

**A7106****Preliminary****2.4G FSK/GFSK Transceiver**

Document Title

A7106 Data Sheet, 2.4GHz FSK/GFSK Transceiver with 500Kbps data rate

Revision History

<u>Rev. No.</u>	<u>History</u>	<u>Issue Date</u>	<u>Remark</u>
0.0	Initial issue.	Aug., 2009	Objective
0.1	Add chapter 11, add 15.5 RSSI calibration	Feb., 2010	Preliminary

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A7106

Preliminary

2.4G FSK/GFSK Transceiver

Table of Contents

1. General Description.....	5
2. Typical Applications	5
3. Feature	5
4. Pin Configurations	6
5. Pin Description (I: input; O: output, I/O: input or output).....	7
6. Chip Block Diagram.....	8
7. Absolute Maximum Ratings.....	9
8. Electrical Specification	10
9. Control Register	12
9.1 Control register table.....	12
9.2 Control register description	14
9.2.1 Mode Register (Address: 00h).....	14
9.2.2 Mode Control Register (Address: 01h).....	14
9.2.3 Calibration Control Register (Address: 02h).....	15
9.2.4 FIFO Register I (Address: 03h).....	15
9.2.5 FIFO Register II (Address: 04h).....	15
9.2.6 FIFO DATA Register (Address: 05h)	16
9.2.7 ID DATA Register (Address: 06h).....	16
9.2.8 RC OSC Register I (Address: 07h)	16
9.2.9 RC OSC Register II (Address: 08h).....	16
9.2.10 RC OSC Register III (Address: 09h).....	16
9.2.11 CKO Pin Control Register (Address: 0Ah)	17
9.2.12 GIO1 Pin Control Register I (Address: 0Bh).....	17
9.2.13 GIO2 Pin Control Register II (Address: 0Ch)	18
9.2.14 Clock Register (Address: 0Dh).....	19
9.2.15 Data Rate Register (Address: 0Eh)	20
9.2.16 PLL Register I (Address: 0Fh).....	20
9.2.17 PLL Register II (Address: 10h).....	20
9.2.18 PLL Register III (Address: 11h)	20
9.2.19 PLL Register IV (Address: 12h).....	21
9.2.20 PLL Register V (Address: 13h).....	21
9.2.21 TX Register I (Address: 14h).....	21
9.2.22 TX Register II (Address: 15h).....	22
9.2.23 Delay Register I (Address: 16h)	22
9.2.24 Delay Register II (Address: 17h)	23
9.2.25 RX Register (Address: 18h).....	23
9.2.26 RX Gain Register I (Address: 19h).....	24
9.2.27 RX Gain Register II (Address: 1Ah).....	24
9.2.28 RX Gain Register III (Address: 1Bh).....	24
9.2.29 RX Gain Register IV (Address: 1Ch).....	24
9.2.30 RSSI Threshold Register (Address: 1Dh)	25
9.2.31 ADC Control Register (Address: 1Eh)	25
9.2.32 Code Register I (Address: 1Fh)	25
9.2.33 Code Register II (Address: 20h).....	26
9.2.34 Code Register III (Address: 21h).....	26
9.2.35 IF Calibration Register I (Address: 22h).....	26
9.2.36 IF Calibration Register II (Address: 23h).....	27
9.2.37 VCO current Calibration Register (Address: 24h).....	27
9.2.38 VCO Single band Calibration Register I (Address: 25h)	27
9.2.39 VCO Single band Calibration Register II (Address: 26h)	28
9.2.40 Battery detect Register (Address: 27h).....	28



A7106

Preliminary

2.4G FSK/GFSK Transceiver

9.2.41 TX test Register (Address: 28h)	28
9.2.42 Rx DEM test Register I (Address: 29h)	29
9.2.43 Rx DEM test Register II (Address: 2Ah)	29
9.2.44 Charge Pump Current Register (Address: 2Bh)	29
9.2.45 Crystal test Register (Address: 2Ch)	29
9.2.46 PLL test Register (Address: 2Dh)	30
9.2.47 VCO test Register I (Address: 2Eh)	30
9.2.48 VCO test Register II (Address: 2Fh)	30
9.2.49 IFAT Register (Address: 30h)	30
9.2.50 RScale Register (Address: 31h)	31
9.2.51 Filter test Register (Address: 32h)	31
9.2.52 Filter test Register II (Address: 33h)	31
10. SPI	32
10.1 SPI Format	33
10.2 SPI Timing Characteristic	33
10.3 SPI Timing Chart	34
10.3.1 Timing Chart of 3-wire SPI	34
10.3.2 Timing Chart of 4-wire SPI	34
10.4 Strobe Commands	35
10.4.1 Strobe Command - Sleep Mode	35
10.4.2 Strobe Command - Idle Mode	35
10.4.3 Strobe Command - Standby Mode	36
10.4.4 Strobe Command - PLL Mode	36
10.4.5 Strobe Command - RX Mode	37
10.4.6 Strobe Command - TX Mode	37
10.4.7 Strobe Command - FIFO Write Pointer Reset	38
10.4.8 Strobe Command - FIFO Read Pointer Reset	38
10.5 Reset Command	38
10.6 ID Accessing Command	39
10.6.1 ID Write Command	39
10.6.2 ID Read Command	39
10.7 FIFO Accessing Command	40
10.7.1 TX FIFO Write Command	40
10.7.2 Rx FIFO Read Command	40
11. State machine	41
11.1 Key states	41
11.1.1 Standby mode	42
11.1.2 Sleep mode	42
11.1.3 Idle mode	42
11.1.4 PLL mode	42
11.1.5 TX mode	42
11.1.6 RX mode	43
11.1.7 CAL mode	43
11.2 Normal FIFO Mode	44
11.3 Quick FIFO Mode	46
11.4 Power Saving FIFO Mode	48
11.5 Quick Direct Mode	50
12 Crystal Oscillator	53
12.1 Use External Crystal	53
12.2 Use external clock	53
13. System Clock	54
13.1 Bypass clock generation	55
13.2 Enable clock generation	56
14. Transceiver LO Frequency	58
14.1 LO Frequency Setting	59
14.2 IF Side Band Select	61



A7106

Preliminary

2.4G FSK/GFSK Transceiver

14.2.1 Auto IF Exchange.....	62
14.2.2 Fast Exchange.....	63
14.3 Frequency Compensation	64
15. Calibration.....	65
15.1 Calibration Procedure	65
15.2 IF Filter Bank Calibration.....	65
15.3 VCO Current Calibration	65
15.4 VCO Bank Calibration.....	66
15.5 RSSI Calibration	66
16. FIFO (First In First Out).....	67
16.1 Packet Format	67
16.2 Bit Stream Process	68
16.3 Transmission Time.....	69
16.4 Usage of TX and RX FIFO	70
16.4.1 Easy FIFO	71
16.4.2 Segment FIFO	72
16.4.3 FIFO Extension.....	73
17. ADC (Analog to Digital Converter)	78
17.1 RSSI Measurement.....	78
17.2 Carrier Detect.....	80
18. Battery Detect	81
19 TX power setting	82
20. Application circuit.....	83
21. Abbreviations.....	85
21. Abbreviations.....	85
22. Ordering Information.....	85
23. Package Information.....	86
24. Top Marking Information.....	87
25. Reflow Profile.....	88
26. Type Reel Information.....	89
27. Product Status.....	91



A7106

Preliminary

2.4G FSK/GFSK Transceiver

1. General Description

A7106 is a high performance and low cost 2.4GHz ISM band wireless transceiver. This device integrates both high sensitivity receiver (-95dBm @ 500Kbps) and high efficiency power amplifier (up to 1dBm). In low data rate application, A7106 has special strength for long LOS (line-of-sight) distance because of its ultra high sensitivity (-107 dBm @ 2Kbps, -104 dBm @ 25Kbps) with no requirement of external LNA or PA. Based on Data Rate Register (0x0E), user can configure on-air data rates from 2Kbps to 500Kbps.

A7106 supports fast settling time (130 us) for frequency hopping system. For packet handling, A7106 has built-in separated 64-bytes TX/RX FIFO (could be extended to 256 bytes) for data buffering and burst transmission, CRC for error detection, FEC for 1-bit data correction per code word, RSSI for clear channel assessment, data whitening for data encryption / decryption. Those functions are very easy to use while developing a wireless system. All features are integrated in a small QFN 4X4 20 pins package.

A7106's control registers can be easily accessed via 3-wire or 4-wire SPI bus. For power saving, A7106 supports sleep mode, idle mode, standby mode. For easy-to-use, A7106 has a unique SPI command set called **Strobe command** that are used to control internal state machine. Based on Strobe commands via SPI bus, MCU can control everything from power saving, TX delivery, RX receiving, channel monitoring, frequency hopping to auto calibrations. In addition, A7106 supports two general purpose I/O pins, GIO1 and GIO2, to inform MCU its status so that MCU could use either polling or interrupt scheme to do radio control. Hence, it is very easy to monitor radio transmission between MCU and A7106 because of its digital interface.

2. Typical Applications

- Wireless keyboard and mice
- Remote control
- Helicopter and airplane radio controller
- 2400 ~ 2483.5 MHz ISM system
- Wireless metering and building automation
- Wireless toys and game controllers

3. Feature

- Small size (QFN4 X4, 20 pins).
- Frequency band: 2400 ~ 2483.5MHz.
- FSK or GFSK modulation
- Low current consumption: RX 16mA, TX 20mA (at 0dBm output power).
- Low sleep current (1.5 uA).
- On chip regulator, support input voltage 2.0 ~ 3.6 V.
- Programmable data rate from 2Kbps to 500Kbps.
- Programmable TX power level from -20 dBm to 1 dBm.
- Ultra High sensitivity:
 - ◆ -95dBm at 500Kbps on-air data rate.
 - ◆ -97dBm at 250Kbps on-air data rate
 - ◆ -104dBm at 25Kbps on-air data rate
 - ◆ -107dBm at 2Kbps on-air data rate
- Fast settling time (130 us) synthesizer for frequency hopping system.
- Built-in Battery Detector.
- Support low cost crystal (6 / 8 / 12 / 16 / 20 / 24MHz).
- Support crystal sharing, (1 / 2 / 4 / 8MHz) to MCU.
- Auto Frequency Compensation
- Easy to use.
 - ◆ Support 3-wire or 4-wire SPI.
 - ◆ Unique Strobe command via SPI.
 - ◆ ONE register setting for new channel frequency.
 - ◆ 8-bits Digital RSSI for clear channel indication.
 - ◆ Fast exchange mode during TRX role switching.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

- ◆ Auto RSSI measurement.
- ◆ Auto Calibrations.
- ◆ Auto IF function.
- ◆ Auto CRC Check.
- ◆ Auto FEC by (7, 4) Hamming code (1 bit error correction / code word).
- ◆ Data Whitening for encryption and decryption.
- ◆ Separated 64 bytes RX and TX FIFO.
- ◆ Easy FIFO / Segment FIFO / FIFO Extension (up to 256 bytes).
- ◆ Support direct mode with recovery clock output to MCU.
- ◆ Support direct mode with frame sync signal to MCU.

4. Pin Configurations

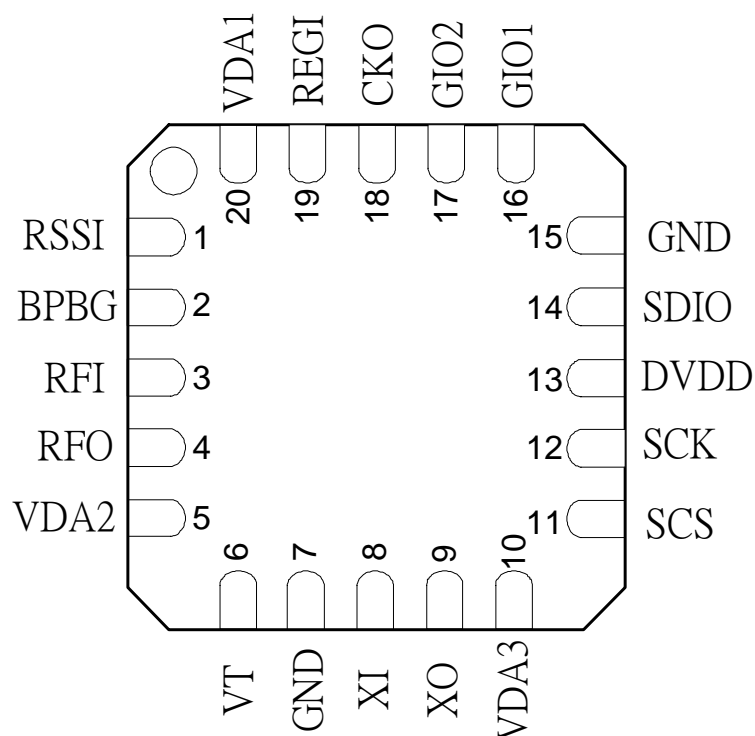


Fig 4-1. A7106 QFN 4x4 Package Top View



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Preliminary

2.4G FSK/GFSK Transceiver

5. Pin Description (I: input; O: output, I/O: input or output)

Pin No.	Symbol	I/O	Function Description
1	RSSI	O	Connected to a bypass capacitor for RSSI reading.
2	BPBG	O	Connected to a bypass capacitor for internal Regulator bias point
3	RFI	I	Low noise amplifier input.
4	RFO	O	Power amplifier output.
5	VDA2	I/O	Voltage supply (from VDA1, pin 20) for RX & TX analog part.
6	VT	I	VCO frequency control input, internal connected to PLL charge pump.
7	GND	G	Ground
8	XI	I	Crystal oscillator input node
9	XO	O	Crystal oscillator output node
10	VDA3	I	Voltage supply (from VDA1, pin 20) for PLL part
11	SCS	I	3 wire SPI chip select.
12	SCK	I	3 wire SPI clock input pin.
13	DVDD	I	Connected to a bypass capacitor to supply voltage for digital part.
14	SDIO	I/O	3 wire SPI read/write data pin.
15	GND	G	Ground
16	GIO1	I/O	Multi-function GIO1 / 4-wire SPI data output.
17	GIO2	I/O	Multi-function GIO2 / 4-wire SPI data output.
18	CKO	O	Multi-function clock output.
19	REGI	I	Internal Regulator input (External Power Input)
20	VDA1	I/O	Internal Regulator output to supply VDA2 (pin 5), VDA2 (pin 10) and RFO (pin 4).
	Back side plate	G	Ground. Back side plate shall be well-solder to ground; otherwise, it will impact RF performance.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

6. Chip Block Diagram

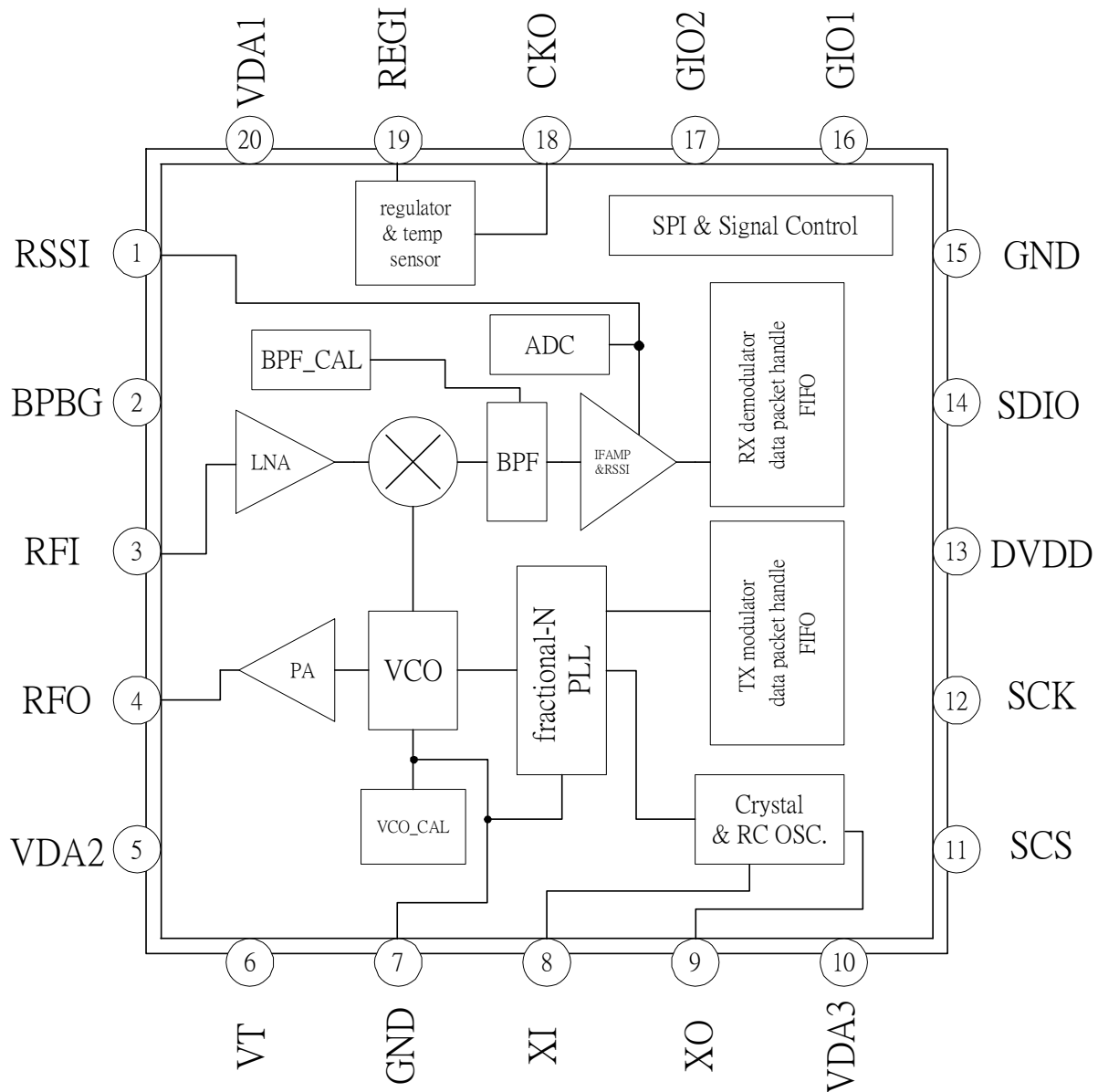


Fig 6-1. A7106 Block Diagram



A7106

Preliminary

2.4G FSK/GFSK Transceiver

7. Absolute Maximum Ratings

Parameter	With respect to	Rating	Unit
Supply voltage range (VDD)	GND	-0.3 ~ 3.6	V
Digital IO pins range	GND	-0.3 ~ VDD+0.3	V
Voltage on the analog pins range	GND	-0.3 ~ 2.1	V
Input RF level		5	dBm
Storage Temperature range		-55 ~ 125	°C
ESD Rating	HBM	± 2K	V
	MM	± 100	V

*Stresses above those listed under "Absolute Maximum Rating" may cause permanent damage to the device. These are stress ratings only; functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

*Device is ESD sensitive. Use appropriate ESD precautions. HBM (Human Body Mode) is tested under MIL-STD-883F Method 3015.7. MM (Machine Mode) is tested under JEDEC EIA/JESD22-A115-A.

*Device is Moisture Sensitivity Level III (MSL 3).





A7106

Preliminary

2.4G FSK/GFSK Transceiver

8. Electrical Specification

(Ta=25°C, VDD=3.0V, data rate= 500Kbps, IF bandwidth = 500KHz, F_{XTAL} =16MHz, with Match Networking and low pass filter, On Chip Regulator = 2.1V, unless otherwise noted.)

Parameter	Description	Min.	Type	Max.	Unit
General					
Operating Temperature		-40		85	°C
Supply Voltage (VDD)	with internal regulator	2.0		3.6	V
Current Consumption	Sleep mode (RC OSC off)		1.5 ^{*1}		μA
	Idle Mode (Regulator on)		0.3 ^{*1}		mA
	Standby Mode (XOSC on, clock generator on)		1.9		mA
	PLL mode		9		mA
	RX Mode		16		mA
	TX Mode (@0dBm output)		20		mA
	TX Mode (@-3dBm output)		16		mA
	TX Mode (@-6dBm output)		14.5		mA
	TX Mode (@-11dBm output)		13.9		mA
	TX Mode (@-20dBm output)		12.5		mA
PLL block					
Crystal start up time ^{*2}			0.6		ms
Crystal frequency		6, 8, 12, 16, 20, 24			MHz
Crystal tolerance	without FW FC	±10			ppm
	with FW FC	±20			ppm
Crystal ESR				80	ohm
VCO Operation Frequency		2400		2483.5	MHz
PLL phase noise	Offset 10k		80		dBc
	Offset 100K		85		
	Offset 1M		90		
PLL settling time ^{*3}	@Loop BW = 500Khz		70		μS
Transmitter					
Output power range		-20	0		dBm
Out Band Spurious Emission ^{*4}	30MHz~1GHz			-36	dBm
	1GHz~12.75GHz			-30	dBm
	1.8GHz~ 1.9GHz			-47	dBm
	5.15GHz~ 5.3GHz			-47	dBm
Frequency deviation ^{*5}	Data rate > 50Kbps		186K		Hz
	Date rate <=50Kbps		124K		Hz
Data rate		2K		500K	Bps
TX ready time ^{*6} (PLL to WPLL + WPLL to TX)	@Loop BW = 500 KHz, LO fixed		10+60		μS
	@Loop BW = 500 KHz, Hopping		70+60		μS
Receiver					
Receiver sensitivity	Data rate 500K (F _{IF} = 500KHz)		-95		dBm



A7106

Preliminary

2.4G FSK/GFSK Transceiver

@ BER = 0.1%	Data rate 250K (F _{IF} = 500KHz)			-97		dBm
	Data rate 25K (F _{IF} = 500KHz)			-104		dBm
	Data rate 2K (F _{IF} = 500KHz)			-107		dBm
IF frequency bandwidth				250/500		KHz
IF center frequency				250/500		KHz
Interference ^{*7}	Co-Channel (C/I ₀)			11		dB
	±1MHz Adjacent Channel			- 20		dB
	±2MHz Adjacent Channel			- 30		dB
	> ±5MHz Adjacent Channel			- 40		dB
	Image (C/I _{IM})			- 12		dB
Maximum Operating Input Power	@RF input (BER=0.1%)				0	dBm
Spurious Emission ^{*4}	30MHz~1GHz				-57	dBm
	1GHz~12.75GHz				-47	
RSSI Range	@RF input		-105		-50	dBm
RX Ready Time* ⁸ (PLL to WPLL + WPLL to RX)	LO fixed	Data rate < = 125 Kbps		10+40		μs
		Data rate = 250 Kbps		10+100		μs
		Data rate = 500 Kbps		10+60		μs
	Hopping	Data rate < = 125 Kbps		70+40		μs
		Data rate = 250 Kbps		70+100		μs
		Data rate = 500 Kbps		70+60		μs
RX Spurious Emission	above 1GHz				-47	dBm
Regulator						
Regulator settling time	Pin 2 connected to 1.5 nF			500		μs
Band-gap reference voltage				1.23		V
Regulator output voltage			1.8	2.1	2.3	V
Line regulation	Load current 30mA		35	40		dBc
Digital IO DC characteristics						
High Level Input Voltage (V _{IH})			0.8*VDD		VDD	V
Low Level Input Voltage (V _{IL})			0		0.2*VDD	V
High Level Output Voltage (V _{OH})	@I _{OH} = -0.5mA		VDD-0.4		VDD	V
Low Level Output Voltage (V _{OL})	@I _{OL} = 0.5mA		0		0.4	V

Note 1: When digital I/O pins are configured as input, those pins shall NOT be floating but pull either high or low (SCS shall be pulled high only); otherwise, leakage current will be induced.

Note 2: Refer to Delay Register II (17h) to set up crystal settling delay.

Note 3: Refer to Delay Register I (17h) to set up PDL (PLL settling delay).

Note 4: With external RF filter that provides minimum 17dB of attenuation in the band: 30MHz ~ 2GHz and 3GHz ~ 12.75GHz.

Note 5: Refer to TX Register II (15h) to set up FD [4:0].

Note 6: Refer to Delay Register I (17h) to set up PDL and TDL delay.

Note 7: The power level of wanted signal is set at sensitivity level +3dB. The modulation data for wanted signal and interferer are PN9 and PN15, respectively. Channel spacing is 500KHz.

Note 8: For 250K/500Kbps, set DCM[1:0] = [10b] by ID, (29h). For $\leq 125\text{Kbps}$, set DCM[1:0] = [01b] by Preamble, (29h).



A7106

Preliminary

2.4G FSK/GFSK Transceiver

9. Control Register

A7106 contains 52 x 8-bit control registers. MCU can access those control registers via 3-wire (SCS, SCK, SDIO) or 4-wire (SCS, SCK, SDIO, GIO1/GIO2) SPI interface (support max. SPI data rate up to 10 Mbps). User can refer to chapter 10 for details of SPI timing. A7106 is simply controlled by registers and outputs its status to MCU by GIO1 and GIO2 pins.

9.1 Control register table

Address / Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
00h Mode	W	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN
	R	--	FECF	CRCF	CER	XER	PLLER	TRSR	TRER
01h Mode control	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
02h Calc	R/W	---	--	--	--	RSSC	VCC	VBC	FBC
03h FIFO I	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
04h FIFO II	W	FPM1	FPM0	PSA5	PSA4	PSA3	PSA2	PSA1	PSA0
05h FIFO Data	R/W	FIFO7	FIFO6	FIFO5	FIFO4	FIFO3	FIFO2	FIFO1	FIFO0
06h ID Data	R/W	ID7	ID6	ID5	ID4	ID3	ID2	ID1	ID0
07h RC OSC I	W	WWS_SL7	WWS_SL6	WWS_SL5	WWS_SL4	WWS_SL3	WWS_SL2	WWS_SL1	WWS_SL0
	R	CALR	RCOC6	RCOC5	RCOC4	RCOC3	RCOC2	RCOC1	RCOC0
08h RC OSC II	W	WWS_SL9	WWS_SL8	WWS_AC5	WWS_AC4	WWS_AC3	WWS_AC2	WWS_AC1	WWS_AC0
09h RC OSC III	W	BBCKS1	BBCKS0	RCOT1	RCOT0	CALW	RCOSC_E	TSEL	TWWS_E
0Ah CKO Pin	W	ECKOE	CKOS3	CKOS2	CKOS1	CKOS0	CKOI	CKOE	SCKI
0Bh GPIO1 Pin I	W	--	--	GIO1S3	GIO1S2	GIO1S1	GIO1S0	GIO1I	GIO1OE
0Ch GPIO2 Pin II	W	--	--	GIO2S3	GIO2S2	GIO2S1	GIO2S0	GIO2I	GIO2OE
0Dh Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
0Eh Data rate	R/W	SDR7	SDR6	SDR5	SDR4	SDR3	SDR2	SDR1	SDR0
0Fh PLL I	R/W	CHN7	CHN6	CHN5	CHN4	CHN3	CHN2	CHN1	CHN0
10h PLL II	R/W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
11h PLL III	R/W	IP7	IP6	IP5	IP4	IP3	IP2	IP1	IP0
12h PLL IV	W	FP15	FP14	FP13	FP12	FP11	FP10	FP9	FP8
	R	RAC15	RAC14	RAC13	RAC12	RAC11	RAC10	RAC9	RAC8
13h PLL V	W	FP7	FP6	FP5	FP4	FP3	FP2	FP1	FP0
	R	RAC7	RAC6	RAC5	RAC4	RAC3	RAC2	RAC1	RAC0
14h TX I	W	TXSM1	TXSM0	TXDI	TME	FS	FDP2	FDP1	FDP0
15h TX II	W	--	PDV1	PDV0	FD4	FD3	FD2	FD1	FD0
16h Delay I	W	DPR2	DPR1	DPR0	TDL1	TDL0	PDL2	PDL1	PDL0

**A7106****Preliminary****2.4G FSK/GFSK Transceiver**

17h Delay II	W	WSEL2	WSEL1	WSEL0	AGC_D1	AGC_D0	RS_DLY2	RS_DLY1	RS_DLY0
18h RX	W	QDLS	RXSM1	RXSM0	AFC	RXDI	DMG	BWS	ULS
19h RX Gain I	R/W	MVGS	AGLNE	IGC	MGC1	MGC0	LGC2	LGC1	LGC0
1Ah RX Gain II	W	RH7	RH6	RH5	RH4	RH3	RH2	RH1	RH0
	R	RHR7	RHR6	RHR5	RHR4	RHR3	RHR2	RHR1	RHR0
1Bh RX Gain III	W	RL7	RL6	RL5	RL4	RL3	RL2	RL1	RL0
	R	RLR7	RLR6	RLR5	RLR4	RLR3	RLR2	RLR1	RLR0
1Ch RX Gain IV	W	ENG C	CRCD	MVSEL1	MVSEL0	MHC	LHC1	LHC0	VGCE
1Dh RSSI Threshold	W	RTH7	RTH6	RTH5	RTH4	RTH3	RTH2	RTH1	RTH0
	R	ADC7	ADC6	ADC5	ADC4	ADC3	ADC2	ADC1	ADC0
1Eh ADC	W	RSM1	RSM0	ERSS	FSARS	--	XADS	RSS	CDM
1Fh Code I	W	--	MCS	WHTS	FECS	CRCS	IDL	PML1	PML0
20h Code II	W	--	DCL2	DCL1	DCL0	ETH1	ETH0	PMD1	PMD0
21h Code III	W	--	WS6	WS5	WS4	WS3	WS2	WS1	WS0
22h IF Calibration I	W	--	--	--	MFB5	MFB3	MFB2	MFB1	MFB0
	R	--	--	---	FBCF	FB3	FB2	FB1	FB0
23h IF Calibration II	R	--	---	--	FCD4	FCD3	FCD2	FCD1	FCD0
24h VCO current Calibration	W	--	--	VCCS	MVCS	VCOC3	VCOC2	VCOC1	VCOC0
	R	--	--	--	FVCC	VCB3	VCB2	VCB1	VCB0
25h VCO Single band Calibration I	W	--	--	--	--	MVBS	MVB2	MVB1	MVB0
	R	--	--	DVT1	DVT0	VBCF	VB2	VB1	VB0
26h VCO Single band Calibration II	W	--	--	VTH2	VTH1	VTH0	VTL2	VTL1	VTL0
27h Battery detect	W	RGS	RGV1	RGV0	QDS	BVT2	BVT1	BVT0	BDS
	R	RGS	RGV1	RGV0	BDF	BVT2	BVT1	BVT0	BDS
28h TX test	W	--	--	TXCS	PAC1	PAC0	TBG2	TBG1	TBG0
29h Rx DEM test I	W	DMT	DCM1	DCM0	MLP1	MLP0	SLF2	SLF1	SLF0
2Ah Rx DEM test II	W	DCV7	DCV6	DCV5	DCV4	DCV3	DCV2	DCV1	DCV0
2Bh CPC	W	ROSCS	CELS	RGC1	RGC0	STS	LVR	CPC1	CPC0
2Ch Crystal test	W	RSIS	PKT1	PKT0	PKS	DBD	XCC	XCP1	XCP0
2Dh PLL test	W	PRS	PMPE	PRIC1	PRIC0	PRRC1	PRRC0	SDPW	NSDO
2Eh VCO test I	W	MQDL	--	--	TLB	TLB	RLB	RLB	VCBS
2Fh VCO test II	W	--	--	--	--	RFT3	RFT2	RFT1	RFT0
30h IFAT	W	IGFI2	IGFI1	IGFI0	IGFQ2	IGFQ1	IGFQ0	IFBC	LIMC



A7106

Preliminary

2.4G FSK/GFSK Transceiver

31h Rscale	R/W	RSC7	RSC6	RSC5	RSC4	RSC3	RSC2	RSC1	RSC0
32h Filter test	W	FT7	FT6	FT5	FT4	FT3	FT2	FT1	FT0
33h TMV	W	--	TRT2	TRT1	TRT0	ASMV2	ASMV1	ASMV0	AMVS

Legend: -- = unimplemented

9.2 Control register description

9.2.1 Mode Register (Address: 00h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode	R	--	FECF	CRCF	CER	XER	PLLER	TRSR	TRER
	W	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN
Reset		--	--	--	--	--	--	--	--

RESETN: Write to this register by 0x00 to issue reset command, then it is auto clear

FECF: FEC flag.

[0]: FEC pass. [1]: FEC error. (FECF is read only, it is updated internally while receiving every packet.)

CRCF: CRC flag.

[0]: CRC pass. [1]: CRC error. (CRCF is read only, it is updated internally while receiving every packet.)

CER: RF chip enable status.

[0]: RF chip is disabled. [1]: RF chip is enabled.

XER: Internal crystal oscillator enabled status.

[0]: Crystal oscillator is disabled. [1]: Crystal oscillator is enabled.

PLLE: PLL enabled status.

[0]: PLL is disabled. [1]: PLL is enabled.

TRER: TRX state enabled status.

[0]: TRX is disabled. [1]: TRX is enabled.

TRSR: TRX Status Register.

[0]: RX state. [1]: TX state.

Serviceable if TRER=1 (TRX is enable).

9.2.2 Mode Control Register (Address: 01h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control I	R	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
	W	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
Reset		0	0	0	0	0	0	0	0

DDPC (Direct mode data pin control): In Direct mode, If DDPC=1, MCU delivers / receives raw data of packet via SDIO pin instead of GIO1 or GIO2 pin.

[0]: Disable. [1]: Enable.

ARSSI: Auto RSSI measurement while entering RX mode.

[0]: Disable. [1]: Enable.

AIF (Auto IF Offset): RF LO frequency will auto offset one IF frequency while entering RX mode.

[0]: Disable. [1]: Enable.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

CD / DFCD: DFCD (Data Filter by CD): The received packet will be filtered out if CD is inactive.

[0]: Disable. [1]: Enable.

CD (Read only): Carrier detector signal.

[0]: Input power below threshold. [1]: Input power above threshold.

WWSE: Reserved for internal usage only. Shall be set to [0].

FMT: Reserved for internal usage only. Shall be set to [0].

FMS: Direct/FIFO mode select.

[0]: Direct mode. [1]: FIFO mode.

ADCM: ADC measurement enable (Auto clear when done).

[0]: Disable measurement or measurement finished. [1]: Enable measurement.

ADCM	A7106 @ Standby mode	A7106 @ RX mode
[0]	Disable ADC	Disable ADC
[1]	No function	Measure RSSI, carrier detect

Refer to chapter 17 for details.

9.2.3 Calibration Control Register (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control II	R/W	--	--	--	--	RSSC	VCC	VBC	FBC
Reset		--	--	--	--	0	0	0	0

VCC: VCO Current calibration enable (Auto clear when done).

[0]: Disable. [1]: Enable.

VBC: VCO Bank calibration enable (Auto clear when done).

[0]: Disable. [1]: Enable.

FBC: IF Filter Bank calibration enable (Auto clear when done).

[0]: Disable. [1]: Enable.

RSSC: RSSI calibration enable (Auto clear when done).

[0]: Disable. [1]: Enable.

9.2.4 FIFO Register I (Address: 03h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FIFO I	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
Reset		0	0	1	1	1	1	1	1

FEP [7:0]: FIFO End Pointer for TX FIFO and Rx FIFO.

Refer to chapter 16 for details.

9.2.5 FIFO Register II (Address: 04h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FIFO II	W	FPM1	FPM0	PSA5	PSA4	PSA3	PSA2	PSA1	PSA0
Reset		0	1	0	0	0	0	0	0

FPM [1:0]: FIFO Pointer Margin

PSA [5:0]: Used for Segment FIFO.

Refer to chapter 16 for details.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

9.2.6 FIFO DATA Register (Address: 05h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
FIFO DATA	R/W	FIFO7	FIFO6	FIFO5	FIFO4	FIFO3	FIFO2	FIFO1	FIFO0
Reset		0	0	0	0	0	0	0	0

FIFO [7:0]: FIFO data. TX FIFO (Write only) and RX FIFO (Read only).

TX FIFO and RX FIFO share the same address (05h).

Refer to chapter 16 for details.

9.2.7 ID DATA Register (Address: 06h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ID DATA	R/W	ID7	ID6	ID5	ID4	ID3	ID2	ID1	ID0
Reset		0	0	0	0	0	0	0	0

ID [7:0]: ID data.

When this address is accessed, ID Data is input or output sequential (ID Byte 0, 1, 2 and 3) corresponding to Write or Read.

Recommend to set ID Byte 0 = 5xh or Axxh.

Refer to section 10.6 for details.

9.2.8 RC OSC Register I (Address: 07h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RC OSC I	R	CALR	RCOC6	RCOC5	RCOC4	RCOC3	RCOC2	RCOC1	RCOC0
	W	WWS_SL7	WWS_SL6	WWS_SL5	WWS_SL4	WWS_SL3	WWS_SL2	WWS_SL1	WWS_SL0
Reset		0	0	0	0	0	0	0	0

Refer to chapter 18 for details.

RCOC [6:0]: RC-oscillator calibration value reading.

CALR: RC-oscillator calibration status.

[0]: calibration finished. [1]: not yet.

9.2.9 RC OSC Register II (Address: 08h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RC OSC II	W	WWS_SL9	WWS_SL8	WWS_AC5	WWS_AC4	WWS_AC3	WWS_AC2	WWS_AC1	WWS_AC0
Reset		0	0	0	0	0	0	0	0

WWS_AC [5:0]: Reserved for internal usage only.

WWS_SL [9:0]: Reserved for internal usage only.

9.2.10 RC OSC Register III (Address: 09h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RC OSC III	W	BBCKS1	BBCKS0	RCOT1	RCOT0	CALW	RCOSC_E	TSEL	TWWS_E
Reset		0	0	0	0	0	1	0	1

BBCKS [1:0]: Clock select for internal digital block

[00]: F_{SYCK} / 8. [01]: F_{SYCK} / 16. [10]: F_{SYCK} / 32. [11]: F_{SYCK} / 64.

F_{SYCK} is A7106's System clock. Refer to chapter 18 for details



A7106

Preliminary

2.4G FSK/GFSK Transceiver

RCOT [1:0]: current select for RC-oscillator.

Refer to chapter 18 for details

CALW: RC-oscillator calibration (Auto clear when done).

[0]: disable, [1]: enable.

RCOSC_E: RC-oscillator enable.

[0]: Disable. [1]: Enable.

TSEL: Timer select for TWWS function.

[0]: Use WWS_AC. [1]: Use WWS_SL.

TWWS_E: Enable TWWS function.

[0]: Disable. [1]: Enable.

9.2.11 CKO Pin Control Register (Address: 0Ah)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
CKO Pin Control	W	ECKOE	CKOS3	CKOS2	CKOS1	CKOS0	CKOI	CKOE	SCKI
Reset		1	0	1	1	1	0	1	0

ECKOE: External Clock Output Enable for CKOS [3:0]= [0100] ~ [0111].

[0]: Disable. [1]: Enable.

CKOS [3:0]: CKO pin output select.

[0000]: DCK (TX data clock) in TX mode, RCK (RX recovery clock) in RX mode.

[0001]: DCK (TX data clock) in TX mode, RCK (RX recovery clock) in RX mode.

[0010]: FPF (FIFO pointer flag).

[0011]: EOP, EOVCB, EOFBC, EOADC, EOVCB, OKADC (Internal usage only).

[0100]: External clock output= F_{SYCK} .

[0101]: External clock output / 2= $F_{SYCK} / 2$.

[0110]: External clock output / 4= $F_{SYCK} / 4$.

[0111]: External clock output / 8= $F_{SYCK} / 8$.

[1xxx]: Reserved.

CKOI: CKO pin output signal invert.

[0]: Non-inverted output. [1]: Inverted output.

CKOE: CKO pin Output Enable.

[0]: High Z. [1]: Enable.

SCKI: SPI clock input invert.

[0]: Non-inverted input. [1]: Inverted input.

9.2.12 GIO1 Pin Control Register I (Address: 0Bh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GIO1 Pin Control I	W	--	--	GIO1S3	GIO1S2	GIO1S1	GIO1S0	GIO1I	GIO1OE
Reset		--	--	0	0	0	0	0	1

GIO1S [3:0]: GIO1 pin function select.

GIO1S [3:0]	TX state	RX state
[0000]	WTR (Wait until TX or RX finished)	
[0001]	EOAC (end of access code)	FSYNC (frame sync)
[0010]	TME0 (TX modulation enable)	CD (carrier detect)
[0011]	Preamble Detect Output (PMDO)	
[0100]	(Reserved.)	
[0101]	In phase demodulator input (DMII)	
[0110]	SDO (4 wires SPI data out)	
[0111]	TRXD In/Out (Direct mode)	



A7106

Preliminary

2.4G FSK/GFSK Transceiver

[1000]	RXD (Direct mode)
[1001]	TXD (Direct mode)
[1010]	In phase demodulator external input (EXDI0)
[1011]	External FSYNC input in RX direct mode
[1100]	INC
[1101]	FPF
[1110]	PDN_RX
[1111]	PDN_TX

GIO1I: GIO1 pin output signal invert.

[0]: Non-inverted output. [1]: Inverted output.

GIO1OE: GIO1 pin output enable.

[0]: High Z. [1]: Enable.

9.2.13 GIO2 Pin Control Register II (Address: 0Ch)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
GIO2 Pin Control II	W	--	--	GIO2S3	GIO2S2	GIO2S1	GIO2S0	GIO2I	GIO2OE
Reset		--	--	0	1	0	0	0	1

GIO2S [3:0]: GIO2 pin function select.

GIO2S	TX state	RX state
[0000]	WTR (Wait until TX or RX finished)	
[0001]	EOAC (end of access code)	FSYNC (frame sync)
[0010]	TME0 (TX modulation enable)	CD (carrier detect)
[0011]	Preamble Detect Output (PMDO)	
[0100]	(Reserved.)	
[0101]	Quadrature phase demodulator input (DMIQ)	
[0110]	SDO (4 wires SPI data out)	
[0111]	TRXD In/Out (Direct mode)	
[1000]	RXD (Direct mode)	
[1001]	TXD (Direct mode)	
[1010]	Quadrature phase demodulator external input (EXDI1)	
[1011]	External FSYNC input in RX direct mode	
[1100]	DEC	
[1101]	FPF	
[1110]	PDN_RX	
[1111]	PDN_TX	

GIO2I: GIO2 pin output signal invert.

[0]: Non-inverted output. [1]: Inverted output.

GIO2OE: GIO2 pin Output Enable.

[0]: High Z. [1]: Enable.

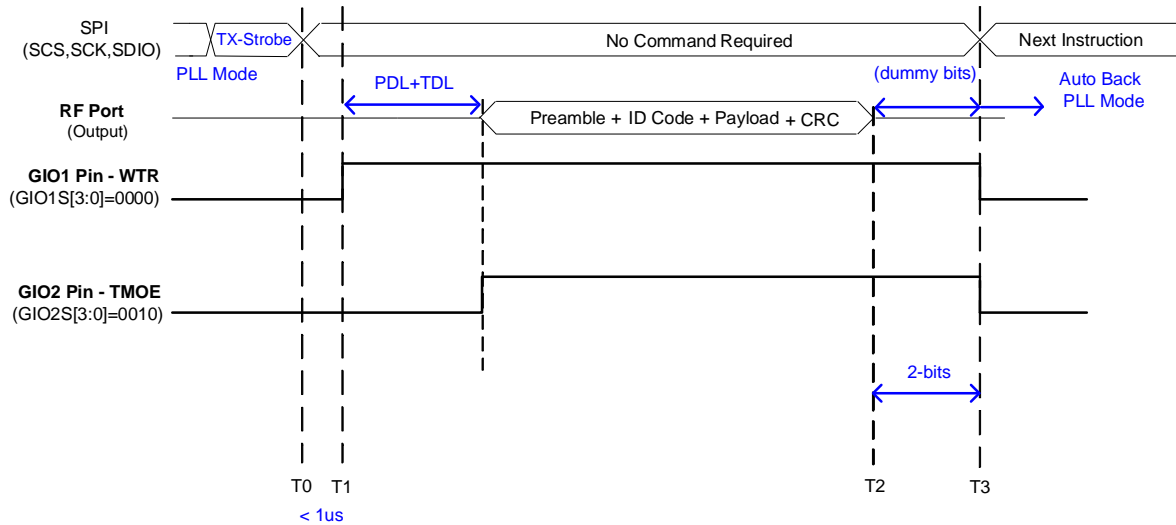


A7106

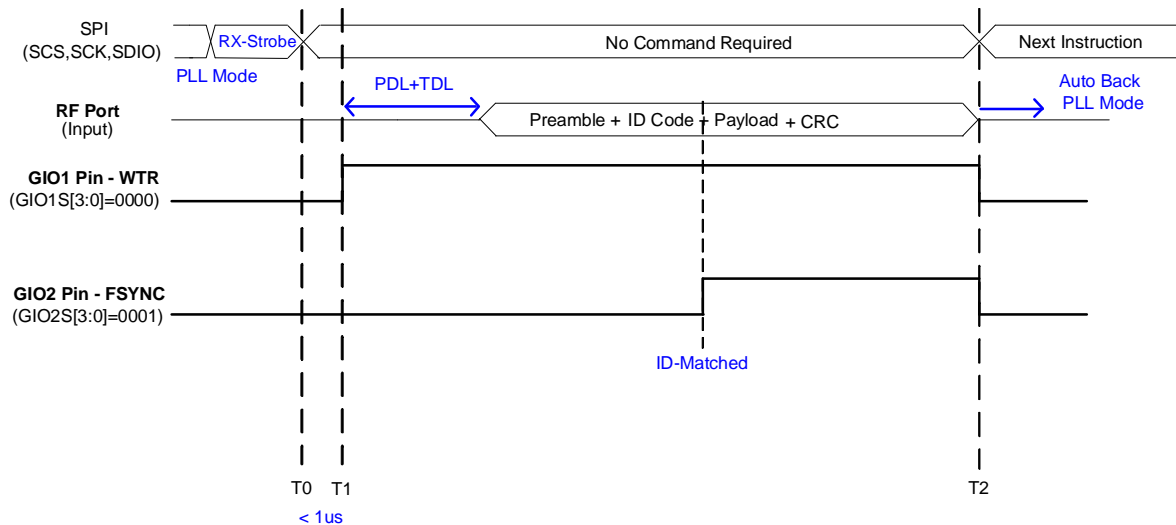
Preliminary

2.4G FSK/GFSK Transceiver

In TX mode



In RX mode



9.2.14 Clock Register (Address: 0Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
Reset		1	1	1	1	0	1	0	1

Refer to chapter 14 for details.

CGS: Clock generator enable. Recommend CGS = [0]

[0]: Disable. [1]: Enable.

CGS = 0 (recommend)	CGS = 1
Disable internal 32MHz PLL clock	F _{MCLK} = 32 MHz



A7106

Preliminary

2.4G FSK/GFSK Transceiver

XS: Crystal oscillator select. Recommend XS = [1]

[0]: External clock. [1]: Crystal.

GRC [3:0]: Clock generation reference counter.

GRC[3:0]	Note
Don't care	Recommend when CGS = 0
$F_{XTAL} \times (DBL+1) / (GRC+1) = 2M$ When CGS = 1	

CSC [1:0]: system clock F_{SYCK} divider select.

CSC [1:0]	System Clock F_{SYCK}	Note
00	F_{MCLK}	F_{SYCK} is used to determine 1. Data rate (0Eh) 2. ADC clock (1Eh) 3. Internal digital clock (09h) 4. CKO pin (0Ah)
01 (Recommend)	$F_{MCLK} / 2$	
10	$F_{MCLK} / 2$	
11	$F_{MCLK} / 4$	

9.2.15 Data Rate Register (Address: 0Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Data Rate	R/W	SDR7	SDR6	SDR5	SDR4	SDR3	SDR2	SDR1	SDR0
Reset		0	0	0	0	0	0	0	0

SDR [7:0]: Data rate division selection.

Data rate = $F_{SYCK} / 32 / (SDR [7:0]+1)$. Refer to chapter 13 for details.

9.2.16 PLL Register I (Address: 0Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL I	R/W	CHN7	CHN6	CHN5	CHN4	CHN3	CHN2	CHN1	CHN0
Reset		0	0	0	0	0	0	0	0

CHN [7:0]: LO channel number select.

Refer to chapter 14 for details.

9.2.17 PLL Register II (Address: 10h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL II	R	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
	W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	BIP8
Reset		1	0	0	1	1	1	1	0

DBL: Crystal frequency doubler selection. Recommend DBL = [1]

[0]: Disable. $F_{XREF} = F_{XTAL}$. [1]: Enable. $F_{XREF} = 2 * F_{XTAL}$.

RRC [1:0]: RF PLL reference counter setting.

CHR [3:0]: PLL channel step setting.

Refer to chapter 14 for details.

9.2.18 PLL Register III (Address: 11h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL III	R	IP7	IP6	IP5	IP4	IP3	IP2	IP1	IP0
	W	BIP7	BIP6	BIP5	BIP4	BIP3	BIP2	BIP1	BIP0
Reset		0	1	0	0	1	0	1	1

BIP [8:0]: LO base frequency integer part setting. Recommend BIP[8:0] = [0x04B]



A7106

Preliminary

2.4G FSK/GFSK Transceiver

BIP [8:0] are from address (0Fh) and (10h),

IP [8:0]: LO frequency integer part value.

IP [8:0] are from address (0Fh) and (10h),

Refer to chapter 14 for details.

9.2.19 PLL Register IV (Address: 12h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL IV	R	RAC15	RAC14	RAC13	RAC12	RAC11	RAC10	RAC9	RAC8
	W	BFP15	BFP14	BFP13	BFP12	BFP11	BFP10	BFP9	BFP8
Reset		0	0	0	0	0	0	0	0

9.2.20 PLL Register V (Address: 13h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL V	R	RAC7	RAC6	RAC5	RAC4	RAC3	RAC2	RAC1	RAC0
	W	BFP7	BFP6	BFP5	BFP4	BFP3	BFP2	BFP1	BFP0
Reset		0	0	0	0	0	0	1	1

BFP [15:0]: LO base frequency fractional part setting.

BFP [15:0] are from address (11h) and (12h),

RAC [15:0] (Read): Auto Frequency compensation value when AFC is enabled

RAC represented below

{PRS(2Dh), AFC(18h)}	RAC [15:0]
1x	PLLFF [15:0]
01	{0, ACO [14:0]}
00	{SYNCF, AC [14:0]}

PLLFF [15:0]: fractional part in PLL,

ACO [14:0] : accumulated frequency compensated value,

SYNCF : SYNC word detection flag. [0]: not detected, [1]: detected.

AC [14:0] : updated frequency compensated value.

FP [15:0] (Read): LO frequency fractional part setting.

Refer to chapter 14 for details.

9.2.21 TX Register I (Address: 14h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TX I	W	TXSM1	TXSM0	TXDI	TME	FS	FDP2	FDP1	FDP0
Reset		0	0	0	1	0	1	1	0

TXSM [1:0]: Moving average for non-filter select. Recommend TXSM = [00]

[00]: not average. [01]: 2 bit average. [10]: 4 bit average. [11]: 8 bit average

TXDI: TX data invert. Recommend TXDI = [0].

[0]: Non-invert. [1]: Invert.

TME: TX modulation enable.

[0]: Disable. [1]: Enable.

FS: Filter select. Recommend FS = [0]

Gaussian filter (BT=0.7).



A7106

Preliminary

2.4G FSK/GFSK Transceiver

[0]: disable. [1]: enable.

FDP [2:0]: Frequency deviation power setting. Refer to control register (15h). Recommend FDP = [110].

9.2.22 TX Register II (Address: 15h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TX II	W	--	PDV1	PDV0	FD4	FD3	FD2	FD1	FD0
Reset		--	0	0	0	1	0	1	1

PDV [1:0]: Reserved for internal usage only. Shall be set to [01].

FD [4:0]: Frequency deviation setting.

$$F_{DEV} = F_{PFD} \times 127 \times (FD [4:0] + 1) \times 2^{(FDP [2:0])} / 2^{24}$$

Where $F_{PFD} = F_{XTAL} \times (DBL+1) / (RRC [1:0]+1)$, PLL comparison frequency.

Data Rate (Kbps)	F _{PFD}	FDP [2:0]	PDV [1:0]	FD[4:0]	Fdev (KHz)
<= 50Kbps	12MHz	110b	01b	10110b (0x16)	122
	16MHz			01111b (0x0F)	124
	24MHz			01010b (0x0A)	127
	32MHz			00111b (0x07)	124
Data Rate (Kbps)	F _{PFD}	FDP [2:0]	PDV [1:0]	FD[4:0]	Fdev (KHz)
> 50Kbps	16MHz	110b	01b	10111b (0x17)	186
	24MHz			01111b (0x0F)	
	32MHz			01011b (0x0B)	

9.2.23 Delay Register I (Address: 16h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Delay	W	DPR2	DPR1	DPR0	TDL1	TDL0	PDL2	PDL1	PDL0
Reset		0	0	0	1	0	0	1	0

DPR [2:0]: Delay scale. Recommend DPR = [000].

TDL [1:0]: Delay for TX settling from WPLL to TX.

$$\text{Delay} = 20 \times (TDL [1:0] + 1) \times (DPR [2:0] + 1) \text{ us}$$

DPR [2:0]	TDL [1:0]	WPLL to TX	Note
000	00	20 us	
000	01	40 us	
000	10	60 us	Recommend
000	11	80 us	

PDL [2:0]: Delay for TX settling from PLL to WPLL.

$$\text{Delay} = 10 + 20 \times (PDL [2:0] + 1) \times (DPR [2:0] + 1) \text{ us}$$

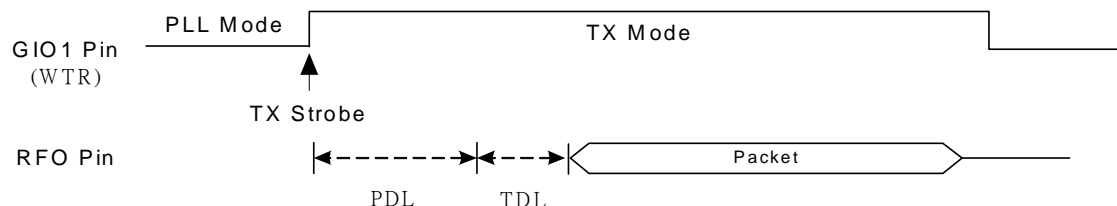
DPR [2:0]	PDL [2:0]	PLL to WPLL (LO freq. fixed)	PLL to WPLL (LO freq changed)	Note
000	001	10 us	50 us	
000	010	10 us	70 us	Recommend
000	011	10 us	90 us	
000	100	10 us	110 us	



A7106

Preliminary

2.4G FSK/GFSK Transceiver



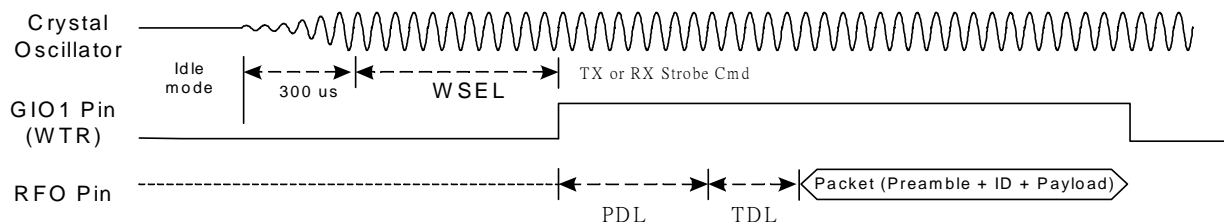
9.2.24 Delay Register II (Address: 17h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Delay	W	WSEL2	WSEL1	WSEL0	AGC_D1	AGC_D0	RS_DLY2	RS_DLY1	RS_DLY0
Reset		0	1	0	0	0	0	0	1

WSEL [2:0]: XTAL settling delay setting (200us ~ 2.5ms). Recommend WSEL = [010].

[000]: 200us. [001]: 400us. [010]: 600us. [011]: 800us.

[100]: 1ms. [101]: 1.5ms. [110]: 2ms. [111]: 2.5ms.



AGC_D [1:0]: AGC delay settling Recommend AGC_D[1:0] = [00].

[00]: 10us. [01]: 20us. [10]: 30us. [11]: 40us.

RS_DLY [2:0]: RSSI measurement delay (10us ~ 80us). Recommend RS_DLY = [000].

[000]: 10us. [001]: 20us. [010]: 30us. [011]: 40us.

[100]: 50us. [101]: 60us. [110]: 70us. [111]: 80us.

9.2.25 RX Register (Address: 18h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX	W	QDLS	RXSM1	RXSM0	FC	RXDI	DMG	BWS	ULS
Reset		0	1	0	0	0	0	1	0

RXSM0: Reserved for internal usage only. Shall be set to [1].

RXSM1: Reserved for internal usage only. Shall be set to [1].

FC: Frequency compensation select.

[0]: Disalbe . [1]: Enable.

Refer to section 14.4 for details.

RXDI: RX data output invert. Recommend RXDI = [0].

[0]: Non-inverted output. [1]: Inverted output.

DMG: Reserved for internal usage only. Shall be set to [0].

BWS: BPF bandwidth select. Recommend BWS = [1].

[0]: 250KHz. [1]: 500KHz.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Data Rate (Kbps)	BWS	Note
2~ 500	1	F _{IF} = 500KHz

ULS: RX Up/Low side band select.

[0]: Up side band, [1]: Low side band.

Refer to section 14.2 for details.

QDLS: limiter amp quick settle select.

[0]: enable, [1]: disable.

9.2.26 RX Gain Register I (Address: 19h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain I	R/W	MVGS	AGLNE	IGC	MGC1	MGC0	LGC2	LGC1	LGC0
Reset		0	0	1	0	0	0	0	0

MVGS: Manual VGA calibrate. Recommend MVGS = [1].

[0]: Auto. [1]: Manual

AGLNE: Reserved for internal usage only. Shall be set to [0].

IGC: Reserved for internal usage only. Shall be set to [0].

MGS [1:0]: Mixer gain. Recommend MGS = [00].

[00]: 24dB. [01]: 18dB. [10]: 12dB. [11]: 6dB.

LGS [2:0]: LNA gain. Recommend LGS = [000].

[000]: 24dB. [001]: 18dB. [010]: 12dB. [011]: 6dB. [1XX]: 0dB.

9.2.27 RX Gain Register II (Address: 1Ah)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain II	R	RHR7	RHR6	RHR5	RHR4	RHR3	RHR2	RHR1	RHR0
	W	RH7	RH 6	RH5	RH4	RH3	RH2	RH1	RH0
Reset		0	0	0	0	1	0	1	0

RHR [7:0]: RSSI calibration reading for high input power –78dBm.

RH [7:0]: Reserved for internal usage only.

9.2.28 RX Gain Register III (Address: 1Bh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain III	R	RLR7	RLR6	RLR5	RLR4	RLR3	RLR2	RLR1	RLR0
	W	RL7	RL6	RL5	RL4	RL3	RL2	RL1	RL0
Reset		1	0	1	1	0	1	0	0

RLR [7:0]: RSSI calibration reading for low input power –90dBm.

RL [7:0]: Reserved for internal usage only.

9.2.29 RX Gain Register IV (Address: 1Ch)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX Gain IV	W	ENG C	CRCD	MVSEL1	MVSEL0	MHC	LHC1	LHC0	VGCE
Reset		1	0	1	0	1	1	1	0

ENG C: Reserved for internal usage only. Shall be set to [0].



A7106

Preliminary

2.4G FSK/GFSK Transceiver

CRCD: CRC package filtering select.

[0]: disable, [1]: enable.

MVSEL [1:0]: moving average bits select for RSSI calibration.

[00]: 8 bit, [01]: 32bit, [10]: 64bit, [11]: 128bit.

MHC: Reserved for internal usage only. Shall be set to [0].

LHC: Reserved for internal usage only. Shall be set to [01].

VGCE: Reserved for internal usage only. Shall be set to [0].

9.2.30 RSSI Threshold Register (Address: 1Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RSSI Threshold	R	ADC7	ADC6	ADC5	ADC4	ADC3	ADC2	ADC1	ADC0
	W	RTH7	RTH6	RTH5	RTH4	RTH3	RTH2	RTH1	RTH0
Reset		1	0	0	1	0	0	0	1

RTH [7:0]: Carrier detect threshold.

Refer to Chapter 17 for details.

ADC [7:0]: ADC output value for RSSI measurement.

ADC input voltage= 1.2 * ADC [7:0] / 256 V.

Refer to chapter 17 for details.

9.2.31 ADC Control Register (Address: 1Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ADC Control	W	RSM1	RSM0	ERSS	FSARS	--	XADS	RSS	CDM
Reset		0	1	0	1	--	0	1	1

RSM [1:0]: RSSI margin = RTH – RTL. Recommend RSM = [11].

[00]: 5. [01]: 10. [10]: 15. [11]: 20.

Refer to Chapter 17 for details.

ERSS: End for RSSI measurement

[0]: RSSI measurement continues until leave off RX mode.

[1]: RSSI measurement will end when carrier detected and ID code word received.

FSARS: ADC clock select. Recommend FSARS = [0].

[0]: 4MHz. [1]: 8MHz.

XADS: ADC input signal select.

[0]: Convert RSS signal. [1]: Reserved for internal usage.

RSS: RSSI measurement select.

[0]: Reserved for internal usage. [1]: RSSI or carrier-detect measurement.

CDM: RSSI measurement mode.

[0]: Single mode. [1]: Continuous mode.

9.2.32 Code Register I (Address: 1Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code I	W	--	MCS	WHTS	FECS	CRCS	IDL	PML1	PML0
Reset		--	0	0	0	0	1	1	1

WHTS: Data whitening (Data Encryption) select.

[0]: Disable. [1]: Enable.

FECS: FEC select.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

[0]: Disable. [1]: Enable.

CRCS: CRC select.

[0]: Disable. [1]: Enable.

IDL: ID code length select. Recommend IDL= [1].

[0]: 2 bytes. [1]: 4 bytes.

PML [1:0]: Preamble length select. Recommend PML= [11].

[00]: 1 byte. [01]: 2 bytes. [10]: 3 bytes. [11]: 4 bytes.

Refer to chapter 16 for details.

9.2.33 Code Register II (Address: 20h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code II	W	--	DCL2	DCL1	DCL0	ETH1	ETH0	PMD1	PMD0
Reset		--	1	1	1	0	1	1	1

DCL [2:0]: Demodulator DC estimation average mode. Recommend DCL[2:0] = [001]

ETH [1:0]: ID code error tolerance. Recommend ETH = [01].

[00]: 0 bit. [01]: 1 bit. [10]: 2 bits. [11]: 3 bits.

PMD [1:0]: Preamble pattern detection length.

[00]: 0bit. [01]: 4bits. [10]: 8bits. [11]: 16bits.

Data Rate (Kbps)	PMD[1:0]	Note
2 ~ 125	11	Also refer to addr. 29h
250 / 500	10	

Refer to chapter 16 for details.

9.2.34 Code Register III (Address: 21h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code III	W	--	WS6	WS5	WS4	WS3	WS2	WS1	WS0
Reset		--	0	1	0	1	0	1	0

WS [6:0]: Data Whitening seed setting (data encryption key).

Refer to chapter 16 for details.

9.2.35 IF Calibration Register I (Address: 22h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IF Calibration I	R				FBCF	FB3	FB2	FB1	FB0
	W	--	--	--	MFBS	MFB3	MFB2	MFB1	MFB0
Reset		--	--	--	0	0	1	1	0

MFBS: IF filter calibration value select. Recommend MFBS = [0].

[0]: Auto calibration value. [1]: Manual calibration value.

MFB [3:0]: IF filter manual calibration value.

FBCF: IF filter auto calibration flag.

[0]: Pass. [1]: Fail.

FB [3:0]: IF filter calibration value.

MFBS= 0: Auto calibration value (AFB),

MFBS= 1: Manual calibration value (MFB).

Refer to chapter 15 for details.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

9.2.36 IF Calibration Register II (Address: 23h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IF Calibration II	R	--	--		FCD4	FCD3	FCD2	FCD1	FCD0
Reset		--	--	--	--	--	--	--	--

FCD [4:0]: IF filter calibration deviation from goal (Read only).

9.2.37 VCO current Calibration Register (Address: 24h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO current Calibration	R				FVCC	VCB3	VCB2	VCB1	VCB0
	W	--	--	VCCS	MVCS	VCOC3	VCOC2	VCOC1	VCOC0
Reset		--	--	0	0	1	0	0	0

VCCS: Reserved for internal usage only. Shall be set [0].

MVCS: VCO current calibration value select. Recommend MVCS = [1].

[0]: Auto calibration value. [1]: Manual calibration value.

VCOC [3:0]: VCO current manual calibration value. Recommend VCOC = [011].

FVCC: VCO current auto calibration flag.

[0]: Pass. [1]: Fail.

VCB [3:0]: VCO current calibration value.

MVCS= 0: Auto calibration value (VCB).

MVCS= 1: Manual calibration value (VCOC).

Refer to chapter 15 for details.

9.2.38 VCO Single band Calibration Register I (Address: 25h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band Calibration I	R	--	--	DVT1	DVT0	VBCF	VB2	VB1	VB0
	W	--	--	--	--	MVBS	MVB2	MVB1	MVB0
Reset		--	--	--	--	0	1	0	0
Reset		--	--	--	--	0	1	0	0

MVBS: VCO bank calibration value select. Recommend MVBS = [0].

[0]: Auto calibration value. [1]: Manual calibration value.

MVB [2:0]: VCO band manual calibration value.

DVT [1:0]: digital VCO tuning voltage output.

[00]: $VT < VTL < VTH$. [01]: $VTL < VT < VTH$. [10]: No used. [11]: $VTL < VTH < VT$.

VBCF: VCO band auto calibration flag.

[0]: Pass. [1]: Fail.

VB [2:0]: VCO bank calibration value.

MVBS= 0: Auto calibration value (AVB).

MVBS= 1: Manual calibration value (MVB).

Refer to chapter 15 for details.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

9.2.39 VCO Single band Calibration Register II (Address: 26h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band Calibration II	W	--	--	VTH2	VTH1	VTH0	VTL2	VTL1	VTL0
Reset		--	--	1	1	1	0	1	1

VTH [2:0]: VCO tuning voltage upper threshold level setting. Recommend VTH = [111].

[000]: VDD_A – 0.6V. [001]: VDD_A – 0.7V. [010]: VDD_A – 0.8V. [011]: VDD_A – 0.9V

[100]: VDD_A – 1.0V. [101]: VDD_A – 1.1V. [110]: VDD_A – 1.2V. [111]: VDD_A – 1.3V

VDD_A is on chip analog regulator output voltage

VTL [2:0]: VCO tuning voltage lower threshold level setting. Recommend VTL = [011].

[000]: 0.1V. [001]: 0.2V. [010]: 0.3V. [011]: 0.4V.

[100]: 0.5V. [101]: 0.6V. [110]: 0.7V. [111]: 0.8V

9.2.40 Battery detect Register (Address: 27h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Battery detect	R	RGS	RGV1	RGV0	BDF	BVT2	BVT1	BVT0	BD_E
	W	RGS	RGV1	RGV0	QDS	BVT2	BVT1	BVT0	BDS
Reset		0	0	0	0	0	1	1	0

RGS: VDD_D voltage setting in Sleep mode.

[0]: 3/5 * REG1. [1]: 3/4 * REG1.

RGV [1:0]: VDD_D and VDD_A voltage setting in non-Sleep mode. Recommend RGV = [00].

[00]: 2.1V. [01]: 2.0V. [10]: 1.9V. [11]: 1.8V.

BVT [2:0]: Battery voltage detect threshold.

[000]: 2.0V. [001]: 2.1V. [010]: 2.2V. [011]: 2.3V.

[100]: 2.4V. [101]: 2.5V. [110]: 2.6V. [111]: 2.7V.

BDS: Battery detect select.

[0]: Disable. [1]: Enable. It will be clear after battery detection done.

BDF: Battery detection flag.

[0]: Battery voltage less than threshold. [1]: Battery voltage greater than threshold.

QDS: analog regulator quick discharge select when enter sleep mode.

[0]: Disable. [1]: Enable.

Refer to chapter 18 for details.

9.2.41 TX test Register (Address: 28h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TX test	W	--	--	TXCS	PAC1	PAC0	TBG2	TBG1	TBG0
Reset		--	--	0	1	0	1	1	1

TXCS: TX Current Setting. [0]

PAC [1:0]: PA Current Setting. [10]

TBG [2:0]: TX Buffer Setting. [111]

Typical Output Power (dBm)	Recommend setting			Typical TX current (mA)
	TXCS	TBG	PAC	
1	0	7	3	21



A7106

Preliminary

2.4G FSK/GFSK Transceiver

0	0	7	1	19
-10	0	3	1	14
-20	0	1	0	13

Refer to chapter 19 and A7106 App. Note for more settings.

9.2.42 Rx DEM test Register I (Address: 29h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Rx DEM test I	W	DMT	DCM1	DCM0	MLP1	MLP0	SLF2	SLF1	SLF0
Reset		0	1	1	0	0	1	0	0

DMT: Reserved for internal usage only. Shall be set to [0].

DCM [1:0]: Demodulator DC estimation mode.

[00]: Fix mode (For testing only). DC level is set by DCV [7:0].

[01]: Preamble hold mode. DC level is preamble average value.

[10]: Average and hold mode. DC level is the average value hold about 8 bit data rate later if preamble is detected.

[11]: Payload average mode (For internal usage). DC level is payload data average.

DCM [1:0]	Data Rate (Kbps)	DCL[2:0] (20h)	Note
01	2 ~ 125	001	By Preamble
10	250 / 500	001	By ID

MLP [1:0]: Reserved for internal usage only. Shall be set to [00].

SLF [2:0]: Reserved for internal usage only. Shall be set to [111].

9.2.43 Rx DEM test Register II (Address: 2Ah)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Rx DEM test II	W	DCV7	DCV6	DCV5	DCV4	DCV3	DCV2	DCV1	DCV0
Reset		1	0	0	0	0	0	0	0

DCV [7:0]: Demodulator fix mode DC value. Recommend DCV = [0x80].

9.2.44 Charge Pump Current Register (Address: 2Bh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Charge Pump Current	W	ROSCS	CELS	RGC1	RGC0	STS	LVR	CPC1	CPC0
Reset		0	0	0	0	0	0	0	1

CPC [1:0]: Charge pump current setting. Recommend CPC = [11].

[00]: 0.5mA. [01]: 1.0mA. [10]: 1.5mA. [11]: 2.0mA

LVR: Reserved for internal usage only. Shall be set to [0].

STS: Reserved for internal usage only. Shall be set to [0].

RGC [1:0]: Reserved for internal usage only. Shall be set to [00].

CELS: Reserved for internal usage only. Shall be set to [0].

ROSCS: Reserved for internal usage only. Shall be set to [0].

9.2.45 Crystal test Register (Address: 2Ch)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Crystal test	W	RSIS	PKT1	PKT0	PKS	DBD	XCC	XCP1	XCP0
Reset		0	0	0	0	0	1	0	1



A7106

Preliminary

2.4G FSK/GFSK Transceiver

DBD: Reserved for internal usage only. Shall be set to [0].

XCC: Reserved for internal usage only. Shall be set to [0].

XCP [1:0]: Reserved for internal usage only. Shall be set to [01].

PKS: Reserved for internal usage only. Shall be set to [0].

PKT [1:0]: Reserved for internal usage only. Shall be set to [0].

RSIS [1:0]: Reserved for internal usage only. Shall be set to [00].

9.2.46 PLL test Register (Address: 2Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL test	W	PRS	PMPE	PRIC1	PRIC0	PRRC1	PRRC0	SDPW	NSDO
Reset		0	1	1	0	1	0	0	0

PMPE: Reserved for internal usage only. Shall be set to [1].

PRRC [1:0]: Reserved for internal usage only. Shall be set to [00].

PRIC [1:0]: Reserved for internal usage only. Shall be set to [01].

SDPW: Reserved for internal usage only. Shall be set to [0].

NSDO: Reserved for internal usage only. Shall be set to [1].

PRS: PLL register IV and V reading select.

Refer to 9.2.20 PLL register V description for details.

9.2.47 VCO test Register I (Address: 2Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO test I	W	MQDL	--	--	TLB1	TLB0	RLB1	RLB0	VCBS
Reset		0	--	--	1	1	0	1	0

TLB [1:0]: Reserved for internal usage only. Shall be set to [11].

RLB [1:0]: Reserved for internal usage only. Shall be set to [00].

VCBS: Reserved for internal usage only. Shall be set to [0].

MQDL: Reserved for internal usage only. Shall be set to [0].

9.2.48 VCO test Register II (Address: 2Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO test II	W	--	--	--	--	RFT3	RFT2	RFT1	RFT0
Reset		--	--	--	--	0	0	0	0

RFT [3:0]: RF analog pin configuration for testing. Recommend RFT= [0000].

9.2.49 IFAT Register (Address: 30h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO test II	W	IGFI2	IGFI1	IGFI0	IGFQ2	IGFQ1	IGFQ0	IFBC	LIMC
Reset		1	0	0	1	0	0	1	1

IGFI [2:0]: Reserved for internal usage only. Shall be set to [000].

IGFQ [2:0]: Reserved for internal usage only. Shall be set to [000].



A7106

Preliminary

2.4G FSK/GFSK Transceiver

IFBC: Reserved for internal usage only. Shall be set to [0].

LIMC: Reserved for internal usage only. Shall be set to [1].

9.2.50 RScale Register (Address: 31h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Rscale	W	RSC7	RSC6	RSC5	RSC4	RSC3	RSC2	RSC1	RSC0
Reset		0	0	0	0	1	1	1	1

RSC [7:0]: Reserved for internal usage only. Shall be set to = [0x0F].

9.2.51 Filter test Register (Address: 32h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Filter test	W	FT7	FT6	FT5	FT4	FT3	FT2	FT1	FT0
Reset									

FT [7:0]: Reserved for internal usage only. Shall be set to = [0x00].

9.2.52 Filter test Register II (Address: 33h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
TMV	W	--	TRT2	TRT1	TRT0	ASMV2	ASMV1	ASMV0	AMVS
Reset		--	0	0	0	0	0	0	0

AMVS: TX ramping up and down select.

[0]: disable, [1]: enable.

ASMV [2:0]: TX ramp up timing select.

Ramping up time = 2* ASMV us

[000]: 2us. [001]: 4us. [010]: 6us. [011]: 8us.

[100]: 10us. [101]: 12us. [110]: 14us. [111]: 16us.

TRT [2:0]: TX ramping time select.

Ramping down time = 2*TRT us

[000]: 2us. [001]: 4us. [010]: 6us. [011]: 8us.

[100]: 10us. [101]: 12us. [110]: 14us. [111]: 16us.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

10. SPI

A7106 only supports one SPI interface with maximum data rate up to 10Mbps. MCU should assert SCS pin low (SPI chip select) to active accessing of A7106. Via SPI interface, user can access **control registers** and issue **Strobe command**. Figure 10.1 gives an overview of SPI access manners.

3-wire SPI (SCS, SCK and SDIO) or 4-wire SPI (SCS, SCK, SDIO and GIO1/GIO2) configuration is provided. For 3-wire SPI, SDIO pin is configured as bi-direction to be data input and output. For 4-wire SPI, SDIO pin is data input and GIO1 (or GIO2) pin is data output. In such case, GIO1S (0bh) or GIO2S (0ch) should be set to [0110].

For SPI write operation, SDIO pin is latched into A7106 at the rising edge of SCK. For SPI read operation, if input address is latched by A7106, data output is aligned at falling edge of SCK. Therefore, MCU can latch data output at the rising edge of SCK.

To control A7106's internal state machine, it is very easy to send Strobe command via SPI interface. The Strobe command is a unique command set with total 8 commands. See section 10.3, 10.4 and 10.5 for details.

	SPI chip select	Data In	Data Out
3-Wire SPI	SCS pin = 0	SDIO pin	SDIO pin
4-Wire SPI	SCS pin = 0	SDIO pin	GIO1 (GIO1S=0110) / GIO2 (GIO2S=0110)



Figure 10.1 SPI Access Manners



A7106

Preliminary

2.4G FSK/GFSK Transceiver

10.1 SPI Format

The first bit (A7) is critical to indicate A7106 the following instruction is “Strobe command” or “control register”. See Table 10.1 for SPI format. Based on Table 10.1, To access control registers, just set A7=0, then A6 bit is used to indicate read (A6=1) or write operation (A6=0). See Figure 10.2 (3-wire SPI) and Figure 10.3 (4-wire SPI) for details.

Address Byte (8 bits)								Data Byte (8 bits)							
CMD	R/W	Address						Data							
A7	A6	A5	A4	A3	A2	A1	A0	7	6	5	4	3	2	1	0

Table 10.1 SPI Format

Address byte:

Bit 7: Command bit

- [0]: Control registers.
- [1]: Strobe command.

Bit 6: R/W bit

- [0]: Write data to control register.
- [1]: Read data from control register.

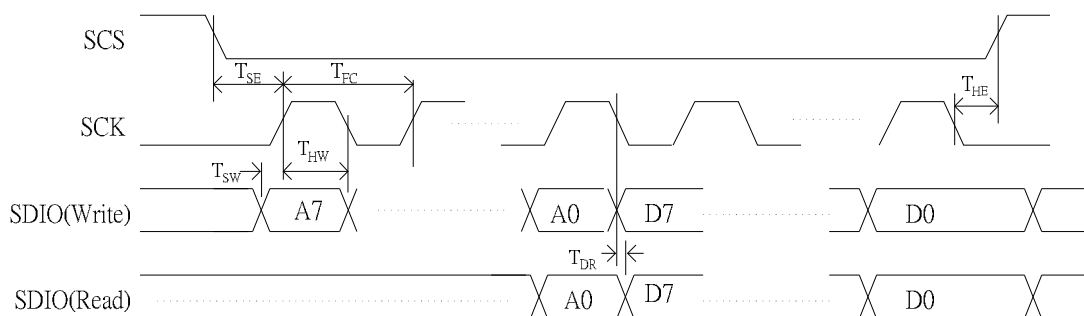
Bit [5:0]: Address of control register

Data Byte:

Bit [7:0]: SPI input or output data, see Figure 10.2 and Figure 10.3 for details.

10.2 SPI Timing Characteristic

No matter 3-wire or 4-wire SPI interface is configured, the maximum SPI data rate is 10 Mbps. To active SPI interface, SCS pin must be set to low. For correct data latching, user has to take care hold time and setup time between SCK and SDIO. See Table 10.2 for SPI timing characteristic.



Parameter	Description	Min.	Max.	Unit
F _C	FIFO clock frequency.		10	MHz
T _{SE}	Enable setup time.	50		ns
T _{HE}	Enable hold time.	50		ns
T _{SW}	TX Data setup time.	50		ns
T _{HW}	TX Data hold time.	50		ns
T _{DR}	RX Data delay time.	0	50	ns

Table 10.2 SPI Timing Characteristic



A7106

Preliminary

2.4G FSK/GFSK Transceiver

10.3 SPI Timing Chart

In this section, 3-wire and 4-wire SPI interface read / write timing are described.

10.3.1 Timing Chart of 3-wire SPI

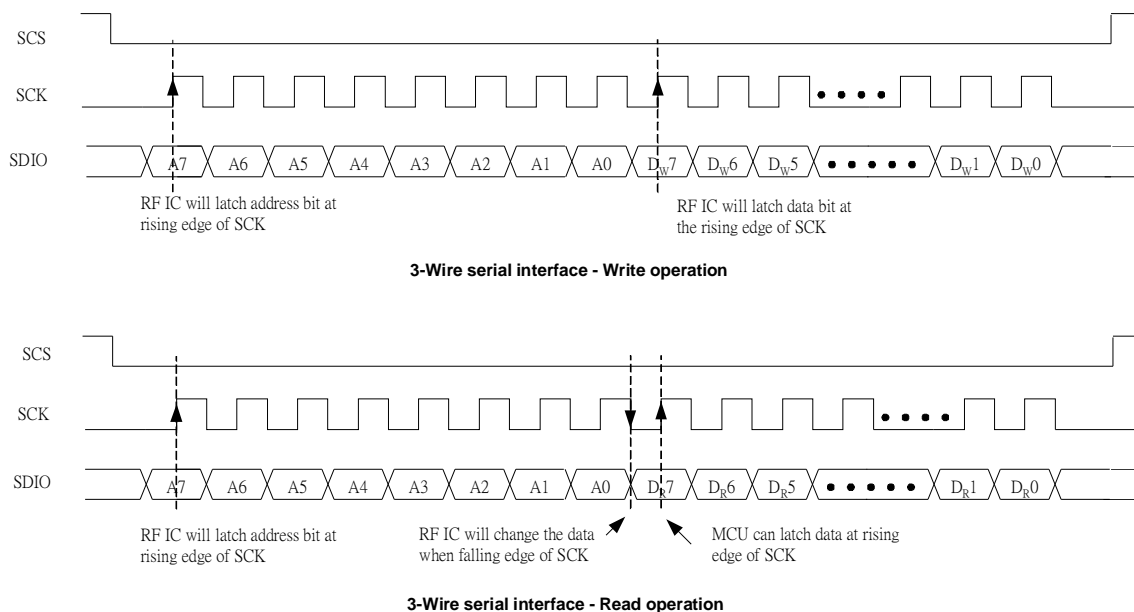


Figure 10.2 Read/Write Timing Chart of 3-Wire SPI

10.3.2 Timing Chart of 4-wire SPI

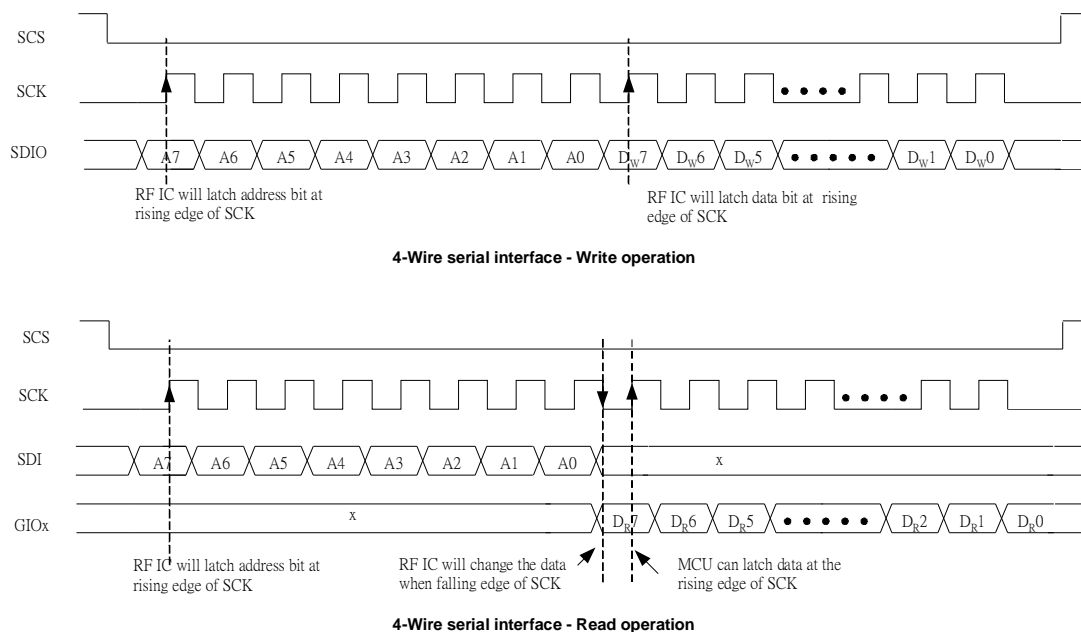


Figure 10.3 Read/Write Timing Chart of 4-Wire SPI



A7106

Preliminary

2.4G FSK/GFSK Transceiver

10.4 Strobe Commands

A7106 supports 8 Strobe commands to control internal state machine for chip's operations. Table 10.3 is the summary of Strobe commands.

Be notice, Strobe command could be defined by 4-bits (A7~A4) or 8-bits (A7~A0). If 8-bits Strobe command is selected, A3 ~ A0 are don't care conditions. In such case, SCS pin can be remaining low for asserting next commands.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	0	0	x	X	x	x	Sleep mode
1	0	0	1	x	X	x	x	Idle mode
1	0	1	0	x	X	x	x	Standby mode
1	0	1	1	x	X	x	x	PLL mode
1	1	0	0	x	X	x	x	RX mode
1	1	0	1	x	X	x	x	TX mode
1	1	1	0	x	X	x	x	FIFO write pointer reset
1	1	1	1	x	X	x	x	FIFO read pointer reset

Table 10.3 Strobe Commands by SPI interface

10.4.1 Strobe Command - Sleep Mode

Refer to Table 10.3 user can issue 4 bits (1000) Strobe command directly to set A7106 into Sleep mode. Below are the Strobe command table and timing chart.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	0	0	x	X	x	x	Sleep mode

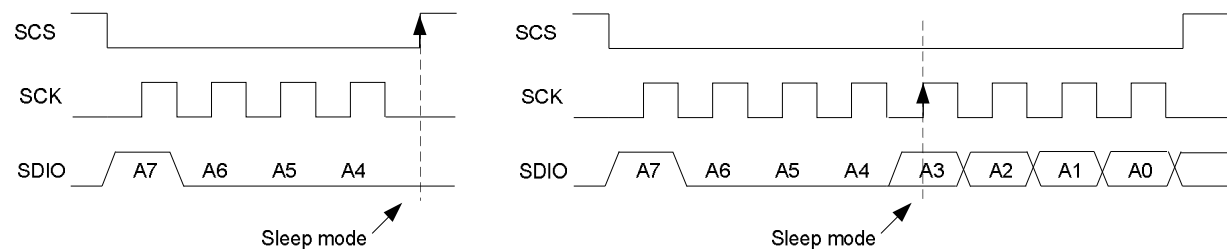


Figure 10.4 Sleep mode Command Timing Chart

10.4.2 Strobe Command - Idle Mode

Refer to Table 10.3, user can issue 4 bits (1001) Strobe command directly to set A7106 into Idle mode. Below is the Strobe command table and timing chart.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	0	1	x	X	x	x	Idle mode

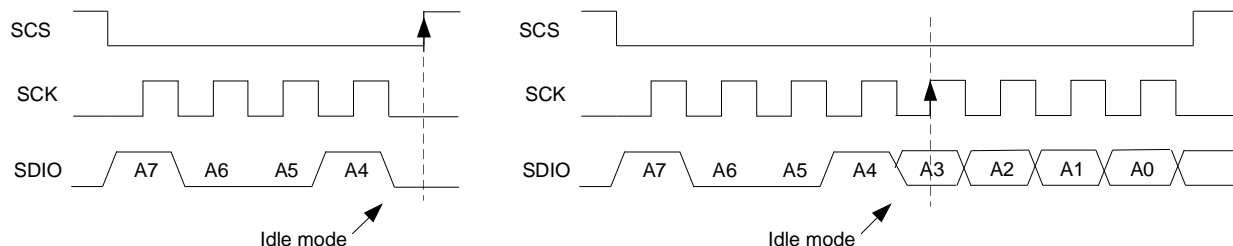


Figure 10.5 Idle mode Command Timing Chart

10.4.3 Strobe Command - Standby Mode

Refer to Table 10.3, user can issue 4 bits (1010) Strobe command directly to set A7106 into Standby mode. Below is the Strobe command table and timing chart.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	1	0	x	X	x	x	Standby mode

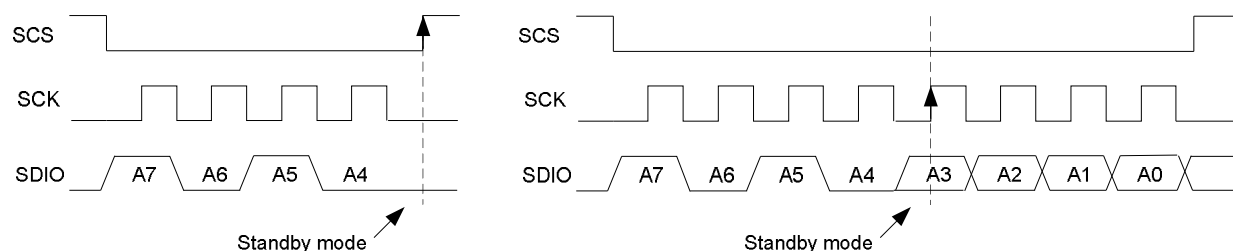


Figure 10.6 Standby mode Command Timing Chart

10.4.4 Strobe Command - PLL Mode

Refer to Table 10.3, user can issue 4 bits (1011) Strobe command directly to set A7106 into PLL mode. Below are the Strobe command table and timing chart.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	0	1	1	x	X	x	x	PLL mode



A7106

Preliminary

2.4G FSK/GFSK Transceiver

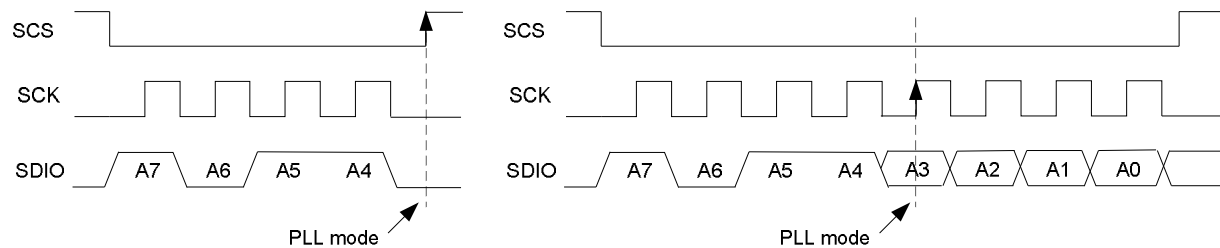


Figure 10.7 PLL mode Command Timing Chart

10.4.5 Strobe Command - RX Mode

Refer to Table 10.3, user can issue 4 bits (1100) Strobe command directly to set A7106 into RX mode. Below are the Strobe command table and timing chart.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	0	0	x	x	x	x	RX mode

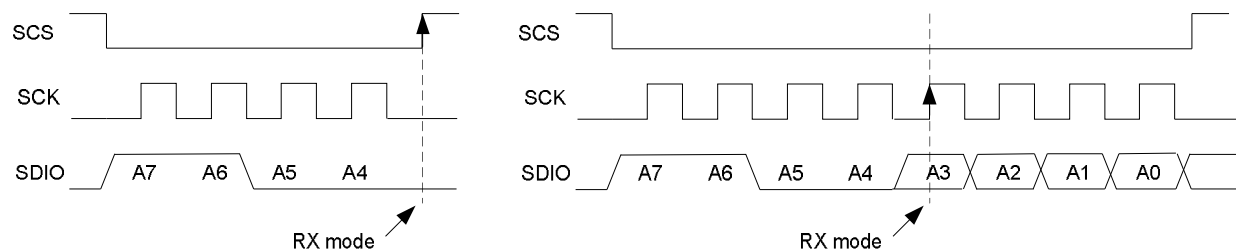


Figure 10.8 RX mode Command Timing Chart

10.4.6 Strobe Command - TX Mode

Refer to Table 10.3, user can issue 4 bits (1101) Strobe command directly to set A7106 into TX mode. Below are the Strobe command table and timing chart.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	0	1	x	x	x	x	TX mode

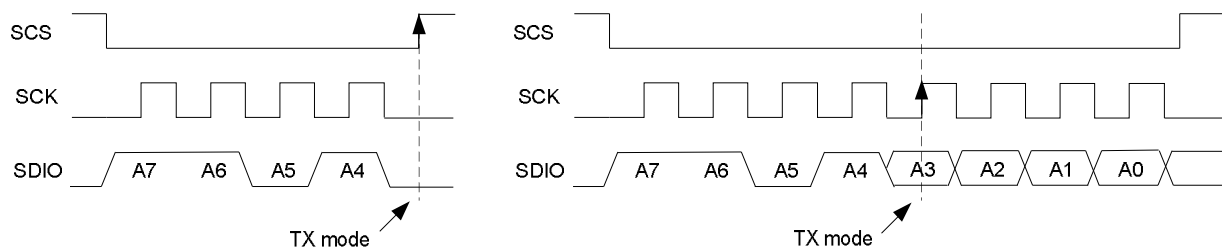


Figure 10.9 TX mode Command Timing Chart



A7106

Preliminary

2.4G FSK/GFSK Transceiver

10.4.7 Strobe Command – FIFO Write Pointer Reset

Refer to Table 10.3, user can issue 4 bits (1110) Strobe command directly to reset A7106 FIFO write pointer. Below is the Strobe command table and timing chart.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	1	0	x	x	x	x	FIFO write pointer reset

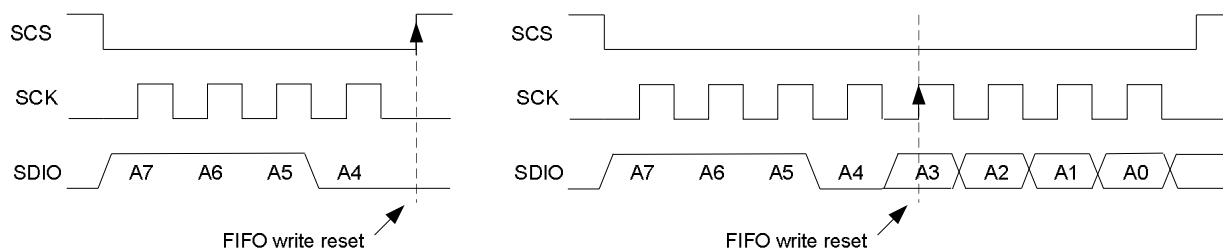


Figure 10.10 FIFO write pointer reset Command Timing Chart

10.4.8 Strobe Command – FIFO Read Pointer Reset

Refer to Table 10.3, user can issue 4 bits (1111) Strobe command directly to reset A7106 FIFO read pointer. Below are the Strobe command table and timing chart.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	1	1	x	x	x	x	FIFO read pointer reset

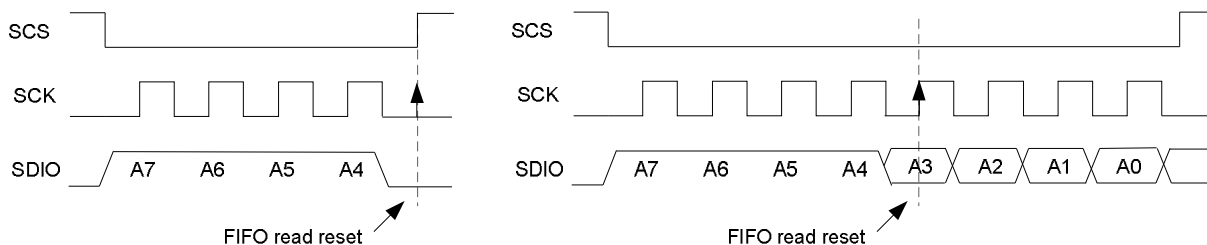


Figure 10.11 FIFO read pointer reset Command Timing Chart

10.5 Reset Command

In addition to power on reset (POR), MCU could issue software reset to A7106 by setting Mode Register (00h) through SPI interface as shown below. As long as 8-bits address (A7~A0) are delivered zero and data (D7~D0) are delivered zero, A7106 is informed to generate internal signal "RESETN" to initial itself. After reset command, A7106 is in standby mode and calibration procedure shall be issued again.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

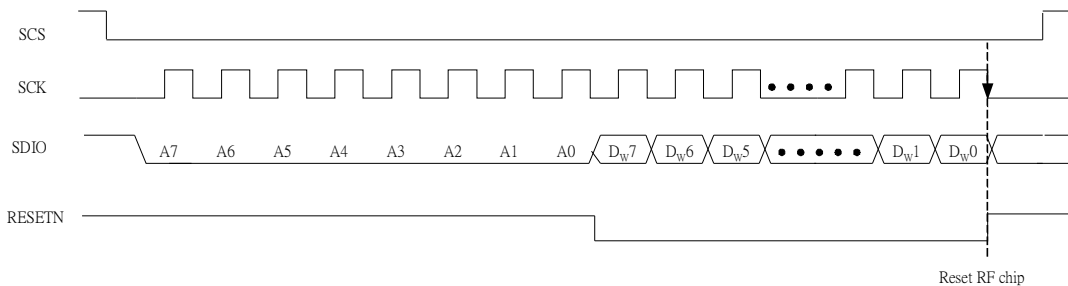


Figure 10.12 Reset Command Timing Chart

10.6 ID Accessing Command

A7106 has built-in 32-bits ID Registers for customized identification code. It is accessed via SPI interface. ID length is recommended to be 32 bits by setting IDL (1Fh). Therefore, user can toggle SCS pin to high to terminate ID accessing command when ID data is output completely.

Figure 10.13 and 10.14 are timing charts of 32-bits ID accessing via 3-wire SPI.

10.6.1 ID Write Command

User can refer to Figure 10.2 for SPI write timing chart in details. Below is the procedure of ID write command.

- Step1: Deliver A7~A0 = 00000110 (A6=0 for write, A5~A0 = 000110 for ID addr, 06h).
- Step2: By SDIO pin, deliver 32-bits ID into A7106 in sequence by Data Byte 0 (**recommend 5xh or Axh**), 1, 2 and 3.
- Step3: Toggle SCS pin to high when step2 is completed.

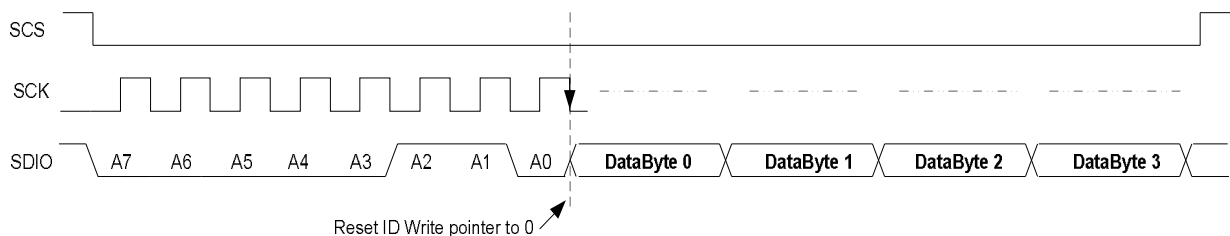


Figure 10.13 ID Write Command Timing Chart

10.6.2 ID Read Command

User can refer to Figure 10.2 for SPI read timing chart in details. Below is the procedure of ID read command.

- Step1: Deliver A7~A0 = 01000110 (A6=1 for read, A5~A0 = 000110 for ID addr, 06h).
- Step2: SDIO pin outputs 32-bits ID in sequence by Data Byte 0, 1, 2 and 3.
- Step3: Toggle SCS pin to high when step2 is completed.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

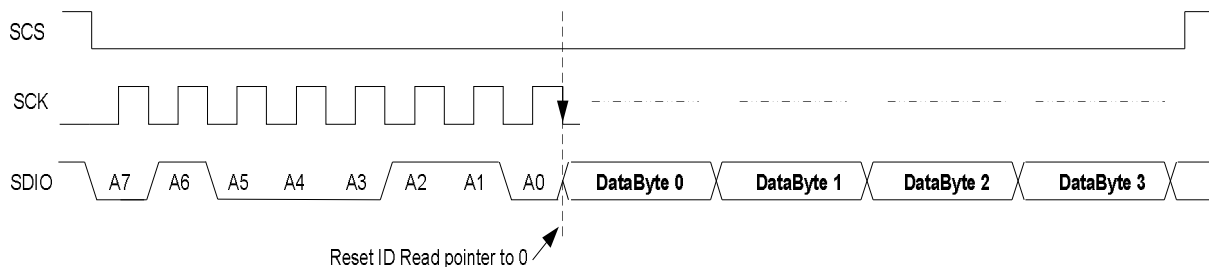


Figure 10.14 ID Read Command Timing Chart

10.7 FIFO Accessing Command

To use A7106's FIFO mode, enable FMS (01h) = 1 via SPI interface. Before TX delivery, just write wanted data into TX FIFO (05h) then issue TX Strobe command. Similarly, user can read RX FIFO (05h) once payload data is received.

MCU can use polling or interrupt scheme to do FIFO accessing. FIFO status can output to GIO1 (or GIO2) pin by setting GIO1S (0Bh) or GIO2S (0Ch).

Figure 10.15 and 10.16 are timing charts of FIFO accessing via 3-wire SPI.

10.7.1 TX FIFO Write Command

User can refer to Figure 10.2 for SPI write timing chart in details. Below is the procedure of TX FIFO write command.

- Step1: Deliver A7~A0 = 00000101 (A6=0 for write control register and issue FIFO A [5:0] = 05h).
- Step2: By SDIO pin, deliver (n+1) bytes TX data into TX FIFO in sequence by Data Byte 0, 1, 2 to n.
- Step3: Toggle SCS pin to high when step2 is completed.
- Step4: Send Strobe command of TX mode (Figure 10.9) to do TX delivery.

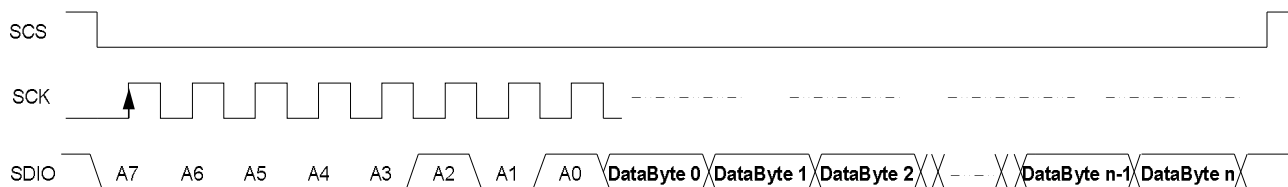


Figure 10.15 TX FIFO Write Command Timing Chart

10.7.2 Rx FIFO Read Command

User can refer to Figure 10.2 for SPI read timing chart in details. Below is the procedure of RX FIFO read command.

- Step1: Deliver A7~A0 = 01000101 (A6=1 for read control register and issue FIFO at address 05h).
- Step2: SDIO pin outputs RX data from RX FIFO in sequence by Data Byte 0, 1, 2 to n.
- Step3: Toggle SCS pin to high when RX FIFO is read completely.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

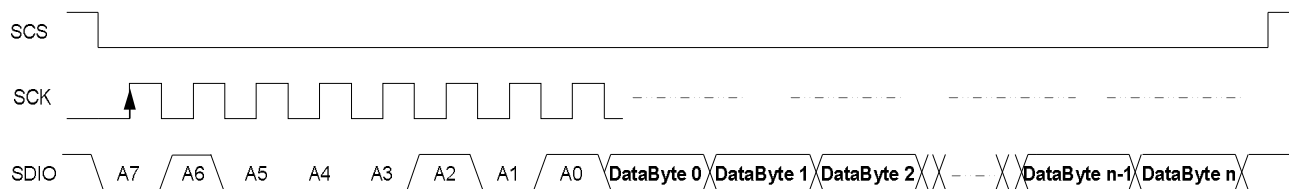


Figure 10.16 RX FIFO Read Command Timing Chart

11. State machine

In chapter 9 and chapter 10, user can not only learn A7106's control registers but also know how to issue Strobe command. From section 10.2 ~ 10.6, it is clear to know configurations of 3-wire SPI and 4-wire SPI, Strobe command, software reset, and how to access ID Registers as well as TX/RX FIFO.

Section 11.1 introduces 7 states of built-in state machine. Combined with Strobe command and accessing control registers, section 11.2, 11.3 and 11.4 demonstrate 3 state diagrams to explain how transitions of A7106's operation.

From accessing data point of view, if FMS=1 (01h), FIFO mode is enabled, otherwise, A7106 is in direct mode. If FMS=1 and FIFO Read/Write in Standby mode, we call it Normal FIFO mode. Otherwise, If FMS=1 and FIFO Read/Write in PLL mode, we called it Quick FIFO mode due to the time reduction of PLL settling. If FMS=1 and FIFO Read/Write in IDLE mode, we called it Power Saving FIFO mode due to the reduction of average current.

	SPI chip select	Data In	Data Out	Operation Mode	Clock Recovery for Direct Mode
3-Wire SPI	SCS pin = 0	SDIO pin	SDIO pin	FIFO (FMS=1) Direct (FMS=0)	CKO pin (CKOS = 0001)
4-Wire SPI	SCS pin = 0	SDIO pin	GIO1 (GIO1S=0110) / GIO2 (GIO2S=0110)	FIFO (FMS=1) Direct (FMS=0)	CKO pin (CKOS = 0001)

- | | |
|----------------------------|---|
| (1) Normal FIFO Mode | (FMS=1 and FIFO R/W @ Standby mode) |
| (2) Quick FIFO Mode | (FMS=1 and FIFO R/W @ PLL mode) |
| (3) Power Saving FIFO Mode | (FMS=1 and FIFO R/W @ IDLE mode) |
| (4) Quick Direct Mode | (FMS=0 and FIFO ignored, write packet @ TX mode, read packet @ RX mode) |

11.1 Key states

A7106 supports 7 key operation states. Those are,

- (1) Standby mode
- (2) Sleep mode
- (3) Idle mode
- (4) PLL mode
- (5) TX mode
- (6) RX mode
- (7) CAL mode

After power on reset or software reset, A7106 is in standby mode. User has to do calibration process because all control registers are in initial values. The calibration process is very easy, user only needs to issue Strobe commands and enable calibration registers. Then, check the calibration flag because it is done automatic by internal state machine. Refer to 11.2, 11.3, 11.4 and chapter 15 for details. After calibration, A7106 is ready to do TX and RX operation.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

11.1.1 Standby mode

If Standby Strobe command is issued, A7106 enters standby mode automatically. Internal power management is listed below. Be notice, A7106 is in standby mode once power on reset or software reset occurs.

Standby mode						Strobe Command
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	OFF	OFF	OFF	OFF	1010xxxxb See Figure 10.6

11.1.2 Sleep mode

If Sleep Strobe command is issued, A7106 enters sleep mode automatically. In sleep mode, A7106 still can accept MCU's commands via SPI interface. But, NOT support to Read/Write FIFO. Internal power management is listed below.

Sleep mode						Strobe Command
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
OFF	OFF	OFF	OFF	OFF	OFF	1000xxxxb See Figure 10.4

11.1.3 Idle mode

If Idle Strobe command is issued, A7106 enters idle mode automatically. In idle mode, A7106 can accept MCU's commands via SPI interface as well as supporting Read/Write FIFO. Internal power management is listed below.

Idle mode						Strobe Command
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	OFF	OFF	OFF	OFF	OFF	1001xxxxb See Figure 10.5

11.1.4 PLL mode

If PLL Strobe command is issued, A7106 enters PLL mode automatically. In PLL mode, internal PLL and VCO are both turned on to generate LO (local oscillator) frequency before TX and RX operation. Internal power management is listed below. According to PLL Register I, II, III, IV and V, PLL circuitry is easy to be controlled by user's definition.

PLL mode						Strobe Command
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	ON	ON	OFF	OFF	1011xxxxb See Figure 10.7

11.1.5 TX mode

If TX Strobe command is issued, A7106 enters TX mode automatically for data delivery. Internal power management is listed below.

(1) In FIFO mode, once TX data packet (Preamble + ID + Payload) is delivered, A7106 supports auto-back function to previous state for next delivered packet.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

(2) In Direct mode, once TX data packet is delivered, A7106 stays in TX mode. User has to issue Strobe command to back to previous state.

TX mode						Strobe Command
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	ON	ON	OFF	ON	(1101xxxx)b See Figure 10.9

11.1.6 RX mode

If RX Strobe command is issued, A7106 enters RX mode automatically for data receiving. Internal power management is listed below.

(1) In FIFO mode, once RX data packet (Preamble + ID + Payload) is received completely, A7106 supports auto-back function to previous state for next receiving packet.

(2) In Direct mode, once RX data packet is received, A7106 stays in RX mode. User has to issue Strobe command to back to previous state.

RX mode						Strobe Command
On Chip Regulator	Crystal Oscillator	VCO	PLL	RX Circuitry	TX Circuitry	
ON	ON	ON	ON	ON	OFF	(1101xxxx)b See Figure 10.9

11.1.7 CAL mode

Calibration process shall be done after power on reset or software reset. Calibration items include VCO and IF Filter. It is easy to implement calibration process by Strobe command and enable CALC (02h) control register. See chapter 15 for details.

Be notice, VCO Calibration is only executable in PLL mode. However, IF Filter Calibration can be executed in Standby or PLL mode.



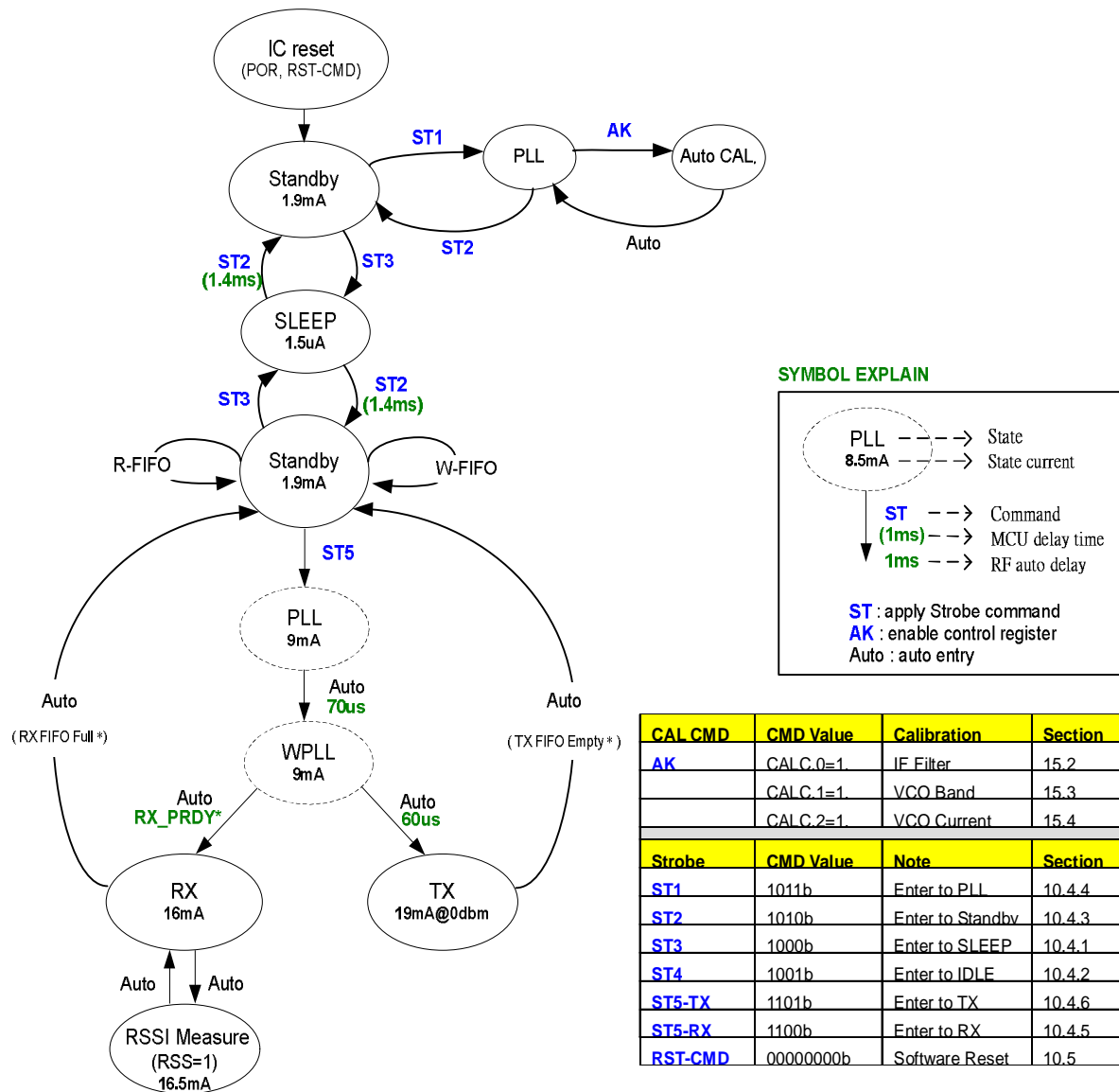
A7106

Preliminary

2.4G FSK/GFSK Transceiver

11.2 Normal FIFO Mode

This mode is suitable for requirement of general purpose applications. After calibration flow, user can issue Strobe command to enter standby mode where write TX FIFO or read RX FIFO. From standby mode to packet transmission, only one Strobe command is needed. Once transmission is done, A7106 is auto back to standby mode. If all packets are finished and deeper power saving is necessary, user can issue Strobe command to ask A7106 staying in sleep mode. Figure 11.1 is the state diagram of Normal FIFO mode.



- Refer to chapter 16 for definition of RX FIFO Full and TX FIFO Empty.
- See Table 11.3 (next page) for RX-PRDY.

Figure 11.1 State diagram of Normal FIFO Mode

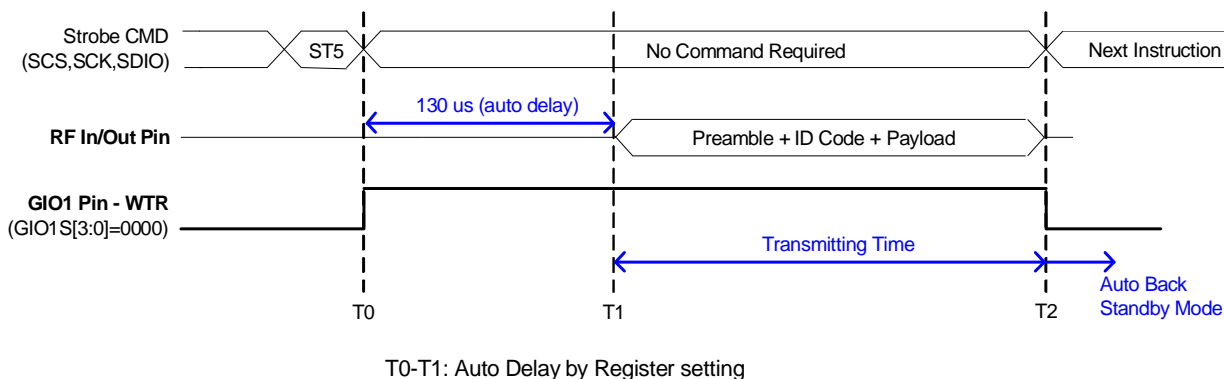


A7106

Preliminary

2.4G FSK/GFSK Transceiver

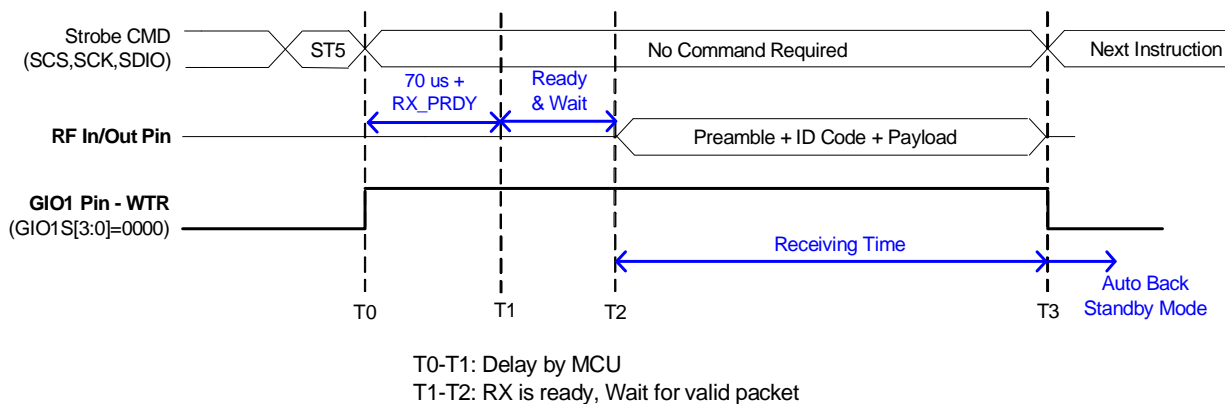
From Figure 11.1, when ST5 command is issued for TX operation, see Figure 11.2 for detailed timing. A7106 status can be represented to GIO1 or GIO2 pin to MCU for timing control.



LO Freq.	Standby to WPLL	WPLL to TX	TX Ready Time
Changed	70 us	60 us	130 us
No Changed	70 us	60 us	130 us

Figure 11.2 Transmitting Timing Chart of Normal FIFO Mode

From Figure 11.1, when ST5 command is issued for RX operation, see Figure 11.3 for detailed timing. A7106 status can be represented to GIO1 or GIO2 pin to MCU for timing control.



LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	Standby to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed / Fixed	<=125K	By preamble (01b)	70 us	40 us	110 us
Changed / Fixed	250K	By ID (10b)	70 us	100 us	170 us
Changed / Fixed	500K	By ID (10b)	70 us	60 us	130 us

Figure 11.3 Receiving Timing Chart of Normal FIFO Mode



A7106

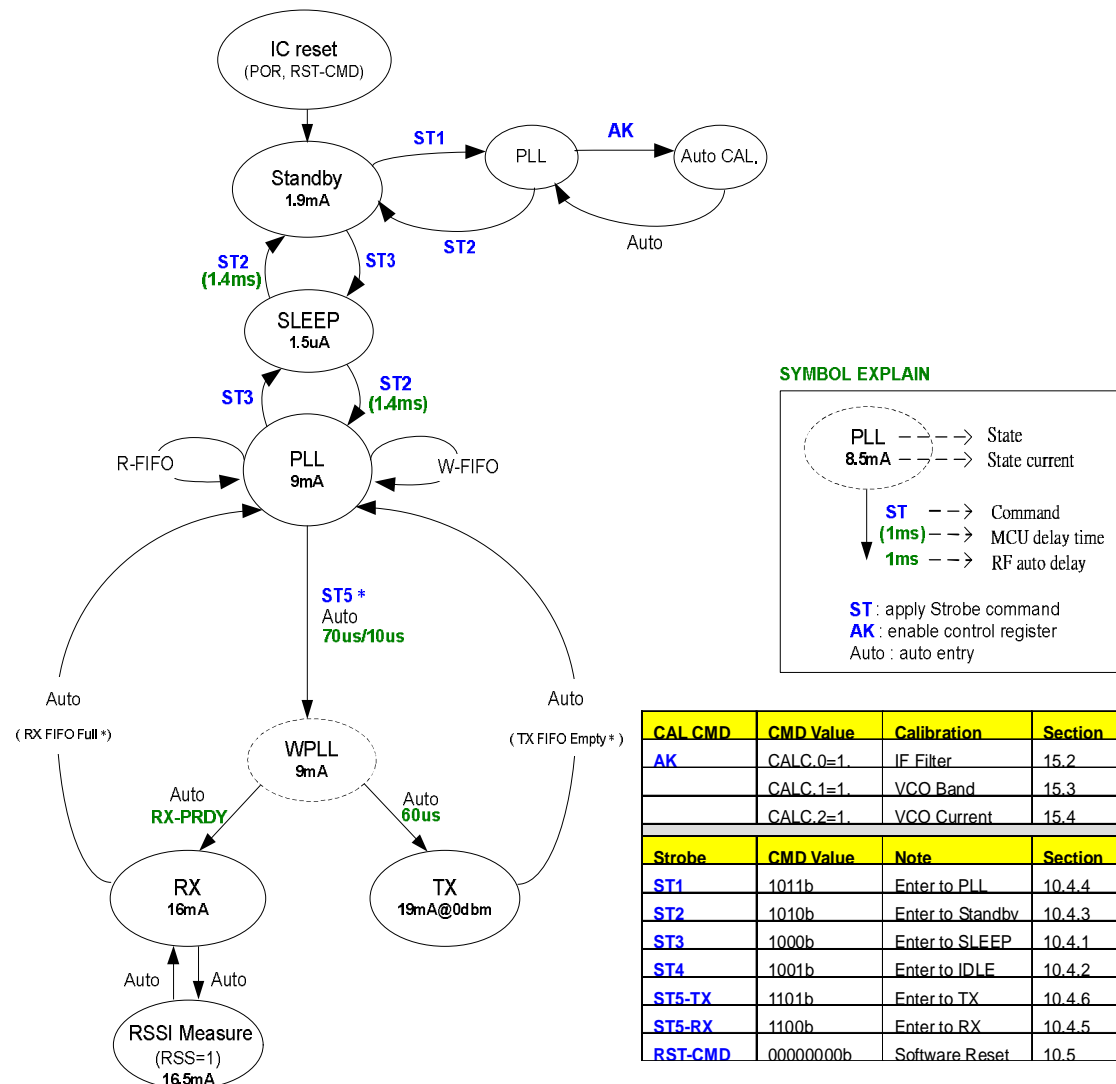
Preliminary

2.4G FSK/GFSK Transceiver

11.3 Quick FIFO Mode

This mode is suitable for requirement of fast transceiving. After calibration flow, user can issue Strobe command to enter PLL mode where write TX FIFO or read RX FIFO. From PLL mode to packet data transceiving, only one Strobe command is needed. Once transceiving is finished, A7106 is auto back to PLL mode.

When packets are finished and deeper power saving is necessary, user can issue Strobe command to ask A7106 staying in sleep mode. Figure 11.4 is the state diagram of Quick FIFO mode.



- Refer to chapter 16 for definition of RX FIFO Full and TX FIFO Empty.
- See Table 11.6 (next page) for RX-PRDY.
- From PLL to WPLL, it is either 70 us (LO frequency changed) or 10 us (LO frequency NOT changed)

Figure 11.4 State diagram of Quick FIFO Mode

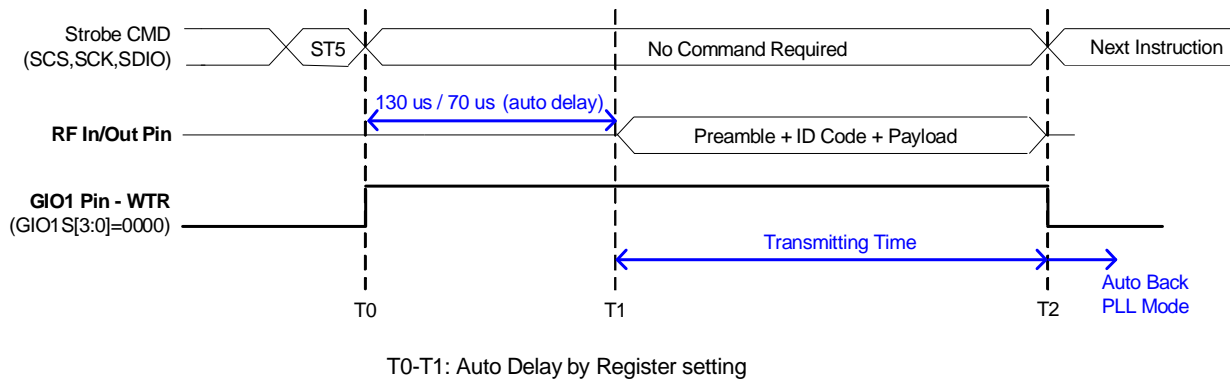


A7106

Preliminary

2.4G FSK/GFSK Transceiver

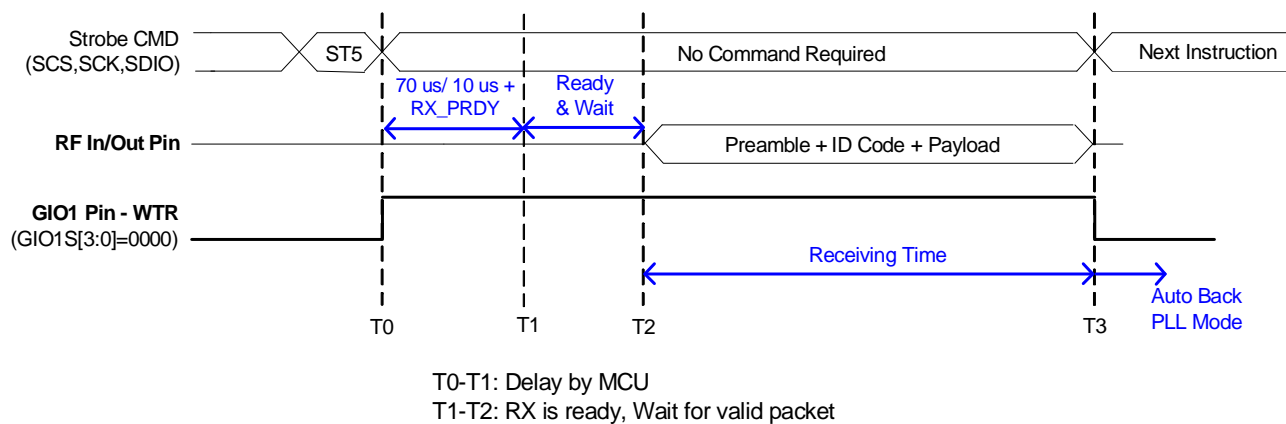
From Figure 11.4, when ST5 command is issued for TX operation, see Figure 11.5 for detailed timing. A7106 status can be represented to GIO1 or GIO2 pin to MCU for timing control.



LO Freq.	PLL to WPLL	WPLL to TX	TX Ready Time
Changed	70 us	60 us	130 us
No Changed	10 us	60 us	70 us

Figure 11.5 Transmitting Timing Chart of Quick FIFO Mode

From Figure 11.4, when ST5 command is issued for RX operation, see Figure 11.6 for detailed timing. A7106 status can be represented to GIO1 or GIO2 pin to MCU for timing control.



LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	PLL to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed	<=125K	By preamble (01b)	70 us	40 us	110 us
Changed	250K	By ID (10b)	70 us	100 us	170 us
Changed	500K	By ID (10b)	70 us	60 us	130 us
Fixed	<=125K	By preamble (01b)	10 us	40 us	50 us
Fixed	250K	By ID (10b)	10 us	100 us	110 us
Fixed	500K	By ID (10b)	10 us	60 us	70 us

Figure 11.6 Receiving Timing Chart of Quick FIFO Mode



A7106

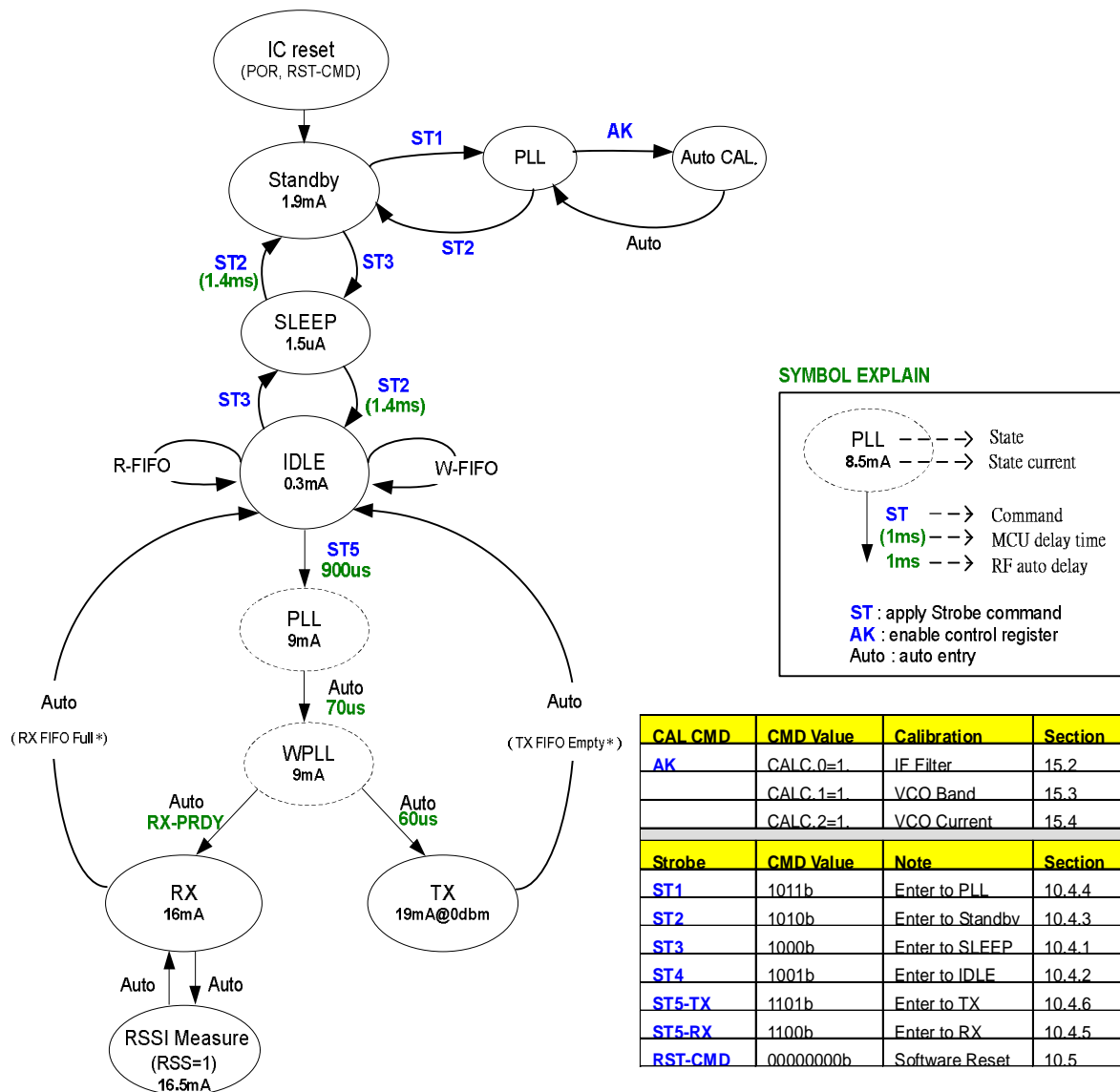
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2.4G FSK/GFSK Transceiver

11.4 Power Saving FIFO Mode

This mode is suitable for requirement of low power consumption. After calibration flow, user can issue Strobe command to enter idle mode where write TX FIFO or read RX FIFO. From idle mode to packet data transceiving, only one Strobe command is needed. Once transmission is done, A7106 is auto back to idle mode.

When packets are finished and deeper power saving is necessary, user can issue Strobe command to ask A7106 staying in sleep mode. Figure 11.7 is the state diagram of Power Saving FIFO mode.



- Refer to chapter 16 for definition of RX FIFO Full and TX FIFO Empty.
- See Table 11.9 (next page) for RX-PRDY..

Figure 11.7 State diagram of Power Saving FIFO Mode

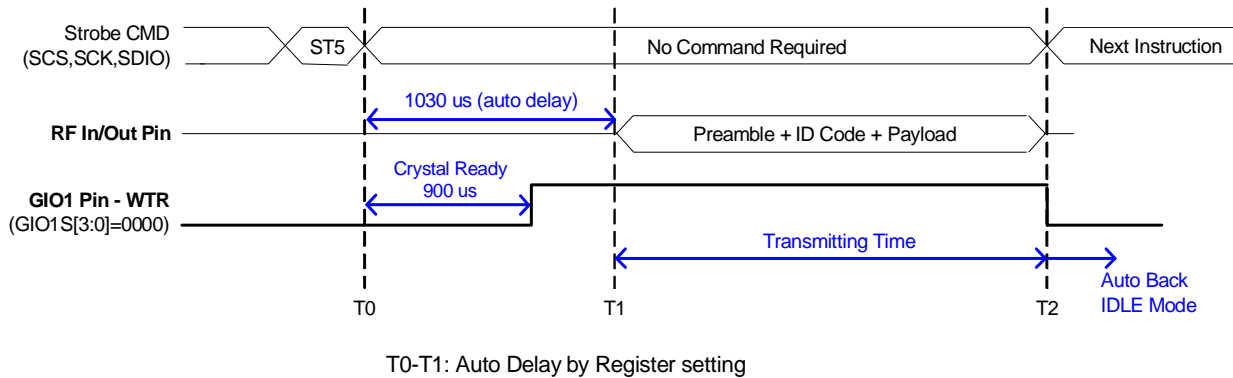


A7106

Preliminary

2.4G FSK/GFSK Transceiver

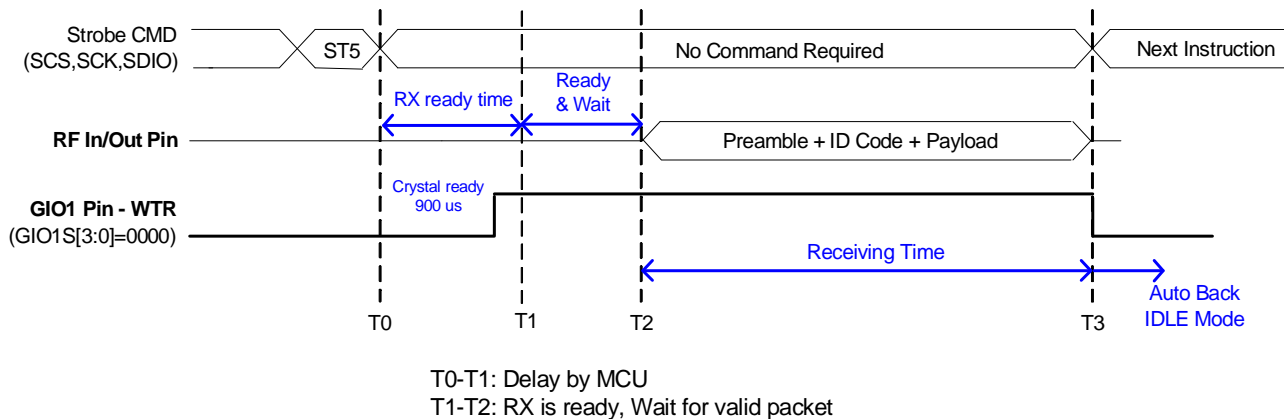
From Figure 11.7, when ST5 command is issued for TX operation, see Figure 11.8 for detailed timing. A7106 status can be represented to GIO1 or GIO2 pin to MCU for timing control.



LO Freq.	IDLE to WPLL	WPLL to TX	TX Ready Time
Changed	970 us	60 us	1030 us
No Changed	970 us	60 us	1030 us

Figure 11.8 Transmitting Timing Chart of Power Saving FIFO Mode

From Figure 11.7, when ST5 command is issued for RX operation, see Figure 11.9 for detailed timing. A7106 status can be represented to GIO1 or GIO2 pin to MCU for timing control.



LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	IDLE to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed / Fixed	<=125K	By preamble (01b)	970 us	40 us	1010 us
Changed / Fixed	250K	By ID (10b)	970 us	100 us	1080 us
Changed / Fixed	500K	By ID (10b)	970 us	60 us	1030 us

Figure 11.9 Receiving Timing Chart of Power Saving FIFO Mode



A7106

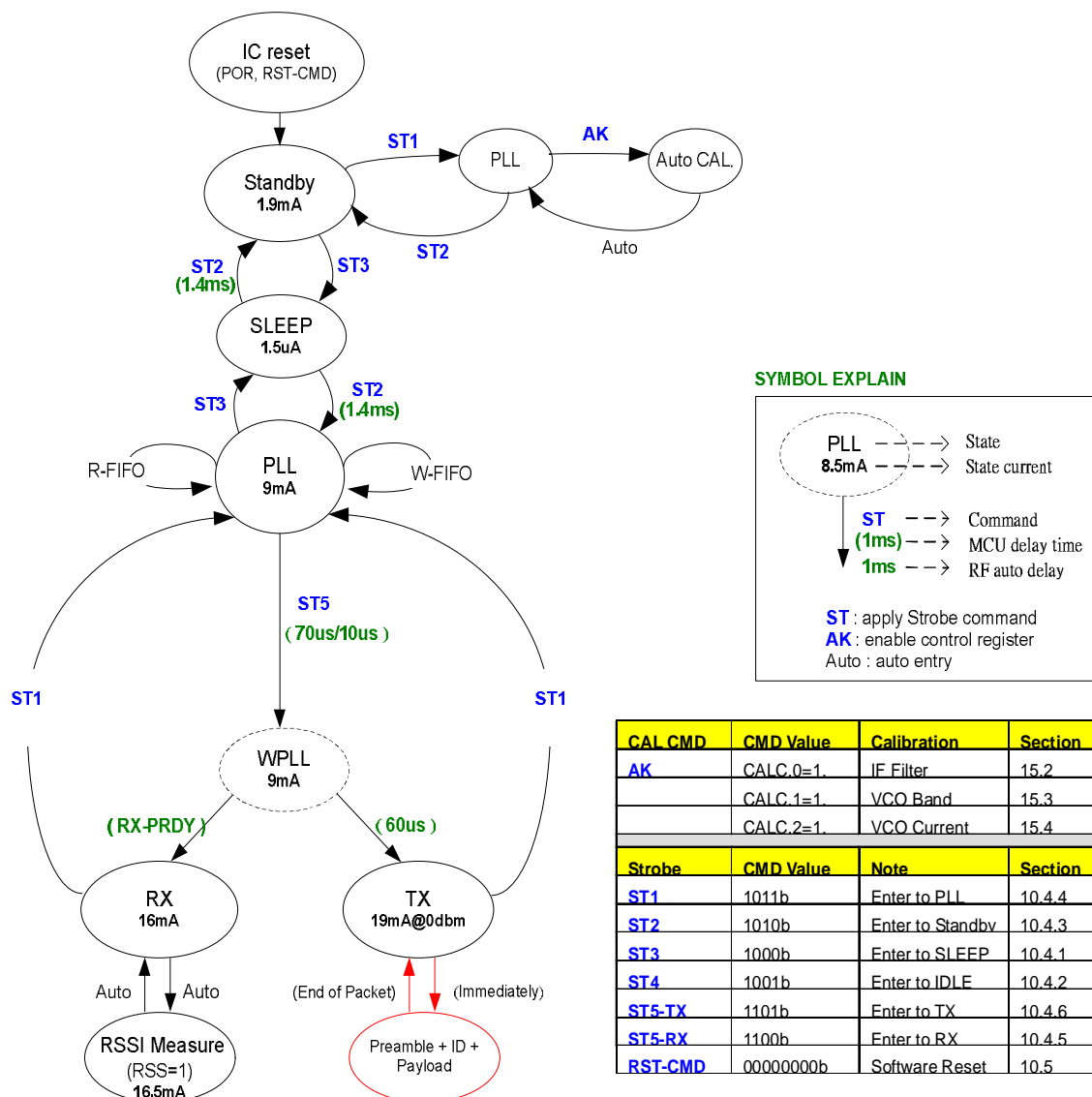
Preliminary

2.4G FSK/GFSK Transceiver

11.5 Quick Direct Mode

This mode is suitable for fast transceiving. After calibration flow, for every state transition, user has to issue Strobe command to A7106. This mode is also suitable for the requirement of versatile packet format. Noted that user needs to take care the transition time by MCU's timer.

When packets are finished and deeper power saving is necessary, user can issue Strobe command to ask A7106 staying in idle mode (or sleep mode). Figure 11.3 is the state diagram of Quick Direct mode.



- See Table 11.12 (next page) for RX-PRDY..
- From PLL to WPLL, it is either 70 us (LO frequency changed) or 10 us (LO frequency NOT changed)

Figure 11.10 State diagram of Quick Direct Mode



A7106

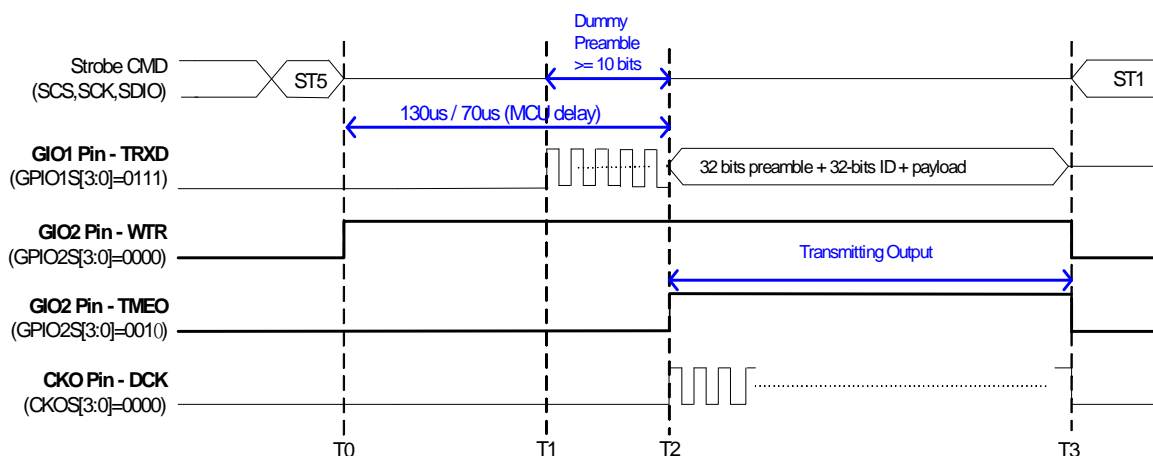
Preliminary

2.4G FSK/GFSK Transceiver

From Figure 11.10, After A7106 enters TX mode, MCU should immediately deliver preamble. Therefore, user can send dummy preamble since WTR goes high or plus a delay loop to make sure dummy preamble is 10 bits at least before DCK is active. See below figure for detail timing.

A7106 Data Rate	Dummy Preamble	Packet			Note
		Preamble	ID (06h)	Max Payload	
2K~500Kbps	≥ 10 bits	32 bits	32 bits	512 bytes	Total Preamble = 42 bits

Table 11.2 Format of dummy preamble and packet.



T0-T1: MCU delay loop
T1-T2: Dummy Preamble.
T2: TMEO (TX Modulation Enable) is auto triggered
T2-T3: Transmitting Time

LO Freq.	PLL to WPLL	WPLL to TX	TX Ready Time
Changed	70 us	60 us	130 us
No Changed	10 us	60 us	70 us

Figure 11.11 Transmitting Timing Chart of Quick Direct Mode

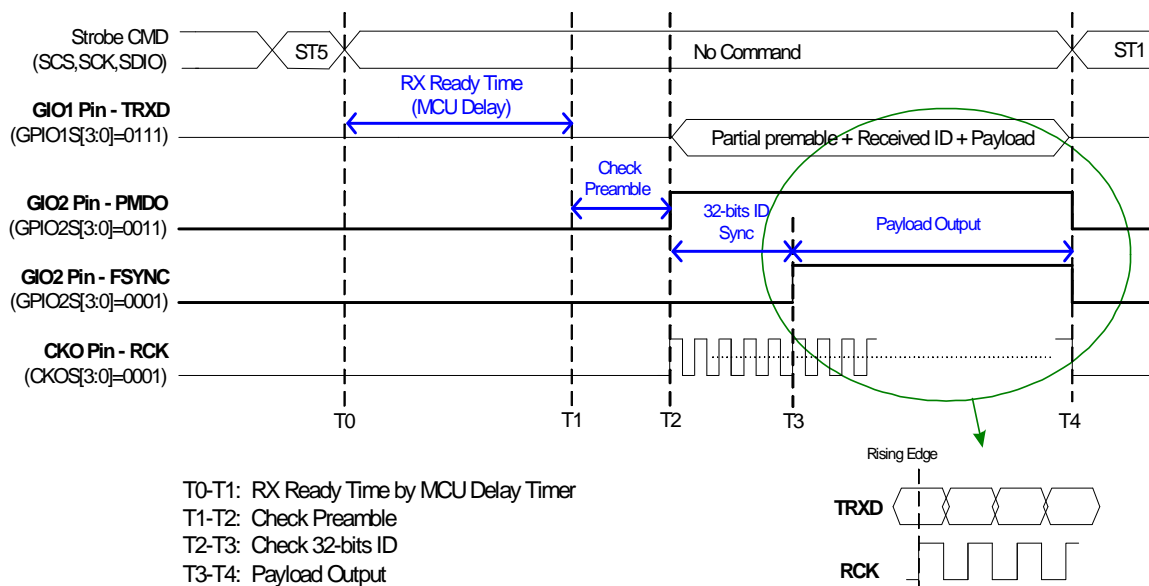
From Figure 11.10, in RX mode, A7106 will check received ID compared to ID register (06h). If ID is matched, FSYNC will be output. MCU can decode received ID and payload from GIO1 pin (TRXD) via rising edge of RCK (recovery clock). Then, GIO2 pin can be used to inform MCU reference timing by PMDO (Preamble Detect Output) or FSYNC (Frame Sync).



A7106

Preliminary

2.4G FSK/GFSK Transceiver



LO Freq.	Date Rate (bps)	DCM[1:0] (29h)	PLL to WPLL	WPLL to RX (RX-PRDY)	RX Ready Time (Delay by MCU)
Changed	<=125K	By preamble (01b)	70 us	40 us	110 us
Changed	250K	By ID (10b)	70 us	100 us	170 us
Changed	500K	By ID (10b)	70 us	60 us	130 us
No Changed	<=125K	By preamble (01b)	10 us	40 us	50 us
No Changed	250K	By ID (10b)	10 us	100 us	110 us
No Changed	500K	By ID (10b)	10 us	60 us	70 us

Figure 11.12 Receiving Timing Chart of Quick Direct Mode



A7106

Preliminary

2.4G FSK/GFSK Transceiver

12 Crystal Oscillator

A7106 needs external crystal or external clock that is either 6 or 8/12/16/20/24 MHz to generate internal wanted clock. Be noted if external clock is equal or lower than 8MHz, A7106 only supports data rate up to 250K.

Relative Control Register

Clock Register (Address: 0Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
Reset		1	1	1	1	0	1	0	1

12.1 Use External Crystal

Figure 12.1 shows the connection of crystal network between XI and XO pins. C1 and C2 capacitance are used to adjust different crystal loading. A7106 supports crystal accuracy within ± 20 ppm under firmware frequency compensation. Be noted that crystal accuracy requirement includes initial tolerance, temperature drift, aging and crystal loading.

A7106	Crystal Accuracy	Crystal ESR
Firmware FC = On	± 20 ppm	≤ 80 ohm
Firmware FC = Off	± 10 ppm	≤ 80 ohm

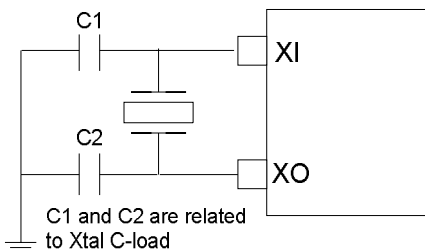


Fig12.1 Crystal oscillator circuit, refer to A7106 App. Note for C1 and C2.

12.2 Use external clock

A7106 has built-in AC couple capacitor to support external clock input. Figure 11.2 shows how to connect. In such case, XI pin is left opened. XS shall be low (0Dh) for selecting external clock. The frequency accuracy of external clock shall be controlled within ± 20 ppm, and the amplitude of external clock shall be within 1.2 ~ 1.8 V peak-to-peak.

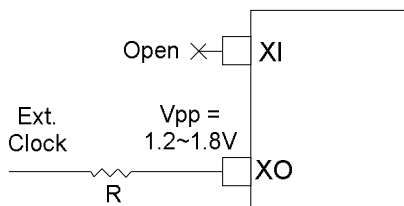


Fig12.2 External clock source. R is used to tune $V_{pp} = 1.2 \sim 1.8V$



A7106

Preliminary

2.4G FSK/GFSK Transceiver

13. System Clock

A7106 supports different crystal frequency by programmable "Clock Register" (0Dh). Based on this, three important internal clocks F_{CGR} , F_{DR} and F_{SYCK} are generated.

- (1) F_{XTAL} : Crystal frequency.
- (2) F_{XREF} : Crystal Ref. Clock = $F_{XREF} * (DBL+1)$.
- (3) F_{CGR} : Clock Generation Reference = $2\text{MHz} = F_{XREF} / (GRC+1)$, where F_{CGR} is used to generate 32M PLL.
- (4) F_{MCLK} : Master Clock is either F_{XREF} or 32M PLL, where F_{MCLK} is used to generate F_{SYCK} .
- (5) F_{SYCK} : System Clock = $16\text{MHz} = F_{MCLK} / CSC = 32 * F_{IF}$, where F_{IF} is recommended to set 500KHz.
- (6) F_{DR} : Data Rate Clock = $F_{IF} / (SDR+1)$.
- (7) F_{PPD} : VCO Compared Clock = $F_{XREF} / (RRC+1)$.

Relative Control Register

Clock Register (Address: 0Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Clock	R/W	GRC3	GRC2	GRC1	GRC0	CSC1	CSC0	CGS	XS
Reset		1	1	1	1	0	1	0	1

Data Rate Register (Address: 0Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Data Rate	R/W	SDR7	SDR6	SDR5	SDR4	SDR3	SDR2	SDR1	SDR0
Reset		0	0	0	0	0	0	0	0

PLL Register II (Address: 10h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL II	W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	BIP8
	R	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
Reset		1	0	0	1	1	1	1	0

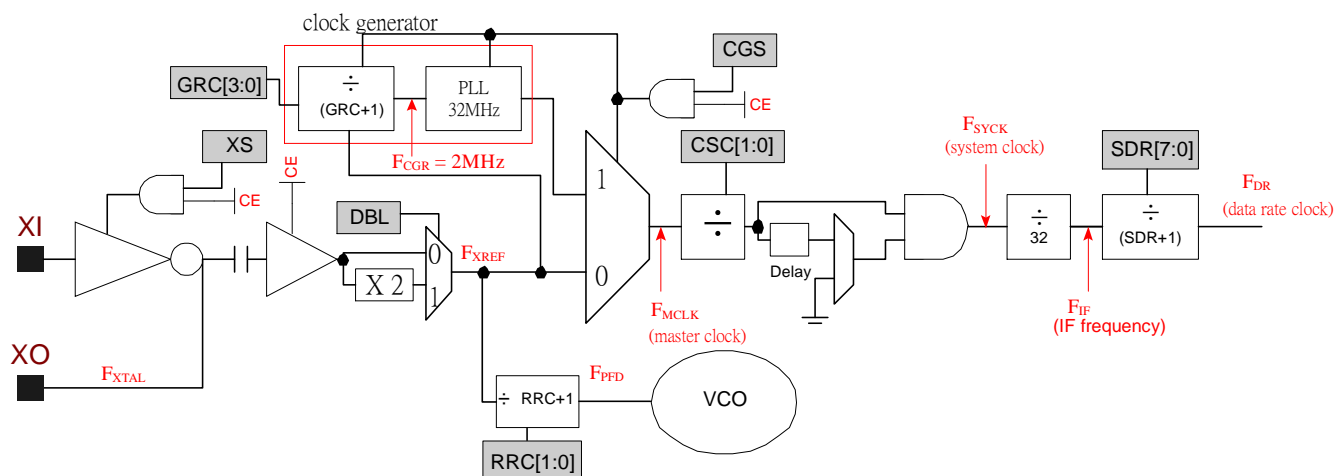


Fig13.1 System clock block diagram



A7106

Preliminary

2.4G FSK/GFSK Transceiver

As show in Fig 13.1, F_{MCLK} , the master clock either come from F_{XREF} ($CGS = 0$) or PLL 32MHz ($CGS = 1$). The relation between F_{SYCK} (the system clock) and F_{MCLK} (master clock) show in table 13.1

F_{SYCK} (Master Clock)		
	$CGS = 0$	$CGS = 1$
$DBL=0$	F_{XTAL}	32 MHz
$DBL=1$	$2 * F_{XTAL}$	32 MHz
	(Recommend)	

$CSC [1:0]$	F_{SYCK} (system clock)	Note
00	F_{MCLK}	F_{SYCK} is used to determine 1. Data rate clock (0Eh) 2. ADC clock (1Eh) 3. Internal digital clock (09h) 4. CKO pin (0Ah)
01	$F_{MCLK} / 2$	
10	$F_{MCLK} / 2$	
11	$F_{MCLK} / 4$	

Table 13.1 System clock and master clock

13.1 Bypass clock generation

If crystal frequency is multiplier of 8MHz, the clock generator block can be turned off by setting $CGS = 0$. The relation between F_{XTAL} (crystal frequency) and data rate show below:

$$F_{XREF} = F_{XTAL} * (DBL+1)$$

$$F_{PFD} = F_{XREF} / (RRC [1:0]+1)$$

$$F_{DR} = F_{XREF} / (CSC [1:0]+1) / 32 / (SDR+1)$$

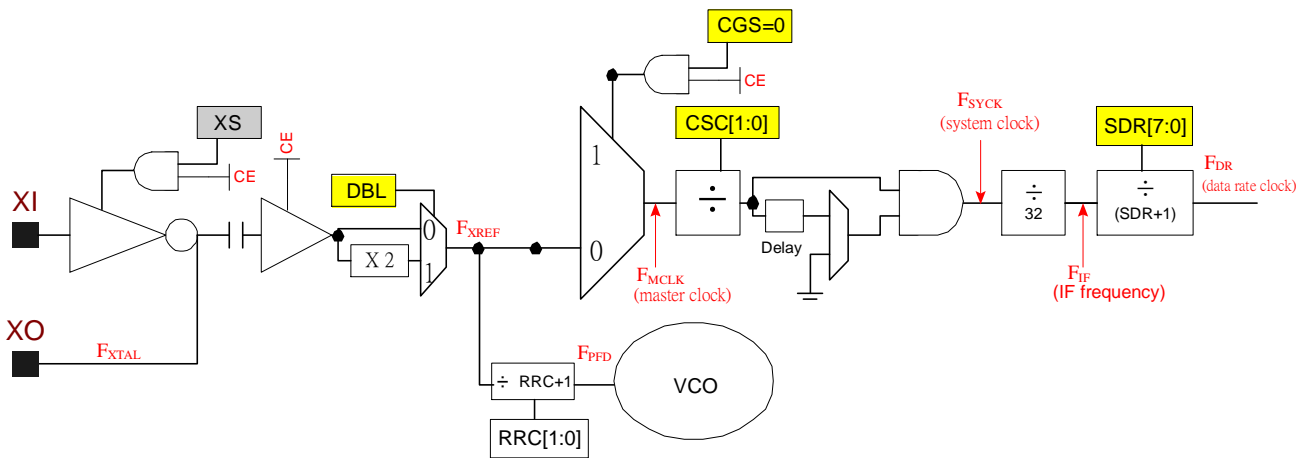


Fig13.2 By pass clock generator to get system clock

For various data rate application, list some examples below.
 For more data rate options, please contact AMICCOM FAE team.

Data rate 500Kbps

Crystal source	CGS (0Dh)	DBL (10h)	$CSC [1:0]$ (0Dh)	$GRC [3:0]$ (0Dh)	F_{IF} (KHz)	BWS (18h)	$RRC [1:0]$ (10h)	F_{PFD} (MHz)	$CHR [3:0]$ (10h)	F_{CHSP} (MHz)	$SDR [7:0]$
16MHz	0	1	01	Don't care	500	1	00	32	1111	0.5	0x00



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Data rate = 250K / 125K / 100K / 50K / 25K / 10K / 2Kbps

Crystal source	CGS (0Dh)	DBL (10h)	CSC[1:0] (0Dh)	GRC [3:0] (0Dh)	F _{IF} (KHz)	BWS (18h)	RRC [1:0] (10h)	F _{PFD} (MHz)	CHR [3:0] (10h)	F _{CHSP} (MHz)	SDR [7:0]
8MHz	0	1	01	Don't care	500	1	00	16	0111	0.5	See next table
16MHz								32	1111		

SDR Table

	250Kbps	125Kbps	100Kbps	50Kbps	25Kbps	10Kbps	2Kbps
SDR [7:0]	0x01	0x03	0x04	0x09	0x13	0x31	0xF9

13.2 Enable clock generation

If crystal frequency is the multiplier of 2MHz and larger than 6MHz, set CGS = 1 to enable $F_{SYCK} = 32\text{MHz}$ (internal 32MHz PLL). The comparison frequency of clock generator F_{CGR} shall be 2MHz by setting GRC[3:0] to meets the below equations.

$$F_{CRG} = F_{XTAL} * (1+DBL) / (GRC+1) = 2\text{MHz.}$$

$$F_{DR} = F_{SYCK} / 32 / (SDR+1).$$

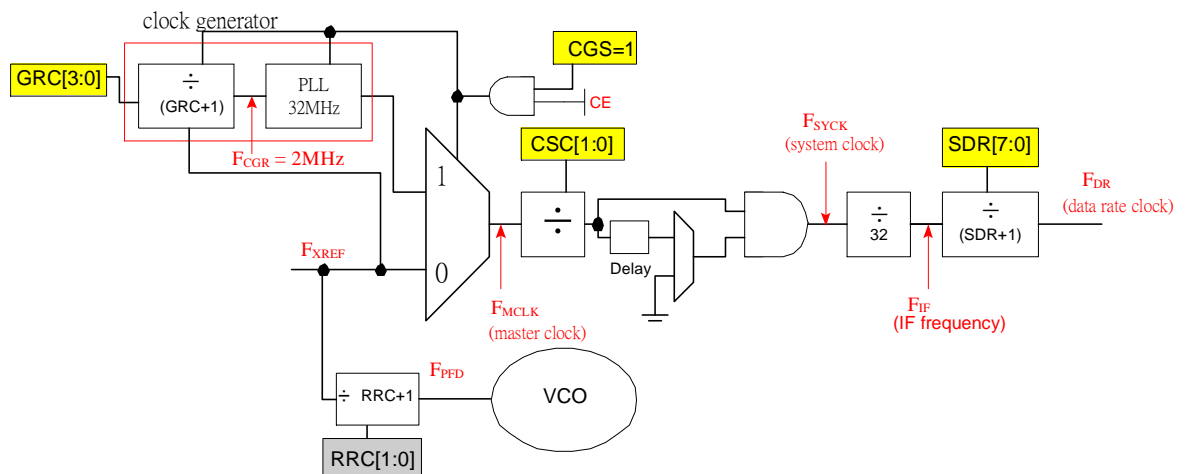


Fig13.3 Enable clock generator to get system clock

For various data rate application, list some examples below.
For more data rate options, please contact AMICCOM FAE team.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Data rate 500Kbps

Crystal source	CGS (0Dh)	DBL (10h)	CSC[1:0] (0Dh)	GRC [3:0] (0Dh)	F _{IF} (KHz)	BWS (18h)	RRC [1:0] (10h)	F _{PFD} (MHz)	CHR [3:0] (10h)	F _{CHSP} (MHz)	SDR [7:0]
12MHz	1	1	01	1011	500	1	00	24	1011	0.5	0x00
16MHz		1		1111				32	1111		
24MHz		0		1011				24	1011		

Data rate = 250K / 125K / 100K / 50K / 25K / 10K / 2Kbps

Crystal source	CGS (0Dh)	DBL (10h)	CSC[1:0] (0Dh)	GRC [3:0] (0Dh)	F _{IF} (KHz)	BWS (18h)	RRC [1:0] (10h)	F _{PFD} (MHz)	CHR [3:0] (10h)	F _{CHSP} (MHz)	SDR [7:0]
6MHz	1	1	01	0101	500	1	00	12	0101	0.5	See next table
8MHz		1		0111				16	0111		
12MHz		1		1011				24	1011		
16MHz		1		1111				32	1111		
24MHz		0		1011				24	1011		

SDR Table

	250Kbps	125Kbps	100Kbps	50Kbps	25Kbps	10Kbps	2Kbps
SDR [7:0]	0x01	0x03	0x04	0x09	0x13	0x31	0xF9



A7106

Preliminary

2.4G FSK/GFSK Transceiver

14. Transceiver LO Frequency

A7106 is a half-duplex transceiver with embedded PA and LNA. For TX or RX frequency setting, user just needs to set up LO (Local Oscillator) frequency for two ways radio transmission.

To target full range of 2.4GHz ISM band (2400 MHz to 2483.5 MHz), A7106 applies offset concept by LO frequency $F_{LO} = F_{LO_BASE} + F_{OFFSET}$. Therefore, this device is easy to implement frequency hopping and multi-channels by just **ONE** register setting, **PLL Register I (CHN [7:0], 0Eh)**.

Below is the LO frequency block diagram.

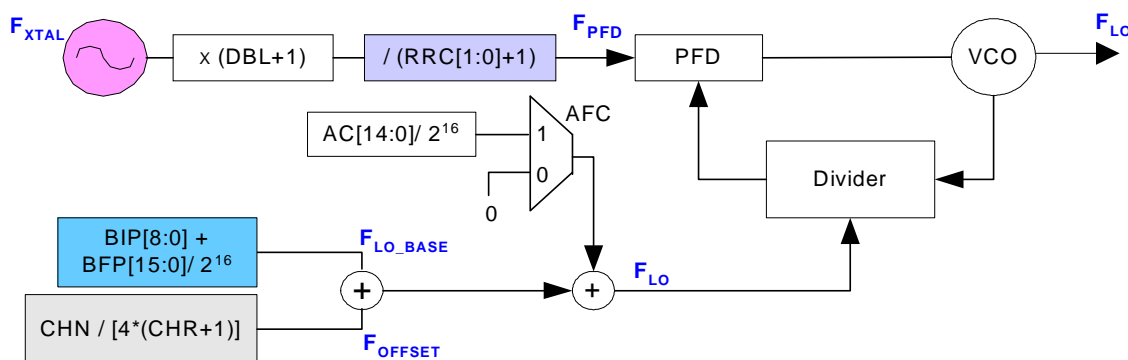


Fig14.1 Frequency synthesizer block diagram

Relative Control Register

PLL Register I (Address: 0Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL I	R/W	CHN7	CHN6	CHN5	CHN4	CHN3	CHN2	CHN1	CHN0
Reset		0	0	0	0	0	0	0	0

PLL Register II (Address: 10h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL II	W	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	BIP8
	R	DBL	RRC1	RRC0	CHR3	CHR2	CHR1	CHR0	IP8
Reset		1	0	0	1	1	1	1	0

PLL Register III (Address: 11h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL III	W	BIP7	BIP6	BIP5	BIP4	BIP3	BIP2	BIP1	BIP0
	R	IP7	IP6	IP5	IP4	IP3	IP2	IP1	IP0
Reset		0	1	0	0	1	0	1	1

PLL Register IV (Address: 12h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL IV	W	BFP15	BFP14	BFP13	BFP12	BFP11	BFP10	BFP9	BFP8
	R	--/FP15	AC14/FP14	AC13/FP13	AC12/FP12	AC11/FP11	AC10/FP10	AC9/FP9	AC8/FP8
Reset		0	0	0	0	0	0	0	0



A7106

Preliminary

2.4G FSK/GFSK Transceiver

PLL Register V (Address: 13h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PLL V	W	BFP7	BFP6	BFP5	BFP4	BFP3	BFP2	BFP1	BFP0
	R	AC7/FP7	AC6/FP6	AC5/FP5	AC4/FP4	AC3/FP3	AC2/FP2	AC1/FP1	AC0/FP0
Reset		0	0	0	0	0	0	1	1

RX Register (Address: 18h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RX	W	--	RXSM1	RXSM0	FC	RXDI	DMG	BWS	ULS
Reset		--	1	0	0	0	0	1	0

Mode Control Register (Address: 01h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control I	W	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS
	R	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS
Reset		0	0	0	0	0	0	0	0

14.1 LO Frequency Setting

From Figure 14.1, F_{LO} is not only for TX radio frequency but also to be RX LO frequency. To set up F_{LO} , it is easy to implement by below 4 steps.

- Set the base frequency (F_{LO_BASE}) by PLL Register II, III, IV and V (10h, 11h, 12h and 13h).
Recommend to set $F_{LO_BASE} \sim 2400.001\text{MHz}$.
- Set the channel step (F_{CHSP}) by PLL Register II (0Fh).
 $F_{CHSP} = F_{XTAL} * (DBL+1) / 4 / (CHR+1)$, Recommend $F_{CHSP} = 500\text{ KHz}$.
- Set CHN [7:0] to get offset frequency by PLL Register I (0Fh).
 $F_{OFFSET} = CHN [7:0] \times F_{CHSP}$
- LO frequency is equal to base frequency plus offset frequency.
 $F_{LO} = F_{LO_BASE} + F_{OFFSET}$



F_{LO_BASE}

$$F_{LO_BASE} = F_{PFD} \cdot (BIP[8:0] + \frac{BFP[15:0]}{2^{16}}) = (DBL + 1) \cdot \frac{F_{XTAL}}{RRC[1:0] + 1} \cdot (BIP[8:0] + \frac{BFP[15:0]}{2^{16}})$$

Base on the above formula, for example, if $F_{XTAL} = 16\text{ MHz}$ and set channel step $F_{CHSP} = 500\text{ KHz}$, to get F_{LO_BASE} and F_{LO} , see Table 14.1, 14.2, and Figure 14.2 for details.

STEP	ITEMS	VALUE	NOTE
1	F_{XTAL}	16 MHz	Crystal Frequency
2	DBL	1	Enable double function
3	RRC	0	If so, $F_{PFD} = 32\text{MHz}$



A7106

Preliminary

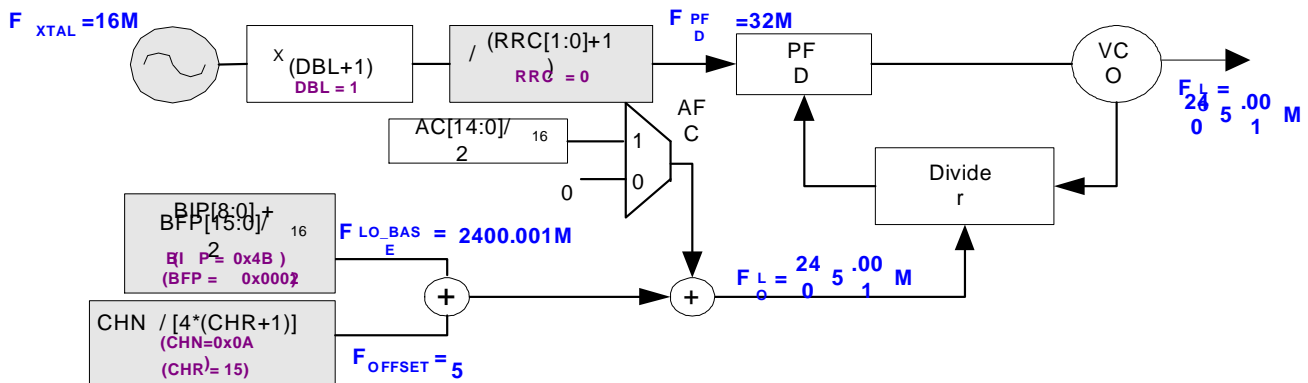
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4	BIP	0x4B	To get $F_{LO_BASE} = 2400$ MHz
5	BFP	0x0002	To get $F_{LO_BASE} \sim 2400.001$ MHz
6	F_{LO_BASE}	~ 2400.001 MHz	LO Base frequency

Table 14.1 How to set F_{LO_BASE}

How to set $F_{TXRF} = F_{LO} = F_{LO_BASE} + F_{OFFSET} \sim 2405.001$ MHz

STEP	ITEMS	VALUE	NOTE
1	F_{LO_BASE}	~ 2400.001 MHz	After set up BIP and BFP
2	CHR	0x0F	To get $F_{CHSP} = 500$ KHz
3	F_{CHSP}	500 KHz	Channel step = 500KHz
4	CHN	0x0A	Set channel number = 10
5	F_{OFFSET}	5 MHz	$F_{OFFSET} = 500 \text{ KHz} * (\text{CHN}) = 5\text{MHz}$
6	F_{LO}	~ 2405.001 MHz	Get $F_{LO} = F_{LO_BASE} + F_{OFFSET}$
7	F_{TXRF}	~ 2405.001 MHz	$F_{TXRF} = F_{LO}$

Table 14.2 How to set F_{TXRF} Figure 14.2 Block Diagram of set up $F_{LO} \sim 2405.001$ MHz

For different crystal frequency, 24MHz / 16MHz / 12 MHz / 8MHz / 6MHz, below are calculation details for F_{FPD} and F_{CHSP}

$$F_{FPD} = \frac{(DBL+1) \cdot f_{XTAL}}{RRC[1:0]+1}$$

F_{XTAL} (MHz)	DBL	RRC	F_{FPD} (MHz)	Note
24	0	0	24	
16	1	0	32	(reference design)
12	1	0	24	
8	1	0	16	
6	1	0	12	

$$F_{CHSP} = \frac{F_{FPD}}{4 \cdot (CHR[3:0]+1)}$$



A7106

Preliminary

2.4G FSK/GFSK Transceiver

F _{XTAL} (MHz)	F _{PFD} (MHz)	CHR [3:0]	F _{CHSP} (KHz)	CHN [7:0]	F _{OFFSET} (MHz)	F _{LO} (MHz)
24	24	1011	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
16	32	1111	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
12	24	1011	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
8	16	0111	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484
6	12	0101	500	0x00 ~ 0xA8	0 ~ 84	2400 ~ 2484

14.2 IF Side Band Select

In two ways radio, both master and slave have two roles, TX and RX. In general, slave usually has to reply an ACK-packet or status update. In such case, A7106 offers two methods to set up F_{LO} while TRX exchanging.

- (1) Auto IF exchange
- (2) Fast exchange

Relative Control Register

Mode Control Register (Address: 01h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
Reset		0	0	0	0	0	0	0	0

RX Register (Address: 18h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	--	RXSM1	RXSM0	FC	RXDI	DMG	BWS	ULS
Reset		--	1	0	0	0	0	1	0

Register Setting	AIF Function	F _{RXLO} Formula
ULS=0	Disable (AIF=0)	F _{RXLO} = F _{LO}
ULS=1		F _{RXLO} = F _{LO}
ULS=0	Enable (AIF=1)	F _{RXLO} = F _{LO} - 500KHz
ULS=1		F _{RXLO} = F _{LO} + 500Kz

Table 14.3 F_{RXLO} Formula



A7106

Preliminary

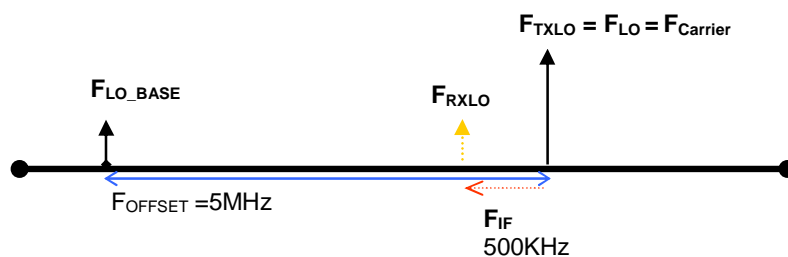
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14.2.1 Auto IF Exchange

A7106 supports Auto IF offset function (AIF, 01h). If AIF is enabled, only one on-air occupied frequency (F_{carrier}). In this case, user has no need to change F_{RXLO} while TRX exchanging because F_{RXLO} is auto shifted F_{IF} . See below Figures and Table 14.4 for details.

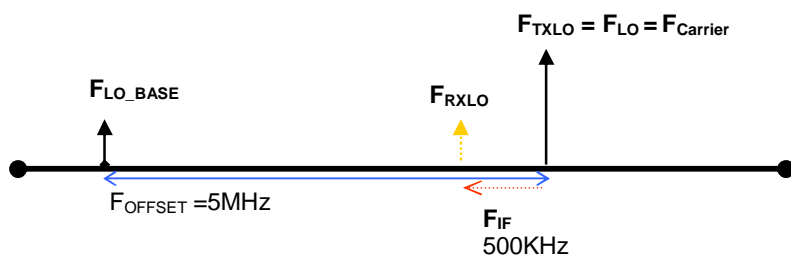
<Master>

AIF=1 and ULS=0, F_{RXLO} is auto shifted lower than F_{TXLO} for 500KHz (F_{IF}).



<Slave>

AIF=1 and ULS=0, F_{RXLO} is auto shifted lower than F_{TXLO} for 500KHz (F_{IF}).



Item	Role	AIF	ULS	CHN[7:0]	F_{CHSP} (KHz)	F_{TXLO} (KHz)	F_{RXLO} (MHz)	NOTE
Master	TX	1	0	10	500	2405.001	-	
	RX	1	0	10	500	-	2404.501	Up side band F_{RXLO} is auto shifted
Slave	TX	1	0	10	500	2405.001	-	
	RX	1	0	10	500	-	2404.501	Up side band F_{RXLO} is auto shifted

Table 14.4 AIF function while TRX exchanging



A7106

Preliminary

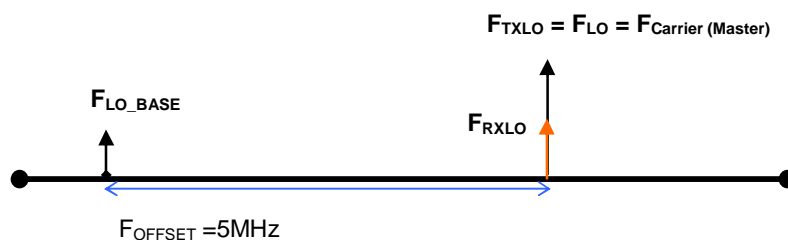
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14.2.2 Fast Exchange

To reduce PLL settling time, user can disable AIF function. If AIF is disabled, two On-air frequency ($F_{\text{Carrier (master)}}$, $F_{\text{Carrier (slave)}}$) are occupied. In this case, user has to control $ULS = 0$ (Master side) and $ULS = 1$ (Slave side) for fast exchange in two-way radio. See below Figures and Table 14.5 for details.

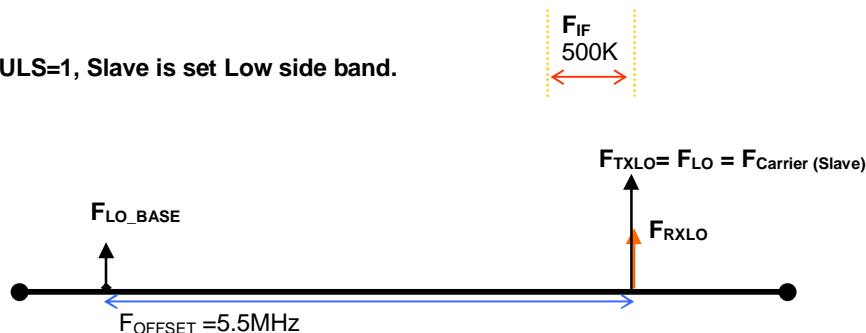
<Master>

AIF=0 and ULS=0, Master is set Up side band.



<Slave>

AIF=0 and ULS=1, Slave is set Low side band.



Item	Role	AIF	ULS	CHN[7:0]	F _{CHSP} (KHz)	F _{TXLO} (KHz)	F _{RXLO} (MHz)	NOTE
Master	TX	0	0	10	500	2405.001	-	
	RX	0	0	10	500	-	2405.001	Up side band
Slave	TX	0	1	14	500	2405.501	-	
	RX	0	1	14	500	-	2405.501	Low side band

Table 14.5 Fast exchange function while TRX exchanging



A7106

Preliminary

2.4G FSK/GFSK Transceiver

14.3 Frequency Compensation

Frequency Compensation function (FC) supports low accuracy crystal (± 20 ppm) without sensitivity degradation. The FC concept is to fine tune RX LO frequency (F_{RXLO}). MCU can read AC[14:0], (12h) and (13h), to executes frequency drift calculation and update new setting to PLL IV (12h) and PLL V (13h) to adjust the best RX LO frequency (F_{RXLO}).

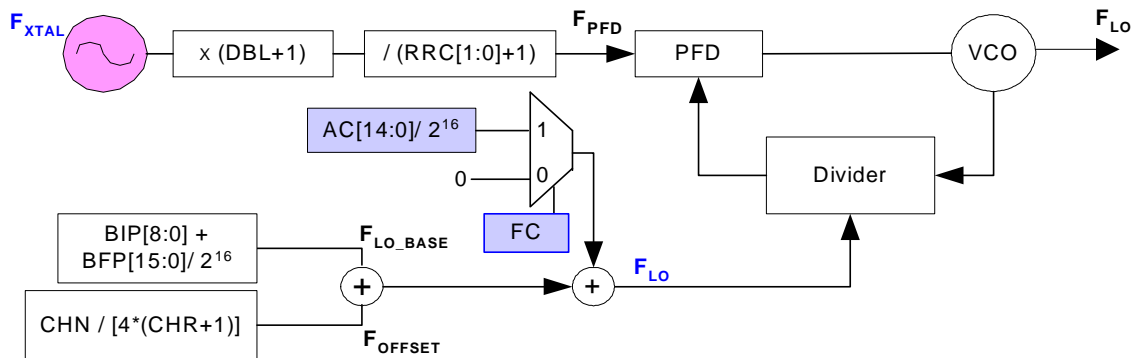


Figure 14.3 Block Diagram of enabling FC function

Relative Control Register

RX Register (Address: 19h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	--	RXSM1	RXSM0	FC	RXDI	DMG	RAW	ULS
Reset		--	1	0	0	0	0	1	0

PLL Register IV (Address: 12h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	--/FP15	AC14/FP14	AC13/FP13	AC12/FP12	AC11/FP11	AC10/FP10	AC9/FP9	AC8/FP8
	W	BFP15	BFP14	BFP13	BFP12	BFP11	BFP10	BFP9	BFP8
Reset		0	0	0	0	0	0	0	0

PLL Register V (Address: 13h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	AC7/FP7	AC6/FP6	AC5/FP5	AC4/FP4	AC3/FP3	AC2/FP2	AC1/FP1	AC0/FP0
	W	BFP7	BFP6	BFP5	BFP4	BFP3	BFP2	BFP1	BFP0
Reset		0	0	0	0	0	1	0	0

For Frequency Compensation procedure, please refer to AMICCOM's reference code and contact AMICCOM FAE team for details.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

15. Calibration

A7106 needs calibration process after power on reset or software reset by 3 calibration items, they are, VCO Current, VCO Bank, and IF Filter Bank.

1. VCO Current Calibration (Standby or PLL mode) is used to find adequate VCO current.
2. VCO Bank Calibration (PLL mode) is used to select best VCO frequency bank for the calibrated frequency.
3. IF Filter Bank Calibration (Standby or PLL mode) is used to calibrate IF filter bandwidth and center frequency.
4. RSSI Calibration is to find the RSSI value corresponding to -70dBm RF input and RSSI curve.

15.1 Calibration Procedure

1. Initialize all control registers (refer to A7106 reference code).
2. Select calibration mode (set MFBS=0, MVCS=1, MVBS=0).
3. Set A7106 in PLL mode.
4. Enable IF Filter Bank (set FBC, RSSC=1), VCO Current (VCC=1), and VCO Bank (VBC=1).
5. After calibration done, FBC, VCC and VBC is auto clear.
6. Check pass or fail by reading calibration flag. (FBCF) and (VCCF, VBCF).

15.2 IF Filter Bank Calibration

Relative Control Register

Calibration Control Register (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control II	R/W	--	--	--	--	RSSC	VCC	VBC	FBC
Reset		--	--	--	--	0	0	0	0

IF Calibration Register I (Address: 22h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IF Calibration I	R				FBCF	FB3	FB2	FB1	FB0
	W	--	--	--	MFBS	MFB3	MFB2	MFB1	MFB0
Reset		--	--	--	0	0	1	1	0

1. Initialize all control registers (refer to A7106 reference code).
2. Set MFBS = 0 for auto calibration.
3. Set A7106 in PLL mode.
4. Set FBC= 1 (02h).
5. The maximum calibration time for this calibration is about 256us.
6. FBC is auto clear after calibration done.
7. User can read calibration flag (FBCF, 22h) to check pass or fail.
8. User can read FB [3:0] (22h) to get the auto calibration value.

15.3 VCO Current Calibration

Relative Control Register

Calibration Control Register (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
------	-----	-------	-------	-------	-------	-------	-------	-------	-------



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Mode Control II	R/W	--	--	--	--	RSSC	VCC	VBC	FBC
Reset		--	--	--	--	0	0	0	0

VCO current Calibration Register (Address: 24h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO current Calibration	R				FVCC	VCB3	VCB2	VCB1	VCB0
	W	--	--	VCCS	MVCS	VCOC3	VCOC2	VCOC1	VCOC0
Reset		--	--	0	0	1	0	0	0

1. Initialize all control registers (refer to A7106 reference code).
2. Set MVCS= 1 for manual calibration.
3. Set VCOC[3:0] = [0011] (24h).

15.4 VCO Bank Calibration

Relative Control Register

Calibration Control Register (Address: 02h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode Control II	R/W	--	--	--	--	RSSC	VCC	VBC	FBC
Reset		--	--	--	--	0	0	0	0

VCO Single band Calibration Register I (Address: 25h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band Calibration I	R	--	--	DVT1	DVT0	VBCF	VB2	VB1	VB0
	W	--	--	--	--	MVBS	MVB2	MVB1	MVB0
Reset		--	--	--	--	0	1	0	0

VCO Single band Calibration Register II (Address: 26h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCO Single band Calibration II	W	--	--	VTH2	VTH1	VTH0	VTL2	VTL1	VTL0
Reset		--	--	1	1	1	0	1	1

1. Initialize all control registers (refer to A7106 reference code).
2. Set MVBS= 0 for auto calibration.
3. Set A7106 in PLL mode.
4. Set VBC= 1 (02h). Set VCO tuning upper threshold voltage VH and lower threshold voltage VL. The recommended voltage is VTH[2:0] = [111], VTL[2:0] = [011].
5. The maximum calibration time for VCO Bank Calibration is about 240 us (4 * PLL settling time).
6. VBC is auto clear after calibration done.
7. User can read calibration flag (VBCF, 25h) to check pass or fail.
8. User can read VB[2:0] (25h) to get the auto calibration value.

15.5 RSSI Calibration

1. Initialize all control registers (refer A7125 reference code).
Set A7125 in PLL mode.
2. Set RSSC= 1 (02h).
3. RSSC is auto clear after calibration done.
4. No need to check calibration flag.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

16. FIFO (First In First Out)

A7106 supports separated 64-bytes TX and RX FIFO by enabling FMS =1 (01h). For FIFO accessing, TX FIFO (write-only) and RX FIFO (read-only) share the same register address 05h. TX FIFO represents transmitted payload. On the other hand, once RX circuitry synchronizes ID Code, received payload is stored into RX FIFO.

In chapter 10 and 11, user can also find listed FIFO information below.

- (1) Figure 10.15 and 10.16 for FIFO accessing via 3-wire SPI.
- (2) Section 10.4.7 and 10.4.8 for FIFO pointer reset command.
- (3) Figure 11.2 and Figure 11.3 for Normal/Quick FIFO mode.

16.1 Packet Format

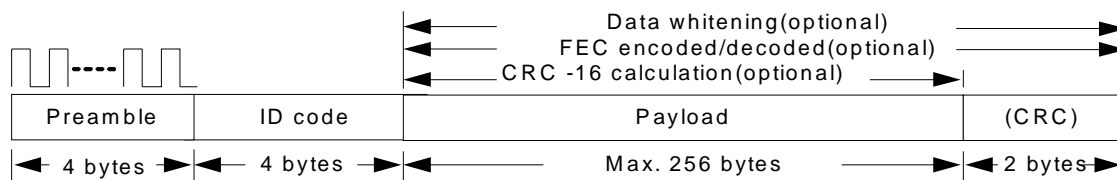


Figure 16.1 Packet Format of FIFO mode

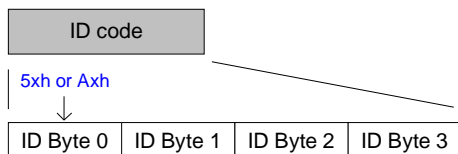


Figure 16.2 ID Code Format

Preamble:

The packet is led by preamble composed of alternate 0 and 1. If the first bit of ID code is 0, preamble shall be 0101...0101. In the contrast, if the first bit of ID code is 1, preamble shall be 1010...1010. Preamble length is recommended to set 4 bytes by PML [1:0] (1Fh).

ID code:

ID code is recommended to set 4 bytes by IDL=1 (1Fh). ID Code is sequenced by Byte 0, 1, 2 and 3 (Recommend to set ID Byte 0 = 5xh or Axh). If RX circuitry checks the ID code correct, received payload will be stored into RX FIFO. In special case, ID code could be set error tolerance (0~ 3bit error) by ETH [1:0] (20h) for ID synchronization check.

Payload:

Payload length is programmable by FEP [7:0] (03h) from 1 byte to 64 bytes. The physical FIFO depth is 64 bytes. A7106 also supports logical FIFO extension up to 256 bytes. See section 16.4.3 for details.

CRC (option):

In FIFO mode, if CRC is enabled (CRCS=1, 1Fh), 2-bytes of CRC value is transmitted automatically after payload. In the same way, RX circuitry will check CRC value and show the result to CRC Flag (00h).



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Relative Control Register

Mode Register (Address: 00h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Mode	R	--	FECF	CRCF	CER	XER	PLLER	TRSR	TRER
	W	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN	RESETN
Reset		--	--	--	--	--	--	--	--

FIFO Register I (Address: 03h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
Reset		0	0	1	1	1	1	1	1

Code Register I (Address: 1Fh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code I	W	--	MCS	WHTS	FECS	CRCS	IDL	PML1	PML0
Reset		--	0	0	0	0	1	1	1

Code Register II (Address: 20h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code II	W	--	DCL2	DCL1	DCL0	ETH1	ETH0	PMD1	PMD0
Reset		--	1	1	1	0	1	1	1

Code Register III (Address: 21h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Code III	W	--	WS6	WS5	WS4	WS3	WS2	WS1	WS0
Reset		--	0	1	0	1	0	1	0

16.2 Bit Stream Process

A7106 supports 3 optional bit stream process for payload, they are,

- (1) CCITT-16 CRC ($x^{16} + x^{15} + x^2 + 1$)
- (2) (7, 4) Hamming FEC
- (3) Data Whitening by XOR PN7 (7-bits Pseudo Random Sequence).

CRC (Cyclic Redundancy Check):

1. CRC is enabled by CRCS= 1 (1Fh). TX circuitry calculates the CRC value of payload (preamble, ID code excluded) and transmits 2-bytes CRC value after payload.
2. RX circuitry checks CRC value and shows the result to CRC Flag (00h). If CRCF=0, received payload is correct, else error occurred. (CRCF is read only, it is revised internally while receiving every packet.)

FEC (Forward Error Correction):

1. FEC is enabled by FECS= 1 (1Fh). Payload and CRC value (if CRCS=1) are encoded by (7, 4) Hamming code.
2. Each 4-bits (nibble) of payload is encoded into 7-bits code word as well as delivered out automatically.
(ex. 64 bytes payload will be encoded to 128 code words, each code word is 7 bits.)
3. RX circuitry decodes received code words automatically. FEC supports 1-bit error correction each code word. Once 1-bit error occurred, FEC flag=1 (00h). (FECF is read only, it is revised internally while receiving every packet.)

Data Whitening:

1. Data whitening is enabled by WHTS= 1 (1Fh). The initial seed of PN7 is WS [6:0] (22h). Payload is always encrypted by bit XOR operation with PN7. CRC and/or FEC are also encrypted if CRCS=1 and/or if FECS=1.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

- RX circuitry decrypts received payload and 2-bytes CRC (if CRCS=1) automatically. Be notice, user shall set the same WS [6:0] (21h) to TX and RX.

16.3 Transmission Time

Based on CRC and FEC options, the transmission time are different. See table 16.1 for details.

Data Rate = 500 Kbps

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 2 us = 1.152 ms
32	32	512	16 bits	Disable	592 bit X 2 us = 1.184 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 2 us = 1.920 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 2 us = 1.976 ms

Data Rate = 250 Kbps

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 4 us = 2.304 ms
32	32	512	16 bits	Disable	592 bit X 4 us = 2.368 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 4 us = 3.840 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 4 us = 3.952 ms

Data Rate = 125 Kbps

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 8 us = 4.608 ms
32	32	512	16 bits	Disable	592 bit X 8 us = 4.736 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 8 us = 7.580 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 8 us = 7.904 ms

Data Rate = 50 Kbps

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 20 us = 11.52 ms
32	32	512	16 bits	Disable	592 bit X 20 us = 11.84 ms
32	32	512	Disable	512 x 7 / 4	960 bit X 20 us = 19.20 ms
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 20 us = 19.76 ms

Data Rate = 2 Kbps

Preamble (bits)	ID Code (bits)	Payload (bits)	CRC (bits)	FEC	Transmission Time / Packet
32	32	512	Disable	Disable	576 bit X 0.5 ms = 0.288 s
32	32	512	16 bits	Disable	592 bit X 0.5 ms = 0.296 s
32	32	512	Disable	512 x 7 / 4	960 bit X 0.5 ms = 0.480 s
32	32	512	16 x 7 / 4	512 x 7 / 4	988 bit X 0.5 ms = 0.494 s

Table 16.1 Transmission time



A7106

Preliminary

2.4G FSK/GFSK Transceiver

16.4 Usage of TX and RX FIFO

In application points of view, A7106 supports 3 options of FIFO arrangement.

- (1) Easy FIFO
- (2) Segment FIFO
- (3) FIFO Extension

For FIFO operation, A7106 supports Strobe command to reset TX and RX FIFO pointer as shown below. User can refer to section 10.5 for FIFO write pointer reset and FIFO read pointer reset.

Strobe Command

Strobe Command								Description
A7	A6	A5	A4	A3	A2	A1	A0	
1	1	1	0	x	x	X	x	FIFO write pointer reset (for TX FIFO)
1	1	1	1	x	x	X	x	FIFO read pointer reset (for RX FIFO)

FIFO Register I (Address: 03h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	FEP7	FEP6	FEP5	FEP4	FEP3	FEP2	FEP1	FEP0
Reset		0	0	1	1	1	1	1	1

FIFO Register II (Address: 04h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	W	FPM1	FPM0	PSA5	PSA4	PSA3	PSA2	PSA1	PSA0
Reset		0	1	0	0	0	0	0	0

FIFO DATA Register (Address: 05h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R/W	FIFO7	FIFO6	FIFO5	FIFO4	FIFO3	FIFO2	FIFO1	FIFO0
Reset		0	0	0	0	0	0	0	0



A7106

Preliminary

2.4G FSK/GFSK Transceiver

16.4.1 Easy FIFO

In Easy FIFO, max FIFO length is 64 bytes. FIFO length is equal to **(FEP [7:0] + 1)**. User just needs to control FEP [7:0] (03h) and disable PSA and FPM as shown below.

Register setting

TX	RX	Control Registers		
FIFO Length (byte)	FIFO Length (byte)	FEP[7:0] (03h)	PSA [5:0] (04h)	FPM [1:0] (04h)
1	1	0x00	0	0
8	8	0x07	0	0
16	16	0x0F	0	0
32	32	0x1F	0	0
64	64	0x3F	0	0

Table 16.2 Control registers of Easy FIFO

Procedures of TX FIFO Transmitting

1. Initialize all control registers (refer to A7106 reference code).
2. Set FEP [7:0] = 0x3F for 64-bytes FIFO.
3. Refer to section 11.2 ~ 11.4.
4. Send Strobe command – TX FIFO write pointer reset.
5. MCU writes 64-bytes data to TX FIFO.
6. Send TX Strobe Command.
7. Done.

Procedures of RX FIFO Reading

1. When RX FIFO is full, WTR (or FSYNC) can be used to trigger MCU for RX FIFO reading.
2. Send Strobe command – RX FIFO read pointer reset.
3. MCU read 64-bytes from RX FIFO.
4. Done

Definitions

DP : Deliver Pointer
RP : Received Pointer

TX FIFO Empty = DP reaches FEP[7:0]
RX FIFO FULL = RP reaches FEP[7:0]

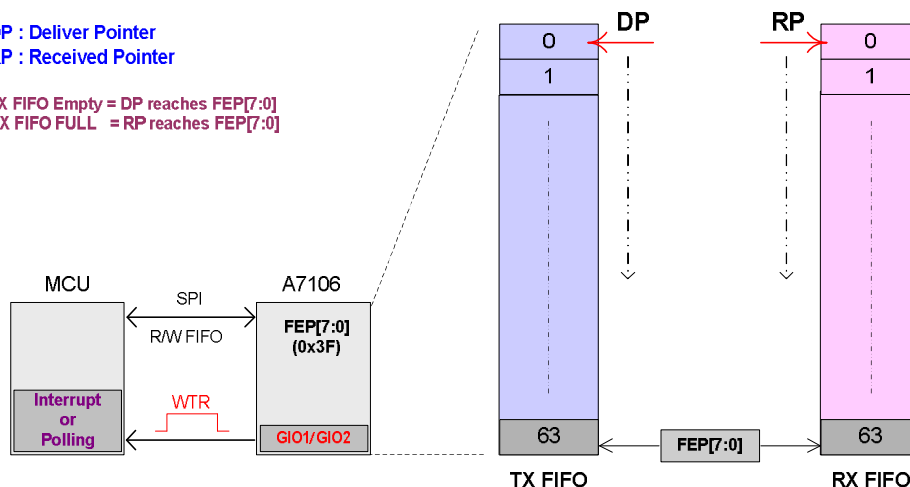


Figure 16.3 Easy FIFO



A7106

Preliminary

2.4G FSK/GFSK Transceiver

16.4.2 Segment FIFO

In Segment FIFO, TX FIFO length is equal to $(FEP [7:0] - PSA [5:0] + 1)$. FPM [1:0] should be zero. This function is very useful for button applications. In such case, each button is used to transmit fixed code (data) every time. During initialization, each fixed code is written into corresponding segment FIFO once and for all. Then, if button is triggered, MCU just assigns corresponding segment FIFO (PSA [5:0] and FEP [7:0]) and issues TX strobe command.

If TX FIFO is arranged into 8 segments, each TX segment and RX FIFO length are 8 bytes

TX				Control Registers		
Segment	PSA	FEP	FIFO Length (byte)	PSA[5:0] (04h)	FEP[7:0] (03h)	FPM[1:0] (04h)
1	PSA1	FEP1	8	0x00	0x07	0
2	PSA2	FEP2	8	0x08	0x0F	0
3	PSA3	FEP3	8	0x10	0x17	0
4	PSA4	FEP4	8	0x18	0x1F	0
5	PSA5	FEP5	8	0x20	0x27	0
6	PSA6	FEP6	8	0x28	0x2F	0
7	PSA7	FEP7	8	0x30	0x37	0
8	PSA8	FEP8	8	0x38	0x3F	0

RX	Control Registers		
FIFO Length (byte)	PSA [5:0] (04h)	FEP [7:0] (03h)	FPM[1:0] (04h)
8	0	0x07	0

Table 16.3 Segment FIFO is arranged into 8 segments

Procedures of TX FIFO Transmitting

1. Initialize all control registers (refer to A7106 reference code).
2. Refer to section 11.2 ~ 11.4.
3. Send Strobe command – TX FIFO write pointer reset.
4. MCU writes fixed code into corresponding segment FIFO once and for all.
5. To consign Segment 1, set PSA = 0x00 and FEP= 0x07
To consign Segment 2, set PSA = 0x08 and FEP= 0x0F
To consign Segment 3, set PSA = 0x10 and FEP= 0x17
To consign Segment 4, set PSA = 0x18 and FEP= 0x1F
To consign Segment 5, set PSA = 0x20 and FEP= 0x27
To consign Segment 6, set PSA = 0x28 and FEP= 0x2F
To consign Segment 7, set PSA = 0x30 and FEP= 0x37
To consign Segment 8, set PSA = 0x38 and FEP= 0x3F
6. Send TX Strobe Command.
7. Done.

Procedures of RX FIFO Reading

1. When RX FIFO is full, WTR (or FSYNC) is used to trigger MCU for RX FIFO reading.
2. Send Strobe command – RX FIFO read pointer reset.
3. MCU read 8-bytes from RX FIFO.
4. Done.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Definitions

DP : Deliver Pointer

RP : Received Pointer

TX FIFO Empty = DP reaches FEP[7:0]

RX FIFO FULL = RP reaches FEP[7:0]

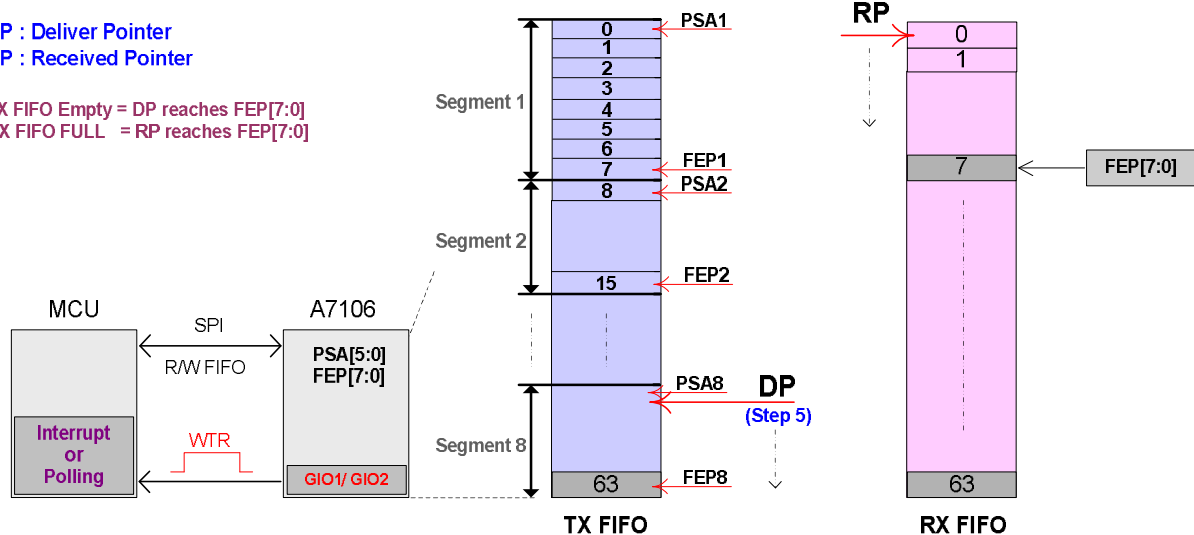


Figure 16.4 Segment FIFO Mode

16.4.3 FIFO Extension

In FIFO Extension, payload is programmable up to 256 bytes. In this mode, SPI data rate is important to prevent error operation of FIFO extension. Therefore, MCU's SPI data rate shall be **faster than A105 on-air data rate**. Then, FPM [1:0] is used to set FIFO Pointer Flag (FPF) to inform MCU correct timing to write TX-FIFO or read RX-FIFO. FIFO pointer Flag (FPF) is output to pin CKO by set CKOS = [0010] (0AH).

Procedures of TX FIFO Extension

1. Initialize all control registers (refer to A7106 reference code).
2. Set FEP [7:0] = 0xFF for 256-bytes FIFO extension.
3. Set FPM [1:0] = 11 for FPF trigger condition.
4. Refer to section 11.2 ~ 11.4.
5. Send Strobe command – TX FIFO write pointer reset.
6. MCU writes 1st 64-bytes TX FIFO.
7. Send TX Strobe command.
8. MCU monitors FPF from A7106.
9. FPF triggers MCU to write 2nd 48-bytes TX FIFO.
10. MCU monitors FPF from A7106.
11. FPF triggers MCU to write 3rd 48-bytes TX FIFO.
12. MCU monitors FPF from A7106.
13. FPF triggers MCU to write 4th 48-bytes TX FIFO.
14. MCU monitors FPF from A7106.
15. FPF triggers MCU to write 5th 48-bytes TX FIFO.
16. Done.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

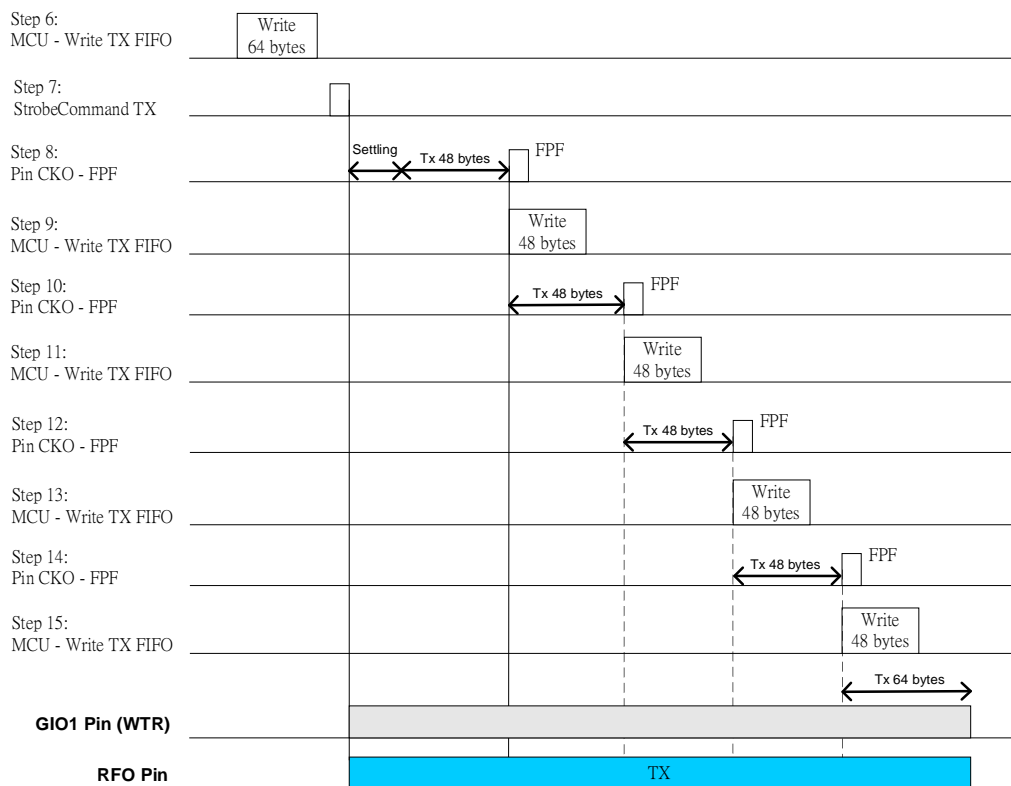


Figure 16.5 Reference timing of TX FIFO Extension

In TX mode, when the result of WTX (write TX pointer) subtracting DP (deliver pointer) is equal or less than the value set by FPM [1:0], FPF is 1. Otherwise FPF is 0.

TX Mode

FPM [1:0]	Bytes in TX FIFO	FPF = 1 (CKO pin)	Note
[00]	4	$WTX - DP \leq 4$	FPF=1, when delivering 60 th byte
[01]	8	$WTX - DP \leq 8$	FPF=1, when delivering 56 th byte
[10]	12	$WTX - DP \leq 12$	FPF=1, when delivering 52 th byte
[11]	16	$WTX - DP \leq 16$	FPF=1, when delivering 48 th byte



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Definitions

DP : Deliver Pointer

RP : Received Pointer

WTX : Write TX FIFO Pointer

Delta : $WTX - DP + 1 = 16$ if $FPM = 11$

TX FIFO Empty = DP reaches FEP[7:0]

RX FIFO FULL = RP reaches FEP[7:0]

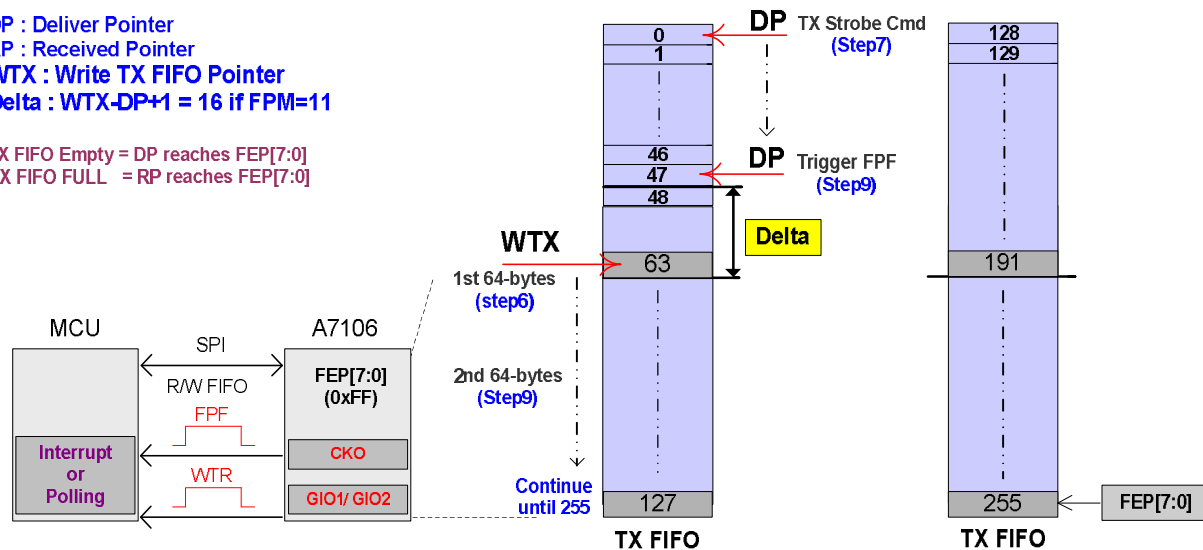


Figure 16.6 TX FIFO Extension

Procedures of RX FIFO Reading

1. Initialize all control registers (refer A7106 reference code).
2. Set FEP [7:0] = 0xFF for 256-bytes FIFO extension.
3. Set FPM [1:0] = 11b for FPF trigger condition.
4. Set CKO Register = 0x12
5. Send Strobe command – RX FIFO read pointer reset.
6. Send RX Strobe command.
7. MCU monitors FPF from A7106's CKO pin.
8. FPF triggers MCU to read 1st 48-bytes RX FIFO.
9. Monitor FPF.
10. FPF triggers MCU to read 2nd 48-bytes RX FIFO.
11. Monitor FPF.
12. FPF triggers MCU to read 3rd 48-bytes RX FIFO.
13. Monitor FPF.
14. FPF triggers MCU to read 4th 48-bytes RX FIFO.
15. Monitor FPF.
16. FPF triggers MCU to read 5th 48-bytes RX FIFO.
17. Monitor WTR falling edge or WTR = low, read the rest 16-bytes RX FIFO
18. Done.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

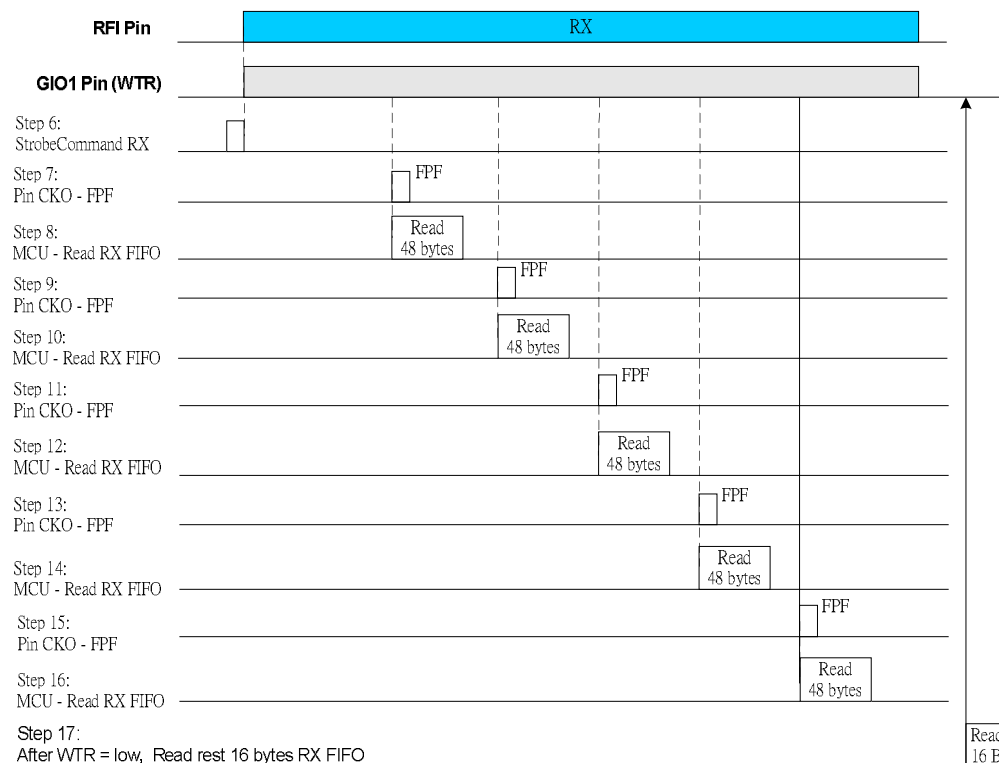


Figure 16.7 Reference timing of RX FIFO Extension

In RX mode, when the result of RP (received pointer) subtracting RRX (read RX pointer) is larger than the value set by FPM [1:0], FPF is 1. Otherwise FPF is 0.

RX Mode

FPM [1:0]	Bytes in RX FIFO	FPF = 1 (CKO pin)	Note
[00]	60	$RP - RRX > 60$	FPF=1, when receiving 60 th byte
[01]	56	$RP - RRX > 56$	FPF=1, when receiving 56 th byte
[10]	52	$RP - RRX > 52$	FPF=1, when receiving 52 th byte
[11]	48	$RP - RRX > 48$	FPF=1, when receiving 48 th byte



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Definitions

DP : Deliver Pointer

RP : Received Pointer

RRX : Read FIFO Pointer

Delta : $RP - RRX + 1 = 48$ if $FPM=11$

TX FIFO Empty = DP reaches FEP[7:0]

RX FIFO FULL = RP reaches FEP[7:0]

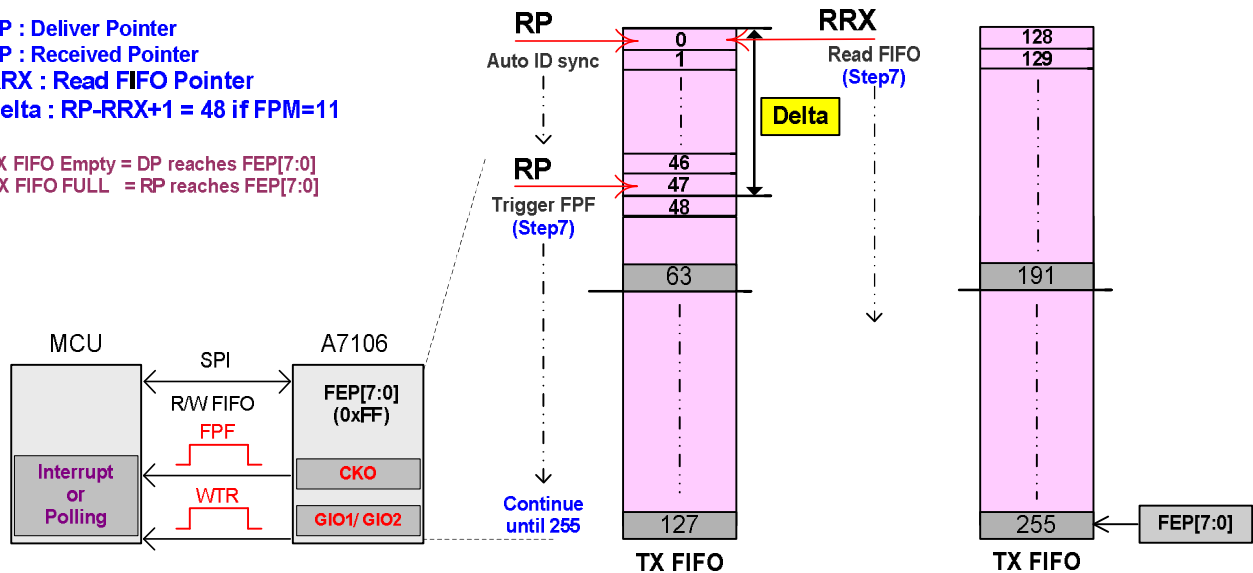


Figure 16.8 RX FIFO Extension Mode



A7106

Preliminary

2.4G FSK/GFSK Transceiver

17. ADC (Analog to Digital Converter)

A7106 has built-in 8-bits ADC do RSSI measurement as well as carrier detection function. User can set FSARS (1Eh) to select 4MHz or 8MHz ADC clock (F_{ADC}). The ADC converting time is 20 x ADC clock periods.

Bit		Mode	
XADS	RSS	Standby	RX
0	1	None	RSSI / Carrier detect

Table 17.1 Setting of ADC function

Relative Control Register

Mode Control Register (Address: 01h)

Bit	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Name	R	DDPC	ARSSI	AIF	CD	WWSE	FMT	FMS	ADCM
	W	DDPC	ARSSI	AIF	DFCD	WWSE	FMT	FMS	ADCM
Reset		0	0	0	0	0	0	0	0

RSSI Threshold Register (Address: 1Dh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
RSSI Threshold	R	ADC7	ADC6	ADC5	ADC4	ADC3	ADC2	ADC1	ADC0
	W	RTH7	RTH6	RTH5	RTH4	RTH3	RTH2	RTH1	RTH0
Reset		1	0	0	1	0	0	0	1

ADC Control Register (Address: 1Eh)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ADC Control	W	RSM1	RSM0	ERSS	FSARS	--	XADS	RSS	CDM
Reset		0	1	0	1	--	0	1	1

17.1 RSSI Measurement

A7106 supports 8-bits digital RSSI to detect RF signal strength. RSSI value is stored in ADC [7:0] (1Dh). Fig 17.1 shows a typical plot of RSSI reading as a function of input power. This curve is base on the current gain setting of A7106 reference code. A7106 automatically averages 8-times ADC conversion a RSSI measurement until A7106 exits RX mode. Therefore, each RSSI measuring time is (8 x 20 x F_{ADC}). For quick RSSI measurement, recommend to set FSARS = 1 (F_{ADC} =8MHz, 20 us measuring time). For power saving, recommend to set FSARS = 0 (F_{ADC} =4MHz, 40 us measuring time). Be aware RSSI accuracy is about $\pm 6\text{dBm}$.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

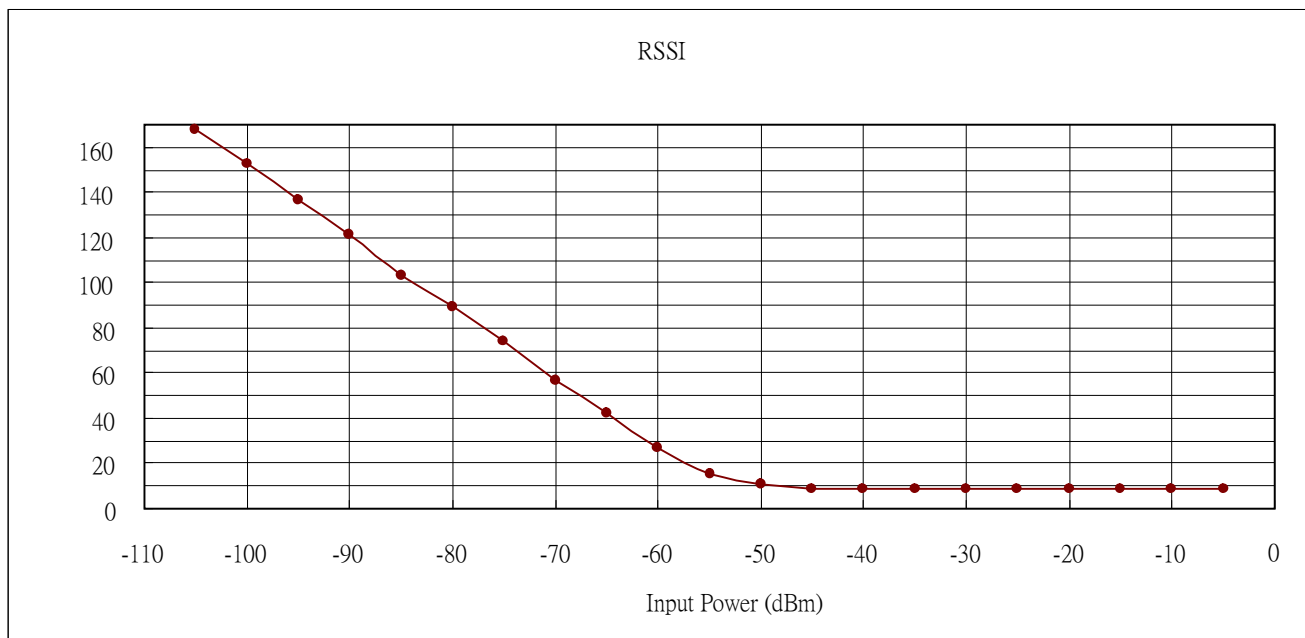


Figure 17.1 Typical RSSI characteristic.

Auto RSSI measurement for TX Power:

1. Set wanted F_{RXLO} (Refer to chapter 14).
2. Set RSS= 1 (1Eh), FSARS= 0 (1Eh, 4MHz ADC clock).
3. Enable ARSSI= 1 (01h).
4. Send RX Strobe command.
5. In RX mode, 8-times average a RSSI measurement periodically.
6. Exit RX mode, user can read digital RSSI value from ADC [7:0] (1Dh) for TX power.

In step 6, if A7106 is set in direct mode, MCU shall let A7106 exit RX mode within 40 us to prevent RSSI inaccuracy.

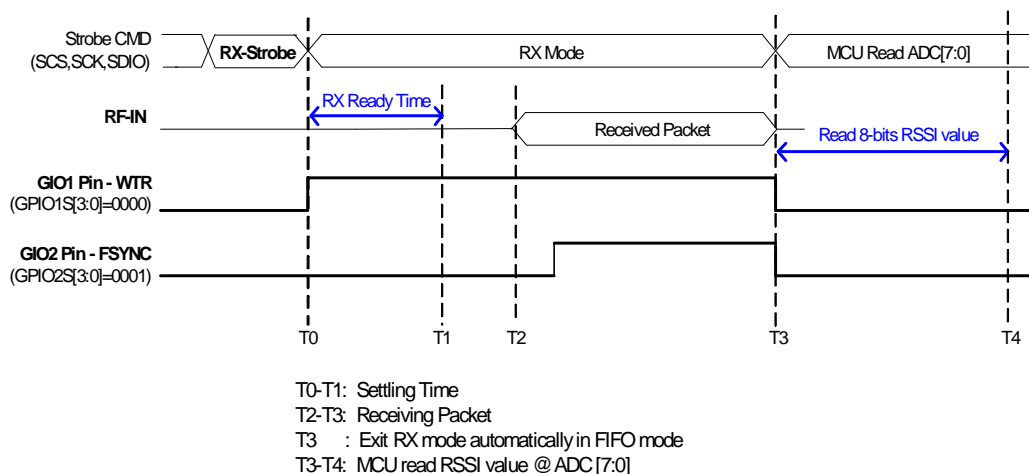


Figure 17.2 RSSI Measurement of TX Power.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

Auto RSSI measurement for Background Power:

1. Set wanted F_{RXLO} (Refer to chapter 14).
2. Set RSS= 1 (1Eh), FSARS= 1 (1Eh, 4MHz ADC clock).
3. Enable ARSSI= 1 (01h).
4. Send RX Strobe command.
5. MCU delays min. 140us.
6. Read digital RSSI value from ADC [7:0] (1Dh) to get background power.
7. Send other Strobe command to let A7106 exit RX mode.

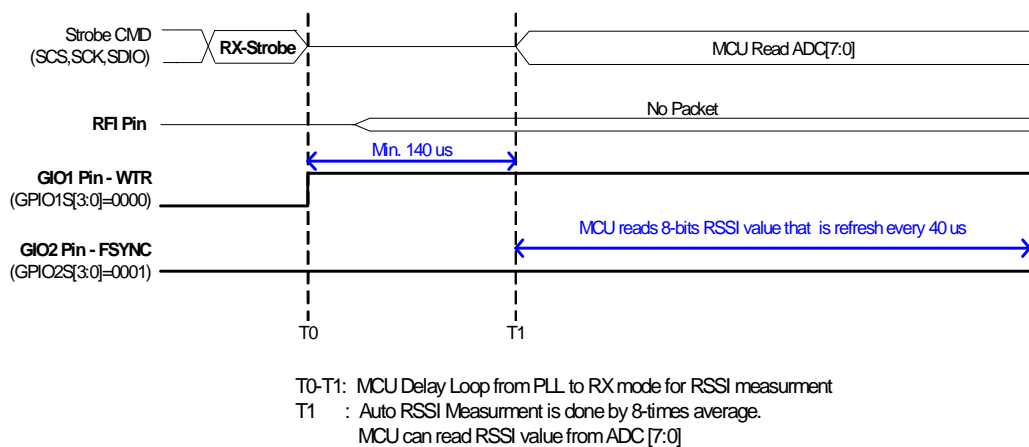


Figure 17.3 RSSI Measurement of Background Power.

17.2 Carrier Detect

Base on RSSI measurement, user can extend its application to do carrier detect (CD). In Carrier Detect mode, RSSI is refresh every 5 us without 8-times average. If RSSI level is below threshold level (RTH), CD is output high to GIO1 or GIO2 pin to inform MCU that current channel is busy.

Below is a reference procedure:

1. Set RTH (1Dh) for absolute RSSI threshold level (ex. RTH = 80d).
2. Set GIO2S = [0010] (0Ch) for Carrier Detect to GIO2 pin.
 - (2-1) Set wanted F_{RXLO} (Refer to chapter 14).
 - (2-2) Set RSS= 1 (1Eh), FSARS= 0 (1Eh, 4MHz ADC clock), RSM= [11] (1Eh, hysteresis, 20d).
 - (2-3) Enable ARSSI= 1 (01h).
 - (2-4) Send RX Strobe command.
 - (2-5) MCU enables a timer delay (min. 100 us).
3. MCU checks GIO2 pin.
 - (3-1) If $ADC \geq (RTH + RSM)$, GIO2 = 0.
 - (3-2) If $ADC \leq (RTH)$, GIO2 = 1.
 - (3-3) If ADC locates in hysteresis zone, GIO2 = previous state.
4. Exit RX mode.



A7106

Preliminary

2.4G FSK/GFSK Transceiver

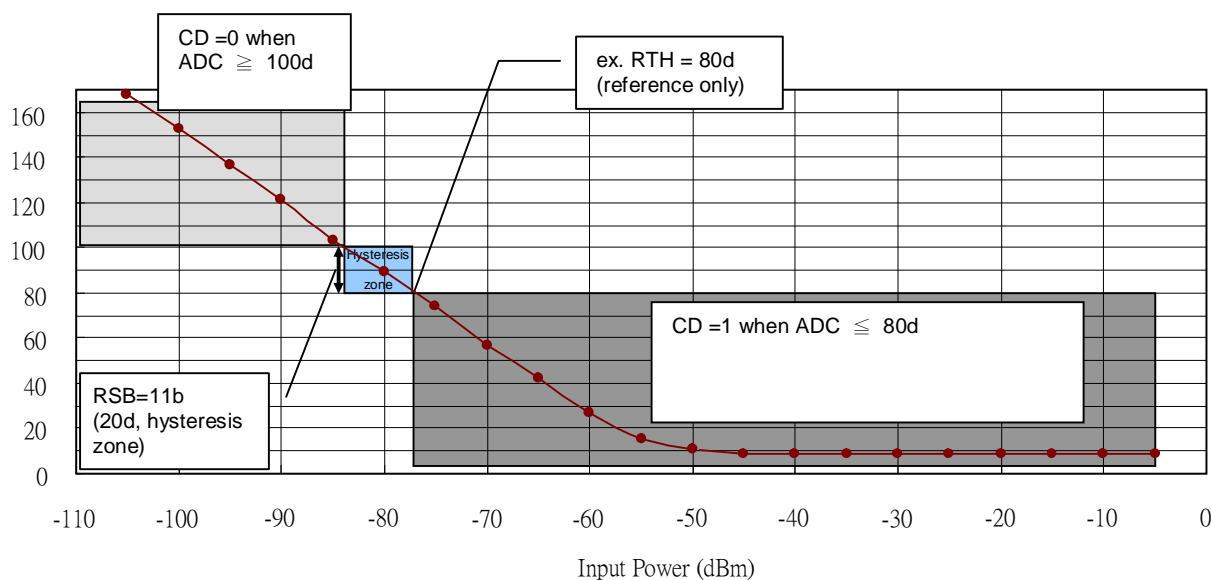


Figure 17.4 Carrier Detect Zone, a reference setting only.

18. Battery Detect

A7106 has a built-in battery detector to check supply voltage (REG1 pin). The detecting range is 2.0V ~ 2.7V in 8 levels.

Relative Control Register

Battery detect Register (Address: 27h)

Name	R/W	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Battery detect	R	--	--	--	BDF	--	--	--	--
	W	RGS	RGV1	RGV0	--	BVT2	BVT1	BVT0	BD_E
Reset		0	0	0	--	0	1	1	0

BVT [2:0]: Battery voltage detect threshold.

[000]: 2.0V. [001]: 2.1V. [010]: 2.2V. [011]: 2.3V.

[100]: 2.4V. [101]: 2.5V. [110]: 2.6V. [111]: 2.7V.

Below is the procedure to detect low voltage input (ex. below 2.1V):

1. Set A7106 in standby or PLL mode.
2. Set BVT (27h) = [001] and enable BD_E (27h) = 1.
3. After 5 us, BD_E is auto clear.
4. MCU reads BDF (27h).
If REG1 pin > 2.1V,
BDF = 1 (battery high). Else, BDF = 0 (battery low).



A7106

Preliminary

2.4G FSK/GFSK Transceiver

19 TX power setting

A7106 supports programmable TX power from – 20dBm ~ 1 dBm by TX test register (28h). User can configures PAC[1:0] and TBG[2:0] for different TX power level. The following tables show the typical TX power vs. current in different settings..

For PAC = 3:

TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-17.6	-14.5	-10	-7.2	-5.1	-3.5	-0.5	1.3
Current (mA)	17.6	17.7	17.78	18.1	18.2	18.5	19.5	21.25

For PAC = 2:

TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-18.7	-15.2	-12	-8.54	-6.84	-4.77	-1.5	0.1
Current (mA)	15.3	15.4	15.5	15.8	16.1	16.5	17.6	19

For PAC = 1:

TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-20.7	-16.9	-13.8	-10.4	-8.3	-6.3	-3.4	-0.5
Current (mA)	13.4	13.5	13.7	13.9	14.3	14.5	15.9	18

For PAC = 0:

TBG	0	1	2	3	4	5	6	7
TX output (dBm)	-23.3	-19.2	-16.6	-13.2	-10.9	-8.9	-4.8	-2.0
Current (mA)	12.4	12.5	12.6	12.9	13.3	13.6	14.9	16.9

For 0 dBm TX output power, the register setting: PAC = 2 and TBG = 7 are recommended.

For -10 dBm TX output power (low current requirement), PAC = 1 and TBG = 3 is recommended.



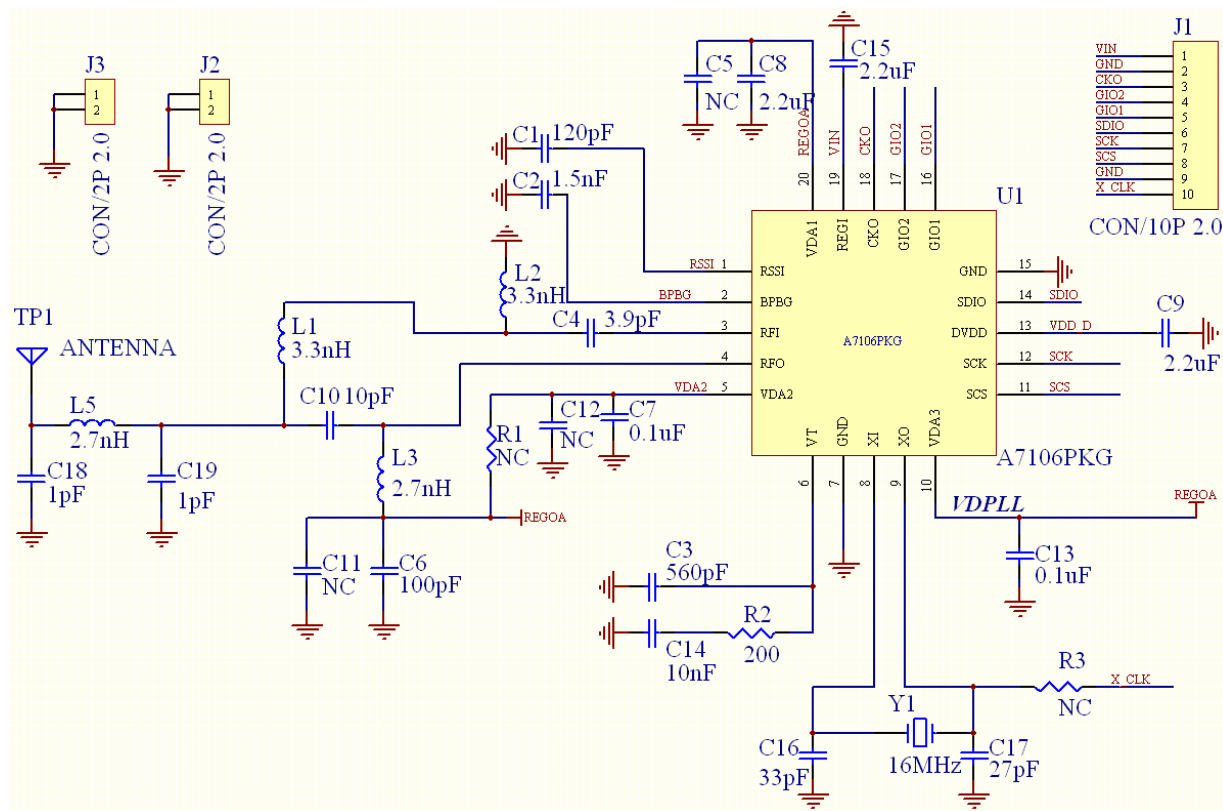
A7106

Preliminary

2.4G FSK/GFSK Transceiver

20. Application circuit

Below are AMICCOM's ref. design module, MD7106-A01, circuit example and its PCB layout.



1. A7106 schematic for RF layouts with single ended 50Ω RF output.
2. C16 and C17 must be matched to the crystal's load capacitance (Cload). Y1 is a 16MHz crystal with 18 pF Cload, max 80ohm ESR and 20 ppm tolerance. Please see application note for detail.



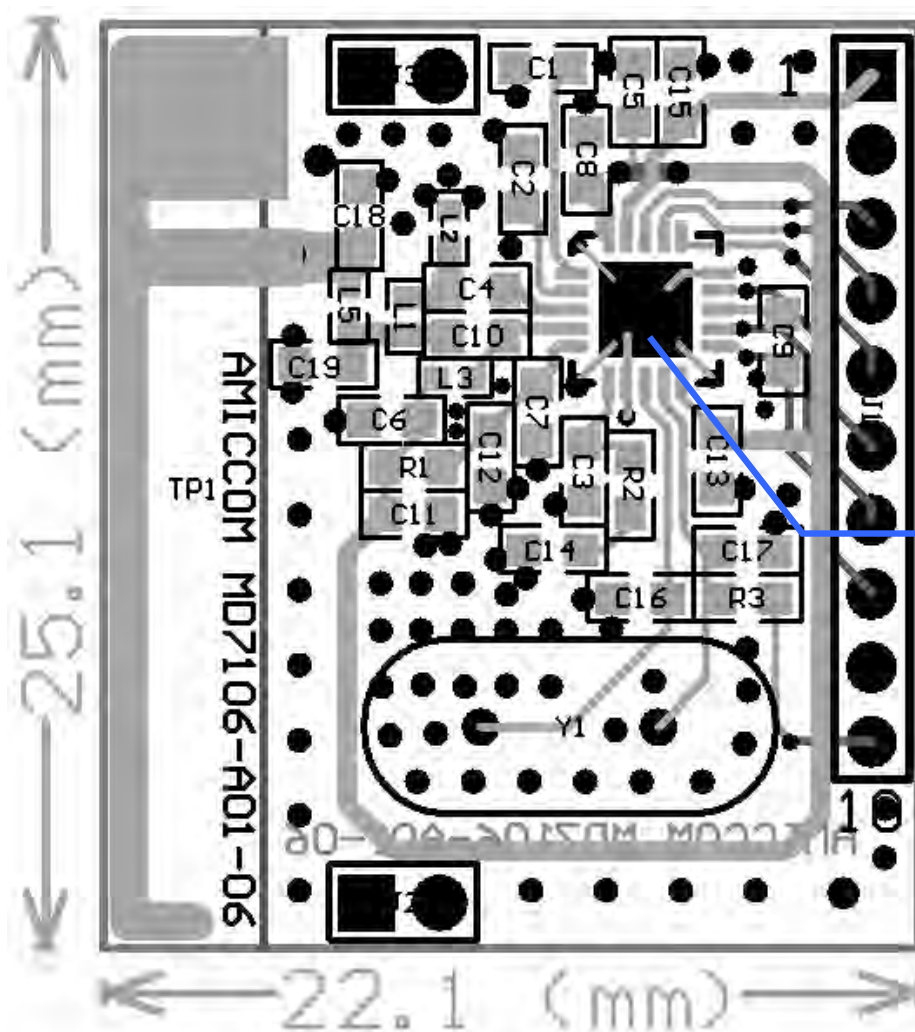
A7106

Preliminary

2.4G FSK/GFSK Transceiver

MD7106-A01 which size is 25mm x 22mm with PCB antenna is suitable for small form factor application. MD7106-A01 is based on a design by a double-sided **FR-4** board of **0.8mm** thickness. All passive components are 0402/ 0603 size. This PCB has a ground plane on the bottom layer. Additionally, there are ground areas on the component side of the board to ensure sufficient grounding of critical components. Keep sufficient via holes to connect the top layer ground areas to the bottom layer ground plane. **Be notice, IC back side plate shall be well-solder to ground; otherwise, it will impact RF performance.**

To get a good RF performance, a well designed PCB is necessary. A poor layout can lead to loss of RF performance especially on matching networks as well as VDD bypass capacitors. PCB layout of critical traces shall follow AMICCOM's recommended values and layout placement. Long power supply lines on the PCB should be avoided. Keep GND via holes as close as possible to A7106's **GND** pad and IC back side plate (**GND**).



Be Notice,

1. IC Back side plate shall be well-solder to ground (U1 area) for good RF performance.
2. Need at least 9 GND via holes at U1 area



A7106

Preliminary

2.4G FSK/GFSK Transceiver

21. Abbreviations

ADC	Analog to Digital Converter
AIF	Auto IF
FC	Frequency Compensation
AGC	Automatic Gain Control
BER	Bit Error Rate
BW	Bandwidth
CD	Carrier Detect
CHSP	Channel Step
CRC	Cyclic Redundancy Check
DC	Direct Current
FEC	Forward Error Correction
FIFO	First in First out
FSK	Frequency Shift Keying
ID	Identifier
IF	Intermediate Frequency
ISM	Industrial, Scientific and Medical
LO	Local Oscillator
MCU	Micro Controller Unit
PFD	Phase Frequency Detector for PLL
PLL	Phase Lock Loop
POR	Power on Reset
RX	Receiver
RXLO	Receiver Local Oscillator
RSSI	Received Signal Strength Indicator
SPI	Serial to Parallel Interface
SYCK	System Clock for digital circuit
TX	Transmitter
TXRF	Transmitter Radio Frequency
VCO	Voltage Controlled Oscillator
XOSC	Crystal Oscillator
XREF	Crystal Reference frequency
XTAL	Crystal

22. Ordering Information

Part No.	Package	Units Per Reel / Tray
A71C06AQFI/Q	QFN20L, Pb Free, Tape & Reel, -40°C ~ 85°C	3K
A71C06AQFI	QFN20L, Pb Free, Tray, -40°C ~ 85°C	490EA
A71C06BH	Die form, -40°C ~ 85°C	100EA



A7106

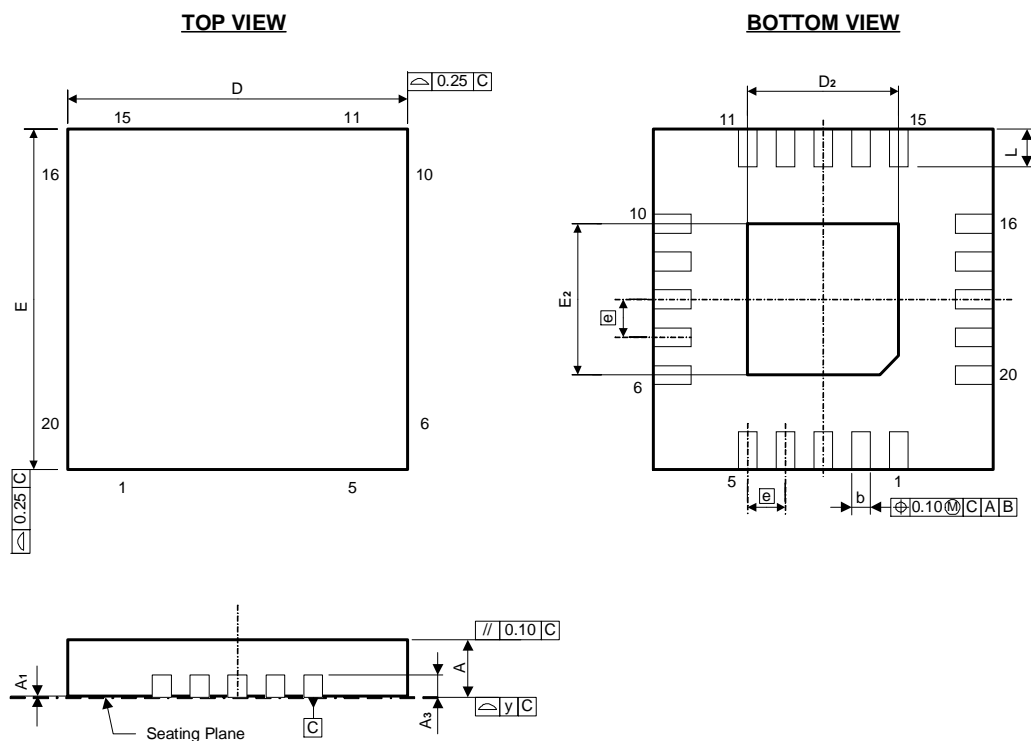
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2.4G FSK/GFSK Transceiver

23. Package Information

QFN 20L (4 X 4 X 0.8mm) Outline Dimensions

unit: inches/mm



Symbol	Dimensions in inches			Dimensions in mm		
	Min	Nom	Max	Min	Nom	Max
A	0.028	0.030	0.032	0.70	0.75	0.80
A1	0.000	0.001	0.002	0.00	0.02	0.05
A3	0.008 REF			0.203 REF		
b	0.007	0.010	0.012	0.18	0.25	0.30
D	0.154	0.158	0.161	3.90	4.00	4.10
D2	0.075	0.079	0.083	1.90	2.00	2.10
E	0.154	0.158	0.161	3.90	4.00	4.10
E2	0.075	0.079	0.083	1.90	2.00	2.10
[e]	0.020 BSC			0.50 BSC		
L	0.012	0.016	0.020	0.30	0.40	0.50
y	0.003			0.08		



A7106

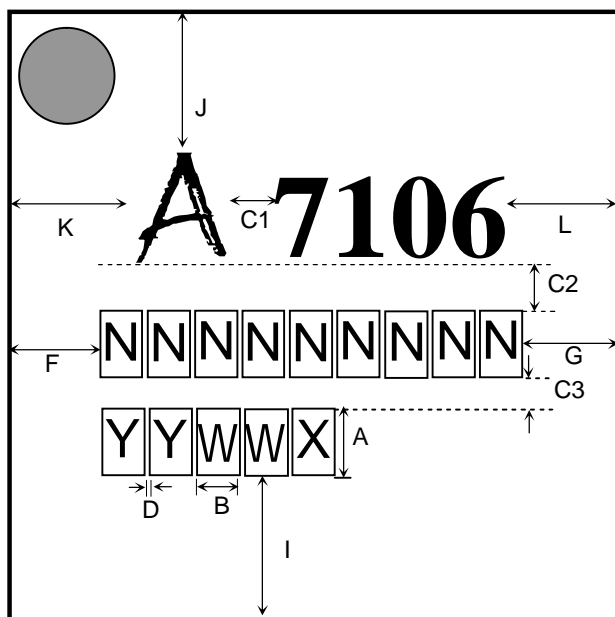
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2.4G FSK/GFSK Transceiver

24. Top Marking Information

A71C06AQFI

- Part No. : 71X06AQFI
- Pin Count : 20
- Package Type : QFN
- Dimension : 4*4 mm
- Mark Method : Laser Mark
- Character Type : Arial

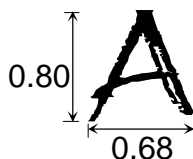


❖ CHARACTER SIZE : (Unit in mm)

A : 0.55
 B : 0.36
 C1 : 0.25
 C3 : 0.2
 D : 0.03
 A1 : 0.75
 B2 : 0.7

C2 : 0.3

F=G
 I=J
 K=L



YYWW

: DATECODE

X

: PKG HOUSE ID

NNNNNNNNNN

: LOT NO.
 (The last 9
 characters,
 no decimals)





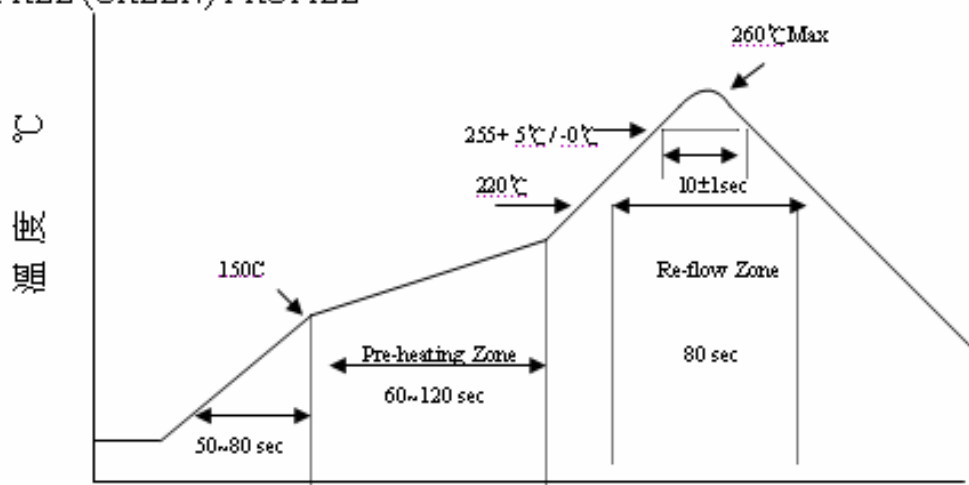
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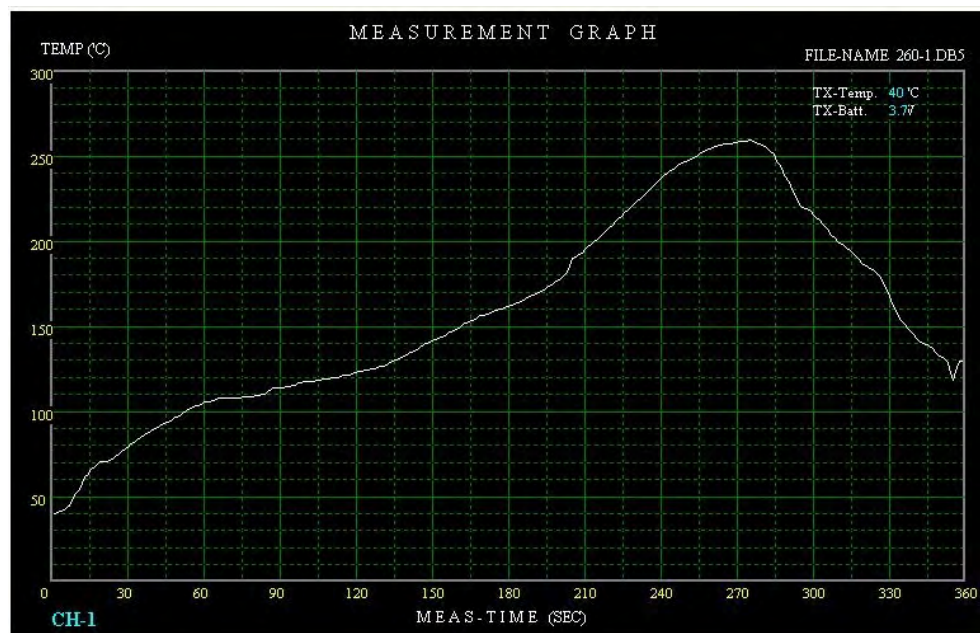
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25. Reflow Profile

LEAD FREE (GREEN) PROFILE :



Actual Measurement Graph





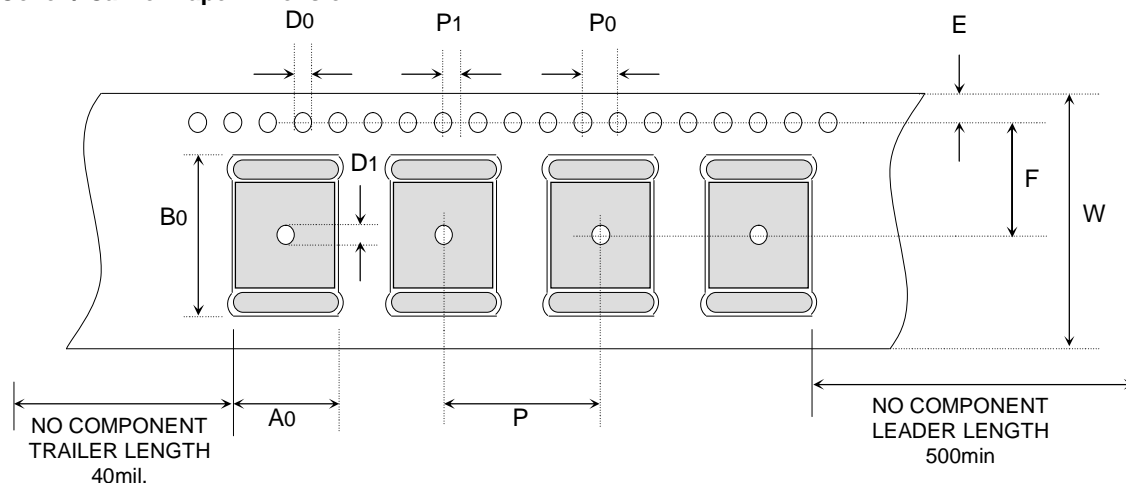
A7106

Preliminary

2.4G FSK/GFSK Transceiver

26. Type Reel Information

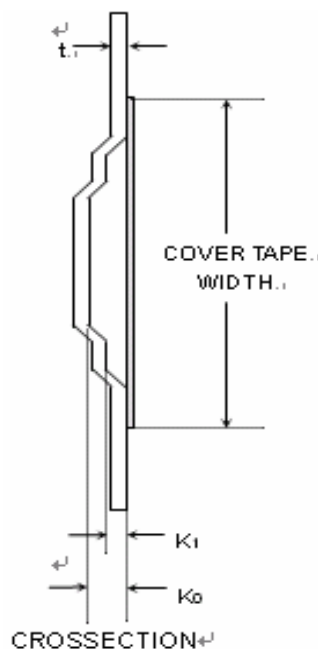
Cover / Carrier Tape Dimension



11 EA IC

60cm±4cm

TYPE	P	A0	B0	P0	P1	D0	D1	E	F	W
20 QFN 4*4	8	4.35	4.35	4.0	2.0	1.5	1.5	1.75	5.5	12
24 QFN 4*4	8	4.4	4.4	4.0	2.0	1.5	1.5	1.75	5.5	12
32 QFN 5*5	8	5.25	5.25	4.0	2.0	1.5	1.5	1.75	5.5	12
48 QFN 7*7	12	7.25	7.25	4.0	2.0	1.5	1.5	1.75	7.5	16
DFN-10	4	3.2	3.2	4.0	2.0	1.5	-	1.75	1.9	8
20 SSOP	12	8.2	7.5	4.0	2.0	1.5	1.5	1.75	7.5	16
24 SSOP	12	8.2	8.8	4.0	2.0	1.5	1.5	1.75	7.5	16
28 SSOP (150mil)	8	6	10	4.0	2.0	1.5	1.5	1.75	7.5	16



TYPE	K0	K1	t
20 QFN (4X4)	1.1	-	0.3
24 QFN (4X4)	1.4	-	0.3
32 QFN (5X5)	1.1	-	0.3
48 QFN (7X7)	1.1	-	0.3
DFN-10	0.75	-	0.25
20 SSOP	2.5	-	0.3
24 SSOP	2.1	-	0.3
28 SSOP (150mil)	2.5	-	0.3

COVER TAPE WIDTH
9.2
9.2
9.2
13.3
8
13.3
13.3
12.5

Unit : mm



A7106

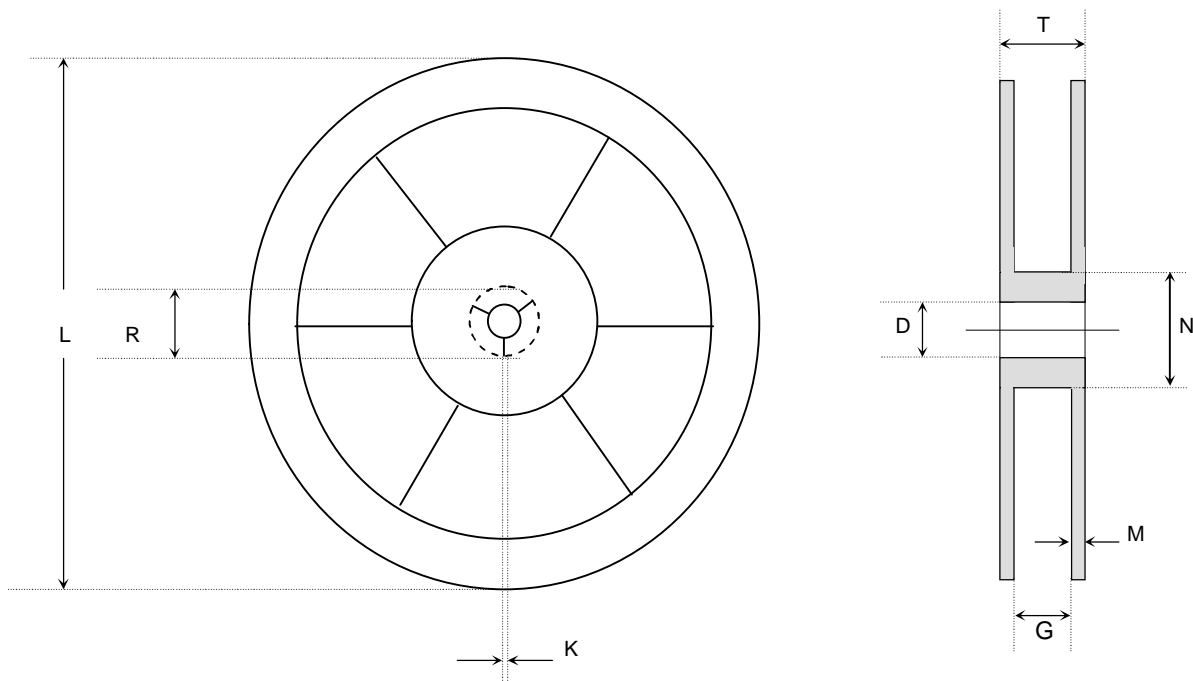
Preliminary

2.4G FSK/GFSK Transceiver

REEL DIMENSIONS

UNIT IN mm

TYPE	G	N	T	M	D	K	L	R
20 QFN(4X4) 24 QFN(4X4) 32 QFN(5X5) DFN-10	12.8+0.6/-0.4	100 REF	18.2(MAX)	1.75±0.25	13.0+0.5/-0.2	2.0±0.5	330+ 0.00/-1.0	20.2
48 QFN(7X7)	16.8+0.6/-0.4	100 REF	22.2(MAX)	1.75±0.25	13.0+0.5/-0.2	2.0±0.5	330+ 0.00/-1.0	20.2
28 SSOP (150mil)	20.4+0.6/-0.4	100 REF	25(MAX)	1.75±0.25	13.0+0.5/-0.2	2.0±0.5	330+ 0.00/-1.0	20.2
20 SSOP 24 SSOP	16.4+2.0/-0.0	100 REF	22.4(MAX)	1.75±0.25	13.0+0.2/-0.2	1.9±0.4	330+ 0.00/-1.0	20.2



**A7106****Preliminary****2.4G FSK/GFSK Transceiver****27. Product Status**

Data Sheet Identification	Product Status	Definition
Objective	Planned or Under Development	This data sheet contains the design specifications for product development. Specifications may change in any manner without notice.
Preliminary	Engineering Samples and First Production	This data sheet contains preliminary data, and supplementary data will be published at a later date. AMICCOM reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
No Identification	Noted Full Production	This data sheet contains the final specifications. AMICCOM reserves the right to make changes at any time without notice in order to improve design and supply the best possible product.
Obsolete	Not In Production	This data sheet contains specifications on a product that has been discontinued by AMICCOM. The data sheet is printed for reference information only.

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