

A unified framework of demographic time

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Abstract

Demographic thought and practice is largely conditioned by the Lexis diagram, a two-dimensional graphical representation of the identity between age, period, and birth cohort. This relationship does not account for remaining years of life, total length of life, or time of death, whose use in demographic research is both underrepresented and incompletely situated. We describe an identity between these six demographic time measures, and generalize this relationship to time measures derived from an arbitrary number of events in calendar time. We describe the sub-identities that pertain to the six-way demographic time identity, and provide a topological overview of the diagrams that pertain to these identities in both two and three dimensions. We provide an application of this framework on the measurement of late-life disability prevalence.

Keywords. Age structure, formal demography, data visualization, age period cohort.

1 Introduction

In the course of training, all demographers are introduced to the Lexis diagram, a convenient graphical identity between the three main time measures used to structure demographic stocks and flows: Age, period, and birth cohort. This representation does not account for time of death, time until death, or length of life, which may be of interest to researchers and policy makers as structuring rather than random variables in order to capture variation in demographic data. ~~This popular representation does not account for remaining years of life and other related time indices that may be of interest to researchers and policy makers.~~

We wish to draw attention to three time indices that are complementary to age (A), period (P) and birth cohort (C). The first such index is time-to-death, which we refer to as “thanatological age” (T) in contrast to “chronological age” (A). The second index is death cohort (D), which groups all individuals (of different ages) dying in the same time period. Finally, lifespan (L) or individual age-at-death itself is an index by which data may be structured. We therefore have six time measures in total to relate. We call these measures of demographic time because each, except period, depends on the timing of birth, death, or both.

The Lexis diagram can be understood as an APC plane that relates age, period, and birth cohort. Other such planes are also identifiable. The “thanatological” “dual” of APC is an identity between thanatological age, period, and death cohort, TPD. A third identity relates thanatological age, chronological age, and lifespan, TAL. A fourth identity relates lifespan, birth cohort, and death cohort, LCD. We call three-way identities of this sort “triad identities”.

Each of these four triad identities (APC, TPD, TAL, and LCD) is sufficiently described by any two of its constituent indices, ~~making the third index redundant~~. For instance, if the exact age of an individual at a particular time is known, the birth cohort to which he or she belongs can be immediately derived. Each of these four identities also lacks a major dimension of time. The TAL identity lacks calendar time, the LCD identity is ageless, APC lacks an endpoint in time, and TPD lacks a starting point in time. To our knowledge, the only triad identity that has received serious treatment at the time of this writing is the APC identity. Different aspects of the APC identity have been discussed since at least 1868 (Knapp 1868), and discussion remains lively today. Here we relate the

six major indices of time in a geometric identity, in much the same spirit as the work on APC relationships done between the late 1860s and mid 1880s.¹

Our goal is to describe the geometric identity between all six measures of demographic time, a hexad identity, that may be useful or an intuitive referent for demographers in the same way as the Lexis diagram. At the same time, this identity relates the four triad identities we have mentioned. We give a bottom-up description of how such temporal identities can be derived from an arbitrary number of events in calendar time in a simple and general event-duration relationship. These more general event-duration foundations facilitate comparison of the demographic time framework with other temporal designs found in the literature, such as the higher-order temporal model of Brinks et al. (2014), or the marriage cohort hexad identity described by Lexis (1875). The framework we describe is general and adaptable for such event history scenarios. We begin by defining some terms used throughout the manuscript. We then explore all combinations of two time measures, the dyadic relationships, followed by the four triad identities, and finally the hexad identity. We give a systematic topological overview of the different elements of demographic time.

Just as the Lexis diagram has been a fundamental instrument to teach demography for decades, we hope that the demographic time measures and their graphical depictions presented here will be helpful to teachers and young demographers. The temporal relationships we describe will also be useful for researchers to better detect and understand patterns data, and for methodologists to better account for the structure of data in demographic methods or statistical designs.

2 Definitions

2.1 Technical terminology

In describing this relationship we attempt to adhere to a rigorous terminology. The following list describes some of the more important terms we use.

Demographic time measures are any of the six time indices discussed to describe demographic time: chronological age (A), period (P), birth cohort (C), thanatological age (T), lifespan (L), and death cohort (D).

Dyads, triads, and hexads are any set of two, three, or six unique time measures, respectively.

A triad identity is a triad with the property that each of its members can be derived from the other two with no additional information. There are four triad identities: APC, TPD, TAL, and LCD.

A temporal plane is any (x, y) -mapping of a dyad of time measures.

Using this terminology, we say that the “Lexis” measures constitute a triad identity between chronological age, period, and birth cohort. Each dyad combination of elements in this identity can be mapped to a temporal plane, the Lexis diagram. If we know that Mindel turned 50 on the 21st of May, 1963, then we also can derive that she was born on the 21st of May, 1913. Hence, any two pieces of information in this case will give the third, and the same holds for the other triad identities.

¹See e.g., Keiding (2011) for an overview of that literature.

2.2 Time measures

We describe time in terms of years, the dominant time scale for human demography, although all relationships are scalable to any time unit. We therefore speak of calendar time. We also describe the framework in terms of human lifespans, although it applies in a more general sense to any durations observed over time. This is to say, birth may be translated to entry, and death to exit, or any other absorbing state. The six measures of time we consider are defined in Table 1, both in the demographic sense we describe, as well as in a more general event history interpretation.

Table 1: Definitions of the six time measures.

Time measure	Short	Demographic def.	Event history def.
chronological age	A	Time since birth	Time since start of exposure
period	P	calendar time	calendar time
birth cohort	C	calendar time of birth	calendar time of exposure start
thanatological age	T	time until death	time until event
death cohort	D	calendar time of death	calendar time of event
lifespan	L	duration of life	duration of exposure

The concepts of thanatological age and death cohorts are likely less familiar to readers than the other measures we consider. Thanatological age invokes the remaining lifetime until death, the information approximated with life expectancy. This term is sometimes referred to in the literature as life left, time to death, remaining lifespan, follow-up duration, residual life, or reverse time. Chronological and thanatological age are in this way complementary, duals. On the other hand, cohorts in general associate individuals that share a characteristic. In demography the grouping characteristic is often a combination of place and time, such as a cohort of young demographers passing through a particular graduate program. These concepts are analogous to the ideas of birth and death cohorts we use here. The deaths of a given year are not usually referred to as a death cohort, although this concept was already introduced by Brouard (1986) as “*génération de décès*” in a retrospective study of the French population during the twentieth century. In the time preceding death, the members of a given death cohort have much in common, despite heterogeneity with respect to time of birth. If the reader accepts this premise, then the abstract construct of a death cohort is also meaningful in the way that other cohort measures are. In event history or non-human contexts, analogs to death cohorts in this framework may be even more meaningful.

Much of the work of demography is directed at the study of lifespan. Lifespan is synonymous both with longevity, chronological age at death, and thanatological age at birth. One’s ultimate completed lifespan is constant throughout life, though we have no knowledge of it until death: It is assigned retrospectively. Demographers have more often used lifespan or age-at-death as a measure of mortality, or similar, than as a measure on which to compare individuals or structure data.

Treating lifespan, death cohorts, and thanatological age as temporal structuring variables enables new classes of comparisons, models of understanding, and discovery, akin to those unlocked by breaking down demographic phenomena by chronological age, period, and birth cohort. The following sections, in this sense, provide an exhaustive classification of the ways in which these six measures of time can be juxtaposed to such ends.

3 From dyads to the triad identities

We distinguish between two kinds of dyads: informative dyads and uninformative dyads. Informative dyads are any pair of measures from which a third time measure can be derived, forming a triad identity. There are $15 = \binom{6}{2}$ possible dyads in our set of time measures, 12 of which are informative, and three of which have no derived time measure, and are therefore called uninformative. For instance, if we take the dyad TA, L is the derived measure, and TAL the corresponding triad identity. In contrast, nothing can be derived from the LP dyad: You can have an eventual lifespan of 100 in the year 2016 and still be alive with the same eventual lifespan in 2017.

In this section we systematically map each dyad to its temporal plane, and we synthesize these into the four primary identities and their essential diagrams. We first discuss the choice between mapping dyads to Cartesian coordinates or to isotropic coordinates, which constrain the scales of all measures to be equal. We then systematically render the 15 dyad-based diagrams that can be derived from the six time measures. Of these 15, 12 diagrams can be distilled into just four, the triad identity diagrams. Each triad identity diagram is then briefly discussed with suggested or speculated applications.

3.1 The question of mapping

Any mapping of two time measures to an (x, y) coordinate system constitutes a temporal plane. If the two given time measures are members of the same triad identity, the third member is a derived measure. If we assign A to y and P to x , thereby implying C (and the APC triad identity) we state this relationship explicitly by writing AP(C). The temporal plane that corresponds to this informative dyad is the contemporary representation of the Lexis diagram (Lexis 1875, Pressat 1961). The informative dyads AC(P) and CP(A) also belong to the Lexis identity, but imply different less-common rotations and projections of the Lexis diagram.²

For each dyad there is a fundamental question of how to map the constituent coordinates to a Cartesian temporal plane. Typically one forces parity between time units within a specified dyad, mapping one element directly to x and the second element directly to y , resulting in a 90° angle between the x and y axes. In this case it is conventional to force a unity aspect ratio between the x and y axes, such that the derived measure, if any, is then *accidentally* present in a 45° ascending or descending angle, depending on the dyad and axis orientation.

It has long been noted (Lexis 1875, Perozzo 1880) that the derived time measure (usually birth cohort) is longer than either the age or period axes when plotted at 45° . If a right angle and unity aspect ratio is forced between the dyad, the derived measure is always stretched by $\sqrt{2}$, or 41%. In the case of informative dyads, another logical mapping is to translate to (x, y) coordinates that force 60° angles between the three measures. Such a mapping ensures that the spatial units are equal for the three measures, and we therefore refer to it as the isotropic mapping. The isotropic mapping is comparable to using ternary or barycentric coordinate systems. The primary justification for isotropic demographic

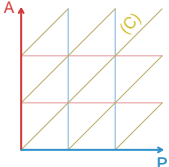
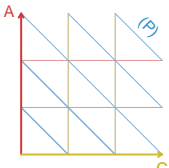
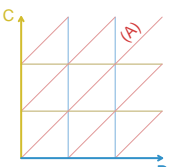
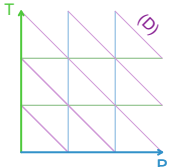
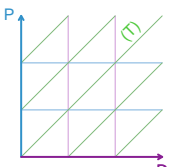
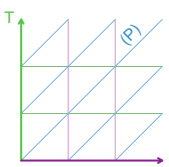
²While uncommon as diagram orientations, these latter two dyads are used to tabulate data for different kinds of rates and probabilities. Measures based on the AC dyad are variously referred to as Type III rates (Caselli et al. 2006) or vertical parallelograms (Wilmoth et al. 2007). The CP dyad delineates Type II rates (Caselli et al. 2006), also known as horizontal parallelograms, for instance used to calculate cohort lifetables in the Human Mortality Database (Wilmoth et al. 2007).

surfaces comes from a data visualization perspective, where it may be hypothesized that the viewer’s ability to compare slopes is hindered if time coordinates are not on the same scale. Under the isotropic representation, the three variants of each triad identity are simple rotations of one another, and they require no rescaling. In this paper, all two-dimensional diagrams are rendered in Cartesian rather than isotropic coordinates.

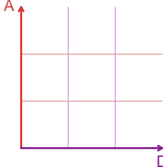
3.2 Dyads to diagrams

Each of the 15 dyads, an explanation or simple example, and the corresponding diagram representations are summarized in Table 2. Each informative dyad is a subset consisting of two elements from one of the four triad identities (APC, TPD, TAL, LCD), which we analyze in detail in further sections. The uninformative dyads are simply pairs of time measures that do not have a derived measure, and therefore are not contained in any of these four triad identities.

Table 2: All dyadic juxtapositions of the six measures of demographic time.

Note: The temporal planes are named after the two given time scales. The derived scale is appended in parentheses. Contrary to mathematical convention we name the ordinate scale first and the abscissa scale second. This is to be consistent with the established <i>APC</i> and <i>ACP</i> terms.		
Relationship	Description	Cartesian
VARIANTS OF APC		
$AP(C)$ $C = P - A$	The $AP(C)$ temporal plane constitutes the classical Lexis diagram.	
$AC(P)$ $P = C + A$	The $AC(P)$ temporal plane is equivalent to the Lexis diagram except birth cohort is given and period is derived rather than the other way around.	
$CP(A)$ $A = P - C$	The $CP(A)$ temporal plane is equivalent to the Lexis diagram except birth cohorts are given and age is derived rather than the other way around.	
VARIANTS OF TPD		
$TP(D)$ $D = P + T$	Helen had 30 years of life left (T) in 1971 (P) and therefore belonged to the 2001 death cohort (D)	
$PD(T)$ $T = D - P$	Mindel died in 1973 (D). In 1953 (P) she had 20 years left to live (T).	
$TD(P)$ $P = D - T$	Irene died in 1974 (D). When she had 30 remaining years of life (T) the year must have been 1944 (P).	
VARIANTS OF TAL		

$TA(L)$ $L = T + A$	<p>The time already lived and the time still left sum up to the total lifespan.</p>	
$TL(A)$ $A = L - T$	<p>Helen lived to the age of 86 (L). When she had 20 years left (T) she must have been 66 (A).</p>	
$AL(T)$ $T = A - L$	<p>Tim is 34 years old (A) and will live to the age of 96 (L), leaving him 62 years (T) to settle affairs.</p>	
VARIANTS OF LCD		
$LC(D)$ $D = C + L$	<p>Àngels was born in 1940 (C) and she lived to be 64 (L), implying an untimely death in 2004 (D)</p>	
$CD(L)$ $L = D - C$	<p>Pascal was born in 1893 (C) and died in 1964 (D), implying a lifespan of 71 (L), or so.</p>	
$LD(C)$ $C = D - L$	<p>Margaret died in Dec., 1995 (D) with a completed lifespan of 96 (L), putting her birth year in 1900 (C).</p>	
THE UNINFORMATIVE DYADS		
$LP(-)$	<p>The LP plane is <i>non-informative</i>. No additional measures can be derived knowing just lifespan and period.</p>	
$CT(-)$	<p>The CT plane is <i>non-informative</i>. No additional measures can be derived knowing just birth cohort and thanatological age.</p>	

AD(-)	<p>The AD plane is <i>non-informative</i>. No additional measures can be derived knowing just death cohort and age.</p>	
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Most of what we know about how rates change over age and time comes from the very first juxtaposition in Table 2, AP(C). While CP(A) and AC(P) are statistically redundant when exact times are used, they are not fully redundant if based on discrete double-classification of data, as often provided in aggregated official statistics. Double classified data are found on the APC diagram in the shape of squares (AP), horizontal parallelograms (AC) and vertical parallelograms (PC), and these are commonly used to compute different kinds of demographic rates and probabilities (Caselli et al. 2006, p. 63). The other dyadic juxtapositions (involving the measures T, D, or L) can be considered as either rare or novel ways of structuring or viewing temporal variation in demography, and these imply new families of rates and probabilities.

3.3 The triad identities

There are $20 = \binom{6}{3}$ ways to choose three time indices out of six, of which four form a triad identity: APC, TPD, TAL, and LCD. Given the three time measures from any of the triad identities, one can derive no further time measures. If one selects three random time indices that do not form any of these four triad identities ($20 - 4 = 16$ possibilities), this property does not hold. For instance, in the triad APT, age and period are not sufficient to determine thanatological age. Given the triad APT one can however derive the remaining three time measures.

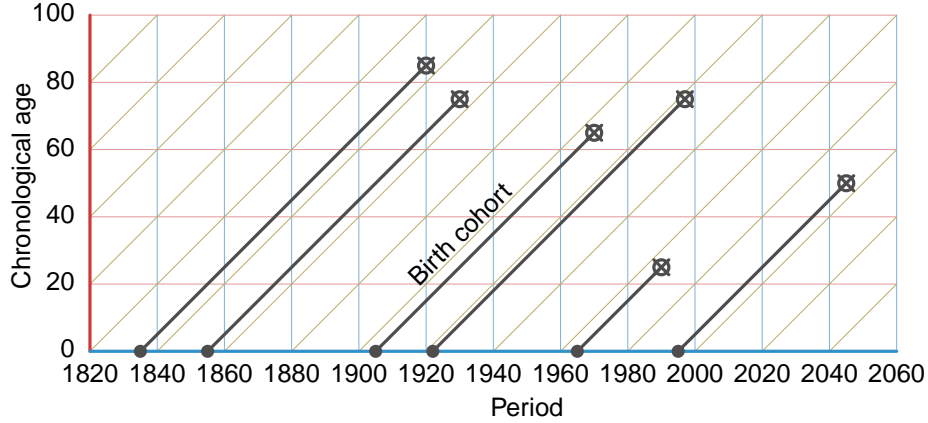
Triad identities are more meaningful than uninformative dyads. This is so even in the absence of data, due to the underlying relationship between measures. Each of the triad identities can accommodate some version of a lifeline, for instance. In the following, we therefore lay out the four primary diagrams that belong to the triad identities. The question of which diagram mapping is relevant to a given demographic phenomena is a function of patterns in the data. The best diagram is the one that captures all meaningful variation in the data. If APC highlights meaningful variation in a phenomenon, then its representation as such is useful. The same holds for the other identities. With each diagram in following we comment or speculate on its potential uses.

3.3.1 APC: Chronological age, period, and birth cohort

The so-called Lexis diagram has long been used in demography as a conceptual tool for structuring data, observations, and rate estimation, as inspiration for work on statistical identification, and as the coordinate basis of contemporary Lexis-surfaces. Since the Lexis diagram could have been named for others (Keiding 2011, Vandeschrick 2001), and since we compare with other temporal configurations, let us refer to it as the APC diagram, as seen in Figures ?? and ??.

The APC diagram in Figure 1 represents years lived on the y axis, calendar years on the x axis, and birth cohorts as the right-ascending diagonals. This is the most common of several possible configurations of the APC dimensions. Individual lifelines (black) are aligned in the birth cohort direction, starting with birth (filled circle) at chronological

Figure 1: An APC diagram with six lifelines.



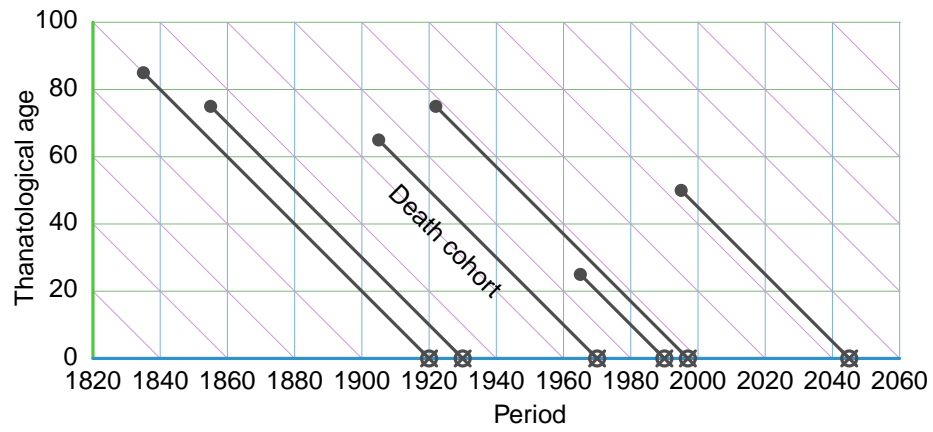
age zero, and death (circled x). Any APC surface can be interpreted along each of these three dimensions of temporal structure.

3.3.2 TPD: thanatological age, period, and death cohort

The TPD diagram is best imagined as the inverse of the APC diagram. One may take the same individuals represented in Figure 1 and group them by death cohorts (D) instead of birth cohorts (C). Lifelines then descend such that all endpoints align to thanatological age 0, creating the diagram in Figure 2 in which individuals dying at different ages but in the same time period are grouped together. To our knowledge, the TPD diagram has only appeared once in the literature, as a didactic aid in a proof of symmetry between chronological and thanatological age structure in discrete stationary populations (Villavicencio & Riffe 2016). TPD diagrams may also be useful to arrange events or durations that are logically aligned (or may only be aligned) by time of termination. It may be reasonable to align on termination in cases where this brings preceding patterns of variation into focus.

There are several examples of analysis of this kind of data, usually stemming from a lack of information on chronological age. This is the case, for instance, in biodemographic studies in which wild animals with unknown ages are captured and then followed-up until death Müller et al. (2004; 2007). Other examples are human historical databases, which usually lack information about births, but individuals can be traced from a particular event until death. This is the case in the Barcelona Historical Marriage Database, which collects information about marriage licenses of Barcelona (Spain) from the mid-fifteenth century until the early twentieth century. In this database, ages are unknown, but individuals are first identified in their marriage record and an estimation of the times of death is plausible (Villavicencio et al. 2015). We speculate that TPD diagrams could also be used in biomedical studies for the representation of lifelines preceding deaths from infectious or acquired conditions, when the time of infection or acquisition remains unknown, an issue which has received attention in the statistical literature (see e.g. Chan & Wang

Figure 2: A TPD diagram with six lifelines.



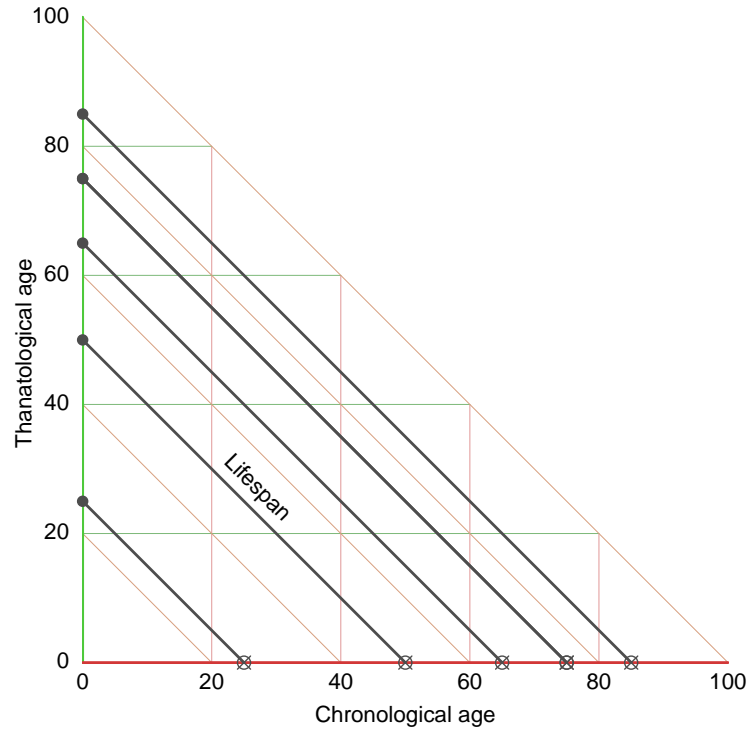
2010).

3.3.3 TAL: Thanatological age, chronological age, and lifespan

TAL is an appropriate diagram to examine processes that vary over the lifecourse. More precisely, the TAL plane can highlight variation that is related to time since birth, time until death, length of life, and their combinations. These key aspects of demographic time are compressed to chronological age only in the APC perspective, which can blend out meaningful variation. Since the lifecourse belongs to the cohort perspective, it is best to think of the TAL plane as belonging to some particular birth cohort. Alternatively, a TAL triangle may be taken as a cross-section through the period dimension, a sort of synthetic TAL plane.

To our knowledge, the TAL diagram has only appeared once in the literature, in an exploration and classification of late-life health conditions (Riffe et al. 2016). There are however instances of statistical designs adapted to this coordinate plane (see e.g., Jewell 2016, Dempsey & McCullagh 2016). The TAL diagram in Figure 3 contains no indication of period or cohorts, as calendar time is blended out in this diagram. The lifelines depicted are identical to those shown in APC Figure 1 and TPD Figure 2. The TAL diagram is useful for characterizing patterns of prevalence of health conditions. We speculate that data structured and aligned in this way may yield hitherto undescribed patterns in other contexts, such as pregnancy (from the perspective of either mother or fetus) by time since conception, time until parturition, and length of gestation, or even smaller event-history time scales, or patterns of growth or reproduction in non-human species.

Figure 3: A TAL diagram with six lifelines (*).

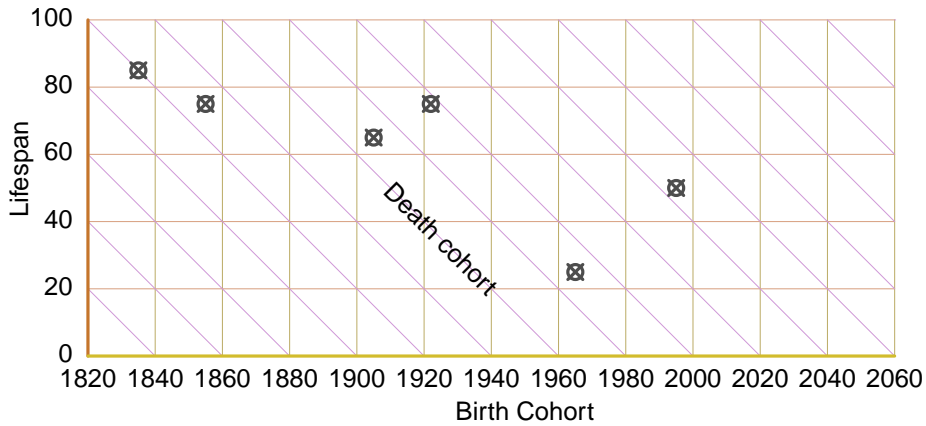


(*) Since two of the six lifelines are of equal length (75), they are overlapped in this figure and appear to be five.

3.3.4 LCD: Lifespan, birth cohort, and death cohort

The LCD diagram completes our set of identities. It is based on the relationship between lifespan, birth cohort, and death cohort. In Figure 4, lifespans are indexed by the y -axis, while birth cohorts are indexed by the x -axis, and death cohorts are found in descending diagonals. To structure data on these three time measures implies excluding time-varying information over the lifecourse. An individual only ever has one lifespan, one birth cohort, and one death cohort, such that the LCD coordinates of an individual are constant throughout life. The LCD plane is therefore orthogonal to lifelines, and individuals are located with points, rather than life segments. In Figure 4, the same six individuals from previous diagram figures are represented with crossed circles.

Figure 4: An LCD diagram in two projections.



We recommend this mapping for plotting surfaces of values that are cumulative or static over the lifecourse, but that may vary over time or by length of life. Imagine an LCD surface of cumulative lifecourse consumptive surplus or deficit, or anything else that might vary by lifespan and moment of birth or death, such as children ever born, years of retirement, the size of trees or other aspects of forestry, populations of buildings in large cities, and so forth. Lexis (1875) describes an analogous relationship between marriage cohort, separation cohort, and duration of marriage.

4 A general relationship between events and durations

The four identity-based diagrams discussed in prior sections are likely straightforward, either because the Lexis diagram is already familiar to the reader, or because Cartesian representations are widely used. However, the special relationship between these diagrams is based on a single hexad identity, which is less straightforward, and its resultant diagram is best derived from a more general groundwork. In this section we therefore describe a more general approach to understanding and constructing higher order temporal

identities. This approach is based on a categorization of time measures into events and durations, and the realization that durations derive from events in calendar time.

The general relationship between events and durations serves not only to introduce the full demographic time framework, but also to compare it with other relatively complicated temporal designs in the literature. Each of the six time measures that we have treated can be categorized into two basic types: Events and durations. Events include birth (C) and death (D), as well as period itself (P). Durations are time differences between pairs of events. Chronological age ($A = P - C$), thanatological age ($T = D - P$), and lifespan ($L = D - C$) are in this sense durations.

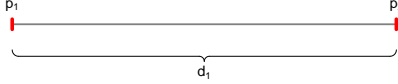
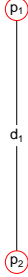
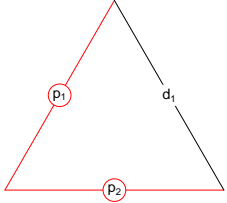
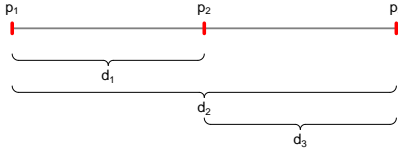
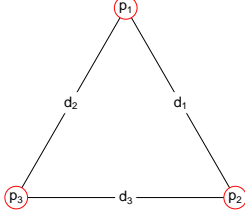
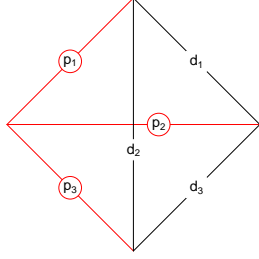
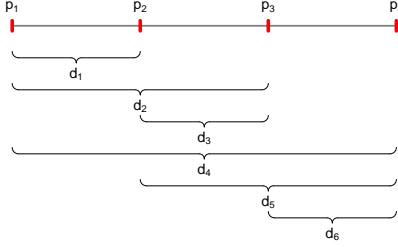
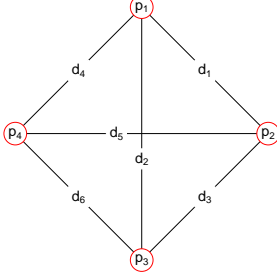
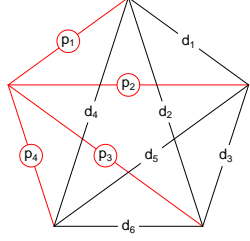
Let us formalize the notions of n points in time $\mathbf{p} = [p_1 \dots p_n]$ and the m durations $\mathbf{d} = [d_1 \dots d_m]$ between these points. \mathbf{d} is linearly dependant on \mathbf{p} in the sense that a linear transformation of \mathbf{p} yields \mathbf{d} . A set of n events implies a total of $m = \binom{n}{2} = n(n-1)/2$ durations. The total number of time measures implied by a set of n events is therefore $n + m$. A set of time measures derived in this way, $\mathbf{g} = [\mathbf{p}, \mathbf{d}]$, forms an identity. In the same way that \mathbf{d} derives from \mathbf{p} , there are $(n+1)^{(n-1)}$ ways to complete \mathbf{g} from a size- n set of potentially mixed durations and events. Proofs for these statements are found in Appendix A.

The relationship between events and durations can be systematically represented in a series of timelines and graphs that may better guide intuition. Table 3 displays a timeline and two levels of graph representation for two, three, and four event sets. The left column shows timelines, a familiar linear representation of time, with events marked with red ticks labelled with $p_1 \dots p_n$. Durations span each of the m possible event dyads and are drawn below the main timeline as curly braces labelled with $d_1 \dots d_m$. It is evident, that as n increases, m increases relatively faster, and this timeline graphical representation is not efficient for $n \gtrsim 4$. Drawing events on a timeline implies an ordering, but the events of \mathbf{p} need not be ordered in any particular way in order for these relationships to hold.

The joint relationship between durations and events is more explicit and more compact in a graph representation. The middle column of Table 3, labelled *graph* consists in the simplest graph representation of the event-duration timeline, with n red vertices for each of the events in \mathbf{p} . A full connection of the graph yields m edges for each of the possible durations in \mathbf{d} . This graph representation loses the linear time analogy of the timeline, but makes the depdenency of \mathbf{d} on \mathbf{p} , and other interdependencies between time measures more explicit.

The right column of Table 3, labelled *temporal plane graph* redraws the graph with a total of $n + 1$ vertices and $m + n$ edges for the elements of both \mathbf{d} and \mathbf{p} . All events of \mathbf{p} connect to a single vertex. Event edges are indicated in red with red-circled labels and nodes have no direct time-measure meaning. In this rendering, each triangle formed by three mutually connecting edges represents a triad identity. The top row $n = 2$ consists in a single identity. Three and four events imply a total of four and ten triad identities, respectively, and in general a given higher order identity will yield $\binom{n+1}{3}$ triad identities. We call this a temporal plane graph because the triangle resulting from any given triad sub-identity can be extended over all valid values of its time measures to form a temporal plane, as of the diagrams in Section 3.3. The dimensionality of the extended diagram of a given identity follows from the number of events from which the identity is derived. $n = 2$ produces a two-dimensional diagram, $n = 3$ produces a 3-dimensional diagram, and so forth.

Table 3: Event-duration timeline, graph, and temporal plane graphs for two, three, and four event sequences.

nr. events	timeline	graph	temporal plane graph
$n = 2$			
$n = 3$			
$n = 4$			

4.1 Examples

Some brief examples will add intuition to the interpretation of Table 3.

Example 1: The Lexis surface Let \mathbf{p} have two elements, as in the first row of Table 3. Then \mathbf{d} consists of just one element, defined as

$$d_1 = p_2 - p_1 \quad . \quad (1)$$

Interpreting d_1 as *age*, p_2 as *period*, and p_1 as *birth cohort* yields the APC identity. The Lexis surface is defined as the plane of all possible combinations between *age* and *period*. *with cohorts as diagonals results from the transformation $P^2 \rightarrow M^2$ as shown to be possible in theorem 3.*

Example 2: Lexis' marriage identity Along with his well known 2-dimensional diagram Lexis (1875) also described a 3-dimensional extension applied to the marriage and separation processes, reproduced in Keiding (2006).

Let \mathbf{p} have three elements, as in the second row of Table 3. Then \mathbf{d} is defined as

$$\begin{aligned}
d_1 &= p_2 - p_1 \\
d_2 &= p_3 - p_1 \\
d_3 &= p_3 - p_2
\end{aligned} \tag{2}$$

Interpreting p_1 as *birth cohort*, p_2 as *marriage cohort* and p_3 as *separation cohort* yields the durations d_1 as *age at marriage*, d_2 as *age at separation*, and d_3 as *duration of marriage*. Lexis’ “marriage space” is reconstructed by transforming $P^3 \rightarrow M^3$ where M has three orthogonal basis vectors corresponding to (p_1, d_1, d_3) .

Example 3: Adding death cohort to the Lexis surface As in Example 2 we start with a three element vector \mathbf{p} yielding the very same identities as in equation set (3) and the second row of Table 3, but with different interpretations. Interpreting p_1 as *birth cohort*, p_2 as *period* and p_3 as *death cohort* yields the durations d_1 as *chronological age*, d_2 as *lifespan*, and d_3 as *time to death*. This vector space P^3 contains the Lexis surface as a sub-space, as well as the other planes presented in Section 3.3. We return to this identity in the following sections.

Example 4: Brinks’ Illness-Death model Brinks et al. (2014) describes an illness-death process atop the Lexis surface, and with diagnosis and death as additional events, for a total of four events. Let \mathbf{p} have four elements, as in the third row of Table 3. Then \mathbf{d} is defined as:

$$\begin{aligned}
d_1 &= p_2 - p_1 \\
d_2 &= p_3 - p_1 \\
d_3 &= p_3 - p_2 \\
d_4 &= p_4 - p_1 \\
d_5 &= p_4 - p_2 \\
d_6 &= p_4 - p_3
\end{aligned} \tag{3}$$

Interpreting p_1 as *birth cohort*, p_2 as *period*, p_3 as *diagnosis*, and p_4 as *death cohort* yields the following composition of \mathbf{d} : d_1 is *chronological age*, d_2 is *age at diagnosis*, d_3 is *time to diagnosis*,³ d_4 is *lifespan*, d_5 is *time to death*, and d_6 is duration of illness (an irreversible state). The complete identity of this model therefore implies a total of ten time measures, although not all measures are explicitly mentioned or used in the model of Brinks et al. (2014).

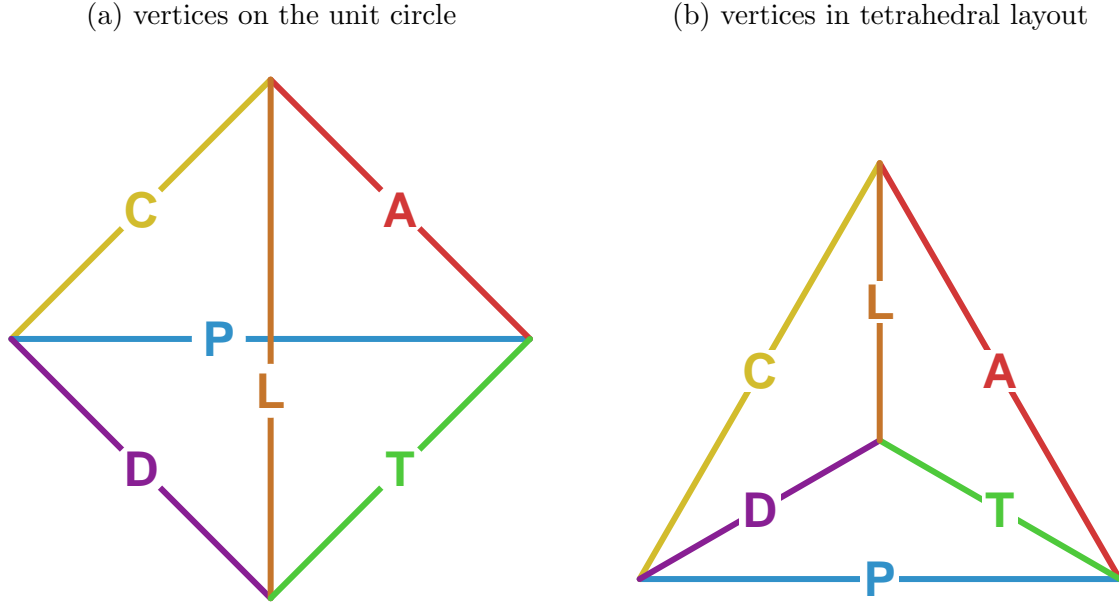
5 A tetrahedron relates the six demographic time measures.

The demographic time framework we present includes three events (period, birth cohort, and death cohort), and it therefore leads to a graph based on the second row and third column of Table 3, here redrawn in Figure 5a withg edges labelled by the six time measures and colored consistent with previous figures. A slight rearrangement of the vertices yields a graph of a tetrahedron in Figure 5b.

³Time to diagnosis can also be time *since* diagnosis if the elements of \mathbf{p} are rearranged. Note that the elements of \mathbf{p} need not be ordered. Although birth and death are likely the first and last elements of \mathbf{p} , this is not strictly required.

There are a total of four triangles in Figure 5, one for each of the triad sub-identities, such that each time measure is an element of two triad identities. In Figure 5b each triangle also is the edge-graph of the face of the tetrahedron, ergo each face of the tetrahedron represents one of the triad identities. It is reasonably straightforward to imagine the tetrahedral graph as the wire-frame of a 3d tetrahedron — as the 3d edge structure of the tetrahedron platonic solid.

Figure 5: Graphs of demographic time hexad identity, with edges labeled by the six time indices.



For exposition, imagine that the middle vertex of Figure 5b is the top (closer to the eye), while the outer edges A, P, and C form the base of the tetrahedron, forming the much-studied APC identity. The South face corresponds to the TPD identity, the Northeast face to the TAL identity, and the Northwest face to LCD identity. A more rigorous explanation of how a three-event system transforms to three dimensions is given in Appendix A (*let's make sure this is true*). It may also suffice to simply imagine that each face of the tetrahedron forms the basis of a plane, such that the tetrahedron itself defines four planes. These four planes are the four temporal planes that underly the four diagrams presented in sections 3.3.1 to 3.3.4. A full diagram of the demographic time identity (or any identity based on three events) conforms in this way with the geometry of a tetrahedron.

6 Diagram of the hexad identity

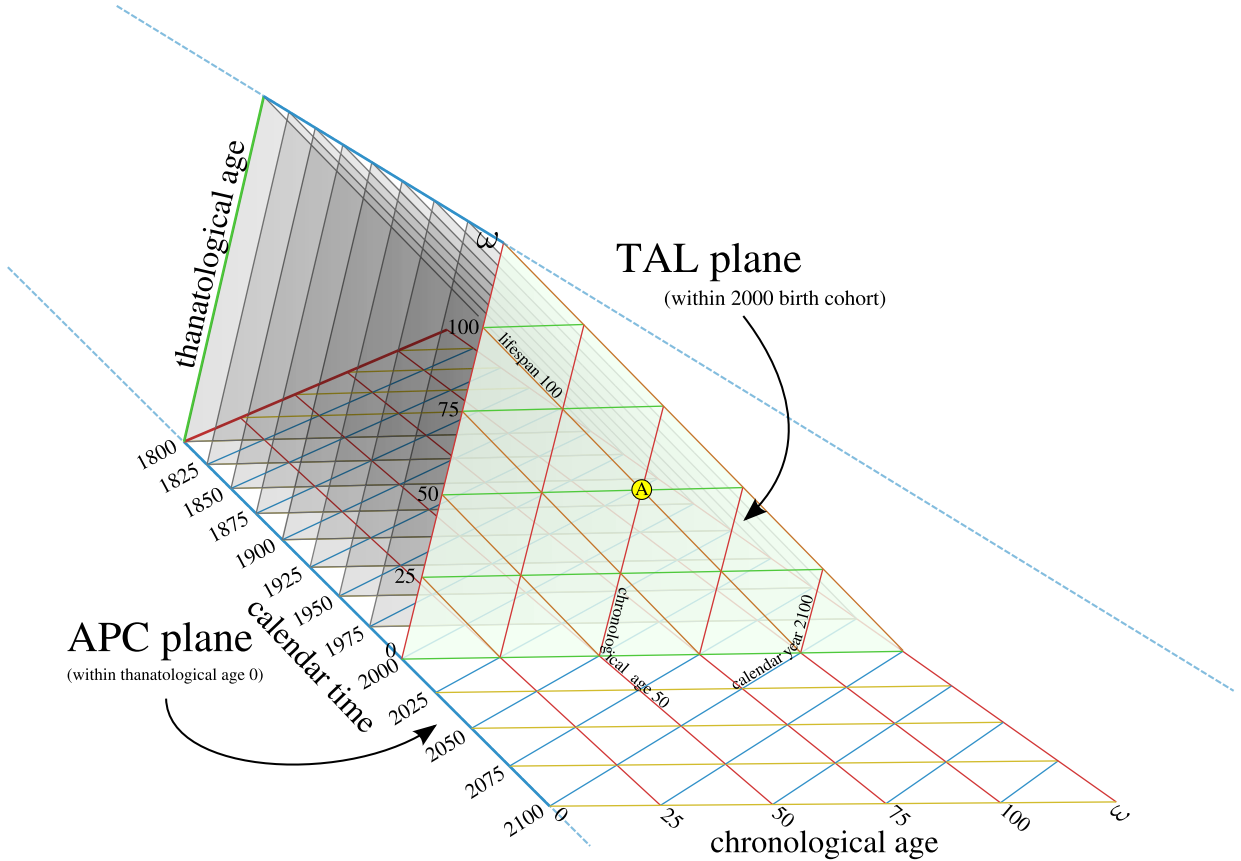
There are different ways to proportion this three dimensional construct, of which we only present the isotropic mapping.⁴ In an isotropic projection, the tetrahedron is regular, such that all edges are of the same length, and the units of each of the six represented time measures are therefore equal. In this case, the four triad identities map to their respective

⁴To compare, Lexis (1875) used a Cartesian mapping for his marriage identity, with right angles between birth cohort, age at marriage, and duration married.

temporal planes as tessellations of equilateral triangles. When the plane parallel to each respective face is repeated in equal intervals, we have an isotropic 3d space.⁵ Displaying all planes simultaneously creates a very dense and difficult-to-read diagram. We opt to delineate the space using the intersection of two planes.

Figure 6 gives a view of a demographic time diagram that corresponds to the hexad identity, where birth-cohort TAL cross-sectional planes are placed in sequence in a perspective drawing.⁶ The most recent TAL plane, for the year 2000, is placed in the front, whereas past TAL planes are stacked behind it, highlighted in 25-year intervals. The left edge of the frontmost TAL plane is labelled as an axis for thanatological age, although the same tick marks also serve for completed lifespan. The base of this figure is the APC plane, drawn through thanatological age 0. Each of the TAL planes sits atop a single birth cohort line from the familiar APC plane that makes up the base of the diagram.

Figure 6: Diagram of the hexad identity, showing a sequence of TAL planes intersecting with a single APC plane.



For example, imagine an infant born in the year 2000. Without further information, we only know that this infant is located somewhere on the thanatological age axis (left

⁵The isotropic space that results from this framework is known in other disciplines with different nomenclatures. In geometry, this structure is called the tetrahedral-octahedral honeycomb, a variety of space-filling tessellation. In architecture, it is found in the octet truss system. In physics it is called the isotropic vector matrix. Constructs following this geometry exist in nature, in other theoretical settings, and in man-made structures.

⁶The coordinates used to render Figure 6 are isotropic. However, there are no 60° angles in this figure due to the use of parallax and an indirect viewing angle in this rendering for the sake of increased legibility.

edge) of the front TAL plane. If this infant is destined to die in the year 2100, then the vertical position at birth will be at the axis tick for thanatological age 100. This person’s entire life stays on the 100 lifespan line (labelled), descending over time towards thanatological age 0 at the base. Point A marks the midpoint in life for this individual, at chronological age 50 (red line, labelled), and thanatological age 50 (green line). If another APC plane were drawn through thanatological age 50, we would see that point A is in the year 2050. Since all individuals born in the year 2000 complete the same age in the same year, we can also recuperate the year for point A by following the chronological age 50 line (red) down to where it meets the blue line for the year 2050. The lifeline descends downward toward the APC plane for thanatological age 0 at chronological age 100, meeting the year 2100, which is individual A’s death cohort.

The density and location of imaginary lifelines in this diagram, omitting migration, is purely a function of birth cohort size and survival. For extinct cohorts all lifelines can be positioned, but for the 2000 birth cohort this is not yet the case. Most of the front TAL plane is in the future. One may imagine yet another plane intersecting this space—the “present plane”, which is identical to the period TAL plane for the present moment. To see how this plane divides the space, imagine that we are in the year 2025, and follow the blue line in the APC base inward 25 years to where it meets the red line for chronological age 25, and follow the red line up the front TAL plane. A single plane cuts through the year 2025 and chronological age 25 from the year 2000 birth cohort. This plane shifts forward or backward in time to meet the present year. In this particular plane, the coordinates T, L, and D are uncertain. The period TAL plane ω years in the past is fully identified, ergo, theoretically the lifespan of each individual in the time of Lexis is knowable.

Figure 6 could have been drawn with TPD or LCD planes highlighted as well, but these can still be imagined upon the current rendering. TPD planes transect this space through any given chronological age, for instance. Imagine a wall on the left side of the prism, cutting through chronological age 0 (recall Figure 2). In this case, the thanatological age axis is indicated in the very back of the diagram, calendar time becomes another axis, and death cohort diagonals are not drawn. TPD planes sequence inward from this first plane, always forming cross-sections through chronological age. The LCD plane is to be found by rotating the current prism such that the angle of view is directly orthogonal to lifelines, which would then appear as points (recall Figure 4).

The essential property of this perspective diagram is that lifelines start and end in parallel, descending downward and forward in time. A real population of renewing lives, spread over time and over the typical range of human lifespans, will tend to fill the entirety of the prism depicted in Figure 6, and any given point in the prism can be given six demographic time coordinates, of which three are redundant.

7 Application

The relationship between the six measures of demographic time is true in the same sense that mathematics is true: Under linear time it is an internally valid set of relationships, and this is self-evident. The coordinate system described here may be useful for the visualization of data, to enable discovery, and to better inform demographic methods. We have not yet mentioned how such developments might arise in practice. We therefore give a brief case study based this coordinate system. We aim to demonstrate the potential

of the present framework, but this is far from an exhaustive application of its usefulness for other substantive questions, nor is the case study described in complete rigor. Specifically, we reason that projections or comparisons of prevalence-based healthy life expectancy (HLE) are in many cases biased in period prevalence-based models unless one takes into account the thanatological age pattern of prevalence, as well as mortality differences.

There are three steps in our empirical inquiry. The first step is to visualize variables on health outcomes using the demographic time diagram. The second step is pattern detection. We assess the primary time measures over which health outcomes appear to vary. Under the assumption that these patterns of temporal variation are empirically regular, we describe a method of standardizing health expectancy calculations for morbidity conditions whose prevalence is more closely related to thanatological age. Finally, we reason that period estimates of health expectancies for certain health conditions are biased when mortality has been or will-be changing, and comparisons of HLE between populations with different mortality are also biased. We conclude that comparisons of health expectancies might be biased in ways not previously documented.

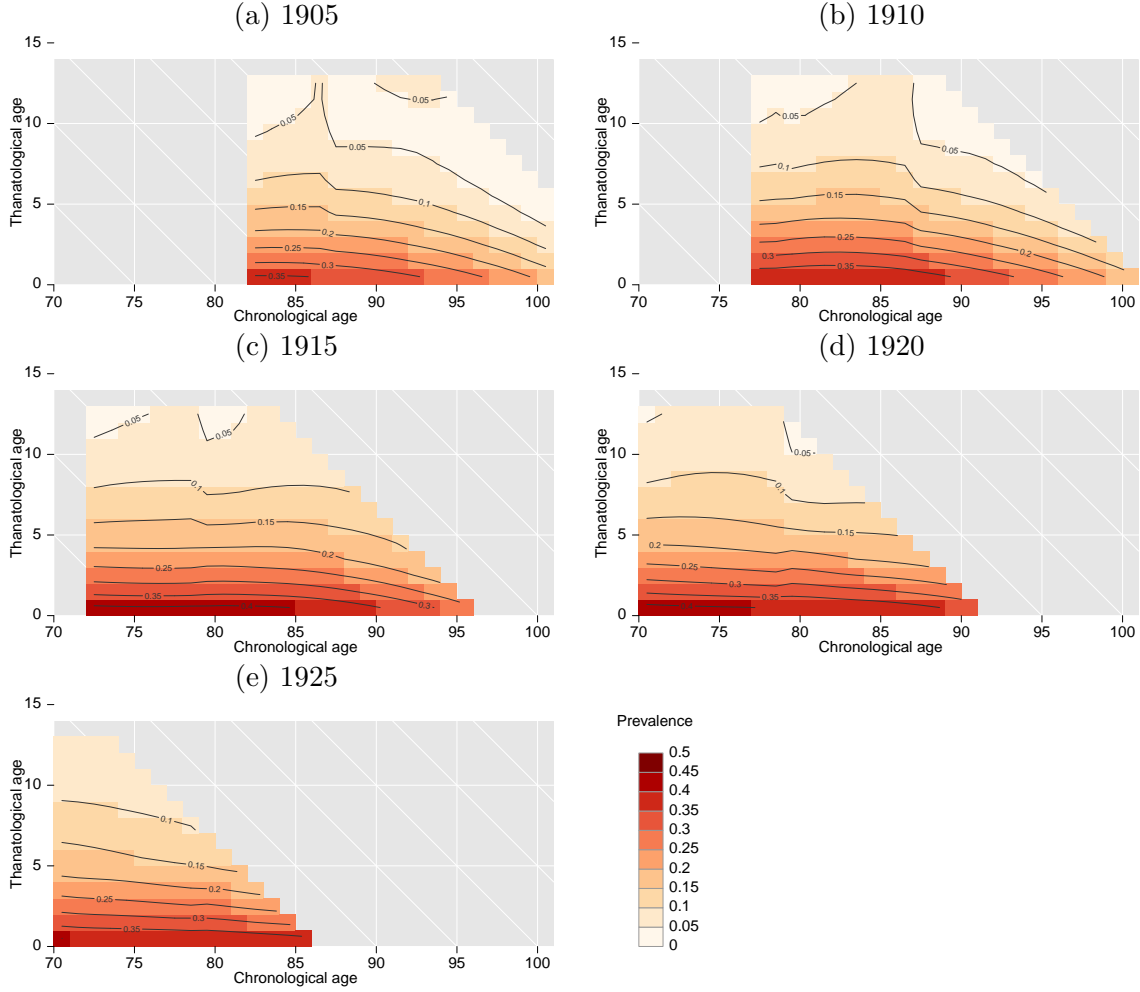
Let us take the example of self-reported health (SRH). The data come from the RAND version of the US Health and Retirement Study (Health and Retirement Study 2013, RAND 2013). Since this survey includes multiple dated observations of individuals, as well as information on time of birth and a followup for time of death, we have or can derive each of the six demographic time measures for each observation. Further methodological details are given by Riffe et al. (2016).

Figure 7 displays a series of TAL surface plots of male SRH prevalence, each referring to a different quinquennial birth cohort (1905-1909, etc). These follow the coordinates of the TAL diagram in Figure 3. The x -axis is chronological age, the y -axis is thanatological age, and downward-sloping diagonals delineate lifespan. Lifelines (not drawn) descend parallel to the downward diagonals seen on the background grid. The density of lifelines in each surface is not visible in this rendering, but one can imagine the mode of the lifetable deaths distribution running down the diagonal that meets near age 80 on the x -axis. Each surface describes the end-of-life SRH prevalence of a birth cohort for the range of lifespan permitted by the survey, but with a lower bound of 70 and an upper bound of 100. Surfaces are therefore shifted down five ages (leftward) for each successive quinquennial birth cohort. Colors and contours indicate prevalence value ranges, with pastel pink for low values (under 10%) and deep reds for high values (over 40%).

Contour lines in the surfaces are perpendicular to the primary direction of variation. For each cohort, the deepest red bar is located in the last year of life and spread over a wide range of ages, giving a roughly horizontal contour line. Other contour lines are also relatively horizontal. This means that variation (in this window of observation) is mainly over thanatological age and not over chronological age. Were variation mostly a function of chronological age the contour lines would be vertical. For each of these birth cohorts we have a series of prevalence trajectories— empirical examples of the life-line morbidity trajectories often conceptually diagrammed in the literature on morbidity compression (e.g., Fries 2005). If we were to summarize each of these surfaces with a single line, a thanatological age pattern would give a much more compact description than a chronological age pattern. Patterns are also relatively stable between cohorts.

When weighted by lifelines, the marginal chronological age pattern of SRH, as measured here (the Sullivan curve, (Sullivan 1971)), would show an increasing tendency over age, in agreement with common expectations. However, such an increasing pattern over age is a marginal artifact, due to an interaction between the distribution of lifespans and

Figure 7: Prevalence of males self-reporting poor health by chronological and thanatological age, by quinquennial birth cohorts, 1905-1925. (HRS)



the relatively fixed underlying pattern of morbidity seen in Figure 7. These surfaces can indeed be tidily summarized with a single line, but it is a line over the thanatological age margin rather than over chronological age.

Since the patterns for each of these cohorts can be presumed to be the same, any shifting in the distribution of age at death ought not produce a change in the expected years of poor health for a given length of life. Further, cohort expected life years spent in poor health should also be approximately the same, even if the underlying age-at-death distribution shifts upward. If morbidity change is a pure function of thanatological age, an increase in life expectancy should increase healthy life expectancy by the same amount. This is not the prediction when we base analyses on the chronological age pattern of self-reported health. Indeed, an underlying morbidity pattern as stable as that seen in Figure 7 would predict improvements in the marginal chronological age pattern of self-reported health if the lifespan distribution were to shift to higher ages. This is because a higher age at death implies more years lived in ages farther from death, where prevalence is low. This potential bias in the current status quo of morbidity measurement and prediction leads to pessimistic morbidity scenarios when mortality improvements are foreseen, and it undermines health expectancy comparisons between groups with different mortality (Van Raalte & Riffe 2016). Cohort health expectancies are in either case unbiased, but these are also not commonly estimated due to data constraints. This approach

and essential finding is in agreement with the results of similar analytic approaches to the prediction of healthcare expenditure (e.g., Miller 2001, Geue et al. 2014)

Using the data from our example surfaces, we calculate some basic results that support our case. Let us take the population of US males aged 60 and older, and assume that mean time-to-death trajectory derived from the Figure 7 surfaces is valid for them. We apply this trajectory to the synthetic stationary population of each year from 1980 and 2010 (HMD 2016) following the formulas in (Van Raalte & Riffe 2016). We then calculate the resulting healthy and unhealthy life expectancies, and compare these with expectancies calculated using the Sullivan method and assuming the 1980 chronological age pattern of poor SRH.⁷ Total remaining life expectancy at age 60 increased 4.3 years from 17.4 in 1980 to 21.7 years in 2010. Assuming the time-to-death prevalence trajectory, we calculate healthy life expectancies of 15.7 and 19.9, respectively, an increase of 4.2 years. Unhealthy life expectancy in this scenario increased just 0.1 years. Had we used the Sullivan curve from 1980 to calculate the 2010 values, we would have predicted an increase of 0.7 years in unhealthy life expectancy, or 39% versus the 4% “observed” in this simple exercise.

This is a large difference in projected morbidity, and it is based on a relatively minor tweak to standard methodology, itself inspired by viewing data under the conditions enabled by the demographic time framework and adjusting standard demographic methods to capture the direction of temporal variation in data. There is a wide variety of prevalence patterns when viewed in this way (Riffe et al. 2016, Wolf et al. 2015), and much empirical and methodological work is still required to verify that these findings are representative and to understand the consequences for the standard ways of comparing and projecting HLE. Our objective in this application has been to demonstrate how viewing data structured by the time-framework we propose can lead to new understandings and approaches to processes over the life course. Other applications are imaginable in other phases of the lifecourse, and non-human subjects.

8 Discussion

In this paper we describe a relationship between six different measures of demographic time: chronological age, period, birth cohort, time to death, death cohort, and individual lifespan. In Section 3 we show how combinations of these time measures imply four triad identities. Each triad identity consists in simple linear relationship between its three constituent time measures. We describe how each triad identity can be extended into a temporal plane, with a characteristic diagram. The four triad identities underly a family of four diagrams. These diagrams include the familiar Lexis diagram (Sec 3.3.1), but also three either new or uncommon diagrams. The TPD diagram (Sec. 3.3.2) relates time of death, period, and time until death, and is therefore a sort of dual to the Lexis diagram. The TAL diagram (Sec. 3.3.3) relates the three duration measures of time to death, chronological age, and lifespan, and it may be useful for analyzing patterns that vary over the lifecourse and/or by length of life. The LCD diagram (Sec. 3.3.4) relates time of birth with time of death and lifespan, and it may be useful for analyzing patterns that vary over time and by length of life, but not necessarily over the lifecourse. These four identities and diagrams relate to one another in a single relationship.

In Section 4 we digress to present a more general event-duration identity framework.

⁷The 1980 chronological age pattern of poor SRH is based on the 1980 stationary population and the same fixed time-to-death prevalence trajectory.

These general terms allow us to present the demographic time hexad identity more rigorously as a special case of the event-duration framework in Section 4.1. We compare this identity with other relatively complicated temporal relationships in the literature, including the Lexis (1875) marriage identity and the illness-death model of Brinks et al. (2014). Some general properties of temporal identities are mentioned in Section 4 described and elaborated and proven in Appendix A. In Section 5 we describe how the graph of the demographic time identity is also the graph of a tetrahedron. As a three-dimensional solid, the tetrahedron forms the basis of the three dimensional extension of the demographic time identity. Each of the four faces of the tetrahedron is parallel to one of the four temporal planes.

In Section 6 we render a diagram of the demographic time identity. We argue that the full three dimensional diagram is not necessarily a practical way to represent demographic data, but that it forms a useful reference to understand demographic processes. In general, data structured by all six demographic time measures can be represented on any of the four diagrams if controlled properly. In Section 7 we present a brief application of this technique to the prevalence of poor self-reported health in older ages in the United States. Prevalence data are displayed in a series of TAL surfaces (See Sec. 3.3.3) representing the end-of-life experience of a sequence of five birth cohorts (1905-1925). Together, these surfaces represent a partial filling of the three-dimensional diagram drawn in Figure 6. As such, this prevalence data is structured by all six demographic time measures. To demonstrate the potential utility of this kind of data structure, we demonstrate (non-rigorously) that the choice of age-pattern when calculating prevalence-based measures of healthy life expectancy can have a non-trivial impact on the result.

The contemporary practice of (macro) demography is based on the premise that vital rates, and other kinds of rates over the lifecourse, are the truest measure of demographic forces. Rates are paramount because they tend to vary in empirically regular ways over the life course. Patterns of primary vital rates fall within a limited range for humans. For this reason, many of the methods of demography are developed to estimate rates, independent of population composition, or to partition crude magnitudes into the effects of population age structure and pure vital rates. Controlling for age like this is in a more general sense controlling for variation in population structure. To the extent that regular temporal variation relates to the end of life, or the length of life, common age-standardization does not fully account for such structure.

An effective way to detect patterns in temporal variation is via data visualization. The coordinate system proposed in this paper is conceived as one adequate to capture such variation, and we suggest its use for visualizing data, probably via small multiples of successive time slices in one of the diagrams from Section 3, similar to that shown in Figure 7 on the basis of the TAL diagram. Such visualization strategies at this time are exploratory, and this is a technique that may benefit from further refinement. Further, a cross-section through the demographic time-space need not be parallel to one of the four identity-planes, and other more complicated temporal designs based on the event-duration framework in Section 4 and Appendix A are also possible.

Panel surveys with mortality follow-ups already provide the requisite information, as do linkable registers that include items such as health measures or proxies and relevant dates of birth, observation, and death. Other kinds of populations, such as animals or items, may have quite different data-gathering mechanisms.

Furthermore, we believe in the pedagogical value of the framework introduced in this paper. We hope that the present inquiry will be useful as a teaching instrument

in the same way as APC diagrams have formed a part of basic demographic education. The relationship between the six dimensions of demographic time helps situate the APC paradigm in a broader framework. Just as scientific discovery in general depends partly on the development of finer optics and instrumentation, we hope that the framework we describe will prove an instrument to enable new discoveries in formal, and empirical demography, as well as other diverse fields of investigation.

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A Event-duration transformation proofs

This appendix provides some formal support to statements and explanations given in Section 4. We explain how durations depend on events (and not vice versa). We list and prove some of the properties of higher-order identities, such as the number of ways they can be derived, the conditions for doing so, the number of event and duration measures they contain, and the number, size, and composition of sub-identities.

Definition A.1. Let \mathbf{p} be a vector with n elements where $n \geq 2$ and elements $p_{i=1} \dots p_n \in \mathbb{R}$. Let \mathbf{d} be a vector with m elements such that $\mathbf{d}_{ij} = p_i - p_j$ for all i and $j = 1, \dots, n$ where $i > j$.

Equivalently \mathbf{d} can be expressed as $\text{vech}(\mathbf{p} \times \mathbf{1}_n^\top - \mathbf{1}_n \times \mathbf{p}^\top)$. For ease of notation we use double indices to index each element of the vector \mathbf{d} . The indices ij of the k^{th} element of \mathbf{d} are given by $d_{ij} = d_k = p_{i=\lfloor \frac{1}{2} + \sqrt{2k} \rfloor + 1} - p_{j=k-C(\lfloor \frac{1+\sqrt{8k}}{2} \rfloor)}$ with $C[f(k)]$ being the binomial coefficient $\binom{f(k)}{2}$.

Theorem A.1. The number of elements in \mathbf{d} is $m = n(n-1)/2$.

Proof. Because d_{ij} must satisfy $i > j$ it can be thought of as all the elements below the subdiagonal of a $n \times n$ matrix of which there are $m = n(n-1)/2$. \square

Corollary A.1.1. The sum of the number of elements in \mathbf{p} and \mathbf{d} is the number of edges on an $n+1$ -polytope, or the number of edges in a complete graph with $n+1$ vertices.

Proof. The sum of the number of elements in p and d is $n + m = n + n(n-1)/2$ which is the number of edges on an $n+1$ -polytope. \square

Consider the set P of all possible choices of n points in time.

Definition A.2. $P = \mathbb{R}^n$: Let $P = \mathbb{R}^n$ be the standard basis vector-space spanning all \mathbf{p} .

Theorem A.2. The linear transformation $T_{\mathbf{A}} : P \rightarrow D$ where $D = \mathbb{R}^{n(n-1)/2}$ and $\mathbf{A}_T \mathbf{p} = \mathbf{d}$ is given by

$$\underbrace{\left[\begin{array}{c|c|c} -\mathbf{I}_1 & \mathbf{1}_1 & \mathbf{0}_{1 \times n-2} \\ -\mathbf{I}_2 & \mathbf{1}_2 & \mathbf{0}_{2 \times n-3} \\ \vdots & \vdots & \vdots \\ -\mathbf{I}_{n-1} & \mathbf{1}_{n-1} & \left(\mathbf{0}_{n-1 \times 0} \right) \end{array} \right]}_{\mathbf{A}_T} \times \underbrace{\begin{bmatrix} p_1 \\ \vdots \\ p_n \end{bmatrix}}_{\mathbf{p}} = \underbrace{\begin{bmatrix} d_1 \\ \vdots \\ d_{n(n-1)/2} \end{bmatrix}}_{\mathbf{d}}.$$

Given *any* n points in time it is always possible to calculate the durations between any pair of these points. This calculation can be understood as a linear transformation of the *point-space* P to the *duration-space* D .⁸

Proof. A_T is a simple consequence of the definition of \mathbf{d} . □

For example, CPD \mathbf{p} yields TAL \mathbf{d} .

Corollary A.2.1. There exists no linear map $T_{\mathbf{A}}^{-1} : D \rightarrow P$.

Given only a set of m durations it is impossible to identify a single set of n points in time marking the endpoints of the durations, e.g. given only age one can not derive birth cohort or period.

Proof. $T_{\mathbf{A}}^{-1}$ exists if and only if \mathbf{A}_T^{-1} exists. \mathbf{A}_T has no inverse since the columns of \mathbf{A}_T are always linearly dependent on each other, i.e. the last element in each row of \mathbf{A}_T is always the negation of the sum of all the other row elements. Therefore $T_{\mathbf{A}}^{-1}$ does not exist. □

For example, although CPD \mathbf{p} yields TAL \mathbf{d} , TAL does not yield CPD.

Theorem A.3. *(Work in progress)* Something that states that you can transform $P^n \leftrightarrow M^n$ where the basis vectors of M are a mixture of point dimensions and duration dimensions.

For example APT yields APCTDL. APT is a mixture of 1 element of \mathbf{p} and 2 elements of \mathbf{d} . This is different from pure $P \rightarrow D$

TR: I think this theorem can be proved using graph theory as in the corollary below.

Definition A.3. \mathbf{g} Let $\mathbf{g} = \{p_{i=1,\dots,n}, d_{k=1,\dots,m}\}$

Theorem A.4. There are $b = (n+1)^{(n-1)}$ many ways to choose n elements out of \mathbf{g} whose linear combination yields the remaining m elements of \mathbf{g} .

Proof. This is a case of Cayley's formula (Cayley 1889), a result from graph theory which gives the number of possible trees on $k = n + 1$ vertices, $k^{(k-2)}$. In our case, the fully conected graph \mathbf{K} with edges defined by the elements of \mathbf{g} according to the third column of Table 3, is complete. By Cayley's fomula, the number of minimal spanning trees on

⁸ \mathbf{I}_n is the $n \times n$ identity matrix; $\mathbf{1}_n$ is a vector with n elements where each element is 1; $\mathbf{0}_{m \times n}$ is a $m \times n$ matrix where each element is 0. For notational convenience we allow for a matrix with 0 columns, written $\left(\mathbf{0}_{n \times 0} \right)$

\mathbf{K} is equal to $k^{(k-2)}$. Four different proofs of this result are given in Aigner et al. (2010). The key is to realize that a minimal spanning tree (MST) on a complete graph will have $k - 1$ edges, connected to each other and all k vertices. As such, the remaining possible edges are linear combinations of any given MST. \square

Corollary A.4.1. Each set of n elements from \mathbf{g} , \mathbf{b}' whose linear transformation yields the remaining m elements of \mathbf{g} includes at least one element of \mathbf{p} .

Proof. One of the vertices of \mathbf{K} , say the k^{th} vertex, is connected only to edges labelled by the elements of \mathbf{p} . Since a spanning tree of \mathbf{K} must connect to this vertex to fully connect \mathbf{K} , all b valid spanning trees must contain at least one edge labelled by an element of \mathbf{p} . \square

TR: is the statement in this proof something that itself also needs to be proved?—that one vertex connects only to \mathbf{p} If that statement needs to be proved, is it a lemma? I think this one takes care of the “mixing” theorem A.3 that is a work in progress above.

Definition A.4. G Let’s define \mathbf{G} as the identity implied by \mathbf{g} whose graph is \mathbf{K} .

Theorem A.5. An identity \mathbf{G} implies a total of $\binom{n+1}{3}$ triad sub-identities.

Proof. Any set of three vertices from \mathbf{K} forms a complete subgraph, and any complete subgraph implies an identity between its labelled edges. \mathbf{K} has $n+1$ vertices, and therefore there are $\binom{n+1}{3}$ ways to select three vertices from \mathbf{K} , hence \mathbf{G} implies the same number of triad subidentities. \square

Corollary A.5.1. Of the $\binom{n+1}{3}$ triad identities implied by \mathbf{G} , $\binom{n}{2}$ contain exactly two events and one duration.

Proof. This follows by noting that the n event-labelled edges in \mathbf{K} connect to a single vertex. Selecting any two of these n event-labelled edges implies a tree on three vertices, whose full connection implies a triad identity composed of the two event edges and one duration edge defined as the time-difference of the former two. There are $\binom{n}{2}$ ways to select two of the n event edges. \square

Corollary A.5.2. For $n \geq 3$, of the $\binom{n+1}{3}$ triad identities implied by \mathbf{G} , $\binom{n+1}{3} - \binom{n}{2} = \binom{n}{3}$ are composed of exactly three durations.

Proof. This is equivalent to deleting the vertex k^{th} from \mathbf{K} , the vertex that connects only to event-labelled edges, which is constructed following the middle column of graphs from Table 3 with vertex labels ignored. This graph has n total vertices, and any set of 3 vertices implies an identity between its three labelled edges, which in this case by definition can only consist of durations. \square

For example, in the demographic time identity there are $n = 3$ event measures. Thus of the $\binom{4}{3} = 4$ triad identities implied $\binom{3}{3} = 1$ of these identities consist in durations only (TAL). Notice that the measures T and A change over the lifecourse of an individual, whereas their sum L is fixed.

Definition A.5. \mathbf{d}_t For \mathbf{p} that include period itself, let \mathbf{d}_t be the set of duration time measures that change over the life course and \mathbf{d}_f consist in those durations that are fixed attributed of an individual. By definition, $\mathbf{d}_t \cup \mathbf{d}_f = \mathbf{d}$.

awkward: how to say that \mathbf{p} includes P? For example, we have P, but Lexis marriage does not, so this corollary is only relevant for us and Brinks here.

Corollary A.5.3. For $n \geq 4$ and For \mathbf{p} that include period itself, of the $d' = \binom{n}{3}$ triad identities whose edges are labelled only by the elements of \mathbf{d} , $d^t = \binom{d'}{2}$ of these identities consist in exactly two elements of \mathbf{d}_t and one element of \mathbf{d}_f , while $d' - d^t$ of the duration-only triad identities consist in relationships between three elements of \mathbf{d}_f .

Proof. $n - 2$ of the edges in K are labelled with the elements of \mathbf{d}_t , and these all connect to the same vertex. There are therefore $\binom{n-2}{2}$ ways to form triad identities with them. The third element of each of these identities cannot connect to the same vertex, and so must be a member of \mathbf{d}_f . (this is almost done, needs a bit more logic) \square

Theorem A.6. In general, the number of subidentities of size h in \mathbf{G} is equal to $\binom{n+1}{n+1-h} \quad \forall h \leq n$.

Proof. Vertex deletion on a complete graph results in a complete subgraph. Therefore, the number of possible complete subgraphs with h vertices is a function of the number of ways that $n + 1 - h$ vertices can be deleted from \mathbf{K} , which is $\binom{n+1}{n+1-h}$. The labelled edges of each possible complete subgraph defined in this way represent subidentities. \square

need to be clear about what “identity size” means. Here it’s based on vertex count, but elsewhere based on edge count

For example, from the tetrahedral graph in Figure 5b, we may delete the vertex that joins the edges labelled A, T, and P, which in effect deletes these edges, leaving us with the CDL identity.