
19
20          ; This interrupt routine when entered every clock tick will decrement the ten
21          ; second counter and turn off the LED if the time is expired, otherwise it
22          ; returns immediately.
23
24
25 000022  005767  000000G      TST    TIME                ; If the time is set update the
26 000026  001406      BEQ    GOBACK             ; counter otherwise go back
27 000030  005367  000000G      DEC    TIME                ; Yes, bump the counter and if it is
28 000034  001003      BNE    GOBACK             ; The last tick then shut the LED off
29 000036  012737  000000G  000000G      MOV    #LEDOFF,#$PCW       ; Otherwise go back
30 000044  000002      GOBACK: RTI
31
32 000046      BREAK:::
33
34          ; This interrupt service routine will be entered if a break detected , this
35          ; is treated as a regular input on the KXT11-AA console port.
36
37
38 000046  012767  001130  000000G      MOV    #<10. * 60.>,TIME      ; Set the timer for ten seconds
39 000054  012737  000000G  000000G      MOV    #LEDON,#$PCW        ; Turn the LED on
40 000062  000002      LAST::: RTI               ; Go back
41
42 000001      .END

```

Figure C-11 Control Task

A timeout will occur when an address does not respond or if a device does not reply to an interrupt acknowledge. When a timeout occurs the SBC-11/21 will trap to location 4 which is the restart address. The start address is defined as location 0 and restart address is defined as location 4 by the factory configuration. The RSTART program is entered via location 4 and informs the operator that a run-time error has occurred and waits for the operator to intervene.

An imminent power failure is detected when the system power is going down. This enables the powerfail interrupt and causes a trap to location 24. The POWERF program (see Figure C-12) is entered via location 24 and the POWER FAIL flags are set in the RAM memory. The RAM memory incorporates the Battery Backup feature of the SBC-11/21 module. Program information contained in the general purpose registers, the stack pointer and other pertinent data are stored in the non-volatile RAM memory. The program then puts the bus into a known state with RESET instruction and waits for the power loss to occur. When power is eventually restored, POWRUP routine is executed and data are recovered as the system restarts.

```

1          .ENABLE LC
2          .GLOBAL POWER1,POWER2,TIME,SAVER6,PRINT,FMESS
3          .NCALL PUSH
4 000000  .PSECT ROM
5
6 000000          POWERF::
7          ;+
8          ; This routine is entered when a power fail is detected and saves the
9          ; pertinent information in non-volatile RAM
10         ;-
11 000000 012767 123456 000000G      MOV    #123456,POWER1      ; Initialize the 32-bit power recovery
12 000006 012767 135724 000000G      MOV    #135724,POWER2      ; test pattern in first two words of RAM
13 000014          PUSH   R0          ; Save the general purpose registers
14 000016          PUSH   R1          ; and any pertinent data in a non-
15 000020          PUSH   R2          ; volatile RAM area
16 000022          PUSH   R3
17 000024          PUSH   R4
18 000026          PUSH   R5
19 000030          PUSH   TIME
20 000034 010667 000000G      MOV    SP,SAVER6      ; Save the stack pointer in the non-
21                                     ; volatile ram area
22 000040 000005          RESET
23 000042 000777          BR    .
24                                     ; and wait for loss of power
25 000044          RESTRT::
26          ;+
27          ; when a bus error occurs such as an interrupt time-out or bus time-out
28          ; a trap thru the restart takes place and comes here
29          ;-
30
31 000044 004767 000000G      CALL   PRINT
32 000050 000000G      WORD  FMESS      ; Indicate that a run-time error has
33 000052 000777          BR    .
34                                     ; occurred and wait for operator
35                                     ; intervention
36 000001          .END

```

Figure C-12 Power Fail Task

APPENDIX D
MACRO-ODT ROM

This appendix provides the user with the program listing of the Macro-ODT ROM firmware.

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27-	1	POWERUP-Exit
27-	20	POWERUP-Subroutine to initialize vectors
28-	1	AUTOBAUD-Synchronize with Console
30-	1	macroODT-Introduction
32-	1	macroODT-Save status and print prompt
33-	1	macroODT-Get ODT command
35-	1	macroODT- Go and Proceed
36-	1	macroODT-Register and PS command
37-	1	macroODT-Examine and Deposit
39-	1	macroODT-Get and echo character
40-	1	macroODT-Type ASCII string
41-	1	macroODT-Get octal digits
42-	1	macroODT-OCTSTR--type binary in R0 as ASCII
43-	1	macroODT-Output messages
44-	1	DIAGNOSTICS-for SLU2 and PPI
45-	1	HARDWARE ENTRY POINT
46-	1	DIAGNOSTICS-Continued
47-	1	BOOTS-Description
48-	9	BOOTS-RX Controller Definitions
48-	56	BOOTS-TU58 Definitions and Protocol Equates
48-	114	BOOTS-R111 Definitions and Equates
49-	1	BOOTS-Program entry point
49-	42	-----> HALT AT PC=172234 INDICATES "Illegal device name"
49-	51	-----> HALT AT PC=172264 INDICATES "Illegal unit number"
49-	58	-----> HALT AT PC=172304 INDICATES "No low memory, can't boot"
49-	92	-----> HALT AT PC=172376 INDICATES "Unexpected timeout during boot"
50-	1	BOOTS-RX01/RX02 Bootstrap
51-	1	BOOTS-Distinguishing type of boot block
51-	23	-----> HALT AT PC=172454 INDICATES "No boot block on volume"
52-	1	BOOTS-TU58 Bootstrap
52-	29	-----> HALT AT PC=172542 INDICATES "TU58 initialization error"
52-	37	-----> HALT AT PC=172562 INDICATES "TU58 block 0 read error"
53-	1	BOOTS-Stand-alone volume bootstrap
53-	24	-----> HALT AT PC=172614 INDICATES "Directory read error"

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TABLE OF CONTENTS

53- 36 -----> HALT AT PC=172652 INDICATES "File not found"
54- 1 BOOTS-Load Stand-Alone Program File
54- 8 -----> HALT AT PC=172732 INDICATES "Stand-alone file read error"
54- 12 -----> HALT AT PC=172750 INDICATES "Illegal transfer address"
55- 1 173000G ENTRY POINT
56- 1 BOOTS-Continued
57- 1 BOOTS-RX01/RX02 Read routines
57- 36 -----> HALT AT PC=173070 INDICATES "Floppy drive not ready"
57- 114 -----> HALT AT PC=173262 INDICATES "Floppy read error"
60- 1 BOOTS-TU58 Read routines
61- 27 -----> HALT AT PC=173556 INDICATES "TU58 END packet missing"
61- 37 -----> HALT AT PC=173610 INDICATES "TU58 checksum error"
63- 1 END STATEMENT

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```
1 .TITLE KXT11-A2 1K FIRMWARE
2 .IDENT /V1.00/
3 .ENABL LC
4
5 ; Place identification number in last ROM location:
6 000000
7 173776
8 173776 000
9 173777 001
          .ASECT
          .=173776
          .BYTE 0
          .BYTE 1.
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 3
COPYRIGHT NOTICE

```
1          .SBTTL COPYRIGHT NOTICE
2
3          ; COPYRIGHT (C) 1980, 1981 BY
4          ; DIGITAL EQUIPMENT CORPORATION, MAYNARD, MASS.
5
6          ; THIS SOFTWARE IS FURNISHED UNDER A LICENSE AND MAY BE USED AND COPIED
7          ; ONLY IN ACCORDANCE WITH THE TERMS OF SUCH LICENSE AND WITH THE
8          ; INCLUSION OF THE ABOVE COPYRIGHT NOTICE. THIS SOFTWARE, OR ANY OTHER
9          ; COPIES THEREOF MAY NOT BE PROVIDED OR OTHERWISE MADE AVAILABLE TO ANY
10         ; OTHER PERSON. NO TITLE TO AND OWNERSHIP OF THE SOFTWARE IS HEREBY
11         ; TRANSFERRED.
12
13         ; THE INFORMATION IN THIS DOCUMENT IS SUBJECT TO CHANGE WITHOUT NOTICE
14         ; AND SHOULD NOT BE CONSTRUED AS A COMMITMENT BY DIGITAL EQUIPMENT
15         ; CORPORATION.
16
17         ; DIGITAL ASSUMES NO RESPONSIBILITY FOR THE USE OR RELIABILITY OF ITS
18         ; SOFTWARE ON EQUIPMENT WHICH IS NOT SUPPLIED BY DIGITAL.
19
20         ; VERSION V1.00
21
22         ; EDWARD P. LUWISH 29-SEP-81
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 4
KXT11-A2 EDIT HISTORY

1 .SBTTL KXT11-A2 EDIT HISTORY
2
3 ;EDIT HISTORY:
4 ;

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 5
EQUATES

```
1 .SBTTL Equates
2
3 ; BIT EQUATES
4
5     000001     BIT0    =    1
6     000002     BIT1    =    2
7     000004     BIT2    =    4
8     000010     BIT3    =   10
9     000020     BIT4    =   20
10    000040     BIT5    =   40
11    000100     BIT6    =  100
12    000200     BIT7    =  200
13    000400     BIT8    =  400
14    001000     BIT9    = 1000
15    002000     BIT10   = 2000
16    004000     BIT11   = 4000
17    010000     BIT12   = 10000
18    020000     BIT13   = 20000
19    040000     BIT14   = 40000
20    100000     BIT15   = 100000
21
22 ; ASCII CHARACTER EQUATES
23
24    000012     LF      =    12          ;Line feed
25    000015     CR      =    15          ;Carriage return
26    000040     SPACE   =    40          ;Space
27
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 6
GENERAL DLART EQUATES

1 .SBTTL General DLART Equates
2
3 ; DLART EQUATES
4
5 177560 RCSR\$1 = 177560 ;SLU1 Receive CSR
6 177562 RBUF\$1 = 177562 ;SLU1 Receive buffer
7 177564 XCSR\$1 = 177564 ;SLU1 Xmit CSR
8 177566 XBUF\$1 = 177566 ;SLU1 Xmit buffer
9 176540 RCSR\$2 = 176540 ;SLU2 Receive CSR
10 176542 RBUF\$2 = 176542 ;SLU2 Receive buffer
11 176544 XCSR\$2 = 176544 ;SLU2 Xmit CSR
12 176546 XBUF\$2 = 176546 ;SLU2 Xmit buffer
13
14 ; DLART RECEIVE CSR BITS
15
16 004000 RC.ACT = BIT11 ;Receiver active (R/O). Set
17 ; while character is being
18 ; received.
19 000200 RC.DUN = BIT7 ;Receiver done (R/O). A
20 ; character has been completely
21 ; received and now resides
22 ; in RBUF.
23 000100 RC.IEN = BIT6 ;Receiver int. enable (R/W).
24 ; when set, enables "Keyboard"
25 ; interrupts, using vector
26 ; at 60.
27
28 ; DLART RECEIVE BUFFER BITS (R/O)
29
30 100000 RB.ERR = BIT15 ;Error. Framing error or
31 ; overrun has occurred.
32 040000 RB.OVR = BIT14 ;Overrun error. Character was
33 ; received before previous one
34 ; was read.
35 020000 RB.FRM = BIT13 ;Framing error. No valid stop
36 ; bit was detected.
37 004000 RB.BRK = BIT11 ;Break detect. Set when break
38 ; is detected, reset when next
39 ; start bit arrives.

KX111-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 7
GENERAL DLART EQUATES

```
1 ; DLART TRANSMIT CSR BITS
2
3     000200      XC.RDY =     BIT7          ;Transmitter ready (R/O).
4                                     ; When set, indicates that the
5                                     ; last character was completely
6                                     ; sent and XBUF is ready for
7                                     ; a new one.
8     000100      XC.IEN =     BIT6          ;Transmit int. enable (R/W).
9                                     ; When set, enables "console
10                                    ; printer" interrupts, using
11                                     ; vector at 64.
12
13                                     ; Programmable baud rate bits
14
15     000010      PBR0 =     BIT3
16     000020      PBR1 =     BIT4
17     000040      PBR2 =     BIT5
18
19                                     ; PBR0=2 set baud rates as follows:
20
21     000000      BD.003 =     0          ;Baud rate = 300
22     000010      BD.006 =     PBR0        ;Baud rate = 600
23     000020      BD.012 =     PBR1        ;Baud rate = 1200
24     000030      BD.024 =     PBR1!PBR0  ;Baud rate = 2400
25     000040      BD.048 =     PBR2        ;Baud rate = 4800
26     000050      BD.096 =     PBR2!PBR0  ;Baud rate = 9600
27     000060      BD.192 =     PBR2!PBR1  ;Baud rate = 19200
28     000070      BD.384 =     PBR2!PBR1!PBR0 ;Baud rate = 38400
29
30     000004      XC.MNT =     BIT2          ;Maintenance (R/W). When set,
31                                     ; creates an internal "loop-
32                                     ; back" between the transmitter
33                                     ; and receiver. Also dis-
34                                     ; connects the external
35                                     ; serial input.
36     000002      XC.PBE =     BIT1          ;Prog. baud rate enable. When
37                                     ; set, the baud rate is deter-
38                                     ; mined by bits 3-5 as
39                                     ; tabulated above. WHEN
40                                     ; CLEAR, BAUD RATE IS DETER-
41                                     ; MINED BY VOLTAGES APPLIED
42                                     ; TO DLART IC PINS.
43     000001      XC.BRK =     BIT0          ;Transmit break (R/W). When
44                                     ; set, serial output is a
45                                     ; continuous BREAK.
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 8
 GENERAL PPI EQUATES

```

1          .S8TTL General PPI Equates
2
3          ; PROGRAMMABLE PERIPHERAL INTERFACE (PPI) EQUATES
4
5          176206      PP.CWR =      176206      ;PPI Control Word Register
6          176200      PP.A =       176200      ;PPI Port A Register
7          176202      PP.B =       176202      ;PPI Port B Register
8          176204      PP.C =       176204      ;PPI Port C Register
9
10         ; PPI MODE-SETTING BITS
11
12         ; KXT11-AA board configuration does not permit all combinations of
13         ; the mode bits. Consult the manual before using the PPI.
14
15         000200      PP.MOD =      BIT7      ;This MUST be or'd with other
16                               ; bits to set mode.
17         000100      PP.MD2 =      BIT6      ;Sets mode 2
18         000040      PP.MDA =      BIT5      ;If bit 6 is low, determines
19                               ; mode of port A
20                               ; (hi=mode 1, lo=mode 0)
21         000020      PP.DRA =      BIT4      ;Direction of port A.
22                               ; Hi=IN, lo=OUT.
23         000010      PP.CHI =      BIT3      ;Direction of port C upper half
24                               ; Hi=IN, lo=OUT.
25         000004      PP.MDB =      BIT2      ;Mode of port B.
26                               ; Hi=mode 1, lo=mode 0.
27         000002      PP.DRB =      BIT1      ;Direction of port B.
28                               ; Hi=IN, lo=OUT.
29         000001      PP.CLO =      BIT0      ;Direction of port C lower half
30                               ; Hi=IN, lo=OUT.
31
32         ; PPI BIT SET/RESET CONTROL BITS
33
34         ;      When bit 7 is low, writing to the PPI CSk will set or reset
35         ;      individual bits in Port C, depending on the mode and direction
36         ;      of the port's bits, and on the combination of bits you write.
37
38         000016      PP.BI7 =      BIT3!BIT2!BIT1      ;Use ONE
39         000014      PP.BI6 =      BIT3!BIT2      ;of these
40         000012      PP.BI5 =      BIT3!BIT1      ;to select
41         000010      PP.BI4 =      BIT3      ;which bit
42         000006      PP.BI3 =      BIT2!BIT1      ;is desired
43         000004      PP.BI2 =      BIT2      ;to be
44         000002      PP.BI1 =      BIT1      ;SET or
45         000000      PP.BI0 =      0      ;CLEARed
46
47         000001      PP.BIS =      BIT0      ;SET specified bit.
48         000000      PP.BIC =      0      ;CLEAR specified bit.

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 9
PROGRAM-SPECIFIC EQUATES

```
1          .SBTITLE Program-specific Equates
2
3          ; EQUATES USED TO TURN LED ON AND OFF
4
5          000221      MODE      =      PP.MOD!PP.DRA!PP.CLO      ;Port A = Mode 0 IN
6                                         ;Port B = Mode 0 OUT
7                                         ;Port C upper nibble = OUT
8                                         ;Port C lower nibble = IN
9
10         000017      LEDUFF    =      PP.BIS!PP.BI7      ;Set PC7
11
12         ; EQUATES USED TO SET UP DLARTS
13
14         000032      BAUDRS   =      BD.024!XC.PBE      ;Initial console baud rate to
15                                         ; be 2400, with prog. baud
16                                         ; rates enabled.
17
18         000072      TUBAUD   =      BD.384!XC.PBE      ;TU58 Baud rate = 38,400
19
20         ; MEMORY CONFIGURATION EQUATES
21
22         160010      RAMBOT   =      160010      ;Bottom address of RAM
23         167776      RAMTOP   =      167776      ;Top address of RAM
24
25         ; SOFTWARE FLAGS AND MASKS
26
27         000300      PR16     =      300      ;PS for priority of 6
28         000340      PR17     =      340      ;PS for priority of 7
29
30         ; USED BY ODT MODULE
31
32         000200      RFLAG    =      BIT7      ;Register flag bit- Indicates
33                                         ; register is being examined
34         000020      T.BIT    =      BIT4      ;Trace bit in PSW
```

KXF11-A2 1K FIRMWARE MACRU V04.00 5-OCT-81 22:56:27 PAGE 10
PROGRAM-SPECIFIC EQUATES

```
1          ; RESTART TYPE WORD BITS
2
3      100000      R.HALT    =     BIT15      ;HALT or BREAK occurred
4      000200      R.NXM     =     BIT7       ;Accessed non-existent memory
5      000001      R.STAK    =     BIT0       ;Double-bus error
6
7          ; BOOT CONTROL WORD BITS
8
9      100000      NO.LOW    =     BIT15      ;No memory found at 000000-
10     000200      DEVBIT   =     BIT7       ; do not boot
11     000001      DEVNUM   =     BIT0       ;1 = RX01/02 floppy
12                           ;0 = TU58 cassette
13                           ;Unit no. (0 or 1)
14
15          ; DIAGNOSTIC MESSAGES
16
17     000100      E.EXT     =     100      ;SLU2 loopback test failed
18     000010      E.INT     =     10      ;SLU2 internal loopback failed
19     000001      E.PAR     =     1       ;Parallel port loopback failed
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 11
MACRO DEFINITIONS

```
1          .SBTTL MACRO DEFINITIONS
2
3          ;
4          ;      MACRO DEFINITIONS
5          ;
6
7          ;+
8          ;
9          ; This macro will insert ABORTS into the code which will halt the
10         ; program, exit to 00F with the PC printed on the console, and generate
11         ; an entry in the table of contents which describes the error condition.
12         ;
13         ;-
14
15         .MACRO ABORT    TEXT
16                 HALT
17                 PCS,\.
18                 .IRP      ----> HALT AT PC="PCS INDICATES ""TEXT"
19                 .ENDR
20                 BK       .-2
21         .ENDM
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 12
MACRO DEFINITIONS

```
1          ;+
2          ; DELAY A,B,N
3          ;      where A and B are names of registers that are free (both will
4          ;      be clear when through) and N is an integer.
5          ;
6          ; This macro produces a delay whose duration (when running in KXT11-AA
7          ; ROM) is .2399N seconds.
8          ; When N<4, it is more efficient to use the following code:
9          ;
10         ;      CLR      kn          ;1W      2.44
11         ;      SOB      Rn,.        ;1W      239861.76
12         ;      [SOB      Kn,.        ;1W      239861.76]
13         ;      [SOB      Rn,.        ;1W      239861.76]
14         ;
15         ; The macro generates code like the following:
16         ;
17         ;      MOV      $N,Ra          ;2W      3.66
18         ;ns:    CLR      Rb          ;1W      N*2.44
19         ;      SOB      Rb,.        ;1W      65536N*3.66
20         ;      SOB      Ra,ns        ;1W      N*3.66
21         ;-
22
23         .MACRO  DELAY  A,B,N,?L
24         MOV      $N,A
25         L:     CLR      B
26         SOB      B,.
27         SOB      A,L
28         .ENDM
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 13
RAM DEFINITION

```
1 .SBTTL RAM Definition
2
3 ; SCRATCH RAM AREA
4
5   167776     TRAP4 == 167776      ;Enables trap-to-4 emulation
6   167774     ODTWHY == 167774    ; when non-zero
7                                     ;User-readable copy of R.TYPE.
8                                     ; Restart cause. See R.TYPE
9                                     ; table in RESTART routine.
10  167772     O.CNTL == 167772    ;ODT Control word. Set Bit 15
11                                     ; to disable T-Bit filter, set
12                                     ; Bit 7 to disable Priority 7
13                                     ; filter.
14  167770     B.CNTL == 167770    ;Boot control word.
15  167766     R.PC == 167766     ;where restart saves top of stack
16  167764     IN.USR == 167764   ;Enables user-caused restart
17                                     ; and BREAK when non-zero
18  167762     R.TYPE == 167762   ;Restart cause. See table in
19                                     ; RESTART routine.
20  167760     USERSP == 167760   ;Used by ODT to store the user's
21                                     ; stack pointer.
22  167756     RPOINT == 167756   ;Used by ODT to point to the image
23                                     ; of user's R0 in its stack.
24  167754     SAVPS == 167754    ;Store halted PS here for ODT
25  167752     SAVPC == 167752    ;Store halted PC here for ODT
26  167750     ODTFLG == 167750   ;Used by ODT for internal flags.
27  167746     ODTLOC == 167746   ;Used by ODT to point to location
28                                     ; currently open.
29  167744     ODTSTK == 167744   ;Bottom of ODT's stack
30  167644     $STACK == ODTSTK-100 ;Bottom of default user stack
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 14
RAM DEFINITION

```
1      170000          .=170000
2
3          .SBTIL TRAPS-Trap-handling routines
4          .SBTIL TRAPS-LTC Trap-killer
5          .SBTIL TRAPS-BREAK handler
6
7          #####;#####;#####;#####;#####;#####;#####;#####
8          #####;#####;#####;#####;#####;#####;#####;#####
9          ####;
10         ####;           BREAK-HANDLING ROUTINE           ####;
11         ####;           AND LINE TIME CLOCK INTERRUPT KILLER   ####;
12         ####;           ####;
13         ####;           ####;
14         ####;           ####;
15
16 170000          $$$$BRK:::
17 170000 005767 177760      TST     IN.USR          ;Are we in user mode?
18 170004 001001          BNE     BRKNUO         ;YES-Go to ODT
19
20 170006          $$$$LTC:::
21 170006 000002          RTI               ;NO-Go back to ROM program.
22                                     ; BREAKS are ignored by ODT,
23                                     ; RESTART, POWERUP and the
24                                     ; DIAGNOSTICS. The BOOTS
25                                     ; can be interrupted, though.
26 170010          BRKNDO:::
27 170010 012667 177736      MOV     (SP)+,SAVPC    ;Save context
28 170014 012667 177734      MOV     (SP)+,SAVPS    ;for ODT.
29 170020 012767 100000 177734      MOV     #R.HALT,R.TYPE ;Causes PC to be printed
30                                     ; upon entry to ODT.
31 170026 005067 177732      CLR     IN.USR          ;Get out of user mode
32 170032 000167 000544      JMP     ODT
```

KXT11-A2 1K FIRMWARE
RESTART-INTRODUCTION

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```
1           .SBTTL RESTART-Introduction
2
3           ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4           ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5           ;;;;
6           ;;;          RESTART MODULE          ;;;;
7           ;;;           ;;;;
8           ;;;           ;;;;
9           ;;;           ;;;;
10          ;;;           ;;;;
11          ;+
12          ;
13          ;The purpose of the RESTART routine is to restore the FALCON to a
14          ;known state following those exceptions which cause a RESTART hardware
15          ;action. This action consists of stacking the current PSW and program
16          ;counter, then setting the PSW to 340 and jumping to the hardwired
17          ;RESTART location. This location is at the address START+4 where
18          ;START is jumper selectable as 000000, 010000, 020000, 040000, 100000,
19          ;140000, 172000 or 173000 (all in octal). This program is designed
20          ;for a START location of 172000, thus RESTARTs jump to 172004.
21          ;
22          ;There are several different ways in which RESTART performs its
23          ;function, depending on the value of IN.USR, TRAP4, the contents
24          ;of the location the SP points to, and one bit (R.STAK) in R.TYPE.
25          ;
26          ;R.TYPE, the restart type word, is RESTART's output to QDT.
27          ;
28          ;-
29          ;
30          ;+
31          ;
32          ;The goal is to maximize PDP-11 software compatibility and to provide
33          ;useful debugging information to the program developer.
34          ;
35          ;-
```

KXT11-AZ 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 16
RESTART-INTRODUCTION

```
1 ; -----  
2 ; | R.STrT | Enter via hardware mechanism,  
3 ; | | with (PS)=340  
4 ; | |  
5 ; |-----  
6 ; | Is the stack |  
7 ; | flag set? |  
8 ; | N | Y |  
9 ; |-----  
10 ; | |  
11 ; |-----  
12 ; | Set R.NXM |  
13 ; | Set IN-ROM mode |  
14 ; | Go to ODT |  
15 ; |-----  
16 ; -----  
17 ; | Set stack bit |  
18 ; | Read top of stack | <--- Could time out and cause the  
19 ; | Check if too close to "hole" | <--- exit to ODT shown above  
20 ; | Clear stack bit |  
21 ; -----  
22 ; |  
23 ; |-----  
24 ; | Did restart occur |  
25 ; | in user mode? |  
26 ; | N | Y |  
27 ; |-----  
28 ; |  
29 ; |-----  
30 ; | Is top of | <----+----- A BREAK does this when  
31 ; | stack 000000? | | there's no memory in  
32 ; | N | Y | | the vector area.  
33 ; |-----  
34 ; | |  
35 ; |-----  
36 ; | | Pop stack | <---- Only a BREAK while in ODT can  
37 ; | | frame and | | get us here, so the RTI takes  
38 ; | | return | | us back to ODT.  
39 ; |-----  
40 ; -----  
41 ; | Set carry | | Leave user mode |  
42 ; | in pushed PS | -----  
43 ; | and return | |  
44 ; |-----  
45 ; | | Is top of |  
46 ; | | stack 000000? |  
47 ; | A BREAK does this-->| Y | N |  
48 ; | when there's no |-----  
49 ; | memory in the | |  
50 ; | vector area |-----  
51 ; | | Pop stack | <---- This entry point is in  
52 ; | | frame and go | | the TKAPS module. It is  
53 ; | | to BREAK's | | where a BREAK in user mode  
54 ; | | SAVE CONTEXT | | goes when there IS memory  
55 ; | | entry point | | in the vector area.  
56 ; |-----  
57 ; |
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 17
RESTART-INTRODUCTION

```
1      ;           |
2      ;           |
3      ;           | Pop stack frame |
4      ;           | if 172004 on top. |
5      ;           | Get pushed PC. |
6      ;           | Set up ODT's PC |
7      ;           | and PS locations. |
8      ;           |
9      ;           |
10     ;           |
11     ;           COULD-->| Test word prior |
12     ;           TIME-->| to where pushed |
13     ;           OUT-->| PC points          |
14     ;           |
15     ;           |
16     ;           |
17     ;           |
18     ;           |
19     ;           |
20     ;           |
21     ;           |
22     ;           |
23     ;           |
24     ;           |
25     ;           |
26     ;           |
27     ;           |
28     ;           |
29     ;           |
30     ;           |
31     ;           |
32     ;           |
33     ;           |
34     ;           |
35     ;           |
36     ;           |
37     ;           |
38     ;           |
39     ;           |
40     ;           |
41     ;           |
42     ;           |
43     ;           |
44     ;           |
45     ;           |
```

```
COULD-->| Test word prior |
TIME-->| to where pushed |
OUT-->| PC points          |

-----
```

```
was the word |
a HALT
or did PC-->NXM?
Y   N
```

```
Set HALT flag |
Go to ODT
```

```
Is trap-to-4 |
emulation
enabled?
N   Y
```

```
Set NXM flag |
Go to ODT
```

```
Set user mode |
Push @#6, @#4
onto stack
and RTI
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 18
RESTART-INTRODUCTION

```
1          ;+
2          ;
3          ;exception-type word (R.TYPE) is passed to ODT and is RESTARTs "best guess"
4          ;as to why a restart happened:
5          ;
6          ;      Note: A user-readable copy of this word is at ODTWHY.
7          ;
8          ;-----|-----|-----|-----|
9          ;| EXIT | BIT | NAME | CAUSE
10         ;|-----|-----|-----|-----|
11         ;|-----|
12         ;| ODT | 15 | R.HALT | HALT instruction in user code-RESTART POPS STACK.
13         ;|       |    |           | Note-BREAK also sets this bit (see the TRAPS
14         ;|       |    |           | module).  UDT uses this bit for PDP-11 ODF
15         ;|       |    |           | compatibility.
16         ;|-----|
17         ;| ODT | 14 |           | Reserved
18         ;| OR  | 13 |           | Reserved
19         ;| TRAP | 12 |           | Reserved
20         ;| TO  | 11 |           | Reserved
21         ;| FOUR | 10 |           | Reserved
22         ;|       |  9 |           | Reserved
23         ;|       |  8 |           | Reserved
24         ;|       |  7 | R.NXM | Timeout during user access of non-existent
25         ;|       |    |           | memory
26         ;|       |  6 |           | Reserved
27         ;|       |  5 |           | Reserved
28         ;|       |  4 |           | Reserved
29         ;|       |  3 |           | Reserved
30         ;|       |  2 |           | Reserved
31         ;|       |  1 |           | Reserved
32         ;|-----|
33         ;| ODT | 0 | R.STAK | Indicates that a timeout was caused by RESTART
34         ;|       |    |           | itself accessing non-existent memory. This
35         ;|       |    |           | occurs in conjunction with testing for
36         ;|       |    |           | validity of the stack pointer.
37         ;|       |    |           | In PDP-11 parlance, this is a
38         ;|       |    |           | "double=bus error"
39         ;|-----|
40         ;
41         ;-
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 19
RESTART-ENTRY POINT

```
1          .SBTTL RESTART-Entry point
2
3
4
5
6          #####           RESTART ENTRY POINT           #####
7
8
9
10
11 170036 R.START:::
12
13
14
15
16          #####           IF THE RESTART ROUTINE CAUSED THE RESTART           #####
17          #####           GO TO ODT AND PRINT "?"           #####
18
19
20          #####           THIS EXCEPTION CAN BE CAUSED BY RESTART'S           #####
21          #####           STACK MANIPULATIONS           #####
22
23
24
25          ; R.TYPE will have been cleared prior to entering
26          ; any ODT command. So, if the stack bit is set, only RESTART
27          ; itself could have caused the trap. Since the stack is always
28          ; valid in in-ROM mode, bad stack means we are in in-USER mode.
29
30          ;State: X=don't care, U=user, R=in-RUM----
31          ;
32 170036 005767 177720      TST     R.TYPE          ;X|Did the stack test fail?
33 170042 001406      BEQ     1S          ;X|NO- go to next test
34 170044 052767 000200 177710      BIS     #R.NXM,R.TYPE    ;U|YES- set R.NXM
35
36 170052 005067 177706      CLR     IN.USR         ;U| this forces "?" from ODT
37 170056 000476      BR     8$          ;R|enter in-ROM mode
                                         ;R|go to ODT
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 20
RESTART-SEE IF STACK EXISTS

```
1          .SBTTL RESTART-See if stack exists
2
3
4
5
6          ;;;;;
7          ;;;;;
8          ;;;;;
9          ;;;;;
10         ;;;;;
11 170060 052767 000001 177674 16:    BIS    -#R.STAK, R.TYPE      ;X|If we timeout, we want RESTART
12                               ;X| to know we were diddling SP
13 170066 005716               TST    (SP)           ;X|see if stack is valid
14 170070 000240               NOP
15 170072 005766 000004       TST    4(SP)          ;X|in case times out
16 170076 000240               NOP
17 170100 005067 177656       CLR    R.TYPE          ;X|see if too close to top of
                                ;X|valid memory
                                ;X|stack is OK
18
19          .SBTTL RESTART-Exit if in IN-ROM state
20
21
22
23
24          ;;;;;
25          ;;;;;
26          ;;;;;
27          ;;;;;
28          ;;;;;
29          ;;;;;
30
31 170104 005767 177654       TST    IN.USR          ;X|Are we in user mode?
32 170110 001007               BNE    3$             ;J|YES-go to next test
33 170112 005716               TST    (SP)           ;R|NO-see if BREAK brought
                                ;R|us here
34
35 170114 001002               BNE    2$             ;R|NO-Just a RESTART
36 170116 022626               CMP    (SP)+,(SP)+    ;R|YES-Behave like a BREAK that
37 170120 000002               RTI
                                ;R|happened with RAM
38
39 170122 005266 000002       2$:    INC    2(SP)          ;R|Set carry in pushed PS
40                               ;R| UNLESS ALREADY SET
41 170126 000002               RTI
                                ;R|and return to ROM code that
                                ;R| caused timeout
42
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 21
RESTART-CAUSE DETERMINATION

```
1          .SBTTL RESTART-Cause determination
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;;
6          ;;; DETERMINE HOW USER CAUSED A RESTART ;;;
7          ;;;;
8          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
9          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
10         ;
11 170130 005067 177630    3$:   CLR     IN.USR      ;U|we were in user mode,
12                      ;R| but no longer.
13 170134 005716          TST     (SP)       ;R|See if BREAK brought
14                      ;R| us here without low "core".
15 170136 001003          BNE     4$       ;R|NO-Just a RESTART
16 170140 022626          CMP     (SP)+,(SP)+ ;R|YES-behave like a BREAK that
17 170142 000167 177642    JMP     BRKNUO    ;R| happened while in user prog.
18
19
20          ;
21          ; If the CPU attempts to fetch an instruction from non-existent
22          ; memory, two traps (the first from executing a HALT, the second
23          ; from timing out) will occur, the result being that second
24          ; trap pushes the restart address and 340 on the stack.
25          ; This information is useless and gets popped here.
26
27 170146 021627 172004    4$:   CMP     (SP),#RESTAR   ;X|Get rid of double stacking
28 170152 001001          BNE     5$       ;X|caused by EXECUTION of NXM
29 170154 022626          CMP     (SP)+,(SP)+ ;X|
30
31          ;
32          ; Note: Because the contents of the stack is assumed to remain
33          ; unchanged following the first instruction below, it is imperative
34          ; that interrupts be disabled during the next three instructions.
35 170156 012667 177604    5$:   MOV     (SP)+,R.PC    ;R|Get pushed PC
36 170162 011667 177566    MOV     (SP),SAVPS   ;R|ODT would like
37 170166 014667 177560    MOV     -(SP),SAVPC  ;R|to see these
38
39 170172 162767 000002 177566    SUB     #2,R.PC    ;R|Set pointer to last word fetched
40                      ;R| before restart occurred
41 170200 005777 177562    TST     @R.PC     ;R|Is contents of pushed PC - 2
42                      ;R| a zero (eg a HALT)?
43 170204 000240          NOP     ;R|Make sure next instruction
44                      ;R| won't execute if we time out
45 170206 001005          BNE     6$       ;R|NU- it was an NXM
46 170210 052767 100000 177544    BIS     *R.HALT,R.TYPE ;R|YES- Flag a HALT,
47 170216 022626          CMP     (SP)+,(SP)+ ;R|pop the non-PDP-11 stack frame
48 170220 000415          BR     8$       ;R|and go to ODT.
49
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 22
RESTART-EXITS

```
1                               .SBTTL RESTART-Exits
2
3
4
5
6           EXIT APPROPRIATELY
7
8
9
10
11 170222 005767 177550      6$:    TST     TRAP4          ;R|Trap-to-4 emulation enabled?
12 170226 001407              BEQ     7$          ;R|NO-go to ODT
13 170230 005167 177530      COM     IN.USR         ;U|YES-Set user mode
14 170234 013746 000006      MOV     @#6,-(SP)       ;U|Emulate a
15 170240 013746 000004      MOV     @#4,-(SP)       ;U|trap to
16 170244 000002              RTI          ;U|four
17
18 170246 052767 000200 177506 7$:    BIS     #R.NXM, R.TYPE   ;R|flag NXM error
19 170254 000167 000322      8$:    JMP     OCT          ;R|go to ODT
```

KXT11-A2 1K FIRMWARE
POWERUP-INTRODUCTION

MACRO V04.00 5-OCT-81 22:56:27 PAGE 23

```
1          .SBTTL POWERUP-Introduction
2
3
4
5
6          ;;;;;;;;;;;;;;;;;;;;
7          ;;;;           POWER-UP MODULE   ;;;;
8
9
10         ; This module contains a series of routines which perform
11         ; tests on the on-board RAM and the console DLART. These
12         ; tests are preceded by the lighting of the LED on the
13         ; KXT11-AA board, and followed by its extinguishing. Should
14         ; the LED fail to either light or go out, there may be a
15         ; defect in the board or its configuration.
16
17         ; Following these tests, the on-board RAM is written with the
18         ; default values of certain control words, and, if there is
19         ; memory in the vector region (i.e., near 000000), the BREAK
20         ; and clock vectors are set up. If not, a bit is set in the
21         ; boot control word to disable the bootstraps.
22
```

KX11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 24
POWERUP-TURN ON LED

```
1          .SBTTL POWERUP-Turn on LED
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;
5          ;;;;
6          ;;;      TURN ON LED      ;;;;
7          ;;;;
8          ;;;;
9          ;;;;
10         ;;;;
11
12 170260          PWRSUP:::
13 170260 012706 167644        MOV      #$STACK,SP           ;Initialize stack pointer
14
15          ; Because a mode-setting command automatically clears all the internal
16          ; registers in the PPI, and clearing Port C Bit 7 turns on the LED, all
17          ; we have to do is set the mode, which is port A and lo half of C as
18          ; input, ports B and hi half of C as output.
19
20 170264 012737 000221 176206        MOV      $MODE,@#PP.CWK       ;Set proper PPI mode
21
22          .SBTTL POWERUP-Test console DLART
23
24          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
25          ;;;;
26          ;;;;
27          ;;;      CHECK THE CONSOLE DLART      ;;;;
28          ;;;;
29          ;;;;
30          ;;;;
31
32 170272 005037 177564          CLR      @#XCSR$1           ;Disable XMIT interrupts,
33                                         ; bRK XMIT, maint. mode
34                                         ; Set baud rate to default
35 170276 005737 177562          TST      @#RBUFS1           ;Take out the trash.
36 170302 032737 000300 177560        BIT      #<RC.IEN!RC.DUN>,@#RCSR$1
37                                         ;Should be clear.
38 170310 001377          BNE      .                 ;if not, drop dead.
39 170312 023727 177564 000200        CMP      @#XCSR$1,#XC.RDY    ;Should be set
40 170320 001377          BNE      .                 ;If not, rest in peace.
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 25
POWERUP-TEST AND SET UP I/O-PAGE RAM

```
1          .SBT1L POWERUP-Test and set up I/O-page RAM
2
3
4
5
6          ;;;;;
7          ;;;;;
8          ;;;;;
9          ;;;;;
10         ;;;;;
11
12         ; Write the location's address into the location and read it back.
13         ; Do this for all I/O page RAM locations.
14         ; If it fails, enter tight loop.
15
16         ; In the process, clear all of this RAM. Note that the default
17         ; value of most of the control and flag words is zero.
18
19 170322 012700 160010      MOV      #RAMBOT,R0           ;Lowest address of RAM
20 170326 010010      1$:    MOV      R0,(R0)           ;Write the address
21 170330 020010      CMP      R0,(R0)           ;Read it back
22 170332 0013/7      2$:    BNE      2$               ;Tight failure loop
23 170334 005020      CLR      (R0)+            ;Clear and go on to next location
24 170336 020027 170000      CMP      R0,#RAMTOP+2     ;Until no more to test.
25 170342 103771      BLO      1$
```

KXT11-A2 1K FIRMWARE MACHRO V04.00 5-OCT-81 22:56:27 PAGE 26
POWERUP-TURN OFF LED

```
1 .SBTTL POWERUP-Turn off LED
2
3
4
5
6 ;;; DELAY SO THAT LED IS ON A VISIBLE LENGTH OF TIME ;;;
7
8
9
10
11 170344 005000      CLR    R0
12 170346 077001      S0B    R0,3$           ;This leaves a 0 in R0, which
13 170350 077001      S0B    R0,4$           ; is essential for testing for
14 170352 077001      S0B    R0,5$           ; the presence of memory at
15 170354 077001      S0B    R0,6$           ; zero below.
16
17 ; Under no circumstances can R0 be altered until "low core" test below.
18
19
20
21
22 ;;; TURN OFF LED
23
24
25
26
27 170356 012737 000017 176206      MOV    #LEDOFF,0#PP.CWR
28
29 .SBTTL POWERUP-Test for "low core"
30
31
32
33
34 ;;; TEST FOR MEMORY AT 000000
35
36
37
38
39 ; Read memory at 000000, discard result. If this fails, exit to
40 ; AUTOBAUD rather than continuing with normal powerup sequence.
41
42 170364 005710      TST    (R0)
43 170366 000240      NOP
44
45 170370 103403      BCS    7$           ;This will execute even if
46 170372 004767 000042  CALL   VECSET      ; last instruction times out
47 170376 000403      BR     8$           ;Timed out, don't set vectors
48
49 170400 052767 100000 177362 76:    BIS    #NO.LOW,B.CNTL    ; Didn't time out,
50                                         ; so go ahead
                                         ;Don't set the NO.LOW flag
                                         ;Did time out,
                                         ; so let the world know.
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 27
 POWERUP-EXIT

```

1          .SBTTL POWERUP-Exit
2
3          ;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;
5          ;;;;
6          ;;; EXIT FROM POWER-UP SEQUENCE ;;;;
7          ;;;;
8          ;;;;;;;;;;;;;;;;;;;
9          ;;;;;;;;;;;;;;;;;;;
10         ;;;;;;;;;;;;;;;;;;;
11 170406 012767 000300 177340 8$:    MOV    #PRI6,SAVPS      ;If P is typed in reponse to
12 170414 012767 170424 177330      MOV    #FAKOUT1,SAVPC   ; ODT prompt before loading R7,
13 170422 000423                  BR     AUTOBA           ; will force yet more ODT.
14
15 170424          FAKOUT:
16 170424 005067 177334          CLR    IN.USR          ; BUT IN THE RIGHT MODE!
17 170430 012706 167644          MOV    #SSTACK,SP       ; And without running out of
18 170434 000167 000142          JMP    ODI              ; stack, either.
19
20          .SBTTL POWERUP-Subroutine to initialize vectors
21
22          ;;;;;;;;;;;;;;;;;;;
23          ;;;;;;;;;;;;;;;;;;;
24          ;;;;
25          ;;; INITIALIZE VECTORS ;;;;
26          ;;;;
27          ;;;;;;;;;;;;;;;;;;;
28          ;;;;;;;;;;;;;;;;;;;
29
30          ; Note: This subroutine is also used by the bootstrap module, to
31          ; restore the vector area in the event that an invalid boot block
32          ; was read into low memory.
33
34 170440          VECSET::
35 170440 012737 170000 000140      MOV    #$$$$BFK,@#140    ;Set up the BREAK-detect
36 170446 012737 000340 000142      MOV    #PRI7,@#142      ; vector.
37 170454 012737 170006 000100      MOV    #$$$LTC,@#100    ;Set up the line time clock
38 170462 012737 000340 000102      MOV    #PRI7,@#102      ; vector.
39 170470 000207                  RETURN

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 28
AUTOBAUD-SYNCHRONIZE WITH CONSOLE

```
1          .SBTTL AUTOBAUD-Synchronize with Console
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;;;
6          ;;;;;
7          ;;;;;
8          ;;;;;
9          ;;;;;
10         ; Description:
11         ;
12         ; AUTOBAUD allows the FALCON to automatically synchronize its
13         ; console DLART to the baud rate of the console terminal.
14         ; On power-up, the user must type a carriage return character.
15         ; Upon synchronization, AUTOBAUD will proceed to OUT where an "q"
16         ; character will be displayed on the console.
17         ;
18         ; Autobaud will loop indefinitely until synchronization is successful.
19         ;
20         ; The algorithm requires that the console terminal generates a
21         ; zero (space) for the eighth bit in the carriage return. This
22         ; will happen if the terminal is capable of sending eight-bit-
23         ; no-parity or seven-bit-odd-parity characters.
24         ;
25         ; Environment:
26         ;
27         ; Interrupts must be disabled for the algorithm to execute correctly
28         ; since time durations are critical and delays due to long
29         ; service routines may cause DLART overruns, which this routine
30         ; ignores but cannot tolerate.
31         ;
32
33
34
35         ; VT103/FALCON configurations leave garbage in the DLART long after the
36         ; powerup sequence has begun. We must delay a bit before clearing garbage
37         ; out of the DLART, otherwise the garbage would arrive after the clear
38         ; (i.e., while polling for input). The "garbage" is an X-ON (<CTRL-Q>)
39         ; that the VT-100 hardware sends after its power-up diagnostics have
40         ; completed successfully.
41         ;
42
43 170472          AUTOBAU:
44 170472 012737 000032 177564    MOV      #BAUDRS,$0#XCSR$1      ;Set 2400 baud
45 170500 005000           CLR      R0                  ;Delay
46 170502 077001           SOB      R0,.                ;     .5
47 170504 077001           SOB      R0,.                ;     seconds
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OC1-81 22:56:27 PAGE 29
AUTBAUD-SYNCHRONIZE WITH CUNSOLE

```

1 ; AUTOBAUD proper:
2
3 170506 105737 177562    10$:   TSTB   @#RBUFS1           ; discard any garbage
4
5 170512 105737 177560    20$:   TSTB   @#RCRS$1          ; wait for input
6 170516 100375          BPL    20$               ; R0 = input character
7 170520 113700 177562    MOVB   @#RBUFS1, R0        ; R1 -> scrambled char table
8 170524 012701 170550    MOV    #INBYTE, R1        ; in the table?
9 170530 120021          CMPB   R0, (R1)+       ; yes
10 170532 001411          BEQ    HVBAUD          ; end of table reached?
11 170534 020127 170556    CMP    R1, #INBYTS      ; not yet
12 170540 001373          BNE    30$               ; uh oh, wait for DLART to clear out
13 170542 005000          CLR    R0               ; wait for a while
14 170544 077001          SOD    R0, 40$          ; and try for another character
15 170546 000757          BR     10$               ; baud rates.

16 ; Table of what you would see if an octal 15 were sent at the following
17 ; baud rates.
18
19
20 170550          INBYTE:
21 170550 200          .BYTE  200             ; 300
22 170551 170          .BYTE  170             ; 600
23 170552 346          .BYTE  346             ; 1200
24 170553 015          .BYTE  15              ; 2400
25 170554 362          .BYTE  362             ; 4800
26 170555 377          .BYTE  377             ; 9600, 19200, 38400
27 170556          INBYTS:
28
29 ; We have a match. Set baud rate into DLART.
30
31 170556          HVBAUD:
32 170556 162701 170551  SUB    #INBYTE+1, R1        ; turn pointer into bit mask
33 170562 006301          ASL    R1               ; turn on XC,PBE
34 170564 006301          ASL    R1               ; set the baud rate
35 170566 005201          INC    R1               ; into CSR
36 170570 006301          ASL    R1               ; delay .24 seconds for rest
37 170572 010137 177564  MOV    R1, e#XCSR$1      ; of char. at slo baud rates
38 170576 005000          CLR    R0               ; Fall into ODT.
39 170600 077001          SUB    R0, .
40
41

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 30
MACROODT-INTRODUCTION

```
1          .SBTITLE macroODT-Introduction
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;;
6          ;;;      macroODT      ;;;;
7          ;;;;
8          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
9          ;;;;;;;;;;;;;;;;;;;
10         ; macroODT is the user interface to the functions contained
11         ; in the KXT11-A2 firmware product. It interprets commands
12         ; entered via the console terminal keyboard (see tables below)
13         ; to permit the user to load a program into memory, execute
14         ; it and debug it.
15
16         ; COMMAND
17         ; 1- Slash (/)
18         ;     a-OPEN MEMORY LOCATION
19         ;     b-OPEN GENERAL REGISTER
20         ;     c-OPEN STATUS REGISTER
21         ; 2- Carriage return (<CR>)
22         ;     a-CHANGE AND CLOSE MEMORY LOCATION OR REGISTER
23         ;     b-CLOSE WITHOUT CHANGE
24         ; 3- Line feed (<LF>)
25         ;     a- CHANGE AND CLOSE MEMORY LOCATION AND OPEN NEXT
26         ;     b- CLOSE MEMORY LOCATION WITHOUT CHANGING AND OPEN NEXT
27         ; 4- Go (G)
28         ; 5- Proceed (P)
29         ; 6- Execute i/O diagnostics (X)
30         ; 7- Execute bootstraps (D)
```

KXT11-A2 1K FIRMWARE MACRU V04.00 5-OC1-81 22:56:27 PAGE 31
MACROOUT-INTRODUCTION

```
1      ;SYNTAX OF COMMANDS LISTED ABOVE, SHOWING CONSOLE BEFORE,
2      ;DURING AND AFTER THE TYPING OF THE COMMAND.
3      ;      Key: n-an octal integer typed by the user, only
4      ;              last 6 digits significant
5      ;      x-a single octal digit
6      ;      u-the digits 0 or 1
7      ;      all other characters are literals
8
9      ;      BEFORE          DURING          AFTER
10     ;
11     ;1a @      @n/             @n/xxxxxx
12     ;1b @      @Rx/            @Rx/xxxxxx
13     ;1c @      @Rs/            @Rs/xxxxxx
14     ;2a @n/xxxxxx @n/xxxxxx n<CR> @
15     ;2a @Rx/xxxxxx @Rx/xxxxxx n<CR> @
16     ;2a @Rs/xxxxxx @Rs/xxxxxx n<CR> @
17     ;2a xxxxxx/xxxxxx xxxxxx/xxxxxx n<CR> @
18     ;2b @n/xxxxxx @n/xxxxxx <CR> @
19     ;2b @Rx/xxxxxx @Rx/xxxxxx <CR> @
20     ;2b @Rs/xxxxxx @Rs/xxxxxx <CR> @
21     ;2b xxxxxx/xxxxxx xxxxxx/xxxxxx <CR> @
22     ;3a @n/xxxxxx @n/xxxxxx n<LF>  xxxxxx/xxxxxx
23     ;3a xxxxxx/xxxxxx xxxxxx/xxxxxx n<LF>  xxxxxx/xxxxxx
24     ;3b @n/xxxxxx @n/xxxxxx <LF>   xxxxxx/xxxxxx
25     ;3b xxxxxx/xxxxxx xxxxxx/xxxxxx <LF>  xxxxxx/xxxxxx
26     ;4 @      @nG
27     ;5 @      @P
28     ;6 @      @X      xxxxxx
29     ;
30     ;7 @      @DDu
31     ;7 @      @DXu
32     ;7 @      @DYu
33     ;7 @      @DD<CR>
34     ;7 @      @DX<CR>
35     ;7 @      @DY<CR>
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 32
MACR0UUT=SAVE STATUS AND PRINT PROMPT

```

1          .SBTLL macroUDT=Save status and print prompt
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;          SAVE CONTEXT, PRINT MESSAGES AND PROMPT      ;;;;
6          ;;;          ;;;;
7          ;;;          ;;;;
8          ;;;          ;;;;
9          ;;;          ;;;;
10         ;ODT:::
11 170602   TSTB    @#RBUFS1           ;Clear out console garbage
12 170602   105737  177562
13
14          ; Copy the restart type word into user area
15
16 170606   016767  177150  177160     MOV     R.TYPE,ODTWHY
17
18          ; Protect against stack timeouts, but save user's SP first
19
20 170614   010667  177140     MOV     SP,USERSP           ;SAVE USERS STACK POINTER
21 170620   012706  167744     MOV     #ODTSIK,SP        ;LOAD NEW SP
22
23          ; Save rest of user program's context
24
25 170624   016716  177130     MOV     USERSP,(SP)       ;RESERVE LOCATION FOR R6
26 170630   010546     MOV     R5,-(SP)          ;SAVE
27 170632   010446     MOV     R4,-(SP)          ; ALL
28 170634   010346     MOV     R3,-(SP)          ; UF
29 170636   010246     MOV     R2,-(SP)          ; USER'S
30 170640   010146     MOV     R1,-(SP)          ; GENERAL
31 170642   010046     MOV     R0,-(SP)          ; REGISTERS
32 170644   010667  177106     MOV     SP,RPOINT        ;POINTER TO R0
33
34          ; Determine whether "?" or PC message is appropriate, and print it
35
36 170650   005767  177106     TST     R.TYPE           ;Did we get a HALT or BREAK?
37 170654   100004     BPL    QODT            ;NU=next question
38
39 170656   016700  177070     MOV     SAVPC,R0        ;YES=PRINT PC
40 170662   004767  000764     CALL   OCTSTO        ;GLI STOPPED PC
41 170666     QODT:::
42 170666   105767  177070     TSTB   R.TYPE           ;TYPE THE PC ON TERMINAL
43
44 170672   100003     BPL    KBDS            ;SEE IF RESTART OCCURRED
45                                         ;(NXM ONLY=BIT 7 SET)
46                                         ;TYPE PROMPT
47
48 170674     KBDQ:::
49 170674   012700  171730     MOV     #MSGQ,R0        ; GET ? ADDRESS
50 170700   000402     BR     PRINT           ;TYPE IN MESSAGE
51 170702     KBDS:::
52 170702   012700  171731     MOV     #MSG$,R0        ;GET PROMPT MESSAGE ADDRESS
53
54 170706   005067  177050     PRINT: CLR    R.TYPE           ;So reentry gives no error msg.
55 170712   106427  000300     MTPS   #PRI6           ;Allow BREAKs to happen
56 170716   004767  000620     CALL   PUTSTR        ;TYPE THE PROMPT ALREADY
57 170722   005067  177022     CLR     ODTFLG         ;CLEAR FLAG FOR NEW ENTRY

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 33
 MACROUT-GET ODT COMMAND

```

1           .SBTTL macroODT-Get ODT command
2
3
4
5
6           ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
7           ;;;          INTERPRET FIRST CHARACTER OF COMMAND   ;;
8           ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
9           ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
10          ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
11          ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
12          ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
13          ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
14          ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
15          ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
16          ;;;          ;;;          ;;;          ;;;          ;;;          ;;;
17
18 170726 004767 000556      CALL    GETCHR          ;...INPUT CHARACTERS
19 170732 120227 000104      CMPB    R2,#'D        ;BOOTSTRAPS?
20 170736 001002            BNE    1$              ;NO
21 170740 000167 001220      JMP    BOOTS          ;YES
22
23 170744 120227 000130      1$:   CMPB    R2,#'X        ;DIAGNOSTICS?
24 170750 001002            BNE    2$              ;NO
25 170752 000167 000776      JMP    DIAGNO         ;YES
26
27 170756 120227 000120      2$:   CMPB    R2,#'P        ;PROCEED?
28 170762 001430            BEQ    PCMD          ;YES
29 170764 120227 000122      CMPB    R2,#'R        ;REGISTER?
30 170770 001465            BEQ    RCMD          ;YES
31 170772 120227 000060      CMPB    R2,#'0        ;OCTAL DIGIT?
32 170776 103736            BLD    KBDQ          ;NO,ERROR
33 171000 120227 000070      CMPB    R2,#'8        ;VALID DIGIT?
34 171004 103333            BHIS   KBDQ          ;NO,ERROR
35 171006 005000            CLR    R0              ;ITS A DIGIT
36 171010 004767 000576      CALL   GETNUM         ;GET REST OF THE DIGIT OR CMD
37 171014 103327            BCC    KBDQ          ;CR WAS ISSUED,ERROR
38
39           ; The last character at the end of the number could be a valid command-
40           ; Let's check:
41
42 171016 120227 000057      CMPB    R2,#'/
43 171022 001511            BEQ    LCSET          ;EXAMINE LOCATION?
44 171024 120227 000107      CMPB    R2,#'G        ;YES
45 171030 001321            BNE    KBDQ          ;GO TO?

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-UCT-81 22:56:27 PAGE 34
MACRODT-GET ODT COMMAND

; TABLE OF PERMISSABLE STATES					
		NU.	STATE	VALID INPUTS	COMMENT
1					
2					
3					
4		1-	prompt @	0-7	-----> digit.
5				P	-----> proceed.
6				R	-----> register designator.
7				X	-----> execute diagnostic
8				D	-----> boot from device
9		2-	@175620	0-7	-----> another digit.
10			[input digit]	/	-----> examine loc.
11				G	-----> go from loc n.
12		3-	@176000/000002	0-7	-----> input new value.
13				LF	-----> display next loc.
14				CR	-----> close loc go to prompt.
15		4-	@200/000023 12	0-7	-----> input more digits.
16				LF	-----> save data display next.
17				CR	-----> save data go to prompt.
18		5-	@R	0-7	-----> register number.
19				S	-----> PSW.
20		6-	@R5	/	-----> examine.
21		7-	@R5/000024	0-7	-----> input new value.
22				CR	-----> close location.
23		8-	@R5/000024 16	0-7	-----> more digits input
24				CR	-----> save value go to prompt
25					

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 35
MACRUUDI- GO AND PROCEED

```
1          .SBTTL MACRUDI- Go and Proceed
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;      PROCESS GO AND PROCEED ODT COMMANDS    ;;;
6          ;;;      ;;;;
7          ;;;      ;;;;
8          ;;;      ;;;;
9          ;;;      ;;;;
10         171032 010067 176714           MOV     R0,SAVPC          ;PUT SUPPLIED PC IN MEMORY LOCATION
11
12
13          ; Prepare the environment for the Go command
14
15         171036 000005           RESET   SAVPS          ;BUS INITIALIZE
16         171040 005067 176710           CLR     SAVPS          ;CLEAR PSW
17
18          ; Entry point for the Proceed command
19
20          ; First, check for valid stack:
21
22         171044           PCMD:
23
24         171044 016600 000014           MOV     14(SP),R0          ;User's stack pointer
25         171050 005740           TST    -(R0)          ;Where SAVPS will go (see below)
26         171052 000240           NOP
27         171054 103403           BCS    18
28         171056 005740           TST    -(R0)          ;(in case of time out)
29         171060 000240           NOP
30         171062 103004           BCC    28          ;No good. Timed out.
31
32          ; Where SAVPS will go (see below)
33          ; Either stack no good, so simulate a double bus trap without losing the
34          ; user's context as stored in the ODT stack.
35         171064 012767 000201 176702 1$:   MOV     #R.STAK!R.NXM,ODTWHY ;Sneaky! (R.TYPE untouched-
36
37         171072 000700           BR     KBDQ          ;only the user image of it)
38
39          ; OR      Stack is OK, so restore user's context.
40
41         171074 012600           2$:   MOV     (SP)+,R0          ;RESTORE
42         171076 012601           MOV     (SP)+,R1          ; ALL
43         171100 012602           MOV     (SP)+,R2          ; OF
44         171102 012603           MOV     (SP)+,R3          ; USER'S
45         171104 012604           MOV     (SP)+,R4          ; GENERAL
46         171106 012605           MOV     (SP)+,R5          ; REGISTERS
47
48         171110 106427 000340           MTPS   #PRI7          ;No BREAKS allowed until out of
49
50         171114 042716 000001           BIC    #BIT0,(SP)        ;ODT!
51         171120 011606           MOV     (SP),SP          ;Odd stacks are too odd for T-11
52         171122 005167 176636           COM    IN.USR          ;RESTORE USER SP
53         171126 016746 176622           MOV     SAVPS,-(SP)        ;Set user mode
54         171132 016746 176614           MOV     SAVPC,-(SP)        ;RESTORE PC AND PS TO ...
55         171136 000006           RTT
56         171140 000655           HKBDQ: BR     KBDQ          ;...STACK WHERE RTT WILL LOOK
57         171142 000657           HKBDS: BR     KBD$          ;RETURN TO USERS PROGRAM
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MACRODTT-REGISTER AND PS COMMAND

```
1           .SBTTL macroDTT-Register and PS command
2
3           ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4           ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5           ;;;;
6           ;;; PROCESS DTT REGISTER COMMANDS ;;;;
7           ;;;;
8           ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
9           ;;;;;;;;;;;;;;;;;;;
10          ;;;;;;;;;;;;;;;;;;;
11          ; Entry point for KX and RS commands
12
13 171144   RCMD:
14 171144   052767  000200  176576     BIS    #RFLAG,ODTFLG      ;SET REGISTER FLAG
15 171152   004767  000420     CALL   ONUM        ;GET REGISTER NUMBER
16 171156   103246     BCC   KBDQ        ;A VALID CMD DID NOT FOLLOW
17 171160   120227  000123     CMPB  R2,*$        ;IS IT THE RS?
18 171164   001412     BEQ   SWCMD        ;YES,BRANCH
19 171166   120227  000057     CMPB  R2,*'        ;EXAMINE?
20 171172   001240     BNE   KBDQ        ;NO,ERROR
21 171174   020027  000007     CMP   R0,#7        ;>?
22 171200   101235     BHI   KBDQ        ;YES,ERROR
23 171202   001013     BNE   RCMD1       ;IS IT EXACTLY SEVEN
24 171204   012700  167752     MOV   #SAVPC,R0      ;YES,GET PC ADDRESS
25 171210   000413     BR    REGOUT       ;DISPLAY
26
27          ; Status register (PS) selected:
28
29 171212   SWCMD:
30 171212   004767  000272     CALL   GETCHR       ;WHAT YOU WANT TO DO WITH RS?
31 171216   120227  000057     CMPB  R2,*'        ;EXAMINE?
32 171222   001224     BNE   KBDQ        ;NO,ERROR
33 171224   012700  167754     MOV   #SAVPS,R0      ;GET ADDRESS WHERE PS IS
34 171230   000403     BR    REGOUT       ;GO AND DISPLAY
35
36 171232   006300     RCMD1: ASL   R0          ;SHIFT FOR OFFSET IN MEMORY
37 171234   066700  176516     ADD   RPOINT,R0      ;GET EXACT ADDRESS OF REG.
38 171240   010067  176502     REGOUT: MOV   R0,ODTL0C      ;STORE LOCATION
39 171244   000402     BR    LOCDSP       ;DISPLAY
```

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MACROOUT-EXAMINE AND DEPOSIT

1 .SBTTL macroODT-Examine and Deposit
2
3 ;;
4 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5 ;;;
6 ;;; PROCESS ODT MEMORY AND REGISTER EXAMINE/DEPOSIT ;;;
7 ;;;
8 ;;;
9 ;;;
10 ;;;
11 ; ODTLOC points to register or memory location
12 ; Following CALL GETNUM, if carry is clear, CR followed digit.
13 ; OUTFLG: If register bit set indicates register is being examined
14
15 ;ENTRY FROM CMD ROUTINE AFTER LOC. VALUE IS GIVEN
16
17 171246 010067 176474 LCSET: MOV R0,ODTLOC ;SAVE NEW LOCATION
18 171252 011000 LOCDSP: MOV (R0),R0 ;GET DATA
19 171254 000240 NOP ;So next inst. does not execute
20 ;if we time out.
21 171256 103730 BCS HKBDQ ;Print "?" if we timed out
22 171260 004767 000372 CALL OCTSTR ;PRINT IT
23 171264 112702 000040 MOVB #SPACE,R2 ;Print a space after the data
24 171270 004767 000226 CALL PUTCHR
25 171274 004767 000210 CALL GETCHR ;GET NEXT CHARACTER
26 171300 120227 000015 CMPB R2,#CR ;FINISH
27 171304 001716 BEQ HKBD\$;YES,CLOSE LOCATION
28 171306 120227 000060 CMPB R2,#"0 ;DEPOSIT?
29 171312 103450 BLO 4\$;NO,CHECK LF
30 171314 120227 000070 CMPB R2,#"8 ;MAYBE!
31 171320 103307 BHIS HKBDQ ;NO,FORGET IT
32 171322 005000 CLR R0 ;YES
33 171324 004767 000262 CALL GETNUM ;GET REST OF NUMBER
34 171330 103006 BCC 1\$;CR FOUND, STGRE NEW VALUE
35
36 171332 120227 000012 CMPB R2,#LF ;Not CR, must be LF
37 171336 001300 BNE HKBDQ ;Print error message
38 171340 105767 176404 TSTB ODTFLG ;If LF, cannot be register
39 171344 100675 BMI HKBDQ ;(Error exit)
40
41 ;T-BIT FILTER. The T-BIT can be set from the keyboard via ODT.
42 ;This can either be useful for debugging or disastrous. So, you can
43 ;do it only if you first set FILT.T in O.CNTL (bit 15).
44
45 171346 022767 167754 176372 1\$: CMP #SAVPS,UDTLOC ;Are we diddling the PS?
46 171354 001021 BNE 3\$;No, we're not.
47 171356 042700 177400 BIC #C<377>,R0 ;PS is not a word.
48 171362 005767 176404 TST O.CNTL ;Is bit 15 (FILT.T) SET?
49 171366 100402 BMI 2\$;Yes, the filter's disabled
50 171370 042700 000020 BIC #T.BIT,R0 ;KILL THE T-BIT
51
52 ;2\$: ;Fall thru to Priority 7
53 ; Filter

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MACRODT=EXAMINE AND DEPOSIT

```
1 ;Priority-7 filter: unless FILT.7 (BIT 7) in O.CNTL is set, you cannot
2 ;actually set the PS to priority 7 using ODT from the keyboard. This
3 ;protects the ability to break.
4
5 171374 105767 176372    2$:   TSTB   O.CNTL          ;ODT control word
6 171400 100407             BMI    3$              ;Do nothing-filter disabled
7 171402 105700             TSTB   R0              ;Intended new PS
8 171404 100005             BPL    3$              ;Do nothing-Priority < 4
9 171406 032700 000100      BIT    #BIT6,R0        ;Check again
10 171412 001402            BEQ    3$             ;Do nothing-Priority < 6
11 171414 042700 000040     BIC    #BITS5,R0      ;LOWER THE BOOM
12 171420 010077 176322    3$:   MOV    R0,@ODTL0C    ;STORE NEW VALUE
13 171424 120227 000012     CMPB   R2,#LF          ;GO on to next location?
14 171430 001407            BEQ    5$             ;Sure, why not.
15 171432 000643            BR    HKBD$          ;GO TO PROMPT
16
17 171434 120227 000012    4$:   CMPB   R2,#LF          ;IS A LF ISSUED
18 171440 001237            BNE    HKBD$          ;NU,ERROR
19 171442 105767 176302    TSTB   ODTFLG         ;IS REGISTER FLAG SET
20 171446 100634            BMI    HKBD$          ;YES, LF NOT PERMITTED
21 171450 112702 000015    5$:   MUVB   #CH,R2        ;TO LINE UP CURSOR
22 171454 004767 000042    CALL   PUTCHR        ;SEND IT
23 171460 062767 000002    ADD    #2,ODIL0C      ;GET ADDRESS OF NEXT LOC.
24 171466 016700 176254    MOV    ODTL0C,R0      ;GET NEXT ADDRESS VALUE...
25 171472 004767 000160    CALL   UCISTK        ;...AND PRINT IT
26 171476 112702 000057    MOVB   #'/,R2        ;SEND A SLASH BEFORE...
27 171502 004767 000014    CALL   PUTCHR        ;...SHOWING THE CONTENTS...
28 171506 000661            BR    LOCDSF        ;...OF THE LOCATION
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 39
MACROUDT-GET AND ECHO CHARACTER

```
1           .SBTTL macroudt-Get and echo character
2
3
4
5
6           ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
7           ;;; CHARACTER INPUT AND ECHO SUBROUTINE ;;;;
8
9
10          ; Get a character from the console keyboard and echo it back
11          ; exactly as received including parity bits if any. Return with
12          ; character in R2, eighth bit (and high byte) zero.
13
14          GETCHR:
15          171510      TSTB    @#RCSRS1           ;CHARACTER READY?
16          171510      105737      177560
17          171514      100375
18          171516      113702      177562      BPL     GETCHR           ;BRANCH IF NOT AND KEEP TRYING
19          171522      MOVBL   @#XBUFS1,R2         ;TRANSFER CHARACTER
20          171522      105737      177564      PUTCHR:
21          171526      100375      TSTB    @#XCSRS1           ;PRINTER READY
22          171530      110237      177566      BPL     PUTCHR           ;NO, TRY AGAIN
23          171534      042702      177600      MOVB    R2,@#XBUFS1         ;YES, XMIT CHARACTER
24          171540      000207      BIC    #^C<17>,R2        ;CLEAR PARITY
                           RETURN             ;CONTINUE
```

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MACRODT-TYPE ASCII STRING

```

1      .SBTTL  macroODI-Type ASCII string
2
3      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5      ;;;;
6      ;;;      MESSAGE PRINT SUBROUTINE      ;;
7      ;;;;
8      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
9      ;;;;;;;;;;;;;;;;;;;
10
11      ; Print message starting with character pointed to by R0 and
12      ; ending with first character with eighth bit set (this character
13      ; is not printed).
14
15 171542          PUTSTR:
16  i71542  112002      MOVB    (R0)+,R2          ;GET ASCII CHAR
17  i71544  100413      BMI     DONE             ;IS IT THE END MARK?
18  i71546  004767  177750      CALL    PUTCHR        ;NO, PRINT IT
19  i71552  000773      BR     PUTSTK          ;MORE
20
21      ;ENTRY FOR CARRIAGE RETURN
22
23 171554          PUTCLF:
24  i71554  112702  000015      MOVB    #CR,R2          ;PRINT CR
25  i71560  004767  177736      CALL    PUTCHR        ;FALL THRU AND PRINT LF
26
27      ;ENTRY FOR LF
28
29 171564          PUTLF:   MOVB    #LF,R2          ;PRINT LF
30  i71570  004767  177726      CALL    PUTCHR
31  i71574  000207      DONE:   RETURN

```

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MACROUDI-GET OCTAL DIGITS

```
1          .SBTTL macroUDI-Get octal digits
2
3
4
5
6          ;;;;;
7          ;;;;;
8          ;;;;;
9          ;;;;;
10         ;;;;;
11         ;;;;;
12         ;;;;;
13         ;;;;;
14         ;;;;;
15
16 171576
17 171576 005000
18 171600
19 171600 004767 177704
20 171604 120227 000015
21 171610 001412
22 171612
23 171612 162702 000070
24 171616 062702 000010
25 171622 103007
26 171624 006300
27 171626 006300
28 171630 006300
29 171632 050200
30 171634 000761
31
32 171636 000241
33 171640 000207
34
35 171642 062702 000060
36 171646 000261
37 171650 000207

          ONENUM:           CLR     R0          ;CLEAR ACCUMULATOR
          NEXNUM:           CALL    GETCHR        ;GET DIGIT OR TERMINATOR
                           CMPB   R2,#CR      ;CLEAR CARRY AND RETURN
                           BEQ    SRET         ;IF <CR> WAS TYPED
          GETNUM:           SUB    #8,R2        ;CONVERT TO BINARY...
                           ADD    #8-^0,R2    ;...AND TEST IF OCTAL OR NOT
                           BCC    NOCT        ;NOT VALID DIGIT.
                           ASL    R0          ;MAKE ROOM FOR NEW DIGIT
                           ASL    R0          ;DITTO
                           ASL    R0          ;DITTO
                           BIS    R2,R0        ;PUT IT IN PLACE
                           BR    NEXNUM       ;GET NEXT
          SRET:             CLC
                           RETURN
          NOCT:             ADD    #0,R2        ;RESTORE ASCII BECAUSE...
                           SEC
                           RETURN
                           ;...POSSIBLE COMMAND
                           ;CONTINUE
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 42
MACROUDT=OCTSTR--TYPE BINARY IN R0 AS ASCII

```
1          .SBTTL  macroUDT=OCTSTR--type binary in R0 as ASCII
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;;
6          ;;;      NUMERIC OUTPUT ROUTINE      ;;;;
7          ;;;;
8          ;;;;
9          ;;;;
10         ; Prints, as a 6-digit octal integer, the value of the binary
11         ; number in R0.
12
13
14 171652  004767  177676    OCTST0: CALL    PUTCLF      ;NEED CRLF AT ODT ENTRY
15 171656
16 171656  010046          MOV     R0,-(SP)      ;SAVE VALUE
17 171660  012746  000006          MOV     $6,-(SP)      ;NU. OF CHARACTERS
18 171664  005002          CLR     R2          ;OUTPUT HOLD
19 171666  006100          5$:    ROL     R0          ;SHIFT MSB INTO LSB
20 171670  006102          ROL     R2          ;   *   *   *   *   *
21 171672  062702  000060          ADD     #0,k2      ;MAKE A DIGIT
22 171676  004767  177620          CALL    PUTCHR      ;OUTPUT A CHARACTER
23 171702  005316          DEC     (SP)        ;COUNT
24 171704  001406          BEQ     10$        ;DONE
25 171706  005002          CLR     R2          ;NEXT
26 171710  006100          ROL     R0          ;GET NEXT DIGIT INTO
27 171712  006102          ROL     R2          ;R2
28 171714  006100          ROL     R0          ;FIRST TWO BITS
29 171716  006102          ROL     R2          ;   *   *   *   *
30 171720  000762          BR     5$          ;CONTINUE
31 171722  005726          10$:   TST     (SP)+      ;CLEAR COUNT
32 171724  012600          MOV     (SP)+,R0      ;ORIGINAL VALUE
33 171726  000207          RETURN
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 43
MACROODT-OUTPUT MESSAGES

```
1          .SBTTL MacroODT-Output messages
2
3
4
5
6          ;;;;;
7          ;;;;;
8          ;;;;;
9          ;;;;;
10         ;;;;;
11
12 171730    077      .NLIST BEX
13 171731    015      MSGQ:  .ASCII  "?"
14           012      MSGS:  .ASCII  <CR><LF>"@<200>      ; ERROR MESSAGE
15           100      .EVEN
16
17          .LIST BEX
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 44
 DIAGNOSTICS-FOR SLU2 AND PPI

```

1          .SBT1L DIAGNOSTICS-for SLU2 and PPI
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;;
6          ;;;      DIAGNOSTIC MODULE      ;;;
7          ;;;;
8          ;;;;
9          ;;;;
10         ; Diagnose PPI in mode 0 with loopback connectors installed.
11         ; Diagnose SLU2 internal circuitry (maintenance mode) and
12         ; SLU2 drivers/receivers (with external loopback connector).
13
14         ; List of error bit definitions to return to user.
15
16
17 171736 000100          .WORD   E.EXT
18 171740 000010          .WORD   E.INT
19 171742          ERBIT:
20
21         ; List of masks to put in XCSR$2. Perform internal loopback
22         ; test first, then external loopback test.
23
24 171742 000000          .WORD   0
25 171744 000002          .WORD   XC.PBE           ; 300 baud
26 171746 000006          .WORD   XC.PBE ! XC.MNT    ; 300 baud and maintenance
27 171750          INITS:
28
29         ; List of pattern bytes to loop around.
30         ; All bits on, alternating bits, all bits off.
31         ; Note: last byte must be 0.
32
33 171750      377      252      000  PATERN: .BYTE  377, 252, 0
34                      .EVEN
35
36                      .ENABL  LSB
37 171754          DIAGNO:
38 171754 012737 000221 176206  MOV    #MODE,@#PP.CWR      ; set proper PPI mode- LED
39 171762 012737 000017 176206  MOV    $LEDOFF,@#PP.CWR    ; must immediately be turned
40                      ; off as a consequence.
41
42 171770 005000          CLR    R0                  ; assume success
43
44          ; Perform parallel port diagnostic
45
46 171772 005001          CLR    R1                  ; R1 = loop pattern
47 171774 000405          BR     AROUND2             ; SKIP OVER THE ENTRY POINT

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 45
HARDWARE ENTRY POINT

```
1                               .SBTTL HARDWARE ENTRY POINT
2
3      172000                  .=172000
4 172000          START:::    JMP      PWR$UP
5 172000  000167  176254
6 172004          RESTAR:::  JMP      R.$TRT
7 172004  000167  176026
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-UC1-81 22:56:27 PAGE 46
 DIAGNOSTICS-CONTINUED

```

1
2 172010          AROUND2:
3 172010 110137 176202      1$:  MOVB   R1, @#PP.B      ; send it out port B
4 172014 123701 176200      CMPB   @#PP.A, R1      ; check input in port A
5 172020 001402          BEQ    2$                  ; branch if same
6 172022 052700 000001      BIS    #E.PAR, R0      ; else set error flag
7 172026 077110          S0B    R1, 1$            ; loop for all values
8
9
10
11 172030 012702 171742      MOV    #ERRB11, R2      ; R2->error flags
12 172034 012701 176540      MOV    #XCSR$2, R1      ; R1 -> SLU2
13 172040 016146 000002      MOV    2(R1), -(SP)    ; ignore garbage, make temp
14 172044 012704 171750      MOV    #INIT$, R4      ; R4->initial XCSR value
15 172050 014461 000004      3$:  MOV    -(R4), 4(R1)  ; init XCSR
16 172054 001436          BEQ    11$                 ; branch if done
17 172056 005742          TST    -(R2)                ; R2->next error flag
18 172060 012716 000010      MOV    #8., (SP)        ; (SP)=baud rate counter
19 172064 012703 171750      MOV    #PATTERN, R3     ; R3->patterns
20 172070 005005          CLR    R5                  ; init timeout counter
21 172072 105761 000004      4$:  TS1B   4(R1)        ; loop pattern around
22 172076 100402          BMI    7$                  ; branch if ready
23 172100 077504          SUB    R5, 6$            ; else bump timeout counter
24 172102 000422          BR     10$                 ; branch if timeout
25
26 172104 111361 000006      7$:  MOVB   (R3), 6(R1)  ; initialize timeout counter
27 172110 005005          CLK    R5
28 172112 105711          8$:  TSTB   (R1)
29 172114 100402          BMI    9$                  ; branch if ready
30 172116 077503          S0B    R5, 8$            ; else bump timeout counter
31 172120 000413          BR     10$                 ; branch if timeout
32
33 172122 126113 000002      9$:  CMPB   2(R1), (R3)  ; come back OK?
34 172126 001010          BNE    10$                 ; no, set error bit & exit
35 172130 105723          TSTB   (R3)+               ; done all bit patterns?
36 172132 001356          BNE    5$                  ; no
37 172134 005316          DEC    (SP)                ; yes, done all bauds?
38 172136 001744          BEQ    3$                  ; yes
39 172140 062761 000010 000004      ADD    #10, 4(R1)  ; no, to next baud rate
40 172146 00074b          BR     4$                  ; set error bit
41
42 172150 051200          10$:  BIS    (R2), R0      ; rid of temp
43 172152 005726          11$:  TST    (SP)+        ; print error flags
44 172154 004767 177472      CALL   OC1STO
45 172160 000167 176516      JMP    KbDS
46          .DSABL LSB

```

KXT11-A2 1K FIRMWARE MACRU V04.00 5-OCT-81 22:56:27 PAGE 47
BOOTS-DESCRIPTION

```
1                      .SBTTL BOOTS-Description
2
3                      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4                      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5                      ;;;;;
6                      ;;; BOOTSTRAP MODULE ;;;;;
7                      ;;;;;
8                      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
9                      ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
10                     000000          .REPT   0
11
12
13 This is a short bootstrap program designed to handle floppy disks or TU58
14 tape cassettes in either our standard bootable format or in the stand-alone
15 volume format (RT-11 ".SAV"-structured files).
16
17 The bootstrap sequence is as follows:
18
19 1. Since entry is effected by typing D in response to ODT prompt, get next
20    character (D, X or Y). Get optional device number next (default is 0).
21
22 2. If floppy boot is selected:
23
24     a. Attempt to read 512 bytes from specified unit of the floppy
25        disk, starting from logical block zero, into memory locations
26        starting at 0 at the density of the medium present in the
27        drive at the time.
28
29     b. If the drive is not ready or does not contain a bootable
30        medium, go back to ODT.
31
32 3. If TU58 boot is selected, read the first block from the selected
33    drive into locations starting at 0.
34
35 4. If the first byte read into RAM is 240 octal, jump to it. If the
36    first byte is 260 octal, execute the stand-alone volume loader,
37    using the selected device as input.
38
39                      .ENDR
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 48
BOOTS-DESCRIPTION

```
1 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
2 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
3 ;;; EQUATES USED ONLY BY BOOTSTRAPS ;;;;
4 ;;; ;;;;
5 ;;; ;;;;
6 ;;; ;;;;
7 ;;; ;;;;
8 ;;; ;;;;
9 .SBITL BOOTS-RX Controller Definitions
10
11 ; RX01/RX02 (RXV11,RXV21) Register Definitions
12
13     177170 ;Control and Status
14     177172 ;Data Buffer
15
16 ; RX Control and Status Bits
17
18     100000 ;Error
19     040000 ;Initialize controller
20     030000 ;Extended address bits
21     004000 ;1 if RX02; 0 if RX01
22     003000 ;Unused bits
23     000400 ;Density (1=double,0=single)
24     000200 ;Transfer function
25     000100 ;Interrupt enable
26     000040 ;Done
27     000020 ;Unit select
28     000016 ;Function select
29     000001 ;GO
30
31 ; RX Function Codes (in RX$SFN) with GO bit preset
32
33     000001 ;Fill buffer
34     000003 ;Empty buffer
35     000005 ;Write sector
36     000007 ;Read sector
37     000011 ;Set media density
38     000013 ;Read status
39     000015 ;Write sector with deleted data
40     000017 ;Read error code
41
42 ; RX Error Codes
43
44     000400 ;Unit selected
45     000200 ;Drive ready
46     000100 ;Deleted data
47     000040 ;Drive density
48     000020 ;Density error
49     000004 ;Initialize done
50     000001 ;CRC error
51
52 ; Miscellaneous Definitions
53
54     000010 ;Number of retries
55
56 .SBTTL BOOTS-TU58 Definitions and Protocol Equates
57
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 48-1
BOOTS-TU58 DEFINITIONS AND PROTOCOL EQUATES

58 ; Absolute address definitions
59
60 000002 FILNAM = 000002 ;Address of RAD50 filename for
61 001000 DIRBUF = 001000 ;stand-alone program loading
62 ;Start of 512. word buffer used
63 ; for RT-11 directory operations
64 ; in stand-alone loading
65
66 ; TU58 Address definitions
67
68 176540 TISCSR = RCSR\$2 ;DL receiver control and status
69 176542 TISBFR = RBUF\$2 ;DL receiver data buffer
70 176544 TO\$CSR = XC\$RS2 ;DL transmitter control and status
71 176546 TO\$BFR = XBUF\$2 ;DL transmitter data buffer
72
73
74 ; TU58 Radial Serial Protocol codes
75
76 ; Flag Byte Definitions:
77
78 000001 RSSDAT = ^B<000001> ;Data message flag
79 000002 RSSCTL = ^B<00010> ;Control message flag
80 000004 RSSINT = ^B<00100> ;Initialize flag
81 000020 RSSCON = ^B<10000> ;Continue flag
82 000023 RSSXUF = ^B<10011> ;XOFF
83
84 ; Control packet operation codes:
85
86 000000 RSNOP = 0. ;No-operation
87 000001 RSINIT = 1. ;Initialize
88 000002 RSREAD = 2. ;Read operation
89 000003 RSWRIT = 3. ;write operation
90 000004 RSCUMP = 4. ;Compare (NOP on TU58)
91 000005 RSPOSI = 5. ;Position operation
92 000006 RSABRT = 6. ;Abort (NOP on Tu58)
93 000007 RSDIAG = 7. ;Diagnose
94 000010 RSGETS = 8. ;Get status
95 000011 RSSSTS = 9. ;Set status (NOP on TU58)
96 000012 RSSETC = 10. ;Get characteristics
97 000013 RSSSETC = 11. ;Set characteristics (NOP on TU58)
98 000100 RSEND = ^B<01000000> ;*END message
99
100 ; END packet success codes:
101
102 000000 SSNORM = 0. ;Normal success
103 000001 SSRETR = 1. ;Success but with retries
104 17776 SSPART = -2. ;Partial operation (end of medium)
105 177770 SSUNIT = -8. ;Invalid unit number
106 177767 SSCART = -9. ;No cartridge
107 177765 SSWPRT = -11. ;Cartridge write protected
108 177757 SSDCHK = -17. ;Data check error
109 177740 SSEEK = -32. ;Seek error (block not found)
110 177737 SSMUTR = -33. ;Motor stopped
111 177720 SSUPCD = -48. ;Invalid operation code
112 177711 SSRECN = -55. ;Invalid record number
113
114 .SBTTL BOOTS-RT11 Definitions and Equates

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 48-2
BOUTS-RT11 DEFINITIONS AND EQUATES

```
115  
116 ; RT-11 Directory Structure Definitions  
117  
118    001000      SEGALO = DIRBUF          ;Number of segments allocated  
119    001002      NXISSEG = DIRBUF+2        ;Number of next logical segment  
120    001004      HGHSEG = DIRBUF+4        ;Highest segment in use  
121    001006      XTRBYT = DIRBUF+6        ;Number of extra bytes per entry  
122    001010      STRBLK = DIRBUF+10       ;Starting block# for files  
123  
124    00001e      ENTSIZ = 7*2            ;Size of a directory entry  
125    000010      D_FLEN = 10             ;Offset to file length in entry  
126    000400      IENTAS = 000400         ;Flag for tentative file entry  
127    001000      EMPTYS = 001000         ;Flag for empty area entry  
128    002000      PERMFS = 002000         ;Flag for permanent file  
129    004000      ENDSGS = 004000         ;Flag for end of segment  
130  
131 ; RT-11 System Communications Area Definitions  
132  
133    000040      RTSSTA = 000040          ;Start address for program  
134    000042      RTSISP = 000042          ;Initial stack pointer  
135    000044      RT$JSW = 000044          ;Job status word  
136    000046      RTSUSR = 000046          ;USR load address  
137    000050      RT$HGH = 000050          ;Job high memory limit  
138    000052      R1SEMT = 000052          ;(Byte) EMT error code  
139    000053      RTSUER = 000053          ;(Byte) User error code  
140    000054      RTSRMN = 000054          ;Base address of resident monitor  
141    000056      RT$FCH = 000056          ;(Byte) Console fill character  
142    000057      RT$FCT = 000057          ;(Byte) Console fill count
```

KXT11-A2 1K FIRMWARE MACKO V04.00 5-UC1-81 22:56:27 PAGE 49
BOUTS-PROGRAM ENTRY POINT

```
1 .SBTTL BOUTS-Program entry point
2
3
4
5
6 ;;; BOOTSTRAP INITIALIZATION AND COMMAND INTERPRETER ;;;;
7
8
9
10
11 ; A "D" was entered in response to the UDT prompt, so we get
12 ; here and expect "D","X" or "Y" next, followed by a CR or a
13 ; unit number. We set bits up in B.CNTL as follows:
14
15 ; BIT 7: 0 = TU58
16 ; 1 = RX01/02
17 ; Used by stand-alone volume loader to select proper
18 ; read routine.
19 ; BIT 0: Device number
20
21 ; Note: if no memory was found at 000000, bit 15 of B.CNTL,
22 ; called "NO.LOW" will be set and the bootstraps will be
23 ; disabled.
24
25 172164
26 172164 012737 000072 176544
27
28 BOUTS:: MOV #TUBAUD, @*T08CSR ;Set TU58 Baud Rate
29
30 172172
31 172172 010667 175566
32
33 172176 005004
34 172200 004767 177304
35 172204 120227 000104
36 172210 001412
37 172212 012704 000200
38 172216 020227 000130
39 1/2222 001405
40 1/2224 020227 000131
41 1/2230 001402
42 172232 ABORT <Illegal device name>
43
44 172236 004767 177246
45 172242 022702 000015
46 172246 001410
47 172250 162702 000060
48 172254 001405
49 1/2256 005302
50 1/2260 001402
51 1/2262 ABORT <Illegal unit number>
52
53 172266 005204
54 172270 110467 175474
55 172274 005767 175470
56 172300 100002
57
```

;Permit HALTs and BREAKS
; by making IN.USR non-zero
;Assemble new B.CNTL here
;Keyboard character in R2
;DD = TU58 cassette
;R4 is clear for DD
;R4 bit 7 is set for DX, DY
;DX = RX01 or RX02
;DY = RX01 or RX02, the code's
; same- it knows both den-
; sities, DMA, non-DMA
;Get device number or CR
;Is it CR?
;CR means drive 0
;Drive 0?
;Yup.
;Drive 1?
;Yes, skip the ABORT
;For unit 1.
;Set device, unit information.
;Test NO.LOW
;we have low memory
;we don't, so go to UDT

KXT11-A2 1K FIRMWARE MACRU V04.00 5-OCT-81 22:56:27 PAGE 49-1
-----> HALI AT PC=172264 INDICATES "ILLEGAL UNIT NUMBER"

```
58 172302          ABORT <No low memory, can't boot>
59
60          ; Before proceeding, we set up the bus timeout trap vector, enable
61          ; trap to 4 emulation and reset the bus. We do a delay (see
62          ; explanation below) and set up the stack so the stand-alone booter and
63          ; device primary bootstraps can get the information they need passed
64          ; to them in R0 and R1 (see CHK240, below).
65
66 172306 012737 172370 000004 4$:    MOV    #BADBOT,e#4      ;If we time out, we want to re-
67 172314 012737 000300 000006      MOV    #PRIO,0#6      ;initialize everything.
68 172322 000005      RESET           ;For now, init. the bus.
69
70          ; Note: the previous instruction also screws up some devices
71          ; which perform a long initialization sequence, such as RX02's,
72          ; which do an automatic boot from drive 0. The long delay below
73          ; is necessary in order to assure drive 1 is ready if a boot
74          ; is desired from it.
75
76 172324          DELAY   R0,R1,9.      ;Delay 2 seconds
77 172336 012706 167644      MOV    #$$STACK,SP      ;Initialize the stack.
78 172342 010667 175430      MOV    SP,TRAP4       ;Set up trap-to-4 emulation
79
80 172346 012716 037776      MOV    #37776,(SP)    ;by making TRAP4 non-zero
81
82 172352 010402          MOV    R4,R2         ;Some boots need a memory-top
83 172354 042702 177776      BIC    *C<DEVENUM>,R2  ;address here, so 8k will do
84 172360 010246          MOV    R2,-(SP)     ;Boot control word here
85
86 172362 105704          TSTB   R4         ;Want only unit no. in R2
87 172364 100405          BMI    RXBOOT        ;And we'll save it too.
88 172366 000436          BR    TUBOOT        ;Bit 7 set for RX01/02
89
90 172370          BADBOT:          MOV    #$$STACK,SP      ;Go to floppy boot
91 172370 012706 167644      ABORT          ;Restore the stack
92 172374
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 50
BOOTS-RX01/RX02 BOOTSTRAP

```
1          .SBTTL BOOTS-RX01/RX02 Bootstrap
2
3          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5          ;;;;
6          ;;;      FLOPPY BOOTSTRAP      ;;;;
7          ;;;;
8          ;;;;;
9          ;;;;;
10         ;;;;;
11         ; This routine will bootstrap either floppy drive, at the density of the
12         ; media mounted in that drive.
13
14 172400 RXBOOT:
15 172400 012746 177170    MOV    #RXCS,-(SP)      ;Need floppy CSR for CHK240
16 172404 005737 177170    TST    @#RXCS        ;If not there, time out via 4
17 172410 000240    NOP
18 172412 012701 001000    MOV    #512.,R1      ;Byte count
19 172416 005000    CLR    R0          ;Starting block number
20 172420 005004    CLR    R4          ;RAM buffer address = 000000
21 172422 004767 000402    CALL   DREAD       ;LOAD IT ALL IN
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 51
BOOTS-DISTINGUISHING TYPE OF BOOT BLOCK

```
1          .SBTTL BOOTS-Distinguishing type of boot block
2
3
4
5
6          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
7          ;;;;;
8          ;;;;;
9          ;;;;;
10         ;;;;;
11
12         ; The CHK240 routine will repeat powerup sequence if location 0 does not
13         ; contain a valid secondary bootstrap (i.e., does not have a 240 or 260
14         ; in it). It starts execution of the booted program if there's a 240,
15         ; and goes to the stand-alone program loader if there's a 260.
16
17 172426      CHK240:
18 i72426 022737 000240 000000    CMP    #240,@#0           ;Did we read a valid bootstrap?
19 i72434 001410                 BEQ    1S
20 i72436 022737 000260 000000    CMP    #260,@#0           ;Stand-alone volumes start with 260
21 i72444 001447                 BEQ    STANDB            ;Restore wiped-out vectors
22 i72446 004767 175766          CALL   VECSET
23 i72452                 ABORT  <No boot block on volume>
24
25 i72456 012601                 1S:   MOV    (SP)+,R1          ;Unit CSR address
26 i72460 012600                 MOV    (SP)+,R0          ;Unit number
27 i72462 005007                 CLR    PC               ;Standard secondary boots
```

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BOOTS-TU58 BOOTSTRAP

```
1 .SBTTL BOOTS-TU58 Bootstrap
2
3 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
5 ;;;;
6 ;;; TU58 TAPE CASSETTE BOOTSTRAP ;;;;
7 ;;;;
8 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
9 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
10
11 .ENABL LSB
12 172464 012746 176540 TUBOOT:
13 172464 012746 176540 MOV #TISCSR,-(SP) ;CHK240 wants TU58 CSR
14 172470 012701 176544 MOV #TUSCSR,R1 ;R1 -> output CSR for TU58 serial line
15 172474 005003 CLR R3 ;Set R3 = 0 (Two NULLs)
16 172476 005211 INC @R1 ;Start transmitting BREAK to TU58
17 172500 004767 001132 CALL CH8OUT ;Send eight NULLs
18 172504 105711 18: TSTB @R1 ;Is transmitter ready again yet?
19 172506 100376 BPL 1$ ;If PL no - wait
20 172510 042711 000001 BIC #XC.BRK,@R1 ;Else stop sending BREAK now
21 172514 012703 MOV (PC)+,R3 ;Get two INIT commands for TU58
22 172516 004 004 .BYTE RSSINT,kSSINT ;And transmit them
23 172520 004715 CALL @R5 ;Dump any garbage char in TISBUF
24 172522 005741 TST -(R1) ;Is character available from the TU58?
25 172524 105737 176540 28: TSTB @#TISCSR ;If PL, no - wait in loop
26 172530 100375 BPL 2$ ;If so, was it a CONTINUE flag?
27 172532 121127 000020 CMPB @R1,#kSSCON ;If EQ, yes- go ahead
28 172536 001402 BEQ 3$ ;ABORT <TU58 initialization error>
29 172540 ABORT <TU58 initialization error>
30
31 ; TU58 is now initialized. Prepare to read block #0.
32
33 172544 005000 3$: CLR R0 ;Block number = 0
34 172546 012701 001000 MOV #S12.,R1 ;Byte count = one block
35 172552 004767 000212 CALL READZU ;Attempt to read the block
36 172556 100323 BPL CHK240 ;If PL, read was successful
37 172560 ABORT <TU58 block 0 read error>
38 .DSABL LSB
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 53
 BOOTS-STAND-ALONE VOLUME BOOTSTRAP

```

1          .SBTTL BOOTS-Stand-alone volume bootstrap
2
3
4
5
6          STAND-ALONE-VOLUME BOOTSTRAP
7
8
9
10
11 ; This routine loads stand-alone programs (assumed to be in RT-11 .SAV
12 ; file format) from an RT-11 file structured TUS8 cartridge. It is
13 ; invoked if the first word in block 0 of the cartridge is a 260.
14
15 172564
16 172564 012700 000001
17 172570 006300
18 172572 022020
19
20 172574 012701 002000
21 172600 012704 001000
22 172604 004767 000162
23 172610 100002
24 172612
25 172616 012704 001010
26
27 172622 012400
28 172624 010403
29 172626 032724 002000
30 172632 001010
31 172634 022744 004000
32
33 172640 001015
34 172642 013700 001002
35 172646 001350
36 172650
37
38 172654 012705 000002
39 172660 022425
40 172662 001004
41 172664 022425
42 172666 001002
43 172670 022425
44 172672 001410
45
46 172674 010304
47 172676 062704 000010
48 172702 062400
49 172704 022424
50 172706 063704 001006
51 172712 000744

STANDB:
      MOV    #1,R0          ;Set directory segment #1
1$:   ASL    R0          ;Two blocks per segment
      CMP    (R0)+,(R0)+  ;Add 4 to R0, as directory starts
                          ;in block#6
      MOV    #1024,,R1      ;Prepare to read two blocks
      MOV    #DIRBUF,R4      ;into the directory buffer
      CALL   READU          ;Read the segment
      BPL   2$              ;If PL, read was successful
      ABORT <Directory read error>
      MOV    #STKBLK,R4      ;Else prepare to pick up
                          ;starting block
      MOV    (R4)+,R0          ;R0 = starting block for files
      3$:   MOV    R4,R3          ;Save pointer to current entry
      BIT    #PERMS,(R4)+    ;Is this a permanent file?
      BNE   4$              ;If bit set, yes - check if it matches
      CMP    #ENDSGS,-(R4)    ;Else is this the end-of-segment
                          ;marker?
      BNE   5$              ;If NE, no - go skip this entry
      MOV    #NXTSEG,R0      ;Else get number of next segment
      BNE   1$              ;If NE, there is one - go read it
      ABORT <file not found>

      MOV    #FILNAM,R5      ;Point to RAD50 name of desired file
      CMP    (R4)+,(R5)+    ;Check file name, first word
      BNE   5$              ;if NE not desired file
      CMP    (R4)+,(R5)+    ;...Check second word of filename
      BNE   5$              ;if NE not desired one
      CMP    (R4)+,(R5)+    ;...Finally, check extension
      BEQ   LOAD             ;If EQ, got it - go load this
                          ;one into memory
      MOV    R3,R4          ;Get entry pointer back
      ADD    #D.FLEN,R4      ;Advance to file size of entry
      ADD    (R4)+,R0          ;Update current file base
      CMP    (R4)+,(R4)+    ;And skip to next file entry
      ADD    @#XTRBYT,R4      ;Plus any extra bytes in each entry
      BR    3$              ;Continue file search

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 54
BOOTS-LOAD STAND-ALONE PROGRAM FILE

1 .SBTTL BOOTS-Load Stand-Alone Program File
2
3 172714 011401 LOADS: MOV @R4,R1 ;R1 = size of file in blocks
4 172716 000301 SWAB R1 ; * 256. = word count
5 172720 006301 ASL R1 ; * 2 = byte count
6 172722 004767 000042 CALL READZU ;read the program file into memory
7 172726 100002 BPL 1\$;If HI, error in read-ABORT
8 172730 ABORT <Stand-alone file read error>
9 172734 013705 000040 1\$: MOV @#RTSSSTA,R5 ;Get program start adrs
10 172740 032705 000001 BIT #1,R5 ;Is adrs even?
11 172744 001402 BEQ STARTS ;If EQ yes - okay
12 172746 ABORT <illegal transfer address>
13
14 172752 STARTS:
15 172752 012601 MOV (SP)+,R1 ;Pass the CSR address
16 172754 112600 MOVB (SP)+,R0 ;Get unit number booted
17 172756 013706 000042 MOV @#RTSISP,SP ;Load program's stack pointer
18 172762 005067 175010 CLR TKAP4 ;Disable trap to 4 feature
19 172766 000115 JMP @R5 ;Go start program execution
20
21 172770 READZU:
22 172770 005004 CLR R4 ;Load at 0
23 172772 016602 000004 READU: MOV 4(SP),R2 ;Get unit number
24 172776 000407 BR AROUND ; SKIP OVER THE ENTRY POINT

KXT11-A2 1K FIRMWARE MACKD V04.00 5-OCT-81 22:56:27 PAGE 55
173000G ENTRY POINT

```
1                               .SBTIL 173000G ENTRY POINT
2
3      173000                 .=173000
4 173000
5 173000 106427 000340          ST173::    MTPS    #PR17      ;Can't assume anything here.
6 173004 000005                RESET
7 173006 005000                CLR     R0      ;But PWRSUP usually does.
8 173010 077001                S08     R0,.     ;DELAY for the sake of DLAKT.
9
10 173012 000167 175242         JMP     PWRSUP   ;(Maint. bit cleared by RESET
                                         ;just a little too long).
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 56
BOOTS-CONTINUED

1					.SBTTL BOOTS-Continued
2	173016				
3	173016	105767	174746	TSTB	B,CNTL
4	173022	100402		BML	DREAD
5	173024	000167	000370	JMP	TREAD

AROUN3:
;Bit 7 set for RX01/RX02
;Read from tape

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 57
BOOTS-RX01/RX02 READ ROUTINES

```
1 .SBTTL BOOTS-RX01/RX02 Read routines
2
3 ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
4 ;;;;
5 ;;;;
6 ;;;; FLOPPY DISK READ ROUTINES ;;;;
7 ;;;;
8 ;;;;
9 ;;;;
10 ; with registers set up as below, read the appropriate number of
11 ; full sectors from the floppy, at either density, with either
12 ; RXV21 DMA or RXV11 Programmed I/O interface.
13 ;
14 ; R0: Starting block number for transfer.
15 ; K1: Byte count for transfer
16 ; K2: Unit number
17 ; K4: Address of buffer to receive data
18 ;
19
20 .ENABL LSB
21 173030 010446 DREAD: MOV R4,-(SP) ;Save buffer address
22 173032 010046 MOV R0,-(SP) ;Save starting LBN
23 173034 010146 MOV R1,-(SP) ;Save byte count
24
25 ; Check status and media density of selected drive
26
27 173036 012701 177172 MOV #RXDB,R1 ;Set up R1 for benefit of RXGU
28 173042 005000 CLR R0 ;Initialize current unit/density word
29 173044 006002 ROR R2 ;Bit 0 set = unit 1
30 173046 103002 BCC 1$ ;Set unit 1
31 173050 052700 000020 BIS #RXSSUN,R0 ;Start a read status operation
32 173054 004567 000312 1$: JSR R5,RXGU ;to determine status and density
33 173060 000013 .WORD RXSRST
34 173062 111102 MOVB @R1,R2 ;Pick up low byte of status
35 173064 100402 BMI 2$ ;If PL, drive not ready
36 173066 ABORT <Floppy drive not ready>
37 173072 032702 000040 2$: BIT #RXESDN,R2 ;Check media density
38 173076 001411 BEQ 3$ ;If EQ, single density
39
40 ; Double density.
41 ; Logical sector number = logical block number * 2
42 ; Sector count = byte count/256.
43
44 173100 052700 000400 BIS #RXSSDE,R0 ;Set double density in command
45 173104 012602 MOV (SP)+,R2 ;Byte count
46 173106 000302 SWAB R2 ;Divide by 256
47 173110 012603 MOV (SP)+,R3 ;LBN
48 173112 006303 ASL R3 ;Multiply by 2
49 173114 012704 000200 MOV #128.,R4 ;#ords per sector
50 173120 000410 BK 4$ ;Single density.
51 ; Logical sector number = logical block number * 4
52 ; Sector count = byte count/128.
53
54 3$: MOV (SP)+,R2 ;Byte count
55 SWAB R2 ;Divide by 256
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 57-1
 -----> HALT AT PC=173070 INDICATES "FLUFFY DRIVE NOT READY"

```

58 173126 006302          ASL     R2                   ;And multiply by 2
59 173130 012603          MOV     (SP)+,R3             ;LBN
60 173132 006303          ASL     R3
61 173134 006303          ASL     R3                   ;Multiply by 4
62 173136 012704 000100    MUW    #64.,R4             ;Words per sector
63
64                               ; Set up stack as follows:
65                               ; 0(SP) = Logical Sector Number
66                               ; 2(SP) = Sector count
67                               ; 4(SP) = words per sector
68                               ; 6(SP) = Buffer address
69
70 173142 010446          4$:    MOV     R4,-(SP)           ;Words per sector
71 173144 010246          MOV     R2,-(SP)           ;Sector count
72 173146 010346          MOV     R3,-(SP)           ;Logical Sector Number
73
74                               ; Start the read operation.
75                               ; This is the top of the loop.
76
77 173150 004567 000216    5$:    JSK     R5,RXGO           ;Start a sector read
78 173154 000007          .WORD   RXSRED
79
80                               ; Convert Logical Sector Numbers to Physical tracks and sectors.
81
82 173156 011603          MOV     @SP,R3              ;Get Logical Sector Number
83 173160 012702 000010    MOV     #8.,R2              ;Loop count
84 173164 022703 006400    6$:    CMP     #26.*200,R3        ;Does 26 go into dividend?
85 173170 101002          BHI    7$                  ;Branch if not, C clear (BHI => BCC)
86 173172 062703 171400    ADD     #-26.*200,R3        ;Subtract 26 from dividend (C set)
87 173176 006103          RUL    R3                  ;Shift dividend and quotient
88 173200 005302          DEC     R2                  ;Decrement loop count
89 173202 003370          BGT    6$                  ;Branch till divide done
90 173204 110302          MOVB   R3,R2              ;Copy track number
91 173206 105003          CLR8   R3                  ;Remove track number from remainder
92 173210 000303          SWAB   R3                  ;Get remainder
93 173212 022703 000014    CMP     #12.,R3              ;C=1 if 13<=R3<=25, else C=0
94 173216 006103          ROL    R3                  ;Sector#2 (2:1 interleave)
95                               ;[+1 (C) if sector 13-25]
96 173220 006302          ASL     R2                  ;Double the track number
97 173222 060203          ADD     R2,R3              ;Skew the sector
98 173224 060203          ADD     R2,R3              ; by adding in
99 173226 060203          ADD     R2,R3              ; 6 * track number
100 173230 006202         ASR     R2                  ;Undouble the track number
101 173232 005202         INC     R2                  ; and make it 1-76 (Skip track 0
102                               ; for ANSI)
103 173234 162703 000032    8$:    SUB    #2b.,R3              ;Put sector
104 173240 002375          BGE    8$                  ; into range
105 173242 062703 000033    ADD    #27.,R3              ; 1-26
106
107                               ; Read the sector
108
109 173246 010311          MOV     R3,@R1              ;Set sector number
110 173250 004514          JSK    R5,@R4              ;
111 173252 010211          MOV     R2,@R1              ;Set track number
112 173254 004514          JSR     R5,@R4              ;Perform a sector read
113 173256 100002          BPL    9$                  ;If MI, error
114 173260                 ABORT <floppy read error>

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 58
 -----> HALT AT PC=173262 INDICATES "FLUPPY READ ERROR"

```

1          ; Empty RXV11/RXV21 buffer into RAM
2
3 173264  004567  000102      9$:   JSR     R5,R4G0      ;Start empty buffer function
4 173270  000003                .WORD   RXSEMPF      ; and wait for TR
5 173272  032737  004000  177170    B11    #RXSSU2,0#RXCS  ;Is DMA available?
6 173300  001407                BEQ     10$      ;If EQ no - handle as RX01
7
8          ; RX02 DMA Operation
9
10 173302 016611  000004        MOV     4(SP),@R1      ;Else load word count
11 173306 004514                JSR     R5,@R4      ;Wait for TR
12 173310 016611  000006        MOV     6(SP),@R1      ;And load current bus address
13 173314 004514                JSR     R5,@R4      ;wait for DONE
14 173316 000410                BR     12$      ;
15
16          ; RX01 Programmed I/O Operation
17
18 173320 016603  000004      10$:  MUV    4(SP),R3      ;Get word count
19 173324 006303                ASL     R3      ;Turn word count into byte count
20 173326 016602  000006      11$:  MOV    6(SP),R2      ;Get starting bus address
21 173332 111122                MOVB   @R1,(R2)+    ;Move one byte from buffer to memory
22 173334 004514                JSR     R5,@R4      ;Wait for TR or DONE
23 173336 077303                SOB    R3,11$      ;Loop for all bytes in first sector
24
25          ; Loop back if not yet finished
26
27 173340 016603  000004      12$:  MOV    4(SP),R3      ;Get word count
28 173344 006303                ASL     k3      ;Turn into byte count
29 173346 060366  000006      ADD    R3,6(SP)      ;update bus address
30 173352 005216                INC    @SP      ;Update Logical Sector Number
31 173354 005366  000002      DEC    2(SP)      ;Decrement Sector Count
32 173360 001273                BNE    5$      ;Read another sector
33 173362 062706  000010      ADD    #8,,SP      ;Pop the stack
34 173366 000257                CCC    ;Clear condition codes
35                                     ; to show success.
36 173370 000207                RETURN
37          .DSABL LSB

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 59
-----> HALT AT PC=173262 INDICATES "FLOPPY READ ERROR"

```
1          ; The main subroutine for sending disk commands and waiting for
2          ; their completion.
3
4          ; Register usage:
5          ;   R0 = density bit ! unit select bit (proto for commands)
6          ;   R1 = RXDB address
7          ;   R4 = RXGO IR/DONE test routine pointer
8
9
10 173372 012504      RXGO:  MOV    (R5)+,R4           ;Copy command word to use
11 173374 050004      BIS    R0,R4           ;Set unit # and density
12 173376 010437 177170      MOV    R4,0#RXCS        ;Start operation
13 173402 010704      MOV    PC,R4           ;Copy adrs for later calls
14 173404 005741      TST    -(R1)          ;R1 -> RXCS
15 173406 0B2711 000240      1$:   BIT    #RXSSIR!RXSSDN,0|R1  ;Wait for IR or DONE
16 173412 001775      BEQ    1$             ;If EQ, neither are true yet
17 173414 005721      TST    (R1)+          ;Reset R1 -> RXDB and check for errors
18 173416 000205      RTS    R5             ;Return to caller
19
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 60
BOOTS-TU58 READ ROUTINES

```
1          .SBTTL BOOTS-TU58 Read routines
2
3
4
5
6          ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;
7          ;;; TU58 DECTape II READ ROUTINES ;;;;
8
9
10         ; Starts a read operation on the TU58 by transmitting a command packet
11
12
13         ; Inputs:
14         ;   R0 = starting block # for transfer
15         ;   R1 = byte count for transfer
16         ;   R2 = unit number
17         ;   R4 = address of buffer to receive data
18
19         ; Outputs:
20         ;   R0, R1, R2 unchanged
21
22         ; Destroys:
23         ;   R3, R4, R5
24
25         .ENABL LSS
26         TREAD: MOV    R4,-(SP)           ;Save buffer address
27             CLR    R4               ;Init checksum
28             MOV    #10.*400+R$SCTL,R3 ;Set command flag and length
29             CALL   CHZOUT            ;Output two chars and set R5
30             MOV    #RSREAD,R3          ;Send read command and modifier=0
31             CALL   @R5
32             MOV    R2,R3              ;Then unit number and switches=0
33             CALL   @R5
34             CLR    R3               ;Plus a zero sequence number
35             CALL   @R5
36             MOV    R1,R3              ;Followed by the byte count
37             CALL   @R5
38             MOV    R0,R3              ;And the block number
39             CALL   @R5
39             MOV    R4,R3              ;Finally, transmit the checksum
```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 61
 BOOTS-TU58 READ ROUTINES

```

1 ; Now ready to accept data messages from the TU58
2
3 173466 012600
4 ; MOV (SP)+,R0 ;R0 -> data buffer
5 173470 006001 ;CLC ;(CH2OUT leaves C clear)
6 173472 004767 000116 ;RUR R1 ;R1 = word count for transfer
7 173476 122703 000001 ;CALL 7$ ;Get first word of packet
8 173502 001017 ;CMPB #RSSDAT,R3 ;Is this indeed a data message?
9 173504 105003 ;BNE 3$ ;If NE no - may be END message
10 173506 000303 ;CLR8 R3 ;Else clear flags
11 173510 106003 ;SWAB R3 ;Move packet byte count to low byte
12 173512 160301 ;RORB R3 ;And convert to word count
13 173514 010305 ;SUB R3,R1 ;Remove from transfer count
14 173516 004767 000102 ;MOV R3,R5 ;And copy for loop counter
15 173522 010320 ;CALL 9$ ;Get next two words
16 173524 077504 ;MOV R3,(R0)+ ;Store in buffer
17 173526 004767 000044 ;SOB R5,2$ ;Loop for entire data message
18 173532 005701 ;CALL 5$ ;Get checksum and compare
19 ;TST R1 ;Have all data records been
20 173534 001356 ;BNE 1$ ;transferred?
21 173536 004767 000052 ;CALL 7$ ;If NE no
22 ;And get prospective
23 173542 004767 000056 ;CALL 9$ ;END packet start
24 ;Get opcode/success bytes
25 173546 122703 000100 ;CMPB #RSEND,R3 ;of END packet
26 173552 001402 ;BEQ 4$ ;Is this an END packet?
27 173554 ;ABORT <TU58 END packet missing> ;If NE no - ABORT
28 173560 010300 ;MOV R3,R0 ;Save success code in R0
29 173562 004767 000032 ;CALL 8$ ;Read remainder of END packet
30 173566 004767 000004 ;CALL 5$ ;And check its checksum
31 173572 000300 ;SWAB R0 ;Set CC's on success code of transfer
32 173574 000207 ;RETURN ;Return to caller
33
34 173576 004767 000064 ;5$: CALL CH2IN ;Get two checksum bytes
35 173602 020403 ;CMP R4,R3 ;Does it match calculated value?
36 173604 001402 ;BEQ 6$ ;If NE no - ERROR
37 173606 ;ABORT <TU58 checksum error>
38
39 173612 000207 ;6$: RETURN ;Else return with success
40
41 173614 005004 ;7$: CLR R4 ;Init checksum
42 173616 000402 ;BR 9$ ;And get the first word
43
44 173620 004717 ;8$: CALL @PC ;Read 4 words
45 173622 004717 ;CALL @PC
46 173624 004767 000036 ;9$: CALL CH2IN ;Read next two bytes
47 173630 060304 ;ADD R3,R4 ;Add into checksum
48 173632 005504 ;ADC R4 ;with end-around carry
49 173634 000207 ;RETURN ;And back to caller
50 .DSABL LSB

```

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 62
 -----> HALT AT PC=173610 INDICATES "TUS8 CHECKSUM ERROR"

```

1 ; CH2OUT -- Write two bytes to the TU58
2 ;
3 ; writes two bytes to interface and updates checksum.
4 ;
5 ; Inputs:
6 ;     R3 = two bytes to be output; low byte first
7 ;     R4 = current checksum word
8 ;
9 ; Outputs:
10 ;     R3 unchanged
11 ;     R4 updated to new checksum
12 ;     R5 pointing to CH2OUT routine for easier future CALLS

13 173636    004717
14 173636    004717
15 173640    004717
16 173642
17 173642    010705
18 173644    060304
19 173646    005504
20 173650    004717
21 173652    105/37  176544
22 173656    100375
23 173660    110337  176546
24 173664    000407

173642      CALL    @PC          ;Entry point to output 8 characters
173642      CALL    @PC
CH2OUT:
173642      MOV     PC,R5        ;Set R5 to following routine adrs
173642      ADD     R3,R4        ;update checksum word
173642      ADC     R4          ;with end-around carry
173642      CALL    @PC          ;Repeat for both characters
173642      TSTB   @#TOSCSR    ;Is interface ready for output?
173642      BPL    1$           ;If PL no - wait
173642      MOVB   R3,@#TOSBFR  ;Else transmit character to TU58
173642      BR     CHRET        ;Merge with other routine to return

173666      ; CH2IN -- Read two bytes from the TU58
173666      ; CHIN  -- Read a single byte from the TU58
173666      ;
173666      ; Inputs:
173666      ;     none.
173666      ; Outputs:
173666      ;     R3 = character(s) read

173666      CH2IN: CALL    @PC          ;Read two, not one
173666      CHIN: CLR B R3          ;And zero out space for new one
173666      1$:    TSTB   @#TISCSR    ;Is a character available?
173666      BPL    1$           ;If PL no
173666      BISB   @#TISBFR,R3    ;Else set into register
173666      CHRET: SWAB   R3          ;Move current character over
173666                  RETURN        ;And return to caller
40 173706    000207

```

KXT11-AZ 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 63
END STATEMENT

1
2 000001 .SBTTL END STATEMENT
.END

KXT11-A2 1K FIRMWARE
SYMBOL TABLE

MACRO V04.00 5-OCT-81 22:56:27 PAGE 63-1

AROUN2	172010	E.PAR = 000001	PP.B16= 000014	RTSUSR= 000046	R.PC = 167766 G
AROUN3	173016	FAKUUT 170424	PP.B17= 000016	RXBOUT 172400	R.STAK= 000001
AUTOBA	170472 G	FILNAM= 000002	PP.C = 176204	RXCS = 177170	R.TYPE= 167762 G
BADBOT	172370	GETCHK 171510	PP.CHI= 000010	RXDB = 177172	R.SRT = 170036 G
BAUDRS=	000032	GEINUM 171612	PP.CLUE= 000001	RXESCR= 000001	SAVPC = 167752 G
BD.003=	000000	HGHSEG= 001004	PP.CWR= 176206	RXESDD= 000100	SAVPS = 167754 G
BD.006=	000010	HKBDQ 171140	PP.DRA= 000020	RXESDE= 000020	SEGALU= 001000
BD.012=	000020	HKBDS 171142	PP.DRB= 000002	RXESDN= 000040	SPACE = 000040
BD.024=	000030	HVAUD 170556	PP.MDA= 000040	RXESDR= 000200	SRET = 171636
BD.048=	000040	INBYLE 170550	PP.MDB= 000004	RXESID= 000004	STANDB = 172564
BD.096=	000050	INBYTS 170556	PP.MD2= 000100	RXESUN= 000400	START = 1/2000 G
BD.192=	000060	INITS 171750	PP.MODE= 000200	RXGO = 173372	STARTS = 172752
BD.384=	000070	IN.USR= 167764 G	PRINT 170706	RXSEMP= 000003	STRBLK= 001010
BIT0 =	000001	KBDQ 170674	PR16 = 000300	RXXFILE= 000001	STTUBD = 172172 G
BIT1 =	000002	KBDS 170702	PK17 = 000340	RXSREC= 000017	ST173 = 173000 G
BIT10 =	002000	LCSET 171246	PUTCHR 171522	RXSRED= 000007	SWCMD = 171212
BIT11 =	004000	LEDOFF= 000017	PUTCLF 171554	RXSRSR= 000013	SSCART= 177767
BIT12 =	010000	LF = 000012	PUTLF 171564	RXSSTD= 000011	SSDCCHK= 177757
BIT13 =	020000	LOAD 172714	PUTSTK 171542	RXSWDD= 000015	SSMOTR= 177737
BIT14 =	040000	LOCDSP 171252	PWRSUP 170260 G	RXSWRT= 000005	SSNORM= 000000
BIT15 =	100000	MODE = 000221	QOUT 170666	RXSSDE= 000400	SSOPCD= 177720
BIT2 =	000004	MSGQ 171730	RAMROT= 160010	RXSSDN= 000040	SSPART= 177776
BIT3 =	000010	MSGS 171731	RAMTOP= 167776	RXSSER= 100000	SSRECN= 177711
BIT4 =	000020	NEXNUM 171600	RBUFS1= 177562	RXSSFN= 000016	SSRETR= 000001
BITS =	000040	NDCT 171642	RBUFS2= 176542	RXSSGO= 000001	SSSEER= 177740
BIT6 =	000100	NO.LOW= 100000	RB.BRK= 004000	RXSSIE= 000100	SSUNIT= 177770
BIT7 =	000200	NXTSEG= 001002	RB.EKR= 100000	RXSSIN= 040000	SSWPRT= 177765
BIT8 =	000400	OCTSTR 171656	RB.FRME= 020000	RXSSTR= 000200	TENTAS= 000400
BIT9 =	001000	OCTST0 171652	RB.OVRE= 040000	RXSSUN= 000020	TISBFR= 176542
BOOT5	172164 G	ODT 170602 G	RCMD 171144	RXSSXA= 030000	T1CSR= 176540
BRKNU0	170010 G	ODTFLG= 167750 G	RCMD1 171232	RXSSXX= 003000	TOSBFR= 176546
B.CNTL=	167770 G	ODTLOC= 167746 G	RCRSR1= 177560	RXSS02= 004000	TOSCSR= 176544
CHIN	173670	ODTSTK= 167744 G	RCRSR2= 176540	RSABRT= 000006	TRAP4 = 167776 G
CHK240	172426	ODTWHx= 167774 G	RC.ACT= 004000	RSCOMP= 000004	TREAD = 173420
CHRET	173704	ONENUM 171576	RC.DUN= 000200	RSDIAG= 000007	TUBAUD= 000072
CH2IN	173666	O.CNTL= 167772 G	RC.IEN= 000100	RSEND = 000100	TUBOOT = 172404
CH2OUT	173642	PATERN 171750	READU 172772	RSGETC= 000012	T.BIT = 000020
CH8OUT	173636	PBRO = 000010	READZU 172770	RSGETS= 000010	USERSP= 167760 G
CR =	000015	PBR1 = 000020	REGOUT 171240	RSINIT= 000001	VECSET = 170440 G
DEVBIT=	000200	PBR2 = 000040	RESTAR 172004 G	RSNOP = 000000	XBUFS1= 177566
DEVNUM=	000001	PCMD 171044	RETRY = 000010	RSPOSI= 000005	XBUFS2= 176546
DIAGNU	171754	PERMFS= 002000	RFLAG = 000200	RSREAD= 000002	XCSR1= 177564
DIRBUF=	001000	PP.A = 176200	RPOINT= 167756 G	RSSE1C= 000013	XCSR2= 176544
DONE	171574	PP.B = 176202	RTSEMT= 000052	RSSETS= 000011	XC.BRK= 000001
DREAD	173030	PP.BIC= 000000	RTSFCH= 000056	RSWRIT= 000003	XC.IEN= 000100
D.FLEN=	000010	PP.BIS= 000001	RTSFCT= 000057	RSSCON= 000020	XC.MNT= 000004
EMPTYS=	001000	PP.BI0= 000000	RISHGHE= 000050	RSSCIL= 000002	XC.PBE= 000002
ENDSGS=	004000	PP.BI1= 000002	RTSISP= 000042	RSSDAT= 000001	XC.RDY= 000200
ENTSIZ=	000016	PP.BI2= 000004	RTSJSW= 000044	RSSINT= 000004	XIRBT= 001046
ERRBIT	171742	PP.BI3= 000006	RTSRMN= 000054	RSSXUF= 000023	SSTACK= 167644 G
E.EXT =	000100	PP.BI4= 000010	RTSSTA= 000040	R.HALT= 100000	SSSBRK = 170000 G
E.INT =	000010	PP.BI5= 000012	RTSUER= 000053	R.NXM = 000200	SSSLTC = 170006 G

. ABS. 174000 000

000000 001

ERRORS DETECTED: 0

KXT11-AZ 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE 63-2
SYMBOL TABLE

VIRTUAL MEMORY USED: 9216 WORDS (36 PAGES)
DYNAMIC MEMORY AVAILABLE FOR 46 PAGES
,FALCON/C=FALCON

KXT11-A2 1K FIRMWARE MACRO V04.00 5-UCH-81 22:56:27 PAGE S-1
 CROSS REFERENCE TABLE (CREF V04.00)

SS\$BRK	14-16#	27-35					
SS\$LTC	14-20#	27-37					
S\$STACK	13-30#	24-13	27-17	49-77	49-91		
ARDUN2	44-47	46-2#					
ARDUN3	54-24	56-2#					
AUTUBA	27-13	28-43#					
B.CNTL	13-14#	26-49*	49-54*	49-55	56-3		
BADBOT	49-66	49-90*					
BAUDRS	9-14#	28-44					
BD.003	7-21#						
BD.006	7-22#						
BD.012	7-23#						
BD.024	7-24#	9-14					
BD.048	7-25#						
BD.096	7-26#						
BD.192	7-27#						
BD.384	7-28#	9-18					
BIT0	5-5#	7-43	8-29	8-47	10-5	10-13	35-50
BIT1	5-6#	7-36	8-27	8-38	8-40	8-42	8-44
BIT10	5-15#						
BIT11	5-16#	6-16	6-37				
BIT12	5-17#						
BIT13	5-18#	6-35					
BIT14	5-19#	6-32					
BIT15	5-20#	6-30	10-3	10-9			
BIT2	5-7#	7-30	8-25	8-38	8-39	8-42	8-43
BIT3	5-8#	7-15	8-23	8-38	8-39	8-40	8-41
BIT4	5-9#	7-16	8-21	9-34			
BIT5	5-10#	7-17	8-18	38-11			
BIT6	5-11#	6-23	7-8	8-17	38-9		
BIT7	5-12#	6-19	7-3	8-15	9-32	10-4	10-11
BIT8	5-13#						
BIT9	5-14#						
BOOTS	33-21	49-25#					
BRKN00	14-18	14-26*	21-17				
CH21N	61-34	61-46	62-34#				
CH2OUT	60-27	62-16#					
CH8OUT	52-17	62-13#					
CHIN	62-35#						
CHK240	51-17#	52-36					
CHRET	62-24	62-39#					
CR	5-25#	37-26	38-21	40-24	41-20	43-13	
D.FLEN	48-125#	53-47					
DEVBIT	10-11#	49-37					
DEVNUM	10-13#	49-83					
DIAGNO	33-25	44-37#					
DIRBUF	48-62#	48-118	48-119	48-120	48-121	48-122	53-21
DONE	40-17	40-31#					
DREAD	50-21	56-4	57-21#				
E.EXIT	10-17#	44-17					
E.INT	10-18#	44-18					
E.PAR	10-19#	46-6					
EMPTY\$	48-127#						
ENDSGS	48-129#	53-31					
ENTSIZE	48-124#						
ERRHIT	44-19#	46-11					

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE S-2
CRUSS REFERENCE TABLE (CREF V04.00)

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE S-3
CRUSS REFERENCE TABLE (CREF V04.00)

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE S-4
 CROSS REFERENCE TABLE (CREF V04.00)

READZU	52-35	54-6	54-21*						
REGOUT	36-25	36-34	36-38*						
RESTAR	21-27	45-6*							
RETRY	48-54*								
RFLAG	9-32*	36-14							
RPUINT	13-22*	32-32*	36-37						
RTSEMT	48-138*								
RTSFCH	48-141*								
RTSFCT	48-142*								
RTSHGH	48-137*								
RTSISP	48-134*	54-17							
RTSJSW	48-135*								
RTSRMN	48-140*								
RTSSSTA	48-133*	54-9							
RTSUER	48-139*								
RTSUSR	48-136*								
RXSS02	48-21*	58-5							
RXSSDE	48-23*	57-44							
RXSSDN	48-26*	59-15							
RXSSER	48-18*								
RXSSFN	48-28*								
RXSSGO	48-29*	48-33	48-34	48-35	48-36	48-37	48-38	48-39	48-40
RXSSIE	48-25*								
RXSSIN	48-19*								
RXSSTR	48-24*	59-15							
RXSSUN	48-27*	57-31							
RXSSXA	48-20*								
RXSSXX	48-22*								
RXSEMP	48-34*	58-4							
RXSFIL	48-33*								
RXSREC	48-40*								
RXSRED	48-36*	57-78							
RXRST	48-38*	57-33							
RXSSDU	48-37*								
RXSWDD	48-39*								
RXSWRT	48-35*								
RXBOUT	49-87	50-14*							
RXCS	48-13*	48-14	50-15	50-16	58-5	59-12*			
RADB	48-14*	57-27							
RXESCR	48-50*								
RXESDD	48-46*								
RXESDE	48-48*								
RXESDN	48-47*	57-37							
RXESDR	48-45*								
RXESİD	48-49*								
RXESUN	48-44*								
RXGU	57-32	57-77	58-3	59-10*					
SSCART	48-106*								
SSDCHK	48-108*								
S\$MUTR	48-110*								
SSNURM	48-102*								
SSOPCD	48-111*								
SSPART	48-104*								
SSRECN	48-112*								
SSRETK	48-103*								
S\$SEEK	48-109*								

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE S-5
CROSS REFERENCE TABLE (CREF V04.00)

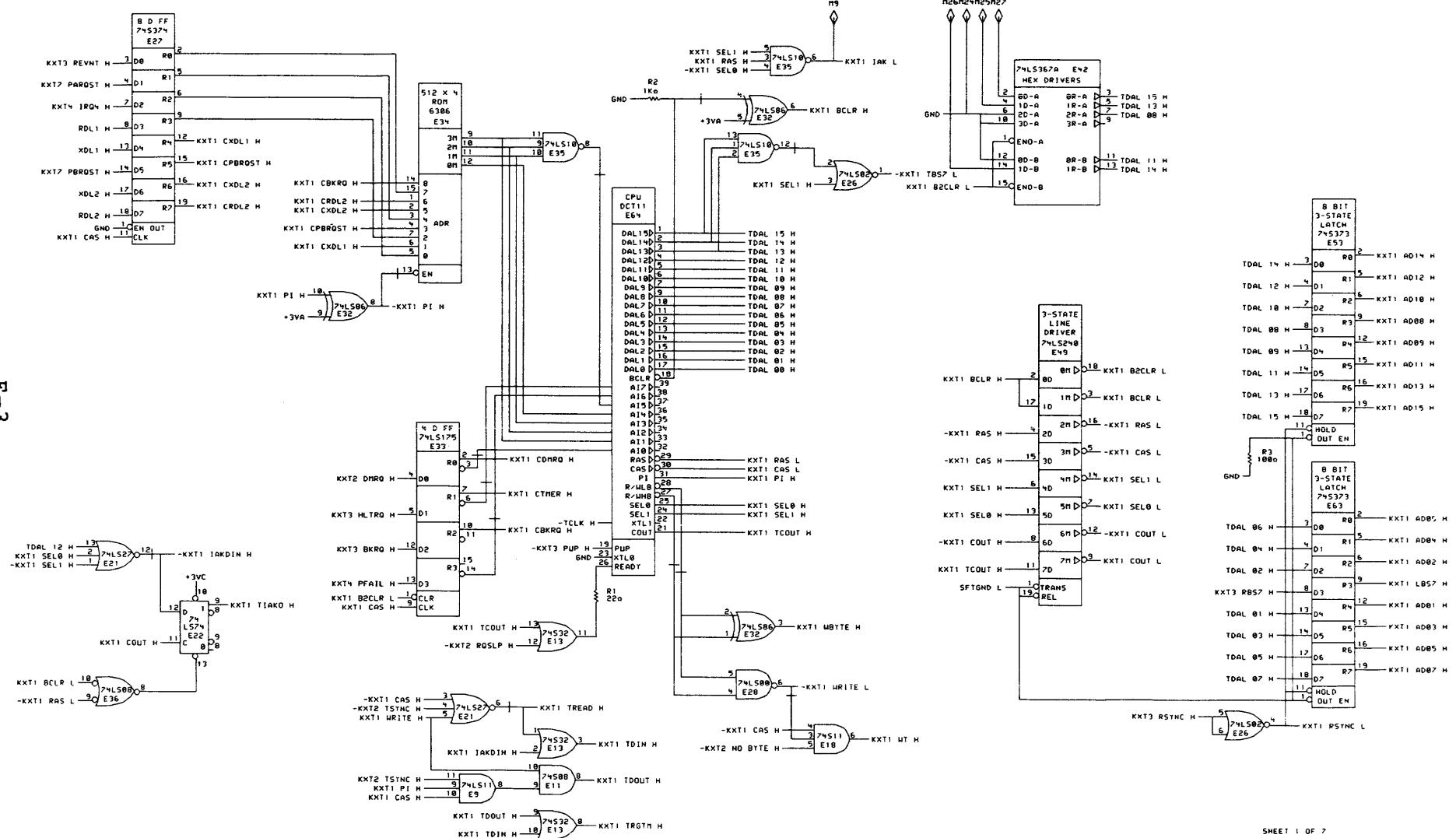
SSUNIT	48-105#							
SSWPRT	48-107#							
SAVPC	13-25#	14-27*	21-37*	27-12*	32-39	35-11*	35-54	36-24
SAVPS	13-24#	14-28*	21-36*	27-11*	35-16*	35-53	36-33	37-45
SEGALD	48-116#							
SPACE	5-26#	37-23						
SRET	41-21	41-32#						
ST173	55-4#							
STANDB	51-21	53-15#						
START	45-4#							
STARTS	54-11	54-14*						
STRBLK	48-122#	53-25						
STTUBD	49-30#							
SWCMD	36-18	36-29*						
T.BIT	9-34#	37-50						
IENTAS	48-126#							
TISBFR	48-69#	62-38						
TISCSR	48-68#	52-13	52-25	62-36				
TIOSBFR	48-71#	62-23*						
TUSCSR	48-70#	49-26*	52-14	62-21				
TRAP4	13-5#	22-11	49-78*	54-18*				
IREAD	56-5	60-24#						
TUBAUD	9-18#	49-26						
TUBOUT	49-88	52-12*						
USERSP	13-20#	32-20*	32-25					
VECSET	26-46	27-34#	51-22					
XBUFS1	6-8#	39-22*						
XBUFS2	6-12#	48-71						
XC_BRK	7-43#	52-20						
XC_IEN	7-8#							
XC_MNT	7-30#	44-26						
XC_PBE	7-36#	9-14	9-18	44-25	44-26			
XC_RDY	7-3#	24-39						
XCSRS1	6-7#	24-32*	24-39	28-44*	29-37*	39-20		
XCSRS2	6-11#	48-70						
XTRBYT	48-121#	53-50						

KXT11-A2 1K FIRMWARE MACRO V04.00 5-OCT-81 22:56:27 PAGE M-i
CROSS REFERENCE TABLE (CREF V04.00)

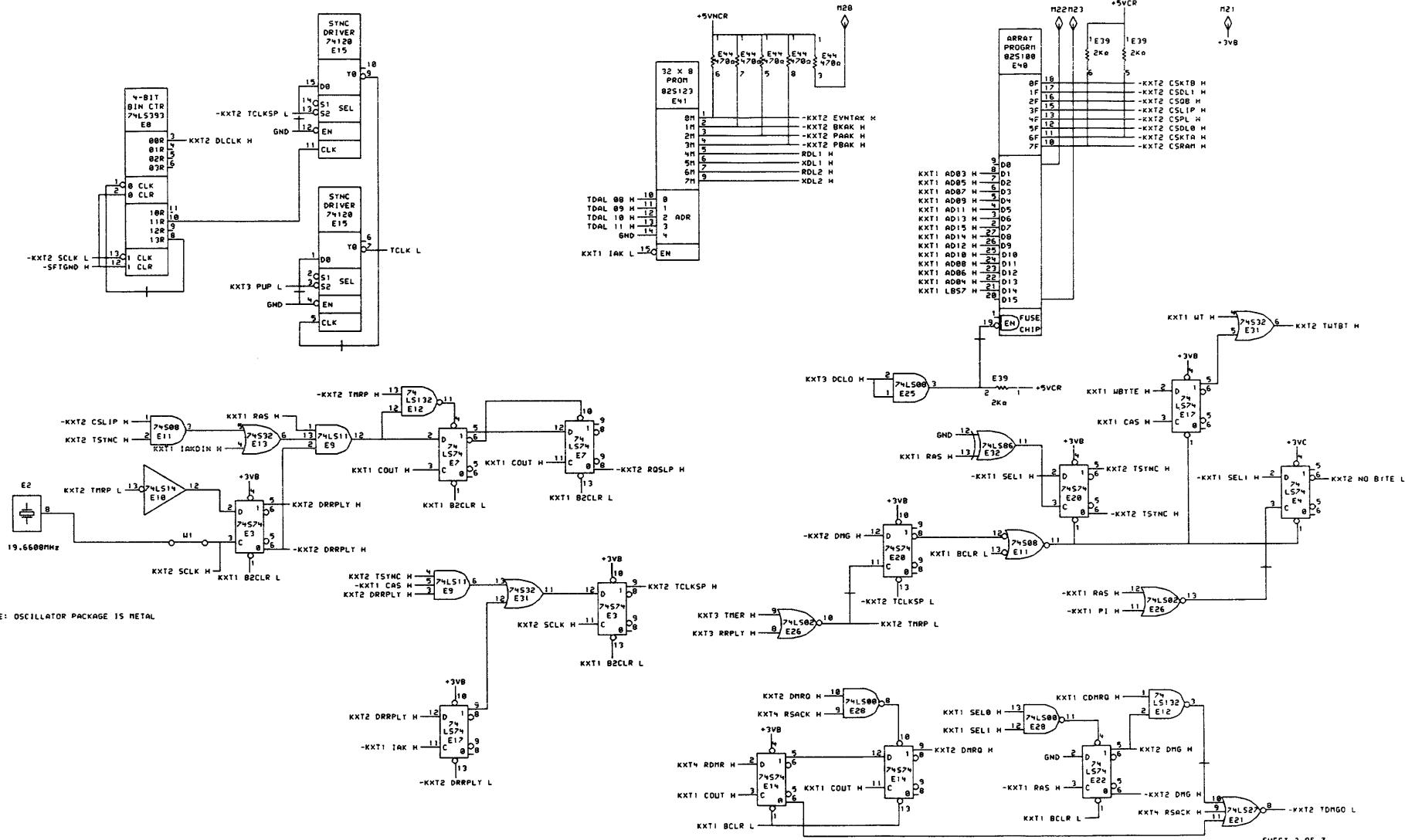
	11-15#	49-42	49-51	49-58	49-92	51-23	52-29	52-37	53-24	53-36	54-8	54-12	57-36	57-114
ABORT														
	61-27	61-37												
DELAY	12-23#	49-76												

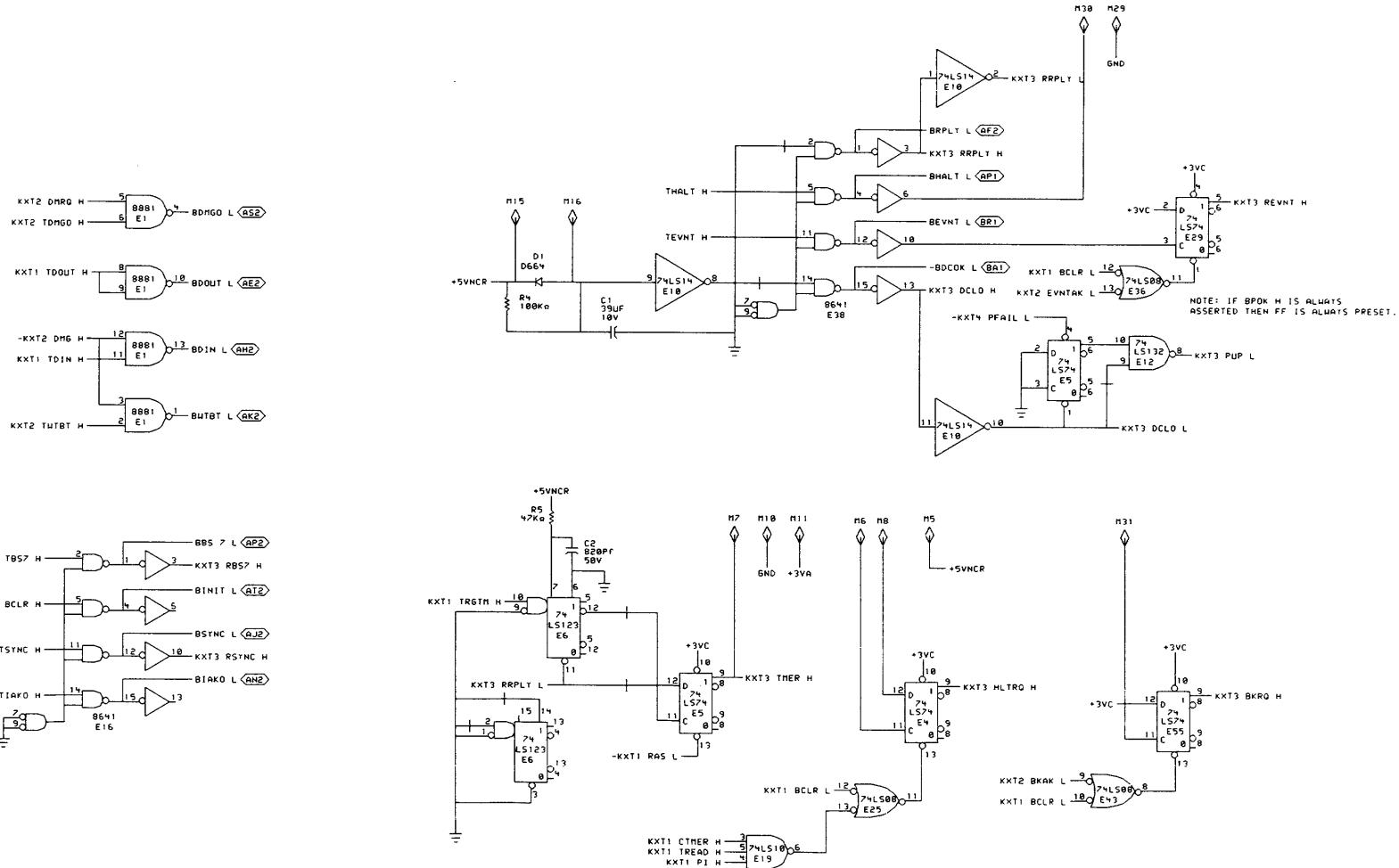
APPENDIX E
SBC-11/21 SCHEMATICS

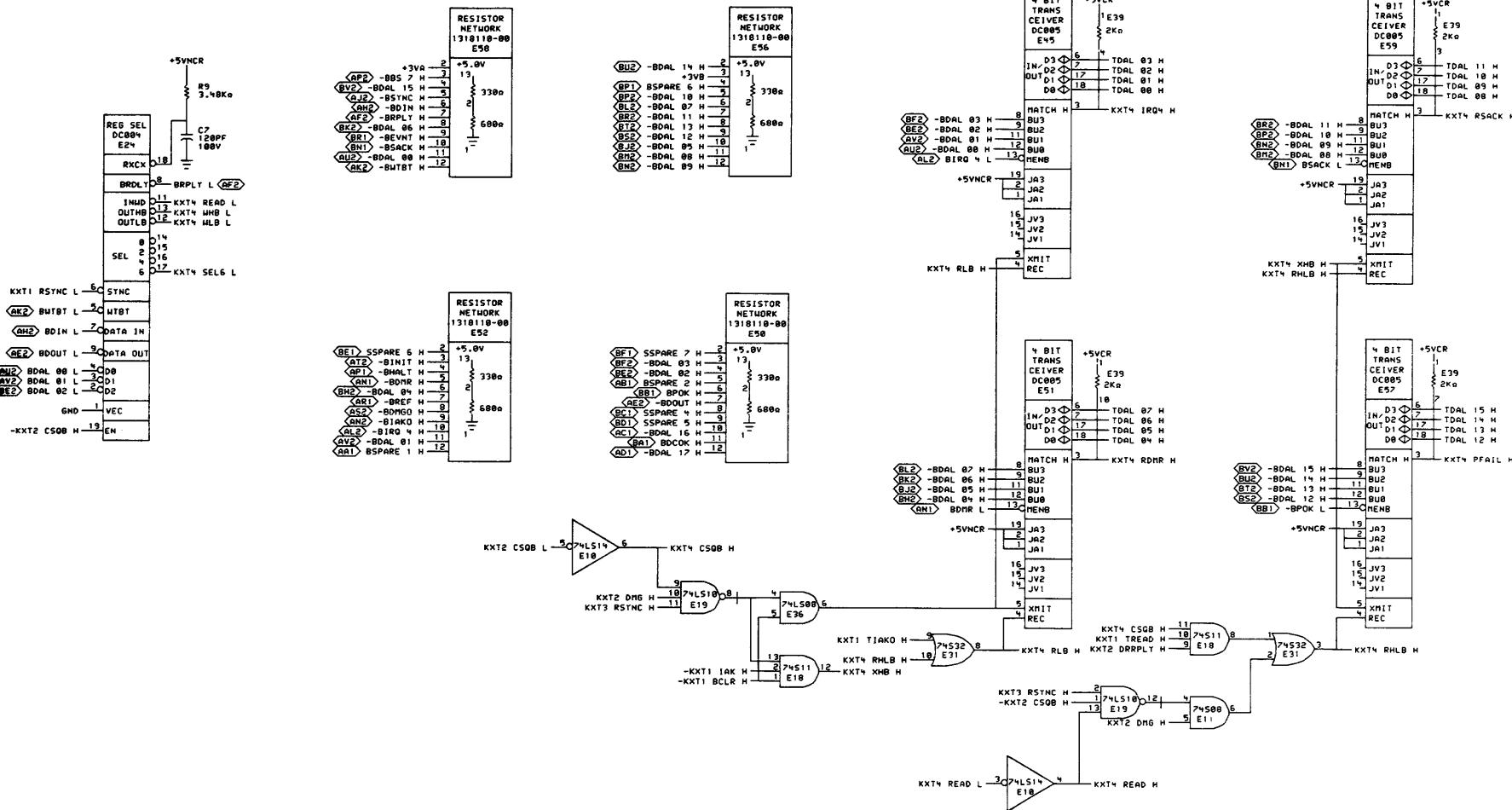
This appendix provides the user with the electrical schematics for the SBC-11/21 module.



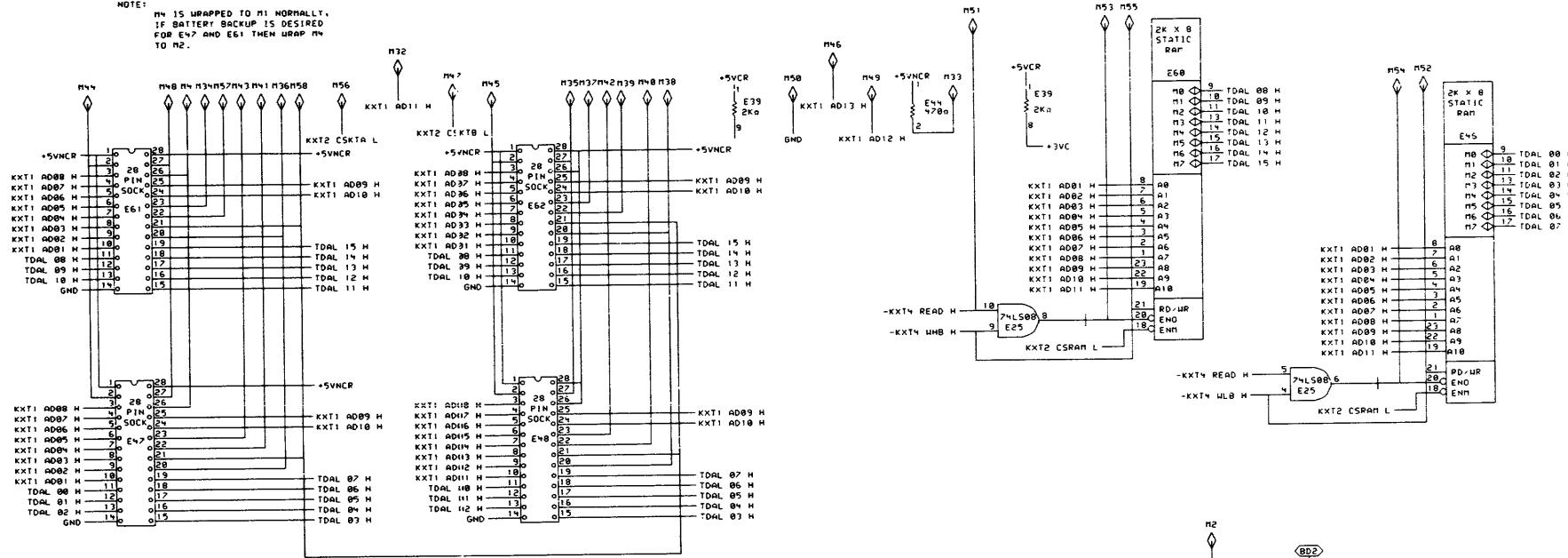
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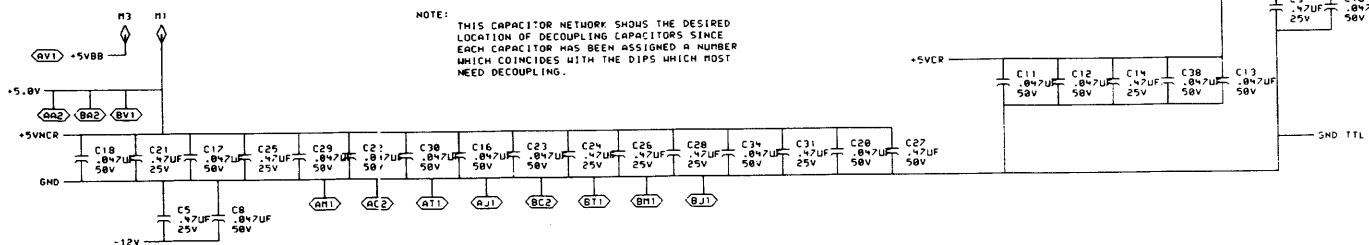


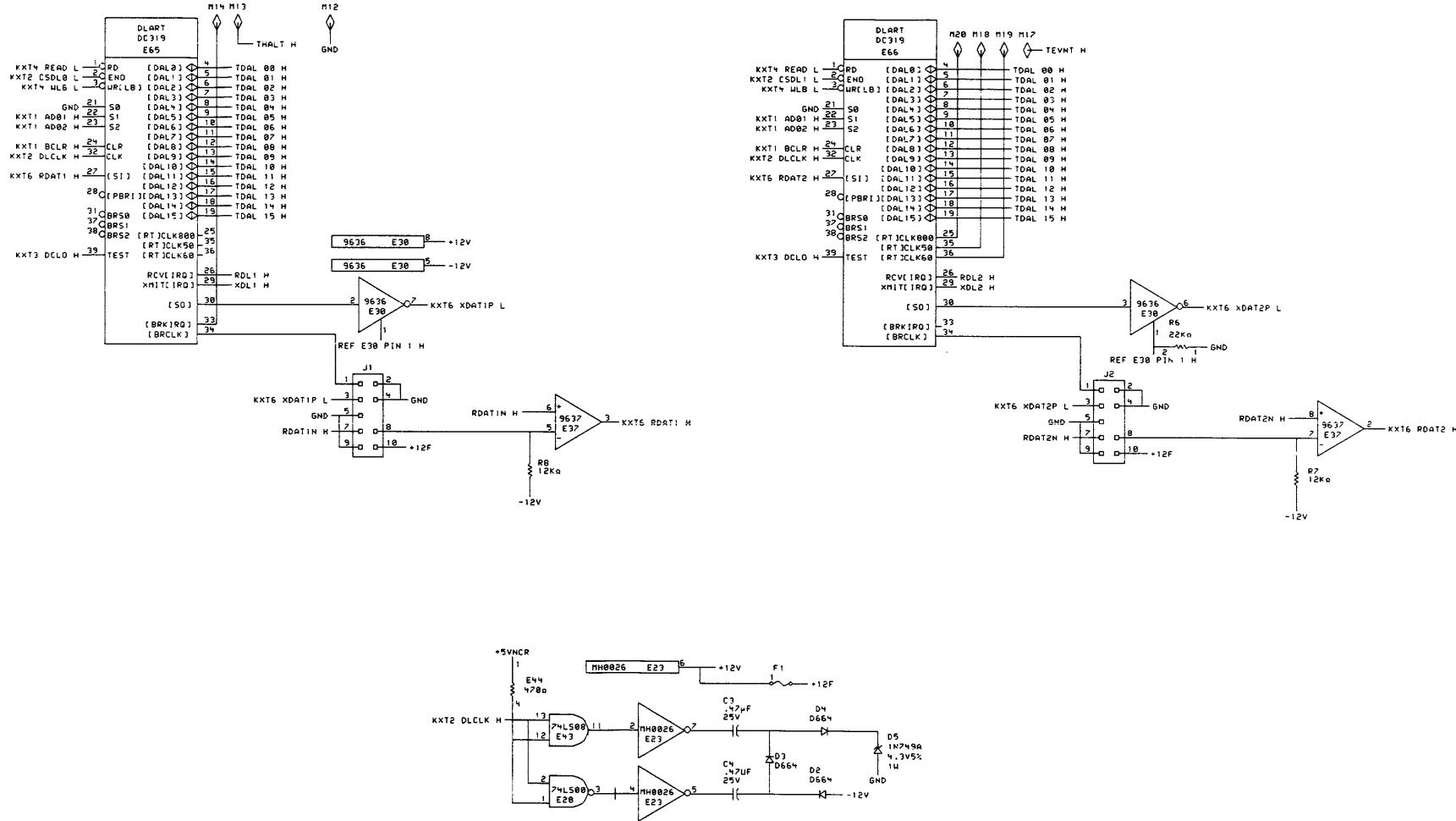


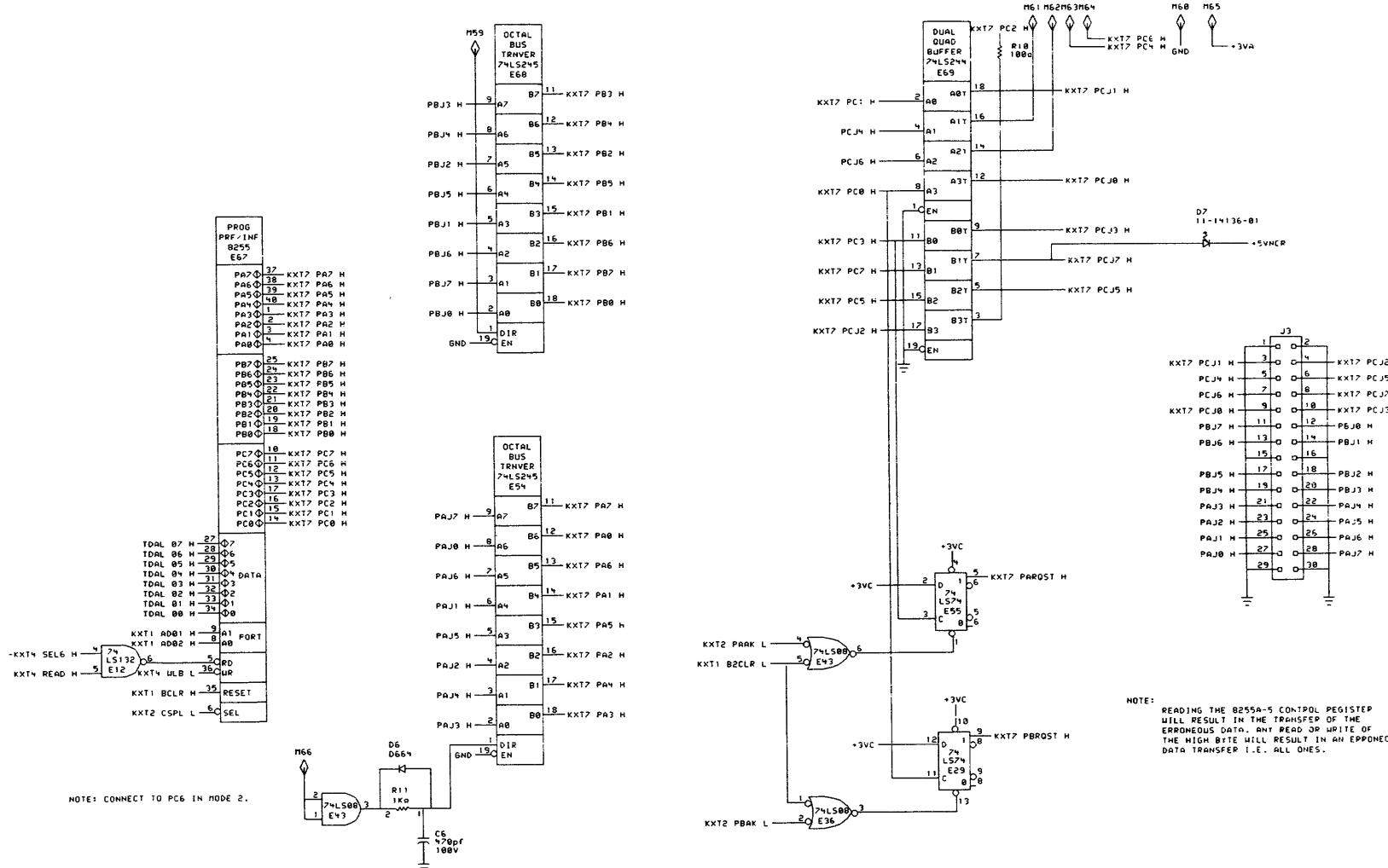
NOTE: M4 IS WRAPPED TO M1 NORMALLY.
IF BATTERY BACKUP IS DESIRED
FOR E47 AND E61 THEN WRAP M4
TO M2.



NOTE: THIS CAPACITOR NETWORK SHOWS THE DESIRED LOCATION OF DECOUPLING CAPACITORS SINCE EACH CAPACITOR HAS BEEN ASSIGNED A NUMBER WHICH COINCIDES WITH THE DIPS WHICH MOST NEED DECOUPLING.







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