Attribute Types

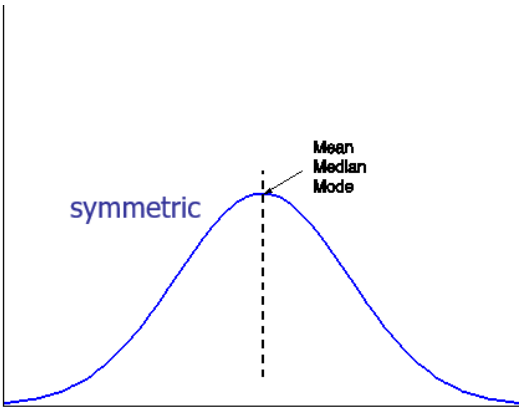
- **Nominal:** categories, states, or "names of things"
  - *Hair_color* = {*auburn, black, blond, brown, grey, red, white*}
  - marital status, occupation, ID numbers, zip codes
- **Binary**
  - Nominal attribute with only 2 states (0 and 1)
  - Symmetric binary: both outcomes equally important
    - e.g., gender
  - Asymmetric binary: outcomes not equally important.
    - e.g., medical test (positive vs. negative)
    - Convention: assign 1 to most important outcome (e.g., HIV positive)
- **Ordinal**
  - Values have a meaningful order (ranking) but magnitude between successive values is not known.
  - *Size* = {*small, medium, large*}, grades, army rankings

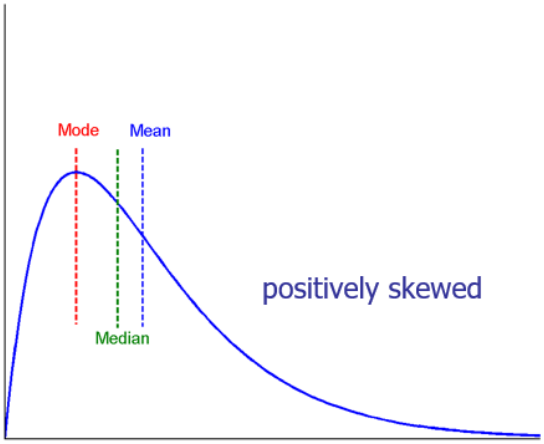
Numeric Attribute Types

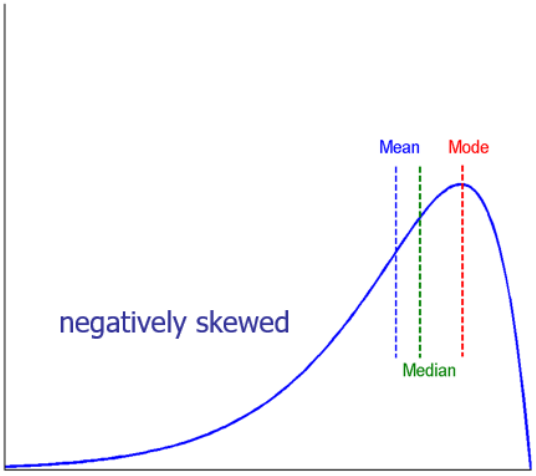
- Quantity (integer or real-valued)
- **Interval**
  - Measured on a scale of **equal-sized units**
  - Values have order
    - E.g., *temperature in C˚or F˚, calendar dates*
  - No true zero-point
- **Ratio**
  - Inherent **zero-point**
  - We can speak of values as being an order of magnitude larger than the unit of measurement (10 K˚ is twice as high as 5 K˚).
    - e.g., *temperature in Kelvin, length, counts, monetary quantities*

Symmetric vs. Skewed Da

- Median, mean and mode of symmetric, positively and negatively skewed data







Measuring the Dispersion of Data

- Quartiles, outliers and boxplots
  - **Quartiles**: Q_1 (25th percentile), Q_3 (75th percentile)
  - **Inter-quartile range**: IQR = $Q_3 - Q_1$
  - **Five number summary**: min, Q_1, median, Q_3, max
  - **Boxplot**: ends of the box are the quartiles; median is marked; add whiskers, and plot outliers individually
  - **Outlier**: usually, a value higher/lower than 1.5 x IQR
- Variance and standard deviation (*sample: s, population: σ)*
  - **Variance**: (algebraic, scalable computation)

$$s^2 = \frac{1}{n-1}\sum_{i=1}^{n}(x_i - \bar{x})^2 = \frac{1}{n-1}[\sum_{i=1}^{n}x_i^2 - \frac{1}{n}(\sum_{i=1}^{n}x_i)^2] \qquad \sigma^2 = \frac{1}{N}\sum_{i=1}^{n}(x_i - \mu)^2 = \frac{1}{N}\sum_{i=1}^{n}x_i^2 - \mu^2$$

  - **Standard deviation** *s (or σ)* is the square root of variance s^2 *(or* σ^2*)*

Major Tasks in Data Preprocessing

- **Data cleaning**
  - Fill in missing values, smooth noisy data, identify or remove outliers, and resolve inconsistencies
- **Data integration**
  - Integration of multiple databases, data cubes, or files
- **Data reduction**
  - Dimensionality reduction
  - Numerosity reduction
  - Data compression
- **Data transformation and data discretization**
  - Normalization
  - Concept hierarchy generation

Data Cleaning

- Data in the Real World Is Dirty: Lots of potentially incorrect data, e.g., instrument faulty, human or computer error, transmission error
  - incomplete: lacking attribute values, lacking certain attributes of interest, or containing only aggregate data
    - e.g., *Occupation*=" " (missing data)
  - noisy: containing noise, errors, or outliers
    - e.g., *Salary*="−10" (an error)
  - inconsistent: containing discrepancies in codes or names, e.g.,
    - *Age*="42", *Birthday*="03/07/2010"
    - Was rating "1, 2, 3", now rating "A, B, C"
    - discrepancy between duplicate records
  - Intentional (e.g., *disguised missing* data)
    - Jan. 1 as everyone's birthday?

How to Handle Missing Data?

- Ignore the tuple: usually done when class label is missing (when doing classification)—not effective when the % of missing values per attribute varies considerably
- Fill in the missing value manually: tedious + infeasible?
- Fill in it automatically with
  - a global constant : e.g., "unknown", a new class?!
  - the attribute mean
  - the attribute mean for all samples belonging to the same class: smarter
  - the most probable value: inference-based such as Bayesian formula or decision tree

How to Handle Noisy Data?

- Binning
  - first sort data and partition into (equal-frequency) bins
  - then one can smooth by bin means, smooth by bin median, smooth by bin boundaries, etc.
- Regression
  - smooth by fitting the data into regression functions
- Clustering
  - detect and remove outliers
- Combined computer and human inspection
  - detect suspicious values and check by human (e.g., deal with possible outliers)

Data Integration

Data integration:

- Combines data from multiple sources into a coherent store

Schema integration: e.g., A.cust-id ≡ B.cust-#

- Integrate metadata from different sources

Entity identification problem:

- Identify real world entities from multiple data sources, e.g., Bill Clinton = William Clinton

Detecting and resolving data value conflicts

- For the same real world entity, attribute values from different sources are different
- Possible reasons: different representations, different scales, e.g., metric vs. British units

Handling Redundancy in Data Integration

- Redundant data occur often when integration of multiple databases
  - *Object identification*: The same attribute or object may have different names in different databases
  - *Derivable data:* One attribute may be a "derived" attribute in another table, e.g., annual revenue
- Redundant attributes may be able to be detected by *correlation analysis* and *covariance analysis*
- Careful integration of the data from multiple sources may help reduce/avoid redundancies and inconsistencies and improve mining speed and quality

Correlation Analysis (Nominal Data)

- **X^2 (chi-square) test**

$$\chi^2 = \sum \frac{(Observed - Expected)^2}{Expected}$$

- The larger the X^2 value, the more likely the variables are related
- The cells that contribute the most to the X^2 value are those whose actual count is very different from the expected count
- Correlation does not imply causality
  - # of hospitals and # of car-theft in a city are correlated
  - Both are causally linked to the third variable: population

Covariance (Numeric Data)

- Covariance is similar to correlation

$$Cov(A, B) = E((A - \bar{A})(B - \bar{B})) = \frac{\sum_{i=1}^{n}(a_i - \bar{A})(b_i - \bar{B})}{n}$$

Correlation coefficient: $$r_{A,B} = \frac{Cov(A, B)}{\sigma_A \sigma_B}$$

where n is the number of tuples, $\bar{A}$ and $\bar{B}$ are the respective mean or **expected values** of A and B, σ_A and σ_B are the respective standard deviation of A and B.

- **Positive covariance**: If $Cov_{A,B} > 0$, then A and B both tend to be larger than their expected values.
- **Negative covariance**: If $Cov_{A,B} < 0$ then if A is larger than its expected value, B is likely to be smaller than its expected value.
- **Independence**: $Cov_{A,B} = 0$ but the converse is not true:
  - Some pairs of random variables may have a covariance of 0 but are not independent. Only under some additional assumptions (e.g., the data follow multivariate normal distributions) does a covariance of 0 imply independence

Data Reduction Strategies

- **Data reduction**: Obtain a reduced representation of the data set that is much smaller in volume but yet produces the same (or almost the same) analytical results
- Why data reduction? — A database/data warehouse may store terabytes of data. Complex data analysis may take a very long time to run on the complete data set.
- Data reduction strategies
  - Dimensionality reduction, e.g., remove unimportant attributes
    - Wavelet transforms
    - Principal Components Analysis (PCA)
    - Feature subset selection, feature creation
  - Numerosity reduction (some simply call it: Data Reduction)
    - Regression and Log-Linear Models
    - Histograms, clustering, sampling
    - Data cube aggregation
  - Data compression

Data Reduction 1: Dimensionality Reduction

- **Curse of dimensionality**
  - When dimensionality increases, data becomes increasingly sparse
  - Density and distance between points, which is critical to clustering, outlier analysis, becomes less meaningful
  - The possible combinations of subspaces will grow exponentially
- **Dimensionality reduction**
  - Avoid the curse of dimensionality
  - Help eliminate irrelevant features and reduce noise
  - Reduce time and space required in data mining
  - Allow easier visualization
- **Dimensionality reduction techniques**
  - Wavelet transforms
  - Principal Component Analysis
  - Supervised and nonlinear techniques (e.g., feature selection)

Data Reduction 2: Numerosity Reduction

- Reduce data volume by choosing alternative, *smaller forms* of data representation
- **Parametric methods** (e.g., regression)
  - Assume the data fits some model, estimate model parameters, store only the parameters, and discard the data (except possible outliers)
  - Ex.: Log-linear models—obtain value at a point in *m*-D space as the product on appropriate marginal subspaces
- **Non-parametric** methods
  - Do not assume models
  - Major families: histograms, clustering, sampling, …

Sampling

- Sampling: obtaining a small sample *s* to represent the whole data set *N*
- Allow a mining algorithm to run in complexity that is potentially sub-linear to the size of the data
- Key principle: Choose a representative subset of the data
  - Simple random sampling may have very poor performance in the presence of skew
  - Develop adaptive sampling methods, e.g., stratified sampling:
- Note: Sampling may not reduce database I/Os (page at a time)

Data Reduction 3: Data Compression

String compression

- There are extensive theories and well-tuned algorithms
- Typically lossless, but only limited manipulation is possible without expansion

Audio/video compression

- Typically lossy compression, with progressive refinement
- Sometimes small fragments of signal can be reconstructed without reconstructing the whole

Time sequence is not audio

- Typically short and vary slowly with time

Dimensionality and numerosity reduction may also be considered as forms of data compression

Data Transformation

A function that maps the entire set of values of a given attribute to a new set of replacement values s.t. each old value can be identified with one of the new values

Methods

- Smoothing: Remove noise from data
- Attribute/feature construction
  - New attributes constructed from the given ones
- Aggregation: Summarization, data cube construction
- Normalization: Scaled to fall within a smaller, specified range
  - min-max normalization
  - z-score normalization
  - normalization by decimal scaling
- Discretization: Concept hierarchy climbing

Normalization

- **Min-max normalization**: to [new_min$_A$, new_max$_A$]

$$v' = \frac{v - min_A}{max_A - min_A}(new\_max_A - new\_min_A) + new\_min_A$$

  - Ex. Let income range \$12,000 to \$98,000 normalized to [0.0, 1.0]. Then \$73,000 is mapped to $\frac{73{,}600 - 12{,}000}{98{,}000 - 12{,}000}(1.0 - 0) + 0 = 0.716$

- **Z-score normalization** (μ: mean, σ: standard deviation):

$$v' = \frac{v - \mu_A}{\sigma_A}$$

  - Ex. Let μ = 54,000, σ = 16,000. Then $\frac{73{,}600 - 54{,}000}{16{,}000} = 1.225$

- **Normalization by decimal scaling**

$$v' = \frac{v}{10^j}$$ Where j is the smallest integer such that Max(|v'|) < 1

Discretization

Three types of attributes

- Nominal—values from an unordered set, e.g., color, profession
- Ordinal—values from an ordered set, e.g., military or academic rank
- Numeric—real numbers, e.g., integer or real numbers

Discretization: Divide the range of a continuous attribute into intervals

- Interval labels can then be used to replace actual data values
- Reduce data size by discretization
- Supervised vs. unsupervised
- Split (top-down) vs. merge (bottom-up)
- Discretization can be performed recursively on an attribute
- Prepare for further analysis, e.g., classification

Supervised vs. Unsupervised Learning

- Supervised learning (classification)
  - Supervision: The training data (observations, measurements, etc.) are accompanied by **labels** indicating the class of the observations
  - New data is classified based on the training set
- Unsupervised learning (clustering)
  - The class labels of training data is unknown
  - Given a set of measurements, observations, etc. with the aim of establishing the existence of classes or clusters in the data

Prediction Problems: Classification vs. Numeric Prediction

- Classification
  - predicts categorical class labels (discrete or nominal)
  - classifies data (constructs a model) based on the training set and the values (class labels) in a classifying attribute and uses it in classifying new data
- Numeric Prediction
  - models continuous-valued functions, i.e., predicts unknown or missing values
- Typical applications
  - Credit/loan approval:
  - Medical diagnosis: if a tumor is cancerous or benign
  - Fraud detection: if a transaction is fraudulent
  - Web page categorization: which category it is

Classification—A Two-Step Process

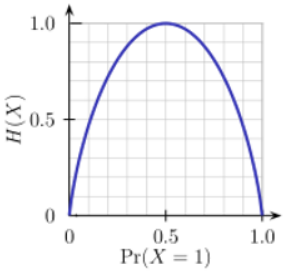
- Model construction: describing a set of predetermined classes
  - Each tuple/sample is assumed to belong to a predefined class, as determined by the class label attribute
  - The set of tuples used for model construction is training set
  - The model is represented as classification rules, decision trees, or mathematical formulae
- Model usage: for classifying future or unknown objects
  - Estimate accuracy of the model
    - The known label of test sample is compared with the classified result from the model
    - Accuracy rate is the percentage of test set samples that are correctly classified by the model
    - Test set is independent of training set (otherwise overfitting)
  - If the accuracy is acceptable, use the model to classify new data
- Note: If *the test set* is used to select models, it is called validation (test) set

Algorithm for Decision Tree Induction

- Basic algorithm (a greedy algorithm)
  - Tree is constructed in a top-down recursive divide-and-conquer manner
  - At start, all the training examples are at the root
  - Attributes are categorical (if continuous-valued, they are discretized in advance)
  - Examples are partitioned recursively based on selected attributes
  - Test attributes are selected on the basis of a heuristic or statistical measure (e.g., information gain)
- Conditions for stopping partitioning
  - All samples for a given node belong to the same class
  - There are no remaining attributes for further partitioning – majority voting is employed for classifying the leaf
  - There are no samples left

Brief Review of Entropy

- Entropy (Information Theory)
  - A measure of uncertainty associated with a random variable
  - Calculation: For a discrete random variable *Y* taking *m* distinct values $\{y_1, \ldots, y_m\}$,
    - $H(Y) = -\sum_{i=1}^{m} p_i \log(p_i)$, where $p_i = P(Y = y_i)$
  - Interpretation:
    - Higher entropy => higher uncertainty
    - Lower entropy => lower uncertainty
- Conditional Entropy
  - $H(Y|X) = \sum_x p(x) H(Y|X = x)$



m = 2

Attribute Selection Measure: Information Gain (ID3/C4.5)

- Select the attribute with the highest information gain
- Let p_i be the probability that an arbitrary tuple in D belongs to class C_i, estimated by $|C_{i,D}|/|D|$
- Expected information (entropy) needed to classify a tuple in D:

$$Info(D) = -\sum_{i=1}^{m} p_i \log_2(p_i)$$

- Information needed (after using A to split D into v partitions) to classify D:

$$Info_A(D) = \sum_{j=1}^{v} \frac{|D_j|}{|D|} \times Info(D_j)$$

- Information gained by branching on attribute A

$$Gain(A) = Info(D) - Info_A(D)$$

Attribute Selection: Information Gain

- Class P: buys_computer = "yes"
- Class N: buys_computer = "no"

$$Info(D) = I(9,5) = -\frac{9}{14}\log_2(\frac{9}{14}) - \frac{5}{14}\log_2(\frac{5}{14}) = 0.940$$

age	p_i	n_i	$I(p_i, n_i)$
<=30	2	3	0.971
31…40	4	0	0
>40	3	2	0.971

age	income	student	credit_rating	buys_computer
<=30	high	no	fair	no
<=30	high	no	excellent	no
31… 40	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
31… 40	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
31… 40	medium	no	excellent	yes
31… 40	high	yes	fair	yes
>40	medium	no	excellent	no

$$Info_{age}(D) = \frac{5}{14}I(2,3) + \frac{4}{14}I(4,0) + \frac{5}{14}I(3,2) = 0.694$$

$\frac{5}{14}I(2,3)$ means "age <=30" has 5 out of 14 samples, with 2 yes'es and 3 no's. Hence

$$Gain(age) = Info(D) - Info_{age}(D) = 0.246$$

Similarly,

$$Gain(income) = 0.029$$
$$Gain(student) = 0.151$$
$$Gain(credit\_rating) = 0.048$$

Computing Information-Gain for Continuous-Valued Attributes

- Let attribute A be a continuous-valued attribute
- Must determine the *best split point* for A
  - Sort the value A in increasing order
  - Typically, the midpoint between each pair of adjacent values is considered as a possible *split point*
    - $(a_i+a_{i+1})/2$ is the midpoint between the values of a_i and a_{i+1}
  - The point with the *minimum expected information requirement* for A is selected as the split-point for A
- Split:
  - D1 is the set of tuples in D satisfying A ≤ split-point, and D2 is the set of tuples in D satisfying A > split-point

Gain Ratio for Attribute Selection (C4.5)

- Information gain measure is biased towards attributes with a large number of values
- C4.5 (a successor of ID3) uses gain ratio to overcome the problem (normalization to information gain)

$$SplitInfo_A(D) = -\sum_{j=1}^{v} \frac{|D_j|}{|D|} \times \log_2\left(\frac{|D_j|}{|D|}\right)$$

  - GainRatio(A) = Gain(A)/SplitInfo(A)
- Ex.

$$SplitInfo_{income}(D) = -\frac{4}{14} \times \log_2\left(\frac{4}{14}\right) - \frac{6}{14} \times \log_2\left(\frac{6}{14}\right) - \frac{4}{14} \times \log_2\left(\frac{4}{14}\right) = 1.557$$

  - gain_ratio(income) = 0.029/1.557 = 0.019
- The attribute with the maximum gain ratio is selected as the splitting attribute

Gini Index (CART, IBM IntelligentMiner)

- If a data set *D* contains examples from *n* classes, gini index, *gini*(*D*) is defined as

$$gini(D) = 1 - \sum_{j=1}^{n} p_j^2$$

  where p_j is the relative frequency of class *j* in *D*

- If a data set *D* is split on A into two subsets D_1 and D_2, the *gini* index *gini*(*D*) is defined as

$$gini_A(D) = \frac{|D_1|}{|D|} gini(D_1) + \frac{|D_2|}{|D|} gini(D_2)$$

- Reduction in Impurity:

$$\Delta gini(A) = gini(D) - gini_A(D)$$

- The attribute provides the smallest $gini_{split}(D)$ (or the largest reduction in impurity) is chosen to split the node (*need to enumerate all the possible splitting points for each attribute*)

Comparing Attribute Selection Measures

The three measures, in general, return good results but

- **Information gain**:
  - biased towards multivalued attributes
- **Gain ratio**:
  - tends to prefer unbalanced splits in which one partition is much smaller than the others
- **Gini index**:
  - biased to multivalued attributes
  - has difficulty when # of classes is large
  - tends to favor tests that result in equal-sized partitions and purity in both partitions

Overfitting and Tree Pruning

Overfitting: An induced tree may overfit the training data

- Too many branches, some may reflect anomalies due to noise or outliers
- Poor accuracy for unseen samples

Two approaches to avoid overfitting

- Prepruning: *Halt tree construction early*-do not split a node if this would result in the goodness measure falling below a threshold
  - Difficult to choose an appropriate threshold
- Postpruning: *Remove branches* from a "fully grown" tree—get a sequence of progressively pruned trees
  - Use a set of data different from the training data to decide which is the "best pruned tree"

Enhancements to Basic Decision Tree Induction

- Allow for **continuous-valued attributes**
  - Dynamically define new discrete-valued attributes that partition the continuous attribute value into a discrete set of intervals
- Handle **missing attribute values**
  - Assign the most common value of the attribute
  - Assign probability to each of the possible values
- **Attribute construction**
  - Create new attributes based on existing ones that are sparsely represented
  - This reduces fragmentation, repetition, and replication

Why is decision tree induction popular?

- relatively faster learning speed (than other classification methods)
- convertible to simple and easy to understand classification rules
- can use SQL queries for accessing databases
- comparable classification accuracy with other methods

Bayesian Classification: Why?

- A statistical classifier: performs *probabilistic prediction, i.e.,* predicts class membership probabilities
- Foundation: Based on Bayes' Theorem.
- Performance: A simple Bayesian classifier, *naïve Bayesian classifier*, has comparable performance with decision tree and selected neural network classifiers
- Incremental: Each training example can incrementally increase/decrease the probability that a hypothesis is correct — prior knowledge can be combined with observed data
- Standard: Even when Bayesian methods are computationally intractable, they can provide a standard of optimal decision making against which other methods can be measured

Bayes' Theorem: Basics

Total probability Theorem: $P(B) = \sum_{i=1}^{M} P(B|A_i)P(A_i)$

Bayes' Theorem: $P(H|\mathbf{X}) = \frac{P(\mathbf{X}|H)P(H)}{P(\mathbf{X})} = P(\mathbf{X}|H) \times P(H) / P(\mathbf{X})$

- Let **X** be a data sample ("*evidence*"): class label is unknown
- Let H be a *hypothesis* that X belongs to class C
- Classification is to determine P(H|**X**), (i.e., *posteriori probability):* the probability that the hypothesis holds given the observed data sample **X**
- P(H) (*prior probability*): the initial probability
  - E.g., **X** will buy computer, regardless of age, income, …
- P(**X**): probability that sample data is observed
- P(**X**|H) (likelihood): the probability of observing the sample **X**, given that the hypothesis holds
  - E.g., Given that **X** will buy computer, the prob. that X is 31..40, medium income

Prediction Based on Bayes' Theorem

Given training data **X**, *posteriori probability of a hypothesis* H, P(H|**X**), follows the Bayes' theorem

$$P(H|\mathbf{X}) = \frac{P(\mathbf{X}|H)P(H)}{P(\mathbf{X})} = P(\mathbf{X}|H) \times P(H) / P(\mathbf{X})$$

Informally, this can be viewed as

posteriori = likelihood x prior/evidence

Predicts **X** belongs to C_i iff the probability $P(C_i|\mathbf{X})$ is the highest among all the $P(C_k|X)$ for all the *k* classes

Practical difficulty: It requires initial knowledge of many probabilities, involving significant computational cost

Classification Is to Derive the Maximum Posteriori

- Let D be a training set of tuples and their associated class labels, and each tuple is represented by an n-D attribute vector **X** = (x_1, x_2, …, x_n)
- Suppose there are *m* classes C_1, C_2, …, C_m.
- Classification is to derive the maximum posteriori, i.e., the maximal $P(C_i|\mathbf{X})$
- This can be derived from Bayes' theorem

$$P(C_i|\mathbf{X}) = \frac{P(\mathbf{X}|C_i)P(C_i)}{P(\mathbf{X})}$$

- Since P(X) is constant for all classes, only

$$P(C_i|\mathbf{X}) = P(\mathbf{X}|C_i)P(C_i)$$

needs to be maximized

Naïve Bayes Classifier

A simplified assumption: attributes are conditionally independent (i.e., no dependence relation between attributes):

$$P(\mathbf{X}|C_i) = \prod_{k=1}^{n} P(x_k|C_i) = P(x_1|C_i) \times P(x_2|C_i) \times \ldots \times P(x_n|C_i)$$

This greatly reduces the computation cost: Only counts the class distribution

If A_k is categorical, $P(x_k|C_i)$ is the # of tuples in C_i having value x_k for A_k divided by $|C_{i,D}|$ (# of tuples of C_i in D)

If A_k is continous-valued, $P(x_k|C_i)$ is usually computed based on Gaussian distribution with a mean μ and standard deviation σ

and $P(x_k|C_i)$ is

$$g(x, \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$P(\mathbf{X}|C_i) = g(x_k, \mu_{C_i}, \sigma_{C_i})$$

Naïve Bayes Classifier: Training Dataset

Class:
C1:buys_computer = 'yes'
C2:buys_computer = 'no'

Data to be classified:
X = (age <=30,
Income = medium,
Student = yes
Credit_rating = Fair)

age	income	student	credit_rating	com
<=30	high	no	fair	no
<=30	high	no	excellent	no
31…40	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
31…40	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
31…40	medium	no	excellent	yes
31…40	high	yes	fair	yes
>40	medium	no	excellent	no

Naïve Bayes Classifier: An Example

age	income	student	credit_rating	com
<=30	high	no	fair	no
<=30	high	no	excellent	no
31…40	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
31…40	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
31…40	medium	no	excellent	yes
31…40	high	yes	fair	yes
>40	medium	no	excellent	no

- $P(C_i)$: P(buys_computer = "yes") = 9/14 = 0.643
  P(buys_computer = "no") = 5/14= 0.357
- Compute $P(X|C_i)$ for each class
  P(age = "<=30" | buys_computer = "yes") = 2/9 = 0.222
  P(age = "<= 30" | buys_computer = "no") = 3/5 = 0.6
  P(income = "medium" | buys_computer = "yes") = 4/9 = 0.444
  P(income = "medium" | buys_computer = "no") = 2/5 = 0.4
  P(student = "yes" | buys_computer = "yes) = 6/9 = 0.667
  P(student = "yes" | buys_computer = "no") = 1/5 = 0.2
  P(credit_rating = "fair" | buys_computer = "yes") = 6/9 = 0.667
  P(credit_rating = "fair" | buys_computer = "no") = 2/5 = 0.4
- **X = (age <= 30 , income = medium, student = yes, credit_rating = fair)**

$P(X|C_i)$: P(X|buys_computer = "yes") = 0.222 x 0.444 x 0.667 x 0.667 = 0.044
P(X|buys_computer = "no") = 0.6 x 0.4 x 0.2 x 0.4 = 0.019

$P(X|C_i)*P(C_i)$: P(X|buys_computer = "yes") * P(buys_computer = "yes") = 0.028
P(X|buys_computer = "no") * P(buys_computer = "no") = 0.007

Therefore, X belongs to class ("buys_computer = yes")

Avoiding the Zero-Probability Problem

- Naïve Bayesian prediction requires each conditional prob. be **non-zero**. Otherwise, the predicted prob. will be zero

$$P(X \mid C_i) = \prod_{k=1}^{n} P(x_k \mid C_i)$$

- Ex. Suppose a dataset with 1000 tuples, income=low (0), income= medium (990), and income = high (10)
- Use **Laplacian correction** (or Laplacian estimator)
  - *Adding 1 to each case*

    Prob(income = low) = 1/1003

    Prob(income = medium) = 991/1003

    Prob(income = high) = 11/1003
  - The "corrected" prob. estimates are close to their "uncorrected" counterparts

Naïve Bayes Classifier: Comments

- Advantages
  - Easy to implement
  - Good results obtained in most of the cases
- Disadvantages
  - Assumption: class conditional independence, therefore loss of accuracy
  - Practically, dependencies exist among variables
    - E.g., hospitals: patients: Profile: age, family history, etc.
      Symptoms: fever, cough etc., Disease: lung cancer, diabetes, etc.
    - Dependencies among these cannot be modeled by Naïve Bayes Classifier
- How to deal with these dependencies? Bayesian Belief Networks (Chapter 9)

Model Evaluation and Selection

- Evaluation metrics: How can we measure accuracy? Other metrics to consider?
- Use **validation test set** of class-labeled tuples instead of training set when assessing accuracy
- Methods for estimating a classifier's accuracy:
  - Holdout method, random subsampling
  - Cross-validation
  - Bootstrap
- Comparing classifiers:
  - Confidence intervals
  - Cost-benefit analysis and ROC Curves

Classifier Evaluation Metrics: Confusion Matrix

Confusion Matrix:

Actual class\Predicted class	C_1	$\neg C_1$
C_1	**True Positives (TP)**	**False Negatives (FN)**
$\neg C_1$	**False Positives (FP)**	**True Negatives (TN)**

Example of Confusion Matrix:

Actual class\Predicted class	buy_computer = yes	buy_computer = no	Total
buy_computer = yes	**6954**	**46**	7000
buy_computer = no	**412**	**2588**	3000
Total	7366	2634	10000

- Given *m* classes, an entry, $\boldsymbol{CM_{i,j}}$ in a **confusion matrix** indicates # of tuples in class *i* that were labeled by the classifier as class *j*
- May have extra rows/columns to provide totals

Classifier Evaluation Metrics: Accuracy, Error Rate, Sensitivity and Specificity

A\P	C	¬C	
C	**TP**	**FN**	**P**
¬C	**FP**	**TN**	**N**
	P'	**N'**	**All**

- **Classifier Accuracy,** or recognition rate: percentage of test set tuples that are correctly classified

  Accuracy = (TP + TN)/All
- **Error rate:** *1 – accuracy*, or

  Error rate = (FP + FN)/All

- **Class Imbalance Problem**:
  - One class may be *rare*, e.g. fraud, or HIV-positive
  - Significant *majority of the negative class* and minority of the positive class
  - **Sensitivity**: True Positive recognition rate
    - **Sensitivity = TP/P**
  - **Specificity**: True Negative recognition rate
    - **Specificity = TN/N**

Classifier Evaluation Metrics: Precision and Recall, and F-measures

- **Precision**: exactness – what % of tuples that the classifier labeled as positive are actually positive

$$precision = \frac{TP}{TP + FP}$$

- **Recall:** completeness – what % of positive tuples did the classifier label as positive?
- Perfect score is 1.0

$$recall = \frac{TP}{TP + FN}$$

- Inverse relationship between precision & recall
- ***F* measure (*F_1* or *F*-score)**: harmonic mean of precision and recall,

$$F = \frac{2 \times precision \times recall}{precision + recall}$$

- ***F_β*:** weighted measure of precision and recall
  - assigns ß times as much weight to recall as to precision

$$F_\beta = \frac{(1 + \beta^2) \times precision \times recall}{\beta^2 \times precision + recall}$$

Evaluating Classifier Accuracy: Holdout & Cross-Validation Methods

- **Holdout method**
  - Given data is randomly partitioned into two independent sets
    - Training set (e.g., 2/3) for model construction
    - Test set (e.g., 1/3) for accuracy estimation
  - Random sampling: a variation of holdout
    - Repeat holdout k times, accuracy = avg. of the accuracies obtained
- **Cross-validation** (*k*-fold, where k = 10 is most popular)
  - Randomly partition the data into *k mutually exclusive* subsets, each approximately equal size
  - At *i*-th iteration, use D_i as test set and others as training set
  - Leave-one-out: *k* folds where *k* = # of tuples, for small sized data
  - ***Stratified cross-validation***: folds are stratified so that class dist. in each fold is approx. the same as that in the initial data

Evaluating Classifier Accuracy: Bootstrap

- **Bootstrap**
  - Works well with small data sets
  - Samples the given training tuples uniformly *with replacement*
    - i.e., each time a tuple is selected, it is equally likely to be selected again and re-added to the training set
- Several bootstrap methods, and a common one is **.632 boostrap**
  - A data set with *d* tuples is sampled *d* times, with replacement, resulting in a training set of *d* samples. The data tuples that did not make it into the training set end up forming the test set. About 63.2% of the original data end up in the bootstrap, and the remaining 36.8% form the test set (since $(1 - 1/d)^d \approx e^{-1} = 0.368$)
  - Repeat the sampling procedure *k* times, overall accuracy of the model:

$$Acc(M) = \frac{1}{k}\sum_{i=1}^{k}(0.632 \times Acc(M_i)_{test\_set} + 0.368 \times Acc(M_i)_{train\_set})$$

Estimating Confidence Intervals: Classifier Models M_1 vs. M_2

- Suppose we have 2 classifiers, M_1 and M_2, which one is better?
- Use 10-fold cross-validation to obtain $\overline{err}(M_1)$ and $\overline{err}(M_2)$
- These mean error rates are just *estimates* of error on the true population of *future* data cases
- What if the difference between the 2 error rates is just attributed to *chance*?
  - Use a **test of statistical significance**
  - Obtain **confidence limits** for our error estimates

Estimating Confidence Intervals: Null Hypothesis

- Perform 10-fold cross-validation
- Assume samples follow a **t distribution** with *k–1* **degrees of freedom** (here, *k=10*)
- Use **t-test** (or **Student's t-test**)
- **Null Hypothesis**: M_1 & M_2 are the same
- If we can **reject** null hypothesis, then
  - we conclude that the difference between M_1 & M_2 is **statistically significant**
  - Chose model with lower error rate

Estimating Confidence Intervals: t-test

If only 1 test set available: **pairwise comparison**

- For i^{th} round of 10-fold cross-validation, the same cross partitioning is used to obtain $err(M_1)_i$ and $err(M_2)_i$
- Average over 10 rounds to get $\overline{err}(M_1)$ and $\overline{err}(M_2)$
- **t-test** computes **t-statistic** with *k-1* **degrees of freedom:**

$$t = \frac{\overline{err}(M_1) - \overline{err}(M_2)}{\sqrt{var(M_1 - M_2)/k}}$$ where

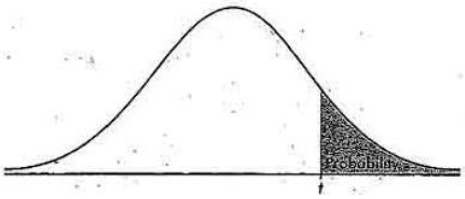
$$var(M_1 - M_2) = \frac{1}{k}\sum_{i=1}^{k}\left[err(M_1)_i - err(M_2)_i - (\overline{err}(M_1) - \overline{err}(M_2))\right]^2$$

If two test sets available: use **non-paired t-test**

where $$var(M_1 - M_2) = \sqrt{\frac{var(M_1)}{k_1} + \frac{var(M_2)}{k_2}},$$

where k_1 & k_2 are # of cross-validation samples used for M_1 & M_2, resp.

Estimating Confidence Intervals: Table for t-distribution



- Symmetric
- **Significance level**, e.g., *sig = 0.05* or *5%* means M_1 & M_2 are *significantly different* for 95% of population
- **Confidence limit**, *z = sig/2*

TABLE B: *t*-DISTRIBUTION CRITICAL VALUES

	Tail probability *p*											
df	.25	.20	.15	.10	.05	.025	.02	.01	.005	.0025	.001	.0005
1	1.000	1.376	1.963	3.078	6.314	12.71	15.89	31.82	63.66	127.3	318.3	636.6
2	.816	1.061	1.386	1.886	2.920	4.303	4.849	6.965	9.925	14.09	22.33	31.60
3	.765	.978	1.250	1.638	2.353	3.182	3.482	4.541	5.841	7.453	10.21	12.92
4	.741	.941	1.190	1.533	2.132	2.776	2.999	3.747	4.604	5.598	7.173	8.610
5	.727	.920	1.156	1.476	2.015	2.571	2.757	3.365	4.032	4.773	5.893	6.869
6	.718	.906	1.134	1.440	1.943	2.447	2.612	3.143	3.707	4.317	5.208	5.959
7	.711	.896	1.119	1.415	1.895	2.365	2.517	2.998	3.499	4.029	4.785	5.408
8	.706	.889	1.108	1.397	1.860	2.306	2.449	2.896	3.355	3.833	4.501	5.041
9	.703	.883	1.100	1.383	1.833	2.262	2.398	2.821	3.250	3.690	4.297	4.781
10	.700	.879	1.093	1.372	1.812	2.228	2.359	2.764	3.169	3.581	4.144	4.587
11	.697	.876	1.088	1.363	1.796	2.201	2.328	2.718	3.106	3.497	4.025	4.437
12	.695	.873	1.083	1.356	1.782	2.179	2.303	2.681	3.055	3.428	3.930	4.318
13	.694	.870	1.079	1.350	1.771	2.160	2.282	2.650	3.012	3.372	3.852	4.221
14	.692	.868	1.076	1.345	1.761	2.145	2.264	2.624	2.977	3.326	3.787	4.140
15	.691	.866	1.074	1.341	1.753	2.131	2.249	2.602	2.947	3.286	3.733	4.073
16	.690	.865	1.071	1.337	1.746	2.120	2.235	2.583	2.921	3.252	3.686	4.015
17	.689	.863	1.069	1.333	1.740	2.110	2.224	2.567	2.898	3.222	3.646	3.965
18	.688	.862	1.067	1.330	1.734	2.101	2.214	2.552	2.878	3.197	3.611	3.922
19	.688	.861	1.066	1.328	1.729	2.093	2.205	2.539	2.861	3.174	3.579	3.883
20	.687	.860	1.064	1.325	1.725	2.086	2.197	2.528	2.845	3.153	3.552	3.850
21	.686	.859	1.063	1.323	1.721	2.080	2.189	2.518	2.831	3.135	3.527	3.819
22	.686	.858	1.061	1.321	1.717	2.074	2.183	2.508	2.819	3.119	3.505	3.792
23	.685	.858	1.060	1.319	1.714	2.069	2.177	2.500	2.807	3.104	3.485	3.768
24	.685	.857	1.059	1.318	1.711	2.064	2.172	2.492	2.797	3.091	3.467	3.745
25	.684	.856	1.058	1.316	1.708	2.060	2.167	2.485	2.787	3.078	3.450	3.725
26	.684	.856	1.058	1.315	1.706	2.056	2.162	2.479	2.779	3.067	3.435	3.707
27	.684	.855	1.057	1.314	1.703	2.052	2.158	2.473	2.771	3.057	3.421	3.690
28	.683	.855	1.056	1.313	1.701	2.048	2.154	2.467	2.763	3.047	3.408	3.674
29	.683	.854	1.055	1.311	1.699	2.045	2.150	2.462	2.756	3.038	3.396	3.659
30	.683	.854	1.055	1.310	1.697	2.042	2.147	2.457	2.750	3.030	3.385	3.646
40	.681	.851	1.050	1.303	1.684	2.021	2.123	2.423	2.704	2.971	3.307	3.551
50	.679	.849	1.047	1.299	1.676	2.009	2.109	2.403	2.678	2.937	3.261	3.496
60	.679	.848	1.045	1.296	1.671	2.000	2.099	2.390	2.660	2.915	3.232	3.460
80	.678	.846	1.043	1.292	1.664	1.990	2.088	2.374	2.639	2.887	3.195	3.416
100	.677	.845	1.042	1.290	1.660	1.984	2.081	2.364	2.626	2.871	3.174	3.390
1000	.675	.842	1.037	1.282	1.646	1.962	2.056	2.330	2.581	2.813	3.098	3.300
∞	.674	.841	1.036	1.282	1.645	1.960	2.054	2.326	2.576	2.807	3.091	3.291
	50%	60%	70%	80%	90%	95%	96%	98%	99%	99.5%	99.8%	99.9%
	Confidence level *C*											

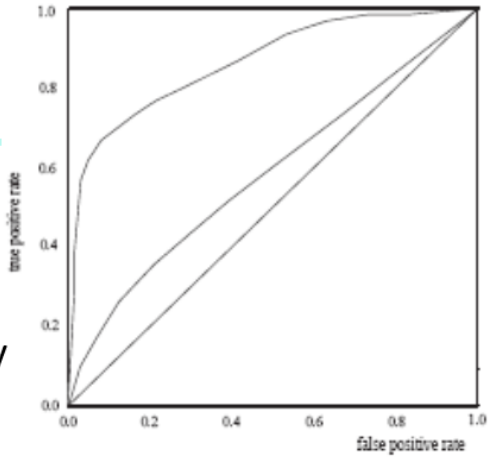
Estimating Confidence Intervals: Statistical Significance

Are M_1 & M_2 **significantly different**?

- Compute *t.* Select *significance level* (e.g. *sig = 5%)*
- Consult table for t-distribution: Find *t value* corresponding to *k-1 degrees of freedom* (here, 9)
- t-distribution is symmetric: typically upper % points of distribution shown → look up value for **confidence limit** *z=sig/2* (here, 0.025)
- **If t > z or t < -z**, then t value lies in rejection region:
  - **Reject null hypothesis** that mean error rates of M_1 & M_2 are same
  - Conclude: statistically significant difference between M_1 & M_2
- **Otherwise**, conclude that any difference is **chance**

Model Selection: ROC Curves

- **ROC** (Receiver Operating Characteristics) curves: for visual comparison of classification models
- Originated from signal detection theory
- Shows the trade-off between the true positive rate and the false positive rate
- The area under the ROC curve is a measure of the accuracy of the model
- Rank the test tuples in decreasing order: the one that is most likely to belong to the positive class appears at the top of the list
- The closer to the diagonal line (i.e., the closer the area is to 0.5), the less accurate is the model

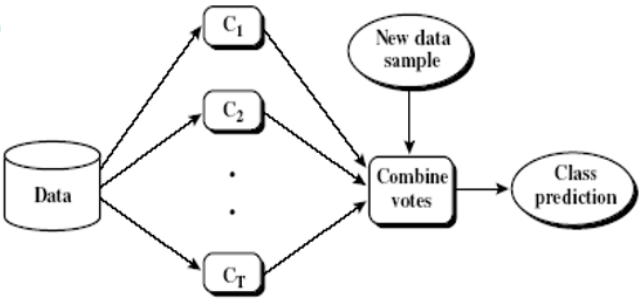


- Vertical axis represents the true positive rate
- Horizontal axis rep. the false positive rate
- The plot also shows a diagonal line
- A model with perfect accuracy will have an area of 1.0

Issues Affecting Model Selection

- **Accuracy**
  - classifier accuracy: predicting class label
- **Speed**
  - time to construct the model (training time)
  - time to use the model (classification/prediction time)
- **Robustness**: handling noise and missing values
- **Scalability**: efficiency in disk-resident databases
- **Interpretability**
  - understanding and insight provided by the model
- Other measures, e.g., goodness of rules, such as decision tree size or compactness of classification rules

Ensemble Methods: Increasing the Accuracy



- Ensemble methods
  - Use a combination of models to increase accuracy
  - Combine a series of k learned models, M_1, M_2, …, M_k, with the aim of creating an improved model M*
- Popular ensemble methods
  - Bagging: averaging the prediction over a collection of classifiers
  - Boosting: weighted vote with a collection of classifiers
  - Ensemble: combining a set of heterogeneous classifiers

Bagging: Boostrap Aggregation

Analogy: Diagnosis based on multiple doctors' majority vote

Training

- Given a set D of *d* tuples, at each iteration *i*, a training set D_i of *d* tuples is sampled with replacement from D (i.e., bootstrap)
- A classifier model M_i is learned for each training set D_i

Classification: classify an unknown sample **X**

- Each classifier M_i returns its class prediction
- The bagged classifier M* counts the votes and assigns the class with the most votes to **X**

Prediction: can be applied to the prediction of continuous values by taking the average value of each prediction for a given test tuple

Accuracy

- Often significantly better than a single classifier derived from D
- For noise data: not considerably worse, more robust
- Proved improved accuracy in prediction

Boosting

Analogy: Consult several doctors, based on a combination of weighted diagnoses—weight assigned based on the previous diagnosis accuracy

How boosting works?

- **Weights** are assigned to each training tuple
- A series of k classifiers is iteratively learned
- After a classifier M_i is learned, the weights are updated to allow the subsequent classifier, M_{i+1}, to **pay more attention to the training tuples that were misclassified** by M_i
- The final **M* combines the votes** of each individual classifier, where the weight of each classifier's vote is a function of its accuracy

Boosting algorithm can be extended for numeric prediction

Comparing with bagging: Boosting tends to have greater accuracy, but it also risks overfitting the model to misclassified data

Adaboost (Freund and Schapire, 1997)

Given a set of *d* class-labeled tuples, ($\mathbf{X_1}$, y_1), …, ($\mathbf{X_d}$, y_d)

Initially, all the weights of tuples are set the same (1/d)

Generate k classifiers in k rounds. At round i,

- Tuples from D are sampled (with replacement) to form a training set D_i of the same size
- Each tuple's chance of being selected is based on its weight
- A classification model M_i is derived from D_i
- Its error rate is calculated using D_i as a test set
- If a tuple is misclassified, its weight is increased, o.w. it is decreased

Error rate: err($\mathbf{X_j}$) is the misclassification error of tuple $\mathbf{X_j}$. Classifier M_i error rate is the sum of the weights of the misclassified tuples:

$$error\ (M_i) = \sum_{j}^{d} w_j \times err\ (\mathbf{X_j})$$

The weight of classifier M_i's vote is $\log \frac{1 - error(M_i)}{error(M_i)}$

Random Forest (Breiman 2001)

Random Forest:

- Each classifier in the ensemble is a *decision tree* classifier and is generated using a random selection of attributes at each node to determine the split
- During classification, each tree votes and the most popular class is returned

Two Methods to construct Random Forest:

- Forest-RI (*random input selection*): Randomly select, at each node, F attributes as candidates for the split at the node. The CART methodology is used to grow the trees to maximum size
- Forest-RC (*random linear combinations*): Creates new attributes (or features) that are a linear combination of the existing attributes (reduces the correlation between individual classifiers)

Comparable in accuracy to Adaboost, but more robust to errors and outliers

Insensitive to the number of attributes selected for consideration at each split, and faster than bagging or boosting

Classification of Class-Imbalanced Data Sets

- Class-imbalance problem: Rare positive example but numerous negative ones, e.g., medical diagnosis, fraud, oil-spill, fault, etc.
- Traditional methods assume a balanced distribution of classes and equal error costs: not suitable for class-imbalanced data
- Typical methods for imbalance data in 2-class classification:
  - **Oversampling**: re-sampling of data from positive class
  - **Under-sampling**: randomly eliminate tuples from negative class
  - **Threshold-moving**: moves the decision threshold, t, so that the rare class tuples are easier to classify, and hence, less chance of costly false negative errors
  - Ensemble techniques: Ensemble multiple classifiers introduced above
- Still difficult for class imbalance problem on multiclass tasks