Introduction to package isismdl

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1 Introduction

This introduction shows how package isismdl can be used to solve a simple example model, a dynamical version of the ISLM model.

[Here follows a description of the ISLM model]

2 The model file

The model file should be defined on an external ASCII file. A detailed discussion about the syntax of this file is provided in the Reference Manual of Isis.

A model file for the ISLM model is included in the example models in directory models of the package directory. To copy this file to you working directory, use

```
> mdl_file <- system.file("models", "islm.mdl", package = "isismdl")
> file.copy(mdl_file, "islm.mdl")
```

The model file islm.mdl has the following contents:

```
param c0 100 c1 0.7   c2 20 c3 0.5;
param i0 100 i1 0.2   i2 40 i3 1.5;
param m0   75 m1 0.23 m2 35 m3 1.5;
param t0 -25 t1 0.22;

? behavourial equations
frml c = c0 + c1 * (0.9 * yd + 0.1 * yd[-1]) - c2 * r + c3 * r**2;
frml i = i0 + i1 * (0.2 * y + 0.8 * y[-1]) - i2 * r[-1] + i3 * r[-1]**2;
frml md = m0 + m1 * y - m2 * r + m3 * r**2;
frml t = t0 + t1 * y;

? ident equations
ident yd = y - t;
ident y = c + i + g;
ident r = r + (ms - md) / ms;
```

3 Creating the model

The function isis_mdl parses the model file and creates an IsisMdl object

```
> mdl <- isis_mdl("islm.mdl")</pre>
Isis Model Compiler 3.00
Compiling model...
       7 equations processed
Ordering equations...
Checking redundant feedback variables
       O redundant feedback variables detected
Generating feedback variable ordering
Writing MIF file...
Writing cross-reference file...
End compilation
Reading mif file...
Model with
               7 equations read
Checking Model-code...
Model is ok...
Feedback ordering generated ...
```

This function generates the file <code>islm.mrf</code>, the so called model reference file (mrf file), a text file with information about the structure of the model. If the compiler detects an error in the model file, an additional file <code>islm.err</code> is created. This file contains a list of errors.

The mrf file for our ISLM looks like this:

```
ISIS model compilation: islm 2018-01-22 11:48:33

Model reference table

Each variable name is followed by its maximum lag (with minus sign) and maximum lead in the model, its type: E(xogenous), B(ehavioral), I(dentity).

Exogenous variables listed first.

Parameters are listed separately.

Each parameter name is followed by its length.
```

```
Equations are listed in solution order,
followed by a list of feedback variables.
*** Statistics ***
      9 variables of which
             2 exogenous
             4 behavioral
             3 identity
      3 total number of lags and leads with
             1 maximum lag
             0 maximum lead
             O variables with leads
     14 parameters
            14 total length of parameter values
      7 equations of which
             0 in prologue
             7 in simultaneous block
             0 in epilogue
      2 feedback variables
                4 (****%) structural non zero's in jacobian
Statistics of feedback ordering
              7 words of memory used
            2 minimum feedback chain (excl. fb equations)
            5 maximum feedback chain (excl. fb equations)
            3.5 average feedback chain (excl. fb equations)
            2 average newton steps (rounded up)
*** Variables ***
*** Exogenous ***
            0 E
        0
          0 F.
ms
*** Endogenous ***
        0
            0 B
С
            0 B
md
        0
           0 B
r
       -1
           0 I
        0
           0 B
t
       -1
            0 I
```

*** Parameters ***

0 I

-1

```
c0
        1
c1
        1
c2
        1
сЗ
        1
i0
        1
i1
        1
i2
        1
i3
mO
        1
m1
        1
        1
m2
        1
mЗ
        1
t0
t1
        1
*** Equations (in solution order) ***
    O Prologue equations
    7 Simultaneous equations
i
          t
     md
                yd
                               r
    O Epilogue equations
*** Feedback variables ***
    2 Feedback variables
r
     у
*** Additional information for feedback variables
    Name of feedback variable followed by how it was chosen: fixed, diagonal, heuristic,
    and the length of the feedback cycle (excluding feedback variables)
```

The mrf file contains technical information about the model. For example, it shows which variables are exogenous or endogenous, and which variables are feedback variables. A brief explanation of these concepts:

- Exogenous variables are variables that only occur at the right hand side of the equation.
- Endogenous variables are variables on the left hand side of the equations.

2

diagonal

diagonal

r

• A feedback variable is a variable that directly or indirectly depends on itself. In order to solve the model, initial guess values for the feedback variables have to be specified.

4 IsisMdl objects

An IsisMdl object is an R6 class object. R6 classes behave quite differently than the more familiar S3 and S4 classes. For example, for R6 classes methods are part of the object itself and not of generic functions. R6 classes behave in a similar way as classes in object oriented languages such as Java, C++ or Python.

For example, the method get_params() can be used to obtain the values of the model parameters. For example, to obtains the values of parameters m0 and c1, use

```
> mdl$get_param(names = c("m0", "c1"))
$m0
[1] 75
$c1
[1] 0.7
```

Methods starting with get_, are often called "getter" methods. There are also corresponding "setter" methods. For example

```
> mdl$set_param(list(m0 = 100))
> mdl$get_param("m0")
```

```
$m0
[1] 100
```

Input for method set_params() is a named list.

4.1 Copying IsisMdl objects

Consider the following assignment:

```
> md12 <- md1
```

Now variables md12 and md1 refer to the same object. If you modify md12, then also md1 is modified.

```
> mdl2$set_param(list(m0 = 75))
> mdl$get_param("m0")
```

```
$m0 [1] 75
```

The usual copy-on-modify semantics that are used for convential R objects such as S3 or S4 classes do not apply to R6 classes.

If you want to create a copy of the model, use the copy() method with argument deep = TRUE:

```
> md12 <- mdl$copy()
> md12$set_param(list(m0 = -9999))
> md1$get_param("m0")
```

\$m0 [1] 75

5 Solving the model

Suppose that we want to solve the model for the period from 2017Q1 to 2018Q2. Then we need the values of the exogenous variables for that period. For the feedback variables y and r we also need initial starting

values for the model period 2017Q1/2018Q2'. Sincer, yandy_dare lagged, we also need values for these variables in 2016Q4'.

In typical applications, the input timeseries are read from an external file, for example a csv file. For this tutorial we will create a timeseries object manually by employing function regts of the regts package. For the exogenous variables g and ms we assume an annual growth of 1.5% after 2016Q4.

```
> # exogenous variables:
> g <- regts(210 * cumprod(rep(1.015, 6)), start = "2017Q1")
> ms <- regts(200 * cumprod(rep(1.015, 6)), start = "2017Q1")
> # feedback variables (with lag):
> r <- regts(3.4, period = "2016Q4/2018Q2")
> y <- regts(980, period = "2016Q4/2018Q2")
> # lagged variable
> yd <- regts(790, start = "2016Q4")
> data <- cbind(g, ms, r, y, yd)
> data
```

```
g ms r y yd

2016Q4 NA NA 3.4 980 790

2017Q1 213.1500 203.0000 3.4 980 NA

2017Q2 216.3472 206.0450 3.4 980 NA

2017Q3 219.5925 209.1357 3.4 980 NA

2017Q4 222.8863 212.2727 3.4 980 NA

2018Q1 226.2296 215.4568 3.4 980 NA

2018Q2 229.6231 218.6887 3.4 980 NA
```

To transfer these variables to the model, we first have to define the model period. This is the period for which the model will be solved. For this we use the method set_period():

```
> mdl$set_period(period_range("2017Q1", "2018Q2"))
> mdl
```

```
      IsisModel object

      Model index:
      1

      Number of variables:
      9

      Maximum lag:
      1

      Maximum lead:
      0

      Model period:
      2017Q1/2018Q2

      Model data period:
      2016Q4/2018Q2
```

The data period is the model period extended with the lag and lead period. You can also retrieve the model period and model data period with the methods get_period() and get_data_period.

Now we can transfer the values in regts object data to the model with method set_data():

```
> mdl$set_data(data)
```

To check the model data, we use

```
> mdl$get_data()
```

```
C G I Md MS T T Y Y Yd 2016Q4 NA NA NA NA NA NA NA NA 3.4 NA 980 790 2017Q1 NA 213.1500 NA NA 203.0000 3.4 NA 980 NA 2017Q2 NA 216.3472 NA NA 206.0450 3.4 NA 980 NA 2017Q3 NA 219.5925 NA NA 209.1357 3.4 NA 980 NA 2017Q4 NA 222.8863 NA NA 212.2727 3.4 NA 980 NA 2018Q1 NA 226.2296 NA NA 215.4568 3.4 NA 980 NA
```

2018Q2 NA 229.6231 NA NA 218.6887 3.4 NA 980 NA

Model variables that we have not explicitly set all value NA. These values are not needed to solve the model. We are now ready to solve the model:

> mdl\$solve()

```
Model Solve Options
Solution period
                              2017Q1/2018Q2
Simulation mode
                              dynamic
Feedback starting values
                              current period
Maximum iterations per period 50
Relaxation minimum
                              0.500E-01
           maximum
                              1.00
           shrinkage
                              0.500
Criteria stepback
                              1.30
          matrix
                              0.900
                                                         10
Maximum updates Newton matrix per period
Maximum number of line searches with old Jacobian
                                                         5
Criterion for line search decisions etc.
                                                         geometric
                                            0 (1/condscal = 1.43E-01)
   1 steps for Newton matrix at iteration
Convergence for 2017Q1 in
                             4 iterations
Convergence for 2017Q2 in
                             5 iterations
Convergence for 2017Q3 in
                             4 iterations
Convergence for 2017Q4 in
                             4 iterations
Convergence for 2018Q1 in
                             4 iterations
Convergence for 2018Q2 in
                             4 iterations
Total number of iterations
                             26
Solve model used
                     0.00 CPU secs
```

The method get_data() can be used to retrieve the solution.

> mdl\$get_data()

```
i
                                        md
                                                                     t
              С
                       g
2016Q4
             NA
                      NA
                               NA
                                        NA
                                                 NA 3.400000
                                                                    NA
2017Q1 595.2722 213.1500 177.5801 203.0000 203.0000 3.284697 191.9205
2017Q2 602.9867 216.3472 182.6351 206.0450 206.0450 3.309682 195.4332
2017Q3 610.2563 219.5925 184.9507 209.1357 209.1357 3.304113 198.2559
2017Q4 617.5631 222.8863 187.7053 212.2727 212.2727 3.301510 201.1941
2018Q1 624.9866 226.2296 190.4614 215.4568 215.4568 3.298568 204.1691
2018Q2 632.5206 229.6231 193.2628 218.6887 218.6887 3.295613 207.1894
                       yd
               у
2016Q4 980.0000 790.0000
2017Q1 986.0023 794.0818
2017Q2 1001.9690 806.5358
2017Q3 1014.7995 816.5436
2017Q4 1028.1548 826.9607
2018Q1 1041.6776 837.5085
2018Q2 1055.4065 848.2171
```

6 Writing and reading IsisMdl objects

To write an IsisMdlobject to a file, use for example

```
> mdl$write_mdl(file = "islm_mdl.ismdl")
```

This methods serializes the model equations, parameters, model data, solve options, etc. You can read this model back with the command

```
> mdl <- read_mdl("islm_mdl.ismdl")</pre>
```

Do not use the standard functions for writing objects to a file and to restore them, such as save, saveRDS, load and readRDS. These functions cannot handle the complex structure of IsisMdl objects.

7 Fixing variables

TODO

8 The fit procedure

TODO

9 Modellen bewerken

9.1 Vergelijkingen uitschakelen

TODO

9.2 Modeldata aanvullen

TODO

9.3 Losse vergelijkingen draaien

10 Bijsturen van het modeloplossen

TODO