GTU CSE344 - System Programming

Homework2 - Report

Ahmet Tuğkan Ayhan 1901042692 In this homework, I used one of my libraries I created in **Homework1** which is **File.h.** Since I explained how it works and handles the possible errors, I won't be explaining it again to prevent report becoming too long.

As said in the instruction pdf, there are 2 different processes in this homework. One is **parentProcess** and other one is **childProcess**. I will explain every function that I created for these processes along with the file format.

Let's start with parentProcess..

parentProcess.c

```
#define NUM_OF_POINTS 10
#define MAX_CHILD 10000
void parentProcess(char * fileBuffer, int fileSize);
void getFilePaths
     getCoordinates
                                          (int pidList[MAX_CHILD], char x_coordinates[10], char y_coordinates[10], char z_coordinates[10]);
void createChildProcess
void getCovarianceMatricesFromOutputFile (float covarianceMatrices[childCount][3][3]);
float calculateFrobeniusNorm
void getFrobeniusNormOfMatrices
float findTwoClosestMatrices
void printFirstDialogue
void printResultToConsole
void printChildInformation (int count, char x_coordinates[10], char y_coordinates[10], char z_coordinates[10]);
void initializeSignalHandler ();
void handleSIG
                            (char * fileBuffer, int pidList[MAX_CHILD]);
void terminateProgram
```

#define

- NUM_OF_POINTS: Indicates how many coordinate points there will be for every x, y and z axis.
- MAX_CHILD: Actually there is no limit for creating child processes. This one shows limit for pidList which stores every child's pid. This pid used for graceful exiting for every child after SIGINT interrupt.

Global Variables

- sigintFlag: When a SIGINT signal is sent to the parent process, this flag is set to 1, initially it is 0.
- readFD: Contains file descriptor value for inputFilePath. I make it global because there are many functions that use this descriptor value.

- writeFD: Contains file descriptor value for outputFilePath. This writeFD value later sent to child processes as they created. Thus, closing and opening operations only done in parent process.
- childCount: Stores current child count. Also used as index for pidList which stores child process id's
- firstChild: After child processes finish, frobenius norm values are calculated. After finding two matrices that has least difference between them, index of first matrix is stored in this global variable.
- **secondChild**: Also index of second matrix is stored in this global variable. Then this information used in covarianceMatrix[childCount][][] array to receive matrix values.
- inputFilePath: Inside main, getFilePaths is executed and after doing error checks, input file's path assigned to this char pointer.
- **outputFilePath**: Same as inputFilePath but this one stores command line argument which comes after "-o" indicator.

Functions

- main: Main function initializes signal handlers, if there is no error then gets file paths. After everything is ok it opens the both input and output files stores their file descriptor value with readFD and writeFD then calls parentProcess.
- parentProcess: Does everything that is explained inside instruction pdf. Prints dialogues, checks if there are 30 or more ASCII character left, turns them into coordinates if there are, creates the child process and sends these coordinates to child process via environment variables(char *agvp[]). Waits child processes to finish, closes files, gets covariance matrices from output file, calculates frobenius norm for each of these matrices and finds the closest two. Finally prints the result to the console.
- **getFilePaths**: Called inside main function. Checks if given arguments are correct or not. If it is then assigns **inputFilePath** and **outputFilePath** values.
- **getCoordinates**: After controlling remaining characters inside input file, it gets these characters and assigns them into x_coordinates[10], y_coordinates[10] and z_coordinates[10].
- createChildProcess: Executes fork-exec paradigm. Checks if forking is successful or not. If it is then calls execve function after assigning coordinate values into environment variables(agvp).
- **getCovarianceMatricesFromOutputFile**: When child processes are finished, this function reads the matrices and assigns them into covarianceMatrices[childCount][3][3] 3d array.
- **getFrobeniusNormOfMatrices**: After filling covarianceMatrices array, this function is called inside parent function and every matrix's frobenius norm values are calculated. Then these values are stored inside frobeniusNorm[childCount] array.
- calculateFrobeniusNorm: Receives a 3x3 float array and calculates frobenius norm for that matrix, then returns the result back to **getFrobeniusNormOfMatrices** function. It is done for every child.

- findTwoClosestMatrices: After every frobenius norm values are calculated, then this function is called inside parent function. This function assigns firstChild and secondChild global variables after finding closest two value.
- printFirstDialogue: These print functions just prints necessary informations to the console. This one prints only first line which is "Process P reading inputFile.dat"
- printResultToConsole: Prints closest 2 matrices and their frobenius norm difference to the console
- printChildInformation: Prints "Created R_* with (...)(...) ... (...)" part.
- initializeSignalHandler: Signals are handled with these 3 functions. This one initializes sigset_t and struct sigaction variables. sigset_t variable is used to block every signal except SIGINT until program terminates. Sigaction structure is used to indicate that SIGINT signal is handled by handleSIG function.
- handleSIG: Receives signal value and handles that signal according to that value. For this homework there is only SIGINT. If coming signal is belong to SIGINT, then switches sigintFlag from 0 to 1 and does nothing else.
- terminateProgram: This function called when sigintFlag is equal to 1. I made this check condition inside parentProcess while waiting for child processes to finish(with wait() function) and inside createChildProcess after creating child process. So there is no program termination or busy waiting inside signal handler. This function simply closes open files, frees all allocated variables and deletes the outputFile(by using unlink function). Also prints the current terminating process into the console.

childProcess.c

```
/* Define Values */
#define NUM_OF_POINTS 10
/* Global Variables */
static int sigintFlag = 0;

/* Main Functions */
void getCoordinatesFromEnvVar (char *argp[], int * x_coordinates, int * y_coordinates, int * z_coordinates);
void calculateCovarianceMatrix (float covarianceMatrix[3][3], int * x_coordinates, int * y_coordinates, int * z_coordinates);
void writeCovarianceMatrixToFile (int writeFD, float covarianceMatrix[3][3]);
/* Helper Functions */
float getMean (int numbers[NUM_OF_POINTS]);
float getVariance (int numbers[NUM_OF_POINTS], float mean);
float getCovariance (int firstNumbers[NUM_OF_POINTS], int secondNumbers[NUM_OF_POINTS], float meanOfFirst, float meanOfSecond);
/* Signal Handler */
void initializeSignalHandler ();
void handleSignal (int signal);
void terminateChild (char * buffer);
```

#define

• NUM_OF_POINTS: Same define rule is used inside parentProcess.c. Same usage.

Global Variables

• sigintFlag: Same define rule is used inside parentProcess.c. Same usage

Functions

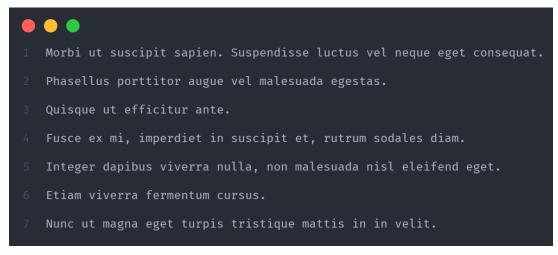
- getCoordinatesFromEnvVar: Since we give coordinat information via environment variables, this function, which called inside main, gets these coordinate values from command line argument argp and stores them inside int coordinate arrays (int x_coordinate[10] for example)
- calculateCovarianceMatrix: After storing coordinate values as int values, this function calculates covariance matrix of these coordinates and stores covariance matrix information inside given 2d array parameter covarianceMatrix[3][3]
- writeCovarianceMatrixToFile: When calculation is done, covariance matrix is written to outputFile(file information is not passed to the child process, only writeFD value is shared with argy).
- **getMean**: An int array is given as parameter and mean value of that array is returned as the result. It is done for every axis(x, y and z)
- **getVariance**: Same int array and mean value is given as parameter and after calculating variance result has returned. This calculation is done for every axis(x, y, z)
- getCovariance: Calculates covariance value of given two axis(XY, XZ and YZ).
- initializeSignalHandler: Same function is used inside parentProcess.c and works same.
- handleSignal: Works same as parentProcess.c
- **terminateChild**: Inside childProcess, terminateChild function doesn't close files, it only frees allocated variables and exits with failure.

!! After explaining every function, now I will show an example execution of the file. To imitate SIGINT signal call I placed sleep(1) functions inside both parentProcess.c and childProcess.c file. This can be done with also raise function but I thought giving SIGINT signal with ctrl+c is more realistic. Before submitting the homework, I will comment these sleep function calls. Inside second execution(with SIGINT interrupt) it can be seen that only one child received SIGINT call. It is because other 2 child processes already finished their job and terminated even though I put sleep function inside them.

!! Parent process first sends SIGINT signals to child processes with kill function call. After child processes terminate, it starts to terminate itself. Signals other then SIGINT are blocked with **sigprocmask** function at the start of parentProcess.c and childProcess.c when they call **initializeSignalHandler**.

Example Execution - Without SIGNAL Interrupt

(inputFile.dat)



```
tgknyhn@Tugkan:/mnt/c/Users/Tugkan/Desktop/hw2$ make withArgument
 gcc -ggdb3 -Wall childProcess.c file.c -o child && gcc -ggdb3 -Wall parentProcess.c file.c -o parent -lm && ./parent -i "inputFile.dat" -o "outputFile.dat"
 Process P reading inputFile.dat
Created R_0 with (77,111,114),(98,105,32),(117,116,32),(115,117,115),(99,105,112),(105,116,32),(115,97,112),(105,101,110),(46,32,83),(117,115,112) Created R_1 with (101,110,100),(105,115,115),(101,32,108),(117,99,116),(117,115,32),(118,101,108),(32,110,101),(113,117,101),(32,101,103),(101,116,32) Created R_2 with (99,111,110),(115,101,113),(117,97,116),(46,10,80),(104,97,115),(101,108,108),(117,115,32),(112,111,114),(116,116,105),(116,111,114) Created R_3 with (32,97,117),(103,117,101),(32,118,101),(108,32,109),(97,108,101),(115,117,97),(100,97,32),(101,103,101),(115,116,97),(115,46,10) Created R_4 with (81,117,105),(115,113,117),(101,32,117),(116,32,101),(102,102,105),(99,105,116),(117,114,32),(97,110,116),(101,46,10),(70,117,115) Created R_5 with (99,101,32),(101,120,32),(109,105,44),(32,105,109),(112,101,114),(100,105,101),(116,32,105),(110,32,115),(117,115,99),(105,112,105) Created R_6 with (116,32,101),(116,44,32),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,117,116),(114,111,116),(114,117,116),(114,111,116),(114,117,116),(114,117,116),(114,117,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,111,116),(114,11
 Created R 9 with (46,10,69),(116,105,97),(109,32,118),(105,118,101),(114,114,97),(32,102,101),(114,109,101),(110,116,117),(109,32,99),(117,114,115)
Created R 10 with (117,115,46),(10,78,117),(110,99,32),(117,116,32),(109,97,103),(110,97,32),(101,103,101),(116,32,116),(117,114,112),(105,115,32)
 Reached EOF, collecting outputs from outputFile.dat
  The closest 2 matrices are
 933.360046
                                                       -225.079987
                                                                                                           -368.979980
                                                                                                                                                                                       204.689987
                                                                                                                                                                                                                                             -165.220016
                                                                                                                                                                                                                                                                                                  -156.360001
  -225.079987
                                                     854.890015
                                                                                                         369.139984
                                                                                                                                                                                        -165.220016
                                                                                                                                                                                                                                            1198.159912
                                                                                                                                                                                                                                                                                                275.579987
                                                                                                                                                                                                                                            275.579987
   -368.979980
                                                     369.139984
                                                                                                          1132.040039
                                                                                                                                                                                         -156.360001
                                                                                                                                                                                                                                                                                                1365.439941
  and their distance is: 17.915
 tgknyhn@Tugkan:/mnt/c/Users/Tugkan/Desktop/hw2$
```

Example Execution - With SIGNINT Interrupt

```
452,440002 423,500000 -20,460007
423.500000 580.849976 -51.800007
-20.460007 -51.800007 1298.239990
420.809998 572.690002 89.090004
572.690002 897.409851 127.810013
89.090004 127.810013 625.010010
933.360046 -225.079987 -368.979980
-225.079987 854.890015 369.139984
-368.979980 369.139984 1132.040039
204.689987 -165.220016 -156.360001
-156.360001 275.579987 1365.439941
552.089966 -170.980011 -69.559982
-170.980011 957.559937 -399.579987
-69.559982 -399.579987 1086.440063
627.650024 -352.399994 -320.000000
-320.000000 657.740051 1531.359985
956.440063 -277.059998 -269.399994
29.409998 -0.780001 37.689995
-0.780001 1123.440063 -70.719994
37.689995 -70.719994 530.609985
868.559937 397.559967 215.500000
397.559967 1623.960083 231.000000
215.500000 231.000000 179.850006
951.559937 170.879990 -448.359955
170.879990 592.240051 -488.780029
-448.359955 -488.780029 1443.809814
```