

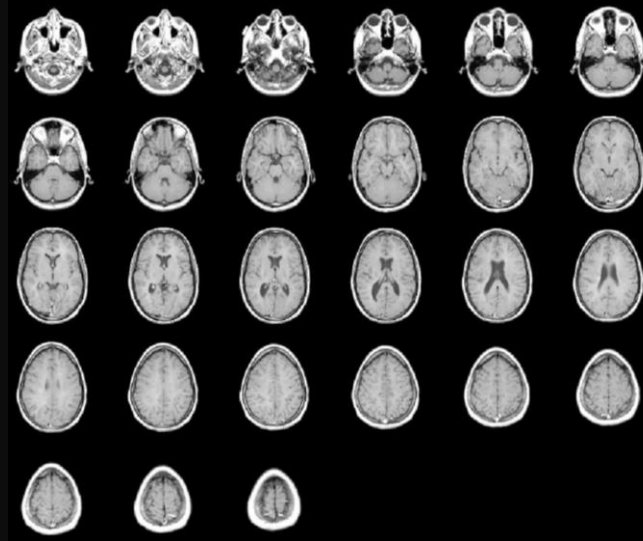
# 3D Volumetric Grayscale Image Slicing

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BIOEN 217

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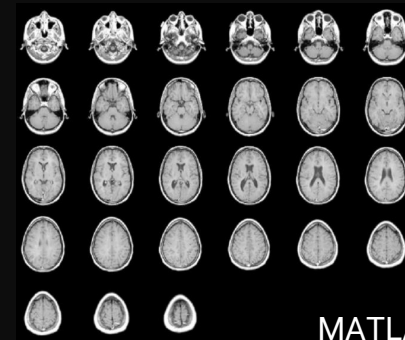
montage(MRI)



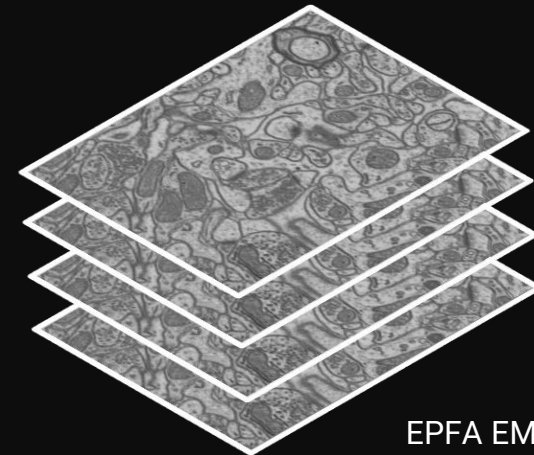
obliquelice3d(MRI, point, n)

# Background

- 3D volumetric image data is widely used in science and medicine
  - Medical imaging (CT, MRI)
  - Microscopy
- Volumetric data are layers of 2D images
  - Slices about coordinate plane – easy
  - Slices about arbitrary plane – need math!



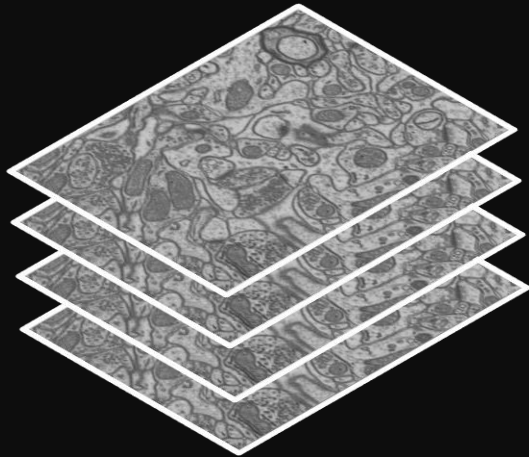
MATLAB MRI dataset



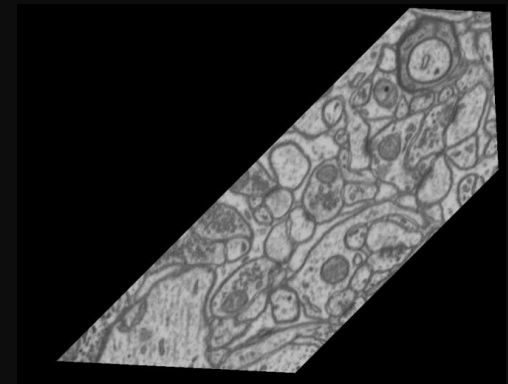
EPFA EM dataset

# Objective

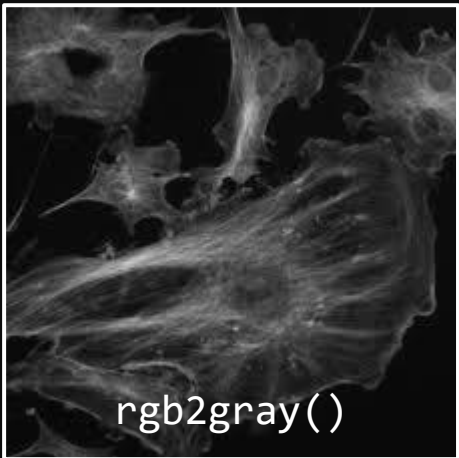
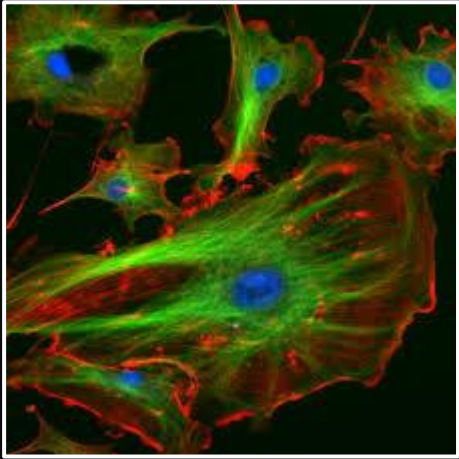
- Explore 3D volumetric image data
- Develop oblique slicing function for 3D volumetric grayscale image
  - Start from 2D



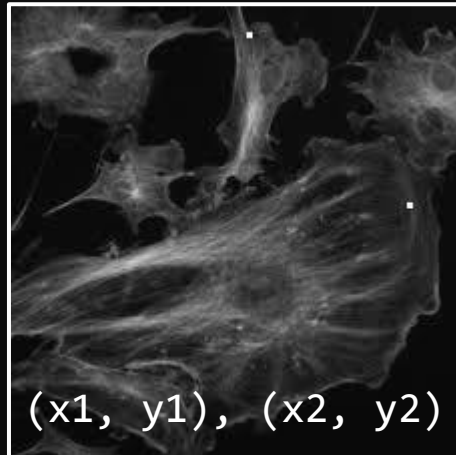
`obliqueslice3d(img, point, normal)`



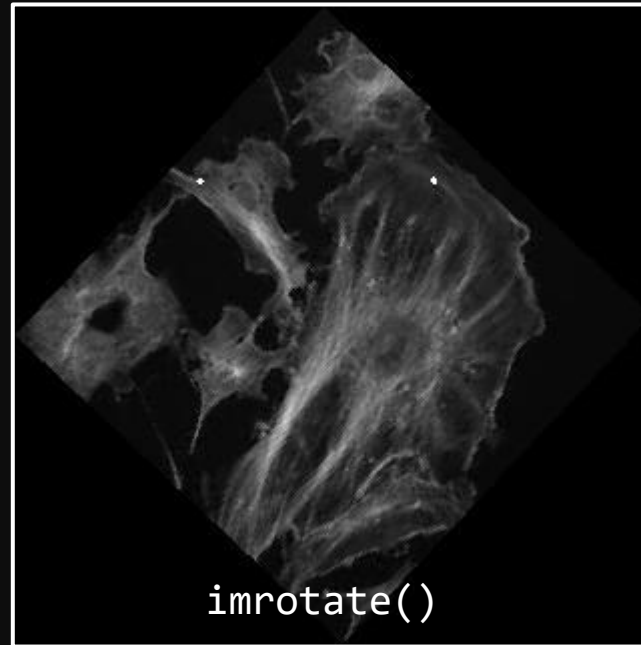
# obliquelice2d(img, point1, point2)



<https://imagej.nih.gov/ij/images/>



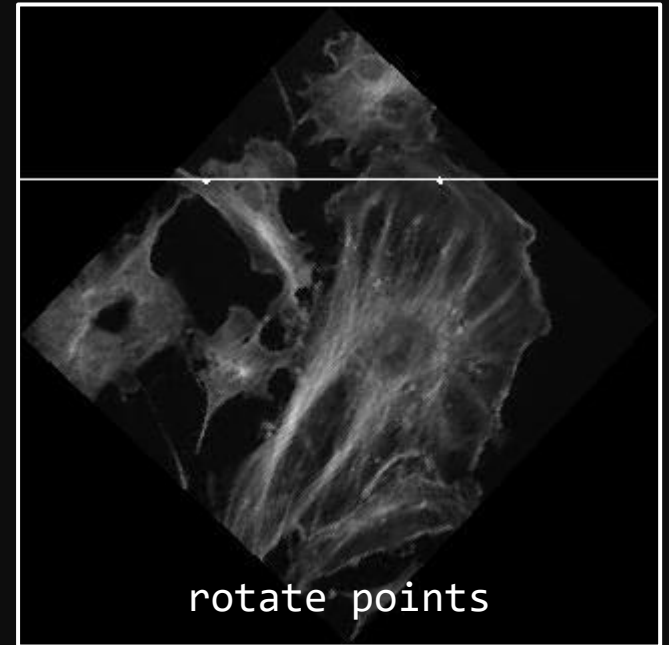
angle = atan(slope)



imrotate()

$$R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

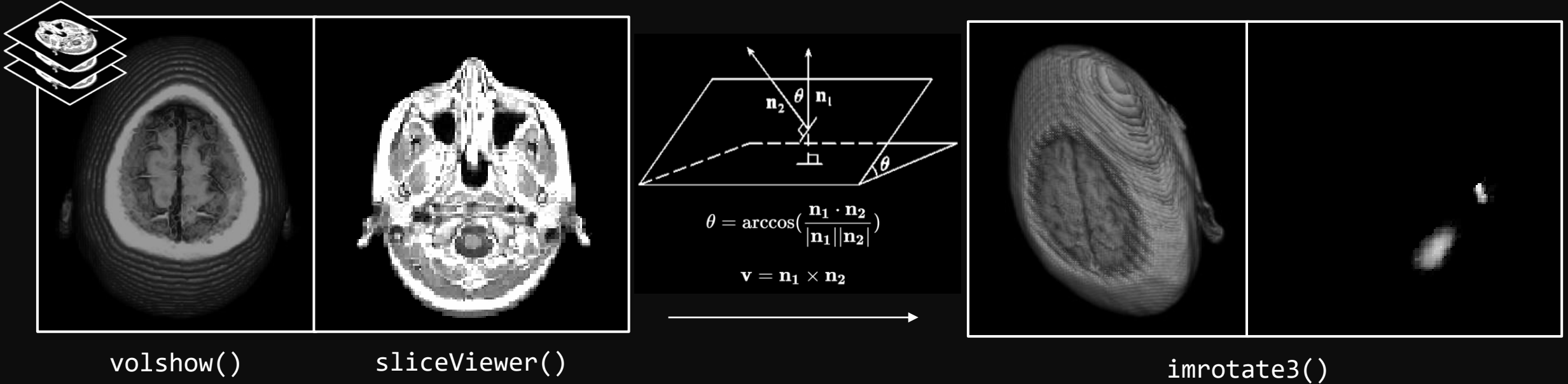
Rotation Matrix,  
Wikipedia



rotate points

obliquelice2d()

# obliquelice3d(img, point, normal)



$$R = \begin{bmatrix} ll(1 - \cos \theta) + \cos \theta & ml(1 - \cos \theta) - n \sin \theta & nl(1 - \cos \theta) + m \sin \theta \\ lm(1 - \cos \theta) + n \sin \theta & mm(1 - \cos \theta) + \cos \theta & nm(1 - \cos \theta) - l \sin \theta \\ ln(1 - \cos \theta) - m \sin \theta & mn(1 - \cos \theta) + l \sin \theta & nn(1 - \cos \theta) + \cos \theta \end{bmatrix}$$

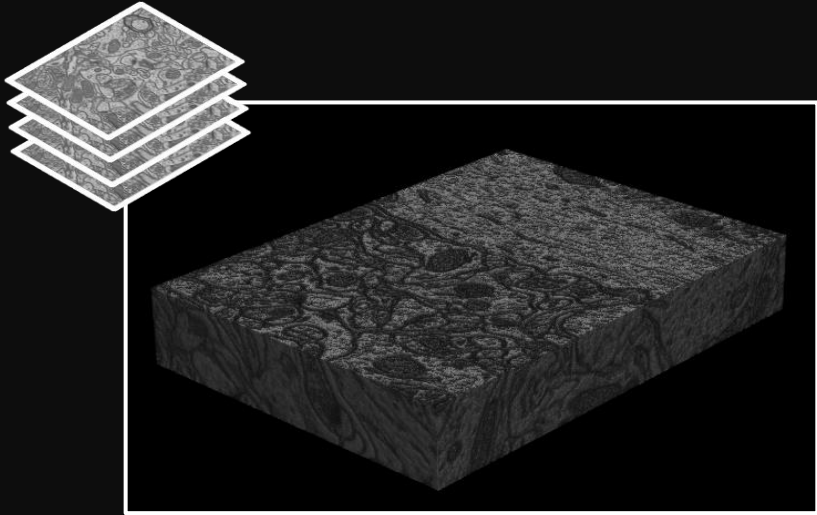
Transformation Matrix, Wikipedia

rotate point; get z coordinate



```
obliquelice3d(  
    MRI,  
    [50, 50, 12],  
    [1; 1; 1]  
)
```

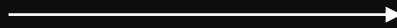
# Application: Microscopy Images



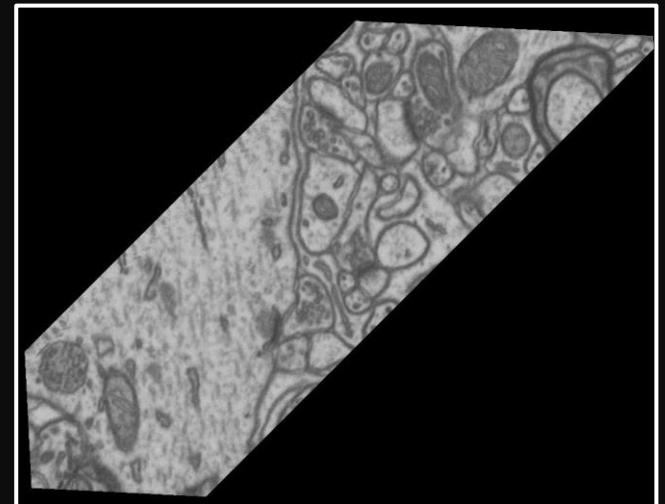
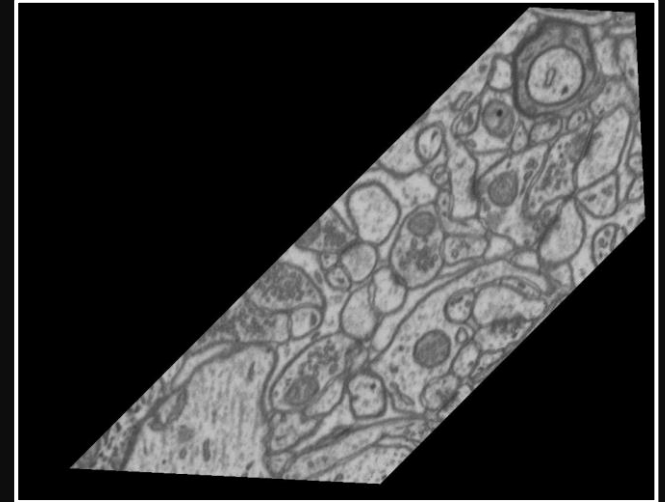
EPFA EM dataset

1024 x 768 x 165

```
obliquelice3d(  
    cells_stack,  
    [250; 250; 50],  
    [1; 1; 3]  
)
```



```
obliquelice3d(  
    cells_stack,  
    [300; 500; 50],  
    [-1; -1; 3]  
)
```



# Conclusion

- Packaged functions
  - `obliquelice2d(img, point1, point2)`
  - `obliquelice3d(img, point, normal)`
- Problem solving skills
  - Extract problem solving pattern from lower dimension
  - Reduce oblique slicing problem to slicing along axis by rotation
- Future directions
  - Inputs characterized by plane parameters make slicing difficult to visualize
  - GUI-guided slicing needed