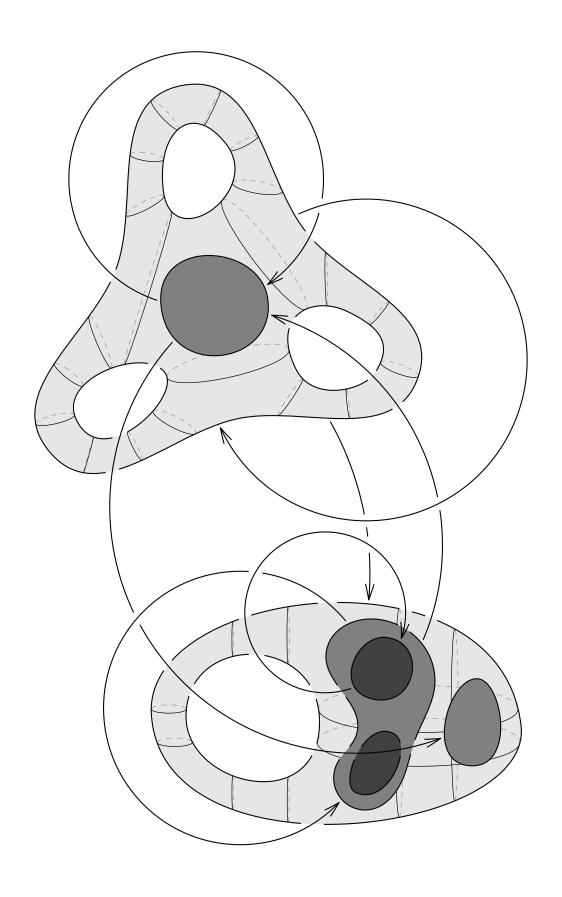
# smoothmanifold.asy - v6.3.1

# Diagrams in higher mathematics with Asymptote by Roman Maksimovich



# Abstract

This document contains the full description and user manual to the smoothmanifold Asymptote module, home page https://github.com/thornoar/smoothmanifold.

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#### 1. Introduction

In higher mathematics, diagrams often take the form of "blobs" (representing sets and their subsets) placed on the plane, connected with paths or arrows. This is particularly true for set theory and topology, but other more advanced fields inherit this style. In differential geometry and multivariate calculus, one draws spheres, tori, and other surfaces in place of these "blobs". In category theory, commutative diagrams are commonplace, where the "blobs" are replaced by symbols. Here are a couple of examples, all drawn with smoothmanifold:

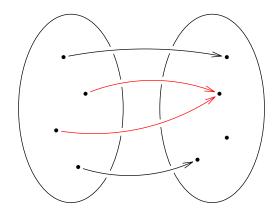


Figure 1: An illustration of non-injectivity (set theory)

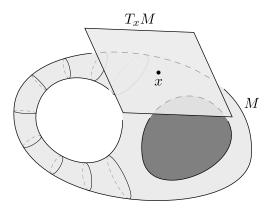


Figure 2: Tangent space at a point on a manifold (diff. geometry)

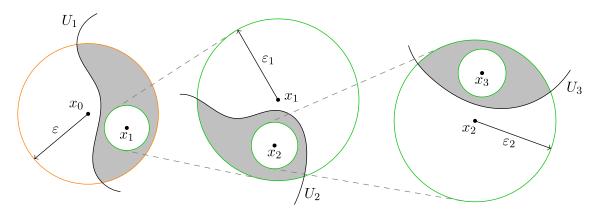


Figure 3: The proof of the Baire category theorem (topology)

Take special note of the gaps that arrows leave on the boundaries of the ovals in Figure 1. I find this feature quite hard to achieve in plain Asymptote, and module smoothmanifold uses some dark magic to implement it. Similarly, note the shaded areas in Figure 3. They represent intersections of areas bounded by two paths. Finding the bounding path of such an intersection is non-trivial and also implemented in smoothmanifold. Lastly, Figure 2 shows a three-dimensional surface, while the picture was fully drawn in 2D. The illusion is achieved through these cross-sectional "rings" on the left of the diagram.

To summarize, the most prominent features of module smoothmanifold are the following:

- Gaps in overlapping paths, achieved through a system of deferred drawing;
- Set operations on paths bounding areas, e.g. intersection, union, set difference, etc.;
- Three-dimensional drawing, achieved through an automatic (but configurable) addition of cross sections to smooth objects.

Do take a look at the source code for the above diagrams, to get a feel for how much heavy lifting is done by the module, and what is required from the user. We will now consider each of the above mentioned features (and some others as well) in full detail.

# 2. Deferred drawing and path overlapping

#### 2.1. The general mechanism

In the picture structure, the paths drawn on a picture are not stored in an array, but rather indirectly stored in a void callback. That is, when the draw function is called, the *instruction to draw* the path is added to the picture, not the path itself. This makes it quite impossible to "modify the path after it is drawn". To go around this limitation, smoothmanifold introduces an auxiliary structure:

```
struct deferredPath {
   path[] g;
   pen p;
   int[] under;
   tarrow arrow;
   tbar bar;
}
```

It stores the path(s) to draw later, and how to draw them. Now, smoothmanifold executes the following steps to draw a "mutable" path p to a picture pic and then draw it for real:

- 1. Have a global two-dimensional array, say arr, of deferredPath's;
- 2. Construct a deferredPath based on p, say dp;
- 3. Exploit the nodes field of the picture structure to store an integer. Retrieve this integer, say n, from pic (or create one if the nodes field doesn't contain it).
- 4. Store the deferred path dp in the one-dimensional array arr[n];
- 5. Move on with the original code, perhaps modifying the deferred path dp in arr as needed, e.g. adding gaps;
- 6. At shipout time, when processing the picture pic, retrieve the index n from its nodes field and draw all deferredPath objects in the array arr[n].

All these steps require no extra input from the user, since the shipout function is redefined to do them automatically. One only needs to use the fitpath function instead of draw.

#### 2.2. The tarrow and tbar structures

Similarly to drawing paths to a picture, arrows and bars are implemented through a function type bool(picture, path, pen, margin), typedef'ed as arrowbar. Moreover, when this arrowbar is called, it automatically draws not only itself, but also the path is was attached to. This makes it impossible to attach an arrowbar to a path and then mutate the path — the arrowbar will remember the path's original state. Hence, smoothmanifold implements custom arrow/bar implementations:

```
struct tarrow {
    arrowhead head;
    real size;
    real angle;
    real angle;
    filltype ftype;
    bool begin;
    bool end;
    bool arc;
}
```

These structures store information about the arrow/bar, and are converted to regular arrowbars when the corresponding path is drawn to the picture. For creating new tarrow/tbar instances and converting them to arrowbars, the following functions are available:

```
tarrow DeferredArrow(
                                               tbar DeferredBar(
    arrowhead head = DefaultHead,
                                                   real size = 0,
    real size = 0,
                                                   bool begin = false,
    real angle = arrowangle,
                                                   bool end = false
    bool begin = false,
    bool end = true,
                                               arrowbar convertbar(
    bool arc = false,
                                                   tbar bar,
    filltype filltype = null
                                                   bool overridebegin = false,
                                                   bool overrideend = false
arrowbar convertarrow(
    tarrow arrow,
    bool overridebegin = false,
    bool overrideend = false
)
```

The overrideegin and overrideend options let the user force disable the arrow/bar at the beginning/end of the path.

## 2.3. The fitpath function

This is a substitute for the plain draw function. The fitpath function implements steps 1-4 of the deferred drawing system describes above.

```
void fitpath (picture pic, path gs, bool overlap, int covermode, bool drawnow, Label L,
pen p, tarrow arrow, tbar bar)
```

#### Arguments:

- pic the picture to fit the path to;
- gs the path to fit;
- overlap whether to let the path overlap the previously fit paths. A value of false will lead to gaps being left in all paths that gs intersects;
- covermode if the path gs is cyclic, this option lets you decide what happens to the parts of previously fit paths that fall "inside" of gs. Suppose a portion s of another path falls inside the cyclic path gs. Then
  - ► covermode == 2: The portion s will be erased completely;
  - covermode == 1: The portion s will be "demoted to the background" either temporarily removed or drawn with dashes;
  - ► covermode == 0: The portion s will be drawn like the rest of the path;
  - ► covermode == -1: If the portion s is "demoted", it will be brought "back to the surface", i.e. drawn with solid pen. Otherwise, it will be draw as-is.

Consider the following example:

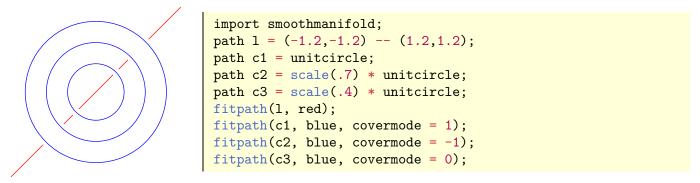


Figure 4: A showcase of the fitpath function

• drawnow — whether to draw the path gs immediately to the picture. When drawnow == true, the path gs leaves gaps in other paths, but is immutable itself, i.e. later fit paths will not leave any gaps in it.

When drawnow == false, the path gs is not immediately drawn, but rather saved to be mutated and finally drawn at shipout time;

- L the label to attach to gs. This label is drawn to pic immediately on call of fitpath, unlike gs;
- p the pen to draw gs with;
- arrow the arrow to attach to the path. Note that the type is tarrow, not arrowbar;
- bar the bar to attach to the path. Note that the type is tbar, not arrowbar.

Apart from different types of the arrow/bar arguments, the fitpath function is identical to draw in type signature, and they can be used interchangeably. Moreover, there are overloaded versions of fitpath, where parameters are given default values (one of these versions is used in the example above):

```
void fitpath (
                                               void fitpath (
    picture pic = currentpicture,
                                                  picture pic = currentpicture,
                                                  path[] g,
    path g,
    bool overlap = config.drawing.overlap,
                                                  bool overlap = config.drawing.overlap,
    int covermode = 0,
                                                  int covermode = 0,
    Label L = "",
                                                  Label L = "",
    pen p = currentpen,
                                                  pen p = currentpen,
    bool drawnow = config.drawing.drawnow,
                                                  bool drawnow = config.drawing.drawnow
    tarrow arrow = null,
    tbar bar = config.arrow.currentbar
```

Here, config is the global configuration structure, see Section 5. Furthermore, there are corresponding fillfitpath functions that serve the same purpose as filldraw.

#### 2.4. Other related routines

```
int extractdeferredindex (picture pic)
```

Inspect the nodes field of pic for a string in a particular format, and, if it exists, extract an integer from it.

```
deferredPath[] extractdeferredpaths (picture pic, bool createlink)
```

Extract the deferred paths associated with the picture pic. If createlink is set to true and pic has no integer stored in its nodes field, the routine will find the next available index and store it in pic.

```
path[] getdeferredpaths (picture pic = currentpicture)
```

A wrapper around extractdeferredpaths, which concatenates the path[] g fields of the extracted deferred paths.

```
void purgedeferredunder (deferredPath[] curdeferred)
```

For each deferred path in curdeferred, delete the segments that are "demoted" to the background (i.e. going under a cyclic path, drawn with dashed lines).

```
void drawdeferred (
   picture pic = currentpicture,
   bool flush = true
)
```

Render the deferred paths associated with pic, to the picture pic. If flush is true, delete these deferred paths.

```
void flushdeferred (picture pic = currentpicture)
```

Delete the deferred paths associated with pic.

```
void plainshipout (...) = shipout;
shipout = new void (...)
{
    drawdeferred(pic = pic, flush = false);
    draw(pic = pic, debugpaths, red+1);
    plainshipout(prefix, pic, orntn, format, wait, view, options, script, lt, P);
};
```

A redefinition of the **shipout** function to automatically draw the deferred paths at shipout time. For a definition of **debugpaths**, see Section 4.4.

The functions erase, \* (transform, picture), add, save, and restore are redefined to automatically handle deferred paths.

# 3. Operations on paths

## 3.1. Set operations on bounded regions

Module smoothmanifold defines a routine called combination which, given two *cyclic* paths p and q, calculates a result path which encloses a region that is a combination of the regions p and q:

```
path[] combination (path p, path q, int mode, bool round, real roundcoeff)
```

This function returns an array of paths because the combination of two bounded regions may be bounded by multiple paths. Rundown of the arguments:

- p and q cyclic paths bounding the regions to combine;
- mode an internal parameter which allows to specialize combination for different purposes;
- round and roundcoeff whether to round the sharp corners of the resulting bounding path(s).

```
filldraw(
    combination(p, q, 1, false, 0), // <- no rounding
    drawpen = linewidth(.7),
    fillpen = palegrey
);
<...>
filldraw(
    combination(p, q, 1, true, .04), // <- yes rounding
    drawpen = linewidth(.7),
    fillpen = palegrey
);
<...>
```

Figure 5: A showcase of the round and roundcoeff parameters

Based on different values for the mode parameter, the module defines the following specializations:

```
path[] difference (
   path p,
   path q,
   bool correct = true,
   bool round = false,
   real roundcoeff = config.paths.roundcoeff
)
path[] operator - (path p, path q)
{ return difference(p, q); }

path[] operator - (path p, path q)
{ return difference(p, q); }
```

Calculate the path(s) bounding the set difference of the regions bounded by p and q. The correct parameter determines whether the paths should be "corrected", i.e. oriented clockwise.

```
path[] symmetric (
   path p,
   path q,
   bool correct = true,
   bool round = false,
   real roundcoeff = config.paths.roundcoeff
)
path[] operator :: (path p, path q)
{ return symmetric(p, q); }

{ return symmetric(p, q); }
```

Calculate the path(s) bounding the set symmetric difference of the regions bounded by p and q.

```
path[] intersection (
   path p,
   path p,
   path q,
   bool correct = true,
   bool round = false,
   real roundcoeff = config.paths.roundcoeff
)
path[] operator ^ (path p, path q)
{ return intersection(p, q); }
```

Calculate the path(s) bounding the set intersection of the regions bounded by **p** and **q**. The following array versions are also available:

```
path[] intersection (
   path[] ps,
   bool correct = true,
   bool round = false,
   real roundcoeff = config.paths.roundcoeff
)
)

path[] intersection (
   bool correct = true,
   bool round = false,
   real roundcoeff = config.paths.roundcoeff
   ... path[] ps
)
```

Inductively calculate the total intersection of an array of paths.

```
path[] union (
   path p,
   path q,
   path q,
   bool correct = true,
   bool round = false,
   real roundcoeff = config.paths.roundcoeff
)

path[] operator | (path p, path q)
{ return union(p, q); }
```

Calculate the path(s) bounding the set union of the regions bounded by **p** and **q**. The corresponding array versions are available:

```
path[] union (
  path[] ps,
  bool correct = true,
  bool round = false,
  real roundcoeff = config.paths.roundcoeff
)

path[] union (
  bool correct = true,
  bool round = false,
  real roundcoeff = config.paths.roundcoeff
  ... path[] ps
)
```

Inductively calculate the total union of an array of paths. Here is an illustration of the specializations:

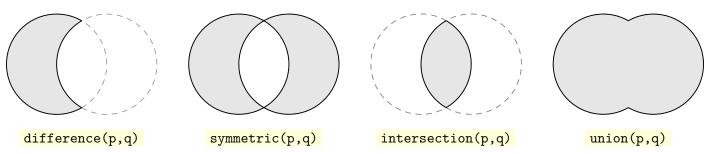


Figure 6: Different specializations of the combination function

#### 3.2. Other path utilities

Module smoothmanifold features dozens of useful auxiliary path utilities, all of which are listed below.

```
path[] convexpaths = { ... }
path[] concavepaths = { ... }
```

Predefined collections of convex and concave paths (14 and 7 paths respectively), added for user convenience.

```
path randomconvex ()
path randomconcave ()
```

Allows the user to sample a random path from the above arrays.

```
path ucircle = reverse(unitcircle);
path usquare = (1,1) -- (1,-1) -- (-1,-1) -- cycle;
```

Slightly changed versions of the unitcircle and unitsquare paths. Most notably, these are *clockwise*, since most of this module-s functionality prefers to deal with clockwise paths.

```
pair center (path p, int n = 10, bool arc = true, bool force = false)
```

Calculate the center of mass of the region bounded by the cyclic path p. If force is false and the center of mass is outside of p, the routine uses a heuristic to return another point, inside of p.

```
bool insidepath (path p, path q)
```

Check if path q is completely inside the cyclic path p (directions of p and q do not matter).

```
real xsize (path p) { return xpart(max(p)) - xpart(min(p)); }
real ysize (path p) { return ypart(max(p)) - ypart(min(p)); }
```

Calculate the horizontal and vertical size of a path.

```
real radius (path p) { return (xsize(p) + ysize(p))*.25; }
```

Calculate the approximate radius of the region enclosed by p.

```
real arclength (path g, real a, real b) { return arclength(subpath(g, a, b)); }
```

A more general version of arclength.

```
real relarctime (path g, real t0, real a)
```

Calculate the time at which arc length a will be traveled along the path g, starting from time t0.

```
path arcsubpath (path g, real arc1, real arc2)
```

Calculate the subpath of g, starting from arc length arc1, and ending with arc length arc2.

```
real intersectiontime (path g, pair point, pair dir)
```

Calculate the time of the intersection of g with a beam going from point in direction dir

```
pair intersection (path g, pair point, pair dir)
```

Same as intersectiontime, but returns the point instead of the intersection time.

```
path reorient (path g, real time)
```

Shift the starting point of the cyclic path g by time time. The resulting path will be same as g, but will start from time time along g.

```
path turn (path g, pair point, pair dir)
{ return reorient(g, intersectiontime(g, point, dir)); }
```

A combination of reorient and intersectiontime, that shifts the starting point of the cyclic path g to its intersection with the ray cast from point in the direction dir.

```
path subcyclic (path p, pair t)
```

Calculate the subpath of the *cyclic* path p, from time t.x to time t.y. If t.y < t.x, the subpath will still go in the direction of g instead of going backwards.

```
bool clockwise (path p)
```

Determine if the cyclic path p is going clockwise.

```
bool meet (path p, path q) { return (intersect(p, q).length > 0); }
bool meet (path p, path[] q) { ... }
bool meet (path[] p, path[] q) { ... }
```

A shorthand function to determine if two (or more) paths have an intersection point.

```
pair range (path g, pair center, pair dir, real ang, real orient = 1)
```

Calculate the begin and end times of a subpath of g, based on center, dir, and angle, as such:

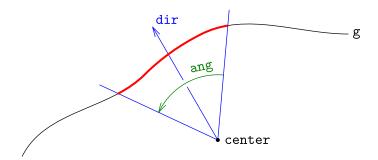


Figure 7: An illustration of the range function

If orient is set to -1 instead of 1, then the returned times are switched.

```
bool outsidepath (path p, path q)
```

Check if q is completely outside (that is, inside the complement) of the region enclosed by p.

```
path ellipsepath (pair a, pair b, real curve = 0, bool abs = false)
```

Produce half of an ellipse connecting points a and b. Curvature may be relative or absolute.

```
path curvedpath (pair a, pair b, real curve = 0, bool abs = false)
```

Construct a curved path between two points. Curvature may be relative (from 0 to 1) or absolute.

```
path cyclepath (pair a, real angle, real radius)
```

A circle of radius radius, starting at a and turned at angle.

```
path midpath (path g, path h, int n = 20)
```

Construct the path going "between" g and h. The parameter n is the number of sample points, the more the more precise the output.

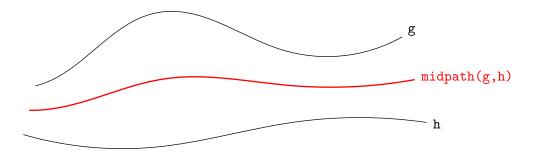


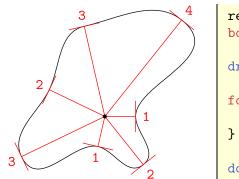
Figure 8: An illustration of the midpath function

```
path connect (pair[] points)
path connect (... pair[] points)
```

Connect an array of points with a path.

```
path wavypath (real[] nums, bool normaldir = true, bool adjust = false)
path wavypath (... real[] nums)
```

Generate a clockwise cyclic path around the point (0,0), based on the nums parameter. If normaldir is set to true, additional restrictions are imposed on the path. If adjust is true, then the path is shifted and scaled such that its center [page 9] is (0,0), and its radius [page 9] is 1. Consider the following example:



```
real[] nums = {1,2,1,3,2,3,4};
bool normaldir = true;

draw(wavypath(nums, normaldir));

for (int i = 0; i < nums.length; ++i) {
    <...> // draw numbers
}

dot((0,0));
```

Figure 9: A showcase of the wavypath function

```
path connect (path p, path q)
```

Connect the paths p and q smoothly.

```
pair randomdir (pair dir, real angle)
{ return dir(degrees(dir) + (unitrand()-.5)*angle); }
path randompath (pair[] controlpoints, real angle)
```

Create a pseudo-random path passing through the controlpoints. The angle parameter determines the "spread" of randomness. Here's an example:

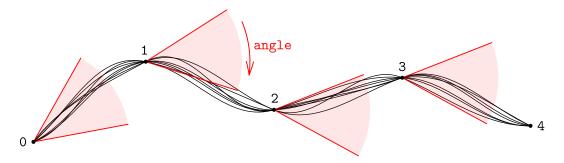


Figure 10: A showcase of the randompath function

```
path neigharc (
    real x = 0,
    real h = config.paths.neighheight,
    int dir = 1,
    real w = config.paths.neighwidth
)
```

Draw an "open neighborhood bracket" on the real line, like so:

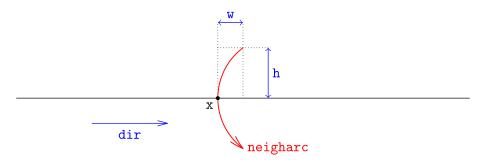


Figure 11: A showcase of the neighbor function

# 4. Smooth objects

#### 4.1. Definition of the smooth, hole, subset, and element structures

The smoothmanifold module's original purpose was to introduce a suitable abstraction to simplify drawing blobs on the plane. The smooth structure is, perhaps, the oldest part of smoothmanifold, that has persisted through countless updates and changes. In its current form, here is how it's defined:

```
struct smooth {
                                               struct hole {
    path contour;
                                                   path contour;
   pair center;
                                                   pair center;
                                                   real[][] sections;
    string label;
                                                   int scnumber;
                                               }
    pair labeldir;
    pair labelalign;
                                               struct subset {
                                                   path contour;
    hole[] holes;
    subset[] subsets;
                                                   pair center;
    element[] elements;
                                                   string label;
                                                   pair labeldir;
    transform unitadjust;
                                                   pair labelalign;
                                                    int layer;
    real[] hratios;
                                                   int[] subsets;
    real[] vratios;
                                                   bool isderivative;
                                                   bool isonboundary;
                                               }
    bool isderivative;
    smooth[] attached;
                                               struct element {
                                                   pair pos;
    void drawextra (dpar, smooth);
                                                   string label;
                                                   pair labelalign;
                                               }
    static smooth[] cache;
```

Every smooth object has a:

- contour the clockwise cyclic path that serves as a boundary of the object;
- center the center of the object, usually inferred automatically with center(contour) [page 9];
- label a string label, e.g. "\$A\$" or "\$S\$", that will be displayed when drawing the smooth object;

• labeldir and labelalign — they determine where the label is to be drawn, namely at intersection(contour, center, labeldir) [page 9], with labelalign as align.

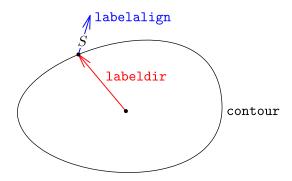


Figure 12: A showcase of the labeldir and labelalign fields

- holes an array of hole structures, each of which has a:
  - contour the clockwise cyclic boundary of the hole;
  - center the center of the hole, typically calculated automatically by center (contour) [page 9];
  - ▶ sections a two-dimensional array that determines where to draw the cross sections seen in Figure 2. For a detailed description, see Section 4.7.2;
  - scnumber the maximum amount of cross sections that the hole allows other holes to share with it. These are sections between holes, not ones between a hole and the contour of the smooth object. For details, see Section 4.7.2:
- subsets an array of subset structures, each of which has a:
  - contour the clockwise cyclic boundary of the subset;
  - center the center of the subset, likewise usually determined by center(contour) [page 9];
  - ▶ label, labeldir, labelalign serve the same purpose as the respective fields of the smooth object;
  - ▶ layer an integer determining the "depth" of the subset. A toplevel subset will have layer == 0, its subsets will have layer == 1, their subsets will have layer == 2, etc. This way, a hierarchy of subsets is established. For details, see Section 4.4;
  - ▶ subsets an index i is an element of this array if and only if the subset subsets[i] (taken from the subsets field of the parent smooth object) is a subset of the current subset. For details, see Section 4.4;
  - isderivative a flag that marks all automatically created subsets (i.e. those that represent intersections of existing subsets). For details, see Section 4.4;
  - isonboundary a flag that marks if the current subset touches the boundary of another subset.
- elements an array of element structures, each of which has a:
  - ▶ pos the position of the element;
  - ▶ label the label attached to the element, e.g. "\$x\$" or "\$y\_0\$";
  - ► labelalign how to align the label when drawing the element;
- unitadjust a transform that converts from unit coordinates of the smooth object to the global user coordinates (see Section 4.5);
- hratios and vratios two arrays that determine where to draw cross sections in the cartesian mode. For details, see Section 4.7.3;
- isderivative similarly to subset, this field marks those smooth objects which are obtained from preexisting objects through operations of intersection, union, etc.;
- attached this field allows to bind an array of smooth objects to the current one. Drawing the current object will trigger drawing all of its attached objects. For example, the tangent space seen in Figure 2 is attached to the main object;
- drawextra a callback to be executed after the smooth object is drawn. It takes as parameters a drawing configuration of type dpar (see Section 5.5) and the current smooth object;
- static cache a global array of all smooth objects constructed so far. It is used mainly to search for smooth objects by label. See Section 4.6.

#### 4.2. Construction

Each of the four structures is equipped with a sophisticated **void** operator init that will infer as much information as possible. To construct a **smooth**, **hole**, or **subset**, it is only necessary to pass a **contour**. All other fields can be set in the constructor, but they are optional. To construct an **element**, it is only necessary to pass a **pos**, the **label** and **labelalign** fields have default values.

#### 4.3. Query and mutation methods

Already constructed structures can be queried and modified in a plethora of ways. Most methods return this at the end of execution for convenience.

#### 4.3.1. smooth objects

```
real xsize () { return xsize(this.contour); }
real ysize () { return ysize(this.contour); }
```

Calculate the vertical and horizontal size of this.

```
bool inside (pair x)
```

Check if x lies inside the contour of this, but not inside any of its holes.

```
smooth move (
    pair shift = (0,0),
    real scale = 1,
    real rotate = 0,
    pair point = this.center,
    bool readjust = true,
    bool drag = true
)
smooth shift (explicit pair shift)

smooth shift
(real xshift, real yshift = 0)

smooth scale (real scale)

smooth scale (real scale)
```

Scale this by scale (with center at point), rotate by rotate around point, and then shift by shift. If readjust is true, also recalculate the unitadjust field. If drag is true, also apply the move to all smooth objects attached to this. In the end return this. The shift, scale and rotate methods on the right are all specializations of the move method.

```
void xscale (real s)
```

Scale this by s along the x-axis.

```
smooth dirscale (pair dir, real s)
```

Scale this by s in the direction dir. Return this.

```
smooth setcenter (
    int index = -1,
    pair center = config.system.dummypair,
    bool unit = config.smooth.unit
)
```

Set the center of this if index == -1, and the center of this.subsets[index] otherwise. If unit is true, interpret center in the unit coordinates of this (i.e. apply this.unitadjust to center). For the definition of config.system.dummypair, see Section 5.1.

```
smooth setlabel (
   int index = -1,
   string label = config.system.dummystring,
   pair dir = config.system.dummypair,
   pair align = config.system.dummypair
)
```

Set the label, labeldir and labelalign of this if index == -1, and set these fields of this.subsets[index] otherwise. For the definition of config.system.dummystring, see Section 5.1.

```
smooth addelement (
   pair pos,
   string label = "",
   pair align = 1.5*S,
   int index = -1,
   bool unit = config.smooth.unit
)
smooth addelement (
   element elt,
   int index = -1,
   bool unit = config.smooth.unit
)
```

Add a new element to this. Return this. If index >= 0, then the function will additionally check if the element is contained within the contour of this.subsets[index]. If unit is true, then the position of the element is interpreted in this object's unit coordinates.

```
smooth setelement (
    int index,
    pair pos = config.system.dummypair,
    string label = config.system.dummystring,
    pair labelalign = config.system.dummypair,
    int sbindex = -1,
    bool unit = config.smooth.unit
)
```

Change the fields of the element of this at index index. Return this. Slightly different versions of this routine are also defined in the source code, feel free to peruse it.

```
smooth rmelement (int index)
```

Delete an element at index index. Return this.

```
smooth movelement (int index, pair shift)
```

Move the element at index index by shift. Return this.

```
smooth addhole (
                                              smooth addhole (
    path contour,
                                                  hole hl,
    pair center = config.system.dummypair,
                                                  int insertindex = this.holes.length,
    real[][] sections = {},
                                                  bool clip = config.smooth.clip,
                                                  bool unit = config.smooth.unit
    pair shift = (0,0),
    real scale = 1,
    real rotate = 0,
    pair point = center(contour),
    bool clip = config.smooth.clip,
    bool unit = config.smooth.unit
)
```

Add a new hole to this. If clip is true and the hole's contour is *not* contained within this object's contour, then clip this smooth object's contour using difference [page 7], like so:

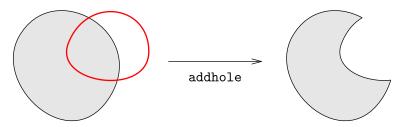


Figure 13: A showcase of the clip parameter

If unit is true, then the hole contour will be treated in the unit coordinates, i.e. the unitadjust transform will be applied to it. See Section 4.5 for more details.

```
smooth addholes (
                                              smooth addholes (
   hole[] holes,
                                                  path[] contours,
    bool clip = config.smooth.clip,
                                                  bool clip = config.smooth.clip,
    bool unit = config.smooth.unit
                                                  bool unit = config.smooth.unit
smooth addholes (
                                              smooth addholes (
    bool clip = config.smooth.clip,
                                                  bool clip = config.smooth.clip,
    bool unit = config.smooth.unit
                                                  bool unit = config.smooth.unit
    ... hole[] holes
                                                  ... path[] contours
```

Auxiliary routines made for conveniently adding multiple holes at the same time.

```
smooth rmhole (int index = this.holes.length-1)
```

Delete the hole under index index from this.

```
smooth rmholes (int[] indices)
smooth rmholes (... int[] indices)
```

Delete a number of holes from this.

```
smooth movehole (
   int index,
   pair shift = (0,0),
   real scale = 1,
   real rotate = 0,
   pair point = this.holes[index].center,
   bool movesections = false
)
```

Move the hole at index index by scaling and rotating it around point, and shifting it by shift. If movesections is true, the sections values of the hole are updated accordingly with the transform. This is only really necessary when rotate is non-zero.

```
smooth addsection (
   int index,
   real[] section = {}
)
smooth setsection (
   int index,
   int scindex = 0,
   real[] section = {}
)
smooth rmsection (
   int index =
   this.holes.length-1,
   int scindex = 0
)
```

Add, set or remove a section under scindex in the hole under index. When adding, the section will have to pass the

```
bool checksection (real[] section)
```

check.

```
smooth addsubset (
    subset sb,
    int index = -1,
    bool inferlabels = config.smooth.inferlabels,
    bool clip = config.smooth.clip,
    bool unit = config.smooth.unit,
    bool checkintersection = true
)
```

Add a new subset to this. The meaning of the arguments is as follows:

- sb the subset to add;
- index the index of another, preexisting subset of this, such that sb should be made a subset of this.subsets[index]. If index is -1, then sb is considered a toplevel subset until found otherwise by

containment checks. Essentially, the index parameter saves the algorithm some work figuring out where to fit sb in the subset hierarchy. See Section 4.4 for more explanation;

- inferlabels if set to true, the intersection subsets arising from the addition of sb will be given labels like "\$A \cap B\$", given that some subsets have labels "\$A\$" and "\$B\$";
- clip if set to false, this leads to an error whenever sb's contour is out of bounds with this object's contour. If clip is set to true, then sb's contour is clipped instead, and its isonboundary field is set to true:
- unit as usual, setting this to true leads to sb being interpreted in this object's unit coordinates, see Section 4.5:
- checkintersection if set to false, the routine will *not* perform out-of-bounds checks. This can significantly increase efficiency when the user is confident in the correctness of the call. But then you only have yourself to blame when your subsets are sticking out of your smooth objects!

```
smooth addsubset (
   int index = -1,
   path contour,
   pair center = config.system.dummypair,
   pair shift = (0,0),
   real scale = 1,
   real rotate = 0,
   pair point = center(contour),
   string label = "",
   pair dir = config.system.dummypair,
   pair align = config.system.dummypair,
   bool inferlabels = config.smooth.inferlabels,
   bool clip = config.smooth.clip,
   bool unit = config.smooth.unit
)
```

A convenience routine that creates the subset from given parameters and calls addsubset [page 16] on it.

```
smooth addsubsets (
                                              smooth addsubsets (
    subset[] sbs,
                                                  path[] contours,
    int index = -1,
                                                  int index = -1,
    bool inferlabels =
                                                  bool inferlabels =
config.smooth.inferlabels,
                                              config.smooth.inferlabels,
    bool clip = config.smooth.clip,
                                                  bool clip = config.smooth.clip,
    bool unit = config.smooth.unit
                                                  bool unit = config.smooth.unit
smooth addsubsets (
                                              smooth addsubsets (
    int index = -1,
                                                  int index = -1,
    bool inferlabels =
                                                  bool inferlabels =
config.smooth.inferlabels,
                                              config.smooth.inferlabels,
    bool clip = config.smooth.clip,
                                                  bool clip = config.smooth.clip,
    bool unit = config.smooth.unit
                                                  bool unit = config.smooth.unit
    ... subset[] sbs
                                                   ... path[] contours
```

Further convenience routines that allow adding multiple subsets.

```
smooth rmsubset (
   int index = this.subsets.length-1,
   bool recursive = true
)

smooth rmsubsets (
   int[] indices,
   bool recursive = true
)

// (... int[] indices)
```

Remove one or more subsets from this. If recursive is set to true, then all subsets of the removed subset shall also be removed.

```
smooth movesubset (
   int index = this.subsets.length-1,
   pair shift = (0,0),
   real scale = 1,
   real rotate = 0,
   pair point = config.system.dummypair,
   bool movelabel = false,
   bool recursive = true,
   bool bounded = true,
   bool clip = config.smooth.clip,
   bool inferlabels = config.smooth.inferlabels,
   bool keepview = true
)
```

Move the subset at index index (say, sb), scaling and rotating it around point, and then shifting it by shift. The meaning of the bool parameters is as follows:

- movelabel if set to true, the labeldir of sb is rotated with the subset itself;
- recursive if set to true, all subsets of sb are moved as well;
- bounded if set to true, the movement of sb is restricted by its subsets and supersets;
- clip if set to true, the contour of sb will be clipped if it becomes out-of-bounds as a result of the movement;
- inferlabels same as the corresponding parameter of the addsubset [page 16] function.

```
smooth attach (smooth sm)
```

Add the smooth object sm to the attached field of this. Return this.

```
smooth fit (
    int index = -1,
    picture pic = currentpicture,
    picture addpic,
    pair shift = (0,0)
)
```

Fit an entire picture pic into one of the subsets of this, namely one under index index. If index is -1, the picture is fit inside the contour of this.

```
smooth copy () smooth replicate (smooth sm)
```

Perform a deep copy of this and return this copy, or deeply copy all fields from another smooth object sm, returning this.

#### 4.3.2. subset objects

```
real xsize () { return xsize(this.contour); }
real ysize () { return ysize(this.contour); }
```

Calculate the vertical and horizontal size of this.

```
subset move (transform move)
```

Move this by applying move to its contour.

```
subset move (pair shift, real scale, real rotate, pair point, bool movelabel)
```

A more sophisticated version of move [page 18], which accepts the usual shift, scale, rotate, point arguments (see smooth.move [page 14]), and moves the subset's labeldir based on the movelabel flag.

```
subset copy () subset replicate (subset s)
```

Perform a deep copy of this and return the copy, or deeply copy all fields of another subset, s, into this, returning this.

#### 4.3.3. hole objects

```
hole move (transform move)
```

Move this by applying move to the hole's contour.

```
hole move (pair shift, real scale, real rotate, pair point, bool movesections)
```

A more sophisticated version of move [page 19], which accepts the usual shift, scale, rotate, point arguments (see smooth.move [page 14]), and rotates the sections of this (see Section 4.7.2) if the movesections flag is set.

```
hole copy () hole replicate (hole h)
```

Perform a deep copy of this and return the copy, or deeply copy all fields of another hole, h, into this, returning this.

#### 4.3.4. element objects

```
element move (transform move)
```

Move this by applying move to the element's contour.

```
element move (pair shift, real scale, real rotate, pair point, bool movelabel)
```

A more sophisticated version of move [page 19], which accepts the usual shift, scale, rotate, point arguments (see smooth.move [page 14]), and rotates this element's labeldir if the movelabel flag is set.

```
element copy () element replicate (element elt)
```

Perform a deep copy of this and return the copy, or deeply copy all fields of another element, elt, into this, returning this.

# 4.4. The subset hierarchy

In general, a system of subsets of a set can form a complicated network of intersections and inclusions. Consider the following example:

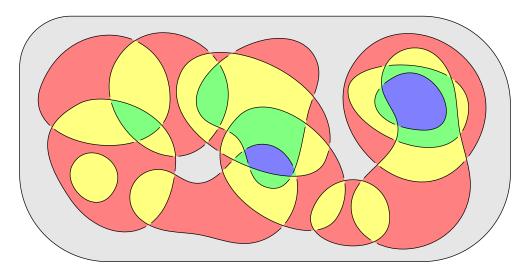


Figure 14: An example of many intersecting subsets

To manage this mess (and to be able to draw the diagram above in under 30 lines of code), smoothmanifold employs a hierarchy of subsets. This is achieved through every subset having a layer field which specifies how deep in the hierarchy it lies (in Figure 14 different layers are colored with different colors). Some points to note:

• The int[] subsets field of a subset sb structure contains all indices of subsets in the parent smooth object, that are direct subsets of sb;

• When adding a subset sb with smooth.addsubset [page 16], the algorithm automatically checks its intersections with all other subsets of the smooth object, creating additional subsets, and fits sb on the appropriate layer.

There are two internally important methods of smooth, related to the subset hierarchy:

```
bool onlyprimary (int index)
```

Determine if the subset of this at index index only contains "proper" subsets (that is, those that are not intersections of other subsets).

```
bool onlysecondary (int index)
```

Same as onlyprimary [page 20], but now check if all subsets of this.subsets[index] are intersections of other subsets.

You will not be able to move [page 18] a subset, if it contains both primary ("proper") and secondary subsets, since the situation becomes too complicated and I don't know how to resolve it algorithmically. This is the case because moving a subset should trigger a recalculation of the entire subset hierarchy, which is a generally difficult task.

#### 4.5. Unit coordinates in a smooth object

Sometimes, when working with a smooth object, it is easier not to think about where it is located in user coordinates, and assume that its center [page 12] is at (0,0), and its radius [page 9] is approximately 1. Module smoothmanifold supports a mechanism to allow this, namely the unitadjust [page 12] field of the smooth structure. It establishes a bridge between the object's "unit coordinates" and the global user coordinates. This field is calculated via

```
transform selfadjust ()
{ return shift(this.center)*scale(radius(this.contour)); }
```

Calculate the unit coordinates of this. See unitadjust [page 12] for reference.

The unit coordinates of a subset can also be obtained:

```
transform adjust (int index)
```

Calculate the unit coordinates of the subset of this at index index. If index is set to -1, the unitadjust field of this is used instead.

Now, any method that accepts a bool unit parameter, can accept pairs/paths in the parent object's unit coordinates, since it will convert them to global coordinates by applying unitadjust.

Another unit-related method of the smooth structure is

```
pair relative (pair point)
```

Convert point (given in unit coordinates) to a point in global coordinates.

#### 4.6. Reference by label

The global array smooth.cache [page 12] gives many opportunities, and one of them is reference by label. Given a string label, one can loop over the smooth.cache array and search for a smooth object with this label. Moreover, one can inspect the subsets and elements of these smooth objects, and compare their labels to label. In this way, one can obtain a smooth, subset, or element from their label. This gives rise to the following versions of the already familiar smooth methods:

```
smooth setcenter (
    string destlabel,
    pair center,
    bool unit = config.smooth.unit
) { return this.setcenter(findlocalsubsetindex(destlabel), center, unit); }
```

An alternative to setcenter page 14, but finds the subset by label.

```
smooth setlabel (
   string destlabel,
   string label,
   pair dir = config.system.dummypair,
   pair align = config.system.dummypair
) { return this.setlabel(findlocalsubsetindex(destlabel), label, dir, align); }
```

An alternative to setlabel page 14, but finds the subset by label.

```
smooth setelement (
    string destlabel,
    pair pos = config.system.dummypair,
    string label = config.system.dummystring,
    pair labelalign = config.system.dummypair,
    bool unit = config.smooth.unit
)
```

An alternative to setelement [page 15], but finds the element by label.

```
smooth rmelement (string destlabel)
```

An alternative to rmelement [page 15], but finds the element by label.

```
smooth movelement (string destlabel, pair shift)
```

An alternative to movelement [page 15], but finds the element by label.

```
smooth addsubset (
    string destlabel,
    subset sb,
    bool inferlabels = config.smooth.inferlabels,
    bool clip = config.smooth.clip,
    bool unit = config.smooth.unit
)
```

An alternative to addsubset [page 16], but finds the destination subset by label. The specialized versions of addsubset also have a label version.

```
smooth rmsubset (
   string destlabel,
   bool recursive = true
)

smooth rmsubsets (
   string[] destlabels,
   bool recursive = true
)

// (... string[] destlabels)
```

Label-based alternatives to rmsubset [page 17] and rmsubsets [page 17].

```
smooth movesubset (
    string destlabel,
    pair shift = (0,0),
    real scale = 1,
    real rotate = 0,
    pair point = config.system.dummypair,
    bool movelabel = false,
    bool recursive = true,
    bool bounded = true,
    bool clip = config.smooth.clip,
    bool inferlabels = config.smooth.inferlabels,
    bool keepview = true
)
```

A label-based alternative of movesubset page 18.

These are methods that facilitate the correct finding of objects by label:

```
static bool repeats (string label)
```

Check if label already exists as a label of some smooth, subset, or element object.

```
int findlocalsubsetindex (string label)
    int findlocalelementindex (string label)
```

Locate a subset of this by its label and return its index.

As a final step, module smoothmanifold defines a number of conversion routines to find objects by label:

```
smooth findsm (string label)
```

Find a smooth object by its label.

```
subset findsb (string label)
```

Find a subset by its label.

```
element findelt (string label)
```

Find an element by its label.

These routines rely on the following auxiliary internal functions:

```
int findsmoothindex (string label)
int[] findsubsetindex (string label)
int[] findelementindex (string label)
```

Inspect the smooth.cache array for label and return the relevant index/indices.

Up until recently module smoothmanifold supported three operator cast routines that could cast strings to smooth, subset, and element structures. However, I have recently realized that this may easily lead to ambiguity in function calls, and so now the module encourages the direct use of the findsm, findsb and findelt routines.

## 4.7. The modes of cross section drawing

Cross sections (as seen in Figure 2) are meant to create the illusion of 3D in a 2D diagram. They typically connect the contours of an object's holes with the contour of the object itself. These sections can be drawn in various modes. Compare:

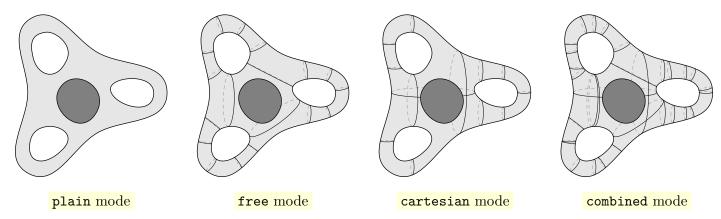


Figure 15: Different modes of drawing cross sections

We will now explain how each mode is implemented.

#### 4.7.1. The plain mode

This is the simplest mode — no sections at all. It is the default mode, since most of smoothmanifold diagrams (despite the name of the module) are purely 2D.

#### 4.7.2. The free mode

This mode makes use of the real[][] sections field of the hole [page 12] structure. Each member of this two-dimensional array is an array {d, a, n} of three real numbers, with the following meaning:

- d and a these numbers determine the region where the cross sections are to be drawn. This is done by calling range(g, ctr, dir(d), a) [page 10], where g is the contour of either the hole or the parent object, and ctr is the center of the hole;
- n the number of cross sections to draw. This is supposed to be an integer, and is converted to one with floor(n).

Consider the following example:

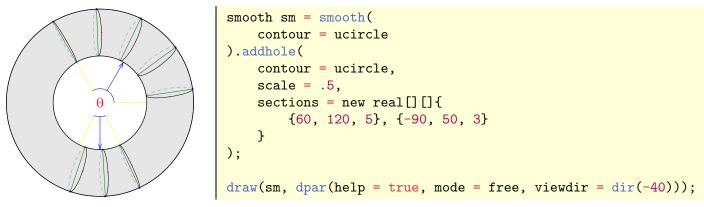


Figure 16: A showcase of the sections field of the hole structure and how it is used

(for an explanation of the dpar structure seen in the code in Figure 16, see Section 4.8). Now, as seen on the second picture in Figure 15, cross sections in free mode can connect not only the parent object's contour with the hole's contour, but also the contours of two holes. This is achieved through the int scnumber field of the hole [page 12] structure. It determines how many "inter-hole" sections a hole is willing to support with any other hole. If hl1 has hl1.scnumber = 4 and hl2 has hl2.scnumber = 2, then there will be 2 cross sections drawn between hl1 and hl2. In fact, there is a very neat trick. The expression to get the resulting number of holes is

```
abs(min(hl1.scnumber, hl2.scnumber))
```

meaning that you can set, for example, hll.scnumber = -3, and it will *force* the number of sections to be 3, regardless of the value of hl2.scnumber (unless it is also negative). In other words,

- setting hll.scnumber = -n guarantees that the number of sections is n or more;
- setting hll.scnumber = n guarantees that the number of sections is n or less;

The free mode is usually the preferred mode for three-dimensional drawing. Its implementation relies heavily on the following technical routines:

```
path[] sectionellipse (pair p1, pair p2, pair dir1, pair dir2, pair viewdir)
```

Return an array of two paths, together composing an ellipse whose center lies on p1 -- p2, such that both vectors dir1, dir2, when starting from p1 and p2 respectively, are tangent to the ellipse.

Figure 17: An illustration of the output of the sectionellipse function

The viewdir parameter represents "direction of view", it helps coordinate the tilt angles of all section ellipses in a picture to maintain the illusion of 3D.

This algorithm uses either an O(1) formula, if config.section.elprecision (see Section 5.3) is less than zero (which is true by default), or an  $O(\log n)$  binary search procedure, otherwise.

```
pair[][] sectionparams (path g, path h, int n, real r, int p)
```

Search for potential section positions between paths g and h, aiming to construct n sections. The meanings of r and p are:

- r ranges from 0 to 1, and can be interpreted as "freedom": when small, it restricts the section positions, but when large, the algorithm has more choice. The default value for r is captured by config.section.freedom (see Section 5.3);
- p controls precision. The bigger the value of p, the more precise the search, but the longer it takes.

The algorithm runs in O(n+p) time and produces an array of pair arrays, whose values can then be plugged into the sectionellipse [page 23] function.

```
void drawsections (picture pic, pair[][] sections, pair viewdir, bool dash, bool help,
bool shade, real scale, pen sectionpen, pen dashpen, pen shadepen)
```

Draw the cross sections specified in sections by calling the sectionellipse [page 23] function. The meanings of the rest of the parameters is as follows:

- viewdir passed to sectionellipse [page 23];
- dash, dashpen after obtaining a path[] array from sectionellipse, whether to draw its second member with dashpen;
- shade, shadepen whether to shade the region bounded by each ellipse with shadepen;
- help whether to draw auxiliary help information, e.g. mark all the parameters;
- scale an internal parameter that only matters when help is true;
- sectionpen the pen to draw the first member of the section ellipse with.

#### 4.7.3. The cartesian mode

This is the alternative mode of drawing cross sections, mainly implemented to draw three-dimensional smooth objects without any holes (note that the free mode relies on the presence of holes). For the cartesian mode, the real[] hratios and real[] vratios fields of the smooth [page 12] structure are used. These fields are completely similar, the only difference being that hratios deals with horizontal sections, where vratios deals with vertical. Both these arrays contain numbers ranging from 0 to 1, and are used as follows:

```
import contour;
smooth sm = smooth(
    contour = contour(<...>),
    hratios = new real[] {0.15, 0.5},
    vratios = new real[] {0.2, 0.6, 0.9}
);

draw(sm, dpar(mode = cartesian, viewdir = .7*dir(45)));
```

Figure 18: A showcase of the way the hratios and vratios fields are used

In other words, horizontal sections are drawn r of the way through sm's height for every r in sm.hratios, and vertical sections are drawn s of the way through sm's width for every s in sm.vratios. The mode is enabled by writing mode = cartesian in the dpar [page 25] structure.

The cartesian mode (so called because the sections are only vertical and horizontal) is implemented by means of the following technical routines:

```
real getyratio (real y)
real getxratio (real x)
real getypoint (real y)
real getxpoint (real x)
```

Convert to and from relative lengths.

```
smooth setratios (real[] ratios, bool horiz)
```

Set the horizontal/vertical Cartesian ratios of this smooth object.

```
pair[][] cartsectionpoints (path[] g, real r, bool horiz)
```

Construct an array of section points in g (which represents a contour and holes in it) at relative length r, either vertically or horizontally, depending on horiz.

```
pair[][] cartsections (path[] g, path[] avoid, real r, bool horiz)
```

A more refined version of cartsectionpoints [page 25], which performs additional tests and selects suitable sections.

```
void drawcartsections (picture pic, path[] g, path[] avoid, real y, bool horiz, pair
viewdir, bool dash, bool help, bool shade, real scale, pen sectionpen, pen dashpen, pen
shadepen)
```

A wrapper drawing function for the cartesian mode, which calls cartsections [page 25] and passes the result to drawsections [page 24], along with other arguments.

Besides, the final section ellipses are, of course, still calculated via the sectionellipse [page 23] function.

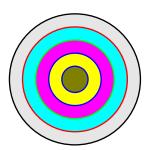
#### 4.7.4. The combined mode

As seen in Figure 15, the combined mode combines both free and cartesian modes together, drawing all sections at once. Maybe, sometimes this is useful.

#### 4.8. The dpar drawing configuration structure

You may have noticed that the smooth [page 12] structure contains no information about how to draw a smooth object (although historically it did). Now, all of this information is isolated into a separate structure called dpar (short for "drawing parameters"), which has the following fields:

- pen contourpen the pen used to draw the contour of the smooth object, as well as those of its holes and subsets;
- pen smoothfill the pen used to fill the smooth object's interior;
- pen[] subsetcontourpens a list of pens to draw subset contours with (by layer). Subsets on layer 0 will be drawn with subsetcontourpens[0], etc. If the array is empty, then contourpen will be used instead for all layers. If the number or layers is larger than the length of subsetcontourpens, then the last member of the array will be used for all subsequent layers that are not covered;
- pen[] subsetfill similarly, a list of pens to use to fill different layers of subsets. If the array is empty, then lightened versions of the corresponding subsetcontourpens pens are used instead. If some layers are not covered by subsetfill, then the last member of the array is used, getting progressively darker. Consider the following example:



```
smooth sm = smooth(
    contour = ucircle
).addsubsets(<...>);

draw(sm, dpar(
    subsetcontourpens = new pen[] {red, green, blue},
    subsetfill = new pen[] {cyan, magenta, yellow}
));
```

Figure 19: A showcase of the interpretation of subsetcontourpens and subsetfill

- pen sectionpen the pen used to draw cross sections (their visible parts);
- pen dashpen the pen used to draw the "invisible" (dashed) parts of cross sections;
- pen shadepen the pen used to fill the section ellipses;
- pen elementpen the pen used to dot the elements of the smooth object;
- pen labelpen the pen used to label the label of the smooth object;
- pen[] elementlabelpens pens used to label the labels of the smooth object's elements. If the array is empty, then labelpen is used for all elements. If there are more elements than the length of elementlabelpens, then the last member of the array is used for all elements not covered;
- pen[] subsetlabelpens pens used to label the labels of the smooth object's subsets. labelpen is used in case subsetlabelpens is empty. All subsets not covered by the array use the last member thereof:
- int mode the drawing mode. Can be one of the four: plain, free, cartesian, combined (which have values of 0, 1, 2, 3 respectively). Any other integer value would be accepted, but the consequences may be unpredictable;
- pair viewdir the viewdir parameter to pass to the sectionellipse [page 23] function;
- bool drawlabels whether to draw the label of the smooth object as well as those of its subsets and elements;
- bool fill whether to fill the region bounded by the contour of the smooth object;
- bool fillsubsets whether to fill the subsets of the smooth object;
- bool drawcontour whether to draw the smooth object's contour;
- bool drawsubsetcontour whether to draw the contours of subsets;
- int subsetcovermode the covermode to pass to fitpath [page 5] when drawing the contours of subsets;
- bool help whether to enable additional information being drawn with the smooth object. Useful for debugging;
- bool dash the dash parameter to pass to drawsections [page 24] or drawcartsections [page 25];
- bool shade the shade parameter to pass to drawsections [page 24] or drawcartsections [page 25];
- bool avoidsubsets whether to avoid drawing cross sections that intersect with the smooth object's subsets. You can see that on the diagram on the title page of this document, this option was disabled;
- bool overlap the overlap parameter to pass to fitpath [page 5];
- bool drawnow the drawnow parameter to pass to fitpath [page 5];
- bool drawextraover whether to apply the drawextra function of the smooth object "over" everything else (that is, after drawing the object itself). In other words, if drawextraover is false, then the drawextra will be called in the beginning of drawing the smooth object, otherwise in the end.

These are all the fields of dpar. The structure has a comprehensive void operator init constructor where all fields are given default values from the config.drawing [page 33] global configuration structure. The dpar structure also supports a method

```
dpar subs (
    pen contourpen = this.contourpen,
    pen smoothfill = this.smoothfill,
    <...>
)
```

which replaces some of the fields of this with new values.

Besides, there are two conveniently defined dpar instances:

```
dpar ghostpar (pen contourpen = currentpen)
```

A dpar to draw a faint outline of a smooth object.

```
dpar emptypar ()
```

A dpar that doesn't draw any contours or fill any regions.

#### 4.9. The draw function

One of the central functions of module smoothmanifold is the draw function which allows one to draw a smooth object:

```
void draw (
    picture pic = currentpicture,
    smooth sm,
    dpar dspec = null
)
```

Draw sm on picture pic, with drawing configuration dspec. This function follows all the drawing protocols described previously in Section 4.4, Section 4.7 and Section 4.8.

Moreover, there are overloaded versions of draw:

```
void draw (
   picture pic = currentpicture,
   smooth[] sms,
   dpar dspec = null
)
void draw (
   picture pic = currentpicture,
   dpar dspec = null
   ... smooth[] sms
)
```

#### 4.10. Set operations on smooth objects

Nobody asked, but module smoothmanifold implements a few very complicated functions dedicated to calculating unions and intersections of smooth objects.

```
smooth[] intersection (
    smooth sm1,
    smooth sm2,
    bool keepdata = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff,
    bool addsubsets = config.smooth.addsubsets
)
smooth[] intersection (
    smooth[] sms,
    bool keepdata = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff,
    bool addsubsets = config.smooth.addsubsets
)
// (... smooth[] sms)
```

Calculate the intersection of two or more smooth objects. The round and roundcoeff parameters are passed to the intersection [page 9] function. If keepdata is set to true, then references to old hole and subset objects will be used in the construction of the new smooth object. If addsubsets is set to true, the function will try to move the subsets of the given smooth objects to their intersection.

For convenience, intersection is available as an operator:

```
smooth[] operator ^^ (smooth sm1, smooth sm2)
{ return intersection(sm1, sm2); }
```

Furthermore, there is a specialized routine which only return one smooth object:

```
smooth intersect (
    smooth[] sms,
    bool keepdata = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff,
    bool addsubsets = config.smooth.addsubsets
)
// (... smooth[] sms)
```

Apply intersection [page 27] and return the 0-th element of the resulting smooth[] array. If the array is empty, raise an error. If the array contains more than one object, give a warning. See Section 6 for details on errors and warnings.

For intersect there is also an operator version:

```
smooth operator ^ (smooth sm1, smooth sm2)
{ return intersect(sm1, sm2); }
```

Likewise, there are similarly defined union and unite routines:

```
smooth[] union (
    smooth sm1,
    smooth sm2,
    bool keepdata = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff
)
smooth[] union (
    smooth[] sms,
    bool keepdata = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff
)
// (... smooth[] sms)
```

Calculate the union of one or more smooth objects. The meanings of round, roundcoeff and keepdata are as in intersection [page 27].

```
smooth[] operator ++ (smooth sm1, smooth sm2)
{ return union(sm1, sm2); }
```

An operator version of union.

```
smooth unite (
    smooth[] sms,
    bool keepdata = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff
)
// (... smooth[] sms)
```

A specialized version of union which returns only one smooth object. An error/warning is raised if the resulting smooth[] array contains any number of elements other than 1.

```
smooth operator + (smooth sm1, smooth sm2)
{ return unite(sm1, sm2); }
```

An operator version of unite.

#### 4.11. Drawing arrows and paths

One of many crucial features of module smoothmanifold is the ease with which arrows can be drawn between smooth objects, their subsets or elements. In plain Asymptote one can easily draw an arrow between two points, but not between two areas. This is mainly what the drawarrow routine takes care of.

```
void drawarrow (
   picture pic = currentpicture,
    smooth sm1 = null,
    int index1 = config.system.dummynumber,
    pair start = config.system.dummypair,
    smooth sm2 = sm1,
    int index2 = config.system.dummynumber,
    pair finish = config.system.dummypair,
    bool elements = false,
    real curve = 0,
    real angle = 0,
    real radius = config.system.dummynumber,
    bool reverse = false,
    pair[] points = {},
   Label L = "",
    pen p = currentpen,
    tarrow arrow = config.arrow.currentarrow,
    tbar bar = config.arrow.currentbar,
    bool help = config.help.enable,
    bool overlap = config.drawing.overlap,
    bool drawnow = config.drawing.drawnow,
    real beginmargin = config.arrow.mar,
    real endmargin = config.system.dummynumber
```

Draw an arrow. The routine is quite sophisticated in that it accepts many different types of arguments. You can start the arrow from:

- The sm1 object;
- A subset of the sm1 object, under index index1;
- An arbitrary point start.

Likewise, you can finish the arrow at:

- The same object sm1 (by default), getting a cyclic arrow;
- The same sm1, but different subset, under index index2;
- A different smooth object, sm2, or its subset under index2;
- An arbitrary point finish.

The meaning of the remaining arguments is as follows:

- elements if set to true, then index1 and index2 will be treated as element indices instead of subset indices;
- curve for non-cyclic arrows, this argument is passed to the curvedpath [page 10] function;
- angle and radius for cyclic arrows, these arguments are passed to the cyclepath [page 10] function;
- reverse whether the arrow should be reversed;
- points an array of arbitrary points that the arrow should pass through. If this array is non-empty, the connect [page 11] function is used instead of curvedpath [page 10] or cyclepath [page 10];
- L the label to attach to the arrow;
- p the pen to draw the arrow with;
- arrow and bar the arrow and bar to use with the arrow. Since drawarrow is integrated with smoothmanifold's deferred drawing system, the custom tarrow [page 4] and tbar [page 4] structures are used here:
- help if set to true, addition help/debug information will be drawn;
- overlap and drawnow these arguments are passed to fitpath page 5 together with arrow and bar;

• beginmargin and endmargin — the margins left at the beginning and end. If endmargin is not specified, beginmargin is used instead.

For the definitions of the default values of drawarrow's parameters, see Section 5.

There is a specialized overloaded version of drawarrow:

```
void drawarrow (
    picture pic = currentpicture,
    string destlabel1,
    string destlabel2 = destlabel1,
    real curve = 0,
    <...>
)
```

A label-based version of drawarrow. It automatically detects if the labels belong to smooth objects/subsets/elements, and passes appropriate arguments to drawarrow [page 29].

Now, apart from arrows, one may want to draw a path connecting two points. This may be done with the drawpath routine:

```
void drawpath (
   picture pic = currentpicture,
    smooth sm1,
    int index1,
    smooth sm2 = sm1,
    int index2 = index1,
    real range = config.paths.range,
    real angle = config.system.dummynumber,
    real radius = config.system.dummynumber,
    bool reverse = false,
    pair[] points = {},
   Label L = "",
   pen p = currentpen,
    bool help = config.help.enable,
    bool random = config.drawing.pathrandom,
    bool overlap = config.drawing.overlap,
    bool drawnow = config.drawing.drawnow
)
```

Draw a surface path connecting sm1.elements[index1] and sm2.elements[index2]. By default, sm1 and sm2 coincide. All remaining arguments have the same meaning as in drawarrow [page 29], except for two:

- range this value is passed to randomdir [page 11] as angle;
- random if set to true, then the randompath [page 11] routine will be used for the path, instead of connect [page 11] or cyclepath [page 10].

Similarly to drawarrow, there is a label-based version of drawpath:

```
void drawpath (
   picture pic = currentpicture,
   string destlabel1,
   string destlabel2 = destlabel1,
   real range = config.paths.range,
   <...>
)
```

Draw a surface path between elements with labels destlabel1 and destlabel2.

# 5. Global configuration and the config structure

Throughout the document, we have seen references to a global **config** structure instance. It is defined as follows:

```
struct globalconfig {
    systemconfig system;
    pathconfig paths;
    sectionconfig section;
    smoothconfig smooth;
    drawingconfig drawing;
    helpconfig help;
    arrowconfig arrow;
}
private globalconfig defaultconfig;
globalconfig config;
```

The defaultconfig instance contains all default values, while config contains all *current* values, which can be changed directly at any time in the Asymptote code. Functions and methods feature default argument values that borrow from config, never defaultconfig. This way, a convenient configuration system is created, where all functions are aware of the flexible current config, and the defaults can be easily restored by deeply copying defaultconfig to config, by means of the

```
void defaults ()
```

function. We will now define in detail the member structures of config.

# 5.1. System variables

```
struct systemconfig {
    string version = "v6.3.1";
    int dummynumber = -10000;
    string dummystring = (string) dummynumber;
    pair dummypair = (dummynumber, dummynumber);
    bool repeatlabels = false;
    bool insertdollars = false;
}
```

A structure containing system configuration variables. Their meanings are as follows:

- version the version of smoothmanifold, currently 6.3.1;
- dummynumber the number that "the program knows what to do with". It is often given as a default value in many functions, when the true default value requires additional computations that are better done in the body of the function. A shorthand dn is defined for it, for convenience;
- dummypair and dummystring versions of dummynumber with different types. Module smoothmanifold features four helper functions to check if a value is "dummy":

```
| bool dummy (int n) | bool dummy (real r) | bool dummy (pair p) | bool dummy(string s)
```

- repeatlabel whether to allow different objects to share the same label. If set to false, an error (see Section 6) will be raised on attempt to bestow an already existent label;
- insertdollars whether to automatically insert \$ characters around all labels (including those passed to drawarrow [page 29] and drawpath [page 30]) right before drawing them. This is useful, but disabled by default to avoid confusion.

#### 5.2. Path variables

```
struct pathconfig {
    real roundcoeff = .03;
    real range = 30;
    real neighheight = .05;
    real neighwidth = .01;
}
```

A structure containing global path-related variables. The meaning of the fields is as follows:

• roundcoeff — default value to pass to combination [page 7] and its derivatives;

- range default value to pass to drawpath [page 30];
- neighheight default value to pass to neighbre [page 12] as h;
- neighwidth default value to pass to neigharc [page 12] as w;

#### 5.3. Cross section variables

```
struct sectionconfig {
    real maxbreadth = .65;
    real freedom = .3;
    int precision = 20;
    real elprecision = -1;
    bool avoidsubsets = false;
    real[] default = new real[] {-10000,235,5};
}
```

A structure to hold cross section-related configuration. The meanings of the fields are as follows:

• maxbreadth — bound on how wide dir1 and dir2 can be spread in sectionellipse [page 23] (see Figure 17). There are two technical routines dedicated to controlling the "quality" of cross sections:

```
real sectionsymmetryrating (pair p1p2, pair dir1, pair dir2)
bool sectiontoobroad (pair p1, pair p2, pair dir1, pair dir2)
```

- freedom the default value to pass to the sectionparams [page 24] function as r;
- precision the default value to pass to sectionparams [page 24] as p;
- elprecision the default precision for the ellipsepath [page 10] binary search algorithm. Set to -1 by default, to use the O(1) formula;
- avoidsubsets the default value for the avoidsubsets field of the dpar [page 25] structure;
- default the default section array used to substitute missing values in addsection [page 16] and its related methods.

## 5.4. Smooth object variables

```
struct smoothconfig {
    int interholenumber = 1;
    real interholeangle = 25;
    real maxsectionlength = -1;
    real rejectcurve = .15;
    real edgemargin = .07;
    real stepdistance = .15;
    real nodesize = 1;
    real maxlength;
    bool inferlabels = true;
    bool addsubsets = true;
    bool correct = true;
    bool clip = false;
    bool unit = false;
    bool setcenter = true;
}
```

A structure to hold all smooth object-related variables, whose meanings are as follows:

- interholenumber the default value for the scnumber field in the hole page 12 structure;
- interholeangle this value gets passed to the range [page 10] function as ang, when drawing sections between holes:
- maxsectionlength the maximum length of a section. A value of -1 means no restriction. Setting this value may help get rid of some annoying sections that look bad because they are too big;
- rejectcurve this value is passed to curvedpath [page 10] when constructing curves to determine which inter-hole sections to draw and which not to. This is done by checking if the curves intersect with any holes or subsets;
- edgemargin no point in explaining, let this one remain a mystery. If you REALLY need to know what this does, go see the source code...

- stepdistance same;
- nodesize the default value of the size parameter in the node [page 36] function;
- maxlength a parameter dependent on maxsectionlength, should not be set manually;
- inferlabels the default value of the inferlabels parameter passed to addsubset [page 16] and its derivatives;
- addsubsets the default value to pass to the intersection [page 27] function and its derivatives;
- correct whether non-clockwise paths should be reversed to clockwise. This value is passed as default in set operations with paths (see Section 3.1);
- clip the default value passed to the addsubset [page 16], addhole [page 15], movesubset [page 18] and their derivatives, as the clip parameter;
- unit whether to use unit coordinates (see Section 4.5). This is the default value of the unit parameter in all methods that accept it;
- setcenter whether to automatically set the centers of various objects in various situations by calling center [page 9] on their contour.

# 5.5. Drawing-related variables

```
struct drawingconfig {
   pair viewdir = (0,0);
   real viewscale = 0.12;
    real gaplength = .05;
    pen smoothfill = lightgrey;
    pen[] subsetfill = {};
    real sectpenscale = .6;
    real elpenwidth = 3.0;
    real shadescale = .85;
    real dashpenscale = .4;
    real dashopacity = .4;
    real attachedopacity = .8;
    real subpenfactor = .5;
    real subpenbrighten = .5;
    pen sectionpen = nullpen;
    real lineshadeangle = 45;
    real lineshadedensity = 0.15;
    real lineshademargin = 0.1;
    pen lineshadepen = lightgrey;
    int mode = 0;
    bool useopacity = false;
    bool dash = true;
    bool underdashes = false;
    bool shade = false;
    bool drawlabels = true;
    bool fill = true;
    bool fillsubsets = true;
    bool drawcontour = true;
    bool drawsubsetcontour = true;
    int subsetcovermode = 0;
    bool pathrandom = false;
    bool overlap = false;
    bool drawnow = false;
    bool drawextraover = false;
    bool subsetoverlap = false;
    real elementcirclerad = -1;
}
```

A structure to hold drawing-related configuration, encoded in the following variables:

• viewdir, smoothfill, subsetfill, sectionpen, mode, dash, shade, drawlabels, fill, fillsubsets, drawcontour, drawsubsetcontour, subsetcovermode, overlap, drawnow, drawextraover — default values of the corresponding dpar [page 25] fields;

- viewscale a value by which the viewdir vector is scale on call of the draw [page 27] function;
- gaplength the default length of the gaps left in deferredPath [page 4] objects when the fitpath [page 5] function is called;
- sectpenscale determines how thinner the section pen is compared to contourpen;
- elpenwidth the width of the dot's representing a smooth object's elements, used when calling draw [page 27]. The relevant pen creation utility is

```
pen elementpen (pen p) { return p + linewidth(config.drawing.elpenwidth); }
```

- shadescale how darker shaded section ellipses are compared to object filling color. This is relevant if the shade flag is set to true;
- dashpenscale how lighter dashed lines (in cross section drawing) are compared to regular lines;
- dashopacity default opacity of dashed pens;
- attachedopacity the opacity used to draw smooth objects attached [page 12] to the one currently being drawn;
- subpenfactor how darker the fill color for subsets get with each layer. See Section 4.8 and Figure 19;
- subpenbrighen how brighter to make the fill color of a subset than its contour color. The relevant pen creation routines are

```
pen brighten (pen p, real coeff) { return inverse(coeff * inverse(p)); }
pen nextsubsetpen (pen p, real scale) { return scale * p; }
```

- lineshadeangle, lineshadedensity, lineshademargin, lineshadepen default values passed to the shaderegion [page 40] function;
- useopacity whether to use Asymptote's opacity function for generating pens (primarily dashed section pens). Since some image formats do not support opacity, this is disabled by default, and so the dashpenscale field is used for dashed pen creation. Otherwise, the dashopacity field is used. The relevant pen creation routines are

```
pen sectionpen (pen p)
pen dashpenscale (pen p)
    { return inverse(config.drawing.dashpenscale*inverse(p))+dashed; }
pen dashopacity (pen p) { return p+dashed+opacity(config.drawing.dashopacity); }
pen dashpen (pen p)
pen shadepen (pen p) { return config.drawing.shadescale*p; }
pen underpen (pen p) { return dashpen(p); }
```

- underdashes whether to draw the "demoted" parts of a deferredPath [page 4] in a dashed line, instead of erasing them;
- pathrandom the default value passed to the drawpath [page 30] function as random;
- elementcirclerad the radius to use when drawing elements as circle's instead of dot's. This exists because sometimes dots are not showing up in SVG output, in which case the simplest thing to do is say screw it and fill a circle instead of calling the dot function.

# 5.6. Help-related variables

```
struct helpconfig {
   bool enable = false;
   real arcratio = 0.2;
   real arrowlength = .2;
   pen linewidth = linewidth(.3);
}
```

A structure to hold the few help-related variables, namely

- enable whether to enable auxiliary drawing by default;
- arcratio the relative radius of the blue arcs seen near the center of the hole in Figure 16, it may be useful to tweak if the arc covers the number in the center of the hole;
- arrowlength the length of auxiliary arrows drawn by the sides of cross sections when help = true. A value of -1 will disable these arrows (like in Figure 16);
- linewidth the pen containing the line width to draw help lines with.

#### 5.7. Arrow variables

```
struct arrowconfig {
    real mar = 0.03;
    tarrow currentarrow = null;
    tbar currentbar = null;
    bool absmargins = true;
}
```

A structure to hold variables related to arrows, namely the following:

- mar the default arrow margin that is passed as the default value to the beginmargin and endmargin parameters of the drawarrow [page 29] function;
- currentarrow, currentbar the default values of the arrow and bar parameters of drawarrow [page 29]; The currentarrow value is updated after the definition of DeferredArrow [page 5]:

```
config.arrow.currentarrow = DeferredArrow(SimpleHead);
```

• absmargins — whether arrow margins should be absolute, as opposed to being relative to the length of the arrow.

# 6. Debugging capabilities

In case an algorithm runs into an incorrect situation or is given incorrect input, mechanisms are put in place in module smoothmanifold to trigger an *error* (subsequently stopping execution) or a *warning* (while continuing execution). For errors, the relevant routine is

```
void halt (string msg) {
    write();
    write("> ! " + msg);
    abort("");
}
```

Warnings are simply written with a direct call to write.

# 7. Miscellaneous auxiliary routines

#### 7.1. smooth-related functions

```
smooth[] concat (smooth[][] smss)
```

Concatenate an array of smooth objects. In Asymptote, it is difficult to write a polymorphic concat function.

```
void print (smooth sm)
```

Print various information about the smooth object sm in the console.

```
void printall ()
```

Print all smooth objects in the global smooth.cache array.

```
void smooth.checksubsetindex (int index, string fname)
```

Check if this has a subset at index index. The fname parameter is used for debugging purposes – it contains the name of the function that is calling checksubsetindex.

```
void smooth.checkelementindex (int index, string fname)
```

Check if this has a element at index index. The fname parameter is used for debugging purposes – it contains the name of the function that is calling checkelementindex.

```
smooth[] drawintersect (
    picture pic = currentpicture,
    smooth sm1,
    smooth sm2,
    string label = config.system.dummystring,
    pair labeldir = config.system.dummypair,
    pair labelalign = config.system.dummypair,
    bool keepdata = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff,
    pair shift = (0,0),
    dpar dspec = null
)
```

Draw the intersection [page 27] of sm1 and sm2 and return it, while also drawing the faint silhouettes of sm1 and sm2 themselves. Remaining arguments:

- label, labeldir and labelalign these are passed as fields to the intersection object(s);
- round and roundcoeff passed to intersection [page 9]
- shift allows to additionally shift the involved objects.

The drawintersect function has overloaded versions that accept smooth[] and ... smooth[] arguments.

```
smooth node (
    string label,
    pair pos = (0,0),
    real size = config.smooth.nodesize
)
```

Produce a smooth object with label label that can be used as a node in a commutative diagram [page 36]. The object will be positioned as pos and have the size size. Moreover, there is a special dpar instance for drawing nodes:

```
dpar nodepar (pen labelpen = currentpen)
```

```
void drawcommuting (
   picture pic = currentpicture,
   smooth[] sms,
   real size = config.smooth.nodesize*.5,
   pen p = currentpen,
   bool direction = CW
)
```

Draw a "commutative diagram symbol" between the objects in the sms array (all presumably generated by node [page 36]), like so:

```
config.system.insertdollars = true;
smooth a = node("A", pos = (0,0));
smooth fa = node("F(A)", (5,2));
smooth g = node("\forall G", (4,-3));

draw(a, fa, g, dspec = nodepar());
drawarrow(a, fa, L = Label("\varphi", align = Relative(W)));
drawarrow(g, a, L = Label("\forall f", align = Relative(W)));
drawarrow(g, fa, p = dashed, L = Label("\exists!", align = Relative(E)));
drawcommuting(g, a, fa, size = .7);
```

Figure 20: A showcase of the drawcommuting function

```
element[] elementcopy (element[] elements)
```

Deeply copy an array of element structures.

```
hole[] holecopy (hole[] holes)
```

Deeply copy an array of hole structures.

```
subset[] subsetcopy (subset[] subsets)
```

Deeply copy an array of subset structures.

```
subset[] subsetintersection (
    subset sb1,
    subset sb2,
    bool inferlabels = config.smooth.inferlabels
)
```

Calculate the intersection of two subsets by applying intersection [page 8] and automatically setting other subset [page 12] fields.

```
void subsetdelete (subset[] subsets, int index, bool recursive)
```

Properly delete entry under index from the subsets array.

```
int[] subsetgetlayer (subset[] subsets, int[] range, int layer)
```

Fetch those elements of subsets, which have layer layer, and return their indices. Moreover, these indices are restricted to the elements of range.

```
int[] subsetgetall (subset[] subsets, subset s)
int[] subsetgetall (subset[] subsets, int index)
{ return subsetgetall(subsets, subsets[index]); }
```

Get all descendants (subsets) of subset s (or subset subsets[index]) in the array subsets.

```
int[] subsetgetallnot (subset[] subsets, subset s)
{ return difference(sequence(subsets.length), subsetgetall(subsets, s)); }
int[] subsetgetallnot (subset[] subsets, int index)
{ return difference(sequence(subsets.length), subsetgetall(subsets, index)); }
```

Return the indices of all subsets in subsets, which are not subsets of s.

```
void subsetdeepen (subset[] subsets, subset s)
```

Descend s one layer deeper, and patch subsets accordingly, so that the subset hierarchy is properly kept.

```
int subsetinsertindex (subset[] subsets, int layer)
```

Calculate the index at which a new subset on layer layer should be inserted.

```
int subsetmaxlayer (subset[] subsets, int[] range)
```

Calculate the maximum layer that subsets in subsets with indices in range occupy.

```
void subsetcleanreferences (subset[] subsets)
```

Clean up the subsets [page 12] fields of all subsets in subsets.

```
int[] findbylabel (string label)
```

A fully general label identification function that returns an index path to either a smooth object or its subset/element with a label matching label.

```
path[] holecontours (hole[] h)
{ return sequence(new path (int i){return h[i].contour;}, h.length); }
```

Return the contours of an array of hole objects.

```
void phantom (picture pic = currentpicture, smooth sm)
```

Inspired by  $T_EX$ 's \phantom commands, this takes the space on the plane that sm would take, without actually drawing it.

```
smooth rn (
   int n,
   pair labeldir = (.5,1),
   pair shift = (0,0),
   real scale = 1,
   real rotate = 0,
   bool drawnow = false
)
```

Construct an  $\mathbb{R}^n$  representation as a smooth object. This mainly utilizes the drawextra [page 12] field to draw the axes. The n parameter controls the n in  $\mathbb{R}^n$ , all the rest are passed to smooth, except for drawnow which is passed to fitpath [page 5]

```
dpar rnpar ()
```

The dpar instance to draw rn [page 38] smooth objects.

```
smooth samplesmooth (int type, int num = 0, string label = "")
smooth sm (int type, int num = 0, string label = "") = samplesmooth;
```

Produce a predefined smooth object. The type parameter determines the number of holes, and num — the index of the object inside its type. label will be attached to the resulting object. The sm function is a convenience shorthand.

```
smooth tangentspace (
    smooth sm,
    int hlindex = -1,
    pair center = config.system.dummypair,
    real angle,
    real ratio,
    real size = 1,
    real rotate = 45,
    string eltlabel = "x",
    pair eltlabelalign = 1.5*S
)
```

Construct a tangent space at a point on sm, and attach it to sm.

- The point is determined by hlindex (an index of sm's hole, a value of -1 means no hole), angle, center (determined automatically by default), and ratio.
- The rotate parameter can be used to rotate the tangent space.
- The eltlabel and eltlabelalign parameters are passed to the element generated at the point where the tangent space is constructed. For a showcase of the tangentspace function, see Figure 2.

#### 7.2. Array utilities

```
path[] c (... path[] source) { return source; }
path[][] dc (... path[][] source) { return source; }
path[][] cc (... path[] source) { return new path[][]{source}; }
```

R-style convenience functions for paths, for those who are tired of writing new path[].

```
real[] r (... real[] source) { return source; }
real[][] dr (... real[][] source) { return source; }
real[][] rr (... real[] source) { return new real[][]{source}; }
```

R-style convenience functions for reals, for those who are tired of writing new real[].

```
pair[] p (... pair[] source) { return source; }
pair[][] dp (... pair[][] source) { return source; }
pair[][] pp (... pair[] source) { return new pair[][]{source}; }
```

R-style convenience functions for pairs, for those who are tired of writing new pair[].

```
int[] i (... int[] source) { return source; }
int[][] di (... int[][] source) { return source; }
int[][] ii (... int[] source) { return new int[][]{source}; }
```

R-style convenience functions for integers, for those who are tired of writing new int[].

```
string[] s (... string[] source) { return source; }
string[][] ds (... string[][] source) { return source; }
string[][] ss (... string[] source) { return new string[][]{source}; }
```

R-style convenience functions for strings, for those who are tired of writing new string[].

```
pair[] concat (pair[][] a)
```

Concatenate an array of pair.

```
path[] concat (path[][] a)
```

Concatenate an array of path.

```
bool contains (int[] source, int a)
```

Check if source contains a.

```
int[] difference (int[] a, int[] b)
```

Calculate the set difference of two arrays of integers.

#### 7.3. Other routines

```
pair comb (pair a, pair b, real t) { return t*b + (1-t)*a;}
```

A convex combination between a and b with time t.

```
transform dscale (real scale, pair dir, pair center = (0,0))
```

Return a transform that scales by scale in direction dir, with center in center.

```
bool inside (real a, real b, real c)
{ return (a <= c && c <= b); }</pre>
```

Determine if c lies in the segment [a,b].

```
path[] intersection (
    path p,
    path q,
    path[] holes,
    bool correct = true,
    bool round = false,
    real roundcoeff = config.paths.roundcoeff
)
```

A version of intersection [page 8], but it subtracts all members of holes from the intersection of p and q, using difference [page 7].

```
pen inverse (pen p)
```

Derive the "inverse" or "negative" pen from p.

```
real mod (real a, real b)
```

Calculate a modulo b by subtracting b until the result falls between 0 and b.

```
string mode (int md)
```

Convert an integer mode (see Section 4.7) value into its string representation. E.g., mode (0) = "plain". Historic side note: in early versions of smoothmanifold, the mode parameter was a string, but I have later found it excessive and inconvenient.

```
path pop (path[] source)
```

Remove the 0-th element of source and return it.

```
real round (real a, int places) { return floor(10^places*a)*.1^places; }
pair round (pair a, int places) { return (round(a.x, places), round(a.y, places)); }
```

Round a to the places number of decimal places.

```
string repeatstring (string str, int n)
```

Produce a string that repeats str n times.

```
transform srap (real scale, real rotate, pair point)
{ return shift(point)*scale(scale)*rotate(rotate)*shift(-point); }
```

[S]cale [R]otate [A]round [P]oint.

```
void shaderegion (
    picture pic = currentpicture,
    path g,
    real angle = config.drawing.lineshadeangle,
    real density = config.drawing.lineshadedensity,
    real mar = config.drawing.lineshademargin,
    pen p = config.drawing.lineshadepen
)
```

Shade the region bounded by g with straight lines, like so:

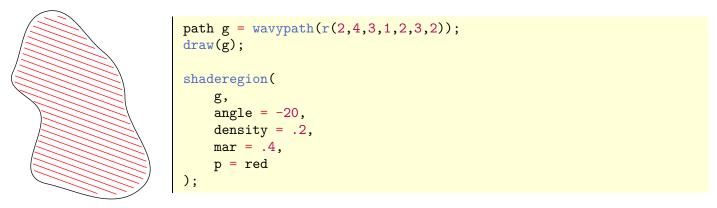


Figure 21: A showcase of the shaderegion function

```
real[] unitseq (real step)
```

Calculate a uniform partition of the unit segment with step step.

```
real xsize (picture p) { return xpart(max(p)) - xpart(min(p)); }
real ysize (picture p) { return ypart(max(p)) - ypart(min(p)); }
```

Calculate the vertical and horizontal size of a given picture p.

```
struct gauss
{
   int x;
   int y;
}

bool operator == (gauss a, gauss b)

gauss operator cast (pair p)
pair operator cast (gauss g)
```

A Gaussian integer structure, mainly used by the combination [page 7] function.

# 8. Index

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(S) int subsetinsertindex (subset[], int) \longrightarrow [page 37]
(S) int subsetmaxlayer (subset[], int[]) \longrightarrow [page 37]
(S) void subsetcleanreferences (subset[]) \longrightarrow [page 37]
(S) dpar dpar.subs (\langle ... \rangle) \longrightarrow [page 26]
(S) transform smooth.selfadjust () \longrightarrow [page 20]
(S) smooth smooth.setratios (real[], bool) \longrightarrow [page 25]
(S) smooth smooth.setcenter (int, pair, bool) \longrightarrow [page 14]
(S) smooth smooth.setcenter (string, pair, bool) \longrightarrow [page 20]
(S) smooth smooth.setlabel (int, string, pair, pair) \longrightarrow [page 14]
(S) smooth smooth.setlabel (string, string, pair, pair) \longrightarrow [page 21]
(S) smooth smooth.setelement (int, element, int, bool) \longrightarrow [page 15]
(S) smooth smooth.setelement (int, pair, string, pair, int, bool) \longrightarrow [page 15]
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(S) smooth smooth.setelement (string, element, bool) \longrightarrow [page 21]
(S) smooth smooth.setelement (string, pair, string, pair, bool) \longrightarrow [page 21]
(S) smooth smooth.setsection (int, int, real[]) \longrightarrow [page 16]
(S) smooth smooth.shift (explicit pair) \longrightarrow [page 14]
(S) smooth smooth.shift (real, real) \longrightarrow [page 14]
(S) smooth smooth.scale (real) \longrightarrow [page 14]
(S) smooth samplesmooth (int, int, string) \rightarrow [page 38]
(S) smooth sm (int, int, string) \longrightarrow page 38
(S) void shaderegion (picture, path, real, real, pen) \longrightarrow [page 40]
(S) void save () \longrightarrow [page 7]
(T) struct tarrow \longrightarrow [page 4]
(T) struct than \longrightarrow [page 4]
(T) path turn (path, pair, pair) \longrightarrow [page 10]
(\mathrm{T}) smooth tangentspace (smooth, int, pair, real, real, real, string, pair) \longrightarrow
    [page 38]
(U) path ucircle \longrightarrow [page 9]
(U) path usquare \longrightarrow [page 9]
(U) real[] unitseq (real) \longrightarrow [page 40]
(U) path[] union (path, path, bool, bool, real) \rightarrow [page 8]
(U) path[] union (path[], bool, bool, real) \rightarrow [page 8]
(U) path[] union (bool, bool, real ... path[]) \longrightarrow [page 8]
(U) pen underpen (pen) \longrightarrow [page 34]
(U) smooth[] union (smooth, smooth, bool, bool, real) \longrightarrow [page 28]
(U) smooth[] union (smooth[], bool, bool, real) \longrightarrow [page 28]
(U) smooth[] union (bool, bool, real ... smooth[]) \rightarrow [page 28]
(U) smooth unite (smooth[], bool, bool, real) \longrightarrow [page 28]
(U) smooth unite (bool, bool, real ... smooth[]) \longrightarrow [page 28]
(V) —
(W) path wavypath (real[], bool, bool) \longrightarrow [page 11]
(W) path wavypath (\dots real[]) \longrightarrow [page 11]
(X) real xsize (path) \longrightarrow [page 9]
(X) real xsize (picture) \longrightarrow [page 40]
(X) real subset.xsize () \longrightarrow [page 18]
(X) real smooth.xsize () \longrightarrow [page 14]
(X) void smooth.xscale (real) \longrightarrow [page 14]
(Y) real ysize (path) \longrightarrow [page 9]
(Y) real ysize (picture) \longrightarrow [page 40]
(Y) real subset.ysize () \longrightarrow [page 18]
(Y) real smooth.ysize () \longrightarrow [page 14]
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(Z) —