

Tristan Schuler

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RESEARCH INTERESTS

Solar Balloons, Lighter Than Air Vehicles, CubeSats, Robot Design, Swarm Robotics, Space Exploration, Autonomous Systems, Guidance Navigation, and Control (GNC), Simulation

EXPERIENCE

U.S. Naval Research Laboratory — Washington D.C. <i>Mechanical Engineer</i>	May 2018 - Present
<ul style="list-style-type: none">Designed and manufactured small Lighter than Air Autonomous Agents (LTA3)Developed software for operating LTA3's manually and autonomously.Researched lightweight indoor localization solutions.Led SWAT-C development in partnership with the USNA	
University of Arizona — Tucson, AZ <i>Graduate Research Assistant</i>	Aug 2019 – Dec 2020
<ul style="list-style-type: none">Designed, manufactured, and conducted terrestrial solar balloon flight experimentsDeveloped software for predicting solar balloon trajectories on Earth, Venus, and MarsDeveloped CubeSat System Design for an aerial exploration mission to Mars	
NASA – Marshall Space Flight Center — Huntsville, AL <i>Intern</i>	Jan 2018—May 2018
<ul style="list-style-type: none">Adapted April Tags OpenCV library to localize robots (open source release on software.nasa.gov)Tested tether deployment and braking dynamics for an electric tether CubeSat	
NASA – Marshall Space Flight Center — Huntsville, AL <i>Intern</i>	Aug 2017—Dec 2017
<ul style="list-style-type: none">Developed programs to interface with several GPS receivers including: JAVAD TR-G2, Novatel SpaceQuest, GNSS-SDRDesigned tools for parsing and analyzing GPS receiver output	
George Mason University — Fairfax, VA <i>National Science Foundation Undergraduate Researcher (NSF REU)</i>	May 2017—Aug 2017
<ul style="list-style-type: none">Developed algorithms to generate CNC machinable furniture parts from 2D vector drawings and customization parameters provided by a user.	
Air Force Research Lab — Eglin AFB, FL <i>Intern</i>	
Developed autonomous ground rover platform using COTS equipment and assessed usability of opensource Pixhawk ArduPilot software for navigation	June 2016—Aug 2016

EDUCATION

University of Arizona, Tucson, AZ Master of Science in Aerospace Engineering Master's Thesis – <i>Solar Balloons- An Aerial Platform for Planetary Exploration</i>	December 2020 GPA 3.6
George Mason University, Fairfax, VA Bachelor of Science in Mechanical Engineering <i>Minor in Computer Science</i>	May 2019 GPA 3.41

SKILLS & CERTIFICATIONS

Programming: Python, C++, Java, ROS, OpenCV, LaTeX, Matlab, Arduino
Software: Solidworks, Inventor, Microsoft Office Suite, Vicon
Operating Systems: Linux, macOS, Windows 10
Certifications: Secret Clearance

PUBLICATIONS

Journal Papers:

1. J. Gibson, **T. Schuler**, L. McGuire, D. Lofaro, and D. Sofge, "Swarm and Multi-agent Time-based Path Planning for LTA3 Systems," in World Scientific: Unmanned Systems, 2019, pp. 1–8

Conference Proceedings:

1. ***T. Schuler**, K. Kukkala, V. Vilvanathan, and J. Thangavelautham, "CubeSat System Design for Mars Exploratory Balloon (MEB)," i-SAIRAS, 2020
2. ***T. Schuler**, S. Shkarayev, and J. Thangavelautham, "Altitude Control of a Solar Balloon for Mars Exploration," AAS Guidance Navigation and Control (GNC), 2020
3. **T. Schuler**, D. Lofaro, L. McGuire, A. Schroer, T. Lin, and D. Sofge, "A Study of Robotic Swarms and Emergent Behaviors using 25+ Real-World Lighter-Than-Air Autonomous Agents (LTA 3)," in SWARM 2019: The 3rd International Symposium on Swarm Behavior and Bio-Inspired Robotics, 2019
4. J. Gibson, **T. Schuler**, L. McGuire, D. Lofaro, and D. Sofge, "Multi-agent Time-based A* Path Planning on Lighter-Than-Air Autonomous Agents," in IEEE International Conference on Cybernetics and Intelligent Systems, and Robotics, Automation and Mechatronics (CIS-RAM), 2019
5. D. Srivastava, D. Lofaro, **T. Schuler**, and D. Sofge, "Gesture-Based Interface for Multi-Agent and Swarm Formation Control," in SWARM 2019: The 3rd International Symposium on Swarm Behavior and Bio-Inspired Robotics, 2019
6. A. Bouskela, A. Kling, A. Chandra, **T. Schuler**, S. Shkarayev, and J. Thangavelautham, "Planetary Exploration Using CubeSat Deployed Sailplanes," in International Astronautical Congress (IAC), 2019

**Denotes Presenter*

Works in Progress

1. **T. Schuler**, D. Lofaro, A. Maxseiner, D. Bhawandi, D. Sofge, "Wall Climbing Blimp Swarm via Sensor Driven Emergence," ICRA – Swarms in the Real World, 2021. *In Progress.*
2. **T. Schuler**, D. Bowman, "Long Duration Flights in Venus' Atmosphere Using Passive Solar Hot Air Balloons," Acta Astronautica, 2021. *In Progress.*
3. R. Nallapu, Y. Xu, **T. Schuler**, J. Thangavelautham, "Development of a Hardware Demonstration Platform for Multi-Spacecraft Reconnaissance of Small Bodies." IEEE Journal on Miniaturization for Air and Space Systems. *In Progress.*
4. A. Bouskela, A. Kling, **T. Schuler**, S. Shkarayev, J. Thangavelautham, "Mars Exploration Using Sailplanes," Advances in Space Research. 2021. *In Progress*
5. J. Thangavelautham, **T. Schuler**, M. Debbins, K. Kukkala, V. Vilvanathan, C. Bukowski, H. Kalita, "Tethered Robotic Explorer for Accessing Cliffs, Canyons, Craters on the Surface of Mars." AAS Advances in Astronautical Sciences, 2021. *In Progress.*

PROFESSIONAL ORGANIZATIONS: Society of Hispanic Professional Engineers (SHPE), American Institute of Aeronautics and Astronautics (AIAA)

INTERESTS: Adventure photography, music composition, hiking and backpacking, skiing

REFERENCES available on request.